ACADEMIC CURRICULA

UNDERGRADUATE DEGREE PROGRAMMES

Bachelor of Technology

(B.Tech Biomedical Engineering)

(Choice Based Flexible Credit System)

Academic Year 2018-2019



SRM INSTITUTE OF SCIENCE AND TECHNOLOGY

(Deemed to be University u/s 3 of UGC Act, 1956) Kattankulathur, Kancheepuram District 603203, Tamil Nadu, India



B.Tech in Biomedical Engineering

(a). Mission of the Department

Mission Stmt - 1	Build on a strong foundation in Basic science and Engineering and educate the students in diverse filed of Biomedical Engineering
Mission Stmt - 2	Work towards state of art Biomedical Engineering research and development through an interdisciplinary curriculum.
Mission Stmt - 3	Apply knowledge about design in development of enabling technologies for improvement of human health

(b) Program Educational Objectives (PEO)

PEO - 1	Develop real world biomedical devices and prototype models and test with multi-disciplinary approach.
PEO - 2	Design technologically enabled equipments that open up new areas of medical research.
PEO - 3	To impose innovative ideas for commercialization of developed products.
PEO - 4	Lead and work in a team with varied expertise and meet the changing needs of the profession through life long learning.
PEO - 5	To promote entrepreneurship skills in creating jobs in health care domain.

(c) Mission of the Department to Program Educational Objectives (PEO) Mapping

	Mission Stmt - 1	Mission Stmt - 2	Mission Stmt - 3
PEO - 1	Н	М	Н
PEO - 2	Н	Н	М
PEO - 3	Н	М	Н
PEO - 4	Н	Н	М
PEO - 5	Н	Н	М

H – High Correlation, M – Medium Correlation, L – Low Correlation

(d) Mapping Program Educational Objectives (PEO) to Program Learning Outcomes (PLO)

		Program Learning Outcomes (PLO)																
		Graduate Attributes (GA)												Program Specific Outcom (PSO)				
	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Leaming	PSO - 1	PSO - 2	PSO - 3			
PEO - 1	Н	Н	Н	Н	М	Н	Н	М	Н	М	Н	М	Н	Н	Н			
PEO - 2	H	М	H	H	H	М	М	М	H	М	H	H	H	Н	H			
PEO - 3	Н	Н	Н	Н	М	Н	Н	Н	М	Н	Н	М	М	Н	Н			
PEO - 4	М	H	H	H	М	М	М	М	H	H	H	М	Н	М	H			
PEO - 5	Н	М	М	H	M	М	М	М	М	М	М	H	Н	М	М			

H - High Correlation, M - Medium Correlation, L - Low Correlation, PSO - Program Specific Outcomes (PSO)

PSO – Program Specific Outcomes (PSO)

PSO - 1	Ability to apply engineering design to offer health care solutions with consideration of safety, welfare, social, cultural and environmental factors
PSO - 2	Ability to model and analyze biological systems with ethical and professional responsibilities in Engineering situations.
PSO - 3	Ability to initiate cross disciplinary and industry collaborative research.

(e) Program Structure for B.Tech in Biomedical Engineering

								Desite Optimum Optimum (D)				
i	ncluding Management Courses (H)							Basic Science Courses (B)				
Course	Course		Ho	urs/ W	/eek	С	Course	Course		١	lours Veek	/ C
Code	Title		L	T	P		Code	Title		L	Т	Ρ
18LEH101J	English		2	0	2	3	18PYB101J	Physics: Electromagnetic Theory, Quantum		3	1	2 5
18LEH102J	Chinese							Mechanics, Waves and Optics				
18LEH103J	French						18CYB101J	Chemistry		3	1	2 5
18LEH104J	German		2	0	2	3	18MAB101T	Calculus and Linear Algebra		3	1	0 4
18LEH105J	Japanese						18MAB102T Advanced Calculus and Complex Analysis			3	1	0 4
18LEH106J	Korean						18MAB201T	Transforms and Boundary Value Problems		3	1	0 4
18PDH101L	General Aptitude		0	0	2	1	18MAB202T	Numerical methods for Engineers		3	1	0 4
18PDH102T	Management Principles for Engineers		2	0	0	2	18MAB301T	Probability and Statistics		3	1	0 4
18PDH103J	Social Engineering		1	0	2	2	18BTB102T	Biology: Human Anatomy and Physiology		2	0	0 2
18PDH201L	Employability Skills & Practices		0	0	2	1		Total Learning Cre	dits			32
	Total Learning Cre	edits				12						
	Engineering Science Courses (S)							Professional Core Courses (C)				
Course	Course	Ho	ours	Wee	k		Course	Course Title		lou	s/	С
Code	Title	L			P	C	Code		١	Nee	k	-
18MES101L	Engineering Graphics and Design	1	()	4	3			L	Т	Ρ	
IOLLOIDID	Engineering	5		'	2	0	18BTC205J	Pathology & Microbiology	3	0	2	4
18MES103L	Civil and Mechanical Engineering	1	()	4	3	18BMC201J	Biomedical Sensors	3	0	2	4
	Workshop	_				_	18BMC202T	Biomedical Signals and Systems	3	0	0	3
18CSS101J	Programming for Problem Solving	3	()	4	5	18BMC203J	Electric and Electronic Circuits	3	0	2	4
18PYS202T	Medical Physics	3	()	0	3	18BMC204T	Principles of Medical Imaging	3	0	0	3
	I otal Learning Credits	5				19	18BMC205J	Linear and digital Integrated Circuit	3	0	2	4
	List of Open Elective Courses (O)						18BMC206J Biomaterials-Tissue interaction		3	0	2	4
	Any 4 Courses						18BMC301J Medical Instrumentation		3	0	2	4
Course	Course	Hours	/ W	eek	С		18BMC302T	Biomechanics	3	0	0	3
Code	Title	L	Т	Ρ			18BMC303J	Biomedical Signal Processing	3	0	2	4
18BMO121T	Fundamentals of Biomedical Engineering	3	0	0	3		18BMC304J	Microcontrollers and its application in medicine	3	0	2	4
18BMO122T	Health Information Systems	3	0	0	3		18BMC305T	Biocontrol Systems	3	0	0	3
18BMO123T	Basics of Medical Imaging	3	0	0	3		18BMC306J	Medical Image Processing	3	0	2	4
18BMO124T	Rehabilitation Engineering	3	0	0	3		18BMC401T	Biomedical Equipments for clinical applications	3	0	0	3
18BMO125T	Quality control for biomedical devices	3	0	0	3		18BMC350T	Comprehension	0	1	0	1
18BMO126T	Biomechanics of Human Movement	3	0	0	3			Total Learning Credits	6			52
								Mandatory Courses (M)				
	Project Work, Seminar, Internship Ir	ı										
	Industry / Higher Technical Institutions	s (P)					Course	Course	Hours	s/ W	eek	С
0	<u> </u>	1		\A/= =			Code	Title	L	Т	Ρ	
Course	Course	HO	urs/	vveek	C		18PDM101L	Professional Skills & Practices	0	0	2	0
Code	Title	L	T	P			18PDM201L	Competencies in Social Skills	0	0	2	0
18BMP101L	MOOC / Industrial Training / Seminar – 1	0	0	2	1		18PDM202L	Critical & Creative Thinking Skills	0	0	2	0
18BMP102L	MOOC / Industrial Training / Seminar – 2	0	0	2	1		18PDM301L	Analytical & Logical Thinking Skills	0	0	2	0
18BMP103L	Project (Phase-I) / Internship (4-6 weeks)	0	0	6	3		18LEM101T	Constitution of India	1	0	0	0
18BMP104L	Project (Phase-II) / Semester Internship	0	0	20	10		18LEM104J	Value Education	1	0	1	0
	Total Learning Cred	lits			15		18GNM101L	Physical & Mental Health using Yoga	0	0	2	0
						_	18GNM102L	NCC/NSS/NSO	0	0	2	0
							18LEM109T	Indian Traditional Knowledge	1	0	0	0
							18LEM110L	Indian Art Form	0	0	2	0
							18CYM101T	Environmental Science	1	0	0	0
								Total Learning Credits				0

	List of Professional Elective Courses (E)			_	
	Any 6 courses				
Course	Course	Hou	irs/ W	/eek	C
Code	Title	L	Т	Р	Ĩ
18BME261T	Biophotonics and Bioimaging	3	0		3
18BME262T	Home Medicare Technology	3	0	0	3
18BME263T	Cellular and molecular biology	3	0	0	3
18BME264T	Biomedical Laser Instruments	3	0	0	3
18BME265T	Artificial Organs and Tissue engineering	3	0	0	3
18BME266T	Biomedical Nano Technology	3	0	0	3
18BME267T	Biometrics	3	0	0	3
18BME361T	BioMEMS	3	0	0	3
18BME362T	Biotransport Phenomenon	3	0	0	3
18BME363T	Human Electro physiology	3	0	0	3
18BME364T	Biomedical device design Fundamentals	3	0	0	3
18BME365T	Innovation, Translation and Entrepreneurship	3	0	0	3
18BME366T	Biomedical microscopy and quantitative imaging	3	0	0	3
18BME367T	Hospital Management system	3	0	0	3
18BME368T	Soft Tissue and Biofluid mechanics	3	0	0	3
18BME369T	Trouble shooting of Medical Devices	3	0	0	3
18BME370T	Quality Assurance and regulatory aspects for medical devices	3	0	0	3
18BME371T	Neuroengineering	3	0	0	3
18BME372T	IOT and Telehealth Technology	3	0	0	3
18BME373T	Micro fluidics	3	0	0	3
18BME374T	Medical Ethics and Intellectual property rights	3	0	0	3
18BME375T	Virtual Instrumentation for Biomedical Engineers	3	0	0	3
18BME376T	Health care data analytics	3	0	0	3
18BME461T	Biomedical Informatics	3	0	0	3
18BME462T	Physiological Modeling	3	0	0	3
18BME463T	Biomimetics	3	0	0	3
18BME464T	Neural Networks and Genetic Algorithms	3	0	0	3
18BME465T	Wearable systems and mobile health care	3	0	0	3
18BME466T	Artificial Intelligence in Health care	3	0	0	3
18BME467T	Bio inspired Robotics	3	0	0	3
18BME468T	Computational tools in Bioengineering and	3	0	0	3
	Biomedicine				
18BME469T	Neuro rehabilitation and Human machine interface	3	0	0	3
18BME470T	Assistive and Augmentative Technologies	3	0	0	3
18BME471T	Machine learning and Deep learning techniques in medicine	3	0	0	3
18BME472T	Virtual Reality in Health care	3	0	0	3
	Total credits				18

24. (a) P	rogram Articulation: B.Tech in Biomedica	ıl Engineer	ing	
			-	-

		Program Learning Outcomes (PLO)														
		Graduate Attributes PSO														
Course Code	Course Name	Engineering Knowledae	Problem Analysis	Design & Develonment	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainabilitv	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
18BMC201J	Biomedical Sensors	Н	М	М	М	L	М	М	М	М	М	L	Н	Н	L	М
18BMC202T	Biomedical Signals and Systems	Н	М	L	L	М	М	М	М	М	L	L	М	М	М	М
18BMC203J	Electric and Electronic Circuits	Н	H	М	Н	М	L	L	L	М	L	L	L	M	H	М
18BMC2041	Principles of Medical Imaging	Н	M	M	M	M	H	M	M	M	L	L	М	H	M	M
18BMC205J	Linear and digital Integrated Circuit	H	M	M	M	M	M	M	M	Н	M	L	M	M	M	M
18BMC206J	Biomaterials-Tissue interaction	H	M	L	L	L	M	M	M	M	M	M	M	H	M	H
10BMC301J	Neulcal Instrumentation	п		П	п	п		П	M	П	IVI M	M	M	П	M	
18BMC3021	Diomedical Signal Processing	п	<u>п</u> н	M	П	M	M	M	M	M	M	M	M	M	M	
18BMC3041	Microcontrollers and its application in medicine	H	M	M	M	M	M	M	M	M	M	M	M	M	M	H
18BMC305T	Ric control Systems	H	M	M	M	M	M	M	M	M	M	M	M	M	M	M
18BMC3061	Medical Image Processing	H	M	H	H	H	H	M	M	H	M	M	M	H	M	H
18BMC401T	Riomedical Equipments for clinical applications	H	1	H	H	H	H	H	M	H	M	M	M	H	M	H
18BMC350T	Comprehension	H	H	Н	H	Н	M	M	M	M	M	M	M	M	H	H
18BMP1011	MOOC / Industrial Training / Seminar - 1	H					M	1	111	111	H	141	H	101	M	
18BMP102L	MOOC / Industrial Training / Seminar - 2	H					M	ī			H		H		M	
18BMP103I	Project (Phase-I) / Internship (4-6 weeks)	H	М	Н	Н	М	H	H	1	Н	H	Н	H	Н	H	М
18BMP104L	Project (Phase-II) / Semester Internship	H	M	H	H	M	H	H	Ē	H	H	H	H	H	H	M
18BME261T	Biophotonics and Bioimaging	H	M	L	L	L	M	M	M	M	M	M	М	H	M	H
18BME262T	Home Medicare Technology	H	L	M	M	M	L	M	M	M	М	M	M	H	M	H
18BME263T	Cellular and molecular biology	Н	L	L	L	L	М	М	М	М	М	М	М	М	М	М
18BME264T	Biomedical Laser Instruments	Н	L	L	L	L	М	М	М	М	М	М	М	М	М	L
18BME265T	Artificial Organs and Tissue engineering	Н	L	L	L	L	М	М	М	М	М	М	М	М	М	М
18BME266T	Biomedical Nano Technology	Н	L	L	L	М	М	М	М	М	М	М	М	Н	М	Н
18BME267T	Biometrics	Н	L	М	М	М	М	М	М	М	М	М	М	Н	Μ	Н
18BME361T	BioMEMS	Н	М	М	М	М	М	М	М	М	М	М	М	Н	Н	Н
18BME362T	Biotransport Phenomenon	Н	L	L	L	L	М	М	М	М	М	М	М	М	М	М
18BME363T	Human Electro physiology	Н	L	L	L	L	М	М	М	М	М	М	М	Н	М	Н
18BME364T	Biomedical device design Fundamentals	Н	Н	Н	Н	Н	Н	Н	Н	Н	М	М	М	Н	Н	Н
18BME365T	Innovation, Translation and Entrepreneurship	Н	М	М	М	М	М	М	М	М	М	М	М	Н	М	Н
18BME366T	Biomedical microscopy and quantitative imaging	Н	М	Н	Н	Н	Н	М	М	Н	М	М	М	Н	М	Н
18BME367T	Hospital Management system	Н	L	L	L	L	М	М	М	М	М	М	М	Н	М	М
18BME368T	Soft Tissue and Biofluid mechanics	Н	L	L	L	L	М	М	М	М	М	М	М	Н	М	М
18BME369T	Trouble shooting of Medical Devices	Н	M	M	M	M	M	M	M	M	М	М	М	H	M	Н
18BME3701	Quality Assurance and regulatory aspects for medical devices	Н	L	L	L	L	M	M	M	M	M	M	M	M	M	M
18BME3/11	Neuroengineering	H	L	L	L	L	M	M	M	M	M	M	M	Н	M	Н
18BME3/21	IUT and Telenealth Technology	H	H	H	H	H	M	M	M	M	M	M	M	H	H	H
18BME3/31	Micro fluidics	H	M	M	M	M	M	M	M	M	M	M	M	H	M	M
18BME3741	Medical Ethics and Intellectual property rights	Н		L	L	L	M	M	M	M	M	M	M	H	M	M
10BME3/31 19DME376T	Virtual Instrumentation for Biomedical Engineers		M	M	M	M	M	M	M	M	M	M	M		M	M
188ME761T	Riomedical Informatics	п	M	IVI		IVI	M	IVI M	M	IVI M	M	M	M	M	M	M
10DIVIE4011	Divineural Informatics	П	M			L	M	M	M	M	M	M	M	M	M	M
18BMF462T	Riomimetics	п					M	IVI M	M	M	M	M	M	M	M	M
18BMF464T	Neural Networks and Genetic Algorithms	H	H	1	1	-	M	M	M	M	M	M	M	H	M	H
18BMF465T	Wearable systems and mobile health care	H	H	M	M	M	M	M	M	M	M	M	M	H	M	H
18BMF466T	Artificial Intelligence in Health care	H	M	M	M	M	M	M	M	M	M	M	M	H	M	M
18BMF467T	Bio inspired Robotics	H	M	M	M	M	M	M	M	M	M	M	M	Н	M	M
18BME468T	Computational tools in Bioengineering and Biomedicine	H	H	M	M	M	M	M	M	M	M	M	M	H	H	H
18BME469T	Neurorehabilitation and Human machine interface	Н	M	M	M	M	M	М	M	М	M	M	M	H	M	Н
18BME470T	Assistive and Augmentative Technologies	H	M	М	M	М	M	M	M	М	M	M	M	Ĥ	M	Н
18BME471T	Machine learning and Deep learning techniques in medicine	Н	М	М	М	М	М	М	М	М	М	М	М	Н	L	Н
18BME472T	Virtual Reality in Health care	Н	М	M	М	М	М	Μ	М	М	М	М	М	Н	М	Н

H – High Correlation, M – Medium Correlation, L – Low Correlation

(g) Implementation Plan: B.Tech in Biomedical Engineering

Semester - I													
Code	Course Title	Course Title Hours/ Week											
		L	Т	Ρ									
18LEH10XJ	Chinese / French / German / Japanese/ Korean	2	0	2	3								
18MAB101T	Calculus and Linear Algebra	3	1	0	4								
18CYB101J	Chemistry	3	1	2	5								
18CSS101J	Programming for Problem Solving	3	0	4	5								
18MES103L	Civil and Mechanical Engineering Workshop	1	0	4	3								
18PDM101L	Professional Skills and Practices	0	0	2	0								
18LEM102J	Value Education	1	0	1	0								
18GNM10XL	NCC/NSS/NSO	0	0	2	0								
	Total Learning Credits				20								

	Semester - II						
Code	Course Title	۲	lour: Nee	s/ k	С		
		L	T	P			
18LEH101J	English	2	0	2	3		
18MAB102T	Advanced Calculus and Complex Analysis	3	1	0	4		
18PYB101J	18PYB101J Physics: Electromagnetic Theory, Quantum Mechanics, Waves and Optics						
18MES101L	Engineering Graphics and Design	1	0	4	3		
18EES101J	Basic Electrical and Electronics Engineering	3	1	2	5		
18PDH101T	General Aptitude	0	0	2	1		
18LEM101T	Constitution of India	1	0	0	0		
18GNM101L	Physical and Mental Health using Yoga	0	0	2	0		
	Total Learning Credits				21		

Semester - IV

Course Title

Code

Hours/ C

Semester - III											
Code	Course Title	Н	lour	s/	С						
		V	Vee	k							
		L	Т	Ρ							
18MAB201T	Transforms and Boundary Value Problems	3	1	0	4						
18PYS202T	Medical Physics	3	0	0	3						
18BTC205J	Pathology & Microbiology	3	0	2	4						
18BMC201J	Biomedical Sensors	3	0	2	4						
18BMC202T	Biomedical Signals and Systems	3	0	0	3						
18BMC203J	Electric and Electronic Circuits	3	0	2	4						
18PDH103T	Social Engineering	2	0	0	2						
18PDM201L	Competencies in Social Skills	0	0	2	0						
18PDM203L	Entrepreneurial Skill Development										
18CYM101T	Environmental Science	1	0	0	0						
	Total Learning Credits				24						

Semester – V													
Code	Course Title	H	lours	s/	С								
		1	Nee	k									
		L	Т	Ρ									
18MAB301T	Probability and Statistics	3	1	0	4								
18BMC301J	Medical Instrumentation	3	0	2	4								
18BMC302T	Biomechanics	3	0	0	3								
18BMC303J	Biomedical Signal Processing	3	0	2	4								
	Professional Elective – 2	3	0	0	3								
	Open Elective – 2	3	0	0	3								
18BMP101L	MOOC / Industrial Training / Seminar - 1	0	0	2	1								
18PDM301L	Analytical and Logical Thinking Skills	0	0	2	0								
19PDM302L	Entrepreneurship Management												
18LEM110L	Indian Art Form	0	0	2	0								
	Total Learning Credits				22								

		V	Vee	k	
		L	Т	Ρ	
18MAB202T	Numerical methods for Engineers	З	1	0	4
18BTB102T	Biology: Human Anatomy and Physiology	2	0	0	2
18BMC204T	Principles of Medical Imaging	З	0	0	3
18BMC205J	Linear and digital Integrated Circuit	З	0	2	4
18BMC206J	Biomaterials - Tissue interaction	3	0	2	4
	Professional Elective – 1	З	0	0	3
	Open Elective – 1	3	0	0	3
18PDH102T	Management Principles for Engineers	2	0	0	2
18PDM202L	Critical and Creative Thinking Skills	0	0	2	0
18PDM204L	Business Basics for Entrepreneurs				
	Total Learning Credits				25

Semester - VI												
Code	Course Title	١	lours Neel	С								
		L	Т	Ρ								
18BMC304J	Microcontrollers and its application in medicine	3	0	2	4							
18BMC305T	Biocontrol Systems	3	0	0	3							
18BMC306J	Medical Image Processing	3	0	2	4							
18BMC350T	Comprehension	0	1	0	1							
	Professional Elective – 3	3	0	0	3							
	Professional Elective – 4	3	0	0	3							
	Open Elective – 3	3	0	0	3							
18BMP102L	MOOC / Industrial Training / Seminar - 2	0	0	2	1							
18PDH201T	Employability Skills and Practices	0	0	2	1							
18LEM109T	Indian Traditional Knowledge	1	0	0	0							
	Total Learning Credits				23							

Semester - VII													
Code	Course Title	۲	lour: Nee	s/ k	С								
		L	Т	Ρ									
18BMC401T	Biomedical Equipments for clinical applications	3	0	0	3								
	Professional Elective – 5	3	0	0	3								
	Professional Elective – 6	3	0	0	3								
	Open Elective – 4	3	0	0	3								
18BMP103L	Project (Phase-I) / Internship (4-6 weeks)	0	0	6	3								
	Total Learning Credits				15								

Semester - VIII													
Code	Course Title	۲	С										
		L	Т	Ρ									
18BMP104L	Project (Phase-II) / Semester Internship	0	0	20	10								
	Total Learning Credits				10								

																						L	Т	Р	С
Course Code	•	18BTC205J	Cours	se Name	PATHOL	DGY AND MICRO	OBIOLO)GY				Cοι	Course Category					Profess	ional C	ore		3	0	2	4
					1									_											
Pre-requisite	Courses			Nil	Co-requisite Courses				Nil			Courses						Nil							
Course Offerin	g Departr	nent		В	Biotechnology		Data B	3ook /	Codes/S	les/Standards Nil															
Course Learni	Learning Rationale (CLR): The purpose of learning this course is to: Learning									Program Learning Outcomes (PLO)															
CLR-1 :	Understan	d the structural and f	unctiona	l aspects of living organisms				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Understand the concept of cellular response during pathogenesis													÷			llity								
CLR-3 :	Illustrate n	nicrobial infections an	nd their li	ifecycle				(moc	(%)	(%)	ge		ŧ	searc			inab		h		e				
CLR-4 :	Apply the	classical and modern	method	s of diagnosing diseases				(Bic	ancy	nent	wled		bme	Re	age	0	usta		n Wi		nanc	þ			
CLR-5 :	Analyze th	e various tissue proc	essing te	echniques				lking	ofici	tainn	Kno	alysi	svelo	sign	I Usé	ulture	t & S		Tear	tion	& Fi	amir			
CLR-6 :	Analyze th	e various antimicrobi	ial drugs					Thir	d Pr	id At	ering	NAna	& De	s, De	Too	& CI	men		al &	nica	Mgt.	g Le			
								elot	pecte	ecte	jinee	blen	sign	alysis	dern	ciety	iron	ics	vidu	nmu	ject	Lon	0-1	0-2	0-3
Course Learni	ng Outco	nes (CLO):		At the end of this course, learne	ers will be able to:			Lev	EXE	Exp	ц	P ⁰	Des	Ana	Mo	Soc	Е Ш	Eth	Indi	Ö	Pro	Life	PS	PS	PS
CLO-1 :	Discuss or	the basic concepts	of cells a	and immune system			1	1, 2	80%	70%												Н			
CLO-2 :	Describe cellular changes during pathogenesis							2	80%	70%				М								Н			
CLO-3 :	Explain the lifecycle of various microbial pathogens							2	80%	70%												Н	Μ		L
CLO-4 :	Explain the application of microscopes in diagnosing various microorganisms							3	80%	70%					М							Н			
CLO-5 :	Discuss various methods and stains used in histopathological analysis							3	80%	70%					Н							Н	М		L
CLO-6 :	Discuss the methods of treatment in microbial infections							3	80%	70%				М								Н			

		Celld and immunity of mammals	Cellular responses during pathogenesis	Clinical Microbiology	Diagnostic pathology	Infection control and prevention
Duratior	n (hour)	15	15	15	15	15
64	SLO-1	Cell structure	Host pathogen interactions – Route of entry	Microbial pathogens – Types, Life cycle	Microscopy	General characters of antimicrobial drugs
3-1	SLO-2	Cytoskeleton	Immune evasion by microbes	Gram positive bacterial pathogens	Light (Bright field & Dark field)	Determining the level of antimicrobial activity
S _2	SLO-1	Structure and function of Cell Membrane	Host damage	Gram negative bacterial pathogens	Phase contrast and Fluorescent microscopy	Antibacterial drugs
5-2	SLO-2	Structure and function of endoplasmic reticulum	PAMS, MAMS	Mycobacterial infections	Electron microscopy	Anti fungal drugs
••	SLO-1	Structure and function of Ribosomes	Microbial secretory systems	Spirochetes	Histopathology	Anti protozoan drugs
S-3	SLO-2	Structure and function of Lysosomes	PRR and signalling	Anaerobic infections	Autopsy pathology	Antiviral drugs
S-4	SLO-1	Lab1: Identification of instruments and culture media preparation	Lab4: Differential Leukocyte count	Lab 7: Differential staining (Spore, AFB)	Lab 10: Fungal pathogen detection by lactophenol cotton blue	Lab 13: antibiotic sensitivity test by Kirby-Bauer method
	SLO-2	Lab1: Identification of instruments and culture media preparation	Lab4: Differential Leukocyte count	Lab 7: Differential staining (Spore, AFB)	Lab 10: Fungal pathogen detection by lactophenol cotton blue	Lab 13: antibiotic sensitivity test by Kirby-Bauer method
85	SLO-1	Lab1: Identification of instruments and culture media preparation	Lab4: Differential Leukocyte count	Lab 7: Differential staining (Spore, AFB)	Lab 10: Fungal pathogen detection by lactophenol cotton blue	Lab 13: antibiotic sensitivity test by Kirby-Bauer method
5-5	SLO-2	Lab1: Identification of instruments and culture media preparation	Lab4: Differential Leukocyte count	Lab 7: Differential staining (Spore, AFB)	Lab 10: Fungal pathogen detection by lactophenol cotton blue	Lab 13: antibiotic sensitivity test by Kirby-Bauer method
5.6	SLO-1	Structure and function of mitochondria	Cellular responses to stress - Hypertrophy	Obligate intracellular bacteria	Surgical pathology	Increase the immune system of host
5-0	SLO-2	Structure and function of nucleus	Metaplasia, Neoplasia	Fungal infections	Enzyme histochemistry	Vaccines – preparation & dosage
S-7	SLO-1	Cell –cell interactions	Hypersensitivity reactions	Yeast infections	Histokinates	Live vaccines
3-7	SLO-2	Gap junctions	Hypersensitivity reactions	Diseases caused by molds	Block making	Attenuated vaccines
c 0	SLO-1	Tight junctions, Desmosomes	Cell injury and death	Dimorphic fungi	Microtomes & Knives	Whole cell vaccines
3-0	SLO-2	Extra cellular matrix	Inflammation (Acute & Chronic)	Parasitic infections	Cryostat	Subunit vaccines
<u> </u>	SLO-1	Lab2: Microscopic observation of prokaryotes and eukaryotes	Lab5: Peripheral blood smear test	Lab 8: Diagnosis of aerobic bacteria by RPR test	Lab 11: Detection of Candida albicans	Lab 14: Demonstration of ELISA based detection of pathogens
3-9	SLO-2	Lab2: Microscopic observation of prokaryotes and eukaryotes	Lab5: Peripheral blood smear test	Lab 8: Diagnosis of aerobic bacteria by RPR test	Lab 11: Detection of Candida albicans	Lab 14: Demonstration of ELISA based detection of pathogens
S-10	SLO-1	Lab2: Microscopic observation of prokaryotes and eukaryotes	Lab5: Peripheral blood smear test	Lab 8: Diagnosis of aerobic bacteria by RPR test	Lab 11: Detection of Candida albicans	Lab 14: Demonstration of ELISA based detection of pathogens

	SLO-2	Lab2: Microscopic observation of prokaryotes and eukaryotes	Lab5: Peripheral blood smear test	Lab 8: Diagnosis of aerobic bacteria by RPR test	Lab 11: Detection of Candida albicans	Lab 14: Demonstration of ELISA based detection of pathogens
S-11	SLO-1	Cell signaling pathways	Apoptosis	Protozoan diseases	Staining	Peptide based therapies
	SLO-2	GPCR and Tyrosine kinase pathway	Causes and biochemical changes of apoptosis	Protozoan diseases	Fat, iron & FAS stains	Antimicrobial peptides
S-12	SLO-1	Signal Transduction	Autophagy	Metazoan diseases	ELISA	Types and therapeutic potential of AMPs
	SLO-2	Cell growth factors – EGF	Intracellular accumulations of autophagy	Metazoan diseases	Western blotting	Prevention of infections
S-13	SLO-1	Hepatocyte growth factors	Immunodeficiency syndrome	DNA virus	PCR	Maintaining the hygiene
	SLO-2	VEGF, PDGF	Immunodeficiency syndrome	RNA virus	Sensor based detection	Isolation for the prevention of infection
S-14	SLO-1	Lab 3: Total WBC count	Lab 6: Simple staining and Gram staining	Lab 9: Detection of salmonella infection by WIDAL test	Lab12: Polymerase chain reaction	Lab15:Demonstration of antigen and antibody purification by using FPLC
	SLO-2	Lab 3: Total WBC count	Lab 6: Simple staining and Gram staining	Lab 9: Detection of salmonella infection by WIDAL test	Lab12: Polymerase chain reaction	Lab15:Demonstration of antigen and antibody purification by using FPLC
S-15	SLO-1	Lab 3: Total WBC count	Lab 6: Simple staining and Gram staining	Lab 9: Detection of salmonella infection by WIDAL test	Lab12: Polymerase chain reaction	Lab15:Demonstration of antigen and antibody purification by using FPLC
	SLO-2	Lab 3: Total WBC count	Lab 6: Simple staining and Gram staining	Lab 9: Detection of salmonella infection by WIDAL test	Lab12: Polymerase chain reaction	Lab15:Demonstration of antigen and antibody purification by using FPLC

Learning Resources	 Robbins and Cotran," Pathologic Basis of Disease" Elsevier Saunders, 9 th edition, 2015. Harsh Mohan, "Textbook of Pathology ', Jaypee publications, 6 th edition, 2010. 	3. Prescott, Harley and Klein's , "Microbiology", Tata McGraw-Hill, New Delhi, 7th edition, 2008
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Learning Assessmen	Learning Assessment													
	Discusio			С	ontinuous Learning Ass	essment (50% weightag	ge)			Final Examinatio	n (50% weightage)			
	BIOOM S Level of Thinking	CLA –	1 (10%)	CLA –	2 (15%)	CLA –	3 (15%)	CLA – 4	4 (10%)#					
	Lover of finitiang	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice			
Lovel 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%			
Level I	Understand	2078	2070	1070	1570	1070	1070	1576	1370	1370	1576			
Lovel 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%			
Level 2	Analyze	2078	2070	2070	2078	2070	2070	2070	2078	2070	2078			
	Evaluate	4004	100/	150/	150/	150/	150/	150/	(5)	1501	(50)			
Level 3 Create		10%	10%	15%	15%	15%	15%	15%	15%	15%	15%			
	Total	100 % 100 %		10	0 %	10	0 %		-					

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldives	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1. Dr.J.Lavanya SRMIST

																	L	Т	Р	С							
Course Co	de	1000102010	Course Name		BION	IEDICAL SEN	SORS					Course Category C			Course Category C			Professional Core		ore		3	0	2	4		
		-																									
Pre-requisit	e Courses		Nil		Co-requisite Courses			Nil						Progre Cour	ssive ses												
Course Offer	ing Departr	nent		Biome	dical Engineering		Data Book	/ Codes/	Standards										Nil								
Course Lear	ning Ration	ale (CLR):	The purpo	ose of learning this co	urse is to:			Learni	ng							Progra	m Lear	ning O	utcome	s (PLO)						
CLR-1 :	Know the	basics of measureme	ent system				1	2	3		1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2 :	Learn the working principles of temperature transducers							y	t												lce						
CLR-3 :	Know the	operating principles of	of pressure transdu	icers				anc	nen			6		-	age				E		nar	þ					
CLR-4 :	Familiarise	e the principles of opt	tical transducers				ting	ficie	in			ysi		ign	Jse	tu	~		ear	5	ίΞ	nir.					
CLR-5 :	Learn the	working of bridges C	ircuits				- ic	2 d	Atta		<u>م</u>	nal	ent	Jes		G	lity		~ ∼	atic	Jt. 8	-ea					
CLR-6 :	Learn the	concepts of smart se	ensors				Ē,	eq	ed		erir dge	٩	∞ bù	is, I ch	1 T	8	ider		a	jū	β	l Br	-	N	~		
								ect	ect		vle vle	ler	ign	lys ear	lerr	iet)	tair	S	k di	Ē	ect	P			Ö		
Course Lear	ning Outco	mes (CLO):	At the end	l of this course, learne	ers will be able to:		Blo e	d Xi %	dx∷⊗		e e	20	Jes Jev	Ana ⋜es	Moc	Soc	Sus	it ji	Noi Noi	Lo Do	jo	_ife	Sc	SC SC	Sc		
CLO-1 :	Explain the	e concepts of measu	rement system				1, 2	80%	70%	N	Λ																
CLO-2 :	Implement	t temperature senso	rs				2	80%	70%	N	Λ																
CLO-3 :	Implement	t pressure sensors					2	80%	70%				М		М								М		L		
CLO-4 :	Demonstra	ate the optical transo	ducers				3	80%	70%						М												
CLO-5 :	Describe t	he operation of brida	es circuits	ircuits			3	80%	70%	N	Λ												М		L		
CLO-6 :	know the o	the concepts of smart sensors					3	80%	70%	N	Λ										1	1	1				

		MEASUREMENT SYSTEM	TEMPERATURE TRANSDUCERS	PRESSURE AND MAGNETIC TRANSDUCERS	OPTICAL TRANSDUCERS AND BRIDGE CIRCUITS	ADVANCES IN SENSING TECHNOLOGIES
Duratio	n (hour)	15	15		15	15
C 1	SLO-1	Measurement system	Transducers	Strain Gauge: Principles	photodiodes	Biosensors: Definition
3-1	SLO-2	Block diagram	Block diagram	Types	Working principles	Block diagram
S-2	SLO-1	Measurement terminologies	Types	Inductive transducer: Principles	phototransistor	Classification of biosensors
0-2	SLO-2	Measurement terminologies	Selection Characteristics	Construction and Working	Working principles	Immobilization of Bio receptor
• •	SLO-1	Types of Instruments	RTD	Load cell	LDR	Lab13: Study on Immobilisation techniques
5-3	SLO-2	types of Instruments	Construction and operating principles	Construction and Working	Working principles	Lab13: Study on Immobilisation techniques
S-4	SLO-1	Selection Criterion	Characteristics	Lab7: Characteristics of strain gauge	Optocouplers	Lab13: Study on Immobilisation techniques
0-4	SLO-2	Selection Criterion	Applications	Lab7: Characteristics of strain gauge	Working principles	Lab13: Study on Immobilisation techniques
	SLO-1	Static characteristics	Lab4: Characteristics of RTD	Lab7: Characteristics of strain gauge	Photovoltaic cell	Biocatalysts based biosensor: Introduction
S-5	SLO-2	Static characteristics	Lab4: Characteristics of RTD	Lab7: Characteristics of strain gauge	Lab10: Characteristics of optoelectronic transducer	Principle
6.6	SLO-1	Dynamic characteristics	Lab4: Characteristics of RTD	LVDT	Lab10: Characteristics of optoelectronic transducer	Glucose Biosensor: Principle
3-0	SLO-2	Dynamic characteristics	Lab:4 Characteristics of RTD	Construction and Working	Lab10: Characteristics of optoelectronic transducer	Construction and operation
S-7	SLO-1	Lab1: Study of static characteristics	Thermistor	Capacitive transducer	Lab10: Characteristics of optoelectronic transducer	Lab14: Measurement of blood glucose
	SLO-2	Lab1: Study of static characteristics	Construction and operating principles	Principles	Working principles	Lab14: Measurement of blood glucose
S_8	SLO-1	Lab1: Study of static characteristics	Characteristics	Modes of operation	wheat stone bridge	Lab14: Measurement of blood glucose
0-0	SLO-2	Lab1: Study of static characteristics	Applications	Modes of operation	Balance equation	Lab14: Measurement of blood glucose
S-9	SLO-1	Errors: Sources and types	Lab5: Characteristics of thermistor	Lab8: Characteristics of LVDT	Kelvin Bridge	Bio affinity based biosensor: Principle
	SLO-2	Methods of minimizing errors	Lab5: Characteristics of thermistor	Lab8: Characteristics of LVDT	Balance equation	Construction and operation
S-10	SLO-1	Lab2: Computation of measurement errors	Lab5: Characteristics of thermistor	Lab8: Characteristics of LVDT	Lab11: Computation of unknown resistance using Bridge circuit	Microbe Biosensor
	SLO-2	Lab2: Computation of measurement errors	Lab5: Characteristics of thermistor	Lab8: Characteristics of LVDT	Lab11: Computation of unknown resistance using Bridge circuit	Construction and operation
S-11	SLO-1	Lab2: Computation of measurement errors	Thermocouple	Piezoelectric active transducer	Lab11: Computation of unknown resistance using Bridge circuit	Electrochemical Biosensor: Principle

	SLO-2	Lab2: Computation of measurement errors	Construction and operating principles	Construction and Working	Lab11: Computation of unknown resistance using Bridge circuit	Construction and operation
S-12	SLO-1	Measurement standards	Characteristics	Hall effect	Maxwell Bridge	Smart Sensors: Introduction
	SLO-2	Types of standards	Applications	Principles of hall effect sensors	Balance equation	Salient features
S-13	SLO-1	Calibration	Lab6: Characteristics of thermocouple	Applications of hall effect sensors	Schering Bridge	Architecture
	SLO-2	Types	Lab6: Characteristics of thermocouple	Applications of hall effect sensors	Balance equation	Applications
S-14	SLO-1	Lab3: Calibration of measuring devices	Lab6: Characteristics of thermocouple	Lab9: Characteristics of Piezoelectric transducer	Lab12: Computation of unknown Inductance and capacitance using Bridge circuit	Lab15: Minor Project
	SLO-2	Lab3: Calibration of measuring devices	Lab6: Characteristics of thermocouple	Lab9: Characteristics of Piezoelectric transducer	Lab12: Computation of unknown Inductance and capacitance using Bridge circuit	Lab15: Minor Project
S-15	SLO-1	Lab3: Calibration of measuring devices	Semiconductor based temperature sensors	Lab9: Characteristics of Piezoelectric transducer	Lab12: Computation of unknown Inductance and capacitance using Bridge circuit	Lab15: Minor Project
	SLO-2	Lab3: Calibration of measuring devices	Semiconductor based temperature sensors	Lab9: Characteristics of Piezoelectric transducer	Lab12: Computation of unknown Inductance and capacitance using Bridge circuit	Lab15: Minor Project

	1.	Sawhney A.K, "A Course in electrical and electronic measurements and instrumentation", Dhanpat Rai & Co (P) Ltd,
		Educational and Technical Publishers, 19th Revised edition 2011, Reprint 2014.
Learning	2.	Patranabis D, "Sensors and transducers", PHI, 2nd edition, 2004
Resources	3.	Murty DVS, "Transducer and instrumentation", PHI, 2nd edition, 2010.
	4.	U.A. Bakshi, A.V. Bakshi, "Measurements and instrumentation", Technical Publications, 3rd revised edition, 2010.
	5.	Paras N, Prasad, "Introduction to biophotonics", John Wiley & Sons, 1st edition, 2003

Learning Assessment													
	Discusio			C	ontinuous Learning Ass	essment (50% weightag	je)			Einal Examination	(E0% weightage)		
	BIOOM S Level of Thinking	CLA –	1 (10%)	CLA –	2 (15%)	CLA – S	3 (15%)	CLA – 4	4 (10%)#	i inai Examination (50 % weightage)			
	20101011111119	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice		
Lovel 1	Remember	200/	200/	150/	150/	150/	150/	150/	150/	150/	150/		
Level I	Understand	2076	2070	1376	1370	1570	1370	1376	1576	1376	1576		
Lovel 2	Apply	200/	200/	200/	20%	20%	200/	200/	200/	200/	200/		
Level 2	Analyze	20%	2078	2076			20%	20%	2076	2076	2070		
	Evaluate	4004	1001	(5)	(5)	1507	1507	(5)	(50)	150/	150/		
Level 3	Create	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%		
	Total	10	0 %	10	0 %	100) %	10	0 %		-		

Course Designers												
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts										
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldives	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1. Dr.D.Kathirvelu, SRMIST										

Course Code	18BMC202T	Course Name		BIOMEDICAL SIGNALS AND			TEMS			Cou	Course Category C			Professional core				L 3	T 0	P 0	C 3			
																					<u> </u>			
Pre-requisite C	ourses			Co-requisite Courses Progressive Courses																				
Course Offering	Department	Biomedica	al Engineering		Data Bo	ok / C	odes/ S	Standard	ls			Nil												
Course Learning	g Rationale (CLR):	The purpo	se of learning this cou	rse is to:		I	Learnir	g						F	Program	n Learr	ning Ou	Itcomes	(PLO))				
CLR-1 :	Understand the Classificati	on of the continuous	time signals and syst	ems and discrete-time signals and		1	2	3		1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 : CLR-3 :	2: Acquire the knowledge about the Continuous Time Signals and System 3: Utilize the knowledge of Convolution and Correlation in biosignals						ency	nent					_	ge				c			þ	sional		8
CLR-4 :	. Understand the concepts	of z-transform and di	screte Fourier transfo	m		king	officie	ainn			lysis		sign	Usa	lture	∞ _		Fear	U	ంద	amir	ofess		alyze
CLR-5 :	Analyze the discrete time I	R and FIR systems b	y using suitable struc	tures		lhin	Pre	Att		je je	Ana	nen	De	0	Cu	ility		_ ∞	icati	lgt.	Le	Pro	Pro Jen 4	Ä
CLR-6 :	Acquire knowledge in biosi	gnal applications				ے و	cted	cted		ledo	em	jn & Iopn	/sis, arch	E E	sty 8	onm ainal	Ś	dua	unu	ct N	ong	- 1: ven	- Z. Igen	- 3: ach
Course Learning	g Outcomes (CLO):	At the end	of this course, learner	s will be able to:		Level (Bloo	Expe	Expe		Engir Know	Probl	Desiç Deve	Anal) Rese	Mode	Socie	Envir Susta	Ethic	Indivi Work	Com	Proje Finar	LifeL	PSO Achie	PSU Mane Tach	PSO Rese
CLO-1 :	Analyze the Discrete time	signals and system	S			3	80	75		М	-	-	-	-	-	-	-	-	-	-	-	М	_	-
CLO-2 :	Analyze the Continuous Ti	me Signals and Syste	em			3	80	70		М	-	-	-	-	-	-	-	-	-	-	-	-	М	- 1
CLO-3 :	Illustrate the concepts of co	onvolution and correl	ation in biosignals			3	75	70		М	-	-	-	-	-	-	-	-	-	-	-	-	_	М
CLO-4 :	Analyze the transforms of I	Discrete Time Signals	and Systems			3	80	75		-	-	М	-	-	-	-	-	-	-	-	-	-	-	М
CLO-5 :	Analyze the concept of realization using suitable filter structures				3	80	70		-	-	-	М	-	-	-	-	-	-	-	-	-	-	М	
CLO-6:	-6: Explain the application of biomedical signals					3	80	70		-	-	-	М	-	-	-	-	-	-	-	-	-	-	М

		Basics OF Discrete time and continuous time	Analysis of Continuous Time Signals and	Convolution and Correlation of Discrete Time	Transforms of Discrete Time Signals and	Realization and Biosignal Applications
		signais and systems	System	Signais	Systems	-
Duratio	n (hour)	9	9	9	9	9
S-1	SLO-1	representation of discrete time signals	Fourier transform analysis	linear convolution	Z transform	Introduction to discrete time Infinite impulse response (IIR)
	SLO-2	continuous time signals	Properties	Tutorials	-properties	finite impulse response (FIR) systems
S-2	SLO-1	standard discrete time signals,	Tutorials	Circular convolution-	region of convergence	Structure for realization of IIR systems-direct form-I
	SLO-2	standard continuous time signals	Tutorials	Tutorials	Tutorials	Tutorials
6.2	SLO-1	Classification of signals: Continuous time(CT)	Laplace transform analysis	linear convolution via circular convolution	representation of poles and zeros in z transform	direct form-II
3-3	SLO-2	Tutorials	properties	Tutorials	Tutorials	Tutorials
S-4	SLO-1	Classification of Discrete time (DT) signals	Tutorials	Sectioned convolution-overlap add method	Inverse z transform- residue method	Cascade form
04	SLO-2	Tutorials	Tutorials	Tutorials	Tutorials	Tutorials
85	SLO-1	Mathematical operations on CTS- scaling, folding	Poles and zeros	Overlap save method	Partial fraction method	parallel form of IIR system
3-3	SLO-2	time shifting, addition and multiplication	Poles and zeros	Tutorials	Tutorials	Tutorials
	SLO-1	Mathematical operations on DTS- scaling, folding	Analysis of differential equation- impulse response	Inverse system	Discrete time fourier transform-	Structure for realization of FIR systems-direct form
S-6	SLO-2	time shifting, addition and multiplication	Transfer function	deconvolution	properties	Tutorials
S- 7	SLO-1	Classification of systems: static and dynamic systems	Tutorials	Correlation- autocorrelation	Tutorials	cascade and linear phase realization of FIR systems
	SLO-2	time invariant and time variant	Tutorials	Tutorials	Tutorials	Tutorials
S-8	SLO-1	linear and nonlinear systems,	Analysis of differential equation-frequency response	cross correlation	Relation between Z transform and DTFT	Neural Firing rate analysis
	SLO-2	causal and non-causal systems,	Tutorials	Tutorials	Introduction to discrete fourier transform	Nerve action potentials
	SLO-1	stable and unstable systems	Biosignal measurements	Correlation of Biosignals	DFT-properties	Linearized model and system equations for immune response
5-9	SLO-2	Tutorials	Biosignal measurements	ECG,EMG	Tutorials	Linearized model and system equations for immune response

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NESUULES		

Learning Assess	sment														
	Bloom's			C	Continuous Learning Ass	essment (50% weightag	ge)			Final Examination (50% weighted)					
	DIUUIIIS	CLA –	1 (10%)	CLA –	2 (15%)	CLA –	3 (15%)	CLA –	4 (10%)#	Final Examination (50 % weightage)					
	Level of Thinking	Theory Practice Theory Practice		Theory	Practice	Theory	Practice	Theory	Practice						
	Remember	20.0/		20.0/		20.0/		20.0/		200/					
	Understand	30 %	-	30 %		30 %	-	30 %	-	30%	-				
Lovel 2	Apply	10 %		10 %		10 %		10 %	_	10%					
Level Z	Analyze	40 70	-	40 /0	-	40 /0	-	40 /0	-	4070	-				
	Evaluate	20.0/		20.0/		20.0/		20.0/		200/					
	Create	30 %	-	30 %	-	30 %	-	30 %	-	30%	-				
i	Total 100 % 100 %				0 %	10	0 %	0 %	100 %						

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldives	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1. Dr.U.Snekhalatha, SRMIST

Course Co	de 18BMC203J	Course Name	ELECTRIC AN	ND ELECTRONIC CIRCUITS		Cour Categ	rse Jory	С	C Professional Core				L	F F) 2		C 4						
Pre-requence Course	uisite _{Nil} ses		Co-requisite Courses			Progre Cou	essive rses	Nil														
Course Off	ering Department	Biomedi	cal Engineering	Data Book / Codes/Standards	Nil																	
Course Learning Rationale (CLR): The purpose of learning this course is to: Learning Program Learning Outcomes (PLO))												
CLR-1 :	Analyze real-time circuits	using mesh and r	odal analysis and network reduction		1	2	3		1	2	3 4	5	6	7	8	9	10	11	12	13 1	4	15
CLR-2 :	To learn various Network	theorems for ana	lyzing electrical circuits																			
CLR-3 :	To learn the principles of I	network theorems	in simplifying electrical circuits																			
CLR-4 :	Provide a basis for unders	tanding semicon	ductor material, how a pn junction is formed a	and its principle of operation										~								
CLR-5 :	Explain the importance of	diode in electron	c circuits by presenting appropriate diode ap	plications	Ê	(%	(%)		e		arch			abilit		×						
CLR-6 :	Describe the basic structu	re, operation and	characteristics of BJT, and discuss its use as	s a switch and an amplifier	(Bloc	ncy ('	ent (/ledg		Rese	e		Istain		Wor		ance	-			
					king	oficie	ainm		Know	lysis	velop sign,	Usaç	lture	& SL		Team	.u	& Fin	arning			
Course Lea	rning Outcomes (CLO):	At the end	of this course, learners will be able to:		Level of Thin	Expected Pro	Expected Att		Engineering	Problem Ana	Design & De Analysis, De	Modem Tool	Society & Cu	Environment	Ethics	Individual & ⁻	Communicat	Project Mgt.	Life Long Le	PSO - 1	PS0 - 2	PSO – 3
CLO-1 :	Apply the concepts of me	sh and nodal ana	ysis in solving electric circuits		1	80	70		Н	Н		-	-	-	-	М	-	-	-	M	М	-
CLO-2 :	Implement the concepts o	f network theorer	ns in simplifying electric circuits		1, 2	80	70		Н	Н	1 -	-	-	-	-	М	-	-	-	M	М	-
CLO-3 :	D-3 : Evaluate solutions of network theorems for electric circuits						70		Н	Η	1 -	-	-	-	-	М	-	-	-	M	И	-
CLO-4 :	LO-4 : Understand the operation, characteristics, parameters and specifications of semiconductor diodes						70		Н	Η	1 -	-	-	-	-	М	-	-	-	M	М	-
CLO-5 :	LO-5 : Review bipolar transistor construction, operation, characteristics and parameters, as well as its application in amplification and switching.						70		Н	Н	- M	-	-	-	-	М	-	-	-	М	И	-
CLO-6 :	LO-6 : Build a circuit, then make functional measurements to understand the operating characteristics of the circuit						70		Н	H	1 -	-	-	-	-	М	-	-	-	М	М	-

Duration (hour)		METHODS OF ANALYSING CIRCUITS	NETWORK THEOREMS	NETWORK THEOREMS	SEMICONDUCTOR DIODES	DIODE CIRCUITS AND BIPOLAR JUNCTION TRANSISTORS
		15	15	15	15	15
6 .1	SLO-1	Introduction – Circuit Variables and Circuit Elements	Thevenin's Theorem	Superposition Theorem	Basic semiconductor theory: Intrinsic & extrinsic semiconductors	Half wave rectifier operation, Efficiency and ripple factor
5-1	SLO-2	Basic Circuits Laws : Kirchoff's Voltage Law (KVL)	Practice problems	Practice problems	Current flow in semiconductors	Center-Tapped Transformer Full wave rectifier operation, Efficiency and ripple factor
S-2	SLO-1	Kirchoff's Current Law (KCL) Practice problems		Practice problems	PN junction theory	Bridge wave rectifier operation, Efficiency and ripple factor
5-2	SLO-2	Practice problems	Practice problems	Practice problems	Forward biased PN junction	Problem solving
6.2	SLO-1	Lab1: Verification of KVL	Lab 4: Verification of Thevenin's theorem	Lab 7: Verification of Superposition Theorem	Reverse biased PN junction	Lab 12: Diode circuits
3-3	SLO-2	Lab1: Verification of KVL	: Verification of KVL Lab 4: Verification of Thevenin's theorem L		Relation between Current and Voltage	Lab 12: Diode circuits
2	SLO-1	Lab1: Verification of KVL	Lab 4: Verification of Thevenin's theorem	Lab 7: Verification of Superposition Theorem	Problem solving	Lab 12: Diode circuits
3-4	SLO-2	Lab1: Verification of KVL	Lab 4: Verification of Thevenin's theorem	Lab 7: Verification of Superposition Theorem	Lab 10: PN Junction Diode Characteristics	Lab 12: Diode circuits
S-5	SLO-1	Mesh analysis	Norton's Theorem	Compensation Theorem	Lab 10: PN Junction Diode Characteristics	Physical structure

	SLO-2	Mesh analysis	Practice problems	Practice problems	Lab 10: PN Junction Diode Characteristics	Device operation of Bipolar junction transistor (BJT)
8-6	SLO-1	Mesh analysis	Practice problems	Practice problems	Lab 10: PN Junction Diode Characteristics	Device operation of Bipolar junction transistor (BJT)
0-0	SLO-2	Practice problems	Practice problems	Practice problems	Calculation of depletion width	Current configuration -Voltage characteristics of Common Emitter (CE) BJT
S-7	SLO-1	Practice problems	Lab 5: Verification of Norton's theorem	Lab 8: Verification of Compensation Theorem	Calculation of barrier potential	Current-Voltage characteristics of CE BJT configuration
3-1	SLO-2	Practice problems	Lab 5: Verification of Norton's theorem	Lab 8: Verification of Compensation Theorem	Derivation: diode current equation	Current-Voltage characteristics of Common Base (CB) BJT configuration
SL0-1		Lab 2: Verification of KCL	Lab 5: Verification of Norton's theorem	Lab 8: Verification of Compensation Theorem	Derivation: diode current equation	Current-Voltage characteristics of CB BJT configuration
5-6	SLO-2	Lab 2: Verification of KCL	Lab 5: Verification of Norton's theorem	Lab 8: Verification of Compensation Theorem	Effect of Capacitance in PN junction: Transition Capacitance	Lab 13: CE and CB configurations – Input and output characteristics
6.0	SLO-1	Lab 2: Verification of KCL	Maximum Power Transfer Theorem	Reciprocity theorem	Diffusion Capacitance	Lab 13: CE and CB configurations – Input and output characteristics
3-9	SLO-2	Lab 2: Verification of KCL	Practice problems	Practice problems	Problem solving	Lab 13: CE and CB configurations – Input and output characteristics
S 10	SLO-1	Nodal Analysis	Practice problems	Practice problems	Lab 11: Zener diode characteristics	Lab 13: CE and CB configurations – Input and output characteristics
3-10	SLO-2	Nodal Analysis	Practice problems	Practice problems	Lab 11: Zener diode characteristics	Current-Voltage characteristics of CC BJT configuration
6 44	SLO-1	Nodal Analysis	Lab 6: Verification of Maximum Power Transfer Theorem	Substitution theorem	Lab 11: Zener diode characteristics	Current-Voltage characteristics of CC BJT configuration
3-11	SLO-2	Practice problems	Lab 6: Verification of Maximum Power Transfer Theorem	Practice problems	Lab 11: Zener diode characteristics	BJT as an amplifier
S-12	SLO-1	Lab 3: Mesh Analysis	Lab 6: Verification of Maximum Power Transfer Theorem	Practice problems	Energy band structure of PN Junction Diode	BJT as a switch
5-12	SLO-2	Lab 3: Mesh Analysis	Lab 6: Verification of Maximum Power Transfer Theorem	Practice problems	Ideal diode and its current-voltage characteristics	Problem solving
S-13	SLO-1	Lab 3: Mesh Analysis	Millman's theorem	Lab 9: Verification of Reciprocity & Substitution theorem	Terminal characteristics & parameters	Lab 14: Miniproject
3-13	SLO-2	Lab 3: Mesh Analysis	Practice problems	Lab 9: Verification of Reciprocity & Substitution theorem	Diode modeling	Lab 14: Miniproject
S-14	SLO-1	Source Transformation Technique	Tellegen's theorem	Lab 9: Verification of Reciprocity & Substitution theorem	DC load line and analysis	Lab 14: Miniproject
5-14	SLO-2	Source Transformation Technique : Practice problems	Practice problems	Lab 9: Verification of Reciprocity & Substitution theorem	Problem solving	Lab 14: Miniproject
SLO-1		Star-Delta Transformation	Duals and Duality	Lab 9: Verification of Reciprocity & Substitution Theorem	Problem solving	Lab 14: Miniproject
3-13	SLO-2	Star-Delta Transformation: Practice problems	Practice problems	Lab 9: Verification of Reciprocity & Substitution Theorem	Problem solving	Lab 14: Miniproject

Learning Resources	 David A. Bell, Electronic Devices and Circuits, 5th ed., Oxford University Press, 2015. Jegatheesan R, Analysis of Electric Circuits, McGraw Hill, 2014. Robert L. Boylestad, Louis Nashelsky, Electronic Devices and Circuit Theory, 11th ed., Pearson Education, 2013 William H. Hayt, Jack E. Kemmerly, Steven M. Durbin, Engineering circuit analysis, 8th ed., McGraw Hill, 2012 Mahmood Nahvi & Joseph Edminister, "Schaum's Outline of Electric circuits", McGraw-Hill Education, 5th edition 2011. 	
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Learning Asse	ssment												
	Dia angla			C	Continuous Learning Ass	essment (50% weightag	ge)			Final Evanination	(EOO/ unsighters)		
	BIOOM S	CLA –	CLA – 1 (10%)		CLA – 2 (15%)		3 (15%)	CLA –	4 (10%)#	Final Examination (50% weightage)			
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice		
Level 1	Remember	10.0/		40.0/		40.0/		20.0/		2007			
Level I	Understand	40 %	40 %	-	40 %	-	40 %	-	30 %	-	30%	-	
Level 0	Apply	40.0/		40.0/		40.0/		40.0/		400/			
Level Z	Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-		
Lovel 2	Evaluate	20.0/		20.0/		20.0/		20.0/		200/			
Level 5	Create	20 %	-	20 %	-	20 %	-	30 %	-	30%	-		
	Total	10	0 %	100 % 100 %) %	10	0 %	100 %				

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldives	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1. Mr.P. Muthu, SRMIST

Course Cod	le	18BMC204T	Course Name	Princip	oles of Medical Imaging						Course Category C Professional Core L T 3 0					P 0	C 3						
Pre-requisite	Courses		Nil	Co-requisite Courses	Deta	Nil Dete Besti / Cede/Chandeda					Progre Cour	essive ses	ne Nil										
Course Offeri	ng Departr	ment		Biomedical Engineering	Data	BOOK / V	Joaes/	Standard	S								INII						
Course Learn	ing Ration	ale (CLR):	The purpo	se of learning this course is to:			Learn	ing						Prograr	n Leari	ning Ou	utcomes	(PLO)					
CLR-1 :	Understan	nd the physics of X –ra	ay production			1	2	3		1	2	3 4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Learn the	components of Comp	outed tomography a	nd different generations			y	ıt											lce				
CLR-3 :	Gain know	vledge in PET and SP	PECT imaging			_	Suc	ner			ŝ	-	age	a)			۶		nar	p	, I		
CLR-4 :	Understan	d the physics of MRI	imaging			ś	fici	ainr			ysi	lign	Us	ture	ø		ear	Б	i. Z	Ē	, I		
CLR-5 :	Gain know	vledge about the reco	nstruction of image	s in MRI		i	Pr	Atta		و م	nal	ent Des	0	Cul	ent.		& T	cati	Jt. 8	Lea	, I		
CLR-6 :	Learn abo	ut different types of se	canners – A, B & N	I mode and Duplex ultrasound scanners		E -	ed	eq		erir dg	٩u	s, l ch	Τ	8	ab ab		la	nić	Ĕ	þ		N	ŝ
						elo	ect	ect		vle	oler	ign lys ear	len	iet)	iror tair	S	k vidi	Ē	ect	ē		Ö	
Course Learn	ing Outco	mes (CLO):	At the end	of this course, learners will be able to:		- è g		(%) dx %		en S	DD-	Dev Ana Res	Moc	တို	≣nv Sus	Ithi	Noi	Sol	D	life	, X I	SC	Sc
CLO-1 :	Describe t	he production of X ray	y and the working I	principle of X –ray machine		1, 2	80%	70%		M					/								
CLO-2 :	Differentia	te the generations of	CT			2	80%	70%		М													
CLO-3 :	Illustrate tl	he working principle o	of PET and SPECT	scanner		2	80%	70%				М	М								М		L
CLO-4 :	Differentia	te and analyze the va	arious image comp	ession and registration algorithms		3	80%	70%					М								, — – I		
CLO-5 :	Describe t	he working principle of	of MRI and its diffe	ent components		3	80%	70%		М											М		L
CLO-6 :	Illustrate the working of Different ultrasound scanners						80%	70%		М											, — – I		

		X-ray Imaging and Digital Radiography	Computed Tomography	Nuclear imaging	Magnetic resonance imaging	Ultrasound imaging
Duration	n (hour)	9	9	9	9	9
6.4	SLO-1	Nature of X-rays	Computed Tomography	Radio isotopes in medical diagnosis	Principles of NMR	Diagnostic Ultrasound
9-1	SLO-2	Properties of X -rays	basic principle	Physics of Radioactivity	Free induction decay	Physics of Ultrasonic Waves
6.2	SLO-1	Production of X-rays	Contrast scale – CT number	Radiation Detectors – Ionization chamber	T1 and T2 relaxation	Generation and detection of ultrasound
3-2	SLO-2	Stationary X –ray anode tube	CT – system components	Scintillation detector	Fourier transformation of FID	Medical Ultrasound
6.2	SLO-1	Rotating anode tube	Scanning system	Semiconductor detectors	Bloch equation	Basic Pulse-echo Apparatus
3-3	SLO-2	X –ray machine	Different generation of CT	Solid state detectors	Image Reconstruction Techniques	A scanner and applications
64	SLO-1	High frequency generator	X – ray source	Pulse Height Analyzer	Sequential point method, Sequential line method	B scanner and applications
3-4	SLO-2	Collimators and grids	X –ray detectors and types	Uptake Monitoring Equipment	Sequential plane method	Echocardiograph (M-mode)
с <i>с</i>	SLO-1	Automatic exposure control – photo cell method	Data acquisition system	Radio-isotope Rectilinear Scanner	Discrimination based on relaxation rates	Block diagram of echo cardiograph circuit
3-0	SLO-2	Ionization method	Processing unit	The Gamma Camera	Saturation recovery	Doppler scanner
5.6	SLO-1	Visualization of X-rays – X- ray film	Iterative reconstruction	Multi crystal gamma camera	Inversion recovery	Principles of Elastography, Shear wave elastography
5-0	SLO-2	Fluorescent screen	Back projection reconstruction	Block diagram and description of Multi crystal gamma camera	Spin echo imaging technique	Real time ultrasonic imaging systems
	SLO-1	X –ray image intensifier tube	Filtered back projection	Emission computed tomography	Generic pulse sequence used in MRI	Multi-element Linear Array Scanners
S-7	SLO-2	X –ray image intensifier system	Block diagram of the image computer	Single-photon Emission Computed Tomography – Principle	Basic NMR Components	Linear array scanner
C 0	SLO-1	Dental X-ray Machines	Viewing system	SPECT system – simplified diagram and description	NMR Detection system, NMR gradient control system	Phased array system
3-0	SLO-2	Portable and Mobile X-ray Units	Storing and documentation	Positron Emission Tomography - Principle	Biological Effects of NMR Imaging Advantages of NMR Imaging System	Area array system
S-9	SLO-1	Digital Radiography	Gantry geometry	PET – Gantry and detector module	fMRI basic physics, Image acquisition procedure	Duplex scanner
	SLO-2	Flat panel detectors	Patient dose in CT scanners	Data acquisition system for PET scanner	MR spectroscopy basic block diagram and applications	Intravascular imaging

Learning	1.	R.S.Khandpur., 'Handbook of Biomedical instrumentation', Tata McGraw Hill Publishing Co Ltd., 3rd edition, 2014.	3.	M. A. Flower (Editor)., "Webb's Physics of medical imaging, Second Edition", CRC Press, Taylor & Francis
Resources	2.	Jerrold T. Bushberg, John M. Boone., "The essential physics of medical imaging", Lippincott Williams & Wilkins, 3rd edition,		Group, ISBN: 978-0-7503-0573-0, 2nd edition, 2016. Nadine Barrie Smith, Andrew Webb, "Introduction to
		2011.		medical imaging: Physics, Engineering and clinical applications", Cambridge University Press, 1st edition,
				2010.
			4.	K. Kirk Shung, Michael Smith, Benjamin M.W. Tsui., "Principles of medical imaging", Academic Press, 1st
				edition, 2012.

Learning Assess	ment													
	Diaam'a			Co	ontinuous Learning Ass	essment (50% weightag	je)			Einal Examination (50% weightage)				
	DIOUIIIS	CLA –	1 (10%)	CLA –	2 (15%)	CLA –	3 (15%)	CLA – 4	4 (10%)#	Final Examination (50% weightage)				
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice			
Lovel 1	Remember	200/	200/	150/	150/	150/	150/	150/	150/	150/	150/			
Level I	Understand	20%	20%	13%	10%	13%	13%	13%	13%	15%	15%			
Lovel 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%			
LEVEIZ	Analyze	2070	2070	2070	2070	2070	2070	2070	2070	2078	2078			
Lough 2	Evaluate	100/	100/	150/	150/	150/	150/	150/	150/	150/	150/			
Level 5	Create	10%	10%	13%	10%	13%	13%	13%	13%	15%	15%			
	Total	10	0 %	100	0 %	100) %	10	0 %		-			

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldives	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1., Dr. S. P. Angeline Kirubha, SRMIST

Course Coo	de 18BMC205T	Course Name	LINEAR AND DIGITAL IN	NTEGRATED CIRCUITS			(Course	Catego	гу	С		Prof	ession	al Core	9	L 3	۲ (P 2	C 4
Pre-requisite Courses Nil Progressive Courses Nil																					
Course Offer	ing Department		Biomedical Engineering	Data Book / Codes/Stand	ards						1				Nil						
Course Learn	ning Rationale (CLR):	The purpose of learning this cou	rse is to:		L	earnin	g					Pro	gram L	.earniı	ng Out	comes	(PLO)				
CLR-1 : U	Inderstand the operation and a	alysis of op-amp oscillators, singl	e chip oscillators and frequency generators		1	2	3	1	2	3	4	5	6	7	8	9 10) 11	12	13	14	15
CLR-2 : I CLR-3 : C CLR-4 : F CLR-5 : F CLR-6 : F	dentify the active filter types, filt Gain knowledge on data convert and D/A conversions. Familiarize mathematical operat Able to design simple combinatio Familiarize with basic sequential analyze sequential logic circuits	er response characteristics, filter p er terminology, its performance pa ons onal logics using basic gates and I logic components: filp-flops, regis and Finite State Machines	arameters and IC voltage regulators rameters, and various circuit arrangements ISI circuits ters, counters and their usage, and able to	s for A/D design and	of Thinking (Bloom)	cted Proficiency (%)	sted Attainment (%)	and a ball and a second	em Analvsis	n & Development	sis, Design, Research	m Tool Usage	ty & Culture	onment & Sustainability		dual & Team Work	ct Mgt. & Finance	ong Leaming	- 1	- 2	- 3
Course Learn	ning Outcomes (CLO):	At the end of this course, learner	s will be able to:		Level	Expe	Expe		Probl	Desiç	Analy	Mode	Socie	Envir	Ethic	Com	Proje	Life L	PSO	PSO	PSO
CLO-1 : E	Elucidate and design the linear a	nd non-linear applications of an o	pamp and special application ICs		1, 2	80	70	٨	1 M	L	-	-	-	-	-		-	М	М	-	-
CLO-2 : 0	Classify and comprehend the wo	rking principle of data converters	and active filters		1, 2	80	70	٨	1 L	-	-	-	-	-	-		-	L	L	-	-
CLO-3 : //	llustrate the function of applicati	on specific ICs such as Voltage re	gulators and ADC and DAC		1,2	80	70		М	-	L	-	-	-	-		-	-	L	L	-
CLO-4 : U	Jnderstand, analyze, design and	I troubleshoot various combination	al logic circuits		2	80	70	٨	1 M	L	М	М	-	-	-		-	-	-	L	М
CLO-5 : U	Inderstand, analyze, design and	I troubleshoot various clocked seq	uential logic circuits.		2,3	80	70	-	-	М	М	М	-	-	-		-	-	-	L	М
CLO-6 : A	Analyze, design and implement	rarious digital logic circuits using F	PLDs		3	80	70	-	M	-	М	-	-	-	-		-	-	-	L	М

Duration (hour)		Applications of Op-amp	Oscillators and Filters	Analog and digital converters	Combinational Systems	Sequential System
		15	15	15	12	12
S-1	SLO-1	Basic op-amp circuits: Inverting & Noninverting voltage amplifiers	Waveform Generators: Sine-wave Generators - Design	Digital to Analog Conversion: DAC Specifications	Binary arithmetic units	Flip-flop and Latch: SR latch,
	SLO-2	Voltage follower	Implementation & Solving problems	Solving problems	Adder	JK flip-flop, T flip-flop, D flip-flop
6.2	SLO-1	Summing, scaling & averaging amplifiers,	Square Wave generators- Design	Weighted Resistor DAC	Design of Half adder	Master-slave RS flip-flop
3-2	SLO-2	AC amplifiers	Implementation & Solving problems	Solving problems	Design of Full adder	Master-slave JK flip-flop
6.2	SLO-1	Linear Applications: Instrumentation Amplifiers	Triangle wave generators	R-2R Ladder DAC	Subtractor	Registers & Counters
8-3	SLO-2	Instrumentation Amplifiers, Solving Problems	Saw-tooth Wave generators	Solving problems	Design subtractor using logic gates	Shift registers (SISO, SIPO, PISO, PIPO)
6.4	SLO-1	Lab 1: Comparators	Lab 4: Waveform generators: using opamp & 555 Timer	Lab 7: Flash Type ADC	LAB 10: Implement combinational logic functions using standard ICs	LAB 13: Design and implement Synchronous Counters
5-4	SLO-2	Lab 1: Comparators	Lab 4: Waveform generators: using opamp & 555 Timer	Lab 7: Flash Type ADC	LAB 10: Implement combinational logic functions using standard ICs	LAB 13: Design and implement Synchronous Counters
0.5	SLO-1	Lab 1: Comparators	Lab 4: Waveform generators: using opamp & 555 Timer	Lab 7: Flash Type ADC	LAB 10: Implement combinational logic functions using standard ICs	LAB 13: Design and implement Synchronous Counters
3-0	SLO-2	Lab 1: Comparators	Lab 4: Waveform generators: using opamp & 555 Timer	Lab 7: Flash Type ADC	LAB 10: Implement combinational logic functions using standard ICs	LAB 13: Design and implement Synchronous Counters
S-6	SLO-1	V-to-I Converters	Comparison between Passive and Active Networks	Inverted R-2R Ladder DAC	n-bit parallel adder & subtractor	Universal shift register
	SLO-2	I-to-V converter	Active Network Design	Monolithic DAC	look ahead carry generator	Synchronous counters, Modulus-n Counter
S-7	SLO-1	Differentiators	Filter Approximations	Analog to Digital conversion: ADC specifications	Decoder	Mealy and Moore model

	SLO-2	Integrators	Design of LPF & Solving problems	Solving problems	Encoder	Mealy and Moore model
c 0	SLO-1	Non-linear Applications: Precision Rectifiers	Design of HPF & Solving problems	Ramp Type ADC	Multiplexer	Synchronous (Clocked) sequential circuits
3-0	SLO-2	Wave Shaping Circuits (Clipper and Clampers)	Design of BPF& Solving problems	Solving problems	Demultiplexer	Synchronous (Clocked) sequential circuits
6.0	SLO-1	Lab 2: Wave shaping circuits	Lab 5: Design of LPF, HPF, BPF and Band Reject Filters	Lab 8: Simulation experiments using EDA SLO-2 tools	LAB 11: Verify characteristic table of flipflops	LAB 14:Design of parallel Adder
3-9	SLO-2	Lab 2: Wave shaping circuits	Lab 5: Design of LPF, HPF, BPF and Band Reject Filters	Lab 8: Simulation experiments using EDA SLO-2 tools	LAB 11: Verify characteristic table of flipflops	LAB 14:Design of parallel Adder
6 10	SLO-1	Lab 2: Wave shaping circuits	Lab 5: Design of LPF, HPF, BPF and Band Reject Filters	Lab 8: Simulation experiments using EDA SLO-2 tools	LAB 11: Verify characteristic table of flipflops	LAB 14:Design of parallel Adder
3-10	SLO-2	Lab 2: Wave shaping circuits	Lab 5: Design of LPF, HPF, BPF and Band Reject Filters	Lab 8: Simulation experiments using EDA SLO-2 tools	LAB 11: Verify characteristic table of flipflops	LAB 14:Design of parallel Adder
6 11	SLO-1	Log and Antilog Amplifiers	Voltage Regulators: Basics of Voltage Regulator	Successive Approximation ADC	Code converters	Design of combinational circuits using PLD's
3-11	SLO-2	Analog voltage multiplier circuit and its applications	Specifications and characteristic parameters	Solving problems	Magnitude comparators	Design of combinational circuits using PLD's
C 12	SLO-1	Operational Trans-Conductance Amplifier (OTA)	Linear Voltage Regulators using Op-amp	Dual Slope ADC	Applications	RAM Memory decoding
5-12	SLO-2	Comparators : operation	IC Regulators (78xx, 79xx, LM 317, LM 337, 723),	Flash Type ADC	Parity generators (Odd parity)	ROM
	SLO-1	Comparators applications	Switching Regulators -operation	Solving problems on Flash Type ADC	Parity generators (Even parity)	Programmable Array Logic (PAL)
S-13	SLO-2	Sample and Hold circuit.	Types	Monolithic ADC	Implementation of combinational logic by standard IC's.	Programmable Array Logic (PAL)
6 14	SLO-1	Lab 3: Waveform generators: using opamp & 555 Timer	Lab 6: R-2R ladder DAC	Lab 9: Simulation experiments using EDA SLO-2 tools	LAB 12: Construct and verify 4-bit ripple counter, Mod-10/Mod-12 ripple counters	LAB 15: Design of subractor
3-14	SLO-2	Lab 3: Waveform generators: using opamp & 555 Timer	Lab 6: R-2R ladder DAC	Lab 9: Simulation experiments using EDA SLO-2 tools	LAB 12: Construct and verify 4-bit ripple counter, Mod-10/Mod-12 ripple counters	LAB 15: Design of subractor
	SLO-1	Lab 3: Waveform generators: using opamp & 555 Timer	Lab 6: R-2R ladder DAC	Lab 9: Simulation experiments using EDA SLO-2 tools	LAB 12: Construct and verify 4-bit ripple counter, Mod-10/Mod-12 ripple counters	LAB 15: Design of subractor
S-15	SLO-2	Lab 3: Waveform generators: using opamp & 555 Timer	Lab 6: R-2R ladder DAC	Lab 9: Simulation experiments using EDA SLO-2 tools	LAB 12: Construct and verify 4-bit ripple counter, Mod-10/Mod-12 ripple counters	LAB 15: Design of subractor

 Learning
 1. Morris Mano M, Michael D. Ciletti, Digital Design with an Introduction to the Verilog HDL, 5th ed., Pearson Education, 2014
 4. Roy Choudhury, Shail Jain, Linear Integrated Circuits, 4th ed., New Age International Publishers, 2014

 Resources
 2. Charles H Roth (Jr), Larry L. Kinney, Fundamentals of Logic Design, 5th ed., Cengage Learning India Edition, 2010
 4. Roy Choudhury, Shail Jain, Linear Integrated Circuits, 4th ed., New Age International Publishers, 2014

 S. Charles H Roth (Jr), Larry L. Kinney, Fundamentals of Logic Design, 5th ed., Cengage Learning India Edition, 2010
 9. Franco, Design with operational amplifier and analog integrated circuits, McGraw Hill, 1997

 S. Thomas L. Floyd, Digital Fundamentals, 10th ed., Pearson Education, 2013
 9. Franco, Design with operational amplifier and analog integrated circuits, McGraw Hill, 1997

Learning Asse	earning Assessment												
	Plaam'a			Conti	inuous Learning Asse	essment (50% weigl	htage)				Final Examination (50% weightage)		
	DIUUIII S Level of Thinking	CLA –	1 (10%)	CLA – 2 (15%)		CLA –	3 (15%)	CLA – 4	! (10%)#				
	Lever of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice		
Loval 1	Remember	20 %	20%	15 %	15%	15 %	15%	15 %	15%	15 %	15%		
Lever	Understand	20 78	2070	15 78	1570	15 78	1576	15 70	1576	15 78	1378		
Loval 2	Apply	20 %	20%	20.%	20%	20.%	20%	20 %	20%	20 %	20%		
Leverz	Analyze	20 78	2070	20 70	2070	20 78	2070	20 78	2070	20 78	2078		
Loval 3	Evaluate	10 %	10%	15 %	15%	15 %	15%	15 %	15%	15 %	15%		
Levers	Create	10 78	1070	15 76	1570	15 76	1576	10 70	1570	15 76	1378		
	Total	10	0 %	10	0 %	100 %		100) %	100 %			

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

SLO – Session Learning Outcome

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldives	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1. Mr.P. Muthu, SRMIST

Course Coo	le	18BMC206J	Cours	se Name	BIOMATERIA	ALS- TISSUE II	NTERAC	ΓΙΟΝ					Cou	ırse Ca	tegory	С			Profes	sional C	ore	_	L	Т	P	С
																							3	0	2	4
Pre-requisite	e Courses		Ν	Nil	Co-requisite Courses				Nil						Progre Cour	essive rses						Nil				
Course Offer	ing Departr	nent			BME		Data Bo	ook / C	odes/S	tandaro	ds									Nil			·		·	
Course Learni	ing Rational	e (CLR):	T k	To study the learners to acquire biomaterials and various biomat	knowledge to the basic pro terials used in biomedical a	operties of pplications.		I	Learnin	g							Progra	m Lear	ning O	utcome	s (PLO)					
CLR-1 :	Attain the	knowledge on basics	propertie	es of biomaterials				1	2	3		1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Study the	phenomena various I	metals us	sed in implant applications			_																		I	
CLR-3 :	Acquire kn	owledge importance	of ceram	nics and polymer used biomedic	cal diagnostics										÷			lity							I	
CLR-4 :	Familiarize	e with biological syste	m, prosth	hetic and medical implants				Bloom)	icy (%)	ent (%)		ledge		nent	Researc	е		stainabi		Work		ance			I	
CLR-5 :	Obtain the	concept of different t	ypes bior	materials applied in-vitro and in-	-vivo biomedical implant ap	plication		ıking (oficier	tainme		Know	alysis	velopi	sign, I	Usag	ulture	& Su		Team	ion	& Fina	arning		I	
CLR-6 :	Have an G	ain the knowledge at	bout biom	naterials used in various biomed	lical implant application			of Thir	ted Pr	ted Att		ering	m Ana	ı & De	is, De	n Tool	y & Cl	nment		ual &	unicat	t Mgt.	ng Le		5	e
Course Learr	ning Outcor	mes (CLO):	A	At the end of this course, learne	ers will be able to:			-evel o	Expect	Expect		Engine	Proble	Jesign	Analys	Moderi	Society	Enviro	Ethics	ndivid	Comm	Project		- OSc	- OSc	- OSc
CLO-1 :	Understan	d the basic principle a	and prope	erties of biomaterials				1, 2	80%	70%		L				L	07			_	Ŭ	H	L			M
CLO-2 :	Analyze va	arious types of metals	s used in i	implant applications.				2	80%	70%		L				М							М			М
CLO-3 :	Explain the	e process of importan	ce of cera	ramics and polymer used biome	dical diagnostics			2	80%	70%		L				М			М				L			М
CLO-4 :	Select app	propriate class of poly	mers usir	ng knowledge of, prosthetic and	l medical implants.			3	80%	70%	1	М											L	М	М	
CLO-5 :	Understan	d the concepts differe	ent types	biomaterials applied in-vitro and	d in-vivo biomedical implan	t application.		3	80%	70%	1	М											М	М	М	
CLO-6 :	Apply the various biomaterials used in implants and artificial organs					3	80%	70%		М		М	Н				М						М	М		

		Introduction to biomaterials and its properties	Metallic and Ceramics implants materials	Polymeric Implant materials	Soft and Hard Tissue Replacements	Biomaterials in Tissue interaction
Duratio	n (hour)	9	9	9	9	9
6.4	SLO-1	Introduction to Biomaterials	Metallic implant materials	Polymer Materials: Synthetic polymer	Sutures, skin, Tapes, and Adhesives	Scaffolds for tissue engineering
3-1	SLO-2	Performance of biomaterials	Stainless steel, Co alloy properties and application	Polymers in biomedical use	Maxillofacial implants	Classes of potential scaffold materials
6.2	SLO-1	Characterization of biomaterials	T i based alloys properties and application	Polyethylene and polypropylene	Cardiovascular Grafts and Stents.	The criteria for an ideal scaffold
3-2	SLO-2	Mechanical properties	Dental metals: Dental Amalgam, Gold	Perfluorinted polymers	Heart Valve Implants.	Polymer scaffolds
	SLO-1	Stress–Strain Behavior	Shape memory alloys:	Acrylic polymers and Hydrogel		Polymer scaffolds applications
S-3	SLO-2	Mechanical Failure	Application of Nickel titanium materials	Polyurethane	Hard Tissue replacement: Wires, Pins, and Screws	Bioactive ceramic scaffolds
64	SLO-1	Lab1 Study of metallurgical Microscope	Lab 4 Preparation and characterization of Hydroxyapatite	Lab7 Physical Characterization of Coated/Uncoated Surfaces Contact Angle measurement polycaprolactone (PCL).	Lab 10 Chemical Characterization of modified/unmodified surfaces(PVA)	Lab 13 Preparation and characterization of Poly (2-hydroxyethyl methacrylate) hydrogels
S-4 SLO-2 Lab1 Specimen preparation metals/alloys B1 Hand Polishing		Lab1 Specimen preparation for identification of metals/alloys B1 Hand Polishing	Lab 4 Preparation and characterization of Hydroxyapatite	Lab7 Physical Characterization of Coated/Uncoated Surfaces Contact Angle measurement polycaprolactone (PCL).	Lab 10 Chemical Characterization of modified/unmodified surfaces(PVA)	Lab 13 Preparation and characterization of Poly (2-hydroxyethyl methacrylate) hydrogels

		B2 Etching				
	SLO-1	Lab1 Study of metallurgical Microscope	Lab 4 Preparation and characterization of Hydroxyapatite	Lab7 Physical Characterization of Coated/Uncoated Surfaces Contact Angle measurement polycaprolactone (PCL).	Lab 10 Chemical Characterization of modified/unmodified surfaces(PVA)	Lab 13 Preparation and characterization of Poly (2-hydroxyethyl methacrylate) hydrogels
S-5	SLO-2	Lab1 Specimen preparation for identification of metals/alloys B1 Hand Polishing B2 Etching	Lab 4 Preparation and characterization of Hydroxyapatite	Lab7 Physical Characterization of Coated/Uncoated Surfaces Contact Angle measurement polycaprolactone (PCL).	Lab 10 Chemical Characterization of modified/unmodified surfaces(PVA)	Lab 13 Preparation and characterization of Poly (2-hydroxyethyl methacrylate) hydrogels
S-6	SLO-1	Static failure	Other metallic materials and properties ,Applications	Polyamides	Lower Extremity Implants: Hip Joint Replacements	Bioactive ceramic scaffolds and its applications
	SLO-2	Dynamic failure.	Other metallic materials and properties ,Applications	Biodegradable synthetic polymer	Knee Joint Replacements	Substrate Scaffold Materials
S-7	SLO-1	Friction and wear failure	New generation of bimetallic materials: Properties and application	Silicone rubber	Introduction to Kidney implant	A guide to basic cell culture and applications in biomaterials and tissue engineering
0-1	SLO-2	viscoelastic properties	Corrosion metallic implants: Electrochemical Aspects	Plasma polymerization and Polymer sterilization	Artificial Lung implant	sterilization of scaffolds, Sterilization methods
	SLO-1	Thermal Properties	Structure and properties of ceramic materials	Composite materials: Structure	Liver implant,	Cell culture protocols
S-8	SLO-2	Surface properties: Contact angle	Impact of fabrication on microstructure and properties :Alumina and its properties	Mechanics of composite and application of composite materials	Artificial Pancreas	Basic techniques for assessment of cell viability
	SLO-1	Lab2 Determination of hardness using Micro Vickers Tester	Lab 5 Preparation and characterization of titanium oxide	Lab8 Physical Characterization of Coated/Uncoated Surfaces Contact Angle measurement poly lactic acid (PLA).	Lab 11 Chemical Characterization of modified/unmodified any biodegradable polymers	Lab 14 Preparation and characterization of any ceramics
5-9	SLO-2	Lab2 Determination of hardness using Micro Vickers Tester	Lab 5 Preparation and characterization of titanium oxide	Lab 8 Physical Characterization of Coated/Uncoated Surfaces Contact Angle measurement poly lactic acid (PLA)	Lab 11 Chemical Characterization of modified/unmodified any biodegradable polymers	Lab 14 Preparation and characterization of any ceramics
S 10	SLO-1	Lab2 Determination of hardness using Micro Vickers Tester	Lab 5 Preparation and characterization of titanium oxide	Lab 8 Physical Characterization of Coated/Uncoated Surfaces Contact Angle measurement poly lactic acid (PLA).	Lab 11 Chemical Characterization of modified/unmodified any biodegradable polymers	Lab 14 Preparation and characterization of any ceramics
5-10	SLO-2	Lab2 Determination of hardness using Micro Vickers Tester	Lab 5 Preparation and characterization of titanium oxide	Lab 8 Physical Characterization of Coated/Uncoated Surfaces Contact Angle measurement poly lactic acid (PLA)	Lab 11 Chemical Characterization of modified/unmodified any biodegradable polymers	Lab14 Preparation and characterization of any ceramics
C 44	SLO-1	Ceramics and Glasses and Polymers and Elastomers	Zirconia and its properties	Porous Implants materials	Optical implants Contact lenses	maintenance of cells in vitro, cryopreservation
5-11	SLO-2	Adhesion, Problem for surface properties	Calcium phosphate and its properties	Fibrous and Particulate Composites in Orthopedic Implants	Ear implant	Regeneration stimulated electrically
S-12	SLO-1	Electrical properties	Glass ceramics. Yitria ceramics and its properties	Design criteria for bio composites	Blood flow in artificial devices	Immunochemical techniques in tissue engineering and biomaterial science
	SLO-2	Piezoelectricity, Density of various materials	Other ceramics	Inflammation and wound healing	Artificial Nose	Basic immunological principles
S-13	SLO-1	Porosity of various materials	Hydroxyapatite ceramics and its properties	Normal wound healing	Regeneration and Potential Future Uses for Stem Cells	Common immunochemical techniques used in biomaterials
	SLO-2	Diffusion properties	Manufacture of Implants in ceramics	Body response to implants, Biocompatibility	Ethical consideration	Immunochemical applications in biomaterial science and tissue engineering research
S-14	SLO-1	Lab 3 Determination of coating thickness using Image analyzer	Lab 6 study the corrosion behaviour of coated and uncoated substrate	Lab 9 preparation of simulated body fluid solution	Lab 12 In-vitro Study in any metallic medical implants	Lab 15 Model Exam
	SLO-2	LAB 3 Determination of coating thickness using Image analyzer	Lab 6 study the corrosion behaviour of coated and uncoated substrate	Lab 9 preparation of simulated body fluid solution	Lab 12 In-vitro Study in any metallic medical implants	Lab 15 Model Exam
Q 45	SLO-1	Lab 3 Determination of coating thickness using Image analyzer	Lab 6 study the corrosion behaviour of coated and uncoated substrate	Lab 9 preparation of simulated body fluid solution	Lab 12 In-vitro Study in any metallic medical implants	Lab 15 Model Exam
3-13	SLO-2	Lab 3 Determination of coating thickness using Image analyzer	Lab 6 study the corrosion behaviour of coated and uncoated substrate	Lab 9 preparation of simulated body fluid solution	Lab 12 In-vitro Study in any metallic medical implants	Lab 15 Model Exam

	1.	Joon park, R.S Lakes, "Biomaterials An Introduction "Springer, 2007
Learning Resources	2.	Sujata V. Bhat "Biomaterials" springer 2002
Resources	3.	Larry L. Hench and Julian R. Jones, Biomaterials, artificial organs and tissue engineering, CRC Press 2010

Learning Asse	Learning Assessment												
	Bloom's Continuous Learning Assessment (50% weightage)												
	DIU0IIIS	CLA –	1 (10%)	CLA –	2 (15%)	CLA –	3 (15%)	CLA – 4	(10%)#		n (50% weightage)		
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice		
Lovel 1	Remember	10 %		10.9/		10.0/		20.0/		200/			
Level I	Understand	40 %	-	40 %	-	40 %	-	30 %	-	3076	-		
Lovel 2	Apply	10.0/		10.9/		10.0/		10.0/		100/			
Level Z	Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40 %	-		
Lovel 2	Evaluate	20.0/		20.0/		20.0/		20.0/		200/			
Level 5	Create	20 %	-	20 %	-	20 %	-	30 %	-	3076	-		
	Total	10	0 %	10	0 %	10	0 %	100	0 %	10	0 %		

Course Designers		
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Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldives	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1., Dr S.Gnanavel, SRMIST

			•													Professional Core			Р	С			
Course Cod	e 1	18BMC301J	Course Name		MEDICAL INSTRUM	ENTATION				Cou	urse Ca	tegory	С			Profess	sional Co	ore		3	0	2	4
Pre-requisite	Courses	Basic Electronic D	evices and Circuits Circuits	, Linear Integrated	Co-requisite Courses		Ni					Progres Cours	ssive ses						Nil				
Course Offerin	ng Departm	ent		Biome	edical Engineering	Data Book	/ Codes	Standards									Nil						
							-	-															
Course Learn	ing Rational	le (CLR):	The purpo	se of learning this co	urse is to:		Learr	ing						Program	n Learr	ning Ou	utcomes	s (PLO)					
CLR-1 :	Understand	the basic function o	f physiological sys	em and basic instru	ment for picking up biological signals	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Analyze van	ious biological signa	al acquired from ph	vsiological system us	sing various instruments		y	t											Ice				
CLR-3 :	Get an idea	about various blood	pressure and blo	od flow measuremer	t techniques		enc	nen		í		-	age	d)			۶		nar	gr			
CLR-4 :	Understand	various technique u	ised for measurem	ent in the respiratory	system	kinç	fici	ainr		ysi		sign	Usi	ture	∞ŏ		ear	ы	Ξ	mi			
CLR-5 :	Identify the	various instruments	used for the therap	peutic and patient sa	fety	hin	P _G	Atta	و م	nal	ent	Des	0	G	iii at		х Т	cati	Jt. 8	Lee		l	
CLR-6 :	Understandi	ing the overall bioele	ectronics instrumer	ts used for physiolog	gical measurement) t	eq	be	erir edg	ح ۲	% md	is, l	Ĕ	~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~	ab de		nal	nii	Ň	bu	~	5	e
							ect	ect	ine	olei	elo elo	llys	den	iet.	tai	cs	μż +	E	ect	Lo		ċ	-
Course Learni	ing Outcom	es (CLO):	At the end	of this course, learn	ers will be able to:	(Bic	EXD (%)	(%)	Kn c	5 P 2	Des	Ana Res	Mo	Soc	Sus	Ethi	Vol	Ğ	°.	Life	PS(PS(PS(
CLO-1 :	Describe the	e function of physiol	ogical system and	basic man instrumer	t system used for analyzes	1, 2	80%	70%	М													-	
CLO-2 :	Identify the	various biological sig	gnal and its abnorn	nalities .Applying pro	cedure to obtain biological signal	2	80%	70%	М														
CLO-3 :	Apply the bl	ood pressure and flo	ow measurement te	echnique		2	80%	70%			М	1	М			M					L		
CLO-4 :	Analyze the	various technique u	ised for measurem	ent of respiratory sys	tem	3	80%	70%				I	М										
CLO-5 :	Apply the v	arious instrument us	sed for the emerge	ncy therapeutic app	ication and patient safety	3	80%	70%	М												М		L
CLO-6 :	Outline the j	iob opportunities in l	biomedical device i	n India		3	80%	70%	М														

		Introduction to Bioinstrumentation system	Biosignal acquisition from physiological system	Blood Pressure and blood flow measurement	Measurements in the Respiratory system	Biomedical instrument for therapeutic and patient safety
Duration	n (hour)	15	15	15	15	15
S-1	SLO-1	Physiological systems of the human body	Cardiovascular system: Basic anatomy and physiology of heart	Measurement of blood pressure: indirect Methods	Introduction of respiratory system	Need for cardiac pacemaker
	SLO-2	Biometrics	Electrophysiology of the Heart	Measurement of blood pressure: indirect Methods	Gas exchange and distribution	External pacemaker
S-2	SLO-1	Introduction to the Man-Instrument system	Electrocardiography waveform and its characteristics	Measurement of blood pressure: Direct methods	Measurement of Respiratory volumes and capacities	Implantable pacemaker
	SLO-2	Components of Man-Instrument system	ECG lead configurations	Measurement of blood pressure: Direct methods	Spirometry	Implantable pacemaker
S-3	SLO-1	Problem encountered in measuring in a living system	12 lead ECG machine circuit	Blood flow measuring techniques: electromagnetic blood flow meter, Ultrasonic blood flow meter	Spirometry	Recent developments in Implantable pacemaker
	SLO-2	Intelligent medical instrumentation system	Various Arrhythmias occurring in ECG signal	NMR blood flow meter, Laser Doppler blood flow meter	Pneumotachometers: different types	Pacing system analyzer
64	SLO-1	Lab1: Study of block diagram of man instrument system	Lab4: Real time ECG recording	Lab 7: Measurement of blood flow	Lab 10: Pulmonary analysis using spirometer	Lab 13: Study of pacemakers
3-4	SLO-2	Lab1: Study of block diagram of man instrument system	Lab4: Real time ECG recording	Lab 7: Measurement of blood flow	Lab 10: Pulmonary analysis using spirometer	Lab 13: Study of pacemakers
0.5	SLO-1	Lab1: Study of block diagram of man instrument system	Lab4: Real time ECG recording	Lab 7: Measurement of blood flow	Lab 10: Pulmonary analysis using spirometer	Lab 13: Study of pacemakers
5-9	SLO-2	Lab1: Study of block diagram of man instrument system	Lab4: Real time ECG recording	Lab 7: Measurement of blood flow	Lab 10: Pulmonary analysis using spirometer	Lab 13: Study of pacemakers
S-6	SLO-1	Resting and action potential	Introduction to basic Anatomy and function of brain	Cardiac output measuring techniques: dye dilution method	Pneumotachometers: different types	DC Defibrillator
	SLO-2	Propagation of Action potential	Bioelectric potential from the brain	Thermal dilution method	Pneumotachometers: different types	DC Defibrillator
6.7	SLO-1	Nernst equation, Goldman equation, Hodgkin- Huxley model	10-20 system of placement of electrode	Cardiac output from aortic pressure waveform	Respiratory gas analyzers: Infrared gas analyzer	Types of implantable Defibrillators
3-7	SLO-2	Sources of Bioelectric potentials	EEG Machine block diagram description	Impedance technique	Oxygen analyzers	Pacer-Cardioverter-defibrillator
S-8	SLO-1	Bio potential measurement: electrode electrolyte	Computerized analysis of EEG	Ultrasound method	Thermal conductivity analyser	Defibrillator analysers

		interface,				
	SLO-2	polarizable and non-polarizable electrodes, The electrode skin interface and motion artifact	Magnetoencephalography	Bioreactance method, CO2 rebreathing method	Nitrogen gas analyzer	Left ventricular assist device
5.0	SLO-1	Lab2: Study of sources of Biopotentials	Lab5: Real time EEG monitoring	Lab 8: Measurement of cardiac output	Lab 11: Study of pneumotachometers	Lab 14: Study of defibrillators
3-9	SLO-2	Lab2: Study of sources of Biopotentials	Lab5: Real time EEG monitoring	Lab 8: Measurement of cardiac output	Lab 11: Study of pneumotachometers	Lab 14: Study of defibrillators
S-10	SLO-1	Lab2: Study of sources of Biopotentials	Lab5: Real time EEG monitoring	Lab 8: Measurement of cardiac output	Lab 11: Study of pneumotachometers	Lab 14: Study of defibrillators
	SLO-2	Lab2: Study of sources of Biopotentials	Lab5: Real time EEG monitoring	Lab 8: Measurement of cardiac output	Lab 11: Study of pneumotachometers	Lab 14: Study of defibrillators
S-11	SLO-1	Biopotential electrodes:Surface,and Micro electrodes	Electromyography(EMG):Basics of EMG	Heart rate measurement	Measurement of respiration rate: displacement method,	Electric shock hazards
	SLO-2	Biopotential electrodes:Needle electrodes	Recording of EMG	Heart rate measurement	Thermistor method,	Microshock and Macroshock
S-12	SLO-1	Biochemical electrodes: pH	Electrooculography(EOG):Origin and measurement	Invitro-oximetry, invivo-oximetry	Impedance pneumography	Threshold of perception and Leakage current
	SLO-2	Biochemical electrodes: pO2, pCO2	Electroretinography(ERG): Origin and measurement	Ear oximeter	CO ₂ method	Safety codes for electromedical equipment
S-13	SLO-1	Transcutaneous electrodes,	Phonocardiography(PCG):Origin of heartsound, Measurement of PCG	Pulse oximeter	Apnea detector	Electrical safety analyzer
	SLO-2	lon sensitive field effect Transistor	Biofeedback instrumentation	Skin reflectance oximeter, Intravascular oximeter	Bedside and Central Monitoring system	Testing of biomedical equipments
S-14	SL0-1	Lab 3: Study of biopotential electrodes	Lab 6: Real time EMG monitoring	Lab 9: Measurement of heart rate	Lab12: Measurement of respiration rate	Lab15:Model exam
	SLO-2	Lab 3: Study of biopotential electrodes	Lab 6: Real time EMG monitoring	Lab 9: Measurement of heart rate	Lab12: Measurement of respiration rate	Lab15:Model exam
S-15	SLO-1	Lab 3: Study of biopotential electrodes	Lab 6: Real time EMG monitoring	Lab 9: Measurement of heart rate	Lab12: Measurement of respiration rate	Lab15:Model exam
	SLO-2	Lab 3: Study of biopotential electrodes	Lab 6: Real time EMG monitoring	Lab 9: Measurement of heart rate	Lab12: Measurement of respiration rate	Lab15:Model exam

 Learning
 1.R.S.Khandpur, 'Handbook of Biomedical instrumentation', Tata McGraw Hill Publishing Co Ltd., 3rd edition, 2014.

 Learning
 2. John G.Webster, "Medical Instrumentation application and design", Wiley India Pvt Ltd, India, 4thedition, 2015

 Resources
 3. Joseph J Carr and John M Brown, "Introduction to biomedical equipment technology", Pearson Education, New Delhi, 4th edition, 2004.

 Leslie Cromwell, Fred J.Weibell, Erich A. Pfeiffer, "Bio-Medical Instrumentation and measurements", Pearson Education, PHI Learning Private limited, India, 2nd edition, 2007.
 Hodgkin, A. L.; Huxley, A. F. (1952),"A quantitative description of membrane current and its application to conduction and excitation in nerve", The Journal of Physiology 117 (4): 500–544.

Learning Assessmer	earning Assessment												
	5			Сс	ontinuous Learning Ass	essment (50% weightag	ge)			Final Examination	(50%) woightago)		
	Bloom's Level of Thinking	CLA –	1 (10%)	CLA – 2 (15%)		CLA –	3 (15%)	CLA – 4	(10%)#				
	Loroi ol rimining	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice		
Lovel 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%		
	Understand	2078	2070	1576	1576	15%	1570	1576	1576	1376	1576		
Loval 2	Apply	200/	20%	200/	200/	20%	200/	200/	200/	200/	20%		
Level 2	Analyze	20%	20%	20%	20%	20%	20%	2078	20%	2076	2078		
	Evaluate												
Level 3	Create	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%		
	Total 100 % 100 % 100 % -												
# CLA –	4 can be from any comb	ination of these: Assig	nments, Seminars, Tech	n Talks, Mini-Projects, C	Case-Studies, Self-Stud	y, MOOCs, Certification	ns, Conf. Paper etc.,			μ			

Course Designers

Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldives	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1. Dr.A.K.Jayanthy, SRMIST

0	18BMC302T	0	_			20		Co	ourse						D(!1	0					L	Т	Ρ	С
Course Cod	e	Course Name	e		BIOMECHANIC	.5		Cat	egory	C	,				Protess	ionai	Core					3	0	0	3
Pre-requi Course	site Nil			Co-requisite Courses	Nil			Pro	gressi ourses	ve s	iil														
Course Offer	ring Department	Biomeo	dical Engineering		Data Book / Codes/Standards Nil																				
Course Lear	Course Learning Rationale (CLR): The purpose of learning this course is to:									g					Pro	gram	Learni	ng Ou	tcome	es (PL)	0)				
CLR-1 :	Understand the fundamen	tals of kinetic a	nd kinematic conce	pts of human motion											13	14	15								
CLR-2 : Get an idea about the skeletal and muscular movements							Ê	()	()																
CLR-3:	Get an idea about the Fun	ctional anatomy	of the upper extre	mity				loor	y (%	nt (%		ade	lent						Vork		ЭС				
CLR-4:	Jet an idea about the Fun	ictional anatomy	/ of the lower extrements of t	mity				9 (B	enc	mer					age	Ð			2 E		inar	b			
	Onderstand the biomecha	the verieve fund	ill gall	ant abaractariation of w	nnar autramity and	lower extremity		ki	offici	ain			velo la	sigr	Us	ltr	∞ _		Геа	ы.	⊥ ∞	ani			
CLR-0:		une vanous iuno	lional and moverne		pper extremity and	lower extremity		'n	P	Att			De	De	00	G	ent		°≈	cat	gt.	Le			
								- Le	cted	cted			2 2 2	sis, arch	E	ty &	nm inat		dual	unu	tM	ong	-	2	β
Course Lear	ning Outcomes (CLO):	At the e	nd of this course, le	earners will be able to:				-evel	Expec	Expec			Desig	Analy	Mode	Socie	Envire	Ethics	ndivi	Comn	^o roje(_ife L	. OSc	OSc	. OSc
CLO-1 :	Apply the common kinema	atic and kinetic	concepts to various	s human motion				1, 2	80	70		1 M	Ē	-	-	-	-	-	-	-	-	M	M	-	-
CLO-2 :	dentify the mechanical pro	operties of bone	and muscle tissue	s				1, 2	80	70		1 L	-	-	-	-	-	L L					-	-	
CLO-3 :	Analyze the functional and	l movement cha	aracteristics of uppe	er extremity bones and	l joints			1,2	80	70		· M	-	L	-	-	-	-	-	-	-	L	-		
CLO-4 :	Analyze the functional and	I movement cha	aracteristics of lowe	er extremity bones and	joints			2	80	70		1 M	L	М	М	-	-	-	-	-	-	L	-	L	М
CLO-5 :	Analyze the biomechanics	of spine and h	uman locomotion					2,3	80	70		· -	М	М	М	-	-	-	-	-	-	L	-	L	Μ
CLO-6 :	CLO-6 : Outline the factors involved in analyzing the performance of lower and upper extremity bones and joints							3	80	70		· M	-	М	-	-	-	-	-	-	-	-	-	L	Μ

Duration (hour)		Kinematic and Kinetic concepts of human motion	Skeletal and muscular movements	Functional Anatomy for the upper extremity	Functional Anatomy for the lower extremity	Biomechanics of spine and gait
		9	9	9	9	9
Q 1	SLO-1	Forms of Motion	Mechanical properties of body tissues-Structural Analysis	Shoulder complex- Functional Characteristics of the Joints of the Shoulder	Pelvis and Hip Complex	Vertebral column
0-1	SLO-2	Standard Reference Terminology	Mechanical properties of body tissues-Structural Analysis	Shoulder complex- Functional Characteristics of the Joints of the Shoulder	Pelvis and Hip Complex	Vertebral column
6.2	SLO-1	Joint Movement Terminology	Biomechanical Characteristics of Bone-Bone tissue function	Movement Characteristics of the Shoulder Complex	Structure of Hip joint	Structural and movement characteristics of spine
3-2	SLO-2	Joint Movement Terminology	Composition of bone tissue	Movement Characteristics of the Shoulder Complex	Muscular actions of Hip	Structural and movement characteristics of spine
63	SLO-1	Qualitative analysis of human movement	Bone Modeling and Remodeling	Loads on the shoulder	Loads on the hip	Movements of spine
3-3	SLO-2	Qualitative analysis of human movement	Bone Modeling and Remodeling	Loads on the shoulder	Loads on the hip	Movements of spine
6.4	SLO-1	Tools for measuring Kinematic quantities	Mechanical properties of bone-Strength and stiffness of bone	Elbow and Radioulnar joints- Functional Characteristics of the Joints of the Elbow	Structure of Knee joint	Posture and spinal stabilization
5-4	SLO-2	Tools for measuring Kinematic quantities	Mechanical properties of bone-Strength and stiffness of bone	Elbow and Radioulnar joints- Functional Characteristics of the Joints of the Elbow	Structure of Knee joint	Posture and spinal stabilization
с г	SLO-1	Basic concepts related to kinetics	Maxwell and voight model	Movement Characteristics of the Elbow	Movement Characteristics of the Knee	Loads on spine
3-0	SLO-2	Basic concepts related to kinetics	Maxwell and voight model	Movement Characteristics of the Elbow	Movement Characteristics of the Knee	Common injuries of spine
S-6	SLO-1	Mechanical loads on the human body	Loads applied on bone	Loads on the elbow	Loads on the knee	Gait cycle

	SLO-2	Mechanical loads on the human body	Stress fractures	Loads on the elbow	Loads on the Knee	Gait cycle
6.7	SLO-1	Effects of loading	Stress-Strain Relationship	Functional Characteristics of the joints Of the wrist and hand	Ankle and foot	Contribution of lower extremity musculature to movements
5-7	SLO-2	Effects of loading	Soft tissue mechanics	Functional Characteristics of the joints Of the wrist and hand	Ankle and foot	Contribution of lower extremity musculature to movements
0.0	SLO-1	Tools for Measuring Kinetic quantities	Muscle tissue Properties	Combined movements of wrist and hand	Combined movements of Ankle and foot	Forces acting on the joints in the lower extremity
5-0	SLO-2	Tools for Measuring Kinetic quantities	Muscle tissue Properties	Combined movements of wrist and hand	Combined movements of Ankle and foot	Forces acting on the joints in the lower extremity
0.0	SLO-1	Vector Composition	Force generation in the muscle	Common injuries of upper extremity	Common injuries of lower extremity	Case study
5-9	SLO-2	Vector Resolution	Biomechanical Analysis of joints	Common injuries of upper extremity	Common injuries of lower extremity	Case study

Learning	1. Joseph Hamill & Kathleen M. Knutzen, "Biomechanical Basis of Human Movement", Lippincott Williams & Wilkins, a	3. Peter M. McGinnis, "Biomechanics of sports and exercise", Human kinetics, 3rd Edition, 2013.
Resources	Wolters Kluwer business, 3rd Edition, 2009	4.Fung Y C, Biomechanics: "Mechanical Properties of Living Tissues", Springer, 2 nd Edition, 1993.
	2. Susan J Hall, "Basic Biomechanics", Tata Mcgraw hill, 6t ^h Edition, 2012.	

Learning Assessmer	Learning Assessment													
	Ricom's Continuous Learning Assessment (50% weightage)													
	DIUUIII S	CLA –	1 (10%)	CLA –	2 (15%)	CLA –	3 (15%)	CLA – 4	l (10%)#		r (50 % weightage)			
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice			
Lovel 1	Remember	10.0/		10.0/		10 %		20.0/		200/				
Level	Understand	40 /0	-	40 %	-	40 %	-	30 %	-	30%	-			
	Apply	10.0/		10.0/		10.0/		10.0/		400/				
Level Z	Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-			
Lough 2	Evaluate	20.0/		20.0/		20.0/		20.0/		200/				
Level 5	Create	20 %	20 % -		-	20 %	-	30 %	-	30%	-			
	Total	10	0 %	10	0 %	10	0 %	10	0 %	10	0 %			

Course Designers											
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts									
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldives	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1. Dr. Ashokkumar D, SRMIST									

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Course Cod	e 18BMC303J	Course Name		BIOMEDICAL	SIGNAL PRO	CESSING				Co	ourse Ca	tegory	C			Profess	ional Co	ore		3	0	2	4
		1	1										1							I		I	
Pre-requisite	Courses	Nil		Co-requisite Courses			Nil					Progres Cours	ssive ses		Nil								
Course Offeri	ng Department		Biome	dical Engineering		Data Book	/ Codes/S	Standards									Nil						
									1 1														
Course Learn	ng Rationale (CLR):	The purpo	ose of learning this co	urse is to:			Learni	ng	Program Learning Outcomes (PLO)														
CLR-1 :	Understand the basic of signal	processing technic	ues			1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Apply the concept of IIR filter of	lesign				У	t											lce			1		
CLR-3 :	: Understand the concepts of FIR filter design and its application						Suc	Jen				_	ge				c		Jar	þ		1	ļ
CLR-4 :	Analyze the various signal proc	essing algorithms	in ECG.			king	ficie	ainn		ysie		ign	Use	ture	<u>مە</u>		ear	uc	Ξ	л.			
CLR-5 :	Gain knowledge in Heart rate v	ariability analysis				hin	Po	Atta	p	ual e	ent	Des		C	ility a		&Τ	catio	Jt. 8	Геа			
CLR-6 :	Analyze the speech signal and	other biosignals us	sing suitable signal pr	ocessing techniques		I I I I I I I I I I I I I I I I I I I	eq	eq	erir	ag ⊿ r	∞ ma	is, L	Ĕ	8	ab dar		lal	unic	Š	ß		2	e
	· · ·						ect	ect	ine .		elo elo	lys	derr	iety	tair	cs	ip X	m	ect	2	-	Ġ	ö
Course Learn	ng Outcomes (CLO):	At the end	d of this course, learne	ers will be able to:		Pe e	L X 🛞	dxi %	l lin,		Oes Oes	Ana Res	Mod	300	Sus	E.	Noi	Cor	0	life	Sc	SC	SC
CLO-1 :	Describe the DIT-FFT and DIF	FFT algorithm				1, 2	80%	70%	M														
CLO-2 :	Implement the IIF filter design i	n real time biosign	als			2	80%	70%	М													1	
CLO-3 :	Analyze the FIR fitler design ar	nd its application				2	80%	70%			М		М							i	М	1	L
CLO-4 :	Apply the various signal processing algorithms in analysis of ECG.					3	80%	70%					М										
CLO-5 :	O-5 : Analyze the signal processing methods used in HRV analysis					3	80%	70%	М												М		L
CLO-6 :	Apply the advanced techniques	s in various biosign	als.			3	80%	70%	М														

		Basics of Signal Processing	IIR Filter design	FIR Filter design and its application	Analysis of ECG	Advanced techniques in Biosignal processing
Duration	n (hour)	15	15	15	15	15
6.4	SLO-1	Sampling	IIR Filter-Introduction	FIR filter-advantages and disadvantages	P-Wave detection	Speech signal analysis-Cepstrum
5-1	SLO-2	Aliasing	Impulse invariant method	Characteristics	Estimation of R-R Interval	Analysis of complex cepstrum
S-2	SLO-1	FFT-Decimation in time radix-2 algorithm	Bilinear transformation method	Frequency method sampling method	QRS complex detection-Template subtraction method	Homomorphic filtering of speech signals
	SLO-2	Butterfly diagram	Problems	Type I and Type II	Template correlation method	Application
6.2	SLO-1	Implementation of DIT- FFT algorithm	Butterworth filter- magnitude response	FIR filter design using windowing techniques- Rectangular window	Pan Tompkins algorithm for QRS detection-block diagram	Spectral distortion using a warped frequency scale
3-3	SLO-2	Implementation of DIT -FFT algorithm	Chebyshev filter-Magnitude response	Filter design using Hamming window	Algorithm and waveforms	LPC and MFCC co-efficient
	SLO-1	Lab1: Basic signal operations	Lab4: Design of digital Butterworth IIR filter	Lab 7: FIR Filter using hamming windowing techniques	Lab 10: Analysis of ECG	Lab 13: Analysis of speech signals
5-4	SLO-2	Lab1: Basic signal operations	Lab4: Design of digital Butterworth IIR filter	Lab 7: FIR Filter using hamming windowing techniques	Lab 10: Analysis of ECG	Lab 13: Analysis of speech signals
	SLO-1	Lab1: Basic signal operations	Lab4: Design of digital Butterworth IIR filter	Lab 7: FIR Filter using hamming windowing techniques	Lab 10: Analysis of ECG	Lab 13: Analysis of speech signals
5-5	SLO-2	Lab1: Basic signal operations	Lab4: Design of digital Butterworth IIR filter	Lab 7: FIR Filter using hamming windowing techniques	Lab 10: Analysis of ECG	Lab 13: Analysis of speech signals
• •	SLO-1	FFT-Decimation in Frequency radix-2 algorithm	Design of butterworth filter using bilinear transformation technique	Filter design using Hanning window	Heart rate variability –Physiological origin	Synchronized averaging of PCG envelopes
5-0	SLO-2	Butterfly diagram	Design of butterworth filter using bilinear transformation technique	Filter design using Hanning window	Generation of HRV	Envelogram
6.7	SLO-1	Implementation of DIF- FFT algorithm	Design of butterworth filter using impulse invariant method	Magnitude response of hanning window	Clinical significance of HRV	Signal averaged ECG-Clinical significance
5-1	SLO-2	Implementation of DIF -FFT algorithm	Design of butterworth filter using impulse invariant method	Phase response of hanning window	Factors Influences on HRV	Advantages and disadvantage
c 0	SLO-1	Different types of bioelectric signals	Design of Chebyshev filter using bilinear transformation technique	Filter design using Blackman window	Time domain methods of HRV	Normal and Ectopic ECG beats classification
3-0	SLO-2	Characteristics	Design of Chebyshev filter using bilinear transformation technique	Filter design using Blackman window	Frequency domain Methods	Analysis of Exercise ECG
S-9	SLO-1	Lab2: DFT and FFT computations	Lab5: Design of digital Low pass Chebyshev IIR	Lab 8: FIR Filter using Hanning windowing	Lab 11: Analysis of Heart rate variability	Lab 14: Classification of Normal and abnormal

			filter	techniques		ECG
	SI 0-2	Lab2: DFT and FFT computations	Lab5: Design of digital Low pass Chebyshev IIR	Lab 8: FIR Filter using Hanning windowing	Lab 11: Analysis of Heart rate variability	Lab 14: Classification of Normal and abnormal
	310-2		filter	techniques		ECG
S-10	SI 0-1	Lab2: DFT and FFT computations	Lab5: Design of digital Low pass Chebyshev IIR	Lab 8: FIR Filter using Hanning windowing	Lab 11: Analysis of Heart rate variability	Lab 14: Classification of Normal and abnormal
5-10	310-1		filter	techniques		ECG
	SI 0-2	Lab2: DFT and FFT computations	Lab5: Design of digital Low pass Chebyshev IIR	Lab 8: FIR Filter using Hanning windowing	Lab 11: Analysis of Heart rate variability	Lab 14: Classification of Normal and abnormal
	010-2		filter	techniques		ECG
S-11	SI 0-1	Bio impedance signals	Design of Chebyshev filter using impulse invariant	Time domain filters -Moving averaging filters	Non-linear analysis of HRV	Adaptive segmentation of EEG signals –SEM
V -III	020-1		method			method
	SI 0-2	Characteristics	Design of Chebyshev filter using impulse invariant	Algorithm	Pit falls in understanding HRV	ACE distance method
	0101		method			
S-12	SLO-1	Bio acoustic signals	Frequency warping	Synchronized averaging filters	Adaptive filter –Introduction	Adaptive segmentation –procedure
	SLO-2	Characteristics	Prewarping effect	Algorithm	Adaptive noise canceller –block diagram	Adaptive segmentation –procedure
S-13	SLO-1	Bio mechanical signal	Frequency transformation-digital domain	Synchronized averaging filters	LMS adaptive filter algorithm	Spectral Analysis-Power spectral density
	SLO-2	Characteristics	Frequency transformation-digital domain	Algorithm	LMS adaptive filter algorithm	Cross Spectral density
S 14	SI 0 1	Lab 2: Penrecentation of biosignals	Lab 6: Design of digital high pass Chebyshev IIR	Lab 9: FIR Filter using blackman windowing	Lab12: Adaptive filtering techniques	Lab15: Spectral analysis of signals
3-14	310-1	Lab 5. Representation of biosignals	filter	techniques		Lab 15.5pectral analysis of signals
	81.0.2	Lab 3: Representation of biosignals	Lab 6: Design of digital high pass Chebyshev IIR	Lab 9: FIR Filter using blackman windowing	Lab12: Adaptive filtering techniques	Lab15:Spectral analysis of signals
	310-2		filter	techniques		
C 15	SI 0 1	Lab 3: Representation of biosignals	Lab 6: Design of digital high pass Chebyshev IIR	Lab 9: FIR Filter using blackman windowing	Lab12: Adaptive filtering techniques	Lab15:Spectral analysis of signals
3-15	3LU-1		filter	techniques		
	81.0.2	Lab 3: Representation of biosignals	Lab 6: Design of digital high pass Chebyshev IIR	Lab 9: FIR Filter using blackman windowing	Lab12: Adaptive filtering techniques	Lab15:Spectral analysis of signals
	310-2		filter	techniques		
		1. Ramesh Babu," Digital signal process	sing" Laxmi Publications, 2005.			

Learning Resources	1. 2.	Ramesh Babu," Digital signal processing" Laxmi Publications, 2005. Rangaraj.M.Rangayyan, "Biomedical signal processing ',Wiley-IEEE press, 2 nd edition,2015.	З.	Reddy D.C, "Biomedical signal processing: Principles and Techniques", Tata McGraw-Hill, New Delhi, 2 nd
Resources				

Learning Assessmer	earning Assessment													
	Disarda			C	ontinuous Learning Ass	essment (50% weightag	je)			Final Examination	(50% weightage)			
	Bloom s Level of Thinking	CLA –	CLA – 1 (10%)		CLA – 2 (15%)		3 (15%)	CLA – 4	l (10%)#		r (50 % weightage)			
	Lotor of thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice			
Lovel 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%			
Level I	Understand	20%	2076	1576	1570	1370	1370	1570	1570	1570	1570			
Lovel 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%			
Level 2	Analyze	20%	2076	2076	2076	2076	2076	2076	2070	20%	2070			
	Evaluate	100/	1001	150/	150/	1501		(5)	150/	1507	1501			
Level 3	Create	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%			
	Total	100	0 %	10	0 %	100) %	10) %		-			

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldives	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1. Dr.U.Snekhalatha, SRMIST

								-			_							L	Т	Р	С		
Course Co	ode	18BMC304J	Course Name	MICROCONTROLLER AND	D ITS APPLICA	TION IN N	MEDICINE	=		Co	urse Ca	egory	С	Professional Core 3			0	2	4				
										1		_											
Pre-requisi	te Courses		Nil	Co-requisite Courses	Nil Progressive Courses					Nil													
Course Offe	ering Departi	ment		Biomedical Engineering	Da	ta Book /	/ Codes/S	Standards									Nil					-	
																		(21.0)					
Course Lear	rning Ration	ale (CLR):	The purpo	se of learning this course is to:			Learnii	ng						Progra	m Leari	ning O	utcome	<u>(PLO) د</u>					
CLR-1 :	Understan	d the fundamental co	ncepts of 8086 mid	croprocessors		1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Explain the	e basic concepts of 8	051 microcontrolle	r			~												e				
CLR-3 :	Obtain knowledge on interfacing devices					_	enci	nen		ŝ		-	age				٤	.	nan	p		I	
CLR-4 :	Have an ir	nsight on Microcontrol	ller			king	ofici	ain		lysi		sign	Us	Iture	∞ _		ear	5	Ш	, ini		I	
CLR-5 :	Familiarize	e about ARM microco	ntroller			ui.	P _r	Att	<u>م</u>	na	ent	ő	0	S	ility		& 1	gati	jt.	- e		I	
CLR-6 :	Acquire kr	nowledge on applicati	ons of microproces	sor and microcontroller in biomedical domain.		of T	fed	ed	erir edg	R A E	% md	is, I	Ĕ	~× ∧	nm6 nab		ual	nii	Ĕ.	ĝ	~	2	e
						ono	ect	ect	vie We	ple	e gi	ilys ea	len	iet	irol	cs	kid	E	ect	<u>ا ک</u>	Ċ	, ,	ċ
Course Lear	rning Outco	mes (CLO):	At the end	of this course, learners will be able to:		(Blo	(%)	% Exp	Kno	Pro	Des	Ana Res	Mod	Soc	Env	Et	Wo	Ğ	Pro	Life	PSC	PSC	PS(
CLO-1 :	Describe t	he fundamental conce	epts of 8086 micro	processors		1, 2	80%	70%	М													1	
CLO-2 :	Implement	t the concepts of 805	1 microcontroller			2	80%	70%	М														
CLO-3 :	Analyze th	ne features of interfaci	ing devices			2	80%	70%			М		М								М		L
CLO-4 :	Apply the	concepts of RISC Pro	ocessor			3	80%	70%					М									1	
CLO-5 :	Develop programming skill					3	80%	70%	М												М	1	L
CLO-6 :	Program for Biomedical appplications					3	80%	70%	М														

		8086 Processor	8051 Microcontroller	Interfacing devices	ARM Microcontroller	Applications in Medicine
Duration	n (hour)	15	15	15	15	15
S 1	SLO-1	Evolution of Microprocessor	Introduction to Microcontroller	Introduction to 8251	Reduced Instruction Set Computer (RISC) Design Physiology	Mobile phone based bio signal recording
3-1	SLO-2	Evolution of Microprocessor	Difference between Microprocessor and Microprocessor	8251 : Architecture	Difference between RISC and Complex Instruction Set Computer (Processor	Mobile phone based bio signal recording
	SLO-1	signal description of 8086	signal description of 8051	8251 : Architecture	Major Design rules	Mobile phone based bio signal recording
S-2	SLO-2	signal description of 8086	signal description of 8051	8251: Processing Mode	Major Design rules	Design of pulse oximeter circuit using ARM microcontroller
S_3	SLO-1	Architecture	Architecture	Interfacing to external memory	ARM Design Physiology	Design of pulse oximeter circuit using ARM microcontroller
5-5	SLO-2	Architecture	Architecture	Interfacing to external memory	ARM core data flow model	Design of pulse oximeter circuit using ARM microcontroller
S-4	SLO-1	Lab1: 16 Bit addition	Lab4: 8 bit addition using 8051 microcontroller	Lab 7: Generate Sawtooth Waveform	Lab 10: Assembly language program to compute sum of n consecutive numbers and to find the factorial of the result	Lab 13: Mini Project
5-4	SLO-2	Lab1: 16 Bit addition	Lab4: 8 bit addition using 8051 microcontroller	Lab 7: Generate Sawtooth Waveform	Lab 10: Assembly language program to compute sum of n consecutive numbers and to find the factorial of the result	Lab 13: Mini Project
0	SLO-1	Lab1: Block transfer of data type	Lab4: 8 bit subtraction using 8051 microcontroller	Lab 7: Generate Triangular Waveform	Lab 10: Assembly language program to compute sum of n consecutive numbers and to find the factorial of the result	Lab 13: Mini Project
5-5	SLO-2	Lab1: Block transfer of data type	Lab4: 8 bit subtraction using 8051 microcontroller	Lab 7: Generate Triangular Waveform	Lab 10: Assembly language program to compute sum of n consecutive numbers and to find the factorial of the result	Lab 13: Mini Project
5.6	SLO-1	Addressing modes	Addressing modes	Timer interfacing	ARM core data flow model	Design of EOG based home appliances using PIC microcontroller
3-0	SLO-2	Addressing modes	Addressing modes	Timer interfacing	Processor Modes	Design of EOG based home appliances using PIC microcontroller
S.7	SLO-1	Minimum mode operation	Register set of 8051	Basic techniques for reading & writing from I/O port pins	Registers	Design of EOG based home appliances using PIC microcontroller
3-1	SLO-2	Minimum mode operation	Instruction set : Data transfer	Basic techniques for reading & writing from I/O port pins	ARM Instruction set	Analysis of EMG signal using microcontroller

	SLO-1	Maximum mode operation	Instruction set : Arithmetic, Logical	Interfacing 8051 to ADC	ARM Instruction set	Analysis of EMG signal using microcontroller
S-8	SLO-2	Maximum mode operation	Instruction set : String Manipulating Instructions, control transfer	Interfacing 8051 to ADC	ARM Instruction set	Analysis of EMG signal using microcontroller
50	SLO-1	Lab2: Sum of n numbers	Lab5: One and two complement of a number	Lab 8: Generate Sine Waveform	Lab 11: Assembly language program to compute factorial of a number and to compute the parity of the result	Lab 14: Mini Project
3-9	SLO-2	Lab2 Sum of n numbers	Lab5: One and two complement of a number	Lab 8: Generate Sine Waveform	Lab 11: Assembly language program to compute factorial of a number and to compute the parity of the result	Lab 14: Mini Project
S-10	SLO-1	Lab2: Sum of n numbers	Lab5: One and two complement of a number	Lab 8: Generate Square Waveform	Lab 11: Assembly language program to compute factorial of a number and to compute the parity of the result	Lab 14: Mini Project
	SLO-2	Lab2: Sum of n numbers	Lab5: One and two complement of a number	Lab 8: Generate Square Waveform	Lab 11: Assembly language program to compute factorial of a number and to compute the parity of the result	Lab 14: Mini Project
S-11	SLO-1	Instruction set : Data transfer	Special Function Registers	Stepper motor	Exceptions	Analysis of EEG signal using microcontroller
	SLO-2	Instruction set : Arithmetic, Logical	Special Function Registers	Stepper motor	Exceptions	Analysis of EEG signal using microcontroller
S-12	SLO-1	Instruction set : String Manipulating Instructions	Special Function Registers	Keyboard Interfacing	Thumb Instruction set	Analysis of EEG signal using microcontroller
	SLO-2	Instruction set : Control Transfer Instructions	8086 Interrupt	Keyboard Interfacing	Thumb Instruction set	Design of heart rate monitoring circuit using ARM microcontroller
S-13	SLO-1	8086 Interrupt	8086 Interrupt	Liquid crystal display (LCD)	Thumb Instruction set	Design of heart rate monitoring circuit using ARM microcontroller
	SLO-2	8086 Interrupt	Memory interfacing	Liquid crystal display (LCD)	Thumb Instruction set	Design of heart rate monitoring circuit using ARM microcontroller
S-14	SLO-1	Lab 3: Sorting even and odd numbers in an array	Lab 6: Fibonacci series	Lab 9: Stepper motor Interface	Lab12: Assembly language program to determine the bigger number of two given number	Lab 15: Mini Project
	SLO-2	Lab 3: Sorting even and odd numbers in an array	Lab 6: Fibonacci series	Lab 9: Stepper motor Interface	Lab12: Assembly language program to determine the bigger number of two given number	Lab 15: Mini Project
S-15	SLO-1 SLO-2	Lab 3: Sorting even and odd numbers in an array	Lab 6: Fibonacci series	Lab 9: Stepper motor Interface	Lab12: Assembly language program to determine the bigger number of two given number	Lab 15: Mini Project
Learning		1 A K Ray, K M Rhurchandi "Advanced Mic	ronrocessor and Perinherals" Tata McGraw Hill 3r	dedition 2013 3. And	rew N.Sloss,DonimicSymes, Chris Wright, "ARM Sys 7	stem Developer's Guide", Elsevier, 1st edition,

Resources

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 1.
 A.K.Ray, K.M.Bhurchandi, "Advanced Microprocessor and Peripherals", Tata McGraw Hill, 3rdedition, 2013
 2007.

 es
 2.
 Douglas V. Hall, "Microprocessor and Interfacing:Programming and Hardware", Glencoe, 2nd edition, 2006.
 4.
 Muhammad Ali Mazidi and Jani

2007. Muhammad Ali Mazidi and JanicaGilliMazidi, 'The 8051 microcontroller and embedded systems', Pearson Education, 5th Indian reprint, 2003.

	Diamain			Einal Examination	(50%) woightaga)								
	Bloom s Level of Thinking	CLA – 1 (10%)		CLA – 2 (15%)		CLA – S	3 (15%)	CLA – 4	4 (10%)#				
	Lovor of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice		
Lovel 1	Remember	200/	20%	150/	150/	150/	150/	150/	150/	150/	150/		
Level I	Understand	2076		1370	1370	1370	1370	1370	1576	1570	1576		
Lovel 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
Leverz	Analyze		2078	2078	20%	2078	20%	20%	2078	2078	2070		
	Evaluate												
Level 3	Create	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%		
	Total	10	0 %	100) %	100) %	10	0 %		-		

Course Designers		
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Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldives	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1.Dr.T.Rajalakshmi, SRMIST

Course Code	18BMC305T	Course Name	9		BIOCONTROL SYSTEMS	Co Cat	ourse egory	С				Profes	sional	core					L 3	T 0	P 0	C 3
Pre-requis Courses	Pre-requisite Courses Nil Co-requisite Courses Nil					Pro C	gressive ourses	Nil														
Course Offering Department Data Book / Codes/Stand						Nil																
Course Learning Rationale (CLR): The purpose of learning this course is to:						L	earning					Pro	ogram	Learn	ing Ou	itcome	es (PL	0)				
CLR-1 : <i>Le</i>	earn about mathematical	modeling of me	echanical and electi	rical systems		1	2	3	1	2	3 4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 : Ad CLR-3 : Id CLR-4 : Kd CLR-5 : Ad CLR-6 : Ld	CLR-2: Acquire knowledge about the transient and steady state error and analysis CLR-3: Identify and analyze stability of a system in time domain using root locus technique CLR-4: Know about different frequency domain analytical techniques CLR-5: Acquire the knowledge of various controllers used in control systems CLR-6: Learn about the biomedical applications of control systems					hinking (Bloom)	Proficiency (%)	Attainment (%)	ng Knowledge	Analysis	Development Design,	ool Usage	Culture	ent & bility		& Team Work	ication	gt. & Finance	Learning			
Course Learn	ing Outcomes (CLO):	At the e	nd of this course, le	earners will be able t	0:	Level of T	Expected	Expected	Engineeri	Problem ,	Design & Analysis, Research	Modern T	Society &	Environm Sustainat	Ethics	Individual	Commun	Project M	Life Long	PSO - 1	PSO - 2	PSO – 3
CLO-1 : D	etermine Transfer functio	on of a system b	y mathematical m	odeling, block diagra	m reduction and signal flow graphs	1, 2	80	70	М	-		-	-	-	-	-	-	-	-	-	-	-
CLO-2 : Id	entify the standard test i	nputs, time don	nain specifications	and calculate steady	state error	1, 2	80	70	-	-	- M	-	-	-	-	-	-	-	М	М	-	-
CLO-3 : PI	lot a root locus curve and	l analyze the sy	stem stability using	Routh array		2	80	70	-	-	- M	-	-	-	-	-	-	-	М	М		-
CLO-4 : A	LO-4 : Analyze the frequency domain specifications from bode plot					1	80	70	-	-	М	-	-	-	-	-	-	-	М	-	М	-
CLO-5 : PI	Plot polar plots				1	80	70	-	-	- M	-	-	-	-	-	-	-	М	-	-	-	
CLO-6 : M	Modelling of lung mechanics					1,2	80	70	-	-		-	-	-	-	-	-	-	Н	-	-	-

Durati	on (hour)	Mathematical Modelling	Time Response Analysis	Stability Analysis	Frequency Response Analysis	State Space Variable Analysis and Biomedical Applications
		9	9	9	9	9
S-1	SLO-1	Control system terminology-classification of control systems, SISO and MIMO control systems	Standard test signals- step, ramp, parabolic and impulse	Poles and zeros of a system	Frequency domain analysis	Introduction to state space
	SLO-2	Feedback and its effects on overall gain, stability, noise and sensitivity	Derivation of expression for standard test signals	Pole zero plot and concept of s plane	Frequency domain specifications	General state space representation
6 .2	SLO-1	Open loop and closed loop control systems with physiological system examples	Type and order of a system	Characteristic equation	Estimation of frequency domain specifications	Applying the state space representation
5-2	SLO-2	Advantages and disadvantages of OLCS and CLCS systems	Transfer function of First order system for Step and ramp input signal	Concept of stability from pole zero location	Correlation between time and frequency domain	Applying the state space representation
6.2	SLO-1	Transfer function of a system and basics of Laplace transform	Transfer function of First order system Impulse and parabolic input signal	Need for Stability analysis and available techniques	Bode plot approach and stability analysis	Converting a transfer function to state space
3-3	SLO-2	Transfer function of translational mechanical systems	General transfer function of second order system	Necessary and sufficient Conditions for stability	Rules for sketching bode plot	Converting a transfer function to state space
2	SLO-1	Transfer function of translational mechanical systems	Identification of damping factor and classification based on it	Routh Hurwitz Technique	Bode plot of typical systems	Converting from state space to a transfer function
3-4	SLO-2	Transfer function of rotational mechanical systems	Step response of critically damped second order system	Significance of Routh Hurwitz Technique	Bode plot of typical systems	Converting from state space to a transfer function
6 5	SLO-1	Transfer function of electrical systems	Step response of under damped second order system	Computation of Routh array	Bode plot of typical systems	Controllers-P, PI and PID controllers
3-3	SLO-2	Transfer function of electrical systems	Step response of over damped second order system	Routh array of stable systems	Bode plot of typical systems	Controllers-P, PI and PID controllers
S-6	SLO-1	Analogous systems	Step response of undamped second order system	Routh array of Unstable systems	Nyquist stability criterion	Physiological control system analysis

	SLO-2	Analogous systems	Transfer function-Time constant form and pole zero form	Routh array of Unstable systems	Nyquist stability criterion	A simple example
87	SLO-1	Block diagram reduction technique	Time domain specifications	Root locus technique	Sketching of polar plot	Linear model of physiological system-Example1
3-1	SLO-2	Block diagram reduction technique	Evaluation of time domain specifications	Rules for construction of root locus	Sketching of polar plot	Linear model of physiological system-Example2
S-8	SLO-1	Signal flow graph	Transient and steady state error analysis	Root locus plot of typical systems	Sketching of polar plot	Distributed parameter Vs Lumped paramter models
	SLO-2	Signal flow graph	Static and dynamic Error coefficients	Root locus plot of typical systems	Sketching of polar plot	Distributed parameter Vs Lumped paramter models
8.0	SLO-1	Conversion of block diagram to signal flow graph	Static error constants and evaluation of steady state error	Root locus plot of typical systems	Polar plot and significance	Lung mechanics model with proportional control
3-9	SLO-2	Conversion of block diagram to signal flow graph	Dynamic error constants and evaluation of steady state error	Effect of adding poles and zeros to a system	Polar plot and significance	Lung mechanics model with proportional control

Learning	1. Nagrath.J and Gopal.M,, "Control System Engineering", 5 th Edition, New Age, 2007.
Resources	2. Benjamin C Kuo, "Automatic Control System", 9th edition, John Wiley & Sons, 2010.

Gopal.M, "Control System Principles and Design", 2nd Edition, TMH, 2002.
 Michael C K Khoo, "Physiological Control Systems: Analysis, Simulation and Estimation", John Wiley & Sons, 2000.

Learning Assessm	ent											
	Final Examination (50% weightage)											
	Diuoini S	CLA – 1 (10%)		CLA – 2 (15%)		CLA –	3 (15%)	CLA – 4	4 (10%)#	T mai Examination (50 % weightage)		
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	
Lovel 1	Remember	40.9/		40.0/		10.0/		20.0/		200/		
Level I	Understand	Understand 40 %	-	40 %	-	40 %	-	30 %	-	30%	-	
Lovel 2	Apply	10.0/		10.0/		10.9/		10.0/	_	400/		
Level Z	Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-	
Loval 3	Evaluate	20.0/		20.0/		20.0/		20.0/		200/		
Level 5	Create	20 %	-	20 %	-	20 %	-	30 %	-	30%	-	
	Total	10	0 %	10	0 %	100	0 %	100 %		10	0 %	

Course Designers									
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts							
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldives	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	Dr.A.K.Jayanthy							

Course Code	18BMC306J	Course Name	MEDICAL IMAGE PROCESSING				Cou Categ	rse Jory	С	Professional core					L 3	Т 0	P 0	C 3						
Pre-requisite Co-requisite Courses						lards		N	Progr Cou	essive rses	Nil													
Course entern	ig Doparatione				Buta Book / Cod		arao		1.0															
Course Learning Rationale (CLR): The numose of learning this course is to:								Learnii	na						Program	1 Learn	nina Ou	tcomes	(PLO)					
CLR1: Understand the basic image operations and image transforms					1	2	3		1	2	3 4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2 :							Y	t											ce					
CLR-3 :	Understand the concepts of Image restoration and reconstruction techniques					_	enc	nen			s	-	age	0			۶		nar	p				
CLR-4 :	Analyze the various type	es of image segr	mentation algorithr	ns			kinç	fici	ainr			ysi	sign	Us	ture	∞. ∞		ear	ы	Ξ	ruir			
CLR-5 :	Gain knowledge in Imag	e compression	methods				i i i	5 2	Atta		و م	nal	Des	8	CUI	ility .		\$ T	cati	Jt. 8	Lea			
CLR-6 :	The learner gains knowl	ledge in fusion o	f two different mod	dality images			J T	fed	fed		erir edg	Ē	n & ppm rch	Ĕ	× م	nme nab		ual	unic	Ŵ	g	.	2	e
								Dect	bect		gine	blei	sign /elc alys	den	ciet	viron	ics	ivid F	ШШ	ject	٦	ò	ò	ò
Course Learni	ng Outcomes (CLO):		At the end of this o	course, learners will be	able to:		(Bic	L A S	Exp (%)		Бпç	Po	De An Re	β	Soc	Sus	딾	bul Vo	G	Pro	Life	PS	PS	PS
CLO-1 :	Describe the elements of	of visual percept	ion and various typ	oes of image transform	s		1, 2	80%	70%		М													
CLO-2 :	Implement the image enhancement techniques for improving the quality of images					2	80%	70%		М														
CLO-3 :	Analyze the various image restoration and reconstruction methods used for medical images					2	80%	70%				Μ	М								М		L	
CLO-4 :	I-4: Apply the different image segmentation algorithms for various medical applications					3	80%	70%					Μ											
CLO-5 :	Differentiate and analyze the various image compression techniques					3	80%	70%		М											М		L	
CLO-6 :	Illustrate the concepts of image fusion					3	80%	70%		Μ														

		Fundamental Image operations and Transforms	Image Enhancement methods	Image Restoration and Reconstruction Techniques	Image Segmentation Techniques	Image Compression and Image Fusion methods	
Duration (hour)		15	15	15	15	15	
S 1	SLO-1	Fundamentals steps in Digital Image processing	Basic Intensity transformation functions - image negative, intensity slicing techniques	Image restoration-Mean filters	Point detection- Detection of isolated points	Image compression-Introduction	
5-1	SLO-2	Components of an Image processing system	Contrast stretching, log transformation and power law transformation	Order-statistic and Adaptive filters	Line detection	Types of redundancies	
S-2	SLO-1	Elements of Visual Perception- structure of human eye and image formation	Histogram equalization	Image degradation model	Basic edge detection	Huffman coding technique	
	SLO-2	Brightness range adaptation and discrimination	Histogram equalization	properties	Marr-Hildreth edge detector	Procedure	
6.2	SLO-1	Image sensing and acquisition-using a single sensor	Histogram specification	Inverse filtering	Canny edge detector	Arithmetic coding technique	
5-5	SLO-2	Using sensor strips	Histogram matching	Minimum mean square error (wiener) filtering	Algorithm	Run length coding technique	
S-4	SLO-1	Lab1: Basic operations on images	Lab4: Intensity transformation and histogram equalization	Lab 7: Image restoration using adaptive filters	Lab 10: Edge detection techniques	Lab 13: Image compression	
	SLO-2	Lab1: Basic operations on images	Lab4: Intensity transformation and histogram equalization	Lab 7: Image restoration using adaptive filters	Lab 10: Edge detection techniques	Lab 13: Image compression	
0.5	SLO-1	Lab1: Basic operations on images	Lab4: Intensity transformation and histogram equalization	Lab 7: Image restoration using adaptive filters	Lab 10: Edge detection techniques	Lab 13: Image compression	
5-0	SLO-2	Lab1: Basic operations on images	Lab4: Intensity transformation and histogram equalization	Lab 7: Image restoration using adaptive filters	Lab 10: Edge detection techniques	Lab 13: Image compression	
S-6	SLO-1	Basic concepts in Image sampling and quantization	Smoothening linear filters	Image reconstruction from projections- Transmission tomography	Thresholding- Foundation	Predictive coding- lossless	
	SLO-2	Spatial and intensity resolution	Non linear filters	Refection and emission tomography	Basic global thresholding	Lossy predictive coding	
S-7	SLO-1	Some basic relationships between pixels- Neighbors of pixel	Sharpening spatial filters	Radon transform- derivation	Optimum global thresholding using otsu's method	Image fusion-Introduction	
	SLO-2	Adjacency, connectivity and distance measures	First order Derivative filters	Properties	Alogrithm	Pixel based image fusion techniques	
S-8	SLO-1	Image Arithmetic operations	Second order derivative filters	Inverse radon transform- convolution back projection	Region based segmentation- Region growing	Wavelet transform based image fusion	

	SLO-2	Logical operations	Un sharp masking and high boost filtering	Filter back projection	Region splitting and merging algorithm	Wavelet transform based image fusion
50	SLO-1	Lab2: Image Arithmetic and logical operations	Lab5: Filtering using averaging filter, unsharp masking and high boost filtering	Lab 8: Image reconstruction using radon transform	Lab 11: Global and otsu's thresholding	Lab 14: Image fusion
3-9	SLO-2	Lab2: Image Arithmetic and logical operations	Lab5: Filtering using averaging filter, unsharp masking and high boost filtering	Lab 8: Image reconstruction using radon transform	Lab 11: Global and otsu's thresholding	Lab 14: Image fusion
S-10	SLO-1	Lab2: Image Arithmetic and logical operations	Lab5: Filtering using averaging filter, unsharp masking and high boost filtering	Lab 8: Image reconstruction using radon transform	Lab 11: Global and otsu's thresholding	Lab 14: Image fusion
	SLO-2	Lab2: Image Arithmetic and logical operations	Lab5: Filtering using averaging filter, unsharp masking and high boost filtering	Lab 8: Image reconstruction using radon transform	Lab 11: Global and otsu's thresholding	Lab 14: Image fusion
S-11	SLO-1	Image transforms-DFT and its properties	Color image processing-Introduction	Digital implementation of filter back projection- Block diagram	Segmentation using morphological watersheds- dam construction	PCA based image fusion techniques
	SLO-2	DCT and its properties	Color models	Different filters	Watershed segmentation algorithm	PCA based image fusion techniques
S-12	SLO-1	DST and its properties	Conversion of RGB to HSI model	Digital implementation of filter back projection- Algorithm	Clustering based segmentation techniques	Transform based fusion techniques-DCT
	SLO-2	Hadamard transform and its properties	Conversion of HSI to RGB Model	Implementation procedure	Algorithms	Transform based fusion techniques-DCT
S-13	SLO-1	Haar transform and its properties	Pseudo color image processing- slicing technique	Fourier reconstruction of MRI images-projection geometry mode	Basic Active Contour Model	Image registration-Introduction
	SLO-2	Haar transform and its properties	Filtering approach	Fourier geometry mode.	Formulation (Feature extraction techniques)	Types of image registration
S-14	SLO-1	Lab 3: Image transforms in frequency domain	Lab 6: Color image processing	Lab 9: Fourier reconstruction of MRI images	Lab 12:Image segmentation by watershed algorithm	Lab 15: Image registration
	SLO-2	Lab 3: Image transforms in frequency domain	Lab 6: Color image processing	Lab 9: Fourier reconstruction of MRI images	Lab 12:Image segmentation by watershed algorithm	Lab 15: Image registration
S-15	SLO-1	Lab 3: Image transforms in frequency domain	Lab 6: Color image processing	Lab 9: Fourier reconstruction of MRI images	Lab 12:Image segmentation by watershed algorithm	Lab 15: Image registration
	SLO-2	Lab 3: Image transforms in frequency domain	Lab 6: Color image processing	Lab 9: Fourier reconstruction of MRI images	Lab 12:Image segmentation by watershed algorithm	Lab 15: Image registration

Learning Resources

Rafael C., Gonzalez and Richard E. Woods, "Digital Image Processing", Pearson Education Asia, Third Edition, 2007
 Anil.k.Jain, "Fundamentals of Digital image processing", Prentice Hall of India, 2nd edition 1997.

Joseph V.Hajnal, Derek L.G.Hill, David J Hawkes, "Medical image registration", Biomedical Engineering series, CRC press, 2001.

∟earning Assessment													
	Bloom's	Continuous Learning Assessment (50% weightage)									Final Examination (E00(weightees)		
	BIOOM S	CLA – 1 (10%)		CLA – 2 (15%)		CLA – S	3 (15%)	CLA – 4	(10%)#	Final Examination (50% weightage)			
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice		
l ovol 1	Remember	200/	200/	150/	150/	150/	150/	150/	150/	150/	150/		
Level I	Understand	20%	2076	1070	1070	1570	1570	1576	1370	1370	1370		
Lovel 2	Apply	20%)% 20%	200/	20%	200/	200/	200/	20%	20%	200/		
Level Z	Analyze			2070		2076	2070	20%			20%		
Level 2	Evaluate	10%	100/	150/	15%	450/	450/	150/	450/	150/	150/		
Level 5	Create		10%	15%		10%	13%	10%	15%	10%	13%		
	Total	100 % 100 %		100) %	100	1%	-					

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Course Designers																							
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts																					
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldives	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	Dr.U.Snekhalatha																					
Course Cod	le 18BMC4	01T Co	ourse Name	BIOMEDICAL EQUI	MENTS FOR CLINICAL APPLICATIONS	Co Cat	ourse egory	С		Professional Core							L 3	T 0	P 0	C 3			
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Pre-requ Course	isite es			Co-requisite Courses		Pro	gressi ourses	ve Ni	I														
Course Offe	ring Department				Data Book / Codes/Standards	Nil																	
Course Lear	rning Rationale (CLR):	The purp	ose of learning this course is to:		L	earnin	g					Prog	gram L	earni	ng Ou	tcomes	፥ (PLC))				
CLR-1 :	Understand the fu	ndamentals	of diagnostic	and therapeutic equipments		1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Get an idea abou electrotherapy eq	functioning upments	of different ty	pes of physiotherapy and			(9	-				arch			bility								
CLR-3 :	Acquire an idea a	bout the the	instruments o	dealing with bone		Loo	/ (%	t (%	0)))	ent	see			aina		,ork		e				
CLR-4 :	Get an idea abou	the respirate	ory care equij	pments		B	anc,	Jeni			, m	Re	ge	-	usta		Š		Jan	ŋ			
CLR-5 :	Get an idea abou	diagnosis p	rocedure of h	nearing problems and Hearing aids		ting	ficie	in	Č.	ysis	elo	ign,	Jsa	Inre	S S		ean	E	Ē	uin.			
CLR-6 :	Get an overall ide	a about lapa	roscope				20	Atta	2	nal a)ev	Ces		G	ant 6		⊢ ∞	atic	Jt. 8	-ea			
-							ed I	éd	-10	u V	& 	s, I	Ĕ	∞ð	Ĕ		a	ių	β	ا و	~	\sim	e
Course Lear	rning Outcomes	CLO):	At the en	d of this course, learners will be able to:		Level o	Expect	Expect		Probler	Design	Analysi	Moderr	Society	Enviror	Ethics	Individu	Comm	Project	Life Lo	- OS4	- OSA	- DSO -
CLO-1 :	Outline the impor	ance of thei	rapeutic and o	diagnostic devicesmedical device		1, 2	80	70	٨	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-2 :	Analyze the types	of pacemak	ers			1, 2	80	70	٨	-	-	-	-	-	-	-	-	-	-	-	М	-	-
CLO-3 :	Apply the principl	e of ultrasour	nd in diagnos	tic and therapeutic application		2	80	70	-	М	-	-	-	-	-	-	-	-	-	-	М		-
CLO-4 :	Outline the impor	ance of resp	piratory care e	equipments		1	80	70	-	-	Н	-	-	-	-	-	-	-	-	М	-	М	-
CLO-5 :	Understand the in	portance an	nd design prod	cedure of hearing aids		1	80	70	-	-	-	-	-	-	-	-	-	-	-	М	-	-	-
CLO-6 :	Understand the c	oncept of sur	rgical diatherr	my		1,2	80	70	L						-								

Durati	on (hour)	Coronary Care Equipments	Physiotherapy, Electrotherapy and Phototherapy Equipments	Instruments Dealing With Bones and Respiratory Care	Sensory Diagnosis and Hearing Aid Equipments	Surgical and Therapeutic Equipments
		9	9	9	9	9
0.1	SLO-1	Cardiac pacemakers: different modes of operation	Short wave diathermy	Introduction to Respiratory care equipments	Mechanism of hearing	Surgical diathermy unit
5-1	SLO-2	external pacemaker	Short wave diathermy	humidifier	Mechanism of hearing	Surgical diathermy unit
S-2	SLO-1	implantable pacemakers,	Advantages of Microwave diathermy over shortwave diathermy	nebulizer	sound conduction system	Endoscopy basic components
	SLO-2	pacemaker standard codes	Microwave diathermy	aspirators	sound conduction system	Endoscopy basic components
6.2	SLO-1	Defibrillator: AC defibrillator	Ultrasound application in medical diagnostic	Working of Ventilators	basic audiometer	Endoscopy different types
3-3	SLO-2	DC defibrillator	Working details of Ultrasonic therapy unit	Ventilators types	pure tone audiometer	Endoscopy different types
C 1	SLO-1	Implantable defibrillator	Electro diagnostic apparatus	capnography	Speech audiometer	Laparoscope
3-4	SLO-2	types	Electro diagnostic apparatus	capnography	bekesyaudiometer system	Laparoscope
с F	SLO-1	automated external defibrillator (AED)	Electro therapeutic apparatus	Anesthesia machine	bekesyaudiometer system	gastro scope
3-0	SLO-2	automated external defibrillator (AED)	Electro therapeutic apparatus	Anesthesia machine	Evoked response audiometry system	bronchoscope
0.0	SLO-1	Pacer- cardioverter defibrillator,	Interferential current therapy,	Baby incubator	Evoked response audiometry system	Cryogenic techniques
5-0	SLO-2	Pacer- cardioverter defibrillator	Interferential current therapy,)	BMD measurements: Single X-ray absorptiometry (SXA)	Hearing aids	Cryogenic techniques

S-7	SLO-1	defibrillator analysers	Transcutaneous electrical nerve stimulation (TENS)	BMD measurements: Single X-ray absorptiometry (SXA)	Hearing aids	Cryogenic technique application
	SLO-2	Heart lung machine (HLM)	bladder stimulator	Dual X-ray absorptiometry (DXA)	galvanic skin response	Operating microscope
C 0	SLO-1	Heart lung machine (HLM)	Spinal cord stimulator,	Dual X-ray absorptiometry (DXA)	galvanic skin response	arthroscopy
3-0	SLO-2	Functional details of oxygenators	deep brain stimulation	Quantitative ultrasound bone densitometer	Tonometry	Modern lithotripter system
50	SLO-1	types of oxygenators	Photo therapy unit	Quantitative ultrasound bone densitometer	Measurement of basal skin response	laser lithotripsy
3-9	SLO-2	types of oxygenators	Photo therapy unit	Comparison of DXA and Bone densitometer	galvanic skin response	Hospital visit

Learning Resources	 R.S.Khandpur, 'Handbook of Bio-Medical instrumentation', Tata McGraw Hill Publishing Co Ltd., 3rd edition, 2014. Albert M.Cook and Webster.J.G, "Therapeutic Medical Devices", Prentice Hall Inc., New Jersey, 1st edition, 1982 Sydney Lou Bonnick, Lori Ann Lewis, "Bone Densitometry and Technologists", Springer, 3rd edition, 2013 Marc. Safran, Bobby. Chhabra. A., Mark. Miller.D., "Primer of Arthroscopy", Elsevier Health Sciences, 2nd edition, 2010 	5. Leslie Cromwell, Fred J.Weibell, Erich A.Pfeiffer, "Bio-Medical Instrumentation and Measurements",Pearson Education, PHI Learning Private limited, India, 2nd edition, 2007 " 6. John G.Webster, "Specifications of Medical Instrumentation Application and Design",Wiley India Pvt Ltd, India, 4th edition, 2015.
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Learning Assessme	ent										
	Diaam'a			Co	ontinuous Learning Ass	essment (50% weightag	je)			Final Examination	(E00/ weightege)
	DIUUIII S	CLA – 1	1 (10%)	CLA – 2	2 (15%)	CLA –	3 (15%)	CLA – 4	(10%)#	FINALEXAMINATION	(50% weightage)
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40.0/		10.0/		10.0/		20.0/		200/	
Level	Understand	40 %	-	40 %	-	40 %	-	30 %	-	30%	-
Lovel 2	Apply	10 %		10.0/		10.0/		10.0/		100/	
Level Z	Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40 %	-
Lovel 3	Evaluate	20.0/		20.0/		20.0/		20.0/		200/	
Level 5	Create	20 %	-	20 %	-	20 %	-	30 %	-	30%	-
	Total	100) %	100	0 %	100) %	100) %	100)%

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldives	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	Mrs. G.Anitha

Course Code	18BME261T	Course Name	Bio photonics an	d Bio imaging	Course Category	Е	Professional Elective	L 3	Т 0	P 0	<u>С</u> 3
Pre-requisi Courses	te _{Nil}		Co-requisite Courses		Progressive Courses	Nil					
Course Offerin	ng Department	Biomedical Engine	neering	Data Book / Codes/Standards	Nil						

Course Le	earning Rationale (CLR):	The purpose of learning this course is to:	Le	arning	g					Prog	jram l	Learni	ing O	utcom	nes (P	LO)				
CLR-1 :	To Know the concepts of spe	stroscopy	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	To Know the concepts of vari	bus biosensors																		
CLR-3 :	Outline the various application	ns of biosensors in medicine																		
CLR-4 :	To understand the concepts of	f various microscopes used in medicine	Ē						rch			bility								
CLR-5 :	Acquire knowledge on the tre	atment mechanism of Phototherapy	loor	y (%	nt (%	dge		ent	esea			aina		Vork		JCe				
CLR-6 :	To understand the special teo	hniques like optical holography	g (B	ienc	mer	owle	<u>.</u>	opm	n, R	sage	е	Sust		M V		inar	ing			
	·		 inkin	Profic	Attain	g Kn	nalys	Jevel	Jesig	ol Us	Cultu	nt & :		& Tea	ation	t. & F	-eam			
Course Lo	earning Outcomes (CLO):	At the end of this course, learners will be able to:	-evel of Th	Expected F	Expected /	Engineerin	^{>} roblem A	Design & [Analysis, 🛛	Modern To	Society & (Environme	Ethics	ndividual	Communic	[⊃] roject Mg	-ife Long L	- SO - 1	- SO - 2	- SO - 3
CLO-1 :	Implement spectroscopy for b	iological imaging	1, 2	80	70	M	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-2 :	Implement the various application	tions of biosensors in medicine	1, 2	80	70	-	-	-	М	-	-	-	-	-	-	-	М	М	-	-
CLO-3 :	Implement Microscopy in med	lical diagnosis	2	80	70	-	-	-	М	-	-	-	-	-	-	-	М	М		-
CLO-4 :	Identify the principle behind n	odern imaging techniques	1	80	70	-	-		М	-	-	-	-	-	-	-	М	-	М	-
CLO-5 :	Describe the medical applicat	ions of phototherapy	1	80	70	-	-	-	М	-	-	-	-	-	-	-	М	-	-	-
CLO-6 :	Analyze the physics behind o	otical holography	1,2	80	70	-	-	-	-	-	-	-	-	-	-	-	Н	-	-	-

Du	ration	LIGHT - MATTER INTERACTION & PRINCIPLE OF OPTICS	OPTICAL BIOSENSORS	BIO-IMAGING	PHOTODYNAMIC THERAPY	OPTICAL HOLOGRAPHY
()	iour)	9	9	9	9	9
S-1	SLO-1	Concepts of Light matter interaction	Biosensors: Definition	Introduction of optical imaging	Basics of radiation therapy	Fundamentals – Object wave
0-1	SLO-2	Interactions Between Light and a Molecule	Block diagram & description	Needs of optical imaging	Basic principles	Photography
6.0	SLO-1	Interaction of light with bulk matter	Principles of Optical Bio sensing	Microscopy: Principles	Mechanism of Photodynamic Photo oxidation	Holography
5-2	SLO-2	Fate of Excited State	Bio recognition	Types of microscopy: Transmission microscopy	Photosensitizers For Photodynamic Therapy	Interference during recording
6.2	SLO-1	Spectroscopy: Principles	Optical Transduction	Fluorescence microscopy	Photosensitizers For Photodynamic Therapy	Diffraction during reconstruction
3-3	SLO-2	System description	Fluorescence Sensing, Fluorescence Energy Transfer Sensors	Scanning microscopy	Mechanism of photodynamic action	Imaging techniques –In line hologram
S-4	SLO-1	Types of spectroscopy	Molecular Beacons, Optical Geometries of Bio sensing	Inverted and Upright Microscopes	Three Principal Mechanisms of Photodynamic Therapy	Off axis hologram, Fourier hologram

	SLO-2	Conventional Spectrometers	Immobilization of bio-recognition elements	Confocal Microscopy	Light Irradiation For Photodynamic Therapy	Fraunhofer hologram, Reflection hologram
6 E	SLO-1	Fourier Transform Spectrometers	Fiber optic Biosensors	Multi-photon- microscopy	Light sources	Optical properties of holographic imaging
3-5	SLO-2	Michelson interferometer	Operating principles of Fiber optic Biosensors	Optical Coherence Tomography	Laser dosimetry	Hologram of an object
5-6	SLO-1	Electronic absorption spectroscopy	Types of optical biosensor: Fiber optic Biosensor	Total Internal Reflection Fluorescence Microscopy	Light delivery	Image equation, Angular magnification
0-0	SLO-2	Types of Electronic Transitions	Planar waveguide Biosensor	Near-Field Optical Microscopy	Two-Photon Photodynamic Therapy	longitudinal magnification, Image aberrations
S-7	SLO-1	Electronic luminescence spectroscopy	Evanescent Wave Biosensors	Fluorescence Resonance Energy Transfer (FRET) Imaging	PUVA technique	Properties of light source -spectral bandwidth
	SLO-2	Electronic luminescence spectroscopy	Principle of Evanescent Wave Biosensors	Fluorescence Lifetime Imaging Microscopy (FLIM)	PUVA technique	Image plane holograms
e 0	SLO-1	Vibrational spectroscopy	Interferometric biosensor	Advantages and disadvantages of optical imaging	Applications of PDT	Image luminance- Without pupil
3-0	SLO-2	Principle of Vibrational spectroscopy	Surface plasmon resonance Biosensor	Applications of Bio imaging, Fluorophores as Bio imaging Probes	Applications of PDT	With pupil, Image plane holograms
S-0	SLO-1	Fluorescence spectroscopy	Applications of optical Biosensors in medicine	Green Fluorescent Protein, Cellular Imaging	Advantages of PDT	Speckles- diffuser
0-9	SLO-2	Fluorescence Correlation Spectroscopy	Advantages and Disadvantages	Tissue Imaging, In Vivo Imaging	Disadvantages of PDT	Resolution, Incoherent illumination

Learning Resources	 Wilson J and Hawkes J.F.B, "Optoelectronics – An Introduction", Prentice Hall of India Pvt. Ltd., NewDelhi, 3rd edition, 2003. Leon Goldman, M.D., & R.James Rockwell, Jr., Lasers in Medicine, Gordon and Breach Science Publishers Inc., 1975. 	 Tuan Vo Dirh, Biomedical Photonics – Handbook, CRC Press, Bocaraton, 2003. Paras N, Prasad, "Introduction to Biophotonics", John Wiley & Sons, First Edition, 2003. Gerhard K. Ackermann, Jürgen Eichler, "Holography: A Practical Approach", WILEY-VCH Verlag GmbH & Co, first edition, 2008.
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Learning Asse	essment										
	Dia amia			Con	tinuous Learning Ass	essment (50% weight	tage)			Final Examinatio	o (EO9/ waightago)
	DIOUIIIS	CLA –	1 (10%)	CLA – 2	2 (15%)	CLA –	3 (15%)	CLA – 4	(10%)#		ii (50 % weiginage)
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Lovel 1	Remember	40.0/		10.0/		10.0/		20.0/		200/	
Level I	Understand	40 %	-	40 %	-	40 %	-	30 %	-	30%	-
Lovel 2	Apply	10.0/		10.0/		10.0/		10.9/		409/	
Leverz	Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Lovel 2	Evaluate	20.0/		20.0/		20.0/		20.0/		200/	
Level 5	Create	20 %	-	20 %	-	20 %	-	30 %	-	30%	-
	Total	10) %	100	0 %	10	0 %	100) %	10	0 %

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldives	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1.Dr.P.Vinupritha,SRMIST

Course Code	Course HO	ME MEDICARE TECHNOLOGY	Course Category	Е	Professional Elective	L 3	T 0	P 0	C 3
Pre-requisite Courses Course Offering Department	Biomedical Engineering	site es Nil Data Book / Codes/Standards	Progres Cours Nil	ssive ses	Nil				

Course Learning Rationale (CLR):	Inse Learning Rationale (CLR): The purpose of learning this course is to:				ng					Prog	gram	Learn	ing Oı	utcom	es (P	LO)				
CLR-1 : Utilize the Home health Nur	sing practice		1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 : Utilize homecare care work	ing with different clients		ĉ	(1																
CLR-3 : Utilize the various medical of	levices used at home		loo	, (%	%):	dge		ät						¥		8				
:LR-4 : Utilize the advancement in medical technologies		B	luc)	lent	Mec		m		ge				Š		Jan	δ				
CLR-5: Utilizte the use of wireless technology in health care		ing	îcie	in T	NO	/sis	elop	gn,	Jsa	nre	~*		ean	E	ιĒ	ці.				
CLR-6: Utilize the various mode of healthcare technology at home			İİ	p	∖tta	gК	nal)eV)esi	0	Cult	it 8		Ĕ	atio	t &	ear			
			Ē	Ъе	pe /	erin	٩u	s S	s, E ch	Ĕ	& (abi		al &	nic	Mg	р Д	_	~	~
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		Level o	Expecte	Expecte	Engine	Probler	Design	Analysi Resear	Modern	Society	Environ Sustain	Ethics	Individu	Commu	Project	Life Lor	- OS4	- OSA	PSO - 3
CLO-1 : Applying Home health Nurs	ing practice		3	80	75	L	-	-	-	-	-	-	-	-	-	-	-	L	-	L
CLO-2 : Illustrate the homecare care	e working with different clients		3	80	70	L	-	-	-	-	-	-	-	-	-	-	-	L	-	L
CLO-3 : Analyze the various medical devices used at home		3	75	70	М	-	-	I	-	-	-	-	-	-	-	-	L	-	L	
CLO-4: Identify the advancement in medical health technologies		3	80	75	М	-	-	1	-	-	-	-	-	-	-	-	L	-	L	
CLO-5: Analyze the use of wireless technology in health care		3	80	70	М	-	-	-	-	-	-	-	-	-	-	-	L	-	L	
CLO-6 : Describe the various type o	f healthcare technology at home		3	80	70	L	-	-	-	-	-	-	-	-	-	-	-	L	-	L

-		Introduction to Home health Nursing	Working With Clients	Medical Devices At Home	Advancement In Medical Technologies	Wireless Technology
Durati	on (hour)	9	9	9	9	9
S 1	SLO-1	Home health care – purpose	Basic human needs	Medical devices at home	Advances and trends in health care technologies	Wireless communication basics
3-1	SLO-2	Organization of homecare system	Communication and interpersonal skills	Medical devices at home	Advances and trends in health care technologies	Wireless communication basics
6.2	SLO-1	Historical development of home care	Caregiver observation	ECG monitors	Driver impacting the growth of medical Technologies	Types of wireless network
5-2	SLO-2	Environmental influences of home care	Caregiver observation	ECG monitors	Driver impacting the growth of medical Technologies	Types of wireless network
S_2	SLO-1	Home care Organization	Recording and reporting, confidentiality.	Smart watch	Impact of Moore"s law of medical imaging-	Body area network
5-5	SLO-2	Legal and ethical issues in home care	Recording and reporting, confidentiality.	Smart watch	Impact of Moore"s law of medical imaging	Body area network
54	SLO-1	Case management and leadership strategies	Working with elderly – aging and body systems.	Wireless infant monitoring system	E-health and personal healthcare	Emergency rescue
3-4	SLO-2	Organisation of home care system	Working with elderly – aging and body systems.	Wireless infant monitoring system	E-health and personal healthcare	Emergency rescue
S-5	SLO-1	Home care organization	Working with children	PCG monitors,	Defining the future of health Technology	Remote recovery
5-5	SLO-2	Home care organization	Working with children	PCG monitors,	Defining the future of health Technology	Remote recovery

8.6	SLO-1	Role of home care nurse and orientation	Need for home care	Medical alert services.	Inventing the future -tools for self-health	Personalized ambient monitoring
3-0	SLO-2	Role of home care nurse and orientation strategies	Need for home care	Medical alert services.	Inventing the future -tools for self-health	Personalized ambient monitoring
67	SLO-1	Environmental influences on home care	Mobility transfers and ambulation	Activity monitors	Future of Nano fabrication molecular scale devices	Future trends in healthcare technology.
3-1	SLO-2	Environmental influences on home care	Mobility transfers and ambulation	Automatic wireless healthcare monitoring system	Future of Nano fabrication molecular scale devices	Future trends in healthcare technology.
.	SLO-1	Infection control in home	Range of motion exercises	The ventilator dependent patient	Future of telemedicine	Multi model interaction and technologies for care at home
3-8	SLO-2	Infection control in home	Range of motion exercises,	Device for patient with congestive heart failure	Future of telemedicine	Multi model interaction and technologies for care at home
S-0	SLO-1	Patient education in home.	Skin care and comfort measures	Device for Patient with chronic Obstructive pulmonary disease	Future of medical computing	Cost of home healthcare
S-9 SLO-2	Patient education in home.	Skin care and comfort measures	Device for patient with Diabetic	Future of medical computing	Direction for emerging technology	

Learning Resources

Robyn Rice, "Home care nursing practice: Concepts and Application", 4th edition, Elsevier, 2006.
 2. LodewijkBos, "Handbook of Digital Homecare: Successes and Failures", Springer, 2011.

Yadin David, Wolf W. von Maltzahn, Michael R. Neuman, Joseph. D,Bronzino, "Clinical Engineering", CRC Press, 2010.
 Kenneth J. Turner, "Advances in Home Care Technologies: Results of the match Project", Springer, 2011.

Learning As	sessment										
	Pleam's			Con	tinuous Learning Ass	essment (50% weigh	tage)			Final Examinatio	n (E0% weightege)
	DIUOIIIS	CLA –	1 (10%)	CLA –	2 (15%)	CLA –	3 (15%)	CLA – 4	4 (10%)#		r (50% weightage)
	Lever of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
l evel 1	Remember	30 %	_	30 %	_	30 %	_	30 %	_	30%	_
Level	Understand	00 /0		00 70		00 70		00 /0		0070	
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Evoluato										+
Level 3	Create	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Total	10	0 %	10	0 %	10	0 %	10	0 %	10	0 %

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldive	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1. Dr. D. Ashok Kumar, SRMIST
		2. Mrs.Lakshmi Prabha.P, SRMIST

Course Code	18BME263T	Course Name		CELLULAF	R AND MOLECULA	AR BIOLOGY	Co Cat	ourse egory	E		Professional Electiv				ective	/e				L T 3 0	P 0	C 3	
Pre-requis Courses Course Offer	ite <i>Nil</i> ing Department	Biomed	dical Enginee	Co-requisite Courses	Nil Data	Book / Codes/Standards	Pro Co Nil	gressi ourses	ve _{Ni}	1													
Course Learn	se Learning Rationale (CLR): The purpose of learning this course is to:								g					Progr	am Le	earnin	ng Out	come	s (PL)	0)			
CLR-1: Ha	ave an idea about the l	asics of cells					1	2	3	1	2	3	4	5	6	7	8	9	10 '	11	12 1	3 1	15
CLR-2 : Kr CLR-3 : Lee CLR-4 : Tc CLR-5 : Ur CLR-6 : Lee	CLR-1: Have an idea about the basics of cells CLR-2: Know the basic aspects of cell structure and functions CLR-3: Learn the principles of cell signaling and cell regulation CLR-4: To understand the concept of molecular biology CLR-5: Understand the concept behind DNA and RNA CLR-6: Learn about cell replication and repair					vel of Thinking (Bloom)	pected Proficiency (%)	pected Attainment (%)	gineering Knowledge	oblem Analysis	sign & Development	alysis, Design, search	odern Tool Usage	ciety & Culture	virunien. œ stainability	lics	lividual & Team Work	mmunication	oject Mgt. & Finance	e Long Learning		50 - 3	
	volain the basics of co	Il and its struc	turo				<u> </u>	Ш ВО	<u> </u>	山	P	ŏ,	¥ ₩	ž	ы	цų	ш	Ĕ	<u>ŏ</u>	2			<u> </u>
CLO-1 : De	escribe the basic conce	epts of cell stru	ucture and its	s function			1, 2	80	70	-	-	-	- M	-	-	-	-	-	-	-	M	1	-
CLO-3 : //	plement the various p	ocesses of ce	ll signaling a	and cell regulation			2	80	70	-	-	-	М	-	-	-	-	-	-	-	ΜΛ	1	-
CLO-4 : Ur	nderstand the concept	of molecular b	biology				1	80	70	-	-		М	-	-	-	-	-	-	-	М -	۸	1 -
CLO-5 : Ex	0-5 : Explain the structures and paring of DNA and RNA					1	80	70	-	-	-	М	-	-	-	-	-	-	-	M -		-	
CLO-6: A	J-6 : Apply the recent advancements in cell repair and replication							80	70	-	-	-	-	-	-	-	-	-	-	-	H ·	· ·	-
Duration AN OVERVIEW OF CELLS CELL STRUCTURE AND FUNCTION CELL SIGNALING - CELL F				CELL SIGNALING -CELL REG	ULATION			INTROD BIOL	UCTIO .OGY–	N TO I DNA A	NOLE	CULAF RNA	7			RE	EPLIC	ATION	I AND	REPA	R		

Du	uration	AN OVERVIEW OF CELLS	CELL STRUCTURE AND FUNCTION	CELL SIGNALING –CELL REGULATION	BIOLOGY- DNA AND RNA	REPLICATION AND REPAIR
,		9	9	9	9	9
6.1	SLO-1	Origin and evolution of cells	Introduction to Nucleus	General principles of cell signaling	Scope and history	Replication in prokaryote and eukaryote
3-1	SLO-2	Origin and evolution of cells	Endoplasmic reticulum	Modes of cell	Structure of DNA	Types and function of DNA
6.2	SLO-1	Evolution of metabolism	Golgi apparatus and Lysosomes	Cell signaling	Nucleoside	Polymerases
3-2	SLO-2	Origin of Prokaryotes	Golgi apparatus and Lysosomes	Pathways of intracellular signal transduction	Nucleotide	Proof reading activity
6.2	SLO-1	Origin of Eukaryotes	Bioenergetics and Metabolism	Function of cell surface receptors	Base pairing	5'- 3' exonuclease activity
5-3	SLO-2	Development of multicellular organisms	Mitochondria	G-protein coupled receptor pathway (GPCR) pathway	Base stacking	Topoisomerase activity
5.4	SLO-1	Development of multicellular organisms	Chloroplasts	Cyclic adenosine 3',5'-monophosphate (cAMP) pathway	Double helix	Telomeric DNA replication and Plasmid replication
0-4	SLO-2	Cells as experimental models	Peroxisomes	Receptor protein tyrosine kinase pathway	Features of Watson and crick model	Theta model
S 5	SLO-1	Tools of cell biology	The cytoskeleton and cell movement	Mitogen-activated protein kinase (MAPK) pathway	Major and minor groove	Strand replacement model
3-0	SLO-2	Tools of cell biology	Cell surface	Cell division : Cell cycle	Supercoiling	Rolling circle model

8.6	SLO-1	Molecular composition	Transport of small molecules	Mitosis - Stages of mitosis	Twist	DNA repair
3-0	SLO-2	Biosynthesis of cellular constituents	Endocytosis	Meiosis - Meiosis I and Meiosis II	Writhe and linking number	Nucleotide excision repair
67	SLO-1	Central role of enzymes as biocatalysts	Cell –cell interactions	Cell death: Necrosis	Forms of DNA	Mismatch repair
3-1	SLO-2	Central role of enzymes as biocatalysts	Cell –cell interactions	Programmed cell death	A, B, Z - Structure and function of RNAs	Photo-reactivation
	SLO-1	Metabolic energy	Adhesion junctions	Apoptosis	mRNA	Recombination repair
3-8	SLO-2	Metabolic energy	Tight junctions	Extrinsic pathway, Intrinsic pathway	rRNA	Recombination repair
e 0	SLO-1	Cell membrane	Gap junctions	Cell differentiation: Stem cells-embryonic stem cells	tRNA	SOS repair
S-9 SLO-2 Cei	Cell membrane	Plasmodesmata	Adult stem cells, therapeutic applications of stem cells	Secondary structures in RNA	SOS repair	

Learning Resources Channarayappa, "Cell biology," Universities Press, 2010
 Rastogi, S.C, "Cell biology," New Age International publishers, 2005.

Learning Assessment Continuous Learning Assessment (50% weightage) Bloom's Final Examination (50% weightage) CLA - 1 (10%) CLA - 2 (15%) CLA - 3 (15%) CLA-4 (10%)# Level of Thinking Theory Practice Theory Practice Theory Practice Theory Practice Theory Practice Remember Level 1 40 % -40 % -40 % -30 % 30% --Understand Apply Level 2 40 % 40 % 40 % 40 % 40% -----Analyze Evaluate 20 % 20 % 30% Level 3 20 % 30 % -----Create Total 100 % 100 % 100 % 100 % 100 %

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldive	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1. Dr.PVinupritha, SRMIST

Course Code	18BME264T	Course Name	BIOMEDICAL LASER IN	STRUMENTS	Course ategory	Е	Professional Elective	L 3	T 0	P 0	C 3
Pre-requisi Courses	te _{Nil}		Co-requisite Courses		Progressiv Courses	ve N	Nil				
Course Offerin	ng Department	Biomedical Engineering		Data Book / Codes/Standards	Nil						

Course Learning Rationale (CLR): The purpose of learning this course is to:	I	earni	ng						Prog	gram	Learn	ing Ou	utcom	es (P	L O)				
CLR-1: Know the functioning of a laser system	1	2	3	1	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2: Learn about the working principle of laser	-		-																
CLR-3: Learn the optical characteristics of tissue	uoc	%	%		lge		ant						Ч,		8				
CLR-4: Familiarise the applications of laser in Urology, Gynecology and dentistry	Ē	nc)	ent		vlec		me		ge				Ň		Jan	D			
CLR-5 : Learn the non- thermal applications of laser in medicine	ing	icie	E L		Nov	/sis	elop	gn,	Jsa	nre	~×		ean	Ę	Ē	ini			
CLR-6 : Acquire knowledge on laser safety and management	ink	lof	∖tta		g K	llal)eVi)esi	olL	Cult	it 8		Ť	atio	ť.	ear			
	- 4	P E E	pe /		erin	١A	8	s, L	To To	& (me		al 8	inic	Mg	Ъ		~ .	
Course Learning Outcomes (CLO): At the end of this course, learners will be able to:	Level of	Expecte	Expecte		Enginee	Problen	Design	Analysi Resear	Modern	Society	Environ Sustain	Ethics	Individu	Commu	Project	Life Lor	PSO - 1	PSO - 2	PSO - 3
CLO-1: Have a deep understanding on technical aspects of a LASER system	3	80	75		-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-2 : Learn about the working principle of laser	3	80	70		М	-	-	-	-	-	-	-	-	-	-	-	М	-	-
CLO-3: Describe the optical properties of tissues	3	75	70		1	Μ	-	-	-	-	-	-	-	-	-	-		М	
CLO-4 : Describe the applications of laser in Urology, Gynecology and dentistry	3	80	75		-	М	-	-	-	-	-	-	-	-	-	-	М		
CLO-5 : Explain the non- thermal applications of laser in medicine	3	80	70]	-	-М	-	-	-	-	-	-	-	-	-	-	М		
CLO-6 : Implement the aspects of laser safety	3	80	70		-	-	-	-	-	-	-	М	-	-	-	-	L		

Durati	on (hour)	LASER SYSTEM	TYPES OF LASER	MECHANISM OF LASER TISSUE INTERACTION	LASER APPLICATIONS	NON THERMAL APPLICATIONS OF LASER AND LASER SAFETY MANAGEMENT
	- ()	9	9	9	9	9
6.4	SLO-1	Absorption and Emission of Radiation by atoms	Classification of Laser	Photochemical interaction	Disorders in Eye	Optical coherence tomography
5-1	SLO-2	lons and Molecules	Solid state Laser Construction	Bio stimulation	Diagnostic and Therapeutic Applications of laser in ophthalmology	System description
	SLO-1	Laser - Definition	Working principle	Thermal interaction	Dermatological disorders	Applications of Optical coherence tomography
5-2	SLO-2	Properties of laser	Atomic laser Construction	Heat generation	Applications of Lasers in dermatology	Laser Induced Fluorescence (LIF)-Imaging,
6.2	SLO-1	Characteristics of Laser	Working principle	Heat transport	Diagnostic Applications of Lasers in cardiology	FLIM Raman Spectroscopy and Imaging
5-3	SLO-2	Construction and working principle of laser system	Molecular Laser Construction	Heat effects	Therapeutic Applications of Lasers in cardiology	FLIM – Holographic and speckle
64	SLO-1	Mono-chromaticity, Coherence	Working principle	LASER induced interstitial thermotherapy (LITT)	Lasers in Surgery	Laser hazards
S-4	SLO-2	Directionality, Brightness	Dye Laser Construction	Photoabalation	Tissue welding and Soldering	Laser hazards

6 E	SLO-1	Pumping mechanism	Working principle	Model, cytotoxicity of UV radiation	Lasers in urology- Lithotripsy	Laser hazards classification
3-0	SLO-2	Optical pumping	Semiconductor Laser Construction	Plasma induced ablation	Therapeutic applications of Lasers in urology	Laser hazards classification
6.6	SLO-1	Electrical pumping	Working principle	Model, analysis of plasma parameters	Laparoscopy- System description	Laser hazards to eye and skin
3-0	SLO-2	Laser pumping, Levels of laser	Gas Laser Construction	Photo distribution	Applications of laser in Gynecology	Viewing laser radiation
67	SLO-1	Resonators	Working principle	Plasma formation	Applications of laser in Gynecology	Non beam hazards
3-1	SLO-2	Q-switching	Chemical Laser Construction	Shock wave generation	Applications of laser in laryngeal surgery	Non beam hazards
c 0	SLO-1	Methods of Q-switching	Working principle	Shock wave generation	Applications of laser in Otology	Laser safety control
3-0	SLO-2	Gain switching	Metal-vapor lasers construction	Cavitation	Applications of laser in neurology	Laser signage
6.0	SLO-1	Mode locking and its types	Working principle	Jet formation.	Applications of Lasers in dentistry	Laser risk management
S-9	SLO-2	Cavity damping	Free-electron laser construction and working	Jet formation.	Applications of Lasers in Orthopedics	Good laser safety practices

Learning Resources

Leon Goldman, M.D., & R.James Rockwell, Jr., Lasers in Medicine, Gordon and Breach 1. Science Publishers Inc., 1975. Abraham Katzir, Lasers and Optical Fibers in Medicine, Academic Press Edition, 1998. Markolf H.Niemz, _Laser Tissue Interaction-Fundamentals and Applications", Springer, 2. 3. Third edition, 2007.

Tuan Vo Dirh, Biomedical Photonics – Handbook, CRC Press, Bocaraton, 2003. Glasser, O., Medical Physics – Vol 1, 2, 3 Adam Hilgar Brustol Inc, 1987. G.David Baxter, Therapeutic Lasers – Theory and practice, Churchill Livingstone Publications 4. 5. 6.

Learning Assessm	nent												
	Diagm's			Con	tinuous Learning Ass	essment (50% weight	tage)			Final Examinatio	n (EO9/ waightaga)		
	DIUUIII S	CLA –	1 (10%)	CLA – 2	2 (15%)	CLA –	3 (15%)	CLA – 4	(10%)#		n (50% weightage)		
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice		
Loval 1	Remember	20.0/		20.0/		20.0/		20.0/		200/			
Level I	Understand	30 %	-	30 %	-	30 %	-	30 %	-	30%	-		
Lovel 2	Apply	10.9/		40.0/		10.0/		10.0/		109/			
Level Z	Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-		
Lovel 3	Evaluate	30 %		30 %		30 %		30 %		30%			
Level J	Create	50 78	-	50 78	-	50 78	-	50 78	-	5070	-		
	Total	10	0 %	100) %	10	0 %	100) %	100 %			

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldive	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1. Dr. P.Vinupritha, SRMIST

														•		_	Professional F		Profession		Professional Electives				L	Т	Р	С
Course Co	de	18BME2651	Course Name		ARTIFICIAL ORGANS AND TIS	SUEEN	NGIN	IEERII	RING				Cours	se Cate	gory	E		Pro	tessior	al Elec	tives		3	0	0	3		
Pre-requ Cours	uisite ses	Basic	Biology and Biomat	erials	Co-requisite Courses			Nii	I					Progre Cour	essive ses						Nil]		
Course Offe	ring Depa	artment		Biomedical E	ngineering [Data Bo	ook /	Code	es/Stand	ards									Nil]		
Course Learr	ning Ratio	nale (CLR):	o study the learners omaterials and vario	to acquire knowle ous biomaterials u	dge to the basic properties of sed in biomedical applications.		L	Learn	ing Program Learning Outcomes (PLO)]												
CLR-1 :	learn the	fundamentals of v	arious organs				1	2	3	3 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15					1													
CLR-2 : CLR-3 : CLR-4 : CLR-5 : CLR-6 :	LR-2: Study the different biomaterials used in artificial organs LR-3: Acquire basic knowledge of various types of artificial organs LR-4: Familiarize with basic biological system in human system LR-5: Obtain the concept of different types biomaterials applied in-vitro test tissue engineering application LR-6: Have an Gain the knowledge about technology transfer and ethical problem				test tissue engineering application cal problem		evel of Thinking (Bloom)	xpected Proficiency (%)	xpected Attainment (%)		ngineering Knowledge	roblem Analysis	esign & Development	nalysis, Design, esearch	odern Tool Usage	ociety & Culture	nvironment & ustainability	thics	dividual & Team Work	ommunication	roject Mgt. & Finance	fe Long Learning	so - 1	SO - 2	SO - 3			
CLO-1 :	Understa	nd the basic Know	ledge of artificial org	ans			<u> </u>	<u>ய</u> 80%	· 10%	_	<u>ش</u> L	ā	ă	ĀΫ	<u>Š</u>	ŭ	ப்ல	Ш	Ē	ŏ	Ē		<u>č</u>	č	M	-		
CLO-2 :	Analyze	various types of ma	terials used in impla	ant applications.			2	80%	70%	_	L				M							М			M	-		
CLO-3 :	Explain t	he process of impo	rtance of Tissue org	anization			2	80%	70%	_	L				М							L			М	-		
CLO-4 :	Select ap	propriate class of p	oolymers using scafi	fold applications			3	80%	% 70% M L M M						1													
CLO-5 :	Understa	nd the concepts di	fferent types biomate	erials applied in-vi	itro and in-vivo biomedical implant applica	ation.	3	80%	70%		М											М	М	М		1		
CLO-6 :	0-6 : Apply the various biomaterials used in implants and artificial organs				ns		3	80%	70%		М		М	Н										М	М]		

		Basics of artificial organ	Types of Artificial organs	Basics concepts of tissue engineering	Types and application of tissue engineering	Recent advancement of tissue engineering
Duratio	n (hour)	9	9	9	9	9
S-1	SLO-1	Introduction -artificial organ	Introduction to Biomaterials in Ophthalmology	Introduction to Tissue engineering	Scaffolds for tissue engineering	Immunochemical techniques in tissue engineering and biomaterial science
0-1	SLO-2	Immunological considerations	Anatomy of eye	Cell source	Classes of potential scaffold materials	Basic immunological principles
S-2		Blood transfusion	Viscoelastic solution	Types of cell Sources	The criteria for an ideal scaffold	Common immunochemical techniques used in biomaterials
	SLO-2	Artificial kidney	Contact lenses	Three-dimensional interactions	Polymer scaffolds	Immunochemical applications in biomaterial science and tissue engineering research
	SLO-1	Cardiovascular organ	Optical implants	Cells as therapeutic Agents with examples, Cell numbers and growth rates.	Polymer scaffolds applications	Clinical applications of tissue engineering
S-3	SLO-2	Vascular organ	Scleral buckling materials for retinal detachment	Tissue organization	Bioactive ceramic scaffolds	Cell source, Stable 3D constructs
S-4	SLO-1	Cardiac pacemakers	Artificial exchange systems: Blood viscosity	Tissue Components,	Bioactive ceramic scaffolds and its applications	Cartilage
	SLO-2	Introduction to Kidney organ	Effects of shear on blood cells	Tissue types, Functional subunits.	Substrate Scaffold Materials	Tendons, ligaments and bone

	SLO-1	Artificial Kidney	Blood–air interactions	Tissue Dynamics, Dynamic states of tissues	Nano Composites	Regeneration in the cardiovascular system
S-5	SLO-2	Artificial Lung	Blood flow in artificial devices	Homeostasis in highly prolific tissues and Tissue repair. Angiogenesis	Control of architecture	3D printing techniques in cardiac stent and bone scaffold
S-6	SLO-1	Liver implant	Exchangers	Measurement of cell characteristics - cell morphology	A guide to basic cell culture and applications in biomaterials and tissue engineering	Regulatory classification of biomaterials and medical devices
	SLO-2	Artificial Pancreas	Hemodialysis	Cell number and viability	sterilization of scaffolds	Classification of medical devices
	SLO-1	Bone, Bone Marrow, and Hands	Soft Tissue Applications	Cell-fate processes, cell motility,	Sterilization methods	Differences between FDA and EU regulations
S-7	SLO-2	Skin and Hair organ	Bulk space fillers	Cell function.	Cell culture protocols	How do companies get through the FDA Process?
	SLO-1	Artificial ear	Maxillofacial implants	Cell-extracellular matrix interactions -	Basic techniques for assessment of cell viability	Technology transfer and Technology transfer paths
5-8	SLO-2	Artificial Nose	Fluid transfer implants	Binding to the ECM, Modifying the ECM, .	culture environment	Efficient technology transfer and Factors affecting rapid technology transfer
	SLO-1	Regeneration and Potential Future Uses for Stem Cells	Functional load-carrying and supporting implants	Malfunctions in ECM signaling	maintenance of cells in vitro, cryopreservation	Ethical issues, The ethical problem and Moral uncertainties
S-9	SLO-2	Ethical consideration	Microencapsulation of live animal cells	Direct Cell-Cell contact - Cell junctions in tissues, malfunctions in direct cell-cell contact Signaling.	Regeneration stimulated electrically	Principles of distributive justice, Sources of conflict and Specific ethical concerns about biomaterials
Learning		Learning Resources				
Resources	s	1. Larry L. Hench and Julian R. Jon	es, Biomaterials, artificial organs and tissue e	ngineering, CRC Press 2010		
	-	Sujata V. Bhat "Biomaterials" spr	inger 2002			

Learning Asse	essment										
	Ploom's			Cor	ntinuous Learning Ass	essment (50% weight	tage)			Final Examinatio	n (50% weightage)
	DIOUIIIS	CLA –	1 (10%)	CLA –	2 (15%)	CLA –	3 (15%)	CLA – 4	(10%)#		ii (50 % weiginage)
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	40 %	-	40 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Evaluate	20 %	-	20 %	-	20 %	-	30 %	-	30%	-
	Create	10	0 %	10	0 %	10	0%	100	1 %	10	0 %
	i Ulai	I. I.	0 /0	10	0 /0	10	0 /0	100	J /0	I. I.	/0 /0

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldive	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1., Dr.Gnanavel, SRMIST

			0		Diama	P						•			-		D			- P		L	Т	Ρ	С
Course Co	ae	18BME2001	Course Name		Biome	edical Nano techr	lology								3	0	0	3							
Pre-req Cour	uisite ses		Nil		Co-requisite Courses			Nil						Progre Cour	ssive ses						Nil				
Course Offe	ring Dep	artment		Biomed	lical Engineering		Data Book /	Codes	s/Standar	rds									Nil						
Course Lear	ning Ratio	onale (CLR):	To study of biomat applicatio	the learners to acqu erials and various bi ns.	ire knowledge to the ba iomaterials used in bion	asic properties nedical		Learni	ng		Program Learning Outcomes (PLO)														
CLR-1 :	Attain th	e knowledge on diff	erent synthesis m	ethod and applicatio	n of Nano material		1	2	3		1	2	3 4 5 6 7 8 9 10 11 12 13 14 1					15							
CLR-2 : CLR-3 : CLR-4 : CLR-5 : CLR-6 :	Study th Acquire Familiai Have ar	te phenomena vario knowledge importar ize with biological sj Gain the knowledg	us characterization ace of nanotechno istem, prosthetic a e about nano mate	n techniques used in logy based biomedia and medical implants erial used in biomed	n Nano material methoc cal diagnostics s in nanotechnology ical application		evel of Thinking (Bloom	er dr 1 mukung (Broom) ected Proficiency (%) ected Attainment (%) ign & Development ign & Development ign & Development igns, Design, earch ien Tool Usage ieity & Culture ieity & Culture ieity & Culture cs cs				ommunication	roject Mgt. & Finance	fe Long Leaming	SO - 1	SO - 2	SO - 3								
	Explain	the familiarity with d	ifforant synthosis	mothod and applicat	tion of Nano matorial in	modical applicat	ion 1.2	<u>نن</u> 80%	<u>نن</u> 70%	-	Ē	ā	Ō	ĂΫ	N N	Š	шō	ш	<u>_</u>	Ő	Ā	-	ä	ă.	M
CLO-1 :	Analyze	the phenomena tak	ing various charad	cterization technique	s used in Nano materia	al method	2	80%	70%	L					M							M			M
CLO-3 :	Explain	the process of impo	tance of nanotecl	nnology based biom	edical diagnostics		2	80%	70%	L							М								
CLO-4 :	Select a nanotec	ppropriate class of hnology	Nano materials us	ing knowledge of, p	rosthetic and medical in	mplants in	3	80%	70%	M L M M				М											
CLO-5 :	Underst	and the concepts of	biomedical applic	ation of different org	anic particles		3	80%	70%	70% M M M M				М											
CLO-6 :							3	80%	70%	70% M H H M M				Μ	М										

		Nano materials preparation techniques	Characterization techniques of Nano Material	Nanotubes and its applications	Biomedical implants in nanotechnology	Organic - Inorganic nanoparticles and is applications
Duratio	on (hour)	9	9	9	9	9
S_1	SLO-1	Introduction - synthesis Nano material	Introduction to Nano scale phenomena	Introduction to carbon Nano tube and its types	Introduction to prosthesis and implants	Introduction to Nano-bio conjugates
0-1	SLO-2	Types of bulk synthesis Material	Nano particle determination	Carbon Nano tube for biomedical application	Nano materials used in Neural implant	Nano-bio conjugates and their significance
6.2	SLO-1	Top Town approaches	Introduction to characterization techniques	Introduction to Improved diagnosis by in vivo imaging	Recent and advancement in Neural implant	Introduction -Nano Biodegradable material
5-2	SLO-2	Bottom up approaches	X-Ray diffraction method	Types of In vivo imaging and its application	Nano materials and coating used in HIP implant	Nano Biodegradable material for biomedical application
	SLO-1	Insert Gas condensation techniques	Particles size determination	Detection of tumors for Nano materials	Recent and advancement in Hip implant	synthesis methods of Magnetic nanoparticles
S-3	SLO-2	Application of gas condensation techniques	Principle of Scanning electron microscopy	Nano particle using drug delivery system	Knee implant coating in Nano technology	Magnetic nanoparticles for biomedical application
54	SLO-1	Types of Physical Vapour deposition Method	Construction and working of SEM	Different types in drug delivery system	Recent advancement in Knee implant	Multi-functional inorganic Nano particles
3-4	SLO-2	Sputtering Techniques	Application of SEM	Nano particle using genetic defect diagnostics	Nano materials and coating used in Dental implant	Multi-functional inorganic Nano particles for biomedical application
S-5	SLO-1	Evaporation techniques	Energy dispersive X-ray spectroscopy	Introduction to Nano robotic medical devices	Recent advancement in Dental implant	Carbon nano tube (CNT) based inorganic Nano particles

	SLO-2	Chemical evaporation techniques	EDS Using elemental analysis	Application of Nano robotic medical devices	Nano Technology in ocular implant	Biomedical application of CNT based inorganic Nano particles.
S-6	SLO-1	Laser ablation method	Principle and working of Transmission electron microscope	Cantilever Sensors in biomedical application.	Recent advancement in Ocular implant	Carbon nano tube (CNT) based organic Nano particles
0-0	SLO-2	Pulsed laser deposition	Application of TEM	Introduction to Nano material in medical imaging	Nano Technology in ear implant	Biomedical application of CNT based organic Nano particles.
S-7	SLO-1	Introduction to chemical synthesis	Principle and working of atomic force microscope	Magnetic resonance imaging based contrast reagent used in Nano particles	Recent advancement in ear implant	Introduction to Nano biosensor
0-7	SLO-2	Sol gel process and micro emulsion method	Application of AFM	Organic Nano particles and Its applications	Artificial skin in Nano material	Nano Biosensor: Fabrication methods
S-8	SLO-1	Hydrothermal process and wet chemical	Fourier transform infrared (FTIR) spectroscopy and its application	Nanoprobes for CT images	Introduction to regenerative medicine in Nano technology	Nano Materials based in breathing gas sensor
	SLO-2	Spray pyrolysis Techniques	Application of Scanning probe microscopy (SPM)	Different types of nanoprobe in CT image	Tissue engineering in nanotechnology	Fabrication of breathing gas sensor
8.0	SLO-1	.0-1 Spin coating methods Contact angle measurement		PET based contrast reagent used as a Nano particle.	Nano fiber scaffold technology	Glucose Nano sensor for Diabetic diagnostics
S-9	SLO-2	Electrochemical deposition method	Nano indentation techniques	SPET based contrast reagent used as a Nano particle.	Nano fiber scaffold technology in Biomedical application	Nano oxygen sensor and its application.

1.W.Gaddand, D.Brenner, S.Lysherski and G.J.Infrate(Eds.), "Handbook of NanoScienceEngineering and Technology", CRC Press, 2013
2.K. Barriham, D.D. Vvedensky, "Low dimensional semiconductor structure fundamental and device applications", Cambridge University Press, 2010
REFERENCE BOOKS / OTHER READING MATERIAL
1.Cao, G, Nanostructures Nanomaterials Synthesis: Properties Applications", Imperial College Press, 2011. Brian, R Eggins; Wiley; New York, Chichester, 3rdedition, 2012
2.Allen J Bard and Larry R Faulkner; Wiley, "Electrochemical Methods: Fundamentals and Applications", New YorkChichester, 4th edition, 2009
3. David Wild; "The Immunoassay Handbook", Elsevier, 4thedition, 2013.

Learning Assessm	nent											
	Diaam'a		Final Examination (50% weightage)									
	DIOUIIIS	CLA –	1 (10%)	CLA –	2 (15%)	CLA –	3 (15%)	CLA – 4	¥ (10%)#		r (50 % weightage)	
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	
Lovel 1	Remember	40.0/		10.0/		10.0/		20.0/		200/		
Level I	Understand	40 %	-	40 %	-	40 %	-	30 %	-	30%	-	
Lovel 2	Apply	40.0/		10.0/		10.0/		10.0/		400/		
Leverz	Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-	
Lovol 3	Evaluate	20 %		20.%		20.%		30 %		30%		
Level 5	Create	20 70	-	20 70	-	20 /0	-	50 70	-	5078	-	
	Total	al 100 % 100 %			10	0 %	10	0 %	100 %			

Course Designers											
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts									
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldive	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1., Dr.Gnanavelu, SRMIST									

																					L	Т	Р	С
Course Code	18BME2671	Course Name			BIOMETRICS						Course Category		Course Category E Professional Elective			3	0	0	3					
	1																							
Pre-requis Courses	ite			Co-requisite Courses	te Progressive Courses																			
Course Offerin	g Department	Biomedi	cal Engineering			Data Book /	Code	les/ Sta	ndards	6			Vil									· · · · · · · · · · · · · · · · · · ·		
						·																		
Course Learni	ng Rationale (CLR):	The purp	ose of learning this cou	urse is to:			Learn	ning						F	rograr	n Learr	ning O	utcome	s (PLC))				
CLR-1 :	Understand the basics of	of biometric systems	3			1	2	2 3		1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Acquire the knowledge	about the finger prin	t and hand geometry i	recognition		_						,	-		0			۶			ğ			Ð
CLR-3 :	Utilize the knowledge in	face recognition sy	stem			ting			_		.io/	5	ign		ture	~		ear	5		ц.	1	eci	lyz
CLR-4 :	Identitly the applications	of biometrics in ga	it recognition.			-in		6)	t (%	p		3	Des	8	Cul	lity at	1	× ∞	catio	Jt. 8	Lea	al al	er jo	רם חר
CLR-5 :	Analyze the concepts of	voice biometrics				τ J	ed ~	ed	leni	eric	ag d	∞	bm s, [<u>مە</u>	idbi		a	jūr	Š.	۱ور	T:	i i i i	3: /
	, ,						ect	ficie	Ľ	- ine		igi is	lysi		iety	tair	S	k ki	Ĩ	ect	Po	- ess) – ese
Course Learning	ng Outcomes (CLO):	At the en	d of this course, learne	ers will be able to:		Le c	E C	P of	Atta	Eng		Des 2	Ana	Moc	Soc	Sus	Ē	Vor	ы Б	Proj	Life	N D 4	Nar P	8 R
CLO-1 :	Analyze the performanc	e and characteristic	s of biometric systems	3		3	80	0 75		M									-			Μ		
CLO-2 :	Explain the image proce	essing techniques u	sed in finger print tech	nology		3	80	0 70		Μ												1	М	
CLO-3 :	LO-3 : Illustrate the concepts of face recognition system in 2D and 3D imaging						75	5 70		М														М
Implement the gait algorithm in gait recognition process and perform on line signature verification using					2	0/	0 70																	
image processing techniques					3	80	0 75				IV			1]						1 I	IVI	
CLO-5 :	Analyze the concept of palm print identification system					3	80	0 70					Μ			1								М
CLO-6:	Explain the application of voice biometrics technology						80	0 70					М											М

		Fundamentals of biometrics	Finger print and Hand geometry recognition	Face Recognition	Gait Recognition and Palm print identification	Voice biometrics
Duratio	on (hour)	9	9	9	9	9
6.4	SLO-1	Introduction to biometrics	Introduction to finger print technology	Face recognition -Introduction	Gait -Introduction	Voice biometrics-Technology
3-1	SLO-2	Definition and Evolution	General description		Human ID gait challenge problem	
6.2	SLO-1	Operation of biometric systems	Finger print sensing-optical sensors	Techniques-Eigen faces, Linear discriminant analysis	Base line gait Algorithm	Identity information in the speech signal
5-2	SLO-2	Block diagram description	Solid state sensor and ultrasound sensors	Independent component analysis , Local feature analysis	Base line gait Algorithm	Language generation and speech production
S-3	SLO-1	Biometric functionalities	Feature extraction-segmentation	Face recognition databases-FRGC,FERET	Recognition Approaches-Temporal alignment	Feature extraction and Tokenization-short term analysis
	SLO-2	Verification vs identification	Enhancement, minutiae extraction	PIE, AR,Yale face database	Shape based approach	parameterization
S-4	SLO-1	Performance of biometric systems	Finger print matching-correlation based methods	Advanced correlation filters	Palm print identification system-block diagram	Phonetic and word Tokenization
	SLO-2		Rigid feature based techniques	Kernel class dependent analysis	Image preprocessing techniques	Prosodic Tokenization
S-5	SLO-1	Biometric system errors-failure to acquire	Performance evaluation-finger print verification competition	Support vector machine for classification	Feature extraction	Text dependent speaker recognition- classification
	SLO-2	Failure to enroll	Finger print vendor technology evaluation	Algorithm	Feature matching	Databases and benchmarks
S-6	SLO-1	Benefits of biometrics	Synthetic finger print generation	Tensor faces method-multilinear analysis of training images	Online signature verification	Text –independent speaker recognition-short term spectral systems
	SLO-2	Parameters of good biometrics	Securing finger print based biometric systems	multilinear analysis of testing images	Architecture	Idiolectal systems
6.7	SLO-1	Application of biometrics-Forensics	Hand geometry: Historical perspective	3D sensor and data for face recognition	Data acquisition and preprocessing	Phonotactic systems
3-1	SLO-2	Government, commercial	Modern hand reader		Feature extraction and enrolment	Prosodic systems
S-8	SLO-1	Characteristics of biometrics	Processing steps –hand capture, processing	3D Face image processing-smoothing	Similarity computation	Applications of voice biometrics-voice authentication
	SLO-2	Commonly used biometrics characteristics	Classification, template adaptation	Local feature extraction	Matching	Speaker detection
S-9	SLO-1	Accuracy in biometric systems	Performance metrics	Representation and features for 3d face recognition- Global and local set point model	Resources for online signature verification systems-Reference systems	Strength of voice biometrics

SLO-2	Legal consideration in use of biometric systems	Standardization	Deformation model	On-line signature databases	Weakness
Learning Resources	 Anil K jain, Patrick F John D. Woodward, J. Wayman, A. Jain, 	Flynn, Arun A. (Eds.), Handbook of Biometrics, S Jr. Nicholas M. Orlans Peter T. Higgins, "Biome D. Maltoni and D. Maio (Eds.), Biometric Syste	Springer, 2008. trics", dreamtech, 2003 ms: Technology, Design and Performance Eva	luation, Springer, 200	

Learning Assessment														
	Dia ami'a		Continuous Learning Assessment (50% weightage)											
	BIOOM S	CLA –	1 (10%)	CLA –	2 (15%)	CLA –	3 (15%)	CLA – 4	l (10%)#		r (50% weightage)			
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice			
Loval 1	Remember	20.0/		20.0/		20.0/		20.0/		200/				
Level I	Understand	30 %	-	30 %	-	30 %	-	30 %	-	30%	-			
	Apply	10.0/		10.0/		10.9/		10.9/		100/				
Leverz	Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-			
Loval 2	Evaluate	20.0/		20.0/		20.0/		20.0/		200/				
Levers	Create	30 %	-	30 %	-	30 %	-	30 %	-	30%	-			
	Total 100 %				0 %	10	0 %	10	0 %	100 %				

Course Designers											
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts									
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldive	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1.Dr.U.Snekhalatha, SRMIST									

Course Code	18BME3611	Course Name			BIOMEN	ΛS	C Ca	ourse itegor	y y	E	Professional Elective				L 3	Т 0	P 0	C 3						
Pre-req Cours	uisite ses			Co-requisite Courses	Nil		Pro	ogres: Course	sive es	Nil														
Course Offering Department Biomedical Engineering Data Book / Codes/Standards Nil																								
Course Le	burse Learning Rationale (CLR): The purpose of learning this course is to:													Pro	gram	Learn	ing O	utcom	nes (P	LO)				
CLR-1 :	Understand the fun	lamental principle	s of microsensors	and microactuators	3		1	2	3		1	2	3 4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 : CLR-3 : CLR-4 : CLR-5 : CLR-6 :	Get an idea about t Acquire an idea about t Get an idea about t Get an idea about t Understand the diff	ne materials used ut the micromach ne biomedical app ne research base rent biomedical a	in MEMS and fab ining lication of MEMS d development in t application of MEN	rication processes in POCT he area of BioMEM IS	S		Thinking (Bloom)	d Proficiency (%)	d Attainment (%)		sring Knowledge	n Analysis	& Uevelopment s, Design,	Tool Usage	& Culture	ment & abilitv		al & Team Work	nication	Mgt. & Finance	g Learning			~
Course Le	arning Outcomes (CLO): At the	end of this course	, learners will be ab	le to:		Level of	Expecte	Expecte		Enginee	Problem	Design Analysis Despara	Modern	Society	Environ Sustain	Ethics	Individu	Commu	Project	Life Lon	PSO - 1	PSO - 2	PSO-0
CLO-1 :	Analyze the working	principle of MEN	IS & Microsystems	s in healthcare doma	ain		1, 2	80	70		М	-		-	-	-	-	-	-	-	-	-	-	-
CLO-2: Explain the micro system fabrication processes and materials used for MEMS						1, 2	80	70		М	-		-	-	-	-	-	-	-	-	М	-	-	
CLO-3 : Differentiate the various Micromanufacturing techniques						2	80	70		-	-	L -	-	-	-	-	-	-	-	-	М		-	
CLO-4 :	Illustrate the conce	ts of BioMEMS ir	POCT				1	80	70		-	-	L -	-	-	-	-	-	-	-	-	-	М	-
CLO-5 :	CLO-5: Illustrate the concepts of BioMEMS with suitable examples						1	80	70		-	-	L -	-	-	-	-	-	-	-	-	-	-	-
CLO-6 :	CLO-6 : Outline the research areas in the field of BioMEMS						1,2	80	70		-	-	L -	-	-	-	-	-	-	-	-	-	-	-

Durati	on (hour)	MEMS and Microsystem	MEMS Materials and Fabrication Processes	Overview of Micro-manufacturing	BioMEMS-1	BioMEMS-2
Durau	on (nour)	9	9	9	9	9
6.1	SLO-1	MEMS and microsystems- Introduction	Substrates and wafers	Micro-Machining- Introduction	Introduction to BioMEMS	Microcantilever BioMEMS
3-1	SLO-2	Typical MEMS and microsystem products	Silicon as a substrate material	Micromachining Techniques	Home Pregnancy Test	Basic Principles of Sensing Biomechanical Interactions
S-2	SLO-1	Difference between MEMS and Microsystems	between MEMS and Microsystems Silicon compounds, Silicon piezoresistor Bulk Micromanufactu		Lab on a Chip	Detection Modes of Biomechanical Interactions- Static Mode
	SLO-2	Application of Microsystems in healthcare industry	Gallium arsenide, Quartz	Steps in Bulk Micromanufacturing	Lab on a cellphone	Detection Modes of Biomechanical Interactions- Dynamic Mode
6.2	SLO-1	Working Principles for Microsensor	Piezoelectric crystals, Polymers	Construction of a Microcantilever using BM	Mobile Point of Care Monitors	Fabrication and Functionalization of Microcantilevers
5-3	SLO-2	Types of microsensors: Chemical Sensors	Packaging materials	Types of Etching process in bulk micromanufacturing	DNA Sensors	Fabrication and Functionalization of Microcantilevers
6.4	SLO-1	Biomedical Sensors & Biosensor	Photolithography	Types of Etching process in bulk micromanufacturing	Drug Delivery- Insulin Delivery	Tissue scaffold fabrication using MEMS approaches
3-4	SLO-2	Optical Sensors	Ion implantation	Surface Micromachining (SM)	Artificial Retinal Prosthesis	Tissue scaffold fabrication using MEMS approaches
6 E	SLO-1	Pressure Sensors	Diffusion	Construction of a Microcantilever using SM	Endoscopic Wireless Pill	Applications of MEMS-fabricated tissue scaffold
S-5	SLO-2	Pressure Sensors	Oxidation	Steps in Surface Micromachining	Medtronic Reveal	Applications of MEMS-fabricated tissue scaffold

8.6	SLO-1	Thermal Sensor	Chemical vapor deposition (CVD)	Steps in Surface Micromachining	Microsystem Approaches to PCR	Paper-Based Microfluidic Devices
3-0	SLO-2	Acoustic Wave Sensors	Types of CVD	LIGA	Microsystem Approaches to PCR	Paper-Based Microfluidic Devices
S-7	SLO-1	Working Principle for Microactuator	Physical vapor deposition (PVD)	Steps in LIGA process	Implantable Microelectrodes	Lens-Based Glucose Sensor
	SLO-2	Actuation using Thermal Forces	Types of PVD	Difference between LIGA, SM, BM	The Michigan Probes	Lens-Based Glucose Sensor
c .	SLO-1	Actuation using Shape-Memory Alloys, Piezo- Electric Crystals	Epitaxy	Difference between LIGA, SM, BM	The Utah Electrode Array	Catheter based sensors
3-0	SLO-2	Actuation using Electrostatic Forces, Magnetic field	Types of Epitaxy	Applications of LIGA	Microfabricated Cochlear Implants	Catheter based sensors
	SLO-1	Application of Microactuations	Etching	Applications of Surface Micromachining	Microfabricated Electrocorticography Arrays	Microneedles
S-9	SLO-2	Application of Microactuations	Types of Etching	Applications of Bulk Micromachining	Microelectrodes for Visual Prostheses	Types of Microneedles

Learning Resources	 Tai-Ran Hsu, "MEMS & Microsystems- Design, Manufacture and Nanoscale Engineering John Wiley & Sons, 2nd Edition, 2008 Nitaigour PremchandMahalik, "MEMS", Tata McGraw Hill, 2nd Reprint, 2008 Steven S. Saliterman, "Fundamentals of BioMEMS & Medical Microdevices", International Society for Optical Engineering, 1st Edition, 2006 Ellis Meng, "Biomedical Microsystems", CRC Press, 1st Edition, 2011 Simona Badilescu and Muthukumaran Packirisamy, "BioMEMS Science and Engineering Perspectives", CRC 	 Wanjun Wang & Steven A.Soper, "BioMEMS- Technologies and applications", CRC Press, 1st Edition, 2007 Walter Karlen and Krzysztof Iniewski, "Mobile Point-of-Care Monitors and Diagnostic Device Design", CRC Press, 1st Edition, 2015 Chao-Min Cheng, Chen-MengKuan & Chien-Fu Chen, "In-Vitro Diagnostic Devices: Introduction to Current Point of Care Diagnostic Devices", Springer, 1st Edition, 2016 Mel L. Mendelson, "Learning Bio-Micro-Nanotechnology", CRC Press, 1st Edition, 2013
	 Simona Badilescu and Muthukumaran Packirisamy, "BioMEMS Science and Engineering Perspectives", CRC Press, 1st Edition, 2011 	10. Mel L. Mendelson, "Learning Bio-Micro-Nanotechnology", CRC Press, 1st Edition, 2013
	6. Albert Folch, "Introduction to BioMEMS", CRC Press, 1st Edition, 2013	

Learning Assessm	Learning Assessment													
	Dia ami'a			Cor	ntinuous Learning Ass	essment (50% weigh	tage)			Final Eventination	(EOO)			
	DIOUIIIS	CLA –	1 (10%)	CLA – 2 (15%)		CLA –	3 (15%)	CLA –	4 (10%)#	Final Examination (50% weightage)				
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice			
Lovel 1	Remember	10.0/		10.0/		10.0/		20.0/		200/				
Level I	Understand	40 %	-	40 78		40 70	_	30 %	-	30%	-			
	Apply	10.0/		10.0/		10.0/		10.9/		100/				
Leverz	Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-			
Loval 2	Evaluate	20.0/		20.0/		20.0/		20.0/		200/				
Level 5	Create	20 %	-	20 %	-	20 %	-	30 %	-	30%	-			
	Total	10	100 % 100 % 100 %		0 %	10	10 %	100 %						

Course Designers									
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts							
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldive	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1. Ms Oinam Robita Chanu, SRMIST							

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Course Cod	le 20BME363T	Course Name	HUMAN	ELECTROPHYS	IOLOGY				Cou	urse Cat	tegory	E		Professional Elective		Professional Elective			3	0	0	3
-											_	-	1							t		
Pre-requisite Anatomy and Physiology Courses Courses		Nil				Progressive					Nil											
Course Offer	ing Department		Biomedical Engineering		Data Bool	k / Codes	/Standards									Nil						
Course Lear	ning Rationale (CLR):	The purp	ose of learning this course is to:			Learni	ng					P	rogram	Learn	ing Ou	utcome	es (PLC)		·		
CLR-1 :	Understand cell elcrophysiol	ogy			1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Know about neuronal communication					y	t											се				
CLR-3 :	Learn about electrophysiology at neuromuscular junctions				_	enci	nen		S		-	age	a)			E		nan	б			
CLR-4 :	Understand the cardiac elect	rophysiology			kinc	ofici	ainr		lysi		sign	Us	lture	∞.		ear	ы	і. Х	in			
CLR-5 :	Understand the importance of	of neural control w	vith other body systems		E	Pro	Att	p p	na	ent	Ğ		Cu	ii a		8_1	cati	jt.	Lee			
CLR-6 :	Explore the latest technologi	es with Electroph	vsiology studeies		J I	eq	eq	erir edg	, ⊲ Ε	∞ m	is, l	n Tc	/ &	ab db		ual	nii	ъ	lgn	~	2	e
					on	ect	ect	wle	olei	elo elo	llys ea	leri	iet	taii	S	iž F	E	eci	Ľ	Ċ	-	Ġ
Course Lear	ning Outcomes (CLO):	At the en	d of this course, learners will be able to:		(Bic	(%) (%)	(%) (%)	Kno	Pro	Des Dev	Ana Res	Moc	Soc	Sus	Ethi	Noi Wo	Cor	Po	Life	PSC	PSC	PSC
CLO-1 :	Describe the physiology of co	ellular communica	ation		1, 2	80%	70%															
CLO-2 :	Explain how neuron communicate and about perception				2	80%	70%															
CLO-3 :	Elaborate on hoe skeletal mu	iscles working wi	h neural system		2	80%	70%															
CLO-4 :	Describe how human system	is are controlled l	by the electrical signals from btrain		3	80%	70%															
CLO-5 :	Explain the cardiac electrophysiology			3	80%	70%		L														
CLO-6 :	Undertake basic electrophys	iological studies ι	ising EEG and other acquired signals.		3	80%	70%			М	L	L									L	

		Cell electrophysiology	Neural communication and perception	Neuromuscular physiology	Electrophysiology of human systems	Electrophysiology studies
Duratio	n (hour)	9	9	9	9	9
C 1	SLO-1	Physiology- levels of organization in the body	Synapse	Autonomic nervous system	Heart anatomy review	Electrophysiology studies (EPS)
3-1	SLO-2	Concept of homeostasis	Process involved in synapse	Somatic nervous system	Electrical activity of heart	Facts -EPS
S-2	SLO-1	Homeostasis control systems	Intracellular communication	Neuromuscular junction	Pacemaker activity	Need for EPS
3-2	SLO-2	Cell structure overview	Signal transduction	Chemical linkage	Refractory periods	Risks involved
6.2	SLO-1	Plasma membrane structure	Organization of nervous system	Skeletal muscles	ECG- Spread of electrical activity	Procedure involved
5-3	SLO-2	Plasma membrane functions	Organization of nervous system- Overview	Skeletal muscles structure and functions	ECG- diagnostic applications	Procedure involved ctd.
64	SLO-1	Membrane transport overview	Brain review	Molecular basis of muscular contraction	Cardiac output	Pacing Maneuvers
3-4	SLO-2	Assisted , unassisted transports	Spinal cord review	Skeletal muscle mechanics	Cardiac output and its control	Pace mapping
6.5	SLO-1	Membrane potential	Peripheral nervous system	Muscle mechanics ctd.	Blood pressure (BP)	Vagal Maneuvers (VM)
3-3	SLO-2	Membrane potential causes	Receptor physiology	Shortening of skeletal muscles	Reflexes responsible for BP	Indications of VM
8.6	SLO-1	Neural communication- Introduction	Pain	Skeletal muscle mechanism	Respiratory mechanics	Technologies for VM
3-0	SLO-2	Graded potentials	Pain perception	Fiber types	Adjustments in ventilation	Special considerations
S-7	SLO-1	Action potential	Eye revisited	Nervous control of motor movements	Nervous control of respiration	Supra ventricular tachycardia (SVT)
3-1	SLO-2	Action potential-generation	Visual perception	Nervous control of motor movements ctd.	Nervous control of respiration ctd.	Causes, types SVT
S_8	SLO-1	Action potential-Propagation	Ear and hearing	Smooth muscle	Nervous control of digestive system	Symptoms of SVT
5-0	SLO-2	All or none law	Ear and equilibrium	Phasic contraction	Defecation reflex	Treatments for SVT
S-0	SL0-1	Myelination	Chemical sensing	Cardiac muscles	Nervous control of excretory system	Latest trends in EPS
0-3	SLO-2	Myelination challenges	Taste and Smell	Blend with smooth and skeletal muscles	Micturition reflex	Future scope

Learning Resources	1. L 2. L 3. L	aura lee Sherwood, "Human Physiology from cell to system", Brooks Cole , 2012. aura lee Sherwood, "Fundamental of Physiology of Excitable Cells", 2010 ionel Opie, "Heart Physiology", Lippincott-Raven, 1998	4. 5.	Aidley, "The Physiology of Excitable Cells", Cambridge Press.,2008 Francis D Murgatroyd, Andrew D. Krahn, "Handbook of cardia Electrophysiology, A practical guide to invasive EP studies and catheter Ablation",Remedica Publisher, 2002
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Course Designers									
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts							
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldive	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1. Dr. Varshini Karthik, SRMIST							

Course Code	18BME364T	Course Name	Biomedi	cal Device Design Fundamentals	Course Category	Е	Professional Elective	L 3	Т 0	P 0	C 3
Pre-requisi Courses	te		Co-requisite Courses	Nil	Progressive Courses) Nil					
Course Offeri	ng Department	Biomedi	ical Engineering	Data Book / Codes/Standards	Nil						

Course Lo	earning Rationale (CLR): The purpose of learning this course is to:	Le	earnir	g]					Prog	gram	Learn	ning O	utcom	ies (Pl	L O)				
CLR-1 :	Understand the basic concepts of design issues in medical devices	1	2	3	1	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Get an idea about the forming applications in the design of medical devices	(-	((
CLR-3 :	Acquire an idea about the laser processing applications	Doc	%)	%)		lge		ŧ						Ar A		e				
CLR-4 :	Get an idea about the machining applications and different advanced techniques	<u>B</u>	nc)	ent		lec		E C		ge				N		ano	0			
CLR-5 :	Acquire an idea about the applications of various technical methods	bu	cie	E E		ě	SiS	g	gu,	Isa	ure			an	c	цЦ ЦЦ	ці.			
CLR-6 :	Get an overall idea about the regulation and protection in medical device design	inki	lof	ttai		дY	ylar	eve	esi	2	Ē	i÷ ⊗		ΤΨ	atio	⊗ŏ i⊥	ear			
		L H	р Ц Ц	d b		, in	٩L	~~ ∞	ۍ ش ا	Ĕ	80	mel		al 8	nic	Mgi	БГ			~
Course Lo	earning Outcomes (CLO): At the end of this course, learners will be able to:	Level of	Expecte	Expecte		Enginee	Problem	Design	Analysi: Resear	Modern	Society	Environ	Ethics	Individu	Commu	Project	Life Lon	PSO - 1	PSO - 2	- OS4
CLO-1 :	Understand the challenges in the Medical Device Industry	1, 2	80	70		H	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-2 :	Have a thorough understanding of typical process parameters	1, 2	80	70		М	-	-	М	-	-	-	-	-	-	-	-	М	-	-
CLO-3 :	Understand the basics of microscale medical device applications	2	80	70	1	-	-	-	М	-	-	-	-	-	-	-	-	L		-
CLO-4 :	Identify the importance of different biomaterials used in device design	1	80	70		Н	-		М	-	-	-	-	-	-	-	М	-	L	-
CLO-5 :	: Analyze the knowledge on machining based fabrication of medical devices			70		-	-	-	М	-	-	-	-	-	-	-	L	-	-	-
CLO-6 :	Extend the basics of safety regulation and protection risk in medical device design			70		Н	-	-	-	-	-	-	-	-	-	-	Н	-	-	-

Durat	ion (hour)	Design Issues in Medical Devices	Forming Applications on Implantable Devices	Laser Processing Applications on Medical Devices	Machining Applications and Advanced Techniques on Medical Implants	Regulation and Protection of Medical Devices
		9	9	9	9	9
	SLO-1	Introduction - Need for Medical Devices	Forming Applications - Forming	Laser Processing procedures	Machinability of Biocompatible Metal Alloys	Minimisation of exposure to radiation
S-1	SLO-2	Technology Contribution to Medical Devices	Typical Process Parameters	Microscale Medical Device Applications	Surfaces Engineering of Metal Implants	Medical devices intended to emit radiation
6.2	SLO-1	Subtractive Technologies	Typical Process Parameters - Temperature	Microscale Medical Device Applications	Surfaces Engineering of Metal Implants	Minimisation of exposure to unintended radiation
3-2	SLO-2	Net-Shape Technologies	Typical Process Parameters - Strain	Processing Methods for Medical Device Fabrication	Wear and Failure of Metal Implants	Medical devices intended to emit ionising radiation – additional requirements
6.2	SLO-1	Additive Technologies	Typical Process Parameters - Strain Rate	Processing Methods for Medical Device Fabrication	Wear and Failure of Metal Implants	Medical devices intended to emit ionising radiation – additional requirements
3-3	SLO-2	Challenges in the Medical Device Industry	Tribology and Micro-Tribology	Processing Methods for Medical Device Fabrication	Wear and Failure of Metal Implants	Medical devices connected to or equipped with an energy source
S-4	SLO-1	Medical Device Development	Tribology and Micro-Tribology	Biomaterials Used in Medical Devices	Micromilling-Based Fabrication of Metallic Microchannels for Medical Devices	Medical devices incorporating electronic programmable systems

	SLO-2	Biomedical Product Life Cycle	Manufacturing Process Chain	Biomaterials Used in Medical Devices	Micromilling-Based Fabrication of Metallic Microchannels for Medical Devices	Safety dependent on internal power supply
<u>с</u> ғ	SLO-1	Biomedical Product Life Cycle	Manufacture of Alloys and Raw Materials	Biomaterials Used in Medical Devices	Machining-Based Fabrication of Polymeric Microneedle Devices	Safety dependent on external power supply
3-0	SLO-2	Medical Device Development Process	Forming	Microjoining of Similar and Dissimilar Materials	Machining-Based Fabrication of Polymeric Microneedle Devices	Medical devices intended to monitor clinical parameters
	SLO-1	Medical Devices' Design Process	Machining and Finishing	Microjoining of Similar and Dissimilar Materials	Degenerative Disc Disease	Minimisation of risk of electromagnetic fields
S-6	SLO-2	Scapholunate Interosseous Ligament	Coating	Microjoining of Similar and Dissimilar Materials	Degenerative Disc Disease	Protection against electrical risks associated with mechanical, vibration, electrical, heat and noise
0.7	SLO-1	Conceptual Design	Packaging and Sterilization	Laser Micromachining for Microfluidics	Intervertebral Spinal Spacers	IEC standards: IEC 60601-2-44: Computed tomography
5-1	SLO-2	Conceptual Design	Implantable Devices	Laser Micromachining for Microfluidics	Intervertebral Spinal Spacers	IEC 60601-2-43: Interventional procedures
	SLO-1	Embodiment Design	Implantable Devices	Laser Micromachining for Microfluidics	Inkjet Technology	IEC 60601-2-45: Mammographic X-ray equipment
S-8	SLO-2	Detailed Design	Bone Implants	Laser Micromachining for Metallic Coronary Stents	Medical Applications of Inkjet Technology	IEC 60601-1-3: Radiation protection in diagnostic X-ray equipment
	SLO-1	Manufacturing a Prototype	Bone Implants	Laser Micromachining for Metallic Coronary Stents	Material Extrusion Technology	IEC 60601-2-54: X-ray equipment for radiography and radioscopy
S-9	SLO-2	Manufacturing a Prototype	Bone Implants	Laser Micromachining for Metallic Coronary Stents	Medical Applications of Extrusion-Based Systems	IEC 60601-2-63: Dental extra-oral X-ray equipment; IEC 60601-2-65: Dental intra-oral X-ray equipment

 Learning
 1.
 Claudio Becchetti, Alessandro Neri, "Medical Instrument Design and Development: From Requirements to Market Placements", Wiley; 1st edition, 2013.
 4.
 Brendan Cooper, "Design Control for Medical Devices: A Short Introduction", Tata McGraw-Hill, New Delhi, 2nd edition, 2016.

 2.
 Andreoni, Giuseppe, Barbieri, Massimo, Colombo, Barbara, "Developing Biomedical Devices Design, Innovation and Protection", Springer, 2014.
 5.
 Paul H. King, Richard C. Fries, Arthur T. Johnson, "Design of Biomedical Devices and Systems", CRC Press, 4th edition, 2018.

 3.
 Tugrul Özel, Paolo Jorge Bártolo, Elisabetta Ceretti, Joaquim De Ciurana Gay, Ciro Angel Rodriguez, Tugrul Özel, Paolo Jorge Bártolo, Elisabetta Ceretti, Joaquim De Ciurana Gay, Ciro Angel Rodriguez, Tugrul Ozel, Paolo Surger, Paolo Jorge Bártolo, Elisabetta Ceretti, Joaquim De Ciurana Gay, Ciro Angel Rodriguez, Tugrul Ozel, Paolo Surger, Paolo Jorge Bártolo, Elisabetta Ceretti, Joaquim De Ciurana Gay, Ciro Angel Rodriguez, Tugrul Ozel, Paolo Jorge Bártolo, Elisabetta Ceretti, Joaquim De Ciurana Gay, Ciro Angel Rodriguez, Tugrul Ozel, Paolo Jorge Bártolo, Elisabetta Ceretti, Joaquim De Ciurana Gay, Ciro Angel Rodriguez, Tugrul Ozel, Paolo Jorge Bártolo, Elisabetta Ceretti, Joaquim De Ciurana Gay, Ciro Angel Rodriguez, Tugrul Ozel, Paolo Jorge Bártolo, Elisabetta Ceretti, Joaquim De Ciurana Gay, Ciro Angel Rodriguez, Tugrul Ozel, Paolo Jorge Bártolo, Elisabetta Ceretti, Joaquim De Ciurana Gay, Ciro Angel Rodriguez, Tugrul Ozel, Paolo Jorge Bártolo, Elisabetta Ceretti, Joaquim De Ciurana Gay, Ciro Angel Rodriguez, Tugrul Ozel, Paolo Jorge Bártolo, Paolo Jorge Paolo Jorge Paolo Jorge B

Jorge Vicente Lopes Da Silva, "Biomedical Devices: Design, Prototyping, and Manufacturing", 1st Edition, 2016.

Learning Assessment Continuous Learning Assessment (50% weightage) Bloom's Final Examination (50% weightage) CLA – 4 (10%)# CLA - 1 (10%) CLA - 2 (15%) CLA - 3 (15%) Level of Thinking Theory Practice Theory Practice Theory Practice Theory Practice Theory Practice Remember Level 1 40 % 40 % 40 % 30 % 30% -----Understand Apply Level 2 40 % -40 % -40 % -40 % -40% -Analyze Evaluate Level 3 20 % 20 % 20 % 30 % 30% -----Create Total 100 % 100 % 100 % 100 % 100 %

Course Designers									
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts							
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldive	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1. Mr.P. Muthu, SRMIST							

							L	Т	Р	С		
Course Code	18BME365T	Course Name		Innovation, Translati	on and Entrepreneurship	Course Categor	E		3	0	0	
L I		1				1						
Pre-requisite		NII		Co-requisite	Nil	Prog	essive	Nii				
Courses		INII		Courses	NII I	Cou	rses	1111				
Course Offering Depa	artment		Biomed	lical Engineering	Data Book / Codes/Standards			Nil				

Course Lear	ning Rationale (CLR): The purpose of learning this course is to:		Learnir	ng	Program Learning Outcomes (PLO)														
CLR-1 :	Learn a range of creative thinking tool and how to practically apply these to the innovation and entrepreneurial process.	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Explain the business environment and idea generation		Ŷ	ŧ											Ice				
CLR-3 :	Understand Marketing feasibility and feasibility plan	-	enc	ner		s		<u>_</u>	age	a)			ε		nar	бĽ			
CLR-4 :	Understand about Entrepreneurship	kinç	fici	ainr		lysi		sign	Usi	ture	∞.		ear	ы	ξ Fi	Ĩ			
CLR-5 :	Familiarizing with the nuances of Intellectual Property Rights	hin	Pro	Atta	و م	vna	ent	Des	0	Cul	≣ity		т Х	cati	jt. 8	Lea			
CLR-6 :	Apply deep learning in real life medical problems	T (eq	eq	eri edg	Ē	∞ md	is, rch	Ē	/ &	ab Jab		ual	ni	Ŵ	bu	~	2	e
			Dec	Dect	gine owle	ble	sign /elc	alys sea	den	ciet	/irol staii	S	iž F	ШШ	ject	٦	ò	ò	ö
Course Lear	ning Outcomes (CLO): At the end of this course, learners will be able to:	(Bld	(%) EX	(%)	Бц	PG	D e	Aná Re:	β	Soc	Яü	딾	bul	õ	Pro	Life	PS	PS	PS
CLO-1 :	Understand the basic of creative thinking learning techniques and correlate to innovation	1, 2	80%	70%	Μ														
CLO-2 :	Understand the business environment and idea generation	2	80%	70%	Μ						L								
CLO-3 :	Apply knowledge of Marketing feasibility and feasibility plan	2	80%	70%			М		М				L				М		Ĺ
CLO-4 :	Apply Knowledge about entrepreneurship and new opportunities	3	80%	70%					М				L						
CLO-5 :	Use Knowledge about current scenario on entrepreneurship	3	80%	70%	М		L										М	į	Ĺ
CLO-6 :	Apply innovation to come up with new business plan	3	80%	70%	М			L					М						

		Innovation & Creative thinking	Business Plan / Idea	Marketing Feasibility and Planning	Entrepreneurship	Intellectual properties and responsibilities
Duration	n (hour)	9	9	9	9	9
6.1	SLO-1	Introduction to Creativity	Scanning of Environment	Market survey & Assessment	Understanding the Meaning of "Entrepreneur"	Product Strategies
3-1	SLO-2	Introduction to Innovation	Understanding factors	Market survey & Assessment	Universal definitions	Product Strategies
6.2	SLO-1	Need for Creativity & Innovation	Sensing Opportunities	Demand and Supply	Characteristics of an Entrepreneur	Distribution Strategies
5-2	SLO-2	Need for Creativity & Innovation	Identify and evaluate factors	Nature of Competition	Characteristics of an Entrepreneur	Distribution Strategies
6.2	SLO-1	The process of Technological Innovation	hamessing different sources of knowledge and information	Fixing cost and price of product	Classification of Entrepreneurs	Promotional Strategies
5-5	SLO-2	The process of Technological Innovation	hamessing different sources of knowledge and information	Fixing cost and price of product	Classification of Entrepreneurs	Promotional Strategies
64	SLO-1	Sources of Innovative Opportunity : Process Need	Generation of Ideas	Project Innovation and Changes	The Entrepreneurial Scene in India	Concept of Intellectual Property Rights (IPR)
3-4	SLO-2	Sources of Innovative Opportunity: Industry and market structures	Methods for Generating ideas	Identification of applicable Entrepreneurial Opportunities	The Entrepreneurial Scene in India	Patents, Trademarks
6 6	SLO-1	Sources of Innovative Opportunity : demographics	Product Planning	Data collection for setting up small ventures	Factors Influencing Entrepreneurship	Copyright, Industrial Designs Registrations
3-3	SLO-2	Sources of Innovative Opportunity: changes in perception	Product Planning	Data collection for setting up small ventures	Factors Influencing Entrepreneurship	Geographical Indications, Trade Secrets
8.6	SLO-1	Organization and personal factors to promote creativity	Writing a Business Plan	Financial, Economic Feasibilities	Entrepreneurial Growth	Territoriality of IPR
3-0	SLO-2	Organization and personal factors to promote creativity	Writing a Business Plan	Technical Feasibilities	Entrepreneurial Growth	Concept and procedures of obtaining rights and ownership for creative works in India
S-7	SLO-1	Creativity and analytical skill	Using and Implementing the Business Plan	Legal Feasibilities	Problems of Entrepreneurs	Environment protection

	SLO-2	Difference between Creativity and Analytical skill	Using and Implementing the Business Plan	managerial, Locational and Other Feasibilities	Problems of Entrepreneurs	Environment protection
<u> </u>	SLO-1	Creativity and Problem Solving	Difference between 'Basic Ideas' and post scanning ideas	Preliminary screening	HEIs Strategies & Governance for Promoting Innovation & Entrepreneurship	importance of Business Ethics and Values in Business
3-8	SLO-2	Creativity and Problem Solving	Difference between 'Basic Ideas' and post scanning ideas	Preliminary screening in market	National Innovation and Startup Policy (NISP) for Higher Educational Institutions (HEIs)	importance of Business Ethics and Values in Business
	SLO-1	Different Techniques for Creative Intelligence	Self Assessment of idea	Preparation of detailed feasibility plan	Creating Innovation Pipeline and Pathways for Entrepreneurs	Role of entrepreneur in economic growth
S-9	SLO-2	Brain storming technique	Reasons for Business Plans Failure	Key features of detailed feasibility plan	Collaboration Co-creation and Business Relationship and Knowledge Exchange	Role of entrepreneur in economic growth

	1.	Peter Drucker, "Innovation and Entrepreneurship", Routledge Classics 2015	6.	S.S.Khanka, Entrepreneurial Development, S.Chand and Company Limited, New Delhi. 2013
	2.	Carolina Machado, J. Paulo Davim, "Entrepreneurship and Organizational Innovation", Springer 2020	7.	Gupta C.B. & Khanka. S.S, — Entrepreneurship and small business managementll, 5th edition ,
Learning	3.	Norman M. Scarborough , "Essentials of Entrepreneurship and Small Business Management" (6th Edition) by		sultan chand & sons, 2014
Resources		(Paperback - Jan 13, 2010)	8.	Jayshree Suresh, — Entrepreneurial Developmentll, Margham Publishers, Chennai, 2011.
	4.	Dr.Jayashree suresh –Entrepreneurship DevelopmentMargham Publication-2012	9.	Jeff Cornwall, —Entrepreneurship From Idea to Launchll, Udemy online Education,
	5.	Ganguli Prabuddha "Intellectual Property RightsUnleashing the Knowledge Economy", Tata McGrawHill (2001)		https://www.udemy.com/entrepreneurship-from-idea-to-launch/

Learning Assessm	nent										
	Diaam'a			Cor	ntinuous Learning Ass	essment (50% weight	tage)			Final Examinatio	n (E0% weightege)
	DIUUIIIS	CLA –	1 (10%)	CLA –	2 (15%)	CLA –	3 (15%)	CLA – 4	4 (10%)#	Final Examinatio	in (50% weightage)
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Lovel 1	Remember	40.0/		10.0/		10.0/		20.0/		200/	
Level I	Understand	40 %	-	40 %	-	40 %	-	30 %	-	30%	-
	Apply	10.9/		10.0/		10.0/		10.0/		409/	
Leverz	Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Loval 2	Evaluate	20.0/		20.0/		20.0/		20.0/		200/	
Levers	Create	20 %	-	20 %	-	20 %	-	30 %	-	30%	-
	Total	10	0 %	10	0 %	10	0 %	10	0 %	10	0 %

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldive	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1. Mrs.P.Bhargavi Haripriya, SRMIST

Course Code	Course Code 18BME366T		ME3667 Course Name Biomedical Microscopy and Quantitative Imaging Course Category E Professional Electiv								С
course coue	Dde 18BME3061 Course Name Biomedical Microscopy and Quantitative Imaging		course category	L	Professional Elective	3	0	0	3		
L						1	L				
Pre-requisite		Nil	Co-requisite	Nii	Progre	essive	Nil				
Courses	Courses		140	Cou	rses	1411					
Course Offering Depa	Course Offering Department Biomedical Engineering		Data Book / Codes/Standards			Nil					

Course Lea	arning Rationale (CLR):	The purpose of learning this course is to:		Learni	ng				Р	rogran	n Learr	ning O	utcome	es (PLC))				
CLR-1 :	Understand the basics of optics i	n microscopy	1	2	3	1	2	3 4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Understand the basics of fluores	ence microscopy		y.	÷										Ice				
CLR-3 :	CLR-3 : Understand the techniques in low light microscopy				nen		Ś	-	age	0			۶		nar	þ			
CLR-4 : Analyze the various methods for quantitative analysis of microscopic images				fici	ainr		ysi	ign	Us	ture	~ð		ear	ы	ξË	nir		1	
CLR-5 : Analyze the various methods for quantitative analysis of fluorescence microscopic images				2	Atte	g a	nal	Des	0	Cul	ent.		& T	cati	jt. δ	Lea			
CLR-6 : Understand the optics of microscopy and the various methods of quantitative analysis				eq	eq	erir	ר ר	rs, l	Ĕ	/ &	ab dar		ual	nii	Ň	bu	~	2	
				ect	pect	bine wie	plei	ilys ilys ieau	derr	iety	'iror tair	S	rk vid	ШШ	ject	Ľ	ö	ö	ö
Course Lea	arning Outcomes (CLO):	At the end of this course, learners will be able to:	(Bic	₿ Å Å Å Å Å Å	(%) Exp	Щ Ч	5 2	Dev Res	Ř	Soc	Env Sus	댪	Wo	Ğ	Pro	Life	PS	PSC	PSC
CLO-1 :	Describe optics and principle of o	peration of microscopic image formation	1, 2	80%	70%	М												1	
CLO-2 :	Describe optics and principle of c	peration of fluorescence microscopic image formation	2	80%	70%	М													
CLO-3 :	Demonstrate the techniques for I	ow light microscopy	2	80%	70%			М	М								М		L
CLO-4 :	Apply the different methods for q	antitative analysis of microscopic images	3	80%	70%				М									1	
CLO-5 :	CLO-5 : Apply the different methods for quantitative analysis of fluorescence microscopic images			80%	70%	М											М		L
CLO-6 :	LO-6 : Apply the knowledge in microscopic image formation and its quantitative analysis			80%	70%	М													

		Optics of microscope image formation	Fluorescence Microscopy	Low-light microscopy	Quantitative Analysis of digital microscope images	Quantitative Fluorescence microscopy
Duratio	n (hour)	9	9	9	9	9
6.4	SLO-1	Finite tube length microscope	Fluorescence Microscopy	Low light imaging	Optical systems as block boxes	Quantitative fluorescence—detectors
3-1	SLO-2	Upright microscope	Beer's Law	Detection of low light	Calibration toolkit	Limits on linearity
S-2	SLO-1	Infinity optics microscope	Atomic fluorescence	Parameters characterizing imaging devices	Simple calibration curve-relative scale	Illumination variations
5-2	SLO-2	Objective basics	Organic molecular fluorescence	Sensitivity and quantum efficiency	Simple calibration curve-Absolute scale	Detector noise
	SLO-1	Physical optics: superposition of waves	Excited state lifetime	Spectral response, Units	Precision in a calibration curve	Photon shot noise
S-3	SLO-2	Huygen's Principle	Excited state saturation	Fill factor (CCD format), Camera noise and the signal-to-noise ratio	Standard deviation and errors	Characterizing the performance of an imaging system
84	SLO-1	Young's experiment : two slit interference, Diffraction from single slit	Nonradiative decay mechanisms	Shot noise, Readout noise	Signal to noise ratio	Preprocessing of images for quantitative analysis
3-4	SLO-2	Microscope resolution, Issues in Microscope resolution	Fluorescence Resonance energy	Background and noise, Example calculation	Signal to background ratio	Processing data for quantitative analysis
	SLO-1	Key components of light microscope	Fluorescence Depolarization	Spatial resolution, Example	Propagation of error in calculated quantities	Methodologies for quantitative imaging
S-5	SLO-2	Illumination Section, Light source	Measuring fluorescence in steady state	Linearity and uniformity, Time response	Error propagation in imaging	Approaches for image deblurring by deconvolution
	SLO-1	Lamp collector	Construction of monochromator	Dynamic range, Gain	Accuracy and precision	Deblurring or neighbor-based methods
S-6	SLO-2	Internal components of illumination paths	Construction of photomultiplier tube	Frame rate and speed, Resolution, sensitivity, and imaging rate	Flatfield Correction	Restoration methods
S-7	SLO-1	Field diaphragm, Condenser, Stage and specimen holder	Measuring fluorescence in the time domain	Imaging Detectors and features	Spatial corrections	Image deconvolution: effects and results
3-7	SLO-2	Microscope imaging section, Objective	Boxcar-gated detection method	Video CCD cameras, Slow-scan and fast CCD cameras	Maximizing resolution	Image deconvolution: practical issues
S-8	SLO-1	Objective Back Focal Plane	Streak Camera method	Intensified Cameras	Converting pixels to microns	Applications for Image Deconvolution

	SLO-2	Revolving nosepiece Turret	Photon correlation method, Phase modulation method	Digital still cameras, SIT Cameras	IS	Imaging warping	Quantitative Ratiometric Imaging of FRET- Biosensors in Living Cells
	SLO-1	Infinity space, Tube lens, Eyepieces	Filters for the selection of wavelength	CMOS imagers		Two color coincidence	Image processing methods
S-9	SLO-2	Koehler Illumination, Conjugate light paths	Power of fluorescence of microscopy	Image acquisition		Two camera and two color imaging	Imaging considerations and caveats and pitfalls
Learning Resources	1. G 3. Ir A	Greenfield Sluder, David E. Wolf," Digital Micros ving J. Bigio, Sergio Fantini "Quantitative Biom pplications", Cambridge University Press, 201	copy", 4th Ed, Academic Press, 2013. edical Optics: Theory, Methods, and ô	2. Je Ac	ennifer Waters cademic Press	s, Torsten Wittmann, "Quantitative Imaging in s, 2014.	Cell Biology"

Learning Assess	Learning Assessment											
	Ploom's			Con	ntinuous Learning Ass	essment (50% weigh	tage)			Einal Examinatio	n (50% woightaga)	
	Diouins	CLA –	1 (10%)	CLA –	2 (15%)	CLA –	3 (15%)	CLA – 4	l (10%)#		r (50 % weightage)	
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	
Lovel 1	Remember	10.9/		10.0/		10.0/		20.0/		200/		
Level I	Understand	40 %	-	40 %	-	40 %	-	30 %	-	30%	-	
Lovel 2	Apply	10.0/		10.0/		10.0/		10.0/		400/		
Level Z	Analyze	40 %	-	40 %	-	40 %	-	40 %	-	4070	-	
Lovel 2	Evaluate	20.0/		20.0/		20.0/		20.0/		200/		
Level 5	Create	20 %	-	20 %	-	20 %	-	30 %	-	30%	-	
	Total	10	0 %	10	0 %	10	0 %	10	0 %	10	0 %	

Course Designers		
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Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldive	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1. Dr.P.VinuprithaSRMIST

0.1			0								•			-		-					L	Т	Р	С
Code		18BME3671	Course Na	me	HOSPITA	LMANGEMENT	SYIEW				Cou	rse Ca	egory	E		Professional Elective		r Tolessional Liective			3	0	0	3
Pre-requ Cours	uisite ses		Nil		Co-requisite Courses			Nil					Progre Coui	essive ses						Nil				
Course Offe	ring Depar	rtment		Bior	medical Engineering	Da	ata Boo	ok / Code	s/Standards									Nil						
Course Lear	ning Ratio	onale (CLR):	The	ourpose of learning th	nis course is to:			Learn	ing					Ρ	rogram	Learr	ning O	utcome	es (PLC))				
CLR-1 :	Understan	nd about quality and	d performant	e improve methods			1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Analysis o	of performance mar	nagement me	thods and project ma	anagement																			
CLR-3 :	Gain the k	knowledge of proce	ss redesign	nd data analytics			Ē		~				Irch			bility								
CLR-4 :	Understan	nd the analytics in h	nealthcare or	anizations and popu	lation health		loon	3 (%	nt (%	agbe		ient	eses			taina		Vork		g				
CLR-5 :	Gain know	wledge strategically	manage ho	pital system			B) BL	cienc	Jmer	lowle	sis.	lopm	JU, R	sage	e	Sus		am V	c	Final	ing			
CLR-6 :	Understan	nd the setup of Hos	pital Informa	ion System(HIS)			inki	Jofe	Attai	ig Kr	naly:	Deve	Jesiç	u lo	Cult	ent &		& Te	atior	t &	earr			
	1						of T	ted	ted /	eerir	em A	n & I	sis, [m To	ty & i	amne		dual	Junic	st Mg	l gnc		5	e.
Course Lear	ning Outc	omes (CLO):	At th	end of this course,	learners will be able to:		Level	Expec	Expec	Engin	Proble	Desig	Analy	Mode	Socie	Envird	Ethics	Individ	Comn	Projec	Life Lo	- OS4	PSO.	- OS4
CLO-1 :	Describe p	performance impro	ve methods				1, 2	80%	70%	М	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-2 :	Identify the	e project managerr	nent in health	care			2	80%	70%	М	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-3 :	CLO-3 : Apply the process redesign and data analytics in population health			2	80%	70%	-	-	М	-	М	-	-	-	-	-	-	-	М	-	L			
CLO-4 :	Gain the k	knowledge of health	n care organi	ations			3	80%	70%	-	-	-	-	М	-	-	-	-	-	-	-	-	-	-
CLO-5 :	Analyzes	the population hea	lth manager	ent			3	80%	70%	М	-	-	-	-	-	-	-	-	-	-	-	М	-	L
CLO-6 :	Understan	nd hospital manage	ment systen				3	80%	70%	М	-				-		-	-						

		Quality and Performance improve Methods	Performance Management Methods and Project Management	Process Redesign, Data analytics and Population health	Analytics in healthcare organizations and population health management	Strategically Hospital management system
Duratio	n (hour)	9	9	9	9	9
C 1	SLO-1	Introduction to Quality management system	Introduction to Quality Measures	Introduction to process redesign	Introduction to healthcare organizations	Strategic, Tactical, and Operational Information Management
3-1	SLO-2	Quality Management	Process and outcome Measures	Importance of Process Improvement in system implementation	Analytical challenges	Information Management
6.2	SLO-1	Core components of Quality managements	Plan do check act	Basic process Improvement Approach	The values of analytics in health care	Strategic Information Management
5-2	SLO-2	Planning, Improvement and control	Six sigma and Lean	Lean Six Sigma	Types of data in health care organizations	Operational Information Management
6.2	SLO-1	Need for health improvement	Theory of constraints and process modeling	Documenting the process	Understanding managing data (Analytical tool and data)	Organizational Structures for Information Management
3-3	SLO-2	Performance improvement	Others Tools and Techniques	Communication Planning	Statistical analysis in health analytics and performance improvement.	Typical Organizational Structures for Strategic Information Management
	SLO-1	Introduction to performance management	Introduction to developing new quality teams	Solidifying the process Improvement Approach	Introduction to population health management	Typical Organizational Structures for Tactical and Operational Information Management
S-4	SLO-2	Performance management	Building a new Quality	Creating Future State	Measure of population health status	Examples: Organizational Structures for Information Management in a Hospital

	SLO-1	Health care strategy	Managing performance improvement	Identify metrics and Information capture points	Interaction with community Public health service Provider	Information Systems Managers as Architects
S-5	SLO-2	Performance frame work	Measure the project status	Gap Analysis definition	Factors influencing population health status	Organizational Structures for Information Management in a Hospital
66	SLO-1	Change versus improvement	Recommendation of Building capacity	Introduction to Big data analysis	Impact of health disparities and inequities	Strategic Planning of Hospital Information Systems
3-0	SLO-2	Performance based planning	Recommendation of Building capacity to all	Decision Model	Healthcare delivery systems	Strategic Alignment of Business Plans and Information Management Plans
67	SLO-1	Benchmarking	Introduction to project management in health care	Predictive Modeling	Continuum of care	The Strategic Information Management Plan
3-7	SLO-2	Identifying problem and gap	Project initiation and design	Define the objects and data collection	Care of co-ordination	Purpose of Strategic Information Management Plans
6.0	SLO-1	Research and Prepare benchmarking visit.	Project risk	Applying algorithm	Network Affiliation Strategies	Strategic Monitoring of Hospital Information Systems
3-0	SLO-2	Guideline for performance management	Project Execution and Control	Apply Prediction to decisions	Community needs assessment	Certification, Accreditation, and Excellence Programs of HIS
	SLO-1	Measure the Historical Performance	Change Management	Information sharing beyond the Organizational walls	Evaluating Community Health status measures	Assessment Study of a Telemedicine System to Improve Care
5-9	SLO-2	Forecast the desired Improvement target	Project Communication	Health information Exchanges	Data sources and incentive for health program	Strategic Directing of Hospital Information Systems

Learning Resources	1. 2.	James R. Lang beer II "Performance Improvement in Hospitals and Health Systems Managing Analytics and Quality in Healthcare 2nd Edition", Taylor francs, 2018. Kathryn J. Hannah Marion J. Ball Series Editors, "Health Informatics", Springer Scienc Business Media, LLC2ndedition, 2009	3. 4.	Pradip Kumar Ray, Jhareswar Maiti, "Healthcare Systems Management: Methodologies and Applications: 21st Century Perspectives of Asia", Springer, 2018 Gerald L. Glandon, Donna Jean Slovensky, Detlev Herb Smaltz," Information Systems for Healthcare Management", Health Administration Press, 2014
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Learning Assess	ment											
	Bloom's Continuous Learning Assessment (50% weightage)											
	DIUUIIIS	CLA –	1 (10%)	CLA – 2 (15%)		CLA –	3 (15%)	CLA – 4	¥ (10%)#		n (50% weightage)	
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	
Lovel 1	Remember	10.0/		10.0/		10.9/		20.0/		200/		
Level I	Understand	40 %	-	40 %	-	40 %	-	30 %	-	30%	-	
Lovel 2	Apply	40.0/		10.0/		40.0/		10.0/		400/		
Leverz	Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-	
	Evaluate	20.0/		20.0/		20.0/		20.0/		200/		
Level 5	Create	20 %	-	20 %	-	20 %	-	30 %	-	30%	-	
	Total	10	0 %	10	0 %	10	0 %	10	0 %	10	JO %	

Course Designers											
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts									
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldive	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1. Dr. S. Gnanavel, SRMIST									

Course	!	10DME260T	Course		SOFT TISSUE AND BIO	ELUID MECHANICS	Co	urse	E		Professional Elective						Т	Ρ	С					
Code		TODIVIESUOT	Name				Cate	egory	E				FIU	162210	iiidi L	lective	,				3	0	0	3
Pre-req Cours	uisite ses	Nil		Co	o-Requisite Courses		Prog Co	gressi ourses	ve Nil															
Course Of	fering	J Department	Biome	edical Engineering		Data Book / Codes/Standards	Nil																	
Course Le	earning	g Rationale (CLR):	The p	rpose of learning this co	ourse is to:		Le	earnin	g					Prog	ram	Learni	ing O	utcom	es (PL	.0)				
CLR-1 :	Unde	erstand the fundame	ntal of soft ti	ssue mechanics			1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 : CLR-3 : CLR-4 :	Get a Acqui Get a	an idea about the bio ire an idea about the an idea about the me an idea about the bio	otransport e fundament echanics of c	al concepts of biofluid m ardiovascular system	nechanics		 g (Bloom)	iency (%)	ment (%)	owledge	S	opment	ć	age	e			m Work		inance	бu			
CLR-5 :	Unde	erstand the soft tissu	ies and bioflu	iid mechanics	ouy organ systems		f Thinkin	ed Profici	ed Attain	erina Kno	Analysi	& Develo	s, Desigr ch	Tool Us	& Cultur	ment & abilitv		ial & Tea	inication	Mgt. & F	ig Learni			e
Course Le	arning	g Outcomes (CLO)	: At the	end of this course, learn	ners will be able to:		Level of	Expecte	Expecte	Enainee	Problen	Design	Analysi Resean	Modern	Society	Environ Sustain	Ethics	Individu	Commu	Project	Life Lor	PSO - 1	PSO - 2	PSO -
CLO-1 :	Unde	erstanding of the fun	damental of	the mechanics soft tissu	ue		1, 2	80	70	Н	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-2 :	Analy	yze the various trans	sport in biolo	gical system			1, 2	80	70	М	-	-	-	-	-	-	-	-	-	-	-	М	-	-
CLO-3 :	Conc	eptualization of biof	fluid mechani	CS			2	80	70	Н	H M M					-								
CLO-4 :	Illustr	rate of the concepts	of cardiac s	ystem and its biofluid me	echanics		1	80	70	-	-	L	-	-	-	-	-	-	-	-	Н	-	М	М
CLO-5 :	Illustr	rate the role of bioflu	ıid mechanic	s in various organ syste	m		1	80	70	-	-	L	-	-	-	-	-	-	-	-	Н	-	-	-
CLO-6 :	Outlin	ne the importance o	f understand	ing soft tissues and biofl	luid mechanics		1,2	80	70	-						-	-							

Durati	an (haur)	Fundamental of Soft Tissue mechanics	Basic concept of Biofluids	Macrocirculation and microcirculation system	Cardiac mechanics	Biofluid mechanics of organs system
Durau	on (nour)	9	9	9	9	9
S 1	SLO-1	Introduction: Structural organization of skeletal muscle	Introduction –Body fluids, Dimension and unit	Introduction of macrocirculation and microcirulation	Introduction	Kidney :Structure and function
3-1	SLO-2	Muscle fiber	Basic Concepts and Definitions of Fluid Mechanics	Pulsatile flow properties	Cardiac Geometry and Structure	Fluid flow in an artificial kidney model
6.2	SLO-1	Motor unit	Fluid Kinematics and Viscosity	Arteries	Cardiac Geometry and Structure	Fluid flow in an artificial kidney model
3-2	SLO-2	Fiber types	Newtonian Fluids	Veins	Ventricular Geometry	Mass transfer in an artificial kidney model
6.2	SLO-1	Fiber architecture	Non-Newtonian Fluids	Vascular bifurcations and branches	Ventricular Geometry	Mass transfer in an artificial kidney model
0-0	SLO-2	Muscle function	Dimensionless Numbers of Biofluid Mechanics	Blood flow through curved vessels	Myofiber Architecture	Liver: structure and function
6.4	SLO-1	Muscle function	Steady versus Unsteady Flow and Laminar Versus Turbulent Flow	Mechanical and elasticity properties of vessels	Myofiber Architecture	Hepatic acinus model
3-4	SLO-2	Maximum Muscle Stress	Boundary Conditions and No Slip Boundary Condition	Atherosclerosis characteristics	Extracellular Matrix Organization	Fluid flow in hepatic acinus model
S 5	SLO-1	Maximum Muscle Contraction Velocity	Compressible and Incompressible Flows, Stress Tensor	Blood flow through stenosis	Cardiac Pump Function: Ventricular Hemodynamics	Mass transfer in hepatic acinus model
3-3	SLO-2	Types of Muscle Models	Viscoelasticity and Viscoplasticity	Arterioles and blood flow aspects	Ventricular Pressure–Volume Relations and Energetics	Lung : Structure and function

SLO-1		Huxley biochemical models	Basic Equations of Fluid Mechanics- conservation of Mass, Momentum and Energy	Capillaries and venules	Ventricular PressureVolume Relations and Energetics	Elasticity of the lung blood vessels and alveoli
3-0	SLO-2	Hill phenomenological models	NavierStokes Equations	Fahraeus and Fahraeus lindqvist effects	Myocardial Material Properties	Pressure-volume relationship for air flow in the lungs
67	SLO-1	Constitutive models	Bernoulli Equation	Fahraeus and Fahraeus lindqvist effects	Myocardial Material Properties: Muscle Contractile Properties	Oxygen/carbon dioxide diffusion and transport in the blood
3-1	SLO-2	Tendon-morphology	Hagen Poiseuille Equation	Mass transport in tissue	Muscle Contractile Properties	Compressible fluid flow
e .	SLO-1	Tendon-properties	Steady Flow Along Tube, Pulsatile Flow in Rigid and Elastic Tubes	Porosity, tortuosity and permeability	Resting Myocardial Properties	Lubrication of joints: function
3-0	SLO-2	Ligament –morphology	Resistance, Compliance and Inertance, Two- Phase Flows	Governing equations in porous media	Resting Myocardial Properties	Formation of synovial fluid
.	SLO-1	Ligament -properties	Hematology and blood rheology	Governing equations in porous media	Regional Ventricular Mechanics: Stress and Strain	Synovial fluid flow
S-9 SLO-2		Articular cartilage –morphology and properties	Hematology and blood rheology	Fluid transport in poroelastic media	Regional Ventricular Mechanics: Stress and Strain	Mechanical forces within joint

	1. David A. Rubenstein, Wei Yin&Mary D. Frame "Biofluid mechanics: An introduction to fluid	
	mechanics,macrocirculation and microcirculation (Biomedical Engineering)", Elsevier, 2 nd edition ,2012	5. Susan Hall, "Basic Biomechanics" McGraw-Hill Education,6 th edition August 2011
Learning	2. Clement Kleinstreuer "Biofluid Dynamics: Principles and Selected Applications", CRC Press; 1 edition, 2016	6. Ali Ostadfar," Biofluid Mechanics - Principles and Applications," Elsevier, 1st edition, 2016
Resources	3. Benjamin Loret, Fernando Manuel & Fernandes Simoes "Biomechanical Aspects of Soft Tissues", CRC Press;	7. Jagan N. Mazumdar, "Biofluid Mechanics," World Scientific, 2 nd edition, 1992
	1 edition, 2017	
	4. Yuan-Cheng Fung, "Biomechanics: Mechanical Properties of Living Tissues", Second Edition, 1993	

Learning Assessme	Learning Assessment													
	Diaam'a			Con	tinuous Learning Ass	essment (50% weight	age)			Final Examination	(E0% weightege)			
	DIUUIIIS	CLA – 1	1 (10%)	CLA –	2 (15%)	CLA – S	3 (15%)	CLA – 4	(10%)#		i (50% weightage)			
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice			
Level 1	Remember	10.0/		40.0/		40.0/		20.0/		2007				
Level 1	Understand	40 %	-	40 %	-	40 %	-	30 %	-	30%	-			
Lovel 2	Apply	10 %		40.9/		10.0/		10.9/		100/				
Level Z	Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-			
Level 2	Evaluate	20.0/		20.0/		20.0/		20.0/		200/				
Level 5	Create	20 %	-	20 %	-	20 %	-	30 %	-	30%	-			
	Total	100) %	100	0 %	100	0 %	10) %	10) %			

Course Designers											
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts									
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldive	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1. Ms. Oinam Robita Chanu									

Course	Course 18BME369T Course TROUBLESHOOTING OF MEDICAL DEVICES				Co	ourse	E				Pro	ofessio	onal El	lective	,			-	L	T	Р	С	
Code			Name			Cat	egory													3	0	0	3
Pre-req Cour	uisite Basic El ses Integrate	lectronic d ted circuits	devices and circuits, Linear s, Biomedical Instrumentation	Co-requisite Courses	Nil	Pro	gressi ourses	ve _{Nil}															
Course O	ffering Departme	ent	Biomedical Engineering		Data Book / Codes/Standards	Nil																	
Course Le	Durse Learning Rationale (CLR): The purpose of learning this course is to:							9					Prog	ıram L	_earni	ing Ou	utcom	ies (Pl	L0)				
CLR-1 :	urse Learning Rationale (CLR): The purpose of learning this course is to: R-1: Understand the fundamental troubleshooting procedures and testing of basic electronic components R-2: Learn the methods to ensure electrical safety R-3: Get an idea about the fault diagnosis in analog and digital ICs.				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLR-2 :	LR-2: Learn the methods to ensure electrical safety LR-2: Cot an idea about the fault diagnosis in analog and disital ICs.				_						÷			lity									
CLR-3 :	Acquire an idea	about the	basic troubleshooting procedu	ures for biomedical	equipment	(moo	(%) /	(%)	gge		ant	searc			ainabi		ork		8				
CLR-5 :	Learn the metho	ods of trou	bleshooting Diagnostic medica	al Equipments		B)	ency	ment	vlec	s	bme	, Re	age	æ	Susta		ج ۲		nan	þ			
CLR-6 :	Understand the	methods	of troubleshooting therapeutic	medical Equipmen	ts	king	ofici	ainr	Kno	alysi	velo	sign	Use	Itur	8		Tear	ion	& ₽	arnir			
Course Le	earning Outcome	es (CLO):	At the end of this course,	learners will be ab	le to:	Level of Thir	Expected Pr	Expected Att	Engineering	Problem Ana	Design & De	Analysis, De	Modem Tool	Society & CL	Environment	Ethics	Individual &	Communicat	Project Mgt.	Life Long Le	PSO - 1	PSO - 2	PSO – 3
CLO-1 :	Apply the commo components	ion trouble	eshooting procedures in Electr	onic Equipment and	Outline the testing procedures of active and passive	1, 2	80	70	М	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-2 :	SLO-2: Analyze the faults in analog circuits and digital ICs				1, 2	80	70	М	-	-	-	-	-	-	-	-	-	-	-	М	-	-	
CLO-3 :	CLO-3 : Identify the problems in common biomedical equipment in hospitals when it is not working and provide a suitable solution		2	80	70	-	М	-	-	-	-	-	-	-	-	-	-	М		-			
CLO-4 :	0-4 : Apply the acquired knowledge in fault diagnosis of medical equipments			1	80	70	-	-	Н	-	-	-	-	-	-	-	-	М	-	М	-		
CLO-5 :	-5: Explain the methods of troubleshooting Diagnostic medical Equipments			1	80	70	-	-	-	-	-	-	-	-	-	-	-	М	-	-	-		
CLO-6 :	Implement the methods of troubleshooting therapeutic medical Equipments			1,2	80	70	-	-	-	-	-	-	-	-	-	-	-	L	-	-	-		

Durati	on (hour)	Basic Troubleshooting Techniques & Procedures	Grounding Systems	Troubleshooting Active and Passive components	Troubleshooting of diagnostic Equipments	Troubleshooting of Therapeutic & Surgical Equipments
		9			9	9
C 1	SLO-1	Making of an electronic equipment	Electrical Hazards	Testing of passive components: Fixed Resistors	Parts of an ECG Machine	Troubleshooting of Defibrillator
0-1	SLO-2	description	Causes	Testing of passive components: variable Resistors	Sources of ECG artifacts	Preventive maintenance of Defibrillator
S-2	SLO-1	РСВ	Types of electrical shock	Testing of passive components: Capacitors	Troubleshooting- ECG Machine	Troubleshooting of Electrosurgical unit
0-2	SLO-2	PCB types	Threshold levels of electrical shock	Testing of passive components: variable Capacitors	Preventive maintenance of ECG system	Preventive maintenance of Electrosurgical unit
6.2	SLO-1	Causes of Equipment Failure	Electrical grounding	Testing of passive components: Inductors	Parts of an EEG Machine	Troubleshooting of Incubator
3-3	SLO-2	Types of Equipment Failure	Need for grounding	Testing of passive components: variable Inductors	Sources of EEG artifacts	Preventive maintenance of Incubator unit
S 1	SLO-1	Functional block diagram of a troubleshooting system	Grounding Systems in Electronic Equipment	Testing of PN Diodes	Troubleshooting- EEG Machine	Troubleshooting of Suction apparatus
3-4	SLO-2	Description of a troubleshooting system	Methods	Testing of Zener Diodes	Preventive maintenance of EEG system	Preventive maintenance of Suction apparatus
9.5	SLO-1	Troubleshooting Process	Temperature Sensitive Intermittent Problems	Testing of NPN transistor	X ray System	Troubleshooting of Anaesthesia Machine
0-0	SLO-2	Description	Methods to rectify	Methods	Sources of errors	Preventive maintenance of Anaesthesia Machine
S-6	SLO-1	Fault finding Aids	Correction Action to repair the Equipment	Testing of PNP transistor	Troubleshooting- X-ray Machine	Troubleshooting of Nebulizer Machine

	SLO-2	Description	Correction Action to repair the Equipment	Methods	Preventive maintenance of X-ray system	Preventive maintenance of Nebulizer Machine
0.7	SLO-1	Troubleshooting techniques: Preliminary Observations	Tools & Aids for Servicing & Maintenance	Testing of FET	Endoscopy: Sources of artifacts	Oxygen cylinders
5-7	SLO-2	Troubleshooting techniques: Functional block diagram approach	Tools & Aids for Servicing & Maintenance	Methods	Troubleshooting of endoscope & its preventive maintenance	Preventive maintenance of Oxygen cylinders
C 0	SLO-1	Troubleshooting techniques: Split half method	Situations where repair not to be attempted	Typical op-amp based medical circuits	Radiation Monitors-trouble shooting	
5-0	SLO-2	Application of Split half method in circuit troubleshooting	Situations where repair not to be attempted	Troubleshooting of Ultrasound system & its preventive maintenance	Radiation Monitors-calibration	
<u> </u>	SLO-1	Troubleshooting techniques: Systematic Troubleshooting	hniques: Systematic Types of power supply Digital IC Troubleshooter:, Logic clip, Logic Troubleshooter:		Troubleshooting of Pulse oximeter	Troubleshooting of Autoclaves & sterilizers
0-9	SLO-2	Correction action	World power supply types	Logic pulser, Logic current tracer	Troubleshooting of Sphygmomanometers	Preventive maintenance of Autoclaves & sterilizers
Learnii Resou	ng rces	 Joseph D Bronzino & Donald R Peterson, "M 2015 Myer Kutz, "Biomedical Engineering and Des 2009 Richard Fries, "Reliable Design of Medical D 4. Basem S EL-Haik & Khalid S Mekki, "Medica Effectiveness", John Wiley & Sons, 1st Edition, 5. John J Tobin & Gary Walsh, "Medical Produc Devices", Wiley-Blackwell, 1st Edition, 2008 Norbert Leitgeb, "Safety of Electromedical D 	Iedical Devices and Human Engineering", CRC I sign Handbook- Volume 2: Applications", McGra evices", CRC Press, 2 nd Edition, 2006 al Device Design for Six Sigma: A Road Map for 2008 ct Regulatory Affairs- Pharmaceutical, Diagnostic evices Law – Risks – Opportunities", SpringerWi	Press, 4 th Edition, w-Hill, 2 nd Edition, Safety and cs, Medical ienNewYork, 1 st 7. "Medical Device Regulatio 8. Jack Wong and Raymond Ltd., 2 nd Edition, 2018 9. Khandpur R S, "Troublesh 2009 10. Nicholas Cram & Selby H edition, 2010 11. Dan Tomal & Neal Widm 12. Ministry of Health & Famili usors" New Dolbi 2010	ns Global overview and guiding principles", Work K Y Tong, "Handbook of Medical device regulate ooting Electronic Equipment- Includes Repair & łolder, "Basic Electronic Troubleshooting for Bior er, "Electronic Troubleshooting", McGraw Hill, 3° y Welfare, "Medical Equipment Maintenance Ma	d Health Organization Geneva, 2003 ory affairs in Asia", Pan Stanford Publishing Pte. Maintenance", Tata McGraw-Hill, 2 nd Edition, medical Technicians", TSTC Publishing, 2 nd ^d edition, 2004 nual- A first line maintenance guide for end

12. Ministry of Health & Family Welfare, "Medical Equipment Maintenance Manual- A first line maintenance guide for end users", New Delhi, 2010

Learning Asse	essment										
	Dia any'a			Cor	ntinuous Learning Ass	essment (50% weight	age)			Final Eventination	- (FO)(
	DIOUIIIS	CLA –	1 (10%)	CLA – 2 (15%)		CLA –	3 (15%)	CLA –	4 (10%)#		r (50% weightage)
	Remember		Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Loval 1	Remember	10.9/		10.0/		10.9/		20.0/		200/	
Level 1	Understand	40 %	-	40 %	-	40 %	-	30 %	-	30%	-
Lovel 2	Apply	10 %		10 %		10 %		10 %		10%	
	Analyze	40 70	-	40 70	-	40 78	-	40 70	-	4070	-
Lovel 3	Evaluate	20 %		20 %		20.04		30 %		30%	
Level 5	Create	20 %	-	20 %	-	20 %	-	30 %	-	30%	-
	Total	10	0 %	10	0 %	10	0 %	10	0 %	10	0%

CLA - 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Edition, 2010

Course Designers		
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Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldive	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	Dr.D.Kathirvelu, SRMIST

Cou Co	rse de	18BME370T	Course Name	QUALITY ASS	SURANCE AND REG	ND REGULATORY ASPECTS IN MEDICINE				ourse tegor	y y	E				Pro	ofessi	ional E	lective)				L 3	Т 0	P 0	C 3
Pre- Co Course	requisit ourses e Offerin	Basic Electronic of Integrated circuits	levices and c , Biomedical Biomed	ircuits, Linear Instrumentatio ical Engineerin	Co-requisite Courses	Nil	Data Book /	/ Codes/Standards	Pro C Nil	ogress Sourse	sive es	Nil															
Course	e Learni	ng Rationale (CLR):	The pu	pose of learnin	g this course is to:				L	.earni	ng						Pro	gram	Learni	ng Ou	itcom	es (Pl	_0)				
CLR-1 CLR-2 CLR-3 CLR-4 CLR-5 CLR-6	: Unc : Get : Acq : Get : Get : Get	erstand the fundamen an idea about the fauli uire an idea about the an idea about the mec an idea about the Indi an overall idea about t	tal troublesh t diagnosis ir basic trouble dical device o an perspecti the importan	ooting procedu a analog circuits eshooting proce classification glo ve medical devi ce of troublesho	res and testing of bas s and digital ICs. dures for biomedical bally and regulatory ice regulatory system boting and medical do	sic electronic con l equipment standards n evice classificati	mponents ion in India		inking (Bloom)	Proficiency (%)	Attainment (%)		g Knowledge	nalysis 5	Development 6	Jesign, 4	ol Usage G	Culture	nt & litv	8	ه Team Work ه	ation 01	t. & Finance 11	earning 71	13	14	15
Course Learning Outcomes (CLO): At the end of this course, learners will be able to: CLO-1 : Apply the common troubleshooting procedures in Electronic Equipment and Outline the testing procedures of active and pass					lures of active and passive	Level of Th	Expected I	Expected /		Engineerin	Problem A	Design & [Analysis, [Research	Modern To	Society &	Environme Sustainabi	Ethics	Individual	Communic	Project Mg	Life Long I	PS0 - 1	PSO - 2	PSO – 3			
CLO-1 CLO-2	CLO-1: Apply the common troubleshooting procedures in Electronic Equipment and Outline the testing procedures of active and passive components CLO-2: Analyze the faults in analog circuits and digital ICs					1, 2 1, 2	80 80	70 70		M M	-	-	-	-	-	-	-	-	-	-	-	- М	-	-			
CLO-3 CLO-4	CLO-2 : Analyze the faults in analog circuits and digital ICs CLO-3 : Identify the problems in common biomedical equipment in hospitals when it is not working and provide a suitable solution CLO-4 : Outline the importance of medical device classification based on the application and ISO standards					a suitable solution	2	80 80	70 70 70		-	М -	- H	-	-	-	-	-	-	-	-	- M	М -	М	-		
CLO-5 CLO-6	: Des : Out	line the job opportunitie	ai device reg es in regulate	ory affairs in Inc	lia				1,2	80 80	70		-	-	-	-	-	-	-	-	-	-	-	L	-	-	-
Durati	on (hou) FUNDAMEN MAN	ITALS OF Q NAGEMENT	UALITY	QUALITY MANA	GEMENT PRIN	ICIPLES	STATISTICAL PROCESS CO	ONTRO	DL TO	OLS	QUAL	ITY N	IANA	GEM	ENT T	ECHI	NIQUE	S		REG	GULA	TORY	′ STRA	TEG	Y	
						9		9							9					9							
S-1	SLO-1	Definition of Quality	,		Customer satisfaction	on		The seven tools of quality: Flo	ow chai	t	I	Benchm	arking	1					F	Purpos	e of re	gulati	on				
	SLO-2	Dimensions of Qual	lity		Customer Perceptio	n of Quality		Check list			1	Benchm	arking	1					F	Principi	les of i	regula vork fi	ntion or roa	ulation	· Nati	ional	
S-2	SLO-1	Dimensions of Qual	lity		Customer Complain	nts		Histograms				Reason	s to B	enchi	mark				L	.egisla	tive pr	ocess	s integr	ulation	. Ivau		
	SLO-2	Quality Planning			Service Quality			Pareto Diagram			I	Reason	to Be	enchn	nark				L p	egal fi process	rame v s	vork f	or reg	ulation	: EU	Legis	lative
S-3	SLO-1	Quality costs.			Customer Retention	1		Cause and Effect diagram			l	Benchm	arking	Proc	ess				F	Relatio nstrum	nship i Ients	betwe	en na	tional	and E	EU leg	;al
	SLO-2	Analysis Technique	s of quality (Cost	Employee Involvem	ent- Motivation		Scatter diagram			l	Benchm	arking	Proc	ess				E	Basic le	egialat	ion					
S-4	SLO-1	Analysis Technique	s of quality (Cost	Empowerment			Control Charts for variables			(Quality I	uncti	on De	ployn	nent (QFD)		S	Scope	of legi	slatior	1				
0 4	SLO-2	Basic concepts of T	otal Quality	Management	Teams			Control Charts for attributes			(Quality I	uncti	on De	eployn	nent (C	QFD)		E	Basic r	egulat	ory st	raterg	y			
S-5	SLO-1	Historical Review			Recognition and Re	ward		New seven Management tool diagram	s: Affin	ity	I	House o	f Qua	lity					٨	leed fo	or Acc	redita	tion of	f hospi	tals		
	SLO-2	Historical Review			Performance appraisal Relationship diagram				I	House o	f Qua	lity					٨	leed fo	or Acc	redita	tion of	f hospi	tals				
26	SLO-1	Principles of TQM		Continuous process improvement Tree diagram					(QFD Pro	cess						F	DA Re	egulati	ions							
3-0	SLO-2	Leadership			Juran Trilogy	uran Trilogy Matrix Diagram					·	Taguchi	Quali	ty Los	ss Fur	nction			J	loint C	ommis	ssion					
S-7	SLO-1	LO-1 Role of Senior Management - PDSA Cycle Matrix diagram				Matrix diagram	Total Productive Maintenance (TPM Regulatory Bodies of India					of Ind	India-Medical Council of														

	SLO-2	Quality Council	5S	Matrix data analysis diagram	Six sigma	Importance of regulatory system
C 0	SLO-1	Quality Statements	Kaizen	Matrix data analysis diagram	Six sigma	Market Overview
S-8 SLO-2	Strategic Planning	Performance Measures-Basic concepts	Process decision program chart	FMEA	Overview of Regulatory Environment	
<u> </u>	SLO-1	Deming Philosophy	Strategy	Process decision program chart	Types of FMEA	Details of Key Regulator
5-9	SLO-2	Barriers to TQM Implementation	Performance measurement.	Arrow diagram	Benefits of Fmea	Organization Chart — CDSCO

	1	
	1. Rose, J.E., "Total Quality Management", Kogan Page Ltd., 1993	7. Jack Wong and Raymond K Y Tong, "Handbook of Medical device regulatory affairs in Asia", Pan Stanford Publishing Pte.
	2. Cesar A. Cacere& Albert Zana, :ThePractise of clinical Engineering". Academic Press, Newyork, 1997	Ltd., 2 nd Edition, 2018
	3. John Bank, "The Essence of Total Quality Management", Prentice Hall of India, 1993	8. Khandpur R S, "Troubleshooting Electronic Equipment- Includes Repair & Maintenance", Tata McGraw-Hill, 2 nd Edition,
Loorning	4. Webster J.G and Albert M.Cook, "Clinical Engineering, Principles & Practices", Prentice Hall Inc., Engle wood	2009
Desources	cliffs, New Jersey, 1979	9. Nicholas Cram & Selby Holder, "Basic Electronic Troubleshooting for Biomedical Technicians", TSTC Publishing, 2 nd
Resources	5. John J Tobin & Gary Walsh, "Medical Product Regulatory Affairs- Pharmaceutical, Diagnostics, Medical	edition, 2010
	Devices", Wiley-Blackwell, 1 st Edition, 2008	10. Dan Tomal& Neal Widmer, "Electronic Troubleshooting", McGraw Hill, 3rd edition, 2004
	6. Medical Device Regulations Global overview and guiding principles", World Health Organization Geneva,	11Ministry of Health & Family Welfare, "Medical Equipment Maintenance Manual- A first line maintenance guide for end
	2003	users", New Delhi, 2010

Learning Ass	essment										
	Diagm's			Con	tinuous Learning Ass	essment (50% weigh	tage)			Final Examination	(EOV) weightege)
	Diouin's	CLA –	1 (10%)	CLA –	2 (15%)	CLA –	3 (15%)	CLA – 4	l (10%)#		(50 % weightage)
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Lovel 1	Remember	40.0/		10.0/		10.0/		20.0/		200/	
Lever	Understand	40 %	-	40 %	-	40 %	-	30 %	-	30%	-
Loval 2	Apply	10.0/		10.9/		10.0/		10.9/		100/	
Leverz	Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Loval 2	Evaluate	20.0/		20.0/		20.0/		20.0/		200/	
Level 5	Create	20 %	-	20 %	-	20 %	-	30 %	-	30%	-
	Total	10	0 %	10	0 %	10	0 %	10	D %	10) %

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldive	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1. Dr. Rajalakshmi S, SRMIST

Course Code	18BME371T	Course Name	Neuro En	ngineering	Course Category	Е	Professional Elective	L 3	Т 0	P 0	C 3
Pre-requisit Courses	te _{Nil}		Co-requisite Courses		Progressive Courses	Nil					
Course Offerin	ng Department	Biomedical Engineering		Data Book / Codes/Standards	Nil						

Course Learning Rationale (CLR): The purpose of learning this course is to:						Program Learning Outcomes (PLO)														
							-	•		-	•		-	•	10		10	10		15
CLR-1: 0	Understand the basic principles of brain anatomy and function	1	2	3		1	2	3	4	5	6	1	8	9	10	11	12	13	14	15
CLR-2 : L	earn about the principles of nervous system and neurotransmission	e l		(
CLR-3 : L	earn about the applications of neural engineering in sensory disorders	l o	Noc %	%)		ge		ant						ĸ		8				
CLR-4 : L	Inderstand the concepts of BCI and neurophysiologic recording and imaging technologies	B	lo l	ent		vlec		me		ge				×		and	D			
CLR-5 : L	Inderstand the basics of neuro prosthetic devices and neuron modelling	g	icie	m		Nor	sis	elop	gu,	Isa	ure			an	ç	Ξ	nin			
CLR-6 : L	CLR-6: Learn about the concepts of neural imaging and its modeling techniques for various applications						lal	eve	esi	9	Cult	it 8		Ĕ	atio	∞ŏ i	ear			
		ЧЦ ЧЦ	Вd	ed ⊿		erin	n Ar	& D	s, D	2	8	imel		s ler	nic	Mg	Ъ	-	~	e
Course Lear	rning Outcomes (CLO): At the end of this course, learners will be able to:	Level o	Expect	Expecte		Engine	Probler	Design	Analysi Resear	Modern	Society	Environ Sustain	Ethics	Individu	Commu	Project	Life Lor	- OSA	PSO - 2	- OSA
CLO-1 : 0	Understand the anatomy of brain and its functions	1, 2	80	70		М	-	1	-	-	-	-	-	-	-	-	-	М	-	-
CLO-2 : L	2: Understand the nervous system					М	-	-		-	-	-	-	-	-	-		М	-	-
CLO-3 : //	D-3: Identify the applications of neural engineering					М	-	1		-	-	-	-	-	-	-		-	-	Μ
CLO-4 : L	D-4 : Understand BCI system and neuro imaging techniques					М	-			-	-	-	-	-	-	-		-	-	М
CLO-5 : //	0-5 : Identify the various neuro prosthetic devices and neuron modelling					М	-	-		-	•	-	-	-	-	-		-	-	Μ
CLO-6 : L	6: Understand the concepts of neuro prosthetics and its modeling techniques					М	-	-	-	-	-	-	-	-	-	-		-	-	Μ

Duration (hour)		Introduction To Neurons And Nervous Systems	Neuro-Transmission And Neuro- Transmitters	Neural stimulation and Neural modeling	Neuro-Prosthetics				
		9	9	9	9	9			
S-1	SLO-1	Brain anatomy	Nervous system	Brain Computer Interface	Sensory prosthetics	Deep brain stimulation			
5-1	SLO-2	Structure of neurons	Nervous system	History of BCI	Retinal prosthetics	Deep brain stimulation			
6.2	SLO-1	Function of neurons Central nervous system Components of a BCI System V		Visual prosthetics	Spinal cord stimulation				
3-2	SLO-2	Types of neurons	Peripheral nervous system	Functional Components	Bionic eye	Spinal cord stimulation			
6.2	SLO-1	Neuroglia	Neurotransmission	Feedback	Bionic eye	Cortical stimulation			
3-3	SLO-2	Myelinated and unmyelinated nerve fibers	Stages in neurotransmission	Signal Acquisition	Auditory prosthetics	Cortical stimulation			
	SLO-1	Properties of nerve fibres	Synaptic transmission	Invasive Techniques	Cochlear implant	Transcranial direct current stimulation			
S-4	SLO-2	Excitability, conductivity, all-or none law, accommodation, adaptation, summation, refractory period, indefatiguability	Synaptic transmission	Noninvasive Techniques	Cochlear implant	Transcranial direct current stimulation			
S-5	SLO-1	Synapse	Chemical synaptic transmission	Feature Extraction and Translation Techniques	Bionic ear	Single neuron model			

	SLO-2	Glial cells	Chemical synaptic transmission	Types of BCI Signals	Bionic ear	Single neuron model		
S-6	SLO-1	Myelination	Electrical synaptic transmission	Training of BCI signals	Spinal cord stimulator	Hodgkin Huxley neuron model		
	SLO-2	Neuronal differentiation	Electrical synaptic transmission	Signal Processing and Feature Extraction	Motor prosthetics	Hodgkin Huxley neuron model		
67	SLO-1	SLO-1 Characterization of neuronal cells Neurotransmitters and their release BCI development		BCI development	Bladder control implant	Fitzhugh Nagumo models		
5-1	SLO-2	Characterization of neuronal cells	Neurotransmitters and their release	Electroencephalography (EEG)	Bladder control implant	Fitzhugh Nagumo models		
S-8	SLO-1	Blood Brain barrier	Types of neurotransmitters	Principle and working of EEG	Sacral anterior root stimulator	Morris lecar model		
	SLO-2	Blood Brain barrier	Types of neurotransmitters	Computerized axial tomography (CAT) scans in brain imaging	Sacral anterior root stimulator	Morris lecar model		
8.0	SLO-1	Meninges	Fast and slow neurotransmission	Functional Magnetic Resonance Imaging (fMRI)	Prosthetics for conscious control of movements	Hind marsh rose model		
3-9	SLO-2	-2 Cerebrospinal fluid Fast and slow neurotransmission		Functional Magnetic Resonance Imaging (fMRI)	Prosthetics for conscious control of movements	Hind marsh rose model		

Learning Resources

1. Bin He, Neural Engineering, Plenum Publishers, 2005. 2.R.S.Khandpur, Handbook of Biomedical Instrumentation, Mc Graw Hill, 3rd Edition, 2015.

Learning Ass	essment												
	Dia ami'a		Continuous Learning Assessment (50% weightage)										
	BIOOM S	CLA –	1 (10%)	CLA –	2 (15%)	CLA –	3 (15%)	CLA – 4	l (10%)#	Final Examination (50% weightage)			
	Lever of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice		
Laval 4	Remember	10.0/		10.0/		10.0/		20.0/		200/			
Level I	Understand	40 %	-	40 %	-	40 %	-	30 %	-	30%	-		
Lovel 2	Apply	10.0/		10.0/		10 %		10.9/		100/			
Level 2	Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-		
Level 3	Evaluate	20.0/		20.0/		20.0/		20.0/		200/			
	Create	20 %	-	20 %	-	20 %	-	30 %	-	30%	-		
	Total	100 % 100 %		0 %	10	0 %	10	0%	100 %				

Course Designers										
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts								
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldive	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	Dr.A.K.Jayanthy								

		1001150707	a							Course Categor		Course Category				ategon	_		Drafoonianal Floating					L	Т	Р	С
Course Co	de	18BME3721	Course Name		IOT AND TELEHE	ALTH TECHNOLOG	iΥ							:	Pi	rotessio	onal Ele	ective		3	0	0	3				
Pre-req	uisite		Nil		Co-requisite		Nil					Progressive Nil															
Course Offe	ering Depa	artment	t Biomedical Engineering Data Book / Codes/Standards Nil																								
Course Lea	rning Rati	onale (CLR):	The purp	ose of learning this o	course is to:		Learni	ng					Р	rogram	Learr	ning O	utcom	es (PLC	D)								
CLR-1 :	Understa	nd the building blo	cks of IoT			1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15				
CLR-2 :	Understa	nd the technologie	s in IoT									ch			ility												
CLR-3 :	Gain kno	wledge in system r	nanagement in we	earable devices		(moc	(%)	(%)	0	n D	t	sear			iinab		농		g								
CLR-4 :	R-4 : Explore the architecture of smart healthcare systems					g (Blo	ency	nent		s a	bme	, Re	age	Ð	Susta		Ň		inanc	ĝ							
CLR-5 :	Gain kno	wledge in basics o	f tele-health techn	ology and architectu	re involved	nking	ofici	tainr		alysi	evelc	sign	I Us	ultur	t & O		Tea	tion	∞ ∾	ami							
CLR-6 :	Gain kno	wledge in architect	ure of IoT systems	s and its applications	s in healthcare	f Thi	Pr Pr	ed At	i i i	u Ang	& De	s, De	T00	80	men		lal &	Inica	Mgt.	jg Le		~	~				
Course Lea	rning Out	comes (CLO):	At the en	d of this course, lea	rners will be able to:	Level o	Expecte	Expecte		Probler	Design	Analysi	Modern	Society	Environ	Ethics	Individu	Commu	Project	Life Lor	PSO - `	PSO - 2	- OSA				
CLO-1 :	Explain t	he various models	and protocols in Ic	σT		1, 2	80%	70%	Μ	-	-	-	-	-	-	-	-	-	-	-	М	-	-				
CLO-2 :	LO-2 : Demonstrate the various technologies for building IOT					2	80%	70%		-	-	L	-	-	-	-	-	-	-	-	М	-	-				
CLO-3 :	: Explain the IoT system management and its applications					2	80%	70%		-	-	L	-	-	-	-	-	-	-	-	М	-	-				
CLO-4 :	4: Apply the techniques in Realtime healthcare applications				3	80%	70%	М	-	-	-	-	-	-	-	-	-	-	-	М	-	-					
CLO-5 :	5: Explain the architecture in tele health technology					3	80%	70%	М	-	-	-	-	-	-	-	-	-	-	-	М	-	-				
CLO-6 :	6 : Demonstrate the IoT system architecture for healthcare applications					3	80%	70%	М	-	-	-	-	-	-	-	-	-	-	-	М	-	-				

		Building blocks of IoT	loT Enabling Technologies	Machine-to-Machine and system management	Smart healthcare applications	Telehealth Technology			
Duration (hour)		9	9	9	9	9			
	SLO-1	Characteristics of IoT	Wireless sensor network	Smart healthcare	Real time smart healthcare model using IoT	Mobile application for medical diagnosis			
S-1	SLO-2	Physical design of IoT	Cloud computing	Distributed Analytics and Edge Intelligence	Sensor modules	Architecture of the program, design of the modules			
6.2	SLO-1	IoT protocols	Big data analytics	Smart Healthcare Use Cases and Applications	Model Architecture	Telecardiology to detect cardiac abnormalities			
5-2	SLO-2	loT devices	Communication protocols	Healthcare Monitoring	Wearable smart health management clothing	Telecommunications, Wearable device for ECG monitoring			
	SLO-1	Network/internet layer	Embedded systems	Wearable Devices	Data acquiring	Virtual clinic – a telemedicine framework			
S-3	SLO-2	Transport layer,	Key components	architecture of wearable devices in health care	Training and testing, accuracy prediction	System model			
S_4	SLO-1	Application layer	IoT levels and deployment templates	Pulse Rate Monitoring System	Fog based Real time analytics	Research methodology			
0-4	SLO-2	Layer protocols	System components	Smart Glove for Paralyzed Patients	IoT analytics	Proposed clinical decision support systems			
	SLO-1	Logical design of IoT	IoT level - 1	Automatic Medicine Dispenser	Data gathering and Consumptions	Personalized Telehealth care			
S-5	SLO-2	IoT functional blocks	loT level - 2	Smart Healthcare Applications and Real-Time Analytics Through Edge Computing q	Protocols used for IoT platform	Categories based tele-based services			
8-6	SLO-1	Communication models	IoT level - 3	Comparison cloud, fog and edge computing	Real-Time Stream Processing	Telediagnosis			
0-0	SLO-2	Request response model	Applications	Edge Computing and Healthcare Systems	Fog Computing	Machine learning approach for telediagnosis			
S-7	SLO-1	Publish subscribe model	IoT Level – 4	Edge Computing General Framework	Fog computing architecture	Architecture of Mobile Telemedicine System using MMS for telediagnosis			
	SLO-2	Push pull model, Exclusive pair model	IoT Level – 5	Edge Computing Use Cases	Characteristics of fog computing	Teleconsultation, Telenursing			
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	SLO-1	IoT communication ApIs	IoT Level – 6	Edge Computing for Real-Time Analysis	Comparison of fog, cloud, and edge	Teletreatment and Telerehabilitation			
S-8	SLO-2	Rest based communication APIs	Applications	Serverless Framework for Real-Time Analysis	Role of Fog Computing in Healthcare	Tele-Psychiatry			
S-0	SLO-1	Request response model used by REST	Wellness monitoring and diagnosis	Deployment of Healthcare Applications	Ethical Challenges, Telemedicine Authorization				
9-9	SLO-2	WebSocket based communication APIs	Wearable electronics	Challenges for IoT-based Edge computing and deployment	Case Study: A Real-Time Fog Healthcare Scenario, Patient monitoring system	Challenges to Tele-Based Healthcare			
Learning Resources	1.	Arshdeep Bahga, Vijay Madisetti ," Internet d 2. Pethuru Raj, Jyotir Moy Chatterjee, Abh Use Cases for the Healthcare Industry"	of things-Hands on approach"VPT Edition 1, nishek Kumar, B. Balamurugan. "Internet of Springer, 2020	2014. 3. Rajkumar Buyya, An Things 4. Hemanth D. Jude, V. and Remote Applicai	nir Vahid Dastjerdi, "Internet of Things: Principles a alentina Emilia Balas, "Telemedicine Technologie: tions for Global Healthcare", Academic Press, 201	and Paradigms" ,Elsevier, 2016. s: Big Data, Deep Learning, Robotics, Mobile 9			

Learning Assessment													
	Diagm's			Con	tinuous Learning Ass	essment (50% weight	tage)			Final Examination	(EO9/ woightogo)		
	DIOUIIIS	CLA –	1 (10%)	CLA –	2 (15%)	CLA –	3 (15%)	CLA – 4	(10%)#		r (50% weightage)		
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice		
Lovel 1	Remember	10.9/		10.0/		10.9/		20.0/		200/			
Level 1	Understand	40 %	-	40 %	-	40 %	-	30 %	-	30%	-		
Lovel 2	Apply	10.9/		10.0/	_	10.9/		10.0/		100/			
Level Z	Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-		
Loval 2	Evaluate	20.0/		20.0/		20.0/		20.0/		200/			
Level 5	Create	20 %	-	20 %	-	20 %	-	30 %	-	30%	-		
	Total	10	0 %	10	0 %	10	0 %	100) %	10	0 %		

Course Designers													
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts											
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldive	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1. Dr. T.Jayanthi, SRMIST											

Course Code	18BME373T	Course Name	MICRO FLUIDICS	Course Category	Е	Professional Elective	L 3	Т 0	P 0	C 3
Pre-requisi Courses	te _{Nil}	Co-Requisite Courses	Nil	Progressive Courses	e Nil					
Course Offeri	ng Department	Biomedical Engineering	Data Book / Codes/Standards	Nil						

Course Learning Rationale (CLR): The purpose of learning this course is to:	Learning Program Learning Outcomes (PLO)																	
					1			_		1 - 1	-							
CLR-1 : Understand the basic concepts o the microfludic and nanofluidic	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2: Get an idea about the Interfaces in Microfluidic and Nanofluidic Systems																		
CLR-3 : Acquire an idea about the materials and various fabrication methods and techniques	l	%	%)	ge		j.						농		e				
CLR-4: Get an idea about the fluidic control methods and detection methods	(Bk	nc)	ent	Med		E C		ge				Š		ano	0			
CLR-5: Get an idea about the application of various microfludic and nanofluidic in biological system	bu	cie.	E	2 Q	Sis	d dia	gn,	Isa	nre	_		an	c	цЦ.	ui.			
CLR-6: Get an overall idea about the microfluidic and nanofluidic system importance in Medical Domain	inki	rofi	ıttai	Σ Σ)al v	eve	esi	٥٢	Ē	it 8		Ĕ	atio	o⊗ it	ear			
	L L	В П П	d be	erin e	١Ar	~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~	с С	To	~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~	mel		al 8	nic	Mgi	ЪГ			e
Course Learning Outcomes (CLO): At the end of this course, learners will be able to:	Level of	Expecte	Expecte	Enginee	Problen	Design	Analysi Resean	Modern	Society	Environ Sustain	Ethics	Individu	Commu	Project	Life Lor	PSO - 1	PSO - 2	PSO -
CLO-1: Understanding of the fundamental of the microfluidic and nanofluidic	1, 2	80	70	М	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-2 : Analyze the various interfaces with surface and devices	1, 2	80	70	М	-	-	-	-	-	-	-	-	-	-	-	М	-	-
CLO-3 : Describes about the techniques and methods with materials used for fabrication of micofluidic and nanofluidic structures	2	80	70	-	М	-	-	-	-	-	-	-	-	-	-	М		-
CLO-4 : Overview of problem for control and detection 's of fluid interaction and techniques used for solving	1	80	70	-	-	Н	-	-	-	-	-	-	-	-	М	-	М	-
CLO-5 : Outline the importance of microfluidic and nanofluidic in biological application	1	80	70	-	-	-	-	-	-	-	-	-	-	-	М	-	-	-
CLO-6 :				-	-	-	-	-	-	-	-	-	-	-	-	-	-	-

Durati	on (hour)	Basic Microfludic concepts	Materials and fabrication Processes for Microfluidic	Fluidic control methods and Detection methods	Microdevice Technologies	Applications to Biological System
		9	9	9	9	9
S 1	SLO-1	Introduction to Microfluidics	Materials for Microfluidic Devices	Fluid Control :Basic theory	Actuators for micropumps	Electrophoresis:DNA separation
3-1	SLO-2	Introduction to Microfluidics	Silicon Based Materials	Pressure –Driven Flow	Actuators for micropumps	Case study :DNA separation
• •	SLO-1	The microfluidic advantage	Glass Based Materials	Shear driven Flow	Actuators for Microvalves	Shear-driven flow: Biomolecular separation
S-2	SLO-2	Fluidics and Transport Fundamentals: The continuum approximation	Polymers Based Material	Shear driven flow examples	Actuators for Microvalves	Case study : Biomolecular separation
	SLO-1	Laminar flow	Fabrication of Microfluidics devices	Electrokinetically –driven flow	Flow sensors	Ion Transport with case study
5-3	SLO-2	Laminar flow(contd.)	Photolithography & its techniques	Electrokinetically –driven flow problem and examples	Microarrays	Concentration with case study
84	SLO-1	Diffusion in microfluidic systems	Additive Techniques	Single Molecule Detection Methods	Microarrays	Bioanalysis:Immunoassay
S-4 SLO-2		Diffusion in microfluidic systems(contd.)	Subtractive Techniques	Optical detection methods	Microreactors	DNA analysis
S-5	SLO-1	Surface forces and droplets	Silicon microfabrication	Optical detection methods examples	Microreactors	On-chip separations and combinations

	SLO-2	Surface forces and droplets(contd.)	(Dry Reactive Ion Etching) DRIE	Electrochemical method	Pipettes and Dispensers	Sample injection and separation
	SLO-1	Pumps and valves	Surface micromachining	Electrochemical method examples	Pipettes and Dispensers	Micro-gas chromatography:
3-0	SLO-2	Pumps and valves(contd.)	Glass Microfabrication – wet isotropic etching	Measurement of Fluidic Properties: Nonintrusive flow measurement techniques	Microanalytical Chips	Micro gas sensors for micro GC
87	SLO-1	Electrokinetics	Wafer Bonding – Fusion, Anionic and Adhesive	Streaming potential/current measurement in pressure-driven flows	Microanalytical Chips	Case study for a micro GC
S-7 SLO-2	Electrokinetics(contd.)	Polymer microfabrication	Current monitoring in electroosmotic flow	Electrochemical microfluidics devices	Micro-scale impedance measurements	
e .	SLO-1	Electro-osmosis	Injection molding and Hot embossing	Optical flow imaging techniques using a tracer: Properties of flow tracers	Electrochemical microfluidics devices(contd.)	Biosensor
3-0	SLO-2	Electro-osmosis(contd.)	Casting & Lithography	Scalar image velocimetry	Paper Microfluidics devices	Biosensors: Case study 1
	SLO-1	Electrophoresis	Fabrication of microfluidic channels in SU-8	Scalar image velocimetry	3D Printed Microfluidic Devices	Nano- Biosensors
S-9 SLO-2	Dielectrophoresis	Microfluidic networks created in biodegradable materials.	Laser-induced fluorescence photo bleaching anemometer with stimulated emission depletion	3D Printed Microfluidic Devices(contd.)	Nano-Biosensors: Case study 2	

	1. Patric Tabeling "Introduction to Microfluids" Oxford U. Press, New York 2005.	5. Wei-Cheng Tian, Erin Finehout," Microfluidics for Biological Applications"Springer, 2008
	2. Yujun Song, Daojian Cheng& Liang Zhao," Microfluidics: Fundamentals, Devices, and Applications", Wiley-	6. Nam-Trung Nguyen, Steven T. Wereley, "Fundamentals And Applications of Microfluidics, Artech Print on Demand, Second
Looming	VCH,First edition ,2018	Edition, 2006
Desources	3. Xiujun (James) Li and Yu Zhou," Microfluidic devices for biomedical applications", Woodhead Publishing	7. Sushanta K. Mitra, Suman Chakraborty "Microfluidics and Nanofluidics Handbook: Fabrication, Implementation, and
Resources	Limited, 16 th edition, 2013.	Applications", CRC Press; 1 edition, 2017.
	4.Jeffrey D. Zahn," Methods in Bioengineering -Biomicrofabrication and Biomicrofluidics", Artech House , 1st	8. Jan Korvink, Oliver Haber, "MEMS: A Practical Guide to Design, Analysis, and Applications", Springer, 2006
	edition,2010	9. Chandra K. Dixit, Ajeet Kaushik," Microfluidics for Biologists: Fundamentals and Applications", Springer, 2016

Learning Assessment													
	Dia ami'a			Cor	ntinuous Learning Ass	essment (50% weigh	tage)			Final Eventination	(EOO)		
	BIOOM S	CLA –	1 (10%)	CLA –	2 (15%)	CLA –	3 (15%)	CLA –	4 (10%)#	Final Examination	i (50% weightage)		
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice		
Loval 1	Remember	10.0/		10.0/		10.0/		20.0/		200/			
Level 1	Understand	40 %	-	40 %	-	40 %	-	30 %	-	30%	-		
Lovel 2	Apply	10 %		10 %		10 %		10 %		10%			
Level 2 Apply Analyze	Analyze	40 70	-	40 /0	-	40 70	-	40 /0	-	4070	-		
Loval 2	Evaluate	20.0/		20.0/		20.0/		20.0/		200/			
Level 3	Create	20 %	-	20 %	-	20 %	-	30 %	-	30%	-		
	Total	10	0 %	10	0 %	100 %		10	0 %	10	0 %		

Course Designers												
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts										
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldive	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1. Ms. Oinam Robita Chanu										

Course Code	18BME374T	Course Name	MEDICAL ETHICS AND INTELL	ECTUAL PROPERTY RIGHTS	Course Category	Е	Professional Elective	L 3	Т 0	P 0	C 3
Pre-requisite Courses	Nil		Co-requisite Courses		Progressive Courses	Nil					
Course Offering	Department	Biomedical Engineering	· · · · ·	Data Book / Codes/Standards	Nil						
Course Learning	Rationale (CLR):	The purpose of learning	this course is to:		Learning		Program Learning Outcomes (PLO))			

				1	,ı														r	
Understand the fundamentals	of medical ethics		1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Get an idea about the codes of	f medical ethics		Ē	-	_				arch			bility								
R3: Acquire an idea about intellectual property rights					%)	dge		üt	sea			ina		ъ К		e				
LR-4: Get an idea about patents						vlec		m	Re	ge		lste		N		and	D			
LR-5 : Get an idea about copyrights						Nov	/SiS	de de	g,	Jsa	nre	s Sl		ean	ç	Ē	nin			
LR-6 : Get an overall idea about trademarks and geographical indicators						gК	lal)eke	lesi	이니	Ħ	nt 8		Ĕ	atio	t &	ear			
			μĻ	р Ш	d Þ	erin	١٩	~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~	Ś	To	8	me		als	uic.	Mg	Ъ			3
earning Outcomes (CLO):	At the end of this course, learners will be able to:		Level of	Expecte	Expecte	Enginee	Problen	Design	Analysi	Modern	Society	Environ	Ethics	Individu	Commu	Project	Life Lor	PSO - 1	PSO - 2	- OS4
Outline the importance of med	lical ethics		1, 2	80	70	-	-	-	-	1	-	,	Н	-	-	-	М	-	-	-
Analyze the development of IF	PR		1, 2	80	70	-	-	-	-	1	М		-	-	-	-	М	М	-	-
CLO-3: Understand the principle of various agreements				80	70	-	-	-	-		-		-	-	-	-	М	М		-
CLO-4 : Outline the importance of patents				80	70	-	-	-	-	-	М	-	-	-	-	-	М	-	М	-
CLO-5: Understand the importance of copyrights				80	70	-	-	-	-	-	M	-	-	-	-	-	М	-	-	-
LO-6 : Understand the concept of trademarks and geographical indicators			1,2	80	70	-	-	-	-	-	-	-	-	-	-	-	М	-	-	-
	Understand the fundamentals Get an idea about the codes o Acquire an idea about intellect Get an idea about patents Get an idea about copyrights Get an overall idea about tradu arning Outcomes (CLO): Outline the importance of med Analyze the development of IF Understand the principle of va Outline the importance of pate Understand the importance of o Understand the concept of traduction	Understand the fundamentals of medical ethics Get an idea about intellectual property rights Get an idea about intellectual property rights Get an idea about patents Get an idea about copyrights Get an overall idea about trademarks and geographical indicators arning Outcomes (CLO): At the end of this course, learners will be able to: Outline the importance of medical ethics Analyze the development of IPR Understand the principle of various agreements Outline the importance of copyrights Understand the importance of copyrights Understand the concept of trademarks and geographical indicators	Understand the fundamentals of medical ethics Get an idea about intellectual property rights Get an idea about intellectual property rights Get an idea about patents Get an idea about copyrights Get an overall idea about trademarks and geographical indicators arning Outcomes (CLO): At the end of this course, learners will be able to: Outline the importance of medical ethics Analyze the development of IPR Understand the principle of various agreements Outline the importance of copyrights Understand the importance of copyrights Understand the concept of trademarks and geographical indicators	Understand the fundamentals of medical ethics 1 Get an idea about the codes of medical ethics 1 Acquire an idea about intellectual property rights 6 Get an idea about patents 6 Get an idea about patents 6 Get an overall idea about trademarks and geographical indicators 9 arning Outcomes (CLO): At the end of this course, learners will be able to: Outline the importance of medical ethics 1, 2 Analyze the development of IPR 1, 2 Understand the principle of various agreements 2 Outline the importance of patents 1 Understand the principle of various agreements 1 Understand the principle of patents 1 Understand the concept of trademarks and geographical indicators 1	Understand the fundamentals of medical ethics 1 2 Get an idea about the codes of medical ethics 6 6 Acquire an idea about intellectual property rights 6 6 Get an idea about patents 6 6 Get an idea about copyrights 7 7 Get an overall idea about trademarks and geographical indicators 7 7 arning Outcomes (CLO): At the end of this course, learners will be able to: 7 7 Outline the importance of medical ethics 1, 2 80 Analyze the development of IPR 1, 2 80 Outline the importance of patents 2 80 Understand the principle of various agreements 2 80 Outline the importance of patents 1 80 Understand the importance of patents 1 80 Understand the importance of opagents 1 80 Understand the importance of trademarks and geographical indicators 1 80 Understand the importance of patents 1 80 Understand the importance of trademarks and geographical indicators 1 80 Understand the concept of trademarks and geographical	Understand the fundamentals of medical ethics 1 2 3 Get an idea about the codes of medical ethics Image: Second Processing Procesenters Processing Processing Processing Processing Pro	Understand the fundamentals of medical ethics 1 2 3 Get an idea about the codes of medical ethics I 2 3 Acquire an idea about intellectual property rights I 0 0 0 Get an idea about patents I 0	Understand the fundamentals of medical ethics 1 2 3 Get an idea about the codes of medical ethics	Understand the fundamentals of medical ethics 1 2 3 Get an idea about the codes of medical ethics I 2 3 Acquire an idea about intellectual property rights I 0 0 0 Get an idea about patents I 0 0 0 0 0 Get an idea about copyrights Image: State about trademarks and geographical indicators Image: State about trademarks about trademarks and geographical indicators	Understand the fundamentals of medical ethics 1 2 3 4 Get an idea about the codes of medical ethics I 2 3 4 Acquire an idea about intellectual property rights I 2 3 4 Get an idea about patents I 0	Understand the fundamentals of medical ethics 1 2 3 4 5 Get an idea about the codes of medical ethics 1 2 3 4 5 Acquire an idea about intellectual property rights 1 2 3 4 5 Get an idea about copyrights 1 2 3 4 5 Get an idea about copyrights 1 2 3 4 5 Get an overall idea about trademarks and geographical indicators 1 2 3 4 5 arning Outcomes (CLO): At the end of this course, learners will be able to: 1 2 80 70 Outline the importance of medical ethics 1, 2 80 70 - - - Understand the principle of various agreements 2 80 70 - <td< td=""><td>Understand the fundamentals of medical ethics 1 2 3 4 5 6 Get an idea about the codes of medical ethics 1 2 3 4 5 6 Acquire an idea about the codes of medical ethics 1 2 3 4 5 6 Get an idea about patents 1 0</td><td>Understand the fundamentals of medical ethics 1 2 3 4 5 6 7 Get an idea about the codes of medical ethics 1 2 3 4 5 6 7 Acquire an idea about the codes of medical ethics 1 2 3 4 5 6 7 Get an idea about patents 1 2 3 4 5 6 7 Get an idea about patents 1 2 3 4 5 6 7 Get an idea about trademarks and geographical indicators 1 80 70 1 1 2 3 4 5 6 7 Mining trademarks and geographical indicators 1 2 80 70 1 1 2 3 4 5 6 7 Mining trademarks and geographical indicators 1 2 80 70 1 2 1 2 1 2 1 2 1 2 1 2 1 2 1 2 1 2 1 2 2 2<</td><td>Understand the fundamentals of medical ethics Get an idea about the codes of medical ethics Acquire an idea about the codes of medical ethics Get an idea about the codes of medical ethics Get an idea about the codes of medical ethics Get an idea about the codes of medical ethics Get an idea about trademarks and geographical indicators The end of this course, learners will be able to: Outline the importance of medical ethics 1, 2 80</td><td>Understand the fundamentals of medical ethics 1 2 3 4 5 6 7 8 9 Get an idea about the codes of medical ethics 1 2 3 4 5 6 7 8 9 Acquire an idea about intellectual property rights 1 2 3 4 5 6 7 8 9 Get an idea about tratelectual property rights 1 0</td><td>Understand the fundamentals of medical ethics Acquire an idea about the codes of medical ethics Acquire an idea about the codes of medical ethics Acquire an idea about the codes of medical ethics Get an idea about the codes of medical ethics Get an idea about trademarks and geographical indicators arning Outcomes (CLO): At the end of this course, learners will be able to: Outline the importance of medical ethics 1, 2 80</td><td>Understand the fundamentals of medical ethics Get an idea about the codes of medical ethics Acquire an idea about intellectual property rights Get an idea about tagtents Get an idea about tagtents Get an overall idea about tagtents Get an overall idea about tagtents Get an overall idea about tagtents Get an overall idea about tagtents Get an overall idea about tagtents Get an overall idea about tagtents Get an overall idea about tagtents Get an overall idea about tagtents Get an overall idea about tagtents Outline the importance of medical ethics Analyze the development of IPR 1, 2, 80, 70 Understand the principle of various agreements 0. Understand the importance of opatients 1, 80, 70 1, 80, 70 1, 80, 70 1, 80, 70 1, 80, 70 1, 80, 70 1, 80, 70 1, 80, 70 1, 80, 70 1, 80, 70 1, 80, 70 1, 80, 70 1, 80, 70 1, 80, 70 1, 80, 70 1, 80, 70 <td>Understand the fundamentals of medical ethics 1 2 3 4 5 6 7 8 9 10 11 12 Get an idea about the codes of medical ethics 1 2 3 4 5 6 7 8 9 10 11 12 Acquire an idea about the codes of medical ethics 1 2 3 4 5 6 7 8 9 10 11 12 Get an idea about topyrights 1</td><td>Understand the fundamentals of medical ethics Get an idea about the codes of medical ethics Acquire an idea about intellectual property rights Get an idea about intellectual property rights Get an idea about trademarks and geographical indicators aming Outcomes (CLO): At the end of this course, learners will be able to: Outline the importance of medical ethics Analyze the development of IPR 0. Understand the principle of various agreements 1. 2 80 1. 2 80 1. 2 80 0. Understand the importance of copyrights 0. Understand the concept of trademarks and geographical indicators 1. 2 80 1. 2 80 0. Understand the formorance of medical ethics 1. 2 0. Understand the importance of copyrights 1 0. Understand the concept of trademarks and geographical indicators 1 1. 2 80 70 0. Understand the concept of trademarks and geographical indicators 1 1. 2 80 70 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0</td><td>Understand the fundamentals of medical ethics 1 2 3 4 5 6 7 8 9 10 11 12 13 14 Get an idea about the codes of medical ethics Acquire an idea about intellectual property rights 1 2 3 4 5 6 7 8 9 10 11 12 13 14 Acquire an idea about intellectual property rights Get an idea about trademarks and geographical indicators 1 2 3 4 5 6 7 8 9 10 11 12 13 14 Get an idea about patents Get an idea about trademarks and geographical indicators 1 10 10 10 11 12 13 14 Get an idea about trademarks and geographical indicators 13 14 10 10 10 11 12 13 14 Get an idea about trademarks and geographical indicators 1,2 10 10 10 10 10 11 13 14 14 14 14 14 14 14 14 14</td></td></td<>	Understand the fundamentals of medical ethics 1 2 3 4 5 6 Get an idea about the codes of medical ethics 1 2 3 4 5 6 Acquire an idea about the codes of medical ethics 1 2 3 4 5 6 Get an idea about patents 1 0	Understand the fundamentals of medical ethics 1 2 3 4 5 6 7 Get an idea about the codes of medical ethics 1 2 3 4 5 6 7 Acquire an idea about the codes of medical ethics 1 2 3 4 5 6 7 Get an idea about patents 1 2 3 4 5 6 7 Get an idea about patents 1 2 3 4 5 6 7 Get an idea about trademarks and geographical indicators 1 80 70 1 1 2 3 4 5 6 7 Mining trademarks and geographical indicators 1 2 80 70 1 1 2 3 4 5 6 7 Mining trademarks and geographical indicators 1 2 80 70 1 2 1 2 1 2 1 2 1 2 1 2 1 2 1 2 1 2 1 2 2 2<	Understand the fundamentals of medical ethics Get an idea about the codes of medical ethics Acquire an idea about the codes of medical ethics Get an idea about the codes of medical ethics Get an idea about the codes of medical ethics Get an idea about the codes of medical ethics Get an idea about trademarks and geographical indicators The end of this course, learners will be able to: Outline the importance of medical ethics 1, 2 80	Understand the fundamentals of medical ethics 1 2 3 4 5 6 7 8 9 Get an idea about the codes of medical ethics 1 2 3 4 5 6 7 8 9 Acquire an idea about intellectual property rights 1 2 3 4 5 6 7 8 9 Get an idea about tratelectual property rights 1 0	Understand the fundamentals of medical ethics Acquire an idea about the codes of medical ethics Acquire an idea about the codes of medical ethics Acquire an idea about the codes of medical ethics Get an idea about the codes of medical ethics Get an idea about trademarks and geographical indicators arning Outcomes (CLO): At the end of this course, learners will be able to: Outline the importance of medical ethics 1, 2 80	Understand the fundamentals of medical ethics Get an idea about the codes of medical ethics Acquire an idea about intellectual property rights Get an idea about tagtents Get an idea about tagtents Get an overall idea about tagtents Get an overall idea about tagtents Get an overall idea about tagtents Get an overall idea about tagtents Get an overall idea about tagtents Get an overall idea about tagtents Get an overall idea about tagtents Get an overall idea about tagtents Get an overall idea about tagtents Outline the importance of medical ethics Analyze the development of IPR 1, 2, 80, 70 Understand the principle of various agreements 0. Understand the importance of opatients 1, 80, 70 1, 80, 70 1, 80, 70 1, 80, 70 1, 80, 70 1, 80, 70 1, 80, 70 1, 80, 70 1, 80, 70 1, 80, 70 1, 80, 70 1, 80, 70 1, 80, 70 1, 80, 70 1, 80, 70 1, 80, 70 <td>Understand the fundamentals of medical ethics 1 2 3 4 5 6 7 8 9 10 11 12 Get an idea about the codes of medical ethics 1 2 3 4 5 6 7 8 9 10 11 12 Acquire an idea about the codes of medical ethics 1 2 3 4 5 6 7 8 9 10 11 12 Get an idea about topyrights 1</td> <td>Understand the fundamentals of medical ethics Get an idea about the codes of medical ethics Acquire an idea about intellectual property rights Get an idea about intellectual property rights Get an idea about trademarks and geographical indicators aming Outcomes (CLO): At the end of this course, learners will be able to: Outline the importance of medical ethics Analyze the development of IPR 0. Understand the principle of various agreements 1. 2 80 1. 2 80 1. 2 80 0. Understand the importance of copyrights 0. Understand the concept of trademarks and geographical indicators 1. 2 80 1. 2 80 0. Understand the formorance of medical ethics 1. 2 0. Understand the importance of copyrights 1 0. Understand the concept of trademarks and geographical indicators 1 1. 2 80 70 0. Understand the concept of trademarks and geographical indicators 1 1. 2 80 70 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0</td> <td>Understand the fundamentals of medical ethics 1 2 3 4 5 6 7 8 9 10 11 12 13 14 Get an idea about the codes of medical ethics Acquire an idea about intellectual property rights 1 2 3 4 5 6 7 8 9 10 11 12 13 14 Acquire an idea about intellectual property rights Get an idea about trademarks and geographical indicators 1 2 3 4 5 6 7 8 9 10 11 12 13 14 Get an idea about patents Get an idea about trademarks and geographical indicators 1 10 10 10 11 12 13 14 Get an idea about trademarks and geographical indicators 13 14 10 10 10 11 12 13 14 Get an idea about trademarks and geographical indicators 1,2 10 10 10 10 10 11 13 14 14 14 14 14 14 14 14 14</td>	Understand the fundamentals of medical ethics 1 2 3 4 5 6 7 8 9 10 11 12 Get an idea about the codes of medical ethics 1 2 3 4 5 6 7 8 9 10 11 12 Acquire an idea about the codes of medical ethics 1 2 3 4 5 6 7 8 9 10 11 12 Get an idea about topyrights 1	Understand the fundamentals of medical ethics Get an idea about the codes of medical ethics Acquire an idea about intellectual property rights Get an idea about intellectual property rights Get an idea about trademarks and geographical indicators aming Outcomes (CLO): At the end of this course, learners will be able to: Outline the importance of medical ethics Analyze the development of IPR 0. Understand the principle of various agreements 1. 2 80 1. 2 80 1. 2 80 0. Understand the importance of copyrights 0. Understand the concept of trademarks and geographical indicators 1. 2 80 1. 2 80 0. Understand the formorance of medical ethics 1. 2 0. Understand the importance of copyrights 1 0. Understand the concept of trademarks and geographical indicators 1 1. 2 80 70 0. Understand the concept of trademarks and geographical indicators 1 1. 2 80 70 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0	Understand the fundamentals of medical ethics 1 2 3 4 5 6 7 8 9 10 11 12 13 14 Get an idea about the codes of medical ethics Acquire an idea about intellectual property rights 1 2 3 4 5 6 7 8 9 10 11 12 13 14 Acquire an idea about intellectual property rights Get an idea about trademarks and geographical indicators 1 2 3 4 5 6 7 8 9 10 11 12 13 14 Get an idea about patents Get an idea about trademarks and geographical indicators 1 10 10 10 11 12 13 14 Get an idea about trademarks and geographical indicators 13 14 10 10 10 11 12 13 14 Get an idea about trademarks and geographical indicators 1,2 10 10 10 10 10 11 13 14 14 14 14 14 14 14 14 14

Duration (bour)		Medical Ethics	Introduction to Intellectual Property Rights	Patents	Copyrights	Trademarks and Geographical Indicators
Durati	on (nour)	9	9	9	9	9
C 1	SLO-1	Definition and historic evolution of bioethics	Origin and development of IPR	Definition of patents	What is copyright	Trademark and purpose of a trademark
0-1	SLO-2	Codes and guidelines, universal principles	History of IPR	Purpose of a patent	Why copyright	Characteristics of trademark
S-2	SLO-1	Medical ethics:some basic issues	Importance and need for protection of intellectual property	What sort of things can be patented, Patentable and non-patentable inventions,	Literature and artistic works	Functions of trademarks
02	SLO-2	Medical ethics:some basic issues	Rights to be given	Conditions for an invention to be patentable	Protection of copyright	Guidelines for the registration of a trademark
5	SLO-1	Teaching and learning medical ethics	Patentable subject matter	Invention vs Innovation	Right of reproduction	Nontraditional trademarks
5-5	SLO-2	Teaching and learning medical ethics	Emerging trends and issues in IPR	Process Patent	Right of public performance	Major types of trademarks
	SLO-1	Codes of conduct	Creativity and Invention	Product Patent	Right of broadcasting	Protection of a trademark
5-4	SLO-2	Codes of conduct	Theories on concept of property	Types of patent applications	Right of translation	Purpose of a trademark
S-5 -	SLO-1	Rights of patients	Public Vs. Private	Precautions while patenting	Right of Adaptation	Madrid system for the International registration of trademarks
	SLO-2 Rights of patients Tangible Vs. Intangible Industrial Vs. Intellectual		Patent specification	Transfer of copyright	Madrid system for the International registration of trademarks	

S-6	SLO-1	Rights of life	World Intellectual Property Organization(WIPO)	Patent claims	Limitations of copyright	Industrial design
5-0	SLO-2	Rights of life	World Trade Organisation (WTO)	Disclosures and non-disclosures	Enforcement of Rights	Purpose of industrial design
0.7	SLO-1	Malpractice	General Agreement on Tariffs and Trade(GATT) agreement	Patent rights and infringement	International conventions and treaties	Protection of industrial design
5-7	SLO-2	Negligence	Major Conventions on IP	Patent rights and infringement	International conventions and treaties	The Hague agreement
<u> </u>	SLO-1	Care of the terminally ill	Berne Convention	Rights of a patent owner	Benefits from copyright protection	Geographical indication
5-0	SLO-2	Distributive Justice in Health Care	Paris Convention	Patent cooperation treaty	Benefits from copyright protection	Appellation of origin
<u> </u>	SLO-1	Human experimentation	TRIPS agreement	Paris convention for the protection of industrial property	Works that are protected by copyright	Protection of geographical indication(GI)
5-9	SLO-2	Clinical trials	Basic forms of intellectual property rights	Importance, advantages and disdvantages of patents	Works that are not protected by copyright	Difference between a GI and a trademark
Loarnir		1. Ramakrishna B and Anil Kumar H	IS, 'Fundamentals of Intellectual Property Rights:	For Students, 2 Chauda H S Int	raduation To Intellocitual Proporty Pichto Oxfor	d and IPH Publiching 2020
Leann	9	Industrialist and Patent Lawyors'	Nation Proce 2017	J. Chawla H J, Ind	iouuciion To mieneciuai Flopelly Rights, Oxioli	2 anu ibi i Fuulisiling, 2020.

Industrialist and Patent Lawyers', Notion Press, 2017. C M Francis, Medical Ethics, Second Edition, Jaypee Brothers, 2004. Resources 2. Learning Assessment Continuous Learning Assessment (50% weightage) Bloom's CLA - 1 (10%) CLA - 2 (15%) CLA - 3 (15%) CLA – 4 (10%)# Level of Thinking Theory Practice Theory Practice Theory Practice Theory Practice Remember Level 1 40 % 40 % 40 % 30 % ----Understand

Level 3 20 % 20 % 20 % 30 % --Create Total 100 % 100 % 100 % 100 %

40 %

CLA - 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

-

Apply

Analyze Evaluate 40 %

Level 2

Course Designers											
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts									
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldive	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	Dr.A.K.Jayanthy									

-

40 %

40 %

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Final Examination (50% weightage)

100 %

Theory

30%

40%

30%

Practice

-

-

-

Course Code		18BME375T	Course Name		Virtual	Instrumentation Engineer	for Biomedical s	C Ca	ourse tegor	y	E	Professional Elective 3								L 3	T 0	P 0	C 3		
Pre-req Course	uisite ses	Nil	Diama	diaal Engineering	Co-requisite Courses	Nil	hata Daalk / Cadaa/Standarda	Pro C	gress ourse	ive s	Nil														
Course Offering Department Biomedical Engineering Data Book / Codes/Standards																									
Course Learning Rationale (CLR): The purpose of learning this course is to:								L	earniı	ng					Ρ	rogra	m Lea	arning	Outco	mes (PLO)				
CLR-1 :	Unders	tand the fundame	ental Virtual In	strumentation				1	2	3	Γ	1	2	3 4	5	6	6 7	8	9	10	11	12	13	14	15
CLR-2 :	Get an	idea about the so	oftware used i	n Virtual Instrume	ntation and functio	n								_	=		H	Γ.							
CLR-3 :	Acquire	e a concept about	the VI progra	mming				(E	(%)	(%		Ð		÷			ide	an	논						
CLR-4 :	Get an	idea about the bi	omedical appl	ication of Virtual Ir	nstrument			Bloc	lcy (ent (ledg		men		D		SIGIL	No No		ance				
CLR-5 :	Get an	idea about the re	search based	development in th	ne area of Virtual In	strument) Bu	cier	mme		Nou	SIS.			he i	a l	no l	am	c	Ein	ning			
CLR-6 :	Unders	tand the different	biological ap	plication of LabVII	EW			inki	Dof	Attai		g K	naly)eve					S T ⊗	atio	t. &	-ear			
								of TI	cted I	cted /		leerir	em A	n & l	1 010, L		ily or		dual	nunic	ct Mg	ong	-	- 2	β
Course Le	earning (Outcomes (CLO)): At the e	end of this course,	learners will be ab	le to:		Level	Expe	Expe		Engir	Probl	Desig				Ethics	Indivi	Comr	Proje	LifeL	PSO	PSO	PSO
CLO-1 :	Analyze	e the Virtual Instru	ument in heal	thcare domain				1, 2	80	70		М	-		-		-	-	-	-	-	- 1	-	-	-
CLO-2 :	Explain	hthe Virtual Instru	ment process	ses and software				1, 2	80	70		М	-		-		-	-	-	-	-	-	М	-	-
CLO-3 :	Differer	ntiate the various	Programming	techniques				2	80	70		-	-	L	-	-		-	-	-	-		М		-
CLO-4 :	Illustrat	te the concepts of	LabVIEW in	Real time experin	nental			1	80	70		-	-	L	-	-	-	-	-	-	-	-	-	М	-
CLO-5 :	Illustrat	te the concepts of	LabVIEW wi	th suitable examp	les			1	80	70		-	-	L	-			-	-	-	-	-	-	-	-
CLO-6 :	Outline	the research app	lication in Bio	logical				1,2	80	70		-	-	L	-		-	-	-	-	-	-	-	-	-

Durat	on (hour)	Virtual Instrumentation	PROGRAMMING MODE& TECHNIQUES	HARDWARE INSTRUMENT	COMMON INSTRUMENT INTERFACE	LABVIEWS TOOLS & ITS APPLICATIONS
Durat	on (nour)	9	9	9	9	9
S 1	SLO-1	Virtual Instrumentation - Introduction	Data Flow Programming	Digital I/O Techniques	General Purpose Interface Bus(GPIB)	Signal Process: Fourier transform
3-1	SLO-2	Conventional Instrumentation	G' Programming Concepts	Digital I/O Techniques	GPIB :IEEE 488.2 STANDARD	Fourier transform problem
6.2	SLO-1	Architecture of VI	Creating and Saving VIs, SubVIs	Data Acquisition in LabVIEW	RS232	Power spectrum
5-2	SLO-2	Architecture of VI	Wiring, Editing, and Debugging VI	Data Acquisition in LabVIEW	RS485	Correlation
S-3	SLO-1	Conventional Virtual Instrumentation	Control Structures such as the For Loop and the While Loop	Hardware Installation and Configuration	Virtual Instrument Software Architecture(VISA)	Windowing
5-5	SLO-2	Distributed Virtual Instrumentation	Shift Registers and Their function	Components of DAQ	VXI	Filters
64	SLO-1	Virtual Instruments Versus Traditional Instruments	Selection Structures: Case and sequence structures	Components of DAQ	VXI	Oscilloscope
5-4	SLO-2	Advantages of VI	Selection Structures: Formulae nodes, feedback nodes	DAQ Signal Accessory	USB	Waveform generator
S-5	SLO-1	Evolution of LabVIEW	Arrays	DAQ Signal Accessory	USB	Multi-channel data acquisition

	SLO-2	Creating Virtual Instruments Using LabVIEW	Arrays	DAQ Assistant: Create a MAX-Based Task	PCI	Vision and Motion tools
6 6	SLO-1	Creating Virtual Instruments Using LabVIEW	Cluster :Creating Cluster Controls and Indicator	DAQ Assistant: Create a Project-Based Task	PCI Express	Vision and Motion tools- problems
5-0	SLO-2	Advantages of LabVIEW	Cluster functions	DAQ Hardware	PXI	Vision and Motion tools -problems
6.7	SLO-1	Front Panel of Virtual Instruments	Waveform Chart and graph	DAQ Hardware	PCMCIA	Bio Bench
5-7	SLO-2	Block Diagram of Virtual Instruments	XY Graph	DAQ Software	PCMCIA	Biomedical work bench
.	SLO-1	SLO-1 LabVIEW Environment and its Menus Strings, Creating String Controls and Indicators		4–20mA Current Loop	SCXI	Biomedical real time application- ECG
5-6	SLO-2	LabVIEW Environment and its Menus	String Functions	4–20mA Current Loop	SCXI	Biomedical real time application-EMG
<u> </u>	SLO-1	Palletes of LabVIEW	Tables and List Boxes	60 mA Current Loop	LXI	Biomedical real time application-EEG
S-9	SLO-2	Palletes of LabVIEW	File Input/Output Functions	60 mA Current Loop	LXI	Biomedical real time application-EOG

			5. Jon B. Olansen and Eric Rosow, "Virtual Bio-Instrumentation: Biomedical, Clinical, and Healthcare Applications in
		1. S. Sumathi and P. Surekha, "Labview based Advanced Instrumentation Systems", Springer, First edition,	LabVIEW ",Prentice Hall,First edition, 2001
		2007	6. Ronald W. Larsen , "LabVIEW for Engineers", Pearson , First edition, 2010
	Looming	2. Gary Jonson, "Labview Graphical Programming", Second Edition, McGraw Hill, New York, Fourth edition	7. Robert H. Bishop," Learning with LabVIEW", Pearson, First edition, 2014
	Deseuress	2006.	8. John Essick ," Hands-On Introduction to LabVIEW for Scientists and Engineers ", Oxford University Press, Fourth edition
ľ	Resources	3. Lisa K. wells and Jeffrey Travis, "Labview for everyone", Prentice Hall Inc., New Jersey; First edition 1997.	,2018
		4. Gupta S and Gupta J P, "PC interfacing for Data Acquisition & Process Control", Instrument Society of	
		America, Second Edition, 1994	

Learning Assessment												
	Ploom's			Final Examination (50% weightage)								
	Diouin's	CLA – 1	1 (10%)	CLA –	2 (15%)	CLA – S	3 (15%)	CLA – 4	(10%)#		i (50 % weightage)	
	Lever of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	
Lovel 1	Remember	10.0/		40.0/		40.0/		20.0/		200/		
Level I	Understand	40 %	-	40 %	-	40 %	-	30 %	-	30%	-	
Lovel 2	Apply	10 %		10.0/		10.0/		10.0/		100/		
Lever Z	Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-	
Lovel 2	Evaluate	20.0/		20.0/		20.0/		20.0/		200/		
Level 5	Create	20 %	-	20 %	-	20 %	-	30 %	-	30%	-	
	Total 100 % 100 %				0 %	100) %	100) %	100 %		

Course Designers												
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts										
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldive	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1. Ms Oinam Robita Chanu, SRMIST										

Course Cod	e 18BME461T	Course Name	BIOME	EDICAL INFORM	ATICS				Course Category E Professional			nal Ele	ctive		L 3	Т 0	P 0	C 3							
Pre-requ Cours	isite es	Nil	Co-requisite Courses				Nil					Progre Cour	ssive ses		Nil						il				
Course Offer	e Offering Department Electronics and Communication Engineering with specialization in Biomedical Engineering Data Book / Codes/Standards Nil																								
Course Lear	ning Rationale (CLR):	The purpo	ose of learning this course is to:			Le	arnin	g					P	rogram	Learr	ning Ou	utcome	s (PLC))						
CLR-1 :	Understand what is medical	informatics, The ty	pes of medical databases and carious thef	t issues	1	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2 :	Gain knowledge about the si	ructure of Hospita	l information system, clinical Information sy	vstem	1										,										
CLR-3 :	CLR-3 : Understand the telemedicine technology, and types of data transfer					Ê	(9	<u> </u>				arch			ability								1		
CLR-4 :	Gain knowledge in an autom	ation of clinical la	boratories		1	Bloor	y (%	nt (%	adge		Jent	ese			taine		Nork		DCe				1		
CLR-5 :	Learn different decision mak	ing algorithms and	l computerized imaging techniques		1	ng (E	cienc	nmei	9 Mor	SIS.	ndola	JU, R	sage	ar	Sus		am /	_	Fina	ning			1		
CLR-6 :	The learn different types of c patients	omputer aids for I	nandicapped and computers in the care of c	critically ill		of Thinki	ed Profi	ed Attai	ering Kr	m Analy	& Deve	is, Desiç	n Tool U	/ & Cultu	nment &		ual & Te	unicatio	: Mgt. &	ng Lear	-	5			
Course Lear	ning Outcomes (CLO):	At the end	l of this course, learners will be able to:			Level c	Expect	Expect	Engine	Proble	Design	Analys	Moden	Society	Enviro	Ethics	Individ	Comm	Project	Life Lo	- OSA	- OSA	- OS4		
CLO-1 :	Understand applications of c	omputers in healt	h care and different types of medical databa	ases		1, 2 8	80%	70%	М																
CLO-2 :	Implement Hospital Informat	ion system and Cl	inical Information system			28	80%	70%	М																
CLO-3 :	LO-3 : Gain knowledge on telemedicine technology					28	80%	70%			М		М								М		L		
CLO-4 : Implement automation of clinical laboratories						3 8	80%	70%					М												
CLO-5 :	CLO-5 : Apply different decision making algorithm for imaging and diagnosis					3 8	80%	70%	М												М		L		
CLO-6 :	LO-6 : Gain knowledge on various computer aids for handicapped and computers role in care of critically ill patients				nts	3 8	80%	70%	М																

		Medical informatics and Computer based patient record	Hospital Information system and Clinical information system, Telemedicine	Computers in a Clinical Laboratory	Computer assisted medical Decision making	Computer aids for the handicapped & Computers in the care of critically ill patients
Duratio	on (hour)	9	9	9	9	9
C 1	SLO-1	What is Medical Informatics?	Functional capabilities of computerized Hospital information system	Microprocessor for automation	General model of CMD	Mobility, EMG controlled limbs
5-1	SLO-2	Prospects of medical informatics	Need for computerization oh hospitals in India	Database approach to laboratory computerization	Various approaches in decision making	Aids for Blind and visually handicapped
6.0	SLO-1	Historical review of the development of computers and informatics	Security of computer records	Automation of clinical laboratories	Computer assisted decision support systems	Braille system, bat cane
3-2	SLO-2	Foundation ontology	Cost effectiveness of information processing by computer	Automated methods in hematology	Algorithmic methods	Portable reading aids
	SLO-1	What is computer based patient record	Benefits of clinical information system	Chromosome analysis by computer	Elements of a protocol	Artificial vision for the blind
S-3	SLO-2	History taking by computer and Dialogue with the computer	Sources of data for decision making	Computerized cytology and histology	Probabilistic approaches to decision making	Concept of artificial retina
6.4	SLO-1	Development tools Intranet	Modes of decision output to Physician	Automated scanning for cervical scanner	Sequential Bayes, Linear discriminant function	Computer aids for the deaf
5-4	SLO-2	CPR in radiology	Registry of Computerized Medical record system	Computer assisted semen analysis	Multivariate analysis	Computer speech generation and recognition
S-5	SLO-1	Types of databases: Bibliographic databases	CIS in obstetrics – Gynecology	Radio Immunoassays	Database comparisons and case based reasoning	Robotics to assist the elderly infirm

	SLO-2	Non Bibliographic databases	Fetal Monitoring	Intelligent laboratory information system	Production rule systems	Cognitive system engineering
	81.0.1	Madical information ratriaval	What is tolomodicing	Computer aided analysis of	Cognitive models	Automated computer assisted Fluid and
S-6	310-1		What is telemedicine	Echocardiograms		metabolic balance
	SLO-2	Medical information retrieval techniques	Need for telemedicine	Computerized ECG, analysis of signals	Semantic networks	Pulmonary function Evaluation
	SI 0-1	Legal, Security and privacy issues in	Telemedicine technology	Assessment of performance of ECG	Decision analysis in clinical medicine	Computerized decision support for
S-7	320-1	computers and internet	relementatione technology	computer programs		mechanical ventilation
	SLO-2	Types of threats	Types of data transfer	Computerized EEG	Computers in nuclear medicine	Cardiovascular physiological evaluation
	SI 0-1	Chuntography	Mode of transmission	Long term monitoring of EEG	Data acquisition, manipulation and	Computer assisted surgery
S-8	320-1	Cryptography			processing	
	SLO-2	Digital Signature	Internet and telemedicine	Computerized EMG	Computer assisted medical imaging-CT	Robotics in surgery
S-9	SLO-1	User Authentication	Telemedicine websites	Single fibre EMG	CT-Radiation therapy planning	Sensing system
	SLO-2	Attacks from inside and outside the system	Applications of telemedicine	Computerized EEG	Computer for MRI	Interactive modes

	1. Ramchandra Lele., "Computers in Medicine Progress in Medical Informatics", Tata McGraw-Hill Publishing Company	2. Educard 4 Shadiffa Jamaa I. Climina "Diamadical informatica Computer Applications in Haalth
Learning	Limited, New Delhi First Edition, 2005	5. Euwaru n.Shorume, James J. Climino., Biomedical miorinaucs computer Applications in realiti Core and Diamodicine". Caringer, Third Edition, 2006
Resources	2. Mohan Bansal, M S., "Medical Informatics A Primer", Tata McGraw-Hill Publishing Company Limited, New Delhi,	Care and Biomedicine , Springer, Third Edition, 2000.
	2 nd edition 2003.	

Learning Asse	ssment										
	Ploom's			Con	tinuous Learning Asse	essment (50% weight	tage)			Einal Examination	(50% woightage)
	Diuolii S	CLA –	1 (10%)	CLA – 2	2 (15%)	CLA –	3 (15%)	CLA – 4	(10%)#		i (50 % weightage)
	Lever of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Lovel 1	Remember	40.0/		40.0/		40.0/		20.0/		200/	
Level I	Understand	40 %	-	40 %	-	40 %	-	30 %	-	30%	-
Lovel 2	Apply	10.0/		10.0/		10.0/		10.0/		100/	
Level 2	Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Lovel 3	Evaluate	20 %		20 %		20 %		30 %		30%	
Level 3	Create	20 %	-	20 %	-	20 %	-	30 %	-	30%	-
	Total	10	0 %	100) %	10	0 %	100) %	10	0 %

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldive	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1., Dr. S. P. Angeline Kirubha, SRMIST

Course	18BME462T	Course	PHYSIC	LOGICAL MODELING	Course	Е	Professional Elective	L	Т	Ρ	С
Code		Name			Category			3	0	0	3
			• • •								
Pre-requisit	e 18BMC 305T Bic	control Systems	Co-requisite	Nil	Progre	ssive	Nil				
Courses	TODIMOSOOT DIC	control bystems	Courses	140	Cour	ses	1411				
Course Offerin	ig Department	Biomedical Eng	lineering	Data Book / Codes/Standards	Nil						

Course Le	arning Rationale (CLR):	The purpose of learning this course is to:		Learni	ng		Program Learning Outcomes (PLO)														
CLR-1 :	Understand the process of mo	odeling to various physiological systems	1	2	3	1	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Understand the mathematical	tools for static analysis of models				1							×								
CLR-3 :	Perform time domain analysis	of the physiological models	Ê							arch			bilit								
CLR-4 :	Perform frequency domain an	alysis of the physiological models	loo	۸ (%	t (%		dge		ent	esee			aina		/ork		ge				
CLR-5 :	Understand techniques in sys	tem identification and parameter estimation	(B)	enc	men		wle	s	mq	Å	age	Ð	Sust		2 E		inar	b			
CLR-6 :	Understand the techniques in	designing physiological system models and to perform analysis	king	ofici	tainı		Kho	ılysi	velo	sign	n, si	iltur	~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~		Геа	ion	& ⊤	arni			
			T _F	E P	4 Att		ing	Ana	De	De	[00]	U N N	nent		∞ŏ	licat	∕lgt.	e l			
Course Le	arning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of	Expected	Expected		Engineer	Problem	Design 8	Analysis,	Modem -	Society 8	Environn	Ethics	Individua	Commur	Project N	Life Lonç	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Explain the different technique	es in designing physiological model	1,2	80%	70%	1	М	-	-	-	-	-	-	-	-	-	-	-	М	-	-
CLO-2 :	Detail about the tools for stati	c analysis of physiological system	1,2	80%	70%	1	-	М	-	-	-	-	-	-	-	-	-	-	М	-	-
CLO-3 :	Describe the techniques for til	me domain analysis of physiological model	1,2	80%	70%	1	-	М	-	-	-	-	-	-	-	-	-	-	М	-	-
CLO-4 :	Describe the techniques for fr	equency domain analysis of the physiological models	1,2	80%	70%		-	М	-	-	-	-	-	-	-	-	-	-	М	-	-
CLO-5 :	Outline the various methods f	or system identification and parameter estimation	1,2	80%	70%]	-	М	-	-	-	-	-	-	-	-	-	-	М	-	-
CLO-6 :	Interpret the various physiolog	gical system models	1,2	80%	70%		М	-	-	-	-	-	-	-	-	-	-	-	М	-	-

Durati	an (haur)	Linear Model	Static Analysis	Time Domain Analysis	Frequency Domain Analysis	System Identification
Durati	on (nour)	9	9	9	9	9
S_1	SLO-1	Introduction to modeling methodology, need for models, approaches to modeling	Static analysis: Open loop versus closed loop	Introduction to time domain analysis	Frequency response: Open loop frequency response	Identification of physiological control system
5-1	SLO-2	Model identification, model validation and Simulation	Loop gain calculation: Room temperature control	Linearized respiratory mechanics transient response	Closed loop frequency response	Basic problems in Physiological system analysis
6.2	SLO-1	System analysis, fundamental concepts	Steady state characteristics	Linearized respiratory mechanics first order model – impulse response for open loop	Relation between transient and frequency response	Nonparametric and parametric identification methods
5-2	SLO-2	Physiological control system an example	Determination of steady state operating point for simple model of muscle stretch reflex	Linearized respiratory mechanics first order model – impulse response for closed loop	Frequency domain specifications	Numerical Deconvolution, Least square estimation
6.2	SLO-1	Engineering control system versus physiological control system	Human body Glucose – Insulin regulatory system	Transient response descriptors : Impulse response	Graphical representation of frequency response: Bode plot	Estimation using correlation functions
0-0	SLO-2	Science of modeling	Steady state analysis of glucose –insulin model	Transient response descriptors : Step response	Bode plot :Linearized lung mechanics	Estimation in frequency domain, optimization techniques
6.4	SLO-1	Generalized system properties	Human body chemical regulation of ventilatory system	Concept of sliding theory	Graphical representation of frequency response: Nicholas chart	Problems in parameter estimation
3-4	SLO-2	Models with combinations of system elements	Mechanism of respiration	Neuromuscular reflex action	Nicholas chart : Linearized lung mechanics	Input design
6 E	SLO-1	Linear model of respiratory mechanics	Gas exchanger mathematical modeling	Mathematical model of neuromuscular reflex motion	Graphical representation of frequency response : Nyquist plot	Identification of closed loop systems – "opening the loop"
3-0	SLO-2	Linear model of respiratory mechanics: Derivation of transfer function	Respiratory controller mathematical modeling	Calculation of transfer function	Nyquist plot: Linearized lung mechanics	Starling heart- lung preparation
	SLO-1	Linear model of muscle mechanics	Closed loop analysis : lung and controller	Stability and transient response	Introduction : Circulatory system	Kao's cross – circulation experiment
3-0	SLO-2	Linear model of muscle mechanics: Derivation of transfer function	Calculation of transfer function	Root locus and Routh-Hurwitz stability criterion	Mathematical model of circulatory system	Opening the Pupillary reflex loop

0.7	SLO-1	Distributed versus lumped parameter model	Heart and systemic circulation	Stability analysis: root l	ocus method	Frequency response of circulatory system	Read rebreathing technique
5-1	SLO-2	Distributed versus lumped parameter model: Derivation of transfer function	Mathematical modeling of cardiac output	Introduction to Nyquist	plot	Graphical representation for frequency response of circulatory system	Adaptive control of Physiological variables
e 0	SLO-1	Linear system and superposition principle	Calculation of transfer function for simplified model of cardiac output regulation	Nyquist criterion for sta	bility	Frequency response of glucose – insulin model	General adaptive control system
3-0	SLO-2	Laplace transform and transfer function	Cardiac characteristics curve analysis	Relative stability theory		Mathematical model and simulation of glucose – insulin model	Multiple model adaptive control
e 0	SLO-1	Impulse function analysis	Venous retum curve	Physiology: Pupillary re	flex control	Frequency response approach to pupil control	Model reference adaptive control
3-9	SLO-2	Basics of Linear convolution	Closed loop analysis of heart and systemic circulation	Stability analysis of pup	illary reflex control	Frequency response characteristics curve for pupillary control	Optimization in systems with negative feedback
Learni Resou	ng rces	 Michael C.K. Khoo, "Physiologi Prentice Hall of India Private Ltd Claudio Cobelli Ewart Carson, , press series, 1st edition, 2008. 	cal Control Systems - Analysis, Simulation an d., 2 nd edition, New Delhi, 2001. "Introduction to Modeling in Physiology and I	d Estimation", Medicine", Academic	 V.Z. Manand Busi Johnny T 	marelis, <i>"Advanced Methods of Physiological</i> ness Media, 2013. [•] . Ottesen, Mette S. Olufsen, Jesper K. Larser	System Modeling", Vol.3, Springer Science
		5. Dorf, "Modern Control Systems	", Pearson Education India, 1st edition, 2008.		Physiolog	<i>gy",</i> Vol.9,SIAM, 2004 .	

Learning Ass	essment										
	Dia ami'a				Final Examination	(EO0/ woightage)					
	BIOOM S	CLA –	1 (10%)	CLA –	2 (15%)	CLA –	3 (15%)	CLA – 4	(10%)#		r (50% weightage)
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Lovel 1	Remember	20.0/		20.0/		20.0/		20.0/		200/	
Lever	Understand	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
Lovel 2	Apply	10 %		10 %		10 %		10 %		10%	
Leverz	Analyze	40 70	-	40 70	-	40 70	-	40 70	-	4070	-
Loval 2	Evaluate	20.0/		20.0/		20.0/		20.0/		200/	
Level 5	Create	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Total	10	0 %	10	0 %	10	0 %	100) %	10	0 %

Course Designers											
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts									
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldive	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1. Dr. T.Jayanthi, SRMIST									

Course		Course			Co	urse												L	Т	Ρ	(С
Code	18BME463T	Name		BIOMIMETICS	Cate	gory	E				Profe	essiona	al Elec	ctive				3	0	0	3	3
Pre-requ Cours	isite es		Co-requisite Courses	Nil	Proç Co	gressi [.] ourses	ve _{Nil}															
Course Of	ering Department	Biomed	lical Engineering	Data Book / Codes/Standards	s Nil																	
Course Le	arning Rationale (CLR)	: The pu	rpose of learning this course is to:			Learni	ng					Pro	gram	Learn	ning C	outcon	nes (F	PLO)				
CLR-1 :	Understand the fundam	entals of biom	imetics and its applications		1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Study the concepts of b	iomimetic mat	terials and process																			
CLR-3 :	Acquire an idea about th	ne mechanism	of cognition and open ended design	n automation							Ē			₹								
CLR-4 :	Utilize the basic concept	ts of bio-inspir	ed sensors and actuators		(m	(%	(%	Ð		÷	earch			lider		¥		0				
CLR-5 :	Employ the skills about	the biomimetic	cs of human motion		(Bloc	ncy (ent (/ledg		men	Res	æ		ıstair		٥M		ance				
CLR-6 :	Get an overall idea abou	ut the applicati	ion of biomimetic technologies		king	officie	ainm	~uov	lysis	/elop	sign,	Usa	lture	& SL		earr	ы	& Fin	amin.			
					Thin	d Pro	d Atta	ing	Ana	De	, Des	Tool	& Cu	nent		a & 1	icati	Agt. 8	g Lea			
Course Le	arning Outcomes (CLO): At the e	end of this course, learners will be ab	ole to:	Level of	Expecte	Expecte	Enginee	Problem	Design 8	Analysis	Modern	Society	Environr	Ethics	Individua	Commur	Project I	Life Lon	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Apply the basic mechan	ism in biomim	etic design in various applications		1, 2	80	70	L	L	-	-	-	-	-	-	-	-	-	-	L	М	-
CLO-2 :	Identify the basic biologi	ically inspired	mechanism, materials and process		1, 2	80	70	М	-	-	-	-	-	-	-	-	-	-	-	L	-	-
CLO-3 :	Identify the mechanism	of cognition ar	nd open ended design automation		2	75	65	-	L	L	-	-	-	-	-	-	-	-	-	L		-
CLO-4 :	Analyze the importance	bio-inspired s	ensors and biomimetic actuators		1,2	75	65	-	-	М	-		-	-	-	-	-	-	М	-	М	-
CLO-5 :	Analyze the biomechani	cs and rhythm	ics of motion		2,3	75	65	L	М	L	-	-	-	-	-	-	-	-	М	-	L	М
CLO-6 :	Outline the application of	of biomimetic te	echnologies		1,2	75	65	-	L	-	L	-	-	-	-	-	-	-	М	-	-М	-

Du	ration	Introduction to Biomimetics	Mechanism of cognition and open ended design automation	Bio-Inspired Sensors and Biomimetic Actuators	Biomimetics of motion	Application of Biomimetic Technologies
, u	iour)	9	9	9	9	9
8 1	SLO-1	Introduction : Biologically Inspired Mechanisms	Mechanized Cognition	Biomimetic tactile sensing:Human sense of touch	Biomechanics of motion: Control center	Artificial intelligence through symbolic connectionism
SLO-2		Biologically Inspired Mechanisms	Training and Education	Biomimetic tactile sensing:Human sense of touch	Biomechanics of motion: Control center	Localist symbolic connectionism
S-2 SLO-1		Biologically Inspired Structures and Parts	Language Cognition	Biomimetic artificial touch	Passive external and internal actuation	Distributed symbolic connectionism
5-2 SLO-2		Defense and Attack Mechanisms in Biology	Language Cognition	Examples of bio-inspired tactile sensing	Active external and internal actuation	Symbolic connectionism in biological models
S-3 SLO-1		Materials and Processes in Biology	Sound Cognition	Bio-Inspired hair based interial sensors: Hair structures for inertial sensing	Agonist Mechanism: Hygroscopic mechanism	Neurofuzzy systems
	SLO-2	Materials and Processes in Biology	Sound Cognition	Cricket-inspired accelerometer	Muscular actuation	Neurofuzzy systems
	SLO-1	Bio-Sensors	Visual Cognition	Fly-inspired gyroscope	Antagonist mechanism: Spring Antagonism	Bio-Inspired adhesion technologies
S-4	SLO-2	Bio-Sensors	Visual Cognition	Fly-inspired gyroscope	Muscular Antagonism	Bio-Inspired adhesion technologies
S-5	SLO-1	Robotics Emulating Biology	Machine Bodies and Brains: Evolving Controllers and Some Aspects of the Morphology	Olfactory sensor system for the e-nose	Power amplification: Elastic amplification	Bio-Inspired locomotion mechanisms
	SLO-2	Interfacing Biology and Machines	Evolving Bodies and Brains	Olfactory classification-data processing	Deformation of a constant volume	Size and current technologyconstrains
S-6	SLO-1	Muscle function	Morphology Representations: Tree representations	Polymer network actuators	Mechanics of hydrostatic systems: Single compartment systems	Quadruped robot system: Mechanical components

	SLO-2	Muscle function	Developmental representations	iomimetic vision systems Multip		Multiple compartment systems	Quadruped robot system: Mechanical components
	SLO-1	Muscle design	Regulatory network representations	Novel biomimetic materials :Intr	oduction	Rhythmics of motion: Gait	Electrical components of quadruped robot
5-7	SLO-2	Muscle design	Evolving Machines in Physical Reality	Design of self-oscillating polyme	er gel	Rhythmics of motion: Gait	Electrical components of quadruped robot
S-8	SLO-1	Muscle adaptation	Evolving Machines in Physical Reality	Control of self-Oscillating chem- behaviors	omechanical	Passive Locomotion	Biologically inspired antenna array design
	SLO-2	Biomimetics of muscle design	Economy of Design Automation	Design of biomimetic soft actua	tors	Passive locomotion	Biologically inspired antenna array design
5.0	SLO-1	Bio-inspired fiber composites	Principles of Design	Design of autonomous mass tra systems	ansport	Limbless locomotion	Biologically inspired antenna beam pattern design
3-9	SLO-2	Bio-inspired fiber composites	Research Methodology	Self-oscillating fluids		Multiple limb locomotion	Biologically inspired antenna beam pattern design
Learni Resou	ng rces	1. Yoseph Bar-Cohen, "BIOMIMETICS Biolog 2. Trung Dung Ngo, "Biomimetic Technologie Edition, 2015.	gically Inspired Technologies", CRC Press, 1 st Ec es: Principles and Applications", Wood head Publ	dition, 2006. ishing Ltd, 1 st Materials, Stru	rsiani, "Biomim D Bruckner, C I ucturesand Pro	etics of Motion: Nature-Inspired Parameters a Hellmich, · H B. Schmiedmayer, H. Stachelbe cessesExamples, Ideas and Case Studies", S	nd Schemes for Kinetic Design", Springer, 1 st rger, I C. Gebeshuber, "Biomimetics – pringer, 1 st Edition, 2011

Learning Assessm	ent										
				Con	tinuous Learning Ass	essment (50% weight	age)			Final Examination	n (50% weightage)
	Bloom's Level of Thinking	CLA –	1 (10%)	CLA – 2 (15%)		CLA –	3 (15%)	CLA – 4	4 (10%)#		in (50 % weightage)
	5	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
l evel 1	Remember	40 %	-	40 %	_	40 %	-	30 %	_	30%	-
	Understand	10 70		10 70		10 /0		00 //		0070	
Level 2	Apply	40 %	_	40 %		40 %	_	40 %		40%	
Leverz	Analyze	40 70	_	40 70		40 70	_	40 70		4070	_
Level 3	Evaluate	20 %	_	20 %	_	20 %	-	30 %	_	30%	_
	Create	20 70		20 70		20 /0		00 /0		0070	
	Total	100	0 %	100	0 %	10	0 %	10	0 %	10	00 %

Course Designers											
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts									
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldive	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1. Dr.D.Ashok kumar, SRMIST									

Course Code	18BME464T	Course Name	NEURAL NETWORK AN	ID GENETIC ALGORITHM		Co Cat	urse egory	E	Ξ	Professional Elective						L	T 0	P 0	C 3				
Pre-requ Cours	iisite es		Co-requisite Courses			Prog Co	jressi urses	ve S	Vil														
Course Off	ering Department	Electrol special	nics and Communication Engineering with ization in BioElectronics	Data Book / Codes/Standards	Ν	iil																	
Course Le	arning Rationale (CLF): The put	rpose of learning this course is to:		Learning Program Learning Outcomes (PLO)																		
CLR-1 :	Understand the fundar	nental of Artificia	al Neural Network			1	2	3		2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Get an insight about v	arious ANN mod	lel																				
CLR-3 :	Familiarize about the p	rinciple of self-o	organizing map			Ē	(rch			bility								
CLR-4 :	Study the basic conce	ots of Genetic al	lgorithm			loon	y (%	nt (%		anna	ient	esea	-		taina		Vork		g				
CLR-5 :	Get an idea about gen	etic algorithm op	perators			ng (B	cienc	nmer			lopm	д, R	sage	er	Sus		am /	_	Final	ing			
CLR-6 :	Explore on the concep	ts of ANN for Bi	omedical Application			hinki	Profi	Attai	:		Deve	Desi		Culti	ent &		& Te	catio	gt. &	Lean			
						l of T	cted	cted			gn &	/sis, l	an To	ety &	onme	s	dual	muni	ct M	ong.	-	- 2	ε
Course Le	arning Outcomes (CL	O): At the e	end of this course, learners will be able to:			Leve	Expe	Expe			Desiç	Analy	Mode	Socie	Envir	Ethic	Indivi	Com	Proje	LifeL	PSO	PSO	PSO
CLO-1 :	Apply the concepts of	Artificial neural r	network			1, 2	80	70		1 -	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-2 :	Implement the algorith	m of various AN	IN			1, 2	80	70	1	1 -	-	-	-	-	-	-	-	-	-	-	М	-	-
CLO-3 :	Apply the concepts of	Neural network I	based on competition			2	80	70		N	-	-	-	-	-	-	-	-	-	-	М		-
CLO-4 :	Outline the concepts o	f genetic algorith	hm			1	80	70		-	Н	-	-	-	-	-	-	-	-	М	-	М	-
CLO-5 :	Describe the genetic a	lgorithm operato	Drs			1	80	70		-	-	-	-	-	-	-	-	-	-	Μ	-	-	-
CLO-6 :	LO-6 : Implement the concepts of ANN for Biomedical applications					1,2	80	70		-	-	-	-	-	-	-	-	-	-	L	-	-	-

Durat	on (hour)	Artificial neural network: An Overview	Artificial Neural network model	Neural network based on competition	Introduction to Genetic Algorithm	GA Operators and Biomedical Applications
Durut	on (nour)	9	9	9	9	9
6.1	SLO-1	Basics of Artificial Neural network	Feed forward networks	Kohonen SOM : Architecture	Biological Background	Genetic operators:
3-1	SLO-2	Basics of Artificial Neural network	Feed forward networks	Algorithm	Genetic algorithm world	Reproduction, Crossover
6.2	SLO-1	Biological neuron, Properties	Back propagation network- structure	Learning vector Quantization(LVQ) : Architecture	Evolution and optimization	Mutation, Replacement
5-2	SLO-2	Artificial model	Algorithm, Applications	Algorithm	Evolution and Genetic algorithm	Fitness form
• •	SLO-1	Network parameters: Weight, activation, threshold	Tutorial: BPN	Max net: Architecture	Gradient based local optimization method	Scaling
3-3	SLO-2	Typical architecture: Single layer net, Multilayer net, competitive layer	Tutorial: BPN	Application procedure	Gradient based local optimization method	Population
54	SLO-1	Common activation function	Associative memory: Heteroassociative memory : Architecture	Mexican Hat: Architecture	Random search	Data structure
3-4	SLO-2	Common activation function	Applications	Training algorithm	Stochastic Hill climbing	Encoding: Binary , Octal,
S-5	SLO-1	McCULLOCH-PITTS net: Architecture	Associative memory:Autoassociative Net: Architecture	Hamming net : Architecture	Simulated anneling	Encoding: Hexadecimal

	SLO-2	Algorithm	Algorithm, Applications	Application procedure Simp		Simple genetic algorithm	Encoding: Permutation
• •	SLO-1	HEBB net: Architecture	Hopfield network:Architecture, Algorithm	ART Fundamental	s	Simple genetic algorithm	Encoding: Value and Tree
5-0	SLO-2	HEBB net: Algorithm	Tutorials	ART: Basic archite	ecture	Comparison of Genetic algorithm with other optimization techniques	ECG signal classification using neural network
S-7	SLO-1	Perceptron: Architecture	Hopfield -travelling salesmanproblem	Learning in ART		Genetic algorithm at work simulation by hands	ECG signal classification using neural network
	SLO-2	Perceptron: Algorithm	Boltzman machine	Visualization in U	matrix	Genetic algorithm at work simulation by hands	ECG signal classification using neural network
• •	SLO-1	Delta rule	Issue in network design	Basics of SVM		Data structures	EMG pattern recognition
5-8	SLO-2	Tutorial	Radial Basis function	Basics of SVM		Data structures	EMG pattern recognition
• •	SLO-1	Tutorial	Matlab programing	Tutorial		Application of Genetic algorithm	Breast cancer detection
5-9	SLO-2	Tutorial	Matlab programing	Tutorial		Advantages and limitation of Genetic algorithm	Breast cancer detection
Learni	ng	1. LaureneFausett, "Fundamentals of Neural N Education India, 3rd edition, 2008. 2. Mohamad H. Hassoun, "Fundamentals of Ar 1stedition, 1995	etworks: Architectures, Algorithms, and Applicati tificial Neural Network", Cambridge, The MIT Pre	ions", Pearson ess,	5.James A Freeman and Dav 6.Robert J Schalkoff, "Artificia 7.David Goldberg, Genetic Al	id M.Skapra, "Neural Network", Addison – Wesl I Neural Networks", McGraw Hill, Third edition, i gorithms in Search, Optimization and Machine L	ay, India, Third edition, 2008 2011. earning", Pearson Education, Fourth edition,

Resources

B. Yegnanarayana, "Artificial Neural Networks", Prentice Hall of India, 3rd edition,2006.
 N. Sivanandam, S. N Deepa, "Introduction to Neural Networks Using Matlab 6.0", Tata McGrawHill, 2006.

Learning Assessm	nent										
	Ploom's			Con	tinuous Learning Ass	essment (50% weight	age)			Einal Examination	(50%) weighten
	Diouin's	CLA –	CLA – 1 (10%)		CLA – 2 (15%)		3 (15%)	CLA – 4	l (10%)#		r (50 % weightage)
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Loval 1	Remember	10.0/		10.0/		10.0/		20.0/		200/	
Level I	Understand	40 %	-	40 %	-	40 %	-	30 %	-	30%	-
Loval 2	Apply	10 %		10 %		10 %		10 %		10%	
Level Z	Analyze	40 70	-	40 /0	-	40 /0	-	40 70	-	4070	-
Loval 3	Evaluate	20.%		20 %		20 %		30 %		30%	
Level 5	Create	20 70	-	20 /0	-	20 /0	-	50 78	-	5070	-
	Total	10	0 %	100	0 %	100) %	10	0 %	10	0 %

2009.

8. Melanie Mitchell, An Introduction to Genetic Algorithms" Prentice Hall of India, New Delhi, First edition, 1998

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldive	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1. Dr. Rajalakshmi S, SRMIST

Course	18		Course	W			Co	ourse		F	Professional Elective						L	Т	Ρ	С					
Code	101	DIVIL-4001	Name	vv			Cat	egory		L				FIO	633101		CIVE					3	0	0	3
Pre-requ Cours	uisite ses	rinciples of Co	mmunication		Co-requisite Courses	Nil		Pro C	gress ourse	ive s	Nil														
Course Of	fering Dep	artment	Biomedia	cal Engineering		Data Book / Codes/Standards		Nil																	
Course Le	arning Rat	ionale (CLR):	The purpo wearable	ose of the learning system and its ap	this course is to p pplication in health	rovide an overview of the technical background care using mobile technology	l of	Le	earnin	ng Program Learning Outcomes (PLO)															
CLR-1 :	Comprehe	end technical in	nformation and o	challenges in WBA	4 <i>N.</i>			1	2	3		1 2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Describe t	he hardware re	equirements of	BAN																					
CLR-3 :	Review the	e wearable ser	nsors and stand	lards for BAN										ч			ility					1			
CLR-4 :	Describe t	he mobile devi	ices that is avai	lable for health ca	re			(mool	y (%)	t (%)		age	ent	esear			ainab		/ork		ce	1			
CLR-5 :	Summariz	e the possible	and latest appli	ications of mobile	healthcare			IB) BL	cienc	nem		ia io	lopm	lı, Re	sage	Ire	Sust		am V	~	Finan	ing			
CLR-6 :	Learn abo	ut context-awa	re health care a	applications				hinkir	Profi	Attair	:	Analys	Deve	Desiç	i) loo	Cultu	ent &		& Te	catior	gt. &	Lear			
								l of T	ected	ected			gn &	ysis, I	ern To	ety &	lonm	ş	idual	muni	ect M	-ong	Ţ	- 2	с Г
Course Le	arning Out	tcomes (CLO)	: At the en	d of this course, le	earns will be able	to :		Leve	Expe	Expe		Engi Pmb	Desi	Anal	Mod	Soci	Envi	Ethic	Indiv	Com	Proje	Life I	PSO	PSO	PSO
CLO-1 :	List out the	e BAN challeng	ges					1	80%	75%		L										1			
CLO-2 :	Identify the	e hardware neo	cessary for BAN	V				1	80%	75%		L										⊢—			
CLO-3 :	List and de	escribe the var	ious wearable s	sensors				1,2	80%	75%		L										1	L		
CLO-4 :	Appreciate	e the mobile de	evices available	for healthcare				1.2	80%	75%		L										1			
CLO-5 :	List the lat	est application	s and research	opportunities with	n mobile healthcar	e.		2	80%	75%												ı T		L]
CLO-6 :	Think abou	ut context-awa	re health care s	solutions				3	80%	75%															М

Durat	on (hour)	Basics of BAN	Hardware requirement for BAN	Wireless communication	Application of WBAN	WBAN application in healthcare
Durau	on (nour)	9	9	9	9	9
6.4	SLO-1	BAN-Definition	Processor in BAN	RF communication	Sensors for wearable system	Mobile health technologies
9-1	SLO-2	Terminologies used with BAN	Low Power MCUs	RF communication in and around the body	Wearable system design for specific applications	Mobile nutrition tracking
6.2	SLO-1	Technical Challenges	Mobile Computing MCU	Antennal Design	Wearable system for ECG monitoring,	Accessing existing virtual electronic patient record
3-2	SLO-2	Sensor design concepts	Integrated processor	Antenna testing	Wearable system for EEG monitoring,	Mobile personal health records,
S-3	SLO-1	Types of sensors	Radio transceiver along with the processor	Propagation issues	Wearable system for Gait analysis	Monitoring hospital patients,
3-3	SLO-2	Biocompatibility issues	Integrated processor with Memory	Base Station considerations	Evaluation of general performance	Sensing vital signs
64	SLO-1	Energy Requirements	Antenna for BAN	Network topology	Evaluation of night time performance	Transmission using wireless networks
3-4	SLO-2	Energy supply	Antenna Requirements	Stand – Alone BAN	Evaluation parameters	Continuous monitoring
S-5	SLO-1	Nodes, number of node	Antenna Considerations	Wireless personal Area Network	Latest health monitoring methods	Patient Monitoring and wearable devices

	SLO-2	Optimal node placement in BAN	Types of antenna	Wireless personal Area Network Technologies	Smart phone based health care monitoring system	Patient Monitoring in Diverse Environments
86	SLO-1	System security	Wire antenna	IEEE 802.15.1	Phone based fall risk prediction	A framework for Capturing Patient Consent in Pervasive Healthcare Applications
3-0	SLO-2	System Reliability	Ceramic antenna	IEEE P802.15.13	Emergency alerts	M-health application
6.7	SLO-1	BAN Standards	External antenna	IEEE 702.15.14	RFID based personal mobile medical assistance	Context aware sensing
3-1	SLO-2	BAN with other standards	Sensor Interface	Zigbee	Other similar technologies	Technology Enablers for context-Aware healthcare Applications
۰ ه	SLO-1	BAN Architecture	Considerations on the interface	BAN and WBAN technologies	Infusing image processing capabilities	8 channel ECG using Ultra wide band WBAN
3-0	SLO-2	BAN and other technologies	Power sources- Batteries	Limitations in use	Secure medical sensor network with HIP	Pulse generator using Ultra wide band WBAN
80	SLO-1	BAN and Healthcare	Fuel cells for sensor nodes.	Coexistence issues with BAN	Diagnostic applications	Multichannel neural recording system
3-9	SLO-2	Medical Applications of BAN	Other novel power sources	Other practical considerations	Therapeutic applications	Electronic pills

- 1. Annalisa Bonfiglio, Danilo De Rossi, "Wearable Monitoring Systems", Springer, 2011.
- 2. Philip Olla, Josep Tan, "Mobile Health solutions for Biomedical applications", Medical Information science reference, Hershey New York, IGI Global 2009. Zhang, Yuan-Ting, Wearable Medical Sensors and systems, Sringers, 2013.
 Guang-Zhogn Yang(ED), " Body Sensor Networks", Springers, 2013

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- 5. Mehmet R. Yuce Jamil Y.Khan, "Wireless Body Area Networks Technology, Implementation and
- applications", Pan Standford Pte. Ltd., Singapore, 2012 Konstantina, James C. Lin, Dimitrios, Maria Teresa, "Wireless mobile communication and healthcare", 6. Secon International ICST conference, Mobihealth 2011, Springers 2011.
- 7. Ullah, Sana, Et at, " A review of wireless body area networks for medical applications", arXiv: 1001.083, 2010
- 8. Patel, Shyamal, Et al, "A review of wearable sensors and systems with application in rehabilitation", Neuroeng Rehabil 9.12, 2012, 1-17.

Learning Asse	essment										
				Cor	ntinuous Learning Ass	essment (50% weight	tage)			Final Examination	n (E0% weightene)
	Bloom's Level of Thinking	CLA –	1 (10%)	CLA – 2 (15%)		CLA –	3 (15%)	CLA – 4	(10%)#		n (50 % weightage)
	Lovor of Trimking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Loval 1	Remember	10.9/		20.9/		20.9/		20.0/		200/	
Level	Understand	40 %	-	50 %	-	30 %	-	30 %	-	30%	-
Lovel 2	Apply	10 %		10 %		10 %		10 %		10%	
	Analyze	40 78	-	40 78	-	40 78	-	40 70	-	4078	-
Lovel 3	Evaluate	20 %		30 %		30 %		30 %		30%	
Level J	Create	20 78	-	50 78	-	50 78	-	50 78	-	5078	-
	Total	10	0 %	10	0 %	10	0 %	100) %	10	0 %
# CLA 4 and	he frame and complianting a	ftheese Assistants	Cominana Tash Tall	a Mini Dusianta Car	a Chudian Calf Chudu	MOOCA Cartification	na Canf Danasata				

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldive	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1. Dr. Varshinin Karthik SRMIST
		2.Mrs. Laskhmi Prabha

Course Code	18BME466T	Course Name	ARTIFICIAL INTELLIO	GENCE IN HEALTH CARE	E IN HEALTH CARE Course Category			L 3	Т 0	P 0	С 3
Pre-requisit Courses	te	Nil	Co-requisite Courses	Nil	Progres	ssive ses	Nil				
Course Offering	J Department	Bion	nedical Engineering	Data Book / Codes/Standards			Nil				

Course Lea	rning Rationale (CLR): The purpose of learning this course is to:		Learni	ng					Pr	rogram	۱ Learn	ing O	utcome	es (PLC))				
CLR-1 :	Understand the basics of Artificial Intelligence and its principles	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Learn the algorithm of various search techniques		2	Ħ											эс				
CLR-3 :	Become familiar with knowledge representation	-	enc	ner		s		<u>_</u>	age	Ð			ε		inar	bu			
CLR-4 :	Explore the techniques of machine learning applicable for healthcare	kinç	fici	ainr		lysi		ign	Us:	ltur	∞ .		ea	uo	Ϋ́Ε	ımi			
CLR-5 :	Understand the use of machine learning in healthcare applications	hin	Pc	Atta	p 2 0	Ina	ent	Des	0	Cu	ent ility		8 1	cati	gt. 8	Lea			
CLR-6 :	Understand the role of artificial intelligence in healthcare	J d T	ted	fed	eri	μ	% ud	is, rch	Ĕ	y &	nme nab		la	iun	t Mę	ng	-	2	3
) ec	Dec.	gine	ble	vel Sign	alys sea	der	ciet	/iro stai	<u>ics</u>	iş F	шш	jec	۶Lo	ò	ò	ò
Course Lea	rning Outcomes (CLO): At the end of this course, learners will be able to:	[Bid	EX 8	EX (%)	ч	Pro	D ei	An: Re:	Mo	Soc	Sus	Шţ	Pud Wo	Col	Pro	Life	PS	PS	PS
CLO-1 :	Demonstrate the basic principles of AI towards problem solving	1, 2	80%	70%	М	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-2 :	Explain the various search techniques in problem solving	2	80%	70%	М	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-3 :	Describe the techniques in knowledge representation	2	80%	70%	-	-	М		М	•	-	-	-	-	-	-	М		L
CLO-4 :	Explain the role of machine learning in healthcare applications	3	80%	70%	-	-			М	-	-	-	-	-	-	-	-	-	-
CLO-5 :	Demonstrate the use of machine learning in healthcare applications	3	80%	70%	М	-	-	-	-	-	-	-	-	-	-	-	М		L
CLO-6 :	Use the AI algorithms for various healthcare applications to solve problems	3	80%	70%	М	-	-	-	-	-	-	-	-	-	-	-	-	-	-

		Principles of Artificial Intelligence	Search Techniques	Knowledge Representation	Machine learning in Healthcare	Machine learning – applications in healthcare
Duratio	n (hour)	9	9	9	9	9
S-1	SLO-1	Al-introduction and definition	Informed search methods	First order logic-syntax and semantics	Data Preparation, Feature Cleaning	Healthcare Survey Dataset with Unsupervised Learning
5-1	SLO-2	Turing Test approach	Best first search-Greedy search	Symbols, terms, sentences	Feature Engineering, Feature Transformation	Feature selection using the Particle swam optimization
6.2	SLO-1	Intelligent agents	A* search-behavior	Quantifiers, equality	Feature Extraction, Feature Selection	Disease Detection System (DDS) Using Machine Learning Technique
3-2	SLO-2	Structure of intelligent agents, Agent programs, example	Complexity of A* search	Extensions	Machine learning models	System Implementation and Disease Detection Methodology
• •	SLO-1	Simple reflex agents	Heuristic functions	notational variations	Machine learning categories	Architecture of DDS
8-3	SLO-2	Goal based agents	Heuristics for constraint satisfaction problem	Higher order logic, A-expression	Machine Learning Challenges	Use Case Diagram of DDS
S-4	SLO-1	Utility based agents	Iterative deepening A* search (IDA*)	Using first order logic-kinship domain	Machine Learning Tools	Accuracy Comparison of DDS with Previous Works
	SLO-2	Environment programs	Simplified Memory Bounded A* search	Axioms, definitions and theorems	Patient centric Machine learning model	Simulation for Result
S-5	SLO-1	Problem solving-problem solving agents	Hill-climbing search	Domain of sets	Pre-processing of data, Results and discussions	Deep learning solutions for skin cancer detection
3-3	SLO-2	Formulating problems,	Simulated annealing	special notations for sets, lists and arithmetic	Machine Learning Models to Classify Healthcare Data	Convolution neural network, methods, dataset
6.6	SLO-1	Well defined problems and solutions	Applications in constraint satisfaction problems	Logical agents for Wumpus world	Exploratory Data Analysis	Data augmentation,
3-0	SLO-2	Example-Toy problems, travelling salesman problem	Knowledge and reasoning	Simple reflex agent-limitations	Machine learning techniques-supervised and unsupervised approaches	Network architecture, performance metrics
S-7	SLO-1	Searching solutions	Knowledge based agent	Representing change in the world-situation calculus	Natural language Processing	Security of Healthcare Systems with Smart Health Records Using Cloud Technology
	SLO-2	Data structures for search trees	Representation reasoning and logic	Frame problem and its relatives	Types of Unsupervised Learning	Cloud Computing in Healthcare

6 0	SLO-1	Search Strategies-breadth first, Uniform cost search	Semantics, Inference	Deducing hidden properties if the world	Clustering	Cloud Service Models						
5-0	SLO-2	Depth first search	Propositional logic	Preferences among actions, toward a global agent	Clustering Algorithms	Deployment Models in Cloud Computing						
	SLO-1	Iterative search	Syntax, semantics	Knowledge engineering - introduction	K-Means Algorithm	Cloud Computing Security						
S-9	SLO-2	Bidirectional search	Validity and inference	Knowledge engineering and programing	Density Based Clustering	Healthcare Data Security in the Cloud, sample algorithm						
	1 Furgere Charniak "Introduction to Artificial Intelligence" Pearson Education India 1985 3 Bernard Nordlinger Cádric Villani, Daniela Rus, "Healthcare and Artificial Intelligence" Springer Nature 2020											

Learning	1. Eugene Charniak, "Introduction to Artificial Intelligence", Pearson Education India, 1985	3. Bernard Nordlinger, Cedric Villani, Daniela Rus, "Healthcare and Artificial Intelligence", Springer Nature, 2020
Learning	2. Stuart Jonathan Russell, Peter Norvig, Ernest Davis, "Artificial Intelligence: A Modern Approach,	4. Vishal Jain, Jyotir Moy Chatterjee "Machine Learning with Health Care Perspective: Machine Learning and Healthcare Volume 13 of
Resources	Prentice Hall series in artificial intelligence, Prentice Hall, 2010	Learning and Analytics in Intelligent Systems", Springer Nature, 2020

Learning Ass	Learning Assessment											
	Diagm's			Con	tinuous Learning Ass	essment (50% weight	tage)			Final Examination	(EO9/ woightage)	
	DIOUIIIS	CLA –	1 (10%)	CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4	4 (10%)#		r (50% weightage)	
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	
Lovel 1	Remember	10 %		10 %		10 %		30 %		30%		
Level I	Understand	70 /0		40 78	-	40 78	-	50 78	-	5070	-	
	Apply	40 %		40 %		40 %		40 %		40%	_	
Leverz	Analyze	40 70	-	40 %	-	40 %	-	40 %	-	4070	-	
Lovel 3	Evaluate	20.%		20.%		20.04		30 %		30%		
Level 5	Create	20 70	-	20 70	-	20 70	-	50 78	-	5070	-	
	Total	10	0 %	10	0 %	10	0 %	10	0 %	10) %	

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldive	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1. Mrs.Bhargavi Haripriya, SRMIST

Course Code	18BME467T	Course Name	В	IO INSPIRED ROBOTICS	C Ca	ourse tegory	, E	Ē	Professional Elective					_	L 3	T 0	P 0	C 3				
Pre-req Cours Course Of	uisite ses fering Department	Nil Data Book / Codes/Standards	Pro C Nil	gress ourse	ive s	lil																
Course Learning Rationale (CLR): The purpose of learning this course is to: Learning Program Learning Outcomes (PLO)																						
CLR-1 :	Understand the basic ab	out bio inspire	d robots		1	2	3		1 2	2 3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 : CLR-3 : CLR-4 : CLR-5 : CLR-6 :	Get an idea about the m Acquire an idea about th Get an idea about assist Get an idea about the sta Get an overall idea abou systems	usculoskeletal e basic of pos ive and rehabi ability analysis t the importan	movements tural balances litation robotics ce of Develop skills related to the de	esign, construction and testing of advanced robotic	f Thinking (Bloom)	ed Proficiency (%)	ed Attainment (%)		ering Knowledge	n Analysis & Development	s, Design, Research	Tool Usage	& Culture	ment & Sustainability		ial & Team Work	inication	Mgt. & Finance	ng Learning			3
Course Le	arning Outcomes (CLO)	: At the e	nd of this course, learners will be ab	ole to:	Level of	Expecte	Expecte		Engine(Problen Design	Analysi	Modern	Society	Environ	Ethics	Individu	Commu	Project	Life Lor	PSO - 1	PSO-2	PSO-
CLO-1 :	Apply the common troub components	leshooting pro	cedures in Electronic Equipment and	d Outline the testing procedures of active and passive	1, 2	80	70		М		-	-	-	-	-	-	-	-	-	-	-	-
CLO-2 :	Analyze the faults in ana	log circuits an	d digital ICs		1, 2	80	70		M		-	-	-	-	-	-	-	-	-	М	-	-
CLO-3 :	Identify the problems in a	common biome	edical equipment in hospitals when i	t is not working and provide a suitable solution	2	80	70		- 1	Λ -	-	-	-	-	-	-	-	-	-	М		-
CLO-4 :	0-4 : Outline the importance of medical device classification based on the application and ISO standards					80	70		-	- H	-	-	-	-	-	-	-	-	М	-	М	-
CLO-5 :	CLO-5 : Describe the Indian medical device regulatory system				1	80	70				-	-	-	-	-	-	-	-	М	-	-	-
CLO-6 :	CLO-6: Outline the job opportunities in regulatory affairs in India					80	70		-	- -	-	-	-	-	-	-	-	-	L	-	-	-

Durati	on (hour)	Introduction to Bio Inspired Robots	A review of computational Musculoskeletal Analysis of Human Lower Extremities	Personalized Modeling for Home –Based Postural Balance Rehabilitation	Non Invasive brain machine interfaces for assistive and rehabilitation robotics	Psychological modeling of humans by assistive robots
		9		9	9	9
S 1	SLO-1	Introduction to Bio-inspired Robotics	Introduction to Musculoskeletal Analysis	Introduction	Introduction to brain machine interfaces	Introduction
3-1	SLO-2	Introduction to Bio-inspired Robotics	Introduction to Musculoskeletal Analysis	Introduction	Introduction to brain machine interfaces	Introduction
6.2	SLO-1	Principles of Biomechanics	Human walking Gait cycle	Home – Based postural balance rehabilitation	BMI for assistive robotics	Dimensions of Human characterization
5-2	SLO-2	Basic Features	Human walking Gait cycle	Home – Based postural balance rehabilitation	BMI for assistive robotics	Dimensions of Human characterization
S-3	SLO-1	What is a biologically Inspired Robotic System, and its advantages and disadvantages	Biomechanics of Normal human walking	Body segment parameters	BMI for rehabilitation robotics	Constructing behavioral models for HRI
	SLO-2	its advantages and disadvantages	Biomechanics of Normal human walking	Body segment parameters	BMI for rehabilitation robotics	Constructing behavioral models for HRI
6.4	SLO-1	Mobility systems Requirements	Quantitative Human Walking Models	Estimating center of mass position for human subjects	Kalman Filter Implementation	Economic decision-making models
S-4 SLO-2		Mobility systems Requirements	Quantitative Human Walking Models	Estimating center of mass position for human subjects	Kalman Filter Implementation	Economic decision-making models

	SLO-1	legs	Computational Musculoskeletal Analysis	Various Methods for balance rehabilitation	Challenges in exoskeleton design	Interfering psychological models
S-5	SLO-2	swimming	Computational Musculoskeletal Analysis Interaction with articulated systems	Various Methods for balance rehabilitation	Challenges in exoskeleton design	Interfering psychological models
	SLO-1	flying system	EMG motion classification	Dynamic Model	Biomechanical modeling	Haptic stability
5-6	SLO-2	Sensors	EMG motion classification	Dynamic Model	Biomechanical modeling	Haptic stability
6.7	SLO-1	Characteristics of Sensors	Task modeling for human interfaces	Dynamic Optimization	Development of HRI model	Human operator Modeling
5-1	SLO-2	tactile,	Task modeling for human interfaces	Dynamic Optimization	Development of HRI model	Human operator Modeling
.	SLO-1	vision	An EMG –controlled Human Robot Interface using Task modelling	Body motion sensing	Design examples	Haptic assist control
5-8	SLO-2	electronic nose	An EMG –controlled Human Robot Interface using Task modelling	Body motion sensing	Design examples	Haptic assist control
e 0	SLO-1	Evolution of Bio Inspired Robot	Modeling of joint stiffness	Strain-Sensitive conductive polymers	Stability analysis	System validation and experimental evaluation
3-9	SLO-2	Evolution of Bio Inspired Robot	Modeling of joint stiffness	Strain-Sensitive conductive polymers	Stability analysis	System validation and experimental evaluation

	1. Biologically Inspired Robotics 1st Edition by Yunhui Liu (Editor), Dong Sun (Editor)
Learning	2 Bio-Inspired Artificial Intelligence: Theories, Methods, and Technologies (Intelligent Robotics and Autonomous
Resources	Agents series) by <u>Dario Floreano</u>

Learning Assessment												
	Pleam's			Con	tinuous Learning Ass	essment (50% weight	age)			Final Examination	(E00/ weightage)	
	DIUUIIIS	CLA –	1 (10%)	CLA – 2 (15%)		CLA – 3	3 (15%)	CLA – 4	(10%)#		i (50% weightage)	
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	
Loval 1	Remember	40.0/		40.0/		10.0/		20.0/		200/		
Level	Understand	40 %	-	40 %	-	40 /0	-	30 %	-	30%	-	
Lovel 2	Apply	40 %	10 %		40 %	-	10.0/	_	10.0/		100/	
Level Z	Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-	
Lovel 3	Evaluate	20 %		20 %		20 %		30 %		30%		
Level 5 Cre	Create	20 %	-	20 %	-	20 %	-	30 %	-	30%	-	
	Total	100 %		100 %		100) %	100) %	100 %		

Course Designers							
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts					
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldive	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1. G.Anitha, SRMIST					

Course 18BME468T	Course Name	COMPUTATIONAL TOOLS IN BIOE	UTATIONAL TOOLS IN BIOENGINEERING AND BIOMEDICINE			Professional Elective	L 3	Т 0	P 0	C 3
Pre-requisite Courses Course Offering Department	Biomedical Engin	Co-requisite Courses Nil	Data Book / Codes/Standards	Progressive Courses Nil	Nil					

Course Learning Rationale (CLR): The purpose of learning this course is to:			ng					Prog	ram L	_earni	ing Ou	utcom	es (P	LO)				
CLR-1 : Understand the basic concepts of computational tools in bioengineering and biomedicinie	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14 1	15
CLR-2: Get an idea about the Concept of aortic dissection		/				ent								се				
CLR-3 : Acquire an idea about the Mechanistic approach to analysis antioxidant action		nc)	lent			Ĕ		ge				_		Jan	b			
CLR-4: Get an idea about the Radical adduct formation (RAF) mechanism	ing	icie	inn		/sis	elo de	gn,	Jsa	nre	~×		ean	E	Ē	Lin			
CLR-5: Acquire an idea about the coupling algorithms on cochlear mechanics	ink	p	∖tta	D	Jal)eV	lesi	0	Ħ	it 8	ŀ	⊢ ~×	atic	t &	eal			
CLR-6 : Get an overall idea about the advanced computational approach	٦ É.	D E	∕ p	erin dae	۲	~	с С	P	<u>م</u>	abil	-	a	nic	Mg	ВГ		~ (e
		ecte	ecte	wle	len	ign	ean	ern	iety	iron tain	8 I	k g	Ĕ	ect	Lo	-		
Course Learning Outcomes (CLO): At the end of this course, learners will be able to:	Leve	a A S	% Exp	Eng Kno	Prot	Des	Ana Res	Mod	Soc	Sus	Ē	Wor Wor	S	Proj	Life	R	DSG	PSC
CLO-1 : Understand the need for computational tools in the field of bioengineering and biomedicine	1, 2	80	70	Н	-	-	-	-	-	-	-	-	-	-	М	-		-
CLO-2: Have a thorough understanding of basic equations of fluid flow and solid motion	1, 2	80	70	Н	-	-	-	-	Н	-	-	-	-	-	-	L		-
CLO-3 : Understand the basics of antiradical mechanisms in the presence of different free radicals	2	80	70	-	L	-	-	-	Н	-	-	-	-	-	-	L	l	L
CLO-4 : Identify the importance of radical adduct formation mechanism	1	80	70	Н	-		-	-	Н	-	-	-	-	-	-	-	Μ	-
CLO-5: Analyze the knowledge on the model of cochlea including feedforward and feedbackward forces	1	80	70	-	-	-	-	-	Н	-	-	-	-	-	-	-		- 7
CLO-6 : Extend the basics of functional Spaces and functional inequalities	1,2	80	70	Н	-	-	-	-	-	-	-	-	-	-	М	-	- ·	-

Duration (hour)		Need for computational tools	Computational approach in aortic dissection	Computational approach in antioxidative mechanisms	Computational approach in cochlear mechanics	Advanced computational approach
		9	9	9	9	9
SLO-1		Elements of computational tools	Diagnostic techniques of acute aortic dissection	Prevention of oxidative stress	Cochlear mechanics	Functional Spaces and Functional Inequalities
5-1	SLO-2	Elements of computational tools	Diagnostic techniques of acute aortic dissection	Prevention of oxidative stress	Concepts of modeling	Metric Spaces
6.2	SLO-1	Elements of mathematical modeling	Treatment of acute aortic dissection	Characteristics of good antioxidants	Concepts of modeling	Complete Metric Spaces
3-2	SLO-2	Elements of mathematical modeling	Treatment of acute aortic dissection	Characteristics of good antioxidants	Solid model	Normed Spaces
6.2	SLO-1	Elements of physics	Basic equations of fluid flow	The proposed reaction mechanisms	Solid model	Banach Spaces
3-3	SLO-2	The rational continuum mechanics approach to matter in motion	Basic equations of fluid flow	The proposed reaction mechanisms	Fluid model	Banach Spaces
S /	SLO-1	Balance laws in integral form	Basic equations of solid motion	The proposed reaction mechanisms	Fluid model	Hilbert Spaces
S-4 SLO-2		Balance laws in integral form	Basic equations of solid motion	Mechanistic approach	Loose coupling algorithm	Hilbert Spaces
<u>с</u> г	SLO-1	Balance laws in local form	Basic equations of solid motion	Mechanistic approach	Loose coupling algorithm	The Nonlinear Differential Model System
S-5	SLO-2	Balance laws in local form	Solid fluid interaction	Thermodynamical parameters for quercetin and gallic acid	Strong coupling algorithm	Time Semidiscretization

56	SLO-1	Continuum approach for multicomponent mixtures	Solid fluid interaction Thermodynamical parameters for quercetin and gallic acid Strong coupling algorithm		Strong coupling algorithm	Time Semidiscretization
3-0	SLO-2	Continuum approach for multicomponent mixtures	Concept of aortic dissection	Thermodynamical parameters for quercetin and gallic acid	Need for finite element modeling of cochlea	Time Semidiscretization
	SI 0-1	Continuum approach for multicomponent	Concept of aortic dissection	Antiradical mechanisms in the presence of	Basic criteria for finite element modeling of	Block Nonlinear Jacobi and Gauss–Seidel
C 7	020 .	mixtures		different free radicals	cochlea	Iterations
3-1	SLO-2	Constitutive relations for fluids	Need for 3D reconstruction	Antiradical mechanisms in the presence of different free radicals	Concept of finite element modeling of cochlea	Block Nonlinear Jacobi and Gauss–Seidel Iterations
<u> </u>	SLO-1	Constitutive relations for solids	itutive relations for solids Need for 3D reconstruction Mechanistic approach to analyze antioxidar. action		Finite element models of cochlea	Block Nonlinear Jacobi and Gauss–Seidel Iterations
3-0	SLO-2	Constitutive relations for solids	Need for 3D reconstruction	Mechanistic approach to analyze antioxidant action	Finite element models of cochlea	Application of Functional Iterations to Biological Models
	SI 0-1	Constitutive relations for multicomponent	Need for geometric 3D modeling	Radical adduct formation (RAF) mechanism	Model of cochlea including feedforward and	Application of Functional Iterations to
0.0	OLO I	mixtures			feedbackward forces	Biological Models
5-9	0100	Constitutive relations for electromagnetism	Need for geometric 3D modeling	Radical adduct formation (RAF) mechanism	Model of cochlea including feedforward and	Application of Functional Iterations to
	3LU-2	and electrodynamics			feedbackward forces	Biological Models

	1.Nenad Filipovic, "Computational Modeling in Bioengineering and Bioinformatics", Academic Press, 1st Edition,	4.Andreas Öchsner, Holm Altenbach, "Applications of Computational Tools in Biosciences and Medical Engineering".
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	2016.	

Learning Assessme	earning Assessment													
	Diagm's		Continuous Learning Assessment (50% weightage)											
	DIUUIIIS	CLA – 1	CLA – 1 (10%)		CLA – 2 (15%)		3 (15%)	CLA – 4	(10%)#	Final Examination (50% weightage)				
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice			
Level 1	Remember	10.0/		10.0/		40.0/		20.0/		200/				
Level I	Understand	40 %	-	40 %	-	40 %	-	30 %	-	30%	-			
Lovel 2	Apply	10.0/	_	10.9/	-	10.0/		10.0/		100/				
Level Z	Analyze	40 %	-	40 %		40 %	-	40 %	-	40%	-			
Level 2	Evaluate	20.0/		20.0/		20.0/		20.0/		200/				
Level 5	Create 20 % - 20 % -		-	20 %	-	30 %	-	30%	-					
	Total	100) %	10	0 %	100	0 %	100) %	10) %			

Course Designers								
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts						
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldive	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1. Mr.P. Muthu, SRMIST						

Course Code	18BME469T	Course Name	NEURO REHABILITATION AND HUMAN MACHINE INTERFACE			КСЕ	Co Cat	ourse egory	1	E		Pi	rofessio	onal El	lective	9				L 3	T 0	P 0	C 3	
Pre-requisite Courses Basic Electronic devices and circuits Co-requisite Courses Nil Courses Offering Department Biomedical Engineering Data Book / Codes/Standards						larde	Pro C	gressi ourse:	ive s	Nil														
Course Course Greening Department Biomedical Engineering Data Book / Codes/standards Course Learning Rationale (CLR): The purpose of learning this course is to:						L	earnin	g				Prog	jram L	_earni	ing Ou	itcom	es (Pl	LO)						
CLR-1 :	Explain the basic growth mechanism	responses of	neurons with cellu	ular and molecular				1	2	3	1	2	3 4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 : CLR-3 : CLR-4 : CLR-5 : CLR-6 :	CLR-2: Analyze the plasticity of cerebral motor function CLR-3: Summarize the role of inflammatory response in central nervous system CLR-4: Illustrate the future perspective of human machine interface (HMI) CLR-5: Explain the motor recovery and compensation in neurorenabilitation CLR-6: Understanding the usage of Human machine Interface in translational research					of Thinking (Bloom)	ted Proficiency (%)	ted Attainment (%)	eering Knowledge	im Analysis	ו & Development sis, Design, rrch	n Tool Usage	y & Culture	nment & nabilitv		lual & Team Work	unication	t Mgt. & Finance	ong Learning	-	2	- 3		
Course Lea	rning Outcomes (CLO	: At the e	nd of this course,	learners will be ab	le to:			Level	Expec	Expec	Engin	Proble	Desigi Analys Resea	Moder	Societ	Enviro Sustai	Ethics	Individ	Comm	Projec	Life Lo	- OSA	- OSA	- OSA
CLO-1 :	Understanding cellular and molecular mechanisms of neural plasticity					1, 2	80	70	M	M		-	-	-	-	-	-	-	-	-	-	-		
CLO-2 :	: Get an idea of Functional Plasticity in the Central Nervous System					1, 2	80	70	М	М		-	-	-	-	-	-	-	-	М	-	-		
CLO-3 :	3: Identify the Regeneration in the Injured Nervous System						2	80	70	Н	-	-	-	-	-	-	-	-	-	-	М		-	
CLO-4 :	Illustrate the future perspective of human machine interface (HMI)							1	80	70	Н	-		-	-	-	-	-	-	-	Н	-	М	-
CLO-5 :	Application of Human machine interface in translational research						1	80	70	Н	-		-	-	-	-	-	-	-	М	М	-	-	
CLO-6 :	Understanding the usage and design development of HMI for research						1,2	80	70	Н	-	MM	-	-	-	-	-	-	-	Н	Н	-	-	

Duration (hour)		Neural Plasticity: Cellular and Molecular Mechanisms	Functional Plasticity in the Central Nervous System	Determination of Regeneration in the Injured Nervous System	Ambient Intelligence and Ubiquitous Computing Scenario	Translational Research: Application in Human Machine Interface
		9	9	9	9	9
C 1	SLO-1	Learning and memory: basic principles and model systems	Plasticity of mature and developing somatosensory systems	Non-mammalian models of nerve regeneration	The advanced human machine interface (HMI) framework	Application uses in robotics
3-1	SLO-2	Learning and memory: basic principles and model systems	Plasticity of mature and developing somatosensory systems	Non-mammalian models of nerve regeneration	The advanced human machine interface (HMI) framework	Application uses in robotics
6.0	SLO-1	Cellular and molecular mechanisms of associative and nonassociative learning	Activity-dependent plasticity in the intact spinal cord	Myelin-associated axon growth inhibitors, Inhibitors of axonal regeneration	The advanced human machine interface (HMI) framework	Robotics and wearable technology for measurement
3-2	SLO-2	Cellular and molecular mechanisms of associative and nonassociative learning	Activity-dependent plasticity in the intact spinal cord	Myelin-associated axon growth inhibitors, Inhibitors of axonal regeneration	The advanced human machine interface (HMI) framework	Robotics and wearable technology for measurement
SLO-1		Degenerative changes and reactive growth responses of neurons following denervation and axotomy	Plasticity of cerebral motor functions: Implications for repair and rehabilitation	Role of the inflammatory response in central nervous system injury and regeneration	Human machine interface systems – structure, protocols,	Clinical application of robotics and technology in restoration of walking
S-3	SLO-2	Degenerative changes and reactive growth responses of neurons following denervation and axotomy	Plasticity of cerebral motor functions: Implications for repair and rehabilitation	Role of the inflammatory response in central nervous system injury and regeneration	Human machine interface systems – structure, protocols	Clinical application of robotics and technology in restoration of walking

S 4	SLO-1	Contemporary issue and theories of motor control learning.	Plasticity of cerebral motor functions: Implications for repair and rehabilitation	Role of the inflammatory response in central nervous system injury and regeneration	Human machine interface systems – applications	Clinical application of robotics and technology in children undergoing neurorehablitation
3-4	SLO-2	Contemporary issue and theories of motor control learning.	Plasticity of cerebral motor functions: Implications for repair and rehabilitation	Role of the inflammatory response in central nervous system injury and regeneration	Human machine interface systems – applications	Clinical application of robotics and technology in children undergoing neurorehablitation
S-5 -	SLO-1	Limbic system influence over motor control and learning	Plasticity in visual connection retinal ganglion cell axonal development and regeneration	Sensor-motor interaction and error augumentation	Human machine interface systems – applications	Clinical application of robotics and technology in children undergoing neurorehablitation
	SLO-2	Limbic system influence over motor control and learning	Plasticity in visual connection retinal ganglion cell axonal development and regeneration	Sensor-motor interaction and error augumentation	. The next-generation advanced HMI 2	Biomimetic design of neural prosthesis Brain responses to neural prosthesis
0.0	SLO-1	Learning of damaged brain/spinal cord neuroplasticity	Plasticity in auditory function cross model plasticity in visual system	Limbic system influence on motor control and learning	The next-generation advanced HMI 2	Biomimetic design of neural prosthesis Brain responses to neural prosthesis
5-0	SLO-2	Learning of damaged brain/spinal cord neuroplasticity	Plasticity in auditory function cross model plasticity in visual system	Limbic system influence on motor control and learning	The next-generation advanced HMI 2	Biomimetic design of neural prosthesis Brain responses to neural prosthesis
	SLO-1	Movement neuroscience foundation of neurorehabilitation	Plasticity in auditory function cross model plasticity in visual system	Normal and impaired cooperative hand movement role of neural coupling	A future perspective for next-generation HMI: fNIRS-EEG	Intracranial human machine interfaces for communication and control
5-7	SLO-2	Movement neuroscience foundation of neurorehabilitation	Plasticity in auditory function cross model plasticity in visual system	Normal and impaired cooperative hand movement role of neural coupling	A future perspective for next-generation HMI: fNIRS-EEG	Intracranial human machine interfaces for communication and control
S-8	SLO-1	Sensor-motor interaction and error Augumentation	Plasticity in auditory function	Physiological aspect of adaptation and adjustment during various phase of neurological Disablity	A future perspective for next-generation HMI: fNIRS-EEG	Intracranial human machine interfaces for communication and control
	SLO-2	Sensor-motor interaction and error Augumentation	Plasticity in auditory function	Physiological aspect of adaptation and adjustment during various phase of neurological Disablity	A future perspective for next-generation HMI: fNIRS-EEG	Understanding motor recovery and compensation in neurorehabilitation
S-9 -	SLO-1	Physiological aspect of adaptation and adjustment during various phase of neurological Disablity	Plasticity in auditory function	Multisystem neurorehablitation in rodents w ith spinal cord injury	Multi-Modal HMI.	Understanding motor recovery and compensation in neurorehabilitation
	SLO-2	Physiological aspect of adaptation and adjustment during various phase of neurological Disablity	Plasticity in auditory function	Multisystem neurorehablitation in rodents w ith spinal cord injury	Multi-Modal HMI.	Understanding motor recovery and compensation in neurorehabilitation

Learning Resources	 Michael E. Seizer, Stephanie Clarke, Lenardo G. Cohen. GertKwakkel, Robert H. Miller., "Textbook of Neural repair and rehabilitation", Volume 1-Neural repair and Plasticity", Cambridge university press, 2nd edition, 2014. Jose L Pons, Diego Torricelli, "Textbook of Neural repair and rehabilitation", Springer, 1stedition, 2014. Jarcy Ann Umphred, Rolando T. Lazaro, Margaret Roller, Gordon Burton ,Neurological Rehabilitation - E- Book, Elsvier mosby 2013. Panagiotis Artemiadi , Neuro-Robotics: From Brain Machine Interfaces to Rehabilitation Robotics springer publishing 2014. 	 Surjo R. Soekadar, NielsBirbaumer, Marc W. Slutzky, Leonardo G. Cohen., "Brain- machine interfaces in neurorehabilitation of stroke', Neurobiology of disease, 2015. F. Nijboer, "Technology transfer of brain-computer interfaces as assistive technology: Barriers and opportunities", Annals of physical and Rehabilitation Medicine, 2015. U. Chaudhary, N. Birbaumer, M.R.Curado., "Brain-machine interface (BMI) in paralysis", Annals of physical and rehabilitation medicine, 2015. D. Franks and J.H. Turner, "Handbook of Neurosociology", Springer, 1stedition, 2013. Jose, Leons, Diego Torricelli, Marta Pajaro., "Converging clinical and engineering research on
	4. Panagiotis Artemiadi , Neuro-Robotics: From Brain Machine Interfaces to Rehabilitation Robotics springer publishing 2014.	 D.D. Franks and J.H. Turner., "Handbook of Neurosociology", Springer, 1stedition, 2013. Jose L Pons, Diego Torricelli, Marta Pajaro., "Converging clinical and engineering research on second billion of the second se
	5. David J. Reinkensmeyer, Volker Diet, Neurorehabilitation Technology, springer publishing 2016.	neurorenabilitation", Springer, 1stedition, 2013.

Learning Assessment													
	Ploom's			C	ontinuous Learning Asse	essment (50% weight	age)			Einal Examination	(50% woightage)		
Loval	DIOUIIIS	CLA –	1 (10%)	CLA	– 2 (15%)	CLA – 3	3 (15%)	CLA – 4	(10%)#		(50% weightage)		
Lever	i or minking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice		

Lovel 1	Remember	10.0/		10.0/		10.0/		20.0/		200/	
Lever	Understand	40 %	-	40 %	-	40 %	-	30 %	-	30%	-
	Apply	10.0/		10.9/		10.9/		10.0/		100/	
Leverz	Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Loval 2	Evaluate	20.0/		20.0/		20.0/		20.0/		200/	
Levers	Create	20 %	-	20 %	-	20 %	-	30 %	-	30%	-
	Total	100 %	0	10	0 %	10	0 %	100	%	10	0 %

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldive	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	Mrs.P.Laskhmi Prabha

Course Code	18BME470T	Course Name		Assistive	and Augmenta	tive Technologies	C Ca	ourse ategor	e Y	Е	Professional Elective L T P 0 3 0 0 3 0 0 3							C 3						
Pre-requ Cours Course Off	visite Nil fering Department	Biomed	ical Engineering	Co-requisite Courses	Nil	Data Book / Codes/Standards	Pro C Nil	ogres Cours	sive es	Nil														
Course Learning Rationale (CLR): The purpose of learning this course is to: Learning Program Learning Outcomes (PLO) Image: Course Learning Rationale (CLR): The purpose of learning this course is to: Image: Course Learning Rationale (CLR): The purpose of learning this course is to:																								
CLR-1 :	Understand the fundame	entals of assist	ive technology too	ols in various disabi	ilities		1	2	3		1 2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 : CLR-3 : CLR-4 : CLR-5 : CLR-6 :	Use the universal princip Utilize the idea about the Study the assistive tech Study the assistive tech Get an overall idea abou	bles and human a low and high hology tools for hology tools for t the various a ht the e ht the e	n factors for Augn technology tools r deafness and he visual and dual s ssistive technolog nd of this course,	nentative and altern for various disabiliti paring impairments sensory impairmen gy tools for mobility, learners will be abl	ative communi es ts seating and d e to:	ication and assistive technology aily living	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)		Engineering Knowleage Drohem Analveis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO – 3
CLO-1 :	Apply the universal princ	ciples of assisti	ve technology too	ols for various disab	ilities		1, 2	80	70		Λ -	-	-	-	-	-	-	-	-	-	-	L-	L	М
CLO-2 :	Identify the basic princip	les and human	factors for perso	n with disabilities			1, 2	80	70		Λ -	-	-	-	-	-	-	-	-]	-	-	L	\square	-
CLO-3 :	Identify the utilization of	low and high te	echnology tools in	n various disability c	onditions		1,2	80	70		- N	-	-	-	-	-	-	-	-	-	-	L	L	-
CLO-4 :	Analyze the assistive tee	chnology tools	and its usage in h	nearing impairments	s persons		2,3	80	70		1 L	L	-	-	-	-	-	-	-	-	М	-	L	М
CLO-5 :	Analyze the assistive tee	chnology tools	and its usage in v	visual and sensory	impairments p	ersons	2,3	80	70		/ L	L	-	-	-	-	-	-	-	-	М	-	L	М
CLO-6 :	Identify the basic assisti	ve technology i	tools for activities	of daily living			2,3	80	70		- N	М	L	-	-	-	-	-	-	-	L	-	L	М

Durat	ion (hour)	Universal Principles and Human factors	Assistive Technology for Communication, Deafness and hearing impairments	Assistive Technology for Visual and Dual sensory impairments and daily living	Augmentative Technology for Prosthetic and Orthopedics	Technology for mobility, seating and
		9	9	9	9	9
S-1	SLO-1	Augmentative and alternative communication (AAC) and Assitive technology (AT) software	Hearing functional assessment	Anatomy of eye, Image formations in eye	Anatomy of upper & lower extremities	Basic assessment and evaluation for mobility
3-1	SLO-2	Evaluation of AAC and AT software	Surgical and non surgical hearing aids	Categories of visual impairment	Classification of amputation types	Mobility devices
6.2	SLO-1	Technical and user considerations	Devices to improve hearing	Artificial vision implants	Prosthesis prescription	Wheel chair :seating assessment
3-2	SLO-2	Quality resources on AAC and AT	Implants: Cochlear implant	Cortical and retinal implants	Hand and arm replacement	Interventions in seating system
	SLO-1	Evaluation of quality resources	Bone anchored hearing aids	External visual devices	Different types of models	Biological aspects of tissue health
S-3	SLO-2	Universal principles in AAC and AT	Assistive listening devices	Low and High technology to improve mobility	externally powered limb prosthesis	Support surface classification
S-4	SLO-1	Evidence based practice in AT	Electronic communication aids	Electronic Travel Aids(ETA)	Foot orthosis	Optimum seated posture

	SLO-2	Human factors in evaluation of AT	Analog and digital recorders	Low and High technology for reading and writing	Pediatric orthoses	Types of wheelchairs : Manual wheel chairs
6 E	SLO-1	Environmental and social factors	Assistive listening devices	Auditory information display	Wrist-hand orthosis	Power wheelchairs
3-3	SLO-2	Psychological factors influencing the use of technology	Devices to improve communication	AT for dual sensory impairments	feedback in orthotic system	Power assisted wheelchairs
5.6	SLO-1	Various Physiological influencing factors	Design constraints in designing Adapted mouse	AT for leisure and recreation	Components of upper limb prosthesis	Control systems, navigation in virtual space by wheelchairs
3-0	SLO-2	Sensory and Motor factors	Smart pen-technology	Activities of daily living (ADL)	Components of lower limb prosthesis	Control systems, navigation in virtual space by wheelchairs
67	SLO-1	Low technology :Communication displays	Keyboard variations for differently abled	Daily living aids	Lower extremity- and upper extremity- orthoses	EOG based voice controlled wheelchair
5-1	SLO-2	Object communication displays, Communication Boards	Modifying existing technology	AT in Home	Intelligent prosthesis	BCI based wheelchair
.	SLO-1	Principles of high technology assistive devices	Voice recognition and word prediction software	Technology for writing	functional electrical stimulation	Wheel chair standards & tests
3-0	SLO-2	Difference in high and medium technology	Communication devices	Alternative devices for safety	Electric Electronic Stimulation	Wheel chair standards & tests
e 0	SLO-1	Picture exchange communication system	Smart phones, Cell phones and videophones	Orientation & navigation Aids	Fuzzy logic expert system for automatic tuning of myoelectric prostheses	Wheel chair transportation
3-9	SLO-2	lssues and considerations for low and high tech tools	Visual devices using sign	Alert systems	Fuzzy logic expert system for automatic tuning of myoelectric prostheses	Mobility device Accessories
		1 Oliver Wordt Doumond W Oviet Lule L. Lle	ud "Assistive Technology Principles and Applie	otions for 5 Drawnooll Simon at al A	avetametic review of lifestyle manifering technol	aging lournal of talamadiaing and talagara

	1. Oliver Wendt, Raymond W Quist, Lyle L Lloyd, "Assistive Technology: Principles and Applications for	5. Brownsell, Simon, et al,. A systematic review of lifestyle monitoring technologies, Journal of telemedicine and telecare
	Communication Disorders and Special Education", Emerald group publishing Ltd, 1st Edition, 2011.	17.4 (2011): 185-189
Learning	2. Albert Cook, Janice Polgar, "Assistive Technologies -Principles and Practice", Mosby, 4 th Edition, 2015.	6. Marion. A. Hersh, Michael A. Johnson, Assistive Technology for visually impaired and blind, 1st ed., Springer Science &
Becourooo	3. Rory A, Cooper, Hisaichi Ohnabe, Douglas A, Hodson, "An Introduction to Rehabilitation Engineering", CRC	Business Media, 2010
Resources	press, I st Edition, 2006.	7. Kenneth J. Turner, Advances in Home Care Technologies: Results of the match Project, 1st ed., Springer, 2011
	4. Marion A Hersh, Michael A, Johnson, "Assistive Technology for Visually impaired and blind people", Springer,	8. Pascal Verdonck, Advances in Biomedical Engineering, 1st ed., Elsevier, 2009
	1 st Edition, 2008	

Learning Ass	essment										
					Final Examinatio	n (EQV) weighteen)					
	Bloom's Level of Thinking	CLA –	1 (10%)	CLA –	2 (15%)	CLA –	3 (15%)	CLA – 4	l (10%)#		n (50% weightage)
	g	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Lovel 1	Remember	40.9/		40.9/		10.9/		20.9/		200/	
Level I	Understand	40 %	-	40 %		40 %	-	30 %	-	50%	-
Loval 2	Apply	40.9/		40.9/		10.9/		40.9/		409/	
Leverz	Analyze	40 %	-	40 %	-	40 %	-	40 %	-	4076	-
Loval 2	Evaluate	20.9/		20.9/		20.9/		20.9/		200/	
Level 3	Create	20 %	-	20 %	-	20 %	-	30 %	-	50%	-
	Total	10	0 %	10	0 %	100	0 %	100	0 %	10	0 %
# OLA 4	the farmer and a successful setting a	(O T T	Mini Duringto Ora		M000. 0	- Oraf Deserve				

Course Designers

Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldive	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1. Mrs. A Bhargavi Haripriya, SRMIST

Course Code	18BME471T	Course Name	MACHINE LEARNING ANI	D DEEP LEARNING TECHNIQUES IN MEDICINE	Co Cat	ourse egory	, E	Professional Elective L T P 3 0 0						<u> </u>							
Pre-requi	isite Neural Netwo	ks	Co-requisite	Nil	Pro	Progressive Courses Nil															
Course Offering Department Biomedical Engineering Data Book / Codes/Standards Nil																					
Course Le	arning Rationale (CLR	: The pu	rpose of learning this course is to:		Le	arnin	g					Prog	gram	Learn	ing O	utcom	es (PL	_0)			
CLR-1 :	Understand the applica	tions of machir	ne learning and types of learning algo	rithms	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12 [·]	13 1	4 15
CLR-2 :	Learn about the param	etric model of	classification		Ê	(%	(%)	a								×					
CLR-3 : CLR-4	Gain knowledge in mu	tivariate data h ina methods	andling and analysis		300	cy (⁶	nt (9	edde		nent		Ð				Worl		ance			
CLR-5 :	Know the techniques	o compare and	assess the learning algorithms		J) Gu	cien	nme	Iwor	SIS.	lopr	Ľ,	sag	PIC			am	_	Fina	ning		
CLR-6 :	Apply deep learning te	hniques in bio	medical field		inki	Profi	Attai	g K	naly	Deve	Desi		Cultu	ent & litv		& Te	atio	t. &	-eari		
					<u> </u>	ted	ted /	erin	M A	۱& I	is, I	n To	Š	nme nabi		nal	unic	t Mg	ng l		v m
Course Le	arning Outcomes (CL): At the d	end of this course, learners will be ab	le to:	Level o	Expec	Expec	Engine	Proble	Desigr	Analys Resea	Moder	Societ	Enviro Sustai	Ethics	Individ	Comm	Projec	Life Lo	- OS	- OST
CLO-1 :	Explain what are the d	fferent types of	f learning algorithm		1, 2	80	70	M	-	-	-	-	-	-	-	-	-	-	-		
CLO-2 :	Familiarize with differe	nt parametric m	nodels		1, 2	80	70	М	-	-	-	-	-	-	-	-	-	-		M ·	
CLO-3 :	Describe the multivaria	te data analysi	s and the different techniques		2	80	70 - M M						-								
CLO-4 :	Give a detailed accour	t on clustering	techniques		1	80	70	-	-	Н	-	-	-	-	-	-	-	-	М	- ۸	1 -
CLO-5 :	Compare the performa	nce of different	algorithms		1	80	70	-	-	-	-	-	-	-	-	-	-	-	М		
CLO-6 :	Apply the machine and	deep learning	algorithms for concept related to imag	ge analysis	1,2	80	70	-	-	-	-	-	-	-	-	-	-	-	L		. _]

D		Machine Learning - Introduction	Parametric models and Multivariate Methods	Unsupervised learning	Machine learning Experiments	Deep learning Application
Durati	on (nour)	9	9	9	9	9
C 1	SLO-1	Bayesian decision theory , Classification	Parametric Methods	Clustering	Design and Analysis of Machine Learning Experiments	Regularization, Normalizing inputs
3-1	SLO-2	Bias and Variance	Maximum Likelihood Estimation	Mixture Densities	cost-sensitive learning	Weight Initialization for Deep Networks
0.0	SLO-1	Bayes' Estimator	Bernoulli Density	k-Means Clustering	Experiment	Numerical approximation of gradients
5-2	SLO-2	Losses and risks	Multinomial Density	vector quantization	strategies of experimentation	Gradient checking, Gradient Checking Implementation
0.2	SLO-1	Discriminant Functions	Parametric Classification-Regression	leader cluster algorithm	factorial design	Mini-batch gradient descent
3-3	SLO-2	Utility Theory	Bias/Variance	leader cluster algorithm	Response Surface Design	Exponentially weighted averages
C 4	SLO-1	Value of information	Model Selection Procedures	Expectation-Maximization Algorithm	Randomization, replication, blocking, pairing	Classical Supervised Tasks with Deep Learning
3-4	SLO-2	Bayesian networks	Validation techniques , Minimum length description, Bayesian model selection	Mixtures of Latent Variable Models	Guidelines for Machine Learning Experiments	Brain MRI Age Classification
с ғ	SLO-1	Influence Diagrams	Multivariate Data	Supervised Learning after Clustering	Choice of Factors and Levels	Image Denoising
3-3	S-5 SLO-2	Association Rules	Parameter Estimation	Hierarchical Clustering	Choice of Experimental Design, Performing the Experiment	Image Denoising

56	SLO-1	Machine learning applications-learning associations,	Estimation of Missing Values	Choosing the Number of Clusters	Statistical Analysis of the Data	Analysis of medical images
3-0	SLO-2	classification, regression,	Multivariate Normal Distribution	Nonparametric Methods	Cross-Validation and Resampling Methods	Analysis of medical images
0.7	SLO-1	unsupervised learning, reinforcement learning	Multivariate Methods- Multivariate Data	Instance-based memory-based learning	K-Fold Cross-Validation	Automatic Interpretation of Carotid Thickness
5-1	SLO-2	Supervised learning-examples	Parameter Estimation	Nonparametric Density Estimation	5×2 Cross-Validation	Automatic Interpretation of Carotid Thickness
0.0	SLO-1	Regression, Noise, learning multiple classes	Principal Components Analysis	Kernel Estimator	Bootstrapping	3-D Brain Tumor Segmentation
5-8	SLO-2	Probably Approximately Correct (PAC) learning	Eigen faces and Eigen digits	k-Nearest Neighbor Estimator	Measuring Classifier Performance	3-D Brain Tumor Segmentation
0.0	SLO-1	Vapnik–Chervonenkis (VC) dimension	reconstruction error, Karhunen-Lève expansion	Generalization to Multivariate Data	Interval Estimation	Convolutional NN for Real time 2D/3D Registration
5-9	SLO-2	Exercises	Multidimensional scaling, Linear discriminant Analysis	Nonparametric Classification	Comparing Multiple Algorithms	Convolutional NN for Real time 2D/3D Registration

Learning Resources	1. 2. 3.	Tony J. Cleophas and Aeilko H. Zwinderman, "Machine Learning in Medicine - a Complete Overview", Springer,2015 Sunila Gollapudi, S., "Practical Machine Learning", Packt Publishing Ltd.2016 Applied Deep Learning: A Case-Based Approach to Understanding Deep Neural Networks, By Umberto Michelucci, Delaware corporation, 2018	 Deep Learning for Medical Image Analysis, edited by S. Kevin Zhou, Hayit Greenspan, Dinggang Shen, Academia Press, 2017 Deep Learning, An MIT Press book, Ian Goodfellow and Yoshua Bengio and Aaron Courville http://www.deeplearningbook.org Introduction to Deep Learning: From Logical Calculus to Artificial Intelligence, By Sandro Skansi, Springer, 2018
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Learning Assessme	Learning Assessment													
	Diagm's			Final Examination (50% weightage)										
	DIUUIIIS	CLA – 1	1 (10%)	CLA –	2 (15%)	CLA – S	3 (15%)	CLA – 4	(10%)#		r (50% weightage)			
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice			
Level 1	Remember	40.0/		10.0/		40.0/		20.0/		200/				
Level	Understand	40 %	-	40 %	-	40 %	-	30 %	-	30%	-			
Lovel 2	Apply	10.0/		10.0/		10.0/		10.0/		100/				
Level Z	Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-			
Lovel 2	Evaluate	20.0/		20.0/		20.0/		20.0/		200/				
Level 3	Create	20 %	-	20 %	-	20 %	-	30 %	-	30%	-			
	Total 100 %				0 %	100) %	100) %	100 %				

Course Designers											
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts									
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldive	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1. Mrs. A Bhargavi Haripriya, SRMIST									

											_					L	Т	Р	С			
Course Coo	le 18BME472T	Course Name	Virtual	Reality in Hea	th care				Course Category E				Pi	rofessio	onal Ele	ctive		3	0	2	4	
		±	· · · · · · · · · · · · · · · · · · ·							1												
Pre-requisite Nil Co-requisite Nil Nil									Progre Cour	ssive ses		Nil										
Course Offer	ring Department		Biomedical Engineering		Data Boo	k / Codes	s/Standards									Nil						
								T T														
Course Lear	ning Rationale (CLR):	The purp	ose of learning this course is to:			Learni	ng					P	rogran	n Learr	ning O	utcome	es (PLC	<u>)</u>				
CLR-1 :	Understand the sensors in v	irtual reality syste	ms		1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 : Understand the techniques in image creation						>	Ŧ											e				
CLR-3: Understand the techniques in image manipulation and viewing						Suc	Jen				-	age				٦		nan	p			
CLR-4 :	Gain knowledge in technique	es involved in hap	tics		king	ficie	ainn		ysi		ign	Use	ture	∞ ŏ		ear	ы	Ξ	Luir.			
CLR-5 :	Gain knowledge in auditory	aspects in VR			- International	Pa	Atta	g a	nal	ent	Des		Cul	lity		S ⊥	cati	٦t. 8	Lea			
CLR-6 :	Understand the various inpu	t sensors, visual a	and auditory aspects of virtual reality system	S	Def T	ed	eq	eri	2 E	∞ m	is, l	דר T	/ &	ab Tab		ual	nii	ž	bu	~	2	ŝ
0						ect a	ect	wle wle	blei	ign /elo	ilys	derr	iety	iror	ics.	ĕ	Ē	ject	2	ö	ö	ö
Course Lear	ning Outcomes (CLO):	At the en	d of this course, learners will be able to:		Lev L	2 X X	(% EX	Ц Ц Ц Ц Ц Ц Ц Ц Ц Ц Ц Ц Ц Ц Ц	5 2	Des Des	Ane Res	Moc	Soc	Sus	Et	Vo Vo	Ğ	D D	Life	PS(PSC	PS(
CLO-1 :	Explain the terms and the va	rious input senso	rs used in VR		1,2	80%	70%	М	-	-	-	-	-	-	-	-	-	-	-	М		
CLO-2 :	Analyze the visual aspects of	f VR systems			2	80%	70%	М	-	-	-	-	-	-	-	-	-	-	-	М		
CLO-3 :	Demonstrate the various tec	hniques for image	e creation and manipulation		2	80%	70%	М	-	-	-	-	-	-	-	-	-	-	-		L	
CLO-4 :	Explain the various haptic se	ensors and technic	ques used in VR		2	80%	70%	М	-	-	-	-	-	-	-	-	-	-	-	М		
CLO-5 :	LO-5 : Explore the various auditory aspects related to VR				2	80%	70%	М	-	-	-	-	-	-	-	-	-	-	-	Μ		
CLO-6 :	0-6 : Describe and explain the various components of Virtuality reality systems				2	80%	70%		L	-	-	-	-	-	-	-	-	-	-	М		

		Input Periphery	Visual Aspects- I	Visual Aspects - II	Haptic Aspects	Auditory Aspects and applications
Duratio	n (hour)	9	9	9	9	9
	SLO-1	Definition of Virtual Reality (VR)	Computer graphics, building blocks	Light Sources and Reflection	Haptic sense and perception	Auditory Sense and Perception
S-1	SLO-2	Presence and Immersion, Need for training in medicine	Visual sense and perception	Point light, directional light, spot light	Tactile receptors,	interaural level differences
S-2	SLO-1	Principles of VR, Main components	Human eye, photoreceptors, color vision	Ambient light, diffuse reflection, specular reflection,	Kinesthetic receptors,	Design of Auditory Displays
	SLO-2	Problems in VR	RGB color space, liquid crystal display	Viewing projections	Psychophysics	Headphones
6.2	SLO-1	Human Actuators , Input Modalities	color spaces, subtractive model	Image projection in the thin lens camera model	Haptic Display Technology	Mono, Stereo, and Surround Loudspeaker Systems
5-3	SLO-2	Position and movement recording	HSV color space	Depth of field in thin lens camera model	Kinematic principles, serial and parallel	Auditory Rendering
S-4	SLO-1	Resistive sensors, Capacitive sensors	Depth Perception, monocular cues	Projection in pinhole camera	Actuation principles	Olfactory and Gustatory Aspects
• •	SLO-2	Inductive sensors, Ultrasound and optical methods	Oculomotor cues,	Early depiction of a Camera Obscura	Shape memory alloys	wearable olfactory display devices
	SLO-1	Position and movement measuring systems	binocular cues	Perspective projection	Electroactive Polymers	Gustatory Sense and Perception
S-5	SLO-2	Desktop systems, body mounted systems	Visual Display technology	2D mapping in the yz-plane	Piezoelectric Actuators	Virtual Reality for Rehabilitation
8.6	SLO-1	Contact free and remote systems	Stereoscopic rendering	Orthographic projection	Control Principles of Haptic Displays	Virtual Reality Supported Physiotherapy
3-0	SLO-2	Eye tracking systems	Display hardware	Orthographic projection onto image plane	Terminology	Gait Rehabilitation,
67	SLO-1	Force and torque recording	Virtual reality displays	Surface Shading	Admittance and Impedance Control Architectures	Robot-Assisted Gait Training
3-1	SLO-2	Sound and speech recording	Cave Automatic Virtual Environment	Flat Shading	Stability, Passivity and safety of Haptic Displays	Motivation for Robot Aided Arm Therapy

	SLO-1	Physiological data recording	Head mounted displays	Gouraud Shading		Ground- and Wall-Mounted Systems	Virtual Reality Applications with ARMin
S-8	SLO-2	Bioelectrical signal	Rendering in computer graphics	Phong Shading		Tactile and Portable systems	Wheelchair Mobility and Functional ADL Training
80	SLO-1	Blood pressure measurements, pulse oximetry, skin conductance Object representations Advanced Rendering Techniques, Ray Tracing Haptic Rendering				Haptic Rendering	VR Based surgical simulator and its components
3-9	SLO-2	Respiratory measurements	Geometry transformations (basics)	Radiosity, Visual Display	rs in Medical VR	Penalty method, Haptic Displays in Medical VR	VR for Surgical planning
Learning	1	Robert Riener, Matthias Harders, "Virutal R	doar "Virtual Reality: Future of Health Care" il	Iniverse 2003			
Resources	2	Wadee Alhalabi "Virtual Reality Implementa 2017	tion in Healthcare Settings", Medical Informatic	on Science Reference,	4. James F	Roland, "Virtual Reality and Medicine", Reference	ePoint Press, Incorporated, 2018.

Learning Ass	Learning Assessment													
	Dia amia			Con	tinuous Learning Ass	essment (50% weight	tage)			Final Evanination	- (FO)(
	BIOOM S	CLA –	1 (10%)	CLA –	2 (15%)	CLA –	3 (15%)	CLA – 4	4 (10%)#	Final Examination (50% weightage)				
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice			
Lovel 1	Remember	10.0/		10.0/		10.0/		20.0/		200/				
Level I	Understand	40 %	-	40 %	-	40 %	-	30 %	-	30%	-			
Lovel 2	Apply	10.0/		10.0/	-	40 %	_	10.0/		100/				
Level 2	Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-			
Lovel 2	Evaluate	20.0/		20.0/		20.0/		20.0/		200/				
Level 5	Create	20 %	-	20 %	-	20 %	-	30 %	-	30%	-			
	Total	10	0 %	10	0 %	10	0 %	10	0 %	100 %				

Course Designers											
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts									
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldive	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1. Dr.T.Jayanthi, SRMIST									

Course Code	18BMO121T	Course Name	Fundamentals of Biomedical Engineering	Course Category	0	Open Elective	L 3	Т 0	P (<u>)</u> 3
					-					_
Pre-requisite	NII		Co-requisite		Pro	ogressive Nil				
Courses	INII		Courses		C	ourses				
Course Offering De	partment	Biomedical Engineering	Data Book / Codes/Standards		Nil					
Course Learning De	tionals (CLD)	The nurnees of learning this source		Learning		Brogrow Learning Outcomes (PLO)				1

Course Learning Rationale (CLR): The purpose of learning this course is to:	L	earnin	g					Pr	ogran	1 Learn	ing Ou	utcome	es (PLC))			
CLR-1: Have an idea about the basics of physiology	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14 15
CLR-2: Know the basic aspects of biomedical recorders	(c	()	(
CLR-3 : Learn the various patient monitoring systems used in health care	Doc	%)	%)	ge		art a						ork		e			
CLR-4 : Perceive the physics behind x-ray imaging and computed tomography (CT)	Big	nc)	ent	vlec		me		ge				N		and	б		
CLR-5 : Understand the physics behind magnetic resonance and the techniques in resonance imaging	ing	icie	m	2 Q	'SiS	de la	gn,	Jsa	ure			earr	ç	Ë	nin		
CLR-6: Describe the properties and techniques involved in Therapeutic Equipment's	inki	rof	tta	- Ч Х	y la	eve	esi	oا ר	ff	ity ity		ΎΕ	atio	°⊗ ∵	ear		
	L L	Ъ	d bé	arine.	٦Ar	~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~	s, D	Lo L	~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~	mel abil		al 8	nic	Mgi	lg L		
Course Learning Outcomes (CLO): At the end of this course, learners will be able to:	Level of	Expecte	Expecte	Enginee	Problen	Design	Analysi: Resear	Modern	Society	Environ Sustain	Ethics	Individu	Commu	Project	Life Lor	PSO - 1	PSO - 2
CLO-1: Explain the basics of physiology	1, 2	80	70	М	-	-	-	-	-	-		-	-	-		-	
CLO-2: Describe the basic concepts of biomedical recorders	1, 2	80	70	-	-	-	М	-	-	-	-	-	-	-	М	М	- -
CLO-3 : Implement the various uses of patient monitoring system	2	80	70	-	-	-	М	-	-	-	-	-	-	-	М	М	
CLO-4 : Understand the physics behind X- ray and CT	1	80	70	-	-		М	-	-	-	-	-	-	-	М	-	М -
CLO-5 : Explain the concepts of MRI	1	80	70	-	-	-	М	-	-	-	-	-	-	-	M	-	
CLO-6 : Apply the recent advancements in Therapeutic Equipment's	1,2	80	70	-	-	-	-	-	-	-	-	-	-	-	Н	-	

Du	ration	FUNDAMENTALS OF BIOMEDICAL INSTRUMENTATION	BIOMEDICAL RECORDERS	PATIENT MONITORING SYSTEMS	DIAGNOSTIC IMAGING SYSTEMS	THEREPEUTIC EQUIPMENTS
(r	our)	9	9	9	9	9
S-1	SLO-1	Anatomy and Physiology	Electrocardiograph	Introduction to cardiac monitor	Basics of diagnostic radiology	Need for cardiac pacemaker
0-1	SLO-2	Physiological system of the body	Block diagram of an ECG machine	Basic Block diagram of Bedside patient monitoring systems	Nature of X-rays	External and Implantable pacemaker
6.2	SLO-1	Sources of Biomedical signals	Block diagram of an ECG machine	Basic block diagram of Central monitors	Production of X-rays	Need for Defibrillators
3-2	SLO-2	2 Sources of Biomedical signals The ECG leads Measurement of heart rate Stationary anode tub		Stationary anode tube	DC defibrillator	
S_2	SLO-1	Basic Block diagram of medical instrumentation system	The ECG leads	Average heart rate meters	Rotating anode tube	Implantable defibrillator
5-5	SLO-2	Basic Block diagram of medical instrumentation system	Effects of Artifacts on ECG recording	Instantaneous heart rate meters	Block diagram of an X-ray machine	Principle of surgical diathermy
84	SLO-1	General constraints in design of medical instrumentation system	Block diagram of Microprocessor based ECG machine	Measurement of pulse rate	Block diagram of an X-ray machine	Surgical diathermy machine
3-4	SLO-2	General constraints in design of medical instrumentation system	Phonocardiograph (PCG)	Blood pressure measurement	Introduction to computed tomography	Short wave diathermy
8.6	SLO-1	Origin of bioelectrical signals	Origin of heart sound	Blood pressure measurement	Introduction to computed tomography	Microwave diathermy and Ultrasonic unit
3-3	SLO-2	Electrocardiogram	Origin of heart sound	Direct methods of monitoring blood pressure	Basic principles of CT	Working of hemodialysis machine
8.6	SLO-1	LO-1 Electroencephalogram Electroencephalograph Direct methods of monitoring blood pressure Basic principles of CT				Principle of peritoneal dialysis
3-0	SLO-2	Electromyogram	Electroencephalograph	Indirect methods of monitoring blood pressure	Introduction to Nuclear imaging	Need for anesthesia

S-7	SLO-1	Recording electrodes	Block diagram description of Electroencephalogram	Indirect methods of monitoring blood pressure	Single photon emission computed tomography	Working principle of anesthesia machine
	SLO-2	Silver-silver chloride electrodes	Block diagram description of Electroencephalogram	Automatic blood pressure measuring apparatus using korotkoffs method	Positron emission tomography	Mechanics of respiration
	SLO-1	Electrodes for ECG	Electromyography	Ultrasonic method	Principle of NMR imaging, spin polarization	Ventilators and types of ventilators
5-8	SLO-2	Electrodes for EEG	Block diagram description of Electroencephalograph	Measurement of Respiration rate	Resonance, relaxation, spin echoes, gradient echoes	Automated Drug delivery system
8.0	SLO-1	Electrodes for EMG	Block diagram description of Electroencephalograph	Displacement method	Introduction to ultrasound	Infusion pumps
S-9	SLO-2	Microelectrodes	Biofeedback Instrumentation	Apnoea detectors	Modes of ultrasound	Implantable Infusion system

	1. Jerrold T. Bushberg, John M. Boone, "The essential physics of medical imaging", Lippincott Williams &	Nadine Barrie Smith, Andrew Webb, "Introduction to medical imaging: Physics, Engineering and clinical applications", Cambridge University Press, 1st
Learning Resources	Wilkins, 3rd edition, 2011.	edition, 2010.
	2. Rongguang Liang, "Biomedical optical imaging technologies: Design and applications", Springer Science &	4. M. A. Flower (Editor), "Webb's Physics of medical imaging, Second Edition", CRC Press, Taylor & Francis Group, ISBN: 978-0-7503-0573-0, 2nd
	Business Media, 1st edition, 2012	edition, 2016.
1		

Learning Assessment													
	Ploom's			Conti		Final Examination (E09/ unightage)							
	DIUUIII S	CLA – 1 (10%)		CLA – 2 (15%)		CLA –	3 (15%)	CLA – 4	(10%)#	Filiai Examination (50% weightage)			
	Level of Thinking		Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice		
Lovel 1	Remember	10 %		10.0/		10.9/		20.0/		200/			
Level I	Understand	40 %	-	40 %	-	40 %	-	30 %	-	30%	-		
Lovel 2	Apply	10 %		10 %		10 %		40 %	-	10%			
Leverz	Analyze	40 /0	-	40 78	-	40 70	-			4070	-		
Level 3	Evaluate	20 %		20.%		20 %		30 %		20%			
	Create	20 70	-	20 /0	-	20 70	-	50 78	-	5078	-		
	Total 100 % 100 % 100 %		0 %	10) %		100 %						

Course Designers									
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts							
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldives	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1.Dr.P.Vinupritha, SRMIST							

Course Code	18BMO122T	Course Name	ŀ	ealth information systems	Cour	rse Cate	egory	0					Open I	Elective					L 3	T 0	P 0	C 3
Pre-requisite Courses Nil Co-requisite Courses Nil Course Offering Department Biomedical Engineering Data Book / Codes/Standards						Progressive Nil Courses Nil																
Course Learnin	g Rationale (CLR):	The purpose of learn	ning this course is to:			Learnir	ıg						Progra	m Learr	ning Ou	utcomes	(PLO)					
CLR-1 :		Understand the basi	ic of health information		1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 : CLR-3 : CLR-4 : CLR-5 : CLR-6 : Course Learnin	g Outcomes (CLO):	Appreciate the use r Identifying different a Understand strategin Use Health informat Apply HIS usage in At the end of this co	new methods in health info architecture of HIS es in HIS data managemer ion system for the hospital Indian context urse, learners will be able to information to be bable to	mation acquisition and medical records t regulations benefit o:	Level of Thinking (Bloom)	Expected Proficiency	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PS0 - 1	PSO - 2	PSO - 3
CLO-1 :		Appreciate the role of administration, educ	of information technologies ation, and research	in potentially revolutionizing healthcare delivery,	1, 2	80%	70%	М														
CLO-2 :		Integration of existin	ng & emerging technology i	n Healthcare	2	80%	70%	М														
CLO-3 :		Know about archited	cture standards in HIS		2	80%	70%			М		М								М		L
CLO-4 :		Identify acceptance	testing & issues on standa	rds in HIS	3	80%	70%			L		М										
CLO-5 :		Use health informati	ion for computer aided diag	nostic purposes	3	80%	70%	М		Ĺ										М		Ĺ
CLO-6 :		Apply Health Inform	ation in hospital context		3	80%	70%	М							М	L						

		Foundations of Health Information Management	Medical Records and other documents	Architecture and Interfacing for Healthcare Technology	Regulations and Computer Aided detection	Future of HIS and Technology			
Duration (hour)		9	9	9	9	9			
6.4	SLO-1	Health Care Systems	A Brief Introduction to Medical record history	Complexity of systems in healthcare	Computer-Aided Diagnostics	eHealth, mHealth			
3-1	SLO-2	Evolution Health Care	Physical Record - Data expected in record	Wireless networks	Computer-Aided detection	Equipment used in eHealth, mHealth data			
S-2	SLO-1	Health Informatics	Health Insurance Portability and Accountability Act (HIPAA)	LAN security	Electronic Health Record Data	Social Media, and Telemedicine			
	SLO-2	Types of data to expect in Life Science	Problems-advantages of Physical Records	overcoming LAN security vulnerabilities	Database Presentation and Statistics	Improved use of Telemedicine			
	SLO-1	Information Management Profession in Hospitals	Modules in Hospital Information System(HIS)	Middleware	Health Record Data	Parts of telemedicine			
S-3	SLO-2	Confidentiality Issue, Ethics	Admission/Discharge/Transfer (ADT) system	Different products in Middleware	Representing data	Connecting rural India through telemedicine			
S-4	SL0-1	Medical Data , Importance of confidentiality	Scheduling & Registration	Network Interoperability	Public Health Informatics	Voice enabled recordings in health			
	SLO-2	Personal and Impersonal data	Pharmacy System	Platform interoperability	Patient EHR Databases in public health	disease progression modeling			
	SLO-1	Health Information Infrastructure	Embedded CDSS	Database Interoperability	Clinical decision support systems	Handheld Technologies in Healthcare at home			
S-5	SLO-2	Health Information Systems	Connecting Teleradiology	GUI/MUI Interoperability	Clinical decision support systems	Handheld Technologies in Healthcare at hospital			
8.6	SLO-1	Standalone Information System	Laboratory Information System(LIS)	Multi-Location Enterprise	Privacy and patient protection concerns	Integrating Handheld Technologies at hospital			
3-0	SLO-2	Clinical Decision Support System(CDSS)	Laboratory Information System(LIS)	Inter-enterprise health care solution	Privacy and patient protection concerns	Technology for personalized medicine			
S-7	SLO-1	Hospital Information System(HIS)	Electronic Health Record Data	Timely Admissions, Discharges, and Transfers	Implementing Computerized Physician Order Entry	Automated Patient Identification			
	SLO-2	Related Parties in HIS	Dangers of Large Databases	Connectivity to Another Health Plan	Issues and Ethics in HIS	Automated Patient Identification in medicine			
۰ ه	SLO-1	Profit & Nonprofit healthcare stakeholders ; Provider (Hospital)	Internal Data – Clinical, Administrative	Information Systems Life Cycle	Privacy and health Law	Bar Coding, and Smart Cards			
-----	-------	--	---	--	------------------------	---			
3-0	SLO-2	Payers(Insurance Companies) ; Employers ; Practitioners ;	Use of internal data	Information Systems Life Cycle	Predicting Uncertainty	Applying Bar Coding, and Smart Cards in research in Hospital			
	SLO-1	Public Health Officials; Educator ; Consumers	External Data – Comparative, Expert Data,	Health Care Informatics	Risk management in HIS	Impact of HIS on Research			
S-9	SLO-2	Expectations and roles of above parties involved	External Data- Knowledge Base	Project management in health Informatics	Risk management in HIS	Impact of Technology on Policy, and Public Health			

	1.	Winter, A., Haux, R., Ammenwerth, E., Brigl, B., Hellrung, N., Jahn, F., "Health Information Systems-Architectures and	3.	Karen A. Wager, Frances W. Lee, John P. Glaser, "Health Care Information Systems: A Practical Approach
Learning		Strategies", 2nd Edition Number, Springer-Verlag London, 2011		for Health Care Management", John Wiley & Sons, 4th edition, 2017
Resources	2.	Mervat Abdelhak Mary Alice Hanken, "Health Information: Management of a Strategic Resource", 5th Edition, Saunders,	4.	Jean A Balgrosky, "Essentials of Health Information Systems and Technology", Jones & Bartlett Publishers,
		2015		2014

Learning Asse	ssment										
	Bloom's			Conti	nuous Learning Ass	essment (50% weigh	ntage)				Final Examination (E0%, weightage)
	DIUUIII S	CLA –	1 (10%)	CLA –	2 (15%)	CLA – S	3 (15%)	CLA – 4	l (10%)#		Final Examination (50% weightage)
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Loval 1	Remember	10.0/		10.0/		40.0/		20.0/		200/	
Level	Understand	40 %	-	40 %	-	40 %	-	30 %	-	30%	-
Lovel 2	Apply	10.0/		10.0/		10.0/		10.9/		100/	
Level Z	Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Loval 2	Evaluate	20.0/		20.0/		20.0/		20.0/		200/	
Level 3	Create	20 %	-	20 %	-	20 %	-	30 %	-	30%	-
	Total	10	0 %	10	0 %	100) %	10	0 %		100 %

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldives	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1.Mrs.Bhargavi Haripriya, SRMIST

Course Code	e Code 18BMO123T Course Name Basics of medical imaging			Cou	rse Cate	egory	0			Open Elective							L 3	T 0	P 0	C 3		
Pre-requisite C Course Offering	Pre-requisite Courses Nil Progressive Courses Nil Progressive Offering Department Biomedical Engineering Data Book / Codes/ Standards Progressive Courses Nil																					
Course Learning Rationale (CLR): The purpose of learning this course is to:										ning Program Learning Outcomes (PLO)												
CLR-1 :	Gain knowledge	e about the working (principle of X-ray imaging	1	2	3		1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Understand the	working principle of	Computed tomography	Ê	(%	(%		е		Ţ						×					les	
CLR-3 :	: Gain knowledge in physics behind nuclear radiation and the imaging modalities in nuclear medicine			300	ر در	ut (°		6pe		nen		0				Vor		nce	1	nal	niqu	~
CLR-4 :	Understand the	working principle of	ultrasound and its different imaging modalities	g (E	ien	me		owl	N.	lopn	ć	sage	e			m	_	ina	ing	ssio	echi	Ze {
CLR-5 :	Interpret the wo	orking principle of ma	agnetic resonance and its application in imaging	nki	lofic	ttain		Kn	alys	evel	esig	ŝ	ultu	t &		Teã	tion	8	eam	nt ofe:	it T	Jaly
CLR-6 :	Understand the	physics behind the	vorking of medical imaging modalities	Thi	Ъ	id Ai		iring	۱An	õ	ے م	100 1	8 0	abili		ସ	nica	Mgt.	g Le	I: PI	E P	Ä –
L				al of	ecte	ecte		nee	ler	gn	lysis earc	еШ	ety	ron	ĸ	/idu	nmi	ect I	Lon) - 1 eve	90e	
Course Learnin	g Outcomes (CL	0):	At the end of this course, learners will be able to:	eve	Å	ă.		Eng	jo L	Des	Ana Res	Nod	Soci	Sust	ţ.	ndiv	Con	jo	life	PSC Achi	^o SC	SC SC
CLO-1 :	Describe the pr	rinciple behind the w	orking of X-ray imaging	1	80	70		M												M		
CLO-2 :	Explain the und	erstanding of princip	le behind working of tomographic imaging and reconstruction procedures.	1, 2	80	70		М											1	М		
CLO-3 :	Gain knowledge	e in working principle	of nuclear medicine imaging modalities	1,2	80	70							М						1			М
CLO-4 :	Understand the	physics of ultrasour	d and the modes of ultrasound imaging	1	80	70							М						1			М
CLO-5 :	Explain the physical principle of magnetic resonance imaging and the instrumental components involved in MR imaging			ig 1	80	70	1	М											1			М
CLO-6 :	Explain the prin	ciple, working and cl	inical application of imaging modality	1,2	80	70	1	М											1			

		X-Ray imaging	Computed Tomography	Nuclear Medicine	Ultrasound	Magnetic Resonance Imaging
Duratio	on (hour)	9	9	9	9	9
S 1	SLO-1	Principles of Imaging with X-rays	Computed Tomography	General principles of Nuclear Medicine	General Principles -Wave Propagation	Nuclear Magnetism
3-1	SLO-2	Production of X- ray	Historical development	Radioactivity basics	Ultrasound Characteristics	Quantum mechanical description
S-2	SLO-1	Interaction of X-ray with Tissue-Coherent, Compton and photoelectric effect	Instrumentation	Production of radionuclides	Wave reflection and refraction	Radiofrequency pulse and rotating frame
SLO-2		Attenuation coefficients of X-rays in tissue	Hounsfield unit	Types of radioactivity	Absorption, Scattering, Attenuation	Spin-Spin and Spin-Lattice relaxation
S-3	SLO-1	Instrumentation of Planar X-ray imaging-collimators	Detectors and Detector arrays	Instrumentation-Gamma camera	Instrumentation-Transducers	Measurement of T1 and T2
3-3	SLO-2	Anti-scatter grids	Tomographic reconstruction	Collimators, scintillation crystal	Transducer arrays	Inversion recovery
S-4 SLO-1		Intensifying screen	Back projection algorithm Digital image display	Photomultiplier tubes	Scanning modes-A-Mode	Spin echo sequences
	SLO-2	Electronic Intensifier	Radiation dose	Pulse height analyzer	B-Mode scan	Slice Selection
S-5	SLO-1	X-ray Film	Image quality	Single photon emission computed tomography	M-Mode	Phase and frequency encoding
0-5	SLO-2	Image characteristics	Artifacts	Instrumentation	Duplex scanner	
5-6	SLO-1	Digital radiography	Helical CT	Image reconstruction	Image characteristics- signal to noise ratio	MRI Instrumentation- Block Diagram
3-0	SLO-2	Flat panel detectors	Multislice spiral CT	Clinical Application	Spatial resolution, Contrast -to-noise ratio	Magnets
67	SLO-1	Mammography – Basics	Multiplica CT Detector configurations	Photon Emission Tomography-General Principles	Doppler effect, Continuous wave Doppler	Magnetic field gradient coil
3-1	SLO-2	Mammography – Basic block diagram		Radionuclides used for PET		Radiofrequency coil
5-8	SLO-1	X-ray tube design	Phase selective imaging Introduction	Instrumentation for PET	Color Doppler imaging	Image characteristics
0-0	SLO-2	Digital Mammography	Phase selective imaging Applications	Image reconstruction	Safety in ultrasound imaging	MRI contrast agents
S-0	SLO-1	Fluoroscopy - Introduction	CT Applications-cerebral scans	Image characteristics	Clinical applications-obstetrics and gynecology	Clinical application-Brain
0-9	SLO-2	Fluoroscopy Imaging system	CT Applications - Pulmonary diseases	Clinical applications of PET	Clinical Applications - Cardiac disease	Clinical application -Cardiac system

	1.	R.S.Khandpur., 'Handbook of Biomedical instrumentation', Tata McGraw Hill Publishing Co Ltd., 3rd	З.	M. A. Flower (Editor)., "Webb's Physics of medical imaging, Second Edition", CRC Press, Taylor & Francis Group, ISBN: 978-0-7503-
Learning		edition, 2014.		0573-0, 2nd edition, 2016. Nadine Barrie Smith, Andrew Webb, "Introduction to medical imaging: Physics, Engineering and clinical
Resources	2.	Jerrold T. Bushberg, John M. Boone., "The essential physics of medical imaging", Lippincott Williams &		applications", Cambridge University Press, 1st edition, 2010.
		Wilkins, 3rd edition, 2011.	4.	K. Kirk Shung, Michael Smith, Benjamin M.W. Tsui., "Principles of medical imaging", Academic Press, 1st edition, 2012.

Learning Assessment												
	Dia ami'a			Conti	nuous Learning Asse	essment (50% weig	htage)				Final Eventian (EQN/ uninhtana)	
	DIUUIII S	CLA –	1 (10%)	CLA – 2 (15%)		CLA –	3 (15%)	CLA – 4	l (10%)#		Final Examination (50% weightage)	
Level of Thinking		Theory	Theory Practice Theory Practice Theory Practice Theory		Theory	Practice	Theory	Practice				
Lovel 1	Remember	10.0/		10.9/		10 %		20.0/		200/		
Level I	Understand	40 %	-	40 %	-	40 %	-	30 %	-	30%	-	
Lovel 2	Apply	10.0/		10.9/		10 %		10.0/		10%		
Leverz	Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-	
Lovel 3	Evaluate	20 %		20.%		20 %		30 %		30%		
Level 5	Create	20 %	-	20 %	-	20 %	-	30 %	-	30%	-	
	Total	10	0 %	100	0 %	10) %	10	0 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldives	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1.Dr.S.P.Angeline kirubha SRMIST

Course Code	20BM0124T	Course Name	REHAB	ILITATION ENGINEERING		Cou Categ	rse jory	O Open elective								L 1 3 (Г Р) 0	C 3				
Due ve vu			Co requisite				Descussion															
Pre-requ Cours	es	Nil	Co-requisite	Nil			Courses															
Course Of	ering Department		Biomedical Engineering	Data Book / Codes/Standards											Nil							
Course Learning Rationale (CLR): The purpose of learning this course is to:																						
CLR-1:	Understand the biome	chanics of mobil	lity and universal design			1 2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Learn about personal	transportation, n	nanual and powered wheelchairs			~	+			ent								ce				
CLR-3 :	Follow the working of	prosthetics, orth	otics			- Suc	Jen		6	ŭ		age				۶		nan	þ	, I		1
CLR-4 :	Understand sensorial	prostheses				ficie	inn		ysi	elo	ign	Use	ture	<u>م</u>		ear	Б	i. Z	mir	, I		1
CLR-5 :	Perceive the idea of r	ehabilitation med	licine and advocacy			Pro	Atta	۲ ۵	nal	Oev	Des		Cul	ility a		& Τ	catio	Jt. 8	Геа	, I		1
CLR-6 :	Explore the advanced	technologies in	rehabilitation engineering			ed T	ed	erir edg	⊾ ۳	~~	is, l	μ	~×	ab der		ual	nii	Ŵ	ng		2	3
·						el c pom	pect	gine ovle	bleı	sign	alys sear	den	ciety	/iror stair	ics	r vid	Ē	ject	۲o	, , ,	ò	Ö
Course Le	arning Outcomes (C	LO): At the end	d of this course, learners will be able to	ç.		EXE (Bic Lev	S L L L L L L L L L L L L L L L L L L L	Ц Ц Ц Ц Ц Ц Ц	Pa	Des	Ana Res	Mo	Soc	Sus	E	Wo	S	D.	Life	- SC	PSC	PS(
CLO-1:	Explain gait cycle and	basic rehabilitat	tion terminologies			1, 2 80%	70%		L	L												
CLO-2 :	Describe the types an	d technologies w	vith wheelchairs			2 80%	70%		М		М				L							
CLO-3 :	Design basic orthotics	and prosthetics				2 80%	70%				М											1
CLO-4 :	Describe the possibili	ies of sensorial p	prosthetics			3 80%	70%			М												L
CLO-5 :	Tell about the rehabili	tation robotics fie	əld			3 80%	70%		М				Ĺ									М
CLO-6:	Explain the various ac	lvanced topics a	nd challenges in rehabilitation enginee	ring		3 80%	70%	L	L											, <u> </u>	Ĺ	

		Rehabilitation Engineering Introduction	Wheelchair technologies	Orthotics and Prosthetics	Sensorial Prosthetics	Rehabilitation applications		
Duratio	n (hour)	9	9	9	9	9		
6.4	SLO-1	Introduction to rehabilitation Engineering	Personal transportation	Upper extremity-anatomy overview	Sensorial Prosthetics-Introduction	Functional electrical stimulation		
3-1	SLO-2	Scope	Associated disabilities	Lower extremity-anatomy overview	Types of sensorial prosthetics	FES application		
6.2	SLO-1	Assistive technology	Lift mechanisms	Amputation classification	Categories of visual impairment	Robots in rehabilitation		
5-2	SLO-2	Terminologies involved	Application areas	Prosthesis prescription	Cortical implants	Therapeutic robots		
	SLO-1	Design considerations	Wheelchairs	Components of upper limb prosthetics	Retinal implants	Rehabilitation in sports		
S-3	SLO-2	Scope of this field	Types	Fabrication techniques	Mobility aids for blind	Areas of sports application		
S-4	SLO-1	Rehabilitation approaches	Wheelchair standards	Components of lower limb prosthetics	Aids for reading and writing	Daily living aids		
	SLO-2	Concepts in rehabilitation engineering	Safety testing	Fabrication techniques	Graphic access	Daily living aids ctd.		
S E	SLO-1	Universal design	Manual wheelchair	Latest technologies	Orientation and navigation aids	Assistive technology for dyslexia		
3-5	SLO-2	Concept of universal design	Components	Latest trends in prosthetics	Intelligent mobility aids	Assistive technology for speech disorders		
	SLO-1	Barrier free design	Powered wheelchair	Orthotics	Hearing functional assessments	Assistive technology for dysphagia		
S-6	SLO-2	Disability assessment	Design considerations	Needs and types	Surgical hearing aids	Available types		
6.7	SLO-1	Legal aspects	Wheels and casters	Lower extremity orthotics	Non surgical hearing aids	Neurological rehabilitation		
3-1	SLO-2	Provision available	Motor selection	Types and consideration	Latest technologies	Cognitive rehabilitation		
5-8	SLO-1	Mobility	Batteries and microprocessors used	Upper extremity orthotics	Tactile prosthetics	Neuromotor rehabilitation		
5-0	SLO-2	Biomechanics of mobility	Smart wheelchair	Types and consideration	Tongue prosthetics	Examples		

60	SLO-1	Introduction to Gait cycle	Other wheelchair technologies	Latest technologies		Olfactory prosthetics	Latest technologies
3-9	SLO-2	Its applications	Human factor, Fault tolerance	Latest trends in Orthotics		Future of sensorial rehabilitation	Future trends
Learning Resources		 Rory.A.Cooper, "Rehabilitation Engineering J Horia-Nicolai.L.Teodorescu, Lakhmi C. Jain, First Edition, CRC press, 2010. 	Applied to Mobility and Manipulation", First Edition, "Intelligent Systems and Technologies in Rehabilita	CRC Press, 2010 ation Engineering",	 Glenn Hedman, Michael P. Barr Press, 2005 	. "Rehabilitation Technology", First Edition, Haworth nes, Anthony B. Ward, "Oxford Handbook of Rehabi	Press Inc, 1990. litation Medicine", First Edition, Oxford University

Learning Assess	arning Assessment											
	Dloom's			Conti	nuous Learning Ass	essment (50% weig	htage)				Final Examination (EOP/ weighters)	
	DIUUIII S	CLA –	1 (10%)	CLA – 2 (15%)		CLA –	CLA – 3 (15%)		4 (10%)#		Final Examination (50% weightage)	
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	
Lovel 1	Remember	10 %		10 %		10 %		30 %		30%		
Level I	Understand	40 70	-	40 70	-	40 70	-	50 78	-	5078	-	
Lovel 2	Apply	10 0/		10.0/		10 0/		10 0/		100/		
Leverz	Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-	
Louis 2	Evaluate	20.0/		20.0/		20.0/	20.9/			200/		
Level 5	Create	20 %	-	20 %	-	20 %	-	30 %	-	30%	-	
	Total	10	0 %	100) %	100) %	10	0 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldives	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1. Dr.Varshini Karthik, SRMIST

Course Code	18BMO125T	Course Name		Quality control for biomedical devices		Course		y O					Ope	n Electi	ive					L T 3 0	P 0	C 3
Pre-requisi Courses Course Offer	Correquisite Courses Co-requisite Courses Nil urse Offering Department Biomedical Engineering Data Book / Codes/Standards						Progre Cours	ssive ses						Nil	Nii	1						
Course Lear	ning Rationale (C		Learni	ng						Prograr	n Leari	ning Ou	utcomes	(PLO)								
CLR-1: Uti	lize Quality, Quali	y, Quality control measures essential for an organization				1 2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2: Uti	: Utilize the quality management principles and good management practices					y	ŧ											лсе				
CLR-3 : Uti	CLR-3 : Utilize the various quality control tools						Jer		S			age	Ð			ε		inar	ĝ	1		
CLR-4 : Uti	CLR-4: Utilize the various quality management tools					kinę	ain		lysi		ign	Usi	Itri	∞ _		ea	ы	LL avi	Ë	1		
CLR-5 : An	alyze the various	standards applicabl	le to healthcare globally and r	ationally		Pro	Atta	e g	∖na	ent	Des	8	Cul	ant		& T	cati	jt.	Lea	1		
CLR-6 : Im	plement the globa	l standards in healt	hcare			of T ted	fed	eri edg	ц ш	s d	is, is	Ĕ	≪ ⊗	nm(ual	in	Ň	bu	<u> </u>	2	ŝ
							0eC	gine	ble	elc sign	alys	der	ciet	/irol staii	<u>is</u>	ivi F	ш	ject	۲C	ò	ò	ò
Course Learn	ning Outcomes (CLO): At the end	of this course, learners will be	able to:		(Bld Exp	S TA	ЧŰ	Pro	De	Ana Re:	οM	Soc	Sus	Eth	bul Wo	Co	Pro	Life	- S	PS	PS
CLO-1 : An	alyze the underly	ng concepts of qua	pts of quality and quality control concepts of an organization				70%													1		
CLO-2 : Ev	aluate the various	quality manageme	ity management principles and good management practices				70%													1		
CLO-3 : Ev	aluate various too	Is of quality control	/ control				70%													1		
CLO-4 : An	Analyze the various quality management tools					3 80%	70%													1		
CLO-5 : An	5: Analyze the various standards applicable to healthcare globally and nationally				3 80%	70%		L														
CLO-6 : An	: Analyze the outcomes of implementing global standards					3 80%	70%			М	L	L									L	

		Introduction to quality	TQM principles	Statistical process control	TQM tools	Standards for medical devices
Duratio	n (hour)	9	9	9	9	9
S-1	SLO-1	Quality: Terminologies	Customer satisfaction – Customer Perception of Quality	The seven tools of quality	Benchmarking	Standards
	SLO-2	Dimensions of Quality	Customer Complaints	Cause-and-effect diagram	Reasons to Benchmark	Standards
6.2	SLO-1	Quality Planning	Service Quality	Check sheet	Benchmarking Process	Need for standards
3-2	SLO-2	Quality Planning	Customer Retention	Check sheet	Benchmarking Process	Need for standards
• •	SLO-1	Basic concepts of Total Quality Management	Employee Involvement	Control chart	Quality Function Deployment (QFD)	Types
5-3	SLO-2	Basic concepts of Total Quality Management	Employee Involvement	Control chart	Quality Function Deployment (QFD)	Types
S-4	SLO-1	Principles of TQM	Motivation	Histogram	House of Quality	Medical device safety
0-4	SLO-2	Principles of TQM	Motivation	Histogram	House of Quality	medical device quality management systems requirements
8.5	SLO-1	Leadership – Concepts	Empowerment	Pareto chart	QFD Process - Benefits	ISO 9000:2000 Quality System
3-3	SLO-2	Role of Senior Management	Empowerment	Pareto chart	QFD Process - Benefits	Clauses
5-6	SLO-1	Quality Council	Teams	Scatter diagram	Total Productive Maintenance (TPM) – Concept	FDA
3-0	SLO-2	Quality Statements	Teams	Scatter diagram	Total Productive Maintenance	Functions
S-7	SLO-1	Strategic Planning	Team Work	Stratification	Improvement Needs	ASTM International
5-1	SLO-2	Strategic Planning	Team Work	Stratification	Improvement Needs	Description
5.9	SLO-1	Strategic Planning	Recognition and Reward	Six sigma	FMEA	CE
3-0	SLO-2	Strategic Planning	Recognition and Reward	Six sigma	FMEA	CE marking
8.0	SLO-1	Barriers to TQM Implementation	Performance Appraisal	Six sigma	Stages of FMEA	IEC
3-9	SLO-2	Barriers to TQM Implementation	Performance Appraisal	Six sigma	Stages of FMEA	Specifications

Learning Resources		 Rose J.E, To Cesar A. Cac Greg Bounds 	tal Quality Manageme ere, Albert Zana,The , Beyond Total Qualit	ent, Kogan Page Lto Practise of clinical y Management-Tow	l., 1993 Engineering, Acade vard the emerging pa	mic Press,1997 aradigm, McGraw Hi	4. ill, 2013	Joseph J.Carr, Ele Jerrold T. Bushber	ements of Electronics g, John M. Boone, T	onics Instrumentation and Measurement, 2 nd ed., Pearson Education, 2003 ne, The essential physics of medical imaging, 3 rd ed., Lippincott Williams & Wilkins,				
Loarning Assoss	mont													
Learning Assess				Conti	nuous Learning Ass	essment (50% weig	htage)							
	Bloom's	CLA -	- 1 (10%)	CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			Final Examination (50% weightage)			
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice			
Level 1	Remember Understand	40 %	-	40 %	-	40 %	-	30 %	-	30%	-			
Level 2	Apply Analyze	- 40 %	-	40 %	-	40 %	-	40 %	-	40%	-			
Level 3	Evaluate Create	20 %	-	20 %	-	20 %	-	30 %	-	30%	-			
	Total	1	00 %	10	0 %	10	0 %	10	0 %		100 %			

 Create
 Control
Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldives	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1. Dr.D.Kathirvelu SRMIST

Course Code	18BMO126T	Course Name		Biomechanics of Human Movements		Course Category	0	Open Elective	L 3	Т 0	P 0	C 3
Pre-requisi	te			Co-requisite	Nil	Progressive	N#					
Courses			1	Courses	INII	Courses	INII					
Course Offer	ing Department	Biomedica	al Engineering		Data Book / Codes/Standards	Nil						

Course L	urse Learning Rationale (CLR): The purpose of learning this course is to:					Program Learning Outcomes (PLO)									-					
CLR-1 :	Identify essential anatomical	components of the musculoskeletal system.	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Get an idea about movemer	ts using standard anatomical terminology	(r	(
CLR-3 :	Identify key contributors to the	noc	%)	%)	ge		t						Ł		g					
CLR-4 :	Describe measurements use	ed in analysis of human movement.	(Blo	ncy	ent	lec		me		e				×		ano	5			
CLR-5 :	Identify causes and comper	sation mechanisms for pathological gait	ng	cie	E	٥ ک	SIS.	dole	gu'	lsa	ar			an	c	Ë	ці.			
CLR-6 :	Perform inverse dynamic an	inki	rofi	ttai	z	Jaly	eve	esi		Sult	nt 8 ity		Te	atio	∞ .:	ear				
			Th	ЧÞ	A b	ŝui	IAr	~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~	<u>م</u> ج	Ē	& C	mei		<u>a</u>	nic	Mgt	gГ			~
Course L	se Learning Outcomes (CLO): At the end of this course, learners will be able to:				Expecte	Enginee	Problem	Design	Analysis Researo	Modern	Society	Environ Sustain	Ethics	Individu	Commu	Project	Life Lon	PS0 - 1	PSO - 2	PSO - 3
CLO-1 :	Apply the common troubleshooting procedures in Electronic Equipment and Outline the testing procedures of active and passiv components				70	М	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-2 :	2: Analyze the faults in analog circuits and digital ICs				70	М	-	-	-	-	-	-	-	-	-	-	-	М	-	-
CLO-3 :	3: Identify the problems in common biomedical equipment in hospitals when it is not working and provide a suitable solution				70	-	М	-	-	-	-	-	-	-	-	-	-	М		-
CLO-4 :	4: Outline the importance of medical device classification based on the application and ISO standards				70	-	-	Н	-	-	-	-	-	-	-	-	М	-	М	-
CLO-5 :	-5 : Describe the Indian medical device regulatory system				70	-	-	-	-	-	-	-	-	-	-	-	М	-	-	-
CLO-6 :	6: Outline the job opportunities in regulatory affairs in India				70	-	-	-	-	-	-	-	-	-	-	-	L	-	-	-

Du	ration	Introduction to Biomechanics	Biomechanics of Human Movements	Joint Mobility	Measurement of Human Movement	Restoring and optimizing human movements
(h	our)	9		9	9	9
C 1	SLO-1	Under standing movement for réhabilitation	Structure of Protein filaments	Introduction to joint mobility	Linear Kinematics	Basic Principles of motor learning
5-1	SLO-2	Under standing movement for réhabilitation	The sarcomere anatomical details	Introduction to joint mobility	Angular Kinematics	Theories of skill learning
6.2	SLO-1	Force measurement	The difference between muscle force and muscle strength	Factors involved in assisting and restricting range of movements	Forces and movements	The balance theory model
3-2	SLO-2	Vector,scalar general introduction	Muscle work	Factors involved in assisting and restricting range of movements	Newton's First law of motion	The task environment
6.2	SLO-1	Drawing vectors ,point of application	Muscle strength	Normal range definition	Newton's second law of motion	The task design
5-5	SLO-2	Drawing vectors ,point of application.	Muscle fiber types	Normal range	Newton's third law of motion	The task design
64	SLO-1	The force of muscles working principle	Gradation of muscle force	Abnormal limitations	Full three dimensional motion capture	Gait of the child with cerebral palsy before and after surgery
3-4	SLO-2	Magnitude and direction of moments	Length-Tension relationship	Abnormal limitations	Full three dimensional motion capture	Gait of the child with cerebral palsy before and after surgery
S-5	SLO-1	Measuring force basic model	Active and passive tension measurement technique	Effects of decreased range of movements	Movement assessment systems	The sit to stand movement
0-0	SLO-2	Gravity	Force – Velocity relationship	Effects of decreased range of movements	Movement assessment systems	The sit to stand movement
.	SLO-1	Moments and posture	Angle of pull	Types of therapeutic movement of joints	Visual movement evaluation	Upper limb impairment after stroke
3-0	SLO-2	Moments and posture	Stability and sequencing	Types of therapeutic movement of joints	Linear Displacement	Upper limb impairment after stroke

6.7	SLO-1	Standing balance	Stability and sequencing	Passive movements	Angular Displament	Medical history and evaluation
3-1	SLO-2	Standing balance	Measuring muscle strength ,endurance	Passive movements	Body functions and structures	Medical history and evaluation
c 0	SLO-1	Force magnitude and change in motion	Measuring muscle strength ,endurance	Active movements	Case study 1:treadmill training	Motor impairment
3-0	SLO-2	Force magnitude and change in motion	Increased vascularization	Active movements	Case study 1:treadmill training	Motor impairment
S 0	SLO-1	Local and general stability	Increased strength	Normal joint constraint in an intact systems	Promoting physical activity to improve health	Functional limitations
3-9	SLO-2	Local and general stability	Increased endurance	Normal joint constraint in an intact systems	Promoting physical activity to improve health	Functional limitations

- 1. Basic Biomechanics of the Musculoskeletal System, Margareta Nordin and Victor Frankel
 - Lippincott Williams & Wilkins, 2001
- 2. Biomechanical Analysis of Fundamental Human Movements, Arthur Chapman First Edition

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- 3. Biomechanics and Motor Control of Human Movement, David Winter 17 September 2009,
 - 2009 John Wiley & Sons, Inc.

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Learning Assess	arning Assessment											
	Diaam'a			Conti	nuous Learning Ass	essment (50% weig	htage)				Final Examination (E0% weightage)	
	DIUUIII S	CLA –	1 (10%)	CLA –	2 (15%)	CLA –	3 (15%)	CLA – 4	4 (10%)#		Final Examination (50% weightage)	
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	
Lovel 1	Remember	10.9/		10.0/		10.9/		20.0/		200/		
Level I	Understand	40 %	-	40 %	-	40 %	-	30 %	-	30%	-	
Lovel 2	Apply	10 %		10 %		10 %		10 %		10%		
Level 2	Analyze	40 70	-	40 70	-	40 /0	-	40 70	-	4070		
Lovel 2	Evaluate	20.0/		20.0/		20.0/		20.0/		200/		
Level 3	Create	20 %	-	20 %	-	20 %	-	30 %	-	30%	-	
	Total	10	0 %	10	0 %	100	0 %	10	0 %		100 %	
		··· · ·										

CLA - 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldives	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1. G.Anitha, SRMIST