ACADEMIC CURRICULA

POSTGRADUATE DEGREE PROGRAMMES

Master of Technology in Computer Aided Design

Two Years(Full Time)

Learning Outcome Based Education

Choice Based Flexible Credit System

Academic Year

2020 - 2021



SRM INSTITUTE OF SCIENCE AND TECHNOLOGY

(Deemed to be University u/s 3 of UGC Act, 1956)

Kattankulathur, Chengalpattu District 603203, Tamil Nadu, India

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M.Tech in Computer Aided Design

1. Department Vision Statement											
Stmt - 1	We envisage to become an interna innovation amongst faculty to empo	tionally acclaimed research departme ower students for a holistic progress.	ent by fostering creativity and								
2. Depa	artment Mission Statement										
Stmt - 1	To impart quality education to prod renowned professionals	uce mechanical engineers and enhar	nce their skills to become world								
Stmt - 2	Stmt - 2 To establish centers of research excellence to inculcate research acumen in faculty and students on the areas like; machining, bio-mechanics, bio-fuels, composites and energy										
Stmt - 3	Stmt - 3 To provide state-of-the-art education and training programs to the faculty and student fellowship										
3. Prog	3. Program Education Objectives (PEO)										
PEO - 1	PEO - 1 Specialize in the domain of engineering design with the support of computing technology.										
PEO - 2	PEO - 2 Engage in professional practice to meet global standards with ethical and social responsibility.										
PEO - 3	Strengthen capability in upcoming	areas of research and development ir	n engineering design and analysis.								
PEO - 4	Leverage necessary ecosystem for	r self-employment.									
PEO - 5	Apply independent life-long learnin	g ability to actively participate in natio	n building.								
4. Con	sistency of PEO's with Mission of	the Department									
	Mission Stmt 1	Mission Stmt 2	Mission Stmt 3								
PEO - 1	Н	Н	L								
PEO - 2	М	Μ	М								
PEO - 3	Н	Н	Н								
PEO - 4	Н	L	Н								
PEO - 5	Н	М	Н								
II IIch C	annolation M. Madium Connolation I. Lor	ry Completion									

High Correlation, M - Medium Correlation, L - Low Correlation

5. Con	5. Consistency of PEO's with Program Learning Outcomes (PLO)														
						Progr	ram Lea	Irning O	utcome	s (PLO)					
	1.	2.	3.	4.	5.	6.	7.	8.	9.	10.	11.	12.	13.	14.	15.
	Disciplinary Knowledge	Critical Thinking	Problem Solving	 F Provenin sorving Analytical Reasoning Research Skills Team Work Scientific Reasoning Scientific Reasoning Scientific Reasoning Beflective Thinking Self-Directed Learning Self-Directed Learning Ethical Reasoning Ethical Reasoning Liet Long Learning Life Long Learning 											
PEO - 1	Н	Н	Н	H	М	М	Н	М	М	М	М	М	Н	М	М
PEO - 2	Н	Н	Н	Н	М	Н	Н	Н	М	Н	Н	Н	Н	Н	Н
PEO - 3	Н	Н	Н	Н	Н	М	Н	Н	М	М	Н	М	Н	М	М
PEO - 4	М	L	М	М	М	Н	М	Н	Н	Н	Н	Н	Н	Н	Н
PEO - 5	Н	Н	Н	М	М	Н	М	М	Н	М	Н	L	М	Н	Н

H – High Correlation, M – Medium Correlation, L – Low Correlation

6. Prog	gramme Structure (70 Total C	Cre	dite	5)								
	1. Professional Core Courses (C) (4 Courses)							2. Professional Elective Courses (E) (4 Courses)				
Course	Course	Но	urs/ V	Veek			Course	Course	Hou	rs/ We	eek	
Code	Title	L	T	Р	С		Code	Title	L	Т	Ρ	С
20MAC501T/	Computational Methods in Engineering	_		_			20MEE501T	Integrated Product Design and Development	4	0	0	
20MAE501T	, , , , , , , , , , , , , , , , , , ,	3	1	0	4		20MEE502.1	Triboloav in Desian	3	0	2	4
20MEC501J	Modeling and Simulation	3	0	2	4		20MEE503T	Advanced Mechanics of Solids	3	1	0	
20MEC502J	Finite Element Analysis	3	0	2	4		20MEE504T	Mechanical Behavior of Engineering Materials	3	1	0	4
20MEC503J	Mechanical Vibrations	3	0	2	4		20MEE505J	Computer Graphics and Virtual Reality	3	0	2	
20MEC504J	Optimization in Engineering Design	3	0	2	4		20MEE506T	Bio-Mechanics	4	0	0	4
	Total Learning Credits	;	1		20		20MEE601J	Advanced Finite Element Analysis	4	0	0	-
	Ŭ							Composites Materials-Mechanics Design and				4
	3. Skill Enhancement Courses (S)					1	20MEE602J	Manufacturing	3	0	2	
	(2 Courses)							Total Learning Credit	s	1		16
	(=)							· · ··································	-			
Course	Course	Но	urs/ V	Veek		ĪĒ						
Code	Title	L	Τ	P	С			4. Open Elective Courses (O)				
20GNS501.J	Research Publishing and Presenting Skills	1	0	2	2			(Any 1 Course)				
20MES501J	Research Methods in Mechanical Sciences	2	0	2	3		Course	Course	Hou	rs/ We	eek	
2011/200010	Total Learning Credits		v	-	5		Code	Title	L	Т	Ρ	С
	· · · · · · · · · · · · · · · · · · ·	-	20MBO601T	Business Analytics	3	0	0	3				
							20MEO601T	Industrial Safety	3	0	0	3
	5. Project Work, Internship In						20MAO601T	Operations Research	3	0	0	3
	Industry / Higher Technical Institutions (P)						20MBO602T	Cost Management	3	0	0	3
Course	Course	Ноц	irs/ W	/eek			20NTO601T	Composite Materials	3	0	0	3
Code	Title	1	Т	P	C		20CEO601T	Waste to Energy	3	0	0	3
20MED601	The	-	•		Ŭ		20MEO602T	Entrepreneurship and IPR	3	0	0	3
2010121-001	Internship (4-6 weeks during 2 nd sem vacation)	0	0	8			20GNO601T	MOOC	-	-	-	3
20MED602					4		20MEO603T	Solar Passive Architecture	3	0	0	3
2010121-002	Minor Project	0	0	8				Total Learning Credit	s			3
20MEP603						Γ		6 Audit Courses (M)				
L	Project Work Phase I	0	0	12	6			(2 Courses)				
20MEP604		~	~	00	10		Course	Course	Hour		ok	
L	Project Work Phase II	0	0	32	16		Code	Titlo	I			0
	Total Learning Credits				26		2000045011	Line Dispoter Management				0
							20CEA501J	Disaster Management	1	0	1	0
	7. Mandatory Courses (M)						20LEA501J	Value Education	1	0	1	0
0	(3 Courses)						20CEA502J	Physical and Mental Health using Voga	1	0	1	0
Course	Course	Hour	S/ VV	еек	0		2001040013	Thysical and Wental Health using Toga	1	0	1	0
Code	litte	L	1	Ρ	C							
20PDM501J	Career Advancement for Engineers – 1	1	0	1	0							
20PDM502J	Career Advancement for Engineers – 2	1	0	1	0							
20PDM601J	Career Advancement for Engineers – 3	1	0	1	0							

7. Imp	7. Implementation Plan														
	Semester - I							Semester - II							
Code	Course Title	Hou L	rs/W T	/eek P	С		Code	Course Title	Hou	rs/ W T	/eek P	С			
20MAC501T/ 20MAE501T	Computational methods in Engineering	3	1	0	4		20MEC503J 20MEC504J	Mechanical Vibrations Optimization in Engineering Design	3 3	0 0	2	4			
20MEC501J 20MEC502J	Modeling and Simulation Finite Element Analysis	3	0	2	4 4		20MEE503T 20MEE504T	Advanced Mechanics of Solids Mechanical Behavior of Engineering Materials	3	1	0 0	4			
20MEE5011 20MEE502J	Integrated Product Design and Development Tribology in Design	4	0	2	4		20MEE505J 20MEE506T	Computer Graphics and Virtual Reality Bio-Mechanics	3	0	2	4			
20GNS501J 20PDM501J	Career Advancement for Engineers – 1 Audit Course - 1	1	0	2 1 1	2 0 0		20MEE6011 20MEE602J	Advanced Finite Element Analysis Composites Materials-Mechanics. Design and Manufacturing	4	0	2	4			
	Total Learning Credits				18		20MES501J 20PDM502J	Research Methods in Mechanical Sciences Career Advancement for Engineers – 2	2 1	0 0	2	<mark>3</mark> 0			
								Audit Course - 2 Total Learning Credits	1	0	1	0 23			
	Semester - III	1						Semester - IV							
Code	Course Title	L	rs/W	P	С		Code	Course Title	Hou L	rs/ W T	/eek P	С			
20MED6021	MOOC Miner Project	3	-	-	3		20MEP604L	Project Work Phase II Total Learning Credits	0	0	32	16 16			
20MEP602L 20MEP601L	Internship (4-6 weeks-to be done in the vacation after II semester)	0	0	8	4										
20MEP603L 20PDM601J	Project Work Phase I Career Advancement for Engineers – 3 Total Learning Credits	0	0	12 1	6 0 13										
L															

8. Progra	m Articulation Matrix	r														
Course Code	Course Name			1		Pro	gram	me L	.earni	ing C)utco	mes			<u> </u>	-
		Disciplinary Knowledge	Critical Thinking	Problem Solving	Analytical Reasoning	Research Skills	Team Work	Scientific Reasoning	Reflective Thinking	Self-Directed Learning	Multicultural Competence	Ethical Reasoning	Community Engagement	ICT Skills	Leadership Skills	Life Long Learning
20MAC501T/20 MAE501T	Computational Methods in Engineering															
20MEC501J	Modeling and Simulation	H	Н	H	Η	M	Н	M	M	H	M	M	M	H	H	H
20MEC502J	Finite Element Analysis	H	H	H	H	M	L	M	M	H	L	L	L	L	L	H
20MEC503J	Mechanical Vibrations	Η	Н	Н	Η	Η	L	Η	H	Н	L	L	L	M	M	Η
20MEC504J	Optimization in Engineering Design	Н	Н	Η	Н	Η	L	Н	Μ	Μ	L	L	L	Μ	L	Η
20MEE501T	Integrated Product Design and Development	Н	H	Н	H	M	Н	M	M	H	M	M	M	Н	Н	Н
20MEE502J	Tribology in Design	Н	Н	Н	Н	Н	Н	Н	Μ	Μ	Μ	Μ	Н	Н	Н	Н
20MEE503T	Advanced Mechanics of Solids	Н	Н	Н	Н	Μ	L	Μ	Μ	Н	L	L	L	L	L	Н
20MEE504T	Mechanical Behavior of Engineering Materials	H	H	Н	M	M	-	M	-	-	-	-	-	-	-	M
20MEE505J	Computer Graphics and Virtual Reality	H	H	H	Н	Η	M	H	H	H	L	L	H	H	L	Η
20MEE506T	Bio-Mechanics	H	Н	H	Н	Н	L	Η	H	Н	Н	Н	M	Н	L	Н
20MEE601T	Advanced Finite Element Analysis	H	Η	Η	Η	Η	L	Η	H	Н	L	L	L	Н	L	Η
20MEE602J	Composites Materials-Mechanics. Design and Manufacturing	Н	Н	Н	Н	Н	M	M	M	M	L	L	L	M	L	M
20GNS501J	Research Publishing and Presenting Skills	L	Н	Н	M	M	-	L	Н	M	-	Η	-	L	-	M
20MES501J	Research Methods in Mechanical Sciences	L	Μ	Μ	L	Н	Μ	L	L	Н	Μ	Н	L	Н	L	Η
20MBO601T	Business Analytics															
20MEO601T	Industrial Safety	Η	M	Н	-	Η	M	Η	M	Н	Η	M	Η	-	Η	Н
20MAO601T	Operations Research															
20MBO602T	Cost Management															
20NTO601T	Composite Materials															
20CEO601T	Waste to Energy															
20MEO602T	Entrepreneurship and IPR	-	-	-	-	-	M	1	Н	-	-	ł	Н	-	Н	Н
20GNO601T	MOOC															
20MEO603T	Solar Passive Architecture	Η	Н	L	H	L	L	L	H	L	L	L	Н	Н	L	H
20MEP601L	Internship (4-6 weeks during 2 nd sem vacation)															
20MEP602L	Minor Project															
20MEP603L	Project Work Phase I															
20MEP604L	Project Work Phase II															
20CEA501J	Disaster Management															
20LEA501J	Constitution of India															
20LEA502J	Value Education															
20GNA501J	Physical and Mental Health using Yoga															
20PDM501T	Career Advancement for Engineers – 1															
20PDM502T	Career Advancement for Engineers – 2															
20PDM601T	Career Advancement for Engineers – 3		[ſ		ľ		[[
	Program Average															

H – High Correlation, M – Medium Correlation, L – Low Correlation

1. Professional Core Courses (C)

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Course Co	de 20MAC5011/20MAE5011	Course Name	COMPUTATIONAL METHODS IN ENGINEERING						Co	ourse C	ategory	В	S		Basic	Science	S		3	1	0	4
										i.												
Pre-requisit	e Courses Nil		Co-requisite Courses Nil							P	rogressiv	/e Cour	ses Ni									
Course Offer	ng Department	Mathemat	tics	Data Book /	Codes/S	Standards	6			Nil												
0	in a Dationale (OLD)	T 1	a flagging this second is a fallower		Lesselas	-							Deserve									
Course Learn	ling Rationale (CLR):	I ne purpos	se of learning this course is as follows:		Learning	g							Progra	am Learn	ing Out	(comes (PLO)	1		,		,
CLR-1 :	Describe different types of Partial or respective branch of mechanical e	tions interpret the solutions by L.T and F.T relate to the	1	2	3		1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLR-2 :	Expose the students to numerical	technique to sol	ve algebraic equation s, transcendental equations		~	Ħ												JCe				
CLR-3 :	Numerical solution of parabolic, elli	ptic and hyperb	olic PDEs and variation problems	-	enc	ner			s		-	age	n.			۶		naı	þ	ا I		
CLR-4 :	To expose the students to probabili	istic approach to	o solve the real life problems	king	fici	ainr			ysi		ign	Usi	tur	~		ear	ы	i۲ «۲	LUI	1 I		1
CLR-5 :	Introduce the students to the conce	pt of statistical	problems in real life	luin	Po	Atta		g a	nal	ent	Des	<u>8</u>	G	iit a		<u>х</u>	cati	jt.	Lea	1 I		1
				el of Ti ven)	bected	pected		gineerir owledg	blem A	sign & /elopm	alysis, I search	dem To	ciety &	vironme stainab	ics	ividual rk	mmunic	ject Mç	e Long I		0 - 2	0 - 3
Course Learn	ing Outcomes (CLO):	At the end	of this course, learners will be able to:	(Bic	ЦЩ Я	8 4 8		щ¥	2	èё	Ana Re:	β	Š	Sus	뮲	P o N	Ö	2	Life	Š	S	S
CLO-1 :	Determine of analytical solution of	partial different	ial equation	3	85	80		M	L	L						М			L			
CLO-2 :	Able to construct the solution of alg	gebraic equatior	ns, differential equations	1	85	80		М	Н		М	М				М	L					
CLO-3 :	Able to find the numerical solution	atioal problems	1	85	80		М	L							М			L				
CLO-4 :	Understanding of probability in real		3	85	80		М	Н		М					М	L						
CLO-5 :	CLO-5 : Statistical problem related to day to day life				85	80		М	L	L						М			L			

Duration (have)		Learning Unit / Module 1	Learning Unit / Module 2	Learning Unit / Module 3	Learning Unit / Module 4	Learning Unit / Module 5
Duration	n (hour)	12	12	12	12	12
S-1	SLO-1	Introduction and classification of second order PDEs	Introduction to Numerical methods	Numerical solution to PDEs	Introduction to Probability	Linear Regression
	SLO-2	Parabolic PDE	Solution of algebraic equation	Liebmann's iteration method	Independent events	Principle of least squares
6.2	SLO-1	Examples	Bisection method	Laplace equation	Multiplication theorem for independent events	Regression coefficients
3-2	SLO-2	Hyperbolic PDE	Solving Problems	Problems solving	Problems Solving	Properties of Regression coefficient
6.2	SLO-1	Example	Fixed point iteration method	Poisson equation	Conditional probability	Fitting of straight lines
3-3	SLO-2	Elliptic PDE	Problems solving	Bender-Schmidth Method	Examples	Problems solving
S-4 SLO-1		Tutorial 1	Tutorial 4	Tutorial 7	Tutorial 10	Tutorial 13
S-4 SLO-2		Tutorial 1	Tutorial 4	Tutorial 7	Tutorial 10	Tutorial 13
S-5	SLO-1	Boundary value problem	Secant method	One dimensional heat equation	Examples	Problems solving
5-5	SLO-2	Example in real life	Problems solving	Explicit scheme	Random Variables	Curve linear regression
	SLO-1	Laplace Transform -L.T	Solution system of nonlinear algebraic equations	One dimensional wave equation	Discrete Random variable	Fitting of parabola
S-6						Problems Solving
	SLO-2	one dimensional wave equation	Interpolation	Introduction to calculus of variations	Moments and Standard Deviation	
						Correlation
S-7	SLO-1	Solution of wave equation using L.T	Lagrange interpolation	Functional	Probability mass function	

	SLO-2	Problem solving	Hermite interpolation	Euler equation and solution of Euler equation	Distribution function	Linear correlation
	SLO-1	Tutorial 2	Tutorial 5	Tutorial 8	Tutorial 11	Tutorial 14
S-8	SLO-2	Tutorial 2	Tutorial 5	Tutorial 8	Tutorial 11	Tutorial 14
S-9	SLO-1	Heat conduction problem in semi infinite string	Numerical Differentiation	Functional dependent on higher order derivative	Problems solving	Examples
	SLO-2	Solution of heat conduction problem using F.T	Numerical Integration	Formula and Examples	Continuous Random variable	Plane of regression
0.40	SLO-1	Solving Problems	Trapezoidal rule	Variational problem involving several independent variables	Moments and S.D	Coefficient of multiple correlation
5-10	SLO-2	Laplace equation	Simpson's Rules	Solving Problems	Normal Distribution	Examples
	SLO-1	Examples	Problems solving	Isoperimetric problems	Exponential Distribution	Coefficient of partial correlation
S-11	SLO-2	Solution of Laplace equation	Gauss-Quadrature rule	Problems	Problems solving	Problems solving
C 12	SLO-1	Tutorial 3	Tutorial 6	Tutorial 9	Tutorial 12	Tutorial 15
3-12	SLO-2	Tutorial 3	Tutorial 6	Tutorial 9	Tutorial 12	Tutorial 15
Learning Resources		 Sankar Rao K., Introduction to F Elsgolts L., Differential Equation S. S. Sastry, Introductory Metho Gupta S.C. and Kapoor V. K., F 	Partial Differential Equations, 4 th Printing, PH1, New E s and Calculus of Variations, Mir Publishers, Moscov ds of Numerical Analysis, 3 rd Edition, PH1, 2001 undamentals of Mathematical Statistics, Sultan Chan	Delhi, April 2003 v, 1966 Id and Sons, New Delhi, Reprint 2003		

	Lovel of Thinking		Continuous Learning Assessment Test (60%)		Final Examination (10%)
	Lever of Thinking	CLA – 1 (20%)	CLA – 2 (25%)	CLA – 3 (15%) #	Final Examination (40%)
Lovel 1	Remember	40 %	30 %	30 %	30 %
Level I	Understand	40 70	50 %	30 //	50 /8
Lovel 2	Apply	40 %	40 %	40 %	40 %
Leverz	Analyze	40 /0	40 /0	40 /8	40 /0
Lovol 3	Evaluate	20 %	30 %	30 %	30 %
Lever 5	Create	20 /0	50 /0	50 /8	50 /0

Assignment and Surprise Test

Course Designer: Dr. B. Bira, Assistant Professor (Sr.G), SRMIST, bibekanb@srmist.edu.in													
(a) Exp	(a) Experts from Industry												
1	Mr.V.Maheshwaran	CTS, Chennai	maheswaran@yah oo.com										
(b) Exp	b) Experts from Higher Technical Institutions												
1	Dr. Y.V.S.S. Sanyasiraju	IIT Madras, Chennai	sryedida@iitm.ac.in	2	Dr.K.C.SivaKumar	IIT Madras, Chennai	kcskumar@iit m.ac.in						
(c) Inter) Internal Experts												
1	Dr.A.Govindarajan	SRMIST	govindaa@srmist.edu.in	2	Prof. K.S. Gnapathy Subramanian.	SRMIST	ganapatk@srmist.edu.in						

			1	1			I		- 1		1											-			_
(Course Code	20MEC501J	Course Name		MODELI	LING AND SIMULATION	Co Cat	ourse egory		C Professional			al Core	9				L S	L T 3 C	P) 2	C 4	_			
Pre C	-requisite ourses	ə _{Nil}			Co-requisite Courses	Nil		Prog Co	ressiv urses	ve	20MEE505J	, 20ME	E506	Г											
Cours	e Offerin	g Department	Mechan	ical Engineering		Data Book / C	Codes/Standards	Nil																	
Cours	e Learnir	ng Rationale (CLR):	The purp	pose of learning i	this course is to:			L	earnir	ng					Pro	gram	Learn	ing O	utcom	ies (Pl	LO)				
CLR-1	: Und	erstand the concepts	of abstracting	physical systems	S			1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2	: Und	erstand the 3D mode	l generation																	e					
CLR-3 : Understand the modeling of biosystems										-	dge								ట్ల	tenc		nent			
CLR-4	: Und	erstand the simulatio		Bloor	cy (%	nt (%	owle	b0		ning			ing	ing	arni	mpe	ట్డ	ageı			ing.				
CLR-5	: Und	erstand the visualization	tion of data for	effective present	tation			ng (E	cien	nme	Knc	king	ving	easo	lls		asor	ink	lLe	S	onir	Eng		skills	carn
CLR-6	: Und	erstand the concept a	and complete p	rocess of produc	ct development and it	ts management		hinki	Profi	Attai	lary	Chin	Sol	al Re	ı Ski	ork	c Re	e Tł	cted	bural	leas	ity	s	up S	βΓ¢
								of T	cted	cted	iplir	cal ,	olem	ytic	arch	n W	ntifie	ectiv	Dire	icul	cal F	mun	Skil	lersł	Lon
Cours	e Learnir	ng Outcomes (CLO):	At the e	nd of this course	, learners will be able	e to:		evel-	Expe	Expe	Disc	Chiti	Prob	Anal	Rese	Fear	òcier	Refle	self-	Mult	Ethi	Con	CT	eac	ife
CLO-1	: Bet	amiliar with and anal	ze the mather	natics behind the	modeling of mechar	nical systems		1	70	65	Ĥ	Ĥ	H	Ĥ	M	H	H	Ĥ	M	Ĥ	M	M	М	L	М
CLO-2	: Und	ertake to generate 3) solid models		-			2	80	75	Н	Н	Н	Н	Н	Н	Н	Н	Н	М	Н	М	Н	Н	Н
CLO-3	: Und	ertake to generate 3I) solid models	of biosystems				3	65	60	Н	М	L	L	М	М	М	М	L	L	L	L	L	М	М
CLO-4	: Car	ry out the process of	simulating mec	hanical systems				3	75	70	Н	Н	Н	Н	L	М	Н	М	Н	М	М	М	Н	М	Н
CLO-5	: Bet	amiliar with the visua	lization techniq	ues of data for e	ffective interpretation	n of analytical solutions		2	70	65	L	L	L	L	L	L	L	L	М	L	М	М	L	М	М
CLO-6	: Moo	lel, simulate and visu	ally interpret th	e models of any	physical systems			3	70	65	Н	Н	Н	Н	М	Н	М	М	Н	М	М	М	Н	Н	Н
		,	2	,	<u>, , , , , , , , , , , , , , , , , , , </u>			1			1 1	1							1						
MATHEMATICAL MODELLING OF MECHANICAL SYSTEMS GEOMETRIC MODELLING MODELLING								SYSTE	MS		MECH	IANIC	AL SYS	STEM	SIMUL		N			D	ata Vi	sualiza	ition		
	•		15			15	15			15 15															
S-1	SLO-1	Idealized Modelin mechanical system	g Elements/ ba ms	sic elements of	2-D Projection (Draw • Wireframe Modelin Analytical Surface	wings) ng, Surface Modeling	Introduction to biomechanics morphology	biomechanics - Anatomical Introduction of system and Models						Data Aesti	to Vis netics	ualiza	tion –	Mappi	ng data	a onto					
	3LU-2				Free-form, Curved,	& Sculptured Surface																			
S-2	SLO-1 SLO-2	Modeling Methods	8		Solid Modeling Constructive Solid C	Geometry (CSG)	History of anatomical models,	digital 3	3D mo	dels	System Stu	ıdy, Sy	stem S	Simulat	tion			Coor	dinate	syste	ms an	d axes	j		
	SLO-1															a .									

	JII (IIUUI)			1	1	
	. ,	15	15	15	15	15
S-1	SLO-1 SLO-2	Idealized Modeling Elements/ basic elements of mechanical systems	2-D Projection (Drawings) • Wireframe Modeling, Surface Modeling Analytical Surface Free-form Curved & Sculptured Surface	Introduction to biomechanics - Anatomical morphology	Introduction of system and Models	Data to Visualization – Mapping data onto Aesthetics
S-2	SLO-1 SLO-2	Modeling Methods	Solid Modeling Constructive Solid Geometry (CSG)	History of anatomical models, digital 3D models	System Study, System Simulation	Coordinate systems and axes
S-3	SLO-1 SLO-2	Two mass system	Boundary Representation (B-Rep)	Creating a 3D Model Using Graphics Software	Input Data Model	Colour scales
S-4	SLO-1 SLO-2	Three mass system	Feature Based Modeling	Creating a 3D Model Using Imaging and Scanning – steps involved, techniques	Continuous System Simulation	Directory of Visualizations
S-5	SLO-1 SLO-2	Electric Motor, Mass Pulley system	Primitive Instancing, Cell Decomposition, Spatial Enumeration, Octree	Image reconstruction	Discreet System Simulation	Visualization amounts – Bar plots, Stacked bars, dot plots, heat maps
S-6	SLO-1 SLO-2	Translational mass element, Rotational mass element, translation spring element, Damper element	Basic Part Modeling techniques	Creating a 3D Model Using Segmentation	System Dynamics	Visualization distribution – Histograms and density plots – single distribution and multiple distribution
S-7	SLO-1 SLO-2	Newton's Law and D'Alemberts principle	Parametric Modeling techniques	Digital 3D Anatomical Models to Create Physical Models	Simulation Language - GPSS	Visualization proportions
S-8	SLO-1	Transfer Function and State's space	Creation of assembly models	3D printing – materials, resolution and accuracy,	Validation of modelling and Simulation	Visualizations associations, Time series and

	SLO-2				costs and safety concerns			trends			
S-9	SLO-1 SLO-2	Lagrange's equation, Hamiltonian equation Modeling of static and dynamic systems	Advanced assembly op	perations	Emerging trends in 3D modeling	Real world application of	simulation	Visualizing geospatial data			
Learnin Resour	g ces	 Kishore V. Pochiraju , "Modeling a James McConville," Introduction f Kevin Russell, Qiong Shen, Rajpa Pushpa Singh, Narendra Singh, " Ibrahim Zeid, CAD / CAM – Theo Jun Ueda and Yuichi Kurta, "Hur Claus O'Wilke, "Fundamentals or 	and Simulation for Mechanical E to Mechanical System Simulatio al S. Sodhi. "Kinematics and Dyr Modelling And Simulation", S.K. bry and Practice", 2009, McGraw nan Modeling for bio-Inspired Ro f Data Visualization", O'Reilly, K	ngineers", John Wiley & S n Using Adams" 2015 namics of Mechanical Sys Kataria & Sons, 2008 v Hill obotics – Mechanical Engi indle Edition	items, Second Edition: Implementation in MATLAB neering in Assistive Technologies", 2016, Science	® and SimMechanics", 20 Direct	18, Taylor and Francis				
	l	Bloom's Level of Thinking	CL/ (20	Continuous L A-1	earning Assessment (CLA) (60% CLA-2 (25%)	weightage)	CLA 3 (15%	Final Exa (40% we	amination eightage)		
			Theory	Practice	Theory	Practice	ULA-3 (13/0	Theory	Practice		
I	Level 1	Remember Understand	40%	40%	20%	20%	20%	20%	20%		
l	Level 2	Apply Analyze	40%	40%	40%	35%	35%				
	Level 3	Evaluate Create	20%	20%	40%	40%	40%	45%	45%		
		Total 100 % 100 % 100 % 100 %							0 %		

- Laboratory practice:

 1.
 Write codes for mathematical models of mechanical systems

 2.
 Create 3D part models using commercial software package

 3.
 Assemble 3D part models to form a product

 4.
 Create 3D models from MRI scans of human systems

 5.
 Model mechanical systems, simulate using any commercial software package
 - Exercises of data visualization 6.

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. Mani S Manivasagam, Global Head of Vehicle Engineering, Tata Technologies, Pune, India	1. Dr. Jayakumar, Principal, Agni Institute of Technology, Chennai	1. Dr. T.V. Gopal, SRMIST
2. Velmurugan Sivaraman, AGM, Ashok Leyland		2. Dr. S.H. Venkatasubramanian, SRMIST

	Course Code	20MEC502J	Course N	lame	FINITE ELEM	ENT ANAL	YSIS					(Course	Catego	ory	C Professional Core L T 3 0						<u>Т Р</u> 0 2	2	C 4		
F	Pre-requisite C	Courses NIL		(Co-requisite Courses NIL									Progre	ssive C	ive Courses NIL										
C	Course Offering	g Department	Mechanica	l Engineering		Data	Book /	Codes	/Standa	ards			N	IIL			1									
Course	e Learning Rat	tionale (CLR):	The purpose of le application of fini	arning this course is	s to be able to understand method in:	Le	earning							F	Program	Leam	ing Ou	tcomes	s (PLO)						
CLR-1	: Solving : of which approxi	g differential equations. The ch has a bearing in professio kimate solution procedures	e learner will be eq onal practice in un	uipped with analytica derstanding differenc	al skills the learning process ce(s) between exact and	1	2	3		1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2	: a few re	representative 1-D linear str	uctural analysis pr	oblems																						
CLR-3	: a few re	representative 1-D linear he	at conduction with	convection problems	S																					
CLR-4	: a few re elemen	representative 2-D linear pr nts in planar problems	oblems associated	with structural analy	ysis and use of two 2-D	(mo	(%)	(%)		θ								h	nce		ent					
CLR-5	: 1-D line	ear time dependent heat co	nduction and struc	tural analysis proble	ms	Blo	сy	ant		edg			ing			bu	Ē	ning	ete		nem			-		
CLR-6	Repres	sentative 1-D and 2-D proble ed, in future	ems so as to build	the ability to engage	e in independent learning, as	hinking (Proficier	Attainme		ny Knowl	inking	Solving	Reason	Skills	¥	Reasonii	Thinking	ted Lear	al Comp	asoning	ly Engag		p Skills	Learning		
r			At the second of the		and the standard and the standard	of T	cted	cted		olina	al Th	em S	tical	arch	Wo	tific	ctive	Direc	sultur	al Re	nuni	kills	ershi	buo		
Course	e Learning Out	tcomes (CLO):	At the end of this understanding, le	ecourse and after contract and a	mpletion of required reading and o:	Level	Expec	Expe		Discip	Critica	Proble	Analy	Rese	Team	Scien	Refle	Self-L	Multic	Ethica	Comr	ICT S	Leade	Life L		
CLO-1	Apply v	weighted residual and Rayle ons	eigh-Ritz methods	in solving structural i	mechanics problems / differential	1, 2	90	75		Н	Н	Н	Н	М	L	М	М	Н	L	L	L	L	L	Н		
CLO-2	Solve for applica	for displacements and force able to linear analysis of stru	s/moments, as ap ictural members m	olicable, using 1-D 2 nade of isotropic mat	noded-bar or beam elements as erials	1, 2	90	75		Н	Н	Н	н	М	L	М	М	Н	L	L	L	L	L	Н		
CLO-3	: Solve fe	for nodal temperatures relat nts	ed to 1-D steady s	tate heat conduction	problems using 2-noded bar	1, 2	90	75		Н	Н	Н	Н	М	L	M M H L L L L H										
CLO-4	Solve fo	for displacements, strains an lateral elements in linear an	nd stresses, as ap alysis of structural	plicable, using 3-nod members made of is	led triangular and/or 4-noded sotropic materials	1, 2	90	75		Н	H H H H M L M M H L L L L L H															
CLO-5	: Solve forces i	for nodal temperatures in lin in linear time dependent str	ear time depender uctural analysis	nt heat conduction a	nalysis and displacements and	1, 2	90	75		Н	Н	Н	Н	М	L	М	М	Н	L	L	L	L	L	Н		
CLO-6	: Learn ii	independently additional ma	aterial as required	in future		1, 2	90	75		Н	Н	H H M L M M H L L L L H														

		Introduction	1-D Linear Static Analysis	1-D Linear Steady-state Heat Transfer Analysis	2-D Elements for Static structural /steady state Analysis	1-D Linear Time Dependent Heat Transfer and Structural Analysis
Duration	n (hour)	15	15	15	15	15
S-1	SLO-1 SLO-2	Basic concept of Finite Element Method (FEM), Historical background, Course overview, Evaluation scheme	1D problems – overview & interpolation polynomial; 2-noded Bar element –derivation of element matrix	Review of basic equations of heat transfer - steady state one dimensional heat conduction, governing equation	Review of the basic theory in 2-D elasticity, plane stress and plane strain	Time-dependent problems: general 1-D governing equation – introduction and use of Galerkin method
S-2	SLO-1	FEM Applications, Commercial FEM software packages, Weighted residual methods – overview and different methods – Collocation, Sub-domain, Least Squares	Bar problem- solution of a sample problem including element stress determination	1-D steady state heat conduction (continued), boundary conditions, element	2-D problems using Constant Strain Triangles (CST) – definition of element, interrolation function	Derivation of element matrices as applicable to 1-D transient heat conduction – Consistent
	SLO-2	Galerkin		Characteristics	interpolation function	
\$ 3	SLO-1	Application of weighted residual methods to	Co-ordinate systems – global, local, natural;	Derivation of element matrix and "load"	CST dorivation of clomont matrix	Introduction to lumped formulation and relevant element capacitance matrix,
S-3 SLO-2		domain methods - solution by hand	co-ordinate transformation	vector for linear 2-noded bar element		introduction to finite difference method; finite difference solution in time
SLO-1		Practice problems on collection method	Exercise on determination of nodal	Practice problems on nodal temperature	Practice problems on use of CST element –	Practice problems on computation of element
S-4 SLO-2		r raciice problems on conocation method	displacements using the computer tool	conditions – by hand	a) determination of shape functions	matrices

S-5	SLO-1 SLO-2	Practice problems on sub-domain method	Exercise on determination of forces in each element and drawing of Free Body Diagrams (FBD)	Practice problems on nodal temperature determination – mixed boundary conditions – by hand	b) nodal values – by hand	Computation of element matrices - continued
S-6	SLO-1 SLO-2	Sample problems – Least squares and Galerkin methods	Planar Truss element, Derivation of element Matrix, Building of global matrix	Heat conduction with convection – derivation of element matrix for convection term – fin example, sample problem – formulation by hand and solution	Bi-linear rectangular element – definition, interpolation function, element matrix derivation procedure	Overview of forward, backward, and central difference schemes, Derivation of Global matrices and setting up of linear system of equations
S-7	SLO-1 SLO-2	Comparison of the four methods, effect of choice of approximation functions	Analysis of a planar truss – by hand and preparation for use of a computer	Additional problems on steady state heat conduction with convection	Derivation of element matrix(continued),	Practical consideration – physical reality, numerical oscillations; guideline for choice of time-step
S-8	SLO-1 SLO-2	Variational formulation approach- Rayleigh- Ritz method, Principle of minimum potential energy	Beam element – definition, interpolation function, derivation of element matrix	Discussion of procedure for solving conduction with convection problems using a computer	Sample problems related to use of bi-linear rectangular elements, Iso-parametric element – definition and example in 2D	Sample problem – 1D transient heat conduction
S-9	SLO-1 SLO-2	Practice problems Least squares & Galerkins methods	Exercise on determination of nodal displacements in a plane truss	Exercise on determination of nodal temperatures – conduction only - with temperature boundary conditions	Demo on use of a finite element software	Development of a program/worksheet to a) compute relevant matrices
S-10	SLO-1 SLO-2	Practice problems on Rayleigh-Ritz method	Exercise on determination of element forces in a plane truss	Exercise on determination of nodal temperatures – conduction only - with mixed boundary conditions	Exercise on bar/truss problems – to be compared with results obtained earlier by another computer tool (in 1D static analysis tooic)	 b) to build global matrices, "load" vector, c) set-up of solution procedure, and d) solution for given problem(s)
S-11	SLO-1 SLO-2	Application of Rayleigh-Ritz method to sample problems – solution by hand	Beam element - solution of a sample problem	Decision on number of 2-node elements required – conduction only, conduction with convection –basis, Discussion of different boundary conditions, Sample problems	Jacobian – definition and derivation	Time dependent response of un-damped and damped (only viscous damping) single degree-of-freedom spring-mass system- free/forced vibration - governing equation and solution procedure
S-12	SLO-1 SLO-2	Application of Rayleigh-Ritz method to sample problems – solution by hand– Continued – effect of choice of approximation functions, intro to spring element	Iso-parametric elements & numerical integration , Gaussian quadrature	Comparison of governing equation and solution procedure for 1D bar problem with those for 1D steady state heat conduction problem	Determination of Jacobian for a given quadrilateral element – sample problems	Time dependent response of un-damped and damped (only viscous damping) two degree- of-freedom spring-mass system- free/forced vibration - governing equations and solution procedure
S-13	SLO-1 SLO-2	Spring element-stiffness matrix, boundary conditions, sample problems	Sample problems – by hand and procedure to solve using a computer	Overview of commercial finite element analysis softwares, use in industry, how to use a software in the learning process	Use of Gaussian quadrature in 2D element matrix derivation – discussion of procedure, Sample problems – use of a computer for solution	Vibration response - Sample problems
S-14	SLO-1 SLO-2	Demo on use of a computing tool (other than a FE software)	Exercise on determination of nodal displacements in a beam	Exercise on determination of nodal temperatures – conduction with convection – a) computation of element matrices	Exercise on beam problems – to be compared with results obtained earlier by another computer tool (in 1D static analysis topic)	Exercise on determination of response of 1- DOF systems
S-15	SLO-1 SLO-2	Problems solution using the tool – spring systems	Exercise on determination of shear force and bending moments in a beam and corresponding FBDs	b) building of global matrix and "load" vector, c) application of boundary conditions, d) computation of nodal temperatures	Demo on use of software in plane stress analysis	Exercise on determination of response of 2- DOF systems
Learning Resources	5	 Segerlind, Larry J., "Applied Finite El Reddy, J.N. "An introduction to the F York; 1984 Rao S.S. "Finite Element Method in I Chandrupatla & Belagundu, "Finite e 1997 	ement Analysis", John Wiley & Sons, 1984 inite Element Method", McGraw Hill Book Com _l Engineering", Pergamon Press, 1989 lements in Engineering", Prentice Hall of India I	pany New 5. Krishnamoorthy. Co., 1987 6. Hubner. K.H., Do Willy & Sons, 19 Private Ltd., 7. Zienkiewicz. O.C	C.S., "Finite Element Analysis- Theory and P onald. L.D, D.E. Smith, Ted G.Byron, "The Fin 82 C. "The Finite Element Method in Engg. Science	rogramming", Tata McGraw-Hill Publishing ite Element Method for Engineers", John, ee", McGraw-Hill, London, 1977

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	6.	Hubner. K.H., Donald. L.D, D.E. Smith, Ted G.Byron, "The Finite Element Method for Engineers", John,
		Willy & Sons, 1982
44	-	

7. Zienkiewicz. O.C. "The Finite Element Method in Engg. Science", McGraw-Hill, London, 1977

		Continuous Lea	arning Assessment	(CLA) (60% weightage))		Final Examination	
	Bloom's Level of Thinking	CLA-1 CLA-2 (20%) (25%)				CLA-3 (15%)	(40% weightage)	
		Theory	Practice	Theory	Practice		Theory	Practice
Lovel 1	Remember	150/	50/	100/	50/		100/	50/
Lever	Understand	15%	5%	10%	5%		10%	5%
Level 2	Apply	60%	20%	50%	35%	100%	50%	35%

	Analyze							
10/012	Evaluate	00/	0%	0%	0%	0%	0%	0%
Level 5	Create	070						
	Total	100 %		100 %		100 %	100 %	

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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2. Dr.A. Velayutham, DRDO, Avadi, vel_sivam@yahoo.com	2. Dr.R.Prabhu sekar, rprabhusekar@mnnit.ac.in, MNNIT Allahabad	

Course Code	20MEC503J	Course Name		ME	CHANICAL VIBRATIONS	c	Course ategor	y	C				Pr	rofess	sional	Core)				L 3	T 0	P 2	C 4
Pre-requ Course	isite es <i>Nil</i>			Co-requisite Courses	Nil	F	rogress Course	ive s	Nil															
Course Offe	ering Department	Mecha	nical Engineerir	ig	Data Book / Codes/Standards	Nil														·	· · · · ·		· · · · ·	
Course Lea	ming Rationale (CLR)	: The pu	rpose of learnin	g this course is to.	:		Learni	ng						Prog	jram l	Learn	ning O	utcom	ies (P	'LO)				
CLR-1:	Understand the funda	mentals of fre	e and forced vib	ration analysis of	single degree of freedom systems	1	2	3		1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2: I CLR-3: I CLR-4: I CLR-5: I CLR-6: I	Analyze the forced vil Perform the free and f Determine the natural and know about variou Analyze the free vibra Perform the free and f	oration respor orced vibratio frequencies a us vibration m tion of distribu orced vibratio	nse of single deg in analysis of mi and mode shape leasurement trai ited mass syste in analysis of an	gree of freedom sy ultiple degrees of f is of multiple degre nsducers and shaf ms with continuou y mechanical syst	rstem under arbitrary forcing function reedom system aes of freedom system using numerical technique kers s system principles rems with appropriate approaches	avel of Thinking (Bloom)	cted Proficiency (%)	cted Attainment (%)		plinary Knowledge	al Thinking	lem Solving	/tical Reasoning	arch Skills	n Wark	ntific Reasoning	ctive Thinking	Directed Learning	cultural Competence	al Reasoning	munity Engagement	Skills	ership Skills	-ong Learning
Course Lea	ming Outcomes (CLC): At the	end of this cours	se, learners will be	able to:	1.25		Pdx 3		r Disc	п Critio	E Prob	c Anal	c Rese	- Tear	r Scie	c Refle	c Self-	- Multi	Ethio	- Com		≿ Leac	r Life I
CLO-1.	Solve a violaling system Solve vibrating system	s subjected t	o arbitrary force	s including impuls	se step and ramp forces	1,20	3 75	70		H	H	H	H	H	L	Н	H	H			1	M	M	H
CLO-3 :	Compute the eigenval	ues or natura	I frequencies of	vibration and the r	modal vectors and determine the free-vibration	1,28	³ 75	70		н	Н	H	Н	H	L	H	H	H	Ĺ	L	L	M	M	H

CLO-3	3 : Com solut	pute the eigenvalues or natural frequencies of ion using the known initial conditions	f vibration and the modal vectors and deter	nine the free-vibration	1,2&3	75	70		Н	Н	Н	Н	Н	L	Н	Н	Н	L	L	L	М	М	Н
CLO-4	t: Find unde	the approximate natural frequencies of vibrat	ion and the modal vectors by using various r tion pickups, and frequency measuringinstru	numerical techniques and ments and shakers	1,2&3	75	70		Н	Н	Н	Η	Н	L	Н	Н	Н	L	L	L	М	М	Н
CLO-	5: Find	the free-vibration solutions of string, bar, sha	ft and beam problems		1,2&3	75	70		Н	Н	Н	Н	Н	L	Н	Н	Н	L	L	L	М	М	Н
CLO-6	6: Solve	e free and forced vibration problems with app	ropriate techniques		1,2&3	75	70		Н	Н	Н	Н	Н	L	Н	Н	Н	L	L	L	М	М	Н
		Fundamentals of Vibration in SDOF	Vibration under general forcing	Multiple DOF S	Systems			Natu sys	ıral fre stema	equer and vi	ncy an ibratio	d moo n mea	des o asure	f MD ment	OF	Co	ontinu	ious s	syster	ms an	d Bal	ancinę	g
Durat	ion (hour)	15	15							15					15								
S 1	SLO-1	Basic concepts and Classifications of vibration	Introduction multi DOF sy	rstem, ex	ample	əs	Orthog	onalit	y of n	normal	mod	es			Introd Trans	ıction ⁄erse	to co Vibra	ontinu Ition (ious s of a Si	ysten tring o	ns, or Cal	ble	
0-1	SLO-2	methodology of vibration analysis and parameters of a vibrating system	Response under general periodic forcing in first order systems	Equation of motion for a l using Newton's second la	MDOF sy w	/stem		Orthon matrix	ormal	lizatic	on of E	igenv	/ector	rs, ma	odal	Deriva vibrati	tion c on of	of gov string	ernin and	ng equ Soluti	ation on	of fre	е
S-2	SLO-1	Equation of motion and natural frequency of free undamped vibrating system using Newtons second law and principle of energy conservation	Response under general periodic forcing in second order systems	Free vibration analysis of undamped system with two DOF					l Vibra Modal	ation (Anal	of Und Iysis	lampe	ed Sy	rstern	S	Deriva Iongitu	tion c dinal	of gov vibra	emin tion d	ng equ of a ba	ation ar	of	
	SLO-2	Free vibration of torsional system with single rotor, center of percussion	Problems on <mark>general periodic input</mark>	Determination of natural t mode shape for a two DC	frequenc <u>)</u> F syster	y and n	1	Probler Systerr	ms on ns Usi	i force ing M	ed Vib Iodal A	ration Analys	n of U sis	ndan	nped	Solutio Iongitu	on of g dinal	gover vibra	ning tion c	equat of a ba	ion oi ar	f	
	SLO-1	Damped free vibration, Types of damping	Response under general periodic force of irregular form	Free vibration response of DOF system	of undam	ped tv	vo I	Determination of natural frequency using Dunkerley's formula Normal functions, orthogo								nogona	ality o	f nom	nal				
S-3	SLO-2	Types of damped systems, logarithmic decrement, equation of motion of viscous, coulomb and hysteretic damping system, energy dissipation by damping	Problems with response under general periodic force of irregular form	Problems on free vibratio undamped two DOF syste	n respon em	ise of		Determ Rayleig	ninatio gh's m	on of i netho	natura d	l freq	uency	y usir	ng	Proble	ms o	n abc	ve				
S-4 S-5	SLO-1 SLO-2 SLO-1 SLO-2	Determination of natural frequency and damping ratio of a free vibrating system	Determination of natural frequency and mode shape for a MDOF system					ninatic rley's	on of I and F	natura Raylei	l freq gh's n	uency netho	y usir d	ng	Deterr modes compa contin	ninati of lo rison uous	on of ngitu with syste	natu dinal the n m ap	ral fre vibrat esults proac	queno ion oi obtai h	cies ai f bar, ned b	nd ıy	
S.F.	SLO-1	SDF system subjected to harmonic excitation	Response under general non-periodic forcing	Forced vibration response of undamped two DOF system					Determination of natural frequency using Holzer's method							Derivation of governing equation of torsional vibration of a shaft							
3-0	SLO-2	Response of undamped SDF systems with harmonic input	Convolution integral	Problems on force vibration undamped two DOF system	on respo em	nse o	f	Problems using Holzer's method						Solution of governing equation of torsional vibration of a shaft									
S-7	SLO-1	Response of damped SDF systems with harmonic input	Response due to an impulse, impulse response function	Coordinate coupling and coordinates	principal			Determ matrix i	ninatic iterati	on of i on m	natura ethod	l freq	uency	y usir	ng	Proble	ms o	n tors	ional	l vibra	tion o	f a sh	aft

	SLO-2	Dynamic magnifier, Response of damped SDF system with rotating unbalance	Problems on impulse loading	Problems on pitch-bounce model		Problems on torsional vibration of a shaft
	SLO-1	Solution using Laplace transform	Response due to general forcing function	Equation of motion for a MDOF system using Lagrange's equation		Derivation of governing equation of lateral vibration of a beam
S-8	SLO-2	Self- excitation system, dynamic stability of the system	Problems on general forcing	Problems using Lagrange;s equation, torsional system with two and three rotors, semi definite systems	Problems using matrix iteration method	Solution of governing equation of lateral vibration of a beam
S-0	SLO-1					Determination of natural frequencies and
0-3	SLO-2	Simulation of forced vibration response of	Forced vibration response under general	Simulation of forced vibration response of	Determination of natural frequency using Holzer's method and matrix iteration	modes of lateral vibration of beam,
S-10	SLO-1	a SDF System	non-pendale forcing function	a MDOF System	method	continuous system approach
	SLO-2		Response spectrum of SDOF system		Vibration measurement Variable-	Balancing of Rotating Machines, Single-
S-11	SLO-1	Vibration isolation	under general forcing	Dynamic vibration absorbers	Resistance transducers	Plane balancing
0-11	SLO-2	Forcetransmissibility	Examples on response spectrum of SDOF system under general forcing	Torsional dynamic absorbers	Piezoelectric transducers, Electrodynamic Transducers and LVDT	Problems on single plane balancing using vibration measurement
0.40	SLO-1	Support motion, base excitation	Response spectrum of SDOF system under general forcing	Influence coefficients, stiffness coefficients	Seismic instruments, vibration pickups, velometer, accelerometers	Two plane balancing using vibration
5-12	SLO-2	Displacement transmissibility using absolute and relative coordinates	Examples on response spectrum of SDOF system under general forcing	Flexibility coefficients, Maxwell's reciprocal theorem	Frequency-Measuring Instruments	measurement
S-13	SLO-1	Whirling of shaft	Numerical solution for SDOF system under general forcing	Determination of stiffness matrix for lumped mass system and beams using influence coefficients	Vibration exciters, mechanical and electrodynamic shakers	Problems on two plane balancing
	SLO-2	Whirling of shaft	Example problems using Runge-kutta	Eigen value problem, solution	Experimental modal analysis	
S-14	SLO-1	Determination of transmissibility of a SDOF	Numerical solution for SDOE system under	Determination of natural frequency and	Domonstration on machine condition	Experimental Two plane balancing using
S-14 SLO-2 S-15 SLO-2 SLO-2		system / Steady state response due to	general forcing	eigen values and eigen vectors/ design of	monitoring techniques	balancing machines
		Dase excitation		vibration absorber		
Learning Resources	 Mechanical Vibration 5 th editic Fundamentals of mechanical vi Thomson. W. T., "Theory of Vib New Delhi, 1990 	 Mechanical Vibration 5 th edition in SI units, Singiresu S. Rao, Pearson, 2011 Fundamentals of mechanical vibrations 2nd edition, Kelly, Graham S., McGrai Thomson. W. T., "Theory of Vibration with Applications", CBS Publishers And New Delhi, 1990 		elly & Shashidar K. Kudari, "Mechanical Vibra ni,2007. Seto - "Mechanical Vibrations" Schaum Publis. I Acoustics Measurement and Signal Analysis 0. rovitch, "Fundamentals of vibrations", McGrav	ations", Tata McGraw–Hill Publishing Com. hing company s, C. Sujatha, Tata Mc Graw Hill Education v Hill International Edition.	

			Final Ex	Final Examination						
	Bloom's Level of Thinking	CL. (20	A-1 1%)	CL (25	A-2 5%)	CLA-3 (15%)	(40% w	eightage)		
		Theory	Practice	Theory	Practice		Theory	Practice		
Level 1	Remember Understand	- 20%	20%	20%	20%	20%	20%	20%		
Level 2	Apply Analyze	20%	20%	20%	20%	20%	20%	20%		
Level 3	Evaluate Create	10%	10%	10%	10%	20%	10%	10%		
	Total	100)%	10	0 %	100 %	10	0 %		

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	Dr. Rajendra Machavaram, rajendra@agfe.iitkgp.ac.in, IIT Kharagpur	Mr. KR. Arunprasath, SRMIST
2. Dr.A. Velayutham, DRDO, Avadi, vel_sivam@yahoo.com	Dr.R.Prabhu sekar, rprabhusekar@mnnit.ac.in, MNNIT Allahabad	Dr. P. Nandakumar, SRMIST

Course Code	20MEC504J	Course Name		OPTIMIZATION IN ENGINEERING DESIGN	Co	ourse		С					Profe	essio	nal C	ore					L	T	P	C
Couc		Nume			Out	logory															3	U	Z	4
Pre-req Cours	uisite ses Nil			Co-requisite Courses		Prog Co	gressi ourse	ive s	Nil										-					
Course Of	fering Department	Mechar	nical Engineerin	g Data Book / Codes/Standards		Nil																		
Course Le	arning Rationale (CLR	: The pur	pose of learning	g this course is to:		Le	arnin	g						Prog	ıram l	Learn	ing O	utcom	nes (P	PLO)				
CLR-1 :	Be familiar with princip	les of optimiz	ation and its ne	ed		1	2	3		1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 : CLR-3 : CLR-4 : CLR-5 : CLR-6 :	Be familiar with variou Be familiar with solving Be familiar with solving Be familiar with moder Be familiar with applic	s conventiona g multivariable g problems us n methods of ation of optimi	I optimization te problems tech ing unconventio optimization zation to design	chniques niques nal optimization techniques nof machine elements.		evel of Thinking Bloom)	d Proficiency (%)	d Attainment (%)		ary Knowledge	'hinking	Solving	al Reasoning	h Skills	ork	c Reasoning	e Thinking	icted Learning	ural Competence	Reasoning	ity Engagement	S	hip Skills	g Learning
Course Le	arning Outcomes (CLC): At the e	end of this cours	e, learners will be able to:			Expecte	Expecte		Disciplin	Critical 7	Problem	Analytic	Researc	Team W	Scientifi	Reflectiv	Self-Dire	Multicult	Ethical F	Commu	ICT Skill	Leaders	Life Lon
CLO-1 :	Understand optimizati	on principles a	and its need			1&2	90	85		Н	М	Η	Н	Η	Ĺ	Η	Μ	М	L	L	L	М	L	Η
CLO-2 :	Understand and apply	the concept of	of conventional of	optimization techniques		1,2,3	90	85		Н	Н	Н	Н	Η	Γ	Н	Μ	М	L	L	L	М	L	Η
CLO-3 :	Understand and apply	the concept of	of constrained in	single variable as well as multivariable		1,2,3	90	85		Н	Н	Н	Н	Н	L	Н	Μ	М	L	L	L	М	L	Н
CLO-4 :	Understand and apply	the concept u	unconventional of	optimization techniques		1,2,3	90	85		Н	Н	Н	Η	Η	L	H	М	М	L	Ĺ	L	М	L	H
CLO-5 :	Understand and apply	Modern Meth	ods of Optimiza	ation		1,2,3	90	85		Н	Н	Н	Н	Н	L	Н	Μ	М	L	L	L	М	L	Н
CLO-6 :	Apply the methods of	optimization ir	n real life situation	on		1,2,3	90	85		Н	Н	Н	Н	Н	Γ	Н	Μ	М	L	L	L	Μ	L	Н

		Introduction optimization techniques	Classical Optimization Techniques	Multi variable and objective	Non-Traditional Optimization Techniques	Optimization in design of machine elements
Durat	ion (hour)	15	15	15	15	15
C 1	SLO-1	Introduction to optimization	Techniques of unconstrained Optimization	Descent methods Gradient of a function	Genetic Algorithm introduction basic elements of natural genetics	Desirable and undesirable offects
3-1	SLO-2	adequate and optimum design	General Approach golden section Fibonacci method	Evaluation of the gradient	reproduction crossover and mutation	
S-2	SLO-1	Principles of optimization	Rate of convergence scaling of design	Conjugate gradient method	The computational procedure involved in optimizing the fitness function in Genetic	Functional requirement
0-2	SLO-2	design vector, design constraints	variables	Fletcher -Reeves method	Algorithm	i uncional requirement
5 -3	SLO-1	Statement of an optimization problem	Direct search methods, Random jump method, Random walk method	Quasi-newton methods	Tutorials on genetic Algorithm	Material and geometrical parameters
0-0	SLO-2		Random walk method with direction exploitation		Tutonais on genetic Aigontinin	material and geometrical parameters
S-4	SLO-1	Drastical: Introduction to MATLAD and	Practical: Create optimization variable for	Drastical use of an diant evolution	Practical: Function GA tool at the	Practical, an desire entireization of shofts
S-5	SLO-1	its Optimization toolbox	each problem variable Create problem and objective	function	command line, Fitness function, individuals, population and generations	and torsionally loaded members
S-6	SLO-1	Formulation of objective function	Grid search method	Transformation techniques	Simulated Annealing steps involved	Design of simple axial transverse loaded members for minimum cost and minimum
00	SLO-2		Univariate method			weight
0.7	SLO-1	Design constraints	Pattern directions	Populty function	Ant colony optimization	Problems on minimum weight design of a
5-1	SLO-2	Design constraints	Hooke and Jeeves method		And colorly optimization	prismatic beam
S-8	SLO-1 SLO-2	Single variable optimization techniques	Powells method	Multi objective optimization	Graphical representation of ant colony optimization process	Design for linear and non-linear geometric problems helical springs
S-9	SLO-1	Practical: Solution method	Practical: Non-linear constraints with	Practical: Multi-objective optimization	Practical: Simulated Annealing solver	Practical: Linear and non-linear geometric
S-10	SLO-1	Choosing the Algorithms	gradients	Algorithms	Generating file	problems helical springs

S	5-11	SLO-1	Classical optimization for multivariable	Interpolation methods	Utility function method	Particle swarm optimization	Methods of Multi-Disciplinary Optimization
-		3L0-2					
S	5-12	SLO-1	Basics of maxima and minima convex	Quadratic interpolation method	Inverted utility function method	Swarm size information links initialization	Methods of Multi-Disciplinary Optimization
		SLO-2	optimization			equation of motion	(MDO) with case studies in engineering
S	6-13	SI 0-1	Important classes of convex		Global criterion method		System identification problems with
		020	ontimization problems	Cubic interpolation method	Goal attainment method	Problems on particle swarm optimization	applications on structural health monitoring
		SLO-2			Bounded objective function method		
ç	5-14	SLO-1			Practical: Multi-objective optimization		
		SLO-2	Practical: Solve a constrained problem	Practical: Linear and quadratic	algorithms Compare fminimax and fminunc	Practical: Particle swarm optimization	Practical: Case studies in engineering
	15	SLO-1	using optimization variable	programming problems	Goal attainment method		
0	6-15	SLO-2					

Learning Resources	 Rao Singaresu.S, "Engineering Optimization – Theory & Practice", New Age Internationa (P) Limited,New Delhi, 2009. Kalyanamoy Deb, "Optimization for Engineering design algorithms and Examples", Prentice Hall ofIndia Pvt. Ltd., 2006. Johnson Ray C, "Optimum design of mechanical elements", Wiley, John & Sons, Digitize 2007 Goldberg .D.E, "Genetic algorithms in search, optimization and machine", Barnen, AddisonWesley,New York, 1989. 	 William Orthwein, "Machine Component Design", Vol. I and II, Jaico Publishing house, New Edition,2006. Rao.C.S, "Optimization Techniques", DhanpatRai& Sons, New Delhi Fox.R.L, "Optimization methods for Engineering Design", Addison Wesley Pub, Digitized 2007. Garret N. Vanderplaats, "Numerical optimization techniques for engineering", McGraw-Hill Ryerson
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			Final Ex	amination				
	Bloom's Level of Thinking	CL (20	CLA-1 CLA-2 (20%) (25%)			CLA-3 (15%)	(40% w	eightage)
		Theory	Practice	Theory	Practice		Theory	Practice
Lovel 1	Remember	20%	20%	20%	20%	Theory	20%	20%
Level I	Understand					30%		
Lovel 2	Apply	20%	20%	20%	20%	40%	20%	20%
Level 2	Analyze					40 /0		
Level 3	Evaluate	10%	10%	10%	10%	30%	10%	10%
Level J	Create					50 /0		
	Total	100) %	10	0 %	100 %	10	0 %

Course Desi	Course Designers									
Experts from	n Industry	Experts from Higher Technical Institutions	Internal Experts							
1.	Mr. Haresh Durai Karuppiah, RENAULT NISSAN, Haresh.durai@rntbci.com	Dr. Subhas Ganguly, NIT G.E, Great Eastern Rd, Raipur, sganguly.met@nitrr.ac.in	Dr. Shubhabrata Datta, SRMIST							
2.	Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in		Mr. Vamsi krishna dommeti , SRMIST							

2. Professional Elective Courses (E)

Course Code	20MEE501T	Course Name	INTE	EGRATED PROD	UCT DESIGN AND DE	VELOPMENT	C Ca	ourse tegory	/	Е	Professional Elective						L 4	T 0	P 0	C 4					
Pre-requisi Courses	te _{Nil}			Co-requisite Courses	Nil			Pro C	gressi	ive s	Nil														
Course Offeri	ng Department	Mecha	nical Engineerin	g	Data Boo	ok / Codes/Standards		Nil																	
Course Learn	ing Rationale (CLR)	: The pur	pose of learning	g this course is to:				Lear	ning		Pro	gram	Learn	ing Ou	tcome	es (PL	.0)								
CLR-1: Und	lerstand the product	t design and c	levelopment pro	cesses				1	2	3	1	2	3	4	5	6	7	8	9	10 [·]	11	12 [·]	13	14	15
CLR-2: Und	lerstand the phases	of product de	evelopment over	the whole produc	t design cycle					(%)	đ	20							g			ient			
CLR-3: Und	lerstand the module	s of architectu	ure of a product		a of docion				ncy	ient	had			ing			ing	p	rnin		5	gem			b
CLR-4: Und	lerstand the forms a	iology for refir	olved in protecti	ant and economic	s of design			king	ficie	ainm	NOU		ing .	asor	<u>s</u>		son	nkir	Lea		ui.	nga		kills	min
CLR-6: Und	lerstand the concep	t and complet	e process of pro	oduct developmen	t and its management			hin	Po	Atta	2	ink	Solv	Ŗ	Ski	논	Rea	Th	ted.	ge al	easc	₹		ip S	Lea
021101 011								of T	sted	sted			L L	tical	arch	Ŵ	tific	ctive	irec.	ultu eter	Å.	inn	kills	ershi	buc
Course Learn	ing Outcomes (CLC): At the e	end of this cours	e, learners will be	able to:			Level (Bloor	Expec (%)	Expec	Discin	Critica	Proble	Analy	Rese	Team	Scient	Reflec	Self-D	Multic	Ethica	Comn	ICT S	Leade	Life Lo
CLO-1 : Ide	ntify and analyze the	e product desi	gn and developr	ment processes in	any industry.			1	70	65	Н	Н	H	H	M	Ĥ.	H	H	М	Ħ /	M	M	M	L	М
CLO-2 : Def	ine the phases of pr	oduct develop	oment over the v	whole product des	ign cycle			2	80	75	Н	Н	Н	Н	H	H.	Н	Н	H	M	H I	M I	H I	H .	Н
CLO-3 : Uno	lertake a methodica	I approach to	evolve the archi	itecture of a produ	ict			3	65	60	H	M	L	L	M	M	М	М	L					M	M
CLO-4 : Car	ry out the process o	t retining and	enhancing the c	design	f a dagignar			3	75	70 65	H	H	H	H	L	M.	H I	M	H I		M	M I M	H I	M	H
	iver newly designed	or modified n	roduct based on	customer needs	i a designer			2	70	65	L	H	H	L		H	L M	M	H	M	M	M		H	H
020 0. 00	iver newly designed							U	10	00															
Duration (hou		VELOPMEN	F PROCESS	CONCEPT GENE AND	RATION, EVALUATIC	PRODUCT A	RCHIT	ECTU	RE		INDUST	RIAL	DESIG FO	iN R X	AND	DESI	PATENTS AND INT PROPERTY R					NTEL Y RIG	LECT HTS	ΓUAL	
20.0001 (,	12			12		12						1	2							12	2			
S-1 SLO-	1 2 Stages in produc	ct developme	<mark>nt</mark> F	Problem decompo	sition	Implications of produ	uct arch	itectur	re	l i	Need for i ndustrial	ndust desig	rial de: n	sign, ir	npact	of	Intellectual Property - type			types					
S-2 SLO- SLO-	1 Recognition of the second	<mark>he need for p</mark> i	roduct s	Search externally		Product change, Pro	oduct va	ariety			ndustrial conceptua needs	Desig alizati	n Proc on, refi	ess - l nemer	nvest nt of c	igatio ustorr	n, ner	Legis	lation	<mark>s cove</mark>	erings	IPRs	in Ind	<mark>dia</mark>	
S-3 SLO- SLO-	1 2 Product Develor	oment Proces	<mark>s</mark> s	Search internally		Component Standar performance, manuf	dizatior acturat	n, prod bility	luct		Vanagerr Process	ient o	f the In	dustria	al Des	ign		Paten	<mark>t - Ty</mark>	<mark>pes o</mark> í	<mark>f Pate</mark>	<mark>nts</mark>			
S-4 SLO- SLO-	1 2 7	evelopment P	rocess S	Systematic explore	ation	Establishing the arch and clustering	the architecture – Creation Technology driven and User driven products				Paten Paten	tabilit iting	y crite	eria - I	<mark>nterna</mark>	ationa	al								
S-5 SLO-	1 2 Demand forecas	sting	E	Evaluating the solu	utions	Geometric layout de	velopm	ent		/	Assessing the Quality of Industrial Design			<mark>gn</mark>	<mark>Copy</mark>	rights	- tra	<mark>dema</mark>	<mark>rk and</mark>	<mark>d serv</mark>	v <mark>ice m</mark>	narks			
S-6 SLO-	1 2 understanding c	ustomer need	l <mark>s</mark> H	Hybridizing concep	ots	fundamental and inc	idental	intera	ctions	[Design for Manufacture			Trade secret- Geo			ograp	ohical	Indic	<mark>ation</mark>					
S-7 SLO-	1 Data collection a	and interpreta	<mark>tion</mark> (Concept selection		Delayed Differentiati	on			I	Design for Assembly and Maintenance Ind			Indus ⁻	<mark>trial D</mark>	<mark>esign</mark>	<mark>s – Pl</mark>	<mark>ant va</mark>	arietie	<mark>es</mark>					
S-8 SLO-	1 2 Organizing the r	needs	c	Concept Screening	9	Platform Planning				Design for Economics Preparing a			<mark>ı discl</mark>	losure											
S-9 SLO-	1 Customer involv 2 requirements	rement in refir	<mark>iing the</mark> C	Concept Scoring		Related System-Lev	ated System-Level Design Issues Design for Safety and reliability Patents Product development				<mark>velopr</mark>	<mark>ment</mark>													
S-10 SLO- SLO-	1 2 Conjoint Analysi	is	C	Concept Screening	g and Scoring – Case	Id Scoring – Case Related system level design issues – secondary systems Product development economics Elements of econ analysis process				nomic	analy	<mark>/sis-</mark> e	econo	omic											
S-11 SLO- SLO-	Establish target	specifications	; (Concept testing		Architecture of the c	hunks			I	Reducing	the c	ompon	ent co	<mark>sts an</mark>	ld		Managing projects- project planning							

									assembly costs	
;	S-12	SLO-1	Sottin	in the Final Specifications	Concept testing - Case study	Creating details	nd interface sne	cifications	Minimize system complexity	Accelerating projects-project execution
		SLO-2	Octui	ig the final opechications	Concept testing - Case study	oreating details	su interface spe	cilications	Within Ze System complexity	Accelerating projects-project execution
_										
			1.	Karl Ulrich, Steven Eppinger, Maria Mc Graw Hill Education, 2019.	C. Yang, "Product Design and Development"	, 7th Edition,	4. S	Stephen Rose 992. ISBN.1-	nthal. "Effective Product Design and Develo 55632-603-4.	pment" Business One Orwin, Homewood
	Learr Reso	ning urces	2.	Foundation Skills in Integrated Prod 2013.	uct Development (FSIPD), Student Handboo	k NASSCOM,	5. s	Staurt Pugh, " Publishing Ne	Tool Design — Integrated Methods for succe	essful Product Engineering', Addison Wesley
			3.	Imad Moustapha, "Concurrent Engir International publishers, 2003	neering in Product Design and Development"	New Age	r	ublishing, Ne	w Tork, N.T. 1991. ISBN 0-202-41039-3.	

			Continuous Learning Assessment (CLA) (60% weightage)							
	Bloom's Level of Thinking	CLA-1 CLA-2 (20%) (25%)				CLA-3 (15%)	(40% we	eightage)		
	5	Theory	Practice	Theory	Practice		Theory	Practice		
Level 1	Remember Understand	40%		20%		20%	20%			
Level 2	Apply Analyze	40%		40%		40%	35%			
Level 3	Evaluate Create	20%		40%		40%	45%			
	Total	100) %	100) %	100 %	100) %		

Course Des	ourse Designers										
Experts from	m Industry	Experts from Higher Technical Institutions	Internal Experts								
1.	Dr. Mani S Manivasagam, Tata Technologies, Pune	Dr. Jayakumar, Principal, Agni Institute of Technology, Chennai	Prof. T.V. Gopal, SRMIST								
2.	Velmurugan Sivaraman, AGM, Ashok Leyland		Dr. S.H. Venkatasubramanian, SRMIST								

Course Code	20MEE502J Course Name				TRIBOLOGY IN DESIGN Co			Course Category	Е	Professi	onal Elective	L 3	T 0	P 2	C 4
Pre-requisite Courses Course Offering I	NIL Department	(Mechanical Engineering	Co-requisite Courses	NIL	Data Book / Codes/Standards	Progressive Courses PSG Design Data	NIL a book								

Course L	earning Rationale (CLR): The purpose of learning this course is to: Understand and analyze the surfaces and friction			ing		Prog	ıram L	.earning	Outco	mes (PL	.0)									
CLR-1 :	Understand and analyze the surfaces an	nd friction	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Understand and analyze the wear mech	anisms																		
CLR-3 :	Understand and analyze the lubricants a	and lubrication phenomenon																		
CLR-4 :	Understand and analyze bearings and s	elect suitable materials	oom	(%) (t (%)	ee	b							БĽ	ence		nent			
CLR-5:	Understand and analyze the surface engineering processes Understand and solve various engineering problems			cienci	nem	owled						oning	king	earni	mpet	ing	gagei		s	ing
CLR-6:	Understand and solve various engineering problems			Profi	Attair	2 X	, indi		Reas	Skills	¥	Reas	Thin	ted L	al co	ason	βĒ		p Ski	Learr
			l of T	cted	cted	plina	- F		/fical	arch	oW r	lific	ctive	Direc	cultur	al Re	munit	skills	ershi	ong
Course L	earning Outcomes (CLO):	At the end of the course, student will be able to:	Leve	Expe	Expe	Disci	Citio		Anah	Rese	Tean	Scier	Refle	Self-I	Multi	Ethic	Com	ICT (Lead	Life L
CLO-1 :	1: Understand friction and engineering surfaces			100	85	Н	Н	М	М	Н	М	Н	М	М	М	Н	Н	Н	М	Н
CLO-2 :	Apply the knowledge and analyze the fa	ilure occurred due to various types of wear	2&3	100	85	Н	Н	Н	Н	н	М	Н	М	М	М	Н	Н	Н	М	Н
CLO-3 :	-3 : Apply the knowledge of lubrication to provide solutions			100	85	Н	Н	Н	Н	Н	М	Н	М	М	М	Н	Н	Н	М	Н
CLO-4 :	-4 : Apply the knowledge of bearings to provide solution		2&3	100	85	Н	Н	Н	Н	н	М	Н	М	М	М	Н	Н	Н	Н	Н
CLO-5:	Analyze various surface conditions and	provide new ideas of surface protection techniques	2&3	100	85	Н	Н	Н	Н	Н	М	Н	Μ	М	М	Н	Н	Н	Н	Н
CLO-6:	6: Investigate the failure of a system		2&3	100	85	Н	Н	Н	Н	Н	Н	Н	М	М	М	М	Н	Н	Н	Н

		friction	Wear	Lubricants and lubrication	Bearings and Surface textures	Applications of Tribology
Duration (I	nour)	15	15	15	15	15
S-1	SLO-1	Introduction to the concept of tribology	Introduction, background of Wear and Types of Wear with applications.	Types of lubricants and their properties	Thrust bearings	Failure of engineering components due to fatigue
S-2	SLO-1	Engineering surfaces and surface topography	Abrasive wear	Stribeck Curve and its importance	Journal bearings	Failure of engineering components due to fracture
S-3	SLO-1	Measurement of surface topography and roughness parameters	Adhesive wear	Boundary and Mixed Lubrication regime	Rolling element bearings. Pad bearings	High temperature wear
S-4			Practical-4: Investigating the wear	Practical 7: investigation the antiwear	Practical 10: Investigation the performance	
S-5		roughness using a profilometer	properties of coper on steel tribo pairs -wet test	properties of lubricants using four ball tribometer – engine oil	characteristics of journal bearings	Practical 13: A case study on failure of gears.
S-6	SLO-1	Contact between surfaces, Sources of sliding Friction, Friction characteristics of metals and non-metals	Corrosive wear	Hydrodynamic lubrication	Introduction to Surface Texturing	Conventional surface treatments
S-7	SLO-1	Friction due to ploughing	Fatigue wear	Elasto hydrodynamic lubrication (EHL)	Surface texturing methods	Conventional coating techniques
S-8	SLO-1	Friction due to adhesion	Fretting wear	Importance of film thickness, Lambda ratio	Influence of surface textures on bearing performance	Advanced coating techniques

S-9	-	Practical 2: Investigating the frictional	Practical 5:Investigating the wear	Practical 8: Inve	estigation of antiwear	Practical 11: Investigating the rolling contact	Practical 14: A case study on failure of high					
S-10		properties of steel on steel tribo pairs-dry test	properties of copper on steel tribo pairs -wet test	properties of lub tribometer – veç	pricants using four ball getable oil	tribometer using gear oil at 75 degree Celsius	temperature coatings.					
S-11	SLO-1	Friction of ceramic materials	Wear of metals	Bio degradable lubricants	lubricants and nano	Role of surface textures in reducing friction and wear in dry conditions	Introduction to bio tribology					
S-12	SLO-1	Friction of polymers	Wear in polymers	Coatings		Role of surface textures in reducing friction and wear in wet conditions	Wear of titanium alloys in bio tribology					
S-13	SLO-1	Measurement of friction	Wear of ceramics	Self-lubricating	coatings	Case study of surface textures in reducing friction and wear in pistons	Wear of biopolymers					
S-14	SLO-1	Practical 3- Investigating the frictional properties of copper on steel tribo pairs	Practical 6: Investigating the wear properties of brass on steel tribo pairs	Practical 9: Inve pressure proper	estigating the extreme rties using four ball	Practical 12: Investigation the rolling contact fatigue properties of lubricants using four ball tribometer at ambient temperature using	Practical 15: A case study on wear of					
S-15		-dry test	-wet test	tribometer		a vegetable oil	bomatenaio					
Learning	1. 2.	Hutchings.I.M and Shipway P, "Tribology, Butterworth – Heinemann, UK, 2017. Bharat Bhushan, "Introduction to tribology" Williams LA "Engineering The Jerry" Off	Friction and Wear of Engineering Material, El: ", Wiley Publication, 2013.	sevier	5. Stolarski. 6. Cameron. 7. Neale.M.	T.A, "Tribology in Machine Design", Industrial Pre A, "Basic Lubrication Theory", Longman, U.K., 19 J., "Tribology Handbook", Newnes Butter worth, H E, "Moebical Matchings," McCandill Dublicat	ss Inc., 1990. 381. Ieinemann, U.K., 1975. ion India Third Edition 2012					
Resources	э.	williams.J.A, Engineening moology, Oxi	JIU UTIIVEISILY FTESS, 2005.		8. Dieter G.E., "Mechanical Metallurgy", McGrawhill Publication, India, Inird Edition, 2013.							

Resources
 GwidonStachowiak, Andrew W Batchelor., "Engineering tribology", Elsevier Butterworth –Heinemann, USA, 2005.

			Continuous Le	earning Assessment (CLA) (60%	weightage)		Final Examination			
	Bloom's Level of Thinking	CL (20	A-1)%)	CL (2:	.A-2 5%)	CLA-3 (15%)	(40% we	eightage)		
	J	Theory	Practice	Theory	Practice	02110(1070)	Theory	Practice		
Level 1	Remember Understand	40%	20	30%	20	20%	20%	20		
Level 2	Apply Analyze	40%	20	30%	20	40%	40%	20		
Level 3	Evaluate Create	20%	60	40%	60	40%	40%	60		
	Total	10	0 %	10	0 %	100 %	100 %			

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Dr. Chiradeep Ghosh, Tata Steel chiradeep.ghosh@tatasteel.com	Dr.M. Kamaraj, Professor, IIT Madras	Dr. Shubrajit Bhaumik, SRM IST ,
Mr.Bharath Kumar, Rane NSK, bharathkumar@nsk.com		Dr. TVVNL Rao, SRM IST

Course Co	ode	20MEE503T	Course Name		inics of S	Solids						Cour Categ	se ory	E	E	Pi	rofessi	onal El	lective	_	L 3	T 1	P 0	C 4		
Pre-rec	quisite			Co-req	uisite	NIL								Pr	ogress	ive Co	urses	NIL								
Course Offe	ering Dep	artment	Mechanical Engi	neering	565		Data	Book /	Codes	/Standa	ards			NIL				I								
Course Lea	amina Rat	ionale (CLR):	The purpose of le	arning this course is to	0:				earnin	a						Р	rogram	Learn	ina Oi	utcome	s (PLC))				
CLR-1 :	Be equi practice Be able exact m	pped with analytical skill: in understanding differe to analyze effects of typ ethods as applicable	s the learning proce ence(s) between exa ical loadings on prin	ss of which has a bea act and approximate so nary structural membe	ring in pro plution pro ers using a	ofessional ocedures approximate o	or	1	2	3		1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Be able primary	to Compute the effect of structural member) subj	f deformation/loadir ected to bending (a	g in straight and curve type of primary loadin	ed beams lg)	(a class of																				
CLR-3 :	Be able flat thin	to Study the effect of be plates (a class of primar	ending (a type of prin y structural membe	mary loading) deforma ^r)	tion/load a	as applied to		(moo	y (%)	t (%)		lge			5					ĝ	tence		nent			
CLR-4 :	Be able to Compute the combined effect of deformation/loading arising out of different causes as applied to structural members made of linear, homogeneous, isotropic material so as to be able to predict (as part of a different course) failure of components/sub-systems of a product Be able to Study the use of energy methods in structural analysis as an alternative means of applying a structural methods in structural analysis as an alternative means of							f Thinking (B	ed Proficienc	ed Attainmen		nary Knowleo	Thinking	n Solving	cal Reasonin	ch Skills	Nork	fic Reasoning	ive Thinking	rected Learni	Itural Compe	Reasoning	unity Engage	llis	ship Skills	ng Learning
CLR-5 :	Be able solving	to Study the use of ener a structural mechanics p	rgy methods in strue problem	ctural analysis as an a	Iternative I	means of		Level o	Expect	Expect		Discipli	Critical	Probler	Analytic	Resear	Team V	Scientif	Reflecti	Self-Din	Multicu	Ethical	Commu	ICT Ski	Leaden	Life Lor
CLR-6 :	Be able	to build the ability to eng	gage in independen	t learning, as required	, in future																					
Course Lea	arning Out	comes (CLO):	At the end of this understanding, le	course, after completi arners will be able to:	on of requ	uired reading a	and	-																		
CLO-1 :	Unders and solv	tand the primary differen ve plane stress and torsion	nce between theory onal problems	of elasticity and mech	anics of m	naterials appro	baches	1, 2	90	75		Н	Н	Н	Н	М	L	М	Μ	Н	L	L	L	L	L	Н
CLO-2 :	Determi stresses (bendin	ne i)bending stress in str s in straight beams and lo g) stresses in curved bea	raight beams (due t ocate shear center ams	o unsymmetrical bend for specified cross-sec	ing), ii) tra ctions, and	ansverse shea d iii) circumfere	ar ential	1, 2	90	75		Н	Η	н	Н	М	L	М	М	Н	L	L	L	L	L	Н
CLO-3 :	i)Derive express Use the	expressions for displace ions) the governing equa expressions for computi	ement/strains, stres ation for bending of ing these paramete	ses, and moments, ii) flat rectangular and ax rs in specified cases	derive (us ki-symmet	sing these tric circular pla	ates.	1, 2	90	75		Н	Н	н	н	М	L	М	М	Н	L	L	L	L	L	Н
CLO-4 :	Perform stresses	2D & 3d stress and stra and find the planes on	in transformation a which these stresse	nd arrive at maximum es act	values for	r normal and s	shear	1, 2	90	75		Н	Н	Н	Н	М	L	М	Μ	Н	L	L	L	L	L	Н
CLO-5 :	2LO-5 : Compute strain energy due to various loadings and using it to determine deflection						1, 2	90	75		Н	Н	Н	Н	М	L	М	Μ	Η	L	L	L	L	L	Н	
CLO-6 :	Learn ir	dependently additional r	material as required	in future				1,2	90	75		Н	Η	Н	Н	М	L	М	М	Н	L	L	L	L	L	Н
		Introduction to Theory Applicat	y of Elasticity & Its tions	Bending of Straigh	nt & Curve	ed Beams		Bendir	ng of fla	at thin p	lates			Stres	s & Str	ain Tra	ansforr	nations	6			Energ	y Metł	nods		
Duration	(hour)	12		1	12				12	2						12							12			
S-1	SLO-1	Introduction – course o Equilibrium, compatibili relations in macroscopi problems for illustration stress at a point in 3D,	verview, ity, and constitutive c form, simple n, Definition of representation on	Bending Stresses in straight) due to symm review and definition bending	beams (in netrical loa of un-sym	nitially ading – f nmetrical	Introduci plate, re circular p comparis structura	tion to ctangul plates, son wit al mem	flat plat lar and thin vs h bean ber (20	tes – de axi-syr thick p ns (1D)), typic	efinitio mmetr lates, as a al rea	n of a ic I-world	Con and Cart direc expr	cept of a vect esian ction co ession	a tens or), 2D coordir osines s	sor (in stress nate sy – deriv	relation transf stem u vation	n to a s formati ising of	scalar on in	Work, perfec due to stress shear	Strain ctly ela o - uni es in c stress	energ stic ma axial st other pe	y defir iterials ress, a erpend	ition fo ; strair addition licular	or linea n energ nal nor directio	r, Iy mal <mark>ons,</mark>

	SLO-2	an element and sign convention		applications. Linear vs non-linear bending – definition. Derivation of governing equation for bending of a flat, thin, rectangular plate – outline of procedure		
S-2	SLO-1 SLO-2	Definition of strain based on small- displacement theory and strain tensor in 3D Cartesian coordinate system, equilibrium and compatibility relations in differential form in Cartesian coordinate system	Bending stresses in beams due to un- symmetrical bending (plane of loading not coinciding with plane of symmetry, even if it exists) – explanation of theory in decoupling the problem into sub-problems using the concept of principal axes and moments of inertia	definition of strains, stresses, and moments and use of these parameters in derivation of governing equation for plate bending (based on Kirchhoff theory) – use of strain-displacement, and stress-strain relations	Stress transformation problems in 2D– numerical problems and depiction of results (normal and shear stresses) on an element based on computation	strain energy due to - general state (3D) of stress, plane stress
S-3	SLO-1 SLO-2	Introduction to and comparison with mechanics of materials approach, definition of Plane stress and plane strain linear elastic problems, Airy's stress function - introduction	Application of theory in computing bending stresses and determination and location of neutral axis	Use of equilibrium equations and completion of derivation of governing equation; specification of different boundary conditions generally used – simply supported, clamped, free	3D stress transformation in Cartesian coordinate system using direction cosines – relevant formulas as an extension based on derivation for 2D	Total strain energy in bars with simple loading conditions – axial loading, torsional loading of a solid circular bar, and transverse loading
S-4	SLO-1 SLO-2	Practice problems on use of equilibrium, compatibility, and constitutive relations	Practice problems on bending stress computation and location of neutral axis	Practice questions on concepts related to plates covered in the earlier lectures	Numerical problems for practice in stress transformation	Practice problems in strain energy computation – due to axial, torsional, and transverse loading
S-5	SLO-1 SLO-2	Airy's stress function in rectangular coordinates – derivation of the biharmonic equation	Deflection due to unsymmetrical bending; A quick review of shear stress in beams due to bending, shear stress computation in beams having rectangular sections	Solution due to sinusoidal bending load on a simply supported plate- step-by-step explanation	Concept of principal stresses, Derivation of characteristic equation for determination of principal stresses in 3D (after doing it for 2D), maximum shear stress	Castigliano's 1st theorem, example problems
S-6	SLO-1 SLO-2	simple problems related to axial loading of bars, bending of beams using Airy's stress function in rectangular coordinates	Intro to shear center, determination of shear center for a symmetrical channel section	Numerical problems on thin, flat rectangular plates – to compute moments and stresses based on given displacement function	Numerical problems (in 2D and 3D based on the above lectures)	brief overview of material non-linearity and plasticity;The complementary energy theorem, and Castigliano's 2nd theorem,
S-7	SLO-1	Additional illustrative problems related to bending of beams using Airy's stress function	determination of shear center for T, unequal I, sections, intro to bending of curved beams	Derivation of governing equation for bending of a flat, thin, axi-symmetric circular plate – outline of procedure - definition of strains, stresses, and moments	strain transformation and principal strains in 2D & 3D for linear, homogeneous, isotropic material. Overview of the derivation to show the difference in approach compared to stress transformation and direct adaptation of	Illustrative problems using Castigliano's 1st & 2nd theorems (for linear materials)
	SLO-2				stress transformation equations	
S-8	SLO-1 SLO-2	Practice problems on Airy's stress function	Numerical problems on deflection, location of shear center	Numerical problems for practice in determining deflection, moments, and stresses in flat plates due to bending given displacement function	Numerical problems for practice on determination of principal stresses, maximum shear stress, and orientation of principal axes	Practice problems in the use of Castigliano's theorem(s)
S-9	SLO-1	overview of torsion of structural members having non-circular sections, Prandtl stress function for torsion, derivation of Poisson's equation (using Prandtl stress function)	Derivation of circumferential stress expression	Continued from previous lecture - use of strain-displacement, stress-strain, and equilibrium relations in derivation of governing equation (for bending)	Numerical problems on 3D strain computation, transformation, and determination of principal strains	Rayleigh's method, example problem of beam bending deflection
S-10	SLO-1	Membrane analogy, brief discussion of torsion of rectangular cross section	Numerical problems on determination of circumferential stresses (rectangular and square sections)	derivation of equations for displacement, support reactions, and maximum stresses for a uniformly loaded, simply supported circular plate	Numerical problems on stress-to-strain and strain-to-stress computation using constitutive relations, transformation, and determination of principal strains/stresses	Rayleigh-Ritz method applied to beams in bending
S-11	SLO-1 SLO-2	torsional stress in hollow closed thin- walled (single cell) tubes – overview and expressions for shear stress and angle of twist	Additional illustrative problems on determination of circumferential stresses (rectangular and square sections); a brief intro (only) to radial stresses in curved beams	Illustrative problems on bending of flat, thin, axi-symmetric circular plates - to compute moments and stresses based on given displacement function	Overview of Maximum principal stress, principal strain, maximum shear stress therories of failure , illustrative examples	Illustrative problems based on Rayleigh- Ritz method
S-12	SI 0-1	Practice problems on torsion	Practice problems on determination of	Practice questions/problems on concepts	Numerical problems on strain	Numerical problems for practice in the use

SLO-2			circumferential stress in curved beams	related to axi- bending and o parameters	-symmetric circula determination of re	r plate elated	transformation, determination of principal stress/strain using constitutive relations	of Rayleigh-Ritz method
Learning Resources	1. 2. 3. 4.	Arthur Boresi and Richardh 3 & Sons, 6ed, 2009 Ansel C. Ugural and Saul K Elasticity," Prentice Hall; 5th Richard G Budynas, "Advan International Editions, 1999 L. S. Srinath, " Advanced Me 2017 S. P. Timoshenko and J. N.G	Schmidt, "Advanced Mechanics of Materia . Fenster, "Advanced Mechanics of Materia ed.,2011 ced Strength and Applied Stress Analysis. schanics of Solids," McGraw Hill Education condier." Theory of Elasticity." McGraw Hil	als," John Wiley als and Applied ," McGraw Hill n, 3rd edition,	6. 7. 8. 9.	G. T. Ma CRC Pre Y. C. Fur Stephan Solids," N Robert C 1998	se, R, E, Smelser, and G, E, Mase, "Continu ss, 2004 ng, "Foundations of Solid Mechanics," Prenti H Crandal, Norman C Dahl, Thomas J Lardr McGraw Hill, 2nd edition,1978 took and Warren Young, "Advanced Mechan	um Mechanics for Engineers," 3rd edition, ce Hall International, 1965 ner," An Introduction to the Mechanics of ics of Materials," Pearson, 2nd edition,

	Bloom's	Continuous Le	arning Assessmer :LA-1	it (CLA) (60% weightage	e) CLA-2		Final Examination (40% weightage)				
	Remember	(2	20%)		(25%)	CLA-3 (15%)					
		Theory	Practice	Theory	Practice	024-3 (1370)	Theory	Practice			
Level 1	Remember	20		20			20				
Level	Understand	20		20			20				
Lovel 2	Apply	90		90		100	90				
Level Z	Analyze	00		00		100	00				
Lovel 2	Evaluate										
Level 5	Create										
	Total	100 %		100 %		100 %	100 %				

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	Dr Joel George M, Asst. Prof., Aerospace Engg, IIT Madras	Dr S H Venkatasubramanian, Visiting Professor, Dept of Mechanical Engg., SRMIST
2. Dr.A. Velayutham, DRDO, Avadi, vel_sivam@yahoo.com	Dr Ranjith Mohan, Asst Prof., Aerospace Engg, IIT Madras	

Course	20MEE504T	Course	Course E	Professional Elective	L	Т	Р	C	
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Code	Name	Mechanical Beh	havior of Engineering Materials	Category		3	1	0	4
Pre-requisite Courses		Co-requisite Courses	Nil	Progressive Courses	Nil				
Course Offering Department	Mechanical Engineering	γ	Data Book / Codes/Standards	Nil					

Course Learning Rationale (CLR): The purpose of learning this course is to:	L	Learnin	Ig					Prog	ram l	_earn	ning C	lutcor	nes (I	PLO)			-	
CLR-1 : Be familiar with the structure and properties	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 : Be familiar with tension and torsion																		
CLR-3 : Know about fatigue				0									ce		т			I
CLR-4 : Know about creep	Ê	(%)	(%)	dge			60					ng	eten		mer			I
CLR-5 : Be familiar with fracture mechanics				owle	ല്പ	ß	oning			guing	king	earni	ompe	ing	ıgage		ls	ning
CLR-6 : Know about the mechanical behavior of materials				inary Kr	Thinkir	n Solvin	cal Reas	th Skills	Vork	ic Rease	ve Thin	rected L	ltural C	Reason	unity En	ills	ship Skil	ng Lear
Course Learning Outcomes (CLO): At the end of this course, learners will be able to:	Level of	Expecte	Expecte	Discipl	Critical	Probler	Analyti	Researd	Team V	Scientif	Reflecti	Self-Di	Multicu	Ethical	Comm	ICT Sk	Leaders	Life Lo
CLO-1 : Recognize and analyze the structure and properties	1& 2	2 90	85	Н	Н	М	М	L	-	М	-	-	-	-	-	-	-	М
CLO-2 : Acquire knowledge on tension and torsion				Н	Н	М	L	М	-	L	-	-	-	-	-	-	-	М
CLO-3 : Acquire knowledge on fatigue				Н	М	М	М	L	-	L	-	-	-	-	-	-	-	М
CLO-4 : Acquire knowledge on creep	1& 2	2 90	85	Н	Н	L	М	L	-	L	-	-	-	-	-	-	-	L
CLO-5 : Understandfracture mechanics	1& 2	2 90	85	H	H	Ĥ	М	M	-	M	-	-	-	-	-	-	-	H
CLO-6 : Acquire knowledge about mechanical behavior of engineering materials				Н	Н	Н	М	М	-	М	-	-	-	-	-	-	-	М

		Structure and Properties	Tension & Torsion	Fatigue	Сгеер	Fracture and Fracture Mechanics
Du (h	ration our)	12	12	12	12	12
C 1	SLO-1	Crystal Structures	Stress - Strain curve	Fatigue phenomena	Description of creep	Types of fracture
3-1	SLO-2	Crystallographic planes & directions				
6.2	SLO-1	Defects in crystals	Measures of yielding	Theories of fatigue failure	Creep curve, Stress-rupture test	Theoretical strength of a solid
3-2	SLO-2					
6.2	SLO-1	Crystal anisotropy	Measures of ductility, Toughness	Evaluation of fatigue resistance	Creep mechanisms	Griffith's Theory
3-3	SLO-2	Microstructure				
64	SLO-1	Deformation	Strain hardening exponent	Methods of presenting fatigue data	Dislocation glide, Diffusion flow	Irwin - Orowan Theory - crack propagation Modes
3-4	SLO-2	Dislocation & Twining	Strain rate sensitivity			
8.5	SLO-1	Dislocation – generation & multiplication	Anisotropy	Fatigue crake propagation	Dislocation and Diffusion	Dislocation Theories of Brittle fracture
0-0	SLO-2	Dislocation – annihilation				
.	SLO-1	Dislocation – Interaction	Mechanical properties in torsion	Parameters influencing fatigue	Creep in two phase alloys	Ductile fracture
3-0	SLO-2	Dislocation – Mechanical properties				
6.7	SLO-1	Strengthening mechanisms	Tensile test	Cyclic stress strain behavior	Deformation Mechanism Maps	Analysis of crack propagation
3-1	S-7 SLO-2	Grain boundary strengthening	Compression test			

	SL0-1	Strain hardening	Types of torsion failures	Design against fatigue	Matarials aspects croop design	Stross intonsity factor
3-0	SLO-2		Torsion test	Design against laugue	Materials aspects creep design	
5.0	SL0-1	Solid solution hardening	Method of measuring shear stress	Low cycle fatigue	Estimates of creep behavior	Crack opening displacement
3-9	SLO-2					
S-10	SL0-1	Precipitation hardening	Hardness	Fatigue failure of metals	Presentation of Engineering creep data Super plasticity	J integrals - Fracture toughness measurement methods
5-10	SLO-2		Micro-hardness			
S-11	SL0-1	Martensitic strengthening	Nano-indentation	Fatigue of ceramics	Creep fracture	Material behaviour during crack propagation
5-11	SLO-2	Texture hardening				
S-12	SLO-1 SLO-2	Strengthening in composite materials	Analysing nano-indentation results	Fatigue of polymers	Increasing the creep resistance	Measuring elastic-plastic fracture mechanics parameters

Learning Resources	1.	George E. Dieter, "Mechanical Metallurgy", McGraw Hill, 1988	3. Joachim Roesler, Harald Harders, Martin Baeker, Mechanical Behaviour of Engineering Materials, Springer, 2007
	2.	Thomas H. Courtney, "Mechanical Behaviour of Materials", McGraw Hill 2000	 Joseph Marin, "Mechanical Behaviour of Engineering Materials", Prentice-Hall of India Pvt. Ltd., 1966

			Continuous Learning Assessment (CLA) (60% weightage)								
	Bloom's Level of Thinking	CL (2)	A-1 0%)	C (2	:LA-2 25%)	CLA-3 (15%)	(40% weightage)				
		Theory	Practice	Theory	Practice		Theory	Practice			
Level 1	Remember Understand	40%		30%	-	30%	30%				
Level 2	Apply Analyze	40%		50%	-	50%	50%				
Level 3	Evaluate Create	20%		20%	-	20%	20%				
Total 100 %			0%	10	00 %	100 %	10	0%			

Course Designers									
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts							
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	Dr. Sudheesh Kumar, sudheeshkumar3@gmail.com, GCE, Kannur	Dr T V V L N Rao, SRM IST							
2. Dr.A. Velayutham, DRDO, Avadi, vel_sivam@yahoo.com	Dr.R.Prabhu sekar, rprabhusekar@mnnit.ac.in, MNNIT Allahabad	Dr. Shubhabrata Datta, SRMIST							

Course Code	201455651	Course		Course	F	Drefeesienel Fleeting	L	Т	Ρ	С
Course Code	20101EE303J	Name	COMPUTER GRAPHICS AND VIRTUAL REALTT	Category	E	Professional Elective	3	0	2	4

Pre-req Cours	uisite ses	Nil		Co-requisite Courses	Nil		Progressive Courses		Nil																
Course Offe	ering Dep	partment	Mechanical Engineering		Data Book / Codes/Standards		Nil																	·	
Course Lea	burse Learning Rationale (CLR): The purpose of learning this course is to:				L	earnin	g						Pr	ogram	n Learr	ning C	outcom	nes (P	LO)						
CLR-1 :	R-1: Be familiar with the basics of computer graphics and its components			1	2	3		1	2	3	4	5	6	7	8	9	10	11	12	13	14	15			
CLR-2 :	Be famili	iar with the complete I	knowledge of 2D and 3D gr	raphics																					
CLR-3 :	Be famili	iar with the curves and	l surfaces																						
CLR-4 :	Be familiar with the graphical kernel system and graphics exchanges standards				۲	(9	(9											e		Ŧ			ĺ		
CLR-5 :	Be famili	iar with the concepts o	of virtual reality and augme	nted reality			(Bloor	ncy (9	ent (%		rledge			ing			ing	Ð	ming	peten	_	gemer			6
CLR-6 :	Conceive	e the knowledge on gi	raphics and associated top	ics with introduction	to VR&AR.		nking	roficie	ttainm		Know	king	lving	easor	kills		eason	hinkin	d Lea	l Com	soninç	Enga		Skills	earnin
Course Lea	arning Out	tcomes (CLO):	At the end of this course,	learners will be abl	e to:		Level of Thi	Expected P	Expected A		Disciplinary	Critical Thin	Problem So	Analytical R	Research S	Team Work	Scientific Re	Reflective T	Self-Directe	Multicultura	Ethical Rea	Community	ICT Skills	Leadership	Life Long Le
CLO-1 :	Understa	anding the history and	development in the compu	uter graphics, and s	olve 2D&3D transformations		1	85	75		Н	Н	М	Н	Н	Н	Н	Н	Н	L	L	М	Н	L	Н
CLO-2 :	Understa	anding the 2D and 3D	rendering pipeline				1,2	80	70		Н	М	Н	Н	Н	Н	Н	Н	Н	L	L	М	Н	L	Н
CLO-3 :	Apply curves and surfaces to create surface modeling for various application.					2,3	80	70		Н	Н	Н	Н	Н	Н	Н	Н	Н	L	L	Н	Н	L	Н	
CLO-4 :	Create data exchange files to communicate between graphics system					1,3	75	70		Н	Н	Н	Н	Н	L	Н	Н	Н	L	L	Н	Н	L	Н	
CLO-5 :	Understanding how virtual reality and augmented reality adds digital elements to a live view for better experience					1,2	75	70		Н	Н	М	Н	Н	Н	Н	Н	Н	L	L	Н	Н	L	Н	
CLO-6 :	Understanding the knowledge on computer graphics and connected topics to apply and create graphic system					1,2,3	75	70	1	Н	Н	Н	Н	Н	М	Н	Н	Н	L	L	Н	Н	L	Н	

	Introduction to Computer Graphics		Two and Three Dimensional Graphics	Curves and Surfaces	Graphics Standards and Open GL	Virtual and Augmented Reality
Durati	on (hour)	15	15	15	15	15
S-1	SLO-1	History of Computer Graphics	2D viewing – viewing pipeline, viewing coordinate reference frame	Introduction to curve and its types	Introduction to Graphic Kernel System, Initial Graphics Exchange Specification (IGES)	Virtual vs Interactive vs Immersive, Virtual Reality (VR) vs Augmented Reality (AR), Real vs Virtual.
S-2	SLO-1	Video Display Devices, Raster Scan and Random Scan Systems	Window-to-viewport coordinate transformation, Two dimensional viewing functions	Hermite curves	Standard for the Exchange of Product Model Data (STEP), Drawing Interchange Format, or Drawing Exchange Format (DXF)	Benefits of VR: 3D Visualization, Navigation, Interaction, Physical Simulation, Virtual environments.
S-3	SLO-1	Graphics monitors and Workstations, Input devices, Hard copy Devices, Graphics Software	Clipping operations – point, line	Bezier curves	Continuous Acquisition and Life-cycle Support (CALS), Stereo Lithography (STL)	VR Hardware: Computers, Tracking Devices, Input Devices, Output Devices, Glasses, Displays, Audio.
S-4 S-5	SLO-1	Demo on Graphic Systems	Exercise on Clipping operations	Exercise on curve generation	Exercise on data exchange	Exercise on VR
S-6	SLO-1	Output primitives – points and lines, line function and line drawing algorithms (DDA & Bresenham's algorithm)	Polygon clipping algorithms, Scan Conversion	B-Spline	Communication Standards - LAN	Head Mounted Display (HMD), Motion Trackers
S-7	SLO-1	circle generating algorithms (mid-point circle algorithm), Loading the frame buffer	3D viewing - viewing pipeline, viewing coordinates	Rational	Communication Standards – WAN. P2P	BOOM, CAVE, Sensor Glove, Haptic Feedback devices.
S-8	SLO-1	Pixel addressing and object geometry, filled area primitives.	Projections, Clipping	Surface Modeling techniques – Coons patch	Open GL – Features in OpenGL, OpenGL operations, Abstractions in OpenGL – GL, GLU & GLUT	VR Software: VR Software Features, Web- Based VR, Division's dVISE
S-9 S-10	SLO-1	Exercise on Line & circle drawing algorithms	Exercise on Projections	Exercise on curve generation	Exercise on data exchange	Exercise on VR/AR
S-11	SLO-1	O-1 2D Transformation - Translation, Rotation, Scaling, composite transformations. Hidden line removal algorithms		Bi-cubic patch	Input and Interaction in OpenGL	Blueberry3D, Boston Dynamics, MultiGen

S-12	SLO-1	3D Transformation - Translation, Rotation, Scaling, composite transformations.	Hidden surface removal algorithms	Bezier surfaces	3D viewing pipeline in OpenGL	VR and AR Applications: Industrial, Training Simulators, Entertainment
S-13	SLO-1	Composite Transformations	Algorithms for shading and rendering.	B-spline surfaces	Viewing matrix (model-view matrix) specifications	VR/AR Centres
S-14 S-15	SLO-1	Exercise on 2D & 3D transformation	Exercise on Shading and Rendering	Exercise on Surface generation	Exercise on open GL programming	Exercise on VR/AR

	1.	Edward Angel and Dave Shreiner, "Interactive Computer Graphics – A Top-down Approach with	5.	J. D. Foley, A. Van Dam, S. K. Feiner and J. F. Hughes, Computer Graphics – Principles and Practice, 2nd Edition
		Shader-Based OpenGL", 6th Edition, Addison Wesley.2012		in C, Pearson Education, 2003.
Learning	2.	Kunwoo Lee "Principles of CAD/CAM/CAE Systems", Addison Wesley. 1999.	6.	D. F. Rogers and J. A. Adams, Mathematical Elements for Computer Graphics, 2nd Edition, McGraw Hill,
Resources	3.	Chris McMahon, Jimmie Browne, "CADCAM: Principles, Practice and Manufacturing Management",		International Edition, 1990.
		2nd Edition, Addison Wesley, 2018.	7.	John Vince, "Introduction to Virtual Reality", Springer-Verlag London, 2004.
	4.	Zeid, Ibrahim. CAD/CAM theory and practice. McGraw Hill, International Edition, 1998.	8.	Gregory Kipper, Joseph Rampolla, "Augmented Reality – An Emerging Technologies Guide to AR", Syngress, 2012.

			Continuous L	earning Assessment (CLA) (60%	weightage)		Final Ex	amination			
	Bloom's Level of Thinking	CL. (20	A-1)%)	CL (25	A-2 5%)	CLA-3 (15%)	(40% weightage)				
		Theory	Practice	Theory	Practice	0210(10)0	Theory	Practice			
Level 1	Remember Understand	- 20% 20% 2		20%	20%	20%	20%	20%			
Level 2	Apply Analyze	20%	20%	20%	20%	20%	20%	20%			
Level 3	Evaluate Create	10%	10%	10%	10%	20%	10%	10%			
	Total	100) %	10	0 %	100 %	10	0%			

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Dr. S. Balamurugan, iRCS, Bangalore	Dr. Seung Nam Min, Shinsung University, South Korea	Dr. T. V. Gopal, SRM IST
	Dr. Kyung-sun Lee, Catholic University, Busan	Dr. S. Murali, SRM IST

Course Code	20MEE506T	Course Name		BIOMECHA	NICS	Course Category	F	Professional Elective	L	Т	Р	С
000130 0000	ZOMELOOOT	oourse Marine		DIOMEON		oourse outegory	L	Trolessional Elective	4	0	0	4
Pre-requisite Cou	ırses NIL		Co-requisite Courses	NIL		Progressiv	e Courses	NIL				
Course Offering I	Department	Mechanical Engine	eering		Data Book / Codes/Standards	NIL						

Course L	Course Learning Rationale (CLR): The purpose of learning this course is to:						
CLR-1 :	Understand the fundamental of musc	lar and skeletal systems	1	2	3		
CLR-2 :	To Understand the principles of mech	anics muscular and skeletal systems					
CLR-3 :	2-3: To Understand the mechanics of soft tissues						
CLR-4 :	Experimental and computational tools	Bloc	JcV (ent (
CLR-5 :	Applications in Biomechanics) bu	cier	hme		
CLR-6	To study about the bone structure and	f functions of skeletal muscle	Thinki	ed Profi	ed Attai		
			el of	ecte	ecte		
Course L	earning Outcomes (CLO):	At the end of this course, learners will be able to:	Lev	Exp	Exp		
CLO-1 :	To familiarize the students with the ar	atomical structure of the human body	1& 2	90	85		
CLO-2 :	To familiarize the students with the re	ference positions, planes, and axes associated with the human body	1	85	80		
CLO-3 :	Understand and quantify the Muscle-	Tendon Function	1	85	80		
CLO-4 :	To understand how to test the biologic	cal specimens and human body in a laboratory environment	1&2	85	80		
CLO-5 :	1-5 : To understand the application of Biomechanics and apply biomechanics knowledge to real-world problems				80		
CLO-6 :	LO-6 : To understand the skeletal function and biomechanics						

	Program Learning Outcomes (PLO)													
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Disciplinary Knowledge	Critical Thinking	Problem Solving	Analytical Reasoning	Research Skills	Team Work	Scientific Reasoning	Reflective Thinking	Self-Directed Learning	Multicultural Competence	Ethical Reasoning	Community Engagement	ICT Skills	Leadership Skills	Life Long Learning
H	Н	Н	Н	Н	L	Н	Н	Н	Н	Н	M	Н	L	Н
Н	Н	Н	Н	Н	L	Н	Н	Н	Н	Н	М	Н	L	Н
H	Н	Н	Н	Н	L	Н	Н	Н	Н	Н	M	Н	L	Н
Н	H	H	H	H	L	H	H	H	H	H	\overline{M}	H	L	H
Н	Н	Н	Н	Н	L	Н	Н	Н	Н	Н	М	Н	L	Н
Н	Н	Н	Н	Н	L	Н	Н	Н	Н	Н	M	Н	L	Н

Duration	n (hour)	12	12	12	12	12
S-1	SLO-1	Biomechanics: definition and perspective	Standard reference terminology and anatomical reference position	Musculoskeletal Soft Tissue Mechanics	Experimental testing in Biomechanics	Biomechanics in Ergonomics Theories of occupational musculoskeletal injury causation
S-2	SLO-1	Quantitative versus qualitative problems	Directional terms, anatomical reference planes and axes joint movement terminology	Structure of Soft Tissue Cartilage, Tendon and Ligament, Muscle.	Biomechanical testing instruments	Biomechanics in work seating design - biomechanics during ladder and stair climbing and walking on ramps.
S-3	SLO-1	Solving Formal Quantitative Problems	Sagittal plane, frontal plane, transverse plane and other movements and spatial reference systems	Composition of tendons and ligaments Mechanical properties	Problems in testing , repeatability , reproducibility , reliability of results	Injury biomechanics and rehabilitation
S-4	SLO-1	Structure, movements and loads on the shoulder.	Equilibrium and Torque , Resultant Joint Torques	Determination of stress and strain, stress - strain curve for tendons and ligaments	Pit falls of biomechanical testing	Orthotics and prosthetics
S-5	SLO-1	Structure, movements and loads on the wrist	Levers Anatomical levers,	Material Properties Cartilage, Tendon.	Computational methods in biomechanics	Biomaterials for implant design
S-6	SLO-1	Structure, movements and loads on the elbow.	Bone behavior under various loads tension compression shear	Material Properties Ligament, Muscle.	Loading and results in computational studies	Sports biomechanics- Qualitative analysis of kicking technique
S-7	SLO-1	Structure, movements and loads on the hip	Basic concepts related to kinetics, inertia,mass,force	Joint Architecture, Synovial joint and loads in joints	Tools for Measuring Body Angles	Qualitative analysis of batting
S-8	SLO-1	Structure, movements and loads on the knee	Centre of gravity ,weight ,pressure volume, density, torque, impulse	Behavioural properties of the Musculotendinous unit	Tools for measuring kinematic quantities video and film	Qualitative analysis of the basketball free throw
S-9	SLO-1	Structure, movements and loads on the spine	Locating the human body Center of Gravity, Stability and balance, Gait analysis.	Factors affecting muscular Force generation	Other movement-monitoring systems.	Qualitative analysis of squat technique
S-10	SLO-1	Structure, movements and loads on the foot	Properties of Bone, Maxwell & Voight Models of bone	Mechanical characteristics Of muscle Force–velocity relationship	Stride and Temporal Parameters , Motion Measurement,	Qualitative analysis of drop jumps
S-11	SLO-1	Common injuries in shoulder, elbow wrist	Common Bone Injuries	Mechanical characteristics Of muscle Force–length relationship	Ground Reaction Measurement Dynamic Electromyography (EMG)	Cardiac Biomechanics ,Cardiovascular biomechanics,
S-12	SLO-1	Common injuries in hip knee, spine and foot.	Forms of motion -linear motion, angular motion general motion and mechanical systems	Mechanical characteristics Of muscle Force–time relationship	Challenges in - In vitro, In vivo and in silco study a and comparison	Mechanics of Blood Vessels, Dental Biomechanics

Learning 1. 2. Resources 3.	. Susan .J. Hall, —Basic biomechanics", Tata Mcgraw Hill, Sixth edition, 2011 Y. C. Fung, Biomechanics - Circulation Springer Verlang, 2nd Edition, 1997. D. J. Schneck and J. D. Bronzino, —Biomechanics- Principles and Applications", CRC Press, Second Edition, 2000	4. 5.	Kreighbaum, E. and Barthels, K. (1996). Biomechanics: A Qualitative Approach for Studying HumanMovement 5.Dr.Ajay Bahi and Dr.Sharad Ranga- Basics of Biomechanics, Jaypee brothers medical publication (P) Ltd.
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			Final Examination								
	Bloom's Level of Thinking	CL. (20	A-1)%)	Cl (2	LA-2 25%)	CLA-3 (15%)	(40% weightage)				
		Theory	Practice	Theory	Practice	0210 (1070)	Theory	Practice			
Level 1	Remember Understand	20%	20%	20%	20%	20%	20%	20%			
Level 2	Apply Analyze	- 20%	20%	20%	20%	20%	20%	20%			
Level 3	Evaluate Create	uate 10% 10% 10% 10%		20%	10%	10%					
	Total	100	0 %	10	00 %	100 %	10)%			

Course Designers											
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts									
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	Dr. Amit Roy Chowdhury, amit@aero.iiests.ac.in, IISER Shibpur	Mr.P.Susai Manickam, SRMIST									
2. Dr.A. Velayutham, DRDO, Avadi, vel_sivam@yahoo.com		Mr. D. Raja, SRMIST									

Course Code	20MEE601T	Course Name	ADVANCED I	FINITE ELEMENT ANALYSIS	Co Cat	urse E egory	Professional Elective	-	L 4	T 0	P 0	C 4
Pre-requisit Courses	e 20MEC502J		Co-requisite Courses	Nil		Progressive Courses	Nil					
Course Offerin	g Department	Mechanical Engineering		Data Book / Codes/Standards		Nil						

Course Le	arning Rationale (CLR):	The purpose of learning this course is to:		L	.earnir	ng	Program Learning Outcomes (PLO)															
CLR-1 :	Be aware in basic theory of Ber	nding of plates and shells		1	2	3		1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Be aware in Formulation of the	Continuum Mechanics																				.
CLR-3 :	Be aware in Nonlinear equatior		(c													e		Ŧ				
CLR-4 :	Be aware in concept of Finite Element Analysis of Heat Transfer							dge			b			-		bu	tenc		men			
CLR-5 :	Be aware in concept of Finite E	lement Analysis of Incompressible Fluid Flows		g (B	ienc	mer		wle	_	5	onin			ninç	king	arni	mpe	bu	Jage		s	ing
CLR-6 :	Be aware in Error estimation ar	d shear locking phenomena	nking Iving as of teams of the second of the						sd Le	ပိ	soni	Enç		Skil	eam							
				f Th	ed P	ed A		nary	Thir	n Sc	cal F	ch S	Nork	fic R	ive	recte	ltura	Rea	unity	sli	ship	ng L
Course Le	arning Outcomes (CLO):	At the end of this course, learners will be able to:		Level c	Expect	Expect		Discipli	Critical	Probler	Analyti	Resear	Team \	Scienti	Reflect	Self-Di	Multicu	Ethical	Commu	ICT Sk	Leader	Life Lo
CLO-1 :	Understand the Classical and N	indlin theory		Н	85	75		Н	Н	Н	H	Н	L	Н	Н	Н	L	L	L	Н	L	Н
CLO-2 :	Understand the Non-linear ana	ysis of bar and beams		Н	75	70		Н	Н	Н	Н	Н	L	Н	Н	Н	L	L	L	Н	L	Н
CLO-3 :	Understand the non-linear dyna	mics problems and numerical techniques		H 75 70 H H					Н	Н	Н	L	Н	Н	Н	L	L	L	Н	L	Н	
CLO-4 :	Understand the Basic concept	f non-linear Finite Element Analysis of Heat Transfer, and Incompressible Fluid Flows		Н	75	5 70 H H H H H L H H L L L					L	Н	L	Н								
CLO-5 :	i: Understand the error and rate of convergence study H 75 70							Н	Н	Н	Н	Н	L	Н	Н	Н	L	L	L	Н	L	Н
CLO-6 :	3: Understand the shear locking zero-energy modes for finite elements							Н	Н	Н	Н	Н	L	Н	Н	Н	L	L	L	Н	L	Н

		BENDING OF PLATES AND SHELLS	NON – LINEAR STATIC ANALYSIS OF BARS AND BEAMS	DYNAMIC ANALYSIS	FLUID MECHANICS AND HEAT TRANSFER ANALYSIS	ERROR ESTIMATES, CONVERGENCE, ZERO- ENERGY MODE AND ADAPTIVE REFINEMENT
Durati	on (hour)	12	12	12	12	12
S-1	SLO-1 SLO-2	Bending of Plates - Basic concept of Finite Element Method	Nonlinear Problems- Introduction-Types of Nonlinearities-	Introduction-Dynamic equations-Mass and Damping matrices	Basic concept of Finite Element Analysis of Heat Transfer, Field Problemsand Incompressible Fluid Flows	Shear locking and its remedy for triangular and quadrilateral elements
S-2	SLO-1 SLO-2	Basic concept of Classical plate and Shear deformable plate theory Confirming and non- Confirming Elements	Formulation of the Continuum Mechanics Incremental Equations of Motion - The Basic Problem, -The Deformation Gradient, Strain, and Stress Tensors,	Natural frequencies-and modes Damping- Proportional damping-modal damping	Heat Transfer Analysis -Governing Heat Transfer Equations- Incremental Equations- Finite Element Discretization of Heat Transfer Equations	Rate of convergence and types of error norms triangular and quadrilateral elements
S-3	SLO-1 SLO-2	Simple examples to Basic concept of Classical plate	Simple examples- Basic Problem, -The Deformation Gradient, Strain, and Stress Tensors,	Simple example- Natural frequencies-and modes Damping	Simple examples –formulation of non-linear heat transfer analysis	zero- energy mode triangular and quadrilateral elements
S-4	SLO-1 SLO-2	Bending of plate model-Displacement model and Finite Element model- Co and C1 Continuity Elements	Displacement based Isoparametric Continuum Finite Elements-Truss and bar elements	Mass matrices – Particle mass lumping and Consistent mass matrices	Numerical examples to simple nonlinear heat transfer problems	Computer coding/ FEM existing software Assembly of elements and load calculation for non-linear FEM USING direct iteration
S-5	SLO-1 SLO-2	plate model- to sample problems – solution by hand	Elastic Material behavior-Rubber like material- Basic concept of Inelastic material -Visco Plasticity-Formulation	Direct Integration methods-Central difference method-Houbolt method-Newmark Methods	Numerical examples to nonlinear heat transfer problems using triangular elements	Computer coding/ FEM existing software Assembly of elements and load calculation for non-linear FEM using Newton's Methods
S-6	SLO-1 SLO-2	plate model- to sample problems – solution by hand	Elastic Material behavior-Rubber like material- Basic concept of Inelastic material -Visco Plasticity-Formulation	Direct Integration methods-Central difference method-Houbolt method-Newmark Methods	Numerical examples to nonlinear heat transfer problems using rectangular	Assembly of elements and load calculation for non-linear FEM using Newton's Methods
S-7	SLO-1 SLO-2	Classical plate model- to sample problems – solution by hand	Procedure to Tangent Stiffness matrix formulation Numerical Examples-by hand calculation	Mode superposition- Change of basis to modal generalized displacement-with damping and without damping	Numerical examples to nonlinear heat transfer problems using rectangular	Introduction to viscous low problems Governing equations
S-8	SLO-1 SLO-2	Introduction to shells-Circular Arches and Arch Elements	Numerical Examples-by hand calculation	Numerical Examples-by hand calculation	Analysis of incompressible fluid flow-Finite element Governing equations	Weak Formulation to Mixed inite element model (2D)

S-9	SLO-1 SLO-2	-1 Shells of Revolution-Thin shell-Mindlin shell Large deflection bending of bars and beams Basic concept and Solution to Nonlinear equations in dynamic analysis		Simple example-Solution to Navier-stroke equation using weighted residual method	Numerical examples using in-house coding/ FEM existing software	
S-10	SLO-1	General Isoparametric formulation-Three and four node shell elements asample Examples	Basic concept of Geometric Non linearity - Large displacement Formulation-Green strain-	Basic concept of Explicit integration-Implicit	Basic concept of fluid –structure interactions	Weak Formulation to Penalty Inite element model (2D)
	SLO-2		Corotational Formulation			
S-11	SLO-1	Three and four node shell elements -sample	Application in Metal Forming Process & Contact	Basic concept of Explicit integration-Implicit	Numerical examples to simple heat transfer and	Numerical examples using in-house coding/
0-11	SLO-2	Examples	calculation	Integration-mode superposition method	fluid mechanics problems	T Lin existing soluware
S-12	SLO-1 SLO-2	Four node shell elements -sample Examples Four node shell elements -sample Examples Contact antile		Numerical examples like simple pendulum, cantilever beam	Numerical examples to simple heat transfer and fluid mechanics problems	Numerical examples using in-house coding/ FEM existing software
L			1	Ш	1	l.

	1. Rao, S.S., he finite element method in engineering. Butterworth-Heinemann. 2017	
Learning	0 Dette 1/ L #Figite Element Decederer in Engineering Anchoist Develop Liett 0040	3. J N Reddy "Introduction to Non-Linear Finite Element Analysis" McGraw Hill Book Company New York; 2016
Resources	2. Bathe K.J. "Finite Element Procedures in Engineering Analysis", Prentice Hall, 2016.	4. Cook R.D., "Concepts and Applications of Finite Element Analysis", John Wiley and Sons Inc., New York, 1989.

			Final Examination									
	Bloom's Level of Thinking	CL (20	A-1 0%)	C (i	LA-2 25%)	CLA-3 (15%)	(40% weightage)					
		Theory	Practice	Theory	Practice		Theory	Practice				
Lovel 1	Remember	20%	20%	200/	20%	200/	20%	20%				
Level I	Understand	2076	2078	20 %	20 %	2078	20 /0	20 /0				
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%				
Level Z	Analyze	2078	2078	2078	2078	2078	2070	2070				
	Evaluate	10%	10%	10%	10%	20%	10%	10%				
Level 5	Create	1078	1078	10 %	10 %	2078	10 /6	10 /6				
	Total	100 % 100 % 100 %						0 %				
# CLA - 4 can be fro	m any combination of these: Assign	ments, Seminars, Tech Talks, Mir	ii-Projects, Case-Studies, Self-Stu	dy, MOOCs, Certifications, Conf.	Paper etc.,	L		-				
Course Designers			•		•							

Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr.Karthic Sethuraman, Valeo Pvt Ltd	Dr.Sundarajan Natarajan; IIT-madras	Dr.P.V.Jeyakarthikeyan, SRMIST
	Dr.Velamurali; ANNA university -chennai	Dr.P.Nandakumar, SRMIST

Course Code	20MEE602J	Course COM	POSITES MATERIAL	S - MECHANICS, DESIGN, AND MANUFACTURING	Course Category	Е	Professional Elective	L 3	T 0	P 2	C 4
Pre-requisit Courses	e _{Nil}		Co-requisite Courses	Nil	Progressive Courses	Nil					
Course Offerin	g Department	Mechanical Engineering		Data Book / Codes/Standards	Nil						

Course Le	aming Rationale (CLR): The purpose of learning this course is to:	L	earning	ing Program Learning Outcomes (PLO)																
CLR-1:	Know the basics of composite materials.	1	2	3		1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Acquire skills required in characterization of fiber-reinforced composites.																			
CLR-3:	Analyze the laminated composite beams.																			
CLR-4:	Predict the failure and design laminated composite.	(u	(%	(9											ce		nt			
CLR-5:	Acquire skills required in processing of different composite materials.	(Bloo	6) houe	rent (9		vledge			ning			ing	Бu	ırning	neten	g	igeme			ß
CLR-6:	Know the basic concepts, characterization, laminate analysis, failure prediction and processing techniques of composites.	of Thinking	ted Profici	ted Attainn		linary Knov	ll Thinking	em Solving	tical Reaso	arch Skills	Work	tific Reasor	tive Thinki	irected Lea	ultural Con	I Reasonin	nunity Enge	kills	rship Skills	ong Learnir
Course Le	arming Outcomes (CLO): At the end of this course, learners will be able to:	Level	Expec	Expec		Discip	Critica	Proble	Analy	Rese	Team	Scien	Reflec	Self-D	Multic	Ethica	Comn	ICT S	Leade	Life Lu
CLO-1:	Understand the basics of composite materials.	1, 2	90	85		Н	М	L	L	М	М	L	L	М	L	L	L	L	L	М
CLO-2:	Understand and practice the characterization of fiber-reinforced composites.	1, 2, 3	90	85		Н	Н	Н	М	Н	М	М	М	М	L	L	L	М	L	М
CLO-3:	Understand the analysis of laminated composite beams.	1, 2, 3	90	85		Н	Н	Н	М	Н	М	М	М	М	L	L	L	М	L	М
CLO-4:	Understand the failure prediction and design of laminated composite.	1, 2, 3	90	85		Н	Н	Н	Н	Н	М	М	М	М	L	L	L	М	L	М
CLO-5:	Understand and practice the processing of different composite materials.	1, 2, 3	90	85		Н	Н	Н	М	Н	М	М	М	М	L	L	L	L	L	М
CLO-6:	Understand the basic concepts, characterization, laminate analysis, failure prediction and processing techniques of composites.	1, 2, 3	90	85		Н	Н	Н	Н	Н	М	М	М	М	L	L	L	М	L	М

		Introduction	Mechanics and Performance	Analysis	Design	Manufacturing
Duration	n (hour)	15	15	15	15	15
S-1	SLO-1	Overview of materials - metals, polymers, ceramics	Develop concepts of volume and mass fractions, density, void content, and Rule of mixtures	Structural analysis of laminated beams	Failure theories for fiber-reinforced composites - Maximum stress theory and Maximum strain theory	Manufacturing of polymer matrix composites – Hand lay-up techniques
	SLO-2	Composite materials - Definition, Characteristics	Characteristics of fiber-reinforced lamina	Governing equations for beams	Azzi–Tsai–Hill theory, Tsai–Wu failure theory	Bag moulding process
6.2	SLO-1	Classification of composites	Elastic properties of lamina, stress – strain relationship for a thin lamina	Application of beam theory – bending	Problems on failure theories	Compression moulding process
0-2	SLO-2	Fiber reinforced composites	Problems on stress – strain relationship for a thin lamina	Problems on laminated beams - bending	Failure prediction in unnotched laminates	Pultrusion process
SLO-1		Particle reinforced composites	Compliance and stiffness matrices of lamina	Application of beam theory – buckling	Failure prediction in notched laminates	Filament winding process
3-3	SLO-2	Applications of composites	Problems on compliance and stiffness matrices of lamina	Problems on laminated beams - buckling	Problems on unnotched and notched laminates	Resin transfer molding, Resin film infusion process
S-4 & S-5	SLO-1	Demonstration on various constituent materials of composite	Measurement of density of lamina using Archimedes principle	Practice on stress – strain analysis of beams using software	Practice on modelling and analysis of laminates using software	Practice on fabrication of fiber reinforced polymer composites
<u> </u>	SLO-1	Fibers – types, Characteristics	Lamination theory –laminate stresses and strains	Vibration analysis of composite beams	Laminate design consideration - Design philosophy	Structural reaction injection molding, Tube rolling process
3-0	SLO-2	Characteristics of glass fibers	Force and moment resultants	Longitudinal vibration of laminated beam - governing equations	Design criteria, Design allowables	Forming methods - matched die forming, hydroforming, and thermoforming.
S 7	SLO-1	Characteristics of carbon fibers	Laminate stiffness matrix: A, B, D Matrix	Problems on longitudinal vibration of laminated beams	General design guidelines	Manufacturing of metal matrix composites - solid state processing – powder metallurgy
3-7	SLO-2	Characteristics of ceramic, boron and aramid fibers	Problems on laminate stiffness matrix	Transverse vibration of laminated beams - governing equations	Laminate design for strength	Liquid state processing - different casting methods
S-8 SLO-1 N		Natural fibers - types	Interlaminar stresses in laminates	Problems on transverse vibration of laminated	Laminate design for stiffness	Manufacturing of ceramic matrix composites -

				beams		hot pressing technique		
	SLO-2	Characteristicsof natural fibers	Mechanical properties of laminates – tensile, compressive properties	Reliability of composites	Design of bolted joints	Reaction bonding process, infiltration technique		
S-9 & S-10	SLO-1	Practice on fiber surface treatments	Practice on mechanical testing of laminates	Practice on vibration analysis of composites using software	Practice on design and fabrication of composite bolted joints	Practice on fabrication of metal matrix composites		
S-11	SLO-1	Matrix materials - characteristics	Shear, flexural properties of laminates	Finite element methods of analysis	Design of bonded joints	Quality inspection method – Radiography technique		
0.11	SLO-2	Polymer – characteristics of thermoset matrix	Fatigue properties of laminates	Problems on finite element methods of analysis	Ultrasonic inspection			
	SLO-1	Characteristics of thermoplastic matrix	Impact properties of laminates	Analysis of hygrothermal stresses in laminates	Design of a beam	Acoustic Emission technique		
S-12	SLO-2	Characteristics of metal matrices	Thermal properties of laminate	Problems on hygrothermal analysis of laminated composites	Design of corvette leaf springs	Acousto-Ultrasonic method		
	SLO-1	Characteristics of ceramic matrices	Environmental effects on laminates	Analysis of sandwich structures	Design of thin pressure vessels	Thermography		
S-13	SLO-2	Fillers and other additives,	Fracture behavior and damage tolerance	Problems on analysis of sandwich structures	Design of tubes for space station truss structure	Laser Shearography		
S-14 & S-15	SLO-1	Practice on incorporation of fillers in polymers	Practice on water absorption and flammability testing of laminates	Practice on thermal analysis of composites using software	ractice on thermal analysis of composites using Practice on design of composite product for offware			
Learning Resources		 Mallick, P.K., "Fibre Reinforced composite Agarwal, B.D and Broutman L.J, "Analys New York, 1990 Autar K. Kaw, "Mechanics of Composite N 	Hill, 2007 blishing Co., 1984					

			Final Examination									
	Bloom's Level of Thinking	(CLA-1 20%)	CL. (25	A-2 5%)	CL 4-3 (15%)	(40% weightage)					
		Theory	Practice	Theory	Practice	02/10(10/0)	Theory	Practice				
Level 1	Remember Understand	20%	20%	20%	20%	20%	20%	20%				
Level 2	Apply Analyze	20%	20%	20%	20%	20%	20%	20%				
Level 3	Evaluate Create	10%	10%	10%	10%	20%	10%	10%				
	Total	1	100)%								

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. P. Thanigaivelan, ,CSIR-Central Leather Research Institute, Adyar, Chennai thanik8@gmail.com	Prof. Debes Bhattacharyya, d.bhattacharyya@auckland.ac.nz University of Auckland, Newzeland	Dr. M. Kamaraj, SRMIST
2. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in		Dr. Shubhabrata Datta, SRMIST

3. Skill Enhancement Courses (S)

Course Code	e 20GNS501J	Course Name		RESEARCH PUBLISHING AND PRESENTING SKILLS	Course	Categ	lory	S	Skill Enhancement						L 1	т 0	P 2	C 2					
Course Offeri	Pre-requisite Courses Nil Co-requisite Courses Nil ourse Offering Department English and Foreign Languages Data Book / Codes/Standards								Nil	Progressive Courses						rses							
Course Learning Rationale (CLR): The purpose of learning this course is to:								g					Pro	gram L	eamir	ng Out	comes	(PLO))				
CLR-1 :	Practice different oral pres	entation material	preparations			1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Practice presenting techn	ques suitable for	different audiences																				
CLR-3: I	Prepare and typeset scier	tific documents to	or disseminating res	earch findings		(mo	(%)	(%)	e								-	nce		ent			
CLR-5	Litilize different intellectua	lating techniques	mechanisms			(Blo	ncy	ent	/ledc			ing			ing	b	Lui	pete	5	gem			b
CLR-6:	Evaluate amongst differer	t options available	e to present, publis	h research findings		king	ficie	ainm	Nor	ing	ing	asol	lls		ason	inkir	Lea	Com	oning	inga		kills	arnin
<u>_</u>	*			×		Thin	Pro	d Att	ary	hink	Solv	al Re	h Sk	ork	Re	eΤ	cted	ural	keas	ΞÂ	s	in S	g Le:
Course Learn	ing Outcomes (CLO):	At the en	d of this course, lea	arners will be able to:		Level of .	Expected	Expected	Disciplin	Critical T	Problem	Analytica	Researc	Team W	Scientific	Reflectiv	Self-Dire	Multicult	Ethical R	Commur	ICT Skill	Leaderst	Life Lonç
CLO-1 :	Identify different oral pres	entation elements	, materials and tech	nnologies		3	85	80	L	Н	Н	М	М	-	L	Н	М	-	Н	-	L	-	М
CLO-2 :	Practice high impact pres	entation skills				3	85	80	L	Н	Н	М	М	-	L	Н	М	-	Н	-	L	-	М
CLO-3 :	Identify ways to present te	chnical / scientific	content structure a	and elements		3	85	80	L	Н	Н	М	М	-	Ĺ	Н	М	-	Н	-	L	-	М
CLO-4 :	Practice the different diss	eminating techniq	ues used in scientif	ic research findings		3	85	80	L	Н	Н	М	М	-	L	Н	М	-	Н	-	L	-	М
CLO-5 :	CLO-5: Identity intellectual property and its components, ways to protect, share intellectual information					3	85	80	L	Н	Н	М	М	-	L	Н	М	-	Н	-	L	-	М
CLO-6 :	CLO-6 : Analyze the different oral and written publishing techniques to disseminate research findings					3	85	80	L	Н	Н	М	М	-	L	Н	М	-	Н	-	L	-	М

		Oral Content Preparation	Presenting Methods	Written Content Preparation	Publishing Methods	Intellectual Property & Plagiarism			
Durat	ion (hour)	9	9	9	9	9			
	9101	Oral Presentation Structure: Manuscript,	Describe Audience; knowledge, Experience,	Writing Preface, Prelude, Prologue, foreword,	Typosotting: LaTox Word XML atc	Public License, Creative Commons, Share-alike,			
C 1	3L0-1	Impromptu, Memory, Extempore	Needs, Goals	Introduction, Abstract,	Typeselling. Latex, Wold, XINE elc.,	Reciprocal License,			
0-1	SI 0-2	context, need, agenda ,task, and object of the	Plan, Prepare, Practice, Present	Writing Dedication, Acknowledgement, Forward,	Indexing: ISI, SCI, SCIE, SCOPUS, SCIMAGO,	Convleft Patentleft Open patent Public Domain			
	010 1	presentation document	Creating a Positive First Impression,	Background	ESCI, WoS,	Copylen, I alenden, Open palent, I ublic Domain			
S	SLO-1	Practice-1: Create Structure of a Presentation	Practice-4: Building rapport with Audience	Practice-7: Writing Preface, Prelude, Prologue,	Practice-12: LaTex Editor, Word Editor	Practice-13: GNU-GPL, Public License Creative			
2-3	SLO-2		Tractice-4. Duilding rapport with Addience	foreword, Introduction, Abstract		Commons License, Unlicense			
	9101	Gather data, evidence to present, visual-auditory	Increasing Credibility, Presenting Complex	Literature Review: Narrative, Systematic,	Disseminating Research Findings: Public Domain,	Intellectual Property Rights, Copyrights, Patents,			
C 4	3L0-1	balance, engagement techniques	Material, Communicating with Impact	Argumentative, Integrative, Theoretical	Open Information, Wikipedia	Trademarks, and Trade secrets			
3-4	SLO-2	Introduction body closure question answer	Motivating Others, Responding to Pressure	Writing Problem Statement, Limitations, Method	Media, Press Release, Flyers, Brochure, Research	Industrial design rights, Plant variety rights, trade			
		introduction, body, closure, question-answer	Situations, Inspiring People	Adapted, Tools & Technology used	Summary, Posters, Websites	dress, geographical indications			
S	SLO-1	Practice-2: Create a structured oral presentation	Practice-5: Communicating with Greater Impact,	Practice 8: Writing Literature Poview	Practice-11: Study of Various Open Publishing	Practice 14: IPP Law Private Domain			
5-6	SLO-2	module	Rehersals and Retrials	Fractice-o. Writing Elterature Review	Methods	Fractice-14. IF IC Law, Frivate Domain			
	CI O 1	Tools: Presentation Slides, Whiteboard Animators,	Delivery Styles: Visual, Freeform, LessigInstructor,	Main Body: Analysis, Design, Development Steps,	Patents, Journals, Conferences, Reports, RFCs	Infringements: Copylefts, Copyrights, Patentlefts,			
S 7	3L0-1	Immersive Technologies	Coach, Storytelling, Connector	Implementation Steps, Evaluations	etc.,	Patentrights,			
5-1	902	Handouts, Visual Aids, Demonstrative Aids, Persuasive, Interactive, Decision Making,		Referencing: Documentary, Parenthetical,	Journal Index, Impact Easter, Quality Standarda	Plagiarism: Paraphrasing, Verbatim, Mosaic,			
	3LU-2	Thought Provoking Questions	Educational, Takahasi Arousing	Numbered, Vancouver, IEEE, Harvard etc.,	Journal muex, impact Factor, Quality Standards	Global, Self, Accidental etc.,			
S	S SLO-1	Practice-3: Demonstrating a multi technology oral	Practice-6: Presenting same content using different	Practice 0: Writing Main Padu	Practice-12:Study of h-index, i10-index,	Practice-15: Plagiarism checking and correcting			
8-9 SLO-2	presentation	delivery styles	Flacuce-9. Whiling Main Body	g-index, r-index, π - index	techniques				

Resources 3. Joseph Mugah, "Essentials of Scientific Writing: How to Write Effective Titles and Abstracts for Research Papers and Proposals", Authorhouse, 2016 5. Robert P. Merges, Peter S. Menell, Mark A. Lemley, "Intellectual Propertyin New Technological Age", 2016	Learning	 Dale Carnegie, "Develop Self-Confidence, Improve Public Speaking", Amazing Reads, 2018 Dale Carnegie, "The Art of Public Speaking", Amazing Reads, 2018 Joseph Mugah, "Essentials of Scientific Writing: How to Write Effective Titles and Abstracts for Research Papers and	 Rajesh Singh, Sanjeev Kumar Sinha, Samir Kumar, "Unfolding Intellectual Property Rights : A Practical Patent Guide for
	Resources	Proposals", Authorhouse, 2016	Researchers, Academicians and start-ups", Notion Press, 2019 Robert P. Merges, Peter S. Menell, Mark A. Lemley, "Intellectual Propertyin New Technological Age", 2016

Learning Assessment	Learning Assessment											
	Ploom's			Continuous Learning Ass	essment (60% weightage)			Einal Examination	(40%) woightage)			
DIOUITIS		CLA –	1 (20%)	CLA –	2 (25%)	CLA –	3 (15%)					
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice			
Level 1	Remember	20%	20%	150/	150/	159/	159/	150/	150/			
Level	Understand	20%	20%	15%	15%	15%	15%	10%	10%			

Level 2	Apply Analyze	- 20%	20%	20%	20%	20%	20%	20%	20%		
	Evaluate	10%	10%	150/	150/	15%	15%	150/	150/		
Lever 5	Create	10%	10%	1576	1576	1576	1576	1370	1370		
	Total	Total 100 %		10	0 %	10	0 %	100 %			

Course Designers									
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts							
1. Dr. Sainarayanan Gopalakrishnan, HCL Technologies, sai.jgk@gmail.com	1. Dr. Venkat Adhikari, Technology Licensing Manager, IISC, venkatadhikari@iisc.ac.in	1. Dr. Rajeev Sukumaran SRMIST							
2. Dr. Sricharan Srinivasan, Wipro Technologies, sricharanms@gmail.com	2. Mr.Ateet Palmurkar, Senior Manager IP Licensing, IITM, ipmarketing@iitm.ac.in	2. Dr. V. Nithyananthan SRMIST							

Course Code	20MES501.1	Course		RESEARCH	METHODS IN ME	CHANICAL SCIENCE	S	C	ourse	s				Skill	Enhar	nceme	nt Cou	Irse			-	L	Т	Ρ	С
oourse ooue	2011200010	Name					<u> </u>	Ca	ategory	/ 0				Onin	Linia			100				2	0	2	3
Pre-requisite Courses	Nil			Co-requisite Courses	Nil			Pro	gressi ourse:	s Nil															
Course Offering	Department	Mechar	nical Engineering		[Data Book / Codes/Sta	ndards	Nil		·															
Course Learning	Rationale (CLR):	The pur	pose of learning t	this course is to:				L	earnin	g					Pro	ogram	Learni	ing Ou	tcome	s (PLC	D)				
CLR-1: form	ulate the research pro	oblem						1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2: expl	ain carrying out a liter	rature search, if	ts review, develop	bing theoretical and c	onceptual framev	vorks and writing a rev	ew																		
CLR-3: expl	explain the details of sampling designs, measurement and scaling techniques and also different methods of data collections.						ctions.	(moc	(%)	(%)	n									eo		ant			
CLR-4: devi	se and design an exp	erimentation se	et-up					(Blc	ancy	Jent	edg			ing			бĽ	5	ning	oeter		Jeme			_
CLR-5: expl	ain the art of interpret	ation and the a	irt of writing resea	irch reports.				king	officie	ainn	Now	þ	bu	ISON	s		soni	nkin	Lear	duo	ning	ngaç		Sills	ning
CLR-6: give	an overview of the re	search method	lology and explair	1 the technique of def	fining a research	problem		f Thin	ed Pro	ed Att	any K	Thinki	i Solvi	al Rea	ch Skil	/ork	c Rea	ve Thi	ected	tural C	Reaso	nity Ei	s	thip St	g Lea
Course Learning	Outcomes (CLO):	At the e	end of this course,	, learners will be able	to:			Level o	Expect	Expect	Disciplir	Critical .	Problem	Analytic	Researc	Team V	Scientifi	Reflecti	Self-Dir	Multicul	Ethical I	Commu	ICT Ski	Leaders	Life Lon
CLO-1: form	ulate the research pro	oblem						1&2	100	95	L	М	М	L	Н	М	L	L	Н	М	Н	L	Н	L	Н
CLO-2: expl	ain carrying out a liter	ature search, it	ts review, develop	bing theoretical and c	onceptual framew	vorks and writing a revi	ew	1&2	100	95	L	М	М	L	Н	М	L	L	Н	М	Н	L	Н	L	Н
CLO-3: expl	ain the details of sam	pling designs, r	measurement and	scaling techniques a	and also different	methods of data collect	ctions.	1&2	100	95	L	М	М	L	Н	М	L	L	Н	М	Н	L	Н	L	Н
CLO-4: devi	se and design an exp	erimentation se	et-up					1&2	100	95	L	М	М	L	Н	М	L	L	Н	М	Н	L	Н	L	Н
CLO-5: expl	ain the art of interpret	ation and the a	irt of writing resea	arch reports.				1&2	100	95	L	М	М	L	Н	М	L	L	Н	М	Н	L	Н	L	Н
CLO-6: give	an overview of the re	search method	lology and explair	1 the technique of def	fining a research	problem		1&2	100	95	L	М	М	L	Н	М	L	L	Н	М	Н	L	Н	L	Η
	Posoarch P	reparation and	Planning	Posoa	rch Posource)	Data	Collection Analysis	and Infor	onco		9	viontific	Evpor	imonta	tion			٨	loadon	nic writ	ting or	d Pros	ontatio	n	

		Research Preparation and Planning	Research Resource)	Data Collection, Analysis, and Inference	Scientific Experimentation	Academic writing and Presentation
Durat	ion (hour)	9	9	9	9	9
S-1	SLO-1 SLO-2	Introduction - Meaning of research	Sources of information	Basic statistical measures and their uses	Principles of experimentation	Proposal submission for funding agencies, Elements of style.
S-2	SLO-1 SLO-2	Objectives of Research	Literature survey - World wide web - Online data bases	Measures of central tendency and dispersion, Skewness, and Kurtosis.	Basic experimental designs: Completely	Organization of proposals
S-3	SLO-1 SLO-2	Characteristics of a research problem	research problem Citation indices - Principles underlying impact factor – literature review Sampling		randomized design, randomized block design and Latin square design	Research report writing
S-4	SLO-1 SLO-2	Critical thinking	Case studies, review articles and Meta-analysis systematic sampling, and cluster sampling.			Communication skills
S-5	SLO-1 SLO-2	Techniques for generating research topics	record of research review Role of the librarian	Large sample tests and small sample tests: Test for sample mean, difference between two sample properties.	Factorial designs:22, 23, and 24	Tailoring the presentation to target audience – Oral presentation, poster presentation.
S-6	SLO-1 SLO-2	Topic selection and justification Ethical and Moral Issues in Research Applica		Student test, F-test, and $\chi 2$ test and their applications in research studies.		Submission of research articles for publication in refereed journals
S-7	SLO-1 SLO-2	O-1 SLO-2 Techniques involved in designing a questionnaire Plagiarism, tools to avoid plagiarism		Correlation and Regression Analysis – Time series analysis: Forecasting methods.	esigns: Explorative, designs: Explorative, descriptive, and diagnostic.	Thesis writing, research report writing

S-8	SLO-1 SLO-2	Methods of scientific enquiry	Intellectual Property Rights	Basic statistical distribution and their applications: Binomial, Poisson, Normal,	Factor analysis. Cluster analysis and	Elements of excellent presentation, Preparation and Visual delivery.
S-9	SLO-1 SLO-2	Development of a research proposal	Copy right laws – Patent rights	Exponential, Weibull and Geometric distributions.	discriminant analysis (basic ideas only)	Oral communication skills and oral defense

		Graves N, Varma V: Working for a doctorate Toutledge 1997.
	1. Ganesan R, Research Methodology for Engineers, MJP Publishers, Chennai. 2011.	7. Graziano, A., M., and Raulin, M.,L.: Research Methods – A Process of Inquiry, Sixth Edition, Pearson, 2007.
	2. Walpole R.A., Myers R.H., Myers S.L. and Ye, King: Probability & Statistics for Engineers and	8. Leedy., P., D.: Practical Research – Planning and Design, Eighth Edition, Pearson., 2005.
Learning	Scientists, Pearson Prentice Hall, Pearson Education, Inc. 2007.	9. Kothari C.K., Research Methodology- Methods and Techniques (New Age International, New Delhi), 2004.
Resources	3. Anderson B.H., Dursaton, and Poole M.: Thesis and assignment writing, Wiley Eastern 1997.	
	4. Bijorn Gustavii: How to write and illustrate scientific papers? Cambridge University Press.	
	5. Bordens K.S. and Abbott, B.b.: Research Design and Methods, Mc Graw Hill, 2008.	

			weightage)		Final Examination							
	Bloom's CLA-1 Level of Thinking (20%)				.A-2 5%)	CLA-3 (15%)	(40% weightage)					
		Theory	Practice	Theory	Practice		Theory	Practice				
Level 1	Remember Understand	20%	20%	20%	20%	20%	20%	20%				
Level 2	Apply Analyze	- 20%	20%	20%	20%	20%	20%	20%				
Level 3	Evaluate Create	10%	10%	10%	10%	20%	10%	10%				
	Total	10	0 %	10	0 %	100 %	100 %					

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
		Mr. KR. Arun prasad, SRMIST

4. Open Elective Courses (O)

5. Project Work, Internship in Industry / Higher Technical Institutions (P)

Course Code	20MEP601L	Course Name		INTERNSHIP				Cours atego	e ry	Ρ	Internship In Industry / Higher Technical Institutions						ions			L 0	T 0	P 8	C 4		
Pre-requisite Courses Nil Co-requisite Courses Nil								Pr (ogres: Course	sive es															
Course Offer	Course Offering Department Mechanical Data Book / Codes/Standards							Nil																	
Course Learning Rationale (CLR): The purpose of learning this course is to:									Learni	ing	Program Learning Outcomes (PLO)														
CLR-1: Pr	ovide an exposure to	o an industrial	l environment o	r research labora	tory / institutio	n		1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 : Ac	quire practical knowl	ledge of theo	retical concepts					5				ino	ing		s									ills	ĺ
CLR-3 : Understand the organization structure, functions and protocols							Thinkin	d (%)	d ent (%)	inary	edge Think	n Solv	cal inp	ch Skill	Vork	ine ine	b e	rected	ltural tence	ing	unity ment	ills	ship Sk	å a	
Course Learning Outcomes (CLO): At the end of this course, learners will be able to:						Level of	(<u>Bloom)</u> Expecte	Expecte Attainme	Discipl	Knowld Critical	Probler	Analyti Reason	Researc	Team V	Scientif Reason	Reflect	Self-Di Learnir	Multicu Compe	Ethical Reason	Comm	ICT Sk	Leader	Life Lo		
CLO-1 : Appreciate the functioning of an organization							1	70	65	ŀ	I H	Н	Н	М	Н	Н	Ĥ	М	Н	М	М	М	L	М	
CLO-2 : Ap	oply the theoretical co	oncepts to so	lve engineering	problems				2	80	75	ŀ	I H	Н	Н	Н	Н	Н	Н	Н	М	Н	М	Н	Н	Н
CLO-3 : Take up different roles in a career with confidence							3	65	60	ŀ	I M	L	L	М	М	М	M	L	L	Ĺ	L	L	М	М	

1. It is mandatory for every student to undergo this course.

2. Every student is expected to spend a minimum of 4 to 6 weeks in an Industry/ Company/ Organization, during the summer vacation between II and III semester

3. The type of industry must be NOT below the Medium Scale category in his / her domain of the degree programme.

4. The student must submit the "Training Completion Certificate" issued by the industry / company / Organisation as well as a technical report not exceeding 15 pages, within the stipulated time to be eligible for making a presentation before the committee constituted by the department.

5. The committee will then assess the student based on the report submitted and the presentation made.

6. Marks will be awarded out of maximum 100.

[7. Appropriate grades will be assigned as per the regulations.

8. Only if a student gets a minimum of pass grade, appropriate credit will be transferred towards the degree requirements, as per the regulations.

9. It is solely the responsibility of the individual student to fulfill the above conditions to earn the credits.

10. The attendance for this course, for the purpose of awarding attendance grade, will be considered 100%, if the credits are transferred, after satisfying the above (1) to (8) norms; else if the credits are not transferred or transferable, the attendance will be considered as ZERO.

11. The committee must recommend redoing the course, if it collectively concludes, based on the assessment made from the report and presentations submitted by the student, that either the level of training received or the skill and / or knowledge gained is NOT satisfactory.

Assessment for Semester Internship										
	Final Evaluation (100% weightage)									
	Report along with completion certificate from company	Viva-Voce								
Semester Internship	50 %	50 %								

Course Code	20MEP602I	Course Name	•	М	INOR PROJECT	C Ca	ourse tegor	/	Ρ				Рі	oject	t Wor	k					L 0	T 0	P 8	C 4
Pre-requ Course	isite es Nil		·	Co-requisite Courses	Nil		Pro C	gress ourse	sive s															
Course Off	fering Department	Mec	hanical		Data Book / Codes/Standards		Nil																	
Course Learning Rationale (CLR): The purpose of learning this course is to: Learning CLR1: Concentualize a povel idea / technique 1 2 3 4 5 6										ram L	earn	ing O	utcor	mes (I	PLO)									
CLR-1 :	Conceptualize	a novel i	dea / technie	que			1	2	З	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 : CLR-3 : CLR-4 :	Think in terms Understand th Prepare a tech	of socia e manag inical rep	l or commer ement techn ort and pres	cialapplicatio iques of impl entin a profes	ns ementing a project ssional manner		Thinking (Bloom)	d Proficiency (%)	d Attainment (%)	inary Knowledge	Thinking	n Solving	cal Reasoning	ch Skills	Vork	ic Reasoning	ive Thinking	rected Learning	lltural Competence	Reasoning	unity Engagement	ills	ship Skills	ng Learning
Course Lea	arning Outcomes (CLO): At th	e end of this cour	rse, learners will be	able to:		Level of	Expecte	Expecte	Discipl	Critical	Probler	Analyti	Researc	Team V	Scientif	Reflecti	Self-Di	Multicu	Ethical	Comm	ICT Sk	Leaders	Life Lo
CLO-1 :	Identify and so	olve simp	le engineeri	ng / biologica	l problems		1	70	65	Н	Н	Н	Н	М	Н	Н	Н	М	Н	М	М	М	L	М
CLO-2 :	Assess the fea	asibility o	f project cor	nmercializatio	on		2	80	75	Н	Н	Н	Н	Н	Н	Н	Η	Η	М	Н	М	Н	Н	Н
CLO-3 :	Manage the in	plement	ation of a pro	oject			3	65	60	Н	М	L	L	М	М	М	М	L	L	L	L	L	М	М
CLO-4 :	Document a p	roject rep	ort				3	75	70	Н	Н	Н	Н	L	М	Н	М	Н	М	М	М	Н	М	Н

- An in-house project to be taken up by the individual student and complete the minor project before the end of III semester
- The project can be a development of an experimental kit/ method, an innovative concept or idea or methodology or algorithm / technique, a 3D model, simulation, prototype product, blueprint for a larger project or any other similar developmental work that the respective department approved by the department, are permitted.
- The student must be attached to a faculty supervisor / mentor
- A comprehensive report is to be submitted.
- A presentation is to be made on the work done by the student to committee of reviewers

Learning Assessment weightage

	Continuous Lear (70% we	ning Assessment eightage)	Final Ev (30% w	valuation eightage)
	Review I	Review II	Report	Viva-Voce
Minor Project	20 %	50 %	15 %	15 %

Course Code	20MEP603L	Course Name	PROJE	CT WORK PHASE - I	Co Cat	ourse tegory	,	Ρ					Proje	ct Wo	rk					L 0	T 0	P 12	C 6
Pre-requ Cours	lisite Nil		Co-requisite Courses	Nil		Pro	gressi ourses	ive s															
Course Of	fering Department	Mechanical		Data Book / Codes/Standards		Nil																	
Course Le	earning Rationale (CLF	R): The purpose of le	earning this course is to:		Learning Program Learning Outcomes (PLC							(PLO))										
CLR-1 :	Provide studen particular pers	nts with the op onal or profes	portunity to ex ssional interest	plore a problem or issue of							11	12	13	14	15								
CLR-2 : CLR-3 :	Address the pr Prepare a techn	oblem or issu	e through focus	sed study and applied researd	ch	g (Bloom)	ency (%)	ment (%)		nowledge	gui	ug soning	0		soning	nking	Learning		ning			ills	rning
						f Thinking	ed Profici	ed Attain		linary K	l Think	in 2010 in Rea	ch Skill	Work	fic Reas	tive Thi	irected	ultural etence	l Reason	nunity ement	sills	rship Sk	ong Lea
Course Le	earning Outcomes (CL	O): At the end of this	s course, learners will be	able to:		Level o	Expect	Expect		Discip	Critica	Analyt	Resear	Team	Scienti	Reflec	Self-D	Multic	Ethica	Comr Eneae	ICT SI	Leade	Life L
CLO-1 :																					-		
CLO-2 :																							
CLO-3 :															1								

- The project work (Phase I) is the preparatory phase for the major project to be taken up during the final semester of the programme.
- Each student is expected to identify an engineering problem in his / her specialization of study.
- Each student must study in-depth the issues / causes & effects underlying the problem and define the objective of the subsequent work.
- A faculty supervisor / mentor will be assigned to each project.
- A report of the work done during Phase I must be submitted at the end of the semester, for evaluation.
- Assessment will be made as per the table below:

	Co	ntinuous Learnin (70% weigł	g Assessment ntage)	Fina (30%	l Evaluation 5 weightage)
	Review - 1	Review -2	Review - 3	Project Report	Viva-Voce
Project Work (Phase I)	15 %	25 %	30 %	15 %	15 %

Course Code	20MEP604L	Course Name		PROJE	CT WORK PHASE - II	c	Course ategor	y	Ρ			Р	rojec	t Wor	k					L 0	T 0	P 32	C 16
Pre-req Cours	uisite ses Nil			Co-requisite Courses	Nil		Pro C	gress ourse	sive es														
Course O	ffering Department	Mecha	nical		Data Book / Codes/St	andards	Nil																
Course L	earning Rationale (CL	R): The pu	rpose of learning	this course is to:			L	earni	ng			T	Prog	ram L	earn	ing O	utcor	nes (l	PLO)				
CLR-1 :	Provide stude particular per	nts with sonal or	the opport profession	tunity to ex	plore a problem or issued	ue of	1	2	3	1 2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Address the p	roblem o	or issue thr	ough focu	sed study and applied 1	esearch																	
	Demonstrate	the stude	ent's ability	to synthes	size and apply the know	wledge																	
CLR-3 :	and skills acq	uired in	his/her aca	ademic pro	gram to real-world issu	ues and																	
	problems																						
	Affirm studen	ts' abilit	y to think of	critically a	nd creatively, to solve	practical												e					
CLR-4 :	problems, to 1	nake rea	soned and	ethical de	cisions, and to commu	nicate	Ê	(%)	()	gge		50					gu	etenc		ment			
	effectively						(Blool	ncy (9	ent (%	owlo 2	о <i>ь</i> с	oning			guing	king	earni	oduic	gu	gage		ls	ing
CLR-5 :	Prepare a tech	inical rep	port and pr	resent in a	professional manner		iking	oficie	tainm	y Kn iabia	olvin	Reas	kills	k	keasc	Thin	ed L	:al Co	isoni	y En		Skil	Lean
							f Thir	ad Pr	ed At	1 Th	en S	lical	rch S	Wor	ific F	tive '	irect	ultu	l Re	nunit	kills	rship	ong
Course L	earning Outcomes (CI	O): At the	end of this course	e, learners will be	able to:		evel o	Expect	Expect	Discip	roble	Analy	lesea	leam	cient	keflec	elf-D	Multic	3thica	Comn	CTS	cade	ife L
CLO-1 :								ш	ш				H		5	H	S	4		Ŭ	н		
CLO-2 :																							
CLO-3 :																							

- The project work Phase II is to extend their academic experience into areas of personal interest, working with new ideas, issues, organizations, and individuals.
- The project shall be driven by realistic constraints like that related to economic, environmental, social, political, ethical, health & safety, manufacturability and sustainability.
- A report of the work done during Phase II must be submitted at the end of the semester, for evaluation.
- Assessment will be made as per the table below:

	Co	ntinuous Learnin (70% weigł	g Assessment ntage)	Fina (30%	l Evaluation 5 weightage)
	Review - 1	Review -2	Review - 3	Project Report	Viva-Voce
Project Work (Phase I)	15 %	25 %	30 %	15 %	15 %

NOTE:

1. The CLO must be filled by each department as per their programme objectives

2. Learning and Programme Learning Outcomes will vary for each project and must be filled for each project, documented and kept in the department for future reference.

6.Audit Courses (M)

7. Mandatory Courses (M)

Course Code		20PDM501T	Course Name		Career Advancement Course for Engineers-I	C Ca	ourse tegory	,	М					Mano	latory						L 1	T 0	P 1	C 0
Pre-requies Course	uisite ses	Nil			Co-requisite Courses		Pro	gress ourse	sive es	Nil														
Course O	ffering	Department	Caree	r Development C	Centre Data Book / Codes/Standar	s	Nil																	
Course Lo	earning	g Rationale (CL	R): The p	urpose of learnin	g this course is to:		Le	earni	ng					Prog	ram l	_earn	ing O	lutcoi	mes (PLO)				
CLR-1 :	Becon	ne an expert in c	ommunicatio	on and problem s	olving skills		1	2	3	Γ	1 2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 : CLR-3 : CLR-4 : CLR-5 : CLR-6 :	Recap Streng Identif Sharp Acquir	bitulate fundamen gthen writing skil fication of relation en logical and cr re the right know g Outcomes (CL	ntal mathem Is profession nships betwe ritical reason ledge, skill a - O): At the	atical concepts a ally and understa een words based ing through skillf nd aptitude to fa end of this cours	nd skills and commercial mathematical applications on their function, usage and characteristics ul conceptualization ce any competitive examination se, learners will be able to:		evel of Thinking (Bloom)	xpected Proficiency (%)	xpected Attainment (%)		ingineering Knowledge	esign & Development	nalysis, Design, Research	fodem Tool Usage	ociety & Culture	invironment & Sustaina bility	thics	ndividual & Team Work	communication	roject Mgt. & Finance	ife Long Learning	SO - 1	SO - 2	SO - 3
CLO-1 :	Acquir	re communicatio	n and proble	m solving skills			2	80	75		- F	1 -	Ĥ	-	-	-	-	H	H	-	H	-	-	-
CLO-2 :	Build a	a strong base in	the fundame	ntal mathematic	al concepts		2	75	70		- H	1 -	Н	-	-	-	-	Н	Н	-	Н	-	-	-
CLO-3 :	Acquir	re writing skill to	communicat	e with clarity			2	80	75		- H	1 -	Н	-	-	-	-	Н	Н	-	Н	-	-	-
CLO-4 :	Use a	pt vocabulary to	embellish la	nguage			3	75	70		- H	- 1	Н	-	-	-	-	Н	Н	-	Н	-	-	-
CLO-5 :	Gain a	appropriate skills	to succeed	in preliminary se	lection process for recruitment		3	85	80		- H	- 1	Н	-	-	-	-	Н	Н	-	Н	-	-	-
CLO-6 :	Enhar	nce aptitude skill	s though sys	tematic applicati	on of knowledge		2	85	80		- H	1 -	Н	-	-	-	-	Н	Н	-	Н	-	-	-

Durati	on (hour)	6	6	6		6	6
6.1	SLO-1	Types of numbers, Divisibility tests	Fractions and Decimals, Surds	Percentage - Introduction	on	Sentence Correction	Number and Alphabet Series
3-1	SLO-2	Solving Problems	Solving Problems	Solving Problems		Practice	Direction Test
6.2	SLO-1	LCM and GCD	Square roots, Cube roots, Remainder	Percentage Problems		Reading Comprehension	Blood Relations
5-2	SLO-2	Solving Problems	Solving Problems	Solving Problems		Practice	ArrangementsLinear, Circular
6.2	SLO-1	Unit digit, Number of zeroes, Factorial notation	Identities	Profit and Loss		Reading Comprehension	Ranking
3-3	SLO-2	Solving Problems	Solving Problems	Solving Problems		Practice	Practice
6.4	SLO-1	Verbal Reasoning-Vocabulary	Spotting Errors	Discount		Reading Comprehension	Critical Reasoning-Strengthening
3-4	SLO-2	Practice	Practice	Solving Problems		Practice	Practice
с <i>Б</i>	SLO-1	Verbal Reasoning-Vocabulary	Spotting Errors	Sentence Correction		Linear Equations	Critical Reasoning-Weakening
3-5	SLO-2	Practice	Practice	Practice		Solving Problems	Practice
	SLO-1	Verbal Reasoning-Vocabulary	Spotting Errors	Sentence Correction		Logical Reasoning-Intro	Critical Reasoning-Assumption
5-0	SLO-2	Practice	Practice	Practice		Coding and Decoding	Practice
Loorn	ina	1. Khattar D. "Quantitative Aptitude", Per	arson's Publications, Third Edition (2015).	on (2016)	5. Arihant. "IBPS F 6.Nishit Sinha. "Ve	PO - CWE Success Master", Arihant Publicat Inbal Ability for CAT", Pearson India, First Ed	ions(I) Pvt.Ltd – Meerut, First Edition (2018) ition (2018).

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7 Arabana Dan	"Dlooomontor"	Outard University Dress	(2010)

 Praveen R. V. "Quantitative Aptitude and Reasoning", EEE Publications, Third Edition (2016)
 Guha A. "Quantitative Aptitude", TATA McGraw Hill Publications, Sixth Edition (2017).
 P.A. Anand, "Quantitative Aptitude for Competitive Examination", WILEY Publications (2019) Learning Resources

Archana Ram, "Placementor", Oxford University Press, (2018)
 Bharadwaj A.P. " General English for Competitive Examination", Pearson Education, First Edition (2013)
 Thorpe S. "English for Competitive Examination", Pearson Education, Sixth Edition (2012).

Learning Assessment :

			Continuous Learning Assessme	nt (CLA) (60% weightage)		Final Exam (40% weig	ination htage)
	Bloom's Level of Thinking	CLA (30%	x-1 %)	C (3	LA-2 30%)	Fully Inte	ernal
		Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	40 %	-	30 %	-	30 %	-
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-
Level 3	Evaluate Create	20 %	-	30 %	-	30 %	-
	Total	100	%	1	00 %	100 %	6
Course Designers							
Experts from Industry		Internal Experts					
1. Mr. Ajay Zener, Caree	r Launcher, ajay.z@careerlauncher.com	1. Dr. P. Madhusoo	odhanan, Head CDC, SRMIST	2. Dr. M.	Snehalatha,, Assistant Professor, SRM	IST	
		3. Mr. J.Jayapragas	sh , Assistant Professor, SRMIST	4. Dr.A.C	lement, Assistant Professor, SRMIST		

Cou Co	rse de	20PDM502T	Course Name		Career Advancer	nent Course For Engine	ers - II	C Ca	ourse tegory	,	М					Manda	atory						L 1	T 0	P 1	C 0
Pre- Co	requisite ourses	• Nil		1	Co-requisite Courses	Nil			Pro	gressi ourse:	ive S	Nil														
Cours	e Offerin	ig Department	Career	Development	Centre	Data Book	/ Codes/Standards		Nil																	
Cours	e Learni	ng Rationale (CLI	R): The pu	rpose of learni	ng this course is to:				Le	earnin	g					Progr	ram L	.earni	ng O	utcon	nes (F	PLO)				
CLR-1	: Reca	apitulate fundamer	ntal mathema	tical concepts	and building the res	ume			1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2	: Beco	ome an expert in c	ommunicatio	n and problem	solving skills										ſ			ty								
CLR-3	: Shai	pen interpretation	al skills throu	gh skillful conc	eptualization,				Ê	(%	(%		, ,	+	earch			abili		¥						
CLR-4	: Shai	pen analytical rea	soning skills	and profession	al skills	rovers the behavior			Bloc	lcy (ent (200	800 B	men	Rese	e		stair		Wo		ance	_			
CLR-J	· Aca	ire the right know	willi iueaiisii Iodao skill ar	s, practical and antitude to f	are any competitive	overni the benavior			ing	icier	m		/sis	elop	gn,	Jsac	ure	s Su		eam	E	Ë	nin			
	. ////		lougo, skiir un			examination			hink	Prot	Atta	20	Anal	Dev	Des	00	Cult	ent 8		& T	catio	gt. 8	Lea			
Cours	e Learni	ng Outcomes (CL	. 0): At the e	end of this cou	rse, learners will be	able to:			evel of T	Expected	Expected		Problem /	Jesign &	Analysis,	Modem T	Society &	Environm	Ethics	ndividual	Communi	Project M	-ife Long	-SO - 1	-SO - 2	SO-3
CLO-1	: Build	d a strong base in t	the fundamer	ntal mathemati	cal concepts and res	sume			2	80	75	-	Ĥ	-	M	-	-	-	-	Ħ	H	-	H	-	-	-
CLO-2	: Acqu	uire communication	n and probler	n solving skills					2	75	70	-	Н	-	М	-	-	-	-	Н	Н	-	Н	-	-	-
CLO-3	: Gair	n appropriate skills	to succeed in	n preliminary s	election process for	recruitment			2	80	75	-	Н	-	М	-	-	-	-	Н	Н	-	Н	-	-	-
CLO-4	: Acqu	uire interpretationa	l skills and pr	ofessional skil	ls				3	75	70	-	Н	-	М	-	-	-	-	Н	Н	-	Н	-	-	-
CLO-5	: Deve	elop professionalis	m with idealis	stic, practical a	nd moral values				3	85	80	-	H	-	M	-	-	-	-	H	H	-	H	-	-	-
CLO-6	: Enna	ance iexical skills t	nrougn syste	matic applicati	on of concepts and	careful analysis of style,	syntax, semantics and	a iogic	Z	80	80	-	Н	-	М	-	-	-	-	Н	н	-	н	-	-	-
Durati	on (hour)		6			6		6						6								6	í			
	SLO-1	Ratio and Propo	rtion-Intro		Sets-Rules		Group Discussion-3				Ĺ	Data Suff	iciency	-Intro					Perso	nal Ini	tervie	W	-			
5-1	SLO-2	Solving Problem	s		Solving Problems		Practice				5	Solving P	roblerr	s					Practi	се						
6.2	SLO-1	Ratio and Propo	rtion		Sets-Identities, Ver	nn Diagram	Group Discussion-4				Ĺ	Data Suff	iciency						Perso	nal Ini	tervie	W				
3-2	SLO-2	Solving Problem	s		Solving Problems		Practice				9	Solving F	roblerr	s					Practi	се						

6 4	SLO-1	Ratio and Proportion-Intro	Sets-Rules	Group Discussion-3	Data Sufficiency-Intro	Personal Interview
3-1	SLO-2	Solving Problems	Solving Problems	Practice	Solving Problems	Practice
6.2	SLO-1	Ratio and Proportion	Sets-Identities, Venn Diagram	Group Discussion-4	Data Sufficiency	Personal Interview
3-2	SLO-2	Solving Problems	Solving Problems	Practice	Solving Problems	Practice
6.2	SLO-1	Mixture and Solutions-Intro	Functions-Intro	Group Discussion-5	Analytical Reasoning-Intro	Mock Interview
3-3	SLO-2	Solving Problems	Solving Problems	Practice	Solving Problems	Mock Interview
84	SLO-1	Mixture and Solutions	Group Discussion- Do's and Don'ts	Data Interpretation-Intro	Analytical Reasoning	Mock Interview
3-4	SLO-2	Solving Problems	Practice	Solving Problems	Solving Problems	Mock Interview
6 E	SLO-1	Profile Building	Group Discussion-1	Data Interpretation-Tables, Pie Chart	Personal Interview-Do's and Don'ts	Mock Interview
3-3	SLO-2	Profile Building	Practice	Solving Problems	Practice	Mock Interview
5.6	SLO-1	Resume Building	Group Discussion-2	Data Interpretation-Lines, Bar Graphs	Personal Interview	Quantitative Reasoning Revision
3-0	SLO-2	Resume Building	Practice	Solving Problems	Practice	Solving Problems
Learni Resou	ng rces	 Khattar D. "Quantitative Aptitude", Pea 2.Guha A. "Quantitative Aptitude", TATA 3.Butterfield J. "Soft Skills for Everyone", 	arson's Publications, Third Edition (2015). McGraw Hill Publications, Sixth Edition (201 Cengage Learning India Private Ltd, First Ed	4. Bono E.D. "Six 7). 5.P.A. Anand, "Qu dition, (2011). 6. Archana Ram, "	Thinking Hats is a book", Little Brown and C antitative Aptitude for Competitive Examinati Placementor", Oxford University Press, (201	Company, First Edition (1981) on", WILEY Publications (2019) 8)

Learning Assessment :

			Final Examination (40% weightage)						
	Bloom's Level of Thinking	CL (30	A-1 %)	CL (3	Fully Internal				
		Theory	Practice	Theory	Practice	Theory	Practice		
Lovel 1	Remember	40.9/			20.0/	20.9/			
Level 1	Understand	40 %	-	-	30 %	30 %	-		
Lovel 2	Apply	40 %			10 %	40 %			
Level 2	Analyze	40 /8	-	-	40 /8	40 /0	-		
Level 3	Evaluate	20.9/			20.9/	20.9/			
	Create	20 /8	-	-	30 %	30 %	-		
	Total	100) %	10	100 %				

Course Designers							
Experts from Industry	nternal Experts						
1. Mr. Ajay Zener, Career Launcher, ajay.z@careerlauncher.com	1. Dr. P. Madhusoodhanan, Head CDC, SRMIST	2. Dr. M. Snehalatha,, Assistant Professor, SRMIST					
	3. Mr.P.Priyanand , Assistant Professor, SRMIST	4. Mrs.Kaviatha Srisarann, Assistant Professor, SRMIST					

Cou Co	rse de	20PDM601T Course Name Career Advancement Course For Engineers - III				C C	Course ategor	y	М					N	landa	atory						L 1	T 0	<u>Р</u> 1	С 0	
Pre-requisite Courses Nil Co-requisite Courses Nil						Pro C	gress ourse	sive s	Nil																	
Cours	e Offering	g Department	Career	Development	Centre Data Book	/ Codes/Standards		Nil																		
Cours	Course Learning Rationale (CLR): The purpose of learning this course is to:																									
CLR-1	: acqui	ire knowledae on	planning prei	Daring and des	signing a learning program			1	2	3	 1 [1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2	: prepa	are effective learn	ing resources	for active pra	ctice sessions			· ·	-	Ŭ	1		-		·	•	•		-						<u></u>	
CLR-3	: facilit	ate active learning	g with new me	ethodologies a	and approaches			Ê	(%	(%		æ		-	arch			abilit		×						
CLR-4	: create	e balanced asses	sment tools	hmont				Bloo	icy (ent (ledg		meni	Rese	Ð		stain		Wor		ance	_			
CLR-5	: define	e standards goals	s and objectiv	es				cing (ficier	ainme		Now	ysis	elop	igi,	Usaç	ture	& Su		eam	Б	Ë	minç			
•=•	. .	o otarradi do, godit	e and expected					Think	I Pro	d Atta		ing k	Anal	Dev	Des	00	Cul	Tent		I & T	icatio	Agt. 8	l Lea			
Cours	e Learnin	ig Outcomes (CL	_O): At the e	end of this cou	rse, learners will be able to:			Level of .	Expected	Expected		Engineer	Problem	Design &	Analysis,	Modern	Society 8	Environn	Ethics	Individua	Commun	Project N	Life Long	PSO - 1	PSO - 2	PSO - 3
CLO-1	: Build	a strong foundati	ion in designin	ig a lesson pla	an			2	80	75		-	Н	Н	Н	М	-	-	-	Н	Н	-	Н	-	-	-
CLO-2	: Acqui	ire knowledge of i	learning resou	irces for effect	tive delivery			2	75	70		-	Н	Н	Н	M	-	-	-	Н	Н	-	Н	-	-	-
CLO-3	: Snarp : Deve	lop practical asse	s with the fates	st methodolog to ensure valid	dity and flexibility			2	75	70	-	-	н Н	н Н	н Н	M	-	-	-	н Н	н Н	-	H	-	-	-
CLO-5	: Enha	nce effective pres	sentation and	teaching meth	nods			3	85	80		-	H	H	H	M	-	-	-	H	H	-	Н	-	-	-
CLO-6	CLO-6: Reinforce Bloom's Taxonomy of educational goals and objectives 2 85 80 - H H - - H - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - </th																									
Durati	on (hour)		6		6 6						6						6									
6.4	SLO-1	Lower and Highe	er order learni	ng	Definition and purpose of assessment	Peer Teaching practice					Live Teaching Sessions						L	Live Teaching Sessions								
3-1	SLO-2	Outcomes from I	lower order lea	arning	Practice	Discussion and feedback					Live Teaching Sessions						L	Live Teaching Sessions								
S-2	SLO-1	Planning and pre programme and	eparing a leari session	ning	istinction between formative and unmative assessment Peer Teaching practice Live Teaching Sessions							L	Live Teaching Sessions													
0-2	SLO-2	Practice			Examples and discussions	Discussion and feedback				Live Teaching Sessions						L	Live Teaching Sessions									
6.2	SLO-1	Teacher and Stu	udent-Centere	d class room	Instructional materials	Cooperative learning procedure					Live Teaching Sessions						L	Live Teaching Sessions								
0-0	SLO-2	Discussion		Examples and discussion Different models of cooperati				ative le	arning	,	Live Teaching Sessions Live Teaching Sessions								S							
S-1	SLO-1	D-1 Roles of teachers and students Instructional design Limitations of cooperative					tive I	learnin	g		Live Te	achin	g Ses	ssions	6			L	_ive T	ve Teaching Sessions						
0-4	SLO-2	Discussion			Practice	Discussion				Live Teaching Sessions						Live Teaching Sessions										
S-5	SLO-1	Discussion Strat	tegies		Presentation of lesson plans Structure of a lecture						Live Teaching Sessions					Live Teaching Sessions										
3-3	SLO-2	Practice			Discussion	Practice Live Teaching Sessions						Live Teaching Sessions														
5-6	SLO-1	Bloom's Taxono	my of education	onal goal	Group Work in learning	Live Teaching Sessions					Live Teaching Sessions						L	Live Teaching Sessions								
5-0	SLO-2	Practice			Discussion	Live Teaching Sessions					Live Te	achin	g Ses	ssions	8			L	ive T	eachii	ng Se	ssion	s			
Learni Resou	1. Barker I. "Cambridge International Diploma for Teachers and Trainers", Cambridge University Press, 2006. 3. Vicki Phillips and Lynn Olson, "Ensuring Effective Instruction: How do I improve teaching using multiple measures?"Bill & Melinda Gates Foundation, 2013 Resources 2. Whitehead Jack, Creating a Living Educational Theory from Questions of the kind: How do I improve my Practice? Cambridge Journal of Education, 2006 3. Vicki Phillips and Lynn Olson, "Ensuring Effective Instruction: How do I improve teaching using multiple measures?"Bill & Melinda Gates Foundation, 2013							ple ed ,																		

Learning Assessment :

			Final Examination (50% weightage)						
	Bloom's Level of Thinking	CL. (30	A-1 %)	CL (20	Fully Internal				
		Theory	Practice	Theory	Practice	Theory	Practice		
Level 1	Remember	_	40 %	_	30 %	_	30 %		
LOVEL	Understand		40 /0		00 /0		00 /0		
Loval 2	Apply		40.9/		40.9/		40 %		
Level Z	Analyze	-	40 %	-	40 %	-			
Level 3	Evaluate		20.9/		20.9/		20.0/		
	Create	-	20 %	-	30 %	-	30 %		
	Total	100) %	10	0 %	100 %			

Note: CLA-1 (Lesson Plan Design)

CLA-2 (Assessment Tools)

CLA-3 (Teaching Practice)

Course Designers							
Experts from Industry	Internal Experts						
1. Mr Ajay Zener, Career Launcher, ajay.z@careerlauncher.com	1. Dr. P. Madhusoodhanan, Head CDC, SRMIST	2. Dr. M. Snehalatha,, Assistant Professor, SRMIST					
	3. Mr J.Jayapragash , Assistant Professor, SRMIST	4. Dr.A.Clement, Assistant Professor, SRMIST					