

ACADEMIC CURRICULA

UNDERGRADUATE DEGREE PROGRAMMES

Bachelor's Degree in Technology

(B.Tech - Four Years)

(Choice Based Flexible Credit System)

Regulations - 2018

Volume – 4

(Detailed Syllabus for Third & Fourth Year Courses)



SRM INSTITUTE OF SCIENCE AND TECHNOLOGY

(Deemed to be University u/s 3 of UGC Act, 1956)

Kattankulathur, Kancheepuram 603203, Tamil Nadu, India

Vision

*To emerge as a World - Class University
in creating and disseminating knowledge,
and providing students a unique learning
experience in Science, Technology, Medicine,
Management and other areas of scholarship
that will best serve the world and
betterment of mankind.*

Mission

MOVE UP through international alliances and collaborative initiatives to achieve global excellence.

ACCOMPLISH A PROCESS to advance knowledge in a rigorous academic and research environment.

ATTRACT AND BUILD PEOPLE in a rewarding and inspiring environment by fostering freedom, empowerment, creativity and innovation.

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7.198	18CSE484T	Deep Learning	816
7.199	18CSE485T	Robotics: Computational Motion Planning	818
7.200	18CSE486T	Advanced Algorithms	820
<i>Sub-stream-2: Big Data Analytics</i>			
7.201	18CSE355T	Data Mining and Analytics	822
7.202	18CSE391T	Big Data Tools and Techniques	824
7.203	18CSE392T	Machine Learning – I	826
7.204	18CSE393T	Text Mining	828
7.205	18CSE394T	Business Intelligence and Analytics	830
7.206	18CSE395T	Web Intelligence	832
7.207	18CSE396T	Data Science	834
7.208	18CSE487T	Data Warehousing and its Applications	836
7.209	18CSE488T	Functional Programming	838
7.210	18CSE489T	Streaming Analytics	840
7.211	18CSE490T	Big Data Visualization	842
7.212	18CSE491T	Machine Learning – II	844
<i>Sub-stream-3: Cloud Computing</i>			
7.213	18CSE341T	Communication Systems Engineering	846
7.214	18CSE342T	Digital Communication Systems	848
7.215	18CSE378T	Principles of Cloud Computing	850
7.216	18CSE377T	Data Centric Networks	852
7.217	18CSE343T	Web Application Development	854
7.218	18CSE344T	Cloud Architecture	856
7.219	18CSE441T	Cloud Application Development	858
7.220	18CSE442T	Cloud Security	860
7.221	18CSE443T	Big Data Analytics	862
7.222	18CSE444T	Cloud Strategy Planning and Management	864
<i>Sub-stream-4: Computer Networking</i>			
7.223	18CSE375T	Distributed Computing	866

7.224	18CSE376T	Optical Networks	868
7.225	18CSE379T	Internet of Things	870
7.226	18CSE380T	Pervasive Computing	872
<i>Sub-stream-5: Cyber Security</i>			
7.227	18CSE381T	Cryptography	874
7.228	18CSE382T	Forensics and Incident Response	876
7.229	18CSE383T	Information Assurance and Security	878
7.230	18CSE384T	Secure Software Development Life Cycle	880
7.231	18CSE385T	Security Audit and Risk Assessment	882
7.232	18CSE386T	Penetration Testing and Vulnerability Assessment	884
7.233	18CSE472T	Malware Analysis	886
7.234	18CSE474T	Cyber Law	888
7.235	18CSE475T	Mobile and Wireless Security	890
7.236	18CSE476T	Database Security	892
7.237	18CSE477T	Security Governance, Risk and compliance	894
7.238	18CSE478T	Operation System Security	896
<i>Sub-stream-6: Information Technology</i>			
7.239	18CSE361T	Web Programming	898
7.240	18CSE362T	Integrative Programming and Technology	900
7.241	18CSE364T	System Administration and Maintenance	902
7.242	18CSE365T	Fundamentals of Virtualization	904
7.243	18CSE366T	Human Computer Interaction	906
7.244	18CSE397T	Computational Data Analysis	908
7.245	18CSE461T	Internet Security and Cyber Forensics	910
7.246	18CSE462T	Data Centre Administration and Management	912
7.247	18CSE463T	IT Service Management and Operations	914
7.248	18CSE464T	Computer Graphics and Game programming	916
7.249	18CSE465T	Computational Media	918
<i>Sub-stream-7: Internet of Things</i>			
7.250	18CSE345T	IOT Architecture and Protocols	920
7.251	18CSE346T	Network Programming	922
7.252	18CSE445T	IOT Security	924
7.253	18CSE446T	Advanced Database Systems	926
7.254	18CSE447T	Edge Computing	928
7.255	18CSE448T	Energy Management for IOT devices	930
<i>Sub-stream-8: Software Engineering</i>			
7.256	18CSE367T	Requirements Engineering	932
7.257	18CSE368T	Software Architecture and Design	934
7.258	18CSE369T	Software Modeling and Analysis	936
7.259	18CSE370T	Design Patterns	938
7.260	18CSE371T	User Interface Design	940
7.261	18CSE372T	Visual Programming	942
7.262	18CSE373T	Programming in Java Script	944

7.263	18CSE374T	Software Engineering Tools	946
7.264	18CSE466T	Software Verification and Validation	948
7.265	18CSE467T	Software Quality Assurance	950
7.266	18CSE468T	Software Measurements and Metrics	952
7.267	18CSE469T	Software Process and Agile Practices	954
7.268	18CSE470T	Software Security	956
7.269	18CSE471T	Software Maintenance and Administration	958
	Electrical and Electronics Engineering		960
	<i>Sub-stream-1: Machines and Drives</i>		
7.270	18EEE301T	Optimization Techniques in Power Electronics	961
7.271	18EEE302T	Finite Element Analysis for Electrical Machines	963
7.272	18EEE303T	Power Converter Analysis and Design	965
7.273	18EEE304T	Switched Mode Power Conversion	967
7.274	18EEE305T	Design of Electrical Machines	969
7.275	18EEE306T	Special Electrical Machines	971
7.276	18EEE401T	Solid State Drives	973
7.277	18EEE402T	Modeling and Analysis of Electrical Machines	975
7.278	18EEE403T	Hybrid Electric Vehicles	977
	<i>Sub-stream-2: Sustainable Energy Sources</i>		
7.279	18EEE307T	Solar Photovoltaic System	979
7.280	18EEE308T	Energy Management System and SCADA	981
7.281	18EEE309T	Distributed Energy Resources	983
7.282	18EEE404T	Distributed Generation and Micro Grid	985
7.283	18EEE405T	Power Electronics in Renewable Energy System	987
7.284	18EEE406T	Wind and Solar Energy System	989
	<i>Sub-stream-3: Power System</i>		
7.285	18EEE310T	Energy Conservation and auditing	991
7.286	18EEE311T	Industrial Power System	993
7.287	18EEE312T	FACTS	995
7.288	18EEE313T	High Voltage Engineering	997
7.289	18EEE314T	Power Quality	999
7.290	18EEE315T	Smart Grid	1001
7.291	18EEE316T	Vehicular Power System	1003
7.292	18EEE407T	Power System Harmonics	1005
7.293	18EEE408T	HVDC and EHVAC Systems	1007
7.294	18EEE409T	Power System Dynamics	1009
7.295	18EEE410T	Modern Power System Analysis	1011
7.296	18EEE411T	Power System Deregulation	1013
	<i>Sub-stream-4: Control Systems and Robotics</i>		
7.297	18EEE317T	System Theory	1015
7.298	18EEE318T	Robust Control System	1017
7.299	18EEE319T	Fundamentals of Robotics	1019
7.300	18EEE320T	Signals and Systems	1021

7.301	18EEE412T	Advance Control Theory	1023
7.302	18EEE413T	Distributed Control Systems	1025
7.303	18EEE414T	Control System Design	1027
7.304	18EEE415T	Digital Control System	1029
<i>Sub-stream-5: Electronics</i>			
7.305	18EEE321T	Photonics	1031
7.306	18EEE322T	Principles of Biomedical Instrumentation	1033
7.307	18EEE323T	Automotive Electronics	1035
7.308	18EEE324T	Analog and digital Communication	1037
7.309	18EEE325T	Wavelet Transform	1039
7.310	18EEE326T	Advanced CMOS Devices and Technology	1041
7.311	18EEE327T	Sensors and Transducers	1043
7.312	18EEE416T	Medical Electronics	1045
7.313	18EEE417T	Advanced Semiconductor Devices	1047
7.314	18EEE418T	Mobile Communication	1049
7.315	18EEE419T	Satellite Communication	1051
7.316	18EEE420T	Embedded System	1053
7.317	18EEE421T	VLSI Design	1055
<i>Sub-stream-6: AI based Techniques</i>			
7.318	18EEE328T	Data Structures	1057
7.319	18EEE329T	Computer System Architecture	1059
7.320	18EEE330T	Computer Networking	1061
7.321	18EEE331T	Internet of Things	1063
7.322	18EEE332T	Principles of Object Oriented Programming	1065
7.323	18EEE422T	Modern Optimization Technique	1067
7.324	18EEE423T	Neuro Fuzzy and Genetics Programming	1069
7.325	18EEE424T	Artificial Intelligence	1071
7.326	18EEE425T	Fundamentals of Big Data Analytics	1073
7.327	18EEE426T	Fundamentals of Cloud Computing	1075
Electronics and Communication Engineering			1077
<i>Sub-stream-1: Electronic Systems Engineering</i>			
7.328	18ECE201J	Python and Scientific Python	1078
7.329	18ECE202T	Micro- and Nano-Fabrication Technologies	1080
7.330	18ECE204J	ARM based Embedded System Design	1082
7.331	18ECE205J	FPGA based Embedded System Design	1084
7.332	18ECE207J	Real Time Operating Systems	1086
7.333	18ECE301J	CMOS Analog IC Design	1088
7.334	18ECE302T	MEMS Technologies	1090
7.335	18ECE303T	Nanoelectronic Devices and Circuits	1092
7.336	18ECE304T	Microwave Integrated Circuits	1094
7.337	18ECE305J	Introduction to ARM-SoC	1096
7.338	18ECE306J	ARM based Digital Signal Processing	1098
7.339	18ECE307J	Applied Machine Learning	1100

<i>Sub-stream-2: Communication Systems Engineering</i>		
7.340	18ECE220T	Advanced Mobile Communication Systems 1102
7.341	18ECE221T	Radar and Navigational Aids 1104
7.342	18ECE223T	Satellite Communication and Broadcasting 1106
7.343	18ECE225T	Information Theory and Coding 1108
7.344	18ECE226T	Optical Components, Systems and Networks 1110
7.345	18ECE320T	Software Defined Networks 1112
7.346	18ECE322T	Opto Electronics 1114
7.347	18ECE323T	Advanced Optical Communication 1116
<i>Sub-stream-3: Signal Processing</i>		
7.348	18ECE243J	Digital Image and Video Processing 1118
7.349	18ECE244J	DSP System Design 1120
7.350	18ECE245T	Adaptive Signal Processing 1122
7.351	18ECE340T	Machine Perception with Cognition 1124
7.352	18ECE341T	Multimedia Compression Techniques 1126
7.353	18ECE342T	Acoustical Signal Processing 1128
7.354	18ECE343T	Automatic Speech Recognition 1130
<i>Sub-stream-4: Bio-Medical Engineering</i>		
7.355	18ECE360T	Rehabilitation Engineering 1132
7.356	18ECE361T	Biomedical Nanotechnology 1134
7.357	18ECE362T	Physiological Modelling and Simulation 1136
7.358	18ECE363J	Medical Image Processing 1138
7.359	18ECE364T	Body Area Networks and Mobile Health Care 1140
7.360	18ECE365T	Bio-inspired Human Machine Interface 1142
7.361	18ECE366T	Implantable Bioelectronics 1144
7.362	18ECE367T	Regulatory Affairs in Medical Instruments 1146
<i>Sub-stream-5: Instrumentation Engineering</i>		
7.363	18ECE280T	Industrial Instrumentation 1148
7.364	18ECE281J	Process Dynamics and Control 1150
7.365	18ECE282T	Modern Control System 1152
7.366	18ECE283J	Programmable Logic Controller 1154
7.367	18ECE284J	Graphical System Design in Virtual Instrumentation 1156
7.368	18ECE380T	Instrumentation and Control in Process Industries 1158
7.369	18ECE381T	Distributed Control System and SCADA 1160
7.370	18ECE382T	Building Automation 1162
7.371	18ECE383J	Instrumentation System Design 1164
7.372	18ECE384T	Factory Instrumentation Networks 1166
7.373	18ECE385T	IoT in Process Instrumentation and Automation 1168
7.374	18ECE386T	MEMS-based Microsystems Analysis and Design 1170
7.375	18ECE387T	Microsensors and Smart Devices 1172
Mechanical Engineering		1174
<i>Sub-stream-1: Design</i>		
7.376	18MEE301T	Fundamentals of Vibration and Noise 1175

7.377	18MEE302T	Industrial Tribology	1177
7.378	18MEE303T	Mechanism Design, Analysis and Synthesis	1179
7.379	18MEE304T	Design for Manufacturing and Assembly	1181
7.380	18MEE305T	Finite Element Methods	1183
7.381	18MEE306T	Advanced Strength of Materials	1185
7.382	18MEE307T	Automotive Engineering	1188
7.383	18MEE308T	Foundation Skills in Integrated Product Development	1190
7.384	18MEE309T	Modeling Systems	1192
7.385	18MEE310T	Human Body Mechanics	1194
7.386	18MEE401T	Design of Transmission Systems	1196
7.387	18MEE402T	Optimization in Engineering Design	1198
7.388	18MEE403T	Tool Engineering Design	1200
7.389	18MEE404T	Computer Graphics	1202
7.390	18MEE405T	Fatigue, Fracture Mechanics and CrECP	1204
7.391	18MEE406T	Linear Elasticity	1206
7.392	18MEE407T	Design of Pressure Vessel and Piping	1208
7.393	18MEE408T	Kinematics and Dynamics of Robots	1210
7.394	18MEE409T	Computer Applications in Design	1212
<i>Sub-stream-2: Manufacturing</i>			
7.395	18MEE321T	Elements of Mechatronics	1214
7.396	18MEE322T	Fluid Power Control	1216
7.397	18MEE323T	Process Planning and Cost Estimation	1218
7.398	18MEE324T	Foundry Engineering	1220
7.399	18MEE325T	Theory of Metal Forming	1222
7.400	18MEE326T	Welding Technology	1224
7.401	18MEE327T	Mechanical Handling Systems and Equipment	1226
7.402	18MEE328T	Non-Traditional Machining Techniques	1228
7.403	18MEE329T	Modern Manufacturing Techniques	1230
7.404	18MEE330T	Flexible Manufacturing Systems	1232
7.405	18MEE421T	Sustainable Green Manufacturing	1234
7.406	18MEE422T	Additive Manufacturing Technology	1236
7.407	18MEE423T	Precision Engineering	1238
7.408	18MEE424T	Technology of Surface Coating	1240
7.409	18MEE425T	Supply Chain Management	1242
7.410	18MEE426T	Composite Materials and Mechanics	1244
7.411	18MEE427T	Global Optimization Algorithms	1246
7.412	18MEE428T	Simulation of Mechanical Systems	1248
7.413	18MEE429T	Industry 4.0	1250
7.414	18MEE430T	TQM and Reliability Engineering	1252
7.415	18MEE431T	Design of Jigs, Fixtures and Press Tools	1254
<i>Sub-stream-3: Thermal</i>			
7.416	18MEE341T	Refrigeration and Air Conditioning Systems	1256
7.417	18MEE342T	Internal Combustion Engines	1258

7.418	18MEE343T	Elements of Space Technology	1260
7.419	18MEE344T	Energy Engineering and Management	1262
7.420	18MEE345T	Turbomachines	1264
7.421	18MEE346T	Thermal Power Systems	1266
7.422	18MEE347T	Solar Energy Systems	1268
7.423	18MEE348T	Gas Turbine Technology	1270
7.424	18MEE349T	Solar Energy Utilization	1272
7.425	18MEE350T	Gas Dynamics And Space Propulsion	1274
7.426	18MEE441T	Computational Fluid Dynamics	1276
7.427	18MEE442T	Advanced Engineering Thermodynamics	1278
7.428	18MEE443T	Advanced Fluid Mechanics	1280
7.429	18MEE444T	Design of Pumps and Turbines	1282
7.430	18MEE445T	Thermal Energy Storage Systems	1284
7.431	18MEE446T	Design of Heat Exchangers	1286
7.432	18MEE447T	Combustion Engineering	1288
7.433	18MEE448T	Sustainable Energy Systems	1290
7.434	18MEE449T	Fuel Cell Technology	1292
7.435	18MEE450T	Modeling of Thermal Systems	1294
<i>Sub-stream-4: Mechanical and Automation Engineering</i>			
7.436	18MEE701J	Sensors and Actuators for Automation	1296
7.437	18MEE702J	Microprocessor and Microcontrollers	1298
7.438	18MEE703T	Industrial Robotics and Automation	1300
7.439	18MEE704T	PLC and its Applications	1302
7.440	18MEE705T	Flexible Manufacturing System	1304
7.441	18MEE706T	IoT in Automation	1306
7.442	18MEE707T	Virtual Instrumentation	1308
7.443	18MEE708T	Neural Network and Fuzzy systems	1310
7.444	18MEE709T	Elements of Mechatronics	1312
<i>Sub-stream-5: Mechanical and Smart Manufacturing Engineering</i>			
7.445	18MEE801J	Artificial Intelligence and Machine Learning	1314
7.446	18MEE802T	Digital Image Processing and Machine Vision	1316
7.447	18MEE803J	Sensors for Intelligent Manufacturing	1318
7.448	18MEE804T	Industry 4.0	1320
7.449	18MEE805T	Manufacturing Execution Systems	1322
7.450	18MEE806T	Additive Manufacturing Technology	1324
7.451	18MEE807T	Industrial Robotics and Material Handling systems	1326
7.452	18MEE808T	Sustainable Green Manufacturing	1328
7.453	18MEE809J	Database Management System	1330
Mechatronics Engineering			1332
7.454	18MHE401T	Elements of Mechatronics Systems	1333
7.455	18MHE402T	Fundamentals of Robotics	1335
7.456	18MHE403T	Industrial Instrumentation and Control	1337
7.457	18MHE404T	Industrial Automation	1339

7.458	18MHE405T	Manufacturing Information Systems	1341
7.459	18MHE406T	Industrial Electronics	1343
7.460	18MHE407T	Geometric Modelling	1345
7.461	18MHE408T	Micro Electro Mechanical Systems	1347
7.462	18MHE409T	Automation and Intelligent Systems	1349
7.463	18MHE410T	Virtual Instrumentation	1351
7.464	18MHE411T	Machine Vision and Image Processing	1353
7.465	18MHE412T	Advanced Control Systems	1355
7.466	18MHE413T	Industrial Programmable Controllers	1357
7.467	18MHE414T	Special Electrical Machines	1359
7.468	18MHE415T	Digital Manufacturing	1361
7.469	18MHE416T	Process Control Engineering	1363
7.470	18MHE417T	Applied Mechatronics Systems	1365
7.471	18MHE418T	Real Time Embedded Systems	1367
7.472	18MHE419T	Intelligent Control System	1369
7.473	18MHE420T	Intelligent Mechatronics Systems	1371
7.474	18MHE421T	Autonomous Mobile Robotics	1373
7.475	18MHE422T	Condition Monitoring Techniques	1375
7.476	18MHE423T	FPGA Based System Design	1377
7.477	18MHE424T	Design and Analysis of Algorithms	1379
7.478	18MHE425T	Advanced Microcontrollers and Signal Processors	1381
7.479	18MHE426T	Robot Kinematics and Dynamics	1383
7.480	18MHE427T	Systems Engineering	1385
		<i>Sub-stream-1: Robotics</i>	
7.481	18MHE501T	Robotics	1387
7.482	18MHE502T	Mechanics of Manipulation	1389
7.483	18MHE503T	Mobile Robotics	1391
7.484	18MHE504T	Robot Control	1393
7.485	18MHE505T	Computer Vision and Its Applications	1395
7.486	18MHE506T	Advanced Computer Vision	1397
7.487	18MHE507T	Vision Guided Robotics	1399
7.488	18MHE508T	Advanced Robotics	1401
7.489	18MHE509T	Applied Robotics	1403
7.490	18MHE510T	Planning and Decision Making in Robotics	1405
7.491	18MHE511T	AI for Robotics and Vision	1407
7.492	18MHE512T	Systems Engineering and Management for Robotics	1409
		Nanotechnology	1411
7.493	18NTE301T	Carbon Nanotechnology	1412
7.494	18NTE302T	Physics of Solid State Devices	1414
7.495	18NTE303T	Molecular spectroscopy and its applications	1416
7.496	18NTE304T	Nanotribology	1418
7.497	18NTE305T	Nanotechnology Legal Aspects	1420
7.498	18NTE306T	Lithography Techniques and Fabrication	1422

7.499	18NTE307T	Sensors and Transducers	1424
7.500	18NTE308T	2D Layered Nanomaterials	1426
7.501	18NTE309T	Supramolecular Systems	1428
7.502	18NTE310T	MEMS and NEMS	1430
7.503	18NTE311T	Surface and Interfaces	1432
7.504	18NTE312T	Nano Technology in Food Production	1434
7.505	18NTE313T	Advanced Drug Delivery Systems	1436
7.506	18NTE314T	Nanomedicines	1438
7.507	18NTE315T	Microelectronics and VLSI	1440
7.508	18NTE316T	Physics of Electronic Materials	1442
7.509	18NTE317T	Nanocatalysts	1444
7.510	18NTE318T	Nano and Micro Emulsions	1446
7.511	18NTE401T	Nanorobotics	1448
7.512	18NTE402T	Micro and Nanofluids	1450
7.513	18NTE403T	Nanotechnology for Energy Systems	1452
7.514	18NTE404T	Photovoltaic technology	1454
7.515	18NTE405T	Nanotechnology in Cosmetics	1456
7.516	18NTE406T	Green Nanotechnology	1458
7.517	18NTE407T	Advanced Computational Techniques	1460
7.518	18NTE408T	Nanotechnology in Textiles	1462
7.519	18NTE409T	Cancer Nanotechnology	1464
7.520	18NTE410T	Vacuum and Thinfilm Technology	1466
7.521	18NTE411T	Atomistic Modeling	1468
7.522	18NTE412T	Societal Implications of Nanotechnology	1470
7.523	18NTE413T	Nanotechnology In Tissue Engineering	1472
7.524	18NTE414T	Nanomagnetism and Spintronics	1474
8	Project Work, Seminar, Internship in Industry / Higher Technical Institutions		1476
8.1	18ASP101L	MOOC-1	1477
8.2	18ASP104L	MOOC-2	1477
8.3	18AUP101L	MOOC-1	1477
8.4	18AUP104L	MOOC-2	1477
8.5	18BTP101L	MOOC-1	1477
8.6	18BTP104L	MOOC-2	1477
8.7	18CHP101L	MOOC-1	1477
8.8	18CHP104L	MOOC-2	1477
8.9	18CEP101L	MOOC-1	1477
8.10	18CEP104L	MOOC-2	1477
8.11	18CSP101L	MOOC-1	1477
8.12	18CSP104L	MOOC-2	1477
8.13	18EEP101L	MOOC-1	1477
8.14	18EEP104L	MOOC-2	1477
8.15	18ECP101L	MOOC-1	1477
8.16	18ECP104L	MOOC-2	1477

8.17	18MEP101L	MOOC-1	1477
8.18	18MEP104L	MOOC-2	1477
8.19	18MHP101L	MOOC-1	1477
8.20	18MHP104L	MOOC-2	1477
8.21	18NTP101L	MOOC-1	1477
8.22	18NTP104L	MOOC-2	1477
8.23	18ASP102L	Industrial Training-1	1478
8.24	18ASP105L	Industrial Training-2	1478
8.25	18AUP102L	Industrial Training-1	1478
8.26	18AUP105L	Industrial Training-2	1478
8.27	18BTP102L	Industrial Training-1	1478
8.28	18BTP105L	Industrial Training-2	1478
8.29	18CHP102L	Industrial Training-1	1478
8.30	18CHP105L	Industrial Training-2	1478
8.31	18CEP102L	Industrial Training-1	1478
8.32	18CEP105L	Industrial Training-2	1478
8.33	18CSP102L	Industrial Training-1	1478
8.34	18CSP105L	Industrial Training-2	1478
8.35	18EEP102L	Industrial Training-1	1478
8.36	18EEP105L	Industrial Training-2	1478
8.37	18ECP102L	Industrial Training-1	1478
8.38	18ECP105L	Industrial Training-2	1478
8.39	18MEP102L	Industrial Training-1	1478
8.40	18MEP105L	Industrial Training-2	1478
8.41	18MHP102L	Industrial Training-1	1478
8.42	18MHP105L	Industrial Training-2	1478
8.43	18NTP102L	Industrial Training-1	1478
8.44	18NTP105L	Industrial Training-2	1478
8.45	18ASP103L	Seminar-1	1479
8.46	18ASP106L	Seminar-2	1479
8.47	18AUP103L	Seminar-1	1479
8.48	18AUP106L	Seminar-2	1479
8.49	18BTP103L	Seminar-1	1479
8.50	18BTP106L	Seminar-2	1479
8.51	18CHP103L	Seminar-1	1479
8.52	18CHP106L	Seminar-2	1479
8.53	18CEP103L	Seminar-1	1479
8.54	18CEP106L	Seminar-2	1479
8.55	18CSP103L	Seminar-1	1479
8.56	18CSP106L	Seminar-2	1479
8.57	18EEP103L	Seminar-1	1479
8.58	18EEP106L	Seminar-2	1479
8.59	18ECP103L	Seminar-1	1479

8.60	18ECP106L	Seminar-2	1479
8.61	18MEP103L	Seminar-1	1479
8.62	18MEP106L	Seminar-2	1479
8.63	18MHP103L	Seminar-1	1479
8.64	18MHP106L	Seminar-2	1479
8.65	18NTP103L	Seminar-1	1479
8.66	18NTP106L	Seminar-2	1479
8.67	18ASP107L	Minor Project	1480
8.68	18AUP107L	Minor Project	1480
8.69	18BTP107L	Minor Project	1480
8.70	18CHP107L	Minor Project	1480
8.71	18CEP107L	Minor Project	1480
8.72	18CSP107L	Minor Project	1480
8.73	18EEP107L	Minor Project	1480
8.74	18ECP107L	Minor Project	1480
8.75	18MEP107L	Minor Project	1480
8.76	18MHP107L	Minor Project	1480
8.77	18NTP107L	Minor Project	1480
8.78	18ASP108L	Internship	1481
8.79	18AUP108L	Internship	1481
8.80	18BTP108L	Internship	1481
8.81	18CHP108L	Internship	1481
8.82	18CEP108L	Internship	1481
8.83	18CSP108L	Internship	1481
8.84	18EEP108L	Internship	1481
8.85	18ECP108L	Internship	1481
8.86	18MEP108L	Internship	1481
8.87	18MHP108L	Internship	1481
8.88	18NTP108L	Internship	1481
8.89	18ASP109L	Project	1482
8.90	18AUP109L	Project	1482
8.91	18BTP109L	Project	1482
8.92	18CHP109L	Project	1482
8.93	18CEP109L	Project	1482
8.94	18CSP109L	Project	1482
8.95	18EEP109L	Project	1482
8.96	18ECP109L	Project	1482
8.97	18MEP109L	Project	1482
8.98	18MHP109L	Project	1482
8.99	18NTP109L	Project	1482
8.100	18ASP110L	Semester Internship	1483
8.101	18AUP110L	Semester Internship	1483
8.102	18BTP110L	Semester Internship	1483

8.103	18CHP110L	Semester Internship	1483
8.104	18CEP110L	Semester Internship	1483
8.105	18CSP110L	Semester Internship	1483
8.106	18EEP110L	Semester Internship	1483
8.107	18ECP110L	Semester Internship	1483
8.108	18MEP110L	Semester Internship	1483
8.109	18MHP110L	Semester Internship	1483
8.110	18NTP110L	Semester Internship	1483

ACADEMIC CURRICULA

Humanities and Social Sciences
including Management Courses

Regulations - 2018



SRM INSTITUTE OF SCIENCE AND TECHNOLOGY

(Deemed to be University u/s 3 of UGC Act, 1956)

Kattankulathur, Kancheepuram, Tamil Nadu, India

Course Code	18PDH201T	Course Name	EMPLOYABILITY SKILLS AND PRACTICES	Course Category	H	Humanities and Social Sciences including Management	L	T	P	C
							0	0	2	1

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Career Development Centre	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:		Learning			Program Learning Outcomes (PLO)																	
CLR-1 :	identify problems	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2 :	recognize the logical coherence of ideas																							
CLR-3 :	understand the structure and principles of writing																							
CLR-4 :	interpret the structure, organization, tone, and main idea of the content																							
CLR-5 :	hone comprehension skills																							
CLR-6 :	give the right knowledge, skill and aptitude to face any competitive examination																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1 :	solve problems	3	80	75																				
CLO-2 :	grasp the approaches and strategies to find solutions	2	80	75																				
CLO-3 :	organize and articulate ideas clearly	2	80	75																				
CLO-4 :	analyze and evaluate contents critically in multifarious ways	2	80	75																				
CLO-5 :	understand, comprehend and provide logical conclusions	2	80	75																				
CLO-6 :	gain appropriate skills to succeed in preliminary selection process for recruitment	3	80	75																				

Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
L	H	-	M	-	-	-	-	M	L	-	H	-	-	-
L	H	-	M	-	-	-	-	M	L	-	H	-	-	-
L	H	-	M	-	-	-	-	M	L	-	H	-	-	-
L	H	-	M	-	-	-	-	M	L	-	H	-	-	-
L	H	-	M	-	-	-	-	M	H	-	H	-	-	-
L	H	-	M	-	-	-	-	M	H	-	H	-	-	-

Duration (hour)	6	6	6	6	6
S-1	SLO-1 Arithmetic Divisibility Rules	Algebra Quadratic Equation	Modern Mathematics - Permutation	Geometry II	Data Interpretation - II
	SLO-2 Arithmetic LCM HCF Factors	Problem Solving	Modern Mathematics - Combination	Problem Solving	Problem Solving
S-2	SLO-1 Sentence Correction	Video Profiling	Group Discussion - Introduction	Group Discussion – Mock IV	Interview Skills – Mock I
	SLO-2 Practice	Video Profiling	Group Discussion – Mock I	Group Discussion – Mock IV	Interview Skills – Mock I
S-3	SLO-1 Arithmetic Unit Digit, Squares	Commercial Mathematics - Profit and Loss	Modern Mathematics - Probability	Mensuration	Data Sufficiency- I
	SLO-2 Problem Solving	Problem Solving	Problem Solving	Problem Solving	Problem Solving
S-4	SLO-1 Para Jumbles	Critical Reasoning – Type I,II and III	Group Discussion – Mock II	Resume writing – Tips and Strategies	Interview Skills – Mock II
	SLO-2 Practice	Practice	Group Discussion – Mock II	Resume Writing - Evaluation	Interview Skills – Mock II
S-5	SLO-1 Algebra Introduction	Commercial Mathematics - Discount and Rebate	Geometry I	Data Interpretation I	Data Sufficiency - II
	SLO-2 Algebra Linear Equation	Problem Solving	Problem Solving	Problem Solving	Problem Solving
S-6	SLO-1 Reading Comprehension	Critical Reasoning – Type IV,V and VI	Group Discussion – Mock III	Interview Skills - Introduction	Revision
	SLO-2 Practice	Practice	Group Discussion – Mock III	Interview Skills - Introduction	Revision

Learning Resources	1. Dinesh Khattar-The Pearson Guide to QUANTITATIVE APTITUDE for competitive examinations. 2. Hari Mohan Prasad, Verbal Ability for Competitive Examinations, Tata McGraw Hill Publications 3. Edgar Thorpe, Test of Reasoning for Competitive Examinations, Tata McGraw Hill, 4th Edition, 2012 4. Norman Lewis, Word Power Made Easy, W.R. Goyal Publications, 2011 5. Joern Meissner, Manhattan Review, GRE Analytical Writing Guide, Manhattan Review Inc, 2011	6. GRE Analytical Writing, Solutions to the Real Essay Topics (Test Prep. Series), Vibrant Publishers, 2011 7. Wiley's GMAT Reading Comprehension Grail, Wiley, 2016 8. Manhattan Prep GRE : Reading Comprehension and Essays, 5th Edition 9. Archana Ram, Placementor, Oxford University Press, 2018 10. P.A.Anand, Quantitative Aptitude for Competitive Examinations, Wiley Publication, 2016
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	-	40%	-	30%	-	30%	-	30%	-	30%
	Understand	-	40%	-	30%	-	30%	-	30%	-	30%
Level 2	Apply	-	40%	-	40%	-	40%	-	40%	-	40%
	Analyze	-	40%	-	40%	-	40%	-	40%	-	40%
Level 3	Evaluate	-	20%	-	30%	-	30%	-	30%	-	30%
	Create	-	20%	-	30%	-	30%	-	30%	-	30%
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr Nishith Singh, dueNorth India Academics LLP, Dehradun, nsinha.alexander@gmail.com	1. Dr. A.K. Sheik Manzoor, Anna University, sheikmanzoor@annauniv.edu	1. Dr.P.Madhusoodhanan SRMIST
2. Mr Ajay Zenner, Career Launcher, ajay.z@careerlauncher.com	2. Dr. Devamainthan, University of Madras	2. Dr.M.Snehalatha SRMIST
3. Dr.Dinesh Khattar, Delhi University, dinesh.khattar31@gmail.com		3. Mr Jayapragash J SRMIST
4. Mr.Pratap Iyer, Study Abroad Mentors, Mumbai		4. Mr.A.Clement SRMIST

ACADEMIC CURRICULA

Basic Science Courses

Regulations - 2018



SRM INSTITUTE OF SCIENCE AND TECHNOLOGY

(Deemed to be University u/s 3 of UGC Act, 1956)

Kattankulathur, Kancheepuram, Tamil Nadu, India

Course Code	18MAB301T	Course Name	PROBABILITY AND STATISTICS FOR ENGINEERS	Course Category	B	Basic Sciences	L	T	P	C
							3	1	0	4

Pre-requisite Courses	18MAB201T/18MAB203T	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mathematics	Data Book / Codes/Standards	Statistical tables		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	To apply the basic rules and theorems of probability theory such as Baye's Theorem, to determine probabilities that help to solve engineering problems and to determine the expectation and variance of a random variable from its distribution.	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	To appropriately choose, define and/or derive probability distributions such as the Binomial, Poisson and Normal etc to model and solve engineering problems.		
CLR-3 :	To learn how to formulate and test hypotheses about means, variances and proportions and to draw conclusions based on the results of statistical tests.		
CLR-4 :	To understand how regression analysis can be used to develop an equation that estimates how two variables are related and how the analysis of variance procedure can be used to determine if means of more than two populations are equal.		
CLR-5 :	To comprehend the fundamentals of quality control and the methods used to control systems and processes.		
CLR-6 :	Acquired the knowledge of probability and statistics and its applications to the respective branches of Engineering.		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	
CLO-1 :	To Pertain the Knowledge of probability concepts, to determine probabilities that help to solve engineering problems. and to determine the expectation and variance of a random variable from its distribution	3 85 80	Engineering Knowledge
CLO-2 :	Gain familiarity in deriving probability distributions such as the Binomial, Poisson and Normal etc and apply them in the problems involving Science and Engineering	3 85 80	Problem Analysis
CLO-3 :	Acquire knowledge in formulating and testing hypotheses about means, variances and proportions	3 85 80	Design & Development
CLO-4 :	Getting the knowledge of Regression analysis, ANOVA and apply them in the problems in Science and Engineering	3 85 80	Analysis, Design, Research
CLO-5 :	Understanding the concept and applications of statistical quality control charts in technology and industries	3 85 80	Modern Tool Usage
CLO-6 :	To solve the problems based on probability and statistics in science and engineering	3 85 80	Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3

Duration (hour)	12	12	12	12	12
S-1	SLO-1 probability concepts, Types of Events	Discrete distributions	Sampling	Correlation and Properties	Introduction and Process Control
	SLO-2 Axioms and theorems	Binomial distribution	Small and large samples	Karl pearson's correlation coefficient	Types of Control charts
S-2	SLO-1 Conditional probability Baye's theorem – without proof	M.G.F	Hypothesis Testing	Spearman's rank correlation coefficient	Control charts for variables
	SLO-2 Applications- Baye's Theorem.	mean	Large sample test-Test of significance for single proportion	Problems on rank correlation –non repeated ranks	Control chart for attributes
S-3	SLO-1 Random variables – Discrete case	variance	Test of significance for difference of proportions	Problems on repeated ranks	Control limits and drawing conclusions
	SLO-2 Probability Mass function	Fitting binomial distribution	More problems on test 2	Linear Regression lines and Properties	Control chart for mean and range when \bar{X} and R data given directly
S-4	SLO-1 Problem solving using tutorial sheet 1	Problem solving using tutorial sheet 4	Problem solving using tutorial sheet 7	Problem solving using tutorial sheet 10	Problem solving using tutorial sheet 13
	SLO-2 Problem solving using tutorial sheet 1	Problem solving using tutorial sheet 4	Problem solving using tutorial sheet 7	Applications of correlation in engineering	Problem solving using tutorial sheet 14
S-5	SLO-1 Cumulative distribution function	Poisson distribution	Test of significance for single mean	regression coefficient Problems	More problems on \bar{X} and R data given directly
	SLO-2 Mathematical expectation –discrete case	M.G.F, mean	Test of significance for difference of means	More problems in regression coefficients	Control chart for mean and range- when \bar{X} and R data not given directly

S-6	SLO-1	Variance	variance	Small sample tests	Relation between correlation and regression	more problems on \bar{X} and R data not given directly
	SLO-2	Probability density function	Fitting Poisson distribution	Student's t- test for single mean	problems on relation between correlation and regression	Control chart for mean and S.D when mean S.D values given directly
S-7	SLO-1	Cumulative distribution function	Geometric distribution-M.G.F, mean, variance	't' test for the difference of means	Applications of regression in engineering	More problems on \bar{X} and S
	SLO-2	Mathematical expectation-continuous case	Memory less property	More problems on t- test	Applications of regression in engineering	Control chart for mean and S.D when mean S.D values not given directly
S-8	SLO-1	Problem solving using tutorial sheet 2	Problem solving using tutorial sheet 5	Problem solving using tutorial sheet 8	Problem solving using tutorial sheet 11	Problem solving using tutorial sheet 14
	SLO-2	Problem solving using tutorial sheet 2	Problem solving using tutorial sheet 5	Problem solving using tutorial sheet 8	Problem solving using tutorial sheet 11	Problem solving using tutorial sheet 14
S-9	SLO-1	Variance	Continuous distribution:	Fisher's F-test	Introduction to ANOVA Analysis of Variance – One way Classification	More problems on \bar{X} and S
	SLO-2	Raw Moments	Uniform distribution – MGF, Mean, Variance	Test of significance for two sample variances	Problems on one way classification	Control chart for attributes- np chart
S-10	SLO-1	Central Moments	Exponential distribution - MGF, Mean, Variance	Chi square test- for goodness of fit	More problems on one way classification	More problems on np-chart
	SLO-2	Moment generating function	Memory less property	Problems on goodness of fit	ANOVA – two way classification	p- chart
S-11	SLO-1	MGF- discrete random variable	Normal distribution	Chi square test- for independence of attributes	Problems on two way classification	More problems on p- chart
	SLO-2	MGF- continuous random variable	Problems on Normal distribution	More problems on Chi square test- for independence of attributes	More problems on two way classification	Control chart for the defects in a single unit- c- chart
S-12	SLO-1	Problem solving using tutorial sheet 3	Problem solving using tutorial sheet 6	Problem solving using tutorial sheet 9	Problem solving using tutorial sheet 12	Problem solving using tutorial sheet 15
	SLO-2	Applications of Probability and Random variables in Engineering field	Application of distributions in Engineering	Applications and the importance of sampling in various fields of engineering	Engineering Applications of ANOVA, Correlation and Regression	Engineering applications of control chart

Learning Resources	1. S. Ross, A First Course in Probability, 6th Ed., Pearson Education India, 2002.	4. Devore (JL), Probability and Statistics, 5 th Edition: For Engineering and the Sciences, 2000.
	2. Johnson. R.A., Miller &Freund's, Probability and Statistics for Engineers, 6 th Edition, Pearson's Education, New Delhi, 2000.	5. Vijay K. Rohatgi., A.K. Md. Ehsanes Saleh, An Introduction to Probability and Statistics, 2 Edition, Wiley, 2008
	3. Veerarajan T., Probability and Statistics, Tata McGraw-Hill, New Delhi, 2010.	

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.V.Maheshwaran, CTS, Chennai, maheshwaranv@yahoo.com	1. Dr.K.C.Sivakumar, IIT Madras, kcskumar@iitm.ac.in	1. Dr.A.Govindarajan, SRMIST
	2. Dr.Nanjundan, Bangalore University, nanzundan@gmail.com	2. Dr.Srinivasan, SRMIST

Course Code	18MAB302T	Course Name	DISCRTE MATHEMATICS FOR ENGINEERS				Course Category	B	Basic Sciences			L	T	P	C									
												3	1	0	4									
Pre-requisite Courses		18MAB102T		Co-requisite Courses		Nil		Progressive Courses		Nil														
Course Offering Department			Mathematics				Data Book / Codes/Standards																	
Course Learning Rationale (CLR):			The purpose of learning this course is to:				Learning			Program Learning Outcomes (PLO)														
CLR-1 :			Apply set theory, functions and relations in storage, communication and manipulation of data				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :			Apply number theory concepts in computer engineering such as public key crypto system.				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :			Apply mathematical reasoning in computer science such as design of computer circuit, verification of programs.																					
CLR-4 :			Learning about groups, rings and fields. Solving problems on coding theory.																					
CLR-5 :			Using graph models in computer network and shortest path problems Apply graph coloring in problems involving scheduling and assignments.																					
CLR-6 :			Apply mathematical reasoning, combinatorial analysis, algebraic structures and graph theory in solving mathematical problems as applied to the respective branches of Engineering.																					
Course Learning Outcomes (CLO):			At the end of this course, learners will be able to:																					
CLO-1 :			Problem solving in sets, relations and functions.				3	85	80	M	H	L					M	L		H				
CLO-2 :			Solving problems in basic counting principles, inclusion exclusion and number theory.				3	85	80	M	H		M	M				M		H				
CLO-3 :			Solving problems of mathematical logic, inference theory and mathematical induction.				3	85	80	M	H							M		H				
CLO-4 :			Gaining knowledge in groups, rings and fields. Solving problems in coding theory.				3	85	80	M	H		M					M		H				
CLO-5 :			Gaining knowledge in graphs and properties. Learning about trees, minimum spanning trees and graph coloring.				3	85	80	M	H	L						M	L	H				
CLO-6 :			Learning mathematical reasoning, combinatorial analysis, algebraic structures and graph theory.				3	85	80	M	H							M		H				
Duration (hour)		12		12		12		12		12		12												
S-1	SLO-1	Sets and examples. Operations on sets.	Permutation and Combination		Propositions and Logical operators		Binary operation on a set- Groups and axioms of groups.		Basic concepts - Basic Definitions- degree and Hand shaking theorem.															
	SLO-2	Laws of Set theory- Proving set identities using laws of set theory.	Simple problems using addition and product rules.		Truth values and truth tables.		Properties of groups.		Some Special Graphs – complete, regular and bipartite graphs.															
S-2	SLO-1	Partition of a set – examples.	Principle of inclusion and exclusion		Propositions generated by a set-Symbolic writing using conditional and biconditional connectives.		Permutation group, equivalence classes with addition modulo m and multiplication modulo m.		Isomorphism of graphs – necessary conditions.															
	SLO-2	Cartesian product of sets.	Problems using inclusion and exclusion principle.		Writing converse inverse and contra positive of a given conditional.		Cyclic groups and properties.		Isomorphism- simple examples.															
S-3	SLO-1	Relations – Properties.	Pigeon-hole principle and generalized pigeon-hole principle.		Tautology, contradiction and contingency-examples.		Subgroups and necessary and sufficiency of a subset to be a subgroup.		Paths, cycles and circuits.															
	SLO-2	Equivalence relation and partial order relation	Problems on pigeon-hole principle.		Proving tautology and contradiction using truth table method.		Group homomorphism and properties.		Connectivity in undirected graphs – connected graphs and odd degree vertices.															
S-4	SLO-1	Problem solving using tutorial sheet 1	Problem solving using tutorial sheet 4		Problem solving using tutorial sheet 7		Problem solving using tutorial sheet 10		Problem solving using tutorial sheet 13															
	SLO-2	Problem solving using tutorial sheet 1	Problem solving using tutorial sheet 4		Problem solving using tutorial sheet 7		Problem solving using tutorial sheet 10		Problem solving using tutorial sheet 13															
S-5	SLO-1	Poset - Graphs of relations Digraphs	Divisibility and prime numbers.		Equivalences – truth table method to prove equivalences.		Rings- definition and examples..Zero devisors.		Eulerian and Hamiltonian graphs.															
	SLO-2	Hasse diagram – problems.	Fundamental theorem of arithmetic – problems.		Implications- truth table method to prove implications.		Integral domain- definition , examples and properties.		Necessary and sufficient condition for a graph to be Eulerian- examples.															
S-6	SLO-1	Closures of relations- examples	Finding prime factorization of a given number.		Laws of logic and some equivalences.		Fields – definition, examples and properties.		Matrix representation of graphs- adjacent and incidence matrices and examples.															
	SLO-2	Transitive closure and warshall's algorithm	Some more problems using fundamental theorem of arithmetic.		Proving equivalences and implications using laws of logic.		Coding Theory – Encoders and decoders- Hamming codes.		Isomorphism using adjacency.															

S-7	SLO-1	Functions – definitions, domain and range of a function - examples	Division algorithm- greatest common divisor and properties-problems.	Rules of inference – Rule P, Rule T and Rule CP	Hamming distance. Error detected by an encoding function.	Digraphs – in degree and out degree – Hand shaking theorem.
	SLO-2	Types of functions- one- one and onto-bijection- examples.	Euclid's algorithm for finding GCD(a,b)- examples..	Direct proofs	examples.	Verification of hand shaking theorem in digraphs.
S-8	SLO-1	Problem solving using tutorial sheet 2	Problem solving using tutorial sheet 5	Problem solving using tutorial sheet 8	Problem solving using tutorial sheet 11	Problem solving using tutorial sheet 14
	SLO-2	Problem solving using tutorial sheet 2	Problem solving using tutorial sheet 5	Problem solving using tutorial sheet 8	Problem solving using tutorial sheet 11	Problem solving using tutorial sheet 14
S-9	SLO-1	Composition of functions – examples.	Problems using Euclid's algorithm.	Problems using direct method.	Error correction using matrices.	Graph colouring – chromatic number-examples.
	SLO-2	Associativity of composition of functions – Identity and inverse of functions.	Least common Multiple(LCM)- relation between LCM and GCD.	Problems using CP rule.	Problems on error correction using matrices.	Four colour theorem(statement only) and problems.
S-10	SLO-1	Necessary and sufficiency of existence of inverse of a function.	Problems on LCM.	Inconsistency and indirect method of proof.	Group codes-error correction in group codes-parity check matrix.	Trees – definitions and examples. Properties.
	SLO-2	Uniqueness of identity	Finding LCM and GCD using prime factorization.	Inconsistent premises and proof by contradiction (indirect method).	Problems on error correction in group codes.	Properties continued.
S-11	SLO-1	Inverse of composition	Finding GCD and LCM using Euclid's algorithm.	Principle of mathematical induction.	Procedure for decoding group codes.	Spanning trees – examples.
	SLO-2	Checking if a given function is bijection and if so, finding inverse, domain and range-problems.	More problems on GCD and LCM.	Problems based on Mathematical Induction	Problems on decoding group codes.	Kruskal's algorithm for minimum spanning trees.
S-12	SLO-1	Problem solving using tutorial sheet 3	Problem solving using tutorial sheet 6	Problem solving using tutorial sheet 9	Problem solving using tutorial sheet 12	Problem solving using tutorial sheet 15
	SLO-2	Applications of sets, relations and functions in Engineering.	Applications of sets, relations and functions in Engineering.	Applications of sets, relations and functions in Engineering.	Applications of sets, relations and functions in Engineering.	Applications of sets, relations and functions in Engineering.

Learning Resources	1. Kenneth H.Rosen, Discrete Mathematics and its Application, Seventh edition, Tata McGraw-Hill Publishing company PVT .Ltd., New Delhi, 2012.	3. Narsing Deo, Graph Theory with applications to Engineering and Computer science, Prentice-Hall of India Pvt. Ltd., New Delhi, 2004.
	2. Tremblay J. P. and Manohar R., Discrete Mathematical Structures with applications to Computer Science, Tata Mc Graw Hill Publishing Co., 35th edition,2008.	4. C.L. Liu, Elements of Discrete Mathematics, 4th Edition, McGraw Higher ED, 2012. 5. T.Veerarajan, Discrete Mathematics with Graph Theory and Combinatorics, Tata McGraw Hill, 2015.

Learning Assessment											
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		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

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Course Designers		
Experts from Industry		Experts from Higher Technical Institutions
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		2. Dr.Nanjundan, Bangalore University, nanzundan@gmail.com
		Internal Experts
		1. Dr.A.Govindarajan, SRMIST
		2. Dr.Sundarammal kesavan, SRMIST

Course Code	18MAB303T	Course Name	BIO STATISTICS FOR BIOTECHNOLOGISTS				Course Category	B	Basic Sciences				L	T	P	C								
													3	1	0	4								
Pre-requisite Courses		18MAB102T		Co-requisite Courses		Nil		Progressive Courses		Nil														
Course Offering Department		Mathematics				Data Book / Codes/Standards		Statistical tables																
Course Learning Rationale (CLR):		The purpose of learning this course is to:						Learning			Program Learning Outcomes (PLO)													
CLR-1 :	gain knowledge in measures of central tendency, dispersion, Skewness and moments in Biotechnology.						1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	appropriately choose, define and / or derive probability distributions such as Binomial, Poisson and Normal distributions to solve biology related problems.						Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	learn how to formulate and test the hypothesis of single means and difference of means for large samples and to understand and apply Chi-square test for goodness of fit and independence of attributes in Biological topics.																							
CLR-4 :	learn to formulate and test the hypothesis about means, variances for small samples using t and F test and to have knowledge in ANOVA in Biology related topics.																							
CLR-5 :	gain knowledge in correlation and regression lines and also get expose to Non- Parametric tests in Biology																							
CLR-6 :	Assess problems and determine the appropriate method to solve problems in application areas of Biotechnology																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1 :	Understand solve numerical problems in measures of central tendency and dispersion.						3	85	80	M	H	L						M	L		H			
CLO-2 :	Solving problems related to probability distributions applicable to bio technologists.						3	85	80	M	H		M	M				M			H			
CLO-3 :	Evaluate the given problems relating to large sample test of mean and difference of mean and Chi-square tests.						3	85	80	M	H							M			H			
CLO-4 :	Choose and solve problems with t test, F test and ANOVA.						3	85	80	M	H		M					M	L		H			
CLO-5 :	Evaluate problems on concepts of correlation, regression and non parametric tests.						3	85	80	M	H	L						M			H			
CLO-6 :	The learners will be able to mathematically formulate and solve numerical problems related to Biotechnogy.						3	85	80	M	H							M						
Duration (hour)		12		12		12			12			12			12									
S-1	SLO-1	Introduction to discrete types of statistical data	Introduction to probability concepts, Random experiment, Trail, Sample space, Sample size,			Sampling Theory - Basic concepts			Introduction to small sample test			Introduction to Correlation and Regression												
	SLO-2	Introduction to continuous types of statistical data	Events(only definitions, properties without proof and simple problems) Problems on Probability related to biological applications.			Population, Sample, Sampling distribution, population parameters and sample statistic			small sample tests based on t-distribution for single mean			Karl Pearson's coefficient of correlations												
S-2	SLO-1	Measures of central tendency – Introduction to Arithmetic mean, median, Mode	Types of Events: Impossible, Simple, Mutually Exclusive and Independent events(only definitions, properties without proof)			Testing of hypothesis, Null and Alternate hypothesis, Single tailed and two tailed tests, Type- I and Type – II errors			Problems on t-test for single mean			Problems on Karl Pearson's coefficient of correlations												
	SLO-2	Problems in Arithmetic mean	Simple problems			Acceptance and Rejection Regions, Level of Significance, Degrees of freedom and Confidence limits			Small sample tests based on t-distribution for difference of means			Spearman's rank correlation coefficient problems												
S-3	SLO-1	Problems in median	Problems based on Addition and Multiplication Theorems			Large sample tests based on normal distribution (Z - test)			Problems on t- distribution for difference of means			Spearman's rank correlation coefficient problems												
	SLO-2	Problems in mode	Baye's Theorem (without proof) and its applications			Z-Test for single proportion and difference of proportions and problems			Paired t-test			Regression lines and its applications												
S-4	SLO-1	Problem solving using tutorial sheet 1	Problem solving using tutorial sheet 4			Problem solving using tutorial sheet 7			Problem solving using tutorial sheet 10			Problem solving using tutorial sheet 13												
	SLO-2	Problem solving using tutorial sheet 1	Problem solving using tutorial sheet 4			Problem solving using tutorial sheet 7			Problem solving using tutorial sheet 10			Problem solving using tutorial sheet 13												
S-5	SLO-1	Measures of dispersion, Range , Quartile deviation	Introduction to one dimensional random variables			Z-Test for single mean			Problems on Paired t-test			Problems related to Regression lines.												
	SLO-2	Mean deviation	Discrete Random variable, Probability mass function , Distribution function, Properties (without proof), Applications			Problems on Z-Test for single mean			F-test for equality of variances			Non-parametric tests - The sign test												

S-6	SLO-1	Standard deviation and Co-efficient of variation	Continuous Random variable, Probability density function, Distribution function, Properties (without proof), Applications	Z-Test for difference of means	Problems on F-test for equality of variances	The sign test additional problems
	SLO-2	Problems on Standard deviation and Co-efficient of variation	Simple problems on discrete random variables and continuous random variables	Problems on Z-Test for difference of means	Problems on F-test for equality of variances	The Wilcoxon rank sum test or The Man Whitney U test problems
S-7	SLO-1	Karl Pearson's coefficient of Skewness	Mathematical Expectation	Introduction to Chi-square test	Introduction to Analysis of Variance (ANOVA)	The Wilcoxon rank sum test or The Man Whitney U test problems
	SLO-2	Problems on coefficient of Skewness	Variance, Properties (without proof), Application related problems	Chi-square test for goodness of fit	Problems on ANOVA –One-way classifications	The Kruskal Wallis test problems
S-8	SLO-1	Problem solving using tutorial sheet 2	Problem solving using tutorial sheet 5	Problem solving using tutorial sheet 8	Problem solving using tutorial sheet 11	Problem solving using tutorial sheet 14
	SLO-2	Problem solving using tutorial sheet 2	Problem solving using tutorial sheet 5	Problem solving using tutorial sheet 8	Problem solving using tutorial sheet 11	Problem solving using tutorial sheet 14
S-9	SLO-1	Introduction to moments	Binomial distribution, Application to population Genetics	Problems on Chi-square test for goodness of fit	Problems on ANOVA –One-way classifications	The Kruskal Wallis test problems
	SLO-2	Raw and Central moments problems	Simple problems on Binomial distribution	Chi-square test for Independence of attributes – Problems formulations	Problems on ANOVA –One-way classifications	The Kruskal Wallis test problems
S-10	SLO-1	Moments about the point $x=a$ problems.	Poisson Distribution, Application to population Genetics	Chi-square test for Independence of attributes using contingency table	ANOVA –Two-way classifications	The Wilcoxon signed ranked test problems
	SLO-2	Additional problems on moments	Normal Distribution, Application to population Genetics	Problems on Chi-square test for Independence of attributes using contingency table	Applications of ANOVA –Two-way classification problems.	The Wilcoxon signed ranked test problems
S-11	SLO-1	Problems on finding central moments given moments about a point	Problems on Poisson and Normal distribution	Additional problems on Chi-square test	ANOVA –Two-way classification problems.	Additional problems on all the non parametric tests
	SLO-2	Additional problems on finding central moments	Additional problems on Normal distribution.	Problems on Chi-square test.	ANOVA –Two-way classification problems	Additional problems on all the non parametric tests
S-12	SLO-1	Problem solving using tutorial sheet 3	Problem solving using tutorial sheet 6	Problem solving using tutorial sheet 9	Problem solving using tutorial sheet 12	Problem solving using tutorial sheet 15
	SLO-2	Engineering applications of Measures of central tendency and dispersion	Application of distributions in Engineering	Engineering applications of sampling techniques	Applications of ANOVA in engineering fields	Engineering Applications of Correlation, Regression and Non-parametric methods

Learning Resources	1. Myra L. Samuels, Jeffery A. Witner, Andrew schaffner, Statistics for the Life Sciences, Pearson, 5 th ed., 2015.	4. K. Kalyanaraman, Hareesh N.Ramanathan, P. N. Harikumar, Statistical methods for Research A step by step Approach Using IBM SPSS, Atlantic, First Edition, 2016.
	2. Bernard Rosner, Fundamentals of Biostatistics, Brooks/core, Seventh edition, 2011.	5. Gupta & Kapoor, Fundamentals of Mathematical Statistics, 10 th ed., Sultan Chand & Sons, 2017
	3. B K Mahajan, Methods in Bio-statistics for Medical students and Research workers, Seventh Edition, 2010.	

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.V.Maheshwaran, CTS, Chennai, maheshwaranv@yahoo.com	1. Dr.K.C.Sivakumar, IIT Madras, kcskumar@iitm.ac.in	1. Dr.A.Govindarajan, SRMIST
	2. Dr.Nanjundan, Bangalore University, nanzundan@gmail.com	2. Dr.Srinivasan, SRMIST

Course Code	18PYB201T	Course Name	WAVES AND OPTICS	Course Category	B	Basic Sciences	L	T	P	C
							3	1	0	4

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Physics and Nanotechnology	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1:	Familiarize with the concepts of simple harmonic motion	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2:	Analyze the principle of transverse and longitudinal wave-motion	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3:	Identify the significance of propagation of light	Expected Proficiency (%)	Problem Analysis
CLR-4:	Create insights to the concepts of interference and diffraction	Expected Attainment (%)	Design & Development
CLR-5:	Understanding the basics of geometrical optics		Analysis, Design, Research
CLR-6:	Understand the basics of lasers		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1:	Identify the problems regarding harmonic motion	2 85 75	H H - - - - - - - - - - - - - -
CLO-2:	Analyze the various types of wave motions	2 80 70	H - - - M - - - - - - - - - - - - - -
CLO-3:	Apply the principles of propagation of light	2 75 70	H H - - - - - - - - - - - - - - - -
CLO-4:	Utilize the concepts of interference and diffraction in applications	2 85 80	H H - - - - - - - - - - - - - - - -
CLO-5:	Apply the principles of geometrical optics	2 85 75	H - H - - - - - - - - - - - - - - -
CLO-6:	Utilizing the principles of laser in holography and microscopy	2 80 70	H - - - - - - - - - - - - - - - -

Duration (hour)	12	12	12	12	12
S-1	SLO-1	Simple harmonic motion – Basics	Transverse and longitudinal waves: Basics	Propagation of light	Superposition of waves
	SLO-2	Energy of a simple harmonic oscillator	Velocity in wave motion	Huygens' principle	Conditions for interference
S-2	SLO-1	Simple harmonic oscillations in an electrical system	Wave equation	Fermat's principle of stationary time	Interference – Constructive and Destructive
	SLO-2	Simple harmonic oscillations in a mechanical system -	Transverse wave on a string	Optical path length	Temporal coherence
S-3	SLO-1	Superposition of two simple harmonic vibrations in one dimension – vibrations having equal frequencies	Characteristic impedance of a string	Mirage effect	Spatial coherence
	SLO-2	Superposition of two simple harmonic vibrations in one dimension – vibrations having different frequencies	Reflection of waves at a boundary	Laws of reflection and refraction	Wave splitting Interference - Young's double slit experiment
S-4	SLO-1	Solving Problems	Solving Problems	Solving Problems	Solving Problems
	SLO-2	Solving Problems	Solving Problems	Solving Problems	Solving Problems
S-5	SLO-1	Damped simple harmonic motion	Transmission of waves at a boundary	Fresnel equations – Derivation	Amplitude splitting Interference
	SLO-2	Heavy damping	Impedance matching	Fresnel equations – Different cases	Newton's ring experiment
S-6	SLO-1	Critical damping	Normal modes and Eigen frequencies	Fresnel equation – Interpretation - Reflectance	Discussion of fringe formation in Newton's ring experiment

	SLO-2	Application of critical damping to a Ballistic galvanometer	Energy in normal mode of operation	Fresnel equation – Interpretation - Transmittance	Michelson's Interferometer- principle and construction	Excimer laser
S-7	SLO-1	Light damping	Longitudinal waves - wave equation	Total internal reflection	Michelson's Interferometer – formation of fringes	Chemical laser
	SLO-2	Methods of describing the damping of an oscillator	Sound waves in gases	Brewster's angle	Mach – Zehnder interferometer	X-Ray laser
S-8	SLO-1	Solving Problems	Solving Problems	Solving Problems	Solving Problems	Solving Problems
	SLO-2	Solving Problems	Solving Problems	Solving Problems	Solving Problems	Solving Problems
S-9	SLO-1	Energy decay in a damped harmonic oscillator	Energy distribution in sound waves	Evanescent waves	Diffraction	Free electron laser
	SLO-2	Quality factor of a damped harmonic oscillator	Longitudinal waves in a solid	Lenses – Refraction at a spherical surfaces	Fraunhofer diffraction from a single slit	Laser Speckles
S-10	SLO-1	Forced oscillator	Young's Modulus and Poisson's ratio	Refraction at spherical surfaces	Fraunhofer diffraction from a circular aperture	Q – Switching
	SLO-2	The impedance of a mechanical circuit	Application to earthquakes	Thin Lenses	Fraunhofer diffraction from a circular aperture – Quantitative approach	Mode Locking
S-11	SLO-1	Steady state motion of forced damped harmonic oscillator	Longitudinal waves in periodic structure	Thin Lenses - Equations	Diffraction grating	Applications of laser- Holography
	SLO-2	Forced oscillator - behavior	Reflection and transmission of sound waves at boundaries.	Quantum Electrodynamics (QED)	Resolving power of grating	Applications of lasers- Fluorescence microscopy, eye surgery
S-12	SLO-1	Solving Problems	Solving Problems	Solving Problems	Solving Problems	Solving Problems
	SLO-2	Solving Problems	Solving Problems	Solving Problems	Solving Problems	Solving Problems

Learning Resources	1. H.J. Pain, <i>The physics of vibrations and waves</i> , J.Wiley & Sons, 2010 2. Eugene Hecht, A.R. Ganesan, <i>Optics</i> , Pearson Education, 4 th Edition, 2008 3. O. Srelto, <i>Principles of Lasers</i> , Springer, 2010	4.Ajay Ghatak, <i>Optics</i> , Tata McGraw Hill Education, 5 th Edition, 2012 5. David Halliday, <i>Fundamentals of Physics</i> , 7 th Edition, John Wiley & Sons Australia, Ltd, 2004
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. Sameer Sharda, New Age Instruments & Materials Pvt. Ltd, Gurgaon, sameer@newagein.com	Prof .C.Vijayan, IITM, Chennai, cvijayan@iitm.ac.in	Dr. Junaid Masud Laskar, SRMIST
Mr. Mohammed Shafi, Holmarc Opto-Mechatronics Pvt. Ltd, Cochin, optics@holmarc.com	Prof . V. Subramanian, IITM, Chennai, manianvs@iitm.ac.in	Dr. P. Mohamed Ameen, SRMIST

ACADEMIC CURRICULA

Engineering Science Courses

Regulations - 2018



SRM INSTITUTE OF SCIENCE AND TECHNOLOGY

(Deemed to be University u/s 3 of UGC Act, 1956)

Kattankulathur, Kancheepuram, Tamil Nadu, India

Course Code	18CHS253L	Course Name	CHEMICAL ENGINEERING PRACTICE	Course Category	S	Engineering Sciences	L	T	P	C
							0	0	4	2

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Chemical Engineering	Data Book / Codes/Standards	Heat and Mass Transfer Data Book		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Understand various modes of heat transfer mechanism, Fourier's law of heat conduction and Newton's law of cooling.	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Understand difference between natural and forced convection heat transfer. Analyze LMTD for different flow patterns.	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Understand Stefan-Boltzmann law and gain knowledge on diffusivity and mass transfer coefficient.	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Gain knowledge on the mechanism of drying, batch and steam distillation.	Expected Attainment (%)	Design & Development
CLR-5 :	Analyze the difference between single and multi stage leaching.		Analysis, Design, Research
CLR-6 :	Provide students first hand experience of verifying various theoretical concepts learnt in Heat and Mass Transfer.		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Determine the thermal conductivity of a material.	2 80 75	H H H H
CLO-2 :	Determine heat transfer coefficient for natural, forced convection. Design double pipe and shell and tube heat exchanger.	2 80 70	H H H M
CLO-3 :	Determine the Stefan-Boltzmann constant, Diffusivity and mass transfer coefficient.	2 80 70	H H M M
CLO-4 :	Verify Rayleigh's equation for batch distillation and determine vapor efficiency for steam distillation	2 80 75	H H H H
CLO-5 :	Determine the percentage recovery of solute by leaching.	2 80 75	H H H H
CLO-6 :	Verify the governing relations for heat and mass transfer phenomena.	2 75 70	H H M M

Duration (hour)	12	12	12	12	12
S 1-4	SLO-1 SLO-2	Heat transfer through Composite wall	Heat transfer by forced convection	Stefan-Boltzmann apparatus	Drying characteristics
S 5-8	SLO-1 SLO-2	Heat transfer through Composite lagged pipe	Double pipe Heat Exchanger	Estimation of Diffusivity	Verification of Rayleigh equation for simple batch distillation
S 9-12	SLO-1 SLO-2	Heat transfer by natural convection	Shell and tube heat exchanger	Estimation of mass transfer coefficients	Determination of vapor efficiency for simple steam distillation
					Estimation of percentage recovery of solute for multi stage leaching

Learning Resources	1. Warren L. McCabe, Julian C. Smith and Peter Harriott, "Unit Operations of Chemical Engineering", 7th Edn., McGraw Hill Education (India) Edition, 2014 2. Robert E. Treybal, "Mass-Transfer Operations", 3rd Edn., McGraw Hill Education (India) Edition, 2012 3. Binay K Dutta, "Heat Transfer: Principles and Applications", PHI Publishers, Delhi, 2010 4. Laboratory Manual
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	-	40 %	-	30 %	-	30 %	-	30 %	-	30%
	Understand										
Level 2	Apply	-	40 %	-	40 %	-	40 %	-	40 %	-	40%
	Analyze										
Level 3	Evaluate	-	20 %	-	30 %	-	30 %	-	30 %	-	30%
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. A. Subramaniam, PESCO Beam Environmental Solutions Pvt. Ltd.,	1. Dr. Lima Rose Miranda, Anna University, email: limamiranda2007@gmail.com	1 Ms. E.POONGUZHALI SRM Inst. of Science & Technology, poonguzhali.e@ktr.srmuniv.ac.in
2. Mr. S. T. Kalaimani, CPCL, Chennai	2. Dr. T. R. Sundararaman, Rajalakshmi Engineering College	2 Dr. K.SOFIYA SRM Inst. of Science & Technology, sofiya.k@ktr.srmuniv.ac.in

ACADEMIC CURRICULA

Mandatory Courses

Regulations - 2018



SRM INSTITUTE OF SCIENCE AND TECHNOLOGY

(Deemed to be University u/s 3 of UGC Act, 1956)

Kattankulathur, Kancheepuram, Tamil Nadu, India

Course Code	18PDM301L	Course Name	ANALYTICAL AND LOGICAL THINKING SKILLS	Course Category	M	Mandatory	L	T	P	C
							0	0	2	0

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Career Development Centre	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 : Recapitulate fundamental mathematical concepts and skills		1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 : Sharpen logical reasoning through skillful conceptualization		Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 : Enable to solve problems and to crack competitive exams.		Expected Proficiency (%)	Problem Analysis
CLR-4 : understand and master the mathematical concepts to solve types of problem		Expected Attainment (%)	Design & Development
CLR-5 : identify problems			Analysis, Design, Research
CLR-6 : give the right knowledge, skill and aptitude to face any competitive examination			Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 : build a strong base in the fundamental mathematical concepts		1 80 75	L H M
CLO-2 : Apply the learn conditions towards solving problems analytically		1 80 75	L H M
CLO-3 : grasp the approaches and strategies to solve problems with speed and accuracy		2 80 75	L H M
CLO-4 : Collectively solve problems in teams and groups		2 80 75	L H M
CLO-5 : solve problems		1 80 75	L H M
CLO-6 : gain appropriate skills to succeed in preliminary selection process for recruitment		3 80 75	L H M

Duration (hour)	6	6	6	6	6
S-1	SLO-1 Arithmetic Progression	Clocks	Time, Speed, Distance	Geometry - Triangles	Data sufficiency Introduction
	SLO-2 Solving Problems	Solving Problems	Solving Problems	Geometry – Lines and Angles	Data sufficiency Type 1
S-2	SLO-1 Geometric Progressions	Calendar	Time, Speed, Distance-Races	Geometry - Circles	Data sufficiency Type 2
	SLO-2 Harmonic Progression	Solving Problems	Solving Problems	Solving Problems	Solving Problems
S-3	SLO-1 Averages	Ratio	Problems on Trains	Mensuration Area	Data Interpretation - Introduction
	SLO-2 Solving Problems	Proportion	Solving Problems	Solving Problems	Data Interpretation - Table
S-4	SLO-1 Weighted Averages	Variation	Boats & Streams	Mensuration – Volume and Surface Area	Data Interpretation - Pie Chart
	SLO-2 Solving Problems	Solving Problems	Solving Problems	Solving Problems	Data Interpretation - Line Graphs
S-5	SLO-1 Sets Two Variables	Mixtures & Solutions	Time and work	Trigonometry- Identities	Data Interpretation – Bar Graphs
	SLO-2 Sets Three Variables	Solving Problems	Solving Problems	Solving Problems	Solving Problems
S-6	SLO-1 Functions	Allegation Method	Pipes and Cisterns	Trigonometry - Height and Distances	Revision I
	SLO-2 Graphs	Solving Problems	Solving Problems	Solving Problems	Revision II

Learning Resources	1. Abhijit Guha, Quantitative Aptitude for Competitive Examinations, Tata McGraw Hill, 3 rd Edition, 2011 2. Arun Sharma-Quantitative aptitude for CAT, Tata McGraw Hill 3. Dinesh Khattar-The Pearson Guide to QUANTITATIVE APTITUDE for competitive examinations.	4. Edgar Thrope, Test of Reasoning for Competitive Examinations, Tata McGraw Hill, 4th Edition, 2012 5. Archana Ram, Placemator, Oxford University Press, 2018 6. P.A.Anand, Quantitative Aptitude for Competitive Examinations, Wiley Publication, 2016
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (100% weightage)								Final Examination	
		CLA – 1 (20%)		CLA – 2 (30%)		CLA – 3 (30%)		CLA – 4 (20%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	-	40%	-	30%	-	30%	-	30%	-	-
	Understand	-	40%	-	30%	-	30%	-	30%	-	-
Level 2	Apply	-	40%	-	40%	-	40%	-	40%	-	-
	Analyze	-	40%	-	40%	-	40%	-	40%	-	-
Level 3	Evaluate	-	20%	-	30%	-	30%	-	30%	-	-
	Create	-	20%	-	30%	-	30%	-	30%	-	-
	Total	100 %		100 %		100 %		100 %		-	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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3. Mr.Pratap Iyer, Study Abroad Mentors, Mumbai, pratap.iyer30@gmail.com		3. Mr Murali K SRMIST
		4. Mr.Harinarayana Rao SRMIST

Course Code	18PDM302L	Course Name	ENTREPRENEURSHIP MANAGEMENT	Course Category	M	Mandatory	L	T	P	C
							0	0	2	0

Pre-requisite Courses	Business Basics for Entrepreneurs	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Career Development Centre	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			
CLR-1 :	Provide the knowledge of Legal Systems and trains the students in application skills that enable students to understand the Law and Legal management concepts.				Level of Thinking (Bloom)	1	2	3
CLR-2 :	Comprehend and Practice Ethical Governance					Expected Proficiency (%)		
CLR-3 :	Understand different HRM concepts					Expected Attainment (%)		
CLR-4 :	Understand Project Management and its application							
CLR-5 :	Use the Project Management skills learnt in the entrepreneurial venture							
CLR-6 :	Acquire knowledge on validation and Launch of startup							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:						
CLO-1 :	Acquire knowledge about the Business law, legal procedures, Intellectual Properties and patents.				1	80	75	
CLO-2 :	Learn the role of government in supporting entrepreneurship to develop the society as well as the role of an entrepreneur as an individual with the government.				1	80	75	
CLO-3 :	Identify and be able to critically analyze the regulation of governance including that in national and international codes of practice, legislation, common law, norms of practice and ethics.				2	80	75	
CLO-4 :	Evaluate the effectiveness of HRM practices in supporting the strategic and operational needs of the startup.				2	80	75	
CLO-5 :	Adapt project management practices to meet the needs of stakeholders from multiple sectors of the economy.				3	80	75	
CLO-6 :	Apply project management practices to the launch of new programs, initiatives, products, services, and events relative to the needs of stakeholders.				3	80	75	
CLO-6 :	Implement project management knowledge, processes, lifecycle and the embodied concepts, tools and techniques in order to achieve project success.				3	80	75	

Program Learning Outcomes (PLO)														
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
L	H	-	M	-	-	-	-	M	L	-	H	-	-	-
L	H	-	M	-	-	-	-	M	L	-	H	-	-	-
L	H	-	M	-	-	-	-	M	L	-	H	-	-	-
L	H	-	M	-	-	-	-	M	H	-	H	-	-	-
L	H	-	M	-	-	-	-	M	H	-	H	-	-	-

Duration (hour)		Law and Legal Systems	Impact of Governance on ED	HRM	Entrepreneurial Project Management	Project Validation and Launch
		6	6	6	6	6
S-1	SLO-1	Introduction to Law and Legal Systems	Corporate Governance for Startups	HRM – Introduction and Overview	Project Management and Entrepreneurship -Introduction	Entrepreneur – Pitching the idea "Pitch Fest 01"
	SLO-2	Types of Laws and its Impact	Governance Structure and Practice	Role of HRM in entrepreneurship development	Project Management and Entrepreneurship – Concepts and Process	Entrepreneur – Pitching the idea "Pitch Fest 02"
S-2	SLO-1	Contractual Law	Government Programs	Functions of HRM	Project Management – Aims and Objectives	Entrepreneur – Pitching the idea "Pitch Fest 03"
	SLO-2	Dispute Resolution	Public Policy and its impact on Startups	Challenges of Performance and Appraisal in Startups	Review of Best Projects – Startup India	Entrepreneur – Pitching the idea "Pitch Fest 04"
S-3	SLO-1	Intellectual Property Rights - Introduction	Market and Institutional mechanisms in Governance	HRM - Models and Systems	Project Formulation – Concepts and Processed	Idea Valuation and Assessment 01
	SLO-2	Intellectual Property Rights - Types and Trademarks	Ethics in Governance	Cultures and Value system for startups	Importance and Implementation – Project Formulation	Idea Valuation and Assessment 02
S-4	SLO-1	Patent Law - Introduction	Measuring business performance	Employee Motivation	Entrepreneurial Project Process Life Cycle - Introduction	Project Creation and Setup
	SLO-2	Rules and Regulations for Patenting	Financial growth for Startups	Employee Engagement and Development	Entrepreneurial Project Process Life Cycle – Concepts and Methods	Project Validation and Assessment

S-5	SLO-1	Company Law and Regulations	Governance Model for Startups	HRM – Key challenges n strategies	Project Boundaries and Integration	Final Project Launch 01
	SLO-2	Types of Companies	Structuring Governance for your startup	Employee Safety and Security – HRM	Core Functionalities in Project Implementation	Final Project Launch 02
S-6	SLO-1	Business Incorporation – Startup India	Risk Management	Best HR practices for a startup	Stakeholder Management	Final Project Launch 03
	SLO-2	Make In India	Entrepreneurial Risks and its Impact	Review for Best Practises in Startup	Stakeholder Engagement and analysis	Final Project Launch 04

Learning Resources	www.wfnen.org ; National Entrepreneurship Network – Wadhvani Foundation https://www.forbes.com/sites/.../2017/...top-entrepreneur-stories-to-inspire-you-in-2017/ https://biztor.com/in/successful-indian-entrepreneurs-stories https://www.entrepreneur.com/article/299214 https://www.fundera.com/blog/young-entrepreneurs The Entrepreneurs: Success and Sacrifice - by Kip Marlow cbseacademic.nic.in/web_material/Curriculum19/Main.../20_Entrepreneurship.pdf	Elon Musk – Ashley Vance- Virgin Books-2015 Think and Grow Rich – Napoleon Hill - The Ralston Society – 1937 The Lean Startup – Eric Ries - Crown Publishing Group (USA) – 2011 The \$100 Startup – Chris Gullibeau - Crown Business- 2012 Creativity, Innovation, and Entrepreneurship: The Only Way to Renew Your Organization - H. James Harrington - Productivity Press- December 2018
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (100% weightage)								Final Examination	
		CLA – 1 (20%)		CLA – 2 (30%)		CLA – 3 (30%)		CLA – 4 (20%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	-	40%	-	30%	-	30%	-	30%	-	-
	Understand	-	40%	-	30%	-	30%	-	30%	-	-
Level 2	Apply	-	40%	-	40%	-	40%	-	40%	-	-
	Analyze	-	40%	-	40%	-	40%	-	40%	-	-
Level 3	Evaluate	-	20%	-	30%	-	30%	-	30%	-	-
	Create	-	20%	-	30%	-	30%	-	30%	-	-
	Total	100 %		100 %		100 %		100 %		-	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. Vijay Nayar, Director, Education Matters, vijayn@edumat.com	Mr. Ashok Kumar V – Professor, NITTE School Of Management Entrepreneurship Development, ashokkumarv2007@gmail.com	Dr. Shantanu Patil, Professor and Head of Department, Department of Translational Medicine and Research, Shantanu.s@ktr.srmuniv.ac.in
Mr. Ajay Zenner, Career Launcher, ajay.z@careerlauncher.com	Dr. A.K. Sheik Manzoor, Anna University, sheikmanzoor@annauniv.edu	Dr. Revathi Venkataraman, Professor, Department of Computer Science and Engineering, revathi.n@ktr.srmuniv.ac.in
		Mr. Ananth Kumar, Assistant Professor (Mgmt.) & Executive Secretary, psecy.director.et@srmuniv.ac.in
		Mrs. Deepa Narayanan Assistant Professor – CDC, deepa.na@ktr.srmuniv.ac.in

Course Code	18LEM110L	Course Name	INDIAN ART FORM	Course Category	M	Mandatory	L	T	P	C
							0	0	2	0

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	English and Foreign Languages			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Introduce the learners to the changing art forms in different periods of time: richness, variety and significance of various Indian art forms				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Enable the students to recognize and appreciate paintings of different schools prevalent in the different geographical locations				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Draw the learner's attention towards the various types of sculpture based on the materials used and the themes behind them																					
CLR-4 :	Cultivate a sense of appreciation about the aesthetics of drawing as an integral part of our daily life																					
CLR-5 :	Orient the learners about the changing Indian social scenario and the ways they are reflected in the changing facets of Modern Indian Art Forms																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	equip with an awareness of the rich cultural heritage of India				3	90	85	-	-	-	-	-	H	M	H	H	H	-	H	-	-	-
CLO-2 :	understand the contexts and significance of various Indian art forms				3	90	85	-	-	-	-	-	H	M	M	H	H	-	H	-	-	-
CLO-3 :	understand how the confluence of the diverse art forms of India create the mosaic of the Indian nation				3	90	85	-	-	-	-	-	H	M	H	H	H	-	H	-	-	-

Duration (hour)	Indian Art over Ages - An Overview		Indian painting	Indian sculpture	The Indian Art of Floor Decoration	Modern Art
S-1	SLO-1	Ancient India: An Overview	Indus Valley civilization paintings on pottery	Sculpture during the Harappan period	Kolam - the traditional floor drawing of South India	Nationalist School of Bengal Art- Introduction
	SLO-2	Raj-Ravi Verma: religious stories like mythologies of Hindu gods	Cave paintings from different parts of India	Terra Cota – What? Where? When? – A discussion	Daily life and Kolam - Line drawings, geometric designs and natural world - Some examples	Matching the picture with the artist
S-2	SLO-1	Mysore and Tanjore Art : included themes revolving around Hindu epics like Ramayana and Mahabharata	The paintings of the Ajanta and Ellora caves	Rock cut sculpture – Differences between rock cut sculpture and stone sculpture	Beliefs behind Kolam	Tracing the major ideas through paintings – Going back to Hindu themes
	SLO-2	Indian artists from different fields	Paintings of North India, South India, East India, West India, Central and Deccan India	Sculptures in religious buildings	Rangoli – Occasions and motifs	Student presentations on individual artists
S-3	SLO-1	Folk Art	Thanjavur, Madhubani paintings	Buddhism, Hinduism, and Jainism in sculptures	Kalamezhuthu in Kerala - Religious significance	Tracing the major ideas through paintings – Indian Village Life and nationalist themes
	SLO-2	Folk art and popular culture: classical and folk art	Analysing the recurrent themes style through selected illustrations	Visit to Mahabalipuram and submitting a report by the students	Mandana paintings of Rajasthan and Madhya Pradesh by oldest tribal communities	Student presentations on individual artists
S-4	SLO-1	Influential factors giving rise to modern art	Kalamkari paintings – Features of organic art; obtaining colours from natural sources	Bronze sculptures in India	Bengal's floor art-Alpona	European influences (British) – Trends in painting – portrait, landscape and realistic
	SLO-2	Concepts and Motifs behind modern art	Attempting simple Kalamkari/Madhubani paintings using natural colours	Cultural stonework in India - in the form of primitive cupule art	Festival specific Floor Art across India	Collection and display of paintings by various artists
S-5	SLO-1	Mughal paintings	Pattachitra paintings		Festival specific Floor Art across India	British Gothic and Indo Saracenic

				<i>the Buddhist Pillars of Ashoka of the Mauryan period</i>		<i>architecture through examples</i>
	SLO-2	<i>Astonishing contemporary paintings by Indian artists</i>	<i>Students presenting and sharing their paintings</i>	<i>The figurative Greco-Buddhist sculpture of the Gandhara and Mathura schools, and the Hindu art of the Gupta period: Brief Introduction</i>	<i>Pookalam: The Onam Floral Rangoli</i>	<i>Field trip to places in Chennai which have Indo Saracenic architecture and report submission</i>
S-6	SLO-1	<i>Fairs, festivals and local deities in the development of art forms</i>	<i>Moghal paintings</i>	<i>Khajuraho Temples in Madhya Pradesh</i>	<i>Body Art: Traditional Mehendi</i>	<i>Indian Art post-Independence Progressive Artists' Group and their Influence</i>
	SLO-2	<i>myth, legends, snippets from epic, multitudinous gods born out of dream and fantasy in art forms</i>	<i>Moghal paintings from the various Moghal dynasties and identification of the common features</i>	<i>Debate on "Religion and Art Today"</i>	<i>Mehendi designs, religious and cultural significances</i>	<i>Fusion of western style and Indian themes</i>

Learning Resources	1. Ketkar, Anil Rao Sandhya. <i>The History of Indian Art (Paperback)</i> . Jyotsna Prakashan, 2017. 2. Chaturvedi, P. N. <i>Encyclopedia of Indian Art and Architecture</i> . M. D. Publications Pvt. Ltd., 2009. 3. Gupta, S. P. <i>Elements of Indian Art: Including Temple Architecture, Iconography and Iconometry</i> . D. K. World Ltd., 2006 4. Goswamy, B. N. Ed. <i>Oxford Readings in Indian Art</i> . OUP, 2018. 5. https://courses.lumenlearning.com/boundless-arhistory/chapter/contemporary-indian-art/
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (100% weightage)								Final Examination	
		CLA – 1 (20%)		CLA – 2 (30%)		CLA – 3 (30%)		CLA – 4 (20%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	-	40%	-	30%	-	30%	-	30%	-	-
	Understand										
Level 2	Apply	-	40%	-	40%	-	40%	-	40%	-	-
	Analyze										
Level 3	Evaluate	-	20%	-	30%	-	30%	-	30%	-	-
	Create										
	Total	100 %		100 %		100 %		100 %		-	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts

Course Code	18LEM109T	Course Name	INDIAN TRADITIONAL KNOWLEDGE	Course Category	M	Mandatory	L	T	P	C
							1	0	0	1

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	English and Foreign Languages			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)															
CLR-1 :	Introduce the learners to the early and traditional environmental friendly agricultural practices				Level of Thinking (Bloom)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Enable the students to recognize and appreciate the contribution of India to astronomical studies					Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3	
CLR-3 :	Draw the learner's attention towards the holistic approach behind Indian system of medicine																						
CLR-4 :	Cultivate a sense of appreciation about ancient Indian Engineering and Technology as diverse, culture and resource specific																						
CLR-5 :	Develop an understanding about the connection of daily life to the environment and a healthy lifestyle through a comparison of the linguistic phrases and sayings and analyzing them from today's science																						
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																					
CLO-1 :	equip with an awareness of the ancient India's eco consciousness and India's contribution to astronomy and the beliefs associated with it				3	90	85	-	-	-	-	-	H	H	H	H	H	-	H	-	-	-	
CLO-2 :	appreciate the Indian aesthetic sensibility which is evidenced in the architectural monuments, economic life and religious worship				3	90	85	-	-	-	-	L	H	M	M	H	H	-	H	-	-	-	
CLO-3 :	understand how Indians have had a holistic approach towards human life integrating the body, mind and soul				3	90	85	-	-	-	-	-	H	H	H	H	H	-	H	-	-	-	

Duration (hour)		Agriculture	Mathematics & Astronomy	Medicine	Engineering & Technology	Customs, Sayings And Life Truths
S-1	SLO-1	Early agricultural settlements - Influencing Factors – locale and climate	Concepts of time and space - Knowledge of the Universe	Introduction to the school of Ayurveda, Siddha and Naturopathy:	Architecture – Temples, forts, palaces, houses and town planning	Regional myths, beliefs, and cultural practices
	SLO-2	Locating the early agricultural settlements in the Indian map and indicating the timeline	Quiz based on the Indian concept of time and distance between the planets	Compare and Contrast of the methodologies, popular beliefs, myths and truths about medications	Group Discussions through examples from different historical periods and geographical locations	Noting the idioms, proverbs in mother tongues connected to seasons and festivals
S-2	SLO-1	Crop cultivation - Community based Environment friendly practices	Great astronomers and mathematicians of ancient India	Common features - Holistic Therapeutic Approach – Natural elements, individual constitution (Humours), and the balance recommended	Metallurgy – Coins, Traditional Indian Metal Carvings	Traditional Foods of India in accordance with the climate and availability of the resources
	SLO-2	Group presentations on the traditional agricultural practices in selected states	The respective contributions of Astronomers and Mathematicians	Understanding the rationale behind selected sample treatments provided or advised, Case Studies	Discussions on historical periods and their architectural influences	Collecting old sayings in specific regions of India
S-3	SLO-1	Ancient Indian Water management and irrigation methods	The planetary system and Indian Astrology: Basic Facts	Yoga and its Universal Appeal	Textile technology – Region / Culture specific Fiber, Fabric and weaving	Translating Regional sayings into English
	SLO-2	A region based study of natural water resources and aquifers and types of irrigation	Discussion on a few sample birth charts and predictions made	Discussions on worldwide popularity of Yoga and meditation	Comparing the Temple Architecture of North and Southern Indian States	Traditional sayings about Hygiene and practices pertaining to them

Learning Resources	<ol style="list-style-type: none"> 1. V. Sivaramakrishnan (Ed.), <i>Cultural Heritage of India-course material</i>, Bharatiya Vidya Bhavan, Mumbai. 5th Edition, 2014. 2. Basham, A.L. ed. <i>A Cultural History of India</i>. OUP, 1997. 3. Thapar, Romila. <i>Indian Cultures as Heritage: Contemporary Past</i>. Aleph Book Company, 2018. 4. GN Jha (Eng. Trans.), Ed. RN Jha, <i>Yoga-darshanam with Vyasa Bhashya</i>, Vidyavidhi Prakashan, Delhi 2016.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (100% weightage)								Final Examination	
		CLA – 1 (20%)		CLA – 2 (30%)		CLA – 3 (30%)		CLA – 4 (20%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	-	40%	-	30%	-	30%	-	30%	-	-
	Understand	-	40%	-	30%	-	30%	-	30%	-	-
Level 2	Apply	-	40%	-	40%	-	40%	-	40%	-	-
	Analyze	-	40%	-	40%	-	40%	-	40%	-	-
Level 3	Evaluate	-	20%	-	30%	-	30%	-	30%	-	-
	Create	-	20%	-	30%	-	30%	-	30%	-	-
	Total	100 %		100 %		100 %		100 %		-	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts

Course Code	18BTM191T	Course Name	BIOETHICS AND IPR	Course Category	M	Mandatory Course	L	T	P	C
							1	0	0	0

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Biotechnology	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Realize the need for ethical values in Biotechnology Research	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Realize the need for ethical values in Health Care		
CLR-3 :	Apply biosafety rules and regulations in research		
CLR-4 :	Know the different forms of IPR		
CLR-5 :	Analyze the requirements for patentability of an invention or innovation		
CLR-6 :	Realize the need for conservation of Biodiversity and sustainable development		

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Comprehend ethical issues in Biotechnology Research	2	80	80	L	H	L			H	H	H	H	H	H	H	H	H	H
CLO-2 :	Comprehend ethical issues in Health Care	2	85	75	L	H	L			H	H	H	H	H	H	H	H	H	H
CLO-3 :	Learn Good Laboratory Practices	2	75	80	L	H	L			H	H	H	H	H	H	H	H	H	H
CLO-4 :	Understand different forms of IP	2	85	80	L	H	L			H	H	H	H	H	H	H	H	H	H
CLO-5 :	Predict the novelty and hence patentability of an invention	3	85	75	L	H	L			H	H	H	H	L	H	H	H	H	H
CLO-6 :	Shoulder ethical responsibility	2	80	80	L	H	L			H	H	H	H	H	H	H	H	H	H

Duration (hour)	3	3	3	3	3
S-1	SLO-1 Ethics and Bioethics	Health Systems and Institutions	Biosafety regulations	Forms of IPR	Patents and methods of application of patents-Legal implications
	SLO-2 Basic Principles of Bioethics	Global Health Ethics	Transgenic Research and Field Trials	Designs, Copyrights and Geographical indications	Objectives of the patent system
S-2	SLO-1 Ethical Theories	Ethical issues in Organ transplantation	Roles of various regulatory bodies	Basic principles and general requirements of patent law	TRIPs-GATT-International conventions
	SLO-2 Use of animals in research and Ethical issues in Clinical Trials	Biobanking	Biosafety Rules for GMOs	Novelty and Utility	Patent Cooperation Treaty
S-3	SLO-1 Ethical issues in Stem Cell Research	Ethical issues in Regenerative Medicine	Biodiversity and Environment conservation	Patentable subjects and protection in biotechnology	Plant variety protection and farmer rights.
	SLO-2 Ethical Issues in In vitro Fertilization	Religious and Cultural Perspectives in Bioethics I	CBD and Cartagena Protocol	Biodiversity	Other forms of IP

Learning Resources	1.Singer and Viens (Eds.) Bioethics – Cambridge University Press, Cambridge,2008 2. The Indian Patent Act and Rules, 2015,Gol, India .
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (100% weightage)								Final Examination	
		CLA – 1 (20%)		CLA – 2 (30%)		CLA – 3 (30%)		CLA – 4 (20%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	-	40%	-	30%	-	30%	-	30%	-	-
	Understand	-	40%	-	30%	-	30%	-	30%	-	-
Level 2	Apply	-	40%	-	40%	-	40%	-	40%	-	-
	Analyze	-	40%	-	40%	-	40%	-	40%	-	-
Level 3	Evaluate	-	20%	-	30%	-	30%	-	30%	-	-
	Create	-	20%	-	30%	-	30%	-	30%	-	-
	Total	100 %		100 %		100 %		100 %		-	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
<i>Dr. Bhanumathy, IPO, Guindy, Chennai, bhanumathir.ipo@nic.in</i>	<i>Prof. K Subramaniam, IITM, Chennai, subbu@iitm.ac.in</i>	<i>Dr.Sarada, DVL, SRMIST</i>
<i>Dr. Sharana Gowda, IPO, Guindy, Chennai, gouda.ipo@nic.in</i>	<i>Prof. R. B. Narayanan, SVCE, Chennai, rbn@svce.ac.in</i>	<i>Dr.Pandima Devi, SRMIST</i>

Course Code	18CEM401J	Course Name	PROFESSIONAL ENHANCEMENT I	Course Category	M	Mandatory Courses	L	T	P	C
							1	0	2	0

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Civil Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:		Learning			Program Learning Outcomes (PLO)															
CLR-1:	To introduce fundamentals of building design			Level of Thinking (Bloom)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Understanding architecture and suggest suitable structural scheme				Expected Proficiency (%)																	
CLR-3:	To impart understanding of integrated design concepts including other trades in building construction				Expected Attainment (%)																	
CLR-4:	To train manual design for RCC and steel structures.																					
CLR-5:	To train in using software and applications for designing RCC and Steel structures.																					
CLR-6:	Awareness to be created in 3dimensional modelling, analysis and design.																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1:	Identify various types of design for buildings			2	85	80																
CLO-2:	Analyze the architectural view and structural design concepts			3	85	75																
CLO-3:	Understand software and manual designs like beam, slab and column			3	85	75																
CLO-4:	Analyze the steel structure as per IS 800-2007			2	85	80																
CLO-5:	Understand about the steel design and its optimization			2	80	75																
CLO-6:	Understand about the 3D-7D planning.			3	85	75																

Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
H	H	-	-	-	-	-	-	-	-	-	-	H	H	-
H	H	-	-	-	-	-	-	-	-	-	-	H	H	-
H	H	-	-	-	-	-	-	-	-	-	-	H	H	-
H	H	-	-	-	-	-	-	-	-	-	-	H	H	-
H	H	-	-	-	-	-	-	-	-	-	-	H	H	-

Duration (hour)	6	6	6	6	6
S-1	SLO-1	Structural Engineering concepts	Aligning with architecture, suitable structural scheme to suite architectural plans.	Using equivalent systems in manual analysis and computer analysis.	Wind loading considerations Seismic loading considerations
	SLO-2		Usage of transfer girders, long spans, irregular building configurations. usage of masonry structures	Designing for architectural features, loading pattern and building typologies based on usage parameters	Steel optimization method in design
S-2	SLO-1	Practical : Overview of structural analysis of building	Practical: load combination as per IS codes for proportioning members	Practical : Reinforcement detailing for RC elements – columns and beams	Practical: Bar bending details and scheduling
S-3	SLO-1	Practical : Overview of structural design of building	Practical : checking of pre and post analysis in software	Practical : Reinforcement detailing for RC elements – slabs, staircases etc.	Practical : Performing steel structure design as per IS800- 2007
S-4	SLO-1	Classification of Structures	Loading definition and equivalent static methods . Using equivalent systems in manual analysis and computer analysis.	Manual design for slabs as per IS456 2000	Reinforcement ductile detailing as per IS 13920 - 2016
S-5	SLO-1	Practical : Load calculations of real buildings	Practical: Using software's for automated seismic and wind loading	Practical: Design of Beams and Columns using software	Practical :Seismic detailing practices
S-6	SLO-1	Practical : Load calculations of special structures like bridges as per IRC codes	Practical : Manual design for beams and columns as per IS456 2000	Practical: Using software's for slab modeling and analysis	Practical : Usage of Custom spreadsheets

Learning Resources	1. Varghese.P.C, "Limit State Design Of Reinforced Concrete", 2nd Ed, PHI Learning Pvt. Ltd., 2004 2. Francis .D.K Ching- "Architecture: Form Space & Order" Van Nostrand Reinhold, 1996 3. Subramanian.N, "Design of Steel Structures-Limit State Method", Oxford University Press, New Delhi, 2016.	4. https://www.bentley.com/en/products/brands/staad 5. https://www.csiamerica.com/products/etabs 6. https://www.csiamerica.com/products/sap2000 7. Prasanna Chandra, "Projects -Planning Analysis Selection Implementation & Review", Fourth Edition, Tata McGraw Hill Publishing Company Ltd., New Delhi.2005.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (100% weightage)								Final Examination	
		CLA – 1 (20%)		CLA – 2 (30%)		CLA – 3 (30%)		CLA – 4 (20%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	-	40%	-	30%	-	30%	-	30%	-	-
	Understand	-	40%	-	30%	-	30%	-	30%	-	-
Level 2	Apply	-	40%	-	40%	-	40%	-	40%	-	-
	Analyze	-	40%	-	40%	-	40%	-	40%	-	-
Level 3	Evaluate	-	20%	-	30%	-	30%	-	30%	-	-
	Create	-	20%	-	30%	-	30%	-	30%	-	-
	Total	100 %		100 %		100 %		100 %		-	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Er. AGV. Desigan, Design Group Engineering Consultancy Pvt Ltd. Chennai, desigan.agv@gmail.com	1. Dr. R. Santhakumar, Professor, Centre for Rural Department, NITTTR	Prof. G. Augustine Maniraj Pandian, SRMIST
2. Er. G. Hariharanath, GA Consultants, Chennai, gac1996@hotmail.com	2. Dr. P. Jayabalan, NIT, Trichy, pjeya@nitt.edu	Dr. K.S. Satyanarayanan, SRMIST

Course Code	18CEM402J	Course Name	PROFESSIONAL ENHANCEMENT COURSE II	Course Category	M	Mandatory Course	L	T	P	C
							1	0	0	0

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Civil Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Create insights into various post tensioning elements.	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Address concepts related to prefabricated buildings	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Analyze concepts of BIM, 3D printing and recent trends	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Address concepts related to LIDAR, UAV, SAR and its recent trends	Expected Attainment (%)	Design & Development
CLR-5 :	Create insights into Scatterometry and polarimetry applications		Analysis, Design, Research
CLR-6 :	Analyze concepts of soil strengthening and stabilization.		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Analyse Post tensioning sections and design of elements.	2 85 80	H H - - - - - - - - - - H H -
CLO-2 :	Understand Prefabricated structural buildings	2 85 75	H H - - - - - - - - - - H H -
CLO-3 :	Understand recent trends in BIM, Top down construction and sustainability in construction.	1 85 75	H H - - - - - - - - - - H H -
CLO-4 :	Analyse about waste management and environmental impact assessment.	2 85 80	H H - - - - - - - - - - H H -
CLO-5 :	Understand recent trends in SAR, LIDAR etc:	2 80 75	H H - - - - - - - - - - H H -
CLO-6 :	Analyze about the soil strengthening and recent trends in soil stabilization.	2 85 75	H H - - - - - - - - - - H H -

Duration (hour)	3	3	3	3	3
S-1 SLO-1	Structural Engineering – Post Tensioning	CEM : Top down construction,BIM,3D printing	Environmental impact assessment	Empherical and semi empherical modelling of SAR	Trends interferometry in land slide application and recent trends.
S-2 SLO-2	Prefabricated structural design	Safety and other recent trends, Sustainability in construction, OR in CEM	Hazardous waste management – rain harvesting.	ANN in optimization in SAR, Altimetry for ocean studies and geoidal modelling	Soil strengthening measures , Geosynthesis
S-3 SLO-3	Recent trends in structural engineering	Water resources and Environmental Engineering, Climate change and impacts	Remote sensing and GIS : LIDAR,UAV	Scatterometry and polarimetry applications and recent trends	Biotechnology , slope stabilization and other recent trends

Learning Resources	<ol style="list-style-type: none"> 1. Krishnaraju .N, "Prestressed Concrete", Tata McGraw-Hill Education, 2008, New Delhi 2. Laszlo Mokka, "Prefabricated Concrete for Industrial and Public Structures", Akademiai Kiado, Budapest, 2007. 3. Kumar NeerajJha, "Construction project management", Dorling Kindersley, New Delhi. 2013 4. "Decision making and operations research techniques for construction management". C.m.tam, thomask.l.tongh.zhang 5. Asawa .G.L, "Irrigation and Water Resources Engineering", New Age International Publishers, New Delhi, 2005 	<ol style="list-style-type: none"> 6. "Decision making and operations research techniques for construction management". C.m.tam, thomask.l.tongh.zhang 7. Charles J.Kibert, "Sustainable Construction: Green Buildings Design And Delivery", John Wiley & Sons, 2005 8. Paneerselvam .R "Environmental Engineering", Vol. I, SPGS Publishers Chennai, 2010 9. Anji Reddy .M, "Remote sensing and Geographical information system," B.S Publications 10. Terzaghi K., Peck R.B., Soil Mechanics in Engineering Practice, John Wiley Ltd., 1967
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (100% weightage)								Final Examination	
		CLA – 1 (20%)		CLA – 2 (30%)		CLA – 3 (30%)		CLA – 4 (20%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	-	40%	-	30%	-	30%	-	30%	-	-
	Understand										
Level 2	Apply	-	40%	-	40%	-	40%	-	40%	-	-
	Analyze										
Level 3	Evaluate	-	20%	-	30%	-	30%	-	30%	-	-
	Create										
	Total	100 %		100 %		100 %		100 %		-	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Er. AGV. Desigan, Design Group Engineering Consultancy Pvt Ltd. Chennai, desigan.agv@gmail.com	1. Dr. R. Santhakumar, Professor, Centre for Rural Department, NITTTR	1. Dr. K.S. Satyanarayanan, SRMIST
2. Er. G. Hariharanath, GA Consultants, Chennai, gac1996@hotmail.com	2. Dr. P. Jayabalan, NIT, Trichy, pjeya@nitt.edu	2. Mr. N. Parthasarathi, SRMIST

ACADEMIC CURRICULA

Open Elective Courses

Regulations - 2018



SRM INSTITUTE OF SCIENCE AND TECHNOLOGY

(Deemed to be University u/s 3 of UGC Act, 1956)

Kattankulathur, Kancheepuram, Tamil Nadu, India

Course Code	18AU0101T	Course Name	HYBRID AND ELECTRIC VEHICLES	Course Category	O	Open Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Provide an insight into how electric vehicle operate	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Demonstrate the functional requirements of Battery management system in detail.	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Demonstrate how Electric and Hybrid Vehicle vary as per design requirements.	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Perform the detailed analysis on the drives and driveline.	Expected Attainment (%)	Design & Development
CLR-5 :	Selection of the appropriate drive and driveline system for the different cases.		Analysis, Design, Research
			Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Learn the basic concepts of electric vehicle technology and electric vehicles.	2 90 85	H M L L L L M L M M H H H M
CLO-2 :	Develop and analyze hybrid and electric drive trains.	2 90 80	H H H H H L M H H H M M H H H
CLO-3 :	Interpret various vehicle power sources in hybrid vehicle technology	2 90 80	H M M M M L M H M H M H M M H
CLO-4 :	Analyze data to determine appropriate design calculations of hybrid system under study.	2 90 80	H H M H M L M H M H M M H M H
CLO-5 :	Apply the concepts in sizing the electric motors	2 90 80	H H M H H L L M H H M H H H M

Title	Electric Vehicle Propulsion and Energy Sources	Electric Vehicle Powerplant And Drives	Hybrid and Electric Drivetrains	Electric and Hybrid Vehicle Design	Electric And Hybrid Vehicles – Case Studies
Duration (hour)	9	9	9	9	9
S-1	SLO-1 Basic concepts and problems concerning the electrification in Mobility	Basic concepts of electric vehicle power plant	Functional requirements of Hybrid Vehicle	Design perspectives of Hybrid vehicle	Parallel Hybrid, Series Hybrid -Charge Sustaining
	SLO-2 Functional components in an electric and hybrid vehicle	Power and Torque plot		Power plant energy distribution	
S-2	SLO-1 Vehicle Mechanics - Kinetics	Construction of Induction Machines,	Operational difference between the Fully Electric, Hybrid and Mild Hybrid	Matching the Electric Machine and the Internal Combustion Engine	Parallel Hybrid, Series Hybrid –Charge Depleting
	SLO-2 Vehicle Mechanics – Dynamics & Roadway Fundamentals	Operating cycle and application in traction			
S-3	SLO-1 Propulsion System Design - Force Velocity Characteristics,	Construction of Permanent Magnet Machines	Topological Phenomena and Social Importance of e-mobility	Parameter optimization – IC Engine	Hybrid Vehicle Case Study –Toyota Prius
	SLO-2 Calculation Of Tractive Power And Energy Required	Construction of Switch Reluctance Machines		Position and Types of arrangements	
S-4	SLO-1 Electric Vehicle Power Source - Battery Capacity	Role of Power Electronic Converters- DC/DC Converters	Role of modern drivetrain and the conversion efficiency and power consumption	Parameter optimization – Motor	Hybrid Vehicle Case Study –Honda Insight
	SLO-2 Battery Construction and Types	Description of Buck Boost Converter		Position and Types of arrangements	
S-5	SLO-1 State of Charge and Discharge	Isolated DC/DC Converter	Description of Hybrid Traction	Sizing of Propulsion Motor	Hybrid Vehicle Case Study –Chevrolet Volt
	SLO-2	Functional Requirements and Operating limits		Power Electronics & Drive System	
S-6	SLO-1 Calculation of Specific Energy and Specific Power & Ragone Plot Relationship	Two Quadrant Chopper	Description of Electric Traction.	Selection of Energy Storage Technology	42 V System for Traction Applications
	SLO-2	Switching Modes		Topological Optimization	
S-7	SLO-1 Battery Modeling - Run Time Battery Model, First Principle Model	AC Drives- PWM	Topological Optimization for Hybrid Traction	Communications & Supporting Subsystem	Lightly Hybridized Vehicles and Low Voltage System

	SLO-2		Current Control Method	Topological Optimization for Electric Traction		
S-8	SLO-1	Battery Management System- SOC Measurement, Battery Cell Balancing.	Role of Switch Reluctance Machine Drives	Power Flow Control & Energy Efficiency Analysis	Energy Management Strategies in Hybrid Vehicles- Classification, Comparison, Implementation	Electric Vehicle Case Study - GM EV1, Nissan Leaf, Mitsubishi Miev
	SLO-2			Configuration and Control of DC Motor Drives		
S-9	SLO-1	Traction Batteries - Nickel Metal Hydride Battery, Li-Ion, Li-Polymer Battery.	Voltage Control	Induction Motor Drive.	Energy Management Strategies in Electric Vehicles- Classification, Comparison, Implementation	Hybrid Electric Heavy-Duty Vehicles, Fuel Cell Heavy Duty Vehicles
	SLO-2		Current Control	Permanent Magnet Motor Drives, Switch Reluctance Motor Drives, Drive System Efficiency.		

Learning Resources	1. Iqbal Husain, "Eclectic and Hybrid vehicles Design Fundamentals", CRC Press, second edition 2013, ISBN 9781439811757 2. James Larminie, John Lowry, "Electric vehicle technology Explained" second Edition, Wiley 2012, ISBN-13: 978-1119942733	3. Ali Emadi, "Hand book of Automotive Power Electronics and Motor Drives", CRC Press 2005, ISBN 9780824723613. 4. Ali Emadi, Mehrdad Ehsani, John M. Muller, "Vehicular Electric Power Systems" Marcel Dekker, Inc., 2004
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	60%		50%		40%		15%		50%	
	Understand										
Level 2	Apply	40%		50%		60%		20%		50%	
	Analyze										
Level 3	Evaluate	-		-		-		15%		-	
	Create										
	Total	100 %		100 %		100 %		100 %		100%	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.K.V. Simmon, Royal Enfield, kvsimmon1@royalenfield.com	1. Dr..A.Samuel Raja, Thiagarajar college of Engineering Madurai, samuel1973@tce.edu	1. Mr. Kaviyarasu T, SRMIST
2. Mr.R.Srikanth, Altair, srikanth.r@altair.com	2. Mr. N.Ravikumar, Crescent Institute of Science and Technology, ravikumar@crescent.education	2. Mr. Jerome Stanley M, SRMIST

Course Code	18AU0102T	Course Name	RENEWABLE SOURCES OF ENERGY	Course Category	O	Open Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Explain the concept of wind energy	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Create insight on solar energy and its application	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Evaluate the use of geothermal and hydro power for power generation	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Analyze the biomass energy and ocean energy	Expected Attainment (%)	Design & Development
CLR-5 :	Develop knowledge on various energy conversion devices		Analysis, Design, Research
			Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Apply the knowledge of using wind energy for power production	2 80 75	H L L M M H H L L M L H H H M
CLO-2 :	Analyze the economy of using solar power	2 85 80	H L L M M H H L L M L H H H M
CLO-3 :	Rationalize geothermal and hydro power plants	2 80 75	H M M M H H H L L M M L H M H M
CLO-4 :	Perceive the concept of biomass and ocean energy for power production	2 80 75	H L M M M H H L L M L H M M L
CLO-5 :	Demonstrate the working of various energy conversion devices	2 85 80	H L M M M H H L L M L H M M L

	Wind Energy	Solar Energy	Geo thermal and Hydro power	Ocean energy and Biomass based energy	Energy Conversions
Duration (hour)	9	9	9	9	9
S-1 SLO-1	Introduction- Renewable energy sources- statistics and technologies	Basic properties of solar energy	Geothermal – Resources, Types of wells	Ocean Energy – Principle, Utilization	Need for direct energy conversion (DEC), carnot cycle
S-2 SLO-1	Wind Energy - Introduction	Application of solar energy	Method of harnessing power and its potential in India	Setting of power plants	Limitations and principle of DEC
S-3 SLO-1	Application of wind energy	Transformation of solar energy	Hydropower – Properties and availability	Thermodynamic cycles	Thermo electric generators
S-4 SLO-1	Transformation of wind energy	Solar heat collectors	Transformation of water energy	Tidal and wave energy	Seebeck, peltier and joule Thompson effect and application
S-5 SLO-1	Wind Turbines	Solar photovoltaic collectors	Hydro power plants	Biomass - Principle of biomass conversion	Magneto hydrodynamic generator (MHD) – Working principle
S-6 SLO-1	Operating characteristics	Application of solar collectors	Applications of hydro power plants	Anaerobic/aerobic digestion	MHD accelerator, MHD engine
S-7 SLO-1	Wind power plant	Solar power plant	Special hydropower plants	Biogas digestors, gas yield and combustion characteristics	Electron gas dynamic conversion
S-8 SLO-1	Utilization of wind power	Economic study	Economic study	Utilization for cooking and economic aspects	Fuel cell – basic principle
S-9 SLO-1	Trends in wind energy utilization	Trends in solar energy utilization	Trends in hydro power utilization	Utilization in IC engine	Hybrid vehicle – Basic principle

Learning Resources	1. Boyle, Godfrey. 2004. <i>Renewable Energy (2nd edition)</i> . Oxford University Press.	2. Boyle, Godfrey, Bob Everett, and Janet Ramage (eds.) 2004. <i>Energy Systems and Sustainability: Power for a Sustainable Future</i> . Oxford University Press, 619 pages (ISBN: 0-19-926179-2)
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Sharath S Subramonian, McLanahan Corporation, ssharathi@mcclanahan.com	1.Dr.M.Arul Prakashajothi, Associate Professor, Mechanical Engineering, VelTech , Deemed to be university ,Email :arulprakashajothi@veltech.edu.in	1. Dr. S. Thiyagarajan, SRMIST
2. Mr. Ram Prasanth A, Caterpillar India Pvt Ltd, anjaneyulu_ram_p@cat.com	2.Dr.S.Natrajan, Assistant Professor(Senior Grade),Mechanical Engineering, Sri Venkateswara College of Engineering,Email: natraj@svce.ac.in	2. Dr. V. Edwin Geo, SRMIST

Course Code	18AU0103T	Course Name	SPECIAL TYPE OF VEHICLES	Course Category	O	Open Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:		Learning			Program Learning Outcomes (PLO)																	
CLR-1 :	Identify the special type of vehicles, their applications			Level of Thinking (Bloom)	2	3	1	2	3	Engineering Knowledge	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Define the principles and design considerations of farm equipments																							
CLR-3 :	Define and Classify earth moving equipments																							
CLR-4 :	Identify the special vehicles used in construction industry																							
CLR-5 :	Classify the special application vehicles																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:		Expected Proficiency (%)	Expected Attainment (%)																			
CLO-1 :	Acquire the knowledge of construction and operation of special type vehicle.			1,2	90	85	H	M	M	L	L	L	H	M	M	M	L	M	L	L	H	H	M	L
CLO-2 :	Understand the tractors operation principles and their types.			1,2	90	85	H	M	M	H	M	M	M	L	M	L	L	L	H	H	M	M	M	M
CLO-3 :	Know the fundamentals of earth moving machines and their types.			2	90	85	H	H	M	H	M	M	M	L	M	L	L	M	H	M	M	M	M	M
CLO-4 :	Applications of special type vehicles in construction industry for material handling.			3	85	80	H	H	M	H	M	M	M	L	M	L	L	M	H	M	M	M	M	M
CLO-5 :	Learn the basics of special application machines			2	85	80	H	H	M	H	M	M	M	L	M	L	L	H	H	M	L	M	L	M

		Off Road Equipments	Farm Equipments	Earth Moving Machines	Construction Equipments	Special purpose vehicles
Duration (hour)		9	9	9	9	9
S-1	SLO-1	Classification of Special Purpose Vehicles,	Classification of farm equipments	Introduction of Earth moving equipments	Scrapers - Introduction	Introduction to special application machines
	SLO-2	wheel type & track type, applications	Introduction to tractors	capacity and applications of earthmovers	Scrappers Constructional Details, Applications	Power Shovel – Introduction and types
S-2	SLO-1	Transport Equipment: Powered Equipment, Trolleys, - Constructional Details, Applications	lay out of wheeled tractor	Basic considerations for equipment selection	Scrappers and their types	Power Shovel- Constructional details and applications
	SLO-2	Trailers Constructional Details, Applications	Classification of tractors	Bulldozers- Constructional details and operations and applications	Graders- Introduction	Drag lines
S-3	SLO-1	Platform Lift Trucks Constructional Details, Applications	Wheeled Tractor - Constructional Details, Applications	Types of Bull dozers	Motor graders Constructional Details, Applications	Revolving shovels –constructional details and applications
	SLO-2	Fork Lift Trucks Constructional Details, Applications	Crawler Tractor - Constructional Details, Applications	Cable And Hydraulic Dozers	Classifications of Motor graders	Stripper Shovels - constructional details and applications
S-4	SLO-1	Containers And Supports.- Constructional Details, Applications	Recent Trends In Tractor Design	Running And Steering Gears	Bush Cutters - Introductions	Capacity Of Shovels
	SLO-2	Hauling Equipment: Types Of Dump Trucks, On-High Way Vehicles, Constructional Details, Applications	Power transmission system In Caterpillar Tractor. – Mechanism	Dump Traction- Introduction	Bush Cutters- Constructional Details, Applications	Ditchers - Introduction
S-5	SLO-1	Off High Way Vehicles Constructional Details, Applications.	Steering system	Dump Trucks and their types	Stumpers -Introduction	Ditchers - constructional details and applications
	SLO-2	Hoisting Equipment: Jacks, Truck Mounted Crane	Accessories of wheeled tractors	Rigid Dump Trucks Constructional Details,	Stumpers - Constructional Details, Applications	Articulated vehicles- constructional details and applications
S-6	SLO-1	Crawler Constructional Details, Applications	Hydraulic control system	Articulated Dump Trucks Constructional Details	Dozer- Introduction	Ambulance

	SLO-2	Crane Constructional Details, Applications	Power take off unit.	Loaders: Single Bucket Constructional Details, Applications	Dozer-- Constructional Details, Applications	fire extinguishing vehicle
S-7	SLO-1	Outriggers. - Constructional Details, Applications	Motor Grader: Recent Trends	Multi Bucket Constructional Details, Applications	Rippers -Constructional Details, Applications	Hover craft
	SLO-2	Vibratory compactors Constructional Details, Applications	Control Mechanism Of A Caterpillar Motor Grader	Skid steer loaders constructional details and applications	Dragline Excavator -Introduction	oil tankers
S-8	SLO-1	Human factors in special purpose vehicle	Ride and stability characteristics	Trenchers- Introduction	Dragline Excavator - Constructional Details, Applications	Introduction to tankers
	SLO-2	Safety features	Safety features in tractors	Trenchers-Principles and operations	Vibratory roller - introduction	Special features and constructional details of tankers
S-9	SLO-1	Regulatory requirements of special purpose vehicles	Human factors in tractor design	criteria for selection of prime mover for dumpers	Vibratory roller – Constructional details and applications	gun carriers - Introduction
	SLO-2	Economics of special purpose vehicle utilization	Procedure of testing and standard code for testing of tractor performance	criteria for selection of prime mover for front end loaders	Concrete mixer-- Constructional details and applications	gun carriers - constructional details

Learning Resources	1. Wong J, "Terramechanics and Off-Road Vehicle Engineering", Butterworth-Heinemann, 2009 2. "Off the Road Wheeled and Combined Traction Devices", - Ashgate Publishing Co. Ltd. 1998 3. Construction Equipment Management for Engineers, Estimators, and Owners, 1st Edition, CRC Press, 2006 4. Rodhiev and Rodhiev, "Tractors and Automobiles", MIR Publishers, Moscow, 1984.	5. Abrosimov. K. Bran berg.A. and Katayer.K, "Road making Machinery", MIR Publishers, Moscow, 1971. 6. RoviraMás, Francisco, Zhang, Qin, Hansen, Alan C, "Mechatronics and Intelligent Systems for Off-road Vehicles", Springer, 2011
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	40%	-	-	-	30 %	-	30	-
	Understand										
Level 2	Apply	40 %	-	20%	-	60%	-	40 %	-	40	-
	Analyze										
Level 3	Evaluate	20 %	-	20%	-	40%	-	30 %	-	30	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Ganeshkumar, Tafe, ganeshkumar@tafe.com	1. Dr. P.D. Jeyakumar, Crescent Institute of Science and Technology, pdjeyakumar@gmail.com	1.. Mr. N. Ganesh Kumar, SRMIST
2. Mr. K. V. Simmon, Royal Enfield, kvsimmon1@royalenfield.com	2. Dr. S. Ramkumar, Vel Tech, drsramkumar@veltech.edu	2. Mr. .S. Kiran, SRMIST

Course Code	18AU0104T	Course Name	FUEL CELLS AND APPLICATIONS	Course Category	O	Open Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)															
CLR-1 :	Impart knowledge on fuel cell technology and applications				Level of Thinking (Bloom)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Know the concept of electrochemistry in fuel cells					Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3	
CLR-3 :	Distinguish different types of fuel cells and operations																						
CLR-4 :	Inferring different hydrogen production techniques																						
CLR-5 :	Identify the application of fuel cells in power generation																						
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			1,2	90	85	H	M	H	H	H	M	M	L	M	M	L	M	H	H	H	
CLO-1 :	Understand the basics of fuel cell technology				1,2	90	85	H	M	H	H	H	L	L	L	M	M	L	M	H	H	H	
CLO-2 :	Infer the concepts of fuel cell electrochemistry				1,2	90	85	H	M	H	H	H	L	L	L	M	M	L	M	H	H	H	
CLO-3 :	Classify the major types of fuel cells and their modes of operation				1,2	90	80	H	M	H	H	H	L	L	L	M	M	L	L	H	H	H	
CLO-4 :	Categorize the methods of production, storage and utilization of hydrogen as a fuel				1,2	80	75	H	H	H	H	H	L	L	L	M	M	L	L	H	H	H	
CLO-5 :	Gain knowledge on application of fuel cells in power cogeneration				1,2	90	85	H	H	H	H	M	L	L	L	M	M	L	M	H	H	H	

		Introduction to fuel cells and fuel cell thermodynamics	Fuel cell electrochemistry	Types of fuel cells	Hydrogen production, storage and utilization	Application of fuel cells in power cogeneration
Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction and overview of fuel cell technology	Introduction to electrode kinetics.	Classification of fuel cells	Hydrogen : Its merit as a fuel,	Balance of fuel cell power plant,
	SLO-2	A simple fuel cell, fuel cell advantages and disadvantages	Introduction to electrode kinetics.	Polymer electrolyte membrane fuel cell (PEMFC)	Production methods: from fossil fuels, electrolysis, thermal decomposition,	Balance of fuel cell power plant,
S-2	SLO-1	Basic fuel cell operation,	Fuel cell reaction kinetics	Electrodes and Electrode Structure in PEMFC	Production methods: from fossil fuels, electrolysis, thermal decomposition,	Fuel cell power plant structure
	SLO-2	Layout of a Real Fuel Cell	Fuel cell reaction kinetics	Water Management in the PEMFC	photochemical, photocatalytic	Cogeneration
S-3	SLO-1	The Hydrogen–Oxygen Fuel Cell with Liquid Electrolyte.	Conversion of chemical energy to electricity in a fuel cell.	PEM Fuel Cell Cooling and Air Supply	Hybrid methods of hydrogen production	Fuel cell electric vehicles
	SLO-2	Difference between fuel cell and batteries, fuel choice	Conversion of chemical energy to electricity in a fuel cell.	Direct methanol fuel cells (DMFC)	Hydrogen storage methods:	Fuel cell in Motor cycles and bicycles, airplanes
S-4	SLO-1	Overview of types of fuel cells (with emphasis on PEMFC and DMFC technology)	Reaction rate of fuel cell	Anode, cathode Reaction and Catalysts in DMFC	Onboard hydrogen storage.	Case study: fuel cell vehicles with electric vehicles
	SLO-2	Fuel cell thermodynamics: Thermodynamics review	Reaction rate of fuel cell	Anode, cathode Reaction and Catalysts in DMFC	Chemical storage	Case study: fuel cell vehicles with electric vehicles
S-5	SLO-1	Application of first and second law to fuel cells	Butler -Volmer equation.	Methanol Production, Storage, and Safety	physical storage of hydrogen	Case study: different fuel cell powered Indian vehicles
	SLO-2	Heat Potential of a fuel	Butler -Volmer equation.	Methanol Production, Storage, and Safety	Storage in metal and alloy hydrides.	Case study: different fuel cell powered Indian vehicles
S-6	SLO-1	Enthalpy of reaction,	Fuel cell charge transfer	Alkaline fuel cell (PAFC)	Storage in metal and alloy hydrides.	Fueling stations
	SLO-2	Work potential of a fuel:	Fuel cell charge transfer	Types of Alkaline Electrolyte Fuel Cell	Carbon nanotubes	Fuel processor and fuel cell stack

S-7	SLO-1	Gibbs free energy	Mass transfer in fuel cells	Electrodes for Alkaline Electrolyte Fuel Cells	Carbon nanotubes	Water Management
	SLO-2	Predicting reversible voltage of a fuel cell under nonstandard-state conditions.	Mass transfer in fuel cells	Molten Carbonate fuel cell (MCFC)	Glass capillary arrays	Water Management
S-8	SLO-1	Basic Parameters of Fuel Cells.	Implications and use of fuel cell polarization curve	Molten Carbonate fuel cell (MCFC)	Glass capillary arrays	Thermal Management
	SLO-2	Fuel cell efficiency.	Implications and use of fuel cell polarization curve	Solid oxide fuel cell (SOFC)	pipeline storage	Thermal Management
S-9	SLO-1	Comparison with Carnot efficiency	Activation polarization, ohmic polarization	Comparison of fuel cell, Performance behavior	hydrogen utilization.	Safety issues and cost expectation
	SLO-2	Comparison with Carnot efficiency	Concentration Polarization, polarization losses	Comparison of fuel cell, Performance behavior	hydrogen utilization.	Safety issues and cost expectation

Learning Resources	1. O'Hayre, R. P., S. Cha, W. Colella, F. B. Prinz, "Fuel Cell Fundamentals", Wiley, 3 rd edition 2016	3. Bagotsky . V.S, "Fuel Cells", Wiley, 2009.
	2. Viswanathan. B, AuliceScibioh, M, "Fuel Cells – Principles and Applications", Universities Press (India) Pvt., Ltd., 2009.	4. DettlefStolten, "Hydrogen and Fuel Cells: Fundamentals, Technologies and Applications", 2011.

Learning Assessment

	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.T.R.Karthikeyan, TAFE, vasucar@gmail.com	1. Dr..A.Samuel Raja, Thiyagarajar college of Engineering Madurai, samuel1973@tce.edu	1. Dr.R.Rajendran, SRMIST
2. Mr.R.Srikanth, Altair, srikanth.r@altair.com	2. Mr. N.Ravikumar, Crescent Institute of Science and Technology, ravikumar@crescent.education	2. Mr.K.Devanathan, SRMIST

Course Code	18AUQ105T	Course Name	TRANSPORT MANAGEMENT	Course Category	O	Open Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	acquire knowledge about Motor Vehicle Act and Laws Governing Transport system	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	familiarize with Transport Taxation and Traffic controls.	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	know the various methods of fare charging and fleet management.	Expected Proficiency (%)	Problem Analysis
CLR-4 :	acquire knowledge in Goods Transport system and Bus scheduling	Expected Attainment (%)	Design & Development
CLR-5 :	familiarize with insurance policies and vehicle maintenance.		Analysis, Design, Research
			Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	.Able to understand and apply the Motor vehicle Act	1,2 90 85	H M H H H M M L M M L M H H H
CLO-2 :	Can able to get knowledge about ownership of vehicle and tax methods	1,2 90 85	H M H H H L L L M M L M H H H
CLO-3 :	Able to apply the knowledge about fleet management.	1,2 90 80	H M H H H L L L M M L L H H H
CLO-4 :	Thorough knowledge about various Goods vehicles and scheduling	1,2 80 75	H H H H H L L L M M L L H H H
CLO-5 :	Able to know the insurance claim and how to register accident case.	1,2 90 85	H H H H M L L L M M L M H H H

	Motor Vehicle Act	Transport systems and Taxation	Passenger Transport operation	Scheduling and Goods Transport operation	Vehicle Maintenance and insurance
Duration (hour)	9	9	9	9	9
S-1	SLO-1	Introduction – Motor Vehicle Act	Introduction – Transport systems and Taxation	Introduction – scheduling and Goods Transport operation	Introduction – vehicle Maintenance and insurance
	SLO-2	Traffic rules and signals – fitness certificate	various transport systems.	Scheduling - introduction	Preventive maintenance system in Transport industry
S-2	SLO-1	Registration of vehicle	Advantages of Motor Transport	Basic factors of Bus scheduling	Tyre maintenance procedure
	SLO-2	Permit insurance	Areas of improvement in Motor Transportation	Problems in Bus scheduling	Causes for uneven tyre wear
S-3	SLO-1	Constructional regulations of vehicles	Principal function of Administration	Structure of Goods transport organisation	Remedies for tyre wear
	SLO-2		Functions of Traffic and Engineering divisions	Scheduling of Goods transport Management information system(MIS)	Maintenance procedure for better fuel economy
S-4	SLO-1	Government administration structure – personal, Authorities.	Chain of responsibility	Storage of petroleum products	Design of Bus depot layout.
	SLO-2		Forms of ownership by state Government.	Transportation of petroleum products	Insurance types - significance
S-5	SLO-1	Responsibilities of Driver, public - offences	Public body undertakings	Description of Tipper, tanker, power wagons vehicles	Comprehensive insurance
	SLO-2	Accidents – causes and analysis – preventive measures			Third party insurance
S-6	SLO-1	State and interstate permits	Forms of ownership by municipality, private undertakings	Description of recovery vans, delivery vans.	Furnishing of particulars of vehicle involved in accident
	SLO-2	Test for competence to drive			MACT – hit and run case
S-7	SLO-1	Licensing of Drivers and conductors	Taxation - objectives	Advance technique in Traffic management	Solatum fund
	SLO-2				

S-8	SLO-1	Rules regarding construction of motor vehicles.	Structure of laving tax	Different rates for different type of service	Traffic navigation	Duty of Driver in case of accident.
	SLO-2		Methods of laving tax.	Principal features of operating cost		Surveyor and loss assessor
S-9	SLO-1	Laws Governing to use of Motor vehicle.	One time tax – Tax exemption	Operation cost - revenues	Global positioning system	Surveyor's report
	SLO-2		Tax renewal	Economics - records		

Learning Resources	1. "Motor vehicle Act" – Govt of India publications. 2. Shrivastava s k, "Transport Development in India", S Chand & co Pvt Ltd., New Delhi 3. John Duke, "Fleet Management", Mc Graw Hill, USA - 1984	4. Government Motor vehicle Act – Eastern Book Company, Lucknow – 1989 5. Kitchin. L. D – Bus operation – ILliffe and sons Co., London, 3 rd edition - 1992
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. K.N. Arun Prakash, Maruti Suzuki Pvt Ltd, knarunprakash@gmail.com	1. Dr.R.Elansezhian, Pondicherry Engineering College, elansezhianr@gmail.com	1. Dr.R.Rajendran, SRMIST,rajendr@srmist.edu.in
2. Mr.A.Venugopal, WABCO, venugopal.a@wabco-auo.com	2. Dr.T.R.Tamilarasan, Crescent Institute of Science and Technology, tamilarasanr@crescent.education	2. Mr. S. Palanisamy, SRMIST

Course Code	18AUQ106T	Course Name	COMPOSITE MATERIAL IN AUTOMOBILE APPLICATIONS	Course Category	O	Open Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Study matrix material, reinforcements of polymer matrix composites, metal and ceramic matrix composites.	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Understand the fundamentals of composite material strength and its mechanical behavior	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Develop knowledge on processing, interfacial properties and application of composites.	Expected Proficiency (%)	Problem Analysis
		Expected Attainment (%)	Design & Development
			Analysis, Design, Research
			Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Understand the basics of reinforcements and matrix material	1,2 90 85	H M H H H M M L M M L M H H H
CLO-2 :	Use of mathematical techniques to predict the macroscopic properties of different laminates	1,2 90 85	H M H H H L L L M M L M H H H
CLO-3 :	Choose suitable material to design composites	1,2 90 80	H M H H H L L L M M L L H H H
CLO-4 :	Select suitable manufacturing process for different types of composites	1,2 80 75	H H H H H L L L M M L L H H H
CLO-5 :	Compare/evaluate the relative merits of using various conventional and composite materials for important engineering and other applications.	1,2 90 85	H H H H M L L L M M L M H H H

	Introduction to composites	Polymer matrix composites	Metal matrix composites	Ceramic matrix composites	Advances in composites
Duration (hour)	9	9	9	9	9
S-1 SLO-1	Fundamentals of composites	Reinforcement material-Fibres	Metallic Matrix Matrix	Ceramic Matrix Material	Carbon /Carbon composites
SLO-2	Need for composites	Glass fibre, Carbon fibre-Processing	Selection of reinforcement	Failure Behavior of CMCs	Carbon Fiber Reinforcements
S-2 SLO-1	Classification of composites	Aramid fibre and Boron fibre-Processing	Processing of MMC	Toughening of CMCs	Matrix Systems-Thermosetting
SLO-2	Advantages of Composite	Properties and Application	Liquid state processes		
S-3 SLO-1	Disadvantage of Composite	Particle reinforcement	Stir Casting, Squeeze Casting	Processing of CMCs	Thermoplastic and Gaseous precursor
SLO-2	Properties of Composite:	Nano reinforcement	Slurry Casting, Melt Infiltration	Ceramic Particle Based Processes	
S-4 SLO-1	Particulate Composites	Polymer matrix material	Spray deposition	Cold Compaction	Processing of C/C Composites
SLO-2	Fibre reinforced Composite	Thermosetting resins, thermoplastic resins	Solid state processes	Slurry Impregnation	Thermosetting Resin Based Processing
S-5 SLO-1	Elastic Behavior under Longitudinal Loading,	Fillers-Additives	Powder Metallurgy technique	Sol-gel Processing	Thermoplastic Pitch Based Processing
SLO-2	Problems on Elastic Behavior under Longitudinal Loading,	Pre-Processed Material-Molding compound	Hot Pressing	Reaction Bonding Processes	Chemical Vapor Infiltration
S-6 SLO-1	Elastic Behavior under Transverse Loading	Prepegs-PMC processes	Diffusion Bonding	In Situ Ceramic Composite Processing	Properties of C/C Composites
SLO-2	Problems on Elastic Behavior under Transverse Loading	Hand layup, Spray up processes	Gaseous state processes	Melt Processing	Oxidation Protection of C/C composites

S-7	SLO-1	Longitudinal Tensile Strength	Compression molding, Injection molding	Deposition techniques	Polymer Infiltration and Pyrolysis	Application of C/C Composites
	SLO-2	Transverse Tensile Strength	Autoclave molding	Machining and joining of MMCs		Nanocomposites
S-8	SLO-1	Discontinuous Fiber Reinforced Composites	Resin transfer molding	Properties of MMCs	Properties of CMCs	Polymer Nanocomposites
	SLO-2		Pultrusion, Filament winding	Parameters affecting properties of MMC		Metal Nanocomposites
S-9	SLO-1	Applications of composite	Properties of PMCs	Interfacial Problems	Automotive Application of CMCs	Ceramic Nanocomposites
	SLO-2		Automotive Application of PMCs.	Automotive Application of MMCs.		Nanocomposites- Properties and Applications

Learning Resources	1. Krishnan K Chawla, <i>Composite Materials: Science and Engineering</i> , International Edition, Springer, 2012. 2. Mallick, P.K. and Newman.S, <i>Composite Materials Technology</i> , Hanser Publishers, 2003. 3. M. Balasubramanian, "Composite Materials and Processing", CRC press, Taylor and Francis Group, 2014.	4. Sanjay K Mazumdar, "Composites Manufacturing: Materials, Product and Process Engineering", CRC Press, New York, 2010. 5. ASM Handbook – Composites, Vol-21, 2001
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr S. Srinivasan, Ashok Leyland, srinchand@gmail.com	1. Dr.R.Elansezhian, Pondicherry Engineering College, elansezhianr@gmail.com	1. Dr.R.Rajendran, SRMIST, rajendrr@srmist.edu.in
2. Mr.A.Venugopal, WABCO, venugopal.a@wabco-auo.com	2. Dr.T.R.Tamilarasan, Crescent Institute of Science and Technology tamilarasanr@crescent.education	2.Dr. J.Chandradass, , SRMIST, chandraj@srmist.edu.in

Course Code	18AU0107T	Course Name	NON DESTRUCTIVE TESTING AND EVALUATION	Course Category	O	Open Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand the basic principle, importance and applications of various NDT techniques	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Acquire proper skills and equip with proper competencies to locate flaws in various materials and products.	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Equip themselves familiar with industrial applications																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Understand various Non Destructive Techniques to detect defects	1	90	90	H	M	L	M	H	M	M	M	H	M	L	M	H	M	M
CLO-2 :	Apply scientific and technical knowledge to the field of non-destructive testing	1,2	90	80	H	H	M	H	H	M	M	M	H	M	M	M	M	M	H
CLO-3 :	Use the relevant non-destructive testing methods for various engineering practice	1,2	85	85	H	H	H	H	H	M	M	M	H	M	M	M	H	M	H
CLO-4 :	Recognize and achieve high levels of professionalism in their work	1,2	90	80	H	H	M	M	M	H	M	H	M	M	M	M	M	M	M
CLO-5 :	Engage in lifelong learning, thought process and development	1,2	85	90	H	M	H	M	M	H	H	H	M	M	M	M	M	M	H

	Overview of NDT	Surface NDE Methods	Thermography and Eddy Current Testing	Ultrasonic Testing (UT) and Acoustic Emission	Radiography
Duration (hour)	09	09	09	09	09
S-1	SLO-1	Introduction to NDT	Principle of Thermography,	Ultrasonic Testing-Introduction, Basic	Radiography- Principle
	SLO-2		IR-radiation-Properties, Factors affecting Thermal measurements	Properties of sound beam, Acoustic Impedance	Electromagnetic radiation sources
S-2	SLO-1	Comparison of Destructive and Non Destructive Methods	Contact and non contact temperature sensors	Ultrasonic Transducers,	Radiation Attenuation and Effect of radiation on film
	SLO-2				
S-3	SLO-1	Overview of Non Destructive Testing Methods	Non Contact Thermography System	Inspection Methods-Transmission and pulse-echo method	Radiographic Imaging
	SLO-2				
S-4	SLO-1	Casting Defects	Advantages, Disadvantages and applications of Thermography	Inspection Methods- Angle beam pulse echo method	Inspection Techniques- Single wall and double wall penetration techniques
	SLO-2				
S-5	SLO-1	Welding Defects	Eddy Current Testing-Introduction and principle	Ultrasonic Flaw Detection Equipment, Mode of Display-A-Scan, B-scan, C-scan	Inspection Techniques-Multiwall penetration technique
	SLO-2				
S-6	SLO-1	Visual Testing-Principle and Tools	Factors affecting eddy current	Advantages, limitations and application of Ultrasonic testing method	Advantages, disadvantages and applications of radiography
	SLO-2				
S-7	SLO-1	Optical Aid used for Visual Inspection-Microscope, Rigid Borescope, Mini and Hybrid Borescope	Instrumentation of eddy current testing	Acoustic Emission Testing-Principle and Technique	Real time Radiography-Microfocal Radiography

	SLO-2					
S-8	SLO-1	Optical Aid used for Visual Inspection-Extendable borescope, Flexible borescope, Endoscope, Telescope and Holography	Residual Magnetism.	Types of probes	Instrumentation of Acoustic Emission Testing	Advantages and limitations of Microfocal Radiography
	SLO-2					
S-9	SLO-1	Merits and Demerits of Visual Testing	Demagnetization-Method of Demagnetization	Advantages, Limitations and application of eddy current testing	Applications	Xero Radiography
	SLO-2					

Learning Resources	<ol style="list-style-type: none"> 1. Baldev Raj, T.Jayakumar, M.Thavasimuthu "Practical Non-Destructive Testing", Narosa Publishing, 3rd Edition, 2014 2. Ravi Prakash, "Non-Destructive Testing Techniques", 1st revised edition, New Age International Publishers, 2010 3. ASM Metals Handbook, "Non-Destructive Evaluation and Quality Control", American Society of Metals, Park, Ohio, USA, 200, Volume-1, 2018.. 	<ol style="list-style-type: none"> 4. Paul E Mix, "Introduction to Non-destructive testing: a training guide", Wiley, 2nd Edition New Jersey, 2005 5. Charles, J. Hellier, "Handbook of Nondestructive evaluation", McGraw Hill, New York, 2nd Edition, 2013.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.C.Subash, Mahindra and Mahindra, SUBASH.C@mahindra.com	1. Dr.P.Jawahar, Assistant Professor, NIT Agartala, drjawahar.me@nita.ac.in	1. Dr. J. Chandradass, SRMIST, chandraj@srmist.edu.in
2. Mr. R. Silambarasan, RNTBCI, silambarasan.ramadoss@rntbci.com	2. Dr. D. Muruganandham, SVC of Tech, svctvp@gmail.com	2.Mr. P. BaskaraSethupathi, SRMIST, sethupab@srmist.edu.in

Course Code	18AUQ108T	Course Name	ADVANCED ENGINE TECHNOLOGY	Course Category	O	Open Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1	Explore the sustainable development, energy conservation, efficiency and environmental preservation.	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Provide a comprehensive reference to understand the current trends in Advanced engines	Level of Thinking (Bloom)	Engineering Knowledge
		Expected Proficiency (%)	Problem Analysis
		Expected Attainment (%)	Design & Development
			Analysis, Design, Research
			Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Acquire knowledge about the Thermodynamic Analysis of SI Engine Combustion process.	2	90	90	H	H	M	H	L	L	M	L	H	M	M	M	H	M	H
CLO-2 :	Acquire knowledge about the Thermodynamic Analysis of CI Engine Combustion process.	2	90	90	H	M	M	M	M	L	L	M	H	M	M	M	H	M	H
CLO-3 :	Understand the Various Fuel injection system for SI & CI engine	2	90	90	H	M	H	H	M	H	L	L	H	M	H	M	H	M	H
CLO-4 :	Gain knowledge about the engine modification required for alternative fuels.	2	90	90	M	H	M	M	H	M	H	H	M	L	H	M	H	M	H
CLO-5 :	Acquire knowledge about recent trends in IC engines.	2	90	90	H	H	M	H	L	H	M	L	L	H	M	M	H	M	H

Duration (hour)	Spark Ignition Engines	Compression Ignition Engines	Fuel systems	Alternate Fuels	Recent Trends
	9	9	9	9	9
S-1	SLO1	Introduction to Spark ignition engines	Introduction to Compression Ignition Engines	Introduction to Fuel Injection System	Introduction to Engine Modifications For Alternative Fuels
	SLO2	Air-Fuel Ratio Requirements	Stages Of Combustion in CI Engine	Fuel Injection System Functions And Components	Alternative fuels Properties , Suitability
S-2	SLO1	Design Of Carburetor	Stages Of Combustion in CI Engine	Petrol Injection - Open Loop Systems	Alcohols as a Fuel for IC engines
	SLO2	Carburetor –Fuel Jet Size And Venture Size	Normal And Abnormal Combustion – Factors Affecting Knock	Petrol Injection - Closed Loop Systems	Vegetable Oils And Bio-Diesel
S-3	SLO1	Carburetor –Fuel Jet Size And Venture Size	Normal And Abnormal Combustion – Factors Affecting Knock	Mono Point And Multi Point Injection System	Bio-Gas
	SLO2	Stages Of Combustion	Direct And Indirect Injection Systems	Mono Point And Multi Point Injection System	Natural Gas
S-4	SLO1	Stages Of Combustion	Direct And Indirect Injection Systems	Direct Injection Systems	Liquefied Petroleum Gas
	SLO2	Normal And Abnormal Combustion	Combustion Chambers	Fuel Injection In-Line, Rotary Pumps	Liquefied Petroleum Gas
S-5	SLO1	Normal And Abnormal Combustion	Combustion Chambers	Testing-Governing- Injection Lag	Hydrogen as a fuel in IC engines
	SLO2	Factors Affecting Knock	Turbo Charging	Fuel Injector - Types Of Injection Nozzle	Hydrogen as a fuel in IC engines
S-6	SLO1	Combustion Chambers	Turbo Charging	Fuel Injector - Types Of Injection Nozzle	Engine Modifications
	SLO2	Combustion Chambers	Introduction To Thermodynamic Analysis Of CI Engine	Fuel Spray Characteristics	Engine Modifications

S-7	SLO1	Introduction To Thermodynamic Analysis Of SI Engine	Thermodynamic Analysis Of CI Engine	Fuel Injection Timing	Performance, emission and combustion characteristics of SI engines	Alternative Power Sources: Wankel Rotary Engine
	SLO2	Thermodynamic Analysis Of SI Engine	Combustion Process in CI Engines	Factors Influencing Fuel Spray Atomization, Penetration And Dispersion Of Diesel	Performance, emission and combustion characteristics of SI engines	Sterling Engine, Gas Turbine Engine
S-8	SLO1	Thermodynamic Analysis Of SI Engine	Combustion Process in CI Engines	Factors Influencing Fuel Spray Atomization, Penetration And Dispersion Of Diesel	Performance, emission and combustion characteristics of CI engines	Sterling Engine, Gas Turbine Engine
	SLO2	Thermodynamic Analysis Of SI Engine Combustion Process	Combustion Process in CI Engines	Electronic Engine Management system	Performance, emission and combustion characteristics of CI engines	Cycle test-I
S-9	SLO1	Recent Developments In SI Engines	Recent Developments In CI Engines	Electronic Engine Management System	Alternative fuels used in CI engines	Cycle test-II
	SLO2	Recent Developments In SI Engines	Recent Developments In CI Engines	Common Rail Direct Injection Diesel Engine	Alternative fuels used in CI engines	Surprise test

Learning Resources	<p>1. Heinz Heisler, "Advanced Engine Technology", SAE International Publications, USA, 1998</p> <p>2. Ganesan V. "Internal Combustion Engines", Third Edition, Tata McGraw-Hill, 2007</p> <p>3. John B Heywood. "Internal Combustion Engine Fundamentals", Tata McGraw-Hill 1988</p> <p>4. Patterson D.J. and Henein N.A, "Emissions from combustion engines and their control", Ann Arbor Science publishers Inc, USA,</p> <p>5. Gupta H.N, "Fundamentals of Internal Combustion Engines". ,Prentice Hall of India, 2006</p> <p>6. Ultrich Adler , "Automotive Electric / Electronic Systems", Published by Robert Bosh GmbH, 1995</p>
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100%-	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. N. Saravanan, Mahindra Research Valley, n.saravanan@mahindra.com	1. Dr.S. Premnath, Sri Venkateswara College of Engineering, prem@svce.ac.in	1. Dr.V. Edwin Geo, SRM IST
2. Mr.P.MohamedAzarudeen, Renault Nissan Technology and Business Centre, mohamedazarudeen.pakkirmohideen@rntbci.com	2. Dr.S.RamKumar, Vel Tech Rangarajan Dr.Sagunthala R&D Institute of Science and Technology, drsramkumar@veltech.edu.in	2. Mr.T.Prakash, SRM IST

Course Code	18AUO109T	Course Name	NEW PRODUCT DEVELOPMENT	Course Category	O	Open Elective	L	T	P	C
							3	0	0	3

Course Learning Rationale (CLR):		<i>The purpose of learning this course is to:</i>		
CLR-1:	<i>understand the new product process</i>			
CLR-2:	<i>learn and apply the concepts and tools necessary through case examples and assignments</i>			
CLR-3:	<i>actually use the new product development process by conceiving your own new product or service and introductory launch plan</i>			

Course Learning Outcomes (CLO):		<i>At the end of this course, learners will be able to:</i>		
CLO-1:	<i>Develop familiarity with models of innovation and the marketing and technology interface</i>			
CLO-2:	<i>Understand the importance of new product development to firm performance</i>			
CLO-3:	<i>Learn methods of generating, evaluating and testing product ideas</i>			
CLO-4:	<i>Identify relevant components and plan a product launch</i>			
CLO-5:	<i>Learn methods of evaluating and monitoring the success of a launch</i>			

Learning		
1	2	3
Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)
1,2	85	80
1,2	80	75
1,2	85	80
1,2	80	75
1,2	85	80

Program Learning Outcomes (PLO)														
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
H	H	H	M	M	M	M	M	H	M	M	H	H	M	M
H	H	H	M	M	M	M	M	M	M	M	H	H	H	H
H	H	H	M	M	M	M	H	M	M	M	M	H	M	H
H	H	H	H	M	H	M	H	H	M	H	H	M	H	M
H	M	M	M	M	H	H	H	M	M	M	M	M	M	M

		Project Selection and Evaluation	New Product Resources	New Product Planning	New Product Development	Product Architecture
Duration (hour)		9	9	9	9	9
S-1	SLO-1 SLO-2	Collection Of Ideas	Technological Research	Design Of Prototype	Journeys In Product Development	Establishing the Product architecture
S-2	SLO-1 SLO-2	Purpose Of Project	Basic concepts and need for Intellectual Property	Testing of prototype	Product Development Process Tools	creation
S-3	SLO-1 SLO-2	Selection Criteria	Patents	Quality Standards	Scoping Product Developments	clustering
S-4	SLO-1 SLO-2	Screening Ideas For New Products	Patent Search	Marketing Research	Technical And Business Concerns	geometric layout development
S-5	SLO-1 SLO-2	Creative design	Patent Laws	Introducing New Products	Understanding Customer Needs	fundamental and incidental interactions
S-6	SLO-1 SLO-2	Model Preparation	International Code For Patents	Integrate process design	Establishing Product Function	related system level design issues
S-7	SLO-1 SLO-2	Testing	Intellectual Property Rights (IPR)	Managing costs	involve customer in development and managing requirements	secondary systems
S-8	SLO-1 SLO-2	Cost evaluation	Copyrights	Robust design	process management and improvement	architecture of the chunks
S-9	SLO-1 SLO-2	Patent application	Geographical Indications	Integrating CAE, CAD, CAM tools	Plan and establish product specifications	creating detailed interface specifications

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. A. Prasad, Mahindra and Mahindra, PRASAD.ARUNKUMAR@mahindra.com	1. Dr. A. Krishnaveni, Govt. College of Engineering, Tirunelveli, krishnaveni@gcetly.ac.in	1. Dr. J. Chandradass, SRMIST, chandraj@srmist.edu.in
2. Mr. S. Ganesh Kumar, TAFE, ganeshkumar@tafe.com	2. Dr. M.A. Saibalaji, BS Abdur Rahman Institute of Science and Technology, Chennai, saibalaji@crescent.education	2. Mr. P. BaskaraSethupathi, SRMIST, sethupab@srmist.edu.in

Course Code	18AUQ110T	Course Name	AUTOMOTIVE STANDARDS AND REGULATIONS	Course Category	O	Open Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Impart knowledge on basics of automobile standards and regulations.	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Know the various safety standards on collision.	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Gain knowledge about various safety standards in automotive electrical systems.				M	L	L	L	M	M	M	L	L	L	L	H	H	L	L
CLR-4 :	Understand the regulations used in hybrid and electric vehicles.				M	L	L	L	M	M	M	L	L	L	L	M	H	M	L
CLR-5 :	Impart knowledge on regulations used in gaseous fuel vehicles.				M	L	L	L	M	M	M	L	M	L	L	M	H	M	M
					M	L	L	L	M	M	M	L	L	L	L	M	H	M	L
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Gain knowledge about basic automobile standards and regulations.	1	80	75															
CLO-2 :	Gain knowledge about standards for safety during collision.	2	75	70															
CLO-3 :	Understand the various standards used for automotive electrical systems.	2	80	77															
CLO-4 :	Gain knowledge about the regulations used for hybrid and electric vehicles.	3	75	70															
CLO-5 :	Gain knowledge about the regulations used for gaseous fuel vehicles.	3	85	80															

		General Automotive Standards and Regulations	Collision Safety Standards	Automotive electrical Standards	Electric and Hybrid Vehicle Standards	CNG, LPG Vehicles and Engine Emission Standards
Duration (hour)		09	09	09	09	09
S-1	SLO-1	Procedure for Type Approval and Certification of Vehicles for Compliance to Central Motor Vehicles Rules.	Bumper Fitment on Vehicles – Test Methods.	Testing Procedure and Requirements for Headlamp Beam.	Battery Operated Vehicles – Requirements for Construction and Functional Safety.	Safety and Procedural Requirements for Type Approval of CNG Operated Vehicles.
S-2	SLO-1	Speed Limitation Devices and Its Specifications.	Safety Belt Assemblies, Safety Belt Anchorages –Specifications.	Approval of Front Position Lamps, Rear Position Lamps, Stop Lamps, Direction Indicators, Rear Registration Plate Illuminating Devices and Reversing Lamp.	Measurement of Electrical Energy Consumption.	Safety and Procedural Requirements for Type Approval of CNG Operated Vehicles.
S-3	SLO-1	Arrangement of Foot Controls of Vehicles.	Seats, their Anchorages and Head Restraints Specifications, Survival Space for the Protection of the Occupants.	Provisions Concerning the Approval of Headlamps Equipped with Gas Discharge Light Sources.	Method of Measuring the Range.	Safety and Procedural Requirements for Type Approval of LPG Operated Vehicles.
S-4	SLO-1	Starting Grade-Ability - Method of Measurement and Requirements.	Requirements for Behaviour of Steering Mechanism of a Vehicle in a Head-On Collision.	Provisions Concerning the Approval of Light Emitting Diode(LED) Light Sources For use in Approved Lamp Units.	Measurement of Net Power and the Maximum 30 Minute Power and Speed.	Safety and Procedural Requirements for Type Approval of LPG Operated Vehicles.
S-5	SLO-1	Protective Helmets for Motor Cycle Riders.	Procedure for Determining the "H" Point and The Torso Angle in Seating Positions of Motor Vehicles.	Lighting, Signalling & Indicating Systems on Motor Vehicles.	Electric Power Train - Requirements for Construction and Functional Safety.	Code of Practice for use of LPG Fuel in Internal Combustion Engine to Power 4 Wheeled Vehicles.
S-6	SLO-1	Protective Helmets and Visors for Motorcycle Riders – Specification.	Requirements for the Protection of the Occupants in the Event of an Offset Frontal Collision.	Performance Requirements of Lighting and Light-Signalling Devices.	Measurement of Electrical Energy Consumption.	Code of Practice for use Of LPG Fuel in Internal Combustion Engine to Power 2 & 3 Wheeled Vehicles.
S-7	SLO-1	Two Wheeled Vehicles – Location, Identification and Operation of Controls, Tell-Tales and Indicators.	Approval of Vehicles with Regards to the Protection of the Occupants in the Event of a Lateral Collision.	Testing Standards for Wind Screen Wiping System.	Method of Measuring the Range.	Code of Practice for use of CNG Fuel in Internal Combustion Engine to Power 4 Wheeled Vehicles.

S-8	SLO-1 SLO-2	Procedure for Type Approval and Establishing Conformity of Production for Safety Critical Components.	Requirements for the Protection of Pedestrian and Other Vulnerable Road Users in the Event of a Collision with a Motor Vehicle.	Horn Installation Requirement.	Measurement of Net Power and The Maximum 30 Minute Power and Speed.	Code of Practice for use of CNG Fuel in Internal Combustion Engine to Power 2 & 3 Wheeled Vehicles.
S-9	SLO-1 SLO-2	NCAP And BNVSAP Ratings, Requirements for School Buses.	Requirements for the Protection of Fuel System in The Event of Rear Impact of a Motor Vehicle.	Electronic Stability Control Systems.	CMVR Type Approval for Hybrid Electric Vehicles, CMVR Type Approval of Vehicles Retrofitted with Hybrid Electric System.	Bharath and Euro Emission Norms.

Learning Resources	1. ARAI publications "Automotive industry standards", April 30, 2016.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.K.V. Simmon, Royal Enfield, kvsimmon1@royalenfield.com	1. Dr..A.Samuel Raja, Thiagarajar college of Engineering Madurai, samuel1973@tce.edu	1. Dr. T. Praveenkumar, SRMIST E-mail: praveent@srmist.edu.in
2. Mr.R.Srikanth, Altair, srikanth.r@altair.com	2. Mr. N.Ravikumar, Crescent Institute of Science and Technology, ravikumar@crescent.education	2. Dr. K. Kamalakkannan E-mail: kamalakk1@srmist.edu.in

Course Code	18AU0111T	Course Name	AUTOMOTIVE SCIENCES				Course Category	O	Open Elective				L	T	P	C								
												3	0	0	3									
Pre-requisite Courses	Nil		Co-requisite Courses		Nil		Progressive Courses	Nil																
Course Offering Department		Automobile Engineering				Data Book / Codes/Standards		Nil																
Course Learning Rationale (CLR):		The purpose of learning this course is to:					Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand the ability and information to follow recent developments about the internal combustion engine technology.						1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Describe methods for reduction of exhaust emissions, and their relations to fuel quality and engine performance						Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO – 3
CLR-3 :	Demonstrate competency in skills related to automotive technology.																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1 :	Understand the Insights in Internal Combustion Engine						1	90	90	H	H	H	M	H	M	H	H	H	L	M	H	H	M	H
CLO-2 :	Summarize the Knowledge in Engine Cycles						2	90	90	H	H	H	H	M	M	M	M	H	L	H	H	H	L	M
CLO-3 :	Compare the technology in emissions						2	90	90	H	M	H	M	H	H	M	H	M	L	H	H	H	H	L
CLO-4 :	Demonstrate the Relationship in Velocity, Acceleration and Speed						2	90	90	H	H	M	H	H	L	L	M	H	L	H	H	H	H	L
CLO-5 :	Explain the technology of Vehicle Characteristics						2	90	90	H	H	H	H	H	M	L	M	H	L	H	H	H	H	M
Duration (hour)	09		09		09		09				09				09									
S-1	SLO-1	Internal combustion engines	Theoretical engine cycles		Fuels and combustion & emissions		Velocity and acceleration, speed				Vehicle Characteristics													
	SLO-2	Engine power and Brake power	The constant volume cycle (Otto cycle)		combustion		Speed and velocity Acceleration				Load transfer under acceleration													
S-2	SLO-1	Dynamometers for high-speed engines	Thermal efficiency of the theoretical Otto cycle		Products of combustion		Velocity–time graph Uniform velocity				Static reactions													
	SLO-2	Mean effective pressure	Thermal efficiency in terms of compression ratio r		Relevant combustion equations		Uniform acceleration				Vehicle under acceleration													
S-3	SLO-1	Horsepower PS – the DIN	Effect of compression ratio on thermal efficiency		Air–fuel ratio Petrol engine combustion		Equations of motion and their application to vehicle technology				Vehicle acceleration – effect of load transfer													
	SLO-2	Indicated power Mean effective pressure	Relative efficiency		Detonation, Pre-ignition		Force, mass and acceleration				Front wheel drive													
S-4	SLO-1	Cylinder pressure vs. crank angle	Diesel or constant pressure cycle		Octane rating		Relation between mass and weight				Maximum acceleration – rear wheel drive													
	SLO-2	Mechanical efficiency of an engine	Diesel or constant pressure cycle		Compression ignition engine combustion chambers		Inertia				Four wheel drive – fixed													
S-5	SLO-1	Morse test	The dual combustion cycle		Diesel fuel-Flash point		Motion under gravity				Four wheel drive – with third differential													
	SLO-2	Characteristic curves of engine performance	Operation of dual combustion cycle		Pour point-Cloud point		Angular (circular) motion				Four wheel drive – with third differential													
S-6	SLO-1	Volumetric efficiency	Comparison between theoretical and practical engine cycles		Exhaust emissions-Factors affecting exhaust emissions		Equations of angular motion				Accelerating force – tractive effort													
	SLO-2	Torque vs. engine speed	Comparison between theoretical and practical engine cycles		Emissions and their causes		Equations of angular motion				Tractive resistance													
S-7	SLO-1	Specific fuel consumption vs. engine speed	The Stirling engine regenerator		Methods of controlling exhaust emissions		Relation between angular and linear velocity				Power required to propel vehicle													
	SLO-2	Brake power, torque and sfc compared	A double-acting Stirling engine		Exhaust gas recirculation		Relation between angular and linear velocity				Gradeability													
S-8	SLO-1	Thermal efficiency	The gas turbine		Catalysts		Centripetal acceleration				Vehicle power on a gradient													
	SLO-2	Indicated thermal efficiency	The gas turbine		Diesel particulate filters		Accelerating torque				Vehicle on a curved track													
S-9	SLO-1	Brake thermal efficiency petrol vs. diesel	Summary of formulae		Liquefied petroleum gas (LPG)		Model problem I				Overturning speed													
	SLO-2	Heat energy balance	Simple Problems		Zero emissions vehicles (ZEVs)		Model problem II				Skidding speed													

Learning Resources	1. Allan Bonnick "Automotive Science and Mathematics" Published by Elsevier Ltd First edition 2008	3. N. K. Giri "Automobile Technology" Khanna Publishers; 2nd edition edition (2002)
	2. Willard W. Pulkrabek "Engineering Fundamentals of the Internal Combustion Engine" Pearson; 2 edition (10 June 2003)	

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.Amarnath, Rampal india, amar@rambalindia.net	1. Dr.Arulselvan, MIT Chennai, arul@annauniv.edu.	1. Dr.K.Kamalakkannan, SRMIST, kamalakk1@srmist.edu.in
2. Mr.S.Ravi Kumar, ARK INFO SOLUTIONS, mymail2ravi@gmail.com	2. Mr.A.Muthuvel, Muthuvel.mech@sairamce.edu.in	2. Mr.S.MadhanKumar, SRMIST, madhanks@srmist.edu.in

Course Code	18AU0112T	Course Name	INTELLIGENT VEHICLE TECHNOLOGY	Course Category	O	Open Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Acquire knowledge of about Intelligent vision system	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Know the architecture of Intelligent transportation system	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Impart the techniques of adaptive control	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Know the architecture for autonomous vehicles	Expected Attainment (%)	Design & Development
CLR-5 :	Study the autonomous vehicle cases		Analysis, Design, Research
			Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Understand the intelligent vision system used in automobiles	2 85 75	H M H L H M M H H M L H H H H
CLO-2 :	Understand the architecture of intelligent transportation system	2 80 75	H M H H H M M H H M L M H H H H
CLO-3 :	Understand adaptive control techniques of an autonomous vehicle	2 90 85	H H H H L M M H M M M H H H M
CLO-4 :	Understand about the successful autonomous vehicle projects	2 85 80	H M H H H H H H H H M H H H H
CLO-5 :	Know the case studies of Autonomous vehicle	2 80 75	H M M M H H H H H H M H H H H

		Introduction to Intelligent Vision System	Vehicle Information System and Intelligent Transportation	Adaptive Control Techniques for Intelligent Vehicles	Decisional Architectures for Autonomous Vehicles	Autonomous Vehicle and Case Studies
Duration (hour)		9	9	9	9	9
S-1	SLO-1	Vision Based Driver Assistance System – Vehicle optical Sensor	Intelligent Transportation System (ITS) –	Automatic Control Of Highway Traffic And Moving Vehicles	Control Architectures	DARPA Challenge Case Study
	SLO-2	Vision Based Driver Assistance System – Laser Radar	Vision for ITS Communications	Automatic Control Of Highway Traffic And Moving Vehicles	Motion Autonomy	DARPA Challenge Case Study
S-2	SLO-1	Non Contact ground velocity detecting Sensor	Multimedia communication in a car	Adaptive Control Of Highway Traffic And Moving Vehicles	Deliberative Architectures,	ARGO Prototype Vehicle
	SLO-2	Road Surface Recognition Sensor	Multimedia communication in a car	Adaptive Control Of Highway Traffic And Moving Vehicles	Deliberative Architectures,	ARGO Prototype Vehicle
S-3	SLO-1	Vehicle Sensors for Electronic Toll Collection System	Current ITS Communication Systems and Services	Adaptive Control Overview	Reactive Architectures,	The Gold System
	SLO-2	Vehicle Sensors for Electronic Toll Collection System	Current ITS Communication Systems and Services	Gain Scheduling	Reactive Architectures,	The Gold System
S-4	SLO-1	Components of a Vision Sensor System	Vehicle to Vehicle Communication Systems	Model Reference Adaptive Control	Hybrid Architecture Overview.	The inverse Perspective Mapping
	SLO-2	Components of a Vision Sensor System	Vehicle to Vehicle Communication Systems	Model Reference Adaptive Control	Hybrid Architecture Examples	Lane Detection
S-5	SLO-1	Driver Assistance on Highways –Lane Recognition	Road to Vehicle Communication Systems	Self-Tuning Adaptive Control System Model	Overview Of Sharp Architecture,	Obstacle Detection
	SLO-2	Driver Assistance on Highways –Lane Recognition	Road to Vehicle Communication Systems	Self-Tuning Adaptive Control System Model	Models Of Vehicles	Vehicle Detection
S-6	SLO-1	Driver Assistance on Highways –Traffic Sign Recognition	Inter Vehicle Communication	System Identification Basics,	Concepts Of Sensor Based Maneuver,	Pedestrian Detection

	SLO-2	Driver Assistance on Highways –Traffic Sign Recognition	Inter Vehicle Communication	Recursive Parameter Estimation,	Reactive Trajectory Following, ,	Software systems architecture
S-7	SLO-1	Driver Assistance in Urban Traffic-Stereo Vision	Intra Vehicle Communication	Estimator Initialization	Parallel Parking	Computational Performances
	SLO-2	Driver Assistance in Urban Traffic-Stereo Vision	Intra Vehicle Communication	Design Of Self-Tuning Controllers	Platooning	ARGO Prototype vehicle Hardware
S-8	SLO-1	Driver Assistance in Urban Traffic- Shape base analysis	VANETS-Devices	Generalized Minimum Variance (GMV) Control	Main Approaches To Trajectory Planning,	Functionalities- ARGO Prototype vehicle
	SLO-2	Driver Assistance in Urban Traffic- Shape base analysis	Optical Technologies	Pole Placement Control	Main Approaches To Trajectory Planning,	Data acquisition System,
S-9	SLO-1	Driver Assistance in Urban Traffic- Pedestrian Recognition	Millimeter Wave technologies	Model Predictive Control Overview	Non-Holonomic Path Planning.	Processing System
	SLO-2	Driver Assistance in Urban Traffic- Pedestrian Recognition	Millimeter Wave technologies	Model Predictive Control Examples	Non-Homonymic Path Planning.	Control System Overview

Learning Resources	<ol style="list-style-type: none"> 1. LjuboVlagic, Michel Parent and Fumio Harashima, "Intelligent Vehicle Technologies", Butterworth-Heinemann publications, Oxford, 2001-ISBN 0 7506 5093 1 2. Ronald K Jurgen, "Automotive Electronics Handbook ", Automotive Electronics Series, SAE, USA, 1998. 	<ol style="list-style-type: none"> 3. NicuBizon, Lucian D Ascalescu And NaserMahdavitAbatabaei "Autonomous Vehicles
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		-	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.Jegan Amirthalingam, Senior Educator, KPIT a-jegan@kpit.com	1. Mr. Sam Jebakumar, SRM IST, jebakumj@srmist.edu.in	1. Mr. Joshua Paul E , SRMIST
		2. Mr.Jesu Godwin D, SRMIST

Course Code	18CHO101T	Course Name	SUSTAINABLE ENERGY ENGINEERING		Course Category	O	Open Elective				L	T	P	C												
											3	0	0	3												
Pre-requisite Courses	Nil		Co-requisite Courses		Nil		Progressive Courses	Nil																		
Course Offering Department		Chemical Engineering			Data Book / Codes/Standards		Nil																			
Course Learning Rationale (CLR):		The purpose of learning this course is to:				Learning			Program Learning Outcomes (PLO)																	
CLR-1 :	Familiarize various ways of collecting solar energy and its applications				Level of Thinking (Bloom)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15			
CLR-2 :	Familiarize various ways of utilizing wind energy								Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3	
CLR-3 :	Familiarize various aspects of Biomass energy and utilization																									
CLR-4 :	Understand the current status and future trends in energy																									
CLR-5 :	Appreciate the need for efficient energy storage and distribution																									
CLR-6 :	Understand the various means of utilizing energy for sustainable development																									
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																								
CLO-1 :	Know the different industrial solar equipments for heat and electricity					1	80	75	L	M	H	L			H						H	L	M			
CLO-2 :	Know the types of wind mill and their design					1	80	75	L	M	H	L			H						H	L	M			
CLO-3 :	Comprehend the uses of energy from biomass and reactor design					1	80	75	L	M	H	L			H						H	L	M			
CLO-4 :	Apply the concept of energy transfer to modern processes					2	70	65	H	H	H	H			H						H	H	H			
CLO-5 :	Comprehend the various means of energy storage and distribution					2	75	65	H	H	H	H			H						H	H	H			
CLO-6 :	Apply the knowledge of sustainable resources for efficient energy utilization and storage					2	70	65	H	H	H	H			H						H	H	H			
Duration (hour)		9		9		9		9		9		9														
S-1	SLO-1	Introduction on solar energy		Availability of wind		Biomass, Biomass resources		Current and future state of energy - Introduction		Energy storage and distribution - Introduction																
	SLO-2	Solar angles		Special features of wind energy		Composition, fuel properties		Current and future state of energy - Introduction		Energy storage systems																
S-2	SLO-1	Solar collectors		Types of wind mills		Biomass conversion technologies		Basic thermodynamic functions and applications		Mechanical energy storage																
	SLO-2	Types of collectors		The power from the wind		Anaerobic digestion		Basic thermodynamic functions and applications		Mechanical energy storage																
S-3	SLO-1	Flat plate and dish type		Performance of wind mills		Direction combustion		Calculation of heat of reaction		Mechanical energy storage																
	SLO-2	Types of flat and dish types		Modern wind energy generators		Pyrolysis		Application of Hess law		Electrical storage																
S-4	SLO-1	Solar concentrators		Horizontal wind mills		Gasification		Problems on heat of reaction and Hess law		Electrical storage: The lead acid battery																
	SLO-2	Types of concentrators		Vertical wind mills		Biogas technology		Problems on heat of reaction and Hess law		Chemical storage																
S-5	SLO-1	Solar pumping		Wind turbines		Bioethanol		Other chemical processes for energy transfer		Chemical storage																
	SLO-2	Problems in collectors		Design parameters		Biodiesel Production		Other chemical processes for energy transfer		Chemical storage																
S-6	SLO-1	Solar refrigeration		Design principles of wind turbine		Community and institutional biogas plants		Microwave-assisted reactions		Chemical storage																
	SLO-2	Solar air cooling, Solar furnaces		Horizontal and vertical axis types		Family biogas plants		Microwave-assisted reactions		Electromagnetic energy storage																
S-7	SLO-1	Solar power generation		Problems in wind mills		Recent Developments in biomass technology		Sonochemistry		Thermal energy storage (Sensible heat)																
	SLO-2	Solar drying, stills and cooking		Problems in wind mills		Energy farming		Sonochemistry		Thermal energy storage (Sensible heat)																
S-8	SLO-1	Photo voltaic cell principle		Problems in wind mills		design consideration		Electrochemistry		Thermal energy storage (Latent heat)																
	SLO-2	Photo voltaic cell types		Problems in wind mills		Problems in digesters		Electrochemistry		Thermal energy storage (Latent heat)																
S-9	SLO-1	Photo voltaic cell design		Wind power farms		Problems in digesters		Photochemistry and Photovoltaic Cells		Biological storage																
	SLO-2	Photo voltaic cell advancement		Modern wind farms		Applications of reactors		Photochemistry and Photovoltaic Cells		Biological storage																

Learning Resources	1. Anne E. Marteel-Parrish and Martin A. Abraham, "Green Chemistry and Engineering - A pathway to sustainability", John Wiley & Sons, 2014. 2. Rai G.D., "Non Conventional Energy Sources", Khanna Publishers, New Delhi, 1999.	3. Bansal N.K, Manfred Kleen Man and Michael Meliss, "Renewable energy sources of conversion technology" TMH Publication. 4. Kothari. P., Singal, K. C. and Rakesh, "Renewable Energy Sources and Emerging Technologies", Ranjan PHI Pvt. Ltd., New Delhi, 2008
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. A. Subramaniam, PESCO Beam Environmental Solutions Pvt. Ltd.,	1. Dr. Lima Rose Miranda, Anna University, email: limamiranda2007@gmail.com	1 Dr. K. Deepa SRM Inst. of Science & Technology, deepak1@srmist.edu.in
2. Mr. S. T. Kalaimani, CPCL, Chennai	2. Dr. T. R. Sundararaman, Rajalakshmi Engineering College	2 Mr. V. Ganesh SRM Inst. of Science & Technology, ganesv@srmist.edu.in

Course Code	18CHO102T	Course Name	PETROLEUM ENGINEERING				Course Category	O	OPEN ELECTIVE				L	T	P	C																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																											
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Pre-requisite Courses		NIL		Co-requisite Courses		NIL		Progressive Courses		NIL																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																	
Course Offering Department		Chemical Engineering				Data Book / Codes/Standards			NIL																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																		
Course Learning Rationale (CLR):		The purpose of learning this course is to:						Learning			Program Learning Outcomes (PLO)																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																
CLR-1 : Understand the formation and evaluation of crude oil, overview of petroleum refining processes, Distillation								1			2			3			1			2			3			4			5			6			7			8			9			10			11			12			13			14			15																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																
CLR-2 : Understand the Evaluation and testing, properties, Petroleum refining processes								Level of Thinking (loom)			Expected Proficiency (%)			Expected Attainment (%)			Engineering Knowledge			Problem Analysis			Design & Development			Analysis, Design, Research			Modern Tool Usage			Society & Culture			Environment & Sustainability			Ethics			Individual & Team Work			Communication			Project Mgt. & Finance			Life Long Learning			PSO - 1			PSO - 2			PSO - 3																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																
CLR-3 : Understand the Thermal and catalytic cracking, treatment techniques																	L			M			H																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																		</		

Learning Resources	1. BhaskaraRao. B.K, "A Text on Petroleum Chemicals", 4thEdn.,Khanna Publishers, New Delhi, 2007 2. Nelson.W.L, "Petroleum Refinery Engineering", McGraw Hill Publishing Company Limited, 1985.	3. GopalaRao M. and Marshall Sittig. "Dryden's Outlines of Chemical Technology", 3rd Edn.,East-West Press, New Delhi, 1997.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Evaluate Create	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

CA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. A. Subramaniam, PESCO Beam Environmental Solutions Pvt. Ltd.,	1. Dr. Lima Rose Miranda, Anna University, email: limamiranda2007@gmail.com	1 Dr. K. Anbalagan, SRM Inst. of Science & Technology, anbalagan.k@ktr.srmuniv.ac.in
2. Mr. S. T. Kalaimani, CPCL, Chennai	2. Dr. T. R. Sundararaman, Rajalakshmi Engineering College	2 Dr. M.Magesh kumar SRM Inst. of Science & Technology, mageshkumar.m@ktr.srmuniv.ac.in

Course Code	18CHO103T	Course Name	INTRODUCTION TO CHEMICAL ENGINEERING	Course Category	O	OPEN ELECTIVE	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Chemical Engineering	Data Book / Codes/Standards			Nil

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
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CLR-1 :	Understand the basics of process calculation	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Be exposed to the fundamentals of Mechanical Operations																		
CLR-3 :	Understand the fundamentals of fluid flow phenomena																		
CLR-4 :	Be exposed to the principles of heat transfer																		
CLR-5 :	Acquire the knowledge on the basics of mass transfer																		
CLR-6 :	Be exposed to the basic principles of chemical engineering																		

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Learn the basics of stoichiometry and mass balance	2	80	70	H	H											H	L	
CLO-2 :	Familiarized with mechanical operations involved in material handling	2	80	70		H	H	L									H	H	L
CLO-3 :	Understand the concept of fluid and its flow	2	70	65		H	H	L										H	H
CLO-4 :	Gain Knowledge on heat transfer principles	2	80	70	H	H	H	L									H	H	
CLO-5 :	Comprehend the basics of mass transfer	2	70	65	H	H		L									M	L	
CLO-6 :	Analyze the concepts in chemical engineering	2	75	65	H	H	H	M									H	M	M

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Units and dimensions, the mole unit	Size reduction	Nature of fluids: Type of fluids and flow:	Introduction to Heat Transfer	Introduction to Mass Transfer operations
	SLO-2 mole fraction (or percent) and mass fraction (or percent)	Size reduction	Nature of fluids: Type of fluids and flow:	Various modes of Heat transfer	Diffusion, Types, Fick's I law of Diffusion.
S-2	SLO-1 analyses of a mixture, concentrations	Size analysis	incompressible and compressible, potential flow, Laminar and turbulent flow	Fourier's law of heat conduction and Thermal conductivity	Steady – state molecular diffusion in fluids at rest and in laminar flow: molecular diffusion in gases.
	SLO-2 basis of calculations	Size analysis	incompressible and compressible, potential flow, Laminar and turbulent flow	Newton's law of cooling, Natural and forced	Molecular diffusion in gases: steady state diffusion of A through non diffusing B
S-3	SLO-1 Problem solving on Units and dimensions	Screen efficiency	Hydrostatic equilibrium and manometers	Steady-state conduction compound resistances in series- slab and cylinder.	Gas phase equimolar counter diffusion. Diffusion in Multicomponent gas mixtures
	SLO-2 Problem solving on Concentrations	Screen efficiency	Hydrostatic equilibrium and manometers	Steady-state conduction compound resistances in series- slab and cylinder.	Gas phase equimolar counter diffusion. Diffusion in Multicomponent gas mixtures
S-4	SLO-1 predicting P-V-T properties of gases using ideal gas law & Van der Waals equation	Filtration and its types – pressure and vacuum filtration	Newtonian and Non-Newtonian fluids: Newton's-law of viscosity	Steady-state conduction compound resistances in series- slab and cylinder.	Molecular diffusion in liquids: steady state diffusion of A through non diffusing B
	SLO-2 Calculation of density	Filtration and its types – pressure and vacuum filtration	Newtonian and Non-Newtonian fluids: Newton's-law of viscosity	Steady-state conduction compound resistances in series- slab and cylinder.	Molecular diffusion in liquids: steady state diffusion of A through non diffusing B
S-5	SLO-1 Basics of chemical equation and stoichiometry	Filters and its classification	Reynolds number and transition from laminar to turbulent flow	Problem solving on heat transfer rate	Liquid phase equimolar counter diffusion
	SLO-2 limiting reactant, excess reactant, conversion, selectivity and yield	Filters and its classification	Reynolds number and transition from laminar to turbulent flow	Problem solving on heat transfer rate	Liquid phase equimolar counter diffusion
S-6	SLO-1 Problem solving on Density calculations	Basics of Settling and sedimentation	Boundary layer concept	heat transfer coefficient and Overall heat transfer coefficient	Effect of temperature and pressure on diffusivity.
	SLO-2 Problem solving on Stoichiometry	Basics of Settling and sedimentation	Boundary layer concept	heat transfer coefficient and Overall heat transfer coefficient	Principles of drying, driers and freeze drying

S-7	SLO-1	Basic concepts involved in material balance calculations	Principles of agitation, Types of agitators	Friction factors	Problem solving on heat transfer coefficient	Various methods of distillation and extraction.
	SLO-2	Basic concepts of recycle, bypass and purge streams	Principles of agitation, Types of agitators	Friction factors	Problem solving on heat transfer coefficient	Various methods of distillation and extraction.
S-8	SLO-1	Problem solving on Material Balance - Mixing	Flow patterns: prevention of swirling-draft tubes	Drag & Lift forces, Terminal settling velocity	Heat transfer to fluids without phase change: Boiling and Condensation	Basic concept of leaching, adsorption,
	SLO-2	Problem solving on Material Balance - Mixing	Flow patterns: prevention of swirling-draft tubes	Drag & Lift forces, Terminal settling velocity	Heat transfer to fluids without phase change: Boiling and Condensation	Basic concept of leaching, adsorption,
S-9	SLO-1	Problem solving on Material Balance - Drying	Blending and Mixing- Mixers: types	Introduction to various types of flow metering devices	Basic concepts of radiation, examples and application	absorption and membrane separation process
	SLO-2	Problem solving on Material Balance - Drying	Blending and Mixing- Mixers: types	Introduction to various types of flow metering devices	Basic concepts of radiation, examples and application	absorption and membrane separation process

Learning Resources	1. David M. Himmelblau, "Basic Principles and Calculations in Chemical Engineering", 6 th Edn., Prentice-Hall of India, New Delhi, 1998.	4. Binay K Dutta, "Heat Transfer: Principles and Applications", PHI Learning Private Limited, Delhi, 2010 5. Christie John Geankoplis, "Transport Processes and Separation Process Principles (Includes Unit Operations)", 4 th Edn., Pearson India Education Services Pvt. Ltd., 2015.
	2. Anup K Swain, Hemalata Patra, Roy. G.K, "Mechanical operations", Tata -McGraw Hill, 2010. 3. Noel de Nevers, "Fluid Mechanics for Chemical Engineers", 3 rd Edn., McGraw Hill International Editions, 2011	

SLO – Session Learning Outcome

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. A. Subramaniam, PESCO Beam Environmental Solutions Pvt. Ltd.,	1. Dr. Lima Rose Miranda, Anna University, email: limamiranda2007@gmail.com	1 Dr. S. Sam David SRM Inst. of Science & Technology, samdavis@srmist.edu.in
2. Mr. S. T. Kalaimani, CPCL, Chennai	2. Dr. T. R. Sundararaman, Rajalakshmi Engineering College	2 Mr. V. Ganesh SRM Inst. of Science & Technology, ganeshv@srmist.edu.in

Course Code	18CHO104T	Course Name	PROCESS PLANT SAFETY	Course Category	O	Open Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Chemical Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)																		
CLR-1 :	Familiarize the basics of Industrial safety management	Level of Thinking (Bloom)	1	2	Expected Proficiency (%)	3	Expected Attainment (%)	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLR-2 :	Acquire knowledge on chemical plant safety							Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3	
CLR-3 :	Impart knowledge on Industrial accidents, prevention and fire protection systems							L	M	M			L	M		H	H		H	H	M	M	M
CLR-4 :	Acquire knowledge on Hazard identification techniques							M	H				M	H	M	H	H		M	H	M	M	M
CLR-5 :	Expose industrial hygiene and Occupational health hazards, Safety legislation in chemical industries							L	M	M	M		H	H	M	H	H		M	H	M	M	M
CLR-6 :	Learning safety management , chemical plant safety, techniques of hazard identification, Industrial Hygiene, occupational Hazards and safety legislation in chemical industries							M	M		M	M	M	H						H	M	M	M
								L		M	M		L	H		H				H	L	L	
			</																				

Duration (hour)		9	9	9	9	9
S1	SLO-1	Importance of Safety consciousness in Indian Chemical Industries	Chemical process Industries - Siting and Layout of a Chemical plant	Definitions, accident causation theories, Classification, Causes, Costs , Principles of Accident prevention	Hazard analysis - Preliminary Hazard Analysis (PHA)	Concepts - Industrial and Occupational health hazards, Housekeeping, human factors and error, stress at work
S2	SLO-1	Development of Industrial Health and Safety	Classification of hazardous chemicals	Industrial accidents – Bhopal Gas tragedy, Chernobyl – case study	Detailed hazard analysis - FMEA	Role of trade unions in Industrial safety and health
S3	SLO-1	Development of Industrial Health and Safety - OSHA	Transportation of hazardous chemicals	Accident prevention technique - Plant and Chemical job safety analysis	Fault Tree Analysis	Personnel protective equipments –head protection, eye and face protection
S4	SLO-1	Safety Organization –Polices-Culture	Storage and handling of hazardous chemicals	Safety performance measurement tools - FR, SR, (FSI)	Hazard and operability (HAZOP) study	Personnel protective equipments –hand and foot protection
S5	SLO-1	Safety Organization – Planning- Promotion	Chemical reaction hazards and their control	Safety performance measurement tools- SafeT-Score, Accident rate per 1000 workers	Hazard and operability (HAZOP) study	Personnel protective equipments –body protection and respirators
S6	SLO-1	Safety Organization – Inspection –Rules	High pressure - High temperature operations – Case studies	Disabling injury index, Accident Compensation Statutes Disabling injury index, Accident Compensation Statutes	Human Error Analysis	Safety legislation in India, Factories act 1948
S7	SLO-1	Safety Organization –Responsibility – Supervision	Emergency preparation: On-site and Offsite	Accident Investigation reporting and Analysis	Risk Analysis	Indian boilers act and regulations, Indian electricity act and rules
S8	SLO-1	Effective Safety Education and Training	Safe guarding of Machines – Ergonomics	Conditions -Fire triangle- Classification of fires	Risk assessment	Indian explosives act and rules, Mines act, Petroleum act and rules
S9	SLO-1	Communication at various levels of production and operation. Safety slogans	Safe guarding of Machines – Ergonomics	Common causes of industrial fires, Fire protection systems- prevention	Dow (Index) Fire and Explosion Index	Environmental protection act.

Learning Resources	1. Sharma. A M "Safety and Health in Industry" -A Hand book, BS Publications , 2009 2. Fulekar. M.H, "Industrial Hygiene and Chemical Safety", I.K International Publishing house Pvt Ltd., 2006. 3. Fawcett .H.H, and Wood .W.S, Safety and Accident Prevention in Chemical Operations, John Wiley & sons, U.S.A.,1965	4. Willie Hammer &Dennis Price, Occupational safety management and Engineering, Prentice Hall, 2001 5. William Handley, Industrial safety hand book, McGraw- Hill, 1969 6. Daniel. A, Crowl& Joseph. F Louvar Chemical Process safety: fundamentals with applications, Prentice Hall international series
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SLO – Session Learning Outcome

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. A. Subramaniam, PESCO Beam Environmental Solutions Pvt. Ltd.,	1. Dr. Lima Rose Miranda, Anna University, email: limamiranda2007@gmail.com	Dr.B.Karunanithi SRM Institute of Science and Technology karunanb@srmist.edu.in
2. Mr. S. T. Kalaimani, CPCL, Chennai	2. Dr. T. R. Sundararaman, Rajalakshmi Engineering College	Ms.D.Nanditha SRM Institute of Science and Technology nandithd@srmist.edu.in

Course Code	18CHO105T	Course Name	POLLUTION ABATEMENT	Course Category	O	OPEN ELECTIVE	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Chemical Engineering	Data Book / Codes/Standards	Nil		

[illegible]

Duration (hour)		9	9	9	9	9
S-1	SLO-1	introduction	environmental regulations prevention vs control of industrial pollution.	air pollution control methods introduction to particulate emission control	principles of water treatment primary, secondary and tertiary treatments	solid waste and disposal methods sources and types of solid waste
	SLO-2	introduction	prevention vs control of industrial pollution	gravitational settling chambers	principles of water treatment secondary treatments	sources and types of solid waste
S-2	SLO-1	industrial activity and environment	prevention vs control of industrial pollution	cyclone separators,	principles of water treatment secondary treatments	processing methods, disposal- principle, practices and methods,
	SLO-2	industrial activity and environment	prevention vs control of industrial pollution	electrostatic precipitators	principles of water treatment secondary treatments	processing methods, disposal- principle, practices and methods,
S-3	SLO-1	industrial activity and environment	prevention vs control of industrial pollution	Volatile organic compounds control	principles of water treatment tertiary treatments	processing methods, disposal- principle, practices and methods,
	SLO-2	industrial activity and environment	prevention vs control of industrial pollution	Volatile organic compounds control	principles of water treatment tertiary treatments	processing methods, disposal- principle, practices and methods,
S-4	SLO-1	fates of industrial contaminants	environment policies and regulations to encourage pollution prevention	Volatile organic compounds control	principles of water treatment tertiary treatments	energy from solid waste, waste management hierarchy,
	SLO-2	fates of industrial contaminants	environment policies and regulations to encourage pollution prevention	control of sulphur dioxide	principles of water treatment tertiary treatments	energy from solid waste, waste management hierarchy,
S-5	SLO-1	case studies on industrial contaminants	environment policies and regulations to encourage pollution prevention	control of sulphur dioxide	advanced waste water treatments	energy from solid waste, waste management hierarchy,
	SLO-2	case studies on industrial contaminants	environment policies and regulations to encourage pollution prevention	control of sulphur dioxide	advanced waste water treatments	energy from solid waste, waste management hierarchy,
S-6	SLO-1	industrialization and sustainable development	environment friendly chemical processes	control of oxides of nitrogen	advanced waste water treatments	energy from solid waste, waste management hierarchy,
	SLO-2	industrialization and sustainable development	environment friendly chemical processes	control of oxides of nitrogen	advanced waste water treatments	energy from solid waste, waste management hierarchy,
S-7	SLO-1	sustainability strategies	environment friendly chemical processes	control of carbon monoxide and hydrocarbons	advanced waste water treatments	energy from solid waste, waste management hierarchy,

	SLO-2	sustainability strategies	environment friendly chemical processes	control of carbon monoxide and hydrocarbons	advanced waste water treatments	energy from solid waste, waste management hierarchy,
S-8	SLO-1	barriers to sustainability	regulations for clean environment and implication for industries	noise pollution measurements and its control	recovery of metals from process effluents	energy from solid waste, waste management hierarchy,
	SLO-2	Barriers to sustainability	Regulations for clean environment and implication for industries	Noise pollution measurements and its control	Recovery of metals from process effluents	energy from solid waste, waste management hierarchy,
S-9	SLO-1	Pollution prevention in achieving sustainability	Regulations for clean environment and implication for industries	Noise pollution measurements and its control	Recovery of metals from process effluents	hazardous waste, biomedical waste, and nuclear waste.
	SLO-2	Pollution prevention in achieving sustainability	Regulations for clean environment and implication for industries	Noise pollution measurements and its control	Recovery of metals from process effluents	hazardous waste, biomedical waste, and nuclear waste.

Learning Resources	<ol style="list-style-type: none"> 1. Bishop.P, "Pollution Prevention: Fundamentals and Practice", McGraw Hill International Edn., McGraw Hill Book Co., Singapore, 2000 2. Freeman.H.M, "Industrial Pollution Prevention Hand Book", McGraw Hill, 1995 3. James. G. Mann and Liu.Y.A, "Industrial Water Reuse and Waste Water Minimization", McGraw Hill, 1999 4. Rose.G.R.D, "Air pollution and Industry", Van Nostrand Reinhold Co., NewYork 1972 5. Pandey.G.N and Carney.G.C, "Environmental Engineering", Tata McGraw Hill, New Delhi,1989 6. Kapoor.B.S, "Environmental Engineering", 3rd Edn., Khanna publishers,1997
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SLO – Session Learning Outcome

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CA –4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. A. Subramaniam, PESCO Beam Environmental Solutions Pvt. Ltd.,	1. Dr. Lima Rose Miranda, Anna University, email: limamiranda2007@gmail.com	1 Dr. B.Karunanithi SRM Inst. of Science & Technology, karunab@srmist.edu.in
2. Mr. S. T. Kalaimani, CPCL, Chennai	2. Dr. T. R. Sundararaman, Rajalakshmi Engineering College	2 Dr. S.Vishali SRM Inst. of Science & Technology, vishalis@srmist.edu.in

Course Code	18CHO106T	Course Name	INTRODUCTION TO PROTEOMICS	Course Category	O	OPEN ELECTIVE	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Chemical Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Introduce protein structure and function	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Understand the methodologies utilized for protein isolation	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Understand the analytical methodologies available for protein identification	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Have an insight into methods available for the identification of proteins in a high-through-put manner	Expected Attainment (%)	Design & Development
CLR-5 :	Apply a scientific approach to proteomics investigation using bioinformatics tools		Analysis, Design, Research
CLR-6 :	Introduce various combination of sample preparation and analytical methodologies for proteomics investigation		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Understand the significance of protein structure and function from a physiological context	2 80 70	L M M M L
CLO-2 :	Design a sequence of methodologies for desired protein isolation from complex matrices	3 80 75	L M M M M
CLO-3 :	Design one or more analytical methodologies in series or parallel for protein identification	3 80 75	L M M M H
CLO-4 :	Conceive high-throughput screening methodology for identification of proteins in complex mixtures	3 85 80	L M M M H L L
CLO-5 :	Utilize proteomics methodologies aided by bioinformatics tools for protein characterization	3 80 75	L M H H H L L L M M
CLO-6 :	Design a sample preparation and analytical methodology scheme for a proteomics investigation	1 75 70	M H H H H L L L H H

Duration (hour)	9	9	9	9	9
S1 SLO-1	An Overview of Proteomics	Strategies for Protein Identification	MS- principles	Protein structures	Protein Chips and Functional Proteomics
S2 SLO-1	Need, scope and challenges of proteomics	Strategies for Protein Identification	MS- principles	Techniques for solving protein structures	Protein Chips and Functional Proteomics
S3 SLO-1	Strategies for Protein separation	Strategies for Protein Identification	Instrumentation and applications in proteomics	Techniques for solving protein structures	Protein Chips and Functional Proteomics
S4 SLO-1	2D gel electrophoresis- principle and applications	Protein Identification with antibodies	Instrumentation and applications in proteomics	Techniques for solving protein structures	Applications of Proteomics in disease diagnosis
S5 SLO-1	2D gel electrophoresis- principle and applications	Protein Identification with antibodies	Strategies for Protein Quantization	Protein interactions- principles and methods to study them	Applications of Proteomics in disease diagnosis
S6 SLO-1	Liquid chromatography- principle and applications	Protein Identification with antibodies	Quantitative proteomics with standard 2D gels Multiplexed proteomics	Protein interactions- principles and methods to study them	Applications of Proteomics in disease diagnosis
S7 SLO-1	Liquid chromatography- principle and applications	Protein sequence determination by chemical degradation	Quantitative proteomics with standard 2D gels Multiplexed proteomics	Protein interactions- principles and methods to study them	Drug development and plant biotechnology
S8 SLO-1	Multidimensional liquid chromatography	Protein sequence determination by chemical degradation	Quantitative with mass spectrometry	Protein Modification in Proteomics.	Drug development and plant biotechnology
S9 SLO-1	Multidimensional liquid chromatography	Protein sequence determination by chemical degradation	Quantitative with mass spectrometry	Protein Modification in Proteomics.	Drug development and plant biotechnology

Learning Resources	1. R. M. Twyman, Principles of Proteomics (Advanced Text Series), Bios Scientific, 2004 2. David W Mount, Bioinformatics- Sequence and genome analysis, Cold Spring Harbor Laboratory Press, second edition, 2004.	3. S. R. Pennington, M. J. Dunn, Proteomics: from Protein Sequence to Function, Springer publications, first edition, 2001. 4. Timothy Palzkill, Proteomics, Springer, 2002.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. A. Subramaniam, PESCO Beam Environmental Solutions Pvt. Ltd.,	1. Dr. Lima Rose Miranda, Anna University, email: limamiranda2007@gmail.com	Dr. M.P. Rajesh SRM Institute of Science and Technology rajeshm@srmist.edu.in
2. Mr. S. T. Kalaimani, CPCL, Chennai	2. Dr. T. R. Sundararaman, Rajalakshmi Engineering College	

Course Code	18CE0301T	Course Name	ADVANCED DESIGN OF RCC	Course Category	O	Open Elective Courses	L	T	P	C
							2	1	0	3

Pre-requisite Courses	18CEC207T	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Civil Engineering	Data Book / Codes/Standards	IS 456-2000, SP 16 Charts, IS 3370 Part1,2,3,4, IS 1343-2012, IRC 3-1983, IRC:83-2018 (Part II)		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Analyse the retaining wall with the effect of active and passive pressure	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Design of Flat Slab using Direct Design Method as per IS456-2000	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Utilize the concept the of yield line theory				H	H	-	-	-	-	-	-	-	-	-	-	H	-	H
CLR-4 :	Design Water Tanks using Working Stress Method				H	H	-	-	-	-	-	-	-	-	-	-	H	-	H
CLR-5 :	Utilize concepts of ILD to analyse the RCC bridge for simple spans				H	H	-	-	-	-	-	-	-	-	-	-	H	-	M
CLR-6 :	Analyse prestressed concrete sections for flexure				H	H	-	-	-	-	-	-	-	-	-	-	H	-	M
					H	H	-	H	-	-	-	-	-	-	-	-	H	-	H
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Identify the effect of active and passive pressure influencing the behavior in design of retaining walls	3	80	75															
CLO-2 :	Analyse the behavior of Flat slab in flexure and punching shear	3	85	75															
CLO-3 :	Apply yield line theory to the design of slabs	3	75	75															
CLO-4 :	Analyse the behavior of underground and elevated water tanks	3	90	80															
CLO-5 :	Analyse and design of RCC Bridge and Culvert using IRC loadings	3	85	75															
CLO-6 :	Apply the strength and load balancing concept to the design of beams in flexure	3	80	75															

Duration (hour)	9	9	9	9	9
S-1	SLO-1	RETAINING WALLS Introduction to Retaining Walls	FLAT SLABS Introduction to Flat Slab	RCC WATER TANKS Introduction to Water Retaining Structures	DESIGN OF BRIDGES Types of bridges and culverts
	SLO-2	Design of Retaining Walls, Proportioning of the size of the wall	Advantages of Flat Slab	Design of Rectangular and Circular Water Tanks	Simply supported girder bridges, Balanced cantilever and their behavior
S-2	SLO-1	Design for Overturning moment	Design of Flat slab, Proportioning	Design Problems – Circular slabs subjected to direct tension	Design Problems
	SLO-2	Design for Sliding and provision for shear key	Design for Bending	Design Problems – Contd.,	Introduction to IRC Loading, impact loading, Codal Provisions for design
S-3	SLO-1	Tutorials	Tutorials	Tutorials	Tutorials
	SLO-2	Tutorials	Tutorials	Tutorials	Tutorials
S-4	SLO-1	Design of Toe and Heel Slab of Retaining Wall	Thickness of flat slab based on punching shear	Design Problems	Design of slab culvert for Class AA, 70R, Class A
	SLO-2	Design of Stem of Retaining Wall	Design Problems	Design of Underground Water Tanks	Design Problems – Design of slabs based on IRC Codes
S-5	SLO-1	Introduction to Counterfort Retaining Walls	INTRODUCTION TO YIELD LINE THEORY	Design Problems – Design of Rectangular Water tanks (L/B >2)	Design Problems – Contd.,
	SLO-2	Design of Counterfort Retaining Walls, Proportioning of the size of the wall and Counterfort	Design of Square and Rectangular Slabs	Design Problems	Design Problems
S-6	SLO-1	Tutorials	Tutorials - Design of Square slabs for simply supported condition	Tutorials - Design of Rectangular Water tanks (L/B < 2)	Tutorials
	SLO-2	Tutorials	Tutorials – Contd.,	Tutorials	Tutorials

S-7	SLO-1	Design for Overturning moment	Design of Square slabs for fixed support condition	Design of overhead water tank and Intze type tanks	Loads on T-beam girder bridges using Courbans theory	Design of beams subjected to losses in shrinkage in concrete
	SLO-2	Design for Sliding and provision for shear key	Check for bending and shear	Design Problems	Design Problems	Design Problems – Contd.,
S-8	SLO-1	Design of Toe and Heel Slab of Counterfort Retaining Wall	Design of Circular and Triangular Slabs	Design of Staging with columns and beams, Shaft and conventional types	Drawing ILD diagram for simple spans and calculation of design Bending moment, shear force for class AA and class A loading	Introduction to design of beams
	SLO-2	Design of Stem of Counterfort Retaining Wall	Design of Circular and Triangular Slabs	Design Problems	Design Problems	Design of beams based on IS 1343.
S-9	SLO-1	Tutorials	Tutorials - Design of triangular slabs for different edge conditions	Tutorials	Tutorials	Tutorials
	SLO-2	Tutorials	Tutorials – Contd.,	Tutorials	Tutorials	Tutorials

Learning Resources	1. Krishnaraju.N, Pranesh.R.N, Reinforced Concrete Design, New Age International Publication, 2003.	5. Subramanian.N, Design of Reinforced Concrete Structures, Oxford University Press, 2013
	2. Ramamrutham.S, Design of Reinforced Concrete Structures, DhanpatRai Publishing Company., 2015.	6. Krishnaraju.N, Prestressed Concrete, Tata McGraw-Hill Education, 2008
	3. Johnson Victor D, Essentials of Bridge Engineering, 4 th ed, Oxford & IBH Publishing Company, 2007.	7. NPTEL Course: Reinforced Concrete Road Bridges. https://onlinecourses-archive.nptel.ac.in/noc17_ce24/preview
	4. Unnikrishna Pillai.S, DevdasMenon, Reinforced Concrete Design, 5 th ed., Tata McGraw, 2003.	8. NPTEL Course: Prestressed Concrete Structures https://nptel.ac.in/courses/105106117

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Er. G. Hariharanath, GA Consultants, Chennai, gac1996@hotmail.com	1. Dr. R. Santhakumar, Professor, Centre for Rural Department, NITTTR	Prof. G. Augustine Maniraj Pandian, SRMIST
2. Er. AGV. Designan, Design Group Engineering Consultancy Pvt Ltd. Chennai, designan.agv@gmail.com	2. Dr. P. Jayabalan, NIT, Trichy, pjeya@nitt.edu	Dr.P.R.Kannan Rajkumar, SRMIST

Course Code	18CEQ302J	Course Name	MODERN CIVIL ENGINEERING ECONOMICS	Course Category	O	Open Elective Course	L	T	P	C
							2	0	2	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Civil Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Understand the basic principles of economies	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Realize the type of firm and market structure	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Understand the concept of Indian economy	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Apply the concept of estimation	Expected Attainment (%)	Design & Development
CLR-5 :	Realize the types of construction specification		Analysis, Design, Research
CLR-6 :	Analyze rate analysis		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Identify the various economic policies	3 85 75	H H - - - H - - - - - H - -
CLO-2 :	Identify the forms of market structure and organization	2 85 75	H H - - - H - - - - - H - -
CLO-3 :	Apply the concepts of time value of money	2 85 75	H H - - - - - - - - - H - -
CLO-4 :	Determine the different types of estimation	2 85 75	H H - M - - - - - - - - H - -
CLO-5 :	Develop the specification for different types of buildings	3 85 75	H H - M - - - - - H - - - H - -
CLO-6 :	Identify the factors affecting rate analysis	3 85 75	H H - M - - - - - H - - - H - -

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Basic Principles and Methodology of Economics.	Forms of organizations	ROI Problem	Present and future worth of cash flows	Rate analysis-Importance
	SLO-2 Demand/supply	Cost & Cost Control – Techniques	Payback Period		Rate analysis-necessity
S-2	SLO-1 Government Policies and Application	Types of Costs	Payback Period Problem	Structure of productive activity	Factors affecting rate analysis
	SLO-2 Basic Macro-economic Concepts	Lifecycle costs	Bid price	Urbanization	Equipment productivity
S-3	SLO-1 Drawings to read and understand - Autocad	Earthwork estimation (Foundation)	Estimation of finishes (Interior and Exterior)	Estimation of MEP works	Rate analysis – Concrete works
S-4	SLO-1 Drawings to read and understand - Autocad	Earthwork estimation (Foundation)	Estimation of finishes (Interior and Exterior)	Estimation of MEP works	Rate analysis – Concrete works
S-5	SLO-1 GDP/GNP/NI/Disposable income	Break even Analysis	Evaluation of bids	Indian economy - plans	Labour productivity
	SLO-2 Public sector economics –welfare			Post reform Growth	Factors affecting productivity
S-6	SLO-1 Public sector economics – externalities, labour market	Budgets	RA Bills	Specifications-Types, requirements and importance	Measurements for various items
	SLO-2 Components of Monetary and Financial System	Capital Budgeting		detailed specifications for buildings	Introduction to the process of Estimation
S-7	SLO-1 Quantity estimation basics - Excel	Estimation of concrete works (Sub and super structure)	Estimation of bridges	Reinforcement calculations	Rate analysis – Masonry works
	SLO-2 Trenches)	Estimation of masonry works	Estimation of culverts	BIM Quantity Takeoff	Rate analysis - Plastering
S-8	SLO-1 Earthwork estimation (Embankments & Trenches)	Estimation of masonry works	Estimation of culverts	BIM Quantity Takeoff	Rate analysis - Plastering
S-9	SLO-1 Central bank –monetary aggregates, Commercial banks & their functions	Application of Linear Programming	Final bills	Detailed specifications for roads, Detailed specifications for minor bridges	IS standards for quantity estimation, IS standards for quantity estimation - recommendations
	SLO-2 Capital and Debt Markets, Elements of Business/Managerial Economics	Investment Analysis – NPV Problem	Depreciation and Time value of money	Detailed specifications for industrial structures, Rate analysis-Purpose	Drawings – Architectural, Drawings – Structural and MEP

Learning Resources	1. Mankiw Gregory N. (2002), <i>Principles of Economics</i> , Thompson Asia 2. V. Mote, S. Paul, G. Gupta(2004), <i>Managerial Economics</i> , Tata McGraw Hill 3. Misra, S.K. and Puri (2009), <i>Indian Economy</i> , Himalaya 4. Pareek Saroj (2003), <i>Textbook of Business Economics</i> , Sunrise Publishers 5. Typical PWD Rate Analysis documents.	6. Dutta, B.N., <i>Estimating and Costing in Civil Engineering (Theory & Practice)</i> , UBS Publishers, 2016 7. Dutta, B.N., <i>Estimating and Costing in Civil Engineering (Theory & Practice)</i> , UBS Publishers, 2016 8. <i>Introduction to Accounting and Finance for Civil Engineers – NPTEL Online course</i>
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20 %	20 %	15 %	15 %	15 %	15 %	15 %	15 %	15 %	15 %
	Understand										
Level 2	Apply	20 %	20 %	20 %	20 %	20 %	20 %	20 %	20 %	20 %	20 %
	Analyze										
Level 3	Evaluate	10 %	10 %	15 %	15 %	15 %	15 %	15 %	15 %	15 %	15 %
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, and Conf. Paper etc.

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. Rajeev Srinivasan, Senior Planning, NASS Contracting, Rajeev.srinivasan@nasscontracting.com	Dr. A .R. Krishnaraja, Associate professor, Kongu Engineering college, krajacivil@kongu.ac.in	Mr.M.B.Sridhar, Asst. Prof., SRMIST
Mr. N. Arivu Sudar, Fosroc India, n.arivusudar@gmail.com	Dr. J. Saravanan, Associate Professor, Annamalai University, ausjs5070@gmail.com	Mr.S.Gopinath, Asst. Prof., SRMIST

Course Code	18CEO303J	Course Name	MODERN TOOLS IN ENGINEERING SURVEYING			Course Category	O	Open Elective Course					L	T	P	C							
												2	0	2	3								
Pre-requisite Courses		18CEC204T	Co-requisite Courses		Nil		Progressive Courses		Nil														
Course Offering Department			CIVIL ENGINEERING			Data Book / Codes/Standards			Nil														
Course Learning Rationale (CLR):		The purpose of learning this course is to:				Learning		Program Learning Outcomes (PLO)															
CLR-1 :	Determine the Horizontal and vertical control					1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Know the Hydrographic surveying																						
CLR-3 :	Understand Advance surveying instruments																						
CLR-4 :	Know Global positioning System and segments																						
CLR-5 :	Introduce photogrammetry to civil engineering																						
CLR-6 :	Introduction of remote sensing to civil engineering																						
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																					
CLO-1 :	know the basics, importance, and methods of Triangulation and Trilateration					2	85	80	H	-	-	-	-	-	M	-	L	-	-	H	H	-	-
CLO-2 :	Study the various Hydrographic Surveying Techniques.					2	85	75	H	-	-	-	-	-	M	-	L	-	-	H	H	-	-
CLO-3 :	Acquire knowledge about EDM and Total Station					2	80	75	H	-	-	-	-	-	H	-	L	-	-	H	H	-	-
CLO-4 :	Survey Using GPS.					2	85	80	H	-	-	-	-	-	H	-	L	-	-	H	H	-	-
CLO-5 :	Study the Concept of Aerial Photo Interpretation.					2	85	75	H	H	H	M	H	-	H	-	M	-	-	H	H	-	-
CLO-6 :	learn the importance and different aspects of remote sensing					2	80	75	H	H	H	H	H	-	H	-	M	-	-	H	H	-	-
Duration (hour)		09		09		09		09		09		09		09		09		09		09		09	
S-1	SLO-1	TRIANGULATION AND TRILATERATION		HYDROGRAPHIC SURVEYING		EDM, TOTAL STATION, GPS SURVEYING		PHOTOGRAMMETRY SURVEYING				REMOTE SENSING											
	SLO-2	Horizontal Vertical control - methods Triangulation – Primary Secondary and Tertiary Triangulation		Methods of Hydrographic Surveying Establishment of Horizontal control Tide Gauges-		Infrared EDM & Microwave system- Measuring DDM-ODM- EDM Electro-optical system- Measuring& Working Principle,				Introduction - Photogrammetry in Civil engineering History of Photogrammetry ,				Introduction , Historical Background Components of Remote sensing									
S-2	SLO-1	Base line –Figure and Layout of base lines		Recording and non recording Type, Staff, float and weight gauge, Self registering Tide Gauge		Sources of error in EDM ,Total station- Types				Terminology in Photogrammetry- Photo theodolite,				Electromagnetic Radiation (EMR) Ideal remote sensing system									
	SLO-2	Base line extension- By Prolongation By Double Sighting Method		Equipments of Sounding-Shore signal and buoys		Measuring and working principle,				Terrestrial and Aerial photographs - vertical and oblique photograph				Wave length and Frequency of Different bands									
S-3	SLO-1	Tacheometric Surveying--Constants of Tacheometer		Setting out simple circular curve --Single Theodolite Method		Total Station Surveying - Measurements of Distances and angles,				Total Station Surveying - Measurements of Traversing,				Identification of aerial photographs									
	SLO-2	Tacheometric Surveying--Constants of Tacheometer		Setting out simple circular curve --Single Theodolite Method		Total Station Surveying - Measurements of Distances and angles,				Total Station Surveying - Measurements of Traversing,				Identification of aerial photographs									
S-4	SLO-1	Tacheometric Surveying--Stadia Tacheometry		Setting out simple circular curve --Double Theodolite Method		Total Station Surveying- Measurements of, Slope				GPS Surveying –Measurement of Coordinates				Aerial Photo Interpretation Using Photo Interpretation Keys									
	SLO-2	Tacheometric Surveying--Stadia Tacheometry		Setting out simple circular curve --Double Theodolite Method		Total Station Surveying- Measurements of, Slope				GPS Surveying –Measurement of Coordinates				Aerial Photo Interpretation Using Photo Interpretation Keys									
S-5	SLO-1	Baseline measurement- instruments and accessories Wheelers baseline apparatus		Sounding Equipment, Angle measuring instruments Location of Sounding-		Coordinate system-Classification, GPS - Fundamentals				Scale of an aerial photograph Types of scales				Interactions with atmosphere & Earth features									
	SLO-2	Jardein's Method & Hunter's short base Method		Observation from the shore , boat, both shore and boat		Space ,Control & User Segments of GPS				Overlapping of Aerial Photographs,				Platform, Sensors Definition, Types Airborne Platforms									

S6	SLO-1	Correction Determination of intervisibility of triangulation stations	Location by stretched wire across a river	Errors in GPS Surveying	Measurement of Scale, Flight Planning,	Geostationary and Sunsynchronous Orbits
	SLO-2	Axial Signal Correction-Eye and Object Correction	Plotting of Sounding - Mechanical method	GPS Surveying Methods	Photo interpretation keys	Active and passive remote sensing
S-7	SLO-1	Tacheometric Surveying--Tangential Tacheometer	Setting out simple circular curve --Single Theodolite Method	Total Station Surveying-Measurements of distances & Height	Use of Stereoscope for 3-D Viewing	Tracing of Landuse and land cover from image
	SLO-2	Tacheometric Surveying--Tangential Tacheometer	Setting out simple circular curve --Single Theodolite Method	Total Station Surveying-Measurements of distances & Height	Use of Stereoscope for 3-D Viewing	Tracing of Landuse and land cover from image
S-8	SLO-1	Tacheometric Surveying--Subtense bar method	Contouring	Total Station Surveying - Measurements of Traversing,	Height determination from a Stereo pair using the Parallax bar	Tracing of Landuse and land cover from image
	SLO-2	Tacheometric Surveying--Subtense bar method	Contouring	Total Station Surveying - Measurements of Traversing,	Height determination from a Stereo pair using the Parallax bar	Tracing of Landuse and land cover from image
S-9	SLO-1	Satellite Station Reduction to Centre	Graphical Method ,Analytical Method Stream Gauge-Area velocity Method	Kinematic Surveying	Stereoscopy-Stereoscope and Stereo-photographs	Spectral --Radiometric & Temporal resolution Microwave remote sensing
	SLO-2	Signals --Luminous and Non-luminous Signals Towers	Velocity Measurement using Floats & Current meter Weir method, Chemical Method	Static Surveying	Photo interpretation keys, Applications of aerial Photos	Scanners - Radiometer - RADAR, Applications of Remote Sensing

Learning Resources	1. Kanetkar .T.P, "Surveying and Levelling" Vols. I and II, United Book Corporation, Pune, 1994. 2. Surveying and leveling Part I', Late T.P Kanetkar and Prof. S V Kulkarni, Poona VidyagrihaPrakashan, 3. Punmia .B.C, "Surveying, Vols". I and II, Laxmi Publications, 1999.	https://nptel.ac.in/noc/individual_course.php?id=noc18-ce37 https://swayam.gov.in/nd1_noc19_ce39 https://swayam.gov.in/nd1_noc19_ce34 https://nptel.ac.in/noc/individual_course.php?id=noc18-ce35 (Part I and II)
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	15%	15%	15%	15%	20%	20%	20%	20%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	15%	15%	15%	15%	10%	10%	10%	10%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr G Hariharanath, Chief Executive , GA consultants, gac1996@hotmail.com	Dr. E S M. Suresh, NITTR, esmsuresh@gmail.com	Dr. Sachikanta Nanda, SRMIST
2. Er. AGV. Designan, Design Group Engineering Consultancy Pvt Ltd. Chennai, design.agv@gmail.com	Dr. Srinivasa Raju, IRS, Anna University, raju_irs@yahoo.com	Dr. R. Annadurai, SRMIST

Course Code	18CE0304T	Course Name	EMERGING TRENDS IN STEEL DESIGN	Course Category	E	Open Elective Course	L	T	P	C
							2	1	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Civil Engineering	Data Book / Codes/Standards	IS : 800-2007, Steel Tables(Revised), IS : 875-Part 1,2 & 3		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Identify the characteristics of steel connection types and different configurations				Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Identifying structural steel connections and appropriate design																							
CLR-3 :	Identify and solve beam-column design, plate and gantry girder																							
CLR-4 :	Solve the basic column base problems and to design the base plates																							
CLR-5 :	Analyze the basic concepts roof types and to design connections for different roof models																							
CLR-6 :	Identify pre-engineered building components, classification of towers and loading combinations																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1 :	Accrue the knowledge of steel connections, beam-column joints and plates				2	85	75	H	M	M	L	-	-	-	-	-	L	-	-	M	L	-	-	
CLO-2 :	Analyze and Design eccentric and moment resistant connections				2	85	75	H	H	M	M	-	-	-	-	-	L	-	-	M	L	-	-	
CLO-3 :	Analyze and Design beam-columns, plate girder and gantry girder				2	85	75	H	H	M	M	-	-	-	-	-	-	-	M	-	-	-	-	
CLO-4 :	Accrue the knowledge on Design of column bases and eccentrically loaded base plate				2	85	75	H	H	M	M	-	-	-	-	-	L	-	-	M	L	-	-	
CLO-5 :	Analyze and design roof truss and connections of industrial structures				2	85	75	H	H	M	M	-	-	-	-	-	-	-	M	-	-	-	-	
CLO-6 :	Accrue comprehensive knowledge in Understanding design principle of pre-engineered buildings and towers				2	85	75	H	H	M	M	-	-	-	-	-	L	-	-	M	L	-	-	

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Introduction to Steel Design	Introduction to Beam-Column	Introduction to column bases	Structural frames and functions of components
	SLO-2	Brief notes on emerging trends in structural steel design	Beam-Column configuration	Introduction to footing	Types of roof trusses for different spans
S-2	SLO-1	Connection types	Behaviour of short beam-columns	Types of footings	Estimation of dead loads, live loads, wind loads
	SLO-2	Connection configuration	Behaviour of long beam-columns	Design of Slabs	Load combinations
S-3	SLO-1	Simple connections	Numerical problems on beam-column	Design of Slabs – Numerical problems	Analysis of roof truss - Principles
	SLO-2	Simple connection configuration	Numerical problems on beam-column	Design of Slabs – Numerical problems	Analysis of roof truss
S-4	SLO-1	Tutorial 1: Connections	Tutorial 3: Beam-Column design	Tutorial 5: Column bases, footings and slabs	Tutorial 7: Roof truss and load
	SLO-2				
S-5	SLO-1	Semi-rigid connections	Interaction Formula	Design of gusseted plate	Design of roof truss - Concept
	SLO-2	Semi-rigid connection configurations	Principles of Beam-Column	Numerical problems on gusseted plate	Design of roof truss
S-6	SLO-1	Rigid Connections	Design approach to beam-column	Numerical problems on gusseted plate	Numerical problems on roof truss design
	SLO-2	Rigid connection configurations	Design consideration	Design of base plate and connections	Numerical problems on roof truss design
S-7	SLO-1	Numerical problems on Simple configuration	Boundary constraints and restraints	Design of base plate and connections – Numerical problems	Design of Purlins - Concept
					Design concept of plate girder

	SLO-2	Numerical problems on Simple configuration	Introduction to gantry girder	Design of base plate and connections – Numerical problems	Design of purlins	Design of plate girder
S-8	SLO-1	Tutorial 2: Connection numerical problems and applications	Tutorial 4: Gantry girder	Tutorial 6: Plates and connections	Tutorial 8: Roof truss and Purlins	Tutorial 10: Plate girder
S-9	SLO-1	Numerical problems on Semi-rigid and rigid configuration	Gantry girder - Principles	Design applications of gusseted plates	Numerical problems on purlins	Plate girder - Principles
	SLO-2	Numerical problems on Semi-rigid and rigid configuration	Gantry girder – Design Concepts	Design applications of base plate	Numerical problems on purlins	Plate girder – Design Concepts

Learning Resources	1. Subramanian.N, "Design of Steel Structures-Limit State Method", Oxford University Press, New Delhi, 2016 2. Duggal .S.K, "Limit State Design of Steel Structures", Tata McGraw Hill Publishing Company, New Delhi, 2010.	3. Ramamrutham .S., "Design of Steel Structures", Dhanpat Rai Pub., 2013 4. Vazirani .V.N, "Design and Analysis of Steel Structures", Khanna Publishes, 2003 5. Ramachandra .S, VirendraGhelot, "Limit State Design of Steel of Structures", Scientific Publishers, New Delhi, 2012.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	-	15%	-	15%	-	15%	-	15%	-
	Understand										
Level 2	Apply	20%	-	20%	-	20%	-	20%	-	20%	-
	Analyze										
Level 3	Evaluate	10%	-	15%	-	15%	-	15%	-	15%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100%	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, and Conf. Paper etc.

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Er. G.Hariharanath, GA Consultants, Chennai, gac1996@hotmail.com	1. Dr. R. Santhakumar, Professor, Centre for Rural Department, NITTTR	1. Dr. S. SenthilSelvan, SRMIST
2. Er. AGV. Designan, Design Group Engineering Consultancy Pvt Ltd. Chennai, designan.agv@gmail.com	2. Dr. P. Jayabalan, NIT, Trichy, pjeya@nitt.edu	2. Dr.K.S. Satyanarayanan, SRMIST

Course Code	18CE0401T	Course Name	ADVANCED PRESTRESSED CONCRETE STRUCTURES	Course Category	O	Open Elective Course	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Civil Engineering	Data Book / Codes/Standards	IS 1343: 2012		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Know and utilize the concepts of prestress concrete to analyse prestress concrete sections	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Understand about the importance of short and long term deflections and transfer of prestressing by bond	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Understand about composite section under flexure and shear	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Know about the process of design of pipes, piles and pavements	Expected Attainment (%)	Design & Development
CLR-5 :	Understand to analyze folded plates and shell		Analysis, Design, Research
CLR-6 :	Make them familiar on continuous beam and concordant cable		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Analyze the prestress concrete sections using different concepts	3 80 75	H H - - - - - - - - - - H - H
CLO-2 :	Determine short and long term deflections and bond stress in prestressed concrete members	3 85 75	H H - - - - - - - - - - H - H
CLO-3 :	Determine the flexural and shear strength of prestressed composite section	3 75 75	H H - H - - - - - - - - - - H - H
CLO-4 :	Design the cylinder and non-cylinder pipe, piles and pavements	3 90 80	H H - - - - - - - - - - H - H
CLO-5 :	Design folded plates and shell	3 85 75	H H - - - - - - - - - - H - H
CLO-6 :	Analyze primary, secondary and resultant moments on continuous beam and identify the concordant cable	3 80 75	H H - - - - - - - - - - H - H

Duration (hour)	9	9	9	9	9
S-1	SLO-1 PRESTRESSED CONCRETE Introduction - Basic concept – Principle of prestressing – Materials.	DEFLECTIONS Reasons to control deflections – Factors influencing deflections – short term deflection – uncracked section - Mohr's theorems	COMPOSITE CONSTRUCTION Introduction – composite action - advantages – types of composite construction. Methods of construction – propped – unpropped construction.	DESIGN OF PIPES Design of non-cylinder pipes – losses of prestress.	FOLDED PLATES Introduction - types of folded plates – slab action – plate action – Names of methods for analysis.
	SLO-2 Forms of steel – systems of prestressing				
S-2	SLO-1 Types of prestressing – uses of prestressed concrete.	Deflection due to different cable profiles	Analysis of stresses	Example	Design example
	SLO-2 Materials – concrete strength limitation – requirements of steel for prestressed concrete.	Example	Example		
S-3	SLO-1 Analysis – basic assumptions.	Example	Examples	Example	Design example
	SLO-2 Concentric and eccentric tendons – resultant stresses – at transfer – at service. Concepts of prestressing – rectangle – symmetrical I-section only.				
S-4	SLO-1 Stress concept	Prediction of long term deflections - Example	Flexural strength of composite section. Example	Design of cylinder pipes Design of shear reinforcement	SHELL Introduction – advantages – methods of prestressing – design.
	SLO-2				Design example
S-5	SLO-1 Stress concept – examples	Examples	Example	Example	
	SLO-2				
S-6	SLO-1 Stress concept - examples	Examples	Example	DESIGN OF PILES	Design example
	SLO-2				

					Advantages – driving stresses – service load stresses - reinforcements.	
S-7	SLO-1 SLO-2	Strength concept - examples	BOND Transmission of prestressing force - transmission length.	Shear strength of composite section.	Example	CONTINUOUS BEAMS Advantages – effects of prestressing - primary moment – secondary moment – resultant moment – pressure line.
S-8	SLO-1 SLO-2	Load balancing concept – cable profile – reaction – equivalent loads.	Example	Example	DESIGN OF PAVEMENTS General features – design of prestress in pavements.	Use of theorem of three moments - example
S-9	SLO-1 SLO-2	Load balancing concept – examples.	Bond stress – example.	Example	Example	Concordant cable profile – examples.

Learning Resources	1. Krishnaraju .R, "Prestressed Concrete", Tata McGraw-Hill Education, Edition: 2018, NewDelhi. 2. Pandit .G.S, Gupta .S.P, "Prestressed Concrete", CBS Publishers & Distributors, 2008 3. S. Ramamrutham, "Prestressed Concrete", DhanpatRai Publishing Company, Fifth Edition, Reprint 2016 4. Lin T.Y, Design of, "Prestressed Concrete Structures", Asia Publishing House, Bombay 1995.	5. IS: 1343-2012 "IS Code of Practice for Prestressed Concrete", BIS, New Delhi, 2012. 6. NPTEL Course: Prestressed Concrete Structures: https://nptel.ac.in/courses/105106117/
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, and Conf. Paper etc.

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Er. G.Hariharanath, GA Consultants, Chennai, gac1996@hotmail.com	1. Dr. R. Santhakumar, Professor, Centre for Rural Department, NITTTR	1. Dr. K. Gunasekaran, SRMIST
2. Er. AGV. Design, Design Group Engineering Consultancy Pvt Ltd. Chennai, design.agv@gmail.com	2. Dr. P. Jayabalan, NIT, Trichy, pjeya@nitt.edu	2. Dr. P. R. Kannan Rajkumar, SRMIST

Course Code	18CE0402T	Course Name	BRIDGE ENGINEERING	Course Category	O	Open Elective Course	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18CEC207T	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Civil Engineering	Data Book / Codes/Standards	IS 456 : 2000, IRC 3-1983, IRC 112:2011, IRC 22: 2015, IRC:83-2018 (Part II)		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Comprehend the principles of bridge engineering	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Acquire knowledge on the various types of IRC (Indian Road Congress) loads	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Understand and evaluate the internal forces due to moving loads																		
CLR-4 :	Get familiarized with the design principles of different types of RCC bridges																		
CLR-5 :	Understand the principles of design of bridge substructure																		
CLR-6 :	Determine the forces in elastomeric bearings.																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Choose the most appropriate type of bridge for the given conditions	3	75	60	H	H	-	H	-	-	L	-	-	-	-	L	H	-	-
CLO-2 :	Calculate the functional dimensions of a bridge across a waterway	3	75	60	H	H	-	H	-	-	-	-	-	-	-	L	H	-	-
CLO-3 :	Design slab type and girder type RCC bridges	3	90	85	H	H	L	H	-	-	-	-	-	-	-	L	H	-	-
CLO-4 :	Calculate the design forces on substructure	3	85	80	H	H	L	H	-	-	-	-	-	-	-	L	H	-	-
CLO-5 :	Design abutments and bridge foundations	3	75	70	H	H	L	H	-	-	-	-	-	-	-	L	H	-	-
CLO-6 :	Design Elastomeric bearings	3	75	60	H	H	L	H	-	-	-	-	-	-	-	L	H	-	-

Duration (hour)	9	9	9	9	9
S-1	SLO-1	FUNDAMENTALS OF BRIDGE ENGINEERING & IRC LOADS Hydraulic factors influencing bridge design	DESIGN OF RCC SLAB BRIDGES Span limitations	DESIGN OF RCC T BEAM BRIDGES Span limitations	DESIGN OF BRIDGE SUBSTRUCTURE Abutment – types
	SLO-2	Calculation of linear waterway	Analysis of simply supported slab due to concentrated loads – introduction	Configuration – spacing of T beams , end overhang	Forces affecting the stability of abutments
S-2	SLO-1	Effect of bridge on river regime	Effective width method for slab supported on opposite edges only	Introduction to Pigeauds method - deck slab supported on T beams	Problem solving to determine the stability of abutments
	SLO-2	Economic span of bridge	Span-wise dispersion	Dispersed dimensions of wheel over the slab	Piers – types of piers
S-3	SLO-1	Calculation of scour depth	Width-wise dispersion	Computation of bending moment using the curves for centrally placed wheel load	Loads on piers
	SLO-2	Design loads – IRC Class AA Class A	Analysis for bending	Design principles for longitudinal T beam girder – Courbon's theory	Analysis of piers
S-4	SLO-1	Design loads – IRC Class A and B	Analysis for shear	Understanding the various terms in the formula and its application	Problem solving – preliminary dimensions
	SLO-2	Impact effect	Design of slab bridge – computation of dead loads	Design of T beam bridge – preliminary dimensions – Class AA trackedload	Determination final stresses in the piers
S-5	SLO-1	Longitudinal forces	Positioning of IRC Class AA loads – tracked	Design of cantilever span	Bridge foundations – types
	SLO-2	Centrifugal forces	Analysis for maximum bending moment & Shear force	Determination of maximum bending moment in the interior span of the deck slab – Pigeaud's method	Well foundations – types
S-6	SLO-1	Types of bridges – suitability of different types of bridges for various spans - slab bridges	Positioning of IRC Class AA loads – wheeled	Design of deck slab using limit state method	Components of well foundations
					Slip in bearing

	SLO-2	Girder bridges	Analysis for maximum bending moment & Shear force	Analysis of longitudinal girder – dead loads bending and shear	Design of well foundations – working stress method	Shear deformation in bearing
S-7	SLO-1	Continuous bridges – precautions from settlement considerations	Positioning of IRC Class A loads	Moving loads – bending	Pile foundations – pile groups	Stability of bearing
	SLO-2	Balanced double cantilever bridges	Analysis for maximum bending moment & Shear force	Moving loads – shear	Design principles of pile foundation	Uplift at the bearing
S-8	SLO-1	Arch bridges	Design using Limit state method - for bending moment	Computing the design bending and shear forces	Design forces	Influence of steel plates in the bearing
	SLO-2	Fundamentals of analysis using moving loads	Design for shear	Design of girder using limit state method – bending	Design using working stress method	Design of bearing – input loads
S-9	SLO-1	Determination of absolute maximum reaction	Detailing of reinforcement	Design for shear	Structural detailing	Design of bearing for stresses
	SLO-2	Determination of absolute maximum shear and bending moment due to moving loads	Sketching the cross section to show structural details	Detailing with sketches	Sketching the cross section to show structural details	Check for deformation

Learning Resources	1. Johnson Victor .D, "Essentials Of Bridge Engineering", Oxford University Press, Sixth edition, 2018	7. IRC:22-2015, Standard Specifications and Code of Practice for Road Bridges, section VI – Composite Construction (Limit States Design) (Third Revision), IRC, 2015.
	2. Jagadeesh.T.R, Jayaram .M.A, "Design Of Bridge Structures", Prentice – Hall of India Pvt. Ltd., 2009.	8. IRC:45-1972, Recommendations for Estimating the Resistance of Soil Below the Maximum Scour Level in the Design of Well Foundations of Bridges, IRC, 1972.
	3. Krishna Raju .N, "Design of Bridges", Oxford & IBH Publishing Company Pvt. Ltd., Fifth edition, 2018	9. IRC:78-2014, Standard Specifications and Code of Practice for Road Bridges, Section VII- Foundations and Substructures (Revised Edition), IRC, 1974.
	4. IRC:3-1983, Dimensions & Weights of Road Design Vehicles (First Revision), IRC, 1983.	10. IRC:83-2018, (Part II), Standard Specifications and Code of Practice for Road Bridges, Section IX – Bearings (Elastomeric Bearings), Part II (Second Revision), IRC, 2018.
	5. IRC:5-2015, Standard Specifications and Code of Practice for Road Bridges, Section I – General Features of Design (Eighth Revision), IRC, 2015.	11. IRC:112-2011, Code of Practice for Concrete Road Bridges, IRC, 2011.
	6. IRC:6-2017, Standard Specifications and Code of Practice for Road Bridges, Section-II Loads and Load Combinations (Seventh Revision), IRC, 2017	

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	40 %	-	40 %	-	10 %	-	40%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	85 %	-	55%	-
	Analyze										
Level 3	Evaluate	20 %	-	20 %	-	20 %	-	5 %	-	5%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
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2. Er. (Mrs.) Mekala Ponmalar Gurubaran, National Highways, Tamilnadu, gmekalaponmalar@yahoo.com	2. Dr. P. Jayabalan, NIT, Trichy, pjeya@nitt.edu	2. Dr. K. S.Satyanarayanan, SRMIST

Course Code	18CEO404J	Course Name	FUNDAMENTALS OF COMPUTING	Course Category	O	Open Elective Course	L	T	P	C
							2	0	2	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Civil Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Learning of basics of computer programming using C, Java, Python	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Description of basic syntax of C, Java, Python programming		
CLR-3 :	Description of Data types, variables and key words		
CLR-4 :	Illustrate the use of reserved words, operators		
CLR-5 :	Understand the need of using statements, Loops in programming		
CLR-6 :	Knowing about numbers, decisions		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom) Expected Proficiency (%) Expected Attainment (%)	Engineering Knowledge Problem Analysis Design & Development Analysis, Design, Research Modern Tool Usage Society & Culture Environment & Sustainability Ethics Individual & Team Work Communication Project Mgt. & Finance Life Long Learning PSO - 1 PSO - 2 PSO - 3
CLO-1 :	Understanding of C, Java, Python languages	2 85 80	H H - - - - - - - - - - - H - -
CLO-2 :	Writing simple programs by using C, Java, Python programming languages	3 85 75	H H - - - - - - - - - - - H - -
CLO-3 :	Programming by using data types, variables and key words	3 85 75	H H - - - - - - - - - - - H - -
CLO-4 :	Express proficiency in using of reserved words and operators	2 85 80	H H - - - - - - - - - - - H - -
CLO-5 :	Identify the operations is using statements, loops in programming	2 80 75	H H - - - - - - - - - - - H - -
CLO-6 :	Expertise in making decisions and in using numbers for operation	3 85 75	H H - - - - - - - - - - - H - -

Duration (hour)	9	9	9	9	9
S-1 SLO-1	Overview	Data types	C programming reserved words	If...else statement	Loops in Python Loops in C?
SLO-2	Introduction to computer program	C and Java Data types	Java programming reserved words	If... else...if statement (if...elseif...else)	Numbers
S-2 SLO-1	Introduction to computer programming	Python Data types	Python programming reserved words	The switch statement	Math operation on Numbers
SLO-2	Uses of computer programs (Advantages of Computer Programs)	Variables	Operators	Decisions in Java, Python (Decisions in C, Java, Python)	Numbers in Java, Python
S-3 SLO-1	Lab Session 1:	Lab Session 3:	Lab Session 5:	Lab Session 7:	Lab Session 9:
SLO-2	Understanding of Computer Hardware and programming environment of C, Java and python Languages.	Initialization of data types in C, Java and Python .	Demonstrate the use of reserve words in C, Java, and Python	Develop a program using Decision statement.	Develop a program to solve computational problems using Math Operators.
S-4 SLO-1	Algorithm	Creating variables	Arithmetic operators	Loops	Characters
SLO-2	Basics of Programming	Store values in variables	Relational operators	The while loop	Escape sequences
S-5 SLO-1	Text editor, Compiler	Access stored values in variables	Logical operators	The do..while loop	Characters in Java Characters in C?
SLO-2	Interpreter, Online Compilation	Variables in Java (Variables in C, Java Family and Python)	Operators in Java (Operators in C, Java)	The break statement	Characters in Java
S-7 SLO-1	Lab Session 2:	Lab Session 4:	Lab Session 6:	Lab Session 8:	Lab Session 10:
SLO-2	Understanding the concept of Algorithm, Flowchart, Naming the program files, Storing, Compilation, Execution and Debugging.	Initialization of variables in C, Java and Python .	Understand and Develop a program to solve simple computational problems using arithmetic operators, relational and logical operators.	Develop a program using loop statement.	Understanding of Escape and Character sequences
S-8 SLO-1	Basic Syntax of C and Java programming	Variables in Python	Operators in Python	The continue statement	Characters in Python
SLO-2	Simple programs in C	Key words	Decision statements	Loops in Java	Characters in Python

Learning Resources	1. <i>Programming in C</i> by E. Balagurusamy, McGraw hill publications (India), New Delhi 2. <i>Programming in Java</i> by E. Balagurusamy , McGrawHill Publications(India), New Delhi 3. <i>Programming in Python</i> by E. Balagurusamy , McGrawHill Publications (India), New Delhi	4. Wesley J Chun, "Core Python Applications Programming", 3rd Edition, Pearson Education India, 2015. ISBN-13: 978-9332555365 5. https://nptel.ac.in/noc/individual_course.php?id=noc18-cs33 6. https://nptel.ac.in/courses/106105191/ 7. https://nptel.ac.in/courses/117106113/34
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20 %	20 %	15 %	15 %	15 %	15 %	15 %	15 %	15 %	15 %
Level 2	Understand										
	Apply	20 %	20 %	20 %	20 %	20 %	20 %	20 %	20 %	20 %	20 %
Level 3	Analyze										
	Evaluate	10 %	10 %	15 %	15 %	15 %	15 %	15 %	15 %	15 %	15 %
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Er. S. Dhanabal, General Manager, NLY, Neyveli, dhans1960@yahoo.co.in	1. Dr. R. Santhakumar, Professor, Centre for Rural Department, NITTTR	Mr. Shaik Niyazuddin Guntakal, SRMIST
2. Er. AGV. Desigan, Design Group Engineering Consultancy Pvt Ltd. Chennai, desigan.agv@gmail.com	2. Dr. P. Jayabalan, NIT, Trichy, pjeya@nitt.edu	Mr. C. Arun, SRMIST

Course Code	18CSO101T	Course Name	IT INFRASTRUCTURE MANAGEMENT	Course Category	O	Open Elective	L 3	T 0	P 0	C 3
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Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science & Engg.	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:					Learning			Program Learning Outcomes (PLO)														
CLR-1:	Understand the design factors and challenges in IT Infrastructure Management						1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Understand service delivery and associated processes						Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO – 3
CLR-3:	Understand storage and security management related to IT Infrastructure																							
CLR-4:	Understand performance and tuning processes and associated case studies																							
CLR-5:	Understand the suitable for combinations in information technology, business administration and electronic																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1:	Be able to describe the business value and processes of ICT services in an organization and apply that knowledge and skill with initiative to a workplace scenario						2	80	85	L	-	L	H	L	-	-	-	H	H	M	L	-	-	-
CLO-2:	Be able to investigate, critically analyze and evaluate the impact of new and current ICT services to an organization						2	75	80	M	-	-	H	H	-	-	-	L	L	L	H	-	-	-
CLO-3:	Be able to describe how effective IT Infrastructure Management requires strategic planning with alignment from both the IT and business perspectives in an organization						2	85	80	M	L	M	H	L	-	-	-	M	H	H	H	-	-	-
CLO-4:	Be able to demonstrate the technical and communications skills that contribute to the operation of ICT services in an organization						2	80	75	M	L	L	L	-	-	-	-	H	H	M	L	-	-	-
CLO-5:	Be able to reflect critically on the role of an enterprise architect in an organization						2	75	85	L	-	L	L	-	-	-	-	L	L	H	L	-	-	-
CLO-6:	Be able to synthesize the theoretical, technical and management issues that deliver ICT services to an organization						2	80	85	H	-	L	L	L	-	-	-	L	L	H	L	-	-	-

Duration (hour)	9		9		9		9		9	
S-1	SLO-1	Introduction – IT Infrastructure	Service Delivery And Support Process - Intro	Storage And Security Management - Intro	Performance And Tuning Process	Case Studies				
	SLO-2	Challenges in IT Infrastructure Management		Backup and Storage, Archive & Retrieve						
S-2	SLO-1	Design Factors for IT Organizations	Service Level Management	Space Management	Introduction on tuning process	Asset Network Corporation case				
	SLO-2	Design Factors for IT Infrastructures								
S-3	SLO-1	Determining customer's Requirements, Identifying System Components to manage	Financial Management	Hierarchical space management	Difference between Performance and Tuning processes and other Infrastructure processes	Radio Shack case				
	SLO-2	Identifying System Components to manage								
S-4	SLO-1	Identifying System Components to manage	IT Service Continuity Management	Database & Application protection	Definitions	Business Process Outsourcing (BPO)				
	SLO-2					Infrastructure Planning and Management				
S-5	SLO-1	Exist Processes, Data, applications,	Capacity Management	Disaster Recovery Bare Machine Recovery (BMR)	Preferred characteristics	e-Commerce Business Infrastructure Planning and Management				
	SLO-2									
S-6	SLO-1	Tools and their integration	Configuration Management	Data Retention	Performance and tuning applied to major resource environments	Enron case				
	SLO-2									
S-7	SLO-1	IT Systems and Service Management Process	Service desk, Incident management	Computer Security Identity Management	Assessing an Infrastructure's performance and tuning process	Tycocase				
	SLO-2									

S-8	SLO-1	Information systems Design Process	Availability management,	Access control system	Measuring and streamlining the P and T process	Worldcom case
S-9	SLO-1	IT Infrastructure Library	Release Management	Intrusion Detection	Performance tuning recommendations for data and event management	Analyze an information infrastructure – case study
	SLO-2					

Learning Resources	1. Rich Schiesser, "IT Systems Management", 2nd edition, 2010, Pearson Education, ISBN: 978-0137025060 2. P.Gupta, "IT Infrastructure and Its Management" 2nd Reprint, 2010, Tata McGraw Hill, ISBN: 978-0070699793 3. Sjaak Laan, "IT Infrastructure Architecture: Infrastructure Building Blocks and Concepts", 2011, Lulu Press Inc, ISBN 978-1-4478-8128-5.	4. Leonard Jessup, Joseph Valacich, "Information System Today: Managing Digital World", 3rd Edition, 2007, Prentice Hall, ISBN: 0-13-233506-9. 5. Hausman, Cook, "IT Architecture for Dummies", 2011, Wiley Publishing, Hoboken, NJ www.wiley.com ISBN: 978-0-470-55423-4 6. Richard J. Reese, "IT Architecture in Action", 2008, Xlibris Publishing, ISBN: 978-1-4363-0505-1
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50%)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#		Theory	Practice
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice		
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Mohamed Yaseen MS, Technical Business Analyst, CBA - Sydney, Australia, yasucseau@gmail.com	1. Dr. J. Baskar Babujee, Associate Professor, Madras Institute of Technology, Chennai. baskarjee@annauniv.edu	1. Dr. C.N.S. Vinoth Kumar, SRMIST
2. Mr. P. Ananda Natarajan, Senior Associate Consultant, Infosys, Chennai., anand_adnan@yahoo.com		2. Dr. MB. Mukesh Krishnan, SRMIST

Course Code	18CSO102T	Course Name	MOBILE APPLICATION DEVELOPMENT				Course Category	O	Open Elective										L	T	P	C		
															3	0	0	3						
Pre-requisite Courses	Nil		Co-requisite Courses		Nil				Progressive Courses		Nil													
Course Offering Department		Computer Science &Engg				Data Book / Codes/Standards				Nil														
Course Learning Rationale (CLR):			The purpose of learning this course is to:				Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand the basics of Android devices andPlatform.				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2 :	Acquire knowledge on basic building blocks ofAndroid programming required for Appdevelopment.							Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3		
CLR-3 :	Understand persistence Data storage mechanismin Android							L	-	-	-	H	-	-	-	-	-	-	-	-	-	-	-	
CLR-4 :	Understand advanced application concepts likenetworking, Animations and Google Maps services etc.							L	-	H	-	-	-	-	-	-	-	-	-	-	-	-	-	
CLR-5 :	Develop and publish Android applications in toAndroid Market							L	-	H	-	H	-	-	-	-	-	-	-	-	-	-	-	
Course Learning Outcomes (CLO):			At the end of this course, learners will be able to:				2	80	85	H	-	-	H	-	-	-	-	-	-	-	-			
CLO-1 :	Acquire the knowledge on Android devices and Platform				2	80	85	L	-	-	-	H	-	-	-	-	-	-	-	-	-			
CLO-2 :	Acquire knowledge on basic building blocks ofAndroid programming required for Appdevelopment.				2	75	80	L	-	H	-	-	-	-	-	-	-	-	-	-	-			
CLO-3 :	Apply the knowledge of persistence Data storage mechanismin Android				2	85	80	-	-	H	-	-	-	-	-	-	-	-	-	-	-			
CLO-4 :	Apply the knowledge in advanced application concepts likenetworking, Animations and Google Maps services etc.				2	80	75	L	-	H	-	H	-	-	-	-	-	-	-	-	-			
CLO-5 :	Design and apply the knowledge to publish Android applications in toAndroid Market				2	75	85	H	-	-	H	-	-	-	-	-	-	-	-	-	-			
Duration (hour)	9		9		7			10							10									
S-1	SLO-1	Introduction: Introduction to mobile application development, trends.		GUI for Android: Introduction to activities life-cycle		Introduction to Different Data persistence schemes		Services :introduction to services– localservice,							Introduction to Location based services									
S-2	SLO-1	introduction to various platforms,		Android v7 supportlibrary form API21 for lower versionsupport		Shared preferences		remote service and binding theservice.,							Google maps V2 services using Google API.									
S-3	SLO-1	introduction to smart phones		Intent :intent object		File Handling se		the communication between serviceand activity, Intent Service							Animations and Graphics: Property Animation .									
S-4	SLO-1	Android platform: Android platform,features and architecture,		intent filters ,addingcategories		Managing data using SQLite databa		MultiThreading: Handlers							View Animations, DrawableAnimations									
S-5	SLO-1	versions ,comparison added features in each versions.		linking activities, user interfacedesign components		Content providers:		,AsyncTask							Media and Camera API: Working withvideo and audio inputs									
S-6	SLO-1	ART(Android Runtime),ADB(AndroidDebug Bridge).		Views and View Groups: Basic views,picker views, adapter views, Menu, App Baretc, basics of screen design; differentlayouts.		user content provider		android network programming:HttpURLConnection							Camera API									
S-7	SLO-1	Development environment/IDE: Android studio and its working environment		App widgets.Lollipop Materialdesign: new themes, new widgets,Cardlayouts. RecyclerView		Android in build content providers		Connecting to REST-based and SOAP based Web services							Sensor programming: Motion sensors									
S-8	SLO-1	gradle build system, emulator setup		Fragments: Introduction to activities,				Broad castreceivers:LocalBroadcastManager,D ynamic broadcast receiver							Position sensors, Environmental sensors.									
S-9	SLO-1	Application anatomy:		activities life-cycle.				System Broadcast. PendingIntent, Notifications							Publishing Android Apps: Guide lines.									
	SLO-2	Applicationframework basics: resources layout, values,asset XML representation																						

		and generated R.java file .Android manifest file. Creating a simple application.				
S-10					Telephony Manager: Sending SMS and making calls.	policies and process of uploading Apps to Google play

Learning Resources	1. Dawn Griffiths, David Griffiths, "Head First: Android Development", O'Reilly 2015, ISBN: 9781449362188. 2. Greg Milette, Adam Stroud, "PROFESSIONAL Android™ Sensor Programming", John Wiley and Sons, Inc 2012, ISBN: 9781112650555, 9781280678943, 978111227459 3. Paul Deitel, Harvey Deitel, Alexander Wald, "Android 6 for Programmers, App Driven approach", 2015, Prentice Hall, ISBN: 9780134289366. 4. http://developer.android.com/training/index.html as on Date 21.4.2016
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Understand										
	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Analyze										
	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
	1. Dr. KHANNA NEHEMIAH, Professor, Ramanujan Computing, Anna University	1. Dr.M.UMA
		2. Dr.Ganesh Kumar, SRMIST
		3.Mr.K.Naveen

Course Code	18CSO103T	Course Name	SYSTEM MODELING AND SIMULATION	Course Category	O	Open Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Select a suitable modeling method according to problem area and assignment, and justify their choice.	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Formulate models of a system to describe the system on different levels of abstraction and from different viewpoints.		
CLR-3 :	Learn and apply the continuous system simulation		
CLR-4 :	Learn theory and probability concepts in simulation		
CLR-5 :	Learn the simulation languages and tools		

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Implement the appropriate modeling method for the given problem	2	80	85	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-2 :	Explain the system abstraction in different levels	2	75	80	H	H	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-3 :	Apply the models under continuous system simulation	2	85	80	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-4 :	Analyze the probability concepts for simulating a system	2	80	75	H	H	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-5 :	Apply tools to like GPSS and SIMSCRIPT to check model properties of a system	2	75	85	H	-	-	H	-	-	-	-	-	-	-	-	-	-	-

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Introduction to system modelling	Continuous System Simulation - Introduction	Probability Theory	Queueing Theory - Introduction
S-2	SLO-1	Modeling principles and concepts	Numerical solution of differential equations	Probability CONCEPTS IN SIMULATION -	Arrival Pattern distributions
S-3	SLO-1	Continuous systems and Discrete systems	Analog computers	Monte Carlo techniques	servicing times, queuing disciplines
S-4	SLO-1	Modeling, types of models, subsystems	Hybrid computers	Application of Monte Carlo techniques	measure of queues
S-5	SLO-1	corporate model, system study..	continuous system simulation languages CSMP	Stochastic variables	mathematical solutions to queuing problems
S-6	SLO-1	System Simulation: Techniques,	system dynamic growth models,	probability functions	Discrete system simulation: Events
S-7	SLO-1	comparison of simulation and analytical methods	logistic curves	Random Number Generation algorithms	Generation of arrival pattern
S-8	SLO-1	types of simulation, distributed log models	Illustration of Continuous System Simulation	Illustration of Probability concepts	Simulation programming tasks
S-9	SLO-1	cobweb models	Case Study	Case Study	Analysis of simulation output

Learning Resources	1. Geoffery Gordon, " System Simulation" , PHI, 2 nd edition 2. Jerry Banks , John S.Carson ,Barry Nelson, David M.Nicol, "Discrete – Event System Simulation", PHI, 3 rd edition 3. Karian. Z.A., Dvdewicz .E.Z, "Modern Statistical Systems and GPSS Simulation",Freeman, 1991
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
		1. Prof.S.S.Sridhar, SRMIST
		2. Mr. C.Arun, SRMIST

Course Code	18CSO104T	Course Name	FREE AND OPEN SOURCE SOFTWARES	Course Category	O	Open Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:	
CLR-1 :	Be exposed to the context and operation of free and open source software (FOSS) communities and associated software projects.		
CLR-2 :	Be familiar with participating in a FOSS project		
CLR-3 :	Learn scripting language like Python or Perl, Ruby		
CLR-4 :	Learn some important FOSS tools and techniques		
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:	
CLO-1 :	Install and run open-source operating systems.		
CLO-2 :	Gather information about Free and Open Source Software projects from software releases and from sites on the internet.		
CLO-3 :	Build and modify one or more Free and Open Source Software packages.		
CLO-4 :	Contribute software to and interact with Free and Open Source Software development projects.		
CLO-5 :	Identify and apply various linux commands		

Learning		
1	2	3
Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)
3	80	70
3	85	75
3	75	70
3	85	80
3	85	75

Program Learning Outcomes (PLO)														
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
L	H	-	H	L	-	-	-	L	L	-	H	-	-	-
M	H	L	M	L	-	-	-	M	L	-	H	-	-	-
M	H	M	H	L	-	-	-	M	L	-	H	-	-	-
M	H	M	H	L	-	-	-	M	L	-	H	-	-	-
H	H	M	H	L	-	-	-	M	L	-	H	-	-	-

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction-	Linux Installation and Hardware Configuration	Unix file system, Unix files, i-nodes and structure and file system related commands	Usage of design Tools like Argo UML or equivalent	Open Source Software Development
	SLO-2	Open Source, Free Software, Free Software vs. Open Source software				
S-2	SLO-1	FOSS examples	Boot Process-The Linux Loader (LILO)	Shell Programming, Shell as command processor, Shell variables	Version Control Systems like Git or equivalent	Case Study – Libreoffice -Samba
	SLO-2	FOSS Characteristics	The Grand Unified Boot loader (GRUB)			
S-3	SLO-1	FOSS History, Examples	Dual-Booting Linux and other Operating System	Creating command substitution, Scripts	Bug Tracking Systems	
	SLO-2	FOSS Copyright	Boot-Time Kernel Options			
S-4	SLO-1	Guidelines for effectively working with FOSS community	Basic Linux Commands	Creating commands for Functions, Conditionals	Package Management Systems	
	SLO-2					
S-5	SLO-1	Benefits of Community based Software Development	Linux Commands for operations - redirection, pipes, filters, job control, changing ownership/permission of files/directories	Creating commands for loops	Introduction to Programming language using Python	
	SLO-2					
S-6	SLO-1	Requirements for being open, free software, open source software	Advanced Linux Commands like curl, wget, ftp, ssh and grep	Customizing environment	Basic commands, variables, Decision Making, Lists, Modules, strings, looping,	Case Studies : Apache, BSD, Linux, Mozilla (Firefox), Wikipedia, Joomla, GCC,
	SLO-2					

S-7	SLO-1	Four degrees of freedom	X Windows System Configuration	Shell scripting for system configurations	conditional statements, classes, Exceptions	Open Office
	SLO-1				packages	
S-8	SLO-1	FOSS Licensing Models	System Administration	Shell scripting with functions and conditions		
	SLO-2	FOSS Licenses – GPL- AGPL- LGPL – FDL	Backup and Restore Procedures			
S-9	SLO-1	Implications	Strategies for keeping a Secure Server	Shell scripting with looping		
	SLO-2					

Learning Resources	1. Ellen Siever, Stephen Figgins, Robert Love, Arnold Robbins, "Linux in a Nutshell", Sixth Edition, O'Reilly Media, 2009. 2. Linux Programming Bible by John Goerzen, IDG Books, New Delhi, 2000. 3. Your Unix - The Ultimate Guide by Sumitabha Das, TMH, 2000	4. Perl Programming book at http://www.perl.org/books/beginning-perl/ . 5. Ruby programming book at http://ruby-doc.com/docs/ProgrammingRuby/ . 6. Samba: URL : http://www.samba.org/ .
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %		30 %		30 %		30 %		30 %	
	Understand										
Level 2	Apply	40 %		40 %		40 %		40 %		40 %	
	Analyze										
Level 3	Evaluate	20 %		30 %		30 %		30 %		30 %	
	Create										
	Total	100 %		100 %		100 %		100 %		-	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Bijoymon Soman Sr. Test Analyst UST Global, Philadelphia, PA, USA	1. Dr. Arun kumar M N Assistant Professor, Federal Institute of Science and Technology, Angamaly, Kerala	1. Mrs Aswathy K Cherian, SRMIST
		2. Mrs. Nimala , SRMIST

Course Code	18CSO105T	Course Name	ANDROID DEVELOPMENT	Course Category	O	Open Elective	L 3	T 0	P 0	C 3
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Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
			1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-1 :		Understand the basics of Android devices and Platform.	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-2 :		Acquire knowledge on basic building blocks of Android programming required for Application development				H	-	L	-	-	-	-	-	-	-	-	-	-	-	-
CLR-3 :		Gain knowledge to user interfaces used in android applications				L	H	H	-	-	-	-	-	-	-	-	-	-	-	-
CLR-4 :		Acquire knowledge on advanced application concepts like networking, Animations and Google Maps services etc				H	-	H	L	-	-	-	-	-	-	-	-	-	-	-
CLR-5 :		Develop and publish Android applications in to Android Market				L	L	H	-	-	-	-	-	-	M	-	-	-	-	-
CLR-6 :		Understand the knowledge of JSON and MQTT				L	-	H	H	L	-	-	-	-	-	-	-	-	-	-
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																		
CLO-1 :		To exposed to technology and business trends impacting Android Platform	2	80	85	H	-	L	-	-	-	-	-	-	-	-	-	-	-	-
CLO-2 :		Be competent with the characterization and architecture of mobile applications	2	75	80	L	H	H	-	-	-	-	-	-	-	-	-	-	-	-
CLO-3 :		To understanding enterprise scale requirements of mobile applications	2	85	80	H	-	H	L	-	-	-	-	-	-	-	-	-	-	-
CLO-4 :		To designing and developing mobile applications using one application development framework	2	80	75	L	L	H	-	-	-	-	-	-	M	-	-	-	-	-
CLO-5 :		To understand how to handle and share android data	2	75	85	L	-	H	H	L	-	-	-	-	-	-	-	-	-	-
CLO-6 :		To develop an android services and to publish android application for use	2	80	85	H	-	H	-	-	-	-	-	-	M	-	-	-	-	-

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Creating a new Android Project	Hosting a UI Fragment	Action Bar and Options Menus	Loopers, Handlers, and HandlerThread	Introduction to JSON
	SLO-2	Defining the Project and SDK setting	Creating a UI Fragment	Enabling Ancestral Navigation	Creating a search interface	JSON and Android
S-2	SLO-1	Creating an Android Virtual Device (AVD) in Android Studio	Adding a UI Fragment to the FragmentManager	An Alternative Menu Item	Hardware search button	Designing JSON and JSON Operation
	SLO-2	Android Virtual Device (AVD) in Android Studio	The FragmentManager and the fragment lifecycle	Saving and Loading Local Files	Creating an IntentService	Server reachability and Connection & Splash App
S-3	SLO-1	Configuring the Android Studio AVD Emulator	Creating User Interfaces with Layouts and Widgets	Context Menu Resource	Delayed Execution with AlarmManager	Lazy Loading Images
	SLO-2	The Emulator Environment and Toolbar Options	XML Layout Attributes	Floating Context Menu	Broadcast Intents	Lazy loading Libraries
S-4	SLO-1	Extended Control options	the Graphical Layout Tool	Contextual Action Mode	Waking Up on Boot	Lazy loading Architecture
	SLO-2	Drag and Drop Support	Creating a ListFragment	Camera I: Viewfinder	Filtering Foreground Notifications	Handling Image Assets
S-5	SLO-1	Configuring Fingerprint Emulation	Hosting a Fragment	Using the Camera API	Receivers and Long-running Tasks	Remote Crash Logs and App
	SLO-2	Android Studio Apps on a Physical Android Device	ListFragment, ListView and ArrayAdapter	Camera II: Taking Pictures and Handling Images	Browsing The Web & WebView	Push Messaging Services
S-6	SLO-1	Enabling ADB on Android based Devices	Fragment Arguments	Updating the Model Layer	Custom Views and Touch Events	Firebase Cloud Messaging
	SLO-2	Android Studio Editor	ViewPager	Updating CrimeFragment's View	Creating BoxDrawingView	Open Source Push Messaging with MQTT

S-7	SLO-1	Splitting the Editor Window, Code Completion, Statement	Dialogs	Implicit Intents	Handling Touch Events	MQTT App and Project
	SLO-2	Parameter Information, Parameter Name Hints,	Audio Playback Using MediaPlayer	Two-Pane Master-Detail Interfaces	Tracking the Device's Location	Message Brokers
S-8	SLO-1	Code Generation	Retained Fragments	Adding Layout Flexibility	Locations and the LocationManager	MQTT Broker setup for AWS
	SLO-2	Code Folding	Rotation and Retained Fragments	Activity: Fragment Boss	Receiving Broadcast Location Updates	Sending Messages with MQTT Web Clients
S-9	SLO-1	Quick Documentation Lookup	Rotation Handling and onSaveInstanceState(Bundle)	Styles And Includes	Updating the UI with Location Data	Firebase Cloud Messaging
	SLO-2	Code Reformatting	Localization	Cleaning Up with Styles	Testing Locations on Real and Virtual Devices	MQTT Push Messaging

Learning Resources	1. Neil Smyth, Kotlin / Android Studio 3.0 Development Essentials - Android 8 Edition, Payload Media, Inc. 2017 2. Bill Phillips and Brian Hardy, Android Programming: The Big Nerd Ranch Guide, Big Nerd Ranch, Inc. 2013	3. Mark Wickham, Practical Android: 14 Complete Projects on Advanced Techniques and Approaches, Apress, 2018 4. David Griffiths, Head First: Android Development, O'Reilly 2015, ISBN: 9781449362188
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50%)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#		Theory	Practice
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice		
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dinesh Babu T, Development Manager, HP India. dinesh.thavamani@hp.com		1. Mr. S. Pradeep, SRMIST
2. Suraj Sundaram, Associate IT Consultant, TCSC Canada. suraj.s@tcs.com		2. Mr. C. Arun, SRMIST

Course Code	18CSO106T	Course Name	DATA ANALYSIS IN R	Course Category	O	Open Elective	L 3	T 0	P 0	C 3
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Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:		Learning			Program Learning Outcomes (PLO)														
				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-1 :		Understand and write programs in R		Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-2 :		Gain knowledge on the working of statistical data in R																			
CLR-3 :		Gain knowledge on Linear regression and manipulation in R																			
CLR-4 :		Acquire knowledge on classification and clustering in R																			
CLR-5 :		Acquire knowledge on Linear Model selection and regularization and working it in R																			
CLR-6 :		Introduce the Tree based methods and working it in R																			
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																			
CLO-1 :		Acquire the knowledge on data analysis in R		2	80	85	H	-	-	-	H	-	-	-	-	-	-	-	-	-	-
CLO-2 :		Acquire the ability to find meaning pattern using R		2	75	80	H	H	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-3 :		Acquire the ability to find graphically interpret data in R		2	75	80	H	H	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-4 :		Apply the knowledge for implementing analytical algorithms		2	80	75	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-5 :		Handle large scale analytics projects from various domains		2	75	85	H	H	-	H	-	-	-	-	-	-	-	-	-	-	-
CLO-6 :		Develop intelligent decision support systems		2	75	80	H	-	-	H	-	-	-	-	-	-	-	-	-	-	-

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Data in data analytics	Simple Linear Regression	An Overview of Classification	Cross-Validation The Validation Set Approach
	SLO-2	NOIR classification	Estimating the coefficients	Logistic Regression - The Logistic Model	Leave-One-Out Cross-Validation
S-2	SLO-1	Introduction to R	Assessing the Accuracy of the Coefficient Estimates	Estimating the Regression Coefficients	k-Fold Cross-Validation
	SLO-2	Data types	Assessing the Accuracy of the Model	Making Predictions	Bias-Variance Trade-Off for k-Fold Cross-Validation
S-3	SLO-1	Control structures	Libraries for Simple Linear Regression in R	Multiple Logistic Regression	The Validation Set Approach in R
	SLO-2	Control structures - Using the console	Programming in simple linear regression in R	Logistic Regression for >2 Response Classes	Leave-One-Out Cross-Validation in R
S-4	SLO-1	Objects in R - Numbers, Attributes	Multiple Linear Regression - Estimating the Regression Coefficients	Linear Discriminant Analysis - Using Bayes' Theorem for Classification	k-Fold Cross-Validation .in R
	SLO-2	Vectors - create vectors	Multiple Linear Regression in R	Linear Discriminant Analysis for $p = 1$	The Bootstrap in R
S-5	SLO-1	Using [] brackets	Extensions of the Linear Model	Linear Discriminant Analysis for $p > 1$	Linear Model Selection and Regularization-Subset Selection
	SLO-2	Vectorized operations	Potential Problems	Quadratic Discriminant Analysis	Stepwise Selection Choosing the Optimal Model
S-6	SLO-1	Matrix -building a matrix, Naming dimensions, Colnames and Rownames	The Marketing Plan	Logistic Regression, LDA,	Shrinkage Methods Ridge Regression
	SLO-2	Matrix operations, Visualizing with Matplot()	Comparison of Linear Regression with K-Nearest Neighbors	QDA, and KNN in R - T	The Lasso Selecting the Tuning Parameter

S-7	SLO-1	Data frame	Qualitative Predictors	Example using Stock Market Data	Dimension Reduction Methods Principal Components RegressionP	Principal Components Analysis in R
	SLO-2	List	Extensions of the Linear Model	Logistic Regression in R	Partial Least Squares	More on PCA - Other Uses for Principal Components
S-8	SLO-1	Functions	Interaction Terms in R	Linear Discriminant Analysis in R	Best Subset Selection in R	Clustering Methods- K-Means
	SLO-2	Indexing data	Non-linear Transformations of the Predictors in R	Quadratic Discriminant Analysis in R	Forward and Backward Stepwise Selection in R	Hierarchical Clustering
S-9	SLO-1	Reading data	Qualitative Predictors in R	K-Nearest Neighbors in R	Choosing Among Models Using the Validation Set Approach and Cross-Validation in R	K-Means Clustering in R
	SLO-2	Writing data	Writing Functions for linear regression in R	An Application to Caravan Insurance Data in R	Ridge Regression and the Lasso in R	Hierarchical Clustering in R

Learning Resources	1. G James, D. Witten, T Hastie, and R. Tibshirani, <i>An Introduction to Statistical Learning: with Applications in R</i> , Springer, 2013 2. Chambers, John, <i>Software for Data Analysis Programming with R</i> , Springer, 2008 3. Trevor Hastie Robert Tibshirani Jerome Friedman, <i>The Elements of Statistical Learning, Data Mining, Inference, and Prediction (2nd Edn.)</i> , Springer, 2014	4. Mark Gardener, <i>Beginning R: The Statistical Programming Language</i> , Wiley, 2013 5. Upadhyaya and A. Upadhyaya, <i>Material Science and Engineering</i> , Anshan Publications, 2007

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50%)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Understand										
	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Analyze										
	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Venkatesh K. Pappakrishnan, Ph.D. Data scientist Physicist, Santa Clara, California	1. Dr. J. Prakash, MIT, Chennai, prakaiti@rediffmail.com	1. Dr.V.Kavitha, SRMIST
2. Prakash V, Technical Lead at Bridgeline Digital Inc Greater Boston Area	2.Dr. Latha Karthigaa, PhD , Innovation Research Assistant, The University of Auckland	2. Dr.Alice Nithya, SRMIST

Course Code	18CSO107T	Course Name	IOS DEVELOPMENT	Course Category	O	Open Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	CSE	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
		1	2	3	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-1:	Understand the basics of ios device and platform	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3			
CLR-2:	Understand the basic building blocks of ios programming required for App development																					
CLR-3:	Understand Data storage mechanism in ios																					
CLR-4:	Understand advanced application concepts like animations, webservices,etc																					
CLR-5:	Develop and publish ios application in to ios market																					
CLR-6:	understanding enterprise scale requirements of mobile application																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1:	Acquire the knowledge of ios device and platform	2	80	85	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-2:	Acquire the knowledge on ios programming for App Development	2	75	80	H	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-3:	Apply the concepts used for data storage in ios	2	85	80	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-4:	Apply the animation and webservice concepts in the App	2	80	75	H	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-5:	Understand the basic idea to publish ios application into ios market	2	75	85	H	-	-	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-6:	Understand the needs of enterprise to develop App	2	80	85	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Top Mobile OS in Market	The Swift Language-Types	Programmatic views-anchors,Margins	Stack Views
	SLO-2	Difference between IOS and Android	Literals and subscripting, Initializers, Properties, Instance methods	Programmatic controls	Nested stack views
S-2	SLO-1	IOS Architecture	Optionals,Subscripting dictionaries, Loops and String Interpolation	Localization	Segues
	SLO-2		Enumerations		JSON Data
S-3	SLO-1	History of IOS	Views-Basics	Internalization	UINavigationController
	SLO-2		Frames, Customizing the labels		Dismissing the keyboard
S-4	SLO-1	Requirements	The auto Layout System	Controlling Animations	Even handling basics
	SLO-2		Adding Constraints	Completion,constraints	Extensions
S-5	SLO-1	Versions	Text Input- Editing,Keyboard attributes	Timing functions	Camera
	SLO-2				Image caching
S-6	SLO-1	Framework -MVC Design Pattern	Dismissing the keyboard	Debugging	Saving,Loading and Application States
	SLO-2		Number formatters		Core Data
S-7	SLO-1	Application Life Cycle	Delegation	UITableView and Controller	Loading files, Error handling
	SLO-2		Conforming to a protocol		Fetch requests and predicates
S-8	SLO-1	Features	View controllers	Editing UITableView	Size class
	SLO-2		UITabBarController		Core Data Relationships
S-9	SLO-1	A simple IOS Application	Appearing and accessing views	Subclassing UITableViewcell	Touch Events and UIResponder
	SLO-2				Accessibility

Learning Resources	1. ChristianKeur,AaronHillegass,iosprogramming:TheBigNerdRanchGuide,6 th ed.,Pearson,2016. 2. Jon Hoffman, Mastering Swift,4 th ed.,Packt Publishing Ltd.,2017.	3. Fahim Farook, Matthijs Hollemans, ios Apprentice,7 th ed.,Razeware LLC,2018. 4. Michael Grant, ios Navigation101,2019.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50%)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Understand	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Apply										
Level 3	Analyze	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Evaluate										
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.K.Mahendran, Founder, Dreams Technologies, Chennai.	1.	1. Dr.D.Rajeswari, SRMIST
2.	2.	2. Mr.K.Navin, SRMIST

Course Code	18EE0301T	Course Name	SUSTAINABLE ENERGY	Course Category	O	Open Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)															
CLR-1 :	Enrich the students on the basics of solar energy				Level of Thinking (Bloom)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Develop the knowledge in wind energy conversion system					Expected Proficiency (%)																	
CLR-3 :	Understand the energy generation by biomass					Expected Attainment (%)																	
CLR-4 :	Gain knowledge on ocean ,tidal energy																						
CLR-5 :	Acquire knowledge in fuel cell and its types																						
CLR-6 :	Apply the concepts of renewable energy in industrial applications																						
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																					
CLO-1 :	Obtain in depth knowledge on solar applications				2	80	75	H	M	M	-	-	-	-	L	-	-	-	-	-	H	M	-
CLO-2 :	Explain the concepts of wind energy conversion systems and their control				3	80	75	H	M	M	-	-	-	-	L	-	-	-	-	-	H	M	-
CLO-3 :	Summarize the biomass technologies and calculate the power conversion of biomass digestion				3	80	75	H	M	-	-	-	-	-	L	-	-	-	-	-	H	M	-
CLO-4 :	Interpret the environmental impacts of ocean and tidal energy				3	80	75	H	M	-	-	-	-	-	L	-	-	-	-	-	H	M	-
CLO-5 :	Summarize the working principle of fuels cells and its types				3	80	75	H	M	-	-	-	-	-	L	-	-	-	-	-	H	M	-
CLO-6 :	Infer the knowledge about various types of renewable energy systems				3	80	75	H	M	M	-	-	-	-	L	-	-	-	-	-	H	M	-

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Solar radiation	Wind energy conversion	Biogas	Ocean thermal energy conversion	Fuel Cell
	SLO-2 Beam and diffuse radiation, solar constant, earth	Principles of Wind energy conversion	Energy from Biomass	Principle of OTEC	Basics of Fuel cell
S-2	SLO-1 Sun angles	Nature of the wind	Types of biomass	Lambert law of absorption	Components of fuel cells
	SLO-2 Calculation of angle of incidence	Factors influencing wind	Photosynthesis	OTEC power plant	Difference between batteries and fuel cell
S-3	SLO-1 Attenuation and measurement of solar radiation	Wind data and energy estimation- wind speed monitoring,	Factors affecting digestion system	Open loop system for ocean energy conversion	Types of fuel cells
	SLO-2 Local solar time, derived solar angles, sunrise, sunset and day length	Site selection	Classification of biogas plants	Closed loop system for ocean energy conversion	Ionic conductivity of fuel cell
S-4	SLO-1 Flat plate collectors, concentrating collectors	Power in the wind	Advantages and disadvantages of biogas plants	Single basin	Electronic conductivity in fuel cell
	SLO-2 Solar air heaters, types, solar driers	Betz limit	Factors affecting bio digestion	dual basin ocean energy conversion system	Principle of working of fuel cell
S-5	SLO-1 Storage of solar energy, thermal storage	Components of a wind energy conversion system	Biomass as Renewable Energy Source	Major problems and operational experience Tidal energy	Performance characteristics of fuel cells
	SLO-2 Solar pond , solar water heaters	Torque on wind	Cofiring	Site selection of tidal power plant	Selection of fuel cells
S-6	SLO-1 Solar distillation	Wind thrust calculations Repowering concept	Dry Process	Tide ,Spring tide	Fuel cell stack
	SLO-2 Solar Pond	Horizontal Axis Wind Turbine(HAWT design consideration)	Photosynthesis	Neap tide, Tidal range	fuel cell power plant
S-7	SLO-1 Solar heating & cooling of buildings	Tip Speed Ratio	Energy forming	Types of Tidal power plant	Cross section of typical PEM fuel cell
	SLO-2 Solar still, solar cooker	Solidity	Pyrolysis	Advantages and disadvantages of tidal power plant	Storage methods for fuel cells
S-8	SLO-1 Photo voltaic. Types of PV cells	Types of generators and power converters in WECS	Types of Biomass Fuels	Wave Energy	Challenges and trends in fuel cell

	SLO-2	Characteristics and working principles of PV	Control schemes for power converters.	Biomass power plant	Wave Characteristics	Efficiency of fuel cell
S-9	SLO-1	Maximum power point tracking methods	Introduction to grid integration of WECS	Biomass cogeneration	Different wave energy convertors, Saltor Duck	Applications of fuel cell
	SLO-2	Net metering concepts	Issues in grid integration	Digester design	Oscillating water column and dolphin types	Advantages and disadvantages of fuel cell

Learning Resources	1. Rai, G.D., Non Conventional sources of Energy, Khanna Publishers, 5th Edition 2016. 2. Khan, B.H., "Non-Conventional Energy Resources", The McGraw Hills, 2nd Edition, 2016	3. O'Hayre, R.P., S. Cha, W. Colella, F.B. Prinz, Fuel Cell Fundamentals, Wiley, NY (2006). 4. https://onlinecourses-archive.nptel.ac.in/ .
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Er.P.Velumani, TANGEDCO, velumaniyazhini@gmail.com	1. Dr.P.Dhamodharan, IITM, damodharan@iitdm.ac.in	1. Dr.K.Saravanan, SRM IST
2. Er.R.Ramanavasulu, BAVINI, BARC, ramanavasulu@igcar.gov.in	2. Dr.S.Kumaravel, NIT Calicut, kumaravel_s@nitc.ac.in	2. Dr.R.Sridhar, SRM IST

Course Code	18EE0302T	Course Name	ANALOG ELECTRONICS	Course Category	O	Open Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:		Learning			Program Learning Outcomes (PLO)														
		1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-1 :	Know the basic amplifier circuits			Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-2 :	Acquire knowledge on different power amplifiers																				
CLR-3 :	Construct different waveform generating circuits																				
CLR-4 :	Discuss the basics of operational amplifiers																				
CLR-5 :	Understand different analog to digital and digital to analog converters																				
CLR-6 :	Design amplifier circuits using transistor and operational amplifiers																				
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																			
CLO-1 :	Analyze the amplifier circuits using small signal model and hybrid model			2	75	75	H	M	-	H	-	-	-	-	-	-	-	M	L	-	
CLO-2 :	Recognize the different power amplifiers			2	75	75	H	M	-	H	-	-	-	-	-	-	-	M	L	-	
CLO-3 :	Design oscillators and multivibrators			3	75	75	H	M	H	M	-	-	-	-	-	-	-	M	L	-	
CLO-4 :	Apply different operational amplifiers			2	75	75	H	-	-	-	-	-	-	-	-	-	-	M	L	-	
CLO-5 :	Evaluate filters and converter circuits			3	75	75	H	L	H	M	H	-	-	-	-	-	-	M	L	-	
CLO-6 :	Demonstrate various electronic circuits for real time applications			2	75	75	H	M	H	H	H	-	-	-	-	-	-	M	L	-	

Duration (hour)	9	9	9	9	9
S-1	SLO-1	BJT -Biasing methods -Base bias, base bias with emitter feedback	Power amplifiers – Types. Determination of efficiency for class A and class B power amplifiers	Oscillators and classification of oscillators	Introduction to Linear Integrated Technology
	SLO-2	Base bias with collector feedback and voltage divider bias	Frequency response of RC coupled class A amplifier	Design and Analysis of RC Phase shift oscillator.	Fabrication process for Integrated Circuits
S-2	SLO-1	Emitter bias using BJT in CE configuration	Frequency response of Transformer coupled class A amplifier	Operation of Hartley's oscillator	DC characteristics of op amp and input bias current.
	SLO-2	Transistor biasing stability using BJT in CE configuration	Operation of Class B push pull power amplifier	Analysis of Hartley's oscillator	Input offset voltage, Thermal Drift
S-3	SLO-1	Operation of BJT as an amplifier.	Operation of Differential amplifier	Operation of Armstrong oscillator	AC characteristics of op-amp and Frequency Response characteristics
	SLO-2	CE, CB, CC Amplifier –Evaluation of h parameters	Analysis of Differential amplifier	Operation of UJT Relaxation oscillator	Frequency compensation and Slew rate
S-4	SLO-1	Small signal analysis of CE Amplifier	Self – biased active load differential amplifier	Operation of Cross coupled Oscillator	Inverting amplifier and Non-inverting amplifier
	SLO-2	Small signal analysis of CB and CC amplifier	Source degenerated common source amplifier	Integrators	Summer and Subtractor
S-5	SLO-1	Large signal analysis of CE Amplifier	Classification of class C power amplifiers (Tuned amplifiers)	Differentiators	Voltage follower and ac amplifiers
	SLO-2	Large signal analysis of CB and CC amplifier	Frequency response of Single, Double and Staggered Tuned Class C power amplifiers	Schmitt trigger	V to I and I to V converters
S-6	SLO-1	JFET - CS Amplifier - Operation	Cascode and Cascaded circuits	Multivibrator and classification of multivibrators. Operation of Astable Multivibrator.	Instrumentation amplifier
					Counter type ADC

	SLO-2	CS Amplifier – small signal analysis	Feedback amplifiers - Barkhausen criterion and Types of feedback amplifier	Analysis of Astable Multivibrator	Log and Antilog amplifiers	Sigma Delta type ADC
S-7	SLO-1	JFET - CD Amplifier - Operation	Analysis of voltage series feedback amplifier	Operation of Monostable Multivibrator.	Comparators and classification of comparators.	Successive approximation type ADC
	SLO-2	Small signal analysis of MOSFET	Analysis of voltage shunt feedback amplifier	Analysis of Monostable Multivibrator.	Applications of Comparators	Digital to Analog converters
S-8	SLO-1	Biasing of MOSFET	Analysis of current series amplifier	Operation of Bistable Multivibrator.	Basics of IC 555 Timer and Pin Details	Pulse width modulator DAC
	SLO-2	CD Amplifier – small signal analysis	Analysis of current shunt feedback amplifier	Analysis of Bistable Multivibrator.	Astable operation using IC 555 Timer with applications	R -2R Ladder DAC
S-9	SLO-1	Problems on biasing of circuits	Problems on power amplifiers	Voltage and time-based circuits.	Monostable operation using IC 555 Timer with applications	Inverted R-2R Ladder DAC
	SLO-2	Problems on hybrid parameters	Problems on feedback amplifiers	Series and shunt voltage regulator	Voltage regulator using IC 723	Binary coded DAC

Learning Resources	1. Jacob Millman, Christos C.Halkias, Satyabrata Jit, Millman's Electronic Devices and Circuits, 4 th ed., Tata McGraw Hill, 2015 2. Boylestead, Nashelsky, Electronic Devices and Circuit Theory, 11 th ed., Pearson, 2015 3. David A. Bell, Electronic Devices and Circuits, 5 th ed., PrenticeHall, 2004	4. Sergio Franco, Design with operational amplifiers and Analog Integrated circuits, 5 th Edition, McGraw-Hill, 2014 5. Roy Choudhary and Shail Jain, Linear Integrated Circuits, 4 th ed., New Age International Publishers, 2014. 6. https://ocw.mit.edu/courses/electrical-engineering-and-computer-science/6-002-circuits-and-electronics-spring-2007/syllabus/
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. S.Paramasivam, Danfoss Industries Pvt Ltd, paramsathya@yahoo.com	1. Dr.P.Satheesh Kumar, Anna University, silkart@gmail.com	1. R.C.Ilbairai, SRMIST
2. A.Thiyagarajan, TANGEDCO, athiyagu3177@gmail.com	2. Dr.S.Kamalakaran, Anna University, kamalakannan1612@gmail.com	2. Dr.K.Mohanraj, SRMIST

Course Code	18EEO303T	Course Name	ELECTRICAL MATERIALS	Course Category	O	Open Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand the basics of electrical materials	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Describe conducting and dielectric materials	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Explore knowledge on the insulating and magnetic materials																		
CLR-4 :	Acquire knowledge on superconducting materials																		
CLR-5 :	Interpret optical phenomena on electrical materials																		
CLR-6 :	Enrich the students on different electrical materials and its applications																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Outline the electrical and electronics materials, their importance, classification and operational requirement	2	80	75	H	L	L	-	-	-	M	-	-	-	-	-	M	M	-
CLO-2 :	Obtain knowledge on conducting and dielectric materials used in engineering application	2	80	75	H	L	L	-	-	-	M	-	-	-	-	-	M	M	-
CLO-3 :	Gain idea on insulators and magnetic materials used in engineering, their properties and classification	2	80	75	H	L	L	-	-	-	M	-	-	-	-	-	M	M	-
CLO-4 :	Define the phenomenon superconductivity, super conducting materials and their application in engineering	2	80	75	H	L	L	-	-	-	M	-	-	-	-	-	M	M	-
CLO-5 :	Understand optical characteristics of conducting and non-conducting electrical materials	2	80	75	H	L	L	-	-	-	M	-	-	-	-	-	M	M	-
CLO-6 :	Summarize the different electrical materials and its applications	2	80	75	H	L	L	-	-	-	M	-	-	-	-	-	M	M	-

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Importance of materials	Types of conducting materials	Insulating materials– Ceramic, Mica, Porcelain, Glass, Micanite and Glass bonded mica	Concept of superconductors	Introduction to Thermoplastics
	SLO-2	Classification of electrical and electronic materials	Low resistivity materials, High resistivity materials	Insulating material applications	Meaning of phenomenon of superconductivity	Introduction to Rubbers
S-2	SLO-1	Scope of electrical and electronic materials	Contact materials	Polymeric materials – Bakelite, Polyethylene. Natural and synthetic rubber and paper	Properties of superconductors	Introduction to Thermosets
	SLO-2	Requirement of Engineering materials	Fusible materials	Choice of solid insulating material for different applications	Types of superconductors	DC and AC properties of plastics
S-3	SLO-1	Classification of solids on the basis of energy gap	Filament materials	Liquid insulating materials requirements	Critical magnetic field	Mechanical properties and processing of plastic
	SLO-2	Types of engineering materials, Levels of material structure	Carbon as filamentary and brush material	Transformer oil, Bubble theory, Aging of mineral insulating oils.	Critical temperature	Materials for Opto – Electronic Devices - Introduction
S-4	SLO-1	Spintronic and its materials	Material for conductors, cables,	Gaseous insulating Materials – Air	Effects of Isotopic mass on critical temperature	Optical phenomena
	SLO-2	Ferromagnetic semiconductors, Left handed materials	Material for wires, solder, sheathing and sealing	Gaseous insulating Materials –Nitrogen, Vacuum	Silsbee rule	Reflection and Refraction
S-5	SLO-1	Conductor materials	Introduction to dielectric materials	Origin of permanent magnetic dipole, Magnetic terminology,	Depth of penetration	Transmittivity and Scattering,
	SLO-2	Factors affecting conductivity	classification of dielectric materials	Relation between relative permeability and magnetic susceptibility	Coherence length	Optical absorption
S-6	SLO-1	Thermal conductivity	Dielectric constant	Classification of magnetic materials - Diamagnetic, Paramagnetism, Ferromagnetism	Ideal and Hard superconductors	Optical properties of non-metals

	SLO-2	Heating effect of current	Dielectric strength and Dielectric loss	Anti-ferromagnetism and the corresponding materials	Mechanism of super conduction	Optical properties of metals
S-7	SLO-1	Thermoelectric effect	Polarization, Mechanisms of polarization	Ferrimagnetism and ferrites properties and applications	London's theory for Type I superconductors, GLAG theory for Type I superconductors	Optical properties of semiconductors
	SLO-2	Seebeck effect	Comparison of different polarization process	Ferrimagnetism and ferrites applications	BCS theory, Applications and limitations	Penetration depth and absorption coefficient
S-8	SLO-1	Thomson effect	Factors affecting polarization	Soft and hard ferrites. Curie temperature	Applications of high temperature superconductors	Optical properties of insulators
	SLO-2	Thomson effect's application	Spontaneous polarization	Laws of magnetic materials.	Superconducting solenoids and magnets	Luminescence
S-9	SLO-1	Wiedemann – Franz law	Behaviour of polarization under impulse and frequency switching	Magnetization curve, Initial and maximum permeability	MRI for medical mechanism	Opto – Electronic devices, Photoconductivity
	SLO-2	Lorentz relation	Decay and build-up of polarization under ac field	Hysteresis loop and loss, Eddy current loss	MRI for medical diagnostics	Photoconductive cell

Learning Resources	1. K.M. Gupta Nishu Gupta, Advanced Electrical and Electronics Materials; Processes and Applications, Wiley, First Edition, 2015 2. R.K. Shukla, Archana Singh, Electronic Engineering Materials, McGraw Hill, 2012 3. Solymar, Electrical Properties of Materials, Oxford , 9th Edition, 2014	4. A.J. Dekker, Electrical Engineering Materials, Pearson, 2016 5. S.O. Kasap, Principle of Electronic Materials and Devices , McGraw Hill, 3rd Edition, 2010 6. https://nptel.ac.in/courses/122102008/36
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.S.Sambath, TANGEDCO Tamilnadu, yeses.eng@gmail.com	1. Dr.Chandramohan, CEG, Anna University, c_dramo@annauniv.edu	1. Dr. C. Subramani, SRMIST
2. Mr. R. Ramanavasulu, BHAVINI, Kalpakkam. ramanavasulu@igcar.gov.in	2. Dr. Srinivasan Mallan, Bannari Amman Institute of Technology, Coimbatore. srinivasanm@bitsathy.ac.in	2. Dr. S. Vidyasagar, SRMIST

Course Code	18EE0304T	Course Name	POWER PLANT ENGINEERING	Course Category	O	Open Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)															
CLR-1:	Provide an overview on power generation through various methods			Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Gain knowledge of power plant measurements and devices				Expected Proficiency (%)	Expected Attainment (%)	Problem Analysis		Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3		
CLR-3:	Categorize the various analyzer In Power Plants																						
CLR-4:	Get detailed knowledge on Nuclear power plant																						
CLR-5:	Outline the concept of Renewable energy																						
CLR-6:	Educate various concept in conventional and non-conventional resources																						
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			2	80	75	H	-	-	-	-	-	H	-	-	-	-	-	H	M	H	
CLO-1:	Familiarize about different power generation process			3	80	75	H	M	-	-	-	-	M	M	-	-	-	-	-	M	M	M	
CLO-2:	Understand the various measurement techniques in power plant			3	80	75	H	M	-	-	-	-	M	M	-	-	-	-	-	H	M	M	
CLO-3:	Analyze important parameter for control of power plant			3	80	75	H	M	-	-	-	-	M	M	-	-	-	-	-	H	M	M	
CLO-4:	Summarize the working of Nuclear Reactor			3	80	75	H	M	-	-	-	-	M	M	-	-	-	-	-	H	H	M	
CLO-5:	Employ the acquired knowledge of Renewable energy in power plant			3	80	75	H	-	-	-	-	-	M	M	-	-	-	-	-	H	M	M	
CLO-6:	Gain knowledge on various concepts related to Power Plant Engineering			3	80	75	H	M	-	-	-	-	M	M	-	-	-	-	-	H	M	M	

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Brief survey of methods of power generation	Electrical measurements: Current, Voltage	Introduction of Flue gas	Basics of Nuclear Engineering	Hydro Electric Power Plants
	SLO-2	Thermal power	Power, Frequency, Power factor	oxygen analyzer	Layout and subsystems of Nuclear Power Plants	Elements of Hydro-electric power plant
S-2	SLO-1	Overview of Nuclear	Non– electrical parameters: Flow of feed water	Analysis of impurities in feed water	Fission reactions	Types of Dams
	SLO-2	Solar and Wind power	Flow of feed fuel	Analysis of impurities in feed steam	Working of Nuclear Reactors	classification of Hydro-electric power plants
S-3	SLO-1	Importance of instrumentation in power generation	Flow of feed air	Dissolved oxygen analyzer	Classification of Reactors	Hydro sources and power plants Energy strategies
	SLO-2	Factors affecting power plant	Steam pressure	Dissolved oxygen analyzer working principle	Nuclear reactor control loops	Size of the plant and choice of units
S-4	SLO-1	Building blocks for all types of power generation plants	Steam temperature	Methods of measuring dissolved oxygen	reactor dynamics	Typical Layout and associated components including Turbines
	SLO-2	Hydro and Thermal power plant	Drum level measurement	Chromatography-principles-applications	Boiling Water Reactor (BWR)	Turbine Governing
S-5	SLO-1	Building blocks for all types of power generation plants	Radiation detector	Types of Chromatography- Gas Chromatography	Pressurized Water Reactor (BWR)	Comparison of hydro and steam power plant
	SLO-2	Nuclear- Solar power	Smoke density measurement	Liquid Chromatography	CANada Deuterium-Uranium reactor (CANDU), Breeder	Cost of Hydroelectric Power Plant
S-6	SLO-1	Building blocks for all types of power generation plants-wind power	Dust monitor	PH meter	Gas Cooled Reactor	Principle, Construction and working of Wind energy
	SLO-2	Tidal power plant	flame monitoring	PH meter-design and working principle	Liquid Metal Cooled Reactor	Principle, Construction and working of tidal energy and Types of tidal power plants
S-7	SLO-1	Details of boiler process	speed vibration	Classifications of Analyzer	Economics of Nuclear Power Plants	Solar Photo Voltaic cell (SPV)

	SLO-2	P&I diagram of boiler	shell temperature	Fuel analyzer	Nuclear power plant in India	Solar thermal power systems use concentrated solar energy
S-8	SLO-1	Piping diagram of boiler	pedestal vibration	Portable fuel property analyzer	Uranium Enrichment	Geo Thermal power plants - types
	SLO-2	Instrumentation diagram of boiler	shaft vibration	Natural Gas analyzer	instrumentation diagram of different types of nuclear power plant	Biogas Photosynthesis and origin of biogas energy
S-9	SLO-1	Power plant performance efficiency	eccentricity measurement	Pollution monitoring instruments	Control Safety measures for Nuclear Power plants	Biogas energy resources
	SLO-2	Cogeneration system	temperature monitoring & control	Pollution control technologies	Waste Disposal Options for Coal and Nuclear Power Plants	Fuel Cell power systems

Learning Resources	1. K. Krishnaswamy, M. Ponnibala, Power Plant Instrumentation, PHI Learning Pvt Ltd., 2013. 2. Philip Kiamah, Power Plant Instrumentation and Controls, McGraw-Hill Professional, 2014. 3. David Lindsley, Power-plant Control and Instrumentation: The Control of Boilers and HRSG Systems, IET, London, 2000.	4. G. F. Gilman, Jerry Gilman, Boiler Control Systems Engineering, ISA, 2010. 5. G.R.Nagpal, Power Plant Engineering, khanna Publisher, 2005 6. M.M. El-Wakil, Power Plant Engineering, Tata McGraw – Hill Publishing Company Ltd., 2010
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Sitangsu Sekhar Biswas, Bhavini, biswas@bhavini.gov.in	1. Dr. P. SOMASUNDARAM, CEG, Anna University, mpsomasundaram@annauniv.edu	1.Mr.R.Senthilkumar, SRMIST
2.Mr Ramanavas, Bhavini, ramanavas@igcar.gov.in	2.Dr.S.K.Patnaik, CEG, Anna University, skpatnaik@annauniv.edu	2.Dr.S.Padmini, SRMIST

Course Code	18EE0305T	Course Name	ELECTRICAL DRIVES	Course Category	O	Open Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 : <i>Enrich the students on the basics of electric drives</i>		1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 : <i>Learn the concepts of DC motor drives and its speed control</i>		Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 : <i>Familiarize the power electronic based speed control of induction motor drives</i>		Expected Proficiency (%)	Problem Analysis
CLR-4 : <i>Get an idea of speed control of synchronous motor</i>		Expected Attainment (%)	Design & Development
CLR-5 : <i>Understand the basic of digital speed control techniques</i>			Analysis, Design, Research
CLR-6 : <i>Get an idea about selection of drives and control schemes</i>			Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 : <i>Acquire knowledge on the concept of electric drives</i>		2 80 75	H L L L - - - - - M M -
CLO-2 : <i>Analyze the concept & characteristics of dc motors</i>		3 80 75	H M M M M - - - - M M -
CLO-3 : <i>Interpret of speed-control of induction motors</i>		3 80 75	H M M M M - - - - M M -
CLO-4 : <i>Get detailed knowledge on synchronous motor drives</i>		3 80 75	H M M M - - - - - M M -
CLO-5 : <i>Apply the digital speed control techniques for various drives</i>		2 80 75	H M L L - - - - - M M -
CLO-6 : <i>Apply the drives and control schemes for real time applications</i>		3 80 75	H M M M M - - - - M M -

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Electric drives - Advantage of electric drives	DC Motor Drives:-Introduction	Induction motor drives-Introduction	Synchronous motor drives – introduction
	SLO-2	Block diagram of electric drives	DC motor and their performance	Advantages and Disadvantages	Synchronous Motor Drives
S-2	SLO-1	Selection of motor power rating	Braking methods	Stator control of IM	Speed control of synchronous motors
	SLO-2	Thermal Modeling	Ward Leonard drives	Stator voltage control	Synchronous motors – Frequency control
S-3	SLO-1	Thermal model of motor for heating and cooling	Transformer fed DC drive	Stator Frequency control	Synchronous motors – Start with Prime mover & damper winding
	SLO-2	Thermal model of motor for heating and cooling - derivation	Uncontrolled rectifier fed DC drive	Stator Frequency control – advantages and disadvantages	Synchronous motors –damper winding
S-4	SLO-1	Classes of motor duty cycle	Single phase half controlled rectifier fed DC drives - operation	V/F control	Voltage Source Inverter fed synchronous motor
	SLO-2	Determination of motor rating	Single phase half controlled rectifier fed DC drives - derivation	Closed loop V/F control	Chopper fed VSI with synchronous motor
S-5	SLO-1	Control of electric drives	Single phase fully controlled rectifier fed DC drive- operation	Cycloconverter - introduction	Current Source Inverter fed synchronous motor
	SLO-2	Modes of operation	Single phase fully controlled rectifier fed DC drive- derivation	Cycloconverter fed induction motor drive	Chopper fed CSI with synchronous motor
S-6	SLO-1	Speed control of electric drives	Chopper - introduction	VSI Inverter fed induction motor drives	Cycloconverter fed synchronous motors
	SLO-2	Drive classifications	Chopper controlled DC drives	Comparison: VSI and CSI	Limitations - Cycloconverter fed synchronous motors
S-7	SLO-1	Closed loop control of drives	Time ratio control	Rotor control	Self control
	SLO-2	Speed, torque and current control	Current limit control	Rotor resistance control	Separate control
S-8	SLO-1	Multiquadrant operation of electrical drive	Single, two quadrant operations	Slip power recovery schemes	Open loop operation of synchronous drive

	SLO-2	Torque equation for rotating system	Four quadrant operation	Static Kramer & static scherbius scheme	Closed loop operation of synchronous drive	Control schemes for crane
S-9	SLO-1	Speed torque characteristics	Simulation of 1-phase rectifier fed DC motor	Simulation of three phase VSI using SPWM	Closed loop operation of power factor control	FPGA based control of electric drives
	SLO-2	Applications of electric drives	Simulation of 3-phase rectifier fed DC motor	Simulation of three phase VSI using pulse generator	Applications synchronous drive	Application of Digital technique in speed control

Learning Resources	1. G. K. Dubey, <i>Fundamentals of Electrical Drives</i> , Second Edition, CRC Press, 2010. 2. R. Krishnan, <i>Electric Motor Drives: Modeling, Analysis and Control</i> , Second Edition, Prentice Hall, 2008.	3. W. Leonhard, <i>Control of Electric Drives</i> , Springer Science & Business Media, Third Edition, 2001. 4. https://onlinecourses-archive.nptel.ac.in/ .
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. A.Kannan, Seshasayee paper and board limited akannan@sbppapers.com	1. Dr. S. Ramareddy, Jerusalem College of Engineering, srr.victory@gmail.com	1. R.Palanisamy, SRMIST
2. Mr. M.Jayakumar, Danfoss, Industries Pvt Ltd., jaya.kumar@danfoss.com	2. Dr. A. Venkadesan, NIT Puducherry, venkadesan@nitpy.ac.in	2. Dr.K.Mohanraj, SRMIST

Course Code	18EE0306T	Course Name	ENERGY CONSERVATION	Course Category	O	Open Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Outline the concepts of world energy scenario in industries	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Describe the basics of electrical system	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Impart knowledge on various methods of improving energy efficiency in industries				H	-	-	-	-	-	-	-	-	-	-	-	L	L	L
CLR-4 :	Give an overview about the energy policies, energy planning and policy making in India				H	-	-	-	-	-	-	-	-	-	-	-	M	M	M
CLR-5 :	Provide an understanding of the basics of energy conservation method and energy auditing in industries				H	-	-	-	-	H	H	-	-	-	-	-	M	H	M
CLR-6 :	Create overall structure of energy conservation starting from environmental aspects to energy management systems				H	-	-	-	-	L	H	-	-	-	-	-	M	M	H
					H	-	-	-	-	L	H	M	M	-	-	-	M	H	M
					H	-	-	-	-	M	H	M	M	-	-	-	M	M	H
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	2	75	75															
CLO-1 :	Gain knowledge of world energy scenario	3	75	75															
CLO-2 :	Understand the concepts of electrical system	3	75	75															
CLO-3 :	Assess the energy efficiency in industrial system	3	75	75															
CLO-4 :	Analyse the energy policies, energy planning and policy making in india	3	75	75															
CLO-5 :	Correlate with various methods of energy conservation	3	75	75															
CLO-6 :	Implement energy conservation methods and laws to save energy	3	75	75															

Duration (hour)	9	9	9	9	9
S-1 SLO-1	Energy classificatios	Introduction Electrical Systems	Air condition and refrigeration	Introduction to energy policy	Investment - need, appraisal and criteria
SLO-2	Power Past & Present scenario of World	Electrical network types and classifications	Diesel Generator	National energy policy in the last plan periods	Financial analysis techniques
S-2 SLO-1	Sectorial energy consumption	HT supply	Energy Efficiency in Building	ISO-50001, PDCA, PAT scheme	Simple payback period
SLO-2	domestic, industrial and other sectors	LT supply	Energy Efficiency in Building	BEE & State Development Agencies & EESL Programmes	Return on investment
S-3 SLO-1	energy needs of growing economy, energy intensity	Transformers and its operation	Savings opportunities in HVAC	Municipal & Agriculture DSM Initiatives	Net present value, internal rate of return, cash flows
SLO-2	long term energy scenario, energy pricing	Types of transformer	Fans and blowers	Energy use and Energy supply	Net present value, internal rate of return, cash flows
S-4 SLO-1	energy security, energy conservation	Cables – and its construction	Conservation opportunities	Overview of renewable energy policy and the Five Year Plan programme	Risk and sensitivity analysis
SLO-2	energy conservation importance, energy strategy for the future	Types and Cable Sizing	Pumps - CASE STUDY	Standards and Labelling Programme EEC initiatives in Other Sectors	Financing options
S-5 SLO-1	National Energy consumption Data	Concept of Capacitors	Control strategies	Basic concept of Input-Output analysis	Energy performance contracts and role of Energy Service Companies (ESCOs)
SLO-2	Energy Pricing	Types of Capacitors	Conservation opportunities	Concept of energy multiplier and Implication of energy multiplier for analysis of regional and national energy policy Organizational structure	Energy Monitoring
S-6 SLO-1	Environmental aspects associated with energy utilization	Power Factor Improvemen	Cooling Tower -performance	key developments and changes in India's energy policies and planning in the context of energy efficiency and environmental concerns	Targeting: Defining monitoring & targeting

	SLO-2	Environmental aspects associated with energy conservation	Harmonics	Efficient system operation	key developments and changes in India's energy policies and planning in the context of energy efficiency and environmental concerns	Targeting: Defining monitoring & targeting
S-7	SLO-1	Energy Auditing: Needs, Types,	Electric Motors – Motor Efficiency Computation	Efficient system operation	regulatory frameworks and reforms across various energy sectors	elements of monitoring & targeting
	SLO-2	Methodology and Barriers	Energy Efficient Motors	Validation of energy saving using application software	regulatory frameworks and reforms across various energy sectors	Data and information-analysis, techniques
S-8	SLO-1	Role of Energy Managers	Illumination – Lux, Lumens	Energy saving opportunities	Energy Policies success stories, failures	Energy consumption
	SLO-2	Needs of Energy Managers	Types of lighting, Efficacy	Energy saving opportunities	Energy saving potential of technology	Production, cumulative sum of differences (CUSUM).
S-9	SLO-1	Instruments for energy auditing	LED Lighting And types	Assessment of cooling towers	Energy tariffs and Energy Instrument	Energy Management Information Systems (EMIS)
	SLO-2	Energy conservation	Scope Of Encon In Illumination	Assessment of cooling towers	CASE STUDY for energy tariffs in industry	Energy Management Information Systems (EMIS)

Learning Resources	1. Witte. L.C., P.S. Schmidt, D.R. Brown, <i>Industrial Energy Management and Utilisation</i> , Hemisphere Publ, Washington, 1988 2. Callaghan, P.W. <i>Design and Management for Energy Conservation</i> , Pergamon Press, Oxford, 1981 3. <i>Energy Manager Training Manual (4 Volumes)</i> available at www.energymanagertraining.com , a website administered by Bureau of Energy Efficiency (BEE), a statutory body under Ministry of Power, Government of India, 2004	4. R Loulou, P R Shukla and A Kanudia, <i>Energy and Environment Policies for a sustainable Future</i> , Allied Publishers Ltd, New Delhi, 1997 5. <i>Handbook on Energy Efficiency</i> , TERI, New Delhi, 2001 6. https://www.edx.org/course/incorporating-renewable-energy-in-electricity-grids-2
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. P. Dharmalingam, Executive Director, Ensav Pvt Ltd, pdlingam@gmail.com	1. Dr.M.Premalathar,NIT-Trichy, latha@nitt.edu	1. Mr. M. Sadees, SRMIST
2. Mr. N. Saravanan, Engineering Manager Electrical, L&T Ltd, n-saravanan@intecc.com	2. Dr.Ruben sudhakar D, NIT-Trichy, rubensudhakar@nitt.edu	2. Dr. D. Sattianadan, SRMIST

Course Code	18EE0307T	Course Name	ELECTRIC POWER UTILIZATION AND ILLUMINATION	Course Category	O	Open Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	1	2	3	Program Learning Outcomes (PLO)														
CLR-1 :	Outline the basic concepts of conventional and modern electric heating methods used for various applications	Level of Thinking (Bloom)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Impart knowledge on fundamentals of illumination technology and design the lighting schemes	Expected Proficiency (%)				Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Educate the students on electroplating, electrodeposition and electroforming	Expected Attainment (%)																		
CLR-4 :	Enumerate the concept of electric traction systems and braking methodologies																			
CLR-5 :	Understand and analyze the working of electric-hybrid vehicles and design the illumination schemes for smart building.																			
CLR-6 :	Create a deep knowledge on the electric power utilization and model the illumination schemes																			

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Understand electric heating, welding and implement the modern methodologies for various applications	2	80	75	M	M	M	-	-	-	-	-	-	-	-	-	M	M	M
CLO-2 :	Gain knowledge on basic laws of illumination and design the lighting system	3	80	75	H	H	H	H	M	-	M	M	-	-	-	-	M	M	M
CLO-3 :	Apply the various process like electroplating, electrolysis and electroforming for modern applications	2	80	75	M	M	M	M	M	-	-	-	-	-	-	-	M	M	-
CLO-4 :	Interpret the design of electric traction systems	3	80	75	H	H	H	H	-	-	-	-	-	-	-	-	M	M	-
CLO-5 :	Obtain an in depth knowledge on the concepts of electric, hybrid vehicles and model the lighting schemes for smart building	3	80	75	H	H	M	M	-	-	-	M	-	-	-	-	M	M	M
CLO-6 :	Design a illumination schemes for buildings along with a in depth knowledge of power utilization concepts	3	80	75	H	H	M	M	M	-	M	M	-	-	-	-	M	M	M

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Principle of heating, modes of transfer	Review of laws of illumination	Fundamental principles of extraction	Electric Traction	History of electric and hybrid vehicles
	SLO-2 Methods of Electrical Heating	Luminous efficacy	Refining of metals	Traction Principles	Vehicle motion
S-2	SLO-1 Types of electric furnace: resistance	Lighting Calculations	Electroplating concepts	Types of traction systems	Dynamic equation for the vehicle
	SLO-2 Arc, dielectric furnace	Lighting sources and its types	Methods of electroplating	Services and supply systems for traction	Configuration of electrical vehicles
S-3	SLO-1 Microwave, induction heating	Lighting sources in domestic application	Estimation of power and current for depositing metals	Traction motor characteristics	Tractive effort, force and gear ratio for electric vehicle
	SLO-2 Eddy current heating	Street Lighting	Factors affecting electro deposition process	equation of train motion	Transmission requirement for electric cars
S-4	SLO-1 Types of welding: Arc	Industrial lighting	Electrolysis process and its chemistry	Speed time curve	Vehicle performance analysis
	SLO-2 Resistance welding	Indoor lighting	Electrodes,	Energy and specific energy consumption	Energy consumption
S-5	SLO-1 Air conditioning working	Outdoor lighting	Cell.potential, Emf of Galvanic cell	Quantitative analysis of speed time curve	Drives for Electric cars
	SLO-2 Different types of Air conditioning system	Design of lighting	Nernst equation	Quantitative analysis of energy consumption for drives used in traction	Braking
S-6	SLO-1 Heating of buildings.	light pollution and light trespass	Concept of equilibrium in electrochemical cells	Quantitative analysis of specific energy consumption	Control equipments of electric car
	SLO-2 Power supply for heating and welding	photometry Energy consideration	Faradays law of electrolysis	Tramways	Auxillary equipments
S-7	SLO-1 comparison of types of heating and welding	IES,ANSI STANDARDS for Lighting schemes	Electroforming process	Railways trolley buses	Introduction to smart buildings
	SLO-2 Quantitative analysis of Electric heating	Polar curves of different types of sources	Modern applications of electroplating,	Riding index	Design of lighting schemes in smart building
S-8	SLO-1 Quantitative analysis of welding	Rousseau's Construction	Applications of Electrolysis and Electroforming	Quantitative analysis of Riding index	Intelligent illuminance control in smart building
	SLO-2 Modern trends in electric heating	Quantitative analysis of illumination	Applications of Electroforming	Disadvantages of conventional traction over modern days drive	Quantitative analysis of electric vehicle tractive force calculations

S-9	SLO-1	Modern trends in welding process	Energy efficient	Difference between electroplating electroforming and electrolysis	Introduction to green energy for traction	Quantitative analysis on gear ratio
	SLO-2	Applications of heating and welding	Lighting scheme of the building using simulation tools	Electroplating design tools	Pros and cons of electric and non electric traction system	Quantitative analysis on efficiency calculations

Learning Resources	1. S.Sivanagaraju,M.Balasubba Reddy,D.Srilatha, Generation and Utilization of Electrical energy, Pearson publication,2010. 2. Wadhwa C.L., Generation, Distribution and Utilization of Electrical Energy, New Age International publishers, 3rd edition, 2010.	3. Mehrdad Ehsani, Yimi Gao, Sebastian E. Gay, Ali Emadi, Modern Electric, Hybrid Electric and Fuel Cell Vehicles: Fundamentals, Theory and Design, CRC Press, 2004. 4. G.C.Garg, Utilization of Electric Power and Electric Traction, Khanna Publishers, 2006. 5. https://swayam.gov.in/explorer?ncCode=NPTEL
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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2. Dr. P. Dharmalingam, Executive Director, Ensav Pvt Ltd, pdlingam@gmail.com	2. Dr. R.Ramesh, CEG, rramesh@annauniv.edu	2. Dr. D.Suchitra, SRMIST

Course Code	18EE0308T	Course Name	ELECTRICAL POWER SYSTEM	Course Category	O	Open Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)															
		1	2	3	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLR-1 :	Understand the fundamentals of power stations							Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3	
CLR-2 :	Understand economics of power generation							H	-	-	-	-	-	-	-	-	-	-	-	-	M	-	-
CLR-3 :	Acquire knowledge on AC power supply schemes and insulators							H	L	-	-	-	-	M	-	-	-	-	-	-	M	-	-
CLR-4 :	Understand the basics of substations							H	L	-	-	-	-	-	-	-	-	-	-	-	M	-	-
CLR-5 :	Understand the design of cables and protection equipments							H	M	-	-	-	-	-	-	-	-	-	-	-	M	-	-
CLR-6 :	Acquire knowledge of transmission lines and cables							H	H	-	-	-	-	-	-	-	-	-	-	-	M	-	-
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																					
CLO-1 :	Understand the various aspects of power station	1	75	75																			
CLO-2 :	Execute the performance of transmission lines	2	75	75																			
CLO-3 :	Summarize the AC power supply schemes and DC power transmission	2	75	75																			
CLO-4 :	Analyse the transmission substation and grounding	2	75	75																			
CLO-5 :	Enrich the types of cables and protection equipments	1	75	75																			
CLO-6 :	Understand the supply systems, design of transmission lines and cables	2	75	75																			

Duration (hour)	9		9		9		9		9	
S-1	SLO-1	Importance of Electrical Energy	Structure of Electric Supply System	Typical AC power supply scheme	Introduction to substation	Underground cables				
	SLO-2	Generation of Electrical Energy	Variable load on power station	Types of power transmission	Classification of substation	Construction of cables				
S-2	SLO-1	Sources of Energy	Types of loads	Comparison of DC and AC transmission	Comparison between outdoor and indoor sub stations	Properties of insulation materials				
	SLO-2	Comparison of Energy Sources, Units of Energy	Load curves and selection of generating units	Advantages of high transmission voltage	Step up substation	Insulation materials for cables				
S-3	SLO-1	Relationship among energy units	Base load and peak load on power station	Limitations of high transmission voltage	Primary grid substation	Classification of cables				
	SLO-2	Arrangement of Steam Power Station	Methods of meeting the load	Elements of a transmission line	Secondary substation	Switchgear				
S-4	SLO-1	Choice of site and Equipment's of Steam Power Stations	Economics of power generation	Economics of power transmission,	Distribution substation	Essential features of switchgear				
	SLO-2	Hydro – electric Power Station	Cost of electrical energy	Economic choice of conductor size	Symbols for equipment in sub station	Faults in power system				
S-5	SLO-1	Choice of site and Equipment's of Hydro Power Stations	Objective of tariff	Economic choice of Transmission voltage	Equipments in a substation	Circuit breakers				
	SLO-2	Diesel Power Station	Characteristics of tariff	Requirements of satisfactory electric power	Key diagram of a substation	Arc phenomenon				
S-6	SLO-1	Nuclear Power Plant	Types of tariff	Main components of overhead lines	Need for grounding	Types of circuit breakers				
	SLO-2	Connected load, Maximum demand, Average load	Types of power factor tariff	Conductor materials	Grounding equipments	Need for Fuses				
S-7	SLO-1	Calculation of Load duration curve, Types of loads	Power factor	Line supports	System grounding	Characteristics of fuse element				
	SLO-2	Load curves and selection of generating units	Power triangle	Types of Insulators	Neutral grounding	Fuse element materials				
S-8	SLO-1	Energy, power, efficiency calculations of conventional power plant	Disadvantages of low power factor	Factors affecting Transmission	Advantages of neutral grounding	Types of Fuses				

	SLO-2	Basic layout of sustainable energy resources –Photovoltaic system	Causes of low power factor	Constants of a transmission line	Voltage surge	Low voltage fuses
S-9	SLO-1	Wind energy	Power factor improvement- static capacitor	Resistance of a transmission line	Causes of over voltages	High voltage fuses
	SLO-2	Different operating voltages of generation, transmission and distribution	Synchronous condenser	Inductance of a transmission line	Internal causes of overvoltages	Difference between a fuse and circuit breaker

Learning Resources	1. C.L.Wadhwa, Electrical Power systems, 7 th edition, New age international publisher, Delhi 2017 2. P.S.R. Murty, Electrical Power Systems, 1 st edition, Butterworth-Heinemann publisher, 2017	3. Metha.V.K and Rohit Metha, Principles of Power System, 3 rd edition , S.Chand, 2005. 4. Despande.M.V, Electrical Power Systems Design, 1 st edition, Tata McGraw Hill Publishing Company, New Delhi, 2009 5. https://www.coursera.org/learn/electric-power-systems
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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Course Code	18ECO101T	Course Name	SHORT RANGE WIRELESS COMMUNICATION	Course Category	O	Open Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/ Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Overview of different modulation scheme and wireless system	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	understand the various components used to implement a short-range radio system.	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Analysis of the various kinds of transmitters and receivers used for Short range Wireless Communication.																		
CLR-4 :	know about regulations and standards of ISM band communications																		
CLR-5 :	Design and analysis of short-range radio like UWB and Visible light.																		
Course Learning Outcomes (CLO):	The purpose of this course is to :																		
CLO-1 :	cover the various forms of signals used for information transmission and modulation, and overall wireless system properties.	2	80	70	L	-	-	-	-	-	-	-	-	-	-	-	-	H	-
CLO-2 :	present various component types that can be used to implement a short-range radio system.	2	85	75	-	-	M	L	-	-	-	-	-	-	-	-	-	H	-
CLO-3 :	describe the various kinds of transmitters and receivers.	2	75	70	-	-	H	M	-	-	-	-	-	-	-	-	-	H	-
CLO-4 :	covers regulations and standards of ISM band communications	2	85	80	M	-	-	-	-	-	-	-	-	-	-	-	M	-	-
CLO-5 :	covers some of the most important new developments in short-range radio like UWB and Visible light.	2	85	75	-	-	L	M	-	-	-	-	-	-	-	-	-	-	H

Duration (hour)		Wireless Systems	Baseband Coding basics	RF transceivers	Wireless standards	Optical wireless Technologies
		9	9	9	9	9
S-1	SLO-1	Introduction to wireless systems	Types of Antennas-Dipole, groundplane, loop	RF Receivers- Introduction	Technical Background to the WPAN Concept - Regulation and Standardization Issues	Fundamentals of UROOF Technologies
	SLO-2	Reasons for the Spread of Wireless Applications	Helical, Patch antennas	RF Source-Frequency control	European Consortium: Overview	Conversion from RF to Optical Domain
S-2	SLO-1	Characteristics of Short-range Radio	Antenna Characteristics-Impedence, directivity and gain, Effective area	Modulation types	Millimeter-Wave Applications and Services - PAN scenarios in the IST Magnet project	Conversion from Optical to RF Domain
	SLO-2	Wireless Applications	Polarization, Bandwidth, Antenna factor	Amplifiers	Typical LDR services connected to the IST-FP6 MAGNET project	Optical Microwave Mixing Used for UWB Over Systems
S-3	SLO-1	Elements of Wireless Communication Systems-Transmitter	Baseband Data Format and Protocol - Radio Communication Link Diagram	Impedance matching in transmitter and receivers	Frequency Regulation and Standardization Issues - Optional UM4 usage models issued from the IEEE802.15.3c TG	Integrated UROOF Transceiver (IUT)
	SLO-2	Elements of Wireless Communication Systems-Receiver	Code Hopping	Filtering	Flexible antenna gain, 60 GHz regulation status for wireless transmissions.	Mixed Wireless-wired UROOF Channel, Carrier-to-noise Ratio
S-4	SLO-1	Wireless Local Area Networks (WLAN)- WIFI	Baseband Coding-Digital systems	SAW band pass filter matching	Channel Propagation Characterization and Modeling- 60 GHz Propagation Measurements	Laser and Photodetector Noise Baseline,
	SLO-2	Network Architecture	Wireless Microphone System	Tuned Radio Frequency (TRF)	Propagation Channel Characterization	Clipping Distortion Implication , Latency
S-5	SLO-1	Bluetooth Transceiver	RF Frequency and Bandwidth-factors	ASH Receiver	Multipath Propagation Modeling	Modelling the Propagation through the Fibre
	SLO-2	Bluetooth Modes	Propagation characteristics	Super regenerative Receiver –Block diagram	France Telecom Propagation Channel Models	Analysis of UWB Technologies for UROOF- Comparing UWB Technologies for Radio-over- fibre

S-6	SLO-1	Zigbee Architecture, Frame Structure	Modulation types	Super regenerative Receiver – Operation	MSK-Based System for LOS Gb/s Communications	MB-OFDM Over Multimode Fibre
	SLO-2	Applications and conflicts	Modulation for digital event communication	Super heterodyne Receiver-Block diagram	System architecture for an MSK-based system to operate in a LOS channel.	All-optical Generation of Ultra-wideband Impulse Radio
S-7	SLO-1	Ultra-wideband Technology-Bit Sequence detection	Continuous Digital Communication	Super heterodyne Receiver- Operation	OFDM-Based System for NLOS Gb/s Communications	Operation Principles and Theoretical Approach
	SLO-2	UWB Block Diagram	Advanced Digital Modulation	Direct Conversion Receiver- Block diagram	System architecture for an OFDM-based system to operate in a NLOS channel.	VLC Link –Transmitter
S-8	SLO-1	Wireless Modules-Japan,UK,USA	Spread Spectrum-DHSS	Direct Conversion Receiver- Operation	System Design Aspects-Channel Plan	The VLC Channel
	SLO-2	Wireless Modules-Austria, Honeywell, Norway	Spread Spectrum-FHSS	Digital Receivers-Software radio	60 GHz Channel Characteristics, Baseband Modulation: OFDM versus Single Carrier	Receiver, Modulation
S-9	SLO-1	FCC Regulations-Terms and definitions	RFID-transceiver	Software radio operation	60 GHz Analog Front-End Architectures	Potential Applications
	SLO-2	Nomenclature for defining Emission, modulation and transmission	Design issues for RFID	Repeaters	Multiple Antenna Technologies	Challenges

Learning Resources	<ol style="list-style-type: none"> 1. Alan Bensky, "Short range Wireless Communications-Fundamentals of RF system design and Applications", Elsevier Inc, 2004 2. Antti V. Rissanen, Arto Lehto, "Radio engineering for wireless communication and sensor applications", Artech House, 2003 	<ol style="list-style-type: none"> 3. Rolf Kraemer and Marcos Katz, "Short-range wireless communications emerging technologies and applications", Wiley WWRP series, March 2009 4. Shlomi Arnon, John Barry, George Karagiannidis, Robert Schober, Murat Uysal, "Advanced Optical Wireless Communication Systems", Cambridge University Press, 2012
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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Course Code	18EC0102J	Course Name	ELECTRONIC CIRCUITS AND SYSTEMS	Course Category	O	Open Elective	L	T	P	C
							2	0	2	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/ Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)															
CLR-1 :	Provide a basis for understanding semiconductor material, how a pn junction is formed and its principle of operation	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLR-2 :	Describe the basic structure, operation and characteristics of transistors BJTs and FETs, and discuss their use as a switch and an amplifier																						
CLR-3 :	Learn the basics of op-amp: the principle, operation, characteristics and fundamentally important circuits																						
CLR-4 :	Describe and analyze the basic operation of sinusoidal oscillators and use a 555 Timer in an oscillator application.																						
CLR-5 :	Learn the fundamentals of analog and digital communication, networking, radio transmission and mobile telephones																						
CLR-6 :	Encourage the learner to assemble and test real circuits in the laboratory																						
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																					
CLO-1 :	Understand the operation, characteristics, parameters and specifications of semiconductor diodes and demonstrate its important applications	1	80	70	L	L	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
CLO-2 :	Review the transistor (BJT & FET) construction, operation, characteristics and parameters, as well as its application in amplification and switching.	1	80	70	L	L	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
CLO-3 :	Identify different configurations of op-amp analyze the parameters of op-amp and observe the frequency response of operational-amplifier.	1	80	70	L	L	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
CLO-4 :	Understand & demonstrate different applications based on operational-amplifier and special linear ICs	1	80	70	L	L	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
CLO-5 :	Understand the basic concepts and techniques of telecommunication systems and networks	1	80	70	L	L	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
CLO-6 :	Understand how circuit behavior can be studied with a computer, using a circuit simulation software	2	90	80	-	-	H	-	H	-	-	-	-	-	-	L	-	M	L	-	-	-	

		Active Discrete Components & Circuits – I	Active Discrete Components & Circuits – II	Linear Integrated Circuits	Oscillators and Timers	Telecommunications
Duration (hour)		12	12	12	12	12
S-1	SLO-1	Conduction in semiconductors	JFETs: Structure & Operation	Introduction to Op-amp	RC Phase-Shift oscillator Operation	Analog & Digital Communication: Stages in telecommunication systems
	SLO-2	Conduction in diodes	Characteristics & Parameters	Basic op-amp and its characteristics	& Design	Carriers and Modulation
S-2	SLO-1	Basic operation of PN junction diode	JFET Biasing (Voltage-Divider Biasing)	op-amp modes	Wein bridge Oscillator operation	Carriers and Modulation
	SLO-2	VI Characteristics of diode	CS-JFET Amplifier operation	parameters	& Design	Pulse Modulation
S-3-4	SLO-1	Lab-1: VI Characteristics of PN Junction Diode	Lab-4: Design & Analysis of CE BJT Amplifier	Lab-7: Negative Feedback op-amp circuits	Lab-10: Analysis & Design of RC Oscillators	Lab-13: Demonstration of AM & FM
	SLO-2					
S-5	SLO-1	Applications of diode: HWR & FWR	MOSFETs: Structure	Op-amp circuits: Scale changer, adder, subtractor	LC oscillators operation: Hartley Oscillator	Pulse Modulation
	SLO-2	Clippers & Clampers	Operation	HWR & FWR	Colpitts Oscillator	Digital Transmission, Frequency Division MultiplexingTime Division Multiplexing
S-6	SLO-1	Basic operation of Zener diode and its VI characteristics	Characteristics	Clipper & Clamper	555 Timer IC: Basic Operation	Networks: RS-232, circuit switching
	SLO-2	Zener diode as a voltage regulator	Parameters	Log & Antilog amplifiers	Astable Operation	Message switching, TCP/IP
S	SLO-1	Lab-2: VI Characteristics of Zener Diode		Lab-8: Op-amp Circuits-I		

7-8	SLO-2		Lab-5: Design & Analysis of CS-JFET Amplifier		Lab-11: 555 Timer Operation & Applications	Lab-14: Demonstration of Pulse Modulation
S-9	SLO-1	BJTs: Structure & Operation	MOSFET as an amplifier	Instrumentation amplifier	Monostable Operation	Radio Transmission: Electromagnetic Spectrum, ground waves, sky waves
	SLO-2	Characteristics & Parameters	MOSFET as a switch	Comparator	Applications of 555 Timer	antennas, directional transmissions,
S-10	SLO-1	CE BJT amplifier operation	MOSFET Biasing (Voltage-Divider Biasing)	Comparator applications	Applications of 555 Timer	Transmitters, Receivers
	SLO-2	Differential amplifier operation	CS-MOSFET amplifier operation	Schmitt trigger	Voltage-Controlled Oscillators	Mobile telephones
S 11-12	SLO-1	Lab-3: Applications of PN Junction diode and Zener diode	Lab-6: Design & Analysis of CS-MOSFET Amplifier	Lab-9: Op-amp Circuits-II	Lab-12: VCO Operation	Mini Project / Model Practical Examination
	SLO-2					

Learning Resources	1. Owen Bishop, "Electronic Circuits and Systems", 4th edition, Elsevier, 2011. 2. Harry Kybett, Earl Boysen, "All New Electronics", 3rd edition, Wiley, 2008.	3. Paul Scherz, "Practical Electronics for Inventors", McGraw-Hill, 2000.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		-	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Anuj Kumar, Bombardier Transportation, Ahmedabad, kumaranuj.ani@gmail.com	1. Dr. Meenakshi, Professor of ECE, CEG, Anna University, meena68@annauniv.edu	1. Mr. Manikandan AVM, SRM IST
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	2. Dr. Rajesh Agarwal, SRM IST

Course Code	18ECO103T	Course Name	MODERN WIRELESS COMMUNICATION SYSTEM			Course Category	O	Open Elective					L	T	P	C							
												3	0	0	3								
Pre-requisite Courses	Nil		Co-requisite Courses		Nil		Progressive Courses	Nil															
Course Offering Department		Electronics and Communication Engineering			Data Book / Codes/Standards		Nil																
Course Learning Rationale (CLR):		The purpose of learning this course is to:				Learning			Program Learning Outcomes (PLO)														
CLR-1 :		Learn to analyze the transmission of various wireless communication systems				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :		Understand the fundamentals of various networks in wireless communication				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :		Understand the techniques involved in personal communication services.																					
CLR-4 :		Introduce various wireless systems for 3G and future communication																					
CLR-5 :		Learn to analyze wireless networks for short range communication																					
CLR-6 :		Understand the Fundamentals, Techniques and Networks of Wireless Communication Systems																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	-	-	-	H	-	-	-	-	-	-	-	-	H	-	-
CLO-1 :		Discuss the fundamentals of transmission in wireless systems				2,3	80	75	-	-	-	H	-	-	-	-	-	-	-	-	H	-	-
CLO-2 :		Provide an overview of various approaches to communication networks				2,3	80	85	-	-	-	H	-	-	-	-	-	-	-	-	-	-	H
CLO-3 :		Study the numerous different-generation technologies with their individual pros and cons				2,3	85	85	-	-	-	H	-	-	-	-	-	-	-	M	-	-	H
CLO-4 :		Discuss about the principles of operation of the different access technologies like FDMA, TDMA, SDMA and CDMA and their pros and cons.				2,3	85	80	-	-	-	H	-	-	-	-	-	-	-	M	-	-	H
CLO-5 :		Learn about the various mobile data services and short range networks.				2,3	85	80	-	-	-	-	-	-	-	-	-	-	-	-	-	-	H
CLO-6 :		Gain knowledge on Fundamentals, Techniques and Networks of Wireless Communication Systems				2,3	85	80	-	-	-	-	-	-	-	-	-	-	-	H	-	-	-
Duration (hour)		Transmission Fundamentals		Network Concepts		Personal Communication Services		3G and Beyond			Mobile Data Services and Short- Range Network												
		9		9		9		9			9												
S-1	SLO-1	Cellphone Generations		Communication Networks		Personal communication Introduction, HSCSD, GPRS, D-AMPS, CDMA One, CDMA Two, Packet Data Systems		3G Introduction			Mobile Data Services Introduction Messaging, wireless web, WAP, site design Short-Range Wireless Networks: Unlicensed spectrum, WLANs, cordless telephony, IrDA, Bluetooth Smart Phones: Future phones, mobile OSs, smart phone applications.												
	SLO-2	1G and 2G		LANs		GSM		IMT-2000 Introduction			Data Services												
S-2	SLO-1	2.5G		MANs		GSM		IMT-2000			Messaging												
	SLO-2	3G		WANs		HSCSD		IMT-2000			Wireless web												
S-3	SLO-1	4G Transmission Introduction		Circuit switching		HSCSD		W-CDMA Introduction			WAP												
	SLO-2	4G Transmission Fundamentals		Packet switching		GPRS		W-CDMA			Site design												
S-4	SLO-1	Time domain concepts		ATM Cellular Networks Introduction		GPRS		CDMA 2000 Introduction			Short-Range Wireless Networks												
	SLO-2	Frequency domain concepts		Cells		D-AMPS		EDGE			Unlicensed spectrum												
S-5-6	SLO-1	Radio Media		Duplexing		D-AMPS		EDGE			WLANs												
	SLO-2																						
S-7	SLO-1	Analog Vs Digital		Multiplexing		CDMA Introduction		Wi-Fi Introduction			Cordless telephony												
	SLO-2	Channel capacity		Voice coding		CDMA One		Wi-Fi			IrDA												
S-8	SLO-1	Transmission media		Multiple Access Techniques: FDMA		CDMA One		WiMAX Introduction			Bluetooth Smart Phones												
	SLO-2	Signaling Schemes		TDMA, SDMA		CDMA Two		WiMAX			Future phones												
S-9	SLO-1	Carrier-based signaling,		CDMA		CDMA Two		OFDM			Mobile OSs												
	SLO-2	Spread-spectrum signaling		Spectral efficiency		Packet Data Systems		MIMO			Smart phone applications												

Learning Resources	1. Simon Haykin, David Kozlowski, Michael Moher, "Modern Wireless Communication", 1/e, Pearson Education, 2011	4. Andy Dornan, "The essential guide to wireless communications applications: from cellular systems to Wi-Fi", 2nd Edition, Prentice Hall, 2002.
	2. Rappaport T.S, "Wireless Communications: Principles and Practice", 2nd edition, Pearson education.	5. Ian F.Akyildiz, David M. Gutierrez Estevez, and Elias Chavarria Reyes, "The evolution of 4G cellular systems: LTE advanced", Physical communication, Volume 3, No. 4, pp. 217-298, Dec. 2010
	3. Andrea Goldsmith, "Wireless Communications", Cambridge University Press, Aug. 2005.	6. William Stallings, "Wireless Communication & Networking", Pearson Education Asia, 2004
		7. Andrea F.Molisch, "Wireless communications", 2nd edition, Wiley Publications.

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

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2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	

Course Code	18ECO104J	Course Name	AUDIO AND SPEECH SIGNAL PROCESSING	Course Category	O	Open Elective	L	T	P	C
							2	0	2	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering		Data Book / Codes/Standards	Nil	

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)															
CLR-1 : To explore about Speech signal processing		Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLR-2 : To explore about the human auditory system																							
CLR-3 : Feature Extraction of Speech signal using Time characteristics																							
CLR-4 : Frequency characteristics of Speech signal																							
CLR-5 : Provide a foundation for developing applications in this field.																							
CLR-6 : Understand the concept of speech processing both in time and frequency domain																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																					
CLO-1 :	Understand the functioning of the human vocal and auditory systems in terms of signal processing	1	90	68	H		H	H								-	-	-	-	M	H		
CLO-2 :	Analyze the function of feature extraction in speech and audio signal processing using Time Domain Characteristics	2	85	67	H			H					M		M	-	-	-	-	M		H	
CLO-3 :	Understand the frequency characteristics of speech signal	2	85	68	H		H			M			M		M	-	-	-	-		H	H	
CLO-4 :	Understand the Digital models for speech signal	1&2	85	65	H		H	H								-	-	-	-	H	M		
CLO-5 :	Understand the elements of music	2&3	85	66			H		H				H		H	-	-	-	-	H		H	
CLO-6 :	Understand Speech signal processing in time and frequency domain and their models.	1,2,3	85	68	H		H			M			H		H	-	-	-	-		M	M	

	Basic Audio Processing		Human auditory system	Speech Signal Analysis in Time Domain	Speech Signal Analysis in Frequency Domain	Speech and Audio processing applications
Duration (hour)	12		12	12	12	12
S-1	SLO-1	Introduction to Digital audio	Human auditory system	Speech signal analysis	Short Time Fourier analysis	Introduction to Speech recognition
	SLO-2	Capturing and converting sound	Human auditory system	Speech signal analysis	Short Time Fourier analysis	Introduction to Speech recognition
S-2	SLO-1	Sampling of sound wave	simplified model of cochlea	Segmental, sub-segmental levels	Filter bank analysis	Complete system for an isolated word recognition with vector quantization /DTW
	SLO-2	Handling audio in MATLAB	simplified model of cochlea	Suprasegmental levels	Formant extraction and Pitch extraction	Complete system for an isolated word recognition with vector quantization /DTW
S-3-4	SLO-1	Lab 1: Read & write a speech signal, Record a speech signal, playback, convert into a wave file, plot the speech signal, and spectrogram plot.	Lab 4: Short-term energy of a speech signal	Lab 7: Estimation of pitch period using simplified inverse filter tracking (SIFT) algorithm	Lab 10: Phoneme-level segmentation of speech	Lab 13: Compute pitch period and fundamental frequency for speech signal
	SLO-2	Normalization	Sound pressure level and loudness	Time domain parameters of speech signal	Homomorphic speech analysis	Complete system for speaker identification, verification
S-5	SLO-1	Audio processing	Sound pressure level and loudness	Time domain parameters of speech signal	Cepstral analysis of Speech	Introduction to speech enhancement
	SLO-2	Segmentation	Sound intensity and Decibel sound levels	Methods for extracting the parameters Energy	Formant and Pitch Estimation	Introduction to speech enhancement
S-6	SLO-1	Analysis of window sizing	Sound intensity and Decibel sound levels	Average ,Magnitude	Linear Predictive analysis of speech	Speech enhancement using spectral subtraction method
	SLO-2	Lab 2: Convert into a wave file, plot the speech signal, and spectrogram plot	Lab 5: Short-time Fourier transform magnitude spectrum	Lab 8: Estimation of pitch period using harmonic product spectrum	Lab 11: To study the quantization and aliasing effect of speech signal	Lab 14: Short term speech analysis

S-9	SLO-1	Visualization	Concept of critical band	Zero crossing Rate	Autocorrelation method, Covariance method	Introduction to Text to speech conversion method
	SLO-2	Sound generation	Uniform filter bank , Non- uniform filter bank	Silence Discrimination using ZCR and energy	Solution of LPC equations	Introduction to Musical instrument classification
S-10	SLO-1	Speech production mechanism, Characteristics of speech	Mel scale and bark scale,	Short Time Auto Correlation Function	Durbin's Recursive algorithm, Application of LPC parameters	Musical Information retrieval.
	SLO-2	Understanding of speech	Speech perception: vowel perception	Pitch period estimation using Auto Correlation Function	Pitch detection using LPC parameters, Formant analysis	Sample Programs
S 11-12	SLO-1	Lab 3:Cepstrum smoothed magnitude spectrum	Lab 6: (i)Linear prediction magnitude spectrum, (ii) (ii) Estimation of formant frequencies using linear prediction	Lab 9: Pitch and duration modification using time-domain pitch synchronous overlap and add (TD-PSOLA) method	Lab 12:: Speech signal to symbol transformation using wavesurfer	Lab 15: Study of Praat
	SLO-2					

Learning Resources	<ol style="list-style-type: none"> 1. Ian McLaughlin, "Applied Speech and Audio processing, with MATLAB examples", 1st Edition, Cambridge University Press, 2009 2. Ben Gold, Nelson Morgan, Dan Ellis, Wiley, "Speech and Audio Signal Processing: Processing and Perception of Speech and Music", 2nd Edition, John Wiley & Sons, 01-Nov-2011. 3. Rabiner,B.H.Juang, "Fundamentals of Speech Recognition", 2nd Edition, Prentice-hall Signal Processing Series, April 1993 4. Ken Pohlmann, "Principles of Digital Audio", 6th Edition, McGraw-Hill, 2007 5. A.R.Jayan, "Speech and Audio Signal Processing", ISBN : 978-81-203-5256-8, PHI Learning Pvt. Ltd, 2016.
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Learning Assessment											
	Bloom'sLevel of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

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Course Code	18ECO105T	Course Name	UNDERWATER ACOUSTICS	Course Category	O	Open Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering		Data Book / Codes/Standards	Nil	

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand what is Sound Navigation and Ranging (SONAR) and how it can be used in underwater applications.				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Study about Ocean Acoustic Processing and sound wave propagation and analyze sea floor characteristics and ocean sounds.				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Understand about Underwater reverberation and how types of noises affects the underwater acoustics signal data analysis.																					
CLR-4 :	Study about Acoustic transducers.																					
CLR-5 :	Know which transducers can be used for underwater applications.																					
CLR-6 :	Understand the basic theory and signal processing application for underwater communication and navigation.																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	Acquire in-depth knowledge and analyze on Sound Navigation and Ranging (SONAR) equations and it characteristics.				1	85	65	M	-	-	-	-	-	-	-	-	-	-	M	L	-	-
CLO-2 :	Analyze Ocean Acoustic Processing and sound wave propagation.				2	85	65	M	H	H	H	H	-	-	-	-	-	-	L	H	H	H
CLO-3 :	Acquire knowledge and analyze Underwater reverberation and various types of noises.				1&2	85	65	M		H	H	H	-	-	-	-	-	-	L	H	M	H
CLO-4 :	Acquire knowledge on working of underwater Acoustic transducers.				1	85	65	H	H	H	H	H	-	-	-	-	-	-	L	H	H	H
CLO-5 :	Gain knowledge and apply SONAR concepts for underwater applications.				1&3	85	65	L		H	H	-	-	-	-	-	-	-	L	H	M	H
CLO-6 :	Understand the development and dynamics of underwater acoustic engineering				2 & 3	85	65	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-

		Sound Navigation and Ranging (SONAR)	Ocean Acoustic Processing and sound wave propagation	Reverberation and Noises	Acoustic Transduction	SONAR Application
Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction to SONAR equation,	Processing ocean sound-Sampling rules	Reverberation-Scattering, back scattering strength and target strength	Piezoelectric transducer-Introduction	Echo sounder
	SLO-2	Source Intensity, Source Directivity	Spatial sampling and Temporal sampling	Surface and bottom scattering	Piezoelectric transducer-33-Mode longitudinal vibrator	Echo Sounder
S-2	SLO-1	Transmission loss	Filter operations-Finite Fourier transformation	Volume scattering, bottom scattering, reverberation target strength	Piezoelectric transducer-33-Mode longitudinal vibrator	Sub-bottom profiling
	SLO-2	Transmission loss	Filter operations-Time domain view of Band pass filtering. convolution operations, frequency domain	Calculation of reverberation for use in the sonar equation, Volume reverberation level	Electrostrictive transducers	Fishing sonars
S-3	SLO-1	Target Strength	Gated Signals-Dependence of Spectrum on ping carrier periodicity	Reverberation frequency spread and Doppler gain potential-Power spectral density of a CW pulse	Electrostrictive transducers	Side scan terrain mapping sonar
	SLO-2	Reflection Intensity Loss Coefficient	Power spectra of random signal-Signal having random characteristics, Spectral density,	Environmental frequency sampling	Magnetostrictive transducers	Side scan terrain mapping sonar
S-4	SLO-1	Sea-floor Loss,	Radom signal simulations-Intensity spectral density, Spectral smoothing	Frequency spreading due to transmitter and receiver motion	Magnetostrictive transducers	Acoustic positioning and navigation
	SLO-2	Sea-surface Loss	Matched filters and autocorrelation	Frequency spreading due to target, important observation with respect to reverberation	Electrostatic Transducers	Acoustic positioning and navigation

S-5	SLO-1	Noise, Reverberation	Sounds in the oceans-natural physical sounds and biological sounds	Noise-Ambient noise models	Electostatic Transducers	3D Imaging Processing-data model
	SLO-2	Active and Passive Sonar Equations	Sound propagation in the ocean and underwater acoustic channel-Sound wave and vibration, velocity of sound	Ambient noise-seismic noise, ocean turbulence, shipping noise	Variable Reluctance Transducers	3D Imaging Processing-acquisition of 3D information
S-6	SLO-1	Passive Sonar Equations, Signal-to-Noise Ratio	Sound propagation in the ocean and underwater acoustic channel-Sound wave velocity of sound	Wave noise, thermal noise	Variable Reluctance Transducers	3D Imaging Processing-matrix approach and real time systems
	SLO-2	Signal Excess, Figure of Merit	Wave and ray theories of underwater sound fields	Rain noise, temporal variability of ambient noise, depth effects of noise	Moving coil transducers	3D Imaging Processing-Image representation, Acoustic image processing
S-7	SLO-1	Active SONAR target strength	Wave and ray theories of underwater sound fields	Under ice noise	Moving coil transducers	3D Imaging Processing-Segmentation and reconstruction of underwater tubular structures
	SLO-2	Active SONAR- reverberation, detection threshold	Wave and ray theories of underwater sound fields	Spatial coherence of ambient noise	Equivalent circuits-Basics Circuit Resonance	3D Imaging Processing-Segmentation and reconstruction of underwater tubular structures
S-8	SLO-1	Active Sonar Sources- Source Level, Cavitation	Sound absorption in sea water and its characteristics	Self-noise-Flow noise	Circuit Q and Bandwidth	Acoustic communication-Cross attributes of the received signal
	SLO-2	Near-Field Interactions Explosive Sources	Upper boundary of acoustic channel	Self-noise – Flow noise	Transducers as projectors-principle	Acoustic communication-channel transfer function
S-9	SLO-1	Physics of Shock Waves in Water, Bubble Pulses	Lower boundary of acoustic channel and its characteristics	Self noise-turbulent noise coherence	Transducers as Hydrophones-principles of operations	Acoustic communication-combating multipath
	SLO-2	Pros and Cons of Explosive Charges, Parametric Acoustic Sources	sound field in shallow water	Self noise-strumming noise	Transducers as Hydrophones-simplified equivalent circuit	Acoustic communication-diversity reception, equalization

Learning Resources	1. Richard P HODGES, "Underwater Acoustics – Analysis, Design and Performance of SONAR", Wiley 1 edition 2010, ISBN 978-0-470-68875-	4. Charles H Sherman, John L Butler, "Transducers and Arrays for Underwater Sound", Springer; 2nd edition, 2016, ISBN-10: 0-387-32940-4 ISBN-13: 978-0387-32940-6
	2. Rodney F W Coates, "Underwater Acoustics Systems", Macmillan New Electronics, Wiley, 1 st edition, 1990, ISBN 978-0-333-42542-8	5. Qihu Li, "Digital Sonar Design in underwater acoustics: Principles and applications", Springer, Zhejiang University Press, 2012
	3. Robert S H Istepanian and Milica Stojanovic, "Underwater Acoustic Digital Signal Processing and Communication Systems", Springer, 2002 edition, ISBN 978-1-4419-4882-3	6. Herman Medwin, Clarence S. Clay, "Fundamentals of Acoustical Oceanography", Academic Press, 1998.

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Evaluate Create	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

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Course Code	18ECO107T	Course Name	FIBER OPTICS AND OPTOELECTRONICS	Course Category	O	Open Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards			Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Analyze the basic laws and theorems of light associated with the optical fiber communication and the classification of optical fibers		1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Address concepts related to transmission characteristics such as attenuation and dispersion.		Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Explore the fundamentals of optoelectronics display devices, Sources and Detectors					H	H	-	-	-	-	-	-	-	-	-	-	-	-	M
CLR-4 :	Gain to information on Optical modulators and amplifiers					H	-	M	-	-	-	-	-	-	-	-	-	-	-	L
CLR-5 :	Illustrate the integration methods available for optoelectronic circuits and devices					H	M	M	-	-	-	-	-	-	-	-	-	-	-	L
CLR-6 :	Utilize the basic optical concepts applied in various engineering problems and identify appropriate solutions					H	-	M	-	-	-	-	-	-	-	-	-	-	-	H
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:				H	-	M	L	-	-	-	-	-	-	-	-	-	-	L
CLO-1 :	Review the basic theorems related to fiber optic communication, and attain knowledge of types of optical fibers		2	80	70	H	M	M	L	-	-	-	-	-	-	-	-	-	-	H
CLO-2 :	Understand the optical signal distortion factors in optical fiber communication		2	85	75	H	-	M	-	-	-	-	-	-	-	-	-	-	-	M
CLO-3 :	Familiarize the principle and operation of various display devices, light sources and detectors		2	75	70	H	M	M	-	-	-	-	-	-	-	-	-	-	-	L
CLO-4 :	Acquire knowledge of various optoelectronic modulators and amplifiers		2	85	80	H	-	M	-	-	-	-	-	-	-	-	-	-	-	H
CLO-5 :	Understand the various optoelectronic integrated circuits		2	85	75	H	-	M	L	-	-	-	-	-	-	-	-	-	-	L
CLO-6 :	Acquire fundamental concepts related to optical communication and optoelectronic devices		2	80	75	H	M	M	L	-	-	-	-	-	-	-	-	-	-	H

Duration (hour)		Introduction to Optical Fibers	Transmission Characteristics of Optical Fibers	Display Devices, Light Sources and Detection Devices	Optoelectronic Modulators and Switching Devices	Optoelectronic Integrated Circuits
		9	9	9	9	9
S-1	SLO-1	Evolution of fiber optic system	Attenuation – Absorption, Attenuation units	Display devices – Photo luminescence	Analog and Digital Modulation	Optoelectronic integrated circuits - Introduction
	SLO-2	Elements of an optical fiber transmission link	Attenuation – Scattering losses	Cathode luminescence	Electro optic modulators – Electro optic effect – Longitudinal electro optic modulator	Need for Integration - Hybrid and Monolithic Integration
S-2	SLO-1	Elements of an optical fiber transmission link	Attenuation – Bending losses, microbending and macro bending losses	Electro luminescence	Electro optic modulators – Transverse electro optic modulator	Hybrid and Monolithic Integration
	SLO-2	Advantages of fiber optic system	Attenuation - Core cladding losses	Injection luminescence	Acousto optic modulators – Transmission type – Raman Nath modulator	Materials and processing of OEICs
S-3	SLO-1	Characteristics and behavior of light	Signal distortion in optical waveguides	Light source materials	Acousto optic modulators – Reflection type – Bragg modulator	Application of optoelectronic integrated circuits
	SLO-2	Total internal reflection	Types of dispersion-Intramodal and Intermodal dispersion	Surface emitting LEDs	Solving Problems	Slab and Strip Waveguides
S-4	SLO-1	Acceptance angle	Material dispersion	Edge emitting LEDs	Optical switching and logic devices – self-electro-optic-device	Integrated transmitters and receivers – Front end photo receivers
	SLO-2	Numerical aperture, Critical angle	Material dispersion, Waveguide dispersion	Quantum efficiency and LED power – Internal quantum efficiency derivation	Optical switching and logic devices – Bipolar controller modulator	Integrated transmitters and receivers – photoreceiver noise and bandwidth considerations
S-5	SLO-1	Solving Problems	Waveguide dispersion	Quantum efficiency and LED power – External quantum efficiency and total LED power	Optical switching and logic devices-tunable threshold logic gate – Switching speed and energy.	Integrated transmitters and receivers – PIN-HBT photoreceivers

	SLO-2	Solving Problems	Signal distortion in single mode fibers	Solving Problems	Optical Amplifiers – General applications of optical amplifiers	Integrated transmitters and receivers – OEIC transmitters – equivalent circuit for integrated receivers
S-6	SLO-1	Ray optics	Polarization mode dispersion	Semiconductor laser diode	Semiconductor optical amplifiers – Basic configuration	Integrated transmitters and receivers – Complex circuits and arrays
	SLO-2	Types of rays	Polarization mode dispersion, Intermodal dispersion	Modes and threshold condition	Semiconductor optical amplifiers – Optical gain - Limitations	Integrated transmitters and receivers - optical control and microwave oscillators
S-7	SLO-1	Optical fiber modes	Intermodal dispersion	Photo detection principle	Erbium doped fiber amplifiers – energy level diagram and amplification mechanism	Guided wave devices – Waveguide and couplers
	SLO-2	Optical fiber configurations	Solving Problems	PIN Photodiode	Erbium doped fiber amplifiers – EDFA configuration	Guided wave devices – Active guided wave devices
S-8	SLO-1	Single mode fibers	Solving Problems	PIN photodiode - Avalanche Photodiode	Solving Problems	Guided wave devices – Mach Zehnder Interferometers
	SLO-2	Multimode Fibers	Pulse Broadening in Graded Index Waveguides	Avalanche Photodiode	Solving Problems	Active couplers
S-9	SLO-1	Step Index Fibers	Mode Coupling	Noise mechanism in photodetectors	Fiber Raman Amplifiers – Configuration – Forward pumping	Active Couplers
	SLO-2	Graded Index Fibers	Design Optimization of Single Mode Fibers	Solving Problems	Fiber Raman Amplifiers – Backward pumping	Active Couplers

Learning Resources	1. Gerd Keiser, "Optical Fiber Communications", 5 th Edition, McGraw Hill Education (India), 2015.	3. J. Wilson and J. Hawkes, "Optoelectronics – An Introduction", Prentice Hall, 1995.
	2. Khare R P, "Fiber Optics and Optoelectronics", Oxford University Press, 2014.	4. Pallab Bhattacharya, "Semiconductor Optoelectronic Devices", Prentice Hall of India Pvt. Ltd, 2006.

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Anuj Kumar, Bombardier Transportation, Ahmedabad, kumaranuj.anii@gmail.com	1. Dr. Meenakshi, Professor of ECE, CEG, Anna University, meena68@annauniv.edu	1. Dr. S. Sathiyar, SRMIST
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	

Course Code	18ECO109J	Course Name	EMBEDDED SYSTEM DESIGN USING RASPBERRY PI	Course Category	O	Open Elective	L	T	P	C
							2	0	2	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards			Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:				Learning			Program Learning Outcomes (PLO)															
CLR-1 :	Understanding the programing of python for Raspberry Pi					Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLR-2 :	Applying python programming on GPIO and interfacing motors using Raspberry Pi								Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3	
CLR-3 :	Applying python programming on GPIO switch and keyboard								H	H	-	-	H	-	-	-	-	-	-	-	-	H	-	-
CLR-4 :	Create insights to the concepts and programming of motion detection ,GPS programming, light sensor ,gas detection								H	H	H	H	H	-	-	-	-	-	-	-	-	H	-	H
CLR-5 :	Analyze and understand the working principle and data sheet of temperature sensor, gas sensor ,ADC, ultrasonic rangefinder, Acceleration and light sensor								H	H	H	H	H	-	-	-	-	-	-	-	-	H	-	-
CLR-6 :	Utilize the technology of node js ,cloud service and MQTT Protocol for moving sensor data to web								H	-	H	H	-	-	-	-	-	-	-	-	-	H	-	-
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1 :	Apply python for Raspberry Pi					2	80	70																
CLO-2 :	Analyze data sheet and functioning of sensors					2	85	75																
CLO-3 :	Apply python programming on GPIO of Raspberry Pi and interfacing of sensor					2	75	70																
CLO-4 :	Apply python programming on GPIO of Raspberry Pi to interfacing of actuators					2	85	80																
CLO-5 :	Apply python programming on GPIO of Raspberry Pi to interfacing input and display device					2	85	75																
CLO-6 :	Apply technology of node js ,cloud service and MQTT Protocol for IOT application					2	80	70																

Duration (hour)		Basic python programming	Programming interrupts –Motor control, switches and keyboard interface	Sensor interface and programming	Temperature sensor and display interface programming	Publishing sensor data on web service
		12	12	12	12	12
S-1	SLO-1	Python Basics- Editing Python Programs with IDLE, Variables, displaying Output, Reading User Input , Arithmetic, Creating Strings	Programming with Interrupts	Detecting Movement-PIR sensor	Measuring Temperature Using a Digital Sensor	publish sensor data on web service-building a home security dash board
	SLO-2	Concatenating (Joining) Strings, Converting Numbers to Strings, Converting Strings to Numbers ,Find the Length of a String, Find the Position of One String Inside Another, Extracting Part of a String, Replacing One String of Characters with Another Inside a String ,Converting a String to Upper- or Lowercase	Programming with Interrupts	Data sheet analysis of PIR sensor	Data sheet analysis Digital Temperature Sensor	publish sensor data on web service-building a home security dash board
S-2	SLO-1	Running Commands Conditionally, Comparing Values, Logical Operators,	Controlling GPIO Outputs Using a Web Interface	Adding GPS to the Raspberry Pi	Measuring Distance-ultrasonic rangefinder	MQTT Protocol
	SLO-2	Repeating Instructions an Exact Number of Times ,Repeating Instructions Until Some Condition Changes , Breaking Out of a Loop, Defining a Function in Python	Controlling GPIO Outputs Using a Web Interface	Data sheet analysis of GPS	Data sheet analysis ultrasonic rangefinder	MQTT Protocol- installation and setting account ,token creation ,reading sensor data and pushing to thingsboard
S-3-4	SLO-1	Lab 1: Arithmetic and string	Lab 7: Programming on interrupts	Lab 13: Programming on PIR sensor	Lab 19: Programming on Digital Temperature Sensor	Lab 25: Publish sensor data on web service
	SLO-2	Lab 2: Loop	Lab 8: Programming on Web Interface	Lab 14: Programming on GPS	Lab 20: Programming on ultrasonic rangefinder	Lab 26: Publish sensor data on web service

S-5	SLO-1	Creating a List , Accessing Elements of a List, Find the Length of a List , Adding Elements to a List , Removing Elements from a List,	Controlling Servo Motors using PWM	Using Resistive Sensors	Logging to a USB Flash Drive	basic of java scripts –node.js
	SLO-2	Creating a List by Parsing a String, Iterating over a List, Enumerating a List, Sorting a List, Cutting Up a List. Applying a Function to a List	Controlling the Speed of a DC Motor	Measuring Light	Logging to a USB Flash Drive	Modules-HTML module
S-6	SLO-1	Creating a Dictionary ,Accessing a Dictionary, Removing Things from a Dictionary,	Controlling the Direction of a DC Motor	Detecting Methane	Using a Four-Digit LED Display	Modules –file –event
	SLO-2	Iterating over Dictionaries	Using a Unipolar Stepper Motor	Data sheet analysis of gas sensor	Displaying Messages on an I2C LED matrix with data sheet discussion	Modules –file –event
S 7-8	SLO-1	Lab 3: Program on list	Lab 9: Programming on Stepper Motor	Lab 15: Programming on light sensor	Lab 21: Programming on Four-Digit LED Display	Lab 27: Programming on node js HTML module
	SLO-2	Lab 4: Program on Dictionary	Lab 10: Programming on DC Motor	Lab 16: Programming on Gas sensor	Lab 22: Programming on I2C LED matrix	Lab 28: Programming on node js file and event module
S-9	SLO-1	Controlling Hardware-Connecting an LED-Controlling the Brightness of an LED	Using a Bipolar Stepper Motor	Measuring a Voltage using MCP3008 And data sheet of MCP3008	Displaying Messages on an Alphanumeric LCD	LED blinking using node.js
	SLO-2	a Buzzing Sound	Building a Simple Robot Rover	Using Resistive Sensors with an ADC	Displaying Messages on an Alphanumeric LCD	LED blinking using node.js
S-10	SLO-1	Switching a High-Power DC Device Using a Transistor	Digital Inputs-Connecting a Push Switch-Toggling with a Push Switch-Using a Two-Position Toggle or Slide Switch	Measuring Temperature with an ADC	Cloud service for IOT	building java script client using MQTT broker
	SLO-2	Switching a High-Power Device Using a Relay	Using a Rotary (Quadrature) Encoder and Using a Keypad	Measuring Acceleration and data sheet discussion of Acceleration sensor	Cloud service for IOT	building java script client using MQTT broker
S 11,12	SLO-1	Lab 5: LED blinking and Brightness control	Lab 11: Programming on Switch	Lab 17: Programming on ADC	Lab 23: Programming on an Alphanumeric LCD	Lab 29: Programming on LED blinking using node.js
	SLO-2	Lab 6: Switching a High-Power DC Device	Lab 12: Programming on Keypad	Lab 18: Programming on Measuring Acceleration	Lab 24: Programming on an Alphanumeric LCD	Lab 30: Building java script client using MQTT broker

Learning Resources	1. Simon Monk, "Raspberry Pi Cookbook", O'Reilly Media, Inc, 2014. 2. Volker Ziemann, "A Hands-On Course in Sensors Using the Arduino and Raspberry Pi, CRC Press, 2018. 3. https://thingsboard.io/docs/ 4. Colin Dow, "Internet of Thing: Programming Projects - Build modern IoT solutions with the Raspberry Pi 3 and Python", packtpub 2018. 5. https://www.w3schools.com/nodejs/nodejs_raspberrypi_blinking_led.asp
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

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1. Mr. Anuj Kumar, Bombardier Transportation, Ahmedabad, kumaranuj.anii@gmail.com	1. Dr. Meenakshi, Professor of ECE, CEG, Anna University, meena68@annauniv.edu	1. Dr. P. Vijayakumar, SRMIST
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	

Course Code	18ECO110J	Course Name	3D PRINTING HARDWARE AND SOFTWARE	Course Category	E	Professional Elective	L	T	P	C
							2	0	2	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards			Nil

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand the tools available for 3D printing	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Familiarize with 3D design software and hardware	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Understand the 3D design criteria and its limitations.																		
CLR-4 :	Learn the contemporary technology available for 3D design and printing																		
CLR-5 :	Understand various post processing methods involved in 3D printing technology																		
CLR-6 :	Develop the skillset on 3D component design and development using contemporary commercial software and hardware available.																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Apply the 3D printing tools for components design	1	80	60	M				M										
CLO-2 :	Able to optimistically select the 3D design software and hardware for the given problem	1	80	60	M				H										
CLO-3 :	Capability to solve 3D design components design problems	2	75	60	M			M										M	
CLO-4 :	Choose the contemporary technology available for 3D design and printing	3	80	60			M											M	L
CLO-5 :	Apply various post processing methods involved in 3D printing technology	2	80	60		H													
CLO-6 :	Ability to develop the skillset on 3D component design and development using contemporary commercial software and hardware available.	2	80	60											M			M	

Duration (hour)	Introductions to 3D design tools		Three-dimensional (3D) Modeling	3D Design Fundamentals and Projects	3D Printing and its Technologies	Post Processing - Product Visualization and Print Cleaning
	12		12	12	12	12
S-1	SLO-1	Introduction to Maya GUI - Object creation workflow, Constructing object primitives to scale and with accuracy	An overview of CAD software packages - Introduction to Fusion 360 - Drawing based workflow, Drawing constraints - Surfacing operations.	The good, the bad, and the ugly of design	History of 3D printing - Overview of 3D Printing technologies	Workflows for printing
	SLO-2					
S-2	SLO-1	Duplication and arrayed duplication - Grid and point/vertex snapping	Moving Parts and Articulation Hinges - Ball and sockets	Prominent Designers	Selective Laser Sintering (SLS) Direct Metal Laser Sintering (DMLS)	Software and Drivers - Formats for Printing (SLA, OBJ, CAD, etc.)
	SLO-2					
S 3-4	SLO-1	Understanding NURBS: NURBS Surfaces advantages, Similarities and differences between NURBS and CAD drawings	Creating a part negative, Creating Text in Maya the proper way (NURBS Curves, surface lofts, conversion to polygon) Painterly Curve and surface construction	Franchises Success stories, Pop culture	Vacuum forming - Resin casting - Injection Molding - Terms and standards for injection molding systems	Post and Export Print Lab setup
	SLO-2					
S-5	SLO-1	Understanding 3D geometry - Modeling workflows for Polygons - Additive vs. Subtractive Tools - Mesh editing	Flexibility and elasticity, Locks, bolts, and fasteners Threading (taps and dies)	Early decision making criteria	Fused Deposition Modeling (FDM) - Stereolithography (SLA)	Cleanup and airtight modeling
	SLO-2					
S-6	SLO-1	Best Practices for constructing printable polygon meshes	Interfacing, support, and reinforcement	Knowing the product	Laminated Object Manufacturing (LOM) - Electron Beam Melting (EBM)	Loading models and arranging print stage
	SLO-2	Fundamental Structure - Combining, merging, and sewing up polygon meshes				

S 7-8	SLO-1	Best Practices for constructing printable polygon meshes - Fundamental Structure - Combining, merging, and sewing up polygon meshes	How the modeling software packages differ from CAD packages, Sketch/drawing based workflows, Similarities and differences between CAD and NURBS.	Brainstorming and critique in the early design phase Group critiques of in-progress projects	Printing Resolutions and Tolerances Materials Properties (Temperature, Flexibility, Strength, Brittleness)	Printing - Removing support material
	SLO-2					
S-9	SLO-1	Understanding two-manifold vs. non-manifold geometry	Form and function visualizing the assembly process	Early decision-making criteria Knowing the product Vision and Reality	3D Printing (3DP) – Selective laser melting (SLM)	Special topics – 3D Scanners and its types
	SLO-2	Exporting geometry - Laying out a simple model on a stage for print				
S-10	SLO-1	Hollow forms and the importance of reducing volume Cost of size, cost of volume, cost of detail, cost of time State table	Complex interactions and motorizations	Calculating the total cost Progress checks and group critiques of in-progress projects	Final cleanup and processing of files for printing	Reverse engineering, Concepts and its hardware and software
	SLO-2					
S 11-12	SLO-1	Clean and uniform topology, Illustrator, IGES, and other import/export pipelines	Broad overview of manufacturing techniques Molding, sculpting, lathing, lofting, welding, cutting, drilling, gluing, etc	Brainstorming and critique in the early design phase Group critiques of in-progress projects	Planning for injection molding - 3D Printing for injection molding	High speed machining
	SLO-2					

Learning Resources	1. Hod Lipson, Melba Kurman, Fabricated: The New World of 3D Printing, Wiley, 2013 2. Matthew Griffin, Design and Modeling for 3D Printing, Maker Media, Inc., 2013. 3. Rob Thompson, Manufacturing Processes for Design Professionals, Thames & Hudson; Reprint edition, 2007. 4. https://web.stanford.edu/class/me137/ 5. SolidWorks Gallery: http://www.3dcontentcentral.com/default.aspx	6. 3D Anatomy Models: http://lifesciencedb.jp/bp3d/?lng=en 7. AutoDesk Fusion360 HomePage: http://fusion360.autodesk.com 8. International Journal of Rapid Manufacturing 9. Academic Journals on 3D Printing 10. International Journal of Rapid Manufacturing
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

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Course Code	18ECO126T	Course Name	SPORTS BIOMECHANICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning		
CLR-1:	Understand the fundamental muscle action and locomotion in biomechanical point of view	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3
CLR-2:	Get an idea about the movement patterns and causes of movements						
CLR-3:	Understand the qualitative and quantitative analysis of sports movements						
CLR-4:	Acquire an idea about the basic concept of jumping & aerial movement and throwing & hitting						
CLR-5:	Get an idea about the injury prevention, rehabilitation and special Olympic sports						
CLR-6:	Get an overall idea about the applications of biomechanics in sports						
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:					
CLO-1:	Illustrate the muscle action in sport and locomotion	1	80	70			
CLO-2:	Analyze the movement patterns and its causes	1,2	80	70			
CLO-3:	Describe the Qualitative and Quantitative analysis of sports movements	2	80	70			
CLO-4:	Analyze the movement of action such as jumping, throwing, hitting and aerial movement	2	80	70			
CLO-5:	Identify the injury scenario and special Olympic sports	2	80	70			
CLO-6:	Outline the major concepts in sports biomechanics						

S-6	SLO-1	Factors Affecting Preferred Rates of Movement in Cyclic Activities	Forces in sport	Recording the movement	Javelin Throwing: an Approach to Performance Development	Sports after Amputation
	SLO-2	The Dynamics of Running	Combinations of forces on the sports performer	Experimental procedures -Two dimensional videography		
S-7	SLO-1	Resistive Forces in Swimming	Momentum and the laws of linear motion	Experimental procedures -Three dimensional videography	Shot Putting	Biomechanics of Dance
	SLO-2	Propulsive Forces in Swimming	Force-time graphs as movement patterns	Data processing	Hammer Throwing: Problems and Prospects	
S-8	SLO-1	Performance-Determining Factors in Speed Skating	Determination of the centre of mass of the human body	Projectile motion	Hammer Throwing: Problems and Prospects	Biomechanics of Martial arts
	SLO-2	Cross-Country Skiing: Technique	Fundamentals of angular kinetics and Generation and control of angular momentum	Linear velocities and accelerations caused by rotation	Hitting	
S-9	SLO-1	Cross-Country Skiing: Equipment	Measurement of force	Rotation in three-dimensional space	Kicking	Biomechanics of YOGA
	SLO-2	Factors Affecting Performance	Measurement of pressure	Rotation in three-dimensional space	Simple concept problems	

Learning Resources	1. Susan J Hall, "Basic Biomechanics", McGraw-Hill Higher Education, 7th edition, 2014	3. Jules Mitchell, "Yoga Biomechanics", 1 edition, Handspring Publishing Limited, 2018
	2. Vladimir M. Zatsiorsky, Biomechanics in Sports: Performance Enhancement and Injury Prevention, 1st ed., Blackwell Science Ltd, 2000	4. Roger Bartlett, Introduction to Sports Biomechanics: Analysing Human Movement Patterns, 2nd ed., Routledge, 2007

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	40 %	-	40 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	20 %	-	20 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Sathyanarayanan J, Mindray Medical India Pvt Ltd, sathyanarayananjayagopal@mindray.com	1. Dr. S. Poonguzhali, Anna University, poongs@annauniv.edu	1. Ms. Oinam Robita Chanu, SRMIST
2. Mr. Anuj Kumar, Bombardier Transportation, Ahmedabad, kumaranuj.anii@gmail.com	2. Dr. Meenakshi, Professor of ECE, CEG, Anna University, meena68@annauniv.edu	2. Dr. D. Ashok kumar, SRMIST
3. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	3. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	

Course Code	18ECO135T	Course Name	FUNDAMENTALS OF MEMS	Course Category	O	Open Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:		
CLR-1 :	Understand the importance of micro system technology			
CLR-2 :	Learn the operating principle of various micro sensors and actuators			
CLR-3 :	Impart the applications of various micro fabrication techniques			
CLR-4 :	Understand the differences and need for microfabrication			
CLR-5 :	Operate MEMS design tools to design simple micro devices			
CLR-6 :	Understand recent developments and challenges in MEMS			

Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:		
CLO-1 :	Appreciate the fundamental concepts in MEMS technology			
CLO-2 :	Understand the fabrication and machining techniques of MEMS devices			
CLO-3 :	Familiarize with the concepts of packaging of MEMS devices			
CLO-4 :	Appreciate the significance of micro fabrication processes			
CLO-5 :	Design and Simulate simple structures using MEMS software			
CLO-6 :	Analyze recent trends and developments in MEMS technology			

Learning		
1	2	3
Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)

Program Learning Outcomes (PLO)														
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
H	-	-	-	-	H	-	-	-	-	-	H	H	-	H
H	-	-	-	-	H	-	-	-	-	-	H	-	-	H
H	-	-	H	-	H	-	-	-	-	-	H	H	-	H
H	-	-	H	-	-	-	-	-	-	-	H	-	-	H
H	-	H	H	H	-	-	H	H	-	-	H	H	-	H
H	-	-	H	-	-	-	-	-	-	-	H	H	-	H

Duration (hour)	Introduction	Fabrication overview	Micromachining	Bonding & Sealing	Recent trends
	9	9	9	9	9
S-1	SLO-1	Introduction to MEMS and Brief recap of Macro devices	Introduction to Micro fabrication process	Introduction to MEMS packaging	Introduction to design tools and simulation
	SLO-2	Microelectronics and Micro systems	Significance of each technique	Challenges in packaging	FEM analysis
S-2	SLO-1	Scaling laws in geometry	Process Description of Photolithography	Different levels of Packaging	Design of a silicon die for a micro pressure sensor
	SLO-2	Silicon as ideal material and as substrate	Implementation of Photolithography	Die, device and system level	Simulation in software
S-3	SLO-1	Si wafer production	Process Description of CVD	Differences in IC packaging technology and MEMS packaging	Application of MEMS in automotive industry
	SLO-2	Cz process	Implementation, merits and demerits of CVD		Airbag deployment
S-4	SLO-1	Sequential steps in wafer processing	Process Description of PVD	Die Preparation	Optical MEMS Application
	SLO-2		Implementation, merits and demerits of PVD	Plastic encapsulation and its significance	Micro mirrors
S-5	SLO-1	Chemical and mechanical properties of Si and compounds	Process Description, implementation of Ion implantation	Types of wire bonding Thermo compression type	Micro fluidics Application
	SLO-2	Chemical and mechanical properties of Polymers, Quartz and GaAs	Oxidation process	Thermo sonic, Ultra sonic type	Lab on chip module
S-6	SLO-1	Chemical, Biomedical type Micro sensors	Diffusion process	Types of surface bonding – Adhesive	IR and Gas sensing
	SLO-2	Piezoelectric type of Micro sensors	Wet etching methods	soldering, SOI type of bonding	Thermal sensors
S-7	SLO-1	Thermal, SMA, Piezoelectric actuators	Properties of etchants	Anodic bonding and lift off process	Micro power generation
			Process Design-block diagram and description		

	SLO-2	Electro static type Micro Actuators	Dry etching methods	Electro-mechanical design, Thermo-electric design	Precautions to be taken	Micro TEG
S-8	SLO-1	Micro devices- operation of Micro gears and micromotors	Production of plasma	CAD- block diagram description and implementation	Types of sealing- Micro shells, Hermetic sealing	Chemical sensors
	SLO-2	Micro devices –operation of Micro valves and pumps	Etch stop methods		Micro 'O' rings, Reactive seal	Micro humidity sensors
S-9	SLO-1	Case study	Case study	Case study	Selection of packaging materials	Micro pressure sensors
	SLO-2				Material requirements	Paper MEMS

Learning Resources	1. Tai-Ran Hsu, "MEMS and MICROSYSTEMS", 22 nd reprint edition, Wiley & sons, 2015	3. Vardhan Gardener, "Micro sensors and smart devices". John Wiley & Sons, 2001
	2. M. Madou, "Fundamentals of Micro fabrication", Taylor and Francis group, 2002	4. NPTEL link: https://nptel.ac.in/downloads/112108092/

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry		Experts from Higher Technical Institutions
1. D. Karthikeyan, Controlsoft Engineering India Pvt Ltd, karthikeyan.d@controlsoftengg.in		1. Dr. J. Prakash, MIT, Chennai, prakait@rediffmail.com
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com		2. Dr. D. Nedumaran, Madras University, dnmaran@gmail.com
		Internal Experts
		1. Dr. A. Vimala Juliet, SRMIST
		2. R. Bakiyalakshmi, SRMIST

Course Code	18MEO101T	Course Name	ROBOTICS ENGINEERING AND APPLICATIONS	Course Category	O	Open Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Be familiar with basic concepts of robotics	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Be familiar with various end effectors and transformation techniques	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Be familiar with different sensors and system controllers																		
CLR-4 :	Be familiar with the design of robot work cell layouts and interfacing																		
CLR-5 :	Be familiar with different robot programming languages and applications in different fields																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Understand the basic concepts of robotics	1& 2	90	85	H		M												
CLO-2 :	Understand the various end effectors and application of transformation techniques	1	90	85	H		M		M		M								
CLO-3 :	Understand the different sensors and system controllers	1	90	85	H						M								
CLO-4 :	Understand the design of robot work cell layouts and interfacing	1&2	90	85	H								H						
CLO-5 :	Understand the different robot programming languages and applications in different fields	1&2	90	85	H														

		Basic concepts of robotics	End effectors and transformation techniques	Sensors and system controllers	Work cell design layouts and interfacing	Robot programming languages and applications
Duration (hour)		9	9	9	9	9
S-1	SLO-1	Basic concepts of robotics (Laws of robotics, robotic systems), RIA definition	End effectors-Introduction, classification.	Sensor devices	Robot cell lay outs	Robot language, classification.
S-2	SLO-1	Robot anatomy (Robot configurations, Robot motions, Joint notation scheme) , Manipulators	Mechanical, Magnetic grippers.	Types of sensors (contact, position and displacement sensors)	Robot work cell design and control	Programming methods, off and on line programming.
S-3	SLO-1	Precision movement (Spatial resolution, accuracy, repeatability) Work volume, robot specifications	Vacuum and adhesive gripper	Force and torque sensors	Multiple robots	Lead through method, powered and Manual lead through and Teach pendent method.
S-4	SLO-1	Types of Robot drives - electric drives	Gripper design and Gripper force analysis	Proximity and range sensors, acoustic sensors.	Machine interface	VAL systems and language, Simple program.
S-5	SLO-1	Hydraulic and pneumatic drives	Orientation of wrist	Robot vision systems, Sensing and digitizing.	Safety considerations in cell design	Application of Robots, Material handling, Constrains, Machine loading and unloading.
S-6	SLO-1	Basic robot motions, Point to point control and continuous path control.	2D transformation (scaling, rotation, translation)	Image processing and analysis.	Interlocks in work cell	Assembly Robot, Assembly operation, RCC device, Benefits- Inspection robot, used in Quality control.
S-7	SLO-1	Forward and inverse kinematics for 2DOF manipulator	3D transformation (scaling, rotation, translation)	Robot control system - Unit control system	Types of work cell controllers	Welding and Spray painting Robots, features, sensors, Advantages
S-8	SLO-1	Forward and inverse kinematics for 3DOF manipulator	Homogeneous transformations	Adaptive and Optimal control	Robot cycle time analysis	Mobile and microbots, types, mobility and application.
S-9	SLO-1	Machine intelligence	Coordinate frames - Description of Objects in Space	Basic Relationship Between Pixels	Error detection and Error recovery	Search techniques in AI and robotics

Learning Resources	<ol style="list-style-type: none"> 1. Mikell P. Groover, "Industrial Robotics Technology Programming and Applications", McGraw Hill Co., New Delhi, 2012. 2. Deb .S.R, "Robotics technology and flexible automation", Tata McGraw Hill publishing company limited, New Delhi, 2010. 3. Klatfer.R.D, Chmielewski.T.A and Noggins, "Robot Engineering: An Integrated Approach", Prentice Hal of India Pvt. Ltd., New Delhi, 2010. 4. Fu K.S, Gonzalez, R.C., & Lee, C.S.G., "Robotics control, sensing, vision and intelligence", McGraw Hill Book Co., Singapore, Digitized 2007. 	<ol style="list-style-type: none"> 5. Craig.J.J, "Introduction to Robotics mechanics and control", Addison- Wesley, London, 2008. 6. References: 7. S. Mukherjee, Robotics, Khanna Book Publishing Co., New Delhi 8. S.K. Saha, Introduction to Robotics, TMH 9. T.C. Manjunath, Fundamentals of Robotics, Nandu Printers and Publishers Private Limited, Mumbai
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc., SLO – Session Learning Outcome

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	Dr. BIJAY KUMAR ROUT, BITS, Pilani	V.RAGHAVENDRA RAO, SRMIST
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	SELVA KUMAR .S, FORD INDIA LIMITED, CHENNAI.	Dr. M. Iqbal, SRMIST

Course Code	18ME0102T	Course Name	ALTERNATIVE SOURCES OF ENERGY	Course Category	E	Open Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Familiarize with the solar energy technologies	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Study the wind energy and hybrid energy systems		
CLR-3 :	Be familiar with the concepts of ocean, hydro and geothermal energy systems		
CLR-4 :	Familiarize with the biomass energy conversion technologies		
CLR-5 :	Familiarize with the operations of direct energy conversion systems		
CLR-6 :	Be familiar with alternative energy needs with its availability		

		Level of	Expected	Expected	Engineering	Problem	Design &	Analysis,	Modern	Society &	Environm	Ethics	Individual	Commun	Project M	Life Long	PSO - 1	PSO - 2	PSO - 3
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																	
CLO-1 :	Recognize and analyze the solar energy systems	1&2	90	80	H	M		M										H	
CLO-2 :	Acquire knowledge on wind energy conversion systems	1	90	80	H	M	M	L			M							H	
CLO-3 :	Understand the ocean, hydro and geothermal energy	1	90	80	H						M							H	
CLO-4 :	Understand and identify biologically degradable resources and its energy conversion processes	1&2	90	80	H													H	
CLO-5 :	Recognize the design needs for direct energy conversion systems	1&2	90	80	H		M											H	
CLO-6 :	Understand and renovate future energy needstowards renewable energy	1	90	80	H	M	M				M							H	

Duration (hour)	Solar Energy	Wind Energy	Ocean, Hydro and Geothermal Energy	Biomass	Direct Energy Conversion Systems
9	9	9	9	9	9
S-1	SLO-1 Solar energy, Solar radiation and its measurements	Wind energy, Basic principle and Components of wind energy conversion system	Wave characteristics and wave energy conversion systems	Biomass, Sources of biomass	Basics of direct energy conversion systems, thermo electric and thermionic power generations
S-2	SLO-1 Types of solar thermal collectors	Wind data, site selection and energy estimation	Tidal energy and its types	Pyrolysis, combustion and gasification process	Fuel cell principles and its classification
S-3	SLO-1 Solar thermal applications for water heaters, solar stills and solar pond	Types of Horizontal axis wind turbine such as Single blade, Two blades,	Estimation of energy and power in single basin tidal system	Updraft and downdraft gasifier	Types - Phosphoric acid, polymer electrolyte membrane fuelcell, molten carbonate fuel cell and solid oxide fuel cell
S-4	SLO-1 Solar thermal applications for refrigeration and air conditioning system	Types of Horizontal axis wind turbine such as Multi blades, Dutch and Sail type	Ocean thermal energy conversion for open system	Fluidized bed gasifier	Fuel cell conversion efficiency and applications
S-5	SLO-1 Solar thermal applications for solar dryer, solar cookers and solar furnaces	Vertical axis wind turbinesuch as Savonius Rotor, Darrieus Type	Ocean thermal energy conversion for closed system.	Fermentation and digestion process	Open cycle magneto hydrodynamic power generation
S-6	SLO-1 Drawbacks/Real field issues in solar thermal systems, sensible and latent heat thermal energy storage systems to avoid day night issues	Design consideration of horizontal axis wind turbine	Hydro power plants for small, mini and micro system	Fixed and floating digester biogas plants	Closed cycle magneto hydrodynamic power generation
S-7	SLO-1 Solar thermal power generation systems	Aerofoil theory, Analysis of aerodynamic forces acting on the blade	Exploration of geothermal energy.	Design considerations of digester	Hydrogen energy: properties and its production methods
S-8	SLO-1 Solar photovoltaic systems: basic working principle, componentsand its applications	Performance of wind turbines	Geothermal power plants	Operational parameter of biogas plants, Economics of biomass power generation	Electrolysis, thermo-chemical, fossil fuels and solar energy methods

S-9	SLO-1	Performance assessment of any one solar thermal and electric systems	Hybrid energy systems (solar and wind), environmental issues of wind energy	Challenges, availability, geographical distribution, scope	Sources and production of biodiesel and ethanol	Hydrogen storage, transportation and applications
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Learning Resources	<ol style="list-style-type: none"> Godfrey Boyle, "Renewable energy", 2nd Edition, Oxford University Press, 2010 G.D Rai, "Non-Conventional Energy Sources", Khanna Publishers, 5th Edition, New Delhi, 2011 Twidell.J.W and Weir.A.D, "Renewable Energy Resources", 1st Edition, UK, E.&F.N. Spon Ltd, 2006 Domkundwar.V.M, Domkundwar. A.V, "Solar energy and Non-conventional sources of energy", Dhanpatrai & Co. (P) Ltd, 1st Edition, New Delhi, 2010 B.H Khan, "Non-conventional Energy Resources", 2nd Edition, New Delhi, Tata McGraw Hill, 2009 S.P. Sukatme, J.K. Mayak, "Solar Energy-Principles of thermal collection and storage", 3rd edition, New Delhi, McGraw Hill, 2008 Tiwari.G.N, Ghosal.M.K, "Fundamentals of renewable energy sources", 1st Edition, UK, Alpha Science International Ltd, 2007. D. LE GOURIERES, "Wind Power Plants, Theory and Design", Pergamon, 1982.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course designers		
Experts from Industry	Experts from Higher Technical Institutions	Faculty in-charges
Mr.M.V.Ramachandran, Sr.Deputy Director & Plant Head (OSD), E-mail - mv.rama@natrip.in	Dr.B.Durga Prasad Professor, JNTUA College of Engineering, Email: mukdhajntu@gmail.com	Dr. R.Senthil Kumar, SRM IST Email: senthilkumar.r@ktr.srmuniv.ac.in
Mr.M.Periasamy Chief Manager Neyveli New Thermal Power Project Email: mpsamy34912@gmail.com	Dr. K. R. Balasubramanian Associate Professor Department of Mechanical Engineering National Institute of Technology Email:krbala@nitt.edu	Dr. G. Balaji, SRM IST Email: balaji.g@ktr.srmuniv.ac.in

Course Code	18MEO103T	Course Name	ENERGY SYSTEMS FOR BUILDINGS	Course Category	O	Open Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Be familiar with the energy transfer in buildings	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Study the solar passive heating and cooling systems		
CLR-3 :	Be familiar with the lighting systems of buildings		
CLR-4 :	Study the Heat control and ventilation methods in buildings		
CLR-5 :	Be familiar with the Green buildings		
CLR-6 :	Be familiar with the design and energy management of buildings		

Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:	Level	Expected	Expected	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3	
CLO-1 :	Acquire knowledge on heating and cooling load calculations on energy efficient buildings		1,2 & 3	90	80	H	M		M											H	
CLO-2 :	Understand the concept of solar passive heating and cooling		1,2	90	80	H	M					M								H	
CLO-3 :	Understand the concept of Day lighting and electrical lighting systems		1&2	90	80	H					L	M								H	
CLO-4 :	Recognize the design parameters influencing thermal design of buildings		1,2 & 3	90	80	H	M		M			M								H	
CLO-5 :	Understand the concept of green buildings and certifications		1 & 2	90	80	H		M			L	M								H	
CLO-6 :	Acquire knowledge on design and energy management of buildings		1,2 & 3	90	80	H	M	M	M		L	M								H	

		Energy transfer in buildings	Passive solar heating & Cooling	Lighting systems of buildings	Heat control & ventilation	Green buildings
Duration (hour)		9	9	9	9	9
S-1	SLO-1	Concepts of energy efficient buildings	General principles of passive solar heating	Introduction to lighting systems of buildings	Introduction to heat control and ventilation	Introduction to green building
S-2	SLO-1	Conventional versus Energy Efficient buildings	Key design elements of passive heating	Glazing materials: Sources and concepts of optical materials	Design parameters influencing thermal design of buildings	Green building features and green construction materials
S-3	SLO-1	Climate and its influence in building design for energy requirement, Thermal properties of building materials	Direct solar heat gain by Trombe mass walls	Concepts of day lighting	Heat transmission through building sections	Green building rating tools
S-4	SLO-1	Codes and standards for the energy efficient buildings-ECBC codes	Passive cooling and its Key design elements, ventilation	Components of daylight factors and Recommended daylight factors	Effect of heating with orientation of buildings	Integrated ecological design, Sustainable site and landscaping
S-5	SLO-1	Energy balance for cooling and heating of buildings	Water walls, evaporative cooling	Day lighting analysis	Ventilation requirements for heat control in buildings	Indoor air quality, Water and waste management systems
S-6	SLO-1	Calculation of heating load, Heat losses and Internal heat sources	Convective air loops and solar chimney effects	Electrical lighting and Illumination requirement	Standards for ventilation	Green Globe, LEED, GRIHA, IGBC codes & certifications
S-7	SLO-1	Calculation of cooling loads of the building	Predicting ventilation in buildings, window ventilation calculations	Selection of luminaries and performance parameters	Ventilation designs, Energy conservation measurement	Standards for green building certifications
S-8	SLO-1	Low and zero energy buildings	Thermal insulation, load control, air filtration,	Electric lighting control for day lighted buildings	Natural ventilation methods	Economics, managing initial costs of green buildings
S-9	SLO-1	Future building design aspects	Odor removal and heat recovery in large buildings	Comparison of day and electrical lighting	Forced ventilation methods	Environment benefits of green buildings

Learning Resources	1. Means R.S., "Green building: project planning and cost estimating", Kingston, 2006 2. Kibert C.J., "Sustainable Construction: Green Building Design", 2nd edition, Wiley, 2007 3. Boecker J., Scot Horst, Tom Keiter, Andrew Lau, Markes Sheffer, Brian Toevs, Bill Reed, "Integrative Design Guide to Green Building", Wiley, 2009 4. Eicker U., "Low Energy Cooling for Sustainable Buildings", Wiley, 2009 5. Gevorkian P., "Alternative Energy Systems in Building Design", McGraw-Hill, 2010.	6. Harvey D.L., "Handbook on Low-Energy Buildings and District-Energy Systems", Earthscan, 2006. 7. Attmann O., "Green Architecture", McGraw-Hill, 2010 8. Kubba S., "Handbook of Green Building Design and Construction", Elsevier, 2012. 9. Majumdar, M., "Energy – Efficient Buildings in India", Tata Energy Research Institute, Ministry of Non-Conventional Energy Sources, 2002. 10. Energy Conservation Building Codes: www.bee-india.nic.in
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	Dr. S. Suresh, Associate Professor, Dept. of Mechanical Engineering, National Institute of Technology, Tiruchirappalli - 620 015.	Dr. C. Selvam Assistant Professor, Department of Mechanical Engineering SRM IST Email: selvam.c@ktr.srmuniv.ac.in
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	Mr. Cibi Chakravarthy N Assistant Engineering Manager-HVAC Engineering Design and Research Centre, L&T Construction, Mount Poonamallee Road, Manapakkam, Chennai-89.	Mr. P. Sundaram Assistant Professor, Department of Mechanical Engineering SRM IST Email: sundaram.p@ktr.srmuniv.ac.in

Course Code	18MEO104T	Course Name	OPERATION RESEARCH	Course Category	O	Open Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	Yes		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Be familiar with the Objectives, Characteristics, Necessity, Scope, Applications of OR and LPP in simplex and to determine what resources are assigned to get most optimum output	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Be familiar with the Applications of LPP in determining resource allocation in existing business structures and in the decision making process of replacing a used equipment		
CLR-3 :	Be familiar with the scheduling and operational problems in manufacturing, service and distribution		
CLR-4 :	Know the waiting line models and all aspects of managing a company's inventories		
CLR-5 :	Determine how decisions are made given unknown variables and an uncertain decision environment framework and how and why people make decisions		
CLR-6 :	Familiar with resource management techniques and its applications in industries		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom) Expected Proficiency (%) Expected Attainment (%)	Engineering Knowledge Problem Analysis Design & Development Analysis, Design, Research Modern Tool Usage Society & Culture Environment & Sustainability Ethics Individual & Team Work Communication Project Mgt. & Finance Life Long Learning PSO - 1 PSO - 2 PSO - 3
CLO-1 :	Understand the Concepts of Linear programming technique	1&2 90 85	M H - M - L - - - - - M - - H H M
CLO-2 :	Learn the applications of Transportation and Replacement models	1 90 85	M H - M - L - - - - - M - - H H M
CLO-3 :	Study the various Techniques of scheduling and sequencing	1 90 85	M H - M - M - - - - - L - - H H M
CLO-4 :	Gain detailed knowledge of Inventory control and Queuing theory	1&2 90 85	M H - M - M - - - - - H - - H H M
CLO-5 :	Understand the techniques involved in Decision theory and Game theory	1&2 90 85	M H - L - M - - - - - M - - H H M
CLO-6 :	Learn resource management techniques to manage resources multiple departments and projects	1&2 90 85	M H - M - M - - - - - M - - H H M

Duration (hour)	9	9	9	9	9
S-1 SLO-1	Operation Research and decision making- Development, Definition, Characteristics, Necessity, Scope, Applications, Advantages, Limitations	Assignment models [Balanced, Unbalanced, Maximization]	Problem of Sequencing, Processing 'n' jobs through two and three machines.	Introduction – Necessity for Maintaining Inventory, Inventory Costs – Types- Variables in an inventory problem – Lead time, Reorder Level, EOQ	Steps in Decision theory approach - Decision making Environments - Making under conditions of Certainty, Uncertainty, Conditions of Risk
S-2 SLO-1	Objectives, Phases, Types of mathematical models in OR and constructing the model. Linear Programming - Requirements, Assumptions, Advantages, Limitations, Applications	Assignment models - Travelling Salesman Problem (Shortest Cyclic Route Models)	Problem of Sequencing, Processing 'n' jobs through two and three machines.	Deterministic Inventory Models – Purchasing model with no shortages, Manufacturing model with no shortages	Steps in Decision theory approach - Decision making Environments - Making under conditions of Certainty, Uncertainty, Conditions of Risk
S-3 SLO-1	Formulation of linear programming problem, Simplex method - Graphical method of Solution	Transportation problem – Assumption, Definition, Formulation and Solution - North west corner method, Least cost method, Vogel's approximation method.	Project - Planning, Scheduling, Controlling – Network Analysis – Constructing a project network - Fulkerson's Rule	Purchasing model with shortages, Manufacturing model with shortages	Decision making conditions – problems
S-4 SLO-1	Simplex method - Analytical - Canonical and Standard forms of LPP	Transportation problem – MODI method	Network computations – Earliest Completion time of a project and Critical path, Floats	Multi item deterministic model, safety stock, storage quantity discount	Decision trees. - Utility Theory
S-5 SLO-1	Artificial Variables Techniques - Big M- method	MODI method [balanced in transportation model]	Programme Evaluation Review Technique	Problems in Multi item deterministic model	Problems in Decision trees

S-6	SLO-1	Artificial Variables Techniques - Two Phase method	MODI method [Unbalance in transportation model]	Total Slack, Free Slack, Probability of achieving completion date	Queuing Models - Elements - Kendall's Notation – Poisson arrivals and exponential service times	Theory of Games , Characteristics Game models -Definition - Rules - Pure Strategy
S-7	SLO-1	Problems in Artificial Variables Techniques	Replacement Model, Replacement of items that deteriorate, Gradually, Fail suddenly	Cost Analysis - Crashing the network	Waiting time, Idle time cost, Single channel problem	Optimal solution of two person zero sum games, mixed strategies
S-8	SLO-1	Sensitivity analysis – Change in objective function	Group Replacement policy analysis - Problems	Resource Scheduling - Advantages, Limitations	Multi-channel problem	Graphical solution of (2xn) and (mx2) games
S-9	SLO-1	Sensitivity analysis – Change in the availability of resources	Group Replacement policy analysis - Problems	Vehicle routing problems	Poisson arrivals and service time	Solution of (mxn) games by linear programming

Learning Resources	1. Premkumar Gupta and Hira, "Operation Research", Third Edition S Chand Company Ltd., New Delhi 2014. 2. A.C.S.Kumar, "Operation Research", Yes Dee Publishing Ltd., Chennai 2015. 3. Fredric.S.Hilleer and Gerold J. Lieberman, "Introduction to Operation Research", 10th Edition, 2014. 4. Handy, "A. Taha, "Operations Research", 10th Edition, Prentice Hall of India, New Delhi, 2016.	5. Philip and Ravindran, "Operational Research", John Wiley, 2000. 6. Sundaresan.V, GanapathySubramanian.K.S, "Resource Management Techniques:Operations Research" A.R Publications, 2003. 7. Panneerselvam.K, "Operation Research", Prentice Hall of India, 2006.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. R. Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in, rkpearls@yahoo.com	1. Dr. Rajendran C , IITM	1. Mr. S. Oliver Nesa Raj, SRMIST
2. Dr. A. Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	2. Dr. Srinivasan G , , IITM	2. Dr. P. Godhandaraman, SRMIST

Course Code	18ME0105T	Course Name	MATERIALS MANAGEMENT	Course Category	O	Open Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	To Understand the principles of materials Management	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	To Acquire knowledge on Inventory control and materials forecasting	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Be familiar with the Material planning and control	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Be familiar with the Storage and distribution	Expected Attainment (%)	Design & Development
CLR-5 :	To attain the knowledge about material accounting and budgeting		Analysis, Design, Research
CLR-6 :	Be familiar with the basic aspects of Material Management, Inventory control procedures, Codification of materials, Online material management system.		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Understand the Materials management and to recognize the relationship with other functional areas and acquire the knowledge on inventory control and material forecasting	1&2 90 85	H
CLO-2 :	Acquire knowledge on Inventory control and materials forecasting	1 90 85	H
CLO-3 :	Appreciate the Job evaluation and understand the need of scheduling	1 90 85	H
CLO-4 :	Understand the theory behind the Project management and acquire the knowledge about MRP, Storage design and storage system and layout	1&2 90 85	H
CLO-5 :	Obtained the knowledge about Materials management controls, Budgetary control	1&2 90 85	M
CLO-6 :	Recognize the use of materials management, acquire knowledge on the inventory management and control procedures, Codification of materials, Online material management system,Purchasing policies and procedures	1&2 90 85	M

Duration (hour)	9	9	9	9	9
S-1	SLO-1	History and development of material management, Policy manual: A to Z items	Materials forecasting, Selection of inventory control, BOM	Codification of materials Storage systems and equipment	Purchasing policies and procedures
S-2	SLO-1	Concept and details of integrated materials and management systems	Spare parts managements and techniques	Storage design, Stores layout	Legal aspects of purchasing
S-3	SLO-1	Important and scope of materials management	Inventory control systems, Lead time analysis, Optimum order quantity	Storage systems and equipments	Selection of sources of supply
S-4	SLO-1	Materials purchase policy and economic ordered quantity	Types of Lead time; Administrative lead time, Supplier lead time, Transport lead time	Stores preservation	Vendor evaluation and rating
S-5	SLO-1	Purchasing cycle, A to Z purchase order	Flow charting techniques to reduce various types of lead time	Stores procedures Stock valuation and verification	Vendor development, Price and Cost analysis
S-6	SLO-1	Functions of Materials Intelligence (MIS)	Aggregate inventory management	Ware housing Distribution management	Ethical buying, Ethical concept in buying
S-7	SLO-1	Specification and Standardization in Materials Management	Problems in Inventory control	Store accounting	Purchasing organisations, Purchasing cycle and contracts
S-8	SLO-1	Make or buy decision, buying process	Materials requirement planning	Material handling system and equipments	Sourcing supplier evaluation
S-9	SLO-1	Purchasing cycle and economic ordered quantity	Supply chain Management	Need for inventory, Inventory cost, Inventory control measures(ABC, XYZ analysis)	Legal aspects of purchasing
					Coding of materials, material purchasing policies and procedures

Learning Resources	1. "Operations and Supply Chain Management" Ann K. Gatewood, Publisher: Pearson 8 editions, January 2016.	5. "Purchasing and Materials Management", Gopalakrishnan.P, Tata McGraw Hill Education, 01-Mar-2001.
	2. "Introduction to Materials Management", Tony K. Arnold, 8th Edition by Steve Chapman, , Publisher: Pearson edition, 2017	6. "Materials Management: An Integrated Systems Approach" Publisher: Springer original 1st edition, 2014.
	3. "Inventory Accuracy: People, Processes, & Technology, OPS Publishing: 1 edition, March 2003.	7. "Material Management an integrated approach" Publisher, PHL Learning Private Limited, 3rd edition, 2011
	4. "Operations Management, Mahadevan B, Publisher: Pearson 3rd edition, 2017.	8. "Production and operations management", SN.Chary, Tata McGraw Hill Education, 5th edition, 2012.

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr.Samsudin-ATI-Chennai	Dr.B.S.MURTY-IIT MADRAS	Mr.R.Saravanakumar
Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	Dr.K.G.Pradeep-IIT MADRAS	Mr. Selwyn Jebadurai

Course Code	18MEO106T	Course Name	ENVIRONMENTAL POLLUTION AND ABATEMENT	Course Category	O	Open Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 : Be Familiar the principles and methods of controlling various types of pollution.		1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 : Understand the emission control techniques.		Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 : understand water treatment and solid removal methods		Expected Proficiency (%)	Problem Analysis
CLR-4 : Be Familiar with aerobic and anaerobic treatments.		Expected Attainment (%)	Design & Development
CLR-5: Be Familiar with the nature of solid waste and their disposal.			Analysis, Design, Research
CLR-6 understand the environmental pollutants and their control			Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 : Understand the basics of pollution and the control methods		1,2 90 80	H
CLO-2 : Acquire knowledge about various air pollutants and emission control techniques.		1,2 90 80	H
CLO-3 : Understand the water treatment methods and solid removal		1,2 90 80	H
CLO-4 : Acquire knowledge about the Aerobic and anaerobic treatments		1,2 90 80	H
CLO-5 : Acquire knowledge about the various Solid waste disposal methods.		1,2 90 80	H
CLO-6 : Acquire knowledge about the environmental pollution and control		1,2 90 80	H

Duration (hour)	Basics of Pollution and Prevention	Air Pollution	Water Pollution	Biological Treatment	Solids disposal
S-1	SLO-1 Environment and environmental pollution from chemical process industries, characterization of emission and effluents	Sources and formation of Sulfur oxides (SOx); nitrogen oxides (NOx), carbon monoxide	Biological uptake of pollutants	Anaerobic degradation of organic matter	Solids waste disposal – composting process and its phases
	SLO-2 -	total suspended particulate matter, respirable particulates			
S-2	SLO-1 environmental Laws, rules and standards for ambient air	photo-chemical oxidants. Other pollutants	effect of pollutants on land, vegetation, animals and human health	Trickling filter – Process description	Sanitary landfill- Principle and process
S-3	SLO-1 noise pollution- effects, control	Green house effect, green house gases: CO ₂ , CH ₄ , N ₂ O, CFCs,	bio-deterioration, bioaccumulation	aerobic treatment – aeration units	gasification process.
	SLO-2 -	water vapor concentration, alternatives for CFCs, global warming and climate change			
S-4	SLO-1 Process modification: alternative raw material, recovery of by product	ozone layer depletion- ozone depleting processes, ozone hole,	bio-magnification and eutrophication	biochemical kinetics: Hydraulic detention time, Mean residence time	Upward, Downward, cross draft gasifier
	SLO-2	environmental effects and strategies for ozone layer protection,			
S-5	SLO-1 recycle and reuse of waste, energy recovery and waste utilization	acid rain-sources and impact	infectious microbial agents in water system	Types of activated sludge process	Incineration and Pyrolysis
	SLO-2				
S-6	SLO-1 Material and energy balance for pollution minimization.	wet gas scrubbing techniques	consequences on human health.	Tapered aeration	Quantum and nature of solid waste
	SLO-2				
S-7	SLO-1 Water use minimization	gaseous emission control by absorption and adsorption methods	Physical treatment- pre-treatment	Stepped aeration	bio methanation -phases involved and factors
	SLO-2				

S-8	SLO-1	<i>Fugitive emission, effluents and leakages</i>	<i>Design of cyclones, Electrostatic Precipitation</i>	<i>solids removal by settling and sedimentation</i>	<i>sludge separation</i>	<i>Pelletization, landfill and gas recovery</i>
	SLO-2					
S-9	SLO-1	<i>Pollution control through housekeeping and maintenance..</i>	<i>fabric filters and absorbers</i>	<i>filtration and centrifugation</i>	<i>Aerobic treatment units (ponds, lagoons, oxidation ditch)</i>	<i>municipal solid waste disposal- Best management practices for containers</i>
	SLO-2			<i>coagulation and flocculation.</i>		

Learning Resources	1. Vallero D; "Fundamentals of Air Pollution", 4 th Ed; Academic Press, 2008	4. Pichtel J; "Waste Management Practices: Municipal, Hazardous and Industrial", CRC, 2005
	2. Eckenfelder W.W; "Industrial Water Pollution Control", 2 Ed; McGraw Hill, 2000	5. Tchobanoglous G., Burton F. L. and Stensel H.D., "Waste Water Engineering: Treatment and Reuse", 4th Ed; Tata McGraw Hill, 2010
	3. Kreith F. and Tchobanoglous G., "Handbook of Solid Waste Management", 2 Ed; Mc Graw Hill, 2002	

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	Dr. S.K. Rani Professor & Dean (SP & CS) Crescent Institute of Science and Technology	V. Praveena Assistant Professor
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	M Malathi Manager R &D, IP Rings	Dr. P. Chandrashekar SRMIST

Course Code	18MEO107T	Course Name	NANO ROBOTICS	Course Category	0	Open Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Be familiar with the basics of Robotics and Nano Technology			Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLR-2 :	Be familiar with the Micro/Nano Sensors						Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3	
CLR-3 :	Be familiar with the Micro/Nano Actuators						H	L	L	L	L								M	H	L	H
CLR-4 :	Be familiar with the Micro/Nano Manipulators						H	L	M	M	H								M	H	L	H
CLR-5 :	Be familiar with the Micro/Nano Robotics manufacturing and control techniques						H	L	M	M	H								M	H	L	H
CLR-6 :	Familiar with the Micro/Nano Sensors, Actuators, Manipulators and Manufacturing Techniques						H	L	M	M	H								M	H	L	H
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	Acquire knowledge on Basics of Robotics and Nano Technology			1	90	85																
CLO-2 :	Understand the various Micro/Nano Sensors			1&2	90	85																
CLO-3 :	Understand the Micro/Nano Actuators			1&2	90	85																
CLO-4 :	Understand the Micro/Nano Manipulators			1&2	90	85																
CLO-5 :	Acquire knowledge on Micro/Nano Robotics manufacturing and control techniques			1	90	85																
CLO-6 :	Learn Micro/Nano Sensors, Actuators, Manipulators and Manufacturing Techniques			1&2	90	85																

		Fundamentals of Robotics and Nanotechnology	Micro/Nano Sensors	Micro/Nano Actuators	Micro/Nano Manipulators	Micro/Nano Robotics manufacturing and control techniques
Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction-History of Robotics	Far field and Near field Imaging sensors	Bending type Piezoelectric actuators	SPM Probes and Micro nano grippers	CAD models and CAD models of nanostructures
S-2	SLO-1	Robot Anatomy and Work Volume	Position and Capacitive sensors	Unimorph, Bimorph and stack type actuators	Atomic manipulation using STM	Micro nano assembly and Self assembly
S-3	SLO-1	Robot Drive Systems	Linear Variable Differential Transformer	Piezo tube and Thin film types ZnO	Optical Tweezers	Precision micro/nanoparticle assembly using SEM
S-4	SLO-1	End Effectors and Robotic Sensors	Interferometric sensors	Surface acoustic waves and Electrostatic actuators	Dielectrophoresis	Guided Self Assembly
S-5	SLO-1	Actuators and Power transmission system	Accelerometers and Gyroscopes	Thermal and Ultrasonic actuators	Bio manipulation	Automated manipulation of nanoparticles
S-6	SLO-1	Importance of Nanotechnology-History of Nanotechnology	Force, Pressure Sensors	Electro and Magnetostrictive based actuators	Slip motion (nanomanipulation)	Micro Mechanical Flying robot
S-7	SLO-1	Opportunity at the nano scale-length and time scale in structures	Chemical and Flow sensors	Shape memory alloy actuators	Carbon nanotube manipulation using nanopores	Kinematics and Dynamics of Robot
S-8	SLO-1	Nano device structures	Strain gauge and Deflection based AFM	Polymer actuators, Dielectric elastomers	High density data storage using nanopores	Kinematics and Dynamics of Robot
S-9	SLO-1	Overview of Nano robotics system Components	Visual force sensing, Bending imaging and Tactile sensors	CNT actuators and Biomolecular Motors	Simple case study	Teleoperation based, Task based and automatic control robot

Learning Resources	1. Norio Taniguchi, "Nanotechnology", Oxford university press, Cambridge, 1996.	4. Fatikow.S. Rembold.U., "Microsystem Technology and Microrobotics", Springer Verlag, 1997
	2. Ning Xi, Guangyoung Li, "Introduction to Nanorobotic Manipulation & Assembly" Artech House press 2012	
	3. Elwenspoek.M and Wiegerink.R., "Mechanical Microsensors", Springer-Verlag Berlin, 2001.	
	5. Bhushan.B., "Handbook of Micro/Nanotribology", CRC Press, 2nd Ed., 1999.	

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. R. Dinesh kumar, TAFE India Pvt Ltd, Chennai	1. Dr. V. Srinivasan, Annamalai University, srinivaghavan@yahoo.com	Mr.S.Dinesh, SRM IST
2. Mr. K.Nivasraj, Vedanta ltd, Goa	2. Dr.Assaitambi, Govn. Col.of. Eng,sengipatti, Thanjavur, basaitambi@gcetj.edu.in	Mr.N.Karthikeyan, SRM IST

Course Code	18MEO108T	Course Name	AUTOMATIC CONTROL SYSTEMS	Course Category	O	Open Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards			NIL

Course Learning Rationale (CLR):		The purpose of learning this course is to:		Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand the history of control systems, relevance of input and output transfer function.			1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Impart the knowledge on principles involved in modeling various mechanical and state space representations of systems.			Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Gain knowledge on steady state and transient state response and stability criterion						H	H	H	M	-	-	-	-	-	-	-	-	-	-	-
CLR-4 :	Know application of various tools used for stability analysis of various systems						H	M	H	M	M	-	-	-	-	-	-	-	-	-	-
CLR-5 :	Understand upon Discrete control systems and Z transformations						H	H	H	M	M	-	-	-	-	-	-	-	-	-	-
CLR-6 :	Impart knowledge on developing a system and studying on the stability of the system using various tools						H	M	-	M	-	-	-	-	-	-	-	-	-	-	-
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																			
CLO-1 :	model systems that are applied to the reality			1 & 2	80	85															
CLO-2 :	understand response analysis			1	80	85															
CLO-3 :	understand the basic tools of analysis and stability			1	80	85															
CLO-4 :	understand the basic tools of analysis and stability			1&2	80	85															
CLO-5 :	understand basic concepts in digital controls			1&2	80	85															
CLO-6 :	Understand the systems and their model creation and utilization of various tools in analyzing the responses of various realistic systems			1&2	80	85															

		Introduction	Modeling systems	Analysis of system status - stability	Tools for Analysis of stability	Discrete Control systems
Duration (hour)		9	9	9	9	9
S-1	SLO-1	Controls – definition – need for control – examples	Principles of modeling – common aspects of all mechanical systems – components – common features	Transient analysis	Routh criteria for stability	Discrete control systems – concepts – back ground - introduction
S-2	SLO-1	necessity of controls for engineers	Development of model – Mechanical systems		Root locus – background	
S-3	SLO-1	History of control systems	Development of model – Electrical systems	Steady state analysis	Root locus – construction – simple systems	Basic components of discrete systems – quantization and errors
S-4	SLO-1	Theory, design and engineering	Development of model – Electrical systems		Root locus – complex systems	
S-5	SLO-1	Basic open loop system,	Linearization of nonlinear systems	Error identification – analysis	Bode plots – concept – simple systems	Concepts behind Z-transforms – basic functions -
S-6	SLO-1	Concept of feedback, closed loop system	State space representation – relationship to transfer function			
S-7	SLO-1	Relevance of relationship between input – output – transfer function	Use of state space representation	Position – velocity – acceleration error constants	Construction of bode plots	Impulse sampling and data hold In Discrete Control systems
S-8	SLO-1	Block diagram - drawing handling - components	Summarizing system modeling			
S-9	SLO-1	Historical examples of control systems		Routh criteria for stability	Introduction to compensation and design of control systems	

Learning Resources	1. Automatic control systems , Benjamin kuo, Wiley publication , Ninth edition ,2014 2. Modern control engineering, Ogata.K, Prentice Hall, Fifth Edition, 2010 3. Discrete time control systems, Ogata.K, Prentice Hall, 1995	4. Control Systems, Gopal, Tata McGraw-Hill 3 rd edition , 2007. 5. Modern Control Engineering, Nagrath & Gopal, New Age International, 2014 6. Control Systems, A. Ambikapathy, Khanna Publishing House, 2018. 7. V.I. Goerge, Digital Control Systems, Cengage, 2014.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.

INDUSTRIAL EXPERT	ACADEMIC EXPERT	INTERNAL EXPERT
SELVA KUMAR .S, FORD INDIA LIMITED, Chennai	Dr. BIJAY KUMAR ROUT, BITS, Pilani	VASANTH KUMAR.CH , SRMIST
Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	Dr.R.Prabhusekar, rprabhusekar@mnit.ac.in, MNNIT Allahabad	Dr. S. Prabhu, SRMIST

Course Code	18MEO109T	Course Name	NEURAL NETWORK AND FUZZY SYSTEMS	Course Category	O	Open Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 : Impart the knowledge of neural network and fuzzy systems		1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 : Understand the various neural network algorithms		Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 : Initialize fuzzy logic and neuro fuzzy logic techniques		Expected Proficiency (%)	Problem Analysis
CLR-4 : Familiarize with fuzzy algorithms		Expected Attainment (%)	Design & Development
CLR-5 : Enhance the knowledge of fuzzy & neural in various applications			Analysis, Design, Research
CLR-6 : Familiarize with genetic algorithm			Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 : Acquire basic understanding of the various algorithms involved in Neural Networks & Fuzzy Systems		1,2 90 85	H L M H M
CLO-2 : Acquire basic understanding of the various learning methods and methodologies		1,2 90 85	H L H H H
CLO-3 : Understand various fuzzy algorithms		1,2 90 85	H M H H H
CLO-4 : Analyze how to apply the concept of fuzzy & neural in mechanical applications		2,3 90 85	H H H H H M
CLO-5 : Application of neural and neuro fuzzy concepts		2 90 85	H H H M M
CLO-6 : Acquire knowledge of Genetic Algorithm		1,3 90 85	H L H H H

Duration (hour)	9	9	9	9	9
S-1 SLO-1	Introduction to Neural networks - Biological foundations	Learning Algorithms: Learning process – Supervised and unsupervised learning	Introduction to Fuzzy Logic: Fuzzy sets – Definition, Basic set – Theoretic operations for fuzzy sets	Fuzzy Logic and Control System: Fuzzy logic controller logic	Neuro-Fuzzy Logic Control –Optimization of membership function
S-2 SLO-1	ANN models, Types of activation functions	Error-correction learning	Fuzzy Relations on sets and fuzzy sets, Compositions of fuzzy relations	Fuzzification interface	Rules base of fuzzy logic controller using neural networks
S-3 SLO-1	Introduction to network architectures	Hebbian learning & Boltzmann learning	Properties of the Min-max Composition	Knowledge base and Decision making	Type A - Membership Model
S-4 SLO-1	Single layered systems	Single layer and multilayer perceptrons	Fuzzy conditional statements	Defuzzification interface	Type A - Membership Model
S-5 SLO-1	Multilayer feed forward network(MLFFN)	Least mean square algorithm	Fuzzy rules	Fuzzy controller - Types	Type B – Membership Model
S-6 SLO-1	Radial basis function network(RBFN)	Back propagation algorithm	Fuzzy analysis – Fuzzy functions on fuzzy sets	The Mamdani Controller	Type B – Membership Model
S-7 SLO-1	Recurring neural network(RNN)	Applications in forecasting	Integration of fuzzy functions	The Sugeno Controller	Adaptive fuzzy systems
S-8 SLO-1	Advanced neural network – Hopfield nets algorithm	Applications in pattern recognition	Fuzzy Graphs	Application of fuzzy logic – Crane control	Adaptive neuron-fuzzy inference system (ANFIS)
S-9 SLO-1	Bumptree network algorithm	Applications in other engineering problems	Fuzzy Differentiation	Application of fuzzy logic – Control of a Model Car	Empirical research on aggregators

Learning Resources	<ol style="list-style-type: none"> 1. Patricia Melin, "Modular Neural Networks and Type-2 Fuzzy systems for pattern recognition" Springer, 2012. 2. James M. Keller, Derong Liu, David B. Fogel, "Fundamentals of computational intelligence. Neural Networks, Fuzzy systems, and evolutionary computation" IEEE Press, John Wiley & Sons, Inc., New Jersey, 2016. 3. Cornelius T. Leondes, "Fuzzy logic and Expert systems applications" Academic Press, USA, 1998. 4. Jacek.M.Zurada, "Introduction to artificial Neural Systems" Jaico Publishing House, Mumbai, 2007. 5. Simon Haykins, "Neural Networks – A comprehensive foundation" Macmillan College, Pro.Con.Inc. New York, 2005. 	<ol style="list-style-type: none"> 6. Zimmermann.H.J. "Fuzzy set theory and its applications" Allied Publication Ltd., Chennai, 2001. 7. Tsoukalas.L.H and Robert E. Uhrig, "Fuzzy and Neural approach in Engineering" John Wiley and Sons, New York, 1997. 8. Klir.G.J and Yuan.B.B. "Fuzzy sets and fuzzy logic" Prentice Hall of India, New Delhi, 1997. 9. Driankov.D, Hellendron.H and Reinfrank.M, "An introduction to fuzzy control" Narosa Publishing House, New Delhi, 1996.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. R. Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in, rkpearls@yahoo.com	1. Dr. P. Hariharan, Anna University, hari@annauniv.edu, hariharan2311@gmail.com	1. Dr. M. R. Stalin John, SRMIST
2. Dr. A. Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	2. Dr. N. Arunachalam, IIT Madras, chalam@iitm.ac.in	2. Mrs. I. Infanta Mary Priya, SRMIST

Course Code	18MEO110T	Course Name	ROBOTIC SENSORS	Course Category	O	Open Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand the basis of latest technology of sensors used in robots	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Be familiar with the concept Different sensing variables that are used as input to robots for sensing	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Impart the knowledge on various vision sensors applied in robots , vision systems and their overview																		
CLR-4 :	Various methods used in robot programming																		
CLR-5 :	Different types of grippers and gripping methods																		
CLR-6 :	Understand various sensors used in robots and various programming methods in robotics, application of various grippers and their design concepts																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Understand the application of sensors in robotics	1& 2	80	70	H	M	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-2 :	Recognize the application of various inertial sensors, displacement measurement sensors, force and touch sensors in robotic applications	1	80	70	H	L	M	-	-	-	-	-	-	-	-	-	-	-	-
CLO-3 :	Understand various miscellaneous sensors and recognize the importance of telepresence and related technologies	1	80	70	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-4 :	Understand the controlling methodologies for a robot using vision sensor modules, and be able to understand robot vision locating position. Application of End effector camera sensor in robotics.	1&2	80	70	H	M	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-5 :	Recognize the various Control Computer configurations, Vision Sensor modules, Software Structure, Vision Sensor software structures and integration of all together for specific applications	1&2	80	70	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-6 :	Various sensors and their working principles in various robotic application, especially inertial sensors, force and other touch related sensors, miscellaneous sensors, vision sensors, telepresence and related technologies	1&2	80	70	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-

Duration (hour)	10	10	10	10	10	
S-1	SLO-1	An Introduction to sensors and Transducers, History and definitions	Position sensors – Optical, non-Optical	Different sensing variables	Introduction to vision sensor, working and principles of vision sensing	Control Computer for robot, Speciation's, Hardware requirements
S-2	SLO-1	Smart Sensing, working of a smart sensor, networking of smart sensors	Contact, non-contact type sensors position sensing	Smell and smart e-nose sensors	classification of vision sensors	Vision Sensor modules
S-3	SLO-1	AI sensing, Need of sensors in Robotics	Range Sensing, types and classification based on the Distance measurement technique	Heat or Temperature Humidity classification of RTD and Thermocouples Non-contact-based temperature measurement Pyrometry and Active, passive type of IR devices	Considerations for camera , and camera specifications	Software Structure,
S-4	SLO-1	Case study on AI	Touch and Slip sensors application in grippers as a feedback device	Light sensors and application of light sensors in robotic interlocks eg (as an interlock switch during power failure)	Integration of vision sensors to robot controller	Vision Sensor software,
S-5	SLO-1	Classification of various sensors	Sensors types of touch and slip sensors , tactile sensors	Speech or Voice recognition Systems,	End effector camera Sensor.	Robot programming,
S-6	SLO-1	Based on operation principle	Force sensors and their application in fixed robots	Speaker dependent voice recognition systems Speaker independent voice recognition system	Calibration of vision sensors	Handling, Gripper, classification of grippers based on operation
S-7	SLO-1	Based on application	Torque Sensors and associated circuitry used for torque sensors	Discrete speech recognition, Continuous speech recognition, Natural language processing system	Robot Control through Vision sensors	Gripping methods, accuracy

S-8	SLO-1	Sensors in mobile and fixed robot configurations	Velocity sensors	Case study on voice recognition system (eg. siri, Google talk)	Robot vision locating position,	A Case study-01
S-9	SLO-1	Application of sensors in various robots	Accelerometers	Need for telepresence	Robot guidance with vision system	A Case study-02
S-10	SLO-1	Case study on fixed robot configurations and mobile robot configurations	Proximity Sensors	Telepresence and related technologies.	End effector camera Sensor	A Case study-03

Learning Resources	<ol style="list-style-type: none"> 1. Richard D. Klaffer, Thomas .A, Chri Elewski, Michael Negin, <i>Robotics Engineering an Integrated Approach</i>, Phi Learning., 2009. 2. John Iovice, "Robots, Androids and Animatrons", Mc Graw Hill, 2003. 3. K.S. Fu, R.C. Gonzalez, C.S.G. Lee, "Robotics – Control Sensing, Vision and Intelligence", Tata McGraw-Hill Education, 2008. 4. Mikell P Groover & Nicholas G Odrey, Mitchel Weiss, Roger N Nagel, Ashish Dutta, <i>Industrial Robotics, Technology programming and Applications</i>, Tata McGraw-Hill Education, 2012. 5. Sabrie Soloman, <i>Sensors and Control Systems in Manufacturing</i>, McGraw-Hill Professional Publishing, 2nd Edition, 2009. 6. 7. Julian W Gardner, <i>Micro Sensor MEMS and Smart Devices</i>, John Wiley & Sons, 2001. 7. John Iovice, "Robots, Androids and Animatrons", Mc Graw Hill, 2003.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
SELVA KUMAR .S	Dr. BIJAY KUMAR ROUT	VASANTHKUMAR.CH
SENIOR ANALYST, FORD INDIA LIMITED CHENNAI.	Birla Institute of Technology and Science (BITS), Pilani, Rajasthan, Professor in the Department of Mechanical Engineering	Assistant Professor, Mechanical Engineering Department, SRMIST, KTR Campus.

Course Code	18MEO111T	Course Name	INDUSTRIAL ENGINEERING	Course Category	O	Open Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Be familiar with the techniques and procedures of work study				Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Know about various plant layout and material handling systems																							
CLR-3 :	Understand the ergonomics, production and productivity measurement																							
CLR-4 :	Impart the concept of production planning and control																							
CLR-5 :	Be familiar with methods of wage payment																							
CLR-6 :	Improve the efficiency, productivity and quality of products manufactured.																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1 :	Acquire knowledge on different techniques and procedures of work study					1	90	85	H	M	-	-	-	-	-	-	-	-	-	-	-	M	-	-
CLO-2 :	Recognize the various plant layouts, need for site selection and about material handling					1&2	90	85	H	-	-	-	H	-	-	-	-	-	-	-	-	M	-	-
CLO-3 :	Acquire knowledge on ergonomics of work design, types and function of production and productivity measurement					1&2	90	85	H	M	H	-	-	-	-	-	-	-	-	-	-	H	M	-
CLO-4 :	Understand inventory management and resource utilization.					1&2	90	85	H	H	-	-	-	-	-	-	-	-	-	-	-	M	-	-
CLO-5 :	Acquire knowledge on job evaluation, incentive schemes and method of wage payment					1	90	85	H	M	-	-	-	-	-	L	-	-	-	-	-	-	-	M
CLO-6 :	Analysis and improve the efficiency and productivity in the industries					1&2	90	85	H	M	-	-	-	-	-	-	-	-	-	-	-	M	M	-

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction to Work measurement and its Techniques	Plant location and site selection.	Introduction to work design, Work design for increased productivity	Objectives and Functions of PPC	Types of Wages and salary administration
S-2	SLO-1	Production study and Time study.	Types, need, factors influencing the plant layout.	The work system, design Introduction to job design.	Aspects of product development and design	Meaning principles in wage fixation, Techniques used of wage fixation
S-3	SLO-1	Standard time, Rating factors and Work sampling.	Tools and techniques for developing layout, process chart, flow diagram, string diagram, Template and Scale models.	Environmental factors and organizational factors	Introduction to Process Planning and types, Principles of Standardization	Method of Job evaluation
S-4	SLO-1	Techniques of Work study	Layout Planning and procedure involved in creating layout	Behavioral factors influencing effective job design.	Break even analysis	Steps involved in merit rating of employee
S-5	SLO-1	Human factors of Work study	Construction and Improvement algorithms-Automated Layout Design Program (ALDEP)	Ergonomics, Objectives system approach of ergonomic model	Introduction to Group Technology. and various types	Various Methods of wage payment
S-6	SLO-1	Method study, Techniques and procedures of improving Productivity.	Construction and Improvement algorithms-Computerized Relative Allocation of Facilities Techniques(CRAFT)	Man machine system, Production and Productivity	Method of finding optimum Batch size. Equipment.	Types, Advantages and disadvantages of Incentive scheme
S-7	SLO-1	Motion economy principles.	Introduction and procedure on Assembly and line balancing	Definition of production and function	ABC analysis.	Productivity base incentives
S-8	SLO-1	Charging Techniques	Material Handling, scope and importance. Types of material handling systems.	Type of production systems	Introduction to Value Engineering and its importance, Case studies	Case Example of Evaluation of incentive scheme
S-9	SLO-1	SIMO chart, Ergonomics and Industrial design.	Methods of material handling	Definition of productivity and productivity measurement.	Types of cost-Cost of production and Labour cost-Simple problems	Importance of Environmental pollution and control

Learning Resources	1. SC Sharma, TR Banga "Industrial Engineering and Management", Khanna Publications Pvt, 2017 2. Khanna.O.P, "Industrial Engineering and Management", Dhanpat Rai Publications Pvt Ltd, 2014 3. Buffa E.S, "Modern Production / Operational Management", John Wiley & Sons, 2013 4. Samuel Eilon, "Elements of Production Planning and Control", McMillan and Co., Digitized, 2012	5. Kumar.B, "Industrial Engineering and Management", 9th edition, Khanna Publishers, New Delhi, 2009 6. James M. Apple, "Principles of Layout and Material Handling", Ronald press, 2012 7. Maynard.H, "Industrial Engineering Hand Book", McGraw Hill Book Co. New York, 2010
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. R. Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in, rkpearls@yahoo.com	Dr. Deepak mathivathanan, Institute of Technology and Innovation, University of Southern Denmark, dem@iti.sdu.dk.	1. Muralidharan. S, SRMIST
2. Dr. A. Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	Dr. Vimal KEK, National Institute of Technology, Patna, vimalkek@nitp.ac.in	2. Thirugnanam. A, SRMIST

Course Code	18MEO112T	Course Name	PRODUCTION MANAGEMENT	Course Category	O	Open Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards			Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand the principles of Production Management				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Acquire knowledge on Inventory Management and Work study				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Be familiar with the Job evaluation and Scheduling																					
CLR-4 :	Be familiar with the Plan and execute of the Project																					
CLR-5 :	Attain the knowledge about Implementation and Quality Assurance in Management																					
CLR-6 :	Be familiar with the basic aspects of Production Management like Inventory Management, Work study, Job evaluation, Scheduling, project management, MRP and TQM.																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	Understand the production management and to recognize the relationship with other functional areas and acquire the knowledge about capacity, location and layout planning.				1 & 2	90	85	H	M	-	-	-	-	-	-	M	-	-	-	-	-	M
CLO-2 :	Acquire knowledge on Inventory management and Work study				1	90	85	H	M	-	-	-	-	-	-	-	-	-	-	-	-	M
CLO-3 :	Appreciate the Job evaluation and understand the need of scheduling				1	90	85	H	-	-	-	-	-	-	-	M	-	-	-	-	-	M
CLO-4 :	Understand the theory behind the Project management and acquire the knowledge about MRP, ERP and Supply chain management.				1 & 2	90	85	H	M	-	-	-	-	-	-	-	-	-	-	-	-	M
CLO-5 :	Obtain the knowledge about Total Quality Management				1 & 2	90	85	H	-	-	-	-	-	-	-	M	-	-	-	-	-	M
CLO-6 :	Recognize the use of production management, acquire knowledge on the inventory management and work study, job evaluation and scheduling, study the total quality management on production process.				1	90	85	H	M	-	-	-	-	-	-	M	-	-	-	-	-	M

		Introduction to Production Management	Inventory Management and Work Study	Job Evaluation and Scheduling	Project Management and MRP	Total Quality Management
Duration (hour)		9	9	9	9	9
S-1	SLO-1	History and development of production management	Inventory Control and cost, procurement and purchasing methods	Job evaluation: objectives, methods and factors affecting wage structure.	Project Management Phases and Project Appraisal	Quality management systems and Factors controlling quality
S-2	SLO-1	Functions and scope of different types of production processes	Warehousing Procedure and records in stock control, stores management	Types of wages, methods of wage system and characteristics	PERT and CPM	Impact of poor quality, challenges and Quality cost
S-3	SLO-1	Relationship of production management with other functional areas	Method Study and Means of increasing productivity	Value analysis and value engineering	Material requirement Planning (MRP)	Quality Assurance and Quality Circle
S-4	SLO-1	Capacity planning and its types	Charts and diagrams used in method study	Aggregate planning and strategies	Manufacturing resources Planning (MRP II)	Statistical Process Control and Control Charts with examples
S-5	SLO-1	Capacity decisions and their importance, Capacity planning strategies: types	Role of work study and human factors in work study	Forecasting and its methods	Enterprise Resource Planning (ERP)	Total Quality Management
S-6	SLO-1	Rooting, Techniques of rooting	Objectives and basic procedure for work study	MPS and Scheduling, Related Problems	Logistics: types and strategies	Just in Time with Case Study
S-7	SLO-1	Location planning: factors, types of planning, location models	Factors affecting work study	Scheduling principles, inputs, strategies, sequence and Assumptions, Case study	Supply chain Management	Six Sigma
S-8	SLO-1	Layout planning: factors and types	work measurement, objectives and techniques of work measurement	Gantt chart and Johnson's algorithm	Objectives and Decision Phases of Supply chain Management	Maintenance management and its types
S-9	SLO-1	Productivity management: definition, productivity index	Problems in Inventory control & work study	Problems in Gantt chart and Johnson's algorithms	Roles and Development in Supply chain Management	Effects of maintenance, Reliability and Replacement Techniques

Learning Resources	1. S.K. HajraChoudhury et al, "Production Management", MP publishers, New Delhi, 1990. 2. Heizer., "Operations Management", Pearson, New Delhi, 2016. 3. Ahuja, K.K., "Production Management", CBS Publishers, New Delhi, 2013. 4. Agarwal and Jain, "Production Management", Khanna publishers, New Delhi, 1998	5. S.N.Chary, "Production and operation management", Tata Mcgraw Hill publications, New Delhi, 2009 6. Goel, B.S., "Production Management", Pragathi&prakasan publishers, Mererut, 1984. 7. S.Anil and N.Suresh, "Production and operation Management", New Age International publishers, New Delhi, 2008
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. S.Bhargav, GM,Rane Brake, Trichy	1. Dr. V.Srinivasan, Annamalai University, srinivaghavan@yahoo.com	1. Mr.T.Geethapriyan, SRMIST
2. Dr. Muthumanikkam, Jt. Director, CVRDE, DRDO,Avadi,Chennai.	2.Dr.Assaitambi, Govt. Col. of. Engg, sengipatti,Thanjavur, basaitambi@gcetj.edu.in	2. Dr.A.Arul Jeya Kumar, SRMIST

Course Code	18ME0113T	Course Name	DESIGN OF EXPERIMENTS	Course Category	O	Open Elective	L 3	T 0	P 0	C 3
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Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	Statistical data books		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Be familiar with necessity, fundamentals and potential practical problems in design of experiments	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Be familiar with methodology used for design of experiments	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Be familiar with robust design concepts with case studies	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Be familiar with the concept of response surface design	Expected Attainment (%)	Design & Development
CLR-5 :	Be familiar with the concepts of confounding and analysis of variance (ANOVA)		Analysis, Design, Research
CLR-6 :	Be familiar with how the analysis of the data from the experiment should be carried out.		Modern Tool Usage
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		Society & Culture
CLO-1 :	Understand the basics and potential practical problems in design of experiments	1, 2	Environment & Sustainability
CLO-2 :	Understand and apply various methodology for design of experiment to evaluate case studies	1, 2 & 3	Ethics
CLO-3 :	Apply the concept of robust design to evaluate case studies	1, 2 & 3	Individual & Team Work
CLO-4 :	Expose the concepts of response surface design to evaluate experimental problems	1, 2 & 3	Communication
CLO-5 :	Apply the concept of confounding and ANOVA to evaluate case studies	1, 2 & 3	Project Mgt. & Finance
CLO-6 :	Construct optimal or good designs for a range of practical experiments and describe how the analysis of the data from the experiment should be carried out	1, 2 & 3	Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Introduction in Design of experiments (DOE)	Need for DOE methodology	Introduction to Robust design, Loss functions	Background of response surface design
S-2	SLO-1	The fundamental and potential practical problems in experimentation	Barriers in the successful application of DOE	Eight steps in Taguchi methodology	Multiple Responses and Contour profile of response surface plot
S-3	SLO-1	Statistical thinking and its role within DOE	Practical methodology of DOE and Analytical tools for DOE	Orthogonal array, Selecting the interaction, Linear graphs	Creation of response surface designs
S-4	SLO-1	Basic principles of DOE and Degrees of freedom	The confidence interval for the mean response	S/N ratio: Larger-the-better, Smaller-the-better, Nominal-the-best	Central composite designs (Rotatable central composite design)
S-5	SLO-1	Selection of quality characteristics for experiments	Introduction to Screening design	Analyze the data, factor effect diagram	Central composite designs (Rotatable central composite design)
S-6	SLO-1	Understanding key interaction in processes	Geometric and non-geometric P-B design	Levels of parameters	Box-Behnken design with case studies
S-7	SLO-1	An alternative method for calculating two-order interaction effect	Introduction of full factorial design, Basic concepts of 2 ² , 2 ³ and 2 ^k designs	Confirmation test	Random factor models and its industrial application, Random Effects Models
S-8	SLO-1	Synergistic interaction, Antagonistic interaction	Solving Case studies on Full factorial design with statistics software	Augmented design with simple case studies	Two Factor Factorial with Random Factors
S-9	SLO-1	Synergistic interaction versus Antagonistic interaction	Solving Case studies on Full factorial design with statistics software	Solving case studies on robust design with statistics software	Two Factor Mixed Models with random factors

Learning Resources	1. Douglas C Montgomery, "Design and Analysis of Experiments", Eighth Edition, John Wiley & Sons Ltd., 2012	5. Russell R. Barton, "Graphical Methods for the Design of Experiments", Springer, 2012.
	2. Box, G.E.P. and Draper N.R, "Empirical Model-Building and Response Surfaces", John Wiley & sons 2007.	6. Larry B. Barrentine, "An introduction to Design of Experiments A simplified approach", New Age International Publishers, 2014.
	3. JijuanTony, "Design of Experiments for Engineers and Scientists", Second Edition, Elsevier, 2014.	7. William G. Cochran, Gertrude M. Cox, "Experimental Design", John Wiley and sons, Inc, 2003.
	4. M N Das, N C Giri, "Design and Analysis of Experiments", New Age International (P) Limited, Publishers, 2003.	8. Myres R.H, Montgomery D. C, Anderson-Cook C. M "Response Surface Methodology", Wiley, 2016.
		9. Cox D.R, Reid N, "The theory of Design of Experiments", Chapman and Hall, CRC Press, 2000.
		10. John, P.W.M, "Statistical Design and Analysis of Experiments", Society for Industrial and Applied Mathematics, 1998.

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	25%	-	20 %	-	20 %	-	20%	-	20 %	-
	Understand										
Level 2	Apply	50 %	-	60 %	-	50 %	-	50%	-	60 %	-
	Analyze										
Level 3	Evaluate	25 %		20 %		30 %	-	30%	-	20 %	-
	Create										
Total		100%		100%		100%		100%		100%	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Dr.R.Kalimuthu, ISRO, Mahendragiri	Dr. P. Hariharan, Anna University, hari@annauniv.edu, hariharan2311@gmail.com	Dr. S. Murali, SRMIST
Dr.A.Velayutham, DRDO, Avadi	Dr.N.Arunachalam, IIT Madras, chalam@iitm.ac.in	Dr. S. Prabhu, SRMIST

Course Code	18ME0114T	Course Name	MODERN CONTROL THEORY	Course Category	O	Open Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards		Statistical data books	

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand and remember the fundamentals of modern control theory including basic controller actions	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Create mathematical models for dynamic systems and Apply transfer function and state space models	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Upon learning the students shall Analyze the transient and steady state system response of control systems				H	H													
CLR-4 :	Upon learning the students shall Analyze the stability of control system by different methods				H	H	H												
CLR-5 :	Upon learning the students shall Analyze multiple input multiple output systems using state space approach				H	H	H												
					H	H		H								H			
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	understand basic terminologies, concepts of feedback, dynamic system modeling using linear differential equations, apply transfer functions for control system	1,2	90	85															
CLO-2 :	Understand modeling in state space, apply state space model and evaluate different mechanical systems	1,2	85	80															
CLO-3 :	understand standard test signals, apply and evaluate system response for first and second order systems	1,2,3	85	80															
CLO-4 :	understand, apply, and create optimal control systems based on stability analysis by different approaches	1,2,3	85	80															
CLO-5 :	Analyze the multiple input multiple output dynamic systems based on state space approach, apply Kalman and Gilbert test	1,2,3	90	85															

Duration (hour)		Introduction to control systems	System Modeling	System response	Stability Analysis	State space analysis of MIMO systems
		9	9	9	9	9
S-1	SLO-1	Brief Review, Basic terminologies and examples, Classical-Modern-Robust-Automatic control systems, Concepts of Feedback: Closed-loop and open-loop control systems, Design and compensation of control systems (Design procedure)	Modeling in state space: State, State variables, State vector, State space, State equations for a MIMO system	Transient and steady state response, Standard test signals- Mathematical expressions- type and order of a system	Complex s-plane, Routh's stability criterion	MIMO System analysis: state-space approach
S-2	SLO-1	Brief Review, Basic terminologies and examples, Classical-Modern-Robust-Automatic control systems, Concepts of Feedback: Closed-loop and open-loop control systems, Design and compensation of control systems (Design procedure)	Modeling in state space: State, State variables, State vector, State space, State equations for a MIMO system	First order Systems: Unit step response and Unit ramp response, Concepts of time constant and its importance in speed of response	Complex s-plane, Routh's stability criterion	MIMO System analysis: state-space approach
S-3	SLO-1	Modeling of control systems using linear differential equations, Transfer function expressions (with note on convolution integral), Block diagrams	State space representation of dynamic systems – nth order systems of linear differential equations, State space models for mechanical systems: Examples from mechanical, electrical, liquid-level, thermal systems	First order Systems: Unit step response and Unit ramp response, Concepts of time constant and its importance in speed of response	Analysis of control systems by Root-Locus method: concepts and procedure, Design of Lead-Lag compensation based on Root-Locus approach	State space representation in controllable, observable, diagonal and jordan canonical forms, order reduction and solution of state equations
S-4	SLO-1	Modeling of control systems using linear differential equations, Transfer function expressions (with note on convolution integral), Block diagrams	State space representation of dynamic systems – nth order systems of linear differential equations, State space models for mechanical systems: Examples from mechanical, electrical, liquid-level, thermal systems	Second order systems: Servo system and Servo system with velocity feedback	Analysis of control systems by Root-Locus method: concepts and procedure, Design of Lead-Lag compensation based on Root-Locus approach	State space representation in controllable, observable, diagonal and jordan canonical forms, order reduction and solution of state equations

S-5	SLO-1	Basic Control action: Types of controllers, Principles of pneumatic, hydraulic and electronic controllers	State space representation of dynamic systems – nth order systems of linear differential equations, State space models for mechanical systems: Examples from mechanical, electrical, liquid-level, thermal systems	Second order systems: Servo system and Servo system with velocity feedback	Analysis of control systems by Root-Locus method: concepts and procedure, Design of Lead-Lag compensation based on Root-Locus approach	Controllability and observability, Kalman and Gilbert test
S-6	SLO-1	Basic Control action: Types of controllers, Principles of pneumatic, hydraulic and electronic controllers	State space representation of dynamic systems – nth order systems of linear differential equations, State space models for mechanical systems: Examples from mechanical, electrical, liquid-level, thermal systems	Second order systems: Servo system and Servo system with velocity feedback	Stability: Polar, Bode and Nyquist plots	Controllability and observability, Kalman and Gilbert test
S-7	SLO-1	Basic Control action: Types of controllers, Principles of pneumatic, hydraulic and electronic controllers	State space representation of transfer function systems	Controller errors, Higher order systems, Effects of proportional-integral-derivative control actions on the system response	Stability: Polar, Bode and Nyquist plots	Pole placement approach to the design of control systems, State observers, Design of servo systems
S-8	SLO-1	Tuning of PID controller: Ziegler-Nichols rules	State space representation of transfer function systems	Controller errors, Higher order systems, Effects of proportional-integral-derivative control actions on the system response	Lead-Lag compensation based on frequency response approach	Pole placement approach to the design of control systems, State observers, Design of servo systems
S-9	SLO-1	Tuning of PID controller: Ziegler-Nichols rules	Linearisation of a non-linear system	Controller errors, Higher order systems, Effects of proportional-integral-derivative control actions on the system response	Lead-Lag compensation based on frequency response approach	Pole placement approach to the design of control systems, State observers, Design of servo systems

Learning Resources	<ol style="list-style-type: none"> 1. K. Ogata - 'Modern Control Engineering - Prentice Hall (India) - Pearson Education - 2009 - 5th Edition 2. Francis. H. Raven - 'Automatic Control Systems' – McGraw Hill - 1995 - 5th Edition 	<ol style="list-style-type: none"> 1. B. C. Kuo - 'Automatic Control Systems' - Wiley - 2009 - 9th Edition 2. Schaum's Series - 'Feedback and Control Systems' – McGraw Hill Education - 2013 - 2nd Edition 3. I. J. Nagarith & M. Gopal - 'Control Systems' - New age International Publishers. 4. Norman Nise- 'Control Systems Engineering' - Wiley and Sons - 2015 - 7th Edition 5. Rihard C. Drof and Robert. H. Bishop Addison - 'Modern Control Systems' – Wesley – 2010 - 12th Edition
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Learning Assessment						
	Level of Thinking	Continuous Learning Assessment (50%)				Final Examination (50%)
		CLA – 1 (10%)	CLA – 2 (15%)	CLA – 3 (15%)	CLA – 4 (10%) #	
Level 1	Remember	40 %	30 %	30 %	30 %	30 %
	Understand					
Level 2	Apply	40 %	40 %	40 %	40 %	40 %
	Analyze					
Level 3	Evaluate	20 %	30 %	30 %	30 %	30 %
	Create					
	Total	100%	100%	100%	100%	100%

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	1. Dr. BIJAY KUMAR ROUT, BITS, Pilani	Dr C. Shrivankumar, SRMIST
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cwrde.drdo.in	2. Dr.R.Prabhusekar, rprabhusekar@mnnit.ac.in, MNNIT Allahabad	Dr. P. Nandakumar, SRMIST

Course Code	18ME0115T	Course Name	FACILITIES PLANNING	Course Category	O	Open Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 : Understand the purpose of facilities planning process		1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 : Acquire knowledge on requirements and relationships of facilities planning		Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 : Be familiar with the facility design		Expected Proficiency (%)	Problem Analysis
CLR-4 : Acquire knowledge on strategies adopted for designing a facility		Expected Attainment (%)	Design & Development
CLR-5 : Attain the knowledge about material handling and facility layout design			Analysis, Design, Research
CLR-6 : Be familiar with the basic aspects of evaluating, selecting maintaining in facilities planning and Industrial Acts and safety			Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 : Understand the basic concepts in facilities planning process		1&2	90	85	H					M						L			
CLO-2 : Acquire knowledge on requirements and relationships of facilities planning		1	90	85	M														
CLO-3 : Understand facility design for various functions and acquire knowledge about strategies adopted for designing a facility		1	90	85	H		H	M										L	
CLO-4 : Acquire knowledge on material handling and facility layout design		1&2	90	85	H		H	M		M						L		L	
CLO-5 : Recognize the basic aspects of evaluating, selecting and maintaining in facilities planning		1&2	90	85	M			M		M									
CLO-6 : Evaluate the existing facility, modify to meet the requirements and understand Industrial Acts and safety.		1	90	85	M					M						M			

Duration (hour)	9	9	9	9	9
S-1 SLO-1	Definition, Significance and objectives of facilities planning	Department planning	Material Handling, Principles and classification	Facility design for various functions	Introduction to Facilities plan Evaluating. Facilities plan evaluation procedure, Factors to evaluate facility planning
S-2 SLO-1	Facilities planning process	Activity relationship	Designing material handling systems, Estimating material handling costs, Safety consideration	Warehouse operation and location problems	Qualitative Evaluation Techniques
S-3 SLO-1	Strategic Facilities Planning	Flow patterns	Layout Planning Models and Basic layout types	Nature of Location Decision, Need for facility location planning	Efficiency indices, Cost of Evaluation of Layout
S-4 SLO-1	Developing facilities planning strategies	Planning and measuring	Layout procedures, Algorithmic approaches and Pair-wise exchange method	General procedures and actors influencing location decisions, Facility Location Models	Facilities plan selection, Steps and involved in Facilities plan selection
S-5 SLO-1	Nature of Location Decision, Need for facility location planning	Space requirements	graph based approaches blocplan, logic, multiple approach	Economics and cost analysis, Rural and urban location pattern	Facility plan preparing, Importance of facility preparing
S-6 SLO-1	General procedures and Factors influencing location decisions, Facility Location Models	Personnel requirements	Multi floor facility layout, Developing layout alternatives	Manufacturing systems and Services	Facilities plan implementing and facility plan maintaining
S-7 SLO-1	Influence of product	Employee, facility interface, Multi-facility location problem, Euclidean-distance location problem, Minimax location problem.	Computer assisted layout planning	Fixed automation system and Flexible manufacturing system	Necessity of Industrial acts, The Indian Factories Act 1948, The industrial Dispute act1947, The minimum Wage Act 1948.
S-8 SLO-1	Process and schedule design	Restrooms, food services, health services	ALDEP, CORE LAP, CRAFT , PLANET , MAT	Reduction in work in process, Just-in-time manufacturing	Introduction to Industrial safety, Investigation and analysis of accidents, Safety devices Causes and sources of accidents.

S-9	SLO-1	Facilities design and procedure	Office facility planning	Commercial facility layout packages	Facilities planning trends	Safety devices, Causes and sources of accidents.
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Learning Resources	1. Tompkins.J.A, White.J.A, Bozer.Y.A, and Tan Choco.J.M.A, "Facilities Planning", 4th Edition, John Wiley & sons, India, 2010. 2. James M. Apple, "Principles of layout and material handling", Ronald press, 1977. 3. Francis.R.L, McGinnis.L.F, and White J.A, "Facility Layout and Location: An analytical approach", Prentice Hall, New Jersey, 1992.	4. Gupta and Patel, "Work study", Khanna Publishers, New Delhi. 5. Kanna.O.P, "Industrial Engineering and management", Khanna Publishers, New Delhi, 2018 6. Sharma SC & Banga TR, "Industrial Engineering & Management", Khanna Publishers, 2017
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.L.Srinivasan , Scientist , ISRO lakhsmanansrinivasan@rocketmail.com	Dr. Sonu Kumar, Assistant Professor, Birla Institute of Technology. sonu.production@gmail.com	Mr. R. Manoj Samson
2. Mr. S.Arun kumar, Executive Engineer, ONGC borntough18@gmail.com	Dr. K.E.K Vimal , Assistant Professor, NIT, Patna	Dr. S.Murali

Course Code	18ME0116T	Course Name	INDUSTRIAL SAFETY AND ENVIRONMENT	Course Category	O	Open Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Be familiar with the safety issues in design, handling and industrial environment	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Be familiar with the accident prevention and motivating factors of safety suggestion schemes	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Know the various safety measures followed in material handling system																		
CLR-4 :	Be familiar with the safety measures followed in chemical industries and chemical laboratories																		
CLR-5 :	Be familiar with the environmental impact Assessment																		
CLR-6 :	Be familiar with the regulations for health, safety and environment																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Conduct basic safety inspections using strategies that they have developed	1&2	90	85	L		H		H	M	H	L	H	M	L	H			
CLO-2 :	Understand the motivating factors of safety suggestion schemes, thereby preventing accidents	1	90	85	H	M	H		H	M	H	L	H	H	M	H			
CLO-3 :	Understand the various safety measures to be followed in material handling system	1&2	90	85	H	L	H		H	L	H	L	M	H		H			
CLO-4 :	Understand the various safety measures followed in chemical industries and chemical laboratories	1&2	90	85	H	L	H		H	L	H	L	M	H		H			
CLO-5 :	Gain knowledge in basic environmental impact Assessment	1&2	90	85	L		H		M		H		M			H			
CLO-6 :	Create a document addressing the principles for developing and implementing a successful occupational health and safety program and evaluation of a work site	1&2	90	85	H	M	H		H	M	H	L	H	H	M	H			

		Accident Prevention	Safety in Material Handling	Safety in Chemical Industries	Environmental Impact Assessment	Regulations for Health, Safety and Environment
Duration (hour)		9	9	9	9	9
S-1	SLO-1	Definitions and theories of accident, reportable and non-reportable accidents, unsafe act, unsafe condition and dangerous occurrence	General safety consideration in material handling	Safety in the design process of chemical plants	Evolution, Concepts, Methodologies, Screening, Scoping and Checklist of EIA	Factories act and rules, Workmen compensation act
S-2	SLO-1	Theories and principles of accident causation	Ropes, Chains, Sling, Hoops, Clamps	Safety in operational and maintenance of chemical plants	Rapid and Comprehensive EIA	Indian explosive act
S-3	SLO-1	Cost of accidents, Accident reporting and investigations, accident reports- Class exercise with case study.	Arresting gears and Prime movers	Exposure of personnel	Legislative and environmental clearance procedure in India	Gas cylinder rules
S-4	SLO-1	Safety committees and their need, types and advantages	Ergonomic consideration in material handling	Operational activities and hazards	Prediction tools for EIA	Environmental pollution act
S-5	SLO-1	Safety education and training and their importance	Design, installation, operation and maintenance of Conveying equipment.	Safety in storage and handling of chemicals and gases	Assessment of Impact of air, water and soil	Indian petroleum act and rules
S-6	SLO-1	Various training methods	Hoisting, traveling and slewing mechanisms	Hazards during transportation and Pipeline transport	Assessment of Impact of noise, biological and Socio cultural environment	Oil industry safety directorate (OISD)
S-7	SLO-1	Accident prevention and Motivating factors of safety suggestion schemes	Selection, operation and maintenance of industrial trucks	Safety in chemical laboratories	Public participation	Indian Electricity act and rules
S-8	SLO-1	Safety performance	Selection, operation and maintenance of Mobile cranes and Tower crane	Specific safety consideration for cement, paper and pharmaceutical	Resettlement and Rehabilitation	Mines act and rules, Manufacture, Storage and Import of Hazardous Chemical rules 1989
S-9	SLO-1	Definitions connected with measuring safety performance as per Indian and International standards	Storage and Retrieval of common goods of various shapes and sizes in a general store of a big industry.	Specific safety consideration for petroleum, petro -chemical, rubber, fertilizer and distilleries	Documentation of EIA	Indian motor vehicles act and rules

Learning Resources	1. Thomas J.Anton, "Occupational safety and health management", (2nd Edition). New York, McGraw Hill 1989. 2. Rieske, David W., Asfahl and C. Ray, "Industrial Safety and Health Management", 6th Edition, Prentice Hall Professional Technical Ref. 2009. 3. Heinrich.H.W, "Industrial Accident Prevention", McGraw-Hill, 1980. 4. Alexandrov.M.P, "Material Handling Equipment", Mir Publishers, Moscow, 1981. 5. Lees.F.P, Loss "Prevention in Process Industries", Butterworths, NewDelhi, 1986.	6. Handlin.W, "Industrial Hand Book", McGraw-Hill, 2000. 7. Canter.R.L, "Environmental Impact Assessment", (2nd Edition), McGraw Hill, 1996. 8. IS CODES: IS 5903, IS 807, IS 2760, IS 14469, IS 13367-1, IS 5324, IS 7167, IS 7155, IS 1800.1, IS 3521 of Oil Industry Safety Directorate, Govt. of India. 9. The manufacture, storage and import of hazardous chemical rules 1989, Madras BookAgency, Chennai.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.

Course Designers		
Experts from Industry		Experts from Higher Technical Institutions
1. Mr. S.Bhargav, GM,Rane Brake, Trichy		1. Dr. R. Raju, Anna university, Chennai.
2. Dr. Muthumanikkam, Jt. Director, CVRDE, DRDO,Avadi,Chennai.		2. Dr. T. Paul Robert, Anna university, Chennai.
		Internal Experts
		1. Mr. A. C. Arun Raj, SRMIST
		2. Mr. A. Thirugnanam, SRMIST

Course Code	18ME0117T	Course Name	ARTIFICIAL INTELLIGENCE AND EXPERT SYSTEMS	Course Category	O	Open elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Department of Mechanical Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Program Learning Outcomes (PLO)														
CLR-1 :	Be familiar with the basic concepts of artificial intelligence	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Be familiar with various search techniques used in artificial intelligence																		
CLR-3 :	Be familiar with various Matching techniques used in artificial intelligence																		
CLR-4 :	Be familiar with the concept of knowledge management																		
CLR-5 :	Be familiar with the programming language																		
CLR-6 :	Be familiar with basic concepts of expert system																		
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																	
CLO-1 :	Understand the basic concepts of artificial intelligence	1&2	90	85	H	L	H	H	H	-	-	-	-	-	-	H	-	-	-
CLO-2 :	Identify and use various search techniques	1&2	90	85	H	H	H	H	H	-	-	-	-	-	-	M	-	-	-
CLO-3 :	Understand the concept of matching techniques	1&2	90	85	H	L	M	M	H	-	-	-	-	-	-	M	-	-	-
CLO-4 :	Gain knowledge on the concept of knowledge management	1&2	90	85	H	L	M	M	H	-	-	-	-	-	-	M	-	-	-
CLO-5 :	Do coding in python language	1	90	85	L	H	H	M	H	-	-	-	-	-	-	M	-	-	-
CLO-6 :	Understand basic concepts of expert system	1&2	90	85	H	H	M	H	H	-	-	-	-	-	-	M	-	-	-

Duration (hour)		Introduction To Ai	Problem Solving Agents	Knowledge Organisation, Communication	Programming Language	Expert Systems
		9	9	9	9	9
S-1	SLO-1	History, Definition of AI	Problem Definition, formulating problems and Searching for solutions	Knowledge organization, manipulation and knowledge acquisition	Introduction to python its syntax	Introduction to Expert Systems
S-2	SLO-1	Emulation of human cognitive process	Measuring problem, solving performance with examples	Indexing and Retrieval techniques	Input, output statements	Basic Activities of an expert system
S-3	SLO-1	Semantic nets	Search /Strategies: Uninformed or Blinded search Breadth first search.	Integration of knowledge in memory organization systems	Numeric functions	Interpretation, Prediction and Diagnosis
S-4	SLO-1	An abstract view of modeling	Uniform cost search: Depth first search, Depth limited search	Matching Techniques: Need for matching and Matching problem	Input statements for declaration of variables, Output statements for declaration of variables	Design, Planning and Monitoring
S-5	SLO-1	Elementary knowledge	Iterative deepening, Depth first search and Bi-directional search	Partial matching, Fuzzy matching and RETE matching algorithm		Debugging, Repair, Instruction and Control
S-6	SLO-1	Computational logic	Comparing uninformed search strategies and Informed search strategies	Natural language processing: Overview of linguistics	Interaction functions	Basic aspect of expert system
S-7	SLO-1	Analysis of compound statements using simple logic connectives	Heuristic information and Hill climbing methods	Basic semantic analysis and Representation structures	recursion functions	Acquisition module frames of expert systems, Knowledge base
S-8	SLO-1	Predicate logic	Best First Search; Greedy Best First Search, Branch-and- Bound Search	Natural language generation.	Property list and arrays	Production rules , Semantic net and Inference engine
S-9	SLO-1	Simple exercises	Optimal search and A* algorithm and iterative deepening A*	Bayesian Networks and Bayesian Inference		Backward chaining and forward chaining

Learning Resources	1.Schalkoff, R.J., "Artificial Intelligence: An Engineering Approach", McGraw-Hill, 1990 2. Elaine Rich and Kelvin Knight, "Artificial Intelligence", Tata McGraw Hill, New Delhi, 2009 3. Russell , " Artificial intelligence :A modern Approach , Pearson Education ,3rd edition,2013 4. Donald A. Waterman, "A Guide to Expert Systems", Addison-Wesley Longman Publishing Co., Inc. Boston, MA, USA ©1985 ISBN:0-201-08313-2	5. Nils J. Nilsson, "Principles of Artificial Intelligence", Narosa Publishing House, 2000. 6. Eugene Charniak and Drew McDermot, "Introduction to Artificial Intelligence", Addison Wesley Longman Inc., 1998 7. Patterson, "Introduction to Artificial Intelligence and Expert systems", Prentice Hall of India, New Delhi, 1990
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. R. Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in, rkpearls@yahoo.com	1. Dr. P. Hariharan, Anna University, hari@annauniv.edu, hariharan2311@gmail.com	1. Mr Gujjari Bala Siva Krishna
2. Dr. A. Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	2. Dr.N.Arunachalam, IIT Madras, chalam@iitm.ac.in	2. Mrs Deborah Stephan

Course Code	18MEO118T	Course Name	MICROCONTROLLER AND ITS APPLICATIONS IN ROBOTICS	Course Category	O	Open Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Acquire the fundamental concepts of microcontroller.				Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Learn to program the microcontroller using assembly language.																							
CLR-3 :	To expose interfacing of microcontroller with the external world using a high level language.																							
CLR-4 :	To introduce students to an open source microcontroller and its programming.																							
CLR-5 :	To enable students with the Design of Microcontroller based circuits based on applications on robotics.																							
CLR-6 :	Impart the Knowledge about the concepts and selection of microcontroller to its application.																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1 :	Understand the fundamental concepts of microcontroller.					1	90	85	M	-	M	-	-	-	-	-	-	-	-	-	-	L	L	L
CLO-2 :	Program the microcontroller using assembly language.					1	90	85	H	M	M	L	L	-	-	-	-	-	-	-	-	H	H	L
CLO-3 :	Interface I/O modules with microcontroller from external world.					1	90	85	H	M	M	M	M	-	-	-	-	-	-	-	-	H	M	L
CLO-4 :	Demonstrate a fundamental knowledge of open source microcontroller and learnt to program it.					2	90	85	H	H	M	M	H	-	-	-	M	-	-	-	H	H	L	
CLO-5 :	Demonstrate microcontroller based circuit for engineering applications.					3	90	85	H	M	H	H	H	-	-	-	H	-	-	-	H	M	L	
CLO-6 :	Select suitable microcontroller to meet specific requirements.					3	90	85	H	M	H	M	L	-	-	-	L	-	-	-	H	M	L	

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Data representation and Numbering system and its types are binary, decimal, hexadecimal systems	Introduction to Assembly language	Introduction to External world interfacing with microcontroller, Analog signals and Digital signals	Introduction to open source microcontroller	Application of Microcontroller in various fields
S-2	SLO-1 Data conversion from hexadecimal to decimal and decimal to binary, binary addition and subtraction	Instruction sets with syntax and examples.	Analog to digital conversion and its types	Open Hardware platform basic knowledge of its hardware and its software environments	Advancement in Microcontroller
S-3	SLO-1 Introduction and history description about microcontrollers	Timers and its types	Digital to Analog conversion and its types	Variables ,Digital inputs with programs	Study and Design a Home security system using microcontroller
S-4	SLO-1 Specification and Internal architecture of 8051	TCON,TMOD	Analog inputs are mechanical switches ,relays	Digital Outputs with programs	Study and Design a Elevator system
S-5	SLO-1 Pin description of 8051	Delay program with and without timer	Digital outputs are LED,7 segment display and LCD interfacing	Reading analog signals and PWM signal generation with programs	Study and Design a Sensor guided mobile robot using ultrasonic sensor
S-6	SLO-1 Various Addressing modes of 8051 are immediate, register, direct	Interrupts and its Types	DC Motor Interfacing	Conditional statements are if ,else and nested if with programs	Study and Design a Tic Tac Toe playing robot
S-7	SLO-1 Indirect, Relative, Indexed and Absolute addressing modes	Programming using Interrupts	Stepper Motor Interfacing	Looping statements are for ,while and Do while with programs	Study and Design a Line following robot as a maze solver using microcontroller
S-8	SLO-1 Difference between microcontroller with microprocessor	I/O Ports and its 3 modes of operation	Servo Motor Interfacing	Functions and recursive function with programs	Study and Design a Unmanned Aerial Vehicle using microcontroller
S-9	SLO-1 Selection criterion for choosing microcontroller	Serial communication and its modes, SCON	Digital inputs -Keypad and its interfacing	Continuous Serial monitoring and hardware interrupt with programs	Study and Design a Soccer playing robot using microcontroller

Learning Resources	1. Muhammad Ali Mazidi, "8051 Microcontroller and Embedded Systems", Pearson New International Edition, 2014. 2. Simon Monk, "Programming Arduino Next Steps: Going Further with Sketches", Second Edition, McGraw Hill Professional, 2018. 3. MacKenzie I. Scott, "The 8051 Microcontroller", Pearson Education India, 2011.	1. Donald Norris, "Python for Microcontrollers: Getting Started with MicroPython", McGraw Hill Professional, 2016. 2. Jeff Cicolani, "Beginning Robotics with Raspberry Pi and Arduino: Using Python and OpenCV, Apress, 2017
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

SLO – Session Learning Outcome

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Sreejith Balachandran, Senior Engineer, COMAU ROBOTICS	Husheini Rasheeth, Vel Tech - Technical University	1. Mr.V.Manojkumar, SRMIST
Dr. R. Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in, rkpearls@yahoo.com	Dr. P. Hariharan, Anna University, hari@annauniv.edu, hariharan2311@gmail.com	2. Mr.N. Karthikeyan, SRMIST
Dr. A. Velayutham, DRDO, Avadi, velayudham.a@cwrde.drdo.in	Dr.N.Arunachalam, IIT Madras, chalam@iitm.ac.in	

Course Code	18MEO119T	Course Name	MACHINERY FAULT DIAGNOSTICS AND SIGNAL PROCESSING	Course Category	0	Open Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Be familiar with the working of a machinery and need for machine maintenance	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Be familiar with the reason for Failure and capable of doing failure analysis		
CLR-3 :	Be familiar with the basics of Signal analysis and Machinery condition monitoring		
CLR-4 :	Be familiar with Instrumentation systems		
CLR-5 :	Be capable of Machine Testing and Analysis		
CLR-6 :	Be familiar of industrial practices in machine troubleshooting		

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Acquire knowledge on basic components and working of a machine	1& 2	90	85	H	-	-	-	-	-	-	-	-	-	-	H	M	-	-
CLO-2 :	Appreciate the process of monitoring the conditions of a machine	1	90	85	H	-	H	-	H	-	-	-	M	-	-	-	-	H	H
CLO-3 :	Understand the techniques in wear and debris analysis, vibration analysis and signal analysis	1	90	85	H	M	H	H	M	-	-	-	-	-	-	-	-	H	H
CLO-4 :	Understand the various tools used for monitoring the condition of machine	1&2	90	85	H	-	H	-	H	-	-	-	-	-	-	-	-	H	-
CLO-5 :	Understand the process of thermography and non- destructive techniques	1&2	90	85	H	-	-	-	M	-	-	-	-	-	-	-	H	-	H
CLO-6 :	Acquire skills in fault finding and diagnosis	1&2	90	85	H	M	-	M	-	-	-	-	H	-	-	H	H	H	-

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Failures and failure analysis	Principles of Maintenance	Time Domain Signal Analysis	Data Recording and Transmission
S-2	SLO-1	Failure concepts and characteristics	Failure Modes Effects	Frequency Domain Signal Analysis	Vibration Transducers, Vibration Monitoring
S-3	SLO-2	Fault detection sensors	Criticality Analysis	Computer Aided Data Acquisition - Basics	Basics of Noise and Noise Monitoring
S-4	SLO-1	Data processing	Fault Diagnostics	FFT Analysis	Numerical problems in Noise Vibration
S-5	SLO-1	signal analysis	Fault Prognostics	Modulation and Sidebands	Numerical problems in Data Acquisition
S-6	SLO-1	Condition based maintenance principles	Basics of Machinery Vibration	Envelope Analysis	Unbalance Detection, Field Balancing
S-7	SLO-2	Fault analysis planning and system availability	Engineering Applications of Vibration	Cepstrum Analysis	Misalignment Detection, Cracked Shaft Detection
S-8	SLO-2	Reliability/failure concepts	Rotor dynamics	Order Analysis	Looseness and Rub Detection, Ball and Journal Bearings
S-9	SLO-1	Application of diagnostic maintenance to specific industrial machinery and plants	Fault findings in rotor machines	Examples on signal processing in MATLAB	Gear Fault Detection

Learning Resources	1. A. R. Mohanty , "Machinery Condition Monitoring: Principles and Practices" , CRC Press, 2014. 2. William T. Thomson, Chandramouli Padmnabhan," Theory of Vibration with Applications", Pearson, V edition, 2008. 3. PareshGirdhar, Cornelius Scheffer, "Practical machinery vibration analysis and predictive maintenance", Elsevier, 2004.	4. J Prasad, C G K Nair, "Non-Destructive Testing and Evaluation of Materials", Tata McGraw Hill, Education Private Limited, 2011 5. S.S. Rao, "Vibration of Continuous systems", Wiley, 2006
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

SLO – Session Learning Outcome

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Senthil Kumar. K, Divisional Manager, Global Bus – Operations, Ashok Leyland Ltd senthilkumar.k3@ashokleyland.com	1. Dr.A.R. Mohanty, Professor, IIT Kharagpur amohanty@mech.iitkgp.ac.in	1. Mr.M. Dhanasekaran, SRMIST
2. Mr.Sumit Bose, Zonal Manager, Man Trucks and Buses, smtbs69@rediffmail.com	2. Prof. N. Ramesh Babu, IIT Madras, nrbabu@iitm.ac.in	2. Mr.V. Manoj Kumar, SRMIST

Course Code	18MEO120T	Course Name	DIGITAL IMAGE PROCESSING AND MACHINE VISION	Course Category	O	Open Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 : Be familiar with the sensors and Image acquisition system		1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 : Be familiar with the basics of image processing in Frequency domain			
CLR-3 : Be familiar with the image enhancement and compression			
CLR-4 : Know the existing vision systems			
CLR-5 : Practice the tasks in any one of image processing software like MATLAB or OpenCV			
CLR-6 : Be Familiar with components of machine vision, image processing and its applications in industries			
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Engineering Knowledge
CLO-1 : Understand the basic concepts of digital image processing.		1&2 90 85	H L M M H L - - L M - - H H M
CLO-2 : Learn the image fundamentals and mathematical transforms necessary for image processing		1&2 90 85	H H M M H - - - M - - H H M
CLO-3 : Study the various image enhancement and compression techniques		1 90 85	H L L M H - - - M - - H H M
CLO-4 : Understand the existing machine vision systems and technique for template matching and feature extraction		1&2 90 85	H L L M H - - - - - M H H M
CLO-5 : Application of Machine Vision in experimental mechanics and basics of 3D Vision		1&2 90 85	H L M M H M M - - - M H H M
CLO-6 : Learn machine vision components and basics of Image Processing		1&2 90 85	H L M M H M - - - M - - H H M

		IMAGE ACQUISITION AND FUNDAMENTALS OF IMAGE PROCESSING	IMAGE TRANSFORMS AND EDGE DETECTION	IMAGE ENHANCEMENT AND COMPRESSION	MACHINE VISION AND 3D VISION	MACHINE VISION APPLICATIONS
Duration (hour)		9	9	9	9	9
S-1	SLO-1	Elements of visual perception, structure of eye	The Basics of Intensity Transformations and Spatial Filtering	Histogram modification and specification techniques	Review of existing vision systems	Digital Image Correlation DIC
S-2	SLO-1	Introduction to image processing, classification of image,	One-dimensional discrete fourier transform (DFT)	Image smoothing, Low pass filtering, Ideal low pass filter,	Binary and Gray vision system Vision system	DIC in sheet metal forming, experimental mechanics
S-3	SLO-1	Fundamental steps involved in image processing, source of image	Two-dimensional discrete fourier transform (DFT)	Butterworth low pass filter	Image Analysis methods, Feature extraction	Stereo vision in experimental mechanics
S-4	SLO-1	Image acquisition and digitization, sensing	Cosine and Sine transform and their properties	Image sharpening, Butterworth filters	Image interpretation Segmentation	Electronic and automotive Industrial Applications
S-5	SLO-1	Illumination and its types	Hadamard and Haar transform and their properties	Generation of spatial masks from frequency domain specification,	Template Matching	Camera Calibration
S-6	SLO-1	CCD and CMOS Cameras	Slant, KL, SVD transforms and their properties	Basic steps in frequency domain filtering	Classification of 3-D Vision Techniques	Dimensional measurements in machine vision
S-7	SLO-1	Representing Digital Images, Spatial and Intensity Resolution, Image Interpolation	Edge detection and their techniques, Roberts operator,	Nonlinear filters, function, Max filter, Min filter	Photometric stereo	Assembly Inspection
S-8	SLO-1	Problems on quantization and sampling	Problems based on FFT, DFT	Run length coding	Structured Light Reconstruction	Food processing Industrial applications
S-9	SLO-1	Practice on reading image and exercise on spatial resolution and sampling in MATLAB or Open CV	Practice on image transformation in MATLAB or Open CV	Practice on image filtering in MATLAB or Open CV	Assignments on feature extraction in MATLAB/Open CV	Practice on photometric stereo MATLAB Or Open CV

Learning Resources	<ol style="list-style-type: none"> 1. Anil K. Jain, "Fundamentals of Digital Image Processing", Prentice Hall of India, New Delhi, 2007. 2. Rafael C. Gonzalez and Richard E. Woods, "Digital Image Processing", Addison Wesley, New York, 2009. 3. Vernon, D., "Machine Vision - Automated Visual Inspection and Robot Vision", Prentice Hall International Ltd., New York, 1991. 4. William K. Pratt, "Digital Image Processing", John Wiley, New York, 2007. 	<ol style="list-style-type: none"> 5. Sid Ahmed M. A., "Image Processing Theory, Algorithms and Architectures", McGraw-Hill, New York, 1995. 6. Umbaugh, S.E., "Computer Vision and image processing - Practical approach using CVIP tools, Prentice Hall of India, New Delhi, 1998. 7. Ramesh Jain, Rangachar Kasturi and Brain G. Schunk, "Machine Vision", McGraw Hill International Editions, Computer Science Series, Singapore, 1995. 8. Emanuele Trucco, Alessandro Verri, "Introductory Techniques For 3D Computer Vision", 1998 Edition, Prentice Hall
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

SLO – Session Learning Outcome

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr.S.A.Krishnan, IGCAR,kalpakkam	Dr.N.Arunachallam, IITM	Dr. A. Vijaya, SRMIST
Mr. Narasimhan Sridhar, TESA Engg, Chennai	Dr.A.Jothilingam, Visiting Faculty, MIT, Anna University	Dr. R. Senthilnathan , SRMIST

Course Code	18MEO121T	Course Name	MULTIDISCIPLINARY DESIGN	Course Category	O	Open Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Department of Mechanical Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																		
CLR-1 :	develop appropriate skills on systemic thinking on how to identify and formulate a problem, evaluate the conceptual design by using scientific, engineering and managerial tools, and to understand the current trend for the problem.			Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2 :	rationalize the product design problem by selecting appropriate design variables, parameters and constraints from the published article																									
CLR-3 :	subdivide a complex system into smaller disciplinary models, analyze the output and reintegrate them into an overall system model and optimize the output																									
CLR-4 :	apply Multi objective optimization for the output to reintegrate them into an overall efficient system model																									
CLR-5 :	take on the challenges of team work, prepare a presentation in a professional manner.																									
CLR-6 :	understand how the various multi-disciplinary fields interact and integrate in real life situations. Develop appropriate skills on systemic thinking , evaluate the conceptual design by using scientific, engineering and managerial tools, analyze and interpret the data, considering safety, socio-politico-cultural, risks and hazards, disposal, regional and national laws, costing and financial model and undertake documentation with a presentation.																									
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																								
CLO-1 :	develop appropriate skills on systemic thinking on how to identify and formulate a problem, evaluate the conceptual design by using scientific, engineering and managerial tools, and to understand the current trend for the problem.			2	80	70																				
CLO-2 :	rationalize the product design problem by selecting appropriate design variables, parameters and constraints from the published article			2	85	75																				
CLO-3 :	subdivide a complex system into smaller disciplinary models, manage the output and reintegrate them into an overall system model and optimize the output			2	75	70																				
CLO-4 :	apply Multi objective optimization for the output to reintegrate them into an overall efficient system model			2	85	80																				
CLO-5 :	take on the challenges of teamwork, prepare a presentation in a professional manner			2	85	75																				
CLO-6 :	develop appropriate skills on systemic thinking on how to identify and formulate a problem, decompose the problem into smaller elements, conceptualize the design, evaluate the conceptual design by using scientific, engineering and managerial tools, select, analyze and interpret the data, consideration of safety, socio-politico-cultural, risks and hazards, disposal, regional and national laws, costing and financial model and undertake documentation and finally with a presentation.			2	80	70																				

Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
H	H	M	M	M	-	-	-	-	-	-	-	H	H	H
H	H	M	M	M	-	-	-	-	-	-	-	H	H	H
H	H	M	H	M	-	-	-	-	-	-	-	H	H	H
H	H	M	M	M	-	-	-	-	-	-	-	H	H	H
H	H	H	H	H	-	-	-	H	-	-	-	H	H	H
H	H	H	H	H	H	H	H	H	H	H	-	H	H	H

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Identifying and Formulating research problem	Student presentation on literature review	Design of experiments -Optimization of variables to get optimized output	Multi objective Optimization to get optimized output and Grey relational analysis	Student presentation on Entropy Method
S-2	SLO-1	Research Process, Research Types, Research and Scientific Method	Student presentation on literature review	Response surface methodology	Student presentation on Grey relational analysis	Student presentation on Entropy Method
S-3	SLO-1	Problem Solving in Engineering	Student presentation on literature review	Analysis of variance (ANOVA)	Student presentation on Grey relational analysis	Student presentation on Entropy Method
S-4	SLO-1	Identification of Research Topic	Report preparation about Literature survey	Students presentation on Response surface methodology and Analysis of variance (ANOVA)	Student presentation on Grey relational analysis	Introduction to TOPSIS Method
S-5	SLO-1	Problem Definition	Student presentation on literature survey	Students presentation on Response surface methodology and Analysis of variance (ANOVA)	Student presentation on Grey relational analysis	Student presentation on TOPSIS Method

S-6	SLO-1	Problem Solving in Engineering	Student presentation on literature survey	Students presentation on Response surface methodology and Analysis of variance (ANOVA)	Student presentation on Grey relational analysis	Student presentation on TOPSIS Method
S-7	SLO-1	Collect primary data and secondary data	Student presentation on literature survey	Students presentation on Response surface methodology and Analysis of variance (ANOVA)	Introduction to Entropy Method to calculate weights of the TOPSIS Method	Student presentation on TOPSIS Method
S-8	SLO-1	Student presentation on literature review	Student presentation on literature survey	Students presentation on Response surface methodology and Analysis of variance (ANOVA)	Student presentation on Entropy Method	Student presentation on TOPSIS Method
S-9	SLO-1	Student presentation on literature review	Student presentation on literature survey	Students presentation on Response surface methodology and Analysis of variance (ANOVA)	Student presentation on Entropy Method	Student presentation on TOPSIS Method

Learning Resources	<ol style="list-style-type: none"> 1. Douglas C Montgomery, "Design and Analysis of Experiments", John Wiley & Sons Ltd., 2005 2. Ganesan R, "Research Methodology for Engineers", MJP Publishers., 2011 3. Rao Singaresu.S, "Engineering Optimization – Theory & Practice", New Age International (P) Limited, New Delhi, 2009. 4. P.C.Tewaria, Ujjwal Prakash, Dinesh Khanduja, Sandeep, "Ranking of Sintered Material for High Loaded Automobile Application using Entropy-Topsis method", Materials Today: Proceedings, 2015, Pp.2375 – 2379 5. Suneesh. E, Multi-response optimisation of micro-milling parameters through GRA, TOPSIS and Taguchi techniques to increase production rate while reducing energy consumption, Measurement, https://doi.org/10.1016/j.measurement.2019.04.090. 6. Rom Kim, "A study on competitiveness analysis of ports in Korea and China by Entropy weight TOPSIS", The Asian Journal of Shipping and Logistics, 2016, 32(4), Pp.187-194. 7. Statistical software-Minitab
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (15%)		CLA – 2 (15%)		CLA – 3 (20%)		CLA – 4 (50%)#			
		Theory	Practice/ Presentation	Theory	Practice/ Presentation	Theory	Practice/ Presentation	Theory	Practice/ Presentation	Theory	Practice/ Presentation
Level 1	Remember	-	20%	-	15%	-	15%	-	15%	-	30%
	Understand										
Level 2	Apply	-	20%	-	20%	-	20%	-	20%	-	40%
	Analyze										
Level 3	Evaluate	-	10%	-	15%	-	15%	-	15%	-	30%
	Create										
	Total	100 %		100 %		100 %		100 %		-	

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. R. Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in , rkpearls@yahoo.com	Dr.P.Sathiya, Professor, NIT, Trichy. psathiya@nitt.edu	Mrs. R.Ambigai, SRMIST
2. Dr. A. Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in		Dr. M. R..Stalin John, SRMIST

Course Code	18MHO101T	Course Name	Mechatronics	Course Category	0	Open Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechatronics Engineering	Data Book / Codes/Standards			Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:		Learning			Program Learning Outcomes (PLO)																
CLR-1 :	To get an overview of Mechatronics as a design philosophy			Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2 :	To get an insight into multi-disciplinary systems																						
CLR-3 :	Familiarize the mechanical engineering aspects of mechatronics systems																						
CLR-4 :	Understand the concepts related to data acquisition and control																						
CLR-5 :	Understand the importance of modeling and model based design																						
CLR-6 :	To have a detailed idea of applying mechatronics design concepts in real world systems																						
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																					
CLO-1 :	Conversant in mechatronics design philosophy			3	80	75	H	H	M	L	L	-	-	-	L	L	-	L	H	M	-		
CLO-2 :	Ability to resolve the sub-systems and challenges involved in a larger mechatroncis system			3	85	80	H	H	M	M	L	-	-	-	M	L	-	L	H	M	-		
CLO-3 :	Understand the concepts related to data acquisition and control			2	75	70	H	M	L	M	L	-	-	-	M	L	-	L	H	M	-		
CLO-4 :	Ability to model and simulate physics based mechatronics systems			2	75	70	H	M	M	M	M	-	-	-	M	L	-	L	H	M	-		
CLO-5 :	Ability to understand the challenges in integration of a multi-disciplinary system			2	85	80	H	M	M	M	M	-	-	-	M	L	-	L	H	M	-		
CLO-6 :	Analyze the functionality of a multi-disciplinary system from the perspective of integration			2	80	75	H	M	M	M	M	-	-	-	L	L	-	L	H	M	-		

		Introduction to Mechatronics	Mechanical and Actuation Systems	Data Acquisition and Control	Modelling and Simulation	Case Studies
Duration (hour)		7	10	10	8	10
S-1	SLO-1	Definition of mechatronics	Fundamental laws governing mechanical systems	Sensors in mechatronics systems	Significance of modeling	Modelling of a serial robot manipulator
	SLO-2	Evolution of mechatronics systems	Actuation subsystem in Mechatronics systems	Sensor characteristics	Example	Need of model based design for the system under consideration
S-2	SLO-1	Multidisciplinary nature of modern machines and their design challenges	Kinematic chains, transmission elements	Sensor signal types	Model-In-Loop(MIL) simulation	Benefits of model based design
	SLO-2	Example	Types, purpose and examples	Analog and digital signals	Example	Understanding the system under consideration
S-3	SLO-1	Traditional vs mechatronics approaches	Gears	Motion encoder, types	Software-In-Loop(SIL) simulations	Mechanical and electronics description
	SLO-2	Example	Types, selection criteria, nomenclature	Specifications and selection criteria	Example	Mathematical description of the model
S-4	SLO-1	Mechatronics design process	Lead screws and belt drives	Incremental optical encoder	Virtual Prototyping- a critical aspect of mechatronics approach	Mathematical modeling- derivation
	SLO-2	Need for design tools integration	Types, selection criteria, nomenclature	Quadrature decoding - Hardware method	Example	Control strategy
S-5	SLO-1	Review of key elements of mechatronics systems	Mechanical aspects of actuator selection	Quadrature decoding - Software method	Real-time (RT) simulations	Analysis of performance
	SLO-2	Example	Types of actuators	Absolute encoder decoding	Example	Analysis of performance
S-6	SLO-1	Role of mechatronics engineer.	Comparison of electrical, pneumatic and hydraulic actuators	Elements of a data acquisition system	concurrent development of subsystems	Modelling of a active suspension
	SLO-2	Various steps for design	Special purpose actuators	Signal conditioning systems	Example	Need of model based design for the system under consideration
S-7	SLO-1	Various Mechatronics systems	Example circuit design of a servo pneumatic actuation system	Analog to digital conversion	Real-time Hardware-In-Loop simulation (HIL)	Benefits of model based design

	SLO-2	Various Mechatronics systems	Case study	Computer hardware aspects of data acquisition	Example	Understanding the system under consideration
S-8	SLO-1		Step motors, types	Introduction to state space modelling	Running the controller model and plant model on real-time target	Mechanical and electronics description
	SLO-2		Construction and selection criteria	Modelling of a DC motor	V&V using HIL RT model.	Mathematical description of the model
S-9	SLO-1		Electronic drives for electrical actuators	Introduction to PID Control		Mathematical modeling- derivation
	SLO-2		Types, pupose and selection criteria	Derivation		Control strategy
S-10	SLO-1		DC motor drives - any one type	State space model of a speed control of a DC motor		Analysis of performance
	SLO-2		AC motor drives - any one type	Derivation		Analysis of performance

Learning Resources	1. Devdasshetty, Richard A.Kolk "Mechatronics Systems Design", 2 nd Edition, Cengage Learning, 2011. 2. W. Bolton, "Mechatronics", 5 th Edition, Pearson Education, 2011.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	20 %	-	40%	-
Level 2	Understand	40 %	-	40 %	-	40 %	-	40 %	-	30%	-
	Apply										
Level 3	Analyze	40 %	-	40 %	-	40 %	-	40 %	-	30%	-
	Evaluate	30 %	-	30 %	-	30 %	-	40 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. N. Ganesh Ram, Intel Labs, ganeshram.nandakumar@intel.com	1. Dr. R. Thiyagarajan, IIT Madras, thiyaguitm@gmail.com	1. Dr. R. Senthilnathan, SRMIST
2. Mr. Mohammed Sagheer , Wabco Technology Center, mohammedsagheer.musthafa@wabco-auto.com	2. Dr. P. Karthikeyan, MIT Campus, Anna University, pkarthikeyan@annauniv.edu	2. Mr. K. Sivanathan, SRMIST

Course Code	18MHO102T	Course Name	Model Based System Design	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechatronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Understand the processes, methods, and practices of model-based systems engineering(MSBE)				Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Comprehend the conflicting requirements of complex engineering systems and their life cycle stages through some relevant case studies and relate the need for model based system engineering																							
CLR-3 :	Define and develop requirements, architectures, behavior, specifications, verifications, and tests that represent engineering systems using model-based systems engineering.																							
CLR-4 :	Analyze systems using model-based systems engineering approaches that lead to better and increased design metrics of systems																							
CLR-5 :	Apply the knowledge of model based system engineering for creating models using SysML diagrams that accurately represent views of engineering systems and analyze the same for improving the performance.																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			2	75	70	Expected Proficiency (%)	Expected Attainment (%)	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3	
CLO-1 :	Ability to describe the processes, methods, and practices of model-based systems engineering																							
CLO-2 :	Recognize the conflicting requirements of complex engineering systems and their life cycle stages through some relevant case studies and relate the need for model based system engineering																							
CLO-3 :	Develop and relate requirements, architectures, behavior, specifications, verifications, and tests that represent cyber-physical systems using model-based systems engineering methods.																							
CLO-4 :	Demonstrate analysis of systems using model-based systems engineering approaches that lead to better and increased design metrics of systems																							
CLO-5 :	Apply the knowledge of model based system engineering to create effective models using SysML diagrams that accurately represent views of engineering systems and analyze the same for improving the performance.				3	75	70	H	H	M	H	M	-	M	M	-	-	M	H	M	M	M	M	

		Foundations to Model Based System Engineering(MSBE)	Modeling, Analysis and Management of System Requirements	Modeling and Simulation of Structures and Behaviors of Systems	Definition of Cyber Physical Systems and Components	Verification and Validation
Duration (hour)		9	9	9	9	9
S-1	SLO-1	Overview of complex engineering systems	Requirement of engineering artifact modeling	Multidisciplinary design modeling requirements	Definition of components and systems	V&V techniques overview
	SLO-2	Motivation for system engineering/ model based system engineering (MBSE)	Requirement of engineering artifact modeling	Multidisciplinary design modeling requirements	Definition of components and systems	V&V techniques overview
S-2	SLO-1	The system engineering process	Eliciting Requirements	Structural modeling	Assigning behaviors to components	Verification techniques: software engineering techniques
	SLO-2	Typical application of system engineering process	Eliciting Requirements	Structural modeling	Assigning behaviors to components	Formal verification technique
S-3	SLO-1	Multidisciplinary systems engineering team	Requirement modeling	Structural modeling using SysML	Incorporating images in to the model	Program analysis technique
	SLO-2	System engineering practice through standards	Requirement modeling	Structural modeling using SysML	Incorporating images in to the model	V&V of engineering design models
S-4	SLO-1	Contrasting document based approach and model based approach	Requirements management	Behavioral model using states and transitions	Allocation	V&V of engineering design models- Tool support
	SLO-2	Contrasting document based approach and model based approach- introduce SysML diagrams and MSBE tool	Requirements management	Behavioral model using states and transitions	Allocate activity partition	Automatic approach for synergistic verification and validation
S-5	SLO-1	Modeling principles- Model and MSBE method definition	Requirements Diagram, Traceability Hierarchy Diagram	Behavioral model in SysML	Unit, dimension and data types	Synergistic verification and validation methodology

	SLO-2	The purpose for modeling a system	Requirements Diagram, Traceability Hierarchy Diagram	Behavioral model in SysML	Adding constraints	Dedicated V&V approach for system engineering
S-6	SLO-1	Model validation	Hazard analysis and threat modeling	Ensuring consistency	Activity diagrams	Verification and validation of behavioral diagrams
	SLO-2	Model metrics	Hazard analysis and threat modeling	Solving inconsistency	Interaction diagrams	Verification and validation of behavioral diagrams
S-7	SLO-1	Introducing the concept of architectures	Creating requirements models of systems using SysML in different contexts and views	The relationship between behavioral diagrams and structure level	Case study: MBSE approach for Elevator	Probability model checking of SysML activity diagrams
	SLO-2	Requirements	Creating requirements models of systems using SysML	The relationship between behavioral diagrams and structure level	Case study: MBSE approach for Elevator	Probability model checking of SysML activity diagrams
S-8	SLO-1	System's life cycle	Creating requirements models of systems using SysML in different contexts and views	Identifying complexity through different levels of abstraction and refinement	Case study: MBSE approach for ATM	Performance analysis of time-constrained activity diagrams
	SLO-2	System's life cycle	Creating requirements models of systems using SysML in different contexts and views	Identifying complexity through different levels of abstraction and refinement	Case study: MBSE approach for ATM	Performance analysis of time-constrained activity diagrams
S-9	SLO-1	Design and integration process	The SysML Use Case Diagram	Independent views of the same system	Case study: MBSE approach for automobile	Case study – Demonstration of V&V
	SLO-2	Types of systems	SysML Blocks and Block definition diagram	Concluding remarks	Case study: MBSE approach for automobile	Case study – Demonstration of V&V

Learning Resources	<ol style="list-style-type: none"> 1. Dennis M. Buede & William D. Miller., "The Engineering Design of Systems Models and Methods" 3rd Edition, Wiley, 2016 2. Jon Hold and Simon Perry., "SysML for System Engineering", The Institution of Engineering and Technology, 2nd Edition, Wiley, 2013 3. Kossiakoff, A. Sweet, Seymour, S., W.N., Biemer, S.M., "Systems Engineering Principles and Practice", John Wiley & Sons, 2nd Edition, 2011. 4. Mourad Debbabi, Fawzy Hassaine., "Verification and validation in Systems Engineering", 1st Edition, Springer, 2010. 	<ol style="list-style-type: none"> 5. Brian Berenbach & Daniel Paulish., "Software and Systems Requirements Engineering in Practice", 1st edition McGraw Hill, 2009 6. David D. Walden, Garry J. Roelder, Kevin J. Forsberg, R. Douglas Hamelin, Thomas M. Shortell., "INCOSE Systems Engineering Handbook- A Guide for System Life Cycle Processes and Activities" Wiley, 4th Edition, 2015 7. Sanford Friedenthal, Alan Moore, Rick Steiner., "A Practical Guide to SysML The Systems Modeling Language", 3rd Edition, Elsevier, 2015
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Elayara Sivaraji, Tesla, California, elayaraj@hotmail.com	1. Dr. Manivannan P V, Indian Institute of Technology, Chennai, pvm@iitm.ac.in	1. Mr. K.Sivanathan, SRMIST
2. Dr. Guna Surendra, Gossamsetti, Hitachi, Japan. surendra.gossamsetti.bu@hitachi.com	2. Dr. D. Sathia Narayanan, National Institute of Ocean Technology, Chennai, sathianarayanan@niot.res.in.	2. Dr.R.Senthilnathan, SRMIST

Course Code	18MHO103T	Course Name	INTRODUCTION TO ROBOTICS	Course Category	O	Open Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechatronics Engineering	Data Book / Codes/Standards			Nil

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 : <i>Introduce the various architectures of industrial robot</i>		1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 : <i>Introduce the vector transformation applied to robotics</i>		Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 : <i>Introduce the forward and inverse kinematics applied to serial manipulator robot</i>		Expected Proficiency (%)	Problem Analysis
CLR-4 : <i>Emphasize on the various actuators and transmission element used in robot.</i>		Expected Attainment (%)	Design & Development
CLR-5 : <i>Introduce the parallel configuration of robot and its kinematics computation.</i>			Analysis, Design, Research
CLR-6 : <i>To define various control strategy used in manipulator robotics</i>			Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 : <i>Understand the architecture and basic technical terms used in robotics</i>		2 80 70	H M M H M - - - - - H H - -
CLO-2 : <i>Apply vector transformation in robotics</i>		2 80 70	H H M H M - - - - - H H - -
CLO-3 : <i>Ability to compute the forward and inverse kinematics of serial manipulator</i>		2 80 70	H H M H M - - - - - H H - -
CLO-4 : <i>Understand the various actuators and transmission elements used in robot.</i>		2 80 70	H H H H M - - - - - H H - -
CLO-5 : <i>Understand the parallel configuration of robot, their kinematics computation.</i>		2 80 70	H H M H M - - - - - H H - -
CLO-6 : <i>Implement various control and trajectory planning algorithm</i>		2 80 70	H H M H M - - - - - H H - -

	Introduction to Robotics	Transformations	Kinematics	Introduction to robot sensors and control	Parallel Manipulator and industrial work cell
Duration (hour)	7	7	11	10	10
S-1	SLO-1 <i>Definition of Robot, Laws of Robotics,</i>	<i>Description of point in space</i>	<i>Introduction to manipulator kinematics</i>	<i>Basic actuators and transmission elements</i>	<i>Introduction to parallel manipulator</i>
	SLO-2 <i>Basic terminologies used in robotics</i>	<i>Description of body in space</i>	<i>Forward and inverse kinematics</i>	<i>Mathematical model of DC motor</i>	<i>Advantage of parallel manipulator over serial manipulator</i>
S-2	SLO-1 <i>Classification based on application</i>	<i>Translation and Rotation</i>	<i>Forward Kinematics of RR planar manipulator- geometric approach</i>	<i>Harmonic Drives</i>	<i>Degree of freedom of parallel manipulator using Gruebler equation</i>
	SLO-2 <i>Classification based on work volume</i>	<i>Derivation of rotation matrix to represent frame orientation in XYZ axes</i>	<i>Inverse Kinematics of RR planar manipulator- geometric approach</i>	<i>Computation of reduction ratio of harmonic drive and its advantage</i>	<i>Problem on finding degree of freedom of planar and spatial mechanism</i>
S-3	SLO-1 <i>Definition – precision, repeatability and accuracy</i>	<i>various rotation representation and their difference</i>	<i>DH formulation</i>	<i>Force sensor</i>	<i>Types of parallel manipulator</i>
	SLO-2 <i>Co-ordinate systems used in robotics, Degree of freedom with examples</i>	<i>Euler angle, fixed angle , arbitrary axis representation</i>	<i>Difference between modified and standard DH convention with example of RR planar manipulator</i>	<i>Various tactile sensors- principle and working</i>	<i>Examples</i>
S-4	SLO-1 <i>Links and various joints in robotics</i>	<i>Properties of rotation matrix</i>	<i>Forward kinematics of 3R spatial articulated arm</i>	<i>Slip sensor</i>	<i>Kinematics of parallel manipulator</i>
	SLO-2 <i>Anatomy of Robot</i>	<i>Homogeneous transformation</i>	<i>Derivation of final DH matrix for 3R spatial articulated arm</i>	<i>Slip sensor</i>	<i>Concept of inverse and forward kinematics</i>
S-5	SLO-1 <i>RPY wrist</i>	<i>Case study- problems on pure rotation (current and fixed axis)</i>	<i>Forward kinematics of 4 DOF SCARA robot</i>	<i>Vision system for robot</i>	<i>Inverse kinematics of planar parallel manipulator</i>
	SLO-2 <i>Configuration space and operational space</i>	<i>Case study –problem on rotation and translation</i>	<i>Derivation of final DH matrix for 4 DOF SCARA robot</i>	<i>Vision architecture block diagram</i>	<i>Derivation</i>
S-6	SLO-1 <i>Robot data sheet interpretation</i>	<i>Operators and mapping</i>	<i>Forward kinematics of RPY wrist</i>	<i>Introduction-trajectory planning, joint space and Cartesian space planning</i>	<i>Inverse kinematics of spatial parallel manipulator</i>

	SLO-2	Important terms and finding in datasheet of manufacturer	Case study - operators and mapping	Derivation of final DH matrix for RPY wrist	Choice of joint space and Cartesian space trajectory planning	Derivation
S-7	SLO-1	Robot End-effector	Compound transformation	Inverse Kinematics - closed loop form	Cubic polynomial trajectory planning	Robot work cell layout
	SLO-2	Types of gripper	Case Study – compound Transformation	Computation method and issues	Problem on cubic polynomial trajectory planning	Classification of robot work cell
S-8	SLO-1			Inverse kinematics of a 3 DOF spatial articulated arm	Robot position control	Multiple robot
	SLO-2			Numerical	Position control of one DOF link	Work cell control
S-9	SLO-1			Velocity kinematics introduction and Jacobian	Robot force control	Safety monitoring
	SLO-2			Understanding and deriving Jacobian matrix elements	Case study- force control (peg in a hole)	Error detection and recovery
S-10	SLO-1			Derivation of Jacobian matrix for RR planar manipulator	Hybrid force/position control	Robot Cycle time analysis
	SLO-2			Concept of singularity for manipulator	Case Study of hybrid force/position control	Criteria for selection of robot work cell
S-11	SLO-1			Computing Jacobian for RRR spatial manipulator		
	SLO-2			Computing singularity for a RRR spatial manipulator		

Learning Resources	1. Mikell P. Groover, "Industrial Robotics", McGraw Hill, 2 nd edition, 2012 2. John J. Craig, "Introduction to Robotics", 3 rd Edition, Addison Wesley, ISE 2008. 3. Deb S.R., "Robotics Technology and Flexible Automation", 2 nd edition, Tata McGraw - Hill Publishing Company Limited, 2012.	4. Arthur Critchlow, "Introduction to Robotics", 1 st edition, Macmillan, 2009. 5. Mohsen Shahinpoor, "A Robot Engineering Text Book", 1 st edition, Harper and Row, 2004 6. Sterling Kinney J, "Indeterminate Structural Analysis", 1 st edition, Narosa Publishing House, 1987.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1.Mr.Ganesh Ram, Intel Labs ,Bangalore, ganeshram.nandakumar.@intel.com	1. Dr., R. Thiyagarajan, Visiting faculty, IIT Madras, thiyaguiitm@gmail.com	1. Ranjith Pillai R, SRMIST
2. Mr. Mohammed Sagheer ,Wabco Technology Center ,India, mohammedsagheer.musthafa@wabco-auto.com	2. Dr., P Karthikeyan, MIT,Anna University, pkarthikeyan@annauniv.edu	2. Dr. R Senthilnathan, SRMIST

Course Code	18NTQ301T	Course Name	APPLICATIONS OF NANOTECHNOLOGY	Course Category	O	Open Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Nanotechnology	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Acquire knowledge on environmental applications of nanotechnology	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Understand the theory of nanotechnology in agriculture and food technology				Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3			
CLR-3 :	Familiarize electrical, electronics and energy applications of nanotechnology				H	H	H	H	H	H	H	H	H	H	M	H	H	H	H			
CLR-4 :	Know nanotechnology in textiles and cosmetics				H	M	M	H	M	H	H	H	M	H	H	M	M	M	M			
CLR-5 :	Explore the concept of biomedical applications of nanotechnology				H	M	H	H	H	H	M	H	H	H	H	H	H	H	H			
CLR-6 :	Understand the current developments and future prospects of nanotechnology				M	H	H	M	H	H	H	H	H	M	H	H	H	H	H			
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	Apply skills to identify new materials for environmental applications	2	80	75																		
CLO-2 :	Analyze the role of nanotechnology in agriculture and food technology	2	80	70																		
CLO-3 :	Discriminate electrical, electronic and energy applications of nanotechnology	2	75	70																		
CLO-4 :	Apply the techniques of nanotechnology in textile and cosmetics	2	80	75																		
CLO-5 :	Appreciate the role of nanotechnology in advancing the biomedical industry	2	80	70																		
CLO-6 :	Utilize the concept of biosensor to analyze the material nature.	2	80	75																		

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Environmental pollutants in air	Nanotechnology in Agriculture	Electronic circuit chips	Nanofibre production in Textiles	Introduction to biomedical applications
	SLO-2	Environmental pollutants in water	Precision farming	Nanosensors and actuators	Electrospinning	Bioreceptors and their properties
S-2	SLO-1	Environmental pollutants in soil	Smart delivery system	Optical switches	Controlling morphologies of nanofibers	Biochips
	SLO-2	Types of toxic and hazards wastes	Nanofertilizers and types	Diodes	Nano-fillers embedded polypropylene fibers	Integrated nanosensor
S-3	SLO-1	Application of nanotechnology - Introduction	Nanourea and mixed fertilizers	Nano-wire transistors	Bionics	DNA based biosensors
	SLO-2	Application of nanotechnology in industrial waste	Nanofertigation	Advantages of nano electrical and electronic devices	Swim-suits with shark-skin effect	Natural nanocomposite systems
S-4	SLO-1	Application of nanotechnology in waste water treatment	Nanopesticides	Memory storage	Soil repellence	Nanomaterials in bone substitutes and dentistry
	SLO-2	Drinking water purifications	Nanoseed Science	Lighting displays and filters	Lotus effect	Implants and Prosthesis
S-5	SLO-1	Air purifications	Nanotechnology in Food industry	Quantum computers	Nano finishing in textile	Tissue Engineering
	SLO-2	Gas purifications	Nanopackaging for enhanced shelf life	Medical diagnosis and conductive additives	Modern textiles Nanopolymers in medical textiles	Neuroscience
S-6	SLO-1	Nanomonitoring	Smart packaging	Lead-free solder	Introduction to cosmetics	Neuro-electronic Interfaces
	SLO-2	Nano Biosensors - Overview	Intelligent packaging	Nanocoatings and EMI shielding.	Formulation of Gels	Nanorobotics
S-7	SLO-1	Nano Biosensors for Pesticide Detection	Food processing	Energy devices	Shampoos	Photodynamic Therapy
	SLO-2	Nano Biosensors for Plant Pathogen Detection	Food safety	Fuel cells	Hair-conditioners	Protein Engineering
S-8	SLO-1	Nano Bioremediation	bio-security	role of nanomaterials in fuel cell applications	Introduction to Sun-screen dispersions	Nanosensors in Diagnosis
	SLO-2	Pesticide Degradation	Electrochemical sensors	Photovoltaic cells	Sun-screen dispersions for UV protection	Drug delivery
S-9	SLO-1	Soil Structure	sensors for food analysis	Application of nanotechnology in solar cells	Colour cosmetics	Cancer therapy
	SLO-2	Soil structure Remediation	contaminant detection	Application of power in transportation	Types of Colour cosmetics	Other therapeutic applications

Learning Resources	1. <i>Environmental Nanotechnology</i> , by M. H. Fulekar, Bhawana Pathak 2. Lynn J. Frewer, Willehm Norde, R. H. Fischer and W. H. Kampers, <i>Nanotechnology in the Agri-food sector</i> , Wiley-VCH Verlag, (2011). 3. Jennifer Kuzma and Peter VerHage, <i>Nanotechnology in agriculture and food production</i> , Woodrow Wilson International Center, (2006).	4. P. J. Brown and K. Stevens, <i>Nanofibers and Nanotechnology in Textiles</i> , Woodhead Publishing Limited, Cambridge, (2007). 5. Neelina. H, Malsch (Ed.), "Biomedical Nanotechnology", CRC Press 2005.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. N. Vijayan, CSIR-NPL, nvijayan@nplindia.org	1. Prof. S. Balakumar, University of Madras, balakumar@unom.ac.in	Dr.J.Archana, SRMIST
2. Dr. Krishna SurendraMuvvala, Saint Gobain Research India, India, Krishna.muvvala@saintgobain.com	2. Prof. V. Subramaniam, IIT Madras, vsubbu@iitm.ac.in	Dr.S.Harish, SRMIST

Course Code	18NTO302T	Course Name	SOLID STATE ELECTRONIC DEVICES	Course Category	O	Open Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Nanotechnology			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)															
CLR-1 :	Realize the basics of solid state physics with particular emphasis on semiconductors.				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLR-2 :	Provide in-depth understanding of diodes, acquire knowledge of various types and operation of diodes.				Thinking (Bloom)			Knowledge	Analysis	Development	Design, Research	Usage	Culture	& Sustainability		Team Work	on	B. Finance	Learning				
CLR-3 :	Develop key understanding related to basics of transistors along with processes involved in working of transistors																						
CLR-4 :	Understand the important ingredient towards technological application of transistors, specifically, field effect transistors																						
CLR-5 :	Get acquainted with various solid state devices and application.																						
CLR-6 :	Develop idea about few exemplary real commonly used electronic devices.																						

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Appreciate the importance of "solid state devices" for the advancement of technology	2	80	75	H	M	H	H	H	M	M	H	H	H	M	H	H	H	H
CLO-2 :	Analyze diodes and understand its significance in technological application	2	80	70	H	M	M	H	M	M	M	H	M	H	M	H	M	M	M
CLO-3 :	Obtain the knowledge on the transistors and its working principles	2	75	70	H	M	H	H	H	H	M	H	M	H	H	H	H	H	H
CLO-4 :	Achieve knowledge about variety of transistors and difference between various transistors	2	80	75	M	H	H	M	H	H	H	H	H	H	M	H	H	H	H
CLO-5 :	Evaluate the working principles of existing devices based on solid state electronics	2	80	70	H	M	H	H	H	M	M	H	M	H	M	H	H	H	H
CLO-6 :	Get an idea of future device application in advancing the existing technology for power efficient devices	2	80	75	H	M	M	H	H	M	M	H	H	H	M	H	H	M	H

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Brief introduction to crystal structure in solids	Basic structure of p-n junction	Basics of Bipolar transistors	Introduction to Field Effect Transistors (FET)	Introduction to light emitting diode (LED)
	SLO-2 Electronic band structure	Current transport in p-n junction diode	Usefulness of transistors	Working principle of FET	Working principle of LED
S-2	SLO-1 Detailed discussion on energy bands in solids	I-V Characteristics, Zero applied bias: Electric field	Theory of operation and action of PNP	Junction FET	Different useful materials for LED
	SLO-2 Discussion on band structure calculation	Built-in potential, junction capacitance, Diffusion capacitance	NPN transistors	Theory of operation and current equation	Multilayers heterojunctions for LED
S-3	SLO-1 Elemental and compound semiconductors	Generation-recombination currents	Description of majority and minority carrier distribution	Introduction of Metal semiconductor FET (MOSFET)	Photodiodes-current and voltage in an illuminated junction
	SLO-2 Doping in semiconductors, Shallow and deep levels	Junction breakdown mechanisms	Terminal currents in transistors	Application of MOSFET	Exemplary description of photodiodes
S-4	SLO-1 Carrier statistics, Carrier transport, Carrier mobility	Introduction of Zener diode	How transistors can be used for amplification?	Metal oxide semiconductor FET (MOSFET): working principle	Photodetectors-noise
	SLO-2 Scattering mechanisms	Unique features associated with Zener diode	Transistor as amplifier	Application of MOSFET	Bandwidth of photodetectors
S-5	SLO-1 Non-equilibrium conditions, Quasi Fermi levels	Heterojunctions: Band alignments	What makes transistors to work as switch?	Details of VI Characteristics of MOSFET	Semiconductor lasers
	SLO-2 Recombination processes	Energy band diagrams of heterojunctions	Application of transistor as switch	Qualitative description of VI characteristics of MOSFET	Population inversion at a junction
S-6	SLO-1 Understanding current density	Formation of two dimensional electron gas	How transistors can be used for switching?	Depletion and enhancement types - threshold voltage	Detailed description of emission spectra for p-n junction lasers
	SLO-2 Mathematical description of continuity equations	Qualitative description of two dimensional electron gas	Summary of transistor application	Gate capacitance inversion and accumulation layers	Quantitative interpretation of emission spectra for p-n junction lasers
S-7	SLO-1 Surface recombination	Metal-semiconductor contacts	Open-circuited transistors-biasing in active region,	Complementary MOSFET	Heterojunction lasers-materials for semiconductor lasers

	SLO-2	Surface states	Schottky barrier diode	Ways to bias a transistors	Significance of CMOSFET	Semiconductor laser applications
S-8	SLO-1	Excitons in semiconductors	Fermi level pinning	Detailed description of Schottky transistors	Introduction to high electron mobility transistor (HEMT)	Introduction to Solar cells
	SLO-2	How to estimate carrier concentration?	C-V characteristics of a Schottky diode	Working principles of Schottky transistors	Ways to achieve HEMT	Relevance of semiconducting materials in solar cell application
S-9	SLO-1	Discussion on Hall effect measurements	Current transport processes	Detailed description of Optical transistors	Working principle of charge coupled devices (CCD)	Transistors as building block of memory devices
	SLO-2	Discussion on fractional quantum Hall effect	I-V characteristics	Application of Optical transistors	Interpretation of information obtained from CCD	Advanced solid state memory devices

Learning Resources	1. Solid State Electronic Devices, by Streetman and Ben Garland, Prentice Hall, 2000 2. Physics of Semiconductor Devices, by S. M. Sze and Kwok. K. Ng, John Wiley & Sons, Inc., 2007	3. Art of Electronics, by Horowitz and Hill, Cambridge University Press, 2 nd ed., 1989
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. Hemant Dixit, Global Foundaries, USA, aplahemant@gmail.com	1. Dr. Debanjan Bhowmik, IIT Delhi, debanjan@ee.iitd.ac.in	1. Dr. Jaivardhan Sinha, SRMIST
2. Dr. Krishna Surendra Muvvala, Saint Gobain Research India, India, Krishna.muvvala@saintgobain.com	2. Dr. M. S. Ramachandra Rao, IIT Madras, msrrao@iitm.ac.in	2. Dr. S. Chandramohan, SRMIST

Course Code	18NT0303T	Course Name	MICRO AND NANOELECTRONICS	Course Category	O	Open Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Nanotechnology	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Understand the physical effects of semiconductor-semiconductor junction, its electrostatics, and device operation	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Learn methodology of lithography and etching to pattern materials at micro and nanoscale		
CLR-3 :	Acquire knowledge of VLSI design and fabrication		
CLR-4 :	Get acquainted with CMOS fabrication rules		
CLR-5 :	Learn integrated circuit passive and component fabrication processes		
CLR-6 :	Introduce next generation printed electronics technology		

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Apply working of semiconductor devices in its large scale operation	2	80	75	H	M	H	H	H	M	M	H	H	H	M	H	H	H	H
CLO-2 :	Pattern diverse materials using lithography techniques to enhance the device density on chip	2	80	70	H	M	M	H	M	M	M	H	M	H	M	H	M	M	M
CLO-3 :	Design the VLSI components	2	75	70	H	M	H	H	H	H	M	H	M	H	H	H	H	H	H
CLO-4 :	Fabricate small-scale devices and chip level device space management	2	80	75	M	H	H	M	H	H	H	H	H	H	M	H	H	H	H
CLO-5 :	Imagining importance of nanoscale devices	2	80	70	H	M	H	H	H	M	M	H	M	H	M	H	H	H	H
CLO-6 :	Envision low cost production of electronic devices using printed technology	2	80	75	H	M	M	H	H	M	M	H	H	H	M	H	H	M	H

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Fundamentals of Electronic Devices	Need and basics of lithography	History of complementary metal-oxide-semiconductor (CMOS)	Integrated circuit fabrication technology	Overview of flexible electronics
	SLO-2	Overview of semiconductor Physics	Optical lithography	CMOS processing: LOCOS and STI isolation	Moor's law and scaling	Advantages of printing
S-2	SLO-1	Intrinsic semiconductors	Optical lithography controls	Layout design rules	Passive component fabrication	Requirements of printing
	SLO-2	Extrinsic semiconductors	Photo-mask making	Rules for: well, transistor, contact, via, etc.	Fabrication of integrated resistor	Printing tools
S-3	SLO-1	p-n junction formation	Working concept and controls of e-beam lithography	MOSIS Scalable CMOS Design Rules	Fabrication of integrated capacitor	Types of fluids for ink
	SLO-2	Charge distribution and Fermi level in p-n junction	Resolution of electron beam lithography	Micron design rules	Fabrication of integrated inductor	Properties of fluids in printing processes
S-6	SLO-1	Depletion region capacitance	Wet etching mechanism and disadvantages	CMOS integrated inverter working principle	Self-aligned gate	Working principle of flexographic printing (FP)
	SLO-2	Depletion region width and its bias dependence	Wet etching of silicon, silicon dioxide and metal	IV characteristics of inverter	fabrication of NMOS with polysilicon self-aligned gate	Advantages and disadvantages of FP
S-7	SLO-1	Metal-Oxide-Semiconductor (MOS) capacitor	Types of dry etching	CMOS fabrication process	3D transistors requirements	Working principle of gravure printing (GP)
	SLO-2	Operation of MOS capacitor	Ways of plasma generation for etching processes, Sputter etching	CMOS integrated inverter design rules	FinFET technology	Advantages and disadvantages of GP
S-8	SLO-1	Operation of MOSFETs in linear region	Capacitively coupled plasma	CMOS process enhancement	Integrated memory devices	Working principle of screen printing (SP)
	SLO-2	Operation of MOSFETs in saturation region	Reactive ion etching	Enhancement for transistor and interconnect	Dynamic RAM (DRAM) fabrication	Advantages and disadvantages of SP
S-9	SLO-1	Sub threshold region	Inductively coupled plasma	Manufacturing issues	Challenges for nanoelectronics	Working principle of inkjet printing (IP), Advantages and disadvantages

	SLO-2	MOSFET scaling	Deep reactive ion etching and bosh process	Yield management	Requirements of nanoelectronics	Future of printed low-cost electronics
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Learning Resources	1. S. M. Sze, and S. Lee, "Semiconductor Devices Physics and Technology", Wiley, 2012 2. Neil H. E. Weste and David Money Harris, "CMOS VLSI design", Addison-Wesley, 2011	3. Giovanni Nisato, Donald Lupo, Simone Ganz, "Organic and Printed Electronics", CRC Press, 2016. 4. Hans H. Gatzert, Volker Saile, Jürg Leuthold, "Micro and Nano Fabrication", Springer 2015
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. Hemant Dixit, Global Foundaries, USA, aplahemant@gmail.com	1. Dr. A. Subrahmanyam, IIT Madras, manu@iitm.ac.in	1. Dr. Abhay Sagade, SRMIST
2. Dr. Krishna Surendra Muvvala, Saint Gobain Research India, India, Krishna.muvvala@saintgobain.com	2. Dr. N. N. Murthy, IIT Tirupati, nmurthy@iittp.ac.in	2. Dr. A. Karthigeyan, SRMIST

Course Code	18NT0304T	Course Name	ENVIRONMENTAL NANOTECHNOLOGY				Course Category	O	Open Elective Course				L	T	P	C							
										3	0	0	3										
Pre-requisite Courses	Nil		Co-requisite Courses		Nil		Progressive Courses		Nil														
Course Offering Department		Nanotechnology			Data Book / Codes/Standards			Nil															
Course Learning Rationale (CLR):			The purpose of learning this course is to:				Learning			Program Learning Outcomes (PLO)													
CLR-1 :	Acquire knowledge on nanotechnology in environmental and health effects					1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Understand the effect of nanomaterials for environmental protection					Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Describes the effect of nanomaterials in environment																						
CLR-4 :	Explains the safety measurements																						
CLR-5 :	Gain knowledge on different sustainable nanotechnologies																						
CLR-6 :	Educate and understanding of sustainable nanotechnology																						
Course Learning Outcomes (CLO):			At the end of this course, learners will be able to:																				
CLO-1 :	Elucidate the effects to human health and the environment					2	80	70	H	M	M	H	M	M	M	H	M	H	M	H	M	M	M
CLO-2 :	Analyze the relationships between key properties of nanomaterials and their environmental fate					2	75	70	H	M	H	H	H	H	M	H	H	H	H	H	H	H	H
CLO-3 :	Apply the physical and chemical properties of nanomaterials					2	80	75	M	H	H	M	H	H	H	H	H	M	H	H	H	H	H
CLO-4 :	Approach the influence of the behavior of nanomaterials in the environment and in biological systems					2	80	70	H	M	H	H	H	M	M	H	M	H	M	H	H	H	H
CLO-5 :	Demonstrate the knowledge of mapping of the environmental fate of nanomaterials					2	80	75	H	M	M	H	H	M	M	H	H	H	M	H	H	M	H
CLO-6 :	Elucidate the use of nanoparticles for environmental remediation and water treatment					2	80	75	H	M	M	H	H	M	M	H	H	H	M	H	H	M	H
Duration (hour)		9		9		9		9		9		9											
S-1	SLO-1	Nanotechnology in environmental and health effects	Nanomaterials for Environmental Protection	Identification and characterization of Hazardous waste	Environmental Nano Remediation Technology		Sustainable Nanotechnology																
	SLO-2	Environmental pollutants in air	Nanotechnology processes	Nano Pollution	Thermal methods		Application of industrial ecology to nanotechnology																
S-2	SLO-1	Environmental pollutants in water	Nano Engineering materials for Pollution Prevention	Air/Gas Contaminants	Physical methods		Fate of nanomaterials in environment																
	SLO-2	Environmental pollutants in soil	Green Chemistry	Water Contaminants	Chemical methods		environmental life cycle of nano materials																
S-3	SLO-1	Hazardous and toxic wastes	Energy efficient resources and materials	Soil Contaminants	Biological Methods		environmental impacts of nano materials																
	SLO-2	Challenges to occupational health	Nanotechnology products- Nanomaterials	Identification and Characterization of Organic and inorganics	Nano Filtration methods for treatment of waste water		health impacts of nano materials																
S-4	SLO-1	Challenges to occupational hygiene	Nanodevices and nanosystems	Identification and Characterization of Organic and inorganics	removal of organics & inorganics and pathogens		toxicological threats																
	SLO-2	Toxicity of nanoparticles	Synthesis of nanomaterials by Physico-chemical approaches	Nanomaterials-Remediation	removal of inorganics		eco-toxicology																
S-5	SLO-1	Effects of inhaled nanosized particles	Bio-nanocomposites	Nano Membranes	removal of pathogens		exposure to nano particles – biological damage																
	SLO-2	Skin exposure to nanoparticles	Nanoparticles and Microorganisms	Nano Meshes	Nanotechnology for water 5 remediation and purification		threat posed by nano materials to humans																
S-6	SLO-1	Impact of CNTs on respiratory systems	Microbial Synthesis of Nanomaterials	Nano Fibres	Treatment of hi-tech industrial waste waters using nano particles/ modified structures/devices		environmental reconnaissance and surveillance																
	SLO-2	Hazards of exposure to nanoparticles	Biological Methods for Synthesis of nano-emulsions using bacteria	Nano Clays and Adsorbents, Zeolites, Nano Catalysts, Carbon Nano Tubes,	Treatment of hi-tech industrial waste waters using modified structures		Corporate social responsibility for nanotechnology																
S-7	SLO-1	Risks of exposure to nanoparticles	Fungi and Actinomycetes	Bio Polymers	Treatment of hi-tech industrial waste waters using dyes		Combining Life Cycle and Risk Assessment																

	SLO-2	Screening of nanomaterials for understanding potential effects to human health and the environment	Different plants based nanoparticle synthesis	Single Enzyme Nanoparticles	Groundwater remediation	Proposed Solutions to prevent toxicology
S-8	SLO-1	Mapping of the environmental fate of nanomaterials	Plants based nanoparticle synthesis	Bio Metallic Iron Nanoparticles	Surface water treatment	Safety measurements
	SLO-2	Relationships between key properties of nanomaterials and their environmental fate	Nano composite biomaterials – Fibres	Nano SemiConductors	Titanium dioxide	Education and understanding of sustainable nanotechnology
S-9	SLO-1	Transport and transportation of nanomaterials	Devices and Structures	Photo catalysis	Challenges	Applications of nanotechnology for sustainability
	SLO-2	Bio-distribution and toxicity of nanomaterials	Nano Bio systems.	Nano-sensors	Environmental Benefits of nanomaterials	Nanomaterials in future - implications.

Learning Resources	1. Nanotechnology: Health and Environmental risk by Jo Anne Shatkin. CRC press, 2008.	3. Environanotechnology by Mao Hong fan, Chin-pao Huang, Alan E Bland, Z Honglin Wang, RachidSliman, Ian Wright. Elsevier, 2010.
	2. Nanotechnologies, Hazards and Resource efficiency by M. Steinfeldt, Avon Gleich, U. Petschow, R. Haum. Springer, 2007.	4. Nanostructured conductive polymers. Edited by Ali Eftekhar. Wiley, 2010.

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. N. Vijayan, CSIR-NPL, nvijayan@nplindia.org	1. Prof. S. Balakumar, University of Madras, balakumar@unom.ac.in	1. Dr. M.Navaneethan, SRMIST
2. Dr. Krishna SurendraMuvvala, Saint Gobain Research India, India, Krishna.muvvala@saintgobain.com	2. Prof. V. Subramaniyam, IIT Madras, manianvs@iitm.ac.in	2. Dr. E. Senthil Kumar, SRMIST

Course Code	18NT0305T	Course Name	MEDICAL NANOTECHNOLOGY	Course Category	O	Open Elective course	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Nanotechnology	Data Book / Codes/Standards			Nil

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 : <i>Understanding the basics of medicine</i>		1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 : <i>Know the various classification of nanomedicine</i>		Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 : <i>Getting knowledge about interaction of nanomaterials with biological environment</i>		Expected Proficiency (%)	Problem Analysis
CLR-4 : <i>Gain a broad understanding about nanosystems for the diagnosis and therapy</i>		Expected Attainment (%)	Design & Development
CLR-5 : <i>Get acquainted with future aspects of nanosurgery</i>			Analysis, Design, Research
CLR-6 : <i>Comprehend the principles behind medical nanotechnology</i>			Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 : <i>To distinguish the advantages between conventional and nanomedicine</i>		2 80 75	H M H H H M M H H H M H H H H
CLO-2 : <i>Analyze the concepts of medical nanotechnology</i>		2 80 70	H M M H M M M H M H M H M M M
CLO-3 : <i>Apply concepts of nanomedicine to a focused clinical area of their choice</i>		2 75 70	H M H H H H H M H H H H H H H
CLO-4 : <i>Apply the nanosystems for diagnosis and therapy</i>		2 80 75	M H H M H H H H H H M H H H H
CLO-5 : <i>Apply the concepts of nanosurgery</i>		2 80 70	H M H H H M M H M H M H H H H
CLO-6 : <i>Apply the principle of nanomolecular tracking</i>		2 80 75	H M M H H M M M H H H M H H M H

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Conventional medicine	Nanosensors & nanoscale scanning	Nanoparticles for imaging & drug delivery	Nanodiagnostics
	SLO-2	Prospect of nanomedicine	Nanosensor Technology	Types of Nanoparticles for drug delivery	Nanodevices for Clinical Nanodiagnostics
S-2	SLO-1	Current Medical Practice	Chemical Nanosensor	Nanoparticles for medical imaging	Nanosensors for Diagnosis
	SLO-2	Challenges in Current Medical Practice	Molecular Nanosensor	Enhancement for X-ray	Nanoarrays for Molecular Diagnostics
S-3	SLO-1	Evolution of Scientific Medicine	Displacement Sensor	MRI imaging	Types of Nanoarrays
	SLO-2	Drawinian medicine	Motion Sensors	IR imaging	Nanoparticles for Molecular Diagnostics
S-4	SLO-1	Volitional Normative Model of Disease	Force Nanosensor	Visible imaging	Gold Nanoparticles
	SLO-2	Disease Nominalism, Disease Relativism	Thermal Nanosensor	UV imaging	Types of Nanodevices for drug delivery
S-5	SLO-1	Treatment Methodology	Electric and Magnetic Sensing	Nanoparticles for targeted imaging	Tools for Nanosurgery
	SLO-2	Conventional methods	Cellular Bio scanning	Targeting moieties	Quantum Dots for Molecular Diagnostics
S-6	SLO-1	Evolution of Bedside Practice	Macrosensing	Nanoparticles for delivery of energy	Nanorobots for Surgery
	SLO-2	Benefits of Bedside Practice	Integated nanosensor technologies	Types of nanoparticles for delivery of energy	DNA Nanomachines for Molecular Diagnostics
S-7	SLO-1	Molecular Nanotechnology	Genomics	Nanoparticles for delivery of drugs	Nanobarcodes Technology
	SLO-2	Introduction and Basic principles	Methods in Genomics	Types of nanoparticles for delivery of drugs	Commercially available Nanobarcodes
S-8	SLO-1	Pathways to Molecular Manufacturing	Proteomics	Materials for drug delivery	QDs for Sensing Cancer Cell Apoptosis
	SLO-2	Molecular Transport	Methods in Proteomics	Fabrication for drug delivery	Dendrimers for Sensing Cancer Cell Apoptosis
					Gold Nanoparticles for Cancer Diagnosis
					Nanotubes for Detection of Cancer Proteins
					Nanoparticles for the Optical Imaging of Tumors
					Nanolaser Spectroscopy for Detection of Cancer in Single Cells

S-9	SLO-1	Molecular Sortation	Real-time monitoring	Nanocapsulation for drug delivery	Nanodiagnostics for Integrating Diagnostics with Therapeutics.	Nanoparticles-MRI for Tracking Dendritic Cells in Cancer Therapy
	SLO-2	Types of Molecular Sortation	In vivo medical monitoring	Application of Nanocapsulation for drug delivery	Advantages of Integrating Diagnostics with Therapeutics.	Advantages of Nanoparticle tracking

Learning Resources	1. Robert .A. Freitas.Jr, "Nanomedicine"- Landes Bioscience Press 2010. 2. Harry F. Tibbals, "Medical Nanotechnology & Nanomedicine' - CRC press,2011.	3. Jain.K.K, "Handbook of Nanomedicine"- Springer, 2012.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. K. Chandru Triviron Healthcare Pvt. Ltd. Chennai, chandru.k@triviron.com	1. Dr. Amit Kumar Mishra , IIT Jodhpur, amit@iitj.ac.in	1. Dr. Devanandh Venkata Subhu, SRMIST
2. Dr.Nagesh Kini, Thermax,Pune,Maharashtra,nagesh.kini@gmail.com	2. Dr. Sampath Kumar T.S,IIT Madras, tssk@iitm.ac.in	2. Dr. Selvamurugan, SRMIST

Course Code	18NT0306T	Course Name	NANOSCALE SURFACE ENGINEERING	Course Category	O	Open Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Nanotechnology	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Obtain vast knowledge on Surface and Interfaces and its structure	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Understand the process involved in surface and Interfaces	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Understand the Diffusion process involved in surface and related laws	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Describe the laws related to surface phenomena	Expected Attainment (%)	Design & Development
CLR-5 :	Gain knowledge on Surface Analysis Techniques		Analysis, Design, Research
CLR-6 :	Understand the principles of XPS, UPS and ISS		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Apply the concept of Surface crystallography to understand the surface structure	2 80 75	H M H H H M M H H H M H H H H
CLO-2 :	Able to analyze surface related process and its measurements	2 80 70	H M M H M M M H M H M H M M M
CLO-3 :	Apply the concept of Fick's law to have clear a understanding on surface diffusion process	2 75 70	H M H H H H H M H H H H H H H
CLO-4 :	Analyze the different mechanisms involved in surface diffusion and kinetics	2 80 75	M H H M H H H H H H M H H H H
CLO-5 :	Utilize the Photoelectron spectroscopic and Secondary electron techniques to understand the properties of surface	2 80 70	H M H H H M M H M H M H H H H
CLO-6 :	Analyze different types of metal and semiconducting surfaces and its properties	2 80 75	H M M H H M M H H H M H H H H

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Introduction to surfaces and interfaces and its related terms and definitions	Adsorption and desorption: Definition & Concept	Concept of Random-walk motion	Surface specificity
	SLO-2	surface energy, surface tension and surface states	Various types of adsorption and desorption	Basic equations -random-walk motion	Spectrum of secondary electrons
S-2	SLO-1	Some basic concepts of bulk crystallography : Direct lattices and directions	Basics of adsorption kinetics	Fick's laws: Definition and its explanation	Photoelectron spectroscopy - Physical process: photoemission, spectral feature
	SLO-2	Symmetry groups and planes	Concept of coverage dependence	Fick's laws: Definition and its explanation	Photoelectron spectroscopy -depth specificity
S-3	SLO-1	Structure of the unit cell, Primitive cell in bulk crystals.	Coverage dependence derivation	Tracer diffusion	Photoelectron spectroscopy (XPS and UPS) - compositional information
	SLO-2	Concept of ideal crystal and of ideal crystal	Langmuir Isotherm	Chemical, diffusion	Photoelectron spectroscopy (XPS and UPS) - elemental sensitivity
S-4	SLO-1	Surface structure and surface order	Temperature dependence Kinetics	Intrinsic diffusion	Photoelectron spectroscopy (XPS and UPS) - chemical-state information
	SLO-2	Surface crystallography	Temperature dependence derivation	Mass transfer diffusion	Photoelectron spectroscopy (XPS and UPS) -spectral resolution and depth profiling
S-5	SLO-1	Surface Crystallography of a plane,	Angular dependence Kinetics	Anisotropy of surface diffusion	Photoelectron spectroscopy (XPS and UPS) -Modular instrumentation: excitation sources
	SLO-2	And its point and space group symmetry	Kinetic energy dependence Kinetics	Anisotropy of surface diffusion	Energy analyzers and detectors
S-6	SLO-1	Unit mesh transformation approach	Thermal deposition	Atomistic mechanisms of surface diffusion and its types	Auger Electron spectroscopy (AES): physical process: photoemission

	SLO-2	Wood notation description	Theory of Desorption kinetics	Atomistic mechanisms of surface diffusion: hopping mechanism	Ion Scattering Spectroscopy (ISS): physical process: photoemission	Different types involved in Photo induced process
S-7	SLO-1	Unit mesh transformation approach	Thermal desorption spectroscopy: Basic working Principle	Atomistic mechanisms of surface diffusion: Vacancy mechanism	Spectral feature and depth Specificity	Metal – semiconductor surfaces
	SLO-2	Matrix notation and classification of overlayer meshes	Thermal desorption spectroscopy: Instrumentation	Atomistic mechanisms of surface diffusion: Atomic exchange mechanism	AES and ISS: compositional information	Analysis of Metal – semiconductor surfaces properties
S-8	SLO-1	Electronic structure (for three dimension)	Adsorption Isotherms: A detailed study	Atomistic mechanisms of surface diffusion: Tunneling mechanism	AES and ISS: elemental sensitivity	Alkali – metal – semiconductor interfaces
	SLO-2	Density of States (Surface states)	Various types of Adsorption Isotherms	Atomistic mechanisms of surface diffusion: Tunneling mechanism	AES and ISS: chemical-state information & spectral resolution and depth profiling	Analysis of Alkali – metal – semiconductor interfaces properties
S-9	SLO-1	Surface states structure (for two dimension)	Non-Thermal desorption	Nucleation and Equilibration via Surface Diffusion	AES and ISS: excitation sources	Growth of trivalent metals on Si (001)
	SLO-2	Surface electronic structure (for two dimension)	Types of Non-Thermal desorption	Experimental study of surface diffusion	AES and ISS: energy analyzers and detectors	Analysis of Growth of trivalent metals on Si (001) properties

Learning Resources	1. John DiNardo N., "Nanoscale Characterization Of Surface And Interfaces", Wiley-VCH, 2008 2. Oura K., V. G. Lifshits, A. A. Saranin, A. V. Zotov and M. Katayama, "Surface Science – An Introduction" Springer, 2013	3. Unertl W.N., "Physical structure" Elsevier Science B. V, 2006 4. Riviere J.C and Myhra S., "Handbook of Surface and Interface analysis", CRC Press, 2009
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1.Mr.Solomon Jonnes,Bengaluru,solomon@terracarb.com	1. Dr.Amit Kumar Mishra , IIT Jodhpur, amit@iitj.ac.in	1. Dr. V. Kathirvel, SRMIST
2. Dr.Nagesh Kini,Thermax,Pune,Maharashtra,nagesh.kini@gmail.com	2. Dr.Sampath Kumar T.S, IIT Madras, tssk@iitm.ac.in	2. Dr. A. Alagirisamy SRMIST

Course Code	18NTO307T	Course Name	NANOCOMPUTING	Course Category	O	Open Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Nanotechnology		Data Book / Codes/Standards	Nil	

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Acquire knowledge on nanoelectronics and its importance	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Introduce the concept of molecular and optical computing	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Understand about biocomputers and related nanomachines																		
CLR-4 :	Learn basics and advancements of quantum computing																		
CLR-5 :	Understand the architecture of processing in nanosystems																		
CLR-6 :	Gain knowledge on soft computing and neural networks																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Apply the basic concepts in nanocomputing	2	80	75	H	M	H	H	M	M	M	H	H	H	M	H	H	H	H
CLO-2 :	Explain major advances in molecular and optical computing	2	80	70	H	M	M	H	M	M	M	H	M	H	M	H	M	M	M
CLO-3 :	Recognize the evolution and advancements of biocomputers	2	75	70	H	M	H	H	H	H	H	M	H	H	H	H	H	H	H
CLO-4 :	Utilize the knowledge in quantum computing	2	80	75	M	H	H	M	H	H	H	H	H	H	M	H	H	H	H
CLO-5 :	Get familiarized with designing of parallel information processing machines	2	80	70	H	M	H	H	H	M	M	H	M	H	M	H	H	H	H
CLO-6 :	Apprehend the importance of soft computing	2	80	75	H	M	M	H	H	M	M	H	H	H	M	H	H	M	H

Duration (hour)	9	9	9	9	9
S-1	SLO-1	History of computing	Molecular computing	Biological networks and neurons	Quantum computers-Bit and Qubit
	SLO-2	Nanocomputing	Brief background of molecular electronics	Function of neuronal cell	Coherence and entanglement
S-2	SLO-1	Transistors inside the Machine	Origin of molecular computing	Biology-inspired concepts	Quantum parallelisms
	SLO-2	Quantum computers	Molecular computing architecture	Biological Neuronal cells on silicon	Classical gates
S-3	SLO-1	Nanocomputing technologies	Some techniques of molecular computing-Adleman's landmark experiment	Modeling of neuron cells by VLSI circuits	Reversible operations
	SLO-2	From Microelectronics to Nanoelectronics	DNA computation in ciliates-Bacteriorhodopsin	Neuronal networks with local adaptation	Beyond Classical Gates-Superposition
S-4	SLO-1	From Nanoelectronics to Nanoelectronics computers	Challenges of molecular computing-Reliability, Efficiency and Scalability	Distributed data processing	Sqrt(NOT) operation
	SLO-2	Alternative to Transistor technology – quantum computing	Encoding problem-Error-preventing codes	Biocomputers – biochemical computers	Quantum algorithms-Necessity of quantum software in Conjunction with the hardware
S-5	SLO-1	Nanoinformation processing - Prospects and challenges	Building and programming molecular computers	Biomechanical computers	Searching by using Sqrt (NOT)
	SLO-2	Digital signals and gates	Optical computing- Introduction	Bioelectronic computers	Hardware challenges to large Quantum Computers
S-6	SLO-1	Silicon nanoelectronics-short channel effects	Current use of optics for computing	Engineering biocomputers	Ion traps-Solids

	SLO-2	Leakage current in scaled devices-process variation	Advantages of optical methods over electronic ones	DNA computer	NMR in organic liquids-Optics	Methods of soft computing -Fuzzy systems
S-7	SLO-1	Carbon nanotube electronics	Some roles of optics – 2D array mapping	Information processing with chemical reactions	Fabrication Challenges	Evolutionary algorithms
	SLO-2	Band structure of carbon nanotubes-Carbon Nanotube properties	Garbage free operations	Peptide computing	Testing and architectural challenges	Connectionistic systems
S-8	SLO-1	Carbon nanotube field effect transistors	Optical computing paradigms	Development of a peptide computer	Quantum dot cellular automata	Computational Intelligence systems
	SLO-2	Simulation of Schottky barrier carbon nanotube FETs	Ultrafast pulse shaping -Tb/sec data speeds	Nanomachines	Computing with QCA	Characteristics of neural networks in nanoelectronics
S-9	SLO-1	MOSFET like carbon nanotube FETs	Role of non-linear materials in Nanocomputing: Need for new materials	Wetware computer	QCA clocking	Local processing
	SLO-2	Simulation of MOSFET characteristics	Advance in Photonic switches	Parallel processing	QCA design rules	Self organization

Learning Resources	1. Vishal Sahni and Debabrata Goswami, "Nanocomputing: The Future of Computing", Tata McGraw-Hill Education, 2008	2. Karl Goser, Peter Glösekötter and Jan Dienstuhl, "Nanoelectronics and Nanosystems: From Transistors to Molecular and Quantum devices", Springer, 2005
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. Hemant Dixit, Global Foundaries, USA, aplahemant@gmail.com	1. Dr. Ranjit Kumar Nanda, IIT Madras, nandab@iitm.ac.in	1. Dr. V. J. Surya, SRMIST
2. Dr. Krishna Surendra Muvvala, Saint Gobain Research India, India, Krishna.muvvala@saintgobain.com	2. Dr. G. P. Das, IIT Kharagpur, gpdas@metal.iitkgp.ac.in	2. Dr. Saurabh Ghosh, SRMIST

Course Code	18NT0308T	Course Name	SMART SENSOR SYSTEMS	Course Category	O	Open Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Nanotechnology	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 : Acquire knowledge on various sensor systems		1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 : Understand different conversion phenomena involved in sensors		Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 : Describe construction and function of different sensors		Expected Proficiency (%)	Problem Analysis
CLR-4 : Gain knowledge on the material requirement for different sensing mechanisms		Expected Attainment (%)	Design & Development
CLR-5 : Gain knowledge on individual sensing devices and integration of technologies			Analysis, Design, Research
CLR-6 : Understand the basic requirements of basic microsystem technologies and MEMS fabrication processes			Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 : Apply the principles involved in conversion from one energy domain to electrical signal		2 80 75	H M H H H M M H H H M H H H
CLO-2 : Analyze the sensor characteristics and its suitability for a particular application		2 80 70	H M M H M M M H M H M H M M M
CLO-3 : Utilize the suitable material properties to design a sensor		2 75 70	H M H H H H H M H H H H H H H
CLO-4 : Implement a suitable sensor technology for a particular application		2 80 75	M H H M H H H H H H M H H H H
CLO-5 : Explain the concepts of system organization and integration to make a smart sensor		2 80 70	H M H H H M M H M H M H H H H
CLO-6 : Utilize the different sensor concepts to design a lab-on-chip		2 80 75	H M M H H M M H H H M H H M H

Duration (hour)	9	9	9	9	9
S-1 SLO-1	Definitions of Sensors and Smart Sensors	Acoustic waves: Fundamentals	Light Detectors	Biosensors definition	Fundamentals of MEMS/ fabrication:
SLO-2	Integrated Smart Sensors and Applications	Piezoelectric materials for acoustic sensors	Photodiodes, Photoresistors	Bioreceptors	Frequently Used Microfabrication Processes
S-2 SLO-1	Sensors classifications	Solid state SAW sensors	HgCdTe infrared sensors	Construction of different biosensors	Lithography, thin film deposition
SLO-2	Detection means used in sensors and conversion phenomena	Applications of SAW sensors	Visible-light color sensors, high-energy photodiodes	Immobilization of biological elements	Oxidation, Etching (wet and dry)
S-3 SLO-1	Measurements	Acoustic Sensors: Resistive Microphones, Condenser Microphones	Radiation Detectors: Scintillating Detectors	Transduction principles used in biosensing	MEMS fabrication technologies: Bulk micromachining and structures
SLO-2	Units of Measurements	Piezoelectric Microphones	Semiconductor Radiation Detectors	Lab-on-chip/Microsystems/MicroTAS	Surface micromachining and structures
S-4 SLO-1	Sensor Characteristics: Transfer Function, Calibration, Static Characteristics	Magnetic sensors	Thermal Sensors: Functional Principle	Microfluidics	High-aspect-ratio technology microfluidics microsystem components
SLO-2	Accuracy, Calibration Error, Hysteresis, Nonlinearity, Resolution, Dynamic Characteristics	Magnetic Effects and materials	Heat Transfer Mechanisms	Microfluidic unit operations	LIGA(Lithographie, Galvanoformung, Abformung)
S-5 SLO-1	Physical principles of sensing: electric charges	Integrated Hall sensors	Temperature Sensors	Microsystem Integration	Microsystem components
SLO-2	Electric fields, and potentials	Magnetotransistors	Thermoresistive Sensors	System organization and functions	Application of different Microsystem components
S-6 SLO-1	Capacitance, dielectric constant	Force, Strain, and Tactile Sensors	Thermoelectric Contact Sensors, Thermocouple Assemblies	Interface electronics	Nanotechnology:
SLO-2	Magnetic Principle	Strain Gauges, Piezoelectric Force Sensors	Semiconductor pn-Junction thermal Sensors, Optical Temperature Sensors	Fundamentals of interfacing	product prospects - application trends

S-7	SLO-1	Induction Principle	Tactile Sensors	Chemical sensors: Classes of Chemical Sensors	Universal transducer interface	Ultra-thin films
	SLO-2	Electrical Resistance	Piezoresistive sensors(Tactile)	Interaction of gaseous species at semiconductor Surfaces	Three-Signal Technique	Making of ultrathin films
S-8	SLO-1	Piezoelectric effect	Piezoelectric Sensors(Tactile)	Catalysis, the acceleration of chemical reactions,	Introduction to microsystems engineering	Creation of lateral nanostructures,
	SLO-2	Pyroelectric effect	Capacitive Touch Sensors (Tactile)	Thin-film sensors (Chemoresistive sensors)	Microtechnologies	Creation of clusters and nanocrystalline materials
S-9	SLO-1	Hall effect Principle	Piezoresistive Pressure Sensors	Field Effect Transistor for Gas sensing	Systems development: methods and tools	Principles of self-organization
	SLO-2	Seebeck and Peltier effects	Capacitive Pressure Sensor	FET devices ion sensing	Constructive and connective techniques	Future trends

Learning Resources	1. Jacob Fraden, "Handbook of Modern Sensors: Physics, Designs, and Applications", Springer; 4th ed. 2010 2. S. M. Sze, "Semiconductor Sensors", Wiley-Interscience, 1994	3. Gerard Meijer, "Smart sensor systems", Wiley, 2008 4. W Gopel, J. Hesse, J. N. Zemel, "Sensors A Comprehensive Survey" Vol. 8, Wiley-VCH, 1995
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. N. Vijayan, CSIR-NPL, nvijayan@nplindia.org	1. Prof. S. Balakumar, University of Madras, balakumar@unom.ac.in	1. Dr. A. Karthigeyan, SRMIST
2. Dr. Krishna SurendraMuvvala, Saint Gobain Research India, India, Krishna.muvvala@saintgobain.com	2. Prof. V. Subramaniam, IIT Madras, manianvs@iitm.ac.in	2. Dr. M.Kiran, SRMIST

Course Code	18NTQ401T	Course Name	2D MATERIALS AND APPLICATIONS	Course Category	O	Open Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Nanotechnology	Data Book / Codes/Standards			Nil

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Acquire knowledge on graphene and its superior physical properties	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Gain the knowledge on other emerging semiconducting and insulating layered materials	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Describe the methods on synthesis of 2D materials	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Understand the 2D materials physical properties using micro and nanocharacterization techniques	Expected Attainment (%)	Design & Development
CLR-5 :	Gain knowledge on applications 2D materials in technological applications		Analysis, Design, Research
CLR-6 :	Understand the importance of 2D materials applications real life applications		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Understand the scientific knowledge on producing graphene	2 80 75	H M H H H M M H H H M H H H H
CLO-2 :	Analyze different 2D materials with tunable properties	2 80 70	H M M H M M M H M H M H M M M
CLO-3 :	Different methods of synthesis method for 2D materials	2 75 70	H M H H H H M H H H H H H H H H
CLO-4 :	Utilize the spectroscopic concepts to analyze the properties of materials	2 80 75	M H H M H H H H H H M H H H H
CLO-5 :	Use the 2D materials for Biomedical applications	2 80 70	H M H H H M M H M H M H H H H
CLO-6 :	Use the 2D materials for optoelectronics and nanoelectronics	2 80 75	H M M H H M M H H H M H H M H

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Carbon Atom and Its Allotropes	Graphene derivatives: Graphene Oxide	Synthesis of 2D materials	Applications of 2D materials	Graphene-based transistors
	SLO-2 Diamond, Graphite, Fullerenes	Graphene composites	Bottom up methods	Biomedical applications of rGO	Graphene based RF transistors for Flexible electronics
S-2	SLO-1 Graphene	Beyond graphene	Chemical Vapor Deposition	Drug/gene delivery, bioimaging, biosensing	2D TMD based Photodetectors
	SLO-2 Electronic Structure of graphene	Transition metal dichalcogenide (TMD) and white graphene(White graphene)	Pulsed Laser Deposition	Photothermal therapy	Phototransistors
S-3	SLO-1 Electronic properties	Crystal structure	Epitaxial growth	Tissue engineering and anti-bacterial applications	Hybrid Phototransistors
	SLO-2 Optical properties	Electronic and optical properties	Physical vapor deposition	Biocompatibility and biodistribution	Heterostructure Photodetectors
S-4	SLO-1 Helicity and Chirality	Traps and defects	Top down methods	Scaffolds for tissue engineering	2D TMD based Light Emitters
	SLO-2 Klein Tunneling	Mechanical properties	Mechanical Exfoliation	Cancer therapy	Hot Carrier EL
S-5	SLO-1 High Mobility of graphene	Strain effect on electrical and vibrational properties	Liquid phase exfoliation	Graphene devices for Biomolecule detection	Light-Emitting Diodes
	SLO-2 Minimum Conductivity and Universal Optical Conductivity of graphene	Theoretical methods	Electrochemical Lithium Intercalation	Graphene devices for Biomolecule sequencing	Circularly Polarized Light Emission
S-6	SLO-1 Bilayer and multilayer Graphene	Silicene and Germanene	Ball Milling	Photocatalysts	Heterostructure Light Emitters
	SLO-2 Presence of a Magnetic Field	Properties of Silicene and Germanene	Hydrodynamics Exfoliation	Graphene oxide (GO) for Dye degradation and pollutant adsorption	2D TMD-Based Photovoltaics applications :
S-7	SLO-1 Homogeneous Magnetic Field	2D Topological Insulator	Basic Characterization of 2D materials	Hydrogen production from water splitting	Solar cells
	SLO-2 LLs in Bilayer Graphene	Phosphorene: A Novel 2D Material	UV-Vis absorption Spectroscopy	TMDs 2D materials for Electrocatalysis and electrochemical sensing	Graphene membranes
S-8	SLO-1 Anomalous Quantum Hall Effect	2D Crystal-Based Heterostructures	Raman spectroscopy	Oxygen evolution reaction (OER)	Membranes for separation
	SLO-2 Carrier density	A 'Legoland' of Two-Dimensional Materials	Scanning electron microscopy	Oxygen reduction reaction (ORR)	Membranes as barriers

S-9	SLO-1	Gauge Fields Induced by Lattice Deformation	Handling of 2D Heterostructures: Practical Issues	Transmission electron microscopy	Hydrogen evolution reaction (HER)	Supercapacitor electrodes
	SLO-2	Deformation and Elastic strain	Tunnel Diodes and Transistors Based on 2D Heterostructures	Atomic force microscopy	Hydrogen oxidation reaction (HOR)	2D Black phosphorus based FET for Sensor and detector applications

Learning Resources	1. Banks, Craig E., and Dale AC Brownson, eds. "2D Materials: Characterization, Production and Applications" - CRC Press, 2018.	3. Tiwari, Ashutosh, and Mikael Syväjärvi, eds. "Advanced 2D Materials" - John Wiley & Sons, 2016.
	2. Houssa, Michel, Athanasios Dimoulas, and Alessandro Molle, "2D Materials for Nanoelectronics" - CRC Press, 2016.	4. Dragoman, Mircea, and Daniela Dragoman, "2D Nanoelectronics: Physics and Devices of Atomically Thin Materials" - Springer, 2016.

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. Hemant Dixit, GlobalFoundaries USA, aplahemant@gmail.com	1. Dr. Ramaprabhu, IIT Madras, ramp@iitm.ac.in	1. Dr.V.Eswaraiah, SRMIST
2. Dr. Krishna Surendra Muvvala, Saint Gobain Research India, India, Krishna.muvvala@saintgobain.com	2. Dr. M. S. Ramachandra Rao, IIT Madras, msrrao@iitm.ac.in	2. Dr. Abhay, SRM IST

Course Code	18NTQ402T	Course Name	NANO AND MICRO ELECTROMECHANICAL SYSTEMS	Course Category	O	Open Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Nanotechnology	Data Book / Codes/Standards			Nil

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Acquire knowledge on MEMS and NEMS fundamentals	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Understand different principles involved in MEMS devices	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Describe construction and function of MEMS actuators	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Gain knowledge on the material requirement for different actuation mechanisms	Expected Attainment (%)	Design & Development
CLR-5 :	Gain knowledge on individual sensing and Micromechanical components and their integration		Analysis, Design, Research
CLR-6 :	Understand the basic microsystem and MEMS fabrication process technologies		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Apply the principles of sensing and actuation to design NEMS and MEMS devices	2 80 75	H M H H H M M H H M H H H H
CLO-2 :	Analyze the suitability of a actuation mechanism for a particular application	2 80 70	H M M H M M H M H M H M M M M
CLO-3 :	Utilize the suitable material properties to design a MEMS structure	2 75 70	H M H H H H H M H H H H H H H
CLO-4 :	Apply a suitable microsystem technology to create different nano and micro mechanical structure	2 80 75	M H H M H H H H H H H H H H
CLO-5 :	Design high aspect ratio structure and integration with microsystem technologies	2 80 70	H M H H H M M H M H M H H H H
CLO-6 :	Utilize the different sensing and actuation concepts to design a lab-on-chip	2 80 75	H M M H H M M H H H H H H M H

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Micro- and nanoelectromechanical systems	Photolithography	Sensing Principles	Magnetic materials used in MEMS
	SLO-2	MEMS and NEMS: An overview	Structural and sacrificial materials	Actuation Principles	Magnetic Properties used in MEMS
S-2	SLO-1	Nanoelectromechanical Systems	Thin film deposition	Components: Beam	Magnetic sensing and detection
	SLO-2	Scaling Laws	Physical Vapor Deposition , Chemical Vapor Deposition techniques	Cantilever, microplates	Magneto resistive sensor
S-3	SLO-1	Modeling	Impurity doping	Capacitive effects	Hall Effect based sensors
	SLO-2	The input-output concept	Etching (Wet and Dry)	Piezo elements	Magnetodiodes, Magnetotransistor
S-4	SLO-1	Sensors and Actuators	Bulk micromachining	Strain Measurements	Magnetic actuation Principles
	SLO-2	Energy Domains and Transducers	Surface micromachining	Pressure and flow measurements	Essential magnetic actuation concepts
S-5	SLO-1	Sensors considerations	Wafer bonding	MEMS Gyroscopes	Magnetic MEMS actuators
	SLO-2	Actuator considerations	Lithographie, Galvanoformung, Abformung (LIGA) Process	Shear mode piezo actuators	Bidirectional Microactuators
S-6	SLO-1	Mechanical MEMS	MEMS Integration	Gripping piezo actuators	RF based communication systems
	SLO-2	Thermal MEMS	Packaging considerations	Strain Measurement	RF MEMS
S-7	SLO-1	Micro-Opto-Electro-Mechanical Systems (MOEMS)	Basic Modeling elements: Mechanical	Thermal sensors and actuators	MEMS inductor
	SLO-2	Magnetic MEMS, Radio-Frequency MEMS	Basic Modeling elements: Electrical systems	Thermal basics	MEMS Varactors
S-8	SLO-1	Microfluidic systems	Basic Modeling elements: Fluid systems	Thermocouples	MEMS Tuner/filter
	SLO-2	Bio-Chemo devices	Basic Modeling elements: Thermal systems	Thermoresistors	MEMS Resonators
S-9	SLO-1	MEMS Architectures	Translational pure mechanical systems	Actuators based on thermal expansion	MEMS Switches
	SLO-2	NEMS Architectures	Rotational pure mechanical systems	Applications of thermal actuators	MEMS Phase shifter

Learning Resources	1. Mahalik N P, "MEMS", Tata McGraw-Hill Education, 2008 2. Sergey Edward Lyshevski, "Micro-Electro Mechanical and Nano-Electro Mechanical Systems, Fundamental of Nano-and Micro-Engineering", CRC Press, 2005	3. Chang Liu "Foundation of MEMS", Prentice Hall, 2012
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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2. Dr. Krishna Surendra Muvvala, Saint Gobain Research India, India, Krishna.muvvala@saintgobain.com	2. Dr. M. S. Ramachandra Rao, IIT Madras, msrrao@iitm.ac.in	2. Dr. M. Kiran, SRMIST

Course Code	18NTQ403T	Course Name	SCIENTIFIC RESEARCH PRINCIPLES	Course Category	O	Open Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses		Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department		Nanotechnology	Data Book / Codes/Standards	Nil	

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 : Familiarize with the concept of research ethics		1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 : Understand the concept of academic plagiarism		Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 : Understand the concept of Good, Bad science and pseudoscience		Expected Proficiency (%)	Problem Analysis
CLR-4 : Gain knowledge on research methodology		Expected Attainment (%)	Design & Development
CLR-5 : Learn the process of scientific writing			Analysis, Design, Research
CLR-6 : Understand the principles of research Design			Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
CLO-1 : Apply the scientific concepts of ethics and plagiarism	At the end of this course, learners will be able to:	2 80 80	H M H H H M M H H M H H H
CLO-2 : Acquire the knowledge of global and national research ethics		2 80 75	H M M H M M M H M H M M M M
CLO-3 : Ability to appreciate the importance of honesty and integrity in academic life		2 80 80	H M H H H H H M H H H H H H
CLO-4 : Apply scientific research methodology for real life problems		2 75 70	M H H M H H H H H M H H H H
CLO-5 : Utilize the method of scientific writing		2 75 70	H M H H H M M H M H M H H H
CLO-6 : Utilize the methods of data analysis in various applications		2 80 75	H M M H H M M H H H M H H M H

Duration (hour)	9	9	9	9	9
S-1 SLO-1	Introduction – ethics	Research and ethics	Good science vs. Bad science	Research design	Scientific Writing
SLO-2	Scientific ethics	Scientific misconduct	Pseudoscience	Design of the apparatus	Authenticity, accuracy
S-2 SLO-1	Code of ethics	Forms of misconduct	Ways of identification	Design issues and remedies	Originality of the work
SLO-2	Ethics for Engineering	Cheating	Curiosity and research	Design methodology	Title preparation
S-3 SLO-1	Standards of ethical conduct	Plagiarism	Empiricism	Experimentation – sampling	List of authors and addresses
SLO-2	Ethical conduct-expectations and outcome	Recognizing plagiarism	Rationalism	Experimentation –measurements	Abstract writing
S-4 SLO-1	National research ethics	Self-plagiarism	Intuition, authority	Replication of the data	introduction writing
SLO-2	Global research ethics	Ghostwriting and detection	Literature review	Data analysis	Description of methods
S-5 SLO-1	Intellectual property rights	Honor code system	Elementary scientific methods	Error identification	Description of methodology
SLO-2	Fundamental IP laws	academic dishonesty	Observations and observational bias	Error in measurement	Measurements
S-6 SLO-1	Patent and copy rights	Prejudice	Problem identification	Classification of errors	Description and types of measurements
SLO-2	Authorship and credit	Intuition	Basic assumptions	Errors analysis	Analysis of results
S-7 SLO-1	Conflict of interest	Observation bias	Hypothesis	Interpretation of the data	Explanation of results
SLO-2	Error and negligence	Self-misunderstanding	Formulation of an hypothesis	Test of the hypothesis	Result and analysis
S-8 SLO-1	Case studies – cloning scandal, miracle drug thalidomide	Egoism	Hypothesis driven research design	Mathematical modeling	Discussion and acknowledgement
SLO-2	Case studies –, miracle drug thalidomide	Some plagiarism cases in India	Verification of Hypothesis	Types of mathematical modeling	Conflict of interest declaration
S-9 SLO-1	Jan HendrikSchön case	Recent Plagiarism cases (abroad)	Identification of experimental techniques	Numerical computation	References, paper/poster presentation
SLO-2	The Baltimore affair	Consequence of Plagiarism	Implementation of the experimental techniques	Result presentation	Electronic publication

Learning Resources	1. National academy of Science, National academy of Engineering, and Institute of Medicine, "On being a scientist: A guide to responsible conduct in research", Third edition, The National Academics Press, 2009 2. Adam Briggie and Carl Mitcham, "Ethics and science: An Introduction", Cambridge University Press, 2012	3. David B. Resnik, "The ethics of science: An introduction", Routledge Publication, 1998 4. Gary Comstock, "Research Ethics: A philosophical guide to the responsible conduct of Research" Cambridge University Press, 2013
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. Narayanasvamy Vijayan, National Physical Laboratory, nvijayan@nplindia.org	1. Prof. V. Subramaniam, IITM, Chennai, manianvs@iitm.ac.in	1. Dr. A. Karthigeyan, SRMIST
2. Dr.A. Pandikumar, Scientist, CSIR-CERL, pandikumar@cecri.res.in	2. Prof. D. Arivuoli, Anna University, arivuoli@annauniv.edu	2. Dr. A. A. Alagirisamy, SRMIST

Course Code	18NTO404T	Course Name	MICRO AND NANOFUIDIC TECHNOLOGY	Course Category	O	Open Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Nanotechnology	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																				
CLR-1 :	Understand the theory of fluidics in a micro scale				Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15				
CLR-2 :	Gain knowledge in micro fluidics equations									Expected Proficiency (%)	Expected Attainment (%)	Problem Analysis																
CLR-3 :	Understand the concept behind viscous flow in micro scale									Design & Development																		
CLR-4 :	Acquire the knowledge in Micro fluidic devices and manufacturing									Analysis, Design, Research																		
CLR-5 :	Gain knowledge scaling materials for manufacturing									Modern Tool Usage																		
CLR-6 :	Understand the sensors for micro fluidic application									Society & Culture																		
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:							Environment & Sustainability																			
CLO-1 :	Apply the concept of fluidics in micro and nanoscale								Ethics																			
CLO-2 :	Analyze the flow and viscosity of the fluidics				2	80	75		Individual & Team Work																			
CLO-3 :	Analyze the viscous flow of micro/nano fluidic devices				2	80	70		Communication																			
CLO-4 :	Utilize the knowledge gained for designing micro/nano fluidic devices				2	80	75		Project Mgt. & Finance																			
CLO-5 :	Apply the various fluidic equations to design micro/nano fluidic devices				2	80	70		Life Long Learning																			
CLO-6 :	Design micro/nano fluidic devices based on theory				2	80	75		PSO - 1																			
									PSO - 2																			
									PSO - 3																			

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Introduction: Fundamentals of kinetic theory	Micro and nanofluids – An Introduction	Introduction to Microscale Viscous Flow	Introduction - concepts microfluidic devices
	SLO-2	Fundamentals of molecular models	Basic concepts in microfluidics & Nanoscale fluidics	Structure of flow in a pipe or channel	Microfluidic Technology
S-2	SLO-1	Kinetic theory of micro and macroscopic properties	Governing equations	Poiseuille's equation	Fabrication Of A Simple Microfluidic Chip
	SLO-2	Molecular models of micro and macroscopic properties	Applications- Preparatory concepts	Poiseuille flow in a pipe	Advantages of microfluidic devices
S-3	SLO-1	Binary collisions	Laws of fluid flows determination of transport properties	Velocity in slip flow of gases	Fluidic transport mechanisms In Microfluidic Devices
	SLO-2	Distribution functions	Classification of fluid flow	Velocity in slip flow of liquids	Pressure-driven and electro-kinetically driven flows in Devices
S-4	SLO-1	Boltzmann equation	Continuum approximation	Theory of flow in a thin film under gravity	Scaling of materials
	SLO-2	Maxwellian distribution functions	Limitations and drawbacks	Two and three dimensional approach	Silicon materials for the manufacture
S-5	SLO-1	Wall slip effects	Kinematics of Microscale Liquid Flow	Derivation - thin film under gravity	Glass materials for the manufacture
	SLO-2	Accommodation coefficients	Derivation of Kinematics of Microscale Liquid Flow	Properties of thin film equation	Polymers materials for the manufacture
S-6	SLO-1	Flow and heat transfer analysis of microscale	Liquid flow along surface	Developing suction and laminar flows	Fluidic structures
	SLO-2	Couette flows	Effect of body forces in liquid flow	Flow control	Manufacturing a fluidic structure
S-7	SLO-1	Pressure driven gas micro- flows	Navier- Stokes equation	Surface tension driven flow	Stacking sequence
	SLO-2	Micro flows with wall slip effects	Equation's properties	And its limitations	Stacking - fabrication methods
S-8	SLO-1	Concept of Heat transfer in micro-Poiseuille flows	Theory of Two-dimensional Navier- Stokes equation	Sedimentation of a solid particle	Surface modifications
					Receptor and Transducer based classification of biosensors

	SLO-2	Expression for Poiseuille flows	Two-dimensional Navier- Stokes equation in terms of Reynolds Equation	Transportation of a solid particle	Different techniques involved in Surface modifications	Types of Biotransducers
S-9	SLO-1	Mechanism of micro flows under compression	Navier- Stokes equation for Steady and compressible flow	Simple model for blood flow	Spotting mechanisms	Nanopores and nanopore membrane for biochemical sensing
	SLO-2	Compressibility and its effects	Steady and incompressible flow Navier- Stokes equation	Non-Newtonian properties of blood	Detection mechanisms	Single Molecule sensing devices

Learning Resources	1. Terrence Conlisk, "Essential of Micro and nanofluidics: with applications to biological and chemical sciences", Cambridge University Press, 2012	3. HenrikBruus, "Theoretical Microfluidics", Oxford Master Series in Physics, 2007
	2. Joshua Edel, "Nanofluidics", RCS publishing, 2009	4. PatricTabeling, "Introduction to Microfluids", Oxford U. Press, 2005

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. Nagesh Kini, Thermax, Pune, Maharastra, nagesh.kini@gmail.com	1. Dr. Sampath Kumar T.S, IIT Madras, tssk@iitm.ac.in	1. Dr. V. Eswaraiah, SRMIST
2. Mr. K. Chandru Triviron Healthcare Pvt. Ltd. Chennai, chandru.k@triviron.com	2. Dr. Amit Kumar Mishra , IIT Jodhpur, amit@iitj.ac.in	2. Dr. Junaid MasudLaskar, SRMIST

Course Code	18NTQ405T	Course Name	THINFILM PHOTOVOLTAICS	Course Category	O	Open Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Nanotechnology	Data Book / Codes/Standards			Nil

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 : Review the basic principles and design of photovoltaic cell technology		1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 : Understand the key properties of semiconductors films used in photovoltaic technology			
CLR-3 : Review the basic photovoltaic device structure and design			
CLR-4 : Develop an understanding of different thin film photovoltaic device technologies and their design			
CLR-5 : Gain exposure to the various tools and techniques used in thin film photovoltaics			
CLR-6 : Acquire knowledge on advanced concepts explored in thin film photovoltaics			
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Engineering Knowledge
CLO-1 : Differentiate between different types of photovoltaic technologies		2 80 75	Problem Analysis
CLO-2 : Interpret important properties of semiconductors relevant to thin film photovoltaics		2 80 70	Design & Development
CLO-3 : Apply different photovoltaic device design concepts for different applications		2 75 70	Analysis, Design, Research
CLO-4 : Appreciate advancement of different types of thin film solar cells		2 80 75	Modern Tool Usage
CLO-5 : Appreciate the advanced concepts and explorations in thin film photovoltaics		2 80 70	Society & Culture
CLO-6 : Perform thin film photovoltaic device fabrication, testing and calculations		2 80 75	Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Basics and basic components of PV systems	Semiconductor thin films-Optical absorption	Different generations of PV	Thin film deposition	Device architectures
	SLO-2 Mechanism of PV	Carrier photo generation	Thin film solar cells	Various techniques	Flexible substrates, transparent devices.
S-2	SLO-1 Sun as a source of energy	Band gap	Silicon solar cells	Evaporation techniques	Multi-junctions
	SLO-2 Solar spectrum, air mass	Direct Vs Indirect bandgaps	Thin film Silicon solar cells	Sputtering techniques	Tandem solar cells
S-3	SLO-1 Solar Cell parameters	Carriers	Amorphous Silicon based solar cells	MBE	Bandgap profile optimization
	SLO-2 Device testing	Carriers transport	a-Si and a-Si: H solar cells	Laser based techniques	Solar spectrum matching
S-4	SLO-1 Efficiency measurements	Minority carrier transport properties	II-VI thin film PV	CVD, PECVD	Light trapping
	SLO-2 FF, V _{oc} , J _{sc} etc for ideal cells	Carrier recombination-lifetime and defects	Chalcopyrite photovoltaics	Spray and Non vacuum routes	Antireflection coatings
S-5	SLO-1 Non-idealities, Loss mechanisms	Band to band and Shockley-Read-hall recombination	CdTe./CdS thin film solar cells	Techniques to measure thickness	Self-cleaning coatings
	SLO-2 Optical & electrical loss mechanisms	High injection effects	Superstrate structure	Optical and electronic properties of thin films	Plasmonic enhancements
S-6	SLO-1 Basics of solar cell device design	Surface and interface recombination	CuInGaSe ₂ /CdS thin film cell technologies	Fabrication process of thin film solar cells	Luminescence concentrators
	SLO-2 Minimization of losses	Implications on device performance	Earth abundant alternatives	Specific techniques used	Up conversion
S-7	SLO-1 Lateral design	PN homojunctions	Thin film solar cells based on Cu ₂ ZnSnS ₄	Established parameters in thin film cell technologies	New concepts
	SLO-2 Vertical design	Carrier transport under broad spectrum illumination	other materials	Basic characterization tools	quantum dots, & wires,
S-8	SLO-1 Optical versus electrical tradeoffs	Photocurrent and Spectral response	3 rd generation thin film solar cells: DSSCs	Advanced characterization methods for device quality & defects	Intermediate band solar cells

	SLO-2	Optimization	Ideal diodes	QDSSCs, heterojunctions	Study of interfaces, recombination etc	Multiple exciton generation, hot carrier solar cells
S-9	SLO-1	Examples of semiconductors in PV	Real p-n diodes	3 rd generation thin film solar cells: organic PV	Basics of device modelling	Commercial status
	SLO-2	Device types in PV	Temperature effects	Hybrid, perovskite solar cells etc.	Simulation softwares	Hopes and challenges for thin film PV

Learning Resources	<ol style="list-style-type: none"> 1. Solanki C.S., "Solar photovoltaics - fundamentals, technologies and applications", 3rd edition, PHI Learning Pvt Ltd, New Delhi, India 2. Fonash S.J., "Solar Cell Device Physics", Academic, 2010 3. Moller H.J., "Semiconductors for Solar Cells", Artech House, 1993 4. Green M.A., "Third Generation Photovoltaics: Advanced Solar Energy Conversion", Springer, 2006 5. Rointan. F, Bunshah, "Hand Book of Deposition technologies for Thin Films and coatings by Science, Technology and Applications", Second Edition, Noyes Publications, 1993 					
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. D.K. Aswal, National Physical Laboratory, dkaswal@nplindia.org	1. Dr. Sudhakar Chandran, IIT Madras, csudhakar@iitm.ac.in	1. Dr. S Venkataprasad Bhat., SRMIST
2. Dr. S. Sudhakar, CSIR-CECRI, sudhakar@cecri.res.in	2. Dr. M. S. Ramachandra Rao, IIT Madras, msrrao@iitm.ac.in	2. Dr. P. Malar, SRMIST

Course Code	18NTO406T	Course Name	NANOTECHNOLOGY IN SOCIETAL DEVELOPMENT	Course Category	O	Open Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Department of Physics and Nanotechnology	Data Book / Codes/Standards			Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:		Learning		
CLR-1 :	Provide an insight into the fundamentals of social-economic implications of nanotechnology			Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)
CLR-2 :	Provide an insight into the fundamentals of ethical implications of nanotechnology					
CLR-3 :	Understand the legal risks related with the nanotechnology					
CLR-4 :	Understand the implications of nanotechnology in quality of life					
CLR-5 :	Understand the problems of governance of nanotechnology					
CLR-6 :	Explore the matters related to patents associated with nanotechnology					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:				
CLO-1 :	Address the socioeconomic implications of nanotechnology			2	80	75
CLO-2 :	Apply the knowledge of ethical implications pertaining to nanotechnology			2	80	70
CLO-3 :	Address the legal risks related with the nanotechnology			2	75	70
CLO-4 :	Improve the quality of life			2	80	75
CLO-5 :	Handle the issues related to patents associated with nanotechnology			2	80	70
CLO-6 :	Address the problems of governance of nanotechnology			2	80	75

Program Learning Outcomes (PLO)														
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
M	H	M	H	M	H	H	H	H	M	H	M	H	H	H
M	H	M	H	M	H	H	H	H	H	M	H	M	M	M
M	M	M	H	M	H	H	M	H	H	M	H	H	H	H
H	H	M	H	M	H	H	H	H	H	M	H	H	H	H
M	M	H	H	M	M	M	H	M	H	H	H	H	H	H
M	M	M	H	M	H	H	H	H	M	H	M	H	M	H

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Knowledge and Scientific Understanding of Nature	National Nanotechnology Initiative	Nanotechnology, Education, and the Fear of Nanobots	Societal Implications of Nanotechnology (Public Perceptions of Nanotechnology
	SLO-2	Industrial Manufacturing, Materials and Products	The Age of Transitions	Mathematical Challenges in Nanoscience and Nanotechnology	Socio-economic Research on Nanoscale Science and Technology: A European Overview and Illustration	Public Awareness of Nanotechnology
S-2	SLO-1	Medicine and the Human Body	Technological Implications of Nanotechnology: Why the Future Needs Us	Implications of Nanotechnology for the Workforce	Nanotechnology and Unintended Consequences	Public interaction research
	SLO-2	Sustainability: Agriculture, Water, Energy, Materials, and Clean Environment	Don't Count Society Out - A Response to Bill Joy	Societal Impacts of Nanotechnology in Education and Medicine	A Cultural Ecology of Nanotechnology	Nanotechnological risks
S-3	SLO-1	Space Exploration	National Needs Drivers for Nanotechnology	Technological and Educational Implications of Nanotechnology: Infrastructural and Educational Needs	Envisioning and Communicating Nanotechnology to the Public	Assessment of Nanotechnological risks
	SLO-2	National Security	Nanotechnology and Societal Transformation	Dynamics of the Emerging Field of Nanoscience	Vision, innovation, and policy	Importance of Risk communication
S-4	SLO-1	Moving into the Market	Focus on Economic and Political Implications of Potential Technology	Focus on Medical, Environmental, Space Exploration and National Security Implications	Challenges for government and universities	Problems in Risk communication
	SLO-2	The Interactive Process of Innovation and Diffusion	Impact of Nanotechnology on the Chemical and Automotive Industries	Challenges and Vision for Nanoscience and Nanotechnology in Medicine: Cancer as a Model	Environmental Impacts of Nanomaterials	Nanotechnology's social impacts
S-5	SLO-1	Unintended and Second-order Consequences	Information Technology Based on a Mature Nanotechnology: Some Societal Implications	Nanotechnology in Medicine	Nanoparticle Toxicity and risk	A preliminary analysis of nanotechnology in the media
	SLO-2	Ethical Issues and Public Involvement in Decision Making	Societal Implications of Scaling to Nanoelectronics	Lifecycle/Sustainability Implications of Nanotechnology	Social impacts of nano biotechnology issues	Nanoscience and engineering - Public enaqement

S-6	SLO-1	Education of Nanoscientists, Nanotechnologists, and Nanofabrication Technicians	Future Implications of Nanoscale Science and Technology: Wired Humans, Quantum Legos, and an Ocean of Information	Implications of Nanotechnology for Space Exploration	Problems of governance of nanotechnology	Nanophobia – Fear of Nanotechnology
	SLO-2	Education of Social Scientists	Implications of Nanotechnology in the Pharmaceuticals and Medical Fields	Security Aspects of Nanotechnology	Negotiations over quality of life in the nanotechnology initiative. Governance	Public Engagement with nanotechnology
S-7	SLO-1	Social Science Research Approaches and Methodologies	We've Only Just Begun	Focus on Social, Ethical, Legal, and Cultural Implications	Technological revolutions and the limits of ethics in an age of commercialization	Nanotechnology: moving beyond risk
	SLO-2	Institutional Infrastructure for Societal Implications Research	An Economist's Approach to Analyzing the Societal Impacts of Nanoscience and Nanotechnology	Social Science Research Methods for Assessing Societal Implications of Nanotechnology	Regulatory structures and society	Communication streams and nanotechnology: interpretation of a nanotechnology
S-8	SLO-1	Other Measures	The Strategic Impact of Nanotechnology on the Future of Business and Economics	Ethical Issues in Nanotechnology	Nanotechnology and social trends	Individual perspectives of nanotechnology
	SLO-2	Specific Areas for Research and Education Investment	Nano-Science and Society: Finding a Social Basis for Science Policy	Social Acceptance of Nanotechnology	Integrative Technology	The case of Cold Fusion
S-9	SLO-1	Recommendations to Organizations	Focus on Science and Education Implications	Social, Ethical and Legal Implications of Nanotechnology	Institutionalizing Multi-Disciplinary Engagement	The case of Recombinant DNA
	SLO-2	With an Eye to the Future	Implications of Nanoscience for Knowledge and Understanding	Envisioning Life on the Nano-Frontier	Nano revolution implications for the artist	Historical comparisons - for anticipating public reactions to nanotechnology

Learning Resources	1. Mihail C.R., and William S.B., "Nanotechnology: societal implications", Springer publication, 2011 (978-1-4020-5432-7 (e-book)) 2. Ronald Sandler, "Nanotechnology the Social & Ethical Issues", Woodrow Wilson, 2009	3. Mihail C. Roco and William Sims Bainbridge, "Societal Implications of Nanoscience and Nanotechnology", National Science Foundation, 2001 (978-0-7923-7178-6)
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Evaluate Create	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 5 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
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1. Mr.Ajay Kumar, Avansa Technology and services, India ajaykumar@avansa.co.in	1. Dr. Hirendra N Ghosh, Institute of Nanoscience and Technology, Punjab, hghosh@inst.ac.in	1. Dr. C.Gopalakrishnan, , SRMIST
2. Dr.Tarvi Sharma ,Nanoshel LLC, Chandigarh, India, tanvisharma@nanoshel.com	2. Dr. Asish Pal, Institute of Nanoscience and Technology, Punjab, apal@inst.ac.in	2. Dr.P.Sivakumar, SRMIST

Course Code	18NT0407T	Course Name	POLYMER ENGINEERING			Course Category	O	Open Elective				L	T	P	C									
											3	0	0	3										
Pre-requisite Courses		Nil		Co-requisite Courses		Nil		Progressive Courses		Nil														
Course Offering Department		Nanotechnology			Data Book / Codes/Standards			Nil																
Course Learning Rationale (CLR):			The purpose of learning this course is to:				Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Acquire basic knowledge about the structure and property of polymers				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2 :	Impart chemistry aspects on various polymer materials							Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3		
CLR-3 :	Acquaint with various compounding ingredients and mixing equipments							H	M	H	H	H	M	M	H	H	H	M	H	H	H	H	H	H
CLR-4 :	Understand the principles behind the elasticity of the polymers							H	M	M	H	M	M	M	H	M	H	M	H	M	M	M	M	M
CLR-5 :	Gain knowledge about reinforcements and effect of nanofillers							H	M	H	H	H	H	H	M	H	H	H	H	H	H	H	H	H
CLR-6 :	Describe rheological behavior with different modifiers							H	M	H	H	H	M	M	H	M	H	M	H	H	H	H	H	H
Course Learning Outcomes (CLO):			At the end of this course, learners will be able to:				2	80	75	H	M	M	H	H	M	M	H	H	M	H	H	M	H	
CLO-1 :	Apply the engineering principles underlying the processing of polymer raw materials				2	80	75	H	M	M	H	H	M	M	H	H	M	H	H	M	M	M		
CLO-2 :	Extend and apply the knowledge of polymers to materials science and engineering				2	80	70	H	M	M	H	M	M	M	H	M	H	M	M	M	M	M		
CLO-3 :	Identify different fillers as reinforcements				2	75	70	H	M	H	H	H	H	H	M	H	H	H	H	H	H	H		
CLO-4 :	Illustrate the working of moulding and extrusion techniques				2	80	75	M	H	H	M	H	H	H	H	H	H	M	H	H	H	H		
CLO-5 :	Evaluate the mechanical behavior of polymers				2	80	70	H	M	H	H	H	M	M	H	M	H	M	H	H	H	H		
CLO-6 :	Enhance knowledge about the various composite materials				2	80	75	H	M	M	H	H	M	M	H	H	H	M	H	H	M	H		
Duration (hour)		9		9		9		9		9		9												
S-1	SLO-1	Basics and chemistry of polymeric Materials		Mechanical behavior of Polymers		Polymer Viscoelasticity and Rheology		Reinforced Polymers and Composites		Elements of Design														
	SLO-2	Historical developments in polymeric materials		Deformation		Definition of elastomers		Reinforced plastics		Engineering thermoplastics														
S-2	SLO-1	Monomer & functionality		Fracture in polymers		Requirements of polymer to be elastomer		Nanofillers and reinforcements		Thermosets and composites														
	SLO-2	Oligomer		Crack growth		Nature of viscoelasticity		Effect of reinforcements like calcium carbonate, dolomite, silica glass		Compression moulds : positive, semi-positive														
S-3	SLO-1	Polymer structure		Tensile strength,		Definition of elastomers		Fibrous reinforcements (inorganic and organic)		Flash mould with horizontal and vertical flash														
	SLO-2	Methods of synthesis		Flexural strength		Classifications of elastomers		Glass fiber and boron fiber		Injection moulds : Two plate and three plates types														
S-4	SLO-1	Addition polymerization		Impact resistance		Stress relaxation		Carbon fiber and aramide fibers		Joining and fastening														
	SLO-2	Condensation polymerization		Percentage elongation		Relaxation and retardation times		Compression moulding		Post extrusion techniques														
S-5	SLO-1	Co- polymers		Griffin theory		The time - temperature superposition principle		Classification and characteristics of composite materials		Metallization														
	SLO-2	Cross linked polymers		Tear test		Dynamic properties		Fibrous composite materials		electroplating														
S-6	SLO-1	Crosslinking plasticizers and fillers		Fatigue and wear		Zener model		Laminated composite materials		Stamping														
	SLO-2	Crystallinity		Hardness		Polymer melt viscosity		Particulate composite materials		Welding and bonding														
S-7	SLO-1	Glass transition temperature		Compressive strength		Plasticizers		Combinations of composite materials		printing and painting on plastics														
	SLO-2	Degree of polymerization		Time dependent properties		Lubricants		Strength of composites		Cross-linking of thermoplastics materials														
S-8	SLO-1	Classification of polymers		Creep		Polymer Rheology		Failure modes of long, fibre composites		Cellular plastics														
	SLO-2	Molecular weight		Effect of weathering		Rheological concepts of polymer solutions and melts		Axial tensile failure		Compound development														
S-9	SLO-1	Molecular weight distribution.		Stress-strain behavior of polymers		Degradation plasticization		Transverse tensile failure, shear failure		Principles of mixing														
	SLO-2	Determination of number and average molecular weight		Mechanical behavior of biomedical polymers		Various rheology modifiers		Applications of fiber reinforced polymer composites		Rubbers, designing for strength														

Learning Resources	1. Sperling L.H., <i>Introduction to Physical Polymer Science</i> , Wiley inter science, 4 th Edition, 2006	3. Hull D., and Clyne W., <i>An Introduction to Composite Materials</i> , Cambridge University Press, 2 nd Edition, 1996
	2. Mc Crum, <i>Principles of polymer Engineering</i> , 2 nd Edition, Oxford, 2001	4. Jones R.M., <i>"Mechanics of Composite Materials"</i> , Taylor & Francis, 2 nd Edition, 1999

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Understand	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Apply										
Level 3	Analyze	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Evaluate										
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. Pankaj Poddar, National Chemical Laboratory, p.poddar@ncl.res.in	1. Dr. G. Arthanareeswaran, NIT Trichy, arthanareeg@gmail.com	1. Dr. N. Angeline Little Flower, SRMIST
2. Dr. P. Sudhakara, CLRI – CSIR, Jalandhar, sudhakarp@clri.res.in	2. Dr. A. Kannan, IIT Madras, kannan@iitm.ac.in	2. Dr. C. Siva, SRMIST

Course Code	18NTQ408T	Course Name	INDUSTRIAL NANOTECHNOLOGY	Course Category	O	Open Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Nanotechnology	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 : Understand various nanotechnology techniques and materials from the point of view of the industry		1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 : Understand the practical and business aspects of nanotechnology		Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 : Understand the concept of self-assembly of carbon nanostructures and various other materials and their applications		Expected Proficiency (%)	Problem Analysis
CLR-4 : Gain knowledge on material in the nanoscale which can be use in Electronics, Medical, Textiles Industry		Expected Attainment (%)	Design & Development
CLR-5 : Acquire knowledge on physical properties of nanostructured materials and their size and dimensionality dependence			Analysis, Design, Research
CLR-6 : Acquire knowledge on the measurement techniques at the nanoscale			Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 : Elucidate on advantages of nanotechnology based applications in each industry		2 80 75	H M H H H M M H H H M H H H H
CLO-2 : Provide instances of contemporary industrial applications of nanotechnology		2 80 70	H M M H M M M H M H M H M M M M
CLO-3 : Provide an overview of future technological advancements and increasing role of nanotechnology in each industry		2 75 70	H M H H H H H M H H H H H H H H
CLO-4 : Apply the techniques for fabrication of small-scale devices such as micro/nano electromechanical systems etc.		2 80 75	M H H M H H H H H H M H H H H H
CLO-5 : Utilize the knowledge on nanomaterial to open a startup company		2 80 70	H M H H H M M H M H M H H H H H
CLO-6 : Apply the techniques for fabrication of nanofiber on advance textiles Industry		2 80 75	H M M H H M M H H H M H H M H H

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Nano electrical	Nanoparticles in bone substitutes	Background of TiO ₂ as a semiconductor photocatalyst	Applications of nanotechnology in the agriculture
	SLO-2	Nano electronic devices and its advantages	Nanoparticles in dentistry	Photocatalytic mechanism and general pathway	Agriculture chemicals
S-2	SLO-1	Data storage	Tissue engineering	Photocatalytic kinetics	Nanomaterials in plant protection
	SLO-2	Memory devices	Regenerative medicine	TiO ₂ nanoparticles for water purification	Diagnosis and control of plant diseases
S-3	SLO-1	Micromechanical systems	Tissue engineering and nanotechnology	Photocatalytic degradation of specific waterborne pollutants	Potential of nano-fertilizers
	SLO-2	Nanoelectromechanical systems	Incorporated scaffolds for tissue engineering	Nanomaterials in water treatment	Nano-fertilizers: Nutritional value and health
S-4	SLO-1	Lasers	Nanorobotics in surgery	Origin of arsenic in groundwater, Health impacts of arsenic	Applications of nanotechnology in food industry
	SLO-2	Use of lasers in lighting and displays	Role of nanoparticles in drug delivery	Nanoparticles for treatment of arsenic	Protein nanostructures
S-5	SLO-1	Rechargeable batteries	Nanoparticles in targeted drug delivery	Mechanism of treatment methods of arsenic-contaminated water	Engineered nanoparticles in food
	SLO-2	Nanostructured electrodes	Metal oxide nanocarriers for drug delivery	Treatment of arsenic using nanoparticles other than TiO ₂	Silica (SiO ₂) and silicates nanoparticles in food
S-6	SLO-1	Basic concepts of fuel cells	Silica-based nano drug delivery	CNTs in water treatment technology	Nanomaterials in active packaging for food preservation
	SLO-2	Different types of fuel cells	Polymer based nanomaterials for drug delivery	Functionalized graphene for removal of contaminations and water treatment	Barrier nanomaterials for food packaging
S-7	SLO-1	Photovoltaic cells characterization	Cancer diagnostics: nanotechnology	Gas-sensor: Techniques used for gas-sensor	Nano-enabled indicators of food quality and safety

	SLO-2	Nanomaterials and different types of photovoltaic cells	Cancer therapy: nanotechnology	Conduction mechanism in semiconducting sensing films	Challenges of using nanotechnology in agriculture and food sectors	Nanotechnology: Self-Cleaning textile
S-8	SLO-1	Electric double layer capacitors	Nano-sensor in cancer	Metal-oxide based gas-sensor devices	Nanomaterials in active packaging for food preservation	Safety evaluation of nanomaterials in cosmetic products
	SLO-2	Capacitance versus pore size	Nanoparticle probes and molecular imaging in Cancer	Classification of semiconductor sensors	Principles of involved nano-enabled sensing	Nanomaterial in cosmetic: determination of physicochemical properties
S-9	SLO-1	Characterization of nanoparticle coatings	Nanomedicine-based use of siRNA in cancer	Challenges and opportunities in solid state sensors	Nanocomposite with antimicrobial properties	Cosmetic formulation: TiO ₂ and ZnO Nanoparticles
	SLO-2	Nanoparticle coatings:Electrical and electronic applications and nanoparticle coatings for electrical products	Magnetic Nanoparticles and cancer	Small dimensional toxic gas sensor for air-quality monitoring	Nanotechnology for intelligent packaging as food freshness and safety monitoring solution	Nanotechnology in shampoos, hair-conditioners: Hair follicle targeting solution

Learning Resources	1. Kenneth E.G., Craig R.H., Cato T.L., Lakshmi S.N., <i>Biomedical Nanostructures</i> , John Wiley & Sons Inc., 2008 2. P. J. Brown, K. Stevens, <i>Nanofibers and Nanotechnology in Textiles</i> , Woodhead Publishing Limited, Cambridge, 2007 3. C. M. Hussain, A. K. Mishra, <i>Nanotechnology in Environmental Science</i> , Volume 2, John Wiley & Sons, 2018	4. M. A. Axelos, M. H. Van de Voorde, <i>Nanotechnology in Agriculture and Food Science</i> , John Wiley & Sons, 2017 5. M. H. Fulekar, <i>Nanotechnology: Importance and Applications</i> , IK International Publishing House Pvt. LTD, 2010
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. Hemant Dixit, Global Foundaries, USA, aplahemant@gmail.com	1. Dr. Pradeep T, IIT Madras, pradeep@iitm.ac.in	1. Dr. Debabrata Sarkar, SRMIST
2. Dr. Krishna Surendra Muvvala, Saint Gobain Research India, India, Krishna.muvvala@saintgobain.com	2. Dr. M. S. Ramachandra Rao, IIT Madras, msrrao@iitm.ac.in	2. Dr. Senthilkumar E, SRMIST

ACADEMIC CURRICULA

Professional Core Courses

Regulations - 2018



SRM INSTITUTE OF SCIENCE AND TECHNOLOGY

(Deemed to be University u/s 3 of UGC Act, 1956)

Kattankulathur, Kancheepuram, Tamil Nadu, India

ACADEMIC CURRICULA

Professional Core Courses

AEROSPACE ENGINEERING

Regulations - 2018



SRM INSTITUTE OF SCIENCE AND TECHNOLOGY

(Deemed to be University u/s 3 of UGC Act, 1956)

Kattankulathur, Kancheepuram, Tamil Nadu, India

Course Code	18ASC301J	Course Name	COMPRESSIBLE AERODYNAMICS	Course Category	C	Professional Core	L	T	P	C
							3	0	2	4

Pre-requisite Courses	18ASC202J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Aerospace Engineering	Data Book / Codes/Standards	Gas tables		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 : Identify the different wave types and wave propagation		1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 : Evaluate the change in properties across shock waves and optimize the supersonic vehicle design		Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 : Evaluate the change in properties across expansion waves		Expected Proficiency (%)	Problem Analysis
CLR-4 : Evaluate and optimize the nozzle flow characteristics.		Expected Attainment (%)	Design & Development
CLR-5 : Design and Evaluate the duct flow with heat transfer and frictional effect.			Analysis, Design, Research
CLR-6 : Design and optimize the supersonic nozzle			Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 : Understand the properties of different waves in supersonic flow		1 90 80	H M M M - - - - - M - H -
CLO-2 : Analyze the properties of shock wave		2 80 75	H H H H - - - - - H - H -
CLO-3 : Analyze the properties of expansion wave		3 80 75	H H H H H - - - - H - H -
CLO-4 : Analyze the flow through nozzle		3 70 60	H H H H H - - - - H - H -
CLO-5 : Analyze the heat transfer and frictional effect in flow		3 80 75	H H H H H - - - - H - H -
CLO-6 : Analyze the compressibility effects and design the supersonic nozzle		2 70 60	H H H H H - - - - H - H -

Duration (hour)	15	15	15	15	15
S-1	SLO-1 Introduction to compressible flow	Normal shock wave properties – Mach number relation	Multiple shock system	Numerical problems on Nozzle flow relations	Fanno curve
	SLO-2 Basic thermodynamic concepts	Normal shock wave properties – density relation	Numerical problems on multiple shock systems	Numerical problems on Nozzle flow relations	Numerical problems on Fanno flow
S-2	SLO-1 Basic thermodynamic equations	Normal shock wave properties – pressure relation	The propagating shock wave	Numerical problems on Nozzle flow relations	Numerical problems on Fanno flow
	SLO-2 Momentum and Energy equations for compressible fluid flow	Normal shock wave properties – temperature relation	Numerical problems on propagating shock wave	Rayleigh flow equations – static properties	Numerical problems on Fanno flow
S-3	SLO-1 Wave propagation	Normal shock wave properties – entropy change	Governing equation of Prandtl-meyer expansion waves	Rayleigh flow equations – stagnation properties	Velocity potential equation for compressible flow
	SLO-2 Shock formation	Hugoniot equation	Expression of Prandtl –meyer function	variation of flow properties for subsonic flow	Small perturbation theory
S 4-5	SLO-1 Lab 1: Study of various types of Supersonic wind tunnel.	Lab 4: Calibration of supersonic wind tunnel	Lab 7: Visualization of shock wave pattern on ramp model using Schlieren flow visualization technique	Lab 10: Visualization of shock wave pattern on Diamond Airfoil using Schlieren flow visualization technique	Lab 13: Investigation of intersection of right and left running shock waves for various deflection angles using Schlieren flow visualization
	SLO-2			variation of flow properties for supersonic flow	Small perturbation theory
S-6	SLO-1 types of waves	Numerical problems on normal shock	Numerical problems on expansion waves	Critical reference states	Linearized pressure coefficient
	SLO-2 Speed of sound derivation	Numerical problems on normal shock	Numerical problems on expansion waves	Rayleigh curve	Linearized pressure coefficient
S-7	SLO-1 Change in entropy relation	Numerical problems on normal shock	Shock Expansion theory – flat plate	Numerical problems on Rayleigh flow	Prandtl-Glauert compressibility correction
	SLO-2 Numerical problems on thermodynamic concepts	Oblique shock properties	Numerical problems on shock expansion theory	Numerical problems on Rayleigh flow	Supersonic linearized theory
S-8	SLO-1 Isentropic relations	Θ - β -M relation and graph	Shock Expansion theory – Diamond airfoil	Numerical problems on Rayleigh flow	Application of Supersonic linearized theory
	SLO-2 Numerical problems on isentropic relations	Supersonic flow over wedges and cones	Numerical problems on shock expansion theory	Numerical problems on Rayleigh flow	

S 9-10	SLO-1	Lab 2: Study of various Supersonic flow visualization techniques and its applications.	Lab 5: Mach number distribution of different area ratio C-D nozzles	Lab 8: Visualization of shock wave pattern on wedge model using Schlieren flow visualization technique	Lab 11: Investigation of supersonic flow over different aircraft/ missile models using Schlieren flow visualization technique	Lab 14: Experimental study of supersonic jet
	SLO-2					
S-11	SLO-1	Isentropic relations – stagnation state	Shock polar	Nozzle flow relations: Area – velocity	Fanno flow- equations	Numerical problems on linearized theory
	SLO-2	Numerical problems on isentropic relations	Shock reflections	Supersonic nozzle and diffuser	Fanno flow- equations	Numerical problems on linearized theory
S-12	SLO-1	Isentropic relations – critical state	Shock interactions	Nozzle flow relations: Area – Mach number	variation of flow properties with duct length	Introduction to Method of characteristics
	SLO-2	Numerical problems on isentropic relations	Numerical problems on oblique shock	Nozzle flow relations: Maximum mass flow rate	variation of flow properties for subsonic flow	Method of characteristics
S-13	SLO-1	Characteristic Mach number	Numerical problems on oblique shock	Variation of Pressure and Mach number along the C-D nozzle	variation of flow properties for supersonic flow	Application of Method of characteristics
	SLO-2	Numerical problems on isentropic relations	Numerical problems on oblique shock reflections	Under expansion and over expansion nozzle	Critical reference states	Application of Method of characteristics
S 14-15	SLO-1	Lab 3: Study of SRM supersonic wind tunnel and its instrumentations.	Lab 6: Investigation of starting normal shock wave movement inside Convergent Divergent Nozzle.	Lab 9: Verification of “Three dimensional relieving effect”.	Lab 12: Investigation of detached shock wave pattern using Schlieren flow visualization technique	Lab 15: Noise measurement in supersonic jet
	SLO-2					

Learning Resources	1. Rathakrishnan, E., “Gas Dynamics”, Prentice Hall India Learning Private Limited, 6th edition, Delhi, India, 2016. 2. Anderson J. D., Jr., “Modern Compressible Flow with Historical Perspective,” McGraw Hill Publishing Co., 3rd edition, 2017	3. Shapiro, A.H., “The Dynamics and Thermodynamics of Compressible Fluid Flow (Vol I and Vol II)”, Ronald Press, 1953. 4. Zucker, R. D., Biblarz, O., “Fundamentals of Gas Dynamics”, Wiley-Blackwell; Third edition (2019) 5. Yahya, S. M., “Fundamentals of Compressible Flow with Aircraft and Rocket Propulsion”, New Age International Publishers; Sixth edition (2018)
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Dr Manishankar C, Senior Scientist, CSIR - National Aerospace Laboratories Bangalore.	1. Dr. Arun Kumar Perumal, Mechanical Eng, IIT Jammu, arun.perumal@iitjammu.ac.in	Mr. R. Mohamed Arif, SRMIST.
		Dr. K. K. Bharadwaj, SRMIST.

Course Code	18ASC302T	Course Name	FLIGHT DYNAMICS - I	Course Category	C	Professional Core	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18ASC202J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Aerospace Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Program Learning Outcomes (PLO)														
					Learning														
					1	2	3	1	2	3	4	5	6	7	8	9	10	11	12
					Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning
CLR-1 :	Understand the art of application of aerodynamics knowledge into an aircraft							H	M	M	H	L	-	H	-	-	-	-	H
CLR-2 :	Know the performance of different powerplants at different flight conditions							M	M	M	M	L	-	H	-	M	-	-	H
CLR-3 :	Know the various performance parameters of an airplane							M	H	M	H	M	-	H	-	-	-	-	H
CLR-4 :	Learn optimizing different performance parameters for maximizing range, endurance and fuel efficiency							M	M	M	M	L	-	L	-	M	-	-	H
CLR-5 :	Learn role of performance parameters in various maneuvers of the airplane							M	M	H	H	M	M	H	M	H	-	M	H
CLR-6 :	Learn experimental determination of various performance parameters of a real airplane by flight testing							M	H	M	M	M	-	-	-	M	M	-	H
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																	
CLO-1 :	Estimate and optimize drag polar of an aircraft				3	85	90												
CLO-2 :	Select optimal powerplant for the required airplane with the desired performance				3	80	85												
CLO-3 :	Indicate the different flight techniques for optimized steady and accelerated flight performance				3	75	80												
CLO-4 :	Perform basic calibration of flight instrument data				3	50	60												
CLO-5 :	Perform conceptual design of any type of airplane				3	70	70												
CLO-6 :	Determine the drag polar of a real airplane with real flight testing				3	00	80												

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Forces and moments acting on a vehicle in flight	Thrust and propulsive efficiency of air breathing engine	Equation of motion for steady level flight	Range -Definition and conditions for maximum range for jet driven aircraft	Flight instruments- Air Data systems
	SLO-2	Coordinate systems	Thrust and propulsive efficiency of rocket engine	Conditions for maximum velocity in steady level flight	Range -Definition and conditions for maximum range for propeller driven aircraft	Altitude and speed definitions
S-2	SLO-1	Equations of motion of a rigid flight vehicle	Trade-off between thrust and propulsive efficiency	Conditions for minimum in steady level flight	Endurance – Definition and conditions for maximum endurance for jet driven airplane	Air speed indicator- construction and working
	SLO-2	Solving Problems	Solving Problems	Solving problems	Endurance – Definition and conditions for maximum endurance for propeller driven airplane	Air speed indicator- speed calibration
S-3	SLO-1	International Standard Atmosphere and various layers in ISA	TSFC and BSFC	Solving problems	Solving problems	Solving air speed calibration problems
	SLO-2	Derivation of hydrostatic equation	Variation of Thrust/Power and SFC with respect to velocity and altitude for reciprocating engine	Power required vs velocity – Graphical approach and analytical approach	Solving problems	Solving air speed calibration problems
S-4	SLO-1	Derivation of Pressure, Temperature and density in troposphere	The propeller – variation of propulsive efficiency with advance ratio	Power available and maximum velocity for propeller driven and jet driven aircraft	Accelerated flight- Level turn- Equations of motion	Altimeter- construction and working
	SLO-2	Solving Problems in Gradient layer	Constant speed propellers	Minimum velocity- Stall and high lift devices	Level turn- conditions for turn radius and turn rate	Altimeter- altitude corrections
S-5	SLO-1	Derivation of Pressure, Temperature and density in Stratosphere	Variation of Thrust/Power and SFC with respect to velocity and altitude for turbojet engine	Aerodynamic relations associated with maximum efficiency conditions	Level turn- constraints on load factor, Constraints on velocity,	Solving problems- altimeter
	SLO-2	Solving Problems in Iso thermal layer	Solving Problems	Solving problems	Level turn- calculation of minimum turn radius and minimum turn rate.	Rate of climb indicator – construction and working

S-6	SLO-1	Various types of drags acting on an airplane	Variation of Thrust/Power and SFC with respect to velocity and altitude for turbofan engine	Rate of climb- equation of motion	Solving problems	Mach meter- construction and working
	SLO-2	Methods to minimize various drags	Solving Problems	Rate of climb- Graphical approach and hodograph	Solving problems	Angle of attack indicator- construction and working
S-7	SLO-1	Interference Drag and methods to minimize it Drag polar of vehicles in subsonic speed	Variation of Thrust/Power and SFC with respect to velocity and altitude for turboprop engine	Analytical approach for maximum climb angle	Pull-up and pull-down maneuvers	Flight determination of drag polar- introduction
	SLO-2	Transonic Drag Divergence	Solving Problems	Analytical approach for maximum rate of climb	V-n diagram and its significance	Flight determination of drag polar- speed power method
S-8	SLO-1	Wave drag and methods to minimize it	Thrust available characteristics of different engines	Absolute ceiling and service ceiling	Takeoff performance – ground roll	Flight determination of drag polar- incremental drag method
	SLO-2	Solving Problems	Selection of Powerplant	Solving problems	Estimation of takeoff distance	Flight determination of drag polar- prop feathered sinks method
S-9	SLO-1	Drag polar of vehicles in supersonic speeds	Thrust required vs velocity- Graphical approach	Gliding flight- Equation of motion, glide hodograph	Landing performance – Estimation of landing distance	Flight determination of drag polar- incremental power method
	SLO-2	Drag polar of vehicles in hypersonic speeds	Thrust required vs velocity- Analytical approach	Minimum sink rate and minimum glide path angle conditions	Methods to minimise landing distance	Solving problems

Learning Resources	1. Perkins, C. D., and Hage, R. E., "Airplane Performance, Stability and Control," Wiley Toppan, 1974	3. Nelson, R.C., "Flight Stability and Automatic Control", McGraw Hill, 1989.
	2. John D. Anderson, "Aircraft Performance and Design", McGraw-Hill, 1999	4. McCormik, B. W., "Aerodynamics, Aeronautics and Flight Mechanics", John Wiley, 1995.

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. Raja S, CSIR-NAL, Bangalore, raja@nal.res.in	1. Dr. K. M. Parammasivam, Madras Institute of Technology, Chennai, mparams@mitindia.edu	1. Mr. M. Vignesh Kumar, SRMIST
2. Wg.Cdr K.Manoharan (Retd), Blue Dart Aviation Ltd., manoharank@bluedart.com	2. Dr. P. K Dash, Nitte Meenakshi Institute of Technology, Bangalore, drpdash@gmail.com	2. Mr. K. Allwyn, SRMIST

Course Code	18ASC303J	Course Name	ROCKET PROPULSION	Course Category	C	Professional Core	L	T	P	C
							3	0	2	4

Pre-requisite Courses	18ASC203T	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Aerospace Engineering	Data Book / Codes/Standards	Gas Tables		

Course Learning Rationale (CLR):		The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)																	
CLR-1 :	Understand the basic principles of rocket propulsion system		1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15			
CLR-2 :	Understand the basic performance parameters of chemical propellants.		Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3			
CLR-3 :	Design the Solid Propellant Rocket					H	-	H	-	-	-	-	-	-	-	-	-	-	-	M	-	M	
CLR-4 :	Design the Liquid Propellant Rocket					H	H	H	-	-	-	-	-	-	-	-	-	-	-	-	M	-	M
CLR-5 :	Understand the working of advanced rocket propulsion techniques					H	H	-	-	-	-	-	-	-	-	-	-	-	-	-	M	M	M
CLR-6 :	Understand Rocket propulsion system, design, advanced propulsion system and its applications					H	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-	H	-
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:	2	85	75	H	-	H	-	-	-	-	-	-	-	-	-	M	-	M			
CLO-1 :	Design a multistage rocket and analyze its performance		2	85	75	H	H	H	-	-	-	-	-	-	-	-	-	-	M	-			
CLO-2 :	Analyze the performance parameter and choose the chemical propellant		2	85	75	H	-	H	H	-	-	-	-	-	-	-	-	M	M	M			
CLO-3 :	Analyze the Solid Propellant Rocket		2	85	75	H	H	-	-	-	-	-	-	-	-	-	-	M	M	M			
CLO-4 :	Analyze the Liquid Propellant Rocket		2	85	75	H	H	-	-	-	-	-	-	-	-	-	-	M	M	M			
CLO-5 :	Understand the working of advanced rocket propulsion techniques		2	85	75	H	-	-	-	-	-	-	-	-	-	-	-	-	H	-			
CLR-6 :	Have a detailed knowledge of Rocket propulsion system, design, advanced propulsion system and its applications		2	85	75	H	H	H	H	-	-	-	-	-	-	-	-	M	M	M			

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)
CLO-1 :	Design a multistage rocket and analyze its performance	2	85	75
CLO-2 :	Analyze the performance parameter and choose the chemical propellant	2	85	75
CLO-3 :	Analyze the Solid Propellant Rocket	2	85	75
CLO-4 :	Analyze the Liquid Propellant Rocket	2	85	75
CLO-5 :	Understand the working of advanced rocket propulsion techniques	2	85	75
CLR-6 :	Have a detailed knowledge of Rocket propulsion system, design, advanced propulsion system and its applications	2	85	75

Duration (hour)	15	15	15	15	15
S-1	SLO-1 SLO-2	History and evolution of rockets	Introduction of chemical propellant	Introduction of Solid Propellant Rocket	Introduction of Liquid Propellant Rocket
S-2	SLO-1 SLO-2	Rocket working principle	Molecular mass	Classifications of Solid Propellant Rocket	Classifications of Liquid Propellant Rocket
S-3	SLO-1 SLO-2	Rocket equation	Specific Heat	Hardware components and its functions	Hardware components and its functions
S-4	SLO-1 SLO-2	Numerical Problems on Rocket equation	specific heat ratio	Mechanism of burning	Propellant feed systems
S-5	SLO-1 SLO-2	Lab 1: Study of Piston Engines	Stoichiometric ratio	Pressure feed system	Arc-jet thruster
S-6	SLO-1 SLO-2	Mass ratio of rocket	Lab 4: Determination of convective heat transfer coefficient over a flat plate by forced convection	Resistojet thruster	Hybrid Rocket motor fuel grain preparation
S-7	SLO-1 SLO-2	Numerical Problems on rocket parameters	Lab 7: Performance test on a propeller	Turbo pump feed system	Electro-static propulsion system
S-8	SLO-1 SLO-2	Rocket Nozzles and its Classifications	Ignition system	Numerical Problems on feed system	Electro-magnetic propulsion system
S-9	SLO-1 SLO-2	Nozzle Performance	Igniter types	Injector	Ion thruster
S-10	SLO-1 SLO-2	Nozzle area ratio- Mass flow rate	Propellant grain	Types of injector	Hall Effect Thruster
S-11	SLO-1 SLO-2	Numerical Problems on nozzle	configuration and applications of propellant grain	Numerical Problems on injector	Magneto plasma dynamic thruster
S-12	SLO-1	Characteristic velocity and Thrust coefficient	Burn rate	Lab 11: Thrust measurement on a prepared solid propellant	Pulsed Plasma Thruster
	SLO-2	Numerical Problems on nozzle performance	Factors influencing burn rates	Lab 14: Regression rate measurement of hybrid rocket motor	
	SLO-1	Performance parameters and Efficiencies of rocket	Lab 5: Characteristic plots of a free jet through a non-circular orifice	Thrust chamber	Nuclear rockets
	SLO-2	Classifications of liquid propellant	Composition and processing	Cooling of Thrust chamber	
	SLO-1	Design of Solid Propellant rocket	Liquid propellants	Cryogenic propulsion system	Solar Propulsion system
	SLO-2		Action time and burn time		

	SLO-2	Numerical Problems on Performance parameters and Efficiencies of rocket	Storability of liquid propellant		Special features of cryogenic systems	
S-13	SLO-1	Staging and Clustering of rocket	Numerical Problems on chemical propellant	Numerical Problems on Solid Propulsion system	Numerical Problems on Liquid Propulsion system	Numerical problems
	SLO-2	Numerical Problems on Staging and Clustering of rocket				
S 14-15	SLO-1	Lab 3: Determination of convective heat transfer coefficient over a flat plate by natural convection	Lab 6: Characteristic plots of a wall jet through a non-circular orifice	Lab 9: Solid Rocket motor propellant preparation	Lab 12: Study of Liquid propulsion system	Lab 15: Thrust measurement of a hybrid rocket
	SLO-2					

Learning Resources	<ol style="list-style-type: none"> 1. Ramamurthi.K, "Rocket propulsion", Laxmi Publications, India, Second edition 2016. 2. George P. Sutton, Oscar Biblarz, "Rocket propulsion elements", Wiley India Pvt Ltd. eighth Edition 2010. 3. Philip Hill and Carl Peterson, "Mechanics and thermodynamics of propulsion", Pearson India, second edition 2010. 4. Stephen R. Turns, "An Introduction to Combustion: Concepts and Applications", McGraw-Hill Education, third Edition, 2011.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20 %	20 %	15 %	15 %	15 %	15 %	15 %	15 %	15 %	15 %
	Understand										
Level 2	Apply	20 %	20 %	20 %	20 %	20 %	20 %	20 %	20 %	20 %	20 %
	Analyze										
Level 3	Evaluate	10 %	10 %	15 %	15 %	15 %	15 %	15 %	15 %	15 %	15 %
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. S. Raja, Senior Principal Scientist and Professor, NAL – Bangalore. raja@nal.res.in	1. Dr P K Dash Professor and HOD at Nitte Meenakshi Institute of Technology Bengaluru, Karnataka, India	1. Mr.G.Saravanan, SRMIST
	2. Dr.K.M.Parammasivam, Professor, MIT-Chennai. mparams@mitindia.edu	2. Mr. A.Vinoth Kumar, SRMIST

Course Code	18ASC304J	Course Name	AIRCRAFT STRUCTURES	Course Category	C	Professional Core	L 3	T 0	P 2	C 4
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Pre-requisite Courses	18ASC201J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Aerospace	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Understand the physical meaning of symmetric bending and unsymmetrical bending				Level of Thinking (Bloom)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLR-2 :	Know the procedure to find the shear flow and shear center in open sections subjected to shear loads					Expected Proficiency (%)				Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Know the procedure to find the shear flow and shear center in closed sections subjected to shear loads					Expected Attainment (%)																		
CLR-4 :	Know the procedure to find the shear flow in closed sections subjected to torque																							
CLR-5 :	Understand the buckling analysis of plates																							
CLR-6 :	Learn the experimental procedure of stress analysis in wing and fuselage																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1 :	Explain the differences between symmetrical bending and unsymmetrical bending				2	85	75	H	H	H	H	-	H	H	H	-	-	-	M	M	M	M		
CLO-2 :	Improve the ability in solving geometrical applications of a structure				2	85	75	H	H	H	H	-	H	H	H	-	-	-	M	M	M	M		
CLO-3 :	Gain the ability to solve the shear flow analysis and shear centre of open section beams				2	85	75	H	H	H	H	-	H	H	H	-	-	-	M	M	M	M		
CLO-4 :	Solve the shear flow and shear center calculations in closed sections subjected to both shear loads and torsion loads.				2	85	75	H	H	H	H	-	H	H	H	-	-	-	M	M	M	M		
CLO-5 :	Describe the buckling modes of thin plates for various end conditions				2	85	75	H	H	H	H	H	H	H	H	-	-	-	M	M	M	M		
CLO-6 :	Describe the stress analysis in wing and fuselage				2	85	75	H	H	H	H	H	H	H	H	-	-	-	M	M	M	M		

		15	15	15	15	15
S-1	SLO-1	Introduction to symmetrical bending	Introduction to thin walled beams	Concept of Bredt - Batho theory and assumptions for Engineers Theory of bending.	Introduction to thin plates and its application to aircraft structures.	Shear distribution for wings
	SLO-2	Concept of bending stresses in beams of symmetrical sections	Section properties of thin walled beams	Derivation of the relation between shear flow and the torque	Plate subjected to pure bending.	Numerical solving
S-2	SLO-1	Symmetrical bending, assumptions	Concept of shear flow and the shear centre.	Multi cell structure subjected to torque, shear flow determination	Flexural rigidity of a plate, anticlastic and synclastic surface	Bending moment distribution for wings
	SLO-2	Direct stress distribution	Introduction to thin walled open section beams, assumptions	Numerical solving	Plate subjected to bending and twisting	Numerical solving
S-3	SLO-1	Anticlastic bending, unsymmetrical bending, sign conventions and notation, Resolution of bending moments.	General stress, strain and displacement relationship for open thin-walled beams.	Shear flow and shear centre determination, and shear flow distribution for a thin-walled symmetrical (three cell) closed sections subjected to torque.	Determination of shear strain for thin plates	Shear distribution for fuselage
	SLO-2	Derivation for bending stress expression due to bending.	Shear flow expression for open sections.	Numerical solving	Plates subjected to a distributed transverse load	Numerical solving
S-4	SLO-1	Lab 1: Determination of the position of principal axes of a Z section	Lab 4: Verification of principle of superposition (Cantilever beam)	Lab 7: Determination of shear center of closed section beam	Lab 10: Determination of the buckling stress of a given column	Lab 13: Study of free and forced vibration analysis
	SLO-2	Position of neutral axis, calculation of section properties, Second moments of area of an inclined thin section and a semicircular section	Shear flow of C section	Shear flow and shear centre determination, and shear flow distribution for a thin-walled symmetrical (single cell) closed sections subjected to shear force	Plate element subjected to bending, twisting and transverse loads.	Bending moment distribution for fuselage
S-5	SLO-1	Approximations for thin-walled sections	Shear flow of C section	Derivation of shear flow for closed section	Numerical solving	Numerical Solving
	SLO-2	Bending of symmetric sections with symmetric loads - Numericals	Shear center of C section	Closed section single cell -shear flow determination	Boundary conditions for various types of edge supports	Shear resistant web beams.
S-6	SLO-1	Numerical solving	Procedure of solving shear centre of c section	Numerical solving	Numerical solving	Numerical solving
	SLO-2					

S-7	SLO-1	Bending of symmetric sections with skew loads – Problems.	Shear flow distribution for thin walled open sections	Closed section two cell structure-shear flow determination	Combined bending and in-plane loading of a thin rectangular plate	Typical wing structural arrangement, wing strength requirements.
	SLO-2	Numerical solving	Shear center position for different type of thin walled open section	Numerical solving	Numerical solving	Numerical solving
S-8	SLO-1	Lab 2: Verification of Maxwell's reciprocal theorem(Cantilever beam)	Lab 5: Verification of principle of superposition (Simply supported beam)	Lab 8: Analysis of constant strength beam	Lab 11: Determination of the ratio of forces carried by two wires of different materials supported by hinged bar	Lab 14:Preparation of a composite laminate
	SLO-2					
S-9	SLO-1	Bending stress determination for symmetrical section with stringers.	Shear flow and shear centre determination, and shear flow distribution for thin-walled symmetrical open sections	Shear flow and shear centre determination, and shear flow distribution for a thin-walled symmetrical (single cell) closed sections subjected to shear force.	Buckling of thin plates	Tension (Wagner's) field beam – complete diagonal tension field beams.Derivation
	SLO-2	Numerical solving	Numerical solving	Numerical solving	Numerical solving	Incomplete diagonal tension field beams
S-10	SLO-1	Bending of unsymmetric sections with skew loads - Problems	Shear flow and shear centre determination, and shear flow distribution for thin-walled unsymmetrical open sections	Shear flow and shear centre determination, and shear flow distribution for a thin-walled symmetrical (two cell) closed sections subjected to shear force.	Inelastic buckling of plates	Typical wing structural arrangement, wing strength requirements.
	SLO-2	Numerical solving	Numerical solving	Numerical solving	Numerical solving	Beam theory assumptions, wing stress analysis methods.
S-11	SLO-1	Bending stress determination for unsymmetrical section with stringers.	Concept of structural idealization.	Shear flow and shear centre determination, and shear flow distribution for symmetrical and unsymmetrical (single cell) closed sections with stringers subjected to shear force	Local instability and Instability of stiffened panels	Shear lag concepts
	SLO-2	Numerical solving	Determination of boom areas	Numerical solving	Numerical solving	Basic fuselage structure, fuselage stress analysis methods.
S-12	SLO-1	Lab 3: Verification of Maxwell's reciprocal theorem(Simply supported beam)	Lab 6: Determination of shear center of open section beam	Lab 9: Determination of principal axes of a hollow shaft subjected to both bending and torsional loads	Lab 12:Determination of hoop stress and longitudinal stress in a thin walled pressure vessel	Lab 15:Design aspect of tension field beam
	SLO-2					
S-13	SLO-1	Bending of thin symmetric sections with symmetric loads - Problems	Shear flow and shear centre determination, and shear flow distribution for symmetrical open sections with stringers.	Shear flow and shear centre determination, and shear flow distribution for symmetrical and unsymmetrical (two cells) closed sections with stringers subjected to shear force.	Flexural–torsional buckling of thin-walled columns	shear flow distribution in the web of the tapered beam
	SLO-2	Numerical solving	Numerical solving	Numerical solving	Numerical solving	Calculation of direct stress due to bending in a fuselage
S-14	SLO-1	Bending of thin unsymmetric sections with skew loads - Problems.	Shear flow and shear centre determination, and shear flow distribution for a unsymmetrical open sections with stringers.	Shear flow and shear centre determination, and shear flow distribution for symmetrical and unsymmetrical (three cells) closed sections with stringers subjected to shear force.	Estimation of crippling stress using Needham's and Gerard's method.	shear flow distribution in the fuselage
	SLO-2	Numerical solving	Numerical solving	Numerical solving	Stiffened panel / Sheet effective width concepts	Principles of stiffener / web construction
S-15	SLO-1	Bending of thin symmetric sections with skew loads - Problems .	Walls effective in bending	Walls effective in bending	Inter rivet and sheet wrinkling failures.	Fuselage frames
	SLO-2	Numerical solving	Walls ineffective in bending	Walls ineffective in bending	Thin walled column strength, Torsional instability of thin walled columns.	Wing ribs

Learning Resources	1. Megson T H G,'Aircraft Structures for Engineering Students', Elsevier, Fifth edition, 2013 2. Bruhn. E.F., 'Analysis and Design of Flight Vehicles Structures', Tri-state offset company, USA 1985 3. Aircraft Structures Laboratory manual	4. Rivello, R.M., Theory and Analysis of Flight Structures, McGraw Hill, 1993. 5. Peery, D.J., Aircraft Structures, 2nd edition, McGraw-Hill, N.Y., 1999
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100%		100%		100%		100%		100%	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. G.Balamurugan, National Aerospace Laboratories, Bangalore, gbala@nal.res.in	1. Dr. V.Arumugam, Madras Institute of Technology, Chennai, arumugam.mitaero@gmail.com	Dr.LR.Ganapathy Subramanian, Professor, SRMIST
2. Dr.A. Sakthivel, CEMILAC, Bangalore, asakthironika@gmail.com	2. Dr. R.Velmurugan, Indian Institute of Technology Madras, rvel@ae.iitm.ac.in	Mr. S.Chandra Sekhar Assistant Professor, SRMIST

Course Code	18ASC305T	Course Name	FLIGHT DYNAMICS - II	Course Category	C	Professional Core	L	T	P	C
							3	0	0	3

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning		
CLR-1:	Know the importance of stability and control of airplane	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3
CLR-2:	Learn the concepts of static stability and dynamic stability of airplane						
CLR-3:	Learn longitudinal, lateral and directional stabilities						
CLR-4:	Understand control fixed and control free effects						
CLR-5:	Learn the criteria for stability and instability						
CLR-6:	Learn experimental techniques to measure stability parameters of an airplane using real flight testing						
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:					
CLO-1:	Determine the degree of stability of any airplane configuration	5	85	90			
CLO-2:	Design an airplane for the required degree of stability and maneuverability	3	80	85			
CLO-3:	Indicate the different flight techniques for safer flight	4	75	80			
CLO-4:	Perform basic calibration of control surfaces	5	50	75			
CLO-5:	Identify different instability modes in flight and suggest the correct recovery procedure	5	80	80			
CLO-6:	Determine the stability derivatives of a real airplane with real flight testing	4	00	95			

S-8	SLO-1	Solving problems	Static margin and neutral point- definition	Derivatives due to the rolling rate	Lateral motion – stick fixed	Determination of stick fixed maneuvering point- parameters
	SLO-2	Directional stability- basics	Stick forces and stick force gradients- definition	Derivatives due to the yawing rate	Pure rolling motion	Determination of stick free maneuvering point- parameters
S-9	SLO-1	Various requirements of rudder for directional control	Solving problems	Solving problems	Tutorial	Tutorial
	SLO-2	Solving problems	Solving problems	Solving problems	Tutorial	Tutorial

Learning Resources	1. Nelson, R.C., "Flight Stability and Automatic Control", McGraw Hill, 1989 2. Bernard Etkin "Dynamics of atmospheric flight" Wiley, 1972	3. Perkins, C. D., and Hage, R.E., "Airplane Performance, Stability and Control," Wiley Toppan, 1974.. 4. Babister, A. W., "Aircraft Stability and Response", Pergamon Press, 1980. 5. L J Clancy "Aerodynamics" John Wiley & Sons (1975)
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. Raja S, CSIR-NAL, Bangalore, raja@nal.res.in	1. Dr. K. M. Parammasivam, Madras Institute of Technology, Chennai, mparams@mitindia.edu	1. Mr. M. Vignesh Kumar, SRMIST
2. Wg.Cdr K.Manoharan (Retd), Blue Dart Aviation Ltd., manoharank@bluedart.com	2. Dr. P. K Dash, Nitte Meenakshi Institute of Technology, Bangalore, drpdash@gmail.com	2. Mr. K. Allwyn, SRMIST

Course Code	18ASC306T	Course Name	INTRODUCTION TO SPACE TECHNOLOGY	Course Category	C	Professional Core	L	T	P	C
							3	0	0	3

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
					1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-1 :	Learn about fundamental laws that govern the orbital dynamics.				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgr. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-2 :	Understand and apply the basic equations of orbital dynamics for different conic orbits.																					
CLR-3 :	Understand the importance of Keplerian orbital elements, Kepler's equation and orbital perturbations.																					
CLR-4 :	Learn the different types of orbit transfers, basics of interplanetary trajectories.																					
CLR-5 :	Study the governing equations of rocket motion, rocket motion under different conditions.																					
CLR-6 :	Understand the fundamentals of ballistic missile trajectory and its governing equations, errors associated during launching of ballistic missiles.																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	Acquire knowledge of laws applied in orbital dynamics.				2	85	75	H	M	L	L	-	-	-	-	-	-	-	L	M	M	M
CLO-2 :	Analyze the properties of conic orbits using the governing equations of orbital mechanics.				2	90	80	H	H	M	M	L	-	-	-	-	-	-	L	H	H	M
CLO-3 :	Apply Kepler's equation, earth's oblateness for positioning the satellite at a desired position in orbit.				2	80	75	H	M	M	M	-	-	-	-	-	-	-	L	M	M	H
CLO-4 :	Accrue knowledge of different orbit transfers which can be used for many practical missions.				2	85	75	H	H	M	M	L	-	-	-	-	-	-	L	H	M	M
CLO-5 :	Apply the governing equations of rocket motion for different conditions.				2	80	70	H	M	L	L	-	-	-	-	-	-	-	L	M	H	M
CLO-6 :	Accrue understanding and importance of ballistic missile trajectory and effectively implement its equations by considering the launching errors.				2	85	75	H	M	M	L	-	-	-	-	-	-	-	L	M	M	M

	SLO-2	Proof - Kepler's Second and Third Law	Earth's Oblateness and its Effects, Applications – Sun-Synchronous and Molniya Orbits	Phasing Maneuvers - Introduction		Numerical Problems on the Movement of the Target Compensation
S-8	SLO-1	Some Important Properties of Individual Conic Orbits – Circular Orbit, Elliptic Orbit	Introduction to Orbital Perturbations – Perturbing Forces, Perturbation Techniques – Definitions of Special and General Perturbations	Introduction to Inter-planetary Mission Trajectories	Introduction to Multi-Stage Rocket and its Types, Restricted Staging and Optimal Staging - Definitions	Effect of Launching Errors on Range – Introduction to Down-Range and Cross-Range Errors
	SLO-2	Some Important Properties of Individual Conic Orbits – Parabolic Orbit, Hyperbolic Orbit				
S-9	SLO-1	Tutorial	Tutorial	Tutorial	Tutorial	Tutorial
	SLO-2					

Learning Resources	1. Howard D. Curtis, <i>Orbital Mechanics for Engineering Students</i> , 4 th Edition, Butterworth-Heinemann, 2019.	4. Ashish Tewari, <i>Atmospheric and Space Flight Dynamics</i> , Springer, 2007.
	2. William E. Wiesel, <i>Spaceflight Dynamics</i> , 3 rd Edition, CreateSpace, 2010.	5. Cornelisse J.W., Schoyer H.F.R. & Wakker K.F., <i>Rocket Propulsion and Spaceflight Dynamics</i> , Pitman Publishing Ltd., 1979.
	3. Roger R. Bate, Donald D. Mueller & Jerry E. White, <i>Fundamentals of Astrodynamics</i> , Dover Publications, Inc., New York, 1971.	6. Martin J. L. Turner, <i>Rocket and Spacecraft Propulsion</i> , 3 rd Edition, Springer, 2009.
		7. Vladimir A. Chobotov, <i>Orbital Mechanics</i> , 3 rd Edition, AIAA Education Series, AIAA, 2002.

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Dr. Manishankar C., Senior Scientist, NAL, Bangalore	Prof. Arun Kumar P., Assistant Professor, IIT Jammu	Dr. S. M. Aravindh Kumar, SRMIST
		Mr. K. Allwyn, SRMIST

Course Code	18ASC307L	Course Name	AEROSPACE COMPUTATIONAL ANALYSIS LABORATORY				Course Category	C	Professional Core				L	T	P	C									
													0	0	2	1									
Pre-requisite Courses	18ASC201J ,18ASC301J				Co-requisite Courses	Nil		Progressive Courses	Nil																
Course Offering Department		Aerospace Engineering				Data Book / Codes/Standards		Gas Table																	
Course Learning Rationale (CLR):		The purpose of learning this course is to:						Learning			Program Learning Outcomes (PLO)														
CLR-1 :		To create 2D Design of aircraft components						1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :		To create 3-Dimensional Design and assembly of typical aircraft & its components.						Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :		To create drafting of aircraft components																							
CLR-4 :		To simulate and evaluate Structural characteristics of beams and aircraft structural components																							
CLR-5 :		To simulate and evaluate aerodynamic properties of Subsonic and supersonic flow over the objects																							
CLR-6 :		To simulate and evaluate Heat transfer and combustion process																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:						1	80	75	H	L	M	M	H	-	-	-	-	-	-	H	-	H	-
CLO-1 :		To familiarize with basic aircraft components						3	80	75	H	H	H	H	H	-	-	-	-	-	-	H	-	H	-
CLO-2 :		To familiarize 3-Dimensional Design of typical aircraft & its components.						3	70	60	H	H	H	H	H	-	-	-	-	-	-	H	-	H	-
CLO-3 :		To familiarize assembly and drafting of aircraft components						3	70	60	H	H	H	H	H	-	-	-	-	-	-	H	-	H	-
CLO-4 :		To familiarize Structural analysis of beams and aircraft structural components						3	70	60	H	H	H	H	H	-	-	-	-	-	-	H	-	H	-
CLO-5 :		To familiarize Subsonic and supersonic flow analysis over the objects						3	70	60	H	H	H	H	H	-	-	-	-	-	-	H	-	H	-
CLO-6 :		To familiarize Heat transfer and combustion analysis						3	70	60	H	H	H	H	H	-	-	-	-	-	-	H	-	H	-
Duration (hour)		06		06		06		06		06		06													
S 1-2	SLO-1	Lab 1: 2D layout of aircraft wing rib and bulkhead sections		Lab 4: Assembly of Typical Aircraft.		Lab 7: 2D analysis of subsonic flow over bluff /streamlined body.		Lab 10: Simulation of Premixed / Non-Premixed Combustion analysis		Lab 13: Heat transfer analysis over a flat plate with natural / forced convection															
S 3-4	SLO-1 SLO-2	Lab 2: 3D model of aircraft Wing Structure		Lab 5: Drafting of Typical Aircraft.		Lab 8: 2D analysis of supersonic flow over bluff /streamlined body.		Lab 11: structural analysis of beams		Lab 14: Heat transfer analysis over a composite plate with natural / forced convection															
S 5-6	SLO-1 SLO-2	Lab 3: 3D model of aircraft fuselage Structure		Lab 6: Introduction to CFD and Grid independency study		Lab 9: 2D analysis of supersonic flow through C-D Nozzle.		Lab 12: Structural analysis of aircraft wing		Lab 15: Heat Transfer analysis in a Thin Plate using MATLAB code															
Learning Resources		Laboratory manual User manual of respective software						Gas Table																	
Learning Assessment																									
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)															
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#																	
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice												
Level 1	Remember	-	40%	-	30%	-	30%	-	30%	-	30%	-	30%												
Level 2	Understand	-	40%	-	30%	-	30%	-	30%	-	30%	-	30%												
Level 3	Apply	-	40%	-	30%	-	30%	-	30%	-	30%	-	30%												
Level 3	Analyze	-	20%	-	30%	-	30%	-	30%	-	30%	-	30%												
Level 3	Evaluate	-	20%	-	30%	-	30%	-	30%	-	30%	-	30%												
Level 3	Create	-	20%	-	30%	-	30%	-	30%	-	30%	-	30%												
Total		100 %		100 %		100 %		100 %		100 %		100 %													
# CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,																									
Course Designers																									
Experts from Industry				Experts from Higher Technical Institutions				Internal Experts																	
Dr. S. Raja, Senior Principal Scientist and Professor, NAL – Bangalore. raja@nal.res.in				Dr.K.M.Parammasivam, MIT-Chennai. mparams@mitindia.edu				Mr. R. Mohamed Arif, SRMIST.																	
								Mr. K. B. RavichandraKumar, SRMIST.																	

Course Code	18ASC350T	Course Name	COMPREHENSION	Course Category	C	Professional Core	L	T	P	C
							0	1	0	1

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Aerospace Engineering	Data Book / Codes/Standards	Machine Data		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1:	Acquire skills to solve real world problems in Engineering Graphics Design, Engineering Mechanics and Fluid Mechanics	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2:	Acquire skills to solve problems in Thermodynamics, Aircraft Systems and Instruments and Aircraft Materials, Production Techniques	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3:	Acquire skills to solve real world problems in Applied Solid Mechanics, Incompressible Aerodynamics and Air Breathing Propulsion	Expected Proficiency (%)	Problem Analysis
CLR-4:	Acquire skills to solve real world problems in Compressible Aerodynamics, Rocket Propulsion and Aircraft Structures	Expected Attainment (%)	Design & Development
CLR-5:	Acquire skills to solve real world problems for competitive examinations in Aerospace Engineering		Analysis, Design, Research
CLR-6:	Acquire skills to solve real world problems in the broad domain of Aerospace Engineering		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1:	Practice and gain confidence, competence to solve problems in Engineering Graphics Design, Engineering Mechanics and Fluid Mechanics	3 85 80	H H H L L L L L L L L L L M L M
CLO-2:	Practice and gain confidence, competence in Thermodynamics, Aircraft Systems and Instruments, Aircraft Materials, Production Techniques	3 85 80	H H M L L L L L L L L L L M M M
CLO-3:	Solve problems in Applied Solid Mechanics, Incompressible Aerodynamics and Air Breathing Propulsion	3 85 80	H H M L L L L L L L L L L M L M
CLO-4:	Practice and gain confidence and competence to solve problems in Compressible Aerodynamics, Rocket Propulsion and Aircraft Structures	3 85 80	H H M L L L L L L L L L L M M M
CLO-5:	Practice and gain confidence and competence to solve problems for competitive examinations in Aerospace Engineering	3 85 80	H H H L L L L L L L L L L M L M
CLO-6:	Practice and gain confidence and competence to solve problems in the broad domain of Aerospace Engineering	3 85 80	H H M L L L L L L L L L L M M M

Duration (hour)	3	3	3	3	3
S-1	SLO-1 Tutorial on Engineering graphics and design	Tutorial on Thermodynamics	Tutorial on Applied Solid Mechanics	Tutorial on Compressible Aerodynamics	Problem Solving
	SLO-2 Problem Solving	Problem Solving	Problem Solving	Problem Solving	Problem Solving
S-2	SLO-1 Tutorial on Engineering Mechanics	Review of Aircraft Systems	Tutorial on Incompressible Aerodynamics	Tutorial on Rocket Propulsion	Problem Solving
	SLO-2 Problem Solving	Review of Aircraft Instruments	Problem Solving	Problem Solving	Problem Solving
S-3	SLO-1 Tutorial on Fluid mechanics	Review of Aircraft Materials	Tutorial on Air Breathing Propulsion	Tutorial on Aircraft Structures	Problem Solving
	SLO-2 Problem Solving	Review of Production Techniques	Problem Solving	Problem Solving	Problem Solving

Learning Resources	1. Ferdinand P. Beer, E. Russell Johnston Jr., David Mazurek, Philip J Cornwell, "Vector Mechanics for Engineers: Statics and Dynamics", McGraw - Hill, New Delhi, Tenth Edition, 2013. 2. Irving H. Shames, "Mechanics of Fluids", 4rd Edition, McGraw-Hill, 2003. 3. Yunus A. Cengel and Michael A. Boles, "Thermodynamics an engineering approach", 7th ed., , McGraw Hill, 2011	4. Cohen. H. Rogers. G.F.C. and Saravanamuttoo. H.I.H.: Gas turbine theory. 4th ed., Pearson 5. George P. Sutton, Oscar Biblarz, "Rocket propulsion elements", Wiley India Pvt Ltd. 8th ed., 2010 6. Anderson, J.D., "Fundamentals of Aerodynamics", McGraw Hill., New York, 6th ed., 2016
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Learning Assessment										
	Bloom's Level of Thinking	Continuous Learning Assessment (100% weightage)								Final Examination
		CLA – 1 (20%)		CLA – 2 (30%)		CLA – 3 (30%)		CLA – 4 (20%)#		
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory Practice
Level 1	Remember	-	40%	-	30%	-	30%	-	30%	- -
	Understand									
Level 2	Apply	-	40%	-	40%	-	40%	-	40%	- -
	Analyze									
Level 3	Evaluate	-	20%	-	30%	-	30%	-	30%	- -
	Create									
	Total	100 %		100 %		100 %		100 %		-

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. Raja S, CSIR-NAL, Bangalore, raja@nal.res.in	1. Dr. K. M. Parammasivam, Madras Institute of Technology, Chennai, mparams@mitindia.edu	Mr.G.Mahendra Perumal , SRMIST
2. Wg.Cdr K.Manoharan (Retd), Blue Dart Aviation Ltd., manoharank@bluedart.com	2. Dr. P. K Dash, Nitte Meenakshi Institute of Technology, Bangalore, drpdash@gmail.com	Dr.S.Gurusideswar , SRMIST

ACADEMIC CURRICULA

Professional Core Courses

AUTOMOBILE ENGINEERING

Regulations - 2018



SRM INSTITUTE OF SCIENCE AND TECHNOLOGY

(Deemed to be University u/s 3 of UGC Act, 1956)

Kattankulathur, Kancheepuram, Tamil Nadu, India

Course Code	18AUC301J	Course Name	AUTOMOTIVE ENGINES				Course Category	C	Professional Core					L	T	P	C									
														3	0	2	4									
Pre-requisite Courses		18AUC203T		Co-requisite Courses		Nil		Progressive Courses		Nil																
Course Offering Department		Automobile Engineering				Data Book / Codes/Standards				Nil																
Course Learning Rationale (CLR):		The purpose of learning this course is to:						Learning			Program Learning Outcomes (PLO)															
CLR-1 :	Understand various components of the engine and its functions						Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Understand the combustion in SI Engine																									
CLR-3 :	Gain knowledge on combustion in CI Engine																									
CLR-4 :	Understand the lubrication, cooling system and able to test the lubricants and fuels used for IC engines																									
CLR-5 :	Understand the turbo, supercharging and scavenging system in IC Engines																									
CLR-6 :	Obtain the knowledge of test engines and can conduct the performance and heat balance test on IC engines using various dynamometers																									
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																								
CLO-1 :	Understand the importance of valve timing diagram and firing order						1	90	85	H	M	H	M	M	L	M	L	L	L	L	L	M	M	L	M	
CLO-2 :	Understand the combustion phenomena in SI Engines						1	90	85	H	L	L	M	L	L	H	L	L	L	L	H	H	L	M		
CLO-3 :	Understand the combustion phenomena in CI Engines						1	90	85	H	L	L	M	L	L	H	L	L	L	L	H	H	L	M		
CLO-4 :	Understand the lubrication and cooling system in IC Engines.						2	90	85	M	M	H	H	L	L	M	L	L	L	L	M	L	M	M		
CLO-5 :	Understand the turbo, supercharging and scavenging system in IC Engines						2	90	85	H	M	M	L	M	L	M	L	L	L	L	M	M	M	M		
CLO-6 :	Knowledge about the recent development in the area of engines						2	90	85	H	L	H	L	H	L	H	L	M	L	L	H	M	M	M		
Duration (hour)		15		15		15		15		15		15														
S-1	SLO-1	Introduction to engine components	Combustion in SI engines	Combustion in CI Engines		Introduction to Lubrication and Cooling system		Supercharging and Scavenging																		
	SLO-2	Constructional details of engine components, function, materials,	Stages of combustion, Flame propagation	Importance of air motion - Swirl, squish and turbulence		Need for cooling system - Types of cooling system		Objectives - Effects on engine performance																		
S-2	SLO-1	Valve timing diagram for SI and CI engine	Flame velocity and area of flame front	Swirl ratio. Fuel air mixing		Liquid cooled system		engine modification required																		
	SLO-2	Port timing diagram for SI and CI engine	Rate of pressure rise - Cycle to cycle variation	Stages of combustion		Thermosyphon system		Thermodynamics of supercharging																		
S-3	SLO-1	Firing order and its significance	Abnormal combustion - Theories of detonation	Delay period - Factors affecting delay period		Forced circulation system		Thermodynamics of Turbocharging																		
	SLO-2	Tutorial 1: Comparison of Valve Timing Diagrams for SI and CI engine	Tutorial 3: Comparison of SI and CI engine combustion process	Knocking in CI engines - methods of controlling diesel knock.		pressure cooling system		Turbo lag-Windage, losses																		
S-4-5	SLO-1	Lab 1: Valve Timing Diagram for Four Stroke Engine and port Timing Diagram for Two Stroke Engine	Lab 3: Performance test on Petrol engine at full throttle and part throttle conditions	Lab 5: Study of gasoline and diesel fuel supply system.		Lab 7: Test for optimum coolant flow rate in IC engines		Lab 9: Energy Balance test on an Automotive Diesel Engine																		
	SLO-2	Intake system components - Discharge coefficient, Pressure drop	Introduction to Combustion chambers	CI engine combustion chamber.		Properties of coolant, additives for coolants		Turbo charging methods																		
S-6	SLO-1	Air filter, intake manifold, Connecting Pipe	Effect of engine operating variables on combustion	Combustion chamber design objectives - open type		Need for lubrication system		Engine exhaust manifold arrangements.																		
	SLO-2	Exhaust system components	Combustion chambers -types	Combustion chamber design objectives – divided type		Mist lubrication system		Classification of scavenging systems																		
S-7	SLO-1	Exhaust manifold and exhaust pipe	factors controlling combustion chamber design	Induction swirl, turbulent combustion chambers		wet sump any dry sump lubrication		Mixture control through Reed valve																		
	SLO-2	Spark arresters	Gasoline injection system	Air cell chamber - M Combustion chamber		Properties of lubricants, consumption of oil		Induction - Charging Processes in two-stroke cycle engine - Terminologies																		

	SLO-2	Exhaust mufflers, Types, operation	Tutorial 4: Combustion chamber designs	Diesel injection system	Tutorial 8: Lubrication methods	Shankey diagram - perfect displacement, perfect mixing.
S 9-10	SLO-1	Lab 2: Performance test on constant speed diesel engine	Lab 4: Morse test on petrol engines	Lab 6: Dismantling, measuring of components and Assembling of a multi cylinder engine.	Lab 8: Determination of viscosity of oil by different methods like, Redwood, Say bolt and Engler's Viscometer	Lab 10: Performance test on Diesel Engine at full load and part load conditions
	SLO-2					

Learning Resources	1. Ganesan V, "Internal combustion engines", 4th edition, Tata McGraw Hill Education, 2012. 2. Rajput R. K, "A textbook of Internal Combustion Engines", 2nd edition, Laxmi Publications (P) Ltd, 2007. 3. John. B, Heywood, "Internal Combustion Engine Fundamentals", McGraw Hill Publishing Co., New York, 1900.	4. Ramalingam K. K, "Internal Combustion Engines", Second Edition, Scitech Publications, 2009 5. Mathur and Sharma, "A course on Internal combustion Engines", Dhanpat Rai & Sons, 1985. 6. Edward F, Obert, "Internal Combustion Engines and Air Pollution", Intext Education Publishers, 1980
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
Level 2	Apply Analyze	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
Level 3	Evaluate Create	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Total	100 %		100 %		100 %		100 %		-	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Jayaraman.R, BLG Logistics, jayaraman.r@blgparekh.com	1. Dr.M.Parthasarathy, Vel Tech, nparthasarathy@veltech.edu.in	1. Dr. A. Prabu, SRMIST
2. Mr. Shanmuga Sundaram, RNTBCI, sankaran@mtbci.com	2. Dr.P.Nanthakumar, Amrita school of Engineering, p_nanthakumar@cb.amrita.edu	2. Dr. S. Thiyagarajan, SRMIST

Course Code	18AUC302J	Course Name	VEHICULAR STRUCTURES AND DRIVELINE SYSTEMS	Course Category	C	Professional Core	L	T	P	C
							3	0	2	4

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1:	Familiarize the structure of Vehicle frames, Front and Rear axles	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2:	Acquire knowledge about various types of automotive driveline systems	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3:	Explore the various components and functions of steering and suspension systems	Expected Proficiency (%)	Problem Analysis
CLR-4:	Understand the different types of automotive transmission systems	Expected Attainment (%)	Design & Development
CLR-5:	Impart the knowledge of braking system, Wheels and tyres		Analysis, Design, Research
			Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1:	Demonstrate the basic structure of an automobile and various types of axles.	2 90 90	H M M M M H H M L L L H H M M
CLO-2:	Identify the various types of automotive driveline systems.	2 90 90	H M M M M H H M L L L H H M M
CLO-3:	Classify the different types of steering and suspension systems.	2 90 90	H H M M M H H M L L L H H M M
CLO-4:	Classify the different types of transmission systems.	3 90 90	H H M M M H H M L L L H H M M
CLO-5:	Identify the various types of braking systems, wheels and tyres.	2 90 90	H M M M M H H M L L L H H M M

Duration (hour)	Frames, Front and Rear Axles	Drive Line and Final Drives	Steering and Suspension Systems	Transmission System	Brakes, Wheels and Tyres
	15	15	15	15	15
S-1	SLO-1 Different types of chassis layout- FF, FR,RR and 4WD.	Effect of driving thrust and torque reactions.	Front wheel geometry - Caster, Camber.	Types of clutches, construction and working of single plate.	Theory of braking.
	SLO-2 Different types of chassis layout- FF, FR,RR and 4WD.	Effect of driving thrust and torque reactions.	Front wheel geometry - Toe in and toe out, SAI.	Multi plate and centrifugal clutch.	Stopping distance - Braking efficiency, Numerical analysis.
S-2	SLO-1 Types of vehicle body and Classifications.	Hotchkiss and torque tube drive.	Steering systems - True rolling motion of wheels and Numerical Analysis.	Torque capacity of clutch – Numerical Analysis.	Drum brakes - Single cam, Double cam.
	SLO-2 Types of vehicle body and Classifications.	Front wheel drive.	Simple problems	Simple problems	Leading and Trailing shoe types.
S-3	SLO-1 Frames- construction, Materials, LoadsActing on frames.	Propeller shaft –Construction, Critical Speed.	Ackermann and Davis steering Mechanism.	Fluid coupling – Construction	Disc brakes - Fixed, floating and radial mounted calipers.
	SLO-2 Frames- construction, Materials, LoadsActing on frames.	Universal joint, Slip joint.	Constructional details of steering linkages for rigid front axle.	Fluid coupling –Principle of operation.	Ventilated discs, cross drilled discs, slotted discs.
S 4-5	SLO-1 Lab 1: Study and measurement of various types of vehicle frame, body and driver seat.	Lab 4: Dismantling, study and assembling of automobile driveline and differential.	Lab 7: Dismantling, study and assembling of automobile suspension system.	Lab 10: Calculating the maximum torque carrying capacity of the given clutch using clutch dynamometer.	Lab 13: Dismantling, assembling and bleeding of a braking system.
	SLO-2 Types of vehicle frames-Ladder frame, Tubular frame.	Constant velocity joints.	Constructional details of steering linkages for independent front axles.	Torque converters - Construction	Mechanical and hydraulic brake actuation.
S-6	SLO-2 Integral frame, X-frame, Roll-cage frames.	Rzeppa and Tripod joints.	Steering gear box - Re-circulating ball type,Rack and pinion type, Worm and Nut type.	Principle of operation.	Pneumatic braking system.
S-7	SLO-1 Common vehicle platform- Need.	Different types of final drive - Worm and worm wheel, Straight bevel gear.	Power assisted steering - Hydraulic and EPS.	Hydro kinetic drives - Multistage torque converters.	Vacuum assisted hydraulic brakes.
	SLO-2 Common vehicle platform- merits and demerits.	Spiral bevel gear and hypoid gear final drives.	Four wheel Steering.	Poly-phase torque converters.	Air assisted hydraulic brakes.

S-8	SLO-1	Case study-Volkswagen PQ platform, Nissan B platform.	Double reduction final drive.	Need for suspension system. Types of suspension - Non independent suspension.	Types of gear boxes - Working of sliding And constant mesh gear boxes.	Need for ABS, ESP, EBD.
	SLO-2	Case study- Nissan B platform.	Twin speed final drive.	Independent suspension - McPherson and Wishbone suspension.	Construction and working of synchromesh gear box and principle of synchronizers	Need for Regenerative braking systems.
S 9-10	SLO-1	Lab 2: Study of different types of front and rear axles and final drives.	Lab 5: Dismantling, study and assembling of different automobile steering systems.	Lab 8: Dismantling, study and assembling of automobile clutches.	Lab 11: Dismantling, gear ratio calculation and assembling of an automobile transmission.	Lab 14: Study and analysis of the construction of various wheels and tyres.
	SLO-2	Calculation of final drive ratio.				
S-11	SLO-1	Front axle – Live axles, Dead axles.	Differential- Principle.	Types of suspension springs - Leaf spring, Coil spring, Torsion bar, and Rubber springs.	Planetary gear box - construction and working.	Types of Wheels
	SLO-2	Front axle – Drop axles, Push and tag axles.	Differential- Construction details.	Shock absorbers.	Planetary gear box - construction and working.	Dimensions and Constructional details
S-12	SLO-1	Rear axles – Semi, full and three quarter floating.	Differential lock.	Pneumatic suspension systems.	Numerical in Gear box.	Types - Construction - Cross ply, Radial ply.
	SLO-2	Housing types- Split Banjo and Salisbury type.	Differential lock.	Rear axle suspension system - Independent, Trailing Arm.	Automatic transmission - Chevrolet turbo glide - Construction and working..	Types - Construction - Tube and tubeless tyres.
S-13	SLO-1	Multi-link rear axles	Limited slip differential.	De-dion suspension and torsion beam.	Automatic transmission – Chevrolet Power glide - Construction and working..	Tyre designation.
	SLO-2	Multi-link rear axles	Limited slip differential.	Anti-roll bar, Pan hard rod and Radius rod	Hydraulic clutch actuation for Automatic transmission.	Tread patterns.
S 14-15	SLO-1	Lab 3: CLA-1	Lab 6: CLA-2	Lab 9: CLA-3	Lab 12: CLA-4	Lab 15: University practical examination.
	SLO-2					

Learning Resources	1. Kirpal Singh, "Automobile Engineering - Vol I", Standard Publishers Distributors, 1999.	3. Heldt P.M, "Torque converters", Chilton Book Co., 1992.
	2. Crouse W.H, Anglin D.L, "Automotive Transmission and Power Train construction", McGraw Hill, 1976.	4. Newton Steeds & Garrot, "Motor Vehicles", SAE International and Butterworth Heinemann, 2001.

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		-	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.SarathRamakannan, Aston Martin, sharath.ramakrishnan@astonmartin.com	1. Dr.N.Balaji, Sri Krishna College of Engineering, balajin@skcet.ac.in	1. Dr. Edwin Geo V, SRMIST
2. Mr.Franklin Darlie, HAL, franklindarlie@rediff.com	2. Dr.R.Sakthivel, Sri Venkateswara College of Engineering, rsakthivel@svce.ac.in	2. Mr.Deepak M, SRMIST

Course Code	18AUC303J	Course Name	AUTOMOTIVE ELECTRICAL AND ELECTRONIC SYSTEMS	Course Category	C	Professional Core				L	T	P	C
										3	0	2	4

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	To acquire knowledge of about the application of electrical and electronics in automotive systems				Level of Thinking (Bloom)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLR-2 :	Familiarize the usage of Sensors and actuators in Automobile					Expected Proficiency (%)																		
CLR-3 :	Acquire the fundamental electronics applied vehicle motion control system					Expected Attainment (%)																		
CLR-4 :	Understanding the working of charging and lighting accessories in automobile																							
CLR-5 :	Know about various Electrical equipment diagnostics and testing methods																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1 :	Understanding battery, Cranking motor construction and testing methods.				2	85	75	H	M	H	L	H	M	M	H	H	M	L	M	H	H	H	H	
CLO-2 :	Understand the principle of alternator and to test the alternator				2	80	75	H	M	H	H	H	M	M	H	H	M	L	M	H	H	H	H	
CLO-3 :	Apply the Electronic Controls in Gasoline Engine				2	90	85	H	H	H	H	L	M	M	H	M	M	M	H	H	H	H	M	
CLO-4 :	Understand the basics of Vehicle Motion Control and telemetric system				2	85	80	H	M	H	H	H	H	H	H	H	M	M	H	H	H	H	H	
CLO-5 :	Perform OBD II test on vehicle and Program hardware using Lab view				2	80	75	H	M	M	M	H	H	H	H	H	H	M	H	H	H	H	H	

		Batteries and Starting Systems	Charging System and Lighting Auxiliaries	Electronic Engine Management System	Fundamentals of Vehicle Motion Control	Telematics and Vehicle Diagnostics
Duration (hour)		15	15	15	15	15
S-1	SLO-1	Unit – I Vehicle Batteries types	Unit- II Charging system - Introduction	Unit –III Introduction – Engine management system	Unit – IV Introduction – Vehicle motion control	Unit – V Introduction – Telematics
	SLO-2	Lead acid battery - Principle	Alternator Principle Construction, Working	Gasoline Engine Fuel Injector	Cruise Control System	GPS Navigation
S-2	SLO-1	Lead acid battery - Construction, Working	Alternator merits over D.C Generator	Single point Fuel Injections	Adaptive Cruise Control System - Construction	GPS Structure
	SLO-2	Battery Rating	Alternator Charging Circuits	Multi Point Fuel Injections	Adaptive Cruise Control System - Working	Dead Reckoning - Construction
S-3	SLO-1	Lead Acid battery Charging methods	Rectification of AC to DC	Merits of MPFI	Throttle Actuator Stepper Motor Based Control	Dead Reckoning - Working
	SLO-2	Testing Methods	Alternator Testing Methods	Testing of Fuel Injectors	Antilock Braking Mechanism - Construction	Inertial Navigation System - Construction
S-4	SLO-1	Lab 1: Battery Testing –Hydrometer, Load test, Individual Cell voltage test	Lab 3: Alternator Testing –Continuity test, Insulation Test, Load test.	Lab 5: Study of Lab view Programming	Lab 7: PWM Signal generation	Lab 9: UART communication for parking sensor
	SLO-2	Fault Diagnosis.	Mechanical Voltage Regulator - Principle	Ignition system- Introduction	Antilock Braking Mechanism - Working	Inertial Navigation System - Working
S-6	SLO-1	Requirement of a starting System	Mechanical Voltage Regulator – construction, working	Conventional Ignition System	Tire Slip Controller	Invehicle infotainment systems
	SLO-2	Starter motor Construction	Electronic Voltage regulator –Principle	Electronic Ignition System	Merits of ABS	ADAS - Introduction
S-7	SLO-1	Starter motor Working.	Electronic Voltage Regulator – construction, working	Programmed ignition system	Electronic Suspension System- Construction	ADAS features
	SLO-2	Starter Drive Mechanism - introduction	Lighting Fundamentals	Distributor less Ignition System	Electronic Suspension System- Working	Electronic Control System Diagnostics.
S-8	SLO-1	Starter Drive Mechanism - types	Lighting Circuit example	Waste spark analysis	Variable Damping	OBDII - Objective
	SLO-2	Lab 2: Starter Motor –Continuity test, Insulation Test, Load test	Lab 4: Study of voltage regulator, solenoids	Lab 6: ADC interfacing for IR Sensor	Lab 8: H-Bridge Motor speed and position Control	Lab 10: Fault Diagnosis using OBD handheld Devices
S-9-10	SLO-1	Bendix drive	Conventional Headlamps – Sealed bulb headlamps	Digital Engine Control Modes	Variable Spring rate	Comparison of OBD I and OBD II
	SLO-2	Folo-thru drive	Conventional Headlamps – Bifilament headlamps	EGR Control	Merits of Electronic suspension system	Diagnostics Fault Codes

S-12	SLO-1	Over Running Clutch drive	LED Lighting System	variable valve timing	Electric Power Assisted Steering Mechanism- Construction	Introduction to Model-based Sensor Failure Detection
	SLO-2	Starter switch	Fog lamp	Ignition Controlling - Introduction	Electric Power Assisted Steering Mechanism- working	Model-based Sensor Failure Detection working
S-13	SLO-1	Starter Motor Fault Diagnosis	Wiper system	Closed loop ignition timing	Four Wheel Steering	Case Study on MAF Sensor calibration
	SLO-2	New Developments in Battery Technologies and Starting System	Signaling and Warning system	Spark Advance Correction Scheme	Steer-by-Wire	Case Study on MAF Sensor calibration .Cont
S-14-15	SLO-1	Lab: Assessment 1	Lab: Assessment 2	Lab: Assessment 3	Lab: Review class	Lab: Mini Project
	SLO-2					

Learning Resources	1.	Tom Denton "Automobile Electrical and Electronic Systems" 3rd edition, Elsevier Butterworth-Heinemann 2004.	4.	Allan.W.M.Bonnick "Automotive Computer Controlled System 2001, Butterworth-Heinemann
	2.	William.B.Ribbens, "Understanding Automotive Electronics" 7th edition Butterworth-Heinemann publications, 2012.	5.	Robert Bosch GmbH "Bosch Automotive Electric and Electronics" 5th edition Springer-2007
	3.	Ed Doering "NI MYRIO Project Essential Guide" 2013 National Technology and Science Press		

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		-	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, and Conf. Paper etc.

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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		2. Mr.Jesu Godwin D, SRMIST

Course Code	18AUC304J	Course Name	CAD ANALYSIS FOR AUTOMOTIVE ENGINEERS	Course Category	C	Professional Core	L	T	P	C
							3	0	2	4

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards			

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning		
CLR-1 :	Describe the various design concepts and modelling techniques				1	2	3
CLR-2 :	Provide knowledge on computer graphics				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)
CLR-3 :	Introduce the latest developments in CAD Packages and GD&T						
CLR-4 :	Understand the FEM concepts						
CLR-5 :	Demonstrate the analysis tools						
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:					
CLO-1 :	Create the design models by various techniques				1	85	80
CLO-2 :	Develop the model using various features				2	80	75
CLO-3 :	Apply GD & T in design of automobile components				3	85	80
CLO-4 :	Solve the real world engineering problems using FEA.				2	80	75
CLO-5 :	Analyze the problems using FEA commercial packages.				3	85	80

Program Learning Outcomes (PLO)														
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
H	M	H	M	L	M	M	H	M	H	H	H	H	H	H
H	M	M	L	L	M	M	M	H	H	L	H	H	H	H
H	H	H	H	H	M	H	M	M	M	H	H	H	H	H
H	H	H	H	M	M	M	M	M	M	M	H	H	H	H
H	H	H	H	H	M	M	M	H	M	M	H	H	H	H

	Introduction to CAD	Graphics Concepts (2D and 3D)	Software Packages and Recent Technology	FEM Fundamentals	Finite element Analysis
Duration (hour)	15	15	15	15	15
S-1	SLO-1 Introduction to CAD	Introduction to Coordinate system	Introduction to Software Packages	FEM Fundamentals - Introduction	Finite element Analysis - Introduction
	SLO-2 Product life cycle management	Model coordinate system,	Salient features of Software Packages	Degrees of freedom, h-convergence and p-convergence	Need for FEA in CAD Environment
S-2	SLO-1 Design models – pahl and beitz model	World coordinate system and Screen coordinate system	Technical comparison, Modules and tools	Need for Finite element method	Various stages of FEA - Preprocessing,
	SLO-2 Shigley model and Ohsuga model	Transformations in 2D and 3D	Need for data exchange standards and types	Nodes, element types	Solving and Post-processing
S-3	SLO-1 Geometric modelling – Introduction	Deriving transformation matrix for translation	Structure of STEP file system	Types of Constraints	Demonstration of the above using any one commercial packages
	SLO-2 Wireframe, surface and solid modelling	Deriving transformation matrix for scaling	Advantages and Disadvantages of STEP file system	Types of Boundary conditions	Structural analysis of beams and truss
S-4-5	SLO-1 LAB 1: Introduction to 2D sketch tool	LAB 3 : Introduction to various features for 3D Modelling	LAB 5 : 3D modelling of piston and connecting rod	LAB 7 : Exercises on Assembly of Knuckle joint	LAB 9 : Structural Analysis of truss and beams using ANSYS APDL
	SLO-2				
S-6	SLO-1 Constructive solid geometry	Deriving transformation matrix for Reflection	Structure of IGES file system	Steps in Finite element method	Introduction to modal analysis – Free Vibration
	SLO-2 Problems on Constructive solid geometry	Deriving transformation matrix for Rotation	Advantages and Disadvantages of IGES file system	Derivation of shape function	Forced Vibration
S-7	SLO-1 Boundary representation	Problems on basic transformations	Brief outline of feature technology	Solution techniques – Point collocation method	Brief outline of kinematic analysis
	SLO-2 Problems on Boundary representation	Concatenated and Inverse transformation	Classification of features	Sub domain and Least square method	Steps in Kinematic analysis
S-8	SLO-1 Operations – Booleans and Extrude	Problems on Concatenated and Inverse transformation Visibility techniques – Minimax test	Design by features	Galerkin method	Modelling of Four bar mechanism
	SLO-2 Demonstration of boolean and extrude using Solidworks		Applications of feature based modelling	Derivation of stiffness matrix	Kinematic analysis of Four bar mechanism

S 9-10	SLO-1	LAB 2 : Exercises on 2D sketch	LAB 4 : Exercises on 3D Modelling	LAB 6: Exercises on Assembly of Screw jack	LAB 8 : Exercises on Assembly of Universal joint	LAB 10 : Finite element analysis on connecting rod using ANSYS Workbench
	SLO-2					
S-11	SLO-1	Sweep and Revolve	Containment test	Applying features to various automotive components	Tutorial on Finite element problems involving stepped bar	Modelling of Single slider mechanism
	SLO-2	Demonstration of sweep and revolve using Solidworks	Hidden line removal – priority algorithm	Advantages and limitations of feature based modelling	Interpretation of the results	Kinematic analysis of Single slider mechanism
S-12	SLO-1	Basic entities – Line	Light source and Shading – Constant shading models	Introduction to GD & T	Tutorial on Finite element problems involving triangular element.	Modelling of an automotive components - 1
	SLO-2	Circle	Gourand and Phong shading models	Need of GD&T	Interpretation of the results	Finite element analysis of an automotive components - 1
S-13	SLO-1	Ellipse and	Color models – RGB and CMYK model	Geometrical tolerance	Tutorial on Finite element problems involving springs.	Modelling of an automotive components - 2
	SLO-2	Parabola	Rendering and Animation	Dimensional tolerance	Interpretation of the results	Finite element analysis of an automotive components - 2
S-14-15	SLO-1 SLO-2	Lab Assessment 1	Lab: Repeat class	Lab Assessment 2	Lab Assessment 3	LAB 11 : Kinematic Analysis of 4-bar mechanism using ANSYS Workbench

Learning Resources	1.Ibrahim Zeid, "CAD / CAM - Theory and Practice", Tata Mcgraw-Hill, New Delhi, 2009 2. Radhakrishnan. P "CAD / CAM / CIM " New age international, 2018 3. Mikell P. Groover, "CAD / CAM", Prentice Hall of India Private Limited, New Delhi, 2003	4.Newman and Sproull R. F., "Principles of interactive computer graphics", Tata Mcgraw-Hill, New Delhi, 2001 5.Chandupatla and Belagundu, "Introduction to Finite Element Methods in Engineering", Prentice Hall of India Private Limited, New Delhi, 2002
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
Level 2	Apply Analyze	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
Level 3	Evaluate Create	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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Course Code	18AUC305T	Course Name	DESIGN OF AUTOMOTIVE COMPONENTS	Course Category	C	Professional Core	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Design Data, PSG College of Technology, 2012		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 : Understand the basic knowledge of automotive components respective to design		1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 : Provide the idea of engineering materials selection		Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 : Provide knowledge of basic valves design		Expected Proficiency (%)	Problem Analysis
CLR-4 : Provides the knowledge on forces of connecting rod		Expected Attainment (%)	Design & Development
CLR-5 : Familiarize the design procedure of engine components			Analysis, Design, Research
			Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:
CLO-1 : Define the requirements and understand the automotive components	1 80 75
CLO-2 : Select suitable materials for automobile components	2 85 80
CLO-3 : Explain the procedure involved in design	3 85 80
CLO-4 : Familiarize with various design standards	3 80 75
CLO-5 : Design various automotive components to suit industrial needs.	3 85 80

Duration (hour)	Design Of Shaft	Design of Cylinder And Piston	Design of Connecting Rod	Design of Crankshaft	Design of valves
	9	9	9	9	9
S-1	SLO-1 Materials and Manufacturing of shaft	Introduction to Cylinder And Piston-	Introduction to Connecting Rod	Introduction to Crankshaft	Introduction to valves
	SLO-2 Materials and Manufacturing of shaft	Introduction to Cylinder And Piston-	Introduction to Connecting Rod	Introduction to Crankshaft	Introduction to valves
S-2	SLO-1 General Phases of design	Principal Parts of an IC Engine	Material selection for connecting rod	Introduction about crank shaft and its function in an I.C Engine.	Valve gear mechanism
	SLO-2 General Phases of design	Principal Parts of an IC Engine	Material selection for connecting rod	Introduction about crank shaft and its function in an I.C Engine.	Valve gear mechanism
S-3	SLO-1 Standard size of transmission shafts, stresses in shafts	Cylinder and Cylinder Liner	Forces Acting on the connecting rod	Materials selection for crankshaft	Types of valves
	SLO-2 Standard size of transmission shafts, stresses in shafts	Cylinder and Cylinder Liner	Forces Acting on the connecting rod	Materials selection for crankshaft	Types of valves
S-4	SLO-1 Shafts subjected to twisting moment only	Design of Bore,Length ,Thickness of cylinder head, studs size of the cylinder head	Dimensions of cross Section of the connecting rod	Bearing pressures and stresses in crankshaft	Design of size of valve port
	SLO-2 Shafts subjected to twisting moment only	Design of Bore,Length ,Thickness of cylinder head, studs size of the cylinder head	Dimensions of cross Section of the connecting rod	Bearing pressures and stresses in crankshaft	Design of size of valve port
S-5	SLO-1 Shafts Subjected to Bending Moment Only	Material for piston	Dimensions of cross Section of the connecting rod	Design Procedure for Crankshaft	Design of the valve disc
	SLO-2 Shafts Subjected to Bending Moment Only	Material for piston	Dimensions of cross Section of the connecting rod	Design Procedure for Crankshaft	Design of the valve disc
S-6	SLO-1 Shafts Subjected to combined Twisting Moment and Bending Moment	Design of critical parameters of piston design	Dimensions of the crank pin at the big end	Design of Centre Crankshaft When the crank is at dead centre	Design of maximum lift of the valve
	SLO-2 Shafts Subjected to combined Twisting Moment and Bending Moment	Design of critical parameters of piston design	Dimensions of the crank pin at the big end	Design of Centre Crankshaft When the crank is at dead centre	Design of maximum lift of the valve

S-7	SLO-1	Shafts Subjected to combined Twisting Moment and Bending Moment	Piston Rings	Dimensions of the piston pin at the small end	Design of Centre Crankshaft When the crank is at angle of maximum twisting moment	Design of valve stem diameter
	SLO-2	Shafts Subjected to combined Twisting Moment and Bending Moment	Piston Rings	Dimensions of the piston pin at the small end	Design of Centre Crankshaft When the crank is at angle of maximum twisting moment	Design of valve stem diameter
S-8	SLO-1	Shafts Subjected to Fluctuating loads	Piston Skirt	Size of bolts for securing the big end cap	Design of Overhung Crankshaft When the crank is at dead centre	Design of Pushrod
	SLO-2	Shafts Subjected to Fluctuating loads	Piston Skirt	Size of bolts for securing the big end cap	Design of Overhung Crankshaft When the crank is at dead centre	Design of Pushrod
S-9	SLO-1	Design of Shafts on the basis of Rigidity	Piston Pin	Thickness of the big end cap	Design of Overhung Crankshaft When the crank is at an angle of maximum twisting moment	Design of cross section of the push rod by rankine's formula
	SLO-2	Design of Shafts on the basis of Rigidity	Piston Pin	Thickness of the big end cap	Design of Overhung Crankshaft When the crank is at an angle of maximum twisting moment	Design of cross section of the push rod by rankine's formula

Learning Resources	1. Kulkarni S. G, "Machine Design", Tata McGraw-Hill Education, 2008. 2. Bhandari V, "Design of Machine Elements", Tata McGraw-Hill Education, 2010.	3. Khurmi, "A text book of Machine Design", S Chand publication, 2016. 4. Shigley J, "Mechanical Engineering Design", Tenth Edition, Mc Graw Hill, 2014.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
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Course Code	18AUC401J	Course Name	VEHICLE DYNAMICS	Course Category	C	Professional Core	L	T	P	C
							3	0	2	4

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning		
CLR-1 :	Learn about the sources, analysis and solution of problems pertaining to vehicular vibrations.				1	2	3
CLR-2 :	Learn about the sources and effects of dynamic forces acting on a vehicle system.						
CLR-3 :	Acquire fundamental knowledge about ride comfort, vehicle stability issues and formulate fundamental mathematical relations for such issues to achieve a better design of automotive systems.						
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)
CLO-1 :	Solve vibration problems with single degree of freedom				2	90	75
CLO-2 :	Interrelate the forces generated in the tire with tire slip phenomenon				2	80	80
CLO-3 :	Construct a mathematical model for vehicle suspension studies				3	85	80
CLO-4 :	Formulate the equation of motion of a vehicle in longitudinal direction				3	90	85
CLO-5 :	Predict the directional stability of vehicles based on driving conditions				2	85	80

Program Learning Outcomes (PLO)														
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
H	H	M	M	M	L	M	L	L	L	L	M	H	L	M
H	M	M	L	H	L	M	L	L	L	L	M	H	L	M
H	H	H	H	H	L	L	L	L	L	L	M	H	L	M
H	H	M	M	H	L	L	L	L	L	M	H	L	M	M
H	H	M	M	H	M	M	M	L	L	M	H	L	M	M

		Basics of Vibration	Tires	Vertical Dynamics	Longitudinal dynamics	Lateral dynamics
Duration (hour)		15	15	15	15	15
S-1	SLO-1	Understand the Basic concepts of vibration	Define the co-ordinate system for an automotive vehicle and tire	List the methods for assessing human tolerance to vibration	List the resistive forces to longitudinal motion of vehicles	List the various side forces acting on a vehicle
	SLO-2	Classify the types of vibration	State the various forces and moments acting in an automotive tire	Describe the criteria for ride comfort	Explain the resistive forces to longitudinal motion of vehicles	Explain the effect of the side forces on the vehicle
S-2	SLO-1	Recall harmonic motion principles	List the various causes of rolling resistance of tires	Categorize the vertical dynamics modeling of vehicles	Apply Newton's law of motion for longitudinal dynamics of vehicles	Define steady state condition in lateral vehicle dynamics
	SLO-2	Explain the procedure for vibration analysis	State the expression for rolling resistance of tires	Evaluate the equation of motion for the vertical dynamic models	Calculate maximum tractive effort from the equation of motion for longitudinal dynamics	Judge the steady state handling characteristics of a vehicle based on the value of under steer co-efficient
S-3	SLO-1	Express and derive equation of motion for Free vibration of single degree of freedom – damped and undamped	Understand the phenomenon of tire slip	Design passive suspension system in quarter car model	Discuss the components in driveline	List the motion variables influenced by steering input
	SLO-2	Infer the amplitude decrement factor as logarithmic decrement	Recognize the generation of slip angle due to side forces	Analyze passive suspension system in quarter car model	Apply driveline dynamics in analyzing longitudinal dynamics equation	Analyze the influence of steering input on motion variables
S 4-5	SLO-1	Lab 1: Analysis of vibration system in Simulink	Lab 4: Magic formula tire model State the magic formula tire model Represent the tire behavior using Magic formula	Lab 7: Half car model Recognize half car model of a vehicle Develop half car model in Simulink	Lab 10: Braking dynamics analysis using Car Maker Recall braking dynamics equation Analyze braking dynamics using Car Maker	Lab 13: Lateral dynamics analysis using Car Maker Recall lateral dynamics fundamentals Analyze lateral dynamics using Car Maker
	SLO-2	Recall the fundamentals of vibration systems Analyze the vibration system in Simulink				
S-6	SLO-1	Express and derive equation of motion for forced vibration of single degree of freedom – damped and undamped	Interpret the variation of longitudinal and lateral forces for various slip angles	Design semi active and active suspension systems in quarter car model	Calculate maximum acceleration for different drives	List the various tests to measure the handling characteristics of vehicles
	SLO-2	Apply the principle of base excitation to automotive vibration	Explain the concept of friction circle in tires	Analyze semi active and active suspension systems in quarter car model	Calculate reaction forces for different drives	Assess the handling characteristics of vehicles through various tests

S-7	SLO-1	Express and derive equation of motion for Free vibration of two degree of freedom – damped and undamped	Interrelate tractive effort with longitudinal slip of tires	Design passive suspension system in half car model	Derive an expression for load transfer while braking	Recognize the transient state conditions in the dynamic motion of vehicles
	SLO-2	Represent simple cases of automotive vibration as two degree of freedom system	Illustrate the relation between tractive effort and longitudinal slip of tires	Analyze passive suspension system in half car model	Derive an expression for load transfer while accelerating	Formulate the equation of motion in transient state
S-8	SLO-1	Examine automotive vibration problems as multi degree of freedom systems	Restate the generation of slip angle in tires	Design semi active and active suspension systems in half car model	Calculate the load distribution for three wheelers	Define the criteria for directional stability of vehicles
	SLO-2	Solve the multi degree of freedom system equation of motion for automotive vibrations	Diagram the cornering characteristics of tires	Analyze semi active and active suspension systems in half car model	Calculate the load distribution for four wheelers	Analyze the directional stability of vehicles through understeer co-efficient
S 9-10	SLO-1	Lab 2: Generation of road profile Identify the statistical method for road profile generation Create Simulink model for road profile generation	Lab 5: Quarter Car model Recognize quarter car model of a vehicle Develop quarter car model in Simulink	Lab 8: Shock absorber testing Recall the construction of a shock absorber Assess the shock absorber in a test rig	Lab 11: Active suspension study in Quanser test rig Recall active suspension concept Assess the active suspension test rig	Lab 14: Rollover analysis using Car Maker Recall vehicle roll over concept Analyze vehicle roll over using Car Maker
	SLO-2					
S-11	SLO-1	Understand modelling procedure	List the parameters for performance of tires on wet surfaces	Design passive suspension system in full car model	Predict the driving performance of vehicles from tractive effort value	Analyze the stability of a vehicle on a banked road
	SLO-2	Study the simulation of dynamic systems	Interpret the phenomenon of hydroplaning	Analyze passive suspension system in full car model	Analyze acceleration and braking performance of vehicles	Analyze the stability of a vehicle while taking turn
S-12	SLO-1	Show the variation of magnification factor with respect to frequency ratio	Demonstrate tire as a brush type model	Design semi active and active suspension systems in full car model	Diagram the ABS control loop	Understand the concept of roll center in vehicle dynamics
	SLO-2	Sketch the variation of vibrating system transmissibility with respect to frequency ratio	Demonstrate tire as a brush-string type model	Analyze semi active and active suspension systems in full car model	Illustrate the ABS control cycles with appropriate practical conditions	Understand the concept of roll axis in vehicle dynamics
S-13	SLO-1	Explain the principle of vibration absorbers	Model the tire empirically based on experimental data	Apply the PID control strategy to automotive suspension systems	Differentiate Traction Control System against ABS	Draw the single track model for a vehicle
	SLO-2	Classify the vibration measuring instruments	Present tire forces and moments as a function of slip phenomenon	Apply the skyhook and LQR control strategy to automotive suspension systems	Explain typical control situations for TCS action	Analyze the dynamics of a vehicle using single track model
S 14-15	SLO-1	Lab 3: Assessment 1	Lab 6: Assessment 2	Lab 9: Assessment 3	Lab 12: Repeat Class	Lab 15: University exam
	SLO-2					

Learning Resources	1. Mechanical Vibrations, Singiresu S Rao, 6 th edition, 2017, Pearson Education, USA 2. Theory of Ground Vehicles, J.Y. Wong, 4 th edition, John Wiley & Sons, New Jersey	3. Vehicle Dynamics and Control, Rajesh Rajamani, 2 nd edition, 2012, Springer, New York 4. Simulink Manual/Documentation, Car Maker manual/ Documentation
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
Level 2	Apply Analyze	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
Level 3	Evaluate Create	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Total	100 %		100 %		100 %		100 %		-	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.G.Giri ATALON, Giri@atalon.co.in.	1.Dr.V M Murugesan, PSG Tech, Vnm.auto@psgtech.ac.in	1. Dr K. Kamalakkannan SRMIST, kamalakk1@srmist.edu.in
2.Mr.RanjithSunderraj, Xitadel, ranjithsunderraj@xitadel.com	2. Dr.P D Jeyakumar, Crescent University, pdjeyakumar@crescent.education.	2.Mr.AJD.Nanthakumar, SRMIST, nanthakd@srmist.edu.in

Course Code	18AUC402L	Course Name	VEHICLE TESTING LABORATORY				Course Category	C	Professional Core										L	T	P	C					
																		0	0	2	1						
Pre-requisite Courses	Nil				Co-requisite Courses	Nil			Progressive Courses	Nil																	
Course Offering Department		Automobile Engineering				Data Book / Codes/Standards				Nil																	
Course Learning Rationale (CLR):		The purpose of learning this course is to:						Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Demonstrate the purpose of chassis dynamometers in vehicle testing.						Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLR-2 :	Understand the procedures involved in HVAC testing and servicing.																										
CLR-3 :	Analyze the various procedures involved in testing the steering and wheel geometry of an automobile.																										
CLR-4 :	Study the procedures involved in measuring the tailpipe emissions of an automobile.																										
CLR-5 :	Analyze the ignition pattern in an automobile.																										
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:						Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLO-1 :	Conduct performance tests on automobiles using chassis dynamometers.																										
CLO-2 :	Perform tests and servicing on automobile HVAC using modern equipment.																										
CLO-3 :	Identify and adjust any deviations in steering and wheel geometry of an automobile using modern tools and equipment.																										
CLO-4 :	Perform tail pipe emission testing and analyze the deviations on emissions in an automobile.																										
CLO-5 :	Interpret the ignition pattern of an automobile to find out any ignition system malfunction.						Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLO-1 :	Conduct performance tests on automobiles using chassis dynamometers.																										
CLO-2 :	Perform tests and servicing on automobile HVAC using modern equipment.																										
CLO-3 :	Identify and adjust any deviations in steering and wheel geometry of an automobile using modern tools and equipment.																										
CLO-4 :	Perform tail pipe emission testing and analyze the deviations on emissions in an automobile.																										
CLO-5 :	Interpret the ignition pattern of an automobile to find out any ignition system malfunction.																										
Duration (hour)	6		6		6		6		6		6		6		6		6		6		6		6		6		
S 1-2	SLO-1	Lab 1: Studying the performance of a two wheeler using Eddy current chassis dynamometer.			Lab 4: CLA-1	Lab 7: Performing dynamic wheel balancing, tyre removal and fitment on the given LMV tyre.			Lab 10: Determination of caster, camber, toe-in and toe-out of the given HMV using computerized wheel alignment system.			Lab 13: Analyzing the tail pipe emissions and smoke density of the given automobile using 5-gas analyzer and smoke meter.															
	SLO-2	Lab 2: Studying the performance of a car using a four wheeler chassis dynamometer.				Lab 8: CLA-2			Lab 11: Performing dynamic wheel balancing, tyre removal and fitment on the given HMV tyre.			Lab 14: Study of secondary ignition pattern of an automobile using an oscilloscope analyzer.															
S 3-4	SLO-1	Lab 3: Performing leak check and refrigerant refilling of the HVAC in an automobile.			Lab 6: Determination of caster, camber, toe-in and toe-out of the given LMV using 3D computerized wheel alignment system.	Lab 9: Performing headlight beam adjustment on the given automobile using computerized headlamp beam tester.			Lab 12: CLA-3			Lab 15: CLA-4															
	SLO-2	Lab 5: Determination of slide slip, suspension efficiency and brake efficiency using car test lane.																									
Learning Resources		1. Automotive Handbook- Robert Bosch GmbH, Wiley, 10 th edition, 2018.						2. SPACE S.r.l. Instruction manual Code M0216 - rev.1.1 (11/2012)						3. Bosch equipment instruction manuals.													
Learning Assessment																											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)										Final Examination (50% weightage)															
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#																			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	-	40%	-	30%	-	30%	-	30%	-	30%	-	30%	-	30%	-	30%	-	30%	-	30%	-	30%	-	30%	-	30%
Level 2	Understand	-	40%	-	30%	-	30%	-	30%	-	30%	-	30%	-	30%	-	30%	-	30%	-	30%	-	30%	-	30%	-	30%
Level 3	Apply	-	40%	-	30%	-	30%	-	30%	-	30%	-	30%	-	30%	-	30%	-	30%	-	30%	-	30%	-	30%	-	30%
Level 3	Analyze	-	40%	-	30%	-	30%	-	30%	-	30%	-	30%	-	30%	-	30%	-	30%	-	30%	-	30%	-	30%	-	30%
Level 3	Evaluate	-	20%	-	30%	-	30%	-	30%	-	30%	-	30%	-	30%	-	30%	-	30%	-	30%	-	30%	-	30%	-	30%
Level 3	Create	-	20%	-	30%	-	30%	-	30%	-	30%	-	30%	-	30%	-	30%	-	30%	-	30%	-	30%	-	30%	-	30%
	Total	100 %		100 %		100 %		100 %		100 %		100 %		100 %		100 %		100 %		100 %		100 %		100 %		100 %	
# CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,																											
Course Designers																											
Experts from Industry														Experts from Higher Technical Institutions										Internal Experts			
1. Mr.GovardhanaGiri, ATALON Product Centre PVT LTD giri@atalon.in.														1. Dr.M.Parthasarathy, Vel Tech, nparthasarathy@veltech.edu.in										1. Dr. Edwin Geo V, SRMIST			
2. Mr. K.Suresh, HAL, sureshhal82@gmail.com.														2. Dr.R.Ben Ruben, Sri Krishna College of Engineering, benrubenr@skcet.ac.in										2. Mr.Deepak M. SRMIST			

Course Code	18AUC350T	Course Name	COMPREHENSION	Course Category	C	Professional Core	L	T	P	C
							0	1	0	1

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 : Acquire skills to solve real world problems in Engineering Graphics Design, Engineering Mechanics and Mechanics of Solids		1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 : Acquire skills to solve real world problems in Machines and Mechanisms, Thermodynamics and Fluid Mechanics			
CLR-3 : Solve problems in Manufacturing Technology, Material Technology, Applied Thermal Engineering for Automotive Engineers			
CLR-4 : Solve problems in Automotive Engines, Vehicular Structures, Driveline Systems and Automotive Electrical and Electronics Systems			
CLR-5 : Acquire skills to solve real world problems in Design of Automotive components and CAD Analysis for Automotive Engineers			
CLR-6 : Acquire skills to solve real world problems for competitive examinations in Automobile and Mechanical Engineering			

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 : Practice and gain confidence, competence to solve problems in Engineering Graphics Design, Engineering Mechanics, Mechanics of Solids		3	85	80	H	H	H	L	L	L	L	L	L	L	L	L	M	L	M
CLO-2 : Practice and gain confidence and competence to solve problems in Machines and Mechanisms, Thermodynamics and Fluid Mechanics		3	85	80	H	H	M	L	L	L	L	L	L	L	L	L	M	M	M
CLO-3 : Solve problems in Manufacturing Technology, Material Technology and Applied Thermal Engineering for Automotive Engineers		3	85	80	H	H	M	L	L	L	L	L	L	L	L	L	M	M	M
CLO-4 : Solve problems in Automotive Engines, Vehicular Structures and Driveline Systems and Automotive Electrical and Electronics Systems		3	85	80	H	H	M	L	L	L	L	L	L	L	L	L	M	M	M
CLO-5 : Practice and gain confidence, competence to solve problems in Design of Automotive components, CAD Analysis for Automotive Engineers		3	85	80	H	H	H	L	L	L	L	L	L	L	L	L	M	L	M
CLO-6 : Practice and gain confidence and competence to solve problems in the broad domain of Automobile and Mechanical Engineering		3	85	80	H	H	M	L	L	L	L	L	L	L	L	L	M	M	M

Duration (hour)	3	3	3	3	3
S-1	SLO-1 Tutorial on Engineering graphics and design	Tutorial on Machines and Mechanisms	Tutorial on Manufacturing Technology for Automotive Engineers	Tutorial on Automotive Engines	Tutorial on Design of Automotive components
	SLO-2 Problem Solving	Problem Solving	Problem Solving	Problem Solving	Problem Solving
S-2	SLO-1 Tutorial on Engineering Mechanics	Tutorial on Thermodynamics	Tutorial on Material Technology	Tutorial on Vehicular Structures and Driveline Systems	Tutorial on CAD Analysis for Automotive Engineers
	SLO-2 Problem Solving	Problem Solving	Problem Solving	Problem Solving	Problem Solving
S-3	SLO-1 Tutorial on Mechanics of Solids	Tutorial on Fluid mechanics	Tutorial on Applied Thermal Engineering for Automotive Engineers	Tutorial on Automotive Electrical and Electronics Systems	Problem Solving
	SLO-2 Problem Solving	Problem Solving	Problem Solving	Problem Solving	Problem Solving

Learning Resources	1. R.S.Khurmi, J.K.Gupta, Mechanical Engineering: Conventional and Objective Types, S.Chand & Co., 2018	2. R.K.Jain, Conventional & Objective Type Question & Answers on Mechanical Engineering for Competitions, Khanna Publishers, 2014
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (100% weightage)								Final Examination	
		CLA – 1 (20%)		CLA – 2 (30%)		CLA – 3 (30%)		CLA – 4 (20%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	-	40%	-	30%	-	30%	-	30%	-	-
	Understand	-	40%	-	30%	-	30%	-	30%	-	-
Level 2	Apply	-	40%	-	40%	-	40%	-	40%	-	-
	Analyze	-	40%	-	40%	-	40%	-	40%	-	-
Level 3	Evaluate	-	20%	-	30%	-	30%	-	30%	-	-
	Create	-	20%	-	30%	-	30%	-	30%	-	-
	Total	100 %		100 %		100 %		100 %		-	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Jayaraman.R. BLG Logistics, jayaraman.r@bigparekh.com	1. Dr. M.Parthasarathy, Vel Tech, nparthasarathy@veltech.edu.in	Dr. C.Prabhu, SRMIST
2. Mr. Shanmuga Sundaram, RNTBCI, sankaran@mtbci.com	2. Dr.P.Nanthakumar, Amrita school of Engineering, p_nanthakumar@cb.amrita.edu	Dr. T.Prakash, SRMIST

ACADEMIC CURRICULA

Professional Core Courses

BIOTECHNOLOGY

Regulations - 2018



SRM INSTITUTE OF SCIENCE AND TECHNOLOGY

(Deemed to be University u/s 3 of UGC Act, 1956)

Kattankulathur, Kancheepuram, Tamil Nadu, India

Course Code	18BTC201J	Course Name	GENE MANIPULATION AND GENOMICS				Course Category	C	Professional Core										L 3	T 0	P 2	C 4		
Pre-requisite Courses	Nil		Co-requisite Courses	Nil		Progressive Courses	Nil																	
Course Offering Department		Biotechnology				Data Book / Codes/Standards			Nil															
Course Learning Rationale (CLR):			The purpose of learning this course is to:					Learning		Program Learning Outcomes (PLO)														
CLR-1 :	Discuss the basic concepts and principles of utilization of different expression vectors for cloning from the perspective of engineers					1 Level of Thinking (Bloom)	2 Expected Proficiency (%)	3 Expected Attainment (%)	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLR-2 :	Demonstrate the different strategies of gene cloning and construction of genomic and cDNA libraries								Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3	
CLR-3 :	Analyse the concepts of structural and functional genomics																							
CLR-4 :	Apply advanced cutting-edge technologies																							
CLR-5 :	Assess the applications of recombinant DNA technology in animals, plants and microbial organisms																							
CLR-6 :	Prepare engineering students to develop the strategies on altering gene expression in vitro and in vivo																							
Course Learning Outcomes (CLO):			At the end of this course, learners will be able to:					1	80	70	L	M	L	M				H		H	H	H	H	
CLO-1 :	Explain the foundations of modern biotechnology					2	85	75	H	H	H	H	H				H		H	H	H	H	H	
CLO-2 :	Design and conduct experiments involving genetic manipulation.					2	75	80	H	M	H	H	H				H		H	H	H	H	H	
CLO-3 :	Use versatile techniques in recombinant DNA technology.					2	85	80	H	H	H	H	H		M		H		H	H	H	H	H	
CLO-4 :	Describe the steps involved in the production of biopharmaceuticals in microbial and mammalian cell systems.					2	80	80	H	M	H	H	H	L	H		H		H	H	H	H	H	
CLO-5 :	Apply modern biotechnology in the different areas like medicine, microbes, environment and agriculture.					2	80	75	H	H	H	H	H		M		H		H	H	H	H	H	
CLO-6 :	Design the cloning experiments using routine and specialized vectors for such applications as plant transformation, protein expression and genomic DNA library construction etc.					2	80	75	H	H	H	H	H		M		H		H	H	H	H	H	
Duration (hour)		15		15		15		15		15		15		15		15		15		15		15		
S-1	SLO-1	Overview of cloning	DNA Library		DNA sequencing		Analysis of gene expression		Applications of cloning															
	SLO-2	DNA cloning vectors	Preparation of DNA Libraries		Principles of DNA sequencing		Transcription and translation		Medical applications															
S-2	SLO-1	Cell based DNA cloning	Genomic DNA library		Sanger's Dideoxy sequencing method		Post transcriptional and post translational regulations		Human and genetic diseases															
	SLO-2	Cell free DNA cloning	Overlapping and non-overlapping DNA fragments		Automated DNA sequencing		Methods for protein expression		DNA vaccines															
S-3	SLO-1	Plasmid vectors – pBR322	Choice of vectors		Next generation sequencing		Analysis of gene function		Gene therapy															
	SLO-2	pUC vector	Evaluation of genomic DNA library		Genome sequencing		Factors influencing gene expression		Study of gene function in vivo															
S-4	SLO-1	Lab 1: Restriction enzyme digestion of genomic DNA	Lab 4: Alkaline Phosphatase treatment for cloning		Lab 7: Transformation of recombinant vector in to E.Coli		Lab 10: Repeat/Revision of experiments		Lab 13: Qualitative and quantitative analyses of RNA															
	SLO-2	Phage vectors – Lambda insertion	cDNA library		Emulsion PCR		Manipulation of gene expression		Embryonic stem cells															
S-6	SLO-1	Lambda Replacement vector	Purification and separation of mRNA		Bridge PCR		Transcriptomics - Non-coding RNA		Applications in Embryonic stem cells															
	SLO-2	Cosmids	cDNA synthesis		RNA sequencing		Small RNAs, siRNAs		Transgenics															
S-7	SLO-1	M13 vector	cDNA library construction		Applications of NGS		MicroRNAs, lncRNA		Methods of producing transgenic mice															
	SLO-2	Phagemid	Evaluation of cDNA library		Labeling of nucleic acids		Expression in prokaryotic host cells		Over-expression															
S-8	SLO-1	pBluescript	Screening libraries		Random priming		Purification of expressed protein		Gene knock-in															
	SLO-2	Lab 2: Restriction enzyme digestion of Vector	Lab 5: Preparation of rDNA- Ligation of DNA fragment with cloning vector		Lab 8: Screening- Blue white selection		Lab 11: Expression in eukaryotic host cells		Lab 14: cDNA synthesis															
S-11	SLO-1	Yeast vectors	Polymerase chain reaction (PCR)		Nick translation and End labeling		Expression in eukaryotic host cells		Gene knock-out															
	SLO-2	Types of yeast vector	Semi quantitative PCR		RNA labeling		Mammalian expression vectors		Conditional knock-out															
S-12	SLO-1	YAC	RNA-PCR		Non-isotopic labeling		Mutagenesis		Genome editing															
	SLO-2	Expression vectors	Real time PCR		Structural genomics		in vitro mutagenesis		CRISPER-Cas9															

S-13	SLO-1	Restriction enzymes	Types of qRT-PCR	comparative genomics	Site directed mutagenesis	Guide RNA
	SLO-2	Linker and homopolymer tailing	Applications of PCR	Microarray	Methods for site directed mutagenesis	Gene inactivation
S	SLO-1	Lab 3: Purification of digested DNA by column purification	Lab 6: Preparation of Competent cell	Lab 9: Identification of recombinants-isolation of rDNA	Lab 12: RNA isolation	Lab 15: Quantitative PCR (Real time PCR)
14-15	SLO-2					

Learning Resources	1. Jeremy W. Dale and Malcolm von Schantz, "From Genes to Genomes," John Wiley and Sons Publications, 2002 2. Sandy-b-primrose, "Principles of Gene Manipulation and Genomics" Seventh Edition, 2012	3. S. B. Primrose and R. M. Twyman, "Principles of Gene Manipulation and Genomics" 7th Edition, Wiley-Blackwell, 2006
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Dr. G. N. Ramchand, Saksin Life sciences Pvt Ltd, Chennai, ramchand@saksinlife.com	Prof.. K Subramaniam, IITM, Chennai, subbu@iitm.ac.in	Dr. N.Selvamurugan, SRMIST
Dr. Karthik Periyasamy, Scientist I, Aurozymes Unit, Aurobindo Pharma Limited, Hyderabad, karthikmpk@gmail.com	Prof. R. B. Narayanan, SVCE, Chennai, rbn@svce.ac.in	Dr. S.Barathi, SRMIST

Course Code	18BTC202J	Course Name	BIOPROCESS ENGINEERING	Course Category	C	Professional Core	L	T	P	C
							3	0	2	4

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Biotechnology	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1:	Demonstrate the various operational modes of bioreactor	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2:	Illustrate about the various transport phenomena in bioprocess systems.	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3:	Demonstrate the monitoring and control of various process parameters in bioreactors.	Expected Proficiency (%)	Problem Analysis
CLR-4:	Analyze the design and operation of various industrially important bioreactor	Expected Attainment (%)	Design & Development
CLR-5:	Illustrate the various mathematical models of biological systems		Analysis, Design, Research
CLR-6:	Illustrate the transformation of bioprocess engineering approaches from laboratory scale to commercial scale		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1:	Analyze the various operations of the bioreactor and evaluating its performance.	2 80 70	H H H H H H H H H H H H H H H
CLO-2:	Discuss the fundamental knowledge on mechanisms of oxygen transfer in biological systems.	2 85 75	H H H H H H H H H H H H H H H
CLO-3:	Illustrate the procedures adopted for monitoring and control of process parameters in bioreactors.	2 75 80	H H H H M H H H H H H H H H H
CLO-4:	Discuss on the design and operation of bioreactors for the cultivation of microbial, plant and animal cell cultures.	2 85 80	H H H H H M H H H H H H H H H
CLO-5:	Explain the applicability of modeling preliminaries and software packages in bioprocess.	3 85 80	H H H H H M H H H H H H H H H
CLO-6:	Explain the engineering approaches for successful commercialization of bioprocess operations.	2 80 75	H H H H H M H H H H H H H H H

Duration (hour)	15	15	15	15	15
S-1	SLO-1	Introduction to ideal reactors	Molecular Diffusion	Bioreactor Instrumentation and Control	Bioreactor configurations for production of metabolites from microbial sources
	SLO-2	Ideal reactor types	Role of Diffusion in Bioprocessing	Monitoring of biochemical parameters	Stirred tank reactor
S-2	SLO-1	Ideal batch reactor - basics	Convective Mass Transfer	Instrumentation for Measurements of Active Fermentation	Packed bed reactor
	SLO-2	Performance equation: Ideal batch reactor	Oxygen Uptake in Cell Cultures	pH, temperature, and DO	Fluidized bed reactor
S-3	SLO-1	Ideal continuous reactor - basics	Oxygen Transfer in Fermenters	Chemical composition and exhaust gas analysis	Air lift loop reactor
	SLO-2	Performance equation: Ideal continuous reactor	Measuring Dissolved-Oxygen Concentrations	Water purity, pressure and mass	Case studies
S 4-5	SLO-1	Lab 1: Batch operation	Lab 4: Estimation of K _L a by sulphite oxidation method	Lab 7: Enzyme Production - Medium optimization by RSM	Lab 10: Repeat/Revision of experiments
	SLO-2				Lab 13: Analysis of various growth kinetic parameters of batch fermentation using Berkley Madonna software
S-6	SLO-1	Ideal plug flow reactor - basics	Estimating Oxygen Solubility	Mass flow rate, volumetric flow rate and broth level	Bioreactor configurations for production of metabolites from plant sources
	SLO-2	Performance equation: Ideal plug flow reactor	Mass-Transfer Correlations	Methods for on-line and off-line biomass estimation	Different types of bioreactors for plant cells, tissues and organs
S-7	SLO-1	Reasons for non-ideality in bioreactors	Measurement of K _L a	On-line analysis of other chemical factors	Light Introducing Bioreactors
	SLO-2	Measurement of non-ideality in bioreactors	Oxygen-Balance Method and Dynamic Method	State and parameter estimation techniques for biochemical process	Rotating Drum Bioreactor
S-8	SLO-1	Residence Time Distribution - Studies	Power correlation analysis for K _L a	Control system in bioreactor	Balloon-type bubble bioreactors
	SLO-2	Non-ideal bioreactors	Oxygen Transfer in Large Vessels	Regulatory and multivariable control	Scale-up
S 9-10	SLO-1	Lab 2: Fed batch operation	Lab 5: K _L a determination by dynamic gassing method	Lab 8: Repeat/Revision of experiments	Lab 11: Wine production
	SLO-2				Lab 14: Estimation of bacterial growth kinetic parameter using Curve Fitting tool in MATLAB

S-11	SLO-1	Axial Dispersion	Regime analysis of bioprocess	Computer-based data acquisition	Bioreactor configurations for production of metabolites from animal sources	Running simulation in MATLAB
	SLO-2	Dispersion Model	Mechanism of mixing in bioreactors	Artificial intelligence for the control of bioreactor systems	Cell culture - basics	Running simulation in SIMULINK
S-12	SLO-1	Application of dispersion model in design of continuous sterilizers	Scale-up of bioreactors	Application of Computer Control and Sensing Technologies for bioreactor systems	Hollow fibre reactors	Dynamic simulation studies
	SLO-2	Tanks-in-Series Model	Scale-up of bioreactors based on power consumption – Gassed	Flow injection analysis – Introduction	Perfusion culture systems	Process Flow sheeting
S-13	SLO-1	Conversion from Tanks-in-Series Model	Scale-up of bioreactors based on power consumption – Ungassed	Various transport system - FIA	Sedimentation column perfusion systems	Examples of various primary metabolites process flow diagram
	SLO-2	Summary - Types of models for non-ideal (real) reactors	Scale-up of bioreactors based on oxygen transfer	FIA applications	Bioreactor strategies for maximizing product formation	Examples of various secondary metabolites process flow diagram
S-14-15	SLO-1	Lab 3: Sterilization kinetics	Lab 6: KLa determination by power correlation analysis	Lab 9: Monitoring of process and kinetics parameters in enzyme production – Shake flask studies	Lab 12: Prediction of flow behavior in fermentation broth	Lab 15: Repeat/Revision of experiments
	SLO-2					

Learning Resources	1. Kargi. F., Shuler. M.L., "Bioprocess Engineering: Basic Concepts", 3 rd Edition, Prentice Hall, 2017. 2. Doran. P. M., "Bioprocess Engineering Principles", Academic press, 2012 3. Najafpour G., "Biochemical Engineering and Biotechnology", 2 nd Edition, Elsevier Science, 2015	4. Scott F.H., "Elements of Chemical Reaction Engineering", 5 th Edition, Pearson Education, Inc., 2015. 5. Burstein L., "Matlab® in Bioscience and Biotechnology, Woodhead Publishing, 2011 6. Schügerl K., Bellgardt K.-H., Bioreaction Engineering: Modeling and Control, Springer, 2000.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
Level 2	Apply Analyze	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
Level 3	Evaluate Create	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Dr. P. BalaKumaran, Proklean Technologies (P) Limited, Chennai, genbalu86@gmail.com	Prof. K Subramaniam, IITM, Chennai, subbu@iitm.ac.in	Dr. V. Vinoth Kumar, SRMIST
Dr. Karthik Periyasamy, Aurobindo Pharma Limited, Hyderabad, karthikmpk@gmail.com	Prof. R. B. Narayanan, SVCE, Chennai, rbn@svce.ac.in	Dr. M. Venkatesh Prabhu, SRMIST

Course Code	18BTC203J	Course Name	ANIMAL BIOTECHNOLOGY	Course Category	C	Professional Core	L	T	P	C
							3	0	2	4

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Biotechnology	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1:	Understand animal breeding,controlling characters and disorders	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2:	Develop an understanding about transgenic animals	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3:	Inculcate the understanding of cell culture technique and production of valuable products from them	Expected Proficiency (%)	Problem Analysis
CLR-4:	Emphasize on animal health thereby improving livestock production	Expected Attainment (%)	Design & Development
CLR-5:	Develop an understanding of alteration of animal body biological system		Analysis, Design, Research
CLR-6:	provide a basic understanding of animal biotechnology		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1:	Impart theoretical knowledge on breeding, Characteristics of animals and biological markers for genetic diseases	2 80 70	H H H H H H H H H H H H H H H H
CLO-2:	Acquire knowledge on Embryo transfer, fertilization methods and transgenic animals	2 85 75	H H H H H H H H H H H H H H H H
CLO-3:	Illustrate on various cell culture techniques and their applications	2 85 80	H H H H H H H H H H H H H H H H
CLO-4:	Explain on microbial infections of animal thereby rendering prophylaxis	2 85 80	H H H H H H H H H H H H H H H H
CLO-5:	Gain knowledge about improvement of animals to increase the yield and quality of animal products	3 85 80	H H H H H H H H H H H H H H H H
CLO-6:	Assess the knowledge on animal biotechnology for its applications	2 80 75	H H H H H H H H H H H H H H H H

Duration (hour)	15	15	15	15	15
S-1	SLO-1 Breed	Artificial insemination	Principles of sterile techniques and cell propagation	Vaccines for animal health	Use of biotechnology in livestock production
	SLO-2 Species	Super ovulation	Primary cell culture	Diseases in cattle:	Effects of Growth hormone
S-2	SLO-1 Different types of breeding: Pros & Cons	In vitro fertilization	secondary cell culture	Bacterial disease- symptoms and prevention	Manipulation of Growth hormone
	SLO-2 Inbreeding, Outbreeding	Embryo transfer	continuous cell lines	Viral disease -symptoms and prevention	Somatotropic hormone
S-3	SLO-1 Types of cross breeding	Embryo sexing	suspension cultures	Parasitic disease -symptoms and prevention	Recombinant Bovine Growth Hormone
	SLO-2 Up grading	Splitting and quality analysis of embryo	Chemically defined and serum free media for cell culture	Diseases in sheep & goat:	Thyroid hormone
S 4-5	SLO-1 Lab 1: Sterilization techniques for animal cell culture	Lab 4: Isolation and culture of Hepatocytes	Lab 7: Cell passaging	Lab 10: Mitochondrial staining by Rhodamine 123	Lab 13: Cytotoxicity-LDH assay
S-6	SLO-1 Choosing Traits in farm animals	Pregnancy diagnosis	Scaling up of monolayer culture	Bacterial disease- symptoms and prevention	Probiotics as growth promoters:
	SLO-2 Quantitative trait loci	Cryopreservation of embryo	Scaling up of suspension culture	Viral disease -symptoms and prevention	Ideal characteristics
S-7	SLO-1 Marker assisted selection	Vitrification	Contamination: sources, types and eradication	Parasitic disease -symptoms and prevention	Mode of action of probiotics
	SLO-2 Single locus marker- RFLP	Slow programmed freezing	Preservation of animal cells	Introduction to animal vaccination	uses of probiotics
S-8	SLO-1 Multilocus marker- AFLP, SSR	Cloning for conservation of endangered species- Pros & Cons	characterization of animal cells	Vaccine production using animal cells	Manipulation of lactation
	SLO-2 RAPD in farm animals	Gene transfer techniques	Species identification	Live vaccines	Mammogenesis
S 9-10	SLO-1 Lab 2: Preparation of cell culture media	Lab 5: Cell counting and Viability	Lab 8: Cryopreservation of cells	Lab 11: Nuclear staining by Propidium iodide	Lab 14: Culture and differentiation of L6 cells
S-11	SLO-1 DNA Finger printing in animals	Transgenic animals – importance & methods of producing it	Organotypic culture	killed vaccines	Lactogenesis
	SLO-2 Applications of molecular markers	Transgenic mice	Types of organ culture	Conjugate vaccines	Galactopoiesis

S-12	SLO-1	Chromosomal aberrations	Transgenic fish	Application of animal cell culture	Anti Idiotypic vaccines	Manipulation of rumen microbial digestive system
	SLO-2	Genetic disorders: Cattle	Molecular farming	Cell cytotoxicity and viability assays	Subunit vaccines	Methods for manipulation
S-13	SLO-1	Sheep & Goat	Expression of therapeutic proteins	Cell culture as source of therapeutic products	Recombinant vaccines	Manipulation of wool growth
	SLO-2	Horse	Animal as a bioreactor	Tissue plasminogen activator	DNA vaccines	Factors affecting wool quality in sheep
S 14-15	SLO-1	Lab 3: Isolation and culture of Splenocytes	Lab 6: Primary culture using Chick embryo	Lab 9: Revival of Cryopreserved cells	Lab 12: Cell viability assay using MTT	Lab 15: Determination of glucose assay by GOD-POD method
	SLO-2					

Learning Resources	1. Animal Biotechnology: Recent concepts and developments - P.Ramadas, MJP Publications, 2015. 2. Animal Biotechnology – M.M.Ranga, Illrd edition, 2007	3. Culture of animal cells; a manual of basic technique - R.Ian Freshney, Vth edition, Wiley publications, 2006. 4. Textbook of Animal Biotechnology – P.Ramadas & S.Meerarani, IInd edition, 2002.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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Dr. Karthik Periyasamy, Scientist I, Aurozymes Unit, Aurobindo Pharma Limited, Hyderabad, karthikmpk@gmail.com	Prof. R. B. Narayanan, SVCE, Chennai, rbn@svce.ac.in	Dr. S.Subhashini, SRMIST

Course Code	18BTC204T	Course Name	PROTEIN ENGINEERING AND PROTEOMICS	Course Category	C	Professional Core	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Biotechnology	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
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CLR-1:	Distinguish the organizational levels of protein structure.	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Appraise the structure-function correlation in selected proteins.																		
CLR-3:	Interpret the structural basis of catalytic mechanism of proteolytic enzymes.																		
CLR-4:	Construct 3D structure of protein from amino acid sequence.																		
CLR-5:	Discuss on the experimental techniques available for protein structure characterization.																		
CLR-6:	Express the structural similarities existing at basal level in a group of proteins with similar functions																		

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1:	Interpret the properties of protein based on the sequence	1	80	80	H	H	H	H		M	L	H	H	H	H	H	H	H	H
CLO-2:	Recognize the 3D orientation of proteins and its correlation to the function of the protein	2	85	75	H	H	H	H			M	H	H	H	H	H	H	H	H
CLO-3:	Design mutated proteins to obtain proteins with desired function	2	75	80	M	H	M	H	M	M		M	H	H	H	H	H	H	H
CLO-4:	Restate the biological significance of select group of proteins	2	85	80	H	H	H	H			H	L	H	H	H	H	H	H	H
CLO-5:	Explain the basics of available experimental techniques for resolving protein structure	3	85	75	H	H	H	H		M	H	H	H	L	H	H	H	H	H
CLO-6:	Devise strategies for prediction, modification and design novel proteins	2	80	80	H	H	H	H	L	M	M	M	H	H	H	H	H	H	H

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Structure of amino acids	Role of Transcription factors in gene expression	Types and uses of proteases	Difficulties in generating crystals of Protein	Introduction to proteomics
	SLO-2 Properties of amino acids	Significance of TATA-box binding proteins (TBP)	Mechanism of action of serine proteases	Methods of generating crystals	Difference between functional genomics and proteomics
S-2	SLO-1 Role of Glycine and Proline in structure determination	Structural elucidation of TBP	Significance of Catalytic triad in serine proteases	Braggs law	Importance of sequencing of protein
	SLO-2 Ramachandran plot and its significance.	Nature of interaction between TBP and DNA	Importance of oxyanion hole for the catalytic activity	Instrumentation setup for diffraction studies	Edmund sequencing method
S-3	SLO-1 Interactions that stabilize secondary structures	Structural elucidation of p53	Specificity of Trypsin towards cleavage of lysine and arginine amino acid bonds	Phase determination	Array based proteomics
	SLO-2 Structural features of alpha helix	Nature of interaction between p53 and DNA	Specificity of Chymotrypsin and subtilisin	Role of Fourier transformation to overcome phase problem	Two hybrid system
S-4	SLO-1 Types of alpha helices	Effect of mutations in the DNA binding domain of p53	Domains of Immunoglobulin	Multi-wavelength Anomalous Diffraction experiments	2D gel electrophoresis
	SLO-2 Parallel beta-strand structure	Effects of mutations in the oligomerization and Nuclear localization region	Class-switching in Immunoglobulins	Recent advances in diffraction studies	Advantages and limitations of 2D gel electrophoresis
S-5	SLO-1 Anti-parallel beta-strand structure	Structural elucidation of leucine zipper	Immunoglobulin fold	NMR principle	Mass Spectrometry - Principle
	SLO-2 Beta turns, loops and other secondary structures	Interaction of leucine zipper and DNA	Secondary structures in hyper-variable loop region	Instrumentation in NMR	Instrumental setup in MS
S-6	SLO-1 Super-secondary structures	Structure-function correlation in actin	Structural orientation in antigen binding site	NOE & NOE-COSY	Ionisation by MALDI
	SLO-2 Difference between motifs & domains	Structure-function correlation in myosin	Nature of interaction between antigen and antibody	Coupling constants	Ionisation by ESI & EI
S-7	SLO-1 Types of motifs	Role of ATP in muscular contraction	Significance of CDR3 loop in antibody	Chemical Shifts	Time of Flight concept & peptide mass fingerprinting
	SLO-2 Types of domains	Structural elucidation of GPCR	Mechanism of activation of T-Cell	Dipolar Coupling constants	Tandem MS and MS/MS

S-8	SLO-1	Monomeric and polymeric proteins	Types of GPCR	Prediction of 3D structure from amino acid sequence	Isothermal Titration Calorimetry (ITC) Principle	SALSA algorithm
	SLO-2	hydrophobic collapse & theories of folding	Mechanism of activation of GPCR	Homology modelling and threading	Instrumentation of ITC	De novo algorithms
S-9	SLO-1	Levinthal paradox	Structural elucidation of Tyrosine kinase receptor	Enhancing binding affinity of T4 lysozyme	Determination enthalpy, entropy and free energy	Revision of entire units
	SLO-2	Role of chaperons and heat shock proteins	Interactions that activate Tyrosine kinase receptor	Enhancing stability in T4 lysozyme	Prediction of binding energy and multiple binding sites by ITC	Revision of entire units

Learning Resources	1. Brandon.C, Tooze.J, "Introduction to Protein Structure", 2nd Edition - Garland Publishing, Taylor & Francis group, 1999. 2. Twyman. R. M, "Principles of Proteomics", Garland Scientific Publishers, 2004. 3. Chatwal. G. R, "Instrumental methods of Chemical Analysis", Himalaya Publishing House, 5 th Edition, 2011.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%) #			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
Level 2	Apply Analyze	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
Level 3	Evaluate Create	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Dr. P. BalaKumaran, Proklean Technologies (P) Limited, Chennai, genbalu86@gmail.com	Prof. K Subramaniam, IITM, Chennai, subbu@iitm.ac.in	Mr. S. Karthik, SRMIST
Dr. Karthik Periyasamy, Aurobindo Pharma Limited, Hyderabad, karthikmpk@gmail.com	Prof. R. B. Narayanan, SVCE, Chennai, rbn@svce.ac.in	Dr. Vasantha Rekha, SRMIST

Course Code	18BTC301J	Course Name	BIOSEPARATION TECHNOLOGY	Course Category	C	Professional core	L	T	P	C
							3	0	2	4

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Biotechnology	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
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CLR-1:	Know the importance of bio separation and its recovery economically	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Learn the separation of product from solid –liquid phase																		
CLR-3:	Know the techniques of isolation of bio-products																		
CLR-4:	Learn the methods of purification of products																		
CLR-5:	Learn the methods of polishing and formulation of products for packaging																		
CLR-6:	Familiarize with separation, isolation, purification, polishing and formulation techniques																		

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1:	Categories the products into various sectors	H	80	70	H	H	H	H	L				H	H	H	H	H	H	H
CLO-2:	Identify the unit operation for separation	H	90	80	H	H	H	H	L				H	H	H	H	H	H	H
CLO-3:	Adapt the best methods of isolation of products	H	80	80	H	H	H	H	L				H	H	H	H	H	H	H
CLO-4:	Identify the sophisticated equipment for purification	H	80	80	H	H	H	H	L				H	H	H	H	H	H	H
CLO-5:	Know the polishing and formulation of the products	H	80	90	H	H	H	H	L				H	H	H	H	H	H	H
CLO-6:	Acquired knowledge in down streaming of Biomaterials	H	90	90	H	H	H	H	L				H	H	H	H	H	H	H

Duration (hour)	15	15	15	15	15
S-1	SLO-1 Introduction to Bio- separation process	SLO-1 Solid –Liquid Separation	SLO-1 Isolation of products	SLO-1 Purification of products	SLO-1 Product Formulation
	SLO-2 Importance of bioseparation in biotechnological processes	SLO-2 Biomass and particulate debris separation techniques	SLO-2 Adsorption-Chemistry of adsorption	SLO-2 Diafiltration	SLO-2 Crystallization- Basic concepts
S-2	SLO-1 Problems and requirements of bio-product purification	SLO-1 Flocculation-Pretreatment of broth	SLO-1 Batch Adsorption	SLO-1 Electro dialysis	SLO-1 Crystallization principles
	SLO-2 Different sectors of products in biotechnology	SLO-2 The electric double layer	SLO-2 Problems	SLO-2 Isoelectric focusing	SLO-2 Batch crystallizers
S-3	SLO-1 Engineering analysis in Bio separation- Stages of Bio separation	SLO-1 Forces Between Particles and Flocculation by Electrolytes	SLO-1 Continuous stirred tank adsorption	SLO-1 Electrophoretic separation of protein	SLO-1 Continuous crystallizers
	SLO-2 Basic principles of Engineering analysis	SLO-2 The Schulze–Hardy Rule Flocculation Rate Polymeric Flocculants	SLO-2 Fixed bed adsorption	SLO-2 Solving Problems	SLO-2 Solving Problems
S-4-5	SLO-1 Lab1. Cell disruption by Sonication	SLO-1 Lab 4. Separation of cells by Flocculation	SLO-1 Lab 7. Extraction of protein by aqueous two phase extraction	SLO-1 Lab 10. Detection and Estimation of Ethanol by Gas Chromatography	SLO-1 Lab 13. Crystallization of bioproducts
	SLO-2				
S-6	SLO-1 Process and product quality	SLO-1 Sedimentation Principles	SLO-1 Extraction	SLO-1 Chromatography principles	SLO-1 Crystallizer design
	SLO-2 Criteria for process development	SLO-2 Sedimentation Methods and coefficients	SLO-2 Chemistry of Extraction	SLO-2 Instruments and practice	SLO-2 Scale-up
S-7	SLO-1 Process Economics and Cost analysis	SLO-1 Centrifugation	SLO-1 Batch Extraction	SLO-1 Normal phase chromatography	SLO-1 Drying- principles
	SLO-2 Solving Problems	SLO-2 Tubular centrifuge	SLO-2 staged Extraction	SLO-2 Reversed phase chromatography,	SLO-2 Adiabatic and Conduction drying
S-8	SLO-1 Chemical and application range of Bioproducts	SLO-1 Disk Centrifuge	SLO-1 Differential Extraction- aqueous two phase.	SLO-1 Ion exchange chromatography	SLO-1 Dryer description and operations-Vacuum shelf dryer
	SLO-2 Sectors of Products	SLO-2 Ultra Centrifuge	SLO-2 Three phase Extraction Super critical Extraction	SLO-2 Gel permeation chromatography	SLO-2 Batch Vacuum rotary dryer
S-9-10	SLO-1 Lab 2. Cell disruption by Enzymatic method	SLO-1 Lab 5. Cell separation by Batch Filtration	SLO-1 Lab 8. Protein separation by Ultra filtration	SLO-1 Lab 11. Protein separation by column chromatography	SLO-1 Lab 14. Freeze drying of Biomaterial
	SLO-2				
S-11	SLO-1 Cell disruption methods for intracellular products	SLO-1 Filtration	SLO-1 Precipitation	SLO-1 Bio affinity chromatography	SLO-1 Freeze dryer

	SLO-2	Physical Cell Disruption	Filter Media and Equipment's	Precipitation by salt, Non solvents and large scale precipitation	Hydrophobic interaction chromatography	Spray dryer
S-12	SLO-1	Chemical and Enzymatic cell disruption	Theory of filtration	Cross flow filtration	Chiral chromatography	Conduction drying
	SLO-2	Solving Problems	Batch Filtration	Micro and Ultra filtration	Analysis of purity	Problems
S-13	SLO-1	Mechanical Cell Disruption	Continuous Rotary filters	Design of Ultra filtration	Scale-up in chromatography	Adiabatic drying
	SLO-2	Solving Problems	Solving Problems	Solving Problems	Solving Problems	Solving Problems
S14-15	SLO-1	Lab 3. Cell disruption by High pressure Homogenizer	Lab 6. Cell separation by Centrifugation	Lab 9. Protein Concentration by salting out method	Lab 12. Protein separation by Gel Electrophoresis	Lab 15. Drying of Bioproducts
	SLO-2					

Learning Resources	1. Harrison. R.G., Todd. P., Rudge S.R, Petrides. D.P, "Bioseparation Science and Engineering" Oxford University press, 2003. 2. Belter. P.A., Cussler, E., "Bioseparations", Wiley, 1985. 3. Nooralabettu Krishna Prasad, "Downstream Process Technology: A New Horizon In Biotechnology", PHI Learning Private Limited 2013
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Dr. P. BalaKumaran, Proklean Technologies (P) Limited, Chennai, genbalu86@gmail.com	Prof. K Subramaniam, IITM, Chennai, subbu@iitm.ac.in	1 Dr.M.Venkatesh Prabhu SRM IST
Dr. Karthik Periyasamy, Aurobindo Pharma Limited, Hyderabad, karthikmpk@gmail.com	Prof. R. B. Narayanan, SVCE, Chennai, rbn@svce.ac.in	2 Dr. Y.Ravichandran SRM IST

Course Code	18BTC350T	Course Name	COMPREHENSION	Course Category	C	Professional Core			
						L	T	P	C
						0	1	0	1

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Biotechnology	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)															
CLR-1 :	Acquire skills to develop knowledge in biochemical principles				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLR-2 :	Acquire skills to solve real world problems in medical biotechnology				Thinking (Bloom)	Efficiency (%)	Attainment (%)	Knowledge	Analysis	Development	Design, Research	Usage	Future	Sustainability	Team Work	Communication	Finance	Learning					
CLR-3 :	Acquire skills in gene manipulation and recombinant DNA technology																						
CLR-4 :	Acquire skills in enzyme technology and bioremediation																						
CLR-5 :	Acquire skills in bioseparation technology																						
CLR-6 :	Acquire skills to solve real world problems in the broad domain of biotechnology																						

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Practice and gain confidence and competence to solve problems in biochemical principles	3	85	80	H	H	H	L	L	L	L	L	L	L	L	L	M	L	M
CLO-2 :	Practice and gain confidence and competence to solve problems in medical biotechnology	3	85	80	H	H	M	L	L	L	L	L	L	L	L	L	M	M	M
CLO-3 :	Practice and gain confidence and competence to solve problems in gene manipulation and recombinant DNA technology	3	85	80	H	H	M	L	L	L	L	L	L	L	L	L	M	M	M
CLO-4 :	Practice and gain confidence and competence to solve problems in enzyme technology and bioremediation	3	85	80	H	H	M	L	L	L	L	L	L	L	L	L	M	M	M
CLO-5 :	Practice and gain confidence and competence to solve problems in bioseparation technology	3	85	80	H	H	H	L	L	L	L	L	L	L	L	L	M	L	M
CLO-6 :	Practice and gain confidence, competence to solve problems in the domain of biotechnology and competitive examinations in biotechnology	3	85	80	H	H	M	L	L	L	L	L	L	L	L	L	M	M	M

Duration (hour)	3	3	3	3	3
S-1	SLO-1 Tutorial on biochemistry	Tutorial on genetics and gene manipulation	Tutorial on microbiology	Tutorial on bioprocess technology	Tutorial on bioinformatics
	SLO-2 Problem Solving	Problem Solving	Problem Solving	Problem Solving	Problem Solving
S-2	SLO-1 Tutorial on cell biology and molecular biology	Tutorial on immunology	Tutorial on plant biotechnology	Tutorial on medical biotechnology	Problem environmental biotechnology
	SLO-2 Problem Solving	Problem Solving	Problem Solving	Problem Solving	Problem Solving
S-3	SLO-1 Tutorial on bioseparation technology	Tutorial on pharmaceutical biotechnology	Tutorial on animal biotechnology	Tutorial on protein engineering	Tutorial on fermentation technology
	SLO-2 Problem Solving	Problem Solving	Problem Solving	Problem Solving	Problem Solving

Learning Resources	2. Pranav Kumar and Usha Mina, Life Sciences, Fundamentals and Practice, Pathfinder Publication, 2016
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (100% weightage)								Final Examination	
		CLA – 1 (20%)		CLA – 2 (30%)		CLA – 3 (30%)		CLA – 4 (20%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	-	40%	-	30%	-	30%	-	30%	-	-
	Understand	-	40%	-	40%	-	40%	-	40%	-	-
Level 2	Apply	-	40%	-	40%	-	40%	-	40%	-	-
	Analyze	-	20%	-	30%	-	30%	-	30%	-	-
Level 3	Evaluate	-	20%	-	30%	-	30%	-	30%	-	-
	Create	-	20%	-	30%	-	30%	-	30%	-	-
	Total	100 %		100 %		100 %		100 %		-	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. C. N. Ramchand, Saksin Life sciences Pvt Ltd, Chennai, ramchand@saksinlife.com	1. Prof. K Subramaniam, IITM, Chennai, subbu@iitm.ac.in	1. Dr. Vinoth Kumar, SRMIST
2. Dr. Karthik Periyasamy, Aurobindo Pharma Limited, Hyderabad, karthikmpk@gmail.com	2. Prof. R. B. Narayanan, SVCE, Chennai, rbn@svce.ac.in	2. Dr. Samuel Jacob, SRMIST

ACADEMIC CURRICULA

Professional Core Courses

CHEMICAL ENGINEERING

Regulations - 2018



SRM INSTITUTE OF SCIENCE AND TECHNOLOGY

(Deemed to be University u/s 3 of UGC Act, 1956)

Kattankulathur, Kancheepuram, Tamil Nadu, India

Course Code	18CHC301T	Course Name	CHEMICAL ENGINEERING THERMODYNAMICS	Course Category	C	Professional Core	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Chemical Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Understand the thermodynamics of mixtures and partial molar properties	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	acquire knowledge on fugacity and fugacity coefficient	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Analyze the phase equilibrium for ideal and non-ideal mixtures	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Acquire knowledge on fundamentals of reaction equilibrium and equilibrium constant	Expected Attainment (%)	Design & Development
CLR-5 :	Expose to application of specific topics in phase and reaction equilibrium		Analysis, Design, Research
CLR-6 :	Understand the phase and chemical reaction equilibrium		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	derive the partial molar properties in a mixture	1 80 70	H H
CLO-2 :	Estimate the fugacity and fugacity coefficient	2 80 70	H H
CLO-3 :	Estimate the degrees of freedom and intensive variable for phase equilibrium	2 70 65	H H
CLO-4 :	To find the equilibrium rate constant in a chemical reaction	2 80 70	H H L
CLO-5 :	Comprehend the phase equilibrium and multi-reaction equilibrium	2 70 65	H H L
CLO-6 :	Comprehend the applications of phase and reaction equilibrium	2 75 65	H H H L

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Review of fundamentals laws of thermodynamics and property relations.	Fugacity and Fugacity coefficient for pure species	Introduction to Phase Equilibrium	Introduction to Reaction Equilibrium
	SLO-2	Review of fundamentals laws of thermodynamics and property relations.	Fugacity and Fugacity coefficient for pure species	Introduction to Phase Equilibrium	Introduction to Reaction Equilibrium
S-2	SLO-1	Introduction to solution thermodynamics	Fugacity and Fugacity coefficient for species in solution	Duhem's Theorem	Reaction Coordinate
	SLO-2	Introduction to solution thermodynamics	Fugacity and Fugacity coefficient for species in solution	Duhem's Theorem	Reaction Coordinate
S-3	SLO-1	Partial molar properties – analytical and graphical	Fugacity coefficient correlations	VLE – qualitative behavior	Criteria for Reaction Equilibrium
	SLO-2	Partial molar properties – analytical and graphical	Fugacity coefficient correlations	VLE – qualitative behavior	Criteria for Reaction Equilibrium
S-4	SLO-1	Partial molar properties – analytical and graphical	Problem solving in fugacity evaluation	Simple models of Vapour Liquid Equilibrium	Standard Gibbs's Energy change and Equilibrium Constant
	SLO-2	Partial molar properties – analytical and graphical	Problem solving in fugacity evaluation	Simple models of Vapour Liquid Equilibrium	Standard Gibbs's Energy change and Equilibrium Constant
S-5	SLO-1	Problem solving in PMM	Ideal Solution Model	Problem solving on simple VLE	Effect of Temperature on Equilibrium Constant
	SLO-2	Problem solving in PMM	Ideal Solution Model	Problem solving on simple VLE	Effect of Temperature on Equilibrium Constant
S-6	SLO-1	Chemical potential and applications	Ideal Solution Model	Vapour Liquid Equilibrium with modified Raoult's Law	Evaluation of Equilibrium Constants
	SLO-2	Chemical potential and applications	Ideal Solution Model	Vapour Liquid Equilibrium with modified Raoult's Law	Evaluation of Equilibrium Constants

S-7	SLO-1	Ideal-gas mixture model	Lewis-Randall Rule	VLE from K-values	Equilibrium Conversions for single reactions	VLE from cubic equations of state
	SLO-2	Ideal-gas mixture model	Lewis-Randall Rule	VLE from K-values	Equilibrium Conversions for single reactions	VLE from cubic equations of state
S-8	SLO-1	Ideal-gas mixture model	Excess properties	Flash Calculations	Problem solving on reaction equilibrium	Equilibrium and Stability
	SLO-2	Ideal-gas mixture model	Excess properties	Flash Calculations	Problem solving on reaction equilibrium	Equilibrium and Stability
S-9	SLO-1	Problem solving with ideal gas mixture model	Excess Gibbs Energy and Activity coefficient	Problem solving	Problem solving on reaction equilibrium	Applications of Phase Equilibrium
	SLO-2	Problem solving with ideal gas mixture model	Excess Gibbs Energy and Activity coefficient	Problem solving	Problem solving on reaction equilibrium	Applications of Phase Equilibrium

Learning Resources	1. Smith. J.M., Van Ness. H.C, and Abbott, M.M., "Introduction to Chemical Engineering Thermodynamics", 7th Edition. McGraw Hill International Edition, 2005. 2. Rao . Y.V.C, "Chemical Engineering Thermodynamics", University Press (I) Ltd., Hyderabad, 1997. 3. Sandler. S "Chemical, Biochemical and Engineering Thermodynamics", 4th Edition, Wiley India, 2006.
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SLO – Session Learning Outcome

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. A. Subramaniam, PESCO Beam Environmental Solutions Pvt. Ltd.,	1. Dr. Lima Rose Miranda, Anna University, email: limamiranda2007@gmail.com	1 Dr. S. Sam David SRM Inst. of Science & Technology, samdavis@srmist.edu.in
2. Mr. S. T. Kalaimani, CPCL, Chennai	2. Dr. T. R. Sundararaman, Rajalakshmi Engineering College	2 Mr. V. Ganesh SRM Inst. of Science & Technology, ganesv@srmist.edu.in

Course Code	18CHC302T	Course Name	CHEMICAL REACTION ENGINEERING	Course Category	C	Professional core	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Chemical Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Understand the classifications and kinetics of chemical reactions	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	acquire knowledge on design aspects of ideal reactors	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Comprehend size comparison of reactors for single reactions and apprehend performance of multiple reactor system	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Familiarize product distribution and contacting patterns for multiple reactions	Expected Attainment (%)	Design & Development
CLR-5 :	Expose to the concept of thermodynamic aspects of chemical reactions		Analysis, Design, Research
CLR-6 :	understand the kinetics of chemical reaction, design aspects of reactors, multiple reaction kinetics and thermodynamics of reactions		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	1 80 70	H H
CLO-1 :	derive the rate equations and calculating kinetic parameters for various types of reactions	2 80 70	H H
CLO-2 :	derive performance equations and understand design aspects of ideal reactors	2 70 65	H H
CLO-3 :	compare the performance of single reactors and understand multiple reactors system	2 80 70	H H
CLO-4 :	identify the favorable conditions and suitable contacting patterns for multiple reactions	2 70 65	H H
CLO-5 :	realize the effect of temperature and pressure on chemical reactions	2 80 70	H H
CLO-6 :	calculate kinetic parameters, reactor design variables, multiple reactor performance, multiple reaction kinetics and thermodynamic parameters		H H

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Classification of chemical reactions and variables affecting the reaction rate	Integrated rate expressions for first order reaction for varying volume systems	problems based on plug flow reactor	Problems based on reactors of different types in series
S-1	SLO-2	Rate equation, concentration and temperature dependency of rate equation	Integrated rate expressions for zero order reaction for varying volume systems	problems based on plug flow reactor	Concept of recycle ratio and its relation to flow conditions
S-2	SLO-1	Concept of constant volume batch reactor and fractional conversion	Problems based on varying volume system	Relationship between Holding Time and Space Time for Flow Reactors	Derivation of performance equation for recycle reactor
S-2	SLO-2	Analysis of total pressure data obtained in a constant-volume System	Problems based on varying volume system	Space time and space velocity calculations	Recycle reactor problems
S-3	SLO-1	Method of Analysis of kinetic data	General aspects of reactor design	necessity for size comparison of reactors	objectives for analyzing multiple reactions
S-3	SLO-2	Method of Analysis of kinetic data	Broad classification of reactor types and applications	Comparison of performance of single mixed flow and plug flow reactors for the n th order reactions	Qualitative discussion about product distribution in parallel reactions
S-4	SLO-1	Integrated rate expressions for first order, second order and zero order reactions	Characteristics of three types of ideal reactors	Plug flow reactors in series and parallel	Contacting patterns for parallel reactions in non continuous operations
S-4	SLO-2	Integrated rate expressions for first order, second order and zero order reactions	Material balance equation for a system with reaction	problems based on PFR in series and parallel	Contacting patterns for parallel reactions in continuous flow operations
S-5	SLO-1	Problems based on kinetic datas	Derivation of performance equation for batch reactor	quantitatively evaluating the behavior of a series of 'N' equal-size mixed flow reactors for first order reaction	Quantitative Treatment of Product Distribution in parallel reactions
S-5	SLO-2	Problems based on kinetic datas	problems based on batch reactor	Effect of number of reactors on the performance	Concept of fractional yield and selectivity for parallel reactions
S-6	SLO-1	Rate expression for First-Order Reversible Reactions	problems based on batch reactor	Mixed Flow Reactors of Different Sizes in Series – procedure for finding the outlet composition	Problems based on parallel reactions

	SLO-2	Rate expression for First-Order Reversible Reactions	Space time and space velocity concept	Problems based on MFR in series	Problems based on parallel reactions	Optimum Temperature Progression; Operating lines for minimum reactor size.
S-7	SLO-1	Empirical Rate Equations of n^{th} Order reactions and calculation of time of complete conversion	Derivation of performance equation for mixed flow reactor (MFR)	Problems based on MFR in series	Problems based on parallel reactions	Fractional conversion in adiabatic operations
	SLO-2	Empirical Rate Equations of n^{th} Order reactions and calculation of time of complete conversion	problems based on mixed flow reactor	Problems based on MFR in series	Problems based on parallel reactions	Fractional conversion in adiabatic operations
S-8	SLO-1	Determination of overall order of irreversible reactions from the half – life data	problems based on mixed flow reactor	Determining the Best System for a Given Conversion using Maximization of Rectangles principle	Irreversible first order reaction in series and its rate equation	Fractional conversion in Non - adiabatic operations
	SLO-2	Problems based on constant volume system	nature and conditions for plug flow	Reactors of Different Types in Series; Conditions for best arrangement of a Set of Ideal reactors	Qualitative Discussion About Product Distribution for series reaction	Graphical representation of energy balance equation for adiabatic operation
S-9	SLO-1	Problems based on constant volume system	Derivation of performance equation for plug flow reactor (PFR)	Problems based on reactors of different types in series	Qualitative Discussion About Product Distribution for series reaction	Problem based on kinetic data for reversible reaction
	SLO-2	Introduction to varying volume batch reactor and expansion factor calculation	problems based on plug flow reactor	Problems based on reactors of different types in series	rule governing favorable product distribution for reactions in series	Problem based on kinetic data for reversible reaction

Learning Resources	<ol style="list-style-type: none"> 1. Octave Levenspiel, "Chemical Reaction Engineering", 3rd edition, John Wiley & Sons, 2011. 2. H. Scott Fogler, "Elements of Chemical Reaction Engineering", 4th edition, Prentice Hall PTR, 2006. 3. J. M. Smith, "Chemical Engineering Kinetics", 3rd edition, McGraw Hill International editions, New Delhi, 1981.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. A. Subramaniam, PESCO Beam Environmental Solutions Pvt. Ltd.,	1. Dr. Lima Rose Miranda, Anna University, email: limamiranda2007@gmail.com	1. Dr. M. Magesh Kumar SRM Inst. of Science & Technology, mageshkm@srmist.edu.in
2. Mr. S. T. Kalaimani, CPCL, Chennai	2. Dr. T. R. Sundararaman, Rajalakshmi Engineering College	2. Mr. V. Ganesh SRM Inst. of Science & Technology, ganeshv@srmist.edu.in

Course Code	18CHC303T	Course Name	MASS TRANSFER APPLICATIONS	Course Category	C	Professional Core	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Chemical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)															
CLR-1 :	Understand the basic principles of distillation, methods and types of distillation.				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLR-2 :	Gain knowledge on the design methods of distillation column.				Thinking (Bloom)	Efficiency (%)	Assessment (%)	Knowledge	Analysis	Development	Design, Research	Usage	Culture & Sustainability			Team Work	Communication	Finance	Innovation				
CLR-3 :	Analyze the difference between liquid – liquid extraction and leaching.																						
CLR-4 :	Have an insight on mechanism of adsorption and crystallization.																						
CLR-5 :	Understand the difference between MF,U.F,NF and RO.																						
CLR-6 :	Gain knowledge on the mass transfer process principles																						

Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			Level of TT	Expected	Expected	Engineering	Problem An	Design &	Analysis,	Modern To	Society &	Environme	Ethics	Individual	Communit	Project Mg	Life Long	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Calculate product rates and composition based on batch and flash distillation.	2	80	75	H	H	H	H												H	H	
CLO-2 :	Apply McCabe Thiele method and determine number of stages in a distillation column.	2	80	75	H	H	H	H												H	H	M
CLO-3 :	Calculate percentage recovery of solute and number of stages for liquid – liquid extraction operation.	2	80	70	H	H	H	H												H	H	
CLO-4 :	Select adsorbents for appropriate applications.	2	80	75	H	H	H	H												H	H	
CLO-5 :	Analyze and apply appropriate membrane separation operation.	2	80	75	H	H	H	H												H	H	
CLO-6 :	Express the knowledge of mass transfer and its applications	2	80	75	H	H	H	H												H	H	M

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction to Distillation	Design of distillation column - McCabe-Thiele method, Assumptions	Introduction to liquid – liquid extraction, General principles of extraction	Introduction to adsorption	Introduction to membrane separation processes
	SLO-2	Principle, Relative Volatility	Enriching section operating line	Choice of solvent	Characteristics of adsorbents	
S-2	SLO-1	Equilibrium Curve	Stripping section operating line	Working principle of extraction equipments: mixer-settlers	Commercial adsorbents, preparation	Classification of membrane separation processes
	SLO-2	Methods of Distillation: without reflux and with reflux, Types of distillation	q line	Packed tower extractors	Application, regeneration	
S-3	SLO-1	Flash Distillation	Feed conditions	Agitated tower extractors	Langmuir Adsorption isotherms	Membrane modules
	SLO-2	Equation of operating line	Condensor and reboiler duty	Pulsed column extractors.	Freundlich Adsorption isotherms	
S-4	SLO-1	Problem Solving	Reflux ratio, total reflux, minimum reflux and optimum reflux	Percentage extraction calculation for single stage operations when liquids are insoluble.	Fixed bed adsorbents.	Microfiltration and its applications
	SLO-2	Problem Solving	Fenske's equation	Percentage extraction calculation for multistage crosscurrent operations when liquids are insoluble.		
S-5	SLO-1	Simple batch Distillation	Problem Solving	Minimum solvent rate for counter current operations.	Introduction to crystallization	ultra filtration and its applications
	SLO-2	Rayleigh's equation	Problem Solving	Number of theoretical stages for continuous countercurrent, multistage extraction operation when liquids are insoluble.	Yield concept, methods of super saturation. Nucleation and Crystal growth.	
S-6	SLO-1	Problem Solving	Problem Solving	Problem Solving	Continuous vacuum crystallizer, construction, working and applications.	Nano filtration and its applications
	SLO-2	Problem Solving	Problem Solving	Problem Solving		
S-7	SLO-1	Steam Distillation	Introduction to Ponchon -Savarit method	Problem Solving	Draft tube-baffle crystallizer, construction, working and applications.	Osmosis – Reverse Osmosis and its applications
	SLO-2	Conditions, Applications		Problem Solving		
S-8	SLO-1	Vacuum Distillation	Azeotropic distillation	Problem Solving	Swenson-walker crystallizer, construction, working and applications.	Dialysis - Electro Dialysis and its applications
	SLO-2	Conditions, Applications	Selection of Entrainer and solvent	Problem Solving		

S-9	SLO-1	Continuous distillation	Extractive distillation	Introduction to Leaching, factors affecting leaching.	Material and Energy balance calculations in batch crystallizers	Ion Exchange principles, types and its applications
	SLO-2	Working of a continuous distillation column	Comparison of Azeotropic Distillation and Extractive Distillation	Bollman extractor		

Learning Resources	<ol style="list-style-type: none"> 1. Robert E. Treybal, "Mass-Transfer Operations", 3rd Edn., McGraw Hill Education (India) Edition, 2012 2. Warren L. McCabe, Julian C. Smith and Peter Harriott, "Unit Operations of Chemical Engineering", 7th Edn., McGraw Hill Education (India) Edition, 2014 . 3. Christie John Geankoplis, "Transport Processes and Separation Process Principles (Includes Unit Operations)", 4thEdn., Pearson India Education Services Pvt. Ltd., 2015 4. Binay K. Dutta, "Principles of Mass transfer and Separation Processes", Prentice- Hall of India, New Delhi, 2007.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. A. Subramaniam, PESCO Beam Environmental Solutions Pvt. Ltd.,	1. Dr. Lima Rose Miranda, Anna University, email: limamiranda2007@gmail.com	1 Ms.E.POONGUZHALI SRM Inst. of Science & Technology, poonguze@srmist.edu.in
2. Mr. S. T. Kalaimani, CPCL, Chennai	2. Dr. T. R. Sundararaman, Rajalakshmi Engineering College	2 .Dr. K.SOFIYA SRM Inst. of Science & Technology, sofiyak@srmist.edu.in

Course Code	18CHC304T	Course Name	CHEMICAL PROCESS TECHNOLOGY	Course Category	C	Professional Course	L	T	P	C
							4	0	0	4

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Chemical Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Provide an overview of the essential features of chemical process industries	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Expose the learners to read and abstract the process flow diagrams		
CLR-3 :	Enable the learners to apply the concept of upstream and downstream processes associated in industrial production processes		
CLR-4 :	Familiarize the sequence of unit operations and unit processes in converting a raw material into consumer products		
CLR-5 :	Understand the various raw materials, processing methods and the applications of end products.		
CLR-6 :	Outline the general principles applied in studying a chemical process industry in which the process industries start with an ore or other raw material and end up with a product of useful to consumers through series of chemical and physical changes		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	
CLO-1 :	Realize the role of chemical engineers in process industries	1 80 75	M
CLO-2 :	Represent the process of conversion of raw material into useful products through process flow diagram	2 80 70	H
CLO-3 :	Recognize the significance of unit operations and unit processes	1 80 75	H L L
CLO-4 :	Apply the general principles, read, analyze, abstract and draw the process flow diagrams	3 80 70	H L L
CLO-5 :	Understand the big picture of chemical industries and the operations carried out in it	1 80 75	H
CLO-6 :	Appreciate the importance of chemical engineers role in diverse chemical industries	1 80 75	M L L

Duration (hour)	12	12	12	12	12
S-1	SLO-1	Overview of chemical industry – Global and Indian Scenario	Overview of fertilizer manufacturing sectors in India	Introduction to natural products industries	Overview of the petroleum refineries and its products
	SLO-2	Overview of chemical industry – Global and Indian Scenario	Overview of fertilizer manufacturing sectors in India	Edible and essential oils	Overview of the petroleum refineries and its products
S-2	SLO-1	Description of block and process flow diagrams in chemicals production	Introduction to commercial methods available to produce ammonia and its applications	Process description of edible oil extraction	Flow sheet of refinery operations
	SLO-2	Description of block and process flow diagrams in chemicals production	Manufacture of synthetic ammonia	Process description for extraction and purification of edible oil	Pyrolysis, Cracking, Reforming
S-3	SLO-1	Unit operations involved in chemicals production	Nitric acid – commercial methods available to produce nitric acid and its applications	Process description for the hydrogenation of edible oil to produce vanaspathi	Overview of synthetic organic chemicals
	SLO-2	Unit processes involved in chemicals production	Manufacture of nitric acid	Process description for the hydrogenation of vegetable oil to produce vanaspathi	Overview of synthetic organic chemicals
S-4	SLO-1	Introduction to inorganic chemicals – Chlor-alkali industries	Urea - commercial methods available to produce urea and its applications	Outline of soaps, detergents and glycerin	Introduction to Methane and synthesis gas
	SLO-2	Applications of different products from Chlor- alkali industries	Manufacture of urea	Manufacture of soaps and glycerin	Steam reforming for synthesis gas
S-5	SLO-1	Different processes involved in the manufacture of soda ash	Overview of phosphorus industries	Short notes on detergents	Manufacture of Ethylene, acetylene and propylene
	SLO-2	Manufacture of soda ash by Solvay process	Phosphate rock and the products from phosphate rock	Summary of edible oil, soaps, and detergents	Properties and end uses of
S-6	SLO-1	Processes involved in the manufacture chlorine and caustic soda	Manufacture of ammonium phosphate	Introduction to pulp and paper industries	Manufacture of aromatic compounds BTX
	SLO-2	Manufacture of Chlorine and caustic soda by electrolysis process	End uses of ammonium phosphates	Introduction to pulp and paper industries	Overview of the BTX and their applications

S-7	SLO-1	Mining of sulfur: Frasch Process	Manufacture of diammonium phosphate	Preparation of wood pulp by sulfate (kraft) process	Production of aromatic chemicals - Benzene, toluene, xylene.	Manufacture of Phenol Formaldehyde
	SLO-2	Applications of Sulfur	End uses of diammonium phosphates	Manufacture of Pulp and Paper from Kraft process	Production of aromatic chemicals - Benzene, toluene, xylene.	Overview of polyamides and polyesters
S-8	SLO-1	Introduction to sulfuric acid	Superphosphate and its applications	Chemical recovery from black liquor	Overview of synthetic, intermediate and end chemicals	Manufacture of Polyamides (Nylon 66)
	SLO-2	Various processes involved in sulfuric acid production	Manufacture of Super phosphate	Paper formation in Paper machine section of pulp and paper industry	Overview of synthetic, intermediate and end chemicals	Uses of Nylon 66
S-9	SLO-1	Manufacture of sulfuric acid	Triple super phosphate and its applications	Summary of pulp and paper production	Methanol and its uses	Manufacture of Polyester
	SLO-2	Manufacture of sulfuric acid	Manufacture of Triple super phosphate	Summary of pulp and paper production	Manufacture of Methanol	Uses of polyester
S-10	SLO-1	Introduction to silicate industries	Introduction to Potassium chloride industries	Overview of sugar production	Manufacture of Formaldehyde	Manufacture of Viscose rayon
	SLO-2	Ceramics and Glass products from silicate industries	Introduction to Potassium chloride industries	Manufacture of sugar from cane sugar	Formaldehyde and its uses	End uses of viscose rayon
S-11	SLO-1	Overview of cement and cement industries	Potassium chloride and its uses	Maize and its application	Ethylene dichloride and its applications	About natural and synthetic rubber
	SLO-2	Ore beneficiation for cement industries	Manufacture of potassium chloride	Manufacture of maize	Manufacture of ethylene dichloride	Processes for the production of SBR
S-12	SLO-1	Manufacture of Portland cement	Potassium sulphate and its uses	Summary of edible oil, soaps, pulp and paper and	Manufacture of vinyl chloride	Summary of all the manufacturing processes studied in the course
	SLO-2	Manufacture of Portland cement	Manufacture of potassium chloride	Summary of edible oil, soaps, pulp and paper and	Applications of vinyl chloride	Summary of all the manufacturing processes studied in the course

Learning Resources	1. GopalaRao. M. and Marshall Sittig, "Dryden's Outlines of Chemical Technology", 3rd Edn., East- West Press, New Delhi, 2008 2. George .T Austin, "Shreve's Chemical Process Industries", 5th Edn., 5 th Reprint, McGraw-Hill International Editions, Singapore, 2015 3. Kirk-Othmer, Encyclopedia of Chemical Technology, 27 Volume set, John Wiley, 2004. 4. Jacob A. Moulijn, MichielMakkee, Annelies E. van Diepen, "Chemical Process Technology", 2 nd Edition, John Wiley, 2013
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. A. Subramaniam, PESCO Beam Environmental Solutions Pvt. Ltd.,	1. Dr. Lima Rose Miranda, Anna University, email: limamiranda2007@gmail.com	1 Dr. S. Balasubramanian SRM Inst. of Science & Technology, balasubs@srmist.edu.in
2. Mr. S. T. Kalaimani, CPCL, Chennai	2. Dr. T. R. Sundararaman, Rajalakshmi Engineering College	2 Mr. K. Selvam SRM Inst. of Science & Technology, selvamk@srmist.edu.in

Course Code	18CHC305L	Course Name	CHEMICAL ENGINEERING LAB II	Course Category	C	Professional Core				L	T	P	C
										0	0	4	2

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Chemical Engineering	Data Book / Codes/Standards	Heat and mass transfer data book		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Provide the students the first hand experience of verifying various theoretical concepts learnt in heat and mass transfer. To Understand heat transfer mechanism, and determine thermal conductivity.				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Determine the heat transfer coefficient in natural and forced convection. Design the double pipe and shell and tube heat exchanger. Determine the effectiveness of the heat exchanger.				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Determine the Stefan-Boltzmann law constant and emissivity of a real surface (gray surface).																					
CLR-4 :	Verify the Rayleigh's equation in simple bath distillation. Determine the vapour efficiency for steam distillation. Determine the VLE data																					
CLR-5 :	Study the drying characteristics. Determine the recovery of solute by simple leaching process. Verify the Freundlich Adsorption isotherm.																					
CLR-6 :	Understand the Equilateral triangular diagram for three component system.																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	Determine thermal conductivity of a material.				2	80	75	H	H	M	M									H	H	L
CLO-2 :	Determine the heat transfer coefficient for natural and forced convection. Determine the effectiveness of a heat exchanger				2	80	75	H	H	M	M									H	H	L
CLO-3 :	Determine the Stefan-Boltzmann law constant and emissivity				2	80	75	H	H	M	M									H	H	L
CLO-4 :	Verify the Rayleigh's equation. Determine the vapour efficiency				2	80	75	H	H	M	M									H	H	L
CLO-5 :	Determine the recovery of solute by leaching. Verify the adsorption isotherm				2	80	75	H	H	M	M									H	H	L
CLO-6 :	Draw the equilateral triangular diagram for three component system.				2	80	75	H	H	M	M									H	H	L

Duration (hour)	12	12	12	12	12
S 1-4	SLO-1 SLO-2	Introduction to all the experiments	Heat transfer by natural convection	Determination of emissivity	Drying characteristics
S 5-8	SLO-1 SLO-2	Heat transfer through Composite lagged pipe	Shell and tube heat exchanger	Stefan-Boltzmann apparatus	Estimation of percentage recovery of solute for single stage leaching
S 9-12	SLO-1 SLO-2	Heat transfer by forced convection	Parallel flow and counter current flow Heat exchanger	Verification of Rayleigh equation for simple batch distillation	Estimation of percentage recovery of solute for multi stage leaching
					Verification of Freundlich Adsorption isotherm
					Phase diagram for three component system
					Determination of vapor efficiency for simple steam distillation

Learning Resources	1. Warren L. McCabe, Julian C. Smith and Peter Harriott, "Unit Operations of Chemical Engineering", 7th Edn., McGraw Hill Education (India) Edition, 2014 2. Robert E. Treybal, "Mass-Transfer Operations", 3rd Edn., McGraw Hill Education (India) Edition, 2012 3. Binay K Dutta, "Heat Transfer: Principles and Applications", PHI Publishers, Delhi, 2010 4. Laboratory Manual
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	-	40 %	-	30 %	-	30 %	-	30 %	-	30%
	Understand	-	40 %	-	30 %	-	30 %	-	30 %	-	30%
Level 2	Apply	-	40 %	-	40 %	-	40 %	-	40 %	-	40%
	Analyze	-	40 %	-	40 %	-	40 %	-	40 %	-	40%
Level 3	Evaluate	-	20 %	-	30 %	-	30 %	-	30 %	-	30%
	Create	-	20 %	-	30 %	-	30 %	-	30 %	-	30%
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. A. Subramaniam, PESCO Beam Environmental Solutions Pvt. Ltd.,	1. Dr. Lima Rose Miranda, Anna University, email: limamiranda2007@gmail.com	1Ms.E.Kavitha SRM Inst. of Science & Technology, kavithae@srmist.edu.in
2. Mr. S. T. Kalaimani, CPCL, Chennai	2. Dr. T. R. Sundararaman, Rajalakshmi Engineering College	2 Dr. K.Sofiya SRM Inst. of Science & Technology, sofiyak@srmist.edu.in

Course Code	18CHC306T	Course Name	TRANSPORT PHENOMENA	Course Category	C	Professional Core	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Chemical Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Understand the chemical and physical transport processes and their mechanism.	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Familiarize various aspects of velocity, temperature and a concentration distribution in laminar and turbulent flow.	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	To do heat, mass and momentum transfer analysis.	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Analyze industrial problems along with appropriate approximations and boundary conditions.	Expected Attainment (%)	Design & Development
CLR-5 :	Formulate the differential forms of the equations of change for momentum, heat and mass transfer problems for steady-state flows.		Analysis, Design, Research
CLR-6 :	Understand the conservation equations and its application for any process		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Identify and describe mechanisms of transport phenomena in laminar flow systems.	2 85 75	H M M
CLO-2 :	Make appropriate connections between the equations of change and physical phenomena in given systems involving momentum.	2 80 75	H M M
CLO-3 :	Ability to analyze velocity distributions in turbulent flow and industrial problems along with appropriate approximations.	2 85 75	H M M
CLO-4 :	Formulate and solve differential equations of heat transfer to calculate temperature distributions.	2 85 80	H M M
CLO-5 :	Formulate and solve differential equations of mass transfer to calculate concentration distributions.	2 85 80	H M M
CLO-6 :	Apply the conservation equation for the micro and macro systems	3 80 70	H M M

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Velocity distribution in laminar flow	Equation of change for isothermal process	Velocity distribution in turbulent flow	Thermal conductivity and the mechanisms of energy transport	Diffusivity and the Mechanisms of Mass Transport
	SLO-2 Introduction - Generalization of Newton's Law of Viscosity	Equation of change for isothermal process	Interphase transport in isothermal systems	Temperature and pressure dependence of thermal conductivity	Fick's law of binary diffusion (Molecular Mass Transport)
S-2	SLO-1 Pressure and temperature dependence of viscosity.	The equation of continuity	Comparisons of laminar and turbulent flows	Shell energy balances and temperature distributions in Solids and laminar flow, boundary conditions	Temperature and pressure dependence of diffusivities
	SLO-2 Shell momentum balances, boundary conditions, introduction to vector analysis	The equation of continuity	Comparisons of laminar and turbulent flows	Shell energy balances and temperature distributions in Solids and laminar flow, boundary conditions	Concentration distributions in solids and in laminar flow, boundary conditions
S-3	SLO-1 Shell momentum balances and velocity distributions: flow of a falling film.	The equation of motion: Eulers equation	Time-smoothed equations of continuity for incompressible fluids	Heat conduction with an electrical heat source	Diffusion through a stagnant gas film
	SLO-2 Shell momentum balances and velocity distributions: flow of a falling film.	The equation of motion: Eulers equation	Time-smoothed equations of continuity for incompressible fluids	Heat conduction with an electrical heat source	Diffusion through a stagnant gas film
S-4	SLO-1 Shell momentum balances and velocity distributions: flow through a circular tube	The equations of change in terms of the substantial derivative : Navier Stokes equation	Time-smoothed equations of motion for incompressible fluids	Heat conduction through composite plane wall	Diffusion with a homogeneous chemical reaction
	SLO-2 Shell momentum balances and velocity distributions: flow through a circular tube	The equations of change in terms of the substantial derivative : Navier Stokes equation	Time-smoothed equations of motion for incompressible fluids	Heat conduction through composite plane wall	Diffusion with a homogeneous chemical reaction
S-5	SLO-1 Shell momentum balances and velocity distributions: flow through an annulus	Applications of equation of motion	Empirical expressions for the turbulent momentum flux	Heat conduction through composite cylindrical wall	Diffusion and chemical reaction inside a porous catalyst
	SLO-2 Shell momentum balances and velocity distributions: flow through an annulus	Applications of equation of motion	Empirical expressions for the turbulent momentum flux	Heat conduction through composite cylindrical wall	Diffusion and chemical reaction inside a porous catalyst

S-6	SLO-1	Shell momentum balances and velocity distributions: flow of two adjacent immiscible fluids	Applications of equation of motion	Universal velocity profile for turbulent flow in a tube	Heat conduction in a cooling fin	Equations of change for multicomponent systems
	SLO-2	Shell momentum balances and velocity distributions: flow of two adjacent immiscible fluids	Applications of equation of motion	Universal velocity profile for turbulent flow in a tube	Heat conduction in a cooling fin	Equations of change for multicomponent systems
S-7	SLO-1	Shell momentum balances and velocity distributions: flow in a narrow slit	Solving problem	Definition of friction factors	The equations of change for non-isothermal systems	Analogies between momentum, heat and mass transport
	SLO-2	Shell momentum balances and velocity distributions: flow in a narrow slit	Solving problem	Friction factors for flow in tubes	The equations of change for non-isothermal systems	Analogies between momentum, heat and mass transport
S-8	SLO-1	Solving problem	Solving problem	Friction factors for flow around spheres	Steady state heat conduction problem	Solving problem
	SLO-2	Solving problem	Solving problem	Friction factors for flow in a narrow slit	Steady state heat conduction problem	Solving problem
S-9	SLO-1	Solving problem	Dimensional analysis of the equations of change	Friction factors for packed columns	Solving problem	Solving problem
	SLO-2	Solving problem	Dimensional analysis of the equations of change	Solving problem	Solving problem	Solving problem

Learning Resources	<ol style="list-style-type: none"> Byron R.Bird., Warren E. Stewart and Edwin N. Lightfoot, "Transport Phenomena", 2nd edition, John Wiley & Sons, New York, 2007. Christie John Geankoplis "Transport Processes and Separation Process Principles (Includes Unit Operations)", 4th Edition, Pearson Education, Prentice Hall, 2003. James R. Welty., Charles E. Wicks., Robert E. Wilson. and Gregory L. Rorrer "Fundamentals of Momentum, Heat, and Mass Transfer", 5th edition, John Wiley & Sons, New York, 2007. Robert S. Brodkey and Harry C. Hershey., Transport Phenomena - A Unified Approach, Volume 2, Brodkey Publishing, Columbus, 2001.
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SLO – Session Learning Outcome

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. A. Subramaniam, PESCO Beam Environmental Solutions Pvt. Ltd.,	1. Dr. Lima Rose Miranda, Anna University, email: limamiranda2007@gmail.com	1. Dr. S. Sam David SRM Inst. of Science & Technology, samdavis@srmist.edu.in
2. Mr. S. T. Kalaimani, CPCL, Chennai	2. Dr. T. R. Sundararaman, Rajalakshmi Engineering College	2. Dr. Ashish Kapoor SRM Inst. of Science & Technology, ashishko@srmist.edu.in

Course Code	18CHC307T	Course Name	REACTOR ANALYSIS AND CATALYSIS	Course Category	C	Professional Core	L 3	T 0	P 0	C 3
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	SLO-2		Derivation of Effectiveness factor for a first order reaction	Derivation of rate equation for spherical particles of unchanging size if surface chemical reaction is rate controlling	unchanging size if gas film diffusion controls	void volume and solid density determination; problems based on void volume and solid density
S-7	SLO-1	Parameter estimation using dispersion model	Performance equation for plug flow reactor containing porous catalyst particles	Problems based on shrinking core model	Expression for fraction unconverted for mixed flow of a size mixture of particles of unchanging size if surface chemical reaction and ash diffusion controls	Classification of catalysts; Promoters, inhibitors and accelerators
	SLO-2		Performance equation for mixed flow reactor containing porous catalyst particles			
S-8	SLO-1	Problems based on dispersion model	Experimental methods for finding rates of catalytic reactions	Reactions involving shrinking spherical particles: factors affecting rate and steps involved	Problems based on conversion of a single – sized feed in a mixed flow reactor	Catalyst preparation methods
	SLO-2	Problems based on dispersion model	Experimental methods for finding rates of catalytic reactions	Development of rate equation if chemical reaction controls the overall rate	Problems based on conversion of a feed mixture in a mixed flow reactor	
S-9	SLO-1	Derivation of RTD function equation (E) by tanks – in – series model	Problems based on finding the rate of catalytic reactions	Derivation of rate equation for shrinking spherical particles if diffusion through gas film controls	Problems based on finding the size of a fluidized bed and fluid – particle reactors	Types of catalyst poisons
	SLO-2	Derivation of RTD function equation (E) by tanks – in – series model	Problems based on finding the rate of catalytic reactions	Derivation of rate equation for shrinking spherical particles if diffusion through gas film controls	Problems based on finding the size of a fluidized bed and fluid – particle reactors	Types of catalyst poisons

Learning Resources	<ol style="list-style-type: none"> 1. Octave Levenspiel, "Chemical Reaction Engineering", 3rd edition, John Wiley & Sons, 2011. 2. H. Scott Fogler, "Elements of Chemical Reaction Engineering", 4th edition, Prentice Hall PTR, 2006. 3. J. M. Smith, "Chemical Engineering Kinetics", 3rd edition, McGraw Hill International editions, New Delhi, 1981.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Evaluate Create	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

CA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. A. Subramaniam, PESCO Beam Environmental Solutions Pvt. Ltd.,	1. Dr. Lima Rose Miranda, Anna University, email: limamiranda2007@gmail.com	1) Dr. M. Magesh Kumar SRM Inst. of Science & Technology, mageshkm@srmist.edu.in
2. Mr. S. T. Kalaimani, CPCL, Chennai	2. Dr. T. R. Sundararaman, Rajalakshmi Engineering College	2) Mr. V. Ganesh SRM Inst. of Science & Technology, ganeshv@srmist.edu.in

Course Code	18CHC308T	Course Name	PROCESS DYNAMICS, CONTROL AND INSTRUMENTATION	Course Category	C	PROFESSIONAL CORE				L	T	P	C
										3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Chemical Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand the importance of process control in industrial process plants.	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Understand the use of block diagrams & the mathematical basis for the design and stability of control systems	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Understand the application of good instrumentation for the effective design of process control loops for process engineering plants.																		
CLR-4 :	Draw a Process & Instrumentation Diagram and devise simple but effective plant wide control strategies using appropriate methods.																		
CLR-5 :	Design and tune process controllers and specify the required final elements to ensure that well-tuned control is achieved.																		
CLR-6 :	Understand the process dynamics and control in process industries																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Use Laplace method to obtain transfer functions related to the first and higher order system.	2	85	75	H	H											H	M	
CLO-2 :	Define linear closed loop control system, controllers, final control elements and use them in the problem solving.	2	80	70	H	H											H	M	
CLO-3 :	Analyze stability of open- and closed-loop control systems.	2	85	80	H	M	M		M								H	M	
CLO-4 :	Identify possible control schemes in chemical Engineering plants.	2	90	85			M		M								H	M	M
CLO-5 :	Understand the instrumentation and automation of modern chemical operation.	2	80	75				M									H	M	H
CLO-6 :	Apply and evaluate the various control schemes and systems	2	75	65	H	M	H	M	L								H	M	M

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Basic Concepts of process control, Block diagram	Linear closed loop systems	Concept of stability	Control system with single loops	Principles of measurements
	SLO-2 Linear open loop systems	Controllers and final control element	Stability criterion	Feedback control systems with examples	Classification of process control instruments
S-2	SLO-1 Laplace transform of simple functions	Principles of pneumatic and electronic controllers	Stability for linear system: Routh-Hurwitz stability criterion	Control systems with multiple loops	Elements of instruments
	SLO-2 Laplace transform of derivatives	Transfer function of controllers	Stability for linear system: Routh-Hurwitz stability criterion	Cascade control scheme with example	Parts of instruments
S-3	SLO-1 Properties of Laplace transform	Dynamic behavior of controllers	Solving Problem	Selective control systems	Static characteristics
	SLO-2 Physical examples of first-order systems	Closed loop response	Solving Problem	Override control	dynamic characteristics
S-4	SLO-1 Transfer function approach	Servo problem	Root locus diagrams	Auctioneering Control	Temperature measuring instruments
	SLO-2 Linearization of nonlinear system	Solving Problem	Root locus diagrams	Split-range control with examples	Temperature measuring instruments
S-5	SLO-1 Solving Problem	Solving Problem	Solving Problem	Feedforward control scheme with examples	Liquid-level measuring instruments
	SLO-2 Solving Problem	Solving Problem	Solving Problem	Control of distillation column: control of composition	Liquid-level measuring instruments
S-6	SLO-1 Response of first-order systems	Solving Problem	Design of control system using frequency response: Bode diagram-stability criterion	Control of distillation column: control of pressure	Pressure measuring instruments
	SLO-2 Response of first- order systems in series	Regulatory problem		Introduction to digital control	Pressure measuring instruments
S-7	SLO-1 Solving Problem	Solving Problem	phase and gain margins	Microprocessor-based controllers	Composition measuring instruments
	SLO-2 Solving Problem	Solving Problem	Solving Problem	Hardware Components	Composition measuring instruments
S-8	SLO-1 Higher order systems: Second-order	Solving Problem	Solving	Tasks of a Microprocessor based controller	Measurements of viscosity

	SLO-2	Transportation lag	Solving Problem	Solving	Special features of Microprocessor based controller	Measurements of pH
S-9	SLO-1	Solving Problem	Mechanism of control valves	Ziegler Nichols controller settings	Introduction to PLC's	Measurements of thermal conductivity
	SLO-2	Solving Problem	Valve characteristics	Solving Problem	Introduction to DCS	Measurements of humidity of gases

Learning Resources	<ol style="list-style-type: none"> 1. Donald R. Coughanowr., Steven E. LeBlanc., "Process system Analysis & Control", 3rd edition., McGraw Hill, New york, 2009. 2. George Stephanopoulos, "Chemical Process Control: An Introduction to Theory and Practice", Prentice Hall, New Delhi, 1984. 3. Peter Harriott, "Process Control" Tata McGraw Hill, New Delhi, 1972. 4. William L. Luyben, "Process modeling, simulation, and control for Chemical Engineers ", 2nd edition, McGraw Hill, New York, 1996. 5. Donald P. Eckman, "Industrial Instrumentation", Wiley Eastern Limited, 2004.
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SLO – Session Learning Outcome

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. A. Subramaniam, PESCO Beam Environmental Solutions Pvt. Ltd.,	1. Dr. Lima Rose Miranda, Anna University, email: limamiranda2007@gmail.com	1 Dr. K.Sofiya SRM Inst. of Science & Technology, sofiyak@srmist.edu.in
2. Mr. S. T. Kalaimani, CPCL, Chennai	2. Dr. T. R. Sundararaman, Rajalakshmi Engineering College	2 Dr.P.Muthamilselvi SRM Inst. of Science & Technology, muthamip@srmist.edu.in

Course Code	18CHC309L	Course Name	CHEMICAL ENGINEERING LAB III	Course Category	C	Professional Core															L	T	P	C			
																		0	0	4	2						
Pre-requisite Courses		Nil		Co-requisite Courses		Nil		Progressive Courses		Nil																	
Course Offering Department		Chemical Engineering				Data Book / Codes/Standards				Nil																	
Course Learning Rationale (CLR):		The purpose of learning this course is to:						Learning			Program Learning Outcomes (PLO)																
CLR-1 :		Provide the firsthand experience on verifying various theoretical concepts learnt in CRE and Process control.						1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2 :		Develop the skills in conducting experiments and to verify the theoretical concepts learnt in Chemical Reaction Engineering and Reactor analysis & catalysis courses.						Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3		
CLR-3 :		Evaluate the performance of single and multiple reactors																									
CLR-4 :		Develop the skills in conducting experiments and to verify the theoretical concepts learnt in .process dynamics, control & instrumentation course.																									
CLR-5 :		Understand the flapper- nozzle system and valve characteristics used for control system																									
CLR-6 :		Understand the characteristics of different mode of controllers P,PI,PD,PID, and tuning process																									
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																									
CLO-1 :	Operate batch and continuous reactors.						2	80	75	H	H	M	M										H	M	M		
CLO-2 :	Understand the performance of combined reactor system.						2	80	75	H	H	H	H										H	M			
CLO-3 :	Understand the non-ideality behavior of the continuous reactors.						2	80	75	H	M	M	M										H	M	L		
CLO-4 :	Understand process control concepts while performing the experiments						2	80	75	H	M	M	M										H	M			
CLO-5 :	study the response of different forcing functions						2	80	75	H	M	M											H	M	L		
CLO-6 :	Determine the controller tuning parameters						2	80	75	H	H	M	M										H	M			
Duration (hour)		12		12		12		12		12																	
S 1-4	SLO-1	Kinetic study in a batch reactor	Performance study of a tubular flow reactor.	Performance study of a mixed flow reactor.	Performance study of (i)tubular flow reactor followed by mixed flow Reactor (ii) mixed flow reactor followed by tubular flow Reactor															Study of an adiabatic reactor.							
	SLO-2																										
S 5-8	SLO-1	Performance study of a semi batch reactor	RTD studies in a tubular flow reactor.	RTD studies in a mixed flow reactor.	Current to pressure and pressure to current converter															Study of step response of first order system							
	SLO-2																										
S 9-12	SLO-1	Study of interacting and non-interacting system	Control Valve characteristics	Study of level controller	Study of pressure process controller															Optimum controller tuning on level controller							
	SLO-2																										
Learning Resources		1. Laboratory Manual 2. Octave Levenspiel, "Chemical Reaction Engineering", 3rd edition, John Wiley & Sons India edition, 2011. 3. George Stephanopoulos, "Chemical Process Control: An Introduction to Theory and Practice", Prentice Hall, New Delhi, 1984.																									

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	-	40 %	-	30 %	-	30 %	-	30 %	-	30%
Level 2	Understand	-	40 %	-	30 %	-	30 %	-	30 %	-	30%
	Apply	-	40 %	-	40 %	-	40 %	-	40 %	-	40%
Level 3	Analyze	-	40 %	-	40 %	-	40 %	-	40 %	-	40%
	Evaluate	-	20 %	-	30 %	-	30 %	-	30 %	-	30%
	Create	-	20 %	-	30 %	-	30 %	-	30 %	-	30%
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
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2. Mr. S. T. Kalaimani, CPCL, Chennai	2. Dr. T. R. Sundararaman, Rajalakshmi Engineering College	2 Dr.P.Muthamilselvi SRM Inst. of Science & Technology, muthamip@srmist.edu.in

Course Code	18CHC401J	Course Name	PROCESS EQUIPMENT DESIGN AND DRAWING	Course Category	C	Professional Course	L	T	P	C
							2	0	2	3

Pre-requisite Courses	18CHC207T 18CHC303T	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Chemical Engineering	Data Book / Codes/Standards	Perry's Chemical Engineers Hand Book		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Outline the importance of drawing conventions and representation of equipment's through process flow sheeting, dimensioning and labeling the parts of equipment's	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Provide the basics of proportioning, various types of selection of enclosures, flanges, nozzles and supports for process vessels		
CLR-3 :	Recap the unit operations and unit process equipment's and the theoretical design and drawing of reaction/agitated vessels, basket centrifuge, gravity thickener and cyclone separator		
CLR-4 :	Outline the principles of heat transfer and theoretical design and drawing of heat transfer equipment's such as shell and tube heat exchanger, evaporator and crystallizer		
CLR-5 :	Overview of the principles of mass transfer process and theoretical design and drawing of distillation column, absorption column and rotary drier		
CLR-6 :	consolidate the fundamental concepts and theoretical relationships useful in theoretical design and drawing of process equipment applied to chemical process industries		

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Draw the simple process flow sheets and use appropriate dimensioning and labeling the parts of equipment's	1	80	75	H	M	M	L					M	M		L	H	L	L
CLO-2 :	Choose appropriate enclosures, flanges, nozzles and supports for process vessels	2	80	70	H	M	M	M					M	M		H	H	M	
CLO-3 :	Perform the theoretical design and drawing of reaction/agitated vessels, basket centrifuge, gravity thickener and cyclone separator	3	80	75	H	H	M	M					M	M		H	H	M	
CLO-4 :	Analyze and theoretically design and draw the heat transfer equipment's such as shell and tube heat exchanger, evaporator and crystallizer	3	80	70	H	H	M	M					M	M		H	H	M	
CLO-5 :	Relate the principles of mass transfer and theoretically design and draw the distillation column, absorption column and rotary drier	3	80	75	H	H	M	M					M	M		H	H	M	
CLO-6 :	Apply the integrated knowledge acquired in different core chemical engineering courses to theoretically design and draw the chemical process equipment	3	80	75	H	H	M	M					M	M		H	H	M	

Duration (hour)	12	12	12	12	12
S-1	SLO-1 Drawing conventions, equipment representation dimensioning and labeling the parts	Classification of enclosures (heads or cover) used for the pressure vessels	Overview of reaction/agitated vessels	Drawing of gravity thickener	Practice drawing session of single effect evaporator evaporators and crystallizers
	SLO-2 Illustrative examples of Drawing conventions		Introduction, classification and design consideration of reaction vessel.		
S-2	SLO-1 Process flow sheeting	Numerical Problem on various types of enclosures	Numerical problem on the design of reaction/agitated vessel	Practice session for reaction/agitated vessel	Theory of crystallizers –Types and their applications.
	SLO-2 Illustrative example				Numerical problem on the design of crystallizers
S-3	SLO-1 General design procedure, materials of construction and design considerations	Specification for various types of enclosures	Drawing of reaction/agitated vessel	Practice session for basket centrifuge	Practice drawing session of crystallizers
	SLO-2 Pressure vessels - classification, applications and design considerations				
S-4	SLO-1 Factors influencing the design of vessels, design pressure, design temperature, factor safety and welding joint efficiency	Drawing of various enclosures (heads or covers) used for the process vessels.	Introduction to basket centrifuge	Practice drawing session for gravity thickener	Overview of distillation column, absorption column and rotary drier
	SLO-2				Theory and design aspects of distillation column
S-5	SLO-1			Outline of Heat exchangers	

	SLO-2	Numerical problem on design of pressure vessel subjected to internal pressure	Introduction to flanges, nozzles and supports	Numerical problem on the design of basket centrifuge		Numerical problem on the design of distillation for binary system
S-6	SLO-1	Numerical problem on design of pressure vessel subjected to external pressure	Selection criteria for flanges, nozzles and supports	Drawing of basket centrifuge	Principles of heat transfer types of heat exchangers and design procedure for 1-2 shell and tube heat exchanger	Drawing and practice session of distillation column for binary system
	SLO-2		Numerical problem on flanges, nozzles and supports.	Drawing of basket centrifuge separator		
S-7	SLO-1	Practice session on drawing of pressure vessel subjected to internal pressure	Drawing of Flanges, and nozzles	Introduction to gravity thickener	Numerical problem on design of shell and tube heat exchanger	Theory and design aspects of absorption column
	SLO-2		Drawing of supports			
S-8	SLO-1	Practice session on drawing of pressure vessel subjected to external pressure	Practice session on drawing of enclosures (heads or cover)s used for the process vessels	Numerical problem on the design of gravity thickener	Drawing of 1-2 shell and tube heat exchanger	Numerical problem on the design of absorption column
	SLO-2					
S-9	SLO-1	Summary of pressure vessel design	Practice session on drawing of flanges and nozzles	Practice drawing session of gravity thickener	Practice drawing session of 1-2 shell and tube heat exchanger	Drawing of absorption column
S-10	SLO-1	Introduction to various types of enclosures, flanges, nozzles and supports	Practice session on drawing of supports	Theory on design of cyclone separator	Theory of Evaporators – Types and their applications	Practice drawing session of absorber
	SLO-2					
S-11	SLO-1	Enclosures and their applications with illustrative examples	Practice session on drawing of flanges, nozzles and supports for pressure vessel subjected to internal pressure	Numerical problem on the design of gravity thickener	Numerical problem on design of single effect evaporator	Theory and design aspects of rotary drier
	SLO-2					Numerical problem on the design of rotary drier
S-12	SLO-1	Classification of enclosures (heads or cover) used for the pressure vessels	Summary of enclosures, flanges, nozzles and supports for pressure vessel subjected to internal pressure	Drawing of gravity thickener	Drawing of single effect evaporator	Drawing and Practice drawing session of rotary dryer
	SLO-2					

Learning Resources	<ol style="list-style-type: none"> 1. Sinnott. R.K, Coulson & Richardson's, "Chemical Engineering", Volume 6, 3rd Edn., Butterworth Heinemann, New Delhi, 1999. 2. Perry. R.H., et al., Perry's, "Chemical Engineers Handbook," 7th Edn., McGraw Hill, New York, 1997. 3. Bownell, L.E., and Young, E.M., "Process Equipment Design", Wiley Eastern, 1968. 4. Joshi. M.V, and Mahajani. V.V, "Process Equipment Design," 3rd Edn., Macmillan India Limited, New Delhi, 1996 5. Maidargi, Suresh C., "Chemical Process Equipment: Design and Drawing (Vol. I)" 2nd Edn. Prentice Hall India, 2015 6. Bhattacharyy, B C., "Introduction to Chemical Equipment Design: Mechanical Aspects", 1st Edn. CBS Publisher, 2012
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. A. Subramaniam, PESCO Beam Environmental Solutions Pvt. Ltd.,	1. Dr. Lima Rose Miranda, Anna University, email: limamiranda2007@gmail.com	1 Dr. S. Balasubramanian SRM Inst. of Science & Technology, balasubs@srmist.edu.in
2. Mr. S. T. Kalaimani, CPCL, Chennai	2. Dr. T. R. Sundararaman, Rajalakshmi Engineering College	2 Mr. V. Ganesh SRM Inst. of Science & Technology, ganeshv@srmist.edu.in

Course Code	18CHC402T	Course Name	PROCESS ECONOMICS AND PROJECT MANAGEMENT	Course Category	C	Professional Core	L 3	T 0	P 0	C 3
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Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Chemical Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:				Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Present the fundamental concepts of time value of money					1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Provide the essential features of balance sheet and profit-loss statements applied to a typical process industry					Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Impart knowledge on the basics of selection of alternatives in process plants using theoretical economic equations																						
CLR-4 :	Explain concepts of the economic balance applied the cyclic process in the manufacture of chemicals in match mode																						
CLR-5 :	Illustrate the role played by the process engineers in chemical engineering project management																						
CLR-6 :	Present the basic theoretical process engineering economic principles, elementary accounting procedures and project management as applied in chemical process industries																						
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																					
CLO-1 :	Apply the concept of time value of money to solve process economic problems					1	80	70	L	M							M		L	M	H	L	M
CLO-3 :	Analyze the chemical engineering processes and illustrate the economic principles used in it towards the economic selection of alternatives					2	80	70	H	H	M						L		L	M	H	H	H
CLO-4 :	Perform economic balance calculations for batch (or cyclic) processes					2	75	70	H	H	M						M				H	H	M
CLO-5 :	Explain the importance of project management applied to chemical engineering projects					1	80	75	M	M							H	M	H	M	H	M	M
CLO-6 :	Apply the knowledge of economics and management principles, methods and illustrate their applications to chemical engineering					2	80	70	M	M							H	M	H	M	H	H	H

Duration (hour)	09	09	09	09	09
S-1	SLO-1	Introduction to time value of money	Overview of Balance sheet and cost accounting	Economics of selecting alternative	Economic balance
	SLO-2	Terminologies used in time value of money and illustrative examples	Capital requirements for process plants	Various methods in economics of selecting alternatives	Illustrative examples of Economic balance applied to process industries
S-2	SLO-1	Simple and compound Interest theory and illustrative examples	Cost index problems for equipment's and plants	Annual cost method and Illustrative example	Problem session in single variable economic balance
	SLO-2	Nominal and effective interest rates theory and illustrative examples	Illustrative example of cost index problems	Illustrative example of annual cost method	Problem session in single variable economic balance
S-3	SLO-1	Practice problem session in time value of money	Conceptual basis for Balance sheet	Practice problem session in annual cost method	Problem session in multi variable economic balance
	SLO-2	Practice problem session in various interest rates	Illustrative example of preparation of Balance sheet	Practice problem session in annual cost method	Problem session in multi variable economic balance
S-4	SLO-1	The concept of equivalence and illustrative examples	Practice problem session of balance sheet preparation	Present worth method and illustrative example	Deriving optimum diameter of pipe for fluid transport using the concept of economic balance
	SLO-2	Theoretical equations for economic studies	Practice problem session in balance sheet preparation	Illustrative example of Present worth method	Practice session for the above mentioned derivation
S-5	SLO-1	Problems using theoretical equations for economic studies	Earnings, process and returns (Income statement)	Practice problem session in present worth method	Economic balance in batch operations
	SLO-2	Problems using theoretical equations for economic studies	Illustrative example of income statement	Practice problem session in present worth method	Illustrative example
S-6	SLO-1	Amortization concept with illustrative example	Practice problem session in income statement	Replacement: Rate-of-return	Economic balance in cyclic
					Project management for chemical engineers
					Importance of management in practice for chemical engineers
					Project, principles and initiation
					Project strategy and organization
					Process specification
					Process Specification-illustrative example
					Detail design strategy
					Illustrative example in detailed design strategy
					Risk analysis and management
					Quantitative test for risk analysis and management
					Scoping, planning and getting approvals prior to starting physical work

	SLO-2	Problem practice session on Amortization	Practice problem session in income statement	Illustrative example of rate-of- return method	Illustrative example	Contracting for engineering and construction activities
S-7	SLO-1	Concept of Depreciation Types of depreciation problems	Concepts of Economic production – break-even analysis	Replacement: Pay-out time method	Problem practice session on economic balance in cyclic processes for the manufacture of a typical chemical in batches	Project execution with regards to health, safety and environment
	SLO-2	Illustrative example in depreciation	Illustrative example of break-even analysis	Illustrative example of pay-out time method	Problem practice session on economic balance in cyclic processes for the manufacture of a typical chemical in batches	Cost, quality and schedule Illustrative example
S-8	SLO-1	Practice problem session in depreciation	Practice problem session in break-even Analysis	Illustrative example on combination of four methods of economics of alternative selection	Economic balance in multiple equipment units and an illustrative example	Special features of small projects
	SLO-2	Practice problem session in depreciation	Practice problem session in break-even analysis	Illustrative example on combination of four methods of economics of alternative selection	Economic analysis of an operating plant - Appraisal value, earning value, stock and bond Value	Illustrative example of salient features of small projects
S-9	SLO-1	Concept of depletion Practice problem on depletion	Cost accounting - pre construction cost estimation- Allocation of cost	Practice problem session in combination of four methods of economics of alternative selection	Practice problem session in appraisal value and construction of data sheet for economic analysis of a process plant.	Value engineering – Illustrative example
	SLO-2	Summary of time value of money	Summary of balance sheet and cost accounting	Summary of economic selection of alternatives	Summary of economic balance and economic analysis of complete process plant	Summary of project management applied to chemical engineering

Learning Resources	<ol style="list-style-type: none"> 1. Max. S.Peters and Klaus. D Timmerhaus, "Plant Design and Economics for Chemical Engineers", 5th Edn., McGraw Hill International Editions, New York, 2004. 2. Schweyer. H.E, "Process Engineering Economics", McGraw Hill, 1969 3. F.C. Jelen and J.H. Black, "Cost and Optimization Engineering", McGraw Hill, 3rd Edn., 1992. 4. Peachey B., R. Evitts and Hill G., "Project Management for Chemical Engineers", Trans IChemE, Part D, 2007 5. Paul C. Dinsmore, PMP, Jeannette Cabanis- Brewin, "The AMA Handbook of Project Management", 3rd Edn., 2011 6. Gillian Lawson, Stephen Weame, Peter Iles-Smith, "Project management for the Process Industries", IChemE, UK, 1999
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. A. Subramaniam, PESCO Beam Environmental Solutions Pvt. Ltd.,	1. Dr. Lima Rose Miranda, Anna University, email: limamiranda2007@gmail.com	1 Dr. S. BALASUBRAMANIAN SRM Inst. of Science & Technology, balasubs@srmist.edu.in
2. Mr. S. T. Kalaimani, CPCL, Chennai	2. Dr. T. R. Sundararaman, Rajalakshmi Engineering College	2 Dr. K. ANBALAGAN SRM Inst. of Science & Technology, anbalagk@srmist.edu.in

Course Code	18CHC403J	Course Name	PROCESS MODELING AND SIMULATION	Course Category	C	Professional Core	L	T	P	C
							2	0	2	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Chemical Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 : Understand the terms involved in Conservation of Mass, Momentum and Energy equations.		1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 : Review the phase equilibrium, Chemical equilibrium and Chemical Kinetics.		Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 : Apply the conservation of mass and energy equation for simple chemical engineering systems.		Expected Proficiency (%)	Problem Analysis
CLR-4 : provide the training to develop process model equations for Chemical Engineering systems.		Expected Attainment (%)	Design & Development
CLR-5 : provide training to solve the process model equation using SCILAB and commercial software (Aspen Plus).			Analysis, Design, Research
CLR-6 : Understand the overview of process modeling			Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
			H H L
			H H L
			H H L
			H H L M
			H H L H
			H H M M

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:
CLO-1 : Understand the modeling concept in Molecular and Convective transport terms.	2 80 70
CLO-2 : Understand the interface and reaction modeling concepts in Chemical Engineering systems.	2 80 70
CLO-3 : Understand the pseudo and unsteady state modeling concepts	2 75 70
CLO-4 : Propose the process modeling equations for simple and complex chemical Engineering systems.	3 80 70
CLO-5 : Solve the model equations using open source software (SCILAB) and Commercial software (Aspen Plus).	3 70 60
CLO-6 : Model a given process and simulate	2 70 65

Duration (hour)	12	12	12	12	12
S-1	SLO-1	Inventory rate equation of the conserved quantities	Interphase transport	Pseudo-Steady-State Approximation	Continuous Stirred Tank Reactor with constant holdup
S-2	SLO-1	Steady state, Uniform, Equilibrium and Flux with suitable examples	Transfer coefficient, diffusivity and flux ratio for the transport of conserved quantities	Conservation of chemical species, momentum, energy and total mass for unsteady state	Continuous Stirred Tank Reactor with variable holdup
S-3	SLO-1	Mathematical formulation of the conserved quantities (Mass, Momentum and Energy equations)	Rate of generation in mass transport	Interacting and non-interacting system using single component	Two heated tanks
S-4	SLO-1	Analogous molecular flux in constitutive equations for mass, momentum and energy	Rate of generation in momentum and energy transport	Unsteady state mass balance in a mixing tank	Gas phase pressurized CSTR
S-5	SLO-1	Determine the molar flux from the plate surface under steady state	Equilibrium conversion for multiple reactions occur simultaneously using SCILAB	Unsteady state energy balance around a Continuous Stirred Tank	Multi-Component Flash Drum
S-6	SLO-1	Identical problem solve using SCILAB code	Solve the identical problem using Aspen Plus	Solving unsteady state problems without reactions using SCILAB	Solve the model equations for multi-component flash drum using SCILAB
S-7	SLO-1	Determine the wall heat flux and heat transfer coefficient using experimental data	Solve the similar problem using Aspen Plus	Solving unsteady state problems without reactions using SCILAB	Identical problem solve using Aspen Plus
S-8	SLO-1	Convective flux	Steady state macroscopic balances	Estimate the transient conversion and temperature in batch reactor using SCILAB	Non-isothermal CSTR with single reaction
S-9	SLO-1	Analogous terms in total flux expressions for various types of transport in one-dimension	Composition of species in mixing tanks	Estimate the transient conversion and temperature in batch reactor using Aspen Plus	Modeling of single phase vaporizer

S-10	SLO-1	Properties estimation using Aspen Plus	Steady state energy balance around a continuous stirred reactor	Unsteady state steam Heating of a liquid	Modeling of mass transfer with reaction	Flow sheeting concepts using sequential modular approach
S-11	SLO-1	Solve the similar problems using Aspen Plus	Problem in continuous stirred reactor with reaction	Unsteady single stage solvent extraction	Steady state simulation of series of isothermal reactors	Demonstrate the simple flow sheet using Aspen Plus
S-12	SLO-1	Solve the similar problems using Aspen Plus	Solve the similar problems using SCILAB	Problem in extraction	Steady state simulation of series of non-isothermal reactors using Aspen Plus	Demonstrate the chemical plant simulation using Aspen plus

Learning Resources	<ol style="list-style-type: none"> 1. William L. Luyben, <i>Process Modeling Simulation and Control for Chemical Engineers</i>, 2ndEdn., McGraw Hill International Editions, New York, 1990. 2. Ismail Tosun, <i>Modeling in Transport Phenomena – A Conceptual Approach</i>, 2ndEdn., Elsevier Publications 2007 3. Y.V.C. Rao, <i>Chemical Engineering Thermodynamics</i>, Universities press, 1997. 4. Steven C. Chapra and Raymond P. Canale, <i>Numerical Methods for Engineers</i>, 6thEdn., McGraw Hill International Editions, New York, 2010 5. H. Scott Fogler, <i>Elements of Chemical Reaction Engineering</i>, 4th Edition, Prentice Hall International Series
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. A. Subramaniam, PESCO Beam Environmental Solutions Pvt. Ltd.,	1. Dr. Lima Rose Miranda, Anna University, email: limamiranda2007@gmail.com	1. Dr. K. Suresh, SRMIST, Sureshk@srmist.edu.in
2. Mr. S. T. Kalaimani, CPCL, Chennai	2. Dr. T. R. Sundararaman, Rajalakshmi Engineering College	2. Dr. S. Balasubramanian, SRMIST, balasubs@srmist.edu.in

Course Code	18CHC350T	Course Name	COMPREHENSION	Course Category	C	Professional Core	L	T	P	C
							0	1	0	1

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Chemical Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1:	Acquire skills to comprehend and solve problems in Chemical Process Calculations and Thermodynamics	1	1
CLR-2:	Acquire skills to comprehend and solve problems in Mechanical Operations and Fluid Mechanics	2	2
CLR-3:	Acquire skills to comprehend and solve problems in Heat Transfer and Mass Transfer	3	3
CLR-4:	Acquire skills to comprehend and solve problems in Reaction Engineering and Process Control		4
CLR-5:	Acquire skills to comprehend and solve problems for competitive examinations in Chemical Engineering		5
CLR-6:	Acquire skills to comprehend and solve real world problems in the broad domain of Chemical Engineering		6

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1:	Practice and gain competence to solve problems in Chemical Process Calculations and Thermodynamics	3	80	75	H	H	H	M	M	L	L	L	L	L	L	L	H	H	M
CLO-2:	Practice and gain competence to solve problems in Mechanical Operations and Fluid Mechanics	3	80	75	H	H	M	M	M	L	L	L	L	L	L	L	H	H	M
CLO-3:	Practice and gain competence to solve problems in Heat Transfer and Mass Transfer	3	80	75	H	H	M	M	M	L	L	L	L	L	L	L	H	H	M
CLO-4:	Practice and gain competence to solve problems in Reaction Engineering and Process Control	3	80	75	H	H	M	M	M	L	L	L	L	L	L	L	H	H	M
CLO-5:	Practice and gain competence to solve problems for competitive examinations in Chemical Engineering	3	80	75	H	H	H	M	M	L	L	L	L	L	L	L	M	M	M
CLO-6:	Practice and gain confidence and competence to solve problems in broad domain of Chemical Engineering	3	75	70	H	H	M	M	M	L	L	L	L	L	L	L	M	M	M

Duration (hour)	3	3	3	3	3
S-1	SLO-1 Tutorial on Chemical Process Calculations	Tutorial on Mechanical Operations	Tutorial on Heat Transfer	Tutorial on Reaction Engineering	Problem Solving - Practice
	SLO-2 Tutorial on Chemical Process Calculations	Tutorial on Mechanical Operations	Tutorial on Heat Transfer	Tutorial on Reaction Engineering	Problem Solving - Practice
S-2	SLO-1 Tutorial on Thermodynamics	Tutorial on Fluid Mechanics	Tutorial on Mass transfer	Tutorial on Process Control	Problem Solving - Practice
	SLO-2 Tutorial on Thermodynamics	Tutorial on Fluid Mechanics	Tutorial on Mass transfer	Tutorial on Process Control	Problem Solving - Practice
S-3	SLO-1 Problem Solving	Problem Solving	Problem Solving	Problem Solving	Problem Solving - Practice
	SLO-2 Problem Solving	Problem Solving	Problem Solving	Problem Solving	Problem Solving - Practice

Learning Resources	1. M. Subbu, An Insight Into Chemical Engineering, Rishal Publications
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (100% weightage)								Final Examination	
		CLA – 1 (20%)		CLA – 2 (30%)		CLA – 3 (30%)		CLA – 4 (20%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	-	40%	-	30%	-	30%	-	30%	-	-
	Understand	-	40%	-	30%	-	30%	-	30%	-	-
Level 2	Apply	-	40%	-	40%	-	40%	-	40%	-	-
	Analyze	-	40%	-	40%	-	40%	-	40%	-	-
Level 3	Evaluate	-	20%	-	30%	-	30%	-	30%	-	-
	Create	-	20%	-	30%	-	30%	-	30%	-	-
Total		100 %		100 %		100 %		100 %		-	

CLA - 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers	Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
	1. Mr. A. Subramaniam, PESCO Beam Environmental Solutions Pvt. Ltd	1. Dr. Lima Rose Miranda, Anna University, email: limamiranda2007@gmail.com	Mr. V. Ganesh, SRMIST
	2. Mr. S. T. Kalaimani, CPCL, Chennai	2. Dr. T. R. Sundararaman, Rajalakshmi Engineering College	

ACADEMIC CURRICULA

Professional Core Courses

CIVIL ENGINEERING

Regulations - 2018



SRM INSTITUTE OF SCIENCE AND TECHNOLOGY

(Deemed to be University u/s 3 of UGC Act, 1956)

Kattankulathur, Kancheepuram, Tamil Nadu, India

Course Code	18CEC301T	Course Name	HYDROLOGY AND WATER RESOURCES ENGINEERING	Course Category	C	Professional Core	L	T	P	C
							3	1	0	4

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	18CEE311T, 18CEE312T, 18CEE313T
Course Offering Department	CIVIL ENGINEERING	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 : Provide knowledge on various processes in the hydrologic cycle		1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 : Address the occurrence, movement and augmentation of groundwater		Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 : Provide deep understanding of various impounding and diversion structures		Expected Proficiency (%)	Problem Analysis
CLR-4 : Create insights on the importance and characteristics of rivers and reservoirs		Expected Attainment (%)	Design & Development
CLR-5 : Address concepts related to necessity of irrigation, methods of applying water to the fields and evapotranspiration			Analysis, Design, Research
CLR-6 : Introduce various hydraulic structures and exploit their practical importance			Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 : Understand the interaction among various processes in the hydrologic cycle		2 85 80	H H M M - - M - - - - H - -
CLO-2 : Intellectualize the basic aquifer parameters and estimate groundwater resources for different hydro-geological boundary conditions		3 85 75	H H - - - - M - - - - H - -
CLO-3 : Understand the importance, features and uses of diversion and impounding structures		3 80 75	H - - - - - M - - - - - H - -
CLO-4 : Perceive the importance of rivers, reservoirs and silt control		2 85 80	H - - - - - M - - - - - H - -
CLO-5 : Understand the basics of irrigation, soil-water relationships and consumptive use		2 85 75	H H M M - - M - - - - H - -
CLO-6 : Identify the functions and importance of various hydraulic structures		3 80 75	H H - - - - M - - - - H - -

Duration (hour)	SURFACE WATER HYDROLOGY	GROUND WATER HYDROLOGY	DIVERSION AND IMPOUNDING STRUCTURES	RIVERS AND RESERVOIRS	IRRIGATION AND DISTRIBUTION SYSTEMS
	12	12	12	12	12
S-1	SLO-1 Introduction, hydrologic cycle	Occurrence of ground water, porosity	Weirs and barrages	Rivers: types and characteristics	Irrigation, necessity, advantages and disadvantages
	SLO-2 World water balance, applications in engineering	Permeability and transmissibility	Gravity and non-gravity weirs	Classification based on the basis of the topography of the river basin	Methods of applying water to the fields
S-2	SLO-1 Precipitation, forms and types	Zones of subsurface water	Diversion head works and its components	Classification based on the basis of flood hydrographs	Surface, subsurface, sprinkler and drip irrigation
	SLO-2 Measurement of precipitation, rain gauge network	Movement of groundwater, Darcy's law	Functions of weir proper, under sluices, divide wall, fish ladder and canal head regulator	Indian rivers and their classification	Soil-water-plant relationship
S-3	SLO-1 Mean areal depth of precipitation, arithmetic average method	Specific yield and specific retention	Failure of hydraulic structures	Behaviour of rivers: straight reaches, bends and meanders	Hygroscopic water, capillary water and gravitational water
	SLO-2 Thiessen polygon method and isohyetal method	Aquifers and their types	Failure by piping and failure by direct uplift	Causes of meandering, cutoff	Field capacity, permanent wilting point, available moisture, readily available moisture
S-4	SLO-1 Tutorial	Tutorial	Tutorial	Tutorial	Tutorial
	SLO-2 Tutorial	Tutorial	Tutorial	Tutorial	Tutorial
S-5	SLO-1 Estimation of missing precipitation	Specific capacity and coefficient of storage	Bligh's creep theory	River training: objectives and classification	Depth of water stored in root zone
	SLO-2 Optimum raingauge network design	Infiltration wells and infiltration galleries	Lane's weighted creep theory	Types of training works	Limiting soil moisture conditions, depth and frequency of irrigation
S-6	SLO-1 Probable Maximum Precipitation	Open wells and tube wells	Khosla's theory	Levees, guide banks	Crop season, duty and delta

	SLO-2	Runoff process, components of stream flow	Types of tube wells	Khosla's method of independent variables for determination of pressures and exit gradient for seepage below a weir or a barrage	Artificial cutoff and pitched island	Factors affecting duty and method of improving duty
S-7	SLO-1	Factors affecting runoff	Yield of an open well, pumping test	Design of pucca floor and aprons	Groyne: types – normal, attracting and deflecting	Consumptive use: estimation by Blaney Criddle method and pan evaporation method
	SLO-2	Estimation of runoff, empirical formulae	Recuperation test	Design of pucca floor and aprons	Reservoir: types	Canal: types of alignment
S-8	SLO-1	Tutorial	Tutorial	Tutorial	Tutorial	Tutorial
	SLO-2	Tutorial	Tutorial	Tutorial	Tutorial	Tutorial
S-9	SLO-1	Infiltration method	Steady state flow in wells	Dams, function and uses, classification	Suitable site for a reservoir and storage zones	Distribution systems, channel losses
	SLO-2	SCS-CN method of estimating runoff volume	Dupuit's equilibrium equation for confined and unconfined aquifers	Factors governing the selection of a particular type of dam	Storage-discharge relation of a reservoir	Design of channels: rigid boundary channels and alluvial channels
S-10	SLO-1	Flow duration curve	Theim's equation for confined aquifer	Selection of dam site, problems in dam construction	Reservoir yield, safe yield, design yield, secondary yield and average yield	Kennedy's and Lacey's theories of regime channels
	SLO-2	Flow mass curve	Theim's equation for unconfined aquifer	Gravity dams: forces on gravity dams	Mass curve and demand curve	Water logging: causes, effects and remedial measures
S-11	SLO-1	Hydrograph, components of hydrograph	Spacing of wells	Modes of failure, construction of gravity dams	Designing reservoir capacity for a given yield and designing yield from a reservoir of a given capacity	Functions and uses of canal regulator and cross regulator
	SLO-2	Environmental flows	Artificial recharge methods	Galleries: functions and types. Earthen dam: types and causes of failure	Reservoir sedimentation: pre and post control measures, economic height of dam	Functions and uses of canal fall, canal escape and cross drainage works
S-12	SLO-1	Tutorial	Tutorial	Tutorial	Tutorial	Tutorial
	SLO-2	Tutorial	Tutorial	Tutorial	Tutorial	Tutorial

Learning Resources	1. Santosh Kumar Garg, <i>Irrigation Engineering and Hydraulic Structures</i> , Khanna Publication, New Delhi, 2000. 2. Subramanya, K., <i>Engineering Hydrology</i> , Tata Mc-Graw Hill 3. Asawa, G.L., <i>Irrigation Engineering</i> , Wiley Eastern 4. Ven Te Chow, David R. Maidment and Larry W. Mays, <i>Applied Hydrology</i> , McGraw-Hill Book Company 5. Raghunath, H.M., <i>Hydrology</i> , New Age International Publishers, New Delhi, 2007. 6. Sharma, R.K., <i>Irrigation Engineering and Hydraulic Structures</i> , Oxford and IBH Publishing Company, New Delhi 7. Punmia, B.C., and Pande, B.B., <i>Irrigation and Water Power Engineering</i> , Laxmi Publications Pvt. Ltd., New Delhi, 2009 8. NPTEL Course: <i>Water Resources Engineering</i> : https://nptel.ac.in/downloads/105105110/# ,
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, and Conf. Paper etc.

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Abdul Hakeem, National Remote Sensing Center, Hyderabad, abdulhakeem_k@nrsc.gov.in	1. Dr. Rehana Shaik, IIIT, Hyderabad, rehana.s@iiit.ac.in	1. Dr. R. Sathyanathan, SRMIST
2. Dr. Sat Kumar Tomer, Satyukt Analytics Pvt Ltd., Bengaluru, sat@satyukt.com	2. Dr. S. Saravanan, NIT Trichy, saravans@nitt.edu	2. Dr. Deeptha Thattai, SRMIST

Course Code	18CEC302T	Course Name	GEOTECHNICAL ENGINEERING			Course Category	C	Professional Core					L	T	P	C							
													2	1	0	3							
Pre-requisite Courses	Nil			Co-requisite Courses	Nil			Progressive Courses	Nil														
Course Offering Department		CIVIL ENGINEERING			Data Book / Codes/Standards			Nil															
Course Learning Rationale (CLR):		The purpose of learning this course is to:					Learning			Program Learning Outcomes (PLO)													
CLR-1 :	Create insights in to different properties of soil					1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Deal with the classification and identification of soil					Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Understand concept of permeability and seepage of soils																						
CLR-4 :	Analyse the consolidation and compaction effect on soil in lab and field																						
CLR-5 :	Analyse the principles of effective stress in saturated soils, various soil condition the shear strength of the soils																						
CLR-6 :	Utilize the concept of various soil condition and shear strength of the soils in real time applications																						
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:					Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	H	H	-	-	-	-	-	-	-	-	-	H	-	-
CLO-1 :	Identify the various properties of soil					2	85	80	H	H	-	-	-	-	-	-	-	-	-	-	H	-	-
CLO-2 :	Analyse the classification of soil					2	85	75	H	H	-	M	-	-	-	-	-	-	-	-	H	-	-
CLO-3 :	Identify permeability and seepage of soils					2	80	75	H	H	-	-	-	-	-	-	-	-	-	-	H	-	-
CLO-4 :	Identify the consolidation and compaction effect on soil in lab and field					2	85	80	H	H	-	-	-	-	-	-	-	-	-	-	H	-	-
CLO-5 :	Apply the principles of effective stress in saturated soils, various soil condition the shear strength of the soils					2	85	80	H	H	-	M	-	-	-	-	-	-	-	-	H	-	-
CLO-6 :	Analyse the concept of various soil condition and shear strength of the soils in real time applications					2	80	75	H	H	-	M	-	-	-	-	-	-	-	-	H	-	-
Duration (hour)	09		09		09		09		09		09												
S-1	SLO-1	Introduction-Definitions: soils	Particle size distribution		Permeability of Soil-importance		Compaction of Soil		Introduction- Stresses in soils														
	SLO-2	Soil mechanics	Sieve analysis - problem		Introduction to hydraulic head		Introduction, theory of compaction,		Geostatic stress														
S-2	SLO-1	Scope of Geotechnical engineering,	Plasticity Characteristics of soil		Darcy's law - Assumptions.		Laboratory determination of optimum moisture content and maximum dry density		Total - Effective and Neutral stress,														
	SLO-2	Basic Definitions and Relationships-	Introduction to definitions of: plasticity of soil		Determination of coefficient of permeability		Standard Proctor test and Modified Proctor test – Problems in compaction		Fluctuations of effective stress														
S-3	SLO-1	Two and three phase system of soil	Consistency limits-liquid limit, plastic limit		Laboratory method: Constant head method problems		Compactive energy –Factors affecting compaction		Effective stress in soils saturated by capillary action,														
	SLO-2	Relationships in terms of weightand volume in phase system – moisture content	Shrinkage limit, Determination of: liquid limit		Coefficient of permeability		CBR of soil – procedure - problem		Problems in Geostatic stress – soil condition														
S-4	SLO-1	Definitions: degree of saturation, void ratio, porosity	Determination of plastic limit and shrinkage limit.		Falling head method - problems		Field compaction methods		Problems in Geostatic stress – water table effect														
	SLO-2	specific gravity, unit weights	Indices: Plasticity, liquidity and consistency, flow and toughness		Field method: types		Factors affecting field compaction		Shear Strength- Lab and filed methods														
S-5	SLO-1	Relationship between bulk and dry density , void ratio- porosity, void ratio	Definition: Activity and sensitivity.		Pumping-out test – Confined aquifer		Consolidation of Soil		Shear test: direct shear test														
	SLO-2	Water content- specific gravity-degree of saturation	Classification of Soils		Field method - Unconfined aquifer		Introduction, comparison between compaction and consolidation,		Shear test: merits and demerits - problem														
S6	SLO-1	Unit weights - specific gravity - void ratio – degree of saturation –	Introduction of soil classification system		problems in field methods		Initial, primary consolidation		Unconfined compression test - problem														
	SLO-2	Moisture content determination – Methods, Determination by oven dry method	methods:- particle size classification		Permeability in stratified soils		Secondary consolidation		Triaxial compression tests.														

S-7	SLO-1	Problems in two phase system.	Indian standard soil classification system	Flow parallel and perpendicular to bedding plane - problems	Spring analogy for primary consolidation,	Drainage conditions
	SLO-2	Problems in three phase system.	Indian Soil classification system cohesive soil, cohesionless soil.	Factors affecting permeability of soil	Terzaghi's theory of one dimensional consolidation	Merits and demerits
S-8	SLO-1	Specific gravity – methods,	Indian Soil classification system – Problems	Quick sand condition - Seepage Analysis	Partial differential equations (no analytical)	Drainage conditions- problem
	SLO-2	Determination by density bottle method and pycnometer method	Problems in BIS system	Introduction- seepage pressure.	Laboratory tests-	Relation between major and minor principal stresses
S-9	SLO-1	Field density methods – Determination by core cutter method	Soil identification	Characteristics of flow nets	Determination of coefficient of consolidation	Vane shear test. – problem
	SLO-2	Sand replacement method.	Field identification of soils.	Uses and application of flow nets.	\sqrt{t} and Log t methods.	Factors affecting shear strength

Learning Resources	1. Raju .K.V.B .and Ravichandran .P.T, "Mechanics of Soils", Ayyappa Publications, 2000.	5. Terzaghi K., Peck R.B., Soil Mechanics in Engineering Practice, John Wiley Ltd., 1967
	2. Punmia B.C., Soil Mechanics and Foundations, Laxmi Publications Pvt. Ltd., 2000	6. Lambe T.W., Whitman, Soil Mechanics, John Wiley Ltd., 1979.
	3. Arora .K.R, "Soil Mechanics and Foundation Engineering", Standard Publication Distributors, 2011.	7. NPTEL Course - Soil Mechanics / Geotechnical Engineering1 : https://nptel.ac.in/courses/105105168/
	4. Gopal Ranjan, Rao.A.S.R., Basic and Applied Soil Mechanics, Wiley Eastern Ltd., 2000	8. NPTEL Course - Concepts in Geotechnical and Foundation Engineering : https://nptel.ac.in/courses/105106142/

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	30%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	30%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 : Assignments and / or Multiple choice Quizzes

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Dr. P.Selvanambi, Divisional Engineer (Highways), sundariselvam@yahoo.com	Dr.M.Muttharam, Anna University, muttharam@annauniv.edu	Dr. P.T. Ravichandran, SRMIST
Mr.Lenin K.R., Head –GEOTECH, SECON Private Limited, Bangalore, lenin.kr@secon.in	Dr.V.Murugaiyan, Pondichery Engineering College, vmurugaiyan@pec.edu	Ms.Divya Krishnan K, SRMIST

Course Code	18CEC302L	Course Name	GEOTECHNICAL ENGINEERING LABORATORY	Course Category	C	Professional Core	L	T	P	C
							0	0	2	1

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Civil Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Determine the engineering and index properties of soils	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Determine the compaction and CBR value of soil	Thinking (Bloom)	Proficiency (%)	Attainment (%)	Knowledge	Analysis	Design	Research	Usage	Culture	Sustainability	Team Work	Communication	Finance	Learning				
CLR-3 :	Impart knowledge on permeability characteristics of soil																		
CLR-4 :	Determine the field density of soil																		
CLR-5 :	Determine the shear strength of soil																		
CLR-6 :	Study the working principle and function of triaxial shear test																		

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Identify the use of sieve, Atterberg's apparatus in determination of soil properties.	2	90	85	H	H	-	-	-	-	-	-	H	-	-	-	M	-	H
CLO-2 :	Estimate the OMC and Density to compact and CBR value of soil	2	85	80	H	H	-	-	-	-	-	-	H	-	-	-	M	-	H
CLO-3 :	Analyse the permeability characteristics of various soil.	2	90	85	H	H	-	-	-	-	-	-	H	-	-	-	M	-	H
CLO-4 :	Measure the density of soil in-situ	2	85	80	H	H	-	-	-	-	-	-	H	-	-	-	M	-	H
CLO-5 :	Evalute the shear strength of soil	2	85	80	H	H	-	-	-	-	-	-	H	-	-	-	M	-	H
CLO-6 :	Understand the working principle and use of triaxial shear test	2	85	80	H	H	-	-	-	-	-	-	H	-	-	-	M	-	H

Duration (hour)	6	6	6	6	6
S SLO-1	Moisture content using oven drying	Consistency limits - Liquid limit, Plastic limit and Shrinkage limit.	Compaction test - Standard Proctor method	California Bearing Ratio of soil	Direct shear test
1-2 SLO-2	method				
S SLO-1	Specific gravity of soil grains	Permeability - Constant head method.	Field density - Core cutter method and Sand replacement method	Unconfined compression strength test	Triaxial shear test
3-4 SLO-2					
S SLO-1	Grain size distribution by sieve analysis	Permeability - Falling head method	Relative density of cohesion less soil	Free swell index test	Vane shear test
5-6 SLO-2					

Learning Resources	5. Raju .K.V.B .and Ravichandran .P.T, "Mechanics of Soils", Ayyappa Publications, 2000. 6. Punmia B.C., Soil Mechanics and Foundations, Laxmi Publications Pvt. Ltd., 2000 7. Laboratory Manual for Soil Mechanics Laboratory, SRMIST	8. Terzaghi K., Peck R.B., Soil Mechanics in Engineering Practice, John Wiley Ltd., 1967 5. NPTEL course – Geotechnical Engineering Laboratory : https://nptel.ac.in/courses/105101160/
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	-	40%	-	30%	-	30%	-	30%	-	30%
	Understand										
Level 2	Apply	-	40%	-	40%	-	40%	-	40%	-	40%
	Analyze										
Level 3	Evaluate	-	20%	-	30%	-	30%	-	30%	-	30%
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from Record and Model Examination.

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Dr. P.Selvanambi, Divisional Engineer (Highways), sundariselvam@yahoo.com	Dr.M.Mutharam, Anna University, muttharam@annauniv.edu	Ms.S. Mary Rebekah Sharmila, SRMIST.
Mr.Lenin K.R., Head –GEOTECH, SECON Private Limited, Bangalore, lenin.kr@secon.in	Dr.V.Murugaiyan, Pondichery Engineering College, vmurugaiyan@pec.edu	Ms.Divya Krishnan K, SRMIST

Course Code	18CEC303T	Course Name	HIGHWAY ENGINEERING AND DESIGN			Course Category	C	Professional Core Course										L	T	P	C			
																	2	1	0	3				
Pre-requisite Courses		Nil		Co-requisite Courses		Nil		Progressive Courses		Nil														
Course Offering Department			CIVIL ENGINEERING			Data Book / Codes/Standards			Nil															
Course Learning Rationale (CLR):		The purpose of learning this course is to:					Learning			Program Learning Outcomes (PLO)														
CLR-1 :		Understand the concepts in the geometric design of highway					1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :		Learn the needs and concepts in horizontal and vertical alignment of highway					Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :		Learn various traffic studies required for traffic management																						
CLR-4 :		Learn the design of various infrastructure facilities required for the traffic																						
CLR-5 :		Understand the material requirement of flexible pavement and design the pavement																						
CLR-6 :		Understand the components of rigid pavement and its design																						
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:					2	85	80	H	H	M	H	-	-	M	-	-	-	-	-	M	-	-
CLO-1 :		Design the geometric cross-section of highway					2	85	75	H	H	H	H	-	-	M	-	-	-	-	-	M	-	-
CLO-2 :		Design the horizontal and vertical alignment of highway					2	80	75	M	H	L	L	-	-	M	-	-	-	-	-	M	-	-
CLO-3 :		Conduct various traffic studies and analysis the volume and speed data					2	85	75	H	H	H	H	-	-	H	-	-	-	-	-	M	-	-
CLO-4 :		Plan and design the various infrastructure facilities required for the traffic					2	85	80	H	H	M	H	-	-	M	-	-	-	-	-	M	-	-
CLO-5 :		Execute the material and the structural design of flexible pavement					2	80	75	H	H	M	H	-	-	M	-	-	-	-	-	M	-	-
CLO-6 :		Execute the material and the structural design of flexible pavement					2			H	H	M	H	-	-	M	-	-	-	-	-	M	-	-
Duration (hour)		9		9		9		9		9		9												
S-1	SLO-1	Highway Geometric Design Elements of transportation Engineering		Extra widening and numerical examples		Traffic Facilities Design Traffic signs and		Flexible Pavement Component of Flexible pavement		Rigid Pavement Components of Rigid pavement														
	SLO-2	Overview of the course		Method of attaining superelevation in curves		Road markings		Functions of each component		Components of Rigid pavement – Details of joints														
S-2	SLO-1	Highway planning and Alignment		Set back distance and shift in curves with numerical examples		Channelization of traffic		Materials - Basic properties of bitumen		Stresses in Rigid pavement – Temperature stress														
	SLO-2	Classification of rural and urban roads		Reverse curve and compound curve		Channelization layouts		Binder grade and classification		Stresses in Rigid pavement – Temperature stress – numerical examples														
S-3	SLO-1	Cross sectional elements of roads		Design of vertical alignment – summit curve		Traffic rotary - design elements capacity of rotary		Materials – Soil and aggregate properties		Stresses in Rigid pavement – Wheel load stress														
	SLO-2	Terrain classification and speed and geometric standards for different terrain		Design of vertical alignment – summit curve – numerical example		Capacity of rotary		Resilient modulus of aggregate and soil		Stresses in Rigid pavement – Wheel load stress – Numerical examples														
S-4	SLO-1	Sight Distance – Stopping sight distance – Concept and derivations		Design of vertical alignment – valley curve		Rotary design - Numerical Example		Materials – Bituminous concrete mix properties		Stress combinations and critical stress														
	SLO-2	Stopping sight distance – Numerical examples		Design of vertical alignment – valley curve – Numerical example		Rotary design - Numerical Example		Materials – Types of bituminous concrete mix		Thickness of Rigid pavement														
S-5	SLO-1	Overtaking sight distance – assumptions and derivations		Traffic studies Fundamental traffic parameters - speed, density, volume, travel time		Grade separated intersection – Warrants and types		Bituminous concrete mix design		Design of Joint spacing														
	SLO-2	Overtaking sight distance – Numerical examples		Headway, and spacing -time mean speed, space mean speed – spot speed		Layout of grade separated intersection		Bituminous concrete mix design		Design of Joint spacing – Numerical examples														

S-6	SLO-1	Overtaking sight distance – Numerical examples	Traffic volume study – need and procedure	Elementsof traffic signal - headway, saturation flow	Flexible pavement design factor – Traffic factor	Dowel bar design
	SLO-2	Intersection sightdistance	Traffic volume calculation and analysis	Design principles of a traffic signal – Phase design, cycle time determination, green splitting	Traffic– equivalent single wheel load and standard axle load	Design of dowel bars – Numerical examples
S-7	SLO-1	Horizontal curve – circular curve radius	Spotspeed study – need and procedure	Two phase signal design – Numerical example	Traffic factor - truck factor, vehicle damage factor,number of repetition of standard axle load	Check for the adequacy of dowel bars – Numerical example
	SLO-2	Super elevation and minimum ruling radius	Traffic speed analysis	Two phase signal design – Numerical example	Number of repetition of standard axle load – Numerical examples	Check for the adequacy of dowel bars – Numerical example
S-8	SLO-1	Determination of radius and super elevation – numerical example	Speed study – Moving observer method	Three phase signal design- with exclusive pedestrian phase – Numerical example -	Design of flexible pavement – determination of pavement thickness (with unbounded layers)	Design of tie bars
	SLO-2	Determination of radius and super elevation – numerical example	Moving observer method – numerical calculation	Three phase signal design- with exclusive pedestrian phase – Numerical example -	Design of flexible pavement – determination of pavement thickness (with unbounded layers)	Design of tie bars – numericaexamples
S-9	SLO-1	Transition curve – length – assumptions and derivations	Parking study and demand analysis	Signal co-ordination	Design of flexible pavement – determination of pavement thickness (with bonded layers)	Codal provisions and issues in current design methods
	SLO-2	Transition curve – length – Numerical examples	Data to be studied in accident spots	Signal co-ordination – determination of bandwidth	Design of flexible pavement – determination of pavement thickness (with bonded layers)	Codal provisions and issues in current design methods

Learning Resources	<p>1. Chakroborthy and A. Das, "Principles of Transportation Engineering", Prentice-Hall of India, 2003</p> <p>2. S. K. Khanna, C.E.G. Justo and A. Veeraragavan, "Highway Engineering", Revised 10th edition, Nem Chand & Bros., Roorkee, 2014.</p> <p>3. Roess, R. P. McShane, W. R. & Prassas, E. S. (1998), Traffic Engineering, Prentice – Hall.</p>	<p>4. Papacostas, C. S. and Prevedouros, P.D. (2001) "Transportation Engineering and Planning", Prentice Hall of India Pvt. Ltd.</p> <p>5. Kadiyali, L. R. (1987), "Traffic Engineering and Transportation Planning", Khanna Publishers, India.</p> <p>6. Yang Huang, Pavement Analysis and Design, Pearson, 2004</p> <p>7. NPTEL – Introduction to Transportation Engineering - https://nptel.ac.in/courses/105105107/ (as on 05.07.2019)</p>
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	30%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of Assignments, Seminars, Tech Talks, Mini Projects, Case Studies, Self Study, MOOCs, Certifications, Conference Paper

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Dr. Asif Ahmed, Business manager, Ingevity, ahmed.asif@ingevity.com	Dr. Venkaiah Chowdary, Associate Professor, NITW, vc@nitw.ac.in	Dr.A.Padma Rekha, SRM IST
Mr. Ankit Pachouri, Transport Planner, IUT, New Delhi, ankit.pachouri@iutundia.org	Dr. V Sunitha, Assistant Professor, NITT, sunitha@nitt.edu	Mr.G.Sivaprakash, SRM IST

Course Code	18CEC303L	Course Name	HIGHWAY ENGINEERING LABORATORY	Course Category	C	Professional Core Course				L	T	P	C
										0	0	2	1

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Civil Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)															
CLR-1 :	Learn to measure traffic volume count and categorize different mode of traffic at straight road and intersection	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Analyze the travel time and speed characteristics				Problem Analysis	Design & Development	Analysis, Design, Research		Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3				
CLR-3 :	Study the parking characteristics																						
CLR-4 :	Measure the properties of bitumen and aggregates																						
CLR-5 :	Learn the proportioning of aggregate																						
CLR-6 :	Measure the volumetric and strength of bituminous mixture																						
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:						H	M	-	-	-	-	-	-	H	-	-	-	H	-	H	
CLO-1 :	Evaluate the vehicular composition in the straight road and intersection	3	90	85				H	M	-	-	-	-	-	-	-	H	-	-	-	H	-	H
CLO-2 :	Understand the travel time, delay and speed characteristics	3	85	80				H	M	-	-	-	-	-	-	-	H	-	-	-	H	-	H
CLO-3 :	Apply the effective parking systems	3	90	85				H	M	-	-	-	-	-	-	-	H	-	-	-	H	-	H
CLO-4 :	Grade the bitumen and select the aggregate for the preparation of bituminous mixture	3	85	80				H	M	-	-	-	-	-	-	-	H	-	-	-	H	-	H
CLO-5 :	Design the aggregate gradation for bituminous mixture	3	85	80				H	M	-	-	-	-	-	-	-	H	-	-	-	H	-	H
CLO-6 :	Design the bituminous mixture mix proportion	3	85	80				H	M	-	-	-	-	-	-	-	H	-	-	-	H	-	H

Duration (hour)	6	6	6	6	6
S 1-2	SLO-1 SLO-2	Determination of Vehicular composition in Straight moving traffic stream	Determination of traffic stream parameters by Moving Observer method	Determination of the penetration value of bitumen	Determination of ductility of bitumen
S 3-4	SLO-1 SLO-2	Determination of Vehicular turning movement at any intersection	Evaluation of on street parking characteristics	Determination of softening point of bitumen	Determination of specific gravity of bitumen and aggregates
S 5-6	SLO-1 SLO-2	Determination of instantaneous spot speed of vehicles	Evaluation of off street parking characteristics	Determination of viscosity of bitumen	Performance grading of bitumen - demo
					Batching of aggregates
					Preparation of bituminous mix and measure of mixture volumetric properties
					Marshall stability test and design of bituminous mix

Learning Resources	1. S. K Khanna, C E G Justo, A Veeraraghavan, Highway Engineering, Nem Chand and Bros 2. IS 73 : 2013, Paving Bitumen - Specification, 4th Revision, BIS, New Delhi			3. IS 15462:2004, Polymer and Rubber Modified Bitumen - Specification, BIS, New Delhi 4. MoRTH. Specification for roads and bridge work. Indian Roads Congress, New Delhi, India.		
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)		Theory	Practice
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice		
Level 1	Remember	-	40 %	-	30 %	-	30 %	-	30 %	-	30%
	Understand	-	40 %	-	30 %	-	30 %	-	30 %	-	30%
Level 2	Apply	-	40 %	-	40 %	-	40 %	-	40 %	-	40%
	Analyze	-	40 %	-	40 %	-	40 %	-	40 %	-	40%
Level 3	Evaluate	-	20 %	-	30 %	-	30 %	-	30 %	-	30%
	Create	-	20 %	-	30 %	-	30 %	-	30 %	-	30%
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from Record and Model Examination.

Course Designers	Experts from Higher Technical Institutions		Internal Experts
Dr. Asif Ahmed, Business manager, Ingevity, ahmed.asif@ingevity.com	Dr. Venkaiah Chowdary, Associate Professor, NITW, vc@nitw.ac.in		Dr. A. Padma Rekha, SRM IST
Mr. Ankit Pachouri, Transport Planner, IUT, New Delhi, ankit.pachouri@iutundia.org	Dr. V Sunitha, Assistant Professor, NITT, sunitha@nitt.edu		Mr. G. Sivaprakash and Ms. R Dhanya, SRM IST

Course Code	18CEC304T	Course Name	CONSTRUCTION ENGINEERING AND MANAGEMENT	Course Category	C	Professional Core Course	L	T	P	C
							2	1	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Civil Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Identify the characteristics of project and planning aspects	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Solve the CPM and PERT problems and apply the concept of project planning																		
CLR-3 :	Identify the techniques of project controlling and monitoring																		
CLR-4 :	Analyse the project performance based on S-Curve and Earned Value																		
CLR-5 :	Analyze the basic concepts of various resources and its importance																		
CLR-6 :	Analyse the project performance based on Quality and Safety																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Accrue the knowledge the characteristics of project and planning aspects	2	85	75	H	L	M	-	L	-	-	-	H	H	H	M	H	-	-
CLO-2 :	Analyze the CPM and PERT problems and apply the concept of project planning	3	85	75	H	H	M	M	-	-	-	-	H	-	H	M	H	-	-
CLO-3 :	Accrue the knowledge project controlling and monitoring	2	85	75	L	H	M	H	M	-	-	-	M	-	H	M	H	-	-
CLO-4 :	Apply the mathematical techniques of S-Curve and Earned Value	3	85	75	H	H	M	H	-	-	-	-	L	M	H	M	H	-	-
CLO-5 :	Accrue the knowledge about Types of resources and its importance	2	85	75	H	L	L	L	-	M	H	L	-	-	H	M	H	-	-
CLO-6 :	Accrue comprehensive knowledge in Quality and safety	2	85	75	H	H	L	L	-	H	-	H	L	-	H	M	H	-	-

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Basics of Construction- Unique features of construction	Work break-down structure	Planning and organizing construction site and resources	Resource Planning- Procurement, Identification
	SLO-2	Construction projects types and features, Phases of a project	Activity lists	Site layout including enabling structures,	Types of resources, manpower, Equipment Material, Money, Time
S-2	SLO-1	Project Life cycle	Estimating durations	developing site organization, Documentation at site	Systems approach In resource management, Characteristics of resources
	SLO-2	Construction project planning and competency skills	Sequence of activities, Activity utility data	Manpower: planning,	Resources Utilization, measurement of actual resources required-Tools for measurement of resources
S-3	SLO-1	Stages of project planning: pre-tender planning	Techniques of planning- Bar charts, Gantt Charts.	organizing, staffing, motivation	Material: Functions of Material Management
	SLO-2	Pre-construction planning,	Networks: Basic terminology,	Histograms and S-Curves	Inventory cost, ABC analysis
S 4-5	SLO-1	Detailed construction planning	AOA, AON	Earned Value	EOQ Model
	SLO-2	Agencies involved and their methods of execution	Types of precedence relationships, Preparation of CPM networks	Supervision, Record keeping,	Equipment: Classification of Construction Equipment
S-6	SLO-1	Process of development of plans and schedules	Activity on link and activity on node representation,	Periodic progress reports, periodical progress meetings	Factors Behind the selection of Construction of equipment
	SLO-2	Role of client and contractor	critical and semi Critical paths	Updating of plans: purpose	Depreciation, Methods of Calculating Depreciation
S-7	SLO-1	Feasibility study - preliminary analysis - market, technical, financial,	Computation of float values	Frequency and methods of updating	Classes of Labor, Labor Productivity
	SLO-2	economic and ecological - detailed market and demand analysis- detailed technical analysis	Crashing Technique	Classification of costs, timecost trade-off in construction projects	Cost of Labour, Labour schedule, optimum use Labour

S-8	SLO-1	Time value of money, NPV	PERT- Assumptions underlying PERT analysis,	Common causes of time and cost overruns	Resource Scheduling- Bar chart, line of balance technique	Cost of Accidents
	SLO-2	Contracts and Types	determining three time estimates, analysis,	Corrective measures	Resource constraints and conflicts	Occupational health problems in construction
S-9	SLO-1	Important Terminologies: Delays, penalties and liquidated damages; Force Majeure, Suspension and Termination	Slack computations	Common Good Practices in Construction	Resource aggregation, allocation, smoothing and leveling	Organizing for safety and health.
	SLO-2	Bidding Process	Calculation of probability of completion.	Basics of Modern Project management systems	Resource smoothing problems	Safety inspection, Safety Audit

Learning Resources	1. Kumar Neeraj Jha, "Construction project management", Dorling Kindersley, New Delhi, 2013 2. Sengupta .B, Guha .H, "Construction management and planning", Tata Mcgraw Hill, New Delhi, 2001 3. Sharma .S.C, "Construction engineering and management", Khanna Publishers, Delhi, 2008	4. Prasanna Chandra, "Planning, Analysis, Selection, Financing, Implementation, and Review", 7 th Edition, Tata Mcgraw Hill, New Delhi, 2001. 5. Principles of Construction Management https://nptel.ac.in/courses/105104161/ 6. Project Planning & Control https://nptel.ac.in/courses/105106149/
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%		40%		40%		40%		40%	
	Understand										
Level 2	Apply	40%		40%		40%		40%		40%	
	Analyze										
Level 3	Evaluate	20%		20%		20%		20%		20%	
	Create										
	Total	100 %		100 %		100 %		100 %		100 %-	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. Jayasankar k, Zonal Head (Technical Services) at UltraTech Cement Limited, jayasankar2411@gmail.com	Dr. Radhakrishna, R.V. College of Engineering (RVCE), radhakrishna@rvce.edu.in	Dr. L. Krishnaraj, SRM IST
Mr. V. Krishnaraju, Modec Offshore Production Systems Pvt. Ltd, krishnaraju.vaithianathan@modec.com	Dr. K.Yogeswari,, B.S. Abdur Rahman Crescent Institute of Science and technology, yogeswari@crescent.education	Mr. N. Ganapathy Ramasamy, SRM IST

Course Code	18CEC304L	Course Name	CONSTRUCTION ENGINEERING & MANAGEMENT LABORATORY				Course Category	C	Professional Core										L	T	P	C			
																			0	0	2	1			
Pre-requisite Courses		Nil		Co-requisite Courses		Nil		Progressive Courses		Nil															
Course Offering Department			Civil Engineering				Data Book / Codes/Standards				Nil														
Course Learning Rationale (CLR):		The purpose of learning this course is to:						Learning 123 Level of Thinking (Bloom)Expected Proficiency (%)Expected Attainment (%)			Program Learning Outcomes (PLO)														
CLR-1 :	Understand the basic skills in network framing						1				2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLR-2 :	Identifying the Activity involved in construction projects						Engineering Knowledge				Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3	
CLR-3 :	Understand the concept of Scheduling						H				H	-	-	-	H	-	-	-	-	-	-	H	-	-	
CLR-4 :	Apply the concept of Planning and scheduling						H				H	-	-	-	-	-	-	-	-	H	-	H	-	-	
CLR-5 :	Identify the resource requirement						H				H	-	M	-	-	-	-	-	-	-	-	H	-	-	
CLR-6 :	Identify resource allocation						H				H	-	M	-	-	-	-	H	-	-	-	H	-	-	
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:						38575 28575 28575 28575 38575 38575			H H - - - H - - - - - H - - - - - H H - M - - - - H - - - - H H - M - - - - H - - - - H H - M - - - - H - - - - H														
CLO-1 :	Accrue the knowledge in Project network diagrams						H				H	-	-	-	H	-	-	-	-	-	-	H	-	-	
CLO-2 :	Analyze the construction activities and activity sequence						H				H	-	-	-	H	-	-	-	-	-	-	H	-	-	
CLO-3 :	Accrue the knowledge in different scheduling charts						H				H	-	-	-	-	-	-	-	-	H	-	H	-	-	
CLO-4 :	Accrue the knowledge in planning of activities in order						H				H	-	M	-	-	-	-	-	-	-	-	H	-	-	
CLO-5 :	Develop the schedule with resources						H				H	-	M	-	-	-	-	-	H	-	-	-	H	-	-
CLO-6 :	Analyze over allocation and under allocation of resources						H				H	-	M	-	-	-	-	-	H	-	-	-	H	-	-
Duration (hour)		6		6		6		6		6		6		6		6		6		6		6			
S-1	SLO-1	MSP- Basic Network diagrammes		Resource list		Complete schedule for Institutional projects		Activity Entry		Complete schedule for Residential projects															
	SLO-2	Terms involved		Resource assigning				Activity Entry																	
S-2	SLO-1	Activity in projects		Resource analysis		Complete schedule for Infra structure projects		Activity Entry		Complete schedule for Residential projects															
	SLO-2	Activity sequence		Resource usage				Activity Entry																	
S-3	SLO-1	Main activities and Sub activities		Cost analysis		Complete schedule for Infra structure projects		Resource list		Complete schedule for Institutional projects															
	SLO-2	Relationship line and precedence relationship		Tracking				Resource assigning																	
S-4	SLO-1	Calendar design and assign		Complete schedule for Residential projects		Primavera Basics		Resource analysis		Complete schedule for Institutional projects															
	SLO-2	Gantt chart and PERT diagram				EPS		Resource usage																	
S-5	SLO-1	Activity resource estimation		Complete schedule for Residential projects		OBS and WBS		Cost analysis		Complete schedule for Infra structure projects															
	SLO-2	Activity duration estimation				Types of calendar		Tracking																	
S-6	SLO-1	Activity entry		Complete schedule for Institutional projects		Relationship lines and Constraints		Linking WBS, OBS and EPS		Complete schedule for Infra structure projects															
	SLO-2	Activity entry				New project Creation		Multiple project entry																	
Learning Resources		1. Laboratory Manual 2. Feigenbaum.L, "Construction Scheduling with Primavera Project Planner", Prentice Hall Inc., 1999. 3. "Project planning and management: Primavera Reference guide", CADD Centre training services 4. Paul F. Aubin, "Mastering Autodesk Revit Building", Cengage Learning, March 2006.						5. Robert M. Thomas, "Advanced AutoCAD Release" 12, ED 3, Wiley, John & Sons, Incorporated, 1993. 6. "Project planning and management: MS Project specially for Civil professional", CADD Centre training services 7. Geprge Omura, "Introducing AutoCAD 2010 and AutoCAD LT 2010", Willey India Pvt. Ltd., 2010.																	

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	-	40%	-	30%	-	30%	-	30%	-	30%
	Understand										
Level 2	Apply	-	40%	-	40%	-	40%	-	40%	-	40%
	Analyze										
Level 3	Evaluate	-	20%	-	30%	-	30%	-	30%	-	30%
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from Record and Model Examination.

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. Jayasankar K, Zonal Head (Technical Services) at ultraTech cement Limited, jayasankar2411@gmail.com	Dr. Radhakrishna, R.V. College of Engineering (RVCE), radhakrishna@rvce.edu.in	Dr. L. Krishnaraj, SRMIST
Mr. V. Krishnaraju,, Modec Offshore Production Systems, pvt,ltd, krishnaraju.vaithyanathan@modec.com	Dr. K.Yogeswari, B.S. Abdur Rahman Crescent Institute of Science and technology, yogeswari@crescent.education	Dr. M. Balasubramanian, SRMIST

Course Code	18CEC350T	Course Name	COMPREHENSION	Course Category	C	Professional Core			
						L	T	P	C
						0	1	0	1

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Civil Engineering	Data Book / Codes/Standards	As Applicable		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Acquire skills to solve real world problems in Engineering Geology and Engineering Surveying	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Acquire skills to solve real world problems in Mechanics of Structures, Design of RCC & Steel and Structural Analysis	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Acquire skills to solve real world problems in Fluid Mechanics, Hydraulic Engineering Design and Hydrology																		
CLR-4 :	Acquire skills to solve real world problems in Geotechnical Engineering																		
CLR-5 :	Acquire skills to solve real world problems in Environmental Engineering																		
CLR-6 :	Acquire skills to solve real world problems in Transportation Engineering																		

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Practice and gain confidence to solve problems in Engineering Geology and Engineering Surveying	3	85	80	H	H	M	L	L	L	L	L	L	L	L	L	H	M	H
CLO-2 :	Practice and gain confidence to solve problems in Mechanics of Structures, Design of RCC & Steel and Structural Analysis	3	85	80	H	H	H	L	L	L	L	L	L	L	L	L	H	M	H
CLO-3 :	Practice and gain confidence to solve problems in Fluid Mechanics, Hydraulic Engineering Design and Hydrology	3	85	80	H	H	M	L	L	L	L	L	L	L	L	L	H	L	H
CLO-4 :	Practice and gain confidence to solve problems in Geotechnical Engineering	3	85	80	H	H	M	L	L	L	L	L	L	L	L	L	H	L	H
CLO-5 :	Practice and gain confidence to solve problems in Environmental Engineering	3	85	80	H	H	M	L	L	L	L	L	L	L	L	L	H	L	H
CLO-6 :	Practice and gain confidence to solve problems in Transportation Engineering	3	85	80	H	H	H	L	L	L	L	L	L	L	L	L	H	L	H

Duration (hour)	3	3	3	3	3
S-1	SLO-1 SLO-2 Tutorial on Engineering Geology and Engineering Surveying	Tutorial on Mechanics of Structures	Tutorial on Structural Analysis	Tutorial on Geotechnical Engineering	Tutorial on Environmental Engineering
S-2	SLO-1 SLO-2 Tutorial on Engineering Geology and Engineering Surveying	Tutorial on Design of RCC and Steel Structures	Tutorial on Fluid Mechanics and Hydraulic Engineering Design and Hydrology	Tutorial on Geotechnical Engineering	Tutorial on Transportation Engineering
S-3	SLO-1 SLO-2 Tutorial on Mechanics of Structures	Tutorial on Design of RCC and Steel Structures	Tutorial on Fluid Mechanics and Hydraulic Engineering Design and Hydrology	Tutorial on Environmental Engineering	Tutorial on Transportation Engineering

Learning Resources	1. Handa, S., and Rangaswamy, Civil Engineering Objective Type, Satya Prakashan, 2017 2. Agor, R., Objective Type and Conventional Questions and Answers on Civil Engineering for All Types of Examinations & Interviews, Khanna Publishers, 2019	3. Venkatramaiah, C., and Krishna Sharma, A., A Compendium of Objective Questions in Civil Engineering, Universities Press, 2014
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (100% weightage)								Final Examination	
		CLA – 1 (20%)		CLA – 2 (30%)		CLA – 3 (30%)		CLA – 4 (20%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	-	40%	-	30%	-	30%	-	30%	-	-
	Understand	-	40%	-	30%	-	30%	-	30%	-	-
Level 2	Apply	-	40%	-	40%	-	40%	-	40%	-	-
	Analyze	-	40%	-	40%	-	40%	-	40%	-	-
Level 3	Evaluate	-	20%	-	30%	-	30%	-	30%	-	-
	Create	-	20%	-	30%	-	30%	-	30%	-	-
	Total	100 %		100 %		100 %		100 %		-	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Er. G.Hariharanath, GA Consultants, Chennai, gac1996@hotmail.com	1. Dr. G. Appa Rao, Professor, IIT Madras, garao@iitm.ac.in	1. Dr. K. S. Satyanarayanan, SRMIST
2. Er. AGV. Design, Design Group Engineering Consultancy Pvt Ltd. Chennai, design.agv@gmail.com	2. Dr. C. Uma Rani, Professor, Anna University, umarani@annauniv.edu	2. Prof. G. Augustine Maniraj Pandian, SRMIST

ACADEMIC CURRICULA

Professional Core Courses

COMPUTER SCIENCE AND ENGINEERING

Regulations - 2018



SRM INSTITUTE OF SCIENCE AND TECHNOLOGY

(Deemed to be University u/s 3 of UGC Act, 1956)

Kattankulathur, Kancheepuram, Tamil Nadu, India

Course Code	18CSC301T	Course Name	FORMAL LANGUAGE AND AUTOMATA	Course Category	C	Professional Core	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Utilize the mathematics and engineering principles for the basics of Formal Language				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2 :	Acquire knowledge of Automata and minimize with Regular language's				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgr. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3		
CLR-3 :	Acquire knowledge of Context free Grammar and simplify using normal forms																							
CLR-4 :	Gain knowledge to push down automata and apply it with CFL																							
CLR-5 :	Analyze the methods of turning machine																							
CLR-6 :	Analyze and Design the methods of computational complexity																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1 :	Acquire the knowledge of mathematics and engineering principles for the basics of Formal Language				3	80	70	M	H	-	H	L	-	-	-	L	L	-	H	-	-	-		
CLO-2 :	Acquire the ability to identify specification of a Regular language's with Automata				3	85	75	M	H	L	M	L	-	-	-	M	L	-	H	-	-	-		
CLO-3 :	Acquire knowledge of Context free Grammar and simplify using normal forms				3	75	70	M	H	M	H	L	-	-	-	M	L	-	H	-	-	-		
CLO-4 :	Understand the concepts of push down automata and CFL .				3	85	80	M	H	M	H	L	-	-	-	M	L	-	H	-	-	-		
CLO-5 :	Apply the knowledge to turning machine and its methods				3	85	75	H	H	M	H	L	-	-	-	M	L	-	H	-	-	-		
CLO-6 :	Design the computational and acceptor machines using FA, PDA and Turing machines				3	80	70	L	H	-	H	L	-	-	-	L	L	-	H	-	-	-		

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)
CLO-1 :	Acquire the knowledge of mathematics and engineering principles for the basics of Formal Language	3	80	70
CLO-2 :	Acquire the ability to identify specification of a Regular language's with Automata	3	85	75
CLO-3 :	Acquire knowledge of Context free Grammar and simplify using normal forms	3	75	70
CLO-4 :	Understand the concepts of push down automata and CFL .	3	85	80
CLO-5 :	Apply the knowledge to turning machine and its methods	3	85	75
CLO-6 :	Design the computational and acceptor machines using FA, PDA and Turing machines	3	80	70

Duration (hour)	11	9	9	9	7
S-1	SLO-1 Introduction to Automaton	Grammars: Introduction: Types of Grammar	Pushdown Automata: Definitions Moves	Turing Machines: Introduction	Undecidability :Basic definitions
	SLO-2 Mathematical concepts	Context Free Grammars and Languages	Instantaneous descriptions	Formal definition of Turing machines, Instantaneous descriptions	Decidable problems,
S-2	SLO-1 Formal Languages: Strings, Languages, Properties	Derivations	Deterministic pushdown automata	Turing Machine as Acceptors	Examples of undecidable problems and Problems
	SLO-2 Finite Representation : Regular Expressions	Ambiguity	Problems related to DPDA	Problems related to turning machine as Acceptors	Rice's Theorem
S-3	SLO-1 Problems related to regular expressions	Relationship between derivation and derivation trees	Non - Deterministic pushdown automata	Problems related to turning machine as Acceptors	Undecidable problems about Turing Machine- Post's Correspondence Problem
	SLO-2 Finite Automata :Deterministic Finite Automata	Problems related to Context free Grammar	Problems related to NDPDA		Problems related to Post's Correspondence Problem
S-4	SLO-1 Nondeterministic Finite Automata	Simplification of CFG : Elimination of Useless Symbols	Problems related to DPDA and NDPDA	Turing Machine as a Computing Device	Properties of Recursive and Recursively enumerable languages
	SLO-2 Finite Automaton with ϵ - moves			Problems related to turning Turing Machine as a Computing Device	
S-5	SLO-1 Problems related to Deterministic and Nondeterministic Finite Automata	Simplification of CFG : Unit productions	Pushdown automata to CFL Equivalence	Problems related to turning Turing Machine as a Computing Device	Introduction to Computational Complexity: Definitions
	SLO-2 Problems related to Finite Automaton with ϵ - moves	Simplification of CFG : Null productions	Problems related to Equivalence of PDA to CFG		Time and Space complexity of TMs
S-6	SLO-1 Equivalence of NFA and DFA	Problems related to Simplification of CFG	Problems related to Equivalence of PDA to CFG	Techniques for Turing Machine Construction	Complexity classes: Class P, Class NP
	SLO-2 Heuristics to Convert NFA to DFA				
S-7	SLO-1 Equivalence of NDFA's with and without ϵ - moves	Chomsky normal form	CFL to Pushdown automata Equivalence	Considering the state as a tuple Considering the tape symbol as a tuple	Complexity classes: Introduction to NP-Hardness

	SLO-2	Problems related Equivalence of NDFA's with and without ϵ -moves	Problems related to CNF	Problems related to Equivalence of CFG to PDA	Checking off symbols	NP Completeness
S-8	SLO-1	Minimization of DFA	Greiback Normal form	Pumping lemma for CFL	Modifications of Turing Machine	
	SLO-2	Problems related to Minimization of DFA			Multi-tape Turing Machine	
S-9	SLO-1	Regular Languages : Equivalence of Finite Automata and Regular Languages	Problems related to GNF	Problems based on pumping Lemma	Non-Deterministic Turing Machine	
	SLO-2	Equivalence of Finite Automata and Regular Grammars			Semi-Infinite Tape Turing Machine	
S-10	SLO-1	Problems related to Equivalence of Finite Automata and Regular Languages and Regular Grammars				
	SLO-2	Variants of Finite Automata : Two-way Finite Automaton Mealy Machines				
S-11	SLO-1	Properties of Regular Languages: Closure Properties				
	SLO-2	Set Theoretic Properties & Other Properties				
	SLO-3	Pumping Lemma				

Learning Resources	<p>1. Hopcroft J.E., Motwani R. and Ullman J.D., "Introduction to Automata Theory, Languages and Computations", Second Edition, Pearson Education, 2008.</p> <p>2. Michael Sipser, "Introduction to the Theory of Computation" Cengage Learning, 2012.</p>	<p>4..John.C.Martin, "Introduction to Languages and the Theory of Computation" McGraw-Hill Education, 01- May-2010.</p> <p>5. Kamala Krithivasan, Rama.R," Introduction to Formal Languages, Automata Theory and Computation", Pearson Education India, 01-Sep-2009.</p> <p>6. Peter Linz , "An introduction to formal languages and automata", Jones & Bartlett Learning, 2001.</p>
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
		Dr.R.AnnieUthra
		Dr.Jeyasudha

Course Code	18CSC302J	Course Name	COMPUTER NETWORKS	Course Category	C	Professional Core	L	T	P	C
							3	0	2	4

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department		Computer Science and Engineering	Data Book / Codes/Standards	Nil	

Course Learning Rationale (CLR):		The purpose of learning this course is to:				Learning			Program Learning Outcomes (PLO)															
CLR-1 :	Understand the evolution of computer networks using the layered network architecture					Level of Thinking (Bloom)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Understand the addressing concepts and learn networks devices						Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3	
CLR-3 :	Design computer networks using subnetting and routing concepts																							
CLR-4 :	Understand the error types , framing, flow control																							
CLR-5 :	Understand the various Medium Access Control techniques and also the characteristics of physical layer functionalities																							
CLR-6 :	Understand basic network administration																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1 :	Acquire the basics of computer network and its architecture					3	80	70	L	H	-	H	L	-	-	-	L	L	-	H	-	-	-	-
CLO-2 :	Acquire the knowledge of various networks devices and addressing methods					3	85	75	M	H	L	M	L	-	-	-	M	L	-	H	-	-	-	-
CLO-3 :	Ability to design the network routing methods					3	75	70	M	H	M	H	L	-	-	-	M	L	-	H	-	-	-	-
CLO-4 :	Acquire the various error codes and framing concepts					3	85	80	M	H	M	H	L	-	-	-	M	L	-	H	-	-	-	-
CLO-5 :	Ability to understand the physical layer functions and components					3	85	75	H	H	M	H	L	-	-	-	M	L	-	H	-	-	-	-
CLO-6 :	Ability to design a computer network using a switch and router					3	80	70	L	H	-	H	L	-	-	-	L	L	-	H	-	-	-	-

Duration (hour)	15	15	15	15	15
S-1	SLO-1 Evolution of Computer Networks	Addressing types	Network layer functionalities	Introduction- error types	Physical layer overview
	SLO-2 The Internet today	Physical, logical, port, specific addresses	Delivery vs Forwarding	Detection vs Correction	Functionalities
S-2	SLO-1 Data communications	IPv4 addresses	Unicast routing protocols	Error detection	Analog and digital
	SLO-2 Components	Notations	Intra , inter domain routing	Parity	Data, signals
S-3	SLO-1 Networks	Classful addressing	Multicast routing protocols	CRC	Transmission impairment
	SLO-2 Physical structures	Categories	Applications	Checksum	Attenuation, Distortion, Noise
S 4-5	SLO-1 Lab 1: Introduction to Packet racer	Lab 4 :IP Addressing and subnetting (VLSM).	Lab 7 : Implementation of Static Routing	Lab 10: Implementation of EIGRP Configuration	Lab 13: Implementation of Single-Area OSPF Link Costs and Interface
	SLO-2				
S-6	SLO-1 Network models	Classless addressing	Distance vector routing	Error correction	Performance metrics
	SLO-2 Categories of network	Prefix usage	Node instability issues	Hamming code	Bandwidth, delay, throughput, jitter
S-7	SLO-1 Protocols and standards	Network Address Translation(NAT)	RIPv1	Framing	Wireless 802.11
	SLO-2 Standards organizations	Translation table	RIPv2	Flow control	Addressing mechanism

S-8	SLO-1	Layered tasks	IPv6 addresses	Link state routing	Error control	Transmission Media
	SLO-2	Hierarchy	Types, Notation	Dijkstra's Algorithm	ARQ types	Twisted pair, Coaxial, Fibre
S 9-10	SLO-1	Lab 2: Implementation of various	Lab 5: Configuring Interfaces	Lab 8: Implementation of Default Routing	Lab 11: Implementation of EIGRP Bandwidth and Adjacencies	Lab 14: Implementation of Multi-Area OSPF with Stub Areas and Authentication
	SLO-2	Topology creation				
S-11	SLO-1	OSI model	VLSM	OSPF	Random access	IEEE 802.15
	SLO-2	Layered approach, Peer-peer approach	Masking	EIGRP	ALOHA	Architecture
S-12	SLO-1	Layers in the OSI model	CIDR	Path vector routing	CSMA/CD	IEEE 802.15.4
	SLO-2	Comparison of layers	Address aggregation	Stabilized routing table creation for AS	CSMA/CA	Architecture
S-13	SLO-1	TCP/IP protocol suite	Networking devices	BGP	Controlled access	IEEE 802.16
	SLO-2	Comparison with OSI model	Router, Switch, hub, Bridges	BGP Sessions	Channelization	Architecture
S 14-15	SLO-1	Lab 3: Implement the categories of network(LAN,MAN,WAN)	Lab 6: Basic Router Configuration, Creating Passwords	Lab 9: Implementation of RIPv1, v2	Lab 12: Implementation of EIGRP Authentication and Timers	Lab 15: Redistribution Between EIGRP and OSPF

Learning Resources	1. Behrouz A.Forouzan,"Data Communications and Networking"5 th edition,July1,2010,ISBN: 9780073376226. 2. Todd Lammle,"CCNA Study Guide",Edition7,2011, ISBN:13:9780470901076. William Stallings,"Data and Computer Communications",Edition9,2010.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		-	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry		Experts from Higher Technical Institutions
1. . Dr. Sricharan, Wipro Technologies, Chennai		1. Dr.Noor Mahammad, IIITDM, Kancheepuram, noor@iiitdm.ac.in
2.		2.
		3.
		Internal Experts
		1. Mr. K. Venkatesh, SRMIST
		2. Ms.D. Anitha, SRMIST
		3. Ms. Femi Ukrit, SRMIST

Course Code	18CSC303J	Course Name	DATABASE MANAGEMENT SYSTEMS	Course Category	C	Professional Core	L	T	P	C
							3	0	2	4

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
			1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-1 :	Understand the fundamentals of Database Management Systems, Architecture and Languages		Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-2 :	Conceive the database design process through ER Model and Relational Model																			
CLR-3 :	Design Logical Database Schema and mapping it to implementation level schema through Database Language																			
CLR-4 :	Familiarize queries using Structure Query Language (SQL) and PL/SQL																			
CLR-5 :	Familiarize the Improvement of the database design using normalization criteria and optimize queries																			
CLR-6 :	Understand the practical problems of concurrency control and gain knowledge about failures and recovery																			
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																		
CLO-1 :	Acquire the knowledge on DBMS Architecture and Languages		3	80	70	H	M	L	L	-	-	-	-	L	L	L	H	-	-	-
CLO-2 :	Apply the fundamentals of data models to model an application's data requirements using conceptual modeling tools like ER diagrams		3	85	75	H	H	H	H	H	-	-	-	H	H	H	H	-	-	-
CLO-3 :	Apply the method to convert the ER model to a database schemas based on the conceptual relational model		3	75	70	H	H	H	H	H	-	-	-	H	H	H	H	-	-	-
CLO-4 :	Apply the knowledge to create, store and retrieve data using Structure Query Language (SQL) and PL/SQL		3	85	80	H	H	H	H	H	-	-	-	H	H	H	H	-	-	-
CLO-5 :	Apply the knowledge to improve database design using various normalization criteria and optimize queries		3	85	75	H	H	L	M	L	-	-	-	M	M	M	L	-	-	-
CLO-6 :	Appreciate the fundamental concepts of transaction processing- concurrency control techniques and recovery procedures.		3	85	75	H	L	L	L	L	-	-	-	H	L	L	L	-	-	-

Duration (hour)	15	15	15	15	15
S-1	SLO-1	What is Database Management System	Database Design	Basics of SQL-DDL,DML,DCL, TCL	Relational Algebra – Fundamental Operators and syntax, relational algebra queries, Tuple relational calculus
	SLO-2	Advantage of DBMS over File Processing System	Design process	Structure Creation, alteration	Transaction concepts, properties of transactions,
S-2	SLO-1	Introduction and applications of DBMS	Entity Relation Model	Defining Constraints-Primary Key, Foreign Key, Unique, not null, check, IN operator	Serial ization of transactions, testing for serial inability, System recovery,
	SLO-2	Purpose of database system			
S-3	SLO-1	Views of data	ER diagram	Functions-aggregation functions	Concurrency Control
	SLO-2			Built-in Functions-numeric, date, string functions, string functions, Set operations,	
S 4-5	SLO-1	Lab 1: SQL Data Definition Language Commands on sample exercise	Lab4 : Inbuilt functions in SQL on sample Exercise.	Lab 7 : Join Queries on sample exercise. * Frame and execute the appropriate DDL,DML,DCL,TCL for the project	Lab 10: PL/SQL Procedures on sample exercise. * Frame and execute the appropriate Join Queries for the project
	SLO-2	* The abstract of the project to construct database must be framed			
S-6	SLO-1	Database system Architecture	Keys , Attributes and Constraints	Sub Queries, correlated sub queries	Two- Phase Commit protocol, Recovery and Atomicity
	SLO-2				
S-7	SLO-1	Data Independence	Mapping Cardinality	Nested Queries, Views and its Types	Log-based recovery
	SLO-2				
S-8	SLO-1	The evolution of Data Models	Extended ER - Generalization, Specialization and Aggregation	Transaction Control Commands	concurrent executions of transactions and related problems
	SLO-2				
S 9-10	SLO-1	Lab 2: SQL Data Manipulation	Lab 5: Construct a ER Model for the	Lab 8: Set Operators & Views.	Lab 11: PL/SQL Functions
					Lab 14: PL/SQL Trigger

	SLO-2	Language Commands * Identification of project Modules and functionality	application to be constructed to a Database	* Frame and execute the appropriate In- Built functions for the project	* Frame and execute the appropriate Set Operators & Views for the project	* Frame and execute the appropriate PL/SQL Cursors and Exceptional Handling for the project
S-11	SLO-1 SLO-2	Degrees of Data Abstraction	ER Diagram Issues Weak Entity	PL/SQL Concepts- Cursors	BCNF	Locking mechanism, solution to concurrency related problems
S-12	SLO-1 SLO-2	Database Users and DBA	Relational Model	Stored Procedure, Functions Triggers and Exceptional Handling	Multi- valued dependency, 4NF	Deadlock
S-13	SLO-1 SLO-2	Database Languages	Conversion of ER to Relational Table	Query Processing	Join dependency and 5NF	two-phase locking protocol, Isolation, Intent locking
S 14-15	SLO-1 SLO-2	Lab 3: SQL Data Control Language Commands and Transaction control commands to the sample exercises * Identify the issues that can arise in a business perspective for the application	Lab 6: Nested Queries on sample exercise * Construction of Relational Table from the ER Diagram	Lab9: PL/SQL Conditional and Iterative Statements * Frame and execute the appropriate Nested Queries for the project	Lab 12: PL/SQL Cursors * Frame and execute the appropriate PL/SQL Conditional and Iterative Statements for the project	Lab 15 : * Frame and execute the appropriate PL/SQL Cursors and Exceptional Handling for the project * Demo of the project

Learning Resources	<p>1. Abraham Silberschatz, Henry F. Korth, S. Sudharshan, Database System ConceptsII, Sixth Edition, Tata McGraw Hill, 2011.</p> <p>2. Ramez Elmasri, Shamkant B. Navathe, Fundamentals of Database SystemsII, Sixth Edition, Pearson Education, 2011.</p> <p>3. C.J Date, A Kannan, S Swamynathan, An Introduction to Database Systems, Eight Edition, Pearson Education, 2006.</p> <p>4. Rajesh Narang, Database Management Systems, 2nd ed., PHI Learning Private Limited, 2011.</p>	<p>4. Martin Gruber, Understanding SQL, Sybex, 1990</p> <p>5. Sharad Maheshwari, Introduction to SQL and PL/SQL, 2^d ed., Laxmi Publications, 2016.</p> <p>6. Raghurama Krishnan, Johannes Gehrke, Database Management Systems, 3rd Edition, McGraw Hill Education, 2003.</p>
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50%weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		-	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. Mariappan Vaithilingam, Engineering Leader Amazon, dr.v.m@ieee.org		1. Ms. Sasi Rekha Sankar SRMIST
2. Mr. Badinath, SDET, Amzon, sbadhrinath@gmail.com		2. Mr. Elizer, SRMIST
		3. Mrs. Hemavathy, SRMIST

Course Code	18CSC304J	Course Name	COMPILER DESIGN	Course Category	C	Professional Core	L	T	P	C
							3	0	2	4

Pre-requisite Courses	18CSC301T	Co-requisite Courses	Nil	Progressive Courses	
Course Offering Department	Computer Science and Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Utilize the mathematics and engineering principles for the Design of Compilers	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Acquire knowledge of Lexical Analyzer from a specification of a language's lexical rules	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Acquire knowledge of Syntax Analyzer for parsing the sentences in a compiler grammar																		
CLR-4 :	Gain knowledge to translate a system into various intermediate codes																		
CLR-5 :	Analyze the methods of implementing a Code Generator for compilers																		
CLR-6 :	Analyze and Design the methods of developing a Code Optimizer																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLR-1 :	Utilize the mathematics and engineering principles for the Design of Compilers	3	80	70	H	H	H	H	M	L	L	L	M	M	L	H	H	H	H
CLR-2 :	Acquire knowledge of Lexical Analyzer from a specification of a language's lexical rules	3	85	75	H	H	H	H	M	L	L	L	M	M	L	H	H	H	H
CLR-3 :	Acquire knowledge of Syntax Analyzer for parsing the sentences in a compiler grammar	3	75	70	H	H	H	H	M	L	L	L	M	M	L	H	H	H	H
CLR-4 :	Gain knowledge to translate a system into various intermediate codes	3	85	80	H	H	H	H	M	L	L	L	M	M	L	H	H	H	H
CLR-5 :	Analyze the methods of implementing a Code Generator for compilers	3	85	75	H	H	H	H	M	L	L	L	M	M	L	H	H	H	H
CLR-6 :	Analyze and Design the methods of developing a Code Optimizer	3	80	70	H	H	H	H	M	L	L	L	M	M	L	H	H	H	H

Duration (hour)	15	15	15	15	15
S-1	SLO-1 Compilers – Analysis of the source program	Syntax Analysis Definition - Role of parser	Bottom Up Parsing	Intermediate Code Generation	Code optimization
	SLO-2 Phases of a compiler – Cousins of the Compiler	Lexical versus Syntactic Analysis	Reductions	Intermediate Languages - prefix - postfix	Introduction– Principal Sources of Optimization
S-2	SLO-1 Grouping of Phases – Compiler construction tools	Representative Grammars	Handle Pruning	Quadruple - triple - indirect triples Representation	Function Preserving Transformation
	SLO-2 Lexical Analysis – Role of Lexical Analyzer	Syntax Error Handling	Shift Reduce Parsing	Syntax tree- Evaluation of expression - three-address code	Loop Optimization
S-3	SLO-1 Input Buffering	Elimination of Ambiguity, Left Recursion	Problems related to Shift Reduce Parsing	Synthesized attributes – Inherited attributes	Optimization of basic Blocks
	SLO-2 Specification of Tokens	Left Factoring	Conflicts During Shift Reduce Parsing	Intermediate languages – Declarations	Building Expression of DAG
S 4-5	SLO-1 Lab 1 - Implementation of Lexical Analyzer	Lab 4 Elimination of Ambiguity, Left Recursion and Left Factoring	Lab 7 - Shift Reduce Parsing	Lab 10-Intermediate code generation – Postfix, Prefix	Lab 13 Implementation of DAG
	SLO-2 Finite automation - deterministic	Top down parsing	LR Parsers- Why LR Parsers	Assignment Statements	Peephole Optimization
S-6	SLO-2 Finite automation - non deterministic	Recursive Descent Parsing, back tracking	Items and LR(0) Automaton, Closure of Item Sets,	Boolean Expressions, Case Statements	Basic Blocks, Flow Graphs
S-7	SLO-1 Transition Tables	Computation of FIRST	LR Parsing Algorithm	Back patching – Procedure calls	Next-Use Information

	SLO-2	Acceptance of Input Strings by Automata	Problems related to FIRST	Operator Precedence Parser Computation of LEADING	Code Generation	Introduction to Global Data Flow Analysis
S-8	SLO-1	State Diagrams and Regular Expressions	Computation of FOLLOW	Computation of TRAILING	Issues in the design of code generator	Computation of gen and kill
	SLO-2	Conversion of regular expression to NFA – Thompson's	Problems related to FOLLOW	Problems related to LEADING AND TRAILING	The target machine – Runtime Storage management	Computation of in and out
S 9-10	SLO-1	Lab 2 conversion from Regular Expression to NFA	Lab 5 -FIRST AND FOLLOW computation	Lab 8- Computation of LEADING AND TRAILING	Lab 11 Intermediate code generation – Quadruple, Triple, Indirect triple	Lab 14 : Implementation of Global Data Flow Analysis
	SLO-2	Conversion of NFA to DFA	Construction of a predictive parsing table	SLR Grammars	A simple Code generator	Parameter Passing.
S-11	SLO-1	Simulation of an NFA	Predictive Parsers LL(1) Grammars	SLR Parsing Tables	Code Generation Algorithm	Runtime Environments
	SLO-2	Converting Regular expression directly to DFA	Transition Diagrams for Predictive Parsers	Problems related to SLR	Register and Address Descriptors	Source Language issues
S-12	SLO-1	Minimization of DFA	Error Recovery in Predictive Parsing	Construction of Canonical LR(1) and LALR	Generating Code of Assignment Statements	Storage Organization
	SLO-2	Minimization of NFA	Predictive Parsing Algorithm	Construction of LALR	Cross Compiler – T diagrams	Activation Records
S-13	SLO-1	Design of lexical analysis (LEX)	Non Recursive Predictive Parser	Problems related to Canonical LR(1) and LALR Parsing Table	Issues in Cross compilers	Storage Allocation strategies
	SLO-2	Lab 3 Conversion from NFA to DFA	Lab 6 Predictive Parsing Table	Lab9 Computation of LR(0) items	Lab 12 : A simple code Generator	Lab 15: Implement any one storage allocation strategies(heap, stack, static)

Learning Resources	1. Alfred VAho, Jeffery DULLman, Ravi Sethi, "Compilers, Principle techniques and tools", Pearson Education 2011	4. K. Muneeswaran,., "Compiler Design", Oxford Higher Education, Fourth edition 2015
	2. S. Godfrey Winstler, S. Aruna Devi, R. Sujatha, "Compiler Design", Yesdee Publishing Pvt. Ltd, 2016	5. David Galles, "Modern Compiler Design", Pearson Education, Reprint 2012.
	3. William M. Waite and Gerhard Goos. Compiler Construction. Springer-Verlag, New York, 2013.	6. Raghavan V., "Principles of Compiler Design", Tata McGraw Hill Education Pvt. Ltd., 2010

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#		Theory	Practice
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice		
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
Level 2	Understand	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
Level 3	Apply	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Analyze										
	Evaluate										
	Create										
	Total	100 %		100 %		100 %		100 %		-	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry		Internal Experts
		1. Ms. R. Jeya
		2. Mrs. J. Jeyasudha

Course Code	18CSC305J	Course Name	ARTIFICIAL INTELLIGENCE	Course Category	C	Professional Core				L	T	P	C
										3	0	2	4

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering		Data Book / Codes/Standards	Nil	

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Provide a broad understanding of the basic techniques for building intelligent computer systems and an understanding of how AI is applied to problems.	1	2	3	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Gain knowledge in problem formulation and building intelligent agents	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3			
CLR-3 :	Understand the search technique procedures applied to real world problems																					
CLR-4 :	Understand the types of logic and knowledge representation schemes																					
CLR-5 :	Acquire knowledge in planning and learning algorithms																					
CLR-6 :	Gain knowledge in AI Applications and advances in Artificial Intelligence																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	Formulate a problem and build intelligent agents	1	80	70	M	M	M	M	H	-	-	-	M	L	-	H	L	L	L			
CLO-2 :	Apply appropriate searching techniques to solve a real world problem	2	85	75	M	H	H	H	H	-	-	-	M	L	-	H	M	L	M			
CLO-3 :	Analyze the problem and infer new knowledge using suitable knowledge representation schemes	2	75	70	M	H	H	M	H	-	-	-	M	L	-	H	M	L	M			
CLO-4 :	Develop planning and apply learning algorithms on real world problems	2	85	80	M	H	M	H	H	-	-	-	M	L	-	H	M	M	M			
CLO-5 :	Design an expert system and implement natural language processing techniques	3	85	75	M	H	H	H	H	-	-	-	M	L	-	H	H	M	H			
CLO-6 :	Implement advance techniques in Artificial Intelligence	3	80	70	L	H	M	M	H	-	-	-	H	L	-	H	H	M	H			

Duration (hour)		15	15	15	15	15
S-1	SLO-1	Introduction to AI-AI techniques	Searching techniques- Uniformed search-General search Algorithm	Knowledge and reasoning-Approaches and issues of knowledge reasoning	Planning- Planning problems, Simple planning agent	Expert system-Architecture
	SLO-2	Problem solving with AI	Uniformed search Methods-Breadth first search	Knowledge base agents-Logic Basics	Planning languages	Pros and Cons of expert system
S-2	SLO-1	AI Models, Data acquisition and learning aspects in AI	Uniformed search Methods-Depth first search	Logic-Propositional logic-syntax , semantics and inferences	Blocks world ,Goal stack planning	Rule based systems
	SLO-2	Problem solving- Problem solving process, Formulating problems	Uniformed search Methods-Depth limited search	Propositional logic- Reasoning patterns	Mean Ends Analysis	Frame based expert system
S-3	SLO-1	Problem types and characteristics	Uniformed search Methods- Iterative Deepening search	Predicate logic – Syntax and semantics, instance and is relationship	Non-linear Planning	Case study
	SLO-2	Problem space and search	Bi-directional search	Unification and Resolution	Conditional planning, Reactive planning	Case study
S-4-5	SLO-1	Lab 1: Implementation of toy problems	Lab4: Implementation and Analysis of DFS and BFS for an application	Lab 7: Implementation of unification and resolution for real world problems.	Lab 10 :Implementation of block world problem	Natural language processing-Levels of NLP
	SLO-2					
S-6	SLO-1	Intelligent agent	Informed search- Generate and test, Best First search	Knowledge representation using rules	Learning- Machine learning	Syntactic and Semantic Analysis
	SLO-2	Rationality and Rational agent with performance measures	Informed search-A* Algorithm	Knowledge representation using semantic nets	Goals and Challenges of machine learning	Information retrieval
S-7	SLO-1	Flexibility and Intelligent agents	AO* research	Knowledge representation using frames	Learning concepts, models	Information Extraction

	SLO-2	Task environment and its properties	Local search Algorithms-Hill Climbing, Simulated Annealing	Inferences	Artificial neural network based learning-Back propagation	Machine translation
S-8	SLO-1	Types of agents	Local Beam Search	Uncertain Knowledge and reasoning-Methods	Support vector machines	NLP Applications
	SLO-2	Other aspects of agents	Genetic Algorithms	Bayesian probability and belief network	Reinforcement learning	NLP Applications
S 9-10	SLO-1	Lab 2: Developing agent programs for real world problems	Lab 5: Developing Best first search and A* Algorithm for real world problems	Lab 8: Implementation of knowledge representation schemes - use cases	Lab 11: Implementation of learning algorithms for an application	Lab 14: Implementation of NLP programs
S-11	SLO-1	Constraint satisfaction problems(CSP)	Adversarial search Methods-Game playing-Important concepts	Probabilistic reasoning	Adaptive learning	Advance topics in Artificial Intelligence-Cloud Computing and intelligent agent
	SLO-2	Crypto arithmetic puzzles	Game playing and knowledge structure	Probabilistic reasoning over time	Multi agent based learning	Business intelligence and analytics
S-12	SLO-1	CSP as a search problem-constraints and representation	Game as a search problem-Mini max approach	Forward and backward reasoning	Ensemble learning	Sentiment Analysis
	SLO-2	CSP-Backtracking, Role of heuristic	Mini max Algorithm	Other uncertain techniques-Data mining	Learning for decision making	Deep learning Algorithms
S-13	SLO-1	CSP-Forward checking and constraint propagation	Alpha beta pruning	Fuzzy logic	Distributed learning	Deep learning Algorithms
	SLO-2	CSP-Intelligent backtracking	Game theory problems	Dempster -shafer theory	Speedup learning	Planning and logic in intelligent agents
S 14-15	SLO-1	Lab 3: Implementation of constraint satisfaction problems	Lab 6: Implementation of mini max algorithm for an application	Lab 9: Implementation of uncertain methods for an application	Lab 12: Development of ensemble model for an application	Lab 15: Applying deep learning methods to solve an application.

Learning Resources	<ol style="list-style-type: none"> 1. Parag Kulkarni, Prachi Joshi, Artificial Intelligence –Building Intelligent Systems, 1st ed., PHI learning, 2015 2. DeepakKemhane, First course in Artificial Intelligence, McGrawHill Pvt Ltd, 2013 3. Stuart J. Russell, Peter Norvig, Artificial Intelligence –A Modern approach, 3rd Pearson Education, 2016 4. Prateek Joshi, Artificial Intelligence with Python, 1st ed., Packt Publishing, 2017 5. Denis Rothman, Artificial Intelligence by Example, Packt, 2018
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	10%	10%	15%	15%	15%	15%	15%	15%
Level 2	Understand	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Apply										
Level 3	Analyze	10%	10%	20%	20%	15%	15%	15%	15%	15%	15%
	Evaluate										
	Create										
	Total	100 %		100 %		100 %		100 %		-	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Jagatheeswaran, Lead, Auxo labs jagatheeswarans.iot@auxolabs.in	1. Dr. Chitrakala, Anna University, au.chitras@gmail.com	1. Dr.M.Pushpalatha, SRMIST
2.	3.	2. Dr.G.Vadivu, SRMIST
		3. Dr.C.Lakshmi, SRMIST

Course Code	18CSC350T	Course Name	COMPREHENSION	Course Category	C	Professional Core	L	T	P	C
							0	1	0	1

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Acquire skills to solve real world problems in Data Structures and Analysis and Design of Algorithms	1	1
CLR-2 :	Acquire skills to solve real world problems in Object Oriented Design and Programming and advanced programming concepts	2	2
CLR-3 :	Acquire skills to solve real world problems in Operating systems , Computer networking and Formal Language and Automata	3	3
CLR-4 :	Acquire skills to solve real world problems in Compiler Design, Database Management systems and Software Engineering		4
CLR-5 :	Acquire skills to solve real world problems for competitive examinations in Mechanical Engineering		5
CLR-6 :	Acquire skills to solve real world problems in the broad domain of Mechanical Engineering		6

Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			Level of Thinking	Expected	Expected	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Practice and gain confidence, competence to solve problems in Data Structures and Analysis and Design of Algorithms				3	85	80	H	H	H	H	M	M	L	L	M	M	L	H	M	L	H
CLO-2 :	Practice and gain confidence, competence to solve problems in Object Oriented Design, Programming and advanced programming concepts				3	85	80	H	H	M	H	M	M	L	L	H	H	M	H	H	H	H
CLO-3 :	Practice and gain confidence, competence to solve problems in Operating systems , Computer networking, Formal Language and Automata				3	85	80	H	H	M	M	M	M	L	L	M	H	L	M	M	H	M
CLO-4 :	Practice and gain confidence, competence to solve problems in Compiler Design, Database Management systems and Software Engineering				3	85	80	H	H	M	H	H	H	L	L	H	H	H	H	M	H	H
CLO-5 :	Practice and gain confidence and competence to solve problems for competitive examinations in Computer Science and Engineering				3	85	80	H	H	H	L	L	L	L	L	L	L	L	M	L	M	M
CLO-6 :	Practice and gain confidence and competence to solve problems in the broad domain of Computer Science and Engineering				3	85	80	H	H	M	L	L	L	L	L	L	L	L	L	M	M	M

Duration (hour)	3	3	3	3	3
S-1	SLO-1 Tutorial on Linear Data Structures	Tutorial on Object Oriented Design	Tutorial on Operating Systems	Tutorial on Compiler Design	Problem Solving
	SLO-2 Problem Solving	Problem Solving	Problem Solving	Problem Solving	Problem Solving
S-2	SLO-1 Tutorial on Non Linear Data Structures	Tutorial on Object Oriented Programming	Tutorial on Computer networking	Tutorial on Database Management systems	Problem Solving
	SLO-2 Problem Solving	Problem Solving	Problem Solving	Problem Solving	Problem Solving
S-3	SLO-1 Tutorial on Analysis and Design of Algorithms	Tutorial on Advanced Programming concepts	Tutorial on Formal Language and Automata	Tutorial on Software Engineering	Problem Solving
	SLO-2 Problem Solving	Problem Solving	Problem Solving	Problem Solving	Problem Solving

Learning Resources	1. Jushta Jaiswal, Objective "Computer Science & Information Technology", Source books, , 2015 2. G.K.Mithal, "Objective Computer Science and Information Technology", G.K.Publishing, 10th edition, 2016	3. R.Agor, "Computer Science Conventional & Objective type solved questions", Birla Publishing, 2004 4. Timothy Williams, "MCQs in Computer Science", McGraw Hill, 5th edition, 2017 5. Surbhi Mitra, "Computer Science and IT", Arihant Handbook series, 2013
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (100% weightage)								Final Examination	
		CLA – 1 (20%)		CLA – 2 (30%)		CLA – 3 (30%)		CLA – 4 (20%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	-	40%	-	30%	-	30%	-	30%	-	-
	Understand	-	40%	-	30%	-	30%	-	30%	-	-
Level 2	Apply	-	40%	-	40%	-	40%	-	40%	-	-
	Analyze	-	40%	-	40%	-	40%	-	40%	-	-
Level 3	Evaluate	-	20%	-	30%	-	30%	-	30%	-	-
	Create	-	20%	-	30%	-	30%	-	30%	-	-
	Total	100 %		100 %		100 %		100 %		-	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers			
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts	
1. Dr. Anbu Rathinavel , Chief Design Officer, Design Intellect	1. Dr. Viraj Kumar, Professor, CSE, PES University	Dr. B.Amutha, Professor & Head, CSE, SRMIST	
		Dr.S.S.Sridhar, Professor, CSE, SRMIST	

ACADEMIC CURRICULA

Professional Core Courses

ELECTRICAL & ELECTRONICS ENGINEERING

Regulations - 2018



SRM INSTITUTE OF SCIENCE AND TECHNOLOGY

(Deemed to be University u/s 3 of UGC Act, 1956)

Kattankulathur, Kancheepuram, Tamil Nadu, India

Course Code	18EEEC301J	Course Name	CONTROL SYSTEMS	Course Category	C	Professional Core				L	T	P	C
										3	0	2	4

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Educate the students on mathematical model of a physical system.				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Provide knowledge on time domain response and stability of a system.				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Explain the concept of frequency domain using mathematical and graphical approach																					
CLR-4 :	Design various controller / compensator to meet system requirement.																					
CLR-5 :	Understand the concept of state space analysis.																					
CLR-6 :	Gain knowledge on the design, control and analysis of physical system.																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	Interpret a physical system in s domain representation.				3	75	75	H	H	M	M	-	-	-	-	M	M	-	-	M	H	-
CLO-2 :	Analyze the use of time domain specification and stability in real time application.				3	75	75	H	H	M	H	M	-	-	-	M	M	-	-	H	H	-
CLO-3 :	Apply various techniques to understand the frequency response of a system				3	75	75	H	H	H	H	M	-	-	-	M	M	-	-	H	H	-
CLO-4 :	Articulate the concept of tuning and design a controller for the given system.				3	75	75	H	H	H	H	M	-	-	L	M	M	-	-	H	H	L
CLO-5 :	Comprehend the state and test the controllability, observability of a system.				3	75	75	H	H	M	M	M	-	-	-	M	M	-	-	M	H	-
CLO-6 :	Analysis the system stability and performance of physical system.				3	75	75	H	H	H	H	M	-	-	L	M	M	-	-	H	H	L

Duration (hour)	15	15	15	15	15
S-1	SLO-1	Classification of control systems.	Introduction to time domain analysis.	Introduction to frequency domain analysis.	Need for controller design and in systems
	SLO-2	Terminology of automatic control systems.	Standard test signals ; Response of first order systems to standard test signals	Frequency response plots of dynamic systems.	Important for compensation in system.
S-2	SLO-1	Principles and effects of feed forward control systems.	Step response of second order systems in detail	Frequency response measurements, Performance specifications in the frequency domain.	Effects of P,PI Controller.
	SLO-2	Principles and effects of feedback control systems.	Different damping conditions.	Log magnitude and phase diagrams.	Effect of PID Controller.
S-3	SLO-1	Transfer functions SISO & MIMO	Transient response analysis.	Determination of Frequency domain specifications.	Classical PID controller
	SLO-2	Transfer functions for simple electrical, mechanical and electro mechanical systems	Time domain specification.	Phase margin and Gain margin	PID controller tuning using Zigler – Nichols tuning rules.
S-4	SLO-1	Lab 1: Determination of transfer function parameter of DC motor	Lab: 4Generating standard test signals.	Lab 7: Frequency response characteristics of second order system.	Lab 10: Design, determination of transfer function and frequency response for lag, lead network.
	SLO-2				Lab 13: State space model for classical transfer function and design and tuning a PID controller.
S-6	SLO-1	Tutorial: Formation of transfer functions of mechanical translational and rotational system.	Steady state response; Steady state error.	Stability Analysis using Bode Plots	Feedback compensation –Lead compensation
	SLO-2	Tutorial: Formation of electrical analogy of mechanical translational and rotational system.	Static & dynamic error coefficients	Procedure for plotting bode plot. .	Lag compensation
S-7	SLO-1	Block diagram algebra.	Effects of additional Pole on the Second-Order System Response	Tutorial – Bode plot problem	Compensator design in frequency domain using bode plot
					Solution of state equation;

	SLO-2	Representation by Signal flow graph	Effects of additional Zero on the Second-Order System Response	Stability margin on the bode plot.	Design procedure.	State Transition Matrix and it's Properties
S-8	SLO-1	Tutorial: Block diagram reduction direct method..	Routh Hurwitz criterion	Nyquist (Polar) Plot	Tutorial - Compensator design	Importance of controllability and observability.
	SLO-2	Tutorial: Block diagram reduction use by Mason's gain formula.	Stability condition and its limitation.	Gain phase plot.	Achieved desired system specification.	Tutorial: Formation of controllability and observability matrix
S-9-10	SLO-1	Lab 2: Determination of transfer function parameter of AC servo motor.	Lab 5: Step response characteristics of second order system.	Lab 8: Stability analysis of second order system using time and frequency domain approach.	Lab 11 Stability analysis of add a pole / zero and lag lead compensator.	Lab 14: Analysis of twin rotor multi input multi output system.
	SLO-2					
S-11	SLO-1	Linear Approximations of Physical Systems.	Properties of the Root Loci	Nyquist stability criterion	Pole zero cancellation design:	Pole zero cancellation for uncontrollability system.
	SLO-2	Linearization of nonlinear systems	Construction of root loci	Stability analysis using nyquist plot.	Notch filter	Design for controllable system.
S-12	SLO-1	Poles and zeros of a transfer function	Tutorial – Root locus	Relations between closed loop and open loop frequency response.	Minor loop feedback control.	Tutorial –Pole placement of state feedback system.
	SLO-2	Graphical evaluation	Gain limitation for stability condition.	M and N circle	Advantages and Applications	Design for pole placement approach.
S-13	SLO-1	BIBO Stability and its important	Effects of adding poles on the root loci.	Time response analysis use by Simulink/ program software.	Case Study: IEC61131 Standards	Case study: State space analysis of electric vehicle charging system.
	SLO-2	Location of poles and stability.	Effects of adding zeros on the root loci.	Frequency response analysis use by Simulink/ program software.	Programming language for industrial automation.	Analysis the system response.
S-14-15	SLO-1	Lab 3: Performance analysis of a motor driving a load through a gear train.	Lab 6. Plotting root locus of a transfer function using a simulator tank level estimation control.	Lab 9: Modeling and control analysis of simple electric network	Lab 12: Effect of feedback on disturbance and PID control design.	Lab 15: Design of speed control of DC motor drive.
	SLO-2					

Learning Resources	<ol style="list-style-type: none"> 1. I J Nagarath and M.Gopal, Control systems Engineering, New age international publication , 6th Edition, 2017. 2. FaridGolnaraghi, Benjamin C. Kuo, Automatic Control Systems, McGraw-Hill Professional, 10th Edition, 2017. 3. Katsuhiko Ogata, Modern control engineering, Pearson publication, 5th Edition, 2017. 4. Stefani, shahian, savant, Hostetter, Design of Feedback control systems, Oxford university press, 4th Edition, 2014, 	<ol style="list-style-type: none"> 5. K.P.Ramachandran, Control Engineering, Wilky India Private Limited, 1st Edition, 2011. 6. Graham C.Goodwin, Stefan F. Graebe, Mario E. Salgado, Control system design ,Pearson Education, 2nd Edition, 2001. 7. .B.S.Manke, Control System Design, Khanna publisher, 5th Edition, 2014. 8. Online course material: Plat form- NPTEL, Author – Prof. S.D Agashe, IIT Bombay, Web link: https://nptel.ac.in/syllabus/108101037/
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
Level 2	Apply Analyze	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
Level 3	Evaluate Create	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1.Ms.Vijayalakshmi Ramani, Head-Engineering at C2C Engineering, Chennai, vijayalakshmi@c2cengineering.co.in	1.Dr.S.K.Patnaik, CEG, Anna University, skpatnaik@annauniv.edu	1.Mr. A.Sureshkumar, SRM IST
2.Mr.Senthilkumar,ATI,rskrd1962@gmail.com,	2.Dr. S. Ramareddy, Jerusalem College of Engineering,srr.victory@gmail.com.	2.Dr.N.Chellammal, SRMIST

Course Code	18EEEC302J	Course Name	POWER ELECTRONICS	Course Category	C	Professional Core	L	T	P	C
							3	0	2	4

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:		Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Emphasize on basics of various power devices			Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Furnish adequate knowledge about the application of power devices in rectifier circuits						Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Educate the students on various DC-DC converters and their design						H	M	-	-	M	-	-	-	M	M	-	-	M	M	-
CLR-4 :	Illustrate the types and working of DC-AC converters						H	H	M	M	M	-	-	-	M	M	-	-	M	M	-
CLR-5 :	Describe the classification of AC-AC converters and their working						H	H	M	M	M	-	-	-	M	M	-	-	M	M	-
CLR-6 :	Providebasic knowledge on different industrial applications of power electronic converters						H	M	-	-	M	-	-	-	M	M	-	-	M	M	-
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:		2	75	75															
CLO-1 :	Understand and analyze the characteristics of different power devices			3	75	75															
CLO-2 :	Comprehend the operation of AC-DC converters and design a converter of specific range			3	75	75															
CLO-3 :	Apply the concept of chopper principle and design a DC-DC converter.			3	75	75															
CLO-4 :	Articulate the concept of DC-AC conversion and model an inverter			3	75	75															
CLO-5 :	Analyze the function of AC-AC converters			2	75	75															
CLO-6 :	Acquire and analyze various applications of power electronic circuits			3	75	75															

Duration (hour)	15	15	15	15	15
S-1	SLO-1 <i>Introduction to Power processing</i>	<i>Single phase full controlled rectifiers with R, RL load</i>	<i>Principles of chopper circuits</i>	<i>Principles of power VSI and CSI inverters</i>	<i>Step down Cycloconverter</i>
	SLO-2 <i>Construction - Principle of operation of Power diodes</i>	<i>Estimation of average & RMS load voltage, RMS load current and input power factor for full controlled rectifiers</i>	<i>Control Strategies in chopper circuits</i>	<i>Single phase voltage source inverter under various loading conditions</i>	<i>Step up Cycloconverter</i>
S-2	SLO-1 <i>Dynamic characteristics of Power diodes</i>	<i>Single phase full controlled rectifiers with RLE load</i>	<i>Multi- quadrant operation of chopper</i>	<i>Working of three phase inverter circuits in 180 degree mode of conduction</i>	<i>Three phase to single phase Cycloconverter</i>
	SLO-2 <i>Construction - Principle of operation of SCR- Dynamic characteristics of SCR</i>	<i>Estimation of average & RMS load voltage</i>	<i>Types of commutation</i>	<i>Determination of RMS ,average values of line and phase voltage</i>	<i>Three phase to three phase cyclo converter</i>
S-3	SLO-1 <i>Construction - Principle of operation of TRIAC,GTO</i>	<i>Estimation of RMS load current and input power factor</i>	<i>Forced commutated chopper :Voltage commutated choppers</i>	<i>Working of three phase inverter circuits in 120 degree mode of conduction</i>	<i>Introduction to matrix converter</i>
	SLO-2 <i>Dynamic characteristics of GTO</i>	<i>Problems in rectifier circuits</i>	<i>Forced commutated chopper : Current commutated choppers</i>	<i>Determination of RMS ,average values of line and phase voltage</i>	<i>Operation of matrix converter</i>
S 4-5	SLO-1 <i>Lab 1: R-RC Triggering Circuits ; UJT Triggering Circuits; HWR-FWR</i>	<i>Lab 4: Single phase half controlled bridge rectifier with resistive and inductive loads</i>	<i>Lab 7: Control of DC Voltage in chopper circuits using Time ratio & pulse width control</i>	<i>Lab 10: Three phase DC-AC converter for different types of loads</i>	<i>Lab 13: Single Phase cycloconverter</i>
	SLO-2 <i>HWR- FWR</i>				
S-6	SLO-1 <i>SCR: turn-on, methods</i>	<i>Three phase full controlled rectifiers with R load</i>	<i>Load commutated chopper</i>	<i>Introduction to Current source inverter</i>	<i>AC Voltage regulator</i>
	SLO-2 <i>SCR: turn-off methods</i>	<i>Working of three phase full controlled rectifiers with R load for various firing angle</i>	<i>Introduction to isolated and Non-isolated topologies</i>	<i>Auto sequential current source inverter</i>	<i>Active power line conditioner</i>
S-7	SLO-1 <i>Over voltage protection:</i>	<i>Three phase full controlled rectifiers with RL load</i>	<i>Basic non-isolated topologies: Characteristics of Buck converter</i>	<i>Single pulse width modulation technique</i>	<i>UPS</i>

	SLO-2	Over current protection	Working of three phase full controlled rectifiers with RL load for various firing angle	Derivation of voltage gain of Buck converter	Multiple pulse width modulation technique	SMPS
S-8	SLO-1	Gate Protection	Estimation of average & RMS load voltage,	Basic non-isolated topologies: Characteristics of Boost converter	Sinusoidal pulse width modulation technique (Unipolar , bipolar schemes)	HVDC systems
	SLO-2	Design of Snubber circuits	Estimation RMS load current and input power factor	Derivation of voltage gain of Boost converter	Introduction to space vector pulse width modulation	Types of HVDC systems
S 9-10	SLO-1	Lab 2: Characteristics of SCR, TRIAC	Lab 5: Three phase fully controlled rectifier with resistive load	Lab 8: Study of forced commutation techniques using chopper circuits	Lab 11: Generation of PWM signals using Sine PWM technique to trigger switches in a three phase inverter	Lab 14: A.C. voltage controllers with R and RL loads
	SLO-2					
S-11	SLO-1	Construction - Principle of operation of Power MOSFET	Single phase semi converter- Construction, working	Steady-State Equivalent Circuit Modeling of dc-dc converters- Losses and Efficiency	Voltage control of inverters	Tap changing of transformers
	SLO-2	Dynamic characteristics of Power MOSFET	Estimation of average & RMS load voltage of single phase semi converter	Resonant converters	Harmonics study and its reduction techniques	Electronic ballast
S-12	SLO-1	Construction - Principle of operation of Power IGBT	Three phase semi converter –Construction	Characteristics of CUK converter	Multilevel inverters: Introduction, Types	Induction heating
	SLO-2	Dynamic characteristics of Power IGBT	Working of three phase converter for different firing angles	Derivation of voltage gain of CUK converter	Working of cascaded seven level Inverter	Light dimmer
S-13	SLO-1	Loss calculation (Switching, conduction and leakage losses)	Estimation of average & RMS load voltage of three phase semi converter	Characteristics of SEPIC converter	Working of Diode clamped five level Inverter	Role of power converters in PV systems
	SLO-2	Problems in calculation of losses of various power devices	Effect of source inductance in full converter	Derivation of voltage gain of SEPIC converter	Working of flying capacitor five level Inverter	Role of power converters in Electric vehicles
S 14-15	SLO-1	Lab 3: Characteristics of MOSFET, IGBT	Lab 6: Three phase semi converter	Lab 9: : case study : Design and Model a Buck-Boost converter a) using real time software b) using discrete components for specific condition	Lab 12: Case study :Design a Single phase DC-AC converter to drive a 0.5 hp Single phase induction motor	Lab 15: Case study Design and analyze a fully controlled rectifier to feed a --- kW inverter using discrete components
	SLO-2					
Learning Resources	1. Mohan N, Undeland T M, and Robbins W P, Power Electronics - Converters, Applications and Design, Third Edition, John Wiley & Sons, Inc., New York, 2017. 2. Rashid M H, Power Electronics, Circuits, Devices and Applications, Prentice Hall Pearson Education, Inc., Fourth Edition 2014.			3. P.S.Bimbhra, Power Electronics, Khanna Publishers, New Delhi, Fifth edition 2012; Reprint 2014 4. M.D.Singh, K.B.Khanchandani, Power Electronics, Tata McGraw Hill, New Delhi, 2nd Edition,, 2006 5. https://nptel.ac.in/downloads/108105066/		

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Prakash G- Lead, CoreEL Technologies, Bangalore, prakash.g@coreel.com	1. Dr.S.Senthilkumar, NIT, Trichy; skumar@nitt.edu	1. Dr.N. Chellammal, SRMIST
2. Mr. Pramod Kumar N, CoreEL Technologies, Bangalore	2. Dr.G.Uma, CEG, Anna University, uma@annauniv.edu	2. Dr.R.Sridhar, SRMIST

Course Code	18EEEC303T	Course Name	POWER SYSTEM ANALYSIS	Course Category	C	Professional Core				L	T	P	C
										3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Understand the modeling of power system				Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Examine power flow analysis using numerical techniques																							
CLR-3 :	Evaluate the behavior of the power system under symmetrical fault conditions																							
CLR-4 :	Evaluate the behavior of the power system under unsymmetrical fault conditions																							
CLR-5 :	Discuss the stability issues of power system under transient condition																							
CLR-6 :	Understand the mathematical modeling and analysis of power system																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)																	
CLO-1 :	Summarize the basics of power system components, formation of network graphs and bus admittance matrix				2	80	75	H	H	L	-	-	-	-	-	-	-	-	-	-	M	M	-	-
CLO-2 :	Solve numerical methods in the application of power flow studies				3	80	75	H	H	L	-	M	-	-	-	-	-	-	-	-	M	M	-	-
CLO-3 :	Analyze the impact of symmetrical faults				3	80	75	H	H	L	-	-	-	-	-	-	-	-	-	-	M	M	-	-
CLO-4 :	Analyze different types of unsymmetrical faults				3	80	75	H	M	L	-	-	-	-	-	-	-	-	-	-	M	M	-	-
CLO-5 :	Examine transient stability analysis and solve numerical methods for transient stability				3	80	75	H	H	L	-	-	-	-	-	-	-	-	-	-	M	M	-	-
CLO-6 :	Analyze the power system under normal and fault conditions				3	80	75	H	H	L	-	M	-	-	-	-	-	-	-	-	M	M	-	-

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Power scenario in India	Necessity of power flow studies	Symmetrical short circuit on Synchronous Machine	Introduction to symmetrical components	Introduction to stability studies
	SLO-2	Power system components	Bus classification	Steady state, transient and sub transient reactances	Sequence voltages and currents	Illustration of steady state stability limit
S-2	SLO-1	Per unit representation	Formulation of Power Flow problems	Study of symmetrical faults in power system	Sequence impedances and networks	Synchronizing power co-efficient
	SLO-2	Single line diagram	Power flow solution using Gauss Seidel method (algorithmic steps)	Numericals in short circuit in synchronous generator	Zero sequence networks	Review of mechanics and swing equation
S-3	SLO-1	Per unit quantities	Handling of Voltage controlled buses	Bus Impedance matrix by building algorithm (without mutual coupling) (algorithmic steps)	Types of unsymmetrical faults	Representation of swing curves
	SLO-2	p.u impedance diagram	Power flow solution using Gauss Seidel method excluding PV buses (quantitative analysis)	Bus Impedance matrix by building algorithm (without mutual coupling) (quantitative analysis)	Fault conditions for single line to ground fault	Power-Angle equation
S-4	SLO-1	Network graph	Conditions for PV buses	Bus Impedance matrix by building algorithm (including mutual coupling) (algorithmic steps)	Fault conditions for line to line fault	Equal area criterion
	SLO-2	Bus incidence matrix	Power flow solution using Gauss Seidel method including PV buses (quantitative analysis)	Bus Impedance matrix by building algorithm (including mutual coupling) (quantitative analysis)	Fault conditions for double line to ground fault	Impact of sudden load increase in synchronous motor
S-5	SLO-1	Primitive parameters	Impact of acceleration factor in convergence	Symmetrical fault analysis using Thevenin's theorem	Single line to ground fault and line to line fault in generator terminals	Illustrations of equal area criterion under different system conditions
	SLO-2	Graph and oriented graph	Power flow solution including acceleration factor	Symmetrical fault analysis using Thevenin's theorem (numericals)	Double line to ground fault in generator terminals	Derivation of Critical clearing angle and time

S-6	SLO-1	Links and trees	Algorithmic steps of Power Flow Solution by Newton Raphson method	Derivation of Bus voltages due to current injection	Assumptions for system representation	Derivation of Critical clearing angle and time (quantitative analysis)
	SLO-2	Bus admittance matrix using singular transformation method without mutual coupling	Power Flow Solution by Newton Raphson method (quantitative analysis)	Calculation of bus voltages and line currents	Formation of positive, negative and zero sequence networks	Classical step-by-step solution of the swing curve (theoretical approach)
S-7	SLO-1	Bus admittance matrix using singular transformation method without mutual coupling (quantitative analysis)	Algorithmic steps of Power Flow Solution by Fast Decoupled method	Symmetrical fault analysis through bus impedance matrix (theoretical approach)	Bus impedance matrices of positive, negative and zero sequence networks	Classical step-by-step solution of the swing curve (numerical approach)
	SLO-2	Bus admittance matrix using singular transformation method including mutual coupling	Power Flow Solution by Fast Decoupled method (quantitative analysis)	Symmetrical fault analysis through bus impedance matrix (quantitative analysis)	Analyzing Single line to ground fault and line to line fault with fault impedance	Algorithmic steps of swing equation using Runge Kutta method
S-8	SLO-1	Representation of off nominal transformer	Derivation of Power flow in lines	Short circuit level /Fault level	Analyzing double line to ground fault with fault impedance	Numeric solution of swing equation using Runge Kutta method (quantitative analysis)
	SLO-2	Numerical problems in off nominal transformer	Numerical solution of Power flow in lines	Fault level and short circuit MVA (numericals)	Analyzing unsymmetrical fault occurring at any point in a power system	Algorithmic steps of swing equation using modified Eulers method
S-9	SLO-1	Formation of bus admittance matrix for large scale system (Theoretical approach)	Derivation of slack bus power and line losses	Current limiting reactors	Unsymmetrical fault analysis using bus impedance matrices (algorithmic)	Numeric solution of swing equation using modified Euler's method
	SLO-2	Formation of bus admittance matrix for large scale system (quantitative analysis)	Numerical solution of slack bus power and line losses	Design of circuit breakers based on fault analysis	Unsymmetrical fault analysis using bus impedance matrices (quantitative analysis)	Factors affecting transient stability

Learning Resources	<ol style="list-style-type: none"> 1. John.J.Grainger, William D. Stevenson, Jr, Power System Analysis, McGraw Hill Education (India) Private Limited, New Delhi, 2015. 2. William D. Stevenson, Jr, Elements of Power System Analysis, McGraw Hill Education (India) Private Limited, New Delhi, 4th Edition, 2014. 3. Nagarath I.J. and Kothari D.P., Modern Power System Analysis, 4th Edition, McGraw Hill Education (India) Private Limited, New Delhi, 2011 4. Hadi Sadat, Power System Analysis, McGraw Hill Education (India) Private Limited, New Delhi, 2nd Edition, 2002. 5. Pai M.A. and Dheeman Chatterjee, Computer Techniques in Power System Analysis, McGraw Hill Education (India) Private Limited, New Delhi, 3rd Edition, 2014. 6. https://nptel.ac.in/courses/108105067/1
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.Sudharsan, L&T, sudharsand@Intecc.com	1. Dr. D.Devaraj, Kalasalingam Academy of Research and Education, deva230@yahoo.com	1. Dr.J.Preetha Roselyn, SRMIST
2. Dr.K.Karthikeyan, ABB India Ltd., k.karthikeyan@in.abb.com	2. Dr. P. Somasundaram, CEG, Anna University, mpsomasundaram@annauniv.edu	2. Dr. D. Suchitra, SRMIST

Course Code	18EEEC304J	Course Name	MICROCONTROLLERS	Course Category	C	Professional Core				L	T	P	C
										3	0	2	4

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand the architecture and instruction set of 8051	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Familiarize with the programming modes of the SFRs in 8051	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Introduce 8051 programming in C																		
CLR-4 :	Outline the features of PIC microcontroller, its architecture and instruction set.																		
CLR-5 :	Explain the architecture of ARM Processor and its instruction set.																		
CLR-6 :	Acquire knowledge on microcontrollers and their applications.																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Summarize and program 8051 microcontrollers	1	75	75	H	M	M	M	M	-	-	-	M	M	-	-	M	M	-
CLO-2 :	Program the SFRs according to the given requirements	3	75	75	H	M	M	M	M	-	-	-	M	M	-	-	H	H	-
CLO-3 :	Interface the various peripherals with 8051 and program 8051 using C	3	75	75	H	M	M	M	M	-	-	-	M	M	-	-	H	H	-
CLO-4 :	Decipher the given problem and develop simple programs using PIC microcontrollers	3	75	75	H	M	M	M	-	-	-	-	M	M	-	-	H	H	-
CLO-5 :	Analyze and develop simple programs using ARM processor for simple applications.	3	75	75	H	M	M	M	M	-	-	-	M	M	-	-	H	H	-
CLO-6 :	Update their knowledge on microcontrollers and program them for real time applications	3	75	75	H	M	M	M	M	-	-	-	M	M	-	-	H	H	-

Duration (hour)		15	15	15	15	15
S-1	SLO-1	Evolution of Microprocessors, Microcontrollers and Computers	Counters & timers: modes of operation	Introduction to interfacing peripheral devices	Introduction to PIC 16F84A microcontroller	The ARM processor -features
	SLO-2	Comparison of Microprocessor and Microcontroller	TMOD register	8255 PPI – Pin diagram and architecture	Applications of PIC 16F84A	Applications of ARM processors
S-2	SLO-1	Overview of 8-bit / 16-bit / 32-bit microprocessors and microcontrollers	TCON register	8255 PPI – Modes of operation	Architecture overview of PIC 16F84A	Architecture overview of ARM processor
	SLO-2	CISC and RISC architectures	Serial data transmission/ reception: modes	8279 keyboard interface - Pin diagram and architecture	PIC 16F84A - Block diagram	ARM processor - Block diagram
S-3	SLO-1	8051 – pin diagram	SCON register	8279 keyboard interface - modes of operation	Working register	The ARM programmer's model
	SLO-2	8051 - Internal Block Diagram	PCON register	LCD interfacing	Status register	ARM Current Program Status Register
S 4-5	SLO-1	Lab 1: Introduction to 8051 microcontroller	Lab 4: Boolean and logical operations (bit & byte level logical operations) using 8051 microcontroller	Lab 7: 8 bit ADC using 8051 microcontroller	Lab 10:: Transfer data serially between two kits	Lab 13: DC motor speed measurement and control.
	SLO-2					
S-6	SLO-1	8051 - architecture	Internal Interrupts	Parallel and serial ADC interface	File selection register	ARM exceptions
	SLO-2	Internal memory organization	External Interrupts	DAC interface	Indirect data addressing register	Introduction to Thumb instructions
S-7	SLO-1	Register banks, PSW	IE register	Sensor interfacing	memory organization- Program memory	Pipeline ARM organization (3,5 stage)
	SLO-2	Ports	IP register	Stepper motor interfacing	Data memory	ARM instruction set: data processing instructions – arithmetic operations
S-8	SLO-1	Classification of instruction set	Clock circuit	DC motor interfacing and PWM	Watch dog timer	data processing instructions –bitwise logical, register movement & comparisons operations
	SLO-2	Addressing modes	RESET circuit	RTC interfacing	Power down/ sleep mode	Data transfer instructions – single load/store

S 9-10	SLO-1	Lab 2: Arithmetic operation using 8051 microcontrollers	Lab 5: Square root computation	Lab 8: 8 bit DAC using 8051 microcontroller	Lab 11: Internal interrupt generation	Lab 14: Basic ARM ALP (32-bit addition, subtraction, multiplication)
	SLO-2					
S-11	SLO-1	Instruction set - Data transfer,	Semiconductor memory -Types	Introduction to 8051 programming in C	PIC 16F84A parallel ports	Data transfer instructions – multiple load/store
	SLO-2	Instruction set - Logical operations, data exchange	Memory address decoding	Data types for 8051 C	Clock and oscillator circuits	Data transfer instructions –swap
S-12	SLO-1	Instruction set - arithmetic operations	8031/51 Interfacing with External ROM and RAM	I/O programming and logical operations in 8051 C	Instruction set – Arithmetic instructions	Control flow instructions – Branch, conditional branch
	SLO-2	Instruction set – Call, return	Pins PSEN, EA	Accessing code ROM space in C	logic instructions	Control flow instructions –jump
S-13	SLO-1	Instruction set – bit jump	Data memory space	Programming timers in 8051C	Instruction set – test and skip instructions	AMBA bus architecture
	SLO-2	Instruction set – byte jump	Problems on external memory interfacing	Calculation of time delays	jump instructions	ARM development tools – ARMulator
S 14-15	SLO-1	Lab 3: Sorting data, Code conversion using 8051 microcontroller	Lab 6: Delay generation using an on-chip timer using 8051 microcontrollers.	Lab 9: 8279 Keyboard & display using 8051 controllers. LCD Display using 8051	Lab 12: Stepper motor control using 8051	Lab 15: Basic ARM binary sorting
	SLO-2					

Learning Resources	1. Muhammad. Ali Mazidi, The 8051 Microcontroller and Embedded Systems: Second edition, Pearson Education Limited, 2013.	5. Steve Furber, ARM System-on-chip architecture, Pearson Education, India, 2000. 6. Tim Wilmshurst, Designing Embedded Systems with PIC Microcontrollers: Principles and applications, Published by Elsevier, 2010 7. https://nptel.ac.in/courses/117104072/
	2. K. J. Ayala, 8051 Microcontroller, Delmar Cengage Learning, 3 rd edition, 2007. 3. Subrata Ghoshal, 8051 Microcontroller Internals, Instructions, Programming and Interfacing, Second edition, Pearson Education Asia, 2014. 4. John Peatman, Design with PIC Microcontrollers, Pearson Education Asia, 8 th impression 2009	

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		100%	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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2. Mr. Muralikrishna, National Instruments, emkrishnan@gmail.com	2. Dr. A. Venkadesan, NIT, Puducherry, venkadesan@nitpy.ac.in	2. Ms. D. Anitha, SRMIST

Course Code	18EEEC305T	Course Name	POWER SYSTEM PROTECTION	Course Category	C	Professional Core				L	T	P	C
										3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)															
CLR-1 :	Understand the principles of modern power system protection				Level of Thinking (Bloom)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Enumerate the various protection schemes					Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3	
CLR-3 :	Acquire the knowledge of protection of Generator, Transformer and Busbar protection system																						
CLR-4 :	Understand the various types of digital protection and relay coordination																						
CLR-5 :	Describe the protection of switchgears in sub-station and its relay setting calculations																						
CLR-6 :	Gain an overall knowledge of power system protection concepts in various applications																						
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																					
CLO-1 :	Recognize the power system protection basics and standards				2	80	75	H	-	-	-	-	-	-	M	-	-	-	-	M	M	M	
CLO-2 :	Employ various protective schemes and needed instruments				3	80	75	H	H	-	-	-	-	-	-	-	-	-	-	M	M	-	
CLO-3 :	Explain the various equipment protection and its characteristics				3	80	75	H	H	-	-	M	-	-	-	-	-	-	-	M	M	-	
CLO-4 :	Familiarise various relay algorithms and applications of digital protection				3	80	75	H	H	-	-	M	-	-	-	-	-	-	-	H	H	-	
CLO-5 :	Analyse the use of protection and switchgears				3	80	75	H	H	-	-	-	-	-	-	-	-	-	-	M	M	-	
CLO-6 :	Apply power system protection concepts in real time environment				3	80	75	H	H	-	-	M	-	-	M	-	-	-	-	H	H	M	

Duration	9	9	9	9	9
S-1	SLO-1	Introduction to power system protection	Over current protection	Transformer protection	Introduction to Digital relays - Numerical relays
	SLO-2	Basic requirements	Characteristics of over current protection	Differential protection	Functional blocks of numerical relay
S-2	SLO-1	Main components of protections	Over current protection coordination	Percentage biased differential protection	Numerical over current relay algorithm
	SLO-2	Functions of protection	Relay setting calculation	Differential protection scheme for various types of three phase transformé	Numerical over current relay Flow chart
S-3	SLO-1	IEC – IEEE standards for protection	Numerical problems for over current setting	Numerical problems for differential protection	Numerical differential relay algorithm
	SLO-2	ANSI standards for protection	Numerical problems for over current setting	Numerical problems for differential protection	Numerical differential relay Flow chart
S-4	SLO-1	Zone of protection - overlapping	Directional over current relay	Magnetizing inrush current and harmonics restraint method	Numerical distance relay algorithm
	SLO-2	Primary – back up protection	Charcateristics of directional over current relay	Over fluxing protection, Incipient fault protection - Buchholz Relay	Numerical distance relay Flow chart
S-5	SLO-1	Unit, Non – Unit protection	Principle of distance protection	Alternator protection	Fibre Optic based relaying
	SLO-2	Applications of unit, non-unit protection	Charcateristics of distance relay	stator protection	Fibre optic relay Functions - application
S-6	SLO-1	Other types of protection schemes	Simple impedance, Reactance and Mho relay	Rotor protection	Wide Area Protection - functions
	SLO-2	Applications of protection schemes	Characteristics of impedance realy	Protection against abnormal condition - unbalanced loading, Over-speeding	Introduction to simulation of relay coordination
S-7	SLO-1	Current Transformer for protection	Three step distance protection	Loss of excitation	Applications of digital signal processing tool for protection
	SLO-2	Characteristics – numerical problems	Application of three step distance protection	Loss of prime mover	Functional blocks DSP

S-8	SLO-1	Voltage Transformer for protection	Carrier aided protection	Bus bar protection scheme	AI techniques to power system protection	Comparison of circuit breakers
	SLO-2	Characteristics of current transformer	Main components of carrier aided protection	Types of bus bar protection	Applications Of artificial intelligence in protection	Testing of circuit breaker
S-9	SLO-1	Electromechanical relays – construction	Bus bar protection scheme	Protection against over voltage - diverters,	Digital protection - Introduction to RTDS	Circuit breakers rating
	SLO-2	Relay operation - application	Types of bus bar	Lightning arrestor	Digital substation	Relay setting calculation and its operation
Learning Resources		1. Badrinar & Vishwakarma, Power System Protection, Tata McGraw-Hill Education, 10th reprint, 2015 2. Paithankar Y. G., S. R. Bhide., Fundamentals of power system protection', PHI Learning Pvt. Ltd., 10th reprint, 2010. 3. J. Lewis Blackburn & Thomas J. Domin, Protective Relaying - Principles and Applications, Fourth Edition, CRC Press. 4. Bhavesh R. Bhalja, R. P. Maheshwari, Niles Chothani, oxford university press, Second Edition, 2018 5. A. Kalam, D.P. Kothari, Power System Protection and Communication, New Age Science Ltd, 2009. 6. Paul M. Anderson, Power System Protection, IEEE press series on Power Engineering, 1999. 7. https://nptel.ac.in/courses/108101039/				

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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Dr. Swaroop Gajare, Lead Engineer, Power Systems Technologies, Eaton Research Labs, swaroopgajare@eaton.com	Dr. P. Raja, NIT Tiruchirappalli, praja@nitt.edu	Dr. M. Senthilkumar, SRMIST

Course Code	18EEEC401J	Course Name	POWER SYSTEM OPERATION AND CONTROL	Course Category	C	Professional Core	L	T	P	C
							3	0	2	4

Pre-requisite Courses	18EES101J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 : Understand the control methods of frequency in power system		1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 : Understand voltage control methods in power system			
CLR-3 : Formulate the economic operation of power system			
CLR-4 : Discuss the different methods to reduce losses and cost in power system			
CLR-5 : Develop knowledge on operation and control strategies of power system			
CLR-6 : Summarize the operation and control of power system			
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom) Expected Proficiency (%) Expected Attainment (%)	Engineering Knowledge Problem Analysis Design & Development Analysis, Design, Research Modern Tool Usage Society & Culture Environment & Sustainability Ethics Individual & Team Work Communication Project Mgt. & Finance Life Long Learning PSO - 1 PSO - 2 PSO - 3
CLO-1 : Analyze frequency control in single area and two area system		3 75 75	H H M L H - - M M - - - M M M
CLO-2 : Model excitation systems and develop methods of voltage control		3 75 75	H H M L H - - M M - - - M M M
CLO-3 : Examine numerical methods of economic dispatch		3 75 75	H H M L H - - M - - - M M -
CLO-4 : Solve unit commitment and optimal power flow problem		3 75 75	H H M H H - - M - - - M M -
CLO-5 : Analyze the functions of modern energy control centre on monitoring, data acquisition and control		3 75 75	H H - - H - - M - - - M M -
CLO-6 : Evaluate the strategies of operation and control		3 75 75	H H M L H - - M M - - - M M M

Duration (hour)	15	15	15	15	15
S-1	SLO-1 Basic concepts of operation and control of power system	Need for voltage control	Input-output characteristics of thermal units and Heat rate Curve	Statement of Unit Commitment problem	Operating strategies
	SLO-2 Plant and system level control	Requirement of reactive power	Input-output characteristics of Cost Curve.	Problem constraints	Control Strategies under abnormal state
S-2	SLO-1 Interaction of AVR and ALFC loops	DC Excitation system with amplitudyne voltage regulator	Optimum generation allocation neglecting network losses and inequality constraints	Priority List method	Concept of modern control centre: monitoring, data acquisition and control
	SLO-2 Speed load characteristics	Field controlled alternator rectifier excitation	Optimum generation allocation neglecting network losses and inequality constraints-numerical approach	Priority List method-numerical approach	Introduction to SCADA system
S-3	SLO-1 Modelling of speed governing mechanisms	Static Excitation systems	Optimum generation allocation neglecting network losses and including inequality constraints	Dynamic programming to unit commitment problem	Components of SCADA system
	SLO-2 Regulation of two alternators in parallel	Brushless AC Excitation systems	Optimum generation allocation neglecting network losses and including inequality constraints- numerical approach	Algorithmic steps of Dynamic programming	Applications of SCADA in power systems
S 4-5	SLO-1 Lab 1: Real time data acquisition of electrical parameters	Lab 4: Development of voltage controllers using simulation tool	Lab 7: Economic dispatch neglecting losses	Lab 10: Unit commitment using priority method	Lab 13: Study of SCADA systems
S-6	SLO-1 Concept of Control area	Schematic diagram of brushless excitation system	Loss Coefficients	Dynamic programming-numerical approach	PLC architecture and communication links
	SLO-2 Closing ALFC loop	Modelling of AVR and Exciter	Transmission line loss formula	Lagrange Relaxation method	State estimation by weighted least square method
S-7	SLO-1 Static response of single area system-uncontrolled case	Modelling of synchronous generator	Incremental cost of received power	OPF problem formulations	State estimation by weighted least square method-numerical approach
	SLO-2 Dynamic response of single area system-uncontrolled case	Static performance of AVR loop	Penalty factors	Constraints in OPF problem	Wide area monitoring systems

S-8	SLO-1	Proportional plus integral controller	Dynamic response of AVR loop	Base point and Participation factor method	Gradient method of OPF problem	Introduction to phasor measurement units
	SLO-2	Static response of single area system-controlled case	Stability compensation and stability analysis using Bode Plot	Base point and Participation factor method-numerical approach	Gradient method of OPF problem-numerical approach	Comparison of SCADA with PMU
S-9-10	SLO-1	Lab 2: Automatic Load frequency control in single area system using simulation tool	Lab 5: Stability analysis of AVR loop	Lab 8: Economic dispatch including losses	Lab 11: Gradient method of OPF problem	Lab 14: State estimation using weighted least square method
	SLO-2	Dynamic response of single area system-controlled case	IEEE Excitation models	Economic dispatch by gradient method	Linear programming OPF	PMU architecture
S-11	SLO-1	Modelling of tie line	Voltage drop/rise in transmission lines	Economic dispatch by gradient method-numerical approach	Newton method of OPF	Levels of PDC
	SLO-2	Modeling of Two area frequency control	Methods of voltage control- shunt capacitors, shunt reactors	Objectives and constraints in Security constrained economic dispatch	Security Constrained OPF-objectives	Mathematical formulation of optimal placement of PMUs
S-12	SLO-1	Block diagram representation of two area system	Methods of voltage control- FACTS devices	Security constrained economic dispatch using linear programming	Security Constrained OPF-constraints	Optimal placement of PMU using linear programming
	SLO-2	Static response of two area system	Methods of voltage control- tap changing transformer	Economic dispatch added to LFC control	Introduction to multi objective OPF	Need for Integration of Distributed generation
S-13	SLO-1	Dynamic response of two area system	Numerical approach in tap changing transformer	Hydrothermal scheduling neglecting network losses –long term	Formulation of combined active and reactive power dispatch	Control and operation of distributed generation
	SLO-2	Lab 3: Automatic Load frequency control in two area system using simulation tool	Lab 6: Study of voltage control techniques	Lab 9:Economic dispatch using gradient method	Lab 12: Study of numerical methods of OPF problem	Lab 15: Performance characteristics of Solar PV system and study of PV emulator

Learning Resources	<ol style="list-style-type: none"> 1. Olle.I.Elgerd, <i>Electric Energy systems theory- An Introduction</i>, Tata Mc Graw Hill publishing Ltd, New Delhi, 27th reprint, 2007. 2. I.J.Nagrath and D.P.Kothari, <i>Power system engineering</i>, Tata Mc Graw Hill publishing Ltd, 2nd edition, 2007. 3. Allen J.Wood and Bruce F. Woollenburg, Gerald B.Sheble, <i>Power generation, operation and control</i>, 3rd edition, John Wiley and sons, 2013. 4. Prabha Kundur, <i>Power system stability and control</i>, Tata Mc Graw Hill publishing Ltd, New Delhi, 1st edition, 2006 5. https://nptel.ac.in/courses/108101040/
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
Level 2	Understand	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
Level 3	Analyze	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.Sudharsan, L&T, sudharsand@Intecc.com	1.Dr.D.Devaraj,Kalasalingam Academy of Research and Education, deva230@yahoo.com	1.Dr.J.Preetha Roselyn, SRMIST
2. Dr.K.Karthikeyan, ABB India Ltd., k.karthikeyan@in.abb.com	2.Dr. P. Somasundaram, CEG, Anna University, mpsomasundaram@annauniv.edu	2.Dr.R.Jegatheesan, SRMIST

Course Code	18EEEC350T	Course Name	COMPREHENSION				Course Category	C	Professional Core					L	T	P	C													
													0	1	0	1														
Pre-requisite Courses		Nil			Co-requisite Courses		Nil		Progressive Courses		Nil																			
Course Offering Department		Electrical and Electronics Engineering				Data Book / Codes/Standards				Nil																				
Course Learning Rationale (CLR):		The purpose of learning this course is to:										Learning			Program Learning Outcomes (PLO)															
CLR-1 :	Acquire skills to solve real world problems in analyzing the electric circuits, analog and digital electronics										Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2 :	Acquire skills to solve real world problems in electromagnetic theory, power electronics and control system																													
CLR-3 :	Acquire skills to solve real world problems in electrical machines, measurements and Instrumentation																													
CLR-4 :	Acquire skills to solve real world problems in Generation, Transmission and Distribution networks and its analysis																													
CLR-5 :	Acquire skills to solve real world problems in microcontrollers and its applications																													
CLR-6 :	Acquire skills to solve real world problems for competitive examinations in Electrical and Electronics Engineering																													
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																												
CLO-1 :	Practice and gain confidence and competence to solve problems in analyzing the electric circuits, analog an ,digital electronics										3	85	80	H	H	H	H	-	L	L	L	L	L	-	L	H	H	M		
CLO-2 :	Practice and gain confidence and competence to solve problems in electromagnetic theory, power electronics and control system										3	85	80	H	H	M	M	-	L	L	L	L	L	-	L	H	H	M		
CLO-3 :	Practice and gain confidence and competence in electrical machines, measurements and Instrumentation										3	85	80	H	H	M	M	-	L	L	L	L	L	-	L	H	H	L		
CLO-4 :	Practice and gain confidence and competence in Generation, Transmission and Distribution networks and its analysis										3	85	80	H	H	M	M	-	L	L	L	L	L	-	L	H	H	M		
CLO-5 :	Practice and gain confidence and competence in microcontrollers and its applications										3	85	80	H	H	H	H	-	L	L	L	L	L	-	L	H	H	L		
CLO-6 :	Practice and gain confidence and competence to solve problems for competitive examinations in Electrical and Electronics Engineering										3	85	80	H	H	M	M	-	L	L	L	L	L	-	L	H	H	L		
Duration (hour)		3		3		3		3		3		3																		
S-1	SLO-1	Tutorial on AC and DC circuits		Tutorial on Electric Field, Dielectric concepts, Maxwell Equation		Tutorial on Transformers, generators and motors		Tutorial on ac and dc transmission concepts and distribution systems		Tutorial on 8085 microcontroller basic design																				
	SLO-2	Problem Solving		Problem Solving		Problem Solving		Problem Solving		Problem Solving																				
S-2	SLO-1	Tutorial on characteristics of diode, amplifiers and OPAMP		Tutorial on semiconductor power devices , rectifier and inverter operation		Tutorial on bridges and potentiometer		Tutorial on per unit quantities and load flow methods		Tutorial on microcontroller programming																				
	SLO-2	Problem Solving		Problem Solving		Problem Solving		Problem Solving		Problem Solving																				
S-3	SLO-1	Tutorial on combinational and sequential logic circuit		Tutorial on Controllers, transient and steady state analysis of LTI systems		Tutorial on phase, time and frequency measurement		Tutorial on protection methods and circuit breakers		Tutorial on interface																				
	SLO-2	Problem Solving		Problem Solving		Problem Solving		Problem Solving		Problem Solving																				
Learning Resources	1. Jegatheesan R, Analysis of Electric Circuits, McGraw Hill, 2014										9. R.S.Goankar, Microprocessor Architecture Programming and Applications with the 8085,6 th edition, Penram International Publishing (India) Pvt.Ltd,2013.																			
	2. Jacob Millman, Christos C.Halkias, SatyabrataJit, Millman's Electronic Devices and Circuits, 4th ed., Tata McGraw Hill, 2015										10. C. L. Wadwa, Electric Power Systems, 7 th ed., New Age International Publishers,2016																			
	3. M. Morris Mano, Michael D. Ciletti, Digital Design: With an Introduction to Verilog HDL, VHDL and System Verilog, 6 th ed., Pearson, 2018										11. https://ocw.mit.edu/courses/electrical-engineering-and-computer-science/6-071j-introduction-to-electronics-signals-and-measurement-spring-2006/lecture-notes/																			
	4. William Hayt, Engineering Electromagnetics, 7 th ed., McGraw Hill, 2014										12. https://ocw.mit.edu/courses/electrical-engineering-and-computer-science/6-632-electromagnetic-wave-theory-spring-2003/index.htm																			
	5. Mohan N, Undeland T M, and Robbins W P, Power Electronics - Converters, Applications andDesign, Third Edition, John Wiley & Sons, Inc., New York, 2017										13. https://nptel.ac.in/downloads/108105066/																			
	6. I J Nagarath and M.Gopal, Control systems Engineering, New age international publication , 6th Edition, 2017.										14. Online course material: Plat form- NPTEL, Author – Prof . S.D Agashe, IIT Bombay, Web link: https://nptel.ac.in/syllabus/108101037/																			
	7. J. B. Gupta, Theory & Performance of Electrical Machines, 15th ed., S.K.Kataria & Sons, 2015																													
	8. A.K.Sawhney, A Course in Electrical and Electronic Measurements and Instrumentation, Dhanpat Rai & Co, 2012.																													

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (100% weightage)								Final Examination	
		CLA – 1 (20%)		CLA – 2 (30%)		CLA – 3 (30%)		CLA – 4 (20%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	-	40%	-	30%	-	30%	-	30%	-	-
	Understand	-	40%	-	30%	-	30%	-	30%	-	-
Level 2	Apply	-	40%	-	40%	-	40%	-	40%	-	-
	Analyze	-	40%	-	40%	-	40%	-	40%	-	-
Level 3	Evaluate	-	20%	-	30%	-	30%	-	30%	-	-
	Create	-	20%	-	30%	-	30%	-	30%	-	-
	Total	100 %		100 %		100 %		100 %		-	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Ms. Vijayalakshmi Ramani, Head-Engineering at C2C Engineering, Chennai, vijayalakshmi@c2cengineering.co.in	1. Dr. S.K.Patnaik, CEG, Anna University, skpatnaik@annauniv.edu	1. Dr. D. Karthikeyan, SRMIST
2. Mr. Senthilkumar, ATl, rskrd1962@gmail.com,	2. Dr. S. Ramareddy, Jerusalem College of Engineering, srr.victory@gmail.com.	2. Mr. V. Pradeep, SRMIST

ACADEMIC CURRICULA

Professional Core Courses

ELECTRONICS AND COMMUNICATION ENGINEERING

Regulations - 2018



SRM INSTITUTE OF SCIENCE AND TECHNOLOGY

(Deemed to be University u/s 3 of UGC Act, 1956)

Kattankulathur, Kancheepuram, Tamil Nadu, India

Course Code	18ECC203J	Course Name	MICROPROCESSOR, MICROCONTROLLER AND INTERFACING TECHNIQUES	Course Category	C	Professional Core	L	T	P	C
							3	0	2	4

[illegible]

S-8	SLO-1	Minimum mode signals	Branch Instructions	Programmable Interrupt Controller 8259	Addressing modes of 8051	Interfacing input devices: push-button / matrix keypad
	SLO-2	Maximum mode signals	Example programs	Interfacing 8259 with 8086 and programming		Example programs
S-9,10	SLO-1	Lab-2: General Purpose Programming in 8086	Lab-5: Simulation of 8086 using MASM Software / 8086 Emulator	Lab-8: Interfacing DC motor / stepper motor / servo motor with 8086 / 8051	Lab-11: Programming interrupts in 8086 / 8051	Lab-14: Model Practical Exam
S-11	SLO-1	Minimum mode 8086 system, and	Assembly Language Programming of 8086	Programmable Keyboard / Display Controller 8279	8051 Instruction Set: Arithmetic and Logical Instructions	Interfacing display devices: LED / 7-segment / LCD displays
	SLO-2	Timings	Assembly Language Programming of 8086	Interfacing 8279 with 8086 and programming	Example Programs	Example programs
S-12	SLO-1	Maximum mode 8086 system, and	Stack structure, and	Programmable Communication Interface 8251 USART	Data Transfer Instructions	Interfacing DAC
	SLO-2	Timings	related programming	Interfacing 8251 with 8086 and programming	Example Programs	Interfacing ADC
S-13	SLO-1	Intel 8088 Microprocessor: Pins signals and Architecture	Interrupt structure, and	DMA Controller 8257	Boolean Variable Instructions and Branch Instructions	Interfacing DC motor / stepper motor / servo motor
	SLO-2	Differences between 8086 & 8088 microprocessors	related programming	Interfacing 8257 with 8086 and programming	Example Programs	Example programs
S-14,15	SLO-1	Lab-3: General Purpose Programming in 8086	Lab-6: Interfacing 8255 with 8086 / 8051	Lab-9: General Purpose Programming in 8051	Lab-10: Programming serial communication in 8086 / 8051	Lab-15: End-Semester Exam

Learning Resources	1. K. M. Bhurchandi and A. K. Ray, "Advanced Microprocessors and Peripherals-with ARM and an Introduction to Microcontrollers and Interfacing ", Tata McGraw Hill, 3rd edition 2015 2. Muhammad Ali Mazidi and Janice GillispieMazidi, "The 8051 - Microcontroller and Embedded systems", 7th Edition, Pearson Education, 2011. 3. Douglas. V. Hall, "Microprocessor and Interfacing : Programming and Hardware", 3rd edition, McGraw Hill, 2015	4. Kenneth. J. Ayala, "8051 Microcontroller Architecture, Programming and Applications", 3rd edition, Thomson, 2007 5. Subrataghoshal " 8051 Microcontroller Internals Instructions ,Programming And Interfacing", 2nd edition Pearson 2010 6. Yu-cheng Liu, Glenn A. Gibson, "Microcomputer systems: The 8086/8088 family-Architecture, programming and design", 2nd edition, Prentice Hall of India, 2007
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Anuj Kumar, Bombardier Transportation, Ahmedabad, kumaranuj.anii@gmail.com	1. Dr. Meenakshi, Professor of ECE, CEG, Anna University, meena68@annauniv.edu	1. Mr. Manikandan AVM, SRMIST
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	

Course Code	18ECC204J	Course Name	DIGITAL SIGNAL PROCESSING	Course Category	C	Professional Core	L	T	P	C
							3	0	2	4

Pre-requisite Courses	18ECC104T	Co-requisite Courses	Nil	Progressive Courses	18ECE243J, 18ECE244J, 18ECE245T
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Understand the operations involved in digital conversion of analog signals.	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Realize a digital filter in direct, cascade and parallel forms. Perform efficient computation of DFT using radix 2 FFT	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Design digital FIR filter using windowing technique and frequency sampling methods.	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Design IIR filters using both direct method and method involving conversion of analog filter to digital filter	Expected Attainment (%)	Design & Development
CLR-5 :	Understand sampling rate conversion and apply it for applications like QMF, sub band coding.		Analysis, Design, Research
CLR-6 :	Utilize the techniques for digital conversions, filter designs and multi rate signal processing to solve real time problems		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Acquire knowledge of sampling and quantization and understand the errors that arise due to quantization.	2 90 70	H M - L - - - - -
CLO-2 :	Understand the concept of DFT and its efficient computation by using FFT algorithm.	2 95 75	H M - L - - - - -
CLO-3 :	Design FIR filters using several methods	2 85 70	- M H H - - - - -
CLO-4 :	Design IIR filters using several methods	2 85 80	- M H H - - - - -
CLO-5 :	Understand the basics of multirate DSP and its applications.	2 90 75	H M - M - - - - -
CLO-6 :	Apply the concepts of digital filter designs and multi rate signal processing for real time signals	2 80 70	H M - H - - - - -

Duration (hour)	Signals and Waveforms	Frequency Transformations	FIR Filters	IIR Filters	Multirate signal Processing
	15	15	15	15	15
S-1	SLO-1 Basic Elements of DSP	Realization of digital filters Direct form of realization	Design of Linear Phase FIR filters General consideration	Design of digital IIR filters Comparison of FIR and IIR filters	Introduction to Multirate signal processing
	SLO-2 Advantages and applications of DSP	Cascade form of realization	Causality, its implication Characteristics of practical frequency selective filters	Analog IIR filter design	Decimation
S-2	SLO-1 Continuous Time vs Discrete time signals	Parallel form of realization	Frequency response of symmetric FIR filter	Properties of Butterworth filters	Interpolation
	SLO-2 Continuous valued vs discrete valued signals	Introduction to DFT	N is odd	Properties of chebyshev filters Comparison of Butterworth and chebyshev filters	Spectrum of interpolated signal
S-3	SLO-1 Concepts of frequency in analog signals	Computation of DFT	Frequency response of symmetric FIR filter	Analog IIR filter design	Sampling rate conversion by a rational factor I/D
	SLO-2 Continuous and discrete time sinusoidal signals	Properties of DFT Periodicity, linearity and symmetry properties	N is even	Design of low pass Butterworth filter	Anti-aliasing and anti-imaging filters
S-4	SLO-1 Lab 1 :Generation of basic signals	Lab 7: Linear convolution	Lab 13: Design of digital FIR Low Pass, High Pass filter using rectangular window	Lab 19: Design of analog Butterworth filter	Lab 25: Interpolation
S-5	SLO-1 Lab 2: Unit step, ramp and impulse	Lab 8: Circular convolution	Lab14: Design of digital FIR Band Pass, Band Stop filter using rectangular window	Lab 20: Design of analog Chebyshev filter	Lab 26: Effect of interpolation in frequency domain
S-6	SLO-1 Sampling of analog signals Sampling theorem	Circular convolution	Frequency response of anti-symmetric FIR filter	Analog IIR filter design	Polyphase structure of decimator Polyphase decimation using z transform
	SLO-2 Aliasing Quantization of continuous amplitude signals	Matrix method and concentric circle method	N is odd and N is even	Design of low pass Chebyshev filter	Polyphase structure of interpolator Polyphase interpolation using z transform
S-7	SLO-1 Analog to digital conversion Sample and hold,	Efficient Computation of the DFT	Design of FIR filters Fourier series method	Design of digital filters Impulse invariance method	Advantages of multirate DSP

	SLO-2	Quantization and coding	Divide and Conquer Approach to Computation of the DFT Using FFT	Need for filter design using window Comparison of various windowing techniques	Design of digital filters Bilinear transformation	Applications of multirate DSP
S-8	SLO-1	Oversampling A/D converters	N Point DFT Decimation-in-Time FFT Radix-2 FFT Algorithm	Filter Design using windowing technique	Design of digital filters Impulse invariance method	Practical Applications of multirate DSP
	SLO-2	Digital to analog conversion Sample and hold	N Point DFT Decimation-in-Frequency FFT	Rectangular window	Design of digital filters Bilinear transformation	interfacing of digital systems with different sampling rates
S-9	SLO-1	Lab 3: Generation of waveforms	Lab9: Autocorrelation and cross correlation	Lab 15: Design of digital FIR Low Pass and High Pass filter using Hanning and Hamming window	Lab 21: Design of digital Butterworth filter using impulse invariance method	Lab 27: Decimation
	SLO-2					
S-10	SLO-1	Lab 4: Continuous and discrete time	Lab10: Spectrum analysis using DFT	Lab 16: Design of digital FIR Band Pass and Band Stop filter using Hanning and Hamming window	Lab 22: Design of digital Butterworth filter using bilinear transformation	Lab 28: Effect of decimation in frequency domain
	SLO-2					
S-11	SLO-1	Oversampling D/A converters	Radix-2 FFT Algorithm Implementation of FFT Using DIT	Filter Design using windowing technique Hanning window	Design of digital Chebyshev filters	Practical Applications of multirate DSP Sub band coding of speech signals
	SLO-2	Quantization noise	Implementation of FFT Using DIF	Filter Design using windowing technique Hamming window	Impulse invariance method	Filter banks Analysis filter bank
S-12	SLO-1	Errors due to truncation	IDFT	Filter Design using windowing technique	Design of digital Chebyshev filters	Synthesis filter bank
	SLO-2	Probability of error	Using DIT FFT	Black mann window	Bilinear transformation	Subband coding filterbank
S-13	SLO-1	Errors due to rounding	IDFT	Design of FIR filters	Frequency transformation in analog domain	Quadrature Mirror Filter
	SLO-2	Probability of error	Using DIF FFT	Frequency sampling method	Frequency transformation in digital domain	Alias free filter bank
S-14	SLO-1	Lab 5: Study of sampling theorem	Lab 11: Efficient computation of DFT using FFT	Lab 17: Design of digital FIR Low Pass, High Pass, Band pass and band stop filter using Black mann window	Lab 23: Design of digital Cheby shev filter using impulse invariance method	Lab 29: Design of anti-aliasing filter
	SLO-2					
S-15	SLO-1	Lab 6: Aliasing effects	Lab12: Computation of IDFT	Lab 18: Design of digital FIR filter using frequency sampling method	Lab 24: Design of digital Cheby shev filter using bilinear transformation	Lab 30: Design of anti-imaging filter
	SLO-2					

Learning Resources	<ol style="list-style-type: none"> John G. Proakis, Dimitris G. Manolakis, "Digital Signal Processing, Principles, Algorithms and Applications", Pearson Education, 4th edition, 2014 Alan V. Oppenheim, Ronald W. Schaffer, "Discrete-Time Signal Processing", Pearson Education, 1st edition, 2015 	<ol style="list-style-type: none"> Sanjit Mitra, "Digital Signal Processing –A Computer Based Approach", McGraw Hill, India, 4th Edition, 2013. Fredric J. Harris, "Multirate Signal Processing for Communication Systems", 1st edition, Pearson Education, 2007
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Anuj Kumar, Bombardier Transportation, Ahmedabad, kumaranuj.anii@gmail.com	1. Dr. Meenakshi, Professor of ECE, CEG, Anna University, meena68@annauniv.edu	Dr. M.S. Vasanthi, SRMIST
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	

Course Code	18ECC205J	Course Name	ANALOG AND DIGITAL COMMUNICATION	Course Category	C	Professional Core	L	T	P	C
							3	0	2	4

Pre-requisite Courses	18MAB203T	Co-requisite Courses	Nil	Progressive Courses	18ECC301T, 18ECC302J, 18ECE221T & 18ECE223T
Course Offering Department	ECE	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Understand the need for modulation, various Amplitude modulators/demodulators, frequency modulators, demodulators	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Comprehend the radio transmitters, receivers using modulators and demodulators and to analyze the noise performance	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	To introduce basics of Digital modulation and detection techniques	Expected Proficiency (%)	Problem Analysis
CLR-4 :	To analyze the pass band data transmission techniques in terms of probability of error	Expected Attainment (%)	Design & Development
CLR-5 :	To introduce basics of spread spectrum techniques and information theory concepts		Analysis, Design, Research
CLR-6 :	Gain hands-on experience to put theoretical concepts learned in the course to practice.		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Understand the concepts of analog modulation and demodulation techniques	2 80 70	M - - - - - H - - -
CLO-2 :	Learn the function of radio transmitters and receivers and familiarize with noise performance of various receivers	2 85 75	- M H - - - - - H - -
CLO-3 :	Understand various digital modulation schemes and matched filter receiver	2 75 70	M - - - - - - - - M H
CLO-4 :	Understand and analyze various digital pass band data transmission schemes	2 85 80	- - - M - - - - - M -
CLO-5 :	Understanding data transmission using spread spectrum and error coding techniques	2 85 75	- H - - - - - - - M H
CLO-6 :	Analyze the operation of analog and digital communication systems and take measurement of various communication systems to compare experimental results in the laboratory with theoretical analysis	2 85 75	- - H - H - - - H - M M H

	Analog Modulation	Radio Transmitters and Receivers	Digital Modulation System and Baseband Detection	Passband Data Transmission	Spread Spectrum Techniques and Information theory Concepts
Duration (hour)	15	15	15	15	15
S-1	SLO-1 Modulation, Need for Modulation,	AM transmitter : Low Level,	Pulse modulation systems, Overview of PAM,PWM,PPM	Overview of ASK, FSK, PSK	Spread spectrum Communications, Frequency Hopping Spread Spectrum (FHSS)
	SLO-2 Amplitude Modulation, Types of Amplitude Modulation	AM transmitter : High Level Transmitter	Pulse modulation systems, Overview of PAM,PWM,PPM	Overview of ASK, FSK, PSK	Spread spectrum Communications, Frequency Hopping Spread Spectrum (FHSS)
S-2	SLO-1 Double sideband Full carrier	FM transmitter: Direct Method	Pulse modulation systems, Sampling and quantization	Generation, Signal Space Diagram and detection of FSK	Direct Sequence Spread Spectrum (DSSS)
	SLO-2 Double sideband Full carrier	FM transmitter: Direct Method	Pulse modulation systems, Sampling and quantization	Generation, Signal Space Diagram and detection of FSK	Direct Sequence Spread Spectrum (DSSS)
S-3	SLO-1 Double sideband Suppressed carrier	FM transmitter: Indirect Method	PCM systems	Probability of Error for FSK	Direct Sequence Spread Spectrum (DSSS)
	SLO-2 Single sideband Suppressed carrier, VSB	FM transmitter: Indirect Method	Bandwidth of PCM, PCM TDM signal multiplexing, Limitations of PCM system	Probability of Error for FSK	Code Division Multiple Access of DSSS
S 4-5	SLO-1 Lab-1: AM modulator and Demodulator	Lab-4: Pre emphasis and De-emphasis	Lab-7: DPCM and its Demodulation	Lab-10: QPSK Modulation and Demodulation	Lab-13: Mini Project
	SLO-2				
S-6	SLO-1 Generation of AM waves: Linear method-Collector modulator	Classification of radio receiver, Functions and Characteristics of radio receiver	Data formatting	Generation, Detection, Signal Space Diagram of PSK	Code Division Multiple Access of DSSS
	SLO-2 Generation of AM waves: Linear method- Collector modulator	Tuned Radio Frequency receiver	Data formatting	Generation, Detection, Signal Space Diagram of PSK	OFDM Communication
S-7	SLO-1 Non-linear Modulation-Balanced Modulator	Super-heterodyne receiver- AM	Differential PCM (DPCM)	Probability of Error for PSK	OFDM Communication
	SLO-2 Non-linear Modulation-Balanced Modulator	Super-heterodyne receiver- AM	Differential PCM (DPCM)	Probability of Error for PSK	OFDM Communication

S-8	SLO-1	Demodulation of AM waves : Linear diode detector	Super-heterodyne receiver- FM	Delta modulation (DM)	Generation, signal space diagram and detection of QPSK	Measures of Information
	SLO-2	Demodulation of AM waves : Linear diode detector	Super-heterodyne receiver- FM	Delta modulation (DM), Noise in DM	Generation, signal space diagram and detection of QPSK	Measures of Information
S 9-10	SLO-1	Lab-2: DSB-SC modulator and demodulator	Lab-5: PAM,PPM,PWM modulation and demodulation	Lab-8: DM and its Demodulation	Lab-11: DPSK Modulation and Demodulation	Lab-14: Model Practical Exam
S-11	SLO-1	Frequency modulation, Types of FM	Sources of Noise	Demodulation and detection process	Probability of Error for QPSK	Source encoding, Shannon's Channel capacity theorem
	SLO-2	Narrow Band FM, Wide Band FM, Phase modulation	Sources of Noise	Demodulation and detection process	Probability of Error for QPSK	Shannon's Channel capacity theorem
S-12	SLO-1	Generation of Narrowband FM	Noise in AM (Envelope Detection),	Maximum likelihood receiver structure, Matched filter receiver	Generation, signal space diagram and detection of $\pi/4$ QPSK	Linear block codes
	SLO-2	Generation of Narrowband FM	Noise in AM (Envelope Detection),	Maximum likelihood receiver structure, Matched filter receiver	Generation, signal space diagram and detection of $\pi/4$ QPSK	Linear block codes
S-13	SLO-1	Demodulation of FM : Foster seely discriminator	Noise in FM	Probability error of the Matched filter, Inter symbol interference, Eye pattern	Generation, signal space diagram and detection of QAM	Cyclic codes
	SLO-2	Demodulation of FM : Foster seely discriminator	Threshold effect, Pre-emphasis and De-emphasis	Probability error of the Matched filter, Inter symbol interference, Eye pattern	Generation, signal space diagram and detection of QAM	Cyclic codes
S 14-15	SLO-1	Lab-3: FM Modulator and Demodulator	Lab-6: Pulse Code Modulation and Demodulation	Lab-9: PSK Modulation and Demodulation	Lab-12: BER performance analysis of various Modulation Schemes	Lab-15: University Practical Exam

Learning Resources	1. Simon Haykin and Michael Moher, "Communication Systems," 5th edition, John Wiley & Sons, 2013 2. Singh. R. P & Sapre. S. D, "Communication Systems: Analog & Digital," 3rd edition, McGrawHill Education, Seventh Reprint, 2016. 3. Simon Haykin, "Communication Systems", John Wiley & Sons, 4th Edition, 20008. 4. Bernard Sklar, "Digital Communication, Fundamentals and Application", Pearson Education Asia, 2nd Edition, 2001	5. Taub & Schilling, "Principle of Communication Systems", McGraw Hill Inc, 2nd Edition, 2003. 6. John G. Proakis, "Digital Communication", McGraw Hill Inc, 5th Edition, 2008. 7. B. P. Lathi, "Modern Digital and Analog Communication System", Oxford University Press, 3rd Edition, 2005. 8. Shu Lin, Daniel Costello, "Error control coding – Fundamentals and Applications", Prentice Hall, Upper Saddle River, NJ, 2nd Edition, 2004. 9. Lab Manual
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		-	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Anuj Kumar, Bombardier Transportation, Ahmedabad, kumaranuj.anii@gmail.com	1. Dr. Meenakshi, Professor of ECE, CEG, Anna University, meena68@annauniv.edu	Mrs. S. Vasanthadev Suryakala, SRMIST
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	

Course Code	18ECC206J	Course Name	VLSI DESIGN			Course Category	C	Professional Core					L	T	P	C										
												3	0	2	4											
Pre-requisite Courses		18ECC103J		Co-requisite Courses		Nil		Progressive Courses		18ECE301J																
Course Offering Department		Electronics and Communication Engineering			Data Book / Codes/Standards			Nil																		
Course Learning Rationale (CLR):		The purpose of learning this course is to:						Learning			Program Learning Outcomes (PLO)															
CLR-1 :	Use Verilog HDL as a design-entry language for FPGA in electronic design automation of digital circuits						Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Design, construct and simulate VLSI adders and multipliers.																									
CLR-3 :	Understand MOSFET operation																									
CLR-4 :	Implement a given logic function using appropriate logic styles for improved performance																									
CLR-5 :	Understand basic processes in IC fabrication, steps in the fabrication of MOS ICs, and as well the layout design rules.																									
CLR-6 :	Use engineering tools such as HSPICE / Modelsim / Xilinx to design experiments, gain experience with the design and analysis of MOS circuits and systems.																									
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																								
CLO-1 :	Design and implement digital circuits using Verilog HDL to simulate and verify the designs.						3	85	75	-	H	H	-	H	-	-	-	-	-	-	-	-	-	-	-	
CLO-2 :	Design general VLSI system components, adder cells and multipliers to address the design of datapath subsystem.						3	85	75	-	H	H	-	H	-	-	-	-	-	-	-	-	-	-	-	
CLO-3 :	Examine the characteristics of MOS transistors						2	80	70	H	M	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
CLO-4 :	Examine CMOS inverter and other complex logic gates designed using different logic styles						2	80	70	-	L	L	-	-	-	-	-	-	-	-	-	-	-	-	-	
CLO-5 :	Explain how the transistors are built, and understand the physical implementation of circuits.						2	80	70	-	L	L	-	-	-	-	-	-	-	-	-	-	-	-	-	
CLO-6 :	Use HSPICE computer analysis program and Verilog HDL for simulation and analysis of MOS circuits and building blocks						3	85	75	-	-	-	-	-	-	-	-	H	M	L	M	-	L	M		
Duration (hour)		Introduction to Verilog HDL & Coding		Subsystem Design		MOS Transistor		CMOS Inverter and Circuit Design Styles			Microelectronic Materials															
		15		15		15		15			15															
S-1	SLO-1	Introduction to HDL & Verilog HDL		General VLSI System Components: Multiplexers		Generic overview of the MOS device: MOS transistor symbols		CMOS Inverter Characteristics: Operation and properties of static CMOS inverter			Properties of basic materials used in microelectronics: Silicon, Silicon dioxide															
	SLO-2	Introduction to Verilog HDL, modules and ports		Decoders		MOS structure: accumulation, depletion, inversion; nMOS transistor: cutoff, linear, saturation regions of operation		VTC of static CMOS inverter			Polysilicon and Silicon Nitride															
S-2	SLO-1	Lexical Conventions: White Space and Comments, Operators		Comparators		MOS Transistor under Static Conditions: The threshold voltage		DC Inverter Calculations			IC Fabrication: Wafer Formation, Photolithography,Well,Channel Formation															
	SLO-2	Numbers, Strings, Identifiers, System Names, and Keywords		priority encoder		Resistive operation		Symmetrical Inverter			Silicon Dioxide (SiO2), Isolation, Gate Oxide															
S-3	SLO-1	Verilog Data Types: Nets, Register Variables, Constants		shift and rotate operations		Saturation region		Inverter switching characteristics			Gate, Source/Drain Formations, Contacts and Metallization, Passivation, Metrology															
	SLO-2	Referencing Arrays of Nets or Regs		Adders: Standard adder cells		Current-voltage characteristics		Output capacitance			Recurring Process: Diffusion, Ion Implantation, Deposition, Etching, Planarization															
S-4, 5	SLO-1	Lab-0: Verilog Operators: Arithmetic, Bitwise, Reduction, Logical, Relational, Shift, Conditional, Concatenation, Expressions and Operands, Operator Precedence		Lab-3: Design using FSM and ASM charts		Lab-6: Realization of VLSI multipliers - I		Lab-9: Design and Analysis of CMOS Inverter using HSPICE			Lab-12: Design and Analysis of 4-input Dynamic NAND gate using HSPICE															
	SLO-2																									
S-6	SLO-1	Verilog modelling: Gate-level modelling		Ripple Carry Adder (RCA)		Dynamic behavior: MOSFET Capacitances, MOS structure capacitances		Secondary Parasitic Effects: Leakage Currents, Parasitic Resistances			Simplified CMOS Process flow															
	SLO-2	Realization of Combinational and sequential circuits		Carry Look-Ahead Adder (CLA)		Channel capacitance and Junction (or, depletion) capacitances		Inverter layout																		
S-7	SLO-1	Compilation and simulation of Verilog code		Carry Select Adder (CSL)		Parasitic Resistances, viz., Drain and Source Resistance, Contact Resistance		Power-Delay Product: Static Power Consumption			Layout design rules: Well rules, transistor rules															

	SLO-2	Test bench	Carry Save Adder (CSA)	Non-ideal I-V effects: Mobility Degradation, Velocity Saturation	Dynamic Power Consumption, Total Power Consumption, PDP	Contact rules, metal rules, via rules and other rules
S-8	SLO-1	Dataflow modelling	Carry Skip Adder (CSK)	Channel Length Modulation, Threshold Voltage Effects	CMOS Circuit Design Styles: Static CMOS logic styles	Gate Layouts
	SLO-2	Realization of Combinational and sequential circuits	Carry Bypass Adder (CBA)	Leakage, Temperature Dependence, Geometry Dependence, Subthreshold Current	CMOS circuits, pseudo-nMOS, tristate circuits, clocked CMOS circuits	Stick diagrams
S-9, 10	SLO-1	Lab-1: Realization of combinational and sequential circuits using gate-level and dataflow modeling	Lab-4: Realization of VLSI adders - I	Lab-7: Realization of VLSI multipliers - II	Lab-10: (a) Design, Analysis of complex CMOS gate using HSPICE (b) Design, Analysis of Pseudo-NMOS gates using HSPICE	Lab-13: Model Practical Examination
	SLO-2					
S-11	SLO-1	Behavioral modelling	Multipliers: Multiplication (unsigned, shift/add multiplication algorithms, multiplication of signed numbers, types of multiplier architectures)	Short-channel MOSFETS: Hot carriers, Lightly-Doped Drain (LDD)	Differential Cascade Voltage Switch Logic (DCVSL), Pass Transistor Logic (PTL)	CMOS Process Enhancements: Transistors (Multiple Threshold Voltages and Oxide Thicknesses, Silicon-on-Insulator, High-k Gate Dielectrics, Higher Mobility, Plastic Transistors,)
	SLO-2	Realization of Combinational and sequential circuits	Braun multiplier	MOSFET scaling	Dynamic CMOS logic styles: Basic dynamic logic	
S-12	SLO-1	Switch-level modelling	Baugh-Wooley multiplier	Short-channel effects: Negative Bias Temperature Instability, oxide breakdown	Signal integrity issues in dynamic design	Interconnects
	SLO-2	Realization of MoS circuits	Wallace Tree multiplier	Drain-Induced Barrier Lowering (DIBL), Gate-Induced Drain Leakage (GIDL), Gate Tunnel Current	Signal integrity issues in dynamic design	Circuit elements
S-13	SLO-1	Design using FSM	Booth multiplier	Tutorials	Domino Logic Circuits: Differential Domino logic, multiple-output domino	Beyond conventional CMOS
	SLO-2	Realization of sequential circuits	Booth multiplier	Tutorials	Compound domino, NORA, TSPC	Tutorials
S-14, 15	SLO-1	Lab-2: (a) Realization of digital circuits using behavioral modeling	Lab-5: Realization of VLSI adders - II	Lab-8: Realization of RAM & ROM	Lab-11: (a) Design, Analysis of AND/NAND gate in DCVSL using SPICE (b) Design, Analysis of Pass-Transistor gates and CPL gates using HSPICE	Lab-14: End-Semester Practical Examination
	SLO-2	(b) Realization of MOS circuits using switch-level modeling				

Learning Resources	1. Jan Rabaey, Anantha Chandrakasan, B Nikolic, "Digital Integrated Circuits: A Design Perspective". Second Edition, Feb 2003, Prentice Hall of India. 2. Weste, Harris, "CMOS VLSI Design: A Circuits and Systems Perspective", 4th ed., Addison-Wesley, 2011. 3. Wayne Wolf, "Modern VLSI Design: IP-based Design", 4th edition, PHI, 2009.	4. R. Jacob Baker, "CMOS Circuit Design, Layout, and Simulation", Wiley, (3/e), 2010. 5. John P. Uyemura, "CMOS Logic Circuit Design", Kluwer, 2001. 6. S. Palnitkar, Verilog HDL – A Guide to Digital Design and Synthesis, Pearson, 2003 7. Paul. R.Gray, Robert G. Meyer, "Analysis and Design of Analog Integrated Circuits", Wiley, (4/e), 2001. 8. M.D.Ciletti, Modeling, Synthesis and Rapid Prototyping with the Verilog HDL, Prentice Hall, 1999
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry		Experts from Higher Technical Institutions
1. Mr. Anuj Kumar, Bombardier Transportation, Ahmedabad, kumar.anuj@gmail.com		1. Dr. Meenakshi, Professor of ECE, CEG, Anna University, meena68@annauniv.edu
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com		2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in
		Internal Experts
		1. Mr. Manikandan AVM, SRMIST
		2. Dr. J. Manjula, SRMIST

Course Code	18ECC301T	Course Name	WIRELESS COMMUNICATION			Course Category	C	Professional Core				L	T	P	C
												3	1	0	4

Pre-requisite Courses	18ECC205J, 18ECC105T	Co-requisite Courses	Nil	Progressive Courses	18ECE220T
Course Offering Department	Electronics and Communication Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :		Understand the elements of Wireless Communication and mobile communications			1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :		Understand the Mobile Radio Wave Propagation - Large Scale Fading			Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :		Analyze how to apply Mobile Radio Wave Propagation - Small Scale Fading																				
CLR-4 :		Study the Capacity and Diversity concepts in wireless communications																				
CLR-5 :		Acquire the knowledge of Wireless System and Standards																				
CLR-6 :		Understand and design various wireless systems																				
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	H	H	H	H	H	H	H	H	H	H	M	M	M	M	M
CLO-1 :		Acquire the knowledge of Wireless communication and basic cellular concepts			2	75	60	-	-	-	-	-	-	-	-	-	-	-	M	M	-	L
CLO-2 :		Understand the essential Radio wave propagation and mobile channel models			2	75	60	H	H	H	H	-	-	-	-	-	-	-	M	M	-	H
CLO-3 :		Familiarize about Various performance analysis of mobile communication system.			2	75	60	H	H	H	-	-	-	-	-	-	-	-	-	-	-	H
CLO-4 :		Attain the knowledge of Diversity and capacity concepts			2	75	60	H	H	-	-	-	-	-	-	-	-	-	-	-	-	H
CLO-5 :		Be familiar with the various standards of Mobile Communication Systems			2	75	60	H	-	-	-	-	-	-	-	-	-	-	M	M	-	L
CLO-6 :		Explore the various concepts of wireless communication, its design with respect to fading and link performance			2	75	60	H	H	H	H	M	-	-	-	-	M	-	M	M	-	H

Duration (hour)		Wireless communication: Mobile communications	Large Scale Fading	Small Scale Fading	Improvement on Link performance	Wireless systems and standards
		12	12	12	12	12
S-1	SLO-1	Introduction to wireless communication and mobile radio communication	Introduction to Radio wave Propagation	Introduction Small scale multipath propagation	Introduction to diversity, equalization and capacity	AMPS Voice modulation Process
	SLO-2	Classification of wireless communications - simplex, half duplex, full duplex	Large scale and small scale fading	Impulse response model of multipath channel		
S-2	SLO-1	Paging and Cordless systems	Friis transmission equation- Free space propagation model - pathloss model	Impulse response model of multipath channel	Space diversity	GSM system architecture and its interfaces
	SLO-2	Cellular telephone systems		Small scale multipath measurements - Direct Pulse measurement	Scanning diversity	
S-3	SLO-1	Timing diagram - landline to mobile	Two Ray model	Small scale multipath measurements - Sliding correlator measurement	Maximal ratio combiner	GSM frame structure
	SLO-2	Timing diagram - mobile to mobile		Small scale multipath measurements - Swept frequency measurement	Equal gain diversity	
S-4	SLO-1	Basic antenna parameters, Far field and near field	Simplified pathloss model	Parameters of mobile multipath channels - Time dispersion and Coherent bandwidth	Rake Receiver	GSM speech operations input - output
	SLO-2	Frequency reuse, sectored and omni-directional antennas	Empirical model - Okumara			
S-5	SLO-1	Channel assignment strategies	Empirical model - Hata model	Parameters of mobile multipath channels - Doppler spread and Coherent time	Capacity in AWGN	Forward CDMA process
	SLO-2	Handoff and its types	Empirical model - Walfish and berton model			
S-6	SLO-1	Interference and system capacity	Piecewise linear model - log normal model	Types of fading: Flat and Frequency selective fading	Capacity of flat fading channels	Reverse CDMA Process
	SLO-2					
S-7	SLO-1	Trunking and Grade of Service	Shadowing	Types of fading: Flat and Frequency selective fading	Equalizer and its mode	Multicarrier modulation
	SLO-2		Combined pathloss and shadowing			

S-8	SLO-1	Cell splitting	Outage Probability	Types of fading: Fast and Slow fading	Adaptive equalizer block diagram	OFDM Transmitter Block diagram
	SLO-2					
S-9	SLO-1	Sectoring	Cell Coverage Area	Types of fading: Fast and Slow fading	Types of Equalizers - elementary level only	OFDM Receiver Block diagram
	SLO-2					
S-10	SLO-1	Microcell zone concepts	Solving problems – Brewster angle	Ricean distribution	Introduction to MIMO antennas	Importance of Cyclic Prefix
	SLO-2					
S-11	SLO-1	Umbrella cells	Solving problems – empirical model	Rayleigh distribution	Introduction to MIMO antennas	Case study - Modern antennas
	SLO-2					
S-12	SLO-1	Solving Problems	Solving problems – Friis transmission formula	Solving problems – Doppler effect	Case study :Recent trends in Diversity and MIMO antennas	Case study - Modern antennas
	SLO-2					

Learning Resources	<ol style="list-style-type: none"> 1. Rappaport.T.S., "Wireless Communications: Principles and Practice", 2nd Edition, Pearson, 2011. 2. John D Kraus , Ronald J Marhefka, Ahmed S Khan "Antenna and Wave Propagation", 4th Edition, Tata McGraw Hill, 2010 3. Constantine Balanis. A, "Antenna Theory: Analysis and Design", 3rd Edition, John Wiley, 2012. 4. Andreas.F.Molisch., "Wireless Communications", Wiley, 2nd Edition-2005, Reprint-2014 	<ol style="list-style-type: none"> 5. Andrea Goldsmith, "Wireless Communications", Cambridge University Press, Aug 2005 6. Schiller, "Mobile Communications", Pearson Education Asia Ltd., Reprint 2012 7. Lee W.C.Y., "Mobile Communications Engineering: Theory and Applications", McGraw Hill, New York, 2nd Edition, 1998
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

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2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	2. Dr. T. Ramarao, SRMIST

Course Code	18ECC302J	Course Name	MICROWAVE & OPTICAL COMMUNICATIONS	Course Category	C	Professional Core				L	T	P	C
										3	0	2	4

Pre-requisite Courses	18ECC205J	Co-requisite Courses	Nil	Progressive Courses	18ECE226T & 18ECE323T
Course Offering Department	Electronics and Communication Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):	The purpose of learning this course is to:
CLR-1 :	Identify Microwave active devices and Microwave generators
CLR-2 :	Analyze Microwave passive devices
CLR-3 :	Explore Microwave Measurements
CLR-4 :	Analyze Optical Fibers Optical Sources, Amplifier and Transmitter Optical Detectors , Receiver and Performance Measurements
CLR-5 :	Explore Optical Communication System Design and Concepts
CLR-6 :	Analyze Microwave and optical components

Learning		
1	2	3
Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)
2	80	70
2	80	70
2	80	70
2	80	70
2	80	70
2	80	70

Program Learning Outcomes (PLO)														
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
H	-	-	L	-	-	-	-	-	-	-	-	-	-	L
H	M	H	H	-	-	-	-	-	-	-	-	L	-	M
H	M	H	M	-	-	-	-	-	-	-	-	M	-	H
H	H	-	M	-	-	-	-	-	-	-	-	L	-	L
H	H	-	H	-	-	-	-	-	-	-	-	M	-	M
H	H	H	H	-	-	-	-	-	-	-	-	M	-	H

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:
CLO-1 :	Acquire knowledge on the theory of microwave transmission, microwave generators and associated components.
CLO-2 :	Analyse microwave passive devices and components.
CLO-3 :	Understand microwave measurements and associated techniques with equipment
CLO-4 :	Familiarize with the fundamentals of light transmission through fiber
CLO-5 :	Design a basic optical communication system.
CLO-6 :	Understand working principle of microwave components , Microwave measurements, optical sources, detector and fibers

Duration (hour)		15	15	15	15	15
S-1	SLO-1	Introduction to microwaves and optical communications	High frequency parameters: S parameters, S matrix analysis for N-port microwave device	Impedance matching.	Elements of Optical fiber communication	Point-to-Point link –Analog system design considerations and design steps
	SLO-2					
S-2	SLO-1	History of Microwave Engineering, Microwave transmission and Applications; Maxwell Equations	Directional coupler	VSWR and Impedance measurement	Functional block diagram of a Transmitter and receiver module	Point-to-Point link – Digital system design considerations and design steps
	SLO-2					
S-3	SLO-1	Microwave Tubes	E and H plane Tee	Measurement of Power	Optical fiber structure, Light Propagation in Optical fibers: Ray theory , Total Internal reflection, Skew rays	Digital Link Design: Link power budget
	SLO-2					
S-4-5	SLO-1	Lab- 1 Characteristics of Reflex Klystron	Lab- 4 Gain and radiation pattern of Horn antenna	Lab- 7 Practice session	Lab- 10 Measurement of Numerical Aperture, propagation and bending losses of optical fiber	Lab- 13 Design of basic Optical Communication system using computational tool
	SLO-2					
S-6	SLO-1	Reflex Klystron oscillators	Magic Tee	Measurement of Frequency and Q factor	Optical Sources: Light source materials, LED Structures	Rise time budget
	SLO-2					
S-7	SLO-1	Magnetron oscillators	Microwave Circulators, Isolators	Insertion loss measurements	LED Characteristics	Overview of Analog links: Radio over Fiber;
	SLO-2					
S-8	SLO-1	Microwave Bipolar Transistors Field effect transistor	Attenuators and Phase Shifters	Attenuation measurements	Semiconductor Laser Diode, Laser Characteristics	Key link parameters
	SLO-2					
S-9-10	SLO-1	Lab- 2 Study of power distribution in Directional coupler, E plane, H plane and Magic Tee	Lab- 5 Characteristics of filters, Microstrip patch antenna and parallel line coupler	Lab- 8 DC characteristics of LED and Laser diode	Lab- 11 Analysis of Analog optical link	Lab- 14 Practice Session
	SLO-2					
S-11	SLO-1	IMPATT, TRAPATT and Tunnel diode	Rectangular Waveguides	Measurement of Scattering parameters	Optical Detectors: PIN and APD photo detector	Multichannel System: Need for multiplexing
	SLO-2					

S-12	SLO-1 SLO-2	Gunn diode	Rectangular Waveguides	Measurement of Scattering parameters	Responsivity and efficiency of APD	WDM Components: Coupler/Splitter, Fabry Perot Filter
S-13	SLO-1 SLO-2	Gunn Oscillation modes	Power Dividers	Functioning details of Vector Network Analyzer; Signal Analyzer; Spectrum analyzers	Fiber attenuation and dispersion	WDM Components: Optical MEMS switches
S-14-15	SLO-1 SLO-2	Lab- 3 Impedance measurement by slotted line method	Lab- 6 Design of RF Filters and Amplifier using computational tool	Lab- 9 DC characteristics of PIN and APD photo-diode	Lab- 12 Analysis of Digital optical link	Lab- 15 Study experiment - Gunn Diode (Microwave) and Optical WDM (Optical)

Learning Resources	<ol style="list-style-type: none"> David M. Pozar, "Microwave Engineering", 4th Edition, John Wiley & Sons, 2012. David M. Pozar, "Microwave & RF Design of Wireless Systems", John Wiley & Sons, 2001. Samuel Y. Liao, "Microwave Devices and Circuits", 3rd Edition, Pearson Education, 2013. Robert. E. Collin, "Foundations for Microwave Engineering", 2nd edition, Wiley, Reprint 2014. Annapurna Das, Sisir K. Das, "Microwave Engineering", 3rd Ed., McGraw Hill, 2015. I. Hunter, "Theory and design of microwave filters", The Institution of Engineering & Technology, 2001. Keiser G, "Optical Fiber Communication Systems", 5th Edition, 6th Reprint, McGraw Hill Education (India), 2015. 	<ol style="list-style-type: none"> Vivekanand Mishra, Sunita P. Ugale, "Fiber Optic Communication: Systems and Components", Wiley-India, 1st edition, 2013 Djafar.K. Mynbaev and Lowell and Scheiner, "Fiber Optic Communication Technology", Pearson Education Asia, 9th impression, 2013 John M. Senior, "Optical fiber Communications: Principles and Practice", Pearson Education, 3rd Edition, 2009 R.P. Khare, "Fiber Optics and Optoelectronics", Oxford University Press, 2007. Rajiv Ramaswami, Kumar N. Sivarajan, Galen H.Sasaki "Optical Networks A practical perspective", 3rd edition, 2013
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
Level 2	Apply Analyze	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
Level 3	Evaluate Create	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry		Internal Experts
1. Mr. Anuj Kumar, Bombardier Transportation, Ahmedabad, kumar.anuj@gmail.com		1. Dr. Meenakshi, Professor of ECE, CEG, Anna University, meena68@annauniv.edu
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com		2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in
		2. Dr. T. Ramarao, SRMIST

Course Code	18ECC303J	Course Name	COMPUTER COMMUNICATION NETWORKS	Course Category	C	Professional Core	L	T	P	C
							3	0	2	4

Pre-requisite Courses	18CSS101J	Co-requisite Courses	Nil	Progressive Courses	18ECE320T
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Introduce the basic concepts in the field of computer networks.	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Understand the functional aspects of OSI model architecture.	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Acquire knowledge of the Network Layer protocols	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Analyze the various issues and challenges of Transport Layer.	Expected Attainment (%)	Design & Development
CLR-5 :	Familiarize the various Application Layer Protocols.		Analysis, Design, Research
CLR-6 :	Utilize the networking concepts to analyze the performance of Routing protocols.		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Understand the basic services and concepts related to internetworking.	2 80 70	H - - - - M M - - - - M H M -
CLO-2 :	Explain the basic OSI model architecture and its lower layer functions.	2 85 75	H - - - - M M - - - - M H M -
CLO-3 :	Give an insight of the various Network Layer concepts, mechanisms and protocols.	2 75 70	H - - - - M M - - - - M H M H
CLO-4 :	Appreciate the services and techniques of Transport Layer.	2 85 80	H - - - - M M - - - - M - H M
CLO-5 :	Discuss the various services and protocols in Application Layer.	2 85 75	H - - - - M M M - - - - M H M
CLO-6 :	Implement and analyze the various Networking concepts and Routing protocols.	2 80 70	- - - - H - - - - - - M M H

Duration (hour)	Data Communication & Networking Basics	Osi Lower Layers	Network Layer	Transport Layer	Application Layer
	15	15	15	15	15
S-1	SLO-1 Introduction to Data Communication and Networking	Network models	Introduction to Network Layer	Introduction to Transport Layer	Introduction to Application Layer
	SLO-2 Data transfer modes-Serial and Parallel transmission	OSI layer architecture	Need for Internetworking	TCP/IP Model	Application Layer Paradigms
S-2	SLO-1 Protocols & Standards	Data Link Layer-Introduction	Addressing-Classful	User Datagram Protocol(UDP)	Client Server Interaction
	SLO-2 Layered Architecture	Link Layer Addressing	Addressing-Classful	User Datagram Protocol(UDP)	Client Server Interaction
S-3	SLO-1 Principles of Layering & Description	Error Detection	Addressing-Classless	Transmission Control Protocol(TCP)	SIP
	SLO-2 Brief description of concepts in OSI & TCP/IP model	Error Detection	Addressing-Classless	Transmission Control Protocol(TCP)	SIP
S 4-5	SLO-1 Lab 1: To build and configure a simple network of four nodes connected with point-to-point links.	Lab 4: To simulate token ring protocol and to study its performance.	Lab 7:To simulate CSMA/CA protocol and to study its performance	Lab 10: Implementation and study of Selective Repeat protocol.	Lab 13: Create a Socket (TCP&UDP) between two computers and enable file transfer between them.
	SLO-2				
S-6	SLO-1 Switching Types- Circuit- & Packet switching	Error Correction	Network Layer Protocol-IPV4	TCP Services & Features	Compression Techniques
	SLO-2 Switching Types- Message switching, Comparison of switching types	Error Correction	Internet Protocol(IP)-IPV4	TCP Services & Features	Compression Techniques
S-7	SLO-1 LAN, MAN & WAN	Data link control-LLC	Internet Protocol(IP)-IPV6	Congestion Control	Introduction to Cryptography
	SLO-2 LAN, MAN & WAN	Data link control-LLC	Internet Protocol(IP)-IPV6	Congestion Control	Types, Attacks and Services
S-8	SLO-1 Network topologies-Types	Data link control-MAC	Routing Protocols- Distance Vector& Link State	Congestion Control	DES
	SLO-2 Comparison of topologies	Data link control-MAC	Routing Issues-Delivery, Forwarding and Routing	Congestion Control	DES
S 9-10	SLO-1 Lab 2: To simulate star and bus network topologies.	Lab 5: Implementation of Error detection and Correction scheme.	Lab 8: Implementation and study of stop and wait protocols	Lab 11: To configure a network using Link State Routing protocol.	Lab 14: Implementation of Data Encryption and Decryption.
	SLO-2				

S-11	SLO-1	IEEE standards for LAN-Ethernet	Flow & Error Control Protocol	Routing Information Protocol-RIP	QOS-Quality of Service	RSA
	SLO-2	Types of Ethernet	Flow & Error Control Protocol	Routing Information Protocol-RIP	QOS-Quality of Service	RSA
S-12	SLO-1	Token Bus	ARQ Schemes	Open Shortest Path First-OSPF	Techniques to improve QOS	Email
	SLO-2	Token Ring	ARQ Schemes	Open Shortest Path First-OSPF	Techniques to improve QOS	FTP
S-13	SLO-1	FDDI	HDLC	Border Gateway Protocol-BGP	Techniques to improve QOS	HTTP
	SLO-2	FDDI	HDLC	Border Gateway Protocol-BGP	Techniques to improve QOS	SNMP
S 14-15	SLO-1	Lab 3: To simulate token bus protocol and to study its performance.	Lab 6: To simulate CSMA/CD protocol and to study its performance	Lab 9: Implementation and study of Go back N protocol.	Lab 12: To configure a network using Distance Vector Routing protocol.	Lab 15: Mini Project
	SLO-2					

Learning Resources	1. Behrouz A.Fehrouzan, "Data communication & Networking", Mc-Graw Hill, 5 th Edition Reprint, 2014.	4. James F. Kurose, Keith W. Ross, "Computer Networking: A Top-Down Approach Featuring the Internet", Pearson Education, 6 th Edition, 2013.
	2. Andrew S.Tanenbaum, "Computer Networks", Pearson Education India, 5 th Edition, 2013.	5. "Lab Manual", Department of ECE, SRM Institute of Science and Technology
	3. William Stallings, "Data & Computer Communication", Pearson Education India, 10 th Edition, 2014	

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Anuj Kumar, Bombardier Transportation, Ahmedabad, kumaranuj.anii@gmail.com	1. Dr. Meenakshi, Professor of ECE, CEG, Anna University, meena68@annauniv.edu	1. Ms. T. Ramya, SRMIST
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	

Course Code	18ECC350T	Course Name	COMPREHENSION				Course Category	C	Professional Core															L	T	P	C																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																											

ACADEMIC CURRICULA

Professional Core Courses

MECHANICAL ENGINEERING

Regulations - 2018



SRM INSTITUTE OF SCIENCE AND TECHNOLOGY

(Deemed to be University u/s 3 of UGC Act, 1956)

Kattankulathur, Kancheepuram, Tamil Nadu, India

Course Code	18MEC201T	Course Name	MACHINES AND MECHANISMS	Course Category	C	Professional Core			
						L	T	P	C
						3	1	0	4

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	understand motion of linked mechanisms in terms of displacement, velocity and acceleration at any point in a rigid link				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	be able to synthesis cam profile and to understand the kinematics of gear trains				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	understand the Balancing of rotating masses and friction																					
CLR-4 :	Know the concepts of free vibration of single degree of freedom systems.																					
CLR-5 :	Know the concepts of forced vibration of single degree of freedom systems.																					
CLR-6 :	understand the concepts of kinematics and machine dynamics																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	explain the basics of mechanism and perform kinematic analysis.				1&2	90	85	H	H	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-2 :	construct various cam profiles based on follower motion and perform kinematic analysis and Epicyclic Gear train				1,2&3	85	85	H	H	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-3 :	perform balancing of rotating masses and describe friction in machine elements				1&2	90	85	H	-	-	H	-	-	-	-	-	-	-	-	-	-	-
CLO-4 :	analyze free vibration single degree of freedom systems.				1&2	90	85	H	H	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-5 :	define the concepts of forced vibration and critical speed or whirling of shaft				1&2	90	90	H	-	H	-	-	-	-	-	-	-	-	-	-	-	-
CLO-6 :	apply the concepts of kinematics and machine dynamics in real time applications				1&2	80	80	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-

Duration (hour)		12	12	12	12	12
S-1	SLO-1	Introduction to mechanism and its elements, Degrees of Freedom, its application in different mechanism	circular Cam terminology, types of cams and followers	Friction- Introduction, Types of friction, Laws of solid and dry friction, Limiting angle of friction	Introduction to vibration terminologies and types of vibration	Equation of motion for harmonically excited single Degree of Freedom system
S-2	SLO-1	Four Bar Chain, Grashof's law, Kutzbach's and Grubler's criterion	Types of follower motion and its derivatives, under cutting	Friction Clutches- single plate and multiplate Clutches	Equation of motion for free un-damped single Degree of Freedom system by Newton's and energy method- Longitudinal vibration	Forced vibration –Beating Phenomenon
S-3	SLO-1	Kinematic Inversions of kinematic chain: Four bar chain, Single and double slider crank chain	Displacement, velocity and acceleration for different follower motion	Cone and Centrifugal Clutches	Equation of motion for free un-damped single Degree of Freedom system by Newton's and energy method- torsional vibration	Forced vibration due to unbalanced rotating and reciprocating masses
S-4	SLO-1	Tutorial-simple problems	Tutorial-simple problems	Tutorial on Clutches	Tutorials on single Degree of Freedom un-damped free vibration systems	Tutorials on harmonically excited single Degree of Freedom system
S-5	SLO-1	Velocity analysis of Four bar and single slider crank mechanism by relative velocity (RV) method	construction of circular cam profile for radial follower with different motion	Friction in Brakes-Block or shoe brake	Equation of motion for free damped single Degree of Freedom systems	Forced vibration due to Base excitation by Relative amplitude Method
S-6	SLO-1	Acceleration analysis of Four bar mechanism and single slider crank linkages by relative	construction of circular cam profile for offset follower with different motion	Friction in Brakes-Band brake principle	Free vibration with viscous damping	Forced vibration due to Base excitation by Absolute Method
S-7	SLO-1	Velocity and Acceleration of double slider crank mechanism.	basic principles of tangent cam profile	Friction in Brakes-Band brake principle	Logarithmic decrement	Force Transmissibility and vibration isolation
S-8	SLO-1	Tutorial on Velocity and Acceleration by relative method	Tutorial on cam profile construction	Tutorial for Friction Brakes	Tutorials on free damped single Degree of Freedom systems	Tutorials on Forced vibration due to Base excitation by Absolute and Relative amplitude Method

S-9	SLO-1	Velocity and Acceleration of six bar mechanism by relative method	Gear terminology, types, law of gearing Tutorial on path of contact, arc of contact, sliding velocity	Balancing of rotating masses- Need for balancing, Static and dynamic balancing of rotating masses	Torsional system with viscous damping	Critical speed or whirling of shaft
S-10	SLO-1	Instantaneous center (IC) method, Kennedy's theorem	Gear train, types and applications	Balancing of several masses rotating in same plane by analytical and graphical methods	Torsional Vibration of Two Rotor and three rotor Systems	Critical speed or whirling of shaft-with air damping
S-11	SLO-1	Velocity analysis of Four bar and single slider crank mechanism by Instantaneous center method	velocity ratio, torque calculations in epicyclic gear train	balancing of several masses rotating in different planes using couple and force polygon	Torsional Vibration of Geared Systems with Two and Three rotor System	Critical speed or whirling of shaft-without air damping
S-12	SLO-1	Tutorial on Instantaneous center method	Tutorials on epicyclic gear train	Tutorial on balancing of several masses rotating in same plane and different planes using couple and force polygon	Tutorials on Torsional Vibration of Two Rotor and three rotor Systems	Tutorials on Critical speed or whirling of shaft-with air damping

Learning Resources	1. Rattan, S. S. "Theory of Machines", McGrawHill Education, 4th edition, 2015 2. Thomas Bevan, "The Theory of Machines", Pearson India Education Services Pvt. Ltd., 3rd Edition, 2010.	3. L Norton, "Design of machinery - An introduction to the synthesis and analysis of mechanisms and machines", McGrawHill Education, 5th edition, 2011. 4. William Cleghorn, Nikolai Dechev, "Mechanics of Machines", Oxford University Press, 2nd Edition, 2014.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Evaluate Create	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	1. Dr. Sudheesh Kumar, sudheeshkumar3@gmail.com, GCE, Kannur	1. Dr.P.Nandakumar, SRMIST
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	2. Dr.R.Prabhusekar, rprabhusekar@mnnit.ac.in, MNNIT Allahabad	2. Dr.P V Jeyakarhikeyan, SRMIST

Course Code	18MEC202T	Course Name	HEAT AND MASS TRANSFER				Course Category	C	Professional core			L 3	T 1	P 0	C 4										
Pre-requisite Courses	18MEC101T & 18MEC102T			Co-requisite Courses	Nil			Progressive Courses	Nil																
Course Offering Department		Mechanical Engineering			Data Book / Codes/Standards			Heat and Mass transfer data book and steam tables																	
Course Learning Rationale (CLR):		The purpose of learning this course is to:				Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Understand the concept of conduction heat transfer				Level of Thinking (Bloom)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2 :	Understand the concepts of fins and unsteady state heat transfer								Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Understand the concept of convection heat transfer																								
CLR-4 :	Understand the concept of radiation heat transfer																								
CLR-5 :	Understand the phase change heat transfer and mass transfer																								
CLR-6 :	Understand the concepts of heat and mass transfer																								
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:				Level of Thinking (Bloom)	3	90	80	H	H	L	H	L	L	L	L	L	L	L	L	H	L		
CLO-1 :	Analyse and evaluate steady state heat conduction in simple and composite systems				H					H	L	H	L	L	L	L	L	L	L	L	L	L	L	H	L
CLO-2 :	Analyse and evaluate steady state heat conduction in finned systems and unsteady state heat conduction in simple geometries				H					H	L	H	L	L	L	L	L	L	L	L	L	L	L	H	L
CLO-3 :	Evaluate the heat transfer coefficient under free and forced convection in various geometries and simple design of heat exchangers				H					H	L	H	L	L	L	L	L	L	L	L	L	L	L	H	L
CLO-4 :	Evaluate surface and gas radiation for black and grey bodies				H					H	L	H	L	L	L	L	L	L	L	L	L	L	L	H	L
CLO-5 :	Analyse and evaluate heat and mass transfer coefficient for phase change process and mass transfer				H					H	L	H	L	L	L	L	L	L	L	L	L	L	L	H	L
CLO-6 :	Apply the concepts of heat transfer in real time applications				3	90	80	H	H	L	H	L	L	L	L	L	L	L	L	L	H	L			
Duration (hour)		12		12		12		12		12															
S-1	SLO-1	Modes and mechanism of heat transfer in solids, liquids and gases	Fins – types,Differential equation,Types of fin boundary conditions		Hydrodynamic and thermal boundary layer,Principles and governing equations		Basic concepts of radiation ,Laws of radiation		Nusselt theory of condensation,Film condensation on a vertical plate and its flow regimes																
S-2	SLO-1	General conduction equation, boundary and initial conditions	Circumferential and longitudinal fins		Dimensional analysis for free convection		Atmospheric and solar radiation		Heat transfer correlations for film condensation,Film condensation inside horizontal tubes																
S-3	SLO-1	One dimensional steady state heat conduction in plane wall, cylinder and sphere, electrical analogy	Fin efficiency,Fin effectiveness		Dimensional analysis for forced convection		Black body radiation Grey body radiation		Dropwise condensation																
S-4	SLO-1	Tutorial on plane wall, cylinders and spheres	Tutorial on fins		Tutorial on hydrodynamic and thermal boundary layer		Tutorial on laws of radiation		Tutorial on Filmwise condensation																
S-5	SLO-1	One dimensional steady state heat conduction in composite plane wall	Unsteady state heat conduction in Lumped heat model		Forced convection: Flow over flat plate, cylinders and spheres		Shape factor algebra		Modes of Boiling																
S-6	SLO-1	One dimensional steady state heat conduction in composite cylindrs	Unsteady state heat conduction in semi-infinite solid		Forced convection : Internal flow		Electrical analogy		Pool boiling regimes, Correlations for pool boiling heat transfer																
S-7	SLO-1	One dimensional steady state heat conduction in composite spheres	Unsteady state heat conduction in infinite solid		Free convection : Flow over plates, cylinders and spheres		Radiation shield		Flow boiling regimes																
S-8	SLO-1	Tutorial on composite systems	Tutorial on unsteady state heat conduction		Tutorial on free and forced convection		Tutorial on shape factor, radiation shield and electrical analogy		Tutorial on pool boiling																
S-9	SLO-1	Critical thickness of insulation for cylinders	Numerical solution for one dimensional steady state heat conduction		Heat Exchangers – Types, overall heat transfer coefficient, fouling factor		Introduction to Solar radiation		Diffusion mass transfer – Fick's law of diffusion, Steady state diffusion through plane membrane																
S-10	SLO-1	Critical thickness of insulation for spheres	Numerical solution for one dimensional steady state heat conduction		LMTD and Effectiveness – NTU method method of analysis		Radiation properties of gases		Equimolar counter diffusion,Isothermal evaporation of water vapour into air																

S-11	SLO-1	One dimensional steady state heat conduction with internal heat generation	Numerical solution for two dimensional steady state heat conduction	Heat transfer enhancement methods, Selection of heat exchangers	Gaseous emission and absorption - water vapour and carbon dioxide	Convective mass transfer, Convective mass transfer correlations, Simultaneous heat and mass transfer
S-12	SLO-1	Tutorial on critical thickness of insulation and internal heat generation	Tutorial on one and two dimensional steady state heat conduction	Tutorial on heat exchangers	Tutorial on gas radiation	Tutorial on diffusion and convective mass transfer

Learning Resources	<ol style="list-style-type: none"> 1. Sachdeva, R.C., Fundamentals of Heat and Mass Transfer, 2nd Edition, New Age International (P) Ltd., New Delhi, 2017. 2. Nag, P.K., Heat Transfer and Mass Transfer, Tata McGraw Hill, 3rd Edition, New Delhi, 2011. 3. Ozisik. M. N, "Heat Transfer", McGraw-Hill Book Co., 2003. 4. Holman. J. P "Heat and Mass Transfer" Tata McGraw-Hill, 2008. 5. Yunus A. Çengel, Afshin J. Ghajar "Heat and Mass Transfer", Tata McGraw Hill Education, 2017. 6. Theodore L. Bergman, Adrienne S. Lavine, Frank P. Incropera, David P. DeWitt, "Fundamentals of Heat and Mass Transfer", John Wiley and Sons, 2016. 7. DATA BOOKS 8. K.K.Ramalingam "Steam Tables", SciTech Publications, 2015. 					
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	1. Dr. M. R. Kamesh, Dayanada Sagar College of Engineering	1. Mr. D. Premnath, SRMIST
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cwrde.drdo.in	2. Dr.N. Saravanan, Smart Implements and Machinery and Sustainability	2. Dr.P. Chandrasekaran, SRMIST

Course Code	18MEC203L	Course Name	MACHINE DYNAMICS LABORATORY	Course Category	C	Professional core	L	T	P	C
							0	0	2	1

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	understand the static and kinematics behavior of machines	Learning (Bloom)	Efficiency (%)	Enrichment (%)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	understand the dynamic behavior of machines																					
CLR-3 :	understand the balancing of masses in machines																					
CLR-4 :	understand the effect of centrifugal forces in machine																					
CLR-5 :	understand the free and forced vibration analysis																					
CLR-6 :	acquire the ability to analyze the dynamics behavior of machines																					

[illegible]

Duration (hour)	6	6	6	6	6
S-1	Cam and Follower Analysis	Dynamic analysis of Proelland porter Governor	Measurement of cutting forces using Drill tool Dynamometers	Free damped and un-damped torsional vibration of single rotor systems	Transmissibility Ratio in Vibrating Systems
S-2		Dynamic analysis of Gyroscope	Dynamic Balancing of massesin machine	Measurement of cutting forces using Milling Dynamometers	Free & forced vibration of equivalent spring mass system
S-3					
S-4					
S-5	Dynamic analysis of Epi cyclic gear trains	Measurement of cutting forces using, Lathe tool Dynamometer	Free Vibration of helical springs	Whirling of shaft	Vibration measurement using strain gauge
S-6					

Learning Resources	<ol style="list-style-type: none"> 1. <i>Laboratory Manual</i> 2. Thomas Bevan, "The Theory of Machines", Pearson India Education Services Pvt. Ltd., 3rd Edition, 2010. 3. Robert L Norton, "Design of machinery - An introduction to the synthesis and analysis of mechanisms and machines". McGrawHill Education, 5th edition, 2011.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	-	40 %	-	30 %	-	30 %	-	30 %	-	30%
	Understand	-	40 %	-	30 %	-	30 %	-	30 %	-	30%
Level 2	Apply	-	40 %	-	40 %	-	40 %	-	40 %	-	40%
	Analyze	-	40 %	-	40 %	-	40 %	-	40 %	-	40%
Level 3	Evaluate	-	20 %	-	30 %	-	30 %	-	30 %	-	30%
	Create	-	20 %	-	30 %	-	30 %	-	30 %	-	30%
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	2. Dr.R.Prabhusekar, rprabhusekar@mnnit.ac.in, MNNIT Allahabad	2. Dr.P V Jeyakartheeyan, SRMIST

Course Code	18MEC204L	Course Name	SIMULATION LABORATORY				Course Category	C	Professional core		L	T	P	C									
											0	0	2	1									
Pre-requisite Courses	Nil		Co-requisite Courses	18MEE305T Finite Element Method				Progressive Courses	Nil														
Course Offering Department		Mechanical Engineering				Data Book / Codes/Standards		Nil															
Course Learning Rationale (CLR):		The purpose of learning this course is to:				Learning 1 2 3 Level of Thinking (Bloom) Expected Proficiency (%) Expected Attainment (%)			Program Learning Outcomes (PLO)														
CLR-1 :	Upon learning the students shall understand the need of software tools to analyze the Engineering problems.				1				2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLR-2 :	Understand and practice structural analysis of components.				Engineering Knowledge				Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3	
CLR-3 :	Understand and practice modal and vibrational analysis of components.				H				H		H	H		H						H			
CLR-4 :	Understand and practice Thermal analysis of components.				H				H		H	H								H			
CLR-5 :	Understand and practice Dynamic analysis of components.				H				H		H	H								H			
CLR-6 :	Simulate any engineering problem numerically.				H	H		H	H								H						
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:				3 75 80 3 75 80 3 75 80 3 75 80 3 75 80																	
CLO-1 :	Learn data exchange standard and integration of FEA with software tools.				H				H		H	H								H			
CLO-2 :	Learn and practice structural analysis of components using software tools.				H				H		H	H								H			
CLO-3 :	Learn and practice modal and vibrational analysis of components using software tools.				H				H		H	H								H			
CLO-4 :	Learn and practice Thermal analysis of components using software tools.				H				H		H	H								H			
CLO-5 :	Learn and practice Dynamic analysis of components of components using software tools.				H				H		H	H								H			
CLO-6 :	Practice numerical simulation of any engineering problem using software.				H	H		H	H								H						
Duration (hour)	6		6		6		6		6		6		6										
S-1	SLO-1	Displacement bar structures with different support conditions.	Stress and deflection analysis in beams with different support condition.	Modal analysis of beam – Finding natural frequency –Cantilever beam, Simply supported beam etc with UDL	Dynamic analysis of thin circular cylindrical shell.	Thermal analysis – Steady state and Transient - 3D problem.																	
S-2																							
S-3	SLO-1	Force and stress analysis using link elements in Trusses.	Plane stress and Plane strain problems – Simple examples – flat plate with hole, circular disc with hole Tapper plate etc.	Modal analysis of beam – Finding natural frequency –Cantilever beam, Simply supported beam etc with UDL	Thermal analysis – Steady state and Transient - 1D problem.	Kinematic analysis of Four bar mechanism.																	
S-4																							
S-5	SLO-1	Stress and deflection analysis in beams with different loading condition.	Stress analysis of axi -symmetric component.	Vibrational analysis - plate with dynamic condition.	Thermal analysis – Steady state and Transient - 2D problem.	Dynamic analysis of slider crank mechanism.																	
S-6																							
Learning Resources	1. Laboratory Manual 2. Reddy .J.N., An Introduction to finite Element Method, 3 rd .,Tata McGraw Hill.2005.				3. Chandrupatla, T.R., Belegundu, A.D., "Introduction to Finite Elements in Engineering", Prentice Hall,1990.1990India, 1997.																		
Learning Assessment																							
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)													
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#															
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice										
Level 1	Remember	-	40 %	-	30 %	-	30 %	-	30 %	-	30 %	-	30%										
Level 2	Understand	-	40 %	-	40 %	-	40 %	-	40 %	-	40 %	-	40%										
	Apply	-	40 %	-	40 %	-	40 %	-	40 %	-	40 %	-	40%										
Level 3	Analyze	-	20 %	-	30 %	-	30 %	-	30 %	-	30 %	-	30%										
	Evaluate	-	20 %	-	30 %	-	30 %	-	30 %	-	30 %	-	30%										
	Create	-	20 %	-	30 %	-	30 %	-	30 %	-	30 %	-	30%										
	Total	100 %		100 %		100 %		100 %		100 %		100 %											
# CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,																							
Laboratory Course Designers																							
Experts from Industry				Experts from Higher Technical Institutions						Internal Experts													
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in				Dr. Davidson Jebaseelan, davidson.jd@vit.ac.in,VIT, Chennai						Mr. S. Balamurugan, SRMIST													
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in				Mr. Vignesh Shanmugam.s.Hyundai Motors Limited, Chennai, 273357@hmail.net						Dr.P V Jeyakarthykeyan, SRMIST													

Course Code	18MEC205L	Course Name	HEAT AND MASS TRANSFER LABORATORY				Course Category	C	Professional core			L	T	P	C
												0	0	2	1

Pre-requisite Courses	Nil				Co-requisite Courses	18MEC202T Heat and Mass Transfer				Progressive Courses	Nil				
Course Offering Department		Mechanical Engineering				Data Book / Codes/Standards				Heat and Mass Transfer Data Book and Refrigerant Tables and Charts					

Course Learning Rationale (CLR):		The purpose of learning this course is to:						Learning			Program Learning Outcomes (PLO)																		
CLR-1 :	Conduction, Convection and Radiation modes of Heat Transfer.											1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	The Performance of Heat Exchangers, condensation and boiling apparatus.											Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	The Performance of Refrigeration and Air Conditioning systems.																												

Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:						Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Analyze Conduction, Convection and Radiation modes of heat transfer and evaluate the thermal conductivity, heat transfer coefficients and radiation constants.																								
CLO-2 :	Evaluate the effectiveness of heat exchangers,heat transfer rate in condensation and boiling.						3	95	90	H	H	L	L	L		M		H							
CLO-3 :	Evaluate the Coefficient of performance of refrigeration and air conditioning systems.						3	95	90	H	H	L	L	L		M		H							

Duration (hour)		Conduction Heat Transfer		Convection Heat Transfer		Radiation Heat Transfer		Heat Exchangers, Boiling and Condensation		Refrigeration and Air Conditioning Systems	
		6		8		4		8		4	
S-1	SLO-1	Heat Transfer through Composite wall.		Heat transfer by Natural Convection.		Study of the Emissivity apparatus.		Study of parallel flow and counter flow Heat Exchanger.		Study of Refrigeration Test Rig.	
	SLO-2	Determination of heat transfer rate.		Determination of convective heat transfer coefficient		Determination of the emissivity of grey surface.		Determination of overall heat transfer coefficient, heat transfer rate and effectiveness of heat exchanger.		Determination of CoP of the Refrigeration Test Rig.	
	SLO-1	Heat Transfer through Composite lagged pipe.		Heat transfer by Forced Convection.		Study of Stefan – Boltzmann's Apparatus.		Study of Shell and tube Heat Exchanger.		Study of Air Conditioning Test Rig.	
	SLO-2	Determination of Thermal Conductivity of the materials.		Determination of convective heat transfer coefficient		Determination of Stefan Boltzmann Constant.		Determination of overall heat transfer coefficient, heat transfer rate and effectiveness of heat exchanger.		Determination of CoP of the Air Conditioning Test Rig.	
S-3	SLO-1	Thermal conductivity of an insulating Material.		Heat transfer through Pin Fin by Natural Convection.		-		Study of Film wise and drop wise condensation apparatus.			
	SLO-2	Determination of Thermal Conductivity of insulating material.		Determination of Efficiency and Effectiveness of the pin fin				Determination of Condensate rate.			
S-4	SLO-1	-		Heat transfer through Pin Fin by Forced Convection.				Study on Critical heat Flux Apparatus.			
	SLO-2	-		Determination of Efficiency and Effectiveness of the pin fin				Determination of Critical heat Flux.			

Learning Resources	1.Laboratory Manual 2.Kothandaraman.C.P, Subramanyan.S, "Heat and Mass Transfer Data Book", New age International, 8th edition, 2014. 3.Mehta.F.S, Mathur.M.L, "Refrigeration & Psychrometric Properties Tables & Charts", 3rd Edition, Jain Publishers, 2014.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	-	40 %	-	30 %	-	30 %	-	30 %	-	30%
	Understand	-	40 %	-	30 %	-	30 %	-	30 %	-	30%
Level 2	Apply	-	40 %	-	40 %	-	40 %	-	40 %	-	40%
	Analyze	-	40 %	-	40 %	-	40 %	-	40 %	-	40%
Level 3	Evaluate	-	20 %	-	30 %	-	30 %	-	30 %	-	30%
	Create	-	20 %	-	30 %	-	30 %	-	30 %	-	30%
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	Dr. M.R.Kamesh, Dayananda Sagar College of Engineering, Bangalore	Mr.M.D.Kathir Kaman , SRM IST
Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	Dr.N.Saravanan, Smart Implements & Machinery and Sustainability, Mahindra Research Valley, Chennai	Dr.C.Selvam, SRM IST

Course Code	18MEC206T	Course Name	METROLOGY AND QUALITY CONTROL	Course Category	C	Professional core	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book / Codes /Standards	Approved Metrology & Quality Control Tables and Charts		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Be familiar with standards of measurements and types of measurement errors	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Know the basics of measurement for thread, gear and surface finish																		
CLR-3 :	Be familiar with optical and other non-contact measurements																		
CLR-4 :	Be familiar with working of coordinate measuring machines and alignments of machine tool																		
CLR-5 :	Select the appropriate control chart and sampling plan																		
CLR-6 :	Be familiar with dimensional and form measurements using conventional and coordinate metrology, together with quality control techniques																		

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Understand the types of measurement errors, design of limit gauges and various comparative measurement methods	3	90	85	H	H	M	L	L								M	L	L
CLO-2 :	Acquire the fundamentals of the gear, thread and surface finish measurements	3	90	85	H	H	M		L								L	L	L
CLO-3 :	Perceive the knowledge about the optical metrology and non-contact measurement	3	90	85	H	M			H								L	L	L
CLO-4 :	Learn the fundamentals of CMMs	3	90	85	H	M			H								H	L	L
CLO-5 :	Choose the appropriate control charts	3	90	85	H	H	L		M				H			L	H	L	L
CLO-6 :	Choose the types of sampling and methods in acceptance sampling for SQC	3	90	85	H	H	M		M							L	H	L	L

		Introduction To Metrology	Measurements Of Screw Thread - Gear Elements – Surface Finish	Optical And Other Non-Contact Measurement Techniques	Coordinate Metrology And Form Measurement; Machine Tool Metrology	Theory Of Control Charts & Acceptance Sampling
Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction to metrology; Need for inspection; Physical measurements	Measurements of various elements of external and internal threads: Measurement of major and minor diameters, pitch and flank angle	Principle of light wave interference, light sources, measurements using optical flats	Introduction to coordinate metrology; Coordinate metrology versus conventional metrology	Definition of quality; Assignable causes and Chance causes; SQC: Benefits and limitations
S-2	SLO-1	Methods of measurement; Classification and characteristics of measuring instruments	Measurement of effective diameter: two and three wire methods; best size wire; error corrections	Types of interferometers: Michelson, Twyman Green Specialization of Michelson	Types and construction of CMM; Components: Bearings; Drive systems	Theory of Control Charts; Control Charts for Variables: X bar and R charts
S-3	SLO-1	Role of NPL; Sources and types of errors	Measurements of various elements of spur gears: gear tooth vernier	NPL flatness interferometer, The Pitter NPL gauge interferometer	Components: Transducers; Probes	Control Charts for attributes: P chart, np chart
S-4	SLO-1	Statistical treatment of errors; tutorial	Constant chord method: derivation and tutorial	Laser interferometer, Laser micrometer	Measuring accuracy, causes of errors and calibration of CMM: Tutorial	Control charts for Non Conformities - C and U chart
S-5	SLO-1	Standards of measurements; Classification of standards; Calibration	Base tangent method: derivation and tutorial	Surface roughness measurement using Lasers	Performance of CMM and its applications	Basic Concepts of acceptance sampling and OC curve, AQL, LTPD ,AOQL
S-6	SLO-1	Limits, fits, and tolerances: tutorial	Circular pitch and composite error measurement	Measurement of straightness using Autocollimator, Tutorial	Overview of alignment tests in machine tools using dial gauge, spirit level, straight edges	Tutorial
S-7	SLO-1	Interchangeability and Selective Assembly	Surface finish: Surface topography definitions	Measurement of flatness using Autocollimator	Measurement of squareness and parallelism	Sampling Plans: Simple
S-8	SLO-1	Inspection Gauges, Types of Gauges	Measurement of surface finish: measuring instruments	Machine vision, Image processing techniques	Circularity: tutorial	Sampling Plans: Double and Multiple - tutorial
S-9	SLO-1	Introduction to Comparators; Mechanical (Sigma), Electrical, and Pneumatic comparators	Methods of evaluation of surface finish	Edge detection, feature extraction - applications	Measurement of cylindrical and conical features, and runout	Sequential sampling plans

Learning Resources	<ol style="list-style-type: none"> 1. Jain, R. K., "Engineering Metrology", Khanna Publishers, New Delhi, 2012. 2. Gupta, R. C., "Statistical Quality Control", Khanna Publishers, New Delhi, 1994. 3. Kevin Harding, "Handbook of Optical Dimensional Metrology", CRC Press, A Taylor & Francis group, 2013. 4. Robert J. Hocken, Paulo H. Pereira, "Coordinate Measuring Machines and Systems", CRC Press, Taylor & Francis Group, 2011. 5. Connie Dotson, Roger Harlow and Richard L. Thompson, "Fundamentals of Dimensional Metrology", Thomson Delmar Learning", 4th edition, 2005. 6. Galyer, J. F. W., and Shotbolt, C. R., Metrology for Engineering, Cassell London, 5th Edition 7. Toru Yoshizawa, "Handbook of Optical Metrology: Principles and Applications", CRC Press, 2009. 8. Grant E. L., "Statistical Quality Control", McGraw Hill, New York, 1972 9. M. Mahajan, Statistical Quality Control, Dhanpat Rai & co. Gagankapur, 2010. 10 Heinrich Schwenke, Ulrich Neuschaefer-Rube, Tilo Pfeifer, Horst Kunzmann, "Optical Methods for Dimensional Metrology in Production Engineering", CIRP Annals - Manufacturing Technology, 51(2) (2002) 685–699 11. A. Weckenmann, T. Estler, G. Peggs, D. McMurtry, "Probing Systems in Dimensional Metrology", CIRP Annals - Manufacturing Technology, 53 (2) (2004) 657–684 12. A.M.A. Al-Ahmari, Javed Aalam, "Optimizing parameters of freeform surface reconstruction using CMM", Measurement, 64 (2015) 17–28 13. K. Duraivelu and S. Karthikeyan. "Engineering Metrology and Measurment", Universities Press (India) Private Limited, 2018.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Understand	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Subburathinam_Shankar@cat.com	1. Dr. G. Rajamohan, NIFFT, grajamohan.nifft@gov.in	1. Mr.Sundar S, SRMIST
2. Sridhar.narasimhan@hexagon.com	2. Dr.N.Arunachalam, IIT Madras, chalam@iitm.ac.in	2. Dr. A. Vijaya, SRMIST

Course Code	18MEC207T	Course Name	CAD/CAM	Course Category	C	Professional core	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	-		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Be familiar with the concepts of modeling in 2D and 3D	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Be familiar with the Mathematical Representation of curves and surfaces	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Be familiar with the concepts of Computer Graphics				H	M	H	L	L	-	-	-	-	L	M	L	H	M	M
CLR-4 :	Be familiar with the basics of CNC machines and manufacturing systems				H	M	H	L	L	-	-	-	-	L	M	L	H	M	M
CLR-5 :	Be familiar with the concepts of Computer aided production planning and control				H	L	M	H	M	-	-	-	-	L	M	M	H	M	M
CLR-6 :	Be familiar with the concepts of CAD and CAM				H	M	L	L	L	-	M	-	-	L	M	H	H	M	H
					H	M	M	L	L	-	L	-	-	L	M	M	H	M	M
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Recognize and analyze the concepts of modeling in 2D and 3D	3	90	85															
CLO-2 :	Apply the concepts learned in Mathematical Representation of curves and surfaces	3	90	85															
CLO-3 :	Understand and apply the concepts of Computer Graphics like shading, coloring, clipping, animation and simulation	3	90	85															
CLO-4 :	Understand and analyze the basics of CNC machines and manufacturing systems	3	90	85															
CLO-5 :	Apply and evaluate the concepts of Computer aided production planning and control	3	90	85															
CLO-6 :	Understand, apply and evaluate the concepts of CAD and CAM	3	90	85															

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Fundamentals of Computer aided design	Mathematical representation of lines, circle	Cohen Sutherland Clipping Algorithm	Fundamentals of CNC machines, Classification, Developments
S-2	SLO-1	Product Life Cycle	Mathematical representation of Hermite curves	Shading and its types	CNC principles of operation and features
S-3	SLO-1	sequential and concurrent engineering	Mathematical representation of Bezier curves, B-spline curves	Colouring and its types	Machining Centers and its types
S-4	SLO-1	Coordinate Systems, 2D transformations	Parametric representation of plane surface and Ruled surface	Introduction to Data exchange standards	Introduction to Group technology and its types
S-5	SLO-1	3D transformations	parametric representation of Surface of revolution and Tabulated cylinder	Data exchange standards: IGES, STEP	Part families, coding and classification
S-6	SLO-1	Wire frame modeling and Surface modeling	Hidden line removal - Visibility Techniques	Data exchange standards: DXF and CALS and GKS	Production flow analysis with case study
S-7	SLO-1	Solid modeling - Constructive Solid Geometry	Priority and Area -oriented Algorithm	Animation Types	Machine cell design with numerical case study
S-8	SLO-1	Solid modeling - Boundary Representation	Hidden surface removal algorithms	Animation Techniques	Introduction to FMS, types, applications and benefits
S-9	SLO-1	Feature Entities and Representation	Hidden Solid removal algorithms	Simulation Technique	FMS :components, Layout Configurations and implementation
					Agile manufacturing

Learning Resources	1. Ibrahim Zeid, "Mastering CAD /CAM (Sie)", Tata McGraw-Hill, New Delhi, 2010 2. P.N. Rao, "CAD/CAM Principles and Application", 3rd Edition, Tata McGraw-Hill, New Delhi, 2012 3. Mikell P. Groover, "Automation, Production systems and computer integrated manufacturing", Prentice Hall of India Private Ltd., New Delhi, 2008. 4. Mikell P. Groover, Emory W. Zimmers Jr., "CAD/CAM: Computer Aided Design and Manufacturing", Prentice Hall of India Private Ltd., New Delhi, 2008.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
<i>Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in</i>	<i>Dr. S. Sridhar, PSNA college of Engg. & Tech., Dindigul</i>	<i>Mr.J.Daniel Glad Stephen, SRMIST</i>
<i>Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in</i>	<i>Mr.V.Selvakumar, vselvakumar86@gmail.com, Ford India, Chennai</i>	<i>Dr. P. Nandakumar, SRMIST</i>

Course Code	18MEC208T	Course Name	MECHANICAL ENGINEERING DESIGN	Course Category	C	Professional core	L 3	T 1	P 0	C 4
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Pre-requisite Courses	18MEC206T	Co-requisite Courses	Nil	Progressive Courses	18MEE401T
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	PSG Design Data Book		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Know fundamental concepts to design the mechanical components.	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Be familiar with the concepts to design the shafts, keys and couplings		
CLR-3 :	Know the concepts to design the temporary joints.		
CLR-4 :	Be familiar with the concepts to design the permanent joints.		
CLR-5 :	Know the concepts to design the levers and springs.		
CLR-6 :	Know the fundamental concepts in design of machine elements		

Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			Level of Thinking	Expected	Expected	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Management	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Design of mechanical components.	3	85	75	H	H	H	M	L	L	L	L	L	L	L	L	L	L	L	L	H	L
CLO-2 :	Design of shafts, keys and couplings.	3	85	75	H	H	H	M	L	L	L	L	L	L	L	L	L	L	L	L	H	L
CLO-3 :	Design of temporary joints.	3	85	75	H	H	H	M	L	L	L	L	L	L	L	L	L	L	L	L	H	L
CLO-4 :	Design of permanent joints.	3	85	75	H	H	H	M	L	L	L	L	L	L	L	L	L	L	L	L	H	L
CLO-5 :	Design of levers and springs.	3	85	75	H	H	H	M	L	L	L	L	L	L	L	L	L	L	L	L	H	L
CLO-6 :	Design of machine elements	3	85	75	H	H	H	M	L	L	L	L	L	L	L	L	L	L	L	L	H	L

		FUNDAMENTALS OF MECHANICAL DESIGN	VARIABLE STRESSES ,DESIGN OF SHAFTS,KEYS AND COUPLINGS	DESIGN OF TEMPORARY JOINTS	DESIGN OF PERMANENT JOINTS	DESIGN OF LEVERS AND SPRINGS
Duration (hour)		12	12	12	12	12
S-1	SLO-1	Introduction to design, types of design.	Analysis of variable stresses: Endurance limit.	Design of Pin joints- cotter joints , basic concepts and types	Riveted joints: Types, materials, arrangement of rivets, terminology of riveted joints	Levers: Types, applications and analysis
	SLO-2	Criteria for Design based on strength, fatigue, stiffness.	Classification of variable stresses, factors influencing the endurance limit and fatigue stress determination.	Design of Socket and spigot cotter joint	Riveted joints: Types of failures.	
S-2	SLO-1	Criteria for Design based on, wear resistance, vibration resistance, heat resistance and reliability.	Stress concentration, Methods of reducing stress concentration, Notch sensitivity,theoretical stress concentration factor and fatigue stress concentration factor.	Design of Sleeve and cotter joint	Strength and efficiency of a riveted joint, Design of riveted joints for non eccentric loads.	Design of hand lever,foot lever.
	SLO-2	Overview of Engineering materials and their properties. Impact stress, Resilience.	Variable stresses using Soderberg method, Goodman method.	Design of Gib and cotter joint for square rods.	Design of riveted joints for pressure vessels.	Design of cranked lever, bell crank lever
S-3	SLO-1	Principal Stresses and Principal Planes,Application of Principal Stresses in design of machine members.	variable stresses using Gerber method.			
	SLO-2	Tutorial -Problems on Principal Stresses and Principal Planes.	Tutorial -Problems on variable stresses using Soderberg method, Goodman method and Gerber method.	Tutorial - problems on cotter joint.	Tutorial –Problems on riveted joints for structural applications and pressure vessels.	Tutorial – Problems on cranked lever and bell crank lever
S-4	SLO-1	Theories of failure, Rankine theory, Guests theory, St.Venants theory, Maximum strain energy theory and Distortion energy theory.	Types of Shafts, Shafting Materials and working stresses in shafts.	Design of Knuckle joint	Design of Diamond riveted joint.	Design of lever safety valve ,Rocker-Arm
	SLO-2		Design of uniform cross sectional Shafts.			
S-5	SLO-1	Theories of failure, Rankine theory, Guests theory, St.Venants theory,	Design of shaft subjected to combined twisting moment and bending moment.		Design of Eccentrically loaded riveted joint.	Springs: classification,application,spring materials and their properties.

	SLO-2	Maximum strain energy theory and Distortion energy theory.		Bolted joints: Design procedure and problems on bolted joints with non eccentric loads,		Terminology and end conditions of helical compression spring
S-7	SLO-1	Design of members subjected to combined stresses with eccentric load.	Design of shaft subjected to combined twisting moment, bending moment and axial loads.	Design of bolted joints for cylinder cover	Welded joints: Types and strength calculations	Design of circular and non circular wire helical springs for static loadings, Eccentric loading of helical springs, buckling of compression springs
	SLO-2					
S-8	SLO-1 SLO-2	Tutorial –Design of members subjected to combined stresses with eccentric load	Tutorial –Problems on Design of shaft.	Tutorial –Problems on bolted joints	Tutorial - Problems on axially loaded welded joints	Tutorial - Problems on helical springs
S-9	SLO-1	Eccentric loading in curved beams, crane hooks	Design of keys: Types of keys, forces acting on a key	Design of bolted joints with eccentric load parallel to axis of bolt and perpendicular to axis of bolt	Welded joints subjected to axial loads for unsymmetrical sections	Design of concentric helical springs
	SLO-2		Couplings: Types of couplings, design of sleeve coupling and clamp coupling.			Design of helical springs for fatigue loading
S-10	SLO-1	Eccentric loading in frames, clamps	Design of Flange coupling	Design of bolted joints with eccentric load in the plane containing bolts.	Eccentrically loaded linear fillet welded joints.	Design of helical torsion springs
	SLO-2					Design of Belleville springs
S-11	SLO-1	Standardization, interchangeability, fits and tolerances-Terminology of fits and tolerances	Design of bushed pin Flexible coupling	Design of Power screws; types, working principal and analysis of power screws.	Eccentrically loaded circular fillet welded joints.	Design of leaf springs, analysis and nipping of leaf springs
	SLO-2	Tolerances and their grades, fundamental deviation, Fits and its classifications			Welded joint subjected to fatigue loading	
S-12	SLO-1	Tutorial –Problems on computation of IT tolerances, fundamental deviations	Tutorial – Problems on coupling	Tutorial – Problems on bolted joints with eccentric load and Power screws.	Tutorial –Problems on eccentrically loaded welded joint.	Tutorial –Problems on leaf springs
	SLO-2					

Learning Resources	<ol style="list-style-type: none"> 1. Robert C.Juvinall and Kurt M. Marshek "Fundamentals of Machine Component Design", John Wiley & sons, 2017. 2. Spotts, M.F., Shoup, T.E., "Design of Machine Elements", Prentice Hall of India Eighth Edition, 2006. 3. Joseph Edward Shigley and Charles R. Mischke, "Mechanical Engineering Design", McGraw-Hill International Editions, 10th edition., 2015 4. William Orthwein, "Machine Component Design", Vol. I and II, Jaico Publishing house, New Edition, 2006. 5. Khurmi, R.S. and Gupta J.K., "Machine design", S.Chand publishing, 14th Edition, 2014. 6. V.B. Bandari, "Design of Machine Elements", McGraw-Hill International Editions, 4th edition., 2016 7. P.S.G Tech., "Design Data Book", Kalaikathir Achchagam, 2012
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	Dr. T.Jeyapoovan jeyapoovan@hindustanuniv.ac.in, Hindustan University, Chennai.	Dr.R.Santhana Krishnan., SRM IST,
Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	Mr. V.Sundara Raghavan, sundararaghavanv@bharatpetroleum.in Bharat Petroleum Corporation Limited, Chennai	Dr. P. Nandakumar, SRMIST

Course Code	18MEC209L	Course Name	CAD/CAM LABORATORY	Course Category	C	Professional core	L 0	T 0	P 2	C 1													
Pre-requisite Courses	Nil		Co-requisite Courses	18MEC207T		Progressive Courses	Nil																
Course Offering Department		Mechanical Engineering		Data Book / Codes/Standards		Nil																	
Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)															
CLR-1 :	Learn to Modeling of 3D Mechanical Components			Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Prepare assembly drawings of joints, couplings and machine elements																						
CLR-3 :	Design and prepare modelling for Jigs and fixtures of given components																						
CLR-4 :	Familiarize CNC Part programming techniques for Lathe operations and milling operations																						
CLR-5 :	Machining of components using CNC Lathe and CNC milling machine																						
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			3	90	85	H	-	H	M	H	-	-	-	M	H	-	-	L	-	L	
CLO-1 :	Acquire knowledge on Modeling of 3D Mechanical Components			3	85	80	H	-	H	M	H	-	-	-	M	H	-	-	M	-	L		
CLO-2 :	Understand the concepts of assembly drawings of joints, couplings and machine elements			3	85	80	H	-	H	M	H	-	-	-	M	H	-	-	M	-	M		
CLO-3 :	Acquire knowledge to design and prepare drawing for Jigs and fixtures of given components			3	90	85	H	-	H	L	H	-	-	-	-	-	-	-	L	-	M		
CLO-4 :	Understand and generate the NC part programming for Lathe and milling operations.			3	90	85	H	-	H	M	H	-	-	-	-	-	-	-	L	-	M		
CLO-5 :	Acquire Practical knowledge on machining of components using CNC Lathe, Milling.			3	90	85	H	-	H	M	H	-	-	-	-	-	-	-	L	-	M		
Duration (hour)	Modeling of mechanical components 6		Machine Tool components 6	Jigs& Fixtures 6		CNC LATHE 6					CNC MILLING 6												
S 1-2	Modeling of Simple Mechanical Components and temporary fasteners, Modeling of components with sweep ,variable sweep ,loft and blend feature		Assembly modeling for Machine Vice	Assembly modelling for lathe, milling and broaching fixtures types		CNC Part Program for Facing, Step turning, Taper and Finish Turning using ordinary cycle					CNC Part Program for Linear and Circular Interpolation using Milling operation												
S 3-4	Assembly Modeling of joints and Couplings		Assembly modelling for Lathe tail stock	Assembly modelling for plate, latch, channel, box, post, pot drill jigs and automatic drill jigs		CNC Part Program for Grooving, Threading and Axial Drilling Using canned cycle					CNC Part Program for Drilling, Mirroring and Threading Operation.												
S 5-6	Assembly modeling of Screw jack		Assembly modeling of connecting rod	Assembly modelling for Grinding, planning, shaping and welding fixtures		Machining of components on Turning operation using CNC Lathe					Machining of components on Milling operation using Vertical machining Center												
Note: Course committee will follow any 11 experiment																							
Learning Resources	1.Narayana.K.L, Kanniah.P and VenkataReddy.K, Machine Drawing, New Age International, New Delhi, 2006. 2.Gopalakrishnan.K.R, Machine Drawing, Subash Publishers, Bangalore, 2000. 3. Narang, JS, "CNC Machines and automation", Dhanpat Rai & Co. Ltd, 2016.					4. James Madison, "CNC Machining Hand Book", Industrial Press Inc., New York, 1996. 5. P.S.G Tech., "Design Data Book", KalaikathirAchchagam, 2012																	
Learning Assessment																							
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)										Final Examination (50% weightage)											
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#															
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice												
		Remember	-	40 %	-	30 %	-	30 %	-	30 %	-	30 %											
	Understand	-	40 %	-	40 %	-	40 %	-	40 %	-	40 %												
Level 2	Apply	-	40 %	-	40 %	-	40 %	-	40 %	-	40 %												
Level 3	Analyze	-	40 %	-	40 %	-	40 %	-	40 %	-	40 %												
Level 3	Evaluate	-	20 %	-	30 %	-	30 %	-	30 %	-	30 %												
Level 3	Create	-	20 %	-	30 %	-	30 %	-	30 %	-	30 %												
Level 3	Total	100 %		100 %		100 %		100 %		100 %													
# CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,																							
Course Designers																							
Experts from Industry											Experts from Higher Technical Institutions											Internal Experts	
Dr.R.Kalimuthu,ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in											Dr. S. Sridhar, PSNA college of Engg. & Tech., Dindigul											S.Balamurugan, SRMIST	
Dr.A.Velavutham. DRDO. Avadi. velavudham.a@cvrde.drdo.in											Mr.V.Selvakumar. vselvakumar86@gmail.com. Ford India. Chennai											J.Santhakumar, SRMIST	

Course Code	18MEC210L	Course Name	AUTOMATION LABORATORY	Course Category	C	Professional core	L 0	T 0	P 2	C 1
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Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Design pneumatic circuits for low cost automation	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Design hydraulic circuits for industrial automation	Thinking (Bloom)	Efficiency (%)	Attainment (%)	Knowledge	Analysis	Development	Design, Research	Usage	Culture	Sustainability	Team Work	Communication	Finance	Marketing				
CLR-3 :	Design of Electro pneumatics, servo and stepper motor control circuits																		
CLR-4 :	Design logic circuits and execute using PLC																		
CLR-5 :	Implement photo electric and ultrasonic, positional and velocity sensors, Virtual instrumentation and pick and placerobot.																		
CLR-6 :	Design circuits and simulate hydraulics/ pneumatics/ stepper, servo motors for industrial applications.																		

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Acquire knowledge on designing pneumatic circuits.	3	90	85	H		H										H	M	M
CLO-2 :	Acquire knowledge on designing hydraulic circuits.	3	85	80	M	M											M	M	L
CLO-3 :	Acquire knowledge on designing electro pneumatic circuits, control of stepper and servo motors for various applications.	3	85	80	M	L											L	M	L
CLO-4 :	Do PLC ladder logic programming and execute.	3	90	85	H		M		H								H	L	L
CLO-5 :	Use photo electric, ultrasonic, positional, velocity sensors for various applications and virtual instrumentation and pick and place robot.	3	90	85	M		L		H								M	M	L
CLO-6 :	Design low cost automation and provide solution for industrial and societal needs	3	85	80	H		M		H								M	M	H

Duration (hour)	Devising and simulation of pneumatic circuits	Designing and simulation of hydraulic circuits	Electro pneumatics, servo and stepper motor control circuits	PLC based ladder logic circuits	Virtual instrumentation and pick & place robot
	10	4	6	4	6
S 1-2	Continuous reciprocation of double acting cylinder with speed control circuit.	Synchronization circuit for two cylinders	Electro Pneumatic circuits: Continuous reciprocation of cylinder (with timer and Counter) and Sequencing of two cylinders	PLC Controlled Pneumatic / Hydraulic linear actuator Circuits	Process control: Temperature/ force/ pressure/ control using virtual instrumentation
S 3-4	Sequencing of two cylinders Circuit	Force, velocity calculations in hydraulic linear actuation	Speed control of AC Servo Motor using open and closed loop control.	PLC application circuits: Basic Trainer kit/ Water Level Controller/ Material Handling system	Characteristics of inductive, capacitive and photoelectric proximity sensors
S 5-6	Cascading circuit for trapped signal- 2 Cylinder		Positional control of a stepper motor	Study of SCADA and PAC systems	Pick and place operation using industrial robot in Teach pendent method / Manual mode
S 7-8	Cascading circuit for trapped signal – 3 Cylinder				Study of Image Processing Technique
S 9-10	Implementation of logic circuits: AND, OR				

Note: Course committee will follow any 11 experiment

Learning Resources	1. Laboratory Manual 2. Anthony Esposito, "Fluid Power with applications", Pearson Education Inc, 2015.	3. FESTO manual, "Fundamentals of Pneumatics", Vol I, II and III. 4. Joji Parambath "Industrial Hydraulic Systems: Theory and Practice", Universal Publishers, USA, 2016.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	-	40 %	-	30 %	-	30 %	-	30 %	-	30%
	Understand	-	40 %	-	30 %	-	30 %	-	30 %	-	30%
Level 2	Apply	-	40 %	-	40 %	-	40 %	-	40 %	-	40%
	Analyze	-	40 %	-	40 %	-	40 %	-	40 %	-	40%
Level 3	Evaluate	-	20 %	-	30 %	-	30 %	-	30 %	-	30%
	Create	-	20 %	-	30 %	-	30 %	-	30 %	-	30%
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. R. Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	1. Dr. P. Hariharan, Anna University, hari@annauniv.edu, hariharan2311@gmail.com	Mr. B.Ramprasath, SRMIST
2. Dr. A. Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	2. Dr.N.Arunachalam, IIT Madras, chalam@iitm.ac.in	Mr.R. Murugesan, SRMIST

Course Code	18MEC211L	Course Name	METROLOGY AND QUALITY CONTROL LABORATORY				Course Category	C	Professional Core			L	T	P	C									
											0	0	2	1										
Pre-requisite Courses		Nil		Co-requisite Courses		18MEC206TMetrology and Quality Control		Progressive Courses		Nil														
Course Offering Department			Department of Mechanical Engineering				Data Book / Codes/Standards				Nil													
Course Learning Rationale (CLR):		The purpose of learning this course is to:				Learning			Program Learning Outcomes (PLO)															
CLR-1 :		Understandvarious standards of measurement (line, end and wavelength standard)				Level of Thinking (Bloom)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :		Perceivethe measurement of Gear, Thread and Form errors								Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :		Acquainthe calibration of measuring instruments.																						
CLR-4 :		Acquire and explore the use of computer aided measuring techniques																						
CLR-5 :		Interpret and drafting sampling and control charts																						
CLR-6 :		Recognize the various measuring techniques in dimensional, optical and computer aided inspection and its role in SQC																						
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:				Level of Thinking (Bloom)	3	95	90	H	H		L	H			L	M	L			H	M	M
CLO-1 :		demonstrate and practice different standards of measuring instrument (line, end& wavelength)								H	H		L	L			M	L	M			L	L	M
CLO-2 :		Apply and accomplish the measurement of Gear, Thread and Form errors								H	H		M				L				L	M	M	M
CLO-3 :		Exhibit and Perform the calibration of measuring instruments.								H	H		M	H	M		H	M	M		H	H	M	M
CLO-4 :		Exemplify and carry measurements using computer aided measuring techniques.										H		M	L		M	H			L	M	L	H
CLO-5 :		Exposition and drafting sampling and control charts															M	H						
Duration (hour)	Basic Measuring instruments (end line and light standard)		Gear, Thread and Form errors		Calibration of Instruments and comparative method of measurement		Measurement using computer aided measuring techniques			Optical methods & Drafting sampling and control charts														
	6		6		6		6			6														
	S 1-2	Linear measurements using Verniercalliper,micrometer, height gauge and slip gauge.	Gear tooth measurement using Gear tooth vernier and Parkinson Gear Tester		Calibration of Measuring Instruments (Micrometer, Vernier Caliper, Vernier Height gauge and Dial)		Various parameter measurement using Computerized profileprojector			Attribute Control Charts using Go, No-Go gauges														
	S 3-4	Angle measurements using Sine bar and Sine center	Thread parameter measurement using floating carriage		Measurement using different comparators (mechanical, electronic and pneumatic)		Fundamental measurements including circularity using CMM			Demo on Interferometers and measurements using laser														
S 5-6	Indirect linear and angular measurements using standard balls and rollers		Straightness, flatness measurement using autocollimator		Surface roughness measurement		Measurement using Machine Vision system			Tool Angle measurement in tool makers microscope														
Learning Resources		1. Laboratory Observation Manual 2. Machine Manuals supplied by supplier/Company																						
Learning Assessment																								
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)														
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#		Theory	Practice													
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice															
Level 1	Remember	-	40 %	-	30 %	-	30 %	-	30 %	-	30%													
	Understand																							
Level 2	Apply	-	40 %	-	40 %	-	40 %	-	40 %	-	40%													
	Analyze																							
Level 3	Evaluate	-	20 %	-	30 %	-	30 %	-	30 %	-	30%													
	Create																							
	Total	100 %		100 %		100 %		100 %		100 %														
Course Designers																								
Experts from Industry					Experts from Higher Technical Institutions					Internal Experts														
1. Dr. R. Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in					1. S Samsudeen, National Skill Training institute, CTI Campus, ssamsadt@gmail.com					1. Dr. A Vijaya, , SRMIST														
2. Dr. A. Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in					2. Mr. Ramesh Ramanathan ,rramanathan@outlook.com					2. Mr. S. Muralidharan, SRMIST														

Course Code	18MEC350T	Course Name	COMPREHENSION				Course Category	C	Professional Core				L	T	P	C																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																														
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Pre-requisite Courses	Nil				Co-requisite Courses	Nil			Progressive Courses	Nil																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																				
Course Offering Department		Mechanical Engineering				Data Book / Codes/Standards			Nil																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																					
Course Learning Rationale (CLR):		The purpose of learning this course is to:								Learning			Program Learning Outcomes (PLO)																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																	
CLR-1 :	Understand the concepts in design engineering courses								Level of Thinking (Bloom)	1	2	3	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																	
CLR-2 :	Understand the concepts in thermal engineering courses																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																													
CLR-3 :	Understand the concepts in manufacturing engineering courses																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																													
CLR-4 :	Understand the concepts in engineering that they have learnt so far in the Mechanical Engineering programme																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																													
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																												

ACADEMIC CURRICULA

Professional Core Courses

MECHATRONICS ENGINEERING

Regulations - 2018



SRM INSTITUTE OF SCIENCE AND TECHNOLOGY

(Deemed to be University u/s 3 of UGC Act, 1956)

Kattankulathur, Kancheepuram, Tamil Nadu, India

Course Code	18MHC201J	Course Name	LINEAR AND DIGITAL CONTROL SYSTEMS			Course Category	C	Professional Core				L	T	P	C										
											3	0	2	4											
Pre-requisite Courses		System Dynamics		Co-requisite Courses		Nil		Progressive Courses		Nil															
Course Offering Department		Mechatronics Engineering			Data Book / Codes/Standards			Nil																	
Course Learning Rationale (CLR):		The purpose of learning this course is to:					Learning			Program Learning Outcomes (PLO)															
CLR-1 :		Learn the significant specifications of control systems					1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLR-2 :		Understand the design techniques of linear compensators and controllers					Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3	
CLR-3 :		Design state space based controllers and observers								H	H	H	H	H	-	-	-	M	-	-	L	H	H	M	-
CLR-4 :		Practically implement state space and discrete-time controllers								H	H	H	H	H	-	-	-	M	-	M	H	H	M	-	
CLR-5 :		Simulate of control systems								H	H	H	H	H	-	-	-	M	-	M	H	H	M	-	
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:					2	80	75	H	H	H	H	H	-	-	-	M	-	-	H	H	M	-	
CLO-1 :		Mathematically model and design classical compensators and controllers					3	80	75	H	H	H	H	H	-	-	-	M	-	-	H	H	M	-	
CLO-2 :		Demonstrate modeling and analysis of dynamic systems in state-space					3	75	70	H	H	H	H	H	-	-	-	M	-	M	H	H	M	-	
CLO-3 :		Design full state feedback controllers and full order observers					3	75	70	H	H	H	H	H	-	-	-	M	-	M	H	H	M	-	
CLO-4 :		Model, analyze and design control systems in z-domain					3	75	70	H	H	H	H	H	-	-	-	M	-	M	H	H	M	-	
CLO-5 :		Design and simulate control systems using software tools					3	75	70	H	H	H	H	H	-	-	-	M	-	M	H	H	M	-	
		Classical Compensators Design		PID Controller Design		State Space Modelling and Analysis		Design of State Controllers and Observers		Discrete-time Control System															
Duration (hour)		15		15		15		15		15															
S-1	SLO-1	Basic elements of automatic control systems, Classification of controlsystems		Introduction to active controllers		Concepts of state, state variables and state model		Concepts of controllability and observability.		Introduction to sampled data systems															
	SLO-2	Review of time and frequency domain specifications of control system in a design perspective		Introduction to On-Off, Proportional, PI, PD and PID controllers		Generic state space representations for systems of different types- Linear, Nonlinear, time variant and time invariant		Problems and illustrations		Sample and holdprocess: Zero order and first order hold.															
S-2	SLO-1	Effect of adding a pole and zero to dynamic systems		Transfer function , time and frequency response of PI controller		Derivation of linear state space model for mechanical systems		Full state feedback controller design- The pole placement techniques		Z-transform analysis of sampled data control systems															
	SLO-2	Introduction to Compensators and types		Transfer function , time and frequency response of PD controller		Example problems		Examples		Problems															
S-3	SLO-1	Pole zero contributions by lead, lag and lead-lag cascade compensators and their effects on compensated systems		Transfer function , time and frequency response of PID controller		Derivation of linear state space model for electrical systems		Full state feedback controller design using transformation method		Transfer function of discrete-time systems															
	SLO-2	Electrical cascade compensating networks- Transfer function, time and frequency response		Effect of each term of PID controller on the response of system		Example problems		Examples		Performance of a sampled-datassecond order system.															
S 4-5	SLO-1	Lab-1:Generate standard test signals: Impulse, step, ramp,parabolic, exponential and sinusoidal functions.		Lab-4:Root locus method: Determination of constant gain K, stability analysis		Lab-7:Design of controllers (PI, PD, PID) in time domain and frequency domain		Lab-10:Modeling in state-space: Determine state transition matrix, controllability and observability of linear systems		Lab-13:Discrete-time control systems: Convert a given transfer functions from analog to digital form, determine performance and stability in Z-domain.															
	SLO-2																								
S-6	SLO-1	Lead compensator design procedure using root locus- qualitative treatment preferably using software tools		Model based design of PI controller		Derivation of linear state space model for electrical systems		Full state feedback controller design using direct substitution method		Stability Analysis of discrete-time systems- Jury's stability criteria															
	SLO-2	Example problems		Example- model based design of PI controller for DC motor speed control		Example problems		Examples		Example problems															
S-7	SLO-1	Lag compensator design procedure using root locus- qualitative treatment preferably using software tools		Model based design of PD controller		Computation of state transition matrix, properties of statetransition matrix.		Full state feedback controller design using Ackerman's formula		Digital controller design-Direct digital design technique and conversion by transformation-introduction															

	SLO-2	Example problems	Example- model based design of PD controller for DC motor position control	Importance of state trajectory in chaotic systems	Examples	Mapping between s-plane and z-plane- different transformation techniques to convert analog controller to digital.
S-8	SLO-1	Lead compensator design procedure using Bode plot- qualitative treatment preferably using software tools	Model based design of PID controller	Solution to state equations	Full order and reduced order observers	Mapping between s-plane and z-plane- different transformation techniques to convert analog controller to digital.
	SLO-2	Example problems	Example- model based design of PID controller for DC motor speed as well as position control.	Example problems	Full order observer design using different methods-Design examples	Examples
S 9-10	SLO-1	Lab-2: Derive transfer functions of electrical, mechanical and electromechanical systems	Lab-5:Frequency response analysis: Determine frequencydomain specifications using Bode plot	Lab-8: System Identification with Qube servo	Lab-11: Design of full state feedback controllers and full order observers.	Lab-14: Implement digital compensators through though transformation technique
	SLO-2	Lag compensator design procedure using Bode plot- qualitative treatment preferably using software tools)	Limitations of Basic PID controller- Sensitive to Noise, Integrator wind-up problem.	Conversions of transfer function to state space model and vice versa.	Integrated full-state feedback and observer	Direct digital compensator design by Root locus technique
S-11	SLO-1	Example problems	A more practical version of PID controller- it's implementation	Example problems	Examples	Direct digital compensator design by Root locus technique
	SLO-2	Introduction to lead-lag compensator	Empirical procedure for tuning of PID gains	Different Canonical forms of representation of state space models	Case study: demonstration of integrated full state feedback & observer in simulation	Example problems
S-12	SLO-1	Comparison- Lead vs Lag compensators, s-domain vs frequency domain design	Zeigler-Nichols method based on open loop and closed loop responses. Cohen-coon method	Example Problems	A case study- demonstration of integrated full state feedback & observer in simulation	Example problems
	SLO-2	Limitations of passive compensators	Comparison between compensators and active controllers	Advantages and disadvantages of state space model representation	Introduction to optimal control systems	Selection of sampling rate, parameters to meet the desired performance of discrete-time control systems
S-13	SLO-1	Need for active controllers	Limitations of PID controllers- Need for model based controllers.	State space model for discrete-time systems	Introduction to optimal control systems	Example problems
	SLO-2	Lab-3: Determine time domain specifications for a givensystem: Transient and steady state.	Lab-6: Design compensators (lead, lag etc..) in time domain and frequency domain.	Lab-9: Speed and position control of Qube servo	Lab-12: Implement Kalman filter	Lab-15: Implement digital compensators by direct digital method

Learning Resources	<ol style="list-style-type: none"> 1. Richard C Dorf and Robert H Bishop, "Modern Control Systems", 13th edition, Pearson Education, 2016. 2. Norman S Nise, "Control Systems Engineering", 7th edition, Wiley, 2015. 3. I J Nagrath, M Gopal, "Control Systems Engineering", 5th edition, New Age International, 2007. 4. Benjamin C Kuo, FaridGolnaraghi, "Automatic Control Systems", 9th edition, Wiley, 2009. 	<ol style="list-style-type: none"> 5. K Ogata, "Modern Control Engineering", Prentice Hall, 2010. 6. A NagoorKani, "Control systems", RBA, 1998. 7. Quanser QNET Practical Control Guide. 8. Linear and Digital Control Systems Laboratory Manual, SRMIST.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
Level 2	Apply Analyze	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
Level 3	Evaluate Create	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Total	100 %		100 %		100 %		100 %		-	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Ganesh Ram, Intel Labs ,Bangalore, ganeshram.nandakumar.@intel.com	1. Dr.R. Thiyagarajan, Visiting faculty, IIT Madras, thiyaguiitm@gmail.com	1. Mr.K.Sivanathan, SRMIST
2. Mr. Mohammed Sagheer, Wabco Technology Center ,India, mohammedsagheer.musthafa@wabco-auto.com	2. Dr.PKarthikeyan, MIT, Anna University, pkarthikeyan@annauniv.edu	2. Ms.T.Rajalakshmi, SRMIST

Course Code	18MHC202J	Course Name	SENSORS AND SIGNAL CONDITIONING	Course Category	C	Professional Core				L 3	T 0	P 2	C 4
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Pre-requisite Courses	18MHC103T	Co-requisite Courses	Nil	Progressive Courses	18MHC302J,18MHE402T,18MHE428T								
Course Offering Department	Mechatronics Engineering			Data Book / Codes/Standards	Nil								

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																	
CLR-1 :	Expose the applications of OPAMP in signal conditioning circuits				Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLR-2 :	Perceive the fundamental knowledge of sensors and their characteristics and know the working principle of sensors for measurement of Force, Displacement					Expected Proficiency (%)	Expected Attainment (%)	Problem Analysis																	
CLR-3 :	Know the working principle of sensors for measurement of Position, Distance and Acceleration							Design & Development																	
CLR-4 :	Know the working principle of sensors for measurement of Pressure, Flow and Temperature							Analysis, Design, Research																	
CLR-5 :	Comprehend about data acquisition systems and applications of sensors							Modern Tool Usage																	
CLR-6 :	Gain knowledge about different sensors for physical system measurement							Society & Culture																	
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																							
CLO-1 :	Understand the functioning of OPAMP based signal conditioning circuits				2	90	85		H	M	L	L	M	-	-	-	-	-	-	L	M	-	M		
CLO-2 :	Identify the different types of sensors, their selection criteria and selection of sensors for measurement of Force and Displacement				3	90	80		H	M	-	L	M	L	-	-	-	-	L	H	M	M	L		
CLO-3 :	Identify and select sensors for measurement of Position, Distance and Acceleration				3	85	80		H	L	-	L	M	L	-	-	-	-	L	M	M	H	M		
CLO-4 :	Identify and select sensors for measurement of Pressure, Flow and Temperature				3	80	80		H	L	-	L	M	L	-	-	-	-	L	M	M	H	M		
CLO-5 :	Understand the working of data acquisition system and applications of sensors in various fields				3	85	80		H	L	L	L	H	L	-	-	-	-	L	M	H	H	H		
CLO-6 :	Prescribe the type of sensor to measure a specific phenomenon and appropriate signal conditioning circuit				2	85	80		H	L	L	L	M	L	-	-	-	-	L	M	M	H	M		

		Signal Conditioning System	Fundamentals of Sensors, Measurement of Force and Displacement	Measurement of Position, Distance and Acceleration	Measurement of Pressure, Flow and Temperature	Data Acquisition System and Case Studies
Duration (hour)		15	15	15	15	15
S-1	SLO-1	Review of OPAMP	Introduction to Sensors and Transducers	Working Principle of Eddy Current Sensor	Piezoelectric effect	Elements of Data Acquisition System
	SLO-2	Discussion	Classification of Sensors According to Various Physical Quantities	Applications of Eddy Current Sensor	Working Principle and Applications of Piezoelectric Sensor	Elements of Data Acquisition System
S-2	SLO-1	Characteristics of Instrumentation Amplifier	Working Principle of Strain Gauge	Working Principle of Hall Effect Sensor	Construction and Working of Bourdon Tubes	Multichannel Data Acquisition System
	SLO-2	Working of Instrumentation Amplifier	Applications of Strain Gauge and Simple Problems	Applications of Hall Effect Sensor	Types and Applications of Bourdon Tubes	Multichannel Data Acquisition System
S-3	SLO-1	Design and Analysis of RC Active Low Pass Filter	Working Principle and Applications of Load Cell	Working Principle and Types of Infra-Red Sensors	Working Principle and Applications of Diaphragms	Multiplexing
	SLO-2	Design and Analysis of Integrator	Quarter Bridge, Half Bridge and Full Bridge Configuration of Load Cells	Applications of IR Sensors	Working Principle and Applications of Bellows	DE multiplexing
S-4-5	SLO-1	Introduction to the Lab Course Lab 1: Study of Characteristics of Instrumentation Amplifier	Lab 4: Study of Characteristics of Load Cell	Lab 7: Distance Measurement using IR Sensor	Lab 10: Study of Characteristics of Pressure Sensor	Lab 13: Introduction to PC Based Data Acquisition System
	SLO-2	Design and Analysis of RC Active High Pass Filter	Working Principle and Applications of Potentiometer	Doppler Effect	Working Principle of Flow Sensors	Applications of Sensors in Bio Medical Systems
S-6	SLO-1	Design and Analysis of Differentiator	Working Principle, Types and Applications of Capacitive Sensors	Working Principle and Applications of Ultrasonic Sensor	Hot Wire Anemometer	Discussion
	SLO-2	Sampling theorem, Effect of Sampling	Working Principle of Magnetic Proximity Switch	Working Principle of SONAR	Working Principle of Acoustic sensors	Applications of Sensors in Aerospace Systems
S-7	SLO-1	Quantization, Quantization Error, Digitizing	Applications of Magnetic Proximity Switches	Working Principle of RADAR	Applications of Acoustic sensors	Discussion
	SLO-2					

S-8	SLO-1	Aliasing, Sample and Hold Circuit	Working Principle of Inductive Proximity Switch	Working Principle and Types of Accelerometer	Working Principle of Thermocouple	Applications of Sensors in Automobile Systems
	SLO-2	Simple Problems	Applications of Inductive Proximity Switches	Applications of Accelerometer	Types and Applications of Thermocouple	Discussion
S-9-10	SLO-1	Lab 2: Study of Characteristics of Active Filters	Lab 5: Study of Characteristics of Potentiometer	Lab 8: Distance Measurement using Ultrasonic Sensor	Lab: 11 Study of Characteristics of Thermocouple and MEMS IC Sensor	Lab 14: Repeat Lab Session
	SLO-2					
S-11	SLO-1	ADC: Flash Type	Working Principle and Applications of LVDT	Inertial Measurement Sensor	Working Principle of Thermistor	Applications of Sensors in Automobile Systems
	SLO-2	ADC: Successive Approximation Type	Working Principle and Applications of RVDT	Inertial Measurement Sensor	Applications of Thermistor	Discussion
S-12	SLO-1	DAC: Weighted Resistor, R-2R Network	Static Characteristics	Introduction to Optical Sensors - Photo Diode, Photo Transistor, Opto-Coupler	Working Principle of RTD	Sensors in Manufacturing
	SLO-2	Specifications of ADC and DAC	Simple Problems	Working Principle of LIDAR	Applications of RTD	Discussion
S-13	SLO-1	Precision Diodes, Half Wave Precision Rectifiers	Dynamic Characteristics	Working Principle of Optical Encoders	Concept of Thermal Mapping	Summary of the Course
	SLO-2	Full Wave Precision Rectifiers	Sensor Calibration	Types and Applications of Optical Encoders	Applications of Thermal Mapping	Discussion
S-14-15	SLO-1	Lab 3: Study of Characteristics of Precision Circuits	Lab 6: Study of Characteristics of LVDT	Lab 9: Position Measurement using Optical Encoders	Lab: 12 Study of Characteristics of Thermistor and RTD	Lab 15: Model Practical Examination
	SLO-2					

Learning Resources	1. Roy Choudhury.D, Shail. B.Jain, "Linear Integrated Circuits", 4th edition, New Age International Publishers, 2010.	4. Pratanabis.D, "Principles of Industrial Instrumentation", 2nd edition, Tata McGraw Hill, 1996.
	2. Pratanabis.D, "Principles of Industrial Instrumentation", 2nd edition, Tata McGraw Hill, 1996.	
	3. Sawhney.A.K., "Course in Mechanical Measurements and Instrumentation", DhanpatRai and Sons, 12th edition, 2001.	5. Paul P.L Regtien, "Sensors for Mechatronics", Elsevier publications, 1st edition, 2012.
		6. Laboratory Manual for Sensors and Signal Conditioning, SRMIST.

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		100%	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.A.Jegan, Assistant Manager, Renault – Nissan Technology and Business Centre India Private Ltd, jegan.a@mtbci.com	1. Dr.K. Kalaichelvan, Professor, Department of Ceramic Technology, Anna University, Chennai, kalaichelvan@annauniv.edu	1. Ms. G. Madhumitha SRMIST
2. Mr.R.GovardhanaGiri, Head – Atalon International, giri@atalon.in	2. Dr. P. Karthikeyan, Assistant Professor, Department of Production Technology, Anna University-MIT Campus, Chennai, pkarthikeyan@mitindia.edu	2. Mr. J. Thiyagarajan SRMIST

Course Code	18MHC203J	Course Name	MACHINE DESIGN	Course Category	C	Professional Core															L	T	P	C	
																					3	0	2	4	
Pre-requisite Courses		18MHC101J	Co-requisite Courses		Nil	Progressive Courses		Nil																	
Course Offering Department		Mechatronics Engineering		Data Book / Codes/Standards		Approved design data book																			
Course Learning Rationale (CLR):		The purpose of learning this course is to:				Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Analyze stress, strain in mechanical components, quantify failure modes in mechanical parts for various load conditions.				Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLR-2 :	formulate, design and identify torque elements.																								
CLR-3 :	estimate the life of sliding and rolling contact bearings.																								
CLR-4 :	analyze the gear failure modes, evaluate forces and stresses within a gear system.																								
CLR-5 :	select flexible drive systems and design for light, medium and heavy duty applications.																								
CLR-6 :	design, analyze, and select the suitable components for any particular engineering applications.																								
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																							
CLO-1 :	design basic mechanical components by considering the stress induced due to different kinds of load.				3	85	80	H	H	M	M	M	L	M	M	H	M	L	H	M	M	M	M		
CLO-2 :	select suitable shaft and coupling for the particular engineering applications.				3	85	80	H	H	H	M	M	L	M	M	H	M	L	H	M	M	M	M		
CLO-3 :	analyze and select bearing and lubricants for various engineering applications.				3	85	80	H	H	M	M	M	L	M	M	H	M	L	H	M	M	M	M		
CLO-4 :	design and analyze various simple gear trains for various power transmission applications.				3	85	80	H	H	M	M	M	L	M	M	H	M	L	H	M	M	M	M		
CLO-5 :	design and select suitable flexible drive system for power transmission applications.				3	85	80	H	H	M	M	M	L	M	M	H	M	L	H	M	M	M	M		
CLO-6 :	design and analyze the fundamental elements of machine component.				3	85	80	H	H	H	H	H	L	M	M	H	M	L	H	M	M	M	M		
Duration (hour)		Stresses In Machine Parts 15		Design of Shafts, Springs And Couplings 15		Design Of Bearings 15		Design of Gears 15		Design of Flexible Drives 15															
S-1	SLO-1	Introduction to the design process, Materials Selection and its Properties, Preferred Numbers, Fits and Tolerances		Introduction to Shafts and Types of Transmission Shafts, Shaft materials		Introduction to Bearings, Types of Rolling Contact Bearings		Introduction to Mechanical Drives, Types of Gears, Gear materials, Gear Nomenclature		Types of Flexible Drives, Belt Materials and Constructions															
	SLO-2	Equilibrium and Free Body Diagram		Shaft Layouts and Shaft design for stress		Selection of Bearing Type, Static and Dynamic Load Carrying capacity, Equivalent Bearing Load		Contact Ratio, Interference, Undercutting and Backlash		Mechanics of Belt Drives, Selection of Belt Drives, Belt Tension															
S-2	SLO-1	Direct, Bending and torsional stresses		Practice 11: Problems on Design of Shaft on Strength basis		Load –Life Relationship, Selection of Ball Bearing Life		Force Analysis-Spur Gear		Flat Belt Drive															
	SLO-2	Practice1: Problems on Bending and Torsional stresses		Practice 15: Problems on Single Row Deep Groove Ball Bearing		Design of spur gear based on Lewis and Buckingham equations		Practice 28: Problems on Design of Flat Belt Drive																	
S-3	SLO-1	Stresses for Various Load Combinations		Practice 12 Problems on Design of Shaft on Torsional Rigidity basis		Selection of Taper Roller Bearings		Practice 22: Problems on Spur Gear Design Based on Lewis and Buckingham Equations		V- Belt Drive															
	SLO-2	Practice 2:Problems on Various Machine Members Subjected to Various Load Combinations		Practice 16: Problems on Taper Roller Bearings		Practice 23: Problems on Spur Gear Design Based on Lewis and Buckingham Equations		Practice 29: Problems on Design of V- Belt Drive																	
S-4	SLO-1	Eccentric Loading		Design of Hallow Shaft		Design for Cyclic Loads and Speeds		Practice 23: Problems on Spur Gear Design Based on Lewis and Buckingham Equations		Practice 30: Problems on Design of V- Belt Drive															
	SLO-2	Practice 3:Problems on Various Machine Members Subjected to Eccentric Loading		Practice 13: Problems on Design of Hallow Shaft on Strength and Torsional Rigidity basis		Practice 17: Design of Ball Bearings subjected to Cyclic Loads and Speeds																			
S-5	SLO-1	Lab 1: Part Modelling of a Mechanical Component using CAD tool		Lab 4: Part Modelling of a Universal Coupling and its Assembly using CAD tool		Lab 7: Part Modelling of a Screw Jackand its Assembly using CAD tool		Lab 10: Stress Analysis of an Axis-Symmetric Component using ANSYS		Lab 13: Convective Heat Transfer Analysis of a 2D Component using ANSYS															
S-6	SLO-1	Factor of safety for Brittle and Ductile Materials		Spring Materials,Stresses in Helical Springs		Types of Lubrication, Viscosity Index, Petroff's Equation		Helical Gear Nomenclature		Chain Drive: Types, Failures, Designation															
	SLO-2	Significance of Factor of Safety in Machine Design		Curvature Effect, Deflection, Compression Springs, Stability		Stable and Thick-Film Lubrication		Force Analysis- Helical Gear		Selection of Chain Drive, Chain Lubrication															
S-7	SLO-1	Theories of failure		Helical Compression Spring Design Against Static Load		Design Considerations		Design of helical gear based on modified Lewis equations		Design of Chain Drive															

	SLO-2	Practice 4: Problems on Theory of failure	Practice 14: Problems on Design of Helical Spring Subjected to Static Load	Hydrostatic Step Bearing and its Energy Losses		Practice 31: Problems on Design of Chain Drive to run a Compressor
S-8	SLO-1	Introduction to Fracture Mechanics, and Fatigue in Metals	Helical Compression Spring Design- Trial and Error method	Practice 18: Problems on Hydrostatic Thrust Bearings	Practice 24: Problems on Helical Gear Design Based on Lewis Equations	Practice 32: Problems on Design of Chain Drive Power Transmission Shaft Applications
	SLO-2	S-N Curve, Fatigue Strength and the Endurance Limit	Practice 14: Problems on Design of Helical Spring based on Trial and Error Method			
S-9	SLO-1	Endurance Limit Modifying Factors, Stress Concentration and Notch Sensitivity	Helical Compression Spring Design Against Fatigue Load	Practice 19: Problems on Hydrostatic Step Bearings	Practice 25: Problems on Helical Gear Design Based on Modified Lewis Equations	Practice 33: Problems on Design of Chain Drive for Drilling Machine Applications
	SLO-2	Practice 6: Problems on Stress Concentration Factors	Practice 14: Problems on Design of Helical Spring Subjected to Fatigue Load			
S-10	SLO-1	Lab 2: Part Modelling of a Mechanical Component using CAD tool	Lab 5: Part Modelling of a Plummer Block and its Assembly using CAD tool	Lab 8: Stress Analysis of Truss using ANSYS	Lab 11: Stress Analysis of Beams (Cantilever, Simply supported, Fixed ends) using ANSYS	Lab 14: Modal analysis of Spring-Mass system using ANSYS
	SLO-2					
S-11	SLO-1	Practice 7: Infinite Life for Machine Member Subjected to Reversed Load	Design of Keys	Hydrodynamic Theory	Bevel Gear and Its Types	Wire Rope - Types, Construction, Lays of Wire Rope
	SLO-2	Practice 8: finite Life for Machine Member Subjected to Reversed Load	Practice 15: Problems on Design of Keys	Sommerfeld Number, Raimondi and Boyd method	Bevel Gear Nomenclature	Failures in Wire Rope
S-12	SLO-1	Soderberg and Goodman lines, Modified Goodman Diagram,	Design of rigid Flange Coupling	Temperature Rise, Bearing Construction, Bearing Materials	Force Analysis- Bevel Gear	Selection of Wire Rope, Stresses in Wire Rope
	SLO-2	Design for Variable Loading	Practice 16: Problems on Flange Coupling	Selection of Lubricants, Bearing failures	Design of bevel gear based on Lewis and Buckingham equations.	Design of a Wire Rope Drive for Crane Applications
S-13	SLO-1	Practice 9: Problems on Infinite Life for Machine Member Subjected to Fluctuating Load	Design of Flexible Flange Coupling	Practice 20: Problems on Hydrodynamic Bearings	Practice 26: Problems on Bevel Gear Design Based on Lewis and Buckingham Equations	Practice 34: Problems on Expected life of Wire Rope under Dynamic Conditions
	SLO-2	Practice 10: Problems on Finite Life for Machine Member Subjected to Fluctuating Load	Practice 16: Problems on Flexible Bushed Pin Flange Coupling			
S-14	SLO-1	Practice 10: Problems on Finite Life for Machine Member Subjected to Fluctuating Load	Practice 17: Problems on Flexible Bushed Pin Flange Couplings	Practice 21: Problems on Hydrodynamic Bearings	Practice 27: Problems on Bevel Gear Design Based on Lewis and Buckingham Equations	Practice 35: Problems on Factor of Safety of Wire Rope under Static Conditions
	SLO-2					
S-15	SLO-1	Lab 3: Part Modelling of a Flange Coupling and its Assembly using CAD tool	Lab 6: Part Modelling of a Knuckle Joint and its Assembly using CAD tool	Lab 9: Stress Analysis of a Plate with a Circular hole using ANSYS	Lab 12: Conductive Heat Transfer Analysis of 2D Component using ANSYS	Lab 15: Model Practical Exam
	SLO-2					

Learning Resources	1. Bhandari.V.B, "Design of Machine Elements", 3 rd ed., Tata McGraw-Hill, 2010.	5. Merhyle Franklin Spotts, Terry E. Shoup and Hornberger.L.E, "Design of Machine Elements", 8 th ed., Prentice Hall, 2003 6. Joseph Shigley and Charles Mischke, "Standard Handbook of Machine Design", 3 rd ed., Tata McGraw Hill, 2004. 7. Richard G.Budynas, J.Keith Nisbett, "Shigley's Mechanical Engineering Design", 10 th ed., Tata McGraw-Hill, 2015.
	2. Robert L. Norton, "Machine Design: An Integrated Approach", 5 th ed., Prentice Hall, 2013. 3. PSG, "Design Data" [Data Book Of Engineers], Kalaikathir Achagam, 2016. 4. CAD Laboratory Manual.	

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		100%	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry		Experts from Higher Technical Institutions
1. Mr.Kesavan Raja Ramasamy, Schlumberger, RK Raja@slb.com		1. Dr.L.Ranganathan, Jeppiaar Engineering College, Chennai, ranganathan1975@gmail.com
2. Mr. S.Jagadeeswaran, Renault Nissan Technology and Business Centre, jagadeeswaran.selvamani@mtbci.com		2. Dr.K.Ramanathan, Alagappa Chettiar Government college of Engineering and Technology, ramsananthi@gmail.com
		Internal Experts
		1. Mr.M.Chandrasekaran, SRMIST
		2. Mr.S.M.Vignesh, SRMIST

Course Code	18MHC204T	Course Name	POWER ELECTRONICS AND DRIVES	Course Category	C	Professional Core	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18MHC102T, 18MHC103T	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechatronics Engineering	Data Book / Codes/Standards	-		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Identify different power semiconductor devices and utilize them in different converter circuits	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Utilise single phase and three phase converters and Choppers	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Utilise single phase and three phase inverters, AC Voltage regulators and cycloconverters																		
CLR-4 :	Apply converters and choppers to drive DC motors																		
CLR-5 :	Apply Inverters, voltage Regulators and cycloconverters to drive AC motors																		
CLR-6 :	Utilise Power Semiconductor devices for converter circuits, operate DC and AC drives using converters																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Analyze various power semiconductor devices used in Power converters	3	75	70	H	-	H	L	M	-	M	M	M	M	-	M	-	-	-
CLO-2 :	Identify working principle of controlled Rectifiers and Choppers	3	75	70	H	M	H	H	M	-	M	M	M	M	-	M	-	-	-
CLO-3 :	Identify working principle of Inverters and Cycloconverters	3	75	70	H	M	H	H	M	-	M	M	M	M	-	M	-	-	-
CLO-4 :	Operate DC drives using controlled rectifiers and choppers	3	75	70	H	-	M	H	M	-	M	M	M	M	-	M	-	-	-
CLO-5 :	Operate AC drives using Inverters and Cycloconverters	3	75	70	H	-	M	H	M	-	M	M	M	M	-	M	-	-	-
CLO-6 :	Identify power semiconductor devices, controlled rectifiers, choppers, inverters, cycloconverters for operating electric drives.	3	75	70	-	-	M	M	M	-	M	M	M	M	-	M	-	-	-

		Semiconductor Devices	Controlled Rectifiers and Choppers	Inverters and AC Chopper	DC Drives	AC Drives
Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction to power semiconductor devices.	Introduction to controlled rectifiers	Introduction to inverters	Drives: Introduction	Induction motor fundamentals
	SLO-2	Basic structure and operation of power diode, Types of power diode	Types of controlled rectifiers	Types of inverters.	Electric Drives: Classification	Types of Induction motor
S-2	SLO-1	Basic structure and operation of power transistor	Operation of single phase fully controlled rectifier with R load	Operation of 1- phase voltage source inverter.	Classes of Duty	Speed control of Induction motor : Types
	SLO-2	Basic structure and operation of SCR	Operation of single phase fully controlled rectifier with RL load		Fundamentals of DC motor	Stator voltage control.
S-3	SLO-1	Characteristics and applications of SCR	Operation of single phase fully controlled rectifier with RLE load	Operation of 3 - phase voltage source inverter: 180° mode VSI	Speed control of DC motor : Armature control	Variable frequency control.
	SLO-2	Basic structure and operation of GTO	Operation of single phase half controlled rectifier with RLE load		Speed control of DC motor: Field control.	VSI fed Induction motor drive
S-4	SLO-1	Basic structure and operation of TRIAC.	Operation of three phase half wave controlled rectifier with R load for continuous current.	Operation of 3 - phase voltage source inverter: 120° mode	Operation of Ward Leonard drives.	Rotor resistance control.
	SLO-2	Characteristics and applications of TRIAC.	Operation of three phase fully controlled rectifier with R load for continuous current.	Operation of 3 - phase current source inverter		Static Rotor resistance control
S-5	SLO-1	Basic structure and operation of MOSFET	Operation of three phase fully controlled rectifier with RL load for continuous current.	Types of ac voltage control: Phase control.	Converter fed DC drive: Types, Quadrant operation	Slip power recovery scheme: Static Kramers Scheme
	SLO-2	Characteristics and applications of MOSFET	Dual Converter	Types of ac voltage control: Integrated cycle control.	Fully controlled converter fed drive	Static Scherbius Scheme
S-6	SLO-1	Basic structure and operation of IGBT	Operation of choppers. Classification of choppers	Operation of 1- phase voltage regulator	Semi-converter controlled converter fed drive	Fundamentals of synchronous motor
	SLO-2	Characteristics and applications of IGBT	Control strategies: Methods and Operation	.	Speed torque characteristics	Types of synchronous motor

S-7	SLO-1	Triggering methods for SCR	Operation of A, B types of chopper.	Operation of 3 - phase AC voltage controls: With anti parallel SCR configuration, with R load operation.	Chopper fed DC drive: types	Open loop control.
	SLO-2		Operation of C type of chopper.		Chopper fed DC drive: operation	Closed loop control.
S-8	SLO-1	Commutation techniques for SCR.	Operation of D type of chopper.	1-phase cyclo-converters: Introduction	Four quadrant operation of dc drive	Variable frequency control: Methods
	SLO-2		E type of chopper.	1-phase cyclo-converters: Types		
S-9	SLO-1	Firing circuits of SCR: R, RC and UJT Firing circuits	Multiphase chopper	1-phase step up cyclo-converters	Closed loop control	Voltage source fed synchronous motor.
	SLO-2		Applications of choppers.	1-phase step down cyclo-converters		Current source fed synchronous motor.

Learning Resources	1. Bhimbra. Dr.P.S., "Power Electronics", Khanna Publishers, 2012.	5. Pillai.S.K., "A first course on Electrical Drives", New Age International (P)Ltd., 2012.
	2. Dubey.G.K., "Fundamentals of Electrical Drives", Narosa publishing house 2001.	
	3. Muhammad H. Rashid, "Power Electronics - Circuits, Devices and Applications", Prentice Hall of India, New Delhi, 2003.	6. Dubey.G.K., "Power Semiconductor Controlled Drives", Narosa publishing house, 1995.
	4. Singh. M.D and Khanchandani. K.B., "Power Electronics", Tata McGraw Hill Publishing Co. Ltd., New Delhi, 2000.	
		7. Dubey. G.K., "Thyristorised Power Controllers", New Age International (P) Publishers Ltd., 2002.

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100%	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry		Experts from Higher Technical Institutions
1. Mr. D.Gokulakrishnan, Planning Engineer, ABB India Ltd, Oman, gokul@tisonan.com		1. Dr.S.S Dash, Government College of Engineering Keddhar, Orisha, munu_dash_2k@yahoo.com
2. Mrs.T.Priya, Sr.Design Engineer, Electrical&Instrumentation,Kavin Engineering and Services Pvt Ltd, priya@kavinengg.com		2. Dr.M.Jagadeeshkumar, Sri SaiRam Institute of Technology, jagadeeshkumar.eee@sairamit.edu.in
		Internal Experts
		1. Dr.M.Santhosh Rani, SRMIST
		2. Mrs.V.Krithika, SRMIST

Course Code	18MHC205J	Course Name	MICROCONTROLLERS AND EMBEDDED SYSTEMS			Course Category	C	Professional Core			L	T	P	C																																																																																																																	
											3	0	2	4																																																																																																																	
Pre-requisite Courses		18MHC108J	Co-requisite Courses		Nil	Progressive Courses		Nil																																																																																																																							
Course Offering Department		Mechatronics Engineering			Data Book / Codes/Standards		Nil																																																																																																																								
Course Learning Rationale (CLR):		The purpose of learning this course is to:			<table><tr><th colspan="3">Learning</th></tr><tr><th>1</th><th>2</th><th>3</th></tr><tr><td rowspan="5">Level of Thinking (Bloom)</td><td rowspan="5">Expected Proficiency (%)</td><td rowspan="5">Expected Attainment (%)</td><td rowspan="5">Engineering Knowledge</td><td rowspan="5">Problem Analysis</td><td rowspan="5">Design & Development</td><td rowspan="5">Analysis, Design, Research</td><td rowspan="5">Modern Tool Usage</td><td rowspan="5">Society & Culture</td><td rowspan="5">Environment & Sustainability</td><td rowspan="5">Ethics</td><td rowspan="5">Individual & Team Work</td><td rowspan="5">Communication</td><td rowspan="5">Project Mgt. & Finance</td><td rowspan="5">Life Long Learning</td><td rowspan="5">PSO - 1</td><td rowspan="5">PSO - 2</td><td rowspan="5">PSO - 3</td></tr><tr></tr><tr></tr><tr></tr><tr></tr></table>			Learning			1	2	3	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3																																																																																																
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CLR-1 :	Familiarize with the functionality of microcontrollers.																																																																																																																														
CLR-2 :	Understand the concepts of microcontroller and its applications to mechatronics systems.																																																																																																																														
CLR-3 :	Understand the fundamentals of embedded systems design with real time system.																																																																																																																														
CLR-4 :	Develop programming skill to design in embedded C.																																																																																																																														
CLR-5 :	Apply knowledge to real-world application.																																																																																																																														
CLR-6 :	To impart knowledge of embedded system and microcontroller programming.																																																																																																																														
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			<table><tr><td>CLO-1 :</td><td>Demonstrate an understanding with the functionality of microcontrollers</td><td>2</td><td>85</td><td>80</td><td>H</td><td>-</td><td>-</td><td>M</td><td>-</td><td>-</td><td>-</td><td>-</td><td>H</td><td>-</td><td>-</td><td>H</td><td>-</td><td>-</td><td>-</td></tr><tr><td>CLO-2 :</td><td>Apply the concepts of microcontroller and its applications to mechatronics systems</td><td>1</td><td>85</td><td>80</td><td>H</td><td>-</td><td>-</td><td>M</td><td>-</td><td>-</td><td>-</td><td>-</td><td>H</td><td>-</td><td>-</td><td>H</td><td>-</td><td>-</td><td>-</td></tr><tr><td>CLO-3 :</td><td>Apply the fundamentals of embedded systems design with real time system.</td><td>1</td><td>85</td><td>80</td><td>H</td><td>H</td><td>H</td><td>H</td><td>-</td><td>-</td><td>-</td><td>-</td><td>H</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td></tr><tr><td>CLO-4 :</td><td>Able to program and design using embedded C</td><td>2</td><td>85</td><td>80</td><td>H</td><td>-</td><td>H</td><td>H</td><td>M</td><td>-</td><td>-</td><td>-</td><td>H</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td></tr><tr><td>CLO-5 :</td><td>Demonstrate the application of knowledge to real world application</td><td>2</td><td>85</td><td>80</td><td>H</td><td>-</td><td>H</td><td>H</td><td>M</td><td>-</td><td>-</td><td>-</td><td>H</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td></tr><tr><td>CLO-6 :</td><td>Demonstrate an understanding on the concept of embedded system and microcontroller programming</td><td>2</td><td>85</td><td>80</td><td>H</td><td>H</td><td>H</td><td>H</td><td>M</td><td>L</td><td>M</td><td>L</td><td>H</td><td>L</td><td>M</td><td>H</td><td>-</td><td>-</td><td>-</td></tr></table>			CLO-1 :	Demonstrate an understanding with the functionality of microcontrollers	2	85	80	H	-	-	M	-	-	-	-	H	-	-	H	-	-	-	CLO-2 :	Apply the concepts of microcontroller and its applications to mechatronics systems	1	85	80	H	-	-	M	-	-	-	-	H	-	-	H	-	-	-	CLO-3 :	Apply the fundamentals of embedded systems design with real time system.	1	85	80	H	H	H	H	-	-	-	-	H	-	-	-	-	-	-	CLO-4 :	Able to program and design using embedded C	2	85	80	H	-	H	H	M	-	-	-	H	-	-	-	-	-	-	CLO-5 :	Demonstrate the application of knowledge to real world application	2	85	80	H	-	H	H	M	-	-	-	H	-	-	-	-	-	-	CLO-6 :	Demonstrate an understanding on the concept of embedded system and microcontroller programming	2	85	80	H	H	H	H	M	L	M	L	H	L	M	H	-	-	-
CLO-1 :	Demonstrate an understanding with the functionality of microcontrollers	2	85	80				H	-	-	M	-	-	-	-	H	-	-	H	-	-	-																																																																																																									
CLO-2 :	Apply the concepts of microcontroller and its applications to mechatronics systems	1	85	80				H	-	-	M	-	-	-	-	H	-	-	H	-	-	-																																																																																																									
CLO-3 :	Apply the fundamentals of embedded systems design with real time system.	1	85	80				H	H	H	H	-	-	-	-	H	-	-	-	-	-	-																																																																																																									
CLO-4 :	Able to program and design using embedded C	2	85	80				H	-	H	H	M	-	-	-	H	-	-	-	-	-	-																																																																																																									
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		Microcontroller 8051	ARM7 Controller	Introduction to Embedded Systems	Computing Platform and Design Analysis	Real Time Operating System
Duration (hour)		15	15	15	15	15
S-1	SLO-1	Microcontroller 8051	ARM7 Controller	Definition, Key Elements Of An Embedded System.	DebuggingTechniques/ Challenges	Arbitration Schemes
	SLO-2	Architecture	Architecture	Design Metric Challenges		Software Architectures
S-2	SLO-1	Pin Description	Functional Description	Cpu Buses	Program Design And Analysis	Round Robin
	SLO-2	FunctionalDescription		Memory Devices, I/O Device	Components For Embedded Programs	Round Robin With Interrupt
S-3	SLO-1	Instruction Set Of 8051 Microcontroller.	ARM State Instruction	Component Interfacing	Model Of Programs	Function Queue Scheduling, Limitations Of Non-RTOS Embedded Systems
	SLO-2	Arithmetic Group	Data Transfer Instruction	Design With Microprocessors	DFG, CDFG	Introduction To RTOS And Its Features
S-4	SLO-1	Arithmetic Operations Using 8051	Arithmetic Operations Using ARM7	Stepper Motor Interface Using Microcontroller.	Keyboard Display Interface Using Microcontroller	Traffic Light Control Interface Using Microcontroller
	SLO-2			Logical Group	Data Processing Instruction	Processor Technology
S-6	SLO-1	Data Transfer Group	Thumb State Instruction	General Purpose Processors	Basic Compilation Techniques	IssuesIn SDP
	SLO-2	Boolean Group	Data Transfer Instruction	Custom Single Purpose Processors	Program Optimization	SolutionsOf Shared Data Problem
S-7	SLO-1	Branching Group	Data Processing Instruction	Application Specific Integrated Circuits	Performance Analysis - System Level & Program Level	Semaphores – Introduction
	SLO-2	Addressing Modes	Addressing Modes	IC Technology		Multiple Semaphores; Reentrancy
S-8	SLO-1	Counting Odd And Even Numbers Using 8051 Microcontroller	Code Conversion Using ARM7	ADC Interfacing Using Microcontroller	PWM Interfacing UsingMicrocontroller	Repeat Session
	SLO-2					
S-11	SLO-1	Assembly Language Programming	Branch, SWI, PSR Instructions	VLSI	Optimization- Performance, Energy	Semaphores & Shared Data Problem
	SLO-2	Mnemonics, Op Code	Loading Constants, Conditional Execution	FPGA	Optimization – Power, Program Size	Semaphores As A Signaling Device
S-12	SLO-1	Programming Of 8051 Using Assembly Language	Programming Of ARM7Using Assembly Language	Design Technology	Program Validation	Operating System Services
	SLO-2			Hardware / Software Co-Design	TestingOf Program	Queues , Mailbox
S-13	SLO-1	Programming Of 8051 Using Assembly Language	Programming Of ARM7 Using Assembly Language	Integrated Development Environments	Interrupts	Pipes , Timer Functions
	SLO-2			Tool Chains	Interrupt Latency	Events
S-14-15	SLO-1	Timer/Counter Programs Using 8051 Microcontroller	Timer/Counter Programs Using ARM7 Controller	DAC Interfacing Using Microcontroller	LED Display Using Microcontroller	Repeat Session
	SLO-2					

Learning Resources	1. Frank Vahid and Tony Givargis, "Embedded system design: A unified hardware/ software approach", Pearson Education Asia, 3rd edition, 2009.	4. Steve Furber, "ARM System-on-chip Architecture", Pearson education, India, 2000. 5. David E.Simon , "An Embedded Software Primer", Pearson Education Asia 2001 6. Joseph Yiu, "The Definitive Guide to ARM Cortex Processors", 3rd edition, Newnes Publication 7. Microcontroller And Embedded Systems Laboratory Manual.
	2. Wayne Wolf, "Computers as components - Principles of Embedded computing system design", 2nd edition, MK Publishers.	
	3. Mazidi and Mazidi , "Intel 8051 Microcontrollers", Pearson education, India, 2006.	

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		100%	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.A.Rajasekar, CCG-RVP,rajasekar.a@intel.com	1. Dr.BamaSrinivasan, Anna University, Guindy, Chennai, bama@annauniv.edu	1. Mrs.T.S.Rajalakshmi, SRMIST
2. Mr. Reuben Fernandes, ATOM 360, India, wenisch@atom360.io	2. Dr.K.Rahimunnisa, EashwariEngineering College, Chennai, krahimunnisa@gmail.com	2. Ms.Cross T AshaWise SRMIST

Course code	18MHC301J	Course name	MANUFACTURING PROCESSES				Course category	P	Professional core				L	T	P	C							
													3	0	2	4							
Pre-requisite courses		Nil		Co-requisite courses		Nil		Progressive courses		Nil													
Course offering department		Mechatronics engineering				Data book / codes/standards			Nil														
Course Learning Rationale (CLR):		The purpose of learning this course is to:				Learning 1 2 3 Level of Thinking (Bloom) Expected Proficiency (%) Expected Attainment (%)			Program Learning Outcomes (PLO)														
CLR-1 :	understand the principle and process of different metal forming process				1				2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLR-2 :	Impart knowledge on types and approaches of metal cutting process.				Engineering Knowledge				Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3	
CLR-3 :	Gain knowledge in concept of computerized machine tool for metal cutting process.				H				H	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLR-4 :	Understand the concept of additive manufacturing process.				H				-	H	-	H	-	-	-	-	-	-	-	-	-	-	-
CLR-5 :	familiar in manufacturing metrology				H				-	-	H	-	-	H	-	-	-	-	-	-	-	-	-
CLR-6 :	implement knowledge of manufacturing processes and manufacturing metrology				H				H	H	H	-	-	H	-	-	-	-	-	-	-	-	-
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:				Level of Thinking (Bloom) Expected Proficiency (%) Expected Attainment (%)			Program Learning Outcomes (PLO)														
CLO-1 :	Explain the process of different metal forming process.				1				85	80	H	H	-	-	-	-	-	-	-	-	-	-	-
CLO-2 :	Distinguish the types and approaches of metal cutting process.				1				85	80	H	H	-	-	-	-	-	-	-	-	-	-	-
CLO-3 :	Implement the concept of computerized machine tool for metal cutting process.				1				85	80	H	-	H	-	H	-	-	-	-	-	-	-	-
CLO-4 :	Understand the concept of additive manufacturing process.				2				85	80	H	-	-	H	-	-	H	-	-	-	-	-	-
CLO-5 :	acquire knowledge on manufacturing metrology				2				85	80	H	H	-	H	-	-	-	-	-	-	-	-	-
CLO-6 :	impart knowledge of manufacturing processes and manufacturing metrology				2				85	80	H	H	H	H	-	-	H	-	-	-	-	-	-
Duration (hour)	15		15		15		15		15														
S-1	SLO-1	Casting process: introduction	Introduction to metal cutting processes	CNC machine tools	Additive manufacturing: concept, types.	Introduction to manufacturing metrology																	
	SLO-2	Classification of casting process.	Cutting tools	NC machines	Fused deposition method: working principle,	Laser metrology and precision instruments																	
S-2	SLO-1	Mould and its types.	Classification: single point cutting tool nomenclature	DNC machines	Advantages, limitations, applications.	Types of lasers – laser in engineering metrology																	
	SLO-2	Pattern: types of pattern	Multi point cutting tool nomenclature	CNC machines: introduction	Selective laser sintering process	Metrological laser methods for applications in machine systems																	
S-3	SLO-1	Special casting techniques	Tool wear	Classification of CNC machines.	Working principle, advantages, limitations,	Interferometry applications – speckle interferometry																	
	SLO-2	Expandable mould casting	Tool life, Prediction of tool life	Constructional feature of CNC turning centre and	Applications.	Laser interferometers in manufacturing and machine tool alignment testing																	
S-4	SLO-1	Lab – 1: Machining of spur gear using universal milling machine.	Lab – 4: Manufacturing a single point cutting tool using tool and cutter grinder.	Lab - 6 :Multiple turning with grooving and thread cutting by applying canned cycle using CNC turning centre	Lab – 9: Profile cutting by applying Mirroring operation using CNC vertical machining centre.	Lab – 11: Profile cutting using Wire cut Electrical Discharge Machine (WEDM).																	
	SLO-2																						
S-6	SLO-1	Investment casting , Shell mould casting,	Orthogonal and oblique cutting	CNCmachining centre.	Stereo lithography process: working principle,.	Introduction to co-ordinate measuring system																	
	SLO-2	Permanent mould casting.	Mechanics of orthogonal cutting using single point cutting tool	Open loopCNC systems, closed loop CNC systems	Advantages, limitations, applications	Co-ordinate metrology																	
S-7	SLO-1	Die casting and its types	Cutting forces in orthogonal cutting, merchant circle analysis.	CNC controllers.	3d printing technique: working process,	CMM configurations , hardware components – software																	
	SLO-2	Centrifugal casting and its types	Calculation of various forces involved during orthogonal cutting.	Structural members of CNC machines: slide ways, linear motion	Advantages, limitations, applications.	Probe sensors – displacement devices –																	
S-8	SLO-1	Defects in casting.	Problem solving	Bearings, ball screws	PCB manufacturing process: silicon wafer production process	Performance evaluations, applications																	
	SLO-2	Mechanical working of metals	Methods to gear generation:	Work holding, tool holding devices,	Diffusion, masking.	Roll of CMM in reverse engineering																	

S 9-10	SLO-1 SLO-2	Lab – 2: Machining of helical gear using gear hobbing machine.	Gear shaping	Lab – 7: Step turning using CNC turning centre.	Lab – 10: Drilling and peck drilling using CNC vertical machining centre.	Lab – 12: Pocketing of Linear and Circular profile using CNC vertical machining centre.
S-11	SLO-1 SLO-2	Rolling process, Mechanism, types and defects of rolling. Joining Process- Welding techniques- Conventional and special Techniques	Milling Hobbing process.	Automatic tool changer. Feedback devices used in machining centre	Photolithography technique. Etching, cleaning,	Opto electronic devices Ccd, on-line and in-process monitoring in production
S-12	SLO-1 SLO-2	Joining Process- Soldering and Brazing Forging: mechanism Types, machine used for forging, defects.	Grinding: cylindrical, surface Centreless grinding process.	fundamentals of part programming, G and m codes.	. Types of pcb: single sided, double sided, Multilayer pcb board	Applications. Image analysis and computer vision
S-13	SLO-1 SLO-2	Extrusion: mechanism, classification, defects. Drawing: mechanism, tube drawing, deep drawing, defects.	Super finishing: lapping. Honing, buffing.	. Types of programming: manual part programming, Canned cycle and subroutines.	flexible PCB board Inspection of PCB boards.	image analysis techniques Comparison laser scanning with vision system
S 14-15	SLO-1 SLO-2	Lab - 3 : Facing, turning and thread cutting using conventional lathe	Lab - 5 :Finishing operation using cylindrical and surface grinding process.	Lab – 8 :Multiple turning by applying canned cycle using CNC turning centre.	Lab – 13: Extra practice session.	Lab – 14 :Model Examination

Learning Resources	<ol style="list-style-type: none"> Sharma.P.C, "A textbook of Production Technology", Vol I and II, S. Chand And Company Ltd., New Delhi, 2007. SeropeKalpakjian and Steven Schmid, "Manufacturing Engineering and Technology", Pearson Education, 7th edition, 2014. Radhakrishnan.P, "CNC Machines", New Central Book Agency, 2000. Pandey and H.S.Shah, "Modern Machining Process", Tata McGraw Hill Publishing Co., New Delhi, 2008. Chua C.K., Leong K.F., and Lim C.S., "Rapid prototyping: Principles and applications", 3rd edition, World Scientific Publishers, 2010. R. S. Khandpur "Printed Circuit Boards: Design, Fabrication, and Assembly" Tata McGraw Hill Publishing Co., New Delhi, 2010. 	<ol style="list-style-type: none"> S.K. HajraChoudry, S.K.Bose, A.K. HajraChoudry, "Elements of Workshop Technology Vol II: Machine tools", Media promoters and Publishers Pvt Ltd, 2002. Chapman.W.A.J, "Workshop Technology" Vol. I and II, Arnold Publisher, 1996. Elanchezian.C, VijayaRamnath.B and Sunder Selwyn, T., Engineering Metrology, Eswar Press, Chennai, 2004. John A. Bosch, Giddings and Lewis Dayton, Co-ordinate Measuring Machines and Systems, Marcel Dekker, Inc, 1999 ZuechNello, Understanding and Applying Machine Vision, Marcel Dekker, Inc, 2000
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
Level 2	Apply Analyze	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
Level 3	Evaluate Create	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.K.Balaguru, Deputy manager, Hindustan Aeronautics limited, Structural Design, gurubala07@gmail.com	1. Dr.v. Senthikumar, NIT Tiruchirappalli, Production department, vskumar@nitt.edu	1. Dr.B.K. Vinayagam, SRMIST
2. Mr. HariPrabhu, Junior Engineer, Indian Railways, Egmore, hpvijay5894@gmail.com	2. Dr. R. Sarala, AlagappaChettiar college of Engineering and Technology, Manufacturing department, r.sarala@accet.edu.in, karaikudi.	2. Mr. J.Arivasan, SRMIST

[illegible]

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand the design challenges involved in multidisciplinary modern machines	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Familiarize the mechatronics approach design process and its benefit	(Bloom) Knowledge Competency (%)		Assessment (%)	1 Knowledge	2 Skills	3 Assessment	4 Research	5 Design	6 Analysis	7 Sustainability	8 Communication	9 Team Work	10 Management	11 Innovation	12 Leadership	13 Ethics	14 Social Responsibility	15 Global Awareness
CLR-3 :	Understand the various simulation methods and its importance																		
CLR-4 :	Understand the importance of modeling and model based design																		
CLR-5 :	Understand and apply the mechatronics design approach for various real systems																		

		Introduction to mechatronic system design	Mechatronics design concepts	Model based system engineering	Case Study-1	Case Study-2
Duration (hour)		15	15	15	15	15
S-1	SLO-1	Definition of mechatronics	Significance of modeling	Motivation for model based system engineering (MBSE)	Need of model based design for the system under consideration	Need of model based design for the system under consideration
	SLO-2	Evolution of mechatronics systems	Example	System engineering process	Benefits of model based design	Benefits of model based design
S-2	SLO-1	Multidisciplinary nature of modern machines and their design challenges	Model-In-Loop(MIL) simulation	System lifecycle	Understanding the system under consideration	Understanding the system under consideration
	SLO-2	Example	Example	Types of systems	Mechanical and electronics description	Mechanical and electronics description
S-3	SLO-1	Traditional vs mechatronics approaches	Software-In-Loop(SIL) simulations	Modeling ,analysis and management of system requirements	Mathematical description of the model	Mathematical description of the model
	SLO-2	Example	Example	Modeling ,analysis and management of system requirements	Mathematical modeling- derivation	Mathematical modeling- derivation
S 4-5	SLO-1	Lab 1	Lab 4	Lab 7	Lab 10	Lab 13
	SLO-2					
S-6	SLO-1	Mechatronics design process	Virtual Prototyping- a critical aspect of mechatronics approach	Structural modeling using SysML	Detailed modelling procedures and simulation parameters.	Detailed modelling procedures and simulation parameters.
	SLO-2	Need of design tools integration	Example	Structural modeling using SysML	Simulation methods	Simulation methods
S-7	SLO-1	Review of key elements of mechatronics systems from integration perspective	Real-time simulations (xPC)	Behavioral modeling using SysML	Key integration issues specific to the system under consideration	Key integration issues specific to the system under consideration
	SLO-2	Example	Example	Behavioral modeling using SysML	Key integration issues specific to the system under consideration	Key integration issues specific to the system under consideration
S-8	SLO-1	Role of mechatronics engineer.	concurrent development of subsystems	Identifying complexities through different levels of abstractions and refinement	System integration	System integration
	SLO-2	Various steps for design	Example	Identifying complexities through different levels of abstractions and refinement	System integration	System integration
S 9-10	SLO-1	Lab 2	Lab 5	Lab 8	Lab 11	Lab 14
	SLO-2					

S-11	SLO-1	Types of design (mechatronics approach)	Real-time Hardware-In-Loop simulation (HIL)	Adding constraints	Control techniques adopted	Control techniques adopted
	SLO-2	Example	Example	Interaction diagrams	Related Control theory	Related Control theory
S-12	SLO-1	integrated product design	Running the controller model and plant model on real-time target	Automatic approach for synergistic verification and validation	Selection of hardware components based on the model based design	Selection of hardware components based on the model based design
	SLO-2	load conditions on mechanisms	V&V using HIL RT model.	Automatic approach for synergistic verification and validation	Selection of hardware components based on the model based design	Selection of hardware components based on the model based design
S-13	SLO-1	Structure and systems	Rapid prototyping of mechatronic products- introduction to precision engineering	Performance analysis	System performance evaluation techniques	System performance evaluation techniques
	SLO-2	Man Machine Interface (MMI).	Example	Performance analysis	System performance evaluation techniques	System performance evaluation techniques
S 14-15	SLO-1	Lab 3	Lab 6	Lab 9	Lab 12	Lab 15: Model Practical Examination

Note: ** List of plants/systems for case study 1,2 and 3 is listed below in the table. Faculty may choose any one plant/system from the list given and continue the same system/plant for the entire case study module

** List of experiments for the lab slots is listed below in the table for mechatronics as well as mechatronics with robotics specialization. Faculty in-charge may choose from the list of experiments to be provided for the various lab slots

LIST OF PLANTS/SYSTEMS FOR CASE STUDIES		
CASE STUDY 1	CASE STUDY 2	CASE STUDY 3
Rotary Inverted pendulum	Hybrid Electric Vehicle	Six Degree of freedom serial manipulator
Inverted pendulum on a cart with rotary actuator	Electronic Stability Control (ABS, EBD and ESP)	Six Degree of freedom parallel manipulator
Inverted pendulum with Linear Actuator	Active Suspension	Collision avoidance in mobile robotic systems
Double inverted pendulum	Engine Control System	Multi-rotor aerial vehicles
Ball and Plate Control Systems	Systems for Passenger Safety and Convenience	Haptics based teleoperation of manipulators
Two wheeled Self Balancing Mobile Robot	Cruise control	Cooperative manipulators
Magnetically levitated Systems		Underwater vehicles

LIST OF EXPERIMENTS FOR LABORATORY EXERCISE FOR MECHATRONICS AND MECHATRONICS WITH ROBOTICS SPECIALIZATION	
MECHATRONICS	MECHATRONICS WITH ROBOTICS SPECIALIZATION
Quadrature decoding of incremental encoder	Quadrature Encoder Decoding for Position and Velocity Estimation of a DC Servo Motor
Closed loop position control of DC motor	Mathematical modeling and control of physical system
Open loop control of mobile robot	Physical Modelling of a Differential Drive Robot
Closed loop control of mobile robot with wheel encoders	Closed Loop Control of a Differential Drive Robot with Wheel Encoder and Acoustic Ranging
Mathematical modeling and control of physical system.	Localization and Global Path Planning for a differential drive robot in a occupancy grid
Introduction to physical modeling	Closed loop control of pneumatics
Creating requirements models of systems using SysML in different context and views	Closed control of pneumatics with PLC
MBSE approach for elevator	Introduction to hardware in loop simulation
Localization and Global Path Planning for a differential drive robot in a occupancy grid	Introduction to forward and inverse Kinematics of a serial Manipulator
Introduction to hardware in loop simulation	Introduction to velocity Kinematics of a Serial Manipulator
One degree of freedom pitch control (VTOL).	Trajectory Planning in Joint Space for Serial Manipulator
Control of rotary inverted pendulum	Trajectory Planning in Cartesian Space for Serial Manipulator
Closed loop control of pneumatics	Position Control of Serial Manipulator – Application task
Closed control of pneumatics with PLC	Force/Position Control of Serial Manipulator- Application task

Learning Resources	1. Devdasshetty, Richard A.Kolk "Mechatronics Systems Design", Cengage Learning, 2011.	6. Quanser QNET VTOL Laboratory manual (available in Mechatronics Laboratory).
	2. D A Bradley and et al,"Mechatronics-Electronics in Products and Processes",Springerscience+business media	7. Quanser QNET Rotary Inverted Pendulum manual (available in Mechatronics Laboratory).
	3. Ni_mechatronics_machine_design_guide from ni.com.	8. Laboratory manual for Mechatronics Laboratory, SRMIST
	4. Advanced model based systems design courseware from mathworks.com.	9. Dennis M.Buede& William D.Miller., "The Engineering Design of Systems Models and Methods" 3 rd Edition, Wiley, 2016
	5. Quanser QNET Practical Control Guide (available in Mechatronics Laboratory).	

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Ganesh Ram, Intel Labs ,Bangalore, ganeshram.nandakumar.@intel.com	1. Dr., R. Thiyagarajan, Visiting faculty, IIT Madras, thiyaguiitm@gmail.com	1. Mr.KSivanathan, SRMIST
2. Mr. Mohammed Sagheer ,Wabco Technology Center ,India, mohammedsagheer.musthafa@wabco-auto.com	2. Dr., P Karthikeyan, MIT,Anna University, pkarthikeyan@annauniv.edu	2. Mr.Ranjith Pillai R, SRMIST

Course Code	18MHC350T	Course Name	COMPREHENSION	Course Category	C	Professional Core	L	T	P	C
							0	1	0	1

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechatronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 : Acquire skills to solve real world problems in Engineering Graphics Design, Engineering Mechanics and Mechanics of Solids		1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 : Acquire skills to solve real world problems in Machines and Mechanisms, Thermodynamics and Fluid Mechanics		Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 : Solve problems in Manufacturing Technology, Material Technology, Applied Thermal Engineering for Automotive Engineers		Expected Proficiency (%)	Problem Analysis
CLR-4 : Solve problems in Automotive Engines, Vehicular Structures, Driveline Systems and Automotive Electrical and Electronics Systems		Expected Attainment (%)	Design & Development
CLR-5 : Acquire skills to solve real world problems in Design of Automotive components and CAD Analysis for Automotive Engineers			Analysis, Design, Research
CLR-6 : Acquire skills to solve real world problems for competitive examinations in Automobile and Mechanical Engineering			Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 : Practice and gain confidence, competence to solve problems in Engineering Graphics Design, Engineering Mechanics, Mechanics of Solids		3 85 80	H H H L L L L L L L L L M L M
CLO-2 : Practice and gain confidence and competence to solve problems in Machines and Mechanisms, Thermodynamics and Fluid Mechanics		3 85 80	H H M L L L L L L L L L M M M
CLO-3 : Solve problems in Manufacturing Technology, Material Technology and Applied Thermal Engineering for Automotive Engineers		3 85 80	H H M L L L L L L L L L M L M
CLO-4 : Solve problems in Automotive Engines, Vehicular Structures and Driveline Systems and Automotive Electrical and Electronics Systems		3 85 80	H H M L L L L L L L L L M M M
CLO-5 : Practice and gain confidence, competence to solve problems in Design of Automotive components, CAD Analysis for Automotive Engineers		3 85 80	H H H L L L L L L L L L M L M
CLO-6 : Practice and gain confidence and competence to solve problems in the broad domain of Automobile and Mechanical Engineering		3 85 80	H H M L L L L L L L L L M M M

Duration (hour)	3	3	3	3	3
S-1	SLO-1 Tutorial on Engineering graphics and design	Tutorial on Machines and Mechanisms	Tutorial on Manufacturing Technology for Automotive Engineers	Tutorial on Automotive Engines	Tutorial on Design of Automotive components
	SLO-2 Problem Solving	Problem Solving	Problem Solving	Problem Solving	Problem Solving
S-2	SLO-1 Tutorial on Engineering Mechanics	Tutorial on Thermodynamics	Tutorial on Material Technology	Tutorial on Vehicular Structures and Driveline Systems	Tutorial on CAD Analysis for Automotive Engineers
	SLO-2 Problem Solving	Problem Solving	Problem Solving	Problem Solving	Problem Solving
S-3	SLO-1 Tutorial on Mechanics of Solids	Tutorial on Fluid mechanics	Tutorial on Applied Thermal Engineering for Automotive Engineers	Tutorial on Automotive Electrical and Electronics Systems	Problem Solving
	SLO-2 Problem Solving	Problem Solving	Problem Solving	Problem Solving	Problem Solving

Learning Resources	1. R.S.Khurmi, J.K.Gupta, Mechanical Engineering: Conventional and Objective Types, S.Chand & Co., 2018	2. R.K.Jain, Conventional & Objective Type Question & Answers on Mechanical Engineering for Competitions, Khanna Publishers, 2014
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (100% weightage)								Final Examination	
		CLA – 1 (20%)		CLA – 2 (30%)		CLA – 3 (30%)		CLA – 4 (20%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	-	40%	-	30%	-	30%	-	30%	-	-
	Understand										
Level 2	Apply	-	40%	-	40%	-	40%	-	40%	-	-
	Analyze										
Level 3	Evaluate	-	20%	-	30%	-	30%	-	30%	-	-
	Create										
	Total	100 %		100 %		100 %		100 %		-	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers			
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts	
1.Mr.Ganesh Ram, Intel Labs ,Bangalore, ganeshram.nandakumar.@intel.com	1. Dr., R. Thiyagarajan, Visiting faculty, IIT Madras, thiyaguitm@gmail.com	1. Mr.KSivanathan, SRMIST	
2. Mr. Mohammed Sagheer ,Wabco Technology Center ,India, mohammedsagheer.musthafa@wabco-auto.com	2. Dr., P Karthikeyan, MIT,Anna University, pkarthikeyan@annauniv.edu	2. Mr.Ranjith Pillai R, SRMIST	

ACADEMIC CURRICULA

Professional Core Courses

NANOTECHNOLOGY

Regulations - 2018



SRM INSTITUTE OF SCIENCE AND TECHNOLOGY

(Deemed to be University u/s 3 of UGC Act, 1956)

Kattankulathur, Kancheepuram, Tamil Nadu, India

Course Code	18NTC201T	Course Name	NANOPHOTONICS	Course Category	C	Professional Core	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Nanotechnology	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Understand the fundamentals of light interaction with nanoscale materials	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Learn the basic concepts of quantum confined materials	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Understand the principles of photonic crystals	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Enrich their knowledge on plasmonics and near field optics	Expected Attainment (%)	Design & Development
CLR-5 :	Familiarize themselves with nanophotonic fabrication		Analysis, Design, Research
CLR-6 :	Understand the various aspects of nanobiophotonics		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Apply the principles of Quantum confinement effects to understand Nanoscale interaction dynamics	2 80 75	H M H H H M M H H H M H H H H
CLO-2 :	Utilize the photonic crystals in various applications	2 80 70	H M M H M M M H M H M H M M M
CLO-3 :	Explore the principles of plasmonics to study Near field scanning optical microscopy	2 75 70	H M H H H H H M H H H H H H H
CLO-4 :	Utilize the Near field scanning optical microscopy in data storage applications	2 80 75	M H H M H H H H H H M H H H H
CLO-5 :	Apply fundamental principles of Near field optical chemical vapor deposition technique for fabrication of nanophotonic materials	2 80 70	H M H H H M M H M H M H H H H
CLO-6 :	Utilize the Fluorescence contrast mechanism concepts to analyze the properties of organic materials	2 80 75	H M M H H M M H H H M H H M H

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Photons and electrons	Quantum confined materials	Plasmonics	Nanophotonic Fabrication	Biophotonics
	SLO-2 Similarities and differences	Inorganic quantum confined structures	Internal reflection	Adiabatic nanofabrication	Nanobiophotonics
S-2	SLO-1 Free space propagation	Manifestation of quantum confinement	Evanescent waves	Non adiabatic nanofabrications	The cell and scale
	SLO-2 Confinement of photons and electrons	Quantum confined Stark effect	Plasmons and surface plasmon resonance	Conditions for non-adiabatic nanofabrications	The cell and constituents
S-3	SLO-1 Propagation through a classically forbidden zone - Electrons	Dielectric confinement effect	Attenuated total reflection	Near field optical Chemical Vapour Deposition NFO CVD - Philosophy	Origin of contrast mechanisms
	SLO-2 Propagation through a classically forbidden zone - Photons	Super lattices	Grating SPR coupling	Near field optical Chemical Vapour Deposition – Design and technique	Optical contrast mechanisms
S-4	SLO-1 Tunneling Localization under a periodic potential - Electrons	Core-shell quantum dots	Optical waveguide SPR coupling	Near field photolithography - Philosophy	Classical contrast mechanisms
	SLO-2 Tunneling Localization under a periodic potential - Photons	Quantum wells	SPR dependencies and materials	Near field photolithography design and technique	Bright field and dark field contrast
S-5	SLO-1 Band gap and cooperative effects of photons	Quantum confined structures as lasing media	Plasmonics and nanoparticles	Self-assembling method	Phase contrast
	SLO-2 Band gap and cooperative effects of electrons	Organic quantum confined structures	Near-Field Optics	Self-assembling method via optical near field interactions	Inter ferrometric contrast
S-6	SLO-1 Nanoscale optical interactions	Photonic crystals	Aperture less near field optics	Regulating the size of Nanoparticles	Fluorescence contrast mechanism
	SLO-2 Axial and lateral nanoscopic localization	Important features of photonic crystals	Near field scanning optical microscopy (NSOM or SNOM) - Principle	Size dependent resonance	Confocal Microscopy
S-7	SLO-1 Nanoscale confinement of photonic interactions	Applications of Photonic crystals	Near field scanning optical microscopy design and technique	Controlling size of Nanoparticles	Nonlinear microscopy based on second harmonic generation
	SLO-2 Nanoscale confinement of electronic interactions	Dielectric mirrors	SNOM Applications	Alignment of Size controlled Nanoparticles	Coherent anti-stokes Raman scattering (CARS)

S-8	SLO-1	Quantum confinement effects	Interference filters	SNOM based visualization of waveguide structures	Controlling position of Nanoparticles	Reduction of the observation volume
	SLO-2	Nanoscale interaction dynamics	Photonic crystal laser, Photonic crystal sensing	SNOM based energy transport	Alignment of position controlled Nanoparticles	Far field method - 4Pi microscopy
S-9	SLO-1	Nanoscale electronic energy transfer	Photonic crystal fibers (PCFs)	SNOM based optical data storage	Separation of Nanoparticles	Microscopy on a mirror
	SLO-2	Cooperative emissions	Introduction to Metamaterials	SNOM based optical data recovery	Alignment of Separated and controlled Nanoparticles	Stimulated emission depletion (STED)

Learning Resources	1. M.Ohtsu, K.Kobayashi, T.Kawazoe and T.Yatsui, <i>Principals of Nanophotonics (Optics and Optoelectronics)</i> , CRC press, 2003	3. BEA Saleh and AC Teich, <i>Fundamentals of Photonics</i> , John Wiley and Sons, 1993
	2. H.Masuhara, S.Kawata and F Tokunga, <i>NanoBiophotonics</i> , Elsevier Science, 2007	4. Y. V. G.S. Murthy and C. Vijayan, <i>Essentials of Nonlinear Optics</i> , Wiley, 1 st edition, 2014

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Sameer Sharda, New Age Instruments & Materials Pvt. Ltd., Gurgaon, sameer@newagein.com	1. Prof. C. Vijayan, IIT Madras, cvijayan@iitm.ac.in	1. Dr. D. John Thiruvadigal, SRMIST
2. Mr. Muhammed Shafi, Holmarc Opto-Mechatronics Pvt. Ltd, Cochin, optics@holmarc.com	2. Prof. S. Balakumar, Univ. of Madras, balakumar@unom.ac.in	2. Dr. Junaid Masud Laskar, SRMIST

course Code	18NTC202J	Course Name	NANOBIOTECHNOLOGY	Course Category	C	Professional Core	L	T	P	C
							3	0	2	4

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Nanotechnology	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 : <i>Understand the interaction of nanomaterials with biological systems</i>		1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 : <i>Know about the properties of biomaterials</i>		Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 : <i>Learn various applications of nanotechnology in biology</i>		Expected Proficiency (%)	Problem Analysis
CLR-4 : <i>Apply the nanoscience concepts in biotechnology</i>		Expected Attainment (%)	Design & Development
CLR-5 : <i>Utilize various biological techniques to understand nano bio interactions</i>			Analysis, Design, Research
CLR-6 : <i>Demonstrate skills in nanobiotechnology experimental techniques</i>			Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 : <i>Choose appropriate biomaterial for biological application</i>		1 80 75	H M H H H H H M H L H H H H
CLO-2 : <i>Explain the concept of biocompatibility</i>		1 80 70	H M H H M M H M H M H M M M
CLO-3 : <i>Perform experiments like Electrophoresis, Protein estimation and Drug loading</i>		2 75 70	H H H H H H H M H L H H H H
CLO-4 : <i>Describe about various biological molecules.</i>		2 80 75	H H H H H H H M H M H H H H
CLO-5 : <i>Analyze the interaction of nanomaterials with biomolecules</i>		2 80 80	H H H H H H H M H M H H H H
CLO-6 : <i>Demonstrate skills required for application of nanotechnology in biology</i>		2 80 80	H H H H H H H M H M H H H H

Duration (hour)	15	15	15	15	15
S-1	SLO-1 <i>Biomaterials</i>	<i>Structure of membranes</i>	<i>Nanodiagnosis</i>	<i>Drug delivery systems</i>	<i>Biosensor</i>
	SLO-2 <i>Surface and bulk properties of bio materials</i>	<i>Lipid bilayer</i>	<i>Detection of tumors</i>	<i>Traditional drug delivery</i>	<i>Nanobiosensors design</i>
S-2	SLO-1 <i>Nanoceramics</i>	<i>Traffic across membranes</i>	<i>Detection of plaque</i>	<i>Controlled drug delivery</i>	<i>optical biosensors based on nanoplasmonics</i>
	SLO-2 <i>Polymeric nanoparticles</i>	<i>Endocytosis</i>	<i>Genetic defects</i>	<i>Nanoparticle based drug delivery</i>	<i>Nanoimmuno sensors</i>
S-3	SLO-1 <i>Hydroxyapatite: Structures, Chemical composition</i>	<i>Exocytosis</i>	<i>Nano medical devices.</i>	<i>Targeted drug delivery to cancer</i>	<i>Immuno Fluorescent Biomarker Imaging</i>
	SLO-2 <i>Applications of hydroxyapatite</i>	<i>Receptor mediated transport</i>	<i>In vivo imaging</i>	<i>Types of drug targeting</i>	<i>Iron Oxide Nanoparticles in Magnetic Resonance Imaging</i>
S 4-5	SLO-1 <i>Lab 1:Introduction to Nanobiotechnology laboratory</i>	<i>Lab 4: Analysis of antimicrobial activity of nanoparticles</i>	<i>Lab 7: Hemocompatibility analysis of nanoparticles</i>	<i>Lab 10: Fabrication of nanoparticles incorporated scaffolds for tissue engineering</i>	<i>Lab 13: Determination of controlled drug release from controlled drug delivery system</i>
	SLO-2 <i>Surface modification of biomaterials</i>	<i>Active transport</i>	<i>Nanotechnology in gene therapy</i>	<i>Surface Modified Nanoparticles</i>	<i>Nanotechnology in food processing</i>
S-6	SLO-2 <i>Surface immobilized biomolecules</i>	<i>Passive transport</i>	<i>Stem cells</i>	<i>Peptide/DNA Coupled Nanoparticles for drug delivery and targeting</i>	<i>Food preservation</i>
S-7	SLO-1 <i>Interaction of biomaterials with cells</i>	<i>Membrane transporters</i>	<i>Polymerase chain reaction</i>	<i>Lipid Nanoparticles For Drug Delivery and targeting</i>	<i>Nanomaterials for food packing</i>
	SLO-2 <i>Immune response to biomaterials</i>	<i>Membrane proteins and Pumps</i>	<i>Enzyme-linked immunosorbent assay(ELISA)</i>	<i>Inorganic Nanoparticles For Drug Delivery</i>	<i>Delivery of nutraceuticals</i>
S-8	SLO-1 <i>Biocompatibility</i>	<i>Antibodies</i>	<i>DNA profiling</i>	<i>Metal/Metal Oxide Nanoparticles for antibacterial/anti-fungal/anti-viral activity</i>	<i>Delivery of functional foods</i>
	SLO-2 <i>In vitro analysis</i>	<i>Monoclonal antibodies</i>	<i>Nanoprobes</i>	<i>Hyperthermia treatment</i>	<i>Nanosensors for food Pathogen Detection</i>
S 9-10	SLO-1 <i>Lab 2: Preparation of media, slants and plates for bacterial growth</i>	<i>Lab 5: Isolation of Genomic DNA</i>	<i>Lab 8: Amplification of DNA by PCR</i>	<i>Lab 11: Quantitation estimation of biomolecules</i>	<i>Lab 14: Fluorescent imaging of nano-bio interaction</i>
	SLO-2				

S-11	SLO-1	<i>In vivo analysis</i>	<i>Nanoimmuno assay</i>	<i>Blotting techniques</i>	<i>Dental implants</i>	<i>Nanotechnology in agriculture</i>
	SLO-2	<i>Tissue compatibility</i>	<i>Blood-Biomaterial Interactions</i>	<i>Western Blotting</i>	<i>Regenerative medicine</i>	<i>Nanof ormulation For The Control Of Plant Disease</i>
S-12	SLO-1	<i>Biomolecular motors</i>	<i>Interactions with Proteins</i>	<i>Surface plasmon Resonance</i>	<i>Tissue engineering</i>	<i>Nanomaterials for PEST control in PLANTS</i>
	SLO-2	<i>Linear motors</i>	<i>Cell Adhesion</i>	<i>Surface enhanced Raman scattering</i>	<i>Nanoparticles and polymeric nanofibers in tissue engineering</i>	<i>Nanotechnology and Agricultural Sustainable Development</i>
S-13	SLO-1	<i>Rotary motors</i>	<i>Biocompatibility</i>	<i>Analysis of biomolecular structure by AFM</i>	<i>Scaffold design and fabrication</i>	<i>Toxicity of nanomaterials</i>
	SLO-2	<i>Actin and myocin</i>	<i>Safety Testing of Biomaterials</i>	<i>Analysis of biomolecular structure by molecular pulling force spectroscopy</i>	<i>Controlled release strategies in tissue engineering</i>	<i>Environmental risks of nanomaterials</i>
S-14-15	SLO-1	<i>Lab 3: Growth of Bacteria by pour plate, spread plate and streak plate techniques</i>	<i>Lab 6: DNA fragmentation analysis by Agarose gel electrophoresis</i>	<i>Lab 9: Repeat/Revision of the experiments</i>	<i>Lab 12: Estimation of drug loading percentage</i>	<i>Lab 15: Protein separation by SDS PAGE analysis</i>
	SLO-2					

Learning Resources	1. Niemeyer, C.M. and Mirkin, C.A., <i>Nanobiotechnology: Concepts, Applications and Perspectives</i> , Wiley-VCH, 2004.	3. Goodsell, D.S., <i>Bionanotechnology</i> , John Wiley and Sons, Inc., 2004.
	2. Madhuri Sharon, Maheshwar Sharon, Sunil Pandey and Goldie Oza, <i>Bio-Nanotechnology_ Concepts and applications</i> . Ane Books Pvt Ltd, 1 edition 2012.	

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		1000%	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. K. Chandru Trivitron Healthcare Pvt. Ltd. Chennai, chandru.k@trivitron.com	1. Dr. Mukesh Doble, IIT M, mukeshd@iitm.ac	1. Dr. G. Devanand Venkatasubbu, SRMIST
2. Dr. Asifkhan Shanavas, INST Mohali, asifkhan@inst.ac.in	2. Dr. T. Prakash, UOM, thanigaiprakash@gmail.com	2. Dr. N. Selvamurugan, SRMIST

Course Code	18NTC203T	Course Name	NANOTOXICOLOGY	Course Category	C	Professional Core				L	T	P	C
										3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Nanotechnology	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand the concept of toxicity	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Acquire knowledge on physical properties of nanostructured materials on toxicity	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Learn about nanoparticle interaction with cells				H	M	H	H	H	H	H	H	M	H	M	H	H	H	H
CLR-4 :	Know about various methods of toxicity assessment				H	M	H	H	M	M	M	H	M	H	M	H	M	M	M
CLR-5 :	Learn various in vivo toxicity methods				H	H	H	H	H	H	H	H	M	H	M	H	H	H	H
CLR-6 :	Gain knowledge about the toxic nanomaterials and their properties				M	H	H	M	H	M	H	H	M	H	M	M	H	H	H
					M	H	H	M	H	M	H	H	M	H	M	M	H	H	H
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Aware about toxicity caused by nanomaterials	1	80	75															
CLO-2 :	Relate the physical properties of nanostructured materials to its toxicity	1	80	70															
CLO-3 :	Analyze the various symptoms caused due to toxicity of nanoparticles	2	75	70															
CLO-4 :	Apply the various methods of toxicity assessment	2	80	75															
CLO-5 :	Analyze the in vivo toxicity data	2	80	80															
CLO-6 :	Demonstrate skills required for application of nanotechnology in toxicity studies	2	80	80															

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Introduction to toxicity	Nanoparticles vs. micron-size particle	Interaction of nanoparticles with lipid bilayers	Methods for toxicity assessment	In vivo Analysis
	SLO-2 Size-specific behavior of nanomaterials	Nanoparticle toxicity	Cell-level studies	LADMET hypothesis	species and strains of animals used in toxicity studies
S-2	SLO-1 Challenges in Nanotoxicology	Comparison to larger counterparts	Nanoparticle-induced membrane permeability	Effects of Nanoparticle on the Cardiovascular System	Dosing profile for animal models
	SLO-2 Entry Routes into the Human Body	Requirement for appropriate model	Internalization of cation nanoparticles into cells	Thrombosis	Studies on toxicology
S-3	SLO-1 Importance of size and shape of Nano particle	Exposure assessment	Placental Barrier	Cardiac ischemia	Histopathology studies
	SLO-2 Physicochemical properties of nanomaterials	Types of exposure pathways	Biological barrier model evaluation of nanoparticle transfer	Fibrinolysis	metabolism in mouse and rat
S-4	SLO-1 Mediators of nano toxicity	Significance of Exposure assessment	Transport across placental barrier	Coagulation	Predicting Penetration of nanomaterials
	SLO-2 physicochemical properties of Nanomaterials related to toxicity	Occurrence of exposure pathways	Assessment of placental Transfer	Endothelial Dysfunction	Fate of Nanoparticles in the Body
S-5	SLO-1 Characterization of administered nanomaterials	Nature of exposures	Biological mechanism of nanoparticle disposition	Effect of Nanoparticles on Nervous system	Toxicity Mechanisms
	SLO-2 Toxicity studies	Documentation of toxicity	Outline of gene	Effect of Nanoparticles on Genotoxicity	Mechanisms for Radical Species Production
S-6	SLO-1 Nanomaterial characterization after administration	Bio-distribution of nanoparticles	Cellular interactions	Effect of Nanoparticles on carcinogenicity	Genotoxicity Mechanisms
	SLO-2 Source and types of Nanoparticles-	Localization of particles in tissues	Nano Biointeractions	Mechanism of carcinogenicity	Detection of Genotoxicity
S-7	SLO-1 Particles due to airpollution	Nanoparticles in the environment	Toxicity based on route of entry	Toxicity caused to Organ by Nanoparticles	Characterization of Genotoxicity
	SLO-2 Biototoxicity of metal oxide Nanoparticles	Nanoparticles in mammalian system	Nature of toxicity	Effect of nanoparticles on Respiratory system	Inflammation analysis

S-8	SLO-1	Carbon nanotubes in practice	Health threats due to Nanoparticles	Toxicodynamics	Dermal toxicity analysis	Biocompatibility studies
	SLO-2	Postproduction processing of carbon nanotubes	Nanoparticle translocation in mammalian system	Dose vs Toxicity Relationships	Hepato toxicity analysis	Laws and Regulations Governing Animal Care and Use in Research
S-9	SLO-1	Toxicity of Carbon nano tubes	Direct vascular effects in mammalian system	Toxicokinetics	Nephrotoxicity studies	Factors Affecting Exposure to Nanomaterials
	SLO-2	Body Distribution; Nanoparticles and Cellular Uptake	Role of Nanoparticles in Mediating the Adverse Pulmonary Effects	Absorption, distribution, metabolism excretion studies (ADME)	Assessment of oxidative stress and antioxidant status	Elements of a Risk Management Program

Learning Resources	<ol style="list-style-type: none"> Niemeyer, C.M. and Mirkin, C.A., "Nanobiotechnology: Concepts, Applications and Yuliang Zhao, Hari Singh Nalwa, "Nanotoxicology: interactions of nanomaterials with biological systems", American Scientific Publishers, 2007. Lynn Goldman, Christine Coussens, "Implications of nanotechnology for environmental health research", National Academic Press, Washington, 2007. 	<ol style="list-style-type: none"> Approaches to safe nanotechnology: Managing the health and safety concerns associated with Engineered Nanomaterials', DHHS (NIOSH) publishers, 2009
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100%	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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Course Code	18NTC204J	Course Name	NANOELECTRONICS	Course Category	C	Professional Core			
						L	T	P	C
						3	0	2	4

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Nanotechnology			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Acquire knowledge on quantum confinement and low-dimensional nanostructures for use in nanoelectronics	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Understand the key aspects of electron tunneling and its application in the operation of nanodevices.	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Understand the functioning of tunnel junctions in single electron devices																		
CLR-4 :	Understand the concept of molecular electronics for realization of device miniaturization																		
CLR-5 :	Acquire knowledge on the fabrication, characterization and modeling of nanodevices																		
CLR-6 :	Acquire knowledge on designing and fabrication process which is Essential for simulation of nanoelectronic devices.																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Acquaint with the fundamentals of nanoelectronics	1	80	75	H	H	M	M	M	M	H	H	H	H	M	H	H	H	H
CLO-2 :	Utilize their knowledge on the electron tunneling phenomena in semiconductor nanodevices	1	80	70	H	H	M	M	M	M	H	H	H	H	M	H	H	H	H
CLO-3 :	Apply the knowledge on the operation and application perspectives of various tunnel devices	2	75	70	H	H	H	H	H	H	H	H	M	H	M	H	H	H	H
CLO-4 :	Analyze the concept of molecular electronics	2	80	75	M	H	M	M	H	H	H	H	M	H	L	H	M	M	M
CLO-5 :	Apply their knowledge on the fabrication and modeling of nanodevices	2	80	80	H	H	H	H	H	H	H	H	H	H	L	H	H	H	H
CLO-6 :	Demonstrate skills required for using advanced experimental techniques	2	80	75	H	M	M	H	M	M	M	H	H	H	M	H	H	M	H

Duration (hour)	15	15	15	15	15
S-1	SLO-1 Introduction to nanoelectronics	Tunnel effect and tunneling elements	Classical and semi-classical transport	Introduction to molecular electronics	Introduction to computational methods
	SLO-2 Review of basic quantum physics	Nanoelectronics in tunneling devices	Ballistic transport in nanostructures	Atomic-scale junctions: an overview	Necessity of computational methods
S-2	SLO-1 Moore's law and its consequences	Tunneling of electrons through a potential barrier	Coulomb blockade - an overview	Schrodinger equation	Molecular wire
	SLO-2 Silicon electronics - limitations	Electron tunneling-key points	Single electron tunneling and Coulomb blockade	Self-consistent field	Molecular wire conductance
S-3	SLO-1 International technology roadmap characteristics (ITRC)	Potential energy profiles for material interfaces	Coulomb blockade in a quantum dot circuit	Molecular functionalities	Theoretical aspects on molecular conductance
	SLO-2 ITRC and Nanoscale importance	Metal-semiconductor and metal-insulator junctions	Coulomb blockade in a nano-capacitor	Metal-molecule interfaces	Computational aspects on molecular conductance
S-4-5	SLO-1 Lab 1: Determination of electron concentration versus temperature using MATLAB	Lab 4: Four probe resistivity measurement	Lab 7: PSpice simulation of FET and its I-V characteristics	Lab 10: PSpice simulation of MOSFETs using a simple DC circuit and a CMOS inverter with DC sweep analysis	Lab 13: Simulation of diode using TCAD and its characterization
	SLO-2 Need for new concepts in electronics	Metal-insulator-metal junctions	Ballistic transport and the Landauer formula	Molecular band Structure	Various modeling techniques
S-6	SLO-2 Challenges in micro to Nano conversion	Metal work function and electron affinity	Quantized Conductance	Level broadening	Monte Carlo method
S-7	SLO-1 Dimensionality in materials	Tunneling applications	Working principle of Single Electron Transistor (SET)	Atomistic view of electrical resistance	Ab initio simulations
	SLO-2 Density of states of materials at nanoscale	Field electron emission	A single-electron pump and turnstile	Conductance of atomic-scale contacts	Ab initio simulations: examples and problems
S-8	SLO-1 Effect of band gap of material at different dimensions	Double barrier tunneling	Quantum dot	Coherent transport through molecular junctions	Multiscale modeling
	SLO-2 Length scales of charge scattering	Resonant tunneling diodes	Quantum-dot cellular automata	Non-coherent transport in molecular electronics devices	Modeling of nanodevices and applications

S 9-10	SLO-1	Lab 2: Determination of electron (μn) and hole (μp) mobilities versus doping concentration in semiconductor using MATLAB	Lab 5: PSpice simulation of diode and its I-V characteristics with smoke analysis	Lab 8: Hall effect of semiconductors	Lab 11: PSpice simulation of Zener Diode model and its I-V characteristics	Lab 14: Designing of 2D MOSFET using TCAD
	SLO-2					
S-11	SLO-1	Special dimensionality case of carbon	Tunneling in MOS Transistors	Electron transport in quantum dots	Molecular diodes	TCAD
	SLO-2	Introduction to 0D, 1D, 2D and 3D carbon forms	Hel transistor	Electron transport in quantum wires	Conducting mechanism of single-molecule junctions	TCAD: examples and problems
S-12	SLO-1	Nanocomputing	Hot electron effects in MOSFETs	Introduction to spintronics	Single-molecule transistors	NEH DFT
	SLO-2	Device simulation software at nanoscale	Gate-oxide tunneling	Giant magneto resistance	Elastic and inelastic co-tunneling	NEH DFT: examples and problems
S-13	SLO-1	Future Prospects of Nanoelectronic Devices	Principles of scanning tunneling microscopy (STM)	Tunnel magneto resistance	Molecular devices and logic switches	Materials studio
	SLO-2	Progress in Nanoelectronic Architectures	Applications of STM in nanotechnology	Spintronic devices and applications	Interface engineering issues	Future of nanoscale modeling
S 14-15	SLO-1	Lab 3: Determination of Fermi function for different temperature using MATLAB	Lab 6: PSpice simulation of BJT and its I-V characteristics	Lab 9: Repeat/Revision of the experiments	Lab 12: PSpice simulation of a Phototransistor	Lab 15: Repeat/Revision of the experiments
	SLO-2					

Learning Resources	1. G. W. Hanson, <i>Fundamentals of Nanoelectronics</i> , Pearson Education; 1 edition (2009)	6. Sarhan. M. Musa, <i>Computational Nanotechnology: Modeling and Applications with MATLAB</i> , CRC Press, 2011
	2. V. V. Mitin, V. A. Kochelap, M. A. Strosio, <i>Introduction to Nanoelectronics</i> , Cambridge University Press; 1 edition (2007)	7. John O. Attia, <i>Electronics and Circuit Analysis using Matlab</i> , CRC Press, 2001
	3. E. Scheer and J. C. Cuevas, <i>Molecular Electronics: An Introduction to Theory and Experiment</i> , World Scientific Pub Co Inc; 1 edition (2010)	8. Mitchell A. Thornton, <i>PSpice for Circuit Theory and Electronic Devices</i> , Morgan & Claypool Publishers series
	4. K. I. Ramachandran, <i>Computational Chemistry and Molecular Modeling</i> , Springer, 2008	9. Simon Li and Yue Fu, <i>3D TCAD Simulation for Semiconductor Processes, Devices and Optoelectronics</i> , Springer, 2012
	5. <i>Nanoelectronics simulation laboratory course manual</i> , 2016	

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		50%	50%

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. Krishna Surendra Muvvala, Saint Gobain Research India, India, Krishna.muvvala@saintgobain.com	1. Prof. V. Subramaniam IIT M, manianvs@iitm.ac.in	1. Dr. D. John Thiruvadigal, SRMIST
2. Dr. Hemant Dixit, Global Foundaries, USA, aplahemant@gmail.com	2. Prof. C. Venkateswaran, Univ. of Madras, cvenkateswaran@unom.ac.in	2. Dr. Arijith Sen, SRMIST

Course Code	18NTC205J	Course Name	MICRO AND NANOFABRICATION	Course Category	C	Professional Core				L	T	P	C
										3	0	1	4

Pre-requisite Courses	SOLID STATE ENGINEERING	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Nanotechnology	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Overview the techniques and processes to organize nanoscale materials in device form				Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Understand methodology of lithography and etching to pattern materials																							
CLR-3 :	Acquire knowledge of different deposition techniques and ion implantation																							
CLR-4 :	Get acquainted with CMOS fabrication rules																							
CLR-5 :	Introduce next generation printed electronics technology																							
CLR-6 :	Make aware of VLSI technology																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3			
CLO-1 :	Realizing the technology of Si wafer manufacturing				2	80	75	H	M	H	H	H	M	M	M	H	H	H	M	H	H	H	H	
CLO-2 :	Pattern diverse materials using lithography techniques to enhance the device density on chip				2	80	70	H	M	M	H	M	M	M	H	M	H	M	H	M	M	M	M	
CLO-3 :	Applying basic diffusion processes importance in semiconductor technology				2	75	70	H	M	H	H	H	H	H	M	H	H	H	H	H	H	H	H	
CLO-4 :	Fabricate small-scale devices and chip level device space management				2	80	75	M	H	H	M	H	H	H	H	H	H	M	H	H	H	H	H	
CLO-5 :	Envision low cost production of electronic devices using printed technology				2	80	70	H	M	H	H	H	M	M	H	M	H	M	H	H	H	H	H	
CLO-6 :	Imagining importance of nanoscale devices				2	80	75	H	M	M	H	H	M	M	M	H	H	M	H	H	M	H	H	

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Importance of micro and nanofabrication techniques in IC: front and back plane	Need and basics of lithography	Classification of material deposition techniques	History of complementary metal-oxide-semiconductor (CMOS)	Overview of printing processes
	SLO-2	Over view of crystal and lattices	Optical lithography	Overview of physical and chemical deposition technique	Requirements of device isolation	Advantages of printing
S-2	SLO-1	Classification of grades of silicon	Optical lithography controls and mask making	Physical vapour deposition	Types of isolation	Requirements of printing
	SLO-2	Production of electronic grade silicon	Working concept and controls of e-beam lithography	Resistive heating evaporation	Local Oxidation of Silicon (LOCOS) and shallow trench isolation (STI) processes for local isolation	Printing tools
S-3	SLO-1	Czochralski growth technique	Resolution of electron beam lithography	Electron beam heating evaporation	Concept of self-alignment	Types of fluids for ink
	SLO-2	float zone growth technique	X-ray lithography	Pulsed laser evaporation	MOS fabrication with self-alignment	Properties of fluids in printing processes
S-4,5	SLO-1	Lab 1:Introduction to the basics of laboratory	Lab 4: To perform patterning by photolithography process	Lab 7: To deposit Al thin film on the oxidized silicon surface by thermal evaporation	Lab 10:To form local anodic oxidation pattern by scanning probe microscopy	Lab 13:To perform contact angle measurement of solvents used in printing process
	SLO-2					
S-6	SLO-1	Silicon wafer shaping	Stamp based lithography	Basics of sputtering	Requirement of planarization	Working principle of flexographic printing (FP)
	SLO-2	Wafer manufacturing steps and inspection	Nanoimprint lithography and applications	DC and magnetron sources for sputtering	Local and global planarization using chemical-mechanical polishing	Advantages and disadvantages of FP
S-7	SLO-1	Overview of types of epitaxy	Etching of silicon	Introduction to atomic layer deposition	Importance of MOS devices	Working principle of gravure printing (GP)
	SLO-2	Definition-epitaxy	Wet etching mechanism and disadvantages	Working principle of atomic layer deposition	Concept of well formation with p and n doping	Advantages and disadvantages of GP
S-8	SLO-1	Comparison of vapour phase epitaxy (VPE), liquid phase epitaxy (LPE) and molecular beam epitaxy (MBE)	Types of dry etching	Concepts of diffusion	Working principle of integrated CMOS inverter	Working principle of screen printing (SP)

	SLO-2	Working of MBE process	Ways of plasma generation for etching processes, Sputter etching	Using Fick's diffusion in semiconductor doping	Fabrication process of CMOS inverter	Advantages and disadvantages of SP
S-9,10	SLO-1	Lab 2: To perform wafer cleaning processes followed for VLSI applications	Lab 5: To perform wet chemical etching of silicon dioxide	Lab 8: To deposit Al thin film on the oxidized silicon surface by e-beam evaporation	Lab 11: To design MOS capacitor design layout using 'layout editor'	Lab 14: To measure gauge factor of flexible strain gauge
	SLO-2					
S-11	SLO-1	General epitaxy growth mechanism	Capacitively coupled plasma	Process of ion implantation	Usage of isolation and biasing of inverter	Working principle of inkjet printing (IP)
	SLO-2	Epitaxy growth kinetics and examples	Inductively coupled plasma	Ion implantation tool	'Latch up' concept for inverter	Advantages and disadvantages of IP
S-12	SLO-1	Understanding silicon oxide properties	Classification of plasma using its density	Fundamentals of ion energy loss and stopping	Design rules for CMOS	Examples of printed devices
	SLO-2	Thermal oxidation furnace	High density plasma	Damage due to implantation	MOSIS specifics for inverter	Comparison of printed devices with lithographically fabricated devices
S-13	SLO-1	Silicon oxide growth kinetics	Reactive ion etching	Ion distribution, junction control	Introduction to silicon-on-insulator (SOI)	Concept of hybrid printed electronics
	SLO-2	Thin oxide growth and process of oxidizing polysilicon	Deep reactive ion etching and bosh process	Carrier recovery using annealing process	On chip fabrication processes of passive components	Future of printed low-cost electronics
S-14,15	SLO-1	Lab 3: To oxidize silicon under O ₂ ambient using temperature controlled furnace	Lab 6: To perform wet chemical etching of metal films	Lab 9: To perform ion beam implantation process and defect analysis using SRIM software	Lab 12: To fabricate MOS capacitor and study its I-V characteristics	Lab 15: Repeating of experiments
	SLO-2					

Learning Resources	1. Hans H. Gatzert, Volker Saile, Jürg Leuthold, "Micro and Nano Fabrication", Springer 2015 2. S. M. Sze, and S. Lee, "Semiconductor Devices Physics and Technology", Wiley, 2012	3. Giovanni Nisato, Donald Lupo, Simone Ganz, "Organic and Printed Electronics", CRC Press, 2016. 4. Sorab K. Gandhi, "VLSI Fabrication and Principles", McGraw Hill, 2005
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. Hemant Dixit, GlobalFoundaries,USA, aplahemant@gmail.com	1. Dr. A. Subrahmanyam, IIT Madras, manu@iitm.ac.in	1. Dr. Abhay Sagade, SRMIST
2. Dr. Krishna Surendra Muvvala, Saint Gobain Research India, India, Krishna.muvvala@saintgobain.com	2. Dr. N. N. Murthy, IIT Tirupati, nnmurthy@iittp.ac.in	2. Dr. P. Malar, SRMIST

Course Code	18NTC301J	Course Name	POLYMER AND NANOCOMPOSITES	Course Category	C	Professional Core Course	L	T	P	C
							3	0	2	4

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Nanotechnology	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Acquire knowledge about fundamentals of polymers	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Understand basics concepts about polymerization reactions	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Gain insight into the importance of polymers in nanotechnology																		
CLR-4 :	Understand the physical and mechanical properties of polymer																		
CLR-5 :	Gain knowledge about the preparation and properties of nanocomposites																		
CLR-6 :	Understand the significance of nanosize on polymer and composites																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Apply the chemical concepts to understand the configuration and conformation of polymers	1	80	75	H	M	H	H	H	H	M	H	M	H	M	H	H	H	H
CLO-2 :	Analyze the mechanical behavior of polymers by studying its properties	1	80	70	H	M	H	H	M	M	M	H	M	H	L	H	M	M	M
CLO-3 :	Utilize the basic principles about polymerization to synthesize polymers using monomers	2	75	70	H	H	H	H	H	M	H	H	M	H	L	H	H	H	H
CLO-4 :	Apply the knowledge about fibers and matrix materials in making nanocomposites	2	80	75	H	H	H	H	H	H	H	H	H	H	M	H	H	H	H
CLO-5 :	Analyze the types of matrix and reinforcements available for the preparation of nanocomposites	2	80	80	H	H	H	H	H	H	H	H	H	H	M	H	H	H	H
CLO-6 :	Utilize the knowledge about polymers towards environmental and biomedical applications	2	80	80	H	H	H	H	H	H	H	H	H	H	H	H	H	H	H

Duration (hour)	15	15	15	15	15
S-1	SLO-1	Importance of polymers: basic concepts	Conducting polymers	Introduction and additives of composites	Metal – Polymer Nanocomposites
	SLO-2	Classification of polymers on the basis of microstructures & macrostructures	Discovery	Characteristics of composites	Physical and chemical properties of Nanosized metal particles
S-2	SLO-1	polymer classifications based on-occurrence, types, process and applications	Structural characteristics	Classification- particulate, fibrous	Metal containing polymers: cryochemical synthesis, structure and physio-chemical properties
	SLO-2	Chain structure, configuration and conformation	Intrinsic and extrinsic conduction in polymers	Laminated and hybrid composites	Nanostructured polymer nanoreactors for metal particle formation
S-3	SLO-1	Homo and heteropolymers - copolymers	Charge carriers and conducting mechanism	Additives for Composites	Metal-polymer nanocomposite synthesis, Ex-situ, In-situ
	SLO-2	Chemistry of polymerization	Chemical and electrochemical methods of synthesis of conducting polymers	Catalysts	Optically anisotropic metal polymer nanocomposites
S 4-5	SLO-1	Lab 1:Introduction to the basics of Polymer science	Lab 4: Preparation of poly vinyl alcohol nanofibers by electro spinning technique	Lab 7: Fabrication of polymer thin film composites using phase inversion techniques	Lab 10: Preparation of ceramic based nanocomposites
	SLO-2				
Coupling Agents	SLO-1	Molecular solution, Melt and elastomer	Synthesis method of polyaniline	Accelerators	Polymer- Clay Nanocomposites
	SLO-2	Crystalline nature of polymers	Polypyrrole		Synthesis of Nylon 6-clay hybrid (NCH) composites and characterization
S-7	SLO-1	Factors affecting crystallization phenomenon	Characterization using UV-Visible and FTIR spectrometer	Fillers	Crystal structure of NCH and properties of NCH
	SLO-2	Glass transition temperature (Tg)	Morphological study using SEM and TEM	Toughening Agents	Polypropylene layered silicate Nanocomposites

S-8	SLO-1	Melting temperature(Tm)	Applications of conducting polymers in corrosion protection	Reinforcement Materials	Epoxy Nanocomposite	Particulate reinforced, graded and layered ceramic composite
	SLO-2	Factors affecting Tg and Tm	Sensors	Fibre Reinforcements	Layered silicate Nanocomposites	Nanophase ceramic composites
S-9-10	SLO-1	Lab 2: Polymerization of Urea-formaldehyde resin	Lab 5: Characterization of the fibers prepared using SEM and wettability test	Lab 8: Preparation of metal-polymer nanocomposites	Lab 11: Morphological characterization of prepared composites using SEM	Lab 14: Synthesis of hydrogel using cellulose acetate polymer
	SLO-2					
S-11	SLO-1	Importance of Tg	Conducting adhesives	Woven and Non-Woven Fabrics	Structure, properties and characterization	Metal reinforced ceramic matrix nanocomposites
	SLO-2	Molecular weight distribution	Electro conducting polymers	Carbon , Aramid Fibre and Boron Fibres	Poly(ethyl acrylate)/bentonite nanocomposites	Refractory and special ceramic composites
S-12	SLO-1	Degree of polymerization	Polymer batteries and electrets	Natural Fibres – Cellulose	Poly(butylene terephthalate) based Nanocomposites	Non-oxide ceramic composites
	SLO-2	Reaction kinetics of polymerization	Polymers with piezoelectric property	Testing of Composites	Polymer/calcium carbonate Nanocomposites	Machinable Nanocomposite ceramics-Silicon nitride and silicon carbide based ceramics
S-13	SLO-1	Dielectric constant	Pyroelectric and ferroelectric property	Tensile, Impact strength, Compression and Flexural Strength	Functional applications of polymer-clay Nanocomposites	Functionally graded ceramics- clay Nanocomposites
	SLO-2	Polarization; Dissipation factor	Photo conducting polymers.	Applications of composites	Biodegradable polymer categories, properties and drawback	Applications of ceramic matrix Nanocomposites
S-14-15	SLO-1	Lab 3: Interfacial Polymerization of polyamide from Diamine and Diacid Chloride.	Lab 6: Fabrication of polymer membrane using phase inversion techniques	Lab 9: Repeat/Revision of the experiments	Lab 12: Synthesis of Nylon-6 polymer	Lab 15: Study of glass transition, melting and crystallization temperature of given materials
	SLO-2					

Learning Resources	1. Gowariker V.R., Viswanathan N.V., Sreedhar J., Polymer Science, New age International publications, 2005	4. Alfred rudin , The elements of polymer science and engineering, 2nd edition, Academic press publication, 1999
	2. Luigi Nicolais, Gianfranco Carotenuto, Metal-polymer Nanocomposites, Wiley-Interscience, 2005	5. Low I. M., Ceramic matrix composites: Microstructure, properties and applications, Woodhead Publishing Limited, 2006
	3. BorZ. Jang, Advanced Polymer composites, ASM International, USA, 1994.	

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		-	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. P. Sudhakara, CLRI – CSIR, Jalandhar, sudhakar@clri.res.in	1. Dr. Kothandaraman Ramanujam, IITM Chennai, rkraman@iitm.ac.in	1. Dr. N. Angeline Little Flower. SRMIST
2. Dr. Sudhakar Selvakumar, CSIR-Central Electrochemical Research Institute, ssudhakar79@gmail.com	2. Dr.Arthanreeswaran, NIT, Trichy, arthanareeg@nitt.edu	2. Dr. C. Siva, SRMIST

Course Code	18NTC350T	Course Name	COMPREHENSION				Course Category	C	Professional Core																				
									0101																				
Pre-requisite Courses	Nil		Co-requisite Courses	Nil				Progressive Courses	Nil																				
Course Offering Department		Nanotechnology				Data Book / Codes/Standards			Nil																				
Course Learning Rationale (CLR):			The purpose of learning this course is to:						Learning			Program Learning Outcomes (PLO)																	
CLR-1 :			Acquire skills to develop knowledge in nanotechnology principles						Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLR-2 :			Acquire skills to understand quantum mechanical concepts of free electron and band theory of solids																										
CLR-3 :			Acquire skills in size effects and reaction kinetics at nanoscale																										
CLR-4 :			Acquire skills in various imaging techniques related to the field of nanotechnology																										
CLR-5 :			Acquire skills in chemistry of biological molecules																										
CLR-6 :			Acquire skills in knowing the electronic property of materials in mesoscopic level																										
Course Learning Outcomes (CLO):			At the end of this course, learners will be able to:																										
CLO-1 :	Practice and gain confidence and competence to solve problems in statistical mechanics & thermodynamics						3	85	80	H	H	H	L	L	L	L	L	L	L	L	L	L	L	L	M	M	M	M	M
CLO-2 :	Practice and gain confidence and competence to solve many body problems using various quantum phenomenon & assumptions						3	85	80	H	H	M	L	L	L	L	L	L	L	L	L	L	L	L	M	M	M	M	M
CLO-3 :	Practice and gain confidence and competence to solve problems in biophysical principles and dynamics involved in biological systems						3	85	80	H	H	M	L	L	L	L	L	L	L	L	L	L	L	L	M	M	M	M	M
CLO-4 :	Practice and gain confidence and competence to solve problems & simulation process involved in nanoelectronics devices						3	85	80	H	H	M	L	L	L	L	L	L	L	L	L	L	L	L	M	M	M	M	M
CLO-5 :	Practice and gain confidence and competence to solve problems using spectroscopic techniques						3	85	80	H	H	H	L	L	L	L	L	L	L	L	L	L	L	L	M	M	M	M	M
CLO-6 :	Solve problems in the broad domain of Naotechnology and competitive examinations in Nanoscience & NT						3	85	80	H	H	M	L	L	L	L	L	L	L	L	L	L	L	M	M	M	M	M	
Duration (hour)	3		3		3		3		3		3		3		3		3		3		3		3		3		3		
S-1	SLO-1	Tutorial on Solid State Physics			Tutorial on Synthesis Methods of Nanomaterials			Tutorial on Nanomagnetism			Tutorial on Nanocomposite Materials			Tutorial on Nanotoxicology															
	SLO-2	Problem Solving			Problem Solving			Problem Solving			Problem Solving			Problem Solving															
S-2	SLO-1	Tutorial on Thermodynamics & Statistical Mechanics			Tutorial on Nanophotonics			Tutorial on Nanoelectronics			Tutorial on Nanobiotechnology			Tutorial on Environmental Nanoscience															
	SLO-2	Problem Solving			Problem Solving			Problem Solving			Problem Solving			Problem Solving															
S-3	SLO-1	Tutorial on Biological Principles			Tutorial on Micro and Nanofabrication			Tutorial on Polymer Technology			Tutorial on Quantum Mechanics			Tutorial on Industrial Nanotechnology															
	SLO-2	Problem Solving			Problem Solving			Problem Solving			Problem Solving			Problem Solving															
Learning Resources		1. Sulabha K. Kulkarni, Nanotechnology: Principles and Practices, 3 rd Edition, Springer, 2015																											
Learning Assessment																													
	Bloom's Level of Thinking	Continuous Learning Assessment (100% weightage)																Final Examination											
		CLA – 1 (20%)				CLA – 2 (30%)				CLA – 3 (30%)				CLA – 4 (20%)#															
		Theory		Practice		Theory		Practice		Theory		Practice		Theory		Practice		Theory		Practice			Theory		Practice				
Level 1	Remember	-		40%		-		30%		-		30%		-		30%		-		30%			-		-				
Level 2	Understand	-		40%		-		40%		-		40%		-		40%		-		40%			-		-				
	Apply	-		40%		-		40%		-		40%		-		40%		-		40%			-		-				
Level 3	Analyze	-		20%		-		30%		-		30%		-		30%		-		30%			-		-				
	Evaluate	-		20%		-		30%		-		30%		-		30%		-		30%			-		-				
	Create	-		20%		-		30%		-		30%		-		30%		-		30%			-		-				
	Total	100 %		100 %		100 %		100 %		100 %		100 %		100 %		100 %		100 %		100 %		100 %		100 %		100 %			
# CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,																													
Course Designers																													
Experts from Industry														Experts from Higher Technical Institutions										Internal Experts					
1. Dr. M. Krishna Surendra, Saint-Gobain Research, Chennai, krishna.muvvala@saint-gobain.com														1. Prof. S. Balakumar, University of Madras, balakumar@unom.ac.in										1. Dr. Angeline Littleflower, SRMIST					
2. Dr. M. Sathish, CSIR-CECRI, Karaikudi, msathish@cecri.res.in														2. Prof. S. Ramaprabhu, IIT Madras, ramp@iitm.ac.in										2. Dr. S. Chandramohan, SRMIST					

ACADEMIC CURRICULA

Professional Elective Courses

Regulations - 2018



SRM INSTITUTE OF SCIENCE AND TECHNOLOGY

(Deemed to be University u/s 3 of UGC Act, 1956)

Kattankulathur, Kancheepuram, Tamil Nadu, India

ACADEMIC CURRICULA

Professional Elective Courses

AEROSPACE ENGINEERING

Regulations - 2018



SRM INSTITUTE OF SCIENCE AND TECHNOLOGY

(Deemed to be University u/s 3 of UGC Act, 1956)

Kattankulathur, Kancheepuram, Tamil Nadu, India

Course Code	18ASE201T	Course Name	INDUSTRIAL AERODYNAMICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18ASC202J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Aerospace Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Understand the application of aerodynamics in fields other than Aerospace				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2 :	understand effect of terrain types on the wind flows				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3		
CLR-3 :	understand the concepts on wind energy and wind turbine aerodynamics							H	M	L	L	-	-	M	-	-	-	-	-	-	-	-	M	L
CLR-4 :	Understand how buildings are affected by wind flows and how to mitigate the unwanted aerodynamic forces							H	M	M	L	-	-	M	-	-	-	-	-	-	-	H	M	M
CLR-5 :	Understand how aerodynamics plays a major role in streamlining and drag reduction of automobiles							H	L	L	L	-	-	H	-	-	-	-	-	-	-	-	M	M
CLR-6 :	Understand the role of aerodynamics in sports balls and vortex induced vibrations							H	L	L	L	-	-	-	-	-	-	-	-	-	-	H	H	H
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			2	80	70	H	L	M	L	-	-	M	-	-	-	-	M	M	M			
CLO-1 :	Understand different aspects of atmosphere and atmospheric boundary layer				2	80	70	H	M <td>L<td>L<td>-</td><td>-</td><td>M</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>M</td><td>L</td></td></td>	L <td>L<td>-</td><td>-</td><td>M</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>M</td><td>L</td></td>	L <td>-</td> <td>-</td> <td>M</td> <td>-</td> <td>-</td> <td>-</td> <td>-</td> <td>-</td> <td>M</td> <td>L</td>	-	-	M	-	-	-	-	-	M	L			
CLO-2 :	Acquire knowledge on Atmospheric boundary layer in a wind tunnel				2	80	70	H	M	M	L <td>-</td> <td>-</td> <td>M</td> <td>-</td> <td>-</td> <td>-</td> <td>-</td> <td>H</td> <td>M</td> <td>M</td>	-	-	M	-	-	-	-	H	M	M			
CLO-3 :	Learn the working principles of wind turbines				2	80	70	H	L	L	L <td>-</td> <td>-</td> <td>H</td> <td>-</td> <td>-</td> <td>-</td> <td>-</td> <td>-</td> <td>M</td> <td>M</td>	-	-	H	-	-	-	-	-	M	M			
CLO-4 :	Appreciate the usefulness of drag reduction devices				2	80	70	H	L	L	L <td>-</td> <td>-</td> <td>-</td> <td>-</td> <td>-</td> <td>-</td> <td>-</td> <td>H</td> <td>H</td> <td>H</td>	-	-	-	-	-	-	-	H	H	H			
CLO-5 :	Gain knowledge on building aerodynamics				2	80	70	H	L	M	L <td>-</td> <td>-</td> <td>M</td> <td>-</td> <td>-</td> <td>-</td> <td>-</td> <td>M</td> <td>M</td> <td>M</td>	-	-	M	-	-	-	-	M	M	M			
CLO-6 :	Acquire comprehensive understanding on sports aerodynamics				2	80	70	H	M	L	L <td>-</td> <td>-</td> <td>-</td> <td>-</td> <td>-</td> <td>-</td> <td>-</td> <td>M</td> <td>M</td> <td>M</td>	-	-	-	-	-	-	-	M	M	M			

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Aerodynamics / Aviation Aerodynamics / Non-Aviation Aerodynamics	Need for renewable energy sources	Rolling resistance Vs Air resistance	Aerodynamics of race cars	Introduction to building aerodynamics
	SLO-2	Introduction to Industrial Aerodynamics	Wind energy and its importance	Need for automotive aerodynamics	Ground effects	Environmental winds in city blocks
S-2	SLO-1	Need for Industrial Aerodynamics	Wind turbine and its parts	History of Automotive Aerodynamics	Down force generation	Low-rise buildings (LRB)
	SLO-2	Branches of Industrial Aerodynamics	Classification of wind turbines	Evolution of Automobile styling	Frontal and rear wings	Roof suction effects
S-3	SLO-1	Atmospheric layers	Horizontal axis wind turbine (HAWT)	Classification of cars	Aerodynamic braking - Spoilers	High-rise buildings (HRB)
	SLO-2	Atmospheric circulations	Advantages and disadvantages of HAWT	Pressure distribution over cars	Aerodynamics of wheels	Dynamic loads
S-4	SLO-1	Local winds	Vertical axis wind turbine (VAWT)	Aerodynamic forces on Automobiles	Introduction to sports aerodynamics	Aerodynamic load mitigation techniques for LRB
	SLO-2	Terrain types	Advantages and disadvantages of VAWT	Lift, Drag and Moments	Aerodynamics of Cricket ball	Aerodynamic load mitigation techniques for HRB
S-5	SLO-1	Atmospheric Boundary Layer (ABL)	Wind power, Power coefficient	Sources of vortices in automobiles	Swing and Spin	Flow over a simplified building
	SLO-2	Aerodynamic Roughness length	Tip speed ratio, Solidity ratio	Flow separation and wake dynamics	Effect of dimples on golf ball	Pressure distribution
S-6	SLO-1	Mean velocity profiles	1-D Momentum theory	Aerodynamic Improvements	Vortex shedding	Wind loads – TVL Formula
	SLO-2	Power-law and Logarithmic law	Betz limit	Aerodynamics Vs Styling - Limitations	Strouhal number	Funneling effect
S-7	SLO-1	Variation of wind velocity with height in ABL for different terrain types	Power losses	Aerodynamics of motor bikes	Flow induced vibrations	Ventilation
	SLO-2	Turbulence Intensity and its variation in ABL	Energy density of different rotors	Aerodynamics of roofless vehicles	Fluid-structure interactions	HVAC
S-8	SLO-1	Need for ABL simulation	Aerodynamic power control	Aerodynamics of Trucks and Buses	Effect of Reynolds number on wake	Architectural Aerodynamics
	SLO-2	Boundary layer tunnels	Methods for power control	Aerodynamics of Trains	Aerodynamic flutter	Wind catchers
S-9	SLO-1	Simulation of ABL in a wind tunnel	Blade sections - Airfoils	Ahmed body – Generic automobile shape	Wake galloping	Building codes
	SLO-2	Methods to produce ABL	Wind turbine siting	Wind tunnel experiments and simulations	Vortex shedding control methods	Loads on launch vehicles subjected to winds

Learning Resources	1. Tom Lawson, <i>Building aerodynamics</i> : Imperial College Press, 2001. 2. Joseph Katz, <i>Automotive Aerodynamics</i> , John Wiley & Sons, 2016. 3. Joseph Katz, <i>Race Car Aerodynamics</i> , Robert Bentley, 1995 4. Erich Hau., <i>Wind turbines: fundamentals, technologies, application, economics</i> . Springer Science & Business Media, 2013.	5. Martin OL Hansen, <i>Aerodynamics of wind turbines</i> . Routledge, 2015. 6. Robert D Blevins, <i>Flow-induced vibration</i> . Van Nostrand Reinhold Co., 1977. 7. Helge Nørstrud, <i>Sport aerodynamics</i> . Springer Science & Business Media, 2009.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Dr. C. Palani Kumar, CFD Application Expert, DJAIR, Korea. Email: kumar@djair.co.kr	1. Dr. Arun Kumar Perumal, Mechanical Eng, IIT Jammu, arun.perumal@iitjammu.ac.in	1. Dr. Bharadwaj K K, SRMIST
		2. Dr. Kannan B T, SRMIST

Course Code	18ASE202T	Course Name	APPLIED STRUCTURAL MECHANICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18ASC201J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Aerospace Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	To familiarize the concept of external load acting on a rigid airplane.	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	To familiarize the concept of statically indeterminate beams.		
CLR-3 :	To familiarize with various energy methods.		
CLR-4 :	To familiarize with the columns.		
CLR-5 :	To study the concepts of failure theories.		
CLR-6 :	Utilize the concepts in better understanding of various structural elements dealing with loads.		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Engineering Knowledge
CLO-1 :	Determine the forces or loads acting on an accelerated airplane.	2 80 70	H H H H - - - - - - M M M M
CLO-2 :	Determine the fixed end moments and plot shear force and bending moment diagram.	2 85 75	H H H H - - - - - - M M M M
CLO-3 :	Determine the deflection of various structures by different energy methods.	2 75 70	H H H H - - - - - - M M M M
CLO-4 :	Determine the buckling load of a column under various end conditions.	2 85 80	H H H H - - - - - - M M M M
CLO-5 :	Application of theorem of three moments to solve for statically indeterminate beams.	2 85 75	H H H H - - - - - - M M M M
CLO-6 :	Apply the concepts of theories of failure to determine the safe design.	3 80 70	H H H H - - - - - - M M M M

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Introduction to limit loads, design loads and factor of safety.	Continuous beam concept. Derivation of Clapeyron's equation of three moments.	Derivation of Strain Energy stored due to axial, bending and Torsional loads.	Introduction to columns and its classification. Buckling load, factor of safety.
	SLO-2	Broad classification of external loads on a conventional aircraft.	Application of Clapeyron's equation of three moments to continuous beam with simply supported ends.	Strain Energy stored due to shear loads, The theorem of Complementary Energy and Castigliano's Theorem.	Failure of a short and long column, Euler's theory for long columns.
S-2	SLO-1	Problems involving accelerated motion of rigid airplane.	Problem solving	Derivation of Castigliano's theorem I and II, Maxwell's Reciprocal theorem	Assumptions followed in Euler's theory for long columns. Different end conditions of a column, concept of buckling stress.
	SLO-2		Application of Clapeyron's equation of three moments to continuous beam with fixed end supports.	Application of Castigliano's theorem – I to find deflection of beams.	Derivation of Euler's formula for crippling load when both ends are hinged
S-3	SLO-1	Landing Gear Structure	Problem solving	Problem solving	Derivation of Euler's formula for crippling load when both ends are fixed
	SLO-2	Problems of Calculating Reactions and Loads on Members of Landing Gear Units	Application of Clapeyron's equation of three moments to continuous over-hanging beam.	Problem solving	Derivation of Euler's formula for crippling load when one end fixed and the other hinged end.
S-4	SLO-1	Problem solving	Problem solving	Differences between statically determinate and statically indeterminate structures with examples	Derivation of Euler's formula for crippling load when one end fixed and the other I free.
	SLO-2	Torque link	Application of Clapeyron's equation of three moments to continuous beam with one end fixed and other one simply supported end.	Application of Castigliano's theorem – II to find deflection of trusses.	Limitations of Euler's formula, slenderness ratio and equivalent length of a column.
S-5	SLO-1	Main forces on the airplane in an accelerated flight condition.	Problem solving	Problem solving	Problems to solve for crippling load using Euler's formula

	SLO-2	Loads on structural components	Derivation for Moment distribution method, stiffness factor, Distribution factor, carry over factor.	Problem solving	Problems to solve for crippling load using Euler's formula	Maximum Strain energy theory : Problem solving
S-6	SLO-1	Function of structural components	Application of Moment distribution method to continuous beam with simply supported ends.	Strain energy methods to find deflection in simply supported beams	Derivation: Column with initial curvature	Maximum Shear Strain energy theory: Derivation.
	SLO-2	Fabrication of structural components	Problem solving	Strain energy methods to find deflection in cantilever beams	Derivation: Column with an Eccentric loading.	Maximum Shear Strain energy theory: Problem solving
S-7	SLO-1	Safe life and fail-safe structures	Application of Moment distribution method to continuous beam with fixed end supports.	Unit load method to find member forces in a single redundant trusses/frames.	Problem solving	Important points from theories of failures used in design
	SLO-2	Aircraft inertia loads - Problems	Problem solving	Problem solving	Rankine's formula for columns and associated problems.	Problems on thin cylindrical shells on design criterion
S-8	SLO-1	Fixed and continuous beam – Introduction, Bending moment diagram for fixed beams	Application of Moment distribution method to continuous beam with one end fixed and other one simply supported end.	Problem solving	Long and short columns - Modes of failure	Problems on thick cylindrical shells on design criterion
	SLO-2	Slope and deflection for a fixed beam carrying point load at the middle	Problem solving	Unit load method to find member forces in double redundant trusses/frames.	Introduction to Beam columns and its applications	Graphical representation of Maximum Principal stress and strain theory
S-9	SLO-1	Slope and deflection for a fixed beam carrying an eccentric point load.	Application of Moment distribution method to continuous over-hanging beam.	Problem solving	Member subjected to combined axial and transverse loads – Point load at the middle and an eccentric load	Graphical representation of Maximum Shear stress and strain energy theory
	SLO-2	Slope and deflection for a fixed beam carrying uniformly distributed load over the entire length.	Problem solving	Problem solving	Member subjected to combined axial and transverse loads – Uniformly Distributed Load.	Graphical representation of Maximum Shear strain energy theory

Learning Resources	1	Rajput R. K., "Strength of Materials", S.Chand publications, Sixth Edition, 2015.	3.	E. F. Bruhn, "Analysis and Design of Flight Vehicle Structures", Tri-State Offset Company (U.S.A),1973
	2.	John Case, and A.H.Chilver, "Strength of Materials and structures", Edward Arnold Publishers Ltd., 2016.		

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	40%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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2. Dr.A. Sakthivel, CEMILAC, Bangalore, asakthironika@gmail.com	2. Dr. R.Velmurugan, Indian Institute of Technology Madras, rvel@ae.iitm.ac.in	Dr.T.Selvakumaran,SRMIST

Course Code	18ASE203T	Course Name	EXPERIMENTAL STRESS ANALYSIS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18PYB101J, 18ASC201J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Aerospace Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand the various aspects of measurements	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15			
CLR-2 :	Understand the different physical principles of strain measuring instruments.																					
CLR-3 :	Identify the different materials for resistance type strain gages																					
CLR-4 :	Know the various circuits for strain measuring purpose.																					
CLR-5 :	Know the principles and materials in photo elastic concepts.																					
CLR-6 :	Understand the various non-destructive testing methods.																					

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1:	Describe the measuring process of various instruments	2	85	75	H	-	H	H	L	H	H	H	-	-	-	M	M	M	M
CLO-2:	Describe about the various strain measuring devices	2	85	75	H	H	H	H	-	H	H	H	-	-	-	M	M	M	M
CLO-3:	Explain the physical principle and circuits used in resistance type strain gages	2	85	75	H	-	H	H	-	H	H	H	-	-	-	M	M	M	M
CLO-4:	Explain the rosette analysis	2	85	75	H	H	-	H	-	H	H	H	-	-	-	M	M	M	M
CLO-5:	Describe the various photo elastic concepts of stress measurements	2	85	75	H	-	H	H	-	H	H	H	-	-	-	M	M	M	M
CLO-6:	Explain the various non destructive methods of flaw detection	2	85	75	H	H	H	H	-	H	H	H	-	-	-	M	M	M	M

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction-Stress and strain	Properties of strain gage system	Introduction to resistance strain gage	Introduction to photoelasticity	NDT method-Introduction
	SLO-2	Introduction- Relation between stresses and strains for different materials	Basic characteristics of strain gage	Principle of operation of the resistance strain gage, Strain sensitivity	wave plates, polarized light	Classification of flaws, Steps in NDT
S-2	SLO-1	Principles of measurements	Huggenberger tensometer	Materials for resistance strain gage, Advance alloy, Isoelastic alloy, Karma alloy and other materials	Stress optic law	Fluorescent penetrant technique
	SLO-2	Aspects of measurements	Advantages and disadvantages, limitations	Types of electrical resistance strain gages- Unbonded wire strain gage, Bonded wire strain gage	Strain optic law	Magnetic particle inspection
S-3	SLO-1	Fundamental methods of measurements	Diffraction strain gage	Types of resistance strain gage-Bonded foil strain gage, Weldable strain gage	Plane polariscope , Derivation of intensity of light in circular polariscope	Eddy current testing
	SLO-2	Generalized measuring system	Advantages and disadvantages	Strain gage adhesives, Selection, Properties and types	Effect of stressed model in plane polariscope	Radiography
S-4	SLO-1	Accuracy and Precision	Interferometric strain gage	Mounting methods-Gage installation, Curing	Circular polariscope	Ultrasonic inspection
	SLO-2	Repeatability and Reproducibility	Advantages and disadvantages	Temperature compensation, Gage sensitivity, Gage factor	Derivation of intensity of light in circular polariscope	A scan, B scan and C scan
S-5	SLO-1	Tolerance and Range	Tuckerman strain gage	Strain gage circuits, Potentiometer circuit	Effect of stressed model in a circular polariscope	Thermography
	SLO-2	Bias and Linearity	Advantages and disadvantages	Temperature compensation ,sensitivity and range in potentiometer circuit	Explanation of fringe patterns	Holography
S-6	SLO-1	Sensitivity explanation	Capacitance strain gage	Wheatstone bridge circuit	Compensation techniques- Babinet soleil method of compensation	Acoustic emission technique
	SLO-2	Numerical solving	Advantages and disadvantages	Derivation of output voltage	Tardy method of compensation	Moire method of strain analysis
S-7	SLO-1	Hysteresis	Inductance strain gage	Circuit sensitivity and different arrangements in wheat stone bridge circuit	Fringe separation methods-Shear difference method, Interferometer method	Methods

	SLO-2	Dead space, Threshold and Resolution	Advantages and disadvantages	Rosette analysis, Different conditions of strain measurements	Electrical analogy method, Oblique-incidence method	Moire fringe pattern
S-8	SLO-1	Error Analysis- Classification	Semiconductor strain gage	Three element rectangular rosette	Fringe multiplication method	Physical explanation of moiré fringe pattern
	SLO-2	Error analysis- Sources	Advantages and disadvantages	Delta rosette	Explanation of fringe multiplication	Brittle coating methods
S-9	SLO-1	Error analysis numerical	Acoustical strain gage	Four element rectangular rosette	Properties of photoelastic materials	Types of brittle coating methods
	SLO-2	Calibration	Advantages and disadvantages	Tee delta rosette	Explanation of different photoelastic materials	Advantages and disadvantages of brittle coating methods

Learning Resources	1. Dally, J.W., and Riley, W.F., <i>Experimental Stress Analysis</i> , McGraw Hill Inc., New York, 1978 2. Hetenyi, M., <i>Hand Book of Experimental Stress Analysis</i> , John Wiley and Sons Inc., New York, 1972	3. Srinath, L.S., Raghava, M.R., Lingaiah, K.Gargesha, G.Pant B., and Ramachandra, K., <i>Experimental Stress Analysis</i> , Tata McGraw Hill, New Delhi, 1984 4. Pollock, A.A., <i>Acoustic Emission in Acoustics and Vibrations Progress</i> , ed. By Stephens R.W.B., Chapman and Hall, 1983
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. G.Balamurugan, National Aerospace Laboratories, Bangalore, gbala@nal.res.in	1. Dr. V.Arumugam, Madras Institute of Technology, Chennai, arumugam.mitaero@gmail.com	1. Dr. L.R. Ganapathi Subramanian, SRMIST
2. Dr.A. Sakthivel, CEMILAC, Bangalore, asakthirionika@gmail.com	2. Dr. R.Velmurugan, Indian Institute of Technology Madras, rvel@ae.iitm.ac.in	2. Mr. S. Chandra Sekhar, SRMIST

Course Code	18ASE204T	Course Name	COMPOSITE MATERIALS AND STRUCTURES	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18ASC201J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Aerospace Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 : Identify Composite materials		Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 : Understand the mechanical behavior of composite materials					Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3			
CLR-3 : Understand the existing production technologies																						
CLR-4 : Identifying the selection of materials																						
CLR-5 : Identify material's Application																						
CLR-6 : Understand the application of various composites																						
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	Aware of the composite materials and it properties	2	80	70	H	H	-	-	-	-	-	-	-	-	-	-	-	M	M	M	M	
CLO-2 :	Understands application of composite materials in different aircraft components	2	85	75	H	H	-	-	H	-	-	-	-	-	-	-	-	M	M	M	M	
CLO-3 :	Identify different treatments to strengthen materials	2	75	70	H	-	H	H	-	-	-	-	-	-	-	-	-	M	M	M	M	
CLO-4 :	Understand molding techniques	2	85	80	H	H	-	-	H	-	-	-	-	-	-	-	-	M	M	M	M	
CLO-5 :	Understand Various terminologies used in composite Materials	2	85	75	H	-	H	-	-	-	-	-	-	-	-	-	-	M	M	M	M	
CLO-6 :	Understand forming Techniques	2	80	70	H	-	-	-	-	-	-	-	-	-	-	-	-	M	M	M	M	

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction to Composite Materials	Hooke's law for Isotropic Materials	Micro Mechanics	Governing differential equation of general laminate	Manufacturing of Glass fibers
	SLO-2	Natural Composites	Numericals solving	Micro Mechanics		Block diagram of Manufacturing
S-2	SLO-1	Basic Definitions	Generalized Hooke's law	Derivation of Volume Fraction, Mass Fraction	Angle ply laminates	Manufacturing of Carbon Fibers
	SLO-2	Basic Definitions	Numericals solving	Density and Void Content	Cross ply laminates	Block diagram of Manufacturing
S-3	SLO-1	Introduction to Fibers	Hooke's law for 3D Orthotropic Materials	Numericals solving	Numericals solving	Fabrication of Composite Materials
	SLO-2	Types of Fibers	Hooke's law for 3D Orthotropic Materials	Numericals solving	Numericals solving	Molding Techniques
S-4	SLO-1	Matrices	Numericals solving	Strength of Materials approach	Laminate Codes	Hand Layup Process
	SLO-2	Types of Matrices		Evaluation of four Elastic Modulii	Laminate Codes	Spray layup process
S-5	SLO-1	Properties of Fibers	Hooke's law for 2D Unidirectional lamina	Numericals solving	Special cases of laminates	Compression Molding
	SLO-2	Properties of Matrices		Numericals solving	ABD Matrix representation	Resin Transfer molding
S-6	SLO-1	Classification of Composite Materials	Numericals solving	Elasticity approach to determine Material Properties	Maximum Stress failure theory	Vacuum Bag and Pressure bag Mödling
	SLO-2	Block Diagram of Classification	Numericals solving		Maximum Strain failure theory	Autoclave Processing
S-7	SLO-1	Application of Composites	Hooke's law for 2D Angle Lamina	Macro Mechanics	Tsai Hill failure theory	Filament winding process
	SLO-2	Application of Composites		Macro mechanics	Tsai wu failure theory	Pultrusion Process
S-8	SLO-1	Hooke's Law	Numericals solving	Stress strain relationship with respect to neutral axis and arbitrary axis	Basic concept of sandwich construction	Types of resins
	SLO-2	Basics of Hooke's Law	Numericals solving		Materials used in sandwich construction	Properties and Applications
S-9	SLO-1	Numericals solving	Numericals solving	Experimental characterization of Lamina	Failure modes of Sandwich panels	Netting Analysis
	SLO-2					

Learning Resources	1. Autar K Kaw, "Mechanics of Composite Materials" CRC Press, Taylor and Francis Group 2005.	3. Agarwal.B.D. and Broutman.L.J, "Analysis and Performance of Fibre Composites", John Wiley and sons. Inc., New York, 1995
	2. Jones.R.M, "Mechanics of Composite Materials", McGraw-Hill, Kogakusha Ltd., Tokyo, 1985.	4. Lubin.G, "Handbook on Advanced Plastics and Fibre Glass", Von Nostrand Reinhold Co., New York, 1989

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

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2. Dr.A. Sakthivel, CEMILAC, Bangalore, asakthironika@gmail.com	2. Dr. R.Velmurugan, Indian Institute of Technology Madras, rvel@ae.iitm.ac.in	Mr. N. Bharat, SRMIST

Course Code	18ASE205T	Course Name	THEORY OF PLATES AND SHELLS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18ASC304J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Aerospace Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1:	Identify Plates and Shells	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2:	Understand the mechanical behavior of Plates and shells		
CLR-3:	Understand the existing technologies		
CLR-4:	Identifying the selection of materials		
CLR-5:	Identify Plates Application		
CLR-6:	Understand the application of various Plates and shells		

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1:	Aware of the plates and shells and its properties	2	80	70	H	H	-	-	-	-	-	-	-	-	-	M	M	M	M
CLO-2:	Understands application of plates and shells in different aircraft components	2	85	75	H	H	-	-	H	-	-	-	-	-	-	M	M	M	M
CLO-3:	Identify different treatments to strengthen materials	2	75	70	H	-	H	H	-	-	-	-	-	-	-	M	M	M	M
CLO-4:	Understand Problem solving techniques	2	85	80	H	H	-	-	H	-	-	-	-	-	-	M	M	M	M
CLO-5:	Understand Various terminologies used in Plates and shells	2	85	75	H	-	H	-	-	-	-	-	-	-	-	M	M	M	M
CLO-6:	Understand forming Techniques	2	80	70	H	-	-	-	-	-	-	-	-	-	-	M	M	M	M

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction	Plates of Various shapes	Eigen value analysis	Approximate Methods	Introduction to shells
	SLO-2	Classical Plates theory				
S-2	SLO-1	Classical Plates theory- Assumptions	Leavy's Method of Solution for Rectangular Plates under Different Boundary Conditions	Stability of Rectangular Plates	Rayleigh – Ritz Method	Basic Concepts of Shell Type of Structures
	SLO-2	Theory				
S-3	SLO-1	Classical Plates theory-Differential equations	Leavy's Method of Solution for Rectangular Plates under Different Boundary Conditions- governing equations	Free Vibration Analysis of Rectangular Plates	Numericals solving	Membrane Theories for Circular Cylindrical Shells.
	SLO-2					
S-4	SLO-1	Classical Plates theory – Boundary conditions	Solution for Axi-symmetric loading	Numericals solving	Galerkin Methods	Bending Theories for Circular Cylindrical Shells.
	SLO-2					
S-5	SLO-1	Naviers method of solution for simply supported Rectangular plates	Numericals solving	Bending Theory of Plates	Finite Difference Method	Governing Equation for Buckling of Cylindrical Shells
	SLO-2					
S-6	SLO-1	Differential equation for cylindrical bending of plates	Annular Plates	Numericals solving	Numericals solving	Derivation of the Linearized Buckling Equation
	SLO-2					
S-7	SLO-1	Cylindrical Bending of Uniformly Loaded Rectangular Plates with Simply Supported Edges	Numericals solving	Bending-Membrane Theory of Plates	Application to Rectangular Plates for Static Analysis	Buckling under Axial Compression
	SLO-2					
S-8	SLO-1	Cylindrical Bending of Uniformly Loaded Rectangular Plates with Built-in Edges	Introduction to plates of other shapes	Numericals solving	Application to Rectangular Plates for free vibration analysis	Formulation for Buckling Stress and Buckling Mode
	SLO-2					
S-9	SLO-1	Cylindrical Bending of Uniformly Loaded Rectangular Plates with Elastically Built-in Edges	Theory of plates of other shapes	Equilibrium Equation and Boundary Conditions	Application to Rectangular Plates for stability analysis	Buckling Coefficient and Batdorf Parameter
	SLO-2					

Learning Resources	1. Timoshenko, S.P. Winowsky. S., and Kreger, "Theory of Plates and Shells", McGraw-Hill Book Co. 1990. 2. T. K. Varadan and K. Bhaskar, "Theory of Plates and Shells", 1999, Narosa.	3. Flugge, W. "Stresses in Shells", Springer – Verlag, 1985. 4. Timoshenko, S.P. and Gere, J.M., "Theory of Elastic Stability", McGraw-Hill Book Co. 1986
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

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2. Dr.A. Sakthivel, CEMILAC, Bangalore, asakthironika@gmail.com	2. Dr. R.Velmurugan, Indian Institute of Technology Madras, rvel@ae.iitm.ac.in	Mr. N. Bharat, SRMIST

Course Code	18ASE206T	Course Name	THEORY OF ELASTICITY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18ASC304J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Aerospace Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1:	Understand the various assumption in solving elasticity problems, equilibrium equations	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2:	Familiarize with stress-strain relations, strain-displacement relations, compatibility equations		
CLR-3:	Understand the solutions by polynomials, stresses & displacements for simple, cantilever beams.		
CLR-4:	Familiarize with problems in polar coordinates for axisymmetric problems		
CLR-5:	Know the various theory of torsion for circular, elliptical, sections.		
CLR-6:	Get a better understanding of solving elasticity problems		

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1:	Apply the knowledge to form equilibrium equations & compatibility conditions.	2	85	75	H	H	H	-	-	-	-	-	-	-	-	M	M	M	M
CLO-2:	Analyze the plane stress & plane strain problems.	2	85	75	H	H	H	-	-	-	-	-	-	-	-	M	M	M	M
CLO-3:	Apply the solutions of polynomials to solve simple two dimensional problems in Cartesian coordinate	2	85	75	H	H	H	H	-	-	-	-	-	-	-	M	M	M	M
CLO-4:	Analyze a two dimensional problems in polar coordinates.	2	85	75	H	H	H	-	-	-	-	-	-	-	-	M	M	M	M
CLO-5:	Analyze the stresses induce due to torsion for non circular cross-sections	2	85	75	H	H	H	-	-	-	-	-	-	-	-	M	M	M	M
CLO-6:	Accrue comprehensive knowledge in theory of elasticity problems	2	85	75	H	H	H	H	-	-	-	-	-	-	-	M	M	M	M

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Introduction to Theory of Elasticity	Introduction to equations of elasticity	Airy's stress function	Equations of equilibrium in polar coordinates	Introduction to torsion of non-circular members
	SLO-2 Definitions of stress & strain	Stress-strain relations	Biharmonic equation equations	Equations of equilibrium in polar coordinates	Saint-Venant's theory of torsion
S-2	SLO-1 Sign conventions, notations for stress & strain	Lame's constant-cubical dilatation	Solutions by polynomials of second degree	Stress-strain relations	General solutions of torsion problems
	SLO-2 Sign conventions, notations for stress & strain	Lame's constant-cubical dilatation	Solutions by polynomials of second degree.	Strain components in polar coordinates	General solutions of torsion problems
S-3	SLO-1 Components of stress	Compressibility of materials, Bulk Modulus	Solutions by polynomials of third degree	Strain-displacement relations	Boundary conditions
	SLO-2 Generalized Hooke's Law	Solving problems	Solutions by polynomials of third degree	Strain-displacement relations	Conditions at the end of a twisted bar
S-4	SLO-1 Components of strain	Compatibility equations for plane stress with constant body force	Solutions by polynomials of fourth degree	Equations of compatibility in polar coordinates.	Solving problems
	SLO-2 Solving problems	Compatibility equations for plane stress with general body force.	Solutions by polynomials of fourth degree	Equations of compatibility in polar coordinates.	Applications of shafts of elliptical cross-sections
S-5	SLO-1 Stress at a point	Compatibility equations for plane strain with constant body force.	Solutions by polynomials of fifth degree	Solving problems	Solving problems
	SLO-2 Boundary conditions	Compatibility equations for plane stress with general body force.	Solutions by polynomials of fifth degree	Solving problems	Solving problems
S-6	SLO-1 Strain at a point	Principal stresses and strain	Stresses due to bending of a cantilever beam in Cartesian coordinate	Stress distribution symmetrical about an axis	Applications of shafts of rectangular cross-sections
	SLO-2 Solving Problems	Solving problems	Stresses due to bending of a cantilever beam in Cartesian coordinate	Stress distribution symmetrical about an axis	Applications of shafts of rectangular cross-sections
S-7	SLO-1 Equations of equilibrium in 2D	Mohr's circle for plane stress	Displacements due to bending of a cantilever beam in Cartesian coordinate	Stress distribution in pure bending of curved bars	Solving problems
	SLO-2 Solving problems	Solving problems	Displacements due to bending of a cantilever beam in Cartesian coordinate	Stress distribution in pure bending of curved bars	Solving problems

S-8	SLO-1	Equations of equilibrium in 3D	Mohr's circle for plane strain	Stresses due to bending of a simply supported beam in Cartesian coordinate	Stress distribution in rotating disc	Applications of shafts of equilateral cross-sections
	SLO-2	Solving problems	Solving problems	Stresses due to bending of a simply supported beam in Cartesian coordinate	Stress distribution in rotating disc	Applications of shafts of equilateral cross-sections
S-9	SLO-1	Index notations for stress & strain	Saint-Venant's Principle	Displacements due to bending of a simply supported beam in Cartesian coordinate	Solving problems	Solving problems
	SLO-2	Solving problems	Solving problems	Displacements due to bending of a simply supported beam in Cartesian coordinate	Solving problems	Solving problems

Learning Resources	1. Timoshenko, S.P and Goodier J.N., Theory of Elasticity, McGraw-Hill Education, Third Edition., 2017	3. Wang, C.T., Applied Elasticity, Mc-Graw-Hill Co., New York 1993
	2. Enrico Volterra and J.H.Caines, Advanced Strength of Materials, Prentice Hall, New Jersey, 1991.	4. Sokolnikoff, IS., Mathematical Theory of Elasticity, Mc-Graw-Hill Co., New York 1978.

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

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Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. G.Balamurugan, National Aerospace Laboratories, Bangalore, gbala@nal.res.in	1. Dr. V.Arumugam, Madras Institute of Technology, Chennai, arumugam.mitaero@gmail.com	1. Dr.L.R.Ganapathy Subramanian, SRMIST
2. Dr.A. Sakthivel, CEMILAC, Bangalore, asakthironika@gmail.com	2. Dr. R.Velmurugan, Indian Institute of Technology Madras, rvel@ae.iitm.ac.in	2. Mr. S. Chandra Sekhar, SRMIST

Course Code	18ASE207T	Course Name	FUNDAMENTALS OF COMBUSTION	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18ASC102J, 18ASC103T	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Aerospace Engineering	Data Book / Codes/Standards	Thermodynamic properties table of C-H-N-O system		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1:	Identify the chemistry of combustion, the efficiency of burning processes and about pollutant emissions.	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2:	Identify the applications of basic thermal and fluid sciences on Engineering systems.		
CLR-3:	Identify the significance of material identification for industrial applications, including burners and engines.		
CLR-4:	Create insights to the combustion in engines and gas turbines, controlled experimentation and computational combustion.		
CLR-5:	Analyze the principle of normal and microgravity flames for space activities and fire safety.		
CLR-6:	Utilize the combustion concepts for the broad understanding of system testing, validation and designing.		

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1:	Understand the combustion phenomenon and its applications to Aerospace Engineering.	2	80	70	H	M	L	L	-	-	-	-	-	-	-	H	-	-	-
CLO-2:	Comprehend the concept and applications of the fundamental combustion parameters.	2	80	70	H	M	M	M	-	-	L	-	-	L	-	H	M	M	M
CLO-3:	Understand combustion regimes: flame and detonation, premixed and diffusion combustion problems with applications.	2	80	70	H	M	L	M	-	-	-	-	L	-	-	H	-	-	-
CLO-4:	Understand the chemical kinetics, chain reactions and related processes.	2	80	70	H	M	M	M	-	-	M	M	M	M	L	H	M	M	M
CLO-5:	Utilize the physical understanding of flame speed and Numerical modelling of combustion processes.	2	80	70	H	M	M	M	M	L	L	-	L	M	L	H	M	M	M
CLO-6:	Understand normal and microgravity flames and apply the knowledge to Aerospace Engineering Applications.	2	80	70	H	M	M	M	M	L	L	M	L	M	L	H	M	M	M

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Basic Concepts: Ideal gases, mass and mole concept, fuel and oxidizer, basics of thermodynamics.	Combustion regimes and classification of combustible materials.	Introduction to Chemical kinetics, Rate laws, order and molecularity, Forward and Reverse Reactions.	Flame classification and structures.	Combustion in Normal and microgravity.
	SLO-2	Various modes of combustion and their characteristics	Flammability limits- Flame stabilization and material identification systems.	Energy Release Rates in a Chemical Reaction, Concentration, Law of Mass Action, Arrhenius Law.	Laminar flame speed, Factors affecting flame velocity--Methods of measuring flame velocity.	Factors affecting heat transfer and flame propagation in normal and low gravity flames.
S-2	SLO-1	Combustion and thermo chemistry - Review of property relations.	Maxwell equation and parametric analysis of enthalpies and internal energy	Variations of Reaction Rate, Temperature and Concentration in a Chemical Reaction with Time.	Stability limits of laminar flames.	Fire safety, Soot formation and related implications.
	SLO-2	Laws of thermodynamics-Reactant and product mixtures.	Phase transformation, Clausius Clapeyron equation and Gibbs-Helmholtz equation.	Rate of Reactions, Temperature dependence of rate coefficients, Pressure dependence of rate coefficients.	Flame propagation through combustible mixtures.	Interactive session with demo on practical working of premixed gas burners and candle flames.
S-3	SLO-1	Solving Problems	Solving Problems	Solving Problems	Solving Problems	Solving Problems
	SLO-2	Solving Problems	Solving Problems	Solving Problems	Solving Problems	Solving Problems
S-4	SLO-1	Combustion Stoichiometry, Heat of Formation, Reaction, combustion.	Combustion products, Flow analysis and approaches.	Phase Rule for a System with Chemical Reactions. Thermodynamic Equilibrium Constant for a Gaseous Reaction.	Introduction to diffusion flames; appearance, structure, theoretical considerations.	Comparison of normal and microgravity experiments.
	SLO-2	Lower Calorific Value (LCV) and Higher Calorific Value (HCV), Relationships between Calorific Values, Reaction Enthalpies and Formation Enthalpies	Partial differential equations for combustion analysis.	Chain Reactions and Methods of Solving Chemical Kinetic Rate Equations.	Burning in convective atmospheres and Thermal spontaneous ignition.	Flame spread over thin fuels in actual and simulated microgravity conditions.
S-5	SLO-1	Thermochemical calculations: Enthalpies, Internal energy, Entropy.	Vectors and conservation equations for energy and momentum.	Solving Problems	Solving Problems	Solving Problems
	SLO-2	Chemical reaction and Stoichiometric coefficients, Air-Fuel ratio, Equivalence ratio.	Application of Mass Energy and species Conservation.	Solving Problems	Solving Problems	Solving Problems

S-6	SLO-1	Calculation of Energy Release for Stoichiometric, oxidizer-rich and fuel rich Explosives.	Solving Problems	Introduction to diffusion mass transfer.	Image processing and combustion experimentation science.	Environnemental combustion considérations.
	SLO-2	Adiabatic flame temperature calculations: Analysis and practical considerations.	Solving Problems	Transport properties for gas mixtures.	Introduction to computational combustion and relevance.	Combustion, heat transfer and emission in industrial applications.
S-7	SLO-1	Chemical equilibrium, volumetric and gravimetric analysis.	Emission reduction and techniques in combustion instruments.	Mass transfer laws, Fick's law of Diffusion.	Numerical modeling of flame spreading phenomenon	Fire safety aspects of combustion sciences.
	SLO-2	Dissociation process and related issues.	Aerospace Engineering Applications of fundamental combustion physics.	Available and non-available energy of a source and finite body.	Numerical modeling of combustion processes.	Prospects in Aerospace propulsion and combustion.
S-8	SLO-1	Solving Problems	Solving Problems	Solving Problems	Solving Problems	Solving Problems
	SLO-2	Solving Problems	Solving Problems	Solving Problems	Solving Problems	Solving Problems
S-9	SLO-1	Chapter Doubt clarification.	Chapter Doubt clarification.	Chapter Doubt clarification.	Chapter Doubt clarification.	Chapter Doubt clarification.
	SLO-2	Chapter Doubt clarification.	Chapter Doubt clarification.	Chapter Doubt clarification.	Chapter Doubt clarification.	Chapter Doubt clarification.

Learning Resources	1.	Stephen R. Turns, "An Introduction to Combustion: Concepts and Applications", 3rd Edition, McGraw-Hill Education, 2011.	4.	H.S. Mukunda., "Understanding Combustion", Universities Press, Second edition 2009.
	2.	Kenneth K Kuo, "Principles of Combustion", 2nd Edition, John Wiley and Sons, 2005.	5.	Anil W. Date., "Analytic Combustion: With Thermodynamics, Chemical Kinetics and Mass Transfer", Cambridge University Press, 2011.
	3.	D. P. Mishra., "Fundamentals of Combustion", Prentice Hall of India, New Delhi, 2008.	6.	Irvin Glassman and Richard A. Yetter., "Combustion", 4th Edition, Elsevier, 2008.

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	20%	20%	20%	20%	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. Vinay Kumar Gupta, National Physical Laboratory, guptavinay@nplindia.org	1. Prof. D.P. Mishra, IIT Kanpur, mishra@iitk.ac.in . (NPTEL- Fundamentals of Combustion)	1. Dr. T. Selvakumaran, SRMIST
2. Dr.A. Sakthivel, CEMILAC, Bangalore, asakthironika@gmail.com	2. Prof. Amit Kumar, IIT Madras, Chennai, amitk@ae.iitm.ac.in .	2. Dr. Pankaj Kumar, SRMIST

Course Code	18ASE208T	Course Name	HEAT TRANSFER	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18ASC102J, 18ASC103T	Co-requisite Courses	Nil	Progressive Courses	18ASE307T
Course Offering Department	Aerospace	Data Book / Codes/Standards	Heat & Mass Transfer Data Book, 9 th edition by C P Kothandaraman, S Subramanyan		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	To familiarize the concept of different modes of heat transfer.	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	To familiarize the concept of conduction in plane wall and cylinders	Thinking (Bloom)	Proficiency (%)	Attainment (%)	Knowledge	Analysis	Development	Design, Research	Usage	Culture	Sustainability		Team Work	Communication	Finance	Learning			
CLR-3 :	To familiarize the Utilization of extended surface & Heat Generation																		
CLR-4 :	To familiarize the concept of convection mode and it various applications																		
CLR-5 :	To familiarize the concept of Radiationmode and it various applications																		
CLR-6 :	To solve the heat transfer practical problems																		

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1:	Understand the heat diffusion equation under different coordinates	2	80	70	H	H	H	-	-	-	-	-	-	-	-	M	M	M	H
CLO-2:	Estimate the heat transfer rate in a wall, composite walls and cylindrical objects	2	85	75	H	H	H	-	-	-	-	-	-	-	-	M	M	M	H
CLO-3:	Estimate the size and numbers of extended surface or fin needed for heat transfer	2	75	70	H	H	H	-	-	-	-	-	-	-	-	M	H	M	M
CLO-4:	Estimate the heat transfer rate in forced convection & natural convection	2	85	80	H	H	H	-	-	-	-	-	-	-	-	M	M	M	H
CLO-5:	Estimate the heat transfer rate in Radiation mode	2	85	75	H	H	H	-	-	-	-	-	-	-	-	L	M	M	M
CLO-6:	To solve the heat transfer practical problems	3	80	70	H	H	H	H	-	-	M	-	-	-	-	L	M	M	H

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction to heat transfer, Different modes of heat transfer and general principles	Conduction with Thermal Energy Generation – Plane wall systems	physical mechanism on convection,	Laminar convective heat transfer analysis in flows between parallel plates	Radiation: Processes, Black body radiation- Stefan Boltzmann law, Planck's law & Wein's Displacement law
	SLO-2	Solving problems	Solving problems	classification of fluid flows,	Solving problems	Solving problems
S-2	SLO-1	Introduction to Conduction – Heat diffusion equation Cartesian systems	Conduction with Thermal Energy Generation – composite Plane wall	Governing equation: Continuity equation	Turbulent convective heat transfer analysis in flows between parallel plates	Radiation intensity
	SLO-2	Heat diffusion equation Cartesian systems - Derivation	Solving Problems	Governing equation: Momentum Equation	Solving problems	Solving problems
S-3	SLO-1	Heat diffusion equation for Cylindrical systems	Conduction with Thermal Energy Generation –radial systems	Governing equation: Energy Equation	Laminar convective heat transfer analysis in flows over a flat plate	Radiation properties, kirchoff's law
	SLO-2	Heat diffusion equation for Cylindrical systems - Derivation	Solving problems	Governing equation: Energy Equation	Solving problems	Solving problems
S-4	SLO-1	Heat diffusion equation for Spherical systems	Conduction with Thermal Energy Generation – composite radial systems	velocity and thermal boundary layer	Turbulent convective heat transfer analysis in flows over a flat plate	. Radiation shape Factors & Its relations
	SLO-2	Heat diffusion equation for Spherical systems - Derivation	Solving problems	Rayleigh number & Grashoff number	Solving problems	Solving problems
S-5	SLO-1	One-Dimensional, Steady-State Conduction – plane wall	Heat Transfer from Extended Surfaces – Rectangular circumferential Fins of Uniform Cross-Sectional Area, Fin Performance, Overall Surface Efficiency	Empirical Correlations: External Free Convection Flows over a vertical & horizontal flat plate	Laminar convective heat transfer analysis in flows over a circular pipe	Concept of black surface -Heat Exchange between two black bodies
	SLO-2	Solving Problems	Solving problems	Solving Problems	Solving problems	Solving problems
S-6	SLO-1	One-Dimensional, Steady-State Conduction – composite walls	Heat Transfer from Extended Surfaces – Cylindrical Fins of Uniform Cross-Sectional Area, Fin Performance, Overall Surface Efficiency	Empirical Correlations: External Free Convection Flows over a Inclined flat plate	turbulent convective heat transfer analysis in flows over a circular pipe	Radiation Heat Transfer in a grey surfaces - Net Radiation Heat Transfer between Any Two Surfaces
	SLO-2	Solving Problems	Solving problems	Solving Problems	Solving problems	Solving problems
S-7	SLO-1	One-Dimensional, Steady-State	Transient Conduction - The Lumped	Empirical Correlations: External Free	Laminar convective heat transfer analysis	Radiation Heat Transfer in Two-Surface

		Conduction – Radial systems	Capacitance Method,	Convection Flows over a vertical cylinder	in flows in a circular pipe	Enclosures
	SLO-2	Solving Problems	Solving Problems	Solving Problems	Solving problems	Solving problems
S-8	SLO-1	One-Dimensional, Steady-State Conduction – Spherical systems	Transient Conduction - Large walls & long cylinders	Empirical Correlations: External Free Convection Flows over a horizontal cylinder	turbulent convective heat transfer analysis in flows in a circular pipe	Radiation Heat Transfer in Three-Surface Enclosures
	SLO-2	Solving Problems	Solving Problems	Solving Problems	Solving problems	Solving problems
S-9	SLO-1	One-Dimensional, Steady-State Conduction – Radial & Spherical systems for Composite	Transient Conduction: Semi-infinite solids	Empirical Correlations: External Free Convection Flows over a Sphere	Laminar & turbulent convective heat transfer analysis in flows in a non-circular pipe	Radiation shields
	SLO-2	Solving Problems	Solving Problems	Solving Problems	Solving problems	Solving problems

Learning Resources	1. Yunus A. Cengel & Afshin J. Ghajar, "Heat & Mass Transfer", fifth Edition, McGraw-Hill, 2014 2. Theodore L. Bergman, Adrienne S. Lavine, Frank P. Incropera, David P. DeWitt, "Fundamentals of Heat and Mass Transfer", seventh Edition, John Wiley and Sons, New York, 2011	3. John H Lienhard, "A Heat Transfer Text Book", Dover publications inc, New York, 2011.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr Raja Samikkannu, Senior Principal Scientist at National Aerospace Laboratories	1. Dr.K.M.Parammasivam, Professor., MIT, Chennai, Email Id: mparams@annauniv.edu	1. Mr. K.B.Ravichandrakumar, SRMIST

Course Code	18ASE209T	Course Name	THEORY OF FIRE PROPAGATION AND SAFETY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18ASC102J, 18ASC103T	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Aerospace Engineering	Data Book / Codes/Standards			

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1:	Identify the fire dynamics, the burning processes and implications.	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2:	Identify the engineering applications of basic chemical combustion driven engineering systems.		
CLR-3:	Identify the significance of material identification for industrial applications, including burners and engines.		
CLR-4:	Create insights to the fires in engines, buildings, forests and compartments.		
CLR-5:	Analyze the fire related hazards in practical, functional, engineering, industrial applications.		
CLR-6:	Utilize the fire safety principles for system testing, validation and designing.		

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1:	Understand fire phenomenon, its applications and safety.	2	80	70	H	M	L	L	-	-	-	-	-	-	-	H	-	-	-
CLO-2:	Comprehend the concept and applications of energy conservation in fires utilizations and apply the same for recent engineering advancement.	2	80	70	H	M	M	M	-	-	L	-	-	L	-	H	M	M	M
CLO-3:	Understand basic knowledge to the physical principles governing fire growth.	2	80	70	H	M	L	M	-	-	-	-	L	-	-	H	-	-	-
CLO-4:	Understand the behavior and chemical reactions related.	2	80	70	H	M	M	M	-	-	M	M	M	M	L	H	M	M	M
CLO-5:	Apply the latest engineering capability in fire detection, prevention systems and life safety	2	80	70	H	M	M	M	M	L	L	-	L	M	L	H	M	M	M
CLO-6:	Understanding prospects of normal and microgravity fire safety for Aerospace Engineering Applications.	2	80	70	H	M	M	M	M	L	L	M	L	M	L	H	M	M	M

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Introduction to Fire Science, fires in history, fire losses, fire and combustion.	Importance of fire dynamics on a fire strategy.	Development and behavior of fire propagation in free and confined atmosphere.	Identifying fire spread hazards and risks.	Active and Passive Fire Protection Features.
	SLO-2 Relevant material properties, combustion and heat transfer.	Fundamentals of heat and mass transfer for fire, smoke production and transport.	Factors affecting fire growth.	Safety and financial implications, developing safe work systems.	Fire prevention-handling and storing flammable and combustible liquids/fuels/propellants.
S-2	SLO-1 Chemistry and classification of fires- Composition of Combustion- (Flame, heat, fire gases, smoke).	Fundamentals of ignition and flame propagation.	Buoyant Plumes, Combusting Plumes, Starting plume.	Introduction to Fires causes / Explosion hazards in Chemical, Electrical units.	Elimination of ignition sources.
	SLO-2 Review of Thermodynamics and Fluid Mechanics in fire behavior	Role of Material flammability in fire propagation.	Fireball, Transient Aspects of Fire Plumes.	Finite Real Fire Effects.	Fire protection in plants and factories, Fire walls, fire doors.
S-3	SLO-1 Solving Problems	Solving Problems	Solving Problems	Solving Problems	Solving Problems
	SLO-2 Solving Problems	Solving Problems	Solving Problems	Solving Problems	Solving Problems
S-4	SLO-1 Heat and mass transfer. Relevance of fire classification and governing dynamics.	Parameters affecting ignition, flame spread.	Fire spread over liquid and solid fuel surfaces.	Fire hazards (health-flammability-reactivity (stability)).	Fire prevention/suppression features, Microgravity fires control.
	SLO-2 Material Flammability principles, Thermal Ignition.	Heat release rate and flame extinction phenomenon.	Enclosure fires, Incineration.	Air contaminants in fires-toxic effects of fire gases.	Fire suppression. Fixed automatic sprinklers. Sprinkler system and design.
S-5	SLO-1 Sources of ignition of combustible materials.	Explosions and fires –fundamental combustion principles.	Solving Problems	Solving Problems	Solving Problems
	SLO-2 Application of Mass Energy and species Conservation.	Egress– principles and calculations.	Solving Problems	Solving Problems	Solving Problems
S-6	SLO-1 Rate of burning. Heat transfer from Flames-Ignition temperature.	Solving Problems	Forest fires Analysis of fire plumes.	Smoldering combustion science.	Environnemental fire propagation considérations.
	SLO-2 Flash point, Fire point, Flash over.	Solving Problems	Fire safety aspects of plumes.	Introduction to smoke formation, composition and movement, hazards.	Role of combustion detectors (Fire detection, smoke detection, types of ionization-photo electric-light intensity-

						scattered light detectors.
S-7	SLO-1	Components and objectives of a fire safety strategy.	Fire safety techniques in combustion instruments.	Standardized material flammability testing.	Essential conditions for explosion occurrence.	Heat detectors. Flame detectors -infra red detector - ultraviolet flame detector).
	SLO-2	Fire dynamics process and related issues.	Aerospace Engineering Applications of fire dynamics.	Solid, liquid and gaseous fuel combustion and its relation to fire safety.	Explosion characteristics and Prevention.	Portable fire Extinguishers-Types-extinguisher-location, Inspection-testing, principles and calculations.
S-8	SLO-1	Solving Problems	Solving Problems	Solving Problems	Solving Problems	Solving Problems
	SLO-2	Solving Problems	Solving Problems	Solving Problems	Solving Problems	Solving Problems
S-9	SLO-1	Chapter Doubt clarification.	Chapter Doubt clarification.	Chapter Doubt clarification.	Chapter Doubt clarification.	Chapter Doubt clarification.
	SLO-2	Chapter Doubt clarification.	Chapter Doubt clarification.	Chapter Doubt clarification.	Chapter Doubt clarification.	Chapter Doubt clarification.

Learning Resources	<ol style="list-style-type: none"> 1. James G. Quintiere, "Fundamentals of Fire Phenomena", 2006 Wiley. 2. Dougal Drysdale, "An Introduction to Fire Dynamics", 2011 Wiley. 3. Akhil Kumar Das., "Principles of Fire Safety Engineering: Understanding Fire and Fire Protection", Prentice Hall of India, New Delhi, 2014. 4. R.S. Gupta., "A Hand Book of Fire Technology", Second edition, Modern press, 2005. 5. V. K. Jain, "Fire safety in buildings", New age international publisher, 2006. 6. Niamh Nic Daeid., "Fire Investigation", CRC Press, 2004.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. Vinay Kumar Gupta, National Physical Laboratory, guptavinay@nplindia.org	1.Prof. Raghavan, V., IIT Madras, Chennai, raghavan@iitm.ac.in.	1.Dr. T. Selvakumaran, SRMIST
	2.Prof. Amit Kumar, IIT Madras, Chennai, amik@ae.iitm.ac.in.	2.Mr. Vinayak Malhotra, SRMIST

Course Code	18ASE210T	Course Name	AIRFRAME MAINTENANCE AND REPAIR	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Aerospace Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:		Learning			Program Learning Outcomes (PLO)																	
CLR-1 :	Identify the type of welding and riveting process to be used in aircraft.	Thinking (Bloom)	Efficiency (%)	Attainment (%)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2 :	Perform Plastic and Composite material repair in Aircraft Structures																							
CLR-3 :	Carryout Assembly & Rigging of Aircraft Flight Controls.																							
CLR-4 :	Execution of Inspection & Maintenance of major and auxiliary systems																							
CLR-5 :	Identify the various hazardous materials and storage practices.																							
CLR-6 :	Utilize the knowledge acquired for repair and maintenance activities on aircraft structure.																							

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1:	Acquire knowledge on welding and sheet metal repair operations and maintenance practices in aviation industry	2	80	70	H	-	M	L	M	-	-	-	-	-	-	L	L	M	M
CLO-2:	Gain knowledge on maintenance and repair procedures on plastics and composite structures	2	80	70	H	-	M	L	M	-	-	-	-	-	-	-	M	M	M
CLO-3:	Understand the Assembly & Rigging procedures and operation of Aircraft flight controls.	2	80	70	H	-	L	L	M	-	-	-	M	-	-	L	M	M	M
CLO-4:	Learn the inspection and maintenance of major and auxiliary systems	2	80	70	H	-	L	L	M	-	M	M	-	-	-	L	M	M	M
CLO-5:	Acquire knowledge on Hazardous materials, safety, Inventory Procedures & Troubleshooting practices	2	80	70	H	L	L	L	M	-	-	-	M	-	-	L	H	H	M
CLO-6:	Acquire comprehensive knowledge on airframe maintenance and repair.	2	80	70	H	L	L	L	M	-	M	M	M	M	-	L	M	M	M

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction to Aircraft Welding	Applications & Advantages of Plastics used in Aircraft.	Introduction to Aircraft Assembly and Rigging operations.	Inspection of Landing Gear System	Introduction to Hazardous Materials
	SLO-2	Nomenclature & Types.of Welding	Classification & Types of Plastics	Rigging Specifications	Maintenance of Landing Gear System	Types
S-2	SLO-1	Equipments used in Welding shop	Identification of Clear Plastics	Aircraft Leveling Procedure	Inspection of Air - conditioning System	Flammables - Handling, Storage & Emergency Procedure
	SLO-2	Need for Maintenance of Welding Equipments	Storage and Protection, Cutting, & Drilling of Plastics	Assembly of Major Structural Components	Maintenance of Air - conditioning System	Corrosives - Handling, Storage & Emergency Procedure
S-3	SLO-1	Maintenance of Welding Equipments	Forming of Plastics.	Assembly of Movable Control Surfaces	Inspection of Pressurization System	Toxins & Reactives - Handling, Storage & Emergency Procedure
	SLO-2		Cementing, Annealing & Cleaning of Plastics	Fixed Surface Alignment – Symmetry Check	Maintenance of Pressurization System	Physical & Biological Hazards
S-4	SLO-1	Characteristics of a good weld & Ensuring Quality Weld	Installation of Plastic Windows and Windshields	Demonstration of Symmetry Check in Cessna Aircraft	Inspection of Aircraft Instruments	Handling, Storage & Emergency Procedure
	SLO-2	Introduction to Non-fusion Welding Process - Soldering & Brazing	Inspection of Plastic Components		Maintenance of Aircraft Instruments	Osha's Hazardous Communication Standards
S-5	SLO-1	Requirements & Process	Repair of Cracks in Plastics.	Effects of Rigging on Flight	Testing of Instruments	Material Safety Data Sheet
	SLO-2	Advantages & Disadvantages.	Repair of Holes in Plastics.	Checking & Adjusting Dihedral angle.	Handling of Instruments	Inventory & Labeling
S-6	SLO-1	Classification of Damage	Introduction to Advanced Composites in Aircraft.	Checking & Adjusting Incidence angle.	Inspection of Fire Protection Systems	Introduction to Troubleshooting Theory
	SLO-2	Damage Investigation	Advantages of Composites over Metals in Aerospace Applications	Alignment Check of Empennage	Maintenance of Fire Protection Systems	Types
S-7	SLO-1	Repair Layout Techniques	Equipments used in Composite Fabrication	Alignment Check of Wings	Inspection of Ice Protection Systems	Troubleshooting with Chart
	SLO-2	Repair Practices	Wet Layup Process of Building Composite Parts.	Alignment Check of Engines.	Maintenance of Ice Protection Systems	Examples

S-8	SLO-1	Introduction to Riveting Process in Aviation Industry.	Prepreg Process of Building Composite Parts.	Demonstration of various checks in Cessna Aircraft	Inspection of Water & Waste Systems	Troubleshooting without chart
	SLO-2	Types & Nomenclature of Rivets	Repair of Composite Components		Maintenance of Water & Waste Systems	Examples
S-9	SLO-1	Equipments used for Riveting	Special Precautions	Need for Balancing Control Surfaces	Inspection of Position & Warning Systems	Troubleshooting intermittent discrepancies
	SLO-2	Installation of Rivets	NDT methods in Composite Materials.	Procedure for Balancing Control Surfaces	Maintenance of Position & Warning Systems	Examples

Learning Resources	1. Michael J.Kroes, William A.Watkins ad Frank Delp, Aircraft Maintenance and Repair, 7 th ed., Tata McGraw Hill, 2013 2. Aviation Maintenance Technician Handbook – Airframe, Vol. 1, 2, U.S.Dept. of Transportation,Federal Aviation Administration, Flight Standards Service, 2012	3. Larry Reithmeir., Aircraft Repair Manual, Palamar Books, Marquette,1992. 4. Civil Aircraft Inspection Procedures Part I & II, CAA, English Book House, New Delhi 1986.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Wg.CdrK.Manoharan (Retd), Blue Dart Aviation Ltd., manoharank@bluedart.com	1. Dr. A. P. Haran, Park College of Engineering & Technology, ap_haran@rediffmail.com	1. Dr. S. Sivakumar, SRMIST
2..Mr.K.Senthilkumar,Deputy Chief Aircraft Engineer, Air India , Bangalore ks_senthilkumar@yahoo.co	2. Dr.Wg.Cdr.N.Muthusamy, Rajalakshmi Engineering college, Chennai, muthusamy55@gmail.com	2. Mr. G. Mahendra Perumal, SRMIST

Course Code	18ASE211T	Course Name	AIRBORNE SENSORS AND ACTUATORS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Aerospace Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand the advanced concepts in airborne sensors and actuators				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Provide mathematical knowledge for modelling				Thinking (Bloom)	Efficiency (%)	Assessment (%)	Knowledge	Analysis	Development	Design, Research	Usage	Culture	& Sustainability		Team Work	Communication	& Finance	Learning			
CLR-3 :	Understand the aircraft actuation systems																					
CLR-4 :	Understand the servo components																					
CLR-5 :	Learn the modeling of sensors and actuators																					
CLR-6 :	To solve problems in avionics engineering																					

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1:	Describe the concepts of airborne sensors and actuators	2	85	75	H	-	-	-	-	-	-	-	-	-	-	-	-	M	-
CLO-2:	To apply mathematical knowledge in modeling of sensors and actuators	2	85	75	H	H	H	-	-	-	-	-	-	-	-	-	M	M	-
CLO-3:	Describe the aircraft actuation systems	2	85	75	H	-	H	H	-	-	-	-	-	-	-	-	-	M	-
CLO-4:	Describe the servo components	2	85	75	H	H	-	-	H	-	-	-	-	-	-	-	M	M	M
CLO-5:	Model the sensors and actuators	2	85	75	H	-	H	-	H	-	-	-	-	-	-	-	M	M	M
CLO-6:	Solve problems in avionics engineering	2	85	75	H	H	H	H	H	-	-	-	-	-	-	-	M	M	M

Duration (hour)		9	9	9	9	9
S-1	SLO-1 SLO-2	Introduction to aircraft actuation systems	Servo Actuators	Linear and non linear actuation systems	Gyroscope principles	Testing philosophies
S-2	SLO-1 SLO-2	Introduction to aircraft actuation systems	Linear Servo Actuators and types	Modeling of actuation systems	Gyro equation	Testing protocols
S-3	SLO-1 SLO-2	Principles of aircraft actuation systems	Rotary Servo Actuators and types	Modeling of actuation systems	Rate gyro and integration	Testing process
S-4	SLO-1 SLO-2	Hardware elements for the actuation systems	Servo Valves	Servo loop analysis	Free gyro, Vertical and directional gyro	Solenoid voltmeter, wheatstone bridge
S-5	SLO-1 SLO-2	Functional block diagram of the actuation systems	Hydraulic servo valves and types	Servo loop analysis	Inertial navigation	EMF meter, electrometer
S-6	SLO-1 SLO-2	Types of actuation systems	Electro hydraulic servo valves and types	Actuator design	Basic principles theory and applications	Signal generators
S-7	SLO-1 SLO-2	Electromagnetic actuators	Servo amplifier pick off	Testing methodologies	Accelerometer- principle and theory	Performance testing of sensors
S-8	SLO-1 SLO-2	Electric motors	Selection factors of servo amplifier	Performance testing	Spring, mass, force balance	Data evaluation
S-9	SLO-1 SLO-2	Solenoid actuators	Power supply consideration for servo amplifier	Test equipment for actuation systems	Piezoelectric accelerometer and MEMS sensors	Calculation of performance parameters

Learning Resources	1. James Ephraim Johnson, Electro hydraulic servo systems, hydraulics and pneumatic magazines, 1984 2. Pallett, EHJ, Aircraft instruments, principles and applications, pitman publishers, London, 1981 3. Neal E wood et al, Electromechanical actuation development AFFDL-TR-150. Dec 1978	4. Alan S Moris, Measurement and instrumentation principles, Third edition, 2001 5. J Jaidev vyas et al, Electro hydraulic actuation systems: Design testing, Identification and validation, 2019 6. Qing Guo, Non linera control techniques for electro hydraulic actuators, 2017
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. S. Raja, National Aerospace Laboratories, Bangalore, raja@nal.res.in	1. Dr. Parammasivam, professor, MIT, Chennai, mparams@mitindia.edu	1. Mr. Umar Rizwan M, SRMIST

Course Code	18ASE301T	Course Name	AIRCRAFT CONTROL SYSTEMS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18ASC305T	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Aerospace Engineering	Data Book / Codes/Standards			

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1:	Understand the basics of control system	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2:	Understand the root locus analysis		
CLR-3:	Understand the frequency response analysis		
CLR-4:	Understand the time and frequency domain design of control system		
CLR-5:	Understand the control system design in state space		
CLO-6:	Understand control systems, various response analysis and control system in state space		

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1:	Design a mathematical model of a dynamic system	2	85	75	H	-	-	-	-	-	-	-	-	-	-	-	-	M	M
CLO-2:	Analyze the system using Root Locus plot	2	85	75	H	H	H	H	-	-	-	-	-	-	-	-	M	-	-
CLO-3:	Analyze the system using Frequency response analysis	2	85	75	H	-	H	H	-	-	-	-	-	-	-	-	-	M	M
CLO-4:	Design a control system in time and frequency domain	2	85	75	H	H	H	-	-	-	-	-	-	-	-	-	M	M	-
CLO-5:	Design and analyze the control system in state space	2	85	75	H	-	-	H	-	-	-	-	-	-	-	-	M	-	M
CLO-6:	Design and analyze control systems, various response analysis and control system in state space	2	85	75	H	H	H	H	-	-	-	-	-	-	-	-	M	M	M

Duration (hour)	9	9	9	9	9
S-1	SLO-1 SLO-2	Introduction to Control Systems Open-Loop, Closed-Loop Control, Feedback control system	Introduction to Root Locus Analysis	Bode Diagrams Rules for Constructing the Bode Plots	Introduction to time domain and frequency domain design of control system Lyapunov Stability
S-2	SLO-1 SLO-2	Block Diagrams and their Simplification	General Rules for Constructing the Root Locus	Nyquist Plots Rules for Constructing the Nyquist Plots	PD Controller Design PI Controller Design Asymptotic Stability Input-Output Stability
S-3	SLO-1 SLO-2	Mason's Gain Formula Numerical	Positive feedback Systems	Stability and Relative Stability Analysis	PID Controller Design State Transition Matrix Controllability and Observability
S-4	SLO-1 SLO-2	Mathematical Modeling of Dynamical Systems	Root Locus plot for positive feedback system	Systems with Transport Lags	Lead Compensation Lag Compensation The Lyapunov Equation
S-5	SLO-1 SLO-2	Modeling in the State Space	Negative feedback Systems	Gain Margin Phase Margin	Lead-Lag Compensation Full-State Feedback Control Design and Pole Placement
S-6	SLO-1 SLO-2	Transfer Functions Impulse Response Functions	Root Locus plot for Negative feedback system	Closed-Loop Frequency Response	Sensitivity Optimal State Space Control System
S-7	SLO-1 SLO-2	Delay Time, Rise Time, Peak Time, Maximum Overshoot, and Settling Time Stability Analysis and Routh's Stability Criterion	Parameter Variation	Frequency Domain Performance Specifications	Complimentary Sensitivity Transfer Functions Linear Quadratic Regulator
S-8	SLO-1 SLO-2	Proportional, Derivative, and Integral Control Actions	Stability analysis of positive feedback system using root locus	Peak Resonance Resonant Frequency	Disturbance Rejection Classical Control Theory
S-9	SLO-1 SLO-2	Steady-State Error Analysis in Feedback Systems	Stability analysis of Negative feedback system using root locus	Bandwidth Numerical example	Loop Shaping Modern Control Theory

Learning Resources	1. Ogata, K., Modern Control Engineering, Prentice Hall, 2002 2. Kuo, B.C., Automatic Control Systems, Prentice Hall, 1991 3. Franklin, G.F., Powell, J.D., and Emami-Naeini, A., Feedback Control of Dynamic Systems, Addison Wesley, 1994.	4. Dorf, R.C., and Bishop, R.H., Modern Control Systems, Prentice Hall, 2001. 5. Nise, N.S., Control Systems Engineering, Benjamin-Cummings, 1995.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. S. Raja, Senior Principal Scientist and Professor, NAL – Bangalore. raja@nal.res.in	1. Dr.K.M.Parammasivam, Professor, MIT-Chennai. mparams@mitindia.edu	1. Mr.A.Vinoth Kumar, SRMIST.

Course Code	18ASE302T	Course Name	HELICOPTER AERODYNAMICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18ASC202J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Aerospace Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Understand the helicopter configurations, characteristics and its rotor systems				Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Learn the momentum theory used in the analysis of helicopter aerodynamics																							
CLR-3 :	Comprehend the performance of helicopter in hovering and climbing.																							
CLR-4 :	Understand the flow states of the rotor and helicopter vertical descent performance																							
CLR-5 :	Study the performance of helicopter in horizontal flight.																							
CLR-6 :	Acquaint with forward flight performance of helicopter and theory of blade stall.																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1 :	Acquire knowledge of helicopter fundamentals, configurations and rotor systems.				2	85	80	H	M	L	L	-	-	-	-	-	-	-	-	L	M	M	H	
CLO-2 :	Apply momentum theory in the analysis of helicopter parameters.				2	90	75	H	H	M	M	L	-	-	-	-	-	-	-	L	H	M	M	
CLO-3 :	Acquire theoretical foundation on the hovering and climbing performance of helicopter.				2	85	75	H	M	M	L	-	-	-	-	-	-	-	-	L	M	H	M	
CLO-4 :	Analyze the vertical descent performance of helicopter.				2	80	70	H	M	L	L	-	-	-	-	-	-	-	-	L	M	M	M	
CLO-5 :	Acquire basic understanding of helicopter performance in horizontal flight.				2	85	75	H	M	L	L	-	-	-	-	-	-	-	-	L	H	H	M	
CLO-6 :	Accrue information on the helicopter performance in forward flight and theory of blade stall.				2	80	70	H	M	M	M	L	-	-	-	-	-	-	-	L	M	M	H	

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Introduction to Helicopters – History	Momentum Theory - Introduction	Performance in Hovering and Climbing	Flow States of the Rotor – Introduction	Forward Flight – Performance Equation
	SLO-2 Helicopter Configurations – Single Rotor, Two Rotor and Multi Rotor Machines				
S-2	SLO-1 Specifics of Helicopters	Thrust Generation	Optimum Hovering Rotor	Normal Working, Vortex-Ring and Windmill States	Drag-Lift Ratio – Forward Flight Parasite Drag Coefficient – Forward Flight
	SLO-2 Articulated Rotor System				
S-3	SLO-1 Definitions – Tip Path, Tip Path Plane, Axis of Rotation, Shaft Axis, Disc Area, Chord, Blade Angle, Angle of Attack	Hovering	Induced Torque	Vertical Descent Performance	Climb Drag-Lift Ratio – Forward Flight
	SLO-2 Definitions – Feathering Angle, Feathering, Disc Loading, Blade Loading, Solidity, Flapping, Lead-Lagging				
S-4	SLO-1 Definitions – Feathering Angle, Feathering, Disc Loading, Blade Loading, Solidity, Flapping, Lead-Lagging	Figure of Merit	Profile Drag Torque	Curves for Calculating Vertical-Descent Velocities, Flight Modes of a Rotor, Autorotation Diagrams	Profile Drag-Lift Ratio – Forward Flight
	SLO-2 Effect of Cyclic Pitch Change				
S-5	SLO-1 Swash Plate	Blade Element Theory	Numerical Problems on Optimum Hovering Rotor, Induced Torque, Profile Drag Torque	Performance in Horizontal Flight – Introduction	Induced Drag – Forward Flight
	SLO-2 Rotor Systems – Fully Articulated, Semi-Rigid Rotor, Rigid Rotor				
S-6	SLO-1 The Atmosphere	General Expression for Induced Velocity	Performance Equation	Flapping and Lag Hinge – Horizontal Flight Steady Hover – Horizontal Flight	Profile Power and Parasite Power in Forward Flight
	SLO-2 International Standard Atmosphere (ISA)				
S-7	SLO-1 Atmospheric Density and Power Required – Definitions of Rotor Profile Power, Induced Power, Parasite Power	Local Solidity	Optimum Rotor Design	Ideally Twisted Blade – Horizontal Flight	Introduction to Blade Stall
	SLO-2 Tip Loss				
S-8	SLO-1 Equivalent Chord	Ground Effect	No Twist Case – Horizontal Flight	Introduction to Quadcopter / Multirotor Aerodynamics	
	SLO-2 Tutorial				
S-9	SLO-1 Tutorial	Tutorial	Tutorial	Tutorial	Tutorial
	SLO-2 Tutorial				

Learning Resources	1. Rathakrishnan E., <i>Helicopter Aerodynamics</i> , PHI Learning Private Limited, Delhi, 2019. 2. Nikolsky Alexander A., <i>Helicopter Analysis</i> , John Wiley & Sons Inc., New York, 1951 3. Alfred Gessow, Garry C. Myers Jr., <i>Aerodynamics of the Helicopter</i> , College Park Press, USA, 1999.	4. George H. Saunders, <i>Dynamics of Helicopter Flight</i> , John Wiley & Sons Inc., New York, 1975. 5. Wayne Johnson, <i>Helicopter Theory</i> , Dover Publications, USA, 1994. 6. Gordon Leishman J., <i>Principles of Helicopter Aerodynamics</i> , Cambridge University Press, New York, 2000. 7. John Seddon, Simon Newman, <i>Basic Helicopter Aerodynamics</i> , 3 rd Edition, John Wiley & Sons, Ltd., 2011.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Evaluate Create	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Expert
Dr. Manishankar C., Senior Scientist, NAL, Bangalore	Prof. Arun Kumar P., Assistant Professor, IIT Jammu	Dr. S. M. Aravindh Kumar, SRMIST

Course Code	18ASE303T	Course Name	ROCKET AERODYNAMICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18ASC301J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Aerospace Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand the concept of boundary layer and its characteristics.	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Learn basics of incompressible and compressible flat plate boundary layer, importance of shock-wave boundary layer interactions.	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Understand and appreciate the qualitative aspects of hypersonic flow, hypersonic shock-wave and Expansion-wave relations, application of Newtonian theory in hypersonic flow				H	M	L	L	-	-	-	-	-	-	-	L	H	M	M
CLR-4 :	Study different classifications and external aerodynamic configurations of missiles.				H	M	L	M	-	-	-	-	-	-	-	L	M	H	M
CLR-5 :	Apply cross-flow analysis in the analysis of aerodynamics characteristics of missiles, vortex shedding and flow separation.				H	H	M	L	L	-	-	-	-	-	-	L	H	M	M
CLR-6 :	Understand the various aerodynamic launching problems of missiles.				H	M	L	M	-	-	-	-	-	-	-	L	M	M	H
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:	2	85	75	H	L	L	L	-	-	-	-	-	-	L	M	M	M
CLO-1 :	Acquire knowledge of boundary layer theory.					H	M	L	M	-	-	-	-	-	-	L	M	H	M
CLO-2 :	Acquire the fundamental differences between incompressible and compressible boundary layers, importance of boundary layer interaction with shock layer.					H	M	L	M	-	-	-	-	-	-	L	M	H	M
CLO-3 :	Appreciate the various qualitative aspects of hypersonic flow.					H	H	M	L	L	-	-	-	-	-	L	H	M	M
CLO-4 :	Accrue knowledge of different aerodynamic configurations of missiles, missile classification.					H	M	L	M	-	-	-	-	-	-	L	M	M	H
CLO-5 :	Acquire basic understanding of cross-flow analysis in study of missile aerodynamics					H	L	L	L	-	-	-	-	-	-	L	M	M	M
CLO-6 :	Accrue information on aerodynamic launching problems of missiles.					H	M	L	L	-	-	-	-	-	-	L	M	M	M

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Concept of Boundary Layer	Qualitative Aspects of Hypersonic Flow – Thin shock layer, Viscous Interaction, High Temperature Shock Layer.	Classification of Missiles	Aerodynamic Characteristics of Slender and Blunt Bodies	Aerodynamic Launching Problems
	SLO-2 Boundary Layer Definitions and Characteristics				Considerations for Safety of Parent Aircraft
S-2	SLO-1 Boundary Layer - Boundary Conditions, Laminar and Turbulent Boundary Layers	Qualitative Aspects of Hypersonic Flow – Entropy Layer, Low-Density Flow, High Temperature Effects, etc.	External Aerodynamic Configurations of Missiles - Wing Control, Canard Control Tail Control, Tail-Less (or Wing Control), Body Extension	Missiles at Small Angles of Attack	Considerations for Safety of Parent Aircraft (Air Launch) – Introduction to Missile-Aircraft Collision, Missile Structural Failure
	SLO-2 Boundary Layer Thickness - Types			Cross-Flow Analysis	
S-3	SLO-1 Displacement Thickness of Boundary Layer – Concept, Derivation	Aerodynamic heating of re-entry bodies – slender and blunt re-entry vehicles.	External Aerodynamic Configurations of Missiles - Nose Flap Control, Dorsal, Jet Control, Wing Arrangements (Monowing, Triform, Cruciform)	Total Lift on a Missile Body – Cross-Flow Analysis	Launch Boundaries – Introduction to Launch-Aircraft Trajectory, Missile Trajectory, Launch Boundary Determination
	SLO-2 Momentum Thickness of Boundary Layer – Concept, Derivation	Hypersonic Flight Paths – Velocity-Altitude Map			
S-4	SLO-1 Newtonian Theory	Newtonian Theory	Forces Acting on Missile during Atmospheric Flight, Effect of Angle of Attack on Aerodynamics Forces and Moments	Total Lift on a Slender Wing – Cross Flow Analysis	Ground Launch – Problem of Launching Missiles from the Ground
	SLO-2 Newton's Sine-Squared Law – Derivation,				Sources of Detrimental Effects causing Excessive Missile Dispersion
S-5	SLO-1 Incompressible Boundary Layer - Incompressible flow over a flat plate, Governing Equations, Numerical Results.	Modified Newtonian Law Mach Number Independence	Introduction to Bodies of Revolution – Nose, Mid-Section, Boat-tail	Total Lift on a Wing-Body Combination – Cross-Flow Analysis	Factors Affecting Missile Launch Dispersion – Launcher Deflection, Tip-Off,
	SLO-2 Compressible Boundary Layer - Compressible flow over a flat plate, Governing equations	Numerical Problems on Newtonian Theory and Exact Shock-Expansion Theory	Different Shapes of Missile Fore Bodies – Advantages and Disadvantages	Introduction to wing-body interference of missile	Factors Affecting Missile Launch Dispersion - Thrust and Fin Malalignment, Wind

S-7	SLO-1	Boundary Layer Separation – Introduction	Hypersonic Similarity Parameter	Boat Tail – Introduction and its Importance	Flow Separation on a Missile Body at Low and High Angles of Attack	Rocket separation – Importance of Rocket Separation, Separation Mechanisms
	SLO-2			Base Pressure		
S-8	SLO-1	Shock Wave Boundary Layer Interaction	Shock wave and Expansion Wave Relations of Inviscid Hypersonic Flows	Introduction to Missile Drag – Friction drag, Pressure drag, Induced drag, Interference drag	Vortex Shedding – Cross-Flow Regimes of Missile at Different Angles of Attack	Impulse Devices for Separation – Stage Ignition, Auxiliary Rockets, Thrust Reversal, Springs
	SLO-2					
S-9	SLO-1	Tutorial	Tutorial	Tutorial	Tutorial	Tutorial
	SLO-2					

Learning Resources	<ol style="list-style-type: none"> 1. John D. Anderson Jr., <i>Fundamentals of Aerodynamics</i>, 5th Edition, McGraw-Hill Companies, Inc., 2010. 2. John D. Anderson., <i>Modern Compressible Flows</i>, 3rd Edition, McGraw-Hill Companies, Inc., 2003. 3. Rathakrishnan E., <i>High Enthalpy Gas Dynamics</i>, John Wiley & Sons Singapore Pte. Ltd., 2015. 	<ol style="list-style-type: none"> 4. John D. Anderson Jr., <i>Hypersonic and High-Temperature Gas Dynamics</i>, 3rd Edition, AIAA Education Series, AIAA, 2003. 5. Chin S. S., <i>Missile Configuration Design</i>, McGraw-Hill Book Company Inc., New York, 1961. 6. Jack N. Nielsen, <i>Missile Aerodynamics</i>, McGraw-Hill Book Company Inc., New York, 1960.

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Understand	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Analyze	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Expert
Dr. Manishankar C., Senior Scientist, NAL, Bangalore	Prof. Arun Kumar P., Assistant Professor, IIT Jammu	Dr. S. M. Aravindh Kumar, SRMIST

Course Code	18ASE304T	Course Name	SPACE MISSION DESIGN & ANALYSIS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18ASC306T, 18ASC303J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Aerospace Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1:	Understand the space mission profiles and types of space missions	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2:	Understand the mission objectives, constraints, needs, and requirements		
CLR-3:	Know the complete set of space systems and various modules of space system and spacecraft		
CLR-4:	Know the basics of spacecraft motions and the governing equations of spacecraft motions		
CLR-5:	Comprehend the satellite attitude dynamics and reentry vehicle dynamics		
CLR-6:	Interpret the interplanetary mission trajectories and associated concepts		

Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:															Level of Thinking (Bloom)	Expected (%)	Expected (%)		
CLO-1:	Describe the space mission and the classifications of space mission	2	85	80	H	-	M	M	-	-	-	-	-	-	-	-	-	-	L	-	-
CLO-2:	Describe the various aspects space environments, mission objective, needs and design of the space mission	2	85	80	H	-	-	-	-	-	L	-	-	-	-	-	-	-	-	-	-
CLO-3:	Explain the importance of the spacecraft systems and instrumentation	2	80	75	H	L	L	H	-	-	-	-	-	-	-	-	-	-	M	-	-
CLO-4:	Explain the necessity of Kepler's equations and orbit maneuvers	2	80	75	H	H	M	M	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-5:	Describe the key features reentry flight physics and injection of spacecrafts	2	80	75	H	M	M	H	-	-	L	-	-	-	-	-	-	-	L	-	-
CLO-6:	Demonstrate the interplanetary mission profile and the importance	2	80	75	H	L	M	H	-	-	L	-	-	-	-	-	-	-	L	-	-

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Definition of space mission	Requirements, constraints of spacecraft design	The N-body problem	Basis of launching of a satellite	General aspects of interplanetary trajectory
	SLO-2 Classification of space missions	Design process of spacecraft	The N-body problem	General aspects of satellite injection	Interplanetary Hohmann transfer
S-2	SLO-1 Low Earth Orbit mission, medium altitude mission	Spacecraft configuration	The orbit equation	Launch vehicle ascent trajectory	Rendezvous opportunities
	SLO-2 Geosynchronous Earth Orbit mission, deep space mission	Integrating the spacecraft design	The energy law.	Dependence of orbital parameters on in-plane injection parameters	Sphere of influence
S-3	SLO-1 Space mission life cycle	Spacecraft payload design	Revision of circular orbits and elliptical orbits	Launch vehicle performance	Method of patched conics
	SLO-2 Mission objectives	Payload sizing process	Parabolic trajectories	Orbit deviation due to injection errors	Planetary departure
S-4	SLO-1 Identification of mission needs, requirements, and constraints	Mission requirements	Hyperbolic trajectories	Small injection errors	Planetary rendezvous
	SLO-2 Mission characterization	Observation of payload design	Keplers equation	Basics of reentry flight dynamics	Planetary flyby
S-5	SLO-1 Mission evaluation	Observation of payload sizing	Lamberts problem	Fundamentals of entry flight mechanics	Design of transfer ellipse
	SLO-2 Orbit design	Spacecraft subsystems	Restricted three body problem	Fundamentals of entry heating	Design of transfer ellipse
S-6	SLO-1 Constellation design	Propulsion subsystem selection and sizing	The Lagrange coefficients	Entry vehicle design	Design of departure trajectory
	SLO-2 Space environment peculiarities	Basic of rocket propulsion and its types	The Lagrange coefficients	Landing techniques	Design of arrival trajectory
S-7	SLO-1 Space environment survivability	Attitude determination and control	Jacobi constants	Recovery techniques	Gravity assist maneuver
	SLO-2 Selection of spacecraft material	Telemetry, tracking and command system	Introduction to orbit perturbation	Reentry errors	Establishing planetary orbit
S-8	SLO-1 Basic launch vehicle considerations	Command and data handling	Earth gravity harmonics	Overview of existing reentry mission	Motion of the Earth-Moon system
	SLO-2 Launch systems selection process	Power and thermal system	Unisolar gravitational attractions	Challenges of existing reentry mission	Time of flight
S-9	SLO-1 Determining the spacecraft design envelop and environments	Guidance and navigation system	Radiation pressure effects, atmospheric drag	Parametric design of a reentry capsule	Time of injection velocity
	SLO-2 Payload environments	Ground system design	Tidal friction effects and Mutual gravitational attraction	Planetary entry vehicle optimization	Lunar patched conic

Learning Resources	1. Larson, Wiley J., and James Richard Wertz. <i>Space mission analysis and design</i> . No. DOE/NE/32145-T1. Torrance, CA (United States); Microcosm, Inc., 1992. 2. Curtis, Howard D. <i>Orbital mechanics for engineering students</i> . Butterworth-Heinemann, 2013. 3. Cornelisse, Jacobus W., H. F. R. Schoyer, and Karel F. Wakker. "Rocket propulsion and spaceflight dynamics." London: Pitman, 1979 (1979).	4. Tewari, Ashish. <i>Atmospheric and space flight dynamics</i> . Birkhäuser Boston, 2007. 5. Griffin, Michael Douglas. <i>Space vehicle design</i> . AIAA, 2004. 6. Fortescue, Peter, Graham Swinerd, and John Stark, eds. <i>Spacecraft systems engineering</i> . John Wiley & Sons, 2011.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. Amit Palankar, GE aviation, Bangalore, palankr.amit@gmail.com	Dr. S. Elangovan, Professor and Dean, Dept. Of Aeronautical Engineering, Bharath Institute of Higher Education and Research, subelango@yahoo.co.in	Dr. Malaikannan G, SRMIST

Course Code	18ASE305T	Course Name	VIBRATIONS AND ELEMENTS OF AEROELASTICITY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18ASC101T	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Aerospace Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning				Program Learning Outcomes (PLO)															
CLR-1 :	Understand the concept of drawing a vibratory model				Level of Thinking (Bloom)	1	2	Expected Proficiency (%)	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Understand the methods of deriving the equations of motion																							
CLR-3 :	Identify the problems of vibration in aerospace industry																							
CLR-4 :	Know the functioning of various vibration measuring instruments																							
CLR-5 :	Learn the various approximate methods of solving natural frequency of various systems																							
CLR-6 :	Get an idea of the various aero elastic phenomena that arise in real time flight conditions.																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1 :	Describe the elements of a vibratory model				2	85	75	H	-	H	H	-	-	-	-	-	-	-	-	M	M	M	M	M
CLO-2 :	Describe the equations of motion of any vibratory system				2	85	75	H	H	H	H	-	-	-	-	-	-	-	-	M	M	M	M	M
CLO-3 :	Explain the solving methods of approach to any vibration problem				2	85	75	H	H	H	H	-	-	-	-	-	-	-	-	M	M	M	M	M
CLO-4 :	Explain the functionality of various vibration measuring instruments				2	85	75	H	H	-	H	-	-	-	-	-	-	-	-	M	M	M	M	M
CLO-5 :	Describe the various approximate methods in determining the natural frequency of various vibratory systems.				2	85	75	H	H	H	H	-	-	-	-	-	-	-	-	M	M	M	M	M
CLO-6 :	Investigate the different aero elastic phenomena for different flight conditions				2	85	75	H	H	H	H	-	-	-	-	-	-	-	-	M	M	M	M	M

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Introduction-Basic Terminology	Single degree of freedom system	Multi degree of freedom system	A three degree of freedom rotor system
	SLO-2	Elements of vibratory system	Examples-spring mass system	Free body diagram and equations of motion	Numerical solving
S-2	SLO-1	Degrees of freedom	Solution of equation of motion-Complementary function	Natural modes of vibration	Vehicle suspension problem
	SLO-2	Examples of vibratory system	Forced damped vibratory system	Mode shapes	Automobile problem
S-3	SLO-1	Simple Harmonic motion-Definition and explanation	Numerical solving –solution of equation of motion	Principal Coordinates	Discrete systems
	SLO-2	Sum of harmonic motions-different conditions	Numerical solving –solution of equation of motion	Principal modes	Examples
S-4	SLO-1	Numerical solving	Solution of equation of motion-Particular Integral	Orthogonal condition	Rayleigh method of finding the natural frequency
	SLO-2	Numerical solving	Solution of equation of motion-Particular Integral	Eigen value problem	Numerical Solving
S-5	SLO-1	Newton's law	Transient motion of damped forced vibration problem	Hamilton's principle	Semi-definite system
	SLO-2	D'Alembert's principle	Numerical solving	Vibration of elastic bodies	Numerical solving
S-6	SLO-1	Equation of motion-Newton's law of motion	Logarithmic decrement	Lateral Vibration of a string	Method of influence coefficient matrix
	SLO-2	Example	Numerical solving	Numerical solving	Numerical solving
S-7	SLO-1	Equation of motion- Energy method	Elevator and control tab numerical	Longitudinal vibration of rod	Dunkerley method
	SLO-2	Example	Helicopter rotor blade numerical	Numerical solving	Numerical –cantilever beam
S-8	SLO-1	Free Vibrations-Forced Vibrations	Springs connected in series	Lateral vibration of beam	Lagrange's equation
	SLO-2	Damped vibrations-Undamped vibrations	Springs connected in parallel	Numerical solving	Numerical solving
S-9	SLO-1	Periodic vibrations-Aperiodic vibrations	Support Excitation	Torsional vibration of shaft	Holzer method
	SLO-2	Numerical Solving	Vibration measuring instruments	Numerical solving	Case studies

Learning Resources	1. Timoshenko S., "Vibration Problems in Engineering" – John Wiley and Sons, New York, 1993.	4. Tse, F.S., Morse, I.F., Hinkle, R.T., "Mechanical Vibrations " – Prentice Hall, New York, 1984
	2. Fung Y.C., "An Introduction to the Theory of Aeroelasticity, - John Wiley & Sons, New York, 1995.	5. Scanlan R.H. & Rosenbaum R., "Introduction to the study of Aircraft Vibration & Flutter", John Wiley and Sons. New York, 1982
	3. Bisplinghoff R.L., Ashley H and Hoffman R.L., "Aeroelasticity"- Addison Wesley Publication, New York, 1983.	6. Tongue. B.H., "Principles of Vibration ". Oxford University Press, 2000.

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. G.Balamurugan, National Aerospace Laboratories, Bangalore, gbala@nal.res.in	1. Dr. V.Arumugam, Madras Institute of Technology, Chennai, arumugam.mitaero@gmail.com	1. Dr. L.R. Ganapathi Subramanian, SRMIST
2. Dr.A. Sakthivel, CEMILAC, Bangalore, asakthironika@gmail.com	2. Dr. R. Velmurugan, Indian Institute of Technology Madras, rvel@ae.iitm.ac.in	2. Mr. S. Chandra Sekhar, SRMIST

Course Code	18ASE306T	Course Name	DIGITAL AVIONICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Aerospace Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1:	Understand the avionics systems and its design	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2:	Understand the avionics system Integration		
CLR-3:	Know the architecture & communication Protocols used in Avionics communication		
CLR-4:	Know the display techniques used in Glass cockpit		
CLR-5:	Know the Electromagnetic interference sources in the aircraft and cooling techniques		
CLR-6:	Understand the maintenance aspect of avionics systems		

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1:	Describe the avionics systems and integration	2	85	75	H	-	-	-	-	-	-	-	-	-	-	-	H	H	H
CLO-2:	Describe about Avionics certification and design	2	85	75	H	H	H	-	-	-	-	-	-	-	-	-	H	H	H
CLO-3:	Explain the architecture and communication protocols of the avionics systems	2	85	75	H	-	H	H	-	-	-	-	-	-	-	-	M	H	H
CLO-4:	Differentiate the difference in display techniques used in Glass cockpit	2	85	75	H	H	-	-	-	-	-	-	-	-	-	-	M	H	H
CLO-5:	Identify the electromagnetic sources and interference prevention techniques	2	85	75	H	-	H	-	-	-	-	-	-	-	-	-	H	H	M
CLO-6:	Explain the maintenance procedures for avionics wiring, testing and maintenance	2	85	75	H	H	H	H	-	-	-	-	-	-	-	-	H	H	H

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Introduction to Avionics	Network Topologies & types of data bus used in Avionics network	Introduction to Head Up Display	Electromagnetic interference (EMI) and its effect	Aluminum wires/cables
	SLO-2 Need for Avionics	Types Bit encoding & Types of communication Protocol	Principle & Optical configuration	EMI on current carrying conductor	Bonding
S-2	SLO-1 Role of Avionics in civil aircrafts	Introduction to ARINC 429	Functional description of HUD	Need for EMI prevention	Types of bonding in composite materials
	SLO-2 Role of Avionics in Military aircrafts	Hardware elements, Word format, Bit encoding and protocols	Introduction to Helmet mounted display	Shielding, Twisted pairs and bandwidth	Lightning protection in composite aircrafts
S-3	SLO-1 Top-Down design Procedure for Avionics system Design	Introduction to MIL-STD 1553B	Optical configurations	Radiated EMI	Earth Returns
	SLO-2 Avionics Design factors	Hardware element, Bit encoding	Helmet Design factors and Functional description of HMD	EMI susceptibility	Aircraft manuals
S-4	SLO-1 Ilities of Avionics Systems	Word format and protocols	Introduction to MFD	EMI reduction	Maintenance manuals
	SLO-2 Avionics certification	RT-BC, BC-RT & RT-RT protocols	Working of MFD	Continuing airworthiness	Wiring diagram manuals
S-5	SLO-1 FTA- Fault tree analysis	Introduction to AFDX network	Direct voice input techniques and HOTAS	Wire and cable installation	Circuit Testing
	SLO-2 Qualitative and quantitative methods	Hardware elements, Protocols	FLIR- IR vision	Cable definition	Avometer and its types
S-6	SLO-1 FMEA- Failure mode and effect analysis	Ethernet frame format, AFDX frame format	Evaluating Avionics cooling requirements	Failure modes of wires and cables	Bonding meter
	SLO-2 Steps in FMEA	Difference between CPIOM & GPM	Heat transmission in Avionics Rack	Wiring procedure	oscilloscopes
S-7	SLO-1 Pros & cons of FTA & FMEA	Trends in Display technologies	Avionics cooling specifications	Cables and wire looms	Automatic Test equipments
	SLO-2 Difference between FTA & FMEA	CRT construction & working	Avionics cooling for Airplanes	Current rating of wire looms	Built In Test equipment
S-8	SLO-1 Avionics Architectures evolution	LCD & LED construction and working	Avionics cooling for missiles	Guidelines for the installation of wire looms	Difference between ATE & BITE
	SLO-2 A320 & B777 architecture examples	Plasma panels And EL panels construction and working	Avionics cooling for satellites& Spacecrafts	Types of wire looms	Centralized Maintenance systems
S-9	SLO-1 A380 & B787 architecture examples	Comparison of CRT, LCD, LED, Plasma and EL panels	Radiation heat transfer in space	Hydrolysis in wires and cables	Aircraft communication and addressing systems
	SLO-2 Attributes of Data bus & transmission classes	Capacitive and resistive touch screen technologies	Effect of α/e ratio on temperature in space	Wire connectors	Cost of maintenance

Learning Resources	1. Carry R spitzer, "The Avionics Handbook", CRC Press,2000	4. RPG Collinson, " Introduction to Avionics", Chapman and Hall, 1996
	2. Spitzer CR, "Digital Avionics systems",	5. Dave S Steinberg, "Cooling Techniques for electronic equipments", Second edition,1991
	3. Lan Moir, "Civil Avionics Systems", Second edition wiley publications, 1996	6. Jim curren, "Trends in Advanced Avionics", IOWA state university, 1992

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. S. Raja, National Aerospace Laboratories, Bangalore, raja@nal.res.in	1.Dr.Parammasivam, Professor, MIT, Chennai, params@mitindia.edu	1. Mr. Umar Rizwan M, SRMIST
		2. Dr. P. Eswaran, SRMIST

Course Code	18ASE307T	Course Name	COMPUTATIONAL HEAT TRANSFER AND FLUID DYNAMICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18MAB202T, 18ASE208T	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Aerospace Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Introduce the students with various techniques of problem solving	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Make the students to understand the governing equations for flow and heat transfer analysis				Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3			
CLR-3 :	Provide sufficient background to the students to gain the ability to discretize fluid flow problems				H	H	H	H	M	-	-	-	-	-	-	-	L	L	H	L		
CLR-4 :	Make the students to simulate and analyze fluid flow problems				H	H	H	H	M	-	-	-	-	-	-	-	L	M	H	-		
CLR-5 :	Make the students to choose proper numerical schemes fluid flows				H	H	H	H	M	-	-	M	L	L	-	-	L	M	H	-		
CLR-6 :	Enable the students to write computer programs for elementary fluid flow/heat transfer problems				H	M	M	H	M	-	-	-	H	-	-	-	L	-	H	-		
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	Understand the governing equations for flow and heat transfer analysis	2	80	70																		
CLO-2 :	Apply discretization techniques to solve the differential equations of fluid flow and heat transfer problems	2	80	70																		
CLO-3 :	Acquire the experience to judge the accuracy of numerical solutions and the numerical uncertainty.	2	80	70																		
CLO-4 :	Analyze convection-conduction problems through numerical algorithms	2	80	70																		
CLO-5 :	Gain fundamental knowledge about numerical code development	2	80	70																		

Duration (hour)	9		9	9	9	9
S-1	SLO-1	The Three Fundamental Approaches to problem solving - Analytical, Experimental & Numerical	Basics of Finite Difference Method	Discretization of 1 – D unsteady diffusion Equation	Discretization of 1 – D convection diffusion Equation	Collocated Grid
	SLO-2	Introduction to CFD	Finite Difference Approximation of derivatives			Staggered Grid
S-2	SLO-1	Processes involved in CFD	Truncation error	Interface conductivity	Central differencing scheme	Checker-board pressure oscillations
	SLO-2	Applications of CFD	Order of magnitude of error	Nonlinearity	Numerical oscillations of Central differencing scheme	Basics of Pressure-velocity coupling algorithm
S-3	SLO-1	Conservation Principles	Basics of Finite volume Method	Explicit Approaches	Properties of Discretization scheme	Discretization of 2D continuity equation
	SLO-2	Lagrangian vs Eulerian Approach	Integration Over a Control Volume	Implicit Approaches	Scarborough Criterion	Discretization of two-dimensional u-momentum equation
S-4	SLO-1	Derivation of continuity equation	Discretization of Computational Domain	Illustrative example	Transportiveness	Discretization of two-dimensional v-momentum equation
	SLO-2		Discretization of 1 – D diffusion equation		Conservativeness	
S-5	SLO-1	Derivation of momentum equations	Example of numerical solution – 1-D steady Heat conduction problem in a rod	Tri – diagonal Matrix Algorithm	Assessment of central differencing scheme	Pressure correction equation formulation
	SLO-2					
S-6	SLO-1	Newton's hypothesis for fluid flow	Example of numerical solution – cooling of a circular fin by convective heat transfer	Analysis of Numerical oscillations	Upwind Differencing Scheme	SIMPLE Algorithm
	SLO-2	Navier-Stokes equations			First order upwind scheme	Applications of SIMPLE
S-7	SLO-1	Conservation law for Energy equation	Comparison with analytical solution	Stability condition for Explicit Approach	Assessment of Upwind Differencing Scheme	Overview of other pressure-velocity coupling algorithms
	SLO-2	Work done by surface forces & Energy flux due to heat conduction		Stability condition for Implicit Approach		
S-8	SLO-1	Derivation of Energy equation	Coding using MATLAB	Overrelaxation and underrelaxation	Overview of other upwind schemes	Types of practical boundary conditions
	SLO-2			Grid layout-2D domain		
S-9	SLO-1	Equilibrium and marching problems	Discretization of 2 – D diffusion equation	Discretization of 2 – D unsteady diffusion Equation	Numerical Diffusion	Grid independency Test
	SLO-2	Initial and boundary conditions	General forms of discretized equations			Best practices for CFD solution

Learning Resources	1. Anil Date, <i>Introduction to CFD</i> Cambridge University Press First Edition (2005) 2. Versteeg. H.K and Malalasekera. W. "An Introduction to Computational Fluid Dynamics, the Finite Volume Method" Addison Wesley Longmen Limited, Second Edition (2007)	3. Patankar. S.V. "Numerical Heat Transfer and Fluid Flow", Hemisphere Publishing corporation, First Edition (1980.) 4. John.D.Anderson jr., "Computational Fluid Dynamics – The basics with applications" McGraw Hill First Edition (1995)
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. N. R. Hero Hemaraj, Senior Data Scientist, General Electric, Bangalore	Dr. B. Premachandran, Professor, Mechanical Engineering, IIT Delhi	Dr. S. Senthilkumar, SRMIST

Course Code	18ASE308T	Course Name	ROCKETS AND MISSILES	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18ASC303J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Aerospace Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	To impart design basics of rockets and missiles systems, their construction and functions.	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	To focus on design principles, materials selection, testing and performance assessment.		
CLR-3 :	To understand aerodynamics, flight dynamics, optimization of performance of multi-stage rockets and separation dynamics.		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom) Expected Proficiency (%) Expected Attainment (%)	Engineering Knowledge Problem Analysis Design & Development Analysis, Design, Research Modern Tool Usage Society & Culture Environment & Sustainability Ethics Individual & Team Work Communication Project Mgt. & Finance Life Long Learning PSO - 1 PSO - 2 PSO - 3
CLO-1 :	To learn about the different systems of rockets and missiles, formulation of the equation of motion and about the advanced rockets for future missions	2 80 70	H H H H M - - - - - M H H L
CLO-2 :	To understand the function of the solid propellant propulsion and pyrotechnic systems and the design principles	2 80 70	H H H H H - M - - M M M H H -
CLO-3 :	To understand the function of the liquid propellant propulsion and control systems and the design principles	2 80 70	H H H H M - M - - M M M H H -
CLO-4 :	To formulate the equation of motions for a mission and spent stage separation dynamics, understanding the principles of navigation, guidance and control of rockets and missiles, and design of a multistage rocket	2 80 70	H H H H H - H - L L H H H H -
CLO-5 :	To understand the system design, construction, function, performance and testing aspects. and to familiarize with the selection of suitable materials for different rocket systems	3 80 70	H M M H M L H L H M H H H H L

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Introduction	Solid propellant rocket fundamentals	Liquid propellant rocket fundamentals	Multi-staging of rockets	Design of prototype rocket
	SLO-2 Classification of launch vehicles and missiles				
S-2	SLO-1 Different space missions	Propellant ingredients, Propellant properties	Liquid propellant rocket applications	Performance estimation of multi-stage rockets	Requirement and design approach
	SLO-2 Rocket flight systems	Propellant grain processing	Liquid propellant rocket types		
S-3	SLO-1 Forces and moments acting on a rocket	Propellant Grain types, requirements	Design of propellant feed system	Multi-stage vehicle optimization techniques	Product design
	SLO-2 Propulsion, aerodynamics				
S-4	SLO-1 Gravity, control systems	Grain design, properties	Gas pressure feed system	Flight trajectory optimisation	Process planning aspects
	SLO-2 Stability analysis			Constraints in optimisation	
S-5	SLO-1 Inertial and non-inertial frames, coordinate transformation	Ballistics of missiles	Design of fuel tanks	Rocket flight simulation techniques	Material selection criteria
	SLO-2 Coriolis theorem		Turbo-pump design		Super alloys, Composites

S-6	SLO-1	equations of motion for three dimensional motion through vacuum and atmosphere	Burn rate control design and evaluation	Liquid propellant rocket engine cycle	Stage separation system	Test and Qualification
	SLO-2				Stage separation dynamics	
S-7	SLO-1	Reentry flight dynamics	Solid rocket components	Cooling systems	Separation techniques	Types of tests
	SLO-2				reentry vehicles landing techniques	
S-8	SLO-1	Rocket flight performance dispersion	Solid rocket motor design	Liquid Slosh, Pogo	Navigation, guidance and control systems in launch vehicle	Environmental tests
	SLO-2	Computation methods		Water hammer, Geyser effect		
S-9	SLO-1	Introduction to single stage to orbit concepts, reusable launch vehicles	Separation systems	Thrust vector control (TVC) system	Missiles guidance	Planning details
	SLO-2	Advanced space propulsion systems	Pyrotechnic devices	Performance improvement of TVC	Aerodynamic control systems	Concluding a normal and incomplete test

Learning Resources	1. Ramamurthi.K: "Rocket Propulsion", Macmillan Publishers, New Delhi-110002, March, 2010 2. George.P.Sutton, Oscar Biblarz: "Rocket Propulsion Elements" John Wiley India, New Delhi-110002, June, 2010 3. Taylor, Travis. S: "Introduction to rocket science and engineering" CRC Press, New York, 2009. 4. Cornelisse, J.W, Schoyer H F R, and Wakker K F, "Rocket Propulsion and Space Dynamic", Pitman Publishing Co., 1979 5. Ashish Tewari, "Atmospheric and Space Flight Dynamics", Birkhauser Boston, 2007				6. Martin J L Turner, "Rocket and Spacecraft Propulsion", Springer Praxis Publishing Co, 2004 7. Ronald Humble, Henry and Larson, "Space Propulsion Analysis and Design", McGraw-Hill, 1995 8. George M Siouris, "Missile guidance and control systems", Springer, 2004 9. W J Larson and J R Wertz, "Space Mission Analysis and Design", Kluwer Academic Publishers, 1999 10. Michael Griffin, "Space Vehicle Design", AIAA education series, 2004	

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Evaluate Create	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Dr. Manishankar C., Senior Scientist, NAL, Bangalore	Prof. Arun Kumar P., Assistant Professor, IIT Jammu	Dr. S. M. Aravindh Kumar, SRMIST
		Mr. K. Allwyn, SRMIST

Course Code	18ASE309T	Course Name	FATIGUE AND FRACTURE MECHANICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18ASC304J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Aerospace Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand the concepts of plotting S-N curve, mean stress, stress concentration				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Emphasis the study of low cycle fatigue, load histories, cumulative damage & statistical aspects of fatigue.				Learning (Bloom)			Knowledge	Analysis	Development	Design, Research	Usage	Culture	& Sustainability	Team Work	Communication	Finance & Economics	Learning				
CLR-3 :	Familiarize with physical aspects, surface effects, temperature effects of fatigue.																					
CLR-4 :	Familiarize with types of fracture, strain energy release rate, theoretical strength of materials.																					
CLR-5 :	Familiarize the various design philosophies, case histories, fatigue resistance of fiber laminates..																					
CLR-6 :	Get a better understanding of solving Fatigue problems																					

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Apply the knowledge to plot S-N curve for various materials.	2	85	75	H	H	H	-	-	-	-	-	-	-	-	M	M	M	M
CLO-2 :	Analyze low cycle fatigue & load histories problems.	2	85	75	H	H	H	-	-	-	-	-	-	-	-	M	M	M	M
CLO-3 :	Apply the physical aspects of fatigue for solving problems.	2	85	75	H	H	H	H	-	-	-	-	-	-	-	M	M	M	M
CLO-4 :	Analyze fracture of various materials	2	85	75	H	H	H	-	-	-	-	-	-	-	-	M	M	M	M
CLO-5 :	Analyze the various design philosophies.	2	85	75	H	H	H	-	-	-	-	-	-	-	-	M	M	M	M
CLO-6 :	Accrue comprehensive knowledge in fatigue & fracture problems	2	85	75	H	H	H	H	-	-	-	-	-	-	-	M	M	M	M

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Introduction to Fatigue & Fracture	Low cycle fatigue	Structural aspects of fatigue, Crack initiation, slip band crack growth	Types of fracture in metals	Introduction to various design philosophies
	SLO-2 S-N curve	High cycle fatigue	Structural aspects of fatigue, Crack initiation, slip band crack growth	Types of fracture in metals	Safe life and fail safe design philosophy
S-2	SLO-1 Endurance limit	Coffin-Manson's relation	Crack growth on planes of high tensile stress, Ultimate fracture	Theoretical cohesive strength	Infinite life and manage tolerant design philosophies
	SLO-2 Effect of mean stress on fatigue	Transition life	Crack growth on planes of high tensile stress, Ultimate fracture.	Theoretical cohesive strength	Infinite life and manage tolerant design philosophies
S-3	SLO-1 Goodman diagram	Solving problems	Fatigue crack propagation, Paris law	Solving problems	Uncertainties, scatter and safety margins
	SLO-2 Gerber and Soderberg relations	Solving problems	Fatigue crack propagation, Paris law	Solving problems	Uncertainties, scatter and safety margins
S-4	SLO-1 Solving problems	Cyclic hardening, cyclic softening, cyclic stress strain curve	Solving problems	Griffith theory of brittle fracture.	Some case histories, Improved shoulder fillets
	SLO-2 Solving problems	Cyclic hardening, cyclic softening, cyclic stress strain curve	Solving problems	Irwin-Orwin theory.	Secondary bending due to non-symmetric holes.
S-5	SLO-1 Notches and Stress concentrations	Solving problems	Size effects on fatigue	Solving problems	Cracked aircraft wing panel repaired with a poorly designed patch
	SLO-2 Notches and Stress concentrations	Solving problems	Surface effects on fatigue	Solving problems	Online structural monitoring of the Tsing Ma bridge
S-6	SLO-1 Solving problems	Strain life equations	Surface roughness, surface properties	Strain energy release rate	Fatigue resistance of fiber-metal laminates, laminated sheet without fibers
	SLO-2 Solving problems	Solving problems	Surface residual stresses	Stress intensity factor, Crack deformation modes	Fatigue resistance of fiber-metal laminates, laminated sheet without fibers
S-7	SLO-1 Neuber's stress concentrations	Analysis of load histories	Fatigue under combined stresses	Solving problems	Fiber-metal laminate Arall and Glare, Fiber metal laminate concept
	SLO-2 Solving problems	Level crossing method	Fatigue under combined stresses	Solving problems	Fiber-metal laminate Arall and Glare, Fiber metal laminate concept

S-8	SLO-1	Plastic stress concentration	Range counting method, Rain flow method	Effects of metallurgical variables on fatigue	Fracture toughness and design	Fiber-metal laminate Arall and Glare, Fiber metal laminate concept
	SLO-2	Solving problems	Solving problems	Corrosion fatigue, fretting	Plane strain toughness testing	Fiber-metal laminates as sheet material
S-9	SLO-1	Notched S-N curve	Cumulative damage, Miner's rule	Effect of low temperature fatigue	Solving problems	Crack growth on Glare
	SLO-2	Solving problems	Solving problems	Effect of high temperature fatigue	Solving problems	Fatigue properties of Glare components

Learning Resources	1. George E.Dieter., "Mechanical Metallurgy", McGraw Hill Education (India) Private Limited, New Delhi, Third Edition, 2013.	3. Barrels, W., and Ripley, "Fatigue of Aircraft Structures", Pergamon Press, Oxford, 1983
	2. Jaap Schijve, "Fatigue of structures and materials" Springer, Second edition, 2009.	4. Knott J.F., "Fundamentals of fracture Mechanics", Butterworth & Co., (Publisher) Ltd., London, 1983

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. G.Balamurugan, National Aerospace Laboratories, Bangalore, gbala@nal.res.in	1. Dr. V.Arumugam, Madras Institute of Technology, Chennai, arumugam.mitaero@gmail.com	1. Dr.L.R.Ganapathy Subramanian, SRMIST
2. Dr.A. Sakthivel, CEMILAC, Bangalore, asakthironika@gmail.com	2. Dr. R. Velmurugan, Indian Institute of Technology Madras, rvel@ae.iitm.ac.in	2. Mr. S. Chandra Sekhar, SRMIST

Course Code	18ASE310T	Course Name	CRYOGENIC ENGINEERING				Course Category	E	Professional Elective				L	T	P	C								
													3	0	0	3								
Pre-requisite Courses		18ASC103T		Co-requisite Courses		Nil		Progressive Courses		Nil														
Course Offering Department		AEROSPACE ENGINEERING				Data Book / Codes/Standards		Nil																
Course Learning Rationale (CLR):		The purpose of learning this course is :						Learning			Program Learning Outcomes (PLO)													
CLR-1 :	To have a detailed study of the basics of cryogenic systems and to provide the knowledge of evolution of low temperature science						1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	To familiarize with various Gas-Liquefaction Systems, Cryo-coolers and gas Refrigeration Systems						Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	To provide the knowledge of cryogenic insulations and Cryogenic technology																							
CLR-4 :	To gain knowledge about different cryogenic instrumentation and to understand Cryo pumping.																							
CLR-5 :	To provide design aspects of cryogenic storage and transfer lines.																							
CLR-6 :	To understand cryogenic systems, gas liquefaction system and pumping system and applications																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:						2	80	70	H	-	-	-	-	-	-	-	-	H	-	-	M	
CLO-1 :	Analyze the Cryogenic systems						2	85	75	H	H	H	H	-	-	-	-	-	-	-	-	M	-	M
CLO-2 :	Have a detailed knowledge of, Gas-Liquefaction Systems, cryo-coolers and gas Refrigeration Systems						2	75	70	H	H	H	H	-	-	-	-	-	-	-	H	M	M	-
CLO-3 :	Understand Cryogenic Insulations and Cryogenic Technology.						2	85	80	H	-	-	-	-	-	-	-	-	-	-	H	-	M	M
CLO-4 :	Understand different cryogenic instrumentation						2	85	75	H	-	-	-	-	-	-	-	-	-	-	H	M	-	-
CLO-5 :	Know and to understand various cryogenic fluid storage and transport systems						2	85	75	H	-	-	-	-	-	-	-	-	-	-	H	M	-	-
CLO-6 :	Know cryogenic systems, gas liquefaction system and pumping system and applications						2	85	75	H	H	H	H	-	-	-	-	-	-	-	H	M	M	M
Duration (hour)		9		9		9		9		9		9												
S-1	SLO-1	Introduction - Cryogenic propellants		Claude cycle	Vuilleumier refrigerator		Numerical Problems on Gas Separation System		Mechanical vacuum pumps															
	SLO-2	Liquid hydrogen, liquid oxygen			Cryogenic regenerators																			
S-2	SLO-1	liquid nitrogen, liquid helium		Claude Liquefaction System	Numerical Problems on Cryogenic Refrigeration system		Numerical Problems on Gas Separation System		Diffusion pumps															
	SLO-2	Properties of cryogenic fluids at cryogenic temperature - Mechanical properties																						
S-3	SLO-1	Thermal properties		Heylandt System	Thermodynamic ideal Gas separation system		Pre purification of Air		Cryo-Pumping															
	SLO-2	Electrical properties		Comparison of Claude and L.H system	Principles of gas separation		Vacuum Technology- Introduction		Cryogenic fluid storage vessels															
S-4	SLO-1	Ortho Hydrogen & Para Hydrogen		Numerical Problems on Claude cycle	Linde single column gas separation		Production of high vacuum		Cryogenic Insulation - Introduction															
	SLO-2	Safety in Cryogenics			Linde double column gas separation																			
S-5	SLO-1	Applications in Space Technology		Numerical Problems on L-H cycle		Argon and Neon separation systems		Flow Regimes in Vacuum		Methods of Cryogenic Insulation														
	Cryocoolers- Introduction																							
S-6	SLO-1	Gas Liquefaction systems- Introduction		Classification of Cryocoolers		Cryogenic Gas Adsorption		Conductance in Vacuum		Evacuated powder insulation														
	Stirling Cryo – cooler																							
S-7	SLO-1	Joule Thomson effect		Gifford-McMahon Cry cooler		Cryo-condensation Process	Pressure drop- Slip flow and mixed flow		Opacified powder insulation															
	SLO-2	Joule Thomson Coefficient		Gas Cycle Refrigeration system- Introduction			Numerical Problems on Vacuum Technology		Gas filled powders Multilayer super-insulation															
S-8	SLO-1	Linde –Hampson cycle		Classification of Gas Cycle refrigeration		Numerical problems on Gas separation system		Numerical Problems on Vacuum Technology		Fibrous materials Multilayer super-insulation														
S-9	SLO-1	Linde –Hampson System		Pulse tube refrigerator		Numerical problems on Gas separation system		Numerical Problems on Vacuum Technology		Propellant servicing														
	Solvay cycle refrigerator					Propellant management																		
										Cryogenic fluid transfer systems														
Learning Resources	1. Randall F. Barron., "Cryogenic Systems", Oxford University, Second edition,1985 2. Walker.G , "Cryocoolers", Plenum Press, First edition,New York (1983) 3. Mamata Mukhopadhyay, "Fundamentals of Cryogenic Engineering", PHI Learning (P) Ltd, India, Fourth edition 2010						4. J.H.Bell , "Cryogenic Engineering" , Prentice Hall, Englewood Cliffs,First edition,1963 5. Pamer, S. F., "Propellant Chemistry", Reinhold Publishing Corpn., New York,1985 6. R.B.Scott , "Cryogenic Engineering" , Van Nostrand Co, New Jercey,1959																	

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Dr. S. Raja, Senior Principal Scientist and Professor, NAL – Bangalore. raja@nal.res.in	1.Dr.Parthasarathi Ghosh, Head, Cryogenic Engineering Centre, IIT Kharagpur psghosh@hijli.iitkgp.ernet.in	1.Mr. G. Saravanan SRMIST
	2. Dr P.K Dsah, Professor and Head, Department of Aeronautical Engineering Nitte Menakshi Institute of Technology, Bangalore. drpdash@gmail.com	2.Mr Vinayak Malhotra SRMIST

Course Code	18ASE311T	Course Name	AIRCRAFT ENGINE AND INSTRUMENT SYSTEMS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Aerospace Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Identify the type ofReciprocating enginefuel metering system and its components used in aircraft.	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15			
CLR-2 :	Layout the components and accessories of gas turbine engine fuel system.																					
CLR-3 :	Demonstrate the type ofinduction and exhaust system in aircraft engines.																					
CLR-4 :	Identify the electrical systems used in in aircraft engines.																					
CLR-5 :	Identify the various aircraft engine instruments and their functions.																					
CLR-6 :	Utilize the knowledge acquired for design, development & maintenance of aircraft & aero engine systems.																					

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1:	Understand the operation of Reciprocating engine fuel metering system and its components used in aircraft.	2	80	70	H	-	L	L	L	-	-	-	-	-	-	L	L	M	M
CLO-2:	Acquire knowledge on components and accessories of gas turbine engine fuel system.	2	80	70	H	-	M	L	M	-	-	-	-	-	-	-	M	M	M
CLO-3:	Learn the working of induction and exhaust system in aircraft engines.	2	80	70	H	-	L	L	M	-	-	-	-	-	-	L	M	M	M
CLO-4:	Appreciate the need and functions of aircraft electrical systems used in aircraft engines.	2	80	70	H	-	L	L	L	-	M	M	-	-	-	L	M	M	M
CLO-5:	Gain knowledge on principle and operation of various aircraft engine instruments.	2	80	70	H	L	L	L	M	-	-	-	-	M	-	L	H	H	M
CLO-6:	Acquire comprehensive knowledge of aircraft systems, engine systems and its instrumentation.	2	80	70	H	L	L	L	M	-	M	M	-	M	-	L	M	M	M

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Introduction to Reciprocating Engines	Introduction to Gas Turbine Engines	Introduction to Induction Systems	Electrical Power Evolution	Introduction to Aircraft Engine Instruments
	SLO-2 Design and Construction, modular concept	Gas Turbine Engines modular concept	Reciprocating Engine Induction Systems	Aircraft Electrical Systems	Reciprocating engine instruments
S-2	SLO-1 Fuels and their characteristics for IC engines.	Fuels and their characteristics for gas turbine engines	Basic Carburetor Induction System	Basic Aircraft Electrical Systems	Operation of Oil pressure
	SLO-2 Contamination of fuels and prevention	Contamination of fuels and prevention	Induction System Icing, Induction System Filtering	Power Generation	Oil temperature indicators
S-3	SLO-1 Fuel system- Basic Fuel System	Turbine Engine Fuel System	Supercharged Induction Systems	DC Power Generation	Operation of Cylinder head temperature (CHT) indicator
	SLO-2 Fuel System Requirements	General Requirements	Operation & Advantages	Typical Aircraft DC System	Manifold pressure indicator
S-4	SLO-1 Fuel Metering Devices for Reciprocating Engines	Hydro mechanical Fuel Control	Reciprocating Engine Exhaust Systems	AC Power Generation	Operation of Fuel quantity, Fuel pressure
	SLO-2 Fuel/Air Mixtures, Carburetion Principles	Hydromechanical/Electronic Fuel Control	Exhaust Systems With Turbocharger.	Inverters, rectifiers	Carburetor temperature, Tachometer indicators
S-5	SLO-1 Application of Venturi Principle to Carburetor	Operation of Hydromechanical/Electronic Fuel Control	Gas Turbine Engines engine inlet systems	Transformers, Batteries	Introduction to Gas Turbine Engine instruments types
	SLO-2 Carburetor Systems, Carburetor Types	Introduction to FADEC	Compressor Inlet Screens	Airplane lighting systems	Principle & Operation of Oil pressure
S-6	SLO-1 Float-Type Carburetors, Float Chamber Mechanism System	FADEC Fuel Control Systems	Turboprop and Turboshaft Compressor Inlets	Classification of lighting systems	Exhaust gas temperature (EGT)
	SLO-2 Main Metering, Idling, Accelerating and Economizer System	FADEC for an Auxiliary Power Unit	Turbofan Engine Inlet Sections	External Lighting Systems	Turbine inlet temperature (TIT) or turbine gas temperature (TGT)
S-7	SLO-1 Pressure Injection Carburetors	FADEC Fuel Control Propulsion Engine	Gas Turbine Engines Engine Exhaust Systems	Internal Lighting Systems	Engine pressure ratio (EPR)
	SLO-2 Operation of Pressure Injection Carburetors	Operation and its Advantages	Turbine engine exhaust nozzles	Airplane lighting- Power utilization in airplanes	Principle & Operation of Fuel quantity, Fuel pressure

S-8	SLO-1	Manual Mixture Control	Engine Fuel System Components	Thrust Reversers	Ground Power	Fuel flow indicator
	SLO-2	Automatic Mixture Control (AMC)	Main Fuel Pumps, Fuel Heater, Fuel Filters	Afterburning / Thrust augmentation	Emergency Power Generation	Principle & Operation of Tachometer (percent calibrated) N1 and N2 compressor speeds
S-9	SLO-1	Fuel-Injection Systems	Flow Divider, Fuel Pressurizing and Dump Valves	Thrust Vectoring	Ram Air Turbine, Backup Power Converters	Principle & Operation of Torquemeter
	SLO-2	Bendix/Precision Fuel-Injection System	Fuel Spray Nozzles and Fuel Manifolds	Engine noise suppression, Turbine engine emissions.	Permanent Magnet Generators (PMGs)	Torquemeter (on turboprop and turboshaft engines)

Learning Resources	1. Aviation Maintenance Technician Handbook – Airframe, Vol.2, U.S.Dept. of Transportation, Federal Aviation Administration, Flight Standards Service, 2012 2. Aviation Maintenance Technician Handbook – Powerplant, Vol.1, 2, U.S.Dept. of Transportation, Federal Aviation Administration, Flight Standards Service, 2012 3. E.H.J.Pallet, Aircraft Instruments, 2 nd edition, Pearson Publishing Company, 2009 4. Adrian P. Mouritz, "Introduction to aerospace materials" Woodhead Publishing Limited, 2012 5. Michael J.Kroes, William A.Watkins and Frank Delp, Aircraft Maintenance and Repair, 7 th ed., Tata McGraw Hill, 2013
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Wg.Cdr K.Manoharan (Retd), Blue Dart Aviation Ltd., manoharank@bluedart.com	1. Dr. A. P. Haran, Park College of Engineering & Technology, ap_haran@rediffmail.com	1. Dr. S. Sivakumar, SRMIST
2. Mr.K.Senthilkumar, Deputy Chief Aircraft Engineer, Air India, Bangalore ks_senthilkumar@yahoo.co	2. Dr.Wg.Cdr.N.Muthusamy, Rajalakshmi Engineering college, Chennai, muthusamy55@gmail.com	2. Mr. S. Raj Kumar SRMIST

Course Code	18ASE312T	Course Name	HELICOPTER MAINTENANCE	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Aerospace Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:		Learning			Program Learning Outcomes (PLO)																	
CLR-1 :	Identify the type of rotor, helicopter controls ,gears, bearings and ground handling	Thinking (Bloom)	Proficiency (%)	Attainment (%)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2 :	Layout the main rotor system components and its maintenance.																							
CLR-3 :	Demonstrate the engine power transmission to rotors.																							
CLR-4 :	Identify the power plant installation and maintenance																							
CLR-5 :	Identify the various airframe construction and related systems.																							
CLR-6 :	Utilize the knowledge acquired for design, development & maintenance of Helicopter.																							

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1:	Understand the helicopter fundamentals and its main components.	2	80	70	H	-	L	L	L	-	-	-	-	-	-	L	L	M	M
CLO-2:	Acquire knowledge on main rotor components and its maintenance.	2	80	70	H	-	M	L	M	-	-	-	-	-	-	-	M	M	M
CLO-3:	Learn the working of helicopter transmission system.	2	80	70	H	-	L	L	M	-	-	-	-	-	-	L	M	M	M
CLO-4:	Acquire knowledge of installation and maintenance of helicopter engines.	2	80	70	H	-	L	L	M	-	M	M	-	-	-	L	M	M	M
CLO-5:	Gain knowledge on helicopter fuselage construction and related systems.	2	80	70	H	L	L	L	M	-	-	-	-	M	-	L	H	H	M
CLO-6:	Acquire comprehensive knowledge of helicopter rotors ,transmission, fuselage and other components and its maintenance activities	2	80	70	H	L	L	L	M	-	M	M	-	M	-	L	M	M	M

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Introduction to Helicopters	Head maintenance	Gradient control boosts	Different types of power plant	Structural components and materials- Body structure
	SLO-2 Evolution of helicopter	Blade alignment	Maintenance in control rigging	Different types of power plant maintenance	Bottom structure
S-2	SLO-1 Helicopter rotor arrangements	Static main rotor balance	Inspection in control rigging	Maintenance of typical Eurocopter Engine	Cabin section
	SLO-2 Rigid rotor arrangements	Vibration, Tracking methods	Engine transmission coupling	Tail rotor system	Rear section
S-3	SLO-1 Semi-rigid rotor arrangements	Spanwise dynamic balance	Drive shaft	Servicing tail rotor track	Tail Boom
	SLO-2 Helicopter flight controls	Blade sweeping	Maintenance clutch	System rigging	Vertical fin
S-4	SLO-1 Basic directions ,colour codes	Electronic balancing	Freewheeling units	Rotary wing fuselage structural construction	Horizontal stabilizer
	SLO-2 Ground handling	Dampener maintenance	Spray clutch	Tubular, sheet metal construction	Skid gear
S-5	SLO-1 Towing	Counter weight adjustments	Roller unit	Bonded construction	Antivibration device
	SLO-2 Towing precautions	Auto rotation adjustments	Torque meter	Bell-206	Special purpose equipments
S-6	SLO-1 Helicopter protection	Mast& Flight Control rotor	Rotor brake	Eurocopter BO-105	High skid gear
	SLO-2 protection equipments	Mast Stabilizer	Rotor brake maintenance of roller unit	Fueslage	Floats
S-7	SLO-1 Bearing and It's types	Mast Dampeners	Rotor brake maintenance of torque meter	Fuselage maintenance	Resque hoists
	SLO-2 Bearing installation	Swash plate flight control systems collective	Vibrations in transmission systems	Airframe systems	Cargo Hooks
S-8	SLO-1 Bearing maintenance	Cyclic	Mounting systems	Stress and loads on airframe	Litter Installations
	SLO-2 Elastomeric bearings	Push-pull tubes	Transmissions	Wheel	Light Installations
S-9	SLO-1 Gear, types	Torque tubes, bell cranks	Fixed wing power plant modifications	Skid gear	Spray equipment
	SLO-2 Gear pattern	Mixer box	Installation of typical Eurocopter engine	Visibility	Stabilization devices

Learning Resources	1. Jeppesen, Helicopter Maintenance Hand Book, Jeppesons and Sons Inc, 2000. 2. Gupta L, Helicopter Engineering , Himalayan books , 1996	3. Civil Aircraft Inspection procedures part I and II ,CAA, English Book House ,New Delhi, 1986. 4. Larry Reiethmier , Aircraft repair manual ,Palamar Books Marquette, 1992
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

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2. Mr.K.Senthilkumar, Deputy Chief Aircraft Engineer, Air India , Bangalore ks_senthilkumar@yahoo.co	2. Dr.Wg.Cdr.N.Muthusamy, Rajalakshmi Engineering college, Chennai, muthusamy55@gmail.com	2. Mr. S. Raj Kumar SRMIST

Course Code	18ASE313T	Course Name	AERIAL ROBOTICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Aerospace Engineering			Data Book / Codes/Standards	

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand the kinematics and dynamics of fixed wing unmanned aerial vehicle				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Understand the kinematics and dynamics of multirotor micro aerial vehicle.				Thinking (Bloom)	Efficiency (%)	Attainment (%)	Knowledge	Analysis	Development	Design, Research	Usage	Culture	Sustainability	Team Work	Communication	Finance & Economics	Learning				
CLR-3 :	Understand the State estimation of Aerial Robots																					
CLR-4 :	Understand the flight controls methods of Aerial Robots																					
CLR-5 :	Understand the applications of Aerial Robots																					
CLO-6 :	Know dynamics of different types of aerial vehicle., flight control methods and its applications																					

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Mathematically model the kinematics and dynamics of fixed wing unmanned aerial vehicle	2	85	75	H	-	H	-	-	-	-	-	-	-	-	-	-	-	M
CLO-2 :	Mathematically model the kinematics and dynamics of multirotor micro aerial vehicle	2	85	75	H	-	H	-	-	-	-	-	-	-	-	-	M	M	-
CLO-3 :	Estimate the state of Aerial Robots	2	85	75	H	H	H	H	-	-	-	-	-	-	-	-	M	M	M
CLO-4 :	Design flight controls of Aerial Robots	2	85	75	H	-	-	-	H	-	-	-	-	-	-	-	M	M	M
CLO-5 :	Utilise the applications of Aerial Robots	2	85	75	H	-	-	-	-	H	-	-	-	-	-	-	-	-	-
CLO-6 :	Understand dynamics of different types of aerial vehicle, flight controls and its applications	2	85	75	H	-	H	H	H	H	-	-	-	-	-	-	M	M	M

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Introduction of Fixed Wing Unmanned Aerial Vehicle(FWUAV)	Introduction of Multirotor Micro Aerial Vehicle (MMAV)	Navigational Sensors	Introduction to Control Methods of UAV	Applications of Aerial Robots
S-2	SLO-1 History of Fixed Wing Unmanned Aerial Vehicle	History of Multirotor Micro Aerial Vehicle(MMAV)	Inertial Sensors	PID Control	Aerial Robots for Military Reconnaissance
S-3	SLO-1 Classification of Fixed Wing Unmanned Aerial Vehicle	Classification of Multirotor Micro Aerial Vehicle(MMAV)	Magnetometer	Lateral control of MMAV using PID	Target attacking aerial robots
S-4	SLO-2 Modelling and Dynamics Formulation	Propeller Theory	Pressure Sensor	LQR Control	Civil Applications
S-5	SLO-1 Frame Rotations and Representations	Thrust and Drag moment	GPS based Navigation	Design of LQR servo control in MATLAB	Surveying Aerial Robots
S-6	SLO-2 Euler angles	Dynamics of a Multirotor Micro Aerial Vehicle(MMAV)	Camera based Navigation	Model Predictive Control for UAV	Aerial mapping
S-7	SLO-1 Quaternions	Gravitational force modelling of FWUAV	Position Estimation	Linear Model Predictive Control	Aerial robots for Precision Agriculture
S-8	SLO-2 Propulsive force modelling of FWUAV	Propulsive force modelling of MMAV	Velocity Estimation	Design of a Linear MPC for MMAV	Payload Delivery
S-9	SLO-1 Aerodynamic Force modelling FWUAV	Aerodynamic Force modelling MMAV	Inertial Navigation Systems	Implementation of a Linear MPC for MMAV	Film making
	SLO-2 Moments acting on FWUAV	Moments acting on MMAV	Attitude estimation		Scientific Research
	SLO-1 Dynamics of a Fixed-Wing Unmanned Aerial Vehicle	Mathematical modelling of Multirotor Micro Aerial Vehicle(MMAV)			Search and Rescue
	SLO-2				Mineral Exploration Aerial Robots

Learning Resources	1. R. Beard, and T. W. McLain, 'Small Unmanned Aircraft: Theory and Practice' Princeton University Press, 2012. 2. R.C. Nelson., Flight Stability and Automatic Control, McGraw Hill, New York 1998. 3. L.R. Newcome., Unmanned Aviation, a Brief History of Unmanned Aerial Vehicles, American Institute of Aeronautics and Astronautics, Reston 2004. 4. Kuo, B.C., Automatic Control Systems, Prentice Hall, 1991.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. S. Raja, Senior Principal Scientist and Professor, NAL – Bangalore. raja@nal.res.in	1. Dr.K.M.Parammasivam, Professor, MIT-Chennai. mparams@mitindia.edu	Mr.A.Vinoth Kumar, SRMIST.

ACADEMIC CURRICULA

Professional Elective Courses

AUTOMOBILE ENGINEERING

Regulations - 2018



SRM INSTITUTE OF SCIENCE AND TECHNOLOGY

(Deemed to be University u/s 3 of UGC Act, 1956)

Kattankulathur, Kancheepuram, Tamil Nadu, India

Course Code	18AUE321T	Course Name	AUTOMOTIVE COMPONENTS MANUFACTURING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	acquire knowledge in understanding the manufacturing processes of automotive components				Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	understanding the professional and ethical responsibility																							
CLR-3 :	Understand The process to meet desired needs within realistic																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			Expected Proficiency (%)	Expected Attainment (%)																		
CLO-1 :	Understand the automotive component to be manufactured				1	90	85	H	M	M	M	L	H	M	H	M	L	M	M	H	H	M	L	
CLO-2 :	Select the suitable materials for the component based on its functionality				2	95	90	H	M	M	M	L	M	M	H	M	L	L	M	H	M	L		
CLO-3 :	Identify the suitable manufacturing process for the component				2	90	85	H	H	M	M	L	L	M	H	H	L	L	M	H	H	M		
CLO-4 :	Examine the primary & secondary machining operation.				2	95	90	H	M	M	M	L	L	M	H	M	L	M	M	H	M	M		
CLO-5 :	Identify the possible defects and suggest suitable remedies				2	85	80	H	M	M	M	L	L	M	H	M	L	L	M	H	H	L		

		Introduction to Automotive Engine Components	Manufacturing of Automotive Engine Components	Manufacturing of Air filters and catalytic converter of spark plugs	Manufacturing of glass & rubber processing technology	Manufacturing of Automotive body
Duration (hour)		09	09	09	09	09
S-1	SLO-1	Introduction to automotive engines - parts, Their function requirement,	Manufacturing of main bearing – Description, Purpose, Material-Production requirement – Consistent wall thickness, Precise crush height, process requirement	Manufacturing of Air filters-Description of Air filters, Functional requirement of air filters	Raw material preparation & melting- Properties of glass-Classification of glass for automotive application	Automotive materials-Automotive steel grades
	SLO-2	Material used in the automotive sector	Centrifugal casting Mold material, Consideration for main bearing in centrifugal casting.-Surface finishing for main bearing	Materials – Core materials, sealing agents, supporting materials.-Production	Glass melting furnace- Pot furnace, Day tank, Continuous tank, Electric furnace	High strength & ultra-strength-Stamping aluminum sheet
S-2	SLO-1	Manufacturing of an engine block of cylinder head-Functional requirement of an engine block	Manufacturing of main bearing cap- Functional requirement	Manufacturing of oil filters-Description of oil filters	Shaping process in glass working-Shaping of Glass- Spinning, processing, blowing	Automotive stamping process & die-Die operations & tooling
	SLO-2	cylinder head-Materials used in engine block casting	Material requirement – Special treatment materials for cap	Functional requirement of oil filters	Shaping of flat glass – Rolling, float, Drawing of glass tubs	Blank holder-Draw B
S-3	SLO-1	Manufacturing process –Low pressure die casting, High pressures die-casting, expendable pattern casting.	Production requirement-Process requirement – Hot chamber die casting	Manufacturing of oil filters-Materials	Forming of glass fibers-Centrifugal spraying	Blanking & sharing dies-Binding
	SLO-2	Machining–Cutting, Milling, Drilling, Boring, Honing, Reaming	Cold chamber die casting-Precision drilling operation	Manufacturing of oil filters-Production	Drawing of continuous filaments	Deep drawing-Coating & lubrication
S-4	SLO-1	Quality consideration during manufacturing	Vibration damper-Functional requirement, Description of vibration, Material requirement, Production requirement,	Manufacturing of ceramic catalytic converter-Description of ceramic catalytic converter	Heat treatment & finishing-Annealing	Advances in metal forming-Hydro forming & extrusion
	SLO-2	Possible defects during manufacturing	Process description.-Vacuum casting Consideration for casting damper-Why vacuum casting & its advantages	Functional requirement	Tempered glass	Industrial origami : Metal folding – based forming-Flexible stamping procedure

S-5	SLO-1	Manufacturing of Camshaft-Functional requirement of Camshaft	Piston ring & pin-Description - types-Functional requirement	ceramic catalytic convertor-Material properties	Finishing – Primary design	Automotive TIG welding-Robotic spot welders
	SLO-2	Materials used in Camshaft, Production requirement-Process requirement	Material-Production requirement-Process requirement	Processing – Processing of starting materials, Shaping, sintering, finishing	secondary design considerations in glass processing	Adhesive bonding
S-6	SLO-1	Closed die forging, Impression die forging-forging force	Valves-Description, Functional requirement- Types of valves Monometallic, Bimetal, Stellite welded, Chrome plate, Nitrate	Manufacturing of metallic catalytic convertor-Description of ceramic catalytic convertor	Manufacturing of tires	Advances in automotive welding-Friction the welding
	SLO-2	Finishing operations. Heat treatment	Process – Cutting, Friction welding (Bimetal Special purpose), Upsetting, Forging, Stellite welding, Heat treatment, Grinding	metallic catalytic convertor Functional requirement	The construction of tires	Lack welding-Weld bonding
S-7	SLO-1	Manufacturing of crankshaft-Functional requirement of crankshaft	Automotive springs-Description, Functional requirement- Manufacturing process – Hot rolling, oil tempering, cold oiling.	metallic catalytic convertor Material properties-Need for honey comb structure is metal catalytic convertor	The production of tires	Automotive joining- automotive frame
	SLO-2	Materials used in crankshaft manufacturing	Stress relieving, Coil and grinding, nitriding, slot peering, Strain aging.	Methods of forming honey comb	The process of tires	Set assembling automotive doors
S-8	SLO-1	Production requirement	Inlet Manifold-Description, Functional requirement	Manufacturing of spark plug-Description of ceramic cat com	Performing of components	Final assembly-Installation of trim assembly
	SLO-2	Process requirement	Inlet Manifold Functional requirement	Functional requirement	Building the carcass	Installation of the chases-Final assembly & testing
S-9	SLO-1	Forging, Precision machining	Process Injection molding, Plastic materials,	Spark plug-Material selection	Molding of curing	Ergonomics of the final assembly
	SLO-2	Heat treatment	Injection molding, Injection molds.	Manufacturing of process – Processing of ceramic, forming of electrode, bonding.	Molding process	Mechanical fastening & bolting

Learning Resources	1. Serop Kalpakjian, "Manufacturing Engineering and Technology", 6th Edition, Addison-Wesley Publishing Co., Boston, 2010 2. Mohammed A. Omar, "The Automotive Body Manufacturing System and Processes" 1st Edition, John Wiley & Sons Inc, USA, 2011.	3. Mikell P. Groover "Fundamentals of Modern Manufacturing", 4th Edition, John Wiley & Sons Inc, 2010 4. Benjamin W Niebel, "Modern Manufacturing Process Engineering", McGraw- HILL international editions
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Evaluate Create	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

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Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Ajeet Babu ARAI, ajeetbabu.fid@araiindia.com	1. Dr. B. Mohan Anna University, bmohan@annauniv.edu	1. Dr. R. Rajendran, SRMIST, rajendrr@srmist.edu.in
2. Mr. Dalpat Singh M & M, singh.dalpat@mahindra.com	2. Dr. R. Elansezhian, Pondicherry Engineering College, elansezhianr@gmail.com	2. Mr. S. Madhan Kumar, SRMIST, madhank@srmist.edu.in

Course Code	18AUE322T	Course Name	WELDING AND JOINING TECHNIQUE	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Acquire knowledge on fusion welding processes and weld joints				Level of Thinking (Bloom)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLR-2 :	Select various welding process based on applications.					Expected Proficiency (%)				Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	List welding parameters and filler metals for various welding process					Expected Attainment (%)																		
CLR-4 :	Understand advanced welding techniques and its applications																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1 :	Categorize the various types of welding processes.				1	80	75	M	M	M	M	L	L	M	M	M	M	M	L	L	H	H	H	H
CLO-2 :	Explain various arc welding techniques and its applications				2	85	80	H	H	M	L	M	M	M	M	M	H	L	M	M	M	H	M	
CLO-3 :	Determine welding parameters for different types of materials				1	85	80	H	M	M	M	M	L	M	L	M	H	M	H	H	M	H	H	
CLO-4 :	Predict the welding process suitable for automotive applications				2	80	75	H	H	L	M	M	H	H	H	M	M	M	M	H	H	H	H	
CLO-5 :	Compare advanced welding with conventional welding techniques				2	75	70	H	H	M	M	H	M	M	M	H	M	H	M	M	H	H	M	

		Welding Technology	Fusion Welding Processes	Weldability of metals and Allied Processes	Resistance Welding and Thermo-chemical welding	Solid state and high energy beam Welding
Duration (hour)		9	9	9	9	9
S-1	SLO-1	Classification of fusion welding processes	Introduction to Arc Welding	Oxygen cutting	Spot welding and types of equipment	Friction welding
	SLO-2					Diffusion joining and process variables and its applications,
S-2	SLO-1	Heat source intensity, Heat Input rates	Carbon arc welding	Flame cut ability of metals, effect of cutting on structure and properties of steel	Rocker arm press type welding and it's applications	Forge welding
	SLO-2					
S-3	SLO-1	Shielding methods	Gas tungsten arc welding	Oxygen lancing machine cutting, Powder cutting	Seam welding and its applications	Ultra sonic welding
	SLO-2					
S-4	SLO-1	Metallurgical effect of weld thermal cycle	Gas Metal Arc Welding	Welding of different types of materials - carbon and alloy steels.	Projection welding and its applications	Explosive welding
	SLO-2					
S-5	SLO-1	Residual stresses	Plasma arc welding	Welding of different types of materials - Cast iron non-ferrous metals and alloys, aluminum.	Flash and butt welding applications	Laser welding
	SLO-2					
S-6	SLO-1	Formation and Relieving	Submerged arc welding	Soldering and Brazing: Capillary and welding action	Gas welding ,fuel gases and flames	Electron beam welding -types of electron gun
	SLO-2					
S-7	SLO-1	Types of weld joints	Electro slag welding	Soldering and Brazing-Temperature Range	Torches, Filler metal and Fluxes	Electron beam welding- spot size beam power
	SLO-2					
S-8	SLO-1	Edge preparation, cleaning of edges	Arc welding applications	Filler Metals and Fluxes	Backward and Forward welding and filler rod diameter	Operating voltage, pulse technique, deep penetration and applications
	SLO-2					
S-9	SLO-1	Tack welding	Arc welding advantages and disadvantages	Processes and application, Design and strength of joints	Thermit welding	Other Joining Techniques for automotive applications
	SLO-2					

Learning Resources	<ol style="list-style-type: none"> 1. Nadkarni. S. V, "Modern Arc Welding Technology", Ador Welding Ltd. Oxford and IBH Publishing, 2008. 2. William A. Bowditch, Kevin E. Bowditch, Mark A. Bowditch, "Welding Technology Fundamentals", Goodheart-Willcox Publisher, 4 edition, 2009 	<ol style="list-style-type: none"> 3. Richard L. Little, "Welding and welding Technology", TATA McGraw Hill Publishing Company Ltd, 1973. 4. Parmar. R. S, "Welding Engineering And Technology", Khanna Publishers, 2004
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	60%		50%		40%		15%		50%	
	Understand										
Level 2	Apply	40%		50%		60%		20%		50%	
	Analyze										
Level 3	Evaluate	-		-		-		15%		-	
	Create										
	Total	100 %		100 %		100 %		100 %		100%	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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2. Mr.S. Senthil Kumar, Deputy Manager, Renault Nissan Technology & Business Centre India, senthilkumar.subramanian@rntbci.com	2. Prof.V.Muthupandi, NIT Trichy, vmuthu@nitt.edu	2.Mr.G.Jesurajendran,AutomobileEngg SRMIST, jesurajg@srmist.edu.in

Course Code	18AUE323T	Course Name	AUTOMOTIVE SURFACE ENGINEERING	Course Category	E	PROFESSIONAL ELECTIVE	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:		Learning			Program Learning Outcomes (PLO)																				
CLR-1 :	Describe the surface preparation techniques			Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15			
CLR-2 :	Interpret the knowledge on thermal spraying technology for surface coating applications						Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3						
CLR-3 :	Understand the process of Hot dip and diffusion coating						H	M	H	M	L	L	H	M	M	M	L	M	M	M	M	M	M	M	M	M	H
CLR-4 :	Illustrate the testing procedure for surface coating						H	M	M	M	M	M	M	L	M	M	M	M	M	M	M	M	M	M	M	M	M
CLR-5 :	Understand the testing and selection of coating						H	H	M	H	M	L	L	L	M	M	-	M	M	M	M	M	M	M	M	M	M
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																									
CLO-1 :	Select the various techniques of surface preparation			3	90	85	H	M	H	M	L	L	H	M	M	M	L	M	M	M	M	M	M	L			
CLO-2 :	Identify the thermal spraying process and electrodeposited coating			1	80	75	H	M	M	M	M	L	M	-	M	M	-	M	M	M	M	M	M	H			
CLO-3 :	Distinguish the process of Hot dip and diffusion coating			2	85	80	H	M	M	M	M	M	M	L	M	M	M	M	M	M	H	M	M	H			
CLO-4 :	Perform the testing procedure for surface coating			2	85	80	H	H	M	H	M	L	L	L	M	M	-	M	M	M	M	M	M	M			
CLO-5 :	Analyze and select the coating for application			1	90	85	H	M	M	M	M	H	H	H	M	M	L	M	M	M	M	M	M	H			

		Metal Cleaning and Surface Treatment	Thermal Spraying Processes	Coatings	Non-Metallic coating oxide and Corrosion	Testing and Selection of coatings
Duration (hour)		09	09	09	09	09
S-1	SLO-1	Need and relevance of surface engineering	Classification of Thermal spraying	Principles – surface preparation batch coating	Plating coating	The quality plan, Design
	SLO-2	Pre-treatment of coating	Thermal barrier and Thermal conductive coatings	Continuous coating process	Lacquers	Testing and inspection of thickness measurement
S-2	SLO-1	General cleaning process for ferrous metals	Thermal spraying – flame	Properties of Coatings	Rubbers	Adhesion
	SLO-2	General cleaning process for non-ferrous metals	Arc spraying method	Applications of coatings	Elastomers	Resistance
S-3	SLO-1	Selection of cleaning process	Plasma Processes	surface treatments in wear	Vitreous enamels	Porosity measurement
	SLO-2	Alkaline cleaning	HVOF processes	Friction control	Anodizing phosphating and chromating	Selection of coatings
S-4	SLO-1	Emulsion cleaning	PLV process	Thick coatings	Application to Aluminium, Magnesium, Tin, Zinc, Cadmium Copper and Silver	Industrial applications of engineering coatings
	SLO-2	Ultrasonic cleaning	Coating production	Principles of cementation	Phosphating primers	Basic mechanisms of wear
S-5	SLO-1	Acid bath descaling	Spray consumables	Cladding	Principle of Corrosion	Abrasive Wear
	SLO-2	Pickling salt bath descaling	Principles of electroplating	Diffusion coating of C.N. Al, Si, Cr and B	Classification of corrosion	adhesive wear
S-6	SLO-1	Abrasive bath cleaning	Technologies used in electroplating systems	Corrosion resistant coatings	Types of corrosion	contact fatigue
	SLO-2	Surface treatment of gears	Factors affecting the electroplating process	Properties of diffusion coatings	Factors influencing corrosion	fretting corrosion
S-7	SLO-1	Short peening	Properties and Faraday's Law	Application of diffusion coatings	Corrosion protection of ferrous and non-ferrous components	Salt spray test
	SLO-2	Blasting	Factors affecting throwing power	Nano-engineered coatings	Testing and Prevention of Corrosion	Humidity test
S-8	SLO-1	Machining	Electroplating	Wear resistant coatings	Material selection	Porosity test
	SLO-2	Boronizing	Applications of electroplating	Characteristics of Wear resistant coatings	Alteration of environment	Susceptibility tests for intergranular corrosion Stress

S-9	SLO-1	Carbonitriding	Non-aqueous	Physical vapor deposition	surface treatments on Gears	Corrosion test
	SLO-2	Aluminising	Electroless deposition	Chemical vapor deposition	Corrosion inhibitors	Testing wear resistance practical diagnosis of wear

Learning Resources	1. George Dieter "Mechanical Metallurgy", McGraw Hill Education; 2012	5. G.W.Stachowiak & A.W. Batchelor, "Engineering Tribology", Butterworth-Heinemann, UK, 2005
	2. Rabinowicz.E, "Friction and Wear of materials", Second Edition: John Wiley & Sons, UK, 2013.	
	3. DeGarmo's "Materials and Processes in Manufacturing" J.T. Black, Ronald A. Kohser, Wiley, 2011.	6. Stand Grainger engineering coatings – design and application jaico publishing House, 1994.
	4. S.K.Basu, S.N.Sengupta & B.B.Ahuja, "Fundamentals of Tribology", Prentice –Hall of India Pvt Ltd, New Delhi, 2005	7. Parthasarathy. N.V., Electroplating Handbooks, Prentice Hall, 1992

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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Course Code	18AUE324T	Course Name	AGILE MANUFACTURING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																	
CLR-1 :	Understand the manufacturing system and operation in terms of economic and technology.				Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLR-2 :	Learn the manufacturing categories, material handling and manufacturing product																								
CLR-3 :	Expertise in industrial automation levels and its functional requirement																								
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																							
CLO-1 :	Identify the lean manufacturing tools and their potential applications.				1	85	80	H	H	L	M	L	L	L	L	L	Ethics	L	H	L	M	H	H	M	H
CLO-2 :	Summarize the usage of visual management, TPM and lean practices				2	80	75	H	H	M	H	M	M	M	M	M	M	H	L	H	H	H	L	H	
CLO-3 :	Compare the technology drivers of agile manufacturing				2	85	80	H	M	H	M	H	H	M	H	M	H	H	L	H	H	H	M	M	
CLO-4 :	Demonstrate the lean manufacturing principles to find and eliminate wastes				2	90	85	H	H	M	H	H	L	L	M	H	L	M	H	L	H	H	H	L	
CLO-5 :	Explain the technology drivers of agile manufacturing				2	85	80	H	H	H	H	H	M	L	M	H	L	M	H	L	H	H	H	M	

	Introduction to Manufacturing Operations	Manufacturing System	Supply Chain Management, Production Planning & Control System	Lean Production : JIT, Value Added & Waste Elimination	Agile Manufacturing
Duration (hour)	09	09	09	09	09
S-1	SLO-1	Introduction to Manufacturing Operations	Manufacturing System- Definition	Supply Chain Management	Agile Manufacturing
	SLO-2	Definition of Manufacturing	Material Handling- Definition	Importance of supply chain-Definition	Introduction-Definition-Organize to master change
S-2	SLO-1	Alternate Definition of Manufacturing system as Technological	Human Resource Manufacturing system in large production system	competitive industrial revolution	leverage the impact of People & information
	SLO-2	Economic Process Comments - Remarks	Components of a manufacturing system	Relying on Suppliers-downside and upside	cooperate to enhance competitiveness-enrich the customers
S-3	SLO-1	Manufacturing Industries & Products Manufacturing Categories –Primary – Secondary – Territory	Various components- Production machines	Supply chain management-Physical supply chain	flexible production line, continuous improvement
	SLO-2	Continuous & Batch Production – Discrete manufacturing industry. Manufacturing Products – Materials, Typical Product	Tools, fixtures & material handling system	management philosophy	Definitions, Functions, & Principles.
S-4	SLO-1	Manufacturing Operation-Processing & Assembly operations-Material handling	Computer systems to coordinate the manufacturing system	Purchasing-changing roles	Smart inventory waste minimization
	SLO-2	Inspection & testing-Coordination & testing-Process, Objective, Working & Stages of operations	Human Workers	requirement specifications	JIT- Concept
S-5	SLO-1	Product & Production Relationship	Classification of Manufacturing systems	suppliers, assessment, selection & contracting	waste of over production
	SLO-2	Production quantity & product variety	Factors – Types of operation performed	managing supplier relationship	waste of waiting

S-6	SLO-1	Complexity of assembled products- Complexity of individual parts	number of work stations & layout	Material Requirement Planning (MRP) inputs to MRP, Bill of materials,	waste of transportation, waste of processing	Reorganizing the production system for agility-marketing
	SLO-2	Operations, functions, capabilities, limitation & examples	level of automation- product variety.	Product Structure, working- Examples, output & benefits of MRP	waste of motion	Reorganizing the production system for agility production operation
S-7	SLO-1	Production Concept & Mathematical Models- Production rate	Overview of Classification of manufacturing systems	Capacity Planning	waste of making defective parts	Agility versus Mass production
	SLO-2	Production capacity-utilization & availability of facility	single station	Shop Floor Control- order release, scheduling & Progress. Data collection.	Objectives of JIT	Agility versus Mass production
S-8	SLO-1	Manufacturing Lead time-Work in Process	Multi station	Inventory Control- Order point inventory system	Ingredients of JIT	Comparison of Lean & agile production
	SLO-2	objective, Operations, Functions & examples	production lines	work in process (WIP) inventory cost	Quality & Quantity principles of JIT	Comparison of Lean & agile production
S-9	SLO-1	Costs of Manufacturing Operations-Fixed & variable cost- Definition, cost equation & application-Direct Labor- Definition, Equation, Application & Examples	Learning curves of manufacturing progress-Definition	Manufacturing Resource Planning II (MRP II)	Primary quantity JIT principles	implementation of agile manufacturing
	SLO-2	Material & overhead- Factory & cooperate.- Estimating manufacturing Cost & establishing selling price-Cost of Equipment	learning rates for typical operations	Definition, structure, working & application	JIT implementation	implementation of agile manufacturing

Learning Resources	1. Mikell P. Groover "Automation, Production System & Computer Integrated Manufacturing ", Prentice Hall; 3 edition (August 3, 2007)	3. S.R.K. Prasad, R. Prabhakar, S. Dhandapani, V. Selladurai " Intelligent Flexible Autonomous Manufacturing Systems", TATA McGraw- Hill Publishing Company Limited, 2010
	2. John M. Nicholas "Competitive Manufacturing Management" 9th Edition, TATA McGraw Hill editions	4. M. P. Chowdiah, Gopinath Gargesa, V. Arun Kumar, "Agile Manufacturing", TATA McGraw- Hill Publishing Company Limited, 2006

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Evaluate Create	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr K Venkateswaran, Bimetal Bearings Limited, drvenki@bimite.co.in	1. Dr.R.Elansezhian, Pondicherry Engineering College, elansezhianr@gmail.com	1. Dr. R.Rajendran, SRMIST, rajendrr@srmist.edu.in
2. Dr.G.Saravanan Caterpillar, gsaravanan@cat.com	2. Mr. N.Ravikumar, Crescent Institute of Science and Technology, ravikumar@crescent.education	2.Mr. S.Madhan Kumar, SRMIST, madhanks@srmist.edu.in

Course Code	18AUE325T	Course Name	MANUFACTURING SYSTEMS AND SIMULATION	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18AUC201J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1:	Provide an insight into how simulation modelling can aid in effective decision-making.	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2:	Create Simulation model building aspects of discrete systems (such as Queuing, Inventory and manufacturing) in detail.	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3:	Demonstrate how computer simulation can be used to successfully model, analyze and improve systems under study.	Expected Proficiency (%)	Problem Analysis
CLR-4:	Perform the statistical analysis of simulation model output.	Expected Attainment (%)	Design & Development
CLR-5:	Selection of the appropriate simulation software for the different cases.		Analysis, Design, Research
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		Modern Tool Usage
CLO-1:	Learn the basic concepts of simulation.	1,2 90 85	Society & Culture
CLO-2:	Develop and analyze complex models for industrial engineering problems using commercially available discrete event simulation software	2 90 80	Environment & Sustainability
CLO-3:	Interpret simulation output using valid statistical methods and make appropriate recommendations.	2 90 80	Ethics
CLO-4:	Analyze data to determine appropriate input distributions using valid statistical methods.	2 90 80	Individual & Team Work
CLO-5:	Apply the simulation software for various manufacturing system/process	2 90 80	Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3

		Introduction to Manufacturing Systems	Manufacturing System Modeling and Simulation	Random Number Generation	Evaluation of Simulation Experiments	Simulation software and Examples
Duration (hour)		9	9	9	9	9
S-1	SLO-1	Basic concepts and problems concerning systems	Basic concepts of probability-	Properties of random numbers	Input modeling, Data collection	Programming for discrete event system simulation in GPSS-
	SLO-2	Components of Manufacturing systems	Discrete versus Continuous Variables		Histograms, Selecting the family distribution,	
S-2	SLO-1	Systems design: Decision making procedures	Probability distribution for discrete variables	Techniques for generating random numbers- Linear Congruential Method	Selecting input distributions with data	GPSS- Single Server Queue simulation
	SLO-2	Classifications of Manufacturing systems	Probability distribution for continuous variables		Quantile-Quantile plots	
S-3	SLO-1	Structural, Transformational and procedural aspects of manufacturing	Binominal Distribution- to test hypothesis	Techniques for generating random numbers- Combined Linear Congruential Generator.	Parameter estimation- sample mean and sample variance	Simulation of Production systems- Models of Material Handling system.
	SLO-2				Suggested estimators	
S-4	SLO-1	Modes of production- Batch Production, Cellular, Flexible Manufacturing.	Statistical Models- Queueing Systems, Inventory and Supply chain system	Techniques for generating random numbers- Random- Number streams	Goodness-of-fit tests	Simulation of Production systems- Models of Material Handling Equipment.
	SLO-2		Reliability and Maintainability		Chi-square test	
S-5	SLO-1	Process systems for manufacturing	Spread Sheet simulations	Tests for random numbers- Frequency Test.	Chi-square test with equal probabilities	Queueing Systems- Characteristics
	SLO-2				Kolmogorov-smirnov goodness of fit test	
S-6	SLO-1	Logistic systems- Product-Production Relationship	Queueing simulation in a spread sheet	Tests for random numbers- Test for Autocorrelation.	p-value and best fits	
	SLO-2		Waiting line models		Selecting input models without data	Queueing Systems- Notations
S-7	SLO-1	Material flow & technological information flow	Simulating a single server queue	Direct transformation for acceptance and rejection techniques- Poisson Distribution	Multivariate and time series input models	Project networks
	SLO-2		Simulating a queue with two servers	Nonstationary Poisson process & Gamma Distribution.	Covariance and correlation	

S-8	SLO-1	Management and information systems for manufacturing	Discrete and Continuous Systems	Inverse Transform Techniques- Exponential Distribution, Uniform Distribution	Time-series input models	Maintenance and replacement systems
	SLO-2		Discrete- Event system simulation	Inverse Transform Techniques- Weibull Distribution, Triangular Distribution		
S-9	SLO-1	Managerial information flow in manufacturing systems	Concepts in Discrete- Event system simulation	Inverse Transform Techniques- Emphatical continuous distributions.	experimental layout and validation	Investment Analysis
	SLO-2			Inverse Transform Techniques- Discrete distribution.		

Learning Resources	1. Jerry Banks and John S Carson, Barry L Nelson, David M Nicol, 'Discrete event system simulation', 5 th edition Pearson Education, 2017, ISBN 13: 9789332518759. 2. David Bedworth & James Bailey, Integrated production control system management, analysis & design, 2nd ed., John Wiley & Sons Ltd, 1987, ISBN 13: 9780471821793	3. Carrle A, "Simulation of Manufacturing Systems", John Wiley and Sons Inc., New York, 2007, ISBN 13: 9780471915744 4. Gordon G, "Systems Simulation", Pearson Education, 2002. ISBN 13: 9788120301405 5. Narsingh Deo, "System Simulation with Digital Computer", Prentice Hall of India, New Delhi, 2001. ISBN 13: 9780138817893
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	60%		50%		40%		15%		50%	
	Understand										
Level 2	Apply	40%		50%		60%		20%		50%	
	Analyze										
Level 3	Evaluate	-		-		-		15%		-	
	Create										
	Total	100 %		100 %		100 %		100 %		100%	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. . Mr.N.Vijayakumar, Head Test labs, Mahindra and Mahindra, vijayakumar.n@mahindra.com.	1. Dr. A.Siddharthan, Madras Institute of Technology, sidharth@mitindia.edu	1.Dr.J.Chandradass, SRMIST, chandraj@srmist.edu.in
2. Mr.S. Senthil Kumar, Deputy Manager, Renault Nissan Technology & Business Centre India, senthilkumar.subramanian@mtbci.com	2. Dr. S. Renold Elsen, Vellore Institute of Technology, renoldelsen.s@vit.ac.in	2. Mr.M.Jerome Stantley, SRMIST, jeromesm@srmist.edu.in

Course Code	18AUE421T	Course Name	ADVANCED MANUFACTURING PROCESS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18AUC201J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Acquire knowledge of various advanced manufacturing processes used in industries				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Understand the various manufacturing process of composite, plastics and glass.				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Acquaint students with the concept of Additive Manufacturing (AM), various AM technologies, selection of materials for AM, modeling of AM processes, and their applications in various fields																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	Identify the advanced metal forming process and its current role in the industries.				1	85	75	H	M	M	M	H	M	M	M	M	M	L	M	H	H	H
CLO-2 :	Choose the manufacturing process for the fabrication of composite, plastics and glass depending on the applications.				3	80	75	H	M	M	H	M	M	M	M	M	M	L	M	H	H	H
CLO-3 :	Integrate microelectronic device for Automotive application				3	85	80	H	M	H	M	M	M	M	M	M	L	M	L	H	H	H
CLO-4 :	List the low temperature joining and surface treatment process.				1	85	80	H	M	M	M	H	M	H	H	M	H	L	L	H	H	H
CLO-5 :	Select economically viable manufacturing process of highly complex parts alternative to conventional manufacturing technologies				3	80	75	H	M	H	M	L	L	L	M	M	L	M	M	H	H	H

		Advanced Metal Forming Process	Composites, Plastics & Glass: Forming, Shaping & Equipment	Fabrication of Microelectronic Devices	Low Temperature Joining Process & Surface Technology	Additive Manufacturing
Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction – why do we need advanced manufacturing process?	Introduction to Composites	Role of Electronics in Industrial Revolution.	Introduction to joining process	Introduction to additive manufacturing.
	SLO-2	Introduction to powder metallurgy technique.	Composites properties and structures.	Integration of Electronics in Automotive Industry.	Brazing & Soldering methods- torch, furnace, induction, resistance, dip, infrared and applications.	Importance of Rapid prototyping.
S-2	SLO-1	Need and role of powder metallurgy in Automotive industry.	Processing of Polymer Matrix composites- Compression molding, injection molding , hand lay-up method , filament winding	Semiconductors & Silicon- Structure, Physical Properties.	Adhesion bonding – types of adhesives and adhesives system – Applications	RPT – classification based on materials, Advantages
	SLO-2	Powder Metallurgy Applications – Automotive parts and components.	Processing of Metal Matrix composites. Stir casting process , squeeze casting process/ infiltration , diffusion bonding, powder metallurgy	Semiconductors – working and types.	Joining of Plastics	Liquid based techniques-overview
S-3	SLO-1	Production and properties of metal powders.	Processing of Ceramic Matrix Composites Chemical vapor infiltration, Sol-gel Process	Semiconductors – advantages.	Joining of ceramics Joining of glass.	Stereo lithography.
	SLO-2	Particle size, distribution and shape of metal powders.	Composites in Automotive applications.	Wafer Formation & preparation	Surface Treatment- need, surface structure.	Solid Ground Curing technique.
S-4	SLO-1	Blending of metal powders and purpose.	Shaping of plastics	Single Crystal growing Techniques.	Mechanical surface treatment – shot peening, laser shot peening	Multi Jet Modeling,
	SLO-2	Hazards in Blending, Compaction of Metal powders.	Injection Molding process.	Slicing of wafers Geometry of wafers.	Water jet peening,	Ballistic particle.
S-5	SLO-1	Purpose of Isotactic pressing.	Blow Molding process	Film Deposition & Oxidation techniques.	Ultrasonic peening	Shape deposition Manufacturing
	SLO-2	Hot & Cold Shaping Process.	Rotational Molding process.	Physical Vapor Deposition	surface rolling - operation	Powder based techniques-overview

S-6	SLO-1	Metal injection molding, Spray Deposition.	Thermoforming process.	Chemical Vapor Deposition	explosive hardening - operation	Selective laser sintering.
	SLO-2	Sintering – process, Coining, Forging.	Compression molding process	Photolithography – Principle and Process.	Cladding - process & working	Laser engineered net shaping.
S-7	SLO-1	Mechanism and Properties of Sintered Parts Secondary & Finishing Operations.	Transfer Molding process.	Photolithography - Types & working	Case hardening - process & working	3D printing – introduction
	SLO-2	Heat treating, Impregnation, Infiltration & Plating.	Economics of Processing Plastics & Composites.	Etching – Need, Types, Principle.	Hard facing - objective, process & working.	3D printing- working and application
S-8	SLO-1	Dent Resistance of Sheet metals – dent formation & automotive application.	Forming & shaping of Glass- piece ware glass-spinning , pressing , press and blow , blow & blow and casting	Etching - Process & Working	Spark hardening - objective, process & working	Solid based technique-overview
	SLO-2	Fabrication of Honey Comb Structure for Catalytic Convertor.	Flat and tubular glass- float process , rolling of flat plate , Danner process	Diffusion- Principle, Process & Working	Thermal spraying – need, materials	Fused Deposition Modeling
S-9	SLO-1	Super plastic Forming – Super plasticity process, advantages and Properties.	Forming of glass fiber- centrifugal spraying, drawing	Ion Implantation - Principle, Process & Working	Thermal spraying – types	Paper Lamination Technology
	SLO-2	Diffusion bonding – process – advantages.	Strengthening Techniques for Glass	A brief outline of Wire Bonding, Packaging, Yield, Reliability	Thermal spraying –process- combustion , electrical and cold spraying	Laminated object modeling – process

Learning Resources	1. Serop Kalpakjian, "Manufacturing Engineering and Technology", 6th Edition, Addison-Wesley Publishing Co., Boston, 2014. 2. Mikell P. Groover "Fundamentals of Modern Manufacturing", 4th Edition, John Wiley & Sons Inc, 2015.	3. Helmi A Youssef, Hassan E El-Holhy, Mahmoud H Ahmed, "Manufacturing Technology", CRC Press. 2010
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
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2. Mr.S. Senthil Kumar, Deputy Manager, Renault Nissan Technology & Business Centre India, senthilkumar.subramanian@rntbci.com	2. Dr.P.Jawahar, Assistant Professor, NIT Agartala, drjawahar.me@nita.ac.in	2. Mr.S.Palanisamy,SRMIST, palaniss@srmist.edu.in

Course Code	18AUE422T	Course Name	COMPUTER INTEGRATED MANUFACTURING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1:	Develop capability in students to understand and use CIM in fabrication industry	1	1
CLR-2:	Prepare planning and scheduling of process equipment fabrication using various CAPP	2	2
CLR-3:	Demonstrate and use automated assembly lines, FMS and Industrial Robots	3	3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Engineering Knowledge
CLO-1:	Discuss the basic components of CIM.	1	H
CLO-2:	Enable knowledge in CAPP and MRP.	2	H
CLO-3:	Explain about Group Technology and Cellular Manufacturing	2	H
CLO-4:	Equip themselves familiar with FMS and AGVs	2	H
CLO-5:	Exposed to the concept of Industrial Robots	2	H

	Introduction to CIM	Production Planning And Control And Computerised Process Planning	Cellular Manufacturing Group Technology(Gt)	Flexible Manufacturing System(Fms) And Automated Guided Vehicle System (Agvs)	Industrial Robotics
Duration (hour)	9	9	9	9	9
S-1	SLO-1 Brief introduction to CAD and CAM	Process planning – Computer Aided Process Planning (CAPP)	Part families	Types of Flexibility	Robot Anatomy
	SLO-2 Manufacturing Planning, Manufacturing control				Related Attributes
S-2	SLO-1 Concurrent Engineering	Retrieval Computer Aided Process Planning	Parts Classification	Flexible Manufacturing System	Classification of Robots
	SLO-2 CIM concepts	Generative Computer Aided Process Planning	Parts coding	FMS Components	Robot Control systems
S-3	SLO-1 Computerized elements of CIM system	Aggregate Production Planning	Opitz Part Coding system	FMS Application	End Effectors
	SLO-2 Types of production	Aggregate Plan Strategies	Form Code in Opitz Part Coding system	FMS Benefits	Sensors in Robotics
S-4	SLO-1 Manufacturing models and Metrics	Master Production Schedule	Model problems I	FMS Planning	Industrial Robot Applications
	SLO-2 Mathematical models of Production Performance	Main Functions of Master Production Scheduling	Model problems II	FMS Control	Material Handling Applications
S-5	SLO-1 Model problems I	Material Requirement planning	Production flow Analysis	Quantitative analysis in FMS	Process Operations
	SLO-2 Model problems II	Demand driven MRP	Cellular Manufacturing	Bottleneck model	Assembly and Inspection
S-6	SLO-1 Marketing engineering	Capacity Planning	Composite part concept	Model problems I	Robot Programming
	SLO-2 Problems I	Control Systems	Individual features of Composite part concept	Model problems II	Leadthrough Programming
S-7	SLO-1 Problems II	Shop Floor Control	Machine cell design	Automated Guided Vehicle System	Motion Programming languages
	SLO-2 Basic Elements of an Automated system	Inventory Control	Machine cell layout	AGV System management	Robot Programming languages
S-8	SLO-1 Levels of Automation	Introduction on Manufacturing Resource Planning-II (MRP-II)	Quantitative analysis in Cellular Manufacturing	AGVS Application	Simulation and Off line programming
	SLO-2 Five Levels of Automation	Enterprise Resource Planning (ERP)	Rank Order Clustering Method	Vehicle Guidance technology	Robot Accuracy
S-9	SLO-1 Lean Production	Problems I	Arranging Machines in a GT cell	Vehicle Guidance technology benefits	Repeatability
	SLO-2 Just-In-Time Production	Problems II	Applications of GT	Vehicle Management & Safety	Problems

Learning Resources	1. Mikell.P.Groover "Automation, Production Systems and computer integrated manufacturing", 4 th edition Pearson Education 2016. 2. Kant Vajpayee. S., 'Principles of Computer Integrated Manufacturing', Prentice Hall of India, 2009	4. Roger Hanman "Computer Intergrated Manufacturing", Addison – Wesley, 1997 5. Mikell.P.Groover and Emory Zimmers Jr., "CAD/CAM", Prentice Hall of India Pvt. Ltd., New Delhi-1, 2008
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Silambarasan Ramadoss, Renault Nissan Technology & Business Centre India, silambarasan.ramadoss@rntbci.com	1. Dr. A.Siddharthan, Madras Institute of Technology, sidharth@mitindia.edu	1.Dr.J.Chandradass,SRMIST, chandraj@srmist.edu.in
2. Mr. Prasad Arun Kumar, Mahindra Research Valley, prasad.arunkumar@mahindra.com	2. Dr. S. Renold Elsen, Vellore Institute of Technology, renoldelsen.s@vit.ac.in	2.Mr.S.MadhanKumar,SRMIST, madhanks@srmist.edu.in

Course Code	18AUE423T	Course Name	PROCESS PLANNING AND COST ESTIMATION	Course Category	E	Professional Core	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Impart basic knowledge about process planning and cost estimation	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Retrieve the basic idea to estimate different cost	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Acquaint knowledge to estimate machining time and cost																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Interpreting knowledge about work study and ergonomics.	1	85	80	M	L	L	M	M	M	M	M	M	M	H	M	H	M	H
CLO-2 :	Execute the process planning concepts	1	85	80	M	M	M	M	H	M	M	M	M	M	H	M	H	M	H
CLO-3 :	Predict various cost estimation	2	85	80	M	M	M	M	H	M	M	M	M	M	H	M	H	M	H
CLO-4 :	Calculate the production cost	2	80	75	M	M	H	M	H	M	M	M	M	M	H	M	H	M	H
CLO-5 :	Solve machining time and cost	3	80	75	M	M	H	M	H	M	M	M	M	M	H	M	H	M	H

	Work Study and Ergonomics	Introduction to Process Planning	Cost Estimation	Production Cost Estimation	Estimation of Machining Times & Cost
Duration (hour)	9	9	9	9	9
S-1	SLO-1 SLO-2	Objectives- Work study, Method study	Introduction to manufacturing system- Fundamental Concept and Basic Manufacturing process	Objectives of cost estimation Types of cost estimation	Estimation of material cost Machine shop operations-Lathe, Drilling
S-2	SLO-1 SLO-2	Basic Procedure for Method Study (Select, Record, Examine, Develop, Define, Install and Maintain)	Process planning-Basic concepts, Process selection and analysis	Fundamentals of costing and cost accounting methods,	Estimation of labor cost Machine shop operations- Milling and Grinding
S-3	SLO-1 SLO-2	Recording Techniques used in Method Study	Details of process plan, process charts and route sheets	Components of a Cost Estimate	Estimation of Overhead cost Estimation of machining time for basic lathe operation-Turning and Facing
S-4	SLO-1 SLO-2	Work Measurements, Objectives of work Measurements	Process planning methods- manual and computer aided process planning & its approaches	Classification of Costing	Foundry basics, Methods of casting, Casting tools and accessories Estimation of machining time for Threading and Chamfering
S-5	SLO-1 SLO-2	Work Sampling, Analytical Estimating	Manual process planning-Basic procedure, merits & demerits, applications and comparisons	Elements of Cost, Cost of Product	Cost estimation in foundry shop- pattern cost, casting cost Estimation of machining time for drilling-sample problems
S-6	SLO-1 SLO-2	Ergonomics	Case study-Preparation of manual process plan for four stroke petrol engine assembly	Methods of Cost Estimates	Welding, Types of weld joints, Gas welding Estimation of machining time for boring operations-sample problems
S-7	SLO-1 SLO-2	Ergonomics Principles Applied to Instrument Design and Control	Computer aided process planning-Types, Basic procedure, merits, demerits and applications	Data Requirements and Sources of information	Estimation of Gas welding cost, Gas cutting Estimation of machining time for milling operation-Sample problems
S-8	SLO-1 SLO-2	Ergonomics Principles Applied to Machines and Controls	Process analysis-Break even analysis & It's objectives	Types of Cost Estimates, Allowances in Estimation (of Standard Time)	Arc welding: Equipments, Cost Estimation Estimation of machining time for Grinding operation-sample problems
S-9	SLO-1 SLO-2	Ergonomics Principles Applied to Layout of a Work place	Statistical process control-Process capability analysis using process control charts	Cost Estimation Procedure	Cost estimation in Welding shop Case studies: Estimation of cost for a product

Learning Resources	1. Chitale, A.K., and Gupta, R.C., "Product Design and Manufacturing", Prentice Hall of India, New Delhi, 2011. 2. Adithan, M., "Process planning and cost estimation", New Age International(P) Limited, 2011	3. Nanua Singh, "System Approach to computer Integrated Design and manufacturing", John Wiley & Sons, New York, 1996. 4. Sinha, B.P., "Mechanical Estimation and Costing", Tata McGraw-Hill, Publishing Co., 1995 5. Narang, G.B.S. and Kumar. "Production and planning", Khana Publishers, New Delhi, 1995.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
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2.Mr. Prasad Arun Kumar, Mahindra Research Valley, prasad.arunkumar@mahindra.com	2. Dr. S. Renold Elsen, Vellore Institute of Technology, renoldelsen.s@vit.ac.in	2. Mr. M.Palanivendhan, SRMIST, palanivm@srmist.edu.in

Course Code	18AUE424T	Course Name	AUTOMOTIVE QUALITY SYSTEMS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Impart the knowledge of quality concepts and quality management systems	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2 :	Implement the knowledge of tool and techniques in automotive industries.	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3		
CLR-3 :	Integrate the idea to work with professional cost accountants to obtain realistic cost estimates																				
CLR-4 :	Collaborate on international quality systems and modern management systems for quality.																				
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																				
CLO-1 :	Relate the quality concepts and quality production	1	80	75	M	M	M	M	M	H	M	H	M	H	H	H	M	H	H		
CLO-2 :	Explain quality Management system and different dimensions of quality	2	85	80	M	H	L	H	M	H	M	H	M	H	H	H	M	H	H		
CLO-3 :	Implement the application of management tools and techniques for process improvement	2	85	80	M	H	H	L	H	H	M	H	M	H	H	H	M	H	H		
CLO-4 :	Assess Automotive TS16949 quality system practices	3	85	80	M	H	H	H	H	M	H	M	H	H	H	H	M	H	H		
CLO-5 :	Validate various system analysis measurement and data collection	3	90	85	M	H	H	H	H	H	M	H	M	H	H	H	M	H	H		

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Basic Concepts of Quality. Quality, classification of quality and services	Quality Management Systems-Introduction	Modern Management Tools and Techniques	ISO TS16949 Scope, application and quality management system	Quality Tools and Measurement Systems Analysis
	SLO-2					
S-2	SLO-1	Quality systems overview	Quality Management – A conceptual Frame Work	Introduction to Modern Management Techniques	Requirements of quality management system	Concepts of SPC detection vs. prevention
	SLO-2					
S-3	SLO-1	Product Quality design	Dimensions of Quality	5s concepts	Advanced Product Quality Planning (APQP)-Focus and benefits	Data collection methods
	SLO-2					
S-4	SLO-1	Quality engineering in design of production processes	Costs of Quality	Kaizen techniques	Advanced Product Quality Planning (APQP)- Different Phases	Statistical Tools
	SLO-2					
S-5	SLO-1	Quality characteristics	Quality System Standards	Six sigma methodologies	Design of Failure Mode Effects Analysis - Types	Understanding of measurement systems
	SLO-2					
S-6	SLO-1	Reliability	ISO 9000 clauses	Quality circles	Design of Failure Mode Effects Analysis-Advantages and Limitations	Variable Gauge R&R
	SLO-2					
S-7	SLO-1	Safety	ISO 9000 interpretations	Taguchi loss function-Theory	Process Failure Mode Effects Analysis	Introduction to Hypothesis Testing
	SLO-2					
S-8	SLO-1	Quality engineering in production	ISO TS16949 clauses	Taguchi loss function-Applications	Production Part Approval Process (PPAP)	ANOVA
	SLO-2					
S-9	SLO-1	Quality engineering in service	ISO TS16949 interpretation	POKE –YOKE Techniques	Single and Multiple Regression	Correlation Analysis
	SLO-2					

Learning Resources	1. David Hoyle, "Automotive quality system Handbook", Butterworth – Heinemann Ltd, second edition, oxford, 2005 2. William M Feld, "Lean Manufacturing: Tools, Techniques and How to Use Them", APICS, 2010	3. Montgomery Douglas C, "Introduction to Statistical Quality Control", John Wiley and Sons, New Delhi, 2009. 4. Logo Thetis N, "Managing for Total Quality – From Deming to Taguchi and SPC", Prentice Hall of India Private Limited, New Delhi, 1997. 5. "Advanced product quality planning and control plan" 2 nd Edition ,Standards media (2008)
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

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2.Mr. Prasad Arun Kumar, Mahindra Research Valley, prasad.arunkumar@mahindra.com	2. Dr. S. Renold Elsen, Vellore Institute of Technology, renoldelsen.s@vit.ac.in	2. Mr.M.Palanivendhan, SRMIST, palanivm@srmist.edu.in

Course Code	18AUE425T	Course Name	INDUSTRIAL ENGINEERING AND OPERATIONAL RESEARCH	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																															
CLR-1 :	Provide an insight into the concepts of industrial engineering and organization				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15																	
CLR-2 :	Develop a diverse group of professionals and leaders in industrial engineering																																						
CLR-3 :	Enhance the scientific awareness of the society in the field of operation research.																																						
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3																	
CLO-1 :	Understand the impact of industrial engineering solutions in a global and social context			1																			85	80	H	M	L	M	L	L	L	H	L	M	L	H	M	H	
CLO-2 :	Use the knowledge and skills of industrial engineering to model and analyze problems			2																			80	75	H	H	M	H	M	M	L	M	H	L	H	H	L	M	
CLO-3 :	Investigate Effective utilization of men, equipment and space			2																			85	80	H	M	H	M	H	H	L	H	H	L	H	H	H	M	M
CLO-4 :	Ensure optimal use of resources with modern technology to create a place of higher learning in the fields of Operation Research			2																			90	85	H	H	M	H	H	L	L	M	H	L	H	H	H	M	L
CLO-5 :	Apply the PERT/CPM for a constraint based problem of service/manufacturing.			2																			85	80	H	H	M	H	H	M	L	M	H	L	H	H	H	H	M

	Industrial Engineering and Management Science	Production And Productivity	Plant Location and Layout	Work Study	Operational Research
Duration (hour)	9	9	9	9	9
S-1	SLO-1 Introduction to Industrial Engineering, Concepts	Production Concept	Factors Governing on plant location	Definition concept and need for work study	Operational Research concept and definition
S-2	SLO-1 History and Development of Industrial Engineering	Production function	Locational Economics	Method Study	Methods of Operational Research
	SLO-2 Scientific management	Production system	Rural V/S Urban plant sites	Method Study Procedure	Linear Programming
S-3	SLO-1 Roles of an Industrial Engineer	Analysis of Production system	Plant layout	Process chart symbols	Graphical method
	SLO-2 Applications of Industrial Engineer	Input output model	Principles of Plant layout	Flow process charts	Model problem in Graphical method
S-4	SLO-1 Functions of Industrial Engineering department and its organization	Productivity	Process layout	Process charts types	Transportation problem
	SLO-2 Production Management	Productivity model problem	Process layout Merits and demerits	Flow diagram	Transportation problem types
S-5	SLO-1 Production Management Versus Industrial Engineer	Factors affecting productivity	Product layout	Steps in flow diagram	Vogels approximate method
	SLO-2 Operations Management	Product design	Product layout Merits and demerits	Man type flow process chart	Model problem in Vogels approximate method
S-6	SLO-1 Management science	Increasing productivity of Resources	Combination layout	String diagram	North west corner method
	SLO-2 Historical Development	Work productivity	Fixed position layout	String diagram construction	Model problem I
S-7	SLO-1 Tools of management science	Model Problem I	Flow pattern layout	Multiple Activity chart	Cost matrix
	SLO-2 Simulation model	Model Problem II	Flow pattern layout types	Multiple Activity chart Construction	Profit matrix
S-8	SLO-1 Managerial economics	Productivity measures	Work station	Operational analysis	Profit matrix with equal supply and demand
	SLO-2 Managerial Techniques	Development of Productivity Measures	Work station design	Example Operational chart	Profit matrix with unequal supply and demand
S-9	SLO-1 Managerial Accounting	Productivity Measurement system	Model Problem I	Analysis of motion	Degeneracy
	SLO-2 Analysis and performance	Components of Productivity Measurement system	Model Problem II	Steps in motion analysis	Degeneracy Problem

Learning Resources	1. O.P. Khanna, "Industrial Engineering and management", 17th Edition, Dhanpat Rai Publishing Co Pvt Ltd, 2018. 2. Martand Telsang, "Industrial Engineering and Production management", 2nd edition, S. Chand publisher, 2014.	3. Hamdy A Taha , "Operations Research : An Introduction" 10th Edition, Pearson, 2016.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.N.Vijayakumar, Head Test labs, Mahindra and Mahindra, vijayakumar.n@mahindra.com.	1. Prof. M.Balasubramanian, Professor, IIT Madras, mbala@iitm.ac.in	1.Dr.J.Chandradass, SRMIST, chandraj@srmist.edu.in
2. Mr.S. Senthil Kumar, Deputy Manager, Renault Nissan Technology & Business Centre India, senthilkumar.subramanian@mtbci.com	2. Dr.P.Jawahar, Assistant Professor, NIT Agartala, drjawahar.me@nita.ac.in	2.Mr.S.MadhanKumar,SRMIST, madhanks@srmist.edu.in

Course Code	18AUE331T	Course Name	HEAT VENTILATION AND AIR CONDITIONING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18AUC203T	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Describe the working of Refrigeration system	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Interpret the knowledge on Psychrometry process	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Understand the refrigerant properties																		
CLR-4 :	Illustrate the Load calculation																		
CLR-5 :	Understand the function of air distribution system																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Select the various Refrigeration system	3	90	85	H	M	H	M	L	L	H	M	M	M	L	M	M	M	L
CLO-2 :	Identify the thermal condition of Psychrometry process	1	80	75	H	M	M	M	M	L	M	L	M	M	L	M	M	M	H
CLO-3 :	Distinguish the refrigerant properties	2	85	80	H	M	M	M	M	M	L	M	M	M	M	M	H	M	H
CLO-4 :	Perform the Load calculation	2	85	80	H	H	M	H	M	L	L	L	M	M	L	M	M	M	M
CLO-5 :	Analyze and select the air distribution system	1	90	85	H	M	M	M	M	H	H	H	M	M	L	M	M	M	H

	Air Conditioning Fundamentals		Psychrometry		Refrigerant		Fans and Air Distribution		Load Calculation and Applied Psychrometrics	
Duration (hour)	09		09		09		09		09	
S-1	SLO-1	Introduction to Air Conditioning System	Mixing Process		Working of Refrigerant in refrigeration system		Fan Characteristics		Preliminary Considerations	
	SLO-2	Location of Air Conditioning system In a Car	Properties of Moist Air		Containers Handling Refrigerants		Centrifugal Fans		Internal Heat gains	
S-2	SLO-1	Schematic layout of Refrigeration System	Dalton's Law of Partial Pressure		Desirable Properties Of Refrigerant		Axial Fans		Occupancy Load	
	SLO-2	Mode of heat transfer	Psychrometric Properties		Selection of Refrigerants		Fan Arrangements		Lighting Load	
S-3	SLO-1	Refrigeration cycle	Dry Bulb Temperature		Thermodynamic Requirements		Fan in Series		Appliances Load	
	SLO-2	Terminologies In HVAC: TR, COP	Wet Bulb Temperature		Freezing Point		Fan in parallel		Product Load	
S-4	SLO-1	EER, SEER	Specific Humidity		Critical Temperature and Pressure		Types of Ducts		System Heat Gains	
	SLO-2	Heat Exchanger And Its Types	Dew Point Temperature		Chemical Requirements		Air Flow Through Simple Duct System		Supply air duct heat gain and Leakage loss	
S-5	SLO-1	Direct-Contact Heat Exchangers	Relative Humidity		Flammability		Duct Fittings		Heat gain from Air Conditioning fan	
	SLO-2	Storage Type Exchangers	Psychrometric Processes		Toxicity		Friction Loss In Duct		Return air duct heat and Leakage gain	
S-6	SLO-1	Tubular Heat Exchangers	Sensible cooling		Action of Refrigerant with water		Dynamic Loss In Ducts		Safety factor	
	SLO-2	Shell-and-Tube Exchangers	Sensible heating		Action of Refrigerant with oil		Dampers		Cooling Load Estimate	
S-7	SLO-1	Double-Pipe Heat Exchangers	Humidifying		Binary Mixtures		Indoor Air Distribution		Room Sensible Heat	
	SLO-2	Spiral Tube Heat Exchangers	Dehumidifying		Classification of Refrigerant Mixtures		Static And Velocity Pressures		Room Latent Heat	
S-8	SLO-1	Air Conditioning Components	Heating and Humidifying		Lubricant in Refrigeration system		Fixed Velocity Method		Grand total load on Air conditioning system	
	SLO-2	Compressor	Cooling and Dehumidifying		Tapping Into The Refrigerant Container		Equal Friction Method		Heat Balance Method	
S-9	SLO-1	Condenser	Cooling and Humidifying		Ambient Conditions Affecting System Pressures		Static Regain Method		Heat Load Calculation	
	SLO-2	Evaporator Expansion Valve	Heating and Dehumidifying		Secondary Refrigerant		Static Pressure Calculation		Tutorials	

Learning Resources	1. C. P. Arora "Refrigeration and Air conditioning" – McGraw Hill Education (India) Private Limited, New Delhi, 2010 2. Roy J. Dossat, "Principles of Refrigeration", 4th edition, Pearson Education Asia, 2009 3. William H. Crouse and Donald I. Anglin - "Automotive Air conditioning" - McGraw Hill, 2000	4. Paul Weiser - "Automotive Air Conditioning" - Reston Publishing Co., Inc., - 1990 5. MacDonald, K.I., "Automotive Air Conditioning" - Theodore Audel series - 1978
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr D Rajasekaran, Freeze India Manufacturing Pvt Limited, rajakd@fim.com	1. Dr A Baskaran, P. A. College of Engineering and Technology, boss120367@gmail.com	1., Dr. S. Thiyagarajan, SRMIST
2. Mr S Ashok, ETA, ashoks@eta-engg.com	2. Dr G Venkatesan, Pondicherry Engineering College, rvenkirm@pec.com	2. Mr. S. Logeshwaran, SRMIST

Course Code	18AUE332T	Course Name	ENGINE TESTING AND VALIDATION	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18AUC301J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)																
CLR-1:	Analyze the various engine operating parameters	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2:	Employ various instruments for measuring engine parameters	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3		
CLR-3:	Evaluate the working principle of measuring instruments																				
CLR-4:	Create insight on the fundamental considerations for engine test facility																				
CLR-5:	Analyze the data acquired from the engine																				
CLR-6:	Validate the data acquired from the engine																				
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																				
CLO-1:	Evaluate the performance parameters in IC engines	2	80	75	H	M	M	M	H	M	M	M	H	H	M	M	H	M	L		
CLO-2:	Measure the various engine operating parameters of I.C engine	2	85	80	H	M	M	M	M	L	M	L	M	M	M	M	H	M	L		
CLO-3:	Apply the knowledge of basic principle of measuring instruments	1	80	75	H	M	H	M	L	L	M	M	M	M	L	L	H	M	L		
CLO-4:	Develop an engine test rig with necessary instrumentation	1	80	75	M	H	M	H	M	M	M	M	H	H	M	M	H	M	L		
CLO-5:	Analyze and validate various engine test results	2	85	80	H	M	M	M	M	M	M	M	H	M	M	M	H	M	M		

Duration (hour)		Performance Parameters	Measurements	Instrumentation	Test facility layout	Data analysis
		9	9	9	9	9
S-1	SLO-1	Engine performance parameters - Introduction	Indicated power measurement	Instrumentation and data acquisition - Introduction	Test facility layout considerations-fundamentals	Validation of data and test results - Introduction
	SLO-2	Engine performance parameters - Explanation	Frictional power measurement	Pressure measurement	Test cell - thermodynamic system	General principles for data validation in engine testing
S-2	SLO-1	Brake power - Calculation	Tutorial session	The Hall-effect sensor	Basics of test cell and control room design	Error types
	SLO-2	Torque Output - Calculation	Tutorial session	Shielded-field sensor	Ventilation and air conditioning	Error Sources
S-3	SLO-1	Tutorial session	Brake power measurements	Crankshaft position sensor	Vibration control	Combination of errors
	SLO-2	Tutorial session	Torque and speed measurements	Types	Test cell noise control	Experiment repeatability
S-4	SLO-1	Mean effective pressure - Calculation	Dynamometer - Introduction	Throttle position sensor	Cooling circuit requirements	Instrument sensitivity
	SLO-2	Mechanical efficiency Calculation	Mechanical Dynamometer	Temperature sensors	Installation	Experimental precision
S-5	SLO-1	Tutorial session	Electrical Dynamometer	Coolant sensors	Exhaust gas system	Absolute and relative accuracy
	SLO-2	Tutorial session	Eddy Current Dynamometer	Sensors for Feedback control	Installation	Traceability
S-6	SLO-1	Volumetric efficiency and Fuel-air ratio calculation	Measurement of speed	Exhaust gas oxygen sensor	Electrical system considerations	Uncertainty- calibration –definition, importance
	SLO-2	Specific fuel consumption calculation	Fuel consumption measurement	EGO characteristics	Layout	Calibration - definition
S-7	SLO-1	Tutorial session	Air consumption measurement	Switching characteristics	Fuel storage requirements	Calibration - importance
	SLO-2	Tutorial session	Smoke and particulate measurement	Knock sensor	Fuel supply requirements	Calibration techniques for pressure
S-8	SLO-1	Heat Balance - Calculation	Measurement of exhaust emissions – HC, CO, NOx and CO ₂	Pressure sensor	Fuel treatment systems	Calibration techniques for temperature
	SLO-2	Brake thermal efficiency - calculation	Tutorial session	Data Acquisition, Data collection and control systems (EDACS)	Input parameters for engine testing	Gaussian distribution as a statistical tool
S-9	SLO-1	Tutorial session	Tutorial session	Post processing of data	Maintenance of engine test facility	Error analysis
	SLO-2	Tutorial session	Tutorial session	Tutorial session	Troubleshooting of engine instruments	Tutorial session

Learning Resources	1. A.J.Martyr, M.A. Plint, <i>Engine Testing and Theory and Practice</i> , 3rd edition, -SAE International, 2007	3. Jyotindra S. Killedar, <i>Dynamometer: Theory and application to engine testing</i> , Xlibris Corporation LLC, 2012
	2. Dietrich, C.F. "Uncertainty, Calibration and Probability", Adam Hilger, London. 1973	4. A.J.Martyr, M.A. Plint, <i>Engine testing: The design, building, modification and use of powertrain test facilities</i> , 4th edition, - Elsevier, 2012

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Shanmuga Sundaram, Renault Nissan, sankaran@mtbci.com	1. Dr. V. Karthickeyan, Sri Krishna College of Engineering, karthickeyanv@skcet.ac.in	1. Dr. V. Edwin Geo, SRMIST
2. Mr S Ashok, ETA, ashoks@eta-engg.com	2. Dr. P. Nanthakumar, Amrita School of Engineering, p_nanthakumar@cb.amrita.edu	2. Dr. S. Thiyagarajan, SRMIST

Course Code	18AUE333T	Course Name	FUEL TESTING AND STANDARDS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18AUC301J	Co-requisite Courses	NIL	Progressive Courses	
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:		Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Learn the sources, composition and properties of automotive fuels			Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Gain knowledge on reference and commercial fuels and road map to quality improvement						Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Acquire knowledge on the significance of different fuel properties with respect to engine application						M	M	L	M	L	H	H	H	M	L	L	M	M	H	H
CLR-4 :	Understand and become familiar with BIS testing standards for gasoline and diesel						M	M	L	M	L	H	H	H	M	L	L	M	M	H	H
CLR-5 :	Conceive idea on the testing methods for LPG, CNG and biodiesels						M	M	L	M	L	H	H	H	M	L	L	M	M	H	H
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																			
CLO-1 :	Understand the sources, composition and properties of automotive fuels and significance of testing fuels			2	80	75	M	M	L	M	L	H	H	H	M	L	L	M	M	H	H
CLO-2 :	Acquire knowledge on the specification of reference fuels for testing vehicles, road map and bottle necks in quality improvement			2	80	75	M	M	L	M	L	H	H	H	M	L	L	M	M	H	H
CLO-3 :	Learn the significant fuel properties and its implication in engine application			2	80	75	M	M	L	M	L	H	H	H	M	L	L	M	M	H	H
CLO-4 :	Gain knowledge on commercial gasoline and diesel fuel testing as specified in BIS			1	80	75	M	M	L	M	L	H	H	H	M	L	L	M	M	H	H
CLO-5 :	Gain knowledge on CNG, LPG and biodiesel testing			1	80	75	M	M	L	M	L	H	H	H	M	L	L	M	M	H	H

	Automotive fuels	Reference and commercial fuels	Fuel Properties	Commercial Gasoline and Diesel fuel testing as specified in BIS	CNG, LPG and Biodiesels testing
Duration (hour)	9	9	9	9	9
S-1	SLO1 Petroleum - sources and composition	Technical specification of fuels - significance	Properties of different fuels-Volatility	Method to determine Distillation temperatures	Method to determine methane and Ethane content
	SLO2 Gasoline, Diesel- sources and composition	Technical Specification of Reference fuel for testing vehicles -Gasoline	Properties of different fuels- Oxidation stability	Research Octane Number (RON), Motor Octane Number (MON)	C ₃ and C ₄ content
S-2	SLO1 CNG- sources and composition	Technical Specification of Reference fuel for testing vehicles - Diesel	Properties of different fuels- Octane rating	Calorific value, Oxidation Stability	Motor Octane number
	SLO2 LPG –sources and composition	Technical Specification of Reference fuel for testing vehicles -CNG	Properties of different fuels- Cetane rating	Sulphur content	Hydrogen sulphide content(LPG)
S-3	SLO1 Alcohols –sources and composition	Technical Specification of Reference fuel for testing vehicles - LPG	Properties of different fuels- Cetane rating	Reid Vapour Pressure	Odour, Copper strip corrosion
	SLO2 Alcohols –sources and composition	Technical Specification of Reference fuel for testing vehicles - Blended fuels	Calorific Value	Benzene, Aromatic	Wobbe Index(CNG)
S-4	SLO1 Biodiesels –sources and composition	Comparison of the specification of Commercial Gasoline and commercial diesel for different Bharat stage norms,	Density	Olefin and oxygen content	Oxidation Stability
	SLO2 Biodiesels –sources and composition	Comparison of the specification of Commercial Gasoline and commercial diesel for different Bharat stage norms,	Viscosity	Method to determine Ash content	Low temperature flow properties
S-5	SLO1 Reformulated fuels -Types and Use	Fuel quality improvement accomplished in India	Carbon Residue Etc.	Carbon residue	Kinematic viscosity
	SLO2 Reformulated fuels -Types and Use	Fuel quality improvement accomplished in India	Characteristic requirements of different fuels in IC engines- Availability	Cetane number and Index	Cetane number, Copper strip corrosion
S-6	SLO1 Additives-Types and Use	Fuel quality compliance issues	Characteristic requirements of different fuels in IC engines- Fuel economy	Distillation temperature	Ester content, Mono, Di and Tri-glycerides

	SLO2	Hydrogen as IC engine fuel	Fuel quality compliance issues	Characteristic requirements of different fuels in IC engines- Performance	Flash point, Kinematic viscosity	Density, Iodine Number
S-7	SLO1	Comparison of LPG, CNG, Hydrogen	Fuel testing	Gasoline quality effects on vehicle emissions,	Density, calorific value	Structure indices
	SLO2	Comparison of LPG, CNG, Hydrogen	Presumptive liability	Diesel quality effects on vehicle emissions	Test for sulphur and water content, sulphated ash	Liquid chromatography technique
S-8	SLO1	Importance of fuel testing	Fuel registration and tracking-A comparison in India, USA and Japan	Ultra low sulphur fuels	Cold filter plug point, Cloud point	Gas chromatography
	SLO2	Need for fuel testing Standards	Fuel registration and tracking-A comparison in India, USA and Japan	Lubricity characteristics	Copper strip corrosion	Mass Spectrometry analysis
S-9	SLO1	An overview of the different standards available for fuel testing-EN, ASTM, ISO, JIS BIS	Inhibiting factors in fuel quality improvement in India	Flame characteristics- burning velocity, flame temperature and flammability limit	Oxidative stability	Photo spectrometry analysis
	SLO2	An overview of the different standards available for fuel testing-EN, ASTM, ISO, JIS BIS	Inhibiting factors in fuel quality improvement in India	Flame characteristics- burning velocity, flame temperature and flammability limit	Polycyclic Aromatic Hydrocarbon	Photo spectrometry analysis

Learning Resources	<ol style="list-style-type: none"> 1. Automotive Fuels Reference Book-Keith Owen, Trevor Coley, Second Edition, Society of Automotive Engineers Inc.,1995 2. ALTERNATIVE FUELS Concepts, Technologies and Developments S.S. Thipse, Jaico Publishing House 3. Practical Handbook on Fuel Properties and Testing by SajidZaman, Lambert Academic Publishing, 2014. 4. Motor Vehicles Act ,2009,India 5. ARAI Tap Document –Document on Test Method, Testing Equipments and Related Procedures for Testing Type approval and Conformity of Production (COP),Ministry of Road Transport and High ways 6. Biodiesel Production and Properties by AmitSarin, RSC Publishing , 2012
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	40%	-	40%	-	40%	-	40%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	20%	-	20%	-	20%	-	20%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100%-	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.Gunabalan,Manager, R&D Turbo Energy ,Chennai,	1.Dr.M.Arul Prakasajothi, Associate Professor, Mechanical Engineering, VelTech , Deemed to be university ,Email :arulprakasajothi@veltech.edu.in	1. Dr. S. Thiyagarajan. SRMIST
2. Mr.Shantha Kumar, Lead Engineer, Royal Enfield	2.Dr.S.Natrajan, Assistant Professor(Senior Grade),Mechanical Engineering, Sri Venkateswara College of Engineering, Email: natraj@svce.ac.in	2.Mr. C. Prabhu, SRMIST

Course Code	18AUE334T	Course Name	AUTOMOTIVE EXHAUST SYSTEM DEVELOPMENT	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18AUC301J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1:	Gain knowledge about Various exhaust systems.	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Understand various emission norms and control methods	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3:	Gain knowledge about noise pollutions and control methods				H	M	M	H	M	M	H	H	H	M	H	M	H	M	M
CLR-4:	Enlighten the knowledge in Computational analysis.				H	H	M	M	L	L	M	H	H	M	M	M	H	M	M
					H	H	H	H	M	M	M	M	M	H	H	H	H	M	M
		2	80	75	H	H	H	H	M	M	H	M	H	M	H	H	L	H	
		2	80	75	H	H	H	H	M	M	M	M	H	H	H	H	M	H	

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	1	85	80	H	M	M	H	M	M	H	H	M	H	M	M	H	M	M
CLO-1:	Understand the History and evolution of Automobile Exhaust System	1	85	80	H	H	M	M	L	L	M	H	H	M	M	M	H	M	M
CLO-2:	Gain familiarity on the emission norms and emission reduction techniques	1	85	80	H	H	M	M	L	L	M	H	H	M	M	M	H	M	M
CLO-3:	Get familiarized with the basics of acoustics, muffler types and characteristic design of mufflers	2	80	75	H	H	H	H	M	M	M	M	M	H	H	H	H	M	M
CLO-4:	Understand the procedures and fundamentals involved in computational fluid dynamic, thermal and structural analysis of vehicle exhaust system	2	80	75	H	H	H	H	M	M	H	M	H	M	H	H	L	H	
CLO-5:	Understand the fundamentals involved in testing and validation of automotive exhaust system	2	80	75	H	H	H	H	M	M	M	M	H	H	H	H	M	H	

Duration (hour)	History of Automobile Exhaust Systems	Hot End	Cold End	Computational Analysis (CFD and FEA)	Testing and Validation
	09	09	09	09	09
S-1	SLO-1 History and evolution of automobile exhaust system	Gasoline engine out pollutants	Basics of acoustics, fundamentals of sound, terminologies, noise cancellation.	CFD for vehicle exhaust system, governing equation of fluid flow and heat transfer	Vehicle noise measurement
	SLO-2 History and evolution of automobile exhaust system	Diesel engine out pollutants	Destructive & constructive interferences	CFD for vehicle exhaust system, governing equation of fluid flow and heat transfer	Vehicle noise measurement
S-2	SLO-1 Basics of exhaust system	Emission norms	Engine noise introduction, gasoline & diesel engine operation	Flow uniformity, pressure loss through exhaust system	Operational vibration analysis, experimental modal analysis
	SLO-2 Exhaust system from engine head face to tail pipe	Converter hot end components	Exhaust noise characteristics, vehicle pass by noise, exhaust noise measurement standards	Exhaust system, flow eccentricity, hego index, conjugate heat transfer analysis	Air leak test, thermal shock tests, thermal fatigue test
S-3	SLO-1 Layout of exhaust system	Three way catalytic converter, manifold – cone profiles.	Types of exhaust noises, pulsation noises, flow noises, booming noises	Introduction to finite element analysis	Back pressure measurement test
	SLO-2 Different components of exhaust system	Substrate	Shell radiation noises, passive noise reduction techniques	Present, past, future features	Hot end system
S-4	SLO-1 Introduction about air pollution and noise pollution	Types of substrate	Types of mufflers, reflective, absorptive, hybrid mufflers	Introduction to preprocessing 1d, 2d, 3d elements	Hot vibration test, cold vibration test
	SLO-2 Air pollution and noise control requirements in automobiles	Wash coat, mat, types of mats, shell	Muffler design constrains, muffler internal design, tri flow muffler, straight through muffler	Meshing and processing techniques	Flow noise measurement
S-5	SLO-1 Hot end components of exhaust system	Canning and types of canning	Helmholtz resonator, internal resonators	Statics of strength of materials	Shell deformation test, cold end: biaxial fatigue test
	SLO-2 Cold end components of exhaust system	Controlled canning, gbd (gab bulk density)	Baffle plates, perforations, shells, end plates, pipe diameters	Types of analysis	Uniaxial fatigue test, salt spray test, condensate water noise test

S-6	SLO-1	Manufacturing of exhaust components	Temperature sensor, oxygen sensor	Absorptive materials, development methodologies, muffler performance parameters, sound transmission loss, insertion loss	Modal analysis	Transmission loss measurement
	SLO-2	Exhaust manifold manufacturing process	Thermal management, insulators, heat shields (gasoline \ diesel).	Noise reduction, tail pipe noise level, back pressure, vehicle interior noise levels, advanced muffler technologies, cat con integrated muffler	Linear static analysis	Shell stiffness measurement , glass wool endurance test
S-7	SLO-1	Silencer manufacturing process	Advancement in substrates, Technology for gasoline engine	Variable flow muffler, twin mufflers, active noise cancellation, sporty sound mufflers	Introduction to non-linear analysis	Resonance frequency measurement
	SLO-2	Exhaust system integration	Gasoline particulate filter(gpf)	Sound engineering, off road, on road, non-road muffler applications examples, manufacturing types & process	Dynamic analysis	Shell radiation noise measurement
S-8	SLO-1	Service of exhaust system	Lean NOx trap (INT), Technology for diesel engine	Roll and spot welding, lock seaming.	Thermal analysis	Tail pipe noise measurement
	SLO-2	Service of exhaust system	Exhaust gas recirculation (EGR)	Double seaming, web forming.	RLDA & fatigue analysis	Tail pipe noise measurement
S-9	SLO-1	Replacing of exhaust system	Diesel oxidation catalyst (DOC), partial flow filter (PFF), diesel particulate filter (DPF)	Clinching, cold metal transfer, hydro forming.	Post processing techniques of different analysis	Water drainage ability test
	SLO-2	Replacing of exhaust system	Selective catalytic reduction (SCR), selective catalytic reduction filter (SCRF), global regulations and testing protocols	Piercing, stamping, muffler examples.	Process flows and targets, case study 1-2-3.	Water drainage ability test

Learning Resources	<p>1. Philip ii smith and John Morrison "The scientific design of exhaust and intake systems engineering and performance"., 3rd edition, publisher : Bentley (Robert) inc., USA</p> <p>2. Istvan I. Ver and leol.Beranek "Noise and vibration control engineering (principles and applications)", 2nd edition 2006, publisher : john wiley& sons inc.</p> <p>3. M.Imunjal "Acoustics of ducts and mufflers with applications to exhaust and ventilation system design"., 2nd edition, publisher : wiley- inter science</p>
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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2. Mr. Ram Prasanth A, Caterpillar India Pvt Ltd, anjaneyulu_ram_p@cat.com	2. Dr.Parthasarathy M,Vel Tech RangarajanDr.Sagunthala R&D Institute of Science and Technology, nparthasarathy@veltech.edu.in.	2. Mr.D. Boopathi, SRMIST

Course Code	18AUE335T	Course Name	ENGINE AUXILIARY SYSTEMS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18AUC301J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Impart knowledge about Super charging & Turbocharging their mapping procedure and thermodynamic issues related to their operation.				Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Provide a fundamental knowledge on Engine Thermal Management																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1 :	Acquire knowledge about Supercharging and compressor mapping.				2	90	90	H	H	M	H	L	L	M	L	H	M	M	M	M	H	H	M	H
CLO-2 :	Gain knowledge about Flow maps of supercharging systems.				2	90	90	H	M	M	M	M	L	L	M	H	M	M	M	M	H	M	H	H
CLO-3 :	Analyze Thermodynamic issues with Turbocharging.				2	90	90	H	M	H	H	M	H	L	L	H	M	H	M	H	M	H	M	H
CLO-4 :	Understand the Modern design features of exhaust turbocharger features.				2	90	90	M	H	M	M	H	M	H	H	M	L	H	M	H	M	H	M	H
CLO-5 :	Acquire knowledge about Engine thermal management.				2	90	90	H	H	M	H	L	H	M	L	L	H	M	M	M	H	M	H	H

Duration (hour)		Introduction	Super charging and turbo charging	Performance characteristics	Feature characteristics	Heat management
		9	9	9	9	9
S-1	SLO1	Introduction to super charging	Introduction to flow maps of supercharging systems	Introduction to thermodynamic issues with turbocharging	Introduction to particular features of exhaust turbocharging	Charge boosting, exhaust pre-release, turbo-cooling
	SLO2	Introduction to compressor mapping	Two stroke engines	Cylinder release temperature	Exhaust manifold arrangements for various firing sequences of engines.	Miller, two stage, complex, hyper-bar, rotor designs
S-2	SLO1	Definitions, survey of supercharging methods,	Four stroke engines	Mean exhaust temperature	Exhaust manifold arrangements for various firing sequences of engines.	Types of impellers, bearing arrangements,
	SLO2	Petrol engines	Interaction between turbocharger and engine.	Theoretical aspects of complete extraction of work	Constant pressure vs pulse turbocharging	types and lubrication on bearings
S-3	SLO1	Diesel engines	Mechanical supercharging,	Expanding from release pressure to ambient pressure	Constant pressure vs pulse turbocharging.	Examples of supercharged engines of road vehicles (cases),
	SLO2	Exhaust turbo charging.	Mechanical supercharging,	Complete conversion into kinetic energy at ambient pressure.	Modified forms of pulse turbocharging.	introduction to engine cooling systems, engine coolants,
S-4	SLO1	Fundamentals of compressor matching,	Exhaust turbo charging	Complete conversion into kinetic energy at ambient pressure.	Transient response.	Heat exchangers, in-vehicle installation, performance curves.
	SLO2	compressor power	Exhaust turbo charging -operational differences.	Compressor power in terms of mean piston pressure	Transient response	Pressurized engine cooling systems: filling, de-aeration & drawdown accessories.
S-5	SLO1	Air consumption	Equivalent nozzle area of turbine	Compressor power in terms of mean piston pressure	Torque characteristics of engines with exhaust turbochargers	On-highway cooling system test code, engine cooling systems field test (air-to-boil)
	SLO2	Types of compressors	Equivalent nozzle area of turbine	Numerical -compressor power in terms of mean piston pressure	Torque characteristics of engines with exhaust turbochargers.	Heat exchanger thermal & pressure cycle durability. Cooling fans
S-6	SLO1	Compressor characteristics	Pulse turbocharging	Numerical problem -compressor power in terms of mean piston pressure	Measures to improve acceleration	Fan laws, fan characteristics, and system resistance curve

	SLO2	Relationship between air consumption and power	Pulse turbocharging	Difference in fuel consumption between mechanical and exhaust superchargers.	Measures to improve acceleration	Cooling flow measurement techniques.
S-7	SLO1	Numerical problems-calculate air consumption and power	Diagram for determination of operating condition of a single stage turbocharger system.	Difference in fuel consumption between mechanical and exhaust superchargers.	Measures to improve torque characteristics of exhaust turbocharged engines.	Cooling system inspection, trouble diagnosis & service.
	SLO2	Numerical problems- calculate air consumption and power	Diagram for determination of operating condition of a single stage turbocharger system.	Effect of cooling the charge air.	Measures to improve torque characteristics of exhaust turbocharged engines.	Radiator field failures. Introduction to EGR (exhaust gas recirculation) coolers
S-8	SLO1	Volumetric efficiency of supercharged four stroke engines.	Examples of computed results	Effect of cooling the charge air.	Altitude de-rating	its significance in reduction of vehicle emissions.
	SLO2	Numerical problems-calculate volumetric efficiency	Examples of computed results	Exhaust turbocharger as a means to increase efficiency	Altitude de-rating	Cycle test-I
S-9	SLO1	Computations of gas exchange process	Examples of computed results	Numerical problem-Exhaust turbocharger as a means to increase efficiency.	Effect of supercharging on exhaust emissions of SI engines	Cycle test-II
	SLO2	Computations of gas exchange process	Tutorials on supercharging systems	Numerical problem-Exhaust turbocharger as a means to increase efficiency.	Effect of supercharging on exhaust emissions of CI engines	Surprise test

Learning Resources	<ol style="list-style-type: none"> 1. Zinner, K, "Auxiliary Engine Systems by Supercharging of Internal Combustion Engines", Springer, 1978. 2. N. Watson and M.S. Janota, "Turbocharging the Internal Combustion Engines", Macmillan Press, London 1982 3. BOSCH, "Automotive Handbook", 8 th Edition, Bentley Robert Incorporated, 2011 4. Lilly, L.C.R, "Diesel Engine Reference Book", Butterworths, London, 1984 	<ol style="list-style-type: none"> 5. Benson, R.S, Whitehouse N.D, "Internal Combustion Engines", Vol 1 and 2, Pergamon Press Ltd. Oxford UK.1980 6. Tom Birch, "Automotive Heating & Air Conditioning", 6th edition, Prentice Hall PTR, 2011 7. Hermann Hiereth, Peter Prenzinger, "Charging the Internal Combustion Engine", Springer, 2010.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		100%	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry		Experts from Higher Technical Institutions
1. Mr. Jayaraman.R, BLG Logistics, jayaraman.r@blgparekh.com		1. Dr.S. Ramkumar, Vel Tech, drsramkumar@veltech.edu
2. Mr. Shanmuga Sundaram, Renault Nissan, sankaran@mtbci.com		2. Mr.R. Sakthivel, Sri Venkateswara College of Engineering, rsakthivel@svce.ac.in
		Internal Experts
		1. Dr. V. Edwin Geo, SRMIST
		2. Mr. T. Prakash, SRMIST

Course Code	18AUE431T	Course Name	DESIGN OF AUTOMOTIVE THERMAL SYSTEMS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18AUC203T	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Psychometric chart, Heat and Mass transfer data book, Refrigerant table		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Understand various thermal systems and its functions				Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Solve cooling load calculations and to select different types of fans.									Problem Analysis														
CLR-3 :	Understand various types of compressors									Design & Development														
CLR-4 :	Familiarize with the applications of different fluid systems.									Analysis, Design, Research														
CLR-5 :	Understand the concepts to design heat exchangers									Modern Tool Usage														
									Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3						
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1 :	Understand the methodology of a thermal system.					1	90	85	H	H	M	M	M	L	L	L	L	L	L	M	H	H	H	H
CLO-2 :	Analyze a refrigeration problem to carryout necessary calculation					1	90	85	H	M	M	M	M	L	M	L	M	L	L	H	M	M	M	M
CLO-3 :	Identify different air compressor systems and its applications and able to calculate its efficiencies					1	90	85	H	H	H	H	M	L	M	L	L	L	L	H	M	M	M	M
CLO-4 :	List the basic components and analyze the working of fluid transport system					2	90	85	H	M	H	H	H	L	L	L	L	L	L	M	M	H	M	M
CLO-5 :	Able to identify parts of heat exchanger systems and design heat exchangers based on various criteria's					2	90	85	H	M	H	H	M	L	M	L	L	L	L	H	M	M	M	H
CLO-6 :	Apply the design concepts of automotive thermal systems					2	90	85	H	H	H	H	H	L	L	L	L	L	L	H	H	H	M	H

Duration (hour)		6	10	10	10	9
S-1	SLO-1	Introduction to Thermal Systems	Introduction to Automotive Air Conditioning	Introduction to Air Compressors	Introduction to Fluid Transport	Introduction to Heat Exchangers
	SLO-2	Introduction to Thermal Systems	Introduction to Automotive Air Conditioning	Introduction to Air Compressors	Introduction to Fluid Transport	Introduction to Heat Exchangers
S-2	SLO-1	System, boundary and surroundings, heat transfer, fluid flow	Psychrometric properties	Types and classification of compressors	Incompressibility and expansion of fluids	Functions of radiator, compressor
	SLO-2	System, boundary and surroundings, heat transfer, fluid flow	Psychrometric properties	Types and classification of compressors	Incompressibility and expansion of fluids	Functions of radiator, compressor
S-3	SLO-1	Heat engines – Functions, components, working	Use of psychrometric chart	Working principle	Transmission of forces through fluids, multiplication of forces Fluid power	Functions of condenser, evaporator, expansion valve
	SLO-2	Heat engines – Functions, components, working	Use of psychrometric chart	Working principle	Transmission of forces through fluids, multiplication of forces Fluid power	Functions of condenser, evaporator, expansion valve
S-4	SLO-1	Cooling , properties of coolant	Refrigerants – Types of refrigerants	Reciprocating compressors	Applications of fluid power – power brakes, power steering, shock absorber	Classification of heat exchangers – According to transfer process
	SLO-2	Cooling , properties of coolant	Refrigerants – Types of refrigerants	Reciprocating compressors	Applications of fluid power – power brakes, power steering, shock absorber	Classification of heat exchangers – According to transfer process
S-5	SLO-1	Coolant recirculation systems	Properties and Selection of refrigerants	Single and multistage compressors	Components of hydraulic and pneumatic systems	Number of fluids, surface compactness
	SLO-2	Coolant recirculation systems	Properties and Selection of refrigerants	Single and multistage compressors	Components of hydraulic and pneumatic systems	Number of fluids, surface compactness
S-6	SLO-1	Coolant lubrication systems	Factors affecting the air flow	Compressors - compression with and without clearance	Reservoir, pumps, strainers, filters, valve types, actuators, motors	Construction features, flow arrangements, heat transfer mechanisms.
	SLO-2	Coolant lubrication systems	Factors affecting the air flow	Compressors - compression with and without clearance	Reservoir, pumps, strainers, filters, valve types, actuators, motors	Construction features, flow arrangements, heat transfer mechanisms.
S-7	SLO-1		Types of fans	Calculations - volumetric, isothermal and isentropic efficiency	Accumulators, oil coolers, cooling fan, tubing, piping, hose	Selection and design of heat exchangers based on – Types, heat transfer rate

	SLO-2		Types of fans	Calculations - volumetric, isothermal and isentropic efficiency	Accumulators, oil coolers, cooling fan, tubing, piping, hose	Selection and design of heat exchangers based on – Types, heat transfer rate
S-8	SLO-1		Axial and Centrifugal fans	Rotary compressors	Fluid transport and power systems	Selection and design of heat exchangers based on – cost, pumping power
	SLO-2		Axial and Centrifugal fans	Rotary compressors	Fluid transport and power systems	Selection and design of heat exchangers based on – cost, pumping power
S-9	SLO-1		Load calculations	Comparison between reciprocating and rotary compressors	Applications of pneumatic and hydraulic systems	Selection and design of heat exchangers based on – size and weight materials
	SLO-2		Load calculations	Comparison between reciprocating and rotary compressors	Applications of pneumatic and hydraulic systems	Selection and design of heat exchangers based on – size and weight materials
S-10	SLO-1		Winter air conditioning	Comparison between centrifugal and axial compressors	Advantage and disadvantages of hydraulic systems	
	SLO-2		Winter air conditioning	Comparison between centrifugal and axial compressors	Advantage and disadvantages of hydraulic systems	

Learning Resources	1. Rajput R.K, "Thermal Engineering", Laxmi Publications, 8th Edition, New Delhi, 2010 2. R. C. Sachdeva, "Fundamentals of Engineering Heat and Mass Transfer", New Age Science Ltd., New Delhi, 2009 3. C.P Arora "Refrigeration and Air conditioning", 3rd edition., McGraw Hill Education (india) private Limited. 2014	4. Holman, J P, "Heat transfer", McGraw – Hill, New york, 1968 5. Yunus A Cengel, Afshin J Ghajar, "Heat and Mass Transfer", Tat McGraw Hill Education Private Limited, New Delhi, 2013 6. Andrew parr, "Hydraulics and Pneumatics", second edition, Butterworth Heinemann
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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2. Mr. Jayaraman. R, BLG Logistics, jayaraman.r@blgparekh.com	2. Dr. V. Karthickeyan, Sri Krishna College of Engineering and Technology, karthickeyanv@skcet.ac.in	2. Dr. A. Prabu, SRMIST

Course Code	18AUE432T	Course Name	SIMULATION OF IC ENGINES	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18AUC301J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Gain Knowledge about various engine design parameters.	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Understand engine numerical modeling.	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Enlighten the knowledge about simulation of various performance parameters for different type engine.	Expected Proficiency (%)	Problem Analysis
		Expected Attainment (%)	Design & Development
			Analysis, Design, Research
			Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Understand the Various Combustion Parameters.	1 90 85	H H M H H L M L L L M L L M M
CLO-2 :	Analyze the various idle cycles	1 90 85	H H M M H L M L L L L L L M M
CLO-3 :	Understand Various Combustion Simulations	2 90 85	H H M M H L M L L L L L L M M
CLO-4 :	Gain knowledge about two Stroke engine simulations	2 90 85	H M L M H L L L L L L M L M M
CLO-5 :	Understand Diesel engine numerical modeling	2 90 85	H H L M H L L L L L L M M L M M

	Introduction to Combustion	SI Engine Simulation With Air as Working Medium	Progressive Combustion	Simulation of 2-Stroke SI Engine	Diesel Engine Simulation
	9	9	9	9	9
S-1	SLO-1 Introduction to combustion	Ideal Cycles in SI Engine	SI Engines Simulation With Progressive Combustion	Simulate The Performance Of 2 Stroke SI Engine	Multi Zone Model For Diesel Combustion
	SLO-2 Heat of reaction	Ideal Cycles in SI Engine	SI Engines Simulation With Progressive Combustion	Simulate The Performance Of 2 Stroke SI Engine	Multi Zone Model For Diesel Combustion
S-2	SLO-1 Measurement of URP	Actual working cycle in SI Engine	SI Engines Simulation With Gas Exchange	Simulate The Performance Of 2 Stroke SI Engine	Multi Zone Model For Diesel Combustion
	SLO-2 Measurement of URP	Actual working cycle in SI Engine	SI Engines Simulation With Gas Exchange	Simulate The Performance Of 2 Stroke SI Engine	Multi Zone Model For Diesel Combustion
S-3	SLO-1 Measurement of HRP	Deviation Between Actual And Ideal Cycle – Problems	Heat Transfer Process	Simulate The Performance Of 2 Stroke SI Engine	Multi Zone Model For Diesel Combustion
	SLO-2 Measurement of HRP	Deviation Between Actual And Ideal Cycle – Problems	Heat Transfer Process	Simulate The Performance Of 2 Stroke SI Engine	Multi Zone Model For Diesel Combustion
S-4	SLO-1 Adiabatic flame temperature	SI Engine Simulation With Adiabatic Combustion	Friction Calculation	Simulate The Performance Of 2 Stroke SI Engine	Different Heat Transfer Models For Diesel Engine Simulation
	SLO-2 Adiabatic flame temperature	SI Engine Simulation With Adiabatic Combustion	Friction Calculation	Simulate The Performance Of 2 Stroke SI Engine	Different Heat Transfer Models For Diesel Engine Simulation
S-5	SLO-1 Complete combustion in C/H/O/N Systems	SI Engine Temperature Drop Due To Fuel Vaporization	Compression Of Simulated Values	Simulate The Performance Of 2 Stroke SI Engine	Different Heat Transfer Models For Diesel Engine Simulation
	SLO-2 Complete combustion in C/H/O/N Systems	SI Engine Temperature Drop Due To Fuel Vaporization	Compression Of Simulated Values	Simulate The Performance Of 2 Stroke SI Engine	Different Heat Transfer Models For Diesel Engine Simulation
S-6	SLO-1 Constant volume adiabatic combustion	Full Throttle Operation - Efficiency Calculation	Validation Of The Computer Code	Simulation Of Unbalanced Forces On Two Stroke Engine	Diesel Engine Equilibrium Calculations
	SLO-2 Constant volume adiabatic combustion	Full Throttle Operation - Efficiency Calculation	Validation Of The Computer Code	Simulation Of Unbalanced Forces On Two Stroke Engine	Diesel Engine Equilibrium Calculations

S-7	SLO-1	Constant pressure adiabatic combustion	SI Engine Part-Throttle Operation	Engine Performance Simulation	Simulation Of Unbalanced Forces On Two Stroke Engine	Diesel Engine Equilibrium Calculations
	SLO-2	Constant pressure adiabatic combustion	SI Engine Part-Throttle Operation	Engine Performance Simulation	Simulation Of Unbalanced Forces On Two Stroke Engine	Diesel Engine Equilibrium Calculations
S-8	SLO-1	Calculation of adiabatic flame temperature	SI Engine Part-Throttle Efficiency Calculation	Pressure Crank Angle Diagram	Simulation Of Unbalanced Forces On Two Stroke Engine	Simulation Of Diesel Engine Performance
	SLO-2	Calculation of adiabatic flame temperature	SI Engine Part-Throttle Efficiency Calculation	Pressure Crank Angle Diagram	Simulation Of Unbalanced Forces On Two Stroke Engine	Simulation Of Diesel Engine Performance
S-9	SLO-1	Isentropic changes of state	Super Charged Operation	Other Engine Performance	Simulation Of Unbalanced Forces On Two Stroke Engine	Diesel Engine Simulation For Pollution Estimation
	SLO-2	Isentropic changes of state	Super Charged Operation	Other Engine Performance	Simulation Of Unbalanced Forces On Two Stroke Engine	Diesel Engine Simulation For Pollution Estimation

Learning Resources	<ol style="list-style-type: none"> Ganesan. V. "Computer Simulation of spark ignition engine process", Universities Press (I) Ltd, Hyderabad, 1996. Ganesan. V, "Computer Simulation of Compression Ignition Engines", Orient Longman, 2000 Ramoss. A. L, "Modelling of Internal Combustion Engines Processes", McGraw Hill Publishing Co., 1992 Ashley Campbel, "Thermodynamic Analysis of Combustion Engines", John Wiley & Sons, New York, 1986
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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2. Mr.P.MohamedAzarudeen, Renault Nissan Technology and Business Centre, mohamedazarudeen.pakkimohideen@mtbci.com	2. Dr.S.RamKumar, Vel Tech RangarajanDr.Sagunthala R&D Institute of Science and Technology , drsramkumar@veltech.edu.in	2. Mr. D. Boopathi, SRMIST

Course Code	18AUE433T	Course Name	AUTOMOTIVE EMISSION FORMATION AND CONTROLS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18AUC301J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Learn about SI engine emission formation	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Provide an insight CI engine emission formation	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Familiarize with the basics of noise pollution																		
CLR-4 :	Create insight on emission measuring instruments																		
CLR-5 :	Learn about noise and vibration measurement																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Comprehend the various emissions from SI engine and its control techniques	1	80	75	M	M	M	H	H	L	L	M	M	H	H	M	H	H	M
CLO-2 :	Match the emission reduction techniques from CI engine	1	85	80	H	M	M	H	M	M	H	M	L	M	H	M	H	H	M
CLO-3 :	Evaluate the noise pollution formation	2	80	75	M	H	H	M	H	M	L	H	M	M	M	L	H	M	M
CLO-4 :	Apply the knowledge on measuring emissions through instruments	2	80	75	H	H	M	M	H	H	M	M	L	H	M	H	H	M	L
CLO-5 :	Cognize the noise and vibration measurement	1	85	80	M	H	H	M	H	M	L	H	M	H	M	L	H	M	L

Duration (hour)		SI engine emission	CI engine emission	Noise Pollution	Emission Measurement	Noise measurement
		9	9	9	9	9
S-1	SLO-1	Emission formation in SI engines (CO, HC)	Emission formation in CI engines (HC, CO)	Basics of acoustics–fundamentals of sound – terminologies–	Principle of operation of emission measuring instruments used in SI and CI engines.	Vehicle noise measurement
	SLO-2	Emission formation in SI engines (CO, HC)	Emission formation in CI engines (HC, CO)	Noise cancellation– destructive & constructive interferences	Principle of operation of emission measuring instruments used in SI and CI engines.	Operational vibration analysis
S-2	SLO-1	Emission formation in SI engines (NOx).	Emission formation in CI engines (NOx, aldehydes)	Engine noise introduction–gasoline & diesel engine operation.	Measurement of CO2 and CO by NDIR	Experimental modal analysis – air leak test
	SLO-2	Emission formation in SI engines (NOx).	Emission formation in CI engines (NOx, aldehydes)	Exhaust noise characteristics –vehicle pass by noise – exhaust noise measurement standards	Measurement of CO2 and CO by NDIR	Experimental modal analysis – air leak test
S-3	SLO-1	Effect of design variables on emission formation in SI engines	Emission formation in CI engines (smoke and particulates)	Types of exhaust noises– pulsation noises– flow noises–booming noises	Hydrocarbon emission by FID	Thermal shock tests – thermal fatigue test
	SLO-2	Effect of design variables on emission formation in SI engines	Emission formation in CI engines (smoke and particulates)	Shell radiation noises–passive noise reduction techniques	Hydrocarbon emission by FID	Thermal shock tests – thermal fatigue test
S-4	SLO-1	Effect of operating variables on emission formation in SI engines	Effect of design variables on emission formation in CI engines	Types of mufflers –reflective–absorptive – hybrid mufflers –muffler design constrains	Chemiluminescentanalyser for NOx	Back pressure measurement test–hot end system
	SLO-2	Effect of operating variables on emission formation in SI engines	Effect of design variables on emission formation in CI engines	Muffler internal design–tri flow muffler –straight though muffler	Chemiluminescentanalyser for NOx	Back pressure measurement test–hot end system
S-5	SLO-1	Control techniques -Thermal reactor,	Effect of operating variables on emission formation in CI engines	Helmholtz resonator – internal resonators – baffle plates– perforations	Gas Chromatograph	Hot vibration test – cold vibration test
	SLO-2	Control techniques -Thermal reactor,	Effect of operating variables on emission formation in CI engines	shells –end plates–pipe diameters	Gas Chromatograph	flow noise measurement
S-6	SLO-1	Control techniques - exhaust gas recirculation	Control techniques, exhaust gas recirculation	Absorptive materials –development methodologies	Spot sampling	Salt spray test – condensate water noise test
	SLO-2	Control techniques - exhaust gas recirculation	Control techniques, exhaust gas recirculation	muffler performance parameters– sound transmission loss –insertion loss	Spot sampling	Salt spray test – condensate water noise test

S-7	SLO-1	Three way catalytic convertor	NOx selective catalytic reduction	Noise reduction–tail pipe noise level –back pressure –vehicle interior noise levels	Continuous indication type smoke meters (Bosch, AVL and Hartridge smoke meters)	Transmission loss measurement – shell stiffness measurement – glass wool endurance test
	SLO-2	Three way catalytic convertor	NOx selective catalytic reduction	Advanced muffler technologies–cat con integrated muffler	Continuous indication type smoke meters (Bosch, AVL and Hartridge smoke meters)	Transmission loss measurement – shell stiffness measurement – glass wool endurance test
S-8	SLO-1	Charcoal canister control for evaporative emission	Diesel oxidation catalyst catalytic convertor	Variable flow muffler –twin mufflers–active noise cancellation–sporty sound mufflers–sound engineering	Emission test procedures – FTP	Resonance frequency measurement – shell radiation noise measurement
	SLO-2	Charcoal canister control for evaporative emission	Diesel oxidation catalyst catalytic convertor	Off road – on road –non road muffler applications examples –manufacturing types & process	Emission test procedures – FTP	Resonance frequency measurement – shell radiation noise measurement
S-9	SLO-1	Positive crank case ventilation for blow by gas control	Diesel particulate filter	Roll and spot welding–lock seaming–double seaming –web forming–clinching–cold metal transfer	Euro and Bharat norms	Tail pipe noise measurement – water drainage ability test.
	SLO-2	Positive crank case ventilation for blow by gas control	NOx versus particulates –trade off	Hydro forming –piercing– stamping–muffler examples	Euro and Bharat norms	Tail pipe noise measurement – water drainage ability test.

Learning Resources	1. Ganesan V, "Internal combustion engines", 4th edition, Tata McGraw Hill Education, 2012	2. John B Heywood. "Internal Combustion Engine Fundamentals". , Tata McGraw-Hill 1988.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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2. Mr.ShanmugaSundaram, Renault Nissan, sankaran@mtbci.com	2. Dr.R.Sakthivel, Sri Venkateswara College of Engineering, rsakthivel@svce.ac.in	2. Dr. S. Thiyagarajan, SRMIST

Course Code	18AUE434T	Course Name	ALTERNATIVE FUELS AND ENERGY SYSTEMS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18AUC301J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Evaluate the use of alcohol in SI and CI engine	1	1
CLR-2 :	Create insight on use of vegetable oil as fuel in CI engine	2	2
CLR-3 :	Evaluate the use of hydrogen as fuel in SI and CI engine	3	3
CLR-4 :	Analyze the other gaseous fuels utilization in SI and CI engine	4	4
CLR-5 :	Create insight on hybrid, solar and electric based vehicles	5	5
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Engineering Knowledge
CLO-1 :	Apply the knowledge of using alcohol as fuel	1	1
CLO-2 :	List the techniques employed to use vegetable oil in CI engine	2	2
CLO-3 :	Develop system for using hydrogen in engines	3	3
CLO-4 :	Understand the concepts of biogas, LPG and CNG as fuels in IC engines	4	4
CLO-5 :	Demonstrate the working of hybrid, solar and electric vehicles	5	5

Duration (hour)	Alcohol Fuels	Vegetable Oil	Hydrogen based fuels	Other Gaseous Fuels	Hybrid, solar and Electric vehicles
	9	9	9	9	9
S-1	SLO-1 Need for Alternate Fuel	Various vegetable oils and its properties	Hydrogen as fuel in IC engine, hydrogen properties	Biogas – Introduction, sources	Layout of Electric vehicles, Advantages and limitations
	SLO-2 Need for Alternate Fuel	Various vegetable oils and its properties	Hydrogen as fuel in IC engine, hydrogen properties	Biogas – Introduction, sources	Layout of Electric vehicles, Advantages and limitations
S-2	SLO-1 Properties of alcohol as IC engine fuel	Problems of using vegetable oil in CI engine and techniques to overcome	Hydrogen production and storage	Biogas production	System components, Electronic controlled system
	SLO-2 Properties of alcohol as IC engine fuel	Problems of using vegetable oil in CI engine and techniques to overcome	Hydrogen production and storage	Biogas production	System components, Electronic controlled system
S-3	SLO-1 Alcohol use in SI engine – Performance and emission	Trans-esterification – Reaction, Process optimization, fuel property variations	Problems associated with hydrogen as fuel and its solution	Factors affecting biogas production	High energy and power density batteries
	SLO-2 Alcohol use in SI engine – Performance and emission	Trans-esterification – Reaction, Process optimization, fuel property variations	Problems associated with hydrogen as fuel and its solution	Factors affecting biogas production	High energy and power density batteries
S-4	SLO-1 Gasohol, Flexible Fuel system, Reformulated Alcohol	Blending – Diesel, ether based fuels	Different methods of using hydrogen in SI and CI engine	Biogas usage in CI and SI engine	Types of hybrid vehicles
	SLO-2 Gasohol, Flexible Fuel system, Reformulated Alcohol	Blending – Diesel, ether based fuels	Different methods of using hydrogen in SI and CI engine	Biogas usage in CI and SI engine	Types of hybrid vehicles
S-5	SLO-1 Alcohol use in SI engine – Performance and emission	Fuel Preheating – electric based and waste exhaust heat, emulsification	Performance, emission and combustion characteristics	Properties of LPG and CNG as fuel in IC engine	Hybrid vehicle configuration
	SLO-2 Alcohol use in SI engine – Performance and emission	Fuel Preheating – electric based and waste exhaust heat, emulsification	Performance, emission and combustion characteristics	Properties of LPG and CNG as fuel in IC engine	Hybrid vehicle configuration
S-6	SLO-1 Dual fuel combustion	Waste to energy – Waste plastic and tires to fuel	Liquid hydrogen and metal hydrides for cars	Fuel metering system	Solar cell for energy collection
	SLO-2 Dual fuel combustion	Waste to energy – Waste plastic and tires to fuel	Liquid hydrogen and metal hydrides for cars	Fuel metering system	Solar cell for energy collection

S-7	SLO-1	Spark assisted diesel engine	Various techniques for conversion of waste solid to fuel	Fuel cell : Concept with hydrogen and methanol	Combustion characteristics	Storage batteries
	SLO-2	Spark assisted diesel engine	Various techniques for conversion of waste solid to fuel	Fuel cell : Concept with hydrogen and methanol	Combustion characteristics	Storage batteries
S-8	SLO-1	Surface ignition, ignition accelerators	Performance and emission comparison of vegetable oil and biodiesel	Power rating, performance and heat dissipation	Effect on performance and emission characteristics	Layout of solar powered vehicles
	SLO-2	Surface ignition, ignition accelerators	Performance and emission comparison of vegetable oil and biodiesel	Power rating, performance and heat dissipation	Effect on performance and emission characteristics	Layout of solar powered vehicles
S-9	SLO-1	Alcohol production techniques	First to fifth generation biofuels	Layout of fuel cell vehicle	LPG and CNG vehicle layout	Advantages and limitations
	SLO-2	Alcohol production techniques	First to fifth generation biofuels	Layout of fuel cell vehicle	LPG and CNG vehicle layout	Advantages and limitations

Learning Resources	1. M.K. GajendraBabu &K.A. Subramanian, Alternate Transportation Fuels: Utilization in combustion engine, CRC press, 2017	2. Richard L.Bechtold, Automotive Fuels Guide Book, SAE Publications, 1997
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. S. Sivaramakrishnan, Volvo Cars, sivaramakrishnan.swaminathan@volvocars.com	1. Dr. K. Balasubramanian, Sri Krishna College of Engineering, balasubramanian@skcet.ac.in	1. Dr. V. Edwin Geo, SRMIST
2. Mr.SarathRamakannan, Aston Martin, sharath.ramakrishnan@astonmartin.com	2. Dr. S. Premnath, Sri Venkateswara College of Engineering, prem@svcce.ac.in	2. Dr. S. Thiyagarajan, SRMIST

Course Code	18AUE341T	Course Name	AUTOMOTIVE DRIVELINE DESIGN	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Design the driveline systems and its components	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Distinguish the design of various flywheel and clutches	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Analyze the stresses and design various gears																		
CLR-4 :	Compare and design different gearboxes																		
CLR-5 :	Design the different braking systems and axles.																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Identify the different types power transmission drives	1,3	90	85	H	M	H	H	M	L	L	L	M	M	L	M	H	H	H
CLO-2 :	Infer the design of various flywheel and clutches	1,2	90	85	H	H	H	H	M	M	L	L	M	M	L	M	H	H	H
CLO-3 :	Classify and design different gears used in transmission systems	1,3	90	80	H	H	H	H	H	L	L	L	M	M	L	L	H	H	H
CLO-4 :	Categorize and design different gearbox and shafts	1,3	80	75	H	H	H	H	H	M	L	L	M	M	L	L	H	H	H
CLO-5 :	Interpret the design of various braking systems and axles.	1,4	90	85	H	H	H	H	M	L	L	L	M	M	L	M	H	H	H

	Design of flexible drives	Design of flywheel and clutches	Design of Spur gear and Helical gear	Design of Gearbox, Propeller shaft and joints	Design of Axles and brakes
Duration (hour)	9	9	9	9	9
S-1	SLO-1 Flexible drives-Introduction	Flywheel and governor	Gears-Introduction	Gear box, components, requirements,	Axles-Types, materials
	SLO-2 Comparison of flexible drives with rigid drives	flywheel materials	Gear terminology and gear trains	Gear matching	Design requirements of front axle
S-2	SLO-1 Belt drives types and construction	Torque analysis	Design of spur gear, Selection of material	Requirements to obtain optimum design	Loads on axles
	SLO-2 Geometrical relationship	Stresses in Solid disc flywheel	Beam strength for gear tooth	Ray diagram, geometric progression and standard step ratio	Design of front axle
S-3	SLO-1 Analysis of belt tensions	Rimmed flywheel	Permissible bending stress	Kinematic layout	Design of rear axle
	SLO-2 Condition for maximum power	Stresses in rimmed flywheel	Effective load on gear tooth	Design of sliding mesh gearbox	Solving problems
S-4	SLO-1 Pulley design for belt drives	Tutorial on flywheel design	Estimation of module based on beam strength	Design of gearbox	Brakes design
	SLO-2 Tutorial on belt drives	Design considerations of clutches	Wear strength of Spur gear	Solving problems	Energy equations
S-5	SLO-1 Introduction of chain drives	Torque Transmission Capacity, uniform pressure theory	Solving problems	Constant mesh gearbox	Design of Block brake with short shoe
	SLO-2 Advantages of chain drives over belt drives	Uniform wear theory	Solving problems	Speed reducer unit	Design of block brake with long shoe
S-6	SLO-1 Roller chains	Design of single plate clutch	Terminology of helical gears	Design of propeller shaft for bending and torsion	Solving problems
	SLO-2 Geometrical relationship	Design of multidisc clutch	Force analysis of helical gears	Design of propeller shaft for bending and torsion	Pivoted block brake with long shoes
S-7	SLO-1 Polygonal effect	Friction materials	Force analysis of helical gears	Design of propeller shaft for rigidity	Solving problems
	SLO-2 Power rating for roller chains	Design of Cone clutches	Beam strength of helical gears	Solving problems	Internal expanding brakes
S-8	SLO-1 Design of sprocket wheels	Solving problems	Effective load on gear tooth	Design of universal joints and CV joints	Band brakes design
	SLO-2 Design of chain drive	Design of centrifugal clutches	Wear strength of helical gear	Slip joint design	Disc brakes design
S-9	SLO-1 Chain lubrication	Energy equation for clutches	Estimation of module based on wear strength	Design of final drive and Differential	Thermal considerations
	SLO-2 Tutorial on chain drives	Thermal consideration in clutch design	Solving problems	Solving problems	Solving problems

Learning Resources	1. Bhandari. V. B., "Design of Machine Elements", Tata McGraw-Hill Publishing Company Ltd, 2010. 2. Gian Carlo Genta, Lorenzo Iorollo "The Automotive Chassis system design" published by Springer, 2009	3. Joseph E. Shigley & Larry D. Mitchell, "Mechanical Engineering Design", 10 th Edition, McGraw-Hill International book company, 2014 4. Julian Hapian Smith, "An Introduction to Modern Vehicle Design", Society of Automotive Engineers Inc, 2002
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.T.R.Karthikeyan, TAFE, vasucar@gmail.com	1. Dr..A.Samuel Raja, Thiyagarajar college of Engineering Madurai, samuel1973@tce.edu	1. Dr.R.Rajendran, SRMIST, rajendrr@srmist.edu.in
2. Mr.R.Srikanth, Altair, srikanth.r@altair.com	2. Mr. N.Ravikumar, Crescent Institute of Science and Technology, ravikumar@crescent.education	2. Mr.K.Devanathan, SRMIST, devanatk@srmist.edu.in

Course Code	18AUE342T	Course Name	AUTOMOTIVE CHASSIS COMPONENT DESIGN	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1:	Design the chassis and its components.	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2:	Design the steering and braking system and its components.	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3:	Compare and classify different transmission system.	Expected Proficiency (%)	Problem Analysis
CLR-4:	Distinguish various suspension systems and designing it.	Expected Attainment (%)	Design & Development
CLR-5:	Gain knowledge about tire and its performance characteristics.		Analysis, Design, Research
			Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1:	Identify different types of frames and loads acting on it.	1,3 90 85	H M H H M L L L M M L M H M M
CLO-2:	Interpret different steering and braking system components.	1,2 90 80	H H H H H M L L M M L M H H M
CLO-3:	Evaluate the transmission components and their design procedures.	1,3 90 75	H H H H H L L L M M L L H M M
CLO-4:	Classify and design different suspension system and its components.	1,3 80 75	H H M M M M L L M M L L M H H
CLO-5:	Infer about tires and their performance characteristics.	1,4 85 80	H H M H N L L L M L L M M H H

Duration (hour)	Frames	Steering and brake system	Transmission	Suspensions	Wheels and their tires
	9	9	9	9	9
S-1	SLO-1 Study of loads Bending case	Introduction Steering mechanism	Manual Gearboxes - classification Mechanical efficiency	Introduction	Description Rim characteristics
	SLO-2 Torsion case Combined bending and torsion	Introduction Steering mechanism	Manual automobile gearboxes Manual gearboxes for industrial vehicles	Design of leaf Springs	Tire characteristics Wheel reference system
S-2	SLO-1 Lateral loading	Rack and pinion steering box	Shifting Mechanisms Internal shifting mechanisms	Design of Helical Springs	Tire operation On-road driving
	SLO-2 Fore and aft loading	Screw and sector steering box	Shifting Mechanisms External shifting mechanisms	Helical Springs in Series and Parallel and design of torsion bar	Off-road driving
S-3	SLO-1 Frame materials	Design Steering column	Start-Up Devices Friction clutch	Independent suspensions McPherson suspension	Rolling radius
	SLO-2 Design of frames Moment of inertia of rectangular section.	Design Steering column	Start-up devices for automatic gearboxes	McPherson suspensions for rear axle	Rolling radius
S-4	SLO-1 Moment of Inertia of a Hollow Rectangular Section.	Power steering	Synchronizers	Double wishbone suspension	Rolling resistance Effect of speed, material nature and structure, tread wear
	SLO-2 Moment of Inertia of a Hollow Rectangular Section.	Design and testing	Design criteria of Synchronizers	Virtual centres suspensions	Effect of operating temperature, inflation pressure and vertical load, tire size, road wheel sideslip angle
S-5	SLO-1 Moment of Inertia of a Circular Section	Braking system: Introduction	Differentials And Final Drives All wheel drive transfer boxes Outline of differential theory	Trailing arm suspensions- Semi-trailing arms suspension	Static Forces
	SLO-2 Moment of Inertia of a Circular Section	Car brakes	Types of self-locking differentials Differential effect on vehicle dynamics	Multilink suspensions	Static Forces
S-6	SLO-1 Moment of Inertia of Hollow Circular Section	Service and secondary systems	Shafts And Joints ,Propeller shafts Half shafts	Semi-independent suspensions	Longitudinal Force
	SLO-2 Moment of Inertia of Hollow Circular Section	Parking system, Disc brakes Drum brakes Control system components	Universal joints Constant speed joints	Twist beam suspension	Longitudinal Force
S-7	SLO-1 Chassis types, introduction -Ladder frames -Cruciform frames	Power brakes Vacuum power brake	Automatic Gearboxes	Rigid axle suspensions - Rigid axles with leaf springs	Cornering forces
	SLO-2 Torque tube backbone frames- Space frames-	Hydraulic power brake	Epi-cycloidal car gearboxes	Rigid guided axles	Interaction between longitudinal and side forces

S-8	SLO-1	Integral structures	Design and testing braking system mechanics	Car CVTs	Industrial vehicles suspensions - Pneumatic springs	Outline on dynamic behavior
	SLO-2	Underbody, Sub-frame, Industrial vehicle frames	Mechanical design	Car CVTs	Front suspension Rear suspensions	Outline on dynamic behavior
S-9	SLO-1	Structural tasks Structural design	Thermal design	Design and testing of Gears, Shafts Bearings	Design and testing	Testing of tires
	SLO-2	Structural testing	Thermal design	Lubricants, Housings and seals	Design and testing	Testing of tires

Learning Resources	1. <i>The Automotive Chassis Volume 1: Components Design</i> Genta, Giancarlo, Morello, L., Springer, Netherlands 2009.	4. <i>Advanced Vehicle Technology</i> Heinz Heisler, Butterworth-Heinemann; 2 edition 2002.
	2. <i>Introduction to Modern Vehicle Design</i> Julian Happlan-Smith, Butterworth-Heinemann 2001.	5. <i>The Motor Vehicle</i> Kenneth Newton, T.K. Garrett, W. Steeds, Butterworth-Heinemann 12 Revised edition 1997
	3. <i>Vector Mechanics for Engineers: Statics and Dynamics</i> Beer, Johnston, McGraw Hill Education; Tenth edition 2017	

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.N. Vijayakumar Mahindra & Mahindra, vijayakumar.n@mahindra.com	1. Mr. B.Vasanthan, Madras Institute of technology, Anna University, bvasanthan@mitindia.edu	1.Dr. R. Rajendran, SRMIST, rajendrr@srmist.edu.in
2. Mr..R.Srikanth, Altair, srikanth.r@altair.com	2. Mr.N.Ravikumar,Crescent Institute of Science and Technology,ravikumar@crescent.education	2. Mr. T. Kaviyarasu ,SRMIST, kaviyart@srmist.edu.in

Course Code	18AUE343T	Course Name	VEHICLE DESIGN DATA CHARACTERISTICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18AUC305T	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1:	Acquire basic knowledge of the preliminary design concepts involved in designing of a vehicle.	1	1
CLR-2:	Acquire the knowledge of Power requirement calculation of the vehicle	2	2
CLR-3:	Inferring various characteristics of performance curves	3	3
CLR-4:	Interpreting vehicle performance by various factors	4	4
CLR-5:	Implementing appropriate gear requirements to meet performance of vehicle	5	5
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	6	6
CLO-1:	Understand the basic design principles of vehicle	7	7
CLO-2:	Able to draw the performance curves pertaining to vehicle motion	8	8
CLO-3:	Familiarize functions of several variables pertaining to vehicular design.	9	9
CLO-4:	Critiquing various design variables of engine components	10	10
CLO-5:	Able to measure the vehicle performance by several methods	11	11

Duration (hour)	Introduction to Basic Concepts in Vehicular Design	Resistance to Vehicle Motion	Performance Curves – I	Performance Curves – II	Gear Ratios calculations
	09	09	09	09	09
S-1	SLO-1 Introduction of Designing a Vehicle	Calculation, of Air Resistances at Various Vehicle Speeds	Calculation of Torque for Different Vehicle Speeds	Connecting Rod Length to Crank Radius Ratio	Gear Ratios
	SLO-2 Assumptions to be Made in Designing a Vehicle	Tabulation and Plotting of Curves for Air Resistances at Various Vehicle Speeds	Tabulation and Plotting of Torque for Different Vehicle Speeds	Calculation of Connecting Rod Length to Crank Radius Ratio	Determination of Gear Ratios
S-2	SLO-1 Gross Vehicle Weight	Tutorial on air resistance	Tutorial on torque calculation	Calculation of piston velocity	Tutorial on gear ratios
	SLO-2 Range of Values for Gross Vehicle Weight	Calculation, of Rolling Resistances at Various Vehicle Speeds	Calculation of Mechanical Efficiency for Different Vehicle Speeds	Plotting of Piston Velocity	Determination of Acceleration
S-3	SLO-1 Tutorial on gross vehicle weight calculations	Tabulation and Plotting of Curves for Rolling Resistances at Various Vehicle Speeds	Tabulation and Plotting of Mechanical Efficiency for Different Vehicle Speeds	Calculation of acceleration	Problems on Acceleration
	SLO-2 Frontal Area calculations	Tutorial on rolling resistance	Tutorial on mechanical efficiency calculations	Plotting of Acceleration Against Crank Angle	Gradability
S-4	SLO-1 Range of Values for Frontal Area	Calculation of Driving Force	Interpolation of Pressure-Volume Diagram	Calculation of gas pressure	Gradability in Different Gears
	SLO-2 Tutorial on frontal area calculations	Plotting of Driving Force	Pressure-Volume Diagram at various stages	Plotting Gas Force, Against Crank Angle	Determination of Gradability
S-5	SLO-1 Range of Values for Maximum Speed	Power Requirement for Different Loads	Frictional Mean Effective Pressure	Inertial force	Problems on Gradability
	SLO-2 Range of Values for Maximum Speed	Power Requirement for Different Loads	Calculation of Frictional Mean Effective Pressure	Calculation of inertial force	Problems on Gradability
S-6	SLO-1 Calculation on maximum speed	Tutorial on power requirement for different loads	Tutorial on Frictional Mean Effective Pressure	Plotting of Inertia Force Against Crank Angle	Influence of Gear ratio and Gradability on vehicle performance
	SLO-2 Range of Values for Maximum Acceleration	Power Requirement for Acceleration	Engine Cubic Capacity	Resultant force	Range of values of gear ratios
S-7	SLO-1 Range of Values for Maximum Acceleration	Tutorial on power requirement for acceleration	Calculation of Engine Cubic Capacity	Calculation of resultant force	Range of values of Gradability
	SLO-2 Calculation on maximum acceleration	Tutorial on power requirement for acceleration	Typical problems on engine cubic capacity	Plotting of Resultant Force Against Crank Angle	Determination of vehicle performance parameters

S-8	SLO-1	Basics of Automobile Design	Maximum Power Calculation	Typical problems on engine cubic capacity	Turning Moment Against Crank Angle	Calculation of vehicle performance
	SLO-2	Basics of Automobile Design	Maximum Power Calculation	Comparison between various performance parameters	Calculation of Turning Moment Against Crank Angle	Calculation of vehicle performance
S-9	SLO-1	Tutorial on overall design procedure of automobile	Tutorial on overall power requirement calculation	Inference from the comparison diagram	Side Thrust Against Crank Angle	Typical Problems on Vehicle Performance
	SLO-2	Tutorial on overall design procedure of automobile	Tutorial on overall power requirement calculation	Inference from the comparison diagram	Calculation of Side Thrust Against Crank Angle	Typical Problems on Vehicle Performance

Learning Resources	1. Hoag, Kevin, Don linger, Brian, "Vehicular Engine Design", 2nd Edition, springer 2016.	4. Giri. N. K., "Automotive Mechanics", Khanna Publishers, New Delhi, 2005.
	2. Fenton, "Handbook of Vehicle Design Analysis", Mechanical Engineering Publications, 1996.	5. T. K. Garrett, K. Newton, W. Steeds, Motor Vehicle, 13 th edition Butterworth-Heinemann, 2000.
	3. Heldt, P.M., "High Speed Combustion Engines", Oxford and I.B.H. Publishing Co., Kolkata, 2002.	

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%) #			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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Course Code	18AUE344T	Course Name	CONCEPTS OF ENGINEERING DESIGN	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:		Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Familiarize the students with the design process			Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Give insights into the various tools used in Design Methods																						
CLR-3 :	Acquaint students with material selection and design strategies																						
CLR-4 :	Familiarize the students with the Engineering statistics and reliability in design																						
CLR-5 :	Give insights into legal and ethical issues in Designing and to various tools involved in Quality Engineering																						
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																					
CLO-1 :	Describe various design processes			1	85	80	H	-	H	L	L	L	L	-	M	M	L	M	M	M	M	L	
CLO-2 :	Demonstrate various tools used in Design Methods			2	80	75	H	H	H	M	M	L	M	-	M	M	-	M	M	M	M	H	
CLO-3 :	Understand the process of material selection and can interpret various techniques involved in Design			1,2	85	80	H	M	H	M	M	M	M	L	M	M	M	M	H	M	M	H	
CLO-4 :	Implement various Engineering statistics methods in design			2	80	75	H	H	H	H	M	L	L	L	M	M	-	M	M	M	M	H	
CLO-5 :	Understand the legal and ethical issues in Designing and apply various tools used in Quality Engineering			1,2	85	80	H	M	H	M	M	H	H	H	M	M	L	M	M	M	M	H	

		Design Process	Design Methods	Material Selection Processing and Design	Engineering Statistics and Reliability	Legal and Ethical Issues in Design and Quality Engineering
Duration (hour)		9	9	9	9	9
S-1	SLO-1	The Design Process	Creativity and Problem Solving, Product Design Specifications	Material Selection Process	Introduction to statistics and Reliability	Introduction to Ethics
	SLO-2	Morphology of Design, Design Drawings	Conceptual Design	Economics, Cost vs Performance		The Origin Of Laws
S-2	SLO-1	Computer Aided Engineering, Designing of Standards	Decision Theory, Decision Tree	Weighted Property Index	Probability	Contracts
	SLO-2	Concurrent Engineering	Embodiment Design	Value Analysis, Role of Processing in Design		Liability
S-3	SLO-1	Product Life Cycle	Detail Design, Mathematical Modeling	Classification of Manufacturing Process	Distributions	Tort Law
	SLO-2	Technological Forecasting				Product Liability
S-4	SLO-1	Market Identification	Simulation, Geometric Modeling	Design for Manufacture	Test Of Hypothesis	Protecting Intellectual Property
	SLO-2					
S-5	SLO-1	Competition Bench Marking	Finite Element Modeling	Design for Assembly	Design Of Experiments	Legal and Ethical Domains
	SLO-2					Codes of Ethics
S-6	SLO-1	Systems Engineering	Optimization, Search Methods	Designing for Castings, Forging	Reliability Theory	Solving Ethical Conflicts
	SLO-2					
S-7	SLO-1	Life Cycle Engineering	Geometric Programming	Designing for Metal Forming, Machining and Welding	Design for Reliability	Total Quality Concept, – Quality Assurance
	SLO-2					Statistics Process Control
S-8	SLO-1	Human Factors in Design	Structural Optimization	Residual Stresses	Reliability Centered Maintenance	Taguchi Methods
	SLO-2					Robust Design
S-9	SLO-1	Industrial Design	Shape Optimization	Fatigue, Fracture and Failure	Tutorial	Failure Mode Effect Analysis
	SLO-2					

Learning Resources	1. Dieter, George E., Engineering Design - "A Materials and Processing Approach", McGraw Hill International Editions, Singapore, 4th Edition, 2008 2. Karl T. Ulrich and Steven D. Eppinger "Product Design and Development" McGraw Hill Edition 6th edition 2015	3. Pahl, G, and Beitz, W., "Engineering Design: A Systematic Approach", Springer London, 2014 4. Ray, M.S., "Elements of Engg. Design", Prentice Hall Inc. 1985. 5. Suh, N.P., "The principles of Design", Oxford University Press, NY.1990.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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2.Mr.Prasad MP AGNITO INSIGHTS, prasad@agnito.in	2. Dr. V. Uma Maheshwar, Osmania University mahesh.v@uceou.edu ,	2. Mr. R. Ganesh, SRMIST, ganeshr@srmist.edu.in

Course Code	18AUE345T	Course Name	RAPID PROTOTYPING AND TOOLING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Understand and use techniques for processing of CAD models for rapid prototyping.	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Understand and apply fundamentals of rapid prototyping techniques.		
CLR-3 :	Use appropriate tooling for rapid prototyping process.		
CLR-4 :	Use rapid prototyping techniques for reverse engineering.		
CLR-5 :	Examine the cases relevant to mass customization and some of the important research challenges associated with AM and its data processing tools		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	
CLO-1 :	Understand history, concepts and terminology of additive manufacturing	2 95 93	H L L H L L M L H L H H H M H
CLO-2 :	Apply the reverse engineering concepts for design development	2 98 96	H L L L H L L M L H L H H H M H
CLO-3 :	Understand the variety of additive manufacturing techniques	2 96 95	H L L L H L L M L H L H H H M H
CLO-4 :	Design and develop newer tooling models	2 98 97	H L L L H L L M L H L H H H M H
CLO-5 :	Analyse the cases relevant to mass customization and some of the important research challenges associated with AM and its data processing tools	2 94 91	H L L L H L L M L H L H H H M H

	Introduction to Rapid Prototyping	Liquid Based Additive Manufacturing System	Solid Based Additive Manufacturing System	Powder Based Additive Manufacturing System	Additive Manufacturing Application And Case Studies
Duration (hour)	9	9	9	9	9
S-1	SLO-1 SLO-2	Overview of subtraction and additive manufacturing History	Methods in liquid based process and material used for fabrication	Introduction to solid based additive Manufacturing system	Methods in powder based process
S-2	SLO-1 SLO-2	Need-Classification of additive manufacturing	Stereo lithography Apparatus (SLA)-	Methods in solid based process and	and material used for fabrication
S-3	SLO-1 SLO-2	Need-Classification of additive manufacturing	Principle, process,	material used for fabrication	Selective Laser Sintering
S-4	SLO-1 SLO-2	The cost and effects of design changes during conceptual modeling, detail designing, prototyping,	advantages, disadvantages and limitations	fused deposition modeling(FDM)- introduction	Principles of SLS-process
S-5	SLO-1 SLO-2	manufacturing and product release	Digital light processing -introduction	fused deposition modeling(FDM)- principle	Process, advantages and
S-6	SLO-1 SLO-2	Reverse Engineering	Digital light processing principle	Process	Applications
S-7	SLO-1 SLO-2	Bench marking	Advantages and dis advantages	Limitation Limitations	Principles of SLS process
S-8	SLO-1 SLO-2	3D scanning, 3D digitizing and Data fitting	Limitations	Multi jet modelling- Principle	Process, advantages and applications
S-9	SLO-1 SLO-2	CAD for RPT: CAD model preparation	Solid ground curing introduction	process, advantages,	Selective heat sintering
S-10	SLO-1 SLO-2	Part Orientation and support generation	Solid ground curing principle	disadvantages and limitations	Laser Engineered Net Shaping (LENS) -,
S-11	SLO-1 SLO-2	Model Slicing –Tool path Generation	Process	Laminated object modeling (LOM)- Principle, process,	Principle, process, advantages
S-12	SLO-1 SLO-2	Materials for Additive Manufacturing Technology	Advantages and dis advantages	advantages, disadvantages and limitations	disadvantages and limitations

S-8	SLO-1	And its classification based on materials	Limitations		Three Dimensional Printing - Principle, process,	Application of RP in Art and jewelry
	SLO-2	RPT and its role in modern manufacturing mechanical design	Continuous Liquid Interface Production	Electron-beam freeform fabrication	advantages and applications-	Challenges in implementation of RP techniques
S-9	SLO-1	-Economics of RP techniques	Shape deposition modelling	Case studies	Electron Beam Melting- Principle, process,	Case Studies
	SLO-2		Ballistic Particle Manufacturing(BPM)		advantages, disadvantages and limitations	

Learning Resources	1. Chua, C.K., Leong K.F. and Lim C.S., "Rapid prototyping: Principles and applications", second edition, World Scientific Publishers, 2010.	3. Gibson, I., Rosen, D.W. and Stucker, B., "Additive Manufacturing Methodologies: Rapid Prototyping to Direct Digital Manufacturing", Springer, 2010.
	2. Gebhardt, A., "Rapid prototyping", Hanser Gardener Publications, 2003.	4. Hilton, P.D. and Jacobs, P.F., Rapid Tooling: Technologies and Industrial Applications, CRC press, 2005.

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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2.Mr.Ajeesh Varghese Halla, Ajeeshvarghese@halla.com	2.Dr.K Prabu VIT, Prabu.k@vit.ac.in	2.Mr.S.Devanand,SRMIST, devanans@srmist.edu.in

Course Code	18AUE346T	Course Name	MODELING AND CONTROL OF VIBRATION IN MECHANICAL SYSTEMS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Impart knowledge on fundamentals of vibrations				Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Know the concept of two degree of freedom systems and continuous systems																							
CLR-3 :	Analyze different methods of modeling multi degree of freedom systems																							
CLR-4 :	Understand the concept of Vibration control techniques																							
CLR-5 :	Gain knowledge on vibration measurement devices																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			Expected Proficiency (%)	90	85	Expected Attainment (%)	Problem Analysis	H	M	H	H	M	L	L	Ethics	Individual & Team Work	Communication	Project Mgt & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Understand the fundamentals of vibration and single degree of freedom system																							
CLO-2 :	Implement two degree of freedom systems in any application																							
CLO-3 :	Classify the different modeling methods in multi degree of freedom systems																							
CLO-4 :	Interpret different vibration control techniques																							
CLO-5 :	Implement the vibration measurement devices in real time application																							

		Fundamentals of vibration and Modelling SDOF systems	Two degree of freedom systems and continuous systems	Modelling of Multi-DegreeofFreedom Systems	Vibration control	Vibration measurement and applications
Duration (hour)		9	9	9	9	9
S-1	SLO-1 SLO-2	Concept of vibration	Two DOF	Multi Degree Freedom System	Introduction to vibration control	Transducers
S-2	SLO-1	Classification of vibration	Modelling of Two Degree of freedom systems	Modeling of Continuous Systems as Multi-degreeofFreedom Systems	Specification of Vibration Limits	Transducers types and applications
	SLO-2	Vibration analysis procedure and elements	Modelling of Two Degree of freedom systems	Influence Coefficients	Static and dynamic balancing	Vibration pickups
S-3	SLO-1	Harmonic and periodic motions, vibration terminology	Free Vibration Analysis of an Undamped System	stiffness coefficients	Balancing of Rotating Machines	Vibrometer
	SLO-2	Modelling of single degree of freedom systems	Free Vibration Analysis of dampedSystem	Flexibility and inertia influence coefficients	Field balancing	Accelerometer
S-4	SLO-1	Vibration model, Equation of motion-Natural Frequency	Equations of Motion for ForcedVibration	Flexibility Matrixand Stiffness Matrix	Whirling of Rotating Shafts	Velometer
	SLO-2	Energy method, Rayleigh method	Forced Vibration with HarmonicExcitation System	Flexibility Matrixand Stiffness Matrix	Critical Speeds, Stability Analysis	Phase Distortion
S-5	SLO-1	Principle of virtual work,	Forced Vibration with HarmonicExcitation System	Eigen Values and Eigen Vectors	Balancing of Reciprocating Engines	Frequency-Measuring Instruments
	SLO-2	Damping models.	Coordinate Couplings and Principal Coordinates	Eigen Values and Eigen Vectors	Control of Natural Frequencies	Vibration Exciters
S-6	SLO-1	Viscously damped free vibration	Vibration of continuous systems	Matrix Iteration Method	Vibration Isolation	Signal Analysis
	SLO-2	Special cases: oscillatory, non-oscillatory and critically damped motions.	Vibrating string	ApproximateMethods	Vibration Isolation methods	Dynamic Testing of Machines and Structures
S-7	SLO-1	Logarithmic decrement, Experimental determination of damping coefficient.	Longitudinal vibration of rods	Dunkerley, Rayleigh's, and Holzer Method	Vibration Absorbers	Experimental Modal Analysis
	SLO-2	Forced harmonic vibration, Magnification factor.	Torsional vibration of rods	Geared Systems	Dynamic vibration absorbers	Measurement of Mode Shapes

S-8	SLO-1	Rotor unbalance, Transmissibility	Vibration of suspension bridges	Eigen Values & Eigenvectors for large system of equations using sub space	torsional and pendulum type absorbers	Machine Condition Monitoring and Diagnosis
	SLO-2	Vibration Isolation	Euler equation for beams	Solving problems	Damped vibration absorbers	Machine Condition Monitoring and Diagnosis
S-9	SLO-1	Equivalent viscous damping, Sharpness of resonance.	Cycle test 2	Cycle test 2	Cycle test 3	Cycle test 3
	SLO-2	Cycle test 1	cycle test 2	cycle test 2	Cycle test 3	Cycle test 3

Learning Resources	1. Ramamurti. V, "Mechanical Vibration Practice with Basic Theory", Narosa, New Delhi, 2010	3. S. Graham Kelly & Shashidar K. Kudari, "Mechanical Vibrations", Tata McGraw-Hill Publishing Com. Ltd New Delhi, 2007
	2. Rao, S.S., "Mechanical Vibrations," Addison Wesley Longman, 6 th Edition 2018.	4. Thomson, W.T. – "Theory of Vibration with Applications", CBS Publishers and Distributors, New Delhi, 2006

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
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Course Code	18AUE441T	Course Name	OPTIMIZATION TECHNIQUES IN ENGINEERING DESIGN	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18MAB202T	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards			

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Familiarize Unconstrained Optimization Techniques				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2 :	Familiarize Constrained Optimization Techniques				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3		
CLR-3 :	Illustrate the Bio-inspired Optimization Techniques							H	M	M	H	M	M	H	M	M	M	M	H	H	H	H	H	
CLR-4 :	Give insights into Fuzzy logic and Neural networks							H	H	H	M	L	M	M	M	M	M	M	M	H	H	H	H	H
CLR-5 :	Acquaint students with optimization in Static and Dynamic Applications							H	H	H	H	L	M	M	M	M	M	M	H	M	H	H	H	H
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1 :	Correlate single and multivariable optimization				1	80	75	H	M	M	M	H	M	M	H	M	M	H	H	H	H	H		
CLO-2 :	Apply the direct and indirect methods for constrained optimization problem				2	85	80	H	H	H	M	L	M	M	M	M	M	H	H	H	H	H		
CLO-3 :	Solve Multi objective optimization problems				3	85	80	H	H	H	H	L	M	M	M	M	M	H	H	H	H	H		
CLO-4 :	Develop the Fuzzy logic and Neural networks				3	80	75	H	H	H	H	L	M	M	M	M	M	M	H	H	H	H		
CLO-5 :	Apply optimization techniques in Static and Dynamic Applications				3	85	80	H	H	H	H	L	M	M	M	M	H	M	H	H	H	H		

Duration (hour)	Unconstrained Optimization Techniques	Constrained Optimization Techniques I	Advanced Optimization Techniques	Fuzzy logic and Neural networks	Static and Dynamic Applications
	9	9	9	9	9
S-1	SLO-1 SLO-2 Unconstrained Optimization	Constrained Optimization	Advanced Optimization	Fuzzy logic and Neural networks	Static and Dynamic Applications
S-2	SLO-1 SLO-2 Classification of optimization problems	Optimization with equality constraints	Multi stage optimization – dynamic programming	Fuzzy Set Theory	Structural Design applications
S-3	SLO-1 SLO-2 General principles of optimization	Optimization with inequality constraints	Multi stage optimization –stochastic programming	Optimization of Fuzzy Systems	Design and optimization of shafts
S-4	SLO-1 SLO-2 Problem formulation	Introduction to Direct methods	Multi objective optimization	Computational Procedure and Numerical Results	Design and optimization of springs
S-5	SLO-1 SLO-2 Single variable optimization	Introduction to Indirect methods	Genetic algorithms	Demonstration of Fuzzy logic using Matlab	Introduction to Dynamic Applications
S-6	SLO-1 SLO-2 Multivariable optimization	Indirect methods using penalty functions	Simulated Annealing algorithm	Introduction to Neural networks	Optimum design of single, two degree of freedom systems
S-7	SLO-1 SLO-2 Techniques of unconstrained minimization	Indirect methods using Lagrange multipliers	Problems on Genetic algorithms and Simulated Annealing algorithm	Neural-Network-Based Optimization	Optimum design of vibration absorbers
S-8	SLO-1 SLO-2 Search methods	Geometric programming	Ant colony Optimization	Feedforward networks for Classification and Regression	Application of optimization in Mechanisms
S-9	SLO-1 SLO-2 Interpolation methods	Problems on Geometric programming	Particle Swarm Optimization	Demonstration of Neural network using Matlab	Optimum design of simple linkage mechanisms

Learning Resources	1. S. Singaresu Rao, "Engineering Optimization – Theory & Practice", New Age International (P) Limited, New Delhi, 2016.	3. Kalyanamoy Deb, "Optimization for Engineering design algorithms and Examples", Prentice Hall of India Pvt. 2012.
	2. D.K. Pratihar Narosa, "Soft Computing: Fundamentals and Applications", Publishing House, New-Delhi, 2014	4. Goldberg, D.E., "Genetic algorithms in search, optimization and machine", Barmen, Addison- Wesley, New York, 2008.

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
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Course Code	18AUE442T	Course Name	MULTIBODY DYNAMICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18MAB202T	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Understand the basics of multibody systems	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Analyze kinematic parameters of multibody systems using computational approach	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Solve for dynamics of multibody systems using computational approach	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Model simple mechanisms and write its constraint equations	Expected Attainment (%)	Design & Development
CLR-5 :	Simulate planar and spatial mechanisms using standard MBD package		Analysis, Design, Research
			Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	formulate a model and free body diagram of multibody systems	1 80 70	H H H H L L L M L M L H H M M
CLO-2 :	derive the equations of motion of a multibody system	2 80 70	H H H H L L L M L M L H H M M
CLO-3 :	incorporate constraints into a multibody system	2 80 70	H H H H L L L M L M L H H M M
CLO-4 :	simulate the motion of a multibody system with a computer	3 90 80	H H H H H L L M L M L H H M M
CLO-5 :	interpret and analyze the results of simulation	3 90 80	H H H H H L L M L M L H H M M

	Multibody Systems Introduction	Kinemaic and Dynamic Analysis	Kinematics of Mechanical Systems	Constrained Kinematics	Applications to Simple Mechanisms
Duration (hour)	9	9	9	9	9
S-1	SLO-1 SLO-2	Classical approach	Position analysis	Mechanical joints	Kinematics of a point moving on a rigid body
S-2	SLO-1 SLO-2	Emergence of computational dynamics	Velocity analysis	Constraint equation for planar joints	Constrained kinematics
S-3	SLO-1 SLO-2	Rigid / flexible multibody systems	Acceleration analysis	Constraint equation for planar joints	Computer algorithm
S-4	SLO-1 SLO-2	Degrees of freedom	Two DOF robot manipulator –kinematic analysis	Constraint equation for spatial joints	Absolute co-ordinates
S-5	SLO-1 SLO-2	Constrained / unconstrained motion	Two DOF robot manipulator –kinematic analysis	Constraint equation for spatial joints	Driving co-ordinates
S-6	SLO-1 SLO-2	Mechanical joints overview	Classical Versus computational approach	Mobility criteria	Formulation of joint constraints
S-7	SLO-1 SLO-2	Prismatic joint	General purpose computer program	Numerical –slider crank mechanism	Ground constraints
S-8	SLO-1 SLO-2	Revolute joint	Force analysis overview	Co-ordinate transformation	Revolute and prismatic joint
S-9	SLO-1 SLO-2	Cylindrical joint	Inertia forces	Co-ordinate transformation	Application to two DOF system
S-10	SLO-1 SLO-2	Spherical joint	Joint forces	Rigid body displacement	Constraint equations for cams and followers
S-11	SLO-1 SLO-2	Higher pairs	External forces	Position equations	Constraint equations for gears
S-12	SLO-1 SLO-2	Cam and gear systems	Principle of virtual work	Velocity equations	Computational methods in kinematics
S-13	SLO-1 SLO-2	Four bar mechanism	Use of redundant system	Acceleration equations	Kinematically driven systems
S-14	SLO-1 SLO-2	Slider crank mechanism	Forward dynamics	Slider crank mechanism	Velocity analysis
S-15	SLO-1 SLO-2	Closed chain systems	Inverse dynamics	Offset slider crank mechanism	Computer implementation to simple four bar mechanism
S-16	SLO-1 SLO-2	Open chain systems	Planar dynamics	Singular configuration	Computer implementation to simple four bar mechanism
S-17	SLO-1 SLO-2	Robotic manipulators	Spatial dynamics	Four bar mechanism	Numerical based on four bar mechanism

Learning Resources	1. Ahmed A Shabana., "Computational Dynamics ", third edition, Wiley & Sons	3. Kinematic and dynamic simulation of multibody systems, first edition Garcia De Jalon 4. Dynamics of multibody systems by Ahmed A Shabana, third edition
	2. Fundamentals of multibody dynamics : theory and applications, first edition, FaridAmirouche	

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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2. Mr.V.Raja Raman Altair rajarav@asiapac.altair.com	2. Dr. R Kannan, PSNA Kannanjothy@gmail.com	2. Mr.S.SenthilKumar, SRMIST senthils6@srmist.edu.in

Course Code	18AUE443T	Course Name	FINITE ELEMENT ANALYSIS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18MEC106T	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:				Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Predict how a product reacts to real-world forces, vibration, heat, fluid flow, and other physical effects					1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Model any physical system in to a finite element model and solve for its field variables					Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Solve real world complex problems which cannot be solved by analytical methods																						
CLR-4 :	Practice few commercial standard packages in solving complex problems																						
CLR-5 :	Understand the basics of multibody systems																						
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																					
CLO-1 :	Apply finite element technique to Engineering problems					2	80	70	H	H	M	H	H	M	M	H	M	M	L	M	H	M	M
CLO-2 :	Improve their ability in solving differential equations for real world problems					2	70	60	H	H	H	M	H	M	M	H	M	M	L	M	H	M	M
CLO-3 :	Equip themselves familiar with multi-domain phenomenon like thermo-structural problems					1	80	70	M	H	H	H	H	M	M	H	M	M	L	M	H	M	M
CLO-4 :	Familiarize themselves with the applications of finite element method & FEA packages					3	90	90	M	H	H	M	H	M	M	H	M	M	L	M	H	M	M
CLO-5 :	Solve kinematic and dynamic problems of multibody systems					2	70	60	H	M	M	M	H	M	M	H	M	M	L	M	H	M	M

Duration (hour)	History and basics of FEA		One dimensional Problems	Two dimensional Problems	Multidomain Problems	Applications of FEA
	9		9	9	9	9
S-1	SLO-1	Comparison Of FEA With Exact Solutions	Elements and node numbering	Two dimensional elements	Vibration analysis introduction	Introduction and basics
S-2	SLO-1	Methods of engineering analysis	Global and local co-ordinates	Plane stress formulation	Vibration analysis introduction	Roll cage analysis
	SLO-2	Numerical methods	Natural co-ordinates	Plane strain formulation	Modal analysis of a structure	Roll cage analysis
S-3	SLO-1	Types of finite elements	Polynomial functions	CST element	Modal analysis of a structure	Rotor thermal analysis
	SLO-2	Displacement or shape function	Displacement function for 1D bar element	Shape function derivation for CST element	fluid flow problems	Rotor thermal analysis
S-4	SLO-1	Material behavior	General stiffness matrix derivation	Strain displacement matrix for CST element	fluid flow problems	Hub analysis
	SLO-2	Stiffness matrix	Stiffness matrix for 1D bar element	Stress strain matrix for CST element	fluid flow problems	Knuckle analysis
S-5	SLO-1	Steps involved in FEA –preprocessing and solution	Assembly of stiffness matrix	Stiffness matrix derivation for CST element	Heat transfer problems	Brake pedal analysis
	SLO-2	Post processing	Force vector	Temperature effects	Heat transfer problems	Brake pedal analysis
S-6	SLO-1	2D and 3D stress element	Spring element	LST element	Heat transfer problems	Bump analysis
	SLO-2	Strain-displacement relationships	Stiffness matrix for spring element	QST element	Heat transfer problems	Bump analysis
S-7	SLO-1	Discretization methods	Boundary conditions	Axi –symmetric formulation	Thermo structural analysis	Multibodydynamics applications
	SLO-2	Discretization process	Imposing boundary conditions to bar element	Isoparametric formulation	Thermo structural analysis	Forward and Inverse dynamics
S-8	SLO-1	Rayleigh ritz method	Beam element	Iso, sub. Super parametric element formulation	Thermo structural analysis	Planar dynamics
	SLO-2	Galerkin method	Stiffness matrix derivation of beam element	Four noded quadrilateral element	Thermo structural analysis	Spatial dynamics
S-9	SLO-1	Advantages and disadvantages of FEA	Truss element	1D heat conduction problems	Introduction to biomedical and MEMS applications	Application Of MBD Technique To Four-Bar Mechanisms
	SLO-2	Applications of FEA	Stiffness matrix for truss element	Derivation of stiffness matrix	Introduction to biomedical and MEMS applications	Application Of MBD Technique Slider Crank Mechanisms

Learning Resources	1. David V. Hutton, "Fundamentals of Finite Element Analysis", Tata McGraw Hill Publishing Company Ltd., New Delhi, 2005 2. Ahmed A Shabana., "Computational Dynamics ", Wiley & Sons.third edition	3. Bhavikatti S.S., "Finite Element Analysis", New Age International Publishers, New Delhi, 2008. 4. ErdoganMadenci, Ibrahim Guven, "the finite element method and applications in engineering using ansys", Springer (India) Private Limited, New Delhi, 2011.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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2. Mr.V.Raja Raman Altair rajarav@asiapac.altair.com	2. Dr.M.Rajesh, Arbaminch institute of technology Rajesh.m@amu.edu.et	2. Mr.S.SenthilKumar, SRMIST senthils6@srmist.edu.in

Course Code	18AUE202T	Course Name	SENSORS, ACTUATORS AND SIGNAL CONDITIONERS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Define the sensors, their operations and select appropriate sensors for automotive applications	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Define and classify the actuators and select to integrate them into an overall system.	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Identify signal conditioning operations and devices																		
CLR-4 :	Evaluate and analyze the sensors signals																		
CLR-5 :	Compare the input signals and select appropriate data conversion methods.																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Acquire the knowledge of construction and operation of sensors and its applications in automobiles	1,2	90	85	H	M	L	L	L	L	M	L	M	M	L	H	H	M	L
CLO-2 :	Understand the basics of actuators and its operations	1,2	90	85	H	H	M	H	M	M	M	L	M	L	L	H	H	M	L
CLO-3 :	Know the fundamentals of signals conditioning and devices and its operation	2	90	85	H	H	M	H	M	M	M	L	M	L	L	M	H	M	L
CLO-4 :	Applications of operational amplifier and its applications	3	85	80	H	H	M	H	M	M	M	L	M	L	L	M	H	M	L
CLO-5 :	Learn and implement the basics of data conversion devices	2	85	80	H	H	M	H	M	M	M	L	M	L	L	H	H	M	L

		Automotive Sensors	Automotive Actuators	Introduction To Op-Amp	Operational Amplifier Applications	Waveform Generators, A/D And D/A Convertors
Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction to sensors	Basics of actuators and its principles of operations.	Introduction – Signal conditioning operations.	Applications of operational amplifiers	Comparator introduction
	SLO-2	Variables to be measured for automotive Engine control applications	Variables to be controlled for automotive Engine control applications.	Basics of operational amplifier	Basics of Instrumentation amplifiers	Comparator Applications
S-2	SLO-1	Airflow Rate Sensor – Construction and operations	Pulse width Modulated signal	Ideal operational amplifier Introduction	Operational amplifier using diodes- Half wave	Regenerative Comparator Introduction
	SLO-2	Pressure Measurement – Strain Gauge and MAP sensor	H-bridge device for speed and direction control.	Ideal operational amplifier characteristics	Full wave rectifiers	Square Wave Generator
S-3	SLO-1	Engine Crank Position sensor - -Magnetic reluctance,	Electric motor actuator - DC motor, Brushless DC Motor	Operational amplifier- open and closed loop	Precision diodes	Astable Multivibrator
	SLO-2	Hall effect sensor Construction and Operation	Stepper Motor mechanism	Operational amplifier- Inverting, Non-Inverting amplifier.	Sample and Hold circuits	Monostable Multivibrator
S-4	SLO-1	Optical crank position Construction and Operation	Servomechanism	Voltage follower	Voltage to Current converters	Bistable Multivibrator
	SLO-2	Throttle angle sensor construction and operations.	Engine control actuators -Fuel injector	Differential amplifier	Current to Voltage converters	Introduction to Analog to Digital Converters
S-5	SLO-1	Temperature Sensor construction and operations and types.	Ignition coil operation	Difference mode gain	Applications of operational amplifiers as Adder	Types of Analog to Digital Converters
	SLO-2	Sensors for Engine feedback control - EGO sensor, EGO characteristics	EGR Actuator operation	Common mode gain	Applications of operational amplifiers as Subtractor	Direct Type ADC – Flash Type
S-6	SLO-1	White Band Lambda sensor	Electric actuators- Introduction.	Common Mode Rejection Ratio	Applications of operational amplifiers as Multiplier	Direct Type ADC – Successive approximation type
	SLO-2	Magnetostrictive principle and Knock sensor	Relays – Construction and Operation	Operation amplifier internal circuit	Applications of operational amplifiers as divider	Numerical Examples for ADC

S-7	SLO-1	Oil Pressure sensors	Reed switches - Construction and Operation	DC characteristics of operational amplifier	Applications of operational amplifiers as Differentiator	Basics of Digital to Analog Conversion Techniques
	SLO-2	Accelerometer construction and operations	Actuators applications	IC 741 internal circuit Introduction	Applications of operational amplifiers as Integrator	R-2R Ladder DAC
S-8	SLO-1	Gyro sensors construction and operations	Electric Power Assisted Steering	IC 741 Operations	Instrumentation amplifier application	Inverted R-2R Ladder DAC
	SLO-2	Inertial measurement unit	Rain sensing wipers	Filters – Introduction	Instrumentation amplifier application. Cont	Weighted Resistor type DAC
S-9	SLO-1	Sensors for climate control	Motorized seat position control	High pass and low pass Filter	Voltage comparator	Numerical Examples for weighted resistor
	SLO-2	Switches and Knobs	Power Window application	Band pass Filter	Peak detector	Numerical Examples for R-2R and Inverted R-2R

Learning Resources	1. William. B. Ribbens, "Understanding Automotive Electronics" 8th Edition Butterworth-Heinemann publications, 2017. 2. Ronald. K. Jurgan "Automotive Electronics Handbook", 2nd Edition, McGraw-Hill, Inc 1999 3. Robert F. Coughlin, Frederick F. Driscoll, "Operational Amplifiers and Linear Integrated Circuits", 6th Edition, PHI, 2000.	4. D.Roy Choudhry, Shail Jain, "Linear Integrated Circuits", New Age International Pvt. Ltd., 2000 5. Sergio Franco, "Design with Operational Amplifiers and Analog Integrated Circuits", 3rd Edition, Tata Mc Graw-Hill, 2007.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.Jegan Amirthalingam, Senior Educator, KPIT a.jegan@kpit.com	1. Mr. Sam Jebakumar, SRM IST, jebakumj@srmist.edu.in	1. Mr. N Ganesh Kumar, SRMIST
2. Mr.G.Giri Atalon giri@atalon.co.in		2. Mr.Jesu Godwin D, SRMIST

Course Code	18AUE351T	Course Name	AUXILIARY VEHICLE SYSTEMS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18AUC302J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Recognize the vehicle motion control and stabilization system	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Identify the importance of Driver assistance, security and warning system	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Build the knowledge of Safety and comfort system				H	H	H	H	L	L	L	L	H	L	L	L	H	M	H
CLR-4 :	Understand the auxiliary systems of chassis.				H	H	H	M	L	L	L	H	H	L	L	L	H	M	H
CLR-5 :	Assess the automotive Safety System				H	M	H	H	L	L	L	L	H	L	L	L	H	M	H
CLO-1 :	Understand the vehicle motion control and stabilization system	2	85	80	H	H	H	M	L	L	L	H	H	L	L	L	H	M	H
CLO-2 :	Know the importance of Driver assistance, security and warning system	2	85	80	H	H	H	M	L	L	L	H	H	L	L	L	H	M	H
CLO-3 :	Know the working of the compartment while moving of the vehicle, about the collapsible steering and tillable steering column, about the collision avoidance system, front and rear Object detection.	2	85	80	H	H	H	M	L	L	L	H	H	L	L	L	H	M	H
CLO-4 :	Understand the auxiliary systems of chassis.	2	85	80	H	M	H	H	L	L	L	L	H	L	L	L	H	M	H
CLO-5 :	Know the various types of safety aspects such as active and passive safety, the active safety components and the working passive safety components such as air bags, seat belts	2	85	80	H	H	H	H	L	L	L	H	H	L	L	L	H	M	H

		Vehicle Motion Control and Stabilization System	Information, Security and Warning System	Comfort Systems	Chassis Auxiliary System	Safety System
Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction	Vehicle integration	Heating, Ventilation	Needs for Auxiliary systems	Seat belt, Seat belt tightener system and importance.
	SLO-2	Introduction	Vehicle integration	Heating, Ventilation	Needs for Auxiliary systems	Seat belt, Seat belt tightener system and importance.
S-2	SLO-1	Antilock braking system,	And navigation system	And Air Conditioning Systems	Power Assisted Steering System	Collapsible Steering Column,
	SLO-2	Stability Control	Looking out sensors	Principles and working	Working principle	Air Bags Deployment System
S-3	SLO-1	Adaptive cruise control	And Looking in sensors,	Electronic Outside Rear View Mirror (OVRM)	Regenerative Braking System	Designing aspects of automotive bumpers
	SLO-2	Lane Keep Assist System	Intelligent vision system,	Rain Sensing Wiper System	Principle and operation	Designing aspects of automotive bumpers
S-4	SLO-1	Collision Warning	Vehicle Integration system.	Environment Information System	Servo Brake	Materials for bumpers.
	SLO-2	avoidance system,	Global Positioning System.	Tilt Able Steering Wheel,	Servo Brake	Materials for bumpers.
S-5	SLO-1	Blind Spot Detection system,	Vehicle Navigation System.	Garage Door Opening System	Vehicle Retarders	Steering and mirror adjustment,
	SLO-2	Blind Spot Detection system,	Road Network	Automatic Climate Control	Electrical retarders	Frontal Object Detection
S-6	SLO-1	Driver alertness detection system	Onboard Diagnosis System	Adaptive Head Light	Hydrodynamic retarders	Rear Vehicle Object Detection System
	SLO-2	Driver alertness detection system	Immobilizer	Night Vision Assist,	Advantages of retarders	Anti-roll bar
S-7	SLO-1	Electronic Transmission Control System	Anti-Theft Alarm System	Traffic Jam Assist	Hydro Elastic Suspension System	Emergency Brake Assist,
	SLO-2	Working principle	Voice Warning System	Hill Start Assist	Hydro Elastic Suspension System	Emergency Response
S-8	SLO-1	Electronic Brake Force Distribution System	Keyless Entry System	Need for Active suspension	Rubber Suspension	Child Lock System
	SLO-2	Electronic Brake Force Distribution System	Central Locking System	Need for Active suspension	Pneumatic Suspension	Child Lock System
S-9	SLO-1	Tutorial	Tire Pressure Monitoring System	Construction of active suspension	Drive By Wire System	Central locking system
	SLO-2	Tutorial	Tire Pressure Monitoring System	Working of active suspension	Brake by wire	Central locking system

Learning Resources	1. William B. Ribbens, "Understanding Automotive Electronics", 6th Edition, Newnes, 2003.	4. Dr. Kirpal Singh, "Automobile Engineering" Volume – 1, 12th Edition, Standard Publishers 5. BOSCH, Automotive Handbook, 6th Edition, Bentley publishers 6. Robert Bosch GmbH -"Safety, Comfort and Convenience Systems"-Wiley; 3rd edition, 2007
	2. Robert N Brady "Automotive computers and Digital Instrumentation". A Reston Book, Prentice Hill, Eagle Wood Cliffs, New Jersey, 1988.	
	3. Ronald.K.Jurgen-"Automotive Electronics Handbook"-Second edition- McGraw -Hill Inc., -1999.	

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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2. Mr.SureshMekalathuru, WABCO India limited, sureshme305@gmail.com	2. Dr.S.Ramkumar, Vel Tech, drsramkumar@veltech.edu.	2. Dr. Edwin Geo V, SRMIST

Course Code	18AUE352T	Course Name	TWO AND THREE WHEELER TECHNOLOGY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Impart knowledge on power plant and different systems in two wheelers	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Know the arrangement of chassis in two wheelers and subsystems like transmission and suspension	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Identify different brakes used in two wheelers and construction of wheels and tires				H	M	H	H	H	M	M	L	M	M	L	M	H	H	H
CLR-4 :	Understand Servicing, maintenance and troubleshooting techniques particularly for two wheelers				H	M	H	H	H	L	L	L	M	M	L	M	H	H	H
CLR-5 :	Gain knowledge on different types of three wheelers, pickup and delivery vans arrangements				H	M	H	H	H	L	L	L	M	M	L	L	H	H	H
					H	H	H	H	M	L	L	L	M	M	L	M	H	H	H
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)															
CLO-1 :	Classify the different power plants and systems arrangement of petrol and electric vehicles	1,2	90	85															
CLO-2 :	Distinguish chassis and transmission systems arrangements in two wheelers	1,2	90	85															
CLO-3 :	Classify different brakes and tires used in two wheelers and their applications	1,2	90	80															
CLO-4 :	Gain knowledge on different servicing and troubleshooting techniques and case studies of two wheelers	1,2	80	75															
CLO-5 :	Infer different types of three wheeler arrangements for different applications and case studies on recent models	1,2	90	85															

		Power plant	Chassis and sub systems	Brakes and wheels	Servicing, Maintenance, Trouble Shooting and Case Study of Major Indian Models	Three wheelers
Duration (hour)		9	9	9	9	9
S-1	SLO-1	Power plant components	Chassis and sub systems-components	Brakes-introduction	Servicing-Introduction	Three wheelers-types
	SLO-2	Two stroke and four stroke SI engines - merits and demerits	Types of main frames.	Braking systems	Service procedure for two wheelers	Case study of Indian models
S-2	SLO-1	Symmetrical and unsymmetrical port timing diagram	Drive from engine to rear wheel	Drum brakes-principle, construction and working	Service procedure for two wheelers	Case study of Indian models
	SLO-2	Valve timing diagram.	chain drive – shaft drive	Disc brakes-principle, construction and working	Petrol engine tune up	Front engine auto rickshaws
S-3	SLO-1	Types of scavenging processes – merits and demerits.	Clutch requirements	Brake links layout – for front wheels – for rear wheels	Petrol engine tune up	Front engine auto rickshaws
	SLO-2	Scavenging efficiency, scavenging pumps	Single plate – multiple plates – centrifugal clutch.	Brake adjustment	Petrol engine tune up	Rear engine auto rickshaws
S-4	SLO-1	Fuel systems	Transmission (gear box)	Need of ABS for two wheelers	Preventive and scheduled maintenance in two wheelers	Rear engine auto rickshaws
	SLO-2	Carburetion, gasoline fuel injection systems. Lubrication systems.	gear controls and gear change mechanism	Single channel and dual channel ABS	Preventive and scheduled maintenance in two wheelers	Pickup vans
S-5	SLO-1	Ignition system – magneto coil spark ignition system	CVT for two wheelers	Wheels	Troubleshooting and maintenance of two-wheeler transmission	Delivery vans
	SLO-2	battery coil spark ignition system, electronic ignition system	Suspension	spokes wheel – cast wheel – disc wheel	Troubleshooting and maintenance of two-wheeler transmission	Trailers
S-6	SLO-1	Starting systems	Suspension – for front wheels	Tires	Troubleshooting of brakes and wheels	frames and transmission
	SLO-2	Kick starter and electrical systems.	Suspension – for rear wheels	Tire construction	Troubleshooting of brakes and wheels	frames and transmission
S-7	SLO-1	Electric scooter power plant	Telescopic and gas charged suspension	Tube and tubeless tires	Servicing and case study of major Indian models	wheel types
	SLO-2	Different types of batteries for electric scooters	Shock absorbers	Radial ply and cross ply tires	Servicing and case study of major Indian models	wheel mountings attachment

S-8	SLO-1	Different traction motors	Panel meters and controls on handle bar	Tubes – vulcanizing.	Case study of Electric scooters	Tyre types.
	SLO-2	Different traction motors	Panel meters and controls on handle bar	Tire requirements of electric vehicles	Case study of Electric scooters	Brake systems.
S-9	SLO-1	Tutorial	Tutorial	Tutorial	Tutorial	Tutorial
	SLO-2	Tutorial	Tutorial	Tutorial	Tutorial	Tutorial

Learning Resources	1. K.K. Ramalingam., "Two wheelers", Scitech Publications (India) Pvt. Ltd., Chennai 2012.	3. Irving, P.E., "Motor cycle Engineering"., Veloce Enterprises, Inc.2017
	2. William H crouse, "Automotive Mechanics", McGraw Hill Education; 10 edition 2017	4. Tim Gilles., "Automotive service", Delmar Cengage Learning; 4th edition edition, 2011 5. Manufacturers manual of various vehicles

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	70 %	-	60 %	-	60 %	-	50 %	-	50 %	-
	Understand										
Level 2	Apply	30 %	-	40 %	-	40 %	-	40 %	-	40 %	-
	Analyze										
Level 3	Evaluate	-	-	-	-	-	-	-	-	-	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.K.V. Simmom, Royal Enfield, kvsimmon1@royalenfield.com	1. Dr..A.Samuel Raja, Thiyagarajar college of Engineering Madurai, samuel1973@tce.edu	1. Dr.V.Edwin Geo, SRMIST
2. Mr.R.Srikanth, Altair, srikanth.r@altair.com	2. Mr. N.Ravikumar, Crescent Institute of Science and Technology, ravikumar@crescent.education	2. Mr.K.Devanathan, SRMIST

Course Code	18AUE353T	Course Name	VEHICLE PERFORMANCE AND TESTING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18AUC302J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:		Learning			Program Learning Outcomes (PLO)															
CLR-1 :	Learn about the various parameters that influence the performance of vehicles			Level of Thinking (Bloom)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Understand the engine performance characteristics and match with transmission related requirements				Expected Proficiency (%)																	
CLR-3 :	Learn about various vehicle tests conducted.				Expected Attainment (%)																	
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:						Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Determine the parameters influencing vehicle performance and predict the performance			2	90	75		M	M	H	M	M	M	M	M	L	L	L	M	H	L	H
CLO-2 :	Diagnose the various engine sub systems for improving engine performance			2	80	80		M	M	H	M	M	H	H	H	L	L	L	M	H	L	H
CLO-3 :	Analyze the performance characteristics of transmission, braking and suspension systems			3	85	80		M	H	H	H	M	M	M	M	L	L	L	M	H	L	H
CLO-4 :	Study the operational performance of vehicles			1	90	85		M	M	H	M	M	M	M	M	L	L	L	M	H	L	H
CLO-5 :	Acquire knowledge about the various vehicle testing methods			2	85	80		M	M	H	M	M	M	M	M	L	L	L	M	H	L	H

		Vehicle performance estimation and prediction	Engine performance diagnosis	Vehicle Transmission and control system performance	Operational performance	Vehicle Testing
Duration (hour)		9	9	9	9	9
S-1	SLO-1	Estimate the aerodynamic drag of road vehicles	List the reasons for engine leakage	Identify the causes of clutch slippage and drag	Restate the engine performance parameters	Review the fundamentals of acoustics
	SLO-2	List the methods of estimation of resistance to vehicle motion	Discuss the cylinder leakage test	Identify the causes of clutch vibration	Discuss the operating characteristics of engines	Discuss the human response to sound
S-2	SLO-1	List the parameters involved in calculating power required for propulsion	Determine and locate the sources of engine noise	Recall the working of automatic transmission systems	Study the operation of engine at full load conditions	Explain the testing procedure for vehicle power
	SLO-2	Calculate the power required for propulsion	Suggest the methods of reducing noise from the various sources	Analyze the performance of automatic transmission systems	Study the operation of engine at part load conditions	Explain the testing procedure for evaluating fuel consumption
S-3	SLO-1	Analyze the power plant characteristics of vehicles	Interpret engine oil issues that affect engine performance	Analyze the performance of bands	Recall the various parameters influencing fuel economy	Explain the head light alignment testing
	SLO-2	Compare the power plant characteristics with the requirements of transmission system of vehicles	Analyze the effect of temperature and its measurement on engine performance	Analyze the performance of transmission fluids	Predict the influence of various parameters influencing fuel economy	Explain the light intensity testing
S-4	SLO-1	Study about the various vehicle controls	Identify the symptoms of cooling system failure	Describe the solenoid valve testing method	Recite the various conditions of vehicle running	Explain the road testing of vehicles
	SLO-2	Sketch the different arrangements in power train configuration	Diagnose the cooling system	Describe the diagnostic procedure for testing of driveline components	Discuss the effects of vehicle conditions on fuel economy	Classify and study the different test tracks for vehicle testing
S-5	SLO-1	Calculate the vehicle acceleration and maximum speed of vehicles	Identify the weak cylinder through power balance test	Categorize the various braking arrangements	Recall the various tyre and road conditions a vehicle is subjected to	Describe the initial inspection procedure in vehicle testing
	SLO-2	Estimate the grade ability performance of vehicles	Conduct compression test and identify the reasons for power loss	Analyze the performance and characteristics of braking systems	Predict the effect of various tyre and road conditions on fuel economy	Describe the PDI procedure in vehicle testing
S-6	SLO-1	List the various drive system of vehicles	Understand valve timing test	Predict the effect of weight transfer in vehicles	List the various traffic conditions	Explain the maximum speed estimation procedure

	SLO-2	Compare the various drive systems for vehicle requirements	Understand clearance test	Diagram the various steering system arrangements	Study the effect of various traffic conditions and driving habits on fuel economy	Explain the maximum acceleration estimation procedure
S-7	SLO-1	Study the hill climbing requirements	Estimate the intake system performance	Evaluate the performance of rigid suspension system	Recall the definition of turning circle radius of a vehicle	Quote the principles of brake testing of road vehicles
	SLO-2	Characterize the vehicle power requirements for hill climbing	Estimate the exhaust system performance	Analyze the characteristics of rigid suspension system	Formulate the turning circle radius test of a vehicle	Explain the procedure of brake testing of road vehicles
S-8	SLO-1	Define ride characteristics of vehicles	Estimate the boost pressure available from a turbocharger	Evaluate the performance of independent suspension system	Describe the testing of vehicles in a two-wheeler chassis dynamometer	Review the basic concepts of vehicle handling
	SLO-2	Study the ride characteristics of vehicles on different road surfaces	Analyze the effect of waste gate on boost pressure	Analyze the characteristics of independent suspension system	Evaluate the performance of vehicles in a two-wheeler chassis dynamometer	Evaluate the handling characteristics of vehicles on different road surfaces
S-9	SLO-1	Analyze the effect of pressure and temperature on power output	List the steps in no start diagnosis	Evaluate the performance of torsion bar, stabilize and radius bars	Describe the testing of vehicles in a four-wheeler chassis dynamometer	Review the basic concepts of side slip
	SLO-2	Analyze the effect of humidity on power output	Explain the scope testing of ignition systems	Analyze the characteristics of torsion bar, stabilize and radius bars	Evaluate the performance of vehicles in a four-wheeler chassis dynamometer	Explain the side slip determination method

Learning Resources	1. Martyr A.J, Plint M.A, <i>Engine Testing Theory and Practice</i> , 3 rd edition, Butter worth-Heinemann, 2007. Butterworth - Heinemann, 2007.	3. Gousha H. M, "Engine Performance Diagnosis & Tune Up Shop Manual".
	2. Ken Pickerill, "Automotive Engineering Engine Performance Shop Manual", Cengage Learning, 2010	4. Crouse. W. H, Anglin. D. L, "Motor Vehicle Inspection", McGraw Hill, 1978. 5. Giles J. G, "Vehicle Operation & Performance".

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.K.V. Simmom, Royal Enfield, kvsimmon1@royalenfield.com	1. Dr..A.Samuel Raja, Thiagarajar college of Engineering Madurai, samuel1973@tce.edu	1. Dr. V. Edwin Geo, SRMIST
2. Mr. Palla Lokesh, Mhaindra & Mahindra, lokeshpalla@mahindra.com	2. Dr.R Sakthivel, Sri Venkateswara College of Engineering ,rsakthivel@svce.ac.in	2. Mr. A.J.D. Nanthakumar SRMIST

Course Code	18AUE354T	Course Name	TYRE TECHNOLOGY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Provide a broad overview of the basic aspects of the design, materials and operation of pneumatic vehicle tyres				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Understand the engine performance characteristics and match with transmission related requirements							Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)															
CLO-1 :	Understand tyre design processes and its testing				2	90	85	H	H	H	M	M	L	M	L	M	L	L	H	H	H	H
CLO-2 :	Know about pneumatic tyre applications in various vehicles				2	90	85	H	H	H	H	M	L	M	L	L	L	L	H	H	H	H
CLO-3 :	Understand the forces and moments acting on the vehicle.				3	90	85	H	H	H	M	H	L	H	H	L	L	L	M	M	M	M
CLO-4 :	Evaluate various tyre analysis procedure				1	90	85	H	H	H	H	H	L	M	L	L	L	L	M	M	M	M
CLO-5 :	Know the tyre measurement techniques				2	90	85	H	M	M	M	H	H	H	H	L	H	L	M	M	M	M

		Overview of tyre technology	Applications of Pneumatic Tyres	Mechanics of Pneumatic Tyres	Tyre Analysis	Tyre Measurement Techniques
Duration (hours)		9	9	9	9	9
S-1	SLO1	Types-Diagonal- belted bias- radial bias	Bicycle Tyres	Tyre Axis system	Tyre Load Capacity	Tyre component Profilometer-Thickness control
	SLO2					
S-2	SLO1	Industry Standards	Two Wheeler – Castoring Trail for Motor cycle	Rolling Resistance – Variation of Rolling resistance coefficient of bias ply and radial ply tyres with speed	TRA Formula , Basic Formula	On roll profile thickness measurement
	SLO2	Tyre components – Radial Tyre	Two Wheeler – Internal heat generation	Rolling Resistance – variation with surface textures	Constant, Pressure exponent, Section Diameter.	On roll profile thickness measurement
S-3	SLO1	Tyre Design Process	Passenger Car Tyres – Tyre ground Contact area	Rolling Resistance – Effect of Tyre diameter	Deflection Analysis:	Dimension control – length measurement
	SLO2	Tyre Design Process	Passenger Car Tyres – contact area shape	Rolling Resistance – Effect of Tractive and Braking effort	Deflection Analysis:	Dimension Control – Width measurement
S-4	SLO1	Tyre performance criteria outdoor test – Wear rate, Irregular wear	Passenger Car Tyres – distribution of ground contact Pressure	Tractive Effort and Longitudinal Slip - Behaviour of Tyre under driving torque	Deflection Analysis:	Tyre piece weight measurement
	SLO2	Tyre performance criteria outdoor test - Handling Dry,Wet and Snow	Passenger Car Tyres - deflation – effects of run – flat	Tractive Effort and Longitudinal Slip - Variation of Tractive effort with longitudinal Slip	Deflection Analysis:	Tyre colour inspection
S-5	SLO1	Tyre performance criteria outdoor test - Ride comfort	Truck Tyres Design	Tractive Effort and Longitudinal Slip - Behaviour of Tyre under braking torque	Sliding Abraration, Tyre Stiffness and Tyre wear	Tyre Geometry inspection
	SLO2	Tyre performance criteria outdoor test – Noise, Drift/Pull	Truck Tyres Design	Tractive Effort and Longitudinal Slip - Variation of braking effort with longitudinal Slip	Sliding Abraration, Tyre Stiffness and Tyre wear	Tyre Geometry Inspection
S-6	SLO1	Tyre performance criteria indoor test – High speed	Truck Tyres – Tread patterns	Cornering Properties - slip angle and cornering force	Sliding Abraration, Tyre Stiffness and Tyre wear	Tyre Mark Inspection
	SLO2	Tyre performance criteria indoor test – Endurance	Truck Tyres – Tread patterns	Cornering Properties - cornering characteristics of bias and radial ply tyres for cars and trucks	Sliding Abraration, Tyre Stiffness and Tyre wear	Retrofit- Tyre Geometry line
S-7	SLO1	Tyre performance criteria indoor test –Rolling resistance Vs Inflation	Truck Tyres – Tread compounds	Cornering Properties - Self aligning torque	Failure Analysis: Structural Failures	Retrofit- Tyre Uniformity line
	SLO2	Tyre performance criteria indoor test –Rolling resistance Vs Inflation	Truck Tyres – Tread Compounds	Cornering Properties – Variation of Self aligning torque with slip angle for bias and radial ply tyres	Failure Analysis: Structural Failures	Retrofit – Tyre balancing line

S-8	SLO1	Technical Test- Force and Moment Properties, Resistivity, Uniformity	Tyres for Agricultural and Earth Movers	Cornering Properties – Camber and Camber Thrust	Failure Analysis: In service failure modes	Non Destructive Testing Methods
	SLO2	Technical Test-Flat spotting, Traction	Tyres for Agricultural and Earth Movers	Cornering Properties – Variation of Camber thrust with normal load and camber angle for car tyres	Failure Analysis: In service failure modes	X-ray Examination
S-9	SLO1	Tyre Manufacturing Process – Compound Preparation, Extrusion process	Tyres for Military Vehicle	Models for Cornering Behavior of tires - Stretched String model	Tyre durability, Servicing, maintenance and safety	Shearography
	SLO2	Tyre Assembly and Curing	Tyres for Military Vehicle	Models for Cornering Behavior of tires - Beam on Elastic foundation model	Tyre durability, Servicing, maintenance and safety	Eddy Current

Learning Resources	1. US Department of Transportation., "The Pneumatic Tire", February 2006	3. J. Y. Wong, "Theory of Ground Vehicles", 4th Edition 2008
	2. Tom French, "Tyre Technology" Taylor and Francis 2007	4. H. B. Pacejka "Tyre and vehicle dynamics", Second Edition 2006

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory		Theory		Theory		Theory		Theory	
Level 1	Remember	40%		40%		40%		40%		40%	
	Understand										
Level 2	Apply	40%		40%		40%		40%		40%	
	Analyze										
Level 3	Evaluate	20%		20%		20%		20%		20%	
	Create										
	Total	100 %		100 %		100 %		100 %		100%	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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Course Code	18AUE355T	Course Name	MOTORSPORT TECHNOLOGY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18AUC302J	Co-requisite Courses	18AUC401J	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Provide an insight on the problems imposed by racing, race car design and development strategies..	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Understand the aerodynamic requirements in racing vehicles and the purpose of various aerodynamic devices.	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Understand the behavior of a racing vehicle chassis at different conditions.	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Gain knowledge about the concepts of various suspension characteristics of racing vehicles.	Expected Attainment (%)	Design & Development
CLR-5 :	Understand the problems faced in drives and braking systems in motorsports.		Analysis, Design, Research
			Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Demonstrate their knowledge on the fundamentals of race car design and development.	2 75 75	H H H M L M L H H H L H H M H
CLO-2 :	Identify the aerodynamic requirements of a race car and characteristics of various aerodynamic devices.	2 80 80	H M H M M M L H M L L H H M H
CLO-3 :	Interpret the effects of various dynamic conditions on a race car chassis.	2 80 80	H H H M L M L H M L L H H M H
CLO-4 :	Compare and classify the different types of suspension systems used in racing.	2 75 75	M M M M L M L H M L L H H M H
CLO-5 :	Identify the appropriate drives and braking systems for the required racing applications.	2 75 75	M M M M L M L H M L L M H M H

Duration (hour)	Race Car Design and Development	Race Car Aerodynamics	Race Car Chassis	Race Car Suspension System	Race Car Drives And Braking Systems
	9	9	9	9	9
S-1	SLO-1 Problems Imposed By Racing	Aerodynamic Force And Moment, Race Car Drag Components	Conditions For Traversing A 90° Corner	Front Suspension- General Design Issues, Camber Effects.	Merits Of Front and Rear wheel drive in racing.
	SLO-2 Racing Objective	Drag Estimation and Drag Improvement	Principle Chassis Tuning Items	McPherson Struts, SLA Suspension.	Four-Wheel Drive In Racing.
S-2	SLO-1 "g-g" Diagram	Ground Effects in a race car	Effects Of High Speed Braking	SLA suspension geometry, Instant Axis Concept.	Differentials Used In Racing- Open Differentials, Locked (Spool) differentials.
	SLO-2 Road car vs race car "g-g" Diagram.	Ground Plane Simulation In Race Car Applications.	Effects Of High Speed Cornering	SLA Rear Suspension, Beam Axle Rear Suspensions, Decoupled Rear Axle Suspension	Limited Slip Differential
S-3	SLO-1 Constraints And Specifications – Performance and Handling	Spoilers, Dams, Wings	Effects of Combined Braking Cornering	F1 car suspension: Double wishbone and outboard spring	Traction Control And Other Electronic Improvements In Racing.
	SLO-2 Constraints And Specifications –Structure, weight distribution.	Effectiveness Of Wings In Steady State Cornering.	Steady State Cornering	Top rocker and inboard spring, pull-rod and inboard spring	Traction Control And Other Electronic Improvements In Racing.
S-4	SLO-1 Driver Accommodation And Safety.	High Lift Devices- Flaps And Slats.	Acceleration Out Of A Corner	Push rod and vertical coil spring, push rod and horizontal coil spring and damper	Mechanical Components In Braking System.
	SLO-2 Tire and adjustable features.	Flow Control Devices- Dams, Fences, Vanes, Skirts, Spoilers.	Straight Line Acceleration	Push rod and Vertical torsion bar with horizontal damper	Mechanical Components In Braking System.
S-5	SLO-1 Preliminary Design And Analysis.	Vortex Creating Devices- Ledges, Edge, Cusps, Lips.	Throttle Behaviour	Suspension Springs- Torsion Springs, Coil Springs	Limitations And Considerations Of Braking In Racing.
	SLO-2 Driver-Vehicle Relationship	Pressure Change Creation Devices- Perforations, Vents, Bleeds, Scoops, Seals.	Steering Wheel Force And Kick Back	Progressive Rate Coil Springs	Limitations And Considerations Of Braking In Racing.
S-6	SLO-1 Desirable Vehicle Characteristics.	Air-Foil Devices- Slats, Flaps, End Plates, Cuffs, Fillets, Trips.	Moving CG Position, Ballasts.	Installation Consideration	Brake Boost in racing

	SLO-2	Fundamentals Of Testing	Active Flow Control Devices- Internal Airflow, RAM Air Ducted Radiator, Air Entrance Scoop	Effect of engine weight reduction on longitudinal CG position.	Damping In Racing, Ride/Handling Compromise	Effects Of "g" Force On Brake Fluids
S-7	SLO-1	Track Test Program Planning	Full size wind tunnel testing	Roll Center Position Changing Anti-Pitch Geometry	Steering Activity, Transient Maneuvering	Brake Hydraulics
	SLO-2	Test Methodology	Full size wind tunnel testing	Chassis Steering Axis Geometry, Changing Camber	Bump Damping And Rebound Damping	Brake Ventilation
S-8	SLO-1	General Notes On Development	Case study: Chaparral wings	Chassis Ride Roll Characteristics	Racing damper schematic	Brake Distribution
	SLO-2	Circular Skid Pad Testing.	Case study: Performance benefits from the Chaparral wings.	Chassis Track Width , Chassis Ride Spring Rate, Tires And Rims	Case study: Penske four-way adjustable damper.	ABS In Racing
S-9	SLO-1	Case study- 1955 Mercedes W196 Grand Prix car.	Case study: Formula Benetton's pressurized, half-scale wind tunnel.	Adjusting Roll Stiffness	Lateral restraints- Pan hard bar, Watts's linkage.	Carbon-Carbon discs.
	SLO-2	Case study- 1998 Ferrari F300 Grand Prix car.	Case study: Moving ground plane Benetton's wind tunnel.	Roll Stiffness Distribution	Cam and follower in track, A-arms.	Case study: Ferrari F300 two-pedal arrangement for braking.

Learning Resources	1. William F.Milliken and Douglas L.Milliken, "Race car vehicle dynamics", 11th edition, SAE, 1995. 2. Peter Wright, "Formula 1 Technology", 2001.	3. Thomas D. Gillespie, "Fundamental of Vehicle Dynamics, Society of Automotive Engineers", USA 11 th edition , 2006 4. Wolf-Heinrich Hucho, "Aerodynamics of road vehicles", 4th edition, 2000.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
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Course Code	18AUE356T	Course Name	AUTOMOTIVE NVH	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	<i>The purpose of learning this course is to:</i>	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	<i>Understand fundamentals of noise and vibration theory</i>	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	<i>Explain fundamental principles of sound quality and vibration modal analysis</i>	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	<i>Equip themselves familiar with basics of vibration and their mathematic models</i>																		
CLR-4 :	<i>Understand measuring instrumentations, techniques and metrics used for automotive NVH</i>																		
CLR-5 :	<i>Understands the various automotive noise sources and their control techniques</i>																		
Course Learning Outcomes (CLO):	<i>At the end of this course, learners will be able to:</i>																		
CLO-1 :	<i>Identify the basics of vibration and formulate the equations for various types of vibrations</i>	3	95	80	H	H	H	H	M	L	L	L	M	L	L	M	H	L	L
CLO-2 :	<i>Design various vibration control techniques</i>	3	95	80	H	H	H	H	H	L	L	L	M	L	L	M	H	H	L
CLO-3 :	<i>Interpret fundamental of noise and its transmission</i>	2	85	80	H	M	H	M	M	L	H	M	M	H	M	M	H	H	M
CLO-4 :	<i>Compare and classify different vibration measurement test</i>	3	90	85	H	M	H	H	M	L	M	M	L	L	M	M	M	H	M
CLO-5 :	<i>Explain the causes of automotive noise and its control methods</i>	3	95	90	H	M	H	H	M	M	H	H	L	L	L	M	H	M	M

	Basics of Vibration Analysis	Vibration Control Techniques	Noise Fundamentals	NVH Measurements	Automotive Noise Sources and Control Techniques
Duration (hour)	9	9	9	9	9
S-1	SLO-1	Basic concepts	Transmissibility Ratio	Fundamental of acoustics	Vibration and Noise Standards
	SLO-2	Formulating the equations of motion	Transmissibility ratio and its different cases	General sound propagation	Pass/Drive by noise-test site
S-2	SLO-1	Free undamped vibration	Vibration isolation	Structure borne sound& air borne sound	Pass/Drive by noise meteorological condition
	SLO-2	Free undamped vibration	Vibration isolation	Structure borne sound& air borne sound	Pass/Drive by noise meteorological condition
S-3	SLO-1	Free damped vibration	Tuned viscous dampers	Plane wave propagation - wave equation	Pass/Drive by noise-constant speed test-wide open throttle test
	SLO-2	Free damped vibration	Tuned viscous dampers	Specific acoustic impedance, acoustic intensity	Pass/Drive by noise-constant speed test-wide open throttle test
S-4	SLO-1	Logarithmic decrement	Tuned viscous dampers	Spherical wave propagation	Interior Noise test- standards – test track condition
	SLO-2	Graphical analysis of Logarithmic decrement	Tuned viscous dampers	Acoustic near and far fields	Interior Noise test- standards– vehicle operating condition
S-5	SLO-1	Forced Vibration	Untuned viscous dampers	The decibel scale, Summation of pure tones	Interior Noise test- standards steady speed – Full throttle test –stationery test
	SLO-2	Magnification Factor	Untuned viscous dampers	Relationship among sound power, sound intensity and sound pressure level	Interior Noise test- standards-microphone positions
S-6	SLO-1	Magnification Factor Different Cases	Untuned viscous dampers	Relationship among sound power, sound intensity and sound pressure level	Stationery vehicle test- standards
	SLO-2	Magnification Factor Different Cases	Untuned viscous dampers	Relationship among sound power, sound intensity and sound pressure level	Stationery vehicle test- test site

S-7	SLO-1	Torsional system characteristics and single disc	Damping treatments and its significance	Decibel addition, subtraction and averaging matrix from element stiffness	Stationery vehicle test- preparation of the vehicle	Noise control strategy, noise control at source
	SLO-2	Torsional system characteristics of two disc	Damping treatments and its significance	Decibel addition, subtraction and averaging matrix from element stiffness	Stationery vehicle test-vehicle operating condition	Noise control along the transmission path
S-8	SLO-1	Two degree of freedom systems under harmonic force, modal analysis.	Free layer damping	Anatomy of Human Ear,	NVH measurement tools and techniques	Barriers, enclosures
	SLO-2	Modal analysis.	Free layer damping	Anatomy of Human Ear,	NVH measurement tools and techniques- vibration and noise measurement transducers	Resonators
S-9	SLO-1	Coordinate coupling	Constrained Layer damping	Mechanism of hearing	Advanced acquisition techniques	Industrial noise control measures-
	SLO-2	Coordinate coupling	Constrained Layer damping	Mechanism of hearing	Advanced acquisition techniques	Green belt development

Learning Resources	<ol style="list-style-type: none"> 1. Singiresu S. Rao , "Mechanical Vibrations" 5th Edition, Pearson, September , 2010 2. Ambekar, A. G., "Mechanical Vibrations and Noise Engineering", Prentice Hall of India, New Delhi, 2006 3. Munjal , "Acoustics of Ducts and Mufflers" Wiley publications, 2010 4. Beranek, L. L. and Ver, I. L., "Noise and Vibration Control Engineering –Principles and Application", John Wiley & Sons, Inc, 1992 	<ol style="list-style-type: none"> 5. Beranek, Leo Leroy , "Acoustic measurements" 10th Edition 2007 6. Manasi P. Joshi, "Noise & Vibration Measurement Techniques in Automotive NVH " 2012 7. Malcolm J. Crocker , "Handbook Of Noise And Vibration Control" John Wiley & Sons, Inc 2007
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

Course Designers		
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Course Code	18AUE451T	Course Name	ADVANCED VEHICLE TECHNOLOGY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand electric and hybrid vehicle operation and architectures	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Analyse the suspension system used in automobiles	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Identify suitable methods to reduce the noise emission and categorize the emission norms				H	H	M	M	H	L	L	L	H	L	L	L	H	M	H
CLR-4 :	Apply the function, construction and operation of various sensors and actuators				H	H	M	M	H	L	L	L	H	L	L	L	H	M	H
CLR-5 :	Understand the basics of control system used in automobiles				H	H	M	M	H	L	L	L	H	L	L	L	H	M	H
					H	H	M	M	H	L	L	L	H	L	L	L	H	M	H
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Understand various trends in automotive power plants	2	95	92															
CLO-2 :	Gain knowledge about various modern suspension and braking systems	2	96	90															
CLO-3 :	Understand various emissions and noise pollution control techniques	2	95	90															
CLO-4 :	Understand the fundamentals of modern sensors, actuators, ignition and injection systems	2	93	89															
CLO-5 :	Gain knowledge about automated tracks for safe and fast travel	2	95	90															

		Trends in Automotive Power Plants	Suspension and Brakes	Emission And Noise Pollution Control	Vehicle Operation and Control	Vehicle Automated Tracks
Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction to power plant	Introduction to suspension systems	Sources of Pollution. Various emissions from Automobiles	Fundamentals of Automotive Electronics	Introduction automated tracks
	SLO-2					
S-2	SLO-1	Lean Burn Engines	Interconnected Air And Liquid Suspensions	Formation — Effects of pollutants on environment human beings.	Introduction to sensors, actuators, Processors	Road network
	SLO-2	Working principle of lean Burn engines	Hydro Elastic Suspension System	Emission control techniques	Introduction to sensors, actuators, Processors	Road network Preparation
S-3	SLO-1	Stratified Charged	Hydro Gas Suspension	Emission standards	Sensors : Position, speed,	Maintenance Of Proper Road Network
	SLO-2	Stratified Charged	Closed Loop Suspension	Engine Emissions, Types Of Catalytic Conversion-	Acceleration/Vibrational , Force/Torque, Flow meters,	Traffic survey
S-4	SLO-1	Needs, advantages and disadvantages of Hydrogen Engines	Introduction to brakes	Charcoal Canister	Automotive Actuators	proposed road priority index
	SLO-2	Hydrogen Engines	Modern Rear Wheel Brake	CI engine emission and its control	Electromechanical actuators	Working principle
S-5	SLO-1	Need for Hybrid Vehicles	Self-Energizing Disc Brake	Formation — Smokes, NOx, soot, sulphur particulate	Fluid-mechanical actuators	Automated highway system
	SLO-2	Hybrid Vehicles working principle	Indirect Floating Caliper Disc Brake Brake Limiting Device,	Control Techniques-Fumigation, EGR, HCCI, Particulate Traps, SCR	Computer Control for pollution, noise and for fuel economy	Advantages and disadvantages
S-6	SLO-1	Concept of electric vehicles	Power-Assisted Braking System	Sources of Noise	Basics of networks	National Highway Network With Automated Roads And Vehicles
	SLO-2	Electric Propulsion With Cables	Power-Assisted Braking System	Engine Noise, Transmission Noise, vehicle	Examples of networked Vehicles - Bus system	National Highway Network With Automated Roads And Vehicles
S-7	SLO-1	Fuel cell introduction	Constructional Details Anti-Skid System	Structural Noise, aerodynamics noise	Introduction to Control area network in vehicle	Satellite Control Of Vehicle Operation For Safe And Fast Travel
	SLO-2	Fuel cell Vehicles	Anti-Skid System	Exhaust Noise. Noise reduction in Automobiles	Control area network in vehicle	

S-8	SLO-1	Introduction about the Magnetic Track Vehicles	Regenerative Braking	Noise Control Techniques.	Electronic Fuel Injection	Intelligent transportation systems
	SLO-2		Working principle of Regenerative Braking	Silencer Design.		
S-9	SLO-1	Magnetic Track Vehicles.	Constructional Details. Active suspension	Noise Control Techniques.	Electronic Ignition system	Transducers and Operation Of The Vehicle Like Optimum Speed And Direction
	SLO-2					

Learning Resources	1. T. K. Garrett "The Motor Vehicle", 13th edition 2009.	4. Heinz Heisler, "Advanced vehicle technology", elsevier Store.2002
	2. Dr. N.K. Giri, "Automobile Mechanic", Khanna Publishers, 2006	5. Crouse/Anglin "Automotive Mechanics" Career Education; 10th edition January 13, 1993
	3. Beranek. L.L. "Noise Reduction", McGraw-Hill Book Co., Inc, Newyork, 1993	6. "Bosch Hand Book", 3rd Edition, SAE, 1993

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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2. Mr.R Siva, GMMCO, rsiva@gmmco.com.	2. Dr.K Prabu, VIT, Prabu.k@vit.ac.in	2.Mr.S.Devanand,SRMIST, devanans@srmist.edu.in

Course Code	18AUE452T	Course Name	AUTOMOTIVE SAFETY AND ERGONOMICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Impart knowledge on basics of vehicle construction details and its effects.	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Know the various safety concepts used in passenger cars.	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Gain knowledge about various safety systems and its equipment.	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Understand the concepts of vehicle ergonomics.	Expected Attainment (%)	Design & Development
CLR-5 :	Interpret the various automotive comfort features.		Analysis, Design, Research
			Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Understand the fundamentals of design and construction of vehicle body.	1 80 75	H L L M M L L L L L L H H L L
CLO-2 :	Classify the various safety parameters such as interior and exterior safety concepts.	2 75 70	H L L M M L L L L L L H H M L
CLO-3 :	Understand the concepts of active and passive safety systems for real time application.	2 80 77	H L L L L L L L L L M H L L
CLO-4 :	Implementing the vehicle ergonomics for enhancing the comfort level.	3 75 70	H M M M L L M L M L L M H M M
CLO-5 :	Describe the different types of comfort and convenience systems.	2 85 80	H L L M L L L L L L M H M L

Duration (hour)	Design and Construction of Vehicle Body	Interior and Exterior Safety Concepts	Active and Passive Safety systems	Vehicle Ergonomics	Comfort and Convenience Systems
	09	09	09	09	09
S-1	SLO-1 Introduction to design and construction of vehicle body	Safety concepts- Introduction	Introduction to safety systems	Introduction to human body	Comfort and Convenience Systems- Introduction
	SLO-2 Design of the body for Safety. Energy equations, Engine location	Active safety, Driving safety, Conditional safety	Seat belt, Automatic seat belt fastening system	Anthropometrics and its application to vehicle ergonomics	Cabin comfort - In-Car air conditioning – overall energy efficiency
S-2	SLO-1 Effects of deceleration inside passenger compartment	Perceptibility safety	Collapsible steering column	Cockpit design	Air Management, Central and unitary systems, Air flow circuits
	SLO-2 Operating safety	Operating safety	Tilttable steering wheel		Air Cleaning, Ventilation, Air space diffusion
S-3	SLO-1 Deceleration on impact with stationary and movable obstacle	Passive safety	Air bags	Driver comfort – seating, visibility	Compact heat exchanger design, Controls and Instrumentation
	SLO-2 Exterior Safety	Exterior Safety	Electronic systems for activating air bags		Compact heat exchanger design, controls and Instrumentation
S-4	SLO-1 Concept of crumple zone and safety sandwich construction	Interior Safety Systems	Frontal design for safety	Driver comfort – Seat pan, Back rest, Steering wheel, Head rest and mirrors	Steering and mirror adjustment
	SLO-2 Active and passive safety	Deformation behaviour of vehicle body	Collision warning system		Central locking system
S-5	SLO-1 Active and passive safety	Deformation behaviour of vehicle body	Causes of rear end collision, frontal object detection	Man-Machine system	Garage Door Opening System, Tire Pressure Control System, Rain sensor System
	SLO-2 Optimization of vehicle structures for crash worthiness	Human impact tolerance- Determination Of injury thresholds	Rear vehicle object detection system	Psychological factors – stress, attention	Environment information System, Automotive lamps, Types, Design, Construction, performance
S-6	SLO-1 Characteristics of vehicle structures	Speed and acceleration characteristics of passenger compartment on impact	Object detection system with braking system interactions	Passenger comfort - Ingress and Egress	Light signalling devices- stop lamp
	SLO-2 Optimization of vehicle structures for crash worthiness	Pedestrian safety	Anti-lock braking system	Spaciousness	Rear position lamp, Direction indicator
S-7	SLO-1 Optimization of vehicle structures for crash worthiness	Human impact tolerance- Determination Of injury thresholds	Anti-lock braking system	Ventilation, Temperature control	Reverse lamp, Reflex reflector
	SLO-2 Types of crash / Roll over tests	Severity index, Study of comparative	ESP And EBD Systems	Dust and fume prevention	Position lamp, Gas discharge lamp, LED
S-8	SLO-1 Types of crash / Roll over tests	Severity index, Study of comparative	ESP And EBD Systems	Interior features and conveniences	Adoptive Front Lighting System (AFLS)

	SLO-2	Regulatory requirements for crash testing	tolerance	Adaptive Cruise Control (ACC)		Daylight Running Lamps (DRL)
S-9	SLO-1	Instrumentation, High speed photography	Study of crash dummies	Navigation systems, traffic telematics	Placement of vehicle controls	Role of MCU in security and safety features
	SLO-2	Image analysis.		Infrared night vision system	Use of Modern technology for the same	

Learning Resources	1. Prasad, Priya and Belwafa Jamel, "Vehicles Crashworthiness and Occupant Protection", American Iron and Steel Institute, USA. 2. JullianHappian-Smith "An Introduction to Modern Vehicle Design" SAE, 2002	3. Bosch - "Automotive Handbook" - 10th edition - SAE publication - 2018. 4. "Recent development in Automotive Safety Technology", SAE International Publication. Editor: Daniel J Helt, 2013. 5. Keitz H.A.E. "Light Calculations and Measurements", Macmillan 1971.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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Course Code	18AUE453T	Course Name	VEHICLE MAINTENANCE	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Learn how to maintain the various systems and components in an automobile	1	1
CLR-2 :	Effectively troubleshoot common problems in an automobile	2	2
CLR-3 :	Prevent premature failure of components and systems by audio-visual inspection	3	3
CLR-4 :	Ensure the safety of occupants by preventive maintenance	3	3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)
CLO-1 :	Understand vehicle operation and maintenance principles	3	90
CLO-2 :	Understand and perform scheduled services	3	90
CLO-3 :	Handle situations where the vehicle is likely to fail	3	90
CLO-4 :	Understand maintenance procedures like repairing, overhauling etc.,	3	90

	Maintenance of Workshop Records and Schedules	Powertrain Maintenance	Vehicle Chassis and Body Maintenance	Electrical System Maintenance	Maintenance of Auxiliary Systems
Duration (hour)	09	09	09	09	09
S-1	SLO-1 Importance Of Maintenance, Scheduled And Unscheduled Maintenance	Dismantling Of Engine Components And Cleaning	Maintenance And Servicing Of Front Axle	Testing Methods For Checking Electrical Components	Servicing Of Fuel System Of Different Types Of Vehicles
S-2	SLO-1 Requirements Of Maintenance	Cleaning Methods	Maintenance And Servicing of Rear Axle	Checking of Battery	Maintenance Of Fuel System Of Different Types Of Vehicles
S-2	SLO-2 Preparation Of Check Lists	Visual And Dimensional Inspections	Maintenance And Servicing of Suspension Systems	Checking of Starter Motor	Calibration And Tuning Of Engine For Optimum Fuel Supply
S-3	SLO-1 Vehicle Down Time	Minor And Major Reconditioning Of Various Components	Maintenance And Servicing of Braking Systems	Checking of Charging System	Maintenance of Cooling System
S-3	SLO-2 Vehicle Inspection, Inspection Schedule	Reconditioning Methods	Overhauling of Steering Systems	Checking of, DC Generator	Water Pump, Radiator
S-4	SLO-1 Maintenance Of Records, Reports	Engine Assembly	Maintenance of Steering Systems	Checking of Alternator	Thermostat
S-4	SLO-2 Log Books, Trip Sheets And Other Forms	Special Tools Used For Maintenance And Overhauling	Wheel Alignment	Checking of Ignition Systems	Anticorrosion And Antifreeze Additives
S-5	SLO-1 Safety Precautions In Maintenance	Engine Tune Up	Computerized Alignment	Checking of Lighting Systems	Maintenance of Lubrication System
S-5	SLO-2 Fleet Maintenance Requirement	Layout of transmission system	Wheel Balancing	Fault Diagnosis Of Modern Electronic Controls	Different grades of oil
S-6	SLO-1 Work Shop Layout	Servicing And Maintenance Of Automobile Clutch	Troubleshooting Checklist For Front Axle	Maintenance Of Modern Electronic Controls	Lubricant oil additives
S-6	SLO-2 Tools And Equipment	Servicing And Maintenance Of Gear Box	Troubleshooting Checklist For Rear Axle	Checking Of Dash Board Instruments	Lubricating Oil Changing
S-7	SLO-1 Spare Parts And Lubricants Stocking	Servicing And Maintenance Of Propeller Shaft	Troubleshooting Checklist For Suspension Systems	Servicing Of Dash Board Instruments	Greasing Of Parts
S-7	SLO-2 Manpower, Training	Servicing And Maintenance Of Differential System	Troubleshooting Checklist For Steering Systems	Trouble Shooting On Engine Management System	Minor And Major Repairs Of Body Parts
S-8	SLO-1 Workshop Management	Trouble Shooting Checklist For Engine	Body Panel Tools For Repairing	Multi-Scanner	Maintenance Of Door Locking Mechanism
S-8	SLO-2 Warranty	Trouble Shooting Checklist For Clutch	Body Panel Tools for Tinkering And Painting	On Board Diagnosis Using Multi-Scanner	Maintenance Of Window Glass Actuating System

S-9	SLO-1	Replacement Policy	Trouble Shooting Checklist Gear Box	Case studies	Case-Studies	Case-Studies
	SLO-2		Case-Studies			

Learning Resources	1.	John Doke, "Fleet Management", McGraw Hill Co. 1984	3.	Tim Gilles, "Automotive service", 5 th edition, Delmar CENGAGE Learning, 2009.
	2.	James D Halderman, "Advanced Engine Performance Diagnosis", PHI, 1998		
			4.	Service manuals.

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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Course Code	18AUE454T	Course Name	VEHICLE BODY ENGINEERING AND AERODYNAMICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18AUC302J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)															
CLR-1 :	Identify different types of vehicle body structures and their details				Learning (Bloom)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Know the details of bus bodies, classification and its regulations																						
CLR-3 :	Impart knowledge on the concept of car aerodynamics and testing of scale models																						
CLR-4 :	Classify different types of commercial vehicles and its types																						
CLR-5 :	Understand the various concepts of commercial vehicle aerodynamics																						

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Understand the fundamentals of various automotive body construction details	1	80	75	H	L	L	M	L	L	L	L	M	L	L	M	H	L	M
CLO-2 :	Classify the various types of bus body construction and able to identify the body layout.	2	75	73	H	L	M	M	L	L	L	L	L	L	L	L	H	M	L
CLO-3 :	Understand the concepts of car aerodynamics in body engineering for better style and low drag.	1	80	78	H	H	L	L	L	L	M	L	M	L	L	M	H	L	L
CLO-4 :	Select a suitable body optimization technique to minimize drag and able to describe the wind tunnel testing procedure	2	75	73	H	L	M	M	L	L	L	L	L	L	L	L	H	M	L
CLO-5 :	Describe the different types of commercial vehicles and its design	2	85	80	H	L	H	H	L	L	M	L	L	L	L	M	H	L	L
CLO-6 :	Apply the concept of commercial vehicle aerodynamics for reducing the drag.	2	75	72	H	L	M	M	L	L	L	L	M	L	L	L	H	M	L

Duration (hour)	Car Body Details 9	Bus Body Details 9	Car Aerodynamics 9	Commercial Vehicle Details 9	Commercial Vehicle Aerodynamics 9
S-1	SLO-1 History - Evolution of vehicle body, Importance of vehicle body	Introduction to bus bodies	Car Aerodynamics - Introduction	Commercial vehicles - Introduction	Commercial vehicle aerodynamics - Introduction
	SLO-2 Car Body Terminologies & types of car bodies	Bus body panels & terminologies	Importance of Aerodynamics	Classification of Commercial vehicle bodies	Importance of Commercial vehicle Aerodynamics
S-2	SLO-1 Visibility - Forward visibility	Classification of bus body	Types of Aerodynamic drag	LCV – Light commercial vehicles and its types – Pickups and delivery vans	Effects of rounding sharp front body edges
	SLO-2 Forward vision measurement and Regulations	Based on distance travelled by the vehicle			
S-3	SLO-1 Driver's Visibility, All round visibility of the vehicle – sensors and its functions	Based on capacity of the vehicle	Various Aerodynamic forces and moments	HCV - Heavy commercial vehicles and its types	Effects of various cabs on trailer body
	SLO-2 Methods of improving visibility	Based on shape and style of the vehicle			
S-4	SLO-1 Safety - factors influencing safety in traffic	Based on types of metal section used	Effect of Aerodynamic forces and moments	Dimensions of commercial vehicle driver's seat in relation to various controls	Fore body pressure distribution
	SLO-2 Classification - Active & Passive safety	Bus body regulations			
S-5	SLO-1 Active safety - Driving, Conditional, Perceptibility & Operational safety	Sequence of bus building operation	Various body optimization techniques for minimum drag	Constructional details of Tanker body	Effect of Cab to trailer body roof height
	SLO-2 Passive safety - Interior & Exterior safety				
S-6	SLO-1 Safety aspects in design - Bumper end, front end	Construction of conventional type of bus body	Wind tunnel technology - Principle & Construction details	Construction of Tipper body	Effects of a cab to trailer body gab seals
	SLO-2 Safety aspects in design - Rear end and importance of larger distance			Various tipping methods	
S-7	SLO-1 Passive Safety devices - Air bag	Construction of Integral type of bus body	Types of wind tunnels	Various Tipping mechanisms	Commercial vehicle drag reducing devices
	SLO-2 Telescopic/Collapsible Steering column			Flat platform and drop side body construction	Cab roof deflectors & Corner Vanes
S-8	SLO-1 Active Safety devices	Comparison of test results of integral and conventional bus.	Flow visualization techniques – Smoke method, Tuft method, Oil coating method	Segmental design of driver's cab	Vortex generators and Diffusers
	SLO-2 Modern Painting process of a passenger car body				Tractor and Trailer Skirting

S-9	SLO-1	Selection of paint and painting process	Frame Construction	Testing with wind tunnel balance (scale models)	Compactness of Driver's cab	Effect of Trailer load position on vehicle's drag resistance
	SLO-2	Corrosion and Anti corrosion methods	Double Skin construction			

Learning Resources	1. Pawloski J, " Vehicle Body Engineering" - Business Books Ltd.,			3. John Fenton, "Vehicle Body layout and analysis", Mechanical Engineering Publication Ltd., 1984		
	2. Wolf-Heinrich Hucho, "Aerodynamics of road vehicles", 4th edition, 2000.			4. Heinz Heisler, "Advanced Vehicle Technology", 2nd edition, Butterworth – Heinemann, 2002.		

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Evaluate Create	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1.Franklin Darlie, HAL, Frank_darlie@rediff.com	1.Dr.C.Prasad HITS, cprasad@hindustanuniv.ac.in	1.. Dr K. Kamalakkannan SRMIST, kamalakk1@srmist.edu.in
2.Mr.V.Raja Raman Altair, rajarav@asiapac.altair.com	2.Mr.A.Muthuvel, Sairam College of Engioneering, muthuvel.mech@sairamce.edu.in	2. Mr.S.Kiran ,SRMIST, kirans@srmist.edu.in

Course Code	18AEE211J	Course Name	ANALOG AND DIGITAL CIRCUITS FOR AUTOMOTIVE APPLICATIONS	Course Category	E	Professional Elective	L	T	P	C
							2	0	2	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1:	Acquire knowledge of about the BJT,MOS based amplifiers	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Know the working of oscillator and Wave Shaper and Multi vibrator circuits	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3:	Impart the techniques of minimizing digital logic circuits				H	M	H	L	H	M	M	H	H	M	L	H	H	H	H
CLR-4:	Familiarize the combinational circuits for different digital applications				H	M	H	H	L	M	M	H	M	M	M	H	H	H	M
CLR-5:	Familiarize the digital sequential circuits and memory devices				H	M	H	H	H	H	H	H	H	H	M	H	H	H	H
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1:	Understanding the use of analog circuits that are essential for Automotive Application	2	85	75	H	M	H	L	H	M	M	H	H	M	L	H	H	H	H
CLO-2:	Understand the Oscillators, Wave Shaping and Multi Vibrator Circuits	2	80	75	H	M	H	H	H	M	M	H	H	M	L	M	H	H	H
CLO-3:	Apply the Minimization Techniques and understand Digital Logic Gates	2	90	85	H	H	H	H	L	M	M	H	M	M	M	H	H	H	M
CLO-4:	Design and implement the Combinational Circuits	2	85	80	H	M	H	H	H	H	H	H	H	H	M	H	H	H	H
CLO-5:	Design and implement Sequential Circuits and understand the Memory Devices	2	80	75	H	M	M	M	H	H	H	H	H	H	M	H	H	H	H

	Introduction to Analog Circuits	Oscillators, Wave Shaping and Multi Vibrator Circuits	Digital Logic Gates and Minimization Techniques	Combinational Circuits	Sequential Circuits and Memory Devices
Duration (hour)	12	12	12	12	12
S-1	SLO-1 Introduction to Analog circuits	Oscillator Introduction	AND,OR Logic circuit implementation	Introduction to Combinational Circuit	Latches, Flip-flops –SR,JK,D,T characteristic table and Equation
	SLO-2 BJT Small signal Model	Analysis of LC oscillator	NOT Logic circuit implementation	Half Adder and Full Adder	Asynchronous Counters
S-2	SLO-1 CMOS Circuit Model	Active RC,RL Filters	NAND,NOR Logic circuit implementation	Half Subtractor and Full Subtractor	Synchronous Counters
	SLO-2 CMOS Circuit Model	RC,RL integrator	EXOR, EX-NOR Logic circuit implementation	Adder and Subtractor circuit example	Programmable Counters
S	SLO-1 Lab 1: basic Digital IC's	Lab 3: Combination Logic Adder, Subtractor	Lab 5: Realization of Encoder, Decoder	Lab 7: Op-Amp Linear Application :Adder, Subtractor	Lab 9: Op-Amp Nonlinear Application : Clipper, Clamper, Peak Detector
3-4	SLO-2 AND,OR,EXOR,NOT,NOR,NAND				
S-5	SLO-1 Biasing Circuits	Differentiator Circuits	TTL Logic	Carry look ahead adder	Registers overview
	SLO-2 Biasing Circuits	Diode-Clippers	CMOS Logic	Serial adder/Subtractor	Shift Registers
S-6	SLO-1 MOS amplifiers	Diode Clamper	Boolean Postulates	BCD addition	Universal Shift Register
	SLO-2 MOS amplifiers - types	Diode Comparator	Demorgan's Theorem	Multiplexer	Sequence Generator
S	SLO-1 Lab 2: Circuit realization of Flip-flops JK, RS, D	Lab 4: Circuit realization of Code Converter	Lab 6: Circuit realization of MUX,DEMUX	Lab 8: Op-Amp Linear Application : Comparator, Differentiator, Integrator	Lab 10: Filters Realization
7-8	SLO-2				
S-9	SLO-1 Frequency response of amplifiers	UJT-Sawtooth Waveform Generator	Min term, Max term	Demultiplexer	Classification of Memories – RAM,ROM,PROM,EPROM,EEPROM
	SLO-2 Frequency response of amplifiers	Astable, MonostableMultivibrators	POS,SOP form	Decoder, Encoder	RAM,ROM Organization
S-10	SLO-1 Differential amplifiers	BistableMultivibrator	K-MAP	Parity Checker, Parity Generator	PLA VS PLD – Combinational Circuit implementation
	SLO-2 Differential amplifiers. Cont	Schmitt trigger circuits	Don't care conditions	Code Converter	Introduction to FPGA
S	SLO-1 Lab: Assessment 1	Lab: Assessment 2	Lab: Assessment 3	Lab: Repeat class	Lab: Mini Project
11-12	SLO-2				

Learning Resources	1. David A.Bell "Electronic Devices and Circuits", Oxford Higher Education Press, 5th Edition, 2010	3. Donald P.Leach and Albert Paul Malvino, "Digital Principles and Applications", 6th Edition, TMH, 2006.
	2. M. Morris Mano, "Digital Design", 4th Edition, Prentice Hall of India Pvt. Ltd., 2008 / Pearson Education (Singapore) Pvt. Ltd., New Delhi.	4. Sedra and Smith, "Micro Electronic Circuits"; Sixth Edition, Oxford University Press, 2011. Millman and Halkias. C., Integrated Electronics, TMH, 2007.

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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Course Code	18AEE311T	Course Name	PRINCIPLES OF LINEAR SYSTEMS AND SIGNALS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	18AEE211J	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:		Learning			Program Learning Outcomes (PLO)																
CLR-1 :		Understand and classify the signals, their operations and the systems		Level of Thinking (Bloom)	2	Expected Proficiency (%)	3	Expected Attainment (%)	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :		Test and execute the continuous time system's response, stability in time domain.							Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :		Formulate and solve the continuous time system equations using Laplace transform.							H	L	L	L	L	L	L	L	L	L	L	M	H	M	L
CLR-4 :		Solve and examine the discrete time system using Z transform							H	H	M	H	M	M	M	L	L	L	L	M	H	M	L
CLR-5 :		Execute the Fourier series based representation of continuous time signal systems							H	H	M	H	M	M	M	L	L	L	L	M	H	M	L
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																					
CLO-1 :		Acquire the fundamentals of signal operation andbasics of system		1	90	85																	
CLO-2 :		Perform time domain analysis of a continuous time system with various inputs.		2	85	80																	
CLO-3 :		Analyse and examine the Continuous Time System in frequency domain using Laplace transform.		2,3	85	80																	
CLO-4 :		Test the stability and the response of discrete time system using Z transform		2,3	85	80																	
CLO-5 :		Know the fundamentals involved in continuous time signal analysis		2	85	80																	

	Signals and Systems	Time Domain Analysis of Continuous Time Systems	Continuous Time System Analysis Using Laplace Transform	Discrete Time Analysis Using Z-Transform	Continuous Time Signal Analysis
Duration (hour)	09	09	09	09	09
S-1	SLO-1 Size of a signal – Signal Energy	System response to internal condition – Zero input response	Laplace transform – Inverse Laplace transform	Z-Transform introduction	Periodic signal representation by trigonometric Fourier series
	SLO-2 Size of a signal – Signal Power	System response to internal condition – Zero input response.	Properties of the Laplace transform – Time shifting	Finding inverse transform	Periodic signal representation by trigonometric Fourier series - The Fourier spectrum
S-2	SLO-1 Signal Operations – Time shifting, Time scaling	Unit Impulse response	Properties of the Laplace transform – frequency shifting	Properties of Z-transform	Periodic signal representation by trigonometric Fourier series - The Fourier spectrum.
	SLO-2 Signal Operations – Time reversal, combined operation	Impulse response.	Properties of the Laplace transform – time differentiation property	Z-transform solution of linear difference equations – Zero-state response of LTID system	Periodic signal representation by trigonometric Fourier series - Effect of symmetry
S-3	SLO-1 Classification of signals – Continuous-Time.	System response to external input – Zero state response	Properties of the Laplace transform – time integration property.	Z-transform solution of linear difference equations – Stability and Inverse system	Periodic signal representation by trigonometric Fourier series - Determining the Fundamental Frequency and Period
	SLO-2 Classification of signals – Discrete-time signals	System response to external input – Zero state response.	Properties of the Laplace transform – Time convolution	Z-transform solution of linear difference equations – Stability and Inverse system	Existence and Convergence of Fourier series
S-4	SLO-1 Classification of signals – Analog and Digital signals	System response to external input – Convolution integral	Properties of the Laplace transform – frequency convolution	System Realization	Existence and Convergence of Fourier series.
	SLO-2 Classification of signals – Periodic and Aperiodic signals.	System response to external input – Convolution integral	Solution of differential and integro - differential equation – Zero state response	System Realization.	Exponential Fourier series - Exponential Fourier spectra
S-5	SLO-1 Classification of signals - Energy and Power signals,	System response to external input – Interconnected systems	Solution of differential and integro - differential equation – Zero state response.	Frequency response of discrete time systems – Periodic nature of frequency response	Exponential Fourier series- Exponential Fourier spectra.

	SLO-2	Classification of signals –Deterministic and Randomsignals	System response to external input – Interconnected system.	Solution of differential and integro-differential equation – stability	Frequency response of discrete time systems – Periodic nature of frequency response.	Exponential Fourier series - Parseval's theorem
S-6	SLO-1	Excitation signals- Unit Step function	System stability –Internal Asymptoticstability	Solution of differential and integro - differential equation – Inverse system	Frequency response of discrete time systems – Aliasing andsampling rate	LTI System response to periodic inputs
	SLO-2	Excitation signals-Unit impulse function and Exponential function	System stability –Internal Asymptoticstability.	System Realization -Introduction	Frequency response of discrete time systems –Aliasing andsampling rate.	LTI System response to periodic inputs.
S-7	SLO-1	Even functions and Odd functions- Properties	Relationship between BIBO and asymptotic stability.	System realization - Direct Form I Realization	Frequency response from pole-zero location	Aperiodic signal representation by Fourier integral
	SLO-2	Classification of system – Linear and nonlinear systems,	Relationship between BIBO and asymptotic stability.	System realization - Direct Form II Realization	Frequency response from pole-zero Location.	Aperiodic signal representation by Fourier integral.
S-8	SLO-1	Classification of system –Time invariant, time varying	Dependence of system behavior on characteristics modes	Analysis of a simple feedback control system	Relationship between Laplace transform and z-transform	Relationship between the Fourier and Laplace transform
	SLO-2	Classification of system – Instantaneous and dynamic	Dependence of system behavior on characteristics modes.	Analysis of a simple feedback control system.	Relationship between Laplace transform and z-transform.	Relationship between the Fourier and Laplace transform.
S-9	SLO-1	Classification of system – causal and non-causal system	Response time of system –time constant, rise time	Frequency response of an LTIC System	Bilateral Z-transform -Introduction	Properties of Fourier transform
	SLO-2	Classification of system –Analog and Digital system	Response time of system –resonance Phenomenon.	Frequency response of an LTIC system.	Bilateral Z-transform -Properties	Properties of Fourier transform.

Learning Resources	1. B.P. Lathi "Principles Of Linear Systems And Signals "Oxford University Press, 2009. 2. Allan V.Oppenheim, S.Wilsky and S.H.Nawab, "Signals and Systems", Pearson, 2007.	3. R.E.Zeimer, W.H.Tranter and R.D.Fannin, "Signals & Systems - Continuous and Discrete", Pearson, 2007.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Evaluate Create	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, and Conf. Paper etc.

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.Jegan Amirthalingam, Senior Educator, KPIT a.jegan@kpit.com	1. Mr. Sam Jebakumar, SRM IST, jebakumj@srmist.edu.in	1. Ms. Srividya K, SRMIST
	2. Dr. P. Sathish Kumar, Jiangsu University, China sathishkumar8989@gmail.com	2. Mr.Jesu Godwin D, SRMIST

Course Code	18AEE312T	Course Name	AUTOMOTIVE INFOTRONICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	State and classify the various driver and vehicle support systems.				Level of Thinking (Bloom)	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Interpret and construct the vehicle communication systems according to the requirement																					
CLR-3 :	Differentiate and construct the various automotive safety systems																					
CLR-4 :	Develop and examine the comfort suitable for the driver's convenience																					
CLR-5 :	Investigate and test the required security for the vehicles																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	Define and identify the driver convenience, perception and general vehicle control				1	90	85	H	M	L	L	L	M	L	L	L	L	L	H	H	M	M
CLO-2 :	Solve and implement the sensors, their modelling for the vehicle communication systems				2,3	90	85	H	H	H	H	M	M	M	L	M	H	L	H	H	H	H
CLO-3 :	Relate and formulate the required safety systems for the required vehicle model.				2,3	90	85	H	H	H	H	M	M	M	L	M	M	L	H	H	H	M
CLO-4 :	Examine and value the relationship between driver and vehicle in comfort perspective.				2,3	90	85	H	H	H	H	M	M	M	L	M	M	L	H	H	H	M
CLO-5 :	Design and experiment the automotive security systems for its performance				2,3	90	85	H	H	H	H	M	M	M	L	M	M	L	H	H	H	H

	Driver and vehicle support systems - Introduction	Automotive Telematics	Automotive safety systems	Automotive comfort systems	Automotive security systems
Duration (hour)	09	09	09	09	09
S-1	SLO-1 Driver information - navigation routing, integrated navigation	Global positioning system – Basics and working	Active and passive safety systems - Introduction	Adaptive cruise control system	Anti-theft technologies – mechanical, electromechanical
	SLO-2 Real-time traffic, traveller information	Geographical information systems - Data representations	Active and passive safety systems - Features	Active suspension system	Anti-theft technologies – Electronic immobilizers
S-2	SLO-1 Driver perception - vision enhancement, electronic mirror	Geographical information systems - Analysis and modeling	Airbag System - components	Adjustable ORVMs	Alarm and warning system
	SLO-2 Parking and reversing aid, state of the road surface systems	geographical information systems – Applications	Airbag System - Working	Electrical Power assisted steering	Stolen vehicle tracking system
S-3	SLO-1 Driver convenience-driver identification, hands – free and remote control	Signpost navigation system	Seat belt tightening system- Block diagram	Collapsible and tiltable steering column	Remote keyless entry
	SLO-2 Driver convenience - automated transactions	Dead reckoning navigation system	seat belt tightening system- Working	Power windows	Smart card system
S-4	SLO-1 Driver monitoring - driver vigilance monitoring	Automotive vision system	Forward collision warning system- Block diagram	Adaptive lighting system	Number plate recognition
	SLO-2 Driver health monitoring	Intelligent Speed Adaptation system	Forward collision warning system- Working	Electrically adjustable seats	Security antenna and transponders
S-5	SLO-1 General vehicle control - automatic stop and go	Fleet Tracking system	Child lock and anti-lock braking system- Block diagram	Rain sensing Wiper systems	Electronic ignition lock
	SLO-2 Vehicle Platooning	Voice based Turn-by-Turn system	Child lock and anti-lock braking system- Working	Reverse parking camera	Radio security system
S-6	SLO-1 Longitudinal control - road and lane departure collision avoidance	Smart-phone App Integration	Electronic Brake force Distribution system- Block diagram	Hands free Bluetooth	Fingerprint vehicle unlock
	SLO-2 Longitudinal control - road and lane departure collision avoidance Cont.	Automotive Collision Notification system	Electronic Brake force Distribution system- Working	Automatic Temperature control	GPS security systems

S-7	SLO-1	Lateral control - lane change and merge collision avoidance	Integrated theft recovery system	Electronic Stability Programme- Block diagram	Connected Mobility assistance and telematics	Speed governing systems
	SLO-2	Lane change and merge collision avoidance .Cont	Intelligent Speed Adaptation system	Electronic Stability Programme- Working	USB charging and navigation systems	Vehicle tracking systems
S-8	SLO-1	rear-end collision avoidance, obstacle and pedestrian detection	Intelligent Speed Adaptation system .Cont	Traction control system - Block diagram	Intelligent windshield wipers	Anti-hijack system
	SLO-2	Intersection collision warning	Voice recognition cell phone dialing system	Traction control system - Working	Intelligent windshield wipers	Vehicle Immobilizer
S-9	SLO-1	Vehicle monitoring - tachograph	Voice recognition cell phone dialing system	Lane departure warning system- Block diagram	Adaptive climate control	Steering-wheel lock
	SLO-2	Vehicle monitoring - alerting systems, vehicle diagnostics	Emergency calling system	Lane departure warning system- Working	Adaptive climate control.	Vehicle GPS tracking

Learning Resources	<ol style="list-style-type: none"> 1. LjuboVlacic, Michel Parent and Fumio Harashima, "Intelligent Vehicle Technologies", Butterworth-Heinemann publications, Oxford, 2001. 2. Robert Bosch, "Automotive Hand Book", SAE, 2000. 3. Allan W M B, "Automotive Computer Controlled Systems", Elsevier Butterworth-Heinemann, 2011. 4. Ronald K Jurgen, "Navigation and Intelligent Transportation Systems – Progress in Technology", Automotive Electronics Series, SAE, USA, 1998. 5. William B R, "Understanding Automotive Electronics", Butter worth Heinemann Woburn, 1998. 6. Bechhold, "Understanding Automotive Electronics", SAE, 1998.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, and Conf. Paper etc.

Course Designers		
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1. Mr.Jegan Amirthalingam, Senior Educator, KPIT a.jegan@kpit.com	1. Mr. Arockiya Vijay, SRMIST, arockiaj1@srmist.edu.in	1. Mr. Srividya K, SRMIST
2. Mr.G.Giri Atalon giri@atalon.co.in		2. Mr.Jesu Godwin D, SRMIST

Course Code	18AEE313T	Course Name	ARTIFICIAL NEURAL NETWORKS AND FUZZY LOGIC	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:		
CLR-1 :	Define and understand the concept of Neural Network Models and Learning algorithm.			
CLR-2 :	Understand the concepts and implementation of fuzzy logic and fuzzy logic controllers.			
CLR-3 :	Interpret and relate the Fuzzy Sets And Fuzzy Relations.			
CLR-4 :	Compare and contrast the Hybrid fuzzy systems such as Neuro fuzzy systems with classical systems.			
CLR-5 :	Understand the implementation of Fuzzy and neuro systems in hardware.			

Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:		
CLO-1 :	List and recognize the various Fuzzy systems in automobile applications.			
CLO-2 :	Identify and Estimate Parameters of a system through Fuzzy Logic and Neural Networks			
CLO-3 :	Identify and use various Fuzzy sets and Fuzzy Relations			
CLO-4 :	Relate and use the various fuzzy logic and fuzzy logic controllers.			
CLO-5 :	Select and Investigate on the various Neural Network Models.			

Learning		
1	2	3
Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)

Program Learning Outcomes (PLO)														
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3

H	M	M	M	L	L	L	L	M	M	L	M	H	H	M	M
H	H	M	H	M	M	M	L	M	L	M	H	H	H	M	M
H	H	M	H	M	M	M	L	M	L	M	H	H	H	M	M
H	H	M	H	M	M	M	L	M	L	M	H	H	H	M	M
H	H	H	H	M	H	H	M	M	M	M	H	H	H	H	H

	Introduction To Neural Networks	Neural Network Models and Application	Fuzzy Sets And Fuzzy Relations	Embedded Fuzzy Application	Hybrid Fuzzy-Neuro Systems And Hardware Implementation
Duration (hour)	09	09	09	09	09
S-1	SLO-1 Introduction to ANN	Neural Network-Feed Forward Application	Basic Concepts of Classical Sets	Introduction to conventional Control System	Introduction to Hybrid Systems
	SLO-2 Components of ANN-Connection, weights, biases	Neural Network-Back Propagation Network Application	Set Operation, Boolean Logic	Description, Design and Analysis	Fuzzy Neuron Overview
S-2	SLO-1 Structure of Neural Network	Layers In Neural Network-Single Layer	Basics of Fuzzy Sets	PID controller	Multilayer FNN architectures XOR Problem
	SLO-2 Structure of Neural Network.	Layers In Neural Network- Multilayer	Representation of Fuzzy Sets	Introduction to Fuzzy logic Controller (FLC)	Types of decision Region
S-3	SLO-1 Output of a Neuron	XOR Function and Linear Separability	Fuzzy Membership Function	Fuzzy logic Controller (FLC)- Description, Design	FNN Neuron Model
	SLO-2 Propagation functions, Learning Rules	XOR Function and Linear Separability.	Trapezoidal, Gaussian and Its Determination	Membership values, Rule table	Fuzzy ART, Fuzzy ARTMAP
S-4	SLO-1 Supervised and unsupervised learning	Threshold Functions-Sigmoid Function, Step Function	Fuzzy Set Properties, Operations	Membership values invented pendulum case study	Fuzzy ARTMAP- Incremental supervised Learning
	SLO-2 Reinforced Learning	Ramp Function And Linear Function	Logic Operation And Algebraic Operations.	Fuzzy logic Controller (FLC) – Knowledge base and Defuzzification	Learning Normalized analog input patterns
S-5	SLO-1 Perception and Multilayer Perception	Function Approximation With Neural Networks	Classical Relations And Fuzzy Reasoning overview	Implementation of Antilock controller example	Neuro-Fuzzy systems
	SLO-2 Perception and Multilayer Perception.	Function Approximation With Neural Networks.	Fundamentals Of Fuzzy Relations	Fuzzy logic Controller (FLC) – Analysis with computer aided Tools	Neuro-Fuzzy applications
S-6	SLO-1 Feed forward Network and Hopfield Network.	System Identification With Neural Networks	Binary Fuzzy Relation operation	Fuzzy based antilock braking system overview	Neuro-Fuzzy systems Linguistic Fuzzy Model
	SLO-2 Introduction to Neural Network Models	Block Box Model Structure	Fuzzy Relations introduction	Fuzzy based antilock braking system.	Fuzzy Membership Fuzzy Rules, Fine-tune Fuzzy Rules

S-7	SLO-1	Neural Network Models –Adaline	Static Neural Network in system Identification	Types Of Fuzzy Relations	Performance and robustness of Fuzzy controller	Hardware Implementation –Analog Techniques
	SLO-2	Neural Network Models –Madaline	Dynamic Neural Network in system Identification	Membership Matrix	Self-Organizing Fuzzy controller	Hardware Implementation - Digital Techniques
S-8	SLO-1	Neural Network Models –Back propagation Network	Model Parameters estimation with Neural Network	Union and intersection of Fuzzy Relations	Fuzzy logic Controller for Automotive Embedded System applications.	Fuzzy Memory and OP-Amp based implementation of basic Neuron Model
	SLO-2	Radial basis function Neural Network	Control system and Neural Networks	Composition of Fuzzy Relations	Case study on Fuzzy logic Controller : Automatic Gearboxes	Fuzzy Memory and OP-Amp based implementation of basic Neuron Model.
S-9	SLO-1	Self-organizing, Recurrent Neural Network	Neural Networks in Predictive control	Fuzzy Reasoning- Fuzzy If-Then Rules	Case study on Fuzzy logic Controller : Four- wheel steering	Microcontroller Based Implementation of Fuzzy controller algorithm for automotive air conditioning Case study
	SLO-2	Convolution, Modular Neural Network	Model Reference Neural Controller	Fuzzy If-Then Rules.	Case study on Fuzzy logic Controller : Vehicle environment control	Microcontroller Based Implementation of Fuzzy controller algorithm for automotive air conditioning. Cont

Learning Resources	<ol style="list-style-type: none"> 1. Ahmad.M.Ibrahim "Fuzzy logic for Embedded System application" -Newness 2004,ISBN: 0-7506-7699 2. Valluru B.Rao " C++,Neural Network and Fuzzy logic", -M&T Books ,IDG books Worldwide,ISBN1558515526 3. M.Gopal "Digital Control and State Variable Methods"-2nd edition, Tata McGraw Hill Publishing,2006 	<ol style="list-style-type: none"> 4. Simon Haykin", Neural Networks and Learning Machines –3rd Edition- Pearson Prentice Hall-ISBN-13: 978-0131471399. 5. Guanrong Chen "Introduction to Fuzzy Sets,Fuzzy logic and Fuzzy control System" Trung Tat Pham-CRC Press -ISBN 0-8493-1658-8
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Understand	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Apply	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Analyze										
	Evaluate										
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, and Conf. Paper etc.

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.Jegan Amirthalingam, Senior Educator, KPIT <a.jegan@kpit.com>	1. Dr. P. Sathish Kumar,Jiangsu University, China sathishkumar8989@gmail.com	1. Mr. Srividya K, SRMIST
		2. Mr.Jesu Godwin D, SRMIST

Course Code	18AEE314T	Course Name	CAD FOR ELECTRONICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Understand concepts of modeling in 2D and 3D.				Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Gain knowledge on computer graphics and Simulation.																							
CLR-3 :	Understand CAD Packages for electronics and recent technologies.																							
CLR-4 :	Use concepts of Computer Graphics in Printed Circuit Boards and Packaging																							
CLR-5 :	Use relevant CAD Standards for Circuit Simulation																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLO-1 :	Use and Relate the role of CAD in Electronics and board design.																							
CLO-2 :	Understand the basic Math fundamentals behind CAD software Graphics.																							
CLO-3 :	Design and Execute Circuits Boards Simulations																							
CLO-4 :	Design Models for Electronic Packaging using CAD																							

		Introduction	Graphics Concepts and Algorithms	Analog Circuit simulation	CAD for Circuit and Component Analysis	CAD for Printed Circuits Boards and Packaging
Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction to Design process – CAD	Introduction to computer Graphics	Introduction to simulation	Introduction to Circuits	Components of a CAD package and its highlights.
	SLO-2	Steps and design Process	Interactive graphics display	Purpose Of Simulation	DC Steady State analysis	Circuit design with CAD package.
S-2	SLO-1	Geometric Modeling Introduction	Display devices, Pixels	Simulation Examples	Simulation Example :Voltage regulator	Work layout and component layout
	SLO-2	Parametric Representation of Lines and curves	Algorithms in computer Graphics	Circuit Equation Modulation	AC Analysis	Process flow-chart.
S-3	SLO-1	Parametric Representation of synthetic curves	DDA Line Drawing Algorithms	Simulation of Modified Nodal analysis method	Simulation Example : Cascode amplifiers with Macro Models	Printing technologies for Printed Wiring Boards
	SLO-2	Geometric Modeling: Entities - Line - Circle - Ellipse - Parabola	Bresenham's Line Drawing algorithm	Modified Nodal analysis.	Cascode amplifiers with Macro Models	Semiconductor Packaging Overview
S-4	SLO-1	Geometric Modeling: Types – Wireframe modeling.	Bresenham's Circle Drawing algorithm	Active device Models overview	Simulation example : Transient analysis Phase Locked Loop circuit	Semiconductor Packages
	SLO-2	Geometric Modeling: Types - surface and solid modeling.	Point clipping algorithms	DC Circuit Simulation Overview	Process and device simulation Overview	Semiconductor Packages design case study
S-5	SLO-1	Solid modeling techniques Overview	Cohen Sutherland Line clipping algorithms	Newton's Method on DC analysis	Process simulation, diffusion, Oxidation, Ion implantation	Board-level packaging aspects
	SLO-2	Constructive Solid Geometry – Boolean set Operations, Sweep Representation	Hidden line removal algorithms	AC Circuit Simulation Overview	Simulation Example: NMOS Transistor	Board-level packaging aspects.
S-6	SLO-1	Constructive Solid Geometry – Quad tree Structure.	2D and 3D transformations	AC Circuit Simulation Example Program	Device simulation	Packaging Examples Case study
	SLO-2	Constructive Solid Geometry- Octree structure	Translation, rotation	Noise Simulation	NMOS IV Curves	CAD output files for PCB fabrication
S-7	SLO-1	Boundary Representation	Scaling – Concatenation.	Noise Simulation Example Program	Parameters Extraction for analog circuit simulation Overview	CAD output files Slandered file format
	SLO-2	Feature Based Modelling and Constraint Based Modelling	Homogeneous Transformation	Transient system Simulation	Device Characterization	Photo plotting and mask generation.

S-8	SLO-1	Parametric Modelling, Extrude, Sweep, Revolve	Translation and scaling	Verilog-A Overview	Least squares curve fitting	Photo Mask File Generation.
	SLO-2	Parametric Modelling Tools Cont	Reflection and rotation	Verilog-A Example Program	Extraction and Optimization	Introduction to DFM, DFR, DFT
S-9	SLO-1	Feature Manipulation	Shear Transformation	Fast Simulation Methods	MOS DC models	DFM, DFR, DFT.
	SLO-2	CAD in Assembly and Drafting	Concatenated transformation - Inverse transformation	General Simulators Overview	MOS DC models.	Computer-Aided Analysis Application

Learning Resources	1. Ibrahim Zeid, "CAD / CAM - Theory and Practice", Tata McGraw-Hill, New Delhi, 2001	3. Mikell P. Groover, "CAD / CAM", Prentice Hall of India Private Limited, New Delhi, 1997
	2. Newman and Sproull R. F., "Principles of interactive computer graphics", Tata McGraw-Hill, New Delhi, 1997	4. The Circuits and Filters Handbook Third Edition "Computer Aided Design Automation" Edited By Wai-Kai Chen

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Evaluate Create	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, and Conf. Paper etc.

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1.Mr.Jegan Amirthalingam, Senior Educator, KPIT a.jegan@kpit.com	1. Dr. P. Sathish Kumar, Jiangsu University, China sathishkumar8989@gmail.com	1. Mr. Joshua Paul E, SRMIST
2. Jonny N, BGR Energy systems, jonnyallathampi@gmail.com		2. Mr.Jesu Godwin D, SRMIST

Course Code	18AEE316J	Course Name	AUTOMOTIVE MICROCONTROLLERS	Course Category	E	Professional Elective	L	T	P	C
							2	0	2	3

Pre-requisite Courses	18AEE211J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1:	Acquire the knowledge of 8051 Microcontroller architecture	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Program 8051 using Assembly level programming	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3:	Use the high level programming language for embedded application development																		
CLR-4:	Get familiarized with the internals of AVR and program it using C language.																		
CLR-5:	Learn about the special on-chip peripherals available on automotive grade Microcontrollers.																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1:	Perform the basic Operations of 8051 Microcontroller	2	85	75	H	M	H	L	H	M	M	H	H	M	L	H	H	H	H
CLO-2:	Carry out basic Operations of 8051 Microcontroller.	2	80	75	H	M	H	H	H	M	M	H	H	M	L	M	H	H	H
CLO-3:	Apply Embedded C Programming in Microcontroller.	2	90	85	H	H	H	H	L	M	M	H	M	M	M	H	H	H	M
CLO-4:	Program ATMEGA328 Microcontroller using Embedded C	2	85	80	H	M	H	H	H	H	H	H	H	H	M	H	H	H	H
CLO-5:	Identify and relate the various Microcontroller in automotive subsistence	2	80	75	H	M	M	M	H	H	H	H	H	H	M	H	H	H	H

		8051 Architecture	Programming 8051	Introduction to Embedded C	Advanced Virtual Risc (AVR) Microcontrollers	Automotive Grade Processors
Duration (hour)		12	12	12	12	12
S-1	SLO-1	Introduction to Microprocessors and Microcontrollers and differences	Logical Operations-Bit level, Byte Level	Program Languages for Embedded system application	Introduction to ATMEGA328	Introduction to Automotive grade processors
	SLO-2	8051 Pin diagram and description	Internal RAM Bit address and SFR Bit address	Introduction to Higher level programming language	ATMEGA328 –Basic Features	Automotive grade processors ex: Renesas, Quorivva
S-2	SLO-1	8051 internal Architecture	Logical Operations-Rotate and swap Operation	Advantages of Higher level programming language	ATMEGA328 – Core SFR'S and Ports	Automotive grade processors : NXP, Infineon
	SLO-2	Clock, PC, DP, CPU registers,	Arithmetic Operations Incrementing, Decrementing	Basics of C program language – Data Types, variables	ATMEGA 328-Timer TMR0,TMR1,TMR2	Architectural attributes of Automotive grade processors Based on subsystems
S-3-4	SLO-1	Lab 1: 8051- Assembly level programming – Basic Arithmetic and logical operations	Lab 3: Introduction to Embedded C Programming and IDE-Tool chains - AVR- ATMEGA328 Operation on bits Blinking with Digital Outputs –Delay functions	Lab 5: ATMEGA328- Configuring on-chip ADC –Interfacing sensors	Lab 7: ATMEGA328- Programming Serial Communication with Interrupts Type1,Type 2	Lab 9: Implementing a moving average filter for sensor noise correction
	SLO-2					
S-5	SLO-1	Data memory Organization	Arithmetic Operations : Addition, Subtraction	Keywords, Pointers, Declarations, Constants and Operators	ATMEGA 328-Capture Compare Module-	On-chip Peripherals overview
	SLO-2	PSW, RAM, ROM, SP, SFR	Jumps, Calls and Subroutines	Introduction to Datatype conversions	ATMEGA 328-CCM in PWM Mode	Special On-chip Peripherals for Body and chassis control applications
S-6	SLO-1	IO ports, Connecting External Memory, Counters, Timers	Interrupts and Return	Switch case and If Loop,For Loop and While Loop	ATMEGA 328-Interrupts Type1,Type 2	On-chip Peripherals for Engine and Power train control
	SLO-2	Serial Data Input / output, Interrupts	Expanding I/O overview	Arrays and pointers	ATMEGA 328- Interrupt Model, Interrupts vectors	Overview of Automotive communication protocols : CAN, LIN
S	SLO-1	Lab 2: 8051-Finding 2's complement of a number	Lab 4:ATMEGA328 –EEPROM	Lab 6: ATMEGA328-	Lab 8: ATMEGA328-Working with RTC and	Lab 10:Building an Automotive Embedded

7-8	SLO-2		Programming	Programming Interrupts and Timers	I2C	application with ATMEGA328
S-11	SLO-1	Addressing Modes of 8051 Microcontroller Overview	Memory Mapped I/O	Functions and Structure	ATMEGA 328-Serial Communication Modules-I2C, SPI	Automotive communication protocols : Flex Ray, MOST
	SLO-2	Immediate and Register Addressing Modes Direct and Register indirect Addressing modes of 8051 Microcontroller	Timing Subroutine-Software and Hardware Delay	Embedded Programming Tool ,IDE with Simulator	ATMEGA 328-Serial Communication Basic Programs	Automotive communication protocols : Ethernet,D2B and DSI
S-10	SLO-1	External memory access of 8051 Microcontroller	Lookup table for 8051 PC,DPTR as Base address	Embedded C Compilers	Analog Modules –A/D converter, Comparator	Introduction to Real-time operating system – for task scheduling activities
	SLO-2	Timer and counter of 8051 Microcontroller	Serial Data Transmission-Polling and interrupt driven for transmission and reception	Data types and libraries in Embedded C	Clock Oscillator ,EEPROM	RTOS Classification - Hard Real-time and Soft Real time
S 11-12	SLO-1	Lab: Assessment 1	Lab: Assessment 2	Lab: Assessment 3	Lab: Review class	Lab: Mini Project
	SLO-2					

Learning Resources	<ol style="list-style-type: none"> 1. Kenneth.J.Ayala "The 8051 Microcontroller,Architecture,Programming and Application" West Publishing Company,1991 2. Muhammad Ali Mazidi, SarmadNaimi, SepehrNaimi "AVR Microcontroller and Embedded Systems Using Assembly and C "Pearson Custom Electronics Technology, 2011. 	<ol style="list-style-type: none"> 3. Muhammad Ali Mazidi, Janice Mazidi, Janice Gillispie Mazidi-8051 Microcontroller and Embedded Systems, The (1999) 4. Gilbert Held "Inter and Intra Vehicle Communications: Auerbach Publications,2008 5. DataSheets of Kinetis 32-bit MCU based on ARM,InfineonXCxx series and Multicore Aurix Architecture
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.Jegan Amirthalingam, Senior Educator, KPIT <a.jegan@kpit.com>	1. Mr. Sam Jebakumar, SRM IST, jebakumj@srmist.edu.in	1. Mr. D. Jesu Godwin, SRMIST
		2. Mr. E. Joshua Paul, SRMIST

Course Code	18AEE317J	Course Name	AUTOMOTIVE CONTROL ENGINEERING	Course Category	E	Professional Elective	L	T	P	C
							2	0	2	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:		Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Familiarize about the importance of feedback control in automotive applications			Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Understand the status of the system in terms of stability																						
CLR-3 :	Develop the knowledge of controller and compensator design																						
CLR-4 :	Familiarize and execute stability analysis on linear system																						
CLR-5 :	Understand the concept of frequency response and analyze feedback systems																						
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																					
CLO-1 :	Find the transfer function for linear control systems .			2	85	75	H	M	H	L	H	M	M	H	H	M	L	H	H	H	H	H	H
CLO-2 :	Perform time response analysis for standard prototyping systems.			2	80	75	H	M	H	H	H	M	M	M	H	H	M	L	M	H	H	H	H
CLO-3 :	Perform stability analysis for the system under study			2	90	85	H	H	H	H	L	M	M	M	H	M	M	M	M	H	H	H	M
CLO-4 :	Apply frequency analysis for the system under study			2	85	80	H	M	H	H	H	H	H	H	H	H	H	M	H	H	H	H	H
CLO-5 :	Design and implement controllers and compensators for the system under study			2	80	75	H	M	M	M	H	H	H	H	H	H	H	M	H	H	H	H	H

Duration (hour)		Introduction to Feedback Systems	Performance of Feedback Systems	Stability Analysis of Linear System	Frequency Response Analysis of Feedback Systems	Controller Design for Linear Feedback System
		12	12	12	12	12
S-1	SLO-1	Introduction to Systems and its types	Introduction to time response analysis	Introduction to the Concept of Stability	Introduction to Frequency response	Introduction to controllers P,PI,PD,PID
	SLO-2	Examples of automotive feedback systems	Transient response and steady state response	Bounded-input, Bounded-output stability(BIBO)	Sinusoidal excitation and response to a system	Effect of Proportional, Integral and differentiator constants
S-2	SLO-1	ADAS, Engine Management system	Sensitivity of a feedback system	Routh –Hurwitz stability criterion	Introduction to Frequency response plots and performance specification	PID design for an automotive feedback system
	SLO-2	Linear Time invariant systems	Standard test inputs for feedback system analysis	Routh –Hurwitz stability - Basic Numerical Problems	Bode plot - constant gain	Frequency domain interpretation of PID controller
S 3-4	SLO-1	Lab 1:Introduction To Matlab Control System Tool Box, Simulink Tool Box	Lab 3: Simulation of cruise control example using Matlab Simulink	Lab 5: Stability analysis of Second Order UnityFeedback System using Matlab control system toolbox.	Lab 7: Determination Of Bode Plot Using Matlab Control System Toolbox for 2nd Order System & Obtain Controller Specification Parameters.	Lab 9: Implementantion of Proportional-Integral-Derivative (PID) controller using Matlab Control System Toolbox.
	SLO-2					
S-5	SLO-1	Parameter varying system and Nonlinear system	Transient response and steady state response - Numerical Problems	Routh – Hurwitz stability - Basic Numerical Problems Cont.	Bode plot - differentiator ,integrator and second order term	Frequency domain interpretation of PID controller
	SLO-2	Impulse response of a system and transfer function representation	Time response analysis of a first order prototyping system	Routh – Hurwitz stability in controller parameter selection	Phase Margin and Gain Margin fundamentals	PID Numerical Problems
S-6	SLO-1	Transfer function of a D.C motor	Time response analysis of First order prototyping system - Numerical Problems	Stability analysis of tracked vehicle turning control	Procedure to plot bode diagram – Gain margin,Phase margin and stability conditions	Lead compensator,Lag compensator
	SLO-2	Transfer function of Throttle position sensor, Velocity Sensor,Accelerometer Model	Time response analysis - Cruise control model	Stability analysis of tracked vehicle turning control Cont.	Bode Diagram - Numerical Problems	Lead Lag compensators Numerical Examples
S	SLO-1	Lab 1: Transfer Function -	Lab 4:Simulation of suspension system	Lab 6: Determination Of Root Locus Plot	Lab 8: Determination Of Nyquist Plot Using	Lab 10: Designing Compensators using

7-8	SLO-2	DC Motor Speed control Simulink Modeling.	System in Matlab Simulink	And Controller Specifications Using Matlab Control System Toolbox	Matlab Control System Toolbox.	Matlab Simulink
S-9	SLO-1	Introduction to Block diagram algebra	Time response analysis of second order prototyping system	The Root locus procedure for stability analysis	.Polar Plot - Overview	Design of phase lead and phase lag compensation
	SLO-2	Block diagram algebra Numerical examples	Time response analysis of second order prototyping system - Numerical Problems	Root locus Analysis - Basic Problems	.Polar Plot - Numerical Problems	Time domain and frequency domain interpretation of design of phase lead and phase lag compensation
S-10	SLO-1	Introduction to Signal Flow Graph	Complex Plane root location and transient response	Root locus Analysis of speed control system	Nyquist criterion for non-minimum phase system	Notch Filter
	SLO-2	Signal Flow Graph numerical problems	Steady state error of feedback control system - Numerical Problems	Controller design using root locus for a closed loop control system-Numerical Example	Nyquist criterion for non-minimum phase system	Notch Filter Numerical Problems
S 11-12	SLO-1	Lab: Assessment 1	Lab: Assessment 2	Lab: Assessment 3	Lab: Review class	Lab: Mini Project
	SLO-2					

Learning Resources	1. Richard.C.Dorf and Robert.H.Bishop, "Modern Control System" 12th edition Pearson Prentice Hall, 2013. 2. Benjamin.C.Kuo, "Automatic control systems", Prentice Hall of India, 7th Edition, 1995 3. P N J.Nagrath and M.Gopal, "Control System Engineering", New Age International Publishers, 5th Edition, 2007.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, and Conf. Paper etc.

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.Jegan Amirthalingam, Senior Educator, KPIT a.jegan@kpit.com	1. Dr. Teoh Yew Heng, University Sains, Malaysia,yewhengteoh@usm.my	1. Mr.Jesu Godwin D, SRMIST
	2. Mr. Arockiya Vijay, SRMIST, arockiaj1@srmist.edu.in	2. Mr. E. Joshua Paul, SRM IST

Course Code	18AEE411T	Course Name	POWER ELECTRONICS FOR ELECTRIC VEHICLE APPLICATION	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18AEE211J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Define and understand the power semiconductor components and its characteristics	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Distinguish and demonstrate the different DC-DC and AC-AC converters topology	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Interpret and relate the operation, characteristics and performance parameters of rectifiers																		
CLR-4 :	Compare and contrast the operation, switching techniques for various types of DC-AC inverters																		
CLR-5 :	Design and develop the motor drives for automotive motor control applications																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	List and recognize the various power semiconductor devices suitable for motor drive applications	1	90	85	H	M	M	M	L	L	L	L	M	M	L	M	H	M	M
CLO-2 :	Identify and solve the DC-DC and AC-AC converters suitable for the desired requirements	2	90	85	H	H	M	H	M	M	M	L	M	L	M	H	H	H	M
CLO-3 :	Experiment and sketch the various AC-DC Rectifier configurations and their input and output Waveforms	2	85	80	H	H	M	H	M	M	M	L	M	L	M	H	H	H	M
CLO-4 :	Relate and use the DC - AC Inverters with various sources and control techniques	2	85	80	H	H	M	H	M	M	M	L	M	L	M	H	H	H	M
CLO-5 :	Investigate and select the various motor drives suitable for the desired applications	3	85	80	H	H	H	H	M	H	H	M	M	M	M	H	H	H	H

		Automotive Semiconductor Devices	AC -DC Converters	AC-DC Rectifiers	DC - AC Inverters	Automotive Motor Drives
Duration (hour)		09	09	09	09	09
S-1	SLO-1	Introduction to power semiconductor devices	DC-DC Converter - Basics	Half Bridge Diode AC-DC Rectifier	DC-to-AC Conversion- Basics	DC motor drives-introduction
	SLO-2	Diodes - Rectification	DC-DC Converter - Types	Characteristics and Circuit Configuration	DC-to-AC Conversion- Basics.	DC motor drives-Types
S-2	SLO-1	Diodes – Freewheeling	Buck, Boost, and Buck-Boost Converter overview	Full Bridge Diode AC-DC Rectifier	Introduction to Inverters	Torque Production in Brushed DC-Motor Drives
	SLO-2	Diodes - Clamping Devices	Buck, Boost, and Buck-Boost Converter Circuit overview	Characteristics and Circuit Configuration	Types of Inverters overview	Torque Production in Brushed DC-Motor Drives.
S-3	SLO-1	Power MOSFETs - Characteristics	Buck Converter - Components	Three-Phase Full-Bridge Diode Rectifier - Circuit Configuration	Voltage Source Inverters-Single phase inverters	Series connected DC motor drives
	SLO-2	Power MOSFETs - Low-Voltage Load Drivers	Buck Converter - circuit	Three-Phase Full-Bridge Diode Rectifier - Analysis	Voltage Source Inverters-Single phase Inverters applications	Series connected DC motor drives.
S-4	SLO-1	IGBTs - Characteristics	Buck Converter - Analysis	Three-Phase Full-Bridge Diode Rectifier - Waveforms	Voltage Source Inverters -Three phase Inverters`	Induction Motor Drives -Introduction
	SLO-2	IGBTs - High-Voltage Power Switches	Buck Converter	Design of Dynamic Breaking Unit	Voltage Source Inverters -Three phase Inverters applications	Induction Motor Drives.
S-5	SLO-1	Power Integrated Circuits	Boost Converter - Components	Design of Dynamic Breaking Unit.	Current Source inverters	Induction motor Variable Speed Drive operating modes
	SLO-2	Power Integrated Circuits Examples	Boost Converter - Circuit	Calculation of DC-Link Power	Current Source inverters applications	Induction motor Variable Speed Drive operating modes.
S-6	SLO-1	Smart Power Devices	Boost Converter - Analysis	Calculation of DC-Link Power	Voltage Control Techniques – Sinusoidal PWM (SPWM) Technique	Torque and speed control of Induction - Motor Drives
	SLO-2	Smart Power Devices.	Boost Converter - Analysis.	Three-Phase Full-Bridge. Thyristor AC-DC Rectifier-Circuit Configuration	Voltage Control Techniques – Sinusoidal PWM (SPWM) Techniques.	Torque and speed control of Induction - Motor Drives.
S-7	SLO-1	Emerging Device Technologies - Super-Junction	Buck-Boost Converter - Components	Three-Phase Full-Bridge Thyristor AC-DC Rectifier-Analysis	Current control techniques - HysteresisCurrent Control	Fundamentals of Scalar and vector control for induction motors

	SLO-2	Emerging Device Technologies - Super-Junction.	Buck-Boost Converter - Circuit	Three-Phase Full-Bridge Thyristor AC-DC Rectifier-Waveforms	Current control techniques – Hysteresis Current Control	Types of scalar control for induction motors
S-8	SLO-1	Emerging Device Technologies - SiC Devices	Buck-Boost Converter - Analysis	Topology and Operation Modes	Multilevel inverters	Vector control for induction motors.
	SLO-2	Emerging Device Technologies - SiC Devices.	Push-Pull Converter - Half Bridge	Topology and Operation Modes.	Multilevel inverters.	Types of vector control for induction motors.
S-9	SLO-1	Power Losses in semiconductors	Push-Pull Converter - Full Bridge	Fire Angle Control Scheme	Hard Switching Effects	Induction motor drives for Electric Vehicles
	SLO-2	Thermal Management in semiconductors	AC- AC Converters	Fire Angle Control Scheme.	Hard Switching Effects. .	Induction motor drives for Electric Vehicles.

Learning Resources	1. Ali_Emadi" Handbook of automotive power electronics and motor drives",3rd Edition, 2014 2. Ned Mohan, T.M.Undeland, W.P.Robbins," Power Electronics: Converters, applications and design", John wiley and Sons, 3rd Edition, 2006. 3. Rashid M.H., "Power Electronics Circuits, Devices and Applications", Prentice Hall India, 3rd Edition, New Delhi, 2004
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, and Conf. Paper etc.

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		2. Mr.Jesu Godwin D, SRMIST

Course Code	18AEE412T	Course Name	STATE SPACE ANALYSIS AND DIGITAL CONTROL SYSTEM	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	18AEE317J	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:		Learning			Program Learning Outcomes (PLO)																	
CLR-1 :	Define and understand the basics of discrete systems and digital control			Level of Thinking (Bloom)	2	3	1	2	3	Engineering Knowledge	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Design and implement digital controllers for discrete time models						Expected Proficiency (%)	Expected Attainment (%)																
CLR-3 :	Formulate state space models for dynamics system																							
CLR-4 :	Acquire the fundamentals of pole placement design and state observers																							
CLR-5 :	Explore the techniques involved in optimal control design																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1 :	List and recognize the various discrete systems and digital control			1	90	85	H	M	M	M	L	L	L	L	M	M	L	M	M	L	M	H	M	M
CLO-2 :	Identify and solve the various digital controllers for discrete time models			2	90	85	H	H	M	H	M	M	M	M	M	L	M	L	M	M	H	H	H	M
CLO-3 :	Experiment on the various state space models for dynamics systems			2	85	80	H	H	M	H	M	M	M	M	M	L	M	L	M	M	H	H	H	M
CLO-4 :	Relate and use the pole placement design and state observers			2	85	80	H	H	M	H	M	M	M	M	M	L	M	L	M	M	H	H	H	M
CLO-5 :	Investigate and implement the optimal control design			3	85	80	H	H	H	H	M	H	H	H	M	M	M	M	M	M	H	H	H	H

	Signal Processing in Digital Control	Models of Digital Control Systems and Algorithm	Control System Analysis With State Variable Methods	Pole Placement Design and State Observers	Lyapunov Stability Analysis and Optimal Control
Duration (hour)	09	09	09	09	09
S-1	SLO-1 Introduction Signal Processing	Introduction to Z transform	Introduction to state space analysis	State feedback Overview	Basic stability definitions
	SLO-2 Control system terminologies	Z domain specification	State variable representation of system	Stability improvement by state feedback	Theorems on stability
S-2	SLO-1 Classical approach to analog controller design	Z-domain description of sampled continuous time plant	State variable representation.	Introduction to Pole Placement	Sign definiteness of functions and matrices
	SLO-2 Classical approach to analog controller design. Cont	Z-domain description of sampled continuous time plant. Cont	State space analysis of systems overview	Necessary and sufficient conditions for arbitrary pole-placement	Lyapunov Stability Theorems for linear and nonlinear systems
S-3	SLO-1 Introduction to digital control system	Implementation of Digital controllers	State space analysis of systems. Cont	Voltage Source Inverters-Single phase inverters	Lyapunov's first or indirect method
	SLO-2 Configuration of basic digital control system scheme	PI,PD,PID controllers	Conversion of transfer function to state variable model	State regulator design	Lyapunov's second or direct method
S-4	SLO-1 Basic discrete time signals	Tunable PID controller	Transfer function to state variable model numerical Examples	State regulator design.	Lyapunov function candidate and Matrix Equation
	SLO-2 Time domain models of discrete time system	Tunable PID Speed Control problem	Transfer function to state variable model numerical Examples. Cont	State observers	Parameter Optimization
S-5	SLO-1 Transfer function Overview	Conversion of Canonical state variable to transfer function model	Conversion of Canonical state variable to transfer function model	Design of state observers	Optimal control examples
	SLO-2 Transfer function Models	Digital temperature control	Conversion of Canonical state variable to transfer function model Numerical Examples	State observers for linear systems	Performance indices
S-6	SLO-1 Transfer function Models.	Concepts of controllability	State observers for linear systems	State observers for non- linear systems	Quadratic Performance index
	SLO-2 Introduction to Stability analysis	Z-plane specification for control system design	State observers for linear systems Examples	State observers examples.	Quadratic Performance index example
S-7	SLO-1 Stability on z-plane and the Jury stability criterion	Z-plane specification for control system design.	Concept of observability Numerical examples	Digital control system with state feedback	Performance indices examples

	SLO-2	Sampling as impulse Modulation	Introduction to digital compensator	State feedback with integral control	State feedback with integral control	Quadratic Performance index example State regulator design
S-8	SLO-1	Practical aspects on the choice of sampling rate	Digital compensator design using frequency response	Multivariable control system overview.	Dead beat control concept	State regulator design through Lyapunov equation
	SLO-2	Principles of Discretization	Digital compensator design using frequency response.	Multivariable control system Numerical Examples	Multilevel inverters.	Duality and Observability
S-9	SLO-1	Routh Stability criterion	Digital compensator design using root locus plots	Digital state space Models	Dead beat control by state feedback and Dead beat observers	Optimal state regulator through the matrix riccati equation
	SLO-2	Routh Stability criterion-.	Digital compensator design using root locus plots.	Digital state space Models Examples	System identification and adaptive control	Optimal digital control systems

Learning Resources	1. M G opal "Digital Control and State Variable Methods", 4th edition, Tata McGraw Hill Education Pvt.Ltd. 2012 2. Kats uhiko Ogata "Discrete time control system" 2nd edition ,Prentice Hall Pvt.Ltd,2012 3. J.Nagrath and M.Gopal, "Control System Engineering", New Age International publishers, 5th Edition, 2007.	2. Richard.C.Dorf and Robert.H.Bishop, "Modern Control System" 12th edition Pearson Prentice Hall, 2013. 3. Benjamin.C.Kuo, "Automatic control systems", Prentice Hall of India, 7 th Edition,1995.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, and Conf. Paper etc.

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.Jegan Amirthalingam, Senior Educator, KPIT a.jegan@kpit.com	1. Mr. Arockiya Vijay, SRMIST, arockiaj1@srmist.edu.in	1. Mr.Jesu Godwin D, SRMIST
	2. Dr. P. Sathish Kumar, Jiangsu University, China sathishkumar8989@gmail.com	2. Mr. E. Joshua Paul, SRMIST

Course Code	18AEE413T	Course Name	MODEL BASED SYSTEM DESIGN	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18AEE317J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:		Learning			Program Learning Outcomes (PLO)															
CLR-1 :	Define and Understand the concept of V-development approach in automotive controller design	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Distinguish and demonstrate the different modelling techniques used in model based system design				Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3			
CLR-3 :	Understand the architecture of ECU and Rapid prototyping Hardware				H	M	M	M	L	L	L	L	M	M	L	M	H	H	H	M		
CLR-4 :	Understand the concept of real time simulation and HIL simulation				H	H	M	H	M	M	M	L	M	L	M	H	H	H	H	M		
CLR-5 :	Create models of physical systems using design of experiment methods				H	H	M	H	M	M	M	L	M	L	M	M	H	H	H	M		
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	Identify and Build mathematical models for components in a system.	1	90	85	H	M	M	M	L	L	L	L	M	M	L	M	L	M	H	M	M	M
CLO-2 :	Investigate on the continuous refinement and improvement to generate accurate models	2	90	85	H	H	M	H	M	M	M	M	L	M	L	M	L	M	H	H	H	M
CLO-3 :	Experiment and run Hardware-in-the-Loop Simulations (HIL)	2	85	80	H	H	M	H	M	M	M	M	L	M	L	M	L	M	H	H	H	M
CLO-4 :	Relate and apply basic control algorithms to a real physical system	2	85	80	H	H	M	H	M	M	M	M	L	M	L	M	L	M	H	H	H	M
CLO-5 :	Apply verification and validation methods to a physical system model	3	85	80	H	H	H	H	M	H	H	H	M	M	M	M	M	M	H	H	H	H

		Model Based Design Approach	Modelling Techniques and development	ECU Architecture and Design	Real-time Simulation	Model Based System Design Application
Duration (hour)		09	09	09	09	09
S-1	SLO-1	Introduction to design process	Introduction to graphical modelling	Rapid Prototyping hardware architecture and features	Introduction to real-time simulation	Introduction to model based system design software tools
	SLO-2	Design validation and verification and requirements	State Flow Modelling	Programming analog ,digital interface	Standalone Plant Simulation	Overview of Simulink and Sim driveline
S-2	SLO-1	Design process implementation	State machines Modelling	Protocol interface and implementing controller	Standalone Controller Simulation	Modelling a series hybrid electric vehicle in Sim drive line
	SLO-2	Introduction to model based design	Algorithmic models	ECU Design - Need for ECUs	Plant and controller simulation on single target	Modelling a series hybrid electric vehicle in Sim drive line.Cont
S-3	SLO-1	Model based design in functional level	Transfer function modelling	Advances in ECUs for automotive application	Plant and controller simulation on single target.Cont	Driver model in Simulink
	SLO-2	Model based design in Architecture level	State space modelling	Requirements for ECU design	RT simulation by Separating the plant from the controller	Battery model in Simulink
S-4	SLO-1	Model based design in implementation level	Event based Modelling	Design complexities of ECU	Real-time simulation.Cont	Modelling electric motor in Simulink
	SLO-2	Key barriers in adaptation of model based engineering	Statistical modelling for system identification	Selection of sensors for ECU design	Controller and Plant on real time target	Modelling speed tracking controller model in Simulink
S-5	SLO-1	Introduction to V-development cycle	Mathematical Modelling for automotive applications	Selection of interfaces for ECU design	Controller and Plant on real time target Cont.	Modelling of a single cylinder IC engine in powertrain block set
	SLO-2	V-developments cycle significance	Simple motor and generator model	Selection of actuators for ECU design	V and V using HIL RT Model	Modelling of a single cylinder IC engine in powertrain block set.Cont
S-6	SLO-1	V-development cycle in automotive domain	Simple IC engine model, Controller model	Selection of actuators for ECU design .Cont	V and V using HIL RT Model case study	Modeling of an IC engine controller in powertrain block set
	SLO-2	Rapid control prototyping	IC engine Controller model	ECU Hardware -Architecture of an advanced Microcontroller	Implementation of communication interfaces	Modeling of an IC engine controller in powertrain blockset.Cont
S-7	SLO-1	Model-in-loop simulation	Quarter car model	Overview of on chip peripherals	Verification of communication interfaces	Virtual modelling of electrified powertrains

	SLO-2	Software-in-loop simulation	Cruise control model	ECU on chip peripherals.Cont	A/D Outputs implementation	Virtual modelling of electrified powertrains.Cont
S-8	SLO-1	Hardware-in-loop simulation	Motor model and development.	ECU protocol interfaces	Control algorithm implementation	Development a hybrid vehicle model
	SLO-2	Processor in the loop simulation	Generator model Development.	GPIO on the advanced Microcontroller ECU	Timing requirements in control algorithm	Development a hybrid vehicle model. Cont
S-9	SLO-1	Vehicle in the loop simulation	Motor controller model and development.	Overview of ECU programming	Verification of timing requirements in control algorithm	Supervisory logic implementation of Hybrid vehicle.
	SLO-2	Constraints in HIL,MIL,SIL,PIL	Motor controller model and development. Cont	ECU interface challenges	Control algorithm optimization	HIL simulation of Hybrid vehicle.

Learning Resources	1. Pete r Wilson and H.AlanMantooth "Model based Engineering for complex Electronics system" 2013,Newness 2. Web course by Zachariah chambers and Marc Herniter –Rose Hulman institute of technology on "Introduction to model based design and Advanced model based design." 3.Rashid M.H., "Power Electronics Circuits, Devices and Applications", Prentice Hall India, 3rd Edition, New Delhi, 2004
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Learning Assessment											
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		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Understand	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Apply										
Level 3	Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, and Conf. Paper etc.

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2. Jonny N, BGR Energy systems, jonnynallathampi@gmail.com	2. Mr. Arockiya Vijay, SRMIST, arockiaj1@srmist.edu.in	2. Mr.Jesu Godwin D, SRMIST

Course Code	18AEE414J	Course Name	MODELLING AND CONTROL OF ELECTRIC AND HYBRID VEHICLES	Course Category	E	Professional Elective	L	T	P	C
							2	0	2	3

Pre-requisite Courses	18AEE317J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	State and classify the electric and hybrid power train technologies				Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Investigate and interpret the performance characteristics of EV / HEV power train components																							
CLR-3 :	Classify and test the various EV / HEV energy storage technologies																							
CLR-4 :	Develop and relate the various Energy management control techniques for EV and HEV vehicles																							
CLR-5 :	Formulate and implement the Vehicle Dynamics Control Systems for EV and HEV vehicles																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1 :	Compare and operate the different electric and hybrid vehicle power train configuration.				1,2	90	85	H	M	M	M	L	L	M	L	L	L	L	L	M	H	M	M	
CLO-2 :	Demonstrate and design the EV / HEV power train model and its components.				2,3	85	80	H	H	H	H	M	M	H	L	M	M	L	M	H	H	H	H	
CLO-3 :	Identify and examine the storage batteries, fuel cells and ultra capacitors used in vehicles.				1,2	85	80	H	M	M	M	L	L	M	L	L	L	L	M	H	H	M		
CLO-4 :	Construct and solve the EV / HEV power and energy management systems.				2,3	85	80	H	H	H	H	L	M	H	L	M	M	L	M	H	H	M		
CLO-5 :	Design the driver, vehicle, environmental model of EV/HEV dynamics control system				2,3	85	80	H	H	H	H	M	M	H	L	L	M	L	M	H	H	H		

		Electric and Hybrid Power train Technologies	Modelling and Characteristics of EV/HEV Power train Components	Energy Storage	Energy, Power Management Systems And Techniques For EV and HEV
Duration (hour)		12	12	12	12
S-1	SLO-1	Introduction to Battery Electric Vehicles (BEV's) – Power train Configuration, Traction	Electric Motor Performance characteristics – Power and torque generation	Electro chemical batteries- Electro chemical reactions	Power /Energy management controllers
	SLO-2	Introduction to Battery Electric Vehicles (BEV's) – Energy sources and storage	Electric Motor Performance characteristics – Efficiency, DC Motors	Electro chemical batteries- Electro chemical reactions	Power /Energy management controllers. Cont
S-2	SLO-1	Fuel Cell Electric vehicle (FCEV) technologies	Electric Motor Performance characteristics – Induction AC motors, Steady state Performance analysis	Battery technologies – Lead acid battery	Battery Management system (BMS) for EV and HEV
	SLO-2	Fuel Cell Electric vehicle (FCEV) technologies	Electric Motor Performance characteristics – Permanent Magnet AC Motors ,BLDC motors	Battery technologies –Nickel based batteries	Battery Management system (BMS) for EV and HEV
S-3-4	SLO-1	Lab 1: Introduction Lab	Lab 4: Data acquisition using data loggers and virtual instrumentation hardware	Lab 7: Testing and validation of Electric Vehicle Battery	Lab 10: Direction control of Electric Vehicle motors
	SLO-2				
S-5	SLO-1	Hybrid Electric Vehicles- Degree of Hybridization, Parallel hybrid	Battery Performance Characteristics- Battery Capacity, Open circuit terminal voltages	Lithium based batteries –Lithium polymer	Rule based Control Strategies for HEV and PHEV –Deterministic Rule-based ,Fuzzy rule based control strategies
	SLO-2	Hybrid Electric Vehicles-Series Hybrid	Battery Performance Characteristics-Charge and Discharge rates	Lithium based batteries –Lithium polymer	Rule based Control Strategies for HEV and PHEV –Deterministic Rule-based, Fuzzy rule based control strategies.
S-6	SLO-1	Hybrid Electric Vehicles-Power split	Battery Performance Characteristics-SOC, SOD, DOD	Lithium based batteries –Lithium ion	Optimization based Control Strategies – Optimization Problem formulation
	SLO-2	Hybrid Electric Vehicles-compound Hybrid Configuration	Battery Performance Characteristics-Battery Energy Density, power density	Lithium based batteries –Lithium ion	Optimization based Control Strategies – Optimization Problem formulation.

S 7-8	SLO-1	Lab 2: Introduction to Virtual Instrumentation and Rapid control prototyping hardware	Lab 5: Interfacing Analog input ,Signal conditioning using control hardware	Lab 8: Testing and Validation of Electric Motor for power assisted Steering system	Lab 11: Electronic differential Design for Electric Vehicles	Lab 14: Lab Model Examination
	SLO-2					
S-9	SLO-1	Plug-in Hybrid Electric Vehicles (PHEV's)	Battery Performance Characteristics-Specific energy and Specific Power	Ultra-capacitors –Basic principle, Performance, Ultra High speed flywheels	Global Energy/Power Management Optimization	VDC System Overview
	SLO-2	Hybrid Hydraulic vehicles (HHV)	Inverters and Motor drives	Ultra-capacitors –Basic principle, Performance, Ultra High speed flywheels	Real-time Energy/Power Management Optimization.	VDC implementation on Electric and Hybrid Vehicles-structure of the control system
S-10	SLO-1	Pneumatic Hybrid Vehicles (PHVs)	Inverters and Motor drives	Fuel cells –Principle, working , requirements and specifications	Optimization techniques	VDC implementation on Electric and Hybrid Vehicles-structure of the control system.
	SLO-2	Power/Energy Management System	Regenerative Braking Characteristics	Fuel cells –Principle, working , requirements and specifications	Optimization techniques	Control system Design and simulation study
S 11-12	SLO-1	Lab 3:Control prototyping using graphical programming methods Control prototyping using graphical programming methods	Lab 6: Control of actuators with Rapid control prototyping hardware	Lab 9: Speed control for Electric Vehicle motors	Lab 12: Revision	Lab 15: Evaluation & Discussion
	SLO-2					

Learning Resources	1. Amir Khajepour, M. Saber Fallah, AvestaGoodarzi-"Electric and Hybrid Vehicles Technologies, Modeling and Control" - A Mechatronic Approach-Wiley Publication,2014 2. Iqbal Husain, "Electric and Hybrid vehicles Design Fundamentals" , CRC Press,second edition 2013 3. James Larminie, John Lowry, "Electric vehicle technology Explained" secondEdition, Wiley Publication, 2012	4. Ali Emadi, MehrdadEhsani, John M. Muller,"Vehicular Electric Power Systems" Marcel Dekker, Inc., 2004 5. Electric vehicle Laboratory Manual 6. NI Systems "Compact Rio" Lab Manual
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, and Conf. Paper etc.

Course Designers		
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1. Mr.Jegan Amirthalingam, Senior Educator, KPIT a.jegan@kpit.com	1. Mr. Arockiya Vijay, SRMIST, arockiaj1@srmist.edu.in	1. Mr. Srividya K, SRMIST
		2. Mr.Jesu Godwin D, SRMIST

Course Code	18AEE415T	Course Name	VEHICLE STABILITY AND CONTROL SYSTEMS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18AEE317J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Define the concepts of vehicle stability and fundamentals of vehicle dynamics.	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Design and Develop Vehicle, Road and driver models.		
CLR-3 :	Understand Longitudinal and Lateral stability control schemes		
CLR-4 :	Distinguish between the effects of Longitudinal and Lateral stability		
CLR-5 :	Interpret the relation between vertical dynamics and ride stability control		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom) Expected Proficiency (%) Expected Attainment (%)	Engineering Knowledge Problem Analysis Design & Development Analysis, Design, Research Modern Tool Usage Society & Culture Environment & Sustainability Ethics Individual & Team Work Communication Project Mgt. & Finance Life Long Learning PSO - 1 PSO - 2 PSO - 3
CLO-1 :	Use and Relate fundamental mathematical concepts to create a Vehicle Model	1,2 90 85	H H H H M L L L M M H H L L M
CLO-2 :	Identify and Optimize parameters like driver behavior and road quality as inputs to check vehicle stability	2,3 85 80	H H H H H M M L H M L M M H M
CLO-3 :	Recognize the effects of Longitudinal and Lateral stability	1,2 85 80	H H H H H L M M H M H H H H
CLO-4 :	Design and check a vehicle for longitudinal and lateral stability	2,3 85 80	H H H H H M M H H H M H M H M
CLO-5 :	Create mathematical models of suspension behavior and control	2,3 85 80	H H H H H M M M M M M H M M M

Duration (hour)	Introduction to Vehicle Stability	Vehicle, Road and Driver Modeling	Longitudinal Dynamics and Control	Lateral Dynamics and Control	Vertical Dynamics and Control
	9	9	9	9	9
S-1	SLO-1 Introduction to stability of motion	Introduction to Vehicle Modeling	Introduction to longitudinal control	Automated lane keeping	Introduction to Automotive Suspension
	SLO-2 Concept and analysis of stability in motion	Introduction to Vehicle Modeling	Adaptive Cruise Control	Steering control for automated lane keeping	Passive suspension
S-2	SLO-1 Static stability	Vehicle Modeling	Collision avoidance system	Lane keeping with Bicycle model	Quarter Car model – passive suspension
	SLO-2 Dynamic stability	Vehicle Modeling. Cont	Automated Highway systems	Lane keeping with Bicycle model - state feedback	Active suspension system
S-3	SLO-1 Mathematical forms for vehicle dynamic equations	Friction coefficient	Cruise controller design	Steady state error from dynamic equation	Tradeoffs and Limitation of Active suspension
	SLO-2 Mathematical forms for vehicle dynamic equations	Calculation of forces	PI Controller for first order plant	Steady state error from dynamic equation. Cont	Performance variable of quarter car suspension
S-4	SLO-1 Eigen values	Tire modelling	PI Controller for second order plant	Unity feedback loop system	Natural Frequencies for the Quarter Car
	SLO-2 Eigen values. Cont	Tire Characteristics	PID Cruise-controller design for second order actuator	Unity feedback loop system. Cont	Mode Shapes for the Quarter Car
S-5	SLO-1 Routh's stability	Effect of Wheel radius	Autonomous cruise control –Speed control	Loop analysis with a proportional controller	Approximate Transfer Functions Using Decoupling
	SLO-2 Routh's stability criterion. Cont	Effect of Wheel radius. Cont	Autonomous cruise control –Headway control	Loop analysis with a proportional controller. Cont	Approximate Transfer Functions Using Decoupling. Cont
S-6	SLO-1 Co-ordinates of vehicle dynamics model	Two track models	Adaptive cruise control –Cruise control with preview based on onsite information	Loop analysis with a lead compensator	Verification Using the Complete Quarter Model
	SLO-2 Notation of vehicle dynamics model	Reduced two track non-linear model	Adaptive cruise control –Cruise control with preview based on onsite information	Loop analysis with a lead compensator. Cont	Verification Using the Complete Quarter Model. Cont
S-7	SLO-1 Longitudinal vehicle motion –During acceleration	Road Model – Requirements of road model	Vehicle Platooning	Simulation of performance with Lead compensator	Optimal passive Suspension with 2DOF model

	SLO-2	Longitudinal vehicle motion –During Braking	Course path of a Road Models	String stability	Simulation of performance with Lead compensator. Cont	Optimal active Suspension with 2DOF model. Cont
S-8	SLO-1	Vertical vehicle motion	Road surface quality	ACC –Autonomous control with constant spacing	Overview of four wheel steering	Linear Quadratic control
	SLO-2	One DOF quarter car model	Wind Strength - Effects	ACC –Autonomous control with constant time gap policy	Four wheel steering system numerical example	LQR Applications - active suspension
S-9	SLO-1	Lateral vehicle motion –Bicycle model	Human factors in driver automation	String stability of CTG spacing Policy	Yaw rate and acceleration response	LQR formulation for active suspension design
	SLO-2	Bicycle model in steady state cornering	Simple PID driver Model	String stability of CTG spacing Policy. Cont	Lane Change Maneuver – 2WS VS 4WS	LQR formulation for active suspension design. Cont

Learning Resources	1. Dean Karnopp "Vehicle Dynamics, Stability, and Control", 2nd edition, CRC Press, 2013 2. A.GalipUlsoy, HeuiPeng, Melih C "Automotive Control System", Cambridge University Press 2012	3. Rajesh Rajamani "Vehicle Dynamics and Control", Second Edition, Springer 2012 4. Kiencke U and Nielsen L "Automotive Control Systems for Engine, Driveline and Vehicle" 2nd edition, Springer 2005
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

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Course Code	18AEE416T	Course Name	AUTOMOTIVE FAULT DIAGNOSTICS	Course Category	C	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand the importance and procedure of fault diagnostics in for automotive field.	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Familiarize the fault diagnostics using tools and equipment	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Know about various case studies in fault diagnosis																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Understand the concept of fault diagnosis	2	85	75	H	M	H	L	H	M	M	H	H	M	L	H	H	H	H
CLO-2 :	Understand about on and off board diagnostics	2	80	75	H	M	H	H	H	M	M	H	H	M	L	M	H	H	H
CLO-3 :	Perform fault diagnosis in automobiles	2	90	85	H	H	H	H	L	M	M	H	M	M	M	H	H	H	M
CLO-4 :	Understand the various advances in fault diagnosis	2	85	80	H	M	H	H	H	H	H	H	H	M	M	H	H	H	H
CLO-5 :	Perform electrical systems diagnosis in automobiles	2	80	75	H	M	M	M	H	H	H	H	H	H	M	H	H	H	H

Duration (hour)	Introduction Fault Diagnosis	On and off Board Diagnostics	Engine System Diagnosis	Chassis and Brake System Diagnosis	Electrical Systems Diagnosis
	9	9	9	9	9
S-1	SLO-1 Introduction To Fault Diagnosis, SLO-2 Safe Working Practices And Techniques	Introduction To ON and OFF Board Diagnostics	Introduction Engine Systems Diagnostics	Introduction To Engine System Diagnostics	Introduction to electrical components and Circuits
S-2	SLO-1 Diagnostics On Paper SLO-2 Systems And Standards	Introduction To Oscilloscope Diagnostics	Engine Operation And Fuel System	Anti-Lock Braking System Diagnostics	Sensing, signal conditioning overview
S-3	SLO-1 Mechanical And Electrical Diagnostic Techniques SLO-2	Sensors Associated With Oscilloscope Diagnostics	Ignition System And Emission System	Traction Control System Diagnostics	Multiplexing, Demultiplexing overview
S-4	SLO-1 Faults Codes SLO-2	Actuators Associated With Oscilloscope Diagnostics	Electronic Fuel Injection Diagnostics	Traction Control System Diagnostics - Steering	Lighting System Faults
S-5	SLO-1 On - And - Off Board Diagnostics SLO-2	On-Board Diagnostics Various Perspectives	Starting And Charging System Diagnostics	Traction Control System Diagnostics - Tires	Auxiliary Faults
S-6	SLO-1 Data Sources SLO-2 Tools And Equipment's	Petrol/Gasoline On-Board Diagnostics	Power Flow Control And Energy Efficiency Analysis	Transmission Systems Diagnostics	In-Car Entertainment Security And Communications Implementation
S-7	SLO-1 Oscilloscopes SLO-2 Scanners/Fault Code Readers,	On-Board Sensors	Engine Management And Faultfinding Information	Diagnostics On Steering	Body-Electrical Systems, Instruments System Faults
S-8	SLO-1 Engine Analyzers SLO-2	On-Board Actuators	Air Supply, Exhaust System Diagnostics	Diagnostics On Tires	Heating Ventilation And Air Conditioning electrical faults
S-9	SLO-1 Application Methods And Procedure SLO-2	Sensors And Actuators Comparative Case Study	Cooling And Lubrication System	Case Study On Diagnostics Of Sub-Assemblies	Cruise Control, Air Bags Electrical faults

Learning Resources	<ol style="list-style-type: none"> Tom denton "Advanced automotive fault diagnosis", Elsevier butterworth-heinemannlinacre house, jordan hill, oxford ox2 8dp, uk - isbn-10: 0-75-066991-8 Tom Denton "Automotive Electronics Handbook", McGraw-Hill Publishing Co.; 2nd Revised edition 1999, ISBN10:0070344531 	<ol style="list-style-type: none"> Routledge "Automobile Electrical and Electronic Systems", 4 edition 2012, ISBN10:0080969429 Newnes "Understanding Automotive Electronics", 6th Revised edition 2003,ISBN10:0750675993
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, and Conf. Paper etc.

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.G.Giri Atalon <i>giri@atalon.co.in</i>	1. Dr. P. Sathish Kumar, <i>Jiangsu University, China sathishkumar8989@gmail.com</i>	1. Mr. S.Kiran, <i>SRMIST</i>
2. Jonny N, <i>BGR Energy systems, jonnynallathampi@gmail.com</i>		2. Mr.Jesu Godwin D, <i>SRMIST</i>

Course Code	18AEE417T	Course Name	ELECTRONIC ENGINE MANAGEMENT SYSTEM	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Automobile Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1:	Understand the components and operation of engine management systems.	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2:	Learn about the various Engine sensors and actuators		
CLR-3:	Learn about the various SI engine electronic ignition and injection systems		
CLR-4:	Understand the various CI engine electronic ignition and injection systems		
CLR-5:	Understand and study the engine emission control systems.		
CLR-6:	Understand the concept of on board diagnostic systems and system data		

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1:	Apply knowledge on modern engine control strategies	2	75	73	H	L	M	M	L	L	L	L	L	L	L	L	H	M	L
CLO-2:	Analyze basic electrical and electronic devices and sensors, Ignition and Fuel Injection Systems involved in SI engine management	1	80	78	H	H	L	L	L	L	M	L	M	L	L	M	H	L	L
CLO-3:	Analyze basic electrical and electronic devices and sensors, Ignition and Fuel Injection Systems involved in CI engine management	2	75	73	H	L	M	M	L	L	L	L	L	L	L	L	H	M	L
CLO-4:	Understand the role of various actuators in engine management	2	85	80	H	L	H	H	L	L	M	L	L	L	L	M	H	L	L
CLO-5:	Describe the key Computer controlled engine Systems	2	75	72	H	L	M	M	L	L	L	L	M	L	L	L	H	M	L
CLO-6:	Access, and interpret on board diagnostic system information	2	75	73	H	L	M	M	L	L	L	L	M	L	L	L	H	M	L

Duration (hour)	Fundamentals of Automotive Electronics and control	Sensors and Actuators	SI Engine Management	CI Engine Management	Digital Engine Control System
	9	9	9	9	9
S-1	SLO-1 Introduction to Electronic Engine management System	Inductive, Hall Effect sensors	Layout and working of SI engine management systems	Introduction to CI engine management	Engine Mapping
S-2	SLO-1 Open and Closed loop control strategies	Thermistor, Piezo Electric sensors	Group and sequential injection techniques	Fuel injection system parameters affecting combustion	Effect of Air-fuel ratio/Spark timing/Exhaust gas Re circulation
S-3	SLO-2 Piezo resistive based sensors	Throttle position, Mass air flow sensors	Contactless (Breaker less) Electronic ignition system	Noise in CI engines	knock control algorithm
S-4	SLO-1 Electronic Fuel Injection Systems	Crank shaft position and Cam position sensors	Solid state ignition system	Emissions from CI engines	EGR Control algorithm
S-5	SLO-2 Single-Point, Multi-Point Fuel Injection systems	Engine Speed sensor, Knock Sensor	K - Jetronic, L - Jetronic fuel injection system	Electronically controlled Unit injection system	Integrated engine control system
S-6	SLO-1 Starter Motor working	Exhaust oxygen level sensor (two step, linear lambda and wide band)	Cold start and warm up phases, idle speed control	Common rail Diesel injection system	Electromagnetic compatibility
S-7	SLO-2 Introduction to Engine control	Manifold temperature and pressure sensors	Acceleration and full load enrichment, Deceleration fuel cut off, Fuel control maps	Diesel injection system components Principle and working	EMI suppression techniques
S-8	SLO-1 Look up tables	Solenoid and stepper motor	Electronic spark timing and control, Spark advance, Spark Retardation	Fuel pump, Fuel injector	On board diagnostics Tool
S-9	SLO-2 Fuzzy logic control technique	Relay (four and five pin)	Closed loop control of knock	Rail pressure limiter, Flow meter, EGR valve	Trouble shooting on EMS and On board diagnostics system
	SLO-1 Adaptive control techniques				
	SLO-2 SI and CI Engine Control				
	SLO-1 Combustion Performance and emission Parameters				
	SLO-2				

Learning Resources	1. <i>Understanding Automotive Electronics 8th Edition</i> Authors: William Ribbens Paperback ISBN: 9780128104347 Imprint: Butterworth-Heinemann Published Date: 18th June 2017 2. Tom Denton "Automotive Electronics Handbook", - - McGraw-Hill Publishing Co.; 2nd Revised edition, 1999, ISBN10:0070344531	3. <i>Diesel-Engine Management Hardcover – 20 Jan 2006</i> by Robert Bosch GmbH (Author), SAE Publications 4. <i>Gasoline Engine Management (Bosch Professional Automotive Information) Paperback – 13 Aug 2014, SAE Publications</i> 5. <i>Automotive Fuel and Emissions Control Systems, 4th Edition James D. Halderman ©2016 Pearson</i>
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, and Conf. Paper etc.

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.Jegan Amirthalingam, Senior Educator, KPIT a.jegan@kpit.com	1. Dr, Teoh Yew Heng, University Sains, Malaysia, yewhengteoh@usm.my	1. Mr. S.Kiran, SRMIST
2. Mr.G.Giri Atalon giri@atalon.co.in	2. Mr. Sam Jebakumar, SRM IST, jebakumj@srmist.edu.in	2. Mr.Jesu Godwin D, SRMIST

ACADEMIC CURRICULA

Professional Elective Courses

BIOTECHNOLOGY

Regulations - 2018



SRM INSTITUTE OF SCIENCE AND TECHNOLOGY

(Deemed to be University u/s 3 of UGC Act, 1956)

Kattankulathur, Kancheepuram, Tamil Nadu, India

Course Code	18BTE301T	Course Name	DEVELOPMENTAL BIOLOGY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Biotechnology	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1:	Describe the mechanisms of developmental patterning and organization	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Discuss fertilization, gametogenesis and sex determination																		
CLR-3:	Compare developmental patterns among metazoan, drosophila and zebrafish																		
CLR-4:	Explain somites and their derivatives.																		
CLR-5:	Describe metamorphosis and organogenesis																		
CLR-6:	Analyze birth defects and endocrine disruptors																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1:	Analyze the mechanisms of cell to cell communication	1	80	80	L	H	H	H		M	L	H	H	H	H	H	L	H	H
CLO-2:	Describe the fundamental organization of reproduction and flowering in plants	2	85	75	M	H	H	M			M	H	L	H	H	H	L	H	H
CLO-3:	Explain the concepts and experiments in the early development, cleavage and axis formation	2	75	80	M	H	M	H	M	M		M	H	H	H	H	L	H	H
CLO-4:	Recognize the various pathways of organogenesis	2	85	80	L	H	H	H			H	L	L	H	H	H	M	H	H
CLO-5:	Discuss about the various endocrine receptors	3	85	75	L	H	H	M		M	H	H	H	L	H	H	H	H	H
CLO-6:	Explain the concepts of development in health and diseases	2	80	80	M	H	H	H	L	H	M	M	H	H	H	H	H	H	H

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Mechanisms of Developmental Organization	Sex determination	Early Development: Cleavage, Gastrulation and Axis formation	Building with mesoderm
	SLO-2	The cycle of life	Chromosomal sex determination	Developmental Patterns among the Metazoa	Endoderm
S-2	SLO-1	Epigenesis and cleavage	Mammalian Pattern of sex determination	Early development in the Nematode C. elegans	Organogenesis
	SLO-2	Evolutionary embryology	Genetic mechanisms	Early Drosophila Development	Paraxial mesoderm
S-3	SLO-1	Cell Specification:	Wnt family and signaling	Early Zebrafish Development	The somites and their derivatives
	SLO-2	Mechanisms of Developmental Patterning	Hormonal regulation of sexual phenotype	Early Development in Mammals	Intermediate and lateral plate mesoderm
S-4	SLO-1	Autonomous and conditional specification	Environmental sex determination	Building with Ectoderm: The vertebrate nervous system and Epidermis	Heart, Blood, and Kidneys
	SLO-2	Cell identities	Gametogenesis	Neural tube formation and patterning	Development of the tetrapod limb
S-5	SLO-1	Differential Gene Expression	Spermatogenesis	Brain growth	The endoderm
	SLO-2	Mechanisms of Cell Differentiation	Oogenesis	Neural crest cells	The tubes and organs for digestion
S-6	SLO-1	Differential RNA processing	Fertilization	Axonal specificity	Organs and tubes for respiration
	SLO-2	Cell-to-Cell communication	Structure of gametes	Ectodermal Placodes	Postembryonic development
S-7	SLO-1	Juxtacrine signaling	Translocation and capacitation	Epidermis	Metamorphosis
	SLO-2	Mechanisms of Morphogenesis	Thermotaxis and chemotaxis	Cell Signaling	The hormonal reactivation and development
S-8	SLO-1	Cadherins and cell adhesions	Fusion of genetic material	Fibroblast growth factors	Regeneration
	SLO-2	Stem cells: Their potential and their niches	Activation of mammalian egg	RTK pathway	Aging and senescence
S-9	SLO-1	Human model systems	Flowering	The Hedgehog family	Differentiation of dermal, ground, and vascular tissues in plants
	SLO-2	Development in Plants	Reproduction in Plants	The TGF- β superfamily	Techniques in embryology

Learning Resources	1. Scott F. Gilbert, Michael J. F. Barresi. <i>Developmental Biology</i> , Sinauer Associates-Oxford University Press; 11 edition, 2016 2. <i>JMW Slack Essentials of Developmental Biology 3rd Edition Wiley-Blackwell</i> ; 2012
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Dr. G. N. Ramchand, Saksin Life sciences Pvt Ltd, Chennai, ramchand@saksinlife.com	Prof.. K Subramaniam, IITM, Chennai, subbu@iitm.ac.in	Dr. S.ThyagaRajan, SRMIST
Dr. Karthik Periyasamy, Scientist I, Aurozymes Unit, Aurobindo Pharma Limited, Hyderabad, karthikmpk@gmail.com	Prof. R. B. Narayanan, SVCE, Chennai, rbn@svce.ac.in	Dr.R.Vasantharekha, SRMIST

Course Code	18BTE302T	Course Name	CELLULAR AND MOLECULAR NEUROSCIENCE	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Biotechnology	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1:	Recall the brain function from its organization	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Discuss Molecular signaling in neurons	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3:	Compare Neural basis of senses				L	H	H	H		M	L	H	H	H	H	H	L	H	H
CLR-4:	Explain different methods for studying neuro-immune functions				M	H	H	M		M	H	L	H	H	H	H	L	H	H
CLR-5:	Describe the cortical structures pertaining to emotions and feelings				M	H	M	H	M		M	H	H	H	H	H	L	H	H
CLR-6:	Analyze genetic variation and inheritance pertaining to nervous system disorders				L	H	H	H		H	L	L	H	H	H	M	H	H	H
					L	H	H	M		M	H	H	L	H	H	H	H	H	H
					M	H	H	H	L	H	M	M	H	H	H	H	H	H	H
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1:	Analyze the role of genes in brain development and functions	1	80	80															
CLO-2:	Describe the fundamental organization of brain and its functions.	2	85	75															
CLO-3:	Explain the concepts and experiments in the ion channels and NEUROTRANSMITTERS	2	75	80															
CLO-4:	Recognize the various pathways of sensory system	2	85	80															
CLO-5:	Discuss the different methods in the neuroendocrine and immune interactions	3	85	75															
CLO-6:	Explain the concepts of nervous system disorder and the diseases associated with it	2	80	80															

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Genetics of nervous system	Electrical signals	Somatic sensory system-Pain	Cognition-Speech and Language	Diseases and injuries of the nervous system
	SLO-2 Advent of genomics in the assembly of brain	Long-distance transmission of Electrical signals	Touch and Proprioception	Overview of cortical structures	Alzheimer's disease
S-2	SLO-1 Model organisms in neuroscience	The ionic basis of resting membrane potential	Pain and its pathways	Sleep and Wakefulness	Huntington's disease
	SLO-2 Development of the nervous system	Voltage-dependent membrane permeability	Visual and Vestibular pathways	The circadian cycle of sleep and wakefulness	Neuromuscular Disorders: Myasthenia gravis
S-3	SLO-1 Molecular basis of neural induction	Ion channels and transporters	Retinal circuitry	Emotions-Memory	Basal ganglia disorders: Parkinson's disease
	SLO-2 Initial differentiation of neurons and glia	Diversity of ion channels	Phototransduction	Early theories of emotional brain	Pharmacological targets of Parkinson's disease
S-4	SLO-1 Cellular Components of the Nervous system	Synaptic transmission-Neurotransmitters and their receptors	Motor neuron circuits-Motor neuron control by the CNS	Kluver-Bucy syndrome	Spinal Cord Injury
	SLO-2 Neurons and Glia	Chemical and electrical synapses	Motor units	Brain reward circuitry	Traumatic Brain Injury (TBI)
S-5	SLO-1 Organization of nerves	Molecular signaling in neurons	The Corticospinal and Corticobulbar Tracts	Learning	chronic traumatic encephalopathy
	SLO-2 Pre synaptic terminals	Activation of signaling pathways	Upper motor neurons	Memory consolidation and Priming	Stroke
S-6	SLO-1 Neural Circuits	Second messengers	Disorders of basal ganglia	Cognition-Speech and Language	Blood Supply to Brain
	SLO-2 Myotactic reflex	Nuclear signaling	Molecular mechanisms involved in synapse formation	Sex and Sexuality	Transient Ischemic Attack
S-7	SLO-1 Organization of the Nervous system	Synaptic plasticity	Molecular basis of trophic interactions	Neuroanatomical basis for brain functions.	Acute stroke treatment
	SLO-2 Divisions of nervous system	Short and long-term synaptic plasticity	Construction and modification of neural circuits	Hypothalamus and endocrine system	Prevention of stroke
S-8	SLO-1 Central nervous system	Synaptic transmission-Neurotransmitters and their receptors	Repair and Regeneration in nervous system	Hormones of endocrine system and its regulation	Dementia
	SLO-2 Peripheral nervous system	Properties of neurotransmitters	Hypoxia/Ischemia in mammalian brain	Interactions between neuroendocrine system and immune system	Mild cognitive impairment

S-9	SLO-1	Structural and Functional analysis of the Nervous system	Receptors of neurotransmitters	Axon Growth after Brain Injury	Neural-Immune interactions in the periphery	Alzheimer's dementia
	SLO-2	Cellular diversity of nervous system	Unconventional neurotransmitters	Goat brain dissection	Nervous-immune system role in health and disease	Prevention and treatment

Learning Resources	<ol style="list-style-type: none"> 1. Dale Purves, George J. Augustine, David Fitzpatrick, William C. Hall, Anthony-Samuel LaMantia, Leonard E. White, "Neuroscience," Sinauer Associates, Inc., 6th Edition, 2017. 2. Eric R. Kandel, James H. Schwartz, Thomas M. Jessell, "Principles of Neural Science," McGraw-Hill, 5th Edition, 2012.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Dr. G. N. Ramchand, Saksin Life sciences Pvt Ltd, Chennai, ramchand@saksinlife.com	Prof. K Subramaniam, IITM, Chennai, subbu@iitm.ac.in	Dr. S.ThyagaRajan, SRMIST
Dr. Karthik Periyasamy, Scientist I, Aurozymes Unit, Aurobindo Pharma Limited, Hyderabad, karthikmpk@gmail.com	Prof. R. B. Narayanan, SVCE, Chennai, rbn@svce.ac.in	Dr.R.Vasantharekha, SRMIST

Course Code	18BTE303T	Course Name	METABOLIC DISORDERS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18BTC101J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Biotechnology	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1:	Learn about the basic principles of metabolic regulation	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Understand the importance of genetics in medicine and in metabolic diseases.	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3:	Learn about the role of enzymes in various metabolic disorders				L	M	L	H	H	H			H	H	H	H	L	M	L
CLR-4:	The common genetic diseases in our society and the reason for it.				L	M	H	H	H	H	M		H	H	H	H	L	M	H
CLR-5:	Learn about various treatment strategies of metabolic disorders.				L	H	M	H	H	H	L		H	H	H	H	L	H	M
CLR-6:	Learn about the basic principles of metabolic regulation				L	H	L	H	H	H	H		H	H	H	H	L	H	L
					L	M	L	H	H	H	M		H	H	H	H	L	M	L
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:				L	H	H	H	H	H	M		H	H	H	H	L	H	H
CLO-1:	understand the metabolic principles	2	80	70															
CLO-2:	able to solve the metabolic problems of specific nutrients	2	85	75															
CLO-3:	able to apply knowledge in metabolic control	2	75	80															
CLO-4:	Know the importance of genetics in medicine and in metabolic diseases.	2	85	80															
CLO-5:	Realize how genetic diseases are common in our society and the reason for it.	3	85	80															
CLO-6:	Understand the various treatment strategies of metabolic disorders	2	80	75															

Duration (hour)	15	15	15	15	15
S-1	SLO-1 SLO-2	Introduction to metabolic disorders	Carbohydrate metabolic pathways and its associated deficiencies	Nitrogen metabolism and its target organs Amino acid synthesis transport and storage	Inborn error of lipid metabolism
S-2	SLO-1 SLO-2	Principles of metabolic regulation- Garrod's hypothesis	Glycolysis	Metabolism of branched chain amino acids Phenylketonuria, tyrosinemia, homocystinuria, maple syrup urine disease, Alkaptonuria, Albinism	Hyperlipidemia
S-3	SLO-1 SLO-2	Regulation of enzyme activity Covalent modifications and reversible modifications	Glycogenesis	Amino acid transport disorders: Cystinuria, Dicarboxylic aminoaciduria, Hartnup disease	Hypercholesterolemia and its associated disorders
S-4	SLO-1 SLO-2	phosphorylation, dephosphorylation,	Glycogenolysis, Gluconeogenesis	Inborn error of purine metabolism	Hypolipoproteinemia
S-6	SLO-1 SLO-2	adenylation and disulphide reduction	Congenital disorders of Glycosylation	adenylosuccinatelyase deficiency, adenosine monophosphate deaminase deficiency	Tangier disease
S-7	SLO-1 SLO-2	Overview of inherited metabolic disease processes	Galactosaemia Fructosaemia	Nucleotide salvage - Lesch-Nyhan syndrome	Lipodystrophy
S-8	SLO-1 SLO-2	Accumulation of substrate	Lactose intolerance	adenine phosphoribosyltransferase deficiency - Adenosine deaminase deficiency, Xanthinuria - Pyrimidine metabolism	Lipid storage disorders: Sphingolipidoses: ganglioside- globoside- sphingomyelin- sphingosine- sulfatide-related
S-9	SLO-1 SLO-2	Accumulation of minor metabolites	Glycogen storage diseases	Inborn error of pyrimidine metabolism: Oroticaciduria	Fatty-acid metabolism disorders, biotinidase deficiency, malonicaciduria
S-11	SLO-1 SLO-2	Deficiency of product, Secondary metabolic phenomena	Insulin, glucose homeostasis and diabetes mellitus	Miller syndrome, Dihydropyrimidine dehydrogenase deficiency	Sjögren-Larsson syndrome
S-12	SLO-1 SLO-2	Introduction to metabolic disorders	Carbohydrate metabolic pathways and its associated deficiencies	Nitrogen metabolism and its target organs Amino acid synthesis transport and storage	Inborn error of lipid metabolism

S-13	SLO-1	Principles of metabolic regulation- Garrod's hypothesis	Glycolysis	Metabolism of branched chain aminoacids Phenylketonuria, tyrosinemia, homocystinuria, maple syrup urine disease, Alkaptonuria, Albinism	Hyperlipidemia	Disorders of water soluble vitamins
	SLO-2					
S 14-15	SLO-1	Regulation of enzyme activity Covalent modifications and reversible modifications	Glycogenesis	Amino acid transport disorders: Cystinuria, Dicarboxylic aminoaciduria, Hartnup disease	Hypercholesterolemia and its associated disorders	Disorders of coenzymes
	SLO-2					

Learning Resources	1. Robert K. Murray, Darryl K. Granner, Peter A. Mayes, Harper's Illustrated Biochemistry 30th Edition, 2003 2. Enid Gilbert-Barness, Lewis A. Barness, Philip M. Farrell. "Metabolic Diseases: Foundations of Clinical Management, Genetics, and Pathology", IOS Press BV, Netherlands, Second Edition, 2017
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Dr. Giridharan Appaswamy, Lifecell International (P) Limited, Chennai, giridharan.a@lifecell.in	Prof. Karunakaran D, IITM, Chennai, karuna@iitm.ac.in	Dr. K.M. Ramkumar, SRMIST
Dr. Karthik Periyasamy, Aurobindo Pharma Limited, Hyderabad, karthikmpk@gmail.com	Dr. Sib Sankar Roy, CSIR-IICB, Kolkata, sibsankar@iicb.res.in	Dr. Koustav Sarkar, SRMIST

Course Code	18BTE304T	Course Name	INFECTIOUS DISEASES	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Biotechnology	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)															
CLR-1 :	Discuss about the different infections and infectious diseases	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLR-2 :	Describe details of bacterial infections and bacterial diseases				Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3	
CLR-3 :	Explain different viral infections, viral diseases and vaccines				H	H	H	H		M	L	H	H	H	H	H	H	H	H	H
CLR-4 :	State about the protozoan and fungal infections and diseases associated with them				H	H	H	H		M	H	H	H	H	H	H	H	H	H	H
CLR-5 :	Record the different strategies to combat common infectious diseases and the impact of infectious diseases.				M	H	M	H	M	M		M	H	H	H	H	H	H	H	H
CLR-6 :	Identify newer approaches/alternative methods for controlling infectious diseases				H	H	H	H		H	L	H	H	H	H	H	H	H	H	H
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																		
CLO-1 :	Demonstrate general understating of the infectious diseases and their causative agents	1	80	80																
CLO-2 :	Illustrate the bacterial infections and ways to tackle different bacterial diseases.	2	85	75																
CLO-3 :	Interpret the viral infections, vaccine development and challenges	2	75	80																
CLO-4 :	Discuss about the protozoan and fungal infections and methods to combat them	2	85	80																
CLO-5 :	Categorize the infectious diseases and their social impact	3	85	75																
CLO-6 :	Analyze the reimmerging infections and their control	2	80	80																

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Origin of Infection	Introduction to pathogenic and non pathogenic bacteria	History of viral infections	Introduction to Protozoan Diseases
	SLO-2	Evolution of infectious diseases	Common bacterial diseases in humans	Different Viral diseases	Different protozoan diseases
S-2	SLO-1	Concept of Infection: Immunity	Basic mechanism of Bacterial pathogenesis	Viral pathogenesis	Severity of protozoan diseases
	SLO-2	Immune surveillance	Bacterial survival in host cells-Quorum sensing	Viral life cycle	General mode of action of protozoa
S-3	SLO-1	Concept of Infection: Virulence	Bacterial virulence factors: Microbial structures	Virus genomes and structure	Pathogenesis of protozoan diseases: Case study: Plasmodium
	SLO-2	Concept of Pathogenesis	Bacterial virulence factors: Microbial structures: Toxins	Host –virus interactions	Host response to Prozoan
S-4	SLO-1	Causative agents of infectious diseases-Virus	Host response to Bacterial infection	Host Immune reaction against viruses	Molecular signaling against Protozoa
	SLO-2	Causative agents of infectious diseases-Bacteria	Molecular cell signaling involved in Bacterial diseases	Viral evasion of host immune surveillance	Hypersensitivity and autoimmunity associated with Protozoan infections
S-5	SLO-1	Causative agents of infectious diseases-Protozoa and Parasites	Host Immune response to bacteria	Antiviral pathways	General fungal diseases
	SLO-2	Causative agents of infectious diseases-Other causative agents	Bacterial immune evasion: Molecular Mimicry	Mutations in viral genome	Mode of action of fungal diseases
S-6	SLO-1	Disease epidemiology	Strategies for antibacterial therapy: Antibiotics	Viral diseases and antibody response	Immune response against fungal infection
	SLO-2	Steps involved in epidemiology	Other antibacterial compounds	Vaccine against viral diseases	Case study: Candidiasis
S-7	SLO-1	Epidemiological case studies-Bacteria	Gut bacteria and their role in pathogenesis	Antivirals compounds for viral infections	Infection caused by Yeast
	SLO-2	Epidemiological case studies-Bacteria	Bacterial vaccines	Challenges in vaccine production against certain virtues	Mode of action of Yeast infection

S-8	SLO-1	Epidemiological case studies-Virus	Case study: E. Coli infection	Case study: Influenza	Case study: Ring worm	Neglected diseases
	SLO-2	Epidemiological case studies-Virus	Case study: Tuberculosis	Case study: Dengue	Strategies to combat Protozoan infections	Reemerging infectious diseases
S-9	SLO-1	Trends in Current epidemiology-Bacterial infections	Case study: Pneumonia	Case study: HPV	Strategies to combat fungal and yeast infections	Sexually transmitted diseases and awareness
	SLO-2	Trends in Current epidemiology-Viral infections	Case study: Helicobacter and gastric cancer	Case study: HIV and AIDS	Zoonotic diseases	Infectious disease and social issues

Learning Resources	1. Brenda A. Wilson, Abigail A. Salyers, Dixie D. Whitt, Malcolm E. Winkler, "Bacterial pathogenesis: a molecular approach": 3 rd Edition- ASM Press, 2011. 2. Alan Cann, "Principles of Molecular Virology": 6 th Edition-Academic Press, 2015 3. Vincent Racaniello, "Principles of Virology": 4 th Edition- ASM Press, 2015 4. Tracey Lamb, "Immunity to Parasitic Infections": Willy Blackwell, 2012. 5. Malcolm D. Richardson, David W. Warnock, "Fungal Infection: Diagnosis and Management": 4 th Edition- Willy Blackwell, 2012.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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Dr. Karthik Periyasamy, Scientist I, Aurozymes Unit, Aurobindo Pharma Limited, Hyderabad, karthikmpk@gmail.com	Dr. Saumya Raychaudhuri, IMTECH, Chandigarh Saumya@imtech.res.in	Dr. Koustav Sarkar

Course Code	18BTE401T	Course Name	CANCER BIOLOGY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Biotechnology	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1:	Describe the genes, risk factors in tumor progression	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Discuss epigenetics, DNA damage and repair in cancer	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3:	Recall the molecular signaling mechanisms in cancer				L	H	H	H		M	L	H	H	H	H	H	L	H	H
CLR-4:	Explain different methods for studying neuro-immune functions				M	H	H	M		M	H	L	H	H	H	L	H	H	
CLR-5:	Describe the role of stem cells in cancer treatment				M	H	M	H	M		M	H	H	H	H	L	H	H	
CLR-6:	Analyze the role of nuclear medicine and alkaloids in cancer				L	H	H	H		H	L	L	H	H	H	M	H	H	
					L	H	H	M		M	H	H	L	H	H	H	H	H	
					M	H	H	H	L	H	M	M	H	H	H	H	H	H	
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1:	Analyze the role of diet in different forms of cancer	1	80	80															
CLO-2:	Describe the fundamental assays in hazard identification	2	85	75															
CLO-3:	Explain the concepts and experiments in cancer development	2	75	80															
CLO-4:	Recognize the various pathways of cancer and pain	2	85	80															
CLO-5:	Discuss the different methods in the neuroendocrine and immune interactions in cancer	3	85	75															
CLO-6:	Explain the concepts of cancer detection and therapy	2	80	80															

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Basic concepts of cancer: Oncogenes and tumor suppressor genes	DNA structure and stability	Signal transduction	Stem cells and cancer	Cancer therapy and detection
	SLO-2 Risk factors, Pathogenesis, treatment and future prospects	Spontaneous DNA damage	Growth factors and receptors	Self-renewal and its molecular mechanisms	Modalities of treatment
S-2	SLO-1 The cell cycle	DNA repair	EGF growth factor receptor signaling	Hedgehog signaling pathway	Nuclear medicine
	SLO-2 cyclin and cyclin dependent kinases	Clinical applications of DNA repair biomarkers	Ras activation	Polycomb group proteins	Chemotherapeutic agents
S-3	SLO-1 Mechanisms of CdK regulation.	Epigenetics	Activation of MAPK pathways	Therapeutic strategies	Plant alkaloids
	SLO-2 Tumor suppressor genes	Epigenome and its implications	Oncogenes	Tumor micro environment in cancer	Antibiotics
S-4	SLO-1 Knudson's two-hit hypothesis	Carcinogenesis	Immune system	Macrophages and tumor progression	Hormonal agents
	SLO-2 P53 and control of cell cycle	Causes of cancer	Effector mechanisms in cancer immunity	SMAD signaling centers	Biological therapy
S-5	SLO-1 Molecular pathways of p53	Cancer risk factors	NF-KB signaling pathway	Invasion and metastasis	Immunotherapy and hematopoietic growth factors
	SLO-2 Myc transcription factor	Types of carcinogens	JAK/STAT and cancer	Cell adhesion molecules	Cancer prevention and early detection
S-6	SLO-1 Powers of Myc oncoprotein	Bacteria and cancer	Neuroendocrine system	Angiogenesis	Screening techniques and diagnostic tests
	SLO-2 Role of myc oncoprotein in regulating pRb	Hormones and cancer	Neurotransmitters and GPCR signaling	Tumor angiogenesis and neovasculature	Imaging and cancer
S-7	SLO-1 TGF role in cancer	Ecogenetics and cancer risk	Estrogen signaling pathways	VEGF signal transduction	X-Ray CT, MRI, and radio imaging
	SLO-2 pRb's role in cancer	Mutations	Growth factors, and growth factor receptors	Angiogenic inhibitors	Optical imaging
S-8	SLO-1 Tumor suppressor genes	Carcinogen metabolism	Wnt signaling	Vascular targets	Tumor vasculature metabolism
	SLO-2 Cell cycle and cancer	Biotransformation and cancer risk	Implications in cancer therapy	Pain and physiology of pain perception	Contrast agents in cancer molecular imaging
S-9	SLO-1 Different forms of cancer	Cancer prevention	Apoptosis and Cancer	Neuropathic cancer pain	Bioinformatics for pathway interaction
	SLO-2 Diet and cancer	Hazard identification assays	Bcl-2 and cancer	Pain therapy	Population screening challenge

Learning Resources	1. Lauren Pecorino, <i>Molecular Biology of Cancer: Mechanisms, Targets, and Therapeutics</i> , Oxford University Press; 4th edition, 2016 2. Robert A. Weinberg, <i>The Biology of Cancer</i> Garland Science; 2nd edition, 2013 3. John Mendelsohn, Peter M. Howley, Mark A. Israel, Joe W. Gray, Craig B. Thompson. <i>The Molecular Basis of Cancer</i> , Saunders; 4 edition, 2014
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Dr. G. N. Ramchand, Saksin Life sciences Pvt Ltd, Chennai, ramchand@saksinlife.com	Prof.. K Subramaniam, IITM, Chennai, subbu@iitm.ac.in	Dr. S.ThyagaRajan, SRMIST
Dr. Karthik Periyasamy, Scientist I, Aurozymes Unit, Aurobindo Pharma Limited, Hyderabad, karthikmpk@gmail.com	Prof. R. B. Narayanan, SVCE, Chennai, rbn@svce.ac.in	Dr.R.Vasantharekha, SRMIST

Course Code	18BTE402T	Course Name	PHYSIOLOGY OF STRESS AND ITS MANAGEMENT	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Biotechnology	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1:	Describe the homeostasis and control systems in stress	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Discuss stress neuroendocrinology	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3:	Recall the behavioral response to stress																		
CLR-4:	Explain different disorders of stress																		
CLR-5:	Describe the role of age and emotion in stress																		
CLR-6:	Analyze the role of education in managing stress																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1:	Analyze the role of endocrine and immune system in stress	1	80	80	L	H	H	H		M	L	H	H	H	H	H	L	H	H
CLO-2:	Describe the role of brain and neurotransmitters in stress	2	85	75	M	H	H	M		M	H	L	H	H	H	L	H	H	
CLO-3:	Explain the concepts and experiments in stress and stressors	2	75	80	M	H	M	H	M	M		M	H	H	H	H	L	H	H
CLO-4:	Recognize the various pathways of stress related disorders	2	85	80	L	H	H	H			H	L	L	H	H	H	M	H	H
CLO-5:	Discuss the different methods in the management of stress	3	85	75	L	H	H	M		M	H	H	H	L	H	H	H	H	H
CLO-6:	Explain the concepts of diet, exercise and life style in managing stress	2	80	80	M	H	H	H	L	H	M	M	H	H	H	H	H	H	H

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Homeostasis and control systems	Stress neuroendocrinology	Behavioral responses to stress	Stress of Boredom	Awareness about managing stress.
	SLO-2 Endocrine system	limbic forebrain	Behavioral sources of stress	Anxiety disorders	Extra role in behavior
S-2	SLO-1 HPA axis	Noradrenergic system	Impairment of response inhibition	Panic disorder	Managing stress and behavior
	SLO-2 Limbic modulation of HPA axis	Corticotropin releasing hormone	lack of motivation	Social anxiety disorder	Extra role in education settings
S-3	SLO-1 Nervous system and stress disorder	CRF family with role in HPA axis	Aggressive behavior	Cognitive behavior therapy	Relaxation.
	SLO-2 Hippocampus and depression	Intracellular signaling mediating external signals of stress	Physiological components of stress response	Post-traumatic syndromes	Effective communication.
S-4	SLO-1 Parasympathetic system	Catecholamines and MAP kinases	Interactions of behavioral and physiological components	Evolution and treatment	Intervention of caregivers
	SLO-2 Fight/flight responses	microRNAs-Telomeres	Environmental factors	Distress	Institutional care
S-5	SLO-1 Rest/digest responses	Role of micro-RNA in fear conditioning	Impact of environmental factors on stress	Psychological concomitants of distress	Managing anger and coping with anxiety.
	SLO-2 Immune system	Neural circuitry of stress, fear and anxiety	Differential exposure	Chronic stress.	Psychophysiological and biological perspective
S-6	SLO-1 Innate Immunity	Serotonergic systems modulates anxiety	Vulnerability of environmental stressors	Fear.	Meditation model
	SLO-2 Adaptive immunity	Locus coeruleus facilitate stress	Psychological stressors	Emotional inhibition	Eating behavior and healthy lifestyle
S-7	SLO-1 Stress and its underpinnings	Neurons and central autonomic control	Historical and general considerations	Aggressive behavior and social stress.	Human research related to stress in food intake
	SLO-2 Kinds of stress	Stress-Hippocampal neurogenesis.	Conceptual developments	Acute and chronic stress models	Mechanisms relating stress to eating
S-8	SLO-1 Norepinephrine in stress	Neurons modulate HPA axis	Methodological considerations	Aging and psychological stress.	Exercise
	SLO-2 Noradrenergic control of stress	Epigenetics and stress and neural network	Cognition and stress	Age-related disease	Time management and stress reduction plan
S-9	SLO-1 Allostasis	Epigenetics and stress response	Cognitive origin of stress	Stress response and central role of brain	General principles of prevention
	SLO-2 Allostatic load	Transgenerational effects of epigenetic stress markers	Cognitive consequences of stress	Job-related stress.	Physical and mental well-being

Learning Resources	1. George Fink. <i>Stress: Concepts, Cognition, Emotion, and Behavior: Handbook in Stress</i> . Academic Press. First edition. 2016 2. George Fink, <i>Stress: Neuroendocrinology and neurobiology</i> : Academic Press. First edition. 2017
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Dr. G. N. Ramchand, Saksin Life sciences Pvt Ltd, Chennai, ramchand@saksinlife.com	Prof.. K Subramaniam, IITM, Chennai, subbu@iitm.ac.in	Dr. S.ThyagaRajan, SRMIST
Dr. Karthik Periyasamy, Scientist I, Aurozymes Unit, Aurobindo Pharma Limited, Hyderabad, karthikmpk@gmail.com	Prof. R. B. Narayanan, SVCE, Chennai, rbn@svce.ac.in	Dr.R.Vasantharekha, SRMIST

Course Code	18BTE305T	Course Name	PHARMACEUTICAL BIOTECHNOLOGY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18BTC101J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Biotechnology	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1:	Appraise the changes the drug and human system undergoes when consumed	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2:	Demonstrate the parameters that affect the action of drug in human system	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3:	Relate the different type of adverse drug reactions and drug abuse	Expected Proficiency (%)	Problem Analysis
CLR-4:	Explain the mechanism of action, toxicity and uses of antibiotics and anti-tubercular drugs	Expected Attainment (%)	Design & Development
CLR-5:	Describe the regulation of drugs in Indian Government and its initiatives in promoting Indian System of medicine		Analysis, Design, Research
CLR-6:	Distinguish various parameters to be considered during drug discovery process		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1:	Select appropriate target, drug-like candidates based on desired pharmacokinetic and pharmacodynamic parameters	1 80 80	M H L H
CLO-2:	Estimate the dose of drug to be administered for individuals	2 85 75	M H L H
CLO-3:	Explain the logical usage of drugs and suggest appropriate treatment	2 75 80	L H M H
CLO-4:	Justify the choice of drugs for microbial infection in an individual	2 85 80	H H H H
CLO-5:	Underline the significance of stringent laws pertaining to manufacturing, distribution and sale of drugs in India	3 85 75	H H H H
CLO-6:	Illustrate the process of pre-clinical investigation of drug designing	2 80 80	H H H H

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Basic concepts	Plateau principle	Pharmacovigilance	Mechanism of action of Tetracyclines	Mechanism of action of Amphoterycin B
	SLO-2 Pharmacopoeia and Essential Drugs	Target level strategy	Casualty assessment	Uses, Spectrum of activity, toxicity of Tetracyclines	Spectrum of activity and adverse effects of Amphoterycin B
S-2	SLO-1 Local routes of drug administration	Prolongation of drug action	Side, secondary and toxic effects of drugs	Mechanism of action of aminoglycoside antibiotics	Mechanism of action of Griseofulvin
	SLO-2 Systemic routes of drug administration	Target delivery devices	Accidental overdose of drugs and the treatment	Classification, Uses of aminoglycosides	Mechanism of action of Imidazoles and Triazoles anti-fungal agents
S-3	SLO-1 Influence of pH on transport of molecules across membranes	Principles of drug action	Drug Intolerance and Drug allergy	Mechanism of action of Macrolide antibiotics	Indian Drug Regulatory System
	SLO-2 Passive transport and facilitated transport	Mechanism of drug action on enzymes	Drug abuse and Treatment	Classification of Macrolide antibiotics	Drug Regulatory body - CDSCO
S-4	SLO-1 Absorption of Drugs	Mechanism of drug action on Ion channels	Classification of anti-microbial agents based on chemical structure	Spectrum of activity of Macrolide antibiotics	Hierarchy at CDSCO
	SLO-2 Bioavailability	Mechanism of drug action on transporters	Classification of anti-microbial agents based on mechanism of action	Uses and toxicity of Macrolide antibiotics	Good clinical Practices
S-5	SLO-1 Distribution and Redistribution of drugs	Action-Effect sequence	Drug modification and alteration of target site by microorganisms	Treatment of Urinary tract infections	Role of Pharmacists in Drug regulation
	SLO-2 Tissue storage, placental & brain transport	Transducer mechanism	Reduction in drug accumulation and alteration of metabolic pathway by microorganisms	Structure, adverse effects of Isoniazid	Functions of State Drug-Inspectors
S-6	SLO-1 Biotransformation of drugs and types	Dose-Response Relationship	Mechanism of action of Co-trimoxazole	Mechanism of action of Isoniazid	Functions of CDSCO
	SLO-2 Cytochrome P450	Therapeutic efficiency	Uses and adverse effects of cotrimoxazole	Structure, adverse effects of Rifampicin	Functions of Central Drug-Inspectors
S-7	SLO-1 Non-synthetic biotransformation reactions	Synergistic drug action	Mechanism of action of Fluoroquinolones	Mechanism of action of Rifampicin	Ayurvedic Formulary of India

	SLO-2	Synthetic biotransformation of drugs	Antagonistic drug action	Classification, Uses and adverse effects of Fluoroquinolones	Structure, Mechanism of action, adverse effects of Pyrazinamide	Ayurvedic Dosage Forms
S-8	SLO-1	Inhibition of drug metabolism	Fixed dose combination of drugs	Structure of beta-lactum antibiotics	Structure, Mechanism of action, adverse effects of Ethambutol	Ayurvedic Pharmacopoeia of India
	SLO-2	Induction of microsomal enzymes	Factors modifying drug action	Classification of beta-lactum antibiotics	Tuberculosis in pregnant and lactating women	Ayurvedic, Unani, Siddha drugs undertaken by British commission
S-9	SLO-1	Routes of excretion of drugs	Pharmacogenetics and Pharmacogenomics	Uses of beta-lactum antibiotics	Tuberculosis in HIV infected individuals in India	Indian Government Initiatives to promote Ayurvedic products
	SLO-2	Rate of Clearance and Plasma half-life	Drug dosage in individuals with hepatic, renal, heart and thyroid problems	Adverse effects of beta-lactum antibiotics	Mycobacterium Avium Complex infections in India	Indian Government Initiatives to promote Unani and Siddha products

Learning Resources	<ol style="list-style-type: none"> 1. Rang and Dale, "Pharmacology", Churchill Livingstone, 2007. 2. Tripathi K.D, "Essentials of Medical Pharmacology", Jaypee Brothers Medical Publishers, New Delhi, 7th Edition, 2013. 3. http://www.cdsc.nic.in/forms/contentpage1.aspx?lid=1888 4. cdsc.nic.in/writereaddata/guidance%20documents.pdf
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Dr. G. N. Ramchand, Saksin Life sciences Pvt Ltd, Chennai, ramchand@saksinlife.com	Prof.. K Subramaniam, IITM, Chennai, suubu@iitm.ac.in	Mr. S. Karthik, SRMIST
Dr. Karthik Periyasamy, Scientist I, Aurozymes Unit, Aurobindo Pharma Limited, Hyderabad, karthikmpk@gmail.com	Prof. R. B. Narayanan, SVCE, Chennai, rnb@svce.ac.in	Mr. M. K. Jaganathan, SRMIST

Course Code	18BTE306T	Course Name	BIOINFORMATICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Biotechnology	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1:	Analyze the databases in bioinformatics	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Use sequence alignment to find similar sequences	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3:	Use alignment to build hierarchical lineages																		
CLR-4:	Apply principles of bioinformatics to build tertiary structures of proteins																		
CLR-5:	Analyze motifs and patterns																		
CLR-6:	Analyze uses of Python programming in Bioinformatics applications																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1:	Describe the applications of bioinformatics to build databases for universal usage	1	80	80	H	H	H	H		M	L	H	H	H	H	H	H	H	H
CLO-2:	Explain the concepts and tools to build alignment between similar sequences of DNA or Protein	2	85	75	H	H	H	H		M	H	H	H	H	H	H	H	H	H
CLO-3:	Recognize the pattern of lineages and evolution	2	80	80	M	H	M	H	M	M		M	H	H	H	H	H	H	H
CLO-4:	Discuss the different methods in the construction the structure of a protein	2	85	80	M	H	H	H		H	M	H	H	H	H	H	H	H	H
CLO-5:	Analyze the importance of conserved regions in a molecular sequence	3	85	75	M	H	H	H		M	H	M	H	L	H	H	H	H	H
CLO-6:	Explain the basic concepts and principles of Programming in Python for bioinformatics	3	80	80	H	H	H	H	L	M	M	M	H	H	H	H	H	H	H

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Bioinformatics significance	Introduction on databases & biological databases	Sequence alignment	Motifs and Patterns prediction	Introduction of Python and text editors
	SLO-2 Applications of bioinformatics	Uses of biological databases	Global Pairwise Alignment Algorithm	Databases for motif prediction	String datatype
S-2	SLO-1 Internet basics: Connecting to internet	Primary sequence databases, Nucleotide	Solving problems	Databases for patterns and blocks	Tuples datatype
	SLO-2 Internet Protocols	Protein sequence database	Local Pairwise Alignment Algorithm	Secondary Database Searching	Lists datatype
S-3	SLO-1 HTML script	Primary structure databases	Database searching	Secondary structure prediction	Flow control: If else
	SLO-2 Webpage creation	PDB file format	BLAST	Tools for secondary structure prediction	For loop
S-4	SLO-1 Human genome project	Fasta, GCG, VFF etc..	FASTA	Specialized secondary structure prediction	While loop
	SLO-2 Uses of human genome project	Secondary databases	Multiple Sequence Alignment:	Tertiary structure prediction	Reading and Writing files
S-5	SLO-1 The NCBI data model: Introduction	secondary sequence databases	Progressive and Iterative Alignment	Comparative modelling	Modules in Python
	SLO-2 SEQ-Ids	secondary structure databases	Tools for pairwise alignment	Abinitio modelling	Functions
S-6	SLO-1 BIOSEQs and BIOSEQ-SETs	SCOP	tools for multiple sequence alignment	Validation of tertiary structure	Regular expressions: Syntax
	SLO-2 SEQ-ANNOT and SEQ-DESCR	CATH	Application of Multiple Sequence Alignment	tools for homology modeling	Regex examples
S-7	SLO-1 Genbank database	Composite protein databases	Databases Of Multiple Alignment	tools for structure validation	Biopython
	SLO-2 Genbank Flat file	Metabolic databases	Molecular Phylogeny	Structure visualization tools	Advantages of python in bioinformatics
S-8	SLO-1 Sequence submission to Genbank	SNP databases	Methods of phylogeny	rasmol	Components of biopython: Alphabet
	SLO-2 Online and offline tools	Whole genome , medelian disease databases	types of trees	Chemical structure building tools	Seq, Seq object, SeqUtils
S-9	SLO-1 Entrez , INSDC	chemical structure databases	Tools for phylogeny	file formats for small molecules	Align and clustalw with Biopython
	SLO-2 Other databases in NCBI	bibliographic databases	PAM and BLOSUM	file format conversion tools	BLAST Running and Processing with Biopython

Learning Resources	<ol style="list-style-type: none"> 1. Andreas D Baxevanis & B F Francis, "Bioinformatics- A practical guide to analysis of Genes & Proteins", John Wiley, 2002 2. T K Attwood, D J Parry-Smith, "Introduction to Bioinformatics", Pearson Education, 1st Edition, 11th Reprint 2005. 3. Jin Xiong, "Essential Bioinformatics", Cambridge University Press, 2006 4. Sebastian Bassi, "Python for Bioinformatics", 2nd Edition CRC Press, 2017.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. Raghu R. Schrodinger, raghu.rangaswamy@schrodinger.com	Dr.G. Ramesh kumar, AU-KBC Research Centre, gramesh@au-kbc.org	Dr. Priya Swaminathan, SRM Institute of Science & Technology, priya.s@ktr.srmuniv.ac.in
Dr. Karthik Periyasamy, Scientist I, Aurozymes Unit, Aurobindo Pharma Limited, Hyderabad, karthikmpk@gmail.com	Prof. R. B. Narayanan, SVCE, Chennai, rbn@svce.ac.in	Mr. M.K.Jagannathan, SRM Institute of Science & Technology, jagannathan.m@ktr.srmuniv.ac.in

Course Code	18BTE307T	Course Name	DRUG DISCOVERY AND DRUG DESIGNING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Biotechnology	Data Book / Codes/Standards			

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 : State the basic concepts of drug discovery and drug design processes		Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 : State the basic concepts of target identification and target characterization																						
CLR-3 : Explain about the various computational tools in drug discovery																						
CLR-4 : Discuss about the pharmacophore Model and QSAR																						
CLR-5 : Discuss about the quantum mechanics in drug design, De novo and future developments in drug design																						
CLR-6 : Explain the basic concepts of drug discovery and drug design processes and computational tools used in the drug designing.																						
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 : Explain basic concepts of drug design processes for a various number of drug development scenarios.		1	85	80	L	H	H	H	H		M	M	H					H	H	H	H	
CLO-2 : Explain the basic concept of target identification and target characterization		1	85	80	L	H	H	H	H		H		H					H	H	H	H	
CLO-3 : Compare the different computational tools for drug designing and the computer software used in the drug designing.		2	80	70	M	H	H	H	H		H		H					H	H	H	H	
CLO-4 : Explain the basic concepts of pharmacophore Model and QSAR.		1	80	70	M	H	H	H	H		H		H					H	H	H	H	
CLO-5 : Summarize the basic concepts of Quantum Mechanics in drug designing and De nova ligand synthesis.		1	85	80	M	H	H	H	H		H		H					H	H	H	H	
CLO-6 : Summarize the basic concepts in the drug design process and the computational techniques used in the drug design process.		1	80	70	M	H	H	H	H		H		H					H	H	H	H	

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Introduction to the drug discovery process	Target Identification: Primary Sequence and Metabolic Pathway.	introduction to computational tools in drug discovery	what is a pharmacophore Model
	SLO-2	The sequence of research activities in the development of new drug	Crystallography and 2D NMR, Homology Models and Protein Folding in target identification	Introduction to Homology Model Building	Components of a Pharmacophore Model
S-2	SLO-1	Terminology related to drug testing: "hits," "leads," "drug candidates," "drugs,"	Analysis of Target Mechanism: Kinetics and Crystallography, Automated Crevice Detection,	Importance of sequence similarity in homology modeling	Creating a Pharmacophore Model from the Active Compounds
	SLO-2	Criteria that may be necessary to move a compound series onto the lead development stage	Transition Structures and Reaction Coordinates.	Steps for Building a Homology Model	Advantages of pharmacophore searching
S-3	SLO-1	Compound Testing: Biochemical Assays	Introduction to Molecular Dynamics Simulations	Homology Model creation	Creating a Pharmacophore Model from the Active Site
	SLO-2	Compound Testing: Cell-Based Assays,	Molecular dynamics in target characterization	Homology Model validation	Example of Pharmacophore Model from the Active Site
S-4	SLO-1	Compound Testing: Animal Testing	Pharmacophore identification	Molecular Mechanics: Brief Introduction to Molecular Mechanics	Searching Compound Databases
	SLO-2	alternatives to animal testing	Deriving and using 3D pharmacophores	How molecular mechanics are utilized in drug design.	Reliability of search Results
S-5	SLO-1	Compound Testing: Human Clinical Trials	The Drug Design Process for a Known Protein Target: The Structure-Based Design Process	Force Fields for Drug Design	QSAR
	SLO-2	Phases in clinical trials	The Drug Design Process for a Known Protein Target: Initial Hits and Compound Refinement, ADMET	common force fields and their usage	Conventional QSAR versus 3D-QSAR
					Example of De novo Ligand synthesis

S-6	SLO-1	<i>Effect of Molecular Structure on Activity</i>	<i>What is Drug Resistance</i>	<i>Introduction to Molecular Docking</i>	<i>The QSAR Process</i>	<i>Nonquantitative predictions</i>
	SLO-2	<i>Effect of Molecular Structure on Bioavailability</i>	<i>Mechanisms of resistance to the drug</i>	<i>Search Algorithms in Molecular Docking</i>	<i>Descriptors</i>	<i>Quantitative predictions</i>
S-7	SLO-1	<i>Drug Side Effects and Toxicity</i>	<i>The Drug Design Process for an Unknown Target: The Ligand-Based Design Process</i>	<i>The Docking Process: Preparation of Protein and Ligand</i>	<i>Automated QSAR Programs</i>	<i>Future Developments in Drug Design: Individual Patient Genome Sequencing</i>
	SLO-2	<i>Multiple Drug Interactions</i>	<i>The Drug Design Process for an Unknown Target: Initial Hits and Compound Refinement, ADMET</i>	<i>Setting the Bounding Box</i>	<i>QSAR versus Other Fitting Methods</i>	<i>Analysis of the Entire Proteome</i>
S-8	SLO-1	<i>Metrics for Drug-Likeness</i>	<i>Drug Design for Other Targets</i>	<i>Docking Options and Running the Docking Calculation</i>	<i>The 3D-QSAR Process</i>	<i>Drugs Customized for Ethnic Group or Individual Patient</i>
	SLO-2	<i>The Lipinski rule of fives</i>	<i>Drug design issues that arise in situations other than competitive inhibition of proteins.</i>	<i>Analysis of docking Results</i>	<i>Criteria are used to construct conformers</i>	<i>Application of Genetic Manipulation in drug designing</i>
S-9	SLO-1	<i>Exceptions to the Rules</i>	<i>Targets inside cells</i>	<i>Docking software</i>	<i>3D-QSAR Software Packages</i>	<i>Cloning and Stem Cells in drug design</i>
	SLO-2	<i>Examples of successful drugs that do not obey the "rules."</i>	<i>Targets within the central nervous system</i>	<i>An important criterion for selecting a docking program.</i>	<i>Advantage and disadvantages of 3D-QSAR Software</i>	<i>Longevity</i>

Learning Resources	<ol style="list-style-type: none"> 1. Young, "Computational Drug Design: a Guide for Computational and Medicinal Chemists", Wiley, 2009 2. Andrew Leach, "Molecular Modeling: Principles and applications," 2nd edition, Pearson Education, 1996 3. Andrew Leach, "An introduction to Chemoinformatics," Springer, 2007 4. Rick NG, "Drugs: From Discovery to Approval," John Wiley & Sons, 2004. 5. Paul S Charifson, "Practical Application of Computer-Aided Drug Design," Informa Health Care, 1997.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Dr. G. N. Ramchand, Saksin Life sciences Pvt Ltd, Chennai, ramchand@saksinlife.com	Prof. K Subramaniam, IITM, Chennai, suubu@iitm.ac.in	Mr. Jaganathan. M. K. SRMIST
Dr. Karthik Periyasamy, Scientist I, Aurozymes Unit, Aurobindo Pharma Limited, Hyderabad, karthikmpk@gmail.com	Prof. R. B. Narayanan, SVCE, Chennai, rbn@svce.ac.in	Dr. S. Priyaswaminathan. SRMIST

Course Code	18BTE308T	Course Name	MARINE BIOTECHNOLOGY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1:	Learn the knowledge of the living and non-living resources.	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Analyze the pharmacological potency of toxins.																		
CLR-3:	Apply the biopolymers from various sources.																		
CLR-4:	Understand the commercialization of marine and aquaculture resources.																		
CLR-5:	Control measures of various marine pollution.																		
CLR-6:	Analyze the techniques on the resource management.																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1:	Describe the economically important marine resources and their wealth.	1	80	80	M	H	H	H	H		H	H	H	H	H	H	H	H	H
CLO-2:	Explain the natural toxins.	2	85	75	M	H	H	H	H		H	H	H	H	H	H	H	H	H
CLO-3:	Distinguish the availability of bioactive compounds.	2	80	80	H	H	H	H	H		H	H	H	H	H	H	H	H	H
CLO-4:	Analyze the useful natural products.	2	85	80	M	H	M	M	H		M	H	H	H	H	H	H	H	H
CLO-5:	Know the degradation process for discharged wastes.	3	85	75	M	M	H	H	H		H	H	H	H	H	H	H	H	H
CLO-6:	Explain the diseases of cultivable animals and its controlling measures.	3	80	80	M	H	H	H	H		H	H	H	H	H	H	H	H	H

Learning Resources	1. Milton Fingerman and Rachakonda Nagabhushanam, "Recent Advances in Marine Biotechnology (Series) Biomaterials and Bioprocessing", Science Publishers, 2009. 2. Proksch and Werner E.G.Muller, "Frontiers in Marine Biotechnology", Horizon Bioscience, 2006. 3. Le Gal, Y., Ulber, R, "Marine Biotechnology I: Advances in Biochemical Engineering/Biotechnology", (Series editor: T. Scheper) Springer-Verlag Berlin Heidelberg. Vol. 96, 2005. 4. Le Gal, Y., Ulber, R "Marine Biotechnology II: Advances in Biochemical engineering/Biotechnology", (Series editor: T. Scheper) Springer-Verlag Berlin Heidelberg. Vol. 97, 2005.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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Dr. Karthik Periyasamy, Scientist I, Aurozymes Unit, Aurobindo Pharma Limited, Hyderabad, karthikmpk@gmail.com	Prof. R. B. Narayanan, SVCE, Chennai, rbn@svce.ac.in	Dr.R.Jaiganesh, SRMIST

Course Code	18BTE403T	Course Name	VACCINE BIOTECHNOLOGY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18BTC106J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Biotechnology	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand the conventional strategies in vaccine production	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Develop an understanding in the vaccine production techniques	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Categorise the types of vaccine																		
CLR-4 :	Analyze different methods of vaccine delivery																		
CLR-5 :	Comprehend the guidelines for vaccine management																		
CLR-6 :	Analyze the immunization of an organism against antigen																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Acquire theoretical knowledge on conventional strategies in vaccine production	1	80	80	H	H	H	H	M	M	L	H	H	H	H	H	H	H	H
CLO-2 :	Exemplify the students with vaccine production techniques	2	85	75	H	H	H	H	M	M	H	H	H	H	H	H	H	H	H
CLO-3 :	Distinguish various types of vaccine	2	75	80	M	H	M	H	M	M		M	H	H	H	H	H	H	H
CLO-4 :	Devise various methods for vaccine delivery	2	85	80	H	H	H	H	M		H	L	H	H	H	H	H	H	H
CLO-5 :	Explain the guidelines for vaccine production and delivery	3	85	75	H	H	H	H		M	H	H	L	H	H	H	H	H	H
CLO-6 :	Illustrate the basic concepts of vaccination and prophylaxis	2	80	80	H	H	H	H	L	M	M	M	H	H	H	H	H	H	H

Duration (hour)	9	9	9	9	9
S-1	SLO-1	History of vaccine development	Technology related to monitoring seed lot for better production	Types of vaccines	Immunomodulators
	SLO-2	Types of Immunity	Temperature Monitoring	Vaccine efficacy	Innovative methods of delivering immunogens
S-2	SLO-1	Conventional strategies for vaccine improvement	Sterilization	Inactivated toxins	liposomes
	SLO-2	Current development in vaccines	Environmental strategies for better production	Inactivated whole bacteria	Mechanism of liposome formation
S-3	SLO-1	Types of vaccines	quality assurance and related areas in vaccine production	Inactivated whole virus	Classification of liposomes
	SLO-2	Live vaccine	Analysis of vaccine efficiency	Live attenuated bacteria	Methods of liposomes preparation
	SLO-1	Attenuated vaccine	Vaccine Production techniques	Live attenuated viruses	Characterisation of liposomes
S-4	SLO-2	subunit vaccine	growing the microorganisms in maximum titre	Subunit vaccines	Therapeutic applications of liposomes
S-5	SLO-1	Peptide vaccine	Steps involved in vaccine production	Polysaccharide vaccines	role of liposomes in delivering vaccines
	SLO-2	killed vaccine	Selecting the strain for vaccine production	Conjugated vaccines	Advantages & disadvantages of liposomes
S-6	SLO-1	Types of adjuvants	Culturing bacteria	Recombinant DNA vaccines	Microspheres
	SLO-2	Mode of action of adjuvants	Culturing virus	Differences between traditional and recombinant vaccine	Types of microspheres
S-7	SLO-1	PRR ligands	Isolation and purification of microbes	Edible vaccines	Methods of preparing microspheres
	SLO-2	Methods to access vaccine efficacy	Inactivation of Microorganism	Plasma derived vaccines	Characterisation and applications of microspheres
S-8	SLO-1	Quality control in vaccine production	Preservation techniques	Virus like particles	ISCOMS-Properties of ISCOM based vaccines
					documentation and evaluation of data

	SLO-2	Preservation of industrially important microbes	Preservation of industrially important microorganisms	HPV L1 VLP vaccine	Types of ISCOM	Test on final products
S-9	SLO-1	monitoring of microorganisms	Preservation using low temperature	Nanoparticles in vaccine delivery	components of ISCOM	General manufacturing recommendations
	SLO-2	Seed lot systems	freeze drying	Induction of immune responses by nanoparticle based vaccine	Induction of antibody responses by ISCOMs	Final product release tests

Learning Resources	<ol style="list-style-type: none"> 1. Ronald W. Ellis, "New Vaccine Technologies", Landes Bioscience, 2001. 2. Noel Mowat, "Vaccine manual: The production and quality control of veterinary vaccines for use in developing countries", Daya books, 1999. 3. Cheryl Barton, "Advances in Vaccine Technology and Delivery", Espicom Business Intelligence, 2009.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Dr. G. N. Ramchand, Saksin Life sciences Pvt Ltd, Chennai, ramchand@saksinlife.com	Prof. K Subramaniam, IITM, Chennai, subbu@iitm.ac.in	Dr. S.Sujatha, SRMIST
Dr. Karthik Periyasamy, Scientist I, Aurozymes Unit, Aurobindo Pharma Limited, Hyderabad, karthikmpk@gmail.com	Prof. R. B. Narayanan, SVCE, Chennai, rbn@svce.ac.in	Dr. Suvankar Ghorai, SRMIST

Course Code	18BTE404T	Course Name	MOLECULAR BASIS OF DRUG ACTION	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Biotechnology	Data Book / Codes/Standards			

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	State the basic knowledge of drug targets and molecular cloning of these targets.	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Discuss the recent advancement and development in human drug target : G-protein coupled receptors.	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Discuss the recent advancement and development in human drug target : ion channels																		
CLR-4 :	Discuss the recent advancement and development in human drug target : transporter proteins																		
CLR-5 :	Explain how an individual's genetic makeup influences their response to therapeutic drugs.																		
CLR-6 :	Discuss about the drug targets and their role in health and disease.																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Summaries about the drug targets and method to clone drug targets.	1	85	80	L	H	H	H	H	M	M	H			H	H	H	H	H
CLO-2 :	Explain about G protein coupled receptors.	1	80	70	L	H	H	H	H			H			H	H	H	H	H
CLO-3 :	Explain about various ion channels.	1	80	75	L	H	H	H	H			H			H	H	H	H	H
CLO-4 :	Explain about various transporters	1	85	80	L	H	H	H	H			H			H	H	H	H	H
CLO-5 :	Discuss how an individual's genetic makeup influences their response to therapeutic drugs.	1	80	70	L	H	H	H	H			H	H		H	H	H	H	H
CLO-6 :	Summaries about the drug targets and their role in health and disease.	2	85	80	L	H	H	H	M			H	M	H		H	H	H	H

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Introduction to molecular pharmacology	Introduction to GPCRs and Heterotrimeric G-protein	introduction to ion channels	introduction Transporter proteins
	SLO-2	Outline of molecular pharmacology based approaches used to interrogate drug targets.	molecular structure of GPCR	Classification of ion channels	classification of Transporter proteins
S-2	SLO-1	Molecular pharmacology vs traditional pharmacology	Classification of GPCR	introduction to Voltage-gated ion channels	Transporter families of pharmacological interest
	SLO-2	Importance of molecular pharmacology.	Activation of GPCR	structure of Voltage-gated ion channels	The major facilitator superfamily (MFS)
S-3	SLO-1	Nature of the Drug targets	Signal transduction pathways - phospholipase C and adenylyl cyclase	Voltage-gated ion channels in health and disease	MFS in health
	SLO-2	Future drug targets	Measurement of phospholipase C and adenylyl cyclase activation	Voltage-gated ion channels and neurotransmission	Role MFS in disease
S-4	SLO-1	Introduction to molecular cloning – from DNA to drug discovery	Desensitization and down-regulation of GPCR signalling	Voltage-gated ion channels and muscle contraction	The neurotransmitter: sodium symporter (NSS)
	SLO-2	The relevance of recombinant DNA technology to pharmacology/drug discovery	Role of GPCR phosphorylation in desensitisation	Voltage-gated Ca2+ channels	Glph transporters
S-5	SLO-1	The 'cloning' of drug targets	Constitutive GPCR activity	Voltage-gated Na+ channels	Leucine Transporter(LeuTAa)
	SLO-2	Cloning using peptide sequence(s)	Promiscuous G-protein coupling	Voltage-gated K+ channels	NSS in health and disease
S-6	SLO-1	Synthesis of cDNA, and construction of a cDNA library	Agonist-directed signalling	Other types of voltage-gated ion channels	Sodium antiporters
	SLO-2	screening of a cDNA library	Allosteric modulators of GPCR function	CatSper channels	NhaA Na+:H+ antiporter (NhaA) family

S-7	SLO-1	Cloning using a specific antibody, a functional assay and Polymerase chain reaction.	Pharmacological chaperones for GPCRs	Ligand-gated ion channels	The cell penetrating peptides (CPP)	β 1-adrenergic receptor single nucleotide polymorphisms
	SLO-2	What information can DNA cloning provide?	Some key examples of GPCR mutations and their associated disease	Pentameric ligand-gated ion channel family	CPP in health and disease	Are β 1AR SNPs risk factors for heart failure?
S-8	SLO-1	Pharmacologic profile of the 'cloned' and the 'native' drug target	GPCR dimerisation	Nicotinic acetylcholine receptors	ATPase transporters	β 2AR SNPs and asthma
	SLO-2	'cloned' and the 'native' drug target	Methods to study GPCR dimerisation	5-HT ₃ receptor channels and GABA _A receptors	ATPase transporters in health and disease	β 2AR SNPs and cardiovascular function
S-9	SLO-1	Reverse pharmacology	GPCR splice variants 1	P2X receptor structure, signalling and pharmacology	Role of transporters in drug pharmacokinetics	Functional consequences of the Trp64Arg SNP
	SLO-2	Reverse pharmacology illustrated on orphan GPCRs	Clinical and pathophysiological relevance of GPCR splice variants	Therapeutic potential of P2X receptors	Role of transporters in cellular homeostasis	β 3AR Trp64Arg SNP: disease associations

Learning Resources	<ol style="list-style-type: none"> 1. Chris Lloyd Mills, Fiona Freeman, Christian Thode, Shiva Sivasubramaniam, John Dickenson, "Molecular pharmacology : from DNA to drug discovery ", Wiley-Blackwell, 2012. 2. Michael Palmer, Alice Chan, Thorsten Dieckmann, John Honek, "Biochemical Pharmacology", Wiley, 2012. 3. Terry Kenakin, "Pharmacology in drug discovery: understanding drug response", Mica Haley, 2016. 4. Rang and Dale, "Pharmacology", Churchill Livingstone, 2007.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Dr. G. N. Ramchand, Saksin Life sciences Pvt Ltd, Chennai, ramchand@saksinlife.com	Prof. K. Subramaniam, IITM, Chennai, suubu@iitm.ac.in	Mr. Jaganathan. M. K. SRMIST
Dr. Karthik Periyasamy, Scientist I, Aurozymes Unit, Aurobindo Pharma Limited, Hyderabad, karthikmpk@gmail.com	Prof. R. B. Narayanan, SVCE, Chennai, rbn@svce.ac.in	Mr. S. karthik. SRMIST

Course Code	18BTE309T	Course Name	PLANT NUTRITION AND PHYSIOLOGY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Biotechnology	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1:	Understand the food production can be limited by the availability of fresh water and nutrients	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Analyze the role of proton pumps in plant nutrition																		
CLR-3:	Illustrate the flow of each of the macronutrients from soil into the plant body																		
CLR-4:	Compare and evaluate the symptoms of macronutrient deficiencies																		
CLR-5:	Study the roles of plants and soil microbes on global nutrient cycles																		
CLR-6:	Interpret the plant responses to deficiency, limitation and a toxic level of a micronutrient																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1:	Describe the Plant-water relations, uptake and transport	1	80	80	M	H	H	H	M	H	H	H	H	H	H	H	H	H	H
CLO-2:	Explain the contributions of two different transporters to plant salinity tolerance	2	85	75	M	M	H	H	-	H	H	H	H	H	H	H	H	H	H
CLO-3:	Recognize the positive and negative impacts of the use of chemically synthesized fertilizers	2	75	80	M	-	M	H	M	H	H	-	H	H	H	H	H	H	H
CLO-4:	Discuss the different ways to calculate Nutrient use efficiency	2	85	80	-	H	H	H	-	H	H	L	H	H	H	H	H	H	H
CLO-5:	Explain the important of influx and efflux transporters	3	85	75	M	H	H	H	H	H	H	-	H	M	H	H	H	H	H
CLO-6:	Gain knowledge about the biological functions of each of the micronutrients	2	80	80	M	M	H	H	-	H	H	M	H	M	H	H	H	H	H

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Plant Nutrition	Nutrient uptake and transport	Overview	Potassium	Introduction
	SLO-2 Water & mineral nutrients	Overview	Plant nutrient requirements and fertilizers	The ashes in the pot, potash	Micronutrients and Metals
S-2	SLO-1 Mineral nutrients	Energizing the membrane	Macronutrients - N, P, K, S, Mg, and Ca	Potassium uptake and remobilization	Nutrients movement
	SLO-2 Macronutrients & micronutrients	Plasma membrane proton ATPases	The most abundant mineral element in a plant	Biphasic uptake response	The apo- and symplast & membrane transporters
S-3	SLO-1 Water uptake and transport	Vacuolar pumps	Nitrogen metabolism	Sulfur	Iron
	SLO-2 Physical laws	Vacuolar H ⁺ -ATPase and Vacuolar H ⁺ -PPase	Uptake, assimilation and remobilization	Global cycles and cells	Abundant, important, and largely insoluble
S-4	SLO-1 Membrane-bound water channels	Potassium Uptake	Nitrogen regulation	Sulfur uptake	Copper
	SLO-2 Aquaporins	Uptake & response	Nitrogen sensing, signaling and deficit responses	SULTR transporters	Critical for aerobic life
S-5	SLO-1 Movement of water	Potassium Transport	Strategies to mitigate the environmental consequences of N fertilizers	Sulfur – metabolic regulation	Zinc
	SLO-2 Water moves through Soil – Plant – Atmosphere Continuum (SPAC)	Co-transporters, channels, The guard cell model	Field-based practices and breeding	Addressing S-deficiency in plants	Deficiency common in plants and people
S-6	SLO-1 Water uptake in roots	Potassium Homeostasis	The most diverse set of functions	Magnesium	Manganese
	SLO-2 From soil to stele	K ⁺ mobilization is critical for K ⁺ homeostasis	Phosphorus	Magnesium in rocks and cells	Central to the water-splitting, oxygen-evolving reaction
S-7	SLO-1 SPAC	Sodium Toxicity, Transport, and Tolerance	Phosphate acquisition	Mg - Uptake and assimilation	Zinc: Deficiency common in plants and people, Nickel: Necessary but rarely limiting
	SLO-2 Flow of water through the xylem	The challenges of soil salinization	Mining & foraging	MRS/ MGT family	Manganese: Central to the water-splitting, oxygen-evolving reaction. Metal tolerance and metal hyper accumulation

S-8	SLO-1	SPAC	Sodium toxicity and tolerance	Phosphate uptake & transport	Calcium	Toxic metals and metalloids
	SLO-2	From leaf to air	Halophytes and salt-tolerant plants	PHT1 family	Low free cytosolic levels	Arsenic, Cadmium, Aluminum
S-9	SLO-1	Water deficit	Ion pumps, channels	Strategies	Calcium uptake and transport	Essential micronutrient
	SLO-2	Plant responses	Transporters contribute to Na ⁺ tolerance	Improve crop plant phosphorus use efficiency	Calcium signaling	Boron, Silicon, Chlorine, Selenium

Learning Resources	1. Lincoln Taiz and Eduardo Zeiger, "Plant Physiology", Third edition. Panima Publishing Corporation, 2003.
	2. Teaching Tools in Plant Biology: Lecture Notes. The Plant Cell (online) http://www.plantcell.org/content/teaching-tools-plant-biology

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry		Experts from Higher Technical Institutions
Internal Experts		
Dr. Senthil, EID Parry, Chennai, parrynutraceuticals@parry.murugappa.com		Prof. Usha Vijayraghavan, IISc, Bangalore, uvr@mcbl.iisc.ernet.in
Dr. G. N. Ramchand, Saksin Life sciences Pvt Ltd, Chennai, ramchand@saksinlife.com		Dr. R. Pachaiappan, SRMIST
		Prof. Akhilesh. S. Raghubanshi, Banaras Hindu University, Varanasi, asr@bhu.ac.in
		Dr. D.V.L. Sarada, SRMIST

Course Code	18BTE310T	Course Name	PLANT HORMONES AND SIGNALING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Biotechnology	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 : <i>Illustrate how plant hormones contribute to their growth, development, reproduction and stress responses</i>		Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2 : <i>Understand the fundamental properties, tropic movement and mechanism of actions of auxin</i>																								
CLR-3 : <i>Interpret the effects of Cytokinin, and its receptor perception & signaling</i>																								
CLR-4: <i>Study the interaction between Gibberlins receptors and regulation of physiological functions</i>																								
CLR-5: <i>Interpret the phenotypes of Arabidopsis seedlings mutated in ethylene perception, and reconstruct a genetic pathway from double mutant phenotypes</i>																								
CLR-6: <i>Illustrate the interactions of the core signaling for controlling the functions of Absciscic acid in plants</i>																								
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1 : <i>Gain knowledge on major plant hormones</i>		1	80	80	L	M	H	H	H	M	H	H	H	H	H	H	H	H	H	H	H	H		
CLO-2 : <i>Explain the history, synthesis, transport and functions of auxin in plant life</i>		2	85	75	M	M	H	H	H	M	H	H	H	M	H	H	H	H	H	H	H	H		
CLO-3 : <i>Describe the cytokinin biosynthetic pathway, two methods of analyzing and protein kinase cascade</i>		2	75	80	M	M	M	H	M	M	H	M	H	M	H	H	H	H	H	H	H	H		
CLO-4 : <i>Discuss the processes that control the accumulation of bioactive GAs, role of DELLAs and physiological responses</i>		2	85	80	M	M	H	H	M	M	M	M	M	H	M	H	H	H	H	H	H	H		
CLO-5 : <i>Gain knowledge the different physiological responses to ethylene</i>		3	85	75	L	H	M	H	M	M	H	M	H	M	H	L	H	H	H	H	H	H		
CLO-6 : <i>Explain the ways that ABA affects development of roots, fruits and seeds</i>		2	80	80	M	M	H	H	L	M	H	M	H	M	H	M	H	H	H	H	H	H		

Duration (hour)	9	9	9	9	9
S-1	SLO-1 What are phytohormones	Historical studies of auxin	Overview	History and overview	Absciscic acid
	SLO-2 Types	Classical studies	The discovery of cytokinins	Inhibitor of an inhibitor	Plant processes
S-2	SLO-1 Overview of hormone action	Auxin signaling pathway	Cytokinin homeostasis	GA synthesis and homeostasis	Biosynthesis and homeostasis
	SLO-2 Signaling	Biosynthesis and homeostasis	Structure of major CKs	GA deactivation & transport	Zeaxanthin epoxidase, NCED, VP14 & CYP707A
S-3	SLO-1 Hormones and vegetative developments	Tools in auxin research	The Agrobacterium tmr gene is a CK biosynthesis gene	GA perception and signaling	Transport
	SLO-2 Auxin & cytokinin	Experimental evidences	CYP735A	GID1 encodes a GA receptor	ABA movement
S-4	SLO-1 Vegetative development	Auxin transport	Formation of active CKs	GA-regulated growth repressors	Perception and signaling
	SLO-2 Strigolactones, Gibberellins & Brassinosteroids	Polar auxin transport	LONELY GUY, IPT over expression	DELLA proteins	PYR/ RCAR
S-5	SLO-1 Hormonal control of reproductive development	Chemiosmotic model	CK inactivation by conjugation or degradation	GA's roles in whole-plant physiology	ABI1 encodes a PP2C protein phosphatase
	SLO-2 Transition to flowering, development of flowers and fruits	Auxin moves through efflux and influx carrier proteins	Cytokinin oxidase	Response to salt stress, seed germination and Flowering	PP2C binds ABA + receptor & SnRK kinase similarly
S-6	SLO-1 Reproductive development	Types of carrier proteins	CK acts as a paracrine and a long-distance signal	Ethylene is a gaseous hormone	Calcium-dependent protein kinases
	SLO-2 Ethylene & Absciscic Acid	AUX1 / LAX, ABCB family & PIN family	PUP and ENT	Triple response	Transcription factors are major targets of SnRK2s and CDPKs
S-7	SLO-1 Hormonal responses to abiotic stress	Auxin perception - receptors	CK perception and signaling	Ethylene synthesis and homeostasis	ABA's roles in the control of guard cell turgor
	SLO-2 Absciscic Acid	ABP1, TIR1 and AFP protein family of F-box proteins	Two-component-like system	Burg and Thimann's studies, The Yang cycle	SnRK2s and PP2Cs contribute to guard cell responses
S-8	SLO-1 Hormonal responses to biotic stress	Auxin signaling	Downstream of the receptors	Ethylene response	ABA in whole-plant processes

	SLO-2	Jasmonates & Salicylates	Aux/IAA proteins, auxin-responsive transcription factors	Histidine phosphotransfer proteins (HPTs) and response regulators (RRs)	Receptors and downstream signaling	drought stress
S-9	SLO-1	Hormonal crosstalk	Auxin action	CK action in whole-plant processes	Ethylene's roles	surviving extreme desiccation
	SLO-2	Cross-talk in defense signaling	Whole-plant processes	Abiotic and biotic stress responses	Whole-plant processes	systemic stress responses

Learning Resources	<ol style="list-style-type: none"> 1. Lincoln Taiz and Eduardo Zeiger, "Plant Physiology", Third edition. Panima Publishing corporation, 2003. 2. Davies, P. J., "Plant Hormones -Biosynthesis, Signal Transduction, Action", Third Edition, Springer 2010. 3. Teaching Tools in Plant Biology: Lecture Notes. The Plant Cell (online) http://www.plantcell.org/content/teaching-tools-plant-biology.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

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Dr. Karthik Periyasamy, Scientist I, Aurozymes Unit, Aurobindo Pharma Limited, Hyderabad, karthikmpk@gmail.com	Prof. Santa Ram Joshi., Department of Biotechnology & Bioinformatics North Eastern Hill University, Shillong-793022, Meghalaya, srjoshi2006@gmail.com	Dr. D.V.L. Sarada, SRMIST

Course Code	18BTE311T	Course Name	PATHOGENESIS - RELATED PROTEINS IN PLANTS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Biotechnology	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1:	Understand the six different types of pathogens by kingdom and by mode of pathogenicity	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Analyze the role of plant defence proteins against pathogens	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3:	Understand the knowledge about the structural, catalytic mechanism and regulation of PR				M	H	H	H	-	H	H	M	H	H	H	H	H	H	H
CLR-4:	Compare and evaluate the plant – insect and other pathogen interactions				M	-	H	H	-	M	H	H	H	H	H	H	H	H	H
CLR-5:	Study the roles of PR-Proteins in physiological and developmental processes in plants				H	M	-	H	H	H	H	M	H	H	H	H	H	H	H
CLR-6:	Interpret the plant molecular responses to biotic factors				-	M	H	H	-	H	H	M	H	H	H	H	H	H	H
					H	H	H	H	H	H	-	H	M	H	M	H	H	H	H
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1:	Describe the three ways that plants defend themselves against pathogens	1	80	80															
CLO-2:	Explain the physiological functions of pathogenesis related proteins in plants	2	85	75															
CLO-3:	Comprehend the concept of cell wall degrading enzymes produced from plants as a defence	2	75	80															
CLO-4:	Discuss the different ways of resistance to pathogens at molecular level	2	85	80															
CLO-5:	Explain the importance of PR-Proteins in agriculture crop development	3	85	75															
CLO-6:	Gain knowledge about the signals, synthesis, binding to the receptor and role during plant – pathogen interactions	2	80	80															

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Pathogens make plants sick	Introduction	Plant chitinases	The PR-6 Family
	SLO-2	Pathogens include viruses, bacteria, fungi, oomycetes and nematodes	PR- 1 Proteins	PR-3, 4, 8, 11	Proteinase Inhibitors in Plant-Microbe and Plant-Insect Interactions
S-2	SLO-1	Brief history	Characterization	Structure of the Proteins	Occurrence and Structure
	SLO-2	Plant pathology	Acidic and basic proteins	PR-3, A Plant-Specific Chitinase Family (Family 19.), Family 18, The Ubiquitous	Plant Proteinase Inhibitors with Potential Defensive Capabilities
S-3	SLO-1	The disease triangle concept	Occurrence	PR-8/Class III Chitinases, PR-11 Chitinases	Proteinases and Proteinase Inhibitors
	SLO-2	Pathogen, Host, Environment	PR - proteins from other organisms & Functions	Other Related Proteins, The PR-4 Family	Plant–Microbe Interactions
S-4	SLO-1	Strategies of pathogenicity	Expression of PR-1	Catalytic Mechanisms and Specificities	Proteinases and Proteinase Inhibitors
	SLO-2	Pathogen lifestyles – biotrophy, necrotrophy, and hemibiotrophy	Pathogens/wounds, salicylic acid, ethylene and other hormones, UV light and developmental stimuli	Family 18 & 19 Chitinases	Plant–Insect Interactions
S-5	SLO-1	Plant immune responses	PR-1 promoter analysis	Structure and Regulation of the Genes	Ribosome inactivating proteins (RIP)
	SLO-2	Pathogen-triggered & Effector-triggered immunity	Acidic and basic proteins	Chib (PR-8) and Chic (PR-11) Genes	Structure
S-6	SLO-1	Pathogen-recognition receptors	Introduction	Functions of Plant Chitinases	RIP
	SLO-2	PTI stimulates production of phytoalexins, reactive oxygen and callose	PR-2 – β -1,3-Glucanases	Antifungal and other physiological	Function, and Engineering
S-7	SLO-1	Recognition and response to effectors through paired R proteins	Structural classes	PR-5 - Thaumatin-like proteins	Plant defensins
	SLO-2	ETI and biochemical response	PR-2 Nomenclature	Occurrence, Physico-Chemical properties	Introduction
S-8	SLO-1	Induction	Biological functions of β -1,3-Glucanases	Biological properties	Protein Structure
					PR Proteins

	SLO-2	Pathogenesis Related proteins (PR-Proteins)	Plant reproductive and defence	Taste, Antifungal Activity, TLPs as Anti-Freeze Proteins & TLPs as Inhibitors?	Disulfide-linked cysteine residues	Antifungal and insecticidal proteins
S-9	SLO-1	PRs, and PR like proteins	Regulation of β -1,3-Glucanases expression	Regulation of TLP Expression	Antimicrobial Activities	PR proteins in Rice
	SLO-2	Occurrence, properties and functions	Developmental and hormonal & pathogenic	Microbial Infection, Osmotic Stress, Absciscic Acid and Ethylene, Salicylate, Methyl Jasmonate, and Elicitors, Wounding.	Structure activity relationships, Mode of action	IR72 and IR64

Learning Resources	<ol style="list-style-type: none"> 1. Agrios, G.N. (2005). <i>Plant Pathology</i>. (Burlington, MA: Elsevier Academic Press). 2. Schumann, G.L., and D'Arcy, C.J. (2010). <i>Essential Plant Pathology</i>. (St. Paul, MN: The American Phytopathological Society). 3. Swapan K. Datta and Muthukrishnan, "Pathogenesis –Related Proteins in plants", CRC Press, 1999.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Dr. Senthil, EID Parry, Chennai, parrynutraceuticals@parry.murugappa.com	Prof. Usha Vijayraghavan, IISc, Bangalore, uvr@mcbl.iisc.ernet.in	Dr. R. Pachiappan, SRMIST
Dr. G. N. Ramchand, Saksin Life sciences Pvt Ltd, Chennai, ramchand@saksinlife.com	Prof. Appa Rao Podile, Central University, Hyderabad, podilerao@gmail.com	Dr. D.V.L. Sarada, SRMIST

Course Code	18BTE312T	Course Name	FOOD SCIENCE AND NUTRITION	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Biotechnology	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 : Identify the need for greater and more efficient utilization of the existing food sources		1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 : Demonstrate nutritional quality and nutritional requirement		Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 : Solve calculate energy requirements of the body		Expected Proficiency (%)	Problem Analysis
CLR-4 : Describe about new trends in nutrition		Expected Attainment (%)	Design & Development
CLR-5 : Design balanced meal preparation			Analysis, Design, Research
CLR-6 : Identify antinutritional factors in food			Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 : Define basic concepts of Food and Nutrition		2 80 70	H H H H H H H H H H H H H H H H
CLO-2 : Formulate food with daily dietary allowances		2 80 70	H H H H H H H H H H H H H H H H
CLO-3 : Identify the scope and prospects of food science in food industries		2 80 70	M H H H M H M H H H H H H H H H
CLO-4 : Design diet according to energy requirements of the body		2 80 70	H H H H H H M H H H H H H H H H
CLO-5 : Design diet for different age group and for people under diseased condition		3 80 70	H H H H H H M H H H H H H H H H
CLO-6 : Evaluate food constituents and its importance		2 80 70	H H H H H H H H H H H H H H H H

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Food as a source of energy	Functions of protein, fat and carbohydrates and their dietary requirements	Carbohydrates- dietary requirements and functions, deficiency in diet	Function and daily intake of water	New trends in nutrition-nutritional value of fast food and junk food
	SLO-2 Macro and micro nutrients	Sources of Carbohydrates	Nutritional significance of carbohydrates ,	Daily loss of body water and deficiency of water	Probiotics and prebiotics
S-2	SLO-1 Carbohydrate, Fat and Protein	Classification of Carbohydrates	Digestion, metabolism and absorption of carbohydrates	Sources of vitamins	Antioxidants
	SLO-2 Food requirement in human body	Polysaccharides –Starch and dietary fibers	Nutritional significance of proteins	Fat soluble vitamins –A,D,E, and K	Nutraceuticals
S-3	SLO-1 Planning balanced diets to meet the requirements of different age groups	Chemical composition of cereals	Animal sources of protein	Water soluble Vitamins-B-complex vitamins, Anemia –preventing vitamins and Vitamin-C	Fortification
	SLO-2 Solving Problems-	Nutritional value of cereals	Digestion, metabolism and absorption of protein	Effect of cooking on vitamins	Significance of nutritional labeling
S-4	SLO-1 Energy requirements of the body	Protein- dietary requirements, functions, and deficiency in diet	Nutritional significance of lipids	stability of vitamin during food processing	Trans fatty acids
	SLO-2 Calculations of energy value based on proximate principles	Sources of Protein	Classification of lipids	toxicity due to vitamins	Role of photochemical
S-5	SLO-1 BMR, Test for basal metabolism and Factors affecting BMR	Chemical composition of pulses (grams and dhal)	Plant Sources of fat/oil	bioavailability of vitamins	Naturally occurring food toxicants in foods
	SLO-2 Estimation of energy requirements	Nutritional value of pulses	Marine and animal sources of fat/oil	reasons for losses of vitamins in foods	protease inhibitors
S-6	SLO-1 Instrumental methods to calculate caloric value of food	Antinutritional factors in pulses	Digestion, metabolism and absorption of fat	Role of these constituents in food industry	hemagglutinins
	SLO-2 RDS's for specific nutrients	Chemical composition of oil seeds	The food pyramid	Mineral in food	goitrogens
S-7	SLO-1 Dietary allowances fixed by FAO	effect of processing on the nutritional value of food grains (cereals and pulses)	Therapeutic diets – A brief account.	Classification of minerals	lathrogens

	SLO-2	Dietary allowances fixed by WHO	Chemical composition of cereals	Planning of balanced meal	Sources of minerals in food	toxic amino acids
S-8	SLO-1	Recommended dietary allowances for Indians fixed by ICMR	Nutritional value of cereals	Dietary requirement for different Age group	stability status of minerals in food	naturally occurring carcinogens in food
	SLO-2	comparison of Indian dietary allowances with that of FAO/WHO standards	Chemical composition of pulses (grams and dhal)	Dietary requirement for women at different stages of life	Nutritional value of fruits	Carcinogens produced during food processing and storage
S-9	SLO-1	Modifying energy content of meals	Nutritional value of pulses	Meal frequency pattern and variety in balanced diet	Nutritional value of vegetables	Acrylamide formation in food
	SLO-2	Under weight/overweight/obesity	Antinutritional factors in pulses	Calculating nutritional value of a recipe	Nutritional value of beverages	furan formation in food

Learning Resources	1. Sunetra Roday. "Food science and nutrition". 2016, Oxford university Press.. 2. Swaminathan, M. (5 th Edition). "Hand Book of food and Nutrition", 2015. The Bangalore Printing and Publishing co. Ltd. Bangalore 3. Ahuja, K.J, Nath Prem and K.R.M Swamy Food and Nutrition, 2010. Studium Press Pvt. Ltd., New Delhi., 4. Shakuntala Manay and Shadasharasamy "Foods; Facts and principles", 1997. New Age international Publishers, New Delhi.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. S. Sam Gunasekar, Orchid Chemicals and Pharmaceuticals Ltd., sam@orchidpharma.com	1. Dr. A. Gnanamani, CSIR-Central Leather Research Institute, agmani_2000@yahoo.com	Dr. K.A.Athmaselvi, SRMIST
2. Dr. D. Gunaseelan, BIOCON Ltd., guna.sachin@gmail.com	2. Dr. Anbumani Sadasivam, CSIR-Indian Institute of Toxicology Research, anbumani@iitr.res.in	Dr. R.Preetha, SRMIST

Course Code	18BTE405T	Course Name	THERAPEUTIC COMPOUNDS FROM PLANTS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Biotechnology	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1:	Gain knowledge on historical uses of plants and plant parts as medicines and traditional knowledge	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Understand the techniques involved in Bioprospecting	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3:	Understand the major secondary metabolic pathways that produce pharmaceutically important compounds				L	M	H	H	H	H	H	H	H	H	H	H	H	H	H
CLR-4:	Understand the structures and roles of the major classes of photochemicals with medicinal properties				H	H	H	H	H	H	H	H	H	H	H	H	H	H	H
CLR-5:	Gain insight into engineering for enhanced production of pharmaceutically important metabolites in planta				H	H	M	H	H	M		M	H	H	H	H	H	H	H
CLR-6:	Know the mechanism of action of major known pharmaceutically important compounds in therapeutics				H	H	H	H	H		L	L	H	H	H	H	H	H	H
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:	1	80	80	H	H	H	H	H	L	L	H	H	H	H	H	H	H
CLO-1:	Identify plants and plant parts used as medicine traditionally					2	85	75											
CLO-2:	Apply techniques to screen plants for drugs and medicines					2	75	80											
CLO-3:	Analyze the secondary metabolic pathways that produce several medicinally important compounds					3	85	80											
CLO-4:	Deduce structure activity relationship					3	85	75											
CLO-5:	Predict the metabolic branch points that can be targeted for engineering					2	80	80											
CLO-6:	Explain the mechanism of action of major known pharmaceutically important compounds in therapeutics																		

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Plants vs Medicinal Plants	Overview of extraction and purification of Phytoconstituents	Primary vs Secondary Metabolism	In vitro Synthesis – Advantages and disadvantages
	SLO-2	Taxonomy and validation of Herbal Medicine	Extraction Techniques	Examples of Major Secondary Metabolic Pathways	Omics, Systems and Semi synthetic methods
S-2	SLO-1	Traditional Indian Medicine	Different Types	The Mevalonate Pathway	Metabolic Engineering - Strategies
	SLO-2	Traditional Chinese Medicine	Advantages and Limitations of Extraction Techniques	Examples	Alteration, Silencing and augmentation of functions
S-3	SLO-1	Traditional Knowledge	Analytical Techniques - Spectrometry	The Shikmate Pathway	Pioneering studies microbial synthesis of plant metabolites
	SLO-2	Ethanobotany	Purification	Examples	Reconstitution of metabolic pathways in microbes
S-4	SLO-1	Quality Assurance of Herbal Medicines	Analytical Techniques – Chromatography	The Phenyl Propanoid and the Polyketide Pathway	Host Selection and Pathway reconstitution
	SLO-2	Over the Counter Herbal Medicines	Bioassay Guided Fractionation	Examples	Optimization
S-5	SLO-1	Plant Extracts vs Purified Compounds	Identification	Biosynthesis of Alkaloids	Metabolic Engineering for alkaloid production in Yeast
	SLO-2	Quest for Active Compounds	Analytical Techniques –Mass Spectrometry	Tissue Cultures for production of metabolites	Metabolic Engineering for terpenoid production in Yeast
S-6	SLO-1	Modern Approaches	Standardization	Examples	Metabolic Engineering for carotenoid production in Yeast
	SLO-2	Screening plants for Drugs	Clinical Validation	Organ Cultures for production of metabolites	Metabolic Engineering for caffeine production in Yeast
S-7	SLO-1	Plant Families associated with Drug Production	Example from TIM to clinical trials	Examples	Other Examples

	SLO-2	Drug discovery by relatedness	Example from TCM to clinical trials	Hairy Root Cultures as a means for enhanced metabolite production	Metabolic Engineering in Plants and Plant Cell Cultures	Terpenoids against Trypanosomes
S-8	SLO-1	Phytoconstituents	Central Drugs Control Standard Organization	Manipulation of hairy roots for metabolite production	Metabolic Engineering of Terpenoids in Plants	Terpenoids against Leishmanias
	SLO-2	Alkaloids	Drugs Technical Advisory Board (DTAB) and Drugs Consultative Committee (DCC)	Production of Ginsenosides	Metabolic Engineering of Alkaloids in Plants	Ephedra- Use and Misuse
S-9	SLO-1	Flavanoids	Regulatory Approval	In vitro production – Role of Endophytes	Metabolic Engineering of Flavanoids in Plants	Ginseng – The Panacea
	SLO-2	Terpenoids	Pharmacovigilance	Production of Taxol	High throughput methods to identify genes intermediates and pathways	Traditional vs Western Medicine

Learning Resources	<ol style="list-style-type: none"> 1. Trease and Evans Pharmacognosy, William Evans, Sixteenth Edition Elsevier 2009 2. Phytochemical Methods – A guide to Modern Techniques in Plant Analysis, Harborne Springer 1998 3. Text Book of Pharmacognasy and Phytochemistry, First Edition, Biren Shah, Elsevier 2009 4. Fundamentals of Pharmacognosy and Phytotherapy Second Edition Michael Heinrich, Joanne Barnes, Simon Gibbons and Elizabeth M. Williamson, Elsevier 2012
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Dr. G. N. Ramchand, Saksin Life sciences Pvt Ltd, Chennai, ramchand@saksinlife.com	Prof.. K Subramaniam, IITM, Chennai, suubu@iitm.ac.in	Dr. R. Pachaiappan, SRMIST
Dr. Karthik Periyasamy, Scientist I, Aurozymes Unit, Aurobindo Pharma Limited, Hyderabad, karthikmpk@gmail.com	Prof. R. B. Narayanan, SVCE, Chennai, rbn@svce.ac.in	Dr. Sarada, DVL, SRMIST

Course Code	18BTE406T	Course Name	FOOD SAFETY AND QUALITY MANAGEMENT	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Biotechnology	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :		Describe safety limits of food additives and risk assessment			Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :		Memorize to prepare HACCP based SOP																						
CLR-3 :		Prepare HACCP program to any food industry																						
CLR-4 :		Apply quality auditing in the food industries																						
CLR-5 :		Describe ISO 9000, ISO 14000, ISO 22000																						
CLR-6 :		Employ ISO 22000 in food industry																						
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			Expected Proficiency (%)	2	80	70	Problem Analysis	H	H	H	M	H	H	H	H	H	H	H	H	H	H	H
CLO-1 :		Describe about the food safety terms																						
CLO-2 :		Identify the issues of food safety and quality																						
CLO-3 :		Explain the process of food safety analysis																						
CLO-4 :		Describe basic concepts of Food Safety and Quality Management																						
CLO-5 :		Set up and operate HACCP, SOP and ISO 22000 for food industries																						
CLO-6 :		Practice quality auditing methods in the food industries			Expected Attainment (%)	2	80	70	Design & Development	H	H	H	M	H	H	M	H	H	H	H	H	H	H	H

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Definition of Quality, Dimensions of Quality	Safety limits of Food additives	Sampling	Quality of Foods
	SLO-2	Quality Planning, Quality costs	Risk assessment and risk benefit Indices of human exposure	concept, methods and importance of sampling	Quality Standards - mandatory and optional standards
S-2	SLO-1	Basic concepts of Food Safety and Quality Management	acute toxicity	Statistical Process and Quality Control	Food Safety Systems
	SLO-2	Historical Review, Principles of FSQM	mutagenicity and carcinogenicity	concept, importance and tools	ISO 9000, ISO 14000, ISO 22000
S-3	SLO-1	Leadership Concepts	reproductive and developmental toxicity	Control charts	Mechanism of developing and fixing food standards
	SLO-2	Quality Council, Quality Statements	teratogenicity, neurotoxicity and behavioral effect, immunotoxicity	importance, types, design process control limits	Good Manufacturing Practice
S-4	SLO-1	Strategic Planning	Determination of the limit for addition		
	SLO-2	Barriers to Food Safety Implementation	NOEL – Method of determining toxicity	Errors in process control	HACCP Standards of Weights
S-6	SLO-1	Barriers to Food Safety Implementation	LD50, FSSAI regulations and GRAS additives.	Process Capability.	HACCP Standards of Measures
	SLO-2	Definition of Quality, Dimensions of Quality	Safety limits of Food additives	Sampling	Quality of Foods
S-7	SLO-1	Quality Planning, Quality costs	Risk assessment and risk benefit Indices of human exposure	concept, methods and importance of sampling	Quality Standards - mandatory and optional standards
	SLO-2	Basic concepts of Food Safety and Quality Management	acute toxicity	Statistical Process and Quality Control	Food Safety Systems
S-8	SLO-1	Historical Review, Principles of FSQM	mutagenicity and carcinogenicity	concept, importance and tools for quality control	ISO 9000, ISO 14000, ISO 22000
	SLO-2	Leadership Concepts	reproductive and developmental toxicity	quality control charts	Mechanism of developing and fixing food standards

S-9	SLO-1 SLO-2	Quality Council, Quality Statements	teratogenicity, neurotoxicity and behavioral effect, immunotoxicity	importance, types, design process	Good Manufacturing Practice	Quality circle, Quality audit, Internal audit
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Learning Resources	1. Andres Vasconcellos J. 2 nd edition. <i>Quality Assurance for the Food industry - A practical approach</i> . 2005, CRC press. 2. Intez Alii. 1 st edition, <i>Food quality assurance - Principles & practices</i> . 2004, CRC Press. New York.	3. Sara Mortimore and Carol Wallace. 3 rd edition <i>HACCP - A practical approach</i> . 2013, Chapman and Hall, London. 4. Roday, S. 2 nd edition <i>Food Hygiene and Sanitation</i> , 201, Tata McGraw-Hill Education.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Dr. S. Sam Gunasekar, Orchid Chemicals and Pharmaceuticals Ltd., sam@orchidpharma.com	Dr. A. Gnanamani, CSIR-Central Leather Research Institute, agmani_2000@yahoo.com	Dr. K.A.Athmaselvi, SRMIST
Dr. D. Gunaseelan, BIOCON Ltd., guna.sachin@gmail.com	Dr. Anbumani Sadasivam, CSIR-Indian Institute of Toxicology Research, anbumani@iitr.res.in	Dr. R.Preetha, SRMIST

Course Code	18BTE313T	Course Name	ENZYME ENGINEERING AND TECHNOLOGY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Biotechnology	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 : Discuss the basics of enzyme mechanism, classification, and factors affecting enzyme activity		1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 : Analyze the kinetics of enzyme action, inhibition, and their regulation			
CLR-3 : Examine the sequential procedure of the enzyme purification process			
CLR-4 : Apply the various methods of enzyme immobilization and evaluating their kinetic efficiency			
CLR-5 : Discuss the applications of enzymes in various industries			
CLR-6 : Demonstrates the importance of enzymes in engineering research and industries			
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	
CLO-1 : Recognize the basic nature of enzyme, classification and their mechanism of working		1 80 80	Engineering Knowledge
CLO-2 : Describe the various kinetic mechanisms and regulation of enzyme actions		2 85 75	Problem Analysis
CLO-3 : Formulate the succession of enzyme purification and their characterization		2 75 80	Design & Development
CLO-4 : Illustrate the methods of enzyme immobilization and evaluating the effectiveness of immobilization		2 85 80	Analysis, Design, Research
CLO-5 : Assess the extent of enzyme applications in various industries		3 85 75	Modern Tool Usage
CLO-6 : Interpret the mechanisms of enzyme action and evaluating their importance in various applications		2 80 80	Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3

Duration (hour)	9	9	9	9	9
S-1 SLO-1	Chemical nature of enzymes	Basics of enzyme kinetics	Production of enzymes on a commercial scale	Enzyme immobilization	Applications of enzymes - Food processing
SLO-2	Characteristics of enzymes	Michaelis-Menten Kinetic equation	Nature of the extraction medium	Advantages and disadvantages	Starch and sucrose industries
S-2 SLO-1	Enzymes and their actions	Significance of Michaelis-Menten Kinetics	Extraction of soluble enzymes	Physical methods of enzyme immobilization	Dairy industries
SLO-2	Mechanism of enzyme action	Solving problems in enzyme kinetics	Extraction of membrane-bound enzymes	Chemical methods of enzyme immobilization	Brewing industries
S-3 SLO-1	Structural components of enzymes	Evaluation of Michaelis-Menten kinetic parameters	Technologies for enzyme production	Carrier-based immobilization	Beverage industries
SLO-2	The active site of an enzyme	Line weaver Burk plot, Hanes Woolf plot and Eadie Hofstee plot	Recovery and purification methods for enzymes	Carrier free immobilization	Leather industries
S-4 SLO-1	Cofactors and coenzymes	Turn over number, Catalytic efficiency	Cell disruption	Immobilization by using porous support	Textile industries
SLO-2	Role of cofactors and coenzymes	Enzyme Inhibitors	Solid-liquid separation	Mass transfer effects and diffusion limitations	Detergent industries
S-5 SLO-1	Classification of enzymes	Types of enzyme inhibition	Concentration	Immobilization by using non-porous support	Pulp and paper industries
SLO-2	Enzyme commission classification of enzymes	Competitive inhibition	Precipitation	Mass transfer effects and diffusion limitations	Polymer industries
S-6 SLO-1	Oxidoreductase, Transferase, Hydrolase	Uncompetitive inhibition	Liquid-liquid extraction	Stabilization of immobilized enzymes in aqueous environment	Analytical applications of enzymes
SLO-2	Lyase, Isomerase, Ligase	Noncompetitive inhibition	Ion exchange chromatography	Stabilization of immobilized enzymes in non-aqueous environment	Diagnostic applications of enzymes
S-7 SLO-1	Enzyme-substrate complex formation models	Substrate inhibition	Gel filtration, Affinity chromatography	Electrostatic and steric effects in immobilized enzyme systems	Role of enzymes - Pharmaceuticals

	SLO-2	Lock and Key and Induced fit models	Feedback inhibition	Criteria of purity – Electrophoresis	Analyzing the effectiveness factor of immobilized enzymes	Medicine
S-8	SLO-1	Mechanisms of enzyme catalysis	Enzyme deactivation model	Isoelectric focusing, Capillary electrophoresis	Applications of immobilized enzyme systems	Medical research
	SLO-2	Proximity and orientation effects, Conformational distortion	Allosteric activation and inhibition	Monitoring of purification of enzymes	Limitations of immobilized enzyme systems	Agriculture
S-9	SLO-1	Factors affecting enzyme activity	Solving problems in enzyme inhibition	Determination of molecular weight of enzymes- MALDI-TOF	Solving problems in enzyme immobilization and their kinetics	Environment protection
	SLO-2	Effect of substrate, enzyme and inhibitor concentration on enzyme activity	Solving problems in enzyme inhibition	Drying and packing	Solving problems in enzyme immobilization and their kinetics	Biofuels development

Learning Resources	<ol style="list-style-type: none"> 1. Trevor Palmer and Philip L Bonner. "Enzymes: Biochemistry, Biotechnology, Clinical Chemistry," East-West Press, 2004. 2. Syed Tanveer Ahmed Inamdar. "Biochemical Engineering: Principles and Concepts "Third Edition, PHI Learning Pvt. Ltd., 2012 3. Kargi. F., Shuler. M.L., "Bioprocess Engineering: Basic Concepts," 3rd Edition. Prentice Hall, 2017.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Dr. G. N. Ramchand, Saksin Life sciences Pvt Ltd, Chennai, ramchand@saksinlife.com	Prof. K Subramaniam, IITM, Chennai, subbu@iitm.ac.in	Dr. V.Vinothkumar, SRMIST, vinothkumar.v@ktr.srmuniv.ac.in
Dr. Karthik Periyasamy, Scientist I, Aurozymes Unit, Aurobindo Pharma Limited, Hyderabad, karthikmpk@gmail.com	Prof. R. B. Narayanan, SVCE, Chennai, rbn@svce.ac.in	Ms. P.Radha, SRMIST, radha.p@ktr.srmuniv.ac.in

Course Code	18BTE314T	Course Name	MEMBRANE TECHNOLOGY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Biotechnology	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1:	Acquire knowledge on membrane and its types cum application	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Understand the casting and characterization of membrane	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3:	Analyse the functions of reverse osmosis, Micro and ultra-filtration membranes				M	M	H	M	M						H	H	H	H	H
CLR-4:	Discuss the functions of dialysis and electro dialysis membrane				M	M	H	M	M						H	H	H	H	H
CLR-5:	Discuss the membranes as reactor and distillation of alcohol				M	M	H	M	M						H	H	H	H	H
CLR-6:	Get acquaint on membranes for industrial application				M	M	H	M	M						H	H	H	H	H
					M	M	H	M	H						H	H	H	H	H
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1:	Apply membranes for bioprocess industries	2	80	90															
CLO-2:	Demonstrate methods of casting membrane	2	85	90															
CLO-3:	Utilize the selection of membranes for micro and Macro molecules separation	2	75	80															
CLO-4:	Apply membrane for dialysis	2	90	85															
CLO-5:	Demonstrate membrane for distillation and production	2	80	80															
CLO-6:	Explain membrane in upstream and downstream process economically	2	80	80															

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Overview of membrane separation process	Membrane Types, Materials, Preparation and Characterization	Reverse Osmosis, Nano filtration, Ultra filtration, and Microfiltration	Dialysis, pervaporation and electro dialysis
	SLO-2	Equilibrium and rate controlled separation	Types of Synthetic Membranes- Micro porous Membranes	Concept of osmosis	Principles of Dialysis
S-2	SLO-1	What is membrane?	Asymmetric, thin film	Determination of osmotic pressure and thermodynamics of osmosis	Dialysis membranes
	SLO-2	Basic principles of Membrane Separation	Electrically Charged Inorganic Membrane	Phenomena of Reverse osmosis	Mass transfer in dialysis
S-3	SLO-1	Historical development of Membranes	Membrane Modules-Plate and frame, Tubular.	Models of Reverse osmosis	Design of Dialysis membranes
	SLO-2	Golden age of Membranes	Spiral wound and Hollow fiber	Design and operating parameters	Applications and its advantages.
S-4	SLO-1	Classification of Membrane Processes	Typical Flow pattern	Design of Reverse Osmosis module	Principles
	SLO-2	Pressure driven, Concentration gradient and Electrical Potential	Membrane Material	Principles, Transport Mechanism	Operation of Pervaporation
S-5	SLO-1	Advantages of Membrane Processes	Pore Characterization	Mass transfer and Industrial Application of Nano filtration	Application of Pervaporation
	SLO-2	Disadvantages of Membrane Processes	General Methods of Membrane Manufacture	Process Limitation	Design of pervaporation modules
S-6	SLO-1	Biotechnology Industry	Phase Inversion Method,	Basic principles of Ultra filtration Types of Ultra filtration	Factors affecting pervaporation
	SLO-2	Micro and Macromolecule Separation	Track-etching	Factors affecting Ultra filtration and membrane flux of ultra filtration	Applications
S-7	SLO-1	Chemical and Pharmaceutical Industry	Sol-gel Peptisation Method	Principles of Microfiltration	Principles of Electro dialysis Ion Exchange Membranes
	SLO-2	Recovery of salt, acid and Bases	Interfacial Polymerization	Microfiltration Membranes	Energy requirements
S-8	SLO-1	Food and Dairy Industry	Melt pressing	Mechanism of Transport	Current utilization and Efficiency
					Membrane in Desalination

	SLO-2	Dairy, animal Products , Fruits and Vegetables etc.	Film Stretching	Flow characterization	Application	Membrane in in Fuel cells
S-9	SLO-1	Electrochemical Industry	Template Leaching	Fouling and applications in Microfiltration	Batch electro- dialysis	Biomedical application of membranes
	SLO-2	Effluent Treatment Plant	Ion Exchange Membrane Preparation	Energy Consideration and Application	Continuous electro- dialysis	Blood Oxygenator and Drug Delivery

Learning Resources	<ol style="list-style-type: none"> 1. Kaushik Nath, " Membrane Separation Processes", PHI, Publication, India, 2012. 2. William.K..Wang," Membrane Separations in Biotechnology", Marcel Dekker. INC, New York,2001 3. Scott .K, "Hand Book of Industrial Membranes "Elsevier Publication, 1995.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Dr. P. BalaKumaran, Proklean Technologies (P) Limited, Chennai, genbalu86@gmail.com	Prof. K Subramaniam, IITM, Chennai, subbu@iitm.ac.in	1 .Dr.M.Venkatesh Prabhu SRM IST
Dr. Karthik Periyasamy, Aurobindo Pharma Limited, Hyderabad, karthikmpk@gmail.com	Prof. R. B. Narayanan, SVCE, Chennai, rbn@svce.ac.in	2 .Dr. Y.Ravichandran SRM IST

Course Code	18BTE315T	Course Name	INDUSTRIAL FERMENTATION TECHNOLOGY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Biotechnology	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1:	Analyze the fundamental behind the need of aseptic strain development.	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Explore the importance of Isolation and Screening of Industrially Important Microorganisms	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3:	Decipher an understanding on the production of various primary metabolites from microbial fermentation																		
CLR-4:	Comprehend the importance and production of secondary metabolites with commercial significance																		
CLR-5:	Apprehend the biochemical transformation in the production of recombinant protein with medical importance																		
CLR-6:	Instigate knowledge on food fermentation, food flavourants, preservatives and SCP																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1:	Accomplish knowledge on improvement of strain development for primary and secondary metabolites	2	80	70	H	H	H	H		H		H		H	H	H	H	H	H
CLO-2:	Explain the upstream and Downstream fermentation process of organic acids and aminoacids	2	85	75	H	H	H	H		H		H		H	H	H	H	H	H
CLO-3:	Describe the industrial scale methodologies for Antibiotic and microbial enzyme production	3	75	80	H	H	H	M	H		H		H		H	H	H	H	H
CLO-4:	Understand enzyme biotransformation biotransformations and recombinant protein production with commercial and medical importance	3	85	80	H	H	H	H	H		M		H		H	H	H	H	H
CLO-5:	Apprehend the food fermentation process and its preservatives used for improving the shelf period	3	85	80	H	H	H	H	H		M		H		H	H	H	H	H
CLO-6:	Decipher the availability and application of various food colourants, flavourants and SCP	2	80	75	H	H	H	H	H		M		H		H	H	H	H	H

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Introduction to industrial fermentations	Production of primary metabolites	Production of secondary metabolites	Recombinant protein production	Food fermentations
	SLO-2 Chronological Development of the Fermentation Industry	Organic acids fermentation	Antibiotic production	Insulin - Upstream process	Cheese and Yogurt fermentation
S-2	SLO-1 Isolation and Screening of Industrially Important Microorganisms	Citric acid – Upstream process	Carbohydrate containing antibiotic: Streptomycin - Upstream process	Insulin - Downstream process	Sauerkraut and Soy sauce fermentation
	SLO-2 Types of fermentation process	Citric acid – Downstream process	Streptomycin - Downstream process	Interferon - Upstream process	Food flavoring agents' fermentations
S-3	SLO-1 Microbial growth metabolism	Lactic acid – Upstream process	Macro cyclic lactones: Erythromycin - Upstream process	Interferon - Downstream process	Mono sodium glutamate fermentation
	SLO-2 Microbial metabolites	Lactic acid – Downstream process	Erythromycin - Downstream process	Production of nucleosides and nucleotides	γ-decalactone fermentation
S-4	SLO-1 Strain development	Acetic acid – Upstream process	Peptide antibiotic: Bacitracin - Upstream process	5' Inosine monophosphate	Food preservative fermentation
	SLO-2 Improvement of Strains Producing Primary metabolites	Acetic acid – Downstream process	Peptide antibiotic: Bacitracin - Downstream process	5' Guanosine monophosphate	Nisin fermentation
S-5	SLO-1 Improvement of Strains Producing Secondary metabolites	Amino acids fermentation	Industrial Enzyme production	Enzyme biotransformations	Food colorants fermentation
	SLO-2 Preservation of Industrially Important Cell Cultures and Microorganisms	L-glutamic acid - Upstream process	Protease - Upstream process	Steroid transformations	Monascus pigments fermentation
S-6	SLO-1 Inoculum Development	L-glutamic acid – Downstream process	Protease - Downstream process	Antibiotic transformations	Carotenoid production
	SLO-2 Aseptic Inoculation of Plant Fermenters	L-lysine – Upstream process	Lipase - Upstream process	Biopolymers fermentation	Astaxanthin Production
S-7	SLO-1 Measuring Process Variables	L-lysine – Downstream process	Lipase - Downstream process	Xanthan gum	Production of single cell protein
	SLO-2 Product development:	L-tryptophan - Upstream process	Vitamins production	Polyhydroxyalkanoates	Bel – symba – pekilo – pruteen processes
S-8	SLO-1 Regulation and safety	L-tryptophan - Downstream process	Cyanoacobalamin - Upstream process	Polyhydroxybutyrate	Beverages
	SLO-2 Use of Process flowcharts	Solvents fermentation	Cyanoacobalamin - Downstream process	Agrochemicals production	Brewing process

S-9	SLO-1	Use of Process block diagrams	Acetone - Butanol – Ethanol - Upstream process	Riboflavin - Upstream process	Bacillus thuringensis	Wine production
	SLO-2	Examples	Acetone - Butanol – Ethanol - Downstream process	Riboflavin - Downstream process	Artemisinin	Cider production

Learning Resources	1.	Cruger W., Cruger A., Aneja K.R., "Biotechnology: A Textbook of Industrial Microbiology", Medtech Publishing, 3 rd edition, 2017.	5.	Saran S., Babu V., Chuabey A., "High Value Fermentation Products: Human Health", Scrivener Publishing, 2019
	2.	Lee Y.K., "Microbial Biotechnology: Principles and Applications", World Scientific Publishing, 3 rd edition, 2013.	6.	Stanbury. P.F., Whitaker. A., Hall. S.J., "Principles of Fermentation Technology", 3 rd Edition, Butterworth–Heinemann, 2016.
	4.	Waites M. J., Morgan N.L., Rockey J.S., Higon G., "Industrial Microbiology: An Introduction", Blackwell Science, 2013.		

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Dr. P. BalaKumaran, Proklean Technologies (P) Limited, Chennai, genbalu86@gmail.com	Prof. K Subramaniam, IITM, Chennai, subbu@iitm.ac.in	Dr. V. Vinoth Kumar, SRMIST
Dr. Karthik Periyasamy, Aurobindo Pharma Limited, Hyderabad, karthikmpk@gmail.com	Prof. R. B. Narayanan, SVCE, Chennai, rbn@svce.ac.in	Dr. M. Venkatesh Prabhu, SRMIST

Course Code	18BTE316T	Course Name	BIOREACTOR DESIGN	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18BTC107J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Biotechnology	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 : Understand the basic design and development of Bioreactors and its operation		Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2 : Design the air driven reactors																								
CLR-3 : Acquire knowledge on different types of Solid state bioreactors and its operation																								
CLR-4 : Learn about the sequential batch reactor and biofilm reactors																								
CLR-5 : Know about the modeling, simulation, Control and CFD analysis of bioreactor																								
CLR-6 : Familiarized with concept of design and application of reactors																								
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1 : Know the basic design of reactor		1	85	80																				
CLO-2 : Acquire knowledge on air driven reactor		2	90	80																				
CLO-3 : Know about reactors for solid state fermentation		2	80	80																				
CLO-4 : Have knowledge on biofilm reactor		2	80	80																				
CLO-5 : Know about modeling, simulation and control system used in reactor		2	85	80																				
CLO-6 : Acquire the basic knowledge on design of SMF and SSF and its control		2	80	80																				

Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
H	H	H	H	M				H	M	H	H	H	H	H
H	H	H	H	M				H	M	H	H	H	H	H
H	H	H	M	L				H	M	H	H	H	H	H
H	H	H	H	M				H	M	H	H	H	H	H
H	H	H	H	M				H	M	H	H	H	H	H
H	H	H	H	H				H	M	H	H	H	H	H

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Understanding of Bioreactor Design	Air Driven Reactors	Solid State Fermentation Bioreactors	Sequential Batch ,Biofilm and Trickle flow reactors
	SLO-2	Basics and importance of bioreactors	General features of bubble column and airlift reactor	Solid-State Bioreactor Fundamentals: Selection and design of SSF reactors	Sequential Batch reactors
S-2	SLO-1	Guidelines for bioreactor design	Factors influencing mass transfer in bubble column	Heat transfer in SSF reactors	Bioreactors containing microbial films
	SLO-2	General requirement for Mechanical construction of Bioreactor	Flow patterns , liquid mixing and gas dispersion in bubble column, Mass and Heat transfer in bubble column	Mass transfer in SSF reactors	Completely mixed microbial reactor
S-3	SLO-1	Design of thin walled , internal pressure, stirred tank reactor	Airlift bioreactors	Laboratory and pilot scale of solid state bioreactor	Microbial film Bioreactor
	SLO-2	Solving Problems	Design and construction of the airlift loop reactor	Industrial scale of solid state bioreactor	Design and Construction
S-4	SLO-1	Development of bioreactors	Modeling in Air Lift Reactor	Classification of SSF Bioreactor	Trickle flow reactor
	SLO-2	Instrumentations to control a bioreactor	Mass and Energy Balance	Mode of Operation	Design and Construction
S-5	SLO-1	Sensors	Hydrodynamics in ALR	Un aerated and Unmixed Bioreactor	Theory of Trickle flow reactor
	SLO-2	Probes in bioreactor	Three phase flow in ALR	Design and Construction	Physical model
S-6	SLO-1	Common operations of bioreactor	Mixing	Forcefully – Aerated bioreactors without mixing	Mathematical model of Trickle flow reactor
	SLO-2	Types of Reactor	Oxygen transfer in ALR	Design and Construction	Solving Problems
S-7	SLO-1	Performance of Batch Reactor	Design of fluidized bed bioreactor	Rotating –Drum and Stirred –Drum bioreactors	Performance analysis of Trickle flow reactor
	SLO-2	Solving Problems	Operation of fluidized bed bioreactor	Continuously mixed bioreactors	High substrate concentration and low substrate concentration

S-8	SLO-1	Performance of Continuous reactor	Design and operation of inverse fluidized bed bioreactor	Mixed ,Forcefully – Aerated Bioreactors	Calculation of parameter estimation	Control Strategy for Bioreactor
	SLO-2	Performance of Continuous reactor with recycle	Models in Fluidized bed bioreactor	Design and Construction	Problems	Solving Problems
S-9	SLO-1	Fed Batch Reactor	Hydrodynamics of fluidized bed reactor	Intermittently Mixed bioreactors	Design method	CFD analysis in Bioreactor design.
	SLO-2	Solving Problems	Solving Problems	Design and Construction	Calculation procedure and Evaluation of parameter estimation	Solving Problems

Learning Resources	<ol style="list-style-type: none"> 1. Scragg. H., "Bioreactors in Biotechnology", Ellis Horwood series, 1991. 2. B.Atkinson., "Biochemical Reactors", Pion limited, London, 1974 3. Panda. T., "Bioreactors: Analysis and Design", McGraw Hill Education (India) Private Limited, 2011 4. Riet. K. V., Tramper. J., "Basic Bioreactor Design", 2nd ed., Marcel Dekker, Inc., New York, 1991.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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Dr. Karthik Periyasamy, Aurobindo Pharma Limited, Hyderabad, karthikmpk@gmail.com	Prof. R. B. Narayanan, SVCE, Chennai, rbn@svce.ac.in	Dr. Y.Ravichandran SRM IST

Course Code	18BTE407T	Course Name	BIOPROCESS MODELLING AND SIMULATION	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Biotechnology	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Illustrate the knowledge on various mathematical models of biological systems.	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2 :	Explore the modelling of bioprocess with a view to engineering application.	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3		
CLR-3 :	Demonstrate the advanced software knowledge for the automation of bioprocess systems.				H	H	H	H		H		H		H	H	H	H	H	H	H	H
CLR-4 :	Demonstrate the Use of Superpro software to design a bioprocess system for the production of bioproducts.				H	H	H	H		H		H		H	H	H	H	H	H	H	H
CLR-5 :	Analyze the solutions of various mathematical problems using MATLAB.				H	H	H	H	H		M		H		H	H	H	H	H	H	H
CLR-6 :	Familiarize the students with the various bioprocess models and softwares.				H	H	H	H	H		M		H		H	H	H	H	H	H	H
					H	H	H	H	H		M		H		H	H	H	H	H	H	H
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																				
CLO-1 :	Describe the fundamental laws and concepts about the mathematical modeling	2	80	70																	
CLO-2 :	Explain about the various mathematical models in biochemical engineering systems	2	85	75																	
CLO-3 :	Discuss the application of SuperPro Design for analysis of material and energy balance of biochemical reaction	3	75	80																	
CLO-4 :	Explain the basic concepts of MATLAB, data analysis and interpretation of data	3	85	80																	
CLO-5 :	Explain the basic concepts of SIMULINK, data analysis and interpretation of data	3	85	80																	
CLO-6 :	Accomplish knowledge about the fundamentals of modeling and simulations of bioprocess	2	80	75																	

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Models - Introduction	Basic Mathematical Models	Introduction to Superpro	MATLAB - Introduction	Modeling of Batch Culture Using MATLAB – basics
	SLO-2 Basic modeling principles	Setting up a model	Developing a Process Model	MATLAB - basics	Batch Culture – programme
S-2	SLO-1 Introduction of mathematical modeling	Continuous flow tanks - enclosed vessel	Process design	MATLAB - Data analysis	Batch Culture – expected outputs
	SLO-2 Uses of mathematical modeling	Continuous flow tanks - mixing vessel	Process Modeling and Simulation	Curve fitting - Introduction	Modeling of Fed-batch Culture Using MATLAB – basics
S-3	SLO-1 Classification of modeling techniques	Steam jacketed vessel	Process flow diagrams	Curve fitting using MATLAB - Theory	Fed-batch Culture – programme
	SLO-2 Grouping of models into opposite pairs	Steam jacketed vessel - open and closed	Process flow diagram to produce human insulin	Curve fitting using MATLAB – examples	Fed-batch Culture – expected outputs
S-4	SLO-1 Classification based on Mathematical complexity	Batch distillation – basics	The β -Galactosidase Process	Numerical Integration	Modeling of Continuous Culture Using MATLAB – basics
	SLO-2 Classification of models according to scale	Batch distillation model	The Industrial Wastewater Treatment Process	Numerical Integration Techniques	Continuous Culture – programme
S-5	SLO-1 Fundamental laws – Expression and examples	Bioprocess modeling	Procedures & Operations	Trapezoidal Rule	Continuous Culture – expected outputs
	SLO-2 Energy equations	Modelling approaches for biomanufacturing operations	Resources	Trapezoidal Rule - Problems	Process Simulation
S-6	SLO-1 Energy equations - expression and examples	Types of bioprocess model	Scheduling	Simpson's Rule	Simulink - Introduction
	SLO-2 Continuity equations	Mathematical models of microbial process	Process Properties & Simulation	Simpson's Rule - Problems	Simulink - basics
S-7	SLO-1 Continuity equations – expression and examples	Applying mechanistic models in bioprocess development	Economics	Euler's Method	Simulation of gravity flow tank
	SLO-2 Transport equations	Model formulation for aerobic cultivation of budding yeast	Reports	Euler's Method - Problems	Simulation of three isothermal CSTR

S-8	SLO-1	Transport equations expression and examples	Parameter identifiable analysis	Material-Balance Calculations	Runge-Kutta 4 th Order Method	Simulation by Simulink in Batch Culture
	SLO-2	Equations of motion	Uncertainty analysis	Material-Balance Problems	Runge-Kutta 4 th Order Method - Problems	Simulation by Simulink in fed-batch Culture
S-9	SLO-1	Chemical kinetics	Metabolic flux modelling (MFM)	Energy-Balance Calculations	Programming with MATLAB	Simulation by Simulink in continuous Culture
	SLO-2	Examples	MFM as a tool to analyze the behavior of genetically modified yeast strain	Energy-Balance Problems	Program design and development	Expected outputs of Batch, Continuous and Fed-batch fermentation process

Learning Resources	1. Mandenius C., Titchener-Hooker N. J., "Measurement, Monitoring, Modelling and Control of Bioprocesses", Springer Publishers, 2013.	6. Biquette. W.B., "Process Dynamics- Modeling analysis with simulation", Prentice Hall; 1 edition, 1998.
	2. Burstein L., "Matlab® in Bioscience and Biotechnology, Woodhead Publishing, 2011.	7. Beers. K.J., "Numerical Methods for Chemical Engineering Applications in MATLAB®", Massachusetts Institute of Technology, Cambridge University press. 2007.
	3. Luben. W.L., "Process Modelling Simulation and Control for Chemical Engineers", McGrawHill, 1990.	www.intelligen.com/ SuperPro Designer user guide.
	5. Franks. R.G.E., "Mathematical Modeling in Chemical Engineering", John Wiley and Sons, Inc., 2004.	

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30%	-	30%	-	30%	-	30%	-
Level 2	Understand	40 %	-	40%	-	40%	-	40%	-	40%	-
Level 3	Apply	20 %	-	30%	-	30%	-	30%	-	30%	-
	Analyze										
	Evaluate										
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Dr. P. BalaKumaran, Proklean Technologies (P) Limited, Chennai, genbalu86@gmail.com	Prof.. K Subramaniam, IITM, Chennai, subbu@iitm.ac.in	Dr. V. Vinoth Kumar, SRMIST
Dr. Karthik Periyasamy, Aurobindo Pharma Limited, Hyderabad, karthikmpk@gmail.com	Prof. R. B. Narayanan, SVCE, Chennai, rbn@svce.ac.in	Dr. M. Venkatesh Prabhu, SRMIST

Course Code	18BTE408T	Course Name	BIOPROCESS PLANT DESIGN	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Biotechnology	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1: Equip the students with designing aspects for industrial scale fermenter		1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2: Infer various scale up and scale down parameters for good optimization process		Level of Thinking (Bloom)	Engineering Knowledge
CLR-3: Understand the factors involved in heat and mass transfer studies for controlling process parameters		Expected Proficiency (%)	Problem Analysis
CLR-4: Envisage the guidelines for plant operation and its risk assessment		Expected Attainment (%)	Design & Development
CLR-5: Decipher process economics involved in industrial operations			Analysis, Design, Research
CLR-6: Instigate the production strategies in protein and other metabolites with commercial importance			Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1: Manage Inoculum development and nutritional balance for product conversion.		2 80 70	H H H H H H H H H H H H H H H
CLO-2: learn about the mass and energy balance of bioprocess		2 85 75	H H H H H H H H H H H H H H H
CLO-3: develop and optimize the process parameters for the industries		3 75 80	H H H M H H H H H H H H H H H
CLO-4: apply design factors for scale up in the industry		3 85 80	H H H H H H M H H H H H H H H
CLO-5: evaluate the process plant design for regulatory compliance		3 85 80	H H H H H H M H H H H H H H H
CLO-6: design a plant layout for processing of biological materials		2 80 75	H H H H H M H H H H H H H H H

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Design-Project Procedure	Heat and Mass Transfer studies	Selection of bioprocess equipment - upstream	Plant location and site selection	Cash Flow for Industrial Operations
	SLO-2 Types of Designs	Effect of scale on oxygenation	Selection of bioprocess equipment - downstream	Plant Layout	Cumulative Cash Position
S-2	SLO-1 Feasibility Survey	mixing and sterilization	Specifications of bioprocess equipment	Plant operation and control	Factors affecting investment and production costs
	SLO-2 Flow Diagrams	Inoculum development and nutrient availability	Mechanical design of reactors	Techniques Used in Site and Plant Layout	Capital Investments
S-3	SLO-1 Process Flow sheeting	Bioreactor scale-up	Heat transfer equipment	Utility supply aspects	Estimation of Capital Investment
	SLO-2 Equipment Design	Scale-up - constant power consumption per volume	Heat exchangers and Evaporators	Environmental Considerations	Cost Indexes
S-4	SLO-1 Equipment Selection	Scale-up - mixing time	Mass transfer equipment	Equipment cleaning aspects	Cost Factors in Capital Investment
	SLO-2 Comparison of Different Design-Projects	Scale-up - impeller tip speed (shear)	Finite-Stage Contactors	Culture cell banks	Estimating Equipment Costs by Scaling
S-5	SLO-1 Material balance	Scale-up - mass transfer coefficients	Continuous contactors - Packed towers	cGMP guidelines	Purchased-Equipment Installation
	SLO-2 Material balance calculations	Problems	Pressure Drop	Global Regulatory Environment	Methods for estimating capital investment
S-6	SLO-1 Examples	Scale up of downstream processes	Factors Influencing Plate and Column Efficiencies	Key Pharmaceutical Regulations Related to Design and Engineering	Estimation of Total Product Cost
	SLO-2 Problems	Adsorption	Piping and instrumentation	Implications for Performance and Compliance	Fixed Charges
S-7	SLO-1 Energy balance	Adsorption (LUB method)	HAZOPS Study	Risk Assessments	Case study – Commodity chemicals
	SLO-2 Energy balance calculations	Chromatography	Safety checklist for identifying process hazards	Validation	Cost analysis of enzyme production
S-8	SLO-1 Examples	Chromatography (constant resolution etc.)	Materials of construction for bioprocess plants	Project Plans	Bioethanol from Corn Stover

	SLO-2	Problems	Filtration (constant resistance etc.) -	Classification of stainless steels by alloy content and microstructure	Detailed Design Phase	Furfural and lignin from Corn Stover
S-9	SLO-1	Scale-Up in Design	Centrifugation (equivalent times etc.)	Low- and high-temperature Materials	Process Safety Management	Insulin production
	SLO-2	Factors in equipment scale-up and design	Scale-down related aspects	Economics in Selection of Materials	Safety Indices	Monoclonal Antibody Production

Learning Resources	<ol style="list-style-type: none"> 1. Jacobs T., Signore A. A., "Good Design Practices for GMP Pharmaceutical Facilities", 2nd edition, Taylor and Francis, 2017. 2. Peters M. S., Timmerhaus. K. D., "Plant Design and Economics for Chemical Engineers", 5th Edition, McGrawHill Book Co., 2003 3. Perry R. H., Green D. W., "Perry's Chemical Engineers' Handbook", 9th Edition, McGraw Hill Book Co., 2018. 4. Towler G., Sinnott R., "Chemical Engineering Design - Principles, Practice and Economics of Plant and Process Design, Elsevier, 2007.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
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Dr. Karthik Periyasamy, Aurobindo Pharma Limited, Hyderabad, karthikmpk@gmail.com	Prof. R. B. Narayanan, SVCE, Chennai, rbn@svce.ac.in	Dr. M. Venkatesh Prabhu, SRMIST

Course Code	18BTE317T	Course Name	ENVIRONMENTAL BIOTECHNOLOGY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Biotechnology	Data Book / Codes/Standards			

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)															
CLR-1 :	Create awareness on environmental pollution and the need for advanced technologies for their mitigation				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLR-2 :	Provide overview of biological approach for the conversion of various environmental pollutants				Thinking (Bloom)	Efficiency (%)	Attainment (%)	Knowledge	Analysis	Development	Design, Research	Usage	Culture	Sustainability & Sustainability	Team Work	Communication	Finance & Finance	Planning					
CLR-3 :	Understand the importance of biotechnology in the environmental management																						
CLR-4 :	Understand various biotechnological contributions to the industries to reduce the environmental pollution																						
CLR-5 :	Educate the relevant information about recovery of bioproducts from industrial wastes																						
CLR-6 :	Identify the novel technology for the environmental pollution abatement																						

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Understand the biotechnological solutions for the treatment of industrial liquid and solid wastes	1	80	80	H	H	H	H	M	M	L	H	H	H	H	H	H	H	H
CLO-2 :	Acquire knowledge in aerobic and anaerobic biological treatment technologies	2	85	75	H	H	H	H	H	H	M	H	H	H	H	H	H	H	H
CLO-3 :	Understand the importance of biotechnology in the environmental pollution management	2	75	80	M	H	M	H	M	M	M	M	H	H	H	H	H	H	H
CLO-4 :	Understand the bioconversion pathways for the degradation of various xenobiotic compounds	2	85	80	H	H	H	H	H	M	H	L	H	H	H	H	H	H	H
CLO-5 :	Gain knowledge on the recovery of high value-added bioproducts from industrial wastes	3	85	75	H	H	H	H	M	M	H	H	H	L	H	H	H	H	H
CLO-6 :	Choose from an array of options to turn waste into economic goods	2	80	80	H	H	H	H	L	M	M	M	H	H	H	H	H	H	H

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Introduction to Environmental pollution-water, air, soil	Recent trends in Biological wastewater treatment	Xenobiotics and recalcitrants	Recent trends in Biodegradation of industrial wastes	Waste to Wealth
	SLO-2 Perspectives of liquid and solid wastes	Aerobic biological treatment technologies	Environmental effects of Xenobiotics and recalcitrants	Contributions of Biotechnology for the environmental managements and industrial applications	Value-added bioproducts from Industrial wastes
S-2	SLO-1 Overview of stages of wastewater treatment	Anaerobic digestion process	Biodegradation of xenobiotics	Microbial enzymes for environmental applications	Slaughterhouse industry wastes
	SLO-2 primary, secondary and tertiary treatment	Stages of anaerobic digestion process	Mechanisms of Biodegradation of xenobiotics -Reductive/Oxidative/Hydrolytic	Advantages of immobile cells or enzymes over free cells and enzymes	Recovery of enzymes from slaughterhouse industry waste for industrial applications
S-3	SLO-1 Physicochemical technologies for the liquid waste disposal	Anaerobic Biological treatment technologies	Aliphatic and Hydrocarbons	Role of Biocatalysts in pollutant removal	Recovery of secondary metabolites from slaughterhouse industry waste for industrial applications
	SLO-2 Coagulation, Flocculation, Sedimentation	Advantages of anaerobic digestion processes over aerobic digestion processes	Biotransformation of Aliphatic and Hydrocarbons	Application of Immobilized cells in pollutants removal	Leather industry wastes
S-4	SLO-1 Chemical precipitation	Microbiology of anaerobic digester	Aromatic Hydrocarbons	Role of Biocatalysts in pollutant removal – Immobilized Enzymes	Types of solid wastes generated from leather industry
	SLO-2 Pros and Cons of chemical precipitation	Factors affecting anaerobic digestion process	Biotransformation of Aromatic Hydrocarbons	Application of Immobilized enzymes in pollutants removal	Recovery of enzymes from leather industry wastes for industrial applications
S-5	SLO-1 Filtration processes-mechanisms	Attached growth system-Biofilm	Polyaromatic hydrocarbons	Classification of dyes and their effects on the environment	Recovery of secondary metabolites from leather industry wastes for industrial applications
	SLO-2 Types of filtration processes	Biofilm development process	Biotransformation of Polyaromatic hydrocarbons	Microbial dye decolourization	Plastic wastes
S-7	SLO-1 Adsorption processes-Activated carbon technology-applications	Biofilm Technologies in environmental pollution management	Polycyclic aromatic Hydrocarbons	Enzyme based dye decolourization	Environmental impacts

	SLO-2	Ion Exchange processes-applications	Advantages of attached growth system over suspended system	Biotransformation of Polycyclic aromatic Hydrocarbons	Biodegradation of textile dyes	Recycling of plastic wastes
S-8	SLO-1	Solid waste disposal-Effects	Nutrients removal-Eutrophication	Halogenated hydrocarbons	Laccases and their role in Bioremediation of Industrial wastes	Bioplastics
	SLO-2	Secured Landfill, Bacterial and Vermi composting, incineration/pyrolysis	Recent advances in Nitrogen removal	Biotransformation of halogenated hydrocarbons	Heavy metal toxicity to the environment	Renewable resources for energy generation
S-9	SLO-1	Advanced oxidation processes for recalcitrants treatment	Biological Phosphorous Removal	Oil pollution and its effect on the environment	Microbial heavy metal removal-mechanisms	Alternate technologies for Energy recovery
	SLO-2	Electrolysis-Cu removal	EBPR process-mechanisms	Microbial treatment of oil pollution	Role of biosurfactants, Extracellular polysaccharides and siderophores in the heavy metal removal	Biomass residue as a fertilizer

Learning Resources	1. Bruce E.Rittmann and Perry L.McCarty, <i>Environmental Biotechnology: Principles and Applications</i> , McGraw Hill, 2001.	5. Ram Chandra, <i>Advances in biodegradation and bioremediation of industrial wastes</i> , CRC Press, Taylor&Francis, 2015.
	2. Bimal C Bhattacharyya, <i>Environmental Biotechnology</i> , Oxford University press, 2007.	6. Hanes Joachim Joardening, <i>Environmental Biotechnology, Concepts and Applications</i> , 2017.
	3. Milton Wainwright, <i>An Introduction to Environmental Biotechnology</i> , Springer, 1999.	7. Chatterjee A.K, <i>Introduction to Environmental Biotechnology</i> , Prentice Hall of India, 2011.
	4. P.Rajendran, P.Gunasekaran, <i>Microbial Bioremediation</i> , MJP Publishers, India, 2006.	

SLO – Session Learning Outcome

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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2. Dr. D. Gunaseelan, BIOCON Ltd., guna.sachin@gmail.com	2. Dr. Anbumani Sadasivam, CSIR-Indian Institute of Toxicology Research, anbumani@iitr.res.in	2 Dr. B.Samuel Jacob SRM Inst. of Science & Technology, Samueljacob.b@ktr.srmuniv.ac.in

Course Code	18BTE318T	Course Name	INDUSTRIAL WASTE MANAGEMENT	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Biotechnology		Data Book / Codes/Standards	Nil	

Course Learning Rationale (CLR):		The purpose of learning this course is to:				Learning			Program Learning Outcomes (PLO)																
CLR-1:		Identify the relevant information about industrial solid waste reduction and hazardous waste management				Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:		Identify the applications of energy conversion technology																							
CLR-3:		Demonstrate the state of the art in technology, organizational and legislative developments and practices																							
CLR-4:		Create insights to the waste characterization aspects																							
CLR-5:		Analyze the mass balance and carbon foot print for a given industrial process																							
CLR-6:		Utilize the concepts environmental regulation and inculcate in newly developed treatment technologies																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:				Expected Proficiency (%)	Expected Attainment (%)	Expected Proficiency (%)	Expected Attainment (%)	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3		
CLO-1:		Formulate an insight into the pollution from major industries including the sources and characteristics of pollutants																							
CLO-2:		Analyze the mode of treatment based on waste characteristics																							
CLO-3:		Design of wastewater treatment plants to attain standard limits																							
CLO-4:		Assess the impact of industrial wastes on the environmental compartments (land, water and air)																							
CLO-5:		Analyze and choose appropriate strategy to convert waste to economic goods																							
CLO-6:		Develop knowledge on environmental regulations and legal aspects																							

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Introduction to industrial wastes and their impacts-Industrial wastes - Sources	Standards for waste disposal & methods of waste reduction –	Treatment and disposal of industrial effluents	Biodegradation/ Recycling Of Industrial Wastes
	SLO-2	Classification of industrial wastes	Standards for disposal of treated effluents, solid wastes and gaseous emissions from different industries	Stages of effluent treatment- primary, secondary and tertiary	Immobilized cell and enzyme technologies for the effluent treatment
S-2	SLO-1	Industrial waste generation scenario in India	Characteristics of industrial wastewater- COD, BOD and TOC	Physicochemical treatment-Coagulation, flocculation and their mechanisms	Energy recovery from hybrid treatment technology
	SLO-2	Industrial waste generation scenario in Global context	Solids analysis – TDS, TSS and VSS	Precipitation –heavy metal removal-Merits and Demerits	Case study f sustainable technologies from European Union
S-3	SLO-1	Environmental impacts	Characteristics of industrial wastewater-, TKN, Ammonia, Chloride, Sulfide and Sulfate	Secondary Biological treatment: Aerobic-activated sludge process,	Algal based technologies for nutrient and pollutant removal
	SLO-2	Threat to biodiversity	Metal analysis using AAS and ICP-MS	Sequential batch process. fluidized bed reactor	Bioreactor designs for algal based wastewater
S-4	SLO-1	Toxicity of industrial effluents	Removal of heavy metals by physico-chemical process	Secondary Biological treatment: Anaerobic-UASB, MBR –Merits and Demerits	Bioelectricity production through MFC with leachate and wastewater
	SLO-2	Case studies of industrial toxicity (Bhopal gas leak, Chernobyl etc.)	Biological process for heavy metal removal	High rate bioreactors	Water splitting technologies
S-5	SLO-1	Functions of Regulatory bodies-State and Central Pollution Control Board	Individual and Common Effluent Treatment Plants	Reprocessing of bio-sludge for value addition	Bioplastic synthesis from the compounds derived from wastewater
	SLO-2	Common effluent treatment plants for textile and tannery industry wastewater treatment	Case study of Indian industries waste treatment through common effluent treatment process	Energy recovery from sludge	Polymer synthesis from the compounds derived from wastewater

S-6	SLO-1	Selection of candidate technologies for waste treatment based on characteristics	Volume and strength reduction	Removal of refractory organics-strategies	Plastics degrading bacteria	Environmental auditing
	SLO-2	Rationale for biological treatment over conventional methods	Material and process modifications	Advanced oxidation processes	Phytoremediation for removal of heavy metals	ISO 14001:2015 And its implication in environmental assessment
S-7	SLO-1	The solid waste landfill	4R principles– Recycle, reuse and by-product recovery	Photo-oxidation process	Bioremediation of hydrocarbon contaminated wastewater of refinery plants through super bugs (GM <i>Pseudomonas putida</i>)	Carbon foot print for an industry
	SLO-2	Leachate management	Waste treatment flow sheets for selected industries such as Textiles, Tanneries, Pharmaceuticals, Electroplating industries,	Volatile organic compound (VOC) removal by Evaporation	Ocean cleaning for oil spill using super bugs	Carbon credit
S-8	SLO-1	The process of composting Industrial wastes	Dairy, Sugar, Paper, distilleries, Steel plants, Refineries, fertilizer, thermal power plants	Air and steam stripping	Biosurfactants for bioremediation and biodegradation of various pollutants discharged from industrial waste	Occupational Safety and Health Assessment
	SLO-2	Vermi-composting and its advantages	Hazardous waste management– Physico chemical treatment	Adsorption processes (Activated carbon)	Mechanism of biosurfactant based technologies for solids reduction in wastewater	Waste Hazard identification and problem formulation
S-9	SLO-1	Hierarchy of Potential Implementation waste management Strategies	Solidification and incineration – Zero discharge	Colour removal from wastewater from textile industries	Application of nanotechnology for waste degradation	Life cycle assessment of industrial wastes
	SLO-2	Waste management pyramid	Secure land fills	Role of microorganisms and enzymes for dye removal	Nano-enzymes for pollutant removal	Implications of biological agents on environment for pollutant removal

Learning Resources	<ol style="list-style-type: none"> 1. Eckenfelder, W.W., (1999) "Industrial Water Pollution Control ", Mc-Graw Hill. 2. Clair N. Sawyer, Perry L. McCarty, "Chemistry for Environmental Engineering and Science" McGraw-Hill, 1978 3. Metcalf & Eddy Inc. Wastewater Engineering: Treatment and reuse 2016
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. S. Sam Gunasekar, Orchid Chemicals and Pharmaceuticals Ltd., sam@orchidpharma.com	1. Dr. A. Gnanamani, CSIR-Central Leather Research Institute, agmani_2000@yahoo.com	Dr. K.Ramani SRM Inst. of Science & Technology, ramani.k@ktr.srmuniv.ac.in
2. Dr. D. Gunaseelan, BIOCON Ltd., guna.sachin@gmail.com	2. Dr. Anbumani Sadasivam, CSIR-Indian Institute of Toxicology Research, anbumani@iitr.res.in	Dr. B. Samuel Jacob SRM Inst. of Science & Technology, ssamuelfjacob.b@ktr.srmuniv.ac.in

Course Code	18BTE319T	Course Name	BIOENERGY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department		Biotechnology	Data Book / Codes/Standards		Nil

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Identify the potent biomass resources for energy production	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Identify the applications of energy conversion technology	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Demonstrate the significance of environmental benefits of bioenergy																		
CLR-4 :	Create insights to the concepts of sustainable and green technologies																		
CLR-5 :	Analyze the important wastes to energy conversion																		
CLR-6 :	Utilize the concepts scale up strategies for biomass based energy production																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	1	80	70	H	H	M	M	M	H	H	H	M	H	M	H	M	H	H
CLO-1 :	Formulate the appropriate biofuel production based on available feedstocks	2	85	75	H	M	M	M	M	H	H	H	M	L	H	H	M	H	H
CLO-2 :	Analyze cell wall components of biomass	2	75	70	H	H	M	M	M	H	H	H	M	H	H	H	M	H	H
CLO-3 :	Apply thermo-chemical conversion process for biomass conversion to produce biofuel	2	85	80	H	H	M	M	M	H	H	H	M	H	H	H	M	H	H
CLO-4 :	Apply enzymatic process to convert biomass to fuel and value added chemicals	2	85	75	H	H	M	M	M	H	H	H	M	H	M	H	H	H	H
CLO-5 :	Employ synthetic routes for ease and fast biofuel production	1	80	70	H	M	M	M	M	H	H	H	M	H	M	H	H	M	H
CLO-6 :	Describe the National policy towards biofuel production and Energy security																		

	Introduction to Sources of energy	First Generation Bioenergy	Second & Third Generation Bioenergy	Fourth generation bioenergy and next generation bio-molecules	Policies and future R&D of biofuels & Bioenergy
Duration (hour)	9	9	9	9	9
S-1	SLO-1 Non-renewable Resources (Fossil fuel)	Sugar and Starch based bioenergy	2 nd generation (Non-edible lignocellulosics)	CO ₂ biosequestration and biofuel production strategies	Policies and Future R&D of Biofuels & Bioenergy
	SLO-2 Alternate and renewable resources (Solar, wind and biomass based)	Corn, sugarcane, sugar beets, soybeans, canola oil, fryer grease, and coconut oil	Wood bioenergy	Use of plants and microalgae for CO ₂ sequestration	National biofuel policy framework
S-2	SLO-1 Bioenergy – Classification (Liquid and gaseous biofuel)	Fuel from food crops	Pretreatment strategies for biofuel production	Synthetic (bio)fuels	Evaluation of current and future R&D needs
	SLO-2 An overview of bioenergy in Global and national context	Consequences for food crops as fuel source	Green chemicals for biomass pretreatment	Sustainability aspects of synthetic biofuels	Focus area such as Mission Innovations India and Horizon 2020
S-3	SLO-1 Rationale of biomass power sustainable environment	Role of cell wall components (Lignin, cellulose and hemicelluloses) in different plants for ethanol production	Rationale for biological pretreatment over physical and chemical modes.	Pyrolysis bio-oil/bio-char	Legal framework to support sustainable development and increased use of biofuels
	SLO-2 Treatment technologies for biomass to useful energy	Bottlenecks in biomass conversion to fuels	Bioethanol plant design and its components	Hydrogenated biodiesels	Need for International cooperation and intervention in biofuel sector in India
S-3	SLO-1 Circular & Biobased Economy	Recalcitrant lignin and its biochemistry	Bio refinery demonstration projects of Bioethanol	Pyrolysis diesel	Government policies and programs with regard to biofuels
	SLO-2 Environment impact over biofuel usage	Importance of cellulose and hemicelluloses	Sustainable Solid and liquid waste management	Comparative analysis of different grades of diesel based on ASTM	R and D focus area for biofuel in India
S-4	SLO-1 Feedstocks – Food Vs Feed Vs Fuel	Conversions Process: Physico-chemical	Biomethanation process	Dimethyl ether (DME)	Investment opportunities on biofuels worldwide
	SLO-2 Characteristics for feedstock for bioenergy	Constraints of conventional processing technologies	Microbiology of anaerobic digestion	Bio-synthetic natural gas (SNG)	Industrial opportunities of biofuels in India – at a glance

S-5	SLO-1	Waste resources – Industrial (solid and liquid) and MSW	Biological route and Enzymatic Conversion	Biological Processes for Hydrogen Production	Comparative analysis of CNG/SNG/bio-gas based on ASTM	Economic, Social and Ecological Impacts of Bioenergy
	SLO-2	Agro waste resources – Crop residues and by-products	Enzymology for conversion of biomass to biofuels – Lignolytic enzymes (MnP, LiP and laccase)	Dark fermentation and algal based technologies	Bio-butanol production	Comparative analysis of National and Global Levels
S-6	SLO-1	Energy crops – Terrestrial	Mechanism of depolymerization of lignin by enzymes and whole cells	3 rd generation biofuel	ABE biosynthesis (Acetone Butanol and Ethanol)	Current and Emerging Challenges to Bioenergy Development
	SLO-2	Energy crops – Aquatic	Hexose sugar conversion to ethanol	Need for 3 rd generation biofuels	Bottlenecks in ABE fermentation; Types of feedstocks preferred	Impact of solar and wind energy over biomass energy
S-7	SLO 1	Potential Benefits of Replacing Fossil Fuels with Biofuel, Biomass and Biogas	Pentose sugar conversion to ethanol	Genetically modified organisms for improved fuel production	Metabolic pathway engineering for ABE biosynthesis	Community Participation in Renewable Energy Development
	SLO 2	Cradle to grave approach of waste raw materials for bioenergy development	By-products of ethanol production and its	Case study of insect ruminant biology for biofuel production	Case study of GM microbes on ABE fermentation	Techno-economic feasibility for biofuel production
S-8	SLO 1	Political Drivers for Biofuel Development	Inhibitory products of bioethanol production	GM plants for enhanced biomass for ethanol production	Bio-alkanes and alkenes from waste biomass	Combined industrial waste treatment for energy recovery
	SLO 2	Consequences of Burning Fossil Fuel	Plausible contaminants from bioethanol production and its re-utilization	GM based oil crops for biodiesel production	Economic advantage of chemicals production from biomass	Zero-discharge concept for wastewater from industries and energy recovery process
S-9	SLO 1	Mitigation of Global Warming	Biodiesel from vegetable oils	Hybrid energy system through biomass	New energy research Projects in Global context	Urban and rural integration system for sustainable waste utilization
	SLO 2	Carbon dioxide sequestration Approaches	Transesterification process	Algal based technologies for biofuel and value added chemical preparation	New energy research Projects in Indian context	Life-cycle Analysis of Biofuels

Learning Resources	1. David M. Mousdale, "Biofuels: Biotechnology, Chemistry, and Sustainable Development", CRC Press, 2008.	3. A.H.Scragg, "Biofuels, Production, Application and Development", CAB Internaional, 2009
	2. Roland A. Jansen, "Second Generation Biofuels and Biomass", Wiley – VCH Verlag GmbH Co., 2013.	4. Robert C. Brown and Tristan R.Brown, "Biorenewable Resources: Engineering New Products from Agriculture," Wiley-Blackwell Publishing, 2 nd Edition, 2014.

Learning Assessment											
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		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

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Dr. S. Sam Gunasekar Orchid Pharma Ltd., Chennai	Dr. Subhabrata Ray IIT Kharagpur, sray@che.iitkgp.ernet.in	Dr. K.Ramani Department of Biotechnology SRM Inst. of Science & Technology, ramani.k@ktr.srmuniv.ac.in

Course Code	18BTE320T	Course Name	ENVIRONMENTAL MICROBIOLOGY. & METAGENOMICS	Course Category	E	Professional Elective Course	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Biotechnology	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1:	Provide the awareness on the microbial applications in the environmental pollution abatement	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2:	Give an overview of indigenous microbes on environmental bioremediation		
CLR-3:	Educate the molecular insights on conservation of biodiversity		
CLR-4:	Understand the environmental metagenomics for novel species identification		
CLR-5:	Apply the metaproteomic concepts for environmental samples		
CLR-6:	Educate the soil microbiome and biofilm organisms in the environment		

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3	
CLO-1:	Apply the concepts of microbial diversity and its taxonomic make up.	1	80	80	H	H	H	H	M	M	L	H	H	H	H	H	H	H	H	H
CLO-2:	Understand the extremophiles and its uses in Biotechnology.	2	85	75	H	H	H	H	M	H	M	H	H	H	H	H	H	H	H	H
CLO-3:	Apply Metagenomics data to describe taxonomic make-up and ecological processes of microbial communities from a range of environments	2	75	80	M	H	M	H	M	M	H	M	H	H	H	H	H	H	H	H
CLO-4:	Assemble and annotate genomes by identifying genes	2	85	80	H	H	H	H	H	H	H	L	H	H	H	H	H	H	H	H
CLO-5:	Apply next generation sequencing technology.	3	85	75	H	H	H	H	H	M	H	H	H	L	H	H	H	H	H	H
CLO-6:	Understand the soil microbiome and biofilm organisms in the environmental cleanup	2	80	80	H	H	H	H	M	M	M	M	H	H	H	H	H	H	H	H

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Microbial diversity	Extremophiles	Environmental Metagenomics	Environmental meta proteomics	Soil microbiome and biofilms
	SLO-2 Microbial existence in the environment	Extremophiles-various types	Importance of metagenomics in microbial ecology	Importance of metaproteomics in microbial ecology	The soil microbiome — from metagenomics to metaphenomics
S-2	SLO-1 Biodiversity and its relationship with Environment	Extremophiles in the environmental management	Metagenomics-types, steps	Gel-based proteomics: 2-DE	Influence of soil structure and connectivity on the soil metaphenome
	SLO-2 Classification of microorganisms	Role of Acidophilic microorganisms and their biomolecules in Environmental remediation	Molecular Diversity and Metagenomics	Gel-based proteomics: DIGE	Influence of physiological status on the soil metaphenome
S-3	SLO-1 Role of microorganisms in the sustainability of biosphere	Role of alkalophilic microorganisms and their biomolecules in Environmental remediation	Concept of e-DNA (environmental DNA)	Gel-based proteomics: BN-PAGE	Influence of microbial community interactions on the soil metaphenome
	SLO-2 Culturability/unculturability and microbial ecology principles	Role of psychrophilic microorganisms in Environmental remediation	Diversity of Microbes in different environments	Merits and demerits of gel-based proteomic techniques	Role of soil microbiome for improving soil health under changing climate
S-4	SLO-1 Classification of microorganisms-Bacteria, Yeasts, Moulds, Viruses, Protozoans	Role of mesophilic microorganisms and in Environmental remediation	Conventional methods to study diversity; Cultured and Uncultured Methods	Gel-free proteomics: Isotope-Coded Affinity Tag (ICAT)	Biofilm mediated decontamination of pollutants from the environment
	SLO-2 Lichens and their role in the biosphere.	Role of thermophilic microorganisms in Environmental remediation	16S-rDNA sequencing of microbial communities	Isobaric Tagging for Relative and Absolute Quantitation (iTRAQ)	Role of Biofilms in Bioremediation
S-5	SLO-1 Mycorrhiza-types	Role of barophilic microorganisms in Environmental remediation	Partial community analysis methods - Genetic fingerprinting techniques - T-RFLP	Multidimensional Protein Identification Technology -MudPIT)	Strategies for Use of Biofilms in Remediation
	SLO-2 Mycorrhiza-Environmental applications	Role of osmophilic microorganisms in Environmental remediation	Partial community analysis methods - Genetic fingerprinting techniques - DGGE	Merits and demerits of gel-free proteomic techniques	Biofilm Survival Strategies in Polluted Environments
S-6	SLO-1 Photosynthetic organisms and their environmental applications	Halophiles- types	Partial community analysis methods - Genetic fingerprinting techniques RISA	Application of gel-free techniques in biological systems	Molecular Methods for the Assessment of Microbial Biofilms in Bioremediation

	SLO-2	Anoxygenic photosynthetic microbes	Halophiles- their biomolecules in Environmental remediation	Partial community analysis methods - Genetic fingerprinting techniques LH-PCR microarrays	Protein microarrays	Detoxification of Hexavalent Chromium from Industrial Wastewater using a Bacterial Biofilm System
S-7	SLO-1	General characteristics of purple and green sulphur bacteria.	Molecular aspects of extremophiles- Genes, Protein s and Enzymes.	Partial community analysis methods - Genetic fingerprinting techniques RAPD	Isotope-Coded Protein Label (ICPL)	Biofilm-mediated Degradation of PAHs and Pesticides
	SLO-2	Oxygenic photosynthetic microbes	Perspectives of Archaeobacteria in Environment- distinguishing features	Partial community analysis methods - Genetic fingerprinting techniques DNA microarrays	Combined FRActional Diagonal Chromatography (COFRADIC)	Metagenome Analyses of Multispecies Microbial Biofilms
S-8	SLO-1	General characteristics of Cyanobacteria and Prochlorales	Phylogenetic groups of Archaeobacteria, Ecology and habitats of Archaeobacteria,	Whole community analysis methods: DNA- DNA reassociation,	Application of gel-free techniques in biological systems	Metagenomic approach for the biofilm community analysis
	SLO-2	Methanogens	Physiology of Archaeobacteria-their role in environmental sustainability	Whole community analysis methods: G+C fractionation	Mass Spectrometry; Matrix Assisted Laser Desorption and Ionization (MALDI)	Metagenomic Approaches for Understanding New Concepts in Microbial Science
S-9	SLO-1	Methanogenic-General characteristics and properties	Role of Archaeobacteria in the environmental pollution management	Whole genome sequencing; DNA Microarray Technology	Electrospray Ionization (ESI)	Accessing the Soil Metagenome for Studies of Microbial Diversity
	SLO-2	Methanogens –Environmental applications	Magneto tactic bacteria.	Next Generation Technology	Mass spectrometry data analysis – computational tools.	Recent Advances and Perspectives in Metagenomic Studies of Soil Microbial Communities

Learning Resources	<ol style="list-style-type: none"> Joanne M Willey, Joanne Willey, "Prescott's Microbiology," McGraw-Hill Education; 9th edition, 2013. Stephen P. Hunt and Frederick J. Livesey, "Functional Genomics" Oxford University Press, 2000. R. M. Twyman, "Principles of Proteomics", Taylor & Francis, 2nd edition, 2008. Diana Marco Universidad Nacional de Cordoba, Argentina "Metagenomics: Current Innovations and Future Trends", Caister Academic Press, 2011. Maier, R.M. Pepper, I.L and Gerba, "Environmental Microbiology," C.P. Academic press, 2000. Gavin Lear, "Biofilms in Bioremediation: Current Research and Emerging Technologies", Caister Academic Press, 2016.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	40 %	-	30%	-	30%	-	30%	-	30%	-
Level 2	Apply Analyze	40 %	-	40%	-	40%	-	40%	-	40%	-
Level 3	Evaluate Create	20 %	-	30%	-	30%	-	30%	-	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. S. Sam Gunasekar, Orchid Chemicals and Pharmaceuticals Ltd., sam@orchidpharma.com	1. Dr. A. Gnanamani, CSIR-Central Leather Research Institute, agmani_2000@yahoo.com	Dr. Ramani, SRMIST
2. Dr. D. Gunaseelan, BIOCON Ltd., guna.sachin@gmail.com	2. Dr. Anbumani Sadasivam, CSIR-Indian Institute of Toxicology Research, anbumani@iitr.res.in	Dr.W.Richard Thilagaraaj

Course Code	18BTE409T	Course Name	BIOREMEDIATION TECHNOLOGY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Biotechnology		Data Book / Codes/Standards	Nil	

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																	
CLR-1: Create the awareness on the microbial applications in the environmental pollution abatement		Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15			
CLR-2: Give an overview of indigenous microbes on environmental bioremediation																									
CLR-3: Educate the molecular insights on conservation of biodiversity																									
CLR-4: Apply the metagenomic approach for the environmental microbial analysis																									
CLR-5: Apply the metaproteomic approach for the environmental applications																									
CLR-6: Demonstrate the application of biofilm communities in environmental applications and their metagenomic approach																									
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																							
CLO-1: Apply the concepts of biodiversity and their importance.		1	80	80																					
CLO-2: Understand the extremophiles and its applications in environmental remediation.		2	85	75																					
CLO-3: Use metagenomics data to describe the taxonomic make-up and ecological processes of microbial communities from a range of environments.		2	75	80																					
CLO-4: Assemble and annotate genomes by identifying genes.		2	85	80																					
CLO-5: Apply next generation sequencing technology.		3	85	75																					
CLO-6: Analyze the biofilm communities in the soil microbiome and their metagenomic strategies.		2	80	80																					

Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
H	H	H	H		M	L	H	H	H	H	H	H	H	H
H	H	H	H			M	H	H	H	H	H	H	H	H
M	H	M	H	M	M		M	H	H	H	H	H	H	H
H	H	H	H			H	L	H	H	H	H	H	H	H
H	H	H	H		M	H	H	H	L	H	H	H	H	H
H	H	H	H	L	M	M	M	H	H	H	H	H	H	H

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Principles of bioremediation	Bioremediation technologies	Bioremediation project management	Microbial oxidation of heavy metals	Nuclear waste bioremediation
	SLO-2 Introduction to Bioremediation: Types of Bioremediation	Bioremediation Techniques: bio stimulation & bio augmentation	Defining the project and goals	Bioremediation	Microbes in pollution Remediation
S-2	SLO-1 Bioremediation Mechanisms	In situ and ex situ remediation technologies : (Bio) venting	Site characterization	Bioremediation	Heavy metal toxicity in the environment
	SLO-2 Microbes for Bioremediation	In situ and ex situ remediation technologies : (Bio)sparging	Screening and selecting remediation alternatives	Microbial sources for the oxidation of minerals from ores	Heavy metal bioremediation
S-3	SLO-1 Metabolic process involved in bioremediation	In situ and ex situ remediation technologies : (Bio)stripping	Process design	Bio-oxidation mechanisms	Various reactors for heavy metal removal
	SLO-2 Factors affecting bioremediation	In situ and ex situ remediation technologies : (Bio)sorption barriers	Remediation field activities- Aerobic Bioremediation	Enzymes for heavy metal detoxification	Actinides pollutant removal strategies
S-4	SLO-1 Metabolic process involved in bioremediation	In situ and ex situ remediation technologies : Biofilters	Bioremediation of Surface Soils	Bacterial oxidation of pyrite	Nuclear waste disposal methods
	SLO-2 Limitations of Bioremediations	In situ and ex situ remediation technologies : Bioreactors	Fate and transport of contaminants in the Vadose zone	Siderophores	Case studies of nuclear accidents and its further remediation strategies
S-5	SLO-1 Mycoremediation,	Use of bioreactors for bioremediation	Anoxic/Anaerobic Bioremediation: Anoxic/Anaerobic Environment	Bacterial oxidation of chalcocopyrite	Types of nuclear wastes and environmental effects
	SLO-2 Phytoremediation technologies.	Molecular techniques in bioremediation	Potential anaerobic Bioremediation	Metallothionein and Biosurfactants from microbial sources and their role in heavy metal removal	Natural nuclear wastes
S-6	SLO-1 Xenobiotics and recalcitrant Man-made pollution	Application, specific advantages and disadvantages of bioremediation technologies,	Anoxic/Anaerobic Processes – Fermentation	Bacterial oxidation Sphalerite	Man-made nuclear wastes
	SLO-2 Dyes and Detergents	Use of bioreactors for bioremediation.	Bioremediation in fresh water and marine systems	Heavy metal bioremediation by filamentous fungi	In situ disposal strategies

S-7	SLO-1	PAH and Aliphatic hydrocarbons	Soil bioreactors: Dry and slurry bioreactors	Bioremediation in marine systems	Microbial Desulfurization of coal	Bioremediation of oil/hydrocarbon contaminated sites
	SLO-2	Ocean oil spills and its consequences	Anaerobic and aerobic bioreactors for ex situ remediation	Natural Attenuation process	Biosorption by live and dead cells	Pathways for hydrocarbon degradation
S-8	SLO-1	Heavy metals leach in ground water	Composting of recalcitrant wastes	Ground water bioremediation	Extraction of metals from ores and metal recovery	Nuclear waste management by microbial intervention
	SLO-2	Antibiotics in wastewater	Land farm bioremediation for in situ wastes	Water desalination	Nano-sponges	e-waste management by microbial intervention
S-9	SLO-1	Volatile organic compounds (VOCs)	Fungal bioremediation	Reverse osmosis for toxic pollutant removal	Microbial enhanced oil recovery (MEOR)	Case studies of e-waste industries
	SLO-2	Radioactive compounds	Functionality of fungal enzymes	Membrane technology for pollutant removal	Nano material for metal recovery and treatment	Emerging contaminants

Learning Resources	1. <i>Principles and Applications</i> McGraw-Hill, 2001. 2. Agarwal S. K., "Environmental Biotechnology", APH Publishing, 2000 3. Martin Alexander, "Biodegradation & Bioremediation", Academic press, 1999.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

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		Internal Experts
		Dr. K.Ramani, SRMIST
		Dr.W.Richard Thilagaj, SRMIST

Course Code	18BTE410T	Course Name	ENVIRONMENT BIOSENSORS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Biotechnology	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 : <i>Understand the fundamentals of biosensors</i>		Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2 : <i>Educate the various types of biosensors</i>																								
CLR-3 : <i>Identify and choose the biosensor for the environmental monitoring</i>																								
CLR-4 : <i>Apply various types of biosensors for the environmental applications</i>																								
CLR-5 : <i>Design the biosensor based on the pollutant parameters</i>																								
CLR-6 : <i>Apply the biomolecules in the development of biosensors</i>																								
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1 : <i>Describe the fundamental principles of biosensors</i>		1	80	80	H	H	H	H	H	H	H	H	H	H	H	H	H	H	H	H	H	H		
CLO-2 : <i>Explain the biosensor concepts for pollutant monitoring</i>		2	85	75	H	H	H	H	H	H	H	M	H	H	H	H	H	H	H	H	H	H		
CLO-3 : <i>Design the biosensors for the detection of emerging contaminants</i>		2	75	80	M	H	M	H	M	M	H	M	H	M	H	H	H	H	H	H	H	H		
CLO-4 : <i>Apply the specific biomolecules for the sensor development for the pollutants monitoring</i>		2	85	80	H	H	H	H	M	H	H	H	H	H	H	H	H	H	H	H	H	H		
CLO-5 : <i>Apply the nanomaterial for the development of environmental biosensors</i>		3	85	75	H	H	H	H	M	M	H	H	H	H	M	H	M	H	H	H	H	H		
CLO-6 : <i>Understand the importance of novel biosensor development for the environmental applications</i>		2	80	80	H	H	H	H	M	M	M	M	M	M	M	H	H	H	H	H	H	H		

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	1	80	80
CLO-1:	Describe the fundamental principles of biosensors	Expected Proficiency (%)	2	85	75
CLO-2:	Explain the biosensor concepts for pollutant monitoring	Expected Attainment (%)	2	75	80
CLO-3:	Design the biosensors for the detection of emerging contaminants		2	85	80
CLO-4:	Apply the specific biomolecules for the sensor development for the pollutants monitoring		3	85	75
CLO-5:	Apply the nanomaterial for the development of environmental biosensors		2	80	80
CLO-6:	Understand the importance of novel biosensor development for the environmental applications				

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Short Biosensor History	Biotransducers	Application of biosensors for Environmental Monitoring- Detection of Organic Compounds	DNA, Biological Recognition & Receptor based Sensors	Nanotechnology-based Biosensor
	SLO-2 Fundamentals of Biosensors	Classification of Biosensors	Polychlorinated biphenyls (PCB)	A Fiber Optic DNA Sensor for Rapid Detection of Environmental E.coli	Multi-analyte determination
S-2	SLO-1 Components of Biosensor	Electrochemical Biosensors	Endocrine-disrupting chemicals	Application of electrochemical DNA-Biosensor to Environmental problems	Miniaturisation
	SLO-2 Types of Biosensors	Electrochemical Immunosensors	Antibiotics	Application of nucleic acid based optical bioprobe for environmental and pharmaceutical analysis	Mass Production
S-3	SLO-1 Characteristics of Biosensor	Optical Biosensors	Pesticides	Lipid-based enzyme electrodes for environmental pollution control- Lipid based sensors for continuous monitoring or rapid screening of environmental pollutants in the field.	Network Systems
	SLO-2 Biosensor Technologies	Electronic Biosensors	Hormones	Immunochemical assays for pesticides and PCBs	Validation
S-4	SLO-1 Types of Bioreceptors	FET- based Electronic Biosensors	Application of Biosensors for Environmental Monitoring- Detection of Inorganic Compounds	Direct piezoelectric immunosensor for pesticides	Bioengineering (GMO)
	SLO-2 Sensing Techniques of Biosensors	Piezoelectric Biosensors	Heavy Metals	Enzyme sensors for detection of pesticides families	Biosensors for environmental monitoring- An EPA perspective
S-5	SLO-1 Biosensors Development for Environmental Monitoring	Gravimetric Biosensors	Inorganic phosphate and nitrate	Biosensors for water quality and exposure assessment issues	Microsystem Technology in Biosensors
	SLO-2 Architectural Design	Pyroelectric Biosensors	Application of Biosensors for Environmental Monitoring- Detection of Biological Compounds	Nanomaterials- based biosensor for detection of environmental pollutants	Recent biosensors for the detection of pathogens
S-6	SLO-1 Bio element and Sensor Element Coupling	Impedimetric Biosensors	Biosides	Recent progress in biosensors for environmental monitoring	Recent biosensors for the detection of potentially toxic elements

	SLO-2	Various Coupling Mechanisms	Amperometric Biosensors	Whole cell bacteria detection	Application of nucleic acid hybridization for the detection of organisms	Recent biosensors for the detection of Toxins
S-7	SLO-1	Covalent Fabrication	Ion Channel Switch	Estimation of Biological Oxygen Demand (BOD)	Enzyme-based electrochemical biosensors to detect pharmaceuticals residues in waste water	Recent biosensors for the detection of Endocrine disrupting chemicals
	SLO-2	Matrix Immobilization	Optical Biosensors	Microbial Detection	Biosensor for the detection of antibiotics residues in milk	Recent biosensors for the detection and monitoring of air pollutants
S-8	SLO-1	Membrane Encapsulation	Microarrays	Antibiotic resistant organisms	Lipid membranes based biosensor for the rapid detection of toxins	Recent biosensors for the detection and monitoring of water pollutants
	SLO-2	Physical Adsorption Fabrication	Surface Plasmon Resonance	Application of Biosensors for Environmental Monitoring- Detection of Air Pollutants	Nucleic acid based biosensors for environmental pollution monitoring	Future sensing system based on conjugation of biosensor and drones for monitoring remote areas
S-9	SLO-1	Nano Biosensors	Reagentless Fluorescent (RF) Biosensors	Biosensors for direct monitoring and indoor air quality and exposure assessment issues	Reporter genes based biosensors for chemical contamination sensing	Recent biosensors for the detection of pollutants in effluents
	SLO-2	Advantages of nanotechnological approaches to biosensor development	Glucose Biosensors	Application in Biodefense Biosensing	Biosensor for the detection of antibiotics in Poultry effluent	Recent biosensor for the detection of contaminants in effluent treatment plant

Learning Resources	1. <i>Biosensors for Direct Monitoring of Environmental Pollutants in Field</i> edited by D.P. Nikolelis, Ulrich J. Krull, Joseph Wang, Marco Mascini.. 2. <i>Chemical Sensors and Biosensors: Fundamentals and Applications</i> edited by F.G. Bănică, Wiley, 2012 W. Strickberger, "Genetics," 3 rd edition – Phi Learning, 2008
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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2. Dr. D. Gunaseelan, BIOCON Ltd., guna.sachin@gmail.com	2. Dr. Anbumani Sadasivam, CSIR-Indian Institute of Toxicology Research,anbumani@iitr.res.in	Dr.W.Richard Thilagaraj, SRMIST

Course Code	18BTE411T	Course Name	MOLECULAR CELL BIOLOGY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Biotechnology	Data Book / Codes/Standards			

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1:	Provide basic knowledge of stem cell specific gene expression in lineage based tissues from the perspective of engineers.	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2:	Identify the role of epigenetic regulation in stem cell proliferation and differentiation		
CLR-3:	Deliver the knowledge on signaling molecules and molecular mechanisms that regulate the stem cell proliferation and differentiation.		
CLR-4:	Analyze transcriptomics and its applications in tissue engineering		
CLR-5:	Create insights on genome reprogramming.		
CLR-6:	Utilize the strategies for novel gene editing techniques for tissue engineering		

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1:	Identify gene regulation in stem cells.	2	85	80	H	-	M	H	-	-	-	H	-	-	-	H	H	H	H
CLO-2:	Analyze gene expression in stem cells and artificial generation of pluripotency.	2	80	75	M	-	M	H	-	-	-	M	-	-	-	M	H	H	H
CLO-3:	Identify the applications of growth factor signaling and their receptor molecules.	2	80	75	M	-	M	H	-	-	-	H	-	-	-	H	H	H	H
CLO-4:	Analyze the regulation of molecules involved in self-renewal of stem cells.	2	85	80	M	-	M	H	-	-	-	H	-	-	-	M	H	H	H
CLO-5:	Discuss stem cell death mechanisms.	2	85	80	H	-	M	H	-	-	-	M	-	-	-	H	H	H	H
CLO-6:	Explain nerve cell regeneration, cell survival and cell death.	2	80	75	H	-	M	H	-	-	-	H	-	-	-	M	H	H	H

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction to nucleic acids - genetic material,	Overview of Central dogma.	Principles of membrane organization membrane proteins	Differentiation in Early Development	Newborn screening: Neonatal PKU
	SLO-2	Structure and physicochemical properties of elements.	Characteristics promoter and enhancer sequences.	cytoskeletal proteins Extra cellular matrix	Potency, Commitment,	Cystic fibrosis and sweat tests.
S-2	SLO-1	Primary and secondary structure of DNA	Transcriptional bubble - prokaryotic and eukaryotic RNA polymerase	cell-cell junctions, various types of transport across cell membrane.	Polarity and the specification of asymmetric divisions.	Prenatal diagnosis of diseases, amniotic fluid
	SLO-2	Watson & Crick model	RNA synthesis- Fidelity of RNA synthesis. Inhibitors of transcription.	Protein sorting and trafficking, cargo proteins.	Cellular differentiation of the Nervous system	Fetal blood examination.
S-3	SLO-1	Hogsteen base pairing, Triple helix, Quadruple helix.	Differences in prokaryotic and eukaryotic transcription.	Growth factor signaling, cell-cell communication	Neuronal and Glial Progenitors in Adult Brain,	Karyotyping, Chromosomal abnormalities by cytogenetics.
	SLO-2	DNA super-coiling	Regulatory elements	Mechanism of action of different class of hormones.	Epithelial Stem Cells; Adult Progenitor Cells,	Restriction fragment length polymorphism (RFLP)
S-4	SLO-1	Linking number- satellite	Mechanism of transcription regulation.	Cell cycle –Molecules controlling cell cycle	Mesenchymal Stem Cells, Plasticity	Polymerase chain reaction (PCR)
	SLO-2	DNA replication	Transcription termination.	Cancer, role of Ras and Raf Oncogenesis and apoptosis.	De-differentiation and redifferentiation	Nuclear injection
S-5	SLO-1	Meselson & Stahl experiment bi-directional DNA replication	Splicing - nuclear export of mRNA - mRNA stability.	Cell culture and immortalization of cells and its applications.	Cancer cells and cancer stem Cells.	stem cell transplantations for sickle-cell anemia, hemophilia,
	SLO-2	Proteomics of DNA replication	Role of gene expression in microRNA	Molecular Basis of Pluripotency	Hematopoietic Stem Cells.	Stem cell transplantation for cancer (leukemia and myeloma).
S-6	SLO-1	Overview of differences in prokaryotic and eukaryotic DNA replication	LncRNA, snoRNA, piRNA	Induced pluripotency.	Stem Cells and tissue engineerings.	Muscular dystrophy and stem cell therapy
	SLO-2	Role of telomerase in aging and cancer	srRNA, siRNA and shRNA.	Cell cycle regulators in Stem Cells	Embryonic Stem Cells in Tissue Engineering.	Stem cell therapy
S-7	SLO-1	Mutagens, DNA mutations and their mechanism	Genetic code: Elucidation of genetic code	Stem Cell Niches,	Organ culture	Neurodegenerative disease

	SLO-2	Telomere replication in eukaryotes DNA Repair.	Codon degeneracy, Wobble hypothesis and its importance	Change of Phenotype and Differentiation,	Characterization and maintenance of murine and human embryonic stem cells,	Stem cell transplantation
S-8	SLO-1	DNA mismatch, Base-excision	Prokaryotic and eukaryotic ribosomes.	Aging and stem cell renewal, Quiescent Stem Cells.	Differentiation of embryonic Stem Cells	Dementia
	SLO-2	Nucleotide-excision and direct repair DNA recombination	Prokaryotic and eukaryotic translation and post-translational modification	Lineage tracing experiments in stem cells	Embryonic stem cell cloning	Neurodegenerative disease
S-9	SLO-1	Homologous, site-specific and DNA transposition	Regulation of gene expression with reference to λ phage life cycle.	Techniques used to study cells: flow cytometry and Confocal Microscopy.	Therapeutic cloning of stem cells	CRISPR/Cas9 system-gene editing
	SLO-2	Operon concept - Lac and Trp operon	Eukaryotic gene regulation	Antibody labeling and Immunohistochemistry	Genomic Reprogramming	Applications of CRISPR/CAS-9 techniques in regenerative medicine.

Learning Resources	1. Fundamentals of Biochemistry. Life at the molecular level by Donald Voet, Judith G. Voet and Charlotte W. Pratt. Wiley 2016.	4. Lecture Notes Clinical Biochemistry (8th Edition). Simon Walker, S., Ashby, P., Rae, P., and Beckett, G., Blackwell, 2010.
	2. Tietz Fundamentals of Clinical Chemistry and Molecular Diagnostics, Carl A. Burtis, David E. Bruns. 7th ed. Elsevier, 2014.	5. Textbook of Biochemistry With Clinical Correlations. Devlin, D.M., (Ed). Wiley-Liss, 2010.
	3. Practical Clinical Biochemistry, Harold Varley, Interscience Publishers Inc, 2005	

SLO – Session Learning Outcome

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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Course Code	18BTE412T	Course Name	CELL COMMUNICATION AND SIGNALING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Biotechnology			Data Book / Codes/Standards	

Course Learning Rationale (CLR):		The purpose of learning this course is to:				Learning			Program Learning Outcomes (PLO)															
CLR-1:		Provide basic concepts of gene expression patterns from the perspective of engineers				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLR-2:		Identify the role of epigenetic regulation in adult stem cells				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3	
CLR-3:		Identify the external and internal signaling molecules that regulate the stem cell proliferation and differentiation																						
CLR-4:		Analyze the self-renewal and cell death mechanisms in stem cells																						
CLR-5:		Encourage engineering students to think solving neural degenerative diseases with stem cells																						
CLR-6:		Analyze the molecular mechanism of stemness- signaling pathways and transcription factors																						
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1:		Apply the basic understanding of gene regulation in stem cells				2	85	80	H	H	-	H	-	-	-	M	-	H	-	H	H	H	H	
CLO-2:		Manipulate the gene expression in stem cells and artificial generation of pluripotency				2	80	75	M	M	-	M	-	-	-	M	-	H	-	H	H	H	H	H
CLO-3:		Identify the applications of growth factor signaling and their receptor molecules				2	80	80	H	M	-	M	-	-	-	M	-	H	-	H	H	H	H	H
CLO-4:		Apply the regulation of molecules involved in self-renewal of stem cells				2	85	80	H	H	-	M	-	-	-	M	-	H	-	H	H	H	H	H
CLO-5:		Discuss the stem cell death mechanisms				2	80	85	M	M	-	H	-	-	-	M	-	H	-	H	H	H	H	H
CLO-6:		Analyze nerve cell regeneration, cell survival and cell death.				2	80	80	H	M	-	H	-	-	-	M	-	H	-	H	H	H	H	H

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Germ line stem cells	cell surface receptor mediated signal transduction	Stem cell aging and apoptosis	Neural stem cells	Regeneration, Stem Cells, and the Evolution of Tumor Suppression
	SLO-2	Embryonic fate cell decision	Growth factor and receptors	Regulation and significance apoptosis in stem cells	Neural progenitors	Smads - Polycomb genes
S-2	SLO-1	Interaction between stem cells and their niche	tyrosine kinases Mediated signaling (Ras-Raf-MAP-MEK)	Stem cell necrosis	The heterogeneity of adult neural stem cells	Cellular signaling of Akt/PKB - β -catenin
	SLO-2	Transcriptional regulatory circuitry in embryonic stem cells	Wnt -signaling	Intrinsic - extrinsic pathways of apoptosis	Emerging complexity of neural niche	Induced pluripotency (iPSc)
S-3	SLO-1	Gene expression during development	Notch signaling pathways	Death ligands, cytokines and tumor necrosis factor	Neural stem cell signaling	Epithelial-mesenchymal transition (EMT)
	SLO-2	Maintenance of totipotency and its factors	Hedgehog singling	Role of apoptosis in hematopoiesis	Neural stem cell homeostasis	EMT markers
S-4	SLO-1	Pluripotency associated transcription factors	Hippo signaling	Apoptosis resistance in stem cells	Galecitin-1 in neural stem cells	Growth factor induced differentiation of stem cells
	SLO-2	Tissue specific multipotency	Insulin-like growth factor signaling	Anti-apoptotic molecules expression in stem cells	Human ESC-derived Neural Rosettes and neural stem cell progression	Pancreatic stem cells
S-5	SLO-1	Stem cells with no tissue specificity	Nf κ B signaling pathways	Caspase mediated apoptosis	CNS fluids and neuronal differentiation	Beta cell differentiation factors and transplantation
	SLO-2	Transcriptional network controlling pluripotency in ES cells	TGF β -activing/nodal BMP-signaling	Apoptosis transcription factors and regulators	Neurotransmitter-induced stem cell differentiation	Stem cell therapy for obesity
S-6	SLO-1	Alternative splicing in embryonic stem cells	FGF signaling pathways	Heat shock proteins	cholinergic-dopaminergic signals	Leukemia, lymphoma and Myeloma
	SLO-2	Niche required for inducing stem cell control	Hematopoiesis and signaling molecules	Apoptosis intracellular kinases	Nerve cell growth factor	Bone marrow transplantation
S-7	SLO-1	Homeostasis and Feed-back regulation in niche	Progenitor cell differentiation factors	Apoptosis adaptor proteins	Induced regeneration of neuronal cells	Cytokine and chemokine therapies
	SLO-2	Cytokines and growth factors maintenance of stemness	Colony stimulating factor and its receptor signaling pathways	Small molecules-induced apoptosis	Neurosphere culture	Cancer stem cell - cell survival and tumor maintenance

S-8	SLO-1	Modeling for stem cell asymmetry	Platelet-derived growth factor signaling pathways	Inhibitors of apoptosis in cancer stem cells	Astrocyte, oligodendrocyte differentiation	Mechanism of cancer stem cell resistance
	SLO-2	Pluripotency genes, expression and regulation	Role of oncogenes in embryonic stem cells	Cellular senescence pathways	Glial cell differentiation	Targeting cancer stem cells
S-9	SLO-1	Epigenetic changes in DNA	Steroid hormone receptor signaling pathways	Telomerase in adult and pluripotent stem cells and Telomerase shortening	Pathophysiology of neuronal stem cell signaling	Selective killing of cancer stem cells
	SLO-2	Epigenetic changes in histones	Effects of melatonin and serotonin in stem cells	Autoimmune destruction of stem cells	Multiple sclerosis, Parkinson's and Alzheimer's	Nanocarrier mediated drug delivery

Learning Resources	<ol style="list-style-type: none"> 1. <i>The science of stem cells</i> - Jonathan M.W Slack - Wiley Blackwell - 2018. 2. <i>Transcriptional and Translational regulation of stem cells</i> - (Advances in experimental medicine and biology - Gary Hime and Helen Abud, 2013. 3. <i>Stem cell regulators (Vitamins and Hormones Book 87)</i> - Gerald Litwack - Academic Press – 2011 4. <i>Control and regulation of stem cells</i>- Bruce Stillman, David Stewart, Terri Grodzicker - Cold Spring Harbor Laboratory -2008
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SLO – Session Learning Outcome

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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Course Code	18BTE413T	Course Name	STEM CELL TECHNOLOGY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Biotechnology	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1:	Provide basic knowledge on embryogenesis from the perspective of engineers.	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Create an interest to know about the different types of stem cells, its isolation, differentiation and transdifferentiation.	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3:	Develop awareness about cancer stem cells, iPSCs and importance of stem cell niches.				-	-	H	M	-	-	M	H	-	H	-	H	H	H	H
CLR-4:	Initiate interest on signaling pathways, epigenetics and latest techniques on gene editing.				-	-	H	M	-	-	M	H	-	H	-	H	H	H	H
CLR-5:	Generate interest on applications and uses of stem cells and create awareness on ethics and regulations of stem cell research.				-	-	H	M	-	-	M	H	-	H	-	H	H	H	H
CLR-6:	Encourage engineering students to develop the strategies for ex vivo for tissue development and disease				-	-	H	M	-	-	M	H	-	H	-	H	H	H	H
					-	-	H	M	-	-	M	H	-	H	-	H	H	H	H
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1:	Apply knowledge about embryogenesis, stem cells and its characteristics.	2	80	70															
CLO-2:	Gain knowledge on different types of stem cells isolation of ESCs, its specialized functions and transdifferentiation.	3	85	70															
CLO-3:	Discuss about cancer stem cells, iPSCs and stem cell niches.	2	80	75															
CLO-4:	Identify the role of signaling pathways, epigenetics and genome editing in engineering of stem cells.	2	80	70															
CLO-5:	Utilize application of stem cells in tissue engineering, treatment of different diseases & ethics and regulations of stem cell research.	3	80	70															
CLO-6:	Apply knowledge on CRISPR/Cas9 gene editing system.	3	80	70															

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Overview of Stem cells	ESCs –IVF, Primate and Mouse ES cells, Markers	Adult stem cells (ASC)-advantages and disadvantages	ESC pluripotency and signaling- JAK-STAT pathway
	SLO-2	Early development of embryos	Nuclear transfer technology in ES cells	Sources of ASCs and its properties and its role as specialised cells in differentiation	Activin/Nodal/TGFβ Signaling Pathway
S-2	SLO-1	Stem Cells in research	Human ESCs	Transdifferentiation-Definition	FGF Signaling Pathway
	SLO-2	Totipotent, multipotent, oligopotent	Isolation and culturing of hESC's	Fusion experiments	Wnt signaling and Insulin-like growth factors
S-3	SLO-1	"Stemness": Definitions, Criteria	Differentiation of stem cells	Experiments on transdifferentiation	HSC signaling pathways- Notch
	SLO-2	Criteria and Standard of stemness	Stem Cell Niche in Regenerative Medicine-Stem cells and their niches	Intestine-oseophagus cell transition, lens regeneration, liver to pancreas and vice versa	Wnt signaling
S-4	SLO-1	Formation of stem cells	Stem Cells derived from early mouse embryos-ES cells	Induced pluripotent stem cells (iPSCs)-Methodology	TGF signaling
	SLO-2	Embryonic and adult stem cells	EC cells	Induced pluripotent stem cells (iPSCs)-Applications	SMAD signalling
S-5	SLO-1	Potency of Stem Cells	EG cells	SCNT	Epigenetic control of stem cells-experimental background
	SLO-2	Types and classification of stem cells based on potency	TS cells	Cell fusion, treatment	Effects of global histone modifications
S-6	SLO-1	Types of stem cells –Embryonic stem cells (ESCs)	Systems/models for ES differentiation	Cancer stem cells- Isolation	DNA methylation in differentiated versus undifferentiated cells
	SLO-2	Types of stem cells-Adult stem cells (ASCs)	3D bioprinting using stem cells	Cancer stem cells -Characterization	Effect of TSA on stem cell differentiation
S-7	SLO-1	Differences between ESCs and ASCs	Formation of early extraembryonic lineages	Cancer Stem Cells - properties, origin	Transcriptional factors network
					Stem cell treatment for burns

	SLO-2	Similarities between ESCs and ASCs	Pluripotent cell development	Cancer Stem Cells - Theories	Effects of histone demethylases	Transplantable matrices
S-8	SLO-1	Identification and characterization of ESCs at cellular level	Formation of somatic lineages—Haematopoietic Lineages	CSCs and Metastasis: The Primary TME	Epigenetics in somatic cells	Ethics of Stem Cell Research- The Ethics of Destroying Human Embryos for Research
	SLO-2	Identification and characterization of ESCs at molecular level	Formation of somatic lineages—Neuronal Lineages	CSCs and Metastasis: Metastatic Niche	Epigenetics in iPSCs	The Ethics of Using Human Embryonic Stem Cells in Research
S-9	SLO-1	Identification and characterization of ASCs at cellular level	Therapeutic cloning using ESCs- Disease cell model development	Breast cancer metastasis	Genome Editing in Stem Cells- ZFN, TALENS	Regulations governing Stem Cell research- ICMR, Drugs and Cosmetic Act
	SLO-2	Identification and characterization of ASCs at molecular level	Reproductive cloning using ESCs	Tumor suppressor and Proto-oncogenes	CRISPR/Cas9 strategies, Design of DNA donor templates for gene knock-ins	Stem Cell as the investigational new drug

Learning Resources	<p>1. Robert Lanza, Edited by: Robert Lanza and Anthony Atala, "Essentials of Stem Cell Biology" 3rd Edition, Academic Press, Copyright © 2014 Elsevier Inc. 4.</p> <p>2. Huang G, Ye S, Zhou X, Liu D, Ying QL. Molecular basis of embryonic stem cell self-renewal: from signaling pathways to pluripotency network. Cell Mol Life Sci. 2015, May; 72 (9):1741-57.</p>
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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2. Dr. A. Premkumar, Ph.D., GVK Biosciences, Hyderabad aprem70@yahoo.com	2. Dr.Sudha Warriar, Associate Professor, Manipal University, sudha.warrier@mannipal.edu	2. Dr. N.Selvamurugan, SRMIST selvamun@srmist.edu.in

Course Code	18BTE414T	Course Name	BIOMATERIALS IN TISSUE ENGINEERING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department		Biotechnolgy		Data Book / Codes/Standards	

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Demonstrate the basic knowledge on biomaterials from the perspective of engineers.	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Analyze biological tissue engineering problems with biomaterials.																		
CLR-3 :	Demonstrate basic concepts regarding design and mechanical properties of selected biomaterials.																		
CLR-4 :	Analyze the design and mechanical properties of selected biomaterials for specific medical applications.																		
CLR-5 :	Demonstrate good manufacturing of biomaterials																		
CLR-6 :	Analyze the strategies for global marketing of biomaterials																		

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)															
CLO-1 :	Explain the basic techniques to manufacture scaffolds from raw biomaterials and explain the different prerequisites for the biomaterials.	2	80	70															
CLO-2 :	Illustrate the types of biomaterials for biomedical applications.	2	75	80															
CLO-3 :	Explain the biological problems in tissue engineering that require engineering expertise to solve them.	2	80	70															
CLO-4 :	Explain the applications of biomaterials for various biomedical applications.	2	80	75															
CLO-5 :	Explain good manufacturing of biomaterials related their applications.	3	80	70															
CLO-6 :	Illustrate global marketing of biomaterials for commercialization	2	85	75															

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Introduction to biomaterials	Introduction to tissue engineering	Bioactive molecules	Applications of biomaterials
	SLO-2	Properties and salient features of biomaterials	Basic concepts in tissue engineering	Classification and role of bioactive molecules in tissue engineering	Healthcare
S-2	SLO-1	Elements of Biomaterials	Fundamentals of tissue engineering	Stimuli responsive in biomaterials	Biomaterials in biomedical applications
	SLO-2	Metals, implants	Complexity of tissue engineering	Stimuli responsive in polymers	Tissue engineering
S-3	SLO-1	Biomaterials preparation	Tissues	Biomimetics	wound care und suture materials,
	SLO-2	Biomaterials characterization	Organization of tissues in vertebrate body	Dental and bone	Regulatory strategies for biomaterials
S-4	SLO-1	Processing of different bioceramic and	Cell sources	Drug deliveries	vascular implants and bio-inspired materials
	SLO-2	Properties of bioceramics	Stem cells	Nanoparticles in drug delivery	Biomimetic devices
S-5	SLO-1	Processing of different polymeric materials	Cell lineages	Designing of nanoparticles for drug delivery	Organ transplant
	SLO-2	Properties of polymeric materials	Osteoblasts	Targeted delivery	Tissue Construction
S-6	SLO-1	biocomposites materials	Cell-material interactions	Peptides in drug delivery	Bioartificial tissues
	SLO-2	Polymers-ceramics	Cell-material response	Proteins in drug delivery	Connective tissues
S-7	SLO-1	Physical properties of biomaterials	Assessment of biocompatibility of biomaterials	DNA in drug delivery	Regeneration of connective tissues
	SLO-2	Chemical properties of biomaterials	MTT and cytotoxicity assays	RNA, oligos in drug delivery	Targeting ligands in drug delivery
S-8	SLO-1	Mechanical properties of biomaterials	Cell viability assays	Surface modifications	Targeting ligands in cancer treatment
	SLO-2	Thermal properties off biomaterials	Antibacterial assessment of biomaterials-	Applications in drug delivery	Tissue regeneration and growth and repair
S-9	SLO-1	Evaluation of biomaterials	In vitro evaluation of biomaterials-	Advantages and limitations of biomaterials in drug delivery	Cell growth and repair
	SLO-2	Biological response	In vivo evaluation of biomaterials	Limitations of biomaterials in drug delivery	Global marketing of biomaterials

Learning Resources	<ol style="list-style-type: none"> 1. Hench L. Larry, and Jones J., (Editors), <i>Biomaterials, Artificial organs and Tissue Engineering</i>, Woodhead Publishing Limited, 2005 2. <i>Nanocomposite science and technology</i>, Pulickel M. Ajayan, Linda S. Schadler and Paul V. Braun, Wiley-VCH, 2005 3. Ulrich Meyer, Thomas Meyer, Jörg Handschel, Hans Peter Wiesmann (2009): <i>Fundamentals of Tissue Engineering and Regenerative Medicine</i>, Springer 4. <i>Regenerative Medicine and Tissue Engineering</i>, Edited by Jose A. Andrade, ISBN 978-953-51-1108-5, Publisher: InTech, 2013 5. S. Amato and B. Ezzell, (Editors), <i>Regulatory Affairs for Biomaterials and Medical Devices</i>, Woodhead Publisher, 2015
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Expert
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2. Dr. Gokuladhas Krishnan, Director, Laboratory, World Stem Cell Clinic, Chennai, care@worldstemcellclinic.com	2. N. Srinivasan, Ph. D., Chettinad Health City, Chennai srinivasanibms@gmail.com	2. Dr. M. Pandima Devi, SRMIST pandimam@srmist.edu.in

Course Code	18BTE415T	Course Name	NANOTECHNOLOGY IN REGENERATIVE MEDICINE	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Biotechnolgy			Data Book / Codes/Standards	

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																	
CLR-1 :	Provide an overview of the distinctive features of nanotechnology and their application to bio-medical problems from the perspective of engineers.	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15			
CLR-2 :	Obtain knowledge on cutting-edge nanomedicine technologies for sensing and imaging, drug delivery, and other therapeutic applications.																								
CLR-3 :	Develop the strategies for drug delivery.																								
CLR-4 :	Initiate interest for utilizing nanotechnology in environmental applications.																								
CLR-5 :	Generate interest on applications related to therapeutic applications.																								
CLR-6 :	Encourage engineering students to develop nanomaterials in intellectual property perspective.																								
					Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge																	
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:						Problem Analysis																	
CLO-1 :	Explain the basics of nanobiotechnology in relation to nanomedicine	1	75	70							H	M	M						M	H		H	H	H	H
CLO-2 :	Learn about the role of nanomaterials as vehicles for drug delivery	3	80	70							H	M	M						M	H		H	H	H	H
CLO-3 :	Obtain the knowledge on nanomedical devices and their applications	2	80	70							H	M	M						M	H		H	H	H	H
CLO-4 :	Learn about various types of nanobiosensors and their applications	2	85	75							H	M	M						M	H		H	H	H	H
CLO-5 :	Discuss about toxicity of nanomaterials and its remediation	2	80	70							H	M	M						M	H		H	H	H	H
CLO-6 :	Gain knowledge on nanomaterials in therapeutic applications.	2	80	70				H	M	M						M	H		H	H	H	H			

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Basics of nanobiotechnology in relation to nanomedicine	Nanomaterials as vehicles for drug delivery	nanorobots in medicine	Introduction- nanobiosensors	Nanomaterials exhibiting toxicity
	SLO-2	Scientific principles of nanomedicine	Types of Nanomaterials	nanorobots in nanosurgery	Biosensing Techniques	Physico-chemical characteristics dependent toxicity
S-2	SLO-1	Nanotools – types	criteria and selection of Nanomaterials	nanocameras	unique properties of nanobiosensors	Toxicity – carbon nanotubes,
	SLO-2	Nanotools – various techniques of detection	Sources of Nanomaterials	Application of nanocameras	nanobiosensors	quantam dots toxicity
S-3	SLO-1	Scanning Tunneling microscope	Drug loading and release	nanochips	Preparation of nanobiosensors-immobilisation strategies	Toxicity – Gold nanomaterials,
	SLO-2	Atomic Force Microscope	biodegradation	nanoimplants	covalent conjugation technique	silver nanoparticles toxicity
S-4	SLO-1	Functional biological nanomaterials nanoengines	Nanomaterial clearance	nanomaterials for bone and cartilage applications	Preparation of nanobiosensors- Self assembled monolayer nanomaterial	Handling, storage and disposal of nanomaterials
	SLO-2	Functional biological nanomaterials nanoengines	Types of nanomaterials for clearance	nanomaterials for vascular applications and skin disorders	Nano biosensors for protein and DNA detection	Remediation in case of nanomaterials spills
S-5	SLO-1	Nanomaterials and their Production	nanopolymers	Nanogenetics	Detection methods – optical detection	In vitro and in vivo toxicity assessment of nanoparticles
	SLO-2	Nanomaterials and their Production	Classification of biopolymers	nanoparticle-based therapy for genetic diseases	Detection methods- electronic detection	Embryonic Toxicity of Nanoparticles
S-6	SLO-1	Nanodevices-Quantum Computing	magnetic nanoparticles – preparation and properties	Cell Delivery of Therapeutic Nanoparticles	In vivo Biosensors	quantitative nanostructure-toxicity relationship
	SLO-2	Spintronics, Photonic and fluidic devices	magnetic nanoparticles - applications	nanomaterials for delivery in cells- nerve cell repair	Nanowire Biosensors	Modelling the Toxicity of Nanoparticles
S-7	SLO-1	Impact of nanotechnology - Scientific and technical Impacts	nanotubes, dendrimers	Applications of Nanofibers in Tissue Engineering	Cantilever Biosensors	Green Synthesis of Nanoparticles – mechanism

	SLO-2	Environmental Impacts	Nano immunotherapy	Applications of Nanofibers in Tissue Engineering	Applications – DNA nanobiosensor	Green Synthesis of Nanoparticles – Applications
S-8	SLO-1	Grand challenges of nanomedicine	Nanomaterials for vaccine delivery	nanomaterials for stem cells growth	Applications – Protein biosensor	Nanoparticles: Environmental Problems
	SLO-2	Ethical issues	Types of nanomaterials as vaccine adjuvants	Stem Cell Tracking with Nanoparticles	whole cell biosensor applications	nanotoxicity regulations
S-9	SLO-1	Government Promotion of Advancements in Nanomedicine	Nanotechnology and Diagnostic Imaging	Nanomaterials for Stem Cell Imaging	Nanobiosensor in diagnostics	nanomaterials intellectual property perspective
	SLO-2	Government Evaluation, Policy and Regulation of Nanotechnology	Nanomaterials as contrast agents in clinical use	Nanotechnology in the regulation of stem cell behavior	Biosensors in forensic sciences	nanomaterials intellectual property perspective

Learning Resources	<ol style="list-style-type: none"> 1. Zoraida P. Aguilar. <i>Nanomaterials for Medical Applications</i> (2012), Elsevier Publications 2. Harry F. Tibbals, <i>Medical Nanotechnology and Nanomedicine Perspectives in Nanotechnology</i> (2017), CRC Press
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. S Natarajan Advisor / Sr. Vice President - R & D; Sami Labs Limited Bangalore. mail@samilabs.com	1. Prof. Sundara Ramaprabhu, Department of Physics IIT-Madras. ramp@iitm.ac.in; ramp@physics.iitm.ac.in	1 Dr. Ramkumar K M, SRMIST ramkumar.km@res.srmuniv.ac.in.
2. Dr. Gokuladhas Krishnan, Director, Laboratory, World Stem Cell Clinic, Chennai, care@worldstemcellclinic.com	2. Prof. Ashok M. Raichur, Department of Materials Engineering IISc, Bangalore. amr@materials.iisc.ernet.in	2. Dr. N. Selvamurugan, SRMIST selvamun@srmist.edu.in

Course Code	18BTE416T	Course Name	TISSUE ENGINEERING FOR REGENERATIVE MEDICINE	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Biotechnolgy	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1:	Describe the fundamentals of tissue engineering and tissue repairing from the perspective of engineers	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Express knowledge on clinical applications of tissue engineering	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3:	Identify the basic concept behind tissue engineering																		
CLR-4:	State engineering students to think more on artificially generated tissues for their tissue engineering applications																		
CLR-5:	Discuss the knowledge on 3D-bioprinting																		
CLR-6:	Explain the strategies for innovative bioactive research on tissue engineering																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1:	Apply the components of the tissue architecture	1	80	70	H	H	H	M		M	M	H	H	H	H	H	H	H	H
CLO-2:	Illustrate the characteristics of stem cells and their relevance in medicine	3	85	75	H	H	H	M		M	H	H	H	H	H	H	H	H	H
CLO-3:	Employ an awareness about the properties and broad applications of biomaterials	2	80	70	M	H	H	M	M	M	M	H	H	H	H	H	H	H	H
CLO-4:	Demonstrate the role of tissue engineering and stem cell therapy in organogenesis	2	80	70	H	H	H	M		M	H	H	H	H	H	H	H	H	H
CLO-5:	Illustrate the developing methods and new biomaterials for the construction of functional tissue and organ substitute's	2	75	80	H	H	H	M		M	M	H	H	H	H	H	H	H	H
CLO-6:	Analyze the testing of biomaterials in vitro and in vivo	2	80	70	H	H	H	M	M	M	M	H	H	H	H	H	H	H	H

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Cellular Basis of Regeneration	Tissue types	Fundamentals of biomaterials science	Introduction to Stem Cells	Discussion on Stem cell therapy
	SLO-2 Molecular Basis of Regeneration	Tissue components	Concept of biocompatibility	Different types of Stem cells	Discussion on Molecular therapy
S-2	SLO-1 Introduction to tissue engineering	Tissue repair	Classes of biomaterials	Hematopoietic differentiation pathway of stem cells	Therapies for spinal cord injury, muscular dystrophy
	SLO-2 Basic definitions used tissue engineering	Engineering wound healing	Basic properties of Biomaterials	Potency of stem cells	Orthopedic applications
S-3	SLO-1 Current scope of development in tissue engineering	Sequence of events of wound healing	Disinfection and sterilization of biomaterials	Plasticity of stem cells	Stem cells and Gene therapy
	SLO-2 Use of tissue engineering in therapeutics	Three-Dimensional Cell Culture	Physico-chemical properties of biomaterials:	Sources of embryonic stem cells	Tissue engineering of bones
S-4	SLO-1 Components used in tissue engineering	Organ Culture	Mechanical (elasticity, yield stress, ductility, toughness, strength, fatigue, hardness, wear resistance)	Sources of hematopoietic and mesenchymal stem cells	Tissue engineering of cartilages
	SLO-2 Primary cells, cell lines and immortalization of cells	Organotypic Culture	Tribological (friction, wear, lubricity)	Stem Cell markers, FACS analysis	Neural tissue engineering
S-5	SLO-1 Measurement of tissue characteristics, appearance, cellular component	Introduction to Basic wound healing	Morphological and texture, Physical (electrical, optical, magnetic, thermal)	Differentiation of Stem cell systems- Liver	Skin tissue engineering
	SLO-2 Cellular fate processes, Cell differentiation, Cell migration	Applications of growth factors:	Chemical and biological properties	Differentiation of neuronal stem cells	Cardiovascular tissue Engineering
S-6	SLO-1 Direct Cell-Cell contact – Cell junctions in tissues	Role of VEGF/angiogenesis	Elements in contact with the surface of a biomaterial: blood composition, plasma proteins, cells, tissues	Types & sources of stem cell with characteristics:	Therapeutic applications
	SLO-2 Malfunctions in direct cell-cell contact signaling. Response to mechanical stimuli	Different approaches for angiogenesis and its importance	Role of Scaffolds in tissue engineering	Embryonic stem cells and Adult stem cells	Introduction to the basic principles for Biofabrication and 3D printing
S-7	SLO-1 Extracellular matrix (ECM) component and their regulation of cell behavior	Basic properties of the growth factors	Biopolymers	Comparison between embryonic and adult stem cells	Methods and materials, for Biofabrication and 3D printing

	SLO-2	Mechanical measurements of the ECM component	Cell-Matrix Interactions	Modifications of Biomaterials	Bone marrow, primordial germ cells	Applications of Biofabrication and 3D printing:
S-8	SLO-1	Physical properties of the ECM component	Cell-Cell Interactions	In vitro testing of biomaterials	Cancer stem cells	Lab-on-chip, Organ-on-chip
	SLO-2	Cell-ECM interactions – Binding to the ECM	Telomeres and Self-renewal	In vivo testing of biomaterials	Induced pluripotent stem cells	Prosthetics and Implants
S-9	SLO-1	Modifying the ECM	Cell migration	Role of Nanotechnology	Culture of stem cells	Innovative bioactive research
	SLO-2	Malfunctions in ECM signaling	Control of cell migration in tissue engineering	Applications of Biomaterials	Immunomodulation of mesenchymal stem cell	Regenerative medicine

Learning Resources	<ol style="list-style-type: none"> 1. Clemens Van Blitterswijk, Jan De Boer, "Tissue Engineering", 2nd Edition - Academic Press, 2014 2. Robert Lanza, Robert Langer, Joseph Vacanti, "Principles of Tissue Engineering", 4th Edition - Academic Press, 2013 3. John P. Fisher, Antonios G. Mikos, Joseph D. Bronzino, Donald R. Peterson, "Tissue Engineering: Principles and Practices", 1st Edition - CRC Press, 2017 4. Buddy D. Ratener, Allan S. Hoffman, Frederick J. Schoen, Jack E. Lemons, "Biomaterial Science: An Introduction to Material in Medicine", 3rd edition – Academic Press, 2013 5. Lijie Grace Zhang, John Fisher, Kam Leong, "3D Bioprinting and Nanotechnology in Tissue Engineering and Regenerative Medicine", 1st Edition - Academic Press, 2015
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Dr. Harikrishna Varma, SCTIMST, Thiruvananthapuram, India e-mail: head-bmtw@sctimst.ac.in	Dr. Sourabh Ghosh, IIT Delhi, India e-mail: sghosh08@textile.iitd.ac.in	Dr. Koutsav Sarkar, SRMIST e-mail: koustavm@srmist.edu.in
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Course Code	18BTE417T	Course Name	BIOREACTORS IN TISSUE ENGINEERING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Biotechnolgy			Data Book / Codes/Standards	

Course Learning Rationale (CLR):		The purpose of learning this course is to:					Learning			Program Learning Outcomes (PLO)														
CLR-1 :		Provide the basic concepts of tissue engineering and bioreactors from the perspective of engineers.					1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :		Identify the 3D- culture of stem cells and organogenesis					Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :		Identify the role of stem cells in clinical applications of different disease conditions.																						
CLR-4 :		Identify the safety and efficacy of bioreactors																						
CLR-5 :		Create the strategies for designing clinically relevant bioreactors																						
CLR-6 :		Identify the usages of bioreactors and their advantages in tissue engineering																						
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:					1	2	3	H	-	-	H	-	-	-	H	-	-	-	H	H	H	H
CLO-1 :		Apply the basic understanding of large scale production stem cells in bioreactors					1	85	85	M	-	-	M	-	-	-	M	-	-	-	H	H	H	H
CLO-2 :		Discuss the 3D- culture systems and artificial organs					2	80	80	M	-	-	M	-	-	-	M	-	-	-	H	H	H	H
CLO-3 :		Identify the bioreactor based strategies to generate organoids					2	85	80	H	-	-	M	-	-	-	M	-	-	-	H	H	H	H
CLO-4 :		Understand the role of bioreactors in the development of drug development and therapy					2	80	85	M	-	-	M	-	-	-	M	-	-	-	H	H	H	H
CLO-5 :		Explain the large scale production of stem cells					2	80	80	H	-	-	H	-	-	-	M	-	-	-	H	H	H	H
CLO-6 :		Apply the clinical applications of bioreactors					3	85	85	H	-	-	H	-	-	-	M	-	-	-	H	H	H	H

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction to tissue engineering – Current scope of development; Cell as therapeutic agents	Bioreactors in Tissue Engineering; Tissue formation in Bioreactor systems – Generation of functional tissues	Bioreactors- Link between in vitro and in vivo studies	Biomaterials: Properties of Biomaterials ,Surface, bulk, mechanical and biological properties	Clinical applications - Stem cell therapy, Molecular therapy
	SLO-2					
S-2	SLO-1	cell numbers and growth rates, measurement of cell characteristics morphology, cell viability, motility and functions	Principles of functional tissue engineering – Functional tissue engineering and role of Biomechanics in a 3D environment	Novel approaches in bioreactor systems for stem cell seeding of vascularized bioscaffolds	Scaffolds & tissue engineering, Types of Biomaterials, biological and synthetic materials	In vitro organogenesis, Neurodegenerative diseases
	SLO-2					
S-3	SLO-1	Biochemical Basics for Nutrition and Growth of living Cells - Measurement of tissue characteristics, appearance, tissue types	Ex vivo engineering of living tissues – generation of mammalian tissue equivalents in vitro – Bioreactors role in tissue engineering of Cartilage	Bioreactor-based strategies with reconstructive applications of (Vascularized composite allotransplantation) VCA	Biopolymers, Applications of biomaterials,Modifications of Biomaterials	spinal cord injury, heart disease, diabetes, burns and skin ulcers
	SLO-2					
S-4	SLO-1	Tissue dynamics and Cell migration cellular component, ECM component, mechanical measurements and physical properties	Cardiovascular tissue (Cardiomyocytes, valves), Vascular tissue, musculoskeletal tissue and Skin –Bone	Stem cell cultivation in scaffold-bioreactor systems; Physiological biomimicry	Role of Nanotechnology. Sensing and Automation in bioreactor systems	muscular dystrophy, orthopedic applications
	SLO-2					
S-5	SLO-1	Complexity and organization of the Organ system; Bioreactors; History of Bioreactors	microfluidic devices and microbioreactors for stem cell micro environment – Perfusion bioreactors for granulocyte progenitor cell growth; Bioreactor stimulation	Understanding Mechanical forces on organs and functional aspects	Bioreactors in drug discovery and implant testing; Bioreactors in clinics	Stem cells and Gene therapy
	SLO-2					
S-6	SLO-1	Types of Bioreactors – Perfusion Bioreactors for 3D cultures, Spinner Flask Bioreactor	Mechanics and Controlled Parameters of Bioreactors – Temperature, pH, Dissolved oxygen (DO), Oxygen Diffusion	Control and Feedback Control in Mechatronics for Mechanical Stimulation; Scaffolds and Constructs for Bioreactor Systems (including adapted Fabrication Techniques)	Stem cell cultivation in scaffold-bioreactor systems;	Physiological models, tissue engineering therapies, product characterization
	SLO-2					

S-7	SLO-1	Rotating Wall Bioreactor, Compression Bioreactor, Strain Bioreactor	Nutrient Transport, Waste Removal; Predicting Mechanical Functionality of Engineered Tissues	Tissue architecture- Tissue types and Tissue components, Tissue repair	Large-scale bioreactor cultivation of pluripotent stem cells	components, safety, efficacy. Preservation – freezing and drying
	SLO-2					
S-8	SLO-1	static culture, stem cell cultivation in scaffold Bioreactor systems	Engineering stem cell niches in bioreactors- Oxygen tension, Scaffold/substrate cues	Basic wound healing events, Applications of growth factors	Engineering of functional bone tissue from human stem cells	Patent protection and regulation of of tissue-engineered products,ethical issues
	SLO-2					
S-9	SLO-1	Hydrostatic pressure Bioreactor, Flow Perfusion Bioreactor, Combined Bioreactor	Decellularized ECMs, Mechanical forces, Electrical stimulation, Flow shear rate, and paracrine and autocrine factors	Role of VEGF, Angiogenesis,Basic properties,Cell-Matrix& Cell-Cell Interactions, Control of cell migration in tissue engineering	Miniature bioreactors for precise, systematic studies of stem cell environments	Emerging trends in clinically relevant bioreactor design and future direction
	SLO-2					

Learning Resources	<ol style="list-style-type: none"> 1. Molecular and cellular tissue engineering (The biomedical hand book, 4th edition), Joseph D. Bronzino and Donald R. Peterson, 2015 2. Biomaterials science and Tissue engineering: Principles and methods (Cambridge IISc series) - Bikramjit Basu, 2017 3. 3D Cell culture: Fundamental and applications in tissue engineering and regenerative medicine, Ranjana C. Dutta and Aroop K Dutta, 2018. 4. Raphael Gorodetsky, Richard Schäfer. Cambridge: RSC publishing, c2011.Stem cell based tissue repair.
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SLO – Session Learning Outcome

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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2. Dr. Sudarshan Reddy Oncosimis Biotech Pvt. Ltd. email: info@oncosimis.com	2. Dr. R. Ilangoan , University of Madras Ilangoan2000@yahoo.com	2. Dr. R. Satish, SRMIST satishr@srmsist.edu.in

Course Code	18BTE418T	Course Name	DEVELOPMENTAL BIOLOGY IN TISSUE ENGINEERING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Biotechnolgy	Data Book / Codes/Standards			

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1:	Describe the biology of animal embryogenesis and development.	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Recognize cell-cell interactions from the context of tissue engineering.	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3:	Analyse the role of stem cells and stem cell niches in organogenesis and tissue regeneration.																		
CLR-4:	Discuss the biology of organogenesis.																		
CLR-5:	Summarize the concepts of tissue and organ regeneration.																		
CLR-6:	Appraise the biology of ageing.																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1:	Interpret the basics of embryology and cell signaling mechanisms.	1	80	70			M	H				M		M		H	H	H	H
CLO-2:	Describe the types of cell specification and differentiation.	2	80	75			M	H				M		M		H	H	H	H
CLO-3:	Appraise the role of stem cells in organ development.	2	80	70			M	H				M		M		H	H	H	H
CLO-4:	Apply the genetics behind organogenesis.	2	80	75			M	H				M		M		H	H	H	H
CLO-5:	Identify the developmental biology concepts behind tissue regeneration.	2	80	70			M	H				M		M		H	H	H	H
CLO-6:	Analyze the genetics of ageing.	2	80	75			M	H				M		M		H	H	H	H

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Differential cell affinity	Cell commitment	Introduction to germ layers	Overview of kidney development	Ageing
	SLO-2 Cadherins and cell adhesion	Levels of cell commitment	Ectoderm - Derivatives	Development of kidney tissue	Genes and ageing
S-2	SLO-1 Adhesion dynamics	Cell specification	Endoderm - Derivatives	Overview of reciprocal interactions	DNA repair enzymes in ageing
	SLO-2 Cell migration	Autonomous specification	Mesoderm - Derivatives	Mechanisms of reciprocal induction	Insulin signaling pathway in ageing
S-3	SLO-1 Induction and competence	Conditional specification	Neurulation	Lateral plate mesoderm	Stem cells and ageing
	SLO-2 Cell-cell interactions	Morphogen gradients	Formation of the neural tube	Specification of lateral plate mesoderm	Senescence
S-4	SLO-1 Paracrine factors	Syncytial specification	Patterning of neural tube – AP axis	Vasculogenesis	Epimorphic regeneration in Salamander
	SLO-2 Signal transduction cascades	Cell fate determination	Patterning of neural tube – DV axis	Initial formation of blood vessels	Blastema formation
S-5	SLO-1 The RTK pathway, the Jak-STAT pathway in development	The stem cell concept	Neural crest cells - Introduction	Angiogenesis	Morphallactic regeneration in Hydra
	SLO-2 The Wnt pathway and TGF- β pathway in development	Embryonic stem cells in developmet	Regionalization of neural crest cells	Sprouting of blood vessels	Activation gradients
S-6	SLO-1 Juxtacrine signaling in development	Adult stem cells in developmet	Paraxial mesoderm	Hematopoiesis	Regeneration in mammalian liver
	SLO-2 The Notch pathway in development	Stem cell potency	Specification of paraxial mesoderm	Sites of hematopoiesis	Compensatory regeneration
S-7	SLO-1 Cell patterning	Pluripotent stem cells in development	Cell types of somites	Hematopoietic stem cells (HSC)	Axonal regeneration
	SLO-2 Maintenance of differentiated state	Multipotent stem cells in development	Hox genes and cell fate specificity	HSC niche	Regeneration of neural tissues
S-8	SLO-1 Developmental signals from ECM	Stem cell niches	Somitogenesis	The Digestive tube – Overview	Regeneration of zebrafish fin tissue
	SLO-2 Integrin signaling in development	Regulatory microenvironments	Clock and wave front model	Specification of gut tissue	Molecular control of fin regeneration
S-9	SLO-1 Cell-Cell communication in development	Mesenchymal stem cells in development	Intermediate mesoderm	The Respiratory tube – Overview	Heart regeneration in zebrafish
	SLO-2 Epithelial-mesenchymal transition	Organogenesis – An introduction	Specification of intermediate mesoderm	Formation of respiratory tube	Cardiomyocyte plasticity during regeneration

Learning Resources	1. <i>Developmental Biology</i> (2016): Scott F. Gilbert and Michael J.F. Barresi, Eleventh Edition, Oxford University Press, Inc. 2. <i>Essential Developmental Biology</i> (2012): J.M.W. Slack, Third Edition, Wiley-Blackwell Publishers 3. <i>Principles of Development</i> (2015): Lewis Wolpert, Cheryll Tickle and Alfonso Arias, Fifth Edition, Oxford Publishers, Inc.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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2. Dr. M.C. Raja, Ph.D., Genotypic Technology, Bangalore genotypic@hotmail.com	2. Dr. Naren Ramanan, Ph.D., IISc, Bangalore naren@cns.iisc.ernet.in	2. Dr. R. Satish, Ph.D., SRMIST satishr@srmist.edu.in

Course Code	18BTE419T	Course Name	ADVANCED IMMUNOLOGY AND VASCULAR TISSUE ENGINEERING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Biotechnolgy			Data Book / Codes/Standards	

Course Learning Rationale (CLR):		The purpose of learning this course is to:				Learning			Program Learning Outcomes (PLO)														
CLR-1 :		Provide the most recent advancement in the field of immunology from the perspective of bioengineers				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :		Enrich with knowledge on immunobiology and immune responses related to regeneration and transplants				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :		Recognizing the issue of shortage of organ donors as major limitations in the transplantation and finding solution for the same																					
CLR-4 :		Learning of various treating methods for injury and the significance of vascular engineering																					
CLR-5 :		Understanding the potentials of immunotherapy																					
CLR-6 :		Train and develop skills among the students to explore strategies for stem cell therapy																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	H	-	M	L	-	-	-	-	-	H	-	M	H	H	H
CLO-1 :		Acquire knowledge on the latest tools for diagnosis of diseases				2	80	75	H	-	M	L	-	-	-	-	-	H	-	M	H	H	H
CLO-2 :		Gain knowledge in molecular and immunological basis of diagnosis				2	85	80	H	-	M	L	-	-	-	-	-	H	-	H	H	H	H
CLO-3 :		Able to appreciate the relevance of clinical immunology				2	80	75	H	-	M	L	-	-	-	M	-	H	-	H	H	H	H
CLO-4 :		Acquire knowledge on vascular biology and vascular tissue engineering				2	80	75	M	-	M	L	-	-	-	-	-	H	-	M	H	H	H
CLO-5 :		Acquire knowledge on host vs Graft rejection and the significance of immune system in this process.				2	85	80	H	-	M	L	-	-	-	-	-	H	-	M	H	H	H
CLO-6 :		Understand the challenges behind successful transplantation or grafting and the significance of neovascularization				2	80	75	H	-	M	L	-	-	-	H	-	H	-	M	H	H	H

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Organs and Cells of the Immune System – Primary and Secondary Lymphoid Organs	The Complement Cascades	Immunobiology of Transplantation	Stem cells – types and sources	Vascular system
	SLO-2	Mucosal and Cutaneous associated lymphoid tissue. (MALT & CALT)	The role of Major Histocompatibility Complex in Immune Response	Cells and Factors involved in Transplant Acceptance vs. Rejection	Stem cells in Regenerative Biology	Mechanisms of blood vessel formation
S-2	SLO-1	Mucosal Immunity	Autoimmune disease	Importance of Adaptive immunity functions in Graft Recognition	Stem cell Therapy for Skin Burns, Ulcers, Neurodegenerative diseases, Spinal cord injury	Hemangiogenesis
	SLO-2	Antigens – immunogens, haptens	Interpersonal compatibility	Importance of Innate immunity functions in Graft Recognition	Stem cell Therapy for Ulcers,	Lymphangiogenesis
S-3	SLO-1	Antibody Structure	T lymphocyte recognition restrictions	Molecular Aspects of Acute and Chronic Rejection	Stem cell Therapy for Neurodegenerative diseases, Spinal cord injury	Angiogenic factors and their receptors
	SLO-2	Antibody Function	Evolutionary diversity	The biological basis of Graft Verses Host Disease	Immunological considerations and the potential barriers for Stem cell therapy	Inflammation
S-4	SLO-1	Generation of antibody diversity	Basis of self – non-self discrimination and Autoimmune disorders	Embryonic stem cells	Clinical transplantation, Immune tolerance, Killer Immunoglobulin like receptors in transplantation	Angiogenesis
	SLO-2	B cell maturation	Kinetics of immune response, Hypersensitivity and their types	Expression of histocompatibility antigens	Immunosuppressive therapy	Tissue injury response
S-5	SLO-1	B cell activation and differentiation	HLA typing	T-cell response against u/dhESCs measured by functional assays	Significance of acellular grafts in regeneration	Importance of Vascularization in Tissue Engineering
	SLO-2	T-cell maturation activation and differentiation	Immunological considerations for Tissue Engineering	Interaction of natural killer cells with hESCs	Mast cells in allograft rejection	Angiogenesis and Vascular Remodeling
S-6	SLO-1	T-cell receptors	Stem cell Banking	Generation of patient-specific isogenic hESC lines	Graft-versus-host disease	Organization and Patterning of Endothelial Cells in Engineered Tissues
	SLO-2	Functional T Cell Subsets	Cell-cell co-operation	Immunological Aspects of Allogeneic mesenchymal stem cell therapy	Mouse models of graft-versus-host disease	Models for studying angiogenesis

S-7	SLO-1	Cell-mediated immune responses	Hapten-carrier system	Autologous Mesenchymal Stem Cell Therapies	Cytokines in Graft-versus-Host Disease	Blood Capillary analogues
	SLO-2	ADCC	Types of Tissue injury	CML of Haematopoietic stem cells	Potential barriers to engraftment of human pluripotent stem cells	Role of Vascular endothelial growth factors on Angiogenesis
S-8	SLO-1	Cytokines-properties, and receptors	Tissue injury and immune responses	allogenic transplantation of HSC	Cancer Stem Cells in Solid Tumors	Signaling pathways of Angiogenesis
	SLO-2	Cytokines and therapeutic uses	Immunoprophylaxis	Graft versus Leukemia	Immunologic targeting of cancer stem cell population	Micropatterning approaches to microvessel creation
S-9	SLO-1	Antigen processing	Immunotherapy	Targeting Malignant progenitors	Opportunities in Engineered tissue grafts	Stem cells for vascular regeneration
	SLO-2	Antigen presenting cells	Current status of Immunotherapy	Recent Advances in transplantation	Opportunities in Engineered tissue grafts	Stem cells and scaffolds for vascular regeneration

Learning Resources	<ol style="list-style-type: none"> 1. <i>The Immunological Barriers to Regenerative Medicine</i>. Editors-Paul J. Fairchild, Humana Press 2013 2. <i>Stem Cell Transplantation</i>, edited by Carlos López-Larrea, Antonio López Vázquez, Beatriz Suárez Álvarez. Springer 2016 3. <i>Vascularization: Regenerative Medicine and Tissue Engineering</i>, edited by Eric M. Brey, CRC Press 2017 4. <i>Kuby Immunology</i>. Thomas J. Kindt, Richard A. Goldsby, W.H.Freeman, 2007.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	40 %	-	30%	-	30%	-	30%	-	30%	-
Level 2	Apply Analyze	40 %	-	40%	-	40%	-	40%	-	40%	-
Level 3	Evaluate Create	20 %	-	30%	-	30%	-	30%	-	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
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Course Code	18BTE420T	Course Name	HUMAN GENETICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18BTC104T	Co-requisite Courses		Progressive Courses	Nil
Course Offering Department	Biotechnology	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)															
CLR-1 :		Categorize the pattern of inheritance in humans			Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLR-2 :		Analyze human genome structure and organization						Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3	
CLR-3 :		Use karyotype to analyze human chromosomal aberrations						H	H	H	H		M	L	H	H	H		H	H	H	H	
CLR-4 :		Apply different methods for mapping of genes in humans						H	H	H	H			M	H	H	H		H	H	H	H	
CLR-5 :		Compare genetic variations in human population and prenatal diagnosis						M	H	M	H		M		H	H	H	H		H	H	H	H
CLR-6 :		Illustrate genetic principles in human biology studies						H	H	H	H			H	H	H	H	L		H	H	H	H
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																					
CLO-1 :		Describe the human inheritance concepts and associated complications			2	80	70																
CLO-2 :		Explain the regulation of human gene expression			2	80	75																
CLO-3 :		Recognize the nature of human chromosome abnormalities			2	80	70																
CLO-4 :		Identify the different methods of human disease gene identification			2	80	75																
CLO-5 :		Discuss the importance of population screening and prenatal diagnosis			3	85	70																
CLO-6 :		Appraise the basic concepts of human genetics			2	80	75																

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Human Genetics – Introduction	Human chromosome structure	Karyotyping	Genetic mapping	Genetic testing
	SLO-2 Modern Human Genetics	Human chromosome organization	Chromosome banding	Recombination fraction	Gene scanning
S-2	SLO-1 Monogenic inheritance	Mitochondrial genome organization	FISH technique	Genetic markers	Analysing specified sequence changes
	SLO-2 Incomplete dominance and Codominance	Limited autonomy of mitochondrial genome	Chromosome painting	Two point mapping	MLPA test
S-3	SLO-1 Uniparental disomy	Protein coding genes	Numerical chromosome abnormalities	Multipoint mapping	DNA profiling
	SLO-2 Penetrance, nonpenetrance	RNA genes	Aneuploidy	Fine mapping analysis	Applications of DNA profiling
S-4	SLO-1 Expressivity	microRNAs	Structural chromosome abnormalities	Segregation analysis	Personalized medicine
	SLO-2 Mitochondrial inheritance	Regulatory RNAs	Mosaicism	Linkage analysis	Drugs for specific genotypes
S-5	SLO-1 Late onset diseases	Overlapping genes	Autosomal abnormalities	Association studies	Prenatal diagnosis
	SLO-2 Disease anticipation, imprinting	Genes-within-genes	Sex chromosome abnormalities	Linkage disequilibrium	Cast study: Down syndrome
S-6	SLO-1 Heterogeneity, consanguinity	Noncoding DNA	Human reproductive disorders	Positional cloning	Population screening
	SLO-2 Pleiotropy, mosaicism	Satellite DNA	Congenital abnormalities	Candidate gene testing	Ethical implications
S-7	SLO-1 Mendelian pedigree patterns	Mini- and microsatellite DNA	Polyploidy	Position independent strategies	Pedigree construction
	SLO-2 Pedigree analysis	Transposon derived repeats	Mixoploidy	Case studies	Proband analysis
S-8	SLO-1 Multifactorial inheritance	Alternative transcription	X-inactivation	Duchenne muscular dystrophy	Pharmacogenetics
	SLO-2 Quantitative traits	Long range control of gene expression	Mosaicism due to X-inactivation	Cystic fibrosis	Genetic differences and drug metabolism
S-9	SLO-1 Polygenic theory	DNA methylation	Locus heterogeneity	Branchio-oto-renal syndrome	Genetic counseling
	SLO-2 Gene and genotype frequencies	Epigenetics	Clinical heterogeneity	Crohn disease	Importance of genetic counseling

Learning Resources	1. Strachan, T., Read, A.P., "Human Molecular Genetics", 4 th edition – Garland Science, 2012.
	2. Jack J. Pasternak, "An introduction to Human Molecular Genetics," 2 nd edition – Wiley Liss, 2005.

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Dr. A. Premkumar, PhD, GVK Biosciences, Hyderabad aprem70@yahoo.com	Dr. Bibhas Kar, Madras Medical Mission, Chennai, Tamilnadu drbibhaskar65@gmail.com	Dr. S. Kirankumar, SRMIST
Dr. M.C. Raja, PhD, Genotypic Technologies, Bangalore genotypic@hotmail.com	Dr. Partha P. Majumder, NIBG, Kalyani, West Bengal ppm1@nibmg.ac.in	Dr. M. Jeevankumar, SRMIST

Course Code	18BTE421T	Course Name	HIGH THROUGHPUT TECHNIQUES IN ADVANCED BIOLOGY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	Nil
Course Offering Department	Biotechnology	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1:	List various high throughput techniques in biology and 2. applying these techniques in their own research				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Describe the basics of genomics and its uses				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3:	Analyse qualitatively and quantitative the expression of protein																					
CLR-4:	Compare the differential expression of proteins and interpret it in biological context																					
CLR-5:	Practice advance high throughput techniques like lipidomics, epigenomics and metabolomics																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1:	Describe the terminology, technology characteristics and stake holder benefits of high throughput technologies				1	90	80	H	H	H	H	L	M	L	H	H	H	H	H	H	H	H
CLO-2:	Investigate genomic data, interpret the data in the population genetics and evolutionary genetic context				2	80	80	H	H	H	H	L	M	H	H	H	H	H	H	H	H	H
CLO-3:	Measure the expression of genes, develop necessary expertise in using different computation tools				2	85	80	M	H	M	H	L	M	L	M	H	H	H	H	H	H	H
CLO-4:	Quantify proteins qualitatively and quantitatively and categorize their interactions and modifications.				2	80	75	H	H	H	H	L	H	L	H	H	H	H	H	H	H	H
CLO-5:	Distinguish Metabolomics, Epigenomics and lipidomics research and interpreting the data generated				3	75	75	H	H	H	L	H	H	L	L	H	H	H	H	H	H	H
CLO-6:	Analyze high throughput data using software				3	70	75	H	H	L	H	L	L	H	M	M	H	H	M	H	H	H

Duration (hour)	9	9	9	9	9
S-1	SLO-1	History of technology advancement in biology	Introduction to Genome	Browser and databases for transcriptomics	Introduction to proteomics
	SLO-2	What is high throughput biology	Ultrafine structure of gene	Tools for transcriptomics	Analytical Techniques in proteomics
S-2	SLO-1	High content screening and their uses	Regulatory Landscapes of Mammalian Genomes	Search for transcription factor binding sites	Protein information databases
	SLO-2	High throughput screening in biology	Epigenetic Landscapes of Mammalian Genomes	miRNA targets and regulatory motifs	SwissPROT and UNIPROT
S-3	SLO-1	Technology characteristics of high throughput screening	Genome sequencing	Overview of Non-Coding RNAs	Mass spectrometry
	SLO-2	Recent theories on High throughput screening	Genome assembly and annotation	iCLIP	ESI MS-MS
S-4	SLO-1	How high throughput technologies empower the stake holders	Application of population genetics in genomics	Expressed Sequence Tag(EST) anlysis	Mass spectrometry ESI MALDI-TOF
	SLO-2	Real world applications	Important principles in population genomics	Serial Analysis of Gene Expression (SAGE)	Peptide mass finger printing database
S-5	SLO-1	Scalability of High through put screening	Comparative genomics of prokaryotes	Ribosome Profiling for ribosome-protected mRNA fragments	Targeted Mass spectrometry -Principles
	SLO-2	Evolvability of High through put screening	Comparative genomics of eukaryotes	What are RNA motifs and their relevance	Targeted Mass spectrometry -Applications
S-6	SLO-1	Exploring and replicating published research work	Functional genomics of prokaryotes	Experimental techniques 1- Micro array	Functional mass spectrometry principles
	SLO-2	Reviews and their uses	Functional genomics of eukaryotes	2. RT-PCR as a validating tool	Functional mass spectrometry applications
S-7	SLO-1	Need of open source research	Ecological genomics (Metagenomics) of microbes	Importance of reference gene	Overview of protein quantitation methods
					Experimental methods for lipid extraction

	SLO-2	Power of open source research	Ecological genomics (Metagenomics) higher organisms	Analysis of differential gene expression	Quantitation of proteins using MS	Lipid assays
S-8	SLO-1	Comparison of available data quality	Pharmacokinetics basics	Generation of transcriptional regulatory networks	Post translational modification of proteins	Lipid detection techniques
	SLO-2	Comparison of methods for published data	Pharmacogenomics	Analysis of transcriptional regulatory networks	Analysis of post translational modification of proteins using MS	Lipid based imaging techniques
S-9	SLO-1	'OMICS' technologies	Application of genomics in public health	Genetic screens for protein network	Protein – Protein interactions	Lipid based disorders
	SLO-2	Current status of OMICS technologies	Application of genomics in industry	Understanding signaling pathways	Interactomics	Lipidomic profiling

Learning Resources	<ol style="list-style-type: none"> 1. <i>High-Throughput Next Generation Sequencing Methods and Applications</i>, Kwon, Young Min, Ricke, Steven C. (Eds.), Humana press, 2011, UK 2. <i>Proteomics: from protein sequence to function</i>, Pennington, Stephen R.; Dunn, Michael J. 1st Edition, 2000, Oxford Publications, UK 3. <i>Text /Video: Genomics and Proteomics: Principles, Technologies, and Applications</i>, Devarajan Thangadurai (Editor), Jeyabalan Sangeetha(Editor), 1st edition, 2015, Apple academic press, New York, USA.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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Shalini M, , Scientist I, ITC Lifesciences PVT LTD Email: shalubioc@gmail.com	Dr. Nishad Fathima Principal scientist, CSIR-Central Leather Research Institute, Chennai Email: nishad.clri@gmail.com	Dr. P. Rathinasabapathi, SRMIST Email: rathinap1@srmist.edu.in

Course Code	18BTE422T	Course Name	METABOLIC ENGINEERING OF MICROBES	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	4

Pre-requisite Courses	18BTC103J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Biotechnology	Data Book / Codes/Standards			

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1: Develop metabolically engineered organisms and products		1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2: Use tools and methods used for metabolic engineering of microbes		Level of Thinking (Bloom)	Engineering Knowledge
CLR-3: Analyze regulatory mechanisms in metabolic pathways		Expected Proficiency (%)	Problem Analysis
CLR-4: Apply knowledge on design of a metabolic engineering in practice		Expected Attainment (%)	Design & Development
CLR-5: Analyze metabolic flux in biochemical pathways			Analysis, Design, Research
CLR-6: Study about thermodynamic principles of cellular processes			Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1: Discuss regulation of metabolic pathways		H 80 80	M H H H H H H H H H H H H H H
CLO-2: To gain insight into methods used for metabolic engineering		H 80 75	M H H H H H H H H H H H H H H
CLO-3: Develop plan and methods for metabolic engineering		H 75 75	M H H H H H H H H H H H H H H
CLO-4: Apply knowledge on tools and techniques used for metabolic engineering		H 75 75	M H H H H H H H H H H H H H H
CLO-5: To understand the product formation from metabolically engineered microbes		H 80 80	M H H H M M H H H H H H H H
CLO-6: Design pathway engineering techniques for diverting metabolic flux into product formation		H 80 80	M H H H H H H H M H H H H H H

Duration (hour)	10	10	10	10	10
S-1	SLO-1 Basic concepts of metabolic engineering	Overview of metabolic pathways in microbes	Metabolic engineering for enhancing product formation	Tools for metabolic engineering	Important aspects of metabolic engineering
	SLO-2 Importance of metabolic engineering	Regulation of metabolic pathways	Acetone production	Classical mutagenesis techniques	Metabolic pathway analysis
S-2	SLO-1 Overview of cellular metabolism	Enzyme mediated pathway regulation	Amino acid production	Methods for screening mutants	Metabolic flux analysis
	SLO-2 Energy generation pathways in microbes	Mechanisms of enzyme action	Engineering pentose metabolism	Gene shuffling methods	Metabolic flux control
S-3	SLO-1 Anaplerotic reactions	Transcriptional control of enzyme activity	Starch and lignin degradation	Gene knockout using CRISPR	Methods to calculate metabolic flux
	SLO-2 Rate constants and reaction equilibrium	Enzyme turnover	Vitamin production	Cloning and expression of gene clusters	Metabolic component analysis
S-4	SLO-1 Fuelling reactions – glycolysis	Enzyme activity by translational control	Polyketide biosynthesis	Antisense RNA based methods	Linear pathway analysis
	SLO-2 Fermentation pathways	Reversible inhibition	Biopolymer production	Directed evolution for improving protein function	Branched pathway analysis
S-5	SLO-1 Catabolism of fats and amino acids	Irreversible inhibition	Production of novel compounds using metabolic engineering	Artificial chromosomes	Structure of a metabolic network
	SLO-2 Biosynthetic of polymers	Global regulation of metabolic pathways	Antibiotics and vitamins	Chromosomal engineering strategies	Flux distribution
S-6	SLO-1 Nucleic acid biosynthesis	Allosteric enzymes involved in metabolic regulation	Production of pigments	RNA engineering technologies	Flux analysis of metabolic networks
	SLO-2 Amino acid biosynthesis	Regulation of enzyme activity using feedback mechanism	Biopolymer production	Improving translational efficiency	Determination of Group Control Coefficient
S-7	SLO-1 Active transport	Sigmoidal kinetics	Pesticide degradation	Stimulation of product formation using precursor molecules	Thermodynamics of cellular processes
	SLO-2 Facilitated diffusion	Allosteric regulation of enzyme activity	Xenobiotic degradation	Multifunctional enzyme systems	Thermodynamic feasibility

S-8	SLO-1	Cellular energetics,	Co-operativity of allosteric enzymes	Metabolic engineering of mammalian cells	Engineering of secretory processing pathway	Metabolic models for growth
	SLO-2	yield coefficients	Examples of enzyme cooperativity	Cell cycle engineering	Phenotype microarrays	Models for product formation
S-9	SLO-1	Primary metabolite production	Branch point classification	Apoptosis control	HighThroughput Mutagenesis	Genome scale modeling of cellular metabolism
	SLO-2	Secondary metabolite production	Coupled reactions	Inhibition of cell proliferation	High Throughput screening	Cell free systems for metabolic engineering

Learning Resources	<ol style="list-style-type: none"> Gregory N. Stephanopoulos, Aristous A. Aristoudou, Jens Neilsen, <i>Metabolic engineering – Principles and methodologies</i>, Academic press, (1998) Quiong Chen – <i>Microbial Metabolic Engineering – Methods and protocols – first edition – Humana Press</i> (2011) Christina Smoke – <i>Metabolic Engineering Pathway Handbook – 2nd edition, CRC press</i> (2017)
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SLO – Session Learning Outcome

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1 Dr. Rajeev Kumar Sukumaran, NIIST, Trivandrum rajeevs@niist.res.in	1 Dr. Guhan Jayaraman IIT, Madras, guhanj@iitm.ac.in	1 Dr. K. N. Rajnish SRM Inst. of Science & Technology
2. Dr. N. Ayyadurai, CLRI, Adyar, ayyadurai@clri.res.in	2 Dr. S. Ramalingam, Anna University, Chennai rama@bioprocess.edu	2 Dr. M. Ramya SRM Inst. of Science & Technology

Course Code	18BTE423T	Course Name	GENETICS OF CROP IMPROVEMENT	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18BTC105J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Genetic Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		Learning			Program Learning Outcomes (PLO)														
		1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-1: Identify the important attributes that demonstrate high yield potential																			
CLR-2: Understanding the factors that control crop productivity.																			
CLR-3: Analyze Biotic and abiotic stress-plant interactions																			
CLR-4: Explore plant-microbe beneficial interactions																			
CLR-5: Analyze metabolic pathways for crop value addition																			
CLR-6: compare, contrast and distinguish the right molecular strategies for crop improvement																			
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																	
CLO-1: Explain the genetic basis of crop productivity		1	85	75															
CLO-2: Analyze the tools for crop improvement		2	90	80															
CLO-3: Develop tolerance against abiotic stress		2	75	65															
CLO-4: Develop tolerance against biotic stress		2	75	65															
CLO-5: Analyze pathways to engineer value addition		3	70	60															
CLO-6: Develop elite cultivars		3	70	60															

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Traditional breeding	Pest tolerance and agriculture sustainability	Abiotic stress and agriculture sustainability	Photosynthetic efficiency
	SLO-2	Methods of breeding	Pathogens and insect pests	Major abiotic stresses	Regulation of photosynthesis
S-2	SLO-1	Marker assisted breeding	Genetics of host-pathogen interactions	Biochemical basis of abiotic stresses	C3, C4, and CAM
	SLO-2	Methods to generate markers	signal transduction	signal transduction	Molecular control of photosynthesis
S-3	SLO-1	Mutation breeding	Virulence- Avirulence in host-pathogens interaction	drought, salinity	Biological Nitrogen Fixation
	SLO-2	Steps in mutation breeding	Molecular mechanism of virulence	Regulation of drought response	Molecular regulation of N fixation
S-4	SLO-1	transgenic technology	Molecular strategies of pathogen tolerance	Temperature	Molecular basis of N fixation
	SLO-2	Over expression and knock outs	Approaches against fungal pathogens	Regulation of temperature response	Enzymes involved in N fixation
S-5	SLO-1	Loss of /Gain of function mutants	Approaches against bacterial pathogens	Stress signal transduction	Hormonal in plant growth and development
	SLO-2	Genetic screens	Insect pest resistance	Key transcriptional factors in stress response	Plant Growth Promoting bacteria
S-6	SLO-1	RNAi	Molecular strategies of insect pest tolerance	Reactive oxygen species	Phosphorus Solubilizing/Mobilizing bacteria
	SLO-2	Genome editing	Biological control of insect pests	Regulation of ROS	Molecular basis of P mobilization
S-7	SLO-1	Zinc finger	multi-gene pyramiding	Molecular strategies for tolerance against abiotic stress	Sucrose as a signaling molecule
	SLO-2	TALEN	Pathogenesis related proteins	calcium, nitric oxide and salicylic acid in plant defence	Vesicular Arbuscular Mycorrhiza
S-8	SLO-1	CRISPR/Cas	Virus resistance	synthesis and functions of proline	Microbes that mimics stress response
	SLO-2	CRISPR/Cas mechanism	Strategies of virus resistance	synthesis and functions of glycine betaine in stress tolerance	Nutrient translocation
S-9	SLO-1	GMO	Molecular methods to generate virus resistance	Role of hormones in stress response	Applications of plant – beneficial microbe association
	SLO-2	Regulation and Monitoring GM	Applications of genetic engineering in pest tolerance	Applications of genetic engineering in abiotic stress tolerance	Genetic engineering approaches to enhance plant growth and development

Learning Resources	1. S. Mohan Jain and D.S. Brar <i>Molecular Techniques in Crop Improvement</i> 2 nd edition. 2010 Springer. ISBN 978-90-481-2966-9 e-ISBN 978-90-481-2967-6
	2. Khalid Rehman Hakeem and Parvaiz Ahmad Munir Ozturk. 2013. Springer. <i>Crop Improvement New Approaches and Modern Techniques</i> . ISBN 978-1-4614-7027-4 ISBN 978-1-4614-7028-1

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Dr. Florida Tilton, Biozone Research Technologies Pvt, Ltd, Chennai (floridatilton@gmail.com)	Dr. Ravindran, TNAU, Coimbatore, TN – (sivakasiravi@yahoo.com)	Dr. D. Rex Arunraj, SRM IST
2. Dr. N. Ayyadurai, CLRI, Adyar, ayyadurai@clri.res.in	Dr. Gopalakrishnan, IARI New Delhi – (krish.icar@gmail.com)	2 Dr. M. Ramya, SRM Inst. of Science & Technology

Course Code	18BTE424T	Course Name	MOLECULAR BIOLOGY OF INFECTIOUS DISEASES	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18BTC103J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Biotechnology	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1:	State the basics of infectious diseases	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Discuss molecular pathogenesis of bacterial diseases	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3:	Discuss molecular pathogenesis of viral diseases																		
CLR-4:	Explain molecular pathogenesis of parasitic and fungal diseases																		
CLR-5:	Illustrate the molecular pathogenesis of fungal pathogens																		
CLR-6:	Recognize defense mechanisms of infectious microbes																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1:	Describe the basics of molecular pathology of various infectious diseases	1	80	75	M	M	M	M	H	H	H	H	M	L	L	H	H	H	H
CLO-2:	Investigate the molecular pathogenesis of bacterial pathogens	2	80	70	M	M	M	M	H	H	H	M	M	L	L	H	H	H	H
CLO-3:	Investigate the molecular pathogenesis of viral pathogens	2	80	75	M	M	M	M	H	H	H	M	M	L	L	H	H	H	H
CLO-4:	Examine the molecular pathogenesis of parasitic diseases	2	80	70	M	M	M	M	H	H	H	M	M	L	L	H	H	H	M
CLO-5:	Explain the molecular pathogenesis of fungal infections	2	85	75	M	M	M	M	H	H	H	M	M	L	M	H	H	H	H
CLO-6:	Recall the defense mechanisms of infectious microbes	3	90	80	M	M	M	M	H	H	H	M	M	L	M	H	H	H	H

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Historical perspective of infectious diseases	Morphology, pathogenicity of Cholera	Morphology, pathogenicity of HIV	Morphology and lifecycle of Malaria
	SLO-2	Disease outbreak	Molecular biology of Cholera	Molecular biology of AIDS virus	Molecular biology of Malaria
S-2	SLO-1	Microbial Toxins	Morphology, pathogenicity of Tuberculosis	Morphology and lifecycle of Dengue	Morphology and lifecycle of Wuchereria bancrofti
	SLO-2	Types of microbial toxins	Molecular biology of Tuberculosis	Molecular biology of Dengue	Molecular biology of Filariasis
S-3	SLO-1	Toxin assays	Enteric fever causes	Morphology, pathogenicity of Rabies virus	Morphology, transmission, pathogenesis of Leptospirosis
	SLO-2	Toxin genes	Molecular biology of Enteric Fever	Molecular biology of Rabies	Molecular biology of Leptospirosis
S-4	SLO-1	Water borne pathogens	Morphology and pathogenesis of Shigella	Structure and pathogenesis of Hepatitis virus	Morphology, pathogenicity of Treponema pallidum
	SLO-2	Air borne Pathogens	Bacterial signals and cell responses during Shigella entry into epithelial cells	Molecular biology of Hepatitis	Molecular biology of Syphilis
S-5	SLO-1	Soil borne pathogens	Insights into biology of Typhoid Toxin	Pathogenesis of papilloma virus	Fungal pathogens
	SLO-2	Pathogens transmitted via animals	Serovars of Salmonella	Molecular biology of cervical cancer	Molecular biology of Aspergillosis
S-6	SLO-1	Mode of Entry of pathogens	Genetic and Molecular aspects of Helicobacter pylori	Morphology and pathogenesis of Flu virus	Causes of Athletes foot
	SLO-2	Initiation of diseases	Molecular biology of Gastric ulcer	Molecular biology of Flu virus	Molecular biology of Athletes foot
S-7	SLO-1	General disease symptoms - External	Morphology and pathogenesis of botulism	Morphology and pathogenesis of Polio virus	Morphology, transmission, pathogenesis of Trypanosomia
	SLO-2	Disease symptoms - Internal	Mode of action of botulism toxin	Molecular biology of Polio virus	Molecular biology of Sleeping sickness
S-8	SLO-1	Virulence factors – Cell bound	Morphological identification methods	Genetic screens to understand signaling pathways	Molecular biology of Amoebiasis
	SLO-2	Virulence factors - secreted	Culture based identification methods	Virus culturing	Molecular biology of Candidiasis
S-9	SLO-1	Virulence associated Genes	Serologic diagnostic methods of bacterial diseases	Serologic diagnostic methods of viral diseases	Serologic diagnostic methods of parasitic diseases
	SLO-2	Plasmid borne virulence associated genes	Molecular diagnostic methods of bacterial diseases	Molecular diagnostic methods of viral diseases	Molecular diagnostic methods of parasitic diseases

Learning Resources	<ol style="list-style-type: none"> 1. Peter Williams, Julian Ketley & George Salmond, "Methods in Microbiology: Bacterial Pathogenesis, Vol. 27", Academic Press, 1998. 2. Rajan.R., "Medical Microbiology", MJP Publishers, 1st edition, 2007.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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Course Code	18BTE425T	Course Name	MOLECULAR DIAGNOSTICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Biotechnology	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Explain hybridization based methods for diagnosis of genetic diseases	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2 :	Discuss PCR based diagnosis	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3		
CLR-3 :	Discuss diagnosis by DNA Sequencing				M	H	H	H	H	L	M	H	H	H	H	H	H	H	H	H	H
CLR-4 :	Explain about nucleic acid based diagnosis of infectious diseases				H	H	H	H	H	M	M	H	H	H	H	H	H	H	H	H	H
CLR-5 :	Discuss immunological diagnosis of infectious diseases				M	H	M	H	H	M	M	H	H	L	H	H	H	H	H	H	H
CLR-6 :	Explain molecular methods for molecular diagnostics				H	H	H	H	H	M	H	L	H	H	H	H	H	H	H	H	H
					H	H	H	H	M	M	H	H	H	L	H	H	H	H	H	H	H
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																				
CLO-1 :	Employ hybridization based methods for diagnosis of genetic diseases	2	75	70																	
CLO-2 :	Apply PCR based diagnosis	3	80	75																	
CLO-3 :	Design diagnostic method by DNA Sequencing	3	85	80																	
CLO-4 :	Apply nucleic acid based diagnosis of infectious diseases	2	80	75																	
CLO-5 :	Employ immunological diagnosis of infectious diseases	3	85	75																	
CLO-6 :	Analyze genetic and infectious diseases through molecular methods	2	80	75																	

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Introduction to FISH	Introduction to PCR based diagnostics	Basics of DNA sequencing	Ribotyping
	SLO-2	Types of FISH	End-point PCR	Mutation detection by sequencing	Applications of Ribotyping
S-2	SLO-1	Interphase FISH	ARMS PCR based diagnostics	Genome wide association studies	Pulse Field Gel Electrophoresis
	SLO-2	Metaphase FISH,	Allele specific PCR	Application in Health care	Application of PFGE
S-3	SLO-1	Principles of Multicolor FISH	Restriction fragment length polymorphism (RFLP)	Next generation sequencing	Multiplex PCR for virulence factor detection
	SLO-2	Multicolor FISH	Mutation detection using RFLP	Application in disease diagnosis	Application and limitations
S-4	SLO-1	Application of FISH	Multiplex PCR	Clinical exome sequencing	Recombinase polymerase amplification (RPA) assay
	SLO-2	Limitations of FISH	Applications of multiplex PCR	Application in Health care	Application and limitations
S-5	SLO-1	Principles of genomic hybridization	LAMP PCR	Linkage analysis	Sequencing for multidrug resistant markers
	SLO-2	Comparative genomic hybridization	LAMP PCR for Molecular diagnosis	Linkage analysis for disease diagnosis	Applications and limitations
S-6	SLO-1	Introduction to DNA chips and Micro-arrays	Multiplex ligation probe dependent amplification (MLPA)	Marfan syndrome: Disease gene identification	DNA chips: Principle and method
	SLO-2	Diagnostics based on DNA chips and Micro-arrays	MLPA in disease diagnosis	Case study: Marfan syndrome	Gene chips for mutation screening in virulence genes
S-7	SLO-1	Down syndrome	Real time PCR	Cystic fibrosis	Case study: MRSA,
					Case study: Flu virus

	SLO-2	Case study: Diagnosis of Down syndrome	Application in diagnosis	Case study: cystic fibrosis	Diagnosis of MRSA	Diagnosis of Flu Virus
S-8	SLO-1	Digeorge syndrome	Sickel cell anaemia	Molecular aspects of diabetes	Case study: Vibrio cholerae	Case study: Dengue
	SLO-2	Case study: Diagnosis of Digeorge syndrome	Case study: Diagnosis of Sickel cell anaemia	Case study: Diagnosis of diabetes	Diagnosis of Vibrio cholerae	Diagnosis of Dengue virus
S-9	SLO-1	Childhood leukemia	Duchenne muscular dystrophy	Dibetes: Disease gene identification	Case study: Acinetobacter boumannii	Case study: chikungunya
	SLO-2	Case study: Diagnosis of Childhood leukemia	Case study: Diagnosis of Duchenne muscular dystrophy	Clinical application of dibetes gene identification	Diagnosis of Acinetobacter boumannii	Diagnosis of chikungunya

Learning Resources	1. Gersen, Keagle, "The Principles of Clinical Cytogenetics" 3 rd edition - Springer-Verlag, Inc., 2013. 2. Donnai, Read, "New Clinical Genetics" 3 rd edition – Scion, Inc., 2015. 3. Tang, Statton, "Advanced Techniques in Diagnostic Microbiology" Springer, Inc., 2013
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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Course Code	18BTE426T	Course Name	GENE THERAPY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18BTC105J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Biotechnology	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1:	Provide basic knowledge on gene therapy and its importance.	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Identify an interest to know about the different types of gene therapy, its applications for diseases.	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3:	Develop awareness about the different methods of gene delivery and provide knowledge on vectors.																		
CLR-4:	Initiate interest on latest techniques in genome editing and understand its applications.																		
CLR-5:	Develop interest on applications and uses of gene therapy in treatment of disease.																		
CLR-6:	Prepare engineering students to know the recent advancements in gene therapy.																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1:	Apply knowledge about gene therapy in treating diseases.	1	80	70	-	-	H	M	-	M	H	-	H	-	H	H	H	H	H
CLO-2:	Practice knowledge on different types of gene therapy and its applications.	2	85	75	-	-	H	M	-	M	H	-	H	-	H	H	H	H	H
CLO-3:	Interpret knowledge on construction of viral vectors and usage of non-viral vectors to correct the genetic defect.	2	80	70	H	-	H	M	-	M	H	-	H	-	H	H	H	H	H
CLO-4:	Use molecular aspects involved in genome editing in gene therapy.	2	80	75	H	-	H	M	-	M	H	-	H	-	H	H	H	H	H
CLO-5:	Evaluate treatment of diseases addressed by gene therapy clinical trials.	3	80	70	H	-	H	M	-	M	H	-	H	-	H	H	H	H	H
CLO-6:	Analyze recent advancements in gene therapy.	2	80	70	H	-	H	M	-	M	H	-	H	-	H	H	H	H	H

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Introduction to Gene therapy	Embryo somatic gene therapy - Reproductive cloning	Gene delivery-An overview	Genome editing-Genes Targeting
	SLO-2	Genes as drugs	Embryo somatic gene therapy - Therapeutic cloning	Methods of gene delivery	Genome editing Processes-Double strand break repair
S-2	SLO-1	Gene therapy – overview	Preimplantation genetic diagnosis-History, Indications and applications	Direct Inoculation of DNAs	Engineered Nucleases
	SLO-2	History of Gene Therapy	Preimplantation genetic diagnosis – Techniques and ethical issues	Direct Inoculation of RNAs	Meganucleases
S-3	SLO-1	Types of gene therapy-somatic	Prenatal/ fetal gene therapy – Concepts and methods	Non-viral methods-Physical methods	Zinc Finger Nucleases
	SLO-2	Types of gene therapy- germ line	Prenatal/fetal gene therapy with case study –Tay Sach's disease	Non-viral methods-Chemical methods	ZNFs as gene editing tools
S-4	SLO-1	Methods of gene therapy-Ex vivo	Postnatal somatic gene therapy	Viral Vectors - Retroviral vectors-Structure	TALENs as gene editing tools
	SLO-2	Methods of gene therapy- In-vivo	Germline gene therapy	Retroviral vectors- Mechanism and action Adenoviral vectors-Structure, Mechanism	CRISPR/Cas9 as gene editing tools-Introduction and Mechanism
S-5	SLO-1	Vectors for gene therapy-viral	Methods of Germline gene therapy	Adenoviral vectors-Structure, Mechanism	CRISPR/Cas9 as gene editing tools-Applications
	SLO-2	Vectors for gene therapy-non-viral	Germline gene therapy-Drawbacks	Adenoviral vectors- Advantages and disadvantages	Precision and efficiency of engineered nucleases
S-6	SLO-1	Diseases with dominant heredity	Suicide gene therapy – Current strategies	Adeno associated viral vectors-Structure, Mechanism	Multiplex automated Genome engineering
					Stem cells in gene therapy-gene therapy of hematopoietic stem cells
					Major Applications Procedures for Gene Transfer into Hematopoietic Stem Cells
					Treatment of genetic diseases - gene therapy of cancer- Gene Therapy of Cancer Using Suicide Genes
					Immunotherapy of Cancer
					Treatment of genetic diseases - neurodegenerative disorders- Gene Therapy of Alzheimer's Disease
					Treatment of genetic diseases - neurodegenerative disorders- Gene Therapy of Parkinson's Disease
					Gene Therapy of Huntington's Disease
					Gene Therapy of Spinal Muscular Dystrophy
					Gene Treatment of genetic diseases - Retinal Photo transduction and the Visual Cycle
					Gene Treatment of genetic diseases - Congenital Retinal degenerations
					Gene Therapy of Retinal Neovascularization and Retinoblastoma

	SLO-2	Diseases with recessive heredity	Suicide gene therapy for Cancer	Adeno associated viral vectors-Advantages and disadvantages	Types of therapeutic genome modifications- Gene disruption	Treatment of genetic diseases - cardiovascular disorders-
S-7	SLO-1	Ex vivo gene therapy with case study-SCID (Causes)	Secretion gene therapy	Herpes simplex viral vectors –Structure	Types of therapeutic genome modifications- Non homologous end joining - NHEJ gene correction	Gene Therapy of Heart Failure
	SLO-2	Ex vivo gene therapy with case study-SCID (Treatment)	Immunotherapy	Herpes simplex viral vectors – Mechanism and Action	Types of therapeutic genome modifications- Non homologous end joining - NHEJ gene addition	Therapeutic Angiogenesis
S-8	SLO-1	In vivo gene therapy with case study- Cystic fibrosis (Causes)	Gene therapy for infectious diseases- Nucleic acid-based gene therapy (Antisense DNA and RNA, Ribozymes, RNA decoys)	Envelope protein pseudo typing of viral vectors	Types of therapeutic genome modifications - Homology directed repair - HDR gene correction	Gene therapy of HIV infection - Natural History of HIV-1 Infection
	SLO-2	In vivo gene therapy with case study- Cystic fibrosis (Treatment)	Protein- based assays for gene therapy	Replication-competent vectors	Types of therapeutic genome modifications - Homology directed repair - HDR gene addition	General Considerations Gene Therapy of HIV Infection by Intracellular Immunization
S-9	SLO-1	Ethical problems in gene therapy	Target pathogens for antimicrobial gene therapy	Cis and trans-acting elements	Applications of Genome editing	Therapy of HIV Infection by Immunotherapy
	SLO-2	Social problems in gene therapy	Examples of clinical trials for infectious diseases	Hybrid vectors	Prospects and limitations of Genome editing	Recent advances in gene therapy

Learning Resources	1. Evelyn B. Kelly, "Gene Therapy", Greenwood Press, 2007. 2. Mauro Giacca, "Gene Therapy", Springer Milan, 2010. 3. Peter J. Quesenberry, "Stem cell biology and gene therapy", John Wiley & Sons, 2002.	4. Roland W. Herzog, "A Guide to Human Gene Therapy", World Scientific Publishing Co Pvt. Ltd. 2010. 5. David Benjamin Turitz Cox et al "Therapeutic genome editing: prospects and challenges" Nature Medicine, Vol 21(2): 121- 131, 2015.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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Dr.Sudha Warriar, Associate Professor, Manipal University, Manipal, School of Regenerative Medicine, sudha.warrier@manipal.edu	Dr. B.S.Lakshmi, Associate Professor, Anna University lakshmibs@annauniv.edu	Dr.Swapna Geetanjali A, SRMIST swapnaga@smist.edu.in

Course Code	18BTE427T	Course Name	FUNCTIONAL GENOMICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Biotechnology	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 : <i>Analyze the genome structure, organization and function across life.</i>		Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2 : <i>Analyze about the comparative genomics of organelles and nuclear genomes across life</i>					Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3					
CLR-3 : <i>Apply different classical methods to study gene expression and whole transcriptome</i>																								
CLR-4 : <i>Compare various NGS techniques to study genome, exome, and transcriptomes.</i>																								
CLR-5 : <i>Infer the basics of metabolic pathways, transcription factors and genome editing.</i>																								
CLR-6 : <i>Analyze the applications of functional genomics in various sectors.</i>																								
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1 : <i>Describe the basics of genome organization across life and study of gene function</i>		1	75	80	M	H	H	H	H						H			H	H	H	H	H		
CLO-2 : <i>Describe the genomics of organelle and nuclear genomes across life</i>		1	75	80	M	H	H	H	H						H			H	H	H	H	H		
CLO-3 : <i>Review the organization of transcriptome and classical methods to study gene expression</i>		2	70	80	M	H	H	H	H						H			H	H	H	H	H		
CLO-4 : <i>Describe about traditional and Next Generation Sequencing (NGS)platforms for the study of genome, exome and transcriptome</i>		2	60	75	H	H	H	H	H					H	H			H	H	H	H	H		
CLO-5 : <i>Describe about genes for metabolic pathways, transcription factors, genome editing.</i>		3	70	80	M	H	H	H	H					H	H			H	H	H	H	H		
CLO-6 : <i>Summarize the applications of functional genomics in various sectors.</i>		3	60	80	M	H	H	H	H				H	H	H			H	H	H	H	H		

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Genome organization in Eukaryotes	Genome size, gene content	Transcriptome from Eukaryotes	DNA Sequencing	Study of Gene functions
	SLO-2 Structural level organization	Gene order	Transcriptome from prokaryotes	Sanger method of DNA Sequencing	Metabolic pathways-KEGG
S-2	SLO-1 Genome organization in Eukaryotes	Orthologs	Gene expression studies with mRNA	Automated DNA Sequencing	Transcription factors
	SLO-2 Sequence level organization	Paralogs	Gene expression studies with other RNAs	Next Generation Sequencing (NGS)	Signaling cascades controlled by Transcription factors
S-3	SLO-1 Genome organization in Prokaryotes	Comparative genomics	Classical methods to study gene expression	Principle and methodology of NGS Platforms	Genome editing
	SLO-2 Sequence level organization	Comparative genomics of bacteria	Northern hybridization	Principle and methodology of NGS Platforms	Targeted genome Editing
S-4	SLO-1 Genetic elements and their organization in Eukaryotes	Pangenome-metagenomics	Differential Display PCR	Third Generation Sequencing methods	Tools for genome editing
	SLO-2 Genetic elements and regulation of gene expression in eukaryotes	Microbiome	Serial Analysis of Gene Expression (SAGE)	Comparison of high-throughput sequencing methods and applications	CRISPR/cas9 genome editing
S-5	SLO-1 Genetic elements and their organization in prokaryotes	Horizontal gene transfer	Reverse transcriptase PCR (RT-PCR) to study gene expression	Genome sequencing	Genetic variations and diseases
	SLO-2 Genetic elements and regulation on gene expression in Prokaryotes	Organelle genomes	Methodology of RT-PCR	Genome assembly	Tools to study mendelian diseases
S-6	SLO-1 Forward genetics	Methods to study organelle genomes	Quantitative PCR (real time) to study gene expression	Gene Prediction	Genomics of monogenic disorders
	SLO-2 Classical Forward genetics	Comparative genomics of mitochondrial genomes	Methodology of realtime-PCR	High-throughput RNA sequencing	Genomics of polygenic disorders
S-7	SLO-1 Functional genomic analysis with Forward genetics	Comparative genomics of plastid genomes	High-throughput methods to study gene expression	RNA sequencing to study genome wide gene expression	Genomics in Diagnostics
	SLO-2 Methods in Forward genetics	Nuclear genomes	Study of Gene expression using Microarray	Differential gene expression analysis with RNAseq	Population genetics

S-8	SLO-1	Reverse Genetics	Comparative genomics of nuclear genomes	Principle of Microarray	Small RNA sequencing	Evolutionary genetics
	SLO-2	Functional genomic analysis with reverse genetics	Plant genomes	Methodology of Microarray	Targeted sequencing	Applications of functional genomics in agriculture
S-9	SLO-1	Classical Methods in Reverse genetics	Animal genomes	Study of splice variants	Exome sequencing	Applications of functional genomics in healthcare
	SLO-2	Current methods in Forward and reverse genetics	Comparison of plant and animal genomes	Correlation of mRNA and protein abundance	Amplicon sequencing	Applications of functional genomics in prokaryotes

Learning Resources	1. Pevsner. J., "Bioinformatics and Functional Genomics", 3rd edition, Wiley-Blackwell. 2015. 2. Mount. D., "Bioinformatics: Sequence and Genome Analysis", 2nd Edition, Cold Spring Harbor Laboratory Press, New York. 2004. 3. Primrose. S.B., Twayman. R.M., "Principles of Gene Manipulation and Genomics" 7th edition, Blackwell publishing. 2006.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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Course Code	18BTE428T	Course Name	PLANT INTERACTIONS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18BTC108J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Biotechnology	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Relate the signaling mechanisms in the development of a plant's root, shoot, leaf and flower	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Discuss the response of plants to physical stimuli and day-night cycle (circadian rhythm)				Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Explain the mechanisms in plant-microbe interaction, biotic and abiotic stresses				M	H		M	M	M	M	H		H	H	H	H	H	H
CLR-4 :	Discuss about hyperaccumulators, heavy metal tolerance and phytoremediation				M	H		H	H	H	H	H		H	H	H	H	H	H
CLR-5 :	Relate the role of phytochemicals in plants behavior and in facilitating plants growth				M	H	H	H	H	H	H	H		H	H	H	H	H	H
CLR-6 :	Recognize the efforts taken by sessile plants for their survival and avoidance of stress.				M	H	H	H	H	H	H	H	M	H	H	H	H	H	H
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)															
CLO-1 :	Describe the perception and responses of plants to environmental stimuli and stress cues	2	85	80	M	H		M	M	M	M	H		H	H	H	H	H	H
CLO-2 :	Design transgenic plants (GMOs) for biotic and abiotic stress tolerance	3	85	80	M	H		H	H	H	H	H	M	H	H	H	H	H	H
CLO-3 :	Exploit light response plasticity for improved productivity	3	80	75	M	H	H	H	H	H	H	H		H	H	H	H	H	H
CLO-4 :	Demonstrate how plants compete with themselves and other plants for nutrients and sunlight	2	75	70	M	H	H	H	H	H	H	H		H	H	H	H	H	H
CLO-5 :	Examine the benefits of intercropping and crop rotation	2	80	75	M	H	H	H	H	H	H	H	M	H	H	H	H	H	H
CLO-6 :	Recall what a plant does in the course of its lifetime for better growth and productivity	3	80	75	M	H	H	H	H	H	H	H	M	H	H	H	H	H	H

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Development biology of plants-an overview	Plant response to physical and light stimuli-an overview	Plant-microbe interaction-an overview	Plant adaptation to abiotic stresses-An overview	Plant-plant interactions
	SLO-2 Signal transduction using G proteins Calcium, MAPK	Response to gravity-gravitropism	Plant growth promoting rhizobacterium	Physiological and molecular response of plant to drought	Plant plasticity
S-2	SLO-1 One-component sensor regulatory system	Response to touch-thigmotropism	Root exudates	Physiological response to salinity	Allelopathy, secondary metabolites
	SLO-2 Two-component sensor regulatory system	Thigmotropism in shoots	Types of root exudates	Molecular mechanisms in salt tolerance	Volatiles
S-3	SLO-1 Stages of embryogenesis	Plant herbivory	Microbial secretions	Physiological response to cold	Plant's competitive behavior
	SLO-2 Genes in embryogenesis	Chemical and mechanical defenses	Microbe secreted plant hormones	Molecular mechanisms in cold tolerance	Behaviour based on memory
S-4	SLO-1 Plant growth hormones-auxin, cytokinin and gibberellin	Response to light-Phototropism	Quorum sensing	Physiological response to water logging	Co-operative behavior
	SLO-2 Ethylene and abscisic acid	Five models of auxin distribution in phototropism	Plant-microbe interaction	Molecular response to water logging	Facilitative behaviour
S-5	SLO-1 Anatomy of shoot apical meristem	Phytochromes-structure	Biofilm formation of PGPR	Physiological response to heat	Below ground competition
	SLO-2 Genes in the development of shoot apical meristem	Function of phytochromes	Biofilm visualization-confocal imaging	Molecular response to heat tolerance	Kith and Kin recognition
S-6	SLO-1 Structure of root apical meristem	Cryptochromes-structure	Phytopathogens	Physiological response to heavy metals	Alien recognition
	SLO-2 Genes in the development of root apical meristem	Function of cryptochromes	Phytopathogens of rice, wheat, tomato, onion, spinach	Genes involved in heavy metal accumulation, tolerance and resistance	Siblings recognition
S-7	SLO-1 Parts of a monoecious and dioecious flower	Circadian clock	Plant immunity	Hyperaccumulators	Shoot competition
	SLO-2 ABC model for flowering-florigenesis	Molecular mechanisms of light perception	Physical barriers	Phytoremediation	Root competition
S-8	SLO-1 Natural fertilization	TOC1, LHY and CCA genes	Systemic acquired resistance (SAR)	Phenotypic plasticity	Shade avoidance
	SLO-2 Artificial fertilization-apomixis and parthenocarp	Model of circadian clock in Arabidopsis	Hormones in SAR	Root plasticity	Effect of phytochromes

S-9	SLO-1	<i>Hormones in seed dormancy</i>	<i>Short day plants</i>	<i>Induced systemic resistance (ISR)</i>	<i>Soil physical constraints</i>	<i>Neighbor signaling as a warning to biotic stresses</i>
	SLO-2	<i>Hormones in seed germination</i>	<i>Long day plants</i>	<i>Hormones in ISR</i>	<i>Plant growth in non-conductive soil</i>	<i>Neighbor signaling as a warning to abiotic stresses</i>

Learning Resources	1. <i>Plant Environment Interactions, Second edition, by Robert E. Wilkinson., Marcel Dekker, Inc., 2000.</i> 2. <i>Principles of plant microbe interactions, by Ben Lugtenberg, Springer, 2015.</i>
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
<i>Dr. P. Sadasivam, Scientist, Du Pont Industrial biosciences, Hyderabad sadha_pbg@yahoo.co.in</i>	<i>Dr. Sivaprakash Ramalingam, Scientist, IGIB, New Delhi sivaprakash.ramalingam@gmail.com</i>	<i>Dr. B. Usha, Associate Professor, SRMIST sundaram.usha@gmail.com</i>
<i>Dr. M. Harikrishnan, Scientist, Pondicherry Biotech Pvt. Ltd, Pondicherry sriharish.m@gmail.com</i>	<i>Prof. Raveendran, Professor, TNAU, TamilNadu raveendrantnau@gmail.com</i>	<i>Dr. A. Swapna Geetanjali, Associate Professor, SRMIST swapna.geetanjali@gmail.com</i>

ACADEMIC CURRICULA

Professional Elective Courses

CHEMICAL ENGINEERING

Regulations - 2018



SRM INSTITUTE OF SCIENCE AND TECHNOLOGY

(Deemed to be University u/s 3 of UGC Act, 1956)

Kattankulathur, Kancheepuram, Tamil Nadu, India

Course Code	18CHE351T	Course Name	RENEWABLE ENERGY ENGINEERING	Course Category	E	Professional Electives	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Chemical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Understand the importance, availability of renewable energy	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Familiarize various aspects of wind energy		
CLR-3 :	Familiarize various aspects of equipment's used to collect solar energy and various applications of solar energy		
CLR-4 :	Familiarize various aspects of Biomass energy and utilization		
CLR-5 :	Other renewable energy resources and hydrogen energy, storage , transmission, fuel cell		
CLR-6 :	Expose to alternate energy		

Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:										Level of Thinking	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO -3
CLO-1 :	Energy supply and demand, need for renewable recourses	1	75	70	L	L	L				L									L						H	H		
CLO-2 :	Evaluate the types and design of windmill	2	85	75	H	H	H	M			L		L		L					L		L		L		H	H	H	
CLO-3 :	Know on various industrial Solar equipments for heat and electricity	2	80	75	H	M	M	M			L		L		L					L		L		L		H	H	H	
CLO-4 :	Energy from biomass and reactor design	2	80	75	H	M	H	M			L		L		L					L		L		L		L	H	H	
CLO-5 :	Wave energy, tidal energy ,OTEC, Geothermal, Hydrogen energy, storage, Fuel cell technology	2	80	75	M	L	L	L			L		L		L					L		L	L	L	L	L	H		
CLO-6 :	Evaluate various renewable energy options	2	75	60	H	M	L	H			H		H		H					H		H	H		M	M	M		

Duration (hour)	9	9	9	9	9
S-1	SLO-1 India's energy demand and supply,management	Availability of wind	Introduction on sun energy	Biomass, Biomass resources	Tidal energy
	SLO-2 Energy planning	Special features of wind energy	Solar angles	Composition, fuel properties	Tidal energy conversion
S-2	SLO-1 Energy needs for the future	Types of wind mills	Solar collectors	Biomass conversion technologies	Wave energy
	SLO-2 Regional prospects and stresses	The power from the wind	Types of collectors	Anaerobic digestion	Wave energy operation, applications
S-3	SLO-1 Status of global resources	Performance of wind mills	Flat plate and dish type	Direction combustion	OTEC
	SLO-2 India's renewable resources	Modern wind energy generators	Types of flat and dish types	Pyrolysis	Open and closed OTEC Cycles
S-4	SLO-1 Energy resources of India ,economic development,	Horizontal wind mills	Solar concentrators	Gasification	Geothermal energy
	SLO-2 Energy cropping	Vertical wind mills	Types of concentrators	Biogas technology,	Geothermal energy conversion
S-5	SLO-1 Energy conversion	Wind turbines	Solar pumping	Bioethanol	Energy operation, applications
	SLO-2 Energy storage	Design parameters	Problems in collectors	Biodiesel Production	Energy conversion
S-6	SLO-1 Advantages and Disadvantages of Non-Conventional source of energy	Design principles of wind turbine	Solar refrigeration	Community and institutional biogas plants	Hydro conversion
	SLO-2 Renewable energy resources	Horizontal and vertical axis types	Solar air cooling, Solar furnaces	Family biogas plants	Small hydro energy conversion
S-7	SLO-1 Potentials of recourses	Problems in wind mills	Solar power generation	Recent Developments in biomass technology	Fuel cell
	SLO-2 Achievements and applications	Problems in wind mills	Solar drying, stills and cooking	Energy farming	Fuel cell technology
S-8	SLO-1 Classification of Energy	Problems in wind mills	Photo voltaic cell principle	design consideration	Hydrogen energy production ,storage
	SLO-2 Classification of Energy resources,	Problems in wind mills	Photo voltaic cell types	Problems in digesters	Transmission, distribution
S-9	SLO-1 Conservation of energy	Wind power farms	Photo voltaic cell design	Problems in digesters	Fuel cell application
	SLO-2 Conservation techniques	Modern wind farms	Photo voltaic cell advancement	Applications of reactors	Fuel cell types

Learning Resources	1. Rai. G.D. "Non Conventional Energy Sources", Khanna Publishers, New Delhi, 1999. 2. "Renewable energy sources of conversion technology": Bansal..N.K Manfred Kleen Man and Michael Meliss, TMH Publication. 3. "Renewable Energy Sources and Emerging Technologies", Kothari. P, K C, Singal and Rakesh RanjanPHI Pvt. Ltd.,New Delhi, 2008
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. A. Subramaniam, PESCO Beam Environmental Solutions Pvt. Ltd.,	1. Dr. Lima Rose Miranda, Anna University, email: limamiranda2007@gmail.com	1. Dr. Anbalagan, SRM Inst. of Science & Technology, anbalagk@srmist.edu.in
2. Mr. S. T. Kalaimani, CPCL, Chennai	2. Dr. T. R. Sundararaman, Rajalakshmi Engineering College	2. Mr. K. SELVAM SRM Inst. of Science & Technology, selvamk@srmist.edu.in

Course Code	18CHE352T	Course Name	INTRODUCTION TO BIOCHEMICAL PRINCIPLES	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Chemical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Expose to the importance of biochemical process and products				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Study the different fermentation media				Level of Thinking (loom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Teach the principle of sterilization and growth kinetics methods																					
CLR-4 :	Study the stoichiometry and yield coefficient cell growth and product formation																					
CLR-5 :	understand the primary and secondary metabolites production process																					
CLR-6 :	study process flow for manufacture of biochemical products																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			Level of Thinking (loom)	Expected Proficiency (%)	Expected Attainment (%)															
CLO-1 :	Identify industrial importance microorganism and storage methods in fermentation process				3	80	75	L	L	L	M			L					M	H	L	L
CLO-2 :	Student able to select and prepare good media for bio product production process				3	90	85	L	L	L	M			M					L	H	L	L
CLO-3 :	Learn the Sterilization methods and determine specific growth rate and monod equation calculation				2	85	80	H	H	L	M			M					L	H	H	L
CLO-4 :	Be able to solve elemental balances and product yield in biochemical reaction				4	80	75	H	H	L	M			M					L	L	H	L
CLO-5 :	Familiarize to draw flow diagrams of primary and secondary metabolites production processes				2	90	85	H	L	H	M			L					L	M	M	H
CLO-6 :	Analyze the design and unit operation involved in the biochemical process				3	85	80	H	L	H	M			L					L	M	M	H

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (loom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1:	Identify industrial importance microorganism and storage methods in fermentation process	3	80	75	L	L	L	M			L					M	H	L	L
CLO-2:	Student able to select and prepare good media for bio product production process	3	90	85	L	L	L	M			M					L	H	L	L
CLO-3:	Learn the Sterilization methods and determine specific growth rate and monod equation calculation	2	85	80	H	H	L	M			M					L	H	H	L
CLO-4:	Be able to solve elemental balances and product yield in biochemical reaction	4	80	75	H	H	L	M			M					L	L	H	L
CLO-5:	Familiarize to draw flow diagrams of primary and secondary metabolites production processes	2	90	85	H	L	H	M			L					L	M	M	H
CLO-6:	Analyze the design and unit operation involved in the biochemical process	3	85	80	H	L	H	M			L					L	M	M	H

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Overview of biochemical engineering	Selection of good medium	Sterilization and function	Stoichiometry of microbial growth
	SLO-2	Classification of biochemical products	Medium requirements for fermentation processes	Types of Sterilization	General biochemical equation
S-2	SLO-1	History of industrial microbiology	Energy source in fermentation media	Physical method: heat sterilization	Define Degrees of reduction
	SLO-2	Comparison of chemical and biochemical Processes	Components of fermentation media	Heat sterilization: pasteurization methods	Solving problem (degrees of reduction)
S-3	SLO-1	Block diagram of fermentation process	Classification of carbon source	Heat sterilization: Autoclave methods	Define respirator co efficient
	SLO-2	Upstream fermentation process	Carbohydrates: starch and cellulose source	Physical method: radiation sterilization	Solving problem (Respirator co-efficient)
S-4	SLO-1	Downstream fermentation process	Oil and fats source	Chemical method: liquid sterilization	Solving problem (Elemental balance)
	SLO-2	Classification of Microorganisms	Nitrogen source and function	Chemical method: gas sterilization	Solving problem (Elemental balance)
S-5	SLO-1	Structure and function of microbial cells	Minerals source and function	Mechanical method: filtrations sterilization	Determination yield coefficient of substrate
	SLO-2	Isolation of micro- organisms-serial dilution method	Additives in media preparation	Factors affecting sterilization process	Solving problem (Yield coefficient of substrate)
S-6	SLO-1	Streak plate method	Growth factors and additives in media preparation	Batch sterilization	Determination yield coefficient of biomass
	SLO-2	Preservation of pure culture-storage at reduced temperature	Water and its function in media preparation	Thermal death kinetics of micro organisms	Solving problem (Yield coefficient of biomass)
S-7	SLO-1	Storage in a dehydrated form	Designing of media for fermentation processes	Continuous sterilization: Indirect heating method	Determination yield coefficient of product
	SLO-2	Types of fermentation processes batch fermentation	Types of media	Continuous sterilization: direct heating method	Solving problem (Yield coefficient of products)
S-8	SLO-1	Continuous fermentation	Simple and complex media	Phases of cell growth in batch cultures	Solving problem (Yield coefficient of products)

	SLO-2	Fed batch fermentation	Crude and natural media	Growth curve and doubling time calculation	Solving problem (Stoichiometric coefficient)	Process flow diagram for Penicillin production
S-9	SLO-1	Comparison of various fermentation processes	Different commercial media and function	Monod growth kinetic model	Solving problem (Stoichiometric coefficient)	Selection of media and microbes for vitamin production
	SLO-2	Applications of Biochemical Processes	Selection of good antifoaming agent	Solving problem (growth rate and monod constant)	Solving problem (Stoichiometric coefficient)	Process flow diagram for vitamin production

Learning Resources	4. Peter F. Stanbury, Allan Whitaker, Stephen J Hall "Principles of Fermentation Technology" 2 nd Edition, Butterworth – Heinemann (an imprint of Elsevier), 1995.	6. Bailey, J.E. and Ollis, D.F. "Biochemical Engineering Fundamentals" 2 nd Edition, McGraw– Hill, 1988.
	5. Michael L. Shuler and Fikret Kargi, "Bioprocess Engineering Basic concepts", Prentice Hall, 2002.	7. Casida Jr, L.E., "Industrial Microbiology", New Age International (P) Ltd.

SLO – Session Learning Outcome

	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. A. Subramaniam, PESCO Beam Environmental Solutions Pvt. Ltd.,	1. Dr. Lima Rose Miranda, Anna University, email: limamiranda2007@gmail.com	1. Dr. K. Tamilarasan SRM Institute of Science and Technology tamilarasan.k@ktr.srmuniv.ac.in
2. Mr. S. T. Kalaimani, CPCL, Chennai	2. Dr. T. R. Sundararaman, Rajalakshmi Engineering College	2. Ms. S. Kiruthika SRM Inst. of Science & Technology, kiruthika.s@ktr.srmuniv.ac.in

Course Code	18CHE353T	Course Name	ENERGY ENGINEERING AND TECHNOLOGY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Chemical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1:	Understand energy challenges and principles involved in energy engineering	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2:	Familiarize with energy conversion technologies	Level of Thinking (loom)	Engineering Knowledge
CLR-3:	Acquire knowledge of nuclear energy, its potential in energy generation and challenges	Expected Proficiency (%)	Problem Analysis
CLR-4:	Familiarize with energy storage and distribution technologies	Expected Attainment (%)	Design & Development
CLR-5:	Get exposure to energy conservation methods and awareness of developing technologies		Analysis, Design, Research
CLR-6:	Exposure to various energy resources, energy conversion and energy storage/distribution technologies		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (loom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1:	Define the importance of energy science and energy technology and their principles	1	80	75	H	L	L	L	M	H	H	M				H	H	L	L
CLO-2:	Analyse the various types of energy conversion technologies and powerplants	2	80	70	H	L	H	M	H	H	M					H	H	L	L
CLO-3:	Remember the benefits of nuclear energy and their potential in energy generation	1	80	75	H	L	H	M	M	H						H	H	H	H
CLO-4:	Identify the various the various energy storage and distribution technologies	2	80	75	M	L	H	M			M					L	H	H	M
CLO-5:	Discover the types of energy conservation technologies	2	80	75	M	M	H	M			H					H	H	M	H
CLO-6:	Familiar with the technologies of energy	2	80	75	H	L	M	M			M					L	M	M	M

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Energy Overview	Types of energy conversion plants for various primary energy sources	Basics of nuclear fission	Energy storage systems	Principles of energy conservation
	SLO-2 A brief history of energy technology	Electrical route and Non-electrical route	Basics of nuclear fusion	Mechanical energy storage	Energy conservation approach
S-2	SLO-1 Forms of energy	Thermal power plant	Concept of binding energy	Pumped Hydroelectric Storage	Co-generation
	SLO-2 Types of energy	Coal fire thermal power plant	Nuclear fission reactors	Compressed Air storage	Types of Co-generation
S-3	SLO-1 Energy Chains	Gas-turbine power plants	Components of nuclear reactor	Energy storage via Flywheels	Waste heat utilization
	SLO-2 Energy demand	Components of Gas-turbine	Types of fission reactor	Electrical storage	Heat recovery boiler
S-4	SLO-1 Supply network	Open cycle Gas turbine power plant	Pressurized water reactor	The lead acid battery	Heat Recuperators
	SLO-2 Energy Resources	Closed cycle Gas-turbine Power plant	Benefits of nuclear energy	Basic battery theory	Classification of heat exchangers
S-5	SLO-1 Conventional energy resources	Gasification types	Nuclear fusion principle	Chemical storage	Heat Regenerators
	SLO-2 Non – Conventional energy resources	Integrated Coal Gasification combined cycle power plant	D-T fusion reactor	Energy storage via hydrogen	The Thermal wheel
S-6	SLO-1 Renewable Energy resources	Principles of MHD power	Requirements for nuclear fusion	Electro Magnetic Energy storage	Heat pumps Operating principles
	SLO-2 Non Renewable Energy resources	Open Cycle MHD Technologies	Ignition temperature, Driven systems and Energy break even condition	Thermal Energy storage	Applications of Heat pumps
S-7	SLO-1 Energy and environment	Closed Cycle MHD Technologies	Plasma Confinement	Sensible Heat storage	Heat pipe principle
	SLO-2 Climate change	Seeded inert gas system	Magnetic confinement	Latent Heat storage	Classification of Heat pipes
S-8	SLO-1 Global warming	Liquid metal system	Thermo Nuclear Function reactors	Materials for phase change energy storage	Applications of Heat pipes
	SLO-2 Effects of green house gases	Materials for MHD	Tokamak reactor	Distribution of energy	Stirling Engine
S-9	SLO-1 Carbon credit	Applications of MHD	Methods of plasma heating	Gas pipelines	General principles of Stirling Engine
	SLO-2 Applications of carbon credit	Advantages & Disadvantages of MHD	Inertial Confinement Fusion	Electricity transmission	Main components of the Stirling Engine

Learning Resources	1. Rai, G.D, Non-Conventional Sources of Energy, Khanna Publishers, New Delhi, 1999. 2. Rao, S.and Parulakar B.B., Energy Technology, Khanna Publishers, New Delhi, 1994. 3. John Andrews and Nick Jelley, Energy Science: Principles, Technologies, and Impacts, 2nd edition, Oxford University Press, 2013.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. A. Subramaniam, PESCO Beam Environmental Solutions Pvt. Ltd.,	1. Dr. Lima Rose Miranda, Anna University, email: limamiranda2007@gmail.com	1. Mrs. D. Nanditha SRM Institute of Science and Technology nanditha.d@ktr.srmuniv.ac.in
2. Mr. S. T. Kalaimani, CPCL, Chennai	2. Dr. T. R. Sundararaman, Rajalakshmi Engineering College	2. Dr. K. Tamilarasan SRM Institute of Science & Technology, tamilarasan.k@srmuniv.ac.in

Course Code	18CHE354T	Course Name	POLYMER TECHNOLOGY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Chemical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	To familiarize the polymers, polymerization techniques and behavior in polymers				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	To familiarize the various types of thermoplastics, thermosetting and elastomers				Level of Thinking (loom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO -3
CLR-3 :	To familiarize the various polymer processing techniques for polymers, rubbers and fibers																					
CLR-4 :	To impart knowledge on various testing methods and characterization of polymers																					
CLR-5 :	To impart knowledge on speciality polymers																					
CLR-6 :	Exposure on polymeric materials, processing techniques and testing methods																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	Memorize the basics of polymer science, polymerization and properties				2	85	75	L	L	L	L								M	H	H	H
CLO-2 :	Identify various types of thermoplastics, thermosetting and elastomers				2	80	70	L	L	H	L								M	H	H	L
CLO-3 :	Recognize the processing methods and techniques of polymers, resins and rubbers				2	85	80	M	L	H	H								M	H	H	L
CLO-4 :	Illustrate the various testing methods and characterization of polymers				3	85	75	H	M	H	H								M	H	M	H
CLO-5 :	Identify the importance of speciality polymers				2	80	70	L	L	H	H								L	H	H	M
CLO-6 :	Know the importance of polymers and their properties, preparation methods, testing and applications				3	80	75	M	M	M	H								H	H	H	M

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Degree of polymerization	Thermoplastic Polymers	Processing of Thermoplastics and Thermosetting Plastics	Polymer Characterization Tests - Melt Flow Index	Speciality polymers
	SLO-2 Classification of Polymers	Commodity plastics -Polyolefins and vinyl polymers	Compounding and processing aids	Viscosity Test	Poly-Electrolytes
S-2	SLO-1 Chemistry of Polymerization –Addition Polymerization	Acrylic polymers	Compression Moulding	Thermal Characterization Techniques	Ionomers
	SLO-2 Free radical polymerization	Polystyrene	Injection Moulding	Thermal Gravimetric Analysis	Conducting Polymers
S-3	SLO-1 Ionic polymerization	Engineering plastics	Extrusion Moulding	Differential Scanning Calorimetry	Electro-Luminescent Polymers
	SLO-2 Condensation polymerization	Fluorine containing polymers	Blow Moulding	Thermo mechanical Analysis	Electrically conductive Polymers
S-4	SLO-1 Coordination polymerization	Polyamides	Rotational Moulding	Morphological properties	Thermoplastic Elastomers
	SLO-2 Molecular weight	Polyesters	Transfer Moulding	Transmission Emission Microscopy	TPEs
S-5	SLO-1 Crystallinity in polymers	Thermosetting resins	Processing of Rubbers –Mastication – Calendaring	Transmission Emission Microscopy	High Temperature Polymers
	SLO-2 Crystallisability and factors	Phenolic resins	Reaction Injection Moulding	X-ray Diffraction	Polymer Blends
S-6	SLO-1 Spherulites	Epoxy resins	Solution Casting	Mechanical Properties	Polymer Composites
	SLO-2 Polymer single crystals	Polyurethane resins	Reinforcing : Hand lay-up technique	Tensile Test	Nano-Composites
S-7	SLO-1 Glass Transition Temperature(Tg)	Silicone resins	Filament – winding technique	Impact Test	Interpenetrating Polymer Networks
	SLO-2 Factors influencing Glass Transition Temperature	Natural rubber – Isoprene rubber	Spray up technique	Hardness	Types of IPNS
S-8	SLO-1 Polymerization Techniques – Bulk polymerization	Butyl rubber	Fibre Spinning	Electrical properties – Di-Electric strength	Liquid Crystalline Polymers
	SLO-2 Solution polymerisation	Styrene Butadiene Rubber	Fibre drawing and post treatment of fibers	Di-Electric Constant	Types of LCPs
S-9	SLO-1 Suspension polymerisation	Chloroprene rubber	Elastomer Technology	Thermal Properties-Heat deflection temperature	Biomedical Polymers
	SLO-2 Emulsion polymerisation	Nitrile rubber	Vulcanization	Vicat Softening temperature	Applications in medical field

Learning Resources	1. V R Gowariker, Vasant R. Gowariker, N V Viswanathan, JayadevSreedhar, "Polymer Science", New Age International, 2 nd Edition 2. Joel R.Fried, "Polymer Science and Technology", PHI, Eastern Economy Edition, 2 nd Edition 3. Billmeyer F.W., Text book of Polymer Science, 3rd edn., Wiley, Singapore, 1984	4. D.H. Morton and Jones, Polymer Processing, Chapman and Hall, London, 1989. 5. Vishu Shah, "Handbook of Plastics Testing Technology", Wiley international publication 6. Maurice Morton, Rubber Technology, Van Nostrand Reinhold, New York, 2002
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. A. Subramaniam, PESCO Beam Environmental Solutions Pvt. Ltd.,	1. Dr. Lima Rose Miranda, Anna University, email: limamiranda2007@gmail.com	1. Mrs. D.Nanditha SRM Institute of Science and Technology nanditha.d@ktr.srmuniv.ac.in
2. Mr. S. T. Kalaimani, CPCL, Chennai	2. Dr. T. R. Sundararaman, Rajalakshmi Engineering College	

Course Code	15CHE355T	Course Name	SUSTAINABLE ENGINEERING				Course Category	E	Professional Elective															L	T	P	C	
																								3	0	0	3	
Pre-requisite Courses	Nil		Co-requisite Courses		Nil		Progressive Courses	Nil																				
Course Offering Department		Chemical Engineering				Data Book / Codes/Standards				Nil																		
Course Learning Rationale (CLR):		The purpose of learning this course is to:						Learning			Program Learning Outcomes (PLO)																	
CLR-1 :	Understand the concept of green chemistry and sustainability						Level of Thinking (loom)	Expected Proficiency %	Expected Attainment (%)	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15				
CLR-2 :	Understand the role of catalysts and green solvents																											
CLR-3 :	Understand sustainable engineering and design of process equipment																											
CLR-4 :	Analyze various industrial examples of sustainable manufacturing processes																											
CLR-5 :	Understand the economic and safety considerations of sustainable engineering.																											
CLR-6 :	Understand the significance of sustainability in chemical reactions and processes, design of equipments, economics and safety																											
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																										
CLO- 1 :	Identify the greener routes of chemical synthesis						2	80	75																			
CLO-2 :	Choose the proper catalyst (chemical/biological) and solvent for a process						3	80	75																			
CLO-3 :	Apply the concepts of sustainability in chemical processes and operations						3	85	80																			
CLO-4 :	Critically analyze the sustainable industrial processes by comparing with conventional routes						3	80	75																			
CLO-5 :	Apply the economics and safety aspects to sustainable chemistry						2	80	75																			
CLO-6 :	Apply the knowledge of sustainability in Chemical industries						2	80	75																			
Duration (hour)	9		9		9		9				9																	
S-1	SLO-1	Introduction to the course	Catalysis and Green Chemistry	Process and operations	Case studies	Introduction to the economics of green and sustainable chemistry																						
	SLO-2	Green Chemistry-Definition	Catalysis and Green Chemistry	Industry perception	The Kalundborg Model	Chemical Manufacturing and Economic Theory																						
S-2	SLO-1	Principles of Green Chemistry and Examples	Examples of green catalysis in industrially significant reactions	Reactions	Ibuprofen: A Green Manufacturing Alternative	Plant (Microscale) Scale Economics																						
	SLO-2	Principles of Green Chemistry and Examples	Biocatalysis and Green Chemistry	Reactor design	Supercritical Carbon Dioxide	Corporate Economics																						
S-3	SLO-1	Use of Greener Synthetic Pathways	Biocatalysis: Advantages Within Industrial Applications	Micro-reactors and micromixers	The Pharmaceutical Industries and Green Chemistry	Macroeconomics																						
	SLO-2	Use of Greener Synthetic Pathways	Biocatalysis: Challenges to Make Biocatalysis Industrially Viable	Novel processes and routes	Sildenafil Citrate	Economic Impact of Green Chemistry																						
S-4	SLO-1	Use of Greener Synthetic Pathways	Homogenous Biocatalysis in Water-Organic Solvent Mixtures and in Organic Solvents	Unit operations	Sertraline Manufacture	Business Strategies Regarding Application of Green Chemistry																						
	SLO-2	Use of Greener Reaction Conditions	Homogenous Biocatalysis in Water-Organic Solvent Mixtures and in Organic Solvents	Unit operations	The Polymer Industry	Incorporation of Green Chemistry in Process																						
S-5	SLO-1	Use of Greener Reaction Conditions	Uses of biocatalysts	Heat exchangers	Pesticides, Antifoulants, and Herbicides	Design for Sustainability																						
	SLO-2	Design of Greener Chemicals	Uses of biocatalysts	Heat exchangers	Fire Extinguishers and Flame Retardants	Case Studies Demonstrating the Economic Benefits of Green Chemistry and Design																						
S-6	SLO-1	Design of Greener Chemicals	Alternate solvents	Distillation columns	The food and flavor industry	Inherent safety: Safe reactor design																						
	SLO-2	Green Engineering - Definition	Alternate solvents	Absorption towers	The surfactant industry	Safety management and hazard identification																						
S-7	SLO-1	Principles of Green Engineering	Safer/green solvents	Bubble columns	The semiconductor manufacture industry	Issues related to transportation and atmospheric losses																						
	SLO-2	Principles of Green Engineering	Water as solvent	Membrane processes	The dye industry	The purification step and associated hazards																						
S-8	SLO-1	Principles of Green Engineering	Solvent-free conditions	Liquid-liquid centrifuges	The textile industry	Process variables - Reaction temperature, pressure, concentration, pH																						
	SLO-2	Principles of Green Engineering	Ionic liquids	Extraction columns	The tannery industry	Effects of operating costs on safety																						
S-9	SLO-1	Sustainability	Supercritical CO ₂	Reactions with separation processes	The sugar and distillery industries	Waste and effluent, dust/particle handling																						
	SLO-2	Sustainability	Supercritical water	Reactions with separation processes	The paper and pulp industry	Safety and risk assessment																						

Learning Resources	1. Mukesh Doble and Anil Kumar Kruthiventi, "Green Chemistry and Engineering", Elsevier Science and Technology Books, 2007. 2. Anne E. Marteel-Parrish and Martin A. Abraham, "Green Chemistry and Engineering - A pathway to sustainability", John Wiley & Sons, 2014.	3. Cost of inherent safety and profit-risk model
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#		Theory	Practice
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. A. Subramaniam, PESCO Beam Environmental Solutions Pvt. Ltd.,	1. Dr. Lima Rose Miranda, Anna University, email: limamiranda2007@gmail.com	1. Mr. V. Ganesh SRM Institute of Science & Technology, ganeshv@srmist.edu.in
2. Mr. S. T. Kalaimani, CPCL, Chennai	2. Dr. T. R. Sundararaman, Rajalakshmi Engineering College	2. Dr. K. Deepa SRM Institute of Science & Technology, deepak1@srmist.edu.in

Course Code	18CHE356T	Course Name	INDUSTRIAL POLLUTION PREVENTION AND CONTROL	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Chemical Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	know about the industrial activities and fates of industrial contaminants	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	know about the environmental regulations		
CLR-3 :	know about the solid waste and disposal methods		
CLR-4 :	know about the principles of water treatment		
CLR-5 :	know about the air pollution control methods		
CLR-6 :	know about the sources and treatment options for environmental issues		

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (loom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO -3
CLO-1 :	Identify the major industries that creates pollutants and how it affects the environment	1	85	75		L				H	H	M				H	H	L	L
CLO-2 :	Implement the rules and regulations in specific industries	1	75	70		H		H	L		H	M	M				H	L	L
CLO-3 :	Identify the solid waste produced and implement the disposal methods	1	85	75		M	M	H	M		L					H	M	H	H
CLO-4 :	Identify different water treatment methods used in industry and able to implement the methods wherever necessary	1	85	75		H	H	M	M		M	M	L			H	M	H	H
CLO-5 :	Identify the sources of air pollution and able to control the air pollution	1	85	75		H	H	M	M		M	M	L			H	M	H	H
CLO-6 :	Identify the pollution nature and able to bring the solution	1	75	70		H	H	M	M		M	M	L			H	M	H	M

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Introduction	Environmental regulations prevention vs control of industrial pollution.	Solid waste and disposal methods sources and types of solid waste	Principles of water treatment primary, secondary and tertiary treatments
	SLO-2	Introduction	Prevention vs control of industrial pollution	Sources and types of solid waste	Principles of water treatment secondary treatments
S-2	SLO-1	Industrial activity and environment	Prevention vs control of industrial pollution	Processing methods, disposal- principle, practices and methods	Principles of water treatment secondary treatments
	SLO-2	Industrial activity and environment	Prevention vs control of industrial pollution	Processing methods, disposal- principle, practices and methods	Principles of water treatment secondary treatments
S-3	SLO-1	Industrial activity and environment	Prevention vs control of industrial pollution	Processing methods, disposal- principle, practices and methods	Principles of water treatment tertiary treatments
	SLO-2	Industrial activity and environment	Prevention vs control of industrial pollution	Processing methods, disposal- principle, practices and methods	Principles of water treatment tertiary treatments
S-4	SLO-1	Fates of industrial contaminants	Environment policies and regulations to encourage pollution prevention	Energy from solid waste, waste management hierarchy	Principles of water treatment tertiary treatments
	SLO-2	Fates of industrial contaminants	Environment policies and regulations to encourage pollution prevention	Energy from solid waste, waste management hierarchy	Principles of water treatment tertiary treatments
S-5	SLO-1	Case studies on industrial contaminants	Environment policies and regulations to encourage pollution prevention	Energy from solid waste, waste management hierarchy	Advanced waste water treatments
	SLO-2	Case studies on industrial contaminants	Environment policies and regulations to encourage pollution prevention	Energy from solid waste, waste management hierarchy	Advanced waste water treatments
S-6	SLO-1	Industrialization and sustainable development	Environment friendly chemical processes	Energy from solid waste, waste management hierarchy	Advanced waste water treatments
	SLO-2	Industrialization and sustainable development	Environment friendly chemical processes	Energy from solid waste, waste management hierarchy	Advanced waste water treatments

S-7	SLO-1	Sustainability strategies	Environment friendly chemical processes	Energy from solid waste, waste management hierarchy	Advanced waste water treatments	Control of carbon monoxide and hydrocarbons
	SLO-2	Sustainability strategies	Environment friendly chemical processes	Energy from solid waste, waste management hierarchy	Advanced waste water treatments	Control of carbon monoxide and hydrocarbons
S-8	SLO-1	Barriers to sustainability	Regulations for clean environment and implication for industries	Hazardous waste, biomedical waste, and nuclear waste.	Recovery of metals from process effluents	Noise pollution measurements and its control
	SLO-2	Barriers to sustainability	Regulations for clean environment and implication for industries	Hazardous waste, Biomedical waste, and Nuclear waste.	Recovery of metals from process effluents	Noise pollution measurements and its control
S-9	SLO-1	Pollution prevention in achieving sustainability	Regulations for clean environment and implication for industries	Hazardous waste, Biomedical waste, and Nuclear waste.	Recovery of metals from process effluents	Noise pollution measurements and its control
	SLO-2	Pollution prevention in achieving sustainability	Regulations for clean environment and implication for industries	Hazardous waste, Biomedical waste, and Nuclear waste.	Recovery of metals from process effluents	Noise pollution measurements and its control

Learning Resources	1. Bishop.P, "Pollution Prevention: Fundamentals and Practice", McGraw Hill International Edn., McGraw Hill Book Co., Singapore, 2000 2. Freeman.H.M, "Industrial Pollution Prevention Hand Book", McGraw Hill, 1995 3. James. G. Mann and Liu.Y.A, "Industrial Water Reuse and Waste Water Minimization", McGraw Hill, 1999	4. Rose.G.R.D, "Air pollution and Industry", Van Nostrand Reinhold Co., New York 1972 5. Pandey.G.N and Carney.G.C, "Environmental Engineering", Tata McGraw Hill, New Delhi, 1989 6. Kapoor.B.S, "Environmental Engineering", 3rd Edn., Khanna publishers, 1997
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CA –4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. A. Subramaniam, PESCO Beam Environmental Solutions Pvt. Ltd.,	1. Dr. Lima Rose Miranda, Anna University, email: limamiranda2007@gmail.com	1. Dr. B. Karunanithi SRM Inst. of Science & Technology, karunab@srmist.edu.in
2. Mr. S. T. Kalaimani, CPCL, Chennai	2. Dr. T. R. Sundararaman, Rajalakshmi Engineering College	2. Dr. S. Vishali SRM Inst. of Science & Technology, vishalis@srmist.edu.in

Course Code	18CHE357T	Course Name	ENZYME ENGINEERING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Chemical Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Understand the mechanism of enzyme action and learn about the different classes of enzymes	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Understand the kinetics of enzyme action and identify the types of inhibition		
CLR-3 :	Understand the need for enzyme immobilization and learn the different methods of immobilization		
CLR-4 :	Analyze the effect of various physicochemical factors on enzyme activity		
CLR-5 :	Understand the various applications of enzymes		
CLR-6 :	Appreciate the various mechanisms of enzyme action and its industrial applications		

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (loom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO- 1 :	Comprehend the basic concepts about enzymes, mechanism of enzyme action, and the classification of enzymes	2	85	80	L	L	M				M		L				M		
CLO-2 :	Identify and estimate the kinetic parameters and type of inhibition using various kinetic plots	3	80	75	M	M	M	M									M		
CLO-4 :	Choose the immobilization technique based on the requirements of the process	3	80	75	M	M	M	M			M		M				M		
CLO-4 :	Identify the circumstances of enzyme deactivation and select the reaction conditions wisely	3	80	75	M	M	M	M	L		M		M				M		
CLO-5 :	Discern the practical applications of enzymes	2	80	75	M	M	M	H	M		M		H				M	M	M
CLO-6 :	Apply the knowledge of enzymes for suitable industries	2	75	70	M	M	H	H	M		M		M				M	M	M

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Action of enzymes	Kinetics of enzyme action	Enzyme immobilization technology	Deactivation enzyme kinetics	Application of enzyme in analysis
	SLO-2 Action of enzymes	Introduction to enzyme kinetics	Introduction to immobilization	Deactivation enzyme kinetics	Application of enzyme in analysis
S-2	SLO-1 Classification of enzymes	Kinetics of single substrate reactions	Types of immobilization	Mechanisms of reversible enzyme modulation	Enzyme electrode
	SLO-2 Classification of enzymes	Estimation of Michelis-Menten parameters	Adsorption	Mechanisms of reversible enzyme modulation	Enzyme electrode
S-3	SLO-1 Mechanisms of enzyme action	Kinetics plots	Matrix entrapment	The effect of pH on enzyme activity	Design of enzyme electrodes
	SLO-2 Mechanisms of enzyme action	Problems on M-M kinetics	Encapsulation	The effect of pH on enzyme activity	Design of enzyme electrodes
S-4	SLO-1 Concept of active site	Problems on M-M kinetics	Cross linking	The effect of temperature on enzyme activity	Applications of enzyme electrodes as biosensors in industry
	SLO-2 Concept of active site	Mechanisms of multi-substrate reactions	Covalent binding	The effect of temperature on enzyme activity	Applications of enzyme electrodes as biosensors in industry
S-5	SLO-1 Energetics of enzyme substrate complex formation	Inhibitors	Advantages and disadvantages of different immobilization techniques	Enzyme deactivation	Applications of hydrolytic enzymes
	SLO-2 Energetics of enzyme substrate complex formation	Types of inhibition mechanisms	Advantages and disadvantages of different immobilization techniques	Enzyme deactivation	Applications of hydrolytic enzymes
S-6	SLO-1 Specificity of enzyme action	Competitive inhibition	Immobilization enzyme kinetics	Mechanisms and manifestations of protein denaturation	Applications of hydrolytic enzymes
	SLO-2 Specificity of enzyme action	Uncompetitive inhibition	Immobilization enzyme kinetics	Mechanisms and manifestations of protein denaturation	Applications of hydrolytic enzymes
S-7	SLO-1 Principles of catalysis	Non-competitive inhibition	Effects of external mass-transfer resistance	Deactivation models and kinetics	Applications of non-hydrolytic enzymes
	SLO-2 Principles of catalysis	Comparison of different type of inhibition	Effects of external mass-transfer resistance	Deactivation models and kinetics	Applications of non-hydrolytic enzymes
S-8	SLO-1 Collision theory	Problems on enzyme inhibition	Analysis of intraparticle diffusion and reaction	Mechanical forces acting on enzymes	Applications of non-hydrolytic enzymes
	SLO-2 Collision theory	Problems on enzyme inhibition	Analysis of intraparticle diffusion and reaction	Strategies for enzyme stabilization	Applications of non-hydrolytic enzymes
S-9	SLO-1 Transition state theory	Problems on enzyme inhibition	Simultaneous film and intraparticle mass-transfer resistances	Problems on enzyme de-activation kinetics	Enzymes used in current and developing industry
	SLO-2 Transition state theory	Problems on enzyme inhibition	Simultaneous film and intraparticle mass-transfer resistances	Problems on enzyme de-activation kinetics	Enzymes used in current and developing industry

Learning Resources	1. Palmer, Trevor "Enzymes : Biochemistry, Biotechnology, Clinical Chemistry", Affiliated East-West Press Pvt. Ltd., 2004 2. Bailey, J.E. and Ollis, D.F. "Biochemical Engineering Fundamentals" 2 nd Edition, McGraw– Hill, 1988. 3. Michael L.Shuler and Fikret Kargi, "Bioprocess Engineering Basic concepts", Prentice Hall, 1992.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CA –4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. A. Subramaniam, PESCO Beam Environmental Solutions Pvt. Ltd.,	1. Dr. Lima Rose Miranda, Anna University, email: limamiranda2007@gmail.com	1. Dr. M. P. Rajesh SRM Institute of Science & Technology, hod.chem.ktr@srmist.edu.in
2. Mr. S. T. Kalaimani, CPCL, Chennai	2. Dr. T. R. Sundararaman, Rajalakshmi Engineering College	2. Dr. K. Deepa SRM Institute of Science & Technology, deepak1@srmist.edu.in

Course Code	18CHE358T	Course Name	FERTILIZER TECHNOLOGY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Chemical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand the importance of fertilizers and growth potential of fertilizer Industries				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Learn the various nitrogen fertilizers production processes				Working (loom) Efficiency (%) Maintenance (%)			Knowledge	Analysis	Development	Design, Research	Usage	Culture	& Sustainability		Team Work	Innovation	Finance & Marketing				
CLR-3 :	Familiarize the different phosphate fertilizers and its manufacturing processes																					
CLR-4 :	Understand the Importance of compound fertilizers and production processes																					
CLR-5 :	Learn the process flow diagram of miscellaneous fertilizers																					
CLR-6 :	Identify Biofertilizers																					

Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			Level of Difficulty	Expected	Expected	Engineering Problem Solving	Design & Analysis	Modern Tools	Society & Environment	Ethics	Individual	Communication	Project Management	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Identify the chronological development of fertilizer industry	2	90	85	L	L	L	L			H	L			M	H	M	L	L
CLO-2 :	Recognize the raw materials and processes for manufacture of nitrogenous fertilizers	2	85	75	M	L	M	L			M	M			M	H	M	L	L
CLO-3 :	Understand the block diagram of phosphate fertilizers	2	85	80	M	L	M	L			M	M			M	M	H	L	L
CLO-4 :	Review the flow diagrams of potassium and compound fertilizers	2	90	80	M	L	L	L			M	M			M	H	H	L	L
CLO-5 :	Classify the miscellaneous fertilizers and production process	2	85	75	M	L	M	L			M	M			M	M	L	H	L
CLO-6 :	Develop the application of Biofertilizers	2	85	80	M	L	M	L			M	M			M	M	L	H	L

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Overview of plant nutrients	Ammonia- - physical and chemical properties, applications	Importance of phosphate fertilizers	Overview of potash fertilizers	Biofertilizers
	SLO-2	Functions of nutrients	Feedstock's for Ammonia production	Phosphate fertilizers-various types	Types of potash fertilizers	Importance of Biofertilizers
S-2	SLO-1	Classification of soil nutrients-macro and micro nutrients	Ammonia production via steam reforming	Raw materials selection for Phosphate fertilizers	Physical, chemical properties and uses of Potassium Chloride,	Types of biofertilizers
	SLO-2	Fundamentals of soil nitrogen	Reactions involved, advantages and disadvantages	Preparation of raw materials - Phosphate Rock, Sulphur, Pyrites	Physical, chemical properties and uses of Potassium nitrate, Potassium sulphate	Benefits of Biofertilizers
S-3	SLO-1	Fundamentals of soil Phosphorus	Partial oxidation method for ammonia production	Sulphuric acid-Raw material including storage and handling	Selection of raw materials for manufacture of potassium chloride	Preparation of a Biofertilizers
	SLO-2	Fundamentals of soil potassium	Storage and Transportation of Ammonia	Processes for the production of sulphuric acid	Process flow diagram for potassium chloride production	Precautions to use Biofertilizers
S-4	SLO-1	Need of fertilizer	Nitric acid-chemical and physical properties, applications	Production processes of Phosphoric acid - Dihydrate processes	Production flow sheet for potassium nitrate	Fluid Fertilizers
	SLO-2	Fertilizer specifications	Manufacture of nitric acid Storage and transportation	Hemihydrate and recrystallization processes	Production flow sheet for potassium sulphate	Fluid Fertilizers
S-5	SLO-1	Classification of fertilizers	Production of Ammonium chloride	Single super phosphate-Agriculture use	Role of compound fertilizers	Controlled release fertilizers
	SLO-2	Classification of fertilizers	Physical and Chemical properties, application	Production process for SSP	Compound fertilizer production Technology	Types of Controlled release fertilizers
S-6	SLO-1	Requisite of fertikzers	Ammonium sulphate- method of manufacture	Selection of raw material & process condition for Triple super phosphate	Processes for manufacturing compound fertilizers	Environmental issues related to the use of fertilizers
	SLO-2	Fertilizer Terminology and defintions	Characteristics, specification, storage handling and applications	Process flow diagram for TSP	Processes for manufacturing compound fertilizers	Impact of fertilizer on the Environment
S-7	SLO-1	Organic manures versus synthetic fertilizers	Feedstock for urea production	Raw material and process condition for Ammonium phosphate synthesis	Importance of NPK fertilizers	Soil and air Pollution from fertilizer industry
	SLO-2	Role of organic manures	Urea production and storage	Manufacture of Ammonium phosphate	Process flow sheet for the manufacture of NPK fertilizer using mixed acid route	Water pollution from fertilizer industry

S-8	SLO-1	Growth of fertilizer Industry in India	Methods of Production, characteristics and specification - Ammonium Nitrate	Fundamental of Nitro phosphates	Nitro phosphate route for NPK fertilizers	Fertilizer plants effluent treatment and disposal
	SLO-2	Growth of fertilizer Industry in India	storage and handling of Ammonium Nitrate	Manufacture of nitro phosphates	Nitro phosphate route for NPK fertilizers	Corrosion problems in fertilizer industries
S-9	SLO-1	Location of fertilizer Industry in India	Production of calcium Ammonium nitrate(CAN)	Other phosphate fertilizers-Enriched super phosphate	Advantages of compound fertilizers	Case study of selected fertilizer plants with environmental aspects.
	SLO-2	Location of fertilizer Industry in India	Granulation of CAN	Application of super phosphate	Application of compound fertilizers	Case study

Learning Resources	1. Hand book of Fertilizer Association of India, New Delhi, 1998 2. Slack A.V., Chemistry & Technology of Fertilizers, Interscience, New York, 1967 3. NPTEL Notes-IITM/Fertilizer Technology
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. A. Subramaniam, PESCO Beam Environmental Solutions Pvt. Ltd.,	1. Dr. Lima Rose Miranda, Anna University, email: limamiranda2007@gmail.com	1. Ms. S. Kiruthika SRM Inst. of Science & Technology, kiruthis@srmist.edu.in
2. Mr. S. T. Kalaimani, CPCL, Chennai	2. Dr. T. R. Sundararaman, Rajalakshmi Engineering College	2. Dr. K. Tamilarasan SRM Inst. of Science & Technology, tamilark@srmist.edu.in

Course Code	18CHE359T	Course Name	PETROLEUM TECHNOLOGY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Chemical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Understand the formation and evaluation of crude oil, overview of petroleum refining processes, Distillation	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Understand the Evaluation and testing, properties, Petroleum refining processes	Level of Thinking (loom)	Engineering Knowledge
CLR-3 :	Understand the Thermal and catalytic cracking, treatment techniques	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Understand the production of fuels, lubricating oil, storage and transportation	Expected Attainment (%)	Design & Development
CLR-5 :	Understand the production of olefin gases, intermediates compounds and important petrochemicals		Analysis, Design, Research
CLR-6 :	Understand the overview of petroleum refining process		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Comprehend the potential growth of petrochemical industries, distillation characteristics	1 75 70	L
CLO-2 :	Comprehend the thermal properties of petroleum fractions	1 75 70	M
CLO-3 :	Comprehend the conversion of petroleum, hydrodesulfurisation	1 80 75	H
CLO-4 :	Comprehend the fuel, storage and transportation -characteristics	1 80 75	M
CLO-5 :	Comprehend the flow sheets of important petrochemicals	1 80 75	M
CLO-6 :	Comprehend the salient features of petroleum engineering	1 80 70	H

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Origin of crude	Octane number	Thermal cracking	Overview of Refinery Products
	SLO-2	Origin of crude	Cetane number, Diesel index, their determination and importance	Thermal cracking in vapor, liquid and mixed phase	Refinery Products
S-2	SLO-1	Formation	Petroleum refining processes	Catalytic cracking	Production of aviation gasoline
	SLO-2	Formation theories	Petroleum Products	Houdry fixed bed	Properties
S-3	SLO-1	Migration of crude	Evaluation of Crude Oil	Fluidized bed	Motor fuel, kerosene, fuel
	SLO-2	Accumulation of petroleum	Testing of Petroleum Products	Catalytic bed	Diesel oil, tractor fuel and jet
S-4	SLO-1	Types of crude	general processing, topping	Reforming process	Lubricating oil manufacture
	SLO-2	Crude classification	vacuum distillations	Alkylation process	Petroleum waxes and asphalts
S-5	SLO-1	Formation and Evaluation of Crude Oil.	Physical properties	Conversion of petroleum gases into motor fuel with alkylation	Storage of petroleum products
	SLO-2	General processing of crude	Thermal properties	Flow digram	Types of storage
S-6	SLO-1	Atmospheric distillation of crude	Properties of petroleum fractions	Polmerization	Tanks
	SLO-2	Flow diagram	Thermal properties	Hydrogenation and dehydrogenation	Bulleets
S-7	SLO-1	Distillation condition	Flash point, fire point	Treatment techniques	Special types of spheres
	SLO-2	Distillation products	Viscosity factor	Removal of Sulphur Compounds	Transportation of petroleum products,road, rail,
S-8	SLO-1	Vacuum distillations	Petroleum refining processes	Dewaxing	Sea and pipeline;
	SLO-2	Flow diagram		Clay Treatment and Hydrofining	Types of transportation
S-9	SLO-1	Primary process	Refining flow diagram	Desulphurization,	Safety norms
	SLO-2	Secondary process		Solvent Treatment Processes	Importance of pipeline transportation.

Learning Resources	1. BhaskaraRao. B.K, "A Text on Petroleum Chemicals", 4thEdn.,Khanna Publishers, New Delhi, 2007 2. Nelson.W.L, "Petroleum Refinery Engineering", McGraw Hill Publishing Company Limited, 1985. 3. GopalaRao M. and Marshall Sittig. "Dryden's Outlines of Chemical Technology", 3rd Edn.,East-West Press, New Delhi, 1997.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. A. Subramaniam, PESCO Beam Environmental Solutions Pvt. Ltd.,	1. Dr. Lima Rose Miranda, Anna University, email: limamiranda2007@gmail.com	1. Dr. Anbalagan, SRM Inst. of Science & Technology, anbalagan.k@ktr.srmuniv.ac.in
2. Mr. S. T. Kalaimani, CPCL, Chennai	2. Dr. T. R. Sundararaman, Rajalakshmi Engineering College	2. Dr. M. Magesh kumar SRM Inst. of Science & Technology, mageshkumar.m@ktr.srmuniv.ac.in

Course Code	18CHE360T	Course Name	PRINCIPLES OF MEMBRANE SEPARATION	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Chemical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Know about membranes, their nature, characteristics and their role in water purification and other separation processes in industries vis-a-vis conventional separation processes.				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Understand the various methods of preparation of membranes in different configurations and their structural & performance characteristics.				Level of Thinking (loom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO -3
CLR-3 :	Understand the principles, mechanism of transport, applications and performance characteristics of pressure driven membrane processes.																					
CLR-4 :	Understand the principles, characteristics and applications of membrane processes driven by electrical and concentration gradients																					
CLR-5 :	Designing of membranebased systems from laboratory studies for various applications including desalination.																					
CLR-6 :	Understand the potential of membrane process for various applications																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	Prepare the membrane and characterize them with respect to their performance.				3	80	75	H	H				M		L					H		
CLO-2 :	know the basic principles, philosophy and process flow diagram for pressure driven membrane processes.				2	75	70	H	H	H				M						H		
CLO-3 :	Use membrane contactors for study of separations based on solvent extraction, gaseous separation, forward osmosis etc.				2	75	70	M	H	H	H	M	M	H	M	H				H		
CLO-4 :	Appreciate and apply concepts such as hybrid systems, zero liquid discharge, value recovery etc				1	90	80	H	M		H		H	M	M					H	M	M
CLO-5 :	Process design of desalination systems for seawater, brackish water and industrial waste water.				2	80	60	M	H	H			H							H	M	M
CLO-6 :	Understand the basis of design for different membrane separation process				3	80	70	H	M	H	H	M		M						H	H	M

Duration (hour)	9	9	9	9	9
S1	SLO-1: Definition of membrane - distinguishing features of membrane processes over conventional processes.	Pressure driven membrane processes: commonalities and distinguishing features.	Pretreatment options – related to recovery and specific flux- selection of High Pressure pump - post treatment systems	Deign of module arrangements – controlling parameters – staggered configurations. Concept of Pass and Stage.	Forward osmosis for desalination – process principles – membranes used- osmotic pouches – challenges & limitations
S2	SLO-1: Types and classification of membranes. Porous and non-porous; asymmetric/symmetric / composite and TFC	Ultra-filtration: features characterization, transport mechanism and operating features	Energy recovery systems – cleaning and maintenance aspects	Post treatment and cleaning systems.	Pervaporation concepts - applications
S3	SLO-1: Structural characterization of membranes: pore size/pore-size distribution, contact angle	Principles behind reverse osmosis and nano-filtration: features and characteristics.	Applications of MF/UF in waste water treatment – comparison with conventional operations. Design approach for UF	High Pressure pump /energy recovery systems	Membrane contactors applications in gaseous separation / solvent extraction.
S4	SLO-1: Classification of membrane processes based on driving forces – membrane requirements for each of the processes	Definition of SR,Rec and product flux, Performance characteristics of membranes with recovery, feedconc. And temperature of water.	Membrane Bio reactors – concept and applications	Once through /recycle mode of operation of RO plants	Zero liquid discharge -concept – how membrane processes can achieve
S5	SLO-1: Membrane preparation techniques / sheet / tubular / capillary /hollow fibre - assembly as membrane element & modules	Transport mechanisms through membranes: Preferential sorption – capillary flow mechanism – concept and transport equations	Application of NF and RO – comparison of the processes based on membrane characteristics, operating aspects and performance.	Basic concepts of electrically driven membrane processes – membrane characteristics – comparison with pressure driven processes	Hybrid membrane systems – an analysis with a case study.
S6	SLO-1: Relative characteristics of different module configurations and advantages and limitations of the modules during applications.	Irreversible thermodynamics model – coupled flow – transport equations	.Design of RO /NF systems – approach -basic elements	Electro-dialysis – process description- membrane characteristics – EDR - limitations – energy consumption – lack of energy recovery	Value recovery – isolation of spent streams at source- techniques like size-enhanced – UF/ combo membrane processes or

S7	SLO-1:	Review of solution properties relevant to membrane processes. -colligative, zeta potential, diffusive flow, capillary flow.	Solution Diffusion model – concept and equations	Feed water characteristics and pretreatment requirements -discussion on fouling, scaling and chemical environments.	Electro-electro-dialysis and bipolar electrolysis- process principles – applications-challenges	Environmental aspects of membrane processes – concentrate disposal -spent membrane disposal
S8	SLO-1:	Definition of osmosis, osmotic pressure and osmotic equilibrium. – problems to illustrate variation of osmotic pressure with temperature and concentration. Relevance of contact angle /zeta potential etc. angle	Comparison of three models – use of transport equations for estimating membrane area and solute concentration in the permeate.	Pretreatment equipments – monitoring aspects of pretreatment performance – SDI ORP	Fuel cells / type of membranes used – different types of Fuel Cells - challenges	Cost elements and analysis of low temperature desalination systems / opportunity costs / sustainability criteria
S9	SLO-1:	Thermodynamic concepts for the minimum energy for membrane separation estimation of minimum energy based on colligative properties.	Laboratory experiments using single element to collect data for designing larger plants. role of each subsystem	Flow sheet of SWRO/NF plant. Role of each subsystem. Batch Vs continuous system	Membrane distillation- process philosophy for desalination – type of membranes. VMD, AGMD, DCMD	Environmental issues – Environmental impact analysis of thermal / membrane desalination plants.

Learning Resources	<ol style="list-style-type: none"> 1. Peter Marcel Mulder : Basic Principles of Membrane Technology Springer (India) Private Ltd. New Delhi(2007) ISBN978-81-8128-683-3 2. W.S.Winston HO and K.K.Sirkar(Ed): Membrane Hand Book Von Nostrand Reinhold (1992) 3. Kaushik Nath Membrane Separation Processes PHI learning Pvt.Ltd.(2016) ISBN 10 :8120352912
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SLO – Session Learning Outcome

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. A. Subramaniam, PESCO Beam Environmental Solutions Pvt. Ltd.,	1. Dr. Lima Rose Miranda, Anna University, email: limamiranda2007@gmail.com	1. Dr. S. Prabhakar SRM Inst. of Science & Technology, sivaprabha50@gmail.com
2. Mr. S. T. Kalaimani, CPCL, Chennai	2. Dr. T. R. Sundararaman, Rajalakshmi Engineering College	

Course Code	18CHE361T	Course Name	SAFETY AND HAZARD ANALYSIS IN PROCESS INDUSTRIES	Course Category	E	PROFESSIONAL ELECTIVE	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Chemical Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	familiarize Basics of Industrial Safety Management.				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Various aspects of Chemical plant safety				Level of Thinking (loom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO -3
CLR-3 :	Various aspects of Industrial accidents and Fire safety																					
CLR-4 :	Hazard identification techniques																					
CLR-5 :	Various aspect of industrial hygiene and Occupational Health hazards, Safety legislation in chemical industries																					
CLR-6 :	Learning Basic Industrial safety Management, Safety of chemical Plants, Identification of Hazards, Industrial Hygiene, Occupational Hazards and safety legislation in Chemical Industries																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	Know the Basics of Industrial Safety Management.				2	80	70	L	M	M			L	M		H	H		H	H	M	M
CLO-2 :	Understand the Various aspects of Chemical plant safety				3	80	75	M	H				M	H	M	H	H		M	H	M	M
CLO-3 :	Understand the Various aspects of Industrial accidents and Fire safety				3	80	75	L	M	M	M		H	H	M	H	H		M	H	M	M
CLO-4 :	Able to use Hazard identification techniques				3	85	80	M	M		M	M	M	H						H	M	
CLO-5 :	Know the Various aspect of industrial hygiene and Occupational Health hazards, Safety legislation in chemical industries				3	80	75	L		M	M		L	H		H				H	L	L
CLO-6 :	Will be able to Control the Accidents in Chemical Industries By applying the acquired knowledge from Course Learning Rationle				1	75	70	M	H	M	M	M	M	H	M	H	H		H	H	H	M

Duration (hour)	9		9	9	9	9
S1	SLO-1	INDUSTRIAL SAFETY MANAGEMENT Importance of Safety consciousness in Indian Chemical Industries -	- CHEMICAL PLANT SAFETY Chemical process Industries - Setting and Layout of a Chemical plant	ACCIDENT AND THEIR PREVENTION Definitions, H. W. Henrich, Frank bird & Multiple Causation theories of accident occurrences, Classification, Causes, Costs	HAZARD IDENTIFIATION TECHNIQUES Safety Appraisal - Risk Assessment -Hazard identification techniques with examples such as FMEA, CMA, Fault Tree Analysis	INDUSTRIAL HYGIENE AND OCCUPATIONAL HEALTH HAZARDS Concepts - Industrial and Occupational health hazards, Housekeeping, human factors and error, stress at work,
S2	SLO-1	Development of Industrial Health and Safety,	Safety in transportation, storage and handling of hazardous chemicals	Industrial accidents, Principles of Accident prevention, Accident prevention technique	Preliminary Hazard Analysis (PHA), Hazard and operability (HAZOP) study	Personnel protective equipments, Role of trade unions in Industrial safety and health
S3	SLO-1	Safety Organization –Polices- Culture -Planning- Promotion – Inspection –Rules- Responsibility – Supervision,	Chemical process hazards and their control - First degree and second degree hazards. Lines of defense	Plant and Chemical job safety analysis, Accident proneness vocational guidance	Quantitative risk analysis-Out line of methodology, Consequences analysis	SAFETY AND LAW Introduction to ILO,
S4	SLO-1	Safety Committee – role of safety functionaries	High pressure - High temperature operations – Case studies	Safety performance measurement tools - FR, SR, (FSI), Safe T-Score, Accident rate per 1000 workers,	Quantitative risk analysis-Out line of methodology, Consequences analysis	Safety legislation in India, Factories act 1948
S5	SLO-1	Safety Committee – role of safety functionaries,	Emergency preparation: On-site and Offsite	Disabling injury index, Accident Compensation Statutes	Calculation of release rates of liquids under ambient pressure and liquids under pressure,	Employees welfare and legislation , Provisions relating to safety , health & environment in other important legislations
S6	SLO-1	Elements of work place Safety Program,	Safety aspects of maintenance in chemical plant	Accident Investigation reporting and Analysis	Calculation of dispersion of released gases and vapors and platting of equal concentration contours	Indian boilers act and regulations, Indian electricity act and rules
S7	SLO-1	Economic and Social Benefits from Safety Program	Effective steps to implement safety procedures-Periodic Advice and checking to follow safety procedures and rules	Case studies	Dow (Index) Fire and Explosion Index	Indian explosives act and rules, Mines act, Petroleum act and rules
S8	SLO-1	Effective Safety Education and Training	Safe guarding of Machines – Ergonomics	Conditions -Fire triangle- Classification of fires, Common causes of industrial fires, Fire protection systems- prevention	Dow (Index) Fire and Explosion Index	Environmental protection act.

S9	SLO-1	Communication at various levels of production and operation, Safety slogans	Proper selection and replacement of handling equipment -Safe handling and operation of materials and machineries	Case studies, Safety in Explosive	System of Risk Analysis	Environmental protection act.
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Learning Resources	1. Sharma. A M "Safety and Health in Industry" -A Hand book, BS Publications , 2009 2. Fulekar. M.H, "Industrial Hygiene and Chemical Safety", I.K International Publishing house Pvt Ltd., 2006.	3. Fawcett. H.H, and Wood .W.S, Safety and Accident Prevention in Chemical Operations, John Wiley & sons, U.S.A., 1965 4. Willie Hammer & Dennis Price, Occupational safety management and Engineering, Prentice Hall, 2001 5. William Handley, Industrial safety hand book, McGraw- Hill, 1969 6. Daniel. A, Crowl & Joseph. F Louvar Chemical Process safety: fundamentals with applications, Prentice Hall international series
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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2. Mr. S. T. Kalaimani, CPCL, Chennai	2. Dr. T. R. Sundararaman, Rajalakshmi Engineering College	

Course Code	18CHE362T	Course Name	FUNDAMENTALS OF DESALINATION	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Chemical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):		The purpose of learning this course is to:		Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand the relevance of desalination technologies and to realize the application of basic principles of solution chemistry and thermodynamics for understanding the processes of desalination.	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2 :	Understand the nature and behavior of the membranes under different imposed parameters and hence to learn the process features and design philosophy of Reverse Osmosis desalination.	Thinking (loom)	Skill Proficiency (%)	Skill Attainment (%)	Learning Knowledge	Analysis	Design & Development	Design, Research	Tool Usage	Culture & Sustainability	Team Work	Communication	Finance & Mgt	Learning							
CLR-3 :	Understand the features of different variants of thermal desalination processes including the role of accessories such as vacuum and control systems, process design philosophy, operational and maintenance aspects.																				
CLR-4 :	To impart knowledge on the use of renewable sources of energy and other desalination processes including those on the Research and Development mode.																				
CLR-5 :	To impart knowledge on decision making synergizing technical, economical and environmental aspects.																				
CLR – 6 :	Understanding the comparative challenges and advantages of various desalination process																				

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (loom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Appreciate the need for desalination and realise the theoretical limitations. Estimate minimum energy requirement based on colligative properties and second law of thermodynamics.	3	80	75	H	M				M		L					H		
CLO-2 :	know the basic principles, philosophy and process flow-sheet of RO and thermal desalination processes	2	75	70	H	M	M										H	M	M
CLO-3 :	Relate environmental parameters, process requirement, use requirements and economics for final system selection	2	75	70	H	H	H	M		M	H	L	L				H		
CLO-4 :	Have awareness about the renewable sources, their limitation and their utilization for desalination	1	90	80	H	H		M		H	M	L					H	M	L
CLO-5 :	Realise challenges of the technology and develop new systems for desalination such as forward osmosis/membrane distillation.	2	80	60	M	H	M										H		
CLO-6 :	Select appropriate desalination system depending upon the environment	2	75	65	H	M	M	H		H	M						H	M	M

Duration (hour)		9	9	9	9	9
S1	SLO-1	Global and Indian Water Scenario: need for desalination	Pressure driven membrane processes-comparative characteristics -structure-operational -applications- transport mechanisms	Design and operational aspects of brackish water desalination plants.	Post treatment of Thermal plant product / why and how?	Comparative analysis of desalination processes – energy, feed quantity, pretreatment , product quality etc.
S2	SLO 1	Structural properties of water, solution properties, classification natural water, variation of seawater composition with depth and latitude.	Role of UF and NF in water treatment & Desalination	Basic components of Thermal desalination – Basic properties of steam – saturated / unsaturated / superheated steam and their applications – definition and meaning of Performance Ratio.	Electro-dialysis – process description-membrane characteristics – EDR - limitations – energy consumption – lack of energy recovery	Scale up characteristics of Desalination plants / comparative aspects on operational aspects.
S3	SLO 1	Types of contaminants in water – Brackish water and industrial water - anthropogenic and geogenic contaminants. Conventional methods of water treatment	Fundamentals of reverse osmosis desalination process -transport equations.	Variation of Seawater properties such as BPE, boiling point, specific heat etc. with temperature, pressure Corrosion aspects with reference hot seawater	Membrane distillation- process philosophy for desalination – type of membranes. VMD, AGMD, DCMD	Cost elements membrane based desalination plants / optimization approach – recovery/product quality
S4	SLO-1	Meaning and description of desalination - Basic elements of Desalination Energy requirements	Basic flow sheet of RO desalination – role of each subsystem.- basic terms Solute rejection/ percent recovery / membrane water flux	Flashing / boiling distinction – single effect evaporation – purpose & function of evaporator / condenser. Why PR is <1 for single effect	Forward osmosis for desalination – process principles – membranes used- osmotic pouches – challenges & limitations	Cost elements of thermal plant using steam – optimization with respect overall cost
S5	SLO-1	Meaning of thermodynamic minimum energy requirement- estimation through colligative properties	Pretreatment need for RO – unit operation and processes used – Scaling potential -monitoring of pretreatment performance – SDI- ORP	Why and how of seawater pretreatment – Scaling potential Why multistage / multi-effect – process requirement: vacuum systems (ejectors), demisters – pumps/limitation of top temperature.	Low temperature distillation – waste heat – advantages & limitations – ocean thermal energy desalination – energy consumption – unique features. - example	Cost elements and analysis of low temperature desalination systems / opportunity costs / sustainability criteria

S6	SLO-1	Concept of Exergy – energy of mixing /de-mixing. Estimation of minimum energy at practical situations.	Description of membrane – membrane element – module – array - selection of membrane configuration – performance features. Membrane arrangement – staggered configuration – Staging/Passing	MSF – description of the process flowsheet- heat recovery / reject /brine heater: explanation of each sub system. Once through and recirculation systems	Solar based desalination systems – solar distillation – solar thermal systems – solar PV -RO	Environmental issues – Environmental impact analysis of thermal / membrane desalination plants.
S7	SLO-1	Classification of desalination processes based on energy source / driving forces etc.- Basic features	Performance characteristics of as a function of temperature, pressure and salinity	MED – description – process flowsheet- parallel /series feed flow systems	Dual purpose plants – advantages – applications	Selection of desalination system – Approach
S8	SLO 1	Membrane – definition- types of membranes -	High Pressure pump features and selection. Energy recovery systems.	Vapor – compression Thermo vapor compression / mechanical vapor compression - specific features	hybrid Desalination – meaning and purpose – thermal- RO , NF -RO	Case study - for drinking water / industrial grade water
S9	SLO 1	Asymmetric/homogenous- membrane preparation techniques and characteristics Membrane configuration/ comparative features	Post treatment – need and methods – cleaning in place	Comparative features of all the thermal processes – capacity, maintenance, energy / cooling water requirements etc.	Design considerations for inland brackish water reverse osmosis plants	Challenging desalination systems – freeze desalination – humidification – dehumidification systems

Learning Resource	1. H.T. El-Dessouky, H.M. Ettouney, <i>Fundamentals of salt water Desalination</i> , Elsevier 2002
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. A. Subramaniam, PESCO Beam Environmental Solutions Pvt. Ltd.,	1. Dr. Lima Rose Miranda, Anna University, email: limamiranda2007@gmail.com	1. Dr. S. Prabhakar SRM Inst. of Science & Technology, sivaprabha50@gmail.com
2. Mr. S. T. Kalaimani, CPCL, Chennai	2. Dr. T. R. Sundararaman, Rajalakshmi Engineering College	

Course Code	18CHE363T	Course Name	AIR POLLUTION CONTROL ENGINEERING	Course Category	E	PROFESSIONAL ELECTIVE	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Chemical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1:	Understand the effect of pollution on human health and the necessity to control the pollutants	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2:	Know how to measure the concentration of the pollutants by models and experiments.		
CLR-3:	Different types of pollutants available and their control		
CLR-4:	Know how Know how to Control the Oxides of Sulphur, Nitrogen		
CLR-5:	Analyze the Effect of Pollutants on Atmosphere		
CLR-6:	Realize the effect of pollutants on living things, Control of Pollutants		

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (loom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1:	Understand the effect of pollution on human health and the necessity to control the pollutants	1	80	75						H	H		H	H		M	H	M	M
CLO-2:	Know how to measure the concentration of the pollutants by models and experiments.	1	75	70	M	M	H	H			H			M			H	M	H
CLO-3:	Different types of pollutants available and their control	2	75	70	M	M	H	H		H	H		H			M	H	M	M
CLO-4:	Know how Know how to Control the Oxides of Sulphur, Nitrogen	2	80	75	M		H	M		H	H			M			M	H	M
CLO-5:	Analyze the Effect of Pollutants on Atmosphere	2	80	75	M			H		H	H					M	H	M	M
CLO-6:	Will be able to analyse the effect of pollutants, Types of pollutants, Controlling of pollutants	1	75	70	H	H	H	H		H	H						H	M	M

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Introduction to Air pollution Control : History of Air pollution control : Dirty Air removal or Emission control	Air pollution measurements, Emission Estimates : Representative Samples, Concentration determination	General ideas in Air Pollution Control: Minimizing Volumetric Flow rate and pressure drop – Efficiency, Penetration, Decontamination factor	CONTROL OF OXIDES OF SULPHUR, NITROGEN AND HYDROCARBONS, CARBON DIOXIDE
S-2	SLO-1	History of Air pollution control: One Problem or Family of Problems ? Emission, Transport, Receptors Units and Standards	Standard Analytical Methods, Emission factor, Visible emission	Homogeneous and Non homogeneous Pollutants, Volume and Composition of Combustion Products	Control of Volatile Organic Compounds (VOC): Vapour Pressure, Equilibrium Vapour Content, Evaporation, VOCs, Control Alternatives
S-3	SLO-1	Air pollution effects : Effect of Air pollution on Human Health Animal Experiments, Regulations to protect Human Health	Meteorology for Air pollution Control Engineers : Horizontal Atmospheric motion, Vertical Atmospheric Motion,	The nature of Particulate Pollutants : Primary and Secondary Particulates	Vapour Pressure, Equilibrium Vapour Content, Evaporation, VOCs, Control Alternatives
S-4	SLO-1	Effect on Property Effect on Visibility	Wind velocity and direction, Temperature Inversions, Fumigations, Stagnations	Settling Velocity and Drag forces, Particle Size Distribution Functions, Behavior of Particles in the Atmosphere	Control of Sulfur Oxides : Overview of Sulphur Problem, Removal of reduced Sulphur Compounds from Petroleum and Natural Gas streams
S-5	SLO-1	Air pollution Control Laws and regulations	Air pollutant Concentration Models: Fixed – Box Models,	Control of Primary Particulates : Wall Collection devices, Dividing Collection Devices	Control of Sulfur Oxides : Overview of Sulphur Problem, Removal of reduced Sulphur Compounds from Petroleum and Natural Gas streams
S-6	SLO-1	Air pollution Control Laws and regulations	Diffusion Model	Control of Primary Particulates : Wall Collection devices, Dividing Collection Devices	Removal of Sulphur dioxide from Rich, Lean Waste Gases Alternatives to "Burn and Then Scrub"
S-7	SLO-1	Air pollution control Philosophies : The Emission Standard Philosophy, Advantages and Disadvantages	Long Term Average Uses of Gaussian Plume Models	Control of Primary Particulates : Wall Collection devices, Dividing Collection Devices	Control of Nitrogen Oxides : Overview of Nitrogen Oxides Problem

S-8	SLO-1	Air pollution control Philosophies. The Air Quality Standard Philosophy, Advantages and Disadvantages	Multiple Cell Models, R	Control of Primary Particulates : Wall Collection devices, Dividing Collection Devices	Control of Nitrogen Oxides : Overview of Nitrogen Oxides Problem	Stratospheric Ozone Depletion and Chlorofluorocarbons, Acid rains
S-9	SLO-1	Emission Tax Philosophy, Cost benefit Philosophy	Receptor – Oriented and Source Oriented Air pollution Models	Control of Primary Particulates : Wall Collection devices, Dividing Collection Devices	Control of Nitrogen Oxide Emissions	Indoor Air Pollution : Indoor and outdoor Concentrations, Models, Control of Indoor Air Quality

Learning Resources	<ol style="list-style-type: none"> 1. Noel De Nevers "Air Pollution Control Engineering" International Editions 1995 McGraw – Hill, Inc 2. Bhartiya S.C "Environmental Pollution and Control in Chemical Process Industries" 3. Perry and Chilton (Editors) "Perry's Chemical Engineer's Hand book
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
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1. Mr. A. Subramaniam, PESCO Beam Environmental Solutions Pvt. Ltd.,	1. Dr. Lima Rose Miranda, Anna University, email: limamiranda2007@gmail.com	1. Dr. B. Karunanithi, SRMIST karunan@srmist.edu.in
2. Mr. S. T. Kalaimani, CPCL, Chennai	2. Dr. T. R. Sundararaman, Rajalakshmi Engineering College	

Course Code	18CHE364T	Course Name	FINE CHEMICALS TECHNOLOGY	Course Category	E	PROFESSIONAL ELECTIVE	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Chemical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1:	Understand the basic fundamentals of drug chemistry	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2:	Learn the various chemical reactions involved in drug formulation		
CLR-3:	Exposure on basic concepts and principles of drug production techniques		
CLR-4:	Impart the knowledge of various parameters involved in the formulation and development of various dosage forms		
CLR-5:	Familiarize the concept of the pharmaceutical industrial manufacturing practices		
CLR 6:	Learn the quality aspects in Pharmaceutical industry		

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (loom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO -3
CLO-1:	Identify the basic concept of drug formulation and their importance in Pharmaceutical Industry	2	90	85	L	L	M	L		M	M	M			M	H	L	L	
CLO-2:	Recognize the different types of reactions involved in bulk drug production	2	80	75	L	L	M	M		M	M	L			M	L	M	L	
CLO-3:	Review the techniques involved in production of drugs	2	80	80	M	L	M	L		M	M				M	L	H	L	
CLO-4:	Implement the methods for drug development	3	75	70	M	L	M	M		M	M				M	L	H	M	
CLO-5:	Investigate the production planning, scheduling and quality management	4	80	75	M	M	H	L		M	M				M	L	M	M	
CLO 6:	Understand the importance of quality attributes of pharmacy products	3	80	75	L	L	M	L		H	M				M	L	L	H	

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Overview of fine chemicals and bulk drugs	Production of fine chemicals	Bulk drug production	Overview of drug Formulation and Pre-formulation development	Overview of production plants
	SLO-2 Characteristic features of fine chemicals manufacture	Unit operations involved in production	Selection of Raw materials for bulk drugs production	Solid and Semi-solid dosage forms	Types of production plants
S-2	SLO-1 Catalysis in fine chemistry	Chemical conversion processes for drug formulation	Various Bulk drugs	Tablet formulation techniques	Dedicated and multipurpose plants
	SLO-2 Selectivity Engineering	Alkylation- reactions involved	Production Techniques	Compressed tablets	Mixed plants
S-3	SLO-1 Process development	Drug production by Carboxylation	Reaction for bulk drugs	Capsules	Equipments in multipurpose plants-Reactors
	SLO-2 Separation methods, Production plants	Carboxylation –reactions and process	Flow Sheet for bulk drugs	Capsules	filters ,centrifuges
S-4	SLO-1 Concept of fine drugs	Condensation	bulk drug production	Polymers and Powder formulation	Driers, extractors
	SLO-2 Bulk drugs and their manufacture	Cyclisation	Equipments for bulk drug production	Milling process	evaporators
S-5	SLO-1 Evolution of process	Dehydration	Paracetamol	Granulation Techniques –Wet Granulation	Production cost
	SLO-2 Process selection: process profile analysis	Esterification	Aspirin	Dry Granulation	capital investment costs, operating costs
S-6	SLO-1 Factors influencing Process choice	Halogenation	Ibuprofen,	Coating techniques in drugs	Batch process
	SLO-2 cleaner and safer technologies	Reaction and process involved	Diazepam	Coating techniques in drugs	Designing of batch plants.
S-7	SLO-1 waste minimization	Oxidation	Darvon	Topical formulation	production planning
	SLO-2 The role of catalysis in waste minimization	Sulfonation	Niacinamide	cutaneous and Inhaled	production planning
S-8	SLO-1 Research in pharmaceutical Industries	Complex Chemical conversions	Chloramphenicol	Polymeric nanoparticles formulation methods	Production scheduling
	SLO-2 Development strategies in pharmaceutical Industries	Complex Chemical conversions	Erythromycin	Targeting	Production scheduling
S-9	SLO-1 Basic drug formulation	Industrial Fermentation products	Antimicrobial agent	Microparticles	Principles of good manufacturing practices
	SLO-2 Radiopharmaceuticals	Industrial Fermentation products	Antimicrobial agent	Microparticles synthesis for drug delivery system	Quality control

Learning Resources	1. AndrzejCybulski , Jacob A. Moulijn , M.M. Sharma , Roger A. Sheldon "Fine Chemicals Manufacture: Technology and Engineering" Elsevier ScienceB.V,2001 2. Rawlins E.A, Bentleys Text Book of Pharmaceutics, A.I.T.B.S.Publisher& Distributors, Delhi, 1996 3. B.M. Mithal., "A textbook of Pharmaceutical formulation", published by vallabhprakashan, 15th reprint 2013, ISBN 81-85731-04-7	3. Rebecca A.Bader, David., "Engineering Polymer systems for improved drug" Wiley publication, December 2013, ISBN: 979-1-118-09847-9 4. Shah, K.M., "Hand Book of Industrial Chemistry", Vol. I and II, Multi-Tech Publishing Co, 1999
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

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1. Mr. A. Subramaniam, PESCO Beam Environmental Solutions Pvt. Ltd.,	1. Dr. Lima Rose Miranda, Anna University, email: limamiranda2007@gmail.com	1. Ms. S. Kiruthika SRM Inst. of Science & Technology, kiruthika. s@ktr.srmuniv.ac.in
2. Mr. S. T. Kalaimani, CPCL, Chennai	2. Dr. T. R. Sundararaman, Rajalakshmi Engineering College	2. Dr. P. Muthamilselvi SRM Inst. of Science & Technology, muthamilselvi.p@ktr.srmuniv.ac.in

Course Code	18CHE365T	Course Name	WASTE WATER TREATMENT	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Chemical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1:	study characteristic of waste water	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2:	Familiarize the different conventional wastewater treatment methods		
CLR-3:	Introduce students to the unit operations and processes used in the advanced treatment of wastewater.		
CLR-4:	Pollution control methods used in a few typical chemical process industries		
CLR-5:	Learn issues involved in water reduce, recover and reuse		
CLR-6:	Get wholesome knowledge of water treatment processes		

Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:										Level of Thinking	Expected	Expected	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Management	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1:	Examine various characteristic of waste water	4	80	75	H			M			M									M					M	H			
CLO-2:	Understand the different conventional treatment process	2	80	70	H			M			M									M					M		H		
CLO-3:	Review the advanced wastewater treatment process	2	80	75	H			M			M									M					M	H		H	
CLO-4:	Understand the block diagram of various industrial effluent treatment	2	80	75	H			M			M									M					M	H		M	
CLO-5:	Understand the different concept of reduce, recover and reuse of waste water	2	80	75	M			H			M									M					M	H		M	
CLO-6:	To select appropriate water treatment system to conserve water	2	80	70	H			H			H									H							H		H

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Waste water sources	Philosophy of waste treatment	Aim of the advanced wastewater Treatment	Water treatment in chemical process industries	Volume reduction – concept of water recovery
	SLO-2	Industrial waste water	Preliminary treatment process	Types of advanced wastewater Treatment	Characteristics of pulp and paper industry waste water	Volume reduction: recycle
S-2	SLO-1	Agricultural waste water	Primary treatment :- screens filters process	Removal of suspended solid	Pulp and paper industry waste water treatment process	Concept of common effluent treatment plants
	SLO-2	Domestic waste water	Primary treatment: gravity settling process	Coagulation process	Characteristics of fertilizer industry waste water	Concept of common effluent treatment plants
S-3	SLO-1	Quantum of waste water produced by industries	Secondary treatment - Aerobic treatment process	Flocculation process	Fertilizer industry waste water treatment process	Philosophy of waste treatment
	SLO-2	Comparison of world and Indian scenario	Activated sludge treatment process	Removal of dissolved solids	Physio chemical characteristics of tannery effluent	Conventional dilute & disperse
S-4	SLO-1	Assessment of waste water composition	Different types of activated sludge process	Ion exchange treatment process	Chrome treat process	current philosophy treat and dispose
	SLO-2	Types of water pollutants	Biological processes in activated sludge process	Osmosis and reverse osmosis process	Overview of tannery effluent treatment	Future philosophy; recover and reuse
S-5	SLO-1	Water pollutants effects	Attached growth aerobic processes	Electro dialysis process	Characteristics of petroleum refinery waste water	Wealth from waste
	SLO-2	waste water sampling	Tricking filters process	Removal of nitrogen compound in water	Overview of refinery effluent treatment	Value recovery – need for value recovery
S-6	SLO-1	Waste water analysis	Rotating biological contactors	Phosphate removal from waste water	Characteristics of petrochemical effluent	Water conservation
	SLO-2	Determination of organic content: BOD,COD,DO	Anaerobic treatment process	Removal of dissolved organic compounds	Petrochemical effluent treatment process	Types of reuse waste water
S-7	SLO-1	Determination of inorganic content	Design of Anaerobic digester	Adsorption process	Characteristics of sugar industry waste water	Zero Liquid Discharge
	SLO-2	Determination of carbonate ions	Mechanism of anaerobic degradation	Different membrane processes	Overview of sugar effluent treatment process	Zero Liquid Discharge
S-8	SLO-1	Determination of alkalinity	Sludge Treatment: Volume Reduction	Membrane treatment: MF, UF and NF	Physio chemical characteristics of distilleries effluent	Regulations for treatment

	SLO-2	Determination of TSS and TDS	Sludge Treatment - Dewatering; Sludge drying; Composting	Different types of disinfection process	Distilleries industry waste water treatment process	ALARA concept
S-9	SLO-1	Determination of physical characteristics	Sludge Treatment: Fluidized bed incineration	Disinfection: chlorination process	Characteristics of textile industry waste water	Pollution control board regulations
	SLO-2	Determination of bacteriological measurements	Sludge Disposal methods	Disinfection: chlorination process uv-treatment	Overview of textile effluent treatment process	Pollution control board regulations

Learning Resources	<ol style="list-style-type: none"> 1. Rao C.S., <i>Environmental Pollution Control Engineering</i>, Wiley Eastern Limited, 1991 2. Eldridge, E.F, "Industrial Waste Treatment Practice", McGraw-Hill Book Company, Inc., New York, NY, 1942 3. Metcalf & Eddy, "Wastewater Engineering Treatment and Reuse", 4th Edn., Tata McGraw-Hill Publishing Company, New Delhi, 2003
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

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2. Mr. S. T. Kalaimani, CPCL, Chennai	2. Dr. T. R. Sundararaman, Rajalakshmi Engineering College	2. Dr. K. Tamilarasan SRM Inst. of Science & Technology, tamilarasan.k@srmuniv.ac.in

Course Code	18CHE366T	Course Name	CHEMICAL PROCESS OPTIMIZATION	Course Category	E	PROFESSIONAL ELECTIVES	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Chemical Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1:	understand the basic concepts of optimization	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2:	introduce the optimization methods for multivariable functions		
CLR-3:	familiarize the single variable function optimization		
CLR-4:	introduce the linear programming method and unconstrained optimization		
CLR-5:	understand the optimization methods in chemical process		
CLR-6:	understand optimization techniques for types of functions, linear programming method, unconstrained optimization and optimization of chemical process		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (loom)	Engineering Knowledge
CLO-1:	remember and recollect the basic concepts of optimization	2 85 75	H H H H
CLO-2:	apply methods for multivariable function optimization	3 75 70	H H H H M
CLO-3:	understand the single variable function optimization	3 85 75	M H H H M
CLO-4:	Solve linear programming and unconstrained optimization problems	3 85 75	H H H H M
CLO-5:	calculate optimized conditions for chemical processes	3 85 75	H H H H M
CLO-6:	calculate optimized variables for different functions, solve linear programming problems and optimized conditions for real chemical processes	3 85 75	H H H H M

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Need for optimization	Unimodal and multi modal functions	Optimization of unconstrained functions	Concept and applications of linear programming
	SLO-2	Hierarchy of levels of optimization	Unconstrained multivariable optimization	Newton method of uni – dimensional search	Geometry of linear programming problems
S-2	SLO-1	Applications and essential features of optimization problems	Random search method grid search method	Quasi-newton method	Standard form for linear programs
	SLO-2	Statement of an optimization problem	Univariate search	Problems based on newton and quasi – newton method	Basic linear programming definitions
S-3	SLO-1	Terms used in optimization	Simplex search method nelder – mead method	Problems based on newton and quasi – newton method	Equivalent systems and elementary operations
	SLO-2	Classification of optimization problems	Hooke-jeeves procedure	Problems based on newton and quasi – newton method	Concept of pivoting and use of pivot operations
S-4	SLO-1	Formulation of the objective functions	Steepest descent method	Quadratic interpolation method	Simplex method for linear programming problems
	SLO-2	Problem based on objective function formation	Steepest descent method	Quadratic interpolation method	Simplex method for linear programming problems
S-5	SLO-1	Necessary and sufficient conditions for optimum	Conjugate gradient method	Cubic interpolation method	Problem based on simplex method
	SLO-2	Steps to solve optimization problems	Conjugate gradient method	Cubic interpolation method	Problem based on simplex method
S-6	SLO-1	Problems based on analytical optimization methods	Problems based on conjugate gradient method	Problems based on cubic and quadratic interpolation method	Integer programming method
	SLO-2	Problems based on analytical optimization methods	Problems based on conjugate gradient method	Problems based on cubic and quadratic interpolation method	Graphical solution for integer linear programming
S-7	SLO-1	Problems based on analytical optimization methods	Newton's method	Problems based on cubic and quadratic interpolation method	Geometric programming method – unconstrained minimization

	SLO-2	Problems based on analytical optimization methods	Problem solving based on newton's method	Problems based on cubic and quadratic interpolation method	Geometric programming method – unconstrained minimization	Process simulators and optimization codes
S-8	SLO-1	Classification of models and mathematical forms of models	Quasi – newton method	Fibonacci method	Dynamic programming method	Optimization using equation-based process simulators
	SLO-2	Classification of models and mathematical forms of models	Lagrange multiplier method	Fibonacci method	Dynamic programming method	Optimization using equation-based process simulators
S-9	SLO-1	Selecting functions to fit empirical data	Problems based on lagrange multiplier method	Golden section method	Quadratic programming method	Optimization using modular-based simulators
	SLO-2	Fitting models by least squares	Problems based on lagrange multiplier method	Golden section method	Quadratic programming method	Optimization using modular-based simulators

Learning Resources	1. Thomas F. Edgar, David M. Himmelblau, Leon S. Lasdon, "Optimization of Chemical Processes", 2nd edition, McGraw-Hill Higher Education, 2001. 2. Singiresu S. Rao, "Engineering Optimization: Theory and Practice", 4th edition, John Wiley & Sons, Inc., 2009.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. A. Subramaniam, PESCO Beam Environmental Solutions Pvt. Ltd.,	1. Dr. Lima Rose Miranda, Anna University, email: limamiranda2007@gmail.com	1. Dr. M. Magesh Kumar SRM Inst. of Science & Technology, mageshkm@srmist.edu.in
2. Mr. S. T. Kalaimani, CPCL, Chennai	2. Dr. T. R. Sundararaman, Rajalakshmi Engineering College	2. Dr. S. Vishali SRM Inst. of Science & Technology, vishalis@srmist.edu.in

Course Code	18CHE367T	Course Name	EQUILIBRIUM STAGE OPERATIONS				Course Category	E	Professional elective										L	T	P	C					
																			3	0	0	3					
Pre-requisite Courses		18CHC303T		Co-requisite Courses		Nil		Progressive Courses		Nil																	
Course Offering Department		Chemical Engineering				Data Book / Codes/Standards				Nil																	
Course Learning Rationale (CLR):		The purpose of learning this course is to						Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Understand fundamental concepts of equilibrium-governed separation processes						Level of Thinking (loom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15			
CLR-2 :	Understand the cascade configurations in chemical process systems									Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO -3			
CLR-3 :	Acquire knowledge of concepts involved in absorption and distillation																										
CLR-4 :	Acquire knowledge of liquid-liquid extraction and solid-liquid extraction operations																										
CLR-5 :	Understand principles of adsorption and its applications																										
CLR-6 :	Understand the concepts underlying equilibrium stage operations in chemical engineering																										
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:						2	80	75	H			M								H					
CLO-1 :	Explain various equilibrium governed separation processes						2	80	75	H			M										H				
CLO-2 :	Analyze cascade configurations for multicomponent separations						2	75	70	H			M										H				
CLO-3 :	Perform calculations for absorption and distillation columns						2	75	75	H	M			M									H	M			
CLO-4 :	Perform calculations for extraction systems and compare various configurations						2	80	75	H	H	L		M									H	M			
CLO-5 :	Perform adsorption bed related calculations						2	75	70	H		H		M									H	M			
CLO-6 :	Understand and perform calculations in equilibrium stage operations						2	75	70	H	M	M	M										H	M			
Duration (hour)	9			9			9			9			9			9			9			9			9		
S-1	SLO-1	Overview of different separation processes		Typical cascade configurations		Equilibrium in a gas-liquid system		Liquid-liquid extraction			Adsorption, isotherms																
	SLO-2	Overview of separation processes		Hybrid systems		Equilibrium in a gas-liquid system		Liquid-liquid extraction			Isotherms																
S-2	SLO-1	Characteristics of separation processes		General approach to analysis of equilibrium governed operations		Stage calculations for absorption and stripping		Solvent selection			Equilibrium considerations in adsorption																
	SLO-2	Types of separating agents		General approach to analysis of equilibrium governed operations		Examples		Solvent selection			Equilibrium considerations in adsorption																
S-3	SLO-1	Separation factors		General approach to analysis of equilibrium governed operations		Batch distillation-binary and multicomponent mixtures		Ternary phase diagrams			Kinetic and transport considerations																
	SLO-2	Practice session for separation factors based problems		Examples		Batch distillation-binary and multicomponent mixtures		Problem solving			Kinetic and transport considerations																
S-4	SLO-1	Sequence of separations		Mass transfer in stage-wise contact of two phases		Continuous multistage distillation of binary mixtures		Single stage			Adsorption in a fixed bed																
	SLO-2	Examples		Mass transfer in stage-wise contact of two phases		Examples		Problem solving			Adsorption in a fixed bed																
S-5	SLO-1	Heuristics for separation schemes		Mass transfer in stage-wise contact of two phases		Multiple feed and product withdrawal		Multistage single section cascades			Design calculations of fixed bed adsorption																
	SLO-2	Examples		Examples		Problem solving		Multistage single section cascades			Design calculations of fixed bed adsorption																
S-6	SLO-1	Review of thermodynamics principles, phase equilibrium		Stage Calculations for cocurrent, cascades		Multicomponent distillation		Design calculations			Design calculations of fixed bed adsorption																
	SLO-2	Ideal and non-ideal solutions, activity coefficients		Problem solving		Key components		Problem solving			Design calculations of fixed bed adsorption																
S-7	SLO-1	Simple equilibrium processes		Crosscurrent cascades		Approximate Methods- Fenske-underwood – Gilliland method		Solid-liquid extraction			Problem solving																
	SLO-2	Single equilibrium stage		Crosscurrent cascades		Problem solving		Solid-liquid extraction			Problem solving																
S-8	SLO-1	Checking phase condition of a mixture		Countercurrent Cascades		Enhanced distillation- extractive distillation		Rate of solid-liquid extraction			Ion-exchange																
	SLO-2	Examples		Problem solving		Azeotropic distillation, reactive distillation		Rate of solid-liquid extraction			Ion-exchange																
S-9	SLO-1	Flash calculations		Kremser equation		Residue-curve maps		Supercritical fluid extraction			Chromatography																
	SLO-2	Binary and multicomponent systems flash equations		Problem solving		Residue-curve maps		Supercritical fluid extraction			Chromatography																

Learning Resources	1. <i>Principles of Mass Transfer and Separation Processes</i> , PHI Learning Pvt. Ltd. 2007 2. <i>J. D. Seader, Ernest J. Henley, D. Keith Roper, Separation process principles : chemical and biochemical operations, 3rd edn, 2011</i>
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
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1. Mr. A. Subramaniam, PESCO Beam Environmental Solutions Pvt. Ltd.,	1. Dr. Lima Rose Miranda, Anna University, email: limamiranda2007@gmail.com	1. Dr. Ashish Kapoor SRM Inst. of Science & Technology, ashishko@srmist.edu.in
2. Mr. S. T. Kalaimani, CPCL, Chennai	2. Dr. T. R. Sundararaman, Rajalakshmi Engineering College	2. Dr. K. Suresh SRM Inst. of Science & Technology, sureshk@srmist.edu.in

Course Code	18CHE368T	Course Name	COMPUTATIONAL FLUID DYNAMICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18CHC205T 18CHC207T	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Chemical Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1:		Discretize the conservation law equations			1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:		Solve the conservation equations by numerical techniques			Level of Thinking (loom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3:		Understand fundamentals underlying Computational fluid dynamic simulations																				
CLR-4:		Understand the flow and temperature field in engineering problems																				
CLR-5:		Learn to assess the quality of numerical results																				
CLR-6:		Acquire knowledge to solve computational fluid dynamics related problems																				
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1:	Appreciate role and importance of CFD and learn underlying fundamental principles			2	80	75	H					L										
CLO-2:	Understand CFD solution methodologies, sources of error			2	75	70	H	M				L										
CLO-3:	Apply discretization using Finite difference method approach			2	75	75	H				L										H	
CLO-4:	Apply discretization using Finite volume method approach			2	80	75	H				L									H		
CLO-5:	Apply discretization using Finite difference element approach, TDMA			2	75	70	H				L											M
CLO-6:	Apply computational knowledge in solving transport processes related problems in chemical engineering			2	75	70	H	M	L	L	L									H	H	

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Introduction to CFD	CFD solution procedure	Types of PDEs	Finite volume method introduction	Finite element method introduction
	SLO-2 Applications	CFD solution procedure	Examples		
S-2	SLO-1 CFD solution strategies	Physical and computational domains	Solution using discretization scheme	General representation form of conservation equation	Concept of weighted residual approach
	SLO-2 CFD solution strategies	Physical and computational domains	Examples	Physical meaning	Concept of weighted residual approach
S-3	SLO-1 Vector and calculus review for fluid dynamics	Boundary conditions	Finite difference methods	Finite volume method procedure of discretization	FEM method of discretization
	SLO-2 Derivation and physical meaning of substantial derivative	Boundary conditions examples	Forward, backward and central difference schemes	Finite volume method procedure of discretization	FEM method of discretization
S-4	SLO-1 Introduction to tensors	Types of mesh	Converting derivatives to algebraic equations	Implementation of boundary conditions- temperature and heat flux	FEM application for 1D steady state heat conduction
	SLO-2 Problem solving	mesh quality parameters	Converting derivatives to algebraic equations	Examples	Problem solving
S-5	SLO-1 Types of models	Solver settings	Converting mixed derivatives to algebraic equations	1-D steady state heat conduction with source	Implementation of boundary conditions
	SLO-2 Types of models	Convergence	Graphical representation	Examples	Problem solving
S-6	SLO-1 Continuity equation derivation based on different models	Types of error	General approach to difference equations for uniform grid	FVM: 1-D steady state diffusion equation problem without source	Solution of system of linear algebraic equations
	SLO-2 Derivation	Types of error	Examples	FVM	Solution of system of linear algebraic equations
S-7	SLO-1 Problem solving	Sources of error	Polynomial approach for finite difference equations	1-D convection and diffusion	Tridiagonal matrix algorithm
	SLO-2 Problem solving	Sources of error	Illustrative examples	Examples	Tridiagonal matrix algorithm
S-8	SLO-1 Momentum balance	Post processing	Implementation of boundary conditions	Problem solving	Problem solving
	SLO-2 Momentum balance	Post processing	Merits and limitations of FDM	Problem solving	Problem solving
S-9	SLO-1 Navier Stokes equation	Examples of CFD solutions	Problem solving	Problem solving	Problem solving
	SLO-2 Navier Stokes equation	Problem solving	Problem solving	Problem solving	Problem solving

Learning Resources	<ol style="list-style-type: none"> 1. H. K. Versteeg and W. Malalasekera, <i>An introduction to computational fluid dynamics – The finite volume method</i>, Longman Group Ltd 1995. 2. J.H. Ferziger and M. Peric, <i>Computational Methods for Fluid Dynamics</i>, Springer, 2002. 3. Tu, Jiyuan, Guan-Heng Yeoh, and Chaoqun Liu. <i>Computational fluid dynamics: a practical approach</i>. Butterworth-Heinemann, 2018.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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2. Mr. S. T. Kalaimani, CPCL, Chennai	2. Dr. T. R. Sundararaman, Rajalakshmi Engineering College	2. Dr. K. Suresh SRM Inst. of Science & Technology, sureshk@srmist.edu.in

Course Code	18CHE369T	Course Name	BIOCHEMICAL PROCESS DESIGN	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Chemical Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1:	Understand the basic configuration, accessories and types of bioreactor	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2:	Understand the scale-up criteria for bioreactors		
CLR-3:	Learn the different control requirements of a bioreactor		
CLR-4:	Understand the different methods of product recovery and purification		
CLR-5:	Understand the process of synthesis of various bioproducts		
CLR-6:	Understand the operation of bioreactors		

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (loom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO- 1:	Select the required bioreactor for a given process	3	80	75	M	L	L	L			M						M		M
CLO-2:	Formulate the scale-up of bioreactor in industrial processes	3	75	70	M	M	M	M									M		M
CLO-3:	Comprehend the different types of instruments and controllers used in bioprocess industries	2	75	70	M		M	L	M		M						M		
CLO-4:	Analyze the various stages of product recovery	4	80	75	H	M	M	M	M		M						M	H	M
CLO-5:	Appreciate the industrial scale synthesis of various bioproducts	3	75	70	H	H	H	H	M		H						M	M	M
CLO-6:	Apply the knowledge of reactor design for novel products/processes	3	75	70	M	M	M	M	M		M						M	M	M

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction to Bioreactors	Biochemical reactor scale-up	Instrumentation control of bioreactors	Product recovery operation	Industrial bioprocess technology
	SLO-2	Basic principle of bioreactor	Transport phenomena in Bioprocess systems	Measurement of physical and chemical parameters in bioreactors	Separation of biomolecules	Aerobic processes
S-2	SLO-1	Components of bioreactor	Gas-liquid mass transfer	Bioreactor sensor s for temperature control	Cell disruption for release of products	Production of citric acid
	SLO-2	Classification and configuration of bioreactors	Determination of oxygen transfer rates	Principles of dissolved oxygen measurement and control	Cell disruption for release of products	Production of penicillin
S-3	SLO-1	Analysis of batch bioreactors	Measurement of k_{La}	Principles of pH control	Mechanical methods of cell disruption	Anaerobic bioprocesses
	SLO-2	Analysis of batch bioreactors	Measurement of k_{La}	Principles of redox measurement and control	Enzymatic methods of cell disruption	Anaerobic bioprocesses
S-4	SLO-1	Analysis of continuous flow bioreactors	Key dimensionless groups	On-line sensors	Chemical methods of cell disruption	Production of ethanol
	SLO-2	Analysis of continuous flow bioreactors	Correlations for mass transfer co-efficients and interfacial area	Off-line analytical methods	Cells and solid particle separation	Production of lactic acid
S-5	SLO-1	Analysis of fed-batch bioreactors	Overall k_{La} estimates and power requirement for sparged and agitated vessels	Measurement of medium properties	Filtration	Acetone-butanol production
	SLO-2	Design of novel biochemical reactors	Overall k_{La} estimates and power requirement for sparged and agitated vessels	Analysis of cell population composition	Filtration	Production of biopolymers
S-6	SLO-1	Operation of novel biochemical reactors	Heat transfer	Prevention of foam	Centrifugation	Production of Xanthan gum
	SLO-2	Air-lift loop reactors	Heat transfer correlations	Determination of biomass	Centrifugation	Production of Xanthan gum
S-7	SLO-1	Fluidized bed biochemical reactors	Scaling of mass transfer equipment	Application of biosensors	Product isolation	Production of PHB
	SLO-2	Immobilized enzyme reactors	Scaling of mass transfer equipment	Application of biosensors	Product isolation	Production of PHB
S-8	SLO-1	Design of immobilized enzyme reactors	Regime analysis of Biochemical reactor processes	Design and operation strategies for batch operation	Adsorption	Production of single cell protein
	SLO-2	Packed bed reactors	Regime analysis of Biochemical reactor processes	Design and operation strategies for batch operation	Liquid-liquid extraction	Production of single cell protein
S-9	SLO-1	Fluidized bed reactors	Scale-up criteria for bioreactors based on oxygen transfer and power consumption	Continuous process control	Product purification- Chromatography	Production of vinegar
	SLO-2	Membrane reactors	Scale-up criteria for bioreactors based on oxygen transfer and power consumption	Continuous process control	Product purification- Chromatography	Production of vinegar

Learning Resources	1. Bailey, J.E. and Ollis, D.F. "Biochemical Engineering Fundamentals", 2 nd edition, McGraw– Hill, 1988. 2. Peter F. Stanbury, Allan Whitaker, "Principles of Fermentation Technology", 2 nd edition, Butterworth – Heinemann (an imprint of Elsevier), 1995. 3. Shuler, M.L. and Kargi, F. "Bioprocess Engineering: Basic Concepts", 2 nd edition, PHI, 2002.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

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2. Mr. S. T. Kalaimani, CPCL, Chennai	2. Dr. T. R. Sundararaman, Rajalakshmi Engineering College	2. Dr. M. P. Rajesh SRM Institute of Science & Technology, hod.chem@ktr.srmuniv.ac.in

Course Code	18CHE370T	Course Name	MICROCHEMICAL SYSTEMS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18CHC205T	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Chemical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):	The purpose of learning this course is to	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Concept of lab-on-a-chip and its significance and relevance	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Fundamental transport processes relevant to micro scale devices		
CLR-3 :	Acquire knowledge of various microfabrication methods and relevant material science		
CLR-4 :	Get a basic knowledge of design, simulation, and experimental methods at microscale		
CLR-5 :	Get exposure to wide range of applications of microchemical systems		
CLR-6 :	Get basic understanding of engineering principles related to microchemical systems		

Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:															Level of Thinking	Expected	Expected	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Management & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Understand lab on chip concept and importance	2	80	75	H		L	M	H																					M				
CLO-2 :	Understand principles of engineering applicable at microscale	2	75	70	H		M																							H				
CLO-3 :	Understand various methods of fabrication and materials for designing microdevices	2	75	75	H		H	M																						M				
CLO-4 :	Understand fundamentals of design, simulation and experimental approaches for microscale systems	2	80	75	H	M	H																							M				
CLO-5 :	Appreciate wide variety of applications possible with microchemical systems	2	75	70	M		M	M	H																						H			
CLO-6 :	Understand principles of microchemical systems	2	75	70	H	M	M	M	H																			H	M		H			

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Concept of lab-on-a-chip and microfluidics	Principles in microfluidics	Microfabrication techniques	Concepts and approach from design to realization	Miniaturized chemical systems
	SLO-2 Concept of lab-on-a-chip and microfluidics	Principles in microfluidics	Microfabrication techniques	Concepts and approach from design to realization	Miniaturized chemical systems
S-2	SLO-1 Origins and motivation	Navier-stokes equation at microscale	Conventional methods	Tools for design	Microreactors
	SLO-2 Origins and motivation	Navier-stokes equation at microscale	Origins	Tools for design	Microreactors examples
S-3	SLO-1 Advantages, limitations, interdisciplinary approach	Multiphase flows	Photolithography	Tools for modeling and simulation	Process intensification principles
	SLO-2 Advantages, limitations, interdisciplinary approach	Multiphase flows	Photolithography	Tools for modeling and simulation	Process intensification examples
S-4	SLO-1 Range of applications- basic sciences	Capillary action	Micromachining	Examples of design and simulation	Point-of-care devices: principles
	SLO-2 Range of applications- basic sciences	Capillary action	Micromachining	Examples of design and simulation	Point-of-care devices: examples
S-5	SLO-1 Range of applications- applied areas of science and engineering	Mixing at microscale and	Etching	Experimental methods at microscale	Sensors
	SLO-2 Range of applications- applied areas of science and engineering	Mixing at microscale and	Etching	Experimental methods at microscale	Sensors for environmental quality monitoring
S-6	SLO-1 Scale out approach	Enhancing mixing	Soft lithography fundamentals	Experimental methods: components pumps	Biomedical diagnostics principles
	SLO-2 Scale out approach	Enhancing mixing	Soft lithography fundamentals	Experimental methods: valves	Biomedical diagnostics examples
S-7	SLO-1 Commercialized technologies	Separations at microscale	Soft lithography applications	Measurements at microscale, pressure, flow rate,	Energy generation devices
	SLO-2 Commercialized technologies	Separations at microscale	Soft lithography applications	Measurements at microscale, pressure, flow rate,	Micro fuel cells
S-8	SLO-1 Challenges	Heat transfer in microchannels,	Alternative fabrication strategies	Temperature measurements	Integrated systems principles
	SLO-2 Challenges	Heat transfer in microchannels,	Unconventional fabrication	Temperature measurements	Integrated systems examples
S-9	SLO-1 Opportunities	Numerical problems	Materials in fabrication: traditional	Analytical techniques	Biomimetics
	SLO-2 Opportunities	Examples	Materials in fabrication: emerging	Analytical techniques examples	Biomimetics

Learning Resources	1. Kirby, B.J., <i>Micro- and Nanoscale Fluid Mechanics: Transport in Microfluidic Devices</i> , Cambridge University Press, 2010. 2. Nguyen, N. T., Wereley, S. T., <i>Fundamentals and applications of Microfluidics</i> , Artech house Inc., 2002 3. Madou, M. J., <i>Fundamentals of Microfabrication</i> , CRC press, 2002.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. A. Subramaniam, PESCO Beam Environmental Solutions Pvt. Ltd.,	1. Dr. Lima Rose Miranda, Anna University, email: limamiranda2007@gmail.com	1. Dr. Ashish Kapoor SRM Inst. of Science & Technology, ashishko@smist.edu.in
2. Mr. S. T. Kalaimani, CPCL, Chennai	2. Dr. T. R. Sundararaman, Rajalakshmi Engineering College	

Course Code	18CHE371T	Course Name	ELECTROCHEMICAL ENGINEERING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Chemical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Understand the concept of electrochemistry	Level of Thinking (loom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2 :	Acquire knowledge on electrochemical processes																							
CLR-3 :	Understand the concepts of corrosion and its types																							
CLR-4 :	Application of electrochemical concepts on environmental issues																							
CLR-5 :	Use of different electrodes and reactors in electrochemical reactor design																							
CLR-6 :	Expose to the importance of electrochemical process on chemical industries																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1 :	Derive the relation between emf and rate of reaction	2	80	70	M	L	L	L						M		M			M	L	L	L		
CLO-2 :	Analyze the mass transfer operations in electrochemical process	2	80	70	H	H	H	M						M		H			M	L	M	L		
CLO-3 :	Relate the corrosion phenomenon with electrochemical reactions	2	75	65	M	L	M	M						H		M			H	L	M	M		
CLO-4 :	Able to use electrochemical energy for environmental issues	3	80	75	H	H	H	M						H		H			H	M	L	M		
CLO-5 :	Ability to design the electrochemical reactor	3	80	70	H	H	H	H						H		H			H	M	H	H		
CLO-6 :	Design electrochemical process for industrial concerns	3	70	60	H	H	M	L						H		M			M	L	M	M		

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Course introduction	Mass transfer in electrochemical systems:	Derivation of potential current relations of activities controlled and diffusion controlled corrosion process.	Electro deposition	Electrodes used in different electrochemical industries
	SLO-2	Review basics of electrochemistry	Mass transfer in electrochemical systems:	Derivation of potential current relations of activities controlled and diffusion controlled corrosion process.	Electro deposition	Electrodes used in different electrochemical industries
S-2	SLO-1	Faraday's law, nemst potential	Diffusion controlled electrochemical reaction	Potential-ph diagram	Electro refining	Metals-graphite –lead dioxide –titanium substrate insoluble electrodes
	SLO-2	Faraday's law, nemst potential	Diffusion controlled electrochemical reaction	Potential-ph diagram	Electro refining	Metals-graphite –lead dioxide –titanium substrate insoluble electrodes
S-3	SLO-1	Galvanic cells	Importance of convention	Forms of corrosion	Electroforming	Iron oxide –semi conducting type etc.
	SLO-2	Galvanic cells	Importance of convention			
S-4	SLO-1	Polarography	Importance of the concept of limiting current	Definition, factors and control methods of various forms of corrosion	Electro polishing	Metal finishing-cell design.
	SLO-2	Polarography	Importance of the concept of limiting current	Definition, factors and control methods of various forms of corrosion	Electro polishing	Metal finishing-cell design
S-5	SLO-1	Electrical double layer	Over potential	Corrosion control measures industrial boiler water corrosion control	Anodizing	Types of electrochemical reactors
	SLO-2	Electrical double layer	Over potential	Corrosion control measures industrial boiler water corrosion control	Anodizing	Types of electrochemical reactors
S-6	SLO-1	Role of electrical double layer in electrochemical processes	Primary-secondary current distribution	Protective coatings	Selective solar coatings	Batch cell, fluidized bed electrochemical reactor
	SLO-2	Role of electrical double layer in electrochemical processes	Primary-secondary current distribution	Protective coatings	Selective solar coatings	Batch cell, fluidized bed electrochemical reactor
S-7	SLO-1	Electro capillary curve	rotating disc electrode	Vapor phase inhibitors	Primary and secondary batteries	filter press cell, Swiss roll cell

	SLO-2	Electro capillary curve	rotating disc electrode	Vapor phase inhibitors	Primary and secondary batteries	filter press cell, Swiss roll cell
S-8	SLO-1	Helmholtz layer	Corrosion	cathodic protection	types of batteries	plug flow cell, design equation,
	SLO-2	Helmholtz layer	Corrosion	cathodic protection	types of batteries	plug flow cell, design equation,
S-9	SLO-1	Guoy, Steven's layer, fields at the interface	Introduction to corrosion, series and corrosion theories	sacrificial anodes –Paint removers	Fuel cells	Figures of merits of different type of electro chemical reactors.
	SLO-2	Guoy, Steven's layer, fields at the interface	Introduction to corrosion, series and corrosion theories	sacrificial anodes –Paint removers	Fuel cells	Figures of merits of different type of electro chemical reactors.

Learning Resources	1. Picket, "Electrochemical Engineering ", Prentice Hall. 1977. 2. Newman, J. S., "Electrochemical systems ", Prentice Hall, 1973.	3. Barak, M. and Stevenge, U. K., " Electrochemical Power Sources – Primary and Secondary Batteries" 1980 4. Mantell, C. "Electrochemical Engineering ", McGraw Hill, 1972.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. 1. Mr. A. Subramaniam, PESCO Beam Environmental Solutions Pvt. Ltd.,	1. Dr. Lima Rose Miranda, Anna University, email: limamiranda2007@gmail.com	1. Dr. S. Sam David SRM Inst. Of Science and Technology samdavid@srmist.edu.in
2. 2. Mr. S. T. Kalaimani, CPCL, Chennai	2. Dr. T. R. Sundararaman, Rajalakshmi Engineering College	2. Dr. K. Deepa SRM Inst. Of Science and Technology

Course Code	18CHE372T	Course Name	PETROCHEMICAL TECHNOLOGY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Chemical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1:	Expose to the importance petrochemical products and feedstock	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2:	Application of different resource for basic petrochemical synthesis process	Level of Thinking (loom)	Engineering Knowledge
CLR-3:	Learn the various second generation petrochemical synthesis process	Expected Proficiency (%)	Problem Analysis
CLR-4:	Understand the process flow diagram of third generation petrochemical process	Expected Attainment (%)	Design & Development
CLR-5:	Study process flow diagram for polymers production and application		Analysis, Design, Research
CLR-6:	Learn process flow for Agrochemicals and Pharmaceuticals products		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1:	Analysis the importance of petrochemicals and growth potential of petrochemical industry	5 85 80	L L L L M M H H H H
CLO-2:	Develop processes for manufacture of basic petrochemicals from hydrocarbon feedstock	2 85 80	H L H M M M L H L L
CLO-3:	Familiarize to draw flow diagrams of intermediate petrochemicals production processes	2 80 75	H L H M M M L M M M
CLO-4:	Ability to draw flow diagram for plastic and resin production process	2 90 85	H L H M M M L M H M
CLO-5:	Familiarize to draw process flow diagram for rubber and fibers production process	3 85 80	H L H M M M L M H M
CLO-6:	Design and analysis the production process for agrochemicals and pharmaceuticals products	3 90 85	H L H M M M L M M H

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Definition of petrochemicals	Selection of raw material and process for acetylene synthesis	Feed stock and process for acrylonitrile synthesis	Classification of industrial important polymers
	SLO-2	History of petrochemical industry	Process flow for manufacture of acetylene	Process flow for manufacture of acrylonitrile	Plastics and its classification
S-2	SLO-1	Overview of petrochemical products	Feed stock and process for and process for Ethylene synthesis	Selection of raw material and process for ethylene derivative synthesis	Selection of raw material and process for polyethylene synthesis
	SLO-2	Importance of petrochemical	Process flow for manufacture of ethylene	Process flow for production of ethylene oxide	Process diagram for polyethylene production
S-3	SLO-1	Structure of petrochemical industry	Application of C1 and C2 petrochemical	Industrial application of acrylonitrile	Industrial application of polyethylene
	SLO-2	Feedstock selection for petrochemical	Selection of raw material and process for propylene synthesis	Selection of raw material and process for propylene oxide synthesis	Selection of raw material and process for PVC production
S-4	SLO-1	Petrochemicals from petroleum fractions feedstock	Process flow for manufacture of propylene	Process flow for manufacture of propylene oxide	Process block diagram for PVC production
	SLO-2	Petrochemical industry in india	Feed stock and process for butadiene synthesis	Raw material and process selection for ethylene chloride synthesis	Definition of elastomer and types
S-5	SLO-1	Growth potential of petrochemical in India	Process flow for manufacture of butadiene	Draw flow diagram for manufacture of ethylene chloride	Feed stock and process for synthetic rubber synthesis
	SLO-2	Petrochemical socio-economic Linkage	Application of C3 and C4 petrochemical	Selection of raw material and process for vinyl acetate synthesis	Process flow for manufacture of synthetic rubber
S-6	SLO-1	Source of petrochemicals	Industrial important basic aromatics compounds	Manufacture of vinyl acetate	Industrial important fibers polymers
	SLO-2	Classification of petrochemicals	Preparation of raw materials and process for aromatic compound synthesis	Feed stock and process for vinyl chloride synthesis	Raw material and process condition for nylon synthesis

S-7	SLO-1	Various petrochemical building block	Process flow diagram for manufacture of BTX	Process flow for manufacture of vinyl chloride	Manufacture of nylon	Manufacture of cationic detergents
	SLO-2	Petrochemical manufacturing involves building blocks processes	Application of BTX petrochemicals	Industrial application of ethylene and propylene derivative	Industrial application of nylon fibers	Raw material and process for non-ionic detergents synthesis
S-8	SLO-1	Various basic petrochemicals	Industrial important Alcohols	Feed stock and process for phenol synthesis	Feed stock for polyesters synthesis	Process flow for manufacture of non-ionic detergents
	SLO-2	Intermediate petrochemical products	Process flow for manufacture of methanol	Process flow for manufacture of phenol	Process flow for manufacture of polyesters	Classification of carbon black
S-9	SLO-1	Major polymer petrochemical products	Process flow for manufacture of ethanol	Selection of raw material and process for styrene synthesis	Synthetic resins- process for phenol formaldehyde synthesis	Various methods of carbon black production
	SLO-2	Various uses of petrochemical products	Application of methanol and ethanol	Process flow for manufacture of styrene	Block diagram for manufacture of phenol formaldehyde	Application carbon black

Learning Resources	1. Bhaskara Rao. B.K, "Petrochemicals", Khanna Publishers, New Delhi. 2. Gopala Rao. M. and Marshall Sittig, "Dryden's Outlines of Chemical Technology", 3rd Edn., East-West Press, New Delhi, 2008. 3. Steiner H. "Introduction to Petroleum Chemicals", Pergammon Press, 1992.
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SLO – Session Learning Outcome

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. A. Subramaniam, PESCO Beam Environmental Solutions Pvt. Ltd.,	1. Dr. Lima Rose Miranda, Anna University, email: limamiranda2007@gmail.com	1. Dr.K.Tamilarasan SRM Inst. of Science & Technology, tamilarasan.k@srmuniv.ac.in
2. Mr. S. T. Kalaimani, CPCL, Chennai	2. Dr. T. R. Sundararaman, Rajalakshmi Engineering College	

Course Code	18CHE373T	Course Name	FOOD TECHNOLOGY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Chemical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Familiarize general aspects of food industry ,role of chemical engineers in food industry and constituents of food	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Study the unit operations used in food processing		
CLR-3 :	Know about the food deterioration, preservation and packing method		
CLR-4 :	Learn the different food products		
CLR-5 :	Learn about the packing methods and waste disposal		
CLR-6 :	Production Processing and Preservation of food		

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (loom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Know about the general aspects of food industry ,role of chemical engineers in food industry and constituents of food	1	80	70	L	M	L	M		L	H	H	L	M			H	L	L
CLO-2 :	Acquire a knowledge about the different types unit operations used in food processing industry	1	80	75	M	M	M	M		L	M	M		M			H	M	H
CLO-3 :	Control the food deterioration by the way of preservation and packing method	1	80	75	H	H	M	M	M	M	H	M	H	M			H	H	H
CLO-4 :	Understand the technology involved in different food products	2	80	70	M	M	M	L		M	H	M	H	M			H	M	H
CLO-5 :	Apply the knowledge gained to provide suitable packing methods to improve the shelf life of the product and able dispose the waste in proper way.	1	80	75	H	M	M	L	M	M	H	H	M	M			H	H	H
CLO-6 :	Able to produce process and preserve food products	1	70	70	H	M	M	M	M	M	H	H	M	M			H	H	M

Duration (hour)	9	9	9	9	9
S-1 SLO-1	INTRODUCTION Characteristics of food industry and role of Engineers	UNIT OPERATION IN FOOD PROCESSING Material handling; Heat exchanging	DETERIORATION AND PRESERVATION Deteriorative factors and their control	FOOD PRODUCTS Bakery, confectionary and chocolate products	PACKING METHODS AND WASTE DISPOSAL Principles of food packaging-
S-2 SLO-1	Constituents of food- Carbohydrates, Proteins	Heating, Cooling	Kinetics of chemical reactions in foods	Bakery, confectionary and chocolate products	Requirements of effective food packaging,
S-3 SLO-1	Constituents of food- Carbohydrates, Proteins	Heating, Cooling	Preservation by heat and cold	Soft and alcoholic beverages	Types of containers,
S-4 SLO-1	Fats and Oils and additional food constituents	Evaporation, Drying	Preservation by heat and cold	Soft and alcoholic beverages	Food packaging materials and forms,
S-5 SLO-1	Nutritive aspects of food constituents	Evaporation, Drying	Dehydration, concentration	Dairy products	Food packaging materials and forms
S-6 SLO-1	Nutritive aspects of food constituents	Forming, Packaging, Controlling	Dehydration, concentration	Dairy products	Package testing, Packages with special features.
S-7 SLO-1	Food additives	Forming, Packaging, Controlling	drying	Meat, Poultry and fish products	Package testing, Packages with special features.
S-8 SLO-1	Quality factors in foods and Quality standards	Overlapping unit operations	Irradiation, Microwave heating	Cereal, grains, pulses	Factory Hygiene
S-9 SLO-1	Quality factors in foods and Quality standards	Energy conservation and new processes	Irradiation, Microwave heating	vegetables, fruits, and spices	Wastewater disposal and pollution control in food industry

Learning Resources	1. Potter. JH, Hotchkiss NN, "Food Science", 5th edn., The CBS Publishing Co, Delhi, 2007. 2. Toldeo. RT, "The Fundamentals of Food Engineering", The CBS Publishing Co, Delhi, 2000.	3. Sivasankar.,B, "Food Processing and Preservation", Prentice-Hall of India, New Delhi, 2002. 4. "Desrosier, NW., "The Technology of Food Preservation," The CBS Publishers & Distributors, 1998.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. A. Subramaniam, PESCO Beam Environmental Solutions Pvt. Ltd.,	1. Dr. Lima Rose Miranda, Anna University, email: limamiranda2007@gmail.com	1. Dr. B. Karunaniithi, SRMIST karunab@srmist.edu.in
2. Mr. S. T. Kalaimani, CPCL, Chennai	2. Dr. T. R. Sundararaman, Rajalakshmi Engineering College	

Course Code	18CHE374T	Course Name	COMPUTATIONAL TECHNIQUES IN CHEMICAL ENGINEERING	Course Category	E	Professional Elective	L 3	T 0	P 0	C 3
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Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Chemical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Review the Numerical methods for solving the different type of equations.	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Familiarize to solve the non-linear algebraic equation, linear simultaneous algebraic equation, Integration, Ordinary differential equation and partial differential equation using numerical methods.	Thinking (loom)	Proficiency (%)	Attainment (%)	Knowledge	Analysis	Development	Design, Research	Usage	Future	Sustainability	Team Work	Communication	Finance & Economics	Learning	PSO - 1	PSO - 2	PSO - 3	
CLR-3 :	Apply the conservation of mass and energy equation for simple chemical engineering systems.																		
CLR-4 :	Analyze the limitations and rate of convergence for different numerical methods.																		
CLR-5 :	Compare the different numerical methods with analytical solution.																		
CLR-6 :	Familiarize to solve the mathematical model equation in chemical engineering system																		

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (loom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Apply the root finding methods for solving the non-linear algebraic equations in thermodynamics and fluid mechanics.	3	80	70	H	H	L	M											
CLO-2 :	Analyze the numerical methods for solving the linear simultaneous algebraic equations in chemical reaction engineering and process heat transfer.	3	80	70	H	H	L	M										L	
CLO-3 :	Apply the numerical integration for solving the chemical engineering problems in chemical reaction engineering and mass transfer application.	3	75	70	H	H	L	H										L	
CLO-4 :	Apply the curve fitting methods to get the batch kinetics parameters using batch reactor data.	3	80	70	H	H	L	L											
CLO-5 :	Analyze the different numerical methods for solving the ordinary and partial differential equations in chemical Reaction Engineering, process heat transfer and mass transfer application	3	70	60	H	H	L	H										L	
CLO-6 :	Solve any mathematical equations involved in engineering problems				H	H	H	H										L	

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Review the root finding methods: Regula-Falsi and Newton Raphson method	Review the methods for solving the linear simultaneous algebraic equations	Review the methods for solving the Integration equations	Review the Taylor series, Euler's method with examples	Review the Finite Difference Method for solving the Partial Differential Equations
S-2	SLO-1	Review the phase equilibrium in ideal solutions	Review the material and energy balance concept without reaction	Rate of drying from batch drying data	Review the Runge-Kutta method with examples	Steady state one dimensional heat transfer problem
S-3	SLO-1	Boiling point of ideal solution using thermodynamics iteration method	Review of material balance with reaction	Determination of drying time from batch drying data using Trapezoidal multistage rule	Estimate the concentration of species in unsteady state of mixing tank	Unsteady steady state one dimensional heat transfer problem
S-4	SLO-1	Boiling point of ideal solution using Newton Raphson method	Continuous Stirred Tank reactor with multiple reaction using Gauss-Siedel method	Determine the volume of single reactor using Simpson's rule	Solve the ODE in batch reactor using Euler's method	Steady state two-dimensional heat transfer problem
S-5	SLO-1	Dew point of ideal solution using Newton Raphson method and plot the T-x-y diagram	Cascade Continuous Stirred Tank Reactors with single reaction using Gauss Elimination method	Determine the volume of cascade flow reactors using Trapezoidal Multistage method	Solve the ODE in Continuous stirred tank reactor with multiple reaction	Convective Diffusion problems
S-8	SLO-1	Review the flash vaporization algorithm	Review of single and multiple stage liquid – liquid extraction	Recap the integral methods to estimate the chemical kinetic parameter (order and rate constant) using batch kinetic data	Solve the ODE in heat conduction problems using R-K method	Convective Diffusion problem
	SLO-2	Flash vaporization calculation using Newton Raphson method	Estimate the composition of extract in each stage using Gauss Elimination method	Differential method to estimate the chemical kinetic parameters	Solve the ODE in Continuous stirred tank without reaction using Euler's method	One dimensional steady state mass transfer
S-9	SLO-1	Recap the equation of state and density of gas mixture	Review of single and multi-stage evaporators	Determine the order and rate constant using polynomial curve fitting combined with Least Square method.	Concentration profile along the reactor length in isothermal plug flow reactor using Euler's method	Stability analysis of finite difference schemes to PDE
	SLO-2	Estimate the molar volume of liquid and vapor using Newton Raphson method	Estimate the area of multi-stage evaporator using explicit method.	Curve fitting in heat conduction problems	Temperature profile in plug flow reactor	Unsteady state heat transfer problem.

Learning Resources	1. Steven C. Chapra and Raymond P. Canale, <i>Numerical Methods for Engineers</i> , sixth Edn., McGraw Hill	4. H. K. Versteeg and W. Malalasekera, <i>An introduction to computational fluid dynamics – The finite volume method</i> , Longman Group Ltd 1995.
	2. Ismail Tosun, <i>Modeling in Transport Phenomena – A Conceptual Approach</i> , 2ndEdn., Elsevier Publications 2007	
	3. Y.V.C. Rao, <i>Chemical Engineering Thermodynamics</i> , Universities press, 1997.	
	5. H. Scott Fogler, <i>Elements of Chemical Reaction Engineering</i> , 4th Edition, Prentice Hall International Series	

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. A. Subramaniam, PESCO Beam Environmental Solutions Pvt. Ltd.,	1. Dr. Lima Rose Miranda, Anna University, email: limamiranda2007@gmail.com	1. Dr. K. Sureshn SRM Inst. of Science & Technology, sureshk@srmist.edu.in
2. Mr. S. T. Kalaimani, CPCL, Chennai	2. Dr. T. R. Sundararaman, Rajalakshmi Engineering College	2. Dr. Ashish Kapoor SRM Inst. of Science & Technology, ashishko@srmist.edu.in

Course Code	18CHE375T	Course Name	INTRODUCTION TO PROCESS PLANT SIMULATION	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Chemical Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)															
CLR-1 :	Overview of mathematical modeling of various chemical engineering systems				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLR-2 :	Understand the modular approaches in process plant simulation				Level of Thinking (loom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3	
CLR-3 :	Understand the various tearing algorithms in process plant simulation																						
CLR-4 :	learnt the convergence promotion methods involved in process simulation																						
CLR-5 :	Evaluate the individual equipment simulation using commercial software																						
CLR-6 :	Hand-on-training for plant simulation using commercial software																						
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			Level of Thinking (loom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3	
CLO-1 :	Propose the mathematical model equation for chemical engineering equipment				1	80	70	H	H	H		H									H	L	
CLO-2 :	Solve the model equations using sequential modular approaches				2	80	70	H	H	L		H									H	H	L
CLO-3 :	Solve the model equations using equation solving approach				2	70	65	H	H	L		H									H	H	
CLO-4 :	Apply the convergence promotion for minimize the total time required for simulation				2	80	70	H	H	L		H									H	H	
CLO-5 :	Perform the process plant simulation using commercial software				2	70	65	H	H	H	L	H						M			M	L	
CLO-6 :	Process plant simulation using commercial software				2	75	65	H	H	H	M										H	M	

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction to process synthesis and analysis	Modular approaches – Analysis Vs Design mode	Decomposition of Networks	Convergence promotion scheme and Newton's method	Cascade simulations
S-2	SLO-1	Process plant simulation	Sequential modular approaches	Tearing Algorithms in decomposition of networks	Direct substitution	Steady state simulation: Ammonia synthesis reactor simulation
S-3	SLO-1	Modeling Aspects	Simultaneous modular approaches	Digraphs and signal flow graph	Wegstein's method	Simulation results and discussion
S-4	SLO-1	Classification of Mathematical Modeling.	Tearing a system of equations	BM Algorithm	Dominant Eigen value method	Steady state simulation of thermal cracking operation
S-5	SLO-1	Artificial Neural Networks	Equation Solving approach	BTA and K & S Algorithms	Quasi-Newton methods	Simulation results and discussion
S-6	SLO-1	steady state single and two stage solvent extraction	Precedence – ordering of equation sets	M&H Algorithms	Criterion for acceleration	Design of Shell-and -Tube Heat Exchanger
S-7	SLO-1	Unsteady-state mass balance in a mixing tank	Disjointing, PTM	Related problems	Introduction to application of flow sheeting software	Simulation results and discussion
S-8	SLO-1	Unsteady state steam heating of a liquid	The SWS and Rudd-Algorithm	Comparison of various Tearing Algorithms	Steady state simulations for single equipment	Steady state simulation of pyrolysis of Biomass
S-9	SLO-1	Degree of freedom for equipment	Direct methods and iterative methods	Linear and non-linear equations.	Dynamics simulations for single equipment	Simulation results and discussion
	SLO-2	Degree of freedom for process flow sheet				

Learning Resources	<ol style="list-style-type: none"> 1. B.V. Babu, Process Plant Simulation, Oxford University Press, India 2004 2. Robin Smith, Chemical Process Design and Integration, 2nd Edition, Wiley, 2016 3. Richard Turton, Analysis, Synthesis and Design of Chemical Processes, Pearson Education International, 2009.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. A. Subramaniam, PESCO Beam Environmental Solutions Pvt. Ltd.,	1. Dr. Lima Rose Miranda, Anna University, email: limamiranda2007@gmail.com	1. Dr. K. Suresh SRM Inst. of Science & Technology, sureshk@srmist.edu.in
2. Mr. S. T. Kalaimani, CPCL, Chennai	2. Dr. T. R. Sundararaman, Rajalakshmi Engineering College	

ACADEMIC CURRICULA

Professional Elective Courses

CIVIL ENGINEERING

Regulations - 2018



SRM INSTITUTE OF SCIENCE AND TECHNOLOGY

(Deemed to be University u/s 3 of UGC Act, 1956)

Kattankulathur, Kancheepuram, Tamil Nadu, India

Course Code	18CEE301T	Course Name	FOUNDATION ENGINEERING AND DESIGN	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	CIVIL ENGINEERING	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understanding the essential steps involved in a Geotechnical Investigation	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Analyze the principle types of foundation and the factors governing the choice of the most suitable type of foundation.	(Bloom)	ency (%)	ent (%)	Wedge	s	oment	Research	ge	s	ustainability	n Work	ance	g					
CLR-3 :	Get exposed to determination of bearing capacity of shallow foundation																		
CLR-4 :	Analyze the cause and remedial measures for settlement and slope failure																		
CLR-5 :	Get an insight into the load carrying capacity of pile foundation in the field condition																		
CLR-6 :	Understand and analyse the concept of earth pressure																		

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Identify the soil characteristics through geotechnical investigation	2	85	80	H	H	-	-	-	-	-	-	-	-	-	-	H	-	-
CLO-2 :	Proper type of foundation is chosen depending upon the soil condition	2	85	75	H	H	-	-	-	-	-	-	-	-	-	-	H	-	-
CLO-3 :	Compute g the bearing capacity of shallow foundation	2	80	75	H	H	-	H-	-	-	-	-	-	-	-	-	H	-	-
CLO-4 :	Utilize the proper measures for reducing the settlement and slope failure	2	85	80	H	H	-	-	-	-	-	-	-	-	-	-	H	-	-
CLO-5 :	Utilize the proper type of pile in the field	2	85	75	H	H	-	H	-	-	-	-	-	-	-	-	H	-	-
CLO-6 :	Estimate of earth pressure for different soil condition	2	80	75	H	H	-	-	-	-	-	-	-	-	-	-	H	-	-

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Site investigation, soil Exploration	Definition: Foundation, purpose of foundation.	Combined footing - types	Deep foundation – Necessity. Pile Foundations classification	Lateral Earth Pressures Theories-Introduction:
	SLO-2 Planning and stages in site investigation	Definition: Shallow Foundation – classification. Ultimate, gross, net, safe bearing capacity. safe and allowable bearing pressure	Combined footing - types	Pile Foundations – classification	applications of earth pressure theories
S-2	SLO-1 Soil exploration – Methods – direct, semi-direct and indirect method	Bearing capacity failure - modes of shear failures – general, local and punching shear failure	Method of proportioning – Rectangular footing	Load carrying capacity of pile – Methods	Different types of earth pressure at rest, active and passive pressure
	SLO-2 Direct method – test pit, trenches	Factors affecting bearing capacity	Method of proportioning – Rectangular footing	Dynamic method – ENR, and Hiley's - Problems	Different types of earth pressure at rest, active and passive pressure
S-3	SLO-1 Indirect methods. Geophysical methods- Seismic Refraction Method	Bearing capacity determinations – Methods.	Method of proportioning – Trapezoidal footing	Static method – all type of soils - problems	Rankine's Earth Pressure Theory, active earth pressure and passive earth pressure for horizontal backfill for cohesion-less soil
	SLO-2 Geophysical methods- Electrical Resistivity Method	Terzaghi theory – Assumption.	Method of proportioning – Trapezoidal footing	Static method – all type of soils - problems	Rankine's Earth Pressure Theory, active earth pressure and passive earth pressure for horizontal backfill for cohesion-less soil
S-4	SLO-1 Indirect method – SPT	Bearing capacity – Strip and Square foundation	Combined footing - problems	Static method – all type of soils - problems	Rankine's Earth Pressure Theory, active earth pressure and passive earth pressure for horizontal backfill for cohesion-less soil-Problems
	SLO-2 Indirect method – SPT	Bearing capacity – Circular and Rectangular foundation	Combined footing - problems	Static method – all type of soils - problems	Rankine's Earth Pressure Theory, active earth pressure and passive earth pressure for horizontal backfill for cohesion-less soil-Problems
S-5	SLO-1 Indirect method – DCPT	Bearing capacity – effect of water table	Settlement – total and differential settlement.	Pile load capacity – penetration test results	Rankine's Earth Pressure Theory, active earth pressure and passive earth pressure for horizontal backfill for cohesive soils.

	SLO-2	Indirect method –SCPT	Bearing capacity – effect of water table	Settlement – total and differential settlement.	Pile load capacity – penetration test results	Rankine's Earth Pressure Theory, active earth pressure and passive earth pressure for horizontal backfill for cohesive soils
S6	SLO-1	Semi direct method Borings – auger	Bearing capacity - problems	Causes and methods to minimize the total settlement	Pile group – efficiency - problems	Rankine's Earth Pressure Theory, active earth pressure and passive earth pressure for horizontal backfill for cohesive soils-Problems
	SLO-2	Semi direct method Borings –shell and auger	Bearing capacity - problems	Causes and methods to minimize the total settlement	Pile group – efficiency - problems	Rankine's Earth Pressure Theory, active earth pressure and passive earth pressure for horizontal backfill for cohesive soils-Problems
S-7	SLO-1	Semi direct method Borings – wash boring and rotary drilling	Bearing capacity - problems	Causes and methods to minimize the differential settlement	Pile group – efficiency - problems	Earth pressure theories – Graphical method
	SLO-2	Semi direct method Borings – percussion method	Bearing capacity - problems	Causes and methods to minimize the differential settlement	Pile group – efficiency - problems	Earth pressure theories – Graphical method
S-8	SLO-1	Number and deposition of trail pits and borings	Hansen and IS code method	Slopes – types – Causes of slope failure	Pile load test : Types - Load carrying capacity of pile, under-reamed pile and pile group	Rebhann's Construction for Active Pressure
	SLO-2	Bore log details	Bearing capacity from Penetration test results	Methods to minimize the slope failure	load test as per BIS – estimation of load carrying capacity	Rebhann's Construction for Active Pressure
S-9	SLO-1	Soil Sample ; UDS	Bearing capacity : Plate load test as per BIS ,	Slope stability – methods - Swedish Method of Slice for a Cohesive-frictional Soil	Problems in pile load test.	Culmann's graphical solutions for active and passive case
	SLO-2	Soil Sample ; DS	limitations and estimation of settlements - Performance of foundation	Slope stability – methods - Swedish Method of Slice for a Cohesive-frictional Soil	Negative skin friction	Culmann's graphical solutions for active and passive case

Learning Resources	1. Joseph.E Bowles, "Foundation Analysis and Design", Mc Graw Hill Publishing co., 2001. 2. Murthy .V.N.S, "Textbook of Soil Mechanics and Foundation Engineering", CBS Publishers and Distributors, New Delhi, 2009. 3. Arora .K.R. "Soil Mechanics and Foundation Engineering", Standard Publishers and Distributors, New Delhi, 2011. 4. Varghese, P.C., "Foundation Engineering", PHI Learning New Delhi. 2011	5. Punmia.B.C., "Soil Mechanics and Foundations", Laxmi publications Pvt Ltd., 2000. 6. Das .B.M, "Principles of Foundation Engineering", (Fifth Edition), Thomson Books, 2010. 7. NPTEL Course – Advanced Foundation Engineering : https://nptel.ac.in/courses/105105039/ 8. NPTEL Course – Foundation Engineering : https://nptel.ac.in/courses/105101083/
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	50%	-	40%	-	40%	-	45%	-	70%	-
	Understand										
Level 2	Apply	50%	-	60%	-	60%	-	55%	-	30%	-
	Analyze										
Level 3	Evaluate	-	-	-	-	-	-	-	-	-	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4: Assignments and / or Field visits

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Dr. P.Selvanambi, Divisional Engineer (Highways), sundariselvam@yahoo.com	Dr.M.Muttharam, Anna University, muttharam@annauniv.edu	Dr. P.T. Ravichandran, SRMIST
Mr.Lenin K.R., Head –GEOTECH, SECON Private Limited, Bangalore, lenin.kr@secon.in	Dr.V.Murugaiyan, Pondichery Engineering College, vmurugaiyan@pec.edu	Ms. S. Mary Rebekah Sharmila, SRMIST.

Course Code	18CEE302T	Course Name	GEOTECHNICAL DESIGN	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	CIVIL ENGINEERING	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1:	Understand the essential steps involved in a Geotechnical Investigation	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2:	Understand the concept of consolidation and the estimation of preconsolidation pressure		
CLR-3:	Analyze the stress strain behavior of different types of soil		
CLR-4:	Compute of the ultimate load carrying capacity of shallow foundation under different field condition		
CLR-5:	Estimate of pile load capacity and settlement of single and group of piles		
CLR-6:	Utilize the ultimate loads of shallow and pile foundation in the civil engineering field		

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1:	Analyze the soil properties based on geotechnical investigation	2	85	80	H	H	-	-	-	-	-	-	-	-	-	-	H	-	-
CLO-2:	Utilize the preconsolidation pressure for determining the rate of consolidation	2	85	75	H	H	-	-	-	-	-	-	-	-	-	-	H	-	-
CLO-3:	Utilize the stress strain behavior of soil in the field	2	80	75	H	H	-	M	-	-	-	-	-	-	-	-	H	-	-
CLO-4:	Identify the application of ultimate loads of shallow foundation in the field	2	85	80	H	H	-	-	-	-	-	-	-	-	-	-	H	-	-
CLO-5:	Identify the application of ultimate loads of pile foundation in the field	2	85	75	H	H	-	M	-	-	-	-	-	-	-	-	H	-	-
CLO-6:	Apply of shallow and deep foundation in the field	2	80	75	H	H	-	-	-	-	-	-	-	-	-	-	H	-	-

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Planning of subsurface investigation	Terzaghi's theory of one dimensional consolidation	Stress and strain behavior of soil	Bearing capacity and settlement analysis of shallow foundations: Modes of failure	Pile foundation: Functions
	SLO-2 Purpose and scope	Terzaghi's theory of one dimensional consolidation	Stress and strain behavior of soil	Bearing capacity and settlement analysis of shallow foundations: Modes of failure	Pile foundation: Functions
S-2	SLO-1 Influence of soil conditions on exploratory program	Derivation of Terzaghi's equation (solution in detail need not be covered)	Triaxial test -drained and un-drained behavior of sand	Failure criteria, Prandtl Reissner Method, Assumptions - Estimation of ultimate loads,	Types of pile foundations
	SLO-2 Type of foundation on exploratory program	Derivation of Terzaghi's equation (solution in detail need not be covered)	Triaxial test -drained and un-drained behavior of sand	Failure criteria, Prandtl Reissner Method, Assumptions - Estimation of ultimate loads,	Types of pile foundations
S-3	SLO-1 Subsurface soundings –Static methods	Estimation of Cc and Cv from laboratory tests	Triaxial test -drained and un-drained behavior of clays	Terzaghi solution, Assumptions - Estimation of ultimate loads	Pile load tests, Use of load tests
	SLO-2 Subsurface soundings –Static methods	Estimation of Cc and Cv from laboratory tests	Triaxial test -drained and un-drained behavior of clays	Terzaghi solution, Assumptions - Estimation of ultimate loads	Pile load tests, Use of load tests
S-4	SLO-1 Subsurface soundings – Dynamic methods	Estimation of Cc and Cv from laboratory tests	Failure criteria in soils –only Mohr – Coulomb's criteria	Estimation of ultimate loads- Effect of shape,	Methods of estimation of pile load capacity- Static and dynamic
	SLO-2 Subsurface soundings – Dynamic methods	Estimation of Cc and Cv from laboratory tests	Failure criteria in soils –only Mohr – Coulomb's criteria	Estimation of ultimate loads- Effect of shape,	Methods of estimation of pile load capacity- Static and dynamic
S-5	SLO-1 Planning of subsurface investigations	Estimation of Pc by various methods	Ideal, plastic and real soil behavior	Estimation of ultimate loads- embedment of footing	Estimation of single pile capacity by static
	SLO-2 Planning of subsurface investigations	Estimation of Pc by various methods	Ideal, plastic and real soil behavior	Estimation of ultimate loads- embedment of footing	Estimation of single pile capacity by static
S6	SLO-1 Planning of subsurface investigations	Field consolidation curves	Shear strength of sand and clays	Estimation of ultimate loads- eccentricity in loading	Estimation of single pile by dynamic methods
	SLO-2 Planning of subsurface investigations	Field consolidation curves	Shear strength of sand and clays	Estimation of ultimate loads- eccentricity in loading	Estimation of single pile by dynamic methods
S-7	SLO-1 Type and sequence of operations	Quasi pre-consolidation	Estimation of stresses: Boussinesq's theory	Compressibility (including critical rigidity index), Choice of factor of safety, Settlement of foundations on sand –	Group capacity of piles

	SLO-2	Type and sequence of operations	Quasi pre-consolidation	Estimation of stresses: Boussinesq's theory	Schmertmann method Compressibility (including critical rigidity index), Choice of factor of safety, Settlement of foundations on sand – Schmertmann method	Group capacity of piles
S-8	SLO-1	Lateral extent and depth of exploration	Quasi Secondary consolidation	Estimation of stresses: Westergard's theory	Foundations on collapsing and swelling soils, non-uniform soils, compressible soils and on rock	Separation of skin friction and end bearing capacity
	SLO-2	Lateral extent and depth of exploration	Quasi Secondary consolidation	Estimation of stresses: Westergard's theory	Foundations on collapsing and swelling soils, non-uniform soils, compressible soils and on rock	Separation of skin friction and end bearing capacity
S-9	SLO-1	Interpretation of field and laboratory data	Practical applications	Estimation of stresses: Newmark's charts	Design of isolated and combined footings	Settlement of single and group of piles.
	SLO-2	Interpretation of field and laboratory data	Practical applications	Estimation of stresses: Newmark's charts	Design of isolated and combined footings	Settlement of single and group of piles.

Learning Resources	1. Joseph.E Bowles, "Foundation Analysis and Design", Mc Graw Hill Publishing co., 2001. 2. Murthy .V.N.S. "Textbook of Soil Mechanics and Foundation Engineering", CBS Publishers and Distributors, New Delhi, 2009. 3. Arora .K.R. "Soil Mechanics and Foundation Engineering", Standard Publishers and Distributors, New Delhi, 2011. 4. Varghese, P.C., "Foundation Engineering", PHI Learning New Delhi. 2011 5. Punmia.B.C., "Soil Mechanics and Foundations", Laxmi publications Pvt Ltd., 2000. 6. Das .B.M. "Principles of Foundation Engineering", (Fifth Edition), Thomson Books, 2010. 7. NPTEL Course – Foundation Design : https://nptel.ac.in/courses/105104162/
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	50%	-	40%	-	40%	-	45%	-	70%	-
	Understand										
Level 2	Apply	50%	-	60%	-	60%	-	55%	-	30%	-
	Analyze										
Level 3	Evaluate	-	-	-	-	-	-	-	-	-	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 : Assignments and / or Field visits

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Dr. P.Selvanambi, Divisional Engineer (Highways), sundariselvam@yahoo.com	Dr.M.Muttharam, Anna University, muttharam@annauniv.edu	Dr. P.T. Ravichandran, SRMIST
Mr.Lenin K.R., Head – GEOTECH, SECON Private Limited, Bangalore, lenin.kr@secon.in	Dr.V.Murugaiyan, Pondichery Engineering College, vmurugaiyan@pec.edu	Ms.S. Mary Rebekah Sharmila, SRMIST.

Course Code	18CEE303T	Course Name	GROUND IMPROVEMENT TECHNIQUES	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	CIVIL ENGINEERING			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):	The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand the need for ground improvement			1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Understand the techniques adopted for ground improvement with respect to hydraulic modification																				
CLR-3 :	Identify conceptual and practical understanding of in-situ soil densification techniques																				
CLR-4 :	Familiarize with soil chemical modification techniques and acquaintance with emerging technologies																				
CLR-5 :	Understand the mechanism and concept related to soil modification by reinforcements																				
CLR-6 :	Recommend and design cost effective ground improvement techniques for difficult practical soil conditions																				

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:			Level of Thinking (Bloom)			Expected Proficiency (%)														
CLO-1 :	Gain a thorough knowledge on the role of ground improvement techniques in the infrastructure development			2	85	80	H	L	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-2 :	Recommend hydraulic modification techniques for related problems			2	85	75	H	M	-	-	-	-	-	-	-	-	-	-	H	-	-
CLO-3 :	Apply densification techniques for loose sand deposits and alternative techniques for soft clay deposits			2	80	75	H	M	-	-	-	-	-	-	-	-	-	-	H	-	-
CLO-4 :	Recommend additives and frame soil chemical modification schemes for stabilizing problematic soil			2	85	80	H	M	-	-	-	-	-	-	-	-	-	-	H	-	-
CLO-5 :	Design geotechnical structures using reinforcements like reinforced earth retaining walls, slopes, foundations etc.,			3	85	75	H	H	-	M	-	-	-	-	-	-	-	-	H	-	-
CLO-6 :	Recommend design efficient and economic alternatives using ground improvement techniques for problematic and difficult sites			3	80	75	H	H	-	-	-	-	-	-	-	-	-	-	H	-	-

Duration (hour)	9		9	9	9	9
S-1	SLO-1	Introduction-Ground improvement techniques	Hydraulic modification-concept and principle	In-situ densification of cohesionless soil	Grouting -introduction	Soil reinforcement concepts
	SLO-2	Role of ground improvement techniques in foundation engineering	Dewatering -objectives -types	Various Methods and mechanism involved	Necessity types of grout-suspension-solution grouts	Principle and mechanism
S-2	SLO-1	Objectives and scope of ground improvement techniques	Dewatering Techniques -well points system	Consolidation of cohesive soil-types	Functions of grouting-permeation	Reinforced earth retaining structures-various applicability in geotechnical engineering
	SLO-2	Classification of techniques adopted	Installation -mechanism and suitability of soil	Properties and behaviour	Functions-Compaction-hydro fracture	Embankments -slopes etc..
S-3	SLO-1	Hydraulic-Mechanical-Chemical-Reinforcement	Dewatering methods-Ditches	Vibrofloatation techniques	Grouting equipment and methods	Types of reinforcing materials
	SLO-2	Choice of method of ground improvement techniques	Dewatering methods-Sumps	Dry feed method-wet feed method	Grouting with soil, bentonite	Natural and manmade materials
S-4	SLO-1	Geotechnical problems in Lateritic soil	Dewatering methods -Vacuum method.	Sand compaction piles	Grouting with cement mixes	Geosynthetics-types
	SLO-2	Properties and behavior and techniques adopted	Dewatering methods-Electroosmotic method	Installation techniques	Mechanism and concept	Geotextile-geogrids-geonets
S-5	SLO-1	Geotechnical problems in Alluvial soil	Seepage analysis of 2-dimensional flow-concepts	Deep compaction -dynamic compaction -blasting technique	Grout injection methods	Functions of geosynthetics
	SLO-2	Properties and behavior and techniques adopted	Theory and problems	Concepts and factors influencing	grout monitoring schemes	Filtration, drainage
S6	SLO-1	Geotechnical problems in Black Cotton soil	Seepage analysis-fully penetrated slot	Stone columns -installation	Civil engineering application of grouting techniques	Geosynthetics-Reinforcement
	SLO-2	Properties and behavior and techniques adopted	Theory and problems	Mechanism	Some of the field studies	Separation function -Geotechnical field application

S-7	SLO-1	Selection of suitable ground improvement techniques based on soil condition	Preloading-concept	Design criteria	Stabilization -concept	Geomembranes-containments
	SLO-2	Some field conditions for practical applicability	Field applicability	Stone column- soil criteria-field application	Stabilization of expansive soil	Barriers- field application
S-8	SLO-1	Use of Piezometers	Vertical drains-sand drains	Lime columns-applicability	Lime stabilization-concept-suitability criteria	Current practices-geosynthetics
	SLO-2	Field applications	Installation and mechanism	Soil criteria-mechanism involved	Mechanism involved	Field application reinforcement
S-9	SLO-1	Use of inclinometers	Prefabricated vertical drains	Field application	Cement stabilization -concept-suitability criteria	Geosynthetics in field applications
	SLO-2	Field applications	Installation and mechanism	Installation -mechanism	Mechanism involved	Introduction of ground anchors

Learning Resources	1. Purushothama Raj. P, "Ground Improvement Techniques", Lakshmi Publications, 2nd Edition, 2016.	4. Nihar Ranjan Patra, "Ground Improvement Techniques", Vikas Publishing House, First Edition, 2012.
	2. Manfred R. Hausmann, Engineering Principles of Ground Modification, McGraw-Hill Pub, Co., 1990.	5. Mittal.S, "An Introduction to Ground Improvement Engineering", Medtech Publisher, First Edition, 2013.
	3. Koerner, R.M. "Construction and Geotechnical Methods in Foundation Engineering", McGraw Hill, 1994.	6. NPTEL Course - Advanced Techniques in Geotechnical and Foundation Engineering : https://nptel.ac.in/courses/105106144/
		7. NPTEL Course - Ground Improvement Techniques : https://nptel.ac.in/courses/105108075/

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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Mr. K.R. Lenin Head – GEOTECH, SECON Private Limited, Bangalore, lenin.kr@secon.in	Dr.V. Murugaiyan, Pondichery Engineering College, vmurugaiyan@pec.edu	Dr. S. Bhuvaneshwari, SRMIST

Course Code	18CEE305J	Course Name	CONCRETE TECHNOLOGY	Course Category	E	Professional Elective	L	T	P	C
							2	0	2	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Civil Engineering	Data Book / Codes/Standards	IS 10262: 2019 and IS 456: 2000		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Understand and test the properties of materials constitutes concrete				Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Understand about chemical and mineral admixtures used in concrete. Also understand and test fresh concrete properties																							
CLR-3 :	Know and understand the properties of concrete in hardened state																							
CLR-4 :	Know and understand the durability properties of concrete and special concrete																							
CLR-5 :	Understand the importance of concrete mix design																							
CLR-6 :	Understand the process involved in manufacture of concrete																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1 :	Test and study the properties of cement, aggregates and water				3	80	75	H	M	-	-	-	-	-	-	-	-	-	-	-	-	L	H	M
CLO-2 :	Know the effects of admixtures in concrete and test the fresh concrete properties				3	85	75	H	M	-	-	-	-	-	-	-	-	-	-	-	-	L	H	M
CLO-3 :	Test the hardened concrete properties				3	75	75	H	M	-	-	-	-	-	-	-	-	-	-	-	-	L	H	M
CLO-4 :	Understand the importance of durability of concrete and properties of special concrete				3	90	80	H	L	-	-	-	-	-	-	-	-	-	-	-	-	L	H	M
CLO-5 :	Design the concrete mix without and with admixtures				3	85	75	H	H	H	-	-	-	-	-	-	-	-	-	-	-	M	H	M
CLO-6 :	Know the various stages of manufacture of concrete				3	80	75	H	L	-	-	-	-	-	-	-	-	-	-	-	-	L	H	M

Duration (hour)		9	9	9	9	9
S-1	SLO-1	CONCRETE CONSTITUENTS MATERIALS Overview. Cement, brought up, invention, chemical composition, oxide composition, limits and role.	ADMIXTURES Overview –Chemical and mineral admixtures – additive – plasticizers – definition – situation need high workability – effects of plasticizer in concrete.	HARDENED CONCRETE Test – purpose – density - compressive strength test.	DURABILITY OF CONCRETE Definition - significance – permeability – reasons for permeability in actual structures.	CONCRETE MIX DESIGN Definition – Principle of mix design – Factors choice of mix proportion – Properties of concrete related to mix design.
	SLO-2	Hydration - Bogue's compound – types of cement.	Super plasticizers – effects in – fresh and hardened concrete.	Factors affects strength of concrete. Failure of compression specimen.	Joints in concrete – classifications.	Physical properties of materials required for mix design.
S-2	SLO-1	Properties of cement - Tests on cement – field.	Accelerators – accelerating plasticizer.	Flexural strength – central point load.	Concrete subjected to high temperature.	Nominal and design mix – variables in mix design.
	SLO-2	Laboratory tests – fineness – specific gravity – procedures.	Retarders – use – materials. Water proofers.	Flexural strength –third point load.	Freezing and thawing.	Objective of mix design – List of methods of mix design. Basic steps – Information required for mix design.
S-3	SLO-1	Determination of fineness of cement and normal consistency of cement practically in lab.	Determination of soundness of cement (Demo only) practically in lab.	Determination of crushing strength of coarse aggregate practically in lab.	Determination of flakiness and elongation index of coarse aggregate practically in lab.	Determination of flexural strength of concrete practically in lab.
	SLO-2					
S-4	SLO-1	Consistency - setting time of cement – initial and final setting time.	Fly ash – characteristics – use – classification –effects in fresh and hardened concrete.	Indirect tension test.	Sulphate attack – methods to control.	Indian standard method of mix design - Step by step mix design procedure.
	SLO-2	Soundness and strength of cement.	Silica fume – characteristics – effects in fresh and hardened concrete.	Stress – strain curve.	Acid attack – concrete in sea water.	Mix design example : Without admixture
S-5	SLO-1	Aggregates – classification – source - size – shape – texture.	GGBS - effects in fresh and hardened concrete – uses.	Modulus of elasticity –determination.	Carbonation - factors.	Mix design examples: With chemical admixture and mineral admixture
	SLO-2	Properties of aggregates and tests: Crushing – 10% fines – impact.	Metakaolin – application – advantages – uses.	Different elastic moduli.	Chloride attack – limits of chloride.	

S-6	SLO-1	Determination of initial setting time of cement and final setting time (Demo only) - practically in lab.	Determination of fineness modulus of coarse aggregate practically in lab.	Determination of impact resistance of coarse aggregate practically in lab.	Compressive strength of bricks and concrete cubes practically in lab.	Determination of split tensile strength of concrete practically in lab.
S-7	SLO-1	Abrasion – bulk density – specific gravity Absorption and moisture content – bulking.	FRESH CONCRETE Workability –factors – tests.	Impact resistance test – Impact energy.	Effects of some materials on durability.	MANUFACTURE OF CONCRETE Process – various stages of manufacture of concrete.
	SLO-2	Soundness – flakiness index – elongation index.	Slump and compaction factor tests.	Impact energy calculation	Surface treatments of concrete – materials used.	Batching – mixing
S-8	SLO-1	Grading – sieve analysis – fineness modulus.	Segregation – types – conditions – remedies.	Shrinkage – classifications – factors affect.	Concrete permeability test - Rapid chloride penetration test.	Transporting – Methods adopted for transportation of concrete.
	SLO-2	Water – quality – quantity.	Bleeding – effects – test.	Creep – definition – measurement of creep – factors affect.	Introduction to special concretes.	Placing – compacting - curing – finishing.
S-9	SLO-1	Determination of specific gravity of cement, fine and coarse aggregate practically in lab.	Determination of bulking of sand practically in lab.	Determination of abrasion resistance of coarse aggregate practically in lab.	Workability of concrete – slump – compaction factor test practically in lab.	Determination of impact strength of concrete practically in lab.
	SLO-2					

Learning Resources	<ol style="list-style-type: none"> 1. Neville, A.M. Properties of Concrete, Fifth Edition, Pearson, 2011. 2. Shetty, M.S. Concrete Technology, Theory and Practice, S. Chand & Company, New Delhi, 2013. 3. A.R. Santhakumar, Concrete Technology, 2009 Edition, Oxford University Press 4. Kumar Mehta Paulo, P and Monteiro, J.M. Concrete Microstructure, Properties and Materials, Fourth Edition, McGraw Hill Education, 2006, copy right ©2014. 5. NPTEL Course: Concrete Technology: https://nptel.ac.in/courses/105102012/ 6. Laboratory Manual - SRMIST
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	20 %	20 %	15 %	15 %	15 %	15 %	15 %	15 %	15 %	15 %
Level 2	Apply Analyze	20 %	20 %	20 %	20 %	20 %	20 %	20 %	20 %	20 %	20 %
Level 3	Evaluate Create	10 %	10 %	15 %	15 %	15 %	15 %	15 %	15 %	15 %	15 %
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Er. G.Hariharanath, GA Consultants, Chennai, gac1996@hotmail.com	1. Dr. R. Santhakumar, Professor, Centre for Rural Department, NITTTR	1. Dr. K. Gunasekaran, SRMIST
2. Er. AGV. Desigan, Design Group Engineering Consultancy Pvt Ltd. Chennai, desigan.agv@gmail.com	2. Dr. P. Jayabalan, NIT, Trichy, pjeya@nitt.edu	2. Dr. P. R. KannanRajkumar, SRMIST

Course Code	18CEE306T	Course Name	PRESTRESSED CONCRETE STRUCTURES	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Civil Engineering	Data Book / Codes/Standards	IS 1343: 2012		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Know and utilize the concepts of prestress concrete to analyseprestress concrete sections				Level of Thinking (Bloom)	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Know and understand the different losses of prestress and anchorage zone stress to design																					
CLR-3 :	Understand flexural failure types and to analyze and also to design flexural and tension members																					
CLR-4 :	Understand shear strength analyze and also to design for shear. Also to analyze due to torsion																					
CLR-5 :	Know the design concept of prestressed concrete one way and two way slab																					
CLR-6 :	Know the design concept of prestressed concrete flat slab																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	Analyze the prestress concrete sections using different concepts				3	80	75															
CLO-2 :	Analyze the different losses of prestress and anchorage zone stress to design				3	85	75															
CLO-3 :	Analyze and design of prestressed concrete flexural and tension members				3	75	75															
CLO-4 :	Analyze and design of prestressed concrete for shear and also analyze due to torsion				3	90	80															
CLO-5 :	Design the prestressed concrete one way and two way slab				3	85	75															
CLO-6 :	Design the prestressed concrete flat slab				3	80	75															

Duration (hour)		9		9		9		9	
S-1	SLO-1	PRESTRESSED CONCRETE Introduction - Basic concept – Principle of prestressing – Materials.	LOSSES OF PRESTRESS Nature of losses of prestress – types of losses of prestress in – pre and post tensioning.	FLEXURAL STRENGTH ANALYSIS Flexural failure - control parameters.	SHEAR STRENGTH ANALYSIS Shear and principal stresses – maximum and minimum principal stresses.	PRESTRESSED CONCRETE SLAB Slabs types –cross section of floor panels.			
	SLO-2	Forms of steel – systems of prestressing		Types of flexural failure.	Eliminate diagonal tension cracks - improvement of shear resistance.				
S-2	SLO-1	Types of prestressing – uses of prestressed concrete.	Loss due to elastic deformation	Indian code provisions – moment of resistance – bonded tendons only.	Example without and with axial prestress	Design of one-way slab			
	SLO-2	Materials – concrete strength limitation – requirements of steel for prestressed concrete.	Example	Rectangular section					
S-3	SLO-1	Analysis – basic assumptions.	Loss due to shrinkage and creep of concrete	Examples	Example with curved cable and vertical cable.	Example			
	SLO-2	Concentric and eccentric tendons – resultant stresses – at transfer – at service. Concepts of prestressing – rectangle – symmetrical I-section only.	Example						
S-4	SLO-1	Stress concept	Loss due to relaxation of steel – friction – anchorage slip.	T – Sections. Neutral axis – within the flange – outside the flange.	DESIGN FOR SHEAR Types of shear cracks – sections uncracked in flexure – sections cracked in flexure.	Example			
	SLO-2		Example	Examples	Design of shear reinforcement				
S-5	SLO-1	Stress concept – examples	ANCHORAGE ZONE STRESSES Anchorage zone – nature of stresses – objective.	DESIGN FOR FLEXURE Stress conditions - minimum section modulus – critical combinations – four fundamental conditions – at transfer – at service loads.	Examples	Design of two-way slab			

	SLO-2		Stress distribution in end block – single and double anchor plates – ideal stress distribution.	Minimum prestressing force – maximum eccentricity.		
S-6	SLO-1 SLO-2	Stress concept - examples	Effect of transverse tensile stress Analysis of anchorage zone stress – methods (names only)	Examples	Examples	Example
S-7	SLO-1 SLO-2	Strength concept - examples	Indian standard method of analysis of anchorage zone stresses	Examples	TORSION ANALYSIS Shear stress due to torsion - circular – rectangle – T – section and box section.	Design of simple flat slab
S-8	SLO-1 SLO-2	Load balancing concept – cable profile – reaction – equivalent loads.	Examples	DESIGN OF TENSION MEMBER Determination of area of concrete Load factor – cracking and collapse	Examples	Example
S-9	SLO-1 SLO-2	Load balancing concept – examples.	Design of anchorage zone. Example	Example	Examples	Example

Learning Resources	1. Krishnaraju .R, "Prestressed Concrete", Tata McGraw-Hill Education, Edition: 2018, NewDelhi. 2. Pandit .G.S. Gupta .S.P, "Prestressed Concrete", CBS Publishers & Distributors, 2008 3. S. Ramamrutham, "Prestressed Concrete", DhanpatRai Publishing Company, Fifth Edition, Reprint 2016	4. Lin T.Y, Design of, "Prestressed Concrete Structures", Asia Publishing House, Bombay 1995. 5. IS: 1343-2012 "IS Code of Practice for Prestressed Concrete", BIS, New Delhi, 2012. 6. NPTEL Course: Prestressed Concrete Structures: https://nptel.ac.in/courses/105106117/
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Er. G.Hariharanath, GA Consultants, Chennai, gac1996@hotmail.com	1. Dr. R. Santhakumar, Professor, Centre for Rural Department, NITTTR	1. Dr. K. Gunasekaran, SRMIST
2. Er. AGV. Design, Design Group Engineering Consultancy Pvt Ltd. Chennai, design.agv@gmail.com	2. Dr. P. Jayabalan, NIT, Trichy, pjeya@nitt.edu	2. Dr. P. R. Kannan Rajkumar, SRMIST

Course Code	18CEE307T	Course Name	DESIGN OF EARTHQUAKE RESISTANT STRUCTURES	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Civil Engineering	Data Book / Codes/Standards	IS 1893 (Part 1):2016, IS 13920 : 2016		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand the principles of structural dynamics with regard to Single Degree Of Freedom (SDOF) system.				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Extension of understanding of SDOF system to Multi Degree Of Freedom System (MDOF) with emphasis on two degree of freedom system.				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Understand the fundamentals of earthquake forces.																					
CLR-4 :	Apply structural dynamics principles to the analysis of structures subjected to earthquake forces.																					
CLR-5 :	Design earthquake resistant moment resistant frames / shear walls with emphasis on ductile detailing.																					
CLR-6 :	Understand the modern concepts in the design of earthquake resistant structures using isolation techniques.																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			3	80	80	H	H	-	H	-	-	-	-	-	-	-	-	H	-	-
CLO-1 :	Analyze single degree moment resistant frame for free and forced vibrations				3	75	75	H	H	-	H	-	-	-	-	-	-	-	-	H	-	-
CLO-2 :	Analyze two degree moment resistant frame for free vibrations using modal superposition method				3	90	85	H	H	H	H	-	-	-	-	-	-	-	L	H	-	-
CLO-3 :	Calculate base shear using equivalent static method as per IS 1893				3	85	80	H	H	H	H	-	-	-	-	-	-	-	L	H	-	-
CLO-4 :	Calculate base shear using response spectrum method as per IS 1893				3	90	80	H	M	M	M	-	-	L	-	-	-	-	L	H	-	-
CLO-5 :	Apply the provisions of IS13920 to structures				3	75	75	H	L	L	L	-	-	L	-	-	-	-	-	M	-	-
CLO-6 :	Suggest isolation systems for earthquake resistance																					

Duration (hour)		9	9	9	9	9
S-1	SLO-1	SINGLE DEGREE OF FREEDOM SYSTEM (SDOF) Introduction to Systems with single degree of freedom	MULTI-DEGREE OF FREEDOM SYSTEM (MDOF) Introduction to Systems with two degrees of freedom	DESIGN SEISMIC FORCES AS PER IS 1893-2016 Basis of earthquakes – epicenter	DUCTILE DESIGN FOR EARTHQUAKE RESISTANCE USING IS 13920-2016 Definition of ductility – member and structural	BASE ISOLATION Introduction to base isolation
	SLO-2	Definition of free vibration – mass, stiffness,	Introduction to Systems with multi degrees of freedom (MDOF)	Magnitude of earthquake – measurement – Richter's scale	Response reduction factor and ductility	Passive base isolation – introduction
S-2	SLO-1	Damped and undamped vibration	Moment resistant frames as MDOF– two degree freedom system	Intensity of earthquake – different scales	General specification for ductility	Base isolation for a building
	SLO-2	Fundamental / Natural frequency and time period – problem solving	Shear building and lumped mass	Configurations of buildings to resist earthquake	Ductile requirements of beams – general	Purpose of base isolation
S-3	SLO-1	Forced vibration –Harmonic loading	Calculation of column stiffness – effect of orientation of column on stiffness	Vertical and in-plan mass irregularities	Ductile requirements of beams – Longitudinal reinforcement	Principles of base isolation
	SLO-2	Derivation of equation of motion for free and forced vibration	Computation of diagonal mass matrix	Vertical and in-plan stiffness irregularities – calculation of eccentricities in plan	Ductile requirements of beams – Transverse reinforcement	Basic requirements of base isolation system
S-4	SLO-1	Solution of equation of motion for free vibration	Computation of stiffness matrix	Storey drift and storey shear	Ductile requirements of columns – geometry	Type of Base Isolation Systems – Elastomeric rubber bearings – Roller and ball bearings,
	SLO-2	Solution of equation of motion for forced vibration – harmonic loading	Forming acceleration and velocity vectors	Response spectrum	Relative strength of columns and beams at a joint	
S-5	SLO-1	Problem solving for finding the response for undamped free vibration	Equation of motion of undamped two degree lumped mass free vibration of moment resistant frame	Seismic zone factor, Importance factor,	Transverse reinforcement in column	Type of Base Isolation Systems – springs – sliding bearing
	SLO-2	Problem solving for finding the response for damped free vibration	Solution of equation of motion of undamped two degree freedom system for free vibration	Response reduction factor	Ductile detailing for shear walls – introduction	Modeling base isolation in SAP – introduction

S-6	SLO-1	Problem solving for finding the response for undamped forced vibration	Eigen value problem and modal superposition method	Percentage of imposed loads , seismic weight of floors- Load combinations	General requirements	Input requirements for SAP
	SLO-2	Problem solving for finding the response for damped forced vibration	Determining modal frequencies and time periods	Introduction to Equivalent Static Method (ESM) and its limitations	Design for shear force	Input requirements for ETABS
S-7	SLO-1	Magnification factor	Uncoupled equations in SDOF and finding modal response	Computation of base shear for single & double storey moment resistant plane frame using ESM	Design for axial force	Modeling for base isolation in STAAD.Pro
	SLO-2	Application to determine the forces transferred to base from machine foundation	Undamped equation of motion for two degree moment resistant frame with lateral harmonic loading at the DOF	Introduction to Response Spectrum Method(RSM) and applicability	Design for bending moment	Input requirements for STAAD.Pro
S-8	SLO-1	Machine isolation	Modal superposition method to form uncoupled SDOF equations including modal load vector.	Computation of base shear for single storey and double storey moment resistant plane frame using RSM	Opening in walls – introduction	Introduction to active base isolation
	SLO-2	Determination of damping required to minimize forces transferred to foundation	Determination of response of the structure at discrete time intervals.	Introduction to DBE (Design Based Earthquake) and MCE(Maximum Considered Earthquake)	Detailing around the openings	Underlying principles of active base isolation
S-9	SLO-1	Definition of ground motion due to earthquake	Superposition of modal responses	Performance based design – Capacity and demand spectra as per ATC40	Ductile construction joints	Schematic diagram of a typical active base isolation system
	SLO-2	Equivalent model for considering ground motion in moment resistant frame	Square Root of Sum of Squares (SRSS) method.	Principles of pushover analysis and pushover curve	Ductile design of gravity columns in buildings	Comparison between passive and active base isolation

Learning Resources	1. Anil K.Chopra, "Dynamics of structures" (Theory and Applications to Earthquake Engineering), 5 th Edition, Pearson, 2016	3. IS 1893: 2016, (Part I) "Criteria for Earthquake Resistant Design of Structures - Part 1: General Provisions and Buildings", BIS, 2016.
	2. Short course on "Seismic design of reinforced concrete buildings", CEP, IIT, Kanpur, 2005.	4. IS 13920: 2016,"Ductile design and detailing of reinforced concrete structures subjected to seismic forces - Code of practice", BIS, 2016.

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	40 %	-	40 %	-	10 %	-	40%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	70 %	-	55%	-
	Analyze										
Level 3	Evaluate	20 %	-	20 %	-	20 %	-	20 %	-	5%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Er. S. Dhanabal, General Manager, NLY, Neyveli, dhans1960@yahoo.co.in	1. Dr. R. Santhakumar, Professor, Centre for Rural Department, NITTTR	Prof. G. Augustine Maniraj Pandian, SRMIST
2. Er. AGV. Design, Design Group Engineering Consultancy Pvt Ltd. Chennai, design.agv@gmail.com	2. Dr. P. Jayabalan, NIT, Trichy, pjeya@nitt.edu	Dr. K.S. Satyanarayanan, SRMIST

Course Code	18CEE308T	Course Name	DESIGN OF STEEL-CONCRETE COMPOSITE STRUCTURES			Course Category	E	Professional Elective										L	T	P	C					
																		3	0	0	3					
Pre-requisite Courses		Nil		Co-requisite Courses		Nil		Progressive Courses		Nil																
Course Offering Department			Civil Engineering			Data Book/Codes/Standards			IS 456 :2000, IS 800: 2007, IS 11384, Steel Tables																	
Course Learning Rationale (CLR):		The purpose of learning this course is to:					Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Understand the concept of steel-concrete composite member design and to get introduced to the relevant IS codes					Level of Thinking (Bloom)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2 :	Create insights to the concepts of Limit state method of design									Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Utilize the concepts in performing design of steel-concrete composite beams and columns																									
CLR-4 :	Utilize the concepts in performing design of steel-concrete composite connections																									
CLR-5 :	Understand the behaviour of composite girder bridges																									
CLR-6 :	Create insights to the seismic behaviour of composite structures																									
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:					2	85	80	H	-	-	M	-	-	-	-	-	-	H	H	M	-			
CLO-1 :	Identify the effect of external loads on steel-concrete composite members and the factors influencing their behaviour and to get familiarity with the relevant IS codes					2	85	80	H	H	-	M	-	-	-	-	-	-	-	H	H	M	-			
CLO-2 :	Analyze the behavior of steel-concrete composite sections under flexure, shear and compression					2	85	80	H	H	H	H	-	-	-	-	-	-	-	H	H	M	-			
CLO-3 :	Apply Limit state method of design to steel-concrete composite beams and columns					2	80	75	H	H	H	H	-	-	-	-	-	-	-	H	H	M	-			
CLO-4 :	Apply Limit state method of design to steel-concrete composite connections					2	80	75	H	H	-	M	-	-	-	-	-	-	-	H	H	M	-			
CLO-5 :	Analyze the behavior of steel-concrete composite girder bridges					2	80	75	H	-	-	M	-	-	-	-	-	-	-	H	H	M	-			
CLO-6 :	Analyze the seismic behaviour of composite structures					2	85	80	H	H	H	H	-	-	-	-	-	-	-	H	H	M	-			
Duration (hour)		9		9		9		9		9		9		9		9		9		9		9				
S-1	SLO-1	INTRODUCTION Introduction to Steel - Concrete Composite Construction-Advantages-Limitations		Design Example 1		Design Example 3		Design Example 1		SEISMIC BEHAVIOUR OF STEEL-CONCRETE COMPOSITE STRUCTURES Introduction																
	SLO-2	Materials to be used-Structural advantages-Factors deciding selection of materials		Design Example 1		DESIGN OF CONNECTIONS Introduction		Design Example 1		Basic concepts																
S-2	SLO-1	Introduction to steel - concrete composite codes/standards		Design Example 2		Types of Connections		Design Example 2		General design criteria																
	SLO-2	Limitations of using BIS codes-Introduction to Eurocode 4		Design Example 2		Choice of Connections in Composite structures		Design Example 2		General design criteria																
S-3	SLO-1	Theory of composite structures		Design Example 2		Behaviour of Connections in Composite structures		DESIGN OF STEEL-CONCRETE COMPOSITE GIRDER BRIDGES Introduction		Code provisions																
	SLO-2	Behaviour of composite beams		Design Example 2		Basic concepts		Behaviour of girder bridges		Seismic behaviour of composite beams																
S-4	SLO-1	Behaviour of composite beams		Design of Composite Columns		Code provisions		Behaviour of girder bridges		Seismic behaviour of composite beams																
	SLO-2	Behaviour of composite columns		Design Procedure		Design procedure		Design concepts		Seismic behaviour of composite slabs																
S-5	SLO-1	Behaviour of composite columns		Relevant BIS code provisions		Design Example 1		Design concepts		Seismic behaviour of composite slabs																
	SLO-2	Limit state method of design of steel-concrete composite sections under flexure-code provisions		Choice of cross-sections		Design Example 1		Materials to be used-Types of cross-sections		Seismic behaviour of composite columns																
S-6	SLO-1	Limit state method of design of steel-concrete composite sections under shear- code provisions		Design Example 1		Design Example 2		Basic design considerations		Seismic behaviour of composite columns																
	SLO-2	Limit state method of design of steel-concrete composite sections under compression- code provisions		Design Example 1		Design Example 2		Basic design considerations		Seismic behaviour of composite connections																

S-7	SLO-1	DESIGN OF STEEL-CONCRETE COMPOSITE MEMBERS Design of Composite beams	Design Example 1	Design Example 3	Failure types	Seismic behaviour of composite connections
	SLO-2	Design Procedure	Design Example 2	Design Example 3	Failure types	Seismic behaviour of composite frames
S-8	SLO-1	Relevant BIS code provisions	Design Example 2	Design of Shear Connections	Relevant code provisions	Seismic behaviour of composite frames
	SLO-2	Choice of cross-sections	Design Example 2	Basic concepts	Mandatory checks	Seismic behaviour of composite frames
S-9	SLO-1	Design Example 1	Design Example 3	Code provisions	Comparison with conventional bridge types	Design methods
	SLO-2	Design Example 1	Design Example 3	Design procedure	Comparison with conventional bridge types	Design methods

Learning Resources	1. "Teaching Resource Material for Structural Steel Design", Volume 2/3 jointly prepared by 1. I.I.T., MS 2. Anna University 3. SERC, MS 4. "Institute for Steel Development and growth", Calcutta.	3. Johnson.R.P, "Composite Structures of Steel and Concrete". Vol-I, # Oxford Black; well Scientific Publications (Third Edition) U.K. 2004.
	2. Owens .G.W, & Knowels.P. "Steel Designs Manual", (sixth Edition) Steel Concrete Institute (UK) Oxford Black; well Scientific Publications, 2003.	4. Subramanian.N, Design of Reinforced Concrete Structures, Oxford University Press New Delhi, 2013 5. Subramanian.N, Design of Steel structures-Limit state method, Oxford University Press New Delhi, 2016

	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3(15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	30%	-	30%	-	30%	-	30%	-	30%	-
Level 2	Apply Analyze	50%	-	50%	-	50%	-	50%	-	60%	-
Level 3	Evaluate Create	20%	-	20%	-	20%	-	20%	-	10%	-
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Mini-Projects

Course Designers		
Experts from Industry		Experts from Higher Technical Institutions
1. Er. G.Hariharanath, GA Consultants, Chennai, gac1996@hotmail.com		1. Dr. R. Santhakumar, Professor, Centre for Rural Department, NITTTR
2. Er. AGV. Design, Design Group Engineering Consultancy Pvt Ltd. Chennai, design.agv@gmail.com		2. Dr. P. Jayabalan, NIT, Trichy, pjeya@nitt.edu
		Internal Experts
		Prof.G.Augustine Maniraj Pandian, SRMIST
		Prof. N.Umamaheswari, SRMIST

Course Code	18CEE310T	Course Name	SOLID AND HAZARDOUS WASTE MANAGEMENT	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	CIVIL ENGINEERING	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1:	Create insights to the various sources and classification of solid and hazardous waste	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2:	Address concepts related to waste characteristics and source reduction		
CLR-3:	Create insights to the storage, collection and transport of waste		
CLR-4:	Address concepts related to waste processing technologies		
CLR-5:	Address concepts related to waste disposal		
CLR-6:	Role of Government and NGO's in sustaining the waste management		

Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:															Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1:	Understand the various sources of solid and hazardous waste	2	85	80	H	H	M	L	-	L	H	-	-	-	-	L	M	-	-															
CLO-2:	Able to identify the options for Reduction, reuse and recycling of waste	2	85	75	H	H	H	H	-	-	H	-	-	-	-	-	M	-	-	-														
CLO-3:	Knowledge of collection and transport of solid and hazardous waste	2	80	75	H	H	M	M	-	L	H	-	-	-	-	-	L	M	-	-														
CLO-4:	Able to know about various waste processing techniques	2	85	75	H	H	H	H	-	-	H	-	-	-	-	-	M	-	-	-														
CLO-5:	Understand the waste disposal methods and management	2	85	80	H	H	M	M	L	L	M	-	-	-	-	-	L	M	-	-														
CLO-6:	Knowledge of basic solid and hazardous waste legislations	2	80	75	H	H	M	-	-	L	M	-	-	-	-	-	M	-	-	-														

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Sources, classification and regulatory framework: Sources of solid waste	Waste characterization and source reduction: Waste generation rates	Storage, collection and transport of waste: Handling of waste at source	Waste processing technologies: Objectives of waste processing	Waste disposal : Waste disposal options for solid and hazardous waste
	SLO-2 Types of solid waste	Waste generation variation	Segregation of waste at source	material separation technologies in solid waste	Disposal in landfills
S-2	SLO-1 Hazardous Waste - Identification	sampling and characterization	Storage of municipal solid waste	Physical Processing Equipment	Landfill Classification
	SLO-2 Hazardous Waste -Classification	factors affecting waste generation rate and Composition	On-site storage methods	material processing technologies	Landfill types
S-3	SLO-1 Need for solid waste management	Physical properties of solid waste	Effect of storage	chemical conversion technologies	Landfill methods
	SLO-2 Need for hazardous waste management	Chemical properties of solid waste	Materials used for containers	biological conversion technologies methods of Composting	Site selection
S-4	SLO-1 Elements of integrated waste management	Biological properties of solid waste	Collection of municipal solid waste- Methods	biological conversion technologies methods of Composting	Design and operation of sanitary landfills
	SLO-2 roles of stakeholder's	Hazardous Characteristics	Collection vehicles – Manpower – Collection routes	Factors of Composting	Landfill liners
S-5	SLO-1 Role of public and NGO's	TCLP tests	Analysis of Collection systems	Thermal conversion technologies-energy recovery	Secure landfills
	SLO-2 Tutorial 1: Case Study: Status of Waste Generation in Bangalore	Tutorial 3 : Practices in household waste management	Solving problems using Tutorial Sheet 7	Thermal conversion technologies- energy recovery	Landfill bioreactors
S-6	SLO-1 Public health and environmental impacts	Tutorial 4: Source Reduction and Recycling.	Need for transfer and transport	Incineration	Leachate management
	SLO-2 Salient features of Indian legislations on management and handling of municipal solid waste	Source reduction of waste	Transfer stations	Hazardous Waste Treatment	Landfill gas management

S-7	SLO-1	Hazardous waste	Waste exchange	Hazardous Waste-Storage and collection	Physical and chemical treatment	Landfill closure
	SLO-2	Biomedical waste	Extended producer responsibility	Hazardous Waste-Storage and collection	Thermal treatment	Environmental monitoring
S-8	SLO-1	Lead acid batteries	Recycling	Hazardous Waste -Transfer and transport	Biological treatment	Rehabilitation of open dumps
	SLO-2	Electronic waste	Reuse	Hazardous Waste -Transfer and transport	Pollution Prevention and Waste Minimization	Landfill remediation
S-9	SLO-1	Plastics and fly ash	Solving problems using Tutorial Sheet 5	Hazardous waste manifests	Hazardous Wastes Management in India	Solving problems using Tutorial Sheet 9
	SLO-2	Tutorial 2: Mention the public awareness program	Solving problems using Tutorial Sheet 6	Hazardous waste transport	Solving problems using Tutorial Sheet 8	Solving problems using Tutorial Sheet 10

Learning Resources	1. George Tchobanoglous, Hilary Theisen and Samuel A. Vigil, "Integrated Solid Waste Management, Mc-Graw Hill International edition, New York, 1993.	3. CPHEEO, "Manual on Municipal Solid waste management, Central Public Health and Environmental Engineering Organisation, Government of India, New Delhi, 2000.
	2. Michael D. LaGrega, Philip L Buckingham, Jeffrey C. E vans and Environmental Resources Management, Hazardous waste Management, Mc-Graw Hill International edition, New York, 2001.	4. NPTEL Course-Municipal solid waste management : https://nptel.ac.in/courses/120108005/ 5. NPTEL Course-Solid and Hazardous waste management : https://nptel.ac.in/courses/105106056/

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	60%	-	60%	-	60%	-	60%	-	60%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	-	-	-	-	-	-	-	-	-	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, and Conference Paper etc.

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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2. Mr. A. Abdul Rasheed, CMWSS Board, juruterarasheed@gmail.com	2. Dr. G. Dhinakaran, Asst. Professor, CES, Anna University, twinsdina@gmail.com	Mr. S. Dhanasekar, Asst.Prof, SRMIST

Course Code	18CEE311T	Course Name	AIR AND NOISE POLLUTION AND CONTROL	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	CIVIL ENGINEERING	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1:	Create insights to the various sources of air quality			1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Address concepts related to modeling of atmospheric pollutants			Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3:	Create insights to the air and noise pollution monitoring techniques						H	H	M	L	-	L	H	-	-	-	-	L	M	-	-
CLR-4:	Address concepts related to reduce air pollution						H	H	M	M	-	L	H	-	-	-	-	L	M	-	-
CLR-5:	Address concepts related to reduce noise pollution						H	H	H	H	-	-	H	-	-	-	-	-	M	-	-
CLR-6:	Role of Government and NGO's in sustaining the air pollution at the source						H	H	M	M	L	L	M	-	-	-	-	L	M	-	-
							H	H	M	-	-	L	M	-	-	-	-	-	M	-	-
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																				
CLO-1:	Understand the various sources of air and noise pollution			2	85	80															
CLO-2:	Able to analyze air quality parameters			2	85	75															
CLO-3:	Knowledge of atmospheric transport models for air pollutants			2	80	75															
CLO-4:	Able to identify techniques to reduce noise pollution			2	85	75															
CLO-5:	Apply the concept of reducing air and noise pollution			2	85	80															
CLO-6:	Knowledge of basic environmental legislations related to air and noise pollution			2	80	75															

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Introduction	Sources, classification and effects	Sampling and Meteorology	Air Pollution Control Measures	Noise pollution and its control
	SLO-2 Air pollutants, Sources, classification,	Ambient air quality and emission standards	Ambient air sampling	Basics of pollution control	Basics of acoustics and specification of sound;
S-2	SLO-1 Monitoring techniques for air and noise pollution	Air pollution indices.	pollution measurement methods,	Control equipments –	sound power, sound intensity and sound pressure levels;
	SLO-2 Combustion Processes and pollutant emission,	Natural sources	principles and instruments	Particulate control methods	plane, point and line sources, multiple sources;
S-3	SLO-1 Air Act, legislation and regulations	Type of air pollutants	Monitoring stations in India	settling chambers,	outdoor and indoor noise propagation;
	SLO-2 Air quality management in India.	Effects on Health, vegetation-	temperature lapse rate and stability	cyclone separation,	psychoacoustics and noise criteria,
S-4	SLO-1 Greenhouse effect.	-materials and atmosphere	Adiabatic lapse rate	Wet collectors	effects of noise on health, annoyance rating schemes;
	SLO-2 Urban heat island	Reactions of pollutants in the atmosphere and their effects	Wind Rose, Inversion	fabric filters	special noise environments
S-5	SLO-1 Major contributions of air pollutant	-Smoke, smog and ozone	Wind velocity and turbulence	electrostatic precipitators	Infrasound, ultrasound, impulsive sound and sonic boom;
	SLO-2 Noise -What is Noise?	Layer disturbance,	Plume behavior	Removal of gaseous pollutants by adsorption, absorption,	
S-6	SLO-1 Noise pollution,	Ambient noise quality and emission standards	Carbon emission	Biological air pollution control technologies,	noise standards and limit values;
	SLO-2 Sources, classification,	Noise pollution indices.	Noise sampling and Noise level meter	Indoor air quality	Occupational noise standard
S-7	SLO-1 Monitoring techniques for noise pollution	Manmade sources	Pollution measurement methods,	control principles	Noise instrumentation and monitoring procedure.
	SLO-2 Noise Act, legislation and regulations	Types of noise pollutant	Principles and instruments	Alternative	Noise indices.
S-8	SLO-1 Noise quality management in India.	Effects on Human Health and	Occupational noise monitoring	Case studies on Air pollution -1	Noise control methods
	SLO-2 Noise management in other countries	Occupational exposure	Monitoring-case studies	Case studies on Air pollution -1	Case studies on Air pollution– 2
S-9	SLO-1 Solving problems using Tutorial Sheet 1	Solving problems using Tutorial Sheet 3	Tutorial hour-1	Tutorial hour-3	Case studies on noise pollution
	SLO-2 Solving problems using Tutorial Sheet 2	Solving problems using Tutorial Sheet 4	Tutorial hour-2	Tutorial hour-4	Case studies on noise pollution

Learning Resources	1. C. S. Rao, "Environmental Pollution Control Engineering", Wiley Eastern Limited, 2000.	6. Mukherjee, "Environmental Pollution and Health Hazards", causes and effects, 1986 7. Antony Milne, "Noise Pollution: Impact and Counter Measures", David & Charles PLC, 1979. 8. Kenneth wark, Cecil F. Warner, "Air Pollution its Origin and Control", Harper and Row Publishers 9. NPTEL Online Course - Noise Management and Control : https://swayam.gov.in/nd1_noc19_me72/
	2. M. N. Rao, H. V. N. Rao, Air pollution, Tata McGraw Hill Pvt Ltd, New Delhi, 1993	
	3. Dr. Y. Anjaneyulu, "Air Pollution and Control Technologies", Allied publishers Pvt. Ltd., 2002.	
	4. Noel De Nevers, "Air pollution control Engineering", McGraw Hill International Edition	
	5. Peterson and E. Gross Jr., "Hand Book of Noise Measurement", 5 th Edition, 1963	

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	60%	-	60%	-	60%	-	60%	-	60%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	-	-	-	-	-	-	-	-	-	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, and Conf. Paper etc.

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. Elvis Dsouza, EDPC Polymer Industries, Maharashtraelvisdsouza11@gmail.com	Dr. Rehana Shaik, Assistant Professor, Dept of Civil Engineering, IIIT Hyderabad rehanaishc@gmail.com	Dr. Paromita Chakraborty, Research Assoc.Professor, SRMIST
Dr.Rajkumar Director Hubert Envirocare Systems, Chennai rajkumar@hecs.in	Dr. E.S.M Suresh Professor & Head Department of Civil Engineering NITTTTR, Chennaiesmsuresh@gmail.com	Mr. S.Ramesh, Assist. Prof & Mr.K.C. Vinuprakash, Assist. Prof. SRMIST

Course Code	18CEE312T	Course Name	ENVIRONMENTAL IMPACT ASSESSMENT AND LIFE CYCLE ANALYSIS				Course Category	E	Professional Elective											L	T	P	C				
																				3	0	0	3				
Pre-requisite Courses		Nil		Co-requisite Courses		Nil		Progressive Courses		Nil																	
Course Offering Department		CIVIL ENGINEERING				Data Book / Codes/Standards				Nil																	
Course Learning Rationale (CLR):		The purpose of learning this course is to:						Learning			Program Learning Outcomes (PLO)																
CLR-1 :		Know the interrelationship between various activities and their impact on environment						1 2 3			1 2 3 4 5 6 7 8 9 10 11 12 13 14 15																
CLR-2 :		Understand how to conduct an environmental impact assessment						Level of Thinking (Bloom) Expected Proficiency (%) Expected Attainment (%)			Engineering Knowledge Problem Analysis Design & Development Analysis, Design, Research Modern Tool Usage Society & Culture Environment & Sustainability Ethics Individual & Team Work Communication Project Mgt. & Finance Life Long Learning PSO - 1 PSO - 2 PSO - 3																
CLR-3 :		Learn principles and methods of environmental analysis																									
CLR-4 :		review and comment on an environmental impact statement, environmental assessment and environmental regulations																									
CLR-5 :		Understand role of standards and how government, NGOs, and the private sector can affect their evolution																									
CLR-6 :		Explain the concept of life cycle assessment (LCA) as an environmental management tool and its potential for identifying all the environmental impacts throughout the entire life cycle of a product																									
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																									
CLO-1 :		Explainkey concepts in environmental impact assessment & Management						3 85 80			H - - - - H H - - - - M - -																
CLO-2 :		Understand the importance of various rules & regulation in EIA						2 85 75			- M - - - M H - - - - M - -																
CLO-3 :		Evaluate the Impact on various environments and role of stake holders in EIA						2 80 75			H M - M - M M - - - - M - -																
CLO-4 :		Explain the application of Life cycle analysis						2 85 75			H M - - - H H M - - - M - -																
CLO-5 :		Identify most suitable tool for assessment process and make suggestions for solutions						2 85 80			H H - M M - M M - - - M - -																
CLO-6 :		Participate in a group to evaluate a project using EIA & LCA using one or more management tools						2 80 75			H H - M - - H - - - - H - -																
Duration (hour)		9		9		9		9		9		9															
S-1	SLO-1	Introduction Introduction, definitions and concepts of EIA, Ethics and environment, EIA for civil engineers		Evolution of EIA Evolution of EIA worldwide; Evolution of EIA in India; Forecasting Environmental Changes		Assessment Technique Components of the Environment: Water- Standards pertaining to water quality		Life Cycle Analysis Life cycle assessment and its purpose; Evolution of Life Cycle Assessment; Stages in LCA of a Product; A Code of Good Conduct for LCA		EIA Methodologies Initial Environmental Examination; Screening																	
	SLO-2	Discussion: Identify the Ethics that you breach in daily activities which affects the environment		Discussion: Introduction to importance of Rio Convention		Activity & Discussion using a Case Study		Discussion: Necessary for LCA		Case Study involving screening																	
S-2	SLO-1	Ecology and the environment ; Ecosystem and its characteristics		Types of EIA: Rapid; Comprehensive; Strategic; Sectoral; Regional Rationale and scope of each type		Components of the Environment: Air & Noise- Standards pertaining to Air & Noise quality		Procedures for LCA; Defining the goal and scope; Analyzing the inventory; Assessing environmental impact		Scoping Analysis of alternatives																	
	SLO-2	In continuation with previous class discussion in how the ecosystem in which you live gets affected your activities		Case Study		Activity & Discussion using a Case Study		Case Study using LCA		Case Study in EIA																	
S-3	SLO-1	Structure of Ecosystem; Biotic Components Abiotic components		EIA Regulations in India Overview of Indian laws – Constitutional Provisions (Water, Air, Forest, Hazardous etc)		Components of the Environment: Soil- Soil quality, Landuse Criteria		Carbon trading: Energy foot printing, Food foot printing and Carbon foot printing.		Mitigation- Definition, options for mitigation of impact on water, air and land, water, energy, flora and fauna																	
	SLO-2	Identify the impact of your activities on Biotic and abiotic components of your ecosystem& How their services gets affected		Discussion: Evolution of law with time		Activity & Discussion using a Case Study		Case Study On carbon footprint		Case study Employing mitigation measures																	
S-4	SLO-1	Food chains, Food webs and Tropic levels		EPA 1986		Components of the Environment: Biosphere (Macro, Micro)- Introduction to Hazard Exposure levels for biota		Environmental management: Principles, problems and strategies; Review of political, ecological and remedial actions.		Environmental Impact Statement- Document planning - collection and organization of relevant information																	
	SLO-2	Identify the impact of your activities on various trophic levels of your ecosystem		Discussion: Amendment of E(P) Rules, 1986 on time of 545 days for finalisation of Draft Notification (MOEFCC Website)		Activity & Discussion using a Case Study		Discussion With Activity: Why Environmental Management is important – using case study		Example: Case study with Documentation																	
S-5	SLO-1	Energy and energy flows; Elemental cycles.		EIA Notification 2006		Components of the Environment: Socio-economic		Environmental audit: Definitions,concepts, partial audit, compliance audit, methods & regulations.		ToR& Sectoral ToR																	

	SLO-2	Choose a element cycle and how it affects the ecosystem	Case Study	Activity & Discussion using a Case Study	Discussion: Introduction to ISO 19011 (EMS Auditing)	Example of ToR for various environments
S-6	SLO-1	Concept of Succession; Role of succession in restoration and recovery of ecosystem	CPCB and State PCBs – roles and responsibilities	Components of the Environment: Cultural and Aesthetics	Local infrastructure development and environmental management: A system approach, Regional environmental management system Landuse Conversion plan development and implementation strategies	Environmental Assessment- Base line, Construction Phase, Post Construction/ Operational phase scenario
	SLO-2	Example: Restoration of an ecosystem (Mining area)	Discussion: Sethusamudram Project- Role of CPCB & SPCB and Central & State Governments	Activity & Discussion using a Case Study	Discussion: Problems faced in developmental projects- using case study	Case study on a project
S-7	SLO-1	Ecosystem disturbances and their causes; natural causes and anthropogenic causes	Structured Environmental Management Systems ISO 14001 - EMS	Role of Public Participation in EIA	Environmental management systems in local government. Certification body assessments of EMS Documentation for EMS	Impact Assessment Methodologies: Checklists- Simple, Descriptive, Scaling Checklist
	SLO-2	Discussion: How Do Species Replace One Another in Ecological Succession?	Case Study: (Whitelaw and Butterworth, ISO 14001: Environmental System Handbook, 1997)	Reference EIA Notification 2006	Discussion: Expert systems (Software/ Model) used for EMS	Case study involving Checklist methods
S-8	SLO-1	Ecosystem and Ecological Footprints	ISO 18001- OHSAS	Role of stakeholders	Sustainable development – Definitions, Charter and Global Conventions; Future scenarios.	Matrix- Simple, Interaction- Leopold Matrix, Stepped matrix
	SLO-2	Discussion: How Cultural Changes Have Increased Our Ecological Footprints?	Discussion: Accreditation Procedure for ISO 14001	Activity & Discussion using a Case Study, Role Play	Discussion on various important conventions	Case study involving Matrix methods Discussion: Aldo Leopold's Environmental Ethics
S-9	SLO-1	Discussion of basic concepts	Environmental Risk Assessment	Setting the baseline	Case Studies on EIA	Network Methods Decision Tree, Expert Systems
	SLO-2	Example: Case study (An Affected Area)	Discussion: risk screening/prioritization	Discussion-Describe the various aspects of the environmental components of your neighborhood	Case Studies on EIA	Case study involving Network methods Introduction to various Expert system (Software/ models widely used)

Learning Resources	1. L. W. Canter, Environmental Impact Assessment, 2 nd Ed., McGraw-Hill, 1997.	5. H. Scott Matthews, Chris T. Hendrickson, and Deanna Matthews, Life Cycle Assessment: Quantitative Approaches for Decisions that Matter, 2014. Open access textbook, retrieved from https://www.lcatextbook.com/
	2. G. Burke, B. R. Singh and L. Theodore, Handbook of Environmental Management and Technology, 2 nd Ed., John Wiley & Sons, 2000	
	3. R. Therivel, John Glasson, Andrew Chadwick, Introduction to Environmental Impact Assessment (Natural and Built Environment), Routledge, 2005.	6. NPTEL Course - Environmental Management: https://nptel.ac.in/courses/120108004/16#
	4. K. Whitelaw and Butterworth, ISO 14001: Environmental System Handbook, 1997	7. NPTEL Course - Environmental Impact Assessment : https://nptel.ac.in/syllabus/105103024/

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	60%	-	60%	-	60%	-	60%	-	60%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	-	-	-	-	-	-	-	-	-	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, and Conf. Paper etc.

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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Dr. Rajkumar, Director, Hubert Envirocare Systems, Chennai, rajkumar@hecs.in	Dr. Harish Gupta, Osmania University, Hyderabad, harishgupta78@gmail.com	Mr. K. Prasanna, SRMIST

Course Code	18CEE313T	Course Name	DESIGN OF HYDRAULIC STRUCTURES AND IRRIGATION ENGINEERING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	CIVIL ENGINEERING	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1:	Provide knowledge on irrigation and its types, and on water movement through soil	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2:	Expound on the design principles of gravity and earthen dams and associated structures		
CLR-3:	Introduce diversion structures and their design by applying failure concepts		
CLR-4:	Provide an understanding of canal structures		
CLR-5:	Address concepts on sediment movement		
CLR-6:	Introduce design concepts for various types of canals		

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1:	Acquire knowledge on soil-plant-water relationship	2	85	80	H	H	-	-	-	-	-	-	-	-	-	-	H	-	-
CLO-2:	Complete a design for dams and spillways	2	85	75	H	H	-	H	-	-	-	-	-	-	-	-	H	-	-
CLO-3:	Understand the types of diversion structures and design them by applying failure concepts	2	85	75	H	H	-	H	-	-	-	-	-	-	-	-	H	-	-
CLO-4:	Identify the various canal structures and design them	2	85	80	H	H	-	H	-	-	-	-	-	-	-	-	H	-	-
CLO-5:	Understand basic concepts of sediment movement	2	80	75	H	H	-	-	-	-	-	-	-	-	-	-	H	-	-
CLO-6:	Design various types of canals considering efficiency and economy	2	85	75	H	H	-	H	-	-	-	-	-	-	-	-	H	-	-

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Irrigation: Necessity and importance of irrigation	Lane's weighted creep theory	Earthen dams – types	Canal falls – necessity and location of falls	Computing the design capacity of an irrigation canal
	SLO-2	Methods of irrigation	Design of a vertical drop weir on Bligh's creep theory	Design of earthen dams	Types of canal falls	Shield's entrainment method
S-2	SLO-1	Methods of improving soil fertility	Design of a vertical drop weir on Bligh's creep theory	Design of earthen dams	Design of a trapezoidal notch fall	Design of non-scouring stable channels with protected side slopes in alluvium soil (Shield's entrainment method)
	SLO-2	Standards of quality for irrigation water	Khosla's method – flow nets	Seepage analysis in earthen dams	Design of a trapezoidal notch fall	Design of non-scouring stable channels with protected side slopes in alluvium soil (Shield's entrainment method)
S-3	SLO-1	Duty and delta – factors affecting duty	Khosla's method of independent variables for determination of pressures and exit gradient for seepage below a weir or a barrage	Seepage analysis in earthen dams	Design of simple vertical drop fall	Design of non-scouring channels with unprotected side slopes in alluvium soil
	SLO-2	Methods of improving duty	Design problem on Khosla's method of independent variables	Design for stability of earthen dams	Design of simple vertical drop fall	Design of non-scouring channels with unprotected side slopes in alluvium soil
S-4	SLO-1	Irrigation efficiencies	Design problem on Khosla's method of independent variables	Design for stability of earthen dams	Design of a Sarda fall	Design of most efficient channel section
	SLO-2	Problems in irrigation efficiencies	Complete design of weir/barrage using Khosla's theory	Spillways – types and design considerations	Design of a Sarda fall	Design of most efficient channel section
S-5	SLO-1	Estimation of consumptive use –Blaney Criddle method	Complete design of weir/barrage using Khosla's theory	Design of chute spillway	Cross drainage works – types	Design of stable channels – Kennedy's theory
	SLO-2	Pan evaporation method – Penman's method	Storage structures: Gravity dam – cross section of gravity dam	Design of chute spillway	Cross drainage works – selection of suitable type	Design of stable channels – Kennedy's theory
S-6	SLO-1	Classes and availability of soil water – soil moisture deficiency	Modes of failure of gravity dam	Design of ogee spillway	Design considerations for cross drainage works	Design of stable channels – Lacey's theory

	SLO-2	Depth of water stored in root zone	Criteria for structural stability of gravity dam	Design of ogee spillway	Design considerations for cross drainage works	Design of stable channels – Lacey's theory
S-7	SLO-1	Limiting soil moisture conditions	Design considerations for gravity dam	Energy dissipators	Design of cross drainage works	Balancing depth of canals
	SLO-2	Depth and frequency of irrigation	Design considerations for gravity dam	Design of stilling basin	Design of cross drainage works	Balancing depth of canals
S-8	SLO-1	Diversion structures: Weirs and barrages	Design of gravity dam	Canal structures: Canal regulators – head and cross regulator	Design of cross drainage works	Economic justification of canal lining for unlined canals
	SLO-2	Diversion head works and its components	Design of gravity dam	Functions – Alignment of the off-taking channel	Design of cross drainage works	Economic justification of canal lining for unlined canals
S-9	SLO-1	Failure of hydraulic structures – failure by piping and failure by direct uplift	Design of gravity dam	Design of cross regulator	Conveyance: Mechanics of sediment transport	Design of lined canals
	SLO-2	Bligh's creep theory	Design of gravity dam	Design of distributary head regulator	Computing the design capacity of an irrigation canal	Design of lined canals

Learning Resources	1. Santhosh Kumar Garg, "Irrigation Engineering and Hydraulic Structures", Khanna Publishers, 2000. 2. Punmia B.C. et al., "Irrigation and Water Power Engineering", Laxmi Publications Pvt. Ltd., New Delhi, 2009 3. Asawa G. L., "Irrigation and Water Resources Engineering", New Age International Publishers, New Delhi, 2005.	4. Sharma R.K., "Irrigation Engineering and Hydraulic Structures", Oxford and IBH Publishing Company, New Delhi, 2002 5. NPTEL – Irrigation and Drainage: https://nptel.ac.in/courses/126105010/ 6. NPTEL – Water Resources Engineering: https://nptel.ac.in/downloads/105105110/
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Evaluate Create	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, MOOCs, Certifications, and Conf. Paper etc.

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Abdul Hakeem, National Remote Sensing Center, Hyderabad, abdulhakeem_k@nrsc.gov.in	1. Dr. Rehana Shaik, IIIT, Hyderabad, rehana.s@iiit.ac.in	1. Dr. Deeptha Thattai, SRMIST
2. Dr. Sat Kumar Tomer, Satyukt Analytics Pvt Ltd., Bengaluru, sat@satyukt.com	2. Dr. S. Saravanan, NIT Trichy, saravanan@s@nitt.edu	2. Dr. R. Sathyanathan, SRMIST

Course Code	18CEE314T	Course Name	GROUND WATER ENGINEERING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	CIVIL ENGINEERING	Data Book/Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Create insights into the occurrence and properties of groundwater	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2 :	Address concepts related to movement of groundwater																							
CLR-3 :	Create insights on well hydraulics																							
CLR-4 :	Address concepts related to exploration and investigation of groundwater																							
CLR-5 :	Create insights into groundwater management and seawater intrusion																							
CLR-6 :	Understand the software applications in groundwater modeling																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1 :	Understand the various properties of groundwater	2	85	80				H	M	L	L	-	L	H	-	-	-	-	L	M	-	-		
CLO-2 :	Understand the governing equations of groundwater movement	2	85	75				H	H	H	H	-	-	H	-	-	-	-	M	-	-	-		
CLO-3 :	Acquire the knowledge on yield of the well and its hydraulics	2	80	75				H	H	M	M	-	L	H	-	-	-	-	L	M	-	-		
CLO-4 :	Understand the concept of various methods of exploration	2	85	75				H	L	M	M	-	-	H	-	-	-	-	M	-	-	-		
CLO-5 :	Understand the concept of seawater intrusion and conjunctive use	2	85	80				H	M	H	H	-	M	M	-	-	-	-	L	M	-	-		
CLO-6 :	Acquire knowledge on groundwater modeling and models in use	2	80	75				H	H	H	H	H	M	H	-	-	-	-	H	M	-	-		

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Introduction to Groundwater: Global distribution of water, role of groundwater in hydrological cycle	Groundwater Movement Groundwater Movement- Governing Equation	Well Hydraulics Flow into a well	Subsurface Exploration Objective and Need for exploration Various methods
	SLO-2	Various water bearing formations, subsurface water distribution	Darcy's Law	Steady radial flow into a well: Dupuit equation, Thiem's equation	Geophysical investigations
S-2	SLO-1	Aquifers and types of aquifers	Heterogeneity and anisotropy	Unsteady radial flow into a well: Theis equation	Surface geophysical techniques
	SLO-2	Aquifer properties: porosity, permeability, specific yield, storage coefficient and transmissivity, factors affecting permeability	Estimation of aquifer parameters	Jacob's correction for very thin aquifers with water table condition	Electrical resistivity method
S-3	SLO-1	Problems on aquifer properties	Problems on Darcy's law	Problems on Theis equation	Seismic refraction method
	SLO-2	Problems on aquifer properties	Problems on aquifer parameter estimation	Problems on Jacob equation	Remote sensing in groundwater exploration
S-4	SLO-1	Groundwater fluctuation	1D governing equation of flow through porous medium	Theis recovery, well hydraulics	Other surveying methods
	SLO-2	Groundwater balance and budgeting	2D governing equation of flow through porous medium	Wells in leaky aquifer	Borehole geophysical techniques
S-5	SLO-1	Problems on water balance equation	Equation for flow into leaky aquifer	Partially penetrating wells	Electric logging, radioactive logging
	SLO-2	Problems on groundwater fluctuation	Flow through unconfined aquifer	Image well theory, multiple wells	Induction, fluid and sonic logging
S-6	SLO-1	Groundwater in different rocks	Boundary conditions	Well capacity and well development	Geochemical method of exploration
					Groundwater Management and Modeling Groundwater quality and Contamination
					Groundwater quality standards
					Types and sources of groundwater contamination
					Various quality parameters and its significance
					Attenuation of groundwater quality
					Potential evaluation of groundwater quality
					Physical, chemical and biological method of analysis
					Problems on quality evaluation
					Conjunctive use of groundwater and basin management
					Groundwater development under various scales
					Groundwater modeling, problems in groundwater

	SLO-2	Groundwater potential in India	Groundwater flow rates and direction	Construction and types of open well	Application of GIS in groundwater exploration	Types of models
S-7	SLO-1	Case Study 1	Groundwater flow problems	Construction and types of tube well	Seawater intrusion theory	Conceptual model, physical model
	SLO-2	Case Study 2	Steady one dimensional flow, flow into galleries	Problems on well hydraulics	Shape of interface	Mathematical model and analog model
S-8	SLO-1	GEC Norms	Aquifer with recharge	Problems on Theis recovery	Slope of interface	Data, input, boundary conditions and output, prediction
	SLO-2	Methodology of estimation	flow into confined aquifer with constant	Pumping test and recuperation test	Causes of seawater intrusion	Calibration and validation of a model
S-9	SLO-1	Status of groundwater in various parts of India- a case study	flow into confined aquifer with variable thickness	Problems on yield test	Effects of seawater intrusion	Groundwater models
	SLO-2	Threats to groundwater	Groundwater Theory, Solution for differential Equations	Well losses and determination	Various methods of reducing seawater intrusion	MODFLOW, MT3D, FEFLOW, SEAWAT

Learning Resources	1. Raghunath, H. M., "Ground Water", New Age International (P) Ltd, 2014. 2. D.K. Todd and L. F. Mays, "Groundwater Hydrology", John Wiley and Sons. 3. K. R. Karanth, "Hydrogeology", Tata McGraw Hill Publishing Company.	4. NPTEL course - Ground Water Hydrology: http://nptel.ac.in/courses/105105042/ 5. NPTEL course - Ground Water Hydrology: http://nptel.ac.in/courses/105103026/
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Understand	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Abdul Hakeem, National Remote Sensing Center, Hyderabad, abdulhakeem_k@nrsc.gov.in	1. Dr. Rehana Shaik, IIIT, Hyderabad, rehana.s@iiit.ac.in	1. Dr. Deeptha Thattai, SRMIST
2. Dr. Sat Kumar Tomer, Satyukt Analytics Pvt Ltd., Bengaluru, sat@satyukt.com	2. Dr. S. Saravanan, NIT Trichy, saravanans@nitt.edu	2. Ms. T. Saranya, SRMIST

Course Code	18CEE315T	Course Name	SURFACE HYDROLOGY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Civil Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1: Create insights into various hydrometeorological variables and components of hydrological cycle		1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2: Address concepts related to precipitation and water losses			
CLR-3: Analyze concepts of runoff and hydrograph analysis			
CLR-4: Address concepts related to floods and their estimation			
CLR-5: Create insights into reservoir routing and stream flow routing			
CLR-6: Address various types of models and their processes			
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Engineering Knowledge
CLO-1: Identify various hydrometeorological variables and components of hydrological cycle		2 85 80	H H - - - - - - - - - - H - -
CLO-2: Analyze precipitation and water losses		3 85 75	H H - - - - - - - - - - H - -
CLO-3: Understand runoff and hydrograph analysis		3 85 75	H H - - - - - - - - - - H - -
CLO-4: Analyze floods and their estimation		2 85 80	H H - - - - - - - - - - H - -
CLO-5: Understand reservoir routing and channel routing		2 80 75	H H - - - - - - - - - - H - -
CLO-6: Analyze various models and their processes		3 85 75	H H - - - - - - - - - - H - -

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Weather and climate	Precipitation: forms and types	Runoff, components of stream flow	Floods: Standard project flood, maximum probable flood, PMP, design flood	Systems and models – system concept in hydrology
	SLO-2 Scope of hydrometeorology	Test for consistency of the record, causes of inconsistency in the record	Catchment characteristics, watershed concepts	Estimation of peak flood: Empirical flood formulae- Dickens, Ryves, Inglis, Myers	Types of models – physical, conceptual, empirical, mathematical models
S-2	SLO-1 Meteorological variables	Double mass curve techniques	Classification of streams, isochrones	Rational method and concentration time method	Life cycle of a model
	SLO-2 Temperature, atmospheric pressure	Depth-Area relationship, Intensity-Duration-Frequency (IDF) curves	Factors affecting runoff	Problems on peak discharge	Types of mathematical models
S-3	SLO-1 Atmospheric humidity	Analysis of rainfall data	Runoff estimation: rational method, assumptions and drawbacks	Flood frequency studies: California method and Weibull method	Formulation of a mathematical model – modeling concepts
	SLO-2 Simple problems on saturation vapour pressure and relative humidity	Problems on mean, median and mode, mass curve, hyetograph, moving average, IDF and frequency curve	Components of streamflow hydrograph	Problems on flood frequency	Watershed–System concept
S-4	SLO-1 Clouds: categories and its classification	Design storm	Baseflow separation methods	Encounter probability: probability of exceedance and Probability of non-exceedance	Types of watershed models
	SLO-2 Atmosphere: different strata of atmosphere	Water losses	Problems on rainfall excess estimation by baseflow separation methods	Problems on encounter probability	Models in practice for various hydrologic processes
S-5	SLO-1 Wind and wind belts	Evaporation from water surfaces, Dalton's law of evaporation	Derivation of a unit hydrograph	Flood routing: Reservoir routing and channel routing	Stochastic model: space independent and space co-related
	SLO-2 Evaporation, vertical air motions	Evaporation pans: floating pans, land pan and Colorado sunken pan	Elements and propositions of unit hydrograph	Reservoir routing: ISD method	Artificial Neural Network (ANN)
S-6	SLO-1 Global distribution of water	Pan coefficient, problems on loss of water due to evaporation	Problems on unit hydrograph	Modified Pul's method	ANN activation function

	SLO-2	Water resources of India	Measures to reduce lake evaporation	Problems on unit hydrograph	Problem on reservoir routing	Network training algorithm – back propagation
S-7	SLO-1	Seasons in India	Transpiration, transpiration ratio and evapotranspiration	S-curve method	Problem on reservoir routing	Advantages and limitations of ANN
	SLO-2	Hydrology and hydrologic cycle	Consumptive use determination by Blaney-Criddle method, problems.	Problems on S-curve hydrograph	Stream flow routing: prism storage and wedge storage	Fuzzy sets and fuzzy logic
S-8	SLO-1	Distribution of rainfall in India	Infiltration, Horton's equation	Problems on S-curve hydrograph	Muskingum method	Fuzzification, evaluation of rules, defuzzification
	SLO-2	Scope of hydrology	Measurement of infiltration: infiltrometer and rainfall simulator	Synthetic unit hydrograph	Problem on Muskingum method	Fuzzy rule based reservoir operation model
S-9	SLO-1	Hydrological data	Infiltration indices: phi index and W-index	Snyder's method	Problem on Muskingum method	Changes in climate as related to water
	SLO-2	Hydrologic equation, simple problems on water budget.	Problems on Horton's equation and infiltration indices	Problems on Snyder's method	Flood forecasting and warning	Impacts and responses – climate change and water resources

Learning Resources	1. Raghunath, H.M., Hydrology, New Age International Publishers, New Delhi, 2007.	6. NPTEL Course – Advanced Hydrology: https://nptel.ac.in/courses/105101002/#
	2. Subramanya, K., Engineering Hydrology, McGraw Hill Education (India) Pvt. Ltd., New Delhi, 2014	7. Bates, B.C., Z.W. Kundzewicz, S. Wu and J.P. Palutikof, Eds., 2008: Climate Change and Water. Technical Paper of the Intergovernmental Panel on Climate Change, IPCC Secretariat, Geneva, 210 pp.
	3. Pukh Raj Rakhecha and Vijay P. Singh, Applied Hydrometeorology, Capital Publishing Company, 2009.	8. NPTEL course – Watershed Management: https://nptel.ac.in/courses/105101010/16
	4. Chow, V.T., and Maidment, Hydrology for Engineers, McGraw Hill Inc., Ltd., 2000	
	5. Vedula, S., and Mujumdar, P.P., Water Resources Systems, McGraw Hill Inc., 2005	

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Abdul Hakeem, National Remote Sensing Center, Hyderabad, abdulhakeem_k@nrsc.gov.in	1. Dr. Rehana Shaik, IIIT, Hyderabad, rehana.s@iiit.ac.in	1. Dr. R. Sathyanathan, SRMIST
2. Dr. Sat Kumar Tomer, Satyukt Analytics Pvt Ltd., Bengaluru, sat@satyukt.com	2. Dr. S. Saravanan, NIT Trichy, saravanan@nitt.edu	2. Dr. Deeptha Thattai, SRMIST

Course Code	18CEE401T	Course Name	PAVEMENT ANALYSIS AND DESIGN	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	CIVIL ENGINEERING	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1:	Learn layered structure stress-strain analysis	1	1
CLR-2:	Understand the viscoelastic characterization of the material	2	2
CLR-3:	To impart basic knowledge on various bituminous technology and its characterization	3	3
CLR-4:	Familiarize with the design of flexible pavement	4	4
CLR-5:	Study about the distress of pavements	5	5
CLR-6:	Knowabout the pavement condition survey	6	6
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Engineering Knowledge
CLO-1:	analyze the critical conditions of the layered structure	2	H
CLO-2:	Predict the real time behavior of the material	2	H
CLO-3:	Select appropriate material for the bituminous pavement construction	2	H
CLO-4:	Design the flexible pavement for different conditions of traffic and with different material combination	2	H
CLO-5:	Evaluate the existing condition of the pavement	2	H
CLO-6:	Suggest the suitable measures to improve the condition of the pavement	2	H
		Expected Proficiency (%)	Problem Analysis
		Expected Attainment (%)	Design & Development
			Analysis, Design, Research
			Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Stress Analysis of Layered Structure: Importance of pavement design	Viscoelasticity: Introduction to viscoelasticity	Pavement Materials: Bitumen.	Design of Flexible pavement: Different layers of flexible pavement
	SLO-2	Overview of layered system	Creep and recovery	Modified bitumen	Design factors
S-2	SLO-1	Single layer system- stress analysis	Stress relaxation	Bitumen emulsion-Types	Traffic factors
	SLO-2	Single layer system- stress analysis	Viscoelastic models	Grading of bitumen	Traffic factors
S-3	SLO-1	Solving problems	Viscoelastic solid model	Performance grading	Material characteristics
	SLO-2	Solving problems	Derivation of Voigt-Kelvin model	Aging of binder	Temperature
S-4	SLO-1	Two-layer pavement- stress analysis	Creep and recovery response of Voigt-Kelvin model	Bituminous mixture	Critical locations in pavement
	SLO-2	Two-layer pavement- stress analysis	Stress relaxation response of Voigt-Kelvin model	Hot mix asphalt mixture	Pavement design as per IRC
S-5	SLO-1	Solving problems	Viscoelastic fluid model	Warm mix asphalt mixture	Solving problems-VDF
	SLO-2	Solving problems	Derivation of Maxwell model	Half warm mix asphalt mixture	Solving problems-VDF
S-6	SLO-1	Multilayered stress analysis	Creep and recovery response of Maxwell model	Cold mix asphalt mixture	Solving problems-Pavement Design
	SLO-2	Multilayered stress analysis	Stress relaxation response of Maxwell model	Cold mix asphalt mixture	Solving problems-Pavement Design

S-7	SLO-1	Multilayered stress analysis	Burger's model	Mixture characterization - Resilient modulus	Solving problems-Pavement Design	Design of overlay by Benkelman beam method
	SLO-2	Multilayered stress analysis	Derivation of Burger's model	Mixture characterization - Determination of resilient modulus	Solving problems-Pavement Design	Design procedure
S-8	SLO-1	Software demo for multilayered structure	Oscillatory shearing	Mixture characterization - Dynamic modulus	Airfield pavement	Design procedure
	SLO-2	Software demo for multilayered structure	Response of elastic material to Oscillatory shearing	Mixture characterization - Determination of dynamic modulus	Specifications of airfield pavement	Solving problems
S-9	SLO-1	Software demo for multilayered structure	Response of viscous material to Oscillatory shearing	Mixture characterization - Time-temperature superposition	Design procedure of airfield pavement	Solving problems
	SLO-2	Software demo for multilayered structure	Response of viscoelastic material to Oscillatory shearing	Mixture characterization – Rutting and fatigue characterization	Design procedure of airfield pavement	Solving problems

Learning Resources	<ol style="list-style-type: none"> 1. Yang Huang, <i>Pavement Analysis and Design</i>, Pearson, 2004 2. Chakroborthy and A. Das, <i>Principles of Transportation Engineering</i>, Prentice-Hall of India, 2003 3. S. K. Khanna, C.E.G. Justo and A. Veeraragavan, <i>Highway Engineering</i>, Revised 10th edition, Nem Chand & Bros., Roorkee, 2014. 4. Yoder, E.J., and Witzczak, <i>Principles of Pavement Design</i>, 2nd ed. John Wiley and Sons, 1975. 5. Wineman, A.S. and Rajagopal, K. R, <i>Mechanical Response Of Polymers: An Introduction</i>, Cambridge University Press, 2000. 6. 6. Guidelines for the Design of Flexible Pavements, IRC :37, The Indian Road Congress, New Delhi 7. Subash C, Saxena, <i>Textbook of Highway and Traffic Engineering</i>, CBS Publishers, 1st Edition, 2014 8. NEPTEL link - https://nptel.ac.in/courses/105105107/1 and https://nptel.ac.in/courses/112104040/12 (as on 05.07.2019)
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	30%	-	30%	-	30%	-	30%	-	30%	-
Level 2	Apply Analyze	40%	-	40%	-	40%	-	40%	-	40%	-
Level 3	Evaluate Create	30%	-	30%	-	30%	-	30%	-	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

#CLA – 4 can be from any combination of Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conference Paper

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Dr. Asif Ahmed, Business manager, Ingevity, ahmed.asif@ingevity.com	Dr. Venkaiah Chowdary, Associate Professor, NITW, vc@nitw.ac.in	Dr. A. Padma Rekha, SRM IST
Mr. Ankit Pachouri, Transport Planner, IUT, New Delhi, ankit.pachouri@iutundia.org	Dr. V Sunitha, Assistant Professor, NITT, sunitha@nitt.edu	Ms R Dhanya, SRM IST

Course Code	18CEE402T	Course Name	RAILWAY, AIRPORT AND HARBOUR ENGINEERING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	CIVIL ENGINEERING	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1:	Get exposed to Railway track planning and design	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2:	Understand the process of operation and maintenance of Railway track	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3:	Attain knowledge on the concepts of planning and design of airport components	Expected Proficiency (%)	Problem Analysis
CLR-4:	Learn the structural design of the airfield pavement	Expected Attainment (%)	Design & Development
CLR-5:	Understand the process in the Evaluation of the airfield pavement		Analysis, Design, Research
CLR-6:	Acquire knowledge on the site characteristics and component planning for harbour		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1:	Apply the planning and design concepts of railway alignment and geometric design of railway track	2 85 80	H H M L - L H - - - - L M - -
CLO-2:	Plan and design the operational facilities for effective rail transportation	2 85 75	H H H H - - H - - - - - M - -
CLO-3:	Apply the planning and design concepts of airport components	2 80 75	H H M M - L H - - - - L M - -
CLO-4:	Design the airfield pavement	2 85 75	H H H H - - H - - - - - M - -
CLO-5:	Evaluate the airfield pavement	2 85 80	H H M M L L M - - - - L M - -
CLO-6:	Understand the basic need for handling the cargos in the harbour	2 80 75	H H M - - L M - - - - - M - -

Duration (hour)	9	9	9	9	9
S-1	SLO-1	RAILWAY PLANNING AND DESIGN Introduction to railway engineering	Numericals in length of transition curve	AIRPORT PLANNING AND GEOMETRIC DESIGN Importance and limitations Advantages and Limitations of Air Transport.	PAVEMENT DESIGN AND EVALUATION Importance of pavement design and evaluation
	SLO-2	Role of Indian Railways in National Development	Numericals in length of transition curve	Characteristics of Air travel.	Components of airfield pavement
S-2	SLO-1	Track Alignment -Importance	Widening of Gauges in Curves , Gradients Grade Compensation	Airport Master Plan, Evaluation and Institutional arrangements	Wheel and Axle Configurations
	SLO-2	Obligatory points in railway track alignment	Vertical Curves	Site Selection and survey.	Traffic considerations
S-3	SLO-1	Engineering Surveys for Track Alignment	RAILWAY TRACK OPERATION AND MAINTENANCE Points and Crossings -	Components of airport- Runway Orientation,	Stress and strain analysis in airfield pavement
	SLO-2	Remote Sensing, GIS &GPS, EDM and other equipment	Turnouts – Types - Working Principle	Cross wind Component, Wind rose Diagram	Stress and strain analysis in airfield pavement
S-4	SLO-1	Permanent Way and its components	Signaling	Numericals in Type I and II Wind Rose Diagram	Numericals in stress and strain
	SLO-2	Functions of each component -Concept of Gauges	Interlocking	Basic Runway length and Corrections	Numericals in stress and strain
S-5	SLO-1	Gauges and the type of gauges	Track Circuiting	Numericals in Corrections of BRL	Cummulative Damage Factor
	SLO-2	Coning of Wheels, Creeps and kinks	Construction & Maintenance Materials,	Numericals in Corrections of BRL	Environmental factors
S-6	SLO-1	Geometric Design of Railway Tracks - basic terms and representations	Track Drainage	Airport classification, Geometric design and specifications of runway	FAARFIELD input
	SLO-2	Super-Elevation, Negative superelevation	Track Modernization	Geometric Design elements and specifications of taxiway	Design of airfield pavement using FAARFIELD
S-7	SLO-1	Numericals in design of superelevation	Automated maintenance and upgrading, Technologies,	Runway patterns - Minimum Separation Distances	Pavement Evaluation - importance
					Harbour Engineering Importance of Harbour Engineering
					History and modern trends of waterway transportation,
					Definition of Terms - Harbours, Ports, Docks, , Sounding,
					Tides and Waves, Sounding, Littoral Drift
					Classification of Harbours
					Site Selection and harbour planning
					Types of Layouts of ports and components
					Approach facilities- With head gates, Without head gates
					Protection facilities
					Breakwater and its types
					Docking facilities
					Wet docks and Dry docks
					Navigational Aids - Buoys and Beacons

	SLO-2	Numericals in design of superelevation	Re-laying of Track	Clearance over Highways and Railways	Method of evaluation and overview	Light ships, Light house
S-8	SLO-1	Numericals in design of superelevation	Lay outs of Railway Stations and Yards,	Drainage - Airport Zoning	Structural Evaluation - test procedure	Storage Facilities
	SLO-2	Numericals in design of superelevation	Rolling Stock	Aircraft parking systems	Structural Evaluation - evaluation techniques	Dolphins
S-9	SLO-1	Horizontal Curves, Transition Curves,	Tractive Power, Track Resistance	Visual Aids , Wind Direction Indicators	Functional Evaluation - test procedure	Mooring Accessories
	SLO-2	Numericals in length of transition curve	Numericals in Tractive resistance	Runway and Taxiway Markings and Lightings	Functional Evaluation - evaluation techniques	Dredging facilities

Learning Resources	<p>1. SaxenaSubhash C and Satyapal Arora, "A Course in Railway Engineering", DhanpatRai and Sons, Delhi, 1998.</p> <p>2. Khanna S K, Arora M G and Jain S S, "Airport Planning and Design", Nemchand and Brothers, Roorkee, 1994.</p> <p>3. R Horonjeff and F X Mckelvy, Planning and design of Airport, Mc-Graw Hill International Editions, 1993</p>	<p>4. R. Srinivasan, "Harbour, Docks and Tunnel Engineering", Charotar Publishing home, 27th Edition, 2015</p> <p>5. S P Bindra, "A Course in Docks and Harbour Engineering", DhanpatRai and Sons, NewDelhi, 1993.</p> <p>6. NPTEL link - https://nptel.ac.in/courses/105107123/ (as on 05.07.2019)</p>
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	30%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of Assignments, Seminars, Tech Talks, Mini Projects, Case Studies, Self Study, MOOCs, Certifications, Conference Paper

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Dr. Asif Ahmed, Business manager, Ingevity, ahmed.asif@ingevity.com	Dr. VenkaiahChowdary, Associate Professor, NITW, vc@nitw.ac.in	Dr. A. Padma Rekha, SRM IST
Mr.AnkitPachouri, Transport Planner, IUT, New Delhi, ankit.pachouri@iutundia.org	Dr. V Sunitha, Assistant Professor, NITT, sunitha@nitt.edu	MsArunimaJayakumar, SRM IST

Course Code	18CEE403T	Course Name	TRAFFIC ENGINEERING AND MANAGEMENT	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	CIVIL ENGINEERING	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand the basics of traffic flow modelling.	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Familiarize the microscopic modelling	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Learn and understand the level of service of traffic flow				H	H	M	L	-	L	H	-	-	-	-	L	M	-	-
CLR-4 :	Address the issues related to flow interruptions				H	H	H	H	-	-	H	-	-	-	-	L	M	-	-
CLR-5 :	Learn and design the facilities required for the traffic control measures				H	H	H	H	-	-	H	-	-	-	-	M	-	-	-
					H	H	M	M	L	L	M	-	-	-	-	L	M	-	-
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	2	85	80	H	H	M	-	-	L	M	-	-	-	-	M	-	-	-
CLO-1 :	Develop model for the traffic stream parameters	2	85	75	H	H	M	M	-	L	H	-	-	-	-	L	M	-	-
CLO-2 :	Create the microscopic models of the traffic flow	2	85	75	H	H	M	M	-	L	H	-	-	-	-	L	M	-	-
CLO-3 :	Apply the qualitative rankings on uninterrupted flow	2	85	75	H	H	M	M	-	L	H	-	-	-	-	L	M	-	-
CLO-4 :	Provide the facilities for interrupted flow	2	85	75	H	H	M	M	L	L	M	-	-	-	-	L	M	-	-
CLO-5 :	Apply the concept of traffic control measures	2	85	80	H	H	M	M	L	L	M	-	-	-	-	L	M	-	-
		2	80	75	H	H	M	-	-	L	M	-	-	-	-	M	-	-	-

Duration (hour)	9	9	9	9	9
S-1	TRAFFIC STREAM MODELLING Importance of traffic Engineering and need for flow modelling	MICROSCOPIC TRAFFIC FLOW MODELLING Concepts of microscopic modeling	UNINTERRUPTED FLOW Concept of uninterrupted flow	INTERRUPTED FLOW Concept of interrupted flow - intersections	TRAFFIC CONTROL Various traffic control measures
S-2	Importance of traffic Engineering and need for flow modelling	Car-following model, Basic terms and notations	Definitions - Capacity, Level of Service(LoS)	Various traffic measures for interrupted flow	Applications of control measures
S-3	Fundamental parameters - speed, density, volume, travel time, headway, spacing	Concept of stimulus - response	Highway capacity	Traffic signs	Traffic signal - elements
S-4	Time-Space diagram	Application of stimulus response theory in traffic flow modelling	Factors affecting LoS	Types and specifications	Definition and analysis of saturation headway, saturation flow, lost time
S-5	Fundamental relations - time mean speed, space mean speed and their relation,	General motor's models	HCM methods	Road markings - longitudinal marking	Phase design - two, three, four phases
S-6	Numerical problems and solutions	Derivation - general motor model	Urban Street - Classification	Road markings - transverse and object marking	Cycle time determination - Green split time
S-7	Relation between speeds, flow, density,	Simulation Problem in general motor model	Operational Performance measures	Channelization	Definitions and measurement of stopped and control delay
S-8	Fundamental diagrams	Simulation Problem in general motor model	Congestion Management	Case studies	Webster's delay model
S-9	Greenshield's model – Assumptions and model form	Simulation Problem in general motor model	Case studies for congestion management	Traffic rotary	Problems in traffic signal design
S-10	Derivation -greenshield model	Simulation Problem in general motor model	Case studies for congestion management	Conflict resolution in a rotary	Capacity and LoS analysis
S-11	Numerical solution - Greenshield model	Vehicle arrival model,Poisson distribution	Multilane highways - Characteristics, Capacity	Geometric layout	HCM 2000 method - analysis of a signalized intersections
S-12	Numerical solution - Greenshield model	Problems in Poisson distribution	Multilane highways - Level of service	Design elements of rotary	Determination of level of service as per HCM 2000
S-13	Greenberg's logarithmic model	Headway modeling	Freeway operations	Capacity of rotary	Signal coordination- concepts

	SLO-2	Underwood's exponential model	Random vehicle generation	Freeway operations- operational considerations	Problem in rotary capacity	Application of coordinated traffic signal
S-8	SLO-1	pipe's generalized model	Microscopic traffic simulation	Capacity and Level of service of freeway segment	Grade separated intersection - road over bridges	Concept of offset
	SLO-2	multi-regime models	Microscopic traffic simulation	Capacity and Level of service of freeway segment	Underpass, Overpass concepts	Common cycle length and bandwidth
S-9	SLO-1	Moving observer method.	Design, calibration, validation, applications,	Weaving operation	Types of interchanges based on the traffic flow	Offset for one-way and two-way streets
	SLO-2	Numerical solution - moving observer method	Operational models.	Weaving operation	Case studies on interchanges	Vehicle actuated signals

Learning Resources	<ol style="list-style-type: none"> 1. Roess, R. P. McShane, W. R. & Prassas, E. S. (1998), <i>Traffic Engineering</i>, Prentice – Hall. 2. May, A. D. (1990), <i>"Fundamentals of Traffic Flow"</i>, second edn, Prentice Hall. 3. Papacostas, C. S. (1987), <i>"Fundamentals of Transportation Engineering"</i>, Prentice-Hall, India 4. Kadiyali, L. R. (1987), <i>"Traffic Engineering and Transportation Planning"</i>, Khanna Publishers, India. 5. Papacostas, C. S. and Prevedouros, P.D. (2001) <i>"Transportation Engineering and Planning"</i>, Prentice Hall of India Pvt. Ltd. 6. Highway Capacity Manual (2010), Transportation Research Board, USA 7. NPTEL link - https://nptel.ac.in/downloads/105101008/# (as on 05.07.2019)
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	30%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of Assignments, Seminars, Tech Talks, Mini Projects, Case Studies, Self Study, MOOCs, Certifications, Conference Paper

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Dr. Asif Ahmed, Business manager, Ingevity, ahmed.asif@ingevity.com	Dr. Venkaiah Chowdary, Associate Professor, NITW, vc@nitw.ac.in	Dr. A. Padma Rekha, SRM IST
Mr. Ankit Pachouri, Transport Planner, IUT, New Delhi, ankit.pachouri@iutundia.org	Dr. V Sunitha, Assistant Professor, NITT, sunitha@nitt.edu	Mr. G. Sivaprakash, SRM IST

Course Code	18CEE404T	Course Name	CONSTRUCTION EQUIPMENT AND AUTOMATION	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Civil Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 : Identify the management concepts of construction equipment		1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 : Identify the various earthwork equipments and its applications in real projects		Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 : Identify the various off shore equipments and techniques for dewatering		Expected Proficiency (%)	Problem Analysis
CLR-4 : Identify the various equipments used on aggregate and concrete production		Expected Attainment (%)	Design & Development
CLR-5 : Analyze the basic concepts of methods and techniques on demolishing and dismantling structures			Analysis, Design, Research
CLR-6 : Explore the advanced level of automated equipments for various construction activities			Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 : Accrue the knowledge of equipment management and cost controlling methods		2 85 75	H M - L - - H M M H H M - H
CLO-2 : Apply the knowledge of calculating productivity of earthwork equipments		3 85 75	H H - L - - - H H H M M - H
CLO-3 : Accrue the knowledge of equipments used in off shore construction practice		2 85 75	H H - M M - - - H H H M M - H
CLO-4 : Accrue the knowledge of equipments used for aggregate and concrete production, techniques for demolition		3 85 75	H H - M M - - - H H H M M - H
CLO-5 : Apply the knowledge in demolition and dismantling the distressed structures		2 85 75	H H - H M - - - H H H M M - H
CLO-6 : Accrue comprehensive knowledge of automation in construction practices		2 85 75	H H - M H - - - H H H H M - H

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Introduction on Construction Equipment	Earth Moving operations	Dredging equipment	Drilling equipments
	SLO-2		Types of Earthwork Equipment	Types of Dredging equipment	Lifting equipments
S-2	SLO-1	Equipment Management in Construction Projects	Earthwork Equipment - Tractors	Types of trenching equipment	Types of Drilling equipments
	SLO-2	Management Programme	capacity calculations	Principles of Blasting	Material handling equipments
S-3	SLO-1	Maintenance and Safety management	Earthwork Equipment - Motor Graders	Types of Blasting equipment	Hoisting Equipments
	SLO-2	Equipment requirement for construction project	Capacity calculations	Aggregate production equipment	Types and safety precautions
S-4	SLO-1	Planning of Equipment	Earthwork Equipment - Scrapers,	Concept of Pipe jacking techniques	Slip form techniques
	SLO-2	Selection of Equipment	capacity calculations	Equipment used for Pipe jacking	Crushers
S-5	SLO-1	Cost Control of Equipment	Earthwork Equipment - Front end Loaders	Compaction equipments	Various types of crushers, feeders and screening equipments
	SLO-2	Depreciation on Equipment	capacity calculations	Types of Compaction equipments	Equipments for Conveyors
S-6	SLO-1	Conventional construction methods	Earthwork Equipment – Bull dozer	Pumping and Dewatering equipments	Types of Conveyors
	SLO-2		Capacity calculations	Concrete mixers	Prestressing techniques
				Types of concrete mixers	Insitu prestressing in high rise structures
				Pouring and pumping of concrete	Aerial transportations
				Precautions	Applications and applications

S-7	SLO-1	Mechanized methods	Earthwork Equipment – Excavators	Pile Driving Equipments	Ready mix concrete - concept and procedure	Robots in construction
	SLO-2	Advanced Mechanized methods	Capacity calculations	Types and methods		Different automated equipments
S-8	SLO-1	Types of construction project	Equipments Used for Box Jacking Techniques	Concept of Cofferdam	Demolition equipment	Conventional plastering machines
	SLO-2	Types of construction equipment		Sheet piling	Controlled demolition techniques	Use of robots for repetitive activities
S-9	SLO-1	Safety Management	General safety in excavations	Tunneling equipments	Sequence of demolition	Drones in construction
	SLO-2	Safety measures		Methods of tunneling	Procedure for Dismantling	Advantages of drones

Learning Resources	1. Peurifoy, R.L., Ledbetter, W.B. and Schexnayder, C. "Construction Planning Equipment and Methods", McGraw Hill, Singapore 2005.	4. Mahesh Varma .Dr., "Construction Equipment and its planning and application", Metropolitan Book Company, New Delhi, 2003.
	2. Sharma S.C. "Construction Equipment and Management", Khanna Publishers, Delhi, 2008.	5. https://nptel.ac.in/courses/105104161/12
	3. Deodhar, S.V. "Construction Equipment and Job Planning", Khanna Publishers Delhi, 2008.	6. https://nptel.ac.in/courses/105103023/

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100%	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, and Conf. Paper etc.

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. G. Murali, Manager, Srivari Foundation, gmuralioffice@gmail.com	Dr. K.Yogeswari, B.S. Abdur Rahman Crescent Institute of Science and technology, yogeswari@crescent.education	Mr. V.R.Prasath Kumarr, SRMIST
Mr. K. M. Nanthan, , L&T, RKMNNN@Intecc.com	Dr. J. Saravanan, Annamalai University, ausjs5070@gmail.com	Mr. S. Prakashchander, SRMIST

Course Code	18CEE405T	Course Name	CONTRACTS MANAGEMENT	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Civil Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1:	To understand Indian Contract Act and to know the various types of construction contracts and their legal aspects				Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Learn about contracts and agreements									Problem Analysis														
CLR-3:	Acquire the knowledge of FIDIC concepts									Design & Development														
CLR-4:	Apply the concept of various types of taxes									Analysis, Design, Research														
CLR-5:	Learn about the different types of labour laws									Modern Tool Usage														
CLR-6:	Utilize the knowledge of labour laws and legal requirements in broader perspective				Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3										
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1:	Understanding the method of quoting the rates for bidding and tender process				3	85	75	H	M	-	-	-	M	-	H	H	M	L	M	H	-	L		
CLO-2:	Knowing the types of contracts				2	85	75	H	H	-	-	-	M	-	H	H	M	L	M	H	-	L		
CLO-3:	Steps involved in making contracts and records to be maintained in execution of contract				2	85	75	H	H	-	-	-	M	-	H	M	M	L	M	H	-	L		
CLO-4:	Knowledge in legal requirements in construction				2	85	75	H	M	-	-	-	L	-	H	M	M	L	M	H	-	L		
CLO-5:	Awareness of labour laws and Indian Contract Act				2	85	75	H	L	-	-	-	L	-	H	M	M	L	M	H	-	L		
CLO-6:	Acquiring knowledge to execute a contract				2	85	75	H	H	-	-	-	M	-	H	H	M	L	M	H	-	L		

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Indian contract act	Tender- Definitions and Methods	Construction claims: Extra items and causes of claims	Legal Requirements- Insurance and Bonding
	SLO-2	Definitions and important terms. Clause 1-75	Need for tendering, agreements and bonds in tendering process	Types of construction claims, documentation	Types of insurance
S-2	SLO-1	Elements of contract	Notice inviting tender	Settlement of claims	Laws governing sale
	SLO-2	Types of contract – Legal parlance, Engineering contracts	Tender- Prequalification process	Arbitration- comparison and action of laws	Purchase and sale of urban and rural land
S-3	SLO-1	Features and suitability	Bidding, Accepting	Agreements, subject matter	Land revenue codes
	SLO-2	Design of contract documents	Evaluation of technical, contractual and commercial point of view	Causes of disputes and importance of role of various stakeholders in prevention of disputes	Tax laws- income tax, sales tax, VAT
S4	SLO-1	International contract document	One cover and two cover system	Alternate dispute resolution methods	Excise on custom duties and their influence on construction cost
	SLO-2	Standard contract document	Contract formation and interpretation	Violations, Appointment of arbitrator	Legal requirements for planning
S-5	SLO-1	Importance of breach of contract	Potential contractual problems	Conditions of arbitrator Powers and duties of arbitrator	Property law, Agency law
	SLO-2	Law of torts	World bank procedures and guidelines	Rules of evidences	Local government laws for approval
S-6	SLO-1	Special and general conditions of contract	Tamilnadu transparency in tenders Act.	Dispute review boards	Statutory regulations
	SLO-2	Introduction to FIDIC contracts and types	EMD, SD	Indian arbitration and conciliation act 1996	The companies act 1956: nature and definition of a company
S-7	SLO-1	ICE conditions- introduction	Environmental provisions for construction contracts	Difference between 1940 act and 1996 act	Registration and incorporation
	SLO-2	Evaluation of FIDIC document, types	Duties and responsibilities- engineers and contractors, Project manager, owner	Extent application of 1996 act. objectives and general provisions	Memorandum of association

S-8	SLO-1	Design and build contract, EPC contract	Important site documents	Conciliation and its provisions in the act	Articles of association,, prospectus, kinds of company	Building and other construction works act, 1996
	SLO-2	Short forms contract-colour code	Process of building permissions	Conduct of conciliation and arbitral proceedings, ground for challenge	Directors: powers, duties, meetings and winding up	Employees state insurance act, 1948
S-9	SLO-1	Various conditions of red book	Provisions for scheduling delays and accelerations	Procedure of appeal against the awards.	Managing performance- introduction, monitoring and performance	Contract labour act, 1970
	SLO-2	Case study	Case study	Case study	Case study	Case study

Learning Resources	1. John G. Betty., "Engineering Contracts", McGraw Hill, 2003	4. Joseph T. Bockrath, "Contracts, the Legal Environment for Engineers and Architects", McGraw Hill, 2000.
	2. Gajaria G.T., "Laws Relating to Building and Engineering Contracts in India", M. M. Tripathi Private Ltd., Bombay, 1982 Tamilnadu PWD Code, 2006.	5. Lecture Notes, "Legal Aspects for Civil Engineers, Short Term Course organized by SRMEC", 29th May to 4th June, 2002.
	3. Jimmie Hinze, "Construction Contracts", McGraw Hill, 2001	6. https://nptel.ac.in/courses/105103093/11
		7. https://nptel.ac.in/syllabus/105102013/

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40	-	30	-	40	-	30	-	40	-
	Understand										
Level 2	Apply	40	-	40	-	40	-	30	-	40	-
	Analyze										
Level 3	Evaluate	20	-	30	-	20	-	40	-	20	-
	Create										
	Total	100 %		100 %		100 %		100 %		100%	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, and Conf. Paper etc.

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Department coordinators
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Mr. Rajeev Srinivasan, , NASS Contracting, Rajeev.srinivasan@nasscontracting.com	Dr. S. Kamal, University College of Engineering, Ramnad, kamalselva21@gmail.com	Mr. S. Anandh, SRM IST

Course Code	18CEE406T	Course Name	REPAIR AND REHABILITATION OF STRUCTURES	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Civil Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1:	To assess the diagnosis of distress	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2:	To provide an overview of performance of concrete structures	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3:	To identify the sources of dampness and its prevention remedies	Expected Proficiency (%)	Problem Analysis
CLR-4:	To choose the appropriate material and its application	Expected Attainment (%)	Design & Development
CLR-5:	To assess the extent of distress		Analysis, Design, Research
CLR-6:	To study strengthening and demolition of structural component		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1:	Diagnosis the distresses	3 85 75	H H - M - H - - - - - H - -
CLO-2:	Understand the performance of the concrete	3 85 75	H H - M - H - - - - - H - -
CLO-3:	Sources of dampness and its remedies can be able to identify	3 85 75	H H - M - H - - - - - H - -
CLO-4:	Know about types of materials and its selection	3 85 75	H H - M - H M - - - - - H - -
CLO-5:	Rectify the Distress in various structures	3 85 75	H H - M - H - - H - - - - H - -
CLO-6:	Strengthen and demolish the structural components	3 85 75	H H - M - H M M H - - - - H - -

Duration (hour)		9	9	9	9	9
S-1	SLO-1	General Consideration – Distresses monitoring, Causes of distresses	Sources of dampness	Materials: Types	Distresses : Concrete Structures: Introduction, Causes of deterioration	General principle for Strengthening
	SLO-2	Defects due to climate, wear and erosion	Moisture movement from ground	Essential parameters for Materials	Diagnosis of causes, Flow charts for diagnosis	Relieving loads
S-2	SLO-1	Quality assurance & Inspection	DPC	Special Mortar And Concretes, Concrete Chemicals	Methods of repair – repairing, spalling and disintegration	Strengthening super structures
	SLO-2	Structural & Economic appraisal	Reasons for ineffective DPC	Special Cements	Repairing of concrete floors and pavements	Plating
S-3	SLO-1	Life Expectancy of Different Types of Buildings	Roof leakage - Pitched roofs	High Grade Concrete	Steel Structures : Types and causes for deterioration	Conversation to composite construction
	SLO-2	Influence of Environmental Elements on Buildings	Madras Terrace roofs	Expansive Cement	Types and causes for deterioration – preventive measures	Post stressing
S-4	SLO-1	Design and Construction Errors	Leakage of Concrete slabs	Polymer Concrete	Repair procedure - Brittle fracture	Jacketing
	SLO-2	Corrosion Mechanism	Protective Seal coatings	Epoxies, Resins	Lamellar tearing	Bonded overlays
S-5	SLO-1	Effect of Biological Agents	Ferro cement overlay	Surface Coatings	Defects in welded joints	Reinforcement addition
	SLO-2	Termite Control and Prevention	Resin or polymer slurry injection	Parameters & types of coatings	Mechanism of corrosion	Fiber wrap techniques
S-6	SLO-1	Chemical Attack on Building	Thin polymer overlay	Sulphur Infiltrated Concrete	Design of protect against corrosion	Pre placed aggregate concrete
	SLO-2	Aspects of Fire on Buildings	Thin epoxy overlay	Properties and application of SIFCON	Design and fabrication errors	Shortcrete

S-7	SLO-1	Building Cracks Causes – diagnosis	Dampness in solid walls	Ferro cement	Distress during erection.	Strengthening concrete by surface impregnations
	SLO-2	Remedial measures	Condensation – hygroscopic salts	Application of Ferro cement	Masonry Structures: Discoloration and weakening of stones	Vacuum methods
S-8	SLO-1	Thermal cracks	Remedial treatments	Fiber Reinforced Concrete	Biological treatments	Strengthening the substructures: Shoring
	SLO-2	Shrinkage cracks	Dry pack & epoxy bonded dry pack	Types and applications	Preservation – Chemical preservatives	Under pinning
S-9	SLO-1	Vegetation and trees	Chemical coating	Admixtures	Brick masonry structures	Increasing the load capacity of footing
	SLO-2	Foundation movements	Flexible and rigid coatings	Chemical and Mineral admixtures	Distresses and remedial measures.	Design for rehabilitation.

Learning Resources	1. "Handbook on repair and rehabilitation of RCC buildings", CPWD, Government of India, Government of India Press, India, 2011	5. Dodge Woodson.R,"Concrete Structures – protection, repair and rehabilitation", Elsevier Butterworth – Heinmann, UK, 2009.
	2. Allen R.T and Edwards S.C, "Repair of Concrete Structures", Blakie and Sons, UK, 1987	6. Peter H.Emmons, "Concrete Repair and Maintenance Illustrated", Galgotia Publications Pvt. Ltd., 2001.
	3. Dayaratnam.P and Rao.R, "Maintenance and Durability of Concrete Structures", University Press, India, 1997.	7. Raikar, R.N., "Learning from failures - Deficiencies in Design, Construction and Service" – Rand D Centre (SDCPL), Raikar Bhavan, Bombay, 1987.
	4. Denison Campbell, Allen and Harold Roper, "Concrete Structures, Materials, Maintenance and Repair", Longman Scientific and Technical, UK, 1991.	8. https://onlinecourses-archive.nptel.ac.in/noc19_mm06/preview

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, and Conf. Paper etc.

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Er. A.G.V. Desigan, Design Group Engineering Consultancy Pvt Ltd., desigan.agv@gmail.com	Dr. B. Vidivelli, Annamalai University, vidivellibk@yahoo.com	Mr.A.Arokiaprakash, SRMIST
Mr. Rajesh, Planning manager, Uthra Constructions, uthraconstructions@gmail.com	Dr. E.B.Perumal Pillai, professor, Veltech University, ebpillai@yahoo.co.in	Mr.S.Manikandaprabhu, SRMIST

ACADEMIC CURRICULA

Professional Elective Courses

COMPUTER SCIENCE AND ENGINEERING

Regulations - 2018



SRM INSTITUTE OF SCIENCE AND TECHNOLOGY

(Deemed to be University u/s 3 of UGC Act, 1956)

Kattankulathur, Kancheepuram, Tamil Nadu, India

Course Code	18CSE351T	Course Name	COMPUTATIONAL LOGIC	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Course Learning Rationale (CLR):		The purpose of learning this course is to:		Learning			
CLR-1 :	Understand the basics of Propositional logic	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3
CLR-2 :	Acquire skills on rules to handle Propositional logic						
CLR-3 :	Understand the First order Logic and Meta theorems						
CLR-4 :	Learn the art of application of AI Concepts.						
CLR-5 :	Master various theorems on Logic						
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:					
CLO-1 :	Apply the skills acquired on propositional logic to solve examples at hand	2	80	85			
CLO-2 :	Apply the rules learnt towards problem solving	2	75	80			
CLO-3 :	Acquire mastery over FOL and Meta theorems and apply the same with confidence	2	85	80			
CLO-4 :	Apply the acquired knowledge on AI under appropriate problem solving contexts	2	80	75			
CLO-5 :	Attempt to apply the acquired knowledge on logics under appropriate problem solving contexts	2	75	85			

Program Learning Outcomes (PLO)														
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO – 3
H	-	-	-	-	-	-	-	-	-	-	-	-	-	-
H	H	-	-	-	-	-	-	-	-	-	-	-	-	-
H	M	-	-	-	-	-	-	-	-	-	-	-	-	-
H	H	H	-	-	-	-	-	-	-	-	-	-	-	-
H	M	H	-	-	-	-	-	M	-	-	H	-	-	-

	SLO-2	Equivalences and Consequences : Introduction to terminologies	Sub Formula	Translating into FL: Illustrations	Compactness of FL: Proof	Natural Deduction in K: Illustration
S-7	SLO-1	Equivalences and Consequences : Examples	Soundness of Propositional Logic	Satisfiability and Validity	Laws in FL	Analytic Tableau for K
	SLO-2	Deduction Theorem (DT)-Introduction	Soundness of Propositional Logic: Illustration	Satisfiability and Validity: Illustrations	Laws in FL: Illustration	Analytic Tableau for K: Illustration
S-8	SLO-1	RA Theorem, Monotonicity Theorem (M)- Introduction	Completeness of Propositional Logic	Metatheorems: Introduction	Natural Deduction	Modalities
	SLO-2	Fitness Theorem	Completeness of Propositional Logic: Illustration	Metatheorems: Deduction, Substitution, Chaining	Natural Deduction: Illustration	Modalities: Illustration
S-9	SLO-1	Theorem-Paradox of material Implication	Gentzen sequent calculus	Metatheorems: Examples	Analytic Tableaux	Computation Tree Logic
	SLO-2	Replacement Laws	Gentzen sequent calculus: Illustration	Metatheorems: Problems	Analytic Tableaux: Illustration	Computation Tree Logic: Illustration

Learning Resources	1. Arindama Singh, "Logics for Computer Science", PHI Learning Private Ltd, 2nd Edition, 2018	4. Dana Richards & Henry Hamburger, "Logic And Language Models For Computer Science", Third Edition, World Scientific Publishing Co. Pte. Ltd, 2018.
	2. Wasilewska & Anita, "Logics for computer science: classical and non-classical", Springer, 2018	
	3. Huth M and Ryan M, "Logic in Computer Science : Modeling and Reasoning about systems", Cambridge University Press, 2005	5. https://www.cs.cornell.edu/courses/cs3110/2012sp/lectures/lec15-logic-contd/lec15.html

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry		Experts from Higher Technical Institutions
Dr. Paventhan Arumugum, Director (R&D), ERNET India		Mr. T.Senthil Kumar, SRMIST
Mr Shiv Kumar Ganesh Full stack developer Altemetric, US		Dr.Kayalvizhi Jayavel, SRMIST
		Ms. Jeyasudha, SRMIST

Course Code	18CSE352T	Course Name	NEURO FUZZY AND GENETIC PROGRAMMING				Course Category	E	Professional Elective				L	T	P	C										
													3	0	0	3										
Pre-requisite Courses		Nil		Co-requisite Courses		Nil		Progressive Courses		Nil																
Course Offering Department		Computer Science and Engineering				Data Book / Codes/Standards		Nil																		
Course Learning Rationale (CLR):		The purpose of learning this course is to:						Learning			Program Learning Outcomes (PLO)															
CLR-1 :	Understand the fundamentals of Artificial Neural Networks						1	2	3	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3		
CLR-2 :	Learn the various topologies and learning algorithms of ANN						Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)																	
CLR-3 :	Understand the principles and fundamentals of Fuzzy Logic																									
CLR-4 :	Understand the Fuzzy Rule based systems																									
CLR-5 :	Understand the basic concepts and techniques of Genetic Algorithms																									
CLR-6 :	Utilize the Neural, Fuzzy and Genetic Algorithms for real-time application development																									
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:									L	H	-	H	L	-	-	-	L	L	-	H	-	-	-	-
CLO-1 :	Acquire the knowledge on constructing a neural network						3	80	75	M	H	M	M	H	-	-	-	M	L	-	H	-	-	-	-	-
CLO-2 :	Identify the basic Neural net and learning algorithm to apply for a real time problem						3	85	75	M	H	M	M	H	-	-	-	M	L	-	H	-	-	-	-	
CLO-3 :	Acquire the ability to use Fuzzy operators, membership functions, Fuzzification and Defuzzification Techniques						3	75	70	M	H	M	H	M	-	-	-	M	L	-	H	-	-	-	-	
CLO-4 :	Gain Knowledge on applying the Fuzzy rules to different applications						3	85	80	M	H	M	H	H	-	-	-	M	L	-	H	-	-	-	-	
CLO-5 :	Acquire the knowledge of fitness functions and Genetic operators						3	85	75	H	H	M	H	M	-	-	-	M	L	-	H	-	-	-	-	
CLO-6 :	Apply the Genetic Algorithm to real-time applications						3	80	70	M	H	M	H	H	-	-	-	L	L	-	H	-	-	-	-	
Duration (hour)		9		9		9		9		9		9														
S-1	SLO-1	Biological and Artificial Neuron	Delta Rule, Derivation of GDR	Crisp sets	Fuzzification of Input Variables, Application of Fuzzy operations		History of Evolutionary Computing, Genetic Algorithms, basic concepts																			
	SLO-2	History of ANN	Backpropagation Algorithm, Local Minima Problem	Fuzzy sets	GA Cycle , Fitness Function,		Introduction to GA Operators Selection Operators, Crossover, Mutation Operations																			
S-2	SLO-1	ANN architectures	Radial Basis Function Neural Network	Fuzzy membership functions	Evaluation of Fuzzy rules, Aggregation of output Fuzzy sets		Schema Theorem, Example																			
	SLO-2	Learning Algorithms	Pattern Association, Auto Associative nets	Operations of Fuzzy sets	Rule based systems, Conventional programs vs Rule based systems		Fuzzy Propositions																			
S-3	SLO-1	Activation Functions, Bias, Threshold and other parameters	Hetero Associative nets	Fuzzy Relations, Operations	Fuzzification		Classification of Genetic Algorithm																			
	SLO-2	McCulloch Pitts model,	Bidirectional Associative Memory Network	Fuzzy Extension Principle	Defuzzification		Holland Classifier Systems																			
S-4	SLO-1	Simulation of Logic Functions	Hopfield network Competitive networks: Maxnet	Crisp Relations, Fuzzy relations, Properties, operations,	Fuzzy Controller : Air conditioner control, Cruise Controller		Genetic Programming																			
S-5	SLO-1	Perceptron Network	Self Organizing Map Network	Propositional Logic	Fuzzy Decision making		Data Representation																			
	SLO-2	Hebbian network	Learning Vector Quantization	Crisp Logic	Fuzzy Truth, Fuzzy Rules		Genetic Operators																			
S-6	SLO-1	ADALINE networks	Adaptive Resonance Theory Network	Predicate Logic Rules of Inference	Introduction to neuro fuzzy system- Adaptive Neuro-Fuzzy Inference Systems Coactive Neuro-Fuzzy Modeling		Application of Genetic Algorithm																			
	SLO-2	MADALINE networks	Practice of Neural Network tool : Delta rule	Fuzzy Reasoning	Recent Applications		Practice of Optimization and Genetic algorithm tool																			
S-7,8	SLO-1	Practice of Neural Network tool : Simple Logic functions	Practice of Neural Network tool : Pattern Classification	Practice of Fuzzy Logic tool: Fuzzy functions	Practice of Fuzzy Logic tool : Fuzzy controller design and applications																					
	SLO-2	Practice of Neural Network tool : XOR problem	Practice of Neural Network tool : Pattern Clustering	Practice of Fuzzy Logic tool: Fuzzy operations																						
S-9	SLO-1	Practice of Neural Network tool : XOR problem	Practice of Neural Network tool : Pattern Clustering	Practice of Fuzzy Logic tool: Fuzzy operations																						
	SLO-2																									

Learning Resources	1. Samir Roy, Udit Chakraborty, "Introduction to Soft Computing: Neuro-Fuzzy and Genetic Algorithms", Pearson Education, 2013.	4. Timothy J. Ross, "Fuzzy Logic with Engineering Applications", John Wiley & Sons Ltd, 2010.
	2. Michael Negnevitsky. Artificial Intelligence: A Guide to Intelligent Systems, 3rd Edition, Pearson Education, 2011.	
	3. Laurene Fausett, "Fundamentals of Neural Networks, Architectures, Algorithms and Applications", Pearson Education, 2008.	5. David E. Goldberg, "Genetic Algorithms-In Search, optimization and Machine Learning", Pearson Education, 2008.

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. K. selvaraj, TCS, Bangalore	1. Dr. A.P. Shanthi, Professor, Dept. of Computer Science & Engineering, Anna University, chennai-600025	1. Dr. V. Ganapathy, SRM IST
2. Mr. Saju G Nair, IBM, Bangalore.	2. Dr. A. Kannan, Professor Dept. of Computer Science & Engineering, VIT, Vellore	2. Dr. D. Malathi, SRM IST
		3. Dr. Femi Ukrit, SRM IST

Course Code	18CSE353T	Course Name	DIGITAL IMAGE PROCESSING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:				Learning			Program Learning Outcomes (PLO)																	
CLR-1 :	provide deep understanding of basic concepts of digital image acquisition					1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15			
CLR-2 :	provide deep Understanding of various digital image enhancement techniques					Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3			
CLR-3 :	Understand image restoration and segmentation methods								H	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
CLR-4 :	provide understanding and implementation of image compression techniques								H	H	M	-	H	-	-	-	-	-	-	-	-	-	-	-	-	-
CLR-5 :	Provide understanding and knowledge of image recognition methods								H	H	M	-	H	-	-	-	-	-	-	-	-	-	-	-	-	-
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																								
CLO-1 :	Understand basics of digital images and tools for image processing					2	80	85	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-		
CLO-2 :	Learn and implement image Enhancement techniques					2	75	80	H	H	H	-	H	-	-	-	-	-	-	-	-	-	-	-		
CLO-3 :	Understand and Learn image Restoration and Segmentation Methods					2	85	80	H	H	M	-	H	-	-	-	-	-	-	-	-	-	-	-		
CLO-4 :	Understand and implement Image Compression techniques					2	80	75	H	H	M	-	H	-	-	-	-	-	-	-	-	-	-	-		
CLO-5 :	Learn and Implement Image Recognition methods					2	75	85	H	H	M	-	H	-	-	-	-	-	-	-	-	-	-	-		

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Introduction	Introduction to Spatial Domain	Noise models – Mean Filters – Order Statistics	Wavelets – Subband coding – Multiresolution expansions
S-2	SLO-1	Origin- Steps in Digital Image Processing	Gray level transformations	Adaptive filters – Band reject Filters – Band pass Filters	Fundamentals of Compression – Image Compression methods - Error Free Compression
S-3	SLO-1	Components	Histogram processing	Inverse Filtering – Wiener filtering Segmentation	Variable Length Coding – Bit-Plane Coding – Lossless Predictive Coding
S-4	SLO-1	Elements of Visual Perception	Basics of Spatial Filtering	Point, Line, and Edge Detection	Lossy Compression – Lossy Predictive Coding
S-5	SLO-1	Image Sensing and Acquisition	Smoothing and Sharpening Spatial Filtering	Marr-Hildreth & Canny edge detector	Compression Standards-Huffman, Arithmetic coding, LZW coding, Run Length Encoding
S-6	SLO-1	Image Sampling and Quantization	Frequency Domain: Basics of filtering	Edge Linking and Boundary detection	Compression StandardsHuffman, Arithmetic coding, LZW coding, Run Length Encoding
S-7	SLO-1	Relationships between pixels	Smoothing and Sharpening frequency domain filters	Local & Regional processing-Region based segmentation	Block Transform coding, Wavelet coding, JPEG standard
S-8	SLO-1	Introduction to Image processing toolbox in MATLAB	Smoothing and Sharpening frequency domain filters	Morphological processing- Watershed segmentation algorithm	MATLAB code for image compression: Huffam coding, Arithmetic coding, wavelet coding
S-9	SLO-1	Tool box practice	MATLAB code for histogram equalization	MATLAB code for restoring an image after degradation using adaptive and wiener filter	MATLAB code for image compression: Huffam coding,
	SLO-2	Exploring functions	MATLAB code for spatial and frequency domain filter.	Edge detection operators	Arithmetic coding, wavelet coding

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
<i>Madhan Thandayithapani kutiyappan, Assistant consultant, TCS - siruseri</i>	<i>Dr. S. Sridhar, Anna University</i>	<i>Dr. G.Niranjana. Associate Professor/CSE</i>
	<i>Dr. Senthil kumar, Annauniversity</i>	<i>Mr. Rajasekar Assistant Professor/IT Mr. James Joseph Assistant Professor/SWE</i>

Course Code	18CSE354T	Course Name	NETWORK SECURITY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	CSE	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1:	Understand the basic concepts of networking devices	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2:	Understand the concept of IP security		
CLR-3:	Understand the various methods and protocols to maintain E-mail security		
CLR-4:	Understand the various methods and protocols to maintain web security		
CLR-5:	Understand security measures for wireless and cell phone Communications		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Engineering Knowledge
CLO-1:	Acquire the knowledge of network devices used in data Communication	2	H
CLO-2:	Acquire the knowledge of IP security and ability to identify the IP security attack	2	H
CLO-3:	Acquire the knowledge of Email security and ability to detect the attacks in e-mail	2	H
CLO-4:	Acquire the knowledge of web security attack and prevention mechanism	2	H
CLO-5:	Acquire the knowledge of wireless network security and prevention mechanism	2	H

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Networking Devices(Layer1,2)	Overview of IPSEC- Security Associations, Security Association Database	Security Services for E-mail	SSL/TLS Basic Protocol
	SLO-2	Networking Devices(Layer 3)	Security Policy databases , AH and ESP	Security Services for E-mail	SSL/TLS Basic Protocol
S-2	SLO-1	Different types of network layer attacks	Tunnel and Transport mode	Establishing keys	computing the keys
	SLO-2	Different types of network layer attacks	IP header Protection	Establishing Public and secret keys	computing the keys
S-3	SLO-1	Firewall- ACL	IP and IPv6	Privacy	client authentication
	SLO-2	Packet Filtering	IPV4 and IPV6 header	End-to-end Privacy, Privacy with distribution List Exploders	client authentication
S-4	SLO-1	DMZ, Alerts	Authentication Header	Authentication of the source	PKI as deployed by SSL
	SLO-2	Audit Trails	Mutable, Immutable and Mutable but predictable	Based on public key technology and secret keys and with distribution list	PKI as deployed by SSL
S-5	SLO-1	IDS	Encapsulation Security Payload(ESP)	Message Integrity	SSLAttacks fixed in v3
	SLO-2	Advantages and Disadvantages of IDS(Need of IPS)	Internet Key Exchange	Non-repudiation	SSLAttacks fixed in v3
S-6	SLO-1	Advantages of IPS ove IDS	Phases of IKE	Introduction and Overview of PGP	Exportability
	SLO-2	IPS	Phase I IKE- Modes and key types	Efficient Encoding	Exportability
S-7	SLO-1	IPS Types- Signature based	Phase I IKE Protocols	Certificate and key revocation	Encoding
	SLO-2	Anomaly based, Policy based	Phase I IKE Protocols	Singature types, Private key, Fing types	Encrypted Record
S-8	SLO-1	IPS Types - Honeypot based	Phase II IKE	Anomalies	Handshake messages
	SLO-2	Applications	Phase II IKE	Object Format	Changechipherspec and Alerts
S-9	SLO-1	Malicious Software	ISAKMP/IKE Encoding	S/MIME	SET
	SLO-2	Malicious Software	ISAKMP/IKE Encoding	S/MIME	SET

Learning Resources	1. Charlie Kaufman, Radia Perlman, Mike Speciner, <i>Network Security</i> , Prentice Hall of India, 2002.	3. William Stallings, <i>Cryptography and Network Security - Principles and Practice</i> , 7th edition, Pearson Publication, 2017
	2. Bernard Menezes - <i>Network Security and Cryptography</i> - Cengage Learning. 2010.	
		4. <i>Cryptography and network security</i> , Atul Kahate/Tata McGraw-Hill Education, 2003

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. M. Sudhakar, M.Tech, (Ph.D)-IIT, IT Infrastructure Service, Tata Consultancy Services.	Dr. P. Yogesh, Associate Professor, Dept of Information Science and Technology, College of Engineering, Guindy,	Dr. A. Jeyasekar, Associate Professor Dr. J. Femilda, Associate Professor Mrs. G. Sujatha, Assistant Professor

Course Code	18CSE356T	Course Name	DISTRIBUTED OPERATING SYSTEMS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	To recognize the essential concepts of distributed system.	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	To comprehend about the communication that takes place in Distributed systems	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	To realize the necessity of synchronization, consistency and Fault tolerance in a Distributed System.	Expected Proficiency (%)	Problem Analysis
CLR-4 :	To value the Process management, File systems, Shared memory	Expected Attainment (%)	Design & Development
CLR-5 :	To acquire apparent scheme regarding distributed object-oriented based systems		Analysis, Design, Research
			Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Characterize the fundamental hardware and software concepts of distributed systems.	3 80 70	H M M H H M - - H M - H - - -
CLO-2 :	Categorize layered protocols and comprehend the communications in distributed systems	3 85 75	H M H M H M - - H M - H - - -
CLO-3 :	Implement synchronization of distributed systems using various algorithms.	3 75 70	H H H H H M - - H M - H - - -
CLO-4 :	Demonstrate process scheduling and fault tolerance of distributed systems.	3 85 80	H H H H H M - - H M - H - - -
CLO-5 :	Evaluate various Distributed Object-Oriented based systems.	3 85 75	H H H M H M - - H M - H - - -

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Introduction- Distributed Systems	Fundamentals of Communication systems	Synchronization in Distributed Systems-Fundamentals of Clock Synchronization	Processes and Processors in Distributed Operating Systems - Threads
	SLO-2	Goals of Distributed Systems		Logical clock, Physical clock	Design issues of Threads package
	SLO-2				Work Station Model
S-2	SLO-1	Hardware Concepts- Bus-based Multiprocessors	Layered Protocols	Algorithms for Clock synchronization	System Model - Introduction
S-3	SLO-1		ATM networks	Mutual Exclusion-Centralized Algorithm	Using Idle Work Stations
	SLO-2	Switched Multiprocessors			Numa Multiprocessors
S-4	SLO-1	Bus-based Multicomputers	Client Server model - Blocking Primitives	Distributed Algorithm	Processor Pool Model, Hybrid Model
	SLO-2		Non-Blocking Primitives	Token Ring Algorithm	Processor Allocation – Allocation Model
S-5	SLO-1	Switched Multicomputers	Buffered Primitives	Comparison of all three algorithms	Design issues for processor Allocation Algorithms
	SLO-2		Unbuffered Primitives	Importance of Election Algorithm	Example of processor Allocation Algorithms
S-6	SLO-1	Software Concepts-Network Operating System	Reliable primitives	Bully Algorithm	Scheduling in Distributed Systems
	SLO-2		Unreliable primitives	Ring Algorithm	Load Balancing and Sharing Approach
S-7	SLO-1	True Distributed Systems	Message passing and its related issues	Atomic Transaction- Introduction	Fault Tolerance-Component Faults
	SLO-2			Transaction Model, Concurrency Control	System Failures
S-8	SLO-1	Multiprocessors Timesharing Systems	Remote Procedure Call and its related issues	Deadlock in Distributed Systems	Synchronous versus Asynchronous Systems

	SLO-2			Distributed Deadlock Detection	Fault tolerance Using Active Replication, Primary-backup	Distributed Object-oriented Communication
S-9	SLO-1	Design Issues-Distributed Systems	Case Studies: SUN RPC, DEC RPC	Distributed Deadlock Prevention	Real Time Distributed Systems-Communication	Case Study - Amoeba
	SLO-2				Real Time Scheduling	Mach-OS, Chorus

Learning Resources	<p>1. Andrew S. Tanenbaum, "Distributed Operating Systems "Pearson Education, 2011.</p> <p>2. Pradeep K. Sinha "Distributed Operating Systems Concepts and Design "PHI 2012.</p> <p>3. Mukesh Singhal, Niranjana G Shrivastava "Advanced concepts in Operating Systems ", Mc Graw Hill International 2011.</p> <p>4. http://www.seas.gwu.edu/~jstanton/courses/cs251/</p> <p>5. http://cse.yeditepe.edu.tr/~sbaydere/courses_new/cse532/</p>
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		-	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
JP Vinjamoori, Director, Pavartha Software Pvt.Ltd, jp@pavarthasoftware.com	Dr. E. Sivasankar, NIT, Trichy	Mrs. S. Aruna, Dr.G. Maragatham, Mrs. A. Jackulin Mahriha, SRMIST

Course Code	18CSE357T	Course Name	BIOMETRICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer science	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1:	Understand the concept of authentication using biometrics.	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2:	Gain knowledge on the basics of biometric traits, sensors and data acquisition		
CLR-3:	Gain knowledge on design of biometric security systems		
CLR-4:	Acquire knowledge on pattern recognition systems		
CLR-5:	Introduce the various feature extraction and matching techniques for different biological traits.		
CLR-6:	Understand the real time application of biometrics		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Engineering Knowledge
CLO-1:	Acquire the knowledge on various biometric traits	1 80 85	H M H H - - H - - - - - - - - - - - - - - - -
CLO-2:	Acquire the ability to identify pattern recognition system and its features	1 75 80	H H H H - - H - - - - - - - - - - - - - - - -
CLO-3:	Understand the basic ideas about physical and behavioural biometric traits	1 85 80	H M M M - - M - - - - - - - - - - - - - - - -
CLO-4:	Apply the knowledge of biometrics on developing identification system.	2 80 75	H M M M M - H - H - - - - - - - - - - - - - - -
CLO-5:	Apply the knowledge for designing biometric systems	2 75 85	H H L - - - - - - - - - - - - - - - - - - - - - -
CLO-6:	Acquire the knowledge on authentication systems for real time security applications	1 80 85	- - - - - - - - - - - - - - - - - - - - - - - - - - -

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Introduction of biometric systems	Biometrics Sensors and Data Acquisition	Introduction to multi-biometrics	Biometric system authentication
	SLO-2	Biometric functionalities: verification, identification	Biometric data acquisition and database	Sources of multiple evidence	physiological and behavioral properties of biometric system,
S-2	SLO-1	The design cycle of biometric systems	Biometrics Pre-processing	Acquisition sequence	Software biometrics systems
	SLO-2	Building blocks of a generic biometric system	The related biometrics preprocessing technologies	Processing sequence	Hardware biometrics systems
S-3	SLO-1	Introduction to unimodal system	Image restoration	Fusion level	Security of biometric systems
	SLO-2	Introduction to Multimodal biometric system	Image segmentation	Sensor level fusion	Advisory, insider, infrastructure attacks
S-4	SLO-1	Biometric system errors	Pattern extraction and classification	Feature level fusion	Attacks at the user interface
	SLO-2	Performance measures	Pattern classification	Score level fusion	impersonation, obfuscation, spoofing
S-5	SLO-1	Image processing basics	Fingerprint Recognition and acquisition	Rank level fusion	Attacks on biometric processing
	SLO-2	what is image, acquisition, type, point operations, Geometric transformations	Fingerprint features, matching and synthesis	Decision level fusion	Attacks on system module and interconnections
S-6	SLO-1	First and second derivative	Face recognition and acquisition	Features Matching and Decision Making	Counter measure: Biometric template security
	SLO-2	steps in edge detection, smoothing, enhancement, thresholding, localization,	Face detection, feature extraction and matching	Feature matching: null and alternative hypothesis h_0 , h_1 , Error type I/II, Matching score distribution, FM/FNM, ROC curve, DET curve, FAR/FRR curve.	Countermeasure: spoof detection
S-7	SLO-1	Robert's method, Sobel's method, Perwitts	Iris recognition and acquisition	Introduction to Various matching methods:	Challenges in biometric systems like fool proofing, false positives

	SLO-2	Laplacian of Gaussian, Zero crossing	Iris Segmentation, normalization and matching	LDA	Developing Tools for Comparing fingerprints	audio-visual tracking
S-8	SLO-1	Low level feature extraction, Describing image motion	Ear recognition	PCA, Eigen vectors and values, 2D-PCA,	Enhancing pattern when data is minimum	stock market;
	SLO-2	High level feature extraction ,Template matching	Ear detection	generalization to p-dim, covariance and correlation, algebra of PCA, projection of data	Biometric failures in special cases like(too much moisture in hands which system can't read)	on-line shopping
S-9	SLO-1	Hough transform for lines	Hand geometry features	Introduction to decision theory and their examples	Mini project: Fingerprint, Face detection	compact embedded systems
	SLO-2	Hough transform for circles and ellipses	palmpoint features	Explanation – examples	Mini project: signature ,iris detection	other commercialized services

Learning Resources	<ol style="list-style-type: none"> 1. James wayman, Anil k.Jain ,Arun A.Ross ,Karthik Nandakumar, —Introduction to. BiometricsII, Springer, 2011 2. Mark S.Nixon, Alberto S.Aguado, Feature Extraction and image processing for computer vision, Third Edition, , Elsevier 2012 3. Digital Image Processing using MATLAB, By: Rafael C. Gonzalez, Richard Eugene Woods, 2nd Edition, Tata McGraw-Hill Education 2010 	<ol style="list-style-type: none"> 4. Guide to Biometrics, By: Ruud M. Bolle, Sharath Pankanti, Nalini K. Ratha, Andrew W. Senior, Jonathan H. Connell, Springer 2009 5. Pattern Classification, By: Richard O. Duda, David G.Stork, Peter E. Hart, Wiley 2007 6. Shimon K.Modi , —Biometrics in Identity Management :concepts to applicationsII, Artech House 2011
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
<ol style="list-style-type: none"> 1. Raghuraghavendra s, Chief Executive Officer at Forensic & Biometric Investigation Services FBIS Chennai, Tamil Nadu, India Chennai Area, India 	<ol style="list-style-type: none"> 1. Dr. J.Dhalia Sweetlin Designation:Assistant Professor [Sr Grade] Madras Institute of Technology, MIT Road, Radha Nagar,Chromepet, Chennai,Tamil Nadu 600044, India.Email:jdsweetlin@mitindia.edu Area of Specialization: Image Processing, Soft Computing 	<ol style="list-style-type: none"> 1. Dr. C. Malathy, SRMIST
		<ol style="list-style-type: none"> 2. M.Gayathri, SRMIST 3.Ms.Meenakshi/IT Dept,SRMIST

Course Code	18CSE358T	Course Name	PATTERN RECOGNITION TECHNIQUES	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	CSE	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1:	Understand the fundamentals of Pattern Recognition techniques	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Learn Statistical models of Pattern Recognition	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3:	Understand the principles of Clustering approaches to Pattern Recognition				-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLR-4:	Understand the Syntactic Pattern Recognition techniques				H	H	-	-	H	-	-	-	-	-	-	-	-	-	-
CLR-5:	Understand the Neural Network approach to Pattern Recognition				-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
					-	H	-	-	H	-	-	-	-	-	-	-	-	-	-
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1:	Acquire the knowledge on various biometric traits	2	80	85															
CLO-2:	Acquire the ability to identify pattern recognition system and its features	2	75	80															
CLO-3:	Understand the basic ideas about physical and behavioural biometric traits	2	85	80															
CLO-4:	Apply the knowledge of biometrics on developing identification system.	2	80	75															
CLO-5:	Apply the knowledge for designing biometric systems																		

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Pattern and features	Introduction to StatPR, Statistical models,	Formulation of unsupervised problems	Syntactic Pattern Recognition, Grammar based approaches,	Neural Networks fundamentals, Learning in Neural networks,
	SLO-2 Classification, Description, Pattern Mappings	Gaussian case and Class Dependence	Illustration	Formal Grammars, Types of Grammars	Physical Neural Networks
S-2	SLO-1 Patterns and Feature Extraction	Discriminant Functions- Uniform Densities	Unsupervised Learning Approaches	String generation as Pattern Description	Artificial Neural Networks model,
	SLO-2 Examples	Classifier Performance, Risk and Errors	Illustration	Example	activation functions, weights
S-3	SLO-1 Classifiers	Supervised learning – Parametric estimation	Clustering for unsupervised learning and classification	Recognition by String Matching and Parsing,	Neural Network based Pattern Associators, CAM
	SLO-2 Example	Maximum Likelihood Estimation	Example	Example	Linear Associative Mappings, Different approaches
S-4	SLO-1 Decision Regions	Bayesian parameter estimation	c-means algorithm	Cocke-Younger-Kasami Parsing Algorithm	Heteroassociative memory design
	SLO-2 Boundaries	Example	Illustration	Illustration	Examples
S-5	SLO-1 Training in pattern recognition systems	Nonparametric approaches-	Learning Vector Quantization,	Augmented Transition Networks, High Dimensional Grammars,	Hebbian learning
	SLO-2 Learning in pattern recognition systems	Density estimation	Example	Example	Example
S-6	SLO-1 Pattern recognition approaches	Parzen Windows	Formal Characterization of General Clustering Procedures	Stochastic Grammars and applications	Feedforward Network Architecture, Training in Feedforward networks,
	SLO-2 Statistical pattern recognition, Example	k-nn Nonparametric estimation	Explanation on procedure	Example	Explanation
S-7	SLO-1 Syntactic pattern recognition	Nearest Neighbor Rule	Clustering Strategies	Graph based structural representations	GDR, Derivation of Delta Rule
	SLO-2 Examples	Example	Different scenarios	Graph Isomorphism	Explanation
S-8	SLO-1 Neural pattern recognition	Linear Discriminant Functions, Fisher's Linear Discriminant	Cluster Swapping Approaches	Attributed Graphs, Match Graphs,	Backpropagation Algorithm,
	SLO-2 Comparison	Discrete and Binary Classification problems	Examples	Examples	Explanation
S-9	SLO-1 Black Box approaches	Techniques to directly obtain Linear Classifiers	Hierarchical clustering procedure	Cliques, Structural Unification using attributed graphs	Pattern Associator for Character Classification
	SLO-2 Reasoning driven pattern recognition	Illustration	Example	Examples	Example

Learning Resources	1. Robert J. Schalkoff, "Pattern Recognition: Statistical, Structural and Neural Approaches", John Wiley & Sons Inc., New York, Reprint 2014. 2. Earl Gose, Richard Johnsonbaugh, Steve Jost, "Pattern Recognition and Image Analysis", Prentice Hall of India Private Ltd., New Delhi – 110 001, 1999. 3. Duda R.O. and Hart P.E., "Pattern Classification and Scene Analysis", Wiley, New York, 1973
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50%)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. Deepan Raj, Visteon, Chennai	Dr. T. Nagarajan, Professor and Head, Dept. of IT, SSN college of Engineering.	1. Dr. M. Thenmozhi, SRMIST
		2. Dr. S. Prabhakaran, SRMIST
		3. Dr. Alice Nithya, SRMIST

Course Code	18CSE359T	Course Name	NATURAL LANGUAGE PROCESSING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	CSE	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Teach students the leading trends and systems in natural language processing.	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Make them understand the concepts of morphology, syntax, semantics and pragmatics of the language and that they are able to give the appropriate examples that will illustrate the above mentioned concepts.	Level of Thinking (Bloom) Expected Proficiency (%) Expected Attainment (%)	Engineering Knowledge Problem Analysis Design & Development Analysis, Design, Research Modern Tool Usage Society & Culture Environment & Sustainability Ethics Individual & Team Work Communication Project Mgt. & Finance Life Long Learning PSO - 1 PSO - 2 PSO - 3
CLR-3 :	Teach them to recognize the significance of pragmatics for natural language understanding.		
CLR-4 :	Enable students to be capable to describe the application based on natural language processing and to show the points of syntactic, semantic and pragmatic processing.		
CLR-5 :	To conceive basics of knowledge representation, inference, and relations to the artificial intelligence.		
CLR-6 :	To understand natural language processing and to learn how to apply basic algorithms in this field		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Understand approaches to syntax and semantics in NLP.	2 80 85	H H H H H - - - H M M H H H H
CLO-2 :	Understand approaches to discourse, generation, dialogue and summarization within NLP.	2 75 80	H H H H H - - - H M M H H H H
CLO-3 :	Understand current methods for statistical approaches to machine translation.	2 85 80	H L M H H - - - H M M H H H H
CLO-4 :	Understand machine learning techniques used in NLP, including the probabilistic context-free grammars and unsupervised methods, as applied within NLP	2 80 75	H H H H H - - - H M M H H H H
CLO-5 :	Understand the knowledge of various levels of analysis involved in NLP	2 75 85	H H H H H - - - H M M H H H H
CLO-6 :	Gain knowledge in automated Natural Language Generation and Machine Translation		

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Introduction to Natural Language Processing	Syntax Parsing	Semantic Relations	Information Extraction and its approaches	Introduction to Probabilistic Approaches
	SLO-2 Steps – Morphology – Syntax – Semantics	Dependency Parsing	Semantic Role Labeling		Statistical Approaches to NLP Tasks
S-2	SLO-1 Morphological Analysis (Morphological Parsing)	Semantics	Semantic Frames	Information Retrieval	Sequence Labeling
	SLO-2 Stemming – Lemmatization	Semantic Parsing	Ontology and Semantics		
S-3	SLO-1 Parts of Speech Tagging	Word Sense Disambiguation	Semantic Network and Knowledge Graph	Semantic Search	Problems - Similarity Measures
	SLO-2 Approaches on NLP Tasks (Rule-based, Statistical, Machine Learning)	Lexical Disambiguation	Intent Detection and Classification	Summarization Extractive Vs Abstractive, Summarization	Word Embeddings
S-5	SLO-1 N-grams	Structural Disambiguation	Paraphrase Extraction	Information Fusion	CBOW
	SLO-2 Multiword Expressions	Word, Context and Sentence-level Semantics	Discourse Coreference Resolution	Single and Multi-document Summarization – Question Answering	Skip-gram
S-7	SLO-1 Collocations (Association Measures, Coefficients and Context Measures)	Pronoun Resolution	Text Coherence	Introduction to Chatbot Applications	Sentence Embeddings
	SLO-2 Vector Representation of Words	Semantic Representation of text	DiscourseStructure	Retrieval based- Conversation based	
S-8			Coherence	NLU and NLG	Recurrent Neural Networks (RNN)
S-9	SLO-1 Language Modeling	Introduction to Semantic Relations	Discourse Planning	Machine Translation	Long Short-Term Memory (LSTM)

Learning Resources	1. Daniel Jurafsky and James H. Martin, "Speech and Language Processing: An introduction to Natural Language Processing, Computational Linguistics and Speech Recognition", Prentice Hall, 2nd Edition, 2018.	3. James Allen, Benjamin Cummings, "Natural Language Understanding", 2nd edition, 1995
	2. C. Manning and H. Schütze, "Foundations of Statistical Natural Language Processing", MIT Press. Cambridge, MA., 1999	4. Yoav Goldberg, Neural Network Methods for Natural Language Processing.
		5. http://mccormickml.com/2106/04/19/word2vec-tutorial-the-skip-gram-model/
		6. https://nlp.stanford.edu/pubs/glove.pdf

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. J. Balaji, Associate Manager, Allstate Solutions Pvt Ltd, jagank.balaji@gmail.com	1. Dr. G. Nagappan, Professor, nagappan@saveetha.ac.in	1. Dr. M. Ferni Ukrit, SRMIST
		2. Dr. A. Pandian, SRMIST
		3. Ms. K. Meenakshi, SRMIST

Course Code	18CSE360T	Course Name	INFORMATION STORAGE AND MANAGEMENT	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:					Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Understand the components of storage infrastructure.						Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Gain knowledge to evaluate storage architectures including storagesubsystems																									
CLR-3 :	Understand the business continuity, backup and recovery methods.																									
CLR-4 :	Acquire knowledge on information security framework																									
CLR-5 :	Introduce the working principle of storage infrastructure with monitoring principles																									
CLR-6 :	Understand the structure of cloud computing and its techniques																									
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																								
CLO-1 :	Acquire the knowledge on the components of storage infrastructure						3	80	70	M	-	-	-	-	-	-	-	-	L	-	-	M	-	-	-	
CLO-2 :	Acquire the ability to evaluate storage architectures including storagesubsystems						3	85	75	M	M	M	M	-	-	-	-	-	L	-	-	H	-	-	-	
CLO-3 :	Understand the business continuity, backup and recovery methods.						3	75	70	M	M	M	M	-	-	-	-	-	L	-	-	H	-	-	-	
CLO-4 :	Appreciate the concepts of storage security and information security applied to virtual machine						3	85	80	M	M	L	L	-	-	-	-	-	M	-	-	H	-	-	-	
CLO-5 :	Apply the knowledge for storage infrastructure						3	85	75	L	M	-	-	-	-	-	-	-	M	-	-	H	-	-	-	
CLO-6 :	Acquire the knowledge on structure of cloud computing and its techniques						3	80	70	M	-	-	-	-	-	-	-	-	L	-	-	H	-	-	-	

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Introduction to Information Storage Management	Virtualization and Cloud Computing : Fiber Channel: Overview	Business Continuity And Back Up Recovery Business Continuity: Information Availability.	Storage Security And Management :
	SLO-2	Evolution of Storage Architecture	SAN and its Evolution	BC Terminology, BC Planning life cycle	Information Security Framework
S-2	SLO-1	Data Centre Infrastructure	Components of FC SAN, FCoE Connectivity, FC Architecture	Failure Analysis, Business Impact Analysis	Risk Triad
	SLO-2	Virtualization and Cloud Computing	IPSAN-iSCSI components	BC Technology Solutions	Storage Security Domains
S-3	SLO-1	Key challenges in managing information.	iSCSI Protocol Stack iSCSI Names	Backup and Archive: Backup Purpose	Security Implementations in Storage Networking
	SLO-2	Data Center Environment: Application	NAS: General Purpose Servers versus NAS Devices	Backup Considerations	Securing Storage Infrastructure in Virtualized and Cloud Environments
S-4-5	SLO-1	Database Management System (DBMS)	Benefits of NAS- File Systems and Network File Sharing	Backup Granularity , Recovery considerations	RSA and VMware Security Products
	SLO-2	Host : Connectivity, Storage	Components of NAS	Backup Methods, Backup Architecture	Monitoring the Storage Infrastructure
S-6	SLO-1	Disk Drive Components, Disk Drive Performance	NAS I/O Operation	Backup and Restore Operations	Monitoring Parameters,
	SLO-2	Intelligent Storage System	NAS Implementations	Backup Topologies	Components Monitored, Monitoring examples
S-7	SLO-1	Components of an Intelligent Storage System	NAS File Sharing Protocols	Backup in NAS Environments	Storage Infrastructure Management Activities
	SLO-2	Storage Provisioning	Object Based Storage Devices	Backup Targets, Data Deduplication for Backup	Storage Infrastructure Management Challenges, Storage Management Examples
S-8	SLO-1	Types of Intelligent Storage Systems	Content Addressed Storage	Backup in Virtualized Environments	Storage Allocation to a New Server/Host,
	SLO-2	Creation of Virtual storage machine, Navigation of storage system .	Configuration and Tracing of FC scan and iSCSI scan	Sharing Files between host and Virtual Machines, Usage of Backup techniques	Creation of an Linux Instance in Public Cloud, Generate a private key, Access using SSH client
S-9	SLO-1				
	SLO-2				

Learning Resources	1. EMC Corporation, "Information Storage and Management", 2nd edition Wiley India, ISBN13: 978-1118094839 2. Thomas Erl, "Cloud Computing: Concepts, Technology & Architecture", Prentice Hall, 2013, ISBN: 9780133387568	3. UlfTroppen Rainer Wolfgang Muller, "Storage Networks Explained", India, Wiley, 2010, ISBN13: 978-0470741436
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100%	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers			
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts	
	Dr.V.Masillamani	1. Dr.B.Amutha SRMIST	
		2. Dr.A.Shanthini, SRMIST	

Course Code	18CSE451T	Course Name	WIRELESS SENSOR NETWORKS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	CSE	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)															
CLR-1 :	Understand basic sensor network concepts				Level of Thinking (Bloom)	2	80	85	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Know physical layer issues, Medium Access Control Protocols								Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Comprehend network and transport layer characteristics and protocols								H	H	H	H	M	M	M	M	M	H	L	H	H	H	H
CLR-4 :	Understand the network management and Middleware services								H	H	H	H	M	M	M	M	M	H	L	H	H	H	H
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:							H	H	H	H	M	M	M	M	M	H	L	H	H	H	H
CLO-1 :	Understand the basic ideas about sensor network concepts with Applications and Apply the knowledge for WSN tools				2	80	85	H	H	H	H	M	M	M	M	M	H	L	H	H	H	H	
CLO-2 :	Acquire the knowledge on wireless transmission technology ,hardware and Medium Access Protocols				2	75	80	H	H	H	H	M	M	M	M	M	H	L	H	H	H	H	
CLO-3 :	Understand the basic ideas about Wireless Sensor Networks Routing protocols and network - transport layer characteristics				2	85	80	H	H	H	H	M	M	M	M	M	H	L	H	H	H	H	
CLO-4 :	Apply the knowledge for network management and Middleware services				2	80	75	H	H	H	H	M	M	M	M	M	H	L	H	H	H	H	

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction to computer and wireless sensor networks	Wireless Transmission Technology and systems	Overview-Wireless Mac Protocols	Design Issues in WSN routing- Data Dissemination and Gathering	WSN middleware principles-
	SLO-2				Routing Challenges in WSN	
S-2	SLO-1	Motivation for a network of Wireless Sensor nodes -	Radio Technology Primer	Characteristics of MAC protocols in Sensor networks	Flooding	Middleware architecture
	SLO-2	Sensing and sensors	Available Wireless Technologies			Data related functions, Architecture
S-3	SLO-1	Challenges and constraints	Hardware- Telosb	Contention free MAC Protocols	Flat Based Routing – SAR	Existing middleware
	SLO-2				Directed Diffusion	MILAN, IrisNet
S-4	SLO-1	Node architecture	Hardware -Micaz motes	MAC Protocols -Characteristics	MCFA Coherent processing	AMF,DSWare
	SLO-2	Sensing sub system		Traffic Adaptive Medium Access	Non-Coherent Processing	CLMF
S-5	SLO-1	Processor sub system	Time Synchronization- Clock	Y-MAC	Hierarchical Routing- LEACH,TEEN,	Operating systems for wireless sensor networks
	SLO-2	Communication interfaces-- prototypes		Low energy Adaptive Clustering	APTEEN,PEGASIS	
S-6	SLO-1	Application of Wireless sensors	Synchronization Problems	Contention based MAC Protocols	Query Based Routing	Performance and traffic management
	SLO-2				Negotiation Based Routing	
S-7	SLO-1	WSN Tools- Overview and Limitations	Basics of time synchronization	Sensor MAC	Geographical Based Routing	Fundamentals of network security
	SLO-2		Time synchronization protocols	Timeout MAC and pattern MAC		
S-8	SLO-1	Contiki -Introduction	Localization	MAC protocols in ContikiOS simulator	Routing protocol simulation in contiki	Network security Challenges
	SLO-2		Ranging Techniques	Nullmac in Contiki simulator	RPL objective function &simulation using DGRM model cooja	
S-9	SLO-1	Characteristics of Contiki WSN simulator	Range based Localization Range Free Localization	CSMA in Contiki simulator	RPL(Routing Protocol for Low-Power and Lossy Networks) Border Router simulation in Contiki 2.7 OS	Attacks Protocols mechanisms for security
	SLO-2		Event driven Localization			

Learning Resources	<ol style="list-style-type: none"> 1. Kazem Sohraby, Daniel manoli, "Wireless Sensor networks- Technology, Protocols and Applications", Wiley InterScience Publications 2013. 2. Waltenegus Dargie, Christian Poellabauer, "Fundamentals of Wireless Sensor Networks, Theory and Practice", Wiley Series on wireless Communication and Mobile Computing, 2011 3. S.Swapna Kumar, "A Guide to Wireless Sensor Networks". kindle Edition, USP publications, 2017 4. C.S Raghavendra, Krishna M.Sivalingam, Taieb znati, "Wireless Sensor Networks", Springer Science 2010. 	<ol style="list-style-type: none"> 5. Bhaskar Krishnamachari, " Networking Wireless Sensors", Cambridge University Press, 2005 6. https://www.amazon.in/Guide-Wireless-Sensor-Networks-ebook/dp/B072R53JJM 7. https://anrg.usc.edu/contiki/index.php/Contiki_tutorials 8. file:///C:/Users/Administrator.RD27/Downloads/Fundamentals-of-Wireless-Sensor-Networks-Waltenegus-Dargie.pdf
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1.Mr.Anirban Chowdhry, Director, Frugal Labs	1. Dr. P.T.V. Bhuvaneshwari, Professor, MIT campus, Anna University	1. Dr. Revathi Venkatraman, SRMIST 2. Dr.N.Snehalatha, SRMIST 3. Dr.MB.Mukesh krishnan, SRMIST

Course Code	18CSE452T	Course Name	NETWORK PROTOCOLS AND PROGRAMMING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	CSE	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1:	Describe the importance of various Internet protocols like ARP, RARP, ICMP, Multicasting and multi routing, SCTP	1	1
CLR-2:	Understand the transport layer protocols, application layer protocol and its characteristics	2	2
CLR-3:	Learn and Understand IPV6 technologies	3	3
CLR-4:	Work with client server sockets and develop related applications to communicate with each other.		4
CLR-5:	Understand the wide area network protocols		5
CLR-6:	Learn the basics of MPLS protocol		6

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1:	Identify the basics of different types of network and transport layer protocols	2	80	85	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-2:	Design and implement the socket programming	2	75	80	H	H	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-3:	Enumerate the types of application layer protocols	2	85	80	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-4:	Analyze and compare the IPv4 and IPv6 protocols	2	80	75	H	H	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-5:	Familiarize with wide area technologies	2	75	85	H	-	-	H	-	-	-	-	-	-	-	-	-	-	-
CLO-6:	Describe the working of MPLS protocol	2	80	85	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-

Duration (hour)	9	9	9	9	9
S-1	SLO-1 IP header	Byte ordering	DNS	IPV6 Overview	DSL
	SLO-2 IP fragmentation	Byte ordering conversion functions	DNS in the Internet,	IPV6 Features	Other DSL Technology
S-2	SLO-1 ARP	System calls	DNS Resolution	IPV6 Addressing Modes	DSL Benefits
	SLO-2 RARP	Sockets	DNS Messages	IPV6 Address Types	Cable Technology
S-3	SLO-1 ICMP -introduction	System calls used with Sockets	TELNET	Introduction	Compare DSL Vs Cable
	SLO-2 ICMP-Messages	Iterative and concurrent server	SSH	Address Space Allocation	Frame Relay
S-4	SLO-1 Debugging tools	Socket Interface	FTP	Global Unicast Addresses	ATM Introduction
	SLO-2 ICMP package	Structure and Functions of Socket	TFTP	Autoconfiguration	ATM Cell Format
S-5	SLO-1 UDP Datagram	Remote Procedure Call	WWW Architecture	Renumbering	ATM Layer
	SLO-2 UDP characteristics	RPC Model, Features	WWW Documents	IPV6 Routing Protocols	AAL Layer
S-6	SLO-1 TCP Header	TCP Client Server Program	HTTP	Introduction	ATM Application
	SLO-2 TCP connection establishment process	Input, Output Processing Module	HTTP Request and Reply	IPV6 Packet Format	PPP
S-7	SLO-1 TCP Error Control	UDP Client Server Program	DHCP Operation	Comparison between IPV4 and IPV6 Header	PPP Services, Components
	SLO-2 TCP Congestion Control	UDP Control block table & Module	DHCP Configuration	IPV4 to IPV6 Tunneling	PPP frame and byte stuffing
S-8	SLO-1 TCP Flow Control	UDP Input & Output Module	SMTP	IPV4 to IPV6 Translation Techniques	HDLC
	SLO-2 Multicasting	SCTP Sockets	POP3	NAT Protocol Translation	HDLC Transfer Modes, Frame
S-9	SLO-1 Multicasting and Multicast Routing Protocol	SCTP Services and Features, Packet Format	IMAP	IPV6 Mobility	Types of HDLC Frame
	SLO-2 Stream Control Transmission Protocol	SCTP Client/Server	MIME	Protocols Changed to Support IPV6	MPLS

Learning Resources	1. Behrouz A. Forouzan, "TCP/IP Protocol Suite" 4 th edition, 2013, McGraw-Hill ISBN: 0073376043 2. Douglas E. Comer, "Internetworking with TCP/IP, Principles, protocols, and architecture, Vol 15th Edition, 2006 ISBN: 0131876716, ISBN: 978-0131876712"	3. Richard Stevens, "Unix Network Programming, vol. 1, 3rd edition, 2003, McGraw-Hill ISBN 0-07-246060-1"
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50%)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Thamaraiselvam, zoho, thamaraiselvam.s@zohocorp.com	1. Dr. Ema, Anna University Chennai, umaramesh@auist.net	1. Dr. G. Usha, SRMIST, Dr. J. Kalaivani, SRMIST
2. Mr. Mithun, Cognizant, Mithun.SS@cognizant.com	2. Dr. Kunvar Singh, NITT Trichy, kunwar@nitt.edu	2. Mr. J. Godwin Pon, SRMIST

Course Code	18CSE453T	Course Name	NETWORK ROUTING ALGORITHMS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18CSC302J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand how addressing and routing are tied together and different architectural components are related to routing.	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Gain knowledge on the need for routers, its functionality and different architectures.	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Understand fundamental basis of various algorithms in centralized and distributed point of view.																		
CLR-4 :	Apply the knowledge of IP addressing in various routing algorithms.																		
CLR-5 :	Understand the various types of key routing protocols used in wireless networks.																		
CLR-6 :	Gain knowledge on past experiences and prepare for next generation networks and routing																		

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Acquire the knowledge of how data transfer happens in conventional networks	2	80	85	H	M	-	-	L	-	-	-	-	M	-	H	-	-	-
CLO-2 :	Comprehend Router Architectures and IP Address Lookup Algorithms	2	75	80	H	H	M	M	L	-	-	-	-	-	L	H	-	-	-
CLO-3 :	Compare routing techniques and protocols	2	85	80	H	H	L	M	M	-	-	-	M	-	L	H	-	-	-
CLO-4 :	Examine how different dimensions of routing differ for different types of network	2	80	75	H	H	H	H	H	L	-	M	M	-	-	H	-	-	-
CLO-5 :	Apply various routing algorithms in wireless network scenario.	2	75	85	H	H	H	H	M	-	-	-	M	-	-	H	-	-	-
CLO-6 :	Understand various routing paradigms in next generation	2	80	85	H	H	H	M	M	L	-	-	-	-	-	H	-	-	-

Duration (hour)	8	9	9	9	10
S-1	SLO-1	Network Routing: An Introduction to Routing algorithms	Router Architectures: Basic Forwarding Functions	Bellman-Ford algorithm	Routers, Networks, and Routing Information: Some Basics
	SLO-2	Functions of Router	Routing table versus forwarding table	Distance Vector Approach	Routing Table, Communication of Routing Information
S-2	SLO-1	IP addressing- Classful Addressing	Types of router	Dijkstra's Algorithm	Routing Information Protocol, Version 1 (RIPv1)
	SLO-2	Classless Addressing	Elements of Router	Comparison of Bellman-Ford and Distance Vector Approach	Routing Information Protocol, Version 2 (RIPv2)
S-3	SLO-1	Protocol architecture stack – OSI Reference Model	Packet Flow	Shortest Path Computation with Candidate Path Caching	Interior Gateway Routing Protocol (IGRP)
	SLO-2	IP Protocol Stack Architecture	Packet Processing	Widest Path Computation with Candidate Path Caching	Enhanced Interior Gateway Routing Protocol (EIGRP), Route Redistribution
S-4	SLO-1	Network Topology Architecture	Shared CPU architecture, Shared forwarding Engine Architecture	Widest Path Algorithm	OSPF: Protocol Features
	SLO-2	Network Management Architecture	Shared Nothing Architectures, Clustered Architectures	k-Shortest Paths Algorithm	OSPF Packet Format
S-5	SLO-1	Public Switched Telephone Network	Impact of Addressing on lookup	Routing Protocol, Routing Algorithm, and Routing Table	Integrated IS-IS
			Longest Prefix Matching	Routing Information Representation and Protocol Messages	Similarities and Differences Between IS-IS and OSPF
S-6	SLO-1	Communication Technologies	Naïve Algorithms, Binary Tries	Distance Vector Routing Protocol	IP Traffic Engineering: Traffic, Stochasticity, Delay, and
					Hierarchical Routing Protocols

					Utilization	
					Applications' View	Power-Aware Routing Protocols
S-7	SLO-1	Standard Committees – International TeleCommunication Union	Multi-bit Tries	Link State Routing Protocol	Traffic Engineering: An Architectural Framework	Toward Next Generation Routing: Quality of Service Routing
	SLO-2	Internet Engineering Task Force, MFA Forum	Compressing multi-bit strides		Traffic Engineering: A Four-Node Illustration	
S-8	SLO-1	Type Length Value	Search By Length Algorithms	Path Vector Routing Protocol	BGP Operations, configuration, faces of BGP	Multiprotocol Label Switching(MPLS)
	SLO-2	Network Protocol Analyzer	Search By value approaches		BGP Decision Process	Generalized MPLS
S-9	SLO-1		Hardware Algorithms	Network Flow Modeling: Single-Commodity Network Flow	Internal BGP Scalability	Routing and Traffic Engineering with MPLS
	SLO-2		Comparing Different Approaches	Multicommodity Network Flow: Three-Node Example	Protocol Message Format	
S-10	SLO-1					PSTN Call Routing Using the Internet
	SLO-2					

Learning Resources	<ol style="list-style-type: none"> 1. D.Medhi and K.Ramasamy, Network Routing: Algorithms, Protocols and Architectures, MorganKaufmann Publishers, First Edition 2007. 2. C.Siva Ram Murthy and B.S.Manoj, Adhoc Wireless Networks, Pearson Education, 2007. 3. D.Medhi and K.Ramasamy, Network Routing: Algorithms, Protocols and Architectures, Morgan Kaufmann Publishers, Second Edition 2017. 	<ol style="list-style-type: none"> 4. SteenStrubM, Routing in Communication networks, Prentice Hall International, 1995. 5. Internetworking Technologies Handbook, Inc. Cisco Systems, ILSG Cisco
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50%)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr.T.Bernald , Senior Consulatant , TCS Chennai. bernald.t@tcs.com	Dr. S.Anbuchelian, Anna University. anbuchelian@annauniv.edu	1. Dr.FemildaJosephin J S,SRMIST
		2. Mr.RajeshBabu,SRMIST
		3. Mr. J.Godwin,SRMIST

Course Code	18CSE454T	Course Name	HIGH PERFORMANCE COMPUTING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	To learn about Modern Processors and concepts	1	1
CLR-2 :	To understand the basic concepts of optimizations	2	2
CLR-3 :	To learn about Parallel Computers and programming	3	3
CLR-4 :	To understand the basic concepts of parallelization	4	4
CLR-5 :	To Study about Memory Parallel Programming using OpenMP	5	5
CLR-6 :	To Study about Memory Parallel Programming using and MPI	6	6

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Acquire the knowledge of Modern processors and concepts	2	80	85	H	H	-	-	-	-	-	-	-	H	-	-	-	-	-
CLO-2 :	Understand the basic ideas about Optimizations	2	75	80	-	H	-	-	-	-	-	-	-	-	-	-	-	-	H
CLO-3 :	Acquire the ability to identify parallel computers	2	85	80	-	-	H	-	-	-	-	M	-	-	L	-	-	-	-
CLO-4 :	Appreciate the concepts of parallelization	2	80	75	-	H	-	-	H	-	-	-	H	-	-	H	-	-	-
CLO-5 :	Apply the knowledge on parallel programming using Open MP	2	75	85	-	-	-	H	-	L	-	-	-	-	-	-	-	-	-
CLO-6 :	Acquire the knowledge on parallel programming using MPI	2	80	85	-	-	-	-	-	-	-	-	-	-	-	H	H	-	-

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Stored Program Computer Architecture	Scalar profiling- Function- and line-based runtime profiling	Taxonomy of parallel computing paradigms	Introduction to OpenMP
	SLO-2	General-ptupose cache-based microprocessor architecture	Hardware performance counters .	Shared-memory computers	Parallel execution
S-2	SLO-1	Performance based metrics and Benchmarks	Manual instrumentation	Cache coherence	Data scoping
	SLO-2	Transistors galore:	Common sense optimizations- Do less work!	UMA – ccNUMA	OpenMP worksharing for loops
S-3	SLO-1	Moore's Law	Avoid expensive operations!	Distributed-memory computers	Synchronization
	SLO-2	Pipelining	Shrink the working set!	Hierarchical (hybrid) systems	Reductions
S-4	SLO-1	Superscalarity	Simple measures, large impact- Elimination of common subexpressions	Networks- Basic performance characteristics of networks	Loop scheduling, Tasking
	SLO-2	SIMD	Avoiding branches	Buses, Switched and fat-tree networks	Miscellaneous
S-5	SLO-1	Memory hierarchies	Using SIMD instruction sets	Mesh networks, Hybrids	Case study: OpenMP-parallel Jacobi algorithm
	SLO-2	Cache	The role of compilers	Parallelism- Data parallelism	Advanced OpenMP: Wavefront parallelization
S-6	SLO-1	Cache mapping	General optimization options	Functional parallelism	Efficient OpenMP programming
	SLO-2	Prefetch	Inlining, Aliasing	Parallel scalability	Profiling OpenMP programs
S-7	SLO-1	Multicore processors	Computational accuracy	Factors that limit parallel execution	Performance pitfalls
	SLO-2	Multithreaded processors	Register optimizations, Using compiler logs	Scalability metrics, Simple scalability laws	Ameliorating the impact of OpenMP worksharing constructs

S-8	SLO-1	Vector processors-	C++ optimizations- Temporaries	Parallel efficiency, Serial performance versus strong scalability	Determining OpenMP overhead for short loops	Aggregating messages
	SLO-2	Design principles	Dynamic memory management	Refined performance models	Serialization	Collective Communication
S-9	SLO-1	Maximum performance estimates	Loop kernels and iterators	Choosing the right scaling baseline	False sharing	Nonblocking vs. asynchronous Communication,
	SLO-2	Programming for vector architectures	Storage order- Case study: Jacobi algorithm and Dense matrix transpose.	Load imbalance	Case study: Parallel sparse matrix-vector multiply	Understanding intranode point-to-point Communication

Learning Resources	1. Georg Hager, Gerhard Wellein, "Introduction to High Performance Computing for Scientists and Engineers", Chapman & Hall/CRC Computational Sciences series, 2011.	3. Kai Hwang, Zhiweixu "Scalable Parallel Computing: Technology, Architecture, Programming",
	2. John Levesque, Gene Wagenbreth, "High Performance Computing: Programming and Application" CRC Press, 2010	4. Charles Severance, Kevin Dowd, "High Performance Computing", O'Reilly Media, 2nd Edition, 1998.

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50%								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Kesavan, HCL Technologies	1. Dr. Surendran Rajendran, AMA International University, Bahrain	1. J. Godwin Ponsam, SRMIST
2. Mr. R. Celein, Symmantec India Limited		2. Mr. Sivakumar SRMIST
		3. Mr. Jothikumar, SRMIST

Course Code	18CSE455T	Course Name	DATABASE SECURITY AND PRIVACY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	CSE	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1:	Understand the fundamentals of security relates to information	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	how security is maintained in information systems	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3:	Understand the concept of security models in database																		
CLR-4:	Implementation of virtual private database																		
CLR-5:	Learn the procedures of database auditing																		
CLR-6:	Implementation of data mining algorithms for PPDM																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1:	Acquire the knowledge of information system and information security	2	80	85	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-2:	Able to manage the security of information system as well as database	2	75	80	H	H	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-3:	Able to design and develop the security model in database	2	85	80	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-4:	Able to implement VPD in various database	2	80	75	H	H	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-5:	Able to audit the database activities, users, security	2	75	85	H	-	-	H	-	-	-	-	-	-	-	-	-	-	-
CLO-6:	Apply the security mechanism in PPDM using various algorithms	2	80	85	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Security Architecture: Introduction	Administration of Users-Introduction	Database Application Security Models: Introduction-	Auditing Database Activities-introduction	Privacy Preserving Data Mining Techniques: Introduction
	SLO-2 Information Systems	Authentication	Types of Users	Oracle Database Activities	Data Mining Techniques:
S-2	SLO-1 Database Management Systems	Creating Users	-Security Models	Oracle Database Activities	Privacy Preserving Data Mining Algorithms
	SLO-2 Information Security Architecture	SQL Server User	Application Types	Creating DLL Triggers with Oracle	Privacy Preserving Data Mining Algorithms
S-3	SLO-1 - Database Security	Removing, Modifying Users	-Application Security Models	Creating DLL Triggers with Oracle	General Survey-Data Mining Techniques
	SLO-2 Asset Types and value	Default users	Data Encryption	Auditing Database Activities with Oracle	Randomization Methods
S-4	SLO-1 Security Methods	Remote Users	Virtual Private Databases: Introduction	Auditing Database Activities with Oracle	Randomization Methods
	SLO-2 Operating System Security Fundamentals: Introduction	Database Links	-Overview of VPD	Auditing Server Activity with SQL Server 2000	Group Based Anonymization
S-5	SLO-1 Operating System Overview	Linked Servers	Implementation of VPD using Views	Auditing Server Activity with SQL Server 2000	Group Based Anonymization
	SLO-2 Security Environment	Remote Servers	Application Context in Oracle	Auditing Server Activity with SQL Server 2000	Distributed Privacy Preserving Data Mining
S-6	SLO-1 Security Components	Practices for Administrators and Managers-	Implementing Oracle VPD-	Auditing Server Activity with Oracle	Distributed Privacy Preserving Data Mining
	SLO-2 Authentication Methods	Profiles, Password Policies, Privileges and Roles: Introduction	Implementing Oracle VPD	Auditing Server Activity with Oracle	Curse of Dimensionality
S-7	SLO-1 User Administration	Defining and Using Profiles	Viewing VPD Policies	Security and Auditing	Application of Privacy Preserving Data Mining
	SLO-2 Password Policies	Designing and Implementing Password Policies	VPD using views	Security and Auditing	Application of Privacy Preserving Data Mining
S-8	SLO-1 Vulnerabilities	Best Practices	Application contexts using Data Dictionary	Casestudy: project security and auditing	Casestudy: on PPDM
	SLO-2 Vulnerabilities	Granting and Revoking User Privileges	Policy manager implementation	Casestudy: project security and auditing	Casestudy: on PPDM

S-9	SLO-1	Email Security	Creating, Assigning and Revoking User Roles	Policy Manager Implementing Row and Column level Security with SQL Server	Casestudy: project security and auditing	Casestudy: on PPDM
	SLO-2	Internet security	Best practices	Policy Manager Implementing Row and Column level Security with SQL Server	Casestudy: project security and auditing	Casestudy: on PPDM

Learning Resources	1. Hassan A. Afyouni, "Database Security and Auditing", Third Edition, Cengage Learning, 2009. 2. Ron Ben Natan, "Implementing Database Security and Auditing", Elsevier Digital Press, 2005	3. Charu C. Aggarwal, Philip S Yu, "Privacy Preserving Data Mining": Models and Algorithms, Kluwer Academic Publishers, 2008
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50%)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Somu Chockalingam, Founder and President, Doyensys, Chennai	Dr. K. Vivekanandan, Professor, Pondicherry Engineering College	1. Dr. B. Murugananthan, SRMIST
		2.. Ms. Thenmozhi, SRMIST
		3.. M. Maheswari, SRMIST

Course Code	18CSE456T	Course Name	SOFTWARE DEFINED NETWORKS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18CSC302J	Co-requisite Courses	Nil	Progressive Courses	
Course Offering Department	CSE	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	cover topics more advanced than a typical undergraduate networking course	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	prepare students for a market that is going to demand computer scientists and software engineers to deliver the next generation of network switches	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	describe the principles by which large computer networks and applications atop them are designed and maintained																		
CLR-4 :	Make students understand the state-of-the art networking technologies proposed in literature or used throughout industry in a variety of areas																		
CLR-5 :	Make students learn to critique research literature through a number of paper reviews and attempt to improve the state-of-the-art through minor and major projects																		
Course Learning Outcomes (CLO):	At the end of this course, learners will::																		
CLO-1 :	have a knowledge of the technology evolution leading to SDN as well as the Open Source role in SDN and OpenFlow specifications	3	75	80	H	M	H	-	H	-	-	-	-	-	-	H	H	H	H
CLO-2 :	gain a knowledge of the advantages and disadvantages of SDN, API approaches, Hypervisor overlays, and Data Center SDN, SDN WAN etc	3	75	80	H	M	H	-	H	-	-	-	-	-	-	H	H	H	H
CLO-3 :	Understand different network virtualization techniques and can deploy SDN/NFV applications	3	75	80	H	M	H	-	H	-	-	-	-	-	-	H	H	H	H
CLO-4 :	understand the economics of SDN and its impacts in the marketplace	3	75	80	H	M	H	-	H	-	-	-	-	-	-	H	H	H	H

Duration (hour)	9		9		9		9		9	
S-1	SLO-1	Introduction	Why SDN? Genesis of SDN	Alternative definitions of SDN	Emerging SDN Models	SDN Ecosystem				
	SLO-2	How to Read a Paper (S. Keshav)	How SDN Works	Potential drawbacks of Open SDN	Protocol Models: NETCONF, BGP, MPLS	White-box switching				
S-2	SLO-1	Ho to Review a Paper (Timothy Roscoe), How to Disagree (Paul Graham)	SDN Evolution, SDN Basics	SDN via APIs	Controller Models	Open Sourcing SDN				
	SLO-2	Networking Basics: Switching, Addressing, Routing	SDN Architecture	SDN via Hypervisor-Based Overlays	Application Models: Proactive, Declarative, External	Open Networking Foundation				
S-3	SLO-1	Paper Reading: 4D	Plane Separation	SDN via Opening Up the Device	SDN in Datacenters: Multitenancy, Failure Recovery	OpenDaylight				
	SLO-2	Paper Reading: 4D	Simple Device and Centralized Control	Building our own SDN Switch	SDN in Internet eXchange Points (IXPs)	The ONOS Project				
S-4	SLO-1	Paper Reading: ALF	Network Automation and Virtualization	SDN on Raspberry Pi, Zodiac Fx	Tunneling and Path Technologies, Ethernet Fabrics in the Data Center	Hypervisors: Background, Types				
	SLO-2	Paper Reading: ALF	Openness, Northbound and Southbound APIs	Ryu on Raspberry Pi, Zodiac Fx	SDN Use Cases, Open SDN versus Overlays in the Data Center	OpenStack Deployment				
S-5	SLO-1	Switching Architecture: Data, Control, and Management Planes	Paper Reading: OpenFlow: Enabling Innovation in Campus Networks	Network Function Virtualization (NFV)	Real-World Data Center Implementations, SDN in Other Environments	OpenStack Orchestration				
	SLO-2	Hardware Lookup	Review 1	Review 2	Review 3	Review 4				
S-6	SLO-1	Forwarding Rules	OpenFlow, Switch-Controller Interaction	SDN vs. NFV	Wide Area Networks	OpenSwitch				
	SLO-2	Dynamic Forwarding Tables	Flow Table, Packet Matching	OPNFV	Paper Reading: B4: Experience with a Globally-Deployed Software Defined WAN, SIGCOMM, 2013	Reactive versus Proactive Applications				

S-7	SLO-1	Autonomous Switches and Routers	Actions and Packet Forwarding	Service Creation and Chaining	Service Provider and Carrier Networks	Analyzing Simple SDN Applications
	SLO-2	Internet Architecture	Extensions and Limitations	NFV Orchestration	Campus Networks	Other SDN Applications
S-8	SLO-1	Control-Data Plane Separation	Paper Reading: P4: Programming Protocol-Independent Packet Processors	Creating Network Virtualization Tunnels	Hospitality Networks, Mobile Networks	Future of SDN
	SLO-2	Packet Scheduling	SDN Controllers: POX, RyuMininet Programming	Offloading Flows in the Data Center	In-Line Network Functions	SDN Security
S-9	SLO-1	Paper Reading: The Road to SDN: An Intellectual History of Programmable Networks	SDN Controllers: OpenDaylight, Mininet Programming	Access Control for the Campus	Optical Networks	Use Cases
	SLO-2	Project Proposal Due	SDN Controllers: ONOS, Mininet Programming	Traffic Engineering for Service Providers	SDN vs. P2P/Overlay Networks	Group Project Presentation

Learning Resources	1. Software Defined Networks: A Comprehensive Approach, 2 nd Edition Morgan Kaufmann, 2016 2. SDN: Software Defined Networks, Thomas D. Nadeau, Ken Gray, O'Reilly Media, 2013.	3. Network Function Virtualization, Ken Gray, Thomas D. Nadeau, Morgan Kaufmann, 2016
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
		1. Dr. Femilda
		2. Mr. K. Venkatesh
		3. Mr. KarthickNanmaran

Course Code	18CSE457T	Course Name	SEMANTIC WEB	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1:	Learn how the Semantic Web allows new uses of data	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2:	Understand how semantic technologies promote data portability	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3:	Become familiar with semantic standards-RDF,OWL	Expected Proficiency (%)	Problem Analysis
CLR-4:	Make use of semantic programming techniques to both enrich web application development	Expected Attainment (%)	Design & Development
			Analysis, Design, Research
			Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
			H L H - H - - - - - H H - M
			H H - - H - - - - - H H H M
			H H H - H - - - - - H - - H
			H H - - H - - - - - H H H H
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1:	Apply flexible approach for integrating and future-proofing systems and data	1 80 85	
CLO-2:	Program the Semantic Web provides a standard	3 75 80	
CLO-3:	Incorporate existing data sources into semantically aware applications and publish rich semantic data	3 85 80	
CLO-4:	Make the machines to find, share, and combine data on the Web	3 80 75	

Duration (hour)	9	9	9	9	9
S-1	SLO-1 The Semantic Web Vision	Querying the Semantic Web	Web Ontology Language	Logic and Inference: Rules	Applications
	SLO-2 Motivation for the Semantic Web	SPARQL Infrastructure	Requirements for Ontology Languages	Logic and Rules	e-commerce
S-2	SLO-1 Semantic Web Technologies	Matching Patterns	OWL Syntax	Rules on the Semantic Web	Adoption
	SLO-2 Explicit Metadata		Formal Semantics	Monotonic Rules	Publication
S-3	SLO-1 Ontologies	Filters	Expressivity	Monotonic Rules: Syntax	News website application
	SLO-2 RDF,OWL			Rules, Facts	Adoption
S-4	SLO-1 Logics-Principles of reasoning	Constructs for Dealing with an Open World	Reasoning Support	Logic Programs	Publication
	SLO-2 The Semantic Web versus Artificial Intelligence			Monotonic Rules: Semantics	Constructing Ontologies Manually
S-5	SLO-1 A Layered Approach	Organizing Result Sets	Compatibility of OWL2 with RDF/RDFS	Predicate Logic Semantics	Reusing Existing Ontologies
	SLO-2 RDF: Data Model	Other Forms of SPARQL Queries	OWL2 Full: RDF-Based Semantics	OWL2 RL	Rule Interchange Format: RIF
S-6	SLO-1 RDF/XML	Querying Schemas	OWL2 DL: Direct Semantics	RIF-BLD	Semiautomatic Ontology Acquisition
	SLO-2 RDFS: Adding Semantics		The OWL2 primitives	Compatibility with RDF and OWL	Ontology Mapping
S-7	SLO-1 Classes and Properties	Adding Information with SPARQL Update	OWL2 Syntax	Semantic Web Rules Language (SWRL)	SemanticWeb Application
	SLO-2 Class Hierarchies and Inheritance	Inserting and Loading Triples	OWL2 Property Types		Architecture
S-8	SLO-1 Property Hierarchies	Deleting Triples	OWL2 Property Axioms	Rules in SPARQL: SPIN	
S-9	SLO-2 RDF Schema	Case study	OWL2 Class Axioms	RuleML	
			Individual Facts		

Learning Resources	1. Grigoris Antoniou and Frank Van Harmelen, <i>A Semantic Web Primer</i> - The MIT Press, Cambridge, Massachusetts London, England, Edition 3, 2012 2. Toby Segaran, Colin Evans, Jamie Taylor, <i>Programming the Semantic Web Build Flexible Applications with Graph Data</i> , O'Reilly Media, 2009	3. John Hebel, Matthew Fisher, Ryan Blace, Andrew Perez-Lopez, Mike Dean <i>Semantic Web Programming</i> , 1st Edition, Wiley, 2009. 4. Thomas B. Passin, <i>Explorer's Guide to the Semantic Web</i> , Manning, 2004
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. Harisekharan, CTO, Sri Seshaa Technologies Pvt. Ltd., Chennai	1. Dr. J. Suresh, SSN College of Engineering	Dr. G. Vadivu
	2. Dr. Sharmila Shankar, Crescent Institute of Science and Technology	Dr. C. N. Subalalitha
		Ms. S. Veena

Course Code	18CSE458T	Course Name	WIRELESS AND MOBILE COMMUNICATION	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	
Course Offering Department	Computer Science and Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1:	Analyze the fundamental of transmission and cellular systems	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2:	Apply skills in real time engineering problems and can have capability to evaluate the transmission errors	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3:	Comprehend the concept of mobile network, transport layer and wireless technologies	Expected Proficiency (%)	Problem Analysis
CLR-4:	Differentiate the various types of cellular standard by their unique services.	Expected Attainment (%)	Design & Development
CLR-5:	Grasp GSM, GPRS, Handover and Localization techniques		Analysis, Design, Research
CLR-6:	Apply skills in various Routing protocols		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1:	Apply Wireless Technology concepts to Engineering problems related to Communication	3 80 70	H H H H H H H H H H M H H H H
CLO-2:	Improve their knowledge on Digital and analog Modulation techniques.	3 85 75	H H H H H H H H H H M H H H H
CLO-3:	Equip themselves familiar with principle of Mobile Communication	3 75 70	H H H H H H H H H H M H H H H
CLO-4:	Familiarize with Digital Cellular Standards	3 85 80	H H H H H H H H H H M H H H H
CLO-5:	Acquaint with routing protocols	3 85 75	H H H H H H H H H H M H H H H
CLO-6:	Expose to the emerging wireless technologies	3 80 70	H H H H H H H H H H M H H H H

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Introduction to wireless Communication	Cellular Concept	Introduction to GSM	Mobile IP	IEEE 802.11
	SLO-2 Elements of wireless Communication system	Cell area	Frequency Bands and Channels	IP packet delivery	System Architecture
S-2	SLO-1 Frequencies for radio Communication	Signal strength	Frames in GSM	Tunneling – Reverse Tunneling	Protocol Architecture
	SLO-2 Signals, Noise – Types of Noise	Cell parameter	Planes and layers of GSM	IPv6	MAC Layer and Management
S-3	SLO-1 Introduction to modulation and demodulation	Capacity of Cell	Protocols	DHCP	802.11a, 802.11b
	SLO-2 Signals in the modulation	Co channel interference	Localization and calling	Tradition TCP	HIPERLAN
S-4	SLO-1 Introduction to Analog modulation schemes	Frequency reuse	Handoff – Short messaging system	Congestion control	Bluetooth Architecture
	SLO-2 Amplitude Modulation Frequency modulation	Cell splitting Cell sectoring	GPRS EDGE	Classical TCP Snooping ,	IEEE 802.15 IEEE 802.15.4
S-5	SLO-1 Phase Modulation Introduction to Analog modulation schemes	Multiple Radio access protocols	3G CELLULAR SystemsMMS	Mobile TCPFast retransmit / Fast recovery	MANET characteristicsROUTING
	SLO-2 Amplitude Shift Keying Frequency Shift Keying Phase Shift Keying- BPSK, QPSK	Frequencydivision Multiple Access	UMTS Release and standards	Transaction oriented TCP TCP over 2.5/3G	AODV Routing VANETCommunications in VANET
S-6	SLO-1 Multiplexing and multiple access techniques	Time division Multiple Access Fixed ALOHA , Slotted ALOHA	UMTS system architecture UTRAN	Introduction to WAP WAP Architecture	Wireless Sensor Networks
S-7	SLO-1 Frequency-division multiplexing	Multiple Access with Collision Avoidance techniques	Handover	Wireless Datagram ProtocolWireless Transaction Protocol	RFID TechnologyTwo tags of RFID
	SLO-2 Time-division multiplexing	Space division Multiple Access Code division Multiple Access	Satellite System Infrastructure- GEO, LEO, MEO	Wireless Session Protocol	Wi-Fi Standards
S-8	SLO-1 Code-division multiplexing	Spread ALOHA multiple Access	Limitations of GPS	Wireless Transport Layer Security	WiMax Standards
	SLO-2 Spread spectrum modulation	OFDM	GPSBeneficiaries of GPS		
S-9	SLO-1 frequency hopping Spread spectrum	Variants of OFDM			
	SLO-2 Direct Sequence Spread spectrum	Comparison of Multiple Access Technique	4G Cellular systems	Wireless Markup Language	Fem-to-Cell Network
			4G Standards (LTE/WiMax)	Push Architecture	Push-to-talk technology for SMS

Learning Resources	1. Roy Blake, <i>Wireless Communication Technology</i> CENGAGE learning, Sixth indian reprint 2013. 2. Dharma Prakash Agarwal, Qing-An Zeng , "Introduction to Wireless and Mobile Systems" CENGAGE learning, First edition 2014. 3. Jochen Schiller, "Mobile Communications", Addison Wesley, 2 nd edition 2011. 4. Singal TL, "Wireless Communication", Tata McGraw Hill Education Private Limited. 5. G.I.Papadimitriou, A.S.Pomportsis, P.Nicopolitids, M.S.Obaidat, "Wireless Networks", John Wiley and Sons, 2003	6. Gray J.Mullet "Wireless TeleCommunication System and Networks", CENGAGE learning, reprint 2014. 7. Upena Dalal, "Wireless Communication" Oxford University Press, First edition 2009. 8. Kaveh Pahlavan & Prashant Krishnamurthy, "Wireless Networks" PHI 2002. 9. Martyn Mallick, "Mobile and Wireless Design Essentials", Wiley Dreamtech India Pvt.Ltd., 2014.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Dr.Madan Lakshmanan	Prof. Subra Ganesan	Dr.S.Suresh
Senior Scientist	Professor, Electrical and Computer Engineering	Mrs.Jeya
CEERI, CSIR, Chennai (R&D Industry)	Oakland University, USA	Mr.H.Karthikeyan

Course Code	18CSE459T	Course Name	SERVICE ORIENTED ARCHITECTURE	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Learn service oriented analysis techniques		1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Learn technology underlying the service design		Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Learn advanced concepts in building SOA					H	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLR-4 :	Understand the Java Web services					H	H	-	-	-	-	-	-	-	-	-	-	-	-	-
CLR-5 :	To know about various Web services specification standards					H	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLR-6 :						H	H	-	-	-	-	-	-	-	-	-	-	-	-	-
						H	-	-	H	-	-	-	-	-	-	-	-	-	-	-
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:				H	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-1 :	Acquire the knowledge on service oriented design technology		2	80	85															
CLO-2 :	Acquire the ability to identify web services in SOA		2	75	80															
CLO-3 :	Understand the basic ideas about building SOA		2	85	80															
CLO-4 :	Appreciate the concepts of standards and security on SOA		2	80	75															
CLO-5 :	Apply the knowledge in Java based web service		2	75	85															
CLO-6 :	Acquire the knowledge on ASP .NET based web services.		2	80	85															

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction to SOA , Defining SOA	Introduction to Web Services	Phases of the SOA delivery lifecycle	SOA support in J2EE	Introduction to WS-BPEL
	SLO-2	Necessity of SOA.	Primitive SOA	SOA Delivery Strategies Top- down strategy, Bottom-up strategy	SOA platform basics and building blocks	Basic terms used in the BPEL terminology
S-2	SLO-1	SOA timeline from XML to Web services to SOA	Web Service Framework with respect to SOA	Agile strategy with Pros and cons	Overview of Java API for XML- based web services(JAX- WS)	WS-Coordination overview
	SLO-2	History about XML	Logical components of the Web services framework	Objectives and service-oriented process steps	Java Architecture for XML binding (JAXB)	WS-Choreography
S-3	SLO-1	Web Services and SOA	Service descriptions with WSDL layout	Benefits of a business-centric SOA	Building web services and client with examples	WS-Policy with SOA
	SLO-2	Service Oriented Enterprise (SOE)	Meta data and service contracts	Service- oriented design	Introduction to Java API for XML Registries(JAXR)	WS Security
S-4	SLO-1	Analyze the past architectures	Messaging with SOAP protocol and SOAP nodes	Introduction to WSDL language basics	Java API for XML based RPC (JAX-RPC)	Notification and Eventing
	SLO-2	Scope Of SOA	SOAP message path	Define the structure of WSDL	Web Services Interoperability	Transaction Management
S-5	SLO-1	SOA Reference Model	Message exchange Patterns and Coordination	Implement sample WSDL file	SOA support in .NET	Case study-SOA in cloud
	SLO-2	Key Service characteristics of SOA	Web Services a Activity Management,	Introduction to SOAP basics	NET Platform overview	research focus on SOA and issues
S-6	SLO-1	Anatomy of SOA	Coordination types and protocols	SOAP language basics	ASP.NET Page Handling	Comparative Analysis of SOA and Cloud Computing
	SLO-2	SOA architecture	ACID properties	Structure of SOAP	Post back vs Non post back events	
S-7	SLO-1	Components in SOA interrelate	Analyze atomic transaction with SOA	Implement SOAP style web services in Java.	ASP.NET web services	
	SLO-2	SOA component and specific behaviors	Business activities and protocols	SOA Composition	Creating a Web Site Using Visual Studio IDE	Case Study On Vehicle management system- create a service for identify the vehicle by entering the vehicle number.

S-8	SLO-1	Relationships among these components	Orchestration	service layers and standards	ASP.NET Programming Basics	Case Study on Online Healthcare System-Design an API to help healthcare providers collect, store, retrieve and exchange patient healthcare information more efficiently and enable better patient care.
	SLO-2	Technical Benefits of SOA	Choreography	Entity-centric business service design: List the step-by-step process	Creating a Web Site Using Visual Studio IDE	
S-9	SLO-1	Business Benefits of SOA	Service layer configuration scenarios	Application service design: process steps	Case Studies: Implement the Small Business Customer Management application as a web applications using ASP.NET	Case study on Simple Library Management System using API to get, post, edits and update book data from server.
	SLO-2	Principles of service orientation	Application Service Layer	Task centric business service design process steps	Web Services Enhancements (WSE)	

Learning Resources	<p>1. Thomas Erl, "Service-Oriented Architecture: Concepts, Technology, and Design", Pearson Education, 2009.</p> <p>2. Eric Newcomer, Lomow, "Understanding SOA with Web Services", Pearson Education, 2005</p> <p>3. James McGovern, Sameer T yagi, Michael E Stevens, Sunil Mathew, Java Web Services Architecture", Elsevier, 2003.</p>	<p>4. Achieving Service-Oriented Architecture: Applying an Enterprise Architecture Approach, Rick Sweeney, 2010</p> <p>5. Shankar Kambhampally, "Service -Oriented Architecture for Enterprise Applications", Wiley India Pvt Ltd, 2008</p> <p>3. Newcomer, Lomow, "Understanding SOA with Web Services", Pearson Education, 2005</p> <p>4. Sandeep Chatterjee, James Webber, "Developing Enterprise Web Services, An Architect's Guide", Pearson Education 2005</p>
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50%)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts

Course Code	18CSE460T	Course Name	NETWORK DESIGN AND MANAGEMENT	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand the various type of Networks and the Network Management basics	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Understand the Network Management Standards	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Understand the working of Simple Network Management Protocol and its various versions																		
CLR-4 :	Understand the working of Remote Monitoring																		
CLR-5 :	Understand the Network Management Applications																		
CLR-6 :	To Understand Network Designing and Planning																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Acquire knowledge on networks and network management	1	70	75	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-2 :	Gain knowledge of the various standards	1	75	80	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-3 :	Gain knowledge on the working of SNMP protocol and its various applications	1	85	80	H	-	-	-	M	-	-	-	M	-	-	-	-	-	-
CLO-4 :	To apply the network management tools and gather information from the network	2	75	70	H	-	-	-	M	-	-	-	M	-	-	-	-	-	-
CLO-5 :	To Familiarize with the working of various management applications	2	75	80	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-6 :	Apply the knowledge to create an efficient network	3	70	75	H	H	H	H	H	-	-	-	H	-	-	-	-	-	-

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Telephone Network Management	Introduction to SNMP	Remote Monitoring	Network Management Applications	Network Design and Planning
	SLO-2 Distributed Computing Environment	SNMP v1 model	RMON SMI and MIB	Fault Management -Architecture	Network Design for Enterprise Network
S-2	SLO-1 TCP/IP Based Networks	Organization Model	RMON1	Fault location ,Fault isolation	Network Design Process
	SLO-2 Communication Protocols and Standards	System overview	RMON2	Algorithm	Data Collection
S-3	SLO-1 Protocol Layer and Services	SNMP v1 Information model	System Utilities for Management	Self-healing	Data Generation
	SLO-2 Challenges of IT Managers	Structure of Management Information	Tools	Avoiding failures	Traffic Generators
S-4	SLO-1 Network Management	Managed Objects	Network Statistics Measurement Systems	Configuration setting,	Cost Generators
	SLO-2 Network and System Management	MIB-Object Group	Traffic Load	Configuration discovery and Change Control	Topology
S-5	SLO-1 Network Management System Platform	System Group, Interfaces Group, Address Translation group	Protocol Statistics	Configuration Management Applications	Architecture
	SLO-2 Current status and future of Network Management	IP Group, ICMP Group, TCP Group, UDP Group	Data and Error Statistics	Patch Management	Graph
S-6	SLO-1 Network Management Standards	SNMP v1Communication model	Network Management System	Approaches for Performance Management	Link
	SLO-2 Network Management Model - Organizational model	Functional model	Components, Requirements	Performance Monitoring and Reporting	Algorithms
S-7	SLO-1 Information Model	SNMPv2	System Management	Performance trouble shooting,	Network Design Techniques
	SLO-2 Management Information Trees	System Architecture, MIB, Protocol	Network Management Applications	Capacity Planning	Performance Analysis
S-8	SLO-1 Communication Model	SNMPv3	Configuration Management	Account Management	Queuing Essentials
	SLO-2 ASN.1	Architecture, Applications, MIB	Inventory Management	Report Management-System and User Reports	Loss and Delay
S-9	SLO-1 Terminology, Symbols and Conventions	User Based Security Model	Performance Management	Policy Management	Reliability
	SLO-2 Functional Model	Access Control	Tools	Service Level Management	Network Cost

Learning Resources	1. Mani Subramanian "Network Management Principles and Practice", Second Edition, Pearson Publication, 2012. 2. DineshChandraVerma, "PrinciplesofComputerSystemsandNetworkManagement", Springer, 2009.	3. Greg Tomsho, Ed Tittel, David Johnson, "Guide to Network Essentials", Fifth Edition, Cengage Learning, 2010 4. Teresa C.Piliouras, "Network Design Management and Technical Perspectives", Second Edition, 2004
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50%)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	40 %	-	20 %	-	30 %	-	40%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	20 %	-	40 %	-	30 %	-	20%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.Vivekanandan ,Nokia Technology Specialist, anandanviv1@gmail.com	1.	1. Dr.B.Amutha, SRMIST
2.Mr.SanthoshKumar.S,Associate Consultant,TCS, santhosh.sansoft@gmail.com	2.	2.Dr.N.Snehalatha, SRMIST

Course Code	18CSE387T	Course Name	GENETIC ALGORITHM AND MACHINE LEARNING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1:	Evolutionary Computation and Genetic Algorithms	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Terminologies and operators of GA and	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3:	Advanced Operators and Techniques in GA and Classification of Genetic Algorithms																		
CLR-4:	Genetic Programming and Genetic Algorithm Optimization problems																		
CLR-5:	Applications of Genetic Algorithms																		

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	L	H	-	H	L	-	-	-	L	L	-	H	-	-	-
CLO-1:	Provides a introduction to genetic algorithm including fundamentals of genetic concepts	3	80	75	M	H	L	H	L	-	-	-	M	L	-	H	-	-	-
CLO-2:	To have a clear view of genetic operators	3	85	75	M	H	M	H	L	-	-	-	M	L	-	H	-	-	-
CLO-3:	To explore Genetic Algorithm optimization problems	3	80	75	M	H	M	H	L	-	-	-	M	L	-	H	-	-	-
CLO-4:	Discuss applications of Genetic Algorithms for various optimization problems.	3	85	80	M	H	M	H	L	-	-	-	M	L	-	H	-	-	-

Duration (hour)	9	9	9	9	9
S-1	SLO-1 The Historical Development of Evolutionary Computing. Genetic Algorithms and Genetic Programming	Terminologies and operators of GA.Key elements, Individuals. Genes, Fitness, Populations. Data Structures.	Diploidy, Dominance etc. Inversion and Reordering. Order Crossover and Cycle crossover.	Genetic programming (GP). Comparison of GP and other algorithms. Genetic operators. Tree based GP, Representation of GP.	Specific Applications of Genetic Algorithms. GA in network synthesis, Control systems engineering and Fuzzy based speed control of Brushless DC motor.
S-2	SLO-1 Features of Evolutionary Computation Advantages of Evolutionary computation.	Breeding, Selection, Crossover, Mutation and Replacement.	Micro operators: Segregation and translocation, Duplications and Deletion, Sexual determination.	Attributes in GP. Steps of GP, Characteristics of GP. What are Human Competitive, High-Return, Routine, and Machine Intelligence?	Feature selection in machine learning using GA. Designing texture filters with GA.
S-3	SLO-1 Genetic algorithms-Biological background. Cell, Chromosomes, Genetics, Reproduction and Natural selection.	Search Termination or Convergence criteria.	Non-binary representation, Multi-objective optimization, combined optimization and Knowledge based techniques.	Applications of Genetic Programming	GA based knowledge acquisition in Image Processing. Object localization in image using GA.
S-4	SLO-1 Search space, GA world, Evolution and optimization	Best individual, Worst individual, Sum of fitness and Medium fitness.	Classification of GAs. Simple Genetic algorithms (SGA). Parallel and distributed GAs.	GA Optimization problems: Fuzzy optimization problems, Multi objective Reliability Design Problem. Network and bicriteria reliability problems.	Data mining applications such as feature selection in data mining, GA in intrusion detection, etc.
S-5	SLO-1 Evolution and genetic algorithms. Conventional optimization and search techniques.	Why do genetic algorithms work? Building block hypothesis	Master-slave, Fine-grained parallel GAs. Multiple-Deme Parallel GAs.	Combinatorial Optimization problems. Linear integer model,	Applications in wireless networks for topology planning. GA application in ATM network.
S-6	SLO-1 Gradient based, Random search, Stochastic Hill climbing	A Macro mutation hypothesis. An adaptive mutation hypothesis.	Hierarchical Parallel algorithms. Hierarchical Genetic Algorithms: Crossover, Initialization heuristics. Remove sharp algorithms.	Applications of combinatorial optimization methods.	VLSI design applications Genetic layout optimization using GA.
S-7	SLO-1 Simulated Annealing, Symbolic AI. A simple Genetic Algorithm.	The schema theorem Optimal allocation of Trials. Implicit Parallelism	Adaptive GA., Initialization, Evaluation function, Selection operators, Crossover operators, and mutation operators.	Network design and Routing problems	Introduction to Particle Swam Optimization [PSO] and Ant Colony Optimization [ACO].

S-8	SLO-1	Comparison of GA with other optimization techniques.	Advanced operators and techniques in GA,	Independent sampling GA and Breeding Phase.	Planning of passive optical networks, Packet switched networks,	Examples on PSO and ACO.
S-9		Limitations of GA.	Convergence problems in GA	Niched pareto genetic algorithm	Optimal topological design of all terminal networks.	Comparison of GA with PSO and ACO

Learning Resources	1. S.N. Sivanandam and S.N. Deepa , "Introduction to Genetic Algorithms", Springer, 2nd edition (2008) 2. Mitsuo Gen and Runwei Cheng, "Genetic Algorithms and Engineering Optimization", John Wiley, Fourth edition (2010) 3. Michael Negnevitsky, "Artificial Intelligence, A Guide to Intelligent Systems", Second edition ((2005))					
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. K. Selvaraj, Caterpillar, Bangalore	Dr. A.P. Shanthi, CSE, Anna University, Chennai	1.Dr. V. Ganapathy SRMIST
	Dr. A. Kannan, CSE, VIT, Vellore.	2.Dr. D. Rajeswari SRMIST
		3.S. Saranya SRMIST

Course Code	18CSE388T	Course Name	ARTIFICIAL NEURAL NETWORKS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																	
CLR-1 :	Connect Biology with Computers	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15			
CLR-2 :	Understand components of artificial neural networks																								
CLR-3 :	Understand supervised learning networkparadigms																								
CLR-4 :	Understand unsupervised learning networkparadigms																								
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:						Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3			
CLO-1 :	Know the purpose of Artificial Neural Networks				1	80	85	H	L	-	-	H	-	-	-	-	-	-	H	L	L	L			
CLO-2 :	Apply the concepts of activation, propagation functions				2	75	80	H	H	-	-	H	-	-	-	-	-	-	H	H	H	H			
CLO-3 :	Work with supervised learning network paradigm				3	85	80	H	H	H	-	H	-	-	-	-	-	-	H	H	H	H			
CLO-4 :	Work with unsupervised learning network paradigm				3	80	75	H	H	-	-	H	-	-	-	-	-	-	H	H	H	H			

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Why neural network?	Components of artificial neural networks	Learning and training samples	Radial basis functions	Unsupervised learning network paradigms
	SLO-2 Basics of Artificial Neural Networks	The concept of time in neural networks	Paradigms of Learning	Information processing of an RBF network	Structure of a self-organizing map(SOM)
S-2	SLO-1 A brief history of neural networks	Connections	Using training samples	Training of RBF networks	Functionality
	SLO-2 Biological neural networks	Propagation function	Gradient Optimization Procedure	Growing of RBF networks	Training
	SLO-1 Biological neural networks	Activation	Hebbian learning rule	Topology function	Topology function
S-3	SLO-2 The vertebrate nervous system	Threshold value, Activation function	Supervised learning network paradigms	Compare multilayer perceptrons and RBF	Decreasing Learning Rate
S-4	SLO-1 peripheral nervous system	Common activation functions	The perceptron, back propagation and its variants	Recurrent perceptron-like networks	Variations of SOMs
	SLO-2 Cerebrum, cerebellum, diencephalon, brainstem	Output function, Learning strategies	Singlelayer perceptron	Jordan networks	Neural gas
S-5	SLO-1 Network topologies	Network topologies	Linear Separability	Elman networks	Multi-SOM
	SLO-2 The Neuron	Feedforward networks	Multilayer perceptron	Training recurrent networks	Multi-neural gas
S-6	SLO-1 Components	Recurrent networks	Backpropagation of error	Growing neural gas	Growing neural gas
	SLO-2 Electrochemical processes	Completely linked networks	Selecting learning rate	Unfolding in time	Adaptive resonance theory(ART)
S-7	SLO-1 Receptor cells- Various types	Bias neuron	Resilient Backpropagation	Teacher forcing	Task and structure of an ART network
	SLO-2 Information processing within nervous system	Representing Neurons	Adaption of Weights		
S-8	SLO-1 Light Sensing organs	Orders of Activation	Variations in Backpropagation	Recurrent backpropagation	Resonance
	SLO-2 Neurons in living organisms	Synchronous activation			
S-9	SLO-1 Transition to technical neurons	Asynchronous activation	Multilayer perceptron	Evolutionary algorithms	Learning process of an ART network
	SLO-2	input and output of data			

Learning Resources	1. David Kriesel, A Brief Introduction to Neural Networks, dkriesel.com, 2005 2. Gunjan Goswami, Introduction to Artificial Neural Networks, S.K. Kataria & Sons, 2012	3. Raul Rojas, Neural Networks: A Systematic Introduction, 1996. 4. S. Sivanandam, Introduction to Artificial Neural Networks, 2003
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.Harisekharan,CTO,Sri SeshaaTechnologies Pvt. Ltd., Chennai	1. Dr.J.Suresh, SSN College of Engineering	Dr.G.Vadivu
	2. Dr. Sharmila Shankar, Crescent Institute of Science and Technology	Dr. D.Rajeswari
		Dr.M.S.Abirami

Course Code	18CSE389T	Course Name	FUZZY LOGIC FOR MACHINE LEARNING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science & Engg	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand the Fuzzy Logic Basics				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Gain knowledge on the Machine learning concepts				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Gain knowledge on Fuzzy based clustering concepts																					
CLR-4 :	Acquire knowledge on Fuzzy Integrated classification																					
CLR-5 :	Understanding Neuro-Fuzzy Modeling concepts																					
CLR-5 :	Acquiring better understanding on Fuzzy logic usage																					
CLR-6 :	Understanding the fuzzylogics in Machine learning																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			2	80	85	H	M	-	H	-	-	-	-	-	-	H	L	H	H	M
CLO-1 :	Acquire the knowledge on Basics of Fuzzy Logic				2	80	85	H	M	-	H	-	-	-	-	-	-	H	L	H	H	M
CLO-2 :	Understand the basic concepts in Machine learning				2	75	80	H	H	-	H	-	-	-	-	-	-	H	L	H	H	M
CLO-3 :	Apply the knowledge of Clustering in Fuzzy logics				2	85	80	H	-	-	H	-	-	-	-	-	-	H	L	H	H	M
CLO-4 :	Apply the concept of Classification in Fuzzy Logics				2	80	75	H	H	-	H	-	-	-	-	-	-	H	L	H	H	M
CLO-5 :	Acquire the knowledge on Neuro-Fuzzy resoning				2	75	85	H	-	-	H	-	-	-	-	-	-	H	L	H	H	M
CLO-6 :	Acquire the insight of Neuro-Fuzzy Modelina				2	75	85	H	-	H	H	H	-	-	-	-	-	H	L	H	H	M

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Fuzzy Logic Introduction : Comparison of traditional logic and fuzzy logic	Machine learning : Importance of ML	Fuzzy Clustering Basics: Cluster analysis Objective function-based cluster analysis, Fuzzy analysis of data	Fuzzy Integral Classification: Introduction and Notation , Reduction vs. Ordering	Neuro Fuzzy Modeling : ANFIS – Adaptive Neuro Fuzzy Inference system
	SLO-2	Basic History of Fuzzy Logic	Types of MachineLearning : SupervisedLearning-Unsupervised Learning, reinforcement Learning	Special objective functions, A principal clustering algorithm	The Borda Count	ANFIS - architecture
S-2	SLO-1	The case of Imprecision, A Historical perspective	TheCurse of dimensionality Overfitting and linear regression	Classical Fuzzy Clustering Algorithms : The fuzzy c-means algorithm	The Average Rule , The Median Alternative	Hybrid learning algorithm
	SLO-2	The Utility of Fuzzy systems, Limitations of Fuzzy systems		The Gustafson-Kessel algorithm	The Product Rule, The MaxMax and MaxMin Rules	Coactive Neuro fuzzy modeling : Towards generalized ANFIS
S-3	SLO-1	Fuzzy sets and membership	Bias andVariance LearningCurve		The Intersection Method , The Union Rule	Framework
	SLO-2	Chance Vs Fuzziness		The Gath-Geva algorithm	Logistic Regression : The Logit Transform and Maximum Likelihood Estimation	Neuron functions for adaptive networks
S-4	SLO-1	Classical sets and Fuzzy sets : Operations on classical sets, properties of classical sets	Classification	Computational effort	Separate Weight Sets	Fuzzy membership functions Vs Receptive field units
	SLO-2	Operations on fuzzy sets, properties of fuzzy sets	Error and noise	Linear and Ellipsoidal Prototypes : The fuzzy c-varieties algorithm	Model Selection by Local Accuracy	Non-linear rule
S-5	SLO-1	Classical relations : Cartesian product, crisp relations	Measuring(dis)similarity-Evaluating the output of clusteringmethod	The adaptive fuzzy clustering algorithm	Maximizing the Fuzzy Integral : What Does This Have to Do with Classifier Combination?	Neuro-fuzzy spectrum
	SLO-2	Fuzzy relations: cardinality of fuzzy relations, operations on fuzzy relations	Hierarchical clustering, Agglomerativeclustering - Divisiveclustering	Algorithms by Gustafson/Kessel and Gath/Geva	Pairwise Coupling - Pairwise Threshold Optimization	Analysis of Adaptive learning capability : Convergence based on the steepest descend method alone
S-6	SLO-1	Properties of fuzzy relations	K-Meansclustering		Comparing the Combination Methods : Small Training Set, Three Models	Interpretability spectrum

	SLO-2	Tolerance and Equivalence relations: crisp tolerance		Cluster Estimation Models :AO membership functions	Large Training Set, Three Models	Evolution of antecedents
	SLO-1	Fuzzy Tolerance	Perceptrons	ACE membership functions	Small Training Set, Three Good Models , One Worthless	Evolution of consequence
S-7	SLO-2	Properties of Membership functions, Fuzzification and defuzzification – Features of the memberfunction	Feedforward networks.	Hyperconic clustering (dancing cones)	Large Training Set, Three Good Models, One Worthless	Evolving partitions
	SLO-1	Various forms	Multilayer Networks and Back Propagation Algorithms	Cluster Validity : Global validity measures	Small Training Set, Worthless and Noisy Models Included	Neuro Fuzzy Control : Feedback control systems and Neuro fuzzy control
	SLO-2	Defuzzification of crisp sets	Linear Models – Linear regression, Logistic regression	Solid clustering validity measures, Shell clustering validity measures	Large Training Set, Worthless and Noisy Models Included	Expert control
	SLO-1	Lambda cuts of fuzzy relations, Defuzzification to scalars	Tree learning : Decision trees	Local validity measures : The compatible cluster merging algorithm, The unsupervised FCSS algorithm	Fuzzy Association rules	Inverse learning, specialized learning
	SLO-2	Conclusion : Benefits of Fuzzy in comparison with crisp	Conclusion : Summary of ML concepts	Conclusion : Fuzzy based clustering merits	Conclusion : Fuzzy based classifier benefits	Conclusion : Summary / benefits of Neuro-fuzzy systems

Learning Resources	<ol style="list-style-type: none"> 1. Vojislav Kecman, Learning and soft computing: Support vector Machines, Neural networks and Fuzzy logic models, A Bradford Book, The MIT Press., 2001, ISBN : 0-262-11255-8 2. Timothy J. Ross, University of New Mexico, USA., Fuzzy Logic with Engineering Applications, 3rd Edition, Wiley, 2010. ISBN 978-0-470-74376-8 3. Frank Höppner, Frank Klawonn, Rudolf Kruse and Thomas Runkler: Fuzzy Cluster Analysis, Wiley (1999) ISBN 0-471-98864-2 4. Timothy Masters, Assessing and Improving Prediction and Classification Theory and Algorithms in C++, ISBN-13 (pbk): 978-1-4842-3335-1 ISBN-13 (electronic): 978-1-4842-3336-8, https://doi.org/10.1007/978-1-4842-3336-8, 2018. 5. Jyh-Shing, Roger Jang, Chuen-Tsai sun, Eiji Mizutani., Neuro fuzzy and soft computing – A computational approach to learning and machine intelligence, Prentice Hall (1997) , ISBN : 0-13-2610663 6. Kevin P. Murphy, "Machine Learning: A Probabilistic Perspective", MIT Press, 2012 7. Elthem Alpaydin, "Introduction to Machine Learning", Prentice Hall of India, 2005 8. Tom Mitchell, "Machine Learning", McGraw-Hill, 1997.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
<ol style="list-style-type: none"> 1. Dr.R.Gokulakrishnan, Additional Director(EXIM), Software Technology Parks of India , r.gokul@stpi.in 2. Dr.Prabhu, Coherent , US., prabu.balu@coherent.com 	Dr.Subrat Kumar Nayak, Associate professor, Institute of Technical education and Research, subratnayak@soa.ac.in	Dr.G.Maragatham , Dr. Manas Ranjan , Ms.A.Saranya

Course Code	18CSE390T	Course Name	COMPUTER VISION	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Recognize and describe both the theoretical and practical aspects of computing with images. Connect issues from Computer Vision to Human Vision				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Describe the foundation of image formation and image analysis. Understand the basics of 2D and 3D Computer Vision.							Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Become familiar with the major technical approaches involved in computer vision. Describe various methods used for registration, alignment, and matching in images.																					
CLR-4 :	Get an exposure to advanced concepts leading to object and scene categorization from images.																					
CLR-5 :	Build computer vision applications.																					
CLR-5 :	Recognize and describe both the theoretical and practical aspects of computing with images. Connect issues from Computer Vision to Human Vision																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			3	80	75	L	H	-	H	L	-	-	-	L	L	-	H	-	-	-
CLO-1 :	Provide an introduction to computer vision including fundamentals of image formation				3	85	75	M	H	L	H	L	-	-	-	M	L	-	H	-	-	-
CLO-2 :	Provide a clear view of image formation				3	80	75	M	H	M	H	L	-	-	-	M	L	-	H	-	-	-
CLO-3 :	Provide a clear view of image processing				3	85	80	M	H	M	H	L	-	-	-	M	L	-	H	-	-	-
CLO-4 :	Provide knowledge about Computational photography				3	80	75	H	H	M	H	L	-	-	-	M	L	-	H	-	-	-
CLO-5 :	Provide knowledge about Image rendering				3	85	80	H	H	M	H	L	-	-	-	M	L	-	H	-	-	-

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction to Computer Vision	Points and patches-An Introduction	Active contours	Triangulation	Motion models
	SLO-2	Image formation	Feature detectors	Snakes	Two-frame structure from motion	Planar perspective motion
S-2	SLO-1	Geometric primitives	Feature descriptors	Dynamic snakes and CONDENSATION	Projective reconstruction	Rotational panoramas
	SLO-2	2D,3D Transformations			Self-calibration	
S-3	SLO-1	3D to 2D Projection	Feature matching	Scissors	Perspective and projective factorization	Gap closing
	SLO-2	Lighting,Reflectance and shading		Level Sets	Bundle adjustment	
S-4	SLO-1	Sampling and aliasing	Feature tracking	Split and merge	Exploiting sparsity	Cylindrical and spherical coordinates
	SLO-2	Image processing Point operators				
S-5	SLO-1	Pixel transforms	Edge detection	Mean shift and mode finding	Constrained structure and motion	Bundle adjustment
	SLO-2	Color transforms				
S-6	SLO-1	Histogram equalization	Edge linking	Normalized cuts	Hierarchical motion estimation	Parallax removal
	SLO-2					
S-7	SLO-1	Linear filtering	Successive approximation	Graph cuts and energy-based methods	Fourier-based alignment	Recognizing panoramas
	SLO-2	Non Linear filtering				
S-8	SLO-1	Fourier transforms	Hough transforms	2D and 3D feature-based alignment	Incremental refinement	Compositing
S-9	SLO-1	Two-dimensional Fourier transforms, Wiener filtering	Vanishing points	Pose estimation	Case Study	Case Study

Learning Resources	1. Richard Szeliski, "Computer Vision: Algorithms and Applications", Springer, 2010. 2. Forsyth/Ponce, "Computer Vision: A Modern Approach", Pearson Education India, 2nd edition (2015)	3. S. Nagabhushana, "Computer Vision and Image Processing", New Age International Pvt. Ltd.; First edition (2005) 4. Rafael C. Gonzalez "Digital Image Processing", Pearson Education; Fourth edition (2018)
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
	Dr. A.P. Shanthy , CEG Campus Anna University	1. Dr. V. Ganapathy, SRMIST
		2. T. Senthil Kumar, SRMIST

Course Code	18CSE479T	Course Name	STATISTICAL MACHINE LEARNING	Course Category	E	Professional Elective			
						L	T	P	C
						3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	CSE	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand the Fuzzy Logic Basics				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Gain knowledge on the Machine learning concepts				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Gain knowledge on Fuzzy based clustering concepts																					
CLR-4 :	Acquire knowledge on Fuzzy Integrated classification																					
CLR-5 :	Understanding Neuro-Fuzzy Modeling concepts																					
CLR-5 :	Acquiring better understanding on Fuzzy logic usage																					
CLR-6 :	Understanding the fuzzylogics in Machine learning																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	Acquire the knowledge on statistical machine learning techniques.				1	80	85	H	-	-	-	-	-	-	-	-	-	-	H	H	-	-
CLO-2 :	Acquire the ability to build model based on logistic regression and random forest techniques				1	75	80	H	H	-	-	-	-	-	-	-	-	-	H	H	-	-
CLO-3 :	Understand the basic ideas of probability and work on probabilistic approaches like Naive Bayes, Bayes Theorem				1	85	80	H	-	-	-	-	-	-	-	-	-	-	H	H	-	-
CLO-4 :	Apply the knowledge of Kernel functions in practical applications				3	80	75	H	H	H	H	-	-	-	-	-	-	-	H	H	M	H
CLO-5 :	Apply the knowledge of K-means clustering on real world examples				3	75	85	H	-	H	H	-	-	-	-	-	-	-	H	H	M	H
CLO-6 :	Acquire the knowledge on using PCA and SVD with Scikit-learn				2	80	85	H	-	H	H	-	-	-	-	-	-	-	H	H	M	H

Duration (hour)	9		9		9		9		9	
S-1	SLO-1	Statistical terminology for model building and validation-Machine Learning, Major differences between statistical modeling and machine learning	Comparison between regression and machine learning models		K-nearest neighbors-KNN voter example		Support Vector Machines and Neural Networks-Support vector machines working principles-Maximum margin classifier		K-means clustering-K-means working methodology from first principles	
	SLO-2		Compensating factors in machine learning models		Curse of dimensionality-Curse of dimensionality with 1D, 2D, and 3D example					
S-2	SLO-1	Steps in machine learning model development and deployment	Assumptions of linear regression		Curse of dimensionality with 3D example		Support vector classifier		Optimal number of clusters and cluster evaluation	
	SLO-2		Steps applied in linear regression modeling							
S-3	SLO-1	Statistical fundamentals and terminology for model building and validation	Example of simple linear regression from first principles		KNN classifier with breast cancer Wisconsin data example		Support vector machines		The elbow method	
	SLO-2									
S-4	SLO-1	Bias versus variance trade-off, Train and test data	Machine learning models - ridge and lasso regression-Example of ridge regression machine learning, Example of lasso regression machine learning model		Naive Bayes		Kernel functions		K-means clustering with the iris data example	
	SLO-2									
S-5	SLO-1	Linear regression versus gradient descent	Logistic Regression Versus Random Forest-Maximum likelihood estimation		Probability fundamentals-Joint probability		Artificial neural networks - ANN		Principal component analysis - PCA-PCA working methodology from first principles	
	SLO-2	Machine learning losses								
S-6	SLO-1	When to stop tuning machine learning models	Terminology involved in logistic regression		Understanding Bayes theorem with conditional probability		Forward propagation and backpropagation		PCA applied on handwritten digits using scikit-learn	
	SLO-2		Applying steps in logistic regression modeling							
S-7	SLO-1	Train, validation, and test data Cross-validation	Random forest-Example of random forest using German credit data		Naive Bayes classification		Optimization of neural networks-		Singular value decomposition - SVD	

	SLO-2		Grid search on random forest		Stochastic gradient descent - SGD	
S-8	SLO-1 SLO-2	Grid Search	Variable importance plot	Laplace estimator	Introduction to deep learning- Solving methodology	SVD applied on handwritten digits using scikit-learn
S-9	SLO-1 SLO-2	Machine learning model overview	Comparison of logistic regression with random forest	Naive Bayes SMS spam classification example	Deep learning software	SVD applied on handwritten digits using scikit-learn

Learning Resources	1. Prapat Dangeti, "Statistics for Machine Learning": Packt Publishing Ltd., 2017. 2. Masashi Sugiyama, "Introduction to Statistical Machine Learning", Elsevier, 2016 3. Gareth James, Daniela Witten, Trevor Hastie and Robert Tibshirani, An Introduction to Statistical Learning with Applications in R, Springer, 2015 4. Hastie Trevor, The Elements of Statistical Learning: Data Mining, Inference, and Prediction, Springer-Verlag New York Inc, February 2009
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50%)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Understand										
	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Analyze										
	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. Harisekharan, CTO, Sri Seshaa Technologies Pvt. Ltd., Chennai	1. Dr. Bagavandas, Centre for Statistics, SRMIST	1. Dr. G. Vadivu
2. Mr. S. Sudarsun – Chief Scientist, Co-Founder, Buddhhealth	2. Dr. Sampath, Professor, Department of Statistics, Madras University	2. Dr. C. Lakshmi
		3. Dr. G. Manju

Course Code	18CSE480T	Course Name	NATURE INSPIRED COMPUTING TECHNIQUES	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	To Understand the basics of Natural systems			Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	To appreciate the concepts of Natural systems and its applications						Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3			
CLR-3 :	To understand newBasic Natural systems functions(operations)						L	H	L	H	L	L	M	L	L	L	M	L	L	L	L			
CLR-4 :	To understand the fundamentals of nature inspired techniques which influence computing						L	H	L	H	L	L	M	L	L	L	M	L	L	L	L			
CLR-5 :	To understand an Integration of Hardware and software in Natural applications.						L	H	L	H	L	L	M	L	L	L	M	L	L	L	L			
CLR-6 :	To Understand practical implementation of Natural design considerations.						L	H	L	H	L	L	M	L	L	L	M	L	L	L	L			
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1 :	Illustrate the basic concepts of Swarm Intelligenceprocesses			3	80	70	L	H	L	H	L	L	M	L	L	L	M	L	L	L	L	L	L	
CLO-2 :	Examine the principle of Immuno computing techniques			3	85	75	L	H	L	H	L	L	M	L	L	L	M	L	L	L	L	L	L	
CLO-3 :	Skills for planning, estimating, and resourcing for Natural design considerations			3	75	70	L	H	L	H	L	L	M	L	L	L	M	L	L	L	L	L	L	
CLO-4 :	Manage the scope changes of nature inspired techniques which influence computing			3	85	80	L	H	L	H	L	L	M	L	L	L	M	L	L	L	L	L	L	
CLO-5 :	Ability to identify optimization Techniques as a means to provide functionality and value to apply context in specific case studies			3	85	75	L	H	L	H	L	L	M	L	L	L	M	L	L	L	L	L	L	
CLO-6 :	Ability to understand the needs and familiarize the DNA Computing			3	80	70	L	H	L	H	L	L	M	L	L	L	M	L	L	L	L	L	L	

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction	Evolutionary Computing	Swarm Intelligence	Introduction to Immune System	DNA Computing
	SLO-2	Overview of Philosophy		Introduction		
S-2	SLO-1	Nature to Nature Computing	Hill Climbing	Ant Colony Optimization	Physiology and main components	DNA Molecule
	SLO-2			Ant Foraging Behavior		
S-3	SLO-1	A Brief Overview of Three Branches	Simulated Annealing	Ant Colony Optimization	Pattern Recognition and Binding	Adleman's experiment
	SLO-2	Individuals, Entities and agents		SACO algorithm		
S-4	SLO-1	Parallelism and Distributivity Interactivity	Simulated Annealing	Ant Colony Algorithm (ACA)	Immune Network Theory	PAM Model
	SLO-2				Danger Theory	
S-5	SLO-1	Adaptation- Feedback	Genetics Principles	scope of ACO algorithms	Immune Algorithms	Splicing Systems
	SLO-2					
S-6	SLO-1	Self-Organization	Standard Evolutionary Algorithm	Swarm Robotics	Genetic algorithms	From Classical to DNA Computing
	SLO-2	Complexity, Emergence	Genetic Algorithms			
S-7	SLO-1	Bottom-up Vs Top-Down Approach	Reproduction	Social Adaptation of Knowledge	Bone Marrow Models	Universal DNA Computers
	SLO-2		Crossover Mutation			
S-8	SLO-1	Determination	Evolutionary Programming	Particle Swarm Optimization	Forest's Algorithm	Scope of DNA Computing
	SLO-2					
S-9	SLO-1	Chaos and Fractals	Genetic Programming	Particle Swarm Optimization	Artificial Immune Networks	Lipton's Solution to SAT Problem
	SLO-2					

Learning Resources	1. Leandro Nunes de Castro, "Fundamentals of Natural Computing, Basic Concepts, Algorithms and Applications", Chapman & Hall/CRC, Taylor and Francis Group, 2007. 2. Floreano D. and Mattiussi C., "Bio-Inspired Artificial Intelligence: Theories, Methods, and Technologies", MIT Press, Cambridge, MA, 2008.	3. Albert Y. Zomaya, "Handbook of Nature-Inspired and Innovative Computing", Springer, 2006 4. Marco Dorigo, Thomas Stutzle, "Ant Colony Optimization", PHI, 2005.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50%)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Lokesh Peta, Head Developer, OEConnection, Newbury-UK; Mail: peta.lokesh@gmail.com	Prof. A. Amuthan, Professor, Pondicherry Engineering College, amuthan@pec.edu	Dr. G. Maragatham / Mr. C. Santhana Krishnan Dr. C. Lakshmi

Course Code	18CSE481T	Course Name	APPLIED MACHINE LEARNING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18CSE392T	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	CSE	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Analyze the text data using Machine Learning	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2 :	Analyze the audio data using Machine Learning																							
CLR-3 :	Analyze Time series and Sequential data using Machine Learning																							
CLR-4 :	Analyze the Image Content using Machine Learning																							
CLR-5 :	Visualize the data																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1 :	Identifying patterns in text using topic modeling	3	75	80																				
CLO-2 :	Building a speech recognizer	3	75	80																				
CLO-3 :	Extracting statistics from time series data, Building Conditional Random Fields for sequential text data	3	75	80																				
CLO-4 :	Building an object recognizer	3	75	80																				

Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
H	M	H	-	H	-	-	-	-	-	-	H	H	H	H
H	M	H	-	H	-	-	-	-	-	-	H	H	H	H
H	M	H	-	H	-	-	-	-	-	-	H	H	H	H
H	M	H	-	H	-	-	-	-	-	-	H	H	H	H

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Text Feature Engineering Introduction	Speech Recognition Introduction	Dissecting Time Series and Sequential Data	Image Content Analysis	Biometric Face Recognition
	SLO-2	Cleaning text data	Reading audio data	Introduction	Computer Vision	Face detection from the image and video
S-2	SLO-1	Preprocessing data using tokenization	Plotting audio data	Transforming data into the time series format Pandas and Numpy to convert Time Series data	Operating on images using OpenCV- Python	Capturing and processing video from a webcam Resizing and Scaling
	SLO-2	Tagging and categorising words	Transforming audio signals into the frequency domain	Plotting time series data	Learn to extract and load the image	Building a face detector using Haar cascades
S-3	SLO-1	Sequential tagging, Backoff tagging	Apply Fourier transform signal and plot	Slicing time series data Operating on time series data	Detecting edges Histogram equalization	determine the location of a face in the video frames captured from the webcam
	SLO-2	Creating features from text data- Stemming,	Generating audio signals with custom parameters	Plotting sliced time series data	Sobel filter, Laplacian edge detector, Canny edge detector	Face detector on the grayscale image
S-4	SLO-1	Lemmatising	Generate the time axis	Operating on time series data	Histogram equalization	Building eye and nose detectors
	SLO-2	Bagging using random forests	Synthesizing music	Extracting statistics from time series data	Visualize gray scale image	Face cascade classifier
S-5	SLO-1	Implementing bag of words	Construct the audio sample -amplitude and frequency	Correlation coefficients	Detecting corners	Visualize eye and nose detector
	SLO-2	Testing prepared data	synthesizer function	Plotting and understanding correlations	Understand the output corner detection image	Performing Principal Components Analysis
S-6	SLO-1	Analyze the results	Extracting frequency domain features	Building Hidden Markov Models for sequential data	Detecting SIFT feature points	PCA in face recognition systems
	SLO-2	Building a text classifier	MFCC and filter bank features	Prepare the Time Series data	SIFT feature detection	Convert the dataset from a five-dimensional set to a two-dimensional set
S-7	SLO-1	Analyzing the sentiment of a sentence	Building Hidden Markov Models	Train Gaussian HMM	Visualize the feature detected image	Kernel Principal Components Analysis
	SLO-2	Implement the sentiment analysis of a sentence	HMM training and prediction	Visualizing the model	Building a Star feature detector	Perform Kernel PCA

S-8	SLO-1	Identifying patterns in text using topic modeling	Building a speech recognizer	Building Conditional Random Fields for sequential text data	Detect features using the Star feature detector	Plot the PCA-transformed data
	SLO-2	Implement identifying patterns in text using topic modeling	MFCC features	CRF Model	Visualize keypoints on the input image	Plot Kernel PCA-transformed data
S-9	SLO-1	Case study- Twitter Data	Case study	Analyzing stock market data using Hidden Markov Models	Creating features using visual codebook and vector quantization	Performing blind source separation
	SLO-2	Case study- Twitter Data	Case study	Train the HMM and visualize	Method to quantize the data points	Independent Components Analysis

Learning Resources	1. Prateek Joshi and co, Python: Real World Machine Learning, Packt Publishing, 2016 2. Sebastian Raschka, Python Machine Learning, Packt Publishing, 2013.	3. Richert Coelho, Building Machine Learning Systems with Python, Packt Publishing, 2016 4. Michael Bowles, Machine Learning in Python, Wiley & Sons, 2015
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember										
	Understand	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Apply										
	Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Evaluate										
	Create	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Dr. Harisekharan, CTO, Sri Seshaa Technologies Pvt. Ltd., Chennai	Dr. J. Suresh, SSN College of Engineering	1. Dr. G. Vadivu
Mr. S. Sudarsun – Chief Scientist, Co-Founder, Buddhealth	Dr. Sharmila Shankar, Crescent Institute of Science and Technology	2. Mr. Karthik Nanmaran
		3. Dr. Renukadevi

Course Code	18CSE482T	Course Name	COMPUTATIONAL NEUROSCIENCE	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science & Engg	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Understand to knowWhat happens in your brain when you make a decision	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Gain knowledge mathematical and computational models that are used in the field of theoretical neuroscience	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Basics of adaptively and learning.	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Acquire knowledge on Basic models of cognitive processing.	Expected Attainment (%)	Design & Development
CLR-5 :	Acquire knowledge on implementation model for neuro models		Analysis, Design, Research
CLR-6 :	Acquire knowledge on various computational algorithm		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	To Design Models of single neurons , and small networks	3 80 70	L H L H H - - - L L - H L H H
CLO-2 :	Implementation of all simple as well as more complex numerical computations with few neurons.	3 85 75	H H L M L - - - M L - H L H H
CLO-3 :	Analyse connected networks in the mean-field limit	3 75 70	H H M H L - - - M L - H L H H
CLO-4 :	Formalize biological facts into mathematical models	3 85 80	M H M H L - - - M L - H L H H
CLO-5 :	Understand a simple mathematical model of memory formation in the brain	3 85 75	H H M H L - - - M L - H L H H
CLO-6 :	Understand a simple mathematical model of decision processes	3 80 70	L H - H L - - - L L - H L H H

Duration (hour)	9	9	9	9	9
S-1	SLO-1 History of Computational Neuroscience	Four components of Neural Signaling	From artificial neural network to realistic neural networks - Introduction	Memory Classification Scheme – Declarative, Non-declarative	Hebbian Learning-Hebbian versus Perceptron Learning-
	SLO-2 Models in Computational Neuroscience	Four components of Neural Signaling	Modelling the ventral stream	Auto-associative network and hippo campus - Learning and retrieval phase	Learning by Error Minimization
S-2	SLO-1 Computational Theory of the Brain	Neurotransmission	Modelling the dorsa and auditory stream	Point-attractor neural networks - Network dynamics and training	Gradient Descent Learning
	SLO-2 Biological Background	Population dynamics	Mechanical behavior of ceramics-flexural strength -The Perceptron .	Signal-to-noise analysis - Noisy weights and dilued attractor networks	Stabilizing Hebbian Learning
S-3	SLO-1 Basic synaptic mechanisms and dendritic processing	Modeling the average behavior of neurons	Mapping function	Sparse attractor neural networks and correlated patterns-Sparse patterns and expansion recoding	Principal Component Analysis (PCA)- Eigenvectors-Eigenvalues- Covariance matrix
	SLO-2 The generation of action potentials	Hodgkin	Multi-layer Perceptron	Control of sparseness in attractor networks	Singular Value Decomposition
S-4	SLO-1 Stimulation and rising phase	Modeling the average behavior of neurons	Back-propagation – Initution , Derivation	Chaotic networks-Attractors	Limits and Extensions of PCA
	SLO-2 Peak and falling phase	Huxley Model	Back-propagation –Loss Function	Lyapunov functions - The Cohen-Grossberg theorem	Variations of Hebbian Learning
S-5	SLO-1 After hyperpolarization and Refractory Period	Spiking neuron models - Single	Back-propagation – Limitation	Asymmetrical networks	Nonlinear Hebbian learning
	SLO-2 Hodgkin and Huxley equations - Intro	Spiking neuron models - Detailed	Support Vector Machines - Introduction	Non-monotonic networks	Linsker's Model of the Visual System
S-6	SLO-1 Neuron - axons,dendritesetc, thefour components ofNeural Signaling	Spiking neuron models – 2D Model	Support Vector Machines - Classification	Complementary memory systems	Application of Lateral Inhibition
	SLO-2 Neurotransmission:neurotrasmmitter,rec epto r, ionchannel, channelgating	Integrate and firing model -Leaky integrate-and-fire model	Support Vector Machines - Regression	Distributed model of working memory- Limited capacity of working memory	Lateral Geniculate Nucleus

S-7	SLO-1	Electrophysiology -Nemst potential,resting potential,Goldman-Hodgkin-Katz voltage equation, outline of the Hodgkin- Huxley model.	Integrate and firing model -Nonlinear integrate-and-fire model	Support Vector Machines – Kernel Function	The spurious synchronization hypothesis	Striate Cortex
	SLO-2	Modeling ion1 channel kinetics,activation and inactivation gates	Integrate and firing model -Stimulation by synaptic currents	Self-organizing Maps - Introduction	The interacting-reverberating-memory hypothesis	Linsker's model for orientation columns
S-8	SLO-1	Complete formulation of Hodgkin-Huxley model. Relation between output firing and constant input current. Discussion of regimes. Software demo.	noise in spiking neuron model – part I	Self-organizing Maps - Variable	Motor Learning and Control	Reinforcement Learning -Elements of Reinforcement Learning
	SLO-2	Compartmental models: Cable theory	noise in spiking neuron model – part II	Self-organizing Maps - Algorithm	Feedback controller	Markov decision process-Dynamic programming algorithms for solving MDPs
S-9	SLO-1	Compartmental models: Cable theory – Cable Equation	compartmental modeling - I	Self-organizing Maps – SOM Initialization	Forward and inverse model controller	Algorithms for large state spaces
	SLO-2	Physical Shape of Neurons and Neuron Simulators	compartmental modeling -II	Self-organizing Maps – Kohonen Algorithm	The cerebellum and motor control	Gradient temporal difference learning

Learning Resources	<ol style="list-style-type: none"> 1. Thomas Trappenberg, "Fundamentals of Computational Neuroscience", Oxford University Press, January 2010 2. Peter Dayan & LF Abbot, "Theoretical Neuroscience: Computational and Mathematical Modeling of Neural Systems", MIT Press, 2005 3. Richard S. Sutton and Andrew G. Barto, "Reinforcement Learning-An Introduction", 2nd Edition, The MIT Press, 2018
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#		Theory	Practice
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice		
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
Total		100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
<ol style="list-style-type: none"> 1. Mr.Venkatesan venkatesan.g@tcs.com 2. Ganesan, Associate Consultant Tata Consultancy Services Australia 	Dr.Sarulatha.K , Pondicherry Engg college, charuladha@pec.edu.in / Prof. Godfrey Winster, Saveetha Engineering College, godfreywinster@saveetha.ac.in	1. Dr. G.Maragatham / Dr. C.Vijayakumaran

Course Code	18CSE483T	Course Name	INTELLIGENT MACHINING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	CSE	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:		Learning			Program Learning Outcomes (PLO)																	
CLR-1 :	Understand the fundamentals of Artificial Intelligence			Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Learn basics of Intelligent machining, sensors and machining process						Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3			
CLR-3 :	Understand the design of Intelligent Systems - RTOS						-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-		
CLR-4 :	Understand the computational methods, optimization and reasoning about physical system						H	H	H	H	H	-	-	-	-	-	-	-	H	-	-	-		
CLR-5 :	Understand implications of Artificial Intelligence in various real time applications						-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-		
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1 :	Acquire the knowledge on the fundamentals of Artificial intelligence and its problem solving approaches			2	80	85	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-2 :	Acquire the knowledge on fundamentals of Intelligent Machining and machining process			2	75	80	H	H	H	H	H	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-3 :	Acquire knowledge on the design of Intelligent Systems and RTOS			2	85	80	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-4 :	Acquire knowledge on computational methods and optimization			2	80	75	-	H	-	-	H	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-5 :	Apply the knowledge on Real time applications			2	75	85	-	H	-	-	H	-	-	-	-	-	-	-	-	-	-	-	-	-

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Introduction to Artificial Intelligence and its techniques	Introduction Intelligent Machining, Basics	Representation of Intelligent systems	Computational methods and optimization	Case Study - Autonomous Vehicle (Driver Less Car)
	SLO-2 Problem Solving with Artificial Intelligence	Open Architecture Machine Control	Control for the Evolution of VLSI Designs		
S-2	SLO-1 AI Models, Data acquisition and learning aspects of AI	Manufacturing Automation Protocol	An Object-Oriented Approach	Neural Network Modelling	Case Study - Defect Prediction , Wear and Tear Prediction in Mechanical devices
	SLO-2 Problem Solving - Problem Solving Process, Formulating Problems	The Evolution of Intelligent Machining			
S-3	SLO-1 Problem types and Characteristics	MOSAIC - NGC	Tools and Techniques for Conceptual Design	Fuzzy set theory	Case Study - Flying Drones
	SLO-2 Problem Space and Search	OSACA - SERCOS	Design Compilers		
S-4	SLO-1 Intelligent Agent	Components of Intelligent Machining	Labelled Interval Calculus	Machining Optimization	Case Study - Cogito
	SLO-2 Rationality and Rational agent with performance measures	Introduction sensors - Machining Process	Knowledge Representations for Design Improvisation		
S-5	SLO-1 Flexibility and Intelligent Agents	Sensing and Monitoring	A knowledge-based Framework for Design	Objective Functions and Constraints	Case Study - Alexa , SIRI
	SLO-2 Task Environment and its Properties	Signal Processing		Optimization Techniques	
S-6	SLO-1 Types of Agents	Transforming Data into Information - Examples	Introduction to RTOS - Hardware Components	Reasoning about physical system	Case Study - Smarter Home robots
	SLO-2 Other aspects of agents	Machining Process Control			
S-7	SLO-1 Constraint satisfaction problem (CSP)	Practical Uses of Machine Learning	Design Principles of RTOS - Interrupt Processing - task Management	Temporal Qualitative Analysis	Case Study -Application of AI in CAD/CAM
	SLO-2 Crypto Arithmetic puzzles	Machine Learning Process Control Strategies			

S-8	SLO-1	CSP as a search problem-constraints and representation	Programmable Logic Controllers (PLC)	Task Scheduling -Synchronization tools	Reasoning about Geometry	Case Study - Streamlining Drug Discovery
	SLO-2	CSP- backtracking and Role of heuristic	Closed Loop Process Control Systems	Task Communication - Memory Management		
S-9	SLO-1	CSP - Forward Checking and constraint propagation	Introduction to Adaptive Control	File System	Study of Heuristic knowledge for automatic configuration Generation and Innovation	Case Study - Betterment (Financial Advisor)
	SLO-2	CSP-Intelligent backtracking	Commercially Available Software	Tracing and Debugging		

Learning Resources	1. Farid Meziane, Sunil Vadera, Khiary Kobbacy and Nathan Proudlove, "Intelligent Systems in Manufacturing: Current Developments and Future Prospects", (unit 1)	5. K.C.Wang, " Embedded and Real-Time Operating Systems (Chapter 10.6- Unit 3) 6. Sam Siewert, John Pratt, " Real-Time Embedded Components and Systems with Linux and RTOS", David Pallai Publisher, 2016. (Chapter 8- Unit 3) 7. Machining: Fundamentals and Recent Advances, J. Paulo Davim, Springer. (Chapter 12-unit 4) 8. Artificial Intelligent in Engineering Design: Volume 2 , Gerard Meurant, Springer (Chapter 10-14 - unit 5)
	2. How Netflix Uses Analytics To Select Movies, Create Content, and Make Multimillion Dollar Decisions Author: Zach Bulygo(unit 1) 3. Digital Signal Processing: A Practical Guide for Engineers and Scientists, Steven Smith (unit 2) 4. Artificial Intelligent in Engineering Design: Volume 1 , Gerard Meurant, Springer (Chapter 2,3,5,6,9 - unit3)	

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Dr. Mariappan, Engineering Leader, Amazon, India	Khanna Nehemiah H, Professor, Ramanujam Computing Center, Anna University	1.Dr.C.Lakshmi, SRMIST
		2. Dr.S.Prabakaran, SRMIST
		3. Dr. M. Thenmozhi, SRMIST

Course Code	18CSE484T	Course Name	DEEP LEARNING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1:	Understand the concepts of Neural Networks and Deep Learning	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2:	Understand Deep neural network and layered learning approach	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3:	Study and understand CNN and RNN for deep learning	Expected Proficiency (%)	Problem Analysis
CLR-4:	Learn and understand Auto Encoders and its applications	Expected Attainment (%)	Design & Development
CLR-5:	Understand concept of transfer learning and its applications with keras		Analysis, Design, Research
			Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1:	Apply basic mathematical concepts in Deep Learning	2 80 85	H L - - H - - - - - H H - -
CLO-2:	Work with powerful framework for supervised learning	3 75 80	H H - - H - - - - - H H H M
CLO-3:	Deal with Convolution Neural Networks	2 85 80	H H H - H - - - - - H H H H
CLO-4:	Analyze various types efficient data encoders	2 80 75	H H - - H - - - - - H H H H
CLO-5:	Apply various network models in deep learning	3 75 85	H H H H H - - - - - H H H H

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Historical trends in deep learning – Machine Learning basics	Introduction to Simple DNN	Convolution Neural Networks Introduction	Encoder	Deep Architectures in Vision
	SLO-2 Learning algorithms – Supervised and Unsupervised Training	Platform for Deep Learning	Convolution Operation	Decoder	AlexNet to ResNet
S-2	SLO-1 Linear Algebra for machine learning	Deep Learning Software Libraries	Motivation	Auto Encoders Introduction	Transfer Learning
	SLO-2 Testing - Cross Validation	Deep Feed Forward Networks Introduction	Pooling	Auto Encoders	
	SLO-1 Dimensionality Reduction	Learning XOR	Normalization	Under Complete Auto Encoder	
S-3	SLO-2 Over fitting /Under Fitting	Gradient-Based Learning	Applications in Computer Vision - ImageNet	Regularized Auto Encoder	Siamese Networks
S-4	SLO-1 Hyper parameters and validation sets	Various Activation Functions, ReLU, Sigmoid – Error Functions	Sequence Modelling –VGGNet, LeNet	Stochastic Auto Encoder	Metric Learning
	SLO-2 Estimators – Bias - Variance	Architecture Design	Recurrent Neural Networks	Denoising Auto Encoder	Ranking / Triplet Loss
S-5	SLO-1 Loss Function-- Regularization	Differentiation Algorithms	RNN topologies- Difficulty in Training RNN	Contractive Auto Encoder	
	SLO-2 Biological Neuron – Idea of Computational units	Regularization methods for Deep Learning		Auto Encoder Applications	RCNNs with keras
S-6	SLO-1 McCulloch-Pitts units and Thresholding logic	Early Stopping	Long Short Term Memory	Dimensionality Reduction and Classification using Auto encoders	CNN-RNN
	SLO-2 Linear Perceptron	Drop Out		Recommendation	
S-7	SLO-1 Perceptron Learning Algorithm	Difficulty of training deep neural networks	Bidirectional LSTMs	Optimization for Deep Learning-Optimizers–RMS prop for RNNs	Applications in captioning and Video tasks
	SLO-2 Convergence theorem for Perceptron Learning Algorithm				
S-8	SLO-1 Linear Separability	Greedy layer wise training	Bidirectional RNNs	SGD for CNNs	3D CNNs
	SLO-2 Multilayer perceptron –The first example of network with Keras code				
S-9	SLO-1 Backpropagation	Optimization methods for Neural Networks-Adagrad, Adam	Application case study -Handwritten digits recognition using deep learning, LSTM with Keras – sentiment Analysis	Application case study – Image dimensionality reduction using encoders LSTM with Keras – sentiment Analysis	Application case study – Image recognition using RCNN and transfer learning

Learning Resources	1. <i>Ian Goodfellow, Yoshua Bengio, Aaron Courville, "Deep Learning", MIT Press, 2016.</i>	3. <i>Neural Networks: A Systematic Introduction, Raul Rojas, 1996.</i>
	2. <i>Kevin P. Murphy, "Machine Learning: A Probabilistic Perspective", MIT Press, 2012.</i>	4. <i>Christopher and M. Bishop, "Pattern Recognition and Machine Learning", Springer Science Business Media, 2006.</i> 5. <i>Jason Brownlee, "Deep Learning with Python", ebook, 2016.</i>

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1.	1.	1. <i>Dr.E.Poovammal</i>
2.	2.	2. <i>Dr.G.Vadivu</i>
		3. <i>Mr.Joseph James</i>

Course Code	18CSE485T	Course Name	ROBOTICS: COMPUTATIONAL MOTION PLANNING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:
CLR-1:	Acquire knowledge of Bug algorithms and configuration Space
CLR-2:	Acquire knowledge of Potential functions and Navigations
CLR-3:	Acquire knowledge of Sampling Algorithms
CLR-4:	Gain knowledge of filtering techniques
CLR-5:	Gain knowledge about Trajectory and Motion Planning
CLR-6:	Design motion plan for Robot in the path specified

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:
CLO-1:	Apply knowledge of Bug algorithms and configuration Space
CLO-2:	Apply knowledge of Potential functions and Navigations
CLO-3:	Apply knowledge of Sampling Algorithms
CLO-4:	Gain knowledge of filtering techniques
CLO-5:	Gain knowledge about Trajectory and Motion Planning

Learning		
1	2	3
Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)
3	80	70
3	85	75
3	75	70
3	85	80
3	85	75

Program Learning Outcomes (PLO)														
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
M	H	-	H	L	-	-	-	L	L	-	H	-	-	-
M	H	L	M	L	-	-	-	M	L	-	H	-	-	-
M	H	M	H	L	-	-	-	M	L	-	H	-	-	-
M	H	M	H	L	-	-	-	M	L	-	H	-	-	-
H	H	M	H	L	-	-	-	M	L	-	H	-	-	-

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Over view of Motion Planning	Potential Function: Addictive Attractive/Repulsive Potential	Sampling - Based Algorithms- Probabilistic Road Maps: Basic PRM	Linear Kalman Filtering	Trajectory Planning : Preliminaries
	SLO-2	Bug1 And Bug 2	Gradient Descent	Implementation of basic PRM		
S-2	SLO-1	Tangent Bug	Computing Distance From Implementation In The Plane	PRM sampling Strategies	Kalman Filter : Example	Decoupled Trajectory Planning
	SLO-2	Implementation: The Tangent Line		PRM connection Strategies		
S-3	SLO-1	Distance On Gradient	Local Minima Problem	Single-Query Sampling Based Planners: Expensive Spaces Trees	Bayesian Methods : Localization	Direct Trajectory Planning: Optimal Control
	SLO-2	Continuation Method	Wave-Front Planner	Rapidly Exploring Random Trees	Basic Idea Probabilistic Localization	Nonlinear Ptimization
S-4	SLO-1	Robot Configuration Specification	Navigation Potential Function: Sphere- Space	Connection Strategies and SBL Planner	Probabilistic Localization As Recursive Bayesian Filtering	Grid-Based Search
	SLO-2		Star-Space			
S-5	SLO-1	Circular Mobile Robot	Potential Functions for Rigid-Body Robots	Integration Of Planners Sampling Based Roadmap	Derivation Of Probabilistic Localization	Nonholonomic And Underactuated Systems : preliminaries Control Systems
	SLO-2	Two joint planer arm	Path Planning for Articulated Bodies			
S-6	SLO-1	Dimension Of The Configuration Space	Visibility Graph	Analysis Of PRM	Representation Of Posterior	Controllability
	SLO-2					
S-7	SLO-1	Topology of configuration space: Homeomorphisms and Diffeomorphisms	Deformation Retracts : Generalized Voronoi Diagram	Control based Planning	Sensor Model	Motion Planning: Optimal Control
	SLO-2			Multiple Robots		
S-8	SLO-1	Differentiable Manifolds	Retract -Like Structure: Generalized Voronoi Graph	Manipulation Planning	Mapping:: Mapping with known locations	Steering Chained -Form Systems Using Sinusoids
	SLO-2					
S-9	SLO-1	Examples	Piecewise Retracts: The Rod Hierarchical Generalized Voronoi GraphSilhouette Methods	Assembly Planning	Bayesian Simultaneous Localization and Mapping	Nonlinear Optimization
	SLO-2					

Learning Resources	1. <i>Howie M. Choset, Seth Hutchinson, Kevin M. Lynch, George Kantor, Wolfram Burgard, Lydia E. Kavraki, Sebastian Thrun, "Principles of Robot Motion: Theory, Algorithms, and Implementation"</i> 2. <i>Jean-Claude Latombe, "Robot Motion Planning", Springer Science & Business Media, 2012</i>	3. http://robotics.stanford.edu/~latombe/cs326/2009/schedule.htm
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50%								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
		<i>Dr.R. Annie Uthra</i>
		<i>Dr.P. Supraja</i>

Course Code	18CSE486T	Course Name	ADVANCED ALGORITHMS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18CS201J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand different asymptotic notations to analyze an algorithms	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Utilize various data structures in developing applications	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Utilize stack and queues in processing data for real-time applications																		
CLR-4 :	Understand various data structures to handle graph theory related real-time applications																		
CLR-5 :	Understand various probabilistic algorithms and randomized algorithms for real-time programming applications																		
CLR-6 :	Understand various Complexity classes like P-Type, NP-Type, NP-Complete, NP-Hard problems																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Understand complexity of various algorithms	3	80	70	L	H	-	H	L	-	-	-	L	L	-	H	-	-	-
CLO-2 :	How efficiently a problem can be solved with respect to time and space	3	85	75	M	H	L	M	L	-	-	-	M	L	-	H	-	-	-
CLO-3 :	To find the appropriateness of Data structure for real time applications	3	75	70	M	H	M	H	L	-	-	-	M	L	-	H	-	-	-
CLO-4 :	Representation and Solving Graph algorithms	3	85	80	M	H	M	H	L	-	-	-	M	L	-	H	-	-	-
CLO-5 :	Understand approximation methods to solve very difficult problems	3	85	75	H	H	M	H	L	-	-	-	M	L	-	H	-	-	-

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Introduction-Basic Terminology	Elementary data structures-Array	Graph algorithms-Representation of graphs	Approximation algorithms
	SLO-2	Complexity of algorithms- Space and time complexity issues-Growth of functions	Operations on Arrays – Insertion and Deletion	BFS-DFS	The vertex-cover problem
S-2	SLO-1	Introduction of various asymptotic notations like $\Theta, \omega, O, \Omega$	Stack-Variou ADT operations- Uses of stack-Variou examples	Strongly connected components	The traveling-salesman problem
	SLO-2	Designing algorithm-Analysis of Insertion sort-Best case, worst case, average case analysis	Queue ADT- Insertion-deletion and various operations on Queue	Minimum Spanning tree-Introduction Prim's algorithm	Example
S-3	SLO-1	Various Problem solving techniques	Linked List- Deletion and Search-Doubly linked list-Variou operations on linked list	Kruskal algorithm	The set-covering problem –With an example
	SLO-2	Divide and Conquer paradigm	Polynomial Arithmetic	Single source Shortest path problem	The subset-sum problem
S 4-5	SLO-1	Recurrence relations-Construction of recurrence relation for various examples- Towers of Hanoi Problem, Fibannacci series	Hashing-Hash functions Open addressing- Perfect Hashing	The Bellman-Ford algorithm - Single-source shortest paths in directed acyclic graphs -Dijkstra's algorithm	String Matching- The naive string-matching algorithm
	SLO-2				
S-6	SLO-1	Solution by Substitution method	Various hashing methods	Shortest paths and matrix multiplication	Example
	SLO-2	Recursion Tree Method	Collision in hashing-Avoiding Collision – Variou methods	The Floyd-Warshall algorithm	The Rabin-Karp algorithm
S-7	SLO-1	Mater Theorem-Proof	Binary search tree	An example	Continued
	SLO-2	Simple examples	Insertion-Deletion-Finding max,min	Johnson's algorithm for sparse graphs	The Knuth-Morris-Pratt algorithm
S-8	SLO-1	Probabilistic analysis of an algorithm	Red Black tree	Example	NP-completeness proofs Continued-Satisfiability of boolean formulas is NP-complete.

	SLO-2	Hiring assistant problem	Insertion-Deletion	Flow network-example	Computational Geometry- Finding Convex hull- Finding the closest pair of points	3-CNF satisfiability problem-NP Complete
S-9	SLO-1	Probabilistic analysis Quick sort with illustration	Properties of RBT	Continued	Continued	NP-Hard problem-Definition and various examples-continued
	SLO-2					

Learning Resources	1. Cormen, Thomas H.; Leiserson, Charles E.; Rivest, Ronald L.; Stein, Clifford (2009) Introduction to Algorithms (3rd ed.). MIT Press and McGraw-Hill 2. Ananyevskiy, Introduction to the Design and Analysis of Algorithms, Kindle edition 2017. 3. Harowitz, Sahani and Sangudevar Rajasekaran, Fundamentals of computer algorithm, Universities Press; Second edition 2008					4. Mark Allen Weiz, Data structures and algorithm analysis, Pearson Education India 2012
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50%)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Understand										
	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Analyze										
	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
	1. Dr.Masila Mani.V IIITDM, Kancheepuram, noor@iiitdm.ac.in	1. K..Senthil Kumar, SRMIST
		2. Dr.Thenmozhi, SRMIST

Course Code	18CSE355T	Course Name	DATA MINING AND ANALYTICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	CSE	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand the concepts of Data Mining	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Familiarize with Association rule mining	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Familiarize with various Classification algorithms																		
CLR-4 :	Understand the concepts of Cluster Analysis																		
CLR-5 :	Familiarize with Outlier analysis techniques																		
CLR-6 :	Familiarize with applications of Data mining in different domains																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Gain knowledge about the concepts of Data Mining	2	80	85															
CLO-2 :	Understand and Apply Association rule mining techniques	2	75	80															
CLO-3 :	Understand and Apply various Classification algorithms	2	85	80															
CLO-4 :	Gain knowledge on the concepts of Cluster Analysis	2	80	75															
CLO-5 :	Gain knowledge on Outlier analysis techniques	2	75	85															
CLO-6 :	Understand the importance of applying Data mining concepts in different domains	2	80	85															

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Why Data mining? What is Data mining ?	Mining frequent patterns: Basic concepts	Classification: Basic concepts	Cluster Analysis: Introduction
	SLO-2	Kinds of data meant for mining	Market Basket Analysis	General approach to Classification	Requirements and overview of different categories
S-2	SLO-1	Kinds of patterns that can be mined	Frequent itemsets, Closed itemsets	Decision tree induction	Partitioning method: Introduction
	SLO-2	Applications suitable for data mining	Association rules-Introduction	Algorithm for Decision tree induction	k-means
S-3	SLO-1	Issues in Data mining	Apriori algorithm-theoretical approach	Numerical example for Decision tree induction	k-medoids
	SLO-2	Data objects and Attribute types	Apply Apriori algorithm on dataset-1	Attribute selection measure	Hierarchical method: Introduction
S-4	SLO-1	Statistical descriptions of data	Apply Apriori algorithm on dataset-2	Tree pruning	Agglomerative vs. Divisive method
	SLO-2		Generating Association rules from frequent itemsets	Scalability and Decision tree induction	Distance measures in algorithmic methods
S-5	SLO-1	Need for data preprocessing and data quality	Improving efficiency of Apriori	Bayes' Theorem	BIRCH technique
	SLO-2			Naive Bayesian Classification	
S-6	SLO-1	Data cleaning	Pattern growth approach	IF-THEN rules for classification	DBSCAN technique
	SLO-2	Data integration		Rule extraction from a decision tree	
S-7	SLO-1	Data reduction	Mining frequent itemsets using Vertical data format	Metrics for evaluating classifier performance	STING technique
	SLO-2		Strong rules vs. weak rules	Cross validation	
S-8	SLO-1	Data transformation	Association analysis to Correlation analysis	Bootstrap	CLIQUE technique
	SLO-2			Ensemble methods-Introduction	
S-9	SLO-1	Data cube and its usage	Comparison of pattern evaluation measures	Bagging and Boosting	Evaluation of clustering techniques
	SLO-2			Random Forests: Introduction	

Learning Resources	1. Jiawei Han and Micheline Kamber, "Data Mining: Concepts and Techniques", 3 rd Edition, Morgan Kauffman Publishers, 2011.	
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.V.Selvakumar, Hexaware Technologies, selvakumarv@hexaware.com	1. Dr.Latha Parthiba, Pondicherry University, lathaparthiban@yahoo.com	1. Mr.L.N.B.Srinivas, SRMIST
2.	2.	2. Mr.S.Karthick, SRMIST
		3. Dr.V.V.Ramalingam, SRMIST

Course Code	18CSE391T	Course Name	BIG DATA TOOLS AND TECHNIQUES	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1:	Gain knowledge about the various tools and techniques used in big data analytics	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2:	Learn the fundamentals of Hadoop and the related technologies	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3:	Understand the basics of development of applications using MapReduce, HDFS, YARN	Expected Proficiency (%)	Problem Analysis
CLR-4:	Learn the basics of Pig, Hive and Sqoop	Expected Attainment (%)	Design & Development
CLR-5:	Learn the basics of Apache Spark, Flink and understand the importance of NoSQL databases		Analysis, Design, Research
CLR-6:	Learn about Enterprise Data Science and data visualization tools		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1:	Use the various tools and techniques in big data analytics	2 80 85	L - H - H - H - - - - - - - - - -
CLO-2:	Apply Hadoop and related technologies to big data analytics	2 75 80	L H H M H - - - - - - - - - -
CLO-3:	Apply MapReduce, HDFS and YARN develop big data applications	2 85 80	L - H - - H - - - - - - - - - -
CLO-4:	Develop applications using Pig, Hive and Sqoop	2 80 75	L H H - H - - - - - - - - - -
CLO-5:	Apply Apache Spark and Flink to applications and understand the importance of NoSQL databases	2 75 85	L - H M H - - - - - - - - - -
CLO-6:	Understand the applications of Enterprise Data Science and data visualization tools	2 80 85	L - H - H - - - - - - - - - -

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Overview of Big Data Analytics	MapReduce	Setting up a Hadoop cluster	Introducing Oozie	Enterprise Data Science Overview
	SLO-2 Introduction to data analytics and big data	Analyzing data with Unix tools and Hadoop	Cluster specification and setup		
S-2	SLO-1 Big data mining	Scaling Out – Data Flow, Combiner Functions	Hadoop configuration	Apache Spark	Data Science Solutions in the enterprise
	SLO-2 Technical elements of the Big Data platform	Hadoop Streaming	YARN configuration		
S-3	SLO-1 Analytics Toolkit, Components of the analytics toolkit	HDFS	Introduction to Pig	Limitations of Hadoop and overcoming the limitations	Enterprise data science – Machine Learning and AI
	SLO-2 Distributed and Parallel Computing for Big Data		Installing and running pig	Core components and architecture of Spark	Enterprise Infrastructure solutions
S-4	SLO-1 Cloud computing and Big Data	Hadoop filesystems	Basics of Pig Latin	Introduction to Apache Flink	Visualizing Big Data
	SLO-2 Java Interface to Hadoop			Installing Flink	
S-5	SLO-1 In-Memory Computing Technology for Big Data	YARN	Introduction to Hive	Batch analytics using Flink	Using Python and R for visualization
	SLO-2 Data	Job Scheduling	Installing and running Hive		Big Data Visualization Tools
S-6	SLO-1 Fundamentals of Hadoop	Hadoop I/O	Introduction to HiveQL	Big Data Mining with NoSQL	Data Visualization with Tableau
	SLO-2 Hadoop Ecosystem				
S-7	SLO-1 The core modules of Hadoop	Data Integrity	Introduction to Zookeeper	Why NoSQL?	Case Studies: Hadoop
	SLO-2	Compression	Installing and running Zookeeper	NoSQL databases	
S-8	SLO-1 Introduction to Hadoop MapReduce	Serialization	The Zookeeper Service	Introduction to HBase	Case Studies: Spark
	SLO-2	File based Data Structures	Flume Architecture		
S-9	SLO-1 Introduction to Hadoop YARN	Developing a MapReduce Application	Introduction to Sqoop	Introduction to MongoDB, Cassandra	Case Studies: NoSQL
	SLO-2				

Learning Resources	1. TomWhite,Hadoop:The Definitive Guide,3 rd Edition,O'Reilly,2012.	3. NatarajDasgupta,Practical Big Data Analytics,Packt,2018.
	2. Sridhar Alla,Big Data Analytics with Hadoop3,Packt,2018.	4. DTEditorialServices,Big Data:Black Book,2016.

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50%)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts

Course Code	18CSE392T	Course Name	MACHINE LEARNING - I	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	CSE	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	To provide basic concepts of machine learning	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	To provide deeper understanding of various tools and techniques for Machine learning Algorithms and outputs	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Understand and Implement the major classification techniques				H	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLR-4 :	Understand and Implement the various Clustering Methods				H	H	H	-	H	-	-	-	-	-	-	-	-	-	-
CLR-5 :	Learn and Understand the Tree based machine Learning Algorithms				H	H	-	-	H	-	-	-	-	-	-	-	-	-	-
					H	H	-	-	H	-	-	-	-	-	-	-	-	-	-
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Understand the concepts of machine learning	2	80	85	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-2 :	Learn and understand machine tools and libraries of machine learning	2	75	80	H	H	H	-	H	-	-	-	-	-	-	-	-	-	-
CLO-3 :	Learn and understand the linear learning models and classification in machine learning	2	85	80	H	H	-	-	H	-	-	-	-	-	-	-	-	-	-
CLO-4 :	Understand the clustering techniques and their utilization in machine learning	2	80	75	H	H	-	-	H	-	-	-	-	-	-	-	-	-	-
CLO-5 :	Study the tree based machine learning techniques and to appreciate their capability	2	75	85	H	H	-	H	H	-	-	-	-	-	-	-	-	-	-

Duration (hour)	9	9	9	9	9
S-1	SLO-1 SLO-2	Machine Learning: What and Why? Types of Machine Learning	Platform for machine learning Machine learning python libraries	Ridge Regression	Measuring (dis)similarity Evaluating output of clustering methods
S-2	SLO-1 SLO-2	Supervised Learning Unsupervised Learning	Scikit-learn training data – testing data – validation data	Maximum likelihood estimation (least squares)	Spectral clustering Hierarchical clustering
S-3	SLO-1 SLO-2	Reinforcement learning The Curse of dimensionality	k-fold cross validation Features	principal component analysis	Agglomerative clustering Divisive clustering
S-4	SLO-1 SLO-2	Over fitting and under fitting linear regression	Performance metrics MSE, accuracy, confusion matrix, precision	Bayesian classifier	Choosing the number of clusters Clustering datapoints and features
S-5	SLO-1 SLO-2	Bias and Variance tradeoff Testing – cross validation	recall, F- score	Support vector machine	Bi-clustering
S-6	SLO-1 SLO-2	Regularization Learning Curve	Linear Regression with multiple variables	Support vector machine + kernels	Multi-view clustering
S-7	SLO-1 SLO-2	Classification Error and noise	Logistic Regression	Multi class classification	K-Means clustering
S-8	SLO-1 SLO-2	Parametric vs. non-parametric models	spam filtering with logistic regression	K nearest neighbour classification	K-meloids clustering
S-9	SLO-1 SLO-2	Linear Algebra for machine learning	Naive Bayes with scikit-learn	Application: face recognition with PCA	Application: image segmentation using K-means clustering

Learning Resources	1.	Kevin P. Murphy, "Machine Learning: A Probabilistic Perspective", MIT Press, 2012.	4.	Sebastian Raschka, Vahid Mirjalili, "Python Machine Learning and deep learning", 2 nd edition, kindle book, 2018
	2.	Ethem Alpaydin, "Introduction to Machine Learning", Prentice Hall of India, 2005	5.	Carol Quadros, "Machine Learning with python, scikit-learn and Tensorflow", Packet Publishing, 2018.
	3.	Tom Mitchell, "Machine Learning", McGraw-Hill, 1997.	6.	Gavin Hackeling, "Machine Learning with scikit-learn", Packet publishing, O'Reilly, 2018.

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
		Dr.G.Vadivu Dr. UshaKiruthika Mr.S.Joseph James

Course Code	18CSE393T	Course Name	TEXT MINING	Course Category	Professional Elective	L	T	P	C
						3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	CSE	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:		
CLR-1 :	Understand the fundamentals of text mining			
CLR-2 :	Utilize text for prediction techniques			
CLR-3 :	Understand the relevance between information retrieval and text mining			
CLR-4 :	Understand the goals of information extraction			
CLR-5 :	Analyze different case studies related to text mining			

Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:		
CLO-1 :	Acquire knowledge on fundamentals of text mining			
CLO-2 :	Perform prediction from text and evaluate it			
CLO-3 :	Perform document matching			
CLO-4 :	Identify patterns and entities from text			
CLO-5 :	Understand how text mining is implemented			

Learning		
1	2	3
Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)

Program Learning Outcomes (PLO)														
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
H	-	-	-	-	-	-	-	-	-	-	-	-	-	-
H	-	-	-	-	-	-	-	-	-	-	-	-	-	-
H	M	-	-	-	-	-	-	-	-	-	-	-	-	-
H	-	M	-	M	-	-	-	-	-	-	-	-	-	-
H	-	-	-	-	-	-	-	-	-	L	-	-	-	-

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Overview of text mining	Labels for the Right Answers	Linear scoring Methods	Clustering Documents by similarity	Ideal Model of Data
	SLO-2 Special about Text Mining	Feature selection by attribute ranking	Evaluation of Performance	Similarity of composite documents	Practical Data Sourcing
S-2	SLO-1 Structured Data	Sentence Boundary Determination	Estimating current and future performance	K-means Clustering	Prototypical Examples
	SLO-2 Unstructured Data	Part of speech Tagging	Getting the most from a Learning Method	Hierarchical Clustering	Hybrid Example
S-3	SLO-1 Is text different from numbers	Word Sense Disambiguation	Errors and Pitfalls in Big data Evaluation	The EM Algorithm	Mixed Data in Standard Table Format
	SLO-2 Types of Problem can be solved.	Phrase Recognition	Graph models for social Networks	Goals for Information Extraction	Case study: Market Intelligence from the web
S-4	SLO-1 Document Classification	Named Entity Recognition	Information Retrieval and Text Mining	Finding Patterns and Entities from Text	Case Study: Lightweight Document Matching for Digital Libraries
	SLO-2 Informational Retrieval	Parsing	Keyword search	Entity Extraction as Sequential Tagging	Generating Model cases for Help desk Application: case study
S-5	SLO-1 Prediction and Evaluation	Feature Generation	Nearest- Neighbor Methods	Tag Prediction as Classification	Assigning topics to news articles: Case study
	SLO-2 From Textual Information to Numerical Vectors	Using text for prediction	Measuring Similarity	The maximum Entropy method	E-mail Filtering: Case study
S-6	SLO-1 Collecting Documents	Recognizing that document Fit a pattern	Shared Word Count	Linguistic Features and Encoding	SearchEngines : case study
	SLO-2 Document Standardization	Document Classification	Word count and Bonus	Local Sequence Prediction Models	Extracting Named Entities from Documents
S-7	SLO-1 Tokenization	Learning to Predict from Text	Cosine Similarity	Global sequence Prediction Models	Mining Social Media
	SLO-2 Lemmatization	Similarity and Nearest-Neighbor Method	Web based Document Search	Coreference and relationship Extraction	Customized Newspapers
S-8	SLO-1 Inflectional Stemming	Document Similarity	Link Analysis	Template Filling And Database Construction	Emerging Directions
	SLO-2 Stemming to a Root	Decision Rules	Document Matching	Commercial Extraction System: Application	Different ways of collecting samples
S-9	SLO-1 Vector Generation for Prediction	Decision trees	Inverted List	Criminal Justice : Application	Learning to Unlabeled data
	SLO-2 Multiword Features	Scoring by Probabilities	Evaluation of Performance	Intelligence Application	Distributed Text Mining

Learning Resources	1. By Sholom M. Weiss, Nitin Indurkha, Tong Zhang., <i>Fundamentals of Predictive Text Mining</i>	
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
		Dr.E.Poovammal, SRMIST
		Mr.L.N.B.Srinivas, SRMIST
		Mr.D.Vivek, SRMIST

Course Code	18CSE394T	Course Name	BUSINESS INTELLIGENCE AND ANALYTICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	CSE	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Familiarize with Business Intelligence, Analytics and Decision Support				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Understand the technologies for Decision making				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Familiarize with predictive modeling techniques																					
CLR-4 :	Familiarize with sentiment analysis techniques																					
CLR-5 :	Understand about Multi-criteria Decision making systems																					
CLR-6 :	Familiarize with Automated decision systems																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	Gain knowledge on Business Intelligence, Analytics and Decision Support				2	80	85															
CLO-2 :	Understand the technologies for Decision making				2	75	80															
CLO-3 :	Apply predictive modeling techniques				2	85	80															
CLO-4 :	Apply sentiment analysis techniques				2	80	75															
CLO-5 :	Gain knowledge on Multi-criteria Decision making systems				2	75	85															
CLO-6 :	Gain knowledge on Automated decision systems				2	80	85															

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Information Systems Support for Decision Making	Decision Making:	Basic Concepts of Neural Networks	Decision Support Systems modeling	Automated Decision Systems
	SLO-2		Introduction and Definitions	Developing Neural Network	Structure of mathematical models for decision support	The Artificial Intelligence field
S-2	SLO-1	An Early Framework for Computerized Decision Support	Phases of the Decision	Based Systems	Decision making under certainty	Basic concepts of Expert Sysytems
	SLO-2		Making Process	Illuminating the Black Box of ANN with Sensitivity	Uncertainty and Risk	
S-3	SLO-1	The Concept of Decision Support Systems	The Intelligence Phase	Support Vector Machines	Decision modeling with spreadsheets	Applications of Expert Sysytems
	SLO-2			A Process		
S-4	SLO-1	A Framework for Business Intelligence	Design Phase	Based Approach to the Use of SVM	Mathematical programming optimization	Structure of Expert Sysytems
	SLO-2			Nearest Neighbor Method for Prediction		
S-5	SLO-1	Business Analytics Overview	Choice Phase	Sentiment Analysis Overview	Decision analysis-introduction	Knowledge Engineering
	SLO-2					
S-6	SLO-1	Brief Introduction to Big Data Analytics	Implementation Phase	Sentiment Analysis Applications	Decision tables	Development of Expert Sysytems
	SLO-2					
S-7	SLO-1	Clickstream Analysis	Decision Support SystemsCapabilities	Sentiment Analysis Process	Decision Trees	Location based Analytics
	SLO-2	Metrics				
S-8	SLO-1	Clickstream Analysis	Decision Support SystemsClassification	Sentiment Analysis	Multi-criteria decision making	Cloud Computing
	SLO-2	Practical Solutions				
S-9	SLO-1	Competitive Intelligence Analysis	Decision Support SystemsComponents	Speech Analytics	Pairwise comparisons	Business Intelligence
	SLO-2					

Learning Resources	1. Ramesh Sharda, Dursun Delen, Efraim Turban, J.E. Aronson, Ting-Peng Liang, David King, "Business Intelligence and Analytics: System for Decision Support", 10 th Edition, Pearson Global Edition, 2013.	
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.V.Selvakumar, Hexaware Technologies, selvakumarv@hexaware.com	1.	1. Mr.L.N.B.Srinivas, SRMIST
2.	2.	2. Ms.S.Nagadevi, SRMIST

Course Code	18CSE395T	Course Name	WEB INTELLIGENCE	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	CSE	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Understand the topics of Web Intelligence	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Study models of information retrieval, semantic webs, search engines, and web mining.	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Gain knowledge on the algorithmic aspect of Web Intelligent systems	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Acquire knowledge on Data mining techniques	Expected Attainment (%)	Design & Development
CLR-5 :	Understand the impact of Social Network Design for Web Intelligence		Analysis, Design, Research
CLR-6 :	Gain Knowledge on different approaches required for studying the impact of social network for Web Intelligence		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Acquire the knowledge on topics and benefits of Web Intelligence	2 80 85	H - - - - - - - - - H H H -
CLO-2 :	Acquire the ability to build models of information retrieval, semantic webs, search engines, and web mining.	2 75 80	H H H - - H - - - - - H H H M
CLO-3 :	Understand the basic ideas of Multimedia Information Retrieval	2 85 80	H - - - - H - - - - - H H H H
CLO-4 :	Acquire knowledge to use web crawlers and fetch relevant information	2 80 75	H H H M M - - - - - H H H H
CLO-5 :	Acquire knowledge to refine the social network design approached used for developing intelligent web	2 75 85	H - - H H - - - - - H H H H
CLO-6 :	Apply the knowledge of different web intelligence based algorithms in practical applications	2 80 85	H - H - - H - - - - - H H H H

Duration (hour)	9	9	9	9	9
S-1	SLO-1 SLO-2	Introduction to Web Intelligence What is Web Intelligence? Benefits of Intelligent Web:What applications can benefit from web intelligence	Information Retrieval-Introduction, Document Representation	Data Mining Techniques-Classification	Web Content Mining-Web Crawlers
S-2	SLO-1 SLO-2	Wisdom Web	Retrieval Models	Data Mining Techniques-Clustering and Association	Web Crawlers
S-3	SLO-1 SLO-2	Ingredients of Intelligent Web	Retrieval Models	Data Mining Techniques- Association	Search Engines
S-4	SLO-1 SLO-2	Topics of Web Intelligence	Evaluation of Retrieval Performance	Web Usage Mining- Web-Log processing	Personalization of Web Content
S-5	SLO-1 SLO-2	How can I build intelligence in my own application?	Semantic Web-Introduction, The Layered-Language Model	Web Usage Mining -Analyzing Web Logs	Multimedia Information Retrieval
S-6	SLO-1 SLO-2	Examples of intelligent web applications	Metadata and Ontologies	Applications of Web Usage Mining Clustering of Web Users	Web Structure Mining- Modeling Web Topology
S-7	SLO-1 SLO-2	Fallacies of Intelligent applications	Ontology Languages for the Web	Applications of Web Usage Mining- Classification Modeling of Web Users	PageRank Algorithm
S-8	SLO-1 SLO-2	Related Technologies	Tool Environment for the Ontology RDFferret-Full Text Search and RDF Querying.Onto Share-Community support Onto Edit-Ontology Development	Applications of Web Usage Mining- Association Mining of Web Usages	Hyperlink-Induced Topic Search (HITS)
S-9	SLO-1 SLO-2	Related Technologies	OntoView-Change Management for Ontologies Sesame-Repositories for Ontologies and Data CORPURIUM-Information Extraction	Sequence-Pattern Analysis of Web Logs	Random Walks on the Web
					Social Network Design for Web Intelligence:Introduction: Social Network Design for Web Intelligence
					Overview of Social Intelligence Design: Groups and Communities, Issues of Social Intelligence Design, Applications of Social Intelligence Design
					The Travelling Conversation Model
					A Broadcast-Based Approach
					A Conversational Agent-Based Approach
					Smart Environment based approach
					Psychological Evaluation, Technical Issues
					Case Study-Putting it all together : an intelligent news portal
					Case Study-Applying Web Intelligence for Business Intelligence

Learning Resources	1. Akerkar, R. & Lingras, P. (2008). <i>Building an Intelligent Web: Theory and practice</i> . Jones and Bartlett Publishers, Sudbury, Massachusetts. ISBN-13: 978-0- 7637-4137-2 2. Marmanis & Babenko: <i>Algorithms of the Intelligent Web</i> , Manning Publications, 2009, ISBN:978-1933988665 3. Witten, Ian H. & Frank, E. (2005). <i>Data Mining: Practical Machine Learning Tools and Techniques</i> . 2 nd Edition, Morgan Kaufman. ISBN 0120884070, 9780120884070	4. Bing Liu: <i>Web Data Mining</i> , Springer, 2nd ed. 2011 (view online or download from Springerlink) 5. Manning, Raghavan and Schuetze: <i>Introduction to Information Retrieval</i> , Cambridge University Press, 2008 (book available online) N. Zhong, J.M. Liu, Y.Y. Yao, <i>Web Intelligence</i> (Springer, 2003)
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.B.Sathiya, Data Scientist, SPI Global - Analytics & AI, Adyar, Chennai	1. Dr.S.RenugaDevi, Assistant Professor(SI.Gr.), College of Engineering, Guindy, Anna University, Chennai	1. Dr.G.Manju
		2.Mr.K.Vijayakumar
		3.Mr.LNB.Srinivas

Course Code	18CSE396T	Course Name	DATA SCIENCE	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1:	Able to apply fundamental algorithmic ideas to process data	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2:	Understand the Data Analytics lifecycle		
CLR-3:	Able to construct predictive models to classify new data set		
CLR-4:	Learn to apply hypotheses and data into actionable predictions		
CLR-5:	Document and communicate the results effectively to different stakeholders		
CLR-6:	Effectively communicate the findings using visualization techniques		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Engineering Knowledge
CLO-1:	Able to comprehend basic methods of processing data from real world problems	2	L
CLO-2:	Able to convert data into actionable insights	2	M
CLO-3:	Build clustering and classification models using R environment	3	L
CLO-4:	Apply statistical techniques for evaluation	3	L
CLO-5:	Analyze and validate the models using appropriate performance metrics	4	H
CLO-6:	Present the results using effective visualization techniques	4	L
		Expected Proficiency (%)	Problem Analysis
		Expected Attainment (%)	Design & Development
			Analysis, Design, Research
			Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Data science process	Approaching Analytics Problems	Introduction to R	Choosing and evaluating models
	SLO-2	The roles in a data science project	Key roles for successful Analytics project	R Graphical user interfaces	Documentation
S-2	SLO-1	Stages in data science project	Discovery	Data Import and Export	Schematic model construction and evaluation
	SLO-2	Define, Collect, Build, Evaluate, Present and Deploy	Business domain, Resources, Problem framing, Key stakeholders, Analytics sponsors, Initial hypotheses, Data sources	Attributes and Data Types	Mapping problems to machine learning
S-3	SLO-1	Working with data from files	Data Preparation	Vectors	Deploying models
	SLO-2	Structured data, other data formats and Transforming data in R	Learning about the data, conditioning	Arrays and Matrices	Solving classification problems, working without known targets
S-4	SLO-1	Working with relational databases and NoSQL databases	Model Planning	Data Frames	Evaluating classification models
	SLO-2	Staging and Curating the data	Data exploration, Model selection	Lists	Presenting your results to the project sponsor
S-5	SLO-1	Exploring data	Model Building	Factors	Summarizing the project goals and stating the results
	SLO-2	Using summary statistics to spot problems	Common tools for model building	Contingency Tables	Evaluating clustering models
S-6	SLO-1	Managing data	Communicate Results	Descriptive statistics	Validating models
	SLO-2	Cleaning data	Analysis over the different models	Model building, Evaluation and Deployment	Overfitting, Quantifying model soundness, Ensuring model quality
S-7	SLO-1	Sampling for modeling and validation	Operationalize	Hypotheses Testing	Memorization methods
					Dirty data
					Using single variable and multi variable
					Visualizing a single variable
					Linear regression
					Examining multiple variables

	SLO-2	Training and test set split, Sample group column, Record grouping, Data provenance	Moving the model to deployment environment	Null hypotheses and Alternative hypotheses	Building a linear regression model and predicting	Dotchart and Barplot
S-8	SLO-1	Data Structures	Analytics Plan	Difference of means	Logistic regression	Box and Whisker plot
	SLO-2	Structured, Semi-structured, Quasi-structured and Unstructured data		Student t-test, Welch's t-test	Building a logistic regression model and predicting	Hexbinplot for large datasets
S-9	SLO-1	Drivers of big data	Key deliverables of analytics project	Wilcoxon Rank-Sum test	Unsupervised methods	Scatterplot matrix
	SLO-2	Devices – Mobile, smart devices	Presentation: Project sponsors, Analysts, Code, Technical specifications	Type I and II errors	Cluster analysis	Analyzing a variable over time

Learning Resources	<ol style="list-style-type: none"> David Dietrich, Barry Heller, Beibei Yang, "Data Science and Big Data Analytics", EMC Education Services, 2015 Nina Zumel, John Mount, "Practical Data Science with R", Manning Publications, 2014 Jure Leskovec, Anand Rajaraman, Jeffrey D. Ullman, "Mining of Massive Datasets", Cambridge University Press, 2014 Mark Gardener, "Beginning R - The Statistical Programming Language", John Wiley & Sons, Inc, 2012 W.N. Venables, D.M. Smith and the R Core Team, "An Introduction to R", 2013 Tony Ojeda, Sean Patrick Murphy, Benjamin Bengfort, Abhijit Dasgupta, "Practical Data Science Cookbook", Packt Publishing Ltd., 2014
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	30 %	-	40 %	-	30 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	40 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers			
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts	
1. Dr. Pethuru Raj, Reliance Jio Infocomm Ltd, peterindia@gmail.com	1. Prof. P. Marikkannu, IT HOD, Anna University Regional centre, Coimbatore, pmarikkannu@gmail.com	1. Dr. G. Vadivu, SRMIST	
	2. Prof. E. Ilavarasan, Pondicherry University, eilavarasan@pec.edu	2. Dr. B. Baranidharan, SRMIST	
		3. Mr. D. Vivek, SRMIST	

Course Code	18CSE487T	Course Name	DATA WAREHOUSING AND ITS APPLICATIONS	Course Category	E	Professional Elective	L 3	T 0	P 0	C 3
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Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1:	Understand the basic idea of data warehouse	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2:	To learn step by step approach to design a data warehouse		
CLR-3:	Understand ETL Process		
CLR-4:	To learn building process of data warehouse and implementation of data mart		
CLR-5:	Identify the Data mining concepts with various domains		
CLR-6:	To learn case studies to bring out practical aspects of data warehouse		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Engineering Knowledge
CLO-1:	Acquire the knowledge, Architecture and schema and OLAP Tool concepts.	2 80 85	H - - - - - - - - - - - - - - - -
CLO-2:	Acquire knowledge to design a data warehouse.	2 75 80	H - - - - - - - - - - - - - - - -
CLO-3:	Implement ETL Process in various data warehouse applications.	2 85 80	H - - - - - - - - - - - - - - - -
CLO-4:	Acquire knowledge to implement a data warehouse.	2 80 75	H - - - - - - - - - - - - - - - -
CLO-5:	Implement the various concepts and applications of data mining rules and technology.	2 75 85	H - - - H - - - - - - - - - - - -
CLO-6:	To Implement the data warehouse concepts in various organizations.	2 80 85	H - - - - - - - - - - - - - - - -

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Introduction to dataware housing	Data Warehouse Schema-Introduction	Building a data warehouse - Introduction	DATA MINING-introduction – Data – Types of Data – Data Mining Functionalities	Data Warehouse in Tamil Nadu government
	SLO-2 Introduction to data ware housing	Dimensional Modeling	Critical success factor	Integrating Data Mining with Data Warehouse	Data warehouse for ministry of commerce
S-2	SLO-1 Data warehousing Components	The Star Schema	Requirement Analysis	Data Mining Task Primitives	Data warehouse for the government of Andhra Pradesh
	SLO-2 Need for Data warehousing	The Snowflake Schema	Planning for the data warehouse	Data Preprocessing	Data warehouse for the government of Andhra Pradesh
S-3	SLO-1 Benefits and application of data warehouse	Aggregate Tables	Data warehouse design stage	Association rule mining and classification	Data warehouse in Hewlett Packard
	SLO-2 Data Warehouse Architecture Goals	DBMS Schemas for Decision Support	Building and implementing data marts	Frequent pattern Mining	Data warehouse in Hewlett Packard
S-4	SLO-1 Data Warehouse Architecture and Characteristics	Data Extraction	Building data warehouse	Apriori algorithm	Data warehouse in Levi Strauss
	SLO-2 Data Warehouse Architecture and Characteristics	Data transformation: Basic tasks	Backup and Recovery	Frequent pattern Mining without candidate generation	Data warehouse in Levi Strauss
S-5	SLO-1 Data Mart	Major transformation types	Establish the data recovery quality framework	Mining Multilevel Association Rules	Data warehouse in World Bank
	SLO-2 Data Mart	OLAP definition,	Operating the warehouse	Mining Multidimensional Association Rule, Correlation Analysis Rule	Data warehouse in World Bank
S-6	SLO-1 Classification of data mart, Implementation	Dimensional Analysis	Recipe for a successful data warehouse	Classification: Decision Tree	HARBOR-A highly available data warehouse
	SLO-2 Classification of data mart, Implementation	Hypercube	Data warehouse pitfalls	Bayesian Classification-Naive Bayes Classification	HARBOR-A highly available data warehouse
S-7	SLO-1 Gathering the business requirement	OLAP operations	Meta Data – Introduction	SVM Linear and Non linear data	A Typical Business Data Warehouse for a trading company

	SLO-2	Planning and project management-Project principles	Drill down	Meta Data – Data Management	Text Mining Temporal Data Mining and Spatial Data mining	A Typical Business Data Warehouse for a trading company
S-8	SLO-1	Data ware house readiness assessment, project team	Roll up	Meta Data – Query Generation	Cluster Analysis-Introduction	Customer Data warehouse of world's first and largest online bank in united kingdom
	SLO-2	Selecting the operating system	Slice	Meta Data – Query Generation	K-means– Partitioning Methods	Customer Data warehouse of world's first and largest online bank in united kingdom
S-9	SLO-1	Selecting the database software	OLAP models	Meta Data and Tools	Hierarchical Methods	A German supermarket Edeka's Data warehouse
	SLO-2	Selecting the tools	MOLAP	Meta Data and Tools	Data Mining Applications	A German supermarket Edeka's Data warehouse

Learning Resources	<ol style="list-style-type: none"> 1. PaulrajPonniah,—DataWarehousing:FundamentalsforITProfessionals,WileyIndia.,2001. 2. Reema Theraja "Data Warehousing" by Oxford UniversityPress-2011. 3. DataMiningandDataWarehousingbyMs.KhushbooSaxena,Mr.Sandeepsaxena,Dr.AkashSaxenafirst edition 2015,BPBpublication,India 4. Prabhu CSR ,Data Warehousing Concepts, Technique, Product and application, PHI Learning private Ltd, Third Edition, 2013. 5. SamAnahory,DennisMurray,DataWarehousingintheRealWorld,Pearsonpublication-2009
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50%)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Understand	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Apply										
Level 3	Analyze	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Evaluate										
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
K Selvanayagam, System Analyst, project Lead, Preludesys, Siruseri, Kancheepuram Dist.	V.Masillamani, Asst Prof,IITDM, Kancheepuram ,chennai	1.A.M.J Muthu Kumaran
		2. S.A Saranya

Course Code	18CSE488T	Course Name	FUNCTIONAL PROGRAMMING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:		
CLR-1 :	Understand the basic building blocks of stream processing			
CLR-2 :	Explore the data ingestion options into stream processing engines			
CLR-3 :	Process streaming data in real time			
CLR-4 :	Utilize NOSQL storage options to store real time data			
CLR-5 :	Deliver stream processing results to end users			

Learning			
1	2	3	
Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	

Program Learning Outcomes (PLO)															
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3	
L	H	H	H	H	-	-	-	L	L	-	H	-	-	-	
M	H	L	M	M	-	-	-	M	L	-	H	-	-	-	
M	H	M	H	H	-	-	-	M	L	-	H	-	-	-	
M	H	M	H	H	-	-	-	M	L	-	H	-	-	-	
H	H	M	H	M	-	-	-	M	L	-	H	-	-	-	

Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:		
CLO-1 :	Comprehend the usage of basic constructs of a functional programming language			
CLO-2 :	Create the different types of functions and evaluate its operations			
CLO-3 :	Create patterns and match the same with traits and case classes			
CLO-4 :	Create lists and collections, evaluate its operations			
CLO-5 :	Construct functional design for real world applications using common structures			

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Programming Paradigms	Modules, Objects and Namespaces	Traits – Purpose and Syntax	Lists – Java vs Scala Lists	Functors - Purpose and Use
	SLO-2 Different types of programming paradigms, Functional vs OOP	Demo - Modules, Objects and Namespaces	Define a trait	Lists definitions and usage demo	Writing a simple functor
S-2	SLO-1 Scala Language Basics - Variables,	Anonymous Functions	Interface types	Working with Lists	Functor Laws
	SLO-2 Expressions	Polymorphic Functions, Nested Functions	Interface types examples	Constructing Lists	Applicatives – Concepts and use
S-3	SLO-1 Functions	Demo – Anonymous , Polymorphic and Nested Functions	Thick Interfaces	Basic operations on lists	Defining an applicative
	SLO-2 Recursion	Closures	Thin Interfaces	head, tail, isEmpty demo, List Patterns	Demo of Applicatives
S-4	SLO-1 Call By Name	Demo - Closures	Comparison - Thick vs Thin Interfaces	Lists - First Order methods	Traversable functors
	SLO-2 Call By Value	Repeated Parameters	Ordered trait	Examples of First Order Methods	Example – Traversable Functors
S-5	SLO-1 Conditionals	Tail Recursion	Demo – Ordered trait, Trait Comparisons	Lists - Higher Order methods	Monads
	SLO-2 Looping – for each and for	Demo – Tail Recursion	Traits for modifying interfaces	Examples of Higher Order Methods	Defining Monads
S-6	SLO-1 Significance of vals	Define a tail recursive function	Stacking modifications	Sequences – Overview and operations	Monad Laws
	SLO-2 Classes	Tracing tail-recursive functions	Recap – Traits and operations	Demo - Sequences	Demo – Monads and Monad Laws
S-7	SLO-1 Types	Demo – Tracing tail-recursive functions	Mixin – Purpose & Composition	Tuples - Overview and operations	Monoid – Concept, Purpose and Use
	SLO-2 Fields	Limits of tail-recursive functions	Mixin Example	Demo - Tuples	Examples of Monoid
S-8	SLO-1 Methods	Curried Functions	Case Classes – Use, Definition	Sets and Maps – Overview and operations	Recap with more examples -Monads and Functors
	SLO-2 Variable scope	Demo - Curried Functions	Pattern Matching, Example	Demo – Sets and Maps	Recap with more examples -Applicatives
S-9	SLO-1 Objects	Higher Order Functions - Definition and Uses	Sealed Classes, Option Type	Recap – Lists and Collections	Applications – Functors, Monads
	SLO-2 Singleton object, Variables of objects	Higher Order Functions Example	Applications – Sealed Classes and Option Type	Examples – Lists and Collections	Applications - Monads

Learning Resources	1. Chiusano,P,BjarnasonR,FunctionalProgramminginScala,ManningPublications,2015	3. Hortsman, C., Scala for the Impatient, 2 nd ed., Addison-Wesley,2016.
	2. OderskeyM,SpoonL,VennersB,"ProgramminginScala",Thirdedition.	4. Raychaudhuri R, Scala in Action, 1 st ed. Manning Publications,2013.

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50%)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
		Ms. K.Somalakshmi
		Mr.R.Rajkumar

Course Code	18CSE489T	Course Name	STREAMING ANALYTICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	
Course Offering Department	Computer Science and Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand the basic building blocks of stream processing		1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Explore the data ingestion options into stream processing engines		Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Process streaming data in real time																			
CLR-4 :	Utilize NOSQL storage options to store real time data																			
CLR-5 :	Deliver stream processing results to end users																			
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																		
CLO-1 :	Comprehend the concepts and terminologies in stream processing		3	80	70	L	H	H	H	H	-	-	-	L	L	-	H	-	-	-
CLO-2 :	Create the data ingestion pipeline for a stream processing application		3	85	75	M	H	L	M	M	-	-	-	M	L	-	H	-	-	-
CLO-3 :	Create stream processing applications using Apache Storm and Spark Streaming		3	75	70	M	H	M	H	H	-	-	-	M	L	-	H	-	-	-
CLO-4 :	Store real time data using NoSQL databases		3	85	80	M	H	M	H	H	-	-	-	M	L	-	H	-	-	-
CLO-5 :	Construct stream data visualizations for users		3	85	75	H	H	M	H	M	-	-	-	M	L	-	H	-	-	-
			3	80	70	L	H	H	H	H	-	-	-	L	L	-	H	-	-	-

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Introduction to Stream Processing	Getting Started with Kafka	Apache Storm – Introduction	Apache Spark Streaming Introduction
	SLO-2	Batch vs Stream Processing, Examples of stream processing	Why Kafka ? Publish Subscribe messaging model	Features of Storm	Spark's Memory Usage
S-2	SLO-1	Map Reduce, Scalability and Fault Tolerance	Kafka Architecture	Storm Components	Understanding Resilience and Fault Tolerance in a Distributed System
	SLO-2	Applications of stream processing	Messages and Batches, Schemas	Nimbus, Supervisor Nodes	Spark's cluster manager
S-3	SLO-1	Stateful Stream Processing	Topics and Partitions,	Zookeeper cluster	Data Delivery Semantics in Spark
	SLO-2	Stream Processing Model	Producers and consumers	Storm Data Model	Data Delivery Semantics in Spark Applications
S-4	SLO-1	Data Sources, Stream processing pipelines, Sinks	Brokers and Clusters	Definition of a Storm topology, Operation modes in Storm	Microbatching
	SLO-2	Transformations and Aggregation	Multiple Clusters, Data Ecosystem	Storm – Prerequisites and Setting up a storm cluster, Developing a hello world example	Dynamic Batch Interval
S-5	SLO-1	Window Aggregations	Sending messages with producers	Storm topology options, Demo of Hello world in Storm	Structured Stream processing model
	SLO-2	Stateless and stateful processing	Steps & Example - Sending messages with producers	Introduction to Storm UI	Spark Streaming Resilience Model
S-6	SLO-1	Effect of time in stream processing	Receiving messages with consumers	Cluster, Nimbus, Supervisor, Topology Summary. Nimbus Configuration	Data Structures in Spark – RDDs and DStreams
	SLO-2	Lambda Architecture	Steps & Example - Receiving messages with consumers	Storm Scheduler	Spark Fault Tolerance Guarantees
S-7	SLO-1	Kappa Architecture	Developing Kafka Streams Application	Types of schedulers	First Steps in Structured Streaming
	SLO-2	Examples – Lambda & Kappa Architectures	Phases in a Kafka Streams Application Development	Applications of schedulers	Streaming Analytics Phases
					Examples of Streaming Data Visualization

S-8	SLO-1	Streaming vs Batch Algorithms	Constructing a topology	Storm Cluster Monitoring	Acquiring streaming data	Visual Distractions and Visual Deception
	SLO-2	Applications – Streaming and Batch Algorithms	Streams and State – Applying stateful operations	Integration of Storm with Kafka	Transforming streaming data	Example – Stream processing visualization dashboards
S-9	SLO-1	Use of a Batch-Processing Component in a Streaming Application	Example application development with Kafka Streams	Integration of Storm with Kafka example	Output the resulting data	Streaming Visualization Techniques
	SLO-2	Recap – Stream Processing Fundamentals	Demo – Kafka Streams	Recap – Storm in Stream Processing	Demo – Stream Processing with Spark Streaming	Demo – Stream Processing visualization

Learning Resource s	1. Ellis B, <i>Real-Time Analytics – Techniques to analyze and visualize streaming data</i> , 1 st ed., John Wiley & Sons Inc, 2014	4. Bejeck Jr. W.P., <i>Kafka Streams in Action- Real-time apps and microservices with the Kafka Streams API</i> , ", 1 st ed., Manning Publications, 2018
	2. Andrade.H.C, Gedik B, Turaga D.S, "Fundamentals of Stream Processing: Application Design, Systems, and Analytics", 1 st ed., Cambridge University Press, 2014.	5. Jain.A, <i>Mastering Apache Storm</i> , 1 st ed., Packt Publishing, 2017.
	3. Narkhede N, Shapira .G, and Palino T., <i>Kafka: The Definitive Guide - Real-Time Data and Stream Processing at Scale</i> , 1 st ed., O'Reilly Media, Inc., 2017.	6. Garillot F and Mass. G., <i>Stream Processing with Apache Spark</i> , 1 st ed., O'Reilly Media, Inc., 2019.
		7. https://docs.mongodb.com/manual/changeStreams/
		8. Banker K., Bakkum P., Verch S., Garret D., Hawkins T., <i>MongoDb in Action</i> , ", 1 st ed., Manning Publications, 2016
		9. Arageus A, <i>Visualizing Streaming Data</i> , 1 st ed., O'Reilly Media, Inc., 2018.

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Evaluate Create	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
		Ms.K.Sornalakshmi
		Ms.A.Saranya, Dr.Manju

Course Code	18CSE490T	Course Name	BIG DATA VISUALIZATION	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Understand the key techniques used in visualization which includes data models, graphical perception and techniques specifically for visual encoding and interaction	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Obtain an exposure to common data domains and the corresponding analysis tasks which includes multivariate data and text		
CLR-3 :	Get hands-on experience in building and evaluating visualization systems		
CLR-4 :	Gain knowledge in data visualization aides		
CLR-5 :	Understand the significance of data by placing it in a visual context		
CLR-6 :	Utilize the knowledge by reading and discussing research papers from the visualization literature		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom) Expected Proficiency (%) Expected Attainment (%)	Engineering Knowledge Problem Analysis Design & Development Analysis, Design, Research Modern Tool Usage Society & Culture Environment & Sustainability Ethics Individual & Team Work Communication Project Mgt. & Finance Life Long Learning PSO - 1 PSO - 2 PSO - 3
CLO-1 :	Design and exploring the result with data visualizations	3 75 70	L M M M L - - - M L M M
CLO-2 :	Conducting exploratory data analysis using visualization techniques and tools.	3 75 70	M H M M M - - - M L M M
CLO-3 :	Visual presentations of data for effective Communication.	3 80 75	M M H H M M - - M M H H
CLO-4 :	Designing and evaluating color palettes for visualization based on principles of perception.	3 85 80	M M M H H - - - M M H H
CLO-5 :	Using the knowledge of perception and cognition to evaluate visualization design alternatives	3 85 80	M H M H H - - - M M H H
CLO-6 :	Identifying opportunities for the application of data visualization in various domains.	3 85 80	M H H H H - - - M M H H

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Introduction to Big Data Visualization	Definitions and explanations of visualization categories	An Introduction to Visualization tools	Introduction to D3
	SLO-2	Challenges of Big Data Visualization	Exploring R In big data	Visualization tools and big data	D3 and big data
S-2	SLO-1	Categorization	Example with Patient Medical History	Example 1 – Sales transactions	Basic Examples
	SLO-2	Visualization Philosophies	Digging in with R	Adding more context	Getting started with D3
S-3	SLO-1	Approaches to Big Data Visualization	No looping	Wrangling the data	D3 visualization sample templates
	SLO-2	Quality of Visualization	Comparisons and Contrasts	Trifacta Script panel	Big data visualization using D3
S-4	SLO-1	Infographics versus Data Visualization	Tendencies	A visualization dashboard	Displaying Results Using D3
	SLO-2	Exploration versus Explanation	Dispersion	Experimenting with the data and build the visualization	Create a summary file for visualization
S-5	SLO-1	Informative versus Persuasive versus Visual Art	Data quality categorized	Data pane_core details	Visualization using HTML document
	SLO-2	Ingredients of Successful Visualizations	Data Manager	Constructing Dashboards	Data visualization showing the stacked view
S-6	SLO-1	Choose Appropriate Visual Encodings-Natural Ordering, Distinct Values	Data Manager and big data	Saving and Presenting the work	Visual transitions
	SLO-2	Redundant Encoding, Defaults versus Innovative Formats ,Readers' Context	Example-Reformatting-A little Setup	Visualization re-coloring, resizing, adding or changing labels	Final Thought
S-7	SLO-1	Compatibility with Reality ,Patterns and Consistency	Adding Script Code	Filters and Measure Names	Multiple donuts
	SLO-2	Selecting Structure	Executing the scene	Example-Promotion Spend Effect on Sales	Another twist on bar chart visualizations with examples
S-8	SLO-1	Position: Layout and Axes	Status and relevance	Sales and spend	Building storytelling with data

	SLO-2	<i>The Meaning of Placement and Proximity</i>	<i>Naming the nodes</i>	<i>Sales v Spend and Spend as % of Sales Trend</i>	<i>D3 Stacked Area via Nest template</i>	<i>competency in your team or organization</i>
S-9	SLO-1	<i>Patterns of Organization-Specific Graphs, Layouts, and Axis Styles</i>	<i>Consistency, Reliability, Appropriateness</i>	<i>ables and indicators</i>	<i>Adopting the sample</i>	
	SLO-2	<i>Appropriate Use of Circles and Circular Layouts</i>	<i>Accessibility and Other Output nodes</i>		<i>Visualization changes format</i>	

Learning Resources	1. <i>Big Data Visualization</i> , James D. Miller, Copyright © 2017 Packt Publishing	3. <i>Storytelling with data - a data visualization guide for business professionals</i> by cole nussbaumer knaffic, Wiley publications
	2. <i>Designing Data Visualizations</i> , by Noah Iliinsky and Julie Steele, Copyright © 2011 Julie Steele and Noah Iliinsky. All rights reserved. Printed in the United States of America	4. <i>Tableau Your Data!</i> by Daniel G. Murray and the InterWorks BI Team, Wiley publications

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Valiyullasha, Bugtreat Technologies, UK, ceo@bugtreat.com	Prof. Shiv ram Dubey, IIIT Sricity, srdubey@iiits.in	Dr. Mangalraj, SRMIST,
Saravanakarthick, Hewlett-Packard, India, saravanakarthick.chinniah@dx.com	Prof. Bhawana Rudra, NITK suratkal, bhawanarudra@nitk.edu.in	Dr. K.P. Vijayakumar, SRMIST

Course Code	18CSE491T	Course Name	MACHINE LEARNING - II	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18CSE392T	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	CSE	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:		Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Understand the Fundamentals of machine Learning Experiments			Level of Thinking (Bloom)	2	80	85	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLR-2 :	Design and implement Ensemble learning methods							Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3	
CLR-3 :	To provide deeper understanding of Reinforcement Learning and its Elements							H	-	-	-	H	-	-	-	-	-	-	-	-	-	-	-
CLR-4 :	Understand and Implement Neural Network Algorithms							H	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLR-5 :	Understand the concepts of Deep Learning Algorithms							H	H	-	H	H	-	-	-	-	-	-	-	-	-	-	-
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																					
CLO-1 :	Design and Analyze Machine Learning Experiments			2	80	85																	
CLO-2 :	Learn and Understand Graphical Model Learning and ensemble learning			2	75	80																	
CLO-3 :	Understand the concept of Reinforcement learning			2	85	80																	
CLO-4 :	Study the neural network systems for machine learning			2	80	75																	
CLO-5 :	Learn and Implement Deep Learning algorithms			2	75	85																	

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Introduction to machine learning	Graphical Models	Reinforcement Learning	Neural Networks representations	Feature selection
	SLO-2 Basic probability theory	Bayesian belief networks	K-Armed Bandit	McCulloch-Pitts units	Feature extraction
S-2	SLO-1 linear algebra	Markov random fields	Elements of reinforcement learning	Thresholding logic	Deep Learning
	SLO-2		Model based learning	Perceptron	Deep learning python libraries
S-3	SLO-1 Factors		Value iteration	Feed forward networks	Simple DNN
	SLO-2 Response and strategy of Experimentation	Naïve Bayes classifiers	policy iteration	Multi-layer perceptron	Activation functions
	SLO-1 Randomization, Replication and Blocking	Markov models	Temporal difference learning		
S-4	SLO-2 Guidelines for machine learning Experiments	Hidden Markov models	Exploration strategies	Back propagation algorithms	Regularization methods
S-5	SLO-1 Cross validation and resampling methods	Ensemble learning methods	Deterministic and Non-deterministic rewards and actions	Convergence and Hidden layer representation in back propagation	Convolutional Neural Networks
	SLO-2 Measuring classifier performance	Voting, Boosting, Adaboost		Optimization Algorithms	
S-6	SLO-1 Interval estimation	Gradient Boosting	Semi-supervised learning	Gradient Decent	Recurrent Neural Networks
	SLO-2 Hypothesis testing	Bagging		Stochastic gradient	
S-7	SLO-1 Assessing a Classification Algorithm's performance	Random Forest	Computational learning theory	Adam, Adagrad	LSTM
	SLO-2 Comparing two classification Algorithms			RMSPProp	Sentiment analysis with LSTM keras code
S-8	SLO-1 Comparing multiple Algorithms	Fine Tuning Ensemble	VC dimension	Drop out	Auto encoders
	SLO-2	Cascading		Batch Normalization	
S-9	SLO-1 Comparison over multiple Datasets	Application Face recognition using Ensemble techniques	PAC learning	Application Face recognition using Neural Networks	Dimensionality reduction using Auto Encoders
	SLO-2				

Learning Resources	1. Kevin P. Murphy, "Machine Learning: A Probabilistic Perspective", MIT Press, 2012. 2. Ethem Alpaydin, "Introduction to Machine Learning", Prentice Hall of India, 2005 3. Tom Mitchell, "Machine Learning", McGraw-Hill, 1997. 4. Sebastian Raschka, Vahid Mirjalili, "Python Machine Learning and deep learning", 2 nd edition, Kindle book, 2018 5. Ian Goodfellow, Yoshua Bengio, Aaron Courville, "Deep Learning", MIT Press, 2016. 6. Jason Brownlee, "Deep Learning with Python", ebook, 2016.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50%)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
		1. Dr. G. Vadivu
		2. Dr. Usha Krithika
		3. Mr. S. Joseph James

Course Code	18CSE341T	Course Name	COMMUNICATION SYSTEMS ENGINEERING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1:	Understand the principles of Communication systems engineering	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2:	Gain knowledge on the basics of Communication system components		
CLR-3:	Acquire knowledge on encoding, decoding techniques		
CLR-4:	Understand the fundamentals of Fiber Optic Communication		
CLR-5:	Understand the basics of Satellite Communication		
CLR-6:			
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)
CLO-1:	Understand the basic ideas about Communication and its types	1	80 85
CLO-2:	Acquire the knowledge on applications of Communication systems	2	75 80
CLO-3:	Gain knowledge on information sources and source coding algorithms	2	85 80
CLO-4:	Understand the concepts of coding for reliable Communication	2	80 75
CLO-5:	Ability to apply/appreciate the skills learnt during the design and integration of the fibre optic mode of Communication in any system under development	2	75 85
CLO-6:	Ability to apply/appreciate the skills learnt during the design and integration of the satellite mode of Communication in any system under development	2	80 85
		Expected Attainment (%)	Engineering Knowledge Problem Analysis Design & Development Analysis, Design, Research Modern Tool Usage Society & Culture Environment & Sustainability Ethics Individual & Team Work Communication Project Mgt. & Finance Life Long Learning PSO - 1 PSO - 2 PSO - 3
			H - - - - - - - - - - - - - - - - H H - - - - - - - - - - - - - - - - H - - - - - - - - - - - - - - - - H H - - - - - - - - - - - - - - - - H - - H - - - - - - - - - - - - - - - H - - H - - - - - - - - - - - - - - -

Duration (hour)	9	6	9	9	9
S-1	SLO-1	Significance of human Communication, Communication systems, transmitter	Introduction to information sources and source coding	Coding for reliable Communication	Fibre Optic Communication: Introduction Through Optical Fiber
	SLO-2	Communication channel, Receivers, Transceivers	Modeling of information sources	Tight bound on error probability of orthogonal signals	Electromagnetic Spectrum
S-2	SLO-1	Attenuation, Noise	Measure of Information	The promise of coding	Types of Optical Fibres
	SLO-2	Types of electronic Communication, simplex	Joint and Conditional Entropy	Linear block codes	Propagation of Light
S-3	SLO-1	Full duplex, half duplex	Source coding theorem	Theorem on Linear code	Single Mode Fibre
	SLO-2	Analog signals, Digital signals	Source coding algorithms	Hamming Codes	Multimode Fibre
S-4	SLO-1	Modulation and multiplexing, Baseband transmission	The Huffman source coding algorithm	Decoding and performance of linear block codes	Losses Within an Optical Fibre: Attenuation Loss
	SLO-2	Broadband transmission	Huffman Encoding Algorithm	Soft decision decoding	Absorption Loss
S-5	SLO-1	Multiplexing	Examples on Huffman Encoding Algorithm	Hard decision decoding	Radiation Loss
	SLO-2	Electromagnetic spectrum	The Lempel-Ziv source coding algorithm	Error detection and Error correction	Dispersion Loss
S-6	SLO-1	Frequency and wavelength	Rate distortion theory	Burst error correcting codes	Rayleigh Scattering Loss
					Altitude Control Components: Sensors, Actuators

	SLO-2	Optical spectrum	Mutual information	Cyclic codes, The structure of cyclic codes	Modal Dispersion Loss	Satellite System Parameters
S-7	SLO-1	Bandwidth	Differential Entropy	The generator matrix, Encoding of cyclic codes	Coupling Losses	Equivalent Noise
	SLO-2	Channel bandwidth	Rate distortion function	BCH Codes, Reed-Solomon Codes	Fibre Optic Transmission System: Fibre Optic Cable Light Sources	Temperature Carrier-to-Noise Density Ratio
S-8	SLO-1	Spectrum management	Examples on Rate distortion function	Convolutional Codes	Types of Fibre Optic Transmitters, Optical Detectors, Optical Repeater	Energy of Bit-to-Noise Density Ratio
	SLO-2	Standards	Digital audio transmission and digital audio recording	Basic properties of convolutional codes, Encoding, The transfer function	Optical Point-to-point Communication System:	Satellite System Link Models
S-9	SLO-1	Communication applications survey - Simplex	Digital audio in telephone transmission systems	Catastrophic codes	Single Channel System Amplified Single Channel System	Satellite System Link Equation 636 Uplink Power Budget Calculation
	SLO-2	Communication applications survey - Duplex	Digital audio recording	Optimum decoding of convolutional codes - The Viterbi algorithm	Wavelength Division Multiplexing (WDM) Systems	Satellite Radio Navigation

Learning Resources	1. Louis E. Frenzel, <i>Principles of Electronic Communication Systems</i> , 4 th Edition, Tata McGraw Hill Education, 2019. (Unit -I) 2. John G. Proakis, Masoud Salehi, <i>Communication Systems Engineering</i> , 2 nd edition, Pearson Education International, 2015. (Unit - II & Unit -III)	3. <i>Communication Systems</i> , V. Chandra Sekar, Oxford University Press, 2015 (Unit - IV & Unit-V)
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50%)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. Ramesh Somasundaram, Director & Head, IT Sourcing Management & Supplier Governance, Energica, Chennai	Dr.M.P Chitra, HOD/ECE, Panimalar Institute of Science and Technology	Dr.Annapurani.K, Dr.M.Prakash
Mr. Umakanthan Velayutham, Senior Partner & Head, Transform Advisory Services, Energica, Chennai	Dr.Dhalia Sweetlin, Asst.Prof(Sr.G), IT Dept, MIT, Chennai	Mrs.Kayalvizhi Jeyavel

Course Code	18CSE342T	Course Name	DIGITAL COMMUNICATION SYSTEMS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																																		
CLR-1 :	Understand the model of digital Communication system.				Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15																		
CLR-2 :	Gain the knowledge about digital coding, signal compression and its application									Expected Proficiency (%)	2	75	80	Problem Analysis																												
CLR-3 :	Gain knowledge on digital modulation , baseband and band-pass modulation														Expected Attainment (%)	2	85	80	Design & Development																							
CLR-4 :	To know the fundamentals of error control coding																			Analysis, Design, Research	2	80	75	Modern Tool Usage																		
CLR-5 :	To learn the importance of Multiplexing and Multiple Access																								Society & Culture	2	75	85	Environment & Sustainability													
																														Ethics	2	80	85	Individual & Team Work								
					Communication	2	75	85	Project Mgt. & Finance																																	
										Life Long Learning	2	75	85	PSO - 1																												
															PSO - 2	2	75	85	PSO - 3																							
																				PSO - 3	2	75	85																			
																</																										

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction Digital Communication System, advantages of Digital Communication	Introduction to digital coding	Introduction to Digital Modulation	Introduction-Types and Measure of Error- Shannon-Hartley Capacity Theorem	Introduction to Multiplexing-Types
	SLO-2	Regeneration of Digital Signals, Power Efficiency of Digital Modulators	Digitizing Analog Signals	Baseband Modulation	Methods of Error Control-Classification of Error Correcting Codes	Frequency Division Multiplexing
S-2	SLO-1	Bandwidth Compression, Multimedia: Unification of Signals	Sampling	Pulse Modulation Systems	Linear Block Codes-Hamming Distance, Weight, Error Detection, Correction	Time Division Multiplexing
	SLO-2	Performance, Technology	Quantization	Baseband Signaling	Linear Block Codes-Generator Matrix, Systematic codes, Parity Check Matrix	Frame Synchronization
S-3	SLO-1	Time and Frequency Representation	Encoding	Correlative Coding: Duo-Binary Coding	Standard Array - Implementing the decoder	Primary Multiplexing in Digital Telephony
	SLO-2	Fourier Series, Fourier Transform	Signal Compression,	Modified Duo-Binary Coding	Cyclic Codes-Generator Polynomial for cyclic code	Higher Order Multiplexing
S-4	SLO-1	Discrete-time Fourier Transform	Signal Statistics and Redundancy	Digital Phase Modulation(Phase Shift Keying): Bi-phase shift keying modulation	Systematic Cyclic code	Multiple Access-Frequency Division Multiple Access
	SLO-2	Discrete Fourier Transform	Companded PCM	Differential coding in Bi-phase shift keying	Polynomial Multiplication and division	Time Division Multiple Access
S-5	SLO-1	Convolution	Predictive Coding	Scrambling	Importance of Block Codes-Hamming Codes	Code Division Multiple Access
	SLO-2	Correlation	Transform Coding	Bi-phase shift keying modulator, Quadrature and Offset Quadrature phase shift keying	Problem solving session	Random Access
S-6	SLO-1	Hilbert Transform	Parametric Coding	Digital Frequency Modulation(Frequency Shift Keying)	Golay-Reed Solomon Codes	Carrier Sense Multiple access/Collision Detection
	SLO-2	Problem solving session	Perceptual Coding	Minimum Shift Keying	Convolutional codes, Convolutional Encoder	Fixed Assignment Multiple Access
S-7	SLO-1	Low-pass and Band-pass Representations,	Application of Digital Coding-Digital	Minimum Shift Keying Modulator, Gaussian	Convolutional Decoding, Maximum	Demand Assignment Multiple Access
		Band-pass Signals and Systems	Speech	Minimum Shift Keying, Continuous Phase	like hood Decoding	

				Modulation		
	SLO-2	Analytic Signals	Adaptive Delta Modulation Codec	Power Spectral Density of Baseband Signals	Viterbi algorithm	Introduction to Pseudo-Noise Sequence
S-8	SLO-1	Low-pass Equivalent Signals	Pulse Code modulation Codec	Power Spectral Density of Band-pass Signals	Sequential Decoding and Fano Algorithm	Properties of PN Sequences
	SLO-2	Problem solving session	Digital Audio: MP3 Coding	Problem solving session	Practical Applications of Error Correcting codes	Direct Sequence Spread Spectrum Transmitter and Receiver, Interface Rejection
S-9	SLO-1	Signal Space Representations: Vector Space	Digital Video: Run Length Coding, variable Length Coding	Comparison of Basic Modulations	Deep Space Communication	Frequency hopping Spread Spectrum, Frequency hopping Spread Spectrum Transmitter and receiver
	SLO-2	Problem solving session	MPEG1	Orthogonal Frequency Division Multiplexing	Satellite Communication	Spread Spectrum Applications

Learning Resources	<ol style="list-style-type: none"> 1. R.N. Mutagi, Digital Communication – Theory, Techniques and Applications, 2nd Edition, Oxford University Press, 2014. 2. John R. Barry, Edward A. Lee, David G. Messerschmitt, Digital Communication, 3rd Edition, Springer International Edition, Springer, 2011 3. John G. Proakis, Masoud Salehi, Digital Communications, 5th Edition, McGraw Hill Education, 2015
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50%)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. Ramesh Somasundaram, Director & Head, IT Sourcing Management & Supplier Governance, Energica, Chennai	Dr.M.P Chitra, HOD/ECE, Panimalar Institute of Science and Technology	Dr. Annapurani.K, Dr.M.Prakash
Mr. Umakanthan Velayutham, Senior Partner & Head, Transform Advisory Services, Energica, Chennai	Dr.Dhalia Sweetlin, Asst.Prof(Sr.G), IT Dept, MIT, Chennai	Mrs. M. Safa, Mrs. D. Anitha

Course Code	18CSE378T	Course Name	PRINCIPLES OF CLOUD COMPUTING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:				Learning			Program Learning Outcomes (PLO)															
CLR-1 :	Understand the fundamental ideas behind Cloud Computing, the evolution of the paradigm, its applicability; benefits, as well as current and future challenges					1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLR-2 :	Learn cloud enabling technologies and get exposure to advanced clouds					Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3	
CLR-3 :	Explore cloud storage technologies and relevant distributed file systems, NoSQL databases and object storage;																							
CLR-4 :	Understand the cloud security threats and protective mechanism for cloud computing																							
CLR-5 :	Participate in team-based peer reviews to analyze the security development life cycle and mitigate risks and vulnerabilities																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:				3	80	70	H	H	H	H	H	M	-	-	-	L	L	-	H	-	-	-
CLO-1 :	Explain terms used in secured software development and life cycle process					3	80	70	M	H	L	M	H	M	-	-	-	M	L	-	H	-	-	-
CLO-2 :	Apply fundamental concepts in cloud infrastructures to understand the cloud system, network and virtualization and outline their role in enabling the cloud computing system model.					3	85	75	M	H	M	M	H	-	-	-	M	L	-	H	-	-	-	
CLO-3 :	Illustrate the fundamental concepts of cloud storage and demonstrate their use in storage systems such as Amazon S3 and HDFS					3	75	70	M	H	L	H	M	-	-	-	M	L	-	H	-	-	-	
CLO-4 :	Evaluate the security issues related to cloud computing and handle the security threats and construct different cloud delivery design models.					3	85	80	M	H	M	M	H	M	-	-	-	M	L	-	H	-	-	-
CLO-5 :	Analyze various cloud programming models and apply them to solve problems on the cloud.					3	85	75	H	H	M	H	H	M	-	-	-	M	M	-	H	-	-	-

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction to Cloud Computing	Cloud enabling technologies- Broadband networks and Internet architecture	Introduction to Cloud Data Storage, The evaluation of storage technology	Fundamental Cloud Security	Cloud Application Development and Architectural Styles
	SLO-2	Evolution of cloud computing			Basic Terms and Concepts	
S-2	SLO-1	Network-Centric Computing	Data Center Technology	Storage Models	Threat Agents, Cloud Security Threats	MapReduce Programming Model
	SLO-2	Network-Centric Content				
S-3	SLO-1	Origin of Cloud Computing, Basic Concepts and Terminology	Web Technology	File Systems and databases	Cloud Security Mechanisms	Case Study: the GrepTheWeb Application
	SLO-2	Terminology	Multitenant Technology			
S-4	SLO-1	Goals and Benefits	Service Technology Virtualization Technology	Distributed File Systems Google File System	Encryption Hashing	Hadoop: Yarn and Tez
	SLO-2	Risks and Challenges, Roles and Boundaries, Cloud Characteristics				
S-5	SLO-1	Cloud Service Models	Virtual Machines	HDFS	Digital Signature, Public Key Infrastructure	SQL on Hadoop: Pig, Hive, and Impala
	SLO-2	Cloud Deployment Models		NoSQL Databases		
S-6	SLO-1	Cloud Service Providers and the Cloud Ecosystem	Full Virtualization and Para- virtualization	Cloud Databases (HBase, MongoDB, Cassandra, DynamoDB)	Identity and Access Management, Single Sign-On: Kerberos authentication	Current Cloud Applications and New Opportunities
	SLO-2					
S-7	SLO-1	Amazon Web Services(AWS), Google Clouds,	Hardware Support for Virtualization	Cloud Object Storage (Amazon S3,	One-time password, Basic cloud data	Design approaches with Case Study

	SLO-2	Microsoft Azure Cloud		OpenStack Swift, Ceph)	security mechanisms	
S-8	SLO-1	SLA Management in Cloud Computing: A Service Providers Perspective	Kernel-Based Virtual Machine, Hypervisors	Data Storage for Online Transaction Processing Systems	Virtual Machine Security, Security of Virtualization, A Trusted Hypervisor	Design methodology for IaaS Service Model
S-9	SLO-1	Case Study on Open Source & Commercial Clouds: Eucalyptus, OpenStack, Aneka	Containers; Docker Containers, Kubernetes	Disk Locality versus Data Locality in Computer Clouds	Mobile Devices and Cloud Security	Google API, AWS EC2 Instances.

Learning Resources	<p>1.Dan C. Marinescu, "Cloud Computing Theory and Practice", Second Edition Copyright © 2018 Elsevier Inc. All. https://www.sciencedirect.com/book/9780128128107/cloud-computing</p> <p>2.Rajkumar Buyya, James Broberg, AndrzejGoscinski, Cloud Computing Principles and Paradigms, Wiley Publications, 2017.</p> <p>3. Thomas Erl, ZaighamMahmood, and RichardoPuttini, "Cloud Computing: Concepts, Technology & Architecture", Prentice Hall/PearsonPTR, Fourth Printing, 2014, ISBN: 978013338752.</p> <p>4.K. Chandrasekaran, "Essentials of Cloud Computing", Chapman and Hall/CRC Press, 2014, ISBN 9781482205435</p> <p>5.Arshdeep Bahga, Vijay Madiseti, "Cloud Computing: A Hands-On Approach", University Press, 2016, ISBN-13: 978-0996025508.</p>					
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100%	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
SuriyadeepanRamamoorthy Research Engineer at Saama Technology Puducherry, Puducherry, India Information Technology and Services	Dr.E. Ilavarasan Professor, CSE Pondicherry Engineering college.	1.Mrs Krishnaveni,SRMIST,KTR-SWE
		2.Dr.S.Ramamoorthy,SRMIST,KTR-CSE
		3.Mr.K. Venkatesh,SRMIST,KTR-IT
		4.Mr. S. VidhyaSagar,SRMIST,Vadapalani campus

Course Code	18CSE377T	Course Name	DATA CENTRIC NETWORKS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1:	Critically discuss data center networking technologies	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2:	Evaluate key concepts in modern Layer 2 & Layer 3 data center networks	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3:	Concepts related to networking technologies in modern data centers.	Expected Proficiency (%)	Problem Analysis
CLR-4:	Design, build and configure complex routed and switched networks	Expected Attainment (%)	Design & Development
CLR-5:	Expose to implementing the networking solutions in a virtualized environment		Analysis, Design, Research
			Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1:	apply networking technologies in data centers	1 90 85	L - - M - - - - - H L - - -
CLO-2:	Design modern data centers which incorporate all dynamic routing protocols.	3 85 80	M M H H H - - - - - H M H -
CLO-3:	Design layer 2 and layer 3 protocols.	3 85 80	M H H H H - - - - - H M H -
CLO-4:	design and configure the data centers	3 80 75	M H H H H - - - - - H H H -
CLO-5:	implement various network solutions for data centers	3 80 75	H H H H H H - M - - - H M H H

Duration (hour)	9	9	9	9	9
S-1	SLO-1 SLO-2	Data centric networking from different perspectives	Introduction to data center architectures	Introduction to server Architectures	Introduction to Layer 2 Networks
S-2	SLO-1 SLO-2	Content-Centric Networking (CCN)	Top of rack (TOR) network connectivity	Clustering in server architectures	IEEE 802.3ba standards
S-3	SLO-1 SLO-2	Content Distribution Networks (CDN)	End of rack(EOR) network connectivity	scaling in server architectures	40 Gbps and 100 Gbps Ethernet
S 4-5	SLO-1 SLO-2	Requirements for modern data centers	Solutions that reduce cabling in architecture	Optimization in server architectures	IEEE 802.1D Spanning Tree Protocol (STP)
S-6	SLO-1 SLO-2	Design for flexibility	Solutions that reduce power in architecture	Stand-alone blades	RSTP protocol
S-7	SLO-1 SLO-2	Design for scalability	TIA/EIA-942. Structured cabling standards	Redundant Layer 2 and Layer 3 designs	PVST protocol
S-8	SLO-1 SLO-2	Design for electrical power	Cable management	Limitation of traditional server deployments	TRILL protocols
S-9	SLO-1 SLO-2	Design for Backup	Bandwidth requirements		IEEE 802.1Qbg Edge Virtual Bridging
		Flooring in data centers	I/O connectivity	Case study	Fiber Channel over Ethernet (FCoE) vs Internet
					OTV& VPLS layer 2 extension

Learning Resources	1. MourcioArregoces,"Data Centre Fundamentals",CiscoPress,2003 2. SilvanoGai,Claudio DeSanti,"I/O Consolidation in the Data Center" Cisco Press;1 edition [ISBN:9781587058882].2009. 3. KevinCorbin,Ron Fuller,DavidJansen,"NX-OSand CiscoNexus Switching:Next-Generation Data Center Architectures"CiscoPress;1 edition [ISBN:9781587058929].2010. 4. Silvano Gai,Tommi Salli,RogerAndersson,"Cisco Unified Computing System" CiscoPress;1edition,[ISBN:9781587141935].2010.	5. NashDarukhanawalla,Patrice Bellagamba,"Interconnecting Data Centers Using VPLS"CiscoPress;1edition,[ISBN:9781587059926].2009. 6. RobertW.Kembel,Roger Cummings(Introduction),"The Fibre Channel Consultant" Northwest Learning Assoc;3rdedition,[ISBN:0931836840],1998. 7. Robert W Kembal"FiberChannelSwitchedFabric"Northwest Learning Associates,inc.[ISBN:0931836719],2009. 8. JohnL.Hufferd,"ISCSI",Addison-WesleyBoston[ISBN:978-0201784190],2003
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50%)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Dr.M.S.Sricharan/Wipro Technologies		Dr. B.Amutha, Professor and Head, Department of CSE, SRM IST
		Dr. G.Vadivu, Professor and Head, Department of IT, SRM IST

Course Code	18CSE343T	Course Name	WEB APPLICATION DEVELOPMENT	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Generate web pages using HTML,CSS, AJAX, JQUERY				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Design and implement dynamic web page with validation using JavaScript objects and by applying different event handling mechanisms.				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Understand web site dynamic behavior and server side Programming																					
CLR-4 :	Generate dynamic web pages using databases																					
CLR-5 :	To understand the different web development frameworks																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	Acquire the knowledge of HTML,CSS, AJAX, JQUERY				2	80	85	M	H	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-2 :	Design the dynamic web page with validation using JavaScript objects and by applying different event handling mechanisms				2	75	80	M	H	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-3 :	Acquire the knowledge of web site dynamic behavior and server side Programming				2	85	80	M	H	-	H	-	-	-	-	-	-	-	-	-	-	-
CLO-4 :	Develop the dynamic web pages using databases				2	80	75	M	H	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-5 :	Understand the web development frameworks				2	75	85	M	-	H	-	H	-	-	-	-	-	-	-	-	-	-

Duration (hour)		11	9	9	7	9
S-1	SLO-1 SLO-2	Introduction: Rich Internet Applications	Introduction Angular JS	Overview of JSP2	Struts Architecture	Web Services
S-2	SLO-1	Introduction to HTML	Expression	Overview of SERVLET	Struts classes , Action Forward	Consuming a RESTfull Web Service Java desktop application /JSP
	SLO-2	HTML5 : Responsive web design			Action Form	Building REST Service with spring
S-3	SLO-1	Introduction about CSS	Module ,Directive Databinding	Creating dynamic web pages using JSP	Action Servlet	Spring Security Architecture
	SLO-2	CSS types			Action classes	
S-4	SLO-1	Introduction to JavaScript	Controllers,Scope-Filter	Standard-Tag Library	Understanding struts	Accessing relational data using JDBC with spring
	SLO-2			Java Beans , Custom Tags	config.xml	
S-5	SLO-1	Control structure	Introduction to Mongo, DB-Documents	Relational Database	Understanding Action Mappings, Struts flow with an example application	Uploading Files using spring application
	SLO-2			Introduction to MYSQL		
S-6	SLO-1	Objects	Collection-Database	JBDC-Driver	Struts Tiles Framework	Validating form input
	SLO-2					Handling form submission
S-7	SLO-1	Events	Datatypes	Understanding JDBC ODBC Connection Management	Struts Validation Framework	Creation of Batch Service
	SLO-2					Securing web application
S-8	SLO-1	Basic AJAX, History of AJAX AJAX - using XMLHttpRequest object	Creating, Updating	Resultset, Statements		Integrating Data
	SLO-2				Accessing data with MongoDB	
S-9	SLO-1	XML- and DOM , creating a full scaled web design	Deleting documents-Querying	Prepared statement, Callable Statement.		Creating asynchronous method,
	SLO-2	AJAX- Enabled Application using JSON.				Using WebSocket to build an interactive web application
S10	SLO-1	JQuery basic				

	SLO-2	jQuery core, events, effects,				
S11	SLO-1	plugins- user interface using jQuery.				
	SLO-2					

Learning Resources	<ol style="list-style-type: none"> 1. Deitel, Deitel and Nieto, "Internet and World Wide Web – How to program", 4th Edition, Pearson Education Publishers, 2009 2. Eric Freeman, Elisabeth Robson, "HTML5 Programming", first edition, O'Reilly Publishers, 2011. 3. Robin Nixon, "Learning PHP, My SQL, JavaScript, CSS & HTML5" Third Edition, O'REILLY, 2014. 4. Marty Hall, "Core Servlet & Java Server Pages " Sun Microsystems, 5. James Holmes "Struts: The Complete Reference", 2nd Edition 2007 McGraw Hill Professional. 6. Patrick Naughton, "COMPLETE REFERENCE: JAVA2", 7th edition, Tata McGraw-Hill, 2010. 7. Thomas Apowell, "The complete reference HTML & CSS", 5th Edition. 8. Craig Walls, "Spring in Action, 4th Edition Kindle Edition, Manning Publication, 2015. 	<ol style="list-style-type: none"> 9. Jobinesh Purushothaman, "RESTful Java Web Services" Second Edition, Packt Publishing, 2015 10. https://www.w3schools.com/angular/angular_filters.asp 11. Kristina Chodorow, MongoDB: The Definitive Guide, 2nd Edition, 2013, O'Reilly.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50%)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Understand	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Apply										
Level 3	Analyze	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Evaluate										
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.M.Prakash Team Lead (Associate Consultant) , Virtusa , Chennai, prakashpm@virtusa.com	1. Dr.KHANNA NEHEMIAH , Professor, Ramanujan Computing, Anna University	1. Dr. M.UMA, Assistant Professor, SWE
		2. Dr.Madhavan, Associate Professor/CSE
		3.K.Navin AP/IT

Course Code	18CSE344T	Course Name	CLOUD ARCHITECTURE	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Observe the fundamentals of cloud architecture	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Observe the Technologies used in cloud platforms	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Understand the advanced cloud architecture and storage arrays	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Understand the importance of cloud architecture design	Expected Attainment (%)	Design & Development
CLR-5 :	Gain knowledge in virtualization architecture		Analysis, Design, Research
CLR-6 :	Gain knowledge in future trends and technologies in cloud structures		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	To understand the concept of basic cloud computing paradigms	2 80 85	H - - - - - - - - - - - - - - -
CLO-2 :	To interpret the concepts of Cloud service structures	2 75 80	H H - - - - - - - - - - - - - - -
CLO-3 :	To Analyze the components of cloud computing showing how business agility in an organization can be created	2 85 80	H - - - - - - - - - - - - - - -
CLO-4 :	To be familiar with the market service providers in cloud.	2 80 75	H H - - - - - - - - - - - - - - -
CLO-5 :	To understand the technologies of data center cloud structures.	2 75 85	H - - - H - - - - - - - - - - - - - - -
CLO-6 :	To work with robust cloud architectural patterns	2 80 85	H - - - - - - - - - - - - - - -

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Introduction to cloud computing fundamentals	Service Oriented Architecture	Introduction to cloud storage infrastructures	Management Of Cloud Services	Introduction to Cloud Architecture patterns
	SLO-2 Cloud Computing definition	REST	Concept, planning and Design	Reliability, availability and security of services deployed from the cloud	Horizontally Scaling Compute Pattern- Cloud Significance
S-2	SLO-1 Cloud deployment models	Systems of Systems	Business continuity	Performance and scalability of services	Queue-Centric Workflow Pattern
	SLO-2 Private, Public, Hybrid, community cloud	Web Services	Basic concepts of information security	Tools and technologies used to manage cloud services deployment	Auto-Scaling Pattern
S-3	SLO-1 Cloud services:	Publish-Subscribe Model	Managing VDC and cloud environments and infrastructures	Cloud Economics	Eventual Consistency Prime
	SLO-2 IaaS, PaaS, SaaS	Basics of Virtualization	Securing storage in virtualized and cloud environments	Cloud Computing infrastructures available for implementing cloud based services	MapReduce Pattern
S-4	SLO-1 Enabling technologies of cloud computing	Types of Virtualization	Monitoring and management	Economics of choosing a Cloud platform for an organization	Database Sharding Pattern
	SLO-2 Benefits and challenges of cloud computing	Implementation Levels of Virtualization	Security auditing and SIEM	Runtime Support Services	Node Failure Pattern
S-5	SLO-1 Business Agility:	Virtualization Structures	Storage Network Design	Resource Provisioning and Platform Deployment-Provisioning of Compute Resources (VMs)	Network Latency Primer
	SLO-2 Benefits and challenges to Cloud architecture.	Tools and Mechanisms	Architecture of storage, analysis and planning.	Resource Provisioning Methods	CDN Pattern.
S-6	SLO-1 Cloud Applications	Virtualization of CPU Memory	Storage network design considerations	NIST Cloud Computing Reference Architecture	Multisite Deployment Pattern
	SLO-2 Application availability	I/O Devices	NAS and FC SANs	Demand-Driven, Event-Driven Resource Provisioning	Network connectivity optimization evolution: Top of rack (TOR), end of rack (EOR), connectivity.

S-7	SLO-1	Performance	Virtualization Support and Disaster Recovery	Hybrid storage networking technologies	Popularity-Driven Resource Provisioning	Stand-alone, blades, stateless,
	SLO-2	Security and disaster recovery	Server Virtualization	iSCSI, FCIP, FCoE	Dynamic Resource Deployment	clustering
S-8	SLO-1	Next generation of Cloud Applications.	Parallel Processing	Design for storage virtualization in cloud computing	Storage-as-a-Service	scaling
	SLO-2	Virtualization	Vector Processing	host system design considerations	Advantages of Cloud Storage - Global Exchange of Cloud Resources	optimization, virtualization.
S-9	SLO-1	Types of virtualization in cloud computing	Symmetric Multiprocessing Systems	Cloud Applications	Application Development	Limitation of traditional server deployments
	SLO-2	Advantages and Disadvantages	Massively Parallel Processing Systems	Technologies and the processes required when deploying web services	Service creation environments to develop cloud based applications	Case studies

Learning Resources	1. Gautam Shroff, "Enterprise Cloud Computing Technology Architecture Applications", Cambridge University Press; 1 edition, [ISBN: 978-0521137355], 2010.	6. Klaus Schmidt, "High Availability and Disaster Recovery" Springer; edition [ISBN: 978-3540244608], 2006.
	2. Toby Velle, Anthony Velle, Robert Elsenpeter, "Cloud Computing, A Practical Approach" McGraw-Hill Osborne Media; 1 edition [ISBN: 0071626948], 2009	7. Kai Hwang, Geoffrey C. Fox, Jack G. Dongarra, "Distributed and Cloud Computing, From Parallel Processing to the Internet of Things", Morgan Kaufmann Publishers, 2012.
	3. Greg Schulz, "Cloud and Virtual Data Storage Networking", Auerbach Publications [ISBN: 978-1439851739], 2011	8. Rittinghouse, John W., and James F. Ransome, —Cloud Computing: Implementation, Management and Security II, CRC Press, 2017.
	4. EMC, "Information Storage and Management" Wiley; 2 edition [ISBN: 978-0470294215], 2012.	9. Silvano Gai, Claudio De Santi, "I/O Consolidation in the Data Center" Cisco Press; 1 edition [ISBN: 9781587058882], 2009.
	5. Volker Herminghaus, Albrecht Scriba, "Storage Management in Data Centers" Springer; edition N [ISBN: 978-3540850229], 2009.	10. 2. Bill Wilder, Cloud Architecture patterns, 2012

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50%)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. Anil Nayer, JPA solutions	Dr. Kanagachidambaresan, Professor, PSG-Tech	Mr K. Venkatesh, SRMIST
		Dr Ramamoorthy, SRMIST
		Mr Vinoth, SRMIST

Course Code	18CSE441T	Course Name	CLOUD APPLICATION DEVELOPMENT	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1:	Utilize the different types of cloud services	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2:	Utilize the different storage services	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3:	Utilize different algorithms for cloud computing	Expected Proficiency (%)	Problem Analysis
CLR-4:	Utilize virtualization techniques	Expected Attainment (%)	Design & Development
CLR-5:	Utilize real-time cloud services from different vendors		Analysis, Design, Research
CLR-6:	Utilize and understand cloud services with real-time cloud applications		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1:	Understand different cloud architecture and models	3 80 70	L H - H L - - - L L - H - - -
CLO-2:	Create the different types of cloud applications using different languages	3 85 75	M H L M L - - - M L - H - - -
CLO-3:	Understand the concepts of virtualization	3 75 70	M H M H L - - - M L - H - - -
CLO-4:	Create simple cloud applications and deploy	3 85 80	M H M H L - - - M L - H - - -
CLO-5:	Understanding cloud application paradigms	3 85 75	H H M H L - - - M L - H - - -
CLO-6:	Analyze different cloud technologies and its implementations	3 80 70	L H - H L - - - L L - H - - -

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Introduction to cloud computing	Cloud Computing: Applications	Server virtualization	Amazon Web Services: EC2 Instances
	SLO-2	Cloud deployment models	Challenges for Cloud Computing	Hypervisor- based virtualization	Connecting Clients to Cloud Instances Through Firewalls
S-2	SLO-1	business drivers for Cloud Computing	Existing Cloud Applications and New Application Opportunities	Techniques for Hypervisor	Security Rules for Application Layer Protocols in EC2
	SLO-2	cloud computing Delivery Models	Architectural Styles for Cloud Applications	Hardware support for Virtualization	Security Rules for Transport Layer Protocols in EC2
S-3	SLO-1	cloud computing Services	Workflows: Coordination of Multiple Activities	VMware virtualization software	How to Launch an EC2 Linux Instance and Connect to it
	SLO-2	challenges of cloud computing	Coordination Based on a State Machine Model	XenServer Virtual Machine Monitor	How to Use S3 in Java
S-4	SLO-1	Cloud Infrastructure : cloud computing at Amazon	The Zookeeper	Storage Virtualization	How to Manage SQS Services in C#
	SLO-2	Cloud computing The Google perspective	Scalable data storage techniques	File virtualization	How to Install the Simple Notification Service on Ubuntu
S-5	SLO-1	Microsoft Windows Azure	The MapReduce Programming Model	Example	Example
	SLO-2	Microsoft Windows Azure services	RIAs, simple Hello world example	Block Virtualization	How to Create an EC2 Placement Group
S-6	SLO-1	Open-Source Software Platforms for Private Clouds	Client-server example , RSS Feed Reader	Examples	How to Use MPI
	SLO-2	Cloud Storage Diversity, Cloud Storage Vendor lock-in	Advanced platform functionality	Grid Computing	Hadoop Ecosystem
S-7	SLO-1	Cloud Computing Inter-operability	Clouds for Science and Engineering	Grid Technologies	How to Install Hadoop on Eclipse on a
	SLO-2				Salesforce.com

					Windows System	
S-8	SLO-1	The inter cloud , Responsibilities of User	High-Performance Computing on a Cloud , social Computing , Digital Content	comparing Grid and Cloud	Cloud-Based Simulation of a Distributed Trust Algorithm	Social Computing services : What Constitutes Social computing?, Case study - Facebook
	SLO-2					
S-9	SLO-1	Responsibilities of service provider	Cloud computing	Creating sample hello world application in OpenShift	A Cloud Service for Adaptive Data Streaming	Micro Blogger : Twitter
	SLO-2	Responsibility Sharing Between User and Cloud Service Provide	A Case Study: The GrepTheWeb Application	Example	Cloud-Based Optimal FPGA Synthesis	Document services

Learning Resources	1. Dinkar Sitaram, Geetha Manjunath, Moving To The Cloud: Developing Apps in the New World of Cloud Computing, Syngress,2013. 2. DanC.Marinescu,CloudComputing:TheoryandPractice.,MorganKaufman,2013	3. AMichael P. McGrath, Understanding PaaS: Unleash the Power of Cloud Computing, O'Reilly Media,2012.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50%								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. Venkatesh Varalu, New YorkTimes, USA	Dr. Balaraman Ravindran, Professor, IITM	Mr. Venkatesh, SRMIST Dr Pradeep Mohan Kumar, SRMIST Mrs Krishnaven, SRMISTI

Course Code	18CSE442T	Course Name	CLOUD SECURITY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	To understand the concept of cloud security	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	The issues related to virtualized infrastructure security	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	To have knowledge on the various issue in cloud security	Expected Proficiency (%)	Problem Analysis
CLR-4 :	To Learn the methods to improve virtualization security and technologies in security	Expected Attainment (%)	Design & Development
CLR-5 :	Understand the cloud contracting Model and case study of commercial cloud		Analysis, Design, Research
			Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Articulate the main concepts of cloud security	3 80 70	L H L H L M H L L L L H H L H L
CLO-2 :	Explain the architecture design of cloud storage.	3 85 75	H H L M L M H L M L H H L H L
CLO-3 :	Explain the core issues of cloud management and security	3 75 70	H H H H H M L L M L M H M M M
CLO-4 :	Be able to install and use current cloud Technologies.	3 85 80	H H H H H L L L M L M H L L H
CLO-5 :	Apply secure design for cloud Models	3 85 75	H H H H H L L L M L M H L M L

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Cloud Security Fundamentals- Infrastructure Security	Layered Cloud Architecture Design	Confidentiality, privacy, integrity, authentication,	IBM security virtual server protection
	SLO-2	Network level security			Authentication in cloud computing
S-2	SLO-1	Host level security	NIST cloud computing Reference Architecture	non-repudiation, availability,	virtualization-based sandboxing
	SLO-2	Application level security			Client access in cloud
S-3	SLO-1	Data security and Storage	Public ,Private and Hybrid Cloud	access control, defence in depth, least privilege,	Cloud Storage
	SLO-2		IaaS,PaaS,SaaS		Cloud contracting Model
S-4	SLO-1	Data privacy and security Issues,	Architectural design Challenges	How these concepts apply in the cloud, what these concepts mean and their importance in PaaS, IaaS and SaaS.	Security- HIDPS
	SLO-2				Commercial and business considerations
S-5	SLO-1	Jurisdictional issues raised by Data location	Cloud Storage	Cryptographic Systems- Symmetric cryptography	log management
	SLO-2				Case Study on Open Source & Commercial Clouds
S-6	SLO-1	Identity & Access Management	Storage-as-a-service	stream ciphers, block ciphers, modes of operation	Data Loss Prevention
	SLO-2				X.509 certificates, OpenSSL.
S-7	SLO-1	Access Control	Advantages of Cloud storage	Public-key cryptography, hashing	Security Governance
	SLO-2				Eucalyptus
S-8	SLO-1	Trust, Reputation	Cloud storage Provider	digital signatures, public-key infrastructures	Cloud security Challenges
	SLO-2				Microsoft Azure
S-9	SLO-1	Risk	Storage Provider-S3	key management	Virtual Machine Security
	SLO-2				Amazon EC2

Learning Resources	<ol style="list-style-type: none"> 1. Tim Mather, SubraKumaraswamy, ShahedLatif, "Cloud Security and Privacy:An Enterprise Perspective on Risks and Compliance" O'Reilly Media; 1edition [ISBN: 0596802765], 2009. 2. Rittinghouse, John W., and James F. Ransome, —Cloud Computing: Implementation, Management and Security, CRC Press, 2017. 3. Kai Hwang, Geoffrey C Fox, Jack G Dongarra, "Distributed and Cloud Computing, From Parallel Processing to the Internet of Things", Morgan Kaufmann Publishers, 2012. 4. Ronald L. Krutz, Russell Dean Vines. "Cloud Security" [ISBN: 0470589876],2010. 5. Toby Velte, Anthony Velte, Robert Elsenpeter, "Cloud Computing – A Practical Approach, Tata Mcgraw Hill, 2009. 6. George Reese, "Cloud Application Architectures: Building Applications and Infrastructure in the Cloud: Transactional Systems for EC2 and Beyond (Theory in Practice), O'Reilly, 2009.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100%	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr.T.Madhan, Team Leader, Tata Consultancy Services, siruseri Campus, Chennai.	Dr. R.Shyamala, Associate Professor [HOD-IT], Anna University College of Engineering Tindivanam.	1. Dr.R.Naresh
		2. Dr.MB.Mukesh krishnan

Course Code	18CSE443T	Course Name	BIG DATA ANALYTICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)															
CLR-1 :	Quick and easy approach to learn the fundamental concept of big data analytics				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLR-2 :	Understand the concept of Hadoop and installation				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3	
CLR-3 :	Get to know the concept of key value pair programming																						
CLR-4 :	Learn about Map Reduce and its features																						
CLR-5 :	Understanding and solving of case studies																						
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																					
CLO-1 :	The main objective is to provide the students the knowledge of big data analytics				1	90	85	L	-	-	M	-	-	-	-	-	-	-	H	L	-	-	
CLO-2 :	The students are trained to have knowledge about the architecture, installation and command execution of Hadoop				3	85	80	M	M	H	H	H	-	-	-	-	-	-	-	H	M	H	-
CLO-3 :	Able to develop a Map Reduce application				3	85	80	M	H	H	H	H	-	-	-	-	-	-	H	M	H	-	
CLO-4 :	Identify knowledge of Map Reduce and develop real world map reduce application				3	80	75	M	H	H	H	H	-	-	-	-	-	-	H	H	H	-	
CLO-5 :	Apply knowledge and solve various case study problems				3	80	75	H	H	H	H	H	H	-	M	-	-	-	H	M	H	H	

	SLO-2					
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Learning Resources	<ol style="list-style-type: none"> 1. Michael Minelli, Michele Chambers, Ambiga Dhiraj, "BigData, BigAnalytics-Emerging Business Intelligence and Analytic Trends for Today's Businesses", Wiley. 2. Tom White, "Hadoop-The Definitive Guide", O'Reilly 3. Frank Ohlhorst, "BigData Analytics-Turning BigData into BigMoney", Wiley 4. Alan Aderson, David Semmelroth, "Statistics for BigData for Dummies", John Wiley & sons
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50%)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Understand	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
		Dr. B. Amutha, Professor and Head, Department of CSE, SRM IST
		Dr. G. Vadivu, Professor and Head, Department of IT, SRM IST

Course Code	18CSE444T	Course Name	CLOUD STRATEGY PLANNING AND MANAGEMENT	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	To learn the concepts and technological advances fueling the rapid adoption of cloud computing today.	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	To provide the students with the skills and knowledge required to plan and manage a Cloud Computing strategy within an organization.	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	To enable students to evaluate the strategic value of Cloud Computing using IT Governance and Compliance.				H	-	-	-	-	-	-	-	-	-	-	-	-	-	-
					H	H	-	-	-	-	-	-	-	-	-	-	-	-	-
					H	-	-	-	-	-	-	-	-	-	-	-	-	-	-
					H	H	-	-	-	-	-	-	-	-	-	-	-	-	-
					H	-	-	H	-	-	-	-	-	-	-	-	-	-	-
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Strategically assess how cloud computing enables IT Transformation and business value in an organization.	2	80	85															
CLO-2 :	Analyze the role that cloud computing can play in the business process.	2	75	80															
CLO-3 :	Evaluate how cloud computing and Service Oriented Architecture (SOA) can deliver business agility.	2	85	80															
CLO-4 :	Implement IT governance to manage business realization from cloud IT services.	2	80	75															
CLO-5 :	Critically appraise how the incorporation of cloud computing in an IT strategy can deliver on strategic business objectives.	2	75	85															

Duration (hour)	9	9	9	9	9
S-1	SLO-1	The four pillars of cloud computing	Moving to a cloud architecture and strategy to achieve business value.	Develop an IT strategy to deliver on strategic business objectives in the business strategy	Shared services delivered by a Service Oriented Architecture (SOA) in a Private or Public Cloud
	SLO-2	Cloud applications and Platforms			Benefit Realization and it Governance
S-2	SLO-1	Providing the cloud infrastructure	BPM, IS, Porter's Value chain model and BPR as a means of delivering business value	IT Project planning in the areas of ITaaS is essential in delivering a successful strategic IT Plan	Services, Databases and Applications on demand
	SLO-2	Cloud computing, Spectral efficiency, Sensors and perspiration			Managing resources (people, process, technology), to realize benefit from Private/Public Cloud IT services
S-3	SLO-1	Strategic inflection points in information Technology	Developing Business Strategy: Investigate business strategy models to gain competitive advantage for organizations	IT Project planning in the areas of SaaS is essential in delivering a successful strategic IT Plan	The effect on Enterprise Architecture and its traditional frameworks such as Zachman).
	SLO-2	Cloud computing and its slogans	SWOT/PEST, Economies of scale, Porter's 3 Strategies and 5 Competitive Forces, D'Aveni's hyper competition models	IT Project planning in the areas of PaaS is essential in delivering a successful strategic IT Plan	Gartner's 5 pillars of benefit realization
S-4	SLO-1	User centered solution and cloud computing	Emphasize the roles of the strategic IS/IT leaders such as Chief Information Officer (CIO)	IT Project planning in the areas of IaaS is essential in delivering a successful strategic IT Plan	IT governance as a service in measuring the delivery of IT Strategy from Cloud IT Services using Sarbanes Oxley (CobiT) and other commonly-used approaches
	SLO-2	For cloud vendors inflection point is risk and opportunity			The Open Group Architecture Framework (TOGAF).
S-5	SLO-1	Potential customers of cloud technology	The Chief Technology Officer (CTO) in planning and managing IT Strategic development in the organization.	Searching for an open architecture	Customer Relationship Management
	SLO-2				Enterprise Resource Planning
S-6	SLO-1	The cloud interests Small and Medium enterprises	Budgeting for cloud computing	Infrastructure as a Utility	Just-in-Time Inventories
	SLO-2				Leadership Is based on Fundamentals
S-7	SLO-1	Virtual companies and the cloud	Service level agreements	Cloud System Architecture and its primitives	Machine-to-Machine and RFID Communications
	SLO-2	Virtual networked objects			Cloud Software For Asset Management

S-8	SLO-1	Consumer technologies and the cloud	Outsourcing, Infrastructural inter dependencies, and the cloud	The User Organizations Business Architecture	Challenges Presented by Organization	Cloud Technology can Improve Fund Management
S-9	SLO-2	Social networks and multimedia messaging	Human resources at the CIO level <i>The transition from legacy to competitive system</i>	Financial Services Applications Architecture	Challenges Presented by Commercial vision	Criteria of Success in Asset Management Technology

Learning Resources	1. Dimitris N. Chorafas: <i>Cloud Computing Strategies</i> , CRC Press, 2011. 2. Arnold J Cummins, "Easiest Ever Guide to Strategic IT Planning" http://strategicitplanningguide.com/ . 3. David S. Linthicum, "Cloud Computing and SOA Convergence in Your Enterprise", Addison Wesley [ISBN: 0136009220], 2009. 4. Charles Babcock, "Management Strategies for the Cloud Revolution", 1st Ed., Tata McGraw/Hill [ISBN: 0071740759], 2010.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr.Saju G Nair, IBM,Bangalore,sajugnair@gmail.com	Dr.Khanna Nehemiah H, Professor, Ramanujan Computing Centre, Anna University	Mrs.J D Dorathi Jayaseeli,CSE,SRM IST

Course Code	18CSE375T	Course Name	DISTRIBUTED COMPUTING			Course Category	E	Professional Elective				L	T	P	C
												3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering	CSE		Data Book /	Nil	

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Layout foundations of Distributed Systems.				Level of Thinking (Bloom)	2	Expected Proficiency (%)	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLR-2 :	Get familiar with the idea of middleware and related issues																							
CLR-3 :	Understand in detail the system level and support required for distributed system																							
CLR-4 :	Understand the issues involved in studying data and cryptographic algorithms																							
CLR-5 :	Expose to the concept of design and implementation of distributed file systems																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1 :	Fundamentals of Distributed System Concepts and access System				2		80	85	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-2 :	An ability to familiar with various architecture models and Distributed File access techniques				2		75	80	H	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-3 :	An ability to understand the security aspects of distributed system				2		85	80	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction to Distributed Systems	Distributed Computing Model	Remote Procedure Call	Introduction of Security systems in distributed system	Distributed File Systems –Introduction
	SLO-2				Potential attacks and threats on computer systems	
S-2	SLO-1	Characterization of Distributed Systems	Workstation model	Remote method invocation	Cryptography	File Service Architecture
	SLO-2	Examples of Distributed Systems	Workstation server model		Symmetric cryptosystem algorithm –DES	
S-3	SLO-1	Architecture of Distributed Systems	Process pool model	Client server model basics concepts	Asymmetric cryptosystems	File Models
	SLO-2	Shared and Distributed Memory Architecture	Comparison of Distributed computing model	Client server addressing		
S-4	SLO-1	Focus on resource sharing the web	Interprocess Communication	Client server implementations	Secure Channels-Authentication	DFS Design
	SLO-2				Message Integrity and confidentiality	
S-5	SLO-1	Challenges in Distributed Systems	External data representation and multicast Communication	Client Server Architecture	Access control	DFS implementation
	SLO-2					
S-6	SLO-1	Design issues in Distributed systems	API for Internet protocol	Group Communication publish and subscribe systems	Security Management	File catching in DFS
	SLO-2				Issues in key distribution	
S-7	SLO-1	Networking and Internetworking basic introduction Types of Network	Network Virtualization and overlay networks	Shared memory approach	Secure group management	Implementation in DFS
	SLO-2			Distributed objects	Authorization management	
S-8	SLO-1	Network Principles	Case Study : interprocess Communication in UNIX	Case study : java RMI	Case study - Kerberos	Case study – Sun network File systems
	SLO-2					
S-9	SLO-1	Internet protocol	Case study - MPI	Case Study - CORBA	Case study - Epayment	Case study - Google File systems
	SLO-2					

Learning Resources	1. GeorgeCoulouris, JeanDollimore, TimKindberg, "DistributedSystemsConceptsandDesign" Fifth edition – 2011- AddisonWesley 2. SunitaMahajan, SeemaShah, "DistributedComputing" SecoundEdition–OxfordPress	3. Liu M.L., "Distributed Computing, Principles and Applications", Pearson and education, 2004. 4. Tanenbaum A.S., Van Steen M., " Distributed Systems: Principles and Paradigms", PearsonEducation, 2007.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50%)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. M.Ravichandran, CEO, Terafast	1.. Dr.K.Vivekanadan, Professor, PEC, k.vivekanandan@pec.edu	1. Dr. A.Murugan , SRMIST
		2. Dr. G.Maragatham, SRMIST 3. Ms. S. Aruna , SRMIST

Course Code	18CSE376T	Course Name	OPTICAL NETWORKS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	CSE	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1:	Study the fundamentals of optical networks	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2:	Gather knowledge about different types of components	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3:	Learn single hop and multi hop networks	Expected Proficiency (%)	Problem Analysis
CLR-4:	Acquire knowledge about different WDM network design	Expected Attainment (%)	Design & Development
CLR-5:	Understand about OADM architecture		Analysis, Design, Research
CLR-6:	Gather knowledge about optical TDM and CDMA		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1:	Acquire knowledge about basic fundamentals of optical networks	2 80 85	H - - - - - - - - - - - - - - -
CLO-2:	Understand various classifications of optical components	2 75 80	H H - - - - - - - - - - - - - - -
CLO-3:	Develop the ability to apply optical concepts in single and multihop networks	2 85 80	H - - - - - - - - - - - - - - -
CLO-4:	Gather knowledge about various multiplexing techniques	2 80 75	H H - - - - - - - - - - - - - - -
CLO-5:	Acquire knowledge about OADM concept	2 75 85	H - - H - - - - - - - - - - - - - - -
CLO-6:	Apply various techniques to handle spectrum with a different perspective	2 80 85	H - - - - - - - - - - - - - - -

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Introduction to optical networks	Components :Couplers – Principle of operation	Broadcast optical networks – characteristics of single hop networks	WDM Network Elements :Optical line terminals
	SLO-2	TeleCommunication Network Architecture and services	Conservation of energy	Experimental WDM Systems	optical line amplifiers
S-2	SLO-1	Optical Networks- Multiplexing Techniques	Isolators	Other Non – Pretransmission Coordination protocols	Optical Add/Drop Multiplexers
	SLO-2	Second Generation Optical Networks	Circulators	Pretransmission coordination protocols	OADM Architecture
S-3	SLO-1	Optical Layer	Multiplexers – Gratings, Diffraction Patterns	Special Case: Linear Bus with Attempt- and-Defer Nodes	Optical crossconnects
	SLO-2	Optical packet switching	Bragg and Fiber Gratings	AMTRAC and multichannel probabilistic scheduling	OXC Configurations
S-4	SLO-1	Transmission Basics – wavelengths, Frequencies, and channel spacing	Filters – fabryperot filters	Single- Hop Case study : IBM Rainbow Protocol	WDM Network Design: Cost trade-offs
	SLO-2	Standards, optical power and loss	Mach-Zehnder Interferometers, Arrayed Waveguide gratings	Model, Analysis	LTD and RWA problems
S-5	SLO-1	WDM Networking Evolutions	Optical Amplifiers – Emissions	Multihop Networks: characteristics, topological optimization studies	Light path topology design
	SLO-2	WDM Network Constructions	Erbium -Doped fiber amplifiers, Raman Amplifiers and Semiconductor optical amplifiers	Regular structures	Routing and wavelength assignment and conversion
S-6	SLO-1	Optical Fiber- Transmission	Transmitters – Lasers, Light emitting diodes,tunable lasers	Near- Optimal Node Placement	Dimensioning Wavelength
	SLO-2	Single mode vs Multimode fiber	Direct and external modulation, pump sources	Shared- channel multihop systems	Routing Networks
S-7	SLO-1	Attenuation in Fiber	Detectors – photo detectors	Multihop case study – GEMNET	Statistical Dimensioning Models : First passage model
	SLO-2	Dispersion in Fiber	Front end amplifiers	GEMNET Architecture and properties	Blocking model

S-8	SLO-1	Non Linear Effects – self phase modulation	Switches – large optical switches, optical switch technologies	Channel sharing	Maximum load dimensioning model : offline lightpath requests	Spread spectrum
	SLO-2	Cross phase modulation	Large electronic switches	Multicasting	Online RWA in rings	Code sequences
S-9	SLO-1	Solitons	Wavelength converters – optoelectronic Approach, optical gating	Shared – channel Multihop GEMNET	Access Networks : Network Architecture overview	CDMA Example
	SLO-2	Dispersion- Managed Solitons	Interferometric techniques, wave mixing	Performance Evaluation	Enhanced HFC	Optical CDMA

Learning Resources	1. Rajiv Ramaswami, Kumar N. Sivarajan, Galen H. Sasaki, Optical Networks A Practical Perspective, third Edition 2. Optical Switching Networks: Mayer & Martin, Cambridge University Press, 2008.	3. U.Black, "Optical Networks: Third Generation Transport Systems"/Pearson Education 4. R.Ramaswami, & K.N.Sivarajan, "Optical Networks a Practical perspective", Morgan Kaufmann Publishers, 3rd Ed.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50%)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Evaluate Create	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Madhumaran, NOKIA digital and Networking, Technical Lead, p.madhumaran@nokia.com	1. Prof. Nilanjan Dey, Techno India College of Technology, Kolkata, nilanjan.dey@tict.edu.in	1. Prof. V.Sivakumar, SRMIST
2. Mr. N.Ramkumar, TCS Assistant Consultant, ram.kumam@tcs.com	2. Prof. E.Rajesh, Galgotias University, Delhi, rajesh.e@galgotiasuniversity.edu.in	2. Prof. P.Visalakshi, SRMIST

Course Code	18CSE379T	Course Name	INTERNET OF THINGS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	CSE	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand the basic concepts of IoT and its possible application areas				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Understand the various IoT architectures along with compute and management stack across layers				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO – 3
CLR-3 :	Understand the architecture dissected at physical, Communication and Access levels																					
CLR-4 :	Introduce existing toolkits, available platforms, boards, software and laguages for easy development of IoT products																					
CLR-5 :	Understand the various enabling technologies for IoT including Big data analytics, Machine learning, Cloud and Streaming analytics																					
CLR-6 :	Understand the underlying business model for IoT and also acquire skills for DiY (Do it Yourself)																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	Appreciate the omnipotent presence of IoT in all fields across globe				2	80	85	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-2 :	Compare and contrast various architectures and be able to justify the right choice for adoption				2	75	80	H	H	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-3 :	Choose appropriate protocols for various levels/layers based on the requirement in hand				2	85	80	H	M	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-4 :	Implement using the available resources and demonstrate quick to deployment sills wherever applicable				2	80	75	H	H	H	M	-	-	-	-	-	-	-	-	-	-	-
CLO-5 :	Apply the tools and techniques towards integration in relevant areas of IoT product development				2	75	85	H	M	H	M	H	-	-	-	M	-	-	H	-	-	-
CLO-6 :	Showcase DiY approach given any implementable idea to product				2	80	85	H	M	H	H	H	-	-	-	H	-	-	H	-	-	-

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction to IOT	Drivers Behind New Network Architectures	Smart Objects: The “Things” in IoT	Data Analytics for IoT- Overview	Business Models for IoT: Introduction
	SLO-2	What, Where and How of IoT?	Comparing IoT Architectures	Sensors, Actuators, and Smart Objects	IoT Data Analytics Challenges	Business Models
S-2	SLO-1	Data Flow of IoT	The IoT World Forum (IoTWF) Standardized Architecture	Micro-Electro-Mechanical Systems (MEMS)	Relevance of ML and IoT- Overview	Business Model Innovation
	SLO-2	Definition and characteristics of IOT	IT and OT Responsibilities in the IoT Reference Model	Smart Objects,Smart Objects: A Definition	Relevance of Big data and IoT- Overview	Value Creation in IoT
S-3	SLO-1	Architecture of Internet of Things: Physical-Things	A simplified IoT architecture	Trends in Smart Objects	ML and getting Intelligence from Big Data	Laws of Information
	SLO-2	Architecture of Internet of Things: Protocols-an Introduction	The core IoT functional stack	Sensor Networks	Big data analytics tools and techniques for IoT: Overview	Revenue Generation in the Internet of Things
S-4	SLO-1	Architecture of Internet of Things: Logical-Functional Blocks	Layer 1: Things: Sensors Layer	Wireless Sensor Networks (WSNs)	MPP, NoSQL	Exemplary Business Model Scenarios for the Internet of Things
	SLO-2	Architecture of Internet of Things: Logical-Communication Models	Layer 1: Things: Actuators Layer	Communication Protocols for WirelessSensor Networks- a Introduction	Hadoop and YARN	Scenario 1: Product as a Service (PaaS)
S-5	SLO-1	Architecture of Internet of Things: Logical-Communication API	Layer 2: Communications Network Layer: Access, Gateway	Communication Criteria- Introduction	Hadoop Eco system	Scenario 2: Information Service Providers
	SLO-2	IOT enabling technologies	Layer 2: Communications Network Layer: Network, Management	Communication Criteria- Definitions	Apache Kafk, Spark, Storm, Flink,	Scenario 3: End-user Involvement
S-6	SLO-1	Introduction to IoT Levels and Deployments	Layer 3: Applications and Analytics Layer:	IoT Access Technologies-Introduction	Lamba Architecture	Scenario 4: Right-time Business Analysis and Decision making
	SLO-2	IoT Deployment Levels: 1 to 6	Analytics Versus Control Applications,	IoT Access Technologies-Definitions	Edge Streaming Analytics for IoT	DIY- Smart Experience (DIYSE) Projects- a introduction

S-7	SLO-1	IoT Security and Privacy	Data Versus Network Analytics	IoT Application transport methods- Definitions	Edge Analytics core functions	Requirements for Enabling DiY in Eco- awareness Applications
	SLO-2	IoT Data Analytics, Protocols	Data Analytics Versus Business Benefits	The Toolkit Approach for End-user Participation in the Internet of Things:	Distributed analytics systems	Technologies and Standards Relevant for DiY Eco-awareness
S-8	SLO-1	IoT Environmental challenges: excess waste disposal	Smart Services	Existing Toolkits	Network Analytics	Sensor-actuator Technologies and Middleware as a Basis for a DiY Service Creation Framework
	SLO-2	Legal Challenges for a Privacy Framework- an IoT perspective	IoT Data Management And Compute Stack: The Hierarchy Of Edge, Fog, And Cloud	I/O Boards	IoT physical servers and cloud offerings (Cloud computing for IoT)	Device Integration, Middleware Technologies
S-9	SLO-1	Privacy Enhancing Technologies for IoT	Fog Computing	HW Based Systems, Introduction to Open source boards (Arduino, Raspberry Pi and other variants)	Relevance of Cloud connectivity and IoT- Overview	Semantic Interoperability- a requirement for IoT DiY
	SLO-2	Case Studies: Domain specific IOT Applications	Edge Computing	SW Based Solutions	Logical design using Python, Useful IoT libraries	DiY Smart Experiences Service Framework-an Introduction

Learning Resources	1. ArshdeepBahga, Vijay Madiseti, "Internet of Things, A Hands -on Approach", 1st Edition 2015, University Press, ISBN: 978-81-7371-954-7 2. InternetofThings:LegalPerspectivesbyRolfH.Weber,RomanaWeber,Springer,2010 3. Uckelmann, D., Harrison, M., & Michahelles, F. (Eds.). Architecting the Internet of Things.doi:10.1007/978-3-642-19157-2 ,2011	4. IoT Fundamentals: Networking Technologies, Protocols, and Use Cases for the Internet of Things by Rob Barton, Gonzalo Salgueiro, David Hanes, Publisher: Cisco Press, Release Date: June 2017, ISBN: 9780134307091 (https://www.oreilly.com/library/view/iot-fundamentals-networking/9780134307091/)

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50%)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Dr. Pavanthan Arumugum, Director (R&D), ERNET India	Dr. S. Srinivasan, Professor and Head, Dept. of Computer Science & Engineering, Anna University, Madurai	Dr.Kayalvizhi Jayavel, SRMIST
Mr. Vinay Solanki, Head IoT, Lenovo (APAC & MEA)	Dr. R. Krishnamoorthy, Professor, Department of CSE and IT, BIT Campus, Anna University, Trichy	Dr. Sreekumar, SRMIST
Mr.Hariharan Ramalingam, Vertical Delivery Head, Wipro ltd	Dr.S.Chithra Selvaraj, Associate Professor, Department of IT, SSN College of Engineering	Mr.V.Haribaabu, SRMIST

Course Code	18CSE380T	Course Name	PERVASIVE COMPUTING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:		Learning		
CLR-1 :	Understanding the basics of pervasive computing and its application			1	2	3
CLR-2 :	Gain knowledge on the voice enabling			Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)
CLR-3 :	Understand the fundamental elements of pervasive computing.					
CLR-4 :	Learn the design process of Pervasive Computing Environments and its solutions					
CLR-5 :	Familiarize with device connectivity & web applications concepts					
CLR-6 :	Introduce the concepts of wearale computing and security in pervasive computing					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:				
CLO-1 :	Understand the fundamental elements of pervasive computing.			2	80	85
CLO-2 :	Learn the design process of Pervasive Computing Environments and its solutions			2	75	80
CLO-3 :	Familiarize hardware, software and the aspects involved in pervasive computing			2	80	85
CLO-4 :	Apply the knowledge for implementing security			2	80	75
CLO-5 :	Organize the functionalities and components of PDA in pervasive computing.			2	75	85
CLO-6 :	Describe the user interface issues in pervasive computing.			2	75	80

Program Learning Outcomes (PLO)																	
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15			
Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO – 3			
H	-	-	-	-	-	-	-	-	-	-	-	-	-	-			
H	-	-	-	-	-	-	-	-	-	-	-	-	-	-			
H	-	-	-	-	-	-	-	-	-	-	-	-	-	-			
H	H	-	-	-	-	-	-	-	-	-	-	-	-	-			
H	-	-	H	-	-	-	-	-	-	-	-	-	-	-			
H	-	-	M	-	-	-	-	-	-	-	-	-	-	-			

Duration (hour)	9	9	9	9	9
S-1	SLO-1	- INTRODUCTION	Device connectivity	WAP & VOICE TECHNOLOGY, WAP and Beyond: Introduction	Wearable Computing and Sensor Systems for Healthcare - Introduction
	SLO-2	Pervasive Computing: Past, Present and Future Pervasive computing	Protocols: wireless	Components of the WAP	The Health Body Area Network
S-2	SLO-1	Pervasive Computing Market,	mobile phone technologies	architecture	Medical and Technological Requirements of Health Sensors
	SLO-2	m-Business	mobile phone technologies	WAP infrastructure,	Wearable Sensors for Vital Signals Monitoring
S-3	SLO-1	Application examples: Retail,	mobile internet protocol	WAP security issues	Wearable Sensors for Activity Recognition
	SLO-2	Application examples: Airline check-in and booking,	mobile internet protocol	Wireless Markup Language	Sensors and Signals for Emotion Recognition
S-4	SLO-1	Healthcare	Synchronization and replication protocol	WAP push	ntra-BAN Communications in Pervasive Healthcare Systems: Standards and Protocols - IEEE 802.15.4 and ZigBee
	SLO-2	Tracking, Car information system,	Synchronization and replication protocol	Products	Bluetooth
	SLO-1	Sales Force Automation		i-Mode	Bluetooth Low Energy
S-5	SLO-2	Email access via WAP and voice	distributed services	VoiceTechnology: Basics of Speech recognition,	Integrated and Additional Solutions for Health BAN Communications
S-6	SLO-1	A Pervasive System for Volcano Monitoring	distributed message	VoiceTechnology: Basics of Speech recognition,	Introduction - Pervasiveness and Mobility in Computing and Communications

	SLO-2	A Pervasive Computing Platform for Individualized Higher Education	transaction protocols	Voice Standards	Context Awareness	Challenges to Privacy Protection
S-7	SLO-1	Device Technology	Security	Voice Standards	Heterogeneity	Location Dependency
	SLO-2	Hardware,	Device Management		Wireless Technologies and Standards	Data Collection
S-8	SLO-1	Human machine interface	Web Application Concepts: WWW Architecture	Speech Applications,	Middleware	Internet Service Provider (ISP) Role
	SLO-2	Bio metrics,	Protocols	Speech Applications,	Future Trends: Beyond the Middleware	Data Ownership Private Systems
S-9	SLO-1	Operating systems	Transcoding	Speech and Pervasive Computing	Pervasive Computing in Extreme Areas; The Hiker's Personal Digital Assistant	Quality of Privacy (QoP)
	SLO-2	Java for pervasive devices	Client Authentication via Internet	Speech and Pervasive Computing	Pervasive Computing in Personal Health Systems; The MyHealthService Approach	Open Issues in Privacy of Systems 'Sharing' in Personal Networks

Learning Resources	<ol style="list-style-type: none"> 1. JochenBurkhardt, Horst Henn, Stefan Hepper, Thomas Schaech & Klaus Rindtorff, "Pervasive Computing, Technology and Architecture of Mobile Internet Applications", Pearson Education, 2012. ISBN-13: 978-0201722154 2. UweHansmann, L. Merk, M. Nicklous, T. Stober, U. Hansmann, "Pervasive Computing (Springer Professional Computing) ", 2003, Springer Verlag, ISBN:3540002189 3. S. Poslad, "Ubiquitous Computing: Smart Devices, Environments and Interactions," Wiley, 2009 	<ol style="list-style-type: none"> 4. Frank Adelstein, Sandeep KS Gupta, Golden Richard III, Loren Schwiebert, "Fundamentals of Mobile and Pervasive Computing", McGraw Hill edition, 2006. ISBN-13: 978-0071412377
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Evaluate Create	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Suganya Anbumani Director of Engineering, Wealth Management, Redi2 Technologies Greater Boston Area	1. Dr. J. Prakash, MIT, Chennai, prakaiit@rediffmail.com	1. Dr. V. Kavitha, SRMIST
Saranya A T Associate at Cognizant Chennai	2. Dr. Latha Karthigaa, PhD , Innovation Research Assistant, The University of Auckland	2. Mr. Haribaabu V, SRMIST

Course Code	18CSE381T	Course Name	CRYPTOGRAPHY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand OSI security architecture and classical encryption techniques.	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Acquire fundamental knowledge on the concepts of finite fields and number theory	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Understand various block cipher and stream cipher models																		
CLR-4 :	Describe the principles of public key cryptosystems, hash functions and digital signature.																		
CLR-5 :	Gain a first-hand experience on encryption algorithms, encryption modes.																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Implement the Classical Encryption Techniques.	2	80	85	H									H					
CLO-2 :	Comprehend fundamental concepts of finite field and number theory.	2	75	80	H														
CLO-3 :	Categorize block cipher modes of operation and comprehend digital signature functions	2	85	80	H														
CLO-4 :	Implement Public Key Cryptography and hash functions.	2	80	75	H							H							

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Introduction to Cryptography and Network Security	Groups, Rings, Fields	Block cipher principles-Introduction	Principles of Public-key Cryptosystems - Structure and key management	Message Authentication Codes
S-2	SLO-2 OSI Security Architecture	Modular arithmetic	Data Encryption Standard	Principles of Public-key Cryptosystems – Applications for Public-key Cryptosystems	Requirements for Message Authentication Codes
S-3	SLO-1 Introduction to Security attacks	Euclid's Algorithm	DES Example, Strength of DES	Requirements for Public-key Cryptosystems and Public – Key Cryptanalysis	Applications of Cryptographic Functions - Message Authentication
S-4	SLO-2 Security mechanisms	Polynomial Arithmetic	Block cipher Modes of operation – Multiple Encryption	RSA algorithm - Key management	Two Simple Hash Function
S-5	SLO-1 Symmetric cipher model	Finite Fields	Block cipher Modes of operation – Triple DES	RSA algorithm - Encryption and Decryption	Security Requirements for Cryptographic hash Functions
S-6	SLO-2 Play fair Cipher	Prime Numbers, Testing for Primality	Electronic Code Book, Cipher Block Chaining Mode	Diffie Hellman key exchange – Algorithm, Key Exchange Protocols	Hash Algorithms - MD5
S-7	SLO-1 Mono alphabetic cipher	Fermat's and Euler's Theorem	Cipher Feedback Mode, Output Feedback Mode and Counter Mode	Diffie Hellman key exchange – Man-in-the-Middle Attack	Hash Algorithms - SHA
S-8	SLO-2 Poly alphabetic ciphers , Onetime pad		Advanced Encryption Standard – Structure and Transformation Functions	Elliptic curve: Arithmetic – Abelian Groups, Elliptic Curves over Real Numbers	Digital Signature Standard
S-9	SLO-1 Hill Cipher -Encryption	The Chinese remainder theorem	AES Key Expansion and AES Example	Elliptic Curves over Z_p , Elliptic Curves over $GF(2^m)$	Applications pertaining to Encryption using different ciphers and modes
	SLO-2 Decryption		Blowfish		
	SLO-1 Transposition techniques, Steganography	Discrete Logarithms	RC5 algorithm	Elliptic Curve Cryptography	One-way hash algorithms.
	SLO-2				

Learning Resources	1. William Stallings, "Cryptography and Network Security", 6 th Edition, 2014, Pearson Education, ISBN: 9789332518773. 2. Atul Kahate, "Cryptography and Network Security", 2 nd Edition, 2009, McGraw Hill Education India Pvt Ltd, ISBN: 100070151458.	3. Web Tutorial: http://www.cis.syr.edu/~wedu/seed/cryptography.html as on 14/04/2016
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mohanraj N - PayPal	1. Dr. E. Sivasankar – Assistant Professor – NIT, Trichy	1. Dr. E. Sasikala, SRMIST
		2. Ms. S. Aruna, SRMIST
		3. Ms. G. Sujatha, SRMIST

Course Code	18CSE382T	Course Name	FORENSICS AND INCIDENT RESPONSE	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering		Data Book / Codes/Standards	Nil	

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Gain knowledge on the basics of procedures for identification, preservation of electronic evidence	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15			
CLR-2 :	Understand the purpose and usage of various forensic tools	Thinking (Bloom)	Efficiency (%)	Attainment (%)	Knowledge	Analysis	Development	Design, Research	Usage	Culture	& Sustainability		Team Work	on	& Finance	Learning						
CLR-3 :	Gain knowledge on how scientific evidence collection/extraction during investigation																					
CLR-4 :	Acquire knowledge on file systems and its innerworking																					
CLR-5 :	Understand the windows and linux investigation procedures																					
CLR-6 :	Introduce the report writing guidelines and principles																					

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Acquire the knowledge on basics of procedures for identification, preservation of electronic evidence	2	80	85	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-2 :	Acquire the ability to identify the purpose and usage of various forensic tools	2	75	80	H	H	-	-	H	-	-	-	-	-	-	-	-	-	-
CLO-3 :	Understand how scientific evidence collection/extraction during investigation	2	85	80	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-4 :	Appreciate the concepts of file systems and its importance in forensic science.	2	80	75	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-5 :	Apply the knowledge of windows and Linux investigation procedures	2	75	85	H	-	-	H	-	-	-	-	-	-	-	-	-	-	-
CLO-6 :	Acquire the knowledge on forensic report writing guidelines and principles	2	80	85	H	-	-	-	-	H	-	-	-	-	-	-	-	-	-

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Introduction to Incident	Introduction to ACPO Principles	Introduction to File System Analysis	Introduction to Investigating Systems	Investigating Hacker Tools
	SLO-2 Goals of Incident Response	ACPO Principles of Computer Based Evidence	What is a File System?	Investigating Windows Systems	What are the goals of tool analysis?
S-2	SLO-1 Introduction to Incident Response Methodology (IRM)	Introduction to computer Storage Formats	Five Data Categories	Where Evidence resides on Windows Systems	How are files compiled?
	SLO-2 Steps in Incident Response Methodology	Understanding Storage Formats for Digital Evidence	FAT Concepts	Conducting a Windows Investigation I	Static Analysis of Hacker Tools I
S-3	SLO-1 IRM: Pre-incident preparation	Forensic Duplication	FAT Analysis	Conducting a Windows Investigation II	Static Analysis of Hacker Tools II
	SLO-2 IRM: Detection of incidents	Forensic Duplication tools	FAT - The Big Picture	File Auditing	Dynamic Analysis of Hacker Tools I
S-4	SLO-1 IRM: Initial Response	Forensic Duplicate creation of HDD	Introduction to NTFS	Theft of Information	Dynamic Analysis of Hacker Tools II
	SLO-2 IRM: Formulate a Response Strategy	Qualified Forensic Duplicate creation	Files in NTFS	Handling the departing employee	Evaluating Computer Forensics Tools
S-5	SLO-1 IRM: Investigate the Incident	Restored Image	MFT Concepts	Investigating Unix Systems	Types of Forensic Tools
	SLO-2 IRM: Reporting	Mirror Image	MFT Attribute Concepts	Overview of steps - Unix Investigation	Tasks performed by Forensic Tools
S-6	SLO-1 Creating response toolkit - Windows	Forensic Duplication Tool Requirements	Other MFT Attribute Concepts	Reviewing pertinent logs	Tool comparisons
	SLO-2 Volatile Data Collection - Windows	Creating a Forensic Duplicate of a Hard Drive	Indexes in NTFS	Performing keyword searches	Computer Forensics Software Tools
S-7	SLO-1 In-depth data collection - Windows	Evidence Handling	NTFS Analysis - File System Category	Reviewing relevant files	Computer Forensics Hardware Tools
	SLO-2 Storing collected data - Windows	Types of Evidence	NTFS Analysis - Content Category	Identifying unauthorized user accounts/groups	Validating and Testing Computer Forensics Software
S-8	SLO-1 Creating response toolkit - Unix	Challenges in Evidence Handling	NTFS Analysis - Metadata Category	Identifying rogue processes	Introduction to Forensic Report Writing
	SLO-2 Volatile Data Collection - Unix	Overview of Evidence Handling Procedure.	NTFS Analysis - File Name Category	Checking for unauthorized access points	Understanding the Importance of Reports
S-9	SLO-1 In-depth data collection - Unix	Evidence Handling Procedure	NTFS Analysis - Application Category	Analyzing trust relationships	Guidelines for Writing Reports
	SLO-2 Storing collected data - Unix	Evidence Handling reports	NTFS - The Big Picture	Detecting loadable kernel modules	A Template for Computer Forensics Reports

Learning Resources	1. Kevin Mandia, Chris Prosise, "Incident Response and Computer Forensics", Tata McGraw Hill, 2006.	3. Eoghan Casey, "Handbook of Computer Crime Investigation's Forensic Tools and Technology", Academic Press, 1st Edition, 2001.
	2. Bill Nelson, Amelia Philips and Christopher Steuart, "Guide to computer forensics and investigations", course technology, Cengage Learning, 4th edition, ISBN: 1-435-49883-6, 2009.	4. Brian Carrier, "File System Forensic Analysis", Addison-Wesley Professional; 1st edition 2005, ISBN-13: 978-0321268174

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50%)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Balan C, Scientist F, CDAC, cbalan@cdac.in	1.	1. Mr. A.R. Nagoor Meeran, SRMIST
2.	2.	2. Dr. C.N.S. Vinoth Kumar, SRMIST

Course Code	18CSE383T	Course Name	INFORMATION ASSURANCE AND SECURITY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Understand the different ways the information systems may be compromised.	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Learn to model the various types of threats.	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Understand the Information Assurance planning strategies.	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Acquire knowledge by analyzing software systems.	Expected Attainment (%)	Design & Development
CLR-5 :	Understand and apply different countermeasures and protect information.		Analysis, Design, Research
CLR-6 :	Perform vulnerability testing.		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Acquire the basic knowledge about the Information Assurance.	2 80 85	H - - - - - - - - - - - - - - -
CLO-2 :	Design an appropriate Policies for the organization.	2 75 80	H H - - - - - - - - - - - - - - -
CLO-3 :	Deliver professional, ethical, legal, security and social issues and responsibilities in an effective manner.	2 85 80	H - - - - - - - - - - - - - - -
CLO-4 :	Develop risk management strategies for an enterprise.	2 80 75	H H - - - - - - - - - - - - - - -
CLO-5 :	Provide the understanding of different security mechanisms used in various areas of computing	2 75 85	H - - - H - - - - - - - - - - - - - - -
CLO-6 :	Apply the current technical concepts and practices in the core information technologies.	2 80 85	H - - - - - - - - - - - - - - -

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Information Assurance Basics	Information Security Planning	Information Assurance Process : Managing Information Assurance	Benefits of Incorporating Security Considerations	Information Assurance Detection and Recovery Processes
	SLO-2 The Need for Information Assurance	Information Security Governance	Information Security project management	System Development Life Cycle	Intrusion Detection and Prevention System(IDPS)
S-2	SLO-1 Key Information Security concepts	Policy, Standards and Practices	Technical aspects of implementing Information Security	Information Assurance in System Development Life Cycle	IDPS types
	SLO-2 Critical characteristics of Information	Policy Management, Information Security Blueprint	Non-Technical aspects of implementing Information Security	Information Assurance in the Service Acquisition Life Cycle	IDPS detection methods
S-3	SLO-1 MSR Model	Continuity Strategies	Structure of an Information Assurance	Physical and Environmental Security Controls	IDPS - Analysis
	SLO-2 Security in System lifecycle	Crisis Management	Organizational Maturity, Asset Management	Handling of Media	Log Management Tools: SIEM
S-4	SLO-1 NIST Approach to Securing SDLC	Information Asset Life Cycle, Plan, Do, Check, Act Model	APM Maturity model	Information Assurance Awareness, Training, and Education (AT and E), Purpose, Benefits	Honeypot/HoneyNet
	SLO-2 Security Professionals and Organizations	Current Practices : Due Care and Due Diligence	Overview of Risk Management	AT and E : Design, Development	Scanning and Analysis tools
S-5	SLO-1 Communities of Interest	Specific Laws and Regulations	Risk Identification	AT and E : Assessment	Malware Detection
	SLO-2 Information Security: Is it an art or Science?	International Laws and Acts	Risk Assessment	Types of Learning Programs	Penetration Test
S-6	SLO-1 Information Assurance Concepts : Defense in Depth	Standards and Best Practices	Risk control	Employment Policies and Practices	Physical Controls
	SLO-2 Information Assurance in Cyber Security	Plans for Information Assurance Strategy	Quantitative vs Qualitative Risk management practices	Security considerations for temporary employees, consultants and other workers	Special considerations for Physical security

S-7	SLO-1	CIA Triangle	Cryptology	Recommended risk control practices	Preventive Information Assurance Tools	Information Assurance Measurement Process
	SLO-2	The Need for Security	Cipher methods	Process , Secure design through threat modeling	Preventive Information Assurance controls	Metrics Program
S-8	SLO-1	Categories of Threats	Cryptographic algorithms	Importance of Policy	Positioning and staffing the Security function	Incident Handling Process
	SLO-2	Software Attacks types	Cryptographic tools	Information Assurance Policy	Credentias for Information Security Professionals	Continuity Strategies
S-9	SLO-1	Other vulnerabilities	Protocols for secure Communications	Policy Development Steps	Access control benefits	Computer Forensics
	SLO-2	Implications from Lack of Information Assurance	Approaches to implement Information Assurance	Certification, Accreditation, and Assurance	Access control Techniques, Administration	Examiner Prerequisites, Team Establishment

Learning Resources	1. Michael E. Whitman and Herbert J. Mattord, "Principles of Information Security", 5th edition, 2015, Thomson Publications, ISBN 1111899134.	3. William Stallings, "Cryptography and Network Security- Principles and Practice", 6th Edition, 2013, Pearson, ISBN: 9780136073734.
	2. Steven Hernandez, Corey Schou, "Information Assurance Handbook: Effective Computer Security and Risk Management Strategies", 1st Edition, 2014, McGraw Hill Osborne Media, ISBN: 0071821651, ISBN : 9780071821650	4. Corey Schou, Dan Shoemaker, "Information Assurance for the Enterprise", Tata McGraw - Hill Edition, 2007.

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50%)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Understand	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Apply										
Level 3	Analyze	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Evaluate										
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. P. Ananda Natarajan, Senior Associate Consultant, Infosys, Chennai.	1. Dr. S. Anbuchelian, Assistant Professor (Sl.G), IT Department, Anna University, Chennai	1. Ms. C. Fancy, SRMIST,
2. Mr. Surender Palanivel, GM, GGS Information Services Pvt. Ltd., Pune.		2. Dr. Vinothkumar, SRMIST vinothks1@srmist.edu.in

Course Code	18CSE384T	Course Name	SECURE SOFTWARE DEVELOPMENT LIFE CYCLE	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Identify project security risks & selecting risk management strategies.				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Analyze software security standards, policies, and guidelines to articulate and elaborate requirements				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Use automated tools and secure coding practices to analyze and test existing code and reduce vulnerabilities																					
CLR-4 :	Select and integrate established security design patterns and address threat assessments to mitigate common vulnerabilities and achieve the target design																					
CLR-5 :	Participate in team-based peer reviews to analyze the security development life cycle and mitigate risks and vulnerabilities																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	Explain terms used in secured software development and life cycle process				3	80	70	L	H	-	L	L	-	-	-	L	L	-	H	-	-	-
CLO-2 :	Incorporate requirements into secured software development process and test software for security vulnerability				3	85	75	M	H	L	M	L	-	-	-	M	M	-	H	-	-	-
CLO-3 :	Identify vulnerable code in implemented software and describe attack consequences				3	75	70	M	H	M	H	L	-	-	-	M	L	-	H	-	-	-
CLO-4 :	Apply mitigation and implementation practices to construct attack resistant software				3	85	80	M	H	M	H	L	-	-	M	M	M	-	H	-	-	-
CLO-5 :	Apply secure design principles for developing attack resistant software				3	85	75	H	H	M	H	L	-	-	-	M	M	-	H	-	-	-

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Software Engineering- Process model	A Risk Management Framework	Introduction toArchitectural Risk Analysis	Code Review with a Tool	Software Penetration Testing
	SLO-2				Catching Implementation Bugs with a Tool)	
S-2	SLO-1	Agile development-Agile Process	The Five Stages of Activity	Common Themes among Security Risk Analysis Approaches	Approaches to Static Analysis	Software Penetration Testing—a Better Approach
	SLO-2	Extreme Programming				
S-3	SLO-1	Need to secure development life cycle	Understanding the Business Context	Traditional Risk Analysis Terminology	Modern Rules	Using Penetration Tests to Assess the Application Landscape
	SLO-2		Gathering the Artifacts			
S-4	SLO-1	Current Software Development Methods Fail to Produce Secure Software .	Identifying the Business and Technical Risks	Knowledge Requirement	Tools from Researchland	Risk-Based Security Testing
	SLO-2	Incentive to Review Code				
S-5	SLO-1	Understanding Security Bugs	Synthesizing and Ranking the Risks	The Necessity of a Forest-Level View	Commercial Tool Vendors	Abuse Cases
	SLO-2	Critical Mass		A Traditional Example of a Risk Calculation		
S-6	SLO-1	Proprietary Software Development Methods- CMMI, TSP, and PSP	Defining the Risk Mitigation Strategy	Modern Risk Analysis	Key Characteristics of a Tool	Software Security Meets Security Operations
	SLO-2					
S-7	SLO-1	SDL for Management	Carrying Out Fixes and Validating	Touchpoint Process: Architectural Risk Analysis	The Fortify Knowledge Base	Knowledge for Software Security
	SLO-2					
S-8	SLO-1	Managing the SDL	The Importance of Measurement	Limitations of Traditional Approaches	Touchpoint Process: Code Review	Establishing a Metrics Program
	SLO-2					
S-9	SLO-1	Case study: A Short History of the SDL at Microsoft	The Cigital Workbench	Getting Started with Risk Analysis	Use a Tool to Find Security Bugs	Continuous Improvement
	SLO-2					

Learning Resources	1. <i>The Security Development Lifecycle: SDL: A Process for Developing Demonstrably More Secure Software (1st Edition)</i> By Michael Howard, 2017. 2. <i>Software Security: Building Security In</i> by Gary McGraw. Addison-Wesley, 2006	3. <i>Software Security Engineering: A Guide for Project Managers</i> by Julia H. Allen, Sean Barnum, Robert J. Ellison, Gary McGraw, and Nancy Mead. Addison-Wesley, 2012
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100%	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr.V.SelvaKumar, Assistant General Manager, Hexaware Technologies.	Dr.N.Prakash, Associate Professor, Department of Information technology, B.S.A Crescent Institute of Science and Technology.	1. Mr.Arivazhagan
		2. Dr. Naresh
		3. Mrs.B.Jothi, SRMIST

Course Code	18CSE385T	Course Name	SECURITY AUDIT AND RISK ASSESSMENT	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	CSE	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand the security audit planning strategies				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Gain knowledge about information risk				Thinking (Bloom)	Efficiency (%)	Attainment (%)	Knowledge	Analysis	Development	Design, Research	Usage	Culture	& Sustainability		Team Work	Communication	Finance & Management				
CLR-3 :	Discover knowledge in collecting data about organization																					
CLR-4 :	Acquire knowledge in various analysis on Information Risk Assessment																					
CLR-5 :	Introduce the System Risk analysis																					
CLR-6 :	Understand the organizational and system specific risk																					

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Acquire the knowledge on various secure auditing techniques	2	80	85	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-2 :	Acquire the ability to identify knowledge in information risk	2	75	80	H	H	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-3 :	Understand the basic ideas about data collection workload	2	85	80	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-4 :	Appreciate the concepts of vulnerability catalogs and impact analysis scheme	2	80	75	H	H	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-5 :	Identify the knowledge in risk classification techniques	2	75	85	H	-	-	H	-	-	-	-	-	-	-	-	-	-	-
CLO-6 :	Acquire the knowledge on system specific risk	2	80	85	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Need for Audit Planning	What is Risk?	Data Collection-Introduction	Compiling Observations from Organizational	System Risk Analysis
	SLO-2	Steps in Audit Planning	Going Deeper with Risk	The Sponsor	Risk Documents	Risk Classification
S-2	SLO-1	Audit Risk Assessment	Components of Risk	The Project Team	Preparation of Threat and Vulnerability Catalogs	Risk Rankings
	SLO-2	Performing Audit	Putting it Altogether	The size and Breadth of the Risk Assessment	Threat Catalog	Risk Prioritization and Treatment
S-3	SLO-1	Internal Controls	Information Security Risk	Scheduling and Deadlines	Vulnerability Catalogs	Review of Audit Findings
	SLO-2	Audit Evidence	Information Security Risk Assessment Overview	Assessor and Organization Experience	Threat Vulnerability Pairs	Review of Security Incidents
S-4	SLO-1	Audit Testing	Assess Information Security Risk	Work load	Overview of the System Risk Computation	Review of Security Exceptions
	SLO-2	Follow up activities	Risk assessment and security Program	Data Collection Mechanisms	Designing the Impact Analysis Scheme	System Specific Risk Treatment
S-5	SLO-1	Security Monitoring and Auditing	Information Security Management in a Nutshell	Collectors	Confidentiality, Integrity	Information Security Risk Assessment Reporting
	SLO-2	Assurance and Trust	Drivers, Laws and Regulations	Containers	Availability	Risk Analysis Executive Summary
S-6	SLO-1	Need for Assurance	Federal Information Security Management	Executive Interview	Preparing the Impact Score	Methodology
	SLO-2	Role of Requirements in Assurance	Gramm-Leach-Blille(GLBA)	Document Requests	Designing the Control analysis Scheme	Organizational
S-7	SLO-1	Audit Assurance in Software Development Phases	Health Insurance Portability and Accountability Act(HIPAA)	IT Asset Inventories	Designing the Likelihood Analysis Scheme	System Specific
	SLO-2	Building Secure and Trusted Systems	State Governments	Asset Scoping	Exposure	Results
S-8	SLO-1	Designing an Auditing System	ISO 27001	Business Impact Analysis and Other Assessments	Frequency	Organizational Analysis
	SLO-2	Auditing to detect Violations of a Security Policy	Drivers,Laws and Regulations	Critical Success Factor Analysis	Controls	System Specific
S-9	SLO-1	Auditing Mechanisms	Risk Assessment Framework	Profile & Control Survey	Likelihood	Risk Register
	SLO-2	Audit Browsing	Practical Approach	Consolidation	Final Risk Score	Post Mortem

Learning Resources	1. Mark Talabis, "Information Security Risk Assessment Toolkit: Practical Assessments through Data Collection and Data Analysis", Syngress; 1 Edition. ISBN: 978-1-59749-735-0. Nov 2012.	3. Thomas R. Peltier, "Information Security Risk Analysis", CRC Press, 2001
	2. David L. Cannon, "CISA Certified Information Systems Auditor Study Guide", SYBEX Publication. ISBN: 978-0-470-23152-4.	

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50%)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Prasanna Kumar, Infosys Prasanna_kumar11@infosys.com	1. Dr. E. Sivashankar, NIT Trichy, sivasankar@nitt.edu	1. Dr. G. Usha, SRMIST, Dr. M. B. Mukesh Krishnan, SRMIST
2. Mr. Mithun, Cognizant, Mithun.SS@cognizant.com	2. Dr. Kunwar Singh, NIT Trichy, kunwar@nitt.edu	2. Mrs G. K. Sandhia, SRMIST

Course Code	18CSE386T	Course Name	PENETRATION TESTING AND VULNERABILITY ASSESSMENT	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Gain knowledge on various security testing techniques and asses sensitiveness of assets.				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Gain knowledge on weaknesses of various OS, network and applications.				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO – 3
CLR-3 :	Identify how security controls can be improved to prevent hackers gaining access to operating systems and networked environments.																					
CLR-4 :	Acquire knowledge on methodologies and techniques of Hacking																					
CLR-5 :	To test and exploit systems using various tools.																					
CLR-6 :	Understand the impact of hacking in real time machines																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	Acquire the knowledge on identifying security vulnerabilities				2	80	85	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-2 :	Acquire the ability to identify problems in network, OS and applications commonly exploited by hackers				2	75	80	H	H	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-3 :	Understand management of static and dynamic security controls in firewalls, IPS, IDS				2	85	80	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-4 :	Appreciate the concepts of hacking and gaining access to remote and local systems.				2	80	75	H	H	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-5 :	Apply the knowledge for creating better security controls.				2	75	85	H	-	-	H	-	-	-	-	-	-	-	-	-	-	-
CLO-6 :	Acquire the knowledge to prevent threats in targeted attacks and real time systems.				2	80	85	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Introduction to penetration testing	Types of Scanning	Meterpreter Basics	Social engineering	DOS Attack
	SLO-2 Introduction to penetration testing -2	Black, White and Grey Scanning	Working with Meterpreter session	Electronic and Non Electronic Social Engineering	DDOS Attack
S-2	SLO-1 Understanding basic Ethical Hacking terminologies	Foot Printing Stages	Exploit Modules	SET- Social Engineering Toolkit	Web application Vulnerability
	SLO-2 Understanding basic Ethical Hacking terminologies -2	Foot Printing Stages-2	Payload Modules	Social Engineering Prevention Techniques	Security assessment of public Domains
S-3	SLO-1 Batch Programming Basics	DNS Information Gathering	Privilege Escalation	Buffer Over Flow Attack	Phishing and its Types
	SLO-2 Batch Programming Basics - 2	NS Lookup	Vertical and horizontal Privilege Escalation	Stack Based Buffer overflow	Cross Site Request Forgery
S-4	SLO-1 Taking control using batch programs	Network Information Gathering	Token Stealing	Heap Based buffer overflow	DOM Based XSS
	SLO-2 Taking control using batch programs-2	NMap	Active and Passive stealing	Deep packet inspection	Brup Suite
S-5	SLO-1 Open web Application Security Project(OWASP)	Scanning	Network Sniffing	SQL Injection –Introduction	Password Cracking
	SLO-2	Port, Network and OS	Active and passive sniffing	SQL Injection Types	John the Ripper
S-6	SLO-1 Stages of Ethical Hacking	Nmap Scripting	Creating Backdoors	Error Based SQL,	Dictionary Attack, Brute Force Attack
	SLO-2		Persistent and Non-Persistent	Union Based SQL	Rainbow Table Attack,
S-7	SLO-1 Vulnerability Research	Vulnerability Scanning	Key Loggers	Blind SQL	Shoulder Sniffing, Spidering
	SLO-2	Nessus	Software and Hardware Key loggers	Boolean-based SQL injection, Time-based SQL injection	Offline Cracking
S-8	SLO-1 Impact of Hacking	'Who is' Information Gathering	ARP Poisoning	SQL Map,DVWA	Wifi Hacking
	SLO-2	Wireshark	Maltigo	SQL injection Counter Measures	Alrcrack
S-9	SLO-1 Introduction to Kali OS	Enumeration	Man In The Middle Attack	Steganography	Documentation and Reporting
	SLO-2 Installation and configuration	Active and Passive Enumeration	Port Forwarding	Steganography counter measures	Dradis Framework

Learning Resources	1. David Kennedy, Jim O'Gorman, Devon Kearns, and Mati Aharoni, <i>METASPLOIT The Penetration Tester's Guide</i> , No Starch Press, 2011.	3. Sean-Philip Oriyano, <i>Penetration Testing Essentials</i> , John Wiley & Sons, 2017.
	2. Wil Allsopp, <i>Advanced Penetration Testing: Hacking the world's most Secure Networks</i> , 1st Edition, John Wiley & Sons, 2017	4. Lee Brotherton, Amanda Berlin, <i>Defensive Security Handbook</i> , O'Reilly, 2017

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. S Manigandan, <i>pmc Cyber Researcher, Symantec Inc</i> manigandan_s@symantec.com		1. Geogen George, SRMIST
		2. Ms. Poomima, SRMIST
		3. Mr. Selvakumaraswamy, SRMIST

Course Code	18CSE472T	Course Name	MALWARE ANALYSIS	Course Category	E	Professional Elective	L 3	T 0	P 0	C 3
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Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand the fundamentals of static and dynamic analysis.	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Gain knowledge about running malware in virtual environment.	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Study about disassembly constructs and its structures.				H	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLR-4 :	Study about new processors and file types using the IDA SDK				H	H	-	-	-	-	-	-	-	-	-	-	-	-	-
CLR-5 :	Explore popular plug-ins that make writing IDA scripts easier, allow collaborative reverse engineering				H	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLR-6 :	Understand how to best approach the subject of Android malware threats and analysis.				H	H	-	-	-	-	-	-	-	-	-	-	-	-	-
					H	-	-	H	-	-	-	-	-	-	-	-	-	-	-
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Gain knowledge about the different forms of malware.	2	80	85	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-2 :	Set up a safe virtual environment to analyze malware.	2	75	80	H	H	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-3 :	Navigate, comment, and modify disassembly.	2	85	80	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-4 :	Use code graphing to quickly make sense of cross references and function calls	2	80	75	H	H	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-5 :	Use IDA's built-in debugger to tackle hostile and obfuscated code.	2	75	85	H	-	-	H	-	-	-	-	-	-	-	-	-	-	-
CLO-6 :	Learn procedures for recognizing and analyzing Android malware threats quickly and effectively.	2	80	85	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-

Duration (hour)	9	9	9	9	9
S-1	SLO-1 The Goals of Malware Analysis	The Structure of a Virtual Machine	Disassembly Theory	Cross-References	Introduction to the Android Operating System and Threats
	SLO-2 Malware Analysis Techniques	Creating Your Malware Analysis Machine	The Why and how of Disassembly	Function Calls	Malware Threats, Hoaxes, and Taxonomy
S-2	SLO-1 Types of Malware	Using Your Malware Analysis Machine	Reversing and Disassembly Tools.	IDA Graphing	Open Source Tools
	SLO-2 General Rules for Malware Analysis	The Risks of Using VMware for Malware Analysis	Getting started with IDA.	Console Mode IDA	Collections
S-3	SLO-1 Antivirus Scanning	Record/Replay: Running Your Computer in Reverse	IDA Data Displays	IDA's Batch Mode	File Data, Metadata
	SLO-2 Hashing- Fingerprint for Malware	Sandboxes: The Quick-and-Dirty Approach	Disassembly Navigation.	Customizing IDA's	Creating a JAR File, VisualThreat Modeling
S-4	SLO-1 Finding Strings	Running Malware	Disassembly Manipulation.	Library Recognitions	Automation
	SLO-2 Packing Files	Monitoring with Process Monitor	Recognizing Data Structure Use	Augmenting Function Information	Processor Emulation
S-5	SLO-1 Detecting Packers with PEID	Viewing Processes with Process Explorer	Creating IDA Structures	Augmenting Predefined Comments	Configuring Emulated Devices within AVD
	SLO-2 Portable Executable File Format	Comparing Registry Snapshots with Regshot	Using Structure Templates	The Infamous Patch Program Menu	Using the ADB Tool
S-6	SLO-1 Static, Runtime, and Dynamic Linking	Faking a Network	Importing New Structures	IDA Output Files and Patch Generation	Installing Samples to Devices and Emulators
	SLO-2 Exploring Dynamically Linked Functions with Dependency Walker	Packet Sniffing with Wireshark	Using Standard Structures	IDA Scripting	Application Storage and Data Locations
S-7	SLO-1 Imported and Exported Functions	Using INetSim	IDA TIL Files	IDA Software Development Kit	Devices View, LogCat View
	SLO-2 PotentialKeylogger.exe: An Unpacked Executable	Basic Dynamic Tools in Practice	C++ Reversing Primer- The this Pointer	The IDA Application Programming Interface	Application Tracing
S-8	SLO-1 Examining PE Files with PEview	Levels of Abstraction	Virtual Functions and Vtables	Writing a Plug-in, Plug-in User Interface Options	Build Your Own Sandbox

	SLO-2	<i>Viewing the Resource Section with Resource Hacker</i>	<i>Reverse-Engineering</i>	<i>The Object Life Cycle</i>	<i>IDA Loader Modules</i>	<i>USB-cleaver, Torec</i>
S-9	SLO-1	<i>Using Other PE File Tools</i>	<i>The x86 Architecture</i>	<i>Name Mangling, Runtime Type Identification</i>	<i>Processor Module Architecture</i>	<i>Static and Dynamic Analysis of Uploaded Malware Samples.</i>
	SLO-2	<i>PE Header Summary</i>	<i>Recognizing C Code Construct in Assembly</i>	<i>Inheritance Relationships, C++ Reverse Engineering References</i>	<i>Real World Applications- Vulnerability Analysis.</i>	<i>Capabilities and Limitations of the Emulators.</i>

Learning Resources	1. Michael Sikorski, <i>Practical Malware Analysis – The Hands-On Guide to Dissecting Malicious Software</i> , Kindle Edition, No Starch Press; 1 edition (1 February 2012), ISBN: 1593272901.	3. Ken Dunham, <i>Android Malware and Analysis</i> , Kindle Edition, Auerbach Publications. International Standard Book Number-13:978-1-4822-5220-0.
	2. Chris Eagle, <i>The IDA Pro Book, 2nd Edition</i> , No Starch Press, 2011. ISBN-10: 1-59327- 289-8.	

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Understand										
	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Analyze										
	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. P. Santhosh, Information Security Risk Analyst, PricewaterhouseCoopers Pvt Ltd, Bangalore, Karnataka 560008. Email: santhoshshivam72@gmail.com	Dr.L.Kavisankar Associate Professor, Dept. Of CSE, Hindustan Institute of Science and Technology Email: lkavis@hindustanuniv.ac.in	1. Mr. V. Joseph Raymond, SRMIST
		2.Ms. Ida Seraphim, SRMIST

Course Code	18CSE474T	Course Name	CYBER LAW				Course Category	E	Professional Elective										L	T	P	C							
																		3	0	0	3								
Pre-requisite Courses		Nil				Co-requisite Courses		Nil				Progressive Courses		Nil															
Course Offering Department			Computer Science and Engineering					Data Book / Codes/Standards				Nil																	
Course Learning Rationale (CLR):			The purpose of learning this course is to:					Learning			Program Learning Outcomes (PLO)																		
								1			2		3																
CLR-1 :	Understand the basics of cyber law and cyber security					Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge																				
CLR-2 :	familiarize the issues those are specific to amendment rights								Problem Analysis																				
CLR-3 :	Become aware on copyright issues in software's								Design & Development																				
CLR-4 :	Understand the Cyber-crimes and Cyber Frauds								Analysis, Design, Research																				
CLR-5 :	Understand the Legal Framework								Modern Tool Usage																				
CLR-6 :	understand ethical laws of computer for different countries								Society & Culture																				
															Environment & Sustainability														
															Ethics														
															Individual & Team Work														
															Communication														
															Project Mgt. & Finance														
															Life Long Learning														
															PSO - 1														
															PSO - 2														
															PSO - 3														
Course Learning Outcomes (CLO):			At the end of this course, learners will be able to:					Level of Thinking (Bloom)			Expected Proficiency (%)		Expected Attainment (%)																
CLO-1 :	Gain in-depth knowledge on information on cyber security and issues specific to amendment rights					3	80	70	Engineering Knowledge																				
CLO-2 :	Apply the knowledge on copyright issues within software packages					3	85	75	Problem Analysis																				
CLO-3 :	Comprehend ethical laws of computer for various countries					3	75	70	Design & Development																				
CLO-4 :	Defines the Cyber-crimes and frauds					3	85	80	Analysis, Design, Research																				
CLO-5 :	Apply the knowledge of Legal framework					3	85	75	Modern Tool Usage																				
CLO-6 :	Construct the secured environment					3	80	70	Society & Culture																				
															Environment & Sustainability														
															Ethics														
															Individual & Team Work														
															Communication														
															Project Mgt. & Finance														
															Life Long Learning														
															PSO - 1														
															PSO - 2														
															PSO - 3														

Learning Resources	1. Justice Yatindra Singh, Cyber Laws, Universal Law Publishing Co, New Delhi, (2012). 2. Verma S, K, Mittal Raman, Legal Dimensions of Cyber Space, Indian Law Institute, New Delhi, (2004) 3. S. R. Bhansali, Information Technology Act, 2000, University Book House Pvt. Ltd., Jaipur (2003). 4. Blockchain, Blueprint for a new Economy, Melanie Swan, 2017 –O'Reilly	5. Sudhir Naib, The Information Technology Act, 2005: A Handbook, OUP, New York, (2011) 6. Upadhyaya and A. Upadhyaya, Material Science and Engineering, Anshan Publications, 2007 7. Vasu Deva, Cyber Crimes and Law Enforcement, Commonwealth Publishers, New Delhi, (2003). 8. Essential CyberSecurity Science, Josiah Dykstra, 2017 –O'Reilly
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Understand	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. Kesawan HCL Technologies	Dr. Surendran Rajendran AMA International University Bahrain	Dr.M.B Mukesh Krishnan, SRMIST
Mr.Celeian, Symantec		Mrs.R.Vidhya, SRMIST

Course Code	18CSE475T	Course Name	MOBILE AND WIRELESS SECURITY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	CSE	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	understand the fundamentals of mobile cellular networks and IEEE wireless networks	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Learn the basic security fundamentals	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	understand the security issues in Wi-Fi and Wi-Max	Expected Proficiency (%)	Problem Analysis
CLR-4 :	explore the security issues in Next generation mobile networks	Expected Attainment (%)	Design & Development
CLR-5 :	understand the security issues and key management in ad-hoc networks.		Analysis, Design, Research
CLR-6 :	study the hacking techniques in IEEE 802.11		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	understand the fundamentals of mobile cellular networks and IEEE wireless networks	2 80 85	H - - - - - - - - - - - - - - - -
CLO-2 :	Identify various possibilities for security threats in wireless networks.	2 75 80	H H - - - - - - - - - - - - - - - -
CLO-3 :	Handle the security threats in Wi-Fi networks.	2 85 80	H - - - - - - - - - - - - - - - -
CLO-4 :	Solve the security attacks in mobile IP networks	2 80 75	H H - - - - - - - - - - - - - - - -
CLO-5 :	Prevent the attacks in ad-hoc networks.	2 75 85	H - - - H - - - - - - - - - - - - - -
CLO-6 :	Protect the 802.11 Networks from attacks.	2 80 85	H - - - - - - - - - - - - - - - -

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Introduction to mobile cellular networks	Wi-Fi Security	Security in Next Generation Mobile Networks	Security in Ad Hoc Networks	Overview of Wireless security-Hacking
	SLO-2 Cellular network basic concepts	Attacks on wireless networks	SIP	Motivations and application fields	Scanning and Enumerating 802.11 Networks
S-2	SLO-1 IEEE wireless networks, WLAN: IEEE 802.11	IEEE 802.11 security mechanisms	VoIP security flaws	Routing protocols	Windows Sniffing/Injection Tools
	SLO-2 WMAN mobile: IEEE 802.20	WEP (Wired Equivalent Privacy) and Shortcomings	Making VoIP secure	Attacks to routing protocols	Attacking 802.11 Wireless Networks
S-3	SLO-1 Mobile Internet networks	Security in 802.1x	IP Multimedia Subsystem (IMS)	Security mechanisms - Basic protections and existing tools	Security Through Obscurity
	SLO-2 Security in the digital age	Authentication	IMS architecture and security	Key management architectures	Attacking WPA-Protected 802.11 Networks
S-4	SLO-1 Threats and risks to TeleCommunication systems	The 802.11i security architecture	4G security	Protections using asymmetric cryptography	Breaking Authentication: WPA-PSK
	SLO-2 From wireline vulnerabilities to vulnerabilities in wireless Communications	Radio security policies	Confidentiality	Protections using symmetric cryptography	Breaking Authentication: WPA Enterprise
S-5	SLO-1 Security services	Authentication in wireless networks	Security of IP-Based Mobile Networks	Protection against data modification	Attack 802.11 Wireless Clients
	SLO-2 Symmetric and asymmetric cryptography	Layer 3 security mechanisms	Vulnerabilities of Mobile IP networks	Protection against tunnel attacks	Attacking the Application Layer
S-6	SLO-1 Hash functions	WiMAX Security	Discovery mechanisms and Authenticity of the mobile location	Key Management in Ad Hoc Networks	Dynamically Generating Rogue APs and Evil Servers with Karmetasloit
	SLO-2 Electronic signatures and MAC	Security evolution in WiMAX standards	Data protection (IP tunnels)	The threshold cryptography technique and Self-managed PKI	Direct Client Injection Techniques
S-7	SLO-1 Public Key Infrastructure (PKI) and electronic certificates	WiMAX low layers	IPv6 mobility mechanisms	Key agreement technique within MANETs and Cryptographic identifiers	Overview of Bluetooth Scanning and Reconnaissance

	SLO-2	Management of cryptographic keys	Security according to the IEEE-802.16e standard	Mobile IPv6 bootstrapping	The Resurrecting Duckling technique	Bluetooth Eavesdropping
S-8	SLO-1	Cryptographic protocols	Authentication with PKMv2-RSA, PKMv2-EAP	Mobility with Mobile IPv4	Group key management within ad hoc networks	Commercial Bluetooth Sniffing
	SLO-2	IPsec protocol suite	SA-TEK 3-way handshake	Protocol and security	Security services and challenges for group Communications within MANETs	Open-Source Bluetooth Sniffing
S-9	SLO-1	Authentication mechanisms	GTEK updating algorithm	Mobility with MOBIKE	Comparison metrics	ZigBee Security
	SLO-2	Access control-Firewalls	Algorithms associated with the TEKs	IP mobility with HIP	Approaches for Group key management	ZigBee Attacks

Learning Resources	1. Hakima Chaouchi, Maryline Laurent-Maknavicius, "Wireless and Mobile Network Security Basics, Security in On-the-shelf and Emerging Technologies", John Wiley & Sons Inc, 2009.	3. Lei Chen, Jiahua Ji, Zihong Zhang, "Wireless Network Security: Theories and Applications", Higher Education Press, 2013.
	2. Johnny Cache, Joshua Wright, Vincent Liu, "Hacking Exposed Wireless: Wireless Security Secrets & Solutions", Second Edition, McGraw-Hill, 2010.	

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Understand										
	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Analyze										
	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts

Course Code	18CSE476T	Course Name	DATABASE SECURITY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:				Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Demonstrate understanding of Fundamentals of Security in database technology with its security architecture in modern computer systems in a typical enterprise.					1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Formulate a working definition of database security and administration and Identify contemporary practices of operating system security.					Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	To identify risks and vulnerabilities in operating systems from a database perspective.																						
CLR-4 :	Demonstrate the knowledge and skills for administration of user, profiles, password policies, privileges and roles.																						
CLR-5 :	Manage database security Model on application level and Conduct database auditing for security and reliability																						
CLR-6 :	Implement typical security projects on enterprise systems.																						
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Students are able to identify fundamentals of data , securityof data and security issues					3	85	75	M	H	L	H	L	-	-	-	H	H	M	H	-	-	-
CLO-2 :	Students are obtaining knowledge about architecture of data base security and Operating System Security					3	85	75	M	H	L	M	L	-	-	-	M	L	M	H	-	-	-
CLO-3 :	Develop and implement a security plan for an enterprise level database (password policies, auditing policies, user privileges, profile, and roles).					3	75	70	M	H	M	H	H	H	-	-	M	L	H	H	-	-	-
CLO-4 :	Students are able to design and implement access control rules to assign privileges and protect data in databases.					3	85	85	M	H	H	H	L	-	H	-	M	L	H	H	-	-	-
CLO-5 :	Identify some of the factors driving the need for Database security and classify particular examples of attacks					3	85	75	H	H	M	H	L	M	-	M	M	L	-	H	-	-	-
CLO-6 :	Students implement database auditing and Virtual Private Database to protect data in databases					3	80	85	H	H	H	H	H	-	-	-	H	H	M	H	-	-	-

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Importance of Data, Identity Theft	Installing a typical database product	Introduction-Authentication-Creating Users	Database Application Security Models: Introduction	Virtual Private Databases: Introduction-Overview
	SLO-2			SQL Server User	Types of Users	Implementation of VPD using Views
S-2	SLO-1	Levels of data security	Security architecture: Database Management Systems	Removing, Modifying Users-Default, Remote Users	Security Models	Application Context in Oracle
	SLO-2	Authorization in databases	Information Security Architecture			Implementing Oracle VPD
S-3	SLO-1	ACL Application Vulnerabilities	Database Security, Basics of Security in distributed databases	Database Links-Linked Servers	Application Types-Application Security Models	Viewing VPD Policies and Application contexts using Data Dictionary
	SLO-2		Asset Types and value-Security Methods			Policy Manager Implementing Row and Column level Security with SQL Server
S-4	SLO-1	Database security issues	Operating system security principles	Remote Servers-Practices for Administrators and Managers	Data Encryption, Excessive privileges, SQL Injections	Auditing Database Activities:
	SLO-2	Access to key fields, Access to surrogate information				
S-5	SLO-1	Problems with data extraction	Security Environment	Best Practices Profiles	Countermeasures of Malware, Countermeasures of Weak Audit Trail	Creating DLL Triggers with Oracle
	SLO-2	Access control in SQL		Password Policies		
S-6	SLO-1	Discretionary security in SQL, Schema level	Components	Introduction-Defining and Using Profiles	DB Vulnerabilities and Misconfiguration	Auditing Server Activity with SQL Server 2000
	SLO-2					
S-7	SLO-1	Authentication, Table level	Authentication Methods	Designing and Implementing Password Policies	Countermeasures of Denial of Service, Stolen Database Backups	Using Oracle Database Activities
	SLO-2		User Administration			

S-8	SLO-1	SQL system tables, Mandatory security in SQL	Password Policies	Granting and Revoking User Privileges	CONTROL METHODS: Access Control, Access control models for XML databases, Inference Policy	Security Project Case study-
	SLO-2		Vulnerabilities			
S-9	SLO-1	Data protection,	E-mail Security	Creating, Assigning and Revoking User Roles-Best Practices	User Identification, Authentication, Accountability, Password Cryptography	Security and Auditing Project Case Study Data Protection and the IoT
	SLO-2					

Learning Resources	1) Alfred Basta ,Melissa Zgola and Dana Bullaboy "Database Security" 1st Edition Cingage ,2012 (Unit 1 to III)	2) Hassan A. Afyouni, "Database Security and Auditing", Third Edition, Cengage Learning,2009. (UNIT III to V)
	3) Michael Gertz and SushilJajodia (Editors) ,Handbook of Database Security: Applications and Trends , ISBN-10: 0387485325. Springer, 2007	4) http://aircconline.com/ijist/V6N2/6216ijist18.pdf (UnitIV)

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50%								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	20%	-	30%	-
Level 2	Understand	40%	-	40%	-	40%	-	40%	10%	40%	-
	Apply										
Level 3	Analyze	40%	-	40%	-	40%	-	40%	10%	40%	-
	Evaluate										
	Create	20%	-	30%	-	30%	-	20%	10%	30%	-
	Total	100 %		100 %		100 %		100 %		-	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr.Prithivi R , Teradata DBA,T.C.S Company	Dr.N.P.Gopal,Professor,Department of Computer Applications , National Institute of Technology,Triuchy	1. Mrs.S.Amudha/SWE, SRMIST
Mr.JeroTerrence,Project Developer in Datawarehousing and DataMining,T.C.S Company	Dr.G.R.KanagaChidambaresan,Asso.Prof,VelTechUniveristy,Chennai	2. Dr. Madhavan/CSE, SRMIST
-	Dr.KanimuthuAsso.Prof,KarpagamCollege of Engineering,Coimbatore	3.Dr.MB.MukeshKrishnan/IT,SRMIST

Course Code	18CSE477T	Course Name	SECURITY GOVERNANCE, RISK AND COMPLIANCE	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1:	Analyze the expanding role of IT governance and its effect on organizations	1	1
CLR-2:	Be aware of management issues in IT governance	2	2
CLR-3:	Analyze the role of risk to an organization and ways to identify key risk factors	3	3
CLR-4:	Evaluate various risks and appropriate actions	4	4
CLR-5:	Develop naming conventions for the resources in a system	5	5
CLR-6:	Create and justify several appropriate policies and procedures to manage resources in a system.	6	6
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Engineering Knowledge
CLO-1:	Having an overview of IT governance	3	M
CLO-2:	Undergo an risk assessment	3	M
CLO-3:	Describe legal and ethical considerations related to the handling and management of enterprise information assets.	3	M
CLO-4:	Specify what constitutes admissible evidence in a legal proceeding and how to acquire and maintain this information.	3	M
CLO-5:	Create a set of policies that implement a specified organizational objective.	3	M
CLO-6:	Justify several appropriate policies and procedures to manage resources in a system.	3	M
		Expected Proficiency (%)	Problem Analysis
		Expected Attainment (%)	Design & Development
			Analysis, Design, Research
			Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Introduction to IT Governance	overview of Industry Best Practice Standards	Security mindset	Trends
	SLO-2				Creation of policies
S-2	SLO-1	IT Risk Management Life Cycle	Model and Guidelines covering some aspect of IT governance	Design principles	Auditing
	SLO-2				Maintenance of policies
S-3	SLO-1	IT Risk framework	principles of Business/IT Alignment Excellence,	System/security life-cycle	Cost / benefit analysis
	SLO-2				Prevention
S-4	SLO-1	IT Risk identification	principles of Program/Project Management Excellence	Security implementation mechanisms	Asset management
	SLO-2				Avoidance
S-5	SLO-1	IT Risk Security Governance	principles of IT Service Management and Delivery Excellence	Information assurance analysis model	Standards
	SLO-2				Incident response
S-6	SLO-1	IT Risk assessment	principles of Vendor Management	Disaster recovery	Enforcement
	SLO-2				Domain integration
S-7	SLO-1	IT Risk evaluation	Outsourcing Excellence	Forensics	Legal issues
	SLO-2				Social engineering
S-8	SLO-1	IT Risk response,	critical success factors	threats	Disaster recovery
	SLO-2			vulnerabilities	Protocol attacks
S-9	SLO-1	IT Risk monitoring and reporting	Case Study	attacks	security related issues and incidents
	SLO-2			countermeasures	Security awareness

Learning Resources	1. Iannarelli, J. G., & O'Shaughnessy, M. O. (2015). <i>Information governance and security: Protecting and managing your company's proprietary information</i> . Waltham, MA: Butterworth Heinemann, Elsevier.	3. <i>Legal Issues in Information Security</i> , Joanna Lyn Grama, 2015. Jones & Bartlett Learning, Second Edition, ISBN: 978-1-284-05474-3. 4. <i>Ethics of Big Data</i> , Kord Davis, 2012. O'Reilly Media, ISBN: 978-1449311797
	2. van Wyk, K. R., Graff, M. G., Peters, D. S., & Burley, D. L. (2015). <i>Enterprise software security: A confluence of disciplines</i> . Upper Saddle River, NJ: Pearson Education.	

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. Kesawan HCL Technologies	Dr. Surendran Rajendran AMA International University Bahrain	1. Dr.M.B Mukesh Krishnan, SRMIST
Mr.Celeian, Symantec		2. Ms. Ramaprabha.J.SRMIST
		3. Dr. G. Usha,SRMIST

Course Code	18CSE478T	Course Name	OPERATION SYSTEM SECURITY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering		Data Book / Codes/Standards	Nil	

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)															
CLR-1 :	To introduce students to a broad range of operating system security topics				Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	To introduce students network and system security plans																						
CLR-3 :	To introduce students security design																						
CLR-4 :	To introduce students security threats and risks																						
CLR-5 :	To introduce students system and application security tools																						
CLR-6 :	To introduce students Network monitoring and audit logs and resolution of any security breach																						
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																					
CLO-1 :	Identify and assess current and anticipated security risks and vulnerabilities				3	80	70	H	H	M	M	M	L	L	L	H	M	L	H	H	H	H	H
CLO-2 :	Monitor, evaluate and test security conditions and environment				3	85	75	H	H	M	M	M	L	L	L	H	M	L	H	H	H	H	H
CLO-3 :	Develop an organizational security plan that provides for periodic reviews of security policies and procedures				3	75	70	H	H	M	M	M	L	L	L	H	M	L	H	H	H	H	H
CLO-4 :	Evaluate tools and technologies for use in protecting the network and individual network systems				3	85	80	H	H	M	M	M	L	L	L	H	M	L	H	H	H	H	H
CLO-5 :	Implement security plan and monitor solutions				3	85	75	H	H	M	M	M	L	L	L	H	M	L	H	H	H	H	H
CLO-6 :	Monitor and evaluate audit logs and set administrator alerts				3	80	70	H	H	M	M	M	L	L	L	H	M	L	H	H	H	H	H

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Secure operating systems	What is a secure OS?	Information Protection And Security	Kali Linux	Implementation of strong password
	SLO-2	Security goals				
S-2	SLO-1	Trust model	Nature of threats/attacks	Requirements	Installation and Configuration	Implementation of buffer overflow attack
	SLO-2			Computer System Assets		
S-3	SLO-1	Threat model	Parts of an OS	Design Principles	Information Gathering Tools	Creation of child process using fork() function
	SLO-2					
S-4	SLO-1	Access Control fundamentals: Lampson's access matrix	Processes & Threads	Protection of Memory	Vulnerability Analyses Tools	Executing programs with exec() functions
	SLO-2					
S-5	SLO-1	Mandatory protection systems	Secure handling of Processes & Threads, Concurrency	User-Oriented Access Control	Wireless Attacks	Communication among multiple processes
	SLO-2					
S-6	SLO-1	Reference monitor	Memory management	Data-Oriented Access Control	Website Penetration Testing	Automating simple jobs simple scripts
	SLO-2					
S-7	SLO-1	Secure operating system definition	Secure memory management	File Sharing	Exploitation Tools	Executing programs at periodic intervals using at and crontab
	SLO-2			Access Rights		
S-8	SLO-1	Assessment criteria	Secure Communication and messaging	Simultaneous Access	Forensics Tools	Building own shell interpreter with limited features (mini project)
	SLO-2			Trusted Systems		
S-9	SLO-1	OS Security Assessment	Security perspective: end-user	Trojan Horse Defense	Social Engineering	Retrofitting security into operating systems
	SLO-2		Hardware/Architecture support for OS security			

Learning Resources	1. Abraham Silberschatz, Peter Baer Galvin and Greg Gagne, "Operating System Concepts", John Wiley & Sons, Inc., 9th Edition, 2012	4. Trent Jaeger, "Operating Systems Security", Morgan & Claypool Publishers, 2008 5. Michael J. Palmer, "Guide to Operating Systems Security", Thomson/Course Technology, 2004
	2. William Stallings, "Operating System: Internals and Design Principles", Prentice Hall, 7th Edition, 2012	
	3. Tom Adelstein and Bill Lubanovic, "Linux System Administration", O'Reilly Media, Inc., 1st Edition, 2007	

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. Kesawan HCL Technologies	Dr. Surendran Rajendran AMA International University Bahrain	1. Dr.M.B Mukesh Krishnan, SRMIST
Mr.Celeian, Symantec		2. Mr. M.V. Ranjith Kumar, SRMIST
		3. Mrs. S. Aruna Sankaralingam, SRMIST

Course Code	18CSE361T	Course Name	WEB PROGRAMMING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Web has become ubiquitous in nature	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Organizations have integrated the Internet “seamlessly” into their information systems and the Web offers endless opportunity to do so.	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	This course provides the basic concepts and techniques used to design, develop, and deploy web applications satisfying the requirements in terms of flexibility, availability and scalability.	Expected Proficiency (%)	Problem Analysis
		Expected Attainment (%)	Design & Development
			Analysis, Design, Research
			Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Understand different internet Technologies, web 2.0 and create a basic website using HTML and Cascading Style Sheets	1 80 70	H H H H H M L M H M M H H H M
CLO-2 :	Design a dynamic web page with validation using JavaScript objects and by applying different event handling mechanisms	1 85 75	H H H H H M L M H M M H H H M
CLO-3 :	Design a server side program using Servlets and JSP	1 75 70	H H H H H M L M H M M H H H M
CLO-4 :	Design a simple web page in PHP, and to present data in XML format.	2 85 80	H H H H H M L M H M M H H H M
CLO-5 :	Get overviews of java specific web services architecture and to enable rich client presentation using AJAX.	2 85 75	H H H H H M L M H M M H H H M

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Understanding Internet , Difference between websites and web server	An introduction to JavaScript	Java Servlet Architecture	An introduction to PHP	Introduction to Ajax
	SLO-2	Internet technologies Overview	Java Script Terminologies	Servlet Life Cycle	Using PHP, Variables, Program control	Ajax Client Server Architecture
S-2	SLO-1	Understanding websites and web servers:	Introduction to DOM Model	Form GET and POST actions	Built-in functions	Introduction to XMLHttpRequest Object
	SLO-2	Understanding the difference between internet and	DOM Model	Session Handling ,	Connecting to Database	XMLHttpRequest Object
S-3	SLO-1	Web 2.0: Basics, RIA Rich Internet Applications	Introduction to Objects	Understanding Cookies,	Using Cookies	Introduction to Call Back Methods
	SLO-2	collaborations tools	Built-in objects: Math Object	Installing and Configuring Apache Tomcat Web Server	Regular Expressions	Call Back Methods
S-4	SLO-1	HTML5.0 Introduction	Built-in objects: String Object	Introduction to JSP	Introduction to XML	Introduction to Web Services
	SLO-2	HTML5.0 Elements Headers ,Linking,Images,List	Date Object	Understanding Java Server Pages	Basic XML Concepts	Java web services Basics
S-5	SLO-1	HTML5.0 Elements Tables, Formatting,Frames	Boolean Object	Applications on JSP	Introduction to DTD	Introduction to SOAP
	SLO-2	CSS Introduction	Object Collections	Introduction to JSTL	Document Type Definition	Elements of SOAP
S-6	SLO-1	CSS Types	Regular Expressions	Understanding of JSTL	Introduction to XML	Introduction to WSDL
	SLO-2	CSS : Positioning,Text Flow and Box Model	Examples of Regular Expressions	JSP Standard Tag Library(JSTL)	XML Schema	Creating, Publishing a WSDL
S-7	SLO-1	XHTML Introduction	Exception Handling	Creating HTML forms by embedding JSP code	DOM and Presenting XML	Testing and Describing a Web services(WSDL)
	SLO-2	XHTML Elements:Headers ,Linking,Images,List	Validation	Creating HTML forms by embedding JSP code	XML Parsers	Consuming a web service
S-8	SLO-1	XHTML Elements:Tables, Formatting,Frames	Event Handling Concept	Creating HTML forms by embedding JSP code	XML Validation	Introduction to Database Driven web

	SLO-2	CSS 3 Introduction	Introduction to DHTML	Creating HTML forms by embedding JSP code	XSL Transformation	service from an application Database Driven web service from an application
S-9	SLO-1	CSS 3 Types	DHTML with JavaScript	Lab 6: Creating HTML forms by embedding JSP code	XSLT Transformation	Applications on Database Driven web service
	SLO-2	CSS 3: Positioning, Text Flow and Box Model		Creating HTML forms by embedding JSP code	News Feed (RSS and ATOM)	Applications on Database Driven web service

Learning Resources	1. Deitel, Deitel and Nieto, <i>Internet and World Wide Web : How to Program</i> , 5 th Edition, 2012, Prentice Hall,. ISBN-13:978-0-13-215100-9 2. Stephen Wynkoop, <i>Running a perfect website</i> , QUE, 2 nd Edition, 2001. ISBN 13: 9780789709448 3. Chris Bates, <i>Web Programming : Building Intranet applications</i> , 3 rd Edition, 2009, Wiley Publications,. ISBN 13:9780470017753.	3. Jeffrey C. Jackson, <i>Web Technologies A computer Science Perspective</i> , 2011, Pearson, ISBN 9780133001976 4. https://www.W3Schools.com
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100%	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
		Dr.R.Jebakumar

Course Code	18CSE362T	Course Name	INTEGRATIVE PROGRAMMING AND TECHNOLOGY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering	Data Book / Codes/Standards			Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Understand the concepts and features of Integrative programming				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2 :	Gain knowledge on Java network programming and JDBC for integrating applications							Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3		
CLR-3 :	Gain knowledge on Java component based technology for integrating reusable components across applications							H	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLR-4 :	Acquire knowledge on XML and JSON technology for data representation and exchange in integrating applications							H	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLR-5 :	Acquire knowledge in Java Messaging Service							H	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLR-6 :	Understand interoperability between programming languages							H	-	-	H	-	-	-	-	-	-	-	-	-	-	-	-	-
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1 :	Understand the basic ideas in Integrative coding				2	80	85																	
CLO-2 :	Acquire the ability to code java socket programming and java application to integrate databases				2	75	80																	
CLO-3 :	Acquire the ability to develop Enterprise Java bean components and Java based Web services				2	85	80																	
CLO-4 :	Appreciate the concepts of ML and JSON techniques in data representation and exchange for integrating applications				2	80	75																	
CLO-5 :	Acquire the knowledge for developing JMS based enterprise application integration				2	75	85																	

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Programming paradigms an overview	Java network programming and RMI overview	Component Based technology overview	Data representation and exchange techniques in integrating applications overview	Interoperability between programming languages an overview
	SLO-2	Integrative programming an overview,	Java networking basics	Java beans concept and feature for reusability	Understanding XML and JSON for data representation and exchange	Understanding Java platform runtime environment and JVM
S-2	SLO-1	Integrative coding and its supporting Object Oriented concepts like inheritance, interface polymorphism .	Socket programming for TCP	Visual Java Beans components features and steps for creation	Understanding XML validation, Schema,	Understanding Java Native Interface(JNI) concepts in integrating native application code in java applications
	SLO-2	Object oriented design pattern for integrative coding overview..	Options and features for socket programming	Integrating visual beans to different applications	Understanding XML parsers DOM and SAX variant parsers.	Java tools for JNI programming
S-3	SLO-1	Creational design pattern, structural design pattern, Behavioral design pattern	UDP programming using Datagram	Enterprise Java platform overview	Understanding Integration of Enterprise applications with XML	Java libraries for JNI support
	SLO-2	Concept of Inversion of Control	options and features for UDP programming	Enterprise java bean components features and types	JSON encoding and decoding implementation	Understanding Usage of IDE for JNI programming
S-4	SLO-1	Application Architecture overview	Secure socket Communication	Session bean concepts and its types	Concept of Messaging Queue in integrating software systems to exchange information Asynchronously	Understanding concepts in JNI programming .Name mangling and function signatures DLL ,The JNIEnv argument
	SLO-2	Multi-tier architecture for integrating application packages like client side, middleware and databases	IP multicast and Multicast socket programming	Entity bean concepts and types	JMS and its role in integrating application in java enterprise platform	Understanding Accessing of Java Strings, Passing and using Java objects in native code
S-5	SLO-1	Enterprise application architecture, overview	RMI and distributed applications	Implementing Enterprise application through integrating session and Entity beans	JMS features and benefits	Exception handling in JNI
	SLO-2	JEE platform and its features	Understanding stub and skeleton concept in RMI	Java web services an overview	JMS service providers	Threading concept in JNI

S-6	SLO-1	Understanding Design principles in Enterprise applications	RMI programming application steps	SOAP based web services .WSDL, SOAP message	Concept of Message queues	Python integration in java platform overview
	SLO-2	Enterprise application integration overview	RMI programming implementation	JAX-WS implementation for SOAP based webservices	Point to point messaging domain features	Jython programming concepts and features
S-7	SLO-1	Role of Design Patterns in Enterprise application integration,	Concepts in Java Database connectivity in integrating java applications with various databases	RESTful web services features	Application scenario for integrating applications through p2p messaging	Installation of Jython for developing applications to run in java platform.
	SLO-2	Designing distributed object interfaces	Understanding Types of data base connectivity Different drivers	JAX-RS implementation for Restful web services	Concept of publish/subscribe method of messaging	Jython programming basics
S-8	SLO-1	Front controller patterns	JDBC application program concepts and implementation	Integrating web services component to client application	Application scenario for integrating applications through publish/subscribe method based messaging	Accessing Java features and libraries of java in Jython code
	SLO-2	Facade patterns,	Java persistence API overview	Service discovery, UDDI	Message driven beans in Enterprise JavaBeans	Java swing based GUI development in Jython
S-9	SLO-1	Adapter patterns	Java Data Objects(JDO) concepts	Policy and security for web services	Features and environmental setup for implementing Message driven beans	Understanding Jython JDBC connectivity
	SLO-2	Concepts of DAO	Java persistence API frameworks overview	Comparison between SOAP and RESTful web services	Understanding and using JMS in Message driven beans	Integrating Jython code in Java application

Learning Resources	1. KogentLearningSolutionsInc, JAVAServerProgrammingJavaEE7BlackBook , 5 th ed., Weily India, 2016. 2. ElliotteRustyHarold, JavaNetworkprogramming, O'Reilly, 2013	3. Cay S. Horstmann , D. R., Core Java Volume II - Advanced Features 10 nd ed., John Wiley & Sons, 2013.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#		Theory	Practice
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice		
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 2	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 3	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Venketasan Palavesam Delivery Head L & T		1.Mr. K. Navin, SRMIST
2. K.S.Kumar COO MindZen, India private Ltd		Mr S.Ramaraj and Dr. Parthiban

Course Code	18CSE364T	Course Name	SYSTEM ADMINISTRATION AND MAINTENANCE	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	
Course Offering Department	Computer Science and Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand the factors that make Authentication/Authorization and stores of system Administration				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Acquire a knowledge and understanding of the specific problems in the Enterprise Security, and be able to apply some of the techniques				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Identify the specific challenges that inherent in the Budget and Desktop Deployment of system Administration that are able to apply some of the techniques that can be of use in comprehending and changing them																					
CLR-4 :	Evaluate and understand the specific problems inherent in the system maintenance and evolution of package- based operating system, and be able to apply techniques for designing change-resistant systems from pre- packaged code.																					
CLR-5 :	Analyze and apply system maintenance technical concepts that relate to UPS software administration																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	Explain terms used in make Authentication/Authorization and stores of system Administration				3	80	70	H	H	H	H	H	-	-	-	H	H	-	H	-	-	-
CLO-2 :	Incorporate a knowledge and understanding of the specific problems Enterprise Security, and be able to apply some of the				3	85	75	M	H	H	M	H	-	-	-	M	H	-	H	-	-	-
CLO-3 :	Identify challenges that inherent in maintenance and evolution of package-based operating system, and be able to apply techniques				3	75	70	M	H	M	H	H	-	-	-	M	H	-	H	-	-	-
CLO-4 :	Apply techniques for designing change-resistant systems from pre-packaged code.				3	85	80	M	H	M	H	H	-	-	-	M	H	-	H	-	-	-
CLO-5 :	Apply system maintenance technical concepts that relate to UPS software administration				3	85	75	H	H	M	H	H	-	-	-	M	H	-	H	-	-	-

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Authentication/Authorization	Thin client support:	Issues relating to proposal construction and endorsement: New project development issues,	Customization of Operating System and maintenance of system:3 types of media to use when backing up your data and when each method is appropriate,	UPS: Identify the specifications of UPS,
	SLO-2					
S-2	SLO-1 SLO-2	Storage: Storage Area Networks	LTSP, Citrix	RFC construction, RFP Process,	How to create automated backups to ensure you always have a recent backup,	Switch-on and Switch-off procedure of UPS,
S-3	SLO-1	Network Attached Storage	Windows Terminal services,	Budgeting,	Learn how to manually backup data, How to make an exact copy of a hard drive	Measurement of Input/output voltage/current levels, battery charge level,
	SLO-2					
S-4	SLO-1 SLO-2	Storage Virtualization, Enterprise Backup and Restoration Issues	Sun Ray Services	Budgeting for new projects	Hardware Troubleshooting: The danger in not diagnosing problems first,	Identifying status of UPS from front panel indicators,
S-5	SLO-1 SLO-2	Enterprise Service Deployment: Clustering and fault tolerance,	Enterprise Security:	Desktop Deployment and Management, Alternative Desktops: SUS	Learn how to test your RAM ,	carryout routine maintenance of battery, battery terminals, loose contacts etc.,
S-6	SLO-1	Virtualization of services, Grids/On Demand/N1	Disaster Recovery	RIS,	check your hard drive for errors	Test UPS as per specification. Verification of back-up time.
	SLO-2					
S-7	SLO-1	Enterprise Applications: Enterprise Resource Planning,	Policies	Sun Java Desktop,	PC Cleaning: The best cleaning supplies to use,	Circuit tracing and fault finding practice
	SLO-2					
S-8	SLO-1	Customer Relationship Management,	Planning	Xandros	How to increase airflow and increase your computers lifespan	Servicing of UPS by simulating more likely faults and systematic approach to identify and rectify them
	SLO-2					
S-9	SLO-1	Office Automation	Procedures	Lindows	How to clean your computer	backup times its dependence on battery's load and its calculations
	SLO-2					

Learning Resources	1. Tittel, et al, A Guide to Microsoft Exchange Server 5.5, Course Technology	2. Hughes and Thomas, Novell's Guide to NetWare 5 Networks, IDG
		3. Harvel et al, Unix and Windows 2000 Handbook, Prentice Hall

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50%)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100%	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
		1. Mr.S.Selvakumara Samy., SRMIST

Course Code	18CSE365T	Course Name	FUNDAMENTALS OF VIRTUALIZATION	Course Category	E	Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1:	Understand about Computing Virtualization tools, applications and techniques	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2:	Understand CPU virtualization, memory virtualization	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3:	How to configure VM CPU and memory options	Expected Proficiency (%)	Problem Analysis
CLR-4:	Understand storage and network virtualization	Expected Attainment (%)	Design & Development
CLR-5:	Acquire knowledge about virtualization security		Analysis, Design, Research
CLR-6:	Learn about many case studies		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1:	Able to define, distinguish Computing Virtualization tools, applications and techniques	3 80 70	L H - H L - - - L L - H - - -
CLO-2:	Create a virtual environment and install VM with several guest operating systems	3 85 75	M H L M L - - - M L - H - - -
CLO-3:	Able to configure virtual machine CPU and memory options	3 75 70	M H M H L - - - M L - H - - -
CLO-4:	Able to configure VM storage and network options	3 85 80	M H M H L - - - M L - H - - -
CLO-5:	Identify threats and able to security to virtualized environment	3 85 75	H H M H L - - - M L - H - - -
CLO-6:	Investigate and discuss about case studies	3 80 70	L H - H L - - - L L - H - - -

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Overview Of Virtualization -Basics of Virtualization -	Creating a Virtual machine- Performing P2V Conversions	Managing Storage for a virtual machine-Understanding storage virtualization	Theory Network Device Virtualization - VLANs
	SLO-2	Virtualization Types – Desktop Virtualization	Loading your Environment	Configuring VM Storage options	VRF Instances- VFIs -Virtual Firewall Contexts Network Device Virtualization
S-2	SLO-1	Storage Virtualization – System-level Operating Virtualization – Application Virtualization-	Building a new Virtual machine	Tuning practices for VM storage	Fundamentals of Virtualization security- Virtualization architecture
S-3	SLO-1	Virtualization Advantages	Managing CPUs for a virtual machine- Understanding CPU Virtualization	SCSI- Speaking SCSI- Using SCSI buses – Fiber Channel – Fiber Channel Cables – Fiber Channel Hardware Devices – iSCSI Architecture – Securing iSCSI	Threats to a virtualized environment
S-4	SLO-2		Configuring VM CPU options	Server virtualization concepts	How security must adapt to virtualization
S-5	SLO-1	Understanding Hypervisors	Tuning practices for VM CPUs	Introduction to server virtualization, Types of server virtualization technologies	Securing hypervisors-Hypervisor configuration and security
S-6	SLO-2			Limitations of server virtualization	
S-7	SLO-1	Understanding Virtual Machines	Managing Memory for a virtual Machine- Understanding memory virtualization, Configuring VM memory options	Managing Networking for a virtual machine- understanding network virtualization	Designing virtual networks for security- comparing virtual and physical networks
S-8	SLO-2	Assignment-Installing windows, Linux on a virtual machine	Tuning practices for VM memory	Configuring VM network options	Virtual network security considerations
S-9				Tuning practices for Virtual networks	Configuring virtual switches for security

Learning Resources	1. William von Hagen, <i>Professional Xen Virtualization</i> , Wrox Publications, January, 2008 2. <i>Virtualization Essentials</i> by Matthew Portnoy ISBN: 978-1118176719	3. <i>Virtualization Security: Protecting Virtualized Environments</i> , Dave Shackleford, Sybex Publications, 2013 4. Kumar Reddy, Victor Moreno, <i>Network Virtualization</i> , Cisco Press, July, 2006. 5. David Marshall, Wade A. Reynolds, <i>Advanced Server Virtualization: VMware and Microsoft Platform in the Virtual Data Center</i> , Auerbach Publications, 2006.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
	Ms.SS.Subashka, SRMIST, Ramapuram	1. Mrs. TYJ Naga Malleswari SRMIST
	Mr. B.S. Vidhyasagar, SRMIST, Vadapalani	2. Mrs Sasirekha Sankar, SRMIST
		3. Dr.MB.Mukesh krishnan SRMIST

Course Code	18CSE366T	Course Name	HUMAN COMPUTER INTERACTION	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NA	Co-requisite Courses	NA	Progressive Courses	//Course code
Course Offering Department	Computer Science and Engineering	Data Book / Codes/Standards	NA		

Course Learning Rationale (CLR):	The purpose of learning this course is to:
CLR-1 :	Understand the basic concepts of HCI
CLR-2 :	Learn the various design and software processes
CLR-3 :	Become familiar with different models of HCI and evaluation techniques
CLR-4 :	Learn web interface design
CLR-5 :	Learn mobile interface design

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:
CLO-1 :	Explain why it is important to design interactive products that are usable
CLO-2 :	Explain key terms used in interactive design
CLO-3 :	Explain the need for different models and the importance of evaluation
CLO-4 :	Gain knowledge on web interface design
CLO-5 :	Attain knowledge on mobile interface design

Learning		
1	2	3
Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)
3	75	70
3	75	70
3	65	60
3	55	50
3	55	50

Program Learning Outcomes (PLO)														
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
			M											
			M											
													M	
			M	H				M					M	
			M	H				M					M	

Duration (hour)	9	9	9	9	9
S-1	Human: I/O Channels, Memory	Interactive design basics: Design process, Navigation design	Cognitive models: Introduction and GOMS	Designing web interfaces:	Mobile Interface design:
S-2	Thinking: Reasoning and Problem Solving, Emotion	Screen design and layout, Iteration and prototyping	Linguistic model	Introduction and Brainstorming session	Introduction and Brainstorming session
S-3	Individual differences, Psychology design of interactive systems	Software process: Software lifecycle, Usability engineering	Physical and device models	Drag and Drop,	Mobile Ecosystem: Platforms
S-4	Computer: Devices, Physical controls, sensors and special devices	Iterative design and prototyping, Design rationale	Organizational issues, Capturing requirements	Direct Selection	Application frameworks
S-5	Readability of text, Memory, Processing and networks	Design rules: Principles, Standards	Communication and collaboration models:	Contextual tools	Types of mobile applications: Widgets,
S-6	Interaction: Basics and Models	Guidelines, Golden rules	face-to-face and conversation	Overlays	Application, Games
S-7	Frameworks, Ergonomics, Interaction styles	Evaluation techniques: Goals, evaluation through expert analysis	Text based Communication and Group working	Inlays and Virtual pages	Mobile Information Architecture
S-8	WIMP interface elements, Interactivity	Evaluation through user participation	Task analysis: Introduction and Task decomposition comparison	Process flow	Mobile design: Elements and Tools
S-9	Paradigms: Interactive paradigms	Universal design: Principles, Multi-modal interaction User support: Requirements and Approaches	Knowledge based analysis	Case Study discussion	Case Study discussion

Learning Resources	<ol style="list-style-type: none"> 1. <i>Human Computer Interaction</i> by Alan Dix, Janet Finlay, Gregory D.Abowd and Russell Beale – Third Edition - Pearson Education – 2004 2. <i>Human Computer Interaction</i> by K.Meena and R.Sivakumar – 2015 – Prentice Hall India 3. <i>Designing the User Interface: Strategies for Effective Human Computer Interaction</i> by Ben Shneiderman and Catherine Plaisant – Fifth Edition - 2009 – Pearson Addison Wesley 4. <i>Designing Web Interfaces</i> by Bill Scott and Theresa Neil – First Edition – O'Reilly Media Inc. – 2009 5. <i>Mobile Design and Development</i> by Brian Fling - First Edition – O'Reilly Media Inc. – 2009
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CA – 3 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

SLO – Session Learning Outcome

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
	<i>Dr.T.Nagarajan, Professor and Head,Dept. of IT, SSN college of Engineering.</i>	<i>1. Dr. M. Thenmozhi, SRMIST</i>
		<i>2. Dr.S Prabakaran, SRMIST</i>
		<i>3. Dr. Alice Nithya , SRMIST</i>

Course Code	18CSE397T	Course Name	COMPUTATIONAL DATA ANALYSIS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1:	Understand the underlying assumptions, verify them, and propose appropriate actions if some assumptions do not hold	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2:	Identify appropriate statistical learning methods for the given problem involving real data.		
CLR-3:	Evaluate performance of the chosen regression and classification techniques and compare them		
CLR-4:	Show, analytically or empirically, the optimal balance between precision within training data and prediction power.		
CLR-5:	Use training and testing data to evaluate performance of the chosen regression and classification techniques and compare them.		
CLR-6:	Illustrate results with appropriate plots and diagrams.		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Engineering Knowledge
CLO-1:	Acquire the knowledge on methods, theory, mathematics and algorithms in data analysis	2 80 85	H - - - - - - - - - - - - - - - -
CLO-2:	Acquire the ability to To formulate and model mathematical and computational tasks	2 75 80	H H - - - - - - - - - - - - - - - -
CLO-3:	Understand the basic ideas about high-level data analysis, concepts and techniques	2 85 80	H - - - - - - - - - - - - - - - -
CLO-4:	Acquire the ability identify other possible problems with messy data, such as multi-collinearity, understand their consequences, and propose solutions.	2 80 75	H H - - - - - - - - - - - - - - - -
CLO-5:	Apply the knowledge To build from scratch the basic components of a data analysis pipeline	2 75 85	H - - - H - - - - - - - - - - - - - - - -
CLO-6:	To Show, analytically or empirically, the optimal balance between precision within training data and prediction power.	2 80 85	H - - - - - - - - - - - - - - - -

Duration (hour)	9	9	9	9	9
S-1	SLO-1 General Introduction	Generative Algorithms: Multivariate Normal	Unsupervised Learning:	Regularization and Model Selection:	Decision Tree and Random Forest:
	SLO-2 Supervised Learning	Linear Discriminant Analysis	PCA	Cross Validation,	Entropy
S-2	SLO-1 Least Squares and Nearest Neighbors	Naive Bayes	Mixture Models	Hill Climbing	Building Tree Bagging features
	SLO-2 Statistical Models	Laplacian Smoothing	Bayesian Graphical Models	Bayesian Optimization	Bagging Samples
S-3	SLO-1 Discriminative Algorithms	Multiclass Classification	Power Method	Bayesian Regression	Random Forest Adaboost
	SLO-2 Supervised Learning Concept	K-NN	Oja's algorithm	Bayesian Logistic	Gradient Tree Boosting
S-4	SLO-1 Linear Regression	Multi-class Fisher Discriminant Analysis	EM Algorithm	Regression Forward and	Boosting and Regularization Paths
	SLO-2 The Gauss–Markov Theorem	Multinomial Regression	Variational Inference	Backward Regression	Learning Ensembles
S-5	SLO-1 Multiple Regression	Support Vector Machines and Kernel Methods	Matrix Factorization/Completion	Lasso	Proximity Plots
	SLO-2 Maximum Likelihood	Intuition, Geometric Margins,	Independent Component Analysis	elastic-net	Random Forests and Overfitting
S-6	SLO-1 Normal Equation	Optimal Margin Classifier	The Google PageRank Algorithm	Proximal Gradient	Neural Network: Concept
	SLO-2 Gradient Descent	Lagrangian Duality, Soft-margin,	Principal Components, Curves and Surfaces	Prox-SVRG	Deep Neural Network
S-7	SLO-1 Stochastic Gradient	Loss function, Stochastic Subgradient Method	Cluster Analysis	Coordinate Proximal Gradient	Backpropagation
	SLO-2 SVRG	Kernel, SMO algorithm	Proximity Matrices	Pathwise Coordinate Descent	Convolutional Neural Network;
S-8	SLO-1 Linear Classification	Coordinate Gradient Descent	Dissimilarities Based on Attributes	Principal Components Regression	Bayesian Neural Nets
	SLO-2 Linear Discriminant Analysis	Kernel PCA, Kernel Logistic Regression	Object Dissimilarity	Incremental Forward Stage wise Regression	Bayes, Boosting and Bagging
S-9	SLO-1 Logistic Regression	Kernel Ridge Regression	Clustering Algorithms	The Dantzig Selector	Fitting Neural Networks
	SLO-2 Newton Method	Multiclass SVM	Combinatorial Algorithms	The Grouped Lasso	Issues in Training Neural Networks

Learning Resources	1. <i>Hastie, Tibshirani and Friedman, The Elements of Statistical Learning, Data Mining, Inference and Prediction, 2nd ed., Springer, 2008.</i>	3. <i>Andrew Ng, CS229 Lecture notes: http://cs229.stanford.edu/notes/cs229-notes1.pdf</i>
	2. <i>Mohri, Rostamizadeh and Talwalker, Foundations of Machine Learning, The MIT Press Cambridge, Massachusetts London, England, 2012</i>	

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. Jayaraj Chandrasekaran, UST Global, Chennai, jayaraj.chandrasekaran@ust-global.com	Dr. Devaki, Rajalakshmi Engineering College, Professor, Department of Computer Science and Engineering,	Mrs. S. Nagadevi
		Dr. G. Vadivu

Course Code	18CSE461T	Course Name	INTERNET SECURITY AND CYBER FORENSICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18CSC302J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering		Data Book / Codes/Standards	Nil	

Course Learning Rationale (CLR):		The purpose of learning this course is to:		Learning			Program Learning Outcomes (PLO)																		
CLR-1 :	Study about various threats associated with security and information warfare			Level of Thinking (Bloom)	1	2	3	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Study about email security and the Importance of Firewalls and their types																								
CLR-3 :	Impart an introduction to the need of computer forensics																								
CLR-4 :	Study the tools and tactics associated with cyber forensics																								
CLR-5 :	Analyze and validate computer forensics data																								
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																							
CLO-1 :	Have thorough knowledge about various threats associated with security and information warfare			2	85	80	L	H	-	L	L	-	-	-	L	L	-	H	-	H	-	-	-	-	
CLO-2 :	Have in-depth knowledge about email security and understand the Importance of Firewalls and their types			2	85	75	M	H	-	M	L	-	-	-	M	L	-	H	-	-	-	-	-		
CLO-3 :	Understand the need of computer forensics			2	80	75	M	H	M	H	L	-	-	H	M	M	-	H	-	-	-	-	-		
CLO-4 :	Utilize the tools and tactics associated with cyber forensics			3	75	70	M	H	M	H	H	-	-	H	M	M	-	H	-	-	-	-	-		
CLO-5 :	Analyze and validate computer forensics data and apply them for solving computer forensics issues			3	75	70	H	H	M	H	M	-	-	H	M	M	-	H	-	-	-	-	-		

Duration (hour)		9	9	9	9	9
S-1	SLO-1	IPSec Protocol – Basics	PGP – Confidentiality and Authentication	Computer Forensics Fundamentals: Introduction to Computer Forensics, Use of Computer Forensics in Law Enforcement, Computer Forensics Assistance to Human Resources/Employment Proceedings	Processing Crime and Incident Scenes: Identifying Digital Evidence	Computer Forensics Analysis and Validation, Determining what data to collect and analyze
	SLO-2	IPSec Protocol - Documents	PGP – Compression and E-mail compatibility via Radix-64 conversion	Computer Forensics Services, Benefits of Professional Forensics Methodology, Steps Taken by Computer Forensics Specialists, Who Can Use Computer Forensic Evidence?	Collecting Evidence in Private-Sector Incident Scenes, Processing Law Enforcement Crime Scenes	Validating Forensics Data, Validating with Hexadecimal Editors, Validating with Computer Forensics Programs
S-2	SLO-1	IPSec Protocol – Security Associations	MIME	Types of Computer Forensics Technology: Types of Military Computer Forensic Technology	Preparing for a Search	Data Hiding Techniques - Hiding Partitions, Marking Bad Clusters, Bit-Shifting
	SLO-2	Hashed Message Authentication Code (HMAC)	S/MIME	Types of Law Enforcement: Computer Forensic Technology	Securing a Computer Incident or Crime Scene , Seizing Digital Evidence at the Scene	Using Steganography to Hide Data,
S-3	SLO-1	IP Authentication Header	Internet Firewalls for Trusted System: Roles of Firewalls	Types of Business Computer Forensic Technology	Storing Digital Evidence, Obtaining a Digital Hash	Examining Encrypted Files, Recovering Passwords
	SLO-2	IP ESP	Firewall related terminology	Specialized Forensics Techniques	Reviewing a Case	Performing Remote Acquisition, Remote Acquisitions with Runtime Software
S-4	SLO-1	Key Management Protocol for IPSec – OAKLEY Key Determination Protocol	Types of Firewalls	Types of Computer Forensics Systems: Internet Security Systems, Intrusion Detection Systems, Firewall Security Systems	Working with Windows and DOS Systems	Network Forensics
	SLO-2	Key Management Protocol for IPSec – ISAKMP	Packet filters	Storage Area Network Security Systems, Network Disaster Recovery Systems, Public Key Infrastructure Systems	Understanding File Systems, Exploring Microsoft File Structures	Securing a Network
S-5	SLO-1	Transport layer Security : SSL and TLS	Circuit level gateways	Wireless Network Security Systems, Satellite Encryption Security Systems, Instant Messaging (IM) Security Systems , Net Privacy Systems	Examining NTFS Disks	Email Investigations – Exploring the Role of E-mail in Investigations, Exploring the Roles of the Client and Server in E-mail
	SLO-2	SSL Protocol	Application level gateways	Identity Management Security Systems, Identity Theft,	Understanding Whole Disk Encryption	Investigating E-mail Crimes and Violations:

				Biometric Security Systems, Homeland Security Systems		Examining E-mail Messages, Viewing E-mail Headers, Examining E-mail Headers, Examining Additional E-mail Files
S-6	SLO-1	SSL Record Protocol	Firewall designs	Understanding Computer Investigation: Preparing a Computer Investigation, Taking a Systematic Approach	Understanding the Windows Registry	Tracing an E-mail Message, Using Network E-mail Logs
	SLO-2	SSL Change Cipher Spec Protocol	Screened Host Firewall (Single – Homed Bastion Host)	Procedures for Corporate High-Tech Investigations	Understanding Microsoft Startup Tasks, Understanding MS-DOS Startup Tasks, Understanding Virtual Machines	Understanding E-mail Servers - Examining UNIX E-mail Server Logs, Examining Microsoft E-mail Server Logs, Examining Novell GroupWise E-mail Logs, Using Specialized E-mail Forensics Tools
S-7	SLO-1	SSL Alert Protocol	Screened Host Firewall (Dual – Homed Bastion Host)	Understanding Data Recovery Workstations and Software	Current Computer Forensics Tools: Software/Hardware Tool	Cell Phone and Mobile Devices Forensics
	SLO-2	SSL Handshake Protocol	Screened Subnet Firewall	Conducting an Investigation, Completing the Case	Evaluating Computer Forensics Tool Needs	Understanding Mobile Device Forensics
S-8	SLO-1	Cryptographic Computations – Computing the Master Secret	SET for E-Commerce Transactions: Business requirements for SET	Data Acquisition: Understanding Storage Formats for Digital Evidence, Determining the Best Acquisition Method, Contingency Planning for Image Acquisitions, Using Acquisition Tools	Types of Computer Forensics Tools, Tasks Performed by Computer Forensics Tools	Mobile Phone Basics, Inside Mobile Devices
	SLO-2	Cryptographic Computations – Converting the Master Secret into Cryptographic Parameters	SET System Participants	Validating Data Acquisitions, Performing RAID Data Acquisitions	Computer Forensics Software Tools, Command-Line Forensics Tools, UNIX/Linux Forensics Tools, Other GUI Forensics Tools	Inside PDAs
S-9	SLO-1	TLS Protocol	SET Cryptographic Operation Principles, Dual Signature, Authentication and Message Integrity	Using Remote Network Acquisition Tools	Computer Forensics Hardware Tools, Forensic Workstations, Using a Write-Blocker, Recommendations for a Forensic Workstation	Understanding Acquisition Procedures for Cell Phones and Mobile Devices
	SLO-2	Cryptographic Computations for TLS	SET Payment Processing	Using Other Forensics Acquisition Tools	Validating and Testing Forensics Software, Using National Institute of Standards and Technology (NIST) Tools, Using Validation Protocols	Mobile Forensics Equipment

Learning Resources	<p>1. Man Young Rhee, "Internet Security: Cryptographic Principles, Algorithms and Protocols", Wiley Publications, 2003</p> <p>2. Christopher Steuart, Bill Nelson, Amelia Phillips, "Guide Computer Forensics and Investigations", Cengage Learning, India, Fourth Edition, 2013.</p>	<p>2. John R. Vacca, "Computer Forensics: Computer Crime Scene Investigation", Charles RiverMedia, 2002.</p> <p>3. Richard E. Smith, "Internet Cryptography", Pearson Education, 3rd Edition, 2008.</p> <p>4. Marjie T. Britz, "Computer Forensics and Cyber Crime: An Introduction", Pearson Education, 3rd Edition, 2013.</p>
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
	1. Dr.L.Kavisankar, Associate Professor, Department of Computer Science and Engineering, Hindustan Institute of Technology and Science, Chennai, India	1. Mr. S.Saminathan, SRMIST
		2. Dr.M.B.Mukesh Krishnan, SRMIST

Course Code	18CSE462T	Course Name	DATA CENTRE ADMINISTRATION AND MANAGEMENT	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1:	Critically discuss data center networking technologies	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2:	Evaluate key concepts in data center design		
CLR-3:	Concepts related to data center maintenance		
CLR-4:	Design, build and configure a data centers		
CLR-5:	Expose to implementing the various system management practices		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Engineering Knowledge
CLO-1:	Manage Server Systems and Data Centres Infrastructure Management	1 90 85	L - - M - - - - - - - - H L - -
CLO-2:	Utilize the Storage, Bandwidth, Efficiency of systems and other resources for Data centre.	3 85 80	M M H H H - - - - - H M H -
CLO-3:	Monitoring the Networks and Resources. .	3 85 80	M H H H H - - - - - H M H -
CLO-4:	Planning for Flexible resource allocation	3 80 75	M H H H H - - - - - H H H -
CLO-5:	Administer the data centers	3 80 75	H H H H H H - M - - - H M H H

Duration (hour)	9	9	9	9	9
S-1	SLO-1 SLO-2	Data center Architecture	Data Center design	Data Center Maintenance	Data Center HVAC
S-2	SLO-1 SLO-2	Data center Requirements	Characteristics of an Outstanding Design	Network Operations Center, Network Monitoring	Reasons for Strict Environmental Requirements
S-3	SLO-1 SLO-2	Data center prerequisites	Characteristics of an Outstanding Design	Datacenter physical security	Need for Energy-Efficient HVAC Systems
S-4	SLO-1 SLO-2	Physical Area for Equipment and Unoccupied Space	Guidelines for Planning a Data Center	Data center Logical security	Air-Conditioning Systems
S-5	SLO-1 SLO-2	Required power to run all the devices	Data Center structures	Data center Cleaning	Air Circulation in a Data Center
S-6	SLO-1 SLO-2	Required cooling and HVAC Required weight	Raised Floor Design and Deployment	Floor Surface Cleaning	Placement of Hardware Racks
S-7	SLO-1 SLO-2	Budget Constraints	Design and Plan against Vandalism	Subfloor and Above-Ceiling Plenum Cleaning	Bottom-to-Top Cooled Racks
S-8	SLO-1 SLO-2	Selecting a Geographic Location Safety from Natural hazards	Data center design case study	Equipment Cleaning	Top-to-Bottom Cooled Racks
S-9	SLO-1 SLO-2				Front-to-Front Cooled Racks
					Front-to-Back Cooled Racks
					Load balancing, Terminology, Advantages & Types of load balancing

Learning Resources	<ol style="list-style-type: none"> 1. Mouricio Arregoces, "Data Centre Fundamentals", Cisco Press ,2003 2. Administering Data Centers: Servers, Storage and Voice over IP, Kailash Jayaswal. 3. Kevin Corbin, Ron Fuller, David Jansen, "NX-OS and Cisco Nexus Switching: Next-Generation Data Center Architectures" Cisco Press; 1 edition [ISBN: 9781587058929], 2010. 4. SilvanoGai, TommiSalli, Roger Andersson, "Cisco Unified Computing System" Cisco Press; 1 edition, [ISBN: 9781587141935], 2010. 5. Nash Darukhanawalla, Patrice Bellagamba, "Interconnecting Data Centers Using VPLS" Cisco Press; 1 edition, [ISBN: 9781587059926], 2009. 6. Robert W. Kembel, Roger Cummings (Introduction), "The Fibre Channel Consultant" Northwest Learning Assoc; 3rd edition, [ISBN: 0931836840], 1998. 7. Robert W Kembel"Fiber Channel Switched Fabric" Northwest Learning Associates, inc. [ISBN: 0931836719], 2009. 8. John L. Hufferd, "ISCSI", Addison-Wesley Boston [ISBN: 978- 0201784190], 2003.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#		Theory	Practice
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice		
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 2	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 3	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Dr.M.S.Sricharan/Wipro Technologies		Dr. B.Amutha, Professor and Head, Department of CSE, SRM IST
		Dr. G.Vadivu, Professor and Head, Department of IT, SRM IST

Course Code	18CSE463T	Course Name	IT SERVICE MANAGEMENT AND OPERATIONS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning		
CLR-1 :	To develop an awareness of the opportunities that information technology can have for enhancing service firms' competitiveness.				1	2	3
CLR-2 :	To appreciate the organizational significance of managing the IT service encounter to achieve internal and external customer satisfaction.				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)
CLR-3 :	To understand new service development from both a product and process perspective.						
CLR-4 :	To gain an appreciation of the complexities associated with implementing change during IT services.						
CLR-5 :	to understand how an integrated ITSM framework						
CLR-6 :	To Understand practical implementation of Information Technology Service Management						
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)
CLO-1 :	Illustrate the basic concepts of Service Science, Management, and Engineering				3	80	70
CLO-2 :	Examine the principle of IT service processes				3	85	75
CLO-3 :	Skills for planning, estimating, and resourcing for IT services				3	75	70
CLO-4 :	Manage the scope changes and the organizational changes in IT services				3	85	80
CLO-5 :	Ability to identify IT services as a means to provide functionality and value to customers in the context of specific case studies				3	85	75
CLO-6 :	Ability to understand the needs and targets of the different stakeholders (service providers, customers, suppliers/partners) in the services value chain.				3	80	70

Program Learning Outcomes (PLO)														
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
L	H	L	H	L	L	M	L	L	L	M	L	L	L	L
L	H	L	H	L	L	M	L	L	L	M	L	L	L	L
L	H	L	H	L	L	M	L	L	L	M	L	L	L	L
L	H	L	H	L	L	M	L	L	L	M	L	L	L	L
L	H	L	H	L	L	M	L	L	L	M	L	L	L	L
L	H	L	H	L	L	M	L	L	L	M	L	L	L	L

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction	IT Project/Service Management	Communication Management	Service management concepts and frameworks	Planning and delivery processes
	SLO-2	Overview of Service Science, Management, Engineering				
S-2	SLO-1	IT Infrastructure	Planning	Team Building in IT Services	Services and service management	Service reporting
	SLO-2					
S-3	SLO-1	RFID Applications	Estimating	IT service project in a start-up company	Customer-facing services	Service availability and continuity management
	SLO-2					
S-4	SLO-1	Data Storage Management	Resourcing	Smaller IT service organization	Resource-facing services	Capacity management
	SLO-2					
S-5	SLO-1	IT Service Strategy	IT Project/Service Change	Soft Skills in IT Service Management	The service lifecycle. Processes. Functions. Roles	Information security management
	SLO-2					
S-6	SLO-1	Approach, and Practice	Quality	Presentation skills	Service strategy	Customer relationship management
	SLO-2					
S-7	SLO-1	IT Infrastructure Library	Issue	Negotiation skills	Service portfolio	Supplier relationship management.
	SLO-2					
S-8	SLO-1	e-Business Case Study	Risk Management	Job interview skills	Service catalog management	Service management tools
	SLO-2					

S-9	SLO-1	IT service report of IBM e-business at Ford Motor	Evaluate issue, and mitigate risk in IT service management	IBM perspectives of IT Service Management	Service level agreements.	Tool assessment framework
	SLO-2				Operational level agreements	Analysis of specific ITSM tools

Learning Resources	1. Service Management, Fourth Edition, J.A. Fitzsimmons and M.J. Fitzsimmons, McGraw Hill. 2. Services Marketing, Valerie Zeithaml, Mary Jo Bitner, and Dwayne Gremler, McGraw-Hill. 3. Introduction to Operations Research, Hillier and Lieberman 4. Service modeling, Principles and Applications. Vilho Räsänen, Wiley 5. Understanding Service Business, S.E. Sampson, Wiley.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. Kesawan HCL Technologies	Dr. Surendran Rajendran AMA International University Bahrain	1. Dr.M.B Mukesh Krishnan, SRMIST
Mr.Celeian, Symantec		2. Mr.C.Santhan Krishnan, SRMIST
		3. Mr. G. Senthil Kumar , SRMIST

Course Code	18CSE464T	Course Name	COMPUTER GRAPHICS AND GAME PROGRAMMING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1:	Understand the fundamental concepts of generating basic output primitives	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Know the basics of transformations and curves and surface representations	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3:	Know the various visible surface detection methods and various color models																		
CLR-4:	Learn the interfaces of Unity and its installation procedure																		
CLR-5:	Know the various objects in Unity to develop games																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1:	Have a very good understanding of generating various output primitives	2	80	85	-	-	H	-	-	-	-	-	-	-	-	-	-	M	-
CLO-2:	Posses the ability to represent various curves and surfaces	2	75	80	-	-	-	-	-	-	-	-	-	-	-	-	-	M	-
CLO-3:	Have a clear understanding of various visible surface detection algorithms and color models	2	85	80	-	-	-	-	-	-	-	-	-	-	-	-	-	M	-
CLO-4:	Apply the knowledge to install and explore the interfaces of Unity	2	80	75	-	-	H	-	H	-	-	-	H	-	-	-	-	-	-
CLO-5:	Possess the ability to design and implement games using Unity	2	75	85	-	-	H	-	H	-	-	-	H	-	-	-	-	-	-

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Graphics systems Overview and IO devices	Basic Three-Dimensional Concepts	Classification of visible surface detection Algorithms	Introduction to Unity Installation and its interface	Concept of collisions
	SLO-2					
S-2	SLO-1	Applications of Computer Graphics	Clipping operations-Point, Line and Polygon	Back-face detection, Depth buffer method and A-buffer method	Game objects, 2D&3D and its transformation	Introduction to Prefabs
	SLO-2					
S-3	SLO-1	Line drawing algorithms	Curve, Text and Exterior Clipping	Scan line method, Depth sorting method, BSP and Area sub division method	Fundamentals of models, materials and shaders	Handling sprites and adding UI to the game
	SLO-2					
S-4	SLO-1	Circle drawing algorithms	Polygon Clipping algorithms	Octree, Ray casting method and curved surfaces	How to sculpt terrain	Basics of particle systems
	SLO-2					
S-5	SLO-1	Ellipse drawing algorithms	Plane equations and meshes	Basic models of illumination	Adding environments	Basics of animation
	SLO-2					
S-6	SLO-1	Filled area primitives	Curved line& surfaces	Halftone and dithering techniques	Using lights	Designing a complex game
	SLO-2					
S-7	SLO-1	Basics of Geometric transformations	Quadratic surfaces and Blobby objects	Properties of Light, RGB Color Model	Using cameras	Basics of audio in Unity
	SLO-2					
S-8	SLO-1	Reflection and shearing -2D	Fractals	YIQ, and CMY color model	Designing a basic game	Basics of audio in Unity
	SLO-2					
S-9	SLO-1	2D viewing and window to viewport	Bezier and B-Spline curves and surfaces	HSV and HLScolor model, Color selection	Introduction to scripting	Requirements for mobile game development
	SLO-2					

Learning Resources	<ol style="list-style-type: none"> 1. Donald Hearn & M.PaulineBaker, "Computer Graphics C Version", 2nd Edition, Pearson Education, 2010, ISBN 978-93-325-3587-9 2. John F.Hughes, Andries VanDam, Morgan McGuire, David F.Sklar, James D.Foley, Steven K.Feiner, KurtAkeley, "Computer Graphics: Principles and Practice", 3rd Edition, Addison-Wesley Professional, 2013, ISBN-13: 0785342399523 3. Mike Geig, "Unity 2018 Game Development in 24 Hours, Sams Teach Yourself " 3rd Edition, Pearson Education, 2018, ISBN-13:978-0134998138, ISBN-10:0134998138 4. Joseph Hocking, "Unity in Action: Multiplatform game development in C#", 2nd Edition, Manning Publications Company, ISBN: 9781617294969 5. Dr. Edward Lavieri, "Getting Started with Unity 2018 - Third Edition: A Beginner's Guide to 2D and 3D game development with Unity ", Packt Publishing Ltd., 2018, ISBN-10: 1788830105, ISBN-13: 978-1788830102.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Valiyullasha, Bugtreat Technologies, UK, coe@bugtreat.com	C.M.T.Karthigeyan, Assistant Professor, Government College of Engineering, Bargur, email: c.m.t.karthikeyan@gcebargur.ac.in	P.Rajasekar, Assistant Professor, Department of Information Technology, Faculty of E&T, &SRMIST, email: rajasekp@srmist.edu.in

Course Code	18CSE465T	Course Name	COMPUTATIONAL MEDIA	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Course Learning Rationale (CLR):		The purpose of learning this course is to:		Learning		
CLR-1 :	Understand the fundamental concepts of analog and digital data		Level of Thinking (Bloom)	1	2	3
CLR-2 :	Know the basics of bitmap, DCT and color models			Expected Proficiency (%)		
CLR-3 :	Learn the various tools for digital image processing			Expected Attainment (%)		
CLR-4 :	Know the basics of digital audio representation					
CLR-5 :	Understand the concepts of video and its compression methods					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:				
CLO-1 :	Have a very good understanding of analog and digital data		2	80	85	
CLO-2 :	Have a clear understanding of bitmap, DCT and color models		2	75	80	
CLO-3 :	Possess the ability to handle various tools for digital image processing		2	85	80	
CLO-4 :	Apply the knowledge to represent digital audio		2	80	75	
CLO-5 :	Possess the ability to compress the video		2	75	85	

Program Learning Outcomes (PLO)														
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
-	-	H	-	-	-	-	-	-	-	-	-	-	M	-
-	-	H	-	-	-	-	-	-	-	-	-	-	M	-
-	-	H	-	H	-	-	-	H	-	-	-	-	M	-
-	H	H	-	H	-	-	-	H	-	-	-	-	-	-

Learning Resources	<ol style="list-style-type: none"> 1. Jennifer Burg, "The Science of Digital Media", Pearson Education, ISBN: 978-01324335802 2. Ze-Nian Li and Mark.s.Drew, "Fundamentals of Multimedia", Pearson Education International, ISBN 0-13-127256-X 	<ol style="list-style-type: none"> 3. Fred Halsall, "Multimedia Communications: Applications, Networks, Protocols and Standards", Pearson Education India, 2002, ISBN-10: 8131709949 and ISBN-13: 978-8131709948
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Valiyullasha, Bugtreat Technologies, UK, coe@bugtreat.com	C.M.T.Karthigeyan, Assistant Professor, Government College of Engineering, Bargur, email: c.m.t.karthikeyan@gcebargur.ac.in	P.Rajasekar, Assistant Professor, Department of Information Technology, Faculty of E&T,&SRMIST, email: rajasekp@srmist.edu.in

Course Code	18CSE345T	Course Name	IOT ARCHITECTURE AND PROTOCOLS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	CSE	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand Data and Knowledge Management and use of Devices in IoT Technology.	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Understand State of the Art – IoT Architecture.	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	To Understand the Architectural Overview of IoT																		
CLR-4 :	Understand the IoT Reference Architecture and RealWorld Design Constraints																		
CLR-5 :	To Understand the various IoT Protocols (Datalink, Network, Transport, Session, Service)																		
CLR-6 :	Understand and apply IoT protocols appropriately																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Interpret the vision of IoT architecture from a global context.	2	80	85	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-2 :	Implement state of the art architecture in IoT.	2	75	80	H	H	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-3 :	Compare and Contrast the use of Devices, Gateways and Data Management in IoT.	2	85	80	H	M	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-4 :	Implement using the available resources and demonstrate quick to deployment protocols wherever applicable	2	80	75	H	H	H	M	-	-	-	-	-	-	-	-	-	-	-
CLO-5 :	Apply the protocols and Techniques towards integration in relevant areas of IoT Product development	2	75	85	H	M	H	M	H	-	-	-	M	-	-	H	-	-	-
CLO-6 :	Choose appropriate protocols for various layers (Datalink, Network, Transport, Session, Service)	2	80	85	H	M	H	H	H	-	-	-	H	-	-	H	-	-	-

Duration (hour)	9	9	9	9	9
S-1	SLO-1 SLO-2	M2M and IoT- Relevance and Transition Building an architecture	Data Management- Introduction Managing M2M data: Data generation,	Introduction to RFID Introduction to NFC	Transport Layer Protocols -Introduction TCP
S-2	SLO-1 SLO-2	Main design principles and needed capabilities IoT architecture outline	Data acquisition, Data validation Data storage, Data processing	WSN(Large topic), Narrow band IoT (NbIoT)	MPTCP UDP
S-3	SLO-1 SLO-2	M2M and IoT Technology Fundamentals Devices and Gateways-Introduction	Data remanence, Data analysis Data management,	WiFi PLC Communication Protocols: A comparison	DCCP SCT
S-4	SLO-1 SLO-2	Basic Devices Gateways	Business processes in IoT Everything as a Service (XaaS)	Popular radio protocols and its security drawbacks 802.15.4 in depth	TLS DTLS
S-5	SLO-1 SLO-2	Advanced devices Need for networking	M2M and IoT Analytics Knowledge Management	Network Layer Protocols- Introduction IPv4	Session Layer-HTTP CoAP
S-6	SLO-1 SLO-2	State of the art-ETSI M2M IoT Reference model-IoT Domain model	Data Link Layer Protocols: PHY/MAC Layer:3GPP MTC IEEE 802.11	IPv6 6LoWPAN in depth	Implementation demo of CoAP MQTT
S-7	SLO-1 SLO-2	Information model Functional model	IEEE 802.15 Wireless HART	6TiSCH ND	Implementation demo of MQTT MQTT-SN

S-8	SLO-1	Communication model	Z-Wave	DHCP	Implementation demo of MQTT-SN	Security in IoT Protocols :MAC 802.15.4
	SLO-2	Safety, privacy, trust, security model	Bluetooth, Bluetooth Low Energy	ICMP	XMPP	Security in IoT Protocols :6LoWPAN,
S-9	SLO-1	Introduction to Protocols- Physical, Data Link	Zigbee, Zigbee Smart Energy	RPL	AMQP	Security in IoT Protocols :RPL
	SLO-2	Introduction to Protocols- Network, Transport, Application	DASH7	CORPL, CARP	Introduction to Contiki- Practical demo	Security in IoT Protocols: Application Layer

Learning Resources	<ol style="list-style-type: none"> 1. Uckelmann, D., Harrison, M., & Michahelles, F. (Eds.). Architecting the Internet of Things.doi:10.1007/978-3-642-19157-2 , 2011 2. IoT Fundamentals: Networking Technologies, Protocols, and Use Cases for the Internet of Things by Rob Barton, Gonzalo Salgueiro, David Hanes, Publisher: Cisco Press, Release Date: June 2017, ISBN: 9780134307091 (https://www.oreilly.com/library/view/iot-fundamentals-networking/9780134307091/) 3. Jan Holler, VlasiosTsiatsis, Catherine Mulligan, Stefan Avesand, StamatisKarnouskos, David Boyle, "From Machine-to-Machine to the Internet of Things: Introduction to a New Age of Intelligence", 1st Edition, Academic Press, 2014 	<ol style="list-style-type: none"> 5. Peter Waher, "Learning Internet of Things", PACKT publishing, BIRMINGHAM – MUMBAI 6. Daniel Minoli, "Building the Internet of Things with IPv6 and MIPv6: The Evolving World of M2M Communications", ISBN: 978-1-118-47347-4, Willy Publications

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. Vinay Solanki, Head IoT, Lenovo (APAC & MEA)	Dr.Zayaraj, Professor / CSE, PEC, Pondicherry	Dr. S.Babu, SRMIST
Dr. Pavanthan Arumugum, Director (R&D), ERNET India	Dr.Vijalakshmi Associate Professor / CSE, PEC, Pondicherry	Dr.Kayalvizhi Jayavel, SRMIST
Shiv Kumar Ganesh, Full Stack Developer, Altimetrik	Dr.P.Yogesh, Professor/IT, Anna University, Chennai.	Mr.V.Haribaabu, SRMIST

Course Code	18CSE346T	Course Name	NETWORK PROGRAMMING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18CSC302J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	To learn different socket function and implement client server applications using sockets	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	To conduct experiments to know how different internet protocols like TCP/IP works	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	To analyze various application program like TELNET, DNS, DHCP	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Build different application like Routing, Load balancing & Security	Expected Attainment (%)	Design & Development
CLR-5 :	To apply protocols get adapted to emerging technologies		Analysis, Design, Research
			Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Become familiar with elementary socket functions	3 80 70	L H - H L - - L L - H - - -
CLO-2 :	Design and implement client –server applications using Sockets	3 85 75	M H L M L - - M L - H - - -
CLO-3 :	Learn about functions that convert between names and numeric values and protocols	3 75 70	M H M H L - - M L - H - - -
CLO-4 :	Analyze network programs	3 85 80	M H M H L - - M L - H - - -
CLO-5 :	Build network applications	3 85 75	H H M H L - - M L - H - - -

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Introduction	Socket function	Get sock opt function	DNS
	SLO-2	simple daytime client	connect function	set sock opt function	resolvers and name servers
S-2	SLO-1	protocol independence	bind function	IPV4	gethostbyname function
	SLO-2	Error handling	listen function	ICMP	gethostbyaddr function
S-3	SLO-1	simple daytime server	accept function	TCP socket options	getservbyname
	SLO-2	Roadmap to client/server.	Fork function		getservbyport function
S 4-5	SLO-1	Overview of TCP/IP protocol- TCP connection establishment and termination	exec function	UDP Echo server and client	tcp_connect function-
	SLO-2				Daemon processes
S-6	SLO-1	TCP state transition diagram – Time-wait state	concurrent servers	recvfrom function	tcp_listen function
	SLO-2	SCTP association establishment and termination	close function-getsockname and getpeername	send to function	udp_client
S-7	SLO-1	TCP port numbers and concurrent servers	TCP Echo server, TCP Echo client	Connect function with UDP	udp_connect
	SLO-2	Buffer size and limitations	normal startup and termination		udp_server function

S 8-9	SLO-1	standard internet services	POSIX signal handling, Wait and Waitpid functions	dg_cli function	BOOTP	Advanced I/O functions
	SLO-2	protocol usage by common, Internet applications	Termination of server process, Crashing and rebooting of server host	lack of flow control with UDP	DHCP	

Learning Resources	<ol style="list-style-type: none"> 1. W.Richard Stevens, Bill Fenner, Andrew M. Rudoff " Unix Network programming " 3rd edition, Volume – 1, Pearson Education , 2015 R.F.Gilberg, B.A.Forouzan, Data Structures, 2nd ed., Thomson India, 2005 2. Douglas.E.Comer " Internetworking with TCP/IP " principles, protocols and architecture, 6th Edition , Volume 1, Pearson Education,2013 	<ol style="list-style-type: none"> 3. Behrouz A.Forouzan , " TCP/IP protocol suite", 4th edition, Mc Graw Hill education private limited,2010 4. Wendell Odom , " IP networking ", 1st edition, Pearson Education 2012
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Dr.Viswanadham, Teken BIM Technologies Pvt. Ltd, 9962514477, Viswanathan_alladi@yahoo.com	Dr. Latha, Prof & Head, CSE dept, SAIRAM engg college,latha.cse@sairam.edu.in, 8754502224	1. MrsT.Manoranjitham, SRMIST
		2. Mr. Godwin , SRMIST
		3. Ms. Vinoth, SRMIST

[illegible]

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	
Course Offering Department	Computer Science and Engineering		Data Book / Codes/Standards	Nil	

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																					
CLR-1:	Understand the fundamentals, various attacks and importance of Security aspects in IoT				Level of Thinking (Bloom)	1	2	3	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15				
CLR-2:	Understand the techniques, protocols and some idea on security towards Gaming models																												
CLR-3:	Understand the relevance of Blockchain, its techniques towards IoT																												
CLR-4:	Understand the operations of Bitcoin blockchain, crypto-currency as application of blockchain technology																												
CLR-5:	Understand the essential components of IoT																												
CLR-6:	Understand security and privacy challenges of IoT																												
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																											
CLO-1:	Incorporate the best practices learnt to identify the attacks and mitigate the same				3		80	70			L	H	M	H	M	-	-	-	M	L	-	H	-	-	-				
CLO-2:	Adopt the right security techniques and protocols during the design of IoT products				3		85	75			L	H	M	H	M	-	-	-	M	L	-	H	-	-	-				
CLO-3:	Apply the skills learnt towards gaming designs				3		75	70			L	H	M	H	M	-	-	-	M	L	-	H	-	-	-				
CLO-4:	Assimilate and apply the skills learnt on cipers and blockchains when appropriate				3		85	80			L	H	M	H	M	-	-	-	M	L	-	H	-	-	-				
CLO-5:	Describe the essential components of IoT				3		85	75			L	H	M	H	M	-	-	-	M	L	-	H	-	-	-				
CLO-6:	Find appropriate security / privacy solutions for IoT				3		80	70			L	H	M	H	M	-	-	-	M	L	-	H	-	-	-				

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Fundamentals of IoT and Security and its need	Prevent Unauthorized Access to Sensor Data	Block ciphers	Introduction to Blockchain	Introduction of IoT devices
	SLO-2	IoT Security Requirements	,M2M Security,	Message integrity	Modeling faults and adversaries	Difference among IoT devices, computers, and embedded devices.
S-2	SLO-1	IoT and cyber-physical systems	RFIDSecurity,	Authenticated encryption	Byzantine Generals problem	sensors and actuators in IoT
	SLO-2	IoT security (vulnerabilities, attacks, and countermeasures),	Cyber Physical Object Security, ,	Hash functions	Consensus algorithms and their scalability problems	Accelerometer, photoresistor, buttons
S-3	SLO-1	Security engineering for IoT development	Hardware Security,	Merkle trees and Elliptic curves	digital signatures, verifiable random functions, Zero-knowledge systems	motor, LED, vibrator,
	SLO-2	IoT security lifecycle	Front-end System Privacy Protection, Management,Secure IoT Databases	Public-key crypto (PKI),	blockchain, the challenges, and solutions,	analog signal vs. digital signal
S-4	SLO-1	Data Privacy	Networking Function Security	Trees signature algorithms	proof of work, Proof of stake,	Networking in IoT
	SLO-2	Device/User Authentication in IoT	IoT Networking Protocols,	Crypto-currencies,	alternatives to Bitcoin consensus, Bitcoin scripting language and their use	Real-time communication
S-5	SLO-1	Introduction to Authentication Techniques	SecureIoT Lower Layers,	Bitcoin P2P network,	Ethereum and Smart Contracts,	Bandwidth efficiency
	SLO-2	Data Trustworthiness in IoT	SecureIoT Higher Layers,	Distributed consensus, , ,	Smart Contract Languages and verification challenges	data analytics in IoT - simple data analyzing methods
S-6	SLO-1	Human IoT Trust Relationship	Secure Communication	Incentives and proof-of-work	comparing Bitcoin scripting vs. Ethereum Smart Contracts	IoT architecture, component and technology
	SLO-2	Trust and Reputation Systems	Links in IoTs,Back-end Security -Secure Resource	Mining, scripts and smart contracts	Hyperledger fabric	Case study: discussion on specific IoT applications and their design considerations
S-7	SLO-1	Trust Negotiation	Game Theory Foundation	Wallets: hot and cold storage ,anonymity, altcoins	Mechanisms in permissioned blockchain	cybersecurity overview in IoT

	SLO-2	IoT Privacy Preservation Issues	Mixed-strategy, ,	Credential management for connected devices: Security credential management system (SCMS),	Pseudo-anonymity vs. anonymity	General cybersecurity concepts in IoT
S-8	SLO-1	Attack Models - Attacks to Sensors in IoTs,	Nash equilibrium	VehicleBased Security System (VBSS),	Zcash and ZK-SNARKS for anonymity preservation	security threats in IoT
	SLO-2	Attacks to RFIDs in IoTs,	Repeated games	PKI design, Certification provisioning	Attacks on Blockchains	data privacy in IoT
S-9	SLO-1	Attacks to Network Functions in IoTs,	Bayesian games	Pseudonyms (privacy-by design),	Sybil attacks, selfish mining	device/User authentication in IoT
	SLO-2	Attacks to Back-end Systems and security in Front end Systems	Coalitional games.	Misbehavior detection and Revocation,	51% attacks	data trustworthiness problem in IoT

Learning Resources	<ol style="list-style-type: none"> 1. B.Rusell and D. Van Duren, "Practical Internet of Things Security," Packt Publishing, 2016. 2. Fei HU, "Security and Privacy in Internet of Things (IoT): Models, Algorithms, and Implementations," CRC Press, 2016 3. Narayanan et al., "Bitcoin and Cryptocurrency Technologies: A Comprehensive Introduction," Princeton University Press, 2016. 4. A. Antonopoulos, "Mastering Bitcoin: Unlocking Digital Cryptocurrencies," O'Reilly, 2014 	<ol style="list-style-type: none"> 5. T. Alpcan and T. Basar, "Network Security: A Decision and Game-theoretic Approach," Cambridge University Press, 2011. 6. Security and the IoT ecosystem, KPMG International, 2015 7. Internet of Things: IoT Governance, Privacy and Security Issues by European Research Cluster 8. Ollie Whitehouse, "Security of Things: An Implementers' Guide to Cyber-Security for Internet of Things Devices and Beyond", NCC Group, 2014 9. Josh Thompson, 'Blockchain: The Blockchain for Beginners, Guide to Blockchain Technology and Blockchain Programming', CreateSpace Independent Publishing Platform, 2017.

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
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		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
	Dr.A.Amuthan, Associate Dean, Dept. of CSE, Pondicherry Engg. College, Pondicherry	Dr.M.Murali Dr.Kayalvizhi Jayavel Mr. H.Karthikeyan

Course Code	18CSE446T	Course Name	ADVANCED DATABASE SYSTEMS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1:	Familiarize with the various query processing, join and optimization techniques	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2:	Improve their ability to choose the appropriate techniques for any parallel and distributed database systems	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3:	Familiarize with the various object based databases techniques	Expected Proficiency (%)	Problem Analysis
CLR-4:	Familiarize with the various Motivation, Structure, Storage, Application and Evaluation of XML Queries	Expected Attainment (%)	Design & Development
CLR-5:	Expose to the concepts of Performance Tuning, Temporal, Spatial, Multimedia and Mobile data bases		Analysis, Design, Research
CLR-6:	Expose to the latest Spatial and Geographic data, R Trees and Multimedia databases		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1:	Acquire the knowledge on query processing, join and optimization on a database	2 80 85	H H L M L - - - M M M - - - -
CLO-2:	Acquire the ability to identify & design a parallel and distributed database	2 75 80	H H L M L - - - M M M - - - -
CLO-3:	Understand the basic ideas about various object based databases	2 85 80	H M L M L - - - M M M - - - -
CLO-4:	Apply the knowledge of XML on various applications	2 80 75	H H L M L - - - M M M - - - -
CLO-5:	Appreciate the concepts of Performance Tuning, Temporal, Spatial, Multimedia and Mobile data bases	2 75 85	H M L M L - - - M M M - - - -
CLO-6:	Appreciate the concepts of latest Spatial and Geographic data, R Trees and Multimedia databases	2 80 85	H M - M L - - - M M M - - - -

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Overview of query processing	Introduction to Parallel Databases	Overview of object based databases	Introduction to XML	Performance Tuning
	SLO-2 Measures of query cost	I/O parallelism	Complex data types		Improving set orientation
S-2	SLO-1 Selection Operation	Interquery Parallelism	Structured types in SQL	Motivation	Tuning of bulk loads and updates
	SLO-2 Sorting	Intraquery Parallelism	Inheritance in SQL		Location of bottlenecks
S-3	SLO-1 Join Operation-Nested loop join	Intraoperation Parallelism	Table inheritance	Structure of XML data	Tunable parameters
	SLO-2 Merge join and Hash join	Interoperation Parallelism			Tuning of hardware
S-4	SLO-1 Projection, set operation, Outer join and Aggregation	Query Optimization	Array and multiset Types in SQL	XML document scheme	Tuning of the schema and Indices
	SLO-2 Evaluation of Expressions	Design of Parallel Systems			Tuning of Physical design
S-5	SLO-1 Overview of query optimization	Homogeneous and heterogeneous database	Object –identity and reference Types in SQL	Querying and transformation	Tuning of concurrent transactions
	SLO-2 Transformation of relational expressions -Equivalence Rules	Distributed data Storage			Introduction to Temporal, Spatial, Multimedia and Mobile data bases
S-6	SLO-1 Join Ordering	Distributed transactions	Implementing O-R features	Application program interface to XML	Performance benchmarks
	SLO-2 Enumeration of Equivalent Expression	Commit protocols			Time in databases
S-7	SLO-1 Estimating statistics of expression results Catalog Information	Concurrency control in distributed databases	Persistent programming languages – Persistence of objects	Storage of XML data	Spatial and Geographic data
	SLO-2 Selection Size and Join size Estimation	Distributed query processing	Object identity and pointers		Representation of Geographic data
S-8	SLO-1 Size Estimation for other Operation, Estimation of Number of Distinct Values	Availability	Persistent C++ systems	XML applications.	Spatial Queries

	SLO-2	Choice of evaluation plans-Cost based join order Selection		Persistent Java systems		Indexing of Spatial Data
S-9	SLO-1	Cost based optimization with equivalence rules	Heterogeneous distributed databases.	Object-relational mapping	Evaluation of XML Queries	R Trees
	SLO-2	Heuristics in optimization, Optimizing Nested Sub queries		Object-oriented versus object-relational.		Multimedia databases

Learning Resources	1. Abraham Silberschatz, Henry F Korth, S Sudarshan, "Database System Concepts", McGraw Hill Education –2013 2. RaghuRamakrisnan, "Database Management Systems", -McGrawHill Education- 2014	3. Elmasri Navathe, Somayajulu, Gupta, "Fundamentals of Database Systems, Pearson Education, 4 th Edition, 2006 4. CJDate, AKannan, SSwamynathan, "An Introduction to Database Systems", Pearson Education, 8 th Edition, 2006
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#		Theory	Practice
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice		
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Understand										
	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Analyze										
	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. Mariappan Vaithilingam, Engineering Leader Amazon, dr.v.m@ieee.org		1. Mr. Elizer, SRMIST
2. Mr. Badinath, SDET, Amzon, sbadhrinath@gmail.com		2. Mrs. Sasi Rekha Sankar, SRMIST
		3. Ms. Hemavathy, SRMIST

Course Code	18CSE447T	Course Name	EDGE COMPUTING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering	Data Book / Codes/Standards			Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Understand the concepts of IoT				level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Understand the IoT and M2M Communication																							
CLR-3 :	Understand the protocols and standards of IoT																							
CLR-4 :	Understand the Fog computing Architecture and its components																							
CLR-5 :	Understand the integration of Fog and Cloud Computing																							
CLR-6 :	Understand the concepts of IoT																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1 :	Apply concepts of IoT				3	80	70	H	L	H	M	H	H	H	H	H	H	H	M	H	H	H	H	H
CLO-2 :	Apply the M2M protocol in IoT.				3	85	75	H	L	H	M	H	H	H	H	H	H	H	M	H	H	H	H	H
CLO-3 :	Equip themselves familiar with Fog computing in IoT				3	75	70	H	L	H	M	H	H	H	H	H	H	H	M	H	H	H	H	H
CLO-4 :	Familiarize with IoT standard and protocols				3	85	80	H	L	H	M	H	H	H	H	H	H	H	M	H	H	H	H	H
CLO-5 :	Acquaint with Fog and Cloud computing in IoT				3	85	75	H	L	H	M	H	H	H	H	H	H	H	M	H	H	H	H	H
CLO-6 :	Apply concepts of IoT				3	80	70	H	L	H	M	H	H	H	H	H	H	H	M	H	H	H	H	H

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Introduction to IoT	IoT Architecture	Fog Computational Model	BIG DATA
	SLO-2	Technologies in IoT	Data Acquisition, Data Aggregation and Data Analysis	Fog Simulators	Data Types in Big data
S-2	SLO-1	IoT Applications- Smart Home, Wearable, Connected Cars, Industrial IoT	IoT Protocols- COAP, MQTT	iFogSim	Characteristics of BIG DATA
	SLO-2	Smart Cities, Agriculture, Smart Retail, smart Grid, Healthcare	XMPP, AMQP, Low power Lossy Network routing	FogTorch	Benefits of Big Data
S-3	SLO-1	Challenges in IoT- Delivering Value to Customers, Hardware Compatibility Issues, Data Connectivity Issues	Communication Methods- Bluetooth, Zigbee Z-wave, 6LowPAN	Cisco IoT and Fog Application	Big Data Application-
	SLO-2	Incorrect Data Capture Capabilities, Analytic Challenges, Data Security challenges,	Wireless Fidelity	Contiki/Cooja	Layered Big Data Architecture- Data Ingestion, Data collection, Data Processing Layer
S 4-5	SLO-1	Introduction to Edge Computing	4G	NS3	Data storage, Data Query and Visualization Layer
	SLO-2				
S-6,7	SLO-1	Need for Edge Computing- Improved Performance, Compliance, Data Privacy, And Data Security	Sigfox, NeUL	Software Defined Multi-Tier Fog Architecture	Big Data Implementation- Hortonworks, Cloudera, MAP R
	SLO-2	Reduced Operational Cost	LoRaWAN	PVFOg simulator	Apache Projects for Big Data
S-8,9	SLO-1	Challenges in Edge/Fog Computing	5G	System Model analysis	Edge Computing for Big Data

Learning Resources	<ol style="list-style-type: none"> 1. Ashton Kevin, (2009), "That Internet of Things Thing," <i>RFID Journal</i>, pp. 4986. 2. Maria Rita Palattella et al., (2013), "Standardized protocol stack for the internet of (important) things," <i>IEEE Communications Surveys and Tutorials</i>, 15(3), pp. 1389–1406. 3. D. Airehrour, J. Gutierrez and S. K. Ray, (2016), "Secure routing for internet of things: A survey," <i>Journal of Network and Computer Applications</i>, 66, pp. 198–213. 4. Reem Abdul Rahman and Babar Shah, (2016), "Security analysis of IoT protocols: A focus in CoAP," 2016 3rd MEC International Conference on Big Data and Smart City, ICBDS 2016, pp. 172–178. 5. Flavio Bonomi, Rodolfo Milito, Jiang Zhu and Sateesh Addepalli, (2012), "Fog Computing and Its Role in the Internet of Things," <i>Proceedings of the first edition of the MCC workshop on Mobile cloud computing</i>, pp. 13–16. 6. Weisong Shi, Jie Cao, Quan Zhang, Youhuizi Li and Lanyu Xu, (2016), "Edge Computing: Vision and Challenges," <i>IEEE Internet of Things Journal</i>, 3(5), pp. 637–646. 7. M. Mukherjee et al., (2017), "Security and Privacy in Fog Computing: Challenges," <i>IEEE Access</i>, 5, pp. 19293–19304. 8. Jie Cao, Quan Zhang and Weisong Shi, (2018), "Challenges and opportunities in edge computing," <i>SpringerBriefs in Computer Science</i>, pp. 59–70. 9. Martina Marjanovic, Aleksandar Antonic and Ivana Podnar Zarko, (2018), "Edge computing architecture for mobile crowd sensing," <i>IEEE Access</i>, 6, pp. 10662–10674. 10. Hesham El-Sayed et al., (2017), "Edge of Things: The Big Picture on the Integration of Edge, IoT and the Cloud in a Distributed Computing Environment," <i>IEEE Access</i>, 6, pp. 1706–1717 11. Huaqing Zhang, Yong Xiao, Shengrong Bu, Dusit Niyato, F. Richard Yu and Zhu Han, (2017), "Computing Resource Allocation in Three-Tier IoT Fog Networks: A Joint Optimization Approach Combining Stackelberg Game and Matching," <i>IEEE Internet of Things Journal</i>, 4(5), pp. 1204–1215 12. Veeramanikandan M. and Suresh Sankaranarayanan, (2019), "Publish/subscribe based multi-tier edge computational model in Internet of Things for latency reduction," <i>Journal of Parallel and Distributed Computing</i>, 127, pp. 18–27. 13. Ashfaq Farooqui, Kristofer Bengtsson, Petter Falkman and Martin Fabian, (2019), "From factory floor to process models: A data gathering approach to generate, transform, and visualize manufacturing processes," <i>CIRP Journal of Manufacturing Science and Technology</i>, 24, pp. 6–16. 14. Hongbing Wang, Chao Yu, Lei Wang and Qi Yu, (2018), "Effective BigDataspace service selection over trust and heterogeneous QoS preferences," <i>IEEE Transactions on Services Computing</i>, 11(4), pp. 644–657. 15. Pekka Pääkkönen and Daniel Pakkala, (2015), "Reference Architecture and Classification of Technologies, Products and Services for Big Data Systems," <i>Big Data Research</i>, 2(4), pp. 166–186 16. Tom White, (2015), "Hadoop: The Definitive Guide, 4th Edition," O'Reilly Media, Inc., (2015). 17. Team Hortonworks, "Hortonworks," [Online]. Available: https://hortonworks.com/. 18. Cloudera, "Cloudera," [Online]. Available: https://www.cloudera.com/about.html. 19. The Apache Software Foundation, "Apache Ni-Fi," [Online]. Available: https://nifi.apache.org/. 20. The Apache Software Foundation, "Apache Kafka," [Online]. Available: https://kafka.apache.org/. 21. The Apache Software Foundation, "Kafka Use cases," [Online]. Available: https://kafka.apache.org/uses. 22. The Apache Software Foundation, "Apache Storm," [Online]. Available: https://storm.apache.org/. 23. The Apache Software Foundation, "Apache Hive," Apache, [Online]. Available: https://hive.apache.org/. 24. The Apache Software Foundation, "Apache Pig," [Online]. Available: https://pig.apache.org/. 25. Alan Gates and Daniel Dai, (2016), "Programming Pig: Dataflow Scripting with Hadoop," Shroff/O'Reilly. 26. The Apache Software Foundation, "Zookeeper," [Online]. Available: https://zookeeper.apache.org/. 27. Shangguang Wang, Yali Zhao, Jinlinag Xu, Jie Yuan and Ching Hsien Hsu, (2019), "Edge server placement in mobile edge computing," <i>Journal of Parallel and Distributed Computing</i>, 127, pp. 160–168. 28. Yuthika, S, Ekta Dagur, Sourabh Mishra, Rijo Jackson Tom, Veeramanikandan, M and Suresh, S, "Intelligent IoT Based Automated Irrigation System", <i>International Journal of Applied Engineering and Research</i>, Vol.12(18), pp.7306-7320, 2017 29. Soundarya, P, Parthyusha, V, Niharika, A. V, Karthick, T and Suresh, S, "Intelligent IoT Based Water Quality Monitoring System", <i>International Journal of Applied Engineering and Research</i>, Vol.12(16), pp.5447-5454, 2017 30. Manav, M, Sameer, S, Suresh, S, Tom, R J and Veeramanikandan, M, "IoT Based Hydroponics System using Deep Neural Networks", <i>Journal of Computers and Electronics in Agriculture</i>, Vol.155, pp.473-486, 2018, Elsevier Publishing 31. Vignesh, M , Lavanya, V, Abhilasha, K, Gunasekhar, A and Suresh, S, "IoT Based Smart Energy Management System", <i>International Journal of Applied Engineering and Research</i>, Vol.12(16), pp.5455-5462, 2017
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Dr.Madan Lakshmanan	Dr.Subra Ganesan	Dr.S.Suresh
Senior Scientist	Professor, Department of Electrical and Computer Engineering	Dr.J. Sujithra
CEERI, CSIR, Chennai (R&D Industry)	Oakland University, USA	

Course Code	18CSE448T	Course Name	ENERGY MANAGEMENT FOR IoT DEVICES	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering	Data Book / Codes/Standards			Nil

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Understand the rudiments of energy conservation and IoT	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Gain the knowledge on various energy conservation schemes in IoT		
CLR-3 :	Utilize the conventional and optimization algorithms for conserving energy in IoT devices		
CLR-4 :	Understand the various techniques of green IoT and impact of conventional techniques of IoT		
CLR-5 :	Gain the knowledge on existing energy efficient architecture for energy conservation and harvesting		
CLR-6 :	Gain the knowledge on low energy Bluetooth devices and its importance		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom) Expected Proficiency (%) Expected Attainment (%)	Engineering Knowledge Problem Analysis Design & Development Analysis, Design, Research Modern Tool Usage Society & Culture Environment & Sustainability Ethics Individual & Team Work Communication Project Mgt. & Finance Life Long Learning PSO - 1 PSO - 2 PSO - 3
CLO-1 :	Acquire the knowledge on IoT and energy conservation approaches in IoT	2 80 85	H M M M - - - - - - - - - - - -
CLO-2 :	Identify and choose appropriate energy conservation component for real world problems	2 75 80	H M M - - - - - - - - - - - -
CLO-3 :	Design and develop energy conservation algorithms for improving the lifetime of IoT devices	2 85 80	H H H H - - - - - - - - - - - -
CLO-4 :	Compare and contrast of various green IoT techniques and able to design green IoT for real world problems	2 80 75	H M H H - - - - - - - - - - - -
CLO-5 :	Design and develop energy efficient architecture for real world problems	2 75 85	H H H H - - - - - - - - - - - -
CLO-6 :	Design and develop energy efficient architecture for real world problems using low energy Bluetooth devices	2 80 85	H M M M - - - - - - - - - - - -

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Introduction to IoT	Energy conservation schemes	Static energy efficient algorithms	Green IoT an Overview	Designing energy efficient IoT based Intelligent Transport System
	SLO-2 Architecture of IoT	Sleep/wakeup scheme	Exact allocation algorithm	Smart Homes, Smart Cities	Intelligent Transport System
S-2	SLO-1 Components of IoT	Data driven scheme	Best Fit Heuristic Algorithm	Energy Efficient smart health care	Motivations for IoT in Transportation
	SLO-2 Applications of IoT	Mobility based scheme	Dynamic energy efficient algorithms	Importance of Green IOT	Communication Technology and Related Power Issues
S-3	SLO-1 Challenges in IOT	Load balancing	Hardware Level Solution	Taxonomy of green IoT techniques	Information Extraction and Underlying Power Issues
	SLO-2 Energy Management in IoT	Working of load balancing	Dynamic Voltage Frequency Scaling (DVFS)	Various Approaches to Achieve Green IoT	Energy Efficiency Challenges and Corresponding Solutions, Further Challenges and Opportunities
S-4	SLO-1 Energy harvesting	Hardware based load balancing	Software Level Solution	software based green IoT techniques	Capacity Estimation of Electric Vehicle Aggregator for Ancillary Services
	SLO-2 Block diagram of energy harvesting	Software Based Load Balancing	First Fit Decreasing algorithm (FFD)	Hardware based green IoT techniques	Development of Electric Vehicles
S-5	SLO-1 Various ambient energies	Compare hardware and software based load balancing techniques	Modified Best Fit Decreasing algorithm (MBFD)	Policy based techniques	Motivation for Vehicle to Everything (V2X) and V2G Technology
	SLO-2 Energy harvesting schemes	Load balancing algorithms	Genetic Algorithm (GA)	Awareness based Approach - Toward Green IoT, Energy Awareness	Electric Vehicles and Solar Power Plants in Smart Grid Environment
S-6	SLO-1 Harvesting modules		Particle Swarm Optimization (PSO)	IoT Based Smart Metering	Potential of EV to Grid Connection, Capacity Estimation of Aggregator
	SLO-2 Rectenna Model	Static Algorithms, Dynamic Algorithms	Ant Colony Optimization (ACO)	Communication Technology Creating Awareness About Green Information, Promoting Recycling	Battery Management System, Grid Connection and Performance Testing of V2G

S-7	SLO-1	Sensing antenna	Issues of energy conservation in IoT	Simulated Annealing (SA)	Habitual Based Techniques	Weather monitoring using Bluetooth Low Energy (BLE) in warehouses
	SLO-2	DC-DC Converter		Cat Swarm Optimization(CSO)	Comparative analysis of different green IoT approaches	BLE Introduction
S-8	SLO-1	Wireless energy harvesting	Basic model of smart home system	Hybrid Genetic Algorithm and Cat Swarm Optimization (HGACSO)	Case study: impact of smart phones on the environment in present and future trends	BLE importance
	SLO-2	Near Field Communication, Inductive coupling	Energy Conservation in Smart Home and IoT	Hybrid Genetic Algorithm, Particle Swarm Optimization and Simulated annealing(HGAPSOA)	Reduce the environmental impact life cycle assesment of smatphones, smart phone emission and selling rate	
S-9	SLO-1	Paradigmatic view of energy efficient IoT	Automation and Sensors in Smart Home	Comparison of dynamic energy efficient algorithms	Promoting the Usage of Sensor Cloud: a step toward green IoT.	Design weather monitoring using BLE
	SLO-2	Pragmatic energy efficient IoT system architecture	Case study: energy conservation component for smart home.	Compare and contrast static and dynamic energy efficient algorithms	Creating Awareness Through Prototyping: A Green IoT-Based Smart	

Learning Resources	<ol style="list-style-type: none"> 1. "EnergyConservationforIoTDevicesConcepts,ParadigmsandSolutions",MamtaMittal,Sudeep Tanwar,BasantAgarwal,LalitMohanGoyal,StudiesinSystems,DecisionandControl 206,2019. 2. "IoTprojectswithBluetoothLowEnergy-Harnessthepowerofconnectedthings",Madhur 	<ol style="list-style-type: none"> 3. 1Green IoT: An Investigation on Energy Saving Practices for 2020 and Beyond, Rushan Arshad, Saman Zahoor, Munam Ali Shah , Abdul Wahid, and Hongnian Yu, special section on future networks: architectures,protocols,andapplications,2017.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1.Mr.Anantha Velavan , Principal Validation Engineer, Micro chip	Dr. Divya Udayan J, PhD(S.Korea) MIEEE MACM MIDF, Associate Professor, VIT University, Vellore	Dr.T.Sujithra,SRMIST
2.Mr.GaneshSKandha, Senior Applications Engineer, Micro chip	Dr.Masoodhu Banu, Professor/Head of Bio Medical, Veltech University,	Dr.Kayalvizhi Jayavel, SRMIST
		Mrs.Anitha,SRMIST

Course Code	18CSE367T	Course Name	REQUIREMENTS ENGINEERING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Identify the sources, collect, organize and classify the requirements	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Improve their ability to choose the appropriate Elicitation Techniques for any systems		
CLR-3 :	Familiarize with the various requirements documentation and validation techniques		
CLR-4 :	Familiarize with the various requirements quality drivers, Traceability models and requirements change control techniques		
CLR-5 :	Expose to the Conflicts, Escalation model , Settlements and Analytics of Cost Benefit analysis		
CLR-6 :	Expose to the latest requirements engineering tools		

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Acquire the knowledge on identifying the Source, organising and classifying requirements	2	80	85	H	H	L	M	-	L	L	M	H	H	M	L	-	-	-
CLO-2 :	Acquire the ability to identify and Apply the appropriate Elicitation Techniques for any systems	2	75	80	H	H	H	L	-	L	-	L	H	H	H	L	-	-	-
CLO-3 :	Understand the basic ideas about various requirements documentation and validation techniques	2	85	80	H	L	L	L	M	-	-	M	M	M	M	-	-	-	-
CLO-4 :	Apply the knowledge on various requirements quality drivers, Traceability models and requirements change control techniques for any system	2	80	75	H	H	L	M	H	M	-	M	M	L	L	M	-	-	-
CLO-5 :	Appreciate the concepts of Conflict, Escalation model , Settlements and Analytics of Cost Benefit analysis	2	75	85	H	H	-	H	H	-	-	M	L	M	M	-	-	-	-
CLO-6 :	Appreciate the concepts of latest requirements engineering tools	2	70	70	H	L	L	M	H	-	L	L	L	L	M	M	-	-	-

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Introduction to Requirements and Requirements Engineering	Requirement Inception	Introduction to Requirement Document, Structure of Document	Business drivers of Quality-components of Integrated Quality approach
	SLO-2	Requirements Types	sources of requirements		
S-2	SLO-1	Classification of Requirements	Introduction to requirement Elicitation	Vision, Scope and Elicitation notes	Quality improvement techniques, Requirements Quality Assurance
	SLO-2	Requirements Gathering relevant to Software Life Cycle Models			
S-3	SLO-1	Stakeholders in the requirements process	Classical Elicitation Techniques-Interview, Questionnaire, Social analysis	Requirement Specification techniques	PDCA Cycle
	SLO-2				
S-4	SLO-1	Requirements Engineering Process Framework, Requirements Engineering Maturity Model	Modern Elicitation Techniques-Brainstorming,	Introduction to requirement validation-Classical Requirement Validation techniques-Inspection, Simple Check	Introduction to Requirement Management-Requirement Identification-Requirements traceability
	SLO-2	Generic Process for requirements Engineering			
S-5	SLO-1	Levels of Requirements Engineering	Modern Elicitation Techniques-Prototyping, Use Centered Design,	. Introduction to requirement validation-Classical Requirement Validation techniques-Desk Check, Walkthrough	Requirement Traceability models, Traceability Matrix- Traceability List & Tree

	SLO-2	System Model for Requirements Engineering				
S-6	SLO-1	Representation of Requirements-Data Flow, ER Diagram	Modern Elicitation Techniques- Walkthrough, Use case Joint Application Development	Format review	Introduction to Requirement Traceability- Requirement traceability methods	Analytic Methods – Mastering and using Consider All Facts (CAF)
	SLO-2	View Point Controlled Requirements				
S-7	SLO-1	Structured Analysis and Design Technique, Viewpoint Oriented Requirements Definition	Requirement reuse	Prototype & Enactments, Functional test Design		Analytic Methods – Plus –Minus- Intresting(PMI)
	SLO-2					
S-8	SLO-1	Object Oriented Methods of Requirements Engineering	Feature Oriented Domain Analysis	Development of User manual	Advance Traceability	Analytic Methods – Cost Benefit Analysis
	SLO-2					
S-9	SLO-1	Case Study : For the given application identify the stakeholders, gather and classify the requirements according to the types	Case Study: For the given application apply various techniques and Elicitation the requirements	Case study. For the given application validate and document the specifications	Requirement Change Control	Case study : Requirement Engineering Tools
	SLO-2					

Learning Resources	<ol style="list-style-type: none"> 1. Elizabeth Hull, Ken Jackson, Jeremy Dick, Requirements Engineering, Springer, 2013 2. Ralph R. Young, "The Requirements Engineering Handbook", 2004 	<ol style="list-style-type: none"> 3. Axel van Lamsweerde, "Requirements Engineering: From System Goals to UML Model to Software Specifications", Wiley, 2014 4. Karl Wiegers, Joy Beatty, Software Requirements (Developer Best Practices), (3rd Edition), Microsoft Press, 2014.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. Mariappan Vaithilingam, Engineering Leader Amazon, dr.v.m@ieee.org		1. Mrs. Sasi Rekha Sankar, SRMIST
2. Mr. Badinath, SDET, Amzon, sbadhrinath@gmail.com		2. Mrs. Geetha.G, SRMIST
		3 Dr. S. Thenmalar, SRMIST

Course Code	18CSE368T	Course Name	SOFTWARE ARCHITECTURE AND DESIGN	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering		Data Book / Codes/Standards	Nil	

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Classify the essential elements of software architecture	1	2	3	Thinking (Bloom)	Efficiency (%)	Retention (%)	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2 :	Understand the issues related to architecting a large-scale software system																							
CLR-3 :	Understand different software architectures views and styles																							
CLR-4 :	Able to use the four-views approach for developing and documenting a software architectures																							
CLR-5 :	Understand the implications of different design patterns																							
CLR-6 :	working as part of a team, develop, analyze and critique an architecture of a software system																							

Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			Level of T	Expected	Expected	Engineering	Problem	Design &	Analysis,	Modern T	Society &	Environm	Ethics	Individual	Communit	Project M	Life Long	PSO - 1	PSO - 2	PSO - 3
CLO-1:	Describe different approaches to design software application	3	80	75	H	H	-	L	-	-	-	-	-	-	-	L	-	H	-	-	-	-
CLO-2:	Analyze specifications and identify appropriate design strategies.	3	85	80	M	H	H	H	-	-	-	-	-	-	M	M	M	H	-	-	-	-
CLO-3:	Develop an appropriate design for a given set of requirements	3	75	75	M	H	H	H	-	-	-	-	-	-	-	M	M	H	-	-	-	-
CLO-4:	Identify applicable design patterns for the solution	3	85	80	H	H	H	H	-	-	-	-	-	-	-	L	L	H	-	-	-	-
CLO-5:	Abstract and document reusable design patterns	3	80	70	M	H	H	-	L	-	-	-	-	-	M	M	M	H	-	-	-	-
CLO-6:	Evaluate a given design against the specifications	3	80	70	M	H	-	-	-	-	-	-	-	-	M	M	M	H	-	-	-	-

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Software Architecture –Software Design	Software Architectural Patterns & Styles	Evaluating a Software Architecture	Introduction to Design Process	Introduction to Design Pattern
	SLO-2	Importance and Need of Software Architecture	Types of Architectural Styles	Why- When -Who evaluate Architecture	Design Strategy	Component of Design Pattern - Types
S-2	SLO-1	4 +1 View Model	Layered pattern	What Qualities Can We Evaluate an Architecture?	Describing the design process the D-Matrix	Creational Design Patten - Abstract Factory Pattern
	SLO-2	Activities in Software Architecture	Merits and Demerits of Layered Pattern		Views associated with D-matrix	Factory Method
S-3	SLO-1	Fundamental design issues	Pipe-Filter pattern	Outputs of an Architecture Evaluation	Design by top-down decomposition	Singleton Pattern
	SLO-2		Merits and Demerits of Pipe and Filter			Structural design Pattern - Types
S-4	SLO-1	Understanding quality attributes -	Shared Data Pattern	Evaluating the Architecture - ATAM	Design by composition	Adaptor pattern
	SLO-2	Six parts of Quality Scenario	Merits and Demerits of Shared Data Pattern	Participants and Outputs of ATAM		Decorator Pattern
S-5	SLO-1	Design for quality attributes - Availability (General Scenario, Tactics)	Client Server pattern	Phases of ATAM	Function-oriented design	Proxy Pattern
	SLO-2		Merits and Demerits of Client Server	CASE Study for ATAM		Behavioral Design Pattern - Types
S-6	SLO-1	Design for quality attributes - Modifiability (General Scenario, Tactics)	Blackboard Architectural Pattern	Evaluating the Architecture - CBAM	Object-oriented design	Observer Pattern
	SLO-2		Merits and Demerits	Decision-Making Context		Strategy Pattern
S-7	SLO-1	Design for quality attributes - Security (General Scenario, Tactics)	Flight Simulation: A Case Study in an Architecture for Integrability	Basis for the CBAM - Case Study	Aspect Oriented Design	Iterator pattern
	SLO-2		Relationship to the Architecture Business			Introduction to ADL

			Cycle			
S-8	SLO-1	Design for quality attributes - Usability (General Scenario, Tactics)	Requirements and Qualities related to flight simulation	Evaluating Software Architecture - SAAM	Design Metrics - Need for Metrics	Components of ADL- Example
	SLO-2			SAAM Evaluation Process	WMC -DIT	
S-9	SLO-1	Design for quality attributes - Testability (General Scenario, Tactics)	Architectural Solution for flight simulation	Evaluating Software Architecture - ARID	NOC - CBC	Future Directions in Architecture
	SLO-2			ARID Evaluation Process	RFC- LCOM	

Learning Resources	<ol style="list-style-type: none"> 1. Len Bass, Paul Clements, & Rick Kazman. <i>Software Architecture in Practice (Third Edition)</i>. Addison-Wesley, 2013 2. Humberto Cervantes, Rick Kazman, <i>Designing Software Architectures: A Practical Approach</i>. Pearson Education, 2016 3. Carlos Otero, "Software Engineering Design: Theory and Practice", CRC Press, 2012 4. Paul Clements, Rick Kazman, Mark Klein, <i>Evaluating Software Architectures: Methods and Case Studies</i>. Addison Wesley; 1 edition (22 October 2001) 5. Jason McC. Smith, "Elemental design Patterns", Addison Wesley, 2012 6. Vasudeva Varma, <i>Software Architecture: A Case Based Approach</i>. Pearson Education, 2009.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Understand										
	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Analyze										
	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
		Mr.C.Arun, SRMIST

Course Code	18CSE369T	Course Name	SOFTWARE MODELING AND ANALYSIS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Select a suitable modeling method according to problem area and assignment, and can justify their choice.				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Formulate models of a system to describe the system on different levels of abstraction and from different viewpoints.				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Identify the Formal models used in software development																					
CLR-4 :	Define model checking concepts using tools																					
CLR-5 :	Model the software system and analyze its characteristics and correctness.																					

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Implement the appropriate modeling method for the given problem	2	80	85	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-2 :	Explain the system abstraction in different levels	2	75	80	H	H	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-3 :	Apply the Formal models in the software development	2	85	80	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-4 :	Apply tools to check model checking properties of a system	2	80	75	H	H	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-5 :	Analyze the characteristics and correctness of software system	2	75	85	H	-	-	H	-	-	-	-	-	-	-	-	-	-	-

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction to software modelling	Representing domain concepts by conceptual objects	Modeling system agents, Characterizing agents.	Correctness of Object Oriented Programs Design by Contract, The Class Invariant	Introduction to Kripke Structures
S-2	SLO-1	Modeling principles	Entities, Association, Attributes	Representing agent models,Refinement of abstract agents	Example - correctness of stack application	Modeling System Design as Kripke Structure
S-3	SLO-1	Goal features as model annotations,Goal refinement	Built-in associations for structuring object models	Building Agent models	A real-time temporal logic for specifying model annotations	Exercise on Kripke Modelling, Recap to Kripke Structures
S-4	SLO-1	Representing conflicts among goals,Connecting the goal model with other system views.	Class Diagrams, Heuristic rules for building object models	Modelling system operations, Characterizing system operations	Specifying goals in the goal model.	Exercises on system modeling using kripke structures, Introduction to LTL
S-5	SLO-1	Modelling alternative options, Goal diagrams as AND/OR graphs.	Object or Attribute Entity, association, agent or event?	Goal Operationalization, Goals, agents, objects and operations	Specifying descriptive properties in the object model	Properties of a system, Liveness and Safety properties , Exercise on specifying properties as LTL formula
S-6	SLO-1	Documenting goal refinements and assignments with annotations	Attribute of a linked object or of the linking association Specialization and generalizing concepts Avoiding common pitfalls	Representing object models, Building operation models	Specifying operationalization's in the operation model	Introduction to NuSMV tool, Model Checking using NuSMV,Introduction to SPIN CHECKER tool
S-7	SLO-1	Building goal models: Heuristic rules and reusable patterns	Aggregation or association? Avoiding common pitfalls	Modelling System behaviour, Modelling instance behaviours	Checking goal refinements deriving goal operations	Model Checking using SPIN checker tool
S-8	SLO-1	Goal obstruction by obstacles	Specialization and generalizing concepts Avoiding common pitfalls	Modelling class behaviours	Generating obstacles for risk analysis Generating anti goals for security analysis	System Property as first order logic formula Proof of correctness using theorem prover

S-9	SLO-1	Modelling obstacles, Obstacle analysis for a more robust goal model	Case Study	Building behaviour models	Formal conflict analysis. Synthesizing behaviour models for animation and model checking.	Introduction Isabelle tool, Theorem proving using Isabelle
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Learning Resources	1. Axel van Lamsweerde "Requirements Engineering: From System Goals to UML Models to Software Specifications" ISBN: 978-0-470-01270-3 February 9, 2009 Wiley 2. http://www.bowdoin.edu/~allen/courses/cs260/readings/ch12.pdf	3. Gerard J. Holzmann, "The SPIN Model Checker: Primer and Reference Manual" ISBN-13: 978-0321773715, AT&T Bell Labs Murray Hill New Jersey ©2004 Addison-Wesley Professional
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Ms T Vijayalakshmi Priyadharsini, Senior Manager, Cognizant Technology Solutions, Chennai	1. Dr. Kumudha Padmanaban, Associate Professor, Coimbatore Institute of Technology, kumudha@cit.edu.in	1. Mr Ramraj S, SRMIST
	2. Dr M Sangeetha, Coimbatore Institute of Technology, citcsesangi@gmail.com	2. Ms A Nithya Kalyani, SRMIST

Course Code	18CSE370T	Course Name	DESIGN PATTERNS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Conceive the importance of reuse of solution for common problems in software development.				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Identify the appropriate patterns for design problems.																					
CLR-3 :	Implement the various design pattern solution for appropriate scenarios																					
CLR-4 :	Refactoring the badly designed program properly using patterns.																					

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Basics of UML Class Diagram, Interaction Diagram	Strategy pattern- Intent, Motivation, Applicability, Structure, Participants, collaborations, consequences	Abstract factory- Intent, Motivation, Applicability, Structure, Participants, collaborations, consequences	Adapter- Intent, Motivation, Applicability, Structure, Participants, collaborations, consequences	What to Expect from Design Patterns The Pattern Community An Invitation
	SLO-2		Strategy pattern- Implementation and sample code	Abstract factory- Implementation and sample code	Adapter- Implementation and sample code	
S-2	SLO-1	Object design, Reuse Concepts, Solution Objects Inheritance & Design Patterns	Mediator - Intent, Motivation, Applicability, Structure, Participants, collaborations, consequences	Singleton pattern- Intent, Motivation, Applicability, Structure, Participants, collaborations, consequences	Bridge- Intent, Motivation, Applicability, Structure, Participants, collaborations, consequences	A Parting Thought A Case Study : Designing a Document Editor : Design Problems, Document Structure
	SLO-2		Mediator- Implementation and sample code	Singleton pattern Implementation and sample code	Bridge- Implementation and sample code	
S-3	SLO-1	Principle and Strategies Open/Closed principle Designing from context, Encapsulating Variation	Template Method- Intent, Motivation, Applicability, Structure, Participants, collaborations, consequences	Factory method pattern- Intent, Motivation, Applicability, Structure, Participants, collaborations, consequences	Decorator, Facade- Intent, Motivation, Applicability, Participants, collaborations, consequences	A Case Study : Designing a Document Editor : Design Problems, Document Structure Formatting, Embellishing the User Interface
	SLO-2		Template Method- Implementation	Factory method pattern Implementation	Decorator, Facade- Implementation	
S-4	SLO-1	Abstract classes and Interfaces Design patterns and Architecture	Template Method- sample code	Factory method pattern sample code	Decorator, Facade- Sample Code	Supporting Multiple Look-and-Feel Standards Supporting Multiple Window Systems
	SLO-2		Case study: Identify which pattern is applicable for the given case study and justify	Case study: Identify which pattern is applicable for the given case study and justify	Case study: Identify which pattern is applicable for the given case study and justify	
S-5	SLO-1	Gand of Four Patterns Basics of UML	Case study: Identify which pattern is applicable for the given case study and justify	Case study: Identify which pattern is applicable for the given case study and justify	Case study: Identify which pattern is applicable for the given case study and justify	User Operations Spelling Checking and Hyphenation What to Expect from Design Patterns
	SLO-2		Strategy pattern- Intent, Motivation, Applicability, Structure, Participants, collaborations, consequences	Abstract factory- Intent, Motivation, Applicability, Structure, Participants, collaborations, consequences	Adapter- Intent, Motivation, Applicability, Structure, Participants, collaborations, consequences	
S-6	SLO-1	Class Diagram. Interaction Diagram	Strategy pattern- Implementation and sample code	Abstract factory- Implementation and sample code	Adapter- Implementation and sample code	The Pattern Community An Invitation

	SLO-2	Object design, Reuse Concepts, Solution Objects	sample code Mediator - Intent, Motivation, Applicability, Structure, Participants, collaborations, consequences	sample code Singleton pattern- Intent, Motivation, Applicability, Structure, Participants, collaborations, consequences	Bridge- Intent, Motivation, Applicability, Structure, Participants, collaborations, consequences	A Parting Thought
S-7	SLO-1	Inheritance & Design Patterns Principle and Strategies Open/Closed principle	Mediator- Implementation and sample code	Singleton pattern Implementation and sample code	Bridge- Implementation and sample code	A Case Study : Designing a Document Editor : Design Problems, Document Structure
	SLO-2		Template Method- Intent, Motivation, Applicability, Structure, Participants, collaborations, consequences	Factory method pattern- Intent, Motivation, Applicability, Structure, Participants, collaborations, consequences	Decorator, Facade- Intent, Motivation, Applicability, Participants, collaborations, consequences Structure	A Case Study : Designing a Document Editor : Design Problems, Document Structure
S-8	SLO-1	Designing from context, Encapsulating Variation Abstract classes and Interfaces	Template Method- Implementation	Factory method pattern Implementation	Decorator, Facade- Implementation	Formatting, Embellishing the User Interface
	SLO-2		Template Method- sample code	Factory method pattern sample code	Decorator, Facade- Sample Code	Supporting Multiple Look-and-Feel Standards
S-9	SLO-1	Design patterns and Architecture	Case study: Identify which pattern is applicable for the given case study and justify	Case study: Identify which pattern is applicable for the given case study and justify	Case study: Identify which pattern is applicable for the given case study and justify	Supporting Multiple Window Systems
	SLO-2					

Learning Resources	1. Bruegge, Bernd and Allen H. Dutoit. "Object-Oriented Software Engineering: Using UML, Patterns and Java", Pearson: Prentice Hall Publishers 2004 2. Erich Gamma, Richard Helm, "Design Patterns: Elements of reusable software development", Pearson Education, 2005	3. Alan Shalloway, James R Trott "Design pattern explained", Pearson Education, 2005. 4. Eric Freeman, Elisabeth Robson, Bert Bates, and Kathy Sierra, "Head First Design Patterns", O'reilly Publications, 2004.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Ms T Vijayalakshmi Priyadharsini, Senior Manager, Cognizant Technology Solutions, Chennai	1. Dr. Kumudha Padmanaban, Associate Professor, Coimbatore Institute of Technology, kumudha@cit.edu.in	1. Dr S Sridar SRMIST
	2. Dr M Sangeetha, Coimbatore Institute of Technology, citcsesangi@gmail.com	2. Ramraj S SRMIST

Course Code	18CSE371T	Course Name	USER INTERFACE DESIGN	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Understand the concepts of design; Utilize by learning various color models	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Gain knowledge on the basics of various law in UX		
CLR-3 :	Construct the task for requirement gathering		
CLR-4 :	Gain knowledge on how to Design for various domains or applications		
CLR-5 :	Introduce tools for designing various applications		
CLR-6 :	Utilised different types of design for real-time programming applications		

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Identify various color models for design	2	80	85	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-2 :	Create the design as per the design law	2	75	80	H	H	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-3 :	Construct the task for requirement gathering	2	85	80	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-4 :	Create wire frames and prototypes	2	80	75	H	H	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-5 :	Create the usability constraints and accessibility	2	75	85	H	-	-	H	-	-	-	-	-	-	-	-	-	-	-
CLO-6 :	Construct real-time applications using real-time programming applications	2	80	85	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-

Duration (hour)	9	9	9	9	9
S-1	SLO-1	What is typography-type properties, baseline, cap height	Laws of UX designing	Introduction to Interaction Design	Culture in usability
	SLO-2	X-height, ascenders	Hicks law	Task analysis	Universal usability
S-2	SLO-1	Descenders and weight	example of hicks law with an application	Data collection for gathering user	Inclusive interaction
	SLO-2	Type classification-Serif	Jakob's law	Data for task requirements	Importance of accessibility
S-3	SLO-1	sans serif fonts	example of jakob's law with an application	Requirements gathering	principles of accessibility
	SLO-2	monospace	Fitts's Law	Eliciting Qualitative data	Universal design
S-4	SLO-1	handwriting and Display	example of Fitts's law with an application	analyzing qualitative data	Accessibility design
	SLO-2	Readability, letter spacing	Ockham's Razor	Qualitative metrics	Font weight, color
S-5	SLO-1	line height with an example	example of Ockham's law with an application	User narratives	Contrast, Screen readers
	SLO-2	Paragraph spacing, power of alignment	Pareto Principle	Scenario implementation and its challenges	Alt text using a tool
S-6	SLO-1	Leading and Kerning	example of Pareto principle with an application	Wireframes	Introduction to Multifaceted Users
	SLO-2	Fundamentals of color	Weber's law	Example on wireframes	Designing for Multifaceted Users

S-7	SLO-1	Color Models Introduction	example of Weber's law with an application	Prototypes	Design guidelines	Approach to design without user data
	SLO-2	RGB, CMYK	Tesler's law	Implementation of Prototypes	Guidelines for helping adults	Designing concept
S-8	SLO-1	Color harmony: monochromatic, analogous	example of Tesler's law with an application	UX design for mobile application	Application example	Implementation problems without data
	SLO-2	Complementary, triadic, double-complementary	Law of proximity	Application design example	Virtual third eye simulator introduction	Dynamic webpages
S-9	SLO-1	Meaning of colors	example of proximity	Responsive Design	Web accessibility guide	Demo
	SLO-2	The power of Contrast	Law of similarity and human eye	Adaptive design and difference with Responsive design	Virtual third eye simulator web accessibility	Perform UI Case study

Learning Resources	1. Jeff Johnson, Kate Finn- "Designing user Interfaces for an aging population towards Universal design- Morgan Kauffman publishers – Elsevier-2017	3. Andrew Rogerson- "User Experience Design" – Smashinmedia 2012-Freiburg, Germany
	2. Elvis Canziba- "Hands-on UX Design for Developers" – Packt Birmingham, Mumbai-2018	4. Barbara Ballard, "Designing the mobile user experience" Wiley publications 2007 5. https://uxdesign.cc/tagged/case-study

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
		1. Mr.S.Karthick, SRMIST
		2.Mrs.Akilandeswari, SRMIST

Course Code	18CSE372T	Course Name	VISUAL PROGRAMMING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	CSE	Data Book / Codes/Standards			Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:		Learning			Program Learning Outcomes (PLO)															
CLR-1 :	Gain knowledge about basics of C# and .NET framework	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Utilize object-oriented aspects of C# to develop applications				Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3			
CLR-3 :	Utilize forms, menus etc. to design Windows applications				-	-	-	-	H	-	-	-	-	-	-	-	H	-	-	-		
CLR-4 :	Utilize ActiveX Data Objects to create Database applications				H	-	M	M	H	L	L	-	H	-	-	H	-	-	-			
CLR-5 :	Utilize web forms to develop Web based applications				H	H	M	-	H	L	L	-	H	-	-	H	-	-	-			
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	Understand the basics of C# and .NET framework	2	80	85																		
CLO-2 :	Develop applications using object-oriented aspects of C#	2	75	80																		
CLO-3 :	Design Windows applications	2	85	80																		
CLO-4 :	Create Database applications using ActiveX Data Objects	2	80	75																		
CLO-5 :	Develop Web based applications	2	75	85																		

Duration (hour)		10	10	9	8	8
S-1	SLO-1 SLO-2	Introducing C# - Understanding .NET Framework	Class – Objects	Building Windows Application	Accessing data with ADO.NET: DataSet	Programming Web Application with Web Forms
S-2	SLO-1 SLO-2	Overview of C# - Literals – Variables Data Types – Operators – Constants - Expressions	Constructors – Types of Constructors	Examples: Windows Applications	Accessing data with ADO.NET: Typed Dataset	Introduction to ASP.NET,
S-3	SLO-1 SLO-2	Program Control Statements: Branching	Inheritance and its types	Creating Window Forms with Events and Controls	Data Adapter	Working with XML and .NET
S-4	SLO-1 SLO-2	Program Control Statements: Looping	Examples - Inheritance	Examples: Window Forms with Events and Controls	Updating Database using Stored Procedures	Creating Virtual Directory and Web Application
S-5	SLO-1 SLO-2	Casting - Methods	Indexers and Properties	Menu and Toolbar	SQL Server with ADO.NET	Session Management
S-6	SLO-1 SLO-2	Arrays: Array Class	Polymorphism – Operator Overloading	Delegates - Inheriting Window Forms	Handling Exceptions	Web Services – web.config
S-7	SLO-1 SLO-2	Array List	Polymorphism – Method Overloading	SDI Application	Validating Controls	Web Services – Passing Datasets and Returning Datasets from Web Services
S-8	SLO-1 SLO-2	String	Interfaces, Abstract Class	MDI Application	Windows Application Configuration	Transaction Handling, Exception Handling – Returning Exceptions from SQL Server
S-9	SLO-1 SLO-2	String Builder	Event Handling	Dialog Box: Modal and Modeless		
S-10	SLO-1 SLO-2	Structures - Enumerations	Errors and Exception Handling			

Learning Resources	3. Herbert Schildt, "The Complete Reference: C# 4.0", Tata McGraw Hill, 2012.	5. Christian Nagel et al. "Professional C# 2012 with .NET 4.5", Wiley India, 2012.
	4. Andrew Troelsen, Philip Japikse, "C# 6.0 and the .NET 4.6 Framework", Seventh Edition, Apress, 2015	6. Andrew Troelsen, Philip Japikse, "Pro C# 7 with .NET and .NET Core", Eighth Edition, Apress, 2017 7. Stephen C. Perry, "Core C# and .NET", Prentice Hall, 2005

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Prakas, Associate Consultant, Virtusa, Chennai	1.	1. Dr. M.S. Abirami, SRMIST
2. Mr. S. Padmanabhan, Associate Vice President, Intellect, Chennai	2.	2. Ms. Nagadevi SRMIST 3. Mr. K. Navin

Course Code	18CSE373T	Course Name	PROGRAMMING IN JAVASCRIPT	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	CSE	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand scripting language basics for web development	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Develop familiarity with the JavaScript language – Arrays, Objects, Functions	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Understand concepts like HTML, CSS, DOM,				H	H	-	-	-	-	-	-	-	-	-	-	-	-	-
CLR-4 :	Acquire knowledge of jQuery, DOM events etc.				H	H	-	-	-	-	-	-	-	-	-	-	-	-	-
CLR-5 :	Apply in AJAX and learn the usage of Closures				H	H	-	-	-	-	-	-	-	-	-	-	-	-	-
					H	H	-	H	-	-	-	-	-	-	-	-	-	-	-
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Learn the basics of Scripting language	2	80	85															
CLO-2 :	Ability to use Javascript in applications	2	75	80															
CLO-3 :	Ability to apply HTML, CSS and DOM	2	85	80															
CLO-4 :	Ability to Apply jQuery concepts in applications	2	80	75															
CLO-5 :	Understand the AJAX environment and Closure concept	2	75	85															

Duration (hour)	9	9	9	9	
S-1	SLO-1	Learn concept of Scripting languages	Arrays. Array insertion and deletion	HTML and CSS and	jQuery, Overview of jQuery
	SLO-2	Compiled vs interpreter a comparison	Array length	The Document Object Model, Tags	Examples
S-2	SLO-1	Understand Web development basics	Sparse arrays	Document structure.	Cross-browser compatibility
	SLO-2	Acquire basic knowledge on Server side programming	Multidimensional arrays	Elements. Text, forms, images, blocks and frames.	The \$ function object
S-3	SLO-1	Understand concept of dynamic interactive web pages.	Objects as unordered maps. Object creation,	Selectors	Element selectors.
	SLO-2	Overview of JavaScript, Brief history	modification and lookup syntax. Nested objects. Object methods.	Cascading and inheritance	Tree traversal.
S-4	SLO-1	Common use-cases. Runtime environments, Overview of language features.	The delete keyword.	Text and color tyles.	Node creation, insertion, modification and deletion.
	SLO-2	Running JavaScriptDebugging JavaScript in the browser. The console and REPL in the browser and at the command line	The for... in statement, and the hasOwnProperty method.	The box model.	Getting and setting attributes,
					Context Object method invocation as method passing

S-5	SLO-1	Values and literals. Primitive types. Numbers. Integer and floating point as a single type Rounding errors.	The global window object. Object references	Layout.	styles and class.	The this variable as an implicit parameter variable.
	SLO-2	Special floating point numbers.	Aliasing. Pass-by-reference-copy semantics.	The DOM as an document API. Browser information	Wrapping and unwrapping DOM raw objects.	Problems with methods in event handlers and callbacks
S-6	SLO-1	The Math library. Strings. Immutability of strings.	Functions :Function declaration and invocation syntax.	The setTimer and setTimeout		Usage of call and apply
	SLO-2	+ and [] operatorsCommon string utilities	Anonymous functions.	Element lookup	The chaining pattern	Binding context.
S-7	SLO-1	Booleans. Ternary operator.	Functions as data.	Tree traversal.	Event handling.	The new keyword.
	SLO-2	Regular expressions. Truth-y and False-y values. null and undefined.	The arguments object.	Attribute getting and setting	bind and unbind.	Closures Lexical scope. Inner functions
S-8	SLO-1	Dynamic typing. Weak typing. The typeof operator.	Variadic functions. Optional parameters.	Creating and deleting nodes.	Keyboard and mouse events.	Closure scope. Examining closure scope in the debugger
	SLO-2	The === and !== operators.	Named parameters. Function overloading.	Events.	Event delegation and bubbling.	Functors.
S-9	SLO-1	Control statements.	Duck typing.	Case studies	Animation.	Simulation of private object properties.
	SLO-2	Examples	Examples	Case Studies	Examples	Simulation of namespaces.

Learning Resources	1. Don Gosselin , JavaScript Fifth Edition, Thomson Learning., Web Technology Series	3. Laura Lemay, Rafe Colburn, Jennifer Kymin, "Mastering HTML, CSS & Javascript", Web Publishing, 2016
	2. Nicholas C Zakas, Professional JavaScript for Web Developers , Wrox Professional Guide, 2012	

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
	1.	1. Prof.S.S.Sridhar, SRMIST

Course Code	18CSE374T	Course Name	SOFTWARE ENGINEERING TOOLS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	CSE	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:				Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Understand the software engineering process and the tools used to support this process to deliver the quality software product					1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2 :	Know the process, tools and methods used for software requirements modeling and the designing process					Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3		
CLR-3 :	Study the various software development approaches, tools and to install and use some software development tools								H	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
CLR-4 :	Know about different web application development technologies and tools used to support the quick development process								H	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLR-5 :	Understand the software testing process used in the industry and various test related tools used for the different task in the testing								H	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLR-6 :	Study the functionalities of different testing tools used in the software maintenance and engineering process								H	-	-	H	-	-	-	-	-	-	-	-	-	-	-	-	-
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:				2	80	85	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-		
CLO-1 :	Use automated tools to develop the quality software product in by following engineering process					2	80	75	H	H	-	-	-	-	-	-	-	-	-	-	-	-	-		
CLO-2 :	Design the specification of software using various techniques and tools					2	75	80	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-		
CLO-3 :	Create application using latest tools, code generators and IDEs					2	85	80	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-		
CLO-4 :	Apply the various web technologies and tools to develop the web application					2	80	75	H	H	-	-	-	-	-	-	-	-	-	-	-	-	-		
CLO-5 :	Know the various testing tools and apply it during the software testing process					2	75	85	H	-	-	H	-	-	-	-	-	-	-	-	-	-	-		
CLO-6 :	Use the tools for process management and to gain the knowledge of various tools used for different task in maintenance activities					2	80	85	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-		

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Introduction to Software Engineering Process	Software Construction Tools	Web Application Development Tools	Software Testing Process	Software Engineering Process Tools
	SLO-2 Need of Tools in the Software Engineering Process	Program editors	Tools for Front End Developers	Software Testing Tools	Process modeling tools
S-2	SLO-1 Requirement Engineering Process	Compilers	TypeScript	Need for Automated Testing Tools	Process management tools
	SLO-2 Software Requirements Tools	Compiler types	Installing TypeScript	Taxonomy of Testing Tools	Integrated CASE environments
S-3	SLO-1 Requirements modeling tools	code generators	AngularJS	Functional/Regression Testing Tools	Process-centered software engineering environments
	SLO-2 Traceability tools	Tools for JAVA code generator	AngularJS Architecture and Features	Performance Testing Tools	Software Configuration Management Tools
S-4	SLO-1 Desirable Features of Requirement Management Tools	Comparison of code generation tools	Tools for Back End Developers	Testing Management Tools	Defect, enhancement, issue and problem tracking tools
	SLO-2 Some Requirement Management Tools Available	Interpreters	PHP	Source Code Testing Tools	Version management tools
S-5	SLO-1 Tools Description	Difference between Compiler and Interpreters	Ruby on Rails	How to Select a Testing Tool?	Software Engineering Management Tools
	SLO-2 Software Design Process	Debuggers	Laravel	Test execution frameworks	Project planning and tracking tools
S-6	SLO-1 Steps in Software Design	Integrated Development Environment	Overview of Content Management System (CMS)	Re-engineering tools	Risk management tools
	SLO-2 Software Modeling Languages	Comparison of IDE	WordPress	WinRunner	Infrastructure Support Tools
S-7	SLO-1 Unified Modeling Language	ATOM Tool	WordPress - Features	Overview of WinRunner	Interpersonal Communication tools
	SLO-2 Behavior Trees	Features of ATOM Tool	WordPress – Installation	LoadRunne - Overview	Information retrieval tools

S-8	SLO-1	C-K theory	Installing Atom	Joomla - Overview	QTP - Overview	System administration and support tools
	SLO-2	IDEF, Object-Role Modeling	NetBeans	Joomla – Features	JUnit - Overview	Miscellaneous Tool Issues
S-9	SLO-1	Petri nets	Features of NetBeans	Joomla – Installation	Testing Java Code using JUnit	Tool integration techniques
	SLO-2	Software Design Tools	Cloud Based Development tools	Drupal – Overview and Architecture	Examples	Tool evaluation

Learning Resources	1.	RogerSPressman, "SoftwareEngineering–APractitioner'sApproach", 7th edition, TataMcGrawHill Education, 2014.	4.	SwapnaKishoreandRajeshNaik, "SoftwareRequirementsandEstimation", TataMcGrawHill, 2003
	2.	IanSomerville "SoftwareEngineering", 9th edition, PearsonEducation, 2010.	5.	K.V.K.K.Prasad, "SoftwareTestingTools", DreamtechPress, 2010
	3.	https://atom.io/	6.	https://www.w3schools.com
			7.	https://www.joomla.org/

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. R.Tamilanban, Senior Software Engineer, Altimetrik India Pvt. Ltd.	1.	1. S.KALIRAJ, SRMIST
2.	2.	2. R.ANITA, SRMIST

Course Code	18CSE466T	Course Name	SOFTWARE VERIFICATION AND VALIDATION	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	COMPUTER SCIENCE AND ENGINEERING	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Provide an understanding of concepts and techniques for testing software				Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Prepare test plan based on the requirement document ,design test plans and document test plans									Problem Analysis														
CLR-3 :	Design test cases suitable for a software development in various domains									Design & Development														
CLR-4 :	Validate and document test cases, assuring software component or system satisfies its requirements and meets stakeholder expectations									Analysis, Design, Research														
CLR-5 :	Use of automation testing tools									Modern Tool Usage														
									Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3						
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1 :	Identify, design different types of test cases for software development in any domain				2	80	85		H	H	H	H	H	M	M	M	H	H	H	M	H	H	H	H
CLO-2 :	Design, develop, implement, validate and document test plans at various levels				3	80	80		H	H	H	H	M	M	M	M	H	H	H	M	H	H	H	H
CLO-3 :	Develop Test cases for a given Software/System Specification				2	90	85		H	H	H	H	M	-	M	M	H	H	M	M	H	H	H	H
CLO-4 :	Validate Test Cases with the Requirement Specifications				2	80	80		H	H	H	M	M	-	M	M	H	H	H	M	H	H	H	H
CLO-5 :	Use various automation tools to implement test cases				3	75	80		H	M	H	H	H	M	M	M	H	H	M	H	H	H	H	H

Duration (hour)	8	10	8	9	10
S-1	SLO-1 Fundamentals of Testing: Necessity of Testing-Case Studies on "Impact of Software bugs"	Test Case Design Strategies: Introduction to basic design strategies	The need for levels of testing, Unit Testing: Planning, Test Harness	Test Management: Choice of Standards	Software Test Automation: Skills and Scope Design
	SLO-2 Objectives of Testing, Basics Definitions		Running the tests Recording Results	Infrastructure Management, Test People Management	
S-2	SLO-1 Testing Principles-Illustrations	White Box Strategies - Peer Reviews, Inspections, Walkthrough	Integration Testing: Goals, Design and Plan	Test Plan Components	Architecture for Automation
	SLO-2 Fundamental Test Process, The tester's role in a software development organization	Comparative Analysis		Test Plan Attachments	
S-3	SLO-1 Test planning	Static Analysis Tools: Coding Standards, Code Metrics, Code Structure	System Testing goals, Types of System Testing: Functional Testing	Locating Test Items, Managing Issues	Requirements for a test tool, Process Model for Automation, Selecting the test tool
	SLO-2 Establishing Test Policy, Structured approach to testing Test Factors	Activity: Static Analysis of a source code	Performance Testing, Stress Testing	Addressing Perception, Taking team together	
S-4	SLO-1 Eleven Step software testing process	Coverage and Control Flow Graphs	Configuration Testing	Documentation uses	Demonstration of a Functional Testing Tool
	SLO-2 Origin of Defects, Defect Repository and Test Design	Activity: Calculate Complexity for a given source code	Security Testing	Documentation Types	
S-5	SLO-1 Developer/Tester support of developing a defect repository	Paths Code Complexity	Recovery Testing, Reliability Testing	Test Analysis report Documentation,	Demonstration of a Web Testing Tool
	SLO-2 Defect Examples, Case Studies – "Identify the defect"	Activity: Calculate Path Code Complexity for a given source code	Usability Testing	Analyze reports and Problem tracking,	
S-6	SLO-1 Evaluating test adequacy criteria, Case Studies-"Applying the suitable White Box Strategy"	Regression Testing	Controlling and Monitoring Test Progress	Test Metrics and measurements: Role, need and types	Démonstration of an Unit Testing Tool
	SLO-2 Alpha, Beta and Acceptance Testing				

S-7	SLO-1 SLO-2	Defect Analysis and Prevention Strategies	Black Box Testing Strategies: Requirements Based Testing, Random Testing	Role of use cases in testing Applying Testing Skills: Compatibility testing, Internationalization testing	Project Metrics with Practice	Demonstration of an Defect Tracking Tool
S-8	SLO-1 SLO-2	Developing adhoc test cases for a case study	Black Box Testing Strategies: Boundary Value Analysis, Equivalence Class Partitioning, Activity: Designing test cases for the given requirement specification using Boundary value analysis and Equivalence Class Partitioning	Testing Documentation plan Recording test cases, Reporting and Measurement of Success	Progress Metrics with Practice	Demonstration of an Test Management Tool
S-9	SLO-1 SLO-2		Black Box Testing Strategies: Cause Effect graphing Activity: Designing test cases for the given requirement specification using cause effect graphing and developing decision tables		Productivity Metrics with Practice	Challenges in Automation
S-10	SLO1 SLO2		Evaluating test adequacy criteria, Case Studies-“Applying the suitable Black Box Strategy”			The Future: Software Quality Assurance

Learning Resources	<ol style="list-style-type: none"> Srinivasan Desikan and Gopalswamy Ramesh, “Software Testing – Principles and Practices”, Pearson Education, 2006 Ron Patton, “Software Testing”, Second Edition, Sams Publishing, Pearson Education, 2007. 	<ol style="list-style-type: none"> Ilene Burnstein, “Practical Software Testing”, Springer International Edition, 2003. Aditya P. Mathur, “Foundations of Software Testing _ Fundamental Algorithms and Techniques”, Dorling Kindersley (India) Pvt. Ltd., Pearson Education, 2008 RenuRajani, Pradeep Oak, “Software Testing-Effective Methods, Tools and Techniques”, Tata McGraw Hill Education, 2011.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. ShrikantSatyanarayan, Technical Manager LDRA Technology PVT LTD	1. Dr. N. Bhalaji, Associate Professor, SSN Institutions	1. Mrs. Anupama.C.G, SRMIST
2. Mr. Girish Raghavan, Senior DMTS Manager, Wipro Technologies		2. Mr. Selvin Paul Peter, SRMIST

Course Code	18CSE467T	Course Name	SOFTWARE QUALITY ASSURANCE	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	CSE	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:		
CLR-1 :	Understand the importance of software quality			
CLR-2 :	Gain knowledge about the components of software quality assurance system			
CLR-3 :	Gain knowledge on conducting reviews walk through and inspection			
CLR-4 :	Understand the importance of SCM, procedures, policies in SQA			
CLR-5 :	Recognize the significance of human components			
CLR-6 :	Gain Knowledge on measurements and standards			

Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:		
CLO-1 :	Acquire the knowledge on software quality			
CLO-2 :	Acquire the ability to identify the dimension of a software project			
CLO-3 :	Apply different quality component in different phase of life cycle			
CLO-4 :	Follow procedures, processes, policies and work instructions in software development			
CLO-5 :	Manage risks and handle human components effectively			
CLO-6 :	Apply different measurements and follow standards			

Learning			
1	2	3	
Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	

Program Learning Outcomes (PLO)														
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO – 3
-	-	-	-	-	-	-	-	-	-	M	-	H	-	-
H	H	-	-	-	-	-	-	-	-	-	-	-	-	-
H	H	-	-	-	-	-	-	-	-	-	-	-	H	H
-	-	-	-	-	-	M	H	-	-	-	-	-	-	-
H	-	-	H	-	M	-	-	-	H	-	-	-	-	-
-	-	H	-	H	-	-	-	H	-	-	H	-	-	-

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction to software Quality	Software Quality Assurance System Architecture	Check lists	Introduction to Risk management	Importance of Measurement
	SLO-2	Defining software quality and software quality Assurance	Components of Software Quality Assurance System	Verification and validation	Risk management according to the standards and models	Measurement according to ISO 9001
S-2	SLO-1	Software error, defects and failures	Contract Review process and its stages Contract Review objectives	Verification and validation	Risk management according to the standards and models	The practical software and systems measurement method
	SLO-2	Software error, defects and failures	Implementation of Contract Review, Contract review for internal projects	Basics of Software Configuration Management , Benefits of Good configuration Management	Risk management according to the standards and models	The practical software and systems measurement method
S-3	SLO-1	Cost of quality	Development plan	Activity: Test the functionalities of the given project using any functional testing tool	Roles, Measurements	Measurement According to the CMMI Model
	SLO-2	Cost of quality	Quality Plan	Activity: Test the functionalities of the given project using any functional testing tool	Human factors and risk management	Measurement According to the CMMI Model
S-4	SLO-1	Quality culture	Reviews,Personal review and desk check review	SCM Activities, Baselines	Introduction to supplier management, Supplier requirements	Survey as a measurement tool

	SLO-2	Five dimensions of a software project	Walk through	Software Repository and its branches, Configuration Control	Agreement Processes, Supplier agreement management according to the CMMI	Survey as a measurement tool
S-5	SLO-1	Software Engineering code of Ethics	Review standards and Models	Configuration Status Accounting	Managing suppliers	Implementing a measurement program
	SLO-2	Software Engineering code of Ethics	Review standards and Models	Software Configuration Audit, Implementing SCM in very small entities with ISO/IEC29110	Software Acquisition life cycle	Standards, cost of quality and business models
S-6	SLO-1	Software quality models- McCall	Inspection	Policies	Software Contract Types	ISO 9000 family
	SLO-2	Software quality models- McCall	Project Launch reviews and project assessments	Process	Software Contract Reviews	IEEE 730 standard for SQA processes
S-7	SLO-1	Software quality models -IEEE 1061	Agile Meetings	Procedures and work instructions	Case Study: Prepare Contract Review Document for a project	IEEE 730 standard for SQA processes
	SLO-2	Software quality models -EEE 1061	Measures	Organizational standards	Case Study: Prepare Contract Review Document for a project	Process Maturity models of the SEI
S-8	SLO-1	Software quality models -ISO-25000 set of standards	Selecting the type of review, Tools	Graphical representation of process and procedures	Staff Training and Certification	Software Quality Assurance Plan
	SLO-2	Software quality models -ISO-25000 set of standards	Audits, Types, Audits according to the IEEE 1028 standard	Graphical representation of process and procedures	Staff Training and Certifications	Software Quality Assurance Plan
S-9	SLO-1	Case Study: Analyzing quality factors involved in a project	Case Study: Prepare a development plan for a project.	Preventive and corrective actions	Management and its Role in Quality Assurance	Case study: Prepare a Software Quality Assurance Plan for –interested project
	SLO-2	Case Study: Analyzing quality factors involved in a project.	Case Study: Prepare a development plan for a project	Document control	Management and its Role in Quality Assurance	Case study: Prepare a Software Quality Assurance Plan for –interested project

Learning Resources	<p>1. Claude Y.Laporte, Alain April, Software quality Assurance, First edition , IEEE computer Society and Wiley, 2018.</p> <p>2. Daniel Galin, "Software Quality Assurance from theory to implementation", Pearson, 2016</p>	<p>3. G.GordonSchulmeyer, "Hand book of Software Quality Assurance", 4th edition, ARTECH HOUSE INC, 2008</p> <p>4. Allen Gilles, "Software quality: Theory and management" - International Thomson - Computer press, 2011</p>
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers			
Experts from Industry		Experts from Higher Technical Institutions	
1.Mr. Benet Zacharias, Senior Consultant, Wipro Consulting Services, Chennai		1. Dr. A. Amuthan, Professor, Dept. of CSE, Pondicherry Engg. College, Pondicherry.	
		Internal Experts	
		1. Dr. T.S.Shiny Angel, Assistant Professor, SRMIST	
		2. Dr. A. Jeyasekar, Associate Professor, SRMIST	

Course Code	18CSE468T	Course Name	SOFTWARE MEASUREMENTS AND METRICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18CSE466T	Co-requisite Courses	Nil	Progressive Courses	NIL
Course Offering Department	Computer Science and Engineering	Data Book / Codes/Standards			Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:				Learning			Program Learning Outcomes (PLO)															
CLR-1 :		Familiarize with different metrics used in different process levels				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLR-2 :		Apply metrics knowledge to measure Engineering problems.				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3	
CLR-3 :		Improve their ability in making decisions via continuous practice like assessment and usage of metrics.							L	H	-	H	L	-	-	-	L	L	-	H	-	-	-	-
CLR-4 :		Design, implement and change metrics based on industry practice							M	M	L	M	L	-	-	-	M	L	-	H	-	-	-	-
						M	M	M	H	L	-	-	-	M	L	-	H	-	-	-	-	-		
						M	H	M	H	L	-	-	-	M	M	L	-	H	-	-	-	-		

Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:				3																	
CLO-1 :		Understand and measure the software features				3																	
CLO-2 :		Understand the need of software quality				3																	
CLO-3 :		Will be able to understand the software development tools				3																	
CLO-4 :		Evaluate the stages of process improvement and its necessities in Development Life Cycle				3																	

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Software Sizing Metrics	Complexity Metrics and Models	Customer Satisfaction Surveys: Methods of survey data collection	Software Quality - Five steps to software quality control	Conducting In-Process Quality Assessments
	SLO-2	Fundamentals in Measurement		Sampling Methods	Product Quality Metrics with practice	The Preparation Phase
S-2	SLO-1	Basic Measures	Lines of Code	Analyzign Satisfaction with practise	In-Process Quality Metrics	The Evaluation Phase
	SLO-2	Reliability and Validity	Halstead's Software Science			The Summarization Phase
S-3	SLO-1	Measurement Errors	Cyclomatic Complexity	Satisfaction with Company terms	Metrics for Software Maintenance	Recommendations and Risk Mitigation
	SLO-2	Assessing Reliability	Syntactic Constructs			Conducting Software Project Assessments
S-4	SLO-1	Evolution in software Metrics	Structure Metrics	Metrics for Object-Oriented Projects with tools	Ishikawa's Seven Basic Tools with practice	Audit and Assessment
	SLO-2					Software Process Maturity Assessment and Software Project Assessment
S-5	SLO-1	Functional Size Measurements	Case Study for the usage of complexity metrics with tools	Concepts and Constructs	Defect removal Effectiveness	Software Process Assessment Cycle
	SLO-2			Design and Complexity Metrics		Measures and metrics of industry leaders
S-6	SLO-1	Cost of counting function point metrics	Testing Metrics :Test Progress S Curve	Lorenz Metrics and Rules of Thumb	The Rayleigh Model	Measures and metrics of industry leaders
	SLO-2					
S-7	SLO-1	Software measures and metrics not based on function points	Testing Defect Arrivals Over Time	CK OO Metrics Suite	Reliability Growth Models - Jelinski-Moranda Model	Measures, Metrics, Innovation
	SLO-2		Product Size Over Time			Measurements, Metrics and outsource Litigation
S-8	SLO-1	Future Technical Developments in Functional Metrics	CPU Utilization	Productivity Metrics	Goel-Okumoto Model	Measurements, Metrics and outsource and Behavioral changes
	SLO-2		Effort/Outcome Model			Software Process Improvement Sequences
S-9	SLO-1	Case Study to Measure software size using various size Metrics	Case Study to apply Testing metrics	Case Study for the usage of Object oriented metrics with tools	Musa-Okumoto Model	Measuring Process Maturity
	SLO-2					Measuring Proess Capability

Learning Resources	1. Stephen H. Kan, "Metrics and Models in Software Quality Engineering", Addison Wesley, Second Edition, 2017. 2. Caper Jones, "Applied Software Measurement: Global Analysis of Productivity and Quality", Third Edition, McGraw Hill Companies, 2008	3. Mark Lorenz, Jeff Kidd, "Object-Oriented Software Metrics", Prentice Hall, 2000 4. Naresh Chauhan, "Software Testing Principles and Practices", Oxford University Press, 2010. 5. Ravindranath Pandian C, "Software Metrics A Guide to planning, Analysis, and Application", Auerbach, First Indian Reprint, 2011
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Bijoymon Soman Sr. Test Analyst UST Global, Philadelphia, PA, USA	1. Dr. Arun kumar M N, FISAT, Kerala, amrakmar.mn11@gmail.com	1. Mrs. B. Jothi, SRMIST
		2. Ms Aswathy, SRMIST

Course Code	18CSE469T	Course Name	SOFTWARE PROCESS AND AGILE PRACTICES	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering	Data Book / Codes/Standards			

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)															
CLR-1 :	Understand the basic concepts of Software process and Agile manifesto				Level of Thinking (Bloom)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Comprehend various Agile principles					Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3	
CLR-3 :	Gain knowledge on Agile Methodologies																						
CLR-4 :	Acquire Knowledge on Agile project management and Environment																						
CLR-5 :	Understand the concepts of Test driven development and Feature driven development																						
CLR-6 :	Understand the Agile approach to Quality assurance																						
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			2																		80
CLO-1 :	Acquire the knowledge of best practices involved in Software process				2	80	85	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
CLO-2 :	Acquire the ability to identify the agile principles for software development				2	75	80	H	H	-	-	-	-	-	-	-	-	-	-	-	-	-	
CLO-3 :	Understand work products, roles and practices of Scrum, XP, UP and EVO				2	85	80	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
CLO-4 :	Apply the knowledge of Agile methodologies in various projects				2	80	75	H	H	-	-	-	-	-	-	-	-	-	-	-	-	-	
CLO-5 :	Apply the knowledge of Agile project management and practices				2	75	85	H	-	-	H	-	-	-	-	-	-	-	-	-	-	-	
CLO-6 :	Acquire the knowledge of Agile quality assurance				2	80	85	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-	

Duration (hour)		9	9	9	9	9
S-1	SLO-1	The nature of Software	Agile And Its Significance	Agile methodology	Agile Project management	Agile Quality assurance
	SLO-2	Defining Software	Agile Story	Extreme Programming: Method Overview	Multi-team and multi-site development	Feature Driven Development
S-2	SLO-1	The Software Process	Evolutionary delivery, Scrum Demo	Life cycle phases	Pipelining activities across Iterations	Feature Driven Development roles
	SLO-2	Software Engineering practice	Planning game, Sprint back log, adaptive planning and retrospective	Work products	Rolling Wave adaptive and predictive planning	Feature Driven Development process
S-3	SLO-1	Agile Development	Agile Motivation	Roles and practices	Benefits of rolling wave adaptive planning	Class Ownership
	SLO-2	Agility and the cost of change	Challenges With The Waterfall	Core practices	Agile requirements	Reporting
S-4	SLO-1	Agile Process	Research Evidence	Process mixtures	Agile modeling	Test Driven Development (TDD)
	SLO-2	Agile Manifesto & Principles	Scrum: Method Overview	Strengths of XP	Defining and keeping the vision	Test Driven Development roles
S-5	SLO-1	Software is new product development	Life cycle phases	Unified process: Method Overview	Evolutionary Requirements workshop	TDD benefits
	SLO-2	Predictable vs. Inventive Projects	Work products	Work products	Gathering requirements	TDD Limitations
S-6	SLO-1	Iterative and Evolutionary methods	Roles and practices	Roles and practices	Tracking requirement across iterations, Direct user involvement	Agile approach to Quality Assurance
	SLO-2	Risk driven and client driven planning	Core practices	Core practices	Brainstorming and Brain writing	Unscheduled and Scheduled
S-7	SLO-1	Time boxed Iterative development	Values of Scrum meeting	EVO: Method Overview	Mind maps, Team rotation writing	Status meeting
	SLO-2	Evolutionary and Adaptive development	Other practices and values	Life cycle phases	Agile environment	Automated unit tests and Acceptance tests
S-8	SLO-1	Adaptive Development	Common mistakes and	Work products	Continuous Integration	Exploratory Testing
	SLO-2	Incremental Delivery, Evolutionary delivery	Sample projects	Roles and practices	Project Wiki webs, Case tools	Code review and code metrics
S-9	SLO-1	Specific Iterative methods	Process mixtures	Core practices	Caves and common rooms	Continuous Integration
	SLO-2	Evolutionary methods	Strengths and Weakness of Scrum	Process mixtures	Reverse engineering	Informative Workspaces

Learning Resources	1. Bruce R. Maxim Roger S. Pressman, "Software Engineering: A Practitioner's Approach", McGraw Hill Education; Eighth edition, 2019 2. Craig Larman, "Agile and Iterative Development – A Manager's Guide", Pearson Education – 2010	3. Elisabeth Hendrickson Quality Tree Software Inc, "Agile Testing" 2008 4. Chetankumar Patel, Muthu Ramachandran, Story Card Maturity Model (SMM): A Process Improvement Framework for Agile Requirements Engineering Practices, Journal of Software, Academy Publishers, Vol 4, No 5 (2009), 422-435, Jul 2009.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. Harihara prasath venkatraman , Agile Coach, Renault Nissan Technology & Business Centre India , Hariharaprasath.Venkataraman@mtbci.com	Dr.N.Prakash , Associate professor , B.S.A. Crescent Institute of Science and Technology	Mr.G.Senthil Kumar, Asst.prof (S.G), SRMIST
	Dr.K.Kumar, Associate professor, Vellore Institute of technology	Mr.Gouthaman, Asst.Prof., SRMIST

Course Code	18CSE470T	Course Name	SOTWARE SECURITY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Computer Science and Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:		
CLR-1 :	Understand the need for Software Security and the threats to software security			
CLR-2 :	Incorporate security principles to software development lifecycle			
CLR-3 :	Understand Secure software architecture design and coding			
CLR-4 :	Gain basic knowledge on web security principles			
CLR-5 :	Learn risk management and mitigation of risk in software development			
CLR-6 :	Learn testing types and strategies for secure software			

Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:		
CLO-1 :	Identify security threats and issues in software			
CLO-2 :	Gather security related requirements during requirement elicitation			
CLO-3 :	Design software by incorporating security principles			
CLO-4 :	Understand the issues in web and database security			
CLO-5 :	Apply risk management strategies and risk mitigation strategies in software development			
CLO-6 :	Apply testing strategies for secure software development			

Learning			
1	2	3	
Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	

Program Learning Outcomes (PLO)														
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
H	-	-	-	-	-	-	-	-	-	-	-	-	-	-
H	H	-	-	-	-	-	-	-	-	-	-	-	-	-
H	-	-	-	-	-	-	-	-	-	-	-	-	-	-
H	H	-	-	-	-	-	-	-	-	-	-	-	-	-
H	-	-	H	-	-	-	-	-	-	-	-	-	-	-
H	-	-	-	-	-	-	-	-	-	-	-	-	-	-

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Introduction to software Security	Secure software architecture and design	Browser Security Principles	Risk Management Framework	Software security testing
	SLO-2 Software assurance and software security	Software security practices for architecture and design	Defining the same-origin policy	Five stages of activity	Contrasting software testing and software security testing
S-2	SLO-1 Threats to Software security	Software security knowledge for architecture and design	Client-side vs. server-side	Applying the RMF	Functional testing
	SLO-2 Sources of Software Insecurity	Software characterization	Exceptions to the same origin policy	Understanding the business context	Risk-based testing
S-3	SLO-1 Benefits of detecting software security defects early	Threat analysis	Cross-site scripting	Gathering the artifacts, conducting project research	Penetration Testing
	SLO-2 Managing Secure software development	Architectural vulnerability assessment	Reflected, POST-based reflected, stored and local XSS	Identifying the business and technical risk	Security testing consideration throughout the SDLC
S-4	SLO-1 Risk Management framework for Software security	Risk likelihood determination	XSS defense	Developing risk questionnaires, interviewing the target project team	Unit testing
	SLO-2 Software security practices in the development lifecycle	Risk Impact Determination	Cross-site request forgery	Analyzing the research and interview data	Testing Libraries
S-5	SLO-1 Properties of secure software	Risk Mitigation Planning	CSRF defense	Uncovering technical risks	Testing Executable files
	SLO-2 Influencing security properties of software	Security principles	Prevent XSS	Analyzing software artifacts	Integration testing
S-6	SLO-1 Building a security assurance case	Security guidelines and attack patterns	SQL Injection	Synthesizing and ranking the risk	System Testing
	SLO-2 Incorporating assurance cases into SDLC	Secure coding and testing	SQL Injection effects	Reviewing the risk data	Security Failures
S-7	SLO-1 Importance of requirements engineering	Code analysis	Blind SQL Injection	Conducting the business and technical peer review	Categories of Errors
	SLO-2 Security Requirements Engineering	common software code vulnerabilities	Setting Database Permissions	Defining the risk mitigation strategy	Attacker Behaviour
S-8	SLO-1 The SQUARE Process model	Source code review	Stored Procedure Security	The importance of measurement	Functional and attacker perspectives for Security Analysis
	SLO-2 SQUARE sample outputs	Coding practices	SQL Injection in stored procedures	Measurement and metrics in the RMF	Identity Management and Software development

S-9	SLO-1	Requirements elicitation	Sources of additional information on secure coding	Insecure direct object references	The Cigital Workbench	System Complexity drivers and security
	SLO-2	Requirements prioritization	Best practices for secure coding	Pre and post authorization checks	Risk Management is a framework for Software security	Deep Technical Problem Complexity

Learning Resources	1. Gary McGraw, Software Security – A Guide for Project Managers, Addison-Wesley Professional, 2008, ISBN-13: 978-0321509178 2. James M. Helfrich, Security for Software Engineers, CRC Press, Taylor and Francis Group 2019 3. James Ransome, Anmol Misra, Core Software Security, CRC Press, Taylor and Francis Group 2014.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Prasanna Kumar, Infosys, prasanna_kumar11@infosys.com	1. Dr. Ema, Anna University Chennai, umaramesh@auist.net	1. Dr. G. Usha, SRMIST
2. Mr. Mithun, Cognizant, Mithun.SS@cognizant.com	2. Dr. Kunvar Singh, NITT Trichy, kunwar@nitt.edu	2. Dr. Usha Krithikka, SRMIST

Course Code	18CSE471T	Course Name	SOFTWARE MAINTENANCE AND ADMINISTRATION	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	
Course Offering Department	Computer Science and Engineering	Data Book / Codes/Standards			Nil

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Understand the factors that make change of existing systems both technically challenging and risky, and the processes required to control change.	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Acquire a knowledge and understanding of the specific problems inherent in the reengineering and evolution of legacy software systems, and be able to apply some of the techniques that can be of use in comprehending and changing them		
CLR-3 :	Identify the specific challenges that inherent in the reengineering and evolution of data-intensive systems that are able to apply some of the techniques that can be of use in comprehending and changing them		
CLR-4 :	Evaluate and understand the specific problems inherent in the reengineering and evolution of package-based software systems, and be able to apply techniques for designing change-resistant systems from pre-packaged code.		
CLR-5 :	Analyze and apply numerous administration tools and technical concepts that relate to software administration		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	
CLO-1 :	Explain terms used in make change of existing systems both technically challenging and risky, and the processes	3 80 70	Engineering Knowledge
CLO-2 :	Incorporate a knowledge and understanding of the specific problems inherent in the reengineering and evolution of	3 85 75	Problem Analysis
CLO-3 :	Identify challenges that inherent in the reengineering and evolution of data-intensive systems that are able to apply some of the techniques	3 75 70	Design & Development
CLO-4 :	Apply techniques for designing change-resistant systems from pre-packaged code.	3 85 80	Analysis, Design, Research
CLO-5 :	Apply numerous administration tools and technical concepts that relate to software administration	3 85 75	Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Meaning of software maintenance, software change, ongoing support, economic implications of modifying software, the nomenclature and image problem	Definition, purposes and objectives	Definition for configuration management, change control,	Quality Assurance,	Analyzing system logs,
S-2	SLO-1 Software maintenance framework,	levels of reverse Engineering,	documentation	fourth generation languages,	patches,
S-3	SLO-2 Potential solutions to maintenance problem.	supports techniques, benefits	Management and organizational issues	object oriented paradigms	configuration changes
S-4	SLO-1 Maintenance process models	Reuse and reusability: Definitions,	Management responsibilities	Maintenance tools	Performing backups. Installing
					Configuring new hardware and software.
					Adding,

	SLO-2	Definition of critical appraisal of traditional process models,				removing,
S-5	SLO-1	Maintenance process models.	objective and benefit of reuse	Enhancing maintenance productivity	Criteria for selecting tools,	resetting passwords,
	SLO-2					System performance tuning
S-6	SLO-1	Program understanding: Aims of program comprehension,	approach to reuse,	maintenance teams	taxonomy of tools,	updating user account information,
	SLO-2					
S-7	SLO-1	maintainers and their information needs	Domain Analysis,	Personnel Education and Training	Program understanding and reverse engineering testing,	Performing routine audits of systems and software
	SLO-2	comprehension process models	Components engineering,			
S-8	SLO-1	Mental models, program comprehension strategies, factors that affect understanding,	reuse process model,	Personnel Education and Training	Configuration management, and other tasks.	Performing routine audits of software
	SLO-2		Factors that impact upon reuse.			
S-9	SLO-1	implications of comprehension theories and studies	Maintenance measures, Definitions, objectives of software measurement, example measures, guidelines for selecting maintenance measures	Organization modes	Past, present and future of software maintenance	Performing routine audits of systems and software

Learning Resources	1. Armstrong A Takang and Penny A.Grubb, "Software Maintenance: concepts and Practice", International Thomson Computer press, London,2015	1. Roger S Pressman, "Software Engineering", 6th edition, Tata McGraw-Hill, 2004
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
		1. Mr.S.Selvakumara Samy., SRMIST
		2., Ms.D.Hema,SRMIST

ACADEMIC CURRICULA

Professional Elective Courses

ELECTRICAL AND ELECTRONICS ENGINEERING

Regulations - 2018



SRM INSTITUTE OF SCIENCE AND TECHNOLOGY

(Deemed to be University u/s 3 of UGC Act, 1956)

Kattankulathur, Kancheepuram, Tamil Nadu, India

Course Code	18EEE301T	Course Name	OPTIMIZATION TECHNIQUES IN POWER ELECTRONICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:	
CLR-1 :	Introduce and classify different conventional optimization techniques.		
CLR-2 :	Understand the fundamentals of genetic algorithm and to apply appropriate algorithm for Power Electronic Applications.		
CLR-3 :	Outline the concept of particle swarm optimization and apply it in Power Electronic applications.		
CLR-4 :	Introduce other modern optimization algorithms for engineering applications.		
CLR-5 :	Extend multi objective optimization techniques to Power Electronics		
CLR-6 :	Introduce the concept of optimization design for Power Electronic Applications		

Learning		
1	2	3
Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)

Program Learning Outcomes (PLO)														
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3

Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:	
CLO-1 :	Categorize optimization problems and its techniques based on constraints and variables		
CLO-2 :	Correlate Genetic algorithm with various power electronic application.		
CLO-3 :	Interpret Particle swarm optimization and develop hybrid algorithm for power electronic applications		
CLO-4 :	Gain knowledge about other modern optimization algorithms and integrate them for power electronic applications		
CLO-5 :	Formulate multi objective optimization algorithm for power electronic applications.		
CLO-6 :	Apply optimization techniques in modelling Power Electronic applications		

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Introduction to optimization	Introduction – Genetic Algorithm	Particle Swarm Optimization	Bacterial foraging-Chemotaxis, Swarming
	SLO-2	Design vector – design constraints – constraint surface	Encoding – Methods for GA	Fundamental principle	Operation of Bacterial foraging
S-2	SLO-1	objective function – objective function surfaces	Fitness function	Velocity updating in PSO -Algorithm	Bees colony algorithm-Behavior of Honey bee swarm
	SLO-2	Classification of optimization problem	Maximization & Minimization	Algorithm for PSO	Algorithm for Bee colony optimization
S-3	SLO-1	Single variable optimization - optimality conditions	Genetic operators	PSO – Parameter Selection	Differential evolution-Initialization, Mutation
	SLO-2	Single variable (unconstrained optimization) – Exhaustive search method	Crossover	Pseudocode	Recombination, Selection
S-4	SLO-1	Successive quadratic estimation method	Mutation	Implementation & Convergence issues in PSO	Ant colony optimization-Introduction
	SLO-2	Newton Raphson method	Parent Selection Roulette wheel selection	Advanced operators of PSO	Algorithm for Ant colony optimization
S-5	SLO-1	Multi variable optimization – optimality conditions (unconstrained)	Stochastic universal selection,	Meta-Optimization- Behavioral parameters	Cuckoo Search Optimization
	SLO-2	Simplex search method	Tournament selection	Algorithm for Meta-Optimization	Algorithm for Cuckoo search Optimization
S-6	SLO-1	Cauchy's method	Rank selection	Applications of PSO	Firefly optimization-Working Principle
	SLO-2	Steepest descent method	Issues in GA implementation	Harmonics Elimination in Inverters	Algorithm for Firefly optimization
S-7	SLO-1	Multivariable optimization (Constrained) Kuhn – Tucker Conditions	Applications of GA	Applications of PSO	Flower Pollination optimization-Introduction
	SLO-2	Penalty Function Method	Passive Filter design using GA	PSO for single phase PWM Inverters	Algorithm for Flower pollination optimization

S-8	SLO-1	Method of Multipliers	Parameter tuning of DC-DC converter using genetic algorithm	Control of Dc-DC converters using PSO	Grey Wolfe optimization-Introduction	Multi objective optimization of power converters (NSGA-II)
	SLO-2	Linearized search Technique – Frank Wolfe method	Tuning of PI Controllers for Power electronic converters	Feedback controller design for boost converters	Algorithm for Grey Wolfe Optimization	Algorithm for Multi objective optimization of power converters
S-9	SLO-1	Non-Linearized Search Technique – Reduced gradient method	MPPT in Renewable Energy systems	HybridofGAandPSO	Comparison of various algorithms	Multi objective optimization for design and tuning of PID controllers
	SLO-2	Quadraticprogramming	Genetic Algorithm for MPPT	Algorithm for hybrid GA and PSO for selective harmonic elimination in VSI fed drives	Benchmark functions	Algorithm for Multi objective optimization for design and tuning of PID controllers

Learning Resources	<ol style="list-style-type: none"> 1. Singiresu Rao S. <i>Engineering Optimization–Theory and Practice</i>, John Wiley & Sons, Inc., New Jersey, 2009. 2. Kalyanmoy Deb, <i>Multi-objective Optimization using Evolutionary Algorithms</i>, Wiley India Private Limited, 2010 3. Kalyanmoy Deb, <i>Optimization of Engineering Design</i>, Prentice Hall of India, second Edition, 2012. 4. Jizhong Zhou, <i>Optimization of Power System Operation</i>, IEEE Press, Second Edition, 2015. 5. Xin - She Yang, <i>Nature Inspired Optimization algorithms</i>, Elsevier, 2014. 6. Chee Peng Lim, Lakhmi C. Jain, Satchidananda Dehuri, <i>Innovations in Swarm Intelligence</i>, Springer, Berlin, Heidelberg, 2009. 7. Design of AC – DC Grid connected converter using Multi objective optimization, <i>Electrical Control & Communication Engineering</i>, 2014 8. https://engineering.purdue.edu/~sudhoff/ee630/Lecture09.pdf 9. https://link.springer.com/content/pdf/10.1007%2F978-3-540-74205-0_68.pdf
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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Mr.Muralikrishna, National Instruments, emkrishnan@gmail.com	Dr.C.Nayanatara, Sri Sairam Engineering College, nayanathara.eee@sairam.edu.in	Dr.D.Suchitra, SRMIST

Course Code	18EEE302T	Course Name	FINITE ELEMENT ANALYSIS FOR ELECTRICAL MACHINES	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Illustrate the basic concepts of CAD and its design consideration	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Derive the output equation of DC and AC machines	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Compute the torque and force for rotating and linear actuators																		
CLR-4 :	Analyze the finite element method in solving electromagnetic field problem																		
CLR-5 :	Enumerate the design concept of CAD in mathematical modelling																		
CLR-6 :	Build the models of electrical machines																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Understand the basic design of electrical machines and the need for CAD	1	75	75	H	M	M	-	-	-	-	-	-	-	-	-	H	M	-
CLO-2 :	Make use of output equation for calculate main dimension of DC and AC machines	2	75	75	H	H	M	M	-	-	-	-	-	-	-	-	M	M	-
CLO-3 :	Deduce the electromagnetic field equations for actuators	3	75	75	H	H	H	M	-	-	-	-	-	-	-	-	H	M	-
CLO-4 :	Examine the mathematical and physical basis of finite element method	3	75	75	H	M	H	M	-	-	-	-	-	-	-	-	H	H	-
CLO-5 :	Apply the design concept of CAD in mathematical modelling	3	75	75	H	H	M	M	M	-	-	-	-	-	-	-	H	M	-
CLO-6 :	Develop the models of switched reluctance motor and rotating actuators	3	75	75	H	H	M	M	M	-	-	-	-	-	-	-	H	M	-

Duration (hour)	9	9	9	9	9
S-1	SLO-1 CAD and its objectives	Maxwell's Equations	Finite element method	Organization of CAD package	model building
	SLO-2 Conventional design procedure of machines	integral form and differential form	Assumptions in FEM	Pre-processor	modeling flowchart
S-2	SLO-1 Output equation of DC machines.	Significance of field equations,	Electromagnetic field equations in Finite element	solver	geometric modeling, drawing edges
	SLO-2 Specific loading values for DC machines	electromagnetic equation-integral and differential form	Finite difference method	post-processor in CAD package	creating surface and creating components
S-3	SLO-1 output equation of AC machines	Magnetic vector potential	Finite difference method for calculation of magnetic field in a linear medium	Applications of finite element analysis	selecting edges surfaces and components
	SLO-2 Specific loading values for AC machines	scalar potential form	Assumptions in linear medium	Considerations in problem modeling	positioning the construction slice materials
S-4	SLO-1 Factors affecting the size of rotating machines	Energy stored in electromagnetic field	Finite difference method for calculation of magnetic field in a non-linear medium	stator and rotor model	boundary condition
	SLO-2 Specific loadings and its dependent factors	Energy stored in current carrying coil	Assumptions in non-linear medium	model replication and air gap discretisation	model solving
S-5	SLO-1 Variation of output and losses with dimension	Energy functional	Stiffness matrix	Post-processing of results-flux and flux linkage	Meshing: 2-D and 3-D
	SLO-2 Separation of main dimensions	Assumptions in energy functional	FEM and FDM functions	Numerical and graphical results using processors	finite element mesh
S-6	SLO-1 Limitations of conventional methods of design	Electromechanical energy conversion	FEM-mathematical basis	Analytical calculation	Design of C-cored coil with rotating actuator
	SLO-2 Need for field analysis based design	Classification of electromechanical energy conversion	FEM- physical basis	Terminal inductance calculation.	Geometric modeling of C-core
S-7	SLO-1 Outline of finite element analysis	Force and torque calculation from energy	Energy functional	Co-energy calculation.	Design of doubly excited rotating actuator
	SLO-2 Necessity of FEA	Force and torque calculation from co-energy	Non-linear energy functional	Force and torque calculation	Design procedure and its assumptions
S-8	SLO-1 Computers in finite element analysis	singly excited linear and rotating actuator	discretization	virtual work method	Design procedure of SRM
	SLO-2 Graphical users of FEA	doubly excited rotating actuator	shape function	Maxwell's stress tensor method	Geometric modeling

S-9	SLO-1	Engineering Optimisation	Force calculation on a current carrying conductor	Shape triangle calculation	Bil method	Material assigning
	SLO-2	Optimisation Methodology	torque calculation on a current carrying conductor	Comparison of Finite difference and finite element method	Boundary conditions	Design of Switched reluctance motor by CAD package

Learning Resources	1. Silvester and Ferrari, <i>Finite Elements for Electrical Engineers</i> , Cambridge University press, 2012.	3. S. Salon, <i>Finite Element Analysis of Electrical Machines</i> , springer, 1995.
	2. S.R.H. Hoole, <i>Computer - Aided, Analysis and Design of Electromagnetic Devices</i> , Elsevier, New York, Amsterdam, London, 1989.	4. Nicola Bianchi, <i>Electrical Machine Analysis Using Finite Elements</i> , 1st Edition, CRC Press, 2005. 5. https://www.classcentral.com/course/edx-finite-element-method-fem-analysis-and-applications-4064

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. Bhaskarsahu, Schneider Electric Ltd, Bhaskar.sahu@schneider-electric.com	1. Dr. K. S. Swarup, IITM, ksswarup@iitm.ac.in	1. Dr. M. Arun Noyal Doss, SRMIST
2. Mr. A.Kannan, Seshasayee paper and board limited akannan@sbppapers.com	2. Dr. R.Ramesh, CEG, rramesh@annauniv.edu	2. Dr. C. Subramani, SRMIST

Course Code	18EEE303T	Course Name	POWER CONVERTER ANALYSIS AND DESIGN	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18EEEC302J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	1	2	3	Program Learning Outcomes (PLO)														
CLR-1 :	Enrich the knowledge on design aspects of phase controlled converters	Level of Thinking (Bloom)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Acquire knowledge in DC-DC converters and its performance	Expected Proficiency (%)				Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Standards & Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Enrich the knowledge of flyback back converter and its design	Expected Attainment (%)				H	H	M	M	H	-	-	-	-	-	-	-	M	H	-
CLR-4 :	Acquire knowledge on the design techniques of the inverters					H	H	M	M	H	-	-	-	-	-	-	-	M	H	-
CLR-5 :	Understand the concept of resonant converters and role of reactive elements in UPS					H	H	M	M	H	-	-	-	-	-	-	-	M	H	-
CLR-6 :	Gain knowledge on power converter analysis and design					H	H	M	M	H	-	-	-	-	-	-	-	M	H	-

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLO-1 :	Design single phase and three phase rectifiers	Expected Proficiency (%)	3	75	75	H	H	M	M	H	-	-	-	-	-	-	-	M	H	-
CLO-2 :	Understand the analysis and design aspects of DC-DC converters	Expected Attainment (%)	3	75	75	H	H	M	M	H	-	-	-	-	-	-	-	M	H	-
CLO-3 :	Design flyback back converter and its various topologies		3	75	75	H	H	M	M	H	-	-	-	-	-	-	-	M	H	-
CLO-4 :	Design the inverter for various applications		3	75	75	H	H	M	M	H	-	-	-	-	-	-	-	M	H	-
CLO-5 :	Apply the knowledge on design concepts of resonant converters and UPS		3	75	75	H	H	M	M	H	-	-	-	-	-	-	-	M	H	-
CLO-6 :	Analyze and Design power converters		3	75	75	H	H	M	M	H	-	-	-	-	-	-	-	M	H	-

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Introduction to single phase controlled converter (rectifier)	Introduction to isolated and non isolated DC-DC converters.	Introduction - Linear versus switch mode power supplies.	Introduction to inverters for single phase application
	SLO-2	Working principle of single phase full converter	Principles of step down converters and step up converters	Functional circuit blocks of an offline switches	Introduction to inverters for three phase application
S-2	SLO-1	Analysis of single phase controlled rectifier for R load	Introduction to buck , boost converters	Classification of Basics switch mode DC-DC converters:	Selection of switching devices
	SLO-2	Analysis of single phase controlled rectifier for RLload and RLE load	Buck boost converters	Switch mode DC-DC converters: Operating principles	Introduction to IPM modules
S-3	SLO-1	Introduction to three phase controlled converters	Analysis of Buck converter	Flyback converters: operating principle	PWM techniques for inverter
	SLO-2	Operation & principle of three phase controlled rectifier	Buck converter Design	Forward Converter: operating principle	Impact of PWM techniques on inverter performance
S-4	SLO-1	Analysis of three phase controlled rectifier for R Load	Analysis of boost converter	Half-Bridge converters and, SMPS : Operating principle	Protection circuits for switches
	SLO-2	Analysis of three phase controlled rectifier for RL Load	Boost converter design	Full Bridge Converters : operating principle	Snubber circuit design
S-5	SLO-1	Selection of converter components for specified load	Analysis of buck-boost converter	Push-Pull Converter and its working	Thermal design considerations
	SLO-2	Design of filter circuit for single phase controlled rectifier	Buck-Boost converter design	SMPS with multiple outputs	Heat sink design
S-6	SLO-1	Design of filter circuit-three phase converter	Introduction to SEPIC converter	Magnetic design: Properties of magnetic cores	Multilevel Inverter(MLI) concept
	SLO-2	Importance of driver circuits	Introduction to CUK converter	High frequency inductor and transformer design	Classification of MLI
S-7	SLO-1	Pulse generation circuits	Analysis of SEPIC converter	Selection of output filter capacitor	Design of MLI

	SLO-2	Design of driver circuits	Analysis of CUK converter	Selection of switches	Pulse Width Modulation for MLI	current filter, DC filters
S-8	SLO-1	Power factor study – Improvement techniques	Thermal design: temperature control	Snubber circuit design	Influence of PWM on inverter performance	Design of inductor and transformé of power electronic applications
	SLO-2	Harmonic analysis study	Heat sink design	Design of driver circuits.	PWM for low inverter loss	Selection of capacitors.
S-9	SLO-1	Simulation of fully controlled converters	Simulation of basic DC- DC converters	Simulation of isolated dc dc converter	Simulation of a typical three phase inverter	Simulation of resonant and quasi resonant converter
	SLO-2	Demonstration of a fully controlled converter for R , RL loads	Demonstration of DC DC converters	Demonstration on Closed Loop Control of SMPS	Demonstration on a three phase inverter	Demonstration of resonant converters

Learning Resources	1.	Robert W. Erickson and Dragan Maksimovic, Fundamentals of Power Electronics, 3 rd Ed., Springer (India) Pvt. Ltd., 2011.	5.	Umanand L and Bhatt S R, Design of Magnetic Components for Switched Mode Power Converters, Wiley Eastern Publication, 2009.
	2.	Abraham I. Pressman, Keith Billings, and Taylor Morey, Switching Power Supply Design, 3 rd Ed., McGraw-Hill Professional, 1 May 2009	6.	Ned Mohan, Tore M. Undeland, William P. Robbins, Power Electronics Converters, Applications, and Design", 3 rd Edition, Wiley India Pvt Ltd, 2010.
	3.	Rashid M.H., Power Electronics Circuits, Devices and Applications, Prentice Hall India, Third Edition, New Delhi, 2004.	7.	Simon Ang, Alejandro Oliva, Power-Switching Converters, Second Edition, CRC Press, Taylor & Francis Group, 2010
	4.	V. Ramanarayanan, Switched Mode Power Conversion, 2007	8.	https://nptel.ac.in/courses/108108036/

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.Muralikrishna, National Instruments, emkkrishnan@gmail.com	1. Dr. Chandrasekaran Subramanian , NIT Hamirpur, chandru@nith.ac.in	1.Dr. R. Sridhar, SRMIST
2. Mr.J.Sassikumar, Philips India Pvt Ltd, sassikumar.ji@gmail.com	2.Dr.R.Ramesh, CEG, rramesh@annauniv.edu	2. Dr. K. Mohanraj, SRMIST

Course Code	18EEE304T	Course Name	SWITCHED MODE POWER CONVERSION	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18EEEC302J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:		
CLR-1 :	Review the basics of the power semiconductor devices and their requirements for the design of SMPC.			
CLR-2 :	Explain the advantage of Switched mode Power supply over linear power Supply and the design of basic switched mode DC-DC converters.			
CLR-3 :	Illustrate the need of derived / isolated converters and the working of various types of derived converters.			
CLR-4 :	Introduce the control and compensating schemes for the design of SMPS and the procedure to be followed in the design of magnetic components.			
CLR-5 :	Demonstrate the use of resonant converters to implement the Zero voltage and Zero current switching concepts.			
CLR-6 :	Learn the basics and steady state operation of efficient switched mode power conversion and control techniques, including component design.			

Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:		
CLO-1 :	Determine the selection criteria of power semiconductor devices, evaluation of losses and their basic heat sink design.			
CLO-2 :	Design the basic switched-mode converters for the given design specifications.			
CLO-3 :	Understand the steady state analysis and working of the Derived DC-DC isolated Converters.			
CLO-4 :	Analyze of Control and Compensating network for SMPS, design high frequency inductor and transformers to be used with SMPS.			
CLO-5 :	Analyze the working principle of resonant converters and understand the importance of Zero voltage and Zero current switching.			
CLO-6 :	Become proficient with the analysis and design of Switched-Mode Converters, including selection of components based on the specification.			

Learning		
1	2	3
Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)

Program Learning Outcomes (PLO)														
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3

H	-	-	-	-	-	-	-	-	-	-	-	M	H	-
H	M	M	L	-	-	-	-	-	-	-	-	M	H	-
H	M	M	L	-	-	-	-	-	M	-	-	M	H	-
H	M	M	L	-	-	-	-	-	M	-	-	M	H	-
H	M	M	L	-	-	-	-	-	M	-	-	M	H	-
H	M	M	L	-	-	-	-	-	M	-	-	M	H	-

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction to switched mode power conversion	Basic concepts of Switched Mode power converters.	DC-DC converters with isolation.	Reactive elements in Power Electronic Systems	Basic resonant circuit concepts
	SLO-2	Industrial relevance of switched mode power conversion	Generalized comparison between switched mode and linear voltage regulator.	Requirement for isolation in the switch-mode converters	Design constraints of reactive elements in Power Electronic Systems	SMPS using resonant circuit
S-2	SLO-1	Requirements of power conversion system	DC-DC converters circuit elements, operating principles	Power circuit of flyback converters	Design of inductor, transformer and capacitors for power electronic applications	Resonant switch converters – Introduction
	SLO-2	Requirements of high performance modern power conversion system	DC-DC converters Characteristics	Steady-state analysis of flyback converters	Filter inductor design constraints, Transformer design constraints	Resonant switch converters – principle of operation
S-3	SLO-1	Review of power diodes, Schottky diodes, power MOSFETs & IGBTs	Operation and steady state performance of Buck Converter in continuous-conduction mode (CCM)	Power circuit of push-pull converters	Modeling of power converters	Buck converter with zero current switching
	SLO-2	Introduction to power semiconductor devices for SMPS	Buck converter - Discontinuous-conduction mode (DCM) and boundary between CCM and DCM operation	Steady-state analysis of push-pull converters	Generalized State Space Model of the switching power converter	Steady state conversion ratio – Buck converters
S-4	SLO-1	Recent developments in power devices	Operation and steady state performance of Boost Converter in continuous-conduction mode (CCM)	Power circuit of forward converters	Transfer Function of switching power converters	Boost converter with zero voltage switching

	SLO-2	New devices: GaN & SiC for switch mode power supplies	Boost converter - Discontinuous-conduction mode (DCM) and boundary between CCM and DCM operation	Steady-state analysis of forward converters	EMI and filter design problem	Steady state conversion ratio – Boost converters
S-5	SLO-1	Gate drive basics	Operation and steady state performance of Buck - Boost Converter in continuous-conduction mode (CCM)	Power circuit and steady-state analysis of half-bridge DC-DC converters	Closed loop control of switching power converters	Series resonant DC-DC converters – principle
	SLO-2	Gate drive requirements	Buck - Boost Converter Discontinuous-mode (DCM) and boundary between CCM and DCM operation	Power circuit and steady-state analysis of full bridge DC-DC converters	Selection of controller parameters for converters	Series resonant DC-DC converters – Analysis and operation
S-6	SLO-1	Switching performance and snubber design	Operation and performance of Cuk Converters	Magnetic circuits in isolated topologies	Feedback compensators for converters	Parallel resonant DC-DC converters – principle
	SLO-2	Turn-on and Turn-off snubber	Operation and performance of SEPIC Converters	Utilization of Magnetic circuits in isolated topologies	Design of feedback compensators	Parallel resonant DC-DC converters – Analysis and operation
S-7	SLO-1	Selection of devices	Inductors current ripple design considerations	Comparison of different isolated topologies	Effect of parasitics on the switching converter design	Resonant DC link converters – principle
	SLO-2	Basic heat sink design for the devices	Output voltage ripple design considerations	Selection criteria of different isolated topologies	Stray inductance and inductive coupling effects	Resonant DC link converters – Analysis and operation
S-8	SLO-1	Sources of losses in SMPS	Effect of parasitic elements	Recent advancements of DC –DC converters (current mode, voltage mode)	Digital Control of power converter	Comparison of resonant converter configurations
	SLO-2	Conduction/Switching losses	Choice of switching frequency	Recent advancements of DC –DC converters (multiple output, high frequency output)	Quantization issues in digitally controlled power converters	Selection criteria of resonant converter configurations
S-9	SLO-1	Losses and efficiency in converters	Comparisons of DC –DC converter configurations	Applications of DC-DC converters	Practical issues in controller design	Applications of Resonant converters
	SLO-2	Realistic converter models	Selection criteria of DC –DC converter configurations	Seminar on Recent advancements and applications of DC –DC converters	Seminar on practical issues in controller design for power converters	Seminar on recent advancements and applications of Resonant converters

Learning Resources	1. Ned Mohan, Tore M. Undeland, William P. Robbins, Power Electronics Converters, Applications, and Design, 3rd Edition, Wiley India Pvt Ltd, 2010.	3. Umanand L and Bhatt S R, Design of Magnetic Components for Switched Mode Power Converters, Wiley Eastern Publication, 2009.
	2. Abraham I. Pressman, Keith Billings, and Taylor Morey, Switching Power Supply Design, 3rd Ed., McGraw-Hill Professional, 1 May 2009.	4. S.N.Singh, Electric power generation, transmission and distribution, 2 nd ed., PHI, 2011 5. https://nptel.ac.in/courses/108108036/

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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2.Jidhun K Murali, Project Engineer, CDAC, Trivandrum, jidhunkm@gmail.com	2. Dr. A. Venkadesan, NIT Puducherry, venkadesan@nitpy.ac.in	2.Dr R Sridhar, SRMIST

Course Code	18EEE305T	Course Name	DESIGN OF ELECTRICAL MACHINES	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18EEEC204J, 18EEEC205J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Enrich the students with basic principles and characteristics of various types of electrical machines.	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Examine the design of armature and field systems for D.C. machines.		
CLR-3 :	Outline the core, windings and cooling systems of transformers		
CLR-4 :	Analyze the design of stator and rotor of induction machines		
CLR-5 :	Understand the design of stator and rotor of synchronous machines and study their thermal behavior.		
CLR-6 :	Understand the overall design of electrical machines		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Engineering Knowledge
CLO-1 :	Understand the mmf calculation and thermal rating of various types of electrical machines.	2 80 75	H H H H L - - L - - - - - M M L
CLO-2 :	Design DC machine parts such as armature, field, commutator and brushes.	3 80 75	H H H H L - - - - - M M -
CLO-3 :	Acquire knowledge on the design of transformers and its operating characteristics.	3 80 75	H H H H L - - - - - M M -
CLO-4 :	Interpret the induction motor stator and rotor design equations and magnetic leakage calculations.	3 80 75	H H H M L - - - - - M M -
CLO-5 :	Design the components of synchronous motor	3 80 75	H H H H L - - - - - M M -
CLO-6 :	Design the components of DC and AC machines	3 80 75	H H H H L - - L - - - - M M L

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Major considerations, Design factors and limitations in machine design	Output Equation of DC machine	kVA output for single transformers	Output equation of three phase induction motor
	SLO-2	Limitations in machine design	Classification of magnetic materials	kVA output for three phase transformers	Output equation of synchronous machine
S-2	SLO-1	Electrical Engineering Materials introduction	Choice of Specific Electric Loading	Window space factor	Main dimensions of induction motor
	SLO-2	Electrical Engineering Materials classification	Choice of Specific Magnetic Loading	Core area factor	Main dimensions and pole constructions in synchronous machine
S-3	SLO-1	Magnetic Circuits Calculations	Problems with main dimensions	Design problems of core dimension for single phase transformer	Choice of Specific Electric and Magnetic Loading
	SLO-2	Problems under MMF Calculation	Problems with specific loading	Design problems of window dimension for single phase transformer	Influence of runaway speed
S-4	SLO-1	Carter's Coefficient and net length of iron	Selection of number of poles	Design of core and winding	Problems in main dimensions including runaway speed
	SLO-2	Problems under net length of Iron	Design problems including pole design	design problems in core and winding	Problems in main dimensions including pole constructions
S-5	SLO-1	Real and Apparent flux densities	Armature Design procedure	Design of three phase transformer winding	Short Circuit Ratio (SCR) and Effect of SCR on machine performance
	SLO-2	Problems based on real and apparent flux densities	Problems in designing of armature	Problems on three phase transformer design	Design problems including air gap length
S-6	SLO-1	Temperature gradients in cores and conductors	Design of Commutator	Temperature rise in Transformers	Estimation of length of air gap
	SLO-2	Thermal resistivity of winding	Design of brushes	Transformer Tank design Procedure	Design procedure of rotor bars, slots and end ring
					Design procedure of slots
					Design procedure of end ring
					Problems in MMF
					Problems in SCR and air gap length
					Armature design in synchronous machine
					Problems in armature design

S-7	SLO-1	Problems in temperature gradients	Problems in designing of commutator	Transformer Cooling tube design Procedure	Design problems in squirrel cage rotor	Procedure for Estimation of air gap length
	SLO-2	Problems in thermal resistivity	Problems in designing of brushes	Transformer Cooling tube design problems	Design procedure for wound rotor	Problems in air gap length
S-8	SLO-1	Indian Standard Specification for conductor, transformer	Computer Aided Design of DC machines – Main dimensions	Computer Aided Design of transformer- Core design	Computer Aided Design of three phase induction motor – Main dimension, stator design, squirrel cage rotor design	Overall design of stator
	SLO-2	International Electro- Technical commission Publications 34-1, 34-2	Computer Aided Design of DC machines – number of poles	Computer Aided Design of transformer- winding design	Computer Aided Design of three phase induction motor – squirrel cage rotor design	Overall design of rotor
S-9	SLO-1	Computer Aided Design introduction and uses	CAD – Armature design	CAD – Tank design	Design practices with software tools for stator design	CAD – Stator design
	SLO-2	Different approaches in Computer Aided Design	CAD – Field design	CAD – Cooling tube design	Design practices with software tools for rotor design	CAD – Rotor design

Learning Resources	1. Sawhney, A.K., A Course in Electrical Machine Design, Dhanpat Rai & Sons, New Delhi, 1984.	3. Sen, S.K., Principles of Electrical Machine Designs with Computer Programmes, Oxford and IBH Publishing Co. Pvt. Ltd., New Delhi, 1987.
	2. Deshpande, M. V., Design and Testing of Electrical Machine Design, Wheeler Publications, 2010	4. https://ocw.mit.edu/courses/electrical-engineering-and-computer-science/6-685-electric-machines-fall-2013/

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Evaluate Create	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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2. Mr.Muralikrishna, National Instruments, emkrishnan@gmail.com	2. Dr. A. Venkadesan, NIT Puducherry, venkadesan@nitpy.ac.in	2. Dr. Arun Noyal Doss, SRMIST

Course Code	18EEE306T	Course Name	SPECIAL ELECTRICAL MACHINES	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1:	Acquire knowledge on Stepper motor and its characteristics	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2:	Understand the concepts of switched reluctance motor and its control.	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3:	Gain knowledge on Permanent magnet DC and BLDC Motors	Expected Proficiency (%)	Problem Analysis
CLR-4:	Analyze the working principle, operation and control of permanent magnet synchronous motor	Expected Attainment (%)	Design & Development
CLR-5:	Gain knowledge on the basics of various application based motors		Analysis, Design, Research
CLR-6:	Understand the overall concepts of various special electrical machines		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1:	Analyze the working and control of Stepper motor	3 75 75	H M - - - - - - - - - - H H -
CLO-2:	Illustrate the operation and characteristics of SRM	2 75 75	H - - - - - - - - - - L L -
CLO-3:	Interpret knowledge on PMDC and BLDC motors for real time applications.	2 75 75	H - - - - - - - - - - L L -
CLO-4:	Evaluate the performance of PMSM	3 75 75	H M - - M - - - - - H H -
CLO-5:	Understand the characteristics of application based motors	2 75 75	H - - - - - - - - - - L L -
CLO-6:	Summarize the characteristics of various special electrical machines.	2 75 75	H M - - M - - - - - M -

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Introduction to Stepper motor	Introduction to Switched reluctance motor.	Construction of PMDC motor	Construction, and types of PMSM	Construction of repulsion motors
	SLO-2 Variable reluctance motor-Construction-Single Stack	Elementary operation of SRM	Principle of Working PMDC motor	Operation of PMSM	working and types of repulsion motors
S-2	SLO-1 Single Stack-Modes of Excitation-single phase	Machine topology	Moving Coil motors	EMF equation of PMSM	Torque equation of repulsion motor
	SLO-2 Half Step On mode	Operation of Linear SRM	Printed coil motors	Torque equation of PMSM	Phasor diagram of repulsion motor
S-3	SLO-1 Multi Stack Motor-Construction	Non Linear Analysis of SRM	Shell type motor	Voltage equation of PMSM	Characteristics of repulsion motor
	SLO-2 Modes of Excitation	Torque Production -SRM	BRUSHLESS –Classification of BLDC motor	Phasor diagram	Applications of repulsion motor
S-4	SLO-1 Hybrid stepper Motor-construction-working	Voltage and torque equation of SRM	Construction and operation of BLDC MOTOR	Performance Characteristics Characteristics of PMSM	Universal motor-construction and operation
	SLO-2 Types of Stepper motors-single phase stepper motor-Disc magnet type-Claw tooth stepper motor	Converter Circuit For SRM With Bifilar Winding	Equivalent Circuit And Torque Equation	Control of PMSM-Vector control	Speed control of universal motor
S-5	SLO-1 Torque Equation Of stepper Motor	Split Link Circuit -SRM	Performance Characteristics of BLDC motor	Self control of PMSM	Linear induction motor – construction
	SLO-2 Windings in stepper motor-Unipolar and Bipolar winding	C- Dump Circuit-SRM	BRUSHLESS –Classification of BLDC motor	Microprocessor based control of PMSM	Equivalent Circuit of LIM
S-6	SLO-1 Static Characteristics of stepper Motor	Converter topology - N + 1, (N + 1) diodes	Construction and operation of BLDC MOTOR	Sensorless control of PMSM	characteristics of LIM
	SLO-2 Dynamic Characteristics of stepper Motor	Control Of SRM -Rotor Position Sensor-Optical Position	Electronic commutation -180° with magnetic arc and 120° with square wave phase currents -star connection	POWER controllers - PMSM	Control of Linear Induction Motor
S-7	SLO-1 Open loop Control of Stepper motors	Hall Effect Sensing	Electronic commutation -180° with square wave phase currents and 120° with magnetic arc -Delta connection	Operation of PMSM using DC-AC Converter with 120° Mode	Linear Reluctance motor- Construction

	SLO-2	Closed loop Control of Stepper motors	Current Regulators-Hysteresis	Control of BLDC motor	Operation of PMSM using DC-AC Converter with 180° Mode	Linear Reluctance motor – working Principle
S-8	SLO-1	Microprocessor –based control of stepper motor	Voltage –PWM type regulators	Microprocessor based control of BLDC motor	Modelling of PMSM Using simulators tool	, Linear Reluctance motor Applications
	SLO-2	Problem Solving- torque- stepper motor	Microprocessor Based Control Of SRM	Comparison-Conventional and BLDC	Problem Solving - torque-PMSM	Ac Servo motors
S-9	SLO-1	Problem Solving- step angle-stepper motor	Advantages of SRM over other machines	Sensor-less Control of BLDC Motors	Problem Solving - speed- PMSM	Construction and Working
	SLO-2	Applications of Stepper Motors	, Applications of SRM motors	Applications of BLDC Motors	Applications of PMSM	Torque speed characteristics of servomotor

Learning Resources	1. T.J.E. Miller, <i>Permanent Magnet and Reluctance Motor Drives</i> , Clarendon Press, Oxford. 2. T. Kenjo, <i>Stepping Motors and Their Microprocessor Controls</i> , Clarendon Press London, 2000. 3. R.Krishnan, <i>Switched Reluctance Motor Drives – Modeling, Simulation, Analysis, Design and Application</i> , CRC Press, New York, 2005.	4. P.P. Acarnley, <i>Stepping Motors – A Guide to Motor Theory and Practice</i> , Peter Perengrinus London, 4 th edition 2001. 5. D.P.Kothari and I.J.Nagrath, <i>Electric machines</i> , Tata Mc Graw hill publishing company, New Delhi, Third Edition, 2004. 6. https://www.coursera.org/learn/motors-circuits-design
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. M.Jayakumar, Danfoss, Industries Pvt Ltd., jaya.kumar@danfoss.com	1. Dr Bindu G R, Government College of Engineering, Kerala, bgr100@gmail.com	1. Ms. S.Vijayalakshmi, SRMIST
2. Mr. A.Kannan, Seshasayee paper and board limited akannan@sbppapers.com	2. Dr.Booma.N, Jerusalem College of Engineering, Chennai, booma_nagarajan@yahoo.com	2. Dr.ArunNoyal Doss, SRMIST

Course Code	18EEE401T	Course Name	SOLID STATE DRIVES	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18EEEC302J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Understand the basics of electric drives	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Explain the working of converter/ chopper fed DC drives	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Design controllers for closed loop operation of DC motor drive	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Acquire knowledge on operation and performance of induction motor drives	Expected Attainment (%)	Design & Development
CLR-5 :	Enumerate the different control strategies of synchronous motor drive		Analysis, Design, Research
CLR-6 :	Expose the students to various power converters associated with DC and AC drives		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Enrich the basics of electric drives, multi-quadrant operation	2 75 75	H M M - - - - - - - - - - M M -
CLO-2 :	Study and analyze the operation of four quadrant chopper / rectifier and solve simple problems	3 75 75	H M M M M - - - - - - - - - - M M -
CLO-3 :	Model closed loop DC motor drive and design the current and speed controllers	3 75 75	H M M M M - - - - - - - - - - M M -
CLO-4 :	Analyze the power electronic converter used for the speed control of induction motor drives	3 75 75	H M M M M - - - - - - - - - - M M -
CLO-5 :	Analyze the various control schemes for the speed control of synchronous motor drives	3 75 75	H M M M M - - - - - - - - - - M M -
CLO-6 :	Analyse the operation of DC and AC drives	3 75 75	H M M M M - - - - - - - - - - M M -

Duration (hour)	9	9	9	9	9
S-1	SLO-1	ElectricDrives: Classification, advantages	Review of emf, torque and speed equations	Closed loop control of DC drive	Review of induction motor torque-speed characteristic
	SLO-2	Components of electric drive	Review of torque-speed characteristics of DC machine	Separately excited DC motor transfer function	Equivalent circuit of Induction motor
S-2	SLO-1	Thermal loading	Conventional speed control techniques	Modelling closed loop speed control of DC drive using armature voltage control	Conventional speed control techniques- Stator side control
	SLO-2	Thermal model of motor for heating and cooling	Armature and field side control	Block diagram of closed loop speed control of DC drive	Rotor side control
S-3	SLO-1	Classes of duty cycle	DC chopper control strategy	Modelling closed loop speed control with inner current controller(P)	Inverter control techniques: three-phase PWM generation
	SLO-2	Determination of motor rating – Continuous and intermittent duty	Constant and variable frequency control strategies	Block diagram of closed loop speed control with inner current controller(P)	Sinusoidal modulation
S-4	SLO-1	Simple problems on power rating estimation with Continuous and intermittent duty	chopper fed dc motor for speed control- One, two quadrant operation	Modelling closed loop speed control with inner current controller(PI)	Introduction to vector control
	SLO-2	Determination of motor rating – short time duty	chopper fed dc motor for speed control- four quadrant operation	Block diagram of closed loop speed control with inner current controller(PI)	Vector control of Induction motor drives
S-5	SLO-1	Determination of motor rating – intermittent periodic duty	Harmonics and ripple in motor current	Modelling closed loop speed control of DC drive with load torque disturbance	Conventional space vector modulation.
	SLO-2	Frequency of operation subjected to intermittent loads	Effect on motor performance	Block diagram of closed loop speed control of DC drive with load torque disturbance	SVPWM for three phase VSI
S-6	SLO-1	Equations governing motor load dynamics	Single phase full converter fed separately excited DC motor	Modelling DC series motor	Introduction to FPGA
					Recap of single and three phase cycloconverters

	SLO-2	Steady state stability at various operating points on Speed – Torque curve	Steady state analysis of the drive– continuous conduction	Block diagram of DC series motor	PWM pulse generation using FPGA	Cycloconverter fed synchronous motor
S-7	SLO-1	Multi-quadrant Operation	Single phase full converter fed separately excited DC motor	System response with filters	Squirrel cage induction motor: constant V/f control of induction motor	Comparison of VSI and CSI fed drives
	SLO-2	Real time example for four quadrant operation	Steady state analysis of the drive– discontinuous conduction	Phase locked loop control	Steady-state performance analysis based on equivalent circuit.	CSIfed synchronous motor
S-8	SLO-1	Components of Load Torques	three phase full converter fed separately excited DC motor drive	Design of speed controller	Impact of rotor resistance on speed torque characteristics – rotor resistance control	Permanent magnet synchronous motor
	SLO-2	Nature and Classification of Load Torques	Steady state analysis of the drive - continuous conduction.	Simple problems	Derivation for equivalent resistance	Closed loop control of PMSM
S-9	SLO-1	Need for closed loop control	Introduction to software simulation of DC drives.	Design of current controller	slip power	Simulation of induction motor characteristics
	SLO-2	Closed loop speed control of drives	Chopper based simulation	Simple problems	slip power recovery schemes - Kramer's drive, Scherbius drive	Introduction to software simulation of AC drives.

Learning Resources	1. G.K. Dubey, <i>Fundamentals of Electrical Drives</i> , CRC Press, 2 nd edition, 2015 2. Ion Boldea, S.A. Nasar, <i>Electric Drives</i> , Third edition, CRC Press 2016. 3. R. Krishnan, <i>Electric Motor Drives: Modeling, Analysis and Control</i> , Prentice Hall, 2001 4. S.K. Pillai, <i>Analysis Of Thyristor Power-Conditioned Motors</i> , Universities press, 2005	5. G.K. Dubey, <i>Power Semiconductor Controlled Drives</i> , Prentice Hall, 1989. 6. W. Leonhard, <i>Control of Electric Drives</i> , Springer Science & Business Media, 2001. 7. P.C. Sen, <i>Thyristor DC Drives</i> , A Wiley-Interscience Publication 8. https://nptel.ac.in/courses/108104011/
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.S.Paramasivam, Danfoss, Industries Pvt Ltd., paramsathya@yahoo.com	1. Dr.R.Subha., Sir MVIT, Bangalore, subha.mvit@gmail.com	1. Ms.D.Anitha, SRMIST
2. Mr. A.Kannan, Seshasayee paper and board limited akannan@sbppapers.com (machines)	2. Dr. A. Venkadesan, NIT Puducherry, venkadesan@nitpy.ac.in	2. Dr.K.Mohanraj, SRMIST

Course Code	18EEE402T	Course Name	MODELLING AND ANALYSIS OF ELECTRICAL MACHINES	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18EEEC204J, 18EEEC205J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical & Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:		Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Illustrate the reference frame theory			1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2 :	Formulate the concept of modelling of DC machines			Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3		
CLR-3 :	Understand the theoretical model of synchronous machine						H	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLR-4 :	Derive the mathematical model of poly phase induction machines						H	H	H	M	M	-	-	-	-	-	-	-	-	-	M	H	-
CLR-5 :	Explain the generalized theory model of a single phase induction machine						H	H	H	M	H	-	-	-	-	-	-	-	-	-	M	H	-
CLR-6 :	Derive the mathematical model of DC and AC machines						H	H	H	M	H	-	-	-	-	-	-	-	-	-	M	H	-
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:		1	2	3																	
CLO-1 :	Outline the basics of rotating reference frame- synchronously and arbitrarily rotating reference frame transformation			1	75	75																	
CLO-2 :	Interpret the modelling of DC machines for dynamic and steady state operation			2	75	75																	
CLO-3 :	Construct the mathematical modelling of three phase synchronous machine			3	75	75																	
CLO-4 :	Inspect the mathematical model of poly phase induction machine for electrical simulation studies			3	75	75																	
CLO-5 :	Apply the generalized theory concept for the modelling of single phase induction machine			3	75	75																	
CLO-6 :	Develop a mathematical model of different types of DC and AC machines			3	75	75																	

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Theory of transformation	Introduction to DC machine	Introduction to Three phase synchronous machine	Three phase induction machine- Types
	SLO-2	Different reference frames	Back EMF equation	RMF, MMF waveform	MMF waveform
S-2	SLO-1	Various sign conventions	Speed, torque equations	Winding model	Equivalent circuit
	SLO-2	Reference frame transformations	Terminal voltage equations	Modelling assumptions	Winding model
S-3	SLO-1	Illustration of how a transformation can result in constant inductances	DC machine types	Sign convention	Modelling assumptions
	SLO-2	Concept of stationary reference frame	separately excited, self-excited- Equivalent circuits	Stator voltage equations in abc coordinates	Sign convention
S-4	SLO-1	Illustration of transformation of stationary circuit variables	Speed - torque characteristics	Rotor voltage equations in abc coordinates	Stator voltage equations in abc coordinates
	SLO-2	Concept of synchronously rotating reference frame	Electromechanical model of DC machine	Stator flux linkage equations in abc coordinates	Rotor voltage equations in abc coordinates, Induction machine: torque equations in abc
S-5	SLO-1	Concept of arbitrarily rotating reference frame	State equations of armature current and speed of DC motor	Rotor flux linkage equations in abc coordinates	Stator flux linkage equations in abc coordinates
	SLO-2	Transformation: stationary circuit variables to arbitrary reference frame	State-space model of DC machines	Stator self-inductance calculation	Rotor flux linkage equations in abc coordinates
S-6	SLO-1	Illustration of transformation of stationary circuit variables-Resistive elements	Transfer function model of DC machines	Stator to rotor Mutual-inductance calculation	Stator self-inductance calculation

	SLO-2	Illustration of transformation of stationary circuit variables-Inductive elements	Steady state response of DC machines	Rotor to Stator Mutual-inductance calculation	Stator to rotor and Rotor to Stator, Mutual-inductance calculation	Application of generalized theory to single-phase induction motor
S-7	SLO-1	Illustration of transformation of stationary circuit variables-Capacitive elements	Dynamic characteristics of DC machines	Rotor self –inductance calculation	Rotor self –inductance calculation	Voltage equations of single-phase induction machine
	SLO-2	Transformations between reference frames x and y	The effect on speed for simultaneous change in input voltage and load torque of DC machine	Park's transformation	Reference frame transformation	Flux linkage equations single-phase induction motor
S-8	SLO-1	Transformation of a balanced set to an arbitrarily rotating reference frame (ARF)	Calculation of efficiency and starting torque of DC separately excited machine.	Voltage equations in dqo reference frame (Park's equations)	Voltage equations in arbitrary reference frame	Torque equation of single-phase induction motor
	SLO-2	Numerical example of transformation to arbitrary reference frame	Calculation of speed of DC machine from steady state equations	Flux linkage equations in (dqo) rotor reference frame	Flux linkage equations arbitrary reference frame,	Equivalent circuit of single phase induction machine
S-9	SLO-1	Transformation to a synchronously rotating reference frame (SRF), Balanced steady-state phasor relationships	Calculation of armature torque and load torque of DC separately excited machine	Synchronous machine torque equations in abc and dq variables, Steady state equations in dq variables	Induction machine: torque equations in reference frame variable, Steady state equations in dq variables	Numerical example to illustrate steady-state computation of single phase induction machine
	SLO-2	Summary – various reference frames	Computer simulation of DC machine dynamics using transfer function	Steady State analysis of Synchronous machine using simulation software	Computer simulation of induction motor dynamics in arbitrary reference frame	Validation of single phase induction machine model using simulation software

Learning Resources	1. Paul C. Krause, Oleg Wasykczuk, Scott D. Sudhoff, Analysis of Electric Machinery and Drive Systems, IEEE Press, Third Edition, 2013.	4. R. Krishnan, Electric Motor Drives: Modelling, Analysis and Control, Prentice Hall of India, 2002.
	2. R. Ramanujam, Modeling & Analysis of electrical machines. "Ic International Publishing House, New Delhi, 2018.	5. Ned Mohan. Advanced electric drives: analysis, control, and modeling using MATLAB/Simulink, John Wiley & sons; 2014.
	3. P. S. Bimbhra, Generalized theory of Electrical Machines, Khanna Publishers, Sixth Edition, 1995.	6. Bernard Adkins, The General Theory of Electrical Machines, Imperial College of Science and Technology, 1974.
		7. https://nptel.ac.in/courses/108106023/

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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2.Dr.V.P.Boopathi, Powersys., Chennai, Boopathivp@gmail.com	2.Prof. R.P.Kumudini Devi, Anna University, kumudini@annauniv.ac.in	2. Dr. M. Arun Noyal Doss. SRMIST

Course Code	18EEE403T	Course Name	HYBRID ELECTRIC VEHICLES	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical & Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Classify the various types of EVs and the power flow involved	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Explain and analyze the storage and battery technologies in EVs	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Discuss and design the various power electronic (PE) topologies involved in EVs																		
CLR-4 :	Analyze the machines and its drives for the propulsion of EVs																		
CLR-5 :	Explain the emerging technologies in EVs																		
CLR-6 :	Create an EV with new and advanced PE topologies and storage systems																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Infer knowledge about the basics of power flow in electric vehicles	2	75	75	H	L	L	-	-	-	-	-	-	-	-	-	-	H	-
CLO-2 :	Understand and model a battery energy storage system for EV	2	75	75	H	L	M	M	M	-	-	-	-	-	-	-	M	H	L
CLO-3 :	Acquire knowledge and develop the various PE converters involved in EV	3	75	75	H	M	M	M	M	-	-	-	L	-	-	-	M	H	-
CLO-4 :	Analyze the various machines and drives involved in EVs	3	75	75	H	M	L	L	M	-	-	-	M	-	-	-	M	H	-
CLO-5 :	Design and describe the future enhancement in EVs	3	75	75	H	M	M	M	M	L	L	-	M	-	-	-	H	H	L
CLO-6 :	Develop an EV with batteries, new PE topologies and drives	3	75	75	H	M	M	M	M	L	L	-	M	-	-	-	H	M	L

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Introduction to Electric Vehicles	Introduction to Energy Storage system	Introduction to charging and requirements of a charging system	Introduction to starting system
	SLO-2	History of electric vehicles and hybrid electric vehicles	Battery Requirements for HEVs, PHEVs, and EVs.	Principles of charging system	Requirements of a starting system
S-2	SLO-1	Social and environmental importance of hybrid and electric vehicles	Types of batteries	Alternators and charging circuits	Principles of starting system
	SLO-2	Key challenges of hybrid and electric vehicles	Battery characterization	Diagnosing charging system faults	Various drive system for the transmission of EV
S-3	SLO-1	Basics of EV	Working principle and construction of lead-acid battery	Rectifiers/Inverters for HEV	DC/DC chopper based two, four quadrant operations of DC drives - Configuration
	SLO-2	Basics of HEV, PHEV	Working principle and construction of nickel cadmium battery	Battery chargers: High frequency transformer based bidirectional DC-DC converter	DC/DC chopper based two, four quadrant operations of DC drives - Control
S-4	SLO-1	Concept of EV	Working principle and construction of nickel metal hydride battery	Isolated bidirectional DC-DC converter	Inverter based V/f Operation (motoring and braking) of induction motor drive system - Configuration
	SLO-2	Configurations of EV	Working principle and construction of lithium ion battery	Half bridge DC-DC converter	Inverter based V/f Operation (motoring and braking) of induction motor drive system - Control
S-5	SLO-1	Concept of Series HEV	Diagnosing battery faults.	Full bridge DC-DC converter	Permanent magnet motor based vector control operation – Configuration
	SLO-2	Configurations of Series HEV	Basic battery modeling: Static and dynamic electric circuit model	Four quadrant operation of DC-DC converter	Permanent magnet motor based vector control operation –Control
S-6	SLO-1	Concept of Parallel HEV	Battery charging control	Flyback converter	SRM drives – Configuration

	SLO-2	Configurations of Parallel HEV (Mechanical Coupling)	Battery charging control	Cell balancing converters: Active and Passive balancing methods	SRM drives – Converter and modes of operation	Smart grid technologies: Applications and Benefits
S-7	SLO-1	Configurations of Parallel HEV (Torque Coupling)	Ultra-capacitor: Symmetrical and asymmetrical – Introduction and Operation	Wireless Charging – Inductive Charging	Types of starters for motors in EV	Smart meter
	SLO-2	Configurations of Parallel HEV (Speed Coupling)	Ultra-capacitor modeling	Wireless Charging – Conductive Charging	Diagnosing starter faults	Smart meter: Purpose and benefits
S-8	SLO-1	Power train components	Operation of flywheel and fuel cell	Advanced charging system technology	Advanced starting system technology	Smart charger
	SLO-2	Vehicle model	Operation of hydraulic energy storage system	New developments in charging systems	New developments in starting systems	Smart charger: Purpose and benefits
S-9	SLO-1	EV power train component sizing	Simulation of battery model	Simulation of any PE converter for EV	Simulation and implementation of PE converter fed drives for EVs	Technical talk on any new emerging trend in EVs
	SLO-2	EV power train component sizing	Simulation of ultra-capacitor model	Simulation of any PE converter for EV	Simulation and implementation of PE converter fed drives for EVs	Technical talk on any new emerging trend in EVs

Learning Resources	<ol style="list-style-type: none"> 1. M. Ehsani, Y. GAO, and A. Emadi, <i>Modern Electric, Hybrid Electric, and Fuel Cell Vehicles: Fundamentals, Theory, and Design</i>, Second Edition, CRC Press, ISBN: 978-1-4200-5398-2, Aug. 2009. 2. Iqbal Hussain, <i>Electric & Hybrid Vehicles – Design Fundamentals</i>, Second Edition, CRC Press, 2011. 3. Sheldon S. Williamson, <i>Energy Management Strategies for Electric and Plug-in Hybrid Electric Vehicles</i>, Springer, 2013. 4. Chris Mi, M. AbulMasrur, David Wenzhong Gao, <i>Hybrid Electric Vehicles Principles and Applications With Practical Perspectives</i>, Wiley Publication, 2011. 5. Tom Denton, <i>Automobile Electrical and Electronic Systems</i>, Elsevier, Butterworth – Heinemann, Third Edition, 2004 6. https://nptel.ac.in/courses/108103009/
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. S.Archana, Valeo Pvt Ltd, archana.arc19@gmail.com	1. Dr.G.Uma, CEG, uma@annauniv.edu	1.Dr. U. Sowmmiya, SRMIST
2. Mr. Kopaka Chaitanya, Valeo Pvt Ltd, chaithu.239@gmail.com	2.Dr.S.Hosimin Thilagar, CEG, shthilagar@gmail.com	2.Dr. A.Rathinam, SRMIST

Course Code	18EEE307T	Course Name	SOLAR PHOTOVOLTAIC SYSTEM	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Learn the fundamental principle and fabrication of PV cell	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Study about PV characteristics and MPPT algorithms	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Utilize the various components and installation of standalone PV system	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Study about the PV integration with utility grid	Expected Attainment (%)	Design & Development
CLR-5 :	Know net metering and applications of Photovoltaic systems		Analysis, Design, Research
CLR-6 :	Model a solar photovoltaic system		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)
CLO-1 :	Understand the basics of PV energy conversion and cell fabrication	2	80	75
CLO-2 :	Acquire knowledge about PV module and MPPT techniques	3	80	75
CLO-3 :	Design stand-alone PV system	3	80	75
CLO-4 :	Analyze grid connected PV system	3	80	75
CLO-5 :	Develop a PV system for various applications	3	80	75
CLO-6 :	Design a photovoltaic on grid and off grid system	3	80	75

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Global energy scenario	I-V,PV characteristics of a PV	Classification of PV systems	Grid Interactive PV System.	Need for Metering, Types of metering
	SLO-2 Indian energy scenario	Modelling of PV	Central Power Station System , Distributed PV System	Principle components in Grid –PV system	Concepts in Grid Tie systems
S-2	SLO-1 Historical development of PV	Short Circuit, Open Circuit and peak power parameters	Stand alone PV System	Classification of Grid Tie Inverters	Net metering and its importance
	SLO-2 Photovoltaic cell technologies	Datasheet study, Cell efficiency	Components of standalone PV connected system	Working Central inverter, String Inverter, Micro Inverter.	Net metering benefits, policies
S-3	SLO-1 Basics of energy from sun: Insolation, irradiance, Solar constant	Effect of irradiation and temperature	Charge controllers	Grid-connected single phase PV inverter schemes	PV potential and facilities in rural areas
	SLO-2 Insolation variation with time of day, Earth centric viewpoint and declination	Shading impacts ,Fill factor	Batteries	Grid-connected PV control	Electrifying rural and remote areas using PV
S-4	SLO-1 Solar geometry	Solar PV Module and its parameters	Inverter control topologies	Power processing schemes based on single string, multi-string	Introduction to hybrid PV system
	SLO-2 Description of the solar spectrum	Specifications of Solar PV Module	Stand-alone connection of PV modules to a battery and load	AC module technologies	Smart grid
S-5	SLO-1 Sun position, sun path diagrams, solar and clock times	Parallel and series connections. Identical cells Non-identical cells connection	Energy storage alternatives for PV systems.	Sizing the inverter	Case studies on Solar PV Power Plant
	SLO-2 Solar radiation measurements, resource of solar data.	Protecting cells in series and parallel, Interconnecting modules	Storage batteries, lead-acid, nickel-cadmium, nickel-metal-hydride and lithium type batteries.	PV system sizing, efficiency	Survey on existing solar PV system
S-6	SLO-1 Photovoltaic effect - Principle of direct solar energy conversion into electricity in a solar cell system.	Estimation and Measurement of PV Module Power	Small storage systems employing ultra capacitors, charging and discharging properties	Transformer less inverter topologies for grid connected PV applications	Design and Development of PV vehicle charging system
	SLO-2 Semiconductor properties semiconductor physics	Selection of PV Module, Interfacing PV modules to loads	Modeling of batteries load estimation, battery sizing	Centralized grid-connected three-phase inverters for large PV installations	PV powered lighting, Solar Lantern, LED for building etc

S-7	SLO-1	Solar cell - p-n Junction, Solar cell- basic structure	PV cell simulation	Design and Installation of a standalone PV system	Design related issues: grounding, dc arcing, islanding	PV water pumping, DC and AC pump drive
	SLO-2	Solar cell materials ,its properties and construction	Simulation of PV cells in series and parallel.	Mechanical Considerations for PV installation	Harmonic content, reactive power, wiring issues,electro-magnetic interference	PV applications in aircraft, power satellites.
S-8	SLO-1	Types of solar cells :crystalline, multi-crystalline, thin film silicon solar cells, etc	Maximum power point concept	Trouble shooting of Standalone Solar PV System	Interfacing with the power grid economic considerations	Socio-economic and environmental impacts of PV system
	SLO-2	Commercial Si solar cells, recent development in materials used for solar cell	Power conditioning and maximum power point tracking	Maintenance of Solar PV System	Energy yield of grid connected PV installation- Cost and Investment	PV in portable devices
S-9	SLO-1	Solar cells fabrication	MPPT basic Algorithms overview	Safety in installation of Solar PV System	Modeling of stand-alone and grid-connected PV systems	Impact of high PV penetration in power system
	SLO-2	Process involved solar cell fabrication technologies	MPPT algorithms based on buck- and boost-converter topologies	Codes and standards Related to PV Systems: National Electric Code(NEC) and IEEE Standard 1547	Simulation of stand-alone and grid-connected PV systems	Markets for photovoltaic systems

Learning Resources	1. Chetan Singh Solanki., Solar Photovoltaic: Fundamentals, Technologies and Application, PHI Learning Pvt., Ltd., 2nd edition 2011. 2. Rai, G.D., Solar Energy Utilization, Khanna Publishers, N. Delhi, 2010.	3. R. Messenger, J. Ventre, Photovoltaic Systems Engineering, CRC Press 3rd edition.,2010. 4. Sukhatme S.P., Solar Energy, Tata McGraw Hills P Co., 3rd Edition, 2008. 5. https://nptel.ac.in/courses/117108141/
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1.Dr.P.Kanagavel,NIWE,Chennai, kanagavel.niwe@nic.in	1. P.Thamizhazhagan,University college of Engineering, Panruti, thamizhme@gmail.com	1. Ms A.Lavanya, SRMIST
2.Mr.Jason Manoraj , L&T Technology Services Limited,Bengaluru, jasonmanoraj@gmail.com	2. Dr Subhransu Sekhar Dash, Government College of Engineering, Keonjhar, Subhransudash_fee@gceekjr.ac.in	2. Dr.R.Sridhar, SRMIST

Course Code	18EEE308T	Course Name	ENERGY MANAGEMENT SYSTEM AND SCADA	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Impart knowledge on energy management and its planning	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Understand the efficient usage of electric energy for motor driven system	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Identify the strategies and control of energy management systems																		
CLR-4 :	Expose to the concept of supervisory control and data acquisition																		
CLR-5 :	Familiarize about Power System Automation and application of SCADA in power systems.																		
CLR-6 :	Understand the concept of Energy management and SCADA																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Understand the values, importance, principles and effective utilization of energy	2	75	75	H	-	-	-	-	-	-	-	-	-	-	-	M	M	-
CLO-2 :	Apply energy efficient schemes for motor under varying loads	2	75	75	H	M	-	-	-	-	-	-	-	-	-	-	M	M	-
CLO-3 :	Implement the energy management control strategies	2	75	75	H	M	-	-	-	-	-	-	-	-	-	-	M	M	-
CLO-4 :	Analyze the Functions and features of SCADA	3	75	75	H	-	-	-	-	-	-	-	-	-	-	-	M	M	-
CLO-5 :	Infer the Applications and Standards of SCADA	2	75	75	H	-	-	-	-	-	-	L	-	-	-	-	M	M	L
CLO-6 :	Apply the knowledge of Energy management and SCADA in Industries	2	75	75	H	M	-	-	-	-	-	L	-	-	-	-	M	M	L

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Value of Energy Management	Power supply of an electrical motor driven system	Introduction to Energy management systems(EMS)	Introduction of SCADA
	SLO-2	Total Quality Management	Effects of Unbalanced Voltages on The Performance of Poly-phase Squirrel-Cage Induction Motors	Usage of EMS	SCADA Systems
S-2	SLO-1	Energy Management Profession	Glossary of frequently occurring motor terms	Direct Digital Control	Evolution of SCADA
	SLO-2	Energy Management skills	Design , Load types and torque of motor	Objectives of an EMCS using DDC	Objectives of SCADA
S-3	SLO-1	Principles of Energy Management	Power factor of motor	Hardware used in Energy management systems	Benefits of SCADA
	SLO-2	Some Suggested Principles of Energy Management	Benefits and correction of power factor	Advantages of Hardware used in Energy management systems	SCADA in Process Control
S-4	SLO-1	Introduction to Energy Management Program	Electric motor design to operate at varying load conditions	Software used in Energy management systems	Usage of SCADA
	SLO-2	Components of Comprehensive Energy Management Program	Determining Electric Motor Operating Loads	Effectiveness of the Software Control Logic	Real-Time Monitoring and Control using SCADA
S-5	SLO-1	Organizational Structure	Power meter to measure unit operation	Control Strategies	Functions of SCADA
	SLO-2	Energy manager , Team and Employees	Selection of Equipment for Power Measurement and Surveys	Routines of Control Strategies	SCADA Applications
S-6	SLO-1	Energy Policy Objectives and Accountability	Slip measurement of motor	Justification of Energy Management Control Systems(EMCSs)	SCADA Hardware
	SLO-2	Energy Policy Reporting and Training	Amperage Readings	EMCSs Functions	SCADA Hardware Functions
S-7	SLO-1	Energy Planning	Amperage Readings of Electric motor	EMCS opportunity	RTU Standards

	SLO-2	Audit Planning	Electric Motor efficiency	EMCS for an building	Difference between PLC and RTU	SCADA for Power Utility Network
	SLO-1	Educational Planning	Comparing Motors based on efficiency	EMCS Retrofit	Features of SCADA	Components of SCADA Applications
S-8	SLO-2	Strategic Planning	Sensitivity of Load To Motor Rpm	New Construction EMCS	Software of SCADA	Introduction to IEC 61850 Standard for SCADA
	SLO-1	Energy Reporting	Motor Performance Management Process(MPMP)	System Integration	Protocols of SCADA, DNP (Distributed Network Protocol)	Intelligent Electronic Devices (IEDs)
S-9	SLO-2	Energy Ownership	How To Start MPMP	Specifics of Software Logic	Protocols of SCADA, IEC (International Electro Technical Commission)	Substation Automation System (SAS) using IED:

Learning Resources	<ol style="list-style-type: none"> Wayne C. Turner, Steve Doty, Energy Management Hand book, The Fairmont Press, 6th Edition, 2007 Green, J. N, Wilson, R, Control and Automation of Electric Power Distribution Systems, Taylor and Francis, 2007 NPTEL Online Courses, Energy Management Systems and SCADA, IIT Madras. Link : "https://nptel.ac.in/courses/108106022/12"
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.P.Kanakavel,NIWET, pkanagavel.niwet@nic.in	1. Dr. S. Arul Daniel, NIT Trichy, daniel@nitt.edu	1. Dr.S.Vidyasagar, SRMIST
2. Mr. Tripathi patro,visam pvt ltd,btp@visom.co.in	2. Dr. P. Somasundaram, CEG, Anna University, mpsomasundaram@annauniv.edu	2. Dr.V.Kalyanasundaram, SRMIST

Course Code	18EEE309T	Course Name	DISTRIBUTED ENERGY RESOURCES	Course Category	E	Professional elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering			Data Book / Codes/Standards	Nil

18EEE327T Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand the basic operation of non conventional energy sources	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Gain the knowledge about PV system	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Acquire the knowledge of wind power Generation																		
CLR-4 :	Explain the energy production from Biomass and OTEC																		
CLR-5 :	Describe the working of Battery, Flywheel, Ultra Capacitors, micro-turbines																		
CLR-6 :	Acquire the Knowledge of Nonconventional energy sources																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Describe the basic operation of PV,wind,Fuel cell, Micro turbine, Biomass, Tidal power generation	1	75	75	H	-	-	-	-	-	M	-	-	-	-	-	M	M	L
CLO-2 :	Develop the knowledge of PV collector types and know the technical parameters	2	75	75	H	M	-	-	-	-	M	-	-	-	-	-	M	M	L
CLO-3 :	Distinguish different types of wind turbine and know the technical parameters	2	75	75	H	M	-	-	-	-	M	-	-	-	-	-	M	M	L
CLO-4 :	Summarize the functions of Biomass and OTEC	1	75	75	H	-	-	-	-	-	M	-	-	-	-	-	M	M	L
CLO-5 :	Realize the functions of Battery, Flywheel, Ultra Capacitors, micro-turbines	2	75	75	H	-	-	-	-	-	M	-	-	-	-	-	M	M	L
CLO-6 :	Develop the knowledge of the fundamental operation of unconventional energy sources	2	75	75	H	M	-	-	-	-	M	-	-	-	-	-	M	M	L

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Definition, Concepts of Non Conventional Energy Sources	Definition, Solar radiation data	Energy available from wind	Biomass Resources	Energy storage, Battery – types
	SLO-2	Limitations of Non Conventional Energy Sources	solar energy conversion in to heat	General formula, Lift and drag etc	Biofuels	Equivalent circuit
S-2	SLO-1	Energy needs of India, and energy consumption patterns	Solar Radiation Measurement	Basis of Wind energy conversion	Biomass Conversion Routes	Performance characteristics
	SLO-2	Worldwide Potentials of these sources.	Types of Measurement	Basic components of wind energy conversion	Combustion, Gasification	Battery design
S-3	SLO-1	Energy efficiency and energy security	Flat plate and Concentrating collectors	Effect of density, Frequency variances,	Anaerobic Digestion	Charging and charge regulators
	SLO-2	Energy and its environmental impacts	Principle of natural and forced convection	Angle of attack, Wind speed	Pyrolysis	Battery management
S-4	SLO-1	Technical impact of Distributed generation	Energy Storage of PV system	Choice of generators	Cogeneration	Flywheel-energy relations
	SLO-2	Economical impact of Distributed generation	Case studies of Solar thermal systems for residential water heating	Turbine rating, electrical load matching	Biogas plants	Components of Flywheel
S-5	SLO-1	Concept of distributed generations, topologies, selection of sources	Industrial heating	Variable speed operation	Energy recovery from Urban waste	Benefits over battery
	SLO-2	regulatory standards/ framework	Solar power generation	Maximum power operation	Energy recovery from liquid waste	Introduction to Ultra Capacitors
S-6	SLO-1	Definition of Distributed Generation	Concept of Maximum Power Point Tracking	control systems, system design features,	Types of Biomass plant	Working Principle of Ultra Capacitors
	SLO-2	Classification of Distributed Generation	Types of MPPT	Windmill rotors, Horizontal axis	Performance analysis of Biomass	Testing of Ultra capacitor
S-7	SLO-1	DG installation classes	DC Power Conditioning Converters	Vertical axis rotors	Testing Biomass systems	Applications
	SLO-2	Security issues in DG implementations.	Types of converter	Induction type generators,	Thermal applications	Fuel Cells – Principle of Operation
S-8	SLO-1	Distributed Generation Impact on Coordinated Relay Protection	AC Power Conditioning –Inverters	Working principle of wind power plant	Power generation	Performance characteristics

	SLO-2	Classification of NCES, Solar, Wind,	Types of inverter	Determination of torque coefficient	Principles of tidal and wave power generations	Applications
S-9	SLO-1	Geothermal, Biomass, Ocean energy sources,	Testing of PV systems	Standalone connected operations	Open cycle OTEC	micro-turbines- Principle -of Operation
	SLO-2	Comparison of these energy sources	Type of testing of PV system	Grid connected operations	Closed cycle OTEC	Advantages and Disadvantages of Microturbine

Learning Resources	1. 0Rai ,G.D.,Non Conventional sources of Energy, Khanna Publishers ,5th Edition, 2016. 2. Rao. S. & Pamlekar Dr.B.B. Energy Technology , Khanna Publishers, 3rd Edition, 2016 3. Khan. B.H, Non-Conventional Energy Resources, The McGraw Hills,Second edition, 2016. 4.D.P.Kothari, Renewable Energy Sources and Emerging Technologies, PHI Learning Private Limited, 4th Edition 2011. 5.Bansal NK, Kleeman and Meliss M, Renewable energy sources and conversion Techniques, Tata Mc Graw Hill, 1990 . 6. https://www.toppr.com/guides/physics/sources-of-energy/non-conventional-sources-of-energy/
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. Bhaskarsahu, Schneider Electric Ltd, Bhaskar.sahu@schneider-electric.com	1. Dr. K. S. Swarup, IITM, ksswarup@iitm.ac.in	1.Dr.D.Sattianadan, SRMIST
2. Dr.P.Kanakavel,NIWET, pkanagavel.niwet@nic.in	2. Dr. R.Ramesh, CEG, rramesh@annauniv.edu	2.Dr.K.Vijayakumar, SRMIST

Course Code	18EEE404T	Course Name	DISTRIBUTED GENERATION AND MICRO GRID	Course Category	E	Professional elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering		Data Book / Codes/Standards	Nil	

Course Learning Rationale (CLR):		The purpose of learning this course is to:				Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Understand the basic operation of non-conventional energy sources					Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Gain knowledge of IEEE rules applied for distributed generation																								
CLR-3 :	Discuss the concept of microgrid																								
CLR-4 :	Acquire the knowledge on the control algorithms of microgrid																								
CLR-5 :	Examine the behavior of microgrid under Faulty condition																								
CLR-6 :	Acquire the Knowledge of Micro grid																								
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:				Level of Thinking (Bloom)	1	75	75	Engineering Knowledge	H	M	M	-	-	-	H	-	-	-	-	-	M	M	H
CLO-1 :	Summarize the basic operation of PV, Wind, Fuel cell, Micro turbine, Biomass, Tidal power generation																								
CLO-2 :	Interpret the standards required for distributed Generation																								
CLO-3 :	Describe Islanding process and Distributed Generation impact on Coordinated Relay Protection																								
CLO-4 :	Apply the knowledge on the control concept and interface devices																								
CLO-5 :	Analyze protection schemes adopted to the microgrid																								
CLO-6 :	Develop the knowledge of fundamental operation of Micro grid					Level of Thinking (Bloom)	1	75	75	Engineering Knowledge	H	M	M	L	-	-	H	M	-	-	-	-	M	M	H
CLO-1 :	Summarize the basic operation of PV, Wind, Fuel cell, Micro turbine, Biomass, Tidal power generation																								
CLO-2 :	Interpret the standards required for distributed Generation																								
CLO-3 :	Describe Islanding process and Distributed Generation impact on Coordinated Relay Protection																								
CLO-4 :	Apply the knowledge on the control concept and interface devices																								
CLO-5 :	Analyze protection schemes adopted to the microgrid																								
CLO-6 :	Develop the knowledge of fundamental operation of Micro grid																								

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Conventional power generation: advantages and disadvantages	Concept of distributed generations	Concept and definition of microgrid	Typical structure and configuration of a microgrid	Modelling of Microgrid
	SLO-2	Energy crises, Nonconventional energy (NCE) resources	topologies, selection of sources, regulatory standards/ framework	microgrid drivers and benefits	AC and DC microgrids	Concept of per unit
S-2	SLO-1	Review of Solar PV	Classification of Distributed Generation	review of sources of microgrids	Control techniques applied to microgrid	DC Microgrid
	SLO-2	Solar Radiation Measurement	DG installation classes	P-f and Q-V control	Concept of Space Vector Modulation	AC Microgrid
S-3	SLO-1	Introduction to Wind Energy systems	IEEE 1547 – Standard for Interconnecting Distributed Resources with Electric Power Systems	ISLANDING - Significance of Islanding Detection	Concept of synchronizing	Technical issues of Micro grid
	SLO-2	Basic components of wind energy conversion	Purpose and Limitations	Effects of Islanding Phenomena	Synchronizing methods	Power loss and Voltage raise
S-4	SLO-1	Types of wind energy collectors	IEEE 1547.1 standard Conformance Test	Islanding Detection Techniques- Active Detection	Enhanced Interface Devices	Protection scheme for grid-connected mode
	SLO-2	Concept of Maximum Power Point Tracking	Purpose and Limitations	Passive Detection	Dynamic Voltage Restorer	Thermal issues
S-5	SLO-1	Introduction to fuel cell	IEEE 1547.4 – Guide for Design, Operation and Integration	Optimal Power Sharing	Constant Voltage Transformers	Power quality issues in microgrids
	SLO-2	Fuel Cells – Principle of Operation	Purpose and Limitations	Microgrid with Multiple Distributed Generators	Noise Filters	Solution methods
S-6	SLO-1	Introduction to Micro turbines	IEEE 1547.8 Recommended practice for Establishing methods and Procedures	Optimal sizing and Siting of DG	Isolation Transformers	Stability issues in micro grid
	SLO-2	Micro-turbines- Principle of Operation	Purpose and Limitations	Peak Shaving Potential of a Microgrid	Static VAR Compensators	Solution methods

S-7	SLO-1	Biomass- Biomass Resources, Biofuels	Energy storage elements - Batteries	Operating modes of DG- Grid connected	Harmonic Filters	Economic impact of DG
	SLO-2	Biomass Conversion Technologies	Principle of operation	Operating modes of autonomous mode	Microgrid Operation Strategies	Barriers to DG Development
S-8	SLO-1	Energy recovery from Urban waste	ultra-capacitors	Concept of reverse power flow	MicroGrids and Traditional Power	Configuration of SCADA
	SLO-2	Energy recovery from liquid waste	Principle of operation	Distributed Generation Impact on Coordinated Relay Protection	System Economics	Energy Management System
S-9	SLO-1	Principles of tidal and wave power generations	Flywheels	Adaptive relaying	Case Studies : Microgrid Economics	active distribution networks Distributed control system (DCS)
	SLO-2	Open cycle OTEC and closed cycle OTEC	Principle of operation	Fault Limiters	Economic Issues Between MicroGrids and the Bulk Power Systems	Impact of EV on micro grid

Learning Resources	<ol style="list-style-type: none"> 1. AmirnaserYezdani, and Reza Iravani, Voltage Source Converters in Power Systems: Modeling, Control and Applications, IEEE John Wiley Publications,2009. 2. DorinNeacsu, Power Switching Converters: Medium and High Power, CRC Press, Taylor & Francis, 2006. 3. Chetan Singh Solanki, Solar Photo Voltaics, PHI learning Pvt. Ltd., New Delhi,2009. 4.J.F. Manwell, Wind Energy Explained, theory design and applications, J.G. McGowan Wiley publication,2002. 5.D. D. Hall and R. P. Grover, Biomass Regenerable Energy, John Wiley, New York, 1987. 6.S.Chowdhury, S.P. Chowdhury, Microgrids and Active Distribution Networks, IET renewable energy series 6 7.https://www.powermag.com/the-smart-grid-and-distributed-generation-better-together/
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. Bhaskarsahu, Schneider Electric Ltd, Bhaskar.sahu@schneider-electric.com	1. Dr.S.Senthilkumar, NIT Trichy, skumar@nitt.edu	1.Dr.D.Sattianadan, SRMIST
2. Dr.P.Kanakavel,NIWET,panagavel.niwet@nic.in	2. Dr. B. K. Panigrahi, IIT Delhi, bkanigrahi@ee.iitd.ac.in	2.Dr.K.Vijayakumar, SRMIST

Course Code	18EEE405T	Course Name	POWER ELECTRONICS IN RENEWABLE ENERGY SYSTEM	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Educate the students on contemporary development in renewable energy studies	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Design and analyze the power converters for PV applications	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Understand the significance of the power converters for wind energy conversion system																		
CLR-4 :	Create insights into the concept of fuel energy system and its power conditioning system																		
CLR-5 :	Enrich the concept of hybrid renewable energy systems and multiport converters																		
CLR-6 :	Create overall structure for integrating renewable electricity on the grid																		

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Learning			Program Learning Outcomes (PLO)														
CLO-1 :	Acquire knowledge on renewable energy sources and their characteristics	2	80	75	H	M	M	-	-	-	M	-	-	-	-	-	H	M	-
CLO-2 :	Select and design the components of a power converter for PV system	3	80	75	H	M	M	-	M	-	M	-	-	-	-	-	M	M	-
CLO-3 :	Propose an appropriate power converter for wind energy conversion system	3	80	75	H	M	M	-	M	-	M	-	-	-	-	-	H	M	-
CLO-4 :	Choose a suitable converter topology for fuel cell-based energy system	3	80	75	H	M	M	-	-	-	M	-	-	-	-	-	H	H	-
CLO-5 :	Analyze various hybrid energy system for various applications	3	80	75	H	-	-	-	-	-	M	-	-	-	-	-	H	M	-
CLO-6 :	Design the building blocks of the renewable energy conversion system	3	80	75	H	M	M	-	M	-	M	-	-	-	-	-	H	M	-

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Present scenario of renewable energy sources in India	Photovoltaic system components	Components of a wind energy conversion system	Basic overview of fuel cell currently under development	Need for Hybrid Systems
	SLO-2	Solar, wind, ocean, Biomass, Fuel cell and geothermal resources.	Factor influencing output	Site selection consideration	Applications and markets- Portable and stationary application	Types of Hybrid system
S-2	SLO-1	Factors influencing the amount of GHG emission	Types of PV system	Wind generators-Introduction	Fuel cell design levels: The unit cell, the stack, and the system	wind-diesel hybrid system
	SLO-2	Impacts of renewable energy generation on environment	Stand-alone PV system and grid connected PV system	Classification of wind generators	Types of fuel cell and its comparative study	PV-Diesel hybrid system
S-3	SLO-1	Basic principle of photovoltaic Energy Conversion	PV and IV characteristics	Power output performance characteristics	Chemical reaction in various fuel cell	PV-hydro hybrid system
	SLO-2	PV materials	Modeling of PV system	Modeling of wind energy conversion system	Components of fuel cell- Electrolytes and catalyst	Biomass-PV-diesel hybrid system
S-4	SLO-1	Issues associated with the tapping of solar energy	Factors to be considered for the selection of inverter and batteries for solar energy conversion	Matrix converters	Thermodynamic and electrochemical principles of hydrogen fuel cell	Economic, technical and sustainability issues involved in the integration of hybrid renewable energy systems
	SLO-2	Limitations of solar power	Sizing the solar arrays	Limitations in the operation of matrix converter.	High temperature fuel cell	Current status of solar-wind hybrid renewable energy system
S-5	SLO-1	Wind resource assessment	Batteries for solar panel	Synchronized operation with grid supply	Fuel cell power system	Hybrid system characteristics
	SLO-2	wind energy pattern for a particular location	various aspects of battery sizing	Harmonic distortion	MPPT techniques for fuel cell	Various power quality issues hybrid renewable power system
S-6	SLO-1	Basic principle of wind energy conversion	DC power conditioning converters	Standards used for grid integration- Grid connection requirement of renewable power system.	Design consideration of power electronics converters for fuel cell system	Merits of Hybrid RES over the isolated RES

	SLO-2	Power in wind –Betz limit	AC Power conditioning converters	Disturbances from power conditioning devices on the power grid- Power quality issues	Power conversion and control strategies	Case studies on wind-PV maximum power tracking system
S-7	SLO-1	Net metering concept	Basic non-isolated converters	problems in grid integrated WECS	Issues in fuel cell power conditioning system	Multi-port DC-DC converter
	SLO-2	Repowering concept	Isolated dc-dc converters	Impact of wind power penetration in power grid	Fuel cell power conditioning for electric power applications	Flux additive dc-dc converter
S-8	SLO-1	Hydrogen energy system	Converter dynamics and control	Design and optimization of renewable energy system	High gain dc-dc converters for fuel cell based electric vehicle	Hybrid controller
	SLO-2	Hydrogen energy to generate electric power	Bidirectional inverter system	Simulation software for distributed generation power system	Operating principles of high gain dc-dc converter	Major features of hybrid system.
S-9	SLO-1	Working principle of fuel cell	Simulation of PV and IV characteristics	Simulation of Sizing, and analysis of WECS	Reliability study on fuel cell	Merits and demerits of various renewable energy technologies
	SLO-2	Fuel cell characteristics	Simulation of Sizing, and analysis of photovoltaic systems.	Simulation of power electronic converters for WECS	Recent research in fuel cell technology	Application of various renewable energy technologies.

Learning Resources	<p>1. Rashid .M. H, Power Electronics Hand book, Academic press, Second edition, 2006.</p> <p>2. Gray, L. Johnson, Wind energy system, prentice hall inc, 1995</p>	<p>3. Fuchs, Ewald F., Masoum, Mohammad A.S, Power Conversion of Renewable Energy Systems, 978-1-4419-7978-0, springer, 2011.S.N.Singh, Electric power generation, transmission and distribution, 2nd ed., PHI, 2011</p> <p>4. Erickson, Robert W., Maksimovic, Dragan Fundamental of Power electronics, springer, 2001.</p> <p>1. https://nptel.ac.in/courses/108108034/</p>
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1.Dr.P.Kanagavel, Additional Director, R & D, NIWE, Government of India, pkanagavel.niwe@nic.in	1.Dr Subhransu Sekhar Dash, Government College of Engineering, Keonjhar, Subhransudash_fee@gcekr.ac.in	1. Dr.J.Divya Navamani, SRMIST.
2.Mr.Jason Mano Raj, Consultant, L& T Technical services, Bangalore jasonmanoraj@gmail.com	2.Dr.P.Thamizhagan, EEE department,University college of Engineering, Panruti, thamizhme@gmail.com	2.Dr.R.Sridhar, SRMIST

Course Code	18EEE406T	Course Name	WIND AND SOLAR ENERGY SYSTEM	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1:	Learn about PV technology and its principles				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2:	Enrich the solar energy concepts				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3		
CLR-3:	Understand the various techniques involved in solar energy							H	M	L	-	-	-	L	-	-	-	-	-	-	-	H	M	-
CLR-4:	Gain knowledge in Wind Energy technology							H	M	L	-	-	-	L	-	-	-	-	-	-	-	H	M	-
CLR-5:	Acquire knowledge in various design of wind energy							H	M	L	-	-	-	L	-	-	-	-	-	-	-	H	M	-
CLR-6:	Apply the concepts of solar and wind power in industrial applications							H	M	L	-	-	-	L	-	-	-	-	-	-	-	H	M	-
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			2	80	75	H	M	L	-	-	-	L	-	-	-	-	-	H	M	-		
CLO-1:	Explain the principle of solar energy				3	80	75	H	M	L	-	-	-	L	-	-	-	-	-	H	M	-		
CLO-2:	Design the Solar PhotoVoltaic and shadow analysis				3	80	75	H	M	L	-	-	-	L	-	-	-	-	-	H	M	-		
CLO-3:	Analyze various solar application				3	80	75	H	M	L	-	-	-	L	-	-	-	-	-	H	M	-		
CLO-4:	Classify the various wind generators and their control techniques				3	80	75	H	M	L	-	-	-	L	-	-	-	-	-	H	M	-		
CLO-5:	Explain the various types of wind generators				3	80	75	H	M	L	-	-	-	L	-	-	-	-	-	H	M	-		
CLO-6:	Apply knowledge of solar and wind energy systems for various applications				3	80	75	H	M	L	-	-	-	L	-	-	-	-	-	H	M	-		

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Solar radiation	Solar cell- module-array	Battery storage autonomy	Wind resources nature	Characteristics of WECS
	SLO-2	Beam and diffuse radiation	Electrical characteristics of the solar cell	State of Charge (SOC)	Occurrence of wind Power in the wind	Principle of operation and analysis of WECS
S-2	SLO-1	Solar constant, earth	Equivalent circuit	Depth of Discharge(DOD)	Wind characteristics	Types of generators: IG, PMSG, SCIG
	SLO-2	Sun angles	Modeling of solar cells including the effects of temperature	Types of battery	Principles of wind energy conversions	DFIG
S-3	SLO-1	Attenuation of solar radiation	Irradiation and series/shunt resistances on the open-circuit voltage	Types of mechanical tracking	Components of wind energy conversions system (WECS) Aerodynamics of wind turbine	Grid Connected WECS
	SLO-2	Measurement of solar radiation	Irradiation and series/shunt resistances on the short-circuit current.	Significance of MPPT	Wind data	Grid connectors concepts
S-4	SLO-1	Local solar time, derived solar angles	IV characteristics of solar cell	Types of MPPT	HAWT, VAWT, power developed, thrust, efficiency	Wind farm and its accessories
	SLO-2	Sunrise, sunset and day length. Flat plate collectors	Shadow effects	Mitigation techniques of shadow analysis	Rotor selection	Systems for feeding into the grid
S-5	SLO-1	Declination angle	Bypass diodes	Street lighting	Rotor design considerations	Induction Generators for direct grid coupling
	SLO-2	Solar window, cosine law	Hot spot problem in a PV module	Solar distillation	Tip speed ratio	Challenges in Grid connected wind power
S-6	SLO-1	Calculation of angle of incidence	Safe operating area	Solar air heaters, types	Number of blades, blade profile	Asynchronous generators in static cascades
	SLO-2	Seasonal variations, daily variation	Temperature effects of solar PV module	Active solar heaters	Power regulation	Power evacuation issues
S-7	SLO-1	hour angle	Types of solar panels	Passive solar heaters	Yaw control, pitch angle control	Synchronous generators
	SLO-2	Latitude angle	Issues in the stand alone solar system	Solar pond	Stall control	Grid related problems
S-8	SLO-1	Longitude angle	Types of losses in solar panel.	Water pumping	Schemes for maximum power extraction.	Wind generator controlling techniques

	SLO-2	Zenith angle	Solar Photovoltaic power plant.	Domestic lighting	Site Selection	Issues in hybrid of solar and wind power
S-9	SLO-1	Concentrating collectors.	Net metering concept	Grid connected PV systems	Environmental aspects	Different schemes
	SLO-2	Advantages and disadvantages of solar	Design :Panel requirements for a particular load	Challenges in Grid connected solar PV	Solidity	AC voltage controllers

Learning Resources	<ol style="list-style-type: none"> 1. Rai, G.D., Non-Conventional sources of Energy, 5th Edition, Khanna Publishers, 2016 2. Khan. B.H, Non-Conventional Energy Resources, 2nd Edition, The McGraw Hills, , 2016 3. Rai, G.D., Non-Conventional sources of Energy, 5th Edition, Khanna Publishers, 2016. 4. Khan. B.H, Non-Conventional Energy Resources, 2nd Edition, The McGraw Hills, 2016. 	<ol style="list-style-type: none"> 5. Thomas Ackermann, Wind Power in Power Systems, John Wiley & Sons, Ltd, 2005 6. Mukund R. Patel, "Wind and Solar Power Systems, CRC Press, 1999 7. Muhammed H. Rashid, "Power Electronics Handbook" Academic Press, Second 8. Bansal N K, Kleeman and Meliss, "Renewable energy sources and conversion Techniques, Tata McGraw hill, 1990. 9. https://onlinecourses-archive.nptel.ac.in/
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.Manjunath rao, Alstrom,manjunath.rao1103@gmail.com	1. Dr.S.Senthilkumar, NIT Trichy, skumar@nitt.edu	1. Dr. K.Saravanan, SRMIST
2. Mr.Srinath rao, Alstrom,sreenathr.rao@alstrom.com	2. Dr. S. Ramareddy, Jerusalem College of Engineering,srr.victory@gmail.com	2. Dr.R.Sridhar, SRMIST

Course Code	18EEE310T	Course Name	ENERGY CONSERVATION & AUDITING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards			

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Understand the current energy scenario and energy conservation.	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Familiarize the basics of energy and its forms	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Outline the concepts of energy management and audit	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Discuss the methods of improving energy efficiency in different electrical machines	Expected Attainment (%)	Design & Development
CLR-5 :	Describe the methods of improving energy efficiency in different industrial systems		Analysis, Design, Research
CLR-6 :	Obtaining wide knowledge about energy management procedures in industrial system		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Relate the energy scenario and energy conservation	2 80 75	H M - - - - H - - - - -
CLO-2 :	Explain about various energies and its conversions	3 80 75	H M - - - - - - - - - -
CLO-3 :	Implement the procedure for energy audit	3 80 75	H H - - - - - - - - - -
CLO-4 :	Assess the energy efficiency in electrical components	3 80 75	H H - - - - H H - - - -
CLO-5 :	Assess the energy efficiency in industrial system	3 80 75	H H M - - - - - H - H M -
CLO-6 :	Apply energy saving concepts in electrical system	3 80 75	H H M - - - - M H - - H - H M H

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Energy Classifications	Forms of energy	Energy management	Introduction to energy policy, synopsis of National energy policies in India, EC Act 2001.
	SLO-2	Primary energy consumption	Energy conversion, Grades	Energy audit - types	ISO-50001, PDCA, PAT scheme
S-2	SLO-1	Indian energy scenario	Electrical energy	Conservation opportunities	BEE & State Development Agencies & EESL Programmes
	SLO-2	World energy scenario	Electrical energy conversion	Conservation opportunities	Ujala & SEEP Programs
S-3	SLO-1	Energy needs	Electricity Tariff – M.D.,	Energy costs, bench marking	Municipal & Agriculture DSM Initiatives
	SLO-2	Energy pricing	Electrical Tariff T.O.D., P.F	Energy performance	Standards and Labelling Programme EEC initiatives in Other Sectors
S-4	SLO-1	Energy sector reforms	Electrical Tariff – two-part tariff and others	System efficiencies	Energy tariffs
	SLO-2	Green house, climate change	Numerical Examples on electrical basics	Energy substitution	Energy Instrument
S-5	SLO-1	Future effects	Numerical Examples on electrical tariff	audit instruments	Energy Instrument
	SLO-2	Energy security	Thermal energy– temperature, pressure	Facility as an energy system	Measurement of harmonics
S-6	SLO-1	Energy conservation	Heat transfer	Preparing process flow	Harmonics Analyzer
	SLO-2	Material and energy balance	Latent heat, super heat	Energy efficiency in electrical system	Power quality analyzer, Thermal Imaging camera, Thermocouple
S-7	SLO-1	Energy balance calculations	Humidity	Electric motor, compressor, pump.	Hot wire anemometer, Energy meter.
	SLO-2	Restructuring energy sector	Conduction / convection / radiation / evaporation	Power factor improvement, Load management.	Combustion analyzer, Airflow meter, Ultrasonic leak detector
S-8	SLO-1	Energy strategy	Units and conversion – pressure, power,	Numerical Examples on power factor	Occupancy sensors,
	SLO-2	Air pollution	Units and conversion - energy units	Numerical Examples on power factor	energy efficient lighting controls

S-9	SLO-1	Energy conservation act	Numerical example on energies	Numerical examples on harmonics	Energy saving potential of technology	Assessment of cooling towers
	SLO-2	Extracted features of the act	Numerical example on energies	Numerical examples on harmonics	Case study on energy saving technologies	Assessment of cooling towers

Learning Resources	1. Guide books for National Certification Examination for Energy Manager / Energy Auditors Book-1, General Aspects (www.aipnpc.org/GuideBooks.aspx) 2. Guide books for National Certification Examination for Energy Manager / Energy Auditors Book-3, Electrical Utilities (www.aipnpc.org/GuideBooks.aspx) 3. S. C. Tripathy, Utilization of Electrical Energy and Conservation, McGraw Hill, 1991. 4. Success stories of Energy Conservation by BEE, New Delhi (www.bee-india.org). 5. Chopra S.K, Energy Policy for India, Oxford & IBH Publishing, ISBN 812041604X 6. Alagiri, Dhandapani, Energy Security in India, icfai university press, ISBN8131404617					
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Dr. P.Dharmalingam, Former Director, NPC	Dr.M.Premalatha , Professor, DEE,NIT-Trichy, latha@nitt.edu	Mr.D.Ravichandran,SRMIST
Mr.J.Sathiyarayanan, Senior engineer, Southern Railway, Railwayengineer1990@gmail.com	Dr.Ruben sudhakar D, Assist. Prof.Grade-I,DEE, NIT-Trichy rubensudhakar@nitt.edu	Dr.C.Naveen,SRMIST

Course Code	18EEE311T	Course Name	INDUSTRIAL POWER SYSTEM	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards			

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Understand the wiring system for residential ,commercial and industrial consumers				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2 :	Acquire knowledge on standard methodologies for measuring energy in the workplace and energy audit instruments.				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3		
CLR-3 :	Acquire knowledge about Electrical distribution system design aspects of industrial and commercial buildings							H	M	M	M	-	-	-	L	-	-	-	-	M	M	L	L	
CLR-4 :	Comprehend power quality issues and power factor correction							H	M	M	L	-	-	-	-	-	-	-	-	-	M	M	L	L
CLR-5 :	Describe the various techniques in industrial automation							H	M	L	L	-	-	-	M	-	-	-	-	-	M	M	-	-
CLR-6 :	Acquire knowledge on the methodologies and technologies of industrial automation							H	-	-	-	-	-	-	-	-	-	-	-	-	M	M	-	-
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			2	80	75	H	M	M	L	M	-	-	-	-	-	-	-	M	M	L		
CLO-1 :	Design the different components of wiring system				3	80	75	H	M	M	L	-	-	-	-	-	-	-	M	M	L	L		
CLO-2 :	Analyze the concept of energy audit and different loads				3	80	75	H	M	M	L	-	-	-	-	-	-	-	M	M	-	-		
CLO-3 :	Evaluate and design of distribution system and address different Communication systems in industries				3	80	75	H	M	L	L	-	-	-	M	-	-	-	M	M	-	-		
CLO-4 :	Address the different power quality problem and various methods of power factor correction				3	80	75	H	-	-	-	-	-	-	-	-	-	-	M	M	-	-		
CLO-5 :	Identify, monitor and control using PLC and SCADA				2	80	75	H	M	M	L	M	-	-	-	-	-	-	M	M	-	-		
CLO-6 :	Analyze the problem pertaining to power management and automation in industries				3	80	75	H	M	M	L	M	-	-	-M	-	-	-	M	M	-	-		

Duration (hour)	9	9	9	9	9
S-1	SLO-1	LT system wiring components	System approach and End use approach to efficient use of Electricity	Electrical System Design	Overview of power quality
	SLO-2	Selection of cables,wires,switches	Energy auditing: Types and objectives	Distribution System Design	Various issues in power quality
S-2	SLO-1	Selection of distribution box.	audit instruments- ECO assessment	Electrical Design Aspects of Industrial Buildings	Various standards of voltages
	SLO-2	Metering system	Economic methods	Commercials Buildings – Design aspects	Voltage sag-Definition and types
S-3	SLO-1	Tariff structure	specific energy analysis	Electrical Safety	System Data for power quality
	SLO-2	Protection components	Minimum energy paths	Earthing Practices at various voltage levels	Voltage Drop Calculations
S-4	SLO-1	Fuse ,MCB inverse current characteristics	Electric motors	IS Code for earthing	Computer- Aided Analysis
	SLO-2	Isolator ,Relay,MPCB	Energy efficient controls and starting efficiency	Distribution Automation System : Necessity, System Control Hierarchy	Power factor correction studies
S-5	SLO-1	Electric shock and safety practices	Motor Efficiency	Basic Distribution Management System Functions	Introduction to over voltages
	SLO-2	Types of Residential system	Load Analysis	Integration of Distributed Generation	Description and Modeling
S-6	SLO-1	Types of commercial wiring system	Variable speed drives	Custom Power components in distribution systems-	Acceptance Criteria-Frequency Scan Analysis
	SLO-2	General rules for wiring system	Pumps and Fans-Efficient Control strategies	Distribution system Performance	Voltage Magnification Analysis
S-7	SLO-1	Guide lines for installation	Optimal selection and sizing	reliability calculations	Sustained Over voltages
	SLO-2	Load calculation	Optimal operation and Storage	Communication Systems for Control and Automation	Switching Surge Analysis

S-8	SLO-1	sizing of wire	Electric Energy Scenario	Wireless Communications	Back-to-Back Switching	Various control of SCADA System
	SLO-2	Rating of main switch and distribution board	Demand Side Management-Industrial Load Management	Wired Communications	KVAR calculation	Supervision and Control in SCADA
S-9	SLO-1	Earthing system calculation	Load Curves-Load Shaping Objectives-Methodologies-Barriers	DA Communication Protocols	Types of compensation	HMI, RTU and Supervisory Stations
	SLO-2	Requirements of commercial installation	Classification of Industrial Loads- Load Modelling; Electricity pricing	Architectures and user interface	Over view of compensation	Trends in SCADA, Security Issues

Learning Resources	1. H. Joshi, Residential Commercial and Industrial Systems, McGraw Hill Education, 2008. 2. DONALD BEEMAN, Industrial Power Systems Handbook, McGRAW-HILL BOOK COMPANY, INC 3. Rasamy Natarajan, Computer-Aided Power System Analysis, Marcel Dekker Inc., 2002 4. S.L. Uppal and G.C. Garg, Electrical Wiring, Estimating & Costing, Khanna publishers, 2008	5. James Northcote – Green, Robert Wilson, Control and Automation of Electrical Power Distribution Systems, CRC Press, New York, 2007. 6. Turan Gonen: .Electric Power Distribution System Engineering. McGraw Hill Company. 1986 7. James Northcote – Green, Robert Wilson, Control and Automation of Electrical Power Distribution Systems, CRC Press, New York, 2007.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1.Mr.Srinath rao, Alstrom,sreenathr.rao@alstrom.com	1.Dr. P. Somasundaram, CEG, Anna University, mpsomasundaram@annauniv.edu	1.Dr.V.Kalyanasundaram,SRMIST
2.Mr.Manjunath rao, Alstrom,manjunath.rao1103@gmail.com	2.Dr. B. K. Panigrahi, IIT Delhi, bkpanigrahi@ee.iitd.ac.in	2.Dr.S.Vidyasagar, SRMIST

Course Code	18EEE312T	Course Name	FACTS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Outline the fundamentals of FACTS controllers	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Discuss shunt and series compensation techniques and its objectives	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Understand the concept of TCSC controllers																		
CLR-4 :	Learn basic idea of voltage and phase angle regulator in power system																		
CLR-5 :	Familiarize the concept of versatile FACTS controllers																		
CLR-6 :	Create overall structure of facts controllers and application of FACTS controller																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Summarize the concepts of FACTS controllers	1	80	75	H	-	-	-	-	-	-	-	-	-	-	-	H	M	-
CLO-2 :	categorize the shunt and series compensation techniques used in facts controllers and its objectives	2	80	75	H	-	-	-	-	-	-	-	-	-	-	-	M	M	-
CLO-3 :	Examine the operation of TCSC and application of TCSC	2	80	75	H	-	-	-	-	-	-	-	-	-	-	-	H	M	-
CLO-4 :	Relate the various application of phase shift transformer and phase angle regulator	2	80	75	H	-	-	-	-	-	-	M	M	-	-	-	H	H	-
CLO-5 :	Gain knowledge the basic concept of STATCOM, UPSC and its application	2	80	75	H	-	-	-	M	-	-	-	-	-	-	-	H	M	-
CLO-6 :	Design a suitable FACTS controller to compensating of real and reactive power using FACTS devices	2	80	75	H	-	-	-	M	-	-	-	M	M	-	-	H	M	-

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Electrical Transmission Network	Introduction to passive compensation	Need for variable series compensation	Phase shifting transformer	voltage source converters
	SLO-2	HVDC Vs HVAC	Objectives of shunt and series compensation	TCSC: Basic and practical module	Configurations of SPST	current source converter
S-2	SLO-1	Conventional Control Mechanisms-Automatic Generation Control (AGC)	Introduction to Single-phase and three phase-Thyristor controlled Reactor (TCR)	Net reactance offered by TCSC,	Objectives of voltage and phase angle regulators	Static synchronous series compensator :
	SLO-2	Excitation Control-Transformer Tap-Changer Control-Phase-Shifting Transformers	The 12-Pulse TCR	Operation of TCSC: Basic principle	Real and reactive power of voltage and phase angle regulators	principle of operation
S-3	SLO-1	System compensation	Analysis of single phase TCR	X-I and V-I characteristics of TCSC	Applications of Phase Angle Regulator	VI characteristics
	SLO-2	Analysis of Uncompensated Transmission system	SVC configurations- Fixed Capacitor	Different modes of Operation Explain TCSC	Approaches to Thyristor controlled voltage regulators	Applications
S-4	SLO-1	Necessity of FACTS controller	Thyristor-Controlled Reactor and its operating characteristics	Different modes of operation Explain MSC	Approaches to phase angle regulators	Introduction to Static synchronous compensator (STATCOM)
	SLO-2	Load and system Compensation	Operating Characteristics without Voltage Control	Analysis of TCSC	Continuously Controllable Thyristor Tap changers	STATCOM Principle of operation
S-5	SLO-1	Comparison between Series-Connected and Shunt-Connected Compensating Voltages	Operating Characteric With Voltage Control	Analysis of TSSC	Thyristor Tap Changer with Discrete Level Control	VI characteristics
	SLO-2	Modeling long transmission line	SVC voltage control operation	Capability Characteristics (single and multi-module TCSC) TCSC losses	Improvement of Transient Stability	Applications
S-6	SLO-1	Real and reactive power flows in AC system	Q-V characteristics	TCSC applications	Power Oscillation Damping	UPFC: basic module -capabilities

	SLO-2	Symmetrical lossless line Midpoint compensation	Thyristor Switched Capacitor (TSC)-operation-	Modelling of TCSC for Stability Studies	Basic Issues in the Damping of Low Frequency Oscillations in Large Power Systems	UPFC Modes of operation
S-7	SLO-1	Surge Impedance Loading	Practical switching strategy V-I characteristics of TSC	power flow enhancement	System Modelling for Small Signal Stability	Applications
	SLO-2	Classification of FACTS controllers controllable parameters	(TSC)-operation -VI characteristics	Variable reactance model for transient stability study	Damping of Power Oscillations Using Series FACTS Controllers	Introduction to Generalized unified power flow controller (GUPFC)
S-8	SLO-1	Applications of FACTS	(TCR)-operation -VI characteristics	TCSC: Open loop current control	Damping of Power Oscillations Using Shunt FACTS Controllers	Inter line power flow controller (IPFC)
	SLO-2	Relative Power Carrying Capability of AC and DC Transmission Lines	Advantages of slope in SVC dynamic characteristics	TCSC: closed loop current control	Switching Converter-Based Voltage and Phase Angle Regulators	Configuration of IPFC
S-9	SLO-1	The Impact of Distributed Generation	SVC Applications	Power flow incorporating with SVC and TCSC	Hybrid Phase Angle Regulators	Application
	SLO-2	The Effect of Electricity Deregulation	Enhancement of steady state and transient stability	Mitigation of Subsynchronous Resonance with TCSC	A Case Study of Damping Controllers in UPFC	Simulation of SVC and TCSC with SMIB system

Learning Resources	1. Mohan Mathur, R. & Rajiv K. Varma, Thyristor Based FACTS Controller for Electrical Transmission Systems, Wiley Interscience Publications, 2011. 2. Narain G. Hingorani & Laszlo Gyugyi, Understanding FACTS – Concepts & Technology of Flexible AC Transmission Systems, Standard Publishers, New Delhi, 2011.	3. Yong Hua Song and Allan T. Johns Flexible Ac Transmission Systems (FACTS), The Institution of Engineering and Technology 2008 4. https://nptel.ac.in/courses/108107114/ 5. https://npti.gov.in/flexible-ac-transmission-system
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1.Mr.Manjunath rao, Alstrom,manjunath.rao1103@gmail.com	1.Dr.D.Devaraj, Dean-Academic,Kalasalingam Academy of Research and Education, d.devaraj@klu.ac.in	1. Mr.D.Maharajan, SRMIST
2.Dr. T. Prakash, TNEB, Mt. Road, prakash.thyagarajan@tnebnet.org	2. Dr. S. Ramareddy, Jerusalem College of Engineering,srr.victory@gmail.com	2. Mr.V.Kubendran, SRMIST

Course Code	18EEE313T	Course Name	HIGH VOLTAGE ENGINEERING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):		Learning			Program Learning Outcomes (PLO)														
		1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-1 : Outline the concepts of over voltages and Insulation Co-ordination on power system					Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge											
CLR-2 : Discuss the solid, liquid and gaseous dielectrics with its relevance to application of high voltages.								Problem Analysis											
CLR-3 : Understand the concept of generation of high voltages								Design & Development											
CLR-4 : Familiarize the concept on the measurement of high voltages and currents								Analysis, Design, Research											
CLR-5 : Describe the testing of high voltage equipments and its application.								Modern Tool Usage											
CLR-6 : Create overall understanding of various types of overvoltages, high voltage generation, measurement and testing								Society & Culture											
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:						Environment & Sustainability											
CLO-1 : Gain knowledge on overvoltage protection and the importance on insulation co-ordination levels.					2	80	75	Ethics											
CLO-2 : Understand the basics of dielectrics and its breakdown process on high voltage application					2	80	75	Individual & Team Work											
CLO-3 : Acquire knowledge on high voltage generation					2	80	75	Communication											
CLO-4 : Gain knowledge on measurement of high voltage generation					2	80	75	Project Mgt. & Finance											
CLO-5 : Demonstrate the testing procedures of high voltage equipment and its application					3	80	75	Life Long Learning											
CLO-6 : Summarize the scenarios of over voltages and applications of high voltage equipments for generation ,measurement and testing					3	75	75	PSO - 1											
								PSO - 2											
								PSO - 3											

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Causes of over voltages	Gaseous breakdown in uniform and non-uniform fields	Generation of high DC voltages – Half-wave and full-wave rectifier circuits	HVDC measurement techniques Series Resistance microammeter
	SLO-2	Effects of overvoltages on power system	Conduction and breakdown in gases-Ionization process	Voltage doubler circuits	Resistance potential divider
S-2	SLO-1	Parameters of lightning strokes	Townsend's current growth equation in the presence of secondary processes	voltage multiplier circuits	Generating voltmeter
	SLO-2	Characteristics of lightning strokes-Direct ,indirect strokes and backflashover	Townsend's Criterion for breakdown	Van de Graff generator	Measurement of high A.C and impulse voltages-
S-3	SLO-1	Origin of Switching overvoltages	Experimental determination of Townsend's coefficients	Generation of high alternating voltages	Series Impedance voltmeters
	SLO-2	Characteristics of Switching overvoltages	Breakdown in electronegative gases	Cascaded transformer	Series capacitance voltmeter
S-4	SLO-1	Impact of switching surges in EHV and UHV systems	Time lags for breakdown	Resonant transformer-Series connection	Capacitance potential dividers and capacitance voltage transformers
	SLO-2	Control of overvoltages due to switching overvoltages	Streamer Breakdown mechanism in gases	Resonant transformer-Parallel connection	Potential Transformer, Electrostatic voltmeter,
S-5	SLO-1	Causes of power frequency overvoltages in EHV and UHV systems	Paschen's law-Derivation	Generation of high frequency alternating voltages- Advantages	Peak reading ac voltmeter-Series capacitor, peak voltmeter
	SLO-2	Remedial measures adopted in EHV and UHV systems	Practical Considerations in using gases for insulation purposes	Tesla coil equivalent circuit	Digital peak voltmeter
S-6	SLO-1	Protection against Lightning overvoltages and switching surges of short duration-Ground wires	vacuum breakdown	Generation of impulse voltages-Standard impulse waveshapes	Measurement of high dc, ac and impulse voltages -Sphere gap measurement
	SLO-2	Protection of transmission lines against over voltages-Ground rods and counter-poise wires	Liquid as insulators-Electrical properties	waveshape control parameters	Factors influencing the spark over voltage of sphere gaps

S-7	SLO-1	Protective devices-Rod gap, Expulsion gap	Conduction and breakdown in pure and commercial liquids	Multistage impulse generator-Marx circuit	Resistance Potential divider for impulse voltage measurements	Testing procedures of surge diverters
	SLO-2	Protector tubes, Surge arrester	Breakdown mechanisms in solid dielectrics-Intrinsic and Electromechanical breakdown	Marx circuit -simulation	Capacitance potential dividers for impulse voltage measurements	Radio Interference Measurements – Measurement of Radio Interference voltage
S-8	SLO-1	Principles of Insulation Coordination-Ideal requirements of a protective device	Breakdown mechanisms in solid dielectrics-Intrinsic and Electromechanical breakdown	Generation of impulse current-Definition- Circuits for producing impulse current waves	Measurement of high DC, AC and impulse measurements-High DC currents-DC current transformer-Hall generators	RIV measurement circuit
	SLO-2	Surge diverters, Equipment insulation level and insulation co-ordination of substation	Thermal breakdown, solid breakdown used in practice	Generation of rectangular current pulses	Measurement of high frequency and impulse currents- Resistive shunts	Non-destructive testing of materials and measurement of direct current resistivity
S-9	SLO-1	insulation level at substation with protective zones	Breakdown in composite dielectrics- properties	Circuits for producing switching surge voltages	Rogowski coils, Magnetic links, Faraday Generator	Measurement of dielectric constant and loss factor. Partial discharge measurements
	SLO-2	Insulation Coordination in EHV and UHV systems	Mechanism of breakdown in composite dielectrics	Tripping and control of impulse generators- Trigatron gap	Cathode Ray Oscillographs for Impulse voltage and current measurements	Application of high voltage engineering in food processing and bio-medical industry

Learning Resources	1. Naidu.M.S. and Kamaraju, High Voltage Engineering, Tata McGraw Hill, 2014.	4. G.V. Barbosa –Canovas, Pulsed electric fields in food processing: Fundamental Aspects and applications, CRC Publisher Edition March 2001.
	2. Wadhwa.C.L., High Voltage Engineering New age international publishers Ltd.-New Delhi 2010. 3. Ravindra Arora, Wolfgang Mosh, High Voltage and Electrical Insulation Engineering, Wiley-IEEE Press 2011.	5.H. L. M. Lelieveld and Notermans.S.et.al., Food preservation by pulsed electric Fields: From research to application, Woodhead Publishing Ltd. October 2007.

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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2.Mr.srinath rao, Alstrom,sreenath.rao@alstrom.com	2.Dr. P. Valsalal, Anna University , valsalal@annauniv.edu	2.Dr. A.Rathinam, SRMIST

Course Code	18EEE314T	Course Name	POWER QUALITY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand the characterization of electric power quality	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Study the sources of power quality events such as voltage sag, short and long duration variations	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Explain the reduction of PQ problems using custom power devices and harmonic filters																		
CLR-4 :	Impart knowledge on various methods of power quality monitoring																		
CLR-5 :	Illustrate the power quality issues in distributed generation																		
CLR-6 :	Understand Power Quality events, Measuring equipments and their impact on Distributed Generation																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Describe the causes and effects of power quality problems and categorize the various electrical power quality issues in power systems	1	75	75	H	-	-	-	-	-	-	M	-	-	-	-	-	-	M
CLO-2 :	Identify the power quality major events like voltage sag, interruptions and harmonics	2	75	75	H	L	L	-	-	-	-	-	-	-	-	-	M	M	-
CLO-3 :	Design and simulate the custom power devices and harmonic filters	3	75	75	H	M	M	L	M	-	L	M	-	-	-	-	M	M	M
CLO-4 :	Interpret in usage of various PQ measuring instruments	2	75	75	H	-	-	-	L	-	M	M	-	-	-	-	L	M	M
CLO-5 :	Identify the various power quality issues in solar system and wind energy conversion system	2	75	75	H	L	L	-	-	-	M	-	-	-	-	-	M	M	-
CLO-6 :	Analyze PQ issues in wind and solar energy system and utilize the monitoring equipments for PQ events	3	75	75	H	L	L	L	M	-	M	M	-	-	-	-	M	M	M

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Introduction to power distribution system	Sources of Sag and Interruptions	Fundamentals of harmonics	Introduction to Power Quality monitoring	Introduction to Distributed Generation Technologies
	SLO-2 Power quality: concepts and definition	Classification of Voltage sag	Sources of harmonics	Power Quality Monitoring considerations	Resurgence of DG
S-2	SLO-1 Characterization of Transients	Estimating Voltage Sag performance – Area of Vulnerability, Equipment sensitivity to voltage sags	Definitions: Average value - RMS value - True power factor - phase sequence - Fourier series	Perspective of Power Quality Measuring equipments	Perspectives on DG benefits
	SLO-2 Causes and effects of Transients	Transmission system sag performance evaluation, Utility distribution system sag performance evaluation	Numerical example for harmonic analysis	Overview of Power Quality measurement equipments	Perspectives on Interconnection
S-3	SLO-1 Characterization, causes and effects of Short duration variations – interruptions	Fundamental principles of protection	Voltage and current distortions, Harmonics indices - (THD and TDD)	Power Quality Measurement Equipment: Power line disturbance analyzer	Interface to the Utility System
	SLO-2 Characterization, causes and effects of Short duration variations – Sags and Swells	Solutions of voltage sag at the end user level	Harmonics standards (IEEE, IEC)	Spectrum analyzer and Harmonic analyzer,	Various types of electrical system interfaces
S-4	SLO-1 Characterization of Long duration variations	Voltage sag and interruption indices	Harmonics sources from commercial load	Flicker meters	Power Quality issues of DG
	SLO-2 Causes and effects of Long duration variations	Basic Reliability evaluation techniques	Harmonics sources from industrial nonlinear load	Disturbance analyzer	Various types of Power Quality issues affected by DG
S-5	SLO-1 Characterization of Voltage imbalance and Waveform distortion	Motor-Starting sags	Effect of harmonics distortion	Transducer requirements	Operating conflicts
	SLO-2 Causes and effects of Voltage imbalance and Waveform distortion	Motor-starting methods	Impact on capacitors, transformers, motors, teleCommunications, energy and demand metering	Demonstration of harmonic analyzer	Description of Operating conflicts results in Power Quality problems

S-6	SLO-1	Characterization of Voltage fluctuation and Power Frequency variations	Utility System Fault-Clearing Issues	Devices for controlling Harmonics - Inline choke	Assessment of Power Quality Measurement Data	DG on Low-Voltage Distribution networks
	SLO-2	Causes and effects of Voltage fluctuation and Power Frequency variations	Overview of Transient Faults	Zig Zag transformer	Off-line and On-line Power quality data assessment	Integration techniques for DG on networks
S-7	SLO-1	CBEMA	Overview of Permanent Faults	Harmonic filters: Passive, Active and Hybrid filters	Application of Intelligent Systems to power quality monitoring	Siting DG
	SLO-2	ITI curves	Voltage sag Mitigation methods	Design of filters - simulation	Design of expert systems for monitoring applications	Discussion on optimal DG siting problem
S-8	SLO-1	Introduction to Power Quality standards	Mitigation of sag - Dynamic Voltage Restorer (DVR)	Harmonic analysis	Requirements on industry Power Quality monitoring applications	DG Interconnection standards
	SLO-2	International Standards of Power Quality	Principle and configuration of DVR	Illustration of Harmonic analysis with an Industry case study	Web based Power Quality monitoring system	Interconnection requirements
S-9	SLO-1	Introduction to Power Quality events	Mitigation of sag - Distribution static synchronous compensator (DSTATCOM)	Seminar on Harmonic analysis	Power Quality monitoring standards	Power Quality issues in grid integrated Solar system
	SLO-2	Computer simulation of Power Quality events	Principle and configuration of DSTATCOM	Recent advancement in Harmonic distortion analysis	IEEE 1159 and IEC 61000-4-30	Power Quality issues in grid connected wind energy conversion system

Learning Resources	1. Roger C. Dugan, Mark Mc Granaghan, Surya Santoso, H.Wayne, H. Wayne Beaty, <i>Electrical Power Systems Quality</i> , Tata McGraw Hill, Third edition, 2012.	3. Arindam Ghosh, <i>Power Quality Enhancement Using Custom Power Devices</i> , Kluwer Academic Publishers, 2002.
	2. Math H J Bollen, <i>Understanding Power Quality Problems: Voltage Sags and Interruptions</i> , IEEE Press, New York, 2000.	4. G.T.Heydt, <i>Electric Power Quality</i> , Stars in a Circle Publications, second edition, 1994. 5. https://nptel.ac.in/courses/108106025/Power%20quality_in_power_distribution_systems.pdf .

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.K.Karthikeyan, ABB India Ltd., k.karthikeyan@in.abb.com	1. Dr.B.Chitti Babu, IIITDM Kanchipuram, bcbabu@iiitdm.ac.in	1. Dr.R.Ramya, SRMIST
2. Mr.Manjunath rao, Alstrom,manjunath.rao1103@gmail.com	2. Dr.K.Selvi, Thiagarajar College of Engineering, Madurai, kseee@tce.edu	2. Mr.D.Ravichandran, SRMIST

Course Code	18EEE315T	Course Name	SMART GRID	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)															
CLR-1 :	Describe the architecture of smart grid, standards and policies				Level of Thinking (Bloom)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Examine the issues with renewable energy integration and energy management system					Expected Proficiency (%)																	
CLR-3 :	Enrich the students with knowledge on measurement techniques in smart grid					Expected Attainment (%)																	
CLR-4 :	Understand power system studies in smart grid																						
CLR-5 :	Acquire knowledge on Communication networks and security challenges																						
CLR-6 :	Understand the management and control of smart grid																						
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																					
CLO-1 :	Understand the smart grid architecture and standards				1	80	75	H	-	-	-	-	-	-	H	H	-	-	-	M	H	M	
CLO-2 :	Analyze the issues with renewable energy integration				2	80	75	H	L	-	-	-	-	M	H	-	-	-	-	M	H	M	
CLO-3 :	Apply measurement techniques in smart grid				2	80	75	H	L	-	-	-	-	-	-	-	-	-	-	M	H	-	
CLO-4 :	Explain the power system studies in smart grid				2	80	75	H	M	-	-	M	-	-	-	-	-	-	-	M	H	-	
CLO-5 :	Summarize Communication networks and security issues				1	80	75	H	-	-	-	-	-	-	-	-	-	-	-	M	H	M	
CLO-6 :	Apply management and control strategies in smart grid				1	80	75	H	L	-	-	M	-	M	H	-	-	-	-	M	H	M	

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Evolution of Electric Grid	Necessity of renewable power generation	Importance of measurement in smart grid	Basics of load flow studies	Role of Communication infrastructures in smart grid
	SLO-2 Definitions and Need for Smart Grid	Benefits of renewable generation in smart grid	Measurement parameters in smart grid	Extended load flow studies in smart grid	Types of Communication infrastructures
S-2	SLO-1 Basics of smart grid	Importance of PV system	Introduction to Smart Meters	Necessity of voltage stability analysis	Elements of data Communication networks
	SLO-2 Comparison of Power grid with Smart grid power system	Grid integration issues of PV system	Block diagram of smart meters	Voltage stability analysis in smart grid	Standards of data Communication networks
S-3	SLO-1 Smart grid components	Importance of wind system	Communication infrastructure for smart metering	Importance of state estimation	Wired networks in smart grid
	SLO-2 Smart grid drivers/functions	Grid integration issues of wind system	Communication protocols for smart metering	Approach of smart grid to state estimation	Wireless networks in smart grid
S-4	SLO-1 Opportunities, challenges and benefits	Basics of energy storage system	Basics of AMI drivers	Necessity of optimization techniques	Functional groups of smart grid Communications
	SLO-2 Functions of Smart Grid Components	Operation of independent Large-Scale Battery Storage system	Benefits of AMI drivers	Optimization techniques in smart grid-case study	Types of Communications in smart grid
S-5	SLO-1 Wholesale energy market in smart grid	Necessity of Battery management system	Necessity of WAMS network	Different intelligent techniques	Characterization of smart grid data
	SLO-2 Advantages of building integrated and distributed power systems	Types of Battery management system in smart grid	Wide area measurement system in smart grid	Applications of computational intelligence in smart grid	Secure data management in smart grid
S-6	SLO-1 Approach to smart grid interoperability standards	Necessity of energy management system	Introduction to Phasor measurement units	Transmission system automation	Applications of smart grid data
	SLO-2 IEEE standards for Smart Grid	Energy management system in smart grid	Architecture of Phasor measurement units	Components of transmission system automation	Impact of bad data in smart grid data
S-7	SLO-1 International policies in Smart Grid	Basics of demand side management	Communications in PMUs	Distribution system automation	Data cleaning in smart grid data
	SLO-2 National and International Initiatives in Smart Grid	Demand side management in smart grid	Implementation of dynamic visualization system for real time power system data	Components of Distribution system automation	Smart grid network interoperability

S-8	SLO-1	Operation of smart grid	Basics of demand response	Smart buildings in smart grid	PHEV in distribution network	Basics of cyber security
	SLO-2	Control strategies of smart grid	Demand response issues in smart grid	Components in smart buildings	Charging strategies in PHEV	Cyber security issues in smart grid
S-9	SLO-1	Basics of microgrid	Study of power quality parameters	ASHRAE standard for smart buildings	Discharging strategies in PHEV	Types of cyber attacks
	SLO-2	Micro grid importance in smart grid	Power quality issues associated with renewable energy in smart grid	Multi agent systems in smart grid	Impact of PHEV on the grid	Mitigation approach to cyber security attacks

Learning Resources	1. James Momoh, Smart Grid: Fundamentals of design and analysis, John Wiley & sons Inc, IEEE press 2012.	4. Clark W. Gellings, The smart grid: Enabling energy efficiency and demand response, Fairmont Press Inc, 2009.
	2. Janaka Ekanayake, Nick Jenkins, Kithsiri Liyanage, Jianzhong Wu, Akihiko Yokoyama, Smart Grid: Technology and Applications, John Wiley & sons inc, 2012.	5. Kenneth C. Budka, Jayant G. Deshpande, Marina Thottan, and Communication networks for smart grids, Springer, 2014.
	3. Fereidoon P. Sioshansi, Smart Grid: Integrating Renewable, Distributed & Efficient Energy, Academic Press, 2012.	6. https://onlinecourses.nptel.ac.in/noc18_ee42/course

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Sudharsan, L&T, sudharsand@Intecc.com	1. Dr Subhransu Sekhar Dash, Government College of Engineering, Keonjhar, Subhransudash_fee@gcekjr.ac.in	1. Dr.J.Preetha Roselyn, SRMIST
2. Dr.K.Karthikeyan, ABB India Ltd., k.karthikeyan@in.abb.com	2. Dr. R.Ramesh, CEG, rramesh@annauniv.edu	2. Dr.K.Vijayakumar, SRMIST

Course Code	18EEE316T	Course Name	VEHICULAR POWER SYSTEM	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:		
CLR-1 :	Understand the importance of electric transportation system and the basics of electric vehicle components and design			
CLR-2 :	Acquire knowledge on battery technologies in transportation			
CLR-3 :	Gain knowledge on charging and starting systems in vehicular application			
CLR-4 :	Explain the importance of fuel cell and application			
CLR-5 :	Examine the working and control of electric propulsion systems			
CLR-6 :	Create overall structure of vehicular power system			

Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:		
CLO-1 :	Examine on different transportation development strategies and architecture of hybrid drive train			
CLO-2 :	Understand the construction, working and maintenance of battery			
CLO-3 :	Summarize the charging and starting systems principle, diagnosing and advancements in automotive			
CLO-4 :	Interpret the fuel cell structure, operation, types and characteristics of fuel cell technology			
CLO-5 :	Outline different electric drives and its control techniques			
CLO-6 :	Understand a vehicle's power system using components like energy storage system and power converters			

Learning		
1	2	3
Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)

Program Learning Outcomes (PLO)														
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
H	L	L	-	-	-	-	-	-	-	-	-	L	L	-
H	M	H	-	-	-	-	-	L	-	-	-	H	M	-
H	-	M	-	-	-	-	-	L	-	-	-	H	M	-
H	L	M	-	-	-	-	-	L	-	-	-	H	M	-
H	-	M	-	-	-	-	-	-	-	-	-	H	M	-
H	L	M	-	-	-	-	-	L	-	-	-	M	M	-

Duration (hour)		9	9	9	9	9
S-1	SLO-1	History of modern transportation	Introduction to energy storage systems	Requirements of charging system	Structure and operation of fuel cell	DC motor drives principle of operation
	SLO-2	Importance of different transportation development strategies to future oil supply	Battery requirements for HEVs, PHEVs and EVs	Charging system principles	Types of fuel cell (PAFC and PEM)	Analysis of DC motor drives performance
S-2	SLO-1	History of hybrid electric vehicles	Working principle and construction of lead-acid, nickel cadmium	Alternators basics and working	Types of fuel cell (MCFC and SOFC)	Chopper control techniques for DC motor drives
	SLO-2	History of electric vehicles	Working principle and construction of nickel cadmium	Charging circuits basics and working	Types of fuel cell (DMFC, AFC and ZAFC)	Rectifier control techniques for DC motor drives
S-3	SLO-1	Social and environmental importance of hybrid and electric vehicles	Working principle and construction of nickel metal hydride	Charging system testing instruments	Fuel cell based power processing systems introduction	Induction motor drives principle of operation
	SLO-2	Key challenges of hybrid and electric vehicles	Working principle and construction of lithium ion batteries	Diagnosing charging system faults	Benefits of power processing systems	Analysis of Induction motor drives performance
S-4	SLO-1	Specifications of PHEVs, BEVs, EVs and HEVs	Properties of battery	New developments in charging systems	Important properties of fuel cells for vehicles	Inverter control techniques for induction motor drives
	SLO-2	The future of electric vehicles	Characteristics of battery	Advanced charging systems	Alternate fuels for fuel cell vehicles	Cycloconverter control techniques for induction motor drives
S-5	SLO-1	Requirement of drive train	Maintenance of battery	Requirements of starting systems	Fuel cost and fuel economies comparison	Permanent magnetic brush-less DC motor drive operation
	SLO-2	Sizing of components in drive train	Visual inspection of battery	Starter motors and its circuits	Comparison of characteristics of fuel cells	Analysis of brush-less DC motor drives performance
S-6	SLO-1	Series configuration of HEVs	Battery testing instruments	Inertia starter and pre-engaged starter	Fuel cell based drive trains	Control techniques of BLDC motor drive
	SLO-2	Parallel configuration of HEVs	Diagnosing battery faults	Permanent magnet starter, integrated starter generator and electronic starter	Comparison of BEV, DHFC/EV and DMFC/EV	Implementing control techniques for BLDC motor drive
S-7	SLO-1	Power split configuration of HEVs	Introduction to supercapacitor	Starting system testing instrument	Transition from diesel to fuel cell engines	Sensorless control for BLDC drive introduction

	SLO-2	Merits and Demerits of different HEV configurations	Introduction to flywheel	Diagnosing in starting system faults	Fuel cell/battery hybrid power system	Different control techniques for BLDC drive introduction
S-8	SLO-1	Vehicle dynamics	Advanced battery technology	Advanced starting system technology	Fuel cell in domestic application	Switched reluctance motor drives principle of operation
	SLO-2	Problems using vehicle dynamics	Developments in electrical storage	New developments in starting systems	Fuel cell in industrial application	Analysis of switched reluctance motor drives performance
S-9	SLO-1	Modelling electric vehicle range	Case studies on battery technologies	Case studies in charging and starting systems	Case studies on fuel cell technologies	Control techniques of switched reluctance motor drive
	SLO-2	Problems under vehicle travel range	Software implementation of battery and its applications	Software implementation of charging and starting systems	Software implementation of fuel cell and its applications	Implementing control techniques for switched reluctance motor drive

Learning Resources	1. A. Emadi, M. Ehsani and John M. Miller, Vehicular Power Systems, Marcel Dekker, New York, 2004. 2. Ion Boldea and S.A Nasar, Electric drives, CRC Press, 2005. 3. Sandeep Dhameja, Electric Vehicle Battery Systems, Newnes, 2002.	4. Chris Mi, M. Abul Masrur, David Wenzhong Gao, Hybrid Electric Vehicles: Principles and Applications with Practical Perspectives, Wiley, 2011. 5. Iqbal Husain, Electric and Hybrid Vehicles: Design Fundamentals, CRC Press, 2nd Edition, 2010. 6. https://www.diyguru.org/course/electric-vehicle/
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.S.Sambath, TANGEDCO, Tamilnadu, eses.eng@gmail.com	1. Dr.Chandramohan, CEG, Anna University, c_dramo@annauniv.edu	1. Mrs. A. Geetha, SRMIST
2. Mr.Sudharsan, L&T, sudharsand@Intecc.com	2. Dr. P. Somasundaram, CEG, Anna University, mpsomasundaram@annauniv.edu	2. Dr. C. Subramani, SRMIST

Course Code	18EEE407T	Course Name	POWER SYSTEM HARMONICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand the fundamentals and standards of harmonics				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Study the various sources of harmonics				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Enumerate the effects of harmonics in various equipments																					
CLR-4 :	Classify the methods of power system harmonics mitigation																					
CLR-5 :	Explore the approach of harmonics system study																					
CLR-6 :	Develop an overall knowledge about harmonics in power system																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	Identify the harmonic indices and study the characteristics of harmonics				2	80	75	H	-	-	-	-	-	-	H	-	-	-	-	-	-	H
CLO-2 :	Understand the level of harmonics in equipments and devices				3	80	75	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-3 :	Familiarize the harmonics effects in critical loads and equipments				3	80	75	H	-	-	-	-	-	-	-	-	-	-	M	M	-	-
CLO-4 :	Study and compare the various filters used for harmonics mitigation				3	80	75	H	H	M	-	-	-	-	-	-	-	-	M	M	-	-
CLO-5 :	Simulate the harmonics analysis in a low/medium voltage system				3	80	75	H	H	M	M	-	-	-	-	-	-	-	M	M	-	-
CLO-6 :	Design a harmonic mitigation for the industrial and commercial applications				3	80	75	H	H	M	M	-	-	-	M	-	-	-	M	M	M	M

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction	Traditional sources	Harmonics effects – Thermal losses	Harmonics Filters	Harmonics modeling of system components - Generator.
	SLO-2	Basics of harmonic theory	Transformers	Copper, core and dielectric losses	Passive filters	Harmonics modeling of Shunt capacitors
S-2	SLO-1	Representation of Harmonics	Rotating machines	Harmonics effects on power system equipment	Single tuned filters	Harmonics modeling of Loads
	SLO-2	Fourier series – coefficients	Arc furnaces	Capacitor bank	Double tuned filters	Harmonics modeling of Induction motor
S-3	SLO-1	Fourier transform	Modern sources	Transformers	Damped filters	Harmonics modeling of Transformer with network
	SLO-2	Discrete Fourier transform (DFT)	Power electronics devices	Neutral grounding overloading	Detuned filters	Harmonics modeling of Transformer with different configuration
S-4	SLO-1	Fast Fourier transform (FFT)	Rectifiers	Rotating machines	Series tuned filter design	Harmonics modeling of Transmission line model
	SLO-2	Examples of harmonic estimation using FFT	A.C. Regulators	Pulsating torque	Impedance plot of series tuned filter design	Harmonics modeling of Transmission line with network
S-5	SLO-1	Characteristics of harmonics in power system – Symmetry	Power converters – Six pulse converters	Power electronics devices	Second order damped filters	Examples – transmission line
	SLO-2	Phase sequence	Six pulse converters - Analysis	Power converters	Impedance plot of second order damped filter design	Examples – Problems on load
S-6	SLO-1	Voltage and current distortion factors - Total harmonic distortion (THD)	Twelve pulse converters	Harmonics on power system protection	Active filters	Harmonics analysis using spread sheet
	SLO-2	Real, Reactive and Apparent power	Twelve pulse converters - Analysis	Unexpected relay operation	Characteristics of active filters	Analysis of harmonics analysis using spread sheet
S-7	SLO-1	Distortion power; Power factor	Inverters	Harmonics effects on consumer equipment	Other methods of mitigation	Simulation of harmonics analysis
	SLO-2	Total influence factor (TIF) and I*T Product	Cycloconverters	UPS	Transformer connection	harmonics resonance

S-8	SLO-1	Voltage THD limits – IEEE standards	Thyristor controlled reactors	Lighting loads	Network topology reconfiguration	Simulation of harmonics filters
	SLO-2	Voltage THD limits – IEC standards	Static VAR compensator	Electronics devices	Increase of supply mode stiffness	Analysis of simulation output of harmonics filters
S-9	SLO-1	Current THD limits – IEEE standards	Effect of transformer connection on harmonics	Harmonic interference with Communication	Harmonic cancellation through use of multi pulse converters	Case study
	SLO-2	Current THD limits – IEC standards	Star-Delta and Delta-Star	Microwave links, telephone interference	Series reactor as harmonic attenuator elements	Analysis of Case study

Learning Resources	1. Power system harmonics ,Fundamentals, Analysis and filter design – George J. Wakileh – Reprinted 2010 2.Power system harmonics, J. Arrillaga and N.R.Watson 1998 – Reprinted 2000 3. Power system harmonics, Francisco_De_La_Rosa – 2006	4. Electrical power system quality, R C Dugan, Mark F.Mcgranaghan, Surya Santoso, H.Wayne Beaty - 5. Harmonics analysis software user manual 6. https://web.ecs.baylor.edu/faculty/grady/Understanding_Power_System_Harmonics_Grady_April_2012

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Evaluate Create	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Dr. K. Karthikeyan, ABB Ltd., k.karthikeyan@in.abb.com	Dr.B.Chitti Babu, IIT, bcbabu@iitdm.ac.in	Mr. D.Ravichandran, SRMIST, ravichandran.d@ktr.srmuniv.ac.in
Dr. Swaroop Gajare, Power Systems Technologies, Eaton Research Labs	Dr. M.M. Rajan Sing ravel, NIT, rajan.singaravel@nitpy.ac.in	Dr. M. Senthilkumar, SRMIST, senthilkumar.mu@ktr.srmuniv.ac.in

Course Code	18EEE408T	Course Name	HVDC AND EHVAC SYSTEMS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	i	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:		
CLR-1 :	Outline the concepts of Extra High Voltage transmission systems			
CLR-2 :	Explain the general background and operational concepts in EHVAC Transmission Systems			
CLR-3 :	Give idea about the factors affecting EHV transmission and the protection of EHV lines			
CLR-4 :	Impart knowledge about HVDC Transmission systems			
CLR-5 :	Expose to the concept of harmonics and basis of protection for HVDC Systems.			
CLR-6 :	Know the detailed background of extra high voltage AC transmission and high voltage DC transmission			

Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:		
CLO-1 :	Understand the basic concepts of Extra High Voltage Transmission.			
CLO-2 :	Analyze the general background of EHVAC Transmission Systems			
CLO-3 :	Acquire knowledge in operational concepts and protection in EHVAC Transmission Systems			
CLO-4 :	Infer the significance of HVDC Transmission and its modern trends and applications.			
CLO-5 :	Gain idea in the general principle of HVDC control and harmonic elimination in HVDC Systems			
CLO-6 :	Interpret the operational concepts of high voltage AC and DC transmission			

Learning		
1	2	3
Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)

Program Learning Outcomes (PLO)														
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
H	-	-	-	-	-	M	L	-	-	-	-	M	M	L
H	M	M	-	-	-	-	-	-	-	-	-	M	M	-
H	M	M	-	-	-	M	L	-	-	-	-	M	M	L
H	-	-	-	-	-	-	-	M	M	-	-	M	M	-
H	M	M	-	M	-	-	-	-	-	-	-	M	H	-
H	M	M	-	M	-	M	L	M	M	-	-	H	M	L

Duration (hour)		9		9		9		9	
S-1	SLO-1	Brief Description of Energy Sources	Power handling capacity of AC transmission line	Effects of corona	Choice of HVDC Transmission	Pulse number			
	SLO-2	Development of Energy sources	Line losses of AC transmission line	Attenuation of travelling waves due to corona loss	Basic outline of HVDC Transmission	Choice of Converter Configuration			
S-2	SLO-1	Introduction to EHV transmission	Introduction to mechanical considerations in transmission line performance	Generation of audible noise	Comparison of Economics, Technical Performance of DC power Transmission	Introduction to Graetz circuit			
	SLO-2	Standard Voltage levels of Transmission systems	Types of vibrations and oscillations	Characteristics and its limitations of audible noise	Comparison of Reliability of DC power Transmission	Simplified analysis of Graetz circuit			
S-3	SLO-1	Hierarchical levels for Transmission systems	Concept of bundled conductors	Generation of corona pulses	Description of HVDC transmission system	Concept of HVDC link Control			
	SLO-2	Costs of Transmission Lines And Equipment	Properties of Bundled conductors	Properties of corona pulses	Types of HVDC links	Principles of HVDC link control			
S-4	SLO-1	Necessity for EHV transmission	Surface voltage gradient on single conductor bundles	Limits for radio interference fields	Components of a Converter station	DC Breaker – Basic concepts of DC circuit interruption			
	SLO-2	Challenges involved in EHV transmission	Derivation of Surface voltage gradient on single conductor bundles	Evaluation of radio interference using Cigre Formula	Description of a Converter station	DC Breaker –Characteristics and Applicationbns			
S-5	SLO-1	Operational Aspects of EHV AC transmission	Surface voltage gradient on double conductor bundles	Concept of RL filter to block corona enery	Basic concepts of multi-terminal HVDC system.	AC Filter –Criteria of design			
	SLO-2	Electrical characteristics of EHV cables	Derivation of Surface voltage gradient on double conductor bundles	Design of RL filter	Types and potential applications of multi-terminal HVDC system.	AC Filter –Ratings of filter components and protection of filters			
S-6	SLO-1	Gas insulated EHV transmission lines	Basic concepts of reactive power compensation	Interference to TV reception from EHV lines	Effects of proximity of ac and dc transmission lines	DC Filter –Criteria of design			
	SLO-2	Properties of SF ₆ gas	Principles of shunt compensation	Discharges from an EHV line causing television interference	HVDC transmission based on Voltage Source Converters	DC Filter –Hybrid active filter for DC filtering			
S-7	SLO-1	Effect of Power-Frequency Magnetic Fields on Human Health	Principles of series compensation	Concept of lightning strokes	Merits of HVDC System	Protection Against Over Currents, Over Voltages			

	SLO-2	Effect of High Electro Static Field on Humans, Animals, and Plants	Sub-synchronous resonance in compensated lines	General principles of the lightning protection problem	Limitations of HVDC System	Protection Systems in HVDC Substation
S-8	SLO-1	Introduction to line parameters	Counter measures for Sub-synchronous resonance problem	Arresters used for EHV systems	Applications of HVDC transmission	Necessity of simulation of a dynamic system
	SLO-2	Determination of resistance of EHV lines	Improvement of system performance due to reactive power compensation.	Protective characteristics of lightning arresters	Modern Trends in HVDC transmission	Tools for simulation of a dynamic system
S-9	SLO-1	Determination of inductance of EHV lines	Comparison of Overhead and Underground lines	Operating characteristics of lightning arresters	Seminar on case Studies of HVDC links in the world- I	Digital Dynamic Simulation of Converters
	SLO-2	Determination of capacitance of EHV lines	Examples of Giant power pools in the world	Insulation Coordination based on lightning	Seminar on case Studies of HVDC links in the world- II	Digital Dynamic Simulation of DC Systems

Learning Resources	1. Rakosh Das Begamudre, Extra High Voltage AC Transmission Engineering, Fourth Edition , New Age International(P) Limited,Publishers.,2011 2. Padiyar K.R., HVDC Power Transmission Systems, Third Edition,New Age International (P) Limited Publishers.,2015.	3. Chakrabarti.A , M.L.Soni,P.V.Gupta,U.S.Bhatnagar, PowerSystem Engineering, DhanpatRai& Co., 2010. 4. Sunil S.Rao, Switchgear Protection and Power Systems, 13 th edition,Khanna Publishers,2008. 5. http://www.nptelvideos.com/course.php?id=480
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1.Dr.K.Karthikeyan, ABB India Ltd., k.karthikeyan@in.abb.com	1. Dr Subhransu Sekhar Dash, Government College of Engineering, Keonjhar, Subhransudash_fee@gcekjir.ac.in	1. Ms. E. Annie Grace, SRMIST
2. Mr.Senthilkumar,ATI,rskrd1962@gmail.com	2.Dr. A. Venkadesan, NIT Puducherry, venkadesan@nitpy.ac.in	2. Dr. S. Padmini, SRMIST

Course Code	18EEE409T	Course Name	POWER SYSTEM DYNAMICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical & Electronics Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																	
CLR-1 :	Enumerate the significance of stability study and its classification				Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLR-2 :	Explain the concept of detailed modelling of synchronous machine for stability studies									Expected Proficiency (%)	Expected Attainment (%)	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Understand and model the various excitation system																								
CLR-4 :	Examine the small-signal stability study of single-machine infinite bus (SMIB) system																								
CLR-5 :	Discuss the Sub-synchronous oscillations and countermeasures for small-signal stability																								
CLR-6 :	Develop the mathematical model of synchronous machine and assessment of small-signal stability																								
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																							
CLO-1 :	Explain the basics of stability analysis and its types				1	75	75	H	H	-	-	-	-	-	-	-	-	-	-	-	M	M	-		
CLO-2 :	Apply the idea of Park's transformation and express the voltage and flux linkage equation, torque and power equation of synchronous machine in rotor reference frame.				3	75	75	H	H	L	H	H	-	-	-	-	-	-	-	-	M	M	-		
CLO-3 :	Describe the excitation system, types and its modelling for stability studies				3	75	75	H	H	L	H	H	-	-	-	-	-	-	-	-	M	M	-		
CLO-4 :	Analyze the small-signal stability for the SMIB system with classical model of synchronous machine				3	75	75	H	H	H	H	H	-	-	-	-	-	H	-	-	M	M	-		
CLO-5 :	Infer Sub-synchronous oscillations and the enhancement methods of small-signal stability				3	75	75	H	H	H	H	-	-	-	-	-	-	-	-	-	M	M	-		
CLO-6 :	Design the mathematical model of synchronous machine and evaluate the small-signal stability				3	75	75	H	H	H	H	H	-	-	-	-	-	H	-	-	M	M	-		

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Introduction –Basic elements of power system	Introduction to Three phase synchronous machine	Excitation system requirements	Small-signal stability of dynamic Systems	Introduction to Sub-synchronous oscillations
	SLO-2 Structure of power system-power system control	RMF, MMF waveform	Basic functions of Excitation system	Local, finite and global stability	Turbine-generator torsional characteristics
S-2	SLO-1 Operating states of power system and control strategies	Winding model	Elements of an excitation system	Linearization	Structure of typical lumped mass shaft system model
	SLO-2 Normal design contingencies	Modelling assumptions,	Control functions of an excitation system	State-space representation	Shaft model representation
S-3	SLO-1 System design for stability	Sign convention	Protective functions of an excitation system	Mathematical analysis of stability	Equations of inertia constant-Torsional stiffness-Damping coefficient
	SLO-2 Classifications of stability	Stator voltage equations in abc coordinates	Types of Excitation System (ES)	Eigen properties of the state matrix	Derive the Shaft system equations between turbine and generators
S-4	SLO-1 The stability phenomena: small-signal and transient stability	Rotor voltage equations in abc coordinates	DC excitation system-(DC1A)	Eigenvalues of the state matrix	Computation of damping and stiffness coefficient for a five mass model system
	SLO-2 Basic assumptions made in stability studies	Stator flux linkage equations in abc coordinates	DC excitation system with amplitudyne	Eigenvectors, participation factor, modal matrices	Computation of each shaft section torque for a five mass model system
S-5	SLO-1 Rotor dynamics and the swing equation	Rotor flux linkage equations in abc coordinates	AC Excitation system	Eigenvalues and stability-trajectory behaviour	Torsional natural frequencies
	SLO-2 Transient stability- Illustrate with Single machine connected to infinite bus (SMIB) system	Stator self-inductance calculation	Field-Controlled Alternator Rectifier ES	Mode shape and participation factor.	Example of torsional characteristics of coal-fired unit with static exciter
S-6	SLO-1 Numerical problem on transient stability analysis of SMIB system	Stator to rotor Mutual-inductance calculation	Stationary rectifier based AC Exciter	Controllability and observability-concept of complex frequency	Small-signal stability enhancement-methods

	SLO-2	Power versus rotor angle curve, Power-rotor angle equations-(during a fault, after fault clearing and removal of the faulted circuit)- Numerical problem	Rotor to Stator Mutual-inductance, Rotor self-inductance calculation	Alternator-supplied controlled-rectifier ES	State-space form of Synchronous machine's swing equation	Different types of Power system stabilizers (PSS)- Need of PSS
S-7	SLO-1	Transient stability assessment of SMIB system by Equal-Area Criterion	Park's transformation	Rotating type- Brush less Excitation system	Case study on small signal stability analysis of Single-Machine Infinite Bus (SMIB) with classical machine model	Stabilizers based on shaft speed signal
	SLO-2	Computation of Critical clearing angle-critical clearing time-Numerical problem	Voltage and flux linkage equations in dqo reference frame (Park's equations)	Static Excitation system	Block diagram representation of SMIB system	Delta-P-Omega stabilizer
S-8	SLO-1	Introduction to Voltage stability	Steady state analysis-voltage, Current, and flux linkage relationships.	Potential-source controlled rectifier-static type excitation system	Calculation of synchronizing torque coefficient, system matrix, eigenvalues and participation factor	Frequency based stabilizer, Digital stabilizer
	SLO-2	Voltage collapse- Illustrate with two bus radial system	Phasor representation-Steady state equivalent circuit.	Modelling and computer simulation of excitation system	The effect of damping torque in the stability of SMIB system with classical machine model	Enhancement of stability by Excitation control design
S-9	SLO-1	Large disturbance and small disturbance	Simplified model (constant flux linkage)- Classical machine model.	Detailed excitation system model- DCIA	Speed and rotor angle time response of SMIB system with classical machine model	Exciter gain, Phase-lead compensation, stabilizing signal washout, Stabilizer gain-Stabilizer limits
	SLO-2	Voltage stability- Mid-term and Long-term stability	Steady State analysis of Synchronous machine using simulation software	AC1A and AC4A model of excitation system	Synchronous machine model using suitable simulation software	General observation on excitation control design

Learning Resources	1. P.Kundur, Power System Stability and Control, McGraw Hill Inc, New York, 1995. 2. R.Ramamurthy, Power System Dynamics: Analysis and Simulation, PHI Publishers, Delhi, 2nd edition 2013. 3. M.A.Pai and W.Sauer, Power System Dynamics and Stability, Pearson Education Asia, India, 2002.	4. K.R.Padiyar, Power System Dynamics, Stability & Control, 2nd Edition, B.S. Publications, Hyderabad, 2002. 5. P.M Anderson and A.A Fouad, Power System Control and Stability, Iowa State University Press, Ames, Iowa, 1978. 6. https://nptel.ac.in/courses/108102080/
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1.Dr. Sharon Ravichandran, ABB Ltd., Chennai,sharonravi87@gmail.com	1. Prof. K.Shanthi Swarup, IITM, Chennai, ksswarup@iitm.ac.in	1.Mr. D. Maharajan, SRMIST
2.Dr.V.P.Boopathi, Powersys., Chennai,Boopathivp@gmail.com	2.Prof. R.P.Kumudini Devi, Anna University, kumudini@annauniv.ac.in	2.Dr. D. Sattianandan, SRMIST

Course Code	18EEE410T	Course Name	MODERN POWER SYSTEM ANALYSIS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18EEEC303T	Co-requisite Courses	NIL	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:		Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Explain the numerical method involved in for optimal power flow analysis			Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Analyse the significance of contingency analysis and power system security states																						
CLR-3 :	Outline the concepts of distribution system																						
CLR-4 :	Understand and analyze the different concepts of stability																						
CLR-5 :	Demonstrate the concepts of state estimation of power systems																						
CLR-6 :	Evaluate the overall analysis of power system problems starting from transmission to distribution																						
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																					
CLO-1 :	Acquire the knowledge on the numerical methods of optimal power flow analysis			3	75	75		H	M	M	M	M	-	-	-	-	-	-	-	-	M	M	-
CLO-2 :	Analyse the concepts of power system security			3	75	75		H	M	M	M	M	-	-	-	-	-	-	-	-	M	M	-
CLO-3 :	Familiarize the knowledge on distribution system and its application			3	75	75		H	M	M	M	M	-	-	-	-	-	-	-	-	M	M	-
CLO-4 :	Categorize the study of stability analysis			3	75	75		H	M	M	M	-	-	-	-	-	-	-	-	-	M	M	-
CLO-5 :	Gain knowledge on the concept of state estimation in power systems			3	75	75		H	L	L	-	-	-	-	-	-	-	-	-	-	M	M	-
CLO-6 :	Create ,design and analyze the power system issues starting from transmission to distribution			3	75	75		H	M	M	M	M	-	-	-	-	-	-	-	-	M	M	-

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Formulation of power flow problem	Overview of security analysis	Basic concepts of stability	Introduction - Primary distribution systems
	SLO-2	Solution through Newton-Raphson method	Need for Power system Security	Classifications of stability	Types of primary distribution systems
S-2	SLO-1	Problems solving- Newton-Raphson method	Factors affecting power system security	Small signal stability of a single machine infinite bus system	Secondary distribution systems
	SLO-2	Fast decoupled power flow solutions	Introduction to Contingency analysis	Small signal stability-solving numerical	Types of Secondary distribution systems
S-3	SLO-1	Problems solving-Fast Decoupled method	Contingency analysis-Addition and removal of one line	Transient stability-Runge kutta method	Ring main distribution systems
	SLO-2	Comparison of Load flow methods	Computation of bus impedance matrix from bus admittance matrix	Runge kutta method - Solving numericals	Ring main distribution systems-solving numerical
S-4	SLO-1	Power flow studies-simulation	Problem solving-contingency analysis	Runge kutta method - Solving numericals	Load flow of radial distribution networks-solving numerical
	SLO-2	Power flow studies-simulation	Problem solving-contingency analysis	Runge kutta method - Solving numericals	Load flow of radial distribution networks - solving numerical
S-5	SLO-1	DC power flow solutions	Calculation of new bus voltage due to addition and removal of one line-simulation	Transient stability- Simulation	General design characteristics of distribution system
	SLO-2	AC-DC power flow model	Solving numericals	Voltage stability	Primary distribution system - design
S-6	SLO-1	Optimal Power Flow-Introduction	Linear sensitivity factors	Transmission characteristics	Primary distribution system - design
	SLO-2	Gradient method	Problem solving-Linear sensitivity factors	Transmission characteristics	Voltage,scheme and feeder size selection solving numerical
S-7	SLO-1	Problem solving-Gradient method	Problem solving-Linear sensitivity factors	Generator characteristics	Secondary distribution system - design
	SLO-2	Newton's method	AC power flow method	Generator characteristics	Lamp flicker-Origin
					Problem solving Network observability

S-8	SLO-1	Security constrained optimal power flow	Problem solving-AC power flow method	Load characteristics	Types of flicker and remedial measures	Pseudo measurements
	SLO-2	Optimal generation scheduling	Contingency selection	Load characteristics	Design of capacitors to distribution systems	State estimation including Phasor measurement units
S-9	SLO-1	Problem solving-optimal generation scheduling	Contingency ranking	Characteristics of reactive compensating devices.	Design of capacitors to distribution systems-solving numerical	State estimation including Phasor measurement units
	SLO-2	Optimal unit commitment	Security analysis and contingency evaluation	Typical scenario of voltage collapse	Design of capacitors to distribution systems-solving numerical	Application of state estimation in power system in load forecasting

Learning Resources	1. Pai M.A. and Dheeman Chatterjee, Computer Techniques in Power System Analysis, Mc Graw Hill Education (India) Private Limited, New Delhi, 2016.	4. Prabha Kundur, Power system stability and control, Electrical power research institute-power system engineering series.
	2. John.J.Grainger, William D. Stevenson, Jr, Power System Analysis, Mc Graw Hill Education (India) Private Limited, New Delhi, 2015.	
	3. Allen Wood J.and Bruce.F. Wollenberg, Power Generation Operation and Control, 2nd Edition, John Wiley & Sons, New York, 1996.	5. Mukhtar Ahmad, Power System State Estimation, Lap Lambert Acad Publishers, 2013.

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

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1.Dr.V.P.Boopathi, Powersys., Chennai,Boopathivp@gmail.com	1.Dr. K. S. Swarup, IITM, Chennai, ksswarup@iitm.ac.in	1.Dr. S. Padmini, SRMIST
2.Dr. T. Prakash, TNEB, Mt. Road, prakash.thyagarajan@tnebnet.org	2.Dr. P. Somasundaram, Anna University, mpsomasundram@annauniv.edu	2.Dr. K. Vijayakumar, SRMIST

Course Code	18EEE411T	Course Name	POWER SYSTEM DEREGULATION	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Electrical & Electronics Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Understand the basics of deregulation and economics of power system	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2 :	Learn Unit commitment, optimal power flow and its constraints																							
CLR-3 :	Understand the activity of GENCO and independent system operator																							
CLR-4 :	Get familiarized with the various transmission services																							
CLR-5 :	Gain knowledge on the role of security and congestion management in deregulated power system.																							
CLR-6 :	Create overall restructuring of power system starting from generation to power transmission and distribution																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:						Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3		
CLO-1 :	Illustrate the basics of deregulation in conventional power system	2	75	75	H	H	-	-	-	-	-	-	-	-	M	-	-	-	-	H	H	-		
CLO-2 :	Use the concept of Unit commitment, optimal power flow in electric power system	2	75	75	H	H	-	-	-	-	-	-	-	M	-	-	-	-	-	H	H	M		
CLO-3 :	Apply the knowledge on the various role of ISO in deregulated environment	2	75	75	H	M	-	-	-	-	-	-	-	-	-	-	-	-	-	H	H	-		
CLO-4 :	Analyze various transmission system problems	2	75	75	H	M	-	-	-	-	-	-	-	-	-	-	-	-	-	H	H	-		
CLO-5 :	Utilize the basic role of security and congestion management and its solutions	3	75	75	H	M	M	M	-	-	-	M	-	-	-	-	-	-	-	H	H	M		
CLO-6 :	Analyze the power system generation and transmission losses with various components in deregulated system	3	75	75	H	M	M	M	-	-	-	M	-	-	-	-	-	-	-	H	H	M		

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction- Deregulation	Optimal Power Flow problem model	Operational planning activities of ISO	embedded cost based transmission pricing	Introduction to Congestion,
	SLO-2	Structure of a deregulated electricity system	Limits on Real and Reactive power flow	Single Auction Market	Postage stamp method	reasons for transfer capability limitation
S-2	SLO-1	Different entities in deregulated electricity markets	OPF Examples (quantitative analysis)	Double Auction Market	MW mile method(quantitative analysis)	Importance of congestion management
	SLO-2	Power system Deregulation in different countries	Characteristic features of OPF & its applications	ISO in Pool markets	Incremental cost based transmission pricing	Features of congestion management
S-3	SLO-1	competitive electricity markets	Unit commitment in conventional electricity market	ISO in Bilateral markets	Short run marginal cost based method	Classification of congestion management methods
	SLO-2	Benefits from a competitive electricity market	UC Constraints	Operational planning activities of GENCO	Long run marginal cost based method	Calculation of ATC
S-4	SLO-1	Classification of electricity markets	price based Unit commitment Design in deregulated electricity market	GENCO in pool and bilateral markets	Revenue Reconciliation	Economic instruments for Handling congestion
	SLO-2	Pool co and Bilateral Markets	Constraints in price based Unit commitment	Market participation issues	Transmission open access and pricing mechanisms in various countries	Congestion pricing methods
S-5	SLO-1	effects of deregulation	Competitive bidding., strategic bidding	Power exchange	Cost components of Transmission System Operator (TSO)	Market splitting
	SLO-2	Pre dispatch and instantaneous dispatch	parameters affecting bidding strategies	market operations	Transfer capability on open access transmission system	counter trade

S-6	SLO-1	Review of Economic Load Dispatch problem (ELD)	Formation of power pools	Market power- standard cost	Developments in international transmission pricing	Transmission rights
	SLO-2	Constraints in ELD problem	Economic Exchange of Energy	Price forecasting	Transmission Security management in deregulated environment	Inter zonal congestion management
S-7	SLO-1	Economic Load Dispatch problem In Deregulation	Multi area Joint Dispatch (quantitative analysis)	Power wheeling	Scheduling of spinning reserves in deregulated electric market	Intra zonal congestion management
	SLO-2	Economic Load Dispatch problem (quantitative analysis)	Energy Brokerage system	Types of wheeling transactions	Introduction of ancillary services	Price area congestion management
S-8	SLO-1	Conditions for optimum	Role of Independent system operator (ISO).	Transmission open access and types	Types of Ancillary services	Capacity alleviation method
	SLO-2	Significance of Lagrange Multipliers	Types of electricity market	Cost components in transmission	Classification of ancillary services	Contingency reserve services
S-9	SLO-1	Security constrained Economic dispatch	Structure of UK Electricity deregulated market	pricing of power transactions	Ancillary services management in various countries	Indian electricity act
	SLO-2	Preventive and corrective rescheduling	Structure of Nordic Electricity deregulated market	Ideal Wheeling Rate	Interruptible load options for security management	Indian power exchange

Learning Resources	1. KankarBhattacharya, Operation of Restructured Power Systems, Kluwer academic publishers, 2001. 2. Mohammad Shahidehpoura and Muwaffaq A Iomoush, Restructured Electric Power System operation trading and volatility, Macsel Dekker Inc, 2001 3. Zaccour.G. Deregulation of Electric Utilities, Kluwer academic publishers, 1998 . 4. Xiao ping Zhang, Restructured Electric Power Systems: Analysis of Electricity Markets with Equilibrium Models, IEEE press, 2010 5. THE ELECTRICITY ACT, 2003, http://www.cercind.gov.in/Act-with-amendment.pdf 6. https://nptel.ac.in/courses/108101005/ .
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1.Dr.S.Sambath, TANGEDCO,Tamilnadu, eses.eng@gmail.com	1.Dr. M.P.Selvan, NIT Trichy, selvanmp@nitt.edu	Mr. K.Selvakumar, SRMIST
2.Mr.Sudharsan, L&T, sudharsand@Intecc.com	2.Dr Subhransu Sekhar Dash, Government College of Engineering, Keonjhar, Subhransudash_fee@gcekr.ac.in	Dr.K.Vijayakumar, SRMIST

Course Code	18EEE317T	Course Name	SYSTEM THEORY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18EEEC301J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical & Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Model and represent the systems in state variable form	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Understand the need of controllability and observability																		
CLR-3 :	Provide adequate knowledge in the phase plane analysis																		
CLR-4 :	Give a basic knowledge in describing function analysis																		
CLR-5 :	Educate on stability analysis of systems using Lyapunov's theory																		
CLR-6 :	Create a mindset to model and analyze the system stability using system theory concepts																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Apply the state space method to model Linear and Nonlinear system	3	75	75	H	H	M	M	-	-	-	-	-	-	-	-	M	M	-
CLO-2 :	Test the controllability and observability of the system	3	75	75	H	H	M	M	-	-	-	-	-	-	-	-	M	M	-
CLO-3 :	Apply the concepts of phase plane analysis to linear and Nonlinear system	3	75	75	H	H	M	M	-	-	-	-	-	-	-	-	M	M	-
CLO-4 :	Formulate the Describing function for Nonlinear system	3	75	75	H	H	M	M	-	-	-	-	-	-	-	-	M	M	-
CLO-5 :	Determine the stability of Nonlinear system using Lyapunov and Variable- Gradient Method	3	75	75	H	H	H	H	-	-	-	-	-	-	-	-	M	M	-
CLO-6 :	Apply system theory concepts to model and analyze real time system	3	75	75	H	H	H	H	-	-	-	-	-	-	-	-	M	M	-

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Concept of State- tate equation for Dynamic Systems	Concept of Controllability & Observability	Features of linear and non-linear systems	Basic concepts of describing functions	Introduction to Stability Analysis of Nonlinear System
	SLO-2 Time invariance and linearity- Non uniqueness of state model	Controllability Test for Time Varying and Time In varying Case: Minimum Energy Control	Common physical non-linearity's	Describing Function and Harmonic Balance	Equilibrium Points
S-2	SLO-1 State Diagram	Observability test for Time Varying and Time In- varying system	Methods of linearizing non-linear systems	Describing function analysis of nonlinear systems	Stability in the sense of Lyapunov
	SLO-2 Physical System: Linear Continuous Time model	Principle of Duality	Introduction to phase portraits	Importance of Describing Function	BIBO Stability
S-3	SLO-1 Physical System: Nonlinear system Model	Controllability of State model in Jordan Canonical Form	Concept of phase portraits	Derivation of describing functions for Hysteresis non-linearity	Stability of Linear Time Invariant Systems
	SLO-2 Local Linearization of Nonlinear Model	Observability of State model in Jordan Canonical Form	Singular points	Derivation of describing functions for Dead zone non-linearity	Problem Solving to find stability of Linear Time Invariant System
S-4	SLO-1 Solution of Nonlinear Continuous Time State Equation	Controllability and Observability Canonical Forms of State mode	Existence of Limit cycles	Basics of Backlash non-linearity	Introduction to Nonlinear Continuous Time Autonomous Systems
	SLO-2 Runge Kutta Method	Controllable Subspace, Unobservable Subspace	Use of Limit cycle in control system	Derivation of describing functions for Backlash non-linearity	Equilibrium Stability of Nonlinear Continuous Time Autonomous Systems
S-5	SLO-1 Solution of Linear Time Varying Continuous Time State Equation	Canonical Decomposition Theorem	Construction of phase portraits	Derivation of describing functions for Ideal Relay non-linearity	Basics of the Direct Method of Lyapunov

	SLO-2	<i>The Homogeneous Solution</i>	<i>Input- Output Maps from State Model for Linear and Nonlinear System</i>	<i>Problem solving in phase portraits</i>	<i>Derivation of describing functions for Hysteretic Relay non-linearity</i>	<i>Direct Method of Lyapunov for Linear Continuous-Time Autonomous Systems</i>
S-6	SLO-1	<i>Evaluation of State Transition Matrix</i>	<i>Output Controllability</i>	<i>Phase plane analysis of linear System</i>	<i>Basics of Saturation non-linearity</i>	<i>Finding Lyapunov Functions for Nonlinear Continuous Time Autonomous Systems</i>
	SLO-2	<i>Non Homogeneous Solution</i>	<i>Dead-beat Controller</i>	<i>Problem solving in Phase plane for linear system</i>	<i>Derivation of describing functions for Saturation non-linearity</i>	<i>Krasovskii Method of Stability Analysis</i>
S-7	SLO-1	<i>Solution of Linear Time In-varying Continuous Time State Equation</i>	<i>Reducibility of Linear System</i>	<i>Phase plane analysis of Nonlinear System</i>	<i>General Conditions for stability of Nonlinear system</i>	<i>Finding Lyapunov Functions for Nonlinear Continuous Time Autonomous Systems</i>
	SLO-2	<i>Evaluation using Similarity Transform</i>	<i>Reducibility of Nonlinear System</i>	<i>Problem solving in Phase plane for Non-linear system</i>	<i>Describing function Conditions for stability of Nonlinear system</i>	<i>Variable- Gradient Method</i>
S-8	SLO-1	<i>Solution of Linear Time In-varying Continuous Time State Equation</i>	<i>Linear System Realizations: Phase Variable Canonical Form</i>	<i>Isocline method</i>	<i>Possibilities of Oscillations occurrence in Non Linear System</i>	<i>Transients in Non Linear System</i>
	SLO-2	<i>Evaluation using Cayley Hamilton Technique</i>	<i>Nonlinear System Realizations: Phase Variable Canonical Form</i>	<i>Importance of Isocline Method in Non Linear control system</i>	<i>Stability analyses of oscillations in Nonlinear system</i>	<i>Use of Lyapunov to Estimate Transients</i>
S-9	SLO-1	<i>Solution of Linear Time In-varying Continuous Time State Equation</i>	<i>Linear System Realizations: Jordan Canonical Form</i>	<i>Basics of Inverted Pendulum</i>	<i>Introduction to DC Motor Model</i>	<i>Stability Analysis Case Study related with Power Engineering Application</i>
	SLO-2	<i>Evaluation using Inverse Laplace Transform</i>	<i>Nonlinear System Realizations: Jordan Canonical Form</i>	<i>Example of Nonlinear System: Inverted Pendulum on a Cart</i>	<i>Describing function analysis of DC Motor with Permanent Magnet</i>	<i>Stability Analysis Case Study related with Power Engineering Application</i>
Learning Resources		<ol style="list-style-type: none"> 1. Katsuhiko Ogata, <i>Modern Control Engineering</i>, 5th ed., Prentice Hall, 2017. 2. M. Gopal, <i>Modern Control System Theory</i>, 3rd ed., New Age International, 2014. 3. Marquez Horacio J Marquez, <i>Nonlinear Control Systems: Analysis and Design</i>, 2nd ed., Wiley Publications, 2012. 4. Zoran Vukic, Ljubomir Kuljaca, Dali Donlagic and Sejid Tesnjak, <i>Nonlinear Control Systems</i>, Marcel Dekker Inc, 2007. 5. Richard C.Dorf, Robert H.Bishop, <i>Modern control system theory</i>, 13th ed., Pearson Education Ltd, 2016. 6. https://www.edx.org/course/introduction-state-space-control-mitx-6-302-1x 				

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30 %	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40 %	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30 %	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry		Experts from Higher Technical Institutions
1. Ms.R.Vijayalakshmi, C2C Engineering, vijayalakshmi@c2cengineering.co.in		Dr.S.K.Patnaik, CEG, Anna University, skpatnaik@annauniv.edu
2. Dr. S. Paramasivam, Danfoss, Industries Pvt Ltd, paramsathya@yahoo.com		Dr. A. Venkadesan, NIT, Pondicherry, venkadesan@nitpy.ac.in
		Internal Experts
		Dr.R. Narayanamoorthi, SRMIST
		Dr.N. Chellammal, SRMIST

Course Code	18EEE318T	Course Name	ROBUST CONTROL SYSTEM	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18EEEC301J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:		Learning			Program Learning Outcomes (PLO)																	
CLR-1 :	Introduce the basics of Robust control principles			Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Solve the various problems in linear systems different stabilization methods						Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3			
CLR-3 :	Compute the performance of linear systems by the measured parameters						H	M	M	-	-	-	-	-	-	-	-	-	-	H	M	-		
CLR-4 :	Understand the performance and limitations of Feedback control						H	H	M	M	M	-	-	-	-	M	-	-	-	H	M	-		
CLR-5 :	Identify the solutions for H^∞ control and μ Synthesis						H	M	M	M	-	-	-	-	M	M	-	-	-	H	M	-		
CLR-6 :	Create a overall structure for Robust control system						H	H	M	M	M	-	-	-	M	M	-	-	-	H	M	-		
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1 :	Understand the basics of Robust control principles			2	80	75																		
CLO-2 :	Calculate the parameters of Linear systems by using different stabilization methods			3	80	75																		
CLO-3 :	Analyze the performance of linear systems by the measured parameters			3	80	75																		
CLO-4 :	Acquire knowledge on Observer, Feedback control systems			3	80	75																		
CLO-5 :	Analyze the basics of H^∞ control and μ Synthesis and its solution			3	80	75																		
CLO-6 :	Design a Robust control system for Real time Control Applications			3	80	75																		

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Introduction Engineering Background of RobustControl	Introduction Fundamentals ofLinearSystem	Introduction to Stabilization ofLinearSystems	Introduction to Performance Limitation ofFeedbackControl	Introduction to H^∞ Control & μ Synthesis
	SLO-2 A Brief History of RobustControl	Structural Properties ofDynamicSystem	StateFeedback	PoissonIntegralFormula	ControlProblem and H^∞ Control Norm
S-2	SLO-1 Methodologies of RobustControl	Stability - Bounded-InputBounded-OutputStability	Observer - Full-OrderObserver	All-Pass and Minimum-PhaseTransferFunctions	Input–OutputRelation ofTransferMatrix's H^∞ Norm
	SLO-2 Small-GainApproach	InternalStability	MinimalOrderObserver	Limitation on Achievable Closed-loopTransferFunction	Disturbance Control andWeightingFunction
S-3	SLO-1 Positive Real Method	Pole–Zero Cancellation	Parametrization ofStabilizingControllers	InterpolationCondition	LMI Solution 1: VariableElimination
	SLO-2 LyapunovMethod	StabilizabilityandDetectability	Generalized FeedbackControl System	Analysis ofSensitivityFunction	LMI Solution 2: VariableChange
S-4	SLO-1 Robust Regional PolePlacement	Problem solving session	Problem solving session	IntegralRelation	Problem solving session
	SLO-2 GainScheduling	LinearFractionalTransformation	ParametrizationofControllers	Problem solving session	Design of Generalized Plant andWeighting Function
S-5	SLO-1 Problem solving session	SystemPerformance	YoulaParametrization	Bode Integral RelationonSensitivity	μ Synthesis
	SLO-2 Basics of Linear Algebra and Function Analysis	TestSignals	Structure ofClosed-LoopSystem	BodePhase Formula	Definition of μ andItsImplication
S-6	SLO-1 Trace, Determinant, Matrix Inverse, and BlockMatrix	Steady-StateResponse & TransientResponse	Structure of2-Degree-of-Freedom Systems	Limitation ofReference Tracking	Propertiesof μ
	SLO-2 Problem solving session	Comparison of Open-Loop andClosed-LoopControls	Implementation of 2-Degree-of-Freedom	1-Degree-& 2 Degree of-FreedomSystem	D–K IterationDesign

S-7	SLO-1	Linear VectorSpace	Problem solving session	SystemPerformance	Relation between Time Domain and FrequencyDomainProperties	RegionalPolePlacement
	SLO-2	Norm and Inner Product of Vector	Basics of Convex Analysis and LMI	Problem solving session	Parseval'sTheorem	Convex Region and ItsCharacterization
S-8	SLO-1	LinearSubspace	Convex Set and Convex Function	TestSignals	Fourier Transform and InverseFourierTransform	Condition for RegionalPolePlacement
	SLO-2	Matrix and Linear Mapping	Control Problem andLMI	Steady-StateResponse	KYPLemma	CompositeLMIRegion
S-9	SLO-1	Eigenvalue and Eigenvector	Interior Point Method	TransientResponse	Problem solving session	Problem solving session
	SLO-2	Problem solving session	Problem solving session	Problem solving session	Case Study: Stabilization of aUnicycleRobot	Case Study: Transient Stabilization of aPowerSystem

Learning Resources	1. Kang zhi liu, Yu Yao, Robust Control – Theory and Applications, Wiley Publications, 2016.	4. B. Burl, Linear Optimal Control H2 and H [∞] Methods, Addison Wesley, California, US.1999.
	2. T. Glad and L. Ljung, Control Theory: Multivariable and Non-linear methods, Taylor and Francis, London, 2009.	5. K. Zhou, J. C. Doyle and K. Glover, Robust and Optimal Control, Prentice-Hall, 1999
	3. S. Skogstad and I. Postlethwaite, Multivariable Feedback Control, John Wiley and Sons, 2005.	6. Online Course: https://swayam.gov.in/
		7. NPTEL: Control Engineering, Robust Control Systems. https://nptel.ac.in/courses/108103007/8

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. Venkatarao Ryali, Electromechanical Control Systems Lab at GE Global Research, Bengaluru.	1. Dr.S.K.Patnaik, CEG, Anna University, skpatnaik@annauniv.edu	1. Mr.S.Senthilmurugan, SRMIST
2. Mr. Pugazhendhi K, Control & Instrumentation at ENMAS GB POWER SYSTEMS PROJECTS LTD.Chennai,	2. r. B. K. Panigrahi, IIT Delhi, bkpanigrahi@ee.iitd.ac.in	2. Ms R.Rajarajeswari, SRMIST

Course Code		18EEE319T	Course Name		FUNDAMENTALS OF ROBOTICS				Course Category	E	Professional Elective			L	T	P	C						
														3	0	0	3						
Pre-requisite Courses		NIL		Co-requisite Courses		Nil				Progressive Courses		Nil											
Course Offering Department				Electrical & Electronics Engineering				Data Book / Codes/Standards		Nil													
Course Learning Rationale (CLR):			The purpose of learning this course is to:				Learning			Program Learning Outcomes (PLO)													
CLR-1	Understand the concepts and basic structure of Robots					1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2	Recognize the basics of end effectors and drive systems					Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3	Enrich the students on the basics of Robotic manipulator and understand the kinematics of serial manipulators																						
CLR-4	Analyze the basics of Sensors and its various applications in Robots.																						
CLR-5	Design the Algorithms for mobile Robot navigation.																						
CLR-6	Utilize the concepts in robotics for the understanding of automation technology																						
Course Learning Outcomes (CLO):			At the end of this course, learners will be able to:				2	75	75	H	H	M	L	-	-	-	-	-	-	-	M	M	-
CLO-1	Interpret the basic structure of Robots and apply it to design the Robots.					3	75	75	H	H	H	M	-	-	-	-	-	-	-	-	H	M	-
CLO-2	Acquire knowledge about end effectors and actuators systems					2	75	75	H	H	H	M	-	-	-	-	-	-	-	-	H	H	-
CLO-3	Select robotic manipulator and understand the kinematics of serial manipulators					3	75	75	H	H	H	M	-	-	-	-	-	-	-	-	M	M	-
CLO-4	Select and implement the sensors for various applications in Robots.					3	75	75	H	H	H	H	-	-	-	-	-	-	-	-	H	M	-
CLO-5	Develop the algorithms for mobile Robot navigation.					3	75	75	H	H	H	H	-	-	-	-	-	-	-	-	H	M	-
CLO-6	Apply the concepts of robotics in real time applications					3	75	75	H	H	H	H	-	-	-	-	-	-	-	-	H	M	-
Duration (hour)		9		9		9			9			9			9			9					
S-1	SLO-1	Robotics: Definition Advantage and disadvantage of robots		Robot Drives- Actuators		Matrix representation			Robot Sensors			Localization											
	SLO-2	History of robotics		Actuators selection.		Fixed – reference frame			Selection of sensor			Path Planning											
S-2	SLO-1	Classification of robots		Characteristics of actuating system		Representation of frame at the origin of a fixed-reference frame			Contact and touch sensor			Examples of localization system											
	SLO-2	Robot components,		Comparisons of actuating system		Representation of frame in a fixed reference frame			Tactile sensor			Brief representations											
S-3	SLO-1	Robot characteristics		Electric Actuators: DC motor		Representation of rigid body			Gripping force sensing			Brief considerations											
	SLO-2	Co-ordinate systems		Brushless DC motor		Robot Kinematics - Position analysis			Slip sensing			Mobile robot localization using practical filters											
S-4	SLO-1	Robot reference frame		Hydraulic actuators		Representation of a pure transformation			Proximity sensor			Map representations											
	SLO-2	Degrees of freedom		Pneumatic actuators		Representation of combined transformation			range sensor			Map considerations											
S-5	SLO-1	Configuration space		Robot end effectors		Calculation of transformations			Light sensors			Simultaneous planning localization and mapping (SLAM)											
	SLO-2	Operational space		Classification of end-effectors		Transformations relative to the rotating frame			Pressure sensors			Path planning											
S-6	SLO-1	Robots as mechanisms		Drive system for grippers		Inverse transformation matrix			strain gauge based force-torque sensors			Path planning challenges											
	SLO-2	Robot configurations-cartesian		Mechanical grippers		Inverse transformation matrix of the universe, robot, hand and end effectors frame			Position sensor			Types of Path planning algorithms											
S-7	SLO-1	Robot configurations- cylinder		Magnetic grippers		Forward kinematics-2 DOF of kinematics analysis			Displacement sensor			Robotics applications with examples											
	SLO-2	Robot configurations- polar		Vacuum grippers		Forward kinematics-3 DOF of kinematics analysis			Sensors-Vision systems			Material handling: Pick and place operation											
S-8	SLO-1	Robot configurations- articulate		Adhesive grippers		Inverse kinematics- 2 DOF of kinematics analysis			Low level vision sensing and digitizing			Palletizing and depalletizing											
	SLO-2	Robot wrist mechanism		Selection criteria for grippers		Inverse kinematics- 3 DOF of kinematics analysis			Vision cameras			Machine loading and unloading											
S-9	SLO-1	Precision and accuracy of robot		Gripper force analysis and design		Euler angles			Charge coupled device line scan sensor			Welding, A sensor based joystick controlled teleoperated manipulator											
	SLO-2	simple problems in precision and accuracy of robot		simple problems in Gripper		Issues in inverse kinematics			Applications of robotics vision system			A sensor based joystick controlled teleoperated manipulator											

Learning Resources	1. S. R. Deb & Sankha Deb, <i>Robotics Technology and Flexible Automation</i> , 2 nd ed., Tata McGraw Hill, 2010.	4. Mikell. P. Groover, <i>Industrial Robotics Technology, Programming and Applications</i> , 3 rd ed., McGraw Hill Co, 2008. 5. https://www.edx.org/learn/robotics
	2. Niku, Saeed, <i>Introduction to robotics</i> , 2 nd ed., John Wiley & Sons, 2010.	
	3. John J. Craig, <i>Introduction to Robotics: Mechanics and Control</i> , 4 th ., Addison Wesley, 2018.	

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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2.Mr.Uday kumar, KPIT, udaykumar2495@gmail.com	2.Dr.S.K.Patnaik, CEG, Anna University, skpatnaik@annauniv.edu	2.Dr.K.Mohanraj, SRMIST

Course Code	18EEE320T	Course Name	SIGNALS AND SYSTEMS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical & Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Categorize the different types of continuous and discrete time signals	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Classify the various types of continuous and discrete systems	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Perform the discrete Fourier transform on signals																		
CLR-4 :	Perceive the digital IIR filters																		
CLR-5 :	Realize the digital FIR filters																		
CLR-6 :	Acquire knowledge on identification and creation of signals and systems																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Identify the continuous and discrete time signals	2	80	75	H	H	L	L	L	-	-	-	-	-	-	-	H	M	-
CLO-2 :	Distinguish the various types of continuous and discrete systems	2	80	75	H	H	L	L	L	-	-	-	-	-	-	-	H	M	-
CLO-3 :	Assess the Discrete Fourier transform on signals	2	80	75	H	H	M	M	-	-	-	-	-	-	-	-	H	M	-
CLO-4 :	Develop the digital IIR filters	3	80	75	H	H	H	H	L	-	-	-	-	-	-	-	H	M	-
CLO-5 :	Design the digital FIR filters	3	80	75	H	H	H	H	L	-	-	-	-	-	-	-	H	M	-
CLO-6 :	Evaluate the various types of signals and systems	3	80	75	H	H	H	H	L	-	-	-	-	-	-	-	H	M	-

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Analog signals, discrete time signals and digital signals	Continuous time systems	System representation through differential equations	Design procedure of Analog Butterworth Filter	Design procedure of FIR filter by window technique
	SLO-2 Deterministic and random signals	Discrete time systems	System representation through difference equations	Design of Analog Butterworth Filter	Rectangular and Hamming windows
S-2	SLO-1 Periodic and aperiodic signals	Memory less and memory systems	Realization of discrete time systems: Direct form - I	Design procedure of Analog Chebyshev Filter	Hanning and Blackmann Windows
	SLO-2 Energy and power signals	Causal and non-causal systems	Realization of discrete time systems: Direct form - II	Design of Analog Chebyshev Filter	Kaiser window
S-3	SLO-1 Even-odd signals	Linear and non-linear systems	Realization of discrete time systems: Cascade form	Bilinear transform technique	Design of low pass FIR filter: Calculation of window coefficients
	SLO-2 Causal and non-causal signals	Time variant and time invariant systems	Realization of discrete time systems: Parallel form	Quantitative treatment of Bilinear transform technique	Design of low pass FIR filter: Calculation of filter coefficients
S-4	SLO-1 Standard continuous time signals: Unit step and Impulse signals	Stable and unstable systems	Discrete Fourier Transform (DFT)	Impulse invariance technique	Design of high pass FIR filter: Determination of window coefficients
	SLO-2 Standard continuous time signals: Sinusoidal and Exponential signals	FIR and IIR systems	Calculation of DFT	Quantitative treatment of Impulse invariance technique	Design of high pass FIR filter: Determination of filter coefficients
S-5	SLO-1 Standard discrete time signals: Unit step and Impulse signals	Recursive and non-recursive systems	DFT properties: Linearity, Periodicity, Circular convolution	Design of IIR Butterworth digital filters using bilinear transform technique	Design of band pass FIR filter: Calculation of window coefficients -
	SLO-2 Standard discrete time signals: Sinusoidal and Exponential signals	System properties via the impulse response: Causality	DFT properties: Time reversal, Circular time shift, Parseval's theorem	Design of IIR Chebyshev digital filters using bilinear transform technique	Design of band pass FIR filter: Calculation of filter coefficients
S-6	SLO-1 Transformations of the independent variable: Addition, Multiplication and Shifting	System properties via the impulse response: Memory	DFT using DIT-FFT algorithm	Design of IIR Butterworth digital filters using impulse invariance technique – Self study	Design of band stop FIR filter: Determination of window coefficients – Seminar

	SLO-2	Transformations of the independent variable: Scaling and Reversal	Relation between continuous and discrete time systems	Calculation of DFT using DIT-FFT	Design of IIR Chebyshev digital filters using impulse invariance technique – Self study	Design of band stop FIR filter: Determination of filter coefficients – Seminar
S-7	SLO-1	Sampling and Sampling Theorem	Continuous time convolution	DFT using DIF-FFT algorithm	Realization of IIR Butterworth digital filters	Realization of FIR filters: Transversal realization structure
	SLO-2	Quantization and Coding	Quantitative treatment of Continuous time convolution	Calculation of DFT using DIF-FFT algorithm -Assignment	Realization of IIR Butterworth digital filters	Realization of FIR filters: Linear phase realization structure
S-8	SLO-1	Aliasing	Discrete time convolution	Inverse DFT	Need of Pre-warping	Realization of FIR filters: Polyphase realization structure
	SLO-2	Effects of Aliasing	Quantitative treatment of Discrete time convolution	Calculation of IDFT	Pre warping – Frequency transformation in digital domain	Realization of FIR filters: Cascade structure
S-9	SLO-1	Simulation on continuous time signals	Simulation on Continuous time systems	Circular convolution	Simulation on digital IIR Butterworth filters	Simulation on digital FIR low and high pass filters
	SLO-2	Simulation on discrete time signals	Simulation on discrete time systems	Quantitative treatment of Circular convolution -Assignment	Simulation on digital IIR Chebyshev filters	Simulation on digital FIR band pass and band stop filters

Learning Resources	1. H. P. Hsu, Signals and systems, Schaum's series, McGraw Hill Education, 2010. 2. S. Haykin and B. V. Veen, Signals and Systems, John Wiley and Sons, 2007. 3. A. V. Oppenheim and R. W. Schaffer, Discrete-Time Signal Processing, Prentice Hall, 2009. 4. M. J. Robert, Fundamentals of Signals and Systems, McGraw Hill Education, 2007.	5. B. P. Lathi, Linear Systems and Signals, Oxford University Press, 2009. 6. A. V. Oppenheim, A. S. Willsky and S. H. Nawab, Signals and systems, Prentice Hall India, 1997. 7. J. G. Proakis and D. G. Manolakis, Digital Signal Processing: Principles, Algorithms, and Applications, Pearson, 2006. 8. https://extension.ucsd.edu/courses-and-programs/signals-and-systems
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. Sharon Ravichandran, ABB Ltd., Chennai, sharonravi87@gmail.com	1. Dr. M.Jaya Bharata Reddy, NIT, Trichy, jbreddy@nitt.edu	1. Dr.K.Mohanraj, SRMIST
2. Mr.Sabari Ramanan, Manager, Siemens, Chennai, sabari.pm@siemens.com	2. Dr. B. K. Panigrahi, IIT Delhi, bkpanigrahi@ee.iitd.ac.in	2. Dr.A.Rathinam, SRMIST

Course Code	18EEE412T	Course Name	ADVANCED CONTROL THEORY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18EEEC301J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical & Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Educate on the basic concepts of multivariable control system	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2 :	Understand the design concepts in model predictive control techniques																							
CLR-3 :	Provide adequate knowledge on preliminary concepts in Adaptive control schemes																							
CLR-4 :	Provide knowledge on Variable Structure control techniques																							
CLR-5 :	Educate on different optimal control practices																							
CLR- 6:	Create a mindset to use the advanced control techniques in complex system																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:						Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO-1	PSO-2	PSO-3		
CLO-1 :	Formulate the Multivariable control techniques to Multiple parameter system	3	75	75	H	H	M	M	-	-	-	-	-	-	-	-	-	-	M	M	-			
CLO-2 :	Apply the model predictive control strategy to linear and Nonlinear systems	3	75	75	H	H	H	H	-	-	-	-	-	-	-	-	-	-	M	M	-			
CLO-3 :	Articulate the basic adaptive control technique to a system	3	75	75	H	H	M	M	-	-	-	-	-	-	-	-	-	-	M	M	-			
CLO-4 :	Design the sliding mode control to a dynamic system	3	75	75	H	H	M	M	-	-	-	-	-	-	-	-	-	-	M	M	-			
CLO-5 :	Analyze and design the optimal control techniques for linear and Nonlinear systems	3	75	75	H	H	H	H	-	-	-	-	-	-	-	-	-	-	M	M	-			
CLO-6 :	Apply the advanced control techniques in real time problems	3	75	75	H	H	H	H	-	-	-	-	-	-	-	-	-	-	M	M	-			

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Basics of Classical Feedback Control	Introduction to Model Predictive control	Introduction to adaptive control	Introduction to Sliding Mode Control	Introduction to Optimal Control
	SLO-2	Introduction to multivariable control systems	MPC Strategy, Historical perspectives.	Effects of process variations	Properties of Sliding Motion	Importance of Optimal Control
S-2	SLO-1	Transfer functions for MIMO systems	MPC Elements: Prediction Model	Introduction to Adaptive control schemes	Pseudo Sliding With a Smooth Control	Basics of Parameter Optimization
	SLO-2	Negative Feedback Control system in MIMO system	MPC Elements: Objective Function	Types of Adaptive Control Schemes	State Space Approach in Sliding Mode	Parameter Optimization in Optimal Control
S-3	SLO-1	Multivariable frequency response analysis	Model forms for model predictive control Forms	Adaptive control problem	Sliding Mode Control: Problem Statement	Performance Index in Optimal Control
	SLO-2	Directions in Multivariable Systems	Dynamic Matrix Control	Non-parametric identification	Existence Solution and Equivalent Control	Constraints in Optimal Control
S-4	SLO-1	Introduction to multivariable system mapping-poles & zeros	Model predictive control Forms	Deterministic Self Tuning Regulators	Properties of Sliding Motion	Calculus of variance in Optimal Control
	SLO-2	Singular value decomposition	Model Algorithmic Control	Pole Placement in Adaptive Control	Properties of Sliding Motion	Basic Concepts, Functions in optimal Control
S-5	SLO-1	Limitations On Performance In MIMO Systems:: Functional controllability	Model predictive control Forms	Indirect Self Tuning Regulators	The reachability Problem in Sliding Mode Control	Optimum of a Function
	SLO-2	Limitations imposed by time delays	Predictive Functional Control	Continuous Time Self tuners	Single input Control Structure	Optimum of a Functional
S-6	SLO-1	Limitations On Performance In MIMO Systems	Generalized Predictive Control	Introduction to Stochastic Tuning Regulators	Unit Vector Approach: Existence in Ideal Sliding Mode	The basic variational Problem
	SLO-2	Limitations imposed by RHP zeros	Introduction and Formulation of Predictive Control	Predictive Self Tuning Regulators	Description of the sliding Motion by Unit Vector Approach	Second Variation Problem

S-7	SLO-1	Trade-offs in MIMO feedback design	Introduction to Multivariable Model Predictive Control	Stochastic Adaptive Problem	Introduction to types of Sliding Mode Design Approach (Qualitative)	Introduction to linear quadratic optimal control system
	SLO-2	Traditional LQG and LQR problems	Generalized Model of Multivariable Predictive Control	Dual Control in stochastic Predictive Control	Introduction to types of Sliding Mode Design Approach (Quantitative)	linear quadratic optimal control system Model
S-8	SLO-1	Introduction to linear quadratic regulation (LQR) control	Constrained Model Predictive Control	Introduction to Auto Tuning of Controller	Direct Eigen Structure Assignment Approach (Qualitative)	Finite Time Linear Quadratic Regulator
	SLO-2	Robustness properties of LQR control	Constraint General Form, Example	PID Controller Auto Tuning	Direct Eigen Structure Assignment Approach (Quantitative)	Problem Formulation in Finite Time Linear Quadratic Regulator
S-9	SLO-1	Introduction to H_2 control	Introduction to Robust Model Predictive Control - Application	Introduction to Gain Scheduling - Application	Introduction to higher order sliding mode control	Introduction to LQR system for general performance Index
	SLO-2	Introduction to H_∞ control	Introduction to Robust Model Predictive Control - Application	Introduction to Gain Scheduling - Application	Problems in Higher order sliding mode control	Introduction to LQR system for general performance Index

Learning Resources	<ol style="list-style-type: none"> 1. Sigurd Skogestad and Ian Postlethwaite, <i>Multivariable Feedback Control: Analysis and Design</i>, 2ed (WILEY-Interscience), 2014. 2. Eduardo F. Camacho, Carlos Bordons Alba, <i>Model Predictive Control</i>, Springer, 2013. 3. Karl J. Astrom and Bjorn Wittenmark, <i>Adaptive Control</i>, Pearson Education, 2nd Edition, 2013. 	<ol style="list-style-type: none"> 4. C Edwards, S Spurgeon <i>Sliding Mode Control: Theory And Applications</i>, CRC Press, 1998. 5. Donald E. Kirk, <i>Optimal Control Theory: An Introduction</i>, Prentice – Hall networks series, New Jersey, 2012. 6. https://www.cranfield.ac.uk/courses/short/energy-and-power/advanced-control-systems
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30 %	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40 %	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30 %	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1.Ms.R.Vijayalakshmi, C2C Engineering, vijayalakshmi@c2cengineering.co.in	1.Dr.S.K.Patnaik, CEG, Anna University, skpatnaik@annauniv.edu	1.Dr.R. Narayanamoorthi, SRMIST
2.Dr. S. Paramasivam, Danfoss Industries Pvt.Ltd, paramsathya@yahoo.com	2. Dr. B. K. Panigrahi, IIT Delhi, bkanigrahi@ee.iitd.ac.in	2.Dr.N. Chellammal, SRMIST

Course Code	18EEE413T	Course Name	DISTRIBUTED CONTROL SYSTEMS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering		Data Book / Codes/Standards	Nil	

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1:	Learn the architecture, Organization and operation of PLC, SCADA and Distributed Control System (DCS)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Impart knowledge about basic controllers and DCS controller Configuration	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3:	Know the importance of Alarm features in DCSs																		
CLR-4:	Impart adequate knowledge on Maintenance and Troubleshooting procedures of DCS																		
CLR-5:	Learn the basics of Advanced Process Controllers in DCSs and Latest trends related to DCS																		
CLR-6:	Gain Knowledge about basic DCS controllers Alarm system management and advanced process controllers																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1:	Familiarize the concepts and abstractions of distributed systems and their limitations	2	80	75	H	L	L	L	-	-	-	-	-	-	-	-	M	M	-
CLO-2:	Obtain the knowledge of basic controllers and DCS controller Configuration	2	80	75	H	L	L	-	-	-	-	-	-	-	-	-	M	M	-
CLO-3:	Enrich the knowledge of Alarm features of DCS	2	80	75	H	L	M	L	-	-	-	-	-	-	-	-	M	L	-
CLO-4:	Analyse the system for the awareness of the issues and procedures to perform DCS Maintenance and Troubleshooting	3	80	75	H	H	M	M	-	-	-	-	-	-	-	-	M	M	-
CLO-5:	Acquire the basics of Advanced Process Controllers in DCSs and Latest trends related to DCS	3	80	75	H	H	H	H	-	-	-	-	-	-	-	-	M	M	-
CLO-6:	Evaluate and specify DCSs to ensure efficient and optimum operation of Plant	3	80	75	H	H	H	H	-	-	-	-	-	-	-	-	M	M	-

Duration (hour)		9		9		9		9	
S-1	SLO-1	Programmable Logic Controller (PLC) – brief overview	Introduction to basic controller, Identification of the controller boards	Alarm system management: An alarm system, Functions of the plant or process operator	Introduction to Distributed control system reporting, Operation of advanced DCS using multi-screen display	Advanced Process Controllers:Feed forward Control			
	SLO-2	Block Diagram of PLC	Discrete and logic control, Sequential and batch control	Functions of an alarm system, An effective alarm system	Cross screen invocation and linking	Cascade Control			
S-2	SLO-1	An overview of SCADA systems: Introduction and Basics of SCADA system	Basic DCS controller configuration: Introduction and Control modes	Design overview	Alarm reporting, generation and acceptance	Statistical Process Control			
	SLO-2	SCADA key features	Tracking and initialization in control slots used for cascade control	Human and ergonomic factors	Different types of logs and reports configurable on a DCS	Basics of advanced process control and optimization			
S-3	SLO-1	Remote terminal units (RTUs)	Control functions	Structure of a good alarm system	Introduction to Distributed control system (DCS) configuration	Latest DCS Trends:Monitoring and control in the Field			
	SLO-2	Typical requirements for an RTU system	Control algorithms	Safety integrity level (SIL)	System/project tree structure, DCS system database	Industrial Internet			
S-4	SLO-1	PLCs used as RTUs and Consideration and benefits of SCADA system	Sequential Controllers for Batch Processing	Definition of strategy, Strategy for alarm system design	Configuration of control functions	Internet of Things			
	SLO-2	DCS versus SCADA terminology	Defining equipment procedures	Strategy for alarm system maintenance and management at the site/plant, Generation of minimum design documentation for each alarm	Configuration of operator/monitoring functions	Mobile and remote devices			
S-5	SLO-1	SCADA software package	Phase logic programming	Measurement of the alarms, Field measurements for deriving alarms	Configuration of system hardware structure	Cloud ProcessingMonitoring and control in the Cloud			
	SLO-2	Hardware, software, system interfacing	Phase logic interface	Hardware for alarm processing, Alarm displays	Configuration of system software	Typical DCS and SCADA systems: Honeywell Plant Scape system			
S-6	SLO-1	Overview of Distributed Control Systems: Introduction and Basic concepts of Distributed Computing	Logic block functions in advanced controller	Testing of alarms, Generation of various types of alarms	Documentation and Commissioning	Foxboro I/A series DCS			

	SLO-2	Evolution of Distributed Computing System	DCS controller configuration	Selection of alarm settings	Introduction to Maintenance & Troubleshooting	Delta system
S-7	SLO-1	Present market trends in DCS	Introduction to Communications for DCS & SCADA systems: Purpose and Basic Communications principles	Setting alarm priority	Maintenance requirements of system and system elements	Citect
	SLO-2	Basic DCS specification	Balanced and unbalanced transmission lines	Design of field sensors for generating alarms	Requirements for in-built diagnostic and maintenance routines	Wonderware
S-8	SLO-1	General description of a commercial DCS	4 EIA-232 interface standards (CCITT V.24 interface standard)	Logical processing of alarms	Requirement for installation of UPS system	Distributed control system applications: Use of DCS in oil and gas processing environment
	SLO-2	Advantage of DCS systems	The EIA-485 interface standard	Design of alarm list displays	Recovery of a DCS following power outage	Use of DCS in pulp and paper environment
S-9	SLO-1	DCS selection criteria	Interoperability, ModBus protocol	Measurement of performance	Proper troubleshooting methods, identify typical Communication malfunctions and faults, Identifying failures, malfunctions, and faults	Use of DCS in petroleum-refining environment
	SLO-2	DCS architecture	HART protocol, The promise of FieldBus and DeviceNet and Benefits	Usefulness of alarms	Diagnostics of Communication faults	Distributed control systems project implementation

Learning Resources	<ol style="list-style-type: none"> 1. Michael P. Lukas, <i>Distributed Control Systems: Their Evaluation and Design</i>, Van Nostrand Reinhold Co., 1986. 2. Boyer, S.A. <i>SCADA: Supervisory Control and Data Acquisition</i>. 4th Edition. International Society for Automation, Raleigh, USA, 2010. 3. Gene F. Franklin, J.David Powell, Abbas Emami, <i>Feedback Control of Dynamic Systems</i>, Naeini, Pearson 4. Srinivas Medida, <i>Pocket Guide on Industrial Automation, For Engineers and Technicians</i>, IDC Technologies. 	<ol style="list-style-type: none"> 5. Bela G. Liptak, <i>Process Measurement and Analysis</i>, Instrument Engineers' Handbook Fourth Edition, CRC Press. 6. Richard L. Shell, Ernest L. Hall, <i>Handbook of Industrial Automation</i>, University of Cincinnati Cincinnati, Ohio, 2000. 7. <i>Practical Distributed Control Systems (DCS) for Engineers and Technicians</i>, Revision 6.1, IDC Technologies. 8. www.isa.org
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Kranti kumar Chittipolu, krantikumar.ch@cleanmaxsolar.com , Reginal Design Head, Solar Sector, CleanMax Solar.	Dr. P. Lakshmi, Anna University, Madras, p_lakshmi@annauniv.edu	Ms. T.M. Thamizh Thentral, SRMIST
Ms. Vijayalakshmi Ramani, Head-Engineering at C2C Engineering, Chennai, vijayalakshmi@c2cengineering.co.in	Dr.S.K.Patnaik, CEG, Anna University, skpatnaik@annauniv.edu	Ms. R. Rajarajeswari, SRMIST

Course Code	18EEE414T	Course Name	CONTROL SYSTEM DESIGN	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18EEEC301J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Gain knowledge on stability using frequency domain methods	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Analyze state space analysis of mechanical systems	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Impart knowledge on controllability/observability of control systems																		
CLR-4 :	Outline the concept and design of robust control systems																		
CLR-5 :	Examine stability of nonlinear autonomous systems by state space methods																		
CLR 6 :	Gain knowledge on the design, control and analysis of Linear and non-linear system.																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Apply frequency domain methods for stability analysis	2	80	75	H	H	L	L	-	-	-	-	-	-	-	-	M	M	-
CLO-2 :	Evaluate linear dynamical systems by state space methods	3	80	75	H	H	M	M	-	-	-	-	-	-	-	-	H	M	-
CLO-3 :	Determine controllability/observability by rank test	3	80	75	H	H	L	L	-	-	-	-	-	-	-	-	L	L	-
CLO-4 :	Design robust control system for real time system	3	80	75	H	H	L	L	-	-	-	-	-	-	-	-	M	M	-
CLO-5 :	Analyse stability of nonlinear autonomous systems by state space methods	2	80	75	H	M	L	I	-	-	-	-	-	-	-	-	L	L	-
CLO 6 :	Design of compensators to analyse the system stability and performance of Control system.	3	80	75	H	H	H	H	-	-	-	-	-	-	-	-	M	M	-

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Introduction to Design of Feedback Control Systems	Introduction to Design of State Variable Feedback Systems	Introduction to Controllability and Observability	Introduction to Robust control system
	SLO-2	Approaches to System Design	Advantages of State Space Representation	Conditions for Controllability and Observability	Review of norms for signals and systems
S-2	SLO-1	Cascade Compensation Networks	State-space Equations	Algebraic definitions for Controllability and Observability	Review of Nyquist Criterion and Classical Stability Margin
	SLO-2	System Design Using Integration Networks	State model of LTI and SISO linear systems	Full-state feedback control design	The small Gain Theorem and Applications of Small Gain Theorem to the Robust Control
S-3	SLO-1	Design procedure for Phase-Lead network Using the Bode Diagram	State space representation using physical variables	Need for Observer	Robust control systems and system sensitivity
	SLO-2	Design example: Phase-Lead design for different types system	State space representation using phase variables	Structure and properties of observer	System sensitivities to parameter perturbations
S-4	SLO-1	Design procedure for Phase-Lead network Using the root locus	State space models of DC motor	Integrated full-state feedback and observer	Analysis of robustness
	SLO-2	Design example: Phase-Lead design for different types system	State space models of inverted pendulum	Pole placement for single-output systems	System with uncertain parameters of robust control system
S-5	SLO-1	Design procedure for Phase-Lag network Using the Bode Diagram	Decomposition of Transfer Functions-Direct Decomposition	Compensator design by separation principle	Considerations in design of robust control system Design
	SLO-2	Design example: Phase-Lag design for different types of system	Cascade and parallel Decomposition	Reference inputs	Design of robust PID controlled systems
S-6	SLO-1	Design procedure for Phase-Lag network Using the root locus	Similarity Transformation	Types of observer	Robust internal mode control systems
	SLO-2	Design example: Phase-Lag design for different types system	Solution of state equations	Compensator design using full order observer	Design of internal mode control systems

S-7	SLO-1	Design on the Bode Diagram Using Analytical Methods	Computation of the State Transition Matrix by infinite series method	Optimal control systems	Loop shaping necessary and sufficient conditions.	Linear Quadratic Regulator
	SLO-2	System design using analytical technique	Computation of the State Transition Matrix by Laplace transformation	Determination of optimal control systems	Robust stability test.	Lasalle's invariance principle
S-8	SLO-1	Systems with a Pre-filter	Computation of the State Transition Matrix by Cayley-Hamilton Theorem	Optimal system with control energy consideration	Robust performance test.	Instability Theorem
	SLO-2	Design for Deadbeat Response	Computation of the State Transition Matrix by Canonical Transformation	Disturbances and tracking systems	Design Examples: the pseudo quantitative feedback system	Design Examples-Linear Harmonic Oscillator
S-9	SLO-1	System design using control design software	Computation of the State Transition Matrix by Sylvester's method	Design Examples-Automatic test system	Robust Control Systems using Control design software	Design Examples-Non-Linear Spring mass system with Damper
	SLO-2	Sequential design of disk drive read system	Transfer Function from the State-Model	Diesel Electric Locomotive control system	Sequential design of disk drive read system	Design Example-Pendulum with and without friction

Learning Resources	1. Richard C. Dorf and Robert H. Bishop, Modern Control Systems, Prentice Hall, Upper Saddle River, NJ, 2001	4. Bernard Friedland, Control System Design: An Introduction to State-Space Methods (Dover Books on Electrical Engineering), Dover Publications Inc., 2005.
	2. Katsuhiko Ogata, Discrete Time Control Systems, Pearson 3. Gene F. Franklin, J. David Powell, Abbas Emami, Feedback Control of Dynamic Systems, Naeini, Pearson	5. Steen Toffner-Clausen, System Identification and Robust Control, Springer Verlag London Limited 1996. 6. R.M. Murray, Z. Li, S.S. Sastry, A Mathematical Introduction to Robotic Manipulations, CRC Press, 1993. 7. http://nptel.ac.in/courses/108103007/16

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. Sharon Ravichandran, ABB Ltd., Chennai, sharonravi87@gmail.com	1. Dr. P. Lakshmi, Anna University, Madras, p_lakshmi@annauniv.edu	1. Ms. T.M. Thamizh Thentral, SRMIST
2. Ms. Vijayalakshmi Ramani, Head-Engineering at C2C Engineering, Chennai, vijayalakshmi@c2cengineering.co.in	2. Dr. S.K. Patnaik, CEG, Anna University, skpatnaik@annauniv.edu	2. Ms. R. Rajarajeswari, SRMIST

Course Code	18EEE415T	Course Name	DIGITAL CONTROL SYSTEM	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18EEEC301J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Enrich the students on the basics of time domain analysis	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Explain the procedure for stability analysis	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Outline the concepts of state space model, controllability and observability																		
CLR-4 :	Gain knowledge on the design of classical compensators																		
CLR-5 :	Understand the concepts of formulation and evaluation of regulators and filters																		
CLR-6 :	Create overall control system structure for industrial applications																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Gain knowledge on Z transform techniques	2	80	75	H	M	M	-	-	-	-	-	-	-	-	-	H	M	-
CLO-2 :	Interpret the knowledge of sampling and design of controllers	3	80	75	H	M	M	M	M	-	-	-	-	-	-	-	M	M	-
CLO-3 :	Illustrate modelling and state variable analysis	3	80	75	H	M	M	M	-	-	-	-	-	-	-	-	H	M	-
CLO-4 :	Analyze the effects of compensators	3	80	75	H	M	M	M	M	-	-	-	-	-	-	-	H	H	-
CLO-5 :	Design of regulators and filters for practical system	3	80	75	H	M	M	M	-	-	-	-	-	-	-	-	H	M	-
CLO-6 :	Design a control system and analyze the stability of the real time system	3	80	75	H	M	M	M	M	-	-	-	-	-	-	-	H	M	-

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Basic components of a control system	Introduction to sampling	Introduction to state variable model	Compensator design	Introduction- Pole placement
	SLO-2 Classification of control systems	Sampled data control systems	State variable concepts, First, second companion forms	Compensating networks types: Cascade and feedback	State observers
S-2	SLO-1 Elements of an automatic control system	Sampled signal flow graph	Various canonical forms	Cascade Lead compensator design using Bode plot	Controller Design by State Feedback
	SLO-2 Applications of control system	Sampling, time and frequency domain description aliasing, hold operation,	Jordan canonical models	Problems related to lead compensators	Stability improvement by state feedback
S-3	SLO-1 Introduction to Z-transform	Mathematical modeling of sampling process and analysis	Analysis-state space models	Cascade Lag compensator design using Bode plot	Necessary and sufficient condition for arbitrary pole placement
	SLO-2 Z-transform Concept	First order hold, factors limiting the choice of sampling rate, reconstruction.	Problems related to state space model	Problems related to lag compensators	State regulator design
S-4	SLO-1 Properties of Z-transform	Sampling and reconstruction of continuous time signals	Discrete state variable models	Problems related to lead- lag compensators	Design of state observers
	SLO-2 Z-transform relation with Laplace transform	Stability analysis of discrete system	Elementary principles.	Digital implementation of lead and lag controllers	Full Order Observer Design
S-5	SLO-1 Inverse z-Transforms and Problems	Jury stability test	Characteristic equation, state transition matrix	Design of digital control systems with deadbeat response	Reduced Order Observer Design
	SLO-2 Mapping of s-plane to z-plane	Bi-linear transformation	Solution to discrete state equation	Practical issues with deadbeat response design	Evaluation of State Feedback Gain Matrix
S-6	SLO-1 Pulse transfer function	Problems related to stability analysis	Stability of discrete state space models	Sampled data control systems with deadbeat response	State feedback with integral control

	SLO-2	Pulse transfer function of closed loop system	Digital PID controllers.	Cayley -Hamilton theorem	Introduction to software tools used in control system for compensator design	Digital control system with state feedback.
S-7	SLO-1	Introduction to the representation of discrete time systems	PID tuning and its importance	Controllability and observability	Coding in simulation software	Linear Quadratic Regulator (LQR) design
	SLO-2	Time response of discrete time systems	Techniques of controller tuning	Analysis of Controllability and observability	Exercises for solving problems related to compensators design	Formulation of LQR problem-
S-8	SLO-1	Time response specifications	Manual tuning Zeigler-Nichols method based on open loop and closed loop responses	Stability- Lyapunov stability theorem	Software implementation using microprocessors and microcontrollers	Optimal estimation- Kalman filter
	SLO-2	Application of the z transform for discrete time signals and systems.	Application of controllers used for control system	Analysis of Lyapunov stability	Microcontroller based temperature control systems	Solution to continuous and discrete systems - Design examples.
S-9	SLO-1	Problems related to time response for standard test signals	Controller design using root locus	Systems with dead time	Speed control of motor load system	Introduction to optimal control
	SLO-2	Problems related to time domain specifications	Root locus based controller design using software tools	Problems related to controllability and observability	Microcontroller based motor speed control systems.	Parameter optimization

Learning Resources	<p>1. B. C. Kuo, Digital Control Systems, Oxford University Press, 2/e, Indian Edition, 2012.</p> <p>2. Richard C Dorf and Robert H Bishop, Modern Control Systems, 13th edition, Pearson Education, 2016.</p>	<p>3. M. Gopal, Digital Control and State Variable Methods, Tata McGraw Hill, 2/e, 2017.</p> <p>4. Norman S Nise, Control Systems Engineering, 7th edition, Wiley, 2015.</p> <p>5. https://nptel.ac.in/courses/108103008/</p>
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. Sharon Ravichandran, ABB Ltd., Chennai, sharonravi87@gmail.com	1. Mr. P. Thamizhazhagan, Associate Professor, University college of Engineering, Panruti, thamizhme@gmail.com	1. Ms. A. Lavanya SRMIST
2. Mr. Jason Manoraj, L&T Technology Services Limited, Bengaluru, Karnataka, jasonmanoraj@gmail.com	2. Dr. B. K. Panigrahi, IIT Delhi, bkpanigrahi@ee.iitd.ac.in	2. Dr. Raja Vikram SRMIST

Course Code	18EEE321T	Course Name	PHOTONICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
		1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15			
CLR-1 :	Introduce the basics principles of photonics				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge														
CLR-2 :	Solve the various problems in Light beams and Variable polarization							Problem Analysis														
CLR-3 :	Analyze the performance of surface and cavity nanophononics							Design & Development														
CLR-4 :	Understand the process and performance of Multiphoton							Analysis, Design, Research														
CLR-5 :	Analyze the basics of Electromagnetic duality, Slow and fast light principles							Modern Tool Usage														
CLR-6 :	Create a over all structure for Photonics system							Society & Culture														
								Environment & Sustainability														
								Ethics														
								Individual & Team Work														
								Communication														
								Project Mgt. & Finance														
								Life Long Learning														
								PSO - 1														
								PSO - 2														
								PSO - 3														
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	Understand the basics of photonics principles				2	80	75															
CLO-2 :	Calculate the parameters of Light beams and Variable polarization				2	80	75															
CLO-3 :	Compute the performance of surface and cavity nanophononics				2	80	75															
CLO-4 :	Acquire knowledge on Multiphoton process				2	80	75															
CLO-5 :	Identify the solutions for slow and fast light				2	80	75															
CLO-6 :	Design a Photonics system for Real Time Applications				2	80	75															

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Photon in Perspective	Light Beams with Spatially Variable Polarization	Surface and Cavity Nanophononics	Multiphoton Processes	Lighting Principles
	SLO-2	Photon Localization	Poincare Modes of Beams	Basic Formalism	Molecular Two-Photon Absorption: Basic Principles	Introduction to Slow and Fast Light
S-2	SLO-1	Wavefunction	Polarization Singularities	Dipole Emitter Near Edge	Molecular Two-Photon Fluorescence	Mechanisms of Slow Light
	SLO-2	The Quantum Vacuum	Quantum Optics	Quantum Correlations	Applications and Future Prospects	Physics with Slow and Fast Light
S-3	SLO-1	Virtual Photons	Open Systems: Inputs and Outputs	Entanglement	Orbital Angular Momentum	Some Applications of Slow and Fast Light
	SLO-2	Structured Light	Photon Counting	Wedge Cavities	Historical Introduction	Fundamental Limits on Slow Light
S-4	SLO-1	Photon Number Fluctuations	Cavity	Quantum Electrodynamics	Creating Beams with OAM	Attosecond Physics
	SLO-2	Photon Number Phase	Circuit QED	Molecular QED: Principle of Minimal Electromagnetic Coupling	Micro-Manipulation through the Use of OAM	Attosecond Streaking Spectroscopy of Atoms and Solids
S-5	SLO-1	The Reality of Photonics	Squeezed Light	Multipolar Hamiltonian	Beam Transformations	Time-Resolved Photoemission from Atoms
	SLO-2	Coherence and Statistical Optics	Salient Features of Squeezed States	One-Photon Absorption	Measuring Beams with OAM	Streaked Photoemission from Solids
S-6	SLO-1	Classical Theory of Optical Coherence in the Space-Time Domain	Detection	Emission of Light: Spontaneous and Stimulated Processes	OAM in Classical Imaging	Attosecond Streaking from Nanostructures

	SLO-2	<i>Classical Theory of Optical Coherence in the Space-Frequency Domain</i>	<i>Preparation</i>	<i>Linear Light-Scattering:</i>	<i>OAM in Nonlinear and Quantum Optics</i>	<i>Attosecond Physics</i>
S-7	SLO-1	<i>Cross-Spectrally Pure Optical Fields</i>	<i>Applications in Quantum Information</i>	<i>The Kramers–Heisenberg Dispersion Formula</i>	<i>Electromagnetic Duality Transformations in Optics</i>	<i>Attosecond Streaking Spectroscopy of Atoms and Solids</i>
	SLO-2	<i>Polarization Properties of Stochastic Beams</i>	<i>Electromagnetic Theory of Materials</i>	<i>Chiroptical Effects</i>	<i>Symmetries and Operators</i>	<i>Attosecond Streaking Spectroscopy of Solids</i>
S-8	SLO-1	<i>Remarks on Partially Coherent</i>	<i>Macroscopic Viewpoint</i>	<i>Two-Photon Absorption</i>	<i>Electromagnetic Duality</i>	<i>Introduction to Photoemission</i>
	SLO-2	<i>Partially Polarized</i>	<i>Constitutive Dyadic</i>	<i>Nonlinear Light-Scattering: Sum-Frequency and Harmonic Generation</i>	<i>Optical Helicity</i>	<i>Time-Resolved Photoemission from Atoms</i>
S-9	SLO-1	<i>Beams Basics of Quantum Theory of Optical Coherence</i>	<i>Linear Materials</i>	<i>Resonance Energy Transfer</i>	<i>Electromagnetic Duality Symmetry</i>	<i>Streaked Photoemission from Solids</i>
	SLO-2	<i>Polarization of singularities</i>	<i>Nonlinear Materials</i>	<i>van der Waals Dispersion Energy</i>	<i>Duality Symmetry in Piecewise Homogeneous and Isotropic Media</i>	<i>Attosecond Streaking from Nanostructures</i>

Learning Resources	1. David L. Andrews, <i>Photonics, Volume 1: Fundamentals of Photonics and Physics</i> , Wiley, 2015. 2. <i>Lasers-Theory and Applications</i> - Ghatak and Thyagarajan, McMillan (2010) 3. <i>Optoelectronic devices and systems</i> - S C Gupta ,Prentice Hall India (2008) 4. <i>Understanding Fiber optics</i> - J Hecht, Pearson Edu. Inc (2006)	5. <i>Light Emitting Diodes</i> -E Fred Scheubert ,Cambridge University Press,(2003) 6. <i>Photonic switching technology</i> - H T Mouftah, J M H Elmirghani - IEE Press (1999). 7. Online Course: IITM-NPTEL – Introduction to Photonics. https://nptel.ac.in/courses/108106135/
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1.Mr.Danrajpurkar, Founder, Danano Photonics, Bengaluru, dananophotonics.com	1.Dr.S.Selladurai, Physics, CEG, Anna University, ssdurai@annauniv.edu	1.Dr.Junaid masud lascar, SRMIST
2.Mr.Satish Bhaker, Director, Sun Photonics, Newdelhi, info@sun-photonics.com	2.Dr.A.Mujeeb, International School of Photonics, CUSAT, mujeeb@cusat.ac.in	2.S.Senthilmurugan, SRMIST

Course Code	18EEE322T	Course Name	PRINCIPLES OF BIOMEDICAL INSTRUMENTATION	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department		Electrical and Electronics Engineering		Data Book / Codes/Standards	

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand the physiological system of the body				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Have an in depth knowledge on the devices for physiological process measurements in the human body				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Acquire knowledge on the measurement of non-electrical parameters in the human body																					
CLR-4 :	Enrich the students on the basic concepts of medical imaging, telemetry techniques and their applications																					
CLR-5 :	Expose the students to medical assisting and therapy equipments																					
CLR-6 :	Create overall structure of biomedical instrumentation starting from physiological system to measurements and assisting equipments																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			1	2	3	H	-	-	-	-	-	-	L	-	-	-	-	M	M	L
CLO-1 :	Explain the various systems of the human body				2	80	75	H	-	-	-	-	-	-	-	-	-	-	-	M	M	-
CLO-2 :	Use electrodes and transducers for physiological process measurements in the human body				2	80	75	H	-	-	-	-	-	-	-	-	-	-	-	M	M	L
CLO-3 :	Measure the non-electrical quantities of the human body				2	80	75	H	-	-	-	-	-	-	-	-	-	-	-	M	M	-
CLO-4 :	Recognize the applications of medical imaging and telemetry techniques				2	80	75	H	-	-	-	-	-	-	-	-	-	-	-	M	M	-
CLO-5 :	Relate the medical assisting and therapy equipments				2	80	75	H	-	-	-	-	-	-	L	-	-	-	-	H	M	L
CLO-6 :	Identify the physiological systems of the body along with various measurements and assisting equipments				2	80	75	H	-	-	-	-	-	-	L	-	-	-	-	M	M	L

Duration (hour)	9		9		9		9	
S-1	SLO-1	Physiological systems of the body	Electrode theory	Measurement of blood pressure- direct method	X-ray machine	Need for Cardiac pacemakers		
	SLO-2	Cells and their structure	Needle and wire electrode	Measurement of blood pressure-indirect method	Physical parameters for X- ray detectors	External pacemakers: Types: Vetricular asynchronous , synchronous and inhibited pacemaker		
S-2	SLO-1	Characteristics of living organisms	Surface and micro electrode	Introduction to the measurement of blood flow	Digital radiography	Atrial synchronous and sequential ventricular inhibited pacemaker		
	SLO-2	General characteristics of a human cell	Metal micropipette electrode	Electromagnetic blood flow meter	Diagnostic ultrasound	Implantable pacemaker		
S-3	SLO-1	Nernst equation	Resistive transducers, thermistor, strain gauge	Ultra sound blood flow meter	Echocardiography	Need for defibrillator		
	SLO-2	Bioelectric potential	Inductive and capacitive transducer	Laser Doppler blood flow meter	Computer tomography	DC defibrillator		
S-4	SLO-1	Electrical characteristics of the human cell	Basic recording system, direct writing recorder, Ink jet recorder	Dye dilution method of cardiac output measuring techniques	CT system components	Implantable defibrillator		
	SLO-2	Bioelectric potential propagation	Potentiometric recorder , Digital recorder and instrumentation type recorder	Thermal dilution method of cardiac output measuring techniques	Patient dose in CT Scanners	Mechanics of respiration		
S-5	SLO-1	Cardiovascular system	Lead system of electrocardiogram	Heart rate measurement	Principles of Magnetic resonance Imaging systems	Artificial ventilation		
	SLO-2	Blood circulation	Standard bipolar leads and unipolar leads	Measurement of heart sounds	Basic MRI components	Types of ventilators: Pressure limited ventilator		
S-6	SLO-1	Heart and its mechanical activities	Recording methods of electrocardiogram	Gas analysers	Image reconstruction techniques	Volume limited and servo controlled ventilators		
	SLO-2	Electrical potentials generated within the heart	Typical waveforms of electrocardiogram	Blood gas analyser	Position Emission Tomography	Pressure volume flow diagram		

S-7	SLO-1	Physiology of the respiratory system	Electromyography	Oximetry	Single Photon Emission Computed Tomography	Kidney machine, Artificial kidney
	SLO-2	Respiratory volumes and capacities	Measurement of conduction velocity	Ear oximeter	Thermography	Dialyzers, Types: Parallel flow dialyzer
S-8	SLO-1	Anatomy of the nervous system	Electroretinography	Pluse oximeter	Biotelemetry	Coil hemodialyzer, Hollow fiber hemodialyzer
	SLO-2	Excitation and inhibition potentials	Electrogastrography	Skin reflection oximeter	Wireless telemetry	Diathermy
S-9	SLO-1	Muscle action	Electroculography	spirometry	Single channel telemetry system	Endoscopes
	SLO-2	Sensory system	Pneumotachography	Measurement of lung volume	Multichannel wireless telemetry system	Lasers in biomedical field

Learning Resources	1. Leslie Cromwell, Fred. J. Weibell and Ench A Pleiffer, Biomedical Instrumentation and measurements Prentice Hall of India, 2 nd ed., 2004	3. C.Raja Roa & .K Guha, Principles of medical electronics and biomedical instrumentation, Universities press, 2001
	2. Kandpur R.S, Handbook of Biomedical Instrumentation, Tata McGraw Hill, 2 nd ed., 2011	4. G.Webster, Medical Instrumentation Application and Design, 3 rd ed., Wiley India edition, 2009. 5. https://swayam.gov.in/nd1_noc19_bt28/preview ,NPTEL Online Course-Bioelectricity

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Understand	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Apply										
Level 3	Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1.Mr.Manjunath rao, Alstrom,manjunath.rao1103@gmail.com	1.Dr Subhransu Sekhar Dash, Government College of Engineering, Keonjhar, Subhransudash_fee@gcekr.ac.in	1. Dr.Y.Jeyashree, SRMIST
2.Mr.Srinath rao, Alstrom,sreenathr.rao@alstrom.com	2. Dr. S. Ramareddy, Jerusalem College of Engineering,sr.victory@gmail.com	2. Mrs. R.Uthra, SRMIST

Course Code		18EEE323T	Course Name		AUTOMOTIVE ELECTRONICS			Course Category	E	Professional Elective					L	T	P	C						
															3	0	0	3						
Pre-requisite Courses					Co-requisite Courses		Progressive Courses																	
Course Offering Department			Electrical and Electronics Engineering				Data Book / Codes/Standards																	
Course Learning Rationale (CLR):		The purpose of learning this course is to:					Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Enrich the students on the basics of batteries					1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLR-2 :	Understand the concepts of battery starting system					Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3	
CLR-3 :	Introduce the different methods of charging systems for batteries																							
CLR-4 :	Learn the fundamentals of Automotive Electronic devices																							
CLR-5 :	Understand different sensors and actuators used in automotive systems																							
CLR-6 :	Get idea about real time automotive electronic systems																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:					3	80	75	H	M	M	M	-	-	-	-	-	-	-	M	L	-	
CLO-1 :	Analyze the concept of batteries & it's working					2	80	75	H	M	M	L	-	-	-	-	-	-	-	-	M	M	-	
CLO-2 :	Gain knowledge on the concepts of battery starting system					2	80	75	H	M	L	L	-	-	-	-	-	-	-	-	M	M	-	
CLO-3 :	Familiarize the principles of charging system for batteries					2	80	75	H	-	-	-	-	-	-	-	-	-	-	-	M	M	-	
CLO-4 :	Acquire knowledge on automotive Electronics					2	80	75	H	M	M	L	-	-	-	-	-	-	-	-	M	M	-	
CLO-5 :	Enhance the use of sensors and actuators in the field of automotive systems					2	80	75	H	M	M	L	-	-	-	-	-	-	-	-	M	M	-	
CLO-6 :	Apply the idea in real time automotive electronics					3	80	75	H	M	M	L	-	-	-	-	-	-	-	-	M	M	-	
Duration (hour)		9		9		9		9		9		9												
S-1	SLO-1	Batteries and Accessories : Principle of lead acid battery		Starting System- introduction		Charging System - introduction		Introduction to Automotive Electronics		Sensors														
	SLO-2	Batteries and Accessories : construction of lead acid battery		Starting System - Condition at starting		Charging System - Generation of direct current		Fundamentals of Automotive Electronics		Activators														
S-2	SLO-1	Characteristics of battery		Behaviour of starter during starting		Evaluating state of battery health		Current trends in automotive electronic engine management system		Sensors- introduction														
	SLO-2	Rating capacity and efficiency of batteries		Advantages and disadvantages		Fundamental in battery testing		Electric power Braking systems		Types of sensors: sensor for speed														
S-3	SLO-1	Various tests on batteries		Series motor and its characteristics for starting system		Battery testing - Capacity		Electromagnetic interference suppression		Throttle position														
	SLO-2	Visual inspection and voltage testing		Shunt motor and its characteristics for starting system		Battery testing – internal resistance		Electromagnetic compatibility		Exhaust oxygen level														
S-4	SLO-1	Lighting system: insulated and earth return system		Principle and construction of starter motor		Battery testing – self discharging quantity		Electronic dashboard instruments		Manifold pressure														
	SLO-2	Vehicle circuits and systems		Cranking motor construction		Factors for degradation and ageing process		Onboard diagnostic system		Crankshaft position														
S-5	SLO-1	Earthing system: Types		Working of different starter drive units		Measurement methods of battery		Security and warning system		Coolant temperature														
	SLO-2	Head light and side light		Care and maintenances of starter motor		Direct measurement method		Nano-electromechanical devices		Exhaust temperature														
S-6	SLO-1	LED lighting system		Starter switches		Indirect measurement method		Engine Ignition		Air mass flow for engine application														
	SLO-2	Control of LED lighting system		Optoelectronic devices- solar cells		Battery Maintenance		Fuel Injection		Solenoids														
S-7	SLO-1	Horn system		Photodiodes		New developments on battery charging system		Collision Avoidance Systems		Various types of electric motors														
	SLO-2	Wiper system and trafficator		Laser Diodes		Rate of charging		Safety Controls		Piezoelectric force generators														
S-8	SLO-1	Maintenance on batteries		Light Absorption and Emission		Depth of charging		Security Alarms		Automatic transmission control systems														
	SLO-2	Charging on batteries		Optical Fiber		Depth of discharging		Transmission Controls		stepper motors														
S-9	SLO-1	Health monitoring of batteries		Surface-Emitting Lasers		SoC and SoH		Navigation System		Relays- Types														
	SLO-2	Battery monitoring methods		Array Lasers		Downfall modes		Applications of Automotive Electronics		Thermal Relay														

Learning Resources	1. William B. Ribbens, <i>Understanding Automotive Electronics</i> , 5th Edition, Butterworth, Heinemann Woburn, 2009.	4. Judge. A.W., <i>Modern Electrical Equipment of Automobiles</i> , Chapman & Hall, 2nd Edition London, 1992. 5. Vinal. G.W., <i>Storage Batteries</i> , John Wiley & Sons Inc., 4th Edition New York, 1985. 6. https://onlinecourses-archive.nptel.ac.in/ .
	2. Tom Denton, <i>Automobile Electrical and Electronics System</i> , Elsevier, Third Edition, 2008.	
	3. Judge. A.W., <i>Modern Electrical Equipment of Automobiles</i> , Chapman & Hall, London, 2010.	

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.Muralikrishna, National Instruments, emkrishnan@gmail.com	1. Dr. M.P.Selvan, NIT Trichy, selvanmp@nitt.edu	1. Mr.R.Palanisamy, SRMIST
2. Mr.Senthilkumar,ATI,rskrd1962@gmail.com	2. A. Venkadesan, NIT Puducherry, venkadesan@nitpy.ac.in	2. Dr.C.Subramani, SRMIST

Course Code	18EEE324T	Course Name	ANALOG AND DIGITAL COMMUNICATION	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	i		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand various analog Communication techniques.	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15			
CLR-2 :	Impart knowledge on data and pulse Communication techniques.	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3			
CLR-3 :	Explain various digital Communication techniques				H	M	M	-	-	-	-	-	-	L	-	M	-	-	L	-	-	
CLR-4 :	Illustrate source and Error control coding				H	M	M	L	-	-	-	-	-	L	-	M	-	-	L	L	L	
CLR-5 :	Gain knowledge on multi-user radio Communication				H	L	-	-	-	-	-	-	-	-	-	M	-	-	-	-	-	
CLR-6 :	Apply the analog and digital Communication concepts in Communication industries				H	M	M	L	-	-	-	-	-	L	-	M	-	-	L	L	L	
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)															
CLO-1 :	Gain knowledge on basics of analog Communication techniques	2	80	75																		
CLO-2 :	Analyze data and pulse Communication techniques	2	80	75																		
CLO-3 :	Summarize digital Communication techniques	2	80	75																		
CLO-4 :	Interpret Source and Error control coding.	2	80	75																		
CLO-5 :	Understand multi-user radio Communication	3	80	75																		
CLO-6 :	Acquire the overall knowledge on analog and digital Communication	3	80	75																		

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Analog Communication:Introduction to Fourier Series	Pulse and data Communication:Introduction to Pulse Communication	Digital Communication:Introduction to digital Communication	Source coding and Error Control Coding: Introduction to coding	Multi-user radio Communication: Global System for Mobile Communications (GSM)
	SLO-2	Fourier Series Properties and applications	Introduction to Data Communication	Analog Communications versus digital Communications	Entropy and Properties of coding	Overview of GSM
S-2	SLO-1	Introduction to Fourier Transform	Pulse Amplitude Modulation (PAM)	conversion of analog signal to digital form	Binary Symmetric Channel	Code division multiple access (CDMA)
	SLO-2	Fourier Transform properties	Pulse Time Modulation (PTM)	baseband signal, band pass signal	Binary Erase Channel	Overview of CDMA
S-3	SLO-1	Modulation – Types	Pulse code Modulation (PCM)	Digital Communication systems – Functional description	Source Coding Theorem	Cellular Concept
	SLO-2	Need for Modulation	Differential pulse code modulation	Block diagram of digital Communications	Lossless data Compression Algorithms	Frequency Reuse
S-4	SLO-1	Noise: Source of Noise	Pulse position modulation(PPM)	Signal processing operations in digital Communications	Shannon fano coding	Channel Assignment
	SLO-2	External Noise, Internal Noise	Comparison of various Pulse Communication System (PAM – PTM– PCM)	quantitative analysis of modulation schemes	Huffman Coding	Handover Techniques
S-5	SLO-1	Amplitude Modulation Theory	Data Communication: Introduction to Data Communication	Amplitude Shift Keying (ASK), Frequency Shift Keying (FSK)	Algorithm and Problem in Shannon fano coding	Overview of Multiple Access Schemes
	SLO-2	Frequency spectrum of AM wave	History of Data Communication	Phase Shift Keying (PSK)	Algorithm and Problem in Huffman Coding	Types of Multiple access

S-6	SLO-1	Double Sideband (DSB) Suppressed Carrier (SC)	Standards Organizations for Data Communication	BPSK	Error Control Coding	IEEE802.11: Wireless LANs Using CSMA/CA
	SLO-2	Conventional AM	Data Communication Circuits	QPSK	Error detection	WLAN Fundamentals
S-7	SLO-1	Single Sideband Modulation (SSB)	Data Communication codes	Principles of MSK	Parity	Cellular Digital Packet Network
	SLO-2	Vestigial Sideband (VSB) Modulation	Error Control, Hardware	Principles of QAM	Redundancy	Overview of cellular digital packet network
S-8	SLO-1	Quadrature Amplitude Modulation	Serial Interfaces	Quadrature Amplitude Modulation (QAM) – 8 QAM	Error correction	Satellite Communication
	SLO-2	Concept synthesis for AM	Parallel interfaces	Quadrature Amplitude Modulation (QAM) - 16 QAM	Forward Error Correction	Satellite Networking
S-9	SLO-1	Theory of Frequency and Phase Modulation	Data Modems – Asynchronous Modem	Bandwidth Efficiency	Application, Convolution Codes	Bluetooth
	SLO-2	Comparison of Analog Communication Systems (AM – FM – PM)	Synchronous Modem	Comparison of various Digital Communication System (ASK – FSK – PSK – QAM)	Block Codes	Bluetooth Applications

Learning Resources	1. Wayne Tomasi, <i>Advanced Electronic Communication Systems</i> , 6th Edition, Pearson Education, 2009 2. Simon Haykin and Michael Moher, <i>Communication Systems</i> , 5th Edition, John Wiley and Sons, Inc., New York, 2009	3. Blake, <i>Electronic Communication Systems</i> , Thomson Delmar Publications, 2002. 4. Martin S. Roden, <i>Analog and Digital Communication System</i> , 3rd Edition, PHI, 2002 5. https://nptel.ac.in/courses/117105143/ 6. https://nptel.ac.in/courses/117105144/
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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2.Mr.Muralikrishna, National Instruments, emkkrishnan@gmail.com	2.Dr. S. Ramareddy, Jerusalem College of Engineering, srr.victory@gmail.com	2.Dr. M. Jagabar Sathik, SRMIST

Course Code	18EEE325T	Course Name	WAVELET TRANSFORM		Course Category	E	Professional Elective					L	T	P	C
												3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department		Electrical and Electronics Engineering		Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning		
CLR-1 :	Introduce the learners to wavelets- its relevant fundamentals and significance			1	2	3	
CLR-2 :	Establish the theory behind construction of wavelets using software tools			Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	
CLR-3 :	Gain knowledge on the details of discrete wavelet transform						
CLR-4 :	Expose the students to the conceptual aspect of multi resolution analysis						
CLR-5 :	Illustrate data compression /extraction and signal processing applications using wavelet transform						
CLR-6 :	Introduce wavelet functions, the advancements in technology and applications						

Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)		
CLO-1 :	Understand the theory and mathematics behind wavelet transform			1				75	75
CLO-2 :	Apply the coding for construction of Daubechies and other wavelet functions			2				75	75
CLO-3 :	Analyze use of wavelets and discrete wavelet transform for filter bank design.			2				75	75
CLO-4 :	Analyze use of wavelets for filter design and multi resolution analysis			2				75	75
CLO-5 :	Use software for various wavelet transform based applications			3				75	75
CLO-6 :	Evaluate existing and new wavelet transform based applications			3				75	75

Program Learning Outcomes (PLO)														
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
H		-	-	-	-	-	-	-	-	-	-	M	-	-
H	M	L	-	-	-	-	-	-	-	-	-	M	M	-
H	M	L	-	M	-	-	-	-	-	-	-	M	M	-
H	M	L	-	M	-	-	-	-	-	-	-	M	M	-
H	M	L	-	M	-	-	-	-	-	-	-	H	H	-
H	M	L	-	M	-	-	-	-	-	-	-	H	H	-

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Wavelets- General introduction	Construction of wavelets	Discrete wavelet transform(DWT) for filter design	Multi resolution analysis (MRA) - Formal definition	Audio compression – Audio masking
	SLO-2	Fields of applications, Heisenberg's un certainty	Relationship between two scale sequences	Signal decomposition- Analysis	Need for multi resolution based image analysis	Standards specifying sub band implementation
S-2	SLO-1	Classical wavelets, Wavelet packets, Local trigonometric bases, Multiwavelets, 2G Wavelets	Relationship between reconstruction and decomposition sequences	Filtering /Frequency response	Multi resolution spaces	Image compression
	SLO-2	Gaussian, Morlet, Daubechies, Mexican Hat, Symlets, Coiflets, Complex, Biorthogonal spline wavelets.	Construction of semi orthogonal spline wavelets	Decimation (Down sampling)	Orthogonal decomposition	The JPEG standard (ITU - T.81)
S-3	SLO-1	Wavelet transform – Translation	Construction of ortho- normal wavelets	Signal reconstruction- Synthesis	Bi orthogonal and Semi orthogonal decomposition	Spatial oriented tree (SOT) code and Generalized self-similarity tree (GST)
	SLO-2	Wavelet transform -Scaling and Shifting Operation	Shannon scaling function	Filtering and Stretching (Up sampling)	Two scale relations	Embedded zero tree wavelet (EZW) code
S-4	SLO-1	Continuous wavelet transform	Meyer scaling function	Computing input co- efficient	A wavelet basis for MRA	Huffman code
	SLO-2	Discrete wavelet transform	Battle- Lemarie scaling function	Lattices and Lifting	Functional subspace relation between scaling and wavelet functions	Run length encoding
S-5	SLO-1	Mathematical prelude – Fourier transform	Daubechies scaling function	Vanishing moments	Scaled and translated version of wavelet functions	Set partitioning in hierarchical tree (SPIHT)
	SLO-2	Parseval Plancherel theorem, Convolution, Dilation and its inverse...	Graphical display – Iteration method	Perfect reconstruction filter banks- Introduction	Wavelet series	Embedded block coding with optimized truncation (EBCOT)

S-6	SLO-1	Continuous time frequency representation of signals	Spectrum method	Spectral domain analysis of a 2 channel PR filter bank	PR banks- Coding tutorial - I	Medical Imaging
	SLO-2	The windowed Fourier transform	Eigen value method	Analysis and Synthesis	PR banks- Coding practice exercises-I	Other applications
S-7	SLO-1	Signal spaces	Daubechies wavelet construction-Coding tutorial - I	Quadrature mirror filter (QMF) approach	PR banks- Coding tutorial - II	Audio compression -Simulation using software tools – Tutorial
	SLO-2	Ortho-gonality and Ortho-normality in brief	Coding practice exercises	Half band filter (HBF) approach	PR banks- Coding practice exercises	Audio compression -Simulation using software tools – Practice
S-8	SLO-1	Haar wavelet and scaling function	Daubechies wavelet construction-Coding tutorial- II	Time domain analysis	PR banks- Coding tutorial - III	Image compression -Simulation using software tools – Tutorial
	SLO-2	Triangle scaling function	Coding practice exercises	PR filter requirements	PR banks- Coding practice exercises	Image compression -Simulation using software tools – Practice
S-9	SLO-1	Short time Fourier transform -Coding tutorial	Daubechies wavelet construction-Coding tutorial- III	Bi-orthogonal filter bank	PR banks- Coding practice tutorial- IV	Image compression -Simulation using software tools – Tutorial
	SLO-2	Coding practice exercises	Coding practice exercises	Simple problems(Qualitative) for practice	PR banks- Coding practice exercises	Image compression -Simulation using software tools – Practice

Learning Resources	1. K. P. Soman, K. I. Ramachandran ,N. G. Resmi, <i>Insights Into Wavelets: From Theory to Practice</i> , Third edition, PHI Learning Pvt. Ltd. 2010.	4. S. Burns, A Ramesh, A Gopinath and Haitao Guo, <i>Introduction to Wavelets and Wavelet Transform</i> , Prentice Hall Inc. 1998.
	2. J. C. Goswami and A. K. Chan, <i>Fundamentals of Wavelets: Theory, Algorithms and Applications</i> , John Wiley and Sons, 2011.	
	3. Raguveer M Rao and Ajit S Bopardikar, <i>Wavelet Transforms – Introduction and Applications</i> , Pearson Education, 2008	5. https://nptel.ac.in/courses/103106114/48

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Evaluate Create	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1.Dr. S. Paramasivam, Danfoss Industries Pvt. Ltd, paramsathya@yahoo.com	1.Dr R. Selvarasu, Adama Science and Technology University, Ethiopia, selvarasunaveen@gmail.com	1.Ms K Subha Shramini, SRMIST
2.Mr.Ravikumar A R, PayPal,ravikumar.venkataramani@gmail.com	1.Dr A. Venkadesan, NIT,Pudhucherry, Karaikkal, venkadesan@nitpy.ac.in, avenkyeee@gmail.com	2.Dr K Mohanraj, SRMIST

Course Code	18EEE326T	Course Name	ADVANCED CMOS DEVICES AND TECHNOLOGY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Enrich the students to have basic knowledge in CMOS technology and scaling	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Upgrade the students with the knowledge on design of CMOS devices	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Buildup knowledge on fabrication and isolation of advanced CMOS																		
CLR-4 :	Outline the concept of layout dependent effect, bench marking and interconnects																		
CLR-5 :	Understand the basic of lithography and manufacturability																		
CLR-6 :	Upgrade the knowledge in Nano CMOS devices																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Describe the operation of CMOS devices and scaling technology	2	80	75	H	-	-	-	-	-	-	-	-	-	-	-	L	H	-
CLO-2 :	Interpret how modern CMOS devices are designed for better power performance	3	80	75	H	-	-	-	-	-	-	-	-	-	-	-	H	M	-
CLO-3 :	Perceive knowledge on basic fabrication process flow steps of advanced CMOS devices and isolation	3	80	75	H	-	-	-	-	-	-	-	-	-	-	-	H	H	-
CLO-4 :	Advance knowledge on layout dependent effect, bench marking and interconnects	3	80	75	H	-	-	-	-	-	-	-	-	-	-	-	H	M	-
CLO-5 :	Infer knowledge about advanced lithography and manufacturability	3	80	75	H	-	-	-	-	-	-	-	-	-	-	-	H	H	-
CLO-6 :	Gain knowledge to develop new improved CMOS devices	3	80	75	H	-	-	-	-	-	-	-	-	-	-	-	H	H	-

Duration (hour)	9	9	9	9	9
S-1	SLO-1	History of silicon technology	Mobility enhancement techniques	Fabrication issues	Compact modeling of analog process
	SLO-2	Review of CMOS scaling, moore's law	Gate dielectric material	Process integration	Digital benchmarking of models
S-2	SLO-1	Junction diode	High K material and Material selection	Atomic layer integration	Layout dependent effects
	SLO-2	MOS capacitor	Electronic structure of transition metal and rare earth metals	Metal organic chemical vapor deposition	Metallization
S-3	SLO-1	Circuit considerations	Band gap energies	Physical vapor deposition	Gate electrodes
	SLO-2	CMOS latch-up	Band off-set energies	Etching	Reduction in device parasitics
S-4	SLO-1	MOS transistor classical models	Bond ionicity and dielectric constant	Fabrication of drain and source	Test structures for characterization
	SLO-2	Threshold voltage and V-I characteristics	Carrier effective masses	Ultra shallow junctions	Characterization variation effects on scaling
S-5	SLO-1	Short channel effects	Thermal stability	Isolation techniques	Dopant activation methods
	SLO-2	Drain induced barrier lowering	Disorders and defects	Device, well and dielectric isolation	Device isolation pitch
S-6	SLO-1	Gate leakage current	Extrinsic defects	Integration challenges	Interconnects
	SLO-2	Tunneling	High -K / Si Interface traps	Dopant activation methods	Limits of interconnects
S-7	SLO-1	Sub-threshold conduction	Fermi level pinning	Reduction of parasitics	Current interconnect technologies
	SLO-2	Short channel modifications	Progress integration of high K gate dielectrics and metal gates	Types of stress elements	Optical interconnects
S-8	SLO-1	Features and uniqueness of MOS transistors	Effect of stress	Strained isolation oxide	Scaling of device isolation
	SLO-2	MOS in Deca-Nano meters	Strain on the band structure of silicon	Ultra shallow junction resistance	Layout dependent effect

						CMOS technology design for mobile applications
S-9	SLO-1	Device structure and channel engineering	Effect of gate length on stress effect	Solution to shallow junction resistance problem	Characterization	CMOS technology designed for wireless applications
	SLO-2	Source , drain and gate stack engineering	Mobility enhancements in strained silicon MOSFETS	Fermi level pinning effect of strain to improve the CMOS performance	Test structures used for characterization	Special MOS devices

Learning Resources	1. J. M. Pimbley, M. Ghezzi, H. Parks, <i>Advanced CMOS Process Technology</i> , Academia Press, 2012. 2. HeiWong, <i>Nano-CMOS Gate Dielectric Engineering</i> , CRC, 2012.	3. S. Deleonibus, <i>Electronic Devices Architectures for the Nano-CMOS Era</i> , Jenny Stanford, 2009. 4. B. Wong, F. Zach, V. Moraz, A. Mittal, G. Starr, A. Kahng, <i>Nano-CMOS Design for Manufacturability</i> , Wiley, 2009. 5. http://www.ee.iitb.ac.in/~slodha/advanced-cmos-devices/
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Akash Neel Dey, Grey Orange Pvt. Ltd, akash.d@greyorange.sg	1. Dr. E. S. Sreeraj, NIT-Goa, sreeraj@nitgoa.ac.in	1. Dr. R. Femi, SRMIST
2. Mr. Prakhar Kumar Verma, Xilinx India, prakhar10692@gmail.com	2. Dr. Pravin Mane, BITS-Pilani, pravinmane@goa.bits-pilani.ac.in	2. Dr. M. Jagabar Sathik, SRMIST

Course Code	18EEE327T	Course Name	SENSORS AND TRANSDUCERS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Expose the students to various sensors and transducers for measuring quantities.	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Emphasize the general background and operational concepts in sensors and transducers	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Elicit the characteristics of inductive and capacitive transducers.																		
CLR-4 :	Examine the advances in sensor technology.																		
CLR-5 :	Facilitate the application of microsensors and actuators																		
CLR-6 :	Analyse the performance of various sensors and transducer																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Enumerate the basics of sensors and transducers	2	75	75	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-2 :	Summarize the underlying principles and performance of different sensors	2	75	75	H	H	-	-	-	-	-	M	-	-	-	-	-	-	M
CLO-3 :	Acquire knowledge on the basic conditioning circuits for inductive and capacitive transducers	2	75	75	H	H	-	-	-	-	-	M	-	-	-	-	-	-	M
CLO-4 :	Upgrade the knowledge in sensor technology	2	75	75	H	-	-	-	-	-	-	M	-	-	-	-	-	-	M
CLO-5 :	Attain a broad area of knowledge in Micro sensors and Actuators	2	75	75	H	-	-	-	-	-	-	-	-	-	-	-	H	M	-
CLO-6 :	Predict correctly the expected performance of various sensors and transducers	2	75	75	H	H	-	-	-	-	-	M	-	-	-	-	H	M	M

Duration (hour)		9	9	9	9	9
CVVVS-1	SLO-1	General concepts of measurement systems	Resistive Transducers	General factors governing the design of self-inductance transducer	Piezoelectric transducer	Introduction to Micro sensor
	SLO-2	Terminologies of measurement systems	Principle of operation, construction details	Variable inductance transducer	Hall Effect transducers	Transducers and its interface standard
S-2	SLO-1	Transducer classification based on principle of transduction	Potentiometer ,Characteristics	Linear Variable Differential Transformer	Magnetostrictive transducers	Evolution of micro-fabrication
	SLO-2	Flow rate sensing elements	Applications of potentiometer	Expression for mutual inductance variation	Fiber optic Sensors	Evolution of Micro system and Microelectronics
S-3	SLO-1	Classification of errors	Loading effect	Rotary variable differential transformer	Geiger counters	The multidisciplinary nature of MEMS, Miniaturization
	SLO-2	Error Analysis	Strain Gauge, Types of Strain gauges	Applications of LVDTs	Scintillation detectors.	Applications of micro systems in automotive, and health care
S-4	SLO-1	Units and standards of measurements	Applications of Strain gauges	Output input relationship	Film sensor	Applications of micro systems in aerospace, and teleCommunication fields
	SLO-2	General input and output configuration	Gauge Factor	Microsyn Transducer	Magneto elastic sensor	Biomedical sensors
S-5	SLO-1	Analog & digital modes of operation	Load cells	Control type Synchro system	Digital displacement sensors	Biosensors
	SLO-2	Null & deflection methods	Torque measurement using strain gauges.	Resolvers classification and application	Proximity sensors	Chemical sensors
S-6	SLO-1	Methods of correction for interfering & modifying inputs	Pressure measurement using strain gauges	Capacitive Transducer	Pneumatic sensors	Optical sensors

	SLO-2	Static characteristics of a measurement system	Measurement of Linear Velocity	Variable Area Type Capacitive Transducers	Semiconductor sensor	Pressure sensors
S-7	SLO-1	Dynamic characteristics of a measurement system	Resistance Thermometers	Variable Air Gap type Capacitive Transducers	Smart sensors	Acoustic wave sensors
	SLO-2	Statistical analysis of measurement data	Thermocouples	variable dielectric constant type	Radiation sensors	Microactuators
S-8	SLO-1	Electric Transducer	Thermistors	Sensitivity factors	Pyroelectric type	Actuators using thermal forces
	SLO-2	Advantages of Electric Transducer	Thermistor material, shape, ranges and accuracy specification	Nonlinearity factors	Digital encoding Transducer	Actuators using shape memory alloy
S-9	SLO-1	Transducer actuating mechanism	Hotwire anemometers	Advantages of capacitive transducer	Photo optic Transducer	Actuators using piezoelectric crystals
	SLO-2	Factors influencing the choice of transducer	Temperature compensation	Applications of capacitive transducer	Environmental Monitoring sensors (Water Quality & Air pollution)	Actuators using electrostatic forces

Learning Resources	1.Sawhney. A.K, A Course in Electrical and Electronics Measurements and Instrumentation, 19th Edition, DhanpatRai& Company Private Limited,2014. 2.Doebelin. E.A, Measurement Systems – Applications and Design, Tata McGraw Hill, New York, 2007..	3.PatranabisD, Sensors and Transducers, Prentice Hall of India, 2010. 4.P. Bentley, Principles of Measurement Systems, III Edition, Pearson Education, 2000 5. https://nptel.ac.in/courses/112103174/3
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.Muralikrishna, National Instruments, emkkrishnan@gmail.com	1. Dr. A. Venkadesan, NIT Puducherry, venkadesan@nitpy.ac.in	Ms. S.Lourdu Jame, SRMIST
2. Mr.Senthilkumar,ATI, rskrd1962@gmail.com	2.Dr. S. Arul Daniel, NIT Trichy, daniel@nitt.edu	Dr.S.Padmini, SRMIST

Course Code	18EEE416T	Course Name	MEDICAL ELECTRONICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Create knowledge on physiological system of the human body	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Learn the various biomedical sensor and amplifiers	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Identify the bio potential electrodes used for ECG, EEG, EOG and ENG measurements																		
CLR-4 :	Understand the various analysis techniques of bio signals and data acquisition systems																		
CLR-5 :	Expose the students to various medical application using optical electronics																		
CLR-6 :	Demonstrate the physiological system, its measurements and application of electronics in the medical field																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Describe the physiological system of the body	2	80	75	H	-	-	-	-	-	-	-	-	-	-	-	-	M	-
CLO-2 :	Use the biomedical sensor and amplifiers	3	80	75	H	-	-	-	H	-	-	L	L	-	-	-	L	M	L
CLO-3 :	Recognize the biopotential electrodes used for ECG, EEG, EMG, ERG and EOG measurements	2	80	75	H	-	-	-	-	-	-	-	-	-	-	-	L	M	-
CLO-4 :	Apply and analyze bio signals and data acquisition system for biomedical application	3	80	75	H	-	-	-	H	-	-	-	L	-	-	-	L	M	-
CLO-5 :	Interpret the various medical application using optical electronics	2	80	75	H	-	-	-	-	-	-	L	-	-	-	-	H	M	L
CLO-6 :	Identify the human body physiological system along with various measurements and application of electronics in the medical field	3	80	75	H	-	-	-	H	-	-	L	L	-	-	-	H	M	L

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Introduction to the physiological system of the body	Sensor parameters	Electrode-electrolyte interface	Introduction to bio signal analysis
	SLO-2	Cardiovascular system	Physical principle of sensing	Electrode types: Surface metal plate electrode	Introduction to medical application using optical electronics
S-2	SLO-1	Respiratory system	Strain gauge, Piezo electric transducer	Needle and wire electrode	Charge coupled devices
	SLO-2	Parts of respiratory system	Load cell, pitot tube	Micro electrode	Types of analog to digital converters
S-3	SLO-1	Nervous system	High impedance charge output	Electrocardiography: Lead system for recording ECG	Flash type ADC
	SLO-2	Structure of neuron and phenomenon of impulse transmission	Linear variable differential transformer	ECG measurement	Fiber optics introduction
S-4	SLO-1	Sources of biomedical signals	Hall effect magnetic sensor	Electrocardiograph	Types of digital to analog converters
	SLO-2	Basic medical instrumentation system	Optical encoder	Electroencephalography: Signal sources	Fiber optics classification
S-5	SLO-1	Performance requirements of medical instrumentation system	Accelerometer	Placement of electrodes	Successive approximation DAC
	SLO-2	Intelligent medical instrumentation system	RTD	EEG recording modes	Features of optical fibers
S-6	SLO-1	Use of microprocessors in medical instruments	Thermistor	Electroencephalograph	Signal to noise improvement
	SLO-2	The microprocessor	Thermocouple	Electromyography: EMG electrodes	Analysis of optical fiber
S-7	SLO-1	The microcontroller	Sensor interfacing	Electromyograph	Amplitude measurements
	SLO-2	Interfacing of analog signals to microprocessors	Driving bridges	Determination of conduction velocities in motor nerves	The step-index fiber
					Signal recovery
					Data acquisition
					Sample and hold conversion
					Sectional imaging
					ECG acquisition
					EMG acquisition
					Endoscope
					EOG acquisition
					Digital X rays

S-8	SLO-1	PC based medical instruments	Signal conditioning amplifiers	Quantity of electricity associated with muscle contraction	EEG acquisition	Medical sensors from fiber optics
	SLO-2	General constraints in design of medical instrumentation systems	Instrumentation amplifiers	Electrical activity of EOG signal	ERG acquisition	Fiber optics for circulatory system
S-9	SLO-1	Regulations of medical devices	Isolation amplifiers	Electroretinograph	Pattern recognition	Fiber optics for respiratory system
	SLO-2	Types of standards	Simulation of pressure sensor	Electrooculograph	Simulation of flash type ADC	Lasers in biomedical field

Learning Resources	1. Leslie Cromwell, Fred. J. Weibell and Ench Apleiffer, Biomedical Instrumentation and measurements Prentice Hall of India, 2 nd ed., 2004	3. C.Raja Roa & .K Guha, Principles of medical electronics and biomedical instrumentation, Universities press, 2001
	2. Kandpur R.S, Handbook of Biomedical Instrumentation, Tata McGraw Hill, 2 nd ed., 2011	4. Rinaldo J. Perez, Design of medical electronic devices, Academic press 2002 5. https://swayam.gov.in/nd1_noc19_bt28/preview ,NPTEL Online Course-Biomedical nanotechnology

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1.Mr.Muralikrishna, National Instruments, emkkrishnan@gmail.com	1.Dr. S. Ramareddy, Jerusalem College of Engineering, srr.victory@gmail.com	1. Dr.Y.Jeyashree, SRMIST
2. Mr.senthilkumar, ATL, rskrd1962@gmail.com	2.Dr Subhransu Sekhar Dash, Government College of Engineering, Keonjhar, Subhransudash_fee@gcekjir.ac.in	2. Mrs. R.Uthra, SRMIST

Course Code	18EEE417T	Course Name	ADVANCED SEMICONDUCTOR DEVICES				Course Category	E	Professional Elective				L	T	P	C								
													3	0	0	3								
Pre-requisite Courses	Nil		Co-requisite Courses	Nil		Progressive Courses	Nil																	
Course Offering Department		Electrical and Electronics Engineering				Data Book / Codes/Standards				Nil														
Course Learning Rationale (CLR):		The purpose of learning this course is to:					Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Outline the aspects of electrical properties of semiconductors					1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLR-2 :	Learn about diode fabrication, properties, and characterization					Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3	
CLR-3 :	Provide the fundamentals of MOSFET fabrication and scaling laws																							
CLR-4 :	Enrich the knowledge on structure quantum effects and development of advanced transistor devices																							
CLR-5 :	Upgrade knowledge on basic principle of operation of LED and solar cell																							
CLR-6 :	Understand the characteristics, operation and limitations of semiconductor devices																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:					2	80	75	H	L	L	L	-	-	-	-	-	-	-	H	H	-	
CLO-1 :	Enrich the knowledge on semiconductor material, properties and classical semiconductor devices					3	80	75	H	L	L	L	-	-	-	-	-	-	-	-	M	H	-	
CLO-2 :	Interpret the fabrication and characterization of PN diode					3	80	75	H	L	L	L	-	-	-	-	-	-	-	-	H	H	-	
CLO-3 :	Perceive knowledge on advanced MOSFET devices, characteristics, application and fabrication					3	80	75	H	L	L	L	-	-	-	-	-	-	-	-	L	M	-	
CLO-4 :	Gain knowledge of hetero structure, quantum effect and transport in the development of advanced transistor devices					3	80	75	H	L	L	L	-	-	-	-	-	-	-	-	H	M	-	
CLO-5 :	Infer knowledge on optoelectronics, solar cell and photovoltaic					3	80	75	H	-	-	-	-	-	-	-	-	-	-	-	H	M	-	
CLO-6 :	Gain knowledge to develop new semiconductor devices					3	80	75	H	L	L	L	-	-	-	-	-	-	-	-	M	H	-	
Duration (hour)	9		9		9		9		9		9													
S-1	SLO-1	Semiconductor materials	Structure of PN junction diode	Metal oxide semiconductor transistor structure	Bipolar transistor structure	Optoelectronic semiconductor devices																		
	SLO-2	Electrons and holes	Zero applied bias	Working of two terminal MOS structure	Principle and modes of operation	Optical absorption																		
S-2	SLO-1	Crystal structures	Reverse applied bias	Inversion channel MOSFET	Minority carrier distribution	Light emitting diode (LED)																		
	SLO-2	Atomic bonding and bond models	Fabrication process	MOSFET Scaling effect	Low frequency common base current gain	Vertical cavity surface emitting laser (VCSEL) diode																		
S-3	SLO-1	Equilibrium and non-equilibrium	Non uniform doped junction	Electrical and DC MOSFET characteristics	Nonlinear effects	Laser diode arrays																		
	SLO-2	Imperfections and Impurities in Solids	Equilibrium electrical properties of a PN junction	Capacitance - voltage characteristics	Equivalent circuit models	Hetero junction LED types																		
S-4	SLO-1	Statistical distribution	PN junction current	Current-voltage characteristics	Frequency limitations	Photoluminescence																		
	SLO-2	Drift and diffusion	DC electrical characteristics	Fabrication of MOSFET	Hetero structure and Quantum well	Electroluminescence																		
S-5	SLO-1	Generation and recombination	Small signal model of PN junction	Small signal analysis	Super lattice and modulation	Advanced semiconductors for solar cell and photovoltaic applications																		
	SLO-2	Principles of Quantum mechanics	Small signal characteristics	Frequency limitations	Two dimensional electron gas (2DEG)	Hetero junction solar Cell																		
S-6	SLO-1	Schrodinger's Wave Equation	Diode switching transients	Switching properties and circuit applications	Coulomb blockade effect, quantized transport	Amorphous Silicon solar Cells																		
	SLO-2	Extensions of the wave theory to atoms	Generation and recombination current	CMOS technology	Large signal switching	Photo detectors																		
S-7	SLO-1	Quantum theory of solids	Charge storage	Gallium nitride (GaN) and Silicon Carbide (SiC) based devices	Ballistic transport and Quantum capacitance	PIN photo diode and photo transistor																		
	SLO-2	Allowed and forbidden energy bands	Junction breakdown	Tunneling field effect transistor (TFET)	High electron mobility transistor (HEMT)	Optical switches and amplifiers																		
S-8	SLO-1	Electrical conduction in solids	Tunnel diode	Thin film transistor (TFT)	Modulation doped FET (MODFET)	Active nano crystalline devices																		
	SLO-2	Semiconductor in equilibrium	Schottky diode	Junction gate field effect transistor (JFET)	Single electron and hetero junction transistor	Nano electronics																		
S-9	SLO-1	Carrier transport phenomena	Metal-semiconductor junctions	Nonlinear effects	Ballistic transistor	Applications of nano electronics																		

	SLO-2	Non-equilibrium excess carriers in semiconductors	Hetero junctions	Threshold voltage modifications	Poly silicon emitter and silicon-germanium transistor	Organic semiconductors
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Learning Resources	1. Donald A. Neamen, <i>Semiconductor Physics and Devices: Basic Principles, Fourth Edition</i> , McGrawHill, 2012. 2. Streetman, S. K. Banerjee, <i>Solid State Devices, Ed. 6, Prantice Hall, 2006.</i>	3. S.M. Sze, Kwok K. Ng, <i>Physics of Semiconductor Devices, Third Edition</i> , Wiley, 2007 4. Chih-Tang Sah, <i>Fundamentals of Solid-State Electronics</i> , World Scientific, 1996. 5. http://www.ioffe.ru/SVA/NSM/Semicond/index.html
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Prakhar Kumar Verma, Xilinx India,, prakhar10692@gmail.com	1. Dr. E. S. Sreeraj, NIT-Goa, sreeraj@nitgoa.ac.in	1. Dr. R. Femi, SRMIST
2. Mr. Akash Neel Dey, Grey Orange Pvt. Ltd, akash.d@greyorange.sg	2. Dr. Dipankar Pal, BITS-Pilani, dipankarp@goa.bits-pilani.ac.in	2. Dr. M. Jagabar Sathik, SRMIST

Course Code	18EEE418T	Course Name	MOBILE COMMUNICATION	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Educate on Cellular Concepts and Wireless Standards	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Understand the Statistical Multipath Channel Models.	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Provide adequate knowledge on Digital Modulation & Multiple Access Schemes																		
CLR-4 :	Give a basic knowledge in Capacity of Wireless Channels																		
CLR-5 :	Educate on Multiple Antennas & Space Time Communications																		
CLR-6 :	Create overall understanding of cellular concepts, multiple antennas and space time Communication.																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Gain Knowledge in the concepts of cellular Communication.	1	80	75	H	M	-	-	-	-	M	-	-	-	-	-	H	M	M
CLO-2 :	Comprehend the statistical multipath channel models	2	80	75	H	M	-	-	-	-	-	-	-	-	-	-	H	M	-
CLO-3 :	Infer the various schemes in the digital modulation and multiple access	2	80	75	H	M	-	-	-	-	-	-	-	-	-	-	M	L	-
CLO-4 :	Identify the capacity of wireless channels	2	80	75	H	M	-	-	-	-	-	-	-	-	-	-	H	L	-
CLO-5 :	Recognize the concepts on multiple antennas & space time Communications	3	80	75	H	M	-	-	-	-	M	-	-	-	-	-	H	M	M
CLO-6 :	Gain Knowledge on the overall Communication process involved in cellular Communication.	3	80	75	H	M	-	-	-	-	M	-	-	-	-	-	H	M	M

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Evolution of Mobile Radio Communication	Signal propagation	Multiple access schemes-FDMA (Frequency Division Multiple Access)	Capacity in Additive White Gaussian Noise Channel	MIMO
	SLO-2 Cellular Telephone Systems-Cell structures	Propagation mechanism- reflection,	Non-linear effects in FDMA	Capacity of flat fading channels-Channel and System Model	Space time signal processing
S-2	SLO-1 Frequency Reuse	Refraction	TDMA (Time Division Multi Access)	Channel and Distribution Information Known	spatial multiplexing
	SLO-2 Example Problems in Frequency Reuse	Diffraction	Efficiency of TDMA and number of channels in TDMA system	Channel side information at receiver	Diversity/Multiplexingtradeoff
S-3	SLO-1 Improving Coverage and Capacity in Cellular Systems-Cell Splitting	Scattering	Spread spectrum multiple access: CDMA (Code-Division Multiple Access)	Shannon (Ergodic) Capacity	Performance measures- Outage
	SLO-2 Sectoring	Large scale signal propagation	Hybrid FDMA/CDMA(FCDMA)	Capacity with outage	Average SNR
S-4	SLO-1 Repeaters for Range Extension	Lognormal Shadowing	SDMA(Space Division Multiple Access)	Channel side information at transmitter and receiver	Average symbol
	SLO-2 A Microcell Zone Concept	Small-Scale Fading and Multipath -Small-Scale Multipath Propagation	Modulation schemes- BPSK (Binary Phase-shift keying)	Shannon Capacity	Bit error rate
S-5	SLO-1 Channel assignment Strategies	Doppler shift, Parameters of Mobile Multipath Channels	Spectrum and Bandwidth of BPSK	Zero-Outage capacity and channel inversion	Receiver structure
	SLO-2 Handoff Strategies - Prioritizing Handoffs	Types of Small-Scale Fading	QPSK (Quadrature Phase Shift Keying), Spectrum and Bandwidth of QPSK Signals	Outage capacity	Diversity receivers- selection
S-6	SLO-1 Practical Handoff Considerations	Statistical multipath channel models	QPSK Transmission and Detection	Truncated Channel Inversion	MRC receivers
	SLO-2 Interference and System Capacity	Narrowband Wideband Fading Models	Offset QPSK	Capacity with receiver Diversity	DFE
S-7	SLO-1 Channel Planning for Wireless Systems	Power delay profile	$\pi/4$ QPSK	Capacity comparisons	System examples- GSM

	SLO-2	Adjacent Channel Interference	Average and RMS delay spread	$\pi/4$ QPSK transmission and detection techniques	Channel and System Model	EDGE
S-8	SLO-1	Power Control for Reducing Interference- Power control of Cellular Circuits	Coherence bandwidth and Coherence time	QAM (quadrature amplitude modulation)	Capacity of frequency selective fading channels	GPRS
	SLO-2	Wireless Standards: Overview of 2G	Flat and Frequency selective fading	MSK (minimum-shift keying) and GMSK (Gaussian minimum shift keying)	Time Invariant Channels	IS-95
S-9	SLO-1	3G cellular standards	Slow and fast fading	Multicarrier Modulation	Time Varying Channels	CDMA 2000
	SLO-2	Channel Planning for Wireless Systems	Average fade duration and Level crossing rate	OFDM (Orthogonal Frequency-Division Multiplexing)	Optimal Power allocation of Block Frequency -Selective Fading	WCDMA.

Learning Resources	1. Andrea Goldsmith, <i>Wireless Communications</i> , Cambridge University Press, 2005. 2. Theodore Rappaport, <i>Wireless Communications: Principles and Practice</i> , 2nd edition, Prentice Hall, 2001. 3. David Tse and Pramod Viswanath, <i>Fundamentals of Wireless Communication</i> , Cambridge University Press, 2005. 4. Rishi Kappal and Milind Pande, <i>Nex Gen Mobile Communication</i> , Mc Graw, 2015. 5. https://www.youtube.com/playlist?list=PL1A4AFAC7AC1909C9
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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2. Mr. K. Muniyandi, Omantel TeleCommunication, muniyandi.kannadasan@omantel.com	2. Dr. G. Thavasi Raja, NIT Trichy, thavasi@nitt.edu	2. Dr. M. Jagabar sathik, SRMIST

Course Code	18EEE419T	Course Name	SATELLITE COMMUNICATION	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering		Data Book / Codes/Standards	Nil	

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Educate on Elements of Satellite Communications and Orbital Aspects	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Understand the role of Satellite Link				Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3			
CLR-3 :	Provide adequate knowledge on Modulation for Satellite Links				H	M	-	-	-	-	-	-	-	-	-	-	-	M	M	-		
CLR-4 :	Extend knowledge on Multiple Access for Satellite Links				H	M	-	-	-	-	-	-	-	-	-	-	-	M	M	-		
CLR-5 :	Enlighten the Error Control For Digital Satellite Links				H	H	-	-	-	-	-	-	-	-	-	-	-	H	H	-		
CLR-6 :	Educate various concepts in Satellite Communication				H	H	-	-	-	-	-	-	-	-	-	-	-	H	H	-		
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLO-1 :	Gain knowledge on elements of satellite Communications and the concepts of Satellite Orbits	1	80	75	H	M	-	-	-	-	-	-	-	-	-	-	-	-	-	M	M	-
CLO-2 :	Relate the role of Satellite Link	2	80	75	H	M	-	-	-	-	-	-	-	-	-	-	-	-	-	M	M	-
CLO-3 :	Infer the necessity of Modulation for Satellite Links	2	80	75	H	M	-	-	-	-	-	-	-	-	-	-	-	-	-	M	M	-
CLO-4 :	Interpret the Multiple Access For Satellite Links	2	80	75	H	H	-	-	-	-	-	-	-	-	-	-	-	-	-	H	H	-
CLO-5 :	Inspect Error Control For Digital Satellite Links	3	80	75	H	H	-	-	-	-	-	-	-	-	-	-	-	-	-	H	H	-
CLO-6 :	Gain Knowledge on various concepts related to Satellite Communication	3	80	75	H	H	-	-	-	-	-	-	-	-	-	-	-	-	-	H	H	-

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Satellite systems-Attitude and Orbit Control System(AOCS)	Basic Transmission Theory	Frequency modulation, Waveform Equation for FM	Frequency Division Multiple Access (FDMA)	Error detection and correction
	SLO-2	Telemetry, Tracking, Command and Monitoring (TTC&M)	Example Problems in Transmission Theory	Bandwidth of FM Signals: Carson's Rule	Inter Modulation, Inter Modulation Example	Channel Capacity
S-2	SLO-1	Power Systems, Communication Subsystems	System noise temperature	Baseband S/N Ration for FM Signals	Calculation of C/N with Intermodulation	Error Control Coding
	SLO-2	Satellite Antennas	Calculation of System noise temperature	Pre-emphasis and de-emphasis	Time Division Multiple Access (TDMA)	Linear and Cyclic Block Codes
S-3	SLO-1	Transmission and Multiplexing	Noise figure and Noise Temperature	Analog FM Transmission by satellite	Bits, Sample and Channels	Golay Codes
	SLO-2	Modulation Multiple access-advent of Digital satellite Communications	G/T ratio for Earth Stations	Television Signals	TDMA Frame Structure	Performance of Block Error Correction Codes
S-4	SLO-1	The Equations of the Orbit	Design of Downlink	S/N Rations for FM Video Transmission	Synchronization in TDMA Networks	Convolution Codes
	SLO-2	Locating the Satellite in the Orbit	Link Budgets	FM Threshold, SCPC FM Links	Transmitter Power in TDMA Networks	Implementation of Error Detection on Satellite Links
S-5	SLO-1	Orbital elements	Design of Uplink	Concept of FM Squared of transmitting analog satellite audio	Satellite Switched TDMA	Concatenate Coding
	SLO-2	Look angle Determination- The Sub-satellite point	Limits on link performance	Digital Transmission	On-board Processing	Interleaving
S-6	SLO-1	Elevation angle Calculation	Design of Satellite links for specified (C/N)	Baseband Digital Signals,	Baseband Processing Transponders	Turbo Codes

	SLO-2	Azimuth angle Calculation	Overall $(C/N)_0$ with Uplink and Downlink Attenuation	Base Band Transmission of Digital Data	Satellite Switched TDMA with Onboard Processing	Repetition Codes
S-7	SLO-1	Geostationary orbit	Uplink and Downlink Attenuation in Rain	Band-pass Transmission of Digital Data	Concept of Pre-assignment	Cyclic Codes
	SLO-2	Visibility	Uplink attenuation and $(C/N)_{up}$, Downlink attenuation and $(C/N)_{dn}$	Analysis of Digital Transmission	Demand Access Multiple Access (DAMA)	Basic of Convolution codes
S-8	SLO-1	Orbital perturbations Longitudinal Changes: Effects of the Earth's Oblateness	Satellite Design for Specific Performance	Digital Modulation	Random Access	Catastrophic Convolutional Code
	SLO-2	Inclination Changes: Effects of the Sun and the Moon	Satellite Communication Link Design Procedure	Digital Demodulation	Packet Radio Systems and Protocols	Performance of block error correction codes
S-9	SLO-1	Orbit Determination	Propagation effects and their Impact on Satellite-Earth Links Quantifying Attenuation and Depolarization: Rain and Ice effects	Digital transmission of Analog signals PCM	Code Division Multiple Access (CDMA)	Implementation of Error Detection on Satellite Links.
	SLO-2	Orbital effects in Communication system performance	Prediction of Rain Attenuation	DPCM and DM	CDMA Capacity	Example Problem on Error Detection on Satellite Links

Learning Resources	1. Dennis Roddy, <i>Satellite Communications</i> , 4 th Edition, Mc Graw-Hill, 2017. 2. Timothy Pratt, Charles W Bostian, and Jeremy Allnutt, <i>Satellite Communications</i> , John Wiley and Sons, New Delhi, 2008	3. Tri T Ha, <i>Digital Satellite Communications</i> , Tata McGraw Hill, New Delhi, 2010. 4. Richaria M, <i>Satellite Communication Systems Design Principles</i> , McGraw Hill, Inc., New York, 1999. 5. https://www.isro.gov.in/applications/satellite-Communication
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. C. Madesh, Bharti Airtel, madesh.c@airtel.com	1. Dr. G. Lakshmi Narayanan, NIT, Trichy, laksh@nitt.edu	1. Mr. T. Vigneswaran, SRMIST
2. Mr. K. Muniyandi, Omantel TeleCommunication, muniyandi.kannadasan@omantel.com	2. Dr. G. Thavasi Raja, NIT Trichy, thavasi@nitt.edu	2. Dr. A.Rathinam, SRMIST

Course Code	18EEE420T	Course Name	EMBEDDED SYSTEM	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Illustrate the concept of embedded system .	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Discuss the various Embedded Controllers with its Interfacing Components	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Explain the different Embedded System protocol layers and bit configurations.	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Understand the basics of the RTOS, its challenges and issues.	Expected Attainment (%)	Design & Development
CLR-5 :	Impart knowledge on the programming skills and execute the different programs using Embedded C		Analysis, Design, Research
CLR-6 :	Understand the concept of embedded system and develop code for real time applications		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Understand the fundamentals of Embedded System	1 75 75	H - - - - - - - - - - - - - - - -
CLO-2 :	Comprehend the various bus and interfacing components in digital controller.	2 75 75	H - - - - - - - - - - - - - - - -
CLO-3 :	Implement the embedded networking concept and various bus protocols	3 75 75	H M M M - - - M - - - - - H M M
CLO-4 :	Analysis the concept of RTOS, the challenges and issues in RTOS.	3 75 75	H M H M H - - - - - - - M M -
CLO-5 :	Develop the embedded system programs for different Real Time applications	3 75 75	H H H H H - - M - - - - H M M
CLO-6 :	Design and development of Embedded coding for electrical engineering applications	3 75 75	H M H H H - - M - - - - H M M

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction To Embedded System: Embedded system,	Memory system mechanisms - Various memory systems	Serial Bus Communication protocols	Message Queues	Programming for LED Display
	SLO-2	Functional building block of embedded system	CPU bus - Memory devices - I/O devices	RS232 standard – RS422,RS 485	Mailboxes and Pipes	Embedded C Seven Segment Display
S-2	SLO-1	Characteristics of embedded system applications	Component interfacing Interrupt – Handler	Characteristics of RS232, RS422, RS423 and RS485	Time functions - Events	Communication Protocols:-I ² C initialization and formation
	SLO-2	Reliability, life time, power consumption	Saving and Restoring the content - Disabling Interrupts.	CAN Bus with control word registers	Memory Management	programming using embedded C
S-3	SLO-1	Challenges in embedded system design	The Shared data Problem – Shared data bug	Serial Peripheral Interface (SPI)	Interrupt Routine in RTOS Environment.	Programming Using SPI Protocols.
	SLO-2	Optimizing the Power Dissipation, reliability, upgradability	Atomic and Critical sections – Interrupt Latency	Inter Integrated Circuits (I ² C)	Design Using RTOS : Design Principles – Short Interrupt Routines	Programming for CAN Bus Protocols
S-4	SLO-1	Embedded system design processes.	Embedded Software Architecture : Round – Robin and other cycles	ZigBee	RTOS Tasks – Tasks for Priority	Commercial Applications: Washing Machine,
	SLO-2	Characteristics of embedded system applications	Round-Robin with interrupts– A Communication Bridge as an Example	Bluetooth with various protocol	Tasks for Encapsulation	Vending machine with flow diagram
S-5	SLO-1	types of embedded system with examples	Characteristics – Functions – Queue – Scheduling	Interfacing Protocols- GPIB	Creating and Destroying tasks	Laser Printer, underground tank monitor,
	SLO-2	Performance & Design issues	Various Queue and scheduling methods	FIREWIRE(IEEE 1394 standard)	Avoidance - Tank Monitoring System	Cordless Bar, Code Scanner
S-6	SLO-1	Performance & Design issues – Throughput – Response – Testability –	Software development process Architecture – Assembly and compiling	Universal Serial Bus (USB)	Design as example – Time Scheduling	Power Electronics Applications: Operation of DC/DC Converter
	SLO-2	Debuggability – Reliability – Memory space – Program Installation	Linking and loading, programme flow	need for device drivers	Embedded Programming and Communication Protocols: Introduction	Embedded C programming for DC-DC Converter pulse generation.

S-7	SLO-1	Power Consumption – Processor Hogs – Cost	Basic compilation techniques	Real Time Operating Systems : Tasks and Task states	Importance of Communication protocol and types of protocols	Introduction to 180Degree mode Three phase inverter
	SLO-2	Small size and weight, Real time/reactive operation, End-product utility, System-level requirements	Program optimization	Tasks and Data share	Embedded C Programming for 8051	Various mode of operation and switching sequence
S-8	SLO-1	Embedded System Architecture : Computer architecture taxonomy	Difference between task and process Multiple tasks	Shared data problems – Re-entrancy-Reentrancy Rules	Various programming language and advantage of embedded C	Programming for Three phase 180° Mode Inverter PWM pulse generation
	SLO-2	Harvard , von Neumann, and hybrid architectures	multiple processes with simple example	Semaphores and Shared data	Syntax, variable initialization and assigning a port address	Applications of Three phase inverter
S-9	SLO-1	CPUs, various processing unit and control units	Embedded Networking: Introduction, I/O ports	RTOS Semaphores	Header file inclusions, condition loop,	Basic concept of induction motor drive and speed control of V/F method
	SLO-2	Programming input and output, Supervisor mode, Exceptions & Traps, Co - processors	Different type of buses	Initializing semaphores Reentrancy and Semaphores – Multiple semaphores	Simple programme using embedded C	Controller Implementation for induction motor drive applications

Learning Resources	<ol style="list-style-type: none"> Wayne Wolf, Computers as Components: Principles of Embedded Computer Systems Design, The Morgan Kaufmann Series in Computer Architecture and Design, Elsevier Publications, 2008. Rajkamal, Embedded Systems – Architecture, Programming and Design, Tata McGraw-Hill Publishing Company Ltd., New Delhi, 3rd Edition 2010. Sriram V Iyer, Pankaj Gupta, Embedded Real-time Systems Programming, Tata McGraw-Hill Publishing Company Ltd, New Delhi, 1st Edition 2017 David E.Simon, An Embedded Software Primer, Pearson Education, 1999. 	<ol style="list-style-type: none"> Muhammad Ali Mazid, The 8051 Microcontrollers & Embedded Systems, Pearson, 2008 Kenneth Ayala, The 8051 Microcontroller & Embedded Systems using Assembly and C with CD https://nptel.ac.in/courses/108102045/
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry		Experts from Higher Technical Institutions
1. Mr. P.Pangayaselvan, Embedded Engineer, Verizon Technologies, vpangayaselvan@yahoo.co.in		1. Dr. S.Moorthi, NIT, Trichy, srimoorthi@nitt.edu
2. Mr. V.Suresh, Vi-Microsystem, Chennai		2. Dr.M.Manimara Boopathi, Vel Tech University
		Internal Experts
		1. Dr. M.Jagabar Sathik, SRMIST
		2. Dr.A.Rathinam, SRMIST

Course Code	18EEE421T	Course Name	VLSI DESIGN	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning		
CLR-1 :	Illustrate the MOS fabrication technologies and understand the electrical properties of MOS, CMOS and Bi CMOS circuits				1	2	3
CLR-2 :	Describe CMOS technology-specific layout rules in the placement and routing of transistors and interconnect and to verify the functionality, timing, power, and parasitic effects				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)
CLR-3 :	Describe the various parameters and its characteristics of CMOS technology						
CLR-4 :	Identify the real-time VLSI tools and its applications						
CLR-5 :	Interpret the various testing methods, design tools and chip-level design techniques						
CLR-6 :	Construct the digital logic gate using VLSI design tools						
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:					
CLO-1 :	Understand the steps for MOS fabrication technologies and analyze electrical behavior of MOS, CMOS and Bi CMOS circuits.				2	75	75
CLO-2 :	Draw the layout of integrated circuits following design rules				2	75	75
CLO-3 :	Analyze the different CMOS technology and its characteristics				3	75	75
CLO-4 :	Develop the coding for FPGA				3	75	75
CLO-5 :	Design a VLSI project having a set of objective criteria and design constraints				3	75	75
CLO-6 :	Design a digital components and basic logic gates circuits using VLSI tools				2	75	75

Program Learning Outcomes (PLO)														
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
H	-	-	-	-	-	-	-	-	-	-	-	-	M	-
H	-	-	-	-	-	-	-	-	-	-	-	-	M	-
H	H	H	H	M	-	-	-	-	-	-	-	M	H	-
H	H	H	H	M	-	-	-	-	-	-	-	H	H	-
H	H	H	H	H	-	-	-	-	-	-	-	H	H	-
H	H	H	H	H	-	-	-	-	-	-	-	H	M	-

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Introduction to IC Technology–MOS	VLSI circuit design processes: MOS Layers- Mask Layout, Layer contact mask layout representation	Gate level design: Transmission Gates	Introduction to design tools FPGAs (Xilinx 4000series)–Features and basic details of FPGA
	SLO-2	Introduction to IC Technology -PMOS	Coloured Stick Diagrams:- capabilities and limitations of stick diagram	Gate level design: Alternate gate circuits	Various functional block diagram with merits and demerits
S-2	SLO-1	Introduction to IC Technology NMOS, CMOS	Types of Design Rules VLSI circuit design	Basic circuit concepts: Sheet Resistance RS	Different syntax of fpga coding and variables
	SLO-2	Introduction to IC Technology Bi-CMOS Historical Perspective& Bi-CMOS technologies.	Layout of circuit diagram	Concept of RS in MOS	Simple basic programme
S-3	SLO-1	basic electrical properties: Basic Electrical Properties of MOS Circuits:	Layer Representations	Area Capacitance Units, Calculations, Delays	CPLDs (Xilinx 9500series)- Features and basic details
	SLO-2	basic electrical properties: Basic Electrical Properties of Bi-CMOS Circuits:	Example of layer presentation	Estimation of Delay and INVERTER DELAYS Estimation of CMOS inverter delay Rise & Fall time estimation	Various functional block diagram with merits and demerits
S-4	SLO-1	Ids-Vds relationships	CMOS Design rules for wires	Capacitance Modeling Driving large Capacitive Loads	Different syntax of CPLDs coding and variables
	SLO-2	Ids-Vds its characteristics	Layout Design rules & Lambda (A)	Sizing Factor (s) , Inverter gain, Delay Optimization Problem	Simple basic programme

S-5	SLO-1	MOS characteristics - transistor threshold Voltage, V_{th}	Design rules of Contacts	Wiring Capacitances, Fan-in and fan-out	Programmable Array Logic: introduction and applications	Test Principles, Design Strategies for test
	SLO-2	MOS characteristics - g_m , g_{ds} characteristics	Design rules of Transistors	Effect of Capacitive Loading, Propagation Delay in Timing Diagrams	Operation and logic with simple problem	Fault Modeling, Design-for-Testability
S-6	SLO-1	Basic design parameters:- Figure of merit, Pass transistor	Layout Diagrams for NMOS Inverters and Gates	Choice of layers. SUBSYSTEM DESIGN: Shifters,	Design Approach with various steps	Chip-level Test Techniques
	SLO-2	MOS Transistor circuit model, Latch-up in CMOS circuits	Example layout of basic logic gates	Choice of layers. Adders, ALUs	Fuse mapping examples	Moving test up the flowFlop Factor
S-7	SLO-1	characteristics of NMOS Inverter, Various pull ups	Layout Diagrams :-CMOS Inverters and Gates	Choice of layers. Multipliers	Multiplier logic	System-level Test Techniques
	SLO-2	Resistive Load, Inverter with N type MOSFET Load	Example layout of CMOS inverters	Choice of layers. Parity generators	Alternate representation of high Fan-in structures	Characterization Test, Functional Board Testing, In-circuit testing
S-8	SLO-1	CMOS Inverter circuit operation	Scaling of MOS circuits	Comparators, Zero/One Detectors	Parameters influencing low power design	Layout Design for Improved Testability
	SLO-2	CMOS and complex CMOS logic circuit	Figure(s) of Merit (FoM) for scaling, Scaling factors for device parameters	Example of problems	Dynamic Power Consumption, Leakage power dissipation	Bridge Fault Model, Bridge Fault Simulation, Test Generation for Bridge Fault
S-9	SLO-1	Performance of the BiCMOS Inverter	Implications of scaling on design of Scaling	High-Density Memory Elements	Low Power Strategies: Sources of Power Dissipation	Observability and controllability
	SLO-2	Power Consumption, Designing BiCMOS Digital Gates	Limitations of Scaling	Bitline IO Circuit, SRAM	Degrees of Freedom, Supply Voltage Scaling, Ultra Low Power System Design	False Path problem

Learning Resources	1. K. Eshraghian Eshraghian, D. A.Pucknell, Essentials of VLSI Circuits and Systems,, Edition II PHI, 2009. 2. Modern VLSI Design : lp - Based Design 4th Edition, 2015, PHI. 3. Basic VLSI Design, 2009, reprint 2017, PHI	3. N.H.E Weste, K.Eshraghian,Principals of CMOS VLSI Design, 2nd ed., Addison Wesley, 1993. 4. Neil Weste,David Harris,CMOS VLSI Design: A Circuits and Systems Perspective ,4th Edition, 2011 4. http://nptel.ac.in/courses/117106092/#
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1 Mr.V.Pangayselvan, Aricent Technologies, Senior analyst, Chennai, pangaya.v@aricent.com	1. Dr. Shady Abdel Aleem, Higher Institute of Engineering, Mathematical, Physical and Engineering Sciences Department, Cairo, Egypt. engyshady@ieee.org	1. Dr. M.Jagabar Sathik, SRMIST
2. Mr. M.Sathisk Kumar, Senior Manager and Programme Specialist, ORCALE DB, Bangalore	2. Dr. B.Moorthy, Associate professor, NIT Trichy	2. Dr.A.Rathinam, SRMIST

Course Code	18EEE328T	Course Name	DATA STRUCTURES		Course Category	E	Professional Elective					L	T	P	C								
							3	0	0	3													
Pre-requisite Courses	Nil		Co-requisite Courses	Nil		Progressive Courses	Nil																
Course Offering Department		Electrical and Electronics Engineering			Data Book / Codes/Standards		Nil																
Course Learning Rationale (CLR):		The purpose of learning this course is to:				Learning			Program Learning Outcomes (PLO)														
CLR-1 :		Illustrate the basic concepts of data structures, Search techniques and their algorithms				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :		Educate with the basic knowledge of stacks and queues				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :		Discuss the concepts of linked lists																					
CLR-4 :		Impart knowledge on trees and its algorithm																					
CLR-5 :		Outline the basics of sorting and graph																					
CLR-6 :		Create an overall knowledge of different data structure algorithms																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:				2	80	75	H	H	M	-	-	-	-	-	-	-	-	-	H	M	-
CLO-1 :		Implement and analyze the different searching algorithms				2	80	75	H	H	M	-	-	-	-	-	-	-	-	-	M	M	-
CLO-2 :		Employ different stacks and queues algorithms				2	80	75	H	H	M	-	-	-	-	-	-	-	-	-	M	M	-
CLO-3 :		Analyze the different linked list algorithms				2	80	75	H	H	M	-	-	-	-	-	-	-	-	-	H	M	-
CLO-4 :		Determine the time and computation complexity in Binary tree and AVL tree				2	80	75	H	M	M	-	-	-	-	-	-	-	-	-	H	H	-
CLO-5 :		Develop an algorithm for graph and compare the performance of sorting methods				2	80	75	H	H	M	-	-	-	-	-	-	-	-	-	H	M	-
CLO-6 :		Develop application using data structure algorithms				2	80	75	H	H	M	-	-	-	-	-	-	-	-	-	H	M	-
Duration (hour)		9		9		9		9		9		9											
S-1	SLO-1	Basic Terminologies		Array implementation of Stack ADT		Singly linked lists		Basic Tree Terminologies		Basic Terminologies of Graph													
	SLO-2	Elementary Data Organizations		Stack ADT operations with example		Singly linked lists - Representation in memory		Basic Tree Operations		Representations of Graph													
S-2	SLO-1	Abstract data type		Application of Stack: Infix to Postfix Conversion		Algorithm of Traversing operation		Binary Tree operations		Graph traversal algorithms - breadth first search with example													
	SLO-2	Abstract data type Example		Infix to Postfix Conversion Algorithm		Algorithm of Searching operation		Algorithm of Binary Tree operations		Graph traversal algorithms - depth first search with example													
S-3	SLO-1	Data Structure Operations		Application of Stack: Evaluation of postfix expression		Insertion into linked list		Binary Search Tree - operations - insertion		Prims Minimum spanning tree algorithm													
	SLO-2	Types of Data Structure Operations		Evaluation of postfix expression Algorithm		Algorithm of Insertion into linked list		Algorithm of Binary Search Tree - insertion		Prims Minimum spanning tree algorithm - Example													
S-4	SLO-1	Analysis of an Algorithm		Application of Stack: Balancing symbols		Deletion from linked list		Binary Search Tree - operations - deletion		Kruskal's Minimum spanning tree algorithm													
	SLO-2	Applications: Analysis of an Algorithm		Balancing symbols Algorithm with example		Algorithm of Deletion from linked list		Algorithm of Binary Search Tree - deletion		Kruskal's Minimum spanning tree algorithm – Example													
S-5	SLO-1	Asymptotic Notations		Queue ADT- OperationsIntroduction		Linked representation of Stack		Binary tree traversal		Bubble sort													
	SLO-2	Properties of Asymptotic Notations		Queue ADT- Operations Examples		Linked representation of Stack - Example		Binary tree traversal - inorder, preorder, postorder		Bubble sort – Example													
S-6	SLO-1	Time-Space trade off		Simple Queue- Operations		Linked representation of Queue		Example of Binary tree traversal		Insertion Sort algorithm													

	SLO-2	Time-Space trade off Example	Algorithm of Simple Queue – Operations with examples	Linked representation of Queue - Example	Applications of Binary Trees	Insertion Sort algorithm – Example
S-7	SLO-1	Linear Search Technique	Circular Queue - Operations	Doubly linked list	AVL Tree- operations: Rotations	Selection Sort algorithm
	SLO-2	Linear Search Technique Example	Algorithm of Circular Queue - Operations	Operations on Doubly linked list	AVL Tree- operations: Rotations - Example	Selection Sort algorithm – Example
S-8	SLO-1	Complexity analysis of Linear Search Technique	Example of Circular Queue - Operations	Example of Doubly linked list	AVL Tree- operations: Insertion	Merge sort algorithm
	SLO-2	Example of Linear Search Technique	Priority Queue - Operations	Circular Linked List	AVL Tree- operations: Insertion - Example	Merge sort algorithm – Example
S-9	SLO-1	Binary Search Technique	Algorithm of Priority Queue - Operations	Circular Linked List algorithms	AVL Tree- operations: Deletion	Quick sort algorithm
	SLO-2	Complexity analysis of Binary Search Technique	Example of Priority Queue - Operations	Circular Linked List example	AVL Tree- operations: Deletion – Example	Quick sort algorithm – Example

Learning Resources	1. Aaron M.Tenenbaum, Yedidyah Langsam and Moshe J.Augenstein, <i>Data Structures Using C</i> , Seventh Edition, 2009, Pearson Education in South Asia. 2. G A Vijayalakshmi Pai, <i>Data Structures and Algorithms - Concepts, Techniques and Applications</i> , Tata McGraw-Hill Publishing Company Limited, 2008.	3. https://www.youtube.com/watch?v=coxWfcz_slk&list=PLrjktQl3jnm8ikiQlelHrMYCaBfkBkFYR&index=1 4. Mark Allen Weiss, <i>Data Structures and Algorithm Analysis in C++</i> , Third Edition, 2009, Pearson Education in South Asia.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1.Mr.Balachandrasekar.K, CTS, dyaksha@gmail.com	1.Dr. B. K. Panigrahi, IIT Delhi, bkpanigrahi@ee.iitd.ac.in	1. Dr.R.Annie Uthra, SRMIST
2.Mr. Tripathi patro, visam pvt ltd, btp@visom.co.in	2.Dr. M.P.Selvan, NIT Trichy, selvanmp@nitt.edu	2. Mr.P.Kanakaraj, SRMIST

Course Code	18EEE329T	Course Name	COMPUTER SYSTEM ARCHITECTURE	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Acquire knowledge about the modern computer organization technologies	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Educate the students' on machine instructions	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Explain the modern Acorn RISC Machine (ARM) Instruction set																		
CLR-4 :	Impart knowledge about the interfacing devices																		
CLR-5 :	Identify potential of memory unit																		
CLR-6 :	Educate the students' on advances in computer technology																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Understand the concepts of modern computer organization	2	75	75	H	H	M	L	-	-	-	-	-	-	-	-	M	M	-
CLO-2 :	Analyze the machine instruction concept and operation	2	75	75	H	H	M	L	-	-	-	-	-	-	-	-	M	M	-
CLO-3 :	Examine and solve issues related to Acorn RISC Machine (ARM) Instruction set	2	75	75	H	H	M	L	-	-	-	-	-	-	-	-	M	M	-
CLO-4 :	Describe the operation of input and output units	2	75	75	H	H	M	L	-	-	-	-	-	-	-	-	M	M	-
CLO-5 :	Examine and solve issues related to memory mapping techniques	2	75	75	M	H	M	L	-	-	-	-	-	-	-	-	M	M	-
CLO-6 :	Acquire knowledge on the recent trends in computer technologies	2	75	75	H	H	M	L	-	-	-	-	-	-	-	-	M	M	-

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Computer types	Numbers ,arithmetic operations and characters	Memory access and data transfer	Accessing I/O devices	Semiconductor RAM memories
	SLO-2 functional units of computer architecture	Memory locations	Acorn RISC Machine(ARM)- Registers	Interrupts	Read only memories
S-2	SLO-1 Operational concepts	Memory addresses	Arithmetic and logic instructions	ARM Interrupt structure	Speed size and cost
	SLO-2 bus structures	Addressing mode	Branch Instructions	Direct memory access	Mapping techniques
S-3	SLO-1 Software Performance	Instructions and sequencing	Setting condition codes	Buses-Synchronous bus	Hit rate and miss penalty
	SLO-2 Performance and metrics	Assembly language	Loop program	Asynchronous bus	Caches on the processor chip
S-4	SLO-1 compiler	Basic input/output operations	Pseudo instructions	Interface circuits-Serial port	Virtual memories
	SLO-2 Uniprocessors to multiprocessors	Subroutines	Byte sorting	Parallel port	Memory management requirements
S-5	SLO-1 operations and operands	Logic instructions	Linked list insertion subroutines	Standard I/O interfaces	Second storage system
	SLO-2 representing instructions	Branch Instructions	Linked list deletion subroutines	PCI buses	Memory hierarchy
S-6	SLO-1 Logical operations	Execution of a complete instruction	Data hazards	Universal serial bus	Memory technologies
	SLO-2 control operations	Addition algorithm	Instruction hazards	Overview of parallelism	Cache basics
S-7	SLO-1 Multiple bus organization	Subtraction algorithm	Influence on instruction sets	Instruction-level-parallelism	Measuring cache performance
	SLO-2 Hardwired control	Multiplication algorithm	Data path and control considerations	Parallel processing challenges	Improving cache performance
S-8	SLO-1 Micro programmed control	Division algorithm	Performance considerations of pipelining	Flynn's classification	Virtual memory
	SLO-2 Multi computers	Floating Point operations	Overview of data path control	Hardware multithreading	Translation Lookaside Buffer
S-9	SLO-1 Multiprocessors	Sub-word parallelism	Pipelined datapath and control	Analysis of parallelism methods	Direct Memory Access
	SLO-2 Nano programming	Write-through and Write-back cache write method	Exception handling	Multi-core computing in parallelism	Interrupts

Learning Resources	1. M. Morris R. Mano Computer System Architecture, Pearson publishers, 3rd Edition, 2007. 2. Carl hamachar Computer Architecture and Organization, Tata McGraw hill, 5 th edition, 2015.	3. David A. Patterson Computer Organization and Design MIPS Edition: The Hardware/Software Interface (The Morgan Kaufmann Series in Computer Architecture and Design) Morgan Kaufmann; 5 edition 2013. 4. https://ocw.mit.edu/courses/electrical-engineering-and-computer-science
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1.Mr.Balachandrasekar.K, CTS, dyaksha@gmail.com	1.Dr.S.K.Patnaik, CEG, Anna University, skpatnaik@annauniv.edu	1.Mr.S.George Fernandez, SRMIST
2.Mr.Ravikumar A R, PayPal, ravikumar.venkataramani@gmail.com	2.Dr. S. Ramareddy, Jerusalem College of Engineering, srr.victory@gmail.com	2.Ms.R.Rajarajeswari, SRMIST

Course Code	18EEE330T	Course Name	COMPUTER NETWORKING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)																			
CLR-1 :	Understand the protocols of modern networking technologies		Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2 :	Educate the students' on data format& data transfer at high speed Communication																								
CLR-3 :	Explain the modern transport layer technologies																								
CLR-4 :	Identify advances in technology that may solve the actual limitations with existing networks																								
CLR-5 :	Impart knowledge about modern technologies used in application layer																								
CLR-6 :	Educate the students on network security																								
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																							
CLO-1 :	Acquire knowledge about the protocols of modern networking technologies		2	75	75	H	H	M	L	-	-	-	-	M	-	-	-	-	-	H	M	M			
CLO-2 :	Analyze the physical properties and performance characteristics of Communication media		2	75	75	H	H	M	L	-	-	-	-	M	-	-	-	-	-	H	M	M			
CLO-3 :	Examine and solve issues related to congestion management		2	75	75	H	H	M	L	-	-	-	-	M	-	-	-	-	-	H	H	M			
CLO-4 :	Describe the importance of reliability and quality of service, for error recovery, traffic differentiation and prioritization.		2	75	75	H	H	M	L	-	-	-	-	M	-	-	-	-	-	H	H	M			
CLO-5 :	Develop an appreciation of the theory of common application layer.		2	75	75	H	H	M	L	-	-	-	-	M	-	-	-	-	-	H	M	M			
CLO-6 :	Acquire knowledge about the network security system.		2	75	75	H	H	M	L	-	-	-	-	M	-	-	-	-	-	H	M	M			

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Historical perspective of computer networking	Theoretical basis for data Communication	Overview of Transport layer	Causes of errors on data transmission	Traditional applications
	SLO-2	Theoretical models of network architecture	Guided transmission media	Elements of transport protocol	Impact of errors on data transmission	Electronic Mail
S-2	SLO-1	Practical models of network architecture	Bounded type transmission mode	Functions of transport layer	Single bit errors	Simple Mail Transfer Protocol
	SLO-2	Introduction to ISO	Unbounded type transmission mode	Addressing modes	Burst errors	POP3
S-3	SLO-1	ISO OSI Seven-layer model	Magnetic Media	Service point addressing	Need for error detection	Web Services
	SLO-2	TCP protocol	Issues with magnetic media	Segmentation process	error detection strategies	Http
S-4	SLO-1	IP protocol	Need for cable transmission modeS	Reassembling process	Overview of error correction	Multimedia
	SLO-2	Comparison of OSI and TCP/IP reference models	Twisted Pair cable	User datagram protocol	error correction strategies	Domain Name System
S-5	SLO-1	Synchronous transfer mode protocol	Baseband Coaxial Cable	Reliable byte stream	Parity Checks	Simple Network Management Protocol
	SLO-2	Asynchronous transfer mode protocol	Broadband Coaxial Cable	Connection management	block sum Check	File Access and Management
S-6	SLO-1	Frame relay protocol	narrowband ISDN	Causes of Congestion	Sliding window protocol	Overview of Network security
	SLO-2	Frame Relay and the OSI Reference Model	broadband ISDN	Retransmission	Elementary data link protocol	Cryptography
S-7	SLO-1	Digital subscriber line technology	Microwave transmission	Congestion Control	Protocol identification	Symmetric key algorithm
	SLO-2	Variation in DSL technology	Electromagnetic Spectrum	Flow control	Protocol verification	Public key algorithm
S-8	SLO-1	2G technology	Radio transmission	Performance issues	Forward error control	Digital signature
	SLO-2	3G,4G technology	Fiber optics	Quality of service	Backward error control	Management of public keys
S-9	SLO-1	Wi-Fi technology	Microwave Transmission	Application requirements	Statistical analysis of the effectiveness of error detection code	Communication security
	SLO-2	Wi-MAX technology	Comparison of transmission medium	Design issues with transport layer	Statistical analysis of the effectiveness of error correction code	Social issues

Learning Resources	1. Andrew S. Tanenbaum, <i>Computer Networks</i> , 4 th edition, Prentice Hall, 2003.	3. James F. Kurose, <i>Computer networking : a top-down approach</i> , 6 th ed. Pearson publishers.
	2. William Stallings, <i>Data and Computer Communications</i> , 5 th edition, PHI, 2005.	4. https://ocw.mit.edu/courses/electrical-engineering-and-computer-science

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.Ravikumar A R, PayPal,ravikumar.venkataramani@gmail.com	1. Dr. A. Venkadesan, NIT Puducherry, venkadesan@nitpy.ac.in	1. Mr.George Fernandez.S, SRMIST
2. Mr.Balachandrasekar.K,CTS,dyaksha@gmail.com	2.Dr Subhransu Sekhar Dash, Government College of Engineering, Keonjhar, Subhransudash_fee@gcekjr.ac.in	2. Dr.J.Divyanavamani, SRMIST

Course Code	18EEE331T	Course Name	INTERNET OF THINGS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning		
CLR-1 :	Outline the basic architectural overview of IoT .				1	2	3
CLR-2 :	Enable the students to differentiate between IoT and M2M.				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)
CLR-3 :	Enrich the knowledge about IoT platforms and design methodology						
CLR-4 :	Examine the various hardware platforms of IoT						
CLR-5 :	Acquire the concept of IoT in application sectors.						
CLR-6 :	Enable the students to acquire the basic knowledge of IoT architecture, various platforms and applications.						
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:					
CLO-1 :	Understand the issues and design challenges in IoT architecture				1	75	75
CLO-2 :	Gain knowledge on M2M and IoT				1	75	75
CLO-3 :	Interpret about various network topologies and design methodologies				1	75	75
CLO-4 :	Analyze on hardware platforms relevant to IoT.				2	75	75
CLO-5 :	Apply knowledge of IoT in various applications.				2	75	75
CLO-6 :	Understand IoT platforms, interfacing and applications.				2	75	75

Program Learning Outcomes (PLO)														
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
H	-	-	-	-	H	-	-	-	-	-	-	H	M	H
H	-	-	-	M	H	-	-	-	-	-	-	M	M	M
H	-	-	-	M	H	-	M	-	-	-	-	H	M	M
H	-	-	-	M	H	-	-	-	-	-	-	H	H	M
H	-	-	-	M	H	-	-	H	-	-	H	H	M	M
H	-	-	-	M	H	-	M	H	-	-	H	H	M	M

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Definitions of IoT	M2M towards IoT - the global context,	IoT platforms	IoT Physical Devices & Endpoints	Case Studies- IoT Design and Cloud incorporation
	SLO-2	Functional requirements of IoT.	Game changers	IoT platforms design methodology	Basic building blocks of an IoT Device	Introduction to IoT Design
S-2	SLO-1	Building an IoT architecture- SOA based architecture	M2M to IoT - building an architecture	IoT design methodology - Purpose & Requirements Specification, Process Specification	Exemplary Device: Raspberry Pi	Home Automation – smart lighting, smart appliances
	SLO-2	API oriented architecture	Main design principles and needed capabilities	Domain Model Specification, Information Model Specification	Linux on Raspberry Pi	Intrusion detection, Smoke /Gas detectors
S-3	SLO-1	Physical things of IoT- Things in IoT,	IoT architecture outline	Service Specifications, IoT Level Specification, Functional View Specification	Raspberry Pi Interfaces - serial	Cities –Smart Parking, Smart Lighting, Smart Roads
	SLO-2	IoT Protocols	Standard considerations	Operational View Specification, Device & Component, Application development.	Raspberry Pi Interfaces - SPI, I2C	Structural health Monitoring, Surveillance, Emergency Response
S-4	SLO-1	Logical Design of IoT - IoT functional Blocks,	Introduction to M2M	IoT Design methodology-case study on IoT system for Weather Monitoring	Programming Raspberry Pi with Python – controlling LED with Raspberry pi	Environment - Weather Monitoring, Air Pollution Monitoring
	SLO-2	Communication model, Communication APIs	Difference between IOT and M2M	Case study on IOT system for Weather Monitoring	Programming Raspberry Pi with Python – interfacing an LED and switch with Raspberry pi	Noise Pollution Monitoring, Forest Fire Detection, River Floods Detections
S-5	SLO-1	IoT enabling technologies- wireless sensor networks	Software defined networking (SDN)	Python data types	Programming Raspberry Pi with Python- interfacing a light sensor with Raspberry Pi	Energy - Smart grids , Renewable Energy Systems, Prognostics
	SLO-2	Cloud Computing	Network function visualization (NFV) for IOT.	Python data structures.	Other IoT Devices- pcDuino, BeagleBone Black	Retail - Inventory Management, Smart Payment, Smart Vending Machines

S-6	SLO-1	IoT enabling technologies - Embedded Systems,	Needs for IoT system management	Logical Design using Python- control flow	Other IoT Devices - Cubieboard	Smart Vending Machines
	SLO-2	Big data analytics	Simple Network Management Protocols (SNMP)	Logical Design using Python - functions	Controlling LED with Raspberry Pi	Logistics - Route Generation and scheduling, Fleet Tracking
S-7	SLO-1	IoT enabling technologies - Communication protocols for IoT,	Limitations of SNMP	Logical Design using Python - modules	Controlling LED with Myrio	Shipment Monitoring, Remote Vehicle Diagnostics
	SLO-2	Embedded systems	Network operator requirements	Logical Design using Python - packages	Interfacing an LED and Switch with Raspberry Pi	Agriculture - Smart irrigation, Green House Control
S-8	SLO-1	IoT levels and deployment templates- level 1, level 2, level 3	Network configuration protocol (NETCONF) layer	Logical Design using Python - file handling,	Interfacing an LED and Switch with Myrio	Industry – Machine Diagnosis and prognosis
	SLO-2	IoT levels and deployment templates- level 4, level 5, level 6	YANG data modelling language.	Logical Design using Python - date/time operations, classes	Interfacing a Light Sensor (LDR) with Raspberry Pi Other IoT Devices - BeagleBone Black,	Indoor Air Quality Monitoring
S-9	SLO-1	IoT data management and Analytics- IoT and the cloud	IOT system management with NETCONF - YANG	Python Packages of Interest for IoT - JSON,XML	Interfacing a temperature and humidity sensors with Raspberry Pi Other IoT Devices -BeagleBone Black	Health and lifestyle - Health and fitness Monitoring
	SLO-2	IoT data management and Analytics- Real time analytics in IoT and Fog computing	NETOPEER	Python Packages of Interest for IoT - XML	Interfacing a temperature and humidity sensors with Raspberry Pi Other IoT Devices -BeagleBone Black	Wearable Electronics

Learning Resources	<ol style="list-style-type: none"> 1. Arshdeep Bahga, Vijay Madiseti, <i>Internet of Things – A hands-on approach</i>, Universities Press, 2015 2. Jan Holler, Vlasios Tsiatsis, Catherine Mulligan, Stamatis Karmouskos, David Boyle, <i>From Machine-to-Machine to the Internet of Things: Introduction to a New Age of Intelligence</i>, Elsevier, 1st Edition ,2014 3. Rajkumar Buyya , James Broberg, Andrzej Goscinski, <i>Cloud Computing Principles and Paradigms</i>, Willey, 1st Edition 2014. 4. Honbo Zhou, <i>The Internet of Things in the Cloud: A Middleware Perspective</i>, CRC Press 2013. 5. Soyata, Tolga, <i>Enabling Real-Time Mobile Cloud Computing through Emerging Technologies</i>, IGI Global, 2015 6. https://www.cse.wustl.edu/~jain/cse570-15/ftp/iot_prot/index.html
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

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1.Mr.Muralikrishna, National Instruments, emkkrishnan@gmail.com	1. Dr.D.Devaraj, Dean (Academics), Kalasalingam Academy of Research and Education, deva230@yahoo.com	1. Mrs.C.Nithya, SRMIST
2. Mr.Ravikumar A R, PayPal, ravikumar.venkataramani@gmail.com	2. Dr.B.ChittiBabu, IIITD, Kanchipuram, chittibabu@gmail.com	2. Dr.J.Preetha Roselyn, SRMIST

Course Code	18EEE332T	Course Name	PRINCIPLES OF OBJECT ORIENTED PROGRAMMING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			
CLR-1 :	Explain the basics of OOPS				Level of Thinking (Bloom)	1	2	3
CLR-2 :	Demonstrate and develop the concepts of C++							
CLR-3 :	Illustrate the importance of the advancements in C++							
CLR-4 :	Explain the basics of JAVA							
CLR-5 :	Elaborate the advanced features of JAVA							
CLR-6 :	Discover the basics of C++ and JAVA							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:						
CLO-1 :	Identify the basic concepts of OOPS				2	75	75	
CLO-2 :	Classify and utilize the concepts of C++				3	75	75	
CLO-3 :	Develop potential applications from the advancements in C++				3	75	75	
CLO-4 :	Discover the basics of JAVA				3	75	75	
CLO-5 :	Apply and analyze the advanced features of JAVA				3	75	75	
CLO-6 :	Design and develop applications based on C++ and JAVA				3	75	75	

Program Learning Outcomes (PLO)														
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
H	-	-	-	-	-	-	-	-	-	-	-	M	M	-
H	M	M	L	M	-	-	-	-	-	-	-	M	M	-
H	H	H	M	M	-	-	-	-	-	-	-	M	M	-
H	L	L	L	M	-	-	-	-	-	-	-	M	M	-
H	H	H	H	M	-	-	-	-	-	-	-	M	M	-
H	H	M	M	M	-	-	-	-	-	-	-	M	M	-

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Need of Object-Oriented Programming	Introduction to Classes	Pointers	Java platform features-Data types, Key words, Scoping rules
	SLO-2	Characteristics of Object-Oriented Languages	Introduction to Objects	Pointers with arrays and functions	Automatic Type Conversion, Type Casting and Arrays
S-2	SLO-1	Introduction to the principles of object-oriented programming	Class fundamentals	Virtual Functions	Java platform features
	SLO-2	Data Types, Variables	Structure of class	Friend Functions	Data types, Key words, Scoping rules
S-3	SLO-1	Constants - Type Conversion	Declaring objects	Programs using pointers and arrays	Operators Precedence
	SLO-2	Basic Program Construction	Simple object creation	Programs using functions	Associativity, Expression
S-4	SLO-1	Operators	Objects and messages	Introduction to STL: Containers, Algorithms	Enhanced for loop, switch statements
	SLO-2	Constants, Strings, Expressions and Data types	Constructors and its types	Introduction to STL: Iterators	Handling Strings
S-5	SLO-1	Library Functions	Destructors	Potential problems with STL: Containers, Algorithms	Declaring objects
	SLO-2	Loops and Decisions	Passing arguments to Functions	Potential problems with STL: Iterators	Assigning object reference variable
S-6	SLO-1	Structures	Passing Objects as Function arguments	Encapsulation	Methods & Method Signatures
	SLO-2	Functions : Simple Functions	Returning values from Functions	Implementation of Encapsulation	Method retuning Values, Method with parameters
S-7	SLO-1	Passing arguments, Returning values	Returning Objects from Functions	Polymorphism	Variable arguments in Java
	SLO-2	Reference Arguments	Operator Overloading	Operator and method overloading	I/O Basics: Byte stream& Character Stream

S-8	SLO-1	Recursion, Inline Functions	Inheritance: Basics	Event handling	Getting user input: Reading console input & Writing console output,	Introduction to Threads
	SLO-2	Default Arguments	Inheritance: Method overriding from operator overriding	Errors and Exception handling	Reading and Writing files-new file system	Multithreaded programming
S-9	SLO-1	Storage Classes	Potential programming using functions, constructors and destructors	Potential programs using encapsulation, polymorphism	Constructors: Default Constructor,	Potential programs using threads
	SLO-2	Arrays – Strings	Potential programming using overloading and inheritance	Potential programs using exception handling	Parameterized constructor	Potential programs using multithreads

Learning Resources	1. D Deitel, C++ How to Program, 6th edition, PHI publication, 2008. 2. R. Subburaj, Object Oriented Programming With C++ , Vikas Publishing House, New Delhi, Revised Edition, 2013 3. Bjarne Stroustrup ,The C++ Programming Language, 4th Edition, Addison Wesley, 2015	4. Herbert Schildt, The Complete Reference (Fully updated for jdk7), Oracle press Ninth Edition,2014. 5. Deitel & Deitel, Java How to Program, Prentice Hall, 10th Edition, 2016. 6. Herbert Schildt ,Java: A Beginner's Guide, Sixth Edition, Oracle Press, 2014. 7. https://docs.oracle.com/javase/tutorial
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1.Mr.Balachandrasekar.K,CTS,dyaksha@gmail.com	1.Dr.P.Ganesh Kumar, Anna University, ganesh23508@gmail.com	1.Dr. U. Sowmmiya, SRMIST
2.Mr.Ravikumar A R, PayPal,ravikumar.venkataramani@gmail.com	2.Dr.N.Sripriya, SSN College of Engineering, sripriyan@ssn.edu.in	2.Dr. G. Niranjana, SRMIST

Course Code	18EEE422T	Course Name	MODERN OPTIMIZATION TECHNIQUE				Course Category	E	Professional Elective			L	T	P	C								
												3	0	0	3								
Pre-requisite Courses	Nil		Co-requisite Courses	Nil				Progressive Courses	Nil														
Course Offering Department		Electrical & Electronics Engineering				Data Book / Codes/Standards			Nil														
Course Learning Rationale (CLR):		The purpose of learning this course is to:				Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Introduce and classify different conventional optimization techniques.				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLR-2 :	Understand the fundamentals of genetic algorithm and to apply appropriate algorithm for Engineering optimization problems				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3	
CLR-3 :	Outline the concept of particle swarm optimization and its hybrid approach to Engineering applications																						
CLR-4 :	Interpret other modern optimization algorithms for engineering applications																						
CLR-5 :	Extend optimization techniques to multi objective optimization																						
CLR-6 :	Introduce the concept of optimization design for Engineering problems																						
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																					
CLO-1 :	Categorize optimization problems and its techniques based on constraints and variables				1	75	75	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
CLO-2 :	Apply Genetic algorithm for various Engineering application				2	75	75	H	H	M	M	-	-	-	-	-	-	-	-	H	H	-	
CLO-3 :	Utilize Particle swarm optimization to Engineering applications				3	75	75	H	M	M	M	-	-	-	-	-	-	-	-	H	H	-	
CLO-4 :	Gain knowledge about other modern optimization algorithms				3	75	75	H	H	H	H	-	-	-	-	-	-	-	-	H	H	-	
CLO-5 :	Formulate multi objective optimization algorithm for various applications				3	75	75	H	H	H	H	-	-	-	-	-	-	-	-	H	H	-	
CLO-6 :	Apply optimization techniques in modelling Engineering problems				3	75	75	H	H	H	H	-	-	-	-	-	-	-	-	H	H	-	
Duration (hour)		9		9		9		9		9		9		9		9		9		9		9	
S-1	SLO-1	Introduction to optimization		Introduction – Genetic Algorithm		Particle Swarm Optimization		Bacterial foraging- Chemotaxis, Swarming		Multiobjective optimization													
	SLO-2	Classification of optimization problem		Encoding – Methods for GA		Fundamental principle		Operation of Bacterial foraging		General form of MOOP													
S-2	SLO-1	Single variable optimization – optimalityconditions		Fitness function		Velocity updating in PSO		Bees colony algorithm- Behavior of Honey bee swarm		Pareto optimality													
	SLO-2	Single variable (unconstrained optimization) – Exhaustive search method		Maximization & Minimization		Algorithm for PSO		Algorithm for Bee colony optimization		Dominance test													
S-3	SLO-1	Successive quadratic estimation method		Genetic operators – Crossover		PSO – Parameter Selection		Differential evolution-Initialization, Mutation		Classical Methods – Weighted sum method, ε-constraint method													
	SLO-2	Newton method		Single point crossover, Two-point crossover		Pseudocode		Recombination, Selection		Weighted metric methods, Benson method.													
S-4	SLO-1	Multi variable optimization – optimality conditions		Uniform Crossover, Arithmetic Crossover		Implementation & Convergence issues in PSO		Ant colony optimization- Introduction		Multi objectiveGA													
	SLO-2	Multi variable optimization (unconstrained) – Simplex search method		Mutation		Advanced operators of PSO		Algorithm for Ant colony optimization		Fitnessassignment													
S-5	SLO-1	Cauchy's method		Parent SelectionMethods		Meta-Optimization-Behavioral parameters		Simulated Annealing optimization- Components and control parameters		Sharing function													
	SLO-2	Steepest Descent Method		Rank selection, Roulette wheel selection, Stochastic universal selection, Tournament selection		Algorithm for Meta Optimization		Algorithm for Simulated Annealing		Convergence criterion													

S-6	SLO-1	Multivariable optimization (Constrained) Kuhn – Tucker Conditions	Issues in GA implementation	Application of PSO	Firefly optimization-Working Principle	NSGA-II-Fitness assignment
	SLO-2	Transformation Method –Method of Multipliers	Applications of GA –Filter design	Harmonics Elimination	Algorithm for Firefly optimization	Sharing Function
S-7	SLO-1	Linearized search Technique	Automatic Load Frequency Control (ALFC)	Applications of PSO	Flower Pollination optimization-Introduction	Dynamic neighborhood PSO-Introduction
	SLO-2	Frank Wolfe method	Automatic Voltage Regulation (AVR)	Maximum Power Point Tracking	Algorithm for Flower pollination	Algorithm for Dynamic neighborhood PSO
S-8	SLO-1	Non-Linearized Search Technique	Evolutionary Algorithm	Application of PSO	Grey Wolfe optimization-Introduction	Vector evaluated PSO
	SLO-2	Reduced gradient method	Evolutionary Programming	Reactive power control using PSO	Algorithm for Grey Wolfe optimization	Applications – Economic load Dispatch
S-9	SLO-1	Quadratic programming-Objective Function	Evolutionary Strategy-Non-Recombinative strategy	Hybrid Algorithm of GA and PSO	Comparison of various algorithms	Unit Commitment,
	SLO-2	Algorithm	Recombinative strategy	GA and PSO operators	Benchmark functions	Robot Path Planning

Learning Resources	1. Singiresu Rao S, Engineering Optimization–Theory and Practice by John Wiley & Sons, Inc., New Jersey, 2009.	4. Jizhong Zhou, Optimization of Power System Operation, IEEE Press, Second Edition, 2015.
	2. Kalyanmoy Deb, Multi-objective Optimization using Evolutionary Algorithms, Wiley India Private Limited, 2010	5. Xin - She Yang, Nature Inspired Optimization algorithms, Elsevier, 2014.
	3. Kalyanmoy Deb, Optimization of Engineering Design, Prentice Hall of India, second Edition, 2012.	6. Chee Peng Lim, Lakhmi C. Jain, Satchidananda Dehuri, Innovations in Swarm Intelligence, Springer, Berlin, Heidelberg, 2009.
		7. https://engineering.purdue.edu/~sudhoff/ee630/Lecture09.pdf

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1.Dr.S.Paramasivam, Danfoss, Industries Pvt Ltd, paramsathya@yahoo.com	1.Dr. R.Subha, Associate Prof. Sir MVIT, subha.mvit@gmail.com	1.Mrs.Uthra.R, SRMIST
2.Mr.Sudharsan, L&T, sudharsand@Intecc.com	2.Dr. B. K. Panigrahi, IIT Delhi, bkpanigrahi@ee.iitd.ac.in	2.Dr.D.Suchitra, SRMIST

Course Code	18EEE423T	Course Name	NEURO FUZZY AND GENETICS PROGRAMMING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:	
CLR-1 :	Acquire knowledge on neural network.		
CLR-2 :	Understand the neural network algorithms for pattern classification and regression problems		
CLR-3 :	Introduce the basics of fuzzy logic and its reasoning.		
CLR-4 :	Study the architecture of Fuzzy logic controller and neuro-fuzzy based systems.		
CLR-5 :	Develop the knowledge on genetic algorithm for optimization problems		
CLR-6 :	Demonstrate the application of neural network, fuzzy logic and Genetic algorithm in real world		
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:	
CLO-1 :	Illustrate the working of various learning algorithms of Neural network.		
CLO-2 :	Develop and analyze neural networks for pattern classification and pattern association.		
CLO-3 :	Apply fuzzy logic and reasoning to handle uncertainty and solve engineering problems		
CLO-4 :	Develop the process of approximate reasoning using Fuzzy logic controller and Neuro-Fuzzy Modeling.		
CLO-5 :	Formulate a mathematical background to carry out optimization using genetic algorithm.		
CLO-6 :	Design and perform experiments on real life problems using Neural network, Fuzzy logic and Genetic algorithm		

Learning		
1	2	3
Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)

Program Learning Outcomes (PLO)														
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
H	H	M	-	-	-	-	-	-	-	-	-	M	M	M
H	H	M	L	H	-	-	-	-	-	-	-	M	M	-
H	H	M	-	-	-	-	-	-	-	-	-	M	M	-
H	H	M	L	H	-	-	-	-	-	-	-	M	M	-
H	H	M	L	H	-	-	-	L	L	-	-	M	M	-
H	H	M	L	H	-	-	-	L	L	-	-	M	M	-

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Biological Neurons and Their Artificial Models	Pattern Association-Hebb rule	Introduction to Fuzzy Logic, Uncertainty based Information	Introduction to Fuzzy Reasoning	Difference between Traditional optimization Algorithms and genetic algorithm
	SLO-2	Models of Artificial Neural Networks, Architectures	Delta Rule for pattern association	Chances / randomness versus Fuzziness	Fuzzy rule generation. Aggregation Operations	The basic operation of genetic algorithm
S-2	SLO-1	Setting Weights, Activation functions, Learning Processes	Hetero associative memories - Architecture-Algorithm	Classical/crisp set	Fuzzy Logic controller- Basic block	Pseudo code of GA
	SLO-2	Learning Paradigms-Supervised, Unsupervised and reinforcement Learning	Example Problem-Application	Properties and operations of classical set	Knowledge Base-Rule base-Inference system-Importance	Schema theorem
S-3	SLO-1	McCulloch-Pitt Neuron	Auto associative memories -Architecture-Algorithm	Fuzzy set- Representation of fuzzy sets	Fuzzification	Encoding operation
	SLO-2	Linear Separability	Example Problem-Application-Storage Capacity	Properties and Operations of Fuzzy Sets	Assignment of membership functions	Binary, Octal, Hexadecimal , Permutation and Tree encoding
S-4	SLO-1	ANN training Algorithms-Training rules	Iterative Associative Net- Discrete Hopfield Network -Energy Function	Measure of Fuzziness and Inaccuracy of fuzzy set	Defuzzification Methods-Weighted Average method	Importance of Selection and Reproduction operators of GA
	SLO-2	Hebb rule-Algorithm -Application	Continuous Hopfield Network-Energy Function	Cartesian Product- Fuzzy Relations-Composition of fuzzy Relations	Centroid method, Center of sums, Mean max method	Selection operators of GA-Roulette Wheel, Tournament selection, Boltzmann selection and Rank Selection
S-5	SLO-1	Perceptrons-Algorithm	Bidirectional associative memories-Architecture (BAM)	Fuzzy Max-Min Composition	Introduction to Architecture of Mamdani Type Fuzzy Control Systems	Crossover operators of GA-Single point
	SLO-2	Application of Perceptron algorithm	BAM Algorithm-Analysis	Fuzzy Max-Product Composition	Fuzzy Reasoning approach	Two point-multiple point-Uniform crossovers

S-6	SLO-1	Delta Rule	Competitive Learning Networks-Basics	Types of fuzzy sets-Terms of fuzzy sets	Takagi and Sugeno's approach	Mutation operators of GA
	SLO-2	Derivations--Adaline Algorithm	Kohonen Self organizing Maps-Algorithm	Types of Membership Function distributions	Introduction to Fuzzy Clustering	Sample Problem to demonstrate the working of GA
S-7	SLO-1	Back Propagation Algorithm-Derivation	Learning Vector Quantization (LVQ)	Classical Logic, Multivalued Logics	Fuzzy Knowledge Based Systems for real world applications.	GA convergence analysis
	SLO-2	Sample problem for BPN	LVQ-Architecture-Algorithm	Fuzzy Propositions	Design of controllers using Simulation Software	Application of Genetic Algorithm.
S-8	SLO-1	Radial Basis Function Networks-Basics	Basic architecture of Adaptive Resonance Theory (ART)	Fuzzy Qualifiers	Hybrid Model implementing Fuzzy and Neuro	Hybrid Algorithms using GA
	SLO-2	Algorithm of RBF	Basic Operation of ART	Linguistic Variables, Linguistic Hedges	Adaptive Neuro-Fuzzy Inference Systems	Basics of GA-Fuzzy Logic, GA-Neural Network
S-9	SLO-1	Multilayer Perceptron Model	Applications of Artificial Neural Networks	Introduction to basic Fuzzy Arithmetic	Architecture of adaptive neuro fuzzy Hybrid Learning Algorithm	GA-Fuzzy-Neural Network
	SLO-2	Madaline	Design of controllers using Simulation Software	Extension Principle.	Learning Methods that Cross-fertilize ANFIS and RBFN	Case study on real time application using Neuro/Fuzzy/Genetics

Learning Resources	<ol style="list-style-type: none"> 1. Laurene Fausett., Fundamentals of Neural Networks-Architecture, Algorithms and Application, Prentice Hall International, First edition, 1994. 2. Timothy J. Ross, Fuzzy Logic with Engineering Applications, John Wiley and sons Ltd. publication, Fourth edition, 2016. 3. Kalyanmoy Deb, Optimization for Engineering Design: Algorithms and Examples, Prentice Hall of India, second edition, 2012. 4. David E. Goldberg, Genetic Algorithms in search, optimization and machine learning, Pearson Education Inc, First edition, 1989. 	<ol style="list-style-type: none"> 5. Anderson, James A., An Introduction to Neural Networks, Prentice Hall of India, ISBN: 978-81-203-13514,, 2008. 6. Zimmerman H.J, Fuzzy set Theory-and its applications, Kluwer Academic Publishers, second edition, 1991. 7. Hertz J. Krogh, R.G. Palmer, Introduction to the Theory of Neural Computation, Addison- Wesley, ISBN 9780201515602, 1991. 8. G.J. Klir & B. Yuan, Fuzzy Sets & Fuzzy Logic, Prentice Hall of India, 2006, ISBN: 978-81-203-1136-7 9. http://www.myreaders.info/html/soft_computing.html

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Roosefart Mohan, Nelcast Limited, Chennai, roosefart@gmail.com	1. Dr. R. Subha, Associate Prof., Sir MVIT, subha.mvit@gmail.com	1. Dr. D. Suchitra., SRMIST
2. Mr. Muralikrishna, National Instruments, emkkrishnan@gmail.com	2. Dr. C. Nayanatara, Shri Sairam Engineering College, nayanatara.eee@sairam.edu.in	2. Dr. J. Preetha Roselyn, SRMIST

Course Code	18EEE424T	Course Name	ARTIFICIAL INTELLIGENCE			Course Category	E	Professional Elective				L	T	P	C
												3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil	
Course Offering Department		Electrical and Electronics Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:					Learning			Program Learning Outcomes (PLO)															
CLR-1 :	Impact the knowledge on AI and its different Heuristic solution strategies							1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Provide adequate knowledge on the technology of knowledge-based agents and Game Playing							Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Describe the different planning approaches																								
CLR-4 :	Discuss the different learning algorithms																								
CLR-5 :	Understand the basics of machine learning algorithm																								
CLR-6 :	Create an overall knowledge of different artificial intelligence approaches																								
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:					2	80	75	H	H	-	-	-	-	-	-	-	-	-	-	H	M	-	
CLO-1 :	Illustrate the concept of AI and different Heuristic methodologies							2	80	75	H	H	-	-	-	-	-	-	-	-	-	-	M	M	-
CLO-2 :	Recall different technologies in knowledge-based agents and Game Playing							2	80	75	H	H	-	-	-	-	-	-	-	-	-	-	M	M	-
CLO-3 :	Analyze the different planning approaches							2	80	75	H	H	-	-	-	-	-	-	-	-	-	-	H	M	-
CLO-4 :	Apply the different learning algorithms for real time systems							2	80	75	H	M	-	-	-	-	-	-	-	-	-	-	H	H	-
CLO-5 :	Implement the machine learning algorithm for clustering and regression							2	80	75	H	H	-	-	-	-	-	-	-	-	-	-	H	M	-
CLO-6 :	Utilize a perfect artificial intelligence approach for different applications							2	80	75	H	H	-	-	-	-	-	-	-	-	-	-	H	M	-

Duration (hour)	9		9		9		9		9	
S-1	SLO-1	Introduction to Artificial Intelligence (AI)	Games as Search Problems	The Planning Problem	Representing Knowledge in an Uncertain Domain	Types of Machine Learning: Supervised Learning Reinforcement				
	SLO-2	The Foundations of AI	Optimal Decisions in Games	Planning with State-Space Search	The Semantics of Bayesian Networks	Unsupervised Learning Reinforcement				
S-2	SLO-1	The History of AI	Alpha-Beta Pruning	Partial-Order Planning, Planning Graphs	Efficient Representation of Conditional Distributions	Over fitting and linear regression				
	SLO-2	The State of the Art	Imperfect Decisions, State-of-the-Art Game Programs	Planning with Propositional Logic	Exact Inference in Bayesian Networks	Learning Curve				
S-3	SLO-1	Structure of Intelligent Agents	Knowledge-Based Agents	Analysis of Planning Approaches	Approximate Inference in Bayesian Networks	Parametric vs. non-parametric models				
	SLO-2	Problem-Solving Agents	The Wumpus World	Hierarchical Task Network Planning	Relational and First-Order Probability Models	Linear models				
S-4	SLO-1	Formulating Problems	Logic, Propositional Logic	Planning and Acting in Nondeterministic Domains	Forms of Learning	Bayesian hierarchical clustering				
	SLO-2	Searching for Solutions	Reasoning Patterns in Propositional Logic	Conditional Planning	Supervised Learning	Clustering datapoints and features				
S-5	SLO-1	Uninformed Search Strategies	Effective propositional inference	Execution Monitoring and Re-planning	Learning Decision Trees	K-Means clustering				
	SLO-2	Informed (Heuristic) Search Strategies	Agents Based on Propositional Logic	Continuous Planning	Ensemble Learning	K-Medoids clustering				
S-6	SLO-1	Heuristic Functions	Syntax and Semantics of First-Order Logic	Multi-Agent Planning	A Logical Formulation of Learning	Neural network Representation				
	SLO-2	Local Search Algorithms	Unification and Lifting	Acting under Uncertainty	Knowledge in Learning	Perceptrons, Feed forward networks				
S-7	SLO-1	Optimization Problems	Forward Chaining	Basic Probability Notation	Explanation-Based Learning	Back Propagation Algorithms				
	SLO-2	Local Search in Continuous Spaces	Backward Chaining	The Axioms of Probability	Learning Using Relevance Information	Recurrent networks				
S-8	SLO-1	Online Search Agents	Resolution, Ontological Engineering	Inference Using Full Joint Distributions	Inductive Logic Programming	Linear Regression				
	SLO-2	Constraint Satisfaction Problems	Categories and Objects	Independence	Statistical Learning	Logistic Regression				
S-9	SLO-1	Backtracking Search for CSPs	Mental Events and Mental Objects	Bayes' Rule and Its Use	Learning with Complete Data	Maximum Likelihood estimation (least squares)				

	SLO-2	Local Search for Constraint	The Internet Shopping World	The Wumpus World Revisited	Learning with Hidden Variables: The EM Algorithm	Online learning and stochastic optimization
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Learning Resources	1. Stuart Russell and Peter Norvig, <i>Artificial Intelligence – A Modern Approach</i> , Pearson Education Press, 2010. 2. Kevin Knight, Elaine Rich, B. Nair, <i>Artificial Intelligence</i> , McGraw Hill, 2008. 3. George F. Luger, <i>Artificial Intelligence</i> , Pearson Education, 2001.	4. Kevin P. Murphy, <i>Machine Learning: A Probabilistic Perspective</i> , MIT Press, 2012. 5. Stephen Marsland, <i>Machine Learning –An Algorithmic Perspective</i> , CRC Press, 2009. 6. https://www.youtube.com/playlist?list=PL6EE0CD02910E57B8 .
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1.Mr. Tripathi patro,visam pvt ltd,btp@visom.co.in	1.Dr.P.Ganesh Kumar, Anna University, ganesh23508@gmail.com	1.Dr.J.Preetha Roselin, SRMIST
2.Mr.Balachandrasekar.K,CTS,dyaksha@gmail.com	2.Dr. C.Nayanatara, Shri Sairam Engineering College, nayanatara.eee@sairam.edu.in	2.Mr.P.Kanakaraj, SRMIST

Course Code	18EEE425T	Course Name	FUNDAMENTALS OF BIG DATA ANALYTICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
		1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-1 :	Introduce big data and its role in various domains	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-2 :	Learn and analyze the big data analytical tools				H	-	-	-	-	-	M	-	-	-	-	-	H	M	M
CLR-3 :	Introduce Hadoop and its components				H	H	H	H	H	-	-	M	-	-	-	-	M	M	M
CLR-4 :	Implement Map Reduce technique				H	H	M	M	H	-	-	-	-	-	-	-	H	M	-
CLR-5 :	Study the security concerns of big-data				H	H	M	M	H	-	-	-	-	-	-	-	H	M	H
CLR-6 :	Create an overall knowledge in big data with different environment				H	H	M	M	-	-	-	H	-	-	-	-	H	M	H
					H	H	M	M	M	-	-	M	-	-	-	-	H	M	M
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	1	2	3															
CLO-1 :	Familiarize with applications of Big Data Analytics in various domains	1	80	75															
CLO-2 :	Practice open source big data analytical tools	2	80	75															
CLO-3 :	Install and operate the open source Distributed File System Hadoop	2	80	75															
CLO-4 :	Solve simple problems using Map Reduce Technique	2	80	75															
CLO-5 :	Analyze the log file in security aspects	2	80	75															
CLO-6 :	Design a big data platform for different applications	2	80	75															

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Introduction to Big Data Platform	Data Analytics Lifecycle	History of Hadoop	Developing a Map Reduce Application	Introduction to Security Analytics
	SLO-2 Challenges of Conventional Systems	Overview of Data Analytics Lifecycle	Hadoop Distributed File System	How MapReduce Works	Challenges in Security Analytics
S-2	SLO-1 Intelligent data analysis	Successful Analytics Project	Components of Hadoop	Unit Tests	Concepts in Data Analytics
	SLO-2 Nature of Data	Key Roles for a Successful Analytics Project	Analyzing the Data with Hadoop	Unit Tests with MapReduce Unit	Techniques in Data Analytics
S-3	SLO-1 Analytic Processes and Tools	Background of Data Analytics Lifecycle	Scaling Out, Hadoop Streaming	Test Data	Data for Security Analysis
	SLO-2 Industry Examples of Big Data	Global Innovation Network and Analysis	Design of HDFS	Local Tests	Analysis in Everyday Life
S-4	SLO-1 Web Analytics	Case Study: Global Innovation Network and Analysis	Java Interfaces to HDFS Basics	Anatomy of a Map Reduce Job Run	Scenarios in Intrusion
	SLO-2 Big Data and Marketing	Introduction to R	Data Flow, Hadoop I/O	Classic MapReduce	Challenges in Intrusion
S-5	SLO-1 Fraud and Big Data	Introduction to SQL	Data Integrity	YARN	Incident Identification
	SLO-2 Risk and Big Data	Charts	Compression, Serialization	Failures in Classic MapReduce	Analysis of Log File
S-6	SLO-1 Credit Risk Management	Graphs	Avro, File Based Data Structures	Failures in YARN	Loading the Data
	SLO-2 Big Data and Algorithmic Trading	Data tools	Pig, Hive	Job Scheduling	Simulation
S-7	SLO-1 Big Data and Healthcare	Statistical Methods	Hbase	Shuffle and Sort	Security Process
	SLO-2 Big Data in Medicine	Clustering	Data Model and Implementations	Task Execution	Access Analytics
S-8	SLO-1 Advertising and Big Data	Association Rules Regression	Hbase Clients, Hbase Examples	MapReduce Types	Security Analysis
	SLO-2 Different advertising in Big Data	Classification	Praxis, Cassandra	MapReduce Formats	Security Analysis with Text Mining
S-9	SLO-1 Big Data Technologies	Time Series Analysis	Cassandra Data Model	MapReduce Features	Security Breaches
	SLO-2 Classification of different technologies in Big Data	Text Analysis	Cassandra Clients, Cassandra Examples	Hadoop environment	Security Breaches Examples

Learning Resources	1. David Dietrich, Barry Heller and Beibei Yang, <i>Data Science and Big Data Analytics: Discovering, Analyzing, Visualizing and Presenting Data</i> , Reprint 2015, EMC Education Services, Wiley, ISBN:9788126556533.	3. https://www.tutorialspoint.com/big_data_analytics/index.htm
	2. Tom White, <i>Hadoop: The Definitive Guide, Third Edition</i> , O'reilly Media, 2012.	4. https://www.youtube.com/playlist?list=PLFW6iRTa1g813lyYHLRP_bWJEKQDeEcSP 5. Mark Allen Weiss, <i>Data Structures and Algorithm Analysis in C++, Third Edition</i> , 2009

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1.Mr. Tripathi patro.visam pvt ltd, btp@visom.co.in	1.Dr.P.Ganesh Kumar, Anna University, ganesh23508@gmail.com	1. Dr.E.Poovammal, SRMIST
2.Mr.Balachandrasekar.K, CTS, dyaksha@gmail.com	2.Dr. C.Nayanatara, Shri Sairam Engineering College, nayanatara.eee@sairam.edu.in	2. Mr.P.Kanakaraj, SRMIST

Course Code	18EEE426T	Course Name	FUNDAMENTALS OF CLOUD COMPUTING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:		Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Outline cloud computing and its model			Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2 :	Explain the cloud-enabling technology and its applications						Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3		
CLR-3 :	Educate on different cloud computing architectures						H	-	-	-	-	-	-	-	-	-	-	-	-	H	M	M	
CLR-4 :	Understand the cost metrics and cloud management						H	H	M	M	M	-	-	-	L	-	-	-	-	M	M	L	
CLR-5 :	Provide adequate knowledge in cloud security						H	-	-	-	-	-	-	-	-	-	-	-	-	-	H	M	-
CLR-6 :	Create application by utilizing cloud platforms						H	H	M	M	-	-	-	M	-	-	-	-	-	H	H	M	
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:		1	80	75	H	H	M	M	-	-	-	M	-	-	-	-	H	M	M		
CLO-1 :	Recall the basic concepts of cloud computing and its model			2	80	75	H	H	M	M	M	-	-	L	-	-	-	M	M	L			
CLO-2 :	Acquire knowledge on the cloud enabling technologies and its applications			1	80	75	H	-	-	-	-	-	-	-	-	-	-	-	H	M	-		
CLO-3 :	Illustrate the basic concepts of cloud computing architecture			2	80	75	H	H	M	M	-	-	-	M	-	-	-	-	H	H	M		
CLO-4 :	Analyze the cost metrics and recall the concepts of cloud management			2	80	75	H	H	H	M	-	-	-	M	-	-	-	-	H	M	M		
CLO-5 :	Realize the security threats in cloud			2	80	75	H	H	M	M	M	-	-	M	-	-	-	-	H	M	M		
CLO-6 :	Design a perfect cloud platform for different applications			2	80	75	H	H	M	M	M	-	-	M	-	-	-	-	H	M	M		

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Cloud	Key Drivers to Adopting the Cloud	Requirements of Cloud computing architecture	Cost Metrics	Infrastructure Security
	SLO-2	Overview of Cloud	Examples of Key Drivers to Adopting the Cloud	Introduction to Cloud computing architecture	Pricing Models	The Network Level Infrastructure Security
S-2	SLO-1	Basic Concepts of Cloud	The Impact of Cloud Computing	Workload Distribution Architecture	Business Cost Metrics	The Host Level Infrastructure Security
	SLO-2	Basic Terminology of Cloud	The Impact of Cloud Computing on Users	Example	Cloud Usage Cost Metrics	The Application Level Infrastructure Security
S-3	SLO-1	Goals	Broadband Networks	Resource Pooling Architecture	Cost Management	Data Security and Storage
	SLO-2	Benefits	Internet Architecture	Example	Considerations of Cost Management	Aspects of Data Security
S-4	SLO-1	Risks	Data Center Technology	Dynamic Scalability Architecture	Service Quality Metrics	Data Security Mitigation
	SLO-2	Challenges	Virtualization Technology	Example	Different types of Service Quality Metrics	Provider Data
S-5	SLO-1	Cloud service provider	Web Technology	Elastic Resource Capacity Architecture	SLA	Provider Data Security
	SLO-2	Cloud service consumer	Multitenant Technology	Example	SLA Guidelines	Encryption
S-6	SLO-1	Cloud Characteristics	Service Technology	Service Load Balancing Architecture	Identity and Access Management	Hashing
	SLO-2	Issues in Cloud Computing	Different Applications of Cloud Computing	Example	Trust Boundaries	Digital Signature
S-7	SLO-1	Cloud Computing	Healthcare	Cloud Bursting Architecture	IAM	Public Key Infrastructure (PKI)
	SLO-2	Grid Computing	Energy systems	Example	IAM Challenges	Example
S-8	SLO-1	Comparative study of Cloud Computing and Grid Computing	Transportation systems	Elastic Disk Provisioning Architecture	Relevant IAM Standards for Cloud Services	Single Sign On (SSO)
	SLO-2	Cloud Service Models	Manufacturing industry	Example	Relevant IAM Protocols for Cloud Services	Kerberos authentication - One-time password
S-9	SLO-1	IaaS, PaaS and SaaS	Education	Redundant Storage Architecture	IAM Practices in the Cloud	Example
	SLO-2	Cloud Deployment Models	Mobile Communication	Example	Cloud Authorization Management	Cloud Based Security Groups

Learning Resources	1. Thomas Erl, Zaigham Mahmood, Richardo Puttini, <i>Cloud Computing: Concepts, Technology & Architecture</i> , Fourth Printing, Prentice Hall/Pearson PTR, 2014, ISBN: 9780133387520.	4. Arshdeep Bahga, Vijay Madisetti, <i>Cloud Computing: A Hands-On Approach</i> , University Press, 2016, ISBN: 9780996025508.
	2. Tim Mather, Subra Kumaraswamy, Shahed Latif, <i>Cloud Security and Privacy: An Enterprise Perspective on Risks and Compliance</i> , O'Reilly Media, Inc., Computers - 338 pages. https://www.youtube.com/channel/UCK73enkfQNDwdBqMyaMtRg/videos	5. K.Chandrasekaran, <i>Essentials of Cloud Computing</i> , Chapman and Hall/CRC Press, 2014, ISBN 9781482205435.
	3. https://www.youtube.com/channel/UCK73enkfQNDwdBqMyaMtRg/videos	6. Thomas Erl, Robert Cope, Amin Naserpour, <i>Cloud Computing Design Patterns</i> , Prentice Hall/Service Tech Press, Pearson, 2015, ISBN: 978-0133858563.

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

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2.Mr.Balachandrasekar.K,CTS,dyaksha@gmail.com	2.Dr. C.Nayanatara, Shri Sairam Engineering College, nayanatara.eee@sairam.edu.in	2. Mr.P.Kanakaraj, SRMIST

ACADEMIC CURRICULA

Professional Elective Courses

ELECTRONICS AND COMMUNICATION ENGINEERING

Regulations - 2018



SRM INSTITUTE OF SCIENCE AND TECHNOLOGY

(Deemed to be University u/s 3 of UGC Act, 1956)

Kattankulathur, Kancheepuram, Tamil Nadu, India

Course Code	18ECE201J	Course Name	PYTHON AND SCIENTIFIC PYTHON	Course Category	E	Professional Elective	L	T	P	C
							2	0	2	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:		
CLR-1 :	Understanding the python language construct and apply them for scientific computation			
CLR-2 :	Apply python vector ,list and plot concept to solve curve fitting			
CLR-3 :	Applying Dictionary concept to model Polynomials			
CLR-4 :	Create insights to difference equation based system model and solving them with python			
CLR-5 :	Analyze Monte Carlo Simulation for computing Probabilities			
CLR-6 :	Create insights to the concepts and programming of SciPy, numpy, matplotlib to solve scientific problem			

Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:		
CLO-1 :	Apply python language construct to compute formula and scientific problem			
CLO-2 :	Analyze Mathematical Models system using f Difference Equations and solving			
CLO-3 :	Apply time sequence concept for generation and processing of audio signal by python			
CLO-4 :	Apply python language construct to solve Polynomials			
CLO-5 :	Apply python language construct to compute probability by Monte Carlo Simulation ,game design and dynamic random motion creation			
CLO-6 :	Apply SciPy, numpy, matplotlib to statistical analysis , correlation coefficient analysis , Solving equations- Linear least squares solutions and signal processing			

Learning		
1	2	3
Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)

Program Learning Outcomes (PLO)														
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
H	H	-	-	-	-	-	-	-	-	-	-	-	-	H
H	H	-	-	-	-	-	-	-	-	-	-	-	-	H
H	-	-	H	-	-	-	-	-	-	-	-	H	-	-
H	H	-	-	-	-	-	-	-	-	-	-	-	-	H
H	-	H	-	-	-	-	-	-	-	-	-	-	-	H
-	-	-	-	-	-	-	-	-	-	-	-	-	-	H

Duration (hour)		Solving Simple Formula And Scientific Problem	Plots, Array and Difference Equation Modelling	File I/O, Polynomials and Web Programming	Random Process and Game Programming	SciPy ,Numpy and Signal Processing
		12	12	12	12	12
S-1	SLO-1	Computing with Formulas- Using a Program as a Calculator	Vectors, Mathematical Operations on Vectors, Vector Arithmetics and Vector Function	Reading Data from File- Line by Line, Reading a Mixture of Text and Numbers	Drawing Random Numbers- Uniformly Distributed Random Numbers	SciPy, numpy, matplotlib
	SLO-2	Using Variables, Formatting Text and Numbers	Arrays in Python Programs-Using Lists for Collecting Function Data	Making Dictionaries	Computing the Mean and Standard Deviation	Basic array methods in numpy, Changing the shape of an array
S-2	SLO-1	Celsius-Fahrenheit Conversion,	Curve Plotting-The SciTools and Easyviz Packages	Dictionary Operations	The Gaussian or Normal Distribution- Drawing a Random Element from a List	Maximum and minimum values
	SLO-2	Evaluating Standard Mathematical Functions, Type Conversion	Plotting a Single Curve, Decorating the Plot, Plotting Multiple Curves, Controlling Line Styles	Polynomials as Dictionaries, File Data in Dictionaries, File Data in Nested Dictionaries	Drawing random interger	Reading and writing an array to a file
S-3-4	SLO-1	Lab 1:programming on formula and Standard Mathematical Functions-	Lab 4: Curve Plotting	Lab 7: reading student marks file into a dictionary data with the student name as key and computing the average grades	Lab 10: real card games	Lab 13: numpy file reading and data analysis
	SLO-2	Evaluate a Gaussian function, Compute the air resistance on a football				
S-5	SLO-1	Complex Numbers, Complex Arithmetic's in Python	Numerical Python Arrays manipulations	Strings- Common Operations on Strings	Computing Probabilities- Principles of Monte Carlo Simulation	Statistical methods in numpy
	SLO-2	Input Data-Reading Keyboard Input- Reading from the Command Line	Higher-Dimensional Arrays- Two-Dimensional Numerical Python Arrays	Reading Coordinates	Throwing Dice, Rolling Two Dice game	Statistical methods in numpy

S-6	SLO-1	Making Modules, Collecting Functions in a Module File	Matrix Objects	Reading Data from Web Pages- About Web Pages	Drawing Balls from a Hat	Histograms
	SLO-2	Using Modules	Mathematical Models Based on Difference Equations- Interest Rates	Access Web Pages in Programs- Reading Pure Text Files,	Simple Games- Guessing a Number	Solving equations- Linear least squares solutions- Beer-Lambert Law
S 7-8	SLO-1	Lab 2: program on Making Modules and using them	Lab 5: Animating a Function-temperature on earth	Lab 8:reading web temperature text file into Dictionaries and computing average Temperature	Lab 11: Simple Games	Lab 14: the correlation coefficient between pressure and temperature
	SLO-2					
S-9	SLO-1	while loops and for loops	the Factorial as a Difference Equation	Extracting Data from an HTML Page	Random Walk in One Space Dimension	One-Dimensional Fast Fourier Transforms
	SLO-2	Lists and list manipulation	Growth of a Population, Payback of a Loan, Making a Living from a Fortune	Writing a Table to File, Reading and Writing Spreadsheet Files	Basic Implementation, visualization and Computing Statistics of the Particle Positions	Matplotlib basics- Plotting on a single axes object, scatter plot, Bar charts and pie charts
S-10	SLO-1	Loops with List Indices, Nested Lists	Logistic Growth, Programming with Sound Writing Sound to File, Reading Sound from File,	Representing a Function as a Class and manipulation	Random Walk in Two Space Dimensions	Choosing the Length of the DFT
	SLO-2	Tuples, Functions, Lambda Functions, If Tests	Playing Many Notes	Bank Accounts as class, A Class for Solving ODEs	Basic Implementation, visualization and Computing Statistics of the Particle Positions	Filters in Signal Processing
S 11-12	SLO-1	Lab 3: Programming on list and loops	Lab 6: Sound generated by formula and difference equation	Lab 9: Programming on class	Lab 12: Random Walk in One Space Dimension or Two Space Dimensions	Lab 15: Numpy signal processing
	SLO-2					

Learning Resources	1. Hans Petter Langtangen, "A Primer on Scientific Programming with Python", Springer, 2000. 2. Christian Hill, "Learning Scientific Programming with Python", Cambridge University Press, 2015.	3. Juan Nunez-Iglesias, Stéfan van der Walt, and Harriet Dashnow Elegant SciPy The Art of Scientific Python, O'Reilly Media, 2017.
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Learning Assessment												
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)		
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#				
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand											
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze											
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%	15%
	Create											
	Total	100 %		100 %		100 %		100 %		100 %		

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Anuj Kumar, Bombardier Transportation, Ahmedabad, kumaranuj.ani@gmail.com	1. Dr. Meenakshi, Professor of ECE, CEG, Anna University, meena68@annauniv.edu	1. Dr. P. Vijayakumar, SRMIST
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	

Course Code	18ECE202T	Course Name	MICRO- AND NANO-FABRICATION TECHNOLOGIES	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:		Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Provide learners a systematic overview of micro and nano fabrication processes			Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Gain understanding of lithography, etching and ion implantation methods to fabricate, structure and modify the layer						Engineering Knowledge	Problem Analysis0	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Understand thin film fabrication techniques including PVD and CVD and to apply the knowledge to film formation																				
CLR-4 :	Apply the knowledge of microfabrication technology to the fields of general microelectronics systems																				
CLR-5 :	Learn the significant advances in molecular engineering																				
CLR-6 :	Embark on building micro/ nano structures applicable to their needs.																				
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:		2	80	70	H	-	-	-	-	-	-	-	-	-	-	M	-		
CLO-1 :	Understand the various layering Technologies			2	85	75	H	-	M	-	-	-	-	-	-	-	-	M	-		
CLO-2 :	Realize how the pattern generation is done using Lithography Techniques			2	75	70	H	-	M	-	-	-	-	-	-	-	-	-	-	H	
CLO-3 :	Gain knowledge on particle sources, Optics and Interaction			2	85	80	H	-	M	-	-	-	-	-	-	-	-	-	-	H	
CLO-4 :	Learn the device and circuit fabrication Techniques			2	85	75	H	-	-	H	-	-	M	-	-	M	-	-	-	H	
CLO-5 :	Learn about new and advances in fabrication Technologies			2	80	70	H	M	-	-	M	-	-	-	-	L	M	-	-	H	
CLO-6 :	Know the limitations and tools of micro, nanofabrication.																				

Duration (hour)		Crystal Growth, Epitaxy, Oxidation	Lithographic Processes	Deposition, Diffusion, Ion implantation	Device Circuit Fabrication	Molecular Nanotechnology
		9	9	9	9	9
S-1	SLO-1	Starting Materials	Photoreactive Materials	Vacuum Evaporation	Isolation	Directed Self Assembly
	SLO-2	Growth from Melt (Czochralski Technique)	Image Reversal	Sputter Deposition	Self Alignment	Device Assembly
S-2	SLO-1	Considerations for Paper Crystal Growth	Pattern Generation	Chemical Vapour Deposition	Local Oxidation-Trench Technique	Electrostatic
	SLO-2	Crystal Orientation, Crystal hardening Techniques	Mask Making	Growth Habit	Planarization	Templated self assembly
S-3	SLO-1	Doping, Dislocation	Pattern Transfer	Films for protection & Masks	Metalization	Colloids & Nanoparticles
	SLO-2	Molecular Beam Epitaxy	Optical Printing	Self-aligned Masks	Gettering	Block Copolymers
S-4	SLO-1	Gas Source MBE	Advanced Techniques	Films for Doping	NIOS-based Micro Circuits	DNA Nanostructures
	SLO-2	Vapour Phase Epitaxy	Short Wave lengths	Dopant Sources	P,n Channel Transistors	Scanning probe lithography Techniques
S-5 S-6	SLO-1	VPE Process to Silicon	Multilayer Resists	Films for Ohmic contacts	Complementary Transistors	Local Anodic Oxidation

	SLO-2	VPE Process for GaAs	Phase Shifting Masks	Wet Chemical etching	Memory Devices	Scribing
S-7	SLO-1	Liquid Phase Epitaxy	Electron Beam Techniques	Anisotropic Effects	SOI Devices	Atomic Manipulation
	SLO-2	LPE System	Lon-Beam Techniques	Dry Physical Etching	BJT based Silicon Micro Circuits	SPM Scanning Probe Microscopy
S-8	SLO-1	Thermal Oxidation of Silicon	X Ray Printing	Dry Chemical Etching	The buried layer	Erasable Electrostatic Lithography
	SLO-2	Kinetics of Oxide Growth	Problem areas- defects	Reactive Lon Etching	p-n-p Transistor	Limits to Nano Fabrication
S-9	SLO-1	Oxidation System	Feature size control & anisotropic Etch Mechanism	Penetration range & Transverse effects	Field Effect Transistor	Limits to MSO Devices
	SLO-2	Halogenic Oxidation	Lift off Techniques	Annealing	BICMOS Integrated Circuits	Limits for Pattern Generation
	SLO-2	Anodix Oxidation Plasma Processes	Plasma reactor Relative Plasma etching Technique	Ion Implantation systems High energy, high current Inplants	Self Aligned Technology The Hetero junction Bipolar Transistor	Nanofabrication Tools

Learning Resources	<ol style="list-style-type: none"> 1. Sorab. K. Gandhi, "VLSI Fabrication and Principles", McGraw Hill, 2005 2. Sami Franssila, "Introduction to Microfabrication", Wiley Publications, 2010 3. Richard C. Jaeger, "Introduction to Microelectronic Fabrication", Prentice hall, 2002 4. Ivor Brodie & Julius J. Muray, "The Physics of Micro/ Nano- Fabrication" Springer, 1992 	<ol style="list-style-type: none"> 5. Bo Cui, "Recent advances in Nanofabrication Techniques and Applications", InTech Publisher, 2011 6. A G Davies and J M T Thompson, "Advances in Nanoengineering Electronics, Materials and Assembly", Imperial College Press, 2007 7. Michael Pycraft Hughes, "Nanoelectromechanics in Engineering and Biology", by CRC Press LLC, 2003
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	40%	-	40%	-	40%	-	40%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	20%	-	20%	-	20%	-	20%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Anuj Kumar, Bombardier Transportation, Ahmedabad, kumar.anuj.ani@gmail.com	1. Dr. Meenakshi, Professor of ECE, CEG, Anna University, meena68@annauniv.edu	1. Dr. P. Aruna Priya, SRMIST
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	

Course Code	18ECE204J	Course Name	ARM-BASED EMBEDDED SYSTEM DESIGN	Course Category	E	Professional Elective	L	T	P	C
							2	0	2	3

Pre-requisite Courses	18ECC203J	Co-requisite Courses	Nil	Progressive Courses	18ECE305J, 18ECE306J
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/ Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Understand fast software development tools of ARM processor	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Understand I/O programming for ARM chip; A/D, PWM etc.	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Understand the usage of timers and serial interfacing.	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Know effective use of memory; and network interfacing, Ethernet and wireless protocol supports	Expected Attainment (%)	Design & Development
CLR-5 :	Make application for audio signal processing.		Analysis, Design, Research
CLR-6 :	Develop ARM Cortex-M based embedded systems for networking and signal processing applications.		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Learns about "mbed" software and C language application for ARM Cortex-M processors.	2 80 70	L
CLO-2 :	Learns using mbed software to use A/D converter, PWM generation and digital input / output.	2 80 70	L M M
CLO-3 :	Learns to program System timer and interval timers; use serial interface and use LCD display.	2 80 70	
CLO-4 :	Learns to use memory effectively and program network interface.	3 80 60	M M
CLO-5 :	Learns to do audio signal processing on embedded platform.	3 80 60	M M M M
CLO-6 :	Use of "mbed" software pack on ARM Cortex-M processor for networking and simple signal processing.	3 80 60	L M M M M

Duration (hour)	Cortex-M processor	Peripheral Interfacing-I	Peripheral Interfacing-II	Network Interfacing	Audio Signal Processing
	15	15	15	15	15
S-1	SLO-1	Introducing embedded systems and mbed	Starting to Program Digital Input and Output	Introducing Synchronous Serial Communication	Memory organization
	SLO-2	Introducing embedded systems and mbed	Voltages as Logic Values	I2C bus	Memory organization
S-2	SLO-1	ARM Cortex assembly language basics.	Introducing Analog output Data Conversion	Communicating With I2C-Enabled Sensors	Using Data Files With the mbed
	SLO-2	ARM Cortex assembly language basics.	Digital Output on the mbed	Asynchronous Serial Data Communication	Example mbed Data File Access
S 3-4	SLO-1	Lab-1: Assembly language program, simulation -1	Lab 4: A/D conversion program	Lab 8: Multinode I2C Bus	Lab 10: Data logging
	SLO-2				Lab 13: Audio signal generation
S-5	SLO-1	Cortex-M processor architecture and Basics : Programming exercises	Digital Input and Output.	LCD interfacing	Using External SD Card Memory With the mbed
	SLO-2	Cortex-M processor architecture and Basics : Programming exercises	Digital Input and Output.	Using the mbed TextLCD Library	Using External USB Flash Memory With the mbed
S-6	SLO-1	Development Environment using the mbed	Switching Larger DC Loads	Time and Tasks in Embedded Systems	Introduction to Internet Communication

	SLO-2	Development Environment using the mbed	Switching Larger DC Loads	Responding to External Events	The Ethernet Communication Protocol	High-Fidelity Digital Audio With the mbed
S 7-8	SLO-1	Lab 2: Assembly language program, simulation-2	Lab 5: Mini Project: Letter Counter	Lab 8: A/D output on LCD	Lab 11: Ethernet Communication	Lab 14: Model lab examination
	SLO-2					
S-9	SLO-1	Keil IDE and Debugging tools	Another Form of Analog Output: Pulse Width Modulation	An Introduction to Timers	Introducing Wireless Data Communication	Summary on Digital Audio and Digital Signal Processing
	SLO-2	Keil IDE and Debugging tools	Pulse Width Modulation on the mbed	Using the mbed Timer	Wireless Data Communication : Bluetooth and Zigbee	Summary on Digital Audio and Digital Signal Processing
S-10	SLO-1	C- language review	Design of PWM problem	Using the mbed Timeout and Ticker	Local Area Network Communications With the mbed	Review and discussions
	SLO-2	Embedded C , introduction	Design of PWM problem	The Real-Time Clock	Using RPC	Review and discussions
S 11-12	SLO-1	Lab 3: Parallel port programming, simulation	Lab 6: PWM waveform generation	Lab 9: Experimenting Interrupts, Timers	Lab 12: RPC Communication through ethernet	Lab 15: Final lab examination
	SLO-2					

Learning Resources	1. Tim Wilmshurst, "Fast and effective embedded system design, Applying the ARM mbed", ARM Education Media, 2018. 2. Andrew Sloss, Dominic Symes, Chris Wright, "ARM System Designers Guide: Designing and optimizing System Software", The Morgan Kaufmann Series in Computer Architecture and Design, 2004.	3. Theory/Lab teaching materials, "Efficient embedded system design kit", ARM Education media.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#		Theory	Practice
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice		
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
Level 2	Understand										
	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
Level 3	Analyze										
	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		-	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

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2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	2. Prof. V. Natarajan, SRMIST

Course Code	18ECE205J	Course Name	FPGA-BASED EMBEDDED SYSTEM DESIGN	Course Category	E	Professional Elective	L	T	P	C
							2	0	2	3

Pre-requisite Courses	18ECC203J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)																				
CLR-1 :	Know why many high volume embedded systems need to be function specific		Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15			
CLR-2 :	Design circuits using FPGA knowledge of using its resources like, clock, cells, device modules, etc.																									
CLR-3 :	study Xilinx FPGA IDE and design practice																									
CLR-4 :	Understand platform FPGAs																									
CLR-5 :	Understand FPGA system design and practical issues																									
CLR-6 :	Develop designs using FPGAs/PSoCs for specific embedded modules and low-power designs																									
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																								
CLO-1 :	Explain Micro controller subsystems		2	80	70																					
CLO-2 :	Make system design with PSoCs		3	80	70																					
CLO-3 :	Understanding of Platform FPGAs		2	80	70																					
CLO-4 :	Understanding of FPGA architecture design		3	80	60																					
CLO-5 :	Designing with Platform FPGAs (examples)		3	80	60																					
CLO-6 :	Design simple FPGA based systems		3	80	60																					

Duration (hour)		Basics of Peripherals	PSoC Design	Xilinx Virtex 5 IDE	Platform FPGA Designs	Designing Simple FPGA based Systems
		15	15	15	15	15
S-1	SLO-1	Embedded systems performance criteria - Interrupts	PSoC3/5 architecture overview	Design challenges, life cycle	Design quality: correctness, reliability, resilience.	Communication: Coprocessor model
	SLO-2	Embedded systems performance criteria - Interrupts	PSoC3 architecture details and 8051 instructions	Metrics: measures of success	Modules and interfaces	Network on chip model
S-2	SLO-1	Embedded systems performance criteria - DMA	Interrupts and interrupt lines	Spectrometer example using Xilinx IDE	Abstraction and state,	Transfer of state
	SLO-2	Latency and its problems	Interrupt priority and nesting	Spectrometer example using Xilinx IDE	Cohesion and coupling and control flow graph	Practical issues: profiling issues
S-3-4	SLO-1	Lab 1: Embedded sensors and sensing -1	Lab 4: PSoC Design -1	Lab 7: VHDL, Verilog Practice session - 1	Lab 10: Sample design implementation	Lab 13: On-chip memory access, FIFOs
	SLO-2					
S-5	SLO-1	Embedded system subsystems: A/D conversion	The concept of memory and its connectivity to CPU	Xilinx Virtex 5 IDE	Origin of Platform FPGA Designs	Spatial design: Principles of parallelism
	SLO-2	Digital ports & its current capacity	Different DMA modes	Xilinx Virtex 5 IDE	Platform FPGA components	Granularity, degree of parallelism
S-6	SLO-1	Introduction to other digital interfaces	Clocking system: Internal master oscillator	PLD basics	Adding to platform FPGA systems	Spatial organizations

	SLO-2	Introduction to other digital interfaces	IMO, and sleep/wake up modes	FPGA configurations	Assembling custom compute cores	Spatial organizations
S 7-8	SLO-1	Lab 2: Embedded sensors and sensing - 2	Lab 5: PSoC Design -2	Lab 8: VHDL, Verilog Practice session - 2	Lab 11: Building base systems	Lab 14: Model lab examination
S-9	SLO-1	Sensors and sensing principles. Optical, capacitive sensors	Clock distribution	Various slices in Virtex 5	Software design :root file system, cross-developmental tools	Managing bandwidth: Balancing
	SLO-2	Magnetic, RF sensors	Power management: Internal regulators	Various slices in Virtex 5	Monitors and boot loaders	Khan process network
S-10	SLO-1	Processing: Mathematical views.	Types of reset	Bit stream	Overview of partitioning platform	Platform FPGA bandwidth techniques
	SLO-2	Programmable logic and mixed signal design fundamentals	Intro to PSoC creator IDE	Programming FPGA	Analytical solution to partitioning	On-chip, off-chip memory
S 11-12	SLO-1	Lab 3: Programmable logic design	Lab 6: PSoC Design - 3	Lab 9: Sample design implementation	Lab 12: Creating IP core	Lab 15: Final lab examination
	SLO-2					

Learning Resources	1. Robert Ashby, "Designers guide to the Cypress PSoC", Cypress Semiconductors, 2005. 2. Edward H. Currie and David Van Ess, "PSoC3/5 Reference Book", Cypress Semiconductor, 2010.	3. Sass and Schmidt, "Embedded system design with Platform FPGAs", Morgan Kaufmann, 2010. 4. Theory/Lab Session Teaching Materials, ARM Educational Media.
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Learning Assessment											
	Bloom'sLevel of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		-	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

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2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	2.

Course Code	18ECE207J	Course Name	REAL TIME OPERATING SYSTEMS			Course Category	E	Professional Elective				L	T	P	C
												2	0	2	3

Pre-requisite Courses	18CSS101J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1:	Develop application program in ARM based hardware, we need to know, C and assembly programming and IDE.				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Interface peripherals, and hence gain the knowledge of programming, need to be known.				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3:	Study RTOS principles																					
CLR-4:	Study RTOS principles of various types																					
CLR-5:	Develop application programming of sample projects																					
CLR-6:	Study and understand, how OS on ARM processor can be implemented and used.																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1:	Read and understand many microprocessor instruction sets and their use.				2	80	50	M												H		
CLO-2:	Implement and write code in assembly and C for embedded applications.				3	99	70		H	H		M				M				H		
CLO-3:	Understand the concepts and requirements of RTOS, in general basic OS principles.				2	80	70					M								H		
CLO-4:	Implement and use RTOS for embedded programs				3	90	70			H	M	M				M				H		
CLO-5:	Apply the knowledge in related sample use cases.				2	90	85	L	L			L										M
CLO-6:	Design processor based embedded systems along with OS implementation. (Specifically RTOS)				2	90	70	L	M	H	M	M				M				H		L

Duration (hour)	Cortex-M processor & 'C'		Peripheral Programming in 'C'		Concepts of RTOS	RTOS Implementation	RTOS Applications
	15		15		15	15	15
S-1	SLO-1	Cortex-M processor architecture	Parallel I/O programming		Introduction to RTOS	Process management	Real time systems: Data acquisition system
	SLO-2	Cortex-M processor architecture	Sample programs		Introduction to RTOS	Dynamic linking and loading	Real time systems: Data acquisition system
S-2	SLO-1	ARM Cortex assembly language – part1	Interrupt processing basics		Concurrent programming	Spin-lock semaphore, cooperative scheduling	Performance metrics
	SLO-2	ARM Cortex assembly language – part2	System tick; periodic interrupts		Thread fundamentals	Thread rendezvous	Examples and discussions
S 3-4	SLO-1	Lab 1: Arm Assembly language programming	Lab 4: Interrupts and timers in C and assembly		Lab 7: Simple thread programming in RTOS – Wave form simulation	Lab 10: Semaphore implementation experiment in RTOS	Lab 13: Any application program using RTOS.
	SLO-2						
S-5	SLO-1	ARM Cortex microcontroller interface standards	UART programming		Shared resources and Critical sections	FIFO & Little's theorem	Solid state disk
	SLO-2	IDE software tools	UART programming		Consumer producer problem	Three semaphore implementation	Flash device driver
S-6	SLO-1	Pointers in C	Digital signal time measurement		Switching threads	Thread sleeping	SD card interface
	SLO-2	Arrays, structures and unions, Linked lists	Use of timers and compare, capture registers.		Profiling the OS	Deadlocks, monitors	Communication systems with Ethernet
S	SLO-1						Lab 14: Model lab examination

7-8	SLO-2	Lab 2: C & assembly programming using Keil IDE and kit	Lab 5: Debugging hardware with target board – UART interface programming	Lab 8: Multi threaded application in RTOS – LED blinking with multi threads	Lab 11: Multi threaded application with Communication -1	
S-9	SLO-1	Embedded debugging tools in Keil IDE	SSI interface	Semaphores and implementation	Fixed scheduling	Application layer protocols for embedded systems
	SLO-2	Embedded debugging example with simulation	SSI programming with interrupt	Operations on semaphores	Fixed scheduling	CoAP, MQTT
S-10	SLO-1	Memory management -1	Analog I/O; A/D converter interfacing	Resource sharing	Kahn process networks	Discussions & Reviews
	SLO-2	Memory management -2	OS considerations of I/O devices	Thread Communications	Review	Discussions & Reviews
S 11-12	SLO-1	Lab 3: Practice: C & assembly programming using Keil IDE and kit	Lab 6: Debugging hardware with target board – Analog I/O programming	Lab 9 : Multi threaded application in RTOS, with semaphores	Lab 12: Multi threaded application with Communication -2	Lab 15: Final Lab Examination
	SLO-2					

Learning Resources	<ol style="list-style-type: none"> Jonathan Valvano, "Real time operating systems for ARM Cortex-M Microcontrollers, Embedded systems - Volume 3", ARM Educational Media, 2017. Andrew Sloss et al, "ARM system developers guide", Elsevier, 2004. Quing Li, "Real time techniques for embedded systems", CMP Books, 2003. K.C. Wang, "Embedded and Real time operating systems", Springer, 2017. Theory/Lab Session teaching materials, "RTOS kit", ARM Educational media
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		-	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

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2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	

Course Code	18ECE301J	Course Name	CMOS ANALOG IC DESIGN	Course Category	E	Professional Elective	L	T	P	C
							2	0	2	3

Pre-requisite Courses	18ECC206J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
		1	2	3	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-1 :	Identify Analog IC Design process flow and IC biasing	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3			
CLR-2 :	Analyze the operation and frequency response of CMOS single stage amplifiers																					
CLR-3 :	Analyze operation and frequency response of the Differential amplifiers and Op-amp																					
CLR-4 :	Create insights to the concepts of noises in amplifiers																					
CLR-5 :	Utilize the concepts of oscillators and switched capacitor circuits																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	Identify IC Biasing concepts	2	80	70	H	H	-	-	H	-	-	-	-	-	-	-	-	-	-	-	-	
CLO-2 :	Analyze Single stage amplifiers	2	85	75	H	H	-	-	H	-	-	-	-	-	-	-	-	-	-	-	-	
CLO-3 :	Analyze Differential Amplifiers and Op-amp	2	75	70	H	-	-	H	H	-	-	-	-	-	-	-	-	-	-	-	-	
CLO-4 :	Identify the noises in Amplifiers	2	85	80	H	H	-	-	H	-	-	-	-	-	-	-	-	-	-	-	-	
CLO-5 :	Identify oscillators and switched capacitors circuits	2	85	75	H	-	H	-	H	-	-	-	-	-	-	-	-	-	-	-	-	

Duration (hour)		12	12	12	12	12
S-1	SLO-1	IC Design Philosophy : Introduction to MOSFET scaling	CMOS Single stage Amplifiers: Analog Design Octagon	Differential Amplifier: MOS Differential Pair- Operation with Common mode input	Noise in Amplifiers: Statistical characteristics of noise	Oscillators: General Considerations
	SLO-2	Analog IC design process flow, Typical values of IC MOSFET parameters	Common Source stage with resistive load	Operation with differential input	Statistical characteristics of noise-contrn	Ring oscillators
S-2	SLO-1	IC Biasing: MOSFET current source	CS stage with diode connected load	Small signal operation of MOS differential pair- Differential gain	Types of Noises- Thermal Noise, flicker noise	LC oscillators
	SLO-2	Effect of the output resistance of the current source load	CS stage with current source load	Common mode gain, CMRR	Noise Model- MOSFET, Resistor	Cross coupled oscillators
S-3-4	SLO-1	Lab 1: Basic MOS Circuits: MOSFET as a switch & Inverter using HSPICE	Lab 4: Common source amplifier with resistive load and diode connect load	Lab 7: Differential amplifier	Lab 10: Noise analysis and a measure of noise figure in CS, CG and CD amplifier	Lab 13: Switched capacitor circuits
	SLO-2					
S-5	SLO-1	Basic MOSFET current mirror-operation	CS stage with triode load	Differential amplifier with current source load	Representation of noise in circuits	One port oscillators
	SLO-2	Study on the effects which deviates performance of the current mirror	CS stage with source degeneration	Cascode Differential amplifier	Representation of noise in circuits-Contrn	Colpitt oscillator
S-6	SLO-1	Cascode Current mirror	Source Follower	Frequency response of the differential amplifier	Noise Analysis of CS stage	Voltage Controlled oscillators
	SLO-2	Cascode Current mirror- contrn. and problem solving	Common gate stage	Frequency response of the differential amplifier- contrn..	Noise Analysis of CD stage	Voltage Controlled oscillators-contrn

S 7-8	SLO-1	Lab 2: Basic MOS current mirror, Current mirror circuit to overcome the channel length modulation effect	Lab 5: Common gate amplifier and Source follower	Lab 8: One stage op-amp	Lab 11: Ring oscillator	Lab 14: Pre and Post layout simulation of CMOS inverter using Cadence EDA (Virtuoso tool)
	SLO-2					
S-9	SLO-1	Wilson MOS current mirror	Cascode Amplifier	Multistage Amplifiers: Performance parameters of Op-Amp	Noise Analysis of CG stage	Switched Capacitors circuits: Basic principles
	SLO-2	MOS current steering circuits	Folded Cascode amplifier	One stage op-amp	Noise Analysis of Cascode stage	Sampling switches
S-10	SLO-1	Band gap reference circuits	Frequency response of CS amplifier	Two stage op-amp	Noise Analysis of Differential amplifier	Switched capacitor amplifier
	SLO-2	Band gap reference circuits-contr.	Frequency response of CS amplifier - Contrn	Two stage op-amp with gain boosting	Noise Bandwidth, Noise Figure Concepts	Switched capacitor integrator
S 11-12	SLO-1	Lab 3: Cascode current mirror, Wilson current mirror	Lab 6: Cascode amplifier	Lab 9: Two stage op-amp	Lab 12: Voltage Controlled oscillators	Lab 15: Pre and Post layout simulation of CMOS Amplifier using Cadence EDA (Virtuoso tool)
	SLO-2					

Learning Resources	<ol style="list-style-type: none"> 1. Adel S. Sedra, Kenneth C. Smith, "Microelectronic Circuits-Theory and Applications" – 6th Edition, Oxford University Press, 2011. 2. Behzad Razavi, "Design of Analog CMOS Integrated Circuits", Mc Graw Hill, 2001 3. Allen Holberg, "CMOS Analog Circuit Design", Oxford University Press, 2004 4. Gray, Meyer, Lewis, Hurst, "Analysis and Design of Analog Integrated Circuits", 4th edition, Wiley International, 2002.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Anuj Kumar, Bombardier Transportation, Ahmedabad, kumaranuj.anil@gmail.com	1. Dr. Meenakshi, Professor of ECE, CEG, Anna University, meena68@annauniv.edu	1. Dr. J. Manjula, SRMIST
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	2. Mr. Manikandan AVM, SRMIST

Course Code	18ECE302T	Course Name	MEMS TECHNOLOGIES	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
		1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15			
CLR-1 :	Identify the characteristics and various technology adopted in MEMS fabrication	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3			
CLR-2 :	Understand the electrical and mechanical phenomenon used in MEMS design				H	-	-	-	-	-	-	-	-	-	-	-	M	L	H			
CLR-3 :	Analyze how to apply electrostatic and thermal principles in MEMS components design				H	H	H	-	-	-	-	-	-	-	-	-	M	L	H			
CLR-4 :	Study the application of piezoresistive, piezoelectric principle and the design of microfluidic devices				H	H	H	-	-	-	-	-	-	-	-	-	M	L	H			
CLR-5 :	Classify the application of polymer in MEMS application, also to explore the principle and application of optical, and RF MEMS devices				H	H	-	-	-	-	-	-	-	-	-	-	M	L	H			
CLR-6 :	Study the mechanics of miniaturization, learning various micro fabrication technologies and the application of mechanisms used in MEMS sensor and Actuators design.				H	-	-	-	-	-	-	-	-	-	-	-	M	L	H			
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	Acquire the knowledge of MEMS devices principles and microfabrication techniques	2	75	60	H	M	H										M	L	H			
CLO-2 :	Understand the essential electrical and mechanical concepts of MEMS.	2	75	60	H	H	H	-	-	-	-	-	-	-	-	-	M	L	H			
CLO-3 :	Familiarize about electrostatic and thermal sensing principles and actuating technique.	2	75	60	H	H	H	-	-	-	-	-	-	-	-	-	M	L	H			
CLO-4 :	Attain the knowledge of piezoresistive, piezoelectric and magnetic sensing and actuating technique and microfluidic devices	2	75	60	H	H	-	-	-	-	-	-	-	-	-	-	M	L	H			
CLO-5 :	Be familiar with the polymers material used in MEMS, design and exposure on optical and RF MEMS.	2	75	60	H	-	-	-	-	-	-	-	-	-	-	-	M	L	H			
CLO-6 :	Understand the mechanics of miniaturization, familiar with various micro fabrication technologies and able to design MEMS sensor and Actuators based on the required application.	2	75	60	H	M	H										M	L	H			

Duration (hour)		Introduction to mems and micro fabrication	Electrical and mechanical concepts of mems	Electrostatic and thermal principle sensing and actuation	Piezoresistive, piezoelectric and magnetic principle sensors and actuator	Polymer, optical, rf mems and its application
		9	9	9	9	9
S-1	SLO-1	History of MEMS Development	Conductivity of semiconductors	Electrostatic sensing - Parallel plate capacitor	Piezoresistive sensors -piezoresistive sensor material	Polymers in MEMS- polyimide, SU-8, Liquid crystal polymer (LCP)
	SLO-2		Problems on conductivity of semiconductors	Problems on electrostatic sensing		
S-2	SLO-1	Characteristics of MEMS – Miniaturization,	Crystal plane and orientation- Single crystal Si (FCC, Miller Indices and notation, crystal planes & characteristics, flats & wafer identification)	Electrostatic actuation Parallel plate capacitor	Stress in flexural cantilever and membrane	Polymers in MEMS- PDMS, PMMA , Parylene, Fluorocarbon
	SLO-2	Microelectronics integration - Mass fabrication with precision		Problems on electrostatic actuation		
S-3	SLO-1	Miniaturization and scaling	Stress and strain - definition , Relationship between tensile stress and strain	Electrostatic sensing and actuation- Application - Inertial, pressure and tactile sensor	Piezoelectric sensing and actuation- piezoelectric material properties	Optical MEMS-passive MEMS optical components-lenses-mirrors
	SLO-2	Sensors and Actuators- Energy domains and example devices for each				
S-4	SLO-1	Micro fabrication process - Bulk and Surface Micromachining	Stress and strain - definition , Relationship between tensile stress and strain	Electrostatic sensing and actuation- Application - parallel plate actuator comb drive	Quartz - PZT-	Actuation for active optical MEMS.
	SLO-2				PVDF -ZnO -Applications	

S-5	SLO-1	Silicon based MEMS processes- processing anisotropic wet etching	Flexural beam bending analysis under single loading condition	Problems on electrostatic sensing and actuation	Magnetic actuation- Principles- Deposition of magnetic materials	RF MEMS: Switches
	SLO-2	Isotropic wet etching				
S-6	SLO-1	Dry etching (plasma etching, ion milling, RIE, DRIE)	Types of beam, longitudinal strain under pure bending	Thermal sensing and Actuators- sensors and actuators based on thermal expansion	Design and fabrication of magnetic coil	RF MEMS - Filters, oscillators
	SLO-2	Photolithography,				
S-7		Thin film deposition -sputtering, evaporation,	Deflection of beam- Spring constant	Thermocouples	Microfluidics – Concepts of fluid mechanics	MEMS Packaging
		Thin film deposition - LPCVD, PECVD	Problems: Deflection of beam- Spring constant	Thermal resistors		
S-8	SLO-1	Thin film deposition - sputtering, evaporation, LPCVD, PECVD	Torsional deflection, intrinsic stress	Application of thermal sensors – Inertial, Flow, Infrared.	Microfluidics –Application: Channels, valves	MEMS Testing
	SLO-2	Thin film deposition - plating, spin-on				
S-9	SLO-1	New material and fabrication processing techniques	Resonance and quality factor	Problems on thermal sensing and actuation	Microfluidics – Application valves	Reliability issues in MEMS packaging
	SLO-2	Points of consideration for processing structural and sacrificial material.				

Learning Resources	1. Chang Liu, "Foundations of MEMS", Second Edition, Pearson , 2017	5. Charles P. Poole and Frank J. Owens, "Introduction to Nanotechnology", John Wiley & Sons, 2009.
	2. Tai-Ran Hsu, MEMS & Microsystem Design and Manufacturing, McGraw Hill Education (India) 1 st Edition , 2015.	
	3. Gaberiel M. Rebiz, "RF MEMS Theory, Design and Technology", John Wiley & Sons, 2010.	6. Julian W. Gardner and Vijay K Varadhan, "Microsensors, MEMS and Smart Devices", John Wiley & sons, 2013.
	4. Microsystem Design - by S. Senturia; Publisher: Springer.,	
		7. Fundamentals of Microfabrication - by M. Madou; Publisher: CRC Press; 2 edition.

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

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Course Code	18ECE303T	Course Name	NANOELECTRONIC DEVICES AND CIRCUITS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18ECC102J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
		1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15			
CLR-1 :	Identify the need and effects of device miniaturization	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3			
CLR-2 :	Understand the principles of nano devices																					
CLR-3 :	Learn about new devices at nano scale																					
CLR-4 :	Create insights to the concepts of nano CMOS circuits																					
CLR-5 :	Analyze the design considerations of the circuits																					
CLR-6 :	Utilize the design procedure in circuits																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			H	M	-	M	-	-	-	-	-	-	-	M	-	-	M			
CLO-1 :	Realize the importance of scaling of devices.	2	80	70	H	-	-	M	-	-	-	-	-	-	-	-	M	-	-			
CLO-2 :	Identify the difference of nano devices from conventional devices.	2	85	75	H	-	M	H	H	-	-	-	-	-	-	-	-	-	H			
CLO-3 :	Analyze the performance measures of various devices	2	85	80	H	H	-	-	-	H	L	H	-	-	-	-	-	L	H			
CLO-4 :	Choose appropriate application of the device	2	85	75	H	-	H	H	M	-	-	-	-	-	-	-	-	-	M			
CLO-5 :	Understand the design considerations of nano circuits	2	80	70	H	M	-	-	-	H	L	H	-	-	-	-	M	-	M			
CLO-6 :	Apply the design concepts of nano circuits in real time applications	2	80	70	H	M	-	-	-	H	L	H	-	-	-	-	M	-	M			

Duration (hour)		Introduction to Nano Devices	Silicon MOSFETs- Novel Materials and Alternative Concepts	Nano Devices – Principles and Techniques	Nano- CMOS scaling Problems and Implications	Mixed Signal Circuit Design
		9	9	9	9	9
S-1	SLO-1	MOS transistor- A First Glance at the Device	SOI MOSFET, partially depleted	Classical transport: classical resistance and conductance	Design Methodology in the Nano-CMOS Era	Design Considerations – Device Modeling
	SLO-2	The MOS Transistor under Static Condition	fully depleted SOI	Quantum ballistic transport: quantum Resistance and conductance	Innovations needed to continue performance scaling -	Passive Components
S-2	SLO-1	MOS Transistor Capacitances- Channel Capacitance	Strained channel MOSFET,	Coulomb blockade effect	Sub-100-nm Scaling Challenges- Back-End-of-Line Challenges (Metallization)-	Design Using Thin Oxide Devices – Design Using Thick Oxide Devices
	SLO-2	Junction Capacitance	Hi-k gate dielectric, Metal gate electrode	Single Electron Transistor	Interconnect scaling-copper wire technology	Low-Voltage Techniques
S-3	SLO-1	The Actual MOS Transistor—Some Secondary Effect	Double gate MOSFET	Performance of the single-electron transistor	Low -k dielectric challenges-future global interconnect technologies	Design Procedures
	SLO-2	Challenges in Nanoscale MOSFETs	FinFET	SET technology and Field effect transistors	Front-End-of-Line Challenges (Transistors)-Quantum effects model	Electrostatic Discharge Protection
S-4	SLO-1	Scaling of transistor dimensions	Tunnel Effect	Carbon Nano Tube(CNT)	Polysilicon gate , Metal gate electrodes,	Multiple-Supply Concerns
	SLO-2	Moore's law	Tunneling through a potential barrier	Electronic properties of CNT	Direct tunneling gate leakage-Parasitic capacitance	Noise Isolation
S	SLO-1				Reliability concerns	

5-6	SLO-2	Short Channel Effects (SCE) : Sub-threshold Conduction,	Potential energy profiles for material interfaces	Geometrical structure, Electronic structure of CNT Transport properties		Guard Ring Structures Isolated NMOS Devices
S-7	SLO-1	Drain Induced Barrier Lowering	Metal -insulator, metal -semiconductor	CNTFET, comparison of Si MOSFET with CNTFET	Process Control Reliability	Epitaxial Material versus Bulk Silicon –
	SLO-2	Velocity Saturation, Hot electrons	Metal –insulator -metal junctions	FeFET	Lithographic Issues	Decoupling
S-8	SLO-1	Emergence of new materials,	Tunneling Diode	Principle of Spintronics	Mask Data Explosion	Power Busing
	SLO-2	Hi-k materials and its issues	Resonant Tunneling diode	Spin valves, SpinFET	New Breed of Circuit	Integration Problems
S-9	SLO-1	metal gate, copper interconnect and	Three-terminal resonant tunneling devices	Magnetic Tunnel Junctions	– Physical Design – Modeling Challenges	Corner Regions
	SLO-2	low-k interlayer dielectric	inverter and logic OR gates based on RTD	MRAM	Need for Design Methodology Changes	Neighboring Circuitry

Learning Resources	<ol style="list-style-type: none"> 1. Rainer Waser (Ed.), "Nanoelectronics and Information Technology", Wiley-VCH, Third, Completely Revised and Enlarged Edition, 2012. 2. Jan M. Rabaey, Anantha Chandrakasan, and Borivoje Nikolic, "Digital Integrated Circuits 2nd edition", Pearson, 2000. 3. Ban P. Wong, Anurag Mittal, YuCao, Gren Starr, "Nano- CMOS Circuit and Physical Design", John Wiley and sons Publication, 2005 	<ol style="list-style-type: none"> 4. George W. Hanson, "Fundamentals of Nanoelectronics", Prentice Hall, 20073.Karl Goser, Peter Glösekötter, Jan Dienstuhl, "Nanoelectronics and Nanosystems", Springer, 2004 5. Vladimir V. Mitin, Viatcheslav A. Kochelap, Michael A. Stroscio, "Introduction to Nanoelectronics: Science, Nanotechnology, Engineering, and Applications", Cambridge University Press, 2012
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	40%	-	40%	-	40%	-	40%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	20%	-	20%	-	20%	-	20%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

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Course Code	18ECE304T	Course Name	MICROWAVE INTEGRATED CIRCUITS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18ECC105T	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering		Data Book / Codes/Standards	Nil	

Course Learning Rationale (CLR):		The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1:	Create the insights of microwave circuits		1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Analyze matching networks and filter design		Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3:	Identify and implement amplifiers and oscillators																			
CLR-4:	Layout the types of mixers and control circuits																			
CLR-5:	Utilize techniques to fabricate and measurement of MICs																			
CLR-6:	Analyze and realize microwave circuits and its techniques																			
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																		
CLO-1:	Understand the different types of MICs, different MIC devices and parameters to be used in MICs		2	75	60	H	-	-	-	-	-	-	-	-	-	-	-	-	-	M
CLO-2:	Explore concept of frequency parameters, ZY smith chart, its interpretation in the analysis and design of matching circuits		2	75	60	H	H	H	M	-	-	-	-	-	-	-	-	-	-	M
CLO-3:	Understand the design of Amplifiers and Oscillators		2	75	60	H	H	H	H	-	-	-	-	-	-	-	-	-	-	H
CLO-4:	Explore the different Mixer types and Microwave diodes		2	75	60	H	H	-	M	-	-	-	-	-	-	-	-	-	-	M
CLO-5:	Understand Micro fabrication of MIC devices and measurement techniques of MICs		2	75	60	H	-	-	M	-	-	-	-	-	-	M	-	-	-	H
CLO-6:	Comprehend the MICs, fabrication and measurement of MIC devices		2	75	60	H	H	H	H	-	-	-	-	-	-	M	M	-	-	M

Duration (hour)		Introduction to MIC	Matching Circuits	Microwave Amplifiers and Oscillators	Mixers and Microwave Diodes	MIC Measurement Techniques
		9	9	9	9	9
S-1	SLO-1	Introduction to MICs	Circuit Representation of two port RF/Microwave Networks	Introduction to amplifiers	Introduction to Mixers	Microwave Integrated Circuits : Introduction to SOC, SOP
	SLO-2			Stability considerations in active networks		
S-2	SLO-1	Frequency Bands	Low Frequency Parameters	Gain Consideration in Amplifiers	Mixer Types	MIC Materials.
	SLO-2	Lumped versus Distributed Circuits	High Frequency Parameters			
S-3	SLO-1	Behavior of finite length transmission lines	Transmission Matrix	Noise Consideration in active networks	Conversion Loss	Hybrid versus Monolithic MICs
	SLO-2					
S-4	SLO-1	General Characteristics of PC Boards	ZY Smith Chart	Broadband Amplifier design	SSB Mixers	Multichip Module Technology
	SLO-2			Low Noise Amplifier Design	DSB Mixers	
S-5	SLO-1	Transmission Lines on PC Boards	ZY Smith Chart	Introduction to oscillators	Design of Mixers: Single Ended Mixers	Fabrication Techniques
	SLO-2					
S-6	SLO-1	Passives made from Transmission Lines	Design of Matching Circuits using Lumped Elements	Oscillator versus Amplifier Design	Single Balanced Mixers	Miniaturization techniques
	SLO-2					
S-7	SLO-1	Resonators	Design of Matching Circuits using Lumped Elements	Oscillation conditions	Sub Harmonic Diode Mixers	Test fixture measurements
	SLO-2		Matching Network Design using Distributed Elements			
S-8	SLO-1	Combiners and Splitters	Matching Network Design using Distributed Elements	Design and stability considerations of Microwave Transistor Oscillators.	Microwave Diodes	probe station measurements
	SLO-2					
S-9	SLO-1	Couplers	Filter design		Phase Shifters and PIN	thermal and cryogenic measurements

SLO-2			Design and stability considerations of Microwave Transistor Oscillators.	Diode Attenuators	
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Learning Resources	1. Thomas H.Lee, "Planar Microwave Engineering", Cambridge University Press, 2004 2. Matthew M. Radmanesh, "Radio Frequency and Microwave Electronics", Pearson Education, II Edition 2002 3. Guillermo Gonzalez, "Microwave Transistor Amplifiers – Analysis and Design", II Edition, Prentice Hall, New Jersey. 4. Ravender Goyal, "Monolithic MIC; Technology & Design", Artech House, 1989. 5. Gupta K.C. and Amarjit Singh, "Microwave Integrated Circuits", John Wiley, New York, 1975.	6. Hoffman R.K. "Handbook of Microwave Integrated Circuits", Artech House, Boston, 1987. 7. Ulrich L. Rohde and David P.N., "RF / Microwave Circuit Design for Wireless Applications", John Wiley, 2000. 8. C. Gentili, "Microwave Amplifiers and Oscillators", North Oxford Academic, 1986. 9. Samuel. Y. Liao, "Microwave Circuit Analysis and Amplifier Design", Prentice Hall. Inc., 1987.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

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Course Code	18ECE305J	Course Name	INTRODUCTION TO ARM -SOC	Course Category	E	Professional Elective	L	T	P	C
							2	0	2	3

Pre-requisite Courses	18ECE204J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)															
CLR-1 :	Study the hardware architecture of ARM Cortex-M core				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLR-2 :	Study the AHB (high speed bus) and peripherals							Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3	
CLR-3 :	Study the AHB (high speed bus) and peripherals																						
CLR-4 :	Program high speed peripherals																						
CLR-5 :	Study APB bus and peripherals. Designing applications with CMSIS																						
CLR-6 :	Understand and learn to use ARM Cortex-M processor architecture, and deice level programming.																						
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																					
CLO-1 :	Explain hardware and register architecture of ARM Cortex-M based processors				2	80	70																
CLO-2 :	Explain AHB and its signals, and program high speed peripherals				3	80	70		M	H	L	H							H			M	
CLO-3 :	Understand AHB and its signals and program high speed peripherals				3	80	70		H	H	L	H							H			M	
CLO-4 :	Program high speed peripherals with case study.				3	80	60		M	H		H							M				
CLO-5 :	Program device driver and create libraries.				3	80	60		M	H		M							M				
CLO-6 :	Perform system programming of ARM Cortex-M based processor.				3	80	60		M	H	L	H							M				

Duration (hour)	ARM Cortex-M architecture	ARM Internal bus	ARM peripherals	SOC programming	Case studies
	12	12	12	12	12
S-1	SLO-1 Introduction to Programmable SoC	AMBA 3 AHB Lite architecture	AHB UART peripheral	Programming an SOC using C language	Graphics LCD interfacing
	SLO-2 Introduction to Programmable SoC	AMBA 3 AHB Lite architecture	AHB UART peripheral	Programming an SOC using C language	Graphics LCD interfacing
S-2	SLO-1 ARM architecture	AMBA 3 AHB Lite architecture	AHB UART peripheral	APB Bus	Board support package
	SLO-2 ARM architecture	AMBA 3 AHB Lite architecture	AHB UART peripheral	APB Bus	Board support package
S	SLO-1 Lab-1: ARM Keil IDE usage – sample ARM program.	Lab 4: Study of AHB peripheral	Lab 7: Multinode I2C Bus	Lab 10: Making a device driver	Lab 13: Case study – 2
3-4	SLO-2				
S-5	SLO-1 ARM Register architecture	AHB SRAM controller	AHB timer	ARM CMSIS	Ethernet interfacing
	SLO-2 ARM Register architecture	AHB SRAM controller	AHB timer	ARM CMSIS	Ethernet interfacing
S-6	SLO-1 ARM assembly language	AHB SRAM controller	AHB-APB bridge	Device drivers	Ethernet interfacing
	SLO-2 ARM assembly language	Review and discussions	AHB-APB bridge	Device drivers	Ethernet interfacing
S	SLO-1 Lab 2: Assembly language programming of ARM processor using Keil IDE	Lab 5: ARM memory management	Lab 8: Application of timers	Lab 11: Using CMSIS	Lab 14: Model lab examination
7-8	SLO-2				
S-9	SLO-1 ARM Cortex-M Architecture -1	AHB VGA peripheral	Fast GPIO programming	Application programming	Student Seminar / discussions
	SLO-2 ARM Cortex-M Architecture -1	AHB VGA peripheral	Fast GPIO programming	Application programming	Student Seminar / discussions
S-10	SLO-1 ARM Cortex-M Architecture -2 (pipelines)	AHB VGA peripheral	Interrupt mechanism of ARM	Case study - 1	Student Seminar / discussions
	SLO-2 ARM Cortex-M Architecture -2	AHB VGA peripheral	Interrupt mechanism of ARM	Case study - 2	Student Seminar / discussions
S	SLO-1 Lab 3: Parallel port programming	Lab 6: Graphics application	Lab 9: Experimenting Interrupts, Timers	Lab 12: Study of USB interface	Lab 15: Final lab examination
11-12	SLO-2				

Learning Resources	1. Steve Furber, "ARM System on a Chip Architecture – 2 nd Edition", Pearson Education, 2000. 2. "AMBA -3 APB Protocol", ARM Limited, 2003. 3. "AMBA -3 AHB Lite Protocol", ARM Limited, 2003.	4. Theory/Lab teaching materials, "Introduction to SoC kit", ARM Education media, 2018.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		-	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Anuj Kumar, Bombardier Transportation, Ahmedabad, kumaranuj.ani@gmail.com	1. Dr. Meenakshi, Professor of ECE, CEG, Anna University, meena68@annauniv.edu	1. Prof. V. Natarajan, SRMIST
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	2.

Course Code	18ECE306J	Course Name	ARM BASED DIGITAL SIGNALS PROCESSING	Course Category	E	Professional Elective	L	T	P	C
							2	0	2	3

Pre-requisite Courses	18ECE204J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand the concepts of DSP, discrete time signals and its properties.	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Understand applications of transforms in solving digital signal processing	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Study FIR filters																		
CLR-4 :	Study IIT filters																		
CLR-5 :	Understand the usage of adaptive filter techniques																		
CLR-6 :	Understand the usage of DSP in embedded ARM Cortex-M processor platform																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Apply theory and application of discrete time signals	3	80	70		M	-	-	M	-	-	-	-	-	-	-	H	-	L
CLO-2 :	Apply theory and implementing methods of Z-transforms, DFT and FFT.	3	80	70		H	-	-	M	-	-	-	-	-	-	-	H	-	L
CLO-3 :	Apply FIR filter theory and processor implementation in C.	3	80	70		H	-	-	M	-	-	-	-	-	-	-	H	-	L
CLO-4 :	Apply IIR filter theory and processor implementation in C	3	80	60		H	-	-	M	-	-	-	-	-	-	-	H	-	L
CLO-5 :	Implement adaptive filter design theory, methods and its uses.	2	80	60		H	-	-	L	-	-	-	-	-	-	-	H	-	L
CLO-6 :	Apply the theory and implementation aspects of DSP in ARM Cortex-M based processor platform.	3	80	60		H	-	-	M	-	-	-	-	-	-	-	H	-	L

Duration (hour)		Basics of digital signals	Transforms for DSP	FIR filters	IIR filters	DSP applications
		12	12	12	12	12
S-1	SLO-1	DT Signals-basics properties & Operations on DT signals	Z-Transform Properties	Design of Finite Impulse Response Filters-Symmetric and Antisymmetric FIR filters	Frequency Response and Characteristics of Analog Filters	Introduction-Steepest Descent Method-Least Mean Squares Method
	SLO-2	DT Signals-basics properties & Operations on DT signals	Z-Transform Properties	Design of Finite Impulse Response Filters-Symmetric and Antisymmetric FIR filters	Frequency Response and Characteristics of Analog Filters	Introduction-Steepest Descent Method-Least Mean Squares Method
S-2	SLO-1	DT systems-Properties of DT Systems – LTI system	Inverse Z-Transform-solving Difference Equation	Design of Linear- Phase FIR filters Using window methods	IIR Filter Design by Impulse Invariance	Adaptive Filters: Prediction and System Identification
	SLO-2	DT systems-Properties of DT Systems – LTI system	Inverse Z-Transform-solving Difference Equation	Design of Linear- Phase FIR filters Using window methods	IIR Filter Design by Impulse Invariance	Adaptive Filters: Prediction and System Identification
S-3-4	SLO-1	Lab 1: Introduction- Keil MDK-ARM application development Environment.	Lab 4: LTI System Implementation	Lab 7: Filter Structures in the CMSIS-DSP Library	Lab 10: IIR Filter Structures in the CMSIS-DSP Library	Lab 13: CMSIS Implementation of the LMS and Normalized LMS methods
	SLO-2					
S-5	SLO-1	Convolution and Correlation	DFT-review; problems	Design of Linear- Phase FIR filters Using window methods	Design of Butterworth filter using Bilinear Transformation	Adaptive Filters: Equalization and Noise Cancellation
	SLO-2	Convolution and Correlation	DFT-review; problems	Design of Linear- Phase FIR filters Using window methods	Design of Butterworth filter using Bilinear Transformation	Adaptive Filters: Equalization and Noise Cancellation
S-6	SLO-1	CT-to DT Conversion Sampling Theorem in the Time Domain	DIT-FFT Radix 2 butterfly derivation - problems	Design of Optimum Equiripple Linear-Phase FIR filters	Chebyshev Filter Designs based on the Bilinear Transformation	Adaptive Filters: Adaptive FIR Filter
	SLO-2	CT-to DT Conversion Sampling Theorem in the Time Domain	DIT-FFT Radix 2 butterfly derivation - problems	Design of Optimum Equiripple Linear-Phase FIR filters	Chebyshev Filter Designs based on the Bilinear Transformation	Adaptive Filters: Adaptive FIR Filter
S-7-8	SLO-1	Lab 2: Digital Signals-operations on Digital Signals	Lab 5: Calculating the DFT-FFT	Lab 8: FIR Filter Design	Lab 11: IIR Filter Design	Lab 14: Model Practicals
	SLO-2					

S-9	SLO-1	Sampling Theorem in the Frequency Domain-Aliasing	Filtering in the FD-Circular & Convolution	Design of Optimum Equiripple Linear-Phase FIR filters	Chebyshev Filter Designs based on the Impulse Invariance	Review, Problems and Discussions
	SLO-2	Sampling Theorem in the Frequency Domain-Aliasing	Filtering in the FD-Circular & Convolution	Design of Optimum Equiripple Linear-Phase FIR filters	Chebyshev Filter Designs based on the Impulse Invariance	Review, Problems and Discussions
S-10	SLO-1	Reconstruction in the Frequency Domain & time Domain	Filtering in the FD-Linear Convolution	Filter Design using Software	Filter Design using Software	Review, Problems and Discussions
	SLO-2	Reconstruction in the Frequency Domain & time Domain	Filtering in the FD-Linear Convolution	Filter Design using Software	Filter Design using Software	Review, Problems and Discussions
S-11-12	SLO-1	Lab 3: A-D & D-A conversion-Changing the Sampling Frequency	Lab 6: Filtering in the Frequency Domain	Lab 9: Implementing a FIR Filter using Different Structures	Lab 12: Implementing a Filter using Different Structures	Lab 15: University practicals
	SLO-2					

Learning Resources	1. Cem Unsalan, M. Yerkun Yuccel, H. Deniz Gurham, "Digital Signal Processing Using ARM Cortex-M based microcontrollers, Theory and Practice", ARM Education Media, 2018.	2. Theory/Lab teaching materials, ARM Educational Media.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
Level 3	Analyze	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Evaluate										
	Create										
	Total	100 %		100 %		100 %		100 %		-	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

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2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	2. Mr. U. Hari, SRMIST

Course Code	18ECE307J	Course Name	APPLIED MACHINE LEARNING	Course Category	E	Professional Elective	L	T	P	C
							2	0	2	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Understanding the Machine Learning concept and types				Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Analyze the ML algorithm performance by Learning Curve and error																							
CLR-3 :	Applying ML algorithm for solving practical problems																							
CLR-4 :	Create insights to the concepts and programming of supervised and unsupervised ML methods																							
CLR-5 :	Analyze and understand the working principle and model development of Evolutionary Learning																							
CLR-6 :	Create insights to the concepts and programming of Reinforcement learning																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1 :	Apply Genetic Algorithm for evaluational learning				2	80	70	H	H	H	-	-	-	-	-	-	-	-	-	-	-	-	-	H
CLO-2 :	Analyze Reinforcement learning				2	85	75	H	H	-	-	H	H	-	-	-	-	-	-	-	-	-	-	H
CLO-3 :	Apply linear model of linear regression and SVM for classification problem				2	75	70	H	H	H	H	-	-	-	-	-	-	-	-	-	-	H	-	H
CLO-4 :	Apply neural network and CNN for classification problem				2	85	80	H	H	H	H	H	-	-	-	-	-	-	-	-	-	H	-	H
CLO-5 :	Apply Decision Trees , clustering For classification problem				2	85	75	H	H	H	H	H	-	-	-	-	-	-	-	-	-	H	-	H
CLO-6 :	Apply probability model of Bayesian decision theory and HMM for classification problem				2	80	70	H	H	H	H	H	-	-	-	-	-	-	-	-	-	H	-	H

Duration (hour)		Introduction to Machine Learning and Linear Model	Multilayer Perceptrons and Decision Tree	Clustering, SOM and HMM	Bayes Network, Reinforcement Learning and CNN	Genetic Algorithm and Application of ML
		12	12	12	12	12
S-1	SLO-1	Introduction to Machine learning: Types of Machine Learning - Supervised Learning – Unsupervised, Learning	Multilayer, Perceptrons	Clustering	Bayesian decision theory	The Genetic Algorithm
	SLO-2	reinforcement learning, The Curse of dimensionality	Multilayer, Perceptrons	K-Means clustering	Bayesian decision theory	The Genetic Algorithm
S-2	SLO-1	Bias and Variance, Learning Curve	Multilayer, Perceptrons	Hierarchical clustering	Bayesian estimation	Facial Expression Recognition
	SLO-2	Classification, Error and noise, linear regression	Multilayer, Perceptrons	Agglomerative clustering	Bayes network	Human Emotion Research
S-3,4	SLO-1	Lab 1: Linear Regression	Lab 4: Multilayer, Perceptrons	Lab 7: K-Means clustering	Lab 10: Bayes Network	Lab 13: Genetic Algorithm
	SLO-2					
S-5	SLO-1	Support Vector Machines	example of using MLP	Vector Quantization	Reinforcement learning	Facial Expression Recognition System
	SLO-2	Support Vector Machines	example of using MLP	Vector Quantization	Reinforcement learning	Facial Expression Recognition System
S-6	SLO-1	Support Vector Machines	example of using MLP	The Self-Organizing Feature Map	Reinforcement learning	Speech Emotion Recognition
	SLO-2	Support Vector Machines	example of using MLP	The Self-Organizing Feature Map	Reinforcement learning	Speech Emotion Recognition
S-7,8	SLO-1	Lab 2: Support Vector Machines	Lab 5: MLP application	Lab 8: SOFM	Lab 11: Reinforcement learning	Lab 14: Speech Emotion Recognition
	SLO-2					Basic classification

S-9	SLO-1	basics of neural network	Decision Trees- classification	HMM	Understanding Convolutions	Neural Network Multi-Layer Perceptron Modeling For Surface Quality Prediction in Laser Machining
	SLO-2	Perceptrons	regression tree,	HMM	Understanding Convolutions	
S-10	SLO-1	LINEAR SEPARABILITY	pruning, rule from tree and data	HMM	CNN Building Blocks	Machine Learning in Cybersecurity- Supervised Learning for Misuse/Signature Detection
	SLO-2	Perceptrons and introduction to Multiplayer, Perceptrons	multivariate tree	HMM	CNN Building Blocks	Machine Learning in Cybersecurity- Supervised Learning for Misuse/Signature Detection
S-11,12	SLO-1	Lab 3: Perceptrons	Lab 6: Decision Trees	Lab 9: HMM	Lab 12: CNN	Lab 15: Mini project

Learning Resources	1. Ethem Alpaydin, "Introduction to Machine Learning", 3 rd edition, MIT Press, 2014. 2. Stephen Marsland, "Machine Learning –An Algorithmic Perspective", 2 nd edition, CRC Press, 2015. 3. Sumeet Dua and Xian Du, "Data Mining and Machine Learning in Cybersecurity", CRC Press, 2011. 4. Aurélien Géron Hands-On Machine Learning with Scikit-Learn and TensorFlow: Concepts, Tools, and Techniques to Build Intelligent Systems. O'Reilly Media, 2017.	5. Yagang Zhang, "Application of Machine Learning", Published by In-Tech, 2010. 6. Starter Bundle, "Deep Learning: A Practitioner's Approach", O'Reilly Media, 2017. 7. Dr. Adrian Rosebrock, "Deep Learning for Computer Vision with Python", Packt Publisher, 2018. 8. Ankur A Patel, "Hands-On Unsupervised Learning Using Python: How to Build Applied Machine Learning Solutions from Unlabeled Data", O'Reilly media, 2019.
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Learning Assessment"											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

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2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	

Course Code	18ECE220T	Course Name	ADVANCED MOBILE COMMUNICATION SYSTEMS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18ECC301T	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1:	Gain knowledge about the latest Standards from 3G to 5G systems.	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2:	Introduce the concepts of OFDM systems and standards.	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3:	Study the basics of MIMO system and the impact of different channel models on it.	Expected Proficiency (%)	Problem Analysis
CLR-4:	Understand the techniques of cognitive radio spectrum sensing and sharing	Expected Attainment (%)	Design & Development
CLR-5:	Study the techniques of Millimeter wave Communication		Analysis, Design, Research
CLR-6:	Apply the knowledge gained to various Advanced Mobile Communication Systems		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
			H - M - M - - - - - - - - - - H - M
			M - - H M - - - - - - - - - - M - H
			H - M H - - - - - - - - - - M - H
			M - - M - - - - - - - - - M - H
			M - M H - - - - - - - - - - M - H
			M - M H - - - - - - - - - - M - H

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	
CLO-1:	Apply the architecture and functionalities of 3G and 4G systems	2,3 85 80
CLO-2:	Understand the concepts of OFDM and it issues	2,3 80 85
CLO-3:	Understand the MIMO Communication systems	2,3 85 80
CLO-4:	Understand the principle of Cognitive Radio Techniques	2,3 80 75
CLO-5:	Acquire the concept of millimeter wave Communication	2,3 85 80
CLO-6:	Able to analyze the Advance Mobile Communication systems	2,3 85 80

Duration (hour)	Advanced cellular mobile Communication systems	Multicarrier modulation technique-OFDM	MIMO systems	Cognitive Spectrum management	Millimeter wave Communication
	9	9	9	9	9
S-1	SLO-1 Overview of the legacy 3GPP cellular systems	Introduction to OFDM	Introduction to MIMO	Cognitive transceiver Introduction	Millimeter Wave Characteristics
	SLO-2 Overview of the legacy 3GPP cellular systems	Multicarrier Modulation Introduction	Introduction to MIMO Channel Capacity	Cognitive transceiver architecture	Introduction to Channel Performance at Mm wave Communication
S-2	SLO-1 WiMAX systems: Introduction	Multicarrier Modulation	MIMO Channel Estimation	Interweaving	Channel Performance at Mm wave Communication
	SLO-2 WiMAX systems: Architecture	Cyclic Prefix	MIMO Channel Estimation	Principle of interweaving	Modulation for Millimeter Wave Communication
S-3	SLO-1 WiMAX systems: Architecture	Channel model	MIMO Spatial Multiplexing	Principle of interweaving	Modulation for Millimeter Wave Communication
	SLO-2 WiMAX systems : Frame structure	SNR	MIMO Spatial Multiplexing	Introduction to Spectrums	Millimeter wave transmitter
S-4	SLO-1 WiMAX systems : Frame structure	SNR Performance	V- BLAST 2	Types of Spectrum	Millimeter wave Receiver
	SLO-2 WiMAX systems : Applications	SNR Problems	V- BLAST 2	Spectrum sensing	Millimeter wave Antenna
S 5-6	SLO-1 LTE systems: Introduction	OFDM Introduction	MIMO Diversity	Advantages of Spectrum sensing	Introduction Mm wave Communications
	SLO-2				

S-7	SLO-1	LTE systems: Architecture	OFDM Issues	MIMO Diversity	Disadvantages of Spectrum sensing	Emerging applications of Mm wave Communications
	SLO-2	LTE systems: Architecture	OFDM Issues	Alamouti	Disadvantages of Spectrum sensing	Emerging applications of Mm wave Communications
S-8	SLO-1	LTE systems: Frame structure	PAPR	Alamouti	Spectrum Management	Millimeter Wave Standards.
	SLO-2	LTE systems: Frame structure	Frequency and timing	OSTBC	Spectrum Management	Introduction to Millimeter Wave Standards.
S-9	SLO-1	LTE systems: applications	Frequency offset issues.	MIMO :OFDM system Introduction	Spectrum Management	Development of Millimeter Wave Standards.
	SLO-2	LTE systems: applications	Timing offset issues.	MIMO :OFDM system	Spectrum Management	Development of Millimeter Wave Standards.

Learning Resources	1. Andrea Molisch, "Wireless Communication", Cambridge University Press, 2 nd edition, 2013.	5. Arslan, Hüseyin, ed. Cognitive radio, software defined radio, and adaptive wireless systems. Springer Science & Business Media, 2007.(263-284)
	2. Theodore Rappaport, "Wireless Communication: Principle and Practice", Prentice Hall, 2 nd edition, 2014.	6. Thomas W.Rondeau, Charles W. Bostain, "Artificial Intelligence in Wireless Communication", ARTECH HOUSE .2009 {pp1-51}
	3. Kao-Cheng Huang, Zhaocheng Wang, "Millimeter Wave Communication System", Wiley-IEEE Press, 2 nd edition, 2011.	7. Andrew Goldsmith, Wireless Communications, Cambridge University Press, 2005.
	4. EzioBigleri, "MIMO Wireless Communications", Cambridge University Press, 1 st edition, 2007.	8. Mischa Dohler, Jose F. Monserrat Afif Osseiran " 5G Mobile and Wireless Communication Technology", Cambridge University Press 2016.

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

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		Internal Experts
		1. Dr. Sabitha Gauni, SRMIST

Course Code	18ECE221T	Course Name	RADAR AND NAVIGATIONAL AIDS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Get introduced to basics of Radar System	1	2	3	Learning (Bloom)	Efficiency (%)	Assessment (%)	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2 :	Impart the knowledge of different types of Radar							Knowledge	Analysis	Development	Design, Research	Usage	Culture & Sustainability	Team Work	Communication	Finance & Economics	Innovation							
CLR-3 :	Analyze the various detection schemes																							
CLR-4 :	Understand the Radar transmitters and Receivers																							
CLR-5 :	Understand the fundamentals of navigation system																							
CLR-6 :	Acquire knowledge on theoretical concepts and analysis techniques related to different types of Radar and various navigational aids																							

Duration (hour)		Introduction To Radar Equation	MTI And Pulse Doppler Radar	Detection Of Signals In Noise	Radar Transmitter And Receiver	Radio Navigation
		9	9	9	9	9
S-1	SLO-1	Introduction-Basic Radar	Introduction to Doppler Radar	Detection of Signals in Noise -Detection Criteria	Radar Transmitters and Receivers.	Introduction - Four methods of Navigation - Positioning- Errors in Direction Finding
	SLO-2	Radar Frequencies -Applications of Radar	Introduction to MTI Radar	Probabilities of Detection and False Alarm	Linear Beam Power Tubes-Reflex Klystron	Line of sight Distance measurement
S-2	SLO-1	The Simple form of Radar Equation	Delay –Line Cancellers	Matched Filter Receiver	Linear Beam Power Tubes-TWT	Terrestrial Radio Navigation systems
	SLO-2	Tutorials	Delay –Line Cancellers	Derivation of Matched filter frequency response	Solid State RF Power Sources	Radio transmission and Reception
S-3	SLO-1	Radar Block Diagram	Doppler Filter Banks	Automatic Detector	Magnetron - Crossed Field Amplifiers	System design considerations-System Performance Parameters
	SLO-2	Receiver Noise	Digital MTI Processing	Constant-False-Alarm Rate Receivers	Magnetron - Crossed Field Amplifiers	The Loop Antenna - Adcock Direction Finders
S-4	SLO-1	Signal-to-Noise Ratio	Block Diagram of Digital MTI Doppler Signal Processor	Signal Management	Other RF Power Sources	Direction Finding at Very High Frequencies - Automatic Direction Finders
	SLO-2	Integration of Radar Pulses	Moving Target Detector - Limitations to MTI Performance	Propagation Radar Waves- Atmospheric Refraction	Other aspects of Radar Transmitter	VHF Omni Directional Range(VOR) - VOR Receiving Equipment - Range and Accuracy of VOR
S-5	SLO-1	Radar Cross Section of Targets-Simple Targets	Pulse Doppler Radar	Standard propagation	The Radar Receiver	Hyperbolic Systems of Navigation-Loran

	SLO-2	Radar Cross Section of Targets-Complex Targets Transmitter Power	High, Medium and Low prf Doppler	Nonstandard Propagation	Receiver noise Figure	Loran-C
S-6	SLO-1	Radar cross Section Fluctuations	Other Doppler Radar Topics	Ambiguity Diagram	Receiver noise Figure	The Decca Navigation System -Decca Receivers
	SLO-2	Swerling Target Model	Tracking with Radar	Ambiguity Diagram	Super heterodyne Receiver	Range and Accuracy of Decca
S-7	SLO-1	Transmitter Power	Mono pulse Tracking	Pulse compression	LNA and Mixers	TACAN
	SLO-2	Pulse Repetition Frequency	Two Coordinate amplitude comparison monopulse tracking	Linear FM pulse compression	Duplexers	TACAN Equipment
S-8	SLO-1	Antenna Parameters	Conical Scan and Sequential Lobing	Binary Phase Coded pulse compression	Receiver Protectors	Case study on Airborne Tactial networks-Instrument Landing System
	SLO-2	System losses-Microwave plumbing loss, Antenna loss, Signal Processing loss	Limitations to Tracking Accuracy	Questionnaire	Receiver Protectors	Case study on Airborne Tactial networks-Instrument Landing System
S-9	SLO-1	System losses-Doppler processing, Collapsing, Operator loss, propagation Effects	Case study on weather radars	Introduction to clutter	Radar Displays	Introduction to satellite Radio Navigation-
	SLO-2	Other Radar Equation Considerations	Case study on weather radars	Surface Clutter Radar equation	Surprise Test	Navstar Global Positioning System (GPS)

Learning Resources	<ol style="list-style-type: none"> 1. Merrill I. Skolnik, "Introduction to Radar Systems", 3rd Edition Tata Mc Graw-Hill 2008 2. R.B. Underdown and David Cockburn, "Ground Studies for Pilots: Radio Aids", sixth Edition, Blackwell Publishing, 2011. 3. Myron Kayton, Walter R.Fried, "Avionics Navigation Systems", second Edition, Wiley- India Edition, 2010. 4. N.S.Nagaraja, "Elements of Electronic Navigation Systems", 2nd Edition, TMH, 2000. 5. Mark, Richards.A, "Fundamentals of radar signal processing", Mc-Graw Hill, Electronic Engineering, 1st Edition, 2005. 6. Jenny L. Reed, Aaron D. Lanterman, John M. Trostel, " Tutorial: Weather Radar: Operation and Phenomenology", IEEE Aerospace and Electronic Systems Magazine, Vol: 32, 7, 2017. 7. Bow-Nan Cheng, Frederick J. Block, B. Russ Hamilton, David Ripplinger, Chayil Timmerman, Leonid Veytser, and Aradhana Narula-Tam, " Design Considerations for Next-Generation Airborne Tactical Networks, IEEE Communications Magazine , May 2014.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Anuj Kumar, Bombardier Transportation, Ahmedabad, kumaranuj.anii@gmail.com	1. Dr. Meenakshi, Professor of ECE, CEG, Anna University, meena68@annauniv.edu	1. Mrs. S. Vasanthadev Suryakala, SRMIST
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	

Course Code	18ECE223T	Course Name	SATELLITE COMMUNICATION AND BROADCASTING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18ECC205J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1:	Understand the orbital and functional principles of satellite Communication systems	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2:	Architect, interpret, and select appropriate technologies for implementation of specified satellite Communication systems	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3:	Analyze and evaluate a satellite link and suggest enhancements to improve the link performance	Expected Proficiency (%)	Problem Analysis
CLR-4:	Select appropriate modulation, multiplexing, coding and multiple access schemes for a given satellite Communication link	Expected Attainment (%)	Design & Development
CLR-5:	Specify, design, prototype and test analog and digital satellite Communication systems as per given specifications		Analysis, Design, Research
CLR-6:	Utilize the concepts in optical Communication for the understanding of engineering and technology		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1:	Understand the principles, concepts and operation of satellite Communication systems	2 80 70	H H M H H L L L M H L M H - -
CLO-2:	Gain the knowledge of Satellite orbits and launching, link design, link availability and perform interference calculations	2 85 75	H H M H H L L L M H L M H - -
CLO-3:	Analyze the concepts of Satellite systems in relation to other terrestrial systems	2 75 70	H H M H H L L L L H L M H - -
CLO-4:	Evaluate the performance of various channel access schemes	2 85 80	H H M H H L L L L H L M H - -
CLO-5:	Familiarize with applications of satellites and compression standards	2 85 75	H H M H H L L L L H L M H - -
CLO-6:	Apply their idea in Satellite Communication module	2 80 70	H H M H H L L L L M H L M H - -

Duration (hour)	Satellite Orbit	Link Design	Space and Earth Segment	Multiple Access Techniques for Satellite Communication	Broadcast and Services
	9	9	9	9	9
S-1	SLO-1 Satellite Orbit	Link Design	Space Segment	Concepts of Multiple Access techniques, types	Concept of Broadcasting satellites
	SLO-2 Kepler's law	EIRP	Basic concept of space segmen	Single Access	Direct Broadcasting Satellite
S-2	SLO-1 Earth - Orbiting satellites terms	Transmission Losses	Power Supply	Pre assigned FDMA	Orbital Spacing
	SLO-2 Types of satellites	Link Power Budget equation	Altitude control	Demand Assigned FDMA	Power ratings
S-3	SLO-1 Orbital elements	System Noise	Station keeping	SPADE system	Frequency and polarization
	SLO-2 Orbit Perturbations	Carrier to noise ratio	Thermal Control	TWT amplifier operation	Transponder Capacity
S-4	SLO-1 Inclined Orbits	Types of FEC	TT&C Subsystems	Downlink analysis	Bit rate
	SLO-2 Sun synchronous orbits	Computer-Aided Design	Antenna subsystem	TDMA	MPEG
S-5	SLO-1 Constellation:Geo stationary satellites	Uplink	Transponders	Reference bursts	Forward Error Correction
	SLO-2 Non geostationary constellation	saturation flux density, input backoff	Wideband Receiver	Preamble, Postamble	Outdoor Unit
S-6	SLO-1 Launching of Geostationary satellites	Down Link	Earth Segment	Carrier recovery	Indoor Unit
	SLO-2 Launch vehicle Types	output backoff, TWTA output	Basic concept of Earth segment	Network synchronization	Downlink Analysis
S-7	SLO-1 Antenna Look angles	Effects of rain	Receive only home TV system	Pre assigned TDMA	Uplink Analysis
	SLO-2 Sun transit outage	Inter modulation Noise	Community antenna TV system	Demand assigned TDMA	Satellite Mobile services
S-8	SLO-1 Solving Problems	Solving Problems	Solving Problems	CDMA	VSAT
	SLO-2 Solving Problems	Solving Problems	Solving Problems	Direct Sequence Spread Spectrum, CDMA throughput	GPS
S-9	SLO-1 Solving Problems	Solving Problems	Solving Problems	Solving Problems	Solving Problems
	SLO-2 Solving Problems	Solving Problems	Solving Problems	Solving Problems	Solving Problems

Learning Resources	1. Dennis Roddy, "Satellite Communications", Tata Mc-Graw Hill Publications, 4th Edition, 13th Reprint, 2014 2. TIMOTHY PRATT, CHARLES BOSTIAN JERMEY ALLNUTT, Satellite Communications, John Wiley, Singapore, 2nd Edition, reprint 2013.	3. MadhavendraRichharia, Leslie David, "Satellite Systems for Personal Applications Concepts and Technology", Wiley-Blackwell, 1st Edition, 2010. 4. Louis J. Ippolito Jr, "Satellite Communications Systems Engineering", John Wiley and Sons, Ltd, Publication, 1st Edition, 2008
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

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2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	

Course Code	18ECE225T	Course Name	INFORMATION THEORY AND CODING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18MAB203T	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering			Data Book / Codes/ Standards	Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)															
CLR-1:	Introduce source coding in information theory	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14		
CLR-2:	Impart the fundamentals of error control coding techniques and their applications																						
CLR-3:	Address the noisy channel coding problem																						
CLR-4:	Assess the performance of both block and convolutional coding schemes in different practical situations																						
CLR-5:	Derive Shannon's fundamental channel capacity results																						
CLR-6:	Know about channel and impairments channel and how to mitigate them																						
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																					
CLO-1:	Comprehend various source coding schemes	2	80	70	-	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-		
CLO-2:	Apply variable length codes for source coding	2	85	75	-	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-		
CLO-3:	Apply linear block codes for error detection and correction	2	75	70	-	H	-	-	-	-	-	-	-	-	-	-	-	-	-	H	-		
CLO-4:	Apply convolution codes for performance analysis & cyclic codes for error detection and correction.	2	85	80	-	H	-	-	-	-	-	-	-	-	-	-	-	-	-	H	-		
CLO-5:	Design the channel performance using Information theory	2	85	75	-	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-		
CLO-6:	Analyse any type of channel and select coding techniques to improve channel performance	2	85	75	-	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-		

Duration (hour)		Source coding	Variable-Length Codes	Error Detecting and Error Correcting Codes	Convolutional Codes	Entropy and Channel Capacity
		9	9	9	9	9
S-1	SLO-1	Introduction to Information theory	Unique decoding	Hamming codes Generation	Convolutional codes introduction	Entropy
	SLO-2	Model of signaling system	Rules and construction of Unique decoding	Hamming code checking	Convolutional codes generation	Mathematical properties
S-2	SLO-1	Block Diagram	Instantaneous codes	Hamming weight	Convolutional encoder	Entropy and coding
	SLO-2	Mathematical models for information sources	Construction of Instantaneous codes	Hamming distance	Encoder for different rates	System entropies
S-3	SLO-1	Encoding a source alphabet	The Kraft's inequality	Minimum distance decoding	code tree formation	Mutual information
	SLO-2	Source coding	Shortened block codes	Linear block codes Generator polynomial	code tree formation	Example Problem solving- Mutual information
S-4	SLO-1	ASCII code	The McMillan's Inequality	Linear block codes Generation	state diagram generation	Shannon-Fano coding
	SLO-2	Code Formation for an information	Huffman codes	Linear block codes Decoding	state diagram generation for different rates	Example Problem solving- Shannon-Fano coding
S-5	SLO-1	Radix r code	Huffman codes -special cases	Example Problem solving- Linear block codes	trellis diagram for decoding convolutional codes	Classification of channels
	SLO-2	Different examples for different 'r'	Extensions of a code	Cyclic codes Generator polynomial	trellis diagram for decoding convolutional codes	Channel Capacity
S-6	SLO-1	Simple parity checks – Generator	Huffman codes Radix r	Cyclic codes Generation	Maximum likelihood decoding of convolutional codes	Calculation of channel capacity
	SLO-2	Simple parity Checker	Example Problem solving in Huffman coding	Cyclic codes Decoding	Maximum likelihood decoding of convolutional codes	Types of channel

S-7	SLO-1	CRC codes-Generation	Example Problem solving in Huffman coding-special cases	Example Problem solving -Cyclic codes	Sequential decoding of convolutional codes-	Conditional mutual information
	SLO-2	CRC codes-Checking	Noise in Huffman coding probabilities	Example Problem solving- Syndrome calculation	Sequential decoding of convolutional codes	Random encoding
S-8	SLO-1	Single parity checks	Use of Huffman codes	Block encoders	Applications of Viterbi decoding	Average random code
	SLO-2	Double parity checks	Hamming coding	Block Decoders	Viterbi decoding	Fano bound
S-9	SLO-1	Miscellaneous codes	Example Problem solving in Hamming coding	Assignment Problems in Linear Block codes	Turbo codes	Converse of Shannon's theorem
	SLO-2	Problems in source coding with different radix and parity	Assignment Problems in Huffman and Hamming coding	Assignment Problems in Cyclic codes	Assignment Problems in Convolutional codes	Assignment Problems in Channel capacity and mutual information

Learning Resources	1. Kennedy, "Electronic Communication systems", McGraw Hill, 4th Ed., 1999	4. Proakis J. G., "Digital Communications", McGraw Hill Inc., 4th Edition, NY, 2001.
	2. Daniel Costello, and Shu Lin, "Error Control coding fundamentals and applications", Prentice Hall Inc, 1983	5. Simon Haykin, "Communication System", Wiley, 2008
	3. Hamming, Richard W. "Coding and Information Theory", Prentice Hall Inc., N.J. 1986.	

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

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		Internal Experts
		1. Dr. J. Subhashini, SRMIST

Course Code	18ECE226T	Course Name	OPTICAL COMPONENTS, SYSTEMS AND NETWORKS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18ECC302J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:		
CLR-1 :	Understand the basics working principle of optical fibers, fiber modes configurations and structures.			
CLR-2 :	Learn the various optical source materials, LED structures, quantum efficiency, Laser diodes. To learn the fiber optical network components, switches, EDFA, SOA.			
CLR-3 :	Acquire the basic knowledge of fiber optical receivers such as PIN APD diodes, noise performance in photo detector, receiver operation and configuration.			
CLR-4 :	Get the knowledge on optical wave guides modulators and other signal degradation factors			
CLR-5 :	Understand the basic working principle of WDM, DWDM etc..			
CLR-6 :	Understand, the basic optical networks and their applications			

Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:				
CLO-1 :	Familiarize with the fundamentals of light transmission through fiber			2	80	70
CLO-2 :	Understand how signal degrades inside the fiber due to physical effects and externally due to various factors like alignment, splicing and connectorization			2	85	75
CLO-3 :	Understand the operation of optical sources, amplifiers and detectors and thereby build transmitter and receiver circuits			2	75	70
CLO-4 :	Familiarize with optical measurements for performance analysis			2	85	80
CLO-5 :	Design a basic optical Communication system			2	85	75
CLO-6 :	Acquire fundamental concepts on multichannel system and related components			2	80	70

Learning			Program Learning Outcomes (PLO)														
1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
H	M	-	-	-	-	-	-	-	-	-	-	-	-	H	-	H	
H	M	-	-	-	-	-	-	-	-	-	-	-	-	H	-	H	
H	-	-	H	-	-	-	-	-	-	-	-	-	-	H	-	H	
H	M	-	-	-	M	M	-	-	-	-	-	-	H	-	-	M	
H	-	H	-	-	-	-	-	-	-	-	-	-	-	H	-	-	M
-	-	-	-	M	-	-	-	-	-	-	-	-	-	-	-	-	-

Duration (Hour)		Optical Fibers and transmission characteristics	Optical Sources, Amplifier and Transmitter	Optical Detectors and receivers	Optical modulators, switches and OEICs	Optical Communication systems
		9	9	9	9	9
S-1	SLO-1	Elements of Optical fiber Communication, Optical spectral bands	Introduction to Luminescence: Photo, electro, cathodo, injection luminescence	Photo detection principle	Electro optic modulators	Point to point links
	SLO-2	Optical fiber structure, Light Propagation in Optical fibers: Ray theory, Total Internal reflection, Skew rays, Fiber types: SI, GI, MM, SM	Plasma display, LCD	Photoconductor,	Acousto optic modulators	Digital and analog systems design considerations
S-2	SLO-1	Overview of Modes, Cutoff wavelength and V number,	LED: Choice of material,	Noise in photoconductors, SNR	Interferometry modulators	Digital link design,
	SLO-2	Problems on v-number	LED Structures; Surface and Edge emitters,	Response time	Semiconductor optical amplifiers	Links power budget
S-3	SLO-1	Wave Equations for Step index fiber, Modal equation, Modes in SI fibers	Quantum efficiency and power, LED Characteristics	Problems on response time and SNR	Optical switching and logic devices	Rise time budget
	SLO-2	Problems on V-number, modes	Problems on LED quantum efficiency	Problems on Photoconductor	Problems on modulators	Overview of analog links
S-4	SLO-1	Special Fibers introduction, Polarization Maintaining fibers,	Semiconductor Laser Diode, Operating principles,	Photodiode: PIN Photodiode	Optical switching	Radio over fibers
	SLO-2	Photonic Crystal fibers, Dispersion compensated fiber	Emission absorption and radiation	Avalanche photodiode	Logic devices	Key link parameters
S-5	SLO-1	Attenuation Introduction	Population inversion	Detector performance parameters	Hybrid integration	Multichannel systems

	SLO-2	Material Adsorption, Scattering, bending and core cladding losses	Optical feed- back, Threshold condition	Detectors for long wavelength operation	Monolithic integration	Need for multiplexing
S-6	SLO-1	Problems	External Quantum efficiency, LASER Characteristics	wavelength selective detection	Comparison of hybrid and monolithic	Operating principle of WDM
	SLO-2	Overview of Signal dispersion in fibers	Problems on LASER quantum efficiency	Fundamental receiver operation	Slab waveguides	Operating principle of DWDM
S-7	SLO-1	Dispersion limitations, Intermodal dispersion	Single mode Laser: VCSEL	Front end amplifier and decision circuit	Strip waveguides	WDM components
	SLO-2	Intra-Modal dispersion: Material dispersion,	Introduction to Fiber Amplifiers	Functional block diagram of receiver circuit	Guided wave devices	Couplers/splitters
S-8	SLO-1	Waveguide dispersion and PMD	EDFA	Measurement standards, basic test equipment	Active filters	Isolators and circulators
	SLO-2	Problems on Dispersion	SOA	Optical spectrum analyzer	Problems	Machzender interferometer
S-9	SLO-1	Non linear effects : Non linear scattering, Kerr effects	Modulation characteristics and Driver circuits	Optical power meter	Integrated Transmitter	Fabry perot filters
	SLO-2	Fiber alignment and Joint Loss, Fiber Splices Optical fiber connectors, Expanded Beam Connectors	Functional block diagram of a Transmitter module	OTDR	Integrated Receivers	Optical MEMS

Learning Resources	1. Gerd Keiser, "Optical Fiber Communication" McGraw –Hill International, Singapore, 3 rd edition, 2000	6. S O Kasap "Optoelectronics and Photonics: Principles and practices", 2 nd Edition Person Education International, 2012.
	2. J. Wilson and JF B Hawkes "Optoelectronics – An Introduction" 3 rd Edition Pearson Education Taiwan Ltd 2010	7. Rajiv Ramaswami, Kumar N. Sivarajan, "Optical Networks A practical perspective", 2 nd edition, Elsevier, 2004
	3. Pallab Bhattachara "Semiconductors Optoelectronics Devices", 2 nd Edition, Prentice Hall of India Pvt Ltd, New Delhi, 2009.	8. Djafar K. Mynbaev, Lowell L. Scheiner, "Fiber-Optic Communications Technology", 1 st edition, Pearson Education, 2001.
	4. Jasprit Singh " Optoelectronics- An Introduction to Materials and Devices",Mc Graw Hill Education India 2014.	9. John Powers, "An Introduction to Fiber optic Systems", 2nd edition, Irwin-McGraw Hill, 1999.
	5. S C Gupta " Optoelectronics Devices and systems", 2 nd Edition, Prentice Hall of India, 2015.	10. J.Gowar, "Optical Communication System", 2nd edition, Prentice Hall of India, 2001.

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

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2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	2. Dr. Shanthi Prince, SRMIST

Course Code	18ECE320T	Course Name	SOFTWARE DEFINED NETWORKS				Course Category	E	Professional Elective				L	T	P	C							
													3	0	0	3							
Pre-requisite Courses		18ECC303J		Co-requisite Courses		Nil		Progressive Courses		Nil													
Course Offering Department		Electronics and Communication Engineering				Data Book / Codes/Standards			Nil														
Course Learning Rationale (CLR):		The purpose of learning this course is to:				Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understanding SDN- Evolution				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLR-2 :	Understanding The Control Plane, Data Plane of SDN							Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3	
CLR-3 :	Analyze and understand various SDN controller																						
CLR-4 :	Create insights to the standard Open Flow for SDN																						
CLR-5 :	understand the Network Programmability for SDN and SDN Open Source																						
CLR-6 :	understand the Application of SDN and role of SDN in 5G																						
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:				2	80	70	H	-	-	-	H	-	-	-	-	-	-	-	H	-	
CLO-1 :	understand the SDN architecture and benefit				2	80	70	H	-	-	-	H	-	-	-	-	-	-	-	-	-	H	-
CLO-2 :	Analyze and compare available SDN controller				2	85	75	H	-	-	H	H	-	-	-	-	-	-	-	-	-	H	-
CLO-3 :	Program the SDN elements				2	75	70	H	-	H	H	-	-	-	-	-	-	-	H	-	-	-	-
CLO-4 :	Apply NVF for next generation networks and 5G				2	85	80	H	H	H	H	H	-	-	-	-	-	-	-	-	-	H	-
CLO-5 :	Understand the possible application of SDN				2	85	75	H	-	-	H	-	-	-	-	-	-	-	-	-	-	-	-
CLO-6 :	Understand standard OpenFlow				2	80	70	H	-	H	-	H	-	-	-	-	-	-	-	-	-	-	-
Duration (hour)		Basics of SDN		SDN Devices and Controller		OpenFlow, Programmability and Management Interface		SDN Application and Use Case		SDN Implementation and Mobile Networks													
		9		9		9		9		9													
S-1	SLO-1	Introduction to SDN- Evolution of Switches and Control Planes , Cost		How SDN Works- Fundamental Characteristics of SDN		OpenFlow Overview- The OpenFlow Switch, The OpenFlow Controller,		SDN in the Data Center - Data Center Definition, Data Center Demands		SDN Open Source-Chapter-Specific Terminology ,Open Source Licensing Issues													
	SLO-2	Introduction to SDN - SDN Implications for Research and Innovation		SDN Operation, SDN Devices		The OpenFlow Protocol, The OpenFlow Protocol		Tunneling Technologies for the Data Center.		Profiles of SDN Open Source Users ,OpenFlow Source Code,													
S-2	SLO-1	need of SDN- Data Center Innovation,		SDN Controller		OpenFlow 1.0 and OpenFlow Basics- Ports and Port Queues, Flow Table, Packet Matching,		Path Technologies in the Data Cente Ethernet Fabrics in the Data Center		Switch Implementations , Controller Implementations SDN Applications													
	SLO-2	need of SDN- Data Center Needs		SDN Applications ,Alternate SDN Methods		Actions and Packet Forwarding, Messaging Between Controller and Switch		SDN Use Cases in the Data Center		Simulation, Testing, and Tools, OpenStack, Example: Applying SDN Open Source .													
S-3	SLO-1	Genesis of SDN- The Evolution of Networking Technology		General Concepts of SDN Controller		Example: Controller Programming Flow Table ,Example: Basic Packet Forwarding, Example: Switch Forwarding Packet to Controller		Open SDN versus Overlays in the Data Center		SDN Futures-Current State of Affairs													
	SLO-2	the Genesis of SDN- forerunners of SDN		VMware		OpenFlow 1.3 Additions and OpenFlow Limitations		Real-World Data Center Implementations		Potential Novel Applications of Open SDN													
S-4	SLO-1	the Genesis of SDN- software Defined Networking is Born, Sustaining SDN Interoperability		Nicira		Introduction to Network Programmability and The Management Interface		SDN in Other Environments - Wide Area Networks. Service Provider and Carrier Networks		role of SDN in 5G- Drawback of hardware-based network functions., Network Functions Virtualization (NFV) and Software Defined Networking (SDN) in 5G													
	SLO-2	Open Source Contributions, Legacy Mechanisms Evolve Toward SDN , Network Virtualization		VMware/Nicira		The Application-Network Divide		Campus Networks, Hospitality Networks		optimization models that aim at finding the optimal design for a mobile core network based on SDN and NFV													

S-5	SLO-1	The Control Plane, Data Plane	OpenFlow-Related	Modern Programmatic Interfaces- Publish and Subscribe Interfaces, XMPP	Mobile Networks. In-Line Network Functions,	SDN and NFV Mobile Network Architectures
	SLO-2	Moving Information Between Planes, Separation Importance	Mininet , NOX/POX	Google's Protocol Buffers , Thrift ,JSON	Optical Networks	Dimensioning and Resource Allocation Problems
S-6	SLO-1	Distributed Control Planes- IP and MPLS, Creating IP Underlay, Convergence Time	Trema, Ryu	I2RS 143 Modern Orchestration- OpenStack	SDN vs. P2P/Overlay Networks	Mobile Core Network Architecture
	SLO-2	Load Balancing ,High Availability, Creating the MPLS Overlay, Replication	Big Switch Networks/Floodlight,	CloudStack, puppet	SDN Applications- reactive versus Proactive Applications ,Analyzing Simple SDN Applications ,	SDN Mobile Core Network Architecture
S-7	SLO-1	Centralized Control Planes- Logical Versus Literal	Layer 3 Centric, L3VPN	Introduction to Network Function Virtualization, Virtualization and Data Plane I/O	A Simple Reactive Java Application, Background on Controllers	NFV Mobile Core Network Architecture
	SLO-2	ATM/LANE ,Route Servers	Path Computation Element Server	Services Engineered Path	Using the Floodlight Controller, Using the OpenDaylight Controller, Using the Cisco XNC Controller, Using the Hewlett-Packard Controller.	Data Plane Function Chains Analysis
S-8	SLO-1	Introduction to OpenFlow- Wire Protocol	Path Computation Element Server	Service Locations and Chaining	Switch Considerations, Creating Network Virtualization Tunnels, Offloading Flows in the Data Center, Access Control for the Campus, Traffic Engineering for Service Providers	Control Plane Function Chains Analysis
	SLO-2	Replication ,FAWG (Forwarding Abstraction Workgroup)	Plexxi Plexxi Affinity	Non-ETSI NFV Work- Middlebox Studie	SDN Use Cases- Use Cases for Bandwidth Scheduling	requirements & challenges of SDN and NFV In 5G
S-9	SLO-1	Configuration and Extensibility, Architecture	Cisco OnePK	Embrane/LineRate	Big Data and Application Hyper-Virtualization for Instant CSPF	Existing Solutions
	SLO-2	Hybrid Approaches , Ships in the Night ,Dual Function Switches	Relation to Idealized SDN Framework	Platform Virtualization	use Cases for Input Traffic Monitoring, Classification, and Triggered Action	future directions

Learning Resources	1. Software Defined Networks: A Comprehensive Approach by Paul Goransson and Chuck Black, Morgan Kaufmann Publications, 2014	4. Bouras, Christos, Anastasia Kollia, and Andreas Papazois. "SDN & NFV in 5G: Advancements and challenges." Innovations in Clouds, Internet and Networks (ICIN), 2017 20th Conference on. IEEE, 2017.
	2. SDN - Software Defined Networks by Thomas D. Nadeau & Ken Gray, O'Reilly, 2013 3. Cho, Hsin-Hung, et al. "Integration of SDR and SDN for 5G." IEEE Access 2 (2014): 1196-1204.	5. Arsany Basta; Andreas Blenk; Klaus Hoffmann; Hans Jochen Morper; Marco Hoffmann; Wolfgang Kellerer, Towards a Cost Optimal Design for a 5G Mobile Core Network Based on SDN and NFV,,IEEE Transactions on Network and Service Management, 2017, Volume: 14, Issue: 4 ,Pages: 1061 - 1075

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Anuj Kumar, Bombardier Transportation, Ahmedabad, kumaranuj.ani@gmail.com	1. Dr. Meenakshi, Professor of ECE, CEG, Anna University, meena68@annauniv.edu	1. Dr. P. Vijayakumar, SRMIST
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	

Course Code	18ECE322T	Course Name	OPTOELECTRONICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18ECC102J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Identify the working and nature of optical wave	Level of Thinking (Bloom)	Expected Proficiency %	Expected Attainment (%)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Identify the working and nature of optical semiconductors				Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3			
CLR-3 :	Analyze the working principles of different photonic sources				H	H	-	-	-	-	-	-	-	-	-	M	-	-	-			
CLR-4 :	Analyze the working principles of different photonic detectors				H	H	H	H	-	-	-	-	-	-	-	M	L	-	H			
CLR-5 :	Create knowledge about various optoelectronic applications				H	H	-	-	-	-	-	-	-	-	-	M	-	-	-			
CLR-6 :	Familiarize the concepts of optoelectronic integrated circuits				H	-	H	-	-	-	-	-	-	-	-	M	L	-	-			
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			2	85	80	H	H	H	H	-	-	-	-	-	-	-	M	-	-	-
CLO-1 :	Review the basics of optics, optical semiconductors	4	85	75	H	H	H	H	-	-	-	-	-	-	-	-	-	M	L	-	H	
CLO-2 :	Understand the working principle of different photonic sources	4	85	75	H	H	H	H	-	-	-	-	-	-	-	-	-	M	L	-	H	
CLO-3 :	Familiarize the principle and operation of various detectors	4	80	70	H	H	-	-	-	-	-	-	-	-	-	-	-	M	-	-	-	
CLO-4 :	Acquire knowledge of various optoelectronic modulators and switches	4	80	70	H	-	H	-	-	-	-	-	-	-	-	-	-	M	L	-	-	
CLO-5 :	Explore the concepts of optoelectronic integrated circuits and components	4	80	70	H	-	H	-	-	-	-	-	-	-	-	-	-	M	L	-	-	
CLO-6 :	Design and analyze the working of different components in optical system and use it for various applications.	4	80	70	H	H	H	H	-	-	-	-	-	-	-	-	-	M	-	-	H	

Duration (hour)		Wave nature of light and semiconductor optics	Semiconductor photon sources and display devices	Semiconductor photon detectors	Optoelectronic modulators, interconnects and switches	Optoelectronic integrated circuits (oeic) and applications
		9	9	9	9	9
S-1	SLO-1	Light Waves In A Homogeneous Medium- Plane electromagnetic wave, Maxwell's wave equation	LED Principles- Homojunction LED, Heterostructure LED	Principle of Photo Detection	Electro-Optic Modulator: Principles, Electro optic effect	Introduction
	SLO-2	Refractive Index And Dispersion- Sellmeier equation and diamond, Cauchy equation and diamond	Quantum Well High Intensity LEDs	The PIN Photodiode	Single waveguide electro optic modulators	Need For Integration
S-2	SLO-1	Polarization Of Light	LED Materials and Structures	Avalanche Photodiode- Principles, Structures	Dual channel waveguide electro optic modulator	Slab and stripe waveguides
	SLO-2	Snell's law and Total internal reflection	LED Efficiencies and Luminous Flux	Responsivity, Efficiency	Electro optic modulator employing reflection or Diffraction	Basic IO structural elements
S-3	SLO-1	Reflection And Refraction	Manufacturing Process and Applications	Heterojunction Photodiodes	Integrated Optical Modulators: Phase and polarization modulation	IO devices: Optical disk read head
	SLO-2	Solving problems	Solving Problems	Schottky Junction Photodetectors	Mach Zehnder modulator, Coupled waveguide modulator	OIC temperature sensor
S-4	SLO-1	Superposition And Interference Of Waves	LASER: Threshold Condition	Solving problems	Acousto-Optic Modulator: Principles, Acousto optic effect, Raman nath and Bragg type modulators	IO high voltage sensor

	SLO-2	<i>Diffraction Principles- Fraunhofer diffraction, Diffraction Grating</i>	<i>Emission and Absorption of Radiation</i>	<i>Solving problems</i>	<i>Performance characteristics, Acousto optic frequency shifters</i>	<i>IO chemical sensor</i>
S-5	SLO-1	<i>Overview Of Semiconductors</i>	<i>Population Inversion</i>	<i>Metal-Semiconductor, Metal Photodiode</i>	<i>Solving problems</i>	<i>IO wavelength meters and spectrum analyzers</i>
	SLO-2	<i>Interaction of Photons With Charge Carriers</i>	<i>Principle of the Laser Diode</i>	<i>Phototransistors</i>	<i>Solving problems</i>	<i>RF Spectrum Analyzer</i>
S-6	SLO-1	<i>Hole Pair Formation And Recombination</i>	<i>Heterostructure Laser Diodes</i>	<i>Array Detectors</i>	<i>Faraday Rotation</i>	<i>Monolithic Wavelength-Multiplexed Optical Source</i>
	SLO-2	<i>Absorption In Semiconductors</i>	<i>Device Fabrication</i>	<i>Photoconductive detectors</i>	<i>Optical Isolators</i>	<i>Analog-To-Digital Converter</i>
S-7	SLO-1	<i>Effect Of Electric Field On Absorption</i>	<i>Solving problems</i>	<i>Noise In Photodetectors</i>	<i>Nonlinear Optics</i>	<i>Integrated-Optic Doppler Velocimeter</i>
	SLO-2	<i>Absorption In Quantum Wells</i>	<i>Display Device: Photo Luminescence</i>	<i>Noise In Photodetectors</i>	<i>Second Harmonic Generation</i>	<i>Guided Wave Devices</i>
S-8	SLO-1	<i>Radiation In Semiconductors</i>	<i>Cathode Luminescence, Electro Luminescence</i>	<i>Solving problems</i>	<i>Optical Interconnects</i>	<i>Guided Wave Devices</i>
	SLO-2	<i>Solving Problems</i>	<i>Injection Luminescence</i>	<i>Solving problems</i>	<i>Optical gates</i>	<i>OEIC: Transmitter</i>
S-9	SLO-1	<i>Heterojunctions</i>	<i>Plasma Displays</i>	<i>Charge Coupled Devices (CCD)</i>	<i>Photonic Switches</i>	<i>OEIC: Receiver</i>
	SLO-2	<i>Heterojunctions</i>	<i>LCD, Numeric Displays</i>	<i>Charge Coupled Devices (CCD)</i>	<i>Solving problems</i>	<i>OEIC phased array antenna driver</i>

Learning Resources	1. Kasap, "Optoelectronics & Photonics: Principles & Practices", 2nd edition, Pearson Education, 2013. 2. Pallab Bhattacharya "Semiconductor Optoelectronic Devices", 2nd Edition, Prentice Hall of India Pvt. Ltd, New Delhi, 2009. 3. B. E. A. Saleh and m.c. Teich, "Fundamentals Of Photonics," 2nd edition, John Wiley & Sons, Inc. 2007.	4. Robert G. Hunsperger, "Integrated Optics- Theory And Technology", Springer, 2009 5. J. Wilson and J F B Hawkes "Optoelectronics- An Introduction", 3rd edition, Pearson Education Taiwan Ltd, 2010. 6. A Ghatak and K Thyagarajan, "Introduction to Fiber Optics", Cambridge University Press 2006.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	40%	-	35%	-	35%	-	40%	-
	Understand										
Level 2	Apply	40%	-	40%	-	35%	-	35%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	20%	-	30%	-	30%	-	20%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

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Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	

Course Code	18ECE323T	Course Name	ADVANCED OPTICAL COMMUNICATION	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18ECC302J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Introduce the advanced features of Fibers and light wave system	Thinking (Bloom)	Efficiency (%)	Attainment (%)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2 :	Illustrate the basics of light wave system and multichannel system																							
CLR-3 :	Understand the various dispersion compensation techniques																							
CLR-4 :	Gain the information on advanced RoF Systems																							
CLR-5 :	Improve the knowledge about the characterization of the Visible Light Communication																							
CLR-6 :	Utilize the concepts in optical Communication for the understanding of engineering and technology																							

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Explain the concept of wave propagation and dispersion in single-mode fibers, loss and nonlinear of fiber and fiber design and fabrication.	2	80	70	H	H	M	H	H	-	L	-	-	H	-	-	H	M	H
CLO-2 :	Apply the concept of optical transmitter and receiver in single-mode semiconductor lasers, light-emitting diodes, transmitter design and receiver design	2	85	75	H	H	M	H	H	-	L	-	-	H	-	-	H	M	H
CLO-3 :	Demonstrate the concept of long-haul systems, computer-aided design, WDM light wave systems, WDM Components, time-division, subcarrier and code division multiplexing	2	75	70	H	H	M	H	H	-	L	-	-	H	-	-	H	M	H
CLO-4 :	Explain the loss and dispersion managements in EDFA - Raman amplifiers, dispersion compensating fibers Fiber Bragg gratings, dispersion-equalizing filters and optical phase conjugation	2	85	80	H	H	M	H	H	-	L	-	-	H	-	-	H	M	H
CLO-5 :	Apply the concept of advanced light wave system in demodulation schemes sensitivity degradation mechanisms and impact of nonlinear effects	2	85	75	H	H	M	H	H	-	L	-	-	H	-	-	H	M	H
CLO-6 :	Apply their idea in Optical Communication module	2	80	70	H	H	M	H	H	-	L	-	-	H	-	-	H	M	H

Duration (hour)		Optical fibers and lightwave systems	Lightwave systems and multichannel systems	Loss management and dispersion management	Radio over fiber systems	Optical wireless Communication
		9	9	9	9	9
S-1	SLO-1	Geometrical-Optics Description	System Architectures	Compensation of Fiber Losses	Trends in Wireless Communications	Free-space optical wireless Communication
	SLO-2	Wave Propagation	Working Principles	Erbium-Doped Fiber Amplifiers les	Basic Transmission problems and solutions	Free-space optical OFDM Communication
S-2	SLO-1	Dispersion in Single-Mode Fibers	Design Guidelines	Raman Amplifiers	Regulation	Wireless optical CDMA Communication systems
	SLO-2	Dispersion Induced Limitations	Long-Haul Systems	Optical Signal-To-Noise Ratio	Standardization	Comparison of Free-space optical OFDM & CDMA Communication
S-3	SLO-1	Fiber Losses	Sources of Power Penalty	Electrical Signal-To-Noise Ratio	System concepts for the central processing of signals	Indoor wireless optical Communication
	SLO-2	Nonlinear Optical Effects	Forward Error Correction	Receiver Sensitivity and Q Factor	Wireless Trends	outdoor wireless optical Communication
S-4	SLO-1	Fiber Design and Fabrication	Types of FEC	role of Dispersive and Nonlinear Effects	Architecture options,	Heterogeneous optical networks (HONs)

	SLO-2	multicore fibers	Computer-Aided Design	Periodically Amplified Lightwave Systems	global centralized Architecture	System Performance
S-5	SLO-1	multiclad fibers	WDM	Dispersion Problem	FUTON scenarios	VLC System Model
	SLO-2	advantages and its applications	DWDM	Its Solution	Optical Infrastructure	Advantages and its applications
S-6	SLO-1	Advanced Modulation Formats	Light wave Systems	Dispersion-Compensating Fibers	Concepts of Radio over Fiber systems	(RF) sensor network system
	SLO-2	Demodulation Schemes	WDM Components	Fiber Bragg Gratings	Features of RoF	Advantages and its applications
S-7	SLO-1	Shot Noise	System Performance Issues	Dispersion Equalizing Filters	Categories RoF systems	(FSO) sensor network system
	SLO-2	Bit-Error Rate	Time-Division Multiplexing	Optical Phase Conjugation	Performances RoF systems	Advantages and its applications
S-8	SLO-1	Sensitivity Degradation Mechanisms	Subcarrier Multiplexing	Channels at High Bit Rates	Applications of RoF Technology	Recent Advancement in Optical Wireless Communication
	SLO-2	Impact of Nonlinear Effects	Code-Division Multiplexing	Electronic Dispersion Compensation	Advantages of RoF Technology	Advantages and its applications
S-9	SLO-1	Recent Progress	Solving Problems	Solving Problems	Solving Problems	Solving Problems
	SLO-2	Ultimate Channel Capacity	Solving Problems	Solving Problems	Solving Problems	Solving Problems

Learning Resources	1. Nathan J. Gomes, Paulo P. Monteiro and Atilio Gameiro "Next Generation wireless Communications using Radio over Fiber" John Wiley & Sons, Ltd, 2012 2. G.P. Agarwal, Fiber optic Communication systems, 4nd Ed, John Wiley & Sons, New York, 2010	3. Shlomi Arnon, John R. Barry, George K. Karagiannidis, Robert Schober, Murat Uysal, "Advanced Optical Wireless Communication Systems" Cambridge University Press, 2012 4. Shlomi Arnon, "Visible light Communication", Cambridge University Press, 2015
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry		Experts from Higher Technical Institutions
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2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com		2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in
		Internal Experts
		1. Dr. C.T. Manimegalai, SRMIST

Course Code	18ECE243J	Course Name	DIGITAL IMAGE AND VIDEO PROCESSING	Course Category	E	Professional Elective	L	T	P	C
							2	0	2	3

Pre-requisite Courses	18ECC204J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
					1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-1 :	Introduce the fundamentals of image processing and transforms				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-2 :	Understand the concepts of image enhancement and restoration																					
CLR-3 :	Acquire knowledge on image compression and segmentation methods																					
CLR-4 :	Gain knowledge on basics of video processing																					
CLR-5 :	Know about motion estimation methods in video processing																					
CLR-6 :	Utilize the concepts of image and video processing for practical applications																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Understand the basics of digital image processing fundamentals and transforms				1,2	95	70	L	-	-	-	-	-	-	-	-	-	-	H	M	-	-
CLO-2 :	Design 2D filters and apply it for image enhancement and restoration				2	90	70	M	H	-	H	H	-	-	-	-	-	-	H	M	-	H
CLO-3 :	Apply image compression and segmentation methods on digital images				2	90	65	M	H	-	H	H	-	-	-	-	-	-	H	-	-	H
CLO-4 :	Analyze the video formation techniques				1	95	70	H	H	-	H	H	-	-	-	-	-	-	H	-	-	H
CLO-5 :	Learn about the techniques for applying motion estimation in video coding				1,2	90	65	M	H	-	H	H	-	-	-	-	-	-	H	-	-	H
CLO-6 :	Apply the concepts of digital image, video processing and their applications				1,2	90	70	-	-	-	-	-	-	-	-	-	-	-	-	M	-	H

Duration (hour)		Digital Image Fundamentals and Image Transforms	Image Enhancement and Restoration	Image Compression and Segmentation	Basic Steps of Video Processing	2D Motion Estimation
		12	12	12	12	12
S-1	SLO-1	Origin of digital image processing	Some basic intensity transformation functions – image negatives, log transformations	Fundamentals of image compression-coding redundancy, spatial and temporal redundancy	Analog video signals, standard	2D motion estimation – Optical flow – 2D motion vs. apparent motion
	SLO-2	Fundamental steps in digital image processing	Piecewise linear transformation functions	Irrelevant information, measuring image information	Digital video signal, standard, Digital video processing	Correspondence and optical flow
S-2	SLO-1	Components of an image processing system	Histogram equalization, Matching	Image compression model, Lossless compression, Huffman coding	Time varying image formation models – 3D motion models	Occlusion problem
	SLO-2	Structure of human eye, Image formation	Local Histogram Processing	Arithmetic Coding, Run length coding	Rigid motion in Cartesian, Homogenous coordinates	Aperture problem, 2D motion field models
S-3-4	SLO-1	Lab 1: To learn MATLAB software and its basic commands for image processing	Lab 4: Histogram Modifications	Lab 7: Run length coding	Lab 10: Wavelet coding	Lab 13: Convert video into frames and process them
	SLO-2					
S-5	SLO-1	Brightness adaptation and discrimination	Using histogram statistics for image enhancement	Lossy compression - Transform coding	Deformable motion	Block motion models- translational block motion

	SLO-2	Basic concepts in sampling and Quantization , Representing digital images	Smoothing linear filters	Wavelet coding	Geometric image formation	Generalized/ Deformable block motion
S-6	SLO-1	Neighbors of a pixel, Adjacency, Connectivity, Regions and Boundaries	Order statistics nonlinear filters	Image segmentation – detection of isolated points, line detection	Perspective projection	Block matching criteria, Matching procedures
	SLO-2	Distance Measures, A simple image formation model	Sharpening spatial filters	Edge models, Basic edge detection	Photometric image formation	Hierarchical motion estimation
S- 7-8	SLO-1	Lab 2: Fourier analysis of image	Lab 5: Image smoothing and sharpening	Lab 8: Basic edge detection operations	Lab 11: JPEG Compression	Lab 14:Filtering video signals
	SLO-2					
S-9	SLO-1	Fourier transform of sampled functions	Combined spatial enhancement methods	Region based segmentation – region growing	Photometric effects of 3D motion	Gradient based optimization
	SLO-2	Sampling theorem, Aliasing, Obtaining the DFT from the Continuous Transform of a Sampled Function	Homomorphic filtering, A model of image degradation/ restoration process	Region splitting and merging	Observation noise, Sampling structures of analog, digital video	Steepest Descent method
S-10	SLO-1	Properties of 2D DFT – Relationship between spatial and frequency interval, Translation and Rotation, Periodicity, symmetric properties	A model of image degradation/ restoration process, Noise models	Spatial, frequency domain techniques	2D fourier transform relations, Intra frame filtering- LMMSE filtering	Newton Raphson method, Transform coding , 3D waveform coding
	SLO-2	DWT, DCT	Singular value decomposition	Texture based segmentation	Median and weighted median filtering, Motion detection based filtering	Local vs. Global minima, Predictive coding
S- 11 - 12	SLO-1	Lab 3: Image filtering	Lab 6: Singular value decomposition	Lab 9: Repeat/Revision of experiments	Lab 12: Region based image segmentation	Lab 15: Mini project
	SLO-2					

Learning Resources	<ol style="list-style-type: none"> 1. Rafael C Gonzalez, Richard E Woods, "Digital Image Processing"- 3rd Edition, Pearson Education 2008. 2. Yao wang, JoemOstarmann and Ya – quin Zhang, "Video processing and Communication ",1st edition , PHI 3. M. Tekalp , "Digital video Processing", Prentice Hall International 4. A.K. Jain, "Fundamentals of Digital Image Processing". Pearson education 5. William K Pratt, "Digital Image Processing", John Willey (2001).
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		-	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Anuj Kumar, Bombardier Transportation, Ahmedabad, kumaranuj.ani@gmail.com	1. Dr. Meenakshi, Professor of ECE, CEG, Anna University, meena68@annauniv.edu	1. Dr. S. Dhanalakshmi, SRMIST
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	2. Mrs. S. Latha, SRMIST

Course Code	18ECE244J	Course Name	DSP SYSTEM DESIGN	Course Category	E	Professional Elective	L	T	P	C
							2	0	2	3

Pre-requisite Courses	18ECC204J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	IEEE 1641-2010, IEEE 754, IEEE Standard. 1149.1		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
		1	2	3	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-1 : Acquire knowledge on Floating and Fixed point Processor such as TMS320C6X for complex signal								Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-2 : Learn and code TMS320C6x Assembly level programming for real time signal processing applications		H	-	H				-	-	-	-	-	-	-	-	-	-	-	-	H	M	L
CLR-3 : Design and coding DSP algorithm such as FFT, DFT, Convolution , IIR and FIR filters in TMS320C6x		H	H	-				H	-	-	-	-	-	-	-	-	-	-	-	H	M	L
CLR-4 : Gain knowledge on advance filter concepts and filter signal noise using Filter Bank, adaptive filters and analyzes such filters for high end designing.		-	H	-				H	-	-	-	-	-	-	-	-	-	-	-	M	L	H
CLR-5 : Design DSP system for real time applications.		H	-	-				-	H	-	-	-	H	-	-	-	H	-	-	M	L	H
CLR-6 : Utilize the concept of DSP for Engineering and Technology		-	-	H				-	H	-	-	-	-	-	-	M	-	-	H	M	M	
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 : Acquire in-depth knowledge on DSP architecture and instruction sets of TMS320C6X		1	85	65																		
CLO-2 : Attain assembly programming knowledge and analyze using TMS320C6x		1, 2	85	65																		
CLO-3 : Implement various DSP algorithm such as FFT, DFT, Convolution , IIR and FIR filters in TMS320C6x		2,3	85	65																		
CLO-4 : Acquire knowledge and analyze on Filter Banks and adaptive filters and analyze such filters.		1,2	85	65																		
CLO-5 : Gain knowledge on DSP system design based applications.		3	85	65																		
CLO-6 : Apply the concept of DSP for real time applications		3	85	65																		

Duration (hour)		TMS320C6X Architecture	TMS3206X Assembly Language	Frequency Transforms	Digital Filters	DSP Applications
		15	15	15	15	15
S-1	SLO-1	Architecture of TMS320C6X	TMS320C6X Assembly Language Operations	Digital filtering using the DFT	Filter banks – Decimation,	Dual tone Multi-Frequency (DTMF) Signaling
	SLO-2	Pipeline CPU	Individual Instruction Descriptions	Convolution and correlation	Inverse Decimation	Software Defined Radio (SDR)
S-2	SLO-1	VelociTI, Functional Units,	Arithmetic operations, ,	Fast Fourier Transform –DIT	Perfect Reconstruction	QAM Transmitter and QAM Receiver
	SLO-2	Addressing modes,	logical operations,	Fast Fourier Transform –DIT	Analysis of M-Band filter Banks	Miscellaneous Projects--FSK Modem
S-3	SLO-1	Lab1: Generation of sequences (functional & random) (Matlab)	Lab 7: MAC operation using various addressing modes	Lab 13: Spectrum analysis using DFT(Matlab)	Lab 19: FIR Implementation using TMS Processor	Lab 25: Equalization (Matlab)
	SLO-2					
S-4	SLO-1	Lab 2: Correlation(Matlab)	Lab 8: MAC operation using various addressing modes	Lab 14: FFT Implementation(DSP processor)	Lab 20: FIR Implementation using TMS Processor	Lab 26: Equalization (Matlab)
	SLO-2					
S-5	SLO-1	TMS320C6X Instruction Sets,	Memory data operations	Fast Fourier Transform –DIF	Orthogonality and Biorthogonality in Filter banks	u-Law for Speech Companding,
	SLO-2	Assembler directives	Conditional Operations	Fast Fourier Transform DIF	QMF Filter banks and	Acoustic Direction Tracker
S-6	SLO-1	Multichannel Buffered Serial Ports	Floating Point –Data type operations,	IFFT	CQF Filter Banks	MultirateFilter, Neural Network for Signal Recognition

	SLO-2	Memory Considerations –Constraints	Floating Point –Data type operations	FIR filters	Transmultiplexers;	PID Controller, Four-Channel Multiplexer for Fast Data Acquisition
S-7	SLO-1	Lab 3: Linear Convolution (Matlab)	Lab 9: MAC operation using various addressing modes	Lab 15: FIR filter design-Windowing Techniques(Matlab)	Lab 21: IIR implementation using TMS processor	Lab 27: Real time audio signal processing with Processor
	SLO-2					
S-8	SLO-1	Lab 4 :Circular convolution(Matlab)	Lab 10: Linear convolution(DSP processor)	Lab 16: FIR filter design-Windowing Techniques(Matlab)	Lab 22: IIR implementation using TMS processor	Lab 28: Real time audio signal processing with Processor
	SLO-2					
S-9	SLO-1	Instruction Operation and Execution notations	Fixed- Point Operations,	FIR filters	Structures and Programming Examples for Noise cancellation	Video Line Rate Analysis
	SLO-2	Overview of IEEE Standard single and Double Precision formats ,	Fixed- Point Operations	IIR filter	Adaptive Filters-Adaptive filters in DSP simulation software's and TMS320C6x	DSP System Design
S-10	SLO-1	Q-format Number Representation on Fixed Point DSPs, Finite Word length effects on Fixed point DSPS	Pipeline Operations overview	IIR filter	Software simulation of FIR	MP3 Player
	SLO-2	Floating point number representation, , Overflow and Scaling	Interrupts-overview.	FIR and IIR filter design using TMS320C6x	IIRFilters and Filter banks	DSP Automotive application
S-11	SLO-1	Lab 5: Study of architecture of Digital Signal Processor	Lab 11: Circular convolution(DSP processor)	Lab 17: IIR filter design-Bilinear and Impulse Invariance Technique(Matlab)	Lab 23: Multirate filters	Lab 29: Real time audio signal processing with Processor
	SLO-2					
S-12	SLO-1	Lab 6: Study of architecture of Digital Signal Processor	Lab 12: Waveform generation(DSP processor)	Lab 18: IIR filter design-Bilinear and Impulse Invariance Technique(Matlab)	Lab 24: Finite Word Length Effect	Lab 30: Real time audio signal processing with Processor
	SLO-2					

Learning Resources	1. B Venkataramani, M Bhaskar, "Digital Signal Processors: Architecture, Programming and Applications", TMH Publishers, 2nd edition, 2017	4. RulphChassaing - "DSP Applications Using C and the TMS320C6x DSK" John Wiley & Sons, Inc. 2002. 5. Nasser Kehtamavaz , "Real-Time Digital Signal ProcessingBased on the TMS320C6000", Newnes, 2005.
	2. Paulo S. R.DinizEduardo A. B. da Silva and Sergio L. Netto, "Digital Signal Processing System Analysis and Design", Cambridge University Press, 2nd Edition. 2010 3. Nasser Kehtamavaz, Namjin Kim, "Digital Signal Processing System-Level Design Using LabVIEW", Newgen Elsevier Publication, 2nd edition, 2014	

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		-	

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Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	Dr. S. Dhanalakshmi, Assoc. Professor, SRMIST

Course Code	18ECE245T	Course Name	ADAPTIVE SIGNAL PROCESSING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18ECC204J	Co-requisite Courses	Nil	Progressive Courses	18ECE342T
Course Offering Department	Electronics and Communication Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Have an insight on basics of random processes	1	2	3	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Gain knowledge on the applications of adaptive filters	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO-1: Professional Achievement	PSO - 2: Project Management Techniques	PSO - 3: Analyze & Research			
CLR-3 :	Have an introduction on LMS techniques																					
CLR-4 :	Analyze the types of LMS algorithm																					
CLR-5 :	Have an introduction on RLS algorithm																					
CLR-6 :	Understanding on need and design of adaptive filters using different algorithms																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	To review the basics of statistical signal processing	1	95	70	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-2 :	To understand about the need for adaptive filters and learn the design of it.	1,2	95	70	H	M	M	H	-	-	-	-	-	-	-	-	-	-	-	L	M	
CLO-3 :	To acquire knowledge on LMS algorithms and constraints associated with it.	2,3	85	65	H	H	H	H	L	-	-	-	-	-	-	-	M	-	M	M		
CLO-4 :	To learn the variants of LMS algorithm and design of lattice structures	2	85	65	H	M	H	H	-	-	-	-	-	-	-	-	-	-	M	M		
CLO-5 :	To gain knowledge on design of RLS filters and others aspects of filter design	1,2	85	65	H	M	M	H	L	-	-	-	-	-	-	-	M	-	M	M		
CLO-6 :	To understand the applications of adaptive signal processing and algorithms in designing the adaptive filters	1,2	85	65	H	H	H	H	L	-	-	-	-	-	-	-	M	-	H	H		

Duration (hour)		Introduction to Stochastic Process	Adaptive Filters	Least Mean Square Algorithm	Variants of LMS Algorithm And Lattice Structures	Recursive Least Square Algorithm
		9	9	9	9	9
S-1	SLO-1	Introduction to random process	Introduction to adaptive filters	Least mean square algorithm	Sign LMS algorithm	Recursive adaptive filters
	SLO-2	Variables, vectors	Block diagram of adaptive structure with shift variant filter	Derivation	Normalized LMS	Principle of RLS algorithm
S-2	SLO-1	Ensemble averages	Properties of adaptive filter	Properties of LMS adaptive filters	Leaky LMS	FIR RLS filter algorithm
	SLO-2	Time averages	Error sequence generation in adaptive filters	Properties of LMS adaptive filters	Block LMS	Derivation
S-3	SLO-1	Stationarity and Stationary random process	Channel Equalization- Block diagram of Communication system with Channel equalization	Complex LMS algorithm	FFT based implementation of block LMS	Sliding window RLS
	SLO-2	Wide sense stationarity	Echo cancellation	Convergence of LMS algorithm	FFT based implementation of block LMS	Derivation
S-4	SLO-1	Power Spectral Density	Concept of adaptive noise cancelling	Learning curve for adaptive filters	Comparison of variants on LMS for some practical problem	Comparing variants of RLS using MATLAB program
	SLO-2	Properties of PSD	Beam forming with pilot signals	Sample MATLAB program for LMS convergence and plotting learning curve	Comparison of variants on LMS for some practical problem	Comparing variants of RLS using MATLAB program
S-5	SLO-1	Sample problems on WSS random process	System modeling using adaptive filters	Performance analysis of LMS adaptive filters by varying step size (MATLAB)	Lattice filters introduction	Kalman filters

	SLO-2	Sample problems on WSS random process	System Identification structure	Performance analysis of LMS adaptive filters by varying step size (MATLAB)	Advantages of Lattice structures	Kalman filters
S-6	SLO-1	Filtering of random process	System inversion using adaptive filters	Weight error correlation matrix	Forward linear prediction	Sample problems on RLS algorithms
	SLO-2	Filtering of random process	Interference cancellation in multi sensor systems	LMS misadjustment definition	Forward linear prediction	Sample problems on RLS algorithms
S-7	SLO-1	Autocorrelation Structures	Minimization of mean square error	Effects of misadjustment factor	Backward linear prediction	Non linear adaptive filters
	SLO-2	Covariance Structures	Derivation on MMSE	Sample problems for designing adaptive filters using LMS	Backward linear prediction	Introduction to Neural networks
S-8	SLO-1	Eigen value decomposition	Steepest Descent algorithm	Sample problems on step size	Reflection coefficients of forward and backward predictors	Neural networks and multilayer perceptrons
	SLO-2	Eigen value analysis of autocorrelation matrices	Linear prediction example	Sample problems on step size	Relation between forward and backward prediction coefficients	Neural networks and multilayer perceptrons
S-9	SLO-1	Ergodicity	Wiener filters	Stability analysis of LMS algorithms	Properties of Lattice structures	Adaptive IIR filtering
	SLO-2	Ergodic random process	Optimization solution in wiener filters	Stability analysis of LMS algorithms	Updating predictor coefficients	Adaptive IIR filtering

Learning Resources	<ol style="list-style-type: none"> 1. S. Haykin ,Adaptive Filter Theory, Prentice-Hall, 4-th edition, 2001. 2. Ali H. Sayed ,Fundamentals of Adaptive Filtering, John Wiley, 2003. 3. D. Manolakis, V. Ingle, S. Kogan,Statistical and Adaptive Signal Processing: Spectral Estimation, Signal Modeling, Adaptive Filtering and Array Processing, McGraw Hill, 1999. 	<ol style="list-style-type: none"> 4. B. Widrow, S. Stearns,Adaptive Signal Processing, Prentice-Hall, 1985 5. Monson H. Hayes,Statistical Digital Signal Processing and Modeling, Edition: 1st, 2008.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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Course Code	18ECE340T	Course Name	MACHINE PERCEPTION WITH COGNITION	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18ECE242J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering		Data Book / Codes/Standards	Nil	

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Have an insight on image and color fundamentals	Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLR-2 :	Analyze the various shapes and regions for the image description		Expected Proficiency (%)																			
CLR-3 :	Acquire knowledge on the texture analysis of an image		Expected Attainment (%)																			
CLR-4 :	Identify the relation between the templates to match the image requirements																					
CLR-5 :	Know the practical applications of computer vision in images understanding																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	To outline the fundamentals of image and color models	1	90	85		H		L		M	H			Ethics					L	L	M	
CLO-2 :	Understand the basic shapes and region based image modeling	1	85	85			H						H						M	H	M	
CLO-3 :	Analyze the various textures for image synthesis	1&2	85	80				M		M		H							L	M	M	
CLO-4 :	Identify the objects based on template relations	1&2	85	75							H	M	M						L	M	M	
CLO-5 :	To apply the image understanding knowledge for image recognition	2&3	85	80		H	M						H	M					L	M	H	
CLO-6 :	To understand the principles of image modeling and synthesis with image recognition	1,2,3	85	80		M	H	H	H	M									M	M	H	

Duration (hour)		Learning Unit / Module 1 Basic Audio Processing	Learning Unit / Module 2 Human Auditory System	Learning Unit / Module 3 Speech Signal Analysis in Time Domain	Learning Unit / Module 4 Speech Signal Analysis in Frequency Domain	Learning Unit / Module 5 Speech and Audio processing applications
		12	12	12	12	12
S-1	SLO-1	Review of Image processing methods	Binary Shape analysis	Representing textures	Finding objects by voting on relation between templates	Face detection
	SLO-2	Review of Image processing methods	Binary Shape analysis	Representing textures	Interest points, Simple voting, Voting on relations.	Face detection
S-2	SLO-1	Introduction to image formation	Connectedness	Extracting image Structure with filter banks	Relational reasoning using probabilistic framework	Face recognition
	SLO-2	Introduction to image formation	Object labeling and counting	Extracting image Structure with filter banks	Growing Assemblies Incrementally, Detection, Pruning	Face recognition
S-3	SLO-1	Image models	Size filtering	Representing texture using statistics of filter output	Frames and probability models	Eigen faces
	SLO-2	Camera models	Distance functions	Representing texture using statistics of filter output	Representing coordinate frames	Active appearance
S-4	SLO-1	Sample programs for reading images, understanding pixels	Skeletons and thinning	Analysis using oriented pyramids	Using probability model for detecting the frames	3D shape models of face surveillance
	SLO-2	Sample programs for reading images, understanding pixels	Deformable shape analysis	Laplacian pyramids	Building probability models for frame invariant	3D shape models of face surveillance
S-5	SLO-1	Shadows	Boundary tracking procedures	Filters in the spatial frequency domain	Classifiers to prune search	Foreground separation

	SLO-2	Color representation	Boundary tracking procedures	Filters in the spatial frequency domain	Identifying acceptable assemblies	Background separation
S-6	SLO-1	Human color perception	Shape models	Oriented pyramids	Sample examples for prune search	Particle filters
	SLO-2	Human color perception	Shape recognition	Oriented pyramids	Hidden Markov model	Particle filters
S-7	SLO-1	Image color	Centroidal profiles	Synthesizing textures for rendering	Computing, Maximizing parameters	Champer matching, tracking and occlusions
	SLO-2	Image color	Handling occlusions	Synthesizing textures for Homogeneity	Varieties of HMM	Champer matching, tracking and occlusions
S-8	SLO-1	Handling Color Images (MATLAB)	Boundary descriptors	Synthesis by sampling local models	Background subtraction	Combining views from multiple cameras
	SLO-2	Handling Color Images (MATLAB)	Boundary descriptors	Synthesis by sampling local models	Sample programs on background subtraction	Human gait
S-9	SLO-1	Surface Color	Region descriptors	Shape from texture planes	Hough transform	Constructing 3D models from image sequences
	SLO-2	Surface Color	Region descriptors	Texture from shape planes	Sample problems on Hough transforms	Scene modeling from registered and unregistered images

Learning Resources	<ol style="list-style-type: none"> 1. E. R. Davies, "Computer & Machine Vision", Fourth Edition, Academic Press, 2012. 2. R. Szeliski, "Computer Vision: Algorithms and Applications", Springer 2011. 3. Simon J. D. Prince, "Computer Vision: Models, Learning, and Inference", Cambridge University Press, 2012 	<ol style="list-style-type: none"> 4. Mark Nixon and Alberto S. Aquado, "Feature Extraction & Image Processing for Computer Vision", Third Edition, Academic Press, 2012 5. D. L. Baggio et al., "Mastering OpenCV with Practical Computer Vision Projects", Packt Publishing, 2012 6. Jan Erik Solem, "Programming Computer Vision with Python: Tools and algorithms for analyzing images", O'Reilly Media, 2012.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Anuj Kumar, Bombardier Transportation, Ahmedabad, kumaranuj.ani@gmail.com	1. Dr. Meenakshi, Professor of ECE, CEG, Anna University, meena68@annauniv.edu	1. Dr. A. Ruhan Bevi, SRM IST
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	

Course Code	18ECE341T	Course Name	MULTIMEDIA COMPRESSION TECHNIQUES	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18ECE240T	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1: Learn about probability model and coding theory		1	1
CLR-2: Understand about lossless compression		2	2
CLR-3: Understand about Lossy data compression		3	3
CLR-4: Learn about the encoding methods		4	4
CLR-5: Compression Techniques and their applications		5	5
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Engineering Knowledge
CLO-1: Understand the fundamental concepts of probability model and practical limits specified by coding theory		L1&L2	90
CLO-2: Learn about rate-distortion theory and what they reveal about efficient information transfer		L2&L3	86
CLO-3: Understand the fundamental approaches towards lossy image compression		L2&L3	86
CLO-4: Analyze image, video and audio in the frequency domain to identify important components to be encoded		L2	85
CLO-5: Applications of various compression techniques		L2&L3	85
CLO-6: Learn about data compression and encoding methods		L1,L2,L3	90

Duration (hour)	9	9	9	9	9
S-1	SLO-1	The discrete memory less information source	Mathematical Preliminaries for Lossless	Rate distortion function	Vector Quantization
	SLO-2	Kraft inequality; optimal codes	Mathematical Preliminaries for Lossless Compression	Rate distortion function	LBG algorithm
S-2	SLO-1	Source coding theorem-Entropy	Huffman Coding	Properties of RD	Tree structured VQ
	SLO-2	Joint Entropy and Conditional Entropy	Huffman Coding	Properties of RD	Structured VQ
S-3	SLO-1	Relative Entropy	Optimality of Huffman codes	Calculation of RD for the binary source and the Gaussian source	Variations of VQ
	SLO-2	Mutual Information	Extended Huffman Coding	Calculation of RD for the binary source and the Gaussian source	Gain shape VQ
S-4	SLO-1	Chain Rules	Adaptive Huffman Coding	Rate distortion theorem	Mean removed VQ
	SLO-2	Data-Processing Inequality	Arithmetic Coding	Rate distortion theorem	Classified VQ
S-5	SLO-1	Fano's Inequality Symmetric Channels	Adaptive Arithmetic coding	Converse of the Rate distortion theorem	Multistage VQ
	SLO-2	Fano's Inequality Symmetric Channels	Run Length Coding	Quantization problem	Adaptive VQ

S-6	SLO-1	Properties of Channel Capacity, Jointly Typical Sequences	Dictionary Techniques	Scalar Quantization- Uniform Quantizer	Trellis coded quantization Transforms.	JPEG
	SLO-2	Properties of Channel Capacity, Jointly Typical Sequences	Lempel Ziv coding	Scalar Quantization- Uniform Quantizer	Trellis coded quantization Transforms.	MDCT
S-7	SLO-1	Channel Coding Theorem	Applications	Adaptive Quantization	Basic algorithm	MDCT
	SLO-2	Channel Coding Theorem	Predictive Coding	Adaptive Quantization	Prediction in DPCM	Image compression – EZW-Analysis/Synthesis Schemes
S-8	SLO-1	Fano's Inequality	Prediction with Partial Match	Non-uniform Quantization	Prediction in DPCM	Image compression – SPIHT-Analysis/Synthesis Schemes
	SLO-2	Fano's Inequality	Burrows Wheeler Transform	Non-uniform Quantization	Adaptive DPCM	Image compression – JPEG 2000-Analysis/Synthesis Schemes
S-9	SLO-1	Converse to the Coding Theorem	Dynamic Markov Compression	Entropy coded Quantization	Adaptive DPCM	Audio coding:-MPEG audio coding
	SLO-2	Converse to the Coding Theorem	Dynamic Markov Compression	Entropy coded Quantization	Delta Modulation	Audio coding:-MPEG audio coding

Learning Resources	<ol style="list-style-type: none"> 1. K. Sayood, "Introduction to Data Compression", 3rd Edition, Morgan Kaufmann Publishers, 2006. 2. N. Jayant and P. Noll, "Digital Coding of Waveforms: Principles and Applications to Speech and Video", ISBN10 0132119137, Prentice Hall, USA, 1984. 3. D. Salomon, "Handbook of Data Compression", 5th Edition, Springer-Verlag London Limited 2010. 4. Ze.Nian. Li and M.S. Drew, "Fundamentals of Multimedia", 2nd Edition, Pearson Education (Asia) Pvt. Ltd., 2004. 5. M.Rabbani: "Digital image compression techniques", 1st Edition, SPIE Press Book, 1991.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers			
Experts from Industry		Experts from Higher Technical Institutions	
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2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com		2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	
		Internal Experts	
		1. Dr. S. Dhanalakshmi, SRMIST	
		2. Mrs. K. Harisudha, SRMIST	

Course Code	18ECE342T	Course Name	ACOUSTICAL SIGNAL PROCESSING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18ECE245T	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering			Data Book / Codes/Standards	ISO/TC 43/SC 1, ISO/TC 43/SC 2

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
					1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
					Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-1 :		learn what is acoustic and its basic sound equations, and how acoustics transmission, reflection, absorption when subjected to various mediums																				
CLR-2 :		learn how does human auditory system and hearing function.																				
CLR-3 :		learn what is acoustic echo, and how to control such echo due to noise and cancel echo using various algorithms.																				
CLR-4 :		learn what are the various types of transducers used for acoustic measurements																				
CLR-5 :		know which transducers can be used in various applications of acoustics.																				
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :		To understand the basics of acoustic such as Sound equation, Transmission, Reflection, Absorption under various mediums			L1	80	65	M											H	H	M	H
CLO-2 :		To acquire knowledge on human auditory system and hearing			L1	85	65	M											H	H	M	H
CLO-3 :		To understand and analyze acoustic echo, noise control and cancel echo using various algorithms.			L1, L2	85	65	H	H	H	H	H							H	M	M	H
CLO-4 :		To understand about various types of transducers used for acoustic measurements			L1	85	65	M	H	H												
CLO-5 :		To gain knowledge on various applications of acoustics.			L1, L3	85	65		H		H								H	H	M	M
CLO-6 :		Speech processing analysis in different environment			L1, L2, L3	85	65	H	H	H	H	H							H	H	H	M

Duration (hour)		Basics of Acoustic Engineering	Auditory System and Hearing	Acoustic Echo and Noise control	Transducers for Acoustic Measurements	Applications of Acoustics
		9	9	9	9	9
S-1	SLO-1	Introduction to acoustic	Anatomy of the auditory systems	Human Perception of Echoes	Fundamental properties of Transducers	Architectural acoustics – Sound in enclosures
	SLO-2	Introduction to acoustic	Anatomy of the auditory systems	Human Perception of Echoes	Fundamental properties of Transducers	Reverberation time
S-2	SLO-1	Harmonic Plane Waves	Physiology of the auditory systems	Echo Problem	Condenser Microphones	Sound absorption materials
	SLO-2	Harmonic Plane Waves	Physiology of the auditory systems	Echo Problem	Condenser Microphones	Measurements of acoustic output in living rooms
S-3	SLO-1	Energy Density	Function of the auditory systems	Adaptive Filters for Echo Cancellation	Dynamic Pressure Microphones	Acoustic Factors in architectural design
	SLO-2	Energy Density	Function of the auditory systems	Adaptive Filters for Echo Cancellation	Dynamic Pressure Microphones	Environmental acoustics – Introduction
S-4	SLO-1	Acoustic Intensity	Physiological measures	LMS algorithm	Dynamic Pressure Microphones	Weighted sound level
	SLO-2	Specific Acoustic Impedance	Physiological measures	NLMS algorithm	Dynamic Pressure difference Microphone	speech interference
S-5	SLO-1	Spherical Waves	Physiological measures	Least Squares Algorithms	Dynamic Pressure difference Microphone	Highway noise

	SLO-2	Spherical Waves	Auditory processing models	Least Squares Algorithms	Piezo ceramic accelerometer	Aircraft noise rating
S-6	SLO-1	Decibel Scales	Auditory processing models	Recursive Least Squares Algorithms	Piezo ceramic accelerometer	Virtual Sound--
	SLO-2	; Rays and Waves	Auditory processing models	Recursive Least Squares Algorithms	Piezo ceramic accelerometer	Sound localization cues
S-70	SLO-1	Transmission-Incidence	Auditory processing models	Affine Projection algorithm	Laser Doppler velocimeter	synthetic 3D Audio
	SLO-2	Transmission-Incidence	Auditory processing models	Affine Projection algorithm	Laser Doppler velocimeter	synthetic 3D Audio
S-8	SLO-1	Reflection	Speech Intelligibility	Noise cancellation using Affine Projection algorithm	Laser Doppler velocimeter	Seismology- Signal Model in seismic processing
	SLO-2	Absorption	Speech Intelligibility	Noise cancellation using Affine Projection algorithm	Capacitive sensors	Optical sensor Signal Model in seismic processings
S-9	SLO-1	Viscosity	signal processing in hearing aids	Fast Affine Projection Algorithm (FAP).	Capacitive sensors	Underwater and Oceanographic acoustics
	SLO-2	Thermal conduction	signal processing in hearing aids	Fast Affine Projection Algorithm (FAP)	Capacitive sensors	Inverse Problems in underwater acoustics

Learning Resources	1. Lawrance E Kinseler, <i>Fundamental of Acoustic</i> , , Wiley 4 th Edition. 2. Steven L. Gay, Jacob Benesty, <i>Acoustic Signal Processing for TeleCommunication</i> , Springer; 2001 edition (March 31, 2000)	3. Havelock, David; Kuwano, Sonoko, Vorländer, Michael (Eds.), <i>Handbook of Signal Processing in Acoustics</i> , Springer; 2008 edition.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	--	30 %	--	30 %	--	30 %	--	30 %	--
	Understand										
Level 2	Apply	40 %	--	40 %	--	40 %	--	40 %	--	40 %	--
	Analyze										
Level 3	Evaluate	20 %	--	30 %	--	30 %	--	30 %	---	30 %	--
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers			
Experts from Industry		Experts from Higher Technical Institutions	
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2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com		2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	
		Internal Experts	
		1. Dr. S. Dhanalakshmi, SRM IST	
		2. Dr. Damodar Panigrahy, SRMIST	

Course Code	18ECE343T	Course Name	AUTOMATIC SPEECH RECOGNITION	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18ECE241J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1:	Understand the basic Techniques of Speech Recognition	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2:	Analyze the different Statistical models	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3:	Modeling different speech recognition systems	Expected Proficiency (%)	Problem Analysis
CLR-4:	Evaluation of dialogue system design	Expected Attainment (%)	Design & Development
CLR-5:	Analyzing the Stochastic Approaches to dialogue		Analysis, Design, Research
CLR-6:	Utilize the concepts in signal processing for the understanding of engineering and technology		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1:	Understand the basic techniques in speech signal processing broadly used in the area of speech recognition	2 80 63	H H - - - - - - - - - - - - - - - -
CLO-2:	Learn how hidden Markov models can be used as generative models for speech and how they can be trained	2 85 68	H H - - - - - - - - - - - - - - - -
CLO-3:	To help in understanding account for commercial as well as research-oriented applications within speech recognition	2 75 68	H - - H - - - - - - - - - - - - - - -
CLO-4:	To understand basic understanding of dialogue system design and evaluation	2 85 68	H H - - - - - - - - - - - - - - - -
CLO-5:	Implement simple dialogue systems and Stochastic Approaches	2 85 68	H - H - - - - - - - - - - - - - - -
CLO-6:	Apply the speech recognition techniques in real time applications.	2 80 68	H - - - - - - - - - - - - - - - -

Duration (hour)	Distance Measurements For Comparing Speech Patterns	Statistical Models For Speech Recognition	Architecture of Continuous Speech Recognition System	Understanding of Spoken Dialogue Systems	Natural Language Generation and Stochastic Process
	9	9	9	9	9
S-1	SLO-1 Feature, Feature Extraction and Pattern Comparison Techniques	Introduction to Perceptual Motivated Representations	Introduction to speech recognition	Simple models of dialogue structure:	Natural language generation for dialogue systems
	SLO-2 Feature, Feature Extraction and Pattern Comparison Techniques	Perceptual Motivated Representations	Introduction to speech recognition	Simple models of dialogue structure:	Natural language generation for dialogue systems
S-2	SLO-1 Speech Distortion measures-Mathematical	Formant Frequencies – Role of Pitch – Pitch Detection of Speech and Music	Large vocabulary continuous speech recognition	Trees and finite state approaches	Text-to-speech synthesis
	SLO-2 Speech Distortion measures-Mathematical	Formant Frequencies – Role of Pitch – Pitch Detection of Speech and Music	Large vocabulary continuous speech recognition	Trees and finite state approaches	Text-to-speech synthesis
S-3	SLO-1 Perceptual-Log spectral distance	Channel Vocoders and Predictive Coding Scalar Waveform Coders	Architecture of large vocabulary continuous speech recognition system	Dialogue acts, key phrase reactive approaches	Use of speech synthesizers in dialogue systems
	SLO-2 Perceptual-Log spectral distance	Channel Vocoders and Predictive Coding Scalar Waveform Coders	Architecture of large vocabulary continuous speech recognition system	Dialogue acts, key phrase reactive approaches	Use of speech synthesizers in dialogue systems
S-4	SLO-1 Cepstral Distances, Weighted Cepstral distances and Filtering	Scalar Frequency Domain Coders	Architecture of large vocabulary continuous speech recognition system	Information retrieval-based approaches	Dialogue system evaluation
	SLO-2 Likelihood Distortions	Code excited linear Prediction	Architecture of large vocabulary continuous speech recognition system	Information retrieval-based approaches	Dialogue system evaluation
S-5	SLO-1 Spectral distortion using a Warped Frequency scale	Low – Bit rate Speech coders	Acoustics model	Voice XML	Stochastic approaches to dialogue
	SLO-2	Speech Recognition			
S-6	SLO-1 LPC, PLC and MFCC Coefficients	Hidden Markov Models (HMM) – Practical Issues in Using HMMs – HMM Limitations	Language model	Speech recognition	Dialogue policy design and training

	SLO-2	LPC, PLC and MFCC Coefficients	Hidden Markov Models (HMM) – Practical Issues in Using HMMs – HMM Limitations	Language model	Speech recognition	Dialogue policy design and training
S-7	SLO-1	Time Alignment and Normalization	Acoustic Modeling – Phonetic Modeling, Language Modeling	n-gram model	Use of speech recognizers in dialogue systems	MDP reinforcement learning
	SLO-2	Time Alignment and Normalization	Acoustic Modeling – Phonetic Modeling, Language Modeling	n-gram model	Use of speech recognizers in dialogue systems	MDP reinforcement learning
S-8	SLO-1	Dynamic Time warping	Speaker Recognition Algorithm	context dependent sub word units	Natural language understanding	POMDP reinforcement learning
	SLO-2	Dynamic Time warping	Speaker Recognition Algorithm	context dependent sub word units	Natural language understanding	POMDP reinforcement learning
S-9	SLO-1	Multiple Time-Alignment Paths	Signal Enhancement for Mismatched Conditions	Applications and present status	Natural language understanding	Simulated users
	SLO-2	Multiple Time-Alignment Paths	Signal Enhancement for Mismatched Conditions	Applications and present status	Natural language understanding	Simulated users

Learning Resources	<ol style="list-style-type: none"> Huang, A. Acero, H-W. Hon, "Spoken Language Processing: A guide to theory, algorithm and system development", Prentice Hall 2001 Rabiner and Juang, "Fundamentals of Speech Recognition", Prentice Hall, 1993 F. Jelinek, "Statistical Methods for Speech recognition", MIT Press, 1997 Jurafsky, Daniel, and James H. Martin, "Speech and Language Processing: An Introduction to Natural Language Processing, Speech Recognition, and Computational Linguistics", 2nd edition. Prentice-Hall, 2009. Jokinen and McTear, "Spoken Dialogue Systems, Morgan & Claypool, Synthesis Lectures on Human Language Technologies", Morgan & Claypool Publishers, 2009
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

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Course Code	18ECE360T	Course Name	REHABILITATION ENGINEERING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering		Data Book / Codes/Standards		Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1:	Learn concepts and terminologies in Rehabilitation Engineering	1	2	3	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Understand different types of wheel chair design and mobility aids	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3			
CLR-3:	Study the components of orthotic and prosthetic devices and their fabrication																					
CLR-4:	Become aware of Engineering concepts in sensory substitution and augmentation																					
CLR-5:	Understand the legal concepts in Rehabilitation Engineering																					
CLR-6:	Study the contemporary topics in Rehabilitation Engineering																					
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																					
CLO-1:	Understand the need for rehabilitation Engineering and proficiently use terminologies related to it.	1,2	80	70						M								L	L			
CLO-2:	Know the various wheel chair design and mobility aid design aspects	1,2	75	65	M		L			L									L	L		
CLO-3:	Learn about orthotic and prosthetic devices, their design and types.	2	70	65	L		L				L								L			
CLO-4:	List the various possibilities to augment or substitute visual and auditory capabilities	2,3	70	65	M	M	L													L		
CLO-5:	Describe the legal concepts in Rehabilitation Engineering	3	80	65						M	M											L
CLO-6:	Gain exposure to the latest topics in Rehabilitation Engineering	3	80	65	M	L	L	M		L									L	M	L	

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduce to Rehabilitation Engineering and Assistive technologies	Interventions in seating system	Amputation: Definition, need, situations where it can be avoided	Basic structure of eye, How it functions, problems that can be faced	Application of robots in rehabilitation
	SLO-2	Learn Concepts of Rehabilitation Engineering	Wheel Chairs-Introduction	Classification of amputation	Categories of visual impairment, identification of level of intervention needed	Types of robots used
S-2	SLO-1	Learn Terminologies Rehabilitation Engineering	Types of Wheelchairs	Prosthetics: Definition, Need for prosthesis	Artificial Eye-Complete replacement	Challenges in robot design for differently abled people
	SLO-2	Considerations for Rehabilitation Engineering	Describe on Manual wheelchairs	Use of prosthesis, Where prosthesis can't be used	Retinal implant	Differences in material used
S-3	SLO-1	Various approaches for Rehabilitation engineering	Component Design	Basic types of prosthesis, Prosthesis Prescription	Sensory augmentation for blind	Functional electrical stimulation definition,
	SLO-2	PAD process	Electrical Power wheel chairs	Prosthesis for shoulder, neck, torso	Cortical prosthesis	Circuit for stimulations
S-4	SLO-1	PHAATE model	Power assisted wheelchair-Design	Prosthesis for elbow, arm	Assist devices for visual rehabilitation	Significance of myoelectic signal
	SLO-2	Universal design- Introduction	Design types	Fabrication and issues involved	Auditory devices	Acquisition of myoelectic signal, challenges
S-5	SLO-1	Seven Principles of Universal design	Wheelchair transportation	Parts of Lower extremity	Devices for navigation, Design of navigation device	Activities of daily living
	SLO-2	Benefits of Universal design	Lift Mechanism	Significance of each part, Different movements involved	Tactual sensory substitution, Applications and examples of tactual substitution in real life	Low tech and hi tech aids in daily living
S-6	SLO-1	Universal design Matrix	Wheelchair safety	Prosthesis for knee, hip	Main part of ear, Measurement of hearing	Neural engineering

	SLO-2	Design based on human ability	Wheelchair standards and tests	Material used for fabrication, examples of available prosthesis	Problems that can arise, Range of hearing	Implementation in rehabilitation
S-7	SLO-1	Standards for assistive technology- National and International	Intelligent Mobility aids	Orthosis: Definition, Difference between orthosis and prosthesis	Surgical hearing aids	Behavioural disorders and its types
	SLO-2	Role of Rehabilitation Engineering in standards development	Smart wheeled walkers	Orthosis for shoulder, neck	Cochlear and eardrum interventions	Rehabilitation methods involves
S-8	SLO-1	Rehabilitation Engineering and its research opportunities	All terrain wheelchair	Orthosis for foot, Material used: the problems faced with the material	Non surgical hearing aids	Sports rehabilitation
	SLO-2	Future of Engineering in Rehabilitation	Current directions in wheelchair research	Components of lower limb prosthesis	Design of a simple external hearing aid	Measurement technology for sports mechanics
S-9	SLO-1	Seating and common pathologies	Parts of Upper extremity	External circuitry design and support system	Sign language	Legal aspect in rehabilitation
	SLO-2	Seating assessment	Significance of each part, Different movements involved	Identifying the orthosis and prosthesis which can be used Practice session: student to identify the area of amputation and what to use in that location	Devices for sign language translation	Provision for rehabilitation

Learning Resources	<ol style="list-style-type: none"> 1. Rory A Cooper, Hisaichi Ohnabe, Douglas A Hodson, "An Introduction to Rehabilitation Engineering", CRC Press, First edition, 2006 2. Rory A Cooper, "Rehabilitation Engineering Applied to Mobility and Manipulation", CRC Press, First edition, 2010 3. Horia-Nicolai L. Teodorescu, Lakshmi C. Jain, "Intelligent Systems and Technologies in Rehabilitation Engineering", CRC Press, First Edition, 2010. 4. Marion A Hersh, Michale A Johnson, "Assistive Technology fo Visually impaired and blind people", Springers Publications, First edition 2008. 5. Suzanne Robitaille, "The illustrated guide to Assistive technology and devices-Tools and gadgets for living independently", Demos Health Newyork, First edition, 2010.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Sathyanarayanan J, Mindray Medical India Pvt Ltd, sathyanarayananjayagopal@mindray.com	1. Dr. S. Poonguzhali, Anna University, poongs@annauniv.edu	1. Dr. Varshini karthik, SRMIST
2. Mr. Anuj Kumar, Bombardier Transportation, Ahmedabad, kumaranuj.anii@gmail.com	2. Dr. Meenakshi, Professor of ECE, CEG, Anna University, meena68@annauniv.edu	2. Mrs. A. Bhargavi haripriya, SRMIST
3. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	3. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	

Course Code	18ECE361T	Course Name	BIOMEDICAL NANOTECHNOLOGY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)															
CLR-1 :	Learn the different synthesis method and its application		Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Apply the various characterization techniques in nano materials																				
CLR-3 :	Comprehend the principles behind nanomedicine																				
CLR-4 :	Gain a broad understanding of concepts and applications of nanomedicine																				
CLR-5 :	Apply concepts of nanomedicine to a focused clinical area of their choice																				
CLR-6 :	Acquire knowledge to apply these nanosystems for the diagnosis and therapy.																				
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:	3	80	75	M	-	-	L	-	-	-	-	-	-	-	-	-	L	-	L
CLO-1 :	Analyze the suitable method in biomedical application		3	80	70	L	-	-	L	-	-	-	-	-	-	-	-	-	L	-	L
CLO-2 :	Identify the various characterization techniques in nano materials		3	75	70	L	-	-	L	-	-	-	-	-	-	-	-	-	L	-	L
CLO-3 :	Describe the properties and techniques in nano biomaterials		3	80	75	M	-	-	M	-	-	-	-	-	-	-	-	-	L	-	L
CLO-4 :	Analyze the concept of nano therapeutics and application in biomedical		3	80	70	M	-	-	M	-	-	-	-	-	-	-	-	-	L	-	L
CLO-5 :	Identify the principle behind modern bio nano imaging techniques		3	80	70	M	-	-	M	-	-	-	-	-	-	-	-	-	L	-	L
CLO-6 :	Apply the nano materials in 3D printing techniques		3	80	70	M	-	-	M	-	-	-	-	-	-	-	-	-	L	-	L

Duration (hour)		Synthesis of nano material	Nano materials characterization techniques	Nano biomaterials	Nano therapeutic	Nano biomedical imaging and 3D Bio printing techniques
		9	9	9	9	9
S-1	SLO-1	Introduction About Nano technology	Introduction to Scanning electron microscope(SEM)	Introduction to nano biomaterials	Drug to delivery to central nervous system	Introduction to biomedical imaging
	SLO-2	Bulk synthesis:	Application of scanning electron microscope	Surface and bulk properties of biomaterials	Drug delivery across blood brain barrier	The emergence of nanoparticle as imaging platform in medicine
S-2	SLO-1	Top down and bottom approaches	Energy dispersive spectroscopy (EDS)	Nano biomaterials, Nano bio ceramics	Nano wire monitoring the brain activity	Magnetic resonance imaging basics
	SLO-2	Physical vapour deposition methods	Basics principle of atomic microscopy	Hydroxyapatite ant its properties	Introduction to Nano robot medical device	MRI working ,paramagnetic contrast agents
S-3	SLO-1	Electron beam evaporation techniques	Construction, working and application of atomic microscopy	Hydroxyapatite ant its applications	Application of Nano robot medical device	Magnetic Nano sensor
	SLO-2	Pulsed laser deposition	Introduction to transmission electron microscopy	Alumina and its properties ,application	Introduction to nano drug carrier	Radio labeled nano particles.
S-4	SLO-1	Sputtering techniques	Application of transmission electron microscopy	Zirconia and Titania and its properties	Nano carrier for ocular drug delivery	Sound waves nano particle

	SLO-2	Evaporation techniques	Scanning probe microscope	Zirconia and Titania and its applications	cell therapy for myocardial infection	Application in ultra sound imaging
S-5	SLO-1	Cathodic arc deposition	Nano indentation techniques	Nano diamond carbon nano materials	Types of cell therapy for myocardial infection	Biological imaging
	SLO-2	Spin coating unit, spray pyrolysis	Cantilever array sensor	Nano diamond carbon materials and its applications.	Nano neurosurgery,	Quantum dot in optical imaging
S-6	SLO-1	Chemical vapor deposition(CVD)	Basics principle of scanning tunneling microscopy	Introduction to surface modification	nanolipoblockers	3D printing
	SLO-2	Types of chemical vapour deposition	Constriction and application of scanning tunneling microscope(STM)	Types of surface modification method	Antirestenosis drugs	Introduction and principle
S-7	SLO-1	Plasma method: Plasma enhanced CVD	Introduction about X-ray diffraction	Textured and porous materials	Introduction to nano particle drug formulations	3D printing technology :ink let based
	SLO-2	Hot filament CVD	Measurement and application of XRD	Cell biomaterials interactions	nano particle drug formulations for spray inhalations	Pressure assisted, laser assisted
S-8	SLO-1	Chemical synthesis: Sol gel processing	X-ray photon spectroscopy(XPS)	Immune response	Introduction to nano bone implants	Solenoid valve based, acoustic jet based
	SLO-2	hydrothermal,co precipitation,	Application XPS	Bone Scaffold preparations	Nano bone implants and scaffolds	3D bio printing in ceramics ,polymers
S-9	SLO-1	Wet chemical method	Electrochemical work station	Scaffold properties and its applications	Introduction to nano technology in cardio vascular system	3D bio printing in organs
	SLO-2	Hydrolysis ,Electrophoretic deposition	Application of electrochemical work station	In vitro and in vivo tissue biocompatibility	Regeneration of cardiovascular system	Challenge and future development of 3D bio printing

Learning Resources	1. Khandpur R.S, Hand-book of Biomedical Instrumentation, 2 nd ed., Tata McGraw Hill, 2003 2. Michael Giersig, Gennady B. Khomutov, "Nanomaterials for Application in Medicine and Biology", Springer, 2008 3. Jeff W.M., Bulte and Michel M.J. Modo "Nanoparticles in Biomedical Imaging Emerging Technologies and Applications", Springer, 2010	4. Guozhong Cao, "Nanostructures and Nanomaterials, synthesis, properties and applications", Imperial College Press, 2004 5. C. N. Rao, A. Muller, A. K. Cheetham "The Chemistry of Nanomaterials: Synthesis, Properties and Applications", Wiley, 2004
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

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2. Mr. Anuj Kumar, Bombardier Transportation, Ahmedabad, kumar.anuj.ani@gmail.com	2. Dr. Meenakshi, Professor of ECE, CEG, Anna University, meena68@annauniv.edu	2. Dr. D. Ashok Kumar, SRMIST
3. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	3. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	

Course Code	18ECE362T	Course Name	PHYSIOLOGICAL MODELING AND SIMULATION	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering		Data Book / Codes/Standards	Nil	

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1:	Build an engineering model based on physiological subsystems	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Implement static analysis for physiological systems	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3:	Understand time domain and stability analysis of physiological systems				M	-	-	-	-	-	-	-	-	-	-	-	M	-	-
CLR-4:	Implement frequency response analysis for physiological systems				-	M	-	-	-	-	-	-	-	-	-	-	M	-	-
CLR-5:	Identify and estimate unknown parameters in system modeling				-	M	-	-	-	-	-	-	-	-	-	-	M	-	-
CLR-6:	Represent the working of physiological systems using different modeling techniques				-	L	-	-	-	-	-	-	-	-	-	-	M	-	-
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	1,2	80	70	M	-	-	-	-	-	-	-	-	-	-	-	M	-	-
CLO-1:	Develop a more in-depth level of understanding engineering analysis for modeling physiological systems	1,2	80	70	-	M	-	-	-	-	-	-	-	-	-	-	M	-	-
CLO-2:	Perform static analysis of a system	1,2	80	70	-	M	-	-	-	-	-	-	-	-	-	-	M	-	-
CLO-3:	Perform transient and stability analysis of a system.	1,2	80	70	-	M	-	-	-	-	-	-	-	-	-	-	M	-	-
CLO-4:	Able to do frequency analysis of the system	1,2	80	70	-	M	-	-	-	-	-	-	-	-	-	-	M	-	-
CLO-5:	Understand and implement system identification techniques	1,2	80	70	-	L	-	-	-	-	-	-	-	-	-	-	M	-	-
CLO-6:	Implement the various mathematical modeling techniques to physiological systems	1,2	80	70	M	-	-	-	-	-	-	-	-	-	-	-	M	-	-

Duration (hour)		Linear Model 9	Static Analysis 9	Time Domain Analysis 9	Frequency Domain Analysis 9	System Identification 9
S-1	SLO-1	Introduction to modeling methodology, need for models, approaches to modeling	Static analysis: Open loop versus closed loop	Introduction to time domain analysis	Frequency response: Open loop frequency response	Identification of physiological control system
	SLO-2	Model identification, model validation and Simulation	Loop gain calculation: Room temperature control	Linearized respiratory mechanics transient response	Closed loop frequency response	Basic problems in Physiological system analysis
S-2	SLO-1	System analysis, fundamental concepts	Steady state characteristics	Linearized respiratory mechanics first order model – impulse response for open loop	Relation between transient and frequency response	Nonparametric and parametric identification methods
	SLO-2	Physiological control system an example	Determination of steady state operating point for simple model of muscle stretch reflex	Linearized respiratory mechanics first order model – impulse response for closed loop	Frequency domain specifications	Numerical Deconvolution, Least square estimation
S-3	SLO-1	Engineering control system versus physiological control system	Human body Glucose – Insulin regulatory system	Transient response descriptors : Impulse response	Graphical representation of frequency response: Bode plot	Estimation using correlation functions
	SLO-2	Science of modeling	Steady state analysis of glucose –insulin model	Transient response descriptors : Step response	Bode plot :Linearized lung mechanics	Estimation in frequency domain, optimization techniques
S-4	SLO-1	Generalized system properties	Human body chemical regulation of ventilatory system	Concept of sliding theory	Graphical representation of frequency response: Nicholas chart	Problems in parameter estimation
	SLO-2	Models with combinations of system elements	Mechanism of respiration	Neuromuscular reflex action	Nicholas chart : Linearized lung mechanics	Input design
S-5	SLO-1	Linear model of respiratory mechanics	Gas exchanger mathematical modeling	Mathematical model of neuromuscular reflex motion	Graphical representation of frequency response : Nyquist plot	Identification of closed loop systems – “opening the loop”

	SLO-2	Linear model of respiratory mechanics: Derivation of transfer function	Respiratory controller mathematical modeling	Calculation of transfer function	Nyquist plot: Linearized lung mechanics	Starling heart- lung preparation
S-6	SLO-1	Linear model of muscle mechanics	Closed loop analysis : lung and controller	Stability and transient response	Introduction : Circulatory system	Kao's cross – circulation experiment
	SLO-2	Linear model of muscle mechanics: Derivation of transfer function	Calculation of transfer function	Root locus and Routh-Hurwitz stability criterion	Mathematical model of circulatory system	Artificial brain perfusion for partitioning central and chemo reflexes
S-7	SLO-1	Distributed versus lumped parameter model	Heart and systemic circulation	Stability analysis: root locus method	Frequency response of circulatory system	Voltage clamp
	SLO-2	Distributed versus lumped parameter model: Derivation of transfer function	Mathematical modeling of cardiac output	Introduction to Nyquist plot	Graphical representation for frequency response of circulatory system	Opening the Pupillary reflex loop, Read rebreathing technique
S-8	SLO-1	Linear system and superposition principle	Calculation of transfer function for simplified model of cardiac output regulation	Nyquist criterion for stability	Frequency response of glucose – insulin model	Identification under closed loop condition
	SLO-2	Laplace transform and transfer function	Cardiac characteristics curve analysis	Relative stability theory	Mathematical model and simulation of glucose – insulin model	Minimal model of blood glucose regulation
S-9	SLO-1	Impulse function analysis	Venous return curve	Physiology: Pupillary reflex control	Frequency response approach to pupil control	Optimization : Introduction
	SLO-2	Basics of Linear convolution	Closed loop analysis of heart and systemic circulation	Mathematical modeling and stability analysis of pupillary reflex control	Frequency response characteristics curve for pupillary control	Optimization in systems with negative feedback

Learning Resources	<ol style="list-style-type: none"> 1. Michael C.K. Khoo, "Physiological Control Systems - Analysis, Simulation and Estimation", Prentice Hall of India Private Ltd., 2nd edition, New Delhi, 2001. 2. V.Z. Marmarelis, "Advanced Methods of Physiological System Modeling", Vol.3, Springer Science and Business Media, 2013. 3. Claudio Cobelli Ewart Carson, , "Introduction to Modeling in Physiology and Medicine", Academic press series, 1st edition, 2008. 4. Johnny T. Ottesen, Mette S. Olufsen, Jesper K. Larsen, "Applied Mathematical Models in Human Physiology", Vol.9, SIAM, 2004. 5. Dorf, "Modern Control Systems", Pearson Education India, 1st edition, 2008
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

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3. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	3. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	

Course Code	15EC363J	Course Name	MEDICAL IMAGE PROCESSING	Course Category	E	Professional Elective	L	T	P	C
							2	0	2	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand the fundamental image operations and image transforms	1	2	3	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Apply various image enhancement techniques in enhancing the medial images	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3			
CLR-3 :	Analyze the various types of image segmentation algorithms																					
CLR-4 :	Gain knowledge in Image compression and image registration methods																					
CLR-5 :	Understand the image reconstruction techniques used in reconstruction of medical images																					
CLR-6 :	The learner gains knowledge in Image retrieval and digital image watermarking																					
Course Learning Outcomes (CLO):																						
CLO-1 :	Describe the 2D Sampling theory and different types of image transforms	1, 2	80	70	M																	
CLO-2 :	Implement the image enhancement techniques for improving the quality of medical images	2	80	70	M																	
CLO-3 :	Apply the different image segmentation algorithms for various medical applications	2	80	70			M		M										M			L
CLO-4 :	Differentiate and analyze the various image compression and registration algorithms	3	80	70					M													
CLO-5 :	Analyze the various image reconstruction methods used for medical images	3	80	70	M														M			L
CLO-6 :	Illustrate the concepts of wavelet transform and digital image water marking	3	80	70	M																	

Duration (hour)		Fundamental Image Operations and Transforms	Image Enhancement methods	Image Segmentation Algorithms	Image compression and image registration methods	Image Reconstruction Methods
		12	12	12	12	12
S-1	SLO-1	Elements of Visual Perception- structure of human eye and image formation	Basic gray level transformation- image negative, intensity slicing techniques	Morphological operations-Erosion	Image compression-Introduction	Image reconstruction from projections- Radon transform- derivation
	SLO-2	Brightness range adaptation and discrimination	Contrast stretching, dynamic range compression and bit plane slicing	Dilation	Types of redundancies	Properties
S-2	SLO-1	Image sampling-2D sampling Theory	Histogram equalization	Image opening	Huffman coding technique	Inverse radon transform- convolution back projection
	SLO-2	Reconstruction from its samples	Histogram specification	Image closing	Procedure	Filter back projection
S 3-4	SLO-1	Lab1: Basic operations on images	Lab4: Gray transformation and histogram equalization	Lab 7: Morphological operations	Lab 10: Image compression	Lab 13: Image reconstruction from projection data
	SLO-2					
S-5	SLO-1	Quantization- optimal mean square quantizer	Image smoothening in spatial domain – Low pass filter	Edge detection- Marr hildreth edge detector	Image registration- Introduction	Digital implementation of filter back projection- Block diagram
	SLO-2	Uniform quantizer	Median filter	Algorithm	Dimensionality transformation	Algorithm
S-6	SLO-1	Neighborhood pixel relationships-adjacencies	Image sharpening in spatial domain – High pass filter, high boost filter	Canny edge detection- smoothing	Rigid registration algorithm	Wavelet transform-Introduction

	SLO-2	Distance measures	Derivative filters	Non maxima suppression and thresholding	Rigid registration algorithm	Algorithm
S 7-8	SLO-1	Lab2: Image transforms in spatial domain	Lab 5: Image smoothening using suitable filters	Lab 8: Edge detection techniques	Lab 11: Image registration	Lab 14: Wavelet transform
	SLO-2					
S-9	SLO-1	Image transform –DFT, DCT	Image smoothening in frequency domain	Thresholding –basics	Registration of MRI and PET images	Digital image watermarking-Introduction
	SLO-2	Properties	Image sharpening in frequency domain	Global thresholding algorithm	Clinical applications	Applications
S-10	SLO-1	Haar Transform	Color image processing-Introduction	Region based segmentation-region growing algorithm	Registration of MRI and CT images	Image retrieval-Introduction
	SLO-2	Properties	Color models	Region splitting and merging algorithm	Clinical applications	Content based image retrieval
S 11-12	SLO-1	Lab3: Image transforms in frequency domain	Lab 6: Image sharpening using suitable filters	Lab9: Image segmentation using Thresholding	Lab 12: Fusion of MRI and CT images	Lab 15: Digital image watermarking
	SLO-2					

Learning Resources	1. Rafael C., Gonzalez and Richard E. Woods, "Digital Image Processing", Pearson Education Asia, Third Edition, 2007	3. Joseph V.Hajnal, Derek L.G.Hill, David J Hawkes, "Medical image registration", Biomedical Engineering series, CRC press,2001.
	2. Anil.k.Jain, "Fundamentals of Digital image processing", Prentice Hall of India, 2 nd edition 1997.	

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Total	100 %		100 %		100 %		100 %		-	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

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Course Code	18ECE364T	Course Name	BODY AREA NETWORK AND MOBILE HEALTHCARE	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18ECC205J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering		Data Book / Codes/Standards		Nil

Course Learning Rationale (CLR):		The purpose of the learning this course is to:	Learning		
CLR-1 :	Comprehend technical information and challenges in WBAN.		Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)
CLR-2 :	Describe the hardware requirements of BAN				
CLR-3 :	Review the wearable sensors and standards for BAN				
CLR-4 :	Describe the mobile devices that is available for health care				
CLR-5 :	Summarize the possible and latest applications of mobile healthcare				
CLR-6 :	Learn about context-aware health care applications				
Course Learning Outcomes (CLO):		At the end of this course, learns will be able to :			
CLO-1 :	List out the BAN challenges		1	80	75
CLO-2 :	Identify the hardware necessary for BAN		1	80	75
CLO-3 :	List and describe the various wearable sensors		1,2	80	75
CLO-4 :	Appreciate the mobile devices available for healthcare		1.2	80	75
CLO-5 :	List the latest applications and research opportunities with mobile healthcare.		2	80	75
CLO-6 :	Think about context-aware health care solutions		3	80	75

Program Learning Outcomes (PLO)														
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
	L													
L														
	L											L		
L														
													L	
														M

Duration (hour)	9	9	9	9	9
S-1	SLO-1 <i>BAN-Definition</i>	<i>Processor in BAN</i>	<i>RF Communication</i>	<i>Sensors for wearable system</i>	<i>Mobile health technologies</i>
	SLO-2 <i>Terminologies used with BAN</i>	<i>Low Power MCUs</i>	<i>RF Communication in and around the body</i>	<i>Wearable system design for specific applications</i>	<i>Mobile nutrition tracking</i>
S-2	SLO-1 <i>Technical Challenges</i>	<i>Mobile Computing MCU</i>	<i>Antennal Design</i>	<i>Wearable system for ECG monitoring,</i>	<i>Accessing existing virtual electronic patient record</i>
	SLO-2 <i>Sensor design concepts</i>	<i>Integrated processor</i>	<i>Antenna testing</i>	<i>Wearable system for EEG monitoring,</i>	<i>Mobile personal health records,</i>
S-3	SLO-1 <i>Types of sensors</i>	<i>Radio transceiver along with the processor</i>	<i>Propagation issues</i>	<i>Wearable system for Gait analysis</i>	<i>Monitoring hospital patients,</i>
	SLO-2 <i>Biocompatibility issues</i>	<i>Integrated processor with Memory</i>	<i>Base Station considerations</i>	<i>Evaluation of general performance</i>	<i>Sensing vital signs</i>
S-4	SLO-1 <i>Energy Requirements</i>	<i>Antenna for BAN</i>	<i>Network topology</i>	<i>Evaluation of night time performance</i>	<i>Transmission using wireless networks</i>
	SLO-2 <i>Energy supply</i>	<i>Antenna Requirements</i>	<i>Stand – Alone BAN</i>	<i>Evaluation parameters</i>	<i>Continuous monitoring</i>

S-5	SLO-1	Nodes, number of node	Antenna Considerations	Wireless personal Area Network	Latest health monitoring methods	Patient Monitoring and wearable devices
	SLO-2	Optimal node placement in BAN	Types of antenna	Wireless personal Area Network Technologies	Smart phone based health care monitoring system	Patient Monitoring in Diverse Environments
S-6	SLO-1	System security	Wire antenna	IEEE 802.15.1	Phone based fall risk prediction	A framework for Capturing Patient Consent in Pervasive Healthcare Applications
	SLO-2	System Reliability	Ceramic antenna	IEEE P802.15.13	Emergency alerts	M-health application
S-7	SLO-1	BAN Standards	External antenna	IEEE 702.15.14	RFID based personal mobile medical assistance	Context aware sensing
	SLO-2	BAN with other standards	Sensor Interface	Zigbee	Other similar technologies	Technology Enablers for context-Aware healthcare Applications
S-8	SLO-1	BAN Architecture	Considerations on the interface	BAN and WBAN technologies	Infusing image processing capabilities	Case study I
	SLO-2	BAN and other technologies	Power sources- Batteries	Limitations in use	Secure medical sensor network with HIP	Case study I
S-9	SLO-1	BAN and Healthcare	Fuel cells for sensor nodes.	Coexistence issues with BAN	Diagnostic applications	Case study II
	SLO-2	Medical Applications of BAN	Other novel power sources	Other practical considerations	Therapeutic applications	Case study II

Learning Resources	<ol style="list-style-type: none"> 1. Annalisa Bonfiglio, Danilo De Rossi, "Wearable Monitoring Systems", Springer, 2011. 2. Philip Olla, Josep Tan, "Mobile Health solutions for Biomedical applications", Medical Information science reference, Hershey New York, IGI Global 2009. 3. Zhang, Yuan-Ting, Wearable Medical Sensors and systems, Springers, 2013. 4. Guang-Zhogn Yang(ED), "Body Sensor Networks", Springers, 2013 5. Mehmet R. Yuce Jamil Y.Khan, "Wireless Body Area Networks Technology, Implementation and applications", Pan Standford Pte. Ltd., Singapore, 2012 	<ol style="list-style-type: none"> 6. Konstantina, James C. Lin, Dimitrios, Maria Teresa, "Wireless mobile Communication and healthcare", Secon International ICST conference, Mobihealth 2011, Springers 2011. 7. Ullah, Sana, Et al, "A review of wireless body area networks for medical applications", arXiv: 1001.083, 2010 8. Patel, Shyamal, Et al, "A review of wearable sensors and systems with application in rehabilitation", Neuroeng Rehabil 9.12, 2012, 1-17.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Sathyanarayanan J, Mindray Medical India Pvt Ltd, sathyanarayananjayagopal@mindray.com	1. Dr. S. Poonguzhali, Anna University, poongs@annauniv.edu	Dr. Varshini Karthik, SRMIST
2. Mr. Anuj Kumar, Bombardier Transportation, Ahmedabad, kumaranuj.ani@gmail.com	2. Dr. Meenakshi, Professor of ECE, CEG, Anna University, meena68@annauniv.edu	Dr. U. Snehalatha, SRMIST
3. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	3. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	

Course Code	18ECE365T	Course Name	BIO-INSPIRED HUMAN MACHINE INTERFACE	Course Category	E	Professional Electives	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Electronics and Communication Engineering			Data Book / Codes/ Standards	NIL

Course Learning Rationale (CLR):		The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1: Study the HMI design, principles and standards			1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2: Attain knowledge in optic and acoustic based HMI design			Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3: Acquire knowledge in Bioelectric interfaces																				
CLR-4: Study the brain signal based HMI design																				
CLR-5: Have an insight knowledge in advanced HMI design																				
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																		
CLO-1: Explain the basics, rules and generic design flow of HMI systems			3	80	75	M	M			L										
CLO-2: Explain and analyze the optic and Acoustic based HMI systems			3	80	70	M	M			L										
CLO-3: Analyze and discuss the bioelectric based HMI design			3	75	70	M	M			L										
CLO-4: Explain and analyze brain signal based HMI design			3	80	75	M	M			L										
CLO-5: Analyze and discuss the advances and challenges in HMI design			3	80	70	M	M			L										
CLO-6: Design a biomimetic system for neural prosthesis			3	80	75	M	M			L										

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction to HMI	Vision based HMI design-Introduction-	Bioelectric Interfaces-Introduction	Brain Computer Interfaces-Introduction	Affective Computing based HMI-Introduction
	SLO-2	Need for HMI systems	Face Recognition-Signal Acquisition	Myoelectric interfaces-Introduction	brain regions and responsibilities	Affective Computing based HMI-Data Acquisition
S-2	SLO-1	Types of HMI	Face Recognition-Data Analysis	Muscle regions and responsibilities	Active methods for measuring brain activity	Affective Computing based HMI-Data Classification
	SLO-2	Types of HMI	Vision based HMI design-Data Classification	Methods for measuring muscle activity	Active methods for measuring brain activity(Contd.)	Application of Affective Computing based HMI
S-3	SLO-1	HMI-guidelines	Gait Recognition-Signal Acquisition	Myoelectric Signal –Data Analysis	Invasive BCI	Wearable Computing-Introduction
	SLO-2	HMI-principles	Gait Recognition-Data Analysis & Classification	Myoelectric Signal –Data Analysis(Contd.)	Non-invasive BCI	Wearable Computing
S-4	SLO-1	HMI-standards	Gesture Recognition-Data Analysis & Classification	Myoelectric Signal –Data Classification	EEG based BCI	Tactile based HMI
	SLO-2	HMI-Ethical Issues	People tracking	Application of Myoelectric HMI	P300 based BCI	Tactile based HMI
S-5	SLO-1	Interaction design-basics	LED based HMI system	ECG based HMI design	VEP based BCI	Motion based HMI
	SLO-2	Interaction design-Design rules	LASER based HMI system	ECG based HMI design(Contd.)	NIRS based BCI	Motion based HMI
S-6	SLO-1	HMI Systems-Data Collection	Speech Communication	EOG based HMI design-Introduction	Application in Prosthetic Control	Biomimetic design of neural prosthesis
	SLO-2	HMI Systems-Data Analysis	Speech Communication (Contd.)	EOG based HMI design-Signal Acquisition	Application in Prosthetic Control	Biomimetic design of neural prosthesis

S-7	SLO-1	HMI Systems-Design	Fundamentals of Speech Recognition	EOG based HMI design-Signal Analysis	Neurorehabilitation	Intracranial human machine interfaces for Communication and control
	SLO-2	HMI Systems-Prototyping	Fundamentals of Speech Recognition(Contd.)	EOG based HMI design-Signal Analysis(Contd.)	Neurorehabilitation	Intracranial human machine interfaces for Communication and control
S-8	SLO-1	Evaluation of HMI Systems	Automatic Speech Recognition	EOG based HMI design-Signal Classification	Neuromarketing	Multimodal approaches for advanced HMI design
	SLO-2	Evaluation of HMI Systems	Automatic Speech Recognition(Contd.)	EOG based HMI design-Signal Classification(Contd.)	Neuromarketing	Multimodal approaches for advanced HMI design
S-9	SLO-1	Bio-inspired HMI Systems	Multimodal Interaction &Approaches	Applications of EOG based HMI	Brain controlled wheel chairs	Multimodal approaches for advanced HMI design
	SLO-2	Bio-inspired HMI Systems	Multimodal Interaction &Approaches (Contd.)	Applications of EOG based HMI (Contd.)	Brain controlled wheel chairs	Multimodal approaches for advanced HMI design

Learning Resources	1. Yvonne Rogers, Helen Sharp, Jenny Preece, "Interaction Design: Beyond Human Computer Interaction", 3rd Edition, Wiley Publisher, 2012.	4. Rajesh P. N. Rao, "Brain-Computer Interfacing : An Introduction", Cambridge University Press, 2013 5. Masaki Kurosu, Human-Computer Interaction. User Interface Design, Development and Multimodality, Springer International Publishing AG, 2017
	2. P C Yuen, Y Y Tang , P S P Wang, "Multimodal Interface For Human-Machine Communication", World Scientific, 2002. 3. Aboul-Ella Hassanien and Ahmad Taher Azar, "Brain-Computer Interfaces:Current Trends and Applications", Springer International Publishing AG, 2016.	

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

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. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	3. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	

Course Code	18ECE366T	Course Name	IMPLANTABLE BIOELECTRONICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18EES101J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
		1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-1 :	Comprehend technical information about miniaturized Implantable Biomedical devices	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-2 :	Introduce to neural interfaces and cyborgs																		
CLR-3 :	Know about implantable user interface and CMOS imaging systems																		
CLR-4 :	Learn about implantable electronics biocompatibility criteria and telemetry																		
CLR-5 :	Know the key design trends in implantable systems																		
CLR-6 :	Know the future of Biomedical Implantable systems																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)															
CLO-1 :	Describe the design of Implantable Biomedical Devices	1,2	80	75	M														
CLO-2 :	Tell about neural interfaces and cyborgs	1	80	75	L														
CLO-3 :	Describe about implantable user interface and CMOS imaging systems	1,2	80	75	M														
CLO-4 :	Tell about implantable electronics biocompatibility criteria and telemetry	1	80	75															
CLO-5 :	Consolidate on design trends in implantable systems	2,3	80	75						L	L								
CLO-6 :	Summarize the future of Biomedical Implantable systems	2,3	80	75	L													L	

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Bioelectronics-Introduction	Neural interfaces and cyborgs- introduction	Implantable user interfaces	Biotelemetry	Design trends in Biomedical Implantable systems
	SLO-2 Energy Harvesting as a Pathway to miniaturization,	Fusing Robotics with the Human Body	Design Considerations	Inductive Link for Forward Data	Design of Implant Systems-
S-2	SLO-1 Implantable Devices	Anatomy of Peripheral Nerves	Evaluating Basic Implanted User Interfaces	Wireless Power Link	Review-History
	SLO-2 Implementation of Implantable Devices	Interfacing with the periphery for recording and stimulation	Qualitative Evaluation,	Implantable device with external units	Basic Considerations and Characteristics of RF MEMS Implantable Systems-
S-3	SLO-1 RF Power Harvesting	Listening to the Brain	Medical Considerations	Implantable Telemetry Link	Legal Considerations of the Radio Frequency (RF)
	SLO-2 Matching network, rectifier,	Interfacing with the Central Nervous System	Limitations	Wideband telemetry links	Field Strength
S-4	SLO-1 Regulator and band gap reference	Electrical Modulation of the Human Nervous System	CMOS Imaging Devices	Multichannel neural recording systems	Power Levels
	SLO-2 Implant functional block	Pain Modulation	Fundamentals of CMOS Imaging	Wireless endoscope	Biocompatibility
S-5	SLO-1 Wireless Communication Link,	Electrical Modulation of Inflammation	Photo sensors,	Microelectrode Arrays	Protection of the Biomedical Implant
	SLO-2 Forward and reserve data link	Cyborgs	Log sensors	Interface Electronics	Systems-Characteristics of Biological and Medical Signals

S-6	SLO-1	<i>Payload</i>	<i>The Neuro-Tech Version</i>	<i>SPAD sensors</i>	<i>Electrode equivalent circuit</i>	<i>Design considerations of Implantable Systems, Micro power Electronic Design</i>
	SLO-2	<i>Applications</i>	<i>Biological Brains in a Robot Body</i>	<i>Artificial Retina</i>	<i>Stimulation Front Ends</i>	<i>Approaches</i>
S-7	SLO-1	<i>Locomotive Implant</i>	<i>Deep Brain Stimulation</i>	<i>Principle of Artificial Retina</i>	<i>Recording Front-Ends</i>	<i>Samples</i>
	SLO-2	<i>Implantable Cardiac Probe,</i>	<i>General Purpose Brain Implants</i>	<i>Artificial Retina Based on CMOS Imaging Device</i>	<i>Instrumentation amplifier</i>	<i>Power Supply design.</i>
S-8	SLO-1	<i>Communication power delivery</i>	<i>Brain-Computer Interfaces</i>	<i>Brain-Implantable CMOS Imaging Device</i>	<i>Improving the Biocompatibility of Implantable Bioelectronics Devices.</i>	<i>System integration</i>
	SLO-2	<i>System Overview of a Generic Bioelectronics Implant</i>	<i>Noninvasive Brain-Computer Interfaces</i>	<i>Measurement Methods for Brain Activities</i>	<i>Implantable Bioelectronics Devices Materials</i>	<i>Micro-Packages,</i>
S-9	SLO-1	<i>Circuit Design for Low-Power Signal Processing.</i>	<i>Sub dermal Magnetic Implants</i>	<i>Fiber Endoscope and Head-Mountable Device</i>	<i>Surface Composition</i>	<i>Present Challenges,</i>
	SLO-2	<i>Architecture-Level Optimization for Low-Power Data Processing</i>	<i>RF ID Implants.</i>	<i>Summary and future directions</i>	<i>Response to Implantation</i>	<i>Nano-Enabled Implantable Device for In Vivo Glucose Monitoring</i>

Learning Resources	<ol style="list-style-type: none"> 1. Evgeny Katz, "Implantable Bioelectronics Devices materials and Applications", Wiley-VCH, 2014. 2. Vinod Kumar Khanna, "Implantable Medical Electronics Prosthetics, Drug Delivery and Health Monitoring", Springer, 2016 	<ol style="list-style-type: none"> 3. Swarup Bhunia, Steve Majerus, Mohamad Sawan, Implantable Biomedical Microsystems: Design Principles and Applications", Elsevier, 2015.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		-	

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Course Code	18ECE367T	Course Name	REGULATORY AFFAIRS IN MEDICAL INSTRUMENTS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18ECC201J, 18ECE260J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering		Data Book / Codes/Standards Nil		

Course Learning Rationale (CLR):		Learning			Program Learning Outcomes (PLO)														
		1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-1 :	Understand the fundamental troubleshooting procedures and testing of basic electronic components	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-2 :	Get an idea about the fault diagnosis in analog circuits and digital ICs.				M	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLR-3 :	Acquire an idea about the basic troubleshooting procedures for biomedical equipment				M	-	-	-	-	-	-	-	-	-	-	-	M	-	-
CLR-4 :	Get an idea about the medical device classification globally and regulatory standards				-	M	-	-	-	-	-	-	-	-	-	-	M	-	-
CLR-5 :	Get an idea about the Indian perspective medical device regulatory system				-	-	H	-	-	-	-	-	-	-	M	-	M	-	-
CLR-6 :	Get an overall idea about the importance of troubleshooting and medical device classification in India				-	-	-	-	-	-	-	-	-	-	M	-	-	-	-
Course Learning Outcomes (CLO):		Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLO-1 :	Apply the common troubleshooting procedures in Electronic Equipment and Outline the testing procedures of active and passive components	1, 2	80	70	M	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-2 :	Analyze the faults in analog circuits and digital ICs	1, 2	80	70	M	-	-	-	-	-	-	-	-	-	-	-	M	-	-
CLO-3 :	Identify the problems in common biomedical equipment in hospitals when it is not working and provide a suitable solution	2	80	70	-	M	-	-	-	-	-	-	-	-	-	-	M	-	-
CLO-4 :	Outline the importance of medical device classification based on the application and ISO standards	1	80	70	-	-	H	-	-	-	-	-	-	-	M	-	M	-	-
CLO-5 :	Describe the Indian medical device regulatory system	1	80	70	-	-	-	-	-	-	-	-	-	-	M	-	-	-	-
CLO-6 :	Outline the job opportunities in regulatory affairs in India	1,2	80	70	-	-	-	-	-	-	-	-	-	-	L	-	-	-	-

Duration (hour)		Basic Troubleshooting Techniques & Testing Procedures	Fault Diagnosis in Analog, Digital Integrated Circuits and Home care device	Biomedical Machine Troubleshooting in Hospitals	Medical Device Classification and Standards	Medical Device Regulatory System in India
		9	9	9	9	9
S-1	SLO-1	Equipment failure and its types	Characteristics of ideal op-amps	Troubleshooting- ECG Machine	Global Harmonization Task Force (GHTF) definition for medical device	Importance of regulatory system
	SLO-2	Causes of Equipment failure	Typical op-amp based medical circuits	And its preventive maintenance	Medical Device Life Cycle: Identify, Characterize	Market Overview
S-2	SLO-1	Functional block diagram of a troubleshooting system	Typical op-amp based medical circuits	Troubleshooting- EEG Machine	Medical Device Life Cycle: Optimize, Verify/Validate	Overview of Regulatory Environment
	SLO-2	Functional block diagram of a troubleshooting system	Fault diagnosis in op-amp circuits	And its preventive maintenance	Global Perspective on medical device regulations: USA, European Union	Overview of Regulatory Environment
S-3	SLO-1	Troubleshooting process	Example: Inverting amplifier troubleshooting process	Troubleshooting- defibrillator, suction machine	Global Perspective on medical device regulations: Canada, Australia, Japan	Functions Undertaken by DCGI and Central Government
	SLO-2	Fault finding aids	Typical Faults in digital circuits	And its preventive maintenance	Medical device classification: USA	Functions Undertaken by the FDA and State Governments
S-4	SLO-1	Troubleshooting techniques: Preliminary Observations	Different testing methods in digital circuits: Functional Testing, DC Test	Troubleshooting- electrosurgical unit	Medical device classification: European Union, GHTF	Indian Pharmacopoeia Commission
	SLO-2	Troubleshooting techniques: Functional block diagram approach	AC Test	And its preventive maintenance	Premarket Notification 510(k), Premarket Approval	Details of Key Regulator
S-5	SLO-1	Troubleshooting techniques: Split half method	Digital IC Troubleshooter:, Logic clip, Logic probe	Troubleshooting- anesthesia machine	Standards and its need	Organization Chart — CDSCO
	SLO-2	Application of Split half method in circuit troubleshooting	Digital IC Troubleshooters: Logic pulser, Logic current tracer	And its preventive maintenance	ISO 9000 core standards: Basic overview	Role of Distributors or Local Subsidiaries

S-6	SLO-1	Troubleshooting techniques: Systematic Troubleshooting	Digital IC Troubleshooters: Logic comparator	Troubleshooting- autoclaves & sterilizers	ISO 13485: Basic overview	Product Registration
	SLO-2	Correction action	Circuit board Troubleshooting	And its preventive maintenance	ISO 14971: Basic overview	Manufacturing site and product registration: process flow chart
S-7	SLO-1	Testing of passive components: Resistors, Capacitors	Troubleshooting- oxygen concentrators	Troubleshooting- endoscope	ISO 10933: Basic overview	Quality System Regulation
	SLO-2	Testing of passive components: Inductors, Diodes, LDR	And its preventive maintenance	And its preventive maintenance	ISO 14155: Basic overview	Technical Material Requirement & Labelling Requirement of Medical Device
S-8	SLO-1	Testing of active components: BJT	Troubleshooting- sphygmomanometers, Analog Blood pressure apparatus	Troubleshooting- incubators	ISO 11607: Basic overview	Manufacturing-Related Regulation
	SLO-2	Testing of active components: JFET	And its preventive maintenance	And its preventive maintenance	ISO 11137: Basic overview	Clinical Trial-Related Regulation
S-9	SLO-1	Testing of active components: MOSFET	Troubleshooting- nebulizer	Troubleshooting- X-ray Machine	IEC 60601: Basic overview	Commercial Aspect
	SLO-2	Testing of variable resistors and its different types	And its preventive maintenance	And its preventive maintenance	IEC 62353: Basic overview	Related Agencies/Departments and Ministries

Learning Resources	<ol style="list-style-type: none"> 1. Joseph D Bronzino & Donald R Peterson, "Medical Devices and Human Engineering", CRC Press, 4th Edition, 2015 2. Myer Kutz, "Biomedical Engineering and Design Handbook- Volume 2: Applications", McGraw-Hill, 2nd Edition, 2009 3. Richard Fries, "Reliable Design of Medical Devices", CRC Press, 2nd Edition, 2006 4. Basem S EL-Haik & Khalid S Mekki, "Medical Device Design for Six Sigma: A Road Map for Safety and Effectiveness", John Wiley & Sons, 1st Edition, 2008 5. John J Tobin & Gary Walsh, "Medical Product Regulatory Affairs- Pharmaceutical, Diagnostics, Medical Devices", Wiley-Blackwell, 1st Edition, 2008 6. Norbert Leitgeb, "Safety of Electromedical Devices Law – Risks – Opportunities", SpringerWienNewYork, 1st Edition, 2010 	<ol style="list-style-type: none"> 7. "Medical Device Regulations Global overview and guiding principles", World Health Organization Geneva, 2003 8. Jack Wong and Raymond K Y Tong, "Handbook of Medical device regulatory affairs in Asia", Pan Stanford Publishing Pte. Ltd., 2nd Edition, 2018 9. Khandpur R S, "Troubleshooting Electronic Equipment- Includes Repair & Maintenance", Tata McGraw-Hill, 2nd Edition, 2009 10. Nicholas Cram & Selby Holder, "Basic Electronic Troubleshooting for Biomedical Technicians", TSTC Publishing, 2nd edition, 2010 11. Dan Tomal & Neal Widmer, "Electronic Troubleshooting", McGraw Hill, 3rd edition, 2004 12. Ministry of Health & Family Welfare, "Medical Equipment Maintenance Manual- A first line maintenance guide for end users", New Delhi, 2010

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	40 %	-	40 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	20 %	-	20 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Sathyanarayanan J, Mindray Medical India Pvt Ltd, sathyanarayananjayagopal@mindray.com	1. Dr. S. Poonguzhali, Anna University, poongs@annauniv.edu	1. Dr. Rajalakshmi S, SRMIST
2. Mr. Anuj Kumar, Bombardier Transportation, Ahmedabad, kumaranj.anii@gmail.com	2. Dr. Meenakshi, Professor of ECE, CEG, Anna University, meena68@annauniv.edu	2. Mr. Karthik Raj V, SRMIST
3. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	3. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	

Course Code	18ECE280T	Course Name	INDUSTRIAL INSTRUMENTATION	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:		
CLR-1 :	Acquire familiarity about various industrial instrumentation types, their parameters and different types of measurement techniques.			
CLR-2 :	Gain knowledge about pressure measurement techniques.			
CLR-3 :	Learn about the different techniques of measurement of flow.			
CLR-4 :	Get exposed to the various techniques of measurement of level.			
CLR-5 :	Gain knowledge about the temperature measurement techniques.			
CLR-6 :	Familiarize the measuring devices used in industrial applications.			

Learning		
1	2	3
Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)

Program Learning Outcomes (PLO)														
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
H	H	-	H	H	-	-	H	L	-	H	H	M	H	L
H	H	H	H	H	-	-	H	L	-	H	H	H	H	L
H	H	H	H	H	-	-	H	L	-	H	H	H	H	L
H	H	H	H	H	-	-	H	L	-	H	H	H	H	H
H	H	H	H	H	-	-	H	L	-	H	H	H	H	H
H	H	-	H	H	-	-	H	L	-	H	H	M	H	H

Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:		
CLO-1 :	Understand the need for measurement in industries and the basic measurement techniques.			
CLO-2 :	Elucidate the construction & working of various industrial devices used to measure pressure.			
CLO-3 :	Summarize the different methods for flow measurement.			
CLO-4 :	Illustrate the different methods for the measurement of level.			
CLO-5 :	Analyze different techniques to measure temperature.			
CLO-6 :	Analyze, formulate and select suitable sensor for the given industrial applications.			

Duration (hour)		Force, Acceleration and Speed Measurement	Pressure Measurement	Level Measurement	Flow Measurement	Temperature Measurement
		9	9	9	9	9
S-1	SLO-1	Introduction to industrial symbols and standards	Units of pressure and vacuum	Need for level Measurement	General concepts - Laminar flow, Reynolds's number	Definitions and standards
	SLO-2	Classification of industry	Need for pressure measurement	Visual level indicators	Effect of temperature and pressure on flow rate measurement	Primary and secondary fixed points
S-2	SLO-1	Definitions of Process variable	Manometer Dynamics	Purge method	Calibration of flow meters.	Calibration of thermometer
	SLO-2	Unit conversions	Types- U tube, Inclined Tube and Well type Manometers	Buoyancy method	Head type flow measurement -Principle	Different types of filled in system thermometer
S-3	SLO-1	Types of measurement required	Elastic Pressure Sensor Instruments – Bourdon Tube Pressure Gauge, Capsule Gauge	Resistance, Capacitance and inductive probes	Orifice , Venturi tube	Sources of errors in filled in systems and their compensation
	SLO-2	Detectors, probe analyzers, actuators	Diaphragm gauges, bellows and force balance type sensors	Ultrasonic type	Pitot Tubes, Flow nozzle	Bimetallic thermometers
S-4	SLO-1	Measurement of force	Electronic Pressure / DP transmitters- capacitive type	Laser type	Variable Area Flow meters-Principle	Review of RTD and Thermistors
	SLO-2	Different types of load cells – Magneto-elastic load cell, Strain gauge load cell	Piezo - resistive and resonating wire type	Optical fiber, Thermal type	Rotameters	Signal conditioning of industrial RTDs and their characteristics
S-5	SLO-1	Acceleration Measurement	Vacuum pressure Measurements- Mcleod Gauge	Radar, Radiation type	Electrical Type Flow meters-Principle	Three lead and four lead RTDs.

	SLO-2	Strain gauges, Piezoelectric	Pirani gauge	Solid level measurement	Electromagnetic type, Ultrasonic type	Thermocouples – Laws of thermocouple
S-6	SLO-1	Translational and rotational displacement using potentiometers	Thermocouple gauge	Boiler drum level measurement :- Differential pressure method	Positive displacement type	Fabrication of industrial thermocouples
	SLO-2	Differential transformers	Knudsen gauge	Hydrastep method	Nutating disc, Reciprocating piston	Commercial circuits for cold junction compensation
S-7	SLO-1	Mechanical type vibration instruments – Seismic instrument as an accelerometer	Ionization gauge- cold cathode and hot cathode types	Miscellaneous Measurement,	Mass flow meters - Coriolis type	Pyrometers: Total radiation pyrometers
	SLO-2	Vibrometer	Thermal conductivity gauge	Humidity – Dry and wet bulb psychrometers	Thermal, Impeller type	Selective radiation pyrometers
S-8	SLO-1	Speed measurement – Revolution counter	Testing and calibration of pressure gauges	Resistive and capacitive type hygrometers	Weirs, Flumes	Optical pyrometer
	SLO-2	D.C and A.C tachogenerators	Dead weight tester	Moisture measurement in solids- Conductivity sensor-Microwave and IR sensors.	Open channel flow measurement	Two colour radiation pyrometers
S-9	SLO-1	Stroboscope.	Discussion of device types and models used in practical industrial applications	Discussion of device types and models used in practical industrial applications	Discussion of device types and models used in practical industrial applications	Discussion of device types and models used in practical industrial applications
	SLO-2	Discussion of device types and models used in practical industrial applications	Installation Requirements	Installation Requirements	Installation Requirements	Installation Requirements

Learning Resources	<ol style="list-style-type: none"> 1. Liptak B.G., "Instrument Engineers Handbook (Measurement)", Chilton book Co., McGraw Hill, publishing Ltd., 19th Revised edition-2011. 2. A.K. Sawhney, "A course in Electrical and Electronic Measurements and instrumentation Dhanpatrai co., 19th Revised edition-2011. Reprint 2014 3. Patranabis D. "Principles of industrial Instrumentation", Tata McGraw Hill, 3rd Edition, New Delhi, Reprint 2010 	<ol style="list-style-type: none"> 4. Tony R. Kuphaldt, "Lessons In Industrial Instrumentation ", Version 2.02, 2014 5. Singh S. K., "Industrial Instrumentation & Control", Tata McGraw Hill, 2nd Edition, Reprint 2007 6. NPTEL video lectures on "Industrial Instrumentation" by Prof. Alok Barua, IIT Kharagpur
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. D. Karthikeyan, Controlsoft Engineering India Pvt Ltd, karthikeyan.d@controlsoftengg.in	1. Dr. J. Prakash, MIT, Chennai, prakaiit@rediffmail.com	1. Ms. N. Deepa, SRMIST
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. D. Nedumaran, Madras University, dnmaram@gmail.com	2. Dr. A. Vimala Juliet, SRMIST

Course Code	18ECE281J	Course Name	PROCESS DYNAMICS AND CONTROL	Course Category	E	Professional Elective	L	T	P	C
							2	0	2	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering		Data Book / Codes/Standards		Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																													
		1	2	3	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15															
CLR-1 : <i>Impart fundamental knowledge on the dynamics and mathematical modeling of various processes</i>		Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3																		
CLR-2 : <i>Introduce the effect of various control actions and the tuning techniques of controllers.</i>																																					
CLR-3 : <i>Impart knowledge on final control elements</i>																																					
CLR-4 : <i>Get exposed different types of advanced control schemes</i>																																					
CLR-5 : <i>Explore the computer as controller in digital control system.</i>																																					
CLR-6 : <i>Identify the different type of control schemes used in process industries and paraphrase their importance</i>																																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																																			
CLO-1 : <i>Analyze and mathematically model the process systems</i>		3	80	75	H	H	M	H	H	-	-	H	H	-	H	H	M	L	L																		
CLO-2 : <i>Select and optimize the tuning of a controller</i>		3	80	70	H	H	H	H	H	-	-	H	H	-	H	H	H	M	L	L																	
CLO-3 : <i>Demonstrate the working and application of different type of actuators and control valves</i>		3	75	70	H	H	H	H	H	-	-	H	H	-	H	H	H	M	L	L																	
CLO-4 : <i>Understand and analyze the various advanced control schemes</i>		3	80	75	H	H	H	H	H	-	-	H	H	-	H	H	H	M	H	H																	
CLO-5 : <i>Design suitable digital controllers for the process</i>		3	80	70	H	H	H	M	H	-	-	H	H	-	H	H	H	H	H	H																	
CLO-6 : <i>Recommend the right choice of control schemes for the application</i>		3	80	70	H	H	M	H	H	-	-	H	H	-	H	H	M	H	H	H																	

Duration (hour)		Process Dynamics	Control Action and Tuning of controllers	Final Control Elements	Advanced Control Schemes	Digital Control System
		12	12	12	12	12
S-1	SLO-1	<i>Need for process control</i>	<i>Basic control actions</i>	<i>I/P converter</i>	<i>Feedback and Feed-forward control</i>	<i>Introduction to state space ,Basic building blocks of computer control system</i>
	SLO-2	<i>The process control loop</i>	<i>Characteristics of ON- OFF controllers</i>	<i>P/I converter</i>	<i>Application of feed forward control in various processing units</i>	<i>Data loggers</i>
S-2	SLO-1	<i>Need for process modeling</i>	<i>Characteristics of Single speed floating controllers</i>	<i>Pneumatic actuators</i>	<i>Split-range control</i>	<i>Data acquisition systems</i>
	SLO-2	<i>Servo and Regulatory operation</i>	<i>P+I, P+D and P+I+D control modes</i>	<i>Electric actuators</i>	<i>Application of cascade control in various processing units</i>	<i>Supervisory control , SCADA, Direct digital control</i>
S-3	SLO-1	<i>Lab1: Identify the components of the process control loop.</i>	<i>Lab 4: Design the on-off, P,PI and PID controller for the Pressure Process</i>	<i>Lab 7: Determine the characteristics of I/P and P/I converter</i>	<i>Lab10: Tune the PID Controller for mathematically described process using ZN method</i>	<i>Lab13:Determine the state model for the mechanical system using MATLAB</i>
	SLO-2					
S-5	SLO-1	<i>Continuous and batch processes</i>	<i>Practical forms of PID controller</i>	<i>Control Valves</i>	<i>Inferential control</i>	<i>Review of z transforms</i>
	SLO-2	<i>Self-regulation, Degrees of freedom</i>	<i>Auto/manual transfer, Reset windup</i>	<i>Characteristic of Control Valves:- Inherent characteristics</i>	<i>Ratio control</i>	<i>Digital PID , Position and velocity form</i>
S-6	SLO-1	<i>Mathematical model of level, flow processes</i>	<i>Evaluation criteria- Quarter Decay Ratio, IAE, ISE and ITAE</i>	<i>Installed characteristics</i>	<i>Cascade control.</i>	<i>Implementation of digital controllers</i>
	SLO-2	<i>Interacting and non interacting systems</i>	<i>Selection of Time Integral performance Criteria</i>	<i>Modeling of control valves and types</i>	<i>Fuzzy controllers</i>	<i>Design of Deadbeat controller, Dahlin's controller</i>
S	SLO-1					

7-8	SLO-2	Lab 2 : Determine the characteristics of interacting system	Lab 5: Design the on-off control, P,PI and PID controller for the flow Process	Lab 8: Determine the characteristics of Pneumatically Actuated Control Valve	Lab11: Tune the PID Controller for mathematically described process using ZN open loop method	Lab14:Design the Deadbeat algorithm for the given system using MATLAB
S-9	SLO-1	Laws and assumptions governing gas process	Tuning – Process reaction curve method	Valve Positioner and its importance	Adaptive controllers	Multi-loop multivariable control , Introduction
	SLO-2	Mathematical models of pressure processes	Z-N open loop tuning techniques	Control valve sizing	Model predictive control	Interaction between control loops
S-10	SLO-1	Laws and assumptions governing thermal process	Continuous cycling method	Cavitation and flashing	Smith predictor control scheme	The Relative Gain Array (RGA)
	SLO-2	Mathematical models of thermal processes	Damped oscillation method	Selection criteria	Internal model control (IMC) ,P& I diagram	Decoupling of control loops
S 11-12	SLO-1	Lab3: Determine the characteristics of non interacting system	Lab 6: Design on-off control, P,PI and PID controller for the level Process	Lab 9: Determine the characteristics of Pneumatically Actuated Control Valve (with and without Positioner)	Lab12: Compare the responses of simple and cascade control system using MATLAB	Case study : Design of computerized multi loop controller
	SLO-2					

Learning Resources	<ol style="list-style-type: none"> Seborg ,D.E., Mellichamp, D.P., Edgar, T.F., and Doyle,F.J., III, "Process Dynamics and Control", John Wiley and Sons, 4th Edition 2016 Stephanopoulos. G' Chemical Process Control - An Introduction to Theory and Practice", Prentice Hall of India, 2nd Edition, 2015 Gopal, M., "Digital Control and State Variable Methods", Tata McGraw Hill, 2003 D.R. Coughanour, 'Process Systems analysis and Control', McGraw-Hill, 3rd Edition, 2013 Bela.G.Liptak., "Process Control and Optimization"., Instrument Engineers' Handbook., volume 2, CRC press and ISA, 2005 Curtis D. Johnson Process Control Instrumentation Technology, 8th Edition, Pearson, 2006 NPTEL video lectures on "Chemical Process Control" by Prof. SujitJogwar, IITM. P.W. Murrill., "Fundamentals of Process Control Theory", 3rd Edition-ISA Books
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		-	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. D. Karthikeyan, Controlsoft Engineering India Pvt Ltd, karthikeyan.d@controlsoftengg.in	1. Dr. J. Prakash, MIT, Chennai, prakait@rediffmail.com	1. Mrs. N. Deepa, SRMIST
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. D. Nedumaran, Madras University, dnmaman@gmail.com	2. Mrs. Indirani, SRMIST

Course Code	18ECE282T	Course Name	MODERN CONTROL SYSTEMS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18ECS201T	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:		Learning			Program Learning Outcomes (PLO)															
		1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15			
CLR-1 :		Know and design various conventional compensators.			Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-2 :		Know and develop mathematical modeling using state space technique.						H	H	H	-	L	-	-	H	-	-	-	H	H	-	H
CLR-3 :		Know and analyze the system using state space analysis techniques.						H	L	H	-	H	-	-	H	-	-	-	-	M	-	H
CLR-4 :		Know the importance of structural properties and to analyze the stability of the system.						H	H	-	H	H	-	-	H	-	-	-	-	M	-	H
CLR-5 :		Study the state space control methodologies for various systems.						H	H	H	H	H	-	-	H	-	-	-	-	M	-	H
CLR-6 :		Know and design modern control techniques which are linear.						H	H	H	-	L	-	-	-	-	-	-	H	H	-	H
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :		Design cascade compensators in time domain and design PID controllers in time domain.			3	80	75															
CLO-2 :		Understand and develop state space model for different systems			3	80	70															
CLO-3 :		Analyze the controllability and observability of a system and to design controllers and observers.			3	75	70															
CLO-4 :		Implement procedure to find the structural properties of any linear system			3	80	75															
CLO-5 :		Understand the procedure of applying the control methodology on various linear systems			3	80	70															
CLO-6 :		Design and apply linear based modeling and modern control methods for different linear systems.			3	80	70															

Duration (hour)		Linear Control Design	State Space Analysis	Controllability And Observability	Controller Design For Linear System	Applications
		9	9	9	9	9
S-1	SLO-1	Design specifications	Concept of State variables	Concept of Stability	Pole placement using feedback	State space Modeling of Inverted Pendulum
	SLO-2	Compensator configuration (series and feedback)-	Concept of State space model	Computation of Stability of State space model	Eigen value placement theorem	
S-2	SLO-1	Design cascade compensators - lag by using time domain	Relationship between transfer function and State space model	Concept of Controllability	Selection of desired poles	State space Modeling of Ball and Beam system
	SLO-2	Design feedback compensators - lag by using time domain	State space representation of linear continuous time systems using physical variables	Computation of Controllability of State space model	Eigen structure assignment	
S-3	SLO-1	Design cascade compensators - lead by using time domain	State space representation of linear continuous time systems using phase variables	Concept of Observability	State controller design exercise	State space Modeling of Translational Mechanical Systems
	SLO-2	Design feedback compensators - lead by using time domain	State space representation of linear continuous time systems using canonical variables	Computation of Observability of State space model		
S-4	SLO-1	Compensator design exercises	Conversion of transfer function to various state space representations	Computation of structural properties using Controllability & Observability	State controller design exercise	State space Modeling of Rotational Mechanical Systems
	SLO-2	Compensator design exercises				
S-5	SLO-1	Design cascade compensators – lead-lag by using time domain	Diagonalization	Computation of structural properties using eigen decomposition	State controller design exercise	Modeling exercises for Translational and Rotational Mechanical Systems

	SLO-2	Design feedback compensators – lead-lag by using time domain	State space representation of discrete time systems			
S-6	SLO-1	Design specifications – PID Controllers	Solution of state equations – from differential equations	Concept of Pole Placement by state feedback	Optimal Control – Linear Quadratic Regulation (LQR)	State space Modeling of Electrical Systems
	SLO-2	Effect of PID on linear systems		Concept of State Observers	Infinite Horizon Regulator	
S-7	SLO-1	Design of PD controller using time domain	Solution of state equations – from Transfer Functions	Control System Design Via Pole Placement by state feedback	Receding Horizon Regulator	Modeling exercises for Electrical Systems
	SLO-2	PD Controller design exercises			Receding Horizon Regulator - Design Parameters	
S-8	SLO-1	Design of PI controller using time domain	Concepts of state transition matrix.	Effect of state feedback	Controller Design with Reference Input	State space Modeling of Field controlled DC Motor
	SLO-2	PI Controller design exercises	Computation of state transition matrix		Tracking/ Servo Control using State Feedback	
S-9	SLO-1	Design of PID controller using time domain	Computation of state transition matrix	State feedback Controller design exercises	State controller with reference input design exercise	State space Modeling of Armature controlled DC Motor
	SLO-2	PID Controller design exercises				

Learning Resources	<ol style="list-style-type: none"> 1. Katsuhiko Ogata, "Modern Control Engineering"-fifth edition, Prentice Hall of India Private Ltd, New Delhi, 2009. 2. Kirk D.E, "Optimal control theory-an introduction", Dover Publications, 2004. 3. Richard .C, Dorf and Robert.H.Bishop, "Modern Control System Engineering", Pearson Education (US), United States, 2010. 4. Gopal. M, "Modern Control System theory", New age international(P) ltd, 2012. 5. Nagarath, I.J. and Gopal, M., "Control Systems Engineering", New Age International Publishers, 2010. 6. NPTEL Video Lecture Notes on "Advanced Linear Continuous Control Systems "by Prof. Yogesh Vijay Hote, IIT Roorkee. https://nptel.ac.in/courses/108107115/
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Evaluate Create	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. D. Karthikeyan, Controlsoft Engineering India Pvt Ltd, karthikeyan.d@controlsoftengg.in	1. Dr. J. Prakash, MIT, Chennai, prakait@rediffmail.com	1. Mr. Arockia Vijay Joseph, SRMIST
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. D. Nedumaran, Madras University, dnmaran@gmail.com	2. Mr. P. Jekan, SRMIST

Course Code	18ECE283J	Course Name	PROGRAMMABLE LOGIC CONTROLLER	Course Category	E	Professional Elective	L	T	P	C
							2	0	2	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering		Data Book / Codes/Standards		Nil

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Study the hardware components of Programmable Logic Controller	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Understand the need of programming languages for PLC	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Explore the ladder logic program for control application				H	L	-	-	-	-	-	-	L	-	-	H	H	H	H
CLR-4 :	Identify applications of timers and counters in process automation				H	H	H	H	H	-	-	H	H	M	-	H	H	H	H
CLR-5 :	Locate the malfunctions and troubleshooting various types of errors in Programmable Logic Controller				H	H	H	H	H	-	-	H	H	M	-	H	H	H	H
CLR-6 :	Provide the knowledge of Commissioning, Maintenance and their importance in industry.				H	H	-	H	H	-	-	-	H	H	-	H	M	H	H
					H	H	-	-	-	-	-	H	H	-	M	M	H	H	H
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Select right I/O modules in PLC for process control	3	80	75															
CLO-2 :	Develop ladder logic program for control application	3	80	70															
CLO-3 :	Use timers and counters in process automation	3	75	70															
CLO-4 :	Interpret data compare instruction in PLC program	3	80	75															
CLO-5 :	Troubleshoot the input and output malfunctions in PLC	3	80	70															
CLO-6 :	Select a right PLC for the given application	3	80	70															

Duration (hour)		PLC Hardware Components 12	PLC Programming and Wiring 12	Timers and Counters 12	Data manipulation and Math instructions 12	Troubleshooting 12
S-1	SLO-1	Evolution of Programmable logic controllers	PLC programming languages-Ladder Logic	Timer Instructions	Data manipulation	Electrical Noise
	SLO-2	Architecture of a PLC	Function Block Diagram, Instruction List	On-Delay timer instruction	Data transfer operations	Leaky Inputs and Outputs
S-2	SLO-1	Principles of Operation	Instruction Addressing	Off-delay timer instruction	Data compare instructions	Grounding
	SLO-2	PLCs versus Computers	Branch Instructions	Retentive Timer	Data manipulation programs	Voltage Variations and Surges
S-3-4	SLO-1	Lab1: PLC Wiring	Lab 4: Traffic light control system	Lab 7: HMI Programming	Lab10: Lift control	Lab13: Electro pneumatic direction control
	SLO-2					
S-5	SLO-1	PLC size and application	Electromagnetic Control Relays	Cascading Timers	Numerical Data I/O Interfaces	Program Editing and Commissioning
	SLO-2	Discrete I/O modules	Contactors	Up-Counter	Closed-Loop Control	Preventive Maintenance
S-6	SLO-1	Sinking and sourcing	Manually Operated Switches	One-Shot Instruction	Math Instructions	Troubleshooting
	SLO-2	Analog I/O modules	Mechanically Operated Switches	Down-Counter	Addition Instruction	Processor Module
S-7-8	SLO-1	Lab 2 :Water level control system	Lab 5: Sequential operation of motor	Lab 8: DC motor speed control system	Lab11: Car parking system	Lab14: Stamping machine control
	SLO-2					

S-9	SLO-1	Special I/O modules	Proximity Sensor, Magnetic Reed Switch	Cascading Counters	Subtraction Instruction	Input Malfunctions
	SLO-2	I/O Specifications	Light Sensors, Velocity and Position Sensors	Combining Counter and Timer Functions	Multiplication Instruction	Output Malfunctions
S-10	SLO-1	Human Machine Interfaces (HMIs)	Output Control Devices, Seal-In Circuits, Electrical Interlocking Circuits	High-Speed Counters	Division Instruction	Comparative study of Industrial PLCs.
	SLO-2	Alarms, Graphics Library	Converting Relay Schematics into PLC Ladder Programs	Problems	Other Word-Level Math Instructions	
S 11-12	SLO-1	Lab3: Material handling system	Lab 6: Bottle filling system	Lab 9: Temperature control system	Lab12: Flow control system	Lab15: Servo controller programming
	SLO-2					

Learning Resources	<ol style="list-style-type: none"> 1. Frank D. Petruzella, "Programmable Logic Controller", Tata McGraw Hill 5th Edition, 2017. 2. Bolton. W, "Programmable Logic Controllers", 6th Edition, Elsevier Newnes, 2016. 3. John W. Webb, Ronald A. Reis, "Programmable Logic Controllers", Principles and Applications, Prentice Hall, 5th Edition, 2011 4. Gary Dunning, "Programmable Logic Controllers", Cengage Learning, 3rd Edition, 2009. 5. John R. Hackworth, "Programmable logic controllers Programming Methods and Applications", Pearson, 1st Edition, 2006 6. NPTEL Video Lecture Notes on "Industrial Automation and Control" by Prof. S. Mukhapadhyay, IIT Kharagpur
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		-	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. D. Nedumaran, Madras University, dnmaran@gmail.com	2. Dr. G. Joselin Retna Kumar, SRMIST

Course Code	18ECE284J	Course Name	GRAPHICAL SYSTEM DESIGN IN VIRTUAL INSTRUMENTATION	Course Category	E	Professional Elective	L	T	P	C
							2	0	2	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering		Data Book / Codes/Standards	Nil	

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																		
CLR-1 :	Study the concepts of Virtual instrumentation and to learn the programming concepts in VI.				Level of Thinking (Bloom)	1	2	3	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Study about the various measurement systems and their data acquisition methods in real time.																									
CLR-3 :	Study about the various Instrument Interfacing concepts.																									
CLR-4 :	Explore various control techniques using VI software																									
CLR-5 :	Explore various remote accessing techniques																									
CLR-6 :	Get exposed with various analysis tools for Process control applications.																									
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																								
CLO-1 :	Identify the purpose and need of virtual instrumentation in process control Industries				1,2	80	70	H	-	-	-	-	-	-	-	-	-	-	H	-	-	-	H	-	-	-
CLO-2 :	Measure the parameters using various data acquisition methods.				2,3	85	75	H	H	-	-	-	-	-	-	-	-	H	H	-	H	H	H	-	-	-
CLO-3 :	Implement the available interfacing instruments				2,3	75	70	H	H	H	H	H	-	-	-	-	-	H	-	H	H	H	H	H	-	-
CLO-4 :	Implement various control techniques using VI software				2,3	85	80	H	H	H	H	H	-	-	-	-	H	H	-	H	H	H	H	H	H	-
CLO-5 :	Apply remote accessing Techniques				2,3	85	75	H	H	H	H	H	-	-	-	-	-	H	H	H	H	H	H	-	-	H
CLO-6 :	Develop a system for an engineering application.				2,3	80	70	H	H	H	H	H	-	-	-	-	H	H	H	H	H	H	H	H	H	-

Duration (hour)		Programming Concepts in LabVIEW	Measuring Concepts in Virtual Instrumentation	Controlling Concepts in Virtual Instrumentation	Final Control Elements and its implementation	Signal Processing and Applications
		12	12	12	12	12
S-1	SLO-1	Historical perspective, Need of VI, Advantages of VI, Virtual Instruments versus Traditional Instruments	Components of Measuring System, Origin of signals	Introduction to Non continuous controllers in LabVIEW	Final Control Operation	PC based digital storage oscilloscope
	SLO-2	Review of software in Virtual Instrumentation, Software environment Architecture of VI, Introduction to the block diagram and Front panel Palettes	Transducer, Sensors, Differences between chemical sensors, physical sensors, Biosensors. Selection criteria	Introduction to continuous controllers in LabVIEW	Fundamentals of Mechatronic Actuators	Sensor Technology
S-2	SLO-1	Creating and saving a VI, Front Panel Tool Bar, Block diagram Tool Bar, Palettes	General Conditioning Functions, A/D Control, D/A Control in VI platform	Design of ON/OFF controller	Position-Controlled Actuators	Oscillators, counters
	SLO-2	Creating sub VI, Creating an ICON, Building a connector pane, Displaying VI'S Placing and Saving Sub VI'S on block diagram Example of full adder circuit using half adder circuit	Introduction to MyRIO, Applications of MyRIO	P,PI,PID controllers for a mathematically described processes using VI software.	open-loop and closed-loop actuator position control in a hands-on application	Signal and image processing Techniques
S-3,4	SLO-1	Lab 1: Verification of Arithmetic Operations & Verification of Half Adder	Lab 4: Design a VI to measure angle with my RIO using Y-axis onboard accelerometer	Lab 7: To apply on-off controller using QNET HVAC in virtual instrumentation platform	Lab 10: To apply Position Controlled actuators	Lab 13: To Design of DSO
	SLO-2					
S-5	SLO-1	Loops-For Loop,	Introduction to PC Buses	Modeling of level process	Manipulator Importance, Operation of Manipulators	Spectrum Analyzer
	SLO-2	While Loop	Local Buses-ISA, PCI,	Basic control of level process in LabVIEW	Types of Manipulators Selection Criteria,	

						Waveform Generator
S-6	SLO-1	Arrays	RS232, RS422	Modeling of Reactor Processes	Controlling techniques on Manipulators	Data visualization from multiple locations
	SLO-2	Clusters, plotting data	RS485	Basic control of Reactor process in LabVIEW	Controlling techniques on Manipulators	Distributed monitoring and control
S-7,8	SLO-1	Lab 2:Program to find Addition of First n natural numbers using for loop	Lab 5:To implement Speed Control of DC Motor (QNET)	Lab 8:Continuous Control of any process using LabVIEW	Lab 11:To apply PID to Control Manipulators	Lab 14:Real time spectrum analysis using LabVIEW
	SLO-2					
S-9	SLO-1	Charts, Graphs, Formula nodes,	Interface Buses-USB,PXI	Case studies on development of HMI in VI	Remote access using LabVIEW	Vision and Motion Control
	SLO-2	Case and Sequence Structures	VXI,	Case studies on development of HMI in VI	Different types of Protocols	Examples on Integrating Measurement with vision and motion
S-10	SLO-1	Acquiring Data Using Hardware	SCXI	Case studies on development of SCADA in VI	Case study on TCP/IP Protocol application	NI Motion control
	SLO-2	DAQ Devices	PCMCIA	Case studies on development of SCADA in VI	Case studies on web publishing tool	Speed control system
S-11,12	SLO-1	Lab 3:Design a Voltmeter by using AO to generate a signal and AI to acquire the signal using DAQ	Lab 6: Simple Modeling of QNET Rotary Inverted Pendulum	Lab 9:Controlling of Rotary Inverted Pendulum	Lab 12:Online process control using LabVIEW using TCP/IP and web publishing	Lab 15 :Minor Project
	SLO-2					

Learning Resources	<ol style="list-style-type: none"> 1. Nadovich, C., "Synthetic Instruments Concepts and Applications", Elsevier, 2005. 2. Bitter, R., Mohiuddin, T. and Nawrocki, M., "Labview Advanced Programming Techniques", CRC Press, 2nd Edition, 2007. 3. Gupta, S. and Gupta, J. P., "PC Interfacing for Data Acquisition and Process Control", 2nd Edition, Instrument Society of America, 1994 4. Liptak, "Instrument Engineers Handbook Process Measurement and Analysis", Elsevier, 2005 	<ol style="list-style-type: none"> 5. Jamal, R. and Picklik, H., "Labview – Applications and Solutions", National Instruments Release. 6. Johnson, G., "Labview Graphical programming", McGraw-Hill, Newyork, 1997. 7. Wells, L.K. and Travis, J., "Labview for Everyone", Prentice Hall, NewJersey, 1997. 8. Buchanan, W., "Computer Busses", CRC Press, 2000.
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Learning Assessment											
	Bloom'sLevel of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry		Experts from Higher Technical Institutions
1. D. Karthikeyan, Controlsoft Engineering India Pvt Ltd, karthikeyan.d@controlsoftengg.in		1. Dr. J. Prakash, MIT, Chennai, prakait@rediffmail.com
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com		2. Dr. D. Nedumaran, Madras University, dnmaman@gmail.com
		Internal Experts
		1. Dr. K.A.Sunitha, SRMIST

Course Code	18ECE380T	Course Name	INSTRUMENTATION AND CONTROL IN PROCESS INDUSTRIES	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering		Data Book / Codes/Standards	Nil	

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning		
CLR-1 :	Learn various methods involved in the petroleum industries.				1	2	3
CLR-2 :	Import the knowledge of control and measurement used in iron and steel industries.				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)
CLR-3 :	Study the various instruments and the role of instrumentation in paper industries.						
CLR-4 :	Learn the measurement and control in thermal industries.						
CLR-5 :	Study the industry standards and safety consciousness in process industries.						
CLR-6 :	Import the knowledge of chemical process hazards in industries.						
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:					
CLO-1 :	Understand the basics of petrochemical industries.				3	80	75
CLO-2 :	Apply knowledge in working of various instruments that are used in iron and steel industries.				3	80	70
CLO-3 :	Acquire the knowledge of analyzers and measurement of density, level in paper industries.				3	75	70
CLO-4 :	Understand the operation of boiler in thermal industries.				3	80	75
CLO-5 :	Understand the process safety in chemical industries.				3	80	70
CLO-6 :	Apply the knowledge of process hazards in industries.				3	80	70

Program Learning Outcomes (PLO)														
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
H	-	-	-	-	-	-	-	H	-	-	H	H	-	-
H	H	-	-	-	-	-	H	H	-	-	H	H	-	H
H	H	M	-	-	-	-	H	H	-	-	H	H	H	H
H	H	M	H	-	-	-	H	H	-	-	H	H	H	H
H	H	M	H	-	H	-	-	H	-	-	H	M	M	H
H	-	-	-	-	H	-	-	-	-	-	H	-	M	-

Duration (hour)		Instrumentation in Petroleum Industry	Measurement and control in Iron and Steel Industry	Instrumentation and control in Paper Industry	Boiler operation and control in Thermal Industry	Industrial Safety Management
		9	9	9	9	9
S-1	SLO-1	Introduction to petroleum	Introduction: Steel Production	Conventional and non-conventional raw materials for paper manufacture	Introduction to power generation	Introduction to process safety
	SLO-2	Petroleum exploration Methods	Basic oxygen furnace	Different pulping processes	Importance of instrumentation & control in power generation	Importance of Safety consciousness in Indian Chemical Industries
S-2	SLO-1	Magnetic Survey	Blast furnace	Continuous and batch digesters	Classification of instruments in power plant	Industry Standards and Regulations.
	SLO-2	Drilling process	Rolling process	Chemical recovery process	Building blocks	Set of Standards. HSE – PES, AICHe – CCPS,
S-3	SLO-1	Rotary Drilling	Hot rolling process	Conversion process	Combined Heat and Power System	Process hazard analysis
	SLO-2	Petroleum production	Cold rolling process	Identification of various process parameters	Control Loops in Boiler	Chemical process hazards
S-4	SLO-1	Petroleum refining and unit operations in refinery	Temperature measurement	pH measurement	Combustion Control,	Material hazards
	SLO-2	Constituents of crude oil	Pressure measurement	Density measurement	Air/fuel ratio control	Energy hazards
S-5	SLO-1	Atmospheric distillation of crude oil	Shape and thickness measurement	Level measurement	Steam flow measurement	Chemical interaction hazards

	SLO-2	Vacuum distillation process	Analyzers in iron and steel industry	Special applications for control	Smoke, density measurement	Layers of protection
S-6	SLO-1	Thermal conversion process	Oxygen analyzer	Digester blow tank control	Turbine speed and vibration measurement	Types of safeguard
	SLO-2	Control of distillation column	Blast furnace and stove combustion control system	Dryer temperature control.	Use of feed forward and cascade control in process industries	Safety performance measurement tools
S-7	SLO-1	Temperature control.	Casting mold Level Control	Fuel gas oxygen analyzer	Instrumentation and control in reactors	Techniques used to reduce explosion hazards
	SLO-2	Pressure control	Computer Applications	Dissolved oxygen analyzer	Sodium analyzer	Hazard identification techniques
S-8	SLO-1	Level measurement of petroleum	Data logging applied to Steel Making	Computer applications: Direct Digital Control	Flue gas analyzer	Fault tree analysis
	SLO-2	Temperature measurement of petroleum	Steel rolling mill Control	Distributed control system in power plant	Fuel composition analyzer	Operation and maintenance
S-9	SLO-1	Case Study: An. Application for Petroleum Refineries.	Case Study on iron and steel manufacturing process.	Case Study: Water Treatment for Paper and Pulp Industry	Case Study: Chandrapura Thermal Power Station	Case Study: Safety in Explosive
	SLO-2	Case Study: Control of an Industrial Distillation Column	Case Study: Analysis of the Production Processes in a Steel Factory	Case Study: Boiler Materials for the Pulp and Paper Industry	Case Study: Boiler tube failures	Case Study: Chemical splash at process plant.

Learning Resources	<ol style="list-style-type: none"> 1. Mian.M.A, "Petroleum Engineering Handbook for the Practicing Engineer", Gulf Professional Publishing, 2005. 2. Liptak, Bela G, "Instrumentation in the Processing Industries", Chilton Publishers, 1973. 3. Considine D. M., "Process/Industrial Instruments and control Handbook", McGraw Hill, 6th Edition 2019. 	<ol style="list-style-type: none"> 4. Sam .G.Duke low, "The Control of boilers", Instrument Society of America, 1991. 5. Paul Gruhn & Harry Cheddie, Safety Instrumented Systems: Design, Analysis and Justification, 2nd Edition, International Society of Automation, 2005.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

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Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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Course Code	18ECE381T	Course Name	DISTRIBUTED CONTROL SYSTEM AND SCADA	Course Category	E	Professional Elective				L	T	P	C
										3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1:		Give basic knowledge in SCADA in the field of automation	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:		Understand the Communication modules used in SCADA	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3:		Give basic knowledge in different architectures of DCS																		
CLR-4:		Explore the local control unit of distributed control system																		
CLR-5:		Impart adequate information in the interfaces used in DCS																		
CLR-6:		Learn the applications of DCS in process industries																		
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																		
CLO-1:		Understand the elements of SCADA system	3	80	75	H	-	-	-	-	H	-	-	-	-	H	H	-	H	-
CLO-2:		Develop any application based on SCADA along with GUI using SCADA software.	3	80	70	H	-	-	-	-	H	-	-	-	-	H	H	-	H	-
CLO-3:		Understand evolution and architecture of DCS and hierarchical control in DCS	3	75	70	H	H	M	H	M	H	-	M	M	-	H	H	H	H	H
CLO-4:		Demonstrate interfacing of hardware and software of computer based automation system.	3	80	75	H	H	M	H	M	-	-	M	H	-	H	H	M	H	H
CLO-5:		Select and use the most appropriate automation technologies for a given application	3	80	70	H	-	M	-	H	-	-	H	H	-	H	H	M	H	H
CLO-6:		Evaluate computer based automation system used in industries ranging from discrete, continuous process to hybrid processes.	3	80	70	H	-	-	-	-	H	-	H	H	-	H	H	H	H	H

Duration (hour)		SCADA Elements 9	Communication 9	DCS Architecture 9	Operator interface 9	DCS Application 9
S-1	SLO-1	SCADA basics introduction	SCADA Communication introduction	DCS - basics	DCS operator interfaces- introduction	DCS Application in Power plant
	SLO-2	Elements of SCADA	Communication system components	Evolution of Distributed Control System	Operator Interface Requirements	Automation strategy
S-2	SLO-1	Functionality of SCADA	Structure of a SCADA Communications Protocol	DCS Architecture	Low-level Operator Interface	Distributed system structure
	SLO-2	Process example	Field/RTU Communication	Local control unit	Continuous control station	Application functions
S-3	SLO-1	History of SCADA	Analog electronic controllers	I/O module(Analog & Digital)	Manual Loader Station	DCS Application in cement plant
	SLO-2	Development from Telemetry	Communication Topology	Basic elements	Indicator/Logic Station	System architecture
S-4	SLO-1	Key features	RTU/MTU Communication	Architectural parameters	Smart annunciators	DCS Application in iron plant
	SLO-2	Real time systems	System components	Types of architecture	High level Operator interface	System architecture
S-5	SLO-1	Analog signals measurement	Communication Protocols	CPU, Memory	Architectural Models	DCS Application in steel plant
	SLO-2	Control techniques	Operator interface	Local control unit languages	Hardware Elements	System architecture

S-6	SLO-1	Discrete signals measurement	Monitoring alarms	Language requirements	Operator displays	DCS Application in Paper and pulp industry
	SLO-2	Control techniques	Status points	Functional blocks	Engineering interface- Introduction	System architecture
S-7	SLO-1	Remote terminal unit	Control interfacing	Problem-oriented languages	System configuration requirements	DCS Application in petroleum-refining industry
	SLO-2	Analog and Discrete control	Parallel operator interface	High-level languages	Diagnosis of System Problems	
S-8	SLO-1	Monitoring signals	SCADA Development for any one typical application	Process interfacing issues	Low-level engineering interface	DCS Application in oil and gas processing industry.
	SLO-2	Master terminal unit		Security design issues	System configuration	
S-9	SLO-1	Process configuration	Programming for GUI development using SCADA software	Process input/output design issues	High-level engineering interface	DCS Application in water treatment plant
	SLO-2	Applications		Remote I/O and Communication modules	System configuration	System architecture

Learning Resources	1. Stuart Boyer A, "SCADA : Supervisory control and data Acquisition", Fourth Edition, ISA-The Instrumentation, Systems, and Automation Society, 2010	3. Michael Lucas, "Distributed Control Systems". Van Nostrand Reinhold Co., 1986
	2. Dobrivojic Poppovik, Vijay P Bhatkar, "Distributed Computer Control Systems in Industrial Automation" CRC Press, 1990	4. IDC Technologies, "Practical Distributed Control Systems (DCS) for Engineers and Technicians"2012 5. Krishna Kant, Computer Based Industrial Control, 2 nd Edition, Prentice Hall of India, New Delhi, 2010

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry		Experts from Higher Technical Institutions
1. D. Karthikeyan, Controls of Engineering India Pvt Ltd, karthikeyan.d@controlsoftengg.in		1. Dr. J. Prakash, MIT, Chennai, prakait@rediffmail.com
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com		2. Dr. D. Nedumaran, Madras University, dnmaran@gmail.com
		Internal Experts
		1. Dr. G. JoselinRetna Kumar, SRMIST
		2. Mr. J. SamJeba Kumar, SRMIST

Course Code	18ECE382T	Course Name	BUILDING AUTOMATION	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1: Give basic knowledge in intelligent building and building automation systems		1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2: Gain Knowledge on different sensors and measurement systems in BMS system		Level of Thinking (Bloom)	Engineering Knowledge
CLR-3: Know the basic concepts of HVAC Air handling unit		Expected Proficiency (%)	Problem Analysis
CLR-4: Understand the basic concepts of HVAC terminal unit		Expected Attainment (%)	Design & Development
CLR-5: Explore the BAS Architecture			Analysis, Design, Research
CLR-6: Present an overview of different Communication protocols			Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1: Understand the need of intelligent buildings and automation systems		3 80 75	H - - - - H H - - - H H H H
CLO-2: Measure the parameters and design of sensors		3 80 70	H - - - - H H - - - H H - M H
CLO-3: Design different Air handling units		3 75 70	H H M H M H M H - - H H H M H
CLO-4: Understand and design terminal units		3 80 75	H H M H M - M H H - - H - M H
CLO-5: Familiarize with the components of BAS architecture		3 80 70	H - M - H - M H - - H - M H
CLO-6: Select the Communication protocol for a particular application		3 80 70	H - - - - H - H - H M H H - H

Duration (hour)	Introduction to Building automation systems	Comfort parameters	HVAC Basic Concepts- Air handling unit	Terminal Unit	BAS Architecture
	9	9	9	9	9
S-1	SLO-1 Introduction to intelligent building	Temperature	Concept of Air handling unit	Concept of Variable Air Volume (VAV) system	BAS Hierarchy
	SLO-2 intelligent architecture	Enthalpy, Entropy	components in AHU	different types of VAV	Field level components
S-2	SLO-1 structure	Heat Transfer - Conduction, Convection, Radiation	different types of dampers	Design, working	Direct Digital Control (DDC)
	SLO-2 Facility management vs. intelligent buildings	Working Principle, Characteristics of RTD	Working, configuration,	series fan powered	Supervisory Controller
S-3	SLO-1 Lifecycle of building	Thermistor, Thermocouple	different types of AHU	parallel fan powered	Server, Operator Workstation (OWS)
	SLO-2 Evolution of intelligent buildings	Bimetallic strip	Design and working	pressure dependent	Different Communication protocol
S-4	SLO-1 Introduction to BAS	Humidity, Specific Humidity,	Operation of different modes in AHU	supply-exhaust VAV	addressing concepts
	SLO-2 Different systems of BAS	Relative Humidity, Dew point, Saturation point	humidification	dual duct VAV	Open Protocols -BACnet, LON
S-5	SLO-1 HVAC	Working principle of relative humidity sensors	dehumidification	Design, working, use of radiation coil	Profibus, Modbus
	SLO-2 HVAC Applications	mounting for humidity sensors in BAS	static pressure control	chilled beam	M-bus

S-6	SLO-1	Security system	Psychrometric chart	volume matching	CRAC unit, VRV systems	Proprietary Protocols- N2, CBUS
	SLO-2	Field Devices	Pressure, Static Pressure, Velocity pressure, Absolute Pressure	cooling, heating,	unit heater, Fan coil unit and unit ventilator	Wireless filed devices
S-7	SLO-1	Fire alarm system	Gauge Pressure, Vacuum Pressure, Differential Pressure, Sealed Pressure	economizer mode	Chilled water system	controllers
	SLO-2	Types of Detectors	Working Principle of Different types of Pressure Sensors	Heat recovery techniques	Concept of refrigeration cycle, components used in refrigeration cycle	routers
S-8	SLO-1	Modules	Working of principle of different air flow sensors	plate heat exchanger	different types of chilled water system	coordinators
	SLO-2	Indicating Devices	Working of principle of different water flow sensors	heat recovery wheel	Working and design of different types of boilers	Benefits of a Wireless BAS
S-9	SLO-1	lighting systems	Measurement of CO2 level	AHU for different applications	Working and design of different types of heat exchanger	Wireless Field Bus
	SLO-2		Working principal of BTU meter			Basic Reference Model (BRM)

Learning Resources	1. <i>Smart Buildings</i> by Jim Sinopoli, Butterworth-Heinemann imprint of Elsevier, 2 nd Edition., 2010 2. <i>Intelligent Building Systems</i> by Albert Ting-Pat So, WaiLok Chan, Kluwer Academic publisher, 3 rd Edition., 2012.	3. <i>Design of Special Hazards and Fire Alarm Systems</i> by Robert Gagnon, Thomson Delmar Learning; 2 nd Edition, 2007.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. D. Karthikeyan, Controlsoft Engineering India Pvt Ltd, karthikeyan.d@controlsoftengg.in	1. Dr. J. Prakash, MIT, Chennai, prakaiti@rediffmail.com	1. Dr.G.JoselinRetna Kumar, SRMIST
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. D. Nedumaran, Madras University, dnmaraman@gmail.com	2. Mr.J.SamJeba Kumar, SRMIST

Course Code	18ECE383J	Course Name	INSTRUMENTATION SYSTEM DESIGN	Course Category	E	Professional Elective	L	T	P	C
							2	0	2	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering		Data Book / Codes/Standards		Nil

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1:	Impart knowledge on basic signal conditioning circuits.	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Familiarize students on the requirements of industry.	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3:	Obtain adequate knowledge on process parameter optimization.				H	H	H	M	-	-	-	-	-	-	-	M	H	-	-
CLR-4:	Gain expertise to handle basic instruments in Industry.				H	H	-	M	H	-	-	-	H	-	L	-	M	M	H
CLR-5:	Acquire knowledge of piping diagram in Industry.				H	-	M	M	M	-	H	M	-	-	-	-	-	-	M
CLR-6:	Bridge the gap between industrial requirements and operational constraints.				H	M	-	M	-	M	M	-	-	-	-	-	-	M	-
		3	80	75	H	-	H	-	-	M	-	H	M	-	-	H	-	L	
		3	80	70	H	H	-	-	-	-	-	-	-	-	-	H	M	H	
		3	75	70															
		3	80	75															
		3	80	70															
		3	80	70															

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)
CLO-1:	Apply mathematical knowledge, science, engineering fundamentals to design circuits pertaining to various process measurements	3	80	75
CLO-2:	Design signal conditioning circuits for various process parameters.	3	80	70
CLO-3:	Optimize the performance of process output.	3	75	70
CLO-4:	Select optimal sensor for process measurement.	3	80	75
CLO-5:	Choose type of indication circuits for industry.	3	80	70
CLO-6:	Analyze and select the suitable sensing and transduction unit.	3	80	70

Duration (hour)		Review of Signal Conditioning circuits	Design of Level and Pressure Measurement	Design of Flow measurements and Control Valve	Design of Transmitters and final control element	Design of indicators and Logic circuits
		12	12	12	12	12
S-1	SLO-1	Requirements of Signal Conditioning	Electronic PID controller Design.	Study of Orifice, Venturi and Rotameter.	2 wire and 3 wire transmitter	Alarm circuit design
	SLO-2	Analog, Digital and adaptive filter design	P,I,D modes of operation Solving numerical..	Review of design requirements.	Thermocouple based temperature transmitter	Annunciator circuit design
S-2	SLO-1	V/I and I/V Converter design. Design of amplifiers – Pre amplifier	Composite modes – PI, PD and PID.	Design of Orifice.	Design of transmitter	Interlocks
	SLO-2	Instrumentation Amplifier, Bridge and Isolation Amplifier.	Realization using composite modes.	Design of Rotameter.	Capacitance based flow transmitter	Overview of Programmable logic controllers
S-3-4	SLO-1	Lab1: Design of Active Filters – LPF, HPF and BPF.	Lab 4: Design, Fabrication and Testing of Analog PID Controller.	Lab 7: Development of Software Program for sizing Orifice.	Lab10: Design, Fabrication and Testing of 2-wire Analog Transmitter.	Lab 13: Sequential controller using PLD
	SLO-2					
S-5	SLO-1	Signal conditioning circuits for temperature measurement. – RTD.	Requirements of Pressure Measurement.	Design constraints.	Level transmitter	Microprocessor based PID controller
	SLO-2	Design of RTD	Bourdon tube, Bellows, Diaphragms	Study of Valve characteristics and valve body	Flapper nozzle amplifier characteristics	Study of recorders
S-6	SLO-1	Signal Conditioning for Thermocouple.	Factors affecting sensitivity.	Design of Actuator and positioner	Pneumatic actuator	Numerical in alarm circuit
	SLO-2	Design of thermocouple		Control Valve sizing	Hydraulic actuator	Real time case study

			Adjustment of set point, bias and controller settings			
S 7-8	SLO-1	Lab 2 :Design of Instrumentation Amplifier.	Lab 5: Design of V/I and I/V converter.	Lab 8: Development of Software Program for sizing Rotameter.	Lab11: Design of multi channel data acquisition system	Lab 14: Functional constraints and specification in industry
	SLO-2					
S-9	SLO-1	Cold junction compensation and Linearization.	Air purge Level Measurement	Design of Control valve factor and plug area.	Characteristics of pumps	Operating console and control room panel design.
	SLO-2	Design of cold junction compensation circuits.	Design of air purge system	Selection of material for body and trim.	Instruments used in pumping practices	Instrument symbols and signals
S-10	SLO-1	Zero and Span adjustment in Temperature Transmitters.	Capacitive based level Measurement.	Cavitation and flashing in Control valve	Pump operation and maintenance	Mini project on any process application.
	SLO-2	Temperature indicators and selection criteria for temperature sensing instruments.	Design of capacitance based level measurement.	Characteristics of control valve for typical applications	Selection of pumps	Discussion on project
S 11-12	SLO-1	Lab3: Design of regulated power supply.	Lab 6: Design of signal conditioning circuits for level measurements.	Lab 9: Study of control valve characteristics	Lab12: Study of P&I diagrams	Lab 15: Process application
	SLO-2					

Learning Resources	1. C.D.Johnson, "Process Control Instrumentation Technology", 8th Edition, Prentice Hall, 2015. 2. Bentley, J. P., Principles of Measurement Systems, Pearson Education, 2015. 3. Bela G.Liptak, "Instrument Engineers Handbook – Process Control and Optimization". 4th Edition. CRC Press. 2008. 4. N.A.Anderson, Instrumentation for Process Measurement and Control, Chilton Company, 2003. 5. R.W.Miller, "Flow measurement engineering Handbook", McGraw hill. New York, 1996.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		-	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. D. Nedumaran, Madras University, dnmaran@gmail.com	2.Dr.G.Joselin Retna Kumar

Course Code	18ECE384T	Course Name	FACTORY INSTRUMENTATION NETWORKS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1:	Educate on the basic concepts of data networks	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Introduce the basics of inter-networking and serial Communications	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3:	Provide details on HART and Field buses																		
CLR-4:	Know different techniques on Modbus, PROFIBUS and other Communication protocols																		
CLR-5:	Present an overview of industrial Ethernet																		
CLR-6:	Study the working of computer busses and protocols																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1:	Understand the basic concepts of data networks	3	80	75	H	H	-	-	M	H	-	-	-	-	-	H	H	-	H
CLO-2:	Analyze the techniques of inter-networking and serial Communications	3	80	70	H	-	-	H	-	H	-	-	-	-	-	H	-	M	H
CLO-3:	Understand the protocols and layers of HART and field bus	3	75	70	H	-	M	H	M	H	-	H	-	H	M	H	M	H	H
CLO-4:	Analyze the techniques of MODBUS, PROFIBUS and other Communication protocol	3	80	75	H	H	M	H	M	-	-	H	H	H	H	H	-	H	H
CLO-5:	Utilize the concept of industrial Ethernet	3	80	70	H	-	M	-	H	-	-	H	-	H	H	H	H	H	H
CLO-6:	Analyze the working of computer busses and protocols	3	80	70	H	-	M	-	-	H	-	H	-	H	-	H	H	H	H

Duration (hour)		OSI Model 9	Inter-Networking	HART and Field bus 9	PROFIBUS and Modbus 9	Industrial Ethernet 9
S-1	SLO-1	Introduction to Modern instrumentation	Introduction to RS-232	Introduction to HART and smart instrumentation	Introduction to PROFIBUS	Introduction to Industrial Ethernet
	SLO-2	Introduction to control systems	RS-422 and RS-423	HART protocol	PROFIBUS protocol stack	10 Mbps Ethernet
S-2	SLO-1	Open systems interconnection (OSI) model	Electrical characteristics of RS 232	Physical layer- Analog 4–20 mA	Physical layer (layer 1)	Media systems
	SLO-2	Representation of the OSI model	Examples	Digital frequency shift keying (FSK)	Type A cable	10Base5, 10Base2, 10BaseT
S-3	SLO-1	Protocols	Communications between two nodes	Data link layer	Type B cable	Signaling methods
	SLO-2	Basic structure of an information frame defined by a protocol	Transmission and reception of characters	HART protocol implementation of OSI model layer	Data link layer (layer 2)	Medium access control
S-4	SLO-1	Standards	Simple no-handshaking Communications	Application layer- Universal commands	Hybrid medium access control	Frame transmission
	SLO-2	EIA-232 interface standard	Software handshaking	Common practice commands, Device specific commands	Application layer	Frame reception
S-5	SLO-1	EIA-485 interface standard	Hardware handshaking	Troubleshooting	Introduction to Modbus	MAC frame format
	SLO-2	Interoperability, Interchangeability	Two-way Communications with handshaking	HART cable length calculation	Modbus protocol structure	Differences between IEEE 802.3 and Blue Book Ethernet (V2)

S-6	SLO-1	Mod bus	DTE-DCE connections (PC to modem)	Introduction to foundation field bus	Function codes	IEEE 802.2 LLC
	SLO-2	Data Highway Plus protocol structure	Exercises	Physical layer	Read coil or digital output status (function code 01) and Read digital input status (function code 02)	Reducing collisions
S-7	SLO-1	DeviceNet	Introduction to RS-485 (ISO 8482)	Wiring rules	Read holding registers (function code 03) and Reading input registers (function code 04)	Design rules
	SLO-2	Profibus	RS-485 connecting to multiple nodes	Encoding rule, permeable and delimiters	Force single coil (function code 05)	Length of the cable segments
S-8	SLO-1	Introduction to OLE for process control	Line drivers	Data link layer	Preset single register (function code 06)	100 Mbps Ethernet
	SLO-2	Common problems and solutions	Unbalanced digital interface circuit (RS-423) and balanced digital interface circuit (RS-422)	Data link layer: packet format	Troubleshooting	Media access: full-duplex
S-9	SLO-1	General comments on troubleshooting	RS-232/485 converter	Application layer	Common Problems and Discussion	Auto-negotiation
	SLO-2	Specific Methodology	Exercises	User layer	Modbus Plus protocol overview	Fiber optic cable distances 100BaseFX

Learning Resources	1. Steve Mackay, Edwin Wrijut, Deon Reynders, John Park, "Practical Industrial Data Networks Design, Installation and Troubleshooting", Newnes Publication, Elsevier 1 st edition, 2004.	4. Andrew S. Tanenbaum, David J. Wetherall, "Computer Networks", Prentice Hall of India Pvt. Ltd., 5 th Edition. 2011.
	2. Ian Verhappen and Augusto Pereira, "Foundation Field bus", 4 th Edition, Feb 29, 2012	
	3. William Buchanan, "Computer Buses", CRC Press, 2000.	5. A. Behrouz Forouzan, "Data Communications & Networking", 3 rd edition, Tata Mc Graw hill, 2006.

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

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2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com		2. Dr. D. Nedumaran, Madras University, dnmaran@gmail.com	
		Internal Experts	
		1. Dr. S. Umamaheswari, SRMIST	
		2. Dr. A. Vimala Juliet, SRMIST	

Course Code	18ECE385T	Course Name	IoT IN PROCESS INSTRUMENTATION AND AUTOMATION	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Impart fundamental knowledge on the concepts of Internet of Things with its Architecture.				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Provide an overview of various techniques that are using Internet of Things in Industry applications.				Thinking (Bloom)	Efficiency (%)	Attainment (%)	Knowledge	Analysis	Development	Design, Research	Usage	Culture	& Sustainability		Team Work	Communication	& Finance	Learning			
CLR-3 :	Understand the working of Internet of Things in Industry with the advanced Industry 4.0 platforms.																					
CLR-4 :	Understand the application of Internet of Things in Automation																					
CLR-5 :	Gain knowledge on the operation of Engineering in IoT Automation with arrowhead framework.																					
CLR-6 :	Explore the working of IoT in various real-time industries																					

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Understand the basic concepts of IoT, Architecture and Its Applications	3	85	80	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-2 :	Analyze the techniques to apply IoT for Industry	3	85	75	H	H	H	H	H	-	-	H	-	-	-	H	-	H	-
CLO-3 :	Apply the knowledge of different techniques of IoT in industry with an advanced platform of Industry 4.0	3	80	80	H	H	H	H	H	H	-	-	-	-	-	H	-	H	H
CLO-4 :	Develop the knowledge of IoT in Automation.	3	85	80	H	H	H	H	H	-	-	-	H	-	-	H	-	H	H
CLO-5 :	Apply the knowledge of Engineering in IoT Automation System	3	80	75	H	-	H	-	H	-	-	H	-	-	-	H	H	H	H
CLO-6 :	Design the IoT based real-time projects	3	85	85	H	-	H	H	H	H	H	H	H	H	H	H	H	H	H

Duration (hour)		IoT – Landscape, System Architectures	Industrial Internet of Things(IIoT)	IIoT Platforms	IIoT Automation	Engineering of IIoT Automation System
		9	9	9	9	9
S-1	SLO-1	Introduction to IoT	Introduction to IIoT	Introduction to IIoT Conceptual diagram	From DCS and SCADA to IIoT	Engineering of an Arrowhead domain facility
	SLO-2	Applications and Architectures	IIoT Architecture	Middleware Architecture	Automation System Architectures	Engineering Tool Interoperability
S-2	SLO-1	Wireless Networks, Devices	Communication Methods for IoT Devices	Functions of Middleware Platforms	Automation System Properties	Component based Engineering Method
	SLO-2	Security and Privacy	IoT Reference Model by ITU	IIoT WAN and Protocol	Communication within Automation Systems	Life Cycle Dimensions
S-3	SLO-1	Event-Driven Systems	IoT Business Model by ITU	IIoT Device for M2M	Current Trends in Automation System	Data Model
	SLO-2	IoT System Architectures	Designing Industrial Internet Systems	Securing the Industrial Internet	Automation System Security	Design Guidelines for Component based Engineering
S-4	SLO-1	Protocols Concepts	OSI Table	Security in Manufacturing	Future Automation System Requirements	Safety and Security Engineering of IIoT Automation System
	SLO-2	IoT- Oriented Protocols	Web 2.0 Layers	OT Manufacturing Network	Next Generation Automation	Security Analysis
S-5	SLO-1	Data bases & Time Bases	IP Layers vs IIoT Layers	OT vs IT Security Domains	Internet of Things	ETSI and STRIDE method
	SLO-2	IoT Device Design Space	Modern Communication Protocols	Defining Industry 4.0	System of Systems	Safety Analysis

S-6	SLO-1	Cost of Ownership	Wireless Communication Technologies	Characteristics of Industry 4.0	Service Oriented Architecture	FMEA / FMECA Analysis
	SLO-2	Power Consumption	Proximity Network Communication Protocols	Industry 4.0 Design Principles	Local Automation Cloud Concept	Engineering Scenarios
S-7	SLO-1	Cost per Transistor and Chip Size	Access Network Technology	Building Blocks of Industry 4.0	Local Cloud Properties	Efficient Deployment of IoT Sensors
	SLO-2	Duty Cycle and Power Consumption	Ethernet, IP Routing	Industry 4.0 Reference Architecture	Local Cloud Establishment	Network Deployment tool
S-8	SLO-1	Platform Design	TCP/IP	Smart Factories - Introduction	Automation Support	Cost of Wireless Sensor Network
	SLO-2	IoT Network Model	Application Programming Interface	Smart Factory Production line	Latency in Local Clouds	Swift Deployment and Configuration
S-9	SLO-1	Single and Multi – Hub Networks	API – Technical Perspective with Example	Smart Manufacturing	Security in Local Clouds	Deployment Procedure
	SLO-2	Physical Networks	Summary	Real World Smart Factories	System of System Scalability	Replacement of Device

Learning Resources	<ol style="list-style-type: none"> 1. Dimirios Serpanos and Marilyn Wolf, <i>Internet-of-Things (IoT) Systems, Architectures, Algorithms, Methodologies</i>, Springer, 2018. 2. Alasdair Gilchrist, <i>Industry 4.0 – The Industrial Internet of Things</i>, Apress, 2016. 3. "IoT Automation Arrowhead Framework", Jerker Delsing, CRC Press, Taylor & Francis Group, 2017. 4. Patel Chintan, <i>Internet of Things Security: Challenges, Advances, and Analytics</i>, Auerbach Publications, 2019. 5. Jeschke S Brecher, Song C, <i>Industrial Internet of Things – Cyber Manufacturing Systems</i>, Springer, 2017. 6. Stamatios Manesis, George Nikolakopoulos, <i>Introduction to Industrial Automation</i>, CRC Press, Taylor & Francis Group, 2018.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. D. Karthikeyan, Controlsoft Engineering India Pvt Ltd, karthikeyan.d@controlsoftengg.in	1. Dr. J. Prakash, MIT, Chennai, prakait@rediffmail.com	1. Dr. G. Y. Rajaa Vikhram, SRMIST
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. D. Nedumaran, Madras University, dnmaman@gmail.com	2. Dr. Joselin Retna Kumar, SRMIST

Course Code	18ECE386T	Course Name	MEMS BASED MICROSYSTEM ANALYSIS AND DESIGN	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Study the basics of microfabrication and its techniques				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Impart the knowledge of mechanical microsystems				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Understand the mechanism for various actuators							H	H	-	H	H	-	-	H	H	-	-	H	M	-	H
CLR-4 :	Know the behavior of fluid at the micro level, working of microfluidic devices and its fabrication techniques							H	H	H	H	H	-	-	H	H	-	-	H	M	-	H
CLR-5 :	Identify the correct interfacing circuits for microsystem							H	H	H	H	H	-	-	H	H	-	-	H	M	-	H
CLR-6 :	Know the working and readout mechanism for microdevices or microsystems							H	H	H	H	H	-	-	H	H	-	-	H	M	-	H
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	Apply the knowledge of micro technology to fabricate micro devices				3	80	80	H	H	-	H	H	-	-	H	H	-	H	M	-	H	
CLO-2 :	Design a microsensor based on an application with a suitable working principle.				3	80	80	H	H	H	H	H	-	-	H	H	-	H	M	-	H	
CLO-3 :	Design, analyse and optimise the microactuator for different applications.				3	80	80	H	H	H	H	H	-	-	H	H	-	H	M	-	H	
CLO-4 :	Design a microfluidic device for automobile, medical, electronics and industrial applications				3	80	80	H	H	H	H	H	-	-	H	H	-	H	M	-	H	
CLO-5 :	Design an interfacing circuit for reading output from microsystems				3	80	80	H	H	H	H	H	-	-	H	H	-	H	M	-	H	
CLO-6 :	Develop a microsystem for a specific application				3	80	80	H	H	H	H	H	-	-	H	H	-	H	M	-	H	

Duration (hour)	Micromachining Technology		Mechanical Microsensors		Microactuators		Microfluidics		Interface Circuitry and Microsystems	
	9		9		9		9		9	
S-1	SLO-1	Introduction	Introduction		Introduction		Introduction		Introduction	
	SLO-2	Bulk Micromachining	Automotive		Actuators: Transducers with Mechanical Output		Properties of Fluids		Microsensor Systems	
S-2	SLO-1	Wet Etching	Computers and Peripherals		Transduction Mechanisms		Volumes and Length Scales		Microsensor System Applications - Automotive Sensors	
	SLO-2	High-Aspect-Ratio Micromachining	Consumer Products		Scaling Advantages and Issues		Mixtures, Physical Properties		Biomedical Sensors	
S-3	SLO-1	Surface Micromachining	Medical and Biological Applications		Electrical Microactuators		Vapour Pressure, Surface Tension		Sensors for Household Appliances, Building Control	
	SLO-2	Basic Process Sequence	Inertial Sensors		Electrostatic Forces		Electrical Properties, Optical Properties, Transport Phenomena		Industrial Control	
S-4	SLO-1	Deposition, Sputtering and Etching	Accelerometers		Electrostatic Systems		Physics of Microfluidic Systems		Environmental Sensors	
	SLO-2	Epi-Micromachining	Yaw-Rate Sensors		Forces in Electrostatic Systems		Navier-Stokes Equations		Interface Circuit Architecture	
S-5	SLO-1	SIMPLE, SCREAM	Pressure Sensors		Scaling Properties		Laminar Flow, Dynamic Pressure		Requirements and Specifications	
	SLO-2	Black Silicon, MELO	Fundamentals		Electrostatic Microactuator Configurations		Fabrication Technologies		Analog Front-End	

S-6	SLO-1	Porous Silicon	Bulk-Micromachined Pressure Sensors	Gap-Closing Electrostatic Microactuators & Examples	Silicon, Plastics,	Voltage Output - Current or Charge Output
	SLO-2	SIMOX	Surface-Micromachined Pressure Sensors	Constant-Gap Electrostatic Microactuators & Examples	Quartz, Glass	Impedance Variation
S-7	SLO-1	Epi-Po1y	Signal Generation	Hybrid Electrostatic Microactuators	Microarrays	A/D Converter
	SLO-2	Release and Stiction	Force and Torque Sensors	Electrostatic Induction, Issues and Challenges	Concept, Fabrication, Particle-Based Microarray Concepts	Types of converters
S-8	SLO-1	IC Compatibility Issues	Linking the Macro World to the Micro World	Piezoelectric Microactuators	Micropumps	Digital Processing and Output Interface
	SLO-2	Compatible Bulk Micromachining	Fabrication	Piezoelectric Energy Density	Microdisplacement Pumps, Charge-Induced Pumping Mechanisms, Other Pumping Mechanisms	Digital Signal Processing
S-9	SLO-1	Compatible Surface Micromachining	Protection	Piezoelectric Microactuator Configurations & Design Issues	Microanalytical Chips	Wired Output Interfaces
	SLO-2	Compatible Epi-Micromachining	Test and Calibration	Electrostriction, Electrets, and Electro-rheological Fluids	Lab-on-a-Chip Systems, Chip-Based Capillary Electrophoresis	Wireless Output Interfaces

Learning Resources	<ol style="list-style-type: none"> 1. Jan G. Korvink, Oliver Paul, "MEMS: A Practical Guide to Design, Analysis and Applications", William Andrew, Inc. & Springer, 2006 2. Chang Liu, "Foundations of MEMS", Pearson; 2nd edition, 2011 3. Mohamed Gad-el-Hak, "MEMS: Design and Fabrication", CRC Press; 1st edition, 2005. 4. Julian W. Gardner, "Micro sensors, MEMS, and Smart Devices", John Wiley & Sons Inc, 2001 5. John A. Pelesko, "Modeling MEMS and NEMS", CRC Press; 1st edition, 2002 6. Stephen Beeby, "MEMS Mechanical Sensors", ARTECH HOUSE, INC 2004
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyse										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

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2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. D. Nedumaran, Madras University, dnmaman@gmail.com	2. Dr. A. Vimala Juliet, SRMIST

Course Code	18ECE387T	Course Name	MICRO SENSORS AND SMART DEVICES	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1:	To realize the importance of micro sensors and actuators	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	To learn the operating principle of various micro sensors	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3:	To analyze the applications of various micro fabrication techniques																		
CLR-4:	To understand the different packaging techniques																		
CLR-5:	To appreciate the significance of available MEMS based smart devices																		
CLR-6:	To recognize recent developments and challenges in MEMS																		

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Learning			Program Learning Outcomes (PLO)														
CLO-1:	Appreciate the importance of sensors and actuators based on MEMS technology	3	80	75	H	-	-	-	-	H	-	-	-	-	-	H	H	-	H
CLO-2:	Understand the fabrication and machining techniques of MEMS devices	3	80	70	H	-	-	-	-	H	-	-	-	-	-	H	-	-	H
CLO-3:	Familiarize with the concepts of packaging and interfaces in MEMS devices	3	75	70	H	H	M	H	M	H	-	-	-	-	-	H	H	-	H
CLO-4:	Appreciate the significance of general micro fabrication processes	3	80	75	H	H	M	H	M	-	-	-	H	-	-	H	-	-	H
CLO-5:	Differentiate between the working principle of various micro sensors	3	80	70	H	-	M	-	H	-	-	-	-	-	-	H	-	-	H
CLO-6:	Analyze recently developed smart devices employing MEMS technology	3	80	70	H	-	-	-	-	H	-	-	-	-	-	H	H	-	H

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction to Microelectronics	Micro thermal Sensors-overview	Micro machining techniques	MEMS Packaging	Smart Devices-Overview
	SLO-2	Evolution& History of MEMS	TEG and Thermopiles	Significance and types	Objectives in Packaging	Functionalities
S-2	SLO-1	Overview of Micro system technology	Micro radiation Sensors-overview	Bulk MMC-overview	Flip chip assembly	Features & requirements
	SLO-2	Broad applications of Micro systems	Implementation	Principle and block diagram	Ball grid array	Broad applications
S-3	SLO-1	Miniaturization & Scaling laws	Micro mechanical Sensors-overview	Surface MMC-overview	wire bonding techniques	Airbag deployment
	SLO-2	Micro devices -examples	Vibration sensor -Accelerometer	Principle and block diagram	Types	Tire pressure monitoring
S-4	SLO-1	Types of Micro Sensors	Micro pressure Sensors-overview	LIGA process-overview	surface bonding techniques	GPS-Gyro sensor
	SLO-2	Types of Micro actuators	Parameter measurement	Principle and block diagram	Types	Micro Energy harvesters
S-5	SLO-1	Si and other substrates	Micro humidity Sensors-overview	Photolithography	sealing	Smart home automation
	SLO-2	Special MEMS Materials& properties	Types of Sensing film & measurement	Process Description, implementation	Different types of sealing	MEMS devices in agriculture

S-6	SLO-1	Polymer materials	Micro SAW Sensors-overview	Ion implantation and oxidation	Process design	Blood pressure monitor
	SLO-2	Electro active polymers	Implementation	Process Description, implementation	Block diagram	Heart Parameter monitors
S-7	SLO-1	Shape memory alloys	Micro magnetic Sensors-overview	PVD-CVD	Interferences	RF MEMS technology
	SLO-2	Shape memory polymers	Significance & measurement	Process Description, implementation	Types of interferences	Optical Mirrors
S-8	SLO-1	Piezoelectric materials	Micro bio chemical Sensors-overview	Wet and dry etching	Electronic Interfacing	Micro fluidics
	SLO-2	Ceramic materials	Parameter measurement	Isotropic and Anisotropic	Electro mechanical interfacing	LOC module
S-9	SLO-1	Case study-1	Micro optical Sensors-overview	Case study-1	Case study-1	Case study-1
	SLO-2	Case study -2	Types & Implementation	Case study -2	Case study -2	Case study -2

Learning Resources	1. Marc Madou, "Fundamentals of Microfabrication" CRC Press 2. Tai Ran Tsu, "MEMS and Microsystems: Design Manufacture", Tata McGraw Hill	3. Vardhan Gardener, "Micro sensors and smart devices", John Wiley & Sons
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

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ACADEMIC CURRICULA

Professional Elective Courses

MECHANICAL ENGINEERING

Regulations - 2018



SRM INSTITUTE OF SCIENCE AND TECHNOLOGY

(Deemed to be University u/s 3 of UGC Act, 1956)

Kattankulathur, Kancheepuram, Tamil Nadu, India

Course Code	18MEE301T	Course Name	FUNDAMENTALS OF VIBRATION AND NOISE	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18MEC201T Machines and Mechanisms	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards			

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
		1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15			
CLR-1 :	Be familiar with the vibrations of two degree of freedom systems	Level of Thinking (Bloom)	Expected refficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3			
CLR-2 :	Be familiar with the vibrations of multi degree of freedom systems																					
CLR-3 :	Be familiar with the vibrations of continuous systems																					
CLR-4 :	Be familiar with the Numerical Integration methods in Vibration analysis																					
CLR-5 :	Be familiar with the vibration measurement devices																					
CLR-6 :	Be familiar with the vibrations of multi degree of freedom systems & Continuous systems, numerical integration methods in vibration analysis and vibration measuring devices																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	Able to learn the concepts of vibration analysis of two degree of freedom systems and vibration absorbers	1& 2	75	70	H	M	M	H	L	L	M	L	L	L	L	M						
CLO-2 :	Able to Understand and apply the various numerical methods for vibration analysis of three degree of freedom systems	1	75	70	H	M	M	H	L	L	M	L	L	L	L	L						
CLO-3 :	Able to learn the concepts of vibration analysis of continuous systems	1	75	70	H	M	M	L	M	L	M	L	L	L	L	L						
CLO-4 :	Able to apply the knowledge of numerical integration methods in vibration analysis	1	75	70	H	M	M	L	M	L	M	L	L	L	L	L						
CLO-5 :	Able to Understand the vibration measurement devices and condition monitoring techniques	1&2	75	70	H	H	M	M	H	L	H	L	L	M	L	M						
CLO-6 :	Able to understand the vibrations of two, multi degree of freedom systems and continuous sytems and apply the knowledge of numerical integration methods in vibration analysis and vibration measuring devices in field measurement.	1&2	75	70	H	H	M	M	H	L	H	L	L	M	L	L						

		Vibrations of Two degree of freedom systems / Module 1	Vibrations of Three Degree of freedom systems / Module 2	Vibrations of Continuous systems Numerical Integration Methods in Vibration Analysis / Module 3	Numerical Integration Methods in Vibration Analysis / Module 4	Vibration Measuring Instruments / Module 5
Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction to vibration terminologies and multidegree of freedom systems	Equation of Motion for free undamped three degrees of freedom systems using Newton's Method, Orthogonality Condition	Transverse Vibrations of String or a cable	Introduction to Finite Difference method	Vibration Measuring Devices – Transducer, Vibrometer
S-2	SLO-1	Equation of Motion for free undamped two degrees of freedom systems using Newton's method	Multidegree of freedom systems – Matrix method, Eigen Value Method – Eigen values and Eigen vector	Longitudinal vibrations of a Bar or a Rod	Central difference method for single degree of freedom systems	Vibration Measuring Devices – Accelerometer and Seismometer.
S-3	SLO-1	Equation of Motion for free undamped two degrees of freedom systems using Lagrangian energy method	Tutorials on Multidegree of freedom systems – Newton's Method, Matrix method, Eigen Value Method	Tutorials on Transverse Vibrations of Strings and Longitudinal vibrations of Rods	Central difference method for multi degree of freedom systems	Tutorials on vibrometer, Accelerometer and Seismometer.
S-4	SLO-1	Tutorials on free undamped two degrees of freedom systems using Newton's method and Lagrangian method	Influence Coefficients Method – Stiffness and Flexibility matrix – spring mass system	Torsional vibrations of rods	Tutorials on central difference method	Frequency Measuring devices – Single Reed, Multi reed and stroboscope.

S-5	SLO-1	Determine the natural frequencies and mode shapes for coordinate coupling	Dunkerly's Method for closed coupled system , Rayleigh's Method for spring mass system	Lateral Vibrations of a Beam	Runge-Kutta Method for single degree of freedom systems	Vibration exciters
S-6	SLO-1	Concept of Linear undamped vibration absorber	Tutorials on Influence Coefficients Method, Dunkerly's Method and Rayleigh's Method	Tutorials on Torsional vibration of rods and lateral vibration of a Beams	Runge-Kutta Method for multi degree of freedom systems	Tutorials on vibration exciters.
S-7	SLO-1	Tutorials on coordinate coupling and Linear undamped vibration absorber	Concept of Holzer's Method for Far Coupled systems and Close Coupled Sytems	Rayleigh's method for continuous system	Tutorials on Runge-Kutta Method	Experimental Modal Analysis, Condition Monitoring techniques
S-8	SLO-1	Torsional Vibration of Two rotor systems.	Torsional Vibration of Three rotor systems- Equivalent Length Determination	Rayleigh's Ritz method for continuous system	Finite Difference Methods for Longitudinal vibration of bars	Balancing Machines – Single plane and two plane balancing
S-9	SLO-1	Torsional Vibration of Geared Systems with Two rotor System	Tutorials on Holzer's method and Three rotor systems.	Tutorials on Rayleigh's method and Rayleigh's Ritz method	Finite Difference Methods for transverse vibration of beams	Tutorials on Modal analysis

Learning Resources	<ol style="list-style-type: none"> 1. Rao.S.S, "Mechanical Vibrations", 5th Edition, Pearson Education Inc. Delhi 2009. 2. Ambekar.A.G, "Mechanical Vibrations and Noise engineering", PHI New Delhi, 2015. 3. Thomson.W.T, "Theory of Vibration and its Applications", 5th Edition, Prentice Hall, New Delhi, 2001. 4. Meirovitch, L., "Elements of Vibration Analysis", Mc Graw – Hill Book Co., New York, 1986. 5. Rao.J.S and Gupta.K, "Introductory course on theory and practice of mechanical vibrations", 2nd Edition, New Age International, New Delhi, 2014. 6. Ramamurthi.V, "Mechanical Vibration Practice with Basic Theory", 1st edition, Narosa Publishing House, Chennai, 2000.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc,

INDUSTRIAL EXPERT	ACADEMIC EXPERT	INTERNAL EXPERT
1. Dr. R. Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in, rkpearls@yahoo.com	Dr. RAJENDRA MACHAVARAM, IIT KHARAGPUR	V.N.B PRASAD SODISETTY, SRMIST
2. Dr. A. Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	RAGHAVENDRA BEJGAM ENGINEERING PROJECT LEAD, PENTAIR, NOIDA.	Dr. P. Nandakumar, SRMIST

Course Code	18MEE302T	Course Name	INDUSTRIAL TRIBOLOGY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	PSG Design Data book		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Understand and analyze the surfaces and friction	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Understand and analyze the wear mechanisms	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Understand and analyze the film theory	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Understand and analyze the lubricants and lubrication phenomenon	Expected Attainment (%)	Design & Development
CLR-5:	Understand and analyze the surface engineering processes and select suitable materials for bearing		Analysis, Design, Research
CLR-6:	Understand and solve various engineering problems		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of the course, student will be able to:		
CLO-1 :	Understand friction and engineering surfaces	1, & 2 100 85	H H H H H H H H H H H H H H H H
CLO-2 :	Apply the knowledge and analyze the failure occurred due to various types of wear	3 & 4 100 85	H H H H H H H H H H H H H H H H
CLO-3 :	Apply the knowledge of lubrication to provide solutions	3 & 4 100 85	H H H H H H H H H H H H H H H H
CLO-4 :	Analyze various surface conditions and provide new ideas of surface protection techniques	3 & 4 100 85	H H H H H H H H H H H H H H H H
CLO-5:	Formulate new materials	5 100 85	H H H H H H H H H H H H H H H H
CLO-6:	Investigate the failure of a system	5 100 85	H H H H H H H H H H H H H H H H

		Surfaces and friction	Wear	Film lubrication theory	Lubricants and lubrication	Surface engineering and materials for bearings
Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction to the concept of tribology, Tribological problems	Introduction, background of Wear and Types of Wear with applications.	Introduction to Viscosity and its importance in lubrication.	Types of lubricants and their properties	Introduction to surface engineering
S-2	SLO-1	Nature of engineering surfaces, Surface topography	Abrasive wear	Influence of various particles on viscosity of a lubricant.	Stribeck Curve and its importance	Surface treatments
S-3	SLO-1	Surface profilometer, measurement of surface topography; importance of roughness parameters	Adhesive wear	Fluid film in simple shear, Viscous flow between very close parallel plates.	Boundary and Mixed Lubrication regime	Coatings and cladded plates
S-4	SLO-1	Contact between surfaces, Sources of sliding Friction, Friction characteristics of metals and non-metals	Wear due to corrosion	Shear variation within the film, Lubricant supply, lubricant low rate.	Hydrodynamic lubrication	In situ formed tribo films
S-5	SLO-1	Friction due to ploughing, Friction due to adhesion	Fatigue and fretting wear	Cold jacking, Couette flow,	Elasto hydrodynamic lubrication(EHL); Problems on EHL	Surface Texturing
S-6	SLO-1	Sources of rolling friction, Stick slip motion	Wear in metals	Cavitations, film rupture and oil whirl	Importance of film thickness, Lambda ratio	Tribo corrosion
S-7	SLO-1	Friction of ceramic materials	Wear in polymers	Petroff's equation	Bio degradable lubricants	Surface analysis techniques
S-8	SLO-1	Friction of polymers	Wear of ceramics	Reynolds equation	Nano lubricants	Materials for bearings
S-9	SLO-1	Measurement of friction	Measurement of wear, Ferrography and oil analysis	Sommerfield Number	Hertzian contact and problems on Hertzian contacts	Condition monitoring

Learning Resources	1. Hutchings.I.M and Shipway P, "Tribology, Friction and Wear of Engineering Material, Elsevier Butterworth –Heinemann , UK, 2017. 2. Bharat Bhushan, "Introduction to tribology", Wiley Publication, 2013. 3. Williams.J.A, "Engineering Tribology", Oxford University Press, 2005. 4. GwidonStachowiak, Andrew W Batchelor., "Engineering tribology", Elsevier Butterworth –Heinemann, USA, 2005. 5. Stolarski.T.A, "Tribology in Machine Design", Industrial Press Inc., 1990. 6. Cameron.A, "Basic Lubrication Theory", Longman, U.K., 1981. 7. Neale.M.J., "Tribology Handbook", Newnes Butter worth, Heinemann, U.K., 1975.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

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Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. R. Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in, rkpearls@yahoo.com	Dr.P. Ramkumar, IITM, ramkumar@iitm.ac.in	Mr. ShubrajitBhaumik, SRM IST ,
2. Dr. A. Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	Dr.Chiradeep Ghosh , chiradeep.ghosh@tatasteel.com, Tata Steel	Dr. TVVNL Rao, SRMIST

Course Code	18MEE303T	Course Name	MECHANISM DESIGN, ANALYSIS AND SYNTHESIS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18MEC201T Machines and Mechanisms	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department		Mechanical Engineering		Data Book / Codes/Standards	
				NIL	

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
					1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
					Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	Determine the position, velocity and acceleration of simple and complex linkages.	1.2 & 3	75	65				H	H	M	M	H	-	-	-	-	-	-	L			
CLO-2 :	Synthesize a linkage based on the given working conditions	1.2 & 3	75	65				H	H	H	H	H	-	-	-	-	-	-	L			
CLO-3 :	Find the conjugate points, radius of curvature and acceleration at any point on the coupler link.	1.2 & 3	75	65				H	H	M	H	H	-	-	-	-	-	-	L			
CLO-4 :	Find forces/moments in various links with or without considering inertia of links	1.2 & 3	75	65				H	H	H	M	H	-	-	-	-	-	-	L			
CLO-5 :	Determine the position, velocity and acceleration of spatial linkages and robot linkages	1.2 & 3	75	65				H	H	H	H	H	-	-	-	-	-	-	L			
CLO-6 :	Do the kinematic and dynamic analysis of mechanisms in addition to its synthesis.	1.2 & 3	75	65				H	H	H	H	H	-	-	-	-	-	-	L			

S-9	SLO-1	Problems on velocity and acceleration of mechanisms by Graphical method	Cognate linkages by the Roberts – Chebyshev theorem	The cubic Stationary curvature - Ball's Point	Problems on Balancing of linkages	Robot actuator force analysis
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Learning Resources	<ol style="list-style-type: none"> 1. Uicker J. J., Gordon R. Pennock & Joseph E. Shigley John J. Uicker "Theory of Machines and Mechanisms", Oxford Higher education, 2014. 2. Rao, J. S., and Dukupatti, R.V., "Mechanisms and Machine Theory", 2nd Edition, New Age international (P) Ltd., 1995 3. Sander, G. N. and Erdman A. G., Mechanism Design, Analysis and Synthesis Vol: I and Vol: II, Prentice Hall, 1990. 4. Norton, R. L., Design of Machinery, McGraw Hill, 1999. 5. Hamilton H Mabie and Charles F. Reinhofz, Mechanisms and Dynamics of Machinery, John Wiley & Sons, 1987. 6. Amitabha Ghose and Ashok Kumar Malik, Theory of Mechanisms and Machines, EWLP, Delhi, 1999. 7. R.S.Hartenberg and J. Denavit, "Kinematic Synthesis of Linkages", Mc. GrawHill Book Company, 1964
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	1. Dr. Shankar Krishnapillai, skris@iitm.ac.in, IIT Madras	1. Dr P. Nandakumar, SRMIST
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	2. Dr.R.Prabhu sekar, rprabhusekar@mnnit.ac.in, MNNIT Allahabad	2. Mr. K.R. Arunprasath, SRMIST

Course Code	18MEE304T	Course Name	DESIGN FOR MANUFACTURING AND ASSEMBLY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	To study how a design can be made suitable for various manufacturing and assembly process requirements	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15			
CLR-2 :	Application of this study to various Casting and welding.	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3			
CLR-3 :	Application of this study to various forging, and machining processes				H	--	H	--	--	--	--	--	--	--	--	--	--	--	--	--	--	
CLR-4 :	To study about the various assembly methods and processes				H	H	H	H	--	--	--	--	--	--	--	--	--	--	--	--	--	
CLR-5 :	Know the effect of manufacturing process and assembly operations.				H	H	H	H	--	--	--	--	--	--	--	--	--	--	--	--	--	
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	Students will demonstrate the ability to identify needs of the customer and convert them in to technical specifications of a product.	1 & 2	90	85	H	--	H	--	--	--	--	--	--	--	--	--	--	--	--			
CLO-2 :	Know the manufacturing issues that must be considered in the Casting and welding	1	85	80	H	H	H	H	--	--	--	--	--	--	--	--	--	--	--			
CLO-3 :	Know the manufacturing issues that must be considered in the forging and machining processes.	1	85	80	H	H	H	H	--	--	--	--	--	--	--	--	--	--	--			
CLO-4 :	Students will understand the principals used while designing for manufacture, assembly.	1&2	85	80	H	H	H	H	--	--	--	--	--	--	--	--	--	--	--			
CLO-5 :	Students will understand principles of assembly to minimize the assembly time.	1&2	85	80	H	H	H		--	--	--	1&2	--	--	--	--	--	--	--			

Duration (hour)		Learning Unit / Module 1	Learning Unit / Module 2	Learning Unit / Module 3	Learning Unit / Module 4	Learning Unit / Module 5
		9	9	9	9	9
S-1	SLO-1	Significance of design- Systematic working plan-The engineering problem to be solved-The basic design	Influence of loading, Materials, Production methods on form design	Forging Considerations-Hammer forging-Drop forging	DFA-Introduction-Distinction between assembly methods and processes	Approaches to design for assembly-Introduction
S-2	SLO-1	Factors influencing choice of materials-The factors influencing manufacturing	Casting considerations-Grey iron castings	Requirements and rules for forging.	Factors Determining assembly methods and processes-Success and failure-Causes of failure	Approaches based on design principles and rules-Example DFA method using Design Principles
S-3	SLO-1	Process Capability-Mean, Median, Variance, Mode, Standard Deviation, Normal Distribution- Process capability metrics-	Steel castings -Aluminum Casting-Requirements and rules for casting	Redesign of components for forging.	Product Design factors independent of methods and processes-Introduction-Number of operations in the product	DFA Systems employing Quantitative evaluation procedures-IPA Stuttgart Method
S-4	SLO-1	Process Capability and Defect Rate, Assumptions, Conditions and Precautions in process capability	Form design of pressure die castings	Choice between casting, forging and welding.	Assembly Precedence-Standardization. Case studies in assembly precedence.	DFA Methods employing a Knowledge-based approach-Knowledge Representation
S-5	SLO-1	Process Capability-Simple problems	Redesign of components for casting- Pattern-Mould-Parting Line	Machining Considerations-Drills-Milling-Keyways-Dwells and Dwelling Procedure-Countersunk Head screws	Design factors dependent on Assembly methods-Introduction-Single Station Assembly	Computer Aided DFA methods-Part model-Feature Processing
S-6	SLO-1	Tolerances-symbols and Definition	Welding considerations-Welding Processes	Requirements and rules for Machining considerations-Reduction of machined areas	Line Assembly-Hybrid Systems-Manual Assembly Lines-Flexible Assembly Lines	Assembly measures-Qualitative and Quantitative measures
S-7	SLO-1	Tolerances relevant to manufacturing, Assembly- Material condition	Requirements and rules for welding	Redesign of components for Machining.	Design factors dependent on Assembly processes-Factors Influencing Production rate to Facility Ratio-Parts Presentation-Manual Assembly	Boothroyd and Dewhurst DFA method- Objectives of the method

S-8	SLO-1	<i>Tolerance stack- effects on assembly-Examples</i>	<i>Redesign of components for welding</i>	<i>Simplification by separation-Simplification by Amalgamation</i>	<i>Dedicated Assembly-Transportation-Separation-Oriented-Flexible Assembly</i>	<i>Redesign of a simple product-Small consumer product-Fastener solution-Redesign using symmetry</i>
S-9	SLO-1	<i>Methods of eliminating tolerance stack-Examples</i>	<i>Case studies in Form Design-simple problems in form design</i>	<i>Case studies- forging and Machining</i>	<i>Gripping-Transferring-Part Insertion-Failures-Error Recovery</i>	<i>Case Studies-Designing of a disposal valve-Design of a lever-arch file mechanism</i>

Learning Resources	<ol style="list-style-type: none"> 1. Harry Peck., <i>Design for Manufacture</i>, Pittman Publications,1983. 2. Alan Redford and ch, <i>Design for Assembly-Principles and Procedures</i>, McGraw Hill International Europe, London, 1994. 3. Robert Matousek,<i>Engineering Design-A Systematic Approach</i>,Blackie&sons Ltd.,1963. 4. James G.Bralla,<i>Hand Book of Product design for Manufacturing</i>,McGraw Hill Co.,1986. 5. Swift,K.G.,<i>Knowledge Based Design for Manufacture</i>,Kogan Page Ltd.,1987. 					
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

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1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	Dr. Davidson Jebaseelan, davidson.jd@vit.ac.in VIT Chennai.	Mr. P.Susai Manickam, SRM IST, Chennai
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	Mr. Vignesh Shanmugam.s Hyundai Motors Limited, Chennai E mail – 273357@hmlil.net	Dr. P. Nandakumar SRM IST, Chennai

Course Code	18MEE305T	Course Name	FINITE ELEMENT METHOD	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18MEC106T Mechanics of Solids, 18MAB202T Numerical methods	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR): <i>The purpose of learning this course is to:</i>		Learning			Program Learning Outcomes (PLO)																
CLR-1 :	<i>Find the approximate solution of boundary value problems</i>	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2 :	<i>Know the variational and Weighted residual approaches to solve differential equations</i>																				
CLR-3 :	<i>Develop basic finite element concepts and solution procedure</i>																				
CLR-4 :	<i>Formulate the element stiffness and mass matrices for various one and two dimensional elements</i>																				
CLR-5 :	<i>Formulate the element heat conductance and convection matrices one dimensional element</i>																				
CLR-6 :	<i>To formulate and solve problems in solid mechanics, Eigen Value and heat transfer using finite element method.</i>																				
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																			
CLO-1 :	<i>Solve the differential equations using weighted residual and variational approaches.</i>	1,2&3	75	65	H	H	L	H	M	-	-	L	L	-	-	M					
CLO-2 :	<i>Solve the structural analysis problems, such as bar, truss and beam using 1D element.</i>	1,2 &3	70	65	H	H	L	H	M	-	-	L	L	-	-	M					
CLO-3 :	<i>Analysis of two-dimensional structural problems on plane triangular and quadrilateral elements.</i>	1,2 &3	70	65	H	H	L	H	M	-	-	L	L	-	-	M					
CLO-4 :	<i>Be able to solve Eigen Value problems in solid mechanics using finite element method.</i>	1,2 &3	65	65	H	H	L	H	M	-	-	L	L	-	-	M					
CLO-5 :	<i>Be able to solve one dimensional heat transfer problems using finite element method</i>	1,2 &3	70	65	H	H	H	H	H	-	-	L	L	-	-	M					
CLO-6 :	<i>Analyze structural and heat transfer problems using Finite Element</i>	1,2 &3	65	60	H	H	M	M	M	-	-	L	L	-	-	M					

Duration (hour)		Introduction to FEA	1D Linear Static Analysis	2D Linear Static Analysis	Dynamic Analysis of Structures	1D Heat Transfer Problems
		9	9	9	9	9
S-1	SLO-1	Basics of FEA, Historical background, applications of FEA in engineering, modelling of discrete and continuum models	Finite element procedure for a continuum problem, discretization, types of elements	Introduction to two dimension elasticity, plane stress and strain conditions	Dynamic analysis, Formulation- Hamilton's Principle, lumped and consistent mass models	Review of fundamentals of heat Transfer
S-2	SLO-1	Variational problems, Euler's equation	Selection of interpolation function, shape function, derivation of element stiffness matrix for a one dimensional bar element	Constant strain triangular element, Area coordinate system, shape function, strain displacement matrix	Derivation of lumped and consistent mass matrices for axial bar element, formulation of eigen value problem	Governing equations and boundary conditions for Heat transfer
S-3	SLO-1	Rayleigh-Ritz method, minimum potential energy, Example problem, solving differential equation	assembly of elements, imposing boundary conditions, calculation of element stress, example problems	Derivation of element stiffness matrix for a CST element	Determination of natural frequencies and normal mode shapes of axial vibration	Derivation of conductance matrix for steady state 1D heat conduction
S-4	SLO-1	Weighted residual approaches, collocation method, subdomain method, Galerkin method and least square method	Tutorial Problems on axial loading of bars	Tutorial on two dimensional plate problems with CST elements	Problems on natural frequencies and normal mode shapes of axial vibration	Tutorial on Steady state 1D heat conduction
S-5	SLO-1	Example problem, solving differential equations using weighted residual approaches	Local and global coordinate systems	LST and four noded quadrilateral elements, isoparametric formulation	Derivation of lumped and consistent mass matrices for beam element	
S-6	SLO-1	Galerkin's Finite Element method for solving differential equations, example problems, comparison of results with different methods	Analysis of truss, coordinate transformations, Derivation of the stiffness matrix		Determination of natural frequencies and normal mode shapes of beam	Derivation of element matrix for steady state 1D heat conduction including convection

S-7	SLO-1	Spring element, formulation of stiffness matrix, assembly procedure for global stiffness matrix, applying boundary conditions	Assembly of stiffness matrix for a truss, Tutorial Problems on Trusses	Gaussian quadrature Integration- Derivation of one point and two point formula	Determination of natural frequencies and normal mode shapes of beam	Tutorial on Steady state 1D heat conduction with convection
S-8	SLO-1	Solution of linear algebraic equations, Gauss elimination method, Cholesky decomposition, example problems	Beam element, Hermite shape functions, derivation of element stiffness matrix of a beam element.	Problems using Gaussian quadrature with one and two points	Problemson eigen value problems on beams	Solution of simple Heat Transfer 1-D and 2-D steady state problems using a FEA software
S-9	SLO-1	Tutorial problems on springs with series and parallel combinations	Calculation of load vector for point, uniform distributed and varying loads on beams	Lagrange interpolation functions for serendipity family elements	Derivation of lumped and consistent mass matrices for a CST element	Introduction to transient heat transfer problems

Learning Resources	<ol style="list-style-type: none"> 1. Hutton, D.V., "Fundamentals of Finite Element Analysis", McGraw Hill, International Edition, 2004. 2. Chandrupatla, T.R., Belegundu, A.D., "Introduction to Finite Elements in Engineering", Prentice Hall of India, 1997. 3. P.Seshu, "Text book of Finite Element Analysis", PHI learning Private Ltd., 2012. 4. S.S.Rao, "The Finite Element method in Engineering", Elsevier Science & Technology Books, 2004 5. Cook R.D., Malkus, D.S., Plesha, M.E., Witt, R.J., "Concepts and Applications of Finite Element Analysis", 4th Edition, John Wiley & Sons, 2001. 6. J.N Reddy, An introduction to the Finite Element Method, 2005, McGraw Hill
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
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	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

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Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	1. Dr. Atanu Banerjee, atanub@iitg.ac.in, IIT Guwahati	1. Dr P. Nandakumar, SRMIST
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	2. Dr.R.Prabhusekar, rprabhusekar@mnnit.ac.in, MNNIT Allahabad	2. Mr.P. SusaiManikam, SRMIST

Course Code	18MEE306T	Course Name	ADVANCED STRENGTH OF MATERIALS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18MEC106T Mechanics of Solids	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):		Learning			Program Learning Outcomes (PLO)														
		1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-1 :	Be able to Compute the combined effect of deformation/loading arising out of different causes as applied to structural members made of linear, homogeneous, isotropic material so as to be able to predict (as part of a different course) failure of components/sub-systems of a product																		
CLR-2 :	Be able to Compute the effect of deformation/loading in straight and curved beams (a class of primary structural member) subjected to bending (a type of primary loading)																		
CLR-3 :	Be able to Study the effect of bending (a type of primary loading) deformation/load as applied to flat thin plates (a class of primary structural member)																		
CLR-4 :	Be able to Study the use of energy methods in structural analysis as an alternative means of solving a structural mechanics problem																		
CLR-5 :	Be equipped with analytical skills the learning process of which has a bearing in professional practice in understanding difference(s) between exact and approximate solution procedures																		
CLR-6 :	Be able to analyze effects of typical loadings on primary structural members using approximate or exact methods as applicable																		
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																	
		Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Perform 2D & 3d stress and strain transformation and arrive at maximum values for normal and shear stresses and find the planes on which these stresses act	1, 2	90	75	H	H													
CLO-2 :	Determine i) bending stress in straight beams (due to unsymmetrical bending), ii) transverse shear stresses in straight beams and locate shear center for specified cross-sections, and iii) circumferential (bending) stresses in curved beams	1, 2	90	75	H	H													
CLO-3 :	i) Derive expressions for displacement/strains, stresses, and moments, ii) derive (using these expressions) the governing equation for bending of flat rectangular and axi-symmetric circular plates. Use the expressions for computing these parameters in specified cases	1,2	90	75	H	H													
CLO-4 :	Compute strain energy due to various loadings and using it to determine deflection	1,2	90	75	H	H													
CLO-5 :	Understand the primary difference between theory of elasticity and mechanics of materials approaches and solve plane stress, torsional, and rotating disk problems	1,2	90	75	H	H													
CLO-6 :	Determine displacements, strains, and stresses related to primary structural members	1,2	90	75															

Duration (hour)		Stress & Strain Theory	Bending of Straight & Curved Beams	Bending of flat thin plates	Energy Methods	Theory of Elasticity & Its Applications
		9	9	9	9	9
S-1	SLO-1	Introduction – course overview, Equilibrium, compatibility, and constitutive relations in macroscopic form, Definition of stress at a point in 3D, representation on an element and sign convention	BendingStresses in beams (initially straight) due to symmetrical loading – review and definition of un-symmetrical bending	Introduction to flat plates – definition of a plate, rectangular and axi-symmetric circular plates, thin vs thick plates, comparison with beams (1D) as a structural member (2D), typical real-world applications. Linear vs non-linear bending – definition. Derivation of governing equation for bending of a flat, thin, rectangular plate – outline of procedure	Work, Strain energy definition for linear, perfectly elastic materials; strain energy due to - uniaxial stress, additional normal stresses in other perpendicular directions, shear stress	Introduction to and comparison with mechanics of materials approach, definition of Plane stress and plane strain linear elastic problems

S-2	SLO-1	concept of a tensor (in relation to a scalar and a vector), 2D stress transformation in Cartesian coordinate system using direction cosines	Bending stresses in beams due to un-symmetrical bending (plane of loading not coinciding with plane of symmetry, even if it exists) – explanation of theory in decoupling the problem into sub-problems using the concept of principal axes and moments of inertia	definition of strains, stresses, and moments and use of these parameters in derivation of governing equation for plate bending (based on Kirchhoff theory) – use of strain-displacement, and stress-strain relations	strain energy due to - general state (3D) of stress, plane stress	Plane stress and plane strain linear elastic problems - Airy's stress function in rectangular coordinates – derivation of the biharmonic equation
S-3	SLO-1	3D stress transformation in Cartesian coordinate system using direction cosines	Application of theory in computing bending stresses and determination and location of neutral axis	Use of equilibrium equations and completion of derivation of governing equation; specification of different boundary conditions generally used – simply supported, clamped, free	Total strain energy in bars with simple loading conditions – axial loading, torsional loading of a solid circular bar, and transverse loading	simple problems related to bending of beams using Airy's stress function in rectangular coordinates
S-4	SLO-1	principal stresses in 3D (after a quick review in 2D)	Deflection due to unsymmetrical bending; Intro to shear center, determination of shear center for a symmetrical channel section	Solution due to sinusoidal bending load on a simply supported plate– step-by-step explanation	Castigliano's 1 st theorem, example problems	Additional problems related to bending of beams using Airy's stress function
S-5	SLO-1	Numerical problems (in 2D and 3D based on the above lectures)	determination of shear center for T, unequal I sections	Numerical problems on thin, flat rectangular plates	brief overview of material non-linearity and plasticity; The complementary energy theorem, and Castigliano's 2 nd theorem,	overview of torsion of rectangular cross section structural members, Prandtl stress function for torsion, derivation of Poisson's equation (using Prandtl stress function)
S-6	SLO-1	octahedral normal and shear stresses, definition of strain based on small-displacement theory and strain tensor in Cartesian coordinate system	intro to bending of curved beams	Derivation of governing equation for bending of a flat, thin, axis-symmetric circular plate – outline of procedure - definition of strains, stresses, and moments	example problems using Castigliano's 1 st & 2 nd theorems (for linear materials)	Membrane analogy, brief discussion of torsion of rectangular cross section
S-7	SLO-1	strain transformation and principal strains in 3D for linear, homogeneous, isotropic material	Derivation of circumferential stress expression	use of strain-displacement, stress-strain, and equilibrium relations in derivation of governing equation (for bending)	Rayleigh's method, example problem of beam bending deflection	torsional stress in hollow closed thin-walled (single cell) tubes – overview and expressions for shear stress and angle of twist
S-8	SLO-1	Numerical problems on 3D strain computation, transformation, and determination of principal strains	Numerical problems on determination of circumferential stresses (rectangular and square sections)	derivation of equations for displacement, support reactions, and maximum stresses for a uniformly loaded, simply supported circular plate	Rayleigh-Ritz method applied to beams in bending	Stresses due to rotation - Radial and tangential stresses in a disc of uniform thickness – derivation of expression for the stresses due to rotation at a constant angular speed; maximum stresses
S-9	SLO-1	equilibrium and compatibility relations in differential form, boundary conditions and St. Venant's principle	Additional numerical problems on determination of circumferential stresses (rectangular and square sections); a brief intro (only) to radial stresses in curved beams	Numerical problems on bending of flat, thin, axis-symmetric circular plates	problems based on Rayleigh-Ritz method	Problems related to computation of Radial and tangential stresses in a rotating disc of uniform thickness based on the previous lecture

Learning Resources	<ol style="list-style-type: none"> 1. Arthur Boresian and Richard Schmidt, "Advanced Mechanics of Materials," John Wiley & Sons, 6ed, 2009 2. Ansel C. Ugural and Saul K. Fenster, "Advanced Mechanics of Materials and Applied Elasticity," Prentice Hall; 5th ed., 2011 3. Richard G Budynas, "Advanced Strength and Applied Stress Analysis," McGraw Hill International Editions, 1999 4. L. S. Srinath, "Advanced Mechanics of Solids," McGraw Hill Education, 3rd edition, 2017 5. S. P. Timoshenko and J N Goodier, "Theory of Elasticity," McGraw Hill 2017 6. G. T. Mase, R. E. Smelser, and G. E. Mase, "Continuum Mechanics for Engineers," 3rd edition, CRC Press, 2004 7. Y. C. Fung, "Foundations of Solid Mechanics," Prentice Hall International, 1965 8. Stephan H Crandal, Norman C Dahl, Thomas J Lardner, "An Introduction to the Mechanics of Solids," McGraw Hill, 2nd edition, 1978 9. Robert Cook and Warren Young, "Advanced Mechanics of Materials," Pearson, 2nd edition, 1998
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	1. Dr. Joel George, IIT Madras, joel@ae.iitm.ac.in	Dr. S. H. Venkatasubramanian, SRMIST
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	2. Dr.Ranjith Mohan,IIT Madras, ranjith.m@iitm.ac.in	

Course Code	18MEE307T	Course Name	AUTOMOTIVE ENGINEERING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department		Mechanical Engineering		Data Book / Codes/Standards	
				NIL	

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																	
					1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15			
					Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3			
CLR-1 :		Be familiar with the understanding of automotive architecture and performance						H	L	L	L	M	L	L	L	L	L	L	L	L	L	L	L	H	L
CLR-2 :		Be familiar with the transmission system						H	L	L	L	M	L	L	L	L	L	L	L	L	L	L	L	H	L
CLR-3 :		Know the working of wheels, tyres, and braking system						H	L	L	L	M	L	L	L	L	L	L	L	L	L	L	L	H	L
CLR-4 :		Be familiar with the suspension and steering system						H	L	L	L	M	L	L	L	L	L	L	L	L	L	L	L	H	L
CLR-5 :		Be familiar with the electrical system and advances in automotive engineering.						H	L	L	L	M	L	L	L	L	L	L	L	L	L	L	L	H	L
CLR-6 :		Understand the structure, transmission system, suspension system, steering system, electrical system and working of wheels, tyres in automotive Engineering						H	L		L	M	L	L	L	L	L	L	L	L	L	L	L	L	L
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																							
CLO-1 :		Broaden the understanding of automotive architecture and performance			1&2	90	85																		
CLO-2 :		Introduce the transmission system			1,2&3	90	85																		
CLO-3 :		Familiarize about the wheels,tyres,and braking system			1	90	85																		
CLO-4 :		Understand the suspension and steering system			1,2&3	90	85																		
CLO-5 :		Familiarize in electrical system in automotive engineering.			1,2&3	90	85																		
CLO-6 :		Familiarize all the systems involved in automotive Engineering			1,2&3	90	85																		

		Automobile Architecture and Performance	Transmission Systems	Wheel, Tyres, and Braking system	Suspension and steering System	Electrical System and Advances in Automotive Engineering
Duration (hour)		9	9	9	9	9
S-1	SLO-1	Automotive components	Clutch types, coil spring and diaphragm type clutch.	Types of wheels, construction, wired wheels	Types front and rear suspension	Battery, general electrical circuits
S-2	SLO-1	Subsystem and their position of chassis	Single and multi-plate clutch	Types, construction, radial, bias tires and belted bias tires	Conventional and independent type suspension	Dash board instrumentation
S-3	SLO-1	Frame and body	Centrifugal clutch	Slip angle, tread patterns	Leaf springs, coil springs, dampers	Chip formation and its passenger comfort, safety and security
S-4	SLO-1	Front, rear and four wheel drives	Gear box types, constant mesh, sliding mesh	Tyre retreading cold and hot, tubeless tyres	Torsion bars, stabilizers bars, arms ,air suspension system	Heating, ventilation and air-conditioning(HVAC), seat belts, air bags
S-5	SLO-1	Operation and performance	Synchromesh gear box	Forces on vehicles, tyre grip	Types of steering system, Ackermann principle	Automotive electronics, Electronic Control Unit(ECU)
S-6	SLO-1	Traction force	Layout of gear box, Gear selector and shifting mechanism	Load transfer, braking distribution between axles, stopping distance	Davis steering gear, steering gear boxes, steering linkages	Variable Valve Timing(VVT), Active suspension system (ASS)
S-7	SLO-1	Traction resistance	Overdrive, automatic transmission	Types of brakes, mechanical, hydraulic brakes	Introduction to sheet metal working and applications	Electronic Brake Distribution(EBD)
	SLO-2		Rolling air, gradient resistance		Power steering , wheel geometry	
S-8	SLO-1	Power required for automobile,	Propeller shaft, universal joint, slip joint	Air brakes, Disc and Drum brakes	Caster, camber toe in,toe out	Electronic Stability program (ESP), Traction control System(TCS)
S-9	SLO-1	Power required for automobile,	Differential and real axle arrangement, hydraulic coupling	Engine brakes, antilock braking system	Wheel Alignment and balancing	Global positioning system(GPS), Electric Hybrid Vehicle

Learning Resources	1. Kirpal Singh, "Automobile Engineering", standard publishers; Vol-I & II, 2017 2. Ramalingam, K. K, "Automobile Engineering", SciTech publications, 2014 3. Rajput R K, "A Text book of Automobile Engineering", Laxmi Publications., 2015 4. Crouse, W.H and Anglia, D.L "Automotive Mechanics", Tata McGraw Hill, 2005 5. Narang, G.B, "Automobile Engineering", khanna publishers, 2001 6. Kamaraju Ramakrishna, "Automobile Engineering", PHI Learning Pvt Ltd, 2012.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	DR. K.L.HARIKRISHNA SSN COLLEGE OF ENGINEERING	Mr. C. Subramanian, SRMIST
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cwrde.drdo.in		Dr.P.Nandakumar, SRMIST

Course Code	18MEE308T	Course Name	FOUNDATION SKILLS IN INTEGRATED PRODUCT DEVELOPMENT	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):		The purpose of learning this course is to:		
CLR-1 :	Understand the fundamentals of Product Development			
CLR-2 :	Understand requirement Engineering and System Design			
CLR-3 :	Understand Conceptual design			
CLR-4 :	Understand detail design			
CLR-5 :	Understand Obsolescence management and IPR			

Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:		
CLO-1 :	Do global trend and PESTEL analysis			
CLO-2 :	Perform requirement Engineering			
CLO-3 :	Develop conceptsfor products as solution to engineering problem			
CLO-4 :	Perform verification and validation			
CLO-5 :	Perform maintenance requirement			

Learning		
1	2	3
Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)

Program Learning Outcomes (PLO)														
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
H		H			H	H		H						
H		H			H	H		H						
H		H			H	H		H						
H	H				H	H		H						

Duration (hour)		09	09	09	09	09s
S-1	SLO-1	Global Trends Analysis and Product decision: Types of various trends affecting product decision -Social Trends(Demographic, Behavioral, Psychographic ,	Requirement Engineering: Types of Requirements (Functional, Performance, Physical ,Regulatory, Economical, Behavioral);	Conceptualization: Industrial Design and User Interface Design	System Integration, Testing, Certification and Documentation: Manufacturing/Purchase and Assembly of Systems	Sustenance: Maintenance
S-2	SLO-1	Economical Trends(Market, Economy, GDP, Income Levels,Spending Pattern, target cost, TCO), Technical Trends(Technology,Applications, Tools, Methods)	Types of Requirements (, Technical, Stakeholder, Environmental, Industry specific, Internal-Company Specific)	Introduction to Concept generation Techniques	Integration of Mechanical, Embedded and S/W systems;	Sustenance: Repair; Enhancements.
S-3	SLO-1	Environmental Trends(Environmental Regulations and Compliance), Political/Policy Trends,(Regulations, Political Scenario, IP Trends and Company Policies);PESTLE Analysis	Requirement Engineering (Gathering (VOC)	Concept Screening & Evaluation - Concept Design	Introduction to Product verification processes and stages - Industry specific (DFMEA)	Product EoL: Obsolescence Management
S-4	SLO-1	Introduction to Product Development Methodologies and Management: Overview of Products and Services (Consumer product, Industrial product, Specialty products etc)	Analysis (QFD)	S/W Architecture, Hardware Schematics and simulation	Introduction to Product verification processes and stages - Industry specific (FEA, CFD)	Configuration Management; EoL Disposal.
S-5	SLO-1	Types of Product Development (NPD/ Re-Engineering (Enhancements, Cost Improvements)/ Reverse Engineering	Design Specification	Detailed Design: Component Design and Verification	Introduction to Product validation processes and stages Industry specific (Sub-system Testing/ Integration Testing	The Industry: Engineering Services Industry - overview; PLM,Product development in Industry versus Academia
S-6	SLO-1	Design Porting & Homologation));	Traceability Matrix and Analysis	High Level Design/Low Level Design of S/W Programs, S/W testing;	Introduction to Product validation processes and stages Industry specific (Functional Testing/ Performance Testing / Compliance Testing	The IPD Essentials: Introduction to vertical specific product development processes

S-7	SLO-1	Overview of Product Development methodologies (Over the Wall/ Waterfall/ V-Model/ Stage-Gate Process/ Spiral/Systems Engineering/ Agile)	Requirement Management	Hardware Schematic, Component design, Layout and Hardware Testing.	Product Testing standards and Certification - Industry specific;	Product development Trade-offs
S-8	SLO-1	Product Life Cycle (S-Curve, Reverse Bathtub Curve)	Introduction to System Modeling, System Optimization	Prototyping: Types of Prototypes (Mockups, Engineering Assessment Prototype, Alpha, Beta, Gamma)	Product Documentation (Compliance Documentation, Catalogue, Brochures, user manual)	Intellectual Property Rights and Confidentiality
S-9	SLO-1	Product Development Planning and Management (Budgeting, Risk, Resources and Design Collaboration) Product Development Planning and Management (Scheduling, Change Management, Product Cost Management)	System Specification; Sub-System Design; Interface Design.	Introduction to Rapid Prototyping and Rapid Manufacturing	Product Documentation (maintenance Manual, Spares Parts List, Warranty, Disposal Guide, IETMS, Web Tools)	Security and configuration management.

Learning Resources	<ol style="list-style-type: none"> 1. Foundation Skills in Integrated Product Development (FSIPD), 1st Edition, 2013, Published by NASSCOM. 2. Ulrich, Karl T. and Eppinger, Steven D (2004) Product Design and Development, 5th Edition, McGraw-Hill, 2012. 3. Kevin N. Otto, "product design – techniques in reverse engineering and new product development", PEARSON, New Delhi, 2011
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	Dr.R.Prabhusekar, rprabhusekar@mnnit.ac.in, MNNIT Allahabad	1. Mr. N. arun, SRM IST
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	Dr. Shanmugam. P, Shanmugam.p@sfl.co.in, Sundaram fasteners, Chennai	2. Dr. P. Nandakumar, SRMIST

Course Code	18MEE309T	Course Name	MODELING SYSTEMS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
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CLR-1 :	Acquire knowledge to model systems seen in reality	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Understand the use of mathematics in modeling																		
CLR-3 :	Understand the basic principles of modeling systems																		
CLR-4 :	Understand and develop simple models																		
CLR-5 :	Understand and recognize that modeling as an interdisciplinary requirement																		
CLR-6 :	Understand and correlate real time problems with mathematical forms																		

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Understand and correlate engineering systems seen in real time environment with the modeling systems	1&2	90	85	H	H	-	-	-	-	H	-	-	-	-	-	-	-	-
CLO-2 :	Understand and realize the use of mathematics in modeling engineering systems	1&2	90	85	H	H	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-3 :	Understand and able to convert real time problems into mathematical form	1&2	90	85	H	H	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-4 :	Understand and model various components of engineering systems	1,2,&3	90	85	H	H	H	H	H	-	-	-	-	-	-	-	-	-	-
CLO-5 :	Modeling engineering systems such as mechanical systems and thermal systems	1,2&3	90	85	H	H	H	H	H	-	-	-	-	-	-	-	-	-	-
CLO-6 :	Understand and recognize that modeling is an interdisciplinary requirement	1,2	90	85	H	H	-	-	-	-	-	-	-	-	-	-	-	-	-

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction: Model – Definition, Nature and necessity	Use of Modeling Mathematics: Principles of modeling – common aspects of all mechanical systems	Generate Simple Models: Introductions to system identification	Understanding the Mathematics in Response: Characteristic equation	Project: Identify a system
S-2	SLO-1	History of modeling	Given a simple system – create a model	Model mechanical systems - Rectilinear	Solution of characteristic equation	Objectives of modeling and simulation of a system
S-3	SLO-1	Different type of modeling	Assessment of reality of the model – degree of accuracy	Model mechanical systems - Torsional	Introduction to Eigen values – natural frequencies - eigen vectors – mode shapes	Identify components
S-4	SLO-1	Impact of computers on modeling	Quadratic oscillator system and need for this model	Model a thermal system	Use of Laplace transforms for stability analysis	Model components – test each component
S-5	SLO-1	Different areas of application – Design, Thermodynamics, Mechanics, Controls etc.	Spring mass damper system and need for such a system	Response analysis – the reverse engineered explanation	Different type of representation of systems	Assemble the model
S-6	SLO-1	Modeling in software	Linearity of springs – modeling	Study of response for different inputs – modeling inputs	How to analyze for controllability	Identify suitable inputs – model them
S-7	SLO-1	Introduction to Discrete and continuous systems	Modeling damping – different type	Time driven models	How to analyze for observability, stabilizability	Analyze the response to that input
S-8	SLO-1	Components of systems	Modeling systems – assemble - quadratic	Event driven models	Conditions for the same	Submit a report
S-9	SLO-1	Areas of applications	Relate mathematics to real system – ODEs, Transforms – solutions	Numerical experimentation	Relevance of these tests to modeling	Presentation and viva voce

Learning Resources	1.G. J. Olsder, J. W. van der Woude, J. G. Maks, D. Jeltsema, "Mathematical Systems Theory", VSSD, Leeghwaterstraat, Delft, Netherlands; 4th Edition, 2011 2. Polderman J. W., Willems J. C., "Introduction to mathematical theory of systems and control", Springer, 1997	3 Frank L Severence, "Systems modeling and simulation – An introduction", student edition, 2012.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	Dr.R.Prabhu sekar, rprabhusekar@mnnit.ac.in, MNNIT Allahabad	Dr. G. Rajasekaran, SRMIST
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in		Dr. P. Nandakumar, SRMIST

Course Code	18MEE310T	Course Name	HUMAN BODY MECHANICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																	
CLR-1 :	Upon learning the students shall understand the fundamentals of biomechanics, joints, tissue overall anatomical structure and their importance.	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15			
CLR-2 :	Upon learning the students shall understandthe mechanism of the different parts of the human body.																								
CLR-3 :	Upon learning the students shall understandthe musculoskeletal system with tissue loads and responses and neuromuscular control.																								
CLR-4 :	Upon learning the students shall understand kinematics, is the accurate description of motion and is essential to understanding the biomechanics of human motion. Kinematics can range from anatomical descriptions of joint rotations to precise mathematicalmeasurements of musculoskeletal motions.																								
CLR-5 :	Upon learning the students shall understand, the Newton's Laws of Motion in the human body and how these laws can be applied to human motion in the biomechanical principles of Force–Motion, Force–Time, and Coordination ContinuumPrinciples																								
CLR-6 :	Enableunderstanding of the concepts of human body mechanics that illustrate the application of biomechanics principles. These principles are the application for the biomechanical concepts used to improve movement or reduce injury risk																								
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3			
CLO-1 :	Upon learning the students shall understand the fundamentals of biomechanics, joints, tissue overall anatomical structure and their importance.	1,2,3	90	85				H	H					H		H									
CLO-2 :	Upon learning the students shall understand the mechanism of the different parts of the human body.	1,2	95	90				H	H					H	H	H	H								
CLO-3 :	Upon learning the students shall understand themusculoskeletal system with tissue loads and responses and neuromuscular control.	1,2,3	90	85				H	H					H	H	H	H	H			H				
CLO-4 :	Upon learning the students shall understand kinematics, is the accurate description of motion and is essential to understanding the biomechanics of human motion. Kinematics can range from anatomical descriptions of joint rotations to precise mathematicalmeasurements of musculoskeletal motions.	1,2,3	90	85				H	H	H	H	H	H	H	H		H				H				
CLO-5 :	Upon learning the students shall understand, the Newton's Laws of Motion in the human body and how these laws can be applied to human motion in the biomechanical principles of Force–Motion, Force–Time, and Coordination Continuum Principles	1,2,3	85	80				H	H					H	H	H	H	H			H				

		Introduction to Biomechanics of Human Movement and Anatomy of Human Body.	Equilibrium and Human Movement	Mechanics of the Musculoskeletal System	Kinematics of Human Movement	Angular Kinetics of Human Movement.
Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction to biomechanics, Importance of Biomechanics, Improving Performance Preventing and Treating Injury	Equilibrium and Torque	General introduction of tissue and its classifications.	Kinematic convention, Proximal, Flexion, Anterior	Introduction to angular kinematics in arms for the biceps femoris muscle
S-2	SLO-1	Quantitative versus qualitative problems	Resultant Joint Torques	Response of Tissues to Forces, Stress, Strain, Stiffness and Mechanical Strength, Viscoelasticity	absolute spatial reference system for human gait	Sample problems on applying forces in optimal direction for maximum torque output
S-3	SLO-1	Structure, movements and loads on the shoulder	Levers, Anatomical levers	Biomechanics of the Passive Muscle–Tendon Unit (MTU)	Total description of a body segmentation in space	Moment of inertia of a skeleton about a specific axis
S-4	SLO-1	Structure, movements and loads on the elbow and wrist	Equations of static and dynamic equilibrium	Biomechanics of Bone	Direct measurement techniques	Newton's laws to calculate the net forces and torques acting on body segments.
S-5	SLO-1	Structure, movements and loads on the hip	Center of gravity and locating the center of gravity	Biomechanics of Ligaments	Goniometers Eleto goniometer	static equilibrium and a reaction board to calculate whole body center of gravity
S-6	SLO-1	Structure, movements and loads on the knee	Locating the human body Center of Gravity, Stability and balance.	Three Mechanical Characteristics	Image measurement techniques	whole body center of gravity of a high jumper using the

				of Muscle, Force–Velocity Relationship, Force–Length Relationship, Force–Time Relationship		segmental method and a three-segment model of the body. Most
S-7	SLO-1	Structure, movements and loads on the spine	Properties of Bone, Maxwell & Voight Models of bone	Stretch-Shortening Cycle (SSC)	Cinematography	PRINCIPLE OF BALANCE
S-8	SLO-1	Structure, movements and loads on the foot	Biomechanics of human skeletal muscle.	Force–Time Principle	Optoelectric techniques	two-dimensional area within all supporting Biomechanical system.
S-9	SLO-1	Common injuries in shoulder, elbow wrist, hip knee, spine and foot.	Biomechanics of human Skeletal Articulations	Neuromuscular Control, The Functional Unit of Control: Motor Units, Regulation of Muscle Force, Proprioception of Muscle Action and Movement.	Problems on calculating velocities and accelerations	The position of the line of gravity relative to the limits of the base of support

Learning Resources	1. Susan .J. Hall, "Basic biomechanics", Tata McGraw Hill, Sixth edition, 2011. 2. Y. C. Fung, "Biomechanics", Springer Verlag, 2nd Edition, 1997. 3. D. J. Schneck and J. D. Bronzino, "Biomechanics- Principles and Applications", CRC Press, Second Edition, 2000 4. Kreighbaum, E. and Barthels, K., "Biomechanics: A Qualitative Approach for Studying Human Movement", Pearson, 1996.	5. Boston: Allyn and Bacon Alexander. R. Mc. Neill, "Biomechanics", Chapman and Hall, 1975 6. Fundamentals of Biomechanics by Duane Knudson (Springer) 7. Biomechanics and Motor Control of Human Movement By David A. Winter
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Evaluate Create	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

Industrial Expert	Academic expert	Internal Expert
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	Dr. Amit Roy Roy Chowdhury, IISER Shibpur, amit@aero.iests.ac.in	Dr. Sandipan Roy, SRMIST
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in		Dr. P. Nandakumar, SRMIST

Course Code	18MEE401T	Course Name	DESIGN OF TRANSMISSION SYSTEMS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18MEC308T	Co-requisite Courses	Nil	Progressive Courses	//Course code
Course Offering Department	Department of Mechanical Engineering	Data Book / Codes/Standards	Approved Design Data Book		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Selection of flexible drives	1	2	3	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Design the Parallel gears	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3			
CLR-3 :	Design the Non-Parallel gears																					
CLR-4 :	Design the gear box																					
CLR-5 :	Selection of bearings																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	Select the flat belt, V-belt, chain and wire ropes	1,2,3	90	85	H	H	H	M	M	L	H	L	M	L	M	M	L	H	L			
CLO-2 :	Design the spur gear and helical gear	1,2,3	90	85	H	H	H	M	M	L	H	L	M	L	M	M	L	H	L			
CLO-3 :	Design the bevel gear and worm gear	1,2,3	90	85	H	H	H	M	M	L	H	L	M	L	M	M	L	H	L			
CLO-4 :	Design the multi speed gear box for machine tool applications	1,2,3	90	85	H	H	H	M	M	L	H	L	M	L	M	M	L	H	L			
CLO-5 :	Select the journal bearing, ball bearings, roller bearings and deep groove bearings	1,2,3	90	85	H	H	H	M	M	L	H	L	M	L	M	M	L	H	L			

Duration (hour)		Flexible Drives	Parallel Gears	Non-Parallel Gears	Gear Boxes	Bearings
		9	9	9	9	9
S-1	SLO-1	Belt drives: types, selection of belt drives	Review of gear fundamentals, Forces and stresses in gear tooth	Straight bevel gear: Terminology	Geometric progression, standard step ratio, structural and ray diagrams	Introduction of Hydrodynamic journal bearings
	SLO-2	Belt materials and applications	Equivalent number of teeth, gear tooth failures, Selection of gear materials	Forces and stresses on gear tooth	Number of teeth calculation	Sommerfeld Number, Raimondi and Boyd graphs
S-2	SLO-1	Selection of flat belt drives using fundamental equations	Design procedure on spur gear based on strength consideration	Design procedure on bevel gear based on strength consideration	Design procedure on sliding mesh gear box	Bearing materials, properties required for bearing materials, System of lubrication
	SLO-2	problems on flat belt drives using fundamental equations	Problems on spur gear based on strength consideration	Problems on bevel gear based on strength consideration	problems on sliding mesh gear box	
S-3	SLO-1	Selection procedure for flat belt drives using manufacturer's data	Problems on spur gear based on strength consideration	Problems on bevel gear based on strength consideration	problems on sliding mesh gear box	Selection procedure for journal bearing
	SLO-2	Problems on flat belt drives using manufacturer's data				
S-4	SLO-1	Selection procedure for V-belt drives using fundamental equations	Design procedure on spur gear based on wear consideration	Design procedure on bevel gear based on wear consideration	Design procedure on constant mesh gear box	Problems in journal bearings
	SLO-2	Problems on V-belt drives using fundamental equations	Problems on spur gear based on wear consideration	Problems on bevel gear based on wear consideration	Problems on constant mesh gear box	
S-5	SLO-1	Selection procedure for V-belt drives using manufacturer's data	Problems on spur gear based on wear consideration	Problems on bevel gear based on wear consideration	Design of Multi speed gear box for machine tool applications	Introduction to Roller contact bearings
	SLO-2	Problems on V-belt drives using manufacturer's data				
S-6	SLO-1	Wire ropes: types, construction and Selection of wire ropes	Design procedure on helical gear based on strength consideration	Worm gear: Thermal capacity, efficiency, forces and stresses	Design of Multi speed gear box for machine tool applications	Types of bearing, Load rating, bearing materials and bearing failure

	SLO-2	Stresses in wire ropes	Problems on helical gear based on strength consideration	Design procedure on worm gear based on strength consideration		
S-7	SLO-1	Selection procedure for wire ropes	Problems on helical gear based on strength consideration	problems on worm gear based on strength consideration	Variable speed gear box	Selection of bearing
	SLO-2	Problems on wire ropes				
S-8	SLO-1	Power transmission chains: types and applications	Design procedure on helical gear based on wear consideration	Design procedure on worm gear based on wear consideration	Fluid couplings	Problems in ball bearing
	SLO-2		Problems on helical gear based on wear consideration	Problems on worm gear based on wear consideration		
S-9	SLO-1	Selection procedure on power transmission chains and sprockets	Problems on helical gear based on wear consideration	Problems on worm gear based on wear consideration	Torque convertor for automotive applications	Problems in roller bearing
	SLO-2	Problems on power transmission chains and sprockets				

Learning Resources	<ol style="list-style-type: none"> 1. Robert. C. Juvinall, Kurt. M. Marshek, "Fundamentals of Machine Component Design", John Wiley & sons, 6th Edition, 2017. 2. Joseph Edward Shigley and Charles R. Mischke, "Mechanical Engineering Design", McGraw – Hill International Editions, New York, 10th Edition, 2014. 3. Spotts, M.F., Shoup, T.E., Hornberger, L.E., "Design of Machine Elements", Prentice Hall of India Eighth Edition, 2004. 4. Paul H Black and O. E. Adams, P., "Machine Design", 3rd edition, Mc Graw Hill Book Company, Inc., New York, USA, 2007. 5. Bernard Hamrock, Steven Schmid, Bo Jacobson, "Fundamentals of Machine Elements", 2nd Edition, Tata McGraw-Hill Book Co., 2006. 6. Dr. Sadhu Singh, "Design of Machine Elements (Machine Design)", Khanna Publishers; Fifth edition (1987). 7. Khurmi R.S., Gupta J.M., "A text book of machine design", S. Chand & Company Ltd, 25th revised edition, 2005. 8. P.S.G Tech., "Design Data Book", Kalaikathir Achchagam, 2012
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	Mr. Vignesh Shanmugam.s Hyundai Motors India Limited, Irungattukottai – 602117. E mail – 273357@hml.in	Mr. D. Raja, SRM IST
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	Dr. Davidson Jebaseelan, davidson.jd@vit.ac.in VIT, Chennai	Dr. P. Nandakumar, SRMIST

Course Code	18MEE402T	Course Name	OPTIMIZATION IN ENGINEERING DESIGN	Course Category	E	Professional elective	L	T	P	C
							2	1	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	Approved design data book		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 : Be familiar with principles of optimization and its need		1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 : Be familiar with various conventional optimization techniques		Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 : Be familiar with Solving multivariable problems techniques		Expected Proficiency (%)	Problem Analysis
CLR-4 : Be familiar with Solving problems using unconventional optimization techniques		Expected Attainment (%)	Design & Development
CLR-5 : Be familiar with Application of optimization to design of machine elements.			Analysis, Design, Research
			Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 : understand optimization principles and its need		1& 2 90 85	H
CLO-2 : understand and apply the concept of conventional optimization techniques		1&2 90 85	H H
CLO-3 : understand and apply the concept of constrained in single variable as well as multivariable		1&2 90 85	H H
CLO-4 : understand and apply the concept unconventional optimization techniques		1&2,3 90 85	H H H
CLO-5 : apply the methods of optimization in real life situation		1&2,3 90 85	H H H H

	Introduction to optimization	Unconstrained optimization techniques	Constrained optimization techniques	Modern Methods of Optimization	Applications
Duration(hour)	9	9	9	9	9
S-1	SLO-1 Introduction to optimization: adequate and optimum design	Techniques of unconstrained optimization	Direct search methods: Random jumping method, Random walk method	Genetic Algorithm Introduction	Design optimization of springs
S-2	SLO-1 Principles of optimization, design vector, design constraints	Golden section method.	Tutorials on Random Jumping Method	Basic elements of natural genetics—reproduction, crossover, and mutation	Design vector for springs
S-3	SLO-1 Statement of an optimization problem	Fibonacci method	Tutorials on Random Walk Method	The computational procedure involved in optimizing the fitness function in genetic algorithm	Objective function for springs
S-4	SLO-1 Formulation of objective function	Random search	Direct search methods: conjugate gradient method, quasi-Newton methods	Tutorials on Genetic Algorithm	Design optimization of shafts and torsionally loaded members.
S-5	SLO-1 Design constraints	Random search	Tutorial on conjugate gradient method	Simulated Annealing: Introduction	Design vectors for torsionally loaded members
S-6	SLO-1 Classical optimization techniques: single variable	Pattern search	Indirect methods –Penalty function method	Simulated Annealing - Steps involved	Objective function for torsionally loaded members
S-7	SLO-1 Classical optimization techniques: single variable	Gradient search	Indirect methods –Penalty function method problems	Ant colony optimization: Basic Concept	Design optimization of simple truss members
S-8	SLO-1 Classical optimization techniques: multivariable	Quadratic interpolation method	Interior penalty function method	Ant colony optimization: Ant Searching Behavior	Design vectors for simple truss members
S-9	SLO-1 Classical optimization techniques multivariable	Cubic interpolation method	Exterior penalty function method	Graphical representation of the Ant colony optimization process	Objective function for simple truss members

Learning Resources	1. Rao Singaresu.S, "Engineering Optimization – Theory & Practice", New Age International (P) Limited, New Delhi, 2009. 2. Kalyanamoy Deb, "Optimization for Engineering design algorithms and Examples", Prentice Hall of India Pvt. Ltd., 2006. 3. Johnson Ray C, "Optimum design of mechanical elements", Wiley, John & Sons, Digitized 2007 4. Goldberg .D.E, "Genetic algorithms in search, optimization and machine", Barmen, AddisonWesley, New York, 1989. 5. William Orthwein, "Machine Component Design", Vol. I and II, Jaico Publishing house, New Edition, 2006. 6. Rao.C.S, "Optimization Techniques", DhanpatRai& Sons, New Delhi 7. Fox.R.L, "Optimization methods for Engineering Design", Addison Wesley Pub, Digitized 2007. 8. Garret N. Vanderplaats, "Numerical optimization techniques for engineering", McGraw-Hill Ryerson, Limited, 1984.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	DR. SUBHAS GANGULY, sganguly.met@nitrr.ac.in NIT Raipur	Vamsi krishna dommeti SRMIST
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cwrde.drdo.in	HARESH DURAI KARUPPIAH, Haresh.durai@mtbci.com, RENAULT NISSAN	Dr. P. Nandakumar, SRMIST

Course Code	18MEE403T	Course Name	TOOL ENGINEERING DESIGN	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Be familiar with tool materials and their properties	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Be familiar with the design of single point cutting tools and twist drills	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Be familiar with the design of various types of dies	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Be familiar with the blank development for different components	Expected Attainment (%)	Design & Development
CLR-5 :	Be familiar with the design of jigs and fixtures for simple components		Analysis, Design, Research
			Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Identify suitable tool materials for the specific manufacturing applications	1&2 85 80	H L M M - - - - M - - - H L H
CLO-2 :	Design single point cutting tools and twist drill for different machining requirements	2&3 85 80	H M M M - - - - M - - - H L H
CLO-3 :	Design various types of dies for manufacturing components	2&3 85 80	H H H M - - - - M - - - H L H
CLO-4 :	Develop the blank for cylindrical and non-cylindrical shells	2&3 85 80	H H H L - - - - M - - - H L H
CLO-5 :	Design and develop the jigs and fixtures for simple mechanical components	2&3 85 80	H H H H - - - - M - - - H L H

Duration (hour)	9	9	9	9	9
S-1 SLO-1	Different types of tool materials: cemented carbides, coated carbides, cermets,	Press working terminology	Principles of jigs and fixtures	Design principles of fixtures	Case study in jigs
S-2 SLO-1	ceramics and polycrystalline and new tool materials	Different types of Presses and press accessories	Locating principles and different locating elements	Design of fixtures for milling operation	Case study in jigs
S-3 SLO-1	Composition and properties of tool materials	Computation of capacities and tonnage requirements of presses	Clamping principles, clamping devices and types in jigs	Design of fixtures for boring operation	Case study in jigs
S-4 SLO-1	Cutting tool selection and treatments	Various types of Strip layout	Analysis of clamping force	Design of fixtures for broaching & grinding operation	Case study in fixture
S-5 SLO-1	Design of single point turning tools and multipoint tools	Different types of dies, Progressive dies, Combination dies and compound dies	Function of drill bush, types drill bushes	Design of fixture for assembly	Case study in fixture
S-6 SLO-1	Problems on the design of single point cutting tool alone	Design and development of various types of cutting, forming, bending and drawing dies	Different types of jigs, Plate jig, latch jig, channel jig,	Design of fixture for inspection	Case study in fixture
S-7 SLO-1	Selection of tool holders and inserts for turning	Design and development of various types of cutting, forming, bending and drawing dies	Different types of jigs Post jig, angle plate jig, turn over jig, and pot jigs	Design of fixture for welding	Case study in press tools
S-8 SLO-1	Function of Chip breaker, types of chip breaker	Blank development for cylindrical and non-cylindrical shells, blank size calculation	Design and development of jigs for given components	Design and development of fixtures for given components	Case study in press tools
S-9 SLO-1	Design of twist drill and reamers	Forging dies basics and materials for forging dies	Design and development of jigs for given components	Design and development of fixtures for given components	Case study in press tools

Learning Resources	<ol style="list-style-type: none"> 1. Sadasivan.T.A, and Sarathy.D, "Cutting tools for Productive machining", 1st edition, Widia (India) Ltd, Bangalore, 1999. 2. Donaldson.C, Lecain.G.H and Goold.V.C, "Tool Design", Tata McGraw Hill publishing company limited, New Delhi, 2002 3. Edward G. Hoffman, "Jigs and Fixture design", 2nd edition, Galgotia publication Pvt. Ltd., New Delhi, 1987 4. Hiram E. Grant, "Jigs and Fixtures - Nonstandard clamping device", Tata McGraw Hill, New Delhi, 1971. 5. Prakash H. Joshi, "Press tool design and construction", 1st edition, Wheeler Publishing, New Delhi, 2000. 6. Kempster.M.H.A, "An Introduction to Jig and tool design", 3rd edition, ELBS, 1987 7. Prakash H. Joshi, "Cutting tools", 1st edition, Wheeler Publishing, New Delhi, 1997. 8. Prakash H. Joshi, "Tooling Data", 1st edition, Wheeler Publishing, New Delhi, 2000.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. S.Bhargav, GM,Rane Brake, Trichy	1. Dr. V.Srinivasan, Annamalai University, srinivaghavan@yahoo.com	1. Mr.V.G.Umasekar, SRMIST
2. Dr. Muthumanikkam, Jt. Director, CVRDE, DRDO,Avadi, Chennai.	2.Dr.Assaitambi, Govn. Col.of. Eng.sengipatti,Thanjavur, basaitambi@gcetj.edu.in	Dr. U. M. Iqbal, SRMIST

Course Code	18MEE404T	Course Name	COMPUTER GRAPHICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Be familiar with the basics of computer graphics and transformations	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Be familiar with the special curves and their parametric representation	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Be familiar with the surface modeling techniques and their mathematical representation	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Be familiar with the three dimensional graphics techniques	Expected Attainment (%)	Design & Development
CLR-5 :	Be familiar with the graphics and Communication standards		Analysis, Design, Research
CLR-6 :	Be familiar with the computer graphics and various modeling techniques		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Understand about computer graphics and basic transformations	1 90 85	H L M L L L L L L L L L L L L
CLO-2 :	Acquire knowledge on special curves and their parametric representation	1&2 90 85	H L H M L L L L L L L L L L L
CLO-3 :	Understand the various surface modeling techniques and their mathematical representation	1&2 90 85	H M H M M L L L L L L L L L
CLO-4 :	Understand the three dimensional modeling techniques and apply these techniques to develop new products	1&2 90 85	H M H M M L L L L L L L L L
CLO-5 :	Acquire knowledge on data exchange and Communication standards	1&3 90 85	H M L M L L L L L L L L L L
CLO-6 :	Understand about computer graphics and various modeling techniques		

	Introduction to Computer Graphics	Special Curves	Surface modeling	Three Dimensional computer graphics	Graphics and Communication standards
Duration (hour)	9	9	9	9	9
S-1 SLO-1	Origin of computer Graphics	Introduction of Curve representation	Introduction of Surface modeling techniques	Boundary representation (B-rep)	Graphics and data exchange standards
S-2 SLO-1	Interactive graphics display	Introduction to Bezier curve	Coons patch	Basic elements and building operations	Graphical Kernel System
S-3 SLO-1	Video Display devices	Parametric representation of Bezier curve	Mathematical representation and boundaries of Coons patch	Constructive solid geometry (CSG)	Bit maps
S-4 SLO-1	Types of Display devices	Introduction to Cubic spline curve	Bi-Cubic patch	Basic elements and Building operations	open GL (graphics library)
S-5 SLO-1	Algorithm for line, circle	Parametric representation of Cubic spline curve	Mathematical representation of Bi-Cubic patch	Viewing transformations	Data exchange standards (IGES)
S-6 SLO-1	2D transformation (scaling, rotation, translation)	Introduction to B-Spline curve	Bezier surface	Clipping operations	STEP and CALLS
S-7 SLO-1	3D transformation scaling & rotation	Parametric representation of B-Spline curve	Mathematical representation of Bezier surface	Hidden line removal for curved surfaces	DXF Standard and STL
S-8 SLO-1	3D transformation Translation	Introduction to Rotational curves	B-Spline surface	Algorithms for shading	Communication standards, LAN
S-9 SLO-1	Concatenation transformations	Parametric representation of Rotational curves	Mathematical representation of B spline surface	Algorithms for rendering	Communication standards, WAN

Learning Resources	1. Donald Hearn and Pauline Baker M. "Computer Graphics", Prentice Hall, Inc., 2009 2. Ibrahim Zeid "CAD/Cam Theory and Practice", McGraw Hill, International Edition, 2010. 3. Harington, Stevan, "Computer Graphics: A Programming Approach", McGraw Hill, 1983 4. Plastock, Roy A., &Kally, "Theory and Problems of Computer Graphics", McGraw Hill, 1986
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	Dr. Davidson Jebaseelan, davidson.jd@vit.ac.in, VIT Chennai	Mr.S.ArunPrasath, SRMIST
2. A. Don Bosco, Valeo, Chennai	S.DineshBabu, Renault Nissan Technology, Chennai	Mr.R.Yogeswaran, SRMIST

Course Code	18MEE405T	Course Name	FATIGUE, FRACTURE MECHANICS AND CREEP	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Be familiar with fatigue crack propagation and micromechanisms of fatigue	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Be familiar with the concepts of environmentally assisted cracking in metals		
CLR-3 :	Know about fracture mechanics and stress intensity factors		
CLR-4 :	Know about deformation at crack tip, crack tip opening displacement, crack initiation and growth		
CLR-5 :	Be familiar with characteristics, mechanisms, effects and considerations of creep		

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Recognize and analyze fatigue crack propagation, crack closure, fatigue threshold, variable amplitude loading and retardation and micromechanisms of fatigue	1&2	90	85	H	H	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-2 :	Appreciate the knowledge on environmentally assisted cracking, stress corrosion, hydrogen embrittlement and corrosion fatigue in metals	1&2	90	85	H	-	-	-	-	H	-	-	-	-	-	-	-	-	-
CLO-3 :	Understand fracture mechanics and acquire knowledge on energy release rate, stress intensity factors of simple and complex cases	1&2	90	85	H	H	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-4 :	Acquire knowledge on elastic deformation at the crack tip, J-integral, crack tip opening displacement and mixed mode crack initiation and growth	1&2	90	85	H	H	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-5 :	Understand characteristics of creep and acquire knowledge on mechanisms, tests, interactions, temperature effects, materials and design considerations of creep	1&2	90	85	H	H	-	-	-	-	-	-	-	-	-	-	-	-	-

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Fatigue crack propagation, similitude in Fatigue	Introduction to environmentally assisted cracking in metals, Corrosion principles: electrochemical reactions	Introduction to fracture mechanics: Kinds of failure, brittle and ductile fracture, modes of fracture failure	Anelastic deformation at crack tip: approximate shape and size of plastic zone	Introduction to creep, characteristics of creep
S-2	SLO-1	Empirical fatigue crack growth equations	Corrosion current and polarization, electrode potential and passivity, cathodic protection	Energy release rate: Griffith's dilemma, surface energy, Griffith's analysis, mathematical formulation, compliance approach, strain energy approach	Anelastic deformation at crack tip: effective crack length, effect of plate thickness	Mechanisms of creep: dislocation creep, diffusion creep, grain boundary sliding, Creep deformation mechanism maps
S-3	SLO-1	Crack closure, closer look at crack-welding mechanisms, loading variables on closure	Environmentally assisted cracking (EAC) overview: Cracking mechanisms	Energy release rate: anelastic deformation at crack tip, thin plate vs thick plate	Definition of J-Integral, path independence, stress-strain relation	Creep under multiaxial loading, combined stresses, stress relaxation
S-4	SLO-1	The fatigue threshold: a two-criterion model, threshold behavior in inert environments	Crack growth rate vs applied stress intensity, threshold for EAC, small crack effects	Energy release rate: crack resistance, stable and unstable crack growth, critical energy release rate	Further discussion on J-integral from a designer's point of view, critical J-integral, safety or failure	Creep-fatigue interaction, creep fractures
S-5	SLO-1	Variable amplitude loading and retardation: reverse plasticity at crack tip, the effect of overloads and underloads	Static, cyclic and fluctuating loads, cracking morphology, life prediction	Introduction to Stress intensity factors, Investigations closer to crack tip, LEFM	J-Integral: engineers approach, simplified relation, applications	Creep test, stress rupture test, representation of creep rupture data
S-6	SLO-1	Models for retardation and variable amplitude fatigue	Stress corrosion cracking, film rupture model	Stress intensity factor: Stress and displacement fields in isotropic elastic materials, field equations	Introduction to CTOD, relationship between CTOD, K _I and G _I , Equivalence between CTOD and J	Creep and Stress Rupture: Deformation and fracture at Elevated Temperature
S-7	SLO-1	Growth of short cracks: microstructural and mechanical	Crack growth rate in stage II, corrosion product wedging	Stress intensity factor: Westergaard's approach, Mode I (opening mode), Mode II (sliding mode), Mode III (tearing mode)	Introduction to mixed mode crack initiation and growth	Theories of low and high temperature creep

S-8	SLO-1	Micromechanisms of fatigue: Fatigue in region II, micromechanisms near the threshold	Hydrogen embrittlement, cracking mechanisms, Variables that effect cracking behavior: load, hydrogen, temperature	SIF of more complex cases: Other applications of Westergaard approach, applications of principle of superposition	Mixed mode crack propagation: maximum tangential stress criteria, Strain energy density criterion	Prediction of longtime properties, effect of metallurgical variables, Creep resistant materials, hightemperature alloys
S-9	SLO-1	Damage tolerance methodology	Corrosion fatigue, time dependent and cycle dependent behavior, Mechanisms of corrosion fatigue, effect of corrosion product wedging on fatigue	Edge cracks, embedded cracks, critical stress intensity factor	Mixed mode examples, crack growth	Design considerations to avoid creep

Learning Resources	<i>T. L. Anderson, "Fracture Mechanics Fundamentals and Applications", CRC Press Taylor & Francis; 4th edition, 2017</i> <i>Prashant Kumar, "Elements of Fracture Mechanics" Tata McGraw-Hill; 2009</i> <i>C. T. Sun, Z. -H. Zin, "Fracture Mechanics ", Elsevier; 2012</i> <i>G. E. Dieter, "Mechanical Metallurgy ", McGraw-Hill; 2017</i>					
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30%	-	30%	-	40%	-	40%	-	30%	-
	Understand										
Level 2	Apply	50%	-	50%	-	40%	-	40%	-	50%	-
	Analyze										
Level 3	Evaluate	20%	-	20%	-	20%	-	20%	-	20%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	Dr. Sudheesh Kumar, sudheeshkumar3@gmail.com, GCE, Kannur	Dr T V V L N Rao, SRMIST
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	Dr.R.Prabhusekar, rprabhusekar@mnnit.ac.in, MNNIT Allahabad	Dr P Nandakumar, SRMIST

Course Code	18MEE406T	Course Name	LINEAR ELASTICITY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Advanced calculus and complex Analysis, mechanics of solids	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Department of Mechanical Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	To studyConcept of Stress- Strains and Deformation	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	To ApplyBoundary Conditions for different kind of problems		
CLR-3 :	To solve the problem using different solution method		
CLR-4 :	To solve the plane elasticity problems using different solution method		
CLR-5 :	To solvetorsion and elastic cylinders problems		
CLR-6 :	To studyConcept of Stress- Strains and Deformation		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Engineering Knowledge
CLO-1 :	understand the basics of Tensors, Index Notation, Coordinate Transformations, Deformation and Strain, Strain Transformation, Principal Strains, StrainCompatibility,	1,2	H H
CLO-2 :	apply boundary conditions and can get the general result	1,2	H H H
CLO-3 :	solve the problem using different solution method	1,2,3	H H H
CLO-4 :	solve the plane elasticity problems using different solution method	1,2,3	H H H
CLO-5 :	Solve torsion and elastic cylinders problems	1,2,3	H H H
CLO-6 :	Able to understand the basics of Tensors, Index Notation, Coordinate Transformations, Deformation and Strain, Strain Transformation, Principal Strains, StrainCompatibility,	1,2	H H
		Expected Proficiency (%)	Design & Development
		Expected Attainment (%)	Analysis, Design, Research
			Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3

Duration (hour)	Foundations	General Results	System Response	Plane Elasticity Problems	Torsion And Flexure Of Elastic Cylinders
	9	9	9	9	9
S-1	SLO-1	Mathematical Preliminaries-Scalar, Vector, Matrix, and Tensor Definitions	Review of Field Equations	Anti-plane Strain	Plane Stress and Plane Strain
S-2	SLO-1	Index notation	Field equations and boundary conditions, Navier equations	Field Equations and Boundary Conditions	Introduction to Airy Stress Function
S-3	SLO-1	Concept of Stress- Strains and Deformation	Stress Formulation-Beltrami-Michell compatibility equations	Complex Variable Solutions to Anti-plane Strain Problems	Stress function, stress function for plane stress and plane strain cases
S-4	SLO-1	Coordinate Transformations -Strain Transformation	Displacement Formulation Principle of Superposition	Solution using Taylor Series	Introduction to Cartesian Coordinate Using Polynomials
S-5	SLO-1	Principal Strains, Strain Compatibility	2D approximations (plane stress and plane strain) and solution strategies	Solution using Laurent Series	Cartesian Coordinate Solutions Using Polynomials
S-6	SLO-1	TractionVector	Uniqueness Theorems-Reciprocal Theorem	Solution using Cauchy Integral Formula	Introduction to Cartesian Coordinate Using Fourier Methods
S-7	SLO-1	Stress Transformation	Principle of Virtual Work	Solution using Cauchy Integral Formula	Cartesian Coordinate Solutions Using Fourier Methods
S-8	SLO-1	Equilibrium Equations&Generalized Hooke's law.	Principle of Minimum Potential and Complementary Energy	Solution using Conformal Mapping	Introduction to Solutions in Polar Coordinates
S-9	SLO-1	Review of Continuum Mechanics Concepts	Saint-Venant's Principle	Solution using Conformal Mapping	Axisymmetric problems, thick-walled cylinders, rotating disks of uniform thickness, stress concentration, effect of circular holes on stress distribution in plates.

Learning Resources	<ol style="list-style-type: none"> 1. Martin H. Sadd, <i>Elasticity: Theory, "Applications and Numeric's"</i>, Elsevier India, 2005 2. Timoshenko.S.P, Goodier.J.N, "Theory of Elasticity", Tata McGraw-Hill Education, 2010. 3. England.A.H, "Complex Variable Methods in Elasticity", Dover Publications, 2003. 4. Malvern.L.E, "Introduction to the Mechanics of a Continuous Medium", Prentice Hall, 1977. 5. Love.A.E.H, "The Mathematical Theory of Elasticity", Dover, 2011. 6. Landau.L.D and Lifshitz.E.M, "Theory of Elasticity, Butterworth-Heinemann", 1986. 7. Atkin.R.J and Fox.N, "An Introduction to the Theory of Elasticity", Dover,2005. 8. Barber.J.R, "Elasticity", Springer, 2009.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30%	-	30%	-	40%	-	40%	-	30%	-
	Understand										
Level 2	Apply	50%	-	50%	-	40%	-	40%	-	50%	-
	Analyze										
Level 3	Evaluate	20%	-	20%	-	20%	-	20%	-	20%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	Dr. R. Damodaram, SSN College of Engineering, Chennai, damodaramr@ssn.edu.in	Mr. K. Jegadheesan, SRMIST
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	Dr.R.Prabhusekar, rprabhusekar@mnnit.ac.in, MNNIT Allahabad	Dr. M. Iqbal, SRMIST

Course Code	18MEE407T	Course Name	DESIGN OF PRESSURE VESSEL AND PIPING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18MEC206T	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	ASME Pressure Vessel and Boiler Code; Section VIII Div. 1&2; 2003.American Standard Code for Pressure Piping; B 31.1.		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1:	Familiarize with basics of Pressure vessel design	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Familiarize with different types of stresses and their effects in Pressure vessel.				Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3			
CLR-3:	Equip with Pressure vessel design.																					
CLR-4:	Expose to failure mechanisms in Pressure vessel.																					
CLR-5:	Expose to the concept of piping layout and the stresses acting on it.																					
CLR-6:	Analyse and design of pressure vessel and piping.																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1:	understand the basics of pressure vessel design	1&2	90	85	H	H	H	M													L	
CLO-2:	determine various stresses, and their effects in pressure vessel.	12&3	90	85	H	H	H														L	
CLO-3:	design pressure vessel.	12&3	90	85	H	H	H														L	
CLO-4:	know the various types of failures in pressure vessel.	12&3	90	85	H	H	H														L	
CLO-5:	know the concepts of piping layout and the stresses acting on it	12&3	90	85	H	H	H														L	
CLO-6:	Know the design concepts of pressure vessel and piping	1 2&3	90	85	H	H	H														L	

Duration (hour)		Overview of Pressure Vessel and stresses	Stresses in Pressure Vessels	Design of Pressure Vessels	Failure Analysis of vessels	Fundamentals of piping design
		09	09	09	09	09
S-1	SLO-1	Introduction, construction and design procedure.	Stresses in cylinder, Dilation of pressure vessels, Intersecting spheres.	Stress concentration at a variable thickness transition section in a cylindrical vessel, circular hole, Elliptical Openings	Buckling phenomenon, vessels under external pressure.	Introduction to piping, definition, codes, standards and specifications.,
S-2	SLO-1	Design approach, design by rule, design by analysis.	Membrane stresses in vessel under internal pressure, cylindrical vessel, spherical, conical vessel.	Stress concentration factor for superposition, Dynamic and thermal transient condition.	Elastic buckling of circular ring, deflection curve, buckling.	Piping components, pipe, pipe fittings, flanges, valves, bolt and gaskets.
S-3	SLO-1	Introduction, Stress intensity, Stresses in a circular ring.	Thermal stresses in long hollow cylinder, logarithmic, thermal gradient.	Design of tall cylindrical self-supporting process columns for short vertical vessels.	Buckling of long cylinder or tubes, inelastic collapse, initial non-circularity.	Flow diagram, piping layout
S-4	SLO-1	Stress significance, stress pattern.	Linear thermal gradient, Steady state Thermal stresses.	Design of supports for short vertical vessel.	Collapse of thick walled cylinder, fully plastic wall,	underground, above ground pipelines
S-5	SLO-1	Residual stress, shape of a member	Thermal stresses due to thermal gradients.	Theory of reinforced openings.	Collapse of the wall of a cylinder.	Piping stress analysis, Forces and moments
S-6	SLO-1	Methods for determining stresses, strain gauge, Photo elastic, Moiré.	Ultra-high-pressure vessel -design principle, wedge, segment principle.	Nozzle reinforced placement shape, single nozzles, Multiple nozzles, Nonradical nozzles.	Effect of supports on elastic buckling, buckling, collapse coefficient.	Piping specifications, static and dynamic loads
S-7	SLO-1	Thermal stresses, thermal strains and their significance.	Cascade principle, yoke Beam and ties, Anvil principle, Bridge man massive conical anvils.	Pressure vessel design, welded joints, strength of weldments.	Buckling under combined external pressure and axial loading	nomenclature of pipe supports, guided cantilever method

S-8	SLO-1	Terminology of vessel, vessel Ligament.	Discontinuity stresses in pressure vessels, Cylindrical vessels with various heads, Infinite long beam, semidefinite beam.	Bolted joints and gaskets, thread and nut design, bolt head, shank design.	interaction method, interaction equations in design.	Design of piping system, pressure components design
S-9	SLO-1	Ligament efficiency, Longitudinal, circumferential ligaments in a cylindrical and spherical shape.	Stresses in a bimetallic joint, deformation and stresses in flanges.	Introduction to ASME pressure vessel codes.	Safety factors in design, Imperfection sensitivity	minimum wall thickness of pipe, pipe span calculations, Ansi piping codes.

Learning Resources	<ol style="list-style-type: none"> 1. John F. Harvey, "Theory and Design of Pressure vessels", CBS publishers and Distributors, 1987. 2. Henry H Bedner, " Pressure Vessels, Design Hand Book ", CBS publishers and Distributors ,1987. 3. Somnath Chattopadhyay," Pressure vessels: Design and practice ", CRC Press ,2004. 4. Smith P., "Fundamentals of piping design", Elsevier Gulf Publishing Company 2007. 5. William. J. Bees"Approximate Methods in the design and analysis of pressure vessels and piping ", Pre ASME-pressure vessels and piping conference ,1997. 6. ASME Pressure Vessel and Boiler code, section viii Div. 1&2,2003 American standard code for pressure piping, B31.1 7. Brownell. L E & Young E.D," Process equipment design ", Wiley Eastern Ltd, India. 					
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	Dr V.MARIAPPAN, vmari@nitt.edu, NIT Trichy	Dr. P.Nandakumar, SRMIST
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in		Mr.R.Harris Samuel, SRMIST

Course Code	18MEE408T	Course Name	KINEMATICS AND DYNAMICS OF ROBOTS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Acquire the fundamental concepts of Robot Transformation	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Impart the Knowledge about the concepts of Direct kinematics of Robot	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Impart the Knowledge about the concepts of Inverse kinematics of Robot	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Acquire fundamental knowledge about the planning trajectories on workspace of robot	Expected Attainment (%)	Design & Development
CLR-5 :	Enable students with the basic knowledge of Robot Dynamics		Analysis, Design, Research
CLR-6 :	Understand the kinematics and dynamics models of robots		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Understanding rigid body transformations, homogeneous transformation matrices of Robot.	1 & 2 85 75	H H M M M L L L M M M M M M M
CLO-2 :	Derive the direct kinematics equation for robot manipulators.	2 80 70	H H M M M L L L M M M M M M M
CLO-3 :	Derive the inverse kinematics equation for robot manipulators.	1 & 2 80 70	H H H M M L L L M M M M M M M
CLO-4 :	Generate workspace and trajectory planning in Cartesian and joint spaces.	1 & 2 75 70	H H H M M L L L M M M M M M M
CLO-5 :	Understand the equations of motion (dynamics model) of manipulators using Lagrange-Euler and Newton-Euler methods.	1 & 2 75 70	H H H M M L L L M M M M M M M
CLO-6 :	Analyze the kinematic and dynamic model of robot	2 75 70	H H M M M L L L M M M M M M M

Duration (hour)	9	9	9	9	9
S-1	SLO-1 SLO-2	Introduction about machines and mechanisms – Robot anatomy	Link coordinates for D-H representation	Inverse Kinematics of transformation	Introduction & analysis of work space
S-2	SLO-1 SLO-2	Arm and wrist configuration of Robot	Arm matrix and Arm equation – DH representation of Kinematics model	General properties of solution	Workspace analysis for 4 axis SCARA robot
S-3	SLO-1 SLO-2	Position and orientation of objects, descriptions: Positions, Orientations and Frames	Direct Kinematics of 2 DOF Planar Manipulator arm	Inverse Kinematics for 2 DOF planar robot	Work space fixtures
S-4	SLO-1 SLO-2	Coordinate transformation / Mapping in fixed angle rotation	Direct Kinematics of 3 axis articulated robot – Link	Inverse kinematics – 3 DOF articulated robot – Guide lines, solution techniques	Trajectory planning - Terminology
S-5	SLO-1 SLO-2	Mappings: Changing descriptions from Frame to Frame		Inverse kinematics – 3 DOF articulated robot – Derivation of equations	Trajectory planning – pick and place motion
S-6	SLO-1 SLO-2	Operators: Translations, Rotations and Transformations, Transformation Arithmetic	Direct Kinematics of 3 DOF wrist	Inverse kinematics of RPY wrist	Continuous path motion – Joint space technique and Cartesian space technique
S-7	SLO-1 SLO-2	Transformation of Vectors for Rotation, translation and composite		Inverse kinematics of – 4 axis SCARA robot – General solution	Trajectory planning – Interpolated motion
					Kinetic and Potential Energy Formulation for Two axis planar robot
					L-E Dynamics model for Two axis planar robot

S-8	SLO-1	Inverting Transformation	Direct Kinematics Analysis of 4 axis SCARA Robot	Tool Configuration	Trajectory planning for 3 DOF Manipulator	Newton – Euler formulation
	SLO-2					
S-9	SLO-1	Rotation Matrix – fixed and Euler angle representation		Tool configuration of a 4 axis SCARA robot	Trajectory planning for 4 DOF SCARA Manipulator	N-E Dynamics model for Two axis planar robot
	SLO-2					

Learning Resources	<ol style="list-style-type: none"> 1. Robert J. Schilling, <i>Fundamentals of Robotics Analysis and Control</i>, Prentice Hall of India Pvt. Ltd., 2003 2. Richard D. Klafter, Thomas. A. Chmielewski, Michael Negin, <i>Robotics Engineering an Integrated Approach</i>, Prentice Hall of India Pvt. Ltd., 1993 3. P.A. Janaki Raman, <i>Robotics and Image Processing An Introduction</i>, Tata Mc Graw Hill Publishing company Ltd., 1995 4. John J. Craig, <i>Introduction to Robotics Mechanics and Control</i>, Fourth Edition, Pearson Education International, 2018. 5. Mittal RK, Nagrath IJ, <i>Robotics and Controls</i>, Tata McGraw Hill Publications, 2003
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	15%	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	20%	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	15%	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	Dr. Yogesh Singh, Yogesh@mech.nits.ac.in, NIT Silchar	Mr. KR. Arun prasad, SRMIST
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	Dr.R.Prabhu sekar, rprabhusekar@mnnit.ac.in, MNNIT Allahabad	Dr. P. Nandakumar, SRMIST

Course Code	18MEE409T	Course Name	COMPUTER APPLICATIONS IN DESIGN	Course Category	E	Professional Elective	L 3	T 0	P 0	C 3
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Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	understand the overall design process and the types of three-dimensional modeling schemes.	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	write programs in MATLAB for Mechanical Engineering Design problems	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	understand in applying CAD model for design	Expected Proficiency (%)	Problem Analysis
CLR-4 :	know how the model data is stored, retrieved and to organize for CIM applications	Expected Attainment (%)	Design & Development
CLR-5 :	know uses of parametric modeling. Uses of Rapid prototyping and Artificial Intelligence		Analysis, Design, Research
CLR-6 :	understand the overall design process and the types of three-dimensional modeling schemes.		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	understand the overall design process and can able to apply on any projects.	1&2 90 85	H - - - - - - - - - - - - - - - -
CLO-2 :	write interactive programs in MATLAB for design problems.	1 90 85	H H - - - - - - - - - - - - - - - -
CLO-3 :	understand in applying CAD model in design	1 90 85	H - M - - - - - - - - - - - - - - - -
CLO-4 :	organize data for CIM applications and various aspects of data storage and manipulation	1&2 90 85	H - M - - - - - - - - - - - - - - - -
CLO-5 :	understand the uses of parametric modelling and artificial intelligence.	1&2 90 85	H - M - - - - - - - - - - - - - - - -

		Introduction to CAD	Writing design programs in MATLAB for Machine Elements	Applying the CAD model in design	Entity Manipulation and Data Storage:	Expanding the capability of CAD
Duration (hour)		9	9	9	9	9
S-1	SLO-1	The design process	Introduction to Machine Drawing	Applications to draughting	Manipulation of the model	Parametric modeling
S-2	SLO-1	Different types of design process	Introduction to Machine Drawing	The use of 3D modeling for 2D representation	Model storage	Variation modeling
S-3	SLO-1	Role of CAD in Design	Introduction to MATLAB software	Approaches to 3D modelling	Data structures	Feature based modeling
S-4	SLO-1	Types and applications of design models	Introduction for Writing interactive programs to solve design problems in MATLAB	Direct assessment for the geometric model	Database consideration	Feature recognition
S-5	SLO-1	Computer representation of drawings	Design problems using MATLAB for Shafts	Generation of new models from the geometric model	Object oriented representations	Design by features
S-6	SLO-1	Three-dimensional modeling schemes	Design problems using MATLAB for Gears	The scope of customization and design automation	CIM	
S-7	SLO-1	Wire frame model	Design problems using MATLAB for Pulleys	Typical facilities for system customization	Organizing data for CIM application	Rapid prototyping
S-8	SLO-1	Surface representation model	Design problems using MATLAB for flywheel	The graphics Kernel System	ERP (Enterprise Resource planning)	
S_9	SLO-1	Solid modeling	Design problems using MATLAB for connecting rods	Standard for exchanging images	Design information system	Artificial intelligence in design

Learning Resources	<ol style="list-style-type: none"> 1. Charles. S. Knox, "Organising data for CIM Applications", Marcel Dekker Inc. New York 1987. 2. Ibrahim Zeid, "CAD/ CAM - Theory and Practice" - McGraw Hill, International Edition, 1998. 3. Chris McMahon and Jimmi Browne, "CAD CAM Principles, practice and Manufacturing Management", Pearson Education Asia, 2002. 4. Kr. Gopalakrishna, "Machine Drawing", Subhas Stores, 2007 5. Chandupatla and Belagundu, "Introduction to Finite Element Methods in Engineering", Prentice Hall of India Private Limited, New Delhi, 1997. 6. http://www.machinedesign.com 7. MATLAB: Easy Way of Learning, S. Swapna Kumar and S. V. B. Lenina, 2016
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	-	15%	-	15%	-	15%	-	15%	-
	Understand										
Level 2	Apply	20%	-	20%	-	20%	-	20%	-	20%	-
	Analyze										
Level 3	Evaluate	10%	-	15%	-	15%	-	15%	-	15%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	Dr. Davidson Jebaseelan, davidson.jd@vit.ac.in VIT Chennai.	Mr. S. Balamurugan, SRM IST
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	Mr. Vignesh Shanmugam.S, 273357@hmail.net Hyundai Motors Limited, Chennai	Dr. P. Nandakumar, SRMIST

Course Code	18MEE321T	Course Name	ELEMENTS OF MECHATRONICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Acquire the fundamental knowledge of mechatronics systems	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Understand the sensors and transducers.	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Understand the actuation systems, signal processing and controllers.	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Acquire knowledge about the PLC.	Expected Attainment (%)	Design & Development
CLR-5 :	Know mechatronics system design and its applications.		Analysis, Design, Research
CLR-6 :	Knowledge about the concept and components of mechatronics systems.		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
			M - - M - - - - - - - - - - - L L L
			H M M L L - - - - - - - H H L
			H M M M - - - - - - - H M L
			H H M M - - - - - - - H H L
			H M H H - - - - - - - H M L
			H M M M L - - - - - - - H M L

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)
CLO-1 :	Differentiate the basic key elements of mechatronics systems	1	90	85
CLO-2 :	Have cognizance on performance of sensors and transducers.	1	90	85
CLO-3 :	Differentiate and utilize actuation systems, signal processing and controllers.	1	90	85
CLO-4 :	program the PLC.	2	90	85
CLO-5 :	Design of mechatronics system and its applications.	3	90	85
CLO-6 :	Differentiate, analysis and design mechatronics systems.	3	90	85

	Introduction to Mechatronics	Sensors and Transducers	Electrical Drives and Controllers	Programmable Logic Controllers	Mechatronics System Design and Application
Duration (hour)	9	10	10	8	8
S-1	SLO-1	Introduction to Mechatronics systems	Introduction to sensors and transducers, classification and Static and dynamic characteristics.	Introduction, Electromagnetic Principles, Solenoids and Relays	Basic structure, Programming units and Memory of Programmable logic controller
S-2	SLO-1	Mechatronics system components and Measurement Systems, Control Systems.	Principle and working of Resistive, capacitive, inductive transducer.	Electrical drives of stepper motors, servo motors.	Input and Output Modules, Mnemonics for programming
S-3	SLO-1	Open and Closed Loops Systems temperature control	Resonant transducer and Optical measurement systems for absolute and incremental encoders	Operational amplifier	Latching and Internal relays
S-4	SLO-1	Water level controller and Shaft speed control	Photo electric sensor and vision system	A/D converters	Timers, Counters and Shift Registers
S-5	SLO-1	Fibre optic transducers	D/A converters	Master relay and Jump Controls	Programming the PLC using Ladder diagram for Simple applications.
S-6	SLO-1	Sequential Controllers : Washing machine control	Solid state sensors and transducers for magnetic measurements	Proportional, Integral, Derivative and PID controller	Case studies for Coin counters, Robot walking and Boiler control using PID.
S-7	SLO-1	Sequential Controllers : Digital camera	Temperature measurements	Chemical measurements, piezoelectric sensor and accelerometers	Introduction to Micro controller : M68HC11 and ATMEGA328
S-8	SLO-1	MEMS and the automobile airbag	Ultrasonic sensors and transducers for flow and distance		
S-9	SLO-1				
S-10	SLO-1				

Learning Resources	TEXT BOOKS Bolton.W, "Mechatronics", Pearson, 6th Edition, 2015. Bradley.D.A, Dawson.D.BurdN.C.and Loader A.J, "Mechatronics", CRC Press, 1993, First Indian Print 2010. Jacob Fraden, "Handbook of Modern Sensors Physics, Designs, and Applications", 5th Edition, Springer International Publishing, 2016.	REFERENCES James Harter, "Electromechanics, Principles and Concepts and Devices", Prentice Hall, New Delhi, 1995. David W. Pessen, "Industrial Automation Circuit Design and Components", Wiley India, 2011. Bolton.W, "Programmable Logic Controllers", Elsevier, 2015. Brian Morris, "Automatic Manufacturing Systems Actuators, Controls and Sensors", McGraw Hill, New York, 1994 Godfrey C. Onwubolu, "Mechatronics Principles and applications", Butterworth-Heinemann, New Delhi, 2006.

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 2	Apply	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Analyze	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. B. Sriram, WABCO INDIA LTD, sriram.b@wabco-auto.com	DR J.Prasanna, CEG, Anna University, pras_me@yahoo.com	1. Mr.N. Karthikeyan, SRMIST
Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	Dr.R.Sivaramakrishnan, MIT, Anna University, srk@mitindia.edu, srk@annauniv.edu	2. Mr.V.Manojkumar, SRMIST

Course Code	18MEE322T	Course Name	FLUID POWER CONTROL	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses		Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards		NIL	

Course Learning Rationale (CLR):	The purpose of learning this course is to:
CLR-1 :	Be familiar with the construction and working of hydraulic power generating and utilizing elements
CLR-2 :	Know the working of various control valves and familiar with accessories in hydraulic systems
CLR-3 :	Be familiar with the construction and working of pneumatic systems and fluidic control
CLR-4 :	Be familiar with designing of fluid power circuits for given applications
CLR-5 :	Know the maintenance procedures and trouble shooting
CLR-6 :	understand the fluid power systems and to develop circuits for industrial applications

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)
CLO-1 :	Recognize the use of power generating elements, and acquire knowledge the principles and characteristics of hydraulic components	1&2	90	85
CLO-2 :	Acquire knowledge on working of various control valves and familiar with accessories in hydraulic systems	1	90	85
CLO-3 :	Acquire knowledge on the principles and working of pneumatic components.	1	90	85
CLO-4 :	Design the circuit for given applications	1,2&3	90	85
CLO-5 :	Acquire knowledge on maintenance and analyze the trouble shooting of fluid power systems	1&2	90	85
CLO-6 :	Understand fluid power systems and apply knowledge to develop fluid power circuits for industrial applications	1,2&3	90	85

Program Learning Outcomes (PLO)														
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
H	-	-	-	-	-	-	-	-	-	-	-	L	L	L
H	-	-	-	-	-	-	-	-	-	-	-	M	L	L
H	-	-	-	-	-	-	-	-	-	-	-	M	L	L
H	H	H	-	M	-	-	-	-	-	-	-	H	H	H
H	-	-	-	-	M	-	-	-	-	M	H	H	H	H
H	H	H	-	-	M	-	-	-	-	-	M	M	M	M

Duration (hour)		Hydraulic Power Generating And Utilizing Systems	Hydraulic Valves And Accessories	Pneumatic Systems	Design Of Fluid Power Systems	Applications, Maintenance And Trouble Shooting
		10	9	9	9	8
S-1	SLO-1	Introduction to fluid power system, Hydraulic fluids functions, types, properties, selection and application.	Construction and working of manually, pilot and solenoid operated 2/2, 3/2, 4/2, 4/3, directional control valves	Introduction, comparison with hydraulic systems and electrical systems	Fluid power actuators: Speed and force calculations in fluid power systems	Industrial hydraulic circuits for riveting machine.
S-2	SLO-1	POWER GENERATING ELEMENTS: Construction, operation, characteristics of External Gear pump, internal Gear pump	Construction and working of pressure relief, compound pressure relief, pressure sequence valves	Construction, operation, characteristics and symbols of reciprocating and rotary compressors	Pump performance calculations, Sizing of reservoirs. Calculation of pressure and pressure drop across components in fluid power circuits	Hydraulic circuits for grinding and shaping machine.
S-3	SLO-1	Construction, operation, characteristics of Lobe, Gerotor and Screw pumps	Construction and working of pressure reducing, counter balance valves	Construction, operation, characteristics and symbols of 3/2, 5/2, 5/3 manual operated, pilot operated and solenoid operated DCVs	Finding the capacity of accumulators required for hydraulic systems.	Working of hydraulic press and pump unloading circuits
S-4	SLO-1	Construction, operation, characteristics of Un balanced and balanced vane pump	Working principle of check valve, throttle valve, one way FCV.	Need for air treatment, Filter, Regulator, Lubricator, Muffler and Dryers	Selection of different components such as reservoir, various valves, actuators, filters, pumps for a practical application.	Hydraulic / pneumatic circuits for material handling Systems
S-5	SLO-1	Construction, operation, characteristics of pressure compensated vane pump	Working principle of pressure compensated FCV, and their applications.	Introduction to fluidic devices, working of Bi-stable, monostable devices	Design of hydraulic/pneumatic circuits for simplereciprocation, regenerative, speed control of actuators	Preventive and breakdown, maintenance procedures in fluid power systems
S-6	SLO-1	Construction, operation, characteristics of bent axis piston pump, swash plate piston pump and Radial Piston Pump	Importance of proportional valves, Servo valves and its applications	Fluidic application circuits – continuous reciprocation and sequencing	Design of hydraulic/pneumatic circuits for sequencing, synchronization	Trouble shooting of fluid power systems : problems, causes and remedies- hydraulics

S-7	SLO-1	Construction and working of single acting, double acting hydraulic linear actuators	Need for intensifier in hydraulic systems, applications	Pneumatic Sensors types and applications	Cascading circuit for trapped signals : two cylinders	Trouble shooting of fluid power systems : problems, causes and remedies- pneumatics
S-8	SLO-1	Special cylinders: Tandem, Rodless, Telescopic	Different switches, filters, seals, fittings and other accessories used in hydraulic systems	Introduction to Electro Pneumatics – switches, relays, solenoids	Cascading circuit for trapped signals : three cylinders	Safety aspects involved fluid power systems
S-9	SLO-1	Cushioning arrangement for cylinders to reduce the impact on the cylinders, Various cylinder mountings	Functions, types and applications of accumulators in hydraulics	Constructing electrical ladder diagrams for various fluid power applications.	Fail-safe circuit, counter balance circuit, actuator locking	
S-10	SLO-1	Construction and working of Gear, Vane, Piston motors to obtain rotary motion				

Learning Resources	<ol style="list-style-type: none"> 1. Anthony Esposito, "Fluid Power with applications", Pearson Education Inc, 2015. 2. Majumdar.S.R, "Oil Hydraulic Systems: Principles and Maintenance", Tata McGraw Hill Publishing company Ltd, New Delhi, 2006. 3. Majumdar.S.R, "Pneumatic systems – principles and maintenance", Tata McGraw Hill Publishing company Ltd, New Delhi, 2006 4. Ilango Sivaraman, "Introduction to Hydraulics and Pneumatics", PHI Learning Pvt. Ltd, New Delhi, 2017. 5. Joji Parambath "Industrial Hydraulic Systems: Theory and Practice", Universal Publishers, USA, 2016. 6. Eurling Ian C. Thmer, "Engineering Applications of Pneumatics and Hydraulics", Routledge, Taylor & Francis group, London and Newyork, 2011. 7. Andrew Parr, "Hydraulics and Pneumatics: A technician's and engineer's guide", Elsevier Ltd, 2011. 8. Anton H Hehn, "Fluid Power Trouble Shooting", Marcel Dekker Inc., NewYork, 1995
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Evaluate Create	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. R. Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in, rkpearls@yahoo.com	1. Dr. P. Hariharan, Anna University, hari@annauniv.edu, hariharan2311@gmail.com	Dr. M. R. Stalin John, SRMIST
Mr. S. Sendilkumar- Festo India Pvt Ltd	2. Dr.N.Arunachalam, IIT Madras, chalam@iitm.ac.in	Mr. R. Murugesan, SRMIST

Course Code	18MEE323T	Course Name	PROCESS PLANNING AND COST ESTIMATION	Course Category	E	Professional Elective	L 3	T 0	P 0	C 3
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Pre-requisite Courses	18MEC103T	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Acquire knowledge about Process planning	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Understand Different Cost and its components	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Learn about cost estimation of products manufactured in foundry and forging shops	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Acquire knowledge about various cost involved in welding and sheet metal shops	Expected Attainment (%)	Design & Development
CLR-5 :	Calculate Machining time for different process		Analysis, Design, Research
CLR-6 :	Impart clear knowledge about process planning, costing, and estimation of machining time		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Design and plan for various process and various manufacturing methodologies	1,2 90 85	H L H M H - - - - - M H H L M
CLO-2 :	Estimate various cost involved in a product	1,2 90 85	H M - M - - - - - M H H L M
CLO-3 :	Estimate cost in different manufacturing shops	1,2 90 85	H H - H - - - - - M M M L H
CLO-4 :	Estimate cost in different fabrication shops	1,2 90 85	H H - H - - - - - M M M L H
CLO-5 :	Estimate machining time of various metal removal operations	1,2 90 85	H H - H - - - - - M M M L H
CLO-6 :	Familiarize in process planning, costing and estimation of machining time	1,2 90 85	H H M M M - - - - - M M M L H

		Process Planning	Costing and Estimation	Estimation of costs in different shops	Estimation of costs in fabrication shops	Estimation of machining times and costs
Duration (hour)		8	9	9	9	10
S-1	SLO-1	Production system and Types of production	Objectives of costing and estimation	Estimation in foundry shop	Welding, Types of weld joints, Gas welding	Machine shop operations, Estimation of Machining time
S-2	SLO-1	Standardization and Simplification	costing and estimation: Functions and procedure	Pattern cost, Casting cost	Estimation of Gas welding cost, Gas cutting	Estimation of machining time for turning, knurling and facing operations : Tutorials
S-3	SLO-1	Production design and selection	Introduction to costs, Computing material cost	Cost estimation in Foundry shop: Tutorials-1	Arc welding: Equipments, Cost Estimation	Estimation of machining time for reaming, threading and tapping operations : Tutorials
S-4	SLO-1	Process planning, Selection and analysis	Direct labor cost, Analysis of overhead costs	Cost estimation in Foundry shop: Tutorials-2	Cost estimation in Welding shop: Tutorials-1	Estimation of machining time for drilling: Tutorials
S-5	SLO-1	Manual/Experience based planning, Variant type CAPP	Expenses: Factory expenses	Forging: Types, Operations	Cost estimation in Welding shop: Tutorials-2	Estimation of machining time for boring : Tutorials
S-6	SLO-1	Generative type CAPP	Administrative expenses, Selling and distributing expenses	Estimation of Losses and time in forging	Estimation in sheet metal shop	Estimation of machining time for shaping Tutorials
S-7	SLO-1	Economics of process planning, case studies	Cost ladder ,Cost of product	Estimation of Forging cost	Shearing and forming	Estimation of machining time for planning Tutorials
S-8	SLO-1	Processes analysis, Break even analysis	Depreciation, Analysis of depreciation	Cost estimation in Forging shop: Tutorials -1	Cost estimation in Sheet metal shop: Tutorials - 1	Estimation of machining time for milling operations : Tutorials
S-9	SLO-1		Problems in depreciation method	Cost estimation in Forging shop: Tutorials -2	Cost estimation in Sheet metal shop: Tutorials - 2	Estimation of machining time for grinding operations : Tutorials
S-10	SLO-1					Case studies: Estimation of cost for a product

Learning Resources	<ol style="list-style-type: none"> 1. Banga.T.R and Sharma.S.C, "Mechanical Estimating and Costing", Khanna publishers, New Delhi, 17th Edition, 2015. 2. Adithan.M.S and Pabla, "Estimating and Costing", Konark Publishers Pvt., Ltd, 2013. 3. Nanua Singh, "System Approach to Computer Integrated Design and Manufacturing", John Wiley & Sons, New York, 2011. 4. Joseph G. Monks, "Operations Management, Theory and Problems", McGraw Hill Book Company, New Delhi, 2008. 5. Narang.G.B.S and Kumar.V, "Production and Planning", Khanna Publishers, New Delhi, 2014. 6. Chitale.A.K and Gupta.R.C, "Product Design and manufacturing", Prentice Hall of India, New Delhi, 2014. 7. Peter Scalton, Process planning, Design/Manufacture Interface, Elsevier Sci. & Tech. 2002.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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2. Dr. A. Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	2. Dr.N.Arunachalam, IIT Madras, chalam@iitm.ac.in	Mr.M.Dhanasekaran, SRMIST

Course Code	18MEE324T	Course Name	FOUNDRY ENGINEERING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
		1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-1 :	Understand the basics of foundry, castings, limitations, patterns, materials, allowances																		
CLR-2 :	Learn design, types of mold, materials, equipment's, sand mold, core, runner, raiser air vents, gatings, methods of solidification.																		
CLR-3 :	Be familiar with the casting process, permanent mold, gravity, pressure die casting, centrifugal casting, precision, shell molding.																		
CLR-4 :	Melting, pouring, qualities issues, types of furnaces, remelting, molten metal treatment, pouring temperature, casting inspection, rectification, cause and remedies for casting defects, destructive testing, NDT, dye penetrant, magnetic particle, X-ray, elimination of dissolved gasses, use of statistical quality control in foundry.																		
CLR-5 :	Understand the Need and area for automation material handling, of raw, molten metal, storage and dispatch, overhead crane, trolley, pollution control, computers in castings and foundry.																		
CLR-6 :	Understand about castings, patterns, molds, quality control, modernization in foundry																		

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Understand the process in foundry, patterns, allowances	1&2	90	85	H	L	M	M	H	L			L	M		M	H	H	M
CLO-2 :	Learn the mold types, core making, methods of solidification	1&2	90	85	H	H	M	M	H					M		M	H	H	M
CLO-3 :	Study the various casting process	1	90	85	H	L	L	M	H					M		M	H	H	M
CLO-4 :	Gain knowledge about furnaces, and quality control in castings.	1&2	90	85	H	L	L	M	H							M	H	H	M
CLO-5 :	Understand the automation in foundry, for handling raw, molten metal finished products,	1&2	90	85	H	L	M	M	H	M	M					M	H	H	M
CLO-6 :	Learn the foundry techniques in broader sense and able to implement.	1&2	90	85	H	L	M	M	H	M						M	H	H	M

		Foundry, patterns, materials, allowances.	Mold types, core making, runner and raisers,	– Different casting types, second operations, rework	Melting of metal and testing of casting and quality control	Modernization economic way of producing castings
Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction to foundry technology, ,	Types of mold	Types of casting process	Types of furnace	Need for modernization in foundry
S-2	SLO-1	Over view of Casting, patterns	Mold equipment's	Permanent molds, gravity casting	Selection of furnace	Materials handling
S-3	SLO-1	Patterns materials, allowances	Mold and core preparation	Co2 process	Melting and remelting	In house metal melting and handling
S-4	SLO-1		Gatings	Image sharpening, Butterworth filters	Inspection of castings	Storage of raw materials, .
S-5	SLO-1	Castings limitations	Runner and raiser	Generation of spatial masks from frequency domain specification,	Defects analysis and remedies, molten metal purification.	work in process, Finished products
S-6	SLO-1	Tupes of patterns	Air vents and its importance	Basic steps in frequency domain filtering	Destructive testing, nondestructive testings. Magnetic particle testings, ultrasonic cell	Types of materials handling
S-7	SLO-1	Advantages of castings	So[dification,typesof solidification	Nonlinear filters, function, Max filter, Min filter	Quality control of castings, techniques.	Electric cranes and trolleys
S-8	SLO-1	Limitations of castings	Defects related to solidifications	Homomorphic filtering, False color, Pseudo color and its approaches and	Application of statistical quality control methods	pollution control
S-9	SLO-1	Assignment on casting, patterns and allowances	Assignment on molds, runner, riser, solidification	Assignments on image filtering in MATLAB/Open CV/Python	Assignment in furnace, casting defects Quality control	Assignment on automation, Materials handling, Materials handling equipments, pollution control

Learning Resources	TEXT BOOKS
	<ol style="list-style-type: none"> 1. Complete casting handbook: Metal casting process, metallurgy., techniques and design-john Campbell. 2. Banga.T.R. and Agelhiarwal.R.I. Foundry engineering, Khanna publishers. New Delhi. 1992. 3. Jain.P.L. Principles of foundry technology, Dhanpat rai & sons. New Delhi.1996
	REFERENCE BOOKS
	<ol style="list-style-type: none"> 4. Taylor.H.F.Flemings.M.C.and Wulff.J. Foundry engineering, WILEY EASTERN LTD. New Delhi.1989 5. Gupta.R.B. Foundry engineering, SATHYA PRAKASAM, New Delhi.1989. 6. ASM Metals, Hand book on castings, vol .15,14 th edition. 2002.

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Understand	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. R. Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in, rkpearls@yahoo.com	1. Dr. P. Hariharan, Anna University, hari@annauniv.edu, hariharan2311@gmail.com	1.,Mr.P.Karthikeyan, SRMIST
2. Dr. A. Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	2. Dr.N.Arunachalam, IIT Madras, chalam@iitm.ac.in	2. Mr.V.Manojkumar, SRMIST

Course Code	18MEE325T	Course Name	THEORY OF METAL FORMING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Impart knowledge about various metal forming process	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Be familiar with the stress criterion for plastic deformation		
CLR-3 :	Attain the ability to identify the process parameters responsible for metal forming		
CLR-4 :	Provide good exposure towards recent trends in metal forming process		
CLR-5 :	Understand the defects and overcome with remedies		
CLR-6 :	Be familiar with the basic science of metal forming, plastic deformation of bulk and sheet metals, in addition to acquire knowledge about the modern processes such as high velocity & super plastic forming.		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Engineering Knowledge
CLO-1 :	Apply & analyze the theories involved in plastic behavior of metals	1&2 90 85	H M L L
CLO-2 :	Estimate the metal working process under various conditions	1,2&3 90 85	H M L L
CLO-3 :	Appreciate the types of plastic forming and equipment's used.	1&2 90 85	H M L L
CLO-4 :	Utilize the various processes of sheet metal forming.	1&2 90 85	H M L L
CLO-5 :	Appreciate the importance of modern metal forming processes.	1&2 90 85	H M L L
CLO-6 :	Apply the theories of plasticity and inspecting methods in various metal forming processes and produce engineering components	1,2&3 90 85	H M L L

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Theory of plasticity: State of stress	Mechanics of metal working -Flow stress determination	Classification of rolling process, Types of rolling mills, Hot and cold rolling	Introduction to Sheet metal forming processes
S-2	SLO-1	Components of Stress- Stress tensor	Effect of temperature in metal working	Forces and geometric relationship in rolling	Rod and wire drawing equipment
S-3	SLO-1	Engineering stress strain relationship	Strain rate effects	Rolling of bars and shapes, Rolling defects, causes and remedies	Shearing, blanking, bending, stretch forming.
S-4	SLO-1	Flow curve and flow rules	Hot, cold and warm working	Classification of Forging process, Forging Equipment, Open and closed die forging	Explosive and press brake forming
S-5	SLO-1	True stress and true strain	Metallurgical structure, Anisotropy	Forging defects, residual stresses	Deep drawing & tube drawing
S-6	SLO-1	Yield criteria	Effects of hardening ,friction and lubrication	Classification of extrusion process, Variables affecting extrusion	Principles and process parameters
S-7	SLO-1	Slip line field theory	Hydrostatic pressure	Hydrostatic extrusion, Production of seamless pipe and tubing	Sheet metal formability
S-8	SLO-1	Plastic work, Plastic anisotropy	Workability, Spring back	Deformation, lubrication and defects in extrusion	Formability limit diagram
S-9	SLO-1	Plastic deformation of crystals	Residual stresses, Deformation processing system	Basics of Severe plastic deformation and its approaches	Defects in formed parts

Learning Resources	1. George E Dieter, "Mechanical Metallurgy", Tata McGraw-Hill Education Pvt. Ltd, 2014. 2. Iuzalec, Andrzej, "Theory of Metal Forming Plasticity", Springer Berlin Heidelberg, 2010 3. A.Rosochowski, "Severe Plastic Deformation Technology", Whittles Publishing, 2017. 4. Z. R. Wang, Weilong Hu, S. J. Yuan, Xiaosong Wang, "Engineering Plasticity: Theory and Applications in Metal Forming", Wiley, 2018, ISBN: 978-1-119-23730-3 5. Serope Kalpakjian and Stevan R Schmid, "Manufacturing Process for Engineering Materials", Pearson Education, 2007	6. Surendar Kumar, "Technology of Metal Forming Processes", PHI Learning Pvt Ltd, 2008 7. William F Hasford, Robert M Caddell "Metal Forming: Mechanics and Metallurgy", Cambridge University Press, 2011 8. ASM "Metals Handbook, Volume 14, Forming and Forging", ASM Metals Park, Ohio, USA, 1998
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
R.GNANAKARAN AGM-Human Resources Super Auto Forge Pvt.Ltd Kolapakkam.Mobile:98849 06001, Email: gnanakaran@superautoforge.net Tel:044 40753611	Dr. Uday Chakkingal, IITM	Mr.S.Sasikumar , SRMIST
2. Dr. A. Velayutham, DRDO, Avadi, velayudham.a@cwrde.drdo.in	Dr.V..S. Sethilkumar,CEG,Anna University	Dr.U. Mohammed Iqbal , SRMIST

Course Code	18MEE326T	Course Name	WELDING TECHNOLOGY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:
CLR-1 :	Be familiar with the welding power sources and welding fundamentals
CLR-2 :	Be familiar with the fusion welding processes
CLR-3 :	Be familiar with the solid-state welding processes
CLR-4 :	attain the knowledge about welding metallurgy
CLR-5 :	attain the knowledge about brazing and soldering technology
CLR-6 :	Understand the concept of weldability, weld quality, welding defects and welding inspection

Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:	Level of TT	Expected	Expected
CLO-1 :	Understand the fundamentals of welding processes and to recognize the importance of arc physics , weld protection		1 & 2	90	85
CLO-2 :	Understand the fusion welding processes and to recognize the various types of fusion techniques and be able to apply those techniques for any work		1, 2 & 3	90	85
CLO-3 :	Understand the solid-state welding processes and to recognize the various types of solid-state techniques and be able to apply those techniques for any work		1, 2 & 3	90	85
CLO-4 :	Obtained the knowledge about welding metallurgy and be able to apply the principle of metallurgy to recognize weld joint microstructure		1, 2 & 3	90	85
CLO-5 :	Understand the concept of brazing and soldering techniques and able to apply the concept to critical welding aspects		1 & 2	90	85
CLO-6 :	Understand the concept of weldability, weld quality, and welding defects, acquire the knowledge of welding inspection and testing and be able to apply the concept to identify any weld defects		1, 2 & 3	90	85

Learning			Program Learning Outcomes (PLO)														
1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
			H	M	L	M	-	M	M	-	-	-	-	-	H	M	H
			H	M	M	H	M	-	H	M	-	-	-	-	H	M	H
			H	M	M	H	M	-	H	M	-	-	-	-	H	M	H
			H	H	-	H	-	-	H	M	-	-	-	-	H	M	M
			H	L	L	L	-	-	M	M	-	-	-	-	H	L	M
			H	H	M	H	L	-	M	M	-	-	-	-	H	M	H

		Welding Fundamentals & Basic Fusion Welding Processes	Advanced Fusion Welding Processes	Solid-State Welding Processes	Welding Metallurgy	Weld Quality & Inspection
Duration (hour)		9	9	9	9	9
S-1	SLO-1	Manufacturing and Joining, Welding, Need for welding, Applications, Advantages and Disadvantages	Fundamentals of gas metal arc welding, process variables, effect of filler metals on weld	Fundamental aspects of solid state processes, common process variables, bonding mechanism	Basic solidification concepts, solidification modes and constitutional supercooling, dendrite and cell spacing	Design of weldments, Concept of weldability
S-2	SLO-1	Fundamental Mechanisms of welding, Classifications of welding process	Fundamentals of gas tungsten arc welding, process variables, flux	Fundamentals of forge welding, characteristics, application	Epitaxial and nonepitaxial growth, effect of welding parameters, weld metal nucleation mechanisms	Weldability of ferrous and nonferrous alloys, Weldability test method
S-3	SLO-1	Heat Input and Power density of different welding processes, Cooling rate effect	Pulsed TIG Welding process, process variables	Fundamentals of roll bonding, characteristics, application	Dissimilar welds: issues and solutions	Fundamental concepts of residual stress and distortion,
S-4	SLO-1	Weld protection, Shielding gas, Flux, Types of flux coatings	Cold metal transfer welding process , Process Variables	Fundamentals of ultrasonic welding, characteristics, application	Weld Thermal Cycle	Welding defects, classification and characteristics
S-5	SLO-1	Principle of Fusion welding process, Gas welding process, Types of flames in gas welding process	Fundamentals of flux cored arc welding, process variables, electrode classification	Fundamentals of friction welding, characteristics, application	Heat affected zone thermal cycle	Solidification crack, Hydrogen induced crack
S-6	SLO-1	Shielded Metal arc welding process, welding variables, electrode classification, Physics of welding arc, polarity	Fundamentals of submerged arc welding, process variables, flux	Fundamentals of friction stir welding, process variables, application	Post weld heat treatment of weldments: Need and selection of PWHT parameters	Destructive testing of welded joints, tensile and hardness

S-7	SLO-1	Volt - Ampere Characteristics: Constant current, constant voltage and alternating current	Fundamentals of plasma arc welding, process variables, Hybrid Plasma TIG process.	Friction stir welding tools, effect of tool geometry	Formation of heat affected zone, recrystallization and grain growth	Destructive testing of welded joints, toughness, fatigue and creep
S-8	SLO-1	Arc characteristics: Arc plasma, effect of temperature, Arc distribution, Arc blow	Fundamentals of resistance welding, process variables, types	Fundamentals of explosive welding, characteristics, application	Fundamental concepts of brazing, characteristics, applications	Concept of non-destructive testing, classification
S-9	SLO-1	Fundamentals of weld bead geometry, Types of welded joints, Welding positions and welding processes	Fundamentals of laser beam welding, process variables, Hybrid laser welding process	Fundamentals of diffusion bonding process, process variables, applications	Fundamental concepts of soldering, characteristics, applications	Concept of Radiography, dye penetration and Ultrasonic test

Learning Resources	1.	John C. Lippold, <i>Welding Metallurgy and Weldability</i> , John Wiley & Sons, Inc., publication, 2015.
	2.	A.C. Davies, <i>The science and practice of welding</i> , Vol. 1 and 2, Tenth Edition, Cambridge University Press, 2010.
	3.	<i>Welding Handbook – 9th Edition</i> , Volume 1 to volume 5, American Welding Society, 2007.
	4.	Sindo Kou, <i>Welding Metallurgy</i> , 2nd edition, John Wiley & Sons, Inc., publication, 2003.
	5.	Robert W. Messler, Jr., <i>Principles of Welding-Processes, Physics, Chemistry, and Metallurgy</i> , John Wiley & Sons, Inc., publication, 1999.
	6.	R S Parmar, <i>Welding Engineering and Technology</i> , Khanna Publisher, 2008
	7.	O. P. Khanna, <i>Welding Technology</i> , Dhanpat Rai Publications; 2013 edition (2011)
	8.	Richard L. Little, <i>Welding and Welding Technology</i> , McGraw Hill Education (1 July 2017)

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Dr. B. Arivazhagan Scientific Officer- E Materials Technology Division Metallurgy and Materials Group IGCAR, Kalpakkam 603 102	Dr. P. Sathiy, Professor, Department of Production Engineering, NIT Trichy	Dr. Madhavan S, SRMIST
Dr. Manidipto Mukherjee Sr. Scientist Advanced Manufacturing Centre, Design and Manufacturing Research Group, CSIR-Central Mechanical Engineering Research Institute, Mahatma Gandhi Rd., City Centre, Durgapur 713209, West Bengal, India	Dr.S.Aravindan, Professor, Department of Mechanical Engineering, IIT Delhi	Dr. Shashi Kumar, SRMIST

Course Code	18MEE327T	Course Name	MECHANICAL HANDLING SYSTEMS AND EQUIPMENT	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	PSG Tech "Design Data Book" Kalaikathir Achchagam Coimbatore		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)															
CLR-1 :	Be familiar with Fundamentals of material handling and intraplant transporting facilities				Level of Thinking (Bloom)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Be familiar with Common material handling systems																						
CLR-3 :	Be familiar with automated feeding mechanism and design																						
CLR-4 :	Be familiar with Unit Built Machines (UBM), Automated systems in transfer lines																						
CLR-5 :	Be familiar with Transfer mechanisms, conveyors, part feeding devices																						
CLR-6 :	Be familiar with material handling equipments,and their automated systems																						
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Understand about Fundamentals of material handling and intraplant transporting facilities																						
CLO-2 :	Acquire knowledge on Common material handling systems																						
CLO-3 :	Acquire knowledge on automated feeding mechanism and design																						
CLO-4 :	Understand the Automated systems in transfer lines																						
CLO-5 :	Understand Transfer mechanisms, conveyors, part feeding devices																						
CLO-6 :	Understand material handling equipments, and their automated systems																						

Duration (hour)		Introduction	Common Material Handling Equipment	Automation of Material Handling	Classification of Automated System	Automated Material Handling Equipment
		9	9	9	9	9
S-1	SLO-1	Introduction to work handling concepts - types of intraplant transporting facility	Concepts of Unit Loads, Material handling and Storage	Automated feeding arrangements for discrete parts	Concepts of Unit Built Machines (UBM)	Automated handling and storage systems in manufacturing environment
S-2	SLO-1	Principles of material handling-manual and mechanical handling	Equipments operation and selection	Design based in work piece requirements, orienting methods	Gain lean and green endorsement, collaboration to achieve lean and green goals	Rail Guided Vehicles (rgvs), Automated Guided Vehicles (agvs)
S-3	SLO-1	Principle groups of material handling	Containers, Pallets, Conveyor systems, Industrial trucks, Wagon tipplers	One by one feeding, agonizing, stapling etc	Classification and elements, Power Units, self-contained and separate feed type, Change over UBM	Applications of rgvs and agvs, Automated Storage and Retrieval Systems (AS / RS)
S-4	SLO-1	Choice of material handling equipment, hoisting equipment	Transporters, stackers, reclaimers	Feeding continuous material liquids, granules etc	Transfer lines – classification and their components	AS / RS in the Automated factory
S-5	SLO-1	Surface and overhead equipment-General characteristics of overhead equipments and their application	Silos & hoppers and their accessories, Ropeways, Ship loaders, Cable cranes	Automated assembly system, elements,	Automated systems for handling and transfer of prismatic, axis symmetric parts and asymmetric parts in transfer lines	Considerations for planning an AS /RS system, Applications of AS / RS
S-6	SLO-1	Introduction to control of hoisting equipments	Container handling systems, Electric lifts	Automated assembly system ,configuration design, details and control	Case studies on transfer lines – interlocked	Principles of work holding devices – Modular fixturing
S-7	SLO-1	Storage – open and closed storage systems	Hoists, EOT cranes, Elevators	Special feeding mechanisms	Case studies on palletized and flexible inter linkage transfer lines	Flexible fixturing systems
S-8	SLO-1	Bulk loading, Unloading, Shipping	Material handling equipments in Steel mills, Power plants, Mines, Automobile and Transport Industries	Automated inspection and their design	Control systems for flexible inter linkage transfer lines	Fixturing for FMS
S-9	SLO-1	Receiving systems and operations-First in first out(FIFO),last in first out(LIFO)	Large scale Constructions etc. Case Study for All Above Mentioned Handling systems.	Case study for automated material handling.	SWARF handling and disposal systems	Robots and their applications in handling and storage

Learning Resources	1. Groover. M. P., "Automation, Production Systems and CIM", Prentice hall India, 2007. 2. Morris A. Cohen, Uday M. Apte., "Manufacturing Automation", Irwin, Chicago, 3. James A. Tompkins., "Facilities planning", John wiley& Sons Inc, 1984. 4. James. M. Apple, "Principles of layout and material handling", Ronald press, 1977 5. N.Rudenko" Materials Handling equipment" Envee publisher, New Delhi
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. R. Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in, rkpearls@yahoo.com	1. Dr. P. Hariharan, Anna University, hari@annauniv.edu, hariharan2311@gmail.com	1. Mr. C. Balasuthagar, SRMIST
2. Dr. A. Velayutham, DRDO, Avadi, velayudham.a@cwrde.drdo.in	2. Dr.N.Arunachalam, IIT Madras, chalam@iitm.ac.in	Dr. M. Iqbal, SRMIST

Course Code	18MEE328T	Course Name	NON-TRADITIONAL MACHINING TECHNIQUES	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Be familiar with the concept of Non-traditional machining techniques and their need and advantages over traditional machining techniques		1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Be familiar with the classification of Non-traditional machining techniques		Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Be familiar with the Mechanical energy based Non-traditional machining techniques																			
CLR-4 :	Be familiar with the Electro-chemical energy based Non-traditional machining techniques																			
CLR-5 :	Be familiar with the Thermal energy based Non-traditional machining techniques																			
CLR-6 :	Be familiar with the latest developments in various Non-traditional machining techniques																			
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																		
CLO-1 :	Differentiate between Traditional and Non-traditional machining techniques.		1, 2	90	85	H	-	-	-	-	M	-	-	-	-	-	-	-	-	M
CLO-2 :	Acquire knowledge on basic components and working principles of different Non-traditional machining techniques.		1	90	85	H	-	-	-	-	-	-	-	-	-	-	-	H	-	-
CLO-3 :	Understand the major process parameters like operating voltage, current, time on, time off etc.		1	90	85	H	-	-	-	M	-	-	-	-	-	-	-	H	-	-
CLO-4 :	Evaluate the effect of various process parameters on machining characteristics like surface roughness, surface integrity, etc.		1, 2, 3	90	85	H	-	-	-	L	-	-	-	-	-	-	-	H	-	-
CLO-5 :	Learn the processes of machining hard to cut and high strength materials and alloys.		1, 2	90	85	H	-	-	-	L	-	M	-	-	-	-	-	H	-	-
CLO-6 :	Understand the recent developments and applications in Non-traditional machining techniques.		1, 3	90	85	H	-	-	-	-	-	-	-	-	-	-	-	H	-	M

		Basics of Non-Traditional Machining and Mechanical Energy Techniques-I	Mechanical Energy Techniques-II	Chemical and Electro Chemical Techniques	Thermo Electrical Energy Techniques	Thermal Energy Techniques
Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction of non-traditional machining	Operating principles and equipment of water jet machining	Fundamentals, operating principle, advantages, limitations, applications of chemical machining process.	Operating principles and equipment of electrical discharge machining	Operating principle and equipment of electron beam machining
	SLO-2	Difference between traditional and non-traditional machining	Process parameters, applications, advantages and limitations of water jet machining	Classification and selection of Etchant and maskant	Subsystems of electrical discharge machining	Generation and control of electron beam
S-2	SLO-1	Need for non-traditional machining	Operating principles and equipment of abrasive water jet machining	Operating principles, equipment and subsystems of electrochemical machining	Power circuits and electrode feed mechanism in electrical discharge machining	Parameters influencing metal removal in electron beam machining
	SLO-2	Machining characteristics and classification of non-traditional machining	Mechanism of metal removal in abrasive water jet machining	Material removal rate and tool design in electrochemical machining	Process parameters, selection of tool electrode in electrical discharge machining	applications, advantages and limitations of electron beam machining
S-3	SLO-1	Consideration in process and material selection.	Parameters influencing metal removal rate	Tool Material, Tool Feed System, Design For Electrolyte Flow	Dielectric fluids and flushing methods in electrical discharge machining	Operating principle and equipment of plasma arc machining
	SLO-2	Applications of non-traditional machining	Applications, advantages and limitations of abrasive water jet machining	Process parameters in electrochemical machining	Characteristics of spark eroded surface	Gas mixture, Types of Torches of plasma arc machining
S-4	SLO-1	Operating principle, elements and equipment of Ultrasonic machining	Operating principle and equipment of abrasive flow machining	Problems for estimation of material removal rate in electrochemical machining	Recast layer formation	Parameters influencing metal removal in plasma arc welding
	SLO-2	Tool feed Mechanism	Mechanism of metal removal in abrasive flow machining	Advantages, limitations, applications and recent development of electrochemical machining	Surface finish and machining accuracy in electrical discharge machining	Applications, advantages and limitations of plasma arc machining

S-5	SLO-1	Cook's model for material removal	Process parameters in abrasive flow machining	Operating principle and equipment of electro chemical grinding	Tool Electrode design, Tool wear characteristics of spark eroded surfaces	Operating principle and equipment of laser beam machining
	SLO-2	Problems in estimation of Material removal rate (MRR) for Ultrasonic machining	Classification of abrasive flow machining, Applications, advantages and limitations of abrasive flow machining	Metal removal rate and process parameters in electro chemical grinding	Problems in estimation of material removal rate in electrical discharge machining	Process Characteristics and Thermal Features of laser beam machining
S-6	SLO-1	Process parameters of Ultrasonic machining	Operating Principle of magnetic abrasive machining	Problems for estimation of metal removal rate in electro chemical grinding	Operating principle of wire cut electrical discharge machining	Types of lasers used in laser beam machining
	SLO-2	Applications, Advantages and limitations of Ultrasonic machining	Elements and equipment of magnetic abrasive machining	Process Characteristics of electro chemical grinding	Equipment of wire cut electrical discharge machining	Parameters influencing metal removal, applications, advantages and limitations of laser beam machining
S-7	SLO-1	Operating Principle of Abrasive jet machining	Mechanism of metal removal in magnetic abrasive machining	Benefits, limitations and applications of electro chemical grinding	Process parameters of wire cut electrical discharge machining	Operating principle and equipment of Ion beam machining
	SLO-2	Elements and equipment of Abrasive jet machining	Process parameters of magnetic abrasive machining	Recent developments in electro chemical grinding process	Advantages, limitations and applications of wire cut electrical discharge machining	Process Characteristics of Ion beam machining
S-8	SLO-1	Mechanism of metal removal in Abrasive jet machining	Applications, advantages and limitations of magnetic abrasive machining	Electrochemical Drilling	Operating principles and equipment in electrical discharge grinding	Material removal rate, Accuracy and surface effects in Ion beam machining
	SLO-2	Process parameters of Abrasive jet machining	Process capabilities of magnetic abrasive machining	Electro Stream (Capillary) and Electrochemical jet drilling.	Process parameters, surface finish and machining accuracy in electrical discharge grinding	Parameters influencing metal removal rate
S-9	SLO-1	Process capabilities of Abrasive jet machining	Operating Principle of Ice jet machining	Fundamentals of electro chemical honing	Machine tool selection	Applications, advantages and limitations of Ion beam machining
	SLO-2	Applications, Advantages and limitations of Abrasive jet machining	Process description of Ice jet machining	Fundamentals of deburring process	Application and recent developments in electrical discharge grinding	Recent developments and trends in Thermal energy based non-traditional machining techniques

Learning Resources	<p>P. C. Pandey and H.S. Shan, "Modern Machining Processes", McGraw Hill, 2017.</p> <p>Vijay K. Jain, "Advanced Machining Processes". Allied Publishers, 2007.</p> <p>P K Mishra, "Nonconventional Machining", Narosa Publishing House, 2007.</p> <p>G. F. Benedict, "Non-Traditional Manufacturing Processes", CRC Press, New York, 1987.</p> <p>Sahu R.K. and Somashekhar S.H, "Corona Discharge Micromachining for the Synthesis of Nanoparticles: Characterization and Applications", CRC Press, Taylor & Francis, New York, 2019.</p>	<p>Amithaba Bhattacharya, 'New Technology', Tata McGraw Hill, 2006.</p> <p>Hassan El-Hofy, 'Advanced Machining Processes', McGraw Hill, 2005.</p> <p>Wellar P C, 'Non-Traditional Machining Processes', SME Michigan, 1984.</p> <p>Carl Sommer, 'Non Traditional Machining Handbook', Advanced Pub, 2000.</p>
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.K.Balasubramanian, AGM, Lucas TVS Ltd., Puducherry	1. Dr.V.Satheesh Kumar, Assistant Professor, Production Engg., NIT Trichy	1. Mr.V.Veeranaath, SRMIST
2. Mr.Durga PrasadPadhy, Manager, Vendata Resources Ltd., Jharsuguda, Orissa		2. Dr.Ranjeet Kumar Sahu, SRMIST

Course Code	18MEE329T	Course Name	MODERN MANUFACTURING TECHNIQUES	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering		Data Book / Codes/Standards	NIL	

Course Learning Rationale (CLR):		The purpose of learning this course is to:		
CLR-1 :	Be familiar with the modern casting methods			
CLR-2 :	Know the modern methods of manufacturing from powders			
CLR-3 :	Be familiar with the micro-electronic manufacturing			
CLR-4 :	Acquire knowledge about polymers and composites manufacturing			
CLR-5 :	Learn the methods of rapid prototyping and additive manufacturing			
CLR-6 :	Be acquainted with manufacturing approaches of modern intricate products			

Course Learning Outcomes (CLO):		<i>At the end of this course, learners will be able to:</i>	Level of T	Expected	Expected	Engineering	Problem	Design &	Analysis,	Modern T	Society &	Environm	Ethics	Individual	Commun	Project M	Life Long	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	<i>Acquire knowledge of modern and non-conventional casting methods for manufacturing complex intricate shapes of metals</i>		1 & 2	90	85	H			L	M								H	H	
CLO-2 :	<i>Understand the manufacturing methods using powders of metals and ceramics</i>		1 & 2	90	85	H			M	M								H	H	
CLO-3 :	<i>Get acquaintance with manufacturing methods of semiconductors and microelectronic devices</i>		1, 2, 3	90	85	H			H	L								H	M	
CLO-4 :	<i>Obtain knowledge of polymers and composites manufacturing methods</i>		1 & 2	90	85	H				L								H	H	
CLO-5 :	<i>Understand the purpose and methods of rapid prototyping and additive manufacturing</i>		1 & 2	90	85	H			H									H	M	
CLO-6 :	<i>Identify suitable methods for various product manufacturing</i>		1, 2, 3	90	85	H			H	L								H	M	

		Modern Casting Methods	Modern Forming Methods	Manufacturing Of Semiconductors And Electronic Devices	Manufacturing Of Composite Materials	Rapid Prootyping And Additive Manufacturing
Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction to conventional and modern casting methods	High speed metal forming- Explosive, Electromagnetic and electrohydraulic	Semiconductors and silicon-Introduction, Structure of silicon, Properties	Selection of composite matrices and reinforcements	Rapid prototyping - Introduction, Steps in RP Technology, STL Format, Support Structures
S-2	SLO-1	Expendable pattern casting - Pattern making process, Advantages, Applications	Semisolid metal forming Types (Thixocasting, Rheocasting, Thixomolding) Advantages, Applications	Crystal growing and wafer preparation	Overview of polymer matrix composites, Types of reinforcements, Preforms, Prepregs	Rapid prototyping- Advantages, Limitations, Applications
S-3	SLO-1	Plaster mold casting – Conventional and Antioch Process, Advantages, Applications	Peen forming of sheet metals - Process, Advantages, Applications	Film deposition -Evaporation, Sputtering, CVD	Open mould processes - Hand lay-up, Spray-up, Vacuum Bagging, Automated tape -laying machines	Introduction to Additive Manufacturing for product development – Advantages, Materials
S-4	SLO-1	Ceramic mold casting - Process, Advantages, Applications	Super plastic forming - Material requirements, Advantages, Disadvantages	Oxidation - Dry oxidation, Wet oxidation	Closed mould processes - Compression moulding, Transfer moulding, Injection moulding	Stereo lithography
S-5	SLO-1	Vacuum casting - Process, Advantages, Applications	Design consideration for Powder Metallurgy forming	Lithography - Photolithography process	Filament winding, Pultrusion, Pulforming, Cutting of FRP	Laminated object manufacturing
S-6	SLO-1	Squeeze casting - Process, Advantages, Applications	Production of metal powders Atomization, Reduction, Electrolytic Deposition, Carbonyls, Comminution, Mechanical Alloying	Etching - Wet chemical etching, Dry plasma etching, Cryogenic dry etching	Fabrication of metal matrix composites- Liquid state and Solid state	Selective laser sintering
S-7	SLO-1	Rapid solidification for amorphous alloys, Melt Spinning Process	Sintering, Finishing of sintered parts, Secondary and finishing operations	Diffusion, Drive-in Diffusion and Ion implantation	Deposition technique for MMC, Insitu composites	Fused deposition modeling
S-8	SLO-1	Casting techniques for single crystal components	Ceramic forming -casting, powder	Metallization - Requirement, Methods and testing	Conventional manufacturing of ceramic composites, Prepeg formation-slurry impregnation	Solid ground curing, 3D ink jet printing

S-9	SLO-1	Conventional casting of Turbine blades, Directional solidified blades, Single crystal blades	Forming and shaping glass-Flat Sheet, Rods and Tubes, Discrete Products, Glass Fiber	Bonding and packaging, MEMS, NEMS	Porous preform infiltration- Melt, Sol-gel, Polymer, Reactive liquid, Chemical vapour, Directed oxidation	Additive manufacturing-Applications
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Learning Resources	<ol style="list-style-type: none"> 1. Serope Kalpakjian, "Manufacturing Engineering and Technology", Fourth Edition, Addison-Wesley Publishing Co., Boston, 2014. 2. Mikell P. Groover, "Principles of Modern Manufacturing SI Version", Wiley India, 2018. 3. Parasuraman Swaminathan, "Semiconductor Materials, Devices and Fabrication", Wiley India, 2017. 4. Madou.M.J, "Fundamentals of micro fabrication: The Science of Miniaturization, Second Edition", CRC Press, USA, 2002. 5. C. S. Lim, K. F. Leong, C. K. Chua, "Rapid Prototyping: Principles and Applications" (3rd Edition), World Scientific Publishing Company, 2009. 6. P. D. Hilton, P.F. Jacobs, "Rapid Tooling: Technologies and Industrial Applications", 1st Ed., Marcel Dekker, Inc., 2010. 7. Steinar Westhrin Killi, "Additive Manufacturing: Design, Methods, and Processes", Pan Stanford Pub., 2017. 8. T. DebRoy et al., Review Article – "Additive manufacturing of metallic components – Process, structure and properties", Progress in Materials Science, Volume 92 (2018), 112-224.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Dr. Saurabh Kundu Head Product Research Tata Steel Jamshedpur Email: saurabhkundu@tatasteel.com	Dr. Debdulal Das Associate Professor Dept of Metallurgy and Materials Engineering Indian Institute of Engineering Science and Technology, Shibpur Howrah, Email: debdulal_das@metal.iests.ac.in	1. Dr.Shubhabrata Datta
Dr. A. Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	2. Dr.N.Arunachalam, IIT Madras, chalam@iitm.ac.in	Dr. M. Iqbal, SRMIST

Course Code	18MEE330T	Course Name	FLEXIBLE MANUFACTURING SYSTEMS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)															
CLR-1 :	Be familiar with the basic types of production systems				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLR-2 :	understand the group technology, methods and FMS							Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3	
CLR-3 :	Be familiar with the fundamentals and need of FMS planning							H	H	-	-	-	-	-	-	-	-	-	-	-	L	-	H
CLR-4 :	Detailed study of flexible manufacturing cells and systems							H	H	H	-	-	-	-	-	-	-	-	-	-	M	L	H
CLR-5 :	Be familiar with the FMS software							H	M	-	-	-	-	-	-	-	-	-	-	-	M	-	M
CLR-6 :	Familiar with production systems, grouping of parts and FMS, FMC and different software's, hard ware components involving.							H	M	-	-	-	-	-	-	-	-	-	-	-	M	-	M
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																					
CLO-1 :	Understand and acquire knowledge on Basics types of production systems, inventory and scheduling				1	90	85	H	H	-	-	-	-	-	-	-	-	-	-	L	-	H	
CLO-2 :	Understand the group technology, types of coding systems and FMS				1,2	90	85	H	H	H	-	-	-	-	-	-	-	-	-	M	L	H	
CLO-3 :	Understand the basic fundamentals and analysis methods for FMS planning				1,2	90	85	H	M	-	-	-	-	-	-	-	-	-	-	M	-	M	
CLO-4 :	Understand the Flexible manufacturing cells and Communication networks for different systems				1,2	90	85	H	M	-	-	-	-	-	-	-	-	-	-	M	-	M	
CLO-5 :	Acquire knowledge on FMS software's				1,2	90	85	H	M	-	-	-	-	-	-	-	-	-	-	M	-	M	
CLO-6 :	Understand about production systems, group technology coding and FMS, FMC systems				1,2	90	85	H	H	H	-	-	-	-	-	-	-	-	-	M	L	M	

		Production systems	Group technology and FMS	Flexible Planning	Flexible Manufacturing Cells	FMS Software
Duration (hour)		9	9	9	9	9
S-1	SLO-1	Types of production systems job, batch and mass production system with examples	Introduction to GT, Formation of part families	Physical planning for FMS, Objective, guide line	Introduction of cell description and its classifications	Introduction to Different FMS software's and advantages
S-2	SLO-1	Different manufacturing functions, Manufacturing support	Part classification methods and different coding systems with examples	Need for flexibility and FMS in industries	Definition of unattended machining, Requirement and features.	General structure and Requirements for FMS software
S-3	SLO-1	Organization and information processing in manufacturing.	Production flow analysis methods, Machine cell design, Clustering algorithm.	User supplier responsibilities in planning, user – supplier role in site preparation.	Component handling and storage systems	Functional descriptions and operational overview
S-4	SLO-1	Different types of plant layouts and advantages of each layout.	Bond Energy algorithm method with example	Machine tool selection and layout of FMS.	Difference between Cellular system and FMS system	FMS installation
S-5	SLO-1	Plant location selection methods with examples	Scheduling and control in cellular manufacturing	Computer control system and different Data files, Reports and planning the FMS system.	FMC hardware configuration and controllers	Acceptance testing, Performance goals
S-6	SLO-1	Work in progress inventory models	System planning guide lines and sizing and human resources.	Human resources for FMS, Objective, staffing, supervisor role.	PLC and computer controllers, Different FMC Communication networks	FMS application in machining, sheet metal fabrication
S-7	SLO-1	Scheduling and its types and advantages	Industrial case study for total parts moving to machine cell and machine cell formation, Manufacturing cell	Quantitative Analysis methods for FMS, Simple problems for FMS System analysis.	A case study for modular control design method for a flexible manufacturing cell.	Prismatic component production
S-8	SLO-1	Simple problems in selection of plant location.	Introduction to FMS, components of FMS.	Benefits and limitations for FMS system	Lean manufacturing with example	FMS development towards factories of the future
S-9	SLO-1	Design the different layouts like automobile plant and supermarket and hospitals and airport...etc	FMS need and types FMS systems.	Simple example of FMS planning for Automobile plant.	Agile manufacturing and example case study	Example case study for FMS

Learning Resources	1. William W. Luggen, "Flexible manufacturing Cells and systems", Prentice hall of New Jersey 1991. 2. Mikell P. Groover, "Automation Production systems and Computer Integrated manufacturing", prentice hall of India, New Delhi, 2007.	3. Jha N.K, " Hand book of Flexible Manufacturing systems", Academic Press, 1991. 4. David J. Parrish, "Flexible Manufacturing", Butterworth-Heinemann, Newton, MA, USA, 1990.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.Mariappan Kanagaraj (Manager - Part Quality Engineering (STA) at Renault Nissan Technology & Business Centre India Pvt Ltd, Chennai Area, India	1. Dr. B. K .Ragunath, Associate Professor, Dept. of Manufacturing Engineering, Annamalai University	1. Mr. Abburi Lakshman Kumar, AP Mech, SRMIST, Kattankulathur
2. Dr. A. Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	2. Dr.G. Elatharasan, Asst.Professor, Dept. of Mechanical Engg., Anna University, Pattukottai.	Dr. M. Iqbal, SRMIST

Course Code	18MEE421T	Course Name	SUSTAINABLE GREEN MANUFACTURING				Course Category	E	Professional Elective				L	T	P	C																																																												
												3	0	0	3																																																													
Pre-requisite Courses		NIL		Co-requisite Courses		NIL		Progressive Courses		NIL																																																																		
Course Offering Department		Mechanical Engineering				Data Book / Codes/Standards				NIL																																																																		
Course Learning Rationale (CLR):		The purpose of learning this course is to:						<table><tr><th colspan="3">Learning</th></tr><tr><th>1</th><th>2</th><th>3</th></tr><tr><td rowspan="6">Level of Thinking (Bloom)</td><td rowspan="6">Expected Proficiency (%)</td><td rowspan="6">Expected Attainment (%)</td></tr></table>			Learning			1	2	3	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	<table><tr><th colspan="15">Program Learning Outcomes (PLO)</th></tr><tr><th>1</th><th>2</th><th>3</th><th>4</th><th>5</th><th>6</th><th>7</th><th>8</th><th>9</th><th>10</th><th>11</th><th>12</th><th>13</th><th>14</th><th>15</th></tr><tr><td>Engineering Knowledge</td><td>Problem Analysis</td><td>Design & Development</td><td>Analysis, Design, Research</td><td>Modern Tool Usage</td><td>Society & Culture</td><td>Environment & Sustainability</td><td>Ethics</td><td>Individual & Team Work</td><td>Communication</td><td>Project Mgt. & Finance</td><td>Life Long Learning</td><td>PSO - 1</td><td>PSO - 2</td><td>PSO - 3</td></tr></table>												Program Learning Outcomes (PLO)															1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
Learning																																																																												
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Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)																																																																										
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			1	2	3	4	5				6	7	8	9	10	11																12	13	14	15																																									
			Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage				Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2													PSO - 3																																												
			CLR-1 :	Be familiar with objectives, concepts and role of Green Manufacturing																																																																								
			CLR-2 :	Be familiar with the tools of Green Manufacturing																																																																								
CLR-3 :	Be familiar with the attribute's decision-making methods																																																																											
CLR-4 :	Be familiar with creating Lean and Green organization																																																																											
CLR-5 :	Be familiar with the Design resources saving into product and processes																																																																											
CLR-6 :	Be familiar with the concepts, tools, attributes, design resources of green manufacturing																																																																											
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																																																																										
CLO-1 :	Understand Green Manufacturing and Sustainable engineering concepts							90	85	M	M	M	L	H	H	M	L					H	H	M																																																				
CLO-2 :	Develop Multi attributes decision making methods							90	85	M	M	M	L	H	H	M	L					H	H	M																																																				
CLO-3 :	Develop Green manufacturing management							90	85	M	M	M	L	H	H	M	L					H	H	M																																																				
CLO-4 :	Develop Applications in green manufacturing							90	85	M	M	M	L	H	H	M	L					H	H	M																																																				
CLO-5 :	Develop design resources saving into product and process									M	M	M	L	H	H	M	L					H	H	M																																																				
CLO-6 :	Understand about the green manufacturing concepts, management, applications and design development.									M	M	M	L	H	H	M	L					H	H	M																																																				
Duration (hour)		8		9		9		9		10																																																																		
S-1	SLO-1	Definition of manufacturing, Impact of manufacturing in environmental ecology		Principles of green manufacturing and its efficiency		Introduction to Multi attributes decision making methods		Question wasteful practices				Design resources saving into product and processes																																																																
S-2	SLO-1	Role of manufacturing sector in national growth		Green manufacturing and sustainability		definition, structure for Multi attributes decision making methods		Gain lean and green endorsement, collaboration to achieve lean and green goals				Closed loop & Open Loop production system																																																																
S-3	SLO-1	Technological change and evolving risk		System model architecture and module		variants and analysis of different methods like Simple Additive Method (SAM)		Track progress for environment and profits				Green manufacturing through clean energy supply																																																																
S-4	SLO-1	concepts of "green" manufacturing need of green manufacturing		Design and planning, control or tools for green manufacturing (Qualitative Analysis)		Weighted Product Method (WPM)		Creation of sustainable growth				Various case studies of implementation of semiconductors manufacturing at industries																																																																
S-5	SLO-1	Green manufacturing strategies		Consumption Analysis, Life Cycle Analysis, Efficiency, Sustainability tools).		Analytic Hierarchy Process (AHP)		Enabling techniques for assuring green manufacturing				Green packaging and supply chain																																																																
S-6	SLO-1	Green manufacturing – motivation, barriers, regulation, policy		Standards for green manufacturing (ISO 14000 and OHSAS 18000)		Technique for Order of Preference by Similarity to Ideal Solution (TOPSIS), Grey Relation Analysis (GRA)		Drivers of green manufacturing, impact, advantages and disadvantages of drivers				Various case studies of implementation of Optimizing Logistics solution at industries																																																																
S-7	SLO-1	Casting defects and remedies.		Waste stream mapping and application		Elimination and Choice Expressing Reality (ELECTRE)		Green architecture and buildings, Sustainable manufacturing resources management				Environmental implication of Nano manufacturing																																																																
S-8	SLO-1	Advantages and limitations of green manufacturing		Identify and apply the concepts of product and process design with environmental forethought		VIKOR method		Carbon footprint analysis and management of manufacturing processes				Various case studies of implementation of lean manufacturing at industries																																																																
S-9	SLO-1	Significance of green manufacturing		Design for environment and for sustainability - Discuss the Product Life Cycle of manufactured goods.		Problems based on different MADMs. 1 C 3 3,4		Green Process Economics, Resource Recovery and Reuse				Various case studies of implementation of Optimizing process or product at industries																																																																

Learning Resources	<ol style="list-style-type: none"> 1. Ronald G. Askin & Jeffrey B. Goldberg, "Design and Analysis of Lean Production Systems", John Wiley & Sons, 2003. 2. Rao.P.N, "Manufacturing Technology, Vol I and II", Tata McGraw Hill Publishing Co., 3rd edition, Sixth Reprint 2010 3. Charles Wankel "21st century management: a reference handbook" SAGE Publications, Inc., 2008. 4. Christian N. Madu "Handbook of environmentally conscious manufacturing" London : Kluwer Academic Publishers, 2001. 5. T.E. Graedel & B.R. Allenby "Industrial Ecology" Pearson Education, Inc. 2003. 6. Joseph Sarkis "Greener manufacturing and operations: from design to delivery and back" Greenleaf Pub., 2001. 7. Ranky, P.G.: "An Introduction to Alternative Energy Sources: An interactive multimedia 3D eBook publication by CIMware USA, Inc. and CIMware Ltd., UK, ISBN 1-872631-97-5, 2008. 8. Ranky, P.G.: "Digital Product Design: Design For Quality, Manufacturing, Assembly & Disassembly Principles, and an Inkjet Printer Disassembly Use Case", DVD video publication by CIMware USA, Inc. and CIMware Ltd., UK, 2008, UPC 632568002983
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. R. Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in, rkpearls@yahoo.com	1.Dr. U. Natarajan, ACGCET-Karaikudi, u.natarajan@accetedu.in	E.Muthu, AP(OG), SRMIST
2. Dr. A. Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	2.Dr. D. Dinakaran, HITS Padur, dinakaran.d@hindustanuniv.ac.in	Dr.P. Nandakumar, SRMIST

Course Code	18MEE422T	Course Name	ADDITIVE MANUFACTURING TECHNOLOGY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Be familiar with the evolution of Additive manufacturing (Why it is disruptive in nature based on evolution) and the materials and design involved				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Be familiar with the various process steps involved in Additive manufacturing (Generic process flow for AM systems)				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Learn the various types of machines and systems involved in Additive manufacturing																					
CLR-4 :	Know the working of powder based Additive manufacturing processes and their applications and limitations																					
CLR-5 :	Know the working of solid and liquid based Additive manufacturing processes and their applications and limitations (Understanding the feedstock material in various AM process)																					
CLR-6 :	Be familiar with components of Additive manufacturing and its applications in industries (Understanding the requirement of process certification for various industrial applications) – Fabrication and repair applications																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	Understand the basic concepts of Additive manufacturing (Why they are classed as disruptive technology(ies)				1&2	90	85	H														
CLO-2 :	The knowledge acquired on the process chain of Additive manufacturing and the various steps involved (Opportunities of implementation in India, global relevance of AM in supply chain – The concepts of Remanufacturing)				1&2	90	85	H		M		H							M	H	H	
CLO-3 :	Recognize the various machines and systems involved in Additive manufacturing and understand their role (in industrial application – fabrication or repair of component)				1	90	85	H	M	M	H	H							M	H	H	
CLO-4 :	Understand the major solid and liquid based Additive manufacturing processes such as stereolithography and fused deposition modeling and recognize their application and potential				1&2	90	85	H	M	M	H	H							M	H	H	
CLO-5 :	Understand the major powder based Additive manufacturing processes such as 3D printing (Directed Energy deposition, powder bed fusion)and electron beam melting, Binder jetting and recognize their application and potential in fabrication and repair for various industrial application				1&2	90	85	H	M	M	H	H							M	H	H	
CLO-6 :	Recognize the importance of Additive manufacturing and its various processes and systems – Industry specific (such as Aerospace, power generation, heavy machinery, Automotive)				1&2	90	85	H														

		Introduction To Additive Manufacturing	Process Chain Of Additive Manufacturing	Machines And Systems Of Additive Manufacturing	Solid And Liquid Based Additive Manufacturing	Powder Based Additive Manufacturing
Duration (hour)		9	9	9	9	9
S-1	SLO-1	Evolution of Additive manufacturing, Need, Comparison with CNC machining (Concepts of Hybrid manufacturing & applications)	Conceptualisation, Synergistic interaction of processes (AM + CNC/Adaptive)	Introduction to various machines and systems of Additive manufacturing (based on feedstock material, based on energy used, application)	Classification (scale of printing)	Classification (scale of printing)
S-2	SLO-1	Basic principles of additive manufacturing (Complex interaction of process, design and materials)	CAD model preparation, CAM operations (Tool path generation)	Construction of CNC machines, Process chamber (Subtractive process conversion to AM process)	Guidelines for process selection	Powder fusion mechanisms: solid-state sintering, Chemically induced sintering
S-3	SLO-1	Classification of Additive manufacturing processes	Part orientation and support generation	Energy Delivery: Lasers and electron beam, plasma arc, kinetic energy (cold spray in AM)	Fused deposition modeling - Processes and principle	Selective laser sintering: process, principles
S-4	SLO-1	Materials for Additive manufacturing (selection of feedstock materials)	Conversion to Stereolithographic file format	Material delivery: Powder feeding and wire feeding systems (difference in powder and wire feedstock – advantages and limitations for both), handling of feedstock material	Advantages, applications	Advantages, applications

S-5	SLO-1	Designing for Additive manufacturing (Design optimization)	Transfer to Additive manufacturing machine and file manipulation	Rapid tooling equipment: direct and indirect methods	Laminated object manufacturing	3D printing: process, principles
S-6	SLO-1	Role of Additive manufacturing in product development (Complex geometry requirements, strength to weight requirements)	Machine setup and build, Health & Safety practice (best practice), Feedstock material handling	Post processing equipment: support material removal, preparation for use as a pattern	Stereolithography apparatus: processes and principle	Advantages, applications
S-7	SLO-1	Advantages, Disadvantages, Applications and Opportunities of Additive manufacturing (Opportunities in Indian industries, global prospective)	Removal and clean up, Health & Safety practice (best practice),	Temperature, humidity, oxygen level controllers (process monitoring, affect on mechanical and microstructural properties with these variables)	Advantages, applications	Laser engineered net shaping (LENS process, unique advantages on hybrid scale), process control advantages, limitations,
S-8	SLO-1	Emerging trends and business models (Concepts of Remanufacturing)	Post processing (insitu or external transformative post processing such as heat treatments), machining	Scanning: Raster scan, patterned vector scanning	Challenges in solid and liquid AM processes	Electron beam melting
S-9	SLO-1	Related technologies: Reverse engineering, Computer aided engineering, AM process simulation concepts, predictive modelling	Property enhancement by thermal and non-thermal methods (In relation to type of material)	Post processing: surface texture, accuracy and aesthetic improvement	Case study (with relevance to technology certification)	Case study (with relevance to technology certification)

Learning Resources	<ol style="list-style-type: none"> 1. Ian Gibson, David W Rosen, Brent Stucker., "Additive Manufacturing Technologies: Rapid Prototyping to Direct Digital Manufacturing", Springer, 2015. 2. Chua C.K., Leong K.F., and Lim C.S., "Rapid prototyping: Principles and applications", Third Edition, World Scientific Publishers, 2010. 3. Gebhardt A., "Rapid prototyping", Hanser Gardener Publications, 2003. 4. Liou L.W. and Liou F.W., "Rapid Prototyping and Engineering applications: A tool box for prototype development", CRC Press, 2007. 5. Kamrani A.K. and Nasr E.A., "Rapid Prototyping: Theory and practice", Springer, 2006. 6. Hilton P.D. and Jacobs P.F., "Rapid Tooling: Technologies and Industrial Applications", CRC press, 2000. 7. Pham D.T, Dimov S.S., "Rapid Manufacturing: The Technologies and Applications of Rapid Prototyping and Rapid Tooling", Springer 2001. 8. Gu D., "Laser Additive Manufacturing of High-Performance Materials", Springer, 2014. 9. Rafiq Noorani, "Rapid prototyping: Principles and Applications in Manufacturing" John Wiley & Sons, 2006.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr.Purushothaman, Tesscom Nano Science Inc.	1. Dr. P. Hariharan, Anna University, hari@annauniv.edu, hariharan2311@gmail.com	Dr. P. Mohan Babu, SRMIST
Dr. A. Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	2. Dr.N.Arunachalam, IIT Madras, chalam@iitm.ac.in	Dr. M. Iqbal, SRMIST

Course Code	18MEE423T	Course Name	PRECISION ENGINEERING			Course Category	E	Professional Elective			L	T	P	C										
											3	0	0	3										
Pre-requisite Courses	NIL			Co-requisite Courses	NIL			Progressive Courses		NIL														
Course Offering Department		Mechanical Engineering				Data Book / Codes/Standards			NIL															
Course Learning Rationale (CLR):		The purpose of learning this course is to:					Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand the concept of accuracy and precision in various parametric testing					Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLR-2 :	Realize the striving need for precision and applications																							
CLR-3 :	Know the causes for dimensional and geometrical characteristics errors prior and during machining																							
CLR-4 :	Impart knowledge about basics of precision and ultra precision machining methods																							
CLR-5 :	Be familiar with different precision measuring systems at micro/nano level																							
CLR-6 :	Be familiar with the various lithography techniques																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1 :	Acquire knowledge about the basics of accuracy and alignment tests					1&3	80	85	H				M		M					H	M		H	
CLO-2 :	Identify the dimensional and geometrical errors prior and during machining					1&2	70	85	H	L			M								M		M	
CLO-3 :	Deepen the knowledge of static stiffness and thermal effects					1, 2&3	75	85	H	L		M	M								H	M		
CLO-4 :	Understand the principles of precision machining and importance of digitization in micro-machining					1,2&3	85	85	H	H	L	M	M		M		L			H	H		H	
CLO-5 :	Understand the principles of nano measuring systems					1&2	80	85	M			M	H		L		M			M			M	
CLO-6 :	Understand the principles of various lithographic techniques and currently emerging microscopic techniques					1&2	80	85	M	H	L	M	M		M		L			H	H		H	

Duration (hour)		9	9	9	9	9
S-1	SLO-1	General concept of accuracy, repeatability and precision; Spindle rotation accuracy	Static stiffness	Introduction to precision Engineering and need for having high precision	Introduction to nanotechnology and need for measurement in nanotechnology	Nano Lithography
S-2	SLO-1	Test methods for displacement accuracy	Nature of deformation in a machine tool	Precision machining and finishing operations	Measuring Systems for Nano-manufacturing	Photolithography
S-3	SLO-1	Dimensional wear of cutting tools	Overall stiffness of a lathe	Ultra-precision Processes	In - process measurement of position of processing point	Electron beam lithography
S-4	SLO-1	Accuracy of NC systems, Clamping errors, Setting errors	Compliance of work piece	Tool Materials for Precision Machining: Carbides, Ceramic, Diamond, Cubic Boron Nitride	Post process and online measurement of dimensional features	Ion Beam lithography
S-5	SLO-1	Location of rectangular prism, cylinder	Errors due to the variation of the cutting force and total compliance	Ultra-Precision Machine Elements	Mechanical measuring systems	Optical lithography
S-6	SLO-1	Basic type of tests, Measuring instruments used for testing machine tools	Case study: Errors caused by cutting force deformation in turning and milling	Machining of micro-sized components	Optical measuring systems	LIGA process
S-7	SLO-1	Alignment, Straightness, Flatness tests	Study of thermal effects on machine tool accuracy	Positioning mechanisms and drives – precision gears, servo control systems, electromagnetic and piezo actuators	Electron beam measuring systems	Nanocoatings
S-8	SLO-1	Parallelism, Squareness tests	Methods of decreasing thermal effects	Micro- electro-Mechanical Systems: Characteristics and Principles, Materials, and Fabrication processes	X-ray imaging systems	Micro-metrology
S-9	SLO-1	Circularity, Cylindricity tests	Influence of vibration and noise on accuracy	Emergence of digital precision machining	Pattern recognition and inspection systems	Microscopy techniques for materials characterization: Electron microbe analysis and atom probe tomography

Learning Resources	<ol style="list-style-type: none"> 1. Murthy.R.L, "Precision Engineering in Manufacturing", New Age International, New Delhi, 2005. 2. V.C.Venkatesh, Precision Engineering, Tata Mc.Graw Hill, New Delhi 2007 3. Kalpakjian S., Manufacturing Engineering and Technology. 3rd Ed. Addison-Wesley Publishing Co.,New York, 2001. 4. Norio Taniguchi, "Nanotechnology", Oxford university press, Cambridge, 1996. 5. Lee Tong Hong, "Precision Motion control, Design and Implementation", Springer Verlag, U.K., 2001. 6. Liangchi Zhang, "Precision Machining of Advanced Materials", Trans Tech Publications Ltd., Switzerland, 2001. 7. HiromuNakazawa, "Principles of precision engineering", Oxford University Press, 1994. 8. Sahu R.K. and Somashekhar S.H, "Corona Discharge Micromachining for the Synthesis of Nanoparticles: Characterization and Applications", CRC Press, Taylor & Francis, New York, 2019.
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* Combination of surprise, quiz and assignment tests.

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Durga Prasad Padhy, Manager, Vedanta Resources Limited (Vedanta Aluminium Limited), Jharsuguda, Odisha - 768201 durga.prasadpadhy@vedanta.co.in	Dr. V. Sateesh Kumar, NIT Trichy, sateeshv@nitt.edu	Dr. Ranjeet Kumar Sahu, SRMIST ranjeetkumar.c@ktr.srmuniv.ac.in
Dr. A. Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	2. Dr.N.Arunachalam, IIT Madras, chalam@iitm.ac.in	Dr. M. Iqbal, SRMIST

Course Code	18MEE424T	Course Name	TECHNOLOGY OF SURFACE COATING			Course Category	E	Professional elective			L	T	P	C									
											3	0	0	3									
Pre-requisite Courses	NIL			Co-requisite Courses	NIL		Progressive Courses		NIL														
Course Offering Department		Mechanical Engineering			Data Book / Codes/Standards		NIL																
Course Learning Rationale (CLR):		The purpose of learning this course is to:				Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand the fundamentals of surface engineering				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3	
CLR-2 :	Understand the practical application and importance of coatings																						
CLR-3 :	Understand the different methods of coatings in micro and nano level																						
CLR-4 :	Understand the measurement techniques of different properties of coating																						
CLR-5 :	Understand the maintenance procedures and trouble shooting																						
CLR-6 :	Understand the special surface coating techniques																						
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																					
CLO-1 :	Be familiar with the concepts of surface engineering of various types of coatings.				1&2	90	75	H												H	L	M	
CLO-2 :	Be familiar with the concepts of surface science of various types of coatings				1 & 2	90	75	H												H	L	M	
CLO-3 :	Be familiar with the concepts of surface characterization methods for various types of coatings				1 & 2	90	75	H		M	H									L	H	M	
CLO-4 :	Be familiar on the principles and working of special coating methods				1 & 2	90	75	H	H	M		M		L						M	L	H	
CLO-5 :	Be familiar on the application of suitable methods of coatings on the surface				3	90	75	H	H	H	M	H	M	M						H	H	H	
CLO-6 :	solve various unwanted problems raised on material surface because of degradation by using suitable methods and measurement				2 & 3	90	75	H	H	H	M	H	M	M						M	H	H	
		Fundamental Of Surface Engineering	Special Surface Coating And Surface Modification Techniques I		Special Surface Coating And Surface Modification Techniques II		Surface Characterization Techniques Of Coatings		Applications Of Surface Coatings														
Duration (hour)		9	9		9		9		9														
S-1	SLO-1	Introduction: Engineering components,	Introduction to Electro Chemical Deposition - Electro Plating		Surface Coating by Wetting, Mechanism of Wetting		Measurement of coatings thickness		Cold Spraying and Hard Facing														
S-2	SLO-1	Surface dependent properties and failures,	Anodizing and Electro-Less Plating		Coating on Ceramics by Wetting,		porosity & adhesion of surface coatings		Case studies based on coatings of important engineering components II														
S-3	SLO-1	Importance and scope of surface engineering	Thermal Spray Coating-Combustion Spray and Plasma Spray Process		Coating of Monolayer Abrasive grain by Wetting		Measurement of residual stress & stability		Case studies based on surface modification of important engineering components I														
S-4	SLO-1	Surface and surface energy: Structure and types of interfaces, surface energy and related equations.	Sputter deposition of thin films & coatings – DC & RF		DLC and diamond coatings,		Spectrum of secondary electrons, Scanning Electron Microscopy		Case studies based on surface modification of important engineering components II														
S-5	SLO-1	Surface engineering: classification, definition, scope and general principles	Sputter deposition of thin films & coatings – Magnetron & Ion Beam		Antifriction and anti-scratch coatings		Electron energy analyzers		Functional and nano-structured coatings														
S-6	SLO-1	Surface engineering by material removal: Cleaning, pickling, etching, grinding, polishing	Hybrid / Modified PVD coating processes		Sol Gel Coating,		Auger Electron spectroscopy, Transmission Electron Microscopy		Functional and nano-structured coatings applications in photovoltaic														
S-7	SLO-1	Buffing / puffing (techniques employed, its principle). Role and estimate of surface roughness.	CVD Coating of TiC, Nitride, Chromium, Aluminum Oxide and Diamond		Laser Assisted Surface Engineering		Surface microscopy & topography by scanning probe microscopy		Functional and nano-structured coatings applications in bio- and chemical sensors														
S-8	SLO-1	Surface engineering by material addition (principle and its application with examples).	Plasma and ion beam assisted surface modification		Micro Arc Oxidation,		Electron Energy Loss Spectroscopy		Surface engineering of polymers														
S-9	SLO-1	Surface modification of steel, non-ferrous and ferrous components: (principle and scope of application).	Surface modification by Ion implantation and Ion beam mixing		Electro Spark Coating		Photoelectron Spectroscopy		Surface engineering of composites														

Learning Resources	1. K.G. Budinski, <i>Surface Engineering for Wear Resistances</i> , Prentice Hall, Englewood Cliffs, 1988. 2. M. Ohring, <i>The Materials Science of Thin Films</i> , Academic Press Inc, 2005 3. D. Satas, Arthur A. Tracton, "Coatings technology handbook", Marcel Dekker, 2000 4. K. Oura, V. G. Lifshits, A. A. Saranin, A. V. Zotov and M. Katayama, "Surface Science – An Introduction" Springer, 2009. 5. B G Miller, "Surface coatings for protection against wear", Wood head Publishing, 1st Edition, 2006 6. Riviere.J.C and Myhra.S, "Handbook of Surface and Interface analysis", CRC Press, 2009. 7. Hari Singh Nalwa, "Nanostructured Materials and Nanotechnology", Academic Press, 2002.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Understand	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. O P Khatri, CSIR-Indian Institute of Petroleum, Dehradun – 248005 (India)- 400701 opkhatri@iip.res.in	1. Dr. P Ramkumar, IIT Madras, ramkumar@iitm.ac.in	Dr. Jitendra Kumar Katiyar, SRMIST jitendrakumar.v@ktr.srmuniv.ac.in
2. Dr. Prasanta Kumar Padhi, Deputy General Manager, SAIL Raurkela, Odisha – 769011 prasantakumar.padhi@sailrsp.co.in	2. Dr. T V K Gupta, VNIT Nagpur, tvkgupta@mec.vnit.ac.in	Dr. T V V L N Rao, SRMIST narasimharao.t@ktr.srmuniv.ac.in

Course Code	18MEE425T	Course Name	SUPPLY CHAIN MANAGEMENT	Course Category	E	Professional Elective	L 3	T 0	P 0	C 3
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Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Understand the role of logistics	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Understand the phases of supply chain	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Understand the evolution of supply chain models	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Understand the supply chain activities	Expected Attainment (%)	Design & Development
CLR-5 :	Understand the SCM organization and information system		Analysis, Design, Research
CLR-6 :	Understand the role, phases, evolution, activities and SCM information system		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3

Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3	
CLO-1 :	Familiar in Logistics and its role of operations.	1 2&3	90	85	H	L				M	M	L											
CLO-2 :	Familiar in Supply chain and its different phases.	1 2&3	90	85	H	L				M	L	L											
CLO-3 :	Familiar in evolution of supply chain models and solution for engineering problem	1 2&3	90	85	H	L				M	L	L											
CLO-4 :	Familiar with the activities of supply chain	1 2&3	90	85	H	L				M	L	L											
CLO-5 :	Familiar in Understanding different SCM organization and different ERP systems	1 2&3	90	85	H	L				M		M											
CLO-6 :	Familiar in logistics operations, SCM phases, SCM models, SCM activities, SCM organization and different ERP systems	1 2&3	90	85	H	L				M		M											

	Introduction to Logistics	Phases of Supply Chain	Evolution of Supply Chain Models	Supply Chain Activities	Scm Organisation and Information System
Duration (hour)	09	09	09	09	09
S-1	SLO-1	Introduction of Logistics and its concepts	The new paradigm shift	Strategy of supply chain	Introduction of Structuring the supply chain
S-2	SLO-1	Logistics definitions	The modular company	structure of supply chain	Supply chain challenge – five tasks for management
S-3	SLO-1	Different Logistics approaches	Introduction to strategic core, network structures, management networks and vertical integration	Factors of supply chain	Supply Chain as activity systems
S-4	SLO-1	Factors influencing logistics	The network relations in supply chain	Manufacturing strategy stages	New products of supply chain
S-5	SLO-1	Basic tasks of supply chain	Supplier relationship, partnerships and alliances, cooperation and integration, Governance, boundary management, global networks	Supply chain progress	Foundation for supply chain change
S-6	SLO-1	Defection of supply chain	Supply processes in supply chain	Introduction of Model for competing through supply chain management	Functional roles in supply chain change
S-7	SLO-1	Approaches of supply chain	Process flow, product design, product issues, product structure, logistics issue	PLC grid in supply chain management	Frame work Design for supply chain
S-8	SLO-1	Influencing supply chain	Procurement processes in supply chain	Redesigning of supply chain	Institutionalizing supply chain changes
S-9	SLO-1	A new corporate model.	Distribution management in supply chain	linking supply chain with customer	Collaborative product commerce
					ERP software's

Learning Resources	1. Shari, P. B. and Lassen, T. S., <i>Managing the global supply chain</i> , Viva books, New Delhi, 2000. 2. Ayers, J. B., <i>Hand book of supply chain management</i> , The St. Lencie press, 2000. 1. 3. Nicolas, J. N., <i>Competitive manufacturing management – continuous improvement, Lean production, customer focused quality</i> , McGrawHill, New York, 1998. 4. Steudel, H. J. and Desruelle, P., <i>Manufacturing in the nineteen – How to become a mean, lean and world class competitor</i> , Van No strand Reinhold, New York, 1992.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. R. Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in, rkpearls@yahoo.com	1. Dr.M. K. Marichelvam, Mepco Schlenk Engineering College, Sivakasi.	1. Mr.M. Sachidhanandham Asst. Professor, ME SRM Institute of Science and Technology, Kattankulathur,
2. Dr. A. Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	2.Mr.A.Prabukarthi A, PSG College of Technology Coimbatore-641004	Dr. M. Iqbal, SRMIST

Course Code	18MEE426T	Course Name	COMPOSITE MATERIALS AND MECHANICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Understand the overview, constituents, classifications, and advanced applications of composites	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Understand the mechanics and performance of composite materials		
CLR-3 :	Understand the manufacturing techniques and inspection of various composite materials		
CLR-4 :	Learn to test and understand the failure, and analysis methods of laminated composites and their constituents and analyze the characteristics of laminated composites		
CLR-5 :	Learn design aspects and acquiring knowledge on material selection for advanced engineering composite materials.		
CLR-6 :	Understand the applications, performance, inspection of composites		

Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Familiar with the Overview, constituents, classifications, and advanced applications of composites and composites mechanics				1& 2	90	85	H				M										
CLO-2 :	Familiar the mechanics and performance of composite materials				1& 2	90	85	H	H													
CLO-3 :	Familiar with the manufacturing techniques and inspection of various composite materials				1& 2	90	85	H		M	L											
CLO-4 :	Familiar with the testing and understand the failure, and analysis methods of laminated composites and their constituents and analyze the characteristics of laminated composites				1& 2	90	85		M	H		M										
CLO-5 :	Familiar with the Design and select the material for advanced engineering composite materials.				1& 2	90	85	H		H	M	M										
CLO-6 :	Familiar with overview, performance, applications and inspection of composites				1&2	90	85	H		H	M	L										

		Overview of Composites	Mechanics and Performance	Manufacturing	Testing and Analysis	Design and Material selection
Duration (hour)		9	9	9	9	9
S-1	SLO-1 & 2	Introduction to composites - Definitions Classification of composite materials	Introduction to solid mechanics - lamina and laminates	Overview of composite manufacturing processes	Fiber test, Neat resin matrix test Tensile, compressive test In-plane shear, Interlaminar shear tests Flexural, Interlaminar fracture, Fiber/Matrix interface tests	Failure predictions in a Unidirectional Lamina
S-2	SLO-1 & 2	Polymer matrix Ceramic matrix,	Mechanics terminology Interlaminar stresses	Overview of glass fibre production	Analysis of an orthographic lamina	Failure predictions for Unnotched Laminates
S-3	SLO-1 & 2	Metal matrix; Special composites - Functionally graded materials	Unidirectional and angle lamina and laminates	Carbon fiber production	Analysis of an orthographic laminates	Laminated Design Consideration
S-4	SLO-1 & 2	Characteristics of composite materials Mechanical behavior of composite materials	Engineering constants of an angle lamina and laminates	Spray-up, Hand lay-up	Hooke's law, stiffness and compliance matrices	Bonded joints; Bolted joints; Bonded-Bolted joints
S-5	SLO-1 & 2	Structural Materials Constituent materials for composite materials	Static Mechanical Properties Hooke's law for different types of materials	Filament winding Fiber placement	Strengths of orthographic lamina	Design requirements and design failure criteria
S-6	SLO-1 & 2	Matrix materials – types and properties Reinforced materials– types and properties	Effective modulus in stress-strain	Closed-mould processes, Bag Moulding	Stress analysis of laminated composite beams	Design load definitions Design analysis philosophy for composite structures

S-7	SLO-1 & 2	Fibers for advanced composites Current and potential advantages of fiber-reinforced composite materials	Symmetry in stress-strain	Compression moulding, Pultrusion, and Other manufacturing processes	Stress analysis of laminated composite Plates	Laminate optimization Design examples
S-8	SLO-1 & 2	Applications of composite materials - Military aircraft, Civil aircraft	Fatigue and Impact properties and Environmental effects	Quality Inspection method	Stress analysis of laminated composite Shells	Materials selection criteria Different material section factors
S-9	SLO-1 & 2	- Automotive applications, Commercial applications,	Fracture Behavior and Damage Tolerance	Composite defects, detection and possible solution	Free vibration	- Fiber selection factor - Matrix selection factor - Importance of constituents

Learning Resources	<ol style="list-style-type: none"> 1. P.K. Mallick, FIBRE REINFORCED COMPOSITES: MATERIALS, MANUFACTURING AND DESIGN, Marcel Dekker, 1993. 2. J.C. Halpin, PRIMER ON COMPOSITE MATERIALS, ANALYSIS, Techomic Publishing Co., 1984. 3. B.D. Agarwal, and L.J. Broutman, ANALYSIS AND PERFORMANCE OF FIBRE COMPOSITES, John Wiley and Sons, New York, 1990. 4. P.K. Mallick and S. Newman, (eds), COMPOSITE MATERIALS TECHNOLOGY: PROCESSES AND PROPERTIES, Hansen Publisher, Munich, 1990. 5. R.P.L. Nijssen, COMPOSITE MATERIALS AN INTRODUCTION, A VKCN publication, 1st Edition, 2015. 6. Robert M. Jones, MECHANICS OF COMPOSITE MATERIALS, 2nd Edition, Taylor & Francis, 1999. 7. Ronald F. Gibson, PRINCIPLE OF COMPOSITES MATERIAL MECHANICS, McGraw Hill, 1994. 8. Autar K. Kaw, MECHANICS OF COMPOSITE MATERIALS, 2nd Edition, Taylor & Francis, 2006. 9. Valery V. Vasiliev and Evgeny V. Morozov, ADVANCED MECHANICS OF COMPOSITE MATERIALS AND STRUCTURAL ELEMENTS, 3rd Edition, Elsevier, 2013. 10. Madhujit Mukhopadhyay, Mechanics of Composite Materials and Structures, University Press, 2018. 11. Reddy J. N., Mechanics of Laminated Composites Plates and Shells, CRC Press, 2016. 12. Bhagwan D. Agarwal, Analysis and Performance of Fiber, Wiley India, 2015. 13. Balasubramaniam, Composite Materials, John Wiley & Sons, Indian Ed., 2013. 14. K.K. Chawla, Composite Materials, Springer, 2012.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
<p>1. Mr. Asit Ghanti Assistant General Manager Vedanta Electrosteel Steel Ltd. Tel: +91-8651037058 Email: asit.ghanti@vedanta.co.in</p>	<p>1 Dr. Mamilla Ravi Sankar Assistant Professor, ME IIT Tirupati Tel: +91-877 2503410 Email: evmrts@iittp.ac.in</p>	<p>1. Dr. Shubhabrata Datta Research Professor, ME SRM Institute of Science and Technology, Kattankulathur, H/P: +91-9477485253 Email: shubhabrata.p@ktr.srmuniv.ac.in</p>
<p>Dr. A. Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in</p>	<p>2. Dr.N.Arunachalam, IIT Madras, chalam@iitm.ac.in</p>	<p>2 Dr. Sumit PRAMANIK Research Associate Professor, ME SRM Institute of Science and Technology, Kattankulathur, H/P: +91-8777740422 Email: sumitpramanik.s@ktr.srmuniv.ac.in</p>

Course Code	18MEE427T	Course Name	GLOBAL OPTIMIZATION ALGORITHMS	Course Category	E	Professional Elective	L 3	T 0	P 0	C 3
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Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Be familiar with evolutionary algorithm	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Be familiar with particle genetic algorithm		
CLR-3 :	Be familiar with modern optimization techniques		
CLR-4 :	Be familiar with search algorithms		
CLR-5 :	Be able to apply the knowledge of optimization in mechanical engineering applications		
CLR-6 :	Be familiar with evolutionary algorithm, genetic algorithm, modern optimization techniques, search algorithms and optimization applications		

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Recall the concepts of optimality criteria for various types of optimization problems.	1	90	85	H				M				H	H	M		H	H	M
CLO-2 :	Understand the problems	2	90	85	H	H		H	M	M			M	H	H		H	H	M
CLO-3 :	Apply the methods of optimization to solve real life problems	3	90	85	H	H	H	H	M	M		M	M	M	M		H	H	M
CLO-4 :	Analyze the methodology followed and test the results	4	90	85	H	H	H		H	M		M			M		H	H	M
CLO-5 :	Investigate the results to obtain the optimized solution	5	90	85	H	H			H	M							H	H	M
CLO-6 :	Investigate with evolutionary algorithm, genetic algorithm, modern optimization techniques, search algorithms and optimization applications	1-5	90	85	H	H	H	H	H	M		M	M	M	M		H	H	M

		Global optimization technique	Modern optimization techniques Part I	Modern optimization techniques Part II	Search Methods	Applications of optimization techniques
Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction to Optimization Algorithms	Introduction to Particle Swarm Optimization (PSO)	Introduction to Simulated Annealing algorithm (SAA)	Linear search and binary search	Desirable and undesirable effects, functional requirements such as geometry and materials.
S-2	SLO-1	The Structure of Optimization - Formulae and Search Space/Operator Design	Theoretical derivatives in particle swarm optimization, Variants of PSO	Asymptotic convergence and typical behavior of SAA, Multi objective SA	Jump search, interpolation search	Stochastic optimization
S-3	SLO-1	Evolutionary algorithms, ranking selection, VEGA, Convergence prevention	Performance Enhancing techniques in PSO, Applications of PSO	External optimization, Tabu Search, Memetic and Hybrid algorithms	Exponential search, Fibonacci search	Integrating simulation in optimization models
S-4	SLO-1	Optimization problems in engineering, Inverse problems; Scheduling and Routing	Introduction to Ant colony optimization (ACO), Framework of ACO	Downhill simplex , Applications of SAA	Golden selection, Random, pattern and gradient search methods	Multi-Disciplinary Optimization in enhancing the features of an automobile.
S-5	SLO-1	Data Mining, Intelligent System designing, Introduction to Genetic Algorithm, Operators of GA's, Differences and similarities between genetic algorithms and traditional techniques	Hill Climbing, Multi-Objective Hill Climbing	Introduction to Differential Evolution (DE)	State Space Search, Uninformed Search	Optimization for modular design.
S-6	SLO-1	Introduction to utilization of computer programs in GA, Schema Algorithm, Advanced operators and techniques in genetic search	Problems in Hill Climbing, Hill Climbing with Random Restarts	Structure of Differential algorithm (DA)	Breadth-First Search, Depth-First Search	Optimization of design parameters to design a mechanical component.
S-7	SLO-1	Genetic algorithm and machine learning, Introduction to multi objective	GRASP, Raindrop Method, Random Optimization	Computing environments in DE	Depth-limited Search, Iterative Deepening Depth	Optimization of process parameters in machining operations.

		optimization, Types of multi objective problems and principles				
S-8	SLO-1	Pareto optimality, Non-Elitist multi objective algorithms, Elitist multi objective algorithms	Monte Carlo methods	Applications of DA	Informed Search - Greedy Search- A* search - Adaptive Walks, Tree search,	Optimization in minimizing cost and enhancing strength mechanical elements
S-9	SLO-1	Constrained multi objective algorithm, Usage of multi objective optimization in various optimization techniques	Multi disciplinary optimization methods and their applications in engineering.	Optimization with parameter uncertainties – Robust Optimisation, formulation, algorithms, applications	Interpolation methods: quadratic and cubic, direct root method.	Optimization problems on scheduling.

Learning Resources	<ol style="list-style-type: none"> 1. Kalyanmoy Deb, "Optimization for Engineering design-Algorithms and Examples", Prentice Hall, India, 2012. 2. Kalyanmoy Deb, "Multi objective optimization using Evolutionary algorithms", John Wiley, 2001. 3. Joshua Knowles, David Corne, Kalyanmoy Deb "Multiobjective Problem Solving from Nature: From Concepts to Applications", Springer- 2008. 4. Thomas Weise, "Global Optimization Algorithms – Theory and Application", Thomas Weise, 2009. 5. S.S Rao, "Optimization – Theory and Applications", Wiley Eastern, New Delhi, 2009 6. Parsopoulos K and Vrahatis M.N, " Particle Swarm Optimization and Intelligence:Advances and Applications", IGI Global, 2010. 					
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Dr. Chiradeep Ghosh, Principal Scientist, TATA Steel. Chiradeep.ghosh@tatasteel.com	1. Dr. P. Hariharan, Anna University, hari@annauniv.edu, hariharan2311@gmail.com	Shubrajit Bhaumik, SRMIST
Dr. A. Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	2. Dr.N.Arunachalam, IIT Madras, chalam@iitm.ac.in	Dr. Shubhabrata Datta, SRMIST

Course Code	18MEE428T	Course Name	SIMULATION OF MECHANICAL SYSTEMS	Course Category	E	Professional Elective	L 3	T 0	P 0	C 3
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Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Be familiar with the function of physical system	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Be familiar with the models use in need for simulation	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	understand about different methods of simulation	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Be familiar with translational simulation	Expected Attainment (%)	Design & Development
CLR-5 :	Be familiar with rotational mechanical systems		Analysis, Design, Research
CLR-6 :	Be familiar with simulation of hydraulic and manufacturing system		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Recognize and analyze the use of different methods of simulation	1&2 90 85	H M M M L
CLO-2 :	Acquire knowledge on basic components and working of various mechanical systems	1 90 85	H M H M L
CLO-3 :	Recognize the application of Random variables and their properties, estimation of means, variance and correlation	1 90 85	H H M M M
CLO-4 :	Understand the Static and dynamic modeling	1&2 90 85	H M M M
CLO-5 :	Recognize the Numerical computation techniques based upon the application	1&2 90 85	H M M H H
CLO-6 :	Simulation of rotational systems and translational system as well as the hydraulic system	1 90 85	H M L L M

		Introduction	Types and principles of modeling	Methods of simulation	simulation of translational and Rotational systems	Simulation of hydraulic systems and manufacturing system
Duration (hour)		09	09	09	09	09
S-1	SLO-1	Need for modeling and simulation in mechanical systems	Static modeling with examples	Monte Carlo simulation	Building of simulation models in mechanical systems	Simulation of hydraulic systems
S-2	SLO-1	Basics of modeling of physical systems	dynamic modeling with examples	Experimental nature of simulation	Simulation of translational systems	hydraulic systems with real time examples
S-3	SLO-1	methods of modeling	Stochastic models with examples	Numerical computation techniques	Case studies – Translatory motion for Serial Manipulator	Simulation of material handling systems in manufacturing
S-4	SLO-1	Review of basic probability and statistics	Principles of modeling	Analog system models	Simulation of rotational systems	Case studies –Automated guided vehicle (AGV) in Goods Transportation
S-5	SLO-1	Random variables and their properties, estimation of means, variance and correlation	Study and evaluation of model	hybrid system models	real time examples	Simulation in flexible manufacturing
S-6	SLO-1	Concept of system and environment, continues and discrete systems	Continues system models	Continues system models	Transform Function Analysis. Developing a Linear Model	Case studies- vice casting product
S-7	SLO-1	Linear systems	Introduction to simulation, basic simulation, advantages of simulation	Role of computers in simulation	Case studies – Rotary Joint Link for SCARA ROBOT	Simulation of waiting line system
S-8	SLO-1	nonlinear systems	Role of simulation in model evaluation with examples	introduction to simulation software packages	Techniques for variance reduction	waiting line system in manufacturing with examples

Learning Resources	<ol style="list-style-type: none"> 1. Dym C.L., "Principles of Mathematical Modeling", Elsevier, 2nd Edition 2004. 2. Geoffrey Gordon, "System Simulation" Phi Learning, 2nd Edition 2002 3. M. Close and Dean K. Frederick, "Modeling and Analysis of Dynamic Systems", Houghton Mifflin, 3rd Edition, 2002 4. Guy L. Richard M. Feldman, "Manufacturing Systems Modeling and Analysis", Springer, 2011. 5. Performance Modeling of Automated Manufacturing Systems (Prentice Hall Information and System Sciences Series) 1st Edition Edition, 1992 6. J. Schwarzenbach and K.F. Gill, "System Modeling and Control".Halsted Press, New York, 1992 7. Robert E. Shannon, "System Simulation: The Art and Science", Prentice Hall, 1975 8. Automation, Production Systems, and Computer-Integrated Manufacturing 4 Edition (English, Paperback, Mikell P. Groover), 2016
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

SLO – Session Learning Outcome

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. S.Bhargav, GM,Rane Brake, Trichy	1. Dr. V.Srinivasan, Annamalai University, srinivraghavan@yahoo.com	1. Dr. M. Prakash, SRMIST
2. Dr. Muthumanikkam, Jt. Director, CVRDE, DRDO,Avadi, Chennai.	2.Dr.Ashok Kumar, Govn. Col.of. Eng, Bargur, Krishnagiri, Tamil Nadu Akrt02au@gmail.com	2. Dr.A.Arul Jeya Kumar, SRMIST

Course Code	18MEE429T	Course Name	INDUSTRY 4.0	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Understand the Architectural Overview of Internet of Things	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Be familiar with the concepts of big data analytics	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Learn the basics of cloud computing	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Be familiar with method and new frameworks of information security management.	Expected Attainment (%)	Design & Development
CLR-5 :	understand the fundamentals concepts of digital manufacturing		Analysis, Design, Research
CLR-6 :	Understand the concepts of Internet of things, big data analysis, cloud computing, cyber security and digital manufacturing		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Recognize and analyze the use of different methods of simulation	1&2 90 85	H M M M L
CLO-2 :	Acquire knowledge on basic components and working of various mechanical systems	1 90 85	H M H M L
CLO-3 :	Recognize the application of Random variables and their properties, estimation of means, variance and correlation	1 90 85	H H M M M
CLO-4 :	Understand the Static and dynamic modeling	1&2 90 85	H M M M
CLO-5 :	Recognize the Numerical computation techniques based upon the application	1&2 90 85	H M M H H
CLO-6 :	Simulation of rotational systems and translational system as well as the hydraulic system	1 90 85	H M L L M

Duration (hour)	9	9	9	9	9
S-1	IoT-An Architectural Overview	Big Data Platforms for the Internet of Things	Introduction to the Cloud Computing	Myths Of Information Security Mana	Introduction To Digital Manufacturing
S-2	Building an architecture	Network protocol	History of cloud computing	The big picture	Features and development of digital manufacturing
S-3	Main design principles and needed capabilities	Data dissemination –current state of art	Cloud service options	Learning from experience	Theory system of digital manufacturing science
S-4	An IoT architecture outline, standards considerations	Improving Data and Service Interoperability with Structure	Cloud Deployment models	Weaknesses in Information Security	Operation Mode
S-5	M2M and IoT Technology Fundamentals	Compliance, Conformance	Business concerns in the cloud,Cloud Orchestration	The extent of crime in cyberspace	Architecture of Digital Manufacturing System
S-6	Devices and gateways, Local and wide area networking	Context Awareness	Exploring virtualization, Load balancing	The cyberspace crimoid syndrome	Additive Manufacturing - overview, Techniques.
S-7	Data management, Business processes in IoT	interoperability problem in the IoT context	Hypervisors, Machine imaging,	Policies and technologies	
S-8	Everything as a Service (XaaS)	Big Data Management Systems for the Exploitation of Pervasive Environment	Cloud marketplace overview	A new framework for information security.	
S-9	M2M and IoT Analytics, Knowledge Management.	Big Data challenges and requirements coming from different Smart City applications.	Comparison of Cloud providers.		

Learning Resources	<ol style="list-style-type: none"> 1. Vijay Madiseti and Arshdeep Bahga, "Internet of Things (A Hands-on-Approach)", 1st Edition, VPT, 2014. 2. Bernd Scholz-Reiter, Florian Michahelles, "Architecting the Internet of Things", ISBN 978-3-642-19156-5 e-ISBN 978-3-642-19157-2, Springer 3. Stackowiak, R., Licht, A., Mantha, V., Nagode, L., "Big Data and The Internet of Things Enterprise Information Architecture for A New Age", Apress, 2015 4. Cloud Computing: Principles and Paradigms by Rajkumar Buyya, James Broberg and Andrzej M. Goscinski, Wiley, 2011. 5. Zude Zhou, Shane (Shengquan) Xie and Dejun Chen, Fundamentals of Digital Manufacturing Science, Springer-Verlag London Limited, 2012 6. Chua.C.K, "Rapid Prototyping", John Wiley, New York, 1997.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

SLO – Session Learning Outcome

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. R. Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in, rkpearls@yahoo.com	1. Dr. P. Hariharan, Anna University, hari@annauniv.edu, hariharan2311@gmail.com	Dr.U.Mohammed Iqbal
2. Dr. A. Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in 3. Mr.P.Karthikeyan, Head Operations Improvement, Nokia Solutions, Oragadam Kartikeyan.p@nokia.com	2. Dr.N.Arunachalam, IIT Madras, chalam@iitm.ac.in	J.Santhakumar

Course Code	18MEE430T	Course Name	TQM AND RELIABILITY ENGINEERING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Understand the importance of TQM and its concepts, tools and techniques and apply in the real-world environment	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Analyze the role of human involvement to improve the quality of product and service		
CLR-3 :	Understand, apply and evaluate the tools and techniques used for product and service quality		
CLR-4 :	Understand the basic concepts of reliability, apply and evaluate reliability for different systems		
CLR-5 :	Understand and apply the concept of maintainability of a system to evaluate time for different cases		
CLR-6 :	Understand the importance of quality and reliability in every process in the current scenario		

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Recognize the importance of quality in every activity of an organization and in personal life	1,2	80	75	M	M	M	-	M	-	-	M	H	M	-	-	-	-	M
CLO-2 :	Apply the different tools and techniques to solve day to day issues and will seek an opportunity to practice	1,2,3	80	75	M	H	-	-	H	-	-	-	H	M	-	M	-	-	M
CLO-3 :	Think from the customer perspective and will plan for customer retention through total quality management	1,2,3	80	75	M	H	M	-	H	M	-	M	H	H	-	-	-	-	M
CLO-4 :	Develop and test a system for its reliability	1,2	80	75	M	M	M	-	M	-	-	-	-	-	-	-	-	-	M
CLO-5 :	Estimate MTTF, MTTR, MMT and MDT and plan for a maintenance strategy	1,2,3	80	75	M	H	M	-	H	-	-	-	-	-	-	-	-	-	M
CLO-6 :	Recognize the importance of quality in every activity of an organization and in personal life	1,2	80	75	M	M	M	-	M	-	-	M	H	M	-	-	-	-	M

		Evolution, theories and implementation	Principles and 7 QC tools	Management Tools	Reliability	Maintainability
Duration (hour)		9	9	9	9	9
S-1	SLO-1	Evolution of Total Quality Management	Customer Satisfaction – Types of customers, customer supplier chain	Affinity diagram – Relations diagram	Probabilistic nature of failures	Introduction Availability and Maintainability
S-2	SLO-1	Definition of quality, Dimensions of Quality	Customer perception of quality customer feed back	Tree diagram – Matrix diagram – Matrix data analysis diagram	Mean failure rate – Meantime between failures	Types of maintenance strategy
S-3	SLO-1	Deming's theory	Customer complaints – Customer retention – Service quality	Process decision program chart, Arrow diagram	Hazard rate – Hazard models	Mean time– to repair (MTTR)
S-4	SLO-1	Juran and Crosby theories	Employee involvement and motivation – Maslow's hierarchy of needs	5S Principles	Weibull model	Factors contributing to Mean Down Time (MDT)
S-5	SLO-1	Taguchi and Ishikawa theories	Herzberg theory – Empowerment and team work	Quality Function Deployment (QFD)	System reliability improvement	Fault diagnosis, and routine testing for unrevealed faults
S-6	SLO-1	Quality costs, Product quality Vs Service quality	Seven QC tools – Check sheets	Failure mode and effects analysis (FMEA)	Redundancy	Factors contributing to Mean Maintenance Time – (MMT) on condition maintenance
S-7	SLO-1	Goal setting	Histograms, control charts	Root cause analysis, poka-yoke	Series – Parallel and Mixed configurations	Total Productive Maintenance (TPM)
S-8	SLO-1	Strategic Quality planning	Pareto diagram, Cause and effect diagram	Introduction to Six Sigma	Problems in Series – Parallel and Mixed configurations	Periodic condition monitoring, Continuous condition monitoring
S-9	SLO-1	TQM implementation	Stratification, Scatter diagrams	DMAIC	Problems in Series – Parallel and Mixed configurations	Economics of maintenance

Learning Resources	<ol style="list-style-type: none"> 1. M. P. Poonia, S.C. Sharma, "Total Quality Management", Khanna Publishing, 2019. 2. R Kiran, "Total Quality Management: Key Concepts and Case Studies", Elsevier Inc., 2017. 3. Dale H Besterfield, "Total Quality Management", Fourth Edition, Pearson Education Asia, 2015. 4. John Oakland, Peter Morris "TQM – A pictorial guide for managers", Routledge, 2011. 5. Roderick A Munro, Govindarajan Ramu and Daniel J Zrymiak, "The Certified Six Sigma Green Belt Handbook", Second Edition, American Society for Quality, USA, 2015. 6. L S Srinath, "Reliability Engineering", Fourth Edition, Affiliated East West Press, 2008. 7. E Balagurusamy, "Reliability Engineering", Tata McGraw Hill Education, 2010.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
<i>Mr. R. Nanda Kumar</i> Vice Chairman National Institution for Quality and Reliability (NIQR)	1. Dr. P. Hariharan, Anna University, hari@annauniv.edu, hariharan2311@gmail.com	Mr. E. Vijayaragavan, SRM IST
Mr. N. Palani Head – Quality Assurance Rane TRW Steering Systems Limited	2. Dr.N.Arunachalam, IIT Madras, chalam@iitm.ac.in	

Course Code	18MEE431T	Course Name	DESIGN OF JIGS, FIXTURE AND PRESS TOOLS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	DESIGN DATA BOOK		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Explore the various locating and clamping method	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Understand the functions and design principles of Jigs	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Understand the functions and design principles of Fixtures	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Understand the functions and design principles of press work	Expected Attainment (%)	Design & Development
CLR-5 :	Understand the functions and design principles of bending, forming and drawing		Analysis, Design, Research
CLR-6 :	Be Familiar with design of jigs, Fixtures and Press Tools		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Able to design the locator and the clamp for the mechanical component	1&2	80	85	H	M	H	-	-	-	-	-	-	-	-	-	M	-	-
CLO-2 :	Acquire knowledge on different type of jigs and its application	1	80	85	H	M	H	-	-	-	-	-	-	-	-	-	H	-	-
CLO-3 :	Acquire knowledge on different type of fixture and its application	1	80	85	H	M	H	-	-	-	-	-	-	-	-	-	H	-	-
CLO-4 :	Understand the major design principle of press work and element of cutting die	1&2	80	85	H	L	M	-	-	-	-	-	-	-	-	-	-	-	-
CLO-5 :	Understand the functions and design principles of bending, forming and drawing	1&2	80	85	H	-	M	-	-	-	-	-	-	-	-	-	-	-	-
CLO-6 :	Understand the functions and design principles of locator and clamping of jigs and fixtures, use of press tools in bending, forming and drawing operations	1&2	80	85	H	H	M	-	-	-	-	-	-	-	-	-	-	-	-

		Locating and Clamping Principles	Design of Jigs	Design of Fixtures	Press Working Terminologies and Element of Cutting Dies	Bending, Forming and Drawing Dies
Duration (hour)		9	9	9	9	9
S-1	SLO-1	Objective of tool design, Function, features and advantages of jigs and fixture.	Types of jigs – Template and Plate Jigs	Introduction to fixture, type of fixtures	Press working terminology, types of presses	Types of Bending dies, press capacity
S-2	SLO-1	Locating Principle, Locating methods and devices,	Channel, Pot, Turnover, Box and Post Jig	Design Principles of milling fixture	Press accessories and press working operation.	Spring back, knockout, direct and indirect, pressure pads, ejectors
S-3	SLO-1	Pin and Button locator, Rest pads and plates, Diamond pin locator	Indexing Jigs	Lathe fixture	Shearing action, clearances, press work materials.	Variables affecting metal flow in drawing operation
S-4	SLO-1	Clamping Principles, types of clamps, mechanical actuation clamps	Drill Bushes and Jig Buttons	Design Principles of boring fixture, and Broaching Fixture	Center of pressure, design of various elements of dies	Draw die insert, draw beads, ironing
S-5	SLO-1	Pneumatic actuation clamping	method of construction of drill jigs	Design Principles of Grinding Fixture	Accessories of blanking dies – punch, punch holder, die set, stripper, pilots	Design and development of bending and forming
S-6	SLO-1	Hydraulic actuation clamping	General consideration in the design of Drill jigs	Assembly, Inspection and welding fixtures		Drawing reverse re-drawing and combination die
S-7	SLO-1	Vacuum and magnetic clamping	Drill jigs and modern manufacturing	Modular fixturing system,	Selection of standard parts	Blank development for axisymmetric, rectangular and elliptic parts, single and double action dies
S-8	SLO-1	Standard parts in jigs and fixtures	Design and development of jigs and for given component 1	Design and development of fixtures and for given component 1	Design and preparation of four standard views of simple blanking and piercing die	Bulging, swaging, Embossing, coining, curling
S-9	SLO-1	Limits, fits, Tolerances and types of tolerances			Shaving, notching, compound and progressive dies	Hole flanging, shaving, and sizing, assembly, fine blanking dies

Learning Resources	<ol style="list-style-type: none"> 1. Donaldson, Lecain and Goold "Tool Design " , 3rd edition Tata McGraw hill ,2007 2. Joshi, P.H. "Jigs and Fixtures" second edition, Tata McGraw hill publishing co., ltd., New delhi,2004 3. K.Venkataraman, "Design of Jigs Fixtures and Press tool", Tata McGraw hill New delhi,2005 4. Kempster, "jigs and fixtures design" Hoddes and Stoughton – third edition 1974 5. Joshi, P.H "Press tool – Design and Construction", S.Chand &company, 2010. 6. Hoffman "Jigs and Fixtures Design" – Thomson Delmar learning, Singapore, 2004. 7. ASTME fundamentals of tool design prentice hall of India. 8. P.S.G tech..., "design data book", kalaikathir Achchagam, 2012.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. R. Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in, rkpearls@yahoo.com	1. Dr. P. Hariharan, Anna University, hari@annauniv.edu, hariharan2311@gmail.com	1. Kolli Balasivarama Reddy Asst. Professor, ME SRM Institute of Science and Technology, Kattankulathur,
2. Dr. A. Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	2.Dr.N.Arunachalam, IIT Madras, chalam@iitm.ac.in	

Course Code	18MEE341T	Course Name	REFRIGERATION AND AIR CONDITIONING SYSTEMS				Course Category	E	Professional Elective		L 3	T 0	P 0	C 3													
Pre-requisite Courses	18MEC107T		Co-requisite Courses		NIL			Progressive Courses		NIL																	
Course Offering Department		Mechanical Engineering				Data Book / Codes/Standards		Refrigerant and Psychrometric Properties Tables &Charts/M.L.Mathur &F.S.Mehta																			
Course Learning Rationale (CLR):		The purpose of learning this course is to:						Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Be familiar with vapour compression system						Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	Design & Development	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Be familiar with the refrigeration cycles and methods for improving Performance																										
CLR-3 :	Understand the working of components of refrigeration systems.																										
CLR-4 :	Be familiar with design of air conditioning systems																										
CLR-5 :	Be familiar with air conditioning systems for various applications.																										
CLR-6 :	Be familiar with refrigeration and air conditioning system s																										
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																									
CLO-1 :	Recognize and analyze the vapour compression systems						1&2	90	80	H	H		M					H								H	
CLO-2 :	Acquire knowledge on refrigeration cycles and methods for improving Performance						1,2,3	90	80	H	M		M				L									H	
CLO-3 :	Understand the working of refrigeration systems.						1,2	90	80	H							H									H	
CLO-4 :	Analyze and design ofair conditioning systems.						1,2,3	90	80	H	H	H	M				M									H	
CLO-5 :	Appreciate the need and applications of air conditioning systems.						1&2	90	80	H							L									H	
CLO-6 :	Understand and analyze the refrigeration and air conditioning system s						1&2	90	80	H	M		M				H									H	
		Vapour Compression Refrigeration Systems		Absorption Refrigeration Systems		Refrigeration Equipment's & Contro		Design of Air Conditioning Systems		Applications of Refrigeration And Air Conditioning Systems																	
Duration (hour)		9		9		9		9		9																	
S-1	SLO1	Review of thermodynamic principles of refrigeration		Ideal vapour absorption refrigeration system		Construction features of reciprocating compressors, Rotary and screw compressors		Different heat sources-sensible heat load, Latent heat load		Preservation of different products																	
S-2	SLO1	Simple vapour compression refrigeration system		Absorbent refrigerant combination - Properties of refrigerant absorbent pair		Type of Condenser, heat transfer in condensers		Heating and Cooling Load - Occupants load, equipment load, fresh air load, infiltration air load		Construction and working of Ice factory																	
S-3	SLO1	Problem on COP of VCR system		Vapour absorption refrigeration system based on Water-lithium bromide.		Types of cooling towers- Construction features of Natural, Mechanical draft.		Design of air conditioning system-cooling load and air quantities		The heating and cooling requirements for different dairy products and processes in Dairy plant																	
S-4	SLO1	Methods to improve the COP of VCR system		Problems based on Water - lithium bromide systems		Type of Evaporators-working of dry expansion and flooded evaporator.		Bypass factor(BPF) of heating and cooling coil, Effective sensible heat factor(ESHF)		Application of non-conventional refrigeration method in vortex and pulse tube refrigeration. system																	
S-5	SLO1	Multiple evaporator and compressor system		Vapour absorption refrigeration system based on Aqua Ammonia		Working of automatic (or) constant pressure expansion valve and thermostatic expansion valve		Room sensible heat factor(RSHF).Grand sensible heat factor		Application of non-conventional refrigeration method in Solar Refrigeration system																	
S-6	SLO1	Cascade system		Problems based on Aqua -Ammonia Systems		Properties of refrigerants		Factors affecting Human comfort		Application of air conditioning in hotels and restaurants																	
S-7	SLO1	COP comparison with sub cooling and super heating		Single effect absorption refrigeration system		Selection of refrigerants-alternate refrigerants		Problems on –RSHF, and GSHF		Application of air conditioning in theatres																	
S-8	SLO1	Problems based on sub cooling		Comparison of vapour compression refrigeration system versus vapour absorption refrigeration system		thermostatic control-operating and safety controls		Problems on design of air conditioning system		Application of air conditioning in auditorium and hospitals																	
S-9	SLO1	Problems based on super heating		Advantage and disadvantage of vapour absorption system		Refrigerant charging procedure, methods for measuring a Refrigerant Charge		Cooling coils and dehumidifier, air washers		Cryogenics-low temperature applications																	

Learning Resources	3. Arora, S. C. and Domkundwar, S., A course in Refrigeration and Air conditioning, DhanpatRai (P) Ltd., New Delhi, 2012 4. Ananthanarayanan.P.N, "Basic Refrigeration and Air Conditioning" ,Tata McGraw Hill ,3 rd Edition,New Delhi,2006 5. Manohar Prasad, Refrigeration and A 6. Air conditioning, New Age International (P) Ltd, New Delhi, 2010 7. Roy J. Dossat, Principles of Refrigeration, Pearson Education Asia, 4th edition, 2001 8. Arora, C. P., Refrigeration and Air Conditioning, Tata McGraw Hill, New Delhi, 2006 9. Andrew D. Althouse,Modern Refrigeration and Air Conditioning,Goodheart-Willcox Company, Incorporated, 2016 10. G F Hundy Refrigeration, Air conditioning and heat pumps, McGraw-Hill Book company(UK) Ltd, fifth edition 2016 11. S.N.Sapali,Refrigeration and Air conditioning ,published by asoke K.Ghosh,PHI Learning Private Limited, Second edition 2014 12. MI Mathur Fs Mehta, Refrigerant & Psychrometric Properties Tables & Charts,Published by Jain Brothers,2010
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

SLO – Session Learning Outcome

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. R. Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in, rkpearls@yahoo.com	Dr P.Balachander Assistant Professor Thermal Sciences Block Refrigeration & Air Conditioning Department of Mechanical Engineering, College of Engineering, Guindy campus, Anna University, Chennai-600025 Email:p_balachander@annauniv.edu	Mr.J.Thavamani Assistant Professor, Department of Mechanical Engineering SRM IST Email: thavamani.j@ktr.srmuniv.ac.in
2. Dr. A. Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	Mr. K. LAKSHMIKANTH M.E (Refrigeration and Air conditioning system) MANAGER Frick India Limited Seshadri Puram, Bangalore - 560020 Email:bng@frickmail.com	Mr. D. kathirkaman Assistant Professor Department of Mechanical Engineering SRM IST Email: kathirkaman.d@ktr.srmuniv.ac.in

Course Code	18MEE342T	Course Name	INTERNAL COMBUSTION ENGINES				Course Category	E	Professional Elective				L	T	P	C										
													3	0	0	3										
Pre-requisite Courses		18MEC101T,18MEC102T				Co-requisite Courses	NIL				Progressive Courses		NIL													
Course Offering Department		Mechanical Engineering				Data Book / Codes/Standards				NIL																
Course Learning Rationale (CLR):		The purpose of learning this course is to:						Learning			Program Learning Outcomes (PLO)															
CLR-1 :	familiarizewith the I.C.enginebasics, analyze the ideal cycles and performance characteristics						Level of Thinking (Bloom)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLR-2 :	Study about carburetors, fuel injection systems, ignition, lubrication and cooling systems.										Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3	
CLR-3 :	Understand the combustion in S.I. engines, combustion chambers and knocking phenomena										H	H	H	H	L	L	M							M	H	M
CLR-4 :	Understand the combustion in C.I. engine, diesel combustion chambers and abnormal combustion;										H	H	M	M	M	L	M							M	H	M
CLR-5 :	Study about the emissions from the I.C. engines, alternative fuels and new combustion concepts										H	H	M	H	M	L	M							M	H	M
CLR-6 :	Understand the design principles of I.C. engines										H	M	M	H	H	M	H							M	H	M
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:						1,2&3	90	80	H	H	M	M	M	L	M						M	H	M	
CLO-1 :	Performance calculations of I.C. engines, Interpret the ideal and fuel-air cycles; performance maps						1&2	90	80	H	H	H	M	M	L	M							M	H	M	
CLO-2 :	Evaluate the functioning of various auxiliary systems						1&2	90	80	H	H	M	M	M	L	M							M	H	M	
CLO-3 :	Analyze SI engine combustion, knocking and the design principles of combustion chamber.						1&2	90	80	H	H	M	H	M	L	M							M	H	M	
CLO-4 :	Analyze CI engine combustion, design principles of combustion chamber and abnormal combustion						1&2	90	80	H	H	M	H	M	L	M							M	H	M	
CLO-5 :	Recognize the need for reducing the emission from I.C. engines, and alternate fuels						1&2	90	80	H	M	M	H	H	M	H							M	H	M	
CLO-6 :	Evaluate the performance, combustion and emissions of I.C. engines from thermodynamic principles						1,2&3	90	80	H	H	M	M	M	M	H							M	H	M	
		Performance of I.C. Engines		Engine Auxiliary systems		Combustion in S.I. Engines		Combustion in C.I. Engines		Emissions and Alternative fuels																
Duration (hour)		9		9		9		9		9																
S-1	SLO-1	Engine operating cycle, terminology and components, four stroke and two stroke engines and their comparison		Carburation, mixture requirements at different loads and speeds, simple carburetor		Combustion in spark ignition engines, Stages of combustion in SI engine, flame front propagation		Combustion in Compression Ignition engines, Stages of combustion in CI engines,		Air pollution due to IC engines, Emissions standards, hydrocarbon and CO emissions,																
S-2	SLO-1	Operation of SI and CI engines, their p-v diagrams and comparison, classifications and applications IC engines,		Problems on simple carburetor		Analysis of cylinder pressure data		Analysis of cylinder pressure data and heat-release analysis		Oxides of nitrogen and soot, aldehydes, sulphur, lead and phosphorus emissions																
S-3	SLO-1	Volumetric efficiency, and its variation with respect to engine speed, supercharging and turbocharging of engines		Functional requirements and classification of an injection systems, injection pump		Factors influencing the flame speed,		Factors affecting the delay period		Exhaust gas recirculation and catalytic converter																
S-4	SLO-1	First law applied to engine, thermal, mechanical efficiencies, pumping work, mean effective pressure		Nozzle types, EFI systems: MPFI, PFI, GDI		Rate of pressure riseAbnormal combustion, knocking in SI engines,		Basics of fuel sprays: Fuel flow rate through injector nozzle, Overall spray structure		Basics of selective catalyst reduction, diesel particulate filter																
S-5	SLO-1	Engine parameter measurements.		Functional requirements of ignition systems, Battery ignition system		Effect of engine variables on engine knock		Atomization and spray penetration		Flame ionization detector, non-dispersive infrared detector																
S-6	SLO-1	Problems on engine performance.		magneto ignition system, Ignition timing and engine parameters		Combustion chambers for SI engines		Phenomenon of knock in CI engines, comparison of knock in CI and SI engine		Chemiluminescence analyzer, smoke types, Bosch smoke meter																
S-7	SLO-1	Concept of heat balance and problems		Functional requirements of lubrication system, properties of lubricants, mist lubrication system		Smooth engine operation, High power output and thermal efficiency		Combustion chambers for CI engine: Direct injection engines		Fuels for IC engines: Liquid fuels: Alcohol, methanol, ethanol, vegetable oil																
S-8	SLO-1	Review of ideal cycles and fuel-air cycles significance		Wet and dry sump lubrication system		Concept of hybrid electric drive trains		Gasoline Direct Injection (GDI) Engines: Direct injection Vs port injection, classification of GDI eninges		Bio diesel advantages and disadvantages; Gaseous fuels: CNG, LPG, Hydrogen																
S-9	SLO-1	Engine performance characteristics		Liquid and air cooling systems, properties of the coolant and antifreeze solutions		Architectures of hybrid electric drive trains		Spray, wall and air guided combustion systems for GDI engines		Advanced concepts: Stratified charge and HCCI engines																

Learning Resources	<ol style="list-style-type: none"> 1. Ganesan. V, "Internal Combustion Engines", Tata McGraw-Hill, New Delhi, 2015 2. Heywood, J.B., "Internal Combustion Engine Fundamentals", McGraw-Hill International, New York, 2017 3. Ramalingam, K.K., "Internal Combustion Engines-Theory and Practice", SciTech Publications India Pvt Ltd, Chennai 2016. 4. Thipse, S.S., "Internal Combustion Engines", Jaico Publication House, 2010. 5. Sharma, M.L., and Mathur R.P., "A Course in Internal Combustion Engines" DhanpantRai& Sons, New Delhi, 2014. 6. Fuquan Zhao, David L.Harrington and Ming-Chia D. Lai, "Automotive Gasoline Direct-Injection Systems", SAE International Publisher, 2002 7. Mehrdad Ehsani, Yimin Gao, Stefano Longo and Kambiz Ebrahimi "Modern Electric, Hybrid Electric and Fuel Cell Vehicles", CRC Press, 2018
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

SLO – Session Learning Outcome

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
K. SaratChander Prasad, Sr. Lead Engineer, Mahindra & Mahindra Pvt Ltd	Dr. ShamitBakshi, Professor, Indian Institute of Technology Madras	Dr. D. Siva Krishna Reddy, Assistant Professor, SRM IST
Ramesh K.J., Kistler, Product Manager, Instruments India Pvt Ltd	Dr. Maha Lakshmi, Professor, Anna University	Dr. G. Balaji, Associate Professor, SRM IST

Course Code	18MEE343T	Course Name	ELEMENTS OF SPACE TECHNOLOGY				Course Category	E	Professional Elective				L	T	P	C
												3	0	0	3	

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses				NIL					
Course Offering Department		Mechanical Engineering				Data Book / Codes/Standards				NIL			

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :		Develop a basic knowledge on earth's atmosphere.			Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :		Learn the different orbit bodies. & Understand the aspects of satellite injection.																						
CLR-3 :		Know the interplanetary and missile trajectories and materials for Spacecraft.																						
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1 :		Develop a basic knowledge on earth's atmosphere.			1&2	100	95	H																
CLO-2 :		Learn the different orbit bodies. & Understand the aspects of satellite injection.			1	100	95	H	H			H												
CLO-3 :		Know the interplanetary and missile trajectories and materials for Spacecraft.			1	100	95	H				H												

Duration (hour)		9	9	9	9	9	
S-1	SLO-1	The solar system	The Many body problem – Lagrange, Jacobi identity	General aspects of satellite injections	The	Two-dimensional interplanetary trajectories	Introduction to Hypersonic Aerodynamics, thin shock layers, Entropy layer, Viscous interaction, High temperature flow, Low density flow.
S-2	SLO-1	Reference frames and coordinate systems	The circular restricted three body problem	Launch Phase, The Orbit Injection Phase		Fast interplanetary trajectories	High temperature gas dynamics- Importance of high temperature flows.
S-3	SLO-1	Motion in Acceleration Reference Frames	Libration points	Satellite orbit transfer - Various cases		Three dimensional interplanetary trajectories	Atmospheric entry of blunt nosed body.
S-4	SLO-1	The celestial sphere	Relative Motion in the N-body problem	Orbit deviations due to injection errors		Launch of interplanetary spacecraft	
S-5	SLO-1	The ecliptic, Motion of vernal equinox	The two body problem	Special and general perturbations - Cowell's Method ,		Trajectory Characteristics	Spacecraft acoustics and shock loads
S-6	SLO-1	The precession and Equatorial Coordinates	Satellite orbits ,Relations between position and time	Encke's method		Trajectory about the target plant.6	Thermal environment and Thermal Balance
S-7	SLO-1	Sidereal time, Solar time, Standard time	Orbital elements.	Cowell's Method ,		The boost phase, The ballistic phase	Thermal analysis and Thermal design
S-8	SLO-1	The earth's atmosphere.	Parameters used to describe the orientation in space	Method of variations of orbital elements		Trajectory geometry - Optimal flights	Thermal active & passive control and thermal control coatings.
S-9	SLO-1	Troposphere, Stratosphere, Mesosphere, Thermosphere, & Exosphere	Examples of orbits	General perturbations approach.		Time of flight, Reentry phase	Requirements and material selection
						The position of the impact point , Influence coefficients	Spacecraft materials and composite materials.

Learning Resources	<ol style="list-style-type: none"> 1. Sutton. G.P, "Rocket Propulsion Elements", 7th Edition, John Wiley & Sons, NewYork, 2011 2. Corneliisse.J.W, "Rocket Propulsion and Space Dynamics", W.H. Freeman & Co., New York, 2005 3. Rudolph X. Meyer., "Elements of Space Technology", Academic press, London, 2003. 4. Parker.E.R, "Materials for Missiles and Spacecraft", McGraw Hill Book Co., NewYork, 2000. 5. Ramamurthi. K, "Rocket Propulsion", MacmillanPublishers India Ltd. 2010.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

SLO – Session Learning Outcome

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. R. Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in, rkpearls@yahoo.com	Dr.Raju Abraham, Scientist –F, National Institute of Ocean Technology Chennai – 600 100	Mr. P.Udayakumar Assistant Professor (O.G) Department of Mechanical Engineering SRM IST
2. Dr. A. Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	Dr. R.Velraj, Professor, Institute for Energy Studies, Anna University, Chennai, India - 600025	Dr. M. Cheralathan, SRMIST

Course Code	18MEE344T	Course Name	ENERGY ENGINEERING AND MANAGEMENT	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):		The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Understand Environmental aspects of energy utilization.		1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2 :	Understand Energy conservation concepts.		Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3		
CLR-3 :	Understand concepts of energy savings in various thermal systems.																					
CLR-4 :	Energy management techniques																					
CLR-5 :	Energy economics concepts																					
CLR-6 :	Know about the importance of energy management systems and its utilization.																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	Recognize the importance of energy usage as per the requirements		1&2	90	80	H	L	L	L	L	M	H	M			L						
CLO-2 :	Acquire knowledge on the energy conservations and acts		1&2	90	80	H	L	L	L	L	M	H	M	M		L						
CLO-3 :	Knowledge of the working of various heat exchangers and various energy storage systems.		1&2	90	80	H	L	L	L	L	L	H	L			L						
CLO-4 :	Recognize the cost involved for energy systems		1,2&3	90	80	H	L	L	L	L	L	M	M	H	M	H						
CLO-5 :	Implementation of energy management systems in industries		1,2&3	90	80	H	L	L	L	L	L	M	M	H	M	H						
CLO-6 :	Get the knowledge about the various energy sources and its management systems		1,2&3	90	80	H	L	L	L	L	L	H	M	H	H	L						

		Energy And Environment	Energy Conservation	Energy Savings In Thermal Systems	Energy Management	Energy Economics
Duration (hour)		09	09	09	09	09
S-1	SLO-1	Introduction to Energy and Environment	Introduction to energy conservation	Fuels and its consumption	Energy management principles.	Introduction to engineering economics
S-2	SLO-1	Represent World energy consumption	Energy conservation schemes	Energy savings in Boiler.	Energy resource management.	Costing techniques in energy engineering
S-3	SLO-1	Effect of Greenhouse gases	Industrial energy conservation methods	Firing methodology in boilers	Energy management levels.	Cost factors
	SLO-2	Global warming				Break even analysis
S-4	SLO-1	Renewable energy sources	Energy surveying for industries.	Waste heat recovery systems	Energy management information systems.	Cost optimization for energy engineering techniques
	SLO-2		Energy auditing for industries.			Optimal target investment schedule
S-5	SLO-1	Environment aspects utilization	Energy index and cost	Energy saving system in HVAC	Energy instrumentation.	Financial appraisal and profitability
S-6	SLO-1	Energy prices	Energy conservation in engineering and process industry	Energy savings in Refrigeration systems	Energy measurement in energy management	Investment decisions
S-7	SLO-1	World energy reserves	Simple case study of energy auditing in process industries	Energy Storage systems	Energy management Techniques.	Method of investment appraisal
	SLO-2					Discounted cash flow
S-8	SLO-1	World energy policies	Energy conservation in Buildings	Energy saving methodologies by using Insulated pipe work systems	Computerized energy management	Summary investment appraisal techniques
	SLO-2					Optimization with one variable
S-9	SLO-1	The energy future and the role of renewable energy	Concept of Green building	Heat exchangers	Importance of energy management	Optimization with multiple variable.

Learning Resources	<ol style="list-style-type: none"> 1. Murphy.W.R and McKay G, "Energy Management", Butterworths, London, 2007. 2. Reay.D.A, "Industrial Energy Conservation", Pergamon Press, 2003. 3. Steve Doty, Wayne C. Turner, "Energy Management Handbook", Fairmont Press, 7th edition, 2009. 4. Barney L. Capehart, Wayne C. Turner, William J. Kennedy, "Guide to Energy Management", The Fairmont Press, 6th edition, 2008. 5. Callaghan.P.W.O, "Design and Management for Energy Conservation", Pergamon Press, Oxford, 2003. 6. Hamies, "Energy Auditing and Conservation; Methods", Measurements, Management and Case study", Hemisphere, 2003. 7. Trivedi.P.R and Jolka.K.R, "Energy Management", Common Wealth Publication, 2002.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	Dr.M.VENKATA RAMANAN Professor Institute for Energy Studies venkat@annauniv.edu	S.PANNEERSELVAM Department of Mechanical Engineering SRM IST Email: panneerselvam.s@ktr.srmuniv.ac.in
2. Dr. A. Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	Dr.S.KUMAR MRT TNEB CHENNAI.	Dr. M. Cheralathan, SRMIST

Course Code	18MEE345T	Course Name	TURBOMACHINES			Course Category	E	Professional elective		L	T	P	C																
										3	0	0	3																
Pre-requisite Courses	18MEC102T		Co-requisite Courses	NIL			Progressive Courses	NIL																					
Course Offering Department		Mechanical Engineering			Data Book / Codes/Standards			NIL																					
Course Learning Rationale (CLR):		The purpose of learning this course is to:					Learning			Program Learning Outcomes (PLO)																			
CLR-1 :	Understand the basic flow concepts in turbo machines					Level of Thinking (Bloom)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15					
CLR-2 :	Understand the performance of centrifugal flow machines.									Expected Proficiency (%)	90	85	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3		
CLR-3 :	Understand the performance of axial flow machines												H	M	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLR-4 :	Familiarize the performance of axial flow turbines												H	H	-	M	-	-	-	-	-	-	-	-	-	-	-	-	-
CLR-5 :	Know the Working and performance of hydraulic turbines.												H	H	-	M	-	-	-	-	-	-	-	-	-	-	-	-	-
CLR-6 :	Understand the performance and design of turbomachines.												H	H	-	M	-	-	-	-	-	-	-	-	-	-	-	-	-
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:					1& 2	90	85	H	M	-	-	-	-	-	-	-	-	-	-	-	-						
CLO-1 :	Acquire the knowledge on basic flow concepts in turbomachines.					1& 2	90	85	H	M	-	-	-	-	-	-	-	-	-	-	-	-	-						
CLO-2 :	Appreciate the working and performance of centrifugal flow machines.					1& 2	90	85	H	H	-	M	-	-	-	-	-	-	-	-	-	-	-						
CLO-3 :	Analyze the working and performance of axial flow machines.					1&2	90	85	H	H	-	M	-	-	-	-	-	-	-	-	-	-	-						
CLO-4 :	Recognize the working and performance of axial flow turbines					1&2	90	85	H	H	-	M	-	-	-	-	-	-	-	-	-	-	-						
CLO-5 :	Analyze the working and performance of hydraulic turbines.					1&2	90	85	H	H	-	M	-	-	-	-	-	-	-	-	-	-	-						
CLO-6 :	Acquire the knowledge on performance and design of turbomachines.					1&2	90	85	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-						

		Basic flow concepts in turbomachines	Centrifugal flow machines	Axial flow machines	Axial flow turbines	Hydraulic turbines
Duration (hour)		9	9	9	9	9
S-1	SLO-1	Definition, classification and stages of turbo machines	Fans - different impeller sizes, shapes, blade angles, speed and construction	Aero-Thermodynamics of flow through an Axial flow Compressor stage.Blade profile, lift and drag coefficients	Introduction:Turbine stage:Turbine blade 2-D (cascade)analysis Work done.	Pelton turbine- impulse wheel, single jet and multiple jet units
S-2	SLO-1	Estimation of specific work for incompressible and compressible flow machines	Blade shape, blade number,designcalculations	Compressors - brief introduction to two-dimensional cascade and its application to design	Degree of reaction;Losses and Efficiency.	Velocity triangles at inlet and exit of buckets
S-3	SLO-1	Internal and external losses, various efficiencies	Performance in series and parallel	Flow deflection and stagnation pressure loss across blade rows	Flowpassage:Subsonic,transonic and supersonic turbines,Multi-staging of Turbine.	Performance calculations considering losses in the nozzle and buckets
S-4	SLO-1	Representation of specific work on T-s and h-s diagrams	Compressor - slip, inducers, designs without inducer but with inlet guide vanes (IGV)			Francis turbine - reaction, impeller shapes for different shape Numbers/heads
S-5	SLO-1	Velocity triangles - centrifugal and axial flow machine impellers	problems with inducer and IGV's - blade angles,temperature rise and static pressure rise across the impeller	Expression for pressure rise coefficient in terms of flow angles and loss coefficient	Exit flow conditions:Turbine cooling	Calculations on impeller dimensions, blade angles and performance using velocity triangles, draft tubes
S-6	SLO-1	Euler's energy equation across the impeller as applicable to all machines,			Turbine blade design	Kaplan / Propeller Turbine - reaction, impeller (adjustable and fixed) blades and guide blades
S-7	SLO-1	Slip and its estimation	Vaned and vaneless diffuser and volute casing,Surging; Chocking; Rotating stall	Design of impeller blades for free vortex and forced vortex	Turbine profiles, Testing of turbine - test rigs - standard instrumentation- operational characteristics	Calculation of performance using velocity triangles / blade angles at different radii for free vortex flow, its suitability for low heads
S-8	SLO-1	Degree of reaction	Pump - system head, priming of pumps, net positive suction head, minimum starting speed and cavitations.Testing of pumps - test rigs – standard instrumentation- operational characteristics	Design and performance calculations. Stall and surgephenomenon. Noise problem in Axial Compressorsand Fans.	Airfoil data and Profile construction.	
S-9	SLO-1	Blade angles and their effects, calculations considering slip.				

Learning Resources	<ol style="list-style-type: none"> 1. .Gopalakrishnan.G, PrithviRaj.D, "Treatise on Turbomachines", 1st Edition, Chennai, SciTechPublications, 2006. 2. .Seppo A. Korpela., "Prinicipile of Turbomachinery", John Wiley and Sons Ltd, 2012. 3. .Yahya.S.M, "Turbines, Fans and Compressors", 3rd Edition, Tata McGraw Hill Publications, 2010. 4. .Dixon.S.L, "Fluid mechanics and Thermodynamics of Turbomachinery", 5th edition, ElsevierButterworth Heinemann, 2005. 5. .Venkanna. B.K, "Fundamentals of Turbomachinery", 4th Edition, New Delhi, PHI Learning Pvt. Ltd,2011.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	Dr.RavindranS,Professor,Hindustan University Padur,Chennai E-mail: drravimepco@gmail.com	Mr. N. Vijay Krishna Assistant Professor (O.G) Department of Mechanical Engineering SRM IST Email: vijaykrishna.n@ktr.srmuniv.ac.in
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	Vanjeswaran MN, Engineer. Tata Steels Ltd, Jamshedpur Email:mechvanje@gmail.com	Mr. P. Sudhakar Assistant Professor(S.G) Department of Mechanical Engineering SRM IST Email: sudhakar.p@ktr.srmuniv.ac.in

Course Code	18MEE346T	Course Name	THERMAL POWER SYSTEM				Course Category	E	Professional Elective			L 3	T 0	P 0	C 3									
Pre-requisite Courses		NIL		Co-requisite Courses		NIL		Progressive Courses		NIL														
Course Offering Department		Mechanical Engineering				Data Book / Codes/Standards		NIL																
Course Learning Rationale (CLR):		The purpose of learning this course is to:				Learning			Program Learning Outcomes (PLO)															
CLR-1 :	Know the functions of various auxiliary combustion equipment's.				Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Understand the various Thermal power systems.																							
CLR-3 :	Analyze the performance of boiler and condenser. Familiarize with operation of cooling towers.																							
CLR-4 :	Familiarize with operation of Nuclear, Diesel and Gas turbine power plants.																							
CLR-5 :	Know the power plant economics.																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:							H															
CLO-1 :	Familiarize with the combustion equipment of Thermal power plants.				12	90	80		H															
CLO-2 :	Familiarize with the Boilers, accessories and mountings in thermal power system.				12	90	80		H	H		M												
CLO-3 :	Familiarize with the working principle of cooling tower and condensers				12	90	80		H	H														
CLO-4 :	Familiarize with the working principle of Nuclear power plant and Diesel power plant.				12	90	80		H						M									
CLO-5 :	Familiarize with economics in power plant				12	90	80		H											L				

		Fuel Combustion	Thermal Power	Performance Of Thermal Power System	Nuclear, Diesel And Gas Turbine Power Plants	Power Plant Economics
Duration (hour)		09	09	09	09	09
S-1	SLO-1	equipmentIntroduction to power plant-Layout of Thermal power plant	systemsclassification of steam generators.	Selectionof Boilers	Fuels for Nuclear power plants	Power load factor
	SLO-2	Combustion equipment's and its types.			Moderator for Nuclear power plants	Utilization factor
S-2	SLO-1	Solid fuel firing method	Working principle of high pressure boilers	Boiler capacity rating	Control rods for Nuclear power plants	Power plant cost economics
	SLO-2				Coolants for Nuclear power plant.	
S-3	SLO-1	Classification and working of stokers	Working principle of high pressure boilers	Boiler testing and performance	Types of Nuclear reactor	Tariff rates for electricity
	SLO-2			Boiler Energy Balance		
S-4	SLO-1	Fuel and ash handling system	Working principle of supercritical boilers	Condenser design factors	Boiling water reactor	Demand changes for electricity
	SLO-2				Pressurized water reactor.	Load distribution
S-5	SLO-1	Working principle of draft system its type	Working of fluidized bed boilers.	Air removal rate and performance of condenser	Radiation hazards	Effect of Variable load on plant design
	SLO-2				Radioactive waste disposal.	Energy conservation in power plant
S-6	SLO-1	Heat recovery equipments: Economiser, preheaters and reheaters	Boiler mountings	Cooling towers range and	Classification of Diesel power plant	Energy audit in power plant
	SLO-2					
S-7	SLO-1	Types of superheaters	Boiler accessories	Cooling towers approach	Components of Diesel power plant	Maintenance aspects of power plant
	SLO-2	Types of desuperheaters.	Feed water Treatment		Selection of Engine type.	
S-8	SLO-1	Emission control methods-Flue gas cleaning	Working of Condensers	Cooling towers load and performance	Closed cycle Gas Turbine plant	Maintenance aspects of power plant
	SLO-2		Types of Condensers. Factors affecting condenser. Theory and Design of Condenser		Open cycle gas turbine plant.	
S-9	SLO-1	Particulate and gaseous emission control methods.	Working of cooling towers.	Selections of condenser and cooling towers.	Combined power cycles.	Natural and global energy scenario.
	SLO-2		Types of cooling towers.Factors affecting cooling Tower			

Learning Resources	1. El Wakil MM "Power plant Technology" McGraw Hill Inc 2010.
	2. Nag P K " Power plant Engineering" Tata McGraw-Hill, New Delhi, 4 th Edition, 2014
	3. Ramalingam K K "Power plant engineering", Scitech publications Pvt Ltd, 2015
	4. Arora S C and Domkundwar S "Power plant Engineering", Dhanapat Rai & sons, New Delhi, 2015
	5. Rai G D " Non-Conventional Energy sources, "Khanna publishers, 5 th Edition, New Delhi, 2014

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.R.Kalimuthu, ISRO, Mahendragirir_kalimuthu@vssc.gov.in	Dr. K Karuppasamy Assistant Professor Department of Mechanical Engineering Anna University Regional Campus Tirunelveli - 627 007	Mr. S.Malarmannan Assistant Professor, Department of Mechanical Engineering SRM IST Email: malarmannan.s@ktr.srmuniv.ac.in
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	D.Ramesh Kumar, Shin Thermo Dynamic Engineering Private Limited Chennai-600 002 Phone:9445534340 Email: ramesh@shinthermo.co.in	Dr. M. Cheralathan Professor, Department of Mechanical Engineering SRM IST Email: cheralathan.m@ktr.srmuniv.ac.in

Course Code	18MEE347T	Course Name	SOLAR ENERGY SYSTEMS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18MEC101T-Thermodynamics	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	be familiar with basics of solar radiation	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	understand the working of solar collectors	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	be familiar with the solar thermal energy systems and their applications																		
CLR-4 :	understand the solar thermal energy storage and solar cooling systems																		
CLR-5 :	be familiar with the solar photovoltaic energy conversion systems																		
CLR-6 :	be familiar with the solar energy conversion systems																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	understand the fundamentals of solar radiation	1,2	90	80	H			M			M							H	
CLO-2 :	understand the basic principles of solar collector systems	1,2	90	80	H		H											H	
CLO-3 :	analyze and design solar thermal energy systems	1,2,3	90	80	H	M	H			L	H							H	
CLO-4 :	acquire knowledge on solar thermal energy storage and solar cooling systems	1,2	90	80	H	H		M			H							H	
CLO-5 :	acquire knowledge and analyze solar photovoltaic energy conversion systems	1,2,3	90	80	H			M		M	H							H	
CLO-6 :	acquire knowledge on solar energy conversion systems	1,2,3	90	80	H			H		L	M							H	

		Solar Radiation	Solar Thermal Collectors	Design of Solar Thermal Systems	Solar Thermal Energy Storage and Solar Cooling	Solar Photovoltaic Energy Conversion
Duration (hour)		9	9	9	9	9
S-1	SLO-1	The sun and the earth, electromagnetic spectrum	Cassification of solar collectors and solar flat plate collectors	Design of solar flat plate collector systems	Need for solar thermal energy storage	Photovoltaic effect , advantages and disadvantages of solarphotovoltaic technology and classification,
S-2	SLO-1	Laws of thermal radiation	Solar evacuated tube collectors		Sensibleand latent heat storage, its advantages and disadvantages	Semiconductors, p-n junction, photo generation of charge carriers
S-3	SLO-1	Solar radiation:beam and diffuse radiations, terrestrial radiation	Advantages and disadvantages of concentrators over flat plate collectors	Problems on solar flat plate collector systems	Stratified thermal energy storage	I-V characteristics of solar cell
S-4	SLO-1	Sun and earth geometry	Solar concentrators and receiver geometries, concentrationratio	Design of solar active systems using f-chart method	PCM based solar thermal energy storage	Losses in solar cells and solar module
S-5	SLO-1	Solar angles	Compound parabolic concentrators, fresnel lens collectors	Design of solar cooker	Selection of latent heat storage materials	Maximum power point tracking in solar photovoltaic system
S-6	SLO-1	Sunrise, sunset and day length	Solar parabolic concentrators: trough systems	Solar air heater and solar dryer	Solar cooling systems and its advantages	Photovoltaic modules in series and parallel
S-7	SLO-1	Solar radiation on tilted surfaces	Solar parabolic concentrators: dish systems	Solar desalination: types, and operation	Vapour compression refrigeration systems and its solar operation	Concentrated photovoltaic cells
S-8	SLO-1	Measurement of solar radiation: pyranometer	Solar central receiver system	Solar pond: types, principles and applications	Vapour absorption cooling systems	Temperature dependencies and multi junction solar cells
S-9	SLO-1	Measurementof solar radiation: pyrhelimeter, sunshinerecorder	Solar collector orientation and sun tracking systems	Solar thermal power plants and solar furnace	Solar thermoelectric cooling systems	Grid connected and standalone photovoltaic system

Learning Resources	<ol style="list-style-type: none"> 1. Duffie.J.A, &Beckman.W.A, "Solar Engineering of Thermal Processes", 3ro Edition, John Wiley & Sons, Inc.,2006 2. Sukhatme.K, Suhas P. Sukhatme, "Solar energy: Principles of thermal collection and storage", Tata McGraw 3. Hill publishing Co. Ltd, 8th Edition, 2011. 4. Green MA. Solar cells: operating principles, technology, and system applications. Englewood Cliffs, NJ, Prentice-Hall, Inc., 2009. 5. Garg. H.P, Prakash.J, "Solar energy fundamentals and applications", Tata McGraw Hill publishing Co. Ltd, 6. 2006. 7. Yogi Goswami.D, Frank Kreith, Jan F.Kreider, "Principle of solar engineering", Taylor and Francis, 2nd Edition,2000. 8. Chetan Singh Solanki, "Solar Photovoltaic technology and systems: A manual for Technicians, Trainers and a. Engineers", PHI Learning private limited, 2013. 9. G. N. Tiwari and M. K. Ghosal, "Renewable Energy Applications", Narosa Publications, 2004.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers	Experts from Higher Technical Institutions	Internal Experts
Experts from Industry		
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	Dr. G Kumaresan Associate ProfessorInstitute for Energy StudiesCollege of Engineering Guindy Anna UniversityE-Mail : gkumaresan@annauniv.edu	Dr. S. Manikandan Research Assistant Professor,Department of Mechanical Engineering SRM IST Email: maniandan.su@ktr.srmuniv.ac.in
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	Mr. SAI SANTHOSH SOMASUNDARAM Senior Designer – Solar Easi Engineering Chennai, Tamil Nadu, India E-Mail : saisanthoshsomasundaram@gmail.com	Mr. Joji Johnson Assistant Professor, Department of Mechanical Engineering SRM IST Email: joji.j@ktr.srmuniv.ac.in

Course Code	18MEE348T	Course Name	GAS TURBINE TECHNOLOGY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	Approved Gas Tables are permitted		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 : Familiarize the functions of components of gas turbine.		1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 : Analyze the power cycles for optimum thermal performance.		Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 : Understand axial flow compressor characteristics.		Expected Proficiency (%)	Problem Analysis
CLR-4 : Understand combustion systems and axial flow turbine operation		Expected Attainment (%)	Design & Development
CLR-5 : Familiar with the performance predictions.			Analysis, Design, Research
CLR-6 : Familiar with gas turbine technologies and their performances			Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 : Appreciate the functions of components of gas turbine.		1 & 2	H - - - - - - - - - -
CLO-2 : Appreciate the analysis knowledge of the power cycles for optimum thermal performance.		1,2,3	H H H - - - - - - - -
CLO-3 : Appreciate the understanding of the axial flow compressor characteristics.		1,2,3	H H H - - - - - - - -
CLO-4 : Appreciate the understanding of the combustion systems and axial flow turbine operation		1,2,3	H H H - - - - - - - -
CLO-5 : Appreciate the familiarity with the performance predictions of gas turbines.		1,2,3	H H H L L - - - - - -
CLO-6 : Appreciate the familiarity with gas turbine technologies and their performances		1,2,3	H H H L L - - - - - -

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Definition, classification of gas turbines	Ideal cycle operation and thermal performance	Centrifugal compressor, Principle of operation, work done. Pressure rise and the diffuser	Operation requirements
S-2	SLO-1	Open cycle single shaft and twin shaft multi speed arrangement, Closed cycle, aircraft propulsion	Methods of determining component losses	Compressibility effects, Non dimensional quantities	Prediction performance of gas turbines component characteristics
S-3	SLO-1	Gas turbine components and their description	Design point performance calculations, Comparative performance of actual and practical cycles.	Computerized design procedure. Axial flow compressor basic operation	type of combustion – Factors affecting combustion process, Combustion chamber performance
S-4	SLO-1	Representation of specific work on T-s and h-s diagrams	Analysis of polytropic efficiency (Infinitesimal stage efficiency) of a gas turbine and Velocity triangles		Different types of combustion chambers and their relative merits and demerits
S-5	SLO-1	Comparison of steam and gas turbines	Closed cycle gas turbine and Combined cycle and Cogeneration schemes, Integrated gasification combined cycle.	Elementary theory, Factors effecting stage pressure ratio, Blockage in compressor annulus	Equilibrium running of gas generator
S-6	SLO-1	Applications of gas turbine in various fields. Industrial applications of gas turbines.	Reheat, intercooling and Regenerator cycles for improved thermal performance.	Degree of reaction, Blade fixing details, Sealing materials, Material selection for compressor blades, Stage performance	Turbine construction – Performance, Impeller blade fixing
S-7	SLO-1	Gas turbine fuels and their properties	Optimum pressure ratio for maximum thermal efficiency, work ratio, air rate, effect of operating variables on thermal efficiency, work ratio, and air rate	Design and off design performance characteristics.	Cooling of turbine blades – Blade vibration
S-8	SLO-1	Environmental issues related to the operation and maintenance, Future of gas turbine engines and the new possibilities			Protective coating – Gas turbine turbo chargers - Power expanders
S-9	SLO-1				Vortex theory – Estimation of stage performance.

Learning Resources	<ol style="list-style-type: none"> 1. Ganesan.V, "Gas Turbines", Tata McGraw Hill, 3rd Edition, 2010. 2. Mattingly.J.D, "Elements of Propulsion: Gas turbines and Rockets", McGraw Hill, 2012 3. Yahya S.M, "Turbines, Fans and Compressors", 3rd Edition, Tata McGraw Hill Publications, 2010. 4. Irwin E. Treager, 'Gas Turbine Engine Technology ', Mc Graw Hill Education, 3rd edition, 2013. 5. Saravanamuttoo. H.I.H, Rogers.G.F.C, Henry Cohen, "Gas Turbine Theory", Pearson Prentice Hall, 6th Edition, 2009. 6. Gopalakrishnan.G, Prithvi Raj D, "Treatise on Turbomachines", 1st Edition, Chennai, SciTech Publications, 2006. 7. Horlock.J.H, "Advanced Gas Turbine Cycles", Elsevier Science Ltd, 2003. 8. Venkanna.B.K, "Fundamentals of Turbomachinery", 4th Edition, New Delhi, PHI Learning Pvt. Ltd, 2011. 9. Yahya.S.M, "Gas Tables for compressible flow calculations", New Age International (P) Ltd, NewDelhi, 6th Edition, 2011
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	Dr.K. Karunamurthy, Associate Professor, School of Mechanical and Building Sciences, VIT, Chennai. Email: karunamurthy.k@vit.ac.in	Dr. R. Senthil Associate Professor Department of Mechanical Engineering SRM IST. Kattankulathur Campus. Email: senthil.r@ktr.srmuniv.ac.in
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	Mr.M.Periyasamy Chief Manager, NLC Limited, Neyveli.Tamil Nadu Email: mpsamy34912@gmail.com	Dr. M. Cheralathan Professor, Department of Mechanical Engineering SRM IST Email: cheralathan.m@ktr.srmuniv.ac.in

Course Code	18MEE349T	Course Name	SOLAR ENERGY UTILIZATION	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Be familiar with basics of solar radiation data and its measurement	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Be familiar with construction and operation of solar thermal energy systems		
CLR-3 :	Understand the operation of solar thermal power plants		
CLR-4 :	Be familiar with basics and design of solar photovoltaic systems		
CLR-5 :	Be exposed to the concept solar architecture in buildings and green buildings		
CLR-6 :	Be familiar with solar energy concepts and various applications of solar energy like thermal systems, photovoltaic systems and building architecture		

Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			Level of Thinking (Bloom)	Expected	Expected	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3	
CLO-1 :	Understand solar radiation, solar angles and recognize and analyze the working of solar radiation measuring instruments	1&2	85	75	H	M							H								M	H	
CLO-2 :	Understand the components and working of low temperature solar thermal systems	1	85	75	M								M	H							M	H	
CLO-3 :	Acquire knowledge on basic components and working of concentrated solar thermal systems for power generation	1	85	75	M								M	H							M	H	
CLO-4 :	Comprehend the solar cell working and manufacturing and can design a solar system for buildings	1&2	85	75	M	M							M	H							M	H	
CLO-5 :	Recognize the various solar architecture in buildings and gain a basic knowledge in green buildings	1	85	75	M								L	H							M	H	
CLO-6 :	Understand solar radiation and its seasonal variations along with understanding of the practical application of solar energy powered systems in the three main domains of thermal, photovoltaic and building architecture	1	85	75	M									H							M	H	

		Solar Radiation and its measurement	Low Temperature Systems	High Temperature systems	Photovoltaics	Solar Systems for Buildings
Duration (hour)		18	18	18	18	18
S-1	SLO-1	The Sun and the Earth, Electromagnetic spectrum	Solar flat plate collectors	Solar concentrators and receiver geometries, Concentration ratio	Photovoltaic effect, Classification, Advantages and disadvantages of Solar photovoltaic technology	Need for passive architecture, Thermal comfort
S-2	SLO-1	Laws of radiation	Basic design of solar flat plate collectors, example problems	Advantages and disadvantages of concentrated collectors over non-concentrated collectors	Semiconductors, p-n junction, Photo generation of charge carriers	Sun's motion, Orientation and design of buildings
	SLO-2	Solar radiation: beam and diffuse radiations, Terrestrial radiation				
S-3	SLO-1	Depletion of Solar radiation in atmosphere	Solar evacuated tube collectors	Rankine power cycle	Photovoltaic cell manufacture: Czochralski, Zone refining and ribbon growth	Thermal capacity, Sensible and latent heat storage in buildings, Insulation
S-4	SLO-1	Solar angles, example problems	Domestic hot water systems: Integral collector storage, Thermosiphon system, Drain back system, Drain down system, Anti-freeze system	Compound parabolic concentrators, Fresnel lens collectors	I-V characteristics of solar cell	Solar Passive architecture : Heating of Buildings
S-5	SLO-1		Solar Cooker : Box type and Dish type	Solar parabolic concentrators: trough system	Losses in solar cell	Solar Passive architecture : Cooling of Buildings
S-6	SLO-1	Sunrise, sunset and day length, example problems	Solar Cooking application problems	Solar parabolic concentrators: dish system	Solar Module manufacturing	Air conditioning : Solar vapour compression refrigeration system
S-7	SLO-1	Solar radiation on tilted surfaces	Solar air heater, Solar dryer and its types	Central receiver plant / Power tower	Photovoltaic system for power generation : Standalone system and grid connected system	Air conditioning : Solar vapour absorption refrigeration system
S-8	SLO-1	Measurement of solar radiation: Pyranometer	Solar desalination, solar still design, example problems	Solar furnaces: types, principle and application	Photovoltaic system design for a building: DC system and AC system, example problems	Green buildings, Zero energy buildings, Rating systems
S-9	SLO-1	Measurement of solar radiation: Pyrheliometer, Sunshine Recorder	Solar Pond: types, principle and application	Orientation and sun tracking systems		

Learning Resources	<ol style="list-style-type: none"> 1. Duffie.J.A, &Beckman.W.A, "Solar Engineering of Thermal Processes", 4th Edition, John Wiley & Sons, Inc., 2013. 2. Sukhatme.K, Suhas P. Sukhatme, "Solar energy: Principles of thermal collection and storage", Tata McGraw Hill publishing Co. Ltd, 8th Edition, 2011. 3. Chetan Singh Solanki, "Solar Photovoltaic: Fundamentals, Technologies and Applications", PHI Learning private limited, 2015. 4. Jan F. Kreider, "The solar heating design process: active and passive systems, McGraw-Hill, 2007. 5. G.D. Rai, "Solar Energy Utilisation", Khanna Publishers, 5th Edition, 2014. 6. Yogi Goswami.D, Frank Kreith, Jan F.Kreider, "Principle of solar engineering", Taylor and Francis, 2nd Edition, 2000. Andy Walker, "Solar Energy", John Wiley & Sons, 2013. 7. Garg. H.P, Prakash.J, "Solar energy fundamentals and applications", Tata McGraw Hill publishing Co. Ltd, 2006. 8. Tiwari.G.N, "Solar energy: Fundamentals, Design, Modeling and Applications", Alpha Science International, Limited, 2013. 9. David A Bainbridge, Ken Haggard, "Passive solar architecture: Heating, Cooling, Ventilation and more use of natural flows", Chelsea Green Publishing, 2011.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers	Experts from Higher Technical Institutions	Internal Experts
Experts from Industry		
1. Dr.R.Kalimuthu, ISRO, Mahendragirir_kalimuthu@vssc.gov.in	Dr. G Kumaresan Associate Professor Institute for Energy StudiesCollege of Engineering Guindy Anna University E-Mail : gkumaresan@annauniv.edu	Mr. Joji Johnson Assistant Professor, Department of Mechanical Engineering SRM ISTEmail: joji.j@ktr.srmuniv.ac.in
2. Dr.A.Velayutham, DRDO, Avadi,velayudham.a@cvrde.drdo.in	Mr. SAI SANTHOSH SOMASUNDARAM Senior Designer – Solar Easi Engineering Chennai, Tamil Nadu, IndiaE-Mail : saisanthoshsomasundaram@gmail.com	Dr. S. Manikandan Research Assistant Professor, Department of Mechanical Engineering SRM IST Email: manikandan.su@ktr.srmuniv.ac.in

Course Code	18MEE350T	Course Name	GAS DYNAMICS AND SPACE PROPULSION	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18MEC201T, 18MEC202T	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	Gas Tables		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Familiarize the compressible fluid flow concepts	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Understand the isentropic flow through variable area ducts and normal shocks.		
CLR-3 :	Familiarize with the oblique shock and expansion waves		
CLR-4 :	Understand the flow through constant area duct with friction and heat transfer		
CLR-5 :	Understand the aircraft and rocket propulsion		
CLR-6 :	Familiarize with the gas dynamics and space propulsion		

Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			Level of Thinking	Expected	Expected	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Management	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Analyse and evaluate the compressible flow problems	123	90	80	H	H		M														
CLO-2 :	Analyse and solve the engineering flow problems through the nozzles and diffusers with and without Normal shock.	123	90	80	H	H		M														
CLO-3 :	Analyse and solve problems related to oblique shock and expansion waves.	123	90	80	H	H		M														
CLO-4 :	Analyse and solve problems related to flow through constant area ducts with friction and heat transfer..	123	90	80	H	H		M														
CLO-5 :	Analyse and evaluate the performance of Aircraft and Rocket Engines.	123	90	80	H	H		M														
CLO-6 :	Understand the gas dynamics and space propulsion.	123	90	80	H	H		M														

		Fundamentals of Compressible Flow	Isentropic Flow Through Variable Area Ducts	Oblique Shock And Expansion	Flow Through Constant Area Ducts	Aircraft and Rocket Propulsion
Duration (hour)		9	9	9	9	9
S-1	SLO-1 SLO-2	Energy equation for compressible fluid flow	T-s and h-s diagrams for nozzles and diffusers	Introduction and oblique shock relations	Flow in constant area ducts with friction (Fanno flow), Fanno curves	Types of aircraft engines and Propulsion theory
S-2	SLO-1 SLO-2	Stagnation state and Mach number	Area ratio as a function of Mach number, Impulse function	Relation between wave angle and deflection angle	Fanno flow equations,	Performance of Turbojet, Turbofan, Turboprop engines
S-3	SLO-1 SLO-2	Various regimes of flow	Mass flow rate through nozzles and diffusers	Supersonic flow over a wedge and weak oblique Shock	Variation of flow properties (no derivation)	Ramjet and pulse jet engine – construction and working.
S-4	SLO-1 SLO-2	Reference velocities , Critical states	Problems on variable area duct	Problems on the oblique shock wave	Variation of Mach number with duct length	Problems on Aircraft Engine Performance
S-5	SLO-1 SLO-2	Problems on energy equations	Flow with normal shock – Development, governing equations	Supersonic compression and expansion, Prandtl-Meyer expansion	Flow in constant area duct with heat transfer - Rayleigh line & curves	Types and applications of rocket engines
S-6	SLO-1 SLO-2	Equivalent of Bernoulli's equation for compressible flow	Derivation of Prandtl – Meyer equation	Problems on Prandtl-Meyer expansion and compression	Rayleigh flow equations	Solid , Liquid and Hybrid propellant rockets – construction and fuels-oxidizers
S-7	SLO-1 SLO-2	Effect of Mach number on compressibility	Variation of flow parameters -static pressure & temperature, density, stagnation pressure and entropy across the shock (no derivations)	Detached shock waves, reflection and intersection of shocks and expansion waves	Variation of flow properties (no derivation)	Performance of Rocket engines.
S-8	SLO-1 SLO-2	Velocity of sound and wave propagation- subsonic, sonic and supersonic waves	Impossibility of shock in subsonic flows, strength of a shock wave	Problems on intersection of shocks and expansion waves	Maximum heat transfer concept	Problems on Rocket engines
S-9	SLO-1 SLO-2	Problems on energy equations	Problems on Normal shock	Underexpanded and overexpanded nozzles	Tables and charts for Fanno flow and Rayleigh flow.	Types and applications of rocket engines

Learning Resources	1. Yahya.S.M, "Fundamentals of Compressible Flow with Aircraft and Rocket Propulsion", New Age International (P) Ltd, New Delhi, 3rd edition, 2012.
	2. Radhakrishnan.E, "Gas Dynamics", PHI Learning Pvt. Ltd, 4th edition, 2012.
	3. Mattingly.J.D, "Elements of Propulsion: Gas turbines and Rockets", McGraw Hill, 2012.
	4. Balachandran.P, "Fundamentals of compressible fluid dynamics", PHI Learning, 2012
	5. Robert.D.Zucker, "Oscar Biblarz, Fundamentals of Gas Dynamics", John Wiley and Sons, 2nd edition, 2011.
	6. Ascher H.Shapiro , 'The dynamics and thermodynamics of compressible flow', R.R.Kreiger Publishers, Volume 2, 1983.
	Databook
	7. Yahya.S.M, "Gas Tables for compressible flow calculations", New Age International (P) Ltd, New Delhi, 6th edition, 2011.

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	Dr. R.Velraj, Professor, Institute for Energy Studies, Anna University, Chennai, India - 600025	Dr. P.Chandrasekaran, Associate Professor, SRMIST
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cwrde.drdo.in	Dr.Raju Abraham, Scientist –F, National Institute of Ocean Technology Chennai – 600 100	Mr.G.Manigandaraja, Assistant Professor, SRMIST

Course Code	18MEE441T	Course Name	COMPUTATIONAL FLUID DYNAMICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18MEC101T,18MEC105T	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Be familiar with the basic governing equations of fluid mechanics and behavior of PDE.	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Be familiar with the different discretization techniques	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Know the CFD solution techniques in compressible flow	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Be familiar with incompressible fluid flow problems solution techniques	Expected Attainment (%)	Design & Development
CLR-5 :	Be familiar with the basics of turbulence modeling.		Analysis, Design, Research
CLR-6 :	Be familiar to solve fluid flow problems		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Understand and apply basic governing equations to different problems.	1& 2	90 85
CLO-2 :	Choose and apply different discretization techniques in solving problems.	1	90 85
CLO-3 :	Choosing different solution techniques to solve numerical problems.	123	90 85
CLO-4 :	Solving different incompressible flow problems with appropriate pressure correction and solution techniques.	123	90 85
CLO-5 :	Apply turbulence modeling in solving high Reynolds number flows	1&2	90 85
CLO-6 :	Choose and apply different discretization and solution techniques to solve fluid flow problems	123	90 85

		Governing Equations	Discretisation Techniques	Soluton Techniques And Numerical Methods For Compressible Flow	Finite Volume Method And Techniques For Incompressible Flow	Turbulence Modeling
Duration (hour)		9	9	9	9	9
S-1	SLO 1	Introduction, various application of computational fluid dynamics	Discretization techniques and principles	Solution techniques for linear system of equations- Gauss elimination method.	Introduction to finite volume method(FVM)	Concept of boundary layer
S-2	SLO 1	Conservation and Non conservation form of governing equations. Models of fluid flow	Finite difference method – Forward, Backward difference methods	Numerical solution – Gauss Siedel and Tri-diagonal matrix algorithm	Discretization of one dimensional steady state heat conduction convection equation using FVM	Laminar sub layer logarithmic layer Velocity defect law
S-3	SLO 1	Continuity equation derivation in all forms	Finite difference method – central difference methods	Numerical solution – Jacobie and relaxation techniques	Discretization of incompressible Naviers Stokes Equations using finite differences	Concept of turbulence, Reynolds averaging
S-4	SLO 1	Momentum equation derivation	One dimensional steady state heat conduction problem -Explicit method	Solution techniques for ordinary differential equations, Linear multistep method	Concept of staggered grid.	Time average equations for turbulent flow
S-5	SLO 1	Energy equation derivation	One dimensional steady state heat conduction problem -Implicit method	Predictor and corrector scheme – McCormack technique	Pressure correction method	Boissuniq approximation method, Types of turbulence models –
S-6	SLO 1	Different types of boundary conditions – Dirichlet, Neumann, Cauchy and Robbins boundary conditions with examples	Discretization of one dimensional wave equation	Solution of supersonic flow through converging-diverging nozzle with predictor and corrector method: Governing equations	SIMPLE algorithm and boundary conditions	Prandtl mixing length model, One-equation models
S-7	SLO 1	Classification of Partial differential equations –elliptic, parabolic, hyperbolic	Stability analysis of different equations, consistency and convergence	Numerical method	Solution of Couette flow using SIMPLE algorithm	Two-equation models
S-8	SLO 1	Mathematical behavior of Partial differential equations - Elliptic, Parabolic equation	Problems on stability analysis	Boundary conditions, case set-up and results	Problems in Couette flow using SIMPLE algorithm	Energy cascade mechanism in turbulent flows
S-9	SLO 1	Mathematical behavior of Partial differential equations - Hyperbolic equations –well posed problems	Discussion on CFL condition	Problems in supersonic flow through converging-diverging nozzle	Alternating direction implicit method and application to unsteady two dimensional heat conduction	Comparison of merits and demerits of different turbulent models

Learning Resources	1. Anderson J.D., "Computational Fluid dynamics", McGraw Hill Int., New York, 2010. 2. Versteeg H.K., and Malalasekera W., An introduction to computational fluid dynamics, "The finite volume method", Longman, 2007. 3. Suhas.V. Patankar, "Numerical Heat Transfer and Fluid Flow", Hemisphere Publishing Corporation, 2009. 4. Muralidhar.K, and Sundararajan.T, "Computational Fluid Flow and Heat Transfer", Narosa Publishing House, New Delhi, Second Edition, 2008. 5. Ghoshdasdar.P.S, "Computer simulation of fluid flow and heat transfer", Tata McGraw Hill Publishing Company Ltd., 1998.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	Dr.R.Sivakumar ,Professor and Dean SMBS, VIT, Chennai	P.Sudhakar, SRMIST
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cwrde.drdo.in	Mr.P.Sivaganga kumar,Support Manager,Siemens Industry software Compiutational Dynamics India(P) ltd Bengaluru	Dr.D.Siva Krishna reddy SRMIST

Course Code	18MEE442T	Course Name	ADVANCED ENGINEERING THERMODYNAMICS	Course Category	P	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Engineering Thermodynamics (18ME101T)	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	Steam tables, Mollier and generalized compressibility chart		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Familiarize with entropy, exergy and thermodynamics properties.				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Be familiar with the relationship between thermodynamic properties				Thinking (Bloom)	Proficiency (%)	Attainment (%)	Knowledge	Analysis	Development	Design, Research	Usage	Culture & Sustainability	Team Work	Communication	Finance & Learning						
CLR-3 :	To attain the knowledge about chemical thermodynamics																					
CLR-4 :	To attain the knowledge about statistical thermodynamics																					
CLR-5 :	To attain the knowledge of irreversibility in Thermodynamics																					
CLR-6 :	To attain the knowledge of thermodynamics for various engineering systems																					

Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:	Level of TT	Expected	Expected	Engineering Problem Design & Analysis, Modern T	Society & Environment	Ethics	Individual	Communi	Project M	Life Long	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Understand the application of exergy and entropy in various engineering devices.		1, 2, 3	95	85	H	H	L	H						H
CLO-2 :	Understand the concept of Real gas behaviour and multicomponent systems.		1, 2, 3	95	85	H	H	L	M						H
CLO-3 :	Understand the concept Chemical thermodynamics and equilibrium.		1, 2, 3	95	85	H	H	L	M						H
CLO-4 :	Understand the concept Statistical thermodynamics.		1, 2, 3	95	85	H	H	L	M						H
CLO-5 :	Understand the concept of irreversible thermodynamics.		1, 2, 3	95	85	H	H	L	M						H
CLO-6 :	Understand the concept of thermodynamics to various engineering systems.		1, 2, 3	95	85	H	H	L	M						H

		Entropy, Exergy Analysis And Property Relations	Real Gas Behaviour And Multicomponent Systems	Chemical Thermodynamics And Equilibrium	Statistical Thermodynamics	Irreversible Thermodynamics
Duration (hour)		9	9	9	9	9
S-1	SLO-1	Entropy principle and its applications, Entropy transfer mechanisms phase diagram, phase changes, various properties diagram, 1st order phasetransition and 2nd order phase transition	Law of corresponding states, Generalized compressibility chart, Reduced coordinate Phase transition, types of equilibrium and stability, multi-component and multi-phase systems, equations of state.	Degree of reaction, reaction equilibrium, law of mass action, heat reaction Chemical equilibrium, Thermodynamic equation for phase	Statistical thermodynamics: Introduction, energy states and energy levels	Introduction to Steady-state thermodynamics,
S-2	SLO-1	Exergy transfer by heat, work and mass	Stability of thermodynamic systems, Le Chatelier's Principle, Other equation of state: Vander Waals equation of state, Beattie-Bridgeman equation of state	Temperature dependence of the heat of reaction and equilibrium constant, thermal ionization of a monatomic gas	Micro and Macro state, Maxwell-Boltzmann statistics	Irreversibility and causes of irreversibility
S-3	SLO-1	Exergy destruction, exergy balance in closed and open systems	Benedict-Webb-Rubin equation of state, Virial equation of state	Gibbs function change, Fugacity and Activity, heat capacity of reacting gases in equilibrium	Sterling's approximation, Maxwell-Boltzmann distribution function	Thermodynamics forces and thermodynamics velocities
S-4	SLO-1	Exergy analysis of industrial systems: power system and refrigeration systems	Use of generalized charts for enthalpy and entropy departure	Enthalpy of formation, 1 st law for reactive system	Bose-Einstein statistics, Fermi-Dirac statistics	Onsager's reciprocal relations
S-5	SLO-1	Maxwell relations, Generalized relations for changes in entropy, internal energy and enthalpy.	Fugacity coefficient, Lee-Kesler generalized three parameter tables	Adiabatic flame temperature, Enthalpy and energy of combustion	Distribution of particles over energy levels, partition function	Calculation of entropy production
S-6	SLO-1	General thermodynamic consideration and equations of state, Evolution of thermodynamics properties from equation of state	Fundamental property relations for systems of variable composition.	Entropy change for reactive system	Microscopic interpretation of heat and work	Thermoelectricity: Application of irreversible thermodynamics to a thermocouple
S-7	SLO-1	Type of equilibrium, local equilibrium condition	Partial molar properties, Real gas mixture.	Absolute entropy, third law of thermodynamics	Statistical interpretation of entropy	Uncoupled effects in thermoelectricity
S-8	SLO-1	Condition of equilibrium for a heterogeneous system. Gibbs phase rule	Ideal solution of real gases and liquid, activity, equilibrium in multi-phase systems	2 nd law analysis for reactive system	Application of statistics to gases-mono-atomic ideal gas	The coupled equations of thermoelectricity

S-9	SLO-1	Condition of stability and Third law of thermodynamics	Gibbs phase rule for non-reactive components.	chemical exergy, 2 nd law efficiency of a reactive system	Principle of equipartition of energy, thermodynamics properties, specific heat of solids	Other effects in Thermocouples
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Learning Resources	Yunus, A. C., and Boles, A., "Thermodynamics-An engineering approach, 8 th edition", Tata McGraw Hill- Education New Delhi, 2015.
	Nag, P. K., "Engineering Thermodynamics", 5 th edition, Tata McGraw Hill education New Delhi, 2013.
	Bejan, A., "Advance Engineering Thermodynamics, 3 rd edition, John Wiley and sons, 2006.
	Smith, J. M. et al, "Introduction to chemical engineering thermodynamics" Tata McGraw Hill, 2005
	Puri, I. K., and Annamalai, K., "Advance Engineering Thermodynamics", CRC Press, 2001.

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Expert from Industry	Experts from Higher Technical Institute	Internal Experts
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	1. Dr. Laltu Chandra Indian Institute of Technology (BHU)	1. Dr. Piyush Sharma, Asst. Prof.
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cwrde.drdo.in	Dr. Amit Gupta (ABSTC) Aditya Birla Science and Technology Company	Dr. Pankaj Kumar Research Asst. Prof.

Course Code	18MEE443T	Course Name	ADVANCED FLUID MECHANICS	Course Category	P	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Fluid Mechanics (18MEC102T)	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards			

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Familiarize with fundamental fluid flow pattern	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Be familiar with the concept of potential flow	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	To attain the knowledge about the exact solution of Navier-Stokes Equations	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Be familiar with laminar boundary layers, turbulent flows, turbulence modeling and equations, Basic discretization method	Expected Attainment (%)	Design & Development
CLR-5 :	To attain the knowledge of the various types of flow stability theory		Analysis, Design, Research
CLR-6 :	Be familiar with the applications of N-S equation in internal and external flows		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)
CLO-1 :	Analyze the different flow patterns, difference in rotational and irrotational flow, Stream and velocity potential function.	1, 2, 3	90	80
CLO-2 :	Acquire knowledge on Source and Sink; Vortex flow, Doublet, Superposition of basic plane potential flows	1, 2, 3	90	80
CLO-3 :	Understand the basic calculations for force and momentum calculations using N-S equations, understand the Couette flows, Poiseuille flows	1, 2, 3	90	80
CLO-4 :	Understand the Integral form of boundary layer equations, Turbulent boundary layer equation, major turbulence modeling, finite element method, finite volume method	1, 2, 3	90	80
CLO-5 :	Understand the concept of the Linear Stability theory	1, 2, 3	90	80
CLO-6 :	Able to apply and solve N-S equation for different flow conditions.	1, 2, 3	90	80

	Analyze the different flow patterns, difference in rotational and irrotational flow, Stream and velocity potential function	Acquire knowledge on Source and Sink; Vortex flow, Doublet, Superposition of basic plane potential flows	Understand the basic calculations for force and momentum calculations using N-S equations, understand the Couette flows, Poiseuille flows	Understand the Integral form of boundary layer equations, Turbulent boundary layer equation, major turbulence modeling, Discretization	Understand the concept of the Linear Stability theory
Duration (hour)	9	9	9	9	9
S-1	SLO-1 Continuity Equation, Streamlines, and Stream Function	Uniform flow, source flow, sink flow	Solutions to the Steady-State Navier-Stokes Equations	Boundary layer on a flat plate	Concept of small-disturbance stability,
S-2	SLO-1 Vorticity and Circulation	Free vortex flow	Problems based on Steady-State Navier-Stokes Equations	Similarity solutions, Integral form of boundary layer equations Approximate Methods	Linear Stability Theory of Fluid Flows
S-3	SLO-1 Problem based on vorticity and circulation	Super imposed flow, source and sink pair	Poiseuille Flow in a Rectangular Conduit	General equations of turbulent flow, Turbulent boundary layer equation	Orr-Sommerfeld equation,
S-4	SLO-1 Irrotational Flows and the Velocity Potential	Doublet	Couette Flow Between Concentric Circular Cylinders	Flat plate turbulent boundary layer	Boundary layer stability
S-5	SLO-1 Problems based on irrotational Flows and the Velocity Potential	Flow past a Rankine oval body	Creeping flows	Turbulent Models-zero, one and two	Thermal Instability
S-6	SLO-1 Lagrangian and Eulerian description	doublet in a uniform flow	Fully developed flows in non- circular cross-sections	Prandtl mixing hypothesis,	Transition to turbulence
S-7	SLO-1 Reynolds transport theorem	Flow past a cylinder with circulation	Unsteady Flows: Impulsive Motion of a Plate—Stokes's First Problem	Basic discretization – Finite difference method	Inviscid stability theory
S-8	SLO-1 Derivation of continuity and momentum equations using Reynolds transport theorem	Magnus effect; Kutta-Joukowski lift theorem	Oscillation of a Plate—Stokes's Second Problem	Finite volume method	Problems based on Navier-Stoke's equation for steady incompressible flows
S-9	SLO-1 Problem based on Reynolds transport theorem	Concept of lift and drag.	Flow in Convergent and Divergent Channels	Finite element method	Favorable and adverse pressure gradients, flow separation

Learning Resources	1. Graebel. W.P, "Advanced Fluid Mechanics", 1st Edition, Academic Press, Elsevier Inc., 2007
	2. Muralidhar and G. Biswas, " Advanced Engineering Fluid Mechanics", 3rd Edition, Narosa Publishers, 2015
	3. Stevan A Jones, "Advanced Methods for Practical Applications in Fluid Mechanics", InTech Publishers, 2012
	4. Kundu P., Cohen I and Dowling D, "Fluid Mechanics" 6 th edition, 2015
	5. Schlichting H., K. Gersten, Boundary Layer Theory, 8/e, Springer 2000

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Expert from Industry	Experts from Higher Technical Institute	Internal Experts
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	Dr. Dhiman Chatterjee, Professor, Dept. of Mechanical Engineering, IIT Madras	1. Dr. Pankaj Kumar
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	1. Dr Parag Deshpande, senior scientist, NAL	Dr. M. Cheralathan, SRMIST

Course Code	18MEE444T	Course Name	DESIGN OF PUMPS AND TURBINES	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18MEC102T	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
		1	2	3	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
		Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3					
CLR-1: <i>Acquire the knowledge on basic flow concepts in turbines and pumps</i>					H	H	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLR-2: <i>Understand the design principles of simple radial flow pumps</i>					H	H	H	M	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLR-3: <i>Know the design principles of various turbines</i>					H	H	H	M	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLR-4: <i>Understand the phenomenon of cavitation in hydraulic machines</i>					H	H	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLR-5: <i>Know the hydro machine applicability from the cavitation point of view.</i>					H	H	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLR-6: <i>Familiarize with the performance and design of turbines and pumps</i>		H	H	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-			
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
		1&2	90	85																				
CLO-1: <i>Appreciate the basic flow concepts in turbines and pumps.</i>		1	90	85																				
CLO-2: <i>Know the design principles of simple radial flow pumps</i>		123	90	85																				
CLO-3: <i>Appreciate the design principles of various turbines</i>		123	90	85																				
CLO-4: <i>Familiarize with the effects of cavitation in hydraulic machines</i>		123	90	85																				
CLO-5: <i>Become familiar with hydro machine applicability from the cavitation point of view.</i>		1&2	90	85																				
CLO-6: <i>To solve practical fluid flow problems in turbines and pumps</i>		123	90	85																				

Duration (hour)		Basic principles of fluid machinery	Theory of Pumps	Design of pumps	Theory and design of turbines	Cavitation
		9	9	9	9	9
S-1	SLO 1	Definition, classification and stages of turbines and pumps	Introduction to mixed flow centrifugal pumps	Design procedure for pumps	Theory of turbines , specific speed, Euler's turbine equation	Introduction to cavitation
S-2	SLO 1	Basic equations of energy transfer between the fluid and the rotor	Calculation of thrust In mixed flow centrifugal pumps	Thermal design of pumps -	Introduction to Pelton wheel (impulse turbine) - single jet and multiple jet units	Cavitation in pumps
S-3	SLO 1	Performance characteristics of various turbines and pumps	Impellers, Pump casings – volute casing and vortex casing	Selection of materials for withstanding high temperature and corrosive fluids	Velocity diagrams at the inlet and exit of the buckets	Cavitation in turbines
S-4	SLO 1	Dimensional analysis	Velocity diagrams for mixed flow centrifugal pumps	Hydraulic design of pumps	Performance calculations considering the losses in the nozzle and the buckets	Thomas cavitation factor
S-5	SLO 1	Dimensionless parameters in turbines and pumps	Calculation of work input to mixed flow centrifugal pumps	Selection of the impeller for pumps	Introduction to reaction turbine (mixed flow and axial flow) and Degree of reaction	Net positive suction head (NPSH)
S-6	SLO 1	Specific speed in turbines and pumps	Head, Losses and efficiency of mixed flow centrifugal pumps	Calculation of casing dimension	Francis turbine – Velocity diagrams and Design procedure	Effects of cavitation on the performance of turbines and pumps
S-7	SLO 1	Velocity triangles of a stage	Specific speed, Power requirement and operating characteristics	Introduction to computer programs for iterative and interactive design	Introduction to Kaplan / Propeller Turbine – axial flow reaction type	Cavitation – damage to equipments
S-8	SLO 1	Calculation of work output of turbine	Minimum starting speed of centrifugal pump	System head, Net positive suction head,	Velocity diagrams and design procedure for Kaplan turbine	Design considerations to avoid cavitation
S-9	SLO 1	Computation of efficiency	Multi stage pump	Priming of pumps	Governing of turbines	Cavitation and energy harvesting

Learning Resources	1. Dixon.S.L, "Fluid Mechanics and Thermodynamics of Turbomachinery", 6th Edition, Butterworth 2. Heinemann, U.K., 2010 3. Viktor Gelpke, "Hydraulic turbines their design and installation", Research press, 2010 4. Seppo A. Korpela., "Principles of Turbomachinery", John Wiley and Sons Ltd, 2012 5. Yahya.S.M, "Turbines, Fans and Compressors", 3rd Edition, Tata McGraw Hill Publications, 2010 6. Venkanna. B.K, "Fundamentals of Turbomachinery", 4th Edition, New Delhi, PHI Learning Pvt. Ltd, 2011.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Understand	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	Dr K KARUNAMURTHY Associate Professor School of Mechanical and Building Sciences VIT Chennai	Mr. S.Bharath Subramaniam, Assistant Professor, SRMIST
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	Mr. Udhayakumar Balaji Senior Piping Engineer Petrofac Engineering services India ltd	Dr. M. Cheralathan, SRMIST

Course Code	18MEE445T	Course Name	THERMAL ENERGY STORAGE SYSTEMS				Course Category	E	Professional Elective				L 3	T 0	P 0	C 3								
Pre-requisite Courses		18MEC101T-Thermodynamics		Co-requisite Courses		NIL		Progressive Courses		NIL														
Course Offering Department		Mechanical Engineering				Data Book / Codes/Standards			NIL															
Course Learning Rationale (CLR):		The purpose of learning this course is to:						Learning			Program Learning Outcomes (PLO)													
CLR-1 :	Familiarize with the techniques used for storing various forms of energy						1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Understand the sensible thermal energy storage systems and materials						Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Understand the latent and thermochemical energy storage systems.																							
CLR-4 :	Understand the properties of storage materials and heat transfer fluids																							
CLR-5 :	Know the various techniques used for storing thermal energy in heating/cooling applications and energy savings																							
CLR-6 :	Be familiar with the Thermal energy storage systems and its applications.																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1 :	Familiarize with the techniques used for storing various forms of energy						12&3	90	80	H	M					L							H	
CLO-2 :	Understand the sensible thermal energy storage, material and methodology						12&3	90	80	H	M					M							H	
CLO-3 :	Understand the latent and thermochemical energy storage systems.						1&2	90	80	H				H	M								H	
CLO-4 :	Understand the properties of storage materials and heat transfer fluids						1&2	90	80	H	L			L	H								H	
CLO-5 :	Know the various techniques used for storing thermal energy in heating/cooling applications and energy savings						12&3	90	80	H	L			M	M								H	
CLO-6 :	Be familiar with various techniques used for storing thermal energy in heating/cooling applications and energy savings																							
		Energy Storage		Sensible Thermal Energy Storage Systems		Latent Thermal And Thermochemical Energy Storage Systems		Thermal Energy Storage Materials		Thermal Storage Applications And Energy Savings														
Duration (hour)		9		9		9		9		9														
S-1	SLO-1	Basics of Energy storage and its types		Sensible Thermal Energy Storage (STES) system and its types		Latent Thermal Energy Storage (LTES) system and its types		Thermal energy storage materials - Classification, thermophysical properties		Cool Thermal Energy Storage (CTES) concept and comparison of storage technologies														
S-2	SLO-1	Energy storage by mechanical medium		Selection of sensible thermal energy storage materials and methodologies		Types and properties of latent heat storage materials and cooling/Heating load calculations		Various methods to improve the thermophysical properties of PCM		Cool thermal energy storage in process cooling														
S-3	SLO-1	Energy storage by chemical medium		Properties of sensible heat storage materials		Encapsulation techniques of LTES (PCM) materials		selection criteria for thermal energy storage materials		CTES systems building air conditioning applications														
S-4	SLO-1	Low and Medium temperature thermal storage systems		Sensible cooling and heating load calculations		Performance assessment of LTES system in building		Phase Change Materials – classifications and properties		Solar energy storage – passive heating and cooling, green house heating														
S-5	SLO-1	High temperature thermal storage systems		STES Technologies, storage tanks using water and rock bed thermal storage		Passive and active LTES systems		PCM selection for heating and cooling applications		Drying and heating for process industries														
S-6	SLO-1	Necessity of TES, types of TES technologies and Comparison of thermal energy storage technologies		Solar pond thermal storage and building structure thermal storage		Thermochemical energy storage principles and materials		Heat transfer fluids and properties		Solar power plant applications.														
S-7	SLO-1	Seasonal thermal energy storage Principle		Passive solar heating storage		Thermochemical energy storage systems - open adsorption energy storage system and closed adsorption energy storage system		Selection of heat transfer fluid for heating and cooling applications		TES and Energy Savings - utilization of waste or surplus energy, reduction of demand charges and deferring equipment purchases														
S-8	SLO-1	Seasonal (Source) TES technologies - aquifer thermal storage, borehole thermal storage and cavern thermal storage		Active solar heating storage		Closed absorption energy storage system solid/gas, thermochemical energy storage system and thermochemical accumulator energy storage system		Measuring instruments for thermophysical properties		Additional energy savings considerations for TES														

S-9	SLO-1	Earth-to-air thermal storage, energy piles thermal storage, sea water thermal storage, rock thermal storage and roof pond thermal storage	High temperature Sensible Thermal Energy Storage system	Floor heating system using thermochemical energy storage and thermochemical energy storage for building heating applications	Necessity of improving thermophysical properties	Case studies for TES energy savings
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Learning Resources	<ol style="list-style-type: none"> 1. R. Parameshwaran and S. Kalaiselvam, "Thermal Energy Storage Technologies for Sustainability: Systems Design, Assessment and Applications", Academic Press Inc, 23 September 2014. 2. Ibrahim Dincer and Marc A. Rosen, "Thermal Energy Storage Systems and Applications", 2nd Edition, John Wiley and Sons Ltd., 2011. 3. Luisa F. Cabeza, "Advances in Thermal Energy Storage Systems: Methods and Applications", October 31, 2014 4. Charles E. Dorgan, James S. Elleson, "Design Guide for Cool Thermal Storage", ASHRAE, Atlanta, 1993. 5. R. Velraj "Sensible heat Storage for solar heating and cooling systems" in the book titled "Advances in Solar Heating and Cooling - Pages 399 - 428, Elsevier Publication, 2016 6. ASHRAE, "Handbook of Fundamentals", American Society of Heating Refrigeration and Air Conditioning Engineers, New York, 1993. 7. Alternate fuels for IC Engines: Liquid fuels, Gaseous fuels - properties, advantages and disadvantages, Emissions from engines – Emission standards – Euro, BS
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers	Experts from Higher Technical Institutions	Internal Experts
Experts from Industry		
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	VELRAJ R Professor Institute for Energy Studies, Anna University Chennai 600 025 Email: velrajr@annauniv.edu	Mr. A.Sathishkumar Assistant Professor, Department of Mechanical Engineering SRM IST Email: sathishkumar.a@ktr.srmuniv.ac.in
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cwrde.drdo.in	Raju Abraham, Sc-F National Institute of Ocean Technology Chennai 600 100 Ph 044-6678 3339 Email: abraham@niot.res.i	Dr. M. Cheralathan Professor, Department of Mechanical Engineering SRM IST Email: cheralathan.m@ktr.srmuniv.ac.in

Course Code	18MEE446T	Course Name	Design of Heat exchangers				Course Category	E	Professional Elective				L	T	P	C							
													3	0	0	3							
Pre-requisite Courses		NIL		Co-requisite Courses		Heat and mass Transfer			Progressive Courses		NIL												
Course Offering Department		Mechanical Engineering				Data Book / Codes/Standards				NIL													
Course Learning Rationale (CLR):		The purpose of learning this course is to:				Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Gain knowledge on the basics of Heat Exchanger					1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Familiarize with Design Aspects of heat exchangers					Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Acquire the basic skills acquired to design the double pipe and shell and tube heat exchangers																						
CLR-4 :	Acquire the basic skills acquired to design the compact and plate heat exchangers																						
CLR-5	familiarize with the condensers and evaporators																						
CLR-6	familiarize with the design of heat exchangers																						
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																					
CLO-1 :	understand the fundamentals of heat exchanger					1	2	3	H			M											
CLO-2 :	Understand the various design aspects of heat exchangers					1	2	3	H			H	M										
CLO-3 :	Evaluate the design of double pipe and shell and tube heat exchangers					1	2	3	H	H	H	M											
CLO-4 :	Evaluate the design of compact and plate type heat exchangers					1	2	3	H	H	H	M											
CLO-5:	Familiarize with design of various types of condensers and evaporators					1	2	3	H	H	H	M											
CLO-4:	To understand with the design of heat exchangers					1	2	3	H	H	H	M											
		Fundamentals Of Heat Exchanger		Design Aspects Of Heat Exchangers		Double Pipe Heat Exchangers And Shell & Tube Heat Exchangers			Compact And Plate Heat Exchanger				Condensers And Evaporators										
Duration (hour)		9		9		9			9				9										
S-1	SLO-1	Introduction, classification of heat exchangers, Recuperator and Regenerator		Introduction, effect of turbulence,		Introduction, Thermal design and analysis of inner tube and outer tube			Classification of compact heat exchangers, Merits and Demerits of Compact heat exchangers				Types of Condensers,										
S-2	SLO-1	Geometry of Construction, Tubular, Plate heat exchangers		Effect of friction factor, pressure drop in tube side,		hydraulic design and analysis of inner tube and outer tube			Design of compact heat exchangers				Design of surface condensers- Down-flow										
S-3	SLO-1	Effect of Extended Surface Heat Exchangers Heat transfer Mechanisms,		Effect of Pressure drop in tube bundles.		Design of Double Pipe Heat Exchangers- parallel flow & counter flow-problems			Factors affecting of compact heat exchangers				Types of Condensers, Design of surface condensers- Central-flow										
S-4	SLO-1	Flow arrangements, Application, Selection of Heat Exchangers.		Heat Transfer and pumping power relationship		Design of Double Pipe Heat Exchangers- cross flow heat exchanger-			Design of plate heat exchangers				Design of evaporative condensers- Inverted flow &Regenerative										
S-5	SLO-1	Overall Heat transfer coefficient, LMTD method for Heat Exchanger analysis for parallel flow heat exchanger		Pressure Drop in Bends and fittings		Basic components of shell & tube heat exchangers			Factors affecting Design of plate heat exchangers				Design of evaporative condensers										
S-6	SLO-1	Overall Heat transfer coefficient, LMTD method for Heat Exchanger analysis for COUNTER flow heat exchanger		Effect of fins arrangement ant its geometry on heat transfer		Design of shell & tube heat exchangers			Operational characteristics of plate heat exchanger				Types of Evaporators,										
S-7	SLO-1	Overall Heat transfer coefficient, LMTD method for Heat Exchanger analysis for CROSS heat exchanger		Fouling of Heat exchangers, effect on heat transfer		Factors affecting in shell & tube heat exchangers			flow arrangements in plate heat exchangers				calculation of Evaporator surface and multiple evaporator										
S-8	SLO-1	ε NTU method for Heat Exchanger analysis		Problems in pressure drop and fouling in Heat exchangers		Shell side heat transfer. Pressure drop			Heat transfer and pressure drop calculations				calculation of Evaporator multiple effect										
S-9	SLO-1	Heat Exchanger design considerations - Material requirement Design codes and its requirement		Factors affecting performance of HE/PHE/Condensers/Evaporator		Problems on design of shell and tube heat exchangers and its applications			Applications of compact and plate heat exchanger				Factors affecting in condensers and evaporators of heat changers										

Learning Resources	<ol style="list-style-type: none"> 1. SadikKakac and Hongtan Liu, "Heat Exchangers Selection, Rating and Thermal Design", CRC Press,2002 2. Kern D.Q, "Process Heat Transfer", Tata McGraw Hill , 1997, Reprint 2008 3. Ramesh K. Shah, "Fundamentals of Heat Exchanger Design", John Wiley & Sons,2003 4. Arthur. P Frass, "Heat Exchanger Design", John Wiley & Sons, 1988. 5. Taborek.T, Hewitt.G.F and Afgan.N, "Heat Exchangers, Theory and Practice", McGraw-Hill Book Co.2018 6. Kuppam T, "Heat Exchanger design handbook", Marcel Dekker INC, 2000. 7. Standards of Tubular Exchanger Manufacturers Association(TEMA), 9th Edition,2007 – www.tema.org 8. Wolverine Heat Transfer Data book – III by Wolverine Tube Inc.,
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers	Experts from Higher Technical Institutions	Internal Experts
Experts from Industry		
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	Dr. K Karuppasamy Assistant Professor Department of Mechanical Engineering Anna University Regional Campus Tirunelveli - 627 007	Mr. G.Manikandaraja Assistant Professor, Department of Mechanical Engineering SRM IST Email: manikandaraja.g@ktr.srmuniv.ac.in
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	K.Pasupathi Deputy manager – mechanical- AQUATHERM Engineering Consultants(India) Pvt. Ltd.,	Mr. S. Malarmanan Assistant Professor, Department of Mechanical Engineering SRM IST Email: malarmanan.s@ktr.srmuniv.ac.in

Course Code	18MEE447T	Course Name	COMBUSTION ENGINEERING	Course Category	E	Professional elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18MEC101T Thermodynamics	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Acquire the fundamental knowledge of combustion	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Gain knowledge on thermodynamics of combustion	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Understand the kinetics of combustion	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Understand the types of flames	Expected Attainment (%)	Design & Development
CLR-5 :	Familiarize with combustion aspects in SI and CI engines		Analysis, Design, Research
CLR-6 :	Acquire knowledge on combustion reactions and its stages in internal combustion engines		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Learning	Program Learning Outcomes (PLO)
CLO-1 :	Acquire the knowledge of combustion equations for different air fuel ratios	1&2 90 80	H M
CLO-2 :	Analyzecom combustions based on first law and second law of thermodynamics in reacting systems	1 90 80	H H
CLO-3 :	Evaluate the kinetic of combustion and reaction order and its theory	1 90 80	H H M
CLO-4 :	Acquire the knowledge of flames characteristics and its types	1&2 90 80	H H M
CLO-5 :	Understand the stages of combustion in SI and CI engines and acquire knowledge with normal and abnormal combustion.	1&2 90 80	H
CLO-6 :	Understand the emission norms and its control method	1 90 80	H

		Combustion Of Fuels	Thermodynamics Of Combustion	Kinetics Of Combustion	Flames	Engine Combustion
Duration (hour)		9	9	9	9	9
S-1	SLO-1	Combustion engineering and its importance	Thermo-chemistry first law analysis of reacting systems	Rates of reaction	Different types of flames Laminar and turbulent	Combustion in SI and CI engines
S-2	SLO-1	Combustion behavior with different air composition	To understand the reacting system and calculations on first law of thermodynamics	Determination of rates of reaction	Premixed and diffusion flames	Stages of combustion in SI and CI engines,
S-3	SLO-1	Combustion equations for Theoretical air	Acquire knowledge on Adiabatic combustion Temperature	Reaction order and molecularity complex reactions	Laminar Jet Flame Height – Turbulent flame Lift-Off Height and Blowout Limit.	Advanced techniques of combustion in IC engines-learn burn engine –HCCI engine
S-4	SLO-1	Combustion equations for excess air	Adiabatic combustion Temperature calculations	Determination of reaction order and molecularity complex reactions	Fuel burning velocity, Determination of Burning velocity, Factors affecting burning velocity	Normal combustion and abnormal combustion
S-5	SLO-1	Proper Air fuel ratio for combustion	Second law analysis of reacting systems	Chainreactions - Arrhenius rate equation, collection theory	Droplet Evaporation and Combustion	Emission norms in Heavy duty and light duty vehicles and its standards BS and Euro norms
S-6	SLO-1	Equivalence Ratio	Criterion for chemical Equilibrium	Calculation on Chain reactions - Arrhenius rate equation, collection theory	Flame Quenching, flammability	Emissions from premixed combustion
S-7	SLO-1	Exhaust gas composition	Determination of equilibrium constant for gaseous mixtures	Activated complex theory	Flame by ignition	Emission from non-premixed combustion
S-8	SLO-1	Air fuel ratio from exhaust gas composition	Evaluation of equilibrium composition	Explosive and general oxidative	Flame stabilization in open burners	Reasons of HC, sulphur , PM, NO _x and CO emissions in engines
S-9	SLO-1	Heating value of fuels	Chemical availability	Characteristics of fuels on Explosive and general oxidative	Methods to stabilize the flame in open burner	Control of HC, sulphur , PM, NO _x and CO emissions in engines

Learning Resources	1. Stephen.R.Turns, "An Introduction to Combustion concepts and applications", 2nd Edition, McGraw Hill Book Company, Boston, Edition 3,2011. 2. Ganesan.V, "Internal Combustion Engines", Tata McGraw-Hill, New Delhi,2009. 3. Ramalingam.K.K, "Internal Combustion Engines - Theory and practice",SciTech Publications India Pvt. Ltd., Chennai, 2010. 4. Thipse.S.S, "Internal Combustion Engines", Jaico Publication House, 2010. 5. Thipse.S.S, "Alternate Fuels", Jaico Publication House., 2010. 6. Mathur.M.L, and Sharma.R.P, "A course in Internal Combustion Engines",Dhanpat Rai & Sons, New Delhi, 2010. 7. Heywood.J.B, "Internal Combustion Engine Fundamentals", McGraw Hill International, New York, 2008. 8. Domkundwar.V.M, "A course inInternal Combustion Engines", Dhanpat Rai & Sons, 2010.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers					
Experts from Industry		Experts from Higher Technical Institutions		Internal Experts	
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in		Dr. K.KarunamurthyAssociate Professor, Department of Mechanical Engineering VIT –Chennai campus		Mr. M.Sivashankar Assistant Professor, Department of Mechanical Engineering SRM IST –KTR campus	
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in		Mr.P.Balaji Manager Product Development HVAC Division Ashok LeylandChennai		Dr. M. Cheralathan, SRMIST	

Course Code	18MEE448T	Course Name	SUSTAINABLE ENERGY SYSTEMS	Course Category	E	Professional Elective	L 3	T 0	P 0	C 3
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Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
					1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
					Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-1 :	be familiar with the energy scenario						H							M								
CLR-2 :	be familiar with environmental impact of energy generation						H			M				H								
CLR-3 :	understand the various energy conservation options and measures						H			M				H					L			
CLR-4 :	be familiar with the energy policies						H							H					L			
CLR-5 :	be familiarwith the sustainable development and life-cycle analysis						H							H					L			
CLR-6 :	be familiar with energy conservation, policies and sustainability of energy systems.						H			M				H								
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	acquire knowledge on the energy scenario.				1&2	90	80	H						M								
CLO-2 :	acquire knowledge on environmental impactof energy generation				1,2&3	90	80	H			M			H								
CLO-3 :	acquire knowledge on basic the energy conservation measures				1,2&3	90	80	H			M			H					L			
CLO-4 :	understand the basic energy policies				1	90	80	H						H					L			
CLO-5 :	acquire knowledge on basic the sustainable development and life-cycle analysis				1	90	80	H						H					L			
CLO-6 :	acquire knowledge on energy conservation, policies and sustainability of energy systems.				1,2&3	90	80	H			M			H								

Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:		
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CLO-1 :	<i>acquire knowledge on the energy scenario.</i>	1&2	90	80
CLO-2 :	<i>acquire knowledge on environmental impact of energy generation</i>	1,2&3	90	80
CLO-3 :	<i>acquire knowledge on basic the energy conservation measures</i>	1,2&3	90	80
CLO-4 :	<i>understand the basic energy policies</i>	1	90	80
CLO-5 :	<i>acquire knowledge on basic the sustainable development and life-cycle analysis</i>	1	90	80
CLO-6 :	<i>acquire knowledge on energy conservation, policies and sustainability of energy systems.</i>	1,2&3	90	80

Duration (hour)		Energy scenario	Environmental impact of energy generation and utilization	Energy conservation	Sustainable development and Energy policies	Life-cycle assessment and Ecology
		9	9	9	9	9
S-1	SLO-1	Basics of sustainability and sustainable energy sources	Global warming and acid precipitation,	Energy conservation measures	Sustainable energy strategies	General description of LCA
S-2	SLO-1	Introduction to conventional energy resources	Analysis of modeling of earth's climate,	Improvement Factors of Energy Conservation	Key expectations from implementation of green energy strategies and policies	LCA methodology
S-3	SLO-1	Introduction to non-conventional energy resources	Radiation balance of earth planet	Energy conservation case studies	Interdependence of the factors affecting sustainable development	Energetic life-cycle analysis
S-4	SLO-1	World energy scenario – Conventional energy sources.	Greenhouse gases and radiative forcing Concept	Energy management-understanding energy costs, Bench marking, Energy performance	Modeling instruments and case studies	
S-5	SLO-1	World energy scenario – Non-Conventional energy sources.	Global warming potentials	Energy management policies	Sustainable assessment of solar energy	LCA of solar PV and thermal systems
S-6	SLO-1	Indian energy scenario – Conventional energy sources.	Anthropogenic effect on climate and its control	Energy conservation in thermal systems	Sustainable assessment of fossil fuel	LCA of hydrogen-fuel cell vehicles
S-7	SLO-1	Indian energy scenario – Non-Conventional energy sources.	Impact of energy efficiency	Energy conservation in electrical systems	fossil fuel combustion	LCA of gasoline vehicles
S-8	SLO-1	Energy forecasting	other environmental impact aspects and cogeneration	Introduction to energy audit	Assessment of green energy strategies	Case study, comparative LCA of hydrogen-fuel cells vs gasoline vehicles
S-9	SLO-1	Energy security	Problems in cogeneration	Case study in energy audit	Green energy-based sustainability ratio	Case study, comparative LCA of conventional and alternative vehicles

Learning Resources	<ol style="list-style-type: none"> 1. Dincer, C. Zamfirescu, "Sustainable Energy Systems and Applications", Springer, 2012. 2. Frank Kreith, Susan Krumdieck, "Principles of Sustainable Energy Systems", 2nd Edition, Taylor & Francis, 2014. 3. Muthu, Subramanian Senthilkannan, "Social Life Cycle Assessment An Insight", Springer, 2015. 4. Demirel, Yaşar, "Energy Production, Conversion, Storage, Conservation, and Coupling", Springer, 2016. 5. https://beeindia.gov.in/sites/default/files/1Ch1.pdf 6. http://www.mospi.nic.in/sites/default/files/publication_reports/Energy_Statistics_2017r.pdf
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Understand	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	Dr. R.Velraj, Professor, Institute for Energy Studies, Anna University, Chennai, India - 600025	S. Arul Kumar, SRMIST.
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	Dr.Raju Abraham, Scientist –F, National Institute of Ocean Technology Chennai – 600 100	Dr.S. Manikandan, SRMIST.

Course Code	18MEE449T	Course Name	FUEL CELL TECHNOLOGY				Course Category	E	Professional Elective				L	T	P	C								
													3	0	0	3								
Pre-requisite Courses		Nil		Co-requisite Courses		Nil		Progressive Courses		Nil														
Course Offering Department		Mechanical Engineering				Data Book / Codes/Standards				Nil														
Course Learning Rationale (CLR):		The purpose of learning this course is to learn:				Learning			Program Learning Outcomes (PLO)															
CLR-1:	The basics of fuel cell technology								1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13
CLR-2:	The concepts of fuel cell electrochemistry					Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3	
CLR-3:	The major types of fuel cells and their modes of operation																							
CLR-4:	The methods of production, storage and utilization of hydrogen as a fuel																							
CLR-5:	The application of fuel cells in power cogeneration																							
CLR-6:	The Safety issues and cost expectation																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:							H						H									
CLO-1:	Understand the basics of fuel cell and fuel cell thermodynamics					1&2	90	80	H															
CLO-2:	Understand the fuel cell electrochemistry&Implications and use of fuel cell polarization curve.					1&2	90	80	H						H									
CLO-3:	The major types of fuel cells and their modes of operation such as Polymer electrolyte membrane fuel cell,Direct methanol fuel cells,Alkaline fuel cell,Molten Carbonate fuel cell&Solid oxide fuel cell					1&2	90	80	H						H									
CLO-4:	The methods of production, storage and utilization of hydrogen as afuel					1&2	90	80	H															
CLO-5:	The methods of production, storage and utilization of hydrogen as afuel					1&2	90	80	H															
CLO-6:	Understand the Fuel Processor &Safety issues and cost expectation					1	90	80	H						H									
		Introduction to Fuel Cells And Fuel Cell Thermodynamics		Fuel Cell Electrochemistry		Types Of Fuel Cells		Hydrogen Production, Storage And Utilization				Application Of Fuel Cells In Power Cogeneration												
Duration (hour)		9		9		9		9				9												
S-1	SLO-1	Introduction and overview of fuel cell technology: A simple fuel cell, fuel cell advantages and disadvantages		Fuel cell reaction kinetics		Classification of fuel cells		Hydrogen: Its merit as a fuel, Production methods: from fossil fuels, electrolysis, thermal decomposition				Fuel cell power plant, Balance of fuel cell power plant.												
S-2	SLO-1	Basic fuel cell operation, Layout of a Real Fuel Cell: The Hydrogen–Oxygen Fuel Cell with Liquid Electrolyte.		Introduction to electrode Kinetics.		Polymer electrolyte membrane fuel cell (PEMFC)		Production method from photochemical.				Fuel cell power plantstructure.												
S-3	SLO-1	Difference between fuel cell and batteries, fuel choice.		Electro Chemical Energy Conversion – Factors affects Electro Chemical Energy Conversion.		Direct methanol fuel cells (DMFC)		Production method from photocatalytic, hybrid.				Cogeneration												
S-4	SLO-1	Overview of types of fuel cells (with emphasis on PEMFC and DMFC technology)		Conversion of chemical energy to electricity in a fuel cell		Alkaline fuel cell (PAFC)		Hydrogen storage methods: Onboard hydrogen storage.				Benefits and Drawbacks of fuel cell power plant.												
S-5	SLO-1	Fuel cell thermodynamics: Thermodynamics review, Application of first and second law to fuel cells		Reaction rate		Molten Carbonate fuel cell (MCFC)		Chemical storage & physical storage.				Fuel cell electric vehicles.												
S-6	SLO-1	Heat Potential of a fuel: Enthalpy of reaction, Work potential of a fuel: Gibbs free energy		Butler -Volmer equation.		Solid oxide fuel cell (SOFC)		In metal and alloy hydrides.				Motor cycles and bicycles, airplanes												
S-7	SLO-1	Predicting reversible voltage of a fuel cell under nonstandard-stateconditions.		Fuel cell charge		Comparison of fuel cell,		Carbon nanotubes.				Fueling stations.												
S-8	SLO-1	Basic Parameters of Fuel Cells. Fuel cell efficiency.		Mass transport.		Performance behavior		Glass capillary arrays - pipeline storage and hydrogenutilization.				Fuel processor and fuel cell stack.												
S-9	SLO-1	Basic Parameters of Fuel Cells. Fuel cell efficiency.. Comparison with Carnot efficiency.		Implications and use of fuel cell polarization curve.		Proton Exchange Membrane Fuel Cells.		Glass capillary arrays - pipeline storage and hydrogenutilization.				Safety issues and cost expectation.												

Learning Resources	1. O'Hayre, R. P., S. Cha, W. Colella, F. B. Prinz, "Fuel Cell Fundamentals", Wiley, NY 2006.
	2. Viswanathan. B. AuliceScibioh, M, "Fuel Cells – Principles and Applications", Universities Press (India) Pvt., Ltd., 2009.
	3. Bagotsky .V.S, "Fuel Cells",Wiley, 2009.
	4. DetlefStolten, "Hydrogen and Fuel Cells: Fundamentals, Technologies and Applications", 2010
	5. Larminie .J, Dicks A. "Fuel Cell Systems", 2nd Edition, Wiley, 2003.
	6. Barclay .F.J. "Fuel Cells, Engines and Hydrogen", Wiley, 2009.

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry		Experts from Higher Technical Institutions
Internal Experts		
Babu C Chief Consultant Conserve Consultant private Limited Hyderabad		Dr. Joseph Daniel, Associate Professor, School of Mechanical and Building Sciences, VIT Chennai
Mr. S. Rajendra Kumar, SRMIST		
C. Anand Raj, Head Green Initiative, Infosys Chennai		Dr. Rayapati Subbarao, Associate Professor, NITTR Kolkata
Mr. V. Thirunavukkarasu, SRMIST		

Course Code	18MEE450T	Course Name	MODELING OF THERMAL SYSTEMS	Course Category	E	Professional Elective	L 3	T 0	P 0	C 3
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Pre-requisite Courses	Thermodynamics Fluid Mechanics Heat Transfer	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):		The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand the fundamentals of the thermal system design		1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	DevelopMathematical models for the thermal systems		Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Apply numerical analysis to solve the mathematical models																			
CLR-4 :	Familiarize with different optimization methods																			
CLR-5 :	Apply optimization methods in problem solving of thermal systems																			
CLR-6 :	Evaluate the economic factors involved in design and application of thermal systems																			
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																		
CLO-1 :	Understand system design and steps involved in the formulation of the design process		1& 2	85	75	H	M	M	M							L				
CLO-2 :	Development of mathematical models from the physical system		1&2	85	75	H	H	M	H							M				
CLO-3 :	Solve the mathematical models using numerical analysis		1&2	85	75	H	H	M	H							M				
CLO-4 :	Explore optimization methods to provide feasible solutions in the design of thermal systems		1&2	85	75	H	H	M	H							H				
CLO-5 :	Evaluate the economic factors in the design and application of thermal systems		1,2& 3	85	75	H	H	H	H							H				
CLO-6 :	familiarize with design and analysis of the thermal systems		12&3	85	75	H	H	M	H							H				

Title of the module		Introduction to Thermal System Design	Mathematical Modeling of Thermal systems	Numerical Analysis of Thermal Systems	Optimization Methods	Economics and Financial Aspects of thermal system
Duration (hour)		9	9	9	9	9
S-1	SLO-1	Engineering design;Design Versus Analysis, Synthesis for Design	Importance of Modeling in Design, Basic Features of Modeling	Numerical Model for a System	Optimization; basic concepts, optimization methods	Calculation of Interest, Simple Interest, Compound Interest, Effective Interest Rate
S-2	SLO-1	Need for optimization; Thermal system design	Types of Models; Analog Models, Mathematical Models, Physical Models, Numerical Models, Interaction Between Models	Modeling of Individual Components	Optimization of Thermal Systems, Practical Aspects in Optimal Design	Profitability estimate; Cost of return earnings
S-3	SLO-1	Basic Characteristics of thermal design; Analysis Types	Development of Mathematical Modeling, General Procedure, Final Model and Validation	System Simulation, Importance of Simulation Methods for Numerical analysis	The Lagrange Multiplier Method, Basic Approach, and Physical Interpretation,	Data requirements for calculation of various cash flow techniques
S-4	SLO-1	Formulation of the Design Problem, Variables, Constraints and Limitations	Physical Modeling, Dimensional Analysis, Modeling and Similitude	Simulation: Steady& Lumped Systems	Significance of the Multipliers, Optimization of Unconstrained Problems	Financial analysis; Discounted & non discounted cash flow techniques
S-5	SLO-1	Design Types; Conceptual Design, Innovative Conceptual Design ; Modifications in the Design of Existing Systems	Development of a Numerical Model Solution Procedures	Dynamic Simulation of Lumped Systems	Search Methods, Basic Considerations, Importance of SearchMethods,	Pay back period method; Average rate of return (ARR) method
S-6	SLO-1	Steps involved in the Design Process	Curve Fitting; Exact Fit, Best Fit	Distributed systems, simulation of large systems	Golden Search method and typical exercise problem	Simple problems on pay back and ARR
S-7	SLO-1	Problems on Thermal Resistance and Capacitance	Problems on exact fit	Numerical Simulation Versus Real System,	Fibonacci Search method	Net present value method (NPV); Profitability Index method (PI) ; Simple problems
S-8	SLO-1	Problems on Building Heating with variable temperatures	Problems on best fit	Design of Systems for Different Application	Problems on Fibonacci Search method	Internal rate of return method (IRR) & Benefit cost method (BCR); Simple Problems
S-9	SLO-1	Problems on unsteady state heat transfer	Problems on nonlinear least squares	Problem on numerical modeling of fluid flow systems	Steepest Ascent/Descent Method	Comparison between NPV and IRR methods

Learning Resources	<ol style="list-style-type: none"> 1. Y Jaluria, "Design and optimization of thermal systems", Tata McGraw Hill, 3rd Edition, New Delhi, 2007 2. W F Stoecker, "Design of thermal systems", Tata McGraw Hill, 3rd Edition, New Delhi, 1989. 3. C Balaji, "Essentials of Thermal System Design and Optimization,," Ane Books, New Delhi 2014 4. J S Arora, "Introduction to optimum design", Elsevier Publication, 3rd Edition, 2012 5. Bender.E.A, "Introduction to Mathematical Modeling", Dover Publication, 2000
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Expert
R. Mohan Prabhu Senior Engineer, Compression GEA Group, Pune, India	Dr. VenkataRamanan Professor, Institute of Energy Studies Anna University, Guindy Campus, Chennai – 600025	Dr. S. Shashi Kumar, SRMIST
Joseph ShekharSanthappan Faculty Mechanical Section, Engg. Dept. Shinas College of Technology, Al-Agur, Shinas, Sultanate of Oman.	Dr. R. Chandrasekhar Research Scientist Dept. of Electrical and Computer Engineering, Colorado State University Fort Collins, Colorado Area, USA	Dr. M. Cheralathan, SRMIST

Course Code	18MEE701J	Course Name	SENSORS AND ACTUATORS FOR AUTOMATION	Course Category	E	Professional Elective	L	T	P	C
							2	0	2	3

Pre-requisite Course	Nil	Co-requisite Course	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book/Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Expose the basics of various sensors used in automation	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Impart the fundamental concept of electro-mechanical and fluid power systems	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Provide exposure on practical knowledge of sensors and its measurements	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Impart knowledge in mechanical, magnetic and electromechanical sensors	Expected Attainment (%)	Design & Development
CLR-5 :	Provide the knowledge on the working principle of hydraulic, pneumatic, mechanical and electrical actuators		Analysis, Design, Research
CLR-6 :	Impart the fundamental concept of drives and control system		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Understand the different types of sensors used in automation	1 85 80	H - M - H - - - - - - - - - - - - - - - -
CLO-2 :	Identify suitable sensor for the developments of automation processes	2 90 85	H M L L H - - - - - - - - - - - - - - - -
CLO-3 :	Develop the automation system by integration of electromechanical sensors and fluid power systems	3 90 80	H H H M H - - - - - - - - - - - - - - - -
CLO-4 :	Identify the type of actuators and its associated drivers for different application	2 85 80	H M - - H - - - - - - - - - - - - - - - -
CLO-5 :	Demonstrate effective use of actuators, its elements for the generation, control and conversion of energy for the typical automation system	2 90 80	H - - - H - - - - - - - - - - - - - - - -
CLO-6 :	Build real time automation system within realistic constraints such as industrial, economic, environmental, ethical, social, health and safety	3 95 85	H M M M H M M L L - - - - - - - - - - -

Duration (hour)	12	12	12	12	12
S-1	SLO-1 Role of sensors in manufacturing: Importance of estimation in sensing	Resistive sensors: Potentiometer	Fiber optic sensors – Temperature sensors	Pneumatic systems – Types, components	Mechanical systems – Types of motion
	SLO-2 Role of sensors in manufacturing: Innovative sensor technologies	Resistive sensors: Strain gauge	Fiber optic sensors – Liquid level sensing	Pneumatic systems – working principle	kinematics chains
S-2	SLO-1 Physical transduction principles: Mechanical, Thermal	Inductive sensors: Methods of achieving inductance	Fluid flow level sensing	Hydraulic systems – Types, components	Cams, gears, ratchet and pawl
	SLO-2 Physical transduction principles: Electrical, Magnetic	Ferromagnetic plunger type, Transformer type	Micro bend sensing	Hydraulic systems – working principle	belt and chain drives
S-3	SLO-1 Classification of sensors: property based	Capacitive sensors: parallel plate capacitive sensor	Film sensors – Thick film sensors	Directional control of valves	Electrical systems – mechanical switches
	SLO-2 Classification of sensors: applications based	Serrated plate capacitive sensor	Thin film sensors	Valve symbols	solid state switches
S-4	SLO-1 Characterization: Electrical	Force/stress sensors using Quartz Resonators	Nano sensors - Introduction	Pressure control valves	Solenoids
	SLO-2 Characterization: Mechanical	Various beam designs	Nano structure, operation mechanism	Cylinders	DC motors
S-5	SLO-1 Characterization: Thermal, Optical	Ultrasonic sensors: introduction	Smart sensors –Introduction, properties	Rotary Actuators (Hydraulic type) components	Stepper motors – introduction, specifications
	SLO-2 Characterization: Biological and Chemical	Principles, Materials, Applications	Smart sensors – primary sensors, Compensation	Working principle	Stepper motors – types
S-6	SLO-1 Static characteristics of sensors	Magnetic sensors: Types	Functional integration of sensors	Rotary Actuators (Pneumatic type) components	Stepper motor – control
	SLO-2 Dynamic characteristics of sensors	Magnetic sensors: working principles	Smart sensors – information coding/processing	Working principle	Stepper motor - characteristics
S 7-8	SLO-1 Lab 1: Measurement of speed and displacement using linear and rotary sensors	Lab 4: Temperature measurement using RTD and thermocouple	Lab 7: Study on eddy current sensor for thickness measurement	Lab 10: Simulation of single and double acting cylinder circuits using different directional control valves	Lab 13: Speed and torque characterization and sequence control of stepper motor
	SLO-2				

S 9-10	SLO-1	Lab 2: Force and Torque measurement using strain gauge	Lab 5: Experimentation on voltage, current, power, and frequency measurement	Lab 8: Study on ultrasonic sensors for material fault diagnosis	Lab 11: Sequencing of pneumatic circuits	Lab 14: Closed loop position and velocity control of a DC servo motor
	SLO-2					
S 11-12	SLO-1	Lab 3: Pressure measurement system using sensors	Lab 6: Experimentation with tactile sensor for force and touch detection	Lab 9: Simulation of hydraulic circuits in a hydraulic trainer	Lab 12: Simulation of logic and electro-pneumatic circuits	Lab 15: Speed and torque characterization and control of DC motors
	SLO-2					

Learning Resources	1. Patranabis D., "Sensor and Actuators", Prentice Hall of India (Pvt) Ltd., 2013. 2. Bolton W., "Mechatronics", Fourth edition, Pearson publishers, 2010. 3. Andrzej M. Pawlak., "Sensors and Actuators in Mechatronics – Design and Applications", CRC press, Taylor and Francis group, 2007.			4. Clarence W de Silva, "Sensors and Actuators – Engineering system instrumentation", second edition, CRC press, Taylor and Francis group, 2016. 5. Ian R. Sinclair, "Sensors and Transducers", third edition, Newnes, 2001. 6. R.K.Rajput, "A text book of Mechatronics", S.Chand & Company Limited, Second edition, 2009.		

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% Weightage)								Final Examination (50% Weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100%		100%		100%		100%		100%	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. P.Kartikeyan, Head – Operations Improvement, Nokia India, kartikeyan.p@nokia.com	1. Dr.K.Senthilkumaran, Assistant professor, IIITDM, Kancheepuram. skumaran@iiitdm.ac.in	1. P.Haja Syeddu Masooth, SRM IST
2. Dr. R. Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	2. Dr.B.Mohan, Professor, Anna University, mohan@mitindia.edu	2. Dr.R.Rajaraman, SRM IST
3. Dr. A. Velayutham, DRDO, Avadi, velayutham.a@cvrde.drdo.in		

Course Code	18MEE702J	Course Name	MICROPROCESSOR AND MICROCONTROLLERS	Course Category	E	Professional Elective	L	T	P	C
							2	0	2	3

Pre-requisite Course	Nil	Co-requisite Course	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book/Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Expose the basics of microprocessors	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Introduce the need and use of Interrupt structure	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Impart the applications of microprocessor	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Enable to understand the architecture of microcontroller	Expected Attainment (%)	Design & Development
CLR-5 :	Expose the instruction set and register set of microcontroller		Analysis, Design, Research
CLR-6 :	Impart knowledge about different peripheral interfacing devices		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Understand the basics of microprocessors	1 95 90	H L M L H - - - L - - L M - M
CLO-2 :	Use the processors for various applications	3 90 85	H L L M M - - - L - - L M - H
CLO-3 :	Develop the assembly language programs	1 85 80	H L L L M - - - M - - L M - L
CLO-4 :	Understand the interfacing techniques	3 80 75	H L L M H - - - M - - L M - M
CLO-5 :	Understand the internal architecture of microcontroller	2 80 75	H L L M M - - - M - - L M - L
CLO-6 :	Use microcontroller with different peripherals	3 90 85	H L M M H - - - H - - L H - M

Duration (hour)	12	12	12	12	12
S-1	SLO-1	Introduction to 8086 microprocessor- Internal Architecture	Peripherals and Interfacing-Interfacing I/O Ports	Application of Microprocessor- Microprocessor based Aluminium Smelter Control, Process Description	Introduction to 8051 Microcontroller- Microcontroller Block Diagram
	SLO-2	Physical Memory Organization	Interfacing I/O Ports		Microcontroller Block Diagram
S-2	SLO-1	Addressing Modes	8086 Interrupts	Microprocessor based Aluminium Smelter Control, Process Description	Instruction Set
	SLO-2		Interrupt Responses		
S-3	SLO-1	Instruction Set	Direct Memory Access (DMA)	Lab 7: Program to perform following conversion : BCD to ASCII	Register Set
	SLO-2		I/O Mode	BCD to hexadecimal	
S-4	SLO-1	Lab1: Basic arithmetic operations	Lab 4: Sorting of array in: Ascending order	Design of Microprocessor based Pattern Scanner System	Lab 10: A/D and D/A converter interface
	SLO-2		Lab 4: Sorting of array in: Descending order	BCD to hexadecimal	Lab 13: Fabrication of 8-bit LED interfaces for 8085 kit through 8155 and 8255
S-5	SLO-1				
	SLO-2				
S-6	SLO-1	I/O Addressing Capability	Interfacing Analog to Digital Data Converters	Design of Microprocessor based Pattern Scanner System	Memory
	SLO-2			BCD to hexadecimal	I/O Addressing
S-7	SLO-1	General Bus Operation	Interfacing Digital to Analog Converters	Lab 8: Program to demonstrate decision making and looping operation	Interrupts
	SLO-2				
S-8	SLO-1	Lab2: Basic Logical operations	Lab 5: Program to demonstrate string manipulations	Design of an Electronic Weighing Bridge	Lab 11: Key board and Display
	SLO-2				
S-9	SLO-1				
	SLO-2				

S-10	SLO-1	Assembler Directives	Stepper Motor Interfacing	Design of an Electronic Weighing Bridge	Design of Microcontroller based Length Measurement System for Continuously Rolling Paper	DC motor Interfacing
	SLO-2	Operators				PWM
S-11	SLO-1	Lab 3: Transfer of block to another location in reverse order	Lab 6: Program to demonstrate Factorial of given numbers	Lab 9: Program to demonstrate parameter passing methods	Lab 12: Stepper motor interface	Lab 15: Interfacing DC motor and Servo motor
	SLO-2					
S-12	SLO-1					
	SLO-2					

Learning Resources	<ol style="list-style-type: none"> 1. A K Ray and K M Bhurchandi, "Advanced Microprocessor and Peripherals", McGraw Hill Education private Limited , 2011. 2. Krishna Kant, "Microprocessors and Microcontrollers", Eastern Economy Edition, PHI learning private ltd, 2012. 3. Douglas V Hall and SSSP Rao, "Microprocessors and Interfacing", Pearson Education, 2012. 	<ol style="list-style-type: none"> 4. Muhammad Ali Mazidi, Janice Gillispie Mazidi, Rolin D.Mckinlay, "The 8051 Microcontroller and Embedded Systems", McGraw Hill Education private Limited, 2008. 5. Ramesh S. Gaonkar, Microprocessor Architecture. Programming and Applications with the 8085, 5th ed., Penram International Publishing (India) Private Limited. 2005
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% Weightage)								Final Examination (50% Weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100%		100%		100%		100%		100%	

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. P.Kartikeyan, Head – Operations Improvement, Nokia India, kartikeyan.p@nokia.com	1. Dr.K.Senthilkumaran, Assistant professor, IIITDM, Kancheepuram. skumaran@iiitdm.ac.in	1. Eastus Russel, SRMIST
2. Dr. R. Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	2. Dr.B.Mohan, Professor, Anna University, mohan@mitindia.edu	2. Dr.R.Rajaraman, SRMIST
3. Dr. A. Velayutham, DRDO, Avadi, velayutham.a@cvrde.drdo.in		

Course Code	18MEE703T	Course Name	INDUSTRIAL ROBOTICS AND AUTOMATION	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Course	Nil	Co-requisite Course	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book/Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Introduce the basics of robotic technology and its applications	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Impart knowledge on robot motion analysis and control	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Explore the application of robot in manufacturing and assembly	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Impart knowledge on automation and control technologies in manufacturing	Expected Attainment (%)	Design & Development
CLR-5 :	Introduce the concept of automated material transport systems		Analysis, Design, Research
CLR-6 :	Impart knowledge on fundamentals and applications of automated production lines		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Understand the basics of robot anatomy, control and sensing system	1 90 85	M L L L M - L - M L L - H - H
CLO-2 :	Gain knowledge on robot manipulator kinematics, path control and dynamics	2 90 85	H M L M M - M - L M L - H - L
CLO-3 :	Understand the application of robot in manufacturing and assembly	2 90 85	M M M L M L M - M H L - H - M
CLO-4 :	Gain knowledge on various elements of automations in manufacturing	2 90 85	L M L M H - L - L L M - H - H
CLO-5 :	Understand the concept of automated guided vehicle system for shop floor application	2 90 85	M L L M H - L - L L M - H - M
CLO-6 :	Gain knowledge on automated storage and retrieval system and automated assembly system	2 90 85	M M L M M - L - M H M - H - H

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction to Robotics	Introduction to manipulator kinematics – position representation	Robot Applications in Manufacturing:	Automation in production systems	Automated material transport systems, storage system and assembly system : Introduction
	SLO-2	History of Robots	forward and reverse transformation of the 2 degree of freedom arm	General consideration in Robot Material Handling	Automated manufacturing system	Automated Guided Vehicle system
S-2	SLO-1	Robot Anatomy	3 degree of freedom arm in two dimensions	Material Transfer Application – pick and place operations	Computerized manufacturing and support systems	AGV types
	SLO-2	Components	4 degree of freedom manipulator in three dimensions	Palletizing and related operations	Reasons for automating	Applications
S-3	SLO-1	Work Volume	Homogeneous transformations and Robot kinematics, parallel kinematics	Machine Loading and unloading	Automation principles and strategies – The USA principle	Vehicle Guidance
	SLO-2	Polar, cylindrical and cartesian	Kinematic equations using Homogeneous transformations	Die casting, plastic moulding	Strategies for Automation and process improvement	Routing
S-4	SLO-1	Robot drive systems	Solving the kinematic equations	Forging and related operations	Automation Migration strategy	Traffic Control
	SLO-2	Hydraulic drive	Examples	Machining operations, Stamping press operations	Manual, automated and automated integrated production	Safety

S-5	SLO-1	Electric drive	A discussion on orientation	Robots used in Spot welding	Basic elements of an Automated System	System Management
	SLO-2	Pneumatic drive	Roll, pitch and yaw for a manipulator wrist mechanism	Application and benefits	Power to accomplish the Automated Process	Autonomous intelligent vehicle
S-6	SLO-1	Control systems	Manipulator path control – motion types	Robots used in Continuous Arc welding	Program of instructions	Automated storage Systems
	SLO-2	Dynamic performance	joint space schemes	Problems for Robots in Arc welding, applications, features of the welding robot, sensors, advantage and benefits	Control system	Retrieval Systems
S-7	SLO-1	Precision of Movement, Spatial resolution	Robot dynamics analysis,	Robots used in Spray Coating, and additive manufacturing	Advanced automation functions –	Carousel Storage Systems.
	SLO-2	Accuracy, Repeatability	Static analysis,	Application and benefits	Safety monitoring,	
S-8	SLO-1	End Effectors – grippers	Compensating for gravity,	Other Processing operation using Robots	Maintenance and repair diagnostics,	Automated assembly system –
	SLO-2	tools	Robot arm dynamics	Drilling, Grinding, Riveting	Error detection and recovery	system configuration,
S-9	SLO-1	Robotic sensors	Configuration of a Robot controller	Assembly system configurations - Single work station assembly,	Levels of automation	parts delivery at work stations,
	SLO-2	Types of sensors	General robot controller elements	series assembly system, parallel assembly system	Device, machine, cell or system, plant, enterprise levels.	applications.

Learning Resources	<ol style="list-style-type: none"> 1. "Industrial Robotics Technology, Programming, and Applications" - Mikell P Groover, Mitchell Weiss, Rogen N Nagel, Nicholas G Odrey, AshishDutta, Tata McGraw Hill Special Indian Edition, 2012. 2. "Computer Aided Design and Manufacturing" - K.Lalit Narayan, K.MallikarjunaRao, Prentice Hall of India, 2008. 3. "Automation, Production systems, and Computer intergrated Manufacturing"- Mikell P. Groover, Prentice Hall of India, 2008. 	<ol style="list-style-type: none"> 4. "Industrial Robotics Technology, Programming, and Applications"- Mikell P Groover, Mitchell Weiss, Roger N Nagel 2008 5. "Robotics Technology & Flexible Automation" - S.R.Deb, S.Deb 2012 6. "Introduction to Robotics in CIM system" - James A Rehg 2002
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Learning Assessment											
	Bloom's Level of Thinking	Continous Learning Assessment (50% Weightage)								Final Examination (50% Weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100%		100%		100%		100%		100%	

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. P.Kartikeyan, Head – Operations Improvement, Nokia India, kartikeyan.p@nokia.com	1. Dr.K.Senthilkumaran, Assistant professor, IIITDM, Kancheepuram. skumaran@iiitdm.ac.in	1. E. Sankar, SRMIST
2. Dr. R. Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	2. Dr.B.Mohan, Professor, Anna University, mohan@mitindia.edu	2. Dr.R.Rajaraman, SRMIST
3. Dr. A. Velayutham, DRDO, Avadi, velayutham.a@cvrde.drdo.in		

Course Code	18MEE704T	Course Name	PLC AND ITS APPLICATIONS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Course	Nil	Co-requisite Course	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book/Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1:	Impart PLC principle to reduce the human efforts by means of automation	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2:	Identify the main parts of PLC and hardware components	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3:	Analyze and interpret typical PLC timer ladder logic programs	Expected Proficiency (%)	Problem Analysis
CLR-4:	Acquire knowledge on HMI remote control monitoring in industrial automation	Expected Attainment (%)	Design & Development
CLR-5:	Learn PLC process – control design and PID configuration		Analysis, Design, Research
CLR-6:	Design PLC control system I/O and its applications		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1:	Utilize the parts of machine controller diagram including rungs, branches of PLC	2 85 80	M - - - M - - - - - L - L
CLO-2:	Understand the equipment used to program a PLC and mnemonic code	2 90 85	M - - - - - - - - - M - L
CLO-3:	Gain knowledge on hardwired and Human Machine Interface communicate with PLC	2 85 80	H - M- M - - - - - - L - M
CLO-4:	Learn the functions of PLC process – control design and elements	2 85 80	H - - - - - - - - - L - L
CLO-5:	Understand basic knowledge of PLCs concepts and its application in industries	3 90 85	H - M M - - - - - - M - H
CLO-6:	Develop complete system of PLC to meet industrial tasks	2 85 80	H M H H M - - - M - M - H - H

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Introduction	Control system classifications	Advanced program techniques- Introduction	Introduction: level of control & automation
	SLO-2	History of the PLC	Manual and auto control system	Physical components vs program components	Components of control system
S-2	SLO-1	Principles of operation	Automated system building block	RS Flip Flop, one shot,	Control elements of industrial automation
	SLO-2	Benefits of PLC	Requirements for industrial control	D Flip Flop, T Flip Flop	Examples of control requirements
S-3	SLO-1	Various parts of PLC	Motor magnetic starter	Forms of counters	Selection criteria for control elements
	SLO-2	Hardwired system replacement	Process control choices	Counter application	Standardization
S-4	SLO-1	Functions of PLC	Components of modularized PLC	Sequencers	Signal conversion
	SLO-2	Need for PLCs and its advantages	PLC configuration	Sequential functional chart	Quantification errors and resolution
S-5	SLO-1	Inputs & Outputs of PLC	Introduction to human machine interface	NAND logic function	Process control system
	SLO-2	Common types of mechanical design for PLCs	Device and PLC / HMI configuration	NOR logic function	Control Strategy and types
S-6	SLO-1	PLC Architecture and Wiring Diagrams	Fundamentals of human machine interfacing	AND ladder Rung	PLC Selection factors
	SLO-2	Internal structure Architecture of PLC	HMI-PLC application	OR ladder Rung	PLC Families
S-7	SLO-1	Basic components and their symbols of Ladder diagram	Network standards	Types of timer	Feedback control of continuous systems

	SLO-2	Functions & function blocks of Ladder diagram	Network systems role in industry	On/off cyclic timer	PLC systems and safety	
S-8	SLO-1	Switches & Its types	Number systems	Simple and complex branches	PID control configuration	Commissioning of PLC systems
	SLO-2	Relay systems	PLC data	standard format program	PID control systems	Fault Finding Techniques
S-9	SLO-1	PLC size and Applications	PLC in automation technology	Logical Actuators: solenoid, valves cylinders	Design cases: Oven temperature control, supervisory control and data acquisition	Power Plant Monitoring and Control
	SLO-2	PLCs versus other technologies	Examples of commercial systems involving PLC	Logical Actuators: hydraulics and pneumatics	Position measurement	Other Applications of PLC

Learning Resources	1. Khaled Kamel, Eman Kamel, "Programmable Logic Controllers, Industrial C", Mc Graw Hill private Ltd, 2014.	7. Kelvin T. Erickson, "Programmable Logic Controllers: An Emphasis on Design and Application" Mc Graw Hill private Ltd 2007.
	2. Gar Dunning, "Programmable Logic Controllers, Industrial Control", Mc Graw Hill private Ltd, 2009. 3. John R. Hackworth, Frederick D. Hackworth, Jr., "Programmable Logic Controllers : Programming Methods and Applications" Prentice Hall Publishing, 2003 4. W. Bolton, "Programmable Logic Controllers", Newnes Education private Limited, 2009. 5. Frank D. Petruzella, "Programmable Logic Controllers", Mc Graw Hill private Ltd, 2011. 6. Hugh Jack, "Automating Manufacturing Systems with PLCs" Mc Graw Hill private Ltd 2007.	8. R. Bliesener, F. Ebel, C. Löffler, "Programmable Logic Controllers", Festo Didactic, Ltd, 2002. 9. Kevin Collins, "PLC Programming for Industrial Automation", Newnes Education private Limited, 2009.

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% Weightage)								Final Examination (50% Weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100%		100%		100%		100%		100%	

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. P.Kartikeyan, Head – Operations Improvement, Nokia India, kartikeyan.p@nokia.com	1. Dr.K.Senthilkumaran, Assistant professor, IIITDM, Kancheepuram. skumaran@iiitdm.ac.in	1. A. Arunnath, SRMIST
2. Dr. R. Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	2. Dr.B.Mohan, Professor, Anna University, mohan@mitindia.edu	2. Dr.R.Rajaraman, SRMIST
3. Dr. A. Velayutham, DRDO, Avadi, velayutham.a@cvrde.drdo.in		

Course Code	18MEE705T	Course Name	FLEXIBLE MANUFACTURING SYSTEM	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Course	Nil	Co-requisite Course	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book/Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Introduce the concepts that can be flexible to the modern competitive environment.	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	To impart knowledge of Group Technology	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	To impart knowledge about flexible manufacturing systems and its concepts	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Introduce the concepts of manufacturing cell and its systems	Expected Attainment (%)	Design & Development
CLR-5 :	Introduce the concepts JIT and KANBAN system		Analysis, Design, Research
CLR-6 :	To impart knowledge about FMS software structure and description		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Understand the concepts of FMS in the modern competitive environment	1 90 85	M - H L M - M - M - M - M - H - H - H
CLO-2 :	Understand the concepts about Group Technology and various coding schemes	2 90 85	H - - L M - M - - M M - H - H - H
CLO-3 :	Understand the need of FMS layout, applications with scheduling concepts	2 90 85	M - M L M - M - M H L - H - H - H
CLO-4 :	Understand the concepts of cell, Unattended machining, JIT in detail	2 90 85	L - L L L - - - L L M - H - H - H
CLO-5 :	Understand the FMS software modules, ideas in data exchanges	2 90 85	M - H L H - - - L - H - H - H - H
CLO-6 :	Ability to perform Planning, Scheduling and control of FMS	2 90 85	M - H L M - - - M H H - H - H - H

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Traditional production planning, forecasting, process planning	Introduction to Group Technology	Introduction to FMS	Manufacturing Cell, Product flow from cell to cell	FMS software – Introduction
	SLO-2 Estimating, master scheduling, and various steps involved in planning and control	Part families	Basic components of FMS	Classification of Cell	General structure and requirements
S-2	SLO-1 Problems in production planning and control	Introduction to parts classification and coding	Application Characteristics of FMS	Unattended machining	Advantages of FMS software
	SLO-2 Cycle of activities	Coding system architecture	Significance of FMS	Features and requirement	Activities and functions to be performed by FMS software, within the system
S-3	SLO-1 Computer Integrated production management systems	Opitz system structure, classification system	Types of FMS	Differences between FMS and FMC	Types of FMS software modules
	SLO-2 Cycle of activities in CIPMS	MICLASS system	Types of FMS layouts	Introduction to JIT, Goals	Work-order processing
S-4	SLO-1 Cost Planning	Code system	Factors influencing FMS layout	Objectives of JIT, Ingredients	Data distribution and collection
	SLO-2 Cost Control	Group Technology machine cells	Objectives, AIMS of FMS	Quality and Quantity Principles of JIT	System diagnostics and maintenance
S-5	SLO-1 Inventory types	Types of GT machine cells	Advantages of FMS	Primary quantity JIT principles	Tool management
	SLO-2 Inventory Management	Benefits of Group technology	Disadvantages of FMS	Benefits of JIT	Traffic management and control
S-6	SLO-1 Material Requirements Planning	Product design benefits, tooling and setups	Area of Application of FMS in an Industry	JIT implementation	Quality control management
	SLO-2 Basic MRP concepts	Material handling	Various equipment and their functions required for an FMS	KANBAN/CARD system introduction	Fixtures and work piece control

S-7	SLO-1	Inputs to MRP	Production and inventory control	CIM technology	Push Vs pull system	Planning scheduling and simulation
	SLO-2	Master production schedule, bill of materials, Inventory record file	Employee satisfaction	Hierarchy of CIM	Dual card KANBAN	Computer simulation
S-8	SLO-1	Principles of MRP	Process planning procedures	Direct Real Time schedule control	Dual card KANBAN for milling and drilling	General phases of simulation analysis
	SLO-2	MRP output reports	System planning-objective, guideline,	Major functions of FMS host	Single card KANBAN concept	Functions
S-9	SLO-1	Benefits of MRP	System definition and sizing-	FMS concepts	Single card KANBAN- Example	FMS hosts
	SLO-2	MRP-II	Human resources	Process routings in an FMS	Benefits of KANBAN system	Data exchanges

Learning Resources	1. "CAD/CAM Computer Aided Design and Manufacturing" - M.Groover&E.Zimmers, Pearson Prentice Hall, 2012	4. "CAD/CAM Theory and Practice"- Ibrahim Zyed, Sivasubramaniam Tata McGraw Hill International 2011
	2. "Flexible Manufacturing System"- H.K.Shivanand, M.M.Benal, V.Koti, New Age International Pvt Limited, 2006	
	3. "Computer Aided Manufacturing" - P.N RAO, N.K. TIWARI, T.K.KUNDRA, McGraw Hill Education India private Ltd, 2014	5. "Flexible Manufacturing Cells and Systems" - William .W.LuggenPrentice Hall 1991 6. "Automation production Systems & Computer Integrated Manufacturing" - MikellP Groover 1989 7. "Handbook of Flexible of Manufacturing Systems" - JHA N.K 1991

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% Weightage)								Final Examination (50% Weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100%		100%		100%		100%		100%	

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. P.Kartikeyan, Head – Operations Improvement, Nokia India, kartikeyan.p@nokia.com	1. Dr.K.Senthilkumaran, Assistant professor, IIITDM, Kancheepuram. skumaran@iiitdm.ac.in	1. M.Kamatchi Hariharan SRMIST
2. Dr. R. Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	2. Dr.B.Mohan, Professor, Anna University, mohan@mitindia.edu	2. Dr.R.Rajaraman, SRMIST
3. Dr. A. Velayutham, DRDO, Avadi, velayutham.a@cvrde.drdo.in		

Course Code	18MEE706T	Course Name	IOT IN AUTOMATION	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes / Standards	NIL		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1:	Acquire knowledge on IoT enabling technologies	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2:	Impart knowledge on work logic of IoT in manufacturing system	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3:	Acquire knowledge on prototyping and production	Expected Proficiency (%)	Problem Analysis
CLR-4:	To know the role of IoT in laser cutting, 3D printing, CNC milling	Expected Attainment (%)	Design & Development
CLR-5:	To know the use of smart objects for smart applications		Analysis, Design, Research
CLR-6:	Track and trace real time manufacturing information		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1:	Understand the design principles of connected devices	2 90 80	H M M L L - - - - - M H - H
CLO-2:	Apply IoT models in manufacturing technologies	2 85 80	H M L L - - - - - M H - H
CLO-3:	Understand the importance of standardization in IoT	1 90 85	H L L - M - - - - M H - H
CLO-4:	Understand the capabilities and application of IoT	2 90 85	H L - - L - - - - M M - M
CLO-5:	Become master of IoT for business model	1 85 80	H L - - - - - M M M - M
CLO-6:	Acquire the real time manufacturing information	2 85 80	H L - - - - - M M - M

Duration (Hour)	9	9	9	9	9
S-1	SLO - 1	Introduction to IoT	Existing manufacturing paradigms and their limitations	Real time status monitoring and Real time production guiding	IoT application for industry value creation and challenges
	SLO - 2	Definition and characteristic of IoT	Agile manufacturing, Networked manufacturing	Real time production data sharing, Real time production requeuing	Configuration of smart shop floor
S-2	SLO - 1	Physical design of IoT	Reconfigurable manufacturing system	Deployment of multi-sensors, multiple sensor selection, multiple sensor manager	IoT application requirement and capabilities
	SLO - 2	Physical design of IoT	Product service system and industrial product service system,	Multisource manufacturing information capturing and sharing	Challenges faced by IoT industries application
S-3	SLO - 1	Logical design of IoT	Manufacturing grid	Information encapsulation	Future factory concepts
	SLO - 2	Logical design of IoT	Cloud manufacturing	Case study – hardware device, software system	The framework of the prototype system
S-4	SLO - 1	IoT enabling technologies	Limitations of agile manufacturing system	IoT standardization	The smart factory initiative
	SLO - 2	IoT enabling technologies	Applications of IoT in manufacturing system	Importance of standardization – beginning of everything	Workflow of the prototype system
S-5	SLO - 1	IoT levels and deployment models	Key features and limitations of IoT in manufacturing system	The need of methods and tools and corresponding research	From technologies to technology concept
	SLO - 2	IoT levels and deployment models	Integration framework of real time manufacturing information – sharing and integration	Gaps between IoT standardization, IoT research, IoT development and IoT innovation	Task driven manufacturing resource configuration model
					Production scheduling / rescheduling model
					The scheduling and rescheduling method

S-6	SLO – 1	Design principles for connected devices	Real time manufacturing data processing	M2M service layer standardization	Smart objects and smart applications	IoT enabled smart materials handling module
	SLO – 2	Design principles for connected devices		Prototype and production		
S-7	SLO – 1	Calm and ambient technology		Physical prototypes and mass personalization	Four aspects in your business to master IoT	IoT enabled smart station
	SLO – 2	Calm and ambient technology	Sharing and exchange service	Open source versus closed source		
S-8	SLO – 1	Internet principles	IoT enabled smart assembly station	Prototyping embedded devices, sensors, actuators	Value creation from big data and serialization from pharmaceutical industry	Operation guidance from the system
	SLO – 2	Internet Communication – overview	Overall architecture of IoT enabled smart assembly station	Embedded computer basics, Arduino, Raspberry Pi, sketch, iterate and explore		Real time queuing under exceptions
S-9	SLO – 1	Overall architecture of IoT manufacturing system (MS)	IoT enabled smart trolley	Non digital methods, Laser cutting, 3D printing, types of 3D printing	IoT for oil and gas industries	Real time manufacturing information track and trace
	SLO – 2	The work logic of IoT MS, Description of core technologies of IoT MS	IoT enabled materials handling	Moving to manufacture, Moving to manufacture, CNC milling, recycling		Real time production performances monitor module

Learning Resources	1. ArshdeepBahga, Vijay Madiseti, "Internet of Things – A hands on approach", ArshdeepBahga& Vijay Madiseti 2014	4. Dr. Ovidiu Vermesan, Dr. Peter Friess, "Internet of Things – Covering technologies for smart environments and ecosystem", River Publishers 2013.
	2. Yingfeng Zhang, Fei Tao, "Optimization of manufacturing using internet of things", Academic Press Elsevier 2017.	
	3. Adrian McEwen, Hakim Cassimally, "Designing the internet of things", Springer International Publishing 2018.	5. Christoph Jan Bartodziej, "The concept of industry 4.0" – An empirical analysis of technologies and applications in production logistics", Springer Gabler 2017
		6. Francis daCosta, "Rethinking the internet of things – A scalable approach to connecting everything", Apress 2013.

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment								Final Examination (50% weightage)	
		CLA-1 (10%)		CLA-2 (15%)		CLA-3 (15%)		CLA-4 (10%) #			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100%	-	100%	-	100%	-	100%	-	100%	-

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from industry	Expert from higher technical institution	Internal Expert
1. Mr. P.Kartikeyan, Head – Operations Improvement, Nokia India, kartikeyan.p@nokia.com	1. Dr.K.Senthilkumaran, Assistant professor, IIITDM, Kancheepuram. skumaran@iiitdm.ac.in	1. N. Dinakar, SRMIST
2. Dr. R. Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	2. Dr.B.Mohan, Professor, Anna University, mohan@mitindia.edu	2. Dr.R.Rajaraman, SRMIST
3. Dr. A. Velayutham, DRDO, Avadi, velayutham.a@cwrde.drdo.in		

Course Code	18MEE707T	Course Name	VIRTUAL INSTRUMENTATION	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Course	Nil	Co-requisite Course	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book/Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Impart knowledge on virtual instrumentation and differentiate it from conventional instruments	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Learn the basic programming concepts		
CLR-3 :	Learn different Data Acquisition System		
CLR-4 :	Impart knowledge on interfacing of virtual instrumentation		
CLR-5 :	Provide knowledge in process analysis by virtual instrumentation tool.		
CLR-6 :	Develop real time applications using LabVIEW		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	
CLO-1 :	Describe about virtual instrumentation	1 90 85	M - M L H - L - - - L H - H
CLO-2 :	Get adequate knowledge on virtual instrumentation tool sets	2 90 85	H - - L H - L - - - L H - H
CLO-3 :	Describe data acquisition	2 90 85	H - M M H - L - M - - L H - H
CLO-4 :	Understand virtual instrumentation programming techniques	2 90 85	H - M L H - - - L - - L- H - H
CLO-5 :	Gain knowledge on interfacing and networking of virtual instrumentation	2 90 85	H - M M H - - - L - - - H - H
CLO-6 :	Use virtual instrumentation tool for process monitoring	2 90 85	H - M L H - L - M - - - H - H

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Historical perspective, advantages of virtual instrumentation	Modular Programming in Lab-VIEW	Introduction to PC based data acquisition	Common Instrument Interfaces	Use of Analysis tools
	SLO-2	Block diagram of a virtual instrument	Building a connector pane	Sampling fundamentals	Current loop	Fourier transforms
S-2	SLO-1	Architecture of a virtual instrument	VIs and sub-Vis	Analog Input/output techniques	Serial port Communication	Power spectrum
	SLO-2	Conventional instruments versus Traditional instruments	Opening and editing sub-Vis	Digital Input/output techniques	Instrument driver VIs	correlation methods
S-3	SLO-1	Hardware in virtual instrumentation	Placing sub-VIs, Saving sub VIs	Buses	RS 232C/ RS485	Windowing and filtering
	SLO-2	Software in virtual instrumentation	Loops and charts, Terminals inside or outside loops	ADC, DAC	GPIB	Distributed I/O modules
S-4	SLO-1	Layers of virtual instrumentation software	Shift Registers	Counters and timers	Using other interfaces	Virtual Laboratory, Simulation of level
	SLO-2	Graphical system design model	Arrays, creating arrays	DMA	Bus Interfaces: USB, PCMCIA	Major equipments- Oscilloscope, Digital Multi-meter
S-5	SLO-1	Virtual instrumentation for test	Deleting, inserting and replacing elements	Software and hardware installation	VXI, SCSI	Temperature data acquisition system
	SLO-2	Virtual instrumentation for industrial I/O and control	Clusters and graphs	Calibration, resolution	PCI, PXI, Fire wire	Image acquisition and processing
S-6	SLO-1	Virtual instrumentation for design	Case and sequence structures	Signal conditioning	PXI system controllers	Image acquisition using line sensor
	SLO-2	Graphical programming in data flow	formula nodes, feedback nodes	Computer based measurements system	Ethernet control of PXI.	Image acquisition using a single sensor
S-7	SLO-1	Comparison with conventional programming	Control timing	Selecting and configuring data acquisition system	Networking basics for office	Motion control employing stepper motor

	SLO-2	Virtual instrumentation in the engineering processes	Local and global variables	Concept of universal data acquisition card	Networking basis for industrial applications	On-Off controller PID Controller
S-8	SLO-1	Virtual instrumentation personal computers	State machine	Data acquisition interface requirements	VISA and IVI.	PID controller theory
	SLO-2	Graphical programming and textual programming	String and file I/O	Use of timers/counters	VISA Programming terminology	PID tuning software
S-9	SLO-1	Development of Virtual Instrument using Graphical user interface (GUI)	Instrument Drivers	Signal sources, measurement system	VISA and Serial	Advantages and Limitations of PID controller
	SLO-2	Real-time systems	Publishing measurement data in the web, cable news network	Increasing the measurement quality	IVI software technology	Advantages and Limitations of On-Off controller

Learning Resources	<ol style="list-style-type: none"> 1. Robert H.Bishop, "Learning with LabVIEW 2009", Pearson Education 2010. 2. Jovitha Jerome, "Virtual Instrumentation Using LabVIEW", Eastern Economy Edition, PHI learning private Ltd, 2010. 3. Sanjay Gupta and Joseph John, "Virtual Instrumentation Using LabVIEW", McGraw Hill Education private Limited, 2013. 4. N.Mathivanan, "PC-based Instrumentation: Concepts and Practice", Eastern Economy Edition, PHI Learning private Ltd, 2007. 5. Kevin James, "PC Interfacing and Data Acquisition: Techniques for Measurement, Instrumentation and Control", Newnes, 2000.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% Weightage)								Final Examination (50% Weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100%		100%		100%		100%		100%	

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. P.Kartikeyan, Head – Operations Improvement, Nokia India, kartikeyan.p@nokia.com	1. Dr.K.Senthilkumaran, Assistant professor, IITDM, Kancheepuram. skumaran@iitdm.ac.in	1. Dr.R.Rajaraman, SRMIST
2. Dr. R. Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	2. Dr.B.Mohan, Professor, Anna University, mohan@mitindia.edu	2. Dr.I.Suresh Kannan, SRMIST
3. Dr. A. Velayutham, DRDO, Avadi, velayutham.a@cvrde.drdo.in		

Course Code	18MEE708T	Course Name	NEURAL NETWORK AND FUZZY SYSTEMS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Course	Nil	Co-requisite Course	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book/Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Acquire knowledge on the fundamental of neural networks	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Apply the neural network recurrence for automation	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Utilize the practical applications of neural networks in automation	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Understand the principles of Clustering approaches to automation	Expected Attainment (%)	Design & Development
CLR-5 :	Understand various applications of fuzzy in automation		Analysis, Design, Research
CLR-6 :	Understand the Neural Network approach to Pattern Recognition		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Acquire basic understanding of the various algorithms involved in Neural Networks & Fuzzy Systems	3 90 80	H H H H - - - H - H - H
CLO-2 :	Analyze the neuron model and fundamentals on learning algorithms	3 90 80	M - - - - - - - H M - M
CLO-3 :	Understand various Fuzzy algorithms.	3 90 80	H H L H H - - - M - - H H - M
CLO-4 :	Analyze how to apply the concept of fuzzy & neural in automation	3 90 80	H M M H H - - - M - - H H - M
CLO-5 :	Application of Neural and Neuro fuzzy concepts	3 90 80	H L L H - - - - M - - H H - M
CLO-6 :	Analyze and compare a variety of automation techniques to real-world problems	3 90 80	H H L H - - - - M - - H H - M

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Introduction to ANN	Counter propagation	Introduction to Fuzzy Sets	Fuzzy Relations on Sets and Fuzzy Sets
	SLO-2	History of neural networks	Self-organization Map	Crispness, Vagueness, Fuzziness, Uncertainty	Application of neural networks and fuzzy logic
S-2	SLO-1	Biological Neurons and its Artificial Models	Cognitron and Neocognitron	Fuzzy Set Theory	Compositions of Fuzzy Relations
	SLO-2	Models of Artificial Neural Networks		Fuzzy Sets-Basic Definitions	Applications of Fuzzy Set Theory
S-3	SLO-1	Learning and Adaptation	Hopfield Net- kohonnen Nets	Basic Set-Theoretic Operations for Fuzzy Sets	Properties of the Min-Max Composition
	SLO-2	Neural Network Learning Rules		Types of Fuzzy Sets	Support Logic Programming and Fril
S-4	SLO-1	Hebbian Learning Rule	Mathematical foundations of Discrete-Time hopfield networks	Further Operations on Fuzzy Sets	Fuzzy Graphs
	SLO-2	Perceptron Learning Rule		Algebraic Operations	Application in Measurement, Control
S-5	SLO-1	Types of activation Functions	Mathematical foundations of gradient type hopfield networks	Set-Theoretic Operations	Fuzzy Functions on Fuzzy Sets
	SLO-2			Criteria for Selecting Appropriate Aggregation Operators	Linguistic Evaluation and Ranking of Machine Tools
S-6	SLO-1	Multilayer perceptron	Grossberg nets	Fuzzification and Defuzzification	Integration of Fuzzy Functions
	SLO-2	Batch Learning and On-Line Learning			Application in Flexible Manufacturing Systems
S-7	SLO-1	Supervised Learning Viewed as an Optimization Problem	Transient response of continuous-Time Networks	Fuzzy Measures and Measures of Fuzziness	Performance index – Modification of rule base
	SLO-2				Adaptive Neural Controllers

S-8	SLO-1	Back propagation algorithm and its variants	Relaxation Modeling in Single-Layer Feedback Networks	The Extension Principle and Applications	Genetic algorithms	Signal Processing and Image Processing
	SLO-2				Adaptive fuzzy system	
S-9	SLO -1	Different types of learning, examples	Art-I, Art-II reinforcement learning	Algebraic Operations with Fuzzy Numbers	Neuro fuzzy systems	Case studies
	SLO-2					

Learning Resources	1. Vallum B. R And Hayagriva V.R C++, <i>Neural networks and Fuzzy logic</i> , BPB Publications.	6. Fuzzy sets Fuzzy logic, Klir, G.J and Yuan B.B Prentice Hall of India Pvt. Ltd., New Delhi
	2. Simon Haykins, "Neural Networks - A comprehensive foundation", Macmillan College, Proc. Con. Inc. New York, 2005	
	3. Zimmermann.H.J, "Fuzzy set theory and its applications", Allied Publication Ltd., Chennai, 2001. New Delhi, 1996	7. Neural Networks and Fuzzy systems, Kosko.. Prentice hall of India Pvt. Ltd., New Delhi 1994
	4. Fuzzy logic & Neural Networks/ Chennakesava R. Alavala/ New Age International, 2008	
	5. Neural Networks for control, Millon W. T, Sutton R.S and Werbos P.J, MIT Press 1992	8. Introduction to Fuzzy control, Dirankov D. Hellendoorn H, Reinfrank M., Narosa Publications House, New Delhi 1996
		9. Introduction to Artificial Neural systems, Zurada J. M Jaico Publishing House, New Delhi 1994

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% Weightage)								Final Examination (50% Weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100%		100%		100%		100%		100%	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. P.Kartikeyan, Head – Operations Improvement, Nokia India, kartikeyan.p@nokia.com	1. Dr.K.Senthilkumaran, Assistant professor, IIITDM, Kancheepuram. skumaran@iiitdm.ac.in	1. S.Thamilarasu, SRMIST
2. Dr. R. Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	2. Dr.B.Mohan, Professor, Anna University, mohan@mitindia.edu	2. Dr.R.Rajaraman, SRMIST
3. Dr. A. Velayutham, DRDO, Avadi, velayutham.a@cwrde.drdo.in		

Course Code	18MEE709T	Course Name	ELEMENTS OF MECHATRONICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Course Learning Rationale (CLR):	<i>The purpose of learning this course is to:</i>
CLR-1 :	<i>Understand the basic key elements of mechatronics systems</i>
CLR-2 :	<i>Have cognizance on performance of sensors and transducers.</i>
CLR-3 :	<i>Understand different actuation systems, signal processing and Controllers</i>
CLR-4 :	<i>Program the PLC</i>
CLR-5 :	<i>Design mechatronics system and its applications</i>
CLR-6 :	<i>Case studies</i>

Learning			Program Learning Outcomes (PLO)														
1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Thinking (Bloom)	Proficiency (%)	Maintainment (%)	Knowledge	Analysis	Development	Design, Research	Usage	Culture	Sustainability	Team Work	Innovation	Finance & Management					

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Mechatronics	Mathematical models	Microprocessor systems	Introduction of basic structure	Stepper motor
	SLO-2	Engineering Design				
S-2	SLO-1	Classification of Sensors	Building Blocks : Mechanical	Basic elements of control systems	Input and output processing	Stepper motor - types
	SLO-2	Classification of transducers	Building Blocks : Electrical			
S-3	SLO-1	Thermal and electrical sensors	Building Blocks : Fluid	Microcontrollers	Programming	Servo motor
	SLO-2	Optical sensor	Building Blocks : thermal system			
S-4	SLO-1	Acoustic sensor	System models	Microprocessor architecture and terminology	Mnemonics	Servo motor - types
	SLO-2	Pneumatic sensor				
S-5	SLO-1	Magnetic sensor	Dynamic response of systems	Closed loop controllers	Timers	Case studies of mechatronics system-pick and place robot
	SLO-2	Piezo electric sensor				
S-6	SLO-1	Transducers: Static characteristics	first and second order systems	Proportional, derivative and integral controls	counters and internal relays	automatic car park barrier
	SLO-2	Transducers: Dynamic characteristics		Derivative and integral controls		
S-7	SLO-1	Open loop control systems	Modeling dynamic systems	PID controller	Data handling	Engine management system
	SLO-2	Closed loop control systems				
S-8	SLO-1	Servo mechanism	System transfer functions	Controllers	Selection of PLC	Digital camera
	SLO-2			Tuning of controller		
S-9	SLO-1	Frequency response	Adaptive control of machine tools	Development of simple ladder programs for specific purposes	A PC based computer numerically controlled drilling machine	
	SLO-2					

Learning Resources	1. W.Bolton, "Mechatronics electronic control systems in mechanical and electrical engineering", Pearson Education 2013.	3. Devdas Shetty & Richard A.Kolk, "Mechatronics system design", Indian Edition, Cenage Learning, 2009.
	2. Godfrey C.Onwubolu, "Mechatronics principles and applications", Elsevier, 2011.	4. Nitaigour Premchand Mahalik, "Mechatronics principles, concepts and applications", Tata McGraw-Hill, 2008. 5. R.K.Rajput, "A textbook of Mechatronics", Revised Edition, S.Chand Company,2009.

Learning Assessment											
	Bloom's Level of Thinking	Continious Learning Assessment (50% Weightage)								Final Examination (50% Weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100%		100%		100%		100%		100%	

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2. Dr. R. Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	2. Dr.B.Mohan, Professor, Anna University, mohan@mitindia.edu	2. Dr.R.Rajaraman, SRMIST
3. Dr. A. Velayutham, DRDO, Avadi, velayutham.a@cvrde.drdo.in		

Course Code	18MEE801J	Course Name	ARTIFICIAL INTELLIGENCE AND MACHINE LEARNING	Course Category	E	Professional Elective	L	T	P	C
							2	0	2	3

Pre-requisite Course	Nil	Co-requisite Course	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book/Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Learn about Artificial Intelligence and identify the need of AI in Mechanical Engineering	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Learn about different search algorithms	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Learn about Logic controllers, Microprocessors	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Learn about Python Programming	Expected Attainment (%)	Design & Development
CLR-5 :	Apply the concept of Machine Learning for mechanical applications		Analysis, Design, Research
CLR-6 :	Apply Mechanical concepts in AI and build an efficient working environment		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Understand the concept of Artificial Intelligence	1 90 85	H L M M H - M H M - - M - - -
CLO-2 :	Characterize the concepts of Machine Learning	1 90 85	H - M M H - M L M - - M - - -
CLO-3 :	Identify the different concepts in Heuristic methods	1 90 85	H - - M L - - H M L - - M L M
CLO-4 :	Understand MATLAB and Python programming	2 90 85	H H L M M - L L M L - M M L M
CLO-5 :	Solve problems in Genetic programming	2 90 85	H H - M M - - L M L - L M L M
CLO-6 :	Apply the basic knowledge of Mechanical in smart manufacturing	2 90 85	H M - M H - L L M L - H M L M

Duration (hour)	12	12	12	12	10
S-1	SLO-1 Artificial Intelligence and its foundations	Lab-4: MATLAB- Optimization methods GA, Fuzzy, Neural & PSO	Tutorial 4: Artificial Intelligence in Manufacturing Industry	Fuzzy matching techniques	Syntax programming for optimization
	SLO-2 History of AI, LISP and PROLOG		Hebb's Rule, McCulloch and Pitts Neurons	Tutorial 6: Microcontrollers	Reduced environmental impact by ML
S-2	SLO-1 Blind search, Breadth first	Formalized symbolic logics	Evolutionary Learning: Genetic Algorithm and Problems in GA	Lab-12: FLEXSIM Software	Harnessing useful data using AI and ML
	SLO-2 Lab-1: Python Programming	Syntax and semantics for Logics Representing knowledge using rules and rules-based deduction systems	Genetic Programming	RETE matching algorithm	Supply chain Communication
S-3	SLO-1 Heuristic search techniques	Reasoning under uncertainty	Lab-7: Image Processing, Object and Motion detection	Object-Oriented representations	Cutting waste using AI
	SLO-2 Hill climbing technique	Bayes' probabilistic inferences		Data mining for Mechanical Engineers	Integration of man machine system
S-4	SLO-1 Best first search technique, A* algorithm,	Heuristic methods	Markov Chain Monte Carlo (MCMC) methods, Bayesian Networks	Lab-13:Hydraulic and Pneumatic simulator	Improved customer service using AI
	SLO-2 AO* algorithm	Fuzzy reasoning	Lab:8- Pick and place operation of ABB Robot in Manual Mode	Dimensionality Reduction PCA	Minimizing Equipment Failures
S-5	SLO-1 Lab-2: Machine Learning using python	Lab-5: Introduction to SIMULINK & Modelling of problems related to kinematics and dynamics of robot using MATLAB	Graphical models Markov Random Fields	Single Value Decomposition(SVD), t-Distributed Stochastic Neighbor Embedding (t-SNE) methods	Predictive Maintenance
	SLO-2 Tutorial:1 Python Programming in Mechanical applications		Hidden Markov Models (HMMs)	Ensemble Techniques Boosting Bagging	Multi-dimensional optimization
S-6	SLO-1 Game trees- Numerical	Expert system, Relationship between Artificial Intelligence and Mechanical Engineering	Lab-9: Pick and place operation of ABB Robot in Teach Pendent method, PLC Controlled material handling system	Data visualization in machine learning	Artificial Neural network
	SLO-2 Minimax algorithm	Expert system, Relationship between Artificial Intelligence and Mechanical Engineering		Text mining	Greedy algorithm

S-7	SLO-1	Game playing	Diagnosis of rule-based reasoning Case-based reasoning and fault-based tree fault diagnosis	Tracking Methods	Lab-14: Study on Microcontrollers	Greedy algorithm problems
	SLO-2	Alpha beta pruning	Diagnosis of rule-based reasoning Case-based reasoning and fault-based tree fault diagnosis	Python- Basics of coding, Writing and importing code		Robotic perception
S-8	SLO-1	Lab-3: Basics of MATLAB programming	Case study: Manufacturing scheduling	Tutorial 5: PLC controllers	Case study on driverless vehicles	Sensors and effectors
	SLO-2		Case study: Manufacturing scheduling			Types of sensors and actuators
S-9	SLO-1	Definition and importance of Knowledge Representation of knowledge	Tutorial 2: Case study in manufacturing industry Case study: Intelligent Diagnostic system for Rotating machinery	Lab-10: 8051 Micro controller-Temperature and Traffic control	Lab-15: Study on Driverless Vehicles	Dynamics and control
	SLO-2	Organization and Manipulation Logical Agents	Case study: Fault diagnosis to Hot Forging Press			Problems in Dynamics
S-10	SLO-1	Problems in Genetic Algorithm	Lab-6: Sensors and its applications	Python coding	Application of AI and ML in Inventory control	Robotic software architecture
	SLO-2	Programming GA in MATLAB				Writing Robotic software
S-11	SLO-1	Problems in Artificial Neural Network	Tutorial 3: Image Processing, Object and Motion detection	MATLAB and its applications in Fault detection and Optimization	Reducing time of production with AI	Robotic programming language
	SLO-2	Programming ANN in MATLAB	Basics of Machine Learning		Cost reduction of production with AI	Case study on Humanoid robot
S-12	SLO-1	Programming Particle swarm optimization (PSO)	Definition & uses of Machine Learning	Lab-11: 8051 Micro controller-Temperature and Traffic control	Automating quality control using AI and ML	Machine Learning in supply chain
	SLO-2	Problems in PSO	Decision Tree & Practical applications			

Learning Resources	<ol style="list-style-type: none"> 1. Russell, Stuart J., and Peter Norvig. Artificial intelligence: a modern approach. Malaysia; Pearson Education Limited., 2016. 2. Patterson, Dan W. Introduction to artificial intelligence and expert systems. Prentice-hall of India, 2010. 3. Marsland, Stephen. Machine learning: an algorithmic perspective. Chapman and Hall/CRC, 2009. 4. Luger, George F., and William A. Stubblefield. Artificial intelligence and the design of expert systems. Benjamin-Cummings Publishing Co., Inc., 2009. 5. Charniak, Eugene. Introduction to artificial intelligence. Pearson Education India, 2000. 6. Nilsson, Nils J. Principles of artificial intelligence. Morgan Kaufmann, 2014.
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Learning Assessment											
	Bloom,s Level of Thinking	Continuous Learning Assessment (50% Weightage)								Final Examination (50% Weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100%		100%		100%		100%		100%	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

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3. Dr. A. Velayutham, DRDO, Avadi, velayutham.a@cvrde.drdo.in		

Course Code	18MEE802T	Course Name	DIGITAL IMAGE PROCESSING AND MACHINE VISION	Course Category	E	Professional Elective	L	T	P	C
							2	0	2	3

Pre-requisite Course	Nil	Co-requisite Course	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book/Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Study the image fundamentals transforms necessary for image processing.	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Study the image enhancement techniques	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Study basic image processing operations	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Overview of image restoration techniques.	Expected Attainment (%)	Design & Development
CLR-5 :	Understand the need for image compression and segmentation		Analysis, Design, Research
CLR-6 :	Understand the rapid advances in Machine vision.		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Review the fundamental concepts of a digital image processing system	2 85 90	M - - M - - - - - L L - L
CLO-2 :	Analyze images in the frequency domain using various transforms	2 85 80	M L M M - - - - L - L M - M
CLO-3 :	Evaluate the techniques for image enhancement and image restoration	2 80 85	M - M M - - - - - - L L - L
CLO-4 :	Analysis different causes for image degradation	2 90 85	M - - M L - - - - - L M - M
CLO-5 :	Interpret Image compression standards.	2 80 80	M L - M - - M - - - L M - L
CLO-6 :	Interpret image segmentation and representation techniques.	3 85 80	M L L M - - - - M - - L L - M

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Origins of digital image processing	Light used in Machine Vision	Image Enhancement Techniques:	Image Compression - Measuring image information
	SLO-2	Origins of digital image processing	Basic Rules and Laws of Light Distribution	Spatial and Frequency domain	Spatial and temporal redundancy
S-2	SLO-1	Fundamental steps in digital image processing	Light Filters	Spatial Domain	Image compression models - Huffman coding
	SLO-2	Fundamental steps in digital image processing	Light Filters	Point operation & Maskoperation	Image compression models - Huffman coding
S-3	SLO-1	Components of image processing system	Types of Light Filters	Histogram manipulation	Image compression models - Arithmetic coding
	SLO-2	Components of image processing system	Types of Light Filters	Histogram equalization and procedure	Image compression models -Run length coding
S-4	SLO-1	Elements of Visual Perception	Machine Vision versus Closed Circuit Television (CCTV)	Linear gray level transformation	Digital Image watermarking
	SLO-2	Basics of Image Sensing and Acquisition	Machine Vision versus Closed Circuit Television (CCTV)	Linear gray level transformation	Digital Image watermarking
S-5	SLO-1	Image Sampling	Imaging Sensors- CCD	Nonlinear gray level transformation	Image Segmentation- Point, line and edge Detection
	SLO-2	Image Quantization	Imaging Sensors- CCD	Nonlinear gray level transformation	Image Segmentation- Point, line and edge Detection
S-6	SLO-1	Basic Relationships between Pixels	Imaging Sensors- CMOS	Comparison between smoothing and sharpening spatial filters	Edge linking and Boundary Detection

	SLO-2	Basic Relationships between Pixels	Imaging Sensors-CMOS	Comparison between smoothing and sharpening spatial filters	Edge linking and Boundary Detection	Industrial Case Study- Glue Check under UV Light
S-7	SLO-1	Digital image file formats – GIF	Digital Cameras- B/W Sensor and Processing	Smoothing frequency domain filters (Ideal, Butterworth, Gaussian)	Thresholding, Basics of Global thresholding	Industrial Case Study Multiple Position and Completeness Check
	SLO-2	Digital image file formats – JPEG	Digital Cameras- B/W Sensor and Processing	Smoothing frequency domain filters (Ideal, Butterworth, Gaussian)	Using edge to improve global thresholding	Industrial Case Study-Multiple Position and Completeness Check
S-8	SLO-1	Digital image file formats – PNG	Color Digital Cameras	Sharpening frequency domain filters (Ideal, Butterworth, Gaussian)	Multiple and variable thresholding	Industrial Case Study- Pin Type Verification
	SLO-2	Digital image file formats – TIFF, BMP	Camera Noise&Photon Noise.	Sharpening frequency domain filters (Ideal, Butterworth, Gaussian)	Multiple and variable thresholding	Industrial Case Study- Pin Type Verification
S-9	SLO-1	Applications of Digital Image Processing	Introduction to video analytics	Homomorphic filtering.	Region Based Segmentation	Industrial Case Study- Robot Guidance
	SLO-2	Applications of Digital Image Processing	Introduction to video analytics	Homomorphic filtering.	Pattern recognitions	Industrial Case Study-Robot Guidance

Learning Resources	<ol style="list-style-type: none"> 1. Rafael C Gonzalez and Richard E Woods, Digital Image Processing, Pearson Education, 3rd Edition, 2009. 2. Jayarman.S, Esakkirajan.S and Veerakumar.T, Digital Image Processing, Tata McGraw Hill, 2010. 3. Alexander Hornberg , Handbook on Machine Vision , Wiley – VCH , 2008. 4. William K Pratt, Digital Image Processing, John Wiley, 2007. 5. Myler, Harley R. Fundamentals of machine vision. SPIE Optical Engineering Press, 1999. 6. MillmanSonka, Vaclav Hlavac, Roger Boyle, and Broos Colic, Image Processing Analysis and Machine Vision, Thompson learning, 2014.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% Weightage)								Final Examination (50% Weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100%		100%		100%		100%		100%	

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3. Dr. A. Velayutham, DRDO, Avadi, velayutham.a@cvrde.drdo.in		

Course Code	18MEE803J	Course Name	SENSORS FOR INTELLIGENT MANUFACTURING	Course Category	E	Professional Elective	L	T	P	C
							2	0	2	3

Pre-requisite Course	Nil	Co-requisite Course	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book/Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Expose the basics and working principle of sensors and Transducers	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Impart knowledge on motion sensors	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Learn the Packaging techniques of sensors	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Provide knowledge on sensors used in Robotics	Expected Attainment (%)	Design & Development
CLR-5 :	Provide insights on advanced sensors		Analysis, Design, Research
CLR-6 :	Impart knowledge on sensor based control		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Describe about sensors and transducers	1 90 85	H - L L M - - - M - - - M - M
CLO-2 :	Familiarize to use motion sensors for various applications	2 90 85	H - L L H - - - M - - - M - M
CLO-3 :	Develop packaging of various sensors	2 90 85	H - M M M - - - M - - - M M - H
CLO-4 :	Understand the use of sensors in Robotic application	2 90 85	H - M M H - - - M - - - M M - M
CLO-5 :	Gain knowledge on advanced sensors	2 90 85	H - L M H - - - M - - - M M - M
CLO-6 :	Develop a control scheme based on sensor feedback.	2 90 85	H - L M M - - - H - - - L M - M

Duration (hour)	12	12	12	12	12
S-1	SLO-1	Role of sensors in manufacturing automation	Motion Sensors	Classification, characteristics	Semiconductor sensors
	SLO-2	Active and passive sensors	Resistive strain gauge	Internal sensors – position	Hall elements
S-2	SLO-1	Operating principles of different sensors electrical,	LVDT, RVDT	Velocity sensors	Silicon sensors for sensing radiation
	SLO-2	Operating principles of optical sensors	Capacitive, piezo	Acceleration sensors	Mechanical signals
S-3	SLO-1	Operating principles of acoustic sensors	Seismic pickups,	Force sensors	Magnetic signals
	SLO-2	Operating principles of pneumatic sensors	Vibrometers and accelerometers	External sensors	Chemical and other signals
S-4	SLO-1	Lab 1: Study of the characteristics of a Piezo resistive Sensor for Pressure Measurement	Lab 4: Characteristics study of LVDT	Lab 7: Study of the characteristics of a Photo reflective sensor for Speed Measurement	Lab 10: Study of PLC system and Programming
S-5	SLO-2				Lab 13: Study of Level sensors
S-6	SLO-1	Operating principles of magnetic sensors	Sensors for CNC machine tools.	Proximity, touch Slip sensors.	Catalytic devices
	SLO-2	Operating principles of electro-optical sensors	Packaging techniques of mechanical sensors	Robotic vision.	Gas sensors
S-7	SLO-1	Vision sensors, Active transducers, passive transducers	Electrical interconnection	Process of imaging, architecture of robotic vision systems	Acoustic sensors
	SLO-2	Classification of transducers, Sensors and Transducers for: flow, temperature, pressure and torque,	Packaging processes	Image acquisition, components of vision system	Applications of sensors in Robotics

S-8	SLO-1	Lab2: Characteristics study of Resistance Temperature Detector (RTD)	Lab 5: Characteristics study of RVDT	Lab:8 Characteristics study of Reflective Beam Sensor	Lab 11: Study of Force and torque sensors	Lab 14: Study of Smart material sensors
	SLO-2					
S-9	SLO-1					
	SLO-2	Current and torque and speed measurements using digital measurement techniques	Mechanical transduction techniques	Image representation, image processing in robotic vision systems	Tactile sensors	Autonomous mobile robots
S-10	SLO-1				Future Inertial Micro machined Sensors	Applications of autonomous mobile robots
	SLO-2					
S-11	SLO-1	Lab 3: Experiment on the Calibration of a Thermocouple	Lab 6: Characteristics study of an Electromagnetic Flow meter	Lab:9 Experiment on image acquisition and processing	Lab 12: Study of Acceleration sensors	Lab 15: Study of Micro and Nano sensors
	SLO-2					
S-12	SLO-1					
	SLO-2					

Learning Resources	<ol style="list-style-type: none"> 1. Stephen Beeby, Graham Ensell, Michael Kraft, Neil White, MEMS Mechanical Sensors, Artech House, Inc. London, 2004. 2. J. Vetelino and A. Reghu, Introduction to sensors, CRC Press, 2010. 3. J. Fraden, Handbook of Modern Sensors: Physics, Designs and Applications, 4th edition, Springer, 2010. 4. T. G. Beckwith, R. D. Marangoni and J. H. Lienhard V., Mechanical Measurements, Pearson Prentice Hall, 2009. 5. Doebelin, Measurement systems: Applications and Design, 5th edition, McGraw Hill Book, 2004. 6. I. R. Sinclair, Sensors and Transducers, Elsevier, 2001. 7. J. S. Wilson, Sensor Technology Handbook, Newnes, 2004. 8. B. K. Ghosh, T. J. Tam and N. Xi, Control in Robotics and Automation: Sensor-Based Integration, Academic Press, 1999. 9. C.W. de Silava, Sensors and Actuators, 2nd edition, CRC Press, 2016.
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Learning Assessment											
	Bloom,s Level of Thinking	Continuous Learning Assessment (50% Weightage)								Final Examination (50% Weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
Total		100%		100%		100%		100%		100%	

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. P.Kartikeyan, Head – Operations Improvement, Nokia India, kartikeyan.p@nokia.com	1. Dr.K.Senthilkumaran, Assistant professor, IIITDM, Kancheepuram, skumaran@iiitdm.ac.in	1. Mr.ArulRaja . R A, SRMIST
2. Dr. R. Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	2. Dr.B.Mohan, Professor, Anna University, mohan@mitindia.edu	2. Dr Suresh Kannan I, SRMIST
3. Dr. A. Velayutham, DRDO, Avadi, velayutham.a@cwrde.drdo.in		

Course Code	18MEE804T	Course Name	INDUSTRY 4.0	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes / Standards	NIL		

Course Learning Rationale (CLR):		The purpose of learning this course is to:				Learning			Program Learning Outcomes (PLO)																	
CLR-1 :	Acquire knowledge on principles of industry 4.0 and building blocks of industry 4.0					1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15			
CLR-2 :	Acquire knowledge on IoT enabled manufacturing systems					Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3			
CLR-3 :	Understand cloud based cyber physical systems in manufacturing								H	-	M	-	-	-	-	-	-	-	-	-	-	M	H	-	-	H
CLR-4 :	Apply data analytics in manufacturing								H	-	M	L	H	-	-	-	-	-	-	-	-	H	H	-	-	H
CLR-5 :	Understand and apply additive manufacturing technologies								H	L	M	L	L	-	-	-	-	-	-	-	-	M	M	-	-	M
CLR-6 :	Acquire knowledge on technologies and application of industry 4.0								H	-	H	L	L	-	-	-	-	-	-	-	-	M	M	-	-	M
									H	-	H	L	L	-	-	-	-	-	-	M	L	-	L	M	-	-
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																								
CLO-1 :	Explain the evolution of industry 4.0					2	90	80																		
CLO-2 :	Explain the concept of IoT					1	85	80																		
CLO-3 :	Understand the application areas of IoT in manufacturing					2	85	80																		
CLO-4 :	Explain the concept of cloud manufacturing					2	90	85																		
CLO-5 :	Explain the advances in robotics in the era of industry 4.0					1	90	85																		
CLO-6 :	Identify advances in virtual factory research and application					1	85	80																		

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	1	2	3	Expected Proficiency (%)	Expected Attainment (%)
CLO-1 :	Explain the evolution of industry 4.0		2	90	80		
CLO-2 :	Explain the concept of IoT		1	85	80		
CLO-3 :	Understand the application areas of IoT in manufacturing		2	85	80		
CLO-4 :	Explain the concept of cloud manufacturing		2	90	85		
CLO-5 :	Explain the advances in robotics in the era of industry 4.0		1	90	85		
CLO-6 :	Identify advances in virtual factory research and application		1	85	80		

Duration (Hour)		9	9	9	9	9
S-1	SLO – 1	Industry 4.0 – Definition	The concept of IoT	Concept of cloud manufacturing	Power consumption in manufacturing	Advances of robotics in the era of industry 4.0
	SLO – 2	Why industry 4.0 and why now?	Existing manufacturing paradigms and their limitations – agile manufacturing	Real time production information	Anomaly detection in air conditioner	Recent technological components of robots
S-2	SLO – 1	Phases of industrial developments	Networked manufacturing	Cloud service selection and composition	Anomaly detection in air conditioner	Artificial intelligence
	SLO – 2	Central features of the concept	Reconfigurable manufacturing system	Overall architecture of manufacturing resources configuration method	Smart remote machinery maintenance system	Internet of robot things, Cloud robotics
S-3	SLO – 1	Principles of industry 4.0	Product service system / industrial product service system	Cloud machine model	Smart remote machinery maintenance system	Cognitive approach of cyber physical robotics
	SLO – 2	Main characteristics of industry 4.0	Manufacturing grid Cloud manufacturing	Cloud machine model	Quality perdition in steel manufacturing	Industrial robotic application
S-4	SLO – 1	Building blocks of Industry 4.0	Limitations of agile manufacturing system	Cloud machine model	Quality perdition in steel manufacturing	Advances in virtual factory research and application
	SLO – 2	The value chain	Applications of IoT in Manufacturing system	Application of cyber physical system &IoT	Predicting drilling efficiency	Virtual factory software
S-5	SLO – 1	Creating the value chain	Key features and limitations of IoT in Manufacturing System	Cloud manufacturing framework	Techniques used for predictive analytics	Additive manufacturing technologies and application
	SLO – 2	Benefits of industry 4.0	Architecture of IoT – MS	Manufacturing capability and manufacturing resource	Techniques used for predictive analytics	Advantages and disadvantages of additive manufacturing
S-6	SLO – 1	Challenges of industry 4.0	Integration framework of real time manufacturing information – sharing and integration	Cloud architecture	Forecast accuracy calculation	Application areas of additive manufacturing

	SLO – 2	Smart manufacturing	Real time manufacturing data processing, sharing and exchange service	Approaches to achieve product information sharing	Forecast accuracy calculation	Impact of additive manufacturing techniques on society
S-7	SLO – 1	Industrial internet of things	The work logic of IoT MS, Description of core technologies of IoT MS	Standardization for cloud manufacturing	Real world case study – definition	Impact on manufacturing and supply chain
	SLO – 2	Gateways	IoT enabled smart assembly station	Standardization for cloud manufacturing	Data gathering and cleaning	Digital traceability through production value chain
S-8	SLO – 1	Wireless Communication technologies	Overall architecture of IoT enabled smart assembly station	Overview of cyber security in industry 4.0 era	Automation based lean production	Digital traceability technologies
	SLO – 2	Industry 4.0 – the way forward	IoT enabled smart trolley	Overview of cyber security in industry 4.0 era	Automation based lean production	Architectural framework of the digital traceability system, Application of digital traceability
S-9	SLO – 1	Technology road map for industry 4.0	IoT enabled materials handling	Security threat and vulnerabilities of IoT	Model application	Project management in digital traceability, Examples for IoT in value creation in different industries
	SLO – 2	Technology road map for industry 4.0	Real time information enabled material handling strategy	Cases – cyber security	Model application	smart manufacturing – maturity model, Smart agriculture, Smart city Smart life and smart health

Learning Resources	<ol style="list-style-type: none"> 1. ArshdeepBahga, Vijay Madiseti, Internet of Things – A hands on approach, ArshdeepBahga& Vijay Madiseti, 2014 2. Yingfeng Zhang, Fei Tao, Optimization of manufacturing using internet of things, Academic Press Elsevier, 2017. 3. Lihui Wang, Xi Vincent Wang, Cloud based cyber physical systems in manufacturing, Springer International Publishing, 2018. 	<ol style="list-style-type: none"> 4. Christoph Jan Bartodziej, The concept of industry 4.0 – An empirical analysis of technologies and applications in production logistics, Springer Gabler, 2017 5. Alp Ustundag, EmriChevikan, Industry 4.0 - Managing the digital transformation, Springer International Publishing, 2018.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% Weightage)								Final Examination (50% Weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100%		100%		100%		100%		100%	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from industry	Expert from higher technical institution	Internal Expert
1. Mr. P.Kartikeyan, Head – Operations Improvement, Nokia India, kartikeyan.p@nokia.com	1. Dr.K.Senthilkumaran, Assistant professor, IIITDM, Kancheepuram, skumaran@iiitdm.ac.in	1. Mr. Dinakar. N, SRMIST
2. Dr. R. Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	2. Dr.B.Mohan, Professor, Anna University, mohan@mitindia.edu	2. Dr. Suresh Kannan I, SRMIST
3. Dr. A. Velayutham, DRDO, Avadi, velayutham.a@cvrde.drdo.in		

Course Code	18MEE805T	Course Name	MANUFACTURING EXECUTION SYSTEMS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Course	Nil	Co-requisite Course	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book/Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1:	Identify the fundamental concepts of MES.	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2:	Utilize the core functions of MES.	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3:	Apply technical aspects of MES.	Expected Proficiency (%)	Problem Analysis
CLR-4:	Identify the requirements of the factory of the future.	Expected Attainment (%)	Design & Development
CLR-5:	Evaluation of Cost Effectiveness in MES.		Analysis, Design, Research
CLR-6:	Implementation in Production and its significance.		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1:	Apply the fundamental concepts and core function of MES	3 90 80	H H H H - - - - M M M H H - H
CLO-2:	Understand what and why MES in modern production systems	3 90 80	H H H M - - - - H L M H H - H
CLO-3:	Setup, analysis, and giving possible application of MES	3 90 80	H H H H - - - - H H M H H - H
CLO-4:	Know the connection of function within production systems to MES	3 90 80	H M M M - - - - H M H H H - H
CLO-5:	Identify the requirements of the factory of the future	3 90 80	H H M H - - - - M H M H H - H
CLO-6:	Evaluate the Cost Effectiveness in MES	3 90 80	H H L M - - - - L H M H H - H

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Historical Development of MES, Standards of MES	Core Function—Production Flow-Oriented Design	Integration within the Overall Process	Software Architecture, Fundamental Variants
	SLO-2	Development of Business Data Processing	Cross-System Cohesiveness, Classification in the Overall System	Order Data Management	Overview of Central Components
S-2	SLO-1	Definitions of Terms - Classification of Terms	General and Complete Data Model, Origins of Master Data	Supply Management within the MES, Demand Planning	Platform Independence, Scalability
	SLO-2	Company Management Level	Data Model for Product Definition, Relevant Concepts	Interaction between the ERP System and the MES, Material Warehousing Costs	Flexible Adjustment versus Suitability for Updates
S-3	SLO-1	Production Management Level	The Operation, Work Plan, Parts List	The Planning Process and Planning Objectives	MES and Service-Oriented Architecture
	SLO-2	Control/Automation Level	Change Management and Product History	Forward Planning/Reverse Planning/Bottleneck Planning	Database, Resource Monitoring
S-4	SLO-1	Shortfalls of Existing Architectures and Solutions	Data Model for Resource Management.	Collision-Free Planning of a Time Container	Scaling the Database System
	SLO-2	Patchwork, No Common Database, Excessive Response Times	Description of Production Environment	The Importance of the Control Station	Data Management and Archiving, Running Maintenance
S-5	SLO-1	High Operating and Management Outlay	Description of Production Environment	Personnel Planning and Release of Orders	Interfaces with Other IT Systems
	SLO-2	Demands of Future Production Management Systems	Description of Production Environment	General Information on Order Processing and Classification	Usage and Visualization, Reporting, Automated Information Distribution
S-6	SLO-1	Target Management, Integration of Applications and Data	Production Personnel	Order Preparation and Setup	Value-Benefit Analysis, General Information on Cost Effectiveness
	SLO-2	Real-Time Data Management	Operating Resources	Order Control, Managing the Production Bin, Material Flow Control	Performance Measurement

S-7	SLO-1	Lean Sigma and MES	Materials and Preliminary Products	Order Processing and Operating DataRecording	General Information on Evaluation	Basic Quantity Units and ProductionUnits
	SLO-2	Commonalities between Existing Approachesand MES	Information and Documents	Process and Quality Assurance	The Benefits of an MES	Tasks of the MES, Challenges,
S-8	SLO-1	Norms and Guidelines, Recommendations	System and Auxiliary Data	Performance Data	Integrated Data Transparency, Reducing Time Usage	Realization and Implementation
	SLO-2	Adjacent Areas, Product Lifecycle Management	Order Fulfillment Data and Orders	Maintenance Management	Reducing Administration Expenses,Improved Customer Service	The MES as a Medium of Product-Development Management
S-9	SLO -1	Implementation Strategies	Production Data, Operating Data, andMachine Data	Preventive Maintenance and Repair	Early Warning System, Real-Time CostControl	Standardization of Function Modules
	SLO -2	Points of Contact with MES	Derived Performance Data and Figures	Alarm Management	The Costs of an MES	Merging Consultancy Activities andIT Systems

Learning Resources	<ol style="list-style-type: none"> 1. Heiko Meyer, Franz Fuchs, Klaus Thiel, Manufacturing Execution Systems, McGraw-Hill, 2009. 2. Jürgen Kletti, Manufacturing Execution System – Springer, 2010. 3. Bianca Scholten, MES Guide for Executives – International society of Automation, 2009. 	4. Michael McClellan, Applying Manufacturing Execution Systems, CRC Press, 2007.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% Weightage)								Final Examination (50% Weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100%		100%		100%		100%		100%	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. P.Kartikeyan, Head – Operations Improvement, Nokia India, kartikeyan.p@nokia.com	1. Dr.K.Senthilkumaran, Assistant professor, IIITDM, Kancheepuram, skumaran@iiitdm.ac.in	1. Mr.S.Thamilarasu, SRM IST
2. Dr. R. Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	2. Dr.B.Mohan, Professor, Anna University, mohan@mitindia.edu	2. Dr. Suresh Kannan I, SRMIST
3. Dr. A. Velayutham, DRDO, Avadi, velayutham.a@cvrde.drdo.in		

Course Code	18MEE806T	Course Name	ADDITIVE MANUFACTURING TECHNOLOGY				Course Category	E	Professional Elective			L	T	P	C												
												3	0	0	3												
Pre-requisite Course		Nil		Co-requisite Course				Nil		Progressive Courses		Nil															
Course Offering Department		Mechanical Engineering				Data Book/Codes/Standards				Nil																	
Course Learning Rationale (CLR):		The purpose of learning this course is to:						Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Learn about Sustainable and Green Manufacturing Techniques						Level of Thinking (Bloom)	1	2	3	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Aspects of Green supply chain and clean energy in manufacturing																										
CLR-3 :	Understanding the principle of green manufacturing																										
CLR-4 :	Learn about green in Manufacturing Processes																										
CLR-5 :	Introduce the concept of life cycle analysis (LCA)																										
CLR-6 :	Sustainability aspects in modern manufacturing enterprises																										
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																									
CLO-1 :	Understand the need for green and sustainable manufacturing						1	80	70	M	-	M	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-2 :	Identification of clean energy and green supply chain in manufacturing						2	85	75	H	-	-	-	M	-	-	-	-	-	-	-	-	-	H	-	-	
CLO-3 :	Apply the concepts green principles and industrial ecology tools						2	75	70	H	M	H	H	-	-	-	-	-	-	-	-	M	H	-	-	-	
CLO-4 :	Identification the strategies for green manufacturing						2	80	75	H	-	M	-	M	-	-	-	-	-	-	-	-	H	-	M	-	
CLO-5 :	Analyze the technologies enabling green manufacturing						1	75	70	H	-	-	M	-	-	-	-	-	-	-	M	M	-	H	-	-	
CLO-6 :	Apply the concepts of sustainability in modern manufacturing enterprises						2	80	70	M	-	-	M	M	-	L	-	-	-	-	M	-	-	H	-	-	
Duration (hour)		9		9		9		9		9		9															
S-1	SLO-1	History and Need of AM		Preparation of CAD Model:		Stereo lithography (SLA) : Introduction to SLA		Selective Laser Sintering (SLS): Introduction to SLS		Materials for AM: Metals, Biomaterials for AM																	
	SLO-2	Evolution of AM		Interfacing of CAD and AM , File formats used in AM		Basic concepts and Working Principle of SLA		Basic concepts and Working Principle of SLS		Polymers for AM																	
S-2	SLO-1	Basic concepts and working principle of AM		Introduction to STL File format		Constructional details for SLA		Constructional details for SLS		Ceramics for AM																	
	SLO-2	Additive Manufacturing vs Subtractive manufacturing		Problems (Errors) with STL file		Advantages of SLA		Advantages of SLS		Composites for AM																	
S-3	SLO-1	AM Process chain		.Reverse engineering: Need for Reverse engineering, Introduction to Co-ordinate Measuring machine (CMM)..		Limitations of SLA		Limitations of SLS		Applications of AM in Manufacturing and tooling																	
	SLO-2	AM Process chain		Reverse engineering: CMM measurement process – Data collection, Digitization from surface, Preprocessing, Surface fitting.		Applications of SLA		Applications of SLS		Applications of AM in Space																	
S-4	SLO-1	Rapid prototyping on product development		Rapid tooling		Fused deposition modelling (FDM) : Introduction to FDM		Laser Engineered Net Shaping (LENS): Introduction to LENS		Applications of AM in Automotive industry																	
	SLO-2	Rapid prototyping on product development		Rapid tooling		Basic concepts and Working Principle of FDM		Basic concepts and Working Principle of LENS		Applications of AM in Aerospace industry																	
S-5	SLO-1	Classification of AM processes		Design for AM: Part orientation		Constructional details for FDM		Constructional details for LENS		Applications of AM in Biomedical industry																	
	SLO-2	Classification of AM processes		Removal of supports		Advantages of FDM		Advantages of LENS		Applications of AM in Biomedical industry																	

S-6	SLO-1	Other Related technologies: Overview about other technologies related to AM	Hollowing out parts	Limitations of FDM	Limitations of LENS	Applications of AM in Jewellery industry
	SLO-2	Computer Aided Engineering (CAE)	Inclusion of Undercuts and other manufacturing constraints	Applications of FDM	Applications of LENS	Applications of AM in Various other fields.
S-7	SLO-1	Haptic based CAD	Interlocking features, Reduction of part count in assembly	Laminated Object Manufacturing (LOM) : Introduction to LOM	Electron Beam Melting (EBM): Introduction to EBM	Introduction to Direct digital manufacturing (DDM)
	SLO-2	Haptic based CAD	Identification markings / numbers	Basic concepts and Working Principle of LOM	Basic concepts and Working Principle of EBM	Rapid prototyping vs DDM
S-8	SLO-1	AM unique capabilities: Shape complexity, Hierarchical complexity	Engineering design rules for AM: Tolerances – Digital to Object	Constructional details for LOM	Constructional details for EBM	Future directions of AM
	SLO-2	AM unique capabilities: Functional complexity, Material complexity	Design freedom, Relative fit	Advantages of LOM	Advantages of EBM	Future directions of AM
S-9	SLO-1	Benefits of AM.	Flexures, Hinges, Snap fits	Limitations of LOM	Limitations of EBM	Digiproneurship
	SLO-2	Limitations of AM.	Orientation and Clamping	Applications of LOM	Applications of EBM	Digiproneurship

Learning Resources	<ol style="list-style-type: none"> Li Yang, Keng Hsu, Brian Baughman, Donald Godfrey, Francisco Medina, Mamballykalathil Menon, Soeren Wiener, Additive Manufacturing of Metals The Technology, Materials, Design and Production", Springer 2017. Ian Gibson, David Rosen, Brent Stucker, Additive Manufacturing Technologies_ 3D Printing, Rapid Prototyping, and Direct Digital Manufacturing", Springer 2015. Andreas Gebhardt, Understanding Additive Manufacturing. Rapid Prototyping - Rapid Tooling - Rapid manufacturing, Hanser publications 2011. T. S. Srivatsan and T. S. Sudarshan, "Additive Manufacturing Innovations, Advances, and Applications, Taylor & Francis group 2016. Ali K Kamrani, Emad Abouel Nasr, Rapid prototyping - Theory and Practice", Springer 2005.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% Weightage)								Final Examination (50% Weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100%		100%		100%		100%		100%	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. P.Kartikeyan, Head – Operations Improvement, Nokia India, kartikeyan.p@nokia.com	1. Dr.K.Senthilkumaran, Assistant professor, IIITDM, Kancheepuram, skumaran@iiitdm.ac.in	1. Mr.T.Gopi, SRMIST
2. Dr. R. Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	2. Dr.B.Mohan, Professor, Anna University, mohan@mitindia.edu	2. Dr. Suresh Kannan I, SRMIST
3. Dr. A. Velayutham, DRDO, Avadi, velayutham.a@cwrde.drdo.in		

Course Code	18MEE807T	Course Name	INDUSTRIAL ROBOTICS&MATERIAL HANDLING SYSTEMS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Course	Nil	Co-requisite Course	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering			Data Book/Codes/Standards	Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Introduce the basic concepts, parts of robots and types of robots				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Familiar with the various drive systems for robot, sensors and their applications in robots and programming of robots				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Select the robots according to its usage																					
CLR-4 :	Know about the various applications of robots, justification and implementation of robot																					
CLR-5 :	Know about material handling in a system																					
CLR-6 :	Acquire knowledge on various material handling equipment used both in automated and non-automated systems																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	Understand the fundamentals of robot technology, sensors, drives and systems				2	90	85	H	-	H	L	M	-	-	-	-	-	H	-	H	-	H
CLO-2 :	Recognize the ideas about robot cell design, work cell control				2	90	85	H	-	H	L	M	-	-	-	-	-	H	-	H	-	H
CLO-3 :	Have knowledge about various applications of robots in material handling				1	90	85	M	-	M	L	M	-	-	-	-	-	L	-	H	-	H
CLO-4 :	Understand the concepts of automated material handling and its types				2	90	85	L	-	L	L	M	-	-	-	-	-	M	-	H	-	H
CLO-5 :	Identify the application of automated guided vehicles in material handling				1	90	85	M	-	H	L	M	-	-	-	-	-	M	-	H	-	H
CLO-6 :	Recognize about vehicle guidance and routing in material handling				2	90	85	H	-	H	L	M	-	-	-	-	-	M	-	H	-	H

Duration (hour)	9	9	9	9	9	9
S-1	SLO-1	Automation and Robotics	Robot cell layouts- Robot centered cell	General consideration in Robot Material Handling	Automated material handling	Automated Guided Vehicle Systems - Introduction
	SLO-2	History of Robots	In line Robot cell	Material Transfer Application	Hand trucks, Powered trucks	Introduction to Drones
S-2	SLO-1	Robot Anatomy	Mobile robot cell	Pick and place operations	Cranes monorails and Hoists	Driverless Trains
	SLO-2	Robot configurations	Multiple robots and machine Interface	Palletizing and related operations	Conveyors systems	AGVs Pallet Trucks
S-3	SLO-1	Robot motions, Joint Notation Scheme	MR- MI Example	Machine loading and unloading	Selection of material handling equipment	AGVs Unit load carriers
	SLO-2	Work volume	Other considerations in work cell design	Die casting, plastic molding	Principles of material handling	Driverless train operation
S-4	SLO-1	Polar, Cylindrical, Cartesian	Work cell control	Forging, Machining operations	Roller, stake wheel conveyor	Storage/ Distribution system
	SLO-2	Robot drive systems	Sequence control	Stamping press operations	Belt, chain conveyors	Assembly line operation
S-5	SLO-1	Speed of motion	operation interface	Robots in spot welding	Overhead trolley conveyor	Miscellaneous operation
	SLO-2	Load carrying capacity	Safety monitoring	Robots in arc welding	slat conveyors	Functions of AGV
S-6	SLO-1	4 types of robot control system	Interlocks	Problems for Robots in arc welding	In floor towline conveyor	Vehicle guidance and routing
	SLO-2	Precision of movement	Error detection and recovery	Features of the welding robot	Cart on track conveyor	Operation of on board sensor system
S-7	SLO-1	End effectors- types of grippers	Work cell controller	Sensors in arc welding robot	Other handling equipment, Dial Indexing tables	Frequency select, path switch select method

	SLO-2	Gripper selection and design	Robot controller	Vision based systems, Benefits	Elevators, Pipelines	Traffic control and safety
S-8	SLO-1	Transducers and sensors	Electro mechanical Relays, Programmable controllers	Robots in Spray coating	Containers, Highway Tractor trailers	On board vehicle sensing, zone blocking
	SLO-2	Tactile sensors	A computer as the work cell controller	Immersion and flow coating, Spray coating methods	Railway trains, Cargo aircraft, Ship, barges.	System management, On board control panel
S-9	SLO-1	Proximity and Range sensors	Robot cycle time analysis	Benefits of robot spray coating	Types of AS / RS	Remote call stations, Central computer control
	SLO-2	Uses of sensors in robotics	Elements in RTM	Other Processing operations using robots	Advanced ware housing robots, Applications.	Automotive Intelligent vehicles

Learning Resources	<ol style="list-style-type: none"> 1. Mikell P Groover, Mitchell Weiss, Rogen N Nagel, Nicholas G Odrey, Ashish Dutta, Industrial Robotics Technology, Programming, and Applications, Tata McGraw Hill Special Indian Edition, 2012. 2. K.Lalit Narayan, K.Mallikarjuna Rao, Computer Aided Design and Manufacturing, Prentice Hall of India, 2008. 3. Mikell P Groover, Mitchell Weiss, Roger N Nagel, Industrial Robotics Technology, Programming, and Applications, Tata McGraw Hill Publishers, 2008. 	<ol style="list-style-type: none"> 4. S.R.Deb, S.Deb, Robotics Technology & Flexible Automation, Tata McGraw-Hill Education, 2012. 5. James A Rehg, Introduction to Robotics in CIM system, Prentice Hall, 2002. 6. S.K.Saha, Introduction to Robotics, Tata McGraw Hill Publishing Company Limited, 2014.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% Weightage)								Final Examination (50% Weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100%		100%		100%		100%		100%	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. P.Kartikeyan, Head – Operations Improvement, Nokia India, kartikeyan.p@nokia.com	1. Dr.K.Senthilkumaran, Assistant professor, IIITDM, Kancheepuram, skumaran@iiitdm.ac.in	1. Mr.M.KamatchiHariharan, SRMIST
2. Dr. R. Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	2. Dr.B.Mohan, Professor, Anna University, mohan@mitindia.edu	2. Dr. Suresh Kannan I, SRMIST
3. Dr. A. Velayutham, DRDO, Avadi, velayutham.a@cvrde.drdo.in		

Course Code	18MEE808T	Course Name	SUSTAINABLE GREEN MANUFACTURING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Course	Nil	Co-requisite Course	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book/Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Learn about Sustainable and Green Manufacturing Techniques	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Aspects of Green supply chain and clean energy in manufacturing		
CLR-3 :	Understanding the principle of green manufacturing		
CLR-4 :	Learn about green in Manufacturing Processes		
CLR-5 :	Introduce the concept of life cycle analysis (LCA)		
CLR-6 :	Sustainability aspects in modern manufacturing enterprises		

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Understand the need for green and sustainable manufacturing	2	90	90	H	H	-	-	-	H	H	-	-	-	-	H	-	-	H
CLO-2 :	Identification of clean energy and green supply chain in manufacturing	2	85	80	H	-	H	H	-	H	H	-	-	-	-	H	-	-	H
CLO-3 :	Apply the concepts green principles and industrial ecology tools	2	85	80	H	-	M	L	-	H	H	-	-	-	-	-	-	-	H
CLO-4 :	Identification the strategies for green manufacturing	2	85	85	M	L	-	-	-	H	H	-	-	-	-	H	-	-	M
CLO-5 :	Analyze the technologies enabling green manufacturing	2	90	85	M	L	H	H	M	H	H	-	H	-	-	H	-	-	M
CLO-6 :	Apply the concepts of sustainability in modern manufacturing enterprises	2	85	70	H	H	H	H	M	H	H	-	H	-	-	H	-	-	M

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Concept of Sustainability	Introduction to thermodynamics analysis in manufacturing processes	Principle of Green Manufacturing	Functions and types of cutting fluids	Introduction to Green supply chain
	SLO-2	Introduction to green Manufacturing	Thermodynamic framework of manufacturing processes	Cleaner Production , Dematerialization	Problems related to cutting fluids	Green Supply Chain
S-2	SLO-1	Motivations for sustainable development	Estimation of minimum work for materials transformations	Closed Loop Production systems Economic and Ecological Benefits of Closed-Loop Systems	Dry machining	Issues in Green supply Chain Techniques
	SLO-2	Motivations for sustainable Manufacturing	Estimation of minimum work for materials transformations	Design for Disassembly, Industrial Metabolism	Advantages and Limitations	Green packaging
S-3	SLO-1	Productivity and sustainability	Estimation of minimum work for materials transformations	Adoption of low carbon technologies	Near dry machining	The Packaging supply chain
	SLO-2	Metrics for green manufacturing	Temperature and Pressure Changes for Open Materials-Processing Systems	Need to reduce the carbon footprint of manufacturing operations	Advantages, Disadvantages	Future of Green Supply Chain
S-4	SLO-1	Societal metrics	Energy use for elastic – plastic deformation	Life Cycle assessment	Minimum Quantity Lubrication systems	Lean Production
	SLO-2	Economic Metrics	Electric energy used in manufacturing processes	Life cycle assessment elements	Economics of Environmentally Friendly Machining	Types of wastes
S-5	SLO-1	Environmental metrics	Resource accounting	Life cycle assessment procedure	Development of Environmentally Friendly cutting fluids, cutting tools and machine tools	Lean Manufacturing Techniques
	SLO-2	Barriers to Green Manufacturing	Introduction to Clean Energy Technologies	Life Cycle Assessment (LCA) of Machine tools	Enabling Technologies for Green Manufacturing	Agile Manufacturing

S-6	SLO-1	Advantages and Limitations of Green manufacturing	Solar Photovoltaic	Design for Environment	Sustainable solutions	Components of the agile manufacturing system/enterprise
	SLO-2	Environmental Impact of Manufacturing	Wind Energy	Product life extension and the service economy	Adoptronics in Machine tools	Comparison between agile and traditional manufacturing enterprises
S-7	SLO-1	Standards for green manufacturing	Fuel cells	Eco Labelling, Industrial Ecology tools	Reconfigurable Machine tools	Analysis of Manufacturing Firms for Agility
	SLO-2	ISO 14000	Comparison of lean Energy Technologies	Case studies in Industrial Ecology	Process Monitoring System	Remanufacturing
S-8	SLO-1	OHSAS 18000	Application Potentials of clean energy supply in green manufacturing	Case studies in Industrial Ecology	Smart building blocks	Recycling
	SLO-2	Sustainability rating schemes	Cost benefit of environmental emission mitigation through clean energy supply	How is Industrial Ecology Viewed by Industry	Add-ons for machine tool upgrade	Materials for sustainability and recycling
S-9	SLO-1	Strategies for Green Manufacturing	Technological Performance of clean Energy Supply.	Awareness of Industrial Ecology and its components	Applying Sensor Flows in Decision Making (Automated Manufacturing) Manufacturing Complexity	Sustainability Assessments of Competitive Manufacturing Strategies
	SLO-2	Strategies for Green Manufacturing	Energy efficient manufacturing processes	Case studies of product improvement and redesign	Environmental implications of nano manufacturing and Semiconductor manufacturing	Sustainability Assessment for Industrial Estates

Learning Resources	<ol style="list-style-type: none"> 1. Dornfeld, David A., ed. Green manufacturing: fundamentals and applications. Springer Science & Business Media, 2012. 2. Gouge, Michael, and Pan Michaleris, eds. Thermo-mechanical modeling of additive manufacturing. Butterworth-Heinemann, 2017. 3. Davim, J. Paulo, ed. Sustainable Manufacturing. John Wiley & Sons, 2013. 4. Dixit, Uday S., D. K. Sarma, and J. Paulo Davim. Environmentally friendly machining. Springer Science & Business Media, 2012. 5. Stark, Rainer, Günther Seliger, and Jérémy Bonvoisin. Sustainable Manufacturing. Springer, 2017. 	<ol style="list-style-type: none"> 6. Garbie, Ibrahim. Sustainability in manufacturing enterprises: Concepts, analyses and assessments for industry 4.0. Springer, 2016. 7. Madu, Christian N., ed. Handbook of environmentally conscious manufacturing. Springer Science & Business Media, 2012. 8. Fiksel, Joseph. Design for environment: a guide to sustainable product development: eco-efficient product development. McGraw Hill Professional, Boston, 2009.
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Learning Assessment											
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		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
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Level 3	Analyze	20%	-	30%	-	30%	-	30%	-	30%	-
	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create	20%	-	30%	-	30%	-	30%	-	30%	-
	Total	100%		100%		100%		100%		100%	

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Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. P.Kartikeyan, Head – Operations Improvement, Nokia India, kartikeyan.p@nokia.com	1. Dr.K.Senthilkumaran, Assistant professor, IITDM, Kancheepuram, skumaran@iitdm.ac.in	1. Dr. Suresh Kannan I, SRMIST
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3. Dr. A. Velayutham, DRDO, Avadi, velayutham.a@cvrde.drdo.in		

Course Code	18MEE809J	Course Name	DATABASE MANAGEMENT SYSTEM		Course Category	E	Professional Elective		L	T	P	C																																																																																																																																																																																																													
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Pre-requisite Course		Nil				Co-requisite Course	Nil	Progressive Courses	Nil																																																																																																																																																																																																																
Course Offering Department		Mechanical Engineering			Data Book/Codes/ Standards			Nil																																																																																																																																																																																																																	
Course Learning Rationale (CLR):		The purpose of learning this course is to:				<table><tr><th colspan="3">Learning</th></tr><tr><th>1</th><th>2</th><th>3</th></tr><tr><td rowspan="5">Level of Thinking (Bloom)</td><td rowspan="5">Expected Proficiency (%)</td><td rowspan="5">Expected Attainment (%)</td><td colspan="15">Program Learning Outcomes (PLO)</td></tr><tr><td>1</td><td>2</td><td>3</td><td>4</td><td>5</td><td>6</td><td>7</td><td>8</td><td>9</td><td>10</td><td>11</td><td>12</td><td>13</td><td>14</td><td>15</td></tr><tr><td>Engineering Knowledge</td><td>Problem Analysis</td><td>Design & Development</td><td>Analysis, Design, Research</td><td>Modern Tool Usage</td><td>Society & Culture</td><td>Environment & Sustainability</td><td>Ethics</td><td>Individual & Team Work</td><td>Communication</td><td>Project Mgt. & Finance</td><td>Life Long Learning</td><td>PSO - 1</td><td>PSO - 2</td><td>PSO - 3</td></tr><tr><td>H</td><td>M</td><td>-</td><td>M</td><td>-</td><td>-</td><td>-</td><td>-</td><td>M</td><td>H</td><td>-</td><td>M</td><td>-</td><td>-</td><td>-</td></tr><tr><td>H</td><td>L</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>H</td><td>-</td><td>L</td><td>-</td><td>-</td><td>-</td></tr><tr><td>CLO-1 :</td><td colspan="4">Develop the terminology and features in database</td><td>2</td><td>90</td><td>85</td><td>H</td><td>M</td><td>-</td><td>M</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td></tr><tr><td>CLO-2 :</td><td colspan="4">Analyze the information of storage details</td><td>2</td><td>90</td><td>85</td><td>H</td><td>L</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>H</td><td>-</td><td>L</td><td>-</td><td>-</td><td>-</td></tr><tr><td>CLO-3 :</td><td colspan="4">Transform an information into relational database</td><td>2</td><td>90</td><td>85</td><td>H</td><td>M</td><td>M</td><td>M</td><td>-</td><td>-</td><td>-</td><td>-</td><td>M</td><td>H</td><td>-</td><td>H</td><td>-</td><td>-</td></tr><tr><td>CLO-4 :</td><td colspan="4">Ability to work in data manipulation</td><td>2</td><td>90</td><td>85</td><td>H</td><td>L</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>M</td><td>L</td><td>-</td><td>L</td><td>-</td><td>-</td></tr><tr><td>CLO-5 :</td><td colspan="4">Analyze the Client/Server and Internet Database Environment</td><td>2</td><td>90</td><td>85</td><td>H</td><td>M</td><td>-</td><td>L</td><td>-</td><td>-</td><td>-</td><td>-</td><td>H</td><td>-</td><td>M</td><td>-</td><td>-</td><td>-</td></tr><tr><td>CLO-6 :</td><td colspan="4">Write queries for design and manipulation of database table using MySQL or Oracle</td><td>2</td><td>90</td><td>85</td><td>H</td><td>H</td><td>M</td><td>M</td><td>M</td><td>-</td><td>-</td><td>-</td><td>M</td><td>H</td><td>-</td><td>H</td><td>-</td><td>-</td></tr></table>			Learning			1	2	3	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Program Learning Outcomes (PLO)															1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3	H	M	-	M	-	-	-	-	M	H	-	M	-	-	-	H	L	-	-	-	-	-	-	H	-	L	-	-	-	CLO-1 :	Develop the terminology and features in database				2	90	85	H	M	-	M	-	-	-	-	-	CLO-2 :	Analyze the information of storage details				2	90	85	H	L	-	-	-	-	-	H	-	L	-	-	-	CLO-3 :	Transform an information into relational database				2	90	85	H	M	M	M	-	-	-	-	M	H	-	H	-	-	CLO-4 :	Ability to work in data manipulation				2	90	85	H	L	-	-	-	-	-	-	M	L	-	L	-	-	CLO-5 :	Analyze the Client/Server and Internet Database Environment				2	90	85	H	M	-	L	-	-	-	-	H	-	M	-	-	-	CLO-6 :	Write queries for design and manipulation of database table using MySQL or Oracle				2	90	85	H	H	M	M	M	-	-	-	M	H	-	H	-	-
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Duration (hour)	12	12	12	12	12	12
S-1	SLO-1	Introduction to database Systems	Entity types	Relational Model	Structured Query Language (SQL)	Introduction to parallel database
	SLO-2	History of DBMS applications	Entity sets	Structural of database	SQL Data definition	I/O Parallelism
S-2	SLO-1	File System versus a DBMS	Attributes and Keys	Structure of relational Databases	Queries on Single Relation	Lab 13: Simple PL/SQL Programs, Use of Exceptions, Cursor, Procedure, Function, Trigger, Sequence
	SLO-2	Database Language	Basic building blocks	Keys, Schema Diagram	Queries on multiple Relations	
S-3	SLO-1	Lab 1: Creating database table	Levels of data abstraction	Relational Algebra	Overview of SQL	Security :Database security – Granting,Removing
	SLO-2		Physical Schemas and Conceptual Schemas	Relational Algebra - Set Operation, Renaming,	Basic structure of SQL Queries	Type of Security
S-4	SLO-1	Lab 2: DDL Commands	Overview ofEntity-Relationship (E-R) Model	Relational Algebra - Joins	Lab 9:Simple queries	Control measures
	SLO-2		Relationship set, Entity set	Relational Algebra - Division		Database Recovery
S-5	SLO-1	Database Interface	Database design and Entity-Relationship(ER) Model, Design alternatives	Lab 7: Joining tables	Lab 10: Nested queries	Storage, Data access
	SLO-2	Form based Interface, Graphical based Interface	Constraints, Entity-Relationship (ER)-Diagrams, Roles and Structural Constraints			Buffer Management
S-6	SLO-1	Database Environment	Lab 4: Basic SELECT statements	Relational Algebra - Division	Data definition commands, DML Commands, Set operations	Database – Backup
	SLO-2	Database Component Modules		Extended Relational Algebra Operations	Aggregate functions	Recovery Algorithm
S-7	SLO-1	Database System utilities	Lab 5: Advanced SELECT statements	Views	Lab 11:Creation, Insertion, Updating, Deletion ofViews operation	Lab 14: DBMS for CAD software design
	SLO-2	Database System Architecture		Functional Dependency		

S-8	SLO-1	Lab 3: Data Manipulation Commands	Entity-Relationship(ER) Design Issues	Various process in designing a Database	Aggregate functions - Basic aggregation	Emerging Database technology - Mobile database
	SLO-2		E-R Model and Enhanced entity-relationship (EER) Model	Lab 8: Basic SQL functions	Aggregate functions- Aggregation with Grouping	Emerging Database technology - Multimedia database
S-9	SLO-1	Data Independence	Enhanced entity-relationship (EER) Model	Normalization using functional dependencies	Lab 12: Basics of PL/SQL	Access controls
	SLO-2	Data Mappings	Enhanced entity-relationship(EER)-Specialization			Security for internet applications
S-10	SLO-1	Structure of DBMS	Enhanced entity-relationship(EER)-Generalization	Decomposition	Null values, Joins, Nested queries	Web Technology in Smart Manufacturing
	SLO-2	Security and Authorization,	Enhanced entity-relationship(EER)-Attribute Inheritance	Boyce-Codd Normal Form	Client/Server Database Environment	Web Technology in Smart Manufacturing
S-11	SLO-1	Database Tuning	Constrain on Generalization	DBMS application in Computer Integrated manufacturing	Basics of Ontology Language and its applications.	DBMS for computer integrated manufacturing
	SLO-2	Data Models	Aggregation	3NF, Correctness of the 3NF Algorithm	Design Challenges in SPARQL,	Material Handling System Design
S12	SLO-1	Types of DBMS	Lab 6: Constraints in Tables	Comparison of BCNF and 3NF	SPARQL Query Forms,	Lab 15:Report Generation for Material Handling System Design
	SLO-2	Objective data model and Hierarchical data model		Normalization using multivalued dependencies	SPARQL Graph Patterns	

Learning Resources	<ol style="list-style-type: none"> 1. RamezElmasri, Shanmkant B., <i>Fundamentals of Database System</i>, 5th Edition, Pearson, 2011. 2. Silberschatz, Abraham, Henry F. Korth, and ShashankSudarshan. <i>Database system concepts</i>. Vol. 4. New York: McGraw-Hill, 1997. 3. Ramakrishnan, Raghu, and Johannes Gehrke. <i>Database management systems</i>. McGraw Hill, 2000. 4. Hansen, Gary W., and James V. Hansen. <i>Database management and design</i>. 1996. 	<ol style="list-style-type: none"> 5. Peter rob, Carlos Coronel, <i>Database Systems – Design, Implementation, and Management</i> , 9th Edition, 2009, Thomson Learning System <p>Software Needed: Oracle 8, MySQL</p>

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% Weightage)								Final Examination (50% Weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100%		100%		100%		100%		100%	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. P.Kartikeyan, Head – Operations Improvement, Nokia India, kartikeyan.p@nokia.com	1. Dr.K.Senthilkumaran, Assistant professor, IIITDM, Kancheepuram, skumaran@iiitdm.ac.in	1. Mr. Joseph Abraham Chacko, SRMIST
2. Dr. R. Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	2. Dr.B.Mohan, Professor, Anna University, mohan@mitindia.edu	2. Dr. Suresh Kannan I, SRMIST
3. Dr. A. Velayutham, DRDO, Avadi, velayutham.a@cvrde.drdo.in		

ACADEMIC CURRICULA

Professional Elective Courses

MECHATRONICS ENGINEERING

Regulations - 2018



SRM INSTITUTE OF SCIENCE AND TECHNOLOGY

(Deemed to be University u/s 3 of UGC Act, 1956)

Kattankulathur, Kancheepuram, Tamil Nadu, India

Course Code	18MHE401T	Course Name	ELEMENTS OF MECHATRONICS SYSTEMS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechatronics Engineering	Data Book / Codes/Standards			Nil

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Identify the key elements of mechatronics system and the design issues	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Identify the different types of sensors used in mechatronics system	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Identify the different types of actuators used in mechatronics system	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Identify the different types of controllers used in mechatronics system	Expected Attainment (%)	Design & Development
CLR-5 :	Identify the mechatronics system applied for different applications		Analysis, Design, Research
CLR-6 :	Utilize the elements of mechatronics systems for different applications		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Analyze the various elements of mechatronics system	1 85 80	H L - H M - L L M - - - M - - -
CLO-2 :	Analyze the different types of sensor for developing a mechatronics system	2 85 80	H H - H M - L L M - - - - - - -
CLO-3 :	Analyze the different types of actuators for developing a mechatronics system	2 85 80	H H - H M - L L M - - - - - - -
CLO-4 :	Analyze the different types of controllers for developing a mechatronics system	2 85 80	H H - H M - L L M - - - - - - -
CLO-5 :	Apply the mechatronics elements in to various applications	2 85 80	H H - H M - L L M - - - - - - -
CLO-6 :	Apply the sensors and actuators for developing a mechatronics system	2 85 80	H H - H M - L L M - - - - - - -

	Introduction to Mechatronics Systems	Sensors	Actuation System	Controllers	Applications of Mechatronics Systems
Duration (hour)	9	9	9	9	9
S-1	SLO-1 Introduction to mechatronics system	Sensor characteristics	Introduction to electrical ,mechanical, hydraulic and pneumatic actuation system	Proportional, Integral controller	Car park barriers using PLC.
	SLO-2 Definition of mechatronics: Concurrent and sequential integration	Signal conditioning system	Solid state switches	Derivative and PID controller	Bar code reader
S-2	SLO-1 The Design process	Resistive sensors	Construction and operation of solenoids	Example: Boiler control using PID	Coin counting machine
	SLO-2 Mechatronics design elements	Types and working principle	Relay Construction, working principle, Types and applications.	Introduction to Micro controller	Conveyor based material handling system
S-3	SLO-1 Measurement system	Capacitive sensors	DC motor: Construction and principle of operation	Architecture of M68HC11 microcontroller	Computer controlled CNC drilling machine
	SLO-2 Actuation system	Types and working principle	AC motor: construction and principle of operation	Architecture of ATMEGA328 microcontroller	Computer controlled CNC drilling machine
S-4	SLO-1 Control system	Inductive transducers	Stepper motors: Construction and principle of operation	Signal processing, Multiplexer and Demultiplexer	Electronic car engine management system
	SLO-2 Control system	Types and working principle	Types of stepper motor	Data acquisition system	Solenoid operated fuel injector: construction and operation
S-5	SLO-1 Introduction to microprocessor based controllers	Temperature sensors	Servo motors: Construction, principle of operation	Types: A/D converters	Electronic control of steering system
	SLO-2 Intelligent control	Types and working principle	Types of servo motor	Types: D/A converters	Autonomous guided vehicle (AGV)
S-6	SLO-1 System integration	Pressure sensors	Construction and operation of Synchronous motor	Basic structure, Programming units and Memory of Programmable logic controller	Automatic vehicle transmission system

	SLO-2	Integrated design issues in mechatronics	Types and working principle	Construction and operation of BLDC motor	Input and Output Modules, Mnemonics for programming	Wind screen wiper using stepper motor control
S-7	SLO-1	Hardware in loop simulation	Nano sensor Parameters and characteristics. Necessity of Nano scale measurements	Construction and operation of PMDC motor	Timers	Pneumatic controlled three axis Pick and place robot
	SLO-2	Shaft speed control	Magneto resistance Nano sensor, Hall effect Nano sensor	Pressure control valve	Counters and Shift Registers	Obstacle avoidance robot
S-8	SLO-1	Water level controller	NEMS accelerometer	Rotary actuators and cylinders	Latching and Internal relays	Self-balancing robot
	SLO-2	Open loop and closed loop temperature control system	Silicon nanowire accelerometer	Hydraulic and pneumatic systems with example	Master relay and Jump Controls	Actuation of robotic gripper using SMA wire
S-9	SLO-1	Washing machine control	Optical displacement Nano sensor, Magneto motive displacement Nano sensor	Mechanical actuation system :Types of motion	Programming the PLC using Ladder diagram for Simple applications	Nano mechanical cantilever based manipulation for sensing and imaging.
	SLO-2	Digital camera control	Piezoresistive and Piezoelectric displacement Nano sensor	Kinematic chains, Cams actuation with example, Gear trains with example	Programming the PLC using Ladder diagram for Simple applications	Swarm of self-organized nano Robots.

Learning Resources	<ol style="list-style-type: none"> 1. Bolton, W., "Mechatronics", Addison Wesley, 2nd edition, New Delhi, 1999. 2. Vinod Kumar Khanna., "Nanosensors: Physical, Chemical and Biological", CRC press, 2012 3. Gabor L. Hornyak., John J. Moore., H.F. Tibbals, Joydeep Dutta., "Fundamentals of Nanotechnology", CRC Press, 2009. 4. Constantinos Mavroidis, Antoine Ferreira., "Nanorobotics: Current Approaches and Techniques", Springer 2013. 5. Bradley.D.A, Dawson.D.BurdN.C.and Loader A.J., "Mechatronics", Chapman and Hall Publications, New York, 1993. 6. Rohner.P., "Automation with Programmable Logic Controllers", Macmillan / McGraw Hill, New York, 1996. 7. Jacob Fraden, "Handbook of Modern Sensors Physics, Designs, and Applications", Third Edition, Springer-Verlag New York, 2004.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. C. Purushothaman, ABB India Ltd, Chennai, purushothaman.c@in.abb.com	1. Dr.G.Sakthivel, VIT University, Chennai, sakthivel.g@vit.ac.in.	1. Mr.R.Gangadevi, SRMIST
2. Mr.J. Srinivasan, KONE Elevator India Private Limited, Chennai, srinikone@gmail.com	2. Dr.R.AmuthaKannan, National University, Muscat, amuthakkannan@nu.edu.om.	2. Mr.A. JosinHippolitus, SRMIST

Course Code	18MHE402T	Course Name	FUNDAMENTALS OF ROBOTICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechatronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Introduce the various architecture of industrial robot				Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Introduce the vector transformation applied to robotics																							
CLR-3 :	Introduce the forward and inverse kinematics applied to serial manipulator robot																							
CLR-4 :	Emphasize on the various actuators and transmission element used in robot. Also to define various control strategy used in manipulator robotics																							
CLR-5 :	Introduce the formulation of various trajectories																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1 :	Understand the architecture and basic technical terms used in robotics				2	80	70	H	M	M	H	M	-	-	-	-	-	-	-	-	H	H	-	-
CLO-2 :	Learn the application of vector transformation in robotics				2	80	70	H	H	M	H	M	-	-	-	-	-	-	-	-	H	H	-	-
CLO-3 :	Learn to compute the forward and inverse kinematics model for various configuration of serial manipulator				2	80	70	H	H	M	H	M	-	-	-	-	H	-	-	-	H	H	-	-
CLO-4 :	Understand the various actuators and transmission elements used in robot. Also will learn the various control and trajectory planning algorithm				2	80	70	H	H	H	H	M	-	-	-	-	M	-	-	-	H	H	-	-
CLO-5 :	Understand the trajectory planning techniques and various industrial workcell				2	80	70	H	H	M	H	M	-	-	-	-	M	-	-	-	H	H	-	-

Introduction to Robotics		Transformations		Manipulator Kinematics		Introduction to sensors and actuators in robotics		Trajectory planning and work cell	
Duration (hour)		7		12		8		9	
S-1	SLO-1	Definition of Robot, Laws of Robotics, Basic terminologies used in robotics		Description of point in space		Introduction to Manipulator Kinematics		Basic actuators and transmission elements	
	SLO-2	Description of body in space		Forward Kinematics		Mathematical model of DC motor		Approach and importance of trajectory planning	
S-2	SLO-1	Classification based on application		Review of Vectors		Forward Kinematics of RR planar manipulator- geometric approach		Harmonic Drives	
	SLO-2	Classification based on work volume		Vector representation of points and bodies		Numerical		Computation of reduction ratio of harmonic drive and its advantage	
S-3	SLO-1	Definition – precision, repeatability and accuracy		Translation- Numerical		DH formulation		Force sensor and its uses	
	SLO-2	Co-ordinate systems used in robotics, Degree of freedom with examples		Rotation-Numerical		Difference between modified and standard DH convention with example of RR planar manipulator		Maltese cross configuration	
S-4	SLO-1	Links and various joints in robotics		Representing Rotation- Rotation Matrix		Forward kinematics of 3R spatial articulated arm		Importance of force control using force sensor	
	SLO-2	Anatomy of Robot		Properties of Rotation matrix		Derivation of final DH matrix for 3R spatial articulated arm		Case study – Application of force sensor	
S-5	SLO-1	RPY wrist		Numerical on rotation matrix		Forward kinematics of RPY wrist		Tactile sensor	
	SLO-2	Configuration space and operational space		Numerical on rotation matrix		Derivation of final DH matrix for RPY wrist		Various Tactile sensors- principle and working	
S-6	SLO-1	Robot data sheet interpretation		Representing Rotation- Euler angles		Forward kinematics of 4 DOF SCARA robot		Slip Sensor	
	SLO-2	Important terms and finding in datasheet of manufacturer		Numerical		Derivation of final DH matrix for 4 DOF SCARA robot		Slip Sensor	

S-7	SLO-1	Robot End effector	Representing Rotation- Equivalent axis representation	Introduction to Inverse kinematics	Application of tactile and slip sensor	Safety monitoring
	SLO-2	Types of gripper	Numerical	Inverse Kinematics of RR planar manipulator- Geometric approach	Case Study	Error detection and recovery
S-8	SLO-1		Difference between Current axis and fixed axis representation	Issues in Inverse Kinematics	Vision system for robot	Robot Cycle time analysis
	SLO-2		Numerical	Issues in Inverse Kinematics	Vision architecture block diagram	Economic analysis of robot
S-9	SLO-1		Homogenous Transformation		Case study on Vision based control	Criteria for selection of robot work cell
	SLO-2		Numerical		Case study on Vision based control	Case Study- Selection of robot based on application
S-10	SLO-1		Operators and Mapping Concept			
	SLO-2		Case Study- Numerical			
S-11	SLO-1		Compound Transformation			
	SLO-2		Case Study			
S-12	SLO-1		Case study of transformations in robotics			
	SLO-2		Case study of transformations in robotics			

Learning Resources	1. Mikell P. Groover, "Industrial Robotics", McGraw Hill, 2nd edition, 2012.	4. ArthorCrichtlow, "Introduction to Robotics", Macmillan, 2009.
	2. John J. Craig, "Introduction to Robotics", Addison Wesley, ISE 2008.	5. Mohsen Shahinpoor, "A Robot Engineering Text Book", Harper and Row, 2004
	3. Deb S.R., "Robotics Technology and Flexible Automation", Tata McGraw - Hill Publishing Company Limited, 2012...	6. Mittal R.K., and Nagrath I.J., "Robotics and Control", 1st edition, Tata McGraw Hill, 2007.

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
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2. Mr. Mohammed Sagheer ,Wabco Technology Center ,India, mohammedsagheer.musthafa@wabco-auto.com		2. Dr., P Karthikeyan, MIT,Anna University, pkarthikeyan@annauniv.edu
		Internal Experts
		1. Dr. G. Murali, SRMIST
		2. Ranjith Pillai R, SRMIST

Course Code	18MHE403T	Course Name	INDUSTRIAL INSTRUMENTATION AND CONTROL	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechatronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Gain the knowledge of industrial automation	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Identify the need for process control		
CLR-3 :	Build the various concepts of PID tuning		
CLR-4 :	Utilize the control algorithm for actuators		
CLR-5 :	Gain knowledge of programmable logic controllers		
CLR-6 :	Introduce the knowledge of distributed control systems		

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Knowledge of industrial automation	2	75	70	H	H	M	H	M	-	-	-	-	-	-	H	H	H	H
CLO-2 :	Knowledge of process control	3	75	70	H	H	M	H	M	-	-	-	-	-	-	H	M	M	M
CLO-3 :	Design of PID based control tuning methods	3	75	70	H	H	M	H	M	-	-	-	-	-	-	H	M	M	M
CLO-4 :	Application of control algorithm for actuators	3	75	70	H	H	M	H	M	-	-	-	-	-	-	H	M	M	M
CLO-5 :	knowledge of programmable logic controllers	3	75	70	H	H	M	H	M	-	-	-	-	-	-	H	M	M	M
CLO-6 :	Interpret the knowledge of distributed control systems	3	75	70	H	H	M	H	H	-	-	-	-	-	-	H	H	H	H

Duration (hour)	Industrial Automation	Process Control	Controlling of Actuators	Programmable Logic Controllers	Distributed Control Systems
9	9	9	9	9	9
S-1	SLO-1 Evolution of instrumentation and control.	Introduction of Process control	Need of Machine tools control	Introduction of sequence Control	Introduction to Distributed Control Systems
	SLO-2 Need of instrumentation and control.	Need of Process control	Need of Machine tools control	Need of sequence Control	Need of Distributed Control Systems
S-2	SLO-1 Need of automation in industry	Basics of P I D control	Need of CNC Machines	Need of Programmable Logic Controllers	Concept of Distributed Control Systems
	SLO-2 Role of automation in industry	Implementation of PID controllers	Components of CNC Machines	Need of Programmable Logic Controllers	Components of Distributed Control Systems
S-3	SLO-1 Components of industrial automation systems	Need for controller tuning	Analysis of a control loop	Concepts of Relay Ladder Logic	Functions of DCS
	SLO-2 Architecture of industrial automation systems	Steps in controller tuning	Analysis of a control loop	Need of Relay Ladder Logic	Advantages and limitations of DCS
S-4	SLO-1 Need for sensors	Need of digital controllers	Adjustable field drives	Scan cycle	DCS as an automation tool
	SLO-2 Need for measurement systems	Significance of digital controllers	DC motor drive	RLL Syntax	Enterprise Resource Planning by DCS
S-5	SLO-1 Pressure measurement	Principles of predictive control	Need of variable frequency control	Analog control using PLC	Schematic block diagram of DCS
	SLO-2 Force measurement	Principles of predictive control	Variable frequency control of induction motor drive	Analog control using PLC	Schematic block diagram of DCS
S-6	SLO-1 Need of temperature measurement	Control of systems with inverse response	Need of closed loop control	Advanced RLL programming	Need of data acquisition
	SLO-2 Thermocouple and Thermistor	Control of systems with inverse response	Closed loop synchronous motor drive	Advanced RLL programming	Concepts of data acquisition
S-7	SLO-1 Displacement measurement	Special control structures	Need of proportional valve in fluid power systems	PLC interfacing to SCADA/DCS using Communications links	Specifications involved in DCS
	SLO-2 Speed measurement	Concepts of cascade control	Implementation of proportional valve in fluid power systems	PLC interfacing to SCADA/DCS using Communications links	Specifications involved in DCS
S-8	SLO-1 Measurement of level	Introduction of automation tools	Need of proportional valve in fluid power systems	Need for industrial Ethernet	Latest trends in DCS

	SLO-2	Measurement of humidity and pH	PLC and DCS	Implementation of proportional valve in fluid power systems	Implementation of industrial Ethernet	Latest developments in DCS
S-9	SLO-1	Need for Signal Conditioning	SCADA	PID based pneumatic controllers for positioning	Advanced applications of PLC	SCADA specifications for different real time applications
	SLO-2	Need for Signal processing	Hybrid DCS/PLC	PID based pneumatic controllers for positioning	Advanced applications of PLC	SCADA specifications for different real time applications

Learning Resources	1. William .C. Dunn., "Fundamentals of industrial instrumentation and process control", McGraw-Hill Publications, 2005.	4. Groover. M.P., "Automation, production systems and computer integrated manufacturing", 3rd edition, Prentice Hall of India, 2007.
	2. Patranabis. D., "Principles of industrial instrumentation", Tata McGraw-Hill, 3rd edition, 2010.	5. Stuart A Boyer., "SCADA supervisory control and data acquisition", International society of automation (ISA) Publications, 4th edition, 2010.
	3. Bolton. W., "Programmable logic controllers", Newnes Publications, 4th edition, 2006.	

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Understand	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Apply	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 3	Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. K.P.Srinivasan, Visteon Automotive Electronics Limited, Chennai, psriniv1@visteon.com	1. Dr. B. Mohan, Anna University, Chennai, mohan@mitindia.edu	1. Dr. T. Muthuramalingam, SRMIST
2. Mr. S. EllanChezhian, Keyence Microscope Limited, Chennai, ellanchezhian@gmail.com	2. Dr. D. Saravanakumar, Vellore Institute of Technology, Chennai, saravanakumar.d@vit.ac.in.	2. Dr. M. Mohamed Rabik, SRMIST

Course Code	18MHE404T	Course Name	INDUSTRIAL AUTOMATION	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechatronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																	
CLR-1 :	Identify potential areas for automation and justify need for automation.	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15			
CLR-2 :	Select suitable major control components required to automate a process.																								
CLR-3 :	Translate and simulate a real time activity using modern tools																								
CLR-4 :	Discuss the benefits of automation.																								
CLR-5 :	Identify the suitable automation hardware for the given application.																								
CLR-6 :	Model and simulate tool for the given manufacturing operation.																								
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																							
CLO-1 :	Identify potential areas for automation and justify need of it.	2	75	70	H	M	M	H	M	L	M	L	M	M	-	H	H	H	H	H	H	H	H		
CLO-2 :	Analyze suitable major control components required to automate a process.	3	75	70	H	M	M	H	M	L	M	-	M	M	L	H	H	H	H	H	H	H	H		
CLO-3 :	Able to Translate and simulate a real time activity using modern tools	3	75	70	H	M	M	M	L	L	M	L	M	M	L	H	-	-	-	-	-	-	-		
CLO-4 :	Analyze discuss the benefits of automation.	3	75	70	H	M	M	-	L	L	M	L	-	M	L	H	H	H	H	H	H	H	H		
CLO-5 :	Analyze suitable automation hardware for the given application.	3	75	70	H	M	M	H	L	-	M	L	M	M	L	H	-	-	-	-	-	-	-		
CLO-6 :	Apply Model and simulate tool for the given manufacturing operation.	3	75	70	H	M	-	H	M	L	M	L	M	M	L	H	H	H	H	H	H	H	H		

Duration (hour)	Automation in production system	Automated manufacturing systems	Industrial control systems.	Computer based industrial control	Modeling and simulation for plant automation:
	9	9	9	9	9
S-1	SLO-1 Automation in production system, principles and strategies of automation,	Automated manufacturing systems: Components, classification and	Industrial control systems. Process industries	Computer based industrial control Need for the system	Modeling and simulation for plant automation: Introduction and process.
S-2	SLO-1 Basic elements of an automated system.	overview of manufacturing systems,	Discrete manufacturing industries.	Automatic process control.	Need for system modeling.
	SLO-2 Functions of automation	Manufacturing cells.	Process industries versus discrete manufacturing industries.	Building blocks of automation systems:	Building model of a plant.
S-3	SLO-1 levels of automations	Group technology	Control systems	LAN	Cement plant
	SLO-2 Advanced automation	Cellular manufacturing.	Basic elements of control system	Interface.	Thermal plant
S-4	SLO-1 flow lines	Flexible manufacturing system	Continuous control	Computer Networks	water treatment plant
	SLO-2 transfer mechanisms	planning for FMS	Discrete control.	Topology.	Steel plant
S-5	SLO-1 fundamentals of transfer lines	Implementation of FMS	Continuous versus discrete control.	Analog I/O Modules,	Modern tools
	SLO-2 Material handling systems: Introduction	Quality control systems,	Regulatory control	Digital I/O Modules,	Future perspective.
S-6	SLO-1 principles and design considerations	traditional and modern quality control methods	Feed forward control.	SCADA systems	Industrial control applications: Cement plant
	SLO-2 Material transport systems – out bound	SPC tools.	Automated control	Real-time user interface.	Design and implementation
S-7	SLO-1 Introduction, conveyors.	inspection principles	Adaptive control	Distributed control system,	thermal plant
	SLO-2 Industrial robots	practices	Definition, Types	Functional requirements.	Design and implementation
S-8	SLO-1 Automated guided vehicles.	Inspection technologies.	Comparisons	Elements of DCS	Industrial control applications: Water treatment plant
	SLO-2 Storage systems:	overview of automatic identification methods	online strategies	Configurations of DCS.	Design and implementation
S-9	SLO-1 Automatic storage and retrieval systems.	Barcode readers	Computer process	Popular distributed control systems.	Industrial control applications: steel plant
	SLO-2 Realtime Application	Machine vision systems.	Forms of computer process	Realtime Application	Design and implementation

Learning Resources	1. P.Groover, "Automation, Production Systems and Computer Integrated Manufacturing", Pearson Education, 5 th edition, 2009. 2. Krishna Kant, "Computer Based Process Control", Prentice Hall of India, 2 nd edition, 2010. 3. Tiess Chiu Chang and Richard A. Wysk, "An Introduction to Automated Process Planning Systems", Prentice Hall of India, 1985. 4. Viswanandham, "Performance Modeling of Automated Manufacturing Systems", Prentice Hall of India, 1 st edition, 2009. 5. S.K.Singh, "Computer Aided Process Control", Prentice Hall of India, 1 st edition, 2004.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. A. Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	Dr.R.Sivaramakrishnan, MIT, Anna University, Chennai	1. Dr. B K Vinayagam, SRMIST
2. Mr. ElayarajSivaraj, Tesla, California, elayaraj@hotmail.com	Dr. R.ArockiaRajan, IIT-Madras, Chennai	2. Mr. S.Vigneshwaran, SRMIST

Course Code	18MHE405T	Course Name	MANUFACTURING INFORMATION SYSTEMS			Course Category	P	Professional Elective			L	T	P	C
											3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechatronics Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand the Concepts of information				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Identify the information generated in manufacturing industry				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Understandthe concepts of database systems in manufacturing industry							H	L	-	M	-	-	-	-	L	-	-	-	-	L	L
CLR-4 :	Understand the database design and architecture							H	H	-	M	-	-	-	-	L	-	-	-	-	L	L
CLR-5 :	Comprehend the computerized manufacturing information systems							H	M	-	H	-	-	-	-	L	-	-	-	-	L	L
CLR-6 :	Understand computerized production planning and scheduling systems							H	H	-	H	-	-	-	-	L	-	-	-	-	L	L
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Identify the various concepts of information with respect to products and processes in manufacturing industry				2	90	85	H	L	-	M	-	-	-	-	L	-	-	-	-	L	L
CLO-2 :	Identify the orderly arrangement of information flow in the manufacturing processes				2	90	85	H	H	-	M	-	-	-	-	L	-	-	-	-	L	L
CLO-3 :	Compare the different types of database systems and utilize the most appropriate one for a given manufacturing industry				2	90	85	H	M	-	H	-	-	-	-	L	-	-	-	-	L	L
CLO-4 :	Identify the suitable database design and architecture for a given manufacturing industry				2	90	85	H	M	-	H	-	-	-	-	L	-	-	-	-	L	L
CLO-5 :	Select the rational computerized manufacturing system for the products				2	90	85	H	H	-	H	-	-	-	-	L	-	-	-	-	L	L
CLO-6 :	Chose the rational computer based production management system for production data control, customer order servicing and plant control				2	90	85	H	H	-	H	-	-	-	-	L	-	-	-	-	L	L

Duration (hour)		INTRODUCTION	DATA PROCESSING	DATA HANDLING	DATA FORM	NEED OF COMPUTER IN MANUFACTURING
		9	9	9	9	9
S-1	SLO-1	Need for manufacturing	Introduction to data base system	Introduction to relational database.	Basic QBE and multiple relations	Parts oriented production information system concept
	SLO-2	Need for manufacturing	Need for database system	Introduction to relational database.	Basic QBE and multiple relations	Parts oriented production information system concept
S-2	SLO-1	Macroscopic view of manufacturing organization	Need for database system	Integrity constraints over relations	Aggregates, condition box, data base design: Schema refinement	Parts oriented production information system structure
	SLO-2	Macroscopic view of manufacturing organization	Benefits of database approach	Integrity constraints over relations	Aggregates, condition box, data base design: Schema refinement	Parts oriented production information system structure
S-3	SLO-1	Principal properties of manufacturing information: MRP I	Data and data models	Enforcing integrity constraint	Functional dependencies and reasoning	Computerized production scheduling
	SLO-2	Principal properties of manufacturing information: MRP II	Data and data models	Enforcing integrity constraint	Functional dependencies and reasoning	Computerized production scheduling
S-4	SLO-1	Principal properties of manufacturing information: SFC	Entity and relationship diagram	Querying relational data	Trivial and non-trivial dependencies.	Online production control system
	SLO-2	Principal properties of manufacturing information: MPS	Diagram, database design with E/R model	Logical database design.	Trivial and non-trivial dependencies.	Online production control system
S-5	SLO-1	Information principles of manufacturing	Data independence and stored fields	Translating ER model to relational model.	Closure of a set of dependencies and attributes.	Computer based production management system: Engineering and production data control
	SLO-2	Information principles of manufacturing	Records and files.	Translating ER model to relational model	Closure of a set of dependencies and attributes.	Computer based production management system: Engineering and production data control
S-6	SLO-1	Measurement of manufacturing information	Three levels of architecture: External	Relational algebra and queries	Normal forms and normalization: First form	Computer based production management system: Customer order servicing

	SLO-2	Information physics, Communication approach	Three levels of architecture: Internal and conceptual.	Syntax and semantics	Normal forms and normalization: Second form	Computer based production management system: Customer order servicing
S-7	SLO-1	Synthesis of manufacturing information	Mappings	Form of basic SQL query	Normal forms and normalization: Third form	Computer based production management system: Forecasting
	SLO-2	Information intensity and value matrices	DBMS functions and components	Form of basic SQL query	Normal forms and normalization: Third normal form	Computer based production management system: Plant maintenance and control
S-8	SLO-1	Dual nature of manufacturing information	Data Communication	Union, intersect and except	Multi valued dependency and fourth normal form	Computerized manufacturing information system, case study
	SLO-2	Performance maximization rules	Data Communication	Nested queries	Multi valued dependency and fourth normal form	Computerized manufacturing information system, case study
S-9	SLO-1	Materialization of manufacturing information	Distributed processing	Aggregate queries and null values	Join dependencies and fifth normal form	Computerized manufacturing information system, case study
	SLO-2	Materialization of manufacturing information	Distributed processing	Triggers and active databases	Join dependencies and fifth normal form	Computerized manufacturing information system, case study

Learning Resources	<ol style="list-style-type: none"> 1. Date.C.J., "An Introduction to Database Systems", Addison Wesley, 8th edition 2003. 2. Raghu Ramakrishnan and Johannes Gehrke, "Data Base Management Systems", McGraw- Hill Higher Education, 3rd edition 2002. 3. Luca G.Sartori, "Manufacturing Information Systems", Addison-Wesley Publishing Company, 1988. Reference Books/Other Reading Materials 	<ol style="list-style-type: none"> 4. FranjoCeceljia, "Manufacturing Information and Data systems – Analysis, Design and Practice", ISBN: 978-1-85718-031-2, Elsevier, 2002. 5. John A. Schey, Introduction to manufacturing processes, 3rd ed., McGraw-Hill, 2000 6. Zude Zhou, Shane (Shengquan) XieDejun Chen, "Fundamentals of Digital Manufacturing Science", ISBN 978-0-85729-563-7, Springer-Verlag London Limited, 2012.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. A. Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	Dr.R.Sivaramakrishnan, MIT, Anna University, Chennai	1. Dr. B K Vinayagam, SRMIST
2. Mr. ElayarajSivaraj, Tesla, California, elayaraj@hotmail.com	Dr. R.ArockiaRajan, IIT-Madras, Chennai	2. Mr. J.Arivarasan, SRMIST

Course Code	18MHE406T	Course Name	INDUSTRIAL ELECTRONICS				Course Category	E	Professional Elective										L	T	P	C			
																				3	0	0	3		
Pre-requisite Courses		18MHC103T, 18MHC204T		Co-requisite Courses		NIL		Progressive Courses		NIL															
Course Offering Department		Mechatronics Engineering				Data Book / Codes/Standards				NIL															
Course Learning Rationale (CLR):		The purpose of learning this course is to:						Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Identify different Regulators and utilize them in different Regulated Power supply circuits						1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLR-2 :	Recognizes the concept of heating and welding.						Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3	
CLR-3 :	Identify working principle of different speed control methods for DC and AC motor.																								
CLR-4 :	Apply Power semiconductor switching devices concept in industrial applications.																								
CLR-5 :	Identify the principle of chopper to drive servo motors																								
CLR-6 :	Gain knowledge on regulators for regulated power supplies, Power Semiconductor devices for industrial applications, operate DC and AC drives using converters.																								
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																							
CLO-1 :	Analyze various regulators used in Power supplies						3	75	70	H	L	M	H	M	-	L	L	M	M	-	H	-	PSO - 1	PSO - 2	PSO - 3
CLO-2 :	Interpret the working principle of heating and welding in order to apply the advanced controls to improve their knowledge in understanding the concept of heating and welding.						3	75	70	H	M	M	H	H	-	M	L	H	M	-	H	-	-	-	
CLO-3 :	Explore themselves familiar with functions of several industrial motor controls.						3	75	70	H	L	M	H	M	-	L	L	M	M	-	H	-	-	-	
CLO-4 :	Operate various industrial appliances using Power semiconductor switching devices						3	75	70	H	-	L	H	M	-	H	L	M	M	-	H	-	-	-	
CLO-5 :	Operate UPS and servo motors using Choppers						3	75	70	H	-	L	H	M	-	M	L	M	M	-	H	-	-	-	
CLO-6 :	Identify power semiconductor devices, regulators, choppers, heating and welding, speed control methods for operating electric drives.						3	75	70	H	L	M	H	M	-	L	L	M	M	-	H	-	-	-	
		Introduction to Regulators and Power Supplies		Heating and Welding Control		Industrial Motor Control		Industrial Application of Power Switching Devices		AC Power Conditioner															
Duration (hour)		9		9		9		9		9															
S-1	SLO-1	Concept of regulation, block diagram of a regulated power supply		Electronic control of heating: Introduction, Types		Method of controlling speed of DC motor		Principle of operation of automatic battery charger using SCR		Power supply noise															
	SLO-2	Significance of regulated power supply.		Electronic control of heating: Resistance heating principle, Induction heating		Basic control circuit: DC motor control		Working of automatic battery charger using SCR		Different forms of noise.															
S-2	SLO-1	Performance parameters: Major specifications of a regulated power supply, line and load regulation, output ripple and transients.		Induction heating: Principle of operation		Speed control of DC motors: Types		Principle of operation of emergency light using SCR.		Servo system: Fundamentals of Servo motor															
	SLO-2	Concepts of fold back limiting, short circuit and overload protection.		Electronic control of heating: effects of supply frequency and source voltage, choice of frequency.		Speed control of small DC motors-operating principle		Working of emergency light using SCR.		Servo system: Principle of Servo motor															
S-3	SLO-1	Principle of series regulators		Electronic control of heating: advantages and applications		Solid state motor control: Speed control of DC shunt motor using thyristor technology.		Principle of operation of Time delay relay circuit		Principle of buck-boost control of a servo controlled voltage stabilizer															
	SLO-2	Types of Series regulators		High frequency induction heating: Fundamentals, Operation		Speed control of DC shunt motor using thyristor technology.		Working of Time delay relay circuit		Working of buck-boost control of a servo controlled voltage stabilizer															
S-4	SLO-1	Principles of shunt regulators: Types		High frequency induction heating: Types		PLL control of a DC motor control		Automatic temperature control circuit.		Servo-controlled voltage stabilizer, Constructional features															
	SLO-2	Types of shunt regulators		Electronic heaters employed for induction heating.		Over-voltage and Over load protection of DC motors.		Automatic temperature control circuit: types.		Servo-controlled voltage stabilizer: Principle of operation															
S-5	SLO-1	Three terminal voltage regulator ICs: Positive, negative and variable applications.		Operation of Electronic heaters employed for induction heating.		AC motor control: Methods		Battery operated inverter circuit using power transistor		Ferro-resonant AC regulator- Synchro: Constructional features															
	SLO-2	Three terminal voltage regulator ICs: negative and variable applications.		Thyristorised supplies used in induction furnaces		Speed control of three phase induction motor		Illumination control using SCR		Ferro-resonant AC regulator- Synchro: Principle of operation															

S-6	SLO-1	Switched Mode Power Supply: Basic working principles	Dielectric heating: Working principle	Speed control of single phase induction motor.	Illumination control using DIAC.	UPS- Introduction, Types
	SLO-2	Switched Mode Power Supply: applications, advantages and disadvantages.	Dielectric heating: Advantages and disadvantages, Applications	Speed control of single phase induction motor.	Illumination control using TRIAC.	UPS - Principle of operation Online UPS
S-7	SLO-1	Concept of floating and grounded power supplies	Electronic control of welding, electric welding	TRIAC as a starter for single phase induction motors and universal series motor.	Electronic timers: Introduction	UPS - Principle of operation Offline UPS
	SLO-2	Concept of floating and grounded power supplies: interconnections to obtain multiple output supplies.	Classification of resistance welding.	Operation of TRIAC as a starter for single phase induction motors and universal series motor.	Advantages of Electronic timers	Advantages and Applications of UPS, Comparison of different types of UPS
S-8	SLO-1	Switch Mode Power Supply: Fly back converter.	Control circuit for resistance welding	Applications of AC line voltage controllers circuit.	Electronic timers: Sequential timer.	Principle of operation of choppers: Types
	SLO-2	Switch Mode Power Supply: forward/buck converter	Operation of Control circuit for resistance welding	Zero voltage switching circuit.	Digital timer	Principle of operation of step up chopper.
S-9	SLO-1	Switch Mode Power Supply: Boost converter and buck-boost converter	AC resistance heating.	Synchronous tap changer circuit.	Electronic time delay circuits.	Principle of operation of step down chopper.
	SLO-2	Switch Mode Power Supply: cuk converter.	Operation and circuit of AC resistance heating	AC power control of a lamp dimmer circuit.	Electronic time delay circuits: Advantages, Applications.	Principle of operation of reversible chopper.

Learning Resources	1. S. Bhattacharya, S. Chatterjee, "Industrial Electronics And Control", Tata McGraw Hill, 2006.	4. Chitode .J.S, "Industrial Electronics", Technical Publications, 2009.
	2. Dubey, G.K., Doradia. S.R., Joshi.A. and Singh.R.M., "Thyristorised Power Controllers", Wiley Eastern Limited, 2008.	5. G. K. Mithal, "Industrial and Power Electronics", Khanna Publishers, Delhi, 2000.
	3. Biswanath Paul, "Industrial Electronics and Control", Prentice Hall India publisher , 2004.	6. M. H. Rashid, "Power Electronics Circuits, Devices and Application", Prentice Hall of India, 3 rd edition, 2004.
		7. Terry Balleit, "Industrial electronics, devices, systems and applications", Delmar publishers, 2006.
		8. Stephan L. Herman, Walter N. Alerich, "Industrial Motor Control", 4 th edition, Delmar publishers, 2010.

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. S. Ananda Kumar, Deputy Chief Engineer, Control & Instrumentation, NLC India Ltd., sith.anandkumar@gmail.com	1. Dr. M. Jagadeesh Kumar, Sri Sai Ram Institute of Technology, jagadeeshkumar.eee@sairamit.edu.in	1. Dr. M. Santhosh Rani, SRMIST
2. Mrs. T. Priya, Sr. Design Engineer, Electrical & Instrumentation, Kavin Engg and Services Pvt. Ltd., priya@kavinengg.com	2. Dr. S. S. Dash, Government College of Engineering Keshavnagar, Odisha, munu_dash_2k@yahoo.com	2. Mrs. V. Krithika, SRMIST

Course Code	18MHE407T	Course Name	GEOMETRIC MODELLING	Course Category	C	Professional Core	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechatronics Engineering		Data Book / Codes/Standards	Nil	

Course Learning Rationale (CLR):		The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1:		Gain the knowledge in fundamentals of Graphics and transformations.	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:		Impart the Knowledge in modeling of CAD system.	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3:		Learn the various algorithm used in geometric modelling																		
CLR-4:		Understand the mathematical concept of Model assembly for a machine elements																		
CLR-5:		Distinguish data exchange standards and common file types in CAD																		
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																		
CLO-1:		Gain knowledge in fundamentals of Graphics and transformations.	1	85	80	H	H	-	H	-	-									
CLO-2:		Impart Knowledge in modelling of CAD system.	1	85	80	H	H	H	-	H	-									
CLO-3:		Learn the various algorithm used in geometric modelling	1	85	80	H	H	H	H	H										
CLO-4:		Understand the mathematical concept of Model assembly for a machine elements	2	85	80	H	H	H	H	H										
CLO-5:		Distinguish data exchange standards and common file types in CAD	2	85	80	H			H											

Duration (hour)		Fundamentals of Computer Graphics	Geometric Modelling	Visual Realism	Assembly and Tolerance	Graphics Standards
		10	10	08	09	08
S-1	SLO-1	Design as a process, sequential and concurrent engineering.	Introduction to geometric modelling	Hidden line removal: Visibility of object views	Assembly modelling: Introduction, Part modelling.	Computer graphics: Introduction
	SLO-2	Computer Aided Design (CAD) and its architecture.	Wire frame modelling: Introduction	Visibility of object techniques	Assembly modeling: Representation Hierarchical relationship & Mating Condition.	Computer graphics: software and Database CAD Graphics
S-2	SLO-1	Computer graphics, co-ordinate system	Model, entities of wire frame modelling.	Visibility of object techniques: Sorting & Coherence	Assembly modeling: Types of Approach	Translator: Types
	SLO-2	Transformation types: Two and three dimensional.	Representation of synthetic curves: Hermite curve	Visibility of object technique: Priority and area orientation	Interferences of positions	Software standards: Graphical Kernel System (GKS)
S-3	SLO-1	Transformation in 2D and 3D: Translational, scaling.	Bezier curve.	Hidden surface removal: Back face, Scan line Algorithm	Tolerance: Introduction, need& concept of conventional.	Exchange Database : IGES
	SLO-2	Problems in translational scaling.	Problems on Bezier Curve	Hidden surface removal: Z-buffer Algorithm	Fits and Limits: MMC , LMC	Exchange Database :STEP
S-4	SLO-1	Transformation in 2D and 3D: Rotation, reflection	B-spline curves	Warnock's algorithm	Tolerance: Modelling Accumulation, Drafting and Manufacturing	Drawing Exchange Format & ACIS
	SLO-2	Problems in Rotation, reflection	Problems on B – Spline curve	Hidden solid removal: Ray-tracing algorithm.	Geometric tolerance: Representation and Types	Graphics Functions: Output Primitives
S-5	SLO-1	Two dimensional transformations: Problems on rotation,	rational curves	Shading: Model, surface	Tolerance analysis: Worst- case arithmetic method	Line attributes: types width , color
	SLO-2	2D Problems on scaling	Surface modelling: Introduction, model.	Shading: Enhancement, solid.	Tolerance analysis: Worst- case statistical method	Curve attributes :Color , table & Grayscale levels
S-6	SLO-1	2D Problems on translation,	Parametric representation of analytic surface.	Shading: solid	Tolerance analysis: Worst- case arithmetic method problems	Area Fill Attributes : Style, pattern, soft
	SLO-2	2D Problems on, reflection.	Plane surface	Coloring: Models	Tolerance analysis: Worst- case statistical method problems	Character Attributes: Text ,Marker

S-7	SLO-1	Three dimensional transformations: Problems on rotation,	ruled surface	Coloring: Types	Monte Carlo simulation method	Processors : Design and Implementation
	SLO-2	3D Problems on scaling,	Parametric representation of synthetic surface: Coons and	Animation: Conventional, Computer & Engineering	Mass property calculations: First and second Moment of inertia	Processors :Error handling , testing and verification,
S-8	SLO-1	3D problems on translation	Parametric representation of Synthetic curve : Bicubic	Animation Types and Techniques	Mass property calculations: second Moment of inertia	Open Graphics Library (OpenGL): Introduction
	SLO-2	3D problems on reflection	Parametric representation of Bezier curve	Morphing: Types and model	Geometrical property: Curve Length, Surface Area	Open Graphics Library (OpenGL) : Types
S-9	SLO-1	Homogeneous co-ordinates.	Parametric representation of B Spline curve		Geometrical property: Volume: & Cross section Area	Communication standards for CAD systems
	SLO-2	Algorithms: Line, circle	Solid modelling: Introduction, models, entities		Properties of composites, mass property calculation by using CAD systems	
S-10	SLO-1	Clipping algorithm.	Solid modelling representation: Boundary representation.			
	SLO-2	Windowing and viewing.	constructive solid geometry.			

Learning Resources	1. Ibrahim Zeid, "Mastering CAD CAM", Tata McGraw-Hill Publishing Co, 2007.	4. William M Neumann and Robert F.Sproul, "Principles of Computer Graphics", McGraw-Hill Book Co.Singapore, 1989.
	2. Chris McMahon and Jimmie Browne, "CAD/CAM Principles", Practice and Manufacturing Management 2nd edition, Pearson Education, 1999.	5. Donald Hearn and M. Pauline Baker, "Computer Graphics", Prentice Hall, Inc, 1992. 6. Foley, Wan Dam, Feiner and Hughes, "Computer Graphics Principles and Practice", Pearson Education, 2003.

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%) #			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mrs.A.Priya ,Principal Engg, TechnipFMC, apriya@technipfmc.com, Chennai	1. Dr.S.NeelavathyPari, Asst. Professor (Senior Grade), MIT, neela@annauniv.edu, Chennai.	1. D.Gayathiri, SRMIST
2. Mr. Ak. Lakshminaraimhan, Senior Principal Engineer, Technip FMC AK lakshminaraimhan@technipfmc.com, Chennai	2. Dr. R.sarala, AlagappaChettiar college of Engineering and Technology, r.sarala@accet.edu.in, karaikudi.	2. Mr.J.Arivarasan, SRMIST

Course Code	18MHE408T	Course Name	MICRO ELECTRO MECHANICAL SYSTEMS				Course Category	E	Professional Elective					L	T	P	C								
														3	0	0	3								
Pre-requisite Courses	Nil		Co-requisite Courses	Nil				Progressive Courses	Nil																
Course Offering Department		Mechatronics Engineering			Data Book / Codes/Standards				Nil																
Course Learning Rationale (CLR):		The purpose of learning this course is to:						Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Provide necessary fundamental knowledge in manufacturing and packaging of micro systems						1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLR-2 :	Impart knowledge of behavior of mechanical and electrical elements at micro level						Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3	
CLR-3 :	Emphasis on electrical and Thermal actuation in microsystems																								
CLR-4 :	Emphasis on Piezoelectric and Magnetic actuation in microsystems																								
CLR-5 :	Expose on MEMS applications in Automotive sector and Space exploration																								
CLR-6 :	Introduce computer aided simulation of microsystems																								
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:						1	85	80	H	L	-	L	L	M	L	M	-	-	-	M	-	-	
CLO-1 :	Understand the operation and manufacturing of microsystems						2	85	80	H	H	-	H	L	-		L	M	-	-	-	-	-	-	
CLO-2 :	Analyze the behavior of MEMS systems						2	85	80	H	H	H	H	L	-	H	L	M	-	-	-	-	-	-	
CLO-3 :	Design micro sensors and actuators actuated by electrical and Thermal actuation						2	85	80	H	H	H	H	L	-	H	L	M	-	-	-	-	-	-	
CLO-4 :	Design micro sensors and actuators actuated by Piezoelectric and Magnetic actuation						2	85	80	H	H	H	H	L	-	H	L	M	-	-	-	-	-	-	
CLO-5 :	Gain knowledge on different applications of MEMS devices						2	85	80	H	H	-	L	L	M		L	M	-	-	-	-	-	-	
CLO-6 :	Simulate simple Microsystems						2	85	80	H	H	-	L	H	-		L	M	-	-	-	-	-	-	
		Introduction to MEMS & Microsystem Fabrication Processes		Mechanical and Electrical Conceptions		Sensing and Actuation-I (Electrical and Thermal)		Sensing and Actuation-II (Piezoelectric and Magnetic)				Mems Case studies													
Duration (hour)		9		9		9		9				9													
S-1	SLO-1	Overview of MEMS,		Review of Semiconductor		Electrostatic sensors and actuators		Piezoresistivity gauge factor				MEMS inertial sensor in automobile airbag deployment													
	SLO-2	Elements of MEMS, Applications		Carrier concentration in Silicon semiconductors		Parallel plate capacitors		Piezoresistive materials				MEMS vibratory gyroscope													
S-2	SLO-1	Intrinsic characteristics of MEMS, Multidisciplinary nature of microsystem design and Manufacture		Calculation of Conductivity and resistivity of semiconductor Electron mobility in Silicon		Equilibrium position of parallel plate actuators		Applications of piezoresistive sensor				Optical MEMS													
	SLO-2	Scaling Law of Miniaturization		Sheet resistivity Numerical Problems		Pull-in effect of parallel plate actuators		Inertia sensors, pressure sensors based on piezoresistivity				Digital Micro Mirror Devices													
S-3	SLO-1	Simple problems related to miniaturization		Crystal planes and Orientations, General scalar relationship between stress and strain		Applications of Parallel plate capacitors, Inertia sensor		Tactile sensor				MEMS devices in Biotechnology													
	SLO-2	Materials for MEMS: Silicon, Silicon Compounds and Polymers		Study of Flexural beams bending under simple loading conditions		Pressure sensors		Flow sensor				Scanning Tunnelling Microscope													
S-4	SLO-1	Microsystem Fabrication Processes: Photolithography		Mechanical deformation of cantilever beam spring		Flow sensors		Piezoelectric sensing and actuation				Polymerase Chain reaction													
	SLO-2	Ion Implantation		Deformation of torsional bars		Tactile sensors, Parallel plate actuators		Piezoelectric materials				Microsystems for DNA amplification													
S-5	SLO-1	Diffusion		Discussing the Simple problems related to force constant		Interdigitated Finger capacitors		Piezoelectric Accelerometer				Fluidic MEMS, Micro channels													
	SLO-2	Oxidation		Origin of intrinsic stress, Methods for characterization		Comb drive accelerometer		Acoustic sensors				Polymer MEMS, Liquid crystal Polymer, PDMS, PMMA													

S-6	SLO-1	Chemical Vapor Deposition (CVD)		Thermal Sensing and Actuation	Tactile sensors	MEMS devices in space exploration
	SLO-2	Physical Vapor Deposition (PVD)		Thermal resistance	Flow sensors	Micro power sources, micro turbines
S-7	SLO-1	Surface micromachining	Control and compensation of bending	Thermal bimorph principle	Magnetic actuation	Introduction to NEMS
	SLO-2	LIGA Process	Analysis of essential elements of MEMS system dynamics	Thermal bimorph actuator	Essential concepts and principles	Nano fabrication
S-8	SLO-1	Bulk micromachining; Dry etching, Wet etching	Discussion	Accelerometer based on thermal transfer principle	Deposition of Magnetic materials	Nano devices
	SLO-2	Plasma etching, DRIE	Damping & Quality factor, Resonant Frequency	Thermal accelerometer with no moving mass	Fabrication of Magnetic coil	Nano manipulation
S-9	SLO-1	MEMS process integration strategies		Flow sensors based on thermal transfer principle	Magnetic motors	Computer aided simulation and design of MEMS devices Background to Finite element method
	SLO-2	Microsystem Packaging	Active Tuning of spring constant and resonant frequency	Infrared sensor	Magnetic beam actuation	Exposure to commercial software packages

Learning Resources	<ol style="list-style-type: none"> 1. Tai- Ran Hsu, "MEMS and Microsystem Design and Manufacture" McGraw Hill Education (India) Private Limited, New Delhi, 2002. 2. Chang Liu , " Foundations of MEMS" 2nd edition, Dorling Kindersley India Pvt Ltd, 2012. 3. Rai-Choudhury.P., " MEMS and MOEMS Technology and Applications" Prentice Hall of Indian Indian Learning Private Limited, 2009. 	<ol style="list-style-type: none"> 4. NadimMaluf, " An Introduction to Microelectromechanical Systems Engineering" 2nd Edition, Artech House, 2004. 5. Reza Ghodssi, Pinyen, " MEMS Materials and Processes Handbook", Springer Science Business Media, 2011. 6. Sergey Edward Lyshevski, "MEMS and NEMS: Systems, Devices and Structures" CRC Press, 2002.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Evaluate Create	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry		Experts from Higher Technical Institutions
1. Mr. C. Purushothaman, ABB India Ltd, Chennai; purushothaman.c@in.abb.com		1. Dr.G.Sakthivel, VIT University, Chennai; sakthivel.g@vit.ac.in.
2. Mr.J. Srinivasan, KONE Elevator India Private Limited, Chennai; srinikone@gmail.com		2. Dr.R.AmuthaKannan, National University, Muscat, amuthakannan@nu.edu.om.
		Internal Experts
		1. Dr.G.Murali, SRMIST
		2. Mr.N.Pradeep, SRMIST

Course Code	18MHE409T	Course Name	AUTOMATION AND INTELLIGENT SYSTEMS	Course Category	C	Professional Core	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechatronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	To impart the basics of automation and intelligent systems.	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Explain the fundamentals of automated systems.	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Identify the elements of CIM and its construction.	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Discuss about the knowledge based systems.	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Apply the artificial intelligent and expert systems in manufacturing.	Expected Attainment (%)	Design & Development
CLR-5 :	Develop the Artificial neural network system for manufacturing		Analysis, Design, Research
			Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Understand the basics of automation system and designing of simple automated system	2 75 75	H L H L M H L L M M H L M -
CLO-2 :	Explain the modeling tools of Petri Nets and Quenching model	2 75 80	H L M - H M - - - L L - - L
CLO-3 :	Analysis the Intelligent manufacturing system components and IMS architecture	3 80 85	H - M L H L - M L M M M - - -
CLO-4 :	Prescribe the structure of knowledge based systems and approaches in KBS	2 80 75	H L L M - - - L - L L L - -
CLO-5 :	Learn the organizational platform in Janus system to implement the Holon control for Manufacturing.	3 85 80	H - L M H M L L - L L L - - H
CLO-6 :	Understand the concept of Artificial Intelligence and Neural Network systems in Manufacturing	3 85 80	H L H - L L - - L - - - L

Duration (hour)	Automation Systems	Modelling of Automation Systems	Computer Integrated Manufacturing Systems	Knowledge Based Systems	Machine Learning, Artificial Intelligence and Expert Systems
	09	09	09	09	09
S-1	SLO-1 Introduction: Automation systems	Introduction of Modeling tools-Markov chain models	Introduction of CIMS Systems, CIM Definitions	Introduction of basic Knowledge Based Systems (KBS).	Introduction of Machine Learning
	SLO-2 Basic elements of automation system	Configuration of Markov model, Assumptions, application	Basic four plan Concept, Components, Benefits of CIMS	Basic components of Knowledge Based Systems (KBS).	Objectives of Machine Learning
S-2	SLO-1 Advantages, evolution of automation systems	Introduction of Quenching models, types of Quenching models	Structural and functional areas of CIMS Systems	Designing of Knowledge Based System(KBS)	Concepts of Machine Learning
	SLO-2 applications of automation systems	Various techniques of quenching models and applications	Features of CIM Wheel, CIM Evolution	Advantages and disadvantages of Knowledge Based System(KBS)	Types of Machine Learning and its algorithm with examples
S-3	SLO-1 Automation systems in Services	Introduction of Petri Nets models, classes of PN Models for manufacturing systems,	Introduction of Manufacturing Communication Systems	Application and limitation of Knowledge Based System(KBS)	Uses of Machine Learning
	SLO-2 Packaging and storage services	Basics of Petri Nets ,Examples	Types, layout of Manufacturing Communication Systems, Applications.	Introduction to Knowledge representation structure	Merits and Demerits of Machine Learning
S-4	SLO-1 Office automation systems	Types of Petri Nets models ,Properties of PN models,	Definition of Data redundancy, types , advantages of Data redundancy	Approaches in KBS.	Fundamental of Artificial Intelligence
	SLO-2 Stages of Growth, Basic activities , advantages and disadvantages of office Automation	Basics architecture of PN Models	Basic Definition of top-down and bottom-up approach volume of information,	Introduction to Engineering design for knowledge based reasoning	Concept and objective of Artificial Intelligence
S-5	SLO-1 Types of functions integrated by OAS	Structural properties of Petri Nets models, applications	Objectives, comparison of top- down and bottom up approaches	Engineering design knowledge based reasoning in manufacturing	Architecture of Artificial Intelligence
	SLO-2 Documentation and Communication	Discussion	Important roles of top- down and bottom up approaches	Introduction to Multi- agent manufacturing system	Various types of design pattern in Artificial Intelligence
S-6	SLO-1 Designing of simple automation systems	Various modeling of Petri Nets,	Introduction of intelligent manufacturing system, basic definition	Designing of Multi- agent manufacturing system	Application and advantages of Artificial Intelligence

	SLO-2	Components of simple automated design	Analysis methods of PN models	Basic concept of IMS, Components of IMS..	Advantages and disadvantages of Multi- agent manufacturing system	Conceptual learning Expert Systems
S-7	SLO-1	Interlocking between feed and opening of the door	Differences between simple Petri Nets and high level Petri Nets.	Basic Principles of IMS, IMS overview, tools used for IMS	Application and limitation of Multi-agent manufacturing system	Basics Function of learning Expert Systems
	SLO-2	Various design steps and implementation of simple Automation	Types of simple Petri Nets, functions, examples	IMS architecture, applications of IMS	Introduction to Holonic manufacturing systems	Fundamental of Neural Networks
S-8	SLO-1	Designing of multi level automation systems	Types of high level Petri nets ,	Introduction of IMS data flow, definitions	Designing Holonic manufacturing systems	Types of Neural Networks
	SLO-2	Design steps and process of Multi level automation	Functions of High level Petri Nets , examples	Process modeling of data flow diagram, Identify the object of DFD(Data Flow Diagram)	Control of Holonic manufacturing systems	Application and limitation of Neural Networks in manufacturing
S-9	SLO-1	Monitoring the temperature on the basis of supply of fuels,	Introduction of PRQN – ESP models, types of PRQN – ESP models	Fundamental of IMS Operation,	Advantages and disadvantages of Holonic manufacturing systems	Introduction of Artificial Neural Networks and Fuzzy Logics
	SLO-2	pressure, velocity and calorific value	Integrated PRQN – ESP models	Tutorial	Application and limitation of Holonic manufacturing systems	Introduction and Concepts of Fuzzy set , Biological neuron , Artificial neuron

Learning Resources	1. Mikel P. Groover , "Automation, Production Systems and Computer Integrated Manufacturing", Prentice Hall of India, 2014. Text / Audio / Video 2. T YagnaNarayana, "Artificial Neural Networks", Prentice Hall of India, 2009ext / Audio / Video 3. Andre Kusaic, "Intelligent Manufacturing Systems", Prentice Hall of India, 1989.	4. Hamid R. Parsaei and Mohammad Jamshidi, "Design and Implementation of Intelligent Manufacturing Systems", Prentice Hall of India, 2009. 5. Z. Zhou, Zude, Xie, Shane Shengquam, Chen, Dejun "Fundamentals of Digital Manufacturing Science", Springer Series in Advanced Manufacturing, Springer Verlag London Limited, 2012.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%) #			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mrs..A.Priya ,Principal Engg, Technip FMC,apriya@technipfmc.com	1. Dr. B.Mohan, Professor,CEG,bmohan@annauniv.edu, Chennai	1. Ms.D.Gayathiri, SRMIST
2.2.Mr. Ak. Lakshminaraimhan, Senior Principal Engineer,Technip FMCAK Lakshminaraimhan@technipfmc.com	2. Dr. Dr.S.NeelavathyPari, Asst. Professor (Senior Grade), MIT,neela@annauniv.edu, Chennai.	2. Mr. K.Saravanan, SRMIST

Course Code	18MHE410T	Course Name	VIRTUAL INSTRUMENTATION	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department		Mechatronics Engineering		Data Book / Codes/Standards	
				Nil	

[illegible]

Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			Level of TT	Expected	Expected	Engineering Problem Design & Analysis, Modern Tn	Society & Environment	Ethics	Individual	Community	Project M	Life Long	PSO - 1	PSO - 2	PSO - 3	
CLO-1 :	Understand the importance and benefits of virtual instrumentation and its application	2	80	70	H	L	H	H	L	-	-	M	-	-	L	M	-	-
CLO-2 :	Understand various data acquisition methods	2	80	70	H	H	H	H	L	-	-	L	-	-	L	M	-	-
CLO-3 :	Understand standard interfaces to connect external device to PC	2	80	70	H	H	H	H	L	-	-	L	-	-	L	M	-	-
CLO-4 :	Program and develop VI for various system	2	80	70	H	H	H	H	L	-	-	M	-	-	L	M	-	-
CLO-5 :	Understand the application of virtual instrumentation in the industry process	3	80	70	H	H	H	H	L	-	-	M	-	-	L	M	-	-

		Introduction to virtual Instrumentation	Data Acquisition Techniques	Interfaces	Concept of Programming	Case Study
	Duration (hour)	8	10	9	13	5
S-1	SLO-1	Concept of virtual instrumentation	Introduction to Data Acquisition methods	Introduction to various Interfaces	Concept of programming	Simulation of system using virtual instrumentation- Introduction
	SLO-2	Example	PC based data Acquisition	Interfacing External instrument to a PC	Various tools and software available	Simple temperature indicator
S-2	SLO-1	Historical perspective of virtual instrumentation	Board DAQ card	RS 232 Interface	Concept of VI and Sub VI	ON/OFF control
	SLO-2	Development of virtual instrumentation	Resolution and sampling Frequency	RS422,RS485 Interfaces	Example	Case study-Any industrial process
S-3	SLO-1	Block diagram of basic virtual instrumentation	I/O techniques and buses,	USB standard	Display Types	PID control
	SLO-2	Architecture of virtual instrumentation	Analog to digital converter, digital to analog converter	Example	Digital ,Analog	Case study-Any industrial process
S-4	SLO-1	Advantages over other conventional programming	Multiplexing of Analog Input	IEEE 488 standard	Display Types	CRO Emulation
	SLO-2	Example for comparison	Single ended and differential ended	Example	Chart , Oscilloscope type	Case study
S-5	SLO-1	Application of VI in mechatronics engineering	Case Study- Data acquisition using DAQ card	Serial Bus	Programming constructs: Loops.	Simulation of simple second order system
	SLO-2	Case Study	Concept of sampling, resolution, single and differential ended	Example	Programming constructs: Charts.	Case Study
S-6	SLO-1	Review of Digital Instrumentation	Strategies for sampling multichannel analog input	Introduction to Bus protocol	Programming constructs: Arrays.	
	SLO-2	Representing Analog Signal in digital domain	Example	Various Example	Example	
S-7	SLO-1	Quantization	Concept of Universal DAQ card	MOD Bus	Programming constructs: Clusters	
	SLO-2	Sample and hold	Example	Example	Example	
S-8	SLO-1	Sampling Theorem	Use of Timers	CAN Bus	Programming constructs: graphs.	
	SLO-2	ADC and DAC	Example	Example	Example	

S-9	SLO-1		Use of Counter	Case Study (Communication protocols I2C, SPI, Serial)	Programming constructs: Case structure	
	SLO-2		Example	Interfacing sensor to the controller	Example	
S-10	SLO-1		Case Study		Programming constructs: sequence	
	SLO-2		Real time data acquisition process		Example	
S-11	SLO-1				Formula nodes	
	SLO-2				Local and global variables	
S-12	SLO-1				State machine	
	SLO-2				State machine	
S-13	SLO-1				Rtring and file input/output	
	SLO-2				Review of programming	

Learning Resources	1. Wells Lisa K and Travis Jeffrey, "LabVIEW for everyone", Prentice Hall, 1997. 2. Gary Johnson, "LabVIEW Graphical Programming", 4th edition, McGraw Hill, Newyork, 1997.	3. Mahesh L Chgani and Abhay R. Samant, "Labview Signal Processing", Prentice Hall of India, 1998. 4. James K, "PC Interfacing and Data Acquisition", Elsevier, 2002.6. Robert H. Bishop, "Learning with Labview", Prentice Hall of India, 2003.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Ganesh Ram, Intel Labs ,Bangalore, ganeshram.nandakumar.@intel.com	1. Dr., R. Thiyagarajan, Visiting faculty, IIT Madras, thiyaguitm@gmail.com	1. R Ranjith Pillai , SRMIST
2. Mr. Mohammed Sagheer ,Wabco Technology Center ,India, mohammedsagheer.musthafa@wabco-auto.com	2. Dr., P Karthikeyan, MIT, Anna University, pkarthikeyan@annauniv.edu	2. G. Madhumitha ,SRMIST

Course Code	18MHE411T	Course Name	MACHINE VISION AND IMAGE PROCESSING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department		Mechatronics Engineering		Data Book / Codes / Standards	
				Nil	

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
		1	2	3	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-1:	Impart knowledge on the machine vision technology as a tool for industrial automation.	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3			
CLR-2:	Understand specifications of vision hardware				L	H	-	H	L	-	-	-	L	L	-	L	H	M	-			
CLR-3:	Understand the fundamental algorithms and implement them.				M	H	L	M	L	-	-	-	M	L	-	L	H	M	-			
CLR-4:	Enable reading of current image processing research literature.				M	H	M	H	H	-	-	-	M	L	-	L	H	M	-			
CLR-5:	Gain the experience in applying image processing algorithms to industrial problems.				M	H	M	H	H	-	-	-	M	L	-	L	H	M	-			
CLR-6:	Get an introductory information related to 3-D vision and deep learning techniques				H	H	M	H	L	-	-	-	L	L	-	L	H	M	-			
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1:	Abstract the physics of light which defines the possibilities and limitations of a vision system.	2	80	80	L	H	-	H	L	-	-	-	L	L	-	L	H	M	-			
CLO-2:	Interpret the various specifications of a imaging system and select the right hardware based on understanding of scene constraints	3	85	75	M	H	L	M	L	-	-	-	M	L	-	L	H	M	-			
CLO-3:	Develop the algorithms to enhance images.	3	75	70	M	H	M	H	H	-	-	-	M	L	-	L	H	M	-			
CLO-4:	Develop the algorithms that extract various types of attributes from digital images.	3	85	80	M	H	M	H	H	-	-	-	M	L	-	L	H	M	-			
CLO-5:	Appreciate the relevance of machine vision to mechatronics systems	3	85	75	H	H	M	H	H	-	-	-	M	L	-	L	H	M	-			
CLO-6:	Apply the concepts of machine vision and image processing in various industrial applications	3	80	70	H	H	M	H	L	-	-	-	L	L	-	L	H	M	-			

Duration (hour)		Introductory concepts	Image acquisition	Image processing	Image analysis	3-d vision & deep learning
		7	10	10	8	10
S-1	SLO-1	Introduction to course	Scene constraints	Introduction to machine vision software	Feature Extraction	Classification of 3-D Vision Techniques
	SLO-2	Related fields and Industries using vision	Performance requirement	Software selection criteria	Region Features	Active Vision - LIDAR
S-2	SLO-1	Physics of light	Fundamentals of lighting	Basics of digital image	Template Matching	Computational Stereo Vision
	SLO-2	Imaging modalities with light	Why Lighting is important?	Sampling and quantization effects	Issues to be addressed	Steps in stereo vision
S-3	SLO-1	Interactions of light	Light sources	Gray scale histogram	Methods of Template Matching	Introduction to Neural Networks
	SLO-2	Reflection and Refraction	Light sources - types and selection	Image processing	Linear Classification	Types of neural networks
S-4	SLO-1	Introduction to machine vision system building	lighting techniques	Thresholding	Corner Detection	Back propagation learning
	SLO-2	Task Specification	lighting techniques - types and selection	Contrast stretching	Harris Corner Detector	Numerical problem
S-5	SLO-1	Design of the system	Machine vision lenses	Image smoothing in spatial domain	Keypoint matching	Concepts in machine learning
	SLO-2	Cost calculation	Filters	Image sharpening in spatial domain	Matching methods	The Deep Learning Idea
S-6	SLO-1	Development, Testing and commissioning	Image sensor specifications	Edge detection in spatial domain	Texture Analysis	Application of deep learning in computer vision
	SLO-2	Human visual system	Terminologies	Derivative operators	Approaches and methods	Concepts in deep learning
S-7	SLO-1	Structure of human eye	Sensor types based on sensing element	Two dimensional discrete Fourier transform	Co-occurrence Matrix	Convolutional layer of neural network
	SLO-2	Comparison with a machine vision system	Selection criteria	Frequency domain processing for image smoothing	Properties of Co-occurrence Matrix	Numerical problem
S-8	SLO-1		Camera computer interfaces	Frequency domain processing for image sharpening	Decision making considerations	Convolutional neural network (CNN) for image classification
	SLO-2		Types and selection	Low and high pass filters	For various machine vision applications	Architecture details
S-9	SLO-1		Camera parameters governing geometrical image formation	Binary morphology		Object detection using CNN
	SLO-2		Camera modeling	Basic Morphological operations		Single shot learning for object detection

S-10	SLO-1		Camera calibration	Non Linear filters		Improving deep learning algorithms
	SLO-2		Distortions	Color image processing		Optimizers

Learning Resources	1. Rafael C. Gonzales, Richard.E.Woods, "Digital Image Processing", 2008 Edition, Pearson Education	4. EmanueleTrucco, Alessandro Verri, "Introductory Techniques For 3D Computer Vision", 1998 Edition, Prentice Hall.
	2. Eugene Hecht, A.R. Ganesan "Optics", 2001 Edition, Pearson India.	5. Ian Goodfellow, YoshuoBengio and Aaron Courville, "Deep Learning", 2015 Edition, MIT Press.
	3. Alexander Hornberg, "Handbook of Machine Vision", 2006 Edition, Wiley .	

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	20 %	-	40%	-
	Understand										
Level 2	Apply	30 %	-	40 %	-	40 %	-	40 %	-	30%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	40 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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2. Mr. Mohammed Sagheer, Wabco Technology Center, mohammedsagheer.musthafa@wabco-auto.com	2. Dr. P. Karthikeyan, MIT Campus, Anna University, pkarthikeyan@annauniv.edu	2. Ms. M. Nandhini, SRMIST

Course Code	18MHE412T	Course Name	ADVANCED CONTROL SYSTEMS			Course Category	P	Professional Elective			L	T	P	C
											3	0	0	3

Pre-requisite Courses	18MHC201J	Co-requisite Courses	NIL			Progressive Courses	NIL							
Course Offering Department	Mechatronics Engineering			Data Book / Codes/Standards			NIL							

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Gain understanding of nonlinear dynamics				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Utilize the concepts pertaining to optimal and robust control systems				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Develop an understanding of model based predictive control.																					
CLR-4 :	Gain knowledge on the implementation of optimal state estimators.																					
CLR-5 :	Gain knowledge on the implementation of adaptive control schemes for systems																					
CLR-6 :	Impart knowledge of design and implementation of advanced control systems																					

Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	Demonstrate an understanding of nonlinear dynamics				1	85	80	H	H	H	H	M	H	M	-	M	M	H	M	M	H	M
CLO-2 :	Identify the concepts pertaining to optimal and robust control systems				1	85	80	H	H	H	H	M	H	M	-	M	M	H	M	M	H	M
CLO-3 :	Demonstrate an understanding of model based predictive control.				1	85	80	H	H	H	H	M	H	M	-	M	M	H	M	M	H	M
CLO-4 :	Familiarize on the implementation of optimal state estimators.				2	85	80	H	H	H	H	M	H	M	-	M	M	H	M	M	H	M
CLO-5 :	Familiarize on the implementation of adaptive control schemes for systems				2	85	80	H	H	H	H	M	H	M	-	M	M	H	M	M	H	M
CLO-6 :	Demonstrate an understanding on the implementation of the design of advanced control systems				2	85	80	H	H	H	H	M	H	M	-	M	M	H	M	M	H	M

Duration (hour)		Non-linear systems	Robust control	Optimal control	Optimal estimation	Adaptive control
		9	9	9	9	9
S-1	SLO-1	Nonlinear Dynamics	Robustness	Principle Of Optimality	Overview Of Stochastic Processes	Need For Adaptive Control
	SLO-2	Common Physical Nonlinearities.	Sensitivity	Dynamic Programming	Probability And Random Variables	Adaptive Control Schemes
S-2	SLO-1	Concept Of Phase Plane Analysis	Analysis Of Robustness In System Parameters	Hamilton-Jacobi-Bellman Equation.	Spectral Analysis Of Stochastic Process,	Gain Scheduling
	SLO-2	Phase Portraits	Analysis Of Uncertainty In System Parameters	Hamilton-Jacobi-Bellman Equation.	Special Cases: Multivariate Normal Distribution.	Gain Scheduling
S-3	SLO-1	Singular Points	Robust Control Systems.	Calculus Of Variations	Linear Quadratic Regulator	Principle And Design
	SLO-2	Symmetry In Phase Plane Portraits	Design Of Robust Control Systems.	Pontryagin's Minimum Principle	Continuous And Discrete Form	Principle And Design
S-4	SLO-1	Non Linear Systems	PID Controlled Systems	Bang-Bang Control	Kalman Filters	Model Reference Adaptive Systems
	SLO-2	Equilibrium Points	Robust PID Controlled Systems.	Bang-Bang Control	Variants Of Kalman Filter	Principle And Approaches
S-5	SLO-1	Stability Analysis	Design Of Robust PID Controlled Systems.	Nonlinear Programming Methods	Extended Kalman Filter	The MIT Rule
	SLO-2	Lyapunov's Stability Criterion For Linear Systems.	Design Of Robust PID Controlled Systems	Direct Method	Unscented Kalman Filter	Determination Of Adaptation Gain.
S-6	SLO-1	Stability Analysis	Internal Model Control System.	Linear Quadratic Regulator Design	Kalman Filters : Continuous Time Versions.	Model Reference Adaptive Systems
	SLO-2	Lyapunov's Stability Criterion For Non-Linear Systems.	The Robust Internal Model Control System.	Continuous Riccati Equation Forms.	Kalman Filters : Continuous Time Versions.	Design Of MRAS Using Lyapunov Theory.
S-7	SLO-1	Phase Plane Trajectories	Pseudo-Quantitative Feedback Systems.	Discrete Riccati Equation Forms.	Kalman Filters : Discrete Time Versions	Self-Tuning Regulators
	SLO-2	Construction Of Phase Plane Trajectories.	Design Of Pseudo-Quantitative Feedback Systems.	Linear Quadratic Regulator Design	Kalman Filters : Discrete Time Versions	Pole Placement Design.

S-8	SLO-1	Describing Function Fundamentals	Overview Of Model Predictive Control Key Elements Of MPC.	H_2 And H-Infinity Optimal Control.	Linear–Quadratic–Gaussian	Direct Self-Tuning Regulators.
	SLO-2	Describing Function Of Common Nonlinearities	Overview Of Model Predictive Control Key Elements Of MPC.	H_2 And H-Infinity Optimal Control.	Linear–Quadratic–Gaussian (LQG) Control Problem	Direct Self-Tuning Regulators.
S-9	SLO-1	Describing Function Analysis Of Nonlinear Systems	Optimal Control	Basics Of Convex Optimization	LQG Controller Design And Implementation.	Indirect Self-Tuning Regulators.
	SLO-2	Stability Analysis By Describing Function Method.	Overview Of Methods In Optimal Control.	Receding Horizon Principle.	LQG Controller Design And Implementation.	Indirect Self-Tuning Regulators.

Learning Resources	1. Richard C Dorf and Robert H Bishop, "Modern Control Systems", 13 th edition, Pearson Education, 2016	4. Karl J Åström, Björn Wittenmark, "Adaptive Control", 2 nd edition, Dover Publication, 2008.
	2. I J Nagrath, M Gopal, "Control Systems Engineering", 6 th edition, New Age International, 2018.	5. Roland S Burns, "Advanced Control Engineering", Butterworth Heinemann, 2005.
	3. Desineni Subbaram Naidu, "Optimal Control Systems", 1 st edition, CRC Press, 2003.	6. Jean-Jacques E Slotine, Weiping Li, "Applied Nonlinear Control", Prentice Hall of India-New Jersey, 1991.

Learning Assessment						
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)				Final Examination (50% weightage)
		CLA – 1 (20%)	CLA – 2 (30%)	CLA – 3 (30%)	CLA – 4 (20%)#	
		Theory	Theory	Theory	Theory	Theory
Level 1	Remember	40 %	30 %	30 %	20 %	30 %
	Understand					
Level 2	Apply	40 %	40 %	40 %	40 %	40 %
	Analyze					
Level 3	Evaluate	20 %	30 %	30 %	40 %	30 %
	Create					
	Total	100 %	100 %	100 %	100 %	-

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
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2. Mr. Reuben Fernandes, ATOM 360, India, wenisch@atom360.io	2. Dr. Sridevi Sathya Priya, Karunya Institute of Technology and Science, s.d.s.priya@gmail.com	2. Mrs. G. Madhumitha, SRMIST

Course Code	18MHE413T	Course Name	INDUSTRIAL PROGRAMMABLE CONTROLLERS			Course Category	E	Professional Elective			L	T	P	C
											3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department		Mechatronics Engineering		Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
		1	2	3	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-1 : Understand the architecture, parts and operation of PLC, Industrial PC and PAC								Engineering Knowledge																
CLR-2 : Equip with the knowledge of various controllers specifications								Problem Analysis																
CLR-3 : Familiarize with the Ladder Programming/other programming constructs								Design & Development																
CLR-4 : Analyze and select the appropriate controller for given applications								Analysis, Design, Research																
CLR-5 : Apply the knowledge of PLC, IPC and PAC for solving typical industrial automation problems								Modern Tool Usage																
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:						Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3							
CLO-1 : Describe the architecture, parts and operation of PLC, Industrial PC and PAC		2	75	70																				
CLO-2 : Recognize various controllers specifications		3	75	70																				
CLO-3 : Develop the Ladder Programming/other programming for given applications		3	75	70																				
CLO-4 : Analyze and select the appropriate controller for given applications		3	75	70																				
CLO-5 : Apply the knowledge of PLC, IPC and PAC for solving typical industrial automation problems		3	75	70																				

	Programmable Logic Controllers (PLC)		Programming of PLC		Application of PLC-Case studies		Industrial PC		Programmable Automation Controllers (PAC)	
Duration (hour)	9		9		9		9		9	
S-1	SLO-1	Introduction to Industrial automation,- Overview of syllabus	Hardwired Logic vs Programmable Logic		Filling/Draining Control		Industrial PC-Introduction and evolution		Introduction to PACs	
	SLO-2	Evolution of PLC , Features	Hardwired Logic vs Programmable Logic		Filling/Draining Control		Industrial PC-Introduction and evolution		FPGA based PACs	
S-2	SLO-1	A short history of Industrial robots	Ladder programming		Car Park Control		Architecture of Generic Industrial PC		Compact RIO architecture	
	SLO-2	Architecture/parts of PLC	Logic functions		Car Park Control		Architecture of Generic Industrial PC		Compact RIO architecture	
S-3	SLO-1	Principles of operation	Latching		Interlocks, Priority determinism and example		Features of IPC		RT Processor	
	SLO-2	Modifying the operation	Internal relay		Interlocks, Priority determinism and example		Types of industrial PCs		Reconfigurable I/O FPGA	
S-4	SLO-1	Comparison with PC	Timers: On-delay - Off-delay - retentive timers		Part sorting		Types of industrial PCs		I/O modules-system configuration	
	SLO-2	PLC selection criteria	Timers: On-delay - Off-delay - retentive timers		Part sorting		Comparison of Various types		I/O modules-system configuration	
S-5	SLO-1	The I/O section-Discrete I/O modules- Analog I/O modules	Counters: Up-counter - down-counter - cascading counters and timers		Automatic control of warehouse door		Industrial control networks-Introduction		Software architecture-Programming modes	
	SLO-2	Special I/O modules- specifications	Counters: Up-counter - down-counter - cascading counters and timers		Automatic control of warehouse door		Industrial control networks-Introduction		Scan interface and FPGA Interface modes	
S-6	SLO-1	The CPU of PLC	Shift registers		Air-conditioning system		Architecture of Industrial control networks		Key considerations for using PAC	
	SLO-2	Memory design	Shift registers		Air-conditioning system		Architecture of Industrial control networks		Key considerations for using PAC	
S-7	SLO-1	Programming terminal device	Handling analog inputs		Applications in Fluid power automation		Requirements of Industrial control networks		Motion control with PAC-case study	
	SLO-2	Programming terminal device	Handling analog inputs		Applications in Fluid power automation		Industrial Field bus and Industrial Ethernet		Motion control with PAC-case study	
S-8	SLO-1	Recording and retrieving data	Introduction to IL&SFC		PID Control in PLC		Industrial Field bus and Industrial Ethernet		Vision based system using PAC- Case study	

	SLO-2	Recording and retrieving data	Introduction to IL & SFC	PID Control in PLC	Security issues and threats in industrial networks	Vision based system using PAC- Case study
S-9	SLO-1	HMI	Introduction to FBD and ST	PLC based servo system	Practical modern SCADA Protocols	Comparison between PLC, IPC and PAC
	SLO-2	HMI	Introduction to FBD and ST	PLC based servo system	Practical modern SCADA Protocols	Concluding Remarks

Learning Resources	1. Frank D. Petruzella, "Programmable Logic Controllers", 4 th Edition, McGraw-Hill, 2011. 2. William Bolton, "Programmable Logic Controllers", 6 th Edition, Elsevier Ltd, 2015 3. Dong Seong Kim, Hoa Tran Dang Petruzella, "Industrial sensors and Controls in Communication Networks", Springer, 2019.	4. www.pactrol.com/download/OMRON-PLC-Programming.pdf 5. http://www.ni.com/pdf/products/us/fullcriodevguide.pdf
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
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Course Code	18MHE414T	Course Name	SPECIAL ELECTRICAL MACHINES	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18MHC102T	Co-requisite Courses	18MHC204T	Progressive Courses	Nil
Course Offering Department	Mechatronics Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :		Understand the construction and principle of operation of Synchronous Reluctance Motors			1			1														
CLR-2 :		Analyse the Performance of Stepping Motors			2			2														
CLR-3 :		Understand the controllers applied in the operation of Switched Reluctance Motors			3			3														
CLR-4 :		Analyse the Magnetic circuit and characteristics of Permanent Magnet Brushless D.C. Motors			Level of Thinking (Bloom)			4														
CLR-5 :		Analyse the Permanent Magnet Synchronous Motors for suitable applications			Expected Proficiency (%)			5														
CLR-6 :		Apply the Control circuits for different applications			Expected Attainment (%)			6														
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			7			7														
CLO-1 :		Operate different types of Synchronous Reluctance Motors			8			8														
CLO-2 :		Operate different types of Stepping Motors			9			9														
CLO-3 :		Operate different types of Special machines			10			10														
CLO-4 :		Analyze the control circuits for suitable actuation			11			11														
CLO-5 :		Apply the different machines for suitable Application			12			12														
CLO-6 :		Operate, Analyze and apply different machines and control circuits for suitable applications			13			13														

		Synchronous reluctance motors	Stepping motors	Switched reluctance motors	Permanent magnet brushless d.c. Motors	Permanent magnet synchronous motors
Duration (hour)		9	9	9	9	9
S-1	SLO-1	Constructional features	Constructional features	Constructional features	Constructional features	Constructional features
	SLO-2	Constructional features	Constructional features	Constructional features	Constructional features	Constructional features
S-2	SLO-1	Types	Principle of operation	Principle of operation	Principle of operation	Principle of operation
	SLO-2	Types	Principle of operation	Principle of operation	Principle of operation	Principle of operation
S-3	SLO-1	Axial and radial air gap motors	Variable reluctance motor	Torque prediction	Types	EMF and torque equations
	SLO-2	Axial and radial air gap motors	Variable reluctance motor	Torque prediction	Types	EMF and torque equations
S-4	SLO-1	Operating principle	Hybrid motor	Power controllers	Magnetic circuit analysis	Reactance
	SLO-2	Operating principle	Hybrid motor	Power controllers	Magnetic circuit analysis	Reactance
S-5	SLO-1	Reluctance	Single and multi stack configurations	Non-linear analysis	EMF and torque equations	Phasor diagram
	SLO-2	Reluctance	Single and multi stack configurations	Non-linear analysis	EMF and torque equations	Phasor diagram
S-6	SLO-1	Phasor diagram	Theory of torque predictions	Microprocessor based control	Power controllers	Power controllers - Converters
	SLO-2	Phasor diagram	Theory of torque predictions	Microprocessor based control	Power controllers	Power controllers - Converters
S-7	SLO-1	Characteristics	Linear and non-linear analysis	Characteristics	Motor characteristics	Volt-ampere requirements
	SLO-2	Characteristics	Linear and non-linear analysis	Characteristics	Motor characteristics	Volt-ampere requirements
S-8	SLO-1	Vernier motor	Characteristics	Computer control	controllers	Torque speed characteristics
	SLO-2	Vernier motor	Characteristics	Computer control	controllers	Torque speed characteristics
S-9	SLO-1	Applications	Drive circuits	Applications	Applications	Microprocessor based control
	SLO-2	Applications	Drive circuits	Applications	Applications	Microprocessor based control

Learning Resources	1. T.J.E. Miller, „Brushless Permanent Magnet and Reluctance Motor Drives“, Clarendon Press, Oxford, 1989. 2. P.P. Aearnley, „Stepping Motors – A Guide to Motor Theory and Practice“, Peter Perengrinus, London, 1982. 	4. T. Kenjo, „Stepping Motors and Their Microprocessor Controls“, Clarendon Press London, 1984. 5. T. Kenjo and S. Nagamori, „Permanent Magnet and Brushless DC Motors“, Clarendon Press, London, 1988.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. D.Gokulakrishnan, Planning Engineer, Trade links & Services, Oman, gokul@tllsoman.com	1. Dr.S.SDash, Government College of Engineering Kednhhar, Orisha, munu_dash_2k@yahoo.com	1. Dr.M.Santhosh Rani, SRMIST
2. Mrs.T.Priya, Sr.Design Engineer, Electrical & Instrumentation, KavinEngg& Services Pvt Ltd, priya@kavinengg.com	2. Dr.M.Jagadeeshkumar, SriSaiRam Institute of Technology, jagadeeshkumar.eee@sairamit.edu.in	2. Ms.R.Gangadevi, SRMIST

Course Code	18MHE415T	Course Name	DIGITAL MANUFACTURING	Course Category	C	Professional Core	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechatronics Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																	
CLR-1 :		To learn about CAE, PLM and numerical control machining integration technology.			Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15			
CLR-2 :		To be familiar in interfacing and Communication with industrial machinery.																							
CLR-3 :		To know to formulate manufacturing computational model.																							
CLR-4 :		To gain knowledge about intelligent controls used in various machinery environment.																							
CLR-5 :		To know about future development in digital manufacturing.																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge																	
CLO-1 :		Gain knowledge in fundamentals of Digital Manufacturing						H	H	-	H	-	-												
CLO-2 :		Impart Knowledge in industrial machinery						H	H	H	-	H	-												
CLO-3 :		Learn the information characteristics of manufacturing						H	H	H	H	H													
CLO-4 :		Understand the concept of intelligent control in digital manufacturing.						H	H	H	H	H													
CLO-5 :		To impart future development and application of digital manufacturing.						H			H		H												

Duration (hour)		Introduction	Modeling	Manufacturing Information System	Intelligent control	Future developments
		9	9	9	9	9
S-1	SLO-1	concepts of digital manufacturing	manufacturing computational model	information characteristics of manufacturing	Introduction to intelligent control in digital manufacturing	Future development and application of digital manufacturing
	SLO-2	Introduction to CIM and digital manufacturing.	Modeling theory of digital manufacturing.	Information activities	Intelligent multi information sensing.	Various digital technologies in product lifecycle
S-2	SLO-1	product life cycle management(PLM).	basic concepts of computing manufacturing methodology.	manufacturing informatics.	Concept of multi information sensing.	cax technology integration.
	SLO-2	Applications of PLM	Application of C space	Measurement of manufacturing information	Application of sensor in processing	Digital equipment
S-3	SLO-1	product data management (PDM).	Application of screw space.	Basic concept of measurement of Manufacturing information	Tool condition monitoring.	digital processing technology.
	SLO-2	Applications of PDM	Virtual Prototyping	synthesis of manufacturing information	Mechanism of tool condition monitoring	Introduction to MEMS
S-4	SLO-1	Virtual environment for digital manufacturing.	Basic theory of virtual prototyping	Mechanism of synthesizing manufacturing information.	Intelligent multi information fusing	Basic concept and application of MEMS in Digital manufacturing
	SLO-2	Application of virtual environment (DM)	Application of virtual prototyping	Materialization of manufacturing information	Elements of multi information fusing	Basic concept and application of NEMS in Digital manufacturing
S-5	SLO-1	Operation mode of digital manufacturing system.	Reverse Engineering	Basic layout of Materialization of manufacturing information	Multi sensor fusion in tool state monitoring.	micro nanoequipment
	SLO-2	Mechanism of operation mode	Basic theory and application of Reverse Engineering.	integration model for manufacturing information.	Self learning	Basic concepts of micro nanoequipment systems.
S-6	SLO-1	architecture of digital manufacturing system.	Discrete model of manufacturing computing.	Block diagram of integration model for manufacturing information.	Autonomy	Extremalization of digital manufacturing
	SLO-2	Introduction to CAE	Discrete model of controlled process in manufacturing	Mechanism of integration model	Compatibility	complex mechanical system modeling.
S-7	SLO-1	CAE:engineering products	information model of manufacturing computing.	introduction to sharing manufacturing resources.	Openness of sensor fusion in tool state monitoring.	complex electrical system modeling.

	SLO-2	Design representation	Geometric modeling	Principle of sharing manufacturing resources.	Tool condition monitoring based on fuzzy theory	Digital manufacturing Technology in Micro Nano Manufacturing
S-8	SLO-1	design process	theoretical foundation for geometric modeling	.mechanism of sharing manufacturing resources	Tool condition monitoring based on neural network.	Bionic Machinery
	SLO-2	role of cad.	geometric modeling forms.	Application of Sharing manufacturing resources.	Data mining applied to digital manufacturing	Application of bionic Machinery in digital manufacturing
S-9	SLO-1	Introduction to caX technology	Geometric reasoning in manufacturing computing.	Introduction to manufacturing information security	Application of data mining in digital manufacturing	Bio-Robot
	SLO-2	Basic concepts of caX technology	Application of geometric modelling in manufacturing computing	Basic theory of manufacturing information security.	knowledge based manufacturing system.	Application of bio robot in digital manufacturing

Learning Resources	<ol style="list-style-type: none"> 1. Zudezhou, Shanxie, Dejunchen, "fundamentals of digital manufacturing science". Springer, 2012. 2. Lihui, Wang, Andrew, Y C Nee, "Collaborative Design and Planning for Digital Manufacturing", springer, 2009. 3. Saaksvuori, Antti, Anselmi, Immonen, 'Product Lifecycle Management', Springer New York, 2008. 	<ol style="list-style-type: none"> 7. Stark, J., "Product Lifecycle Management - 21st Century Paradigm for Product Realisation", Springer, 2005. 8. Vukicajovanovic, Michealdebevee. "Applications of digital manufacturing in manufacturing process support" proceedings of IAJC/ ISAM, 2014.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%) #			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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2.Mr.V.G. Balaji, Design Engineer, Rotork control, India private limited, balaji.govindan@rotork.com, Ambattur,	2. Dr. R.sarala,AlagappaChettiar college of Engineering and Technology, Manufacturing department, r.sarala@accet.edu.in, karaikudi.	2. Dr. B. K. Vinayagam, SRMIST

Course Code	18MHE416T	Course Name	PROCESS CONTROL ENGINEERING	Course Category	E	Professional Elective	L 3	T 0	P 0	C 3
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Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechatronics Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
		1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15			
CLR-1 :	Identify the need for process control	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3			
CLR-2 :	Gain the knowledge on different controller modes				H	M	M	H	M	-	-	-	M	M	-	H	H	H	H	H		
CLR-3 :	Build the various concepts of auto tuning				H	M	M	H	M	-	-	-	M	M	-	H	L	L	L	L		
CLR-4 :	Utilize the control algorithm in pneumatic				H	M	M	M	M	-	-	-	M	M	-	H	M	M	M	M		
CLR-5 :	Gain knowledge of multi loop control system				H	M	M	-	M	-	-	-	M	M	-	H	L	L	L	L		
CLR-6 :	Introduce the knowledge of non-linear control algorithms				H	M	M	H	M	-	-	-	M	M	-	H	H	H	H	H		
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	Knowledge of process control	2	75	70	H	M	M	H	M	-	-	-	M	M	-	H	H	H	H			
CLO-2 :	Knowledge about the different controller modes	3	75	70	H	M	M	H	M	-	-	-	M	M	-	H	M	M	M			
CLO-3 :	Design various control tuning methods	3	75	70	H	M	M	M	M	-	-	-	M	M	-	H	L	L	L			
CLO-4 :	Application of control algorithm in pneumatic	3	75	70	H	M	M	-	M	-	-	-	M	M	-	H	M	M	M			
CLO-5 :	Evaluate about the multi loop control system	3	75	70	H	M	M	H	M	-	-	-	M	M	-	H	L	L	L			
CLO-6 :	Interpret the knowledge of non-linear control algorithms	3	75	70	H	M	-	H	H	-	-	-	M	M	-	H	H	H	H			

	Introduction to Process Control	Controller Modes and Tuning	Final Control Elements	Multi Loop System	Nonlinear Systems and Intelligent Controllers
Duration (hour)	9	9	9	9	9
S-1	SLO-1 Process control: Introduction,	First order system,	Basic of I/P converter.	Need, types of feed-forward controller	Non-linear elements in loop: Limiters
	SLO-2 Need for process control, terminologies.	second order system	Description about I/P converter.	Introduction to steady state and dynamic,	Non-linear elements in loop: dead zones
S-2	SLO-1 Characteristics of process.	Definition of Multi position action and floating action	Introduction of Pneumatic and electric actuators	Mathematical equation for steady state and dynamic feed-forward control	Non-linear elements in loop :backlash
	SLO-2 Liquid level control system Introduction	Need of Multi position action and floating.	Description about Pneumatic and electric actuators	Mathematical equation for dynamic feed-forward control	Non-linear elements in loop: dead band velocity.
S-3	SLO-1 Block diagram of Liquid level control system	Diagram of Multi position action and floating action:	Control algorithm for Servo motor	Definition of ratio control	Introduction of Limiter, negative resistance.
	SLO-2 Description of control elements used in liquid level control	Application of Multi position action, floating action:	Control algorithm for Stepper motor	Block diagram of ratio control, uses of ratio control.	Description of Limiter, negative resistance
S-4	SLO-1 Introduction of temperature control system	Introduction of PI, PD, PID controllers	Definition and need of Valve positioner control valves	Definition of cascade controller for heat exchanger	Introduction of optimal controller
	SLO-2 Block diagram of temperature control system	Block diagram and mathematical model of PI Controller	Types and configuration of valve position.	Advantages of cascade control	Definition of optimal controller
S-5	SLO-1 Description of control elements used in temperature control.	Block diagram and mathematical model of PD Controller	Introduction of control valves.	Adaptive control: Definition, objective, types, gain schedule adaptive controller.	Need for an optimal controller
	SLO-2 Explanation about temperature control	Block diagram and mathematical model of PID Controller	Characteristics of control valves.	Block diagram description of adaptive control	Structure of an optimal controller.
S-6	SLO-1 Introduction of process dynamics	Basic Selection criteria for controllers.	Inherent characteristics of control valves.	Inferential control: Need, inferential controller for distilled column	Introduction of Dynamic matrix controller (DMC)

	SLO-2	Elements of process dynamics	Description Selection criteria for controllers.	Installed characteristics of control valves.	block diagram description of Inferential control	Definition of Dynamic matrix controller
S-7	SLO-1	Interacting systems	Need of controller tuning.	Introduction of Mathematical modeling of pneumatic control valve.	Split-range control, objective of split range control	Structure of Dynamic matrix controller
	SLO-2	Non interacting systems	Criteria for good control.	Description of Mathematical modeling of pneumatic control valve.	Block diagram for split range control.	tuning parameters required to implement Dynamic matrix controller
S-8	SLO-1	Degrees of freedom: Definition	Tuning methods: Basic of Choen-Coon method.	Valve body	Introduction of Internal mode control	Introduction of self-tuning controller
	SLO-2	Determination of degrees of freedom.	Description of Choen-Coon method.	Commercial valve` bodies	Principle and structure of Internal mode control	Need for self-tuning controller
S-9	SLO-1	Introduction of Continuous and batch process.	Introduction of Process identification for controller tuning.	Control valve sizing	Principle of Model predictive control	Structure of self- tuning controller.
	SLO-2	Description about Continuous and batch process.	Description of Process identification for controller tuning.	Cavitation and flashing	Theory of model predictive control, applications.	Case study: Process control in chemical plant.

Learning Resources	1. David A Bell., "Electronic devices and circuits", Oxford Publication., 2008.	3. D.Roy Choudhury, ShailB.Jain., "Linear integrated circuits". New Age International publishers, 2010.
	2. Robert Boylestad and Louis Nashelsky., "Electronic devices and circuit theory", Prentice Hall., 7th edition, 2005.	4. J.B. Gupta., "Electronic devices and Circuits", Sanjay Kumar Kattaria Publication, 2010. 5. Milman and Halkias.C., "Electronic devices and circuits", Tata McGraw Hill publications, 2001.

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. K.P.Srinivasan, Visteon Automotive Electronics Limited, Chennai, psriniv1@visteon.com	1. Dr. P.Karthikeyan, Anna University, Chennai, pkarthikeyan@mitindia.edu	1. Dr. T. Muthuramalingam, SRMIST
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Course Code	18MHE417T	Course Name	APPLIED MECHATRONICS SYSTEMS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechatronics Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:		Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Understand the design process and integrated design issues in mechatronics system			Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Apply the concept of robots used in different applications																						
CLR-3 :	Apply the concept of mechatronics system in medical application.																						
CLR-4 :	Apply the concept of mechatronics system in automobile application.																						
CLR-5 :	Apply the concept of mechatronics system in various industrial applications.																						
CLR-6 :	Utilize the concept of mechatronics system design into robotics, automobile and other industrial applications.																						
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																					
CLO-1 :	Analyze the mechatronics system process into various applications.				1	85	80	H	L	-	H	M	-	L	L	M	-	-	-	M	-	-	
CLO-2 :	Build parallel manipulator ,wall climbing, firefighting robot and obstacle avoidance robot				2	85	80	H	H	M	H	M	-	L	L	M	-	-	-	-	-	-	
CLO-3 :	Build a robot for Neuro rehabilitation, mechatronic assistant for laparoscopic solo surgery, Exoskeleton and powered wheelchair				2	85	80	H	H	M	H	M	-	L	L	M	-	-	-	-	-	-	
CLO-4 :	Build a system for cruise control, ABS, suspension, unmanned ground vehicle and measurement system in automobile applications.				2	85	80	H	H	M	H	M	-	L	L	M	-	-	-	-	-	-	
CLO-5 :	Build a system for thermal cycle fatigue failure, PH level neutralization system and CNC controlled drilling machine in to industrial applications				2	85	80	H	H	M	H	M	-	L	L	M	-	-	-	-	-	-	
CLO-6 :	Build the mechatronics system into various applications				2	85	80	H	H	M	H	M	-	L	L	M	-	-	-	-	-	-	

Duration (hour)		Introduction	Robotic Applications	Medical Applications	Automobile Applications	Other applications
		9	9	9	9	9
S-1	SLO-1	Mechatronics design concept and framework.	Case study 1: Parallel manipulators: state of art and perspectives	Application of robotics and mechatronic systems to neuro rehabilitation: Overview.	Electronics car engine management system	Case study 1:Thermal cycle fatigue of a ceramic plate
	SLO-2	Overview of mechatronics key elements.	Theoretical aspects of parallel manipulators and Practical applications	Robotic systems for upper limbs rehabilitation.	Stepper motor and vacuum operated throttle actuator	Case study 2:Strain gauge weighing system
S-2	SLO-1	Definition of mechatronics: Sequential integration and concurrent integration.	Development of parallel manipulator	Robotic systems for lower limbs rehabilitation.	Adaptive cruise control system	Case study 3:pH control system
	SLO-2	Integrated design issues in mechatronics.	Direct and inverse kinematics	Material and methods of neurorhabilitation system.	Adaptive cruise control system	Case study 3:pH control system
S-3	SLO-1	Introduction to real time interfacing	Bio parallel mechanism of mastication robot	Mechatronic systems for the functional assessment and the movement analysis.	Antilock braking system	Case study 4: Skip control of a CD player
	SLO-2	Elements of Data acquisition and control system	Mandibular movement and its parallel mechanism	Open issues.	Antilock braking system	Case study 4: Skip control of a CD player
S-4	SLO-1	Transducer and signal conditioning	Case study 2: Overview of a bio-inspired small sized wall climbing caterpillar Robot.	Overview of postural mechatronic assistant for laparoscopic solo surgery.	Electronics suspension control system	Case study 5: Position control of permanent magnet dc gear motor
	SLO-2	Transducer and signal conditioning	System architecture and Control methods of a bio-inspired Robot.	Overview of postural mechatronic assistant for laparoscopic solo surgery.	Electronics suspension control system	Case study 5: Position control of permanent magnet dc gear motor
S-5	SLO-1	Devices for data conversion	Climbing mechanism of the caterpillars.	Exoskeleton development and control	Electronic steering control for 4WS configuration	Case study 6: Testing of transportation bridge surface materials.
	SLO-2	Data conversion process	Mechanical module design and inchworm configuration realization, control realization.	Human robot interface	Low tire pressure warning system	Case study 6: Testing of transportation bridge surface materials.

S-6	SLO-1	Linking HMI design and system design	Locomotion control.	Wearable exoskeletal rehabilitation robot for interactive therapy	Automatic car parking system	PC based computer numerically controlled (CNC) drilling machine
	SLO-2	Human machine interface design process.	Case study 3: Firefighting Robot. Multiple interfaces based firefighting Robot.	Robot controller and therapy modes	Fuel quantity, coolant temperature measurement system	PC based computer numerically controlled (CNC) drilling machine
S-7	SLO-1	HMI design method	Case study 4: Torque cancelling system for quick-motion robots	Force sensing in medical robotics	Oil pressure and vehicle speed measurement system	Auto control system for green house temperature
	SLO-2	Designing human-automation interaction	Case study 4: Torque cancelling system for quick-motion robots	Haptic feedback using robotics surgery	Onboard diagnosis system	Mechatronics design of coin counter
S-8	SLO-1	Human error, interaction and the development of safety -critical systems	Case study 5: Recognition of finger motions for bio electric prosthetic hand via surface EMG	Model based fault detection and isolation for a powered wheelchair	Series hybrid electric vehicle	Magnetic levitation system
	SLO-2	Human error, interaction and the development of safety -critical systems	Case study 5: Recognition of finger motions for bio electric prosthetic hand via surface EMG	Model based fault detection and isolation for a powered wheelchair	Parallel hybrid electric vehicle	Washing machine control.
S-9	SLO-1	Cognitive function analysis in the design of human and machine multi agent system	Case study 6: Swimming Mechanism for robotic fish	Accurate positioning for intervention on a beating heart using crawling robot	Mechatronics design of an unmanned ground vehicle for military applications: Historical perspective, Current military systems	Electronic control of a balancing robot.
	SLO-2	Cognitive function analysis in the design of human and machine multi agent system	Case study 6: Swimming Mechanism for robotic fish	Accurate positioning for intervention on a beating heart using crawling robot	Design considerations, hardware implementation of unmanned ground vehicle, Vehicle software architecture.	Pneumatic controlled car park barrier system.

Learning Resources	1. Robert H Bishop, "Mechatronics an introduction", Taylor and Francis, 2nd edition, 2003	4. Devdasshetty, Richard A. Kolkm, "Mechatronics System Design", PWS Publishing company, 2nd edition, 2010.
	2. Annalisa Melilla, Donato Di Paola and GraziaCicirelli, "Mechatronic Systems, Applications", InTech publisher, 2010	
	3. Bolton, "Mechatronics - Electronic Control Systems in Mechanical and Electrical Engineering", 2nd edition, Addison Wesley Longman Ltd., 2007.	5. M. D. Singh, J. G. Joshi, "Mechatronics", Prentice Hall of India private limited, 2006.
		6. William B. Ribbens, Norman P. Mansour, "Understanding Automotive Electronics", 6 th edition, Elsevier science, 2013.

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. C. Purushothaman, ABB India Ltd, Chennai, purushothaman.c@in.abb.com	1. Dr.G.Sakthivel, VIT University, Chennai, sakthivel.g@vit.ac.in.	1. Ms.R.Gangadevi, SRMIST
2. Mr.J. Srinivasan, KONE Elevator India Private Limited, Chennai.srinikone@gmail.com	2. Dr.V.Santhanam, Rajalakshmi Engineering College, Chennai, santhanam.v@rajalakshmi.edu.in	2. Dr. S. Senthilraja, SRMIST

Course Code	15MHE418T	Course Name	REAL TIME EMBEDDED SYSTEMS			Course Category	C	Professional Core				L	T	P	C
												3	0	0	3

Pre-requisite Courses	18MHC205J	Co-requisite Courses	Nil			Progressive Courses	Nil
Course Offering Department		Mechatronics Engineering		Data Book / Codes/Standards		Nil	

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Learn the basics of Embedded System	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Perceive the concept of interrupts,memory and I/O management				Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3			
CLR-3 :	Study the functions and scheduling of real –time operating systems																					
CLR-4 :	Learn the concept of semaphore, Queue and pipes																					
CLR-5 :	Know the different approach of a Real Time characteristics																					
CLR-6 :	Implement the concept of interrupts with an interfacing applications																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Explain the fundamentals of embedded system design with real time system	2	90	85	H	L	H	L	M	-	H	-	-	-	-	-	-	L	M	-	M	
CLO-2 :	Analyze the fundamental concepts and can control with OS	2	90	80	H	L	M	L	M	L	M	-	-	H	-	H	M	M	L			
CLO-3 :	Evaluate the feasible algorithm and interrupts with interface applications	2	90	85	H	L	H	L	M	L	M	-	-	H	-	M	M	H	M			
CLO-4 :	Implement the concept of RTOS and interrupts with interface	2	95	90	H	L	H	L	M	-	M	-	-	M	-	M	M	H	M			
CLO-5 :	Analyse real time systems with regard to keeping time and resource restrictions	2	90	85	H	L	M	L	H	L	M	-	-	M	-	M	H	H	M			
CLO-6 :	Know the concepts of interfacing applications	2	85	85	H	L	H	M	M	-	-	-	-	M	-	M	M	H	M			

Duration (hour)		Introduction to Embedded System	Interrupts in Embedded Systems	Overview of RTOS	Real-Time Characteristics	Communication Interfacing
		09	09	09	09	09
S-1	SLO-1	Introduction to the course and Discussion	Terminologies of an Embedded System.	Introduction	Introduction to Real time Characteristics	Introduction to converters and its types
	SLO-2	Embedded computers, Characteristics of embedded computing, challenges in embedded computing system design	Gates and timing diagram	Multiple task and Multiple processes: Task and Process, Multirate Systems	Algorithm: Clock driven approach	Types of ADCs and its working principle
S-2	SLO-1	Embedded System Design process: Requirements, Specification	Memory and its types	Timing requirements on process, CPU metrics	Weighted round robin approach	Types of DACs and its working principle
	SLO-2	Architecture Design	Memory and its types	Process state and scheduling, some scheduling policies	Weighted round robin approach	Types of DACs and its working principle
S-3	SLO-1	Designing of hardware components	Microprocessor buses	Running periodic process, RTOS task and task state	Priority Driven Approach: Introduction and Concepts	Introduction to programmable Interface with A/D and its working principle
	SLO-2	Designing of software components	Programming the Input and Output Devices	Preemptive Real Time Operating Systems, Multithread preemptive schedule	Priority Driven Approach: Introduction and Concepts	Introduction to programmable Interface with A/D and its working principle
S-4	SLO-1	System Integration	Direct Memory Access	Priority Based Scheduling: Introduction and its types	Example of Priority Driven Approach	Introduction to programmable Interface with D/A and its working principle and Digital Voltmeter
	SLO-2	System Integration	Direct Memory Access	Rate-Monotonic Scheduling	Example of Priority Driven Approach	Introduction to programmable Interface with D/A and its working principle and Digital Voltmeter
S-5	SLO-1	Formalism for System Design: Structural Description	Interrupts: Built interrupts	Earliest Deadline First scheduling.	Dynamic versus Static systems	Introduction and working principle of Control robot system

	SLO-2	Formalism for System Design:Structural Description	Interrupts basis:Supervisemode,Exceptions and Traps	Evaluation of operating systems performance	Dynamic versus Static systems	Introduction and working principle of Control robot system
S-6	SLO-1	Formalism for System Design:Behavioral Description	Shared Data problem	Design of Telephone Answering Machine	Effective release Times and deadline	Introduction and working principle of Pulse Width Modulation
	SLO-2	Formalism for System Design:Behavioral Description	Disadvantage and interrupt latency	Design of Telephone Answering Machine	Effective release Times and deadline	Introduction and working principle of Motor Speed Controller
S-7	SLO-1	Design Example: Data Compressor	Embedded System evolution trends	Process synchronizationand Message queues.	Optimality of the Earliest Deadline First(EDF) algorithm:Introduction	Serial Communication and parallel Communication
	SLO-2	Design Example: Data Compressor	Embedded System evolution trends	Mailboxes,Pipes,critical selection	Optimality of the Earliest Deadline First(EDF) algorithm:Introduction	Wireless Communication
S-8	SLO-1	Design Example: Data Compressor	Interrupt routines in an RTOS environment	Semaphores:Classical synchronization problem,deadlocks.	Real Time concepts of EDF	Serial Protocols:I ² C,CAN and USB
	SLO-2	Design Example: Data Compressor	Interrupt routines in an RTOS environment	Semaphores:Classical synchronization problem,deadlocks.	Real Time concepts of EDF	Serial Protocols:I ² C,CAN and USB
S-9	SLO-1	Design Example:Alarm Clock	Real time clock	Basic Design using a Real-Time Operating System:Principle	Challenges in validating timing constraints in priority driven systems	Parallel Protocols:PCI and ARM Bus
	SLO-2	Design Example:Alarm Clock	System Clock	Encapsulating semaphores and Queues,Hard Real –Time Scheduling Considerstions	Off-line versus online scheduling	Wireless Protocols:IrDA,Bluetoothand IEEE 802.11

Learning Resources	1. Wayne Wolf,"Computers as Components:Principles of Embedded Computing System Design", Morgan Kauffman Publishers,2011 2. Frank Vahid and Tony Givargis,"Embedded SystmeDesign:AUnifiied Hardware/Software Introducton", John Wiley and Sons,2002.	3. David E.Simon, "An Embedded Software Primer",Pearson Education Asia,2001. 4. RajKamal, "Embedded Systems",Tata McGraw Hill,2009 5. NPTEL Engineering Mechanics Lectures by IIT Guwahati 'https://nptel.ac.in/courses/112103109/'
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	20 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	45 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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2.Mrs.A.Priya,Principal Engineer,TechnipFMC,Chennai,apriya@technipfmc.com	2.Dr.Albert Rajan,Karunya Institute of Technology and Sciences,Coimbatore,albert@karunya.edu	2.Dr.M.Mohamed Rabik, SRMIST

Course Code	18MHE419T	Course Name	INTELLIGENT CONTROL SYSTEMS	Course Category	P	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	18MHE412T	Progressive Courses	NIL
Course Offering Department	Mechatronics Engineering		Data Book / Codes/Standards	NIL	

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :		Understand the basics of fuzzy logic			1			1														
CLR-2 :		Impart knowledge on the learning in neural network systems			2			2														
CLR-3 :		Gain knowledge on the Hybrid Intelligent Systems			3			3														
CLR-4 :		Impart knowledge on controllers based on fuzzy logic.			4			4														
CLR-5 :		Design control systems based on artificial neural networks.			5			5														
CLR-6 :		Impart the knowledge of advanced control systems for implementation.			6			6														
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			Expected Proficiency (%)			Expected Attainment (%)														
CLO-1 :		Comprehend the basics of fuzzy logic			1			85														
CLO-2 :		Understand the learning in neural network systems			1			85														
CLO-3 :		Familiarize with the controllers based on fuzzy logic.			1			85														
CLO-4 :		Demonstrate synthesis of controllers based on fuzzy logic.			2			85														
CLO-5 :		Implement control systems based on artificial neural networks.			2			85														
CLO-6 :		Implement control system based on fuzzy or neural network			2			85														

Duration (hour)		Fuzzy logic	Artificial neural networks	Hybrid intelligent systems	Fuzzy control	Neural control
		9	9	9	9	9
S-1	SLO-1	Intelligent Systems	Artificial Neural Networks	Neuro-Fuzzy Systems	Knowledge-Based Fuzzy Control	Overview Of Supervisory Control.
	SLO-2	Intelligence In Machines	Operation Of A Single Artificial Neuron.	Fuzzy Basis Function Networks	Fuzzy PID Control	Direct Inverse Control
S-2	SLO-1	Intelligent Control System Structure	Network Architectures	Adaptive Neuro-Fuzzy Inference System - ANFIS	Knowledge-Based Fuzzy Control	Direct Learning Schemes.
	SLO-2	Soft Computing Techniques For Intelligent Control	Feed Forward Networks	Adaptive Neuro-Fuzzy Inference System - ANFIS	Model Reference Based Fuzzy Control	Indirect Learning Schemes.
S-3	SLO-1	Fuzzy Logic Systems	Radial Basis Function Networks	Training Algorithm -Supervised Algorithm	Fuzzy Control.	Model Reference Neural Adaptive Control - Direct Control
	SLO-2	Fuzzy Set Theory	Definition And Types Of RBF	Training Algorithm -Supervised Algorithm	Hybrid Fuzzy Control	Model Reference Neural Adaptive Control - Direct Control
S-4	SLO-1	Fuzzy Operations	Recurrent Networks	Training Algorithm -Unsupervised Algorithm.	Adaptive Fuzzy Control -Direct Adaptive Control.	Model Reference Neural Adaptive Control - Indirect Control
	SLO-2	Fuzzy Relations	Recurrent Network Architecture	Training Algorithm -Unsupervised Algorithm.	Adaptive Fuzzy Control -Direct Adaptive Control.	Model Reference Neural Adaptive Control - Direct Control
S-5	SLO-1	Fuzzy Implications	Learning In Neural Networks	Back Propagation Algorithm	Adaptive Fuzzy Control -Indirect Adaptive Control	Fundamentals Of Internal Model Control
	SLO-2	Theory Of Approximate Reasoning	Supervised Learning	Back Propagation Algorithm	Adaptive Fuzzy Control -Indirect Adaptive Control	Model Predictive Control
S-6	SLO-1	Fuzzy Inference System	Learning In Neural Networks	Dynamic Back Propagation	Self-Organizing Fuzzy Control	MPC With NN
	SLO-2	Fuzzifier	Unsupervised Learning	Dynamic Back Propagation	SOFC Based On The Direct Lyapunov Method.	MPC Vs Conventional Control

S-7	SLO-1	Fuzzy Rule Base	Activation Function, Adding A Bias	Orthogonal Least Squares Algorithm	SOFC Based Hurwitz Stability Criteria.	MPC Features
	SLO-2	Fuzzy Inference Engine	Perceptron Learning Rule	OLS Learning	SOFC Based On Sensitivity Functions	MPC Control Law And Convergence
S-8	SLO-1	Defuzzifier	Back Propagation Algorithm	Orthogonal Least Squares And Genetic Algorithm	Model Based Fuzzy Control	Pros And Cons Of MPC
	SLO-2	Defuzzification Methods	Back Propagation Algorithm	Orthogonal Least Squares And Genetic Algorithm	Fuzzy Inverse Control.	Feed Forward Control.
S-9	SLO-1	Fuzzy Logic Controllers	Neural Network Controller	Adaptive Least Squares Learning Using Genetic Algorithm.	Fuzzy Model Based Predictive Control.	FFC With NN
	SLO-2	General Case Study	Application Of Neural Networks In Modeling, Estimation And Control	Adaptive Least Squares Learning Using Genetic Algorithm.	Fuzzy Internal Model Control	FFC Vs Conventional Control

Learning Resources	<ol style="list-style-type: none"> Yung C. Shin and Chengying Xu, "Intelligent Systems: Modeling, Optimization and Control", CRC Press, 2009. Roland S Burns, "Advanced Control Engineering", Butterworth Heinemann, 2005. René Jager, "Fuzzy Logic in Control", TU Delft Institutional Repository, 1995. 	<ol style="list-style-type: none"> George William Irwin, K Warwick, Kenneth J Hunt, "Neural Network Applications in Control", The Institution of Electrical Engineers, 1995. Ali Zilouchian, Mo Jamshidi, "Intelligent Control Systems using Soft Computing Methodologies", CRC Press, 2001. Hung T Nguyen, Nadipuram R Prasad, Carol L Walker, Elbert A Walker, "A First Course in Fuzzy and Neural Control", Chapman and Hall, CRC, 2003.
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Learning Assessment						
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)				Final Examination (50% weightage)
		CLA – 1 (20%)	CLA – 2 (30%)	CLA – 3 (30%)	CLA – 4 (20%)#	
		Theory	Theory	Theory	Theory	Theory
Level 1	Remember	40 %	30 %	30 %	20 %	30 %
	Understand					
Level 2	Apply	40 %	40 %	40 %	40 %	40 %
	Analyze					
Level 3	Evaluate	20 %	30 %	30 %	40 %	30 %
	Create					
	Total	100 %	100 %	100 %	100 %	-

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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2. Mr. SaferUsman, Founder, TetherBox Technologies, safeerk@gmail.com	2. Dr.SrideviSathyaPriya, Karunya Institute of Technology and Science, s.d.s.priya@gmail.com	2. Mrs.G.Madhumitha, SRMIST

Course Code	18MHE420T	Course Name	INTELLIGENT MECHATRONICS SYSTEM			Course Category	E	Professional Elective			L	T	P	C
											3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses		Nil								
Course Offering Department		Mechatronics Engineering			Data Book / Codes/Standards			Nil						

Course Learning Rationale (CLR):		The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand the different types intelligent mechatronics		1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Analyze the biological foundation used in intelligent systems																			
CLR-3 :	Identify the modeling technique of intelligent mechatronics system using bond graph																			
CLR-4 :	Identify the intelligent system applied into robots																			
CLR-5 :	Identify the intelligent system applied to automobiles																			
CLR-6 :	Utilize the knowledge of artificial intelligence, neural network, bond graph modeling into developing and controlling of mechatronics system.																			

Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:	Level of Th	Expected Pt	Expected At	Engineering	Problem An	Design & D	Analysis, D	Modern Tool	Society & C	Environment	Ethics	Individual & M	Communication	Project Mgt	Life Long L	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Identify the different types of intelligent mechatronics system		1	85	80	H	L	-	H	M	-	L	L	M	-	-	-	M	-	-
CLO-2 :	Apply the knowledge of artificial intelligent, neural network and genetic algorithm in to mechatronics system		2	85	80	H	H	-	H	M	-	L	L	M	-	-	-	-	-	-
CLO-3 :	Apply the bond graph modeling technique for intelligent mechatronics system		2	85	80	H	H	-	H	M	-	L	L	M	-	-	-	-	-	-
CLO-4 :	Apply the intelligent control into robotics application		2	85	80	H	H	-	H	M	-	L	L	M	-	-	-	-	-	-
CLO-5 :	Apply the intelligent control into automobile application		2	85	80	H	H	-	H	M	-	L	L	M	-	-	-	-	-	-
CLO-6 :	Apply the artificial intelligence, neural network, bond graph modeling into developing and controlling of mechatronics system.		2	85	80	H	H	-	H	M	-	L	L	M	-	-	-	-	-	-

		Introduction to Intelligent Mechatronics Systems	Biological Foundations to Intelligent Systems	Bond graph modeling of Mechatronics	Case Studies - I	Case Studies - II
Duration (hour)		9	9	9	9	9
S-1	SLO-1	Design of a mechatronics system	Artificial Neural Networks: Introduction	Bond graph for modeling, control and diagnostic	Introduction: Automatically evaluating the training of the laparoscopic surgeon	Introduction: Rail bound mechatronics systems.
	SLO-2	Autonomous supervisory control	AI programming vs conventional programming	Power variable, energy variable	Development of three-dimensional registration system, user interface	Hybrid planning for self-optimization
S-2	SLO-1	Intelligent mechatronics device	Knowledge acquisition and knowledge representation	Pseudo bond graph, analogy of energy variable	Calibration of the mechatronics evaluation system	Active suspension system
	SLO-2	Hierarchical architecture	Back - propagation networks	Bond graph elements: passive, active and junctions, two port elements	Automatic evaluation of laparoscopic training, discussion.	Air Gap Adjustment System (AGAS)
S-3	SLO-1	System structure of intelligent mechatronics	Radial basis function networks	Causality: sequential causality assignment procedure(SCAP), Bicasual bond graph	Artificial intelligence for an automatic robotic excavator	Overview of the hybrid planning architecture.
	SLO-2	Introduction to Network intelligent mechatronics	Implementation of neural network	Casual path: Types	Development of low cost electromyography(EMG)prosthetic hand: background	Modeling and optimization of the suspension system
S-4	SLO-1	Structure of Network intelligent mechatronics	Fuzzy logic: Fuzzy set and membership functions.	State space equation, state equation, properties of state variable	Mechanical design and modeling	Modeling for air gap adjustment and prediction.
	SLO-2	Introduction to Cognitive intelligent mechatronics	Knowledge representation and inference mechanism.	State space equation of an electrical system	Electronic design ,control and actuators	Modeling for air gap adjustment and prediction.
S-5	SLO-1	Structure of Cognitive intelligent mechatronics.	Fuzzy reasoning and control	Bond graph for electrical system	Robust monitoring of an omnidirectional mobile robot: introduction	Automatic transmission system
	SLO-2	Introduction to Communicative intelligent mechatronics	Developing a fuzzy system	Bond graph for mechanical system	Bond graph modeling, fault detection and isolation using bond graph	Concept of Hybrid electric vehicles

S-6	SLO-1	Structure and operation of Communicative intelligent mechatronics	Fuzzy neural systems: Feed forward network	Bond graph for multi energy domain system	Residual evaluation, application and conclusion	Concept of High speed tilting trains
	SLO-2	Introduction to Biological intelligent mechatronics	Feedback neural networks	Multi-port field element: RS element	Dynamic modeling and control of an hexapod robot: Introduction	Concept of Path planning robot
S-7	SLO-1	Structure and operation of Biological intelligent mechatronics.	Genetic algorithm and traditional search methods	C field, I field, IC field	Geometric modeling, hexapod dynamic model, force distribution problem	Introduction to Intelligent autonomous vehicle ,definition and problem formulation
	SLO-2	Introduction to Human assistive intelligent mechatronics	Genetic algorithm: Data analysis and prediction	R field and vector junction	Quadratic problem formulation and solution	Model based fault detection and isolation for electric vehicle
S-8	SLO-1	Structure and operation of Human assistive intelligent mechatronics.	Implementation of genetic algorithm	Vector bond graph for rigid body dynamics	Computed torque control and conclusion	Results of the co-simulations and conclusion
	SLO-2	Fault ,failure, safety and fault tolerance	Implementation of genetic algorithm	Bond graph modeling of uncertain systems	Control of free and constrained motion of a C5 parallel robot, adaptive position and force controller design	Vehicle braking ,brake system model
S-9	SLO-1	Signal conditioning and interfacing	Hybrid genetic algorithm: Lamarckian evaluation, memetic algorithm	Bond graph for modeling, control and diagnostic	Mode control for unmanned aerial vehicle	Regenerative braking,4 wheel vehicle model and conclusion
	SLO-2	Signal conditioning and interfacing	Hybrid genetic algorithm: Lamarckian evaluation, memetic algorithm	Power variable, energy variable	Mode control for unmanned aerial vehicle	Regenerative braking,4 wheel vehicle model and conclusion

Learning Resources	1. Bodgan Wilamowski, J. David Irwin, "Control and Mechatronics", 2nd edition, CRC press, 2008. 2. Stanislaw H. Zak, "Systems and Control", Oxford University Press, 2003 3. Ganesh Naik, "Intelligent Mechatronics", Intech publication, 2016	4. Kevin M. Passino and Stephen Yurkovich, "Fuzzy Control", Addison Wesley Longman publication, 2001 5. Timothy J. Ross, "Fuzzy Logic with Engineering Applications", 2nd edition, John Wiley and sons, 2008 6. Rochdi Merzouki "Mechatronic & Innovative Applications" Bentham books, 2004
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
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2. Mr.J. Srinivasan, KONE Elevator India Private Limited, Chennai.srinikone@gmail.com	2. Dr.R.AmuthaKannan, National University, Muscat, amuthakkannan@nu.edu.om.	2. Mr.A. Josin Hippolitous, SRMIST

Course Code	18MHE421T	Course Name	AUTONOMOUS MOBILE ROBOTICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechatronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Formulate the challenges in developing autonomous mobile robots	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Abstract kinematic control of wheeled mobile robots	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Understand the challenges involved in sensory perception for mobile robots	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Understand the localization and path planning algorithms	Expected Attainment (%)	Design & Development
CLR-5 :	Comprehend the challenges and configurations of aerial and underwater mobile robots		Analysis, Design, Research
CLR-6 :	Build the foundations of mobile robots in various modalities		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Formulate the challenges in developing autonomous mobile robots	3 80 75	H H M L L - - - L L - L H M -
CLO-2 :	Abstract kinematic control of wheeled mobile robots	3 85 80	H H M M L - - - M L - L H M -
CLO-3 :	Understand the challenges involved in sensory perception for mobile robots	2 70 65	H M L M L - - - M L - L H M -
CLO-4 :	Develop localization and path planning algorithm for mobile robot navigation	2 75 70	H M M M M - - - M L - L H M -
CLO-5 :	Comprehend the challenges and configurations of legged, aerial and underwater mobile robots.	2 85 80	H M M M M - - - M L - L H M -
CLO-6 :	Build the required foundation for developing autonomous mobile robots.	2 80 75	H M- M M M - - - L L - L H M -

Duration (hour)	Introduction	Kinematics and Control of Mobile Robots	Sensors for Mobile Robots	Localization and Path Planning	Aerial and Underwater Robots
	6	10	9	10	10
S-1	SLO-1 Mobile Robots vs. Manipulators	Kinematic constraints of a fixed standard wheel	Sensors for mobile robots	Introduction to localization	Non-ground modality
	SLO-2 Introduction to autonomous mobile robots	Derivation	Definitions, classification	Localization challenges	Case studies
S-2	SLO-1 Locomotion aspects of mobile robots	Kinematic constraints of a omni-directional wheel	Characteristics applicable to mobile robots	Belief representations	Aerial robots
	SLO-2 Locomotion aspects of mobile robots	Derivation	Relating the characteristics to performance attributes of mobile robot	Considerations in Belief representations	Types and comparison
S-3	SLO-1 Introduction to wheeled mobile robots	Forward kinematic models of three wheeled differential drive robot	Physical and computational attributes of sensors applicable to mobile robots	Map representations	Multi-rotor aerial robot
	SLO-2 wheel types	Derivation	sensor noise and sensor aliasing	Types	Types and applications
S-4	SLO-1 Wheeled Configurations	Forward kinematics of a three wheeled omni-directional robot	GPS and heading sensors	Probabilistic localization	Quadrotor aerial robot
	SLO-2 Various wheeled configurations	Derivation	Principles, challenges and interpretation	Markov localization	Modelling of dynamics
S-5	SLO-1 Maneuverability, controllability	Degree of freedom, differential degrees of freedom	Light and sound based ranging	Introduction to Kalman filtering	Modelling of flight controller
	SLO-2 stability of mobile robots	Degree of Maneuverability	Principles, challenges and interpretation	Derivation of Kalman gain	Derivation
S-6	SLO-1 Wheeled Locomotion	Mobility analysis of various wheeled configurations	Wheel Odometry	Kalman filter for localization	Commercial flight controllers
	SLO-2 Case studies	Two, three, four, five and six wheeled configurations	Implementation algorithm for wheel odometry	Example case study and derivation	Specifications and selection criteria
S-7	SLO-1	Workspace and trajectory considerations	Wheel Odometry Critical Analysis	Sensor fusion using Kalman filter	Underwater vehicles
	SLO-2	Comparison of maneuverability and controllability	Wheel Odometry error reduction	Derivation	Foundations topics and challenges

S-8	SLO-1		State space modelling of three wheeled differential drive robot	Vision for mobile robots	Introduction to path planning,	Types of underwater vehicles
	SLO-2		Derivation	Introduction to Visual Odometry and V-SLAM	Types, Challenges and Algorithms	Comparison
S-9	SLO-1		Go-goal controller	Multi-sensor combinations	D* Lite	Modelling of underwater dynamics
	SLO-2		Block diagram level understanding	Need and types	Numerical case study	Derivation
S-10	SLO-1		Cruise Controllers		Bug algorithms	Modelling of underwater vehicle
	SLO-2		Block diagram level understanding		Vector field histogram	Derivation

Learning Resources	<ol style="list-style-type: none"> 1. Siegwart, Nourbakhsh, "Introduction to Autonomous Mobile Robots", 2nd Edition, MIT Press, 2011. 2. Bruno Siciliano, Oussama Khatib, "Handbook of Robotics", 2nd Edition, Springer, 2016. 3. Perter Corke, "Robotics, Vision and Control", 2nd Edition, Springer, 2017.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	20 %	-	40%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	30%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	40 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. N. Ganesh Ram, Intel Labs, ganeshram.nandakumar@intel.com	1. Dr. R. Thiyagarajan, IIT Madras, thiyaguilm@gmail.com	1. Dr. R. Senthilnathan, SRMIST
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Course Code	18MHE422T	Course Name	CONDITION MONITORING TECHNIQUES				Course Category	P	Professional Elective					L	T	P	C													
																	3	0	0	3										
Pre-requisite Courses	18MHC202J	Co-requisite Courses	Nil				Progressive Courses	Nil																						
Course Offering Department		Mechatronics Engineering			Data Book / Codes/Standards			Nil																						
Course Learning Rationale (CLR):		The purpose of learning this course is to:						Learning			Program Learning Outcomes (PLO)																			
CLR-1 :	Understand the basics of failures of equipments						Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15				
CLR-2 :	Impart the knowledge on the learning in fault diagnosis											Problem Analysis																		
CLR-3 :	Gain knowledge on the condition monitoring techniques											Design & Development																		
CLR-4 :	Impart the knowledge on condition monitoring of rotating electrical machines											Analysis, Design, Research																		
CLR-5 :	Impart the knowledge on condition monitoring of machine tools											Modern Tool Usage																		
CLR-6 :	Study the basic knowledge of failures of equipments and knowledge on condition monitoring of different machine tools											Society & Culture																		
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																												
CLO-1 :	Comprehend the basics of failures of equipments						1	85	80	H	L	-	M	-	-	-	-	-	-	-	-	-	-	-	-	-	-			
CLO-2 :	Understand the learning in fault diagnosis						1	85	80	H	L	-	M	-	-	-	-	-	-	-	-	-	-	-	-	-	-			
CLO-3 :	Familiarize with the condition monitoring techniques						1	85	80	H	L	-	M	L	-	-	-	-	-	-	-	-	M	H	H	H				
CLO-4 :	Implement the condition monitoring techniques on rotating electrical machines						2	85	80	H	L	-	M	L	-	-	-	-	-	-	-	-	M	H	H	H				
CLO-5 :	Implement the condition monitoring techniques on machine tools						2	85	80	H	L	-	M	L	-	-	-	-	-	-	-	-	M	H	H	H				
CLO-6 :	To understand the diagnostics techniques of different machine tools						2	85	80	H	L	-	M	L	-	-	-	-	-	-	-	-	M	H	H	H				
Duration (hour)	9		9		9		9		9		9																			
S-1	SLO-1	Introduction to condition monitoring	Condition monitoring of electrical machines - Introduction	Condition monitoring in machine tool - Introduction	Condition monitoring techniques for hydraulic system – introduction	Case study 1: Fault detection on gearboxes operating under fluctuating load con																								
	SLO-2	Theory of condition monitoring	Construction of electrical machines	Types of cutting tool in lathe	Elements in hydraulic systems	Bearing Fault diagnosis in gear box																								
S-2	SLO-1	Stages of condition monitoring	Structure of electrical machines and types	Tool wear measurement techniques – Direct method	Pump supervision methods and fault detection techniques	Case study 2: Detection of rotor – Stator rubbing in rotating machinery using acoustic emissions																								
	SLO-2	Data used for condition monitoring – Time, model and frequency domain	Types of insulation ageing mechanism – Thermal and electrical ageing	Tool wear measurement techniques – Indirect method	Fault detection of centrifugal pumps with vibration sensors	Condition monitoring of very slowly rotating machinery using AE techniques																								
S-3	SLO-1	Data processing techniques for condition monitoring	Types of insulation ageing mechanism – Mechanical and environmental ageing	Types of machine tool failures	Types failures in reciprocating pump	Case study 3: Condition monitoring for a car engine																								
	SLO-2	Data acquisition system – filter, data logging system	Condition monitoring techniques: Visual monitoring.	Fault detection and diagnosis of machine tool	Fault diagnosis in reciprocating pumps	Application of vibration diagnostics and suppression in automobile																								
S-4	SLO-1	Condition monitoring methods – vibration analysis, Thermography	Failure modes in electrical machines – Stator core and rotor winding failure	Vision based tool condition monitoring system	Leak detection methods in fluid power pipe line	Case study 4: Condition monitoring of a hydraulic system using neural networks																								
	SLO-2	Condition monitoring methods – Oil Analysis, Performance analysis	Failure modes in electrical machines – Electrical connection and bearing failures	Decision making for sensor based tool condition monitoring system	Leak detection with mass balance for liquid pipe line	Multi-layer neural networks and pattern recognition for pump fault diagnosis																								
S-5	SLO-1	Instruments for condition monitoring – Displacement and velocity measurement	Electrical machines temperature monitoring	Online tool vibration monitoring system	Types of failures in fluid power linear actuators	Case study 5: Non-destructive fault induction in an electro-hydraulic servo system																								
	SLO-2	Instruments for condition monitoring – Force and noise measurement	Electrical machines wear debris monitoring	Online tool wear monitoring system	Fault detection and diagnosis of cylinder	Failure analysis and fault simulation of an electro hydraulic servo valve																								
S-6	SLO-1	Instruments for condition monitoring – Temperature measurement	Electrical machines lubrication oil monitoring	Introduction to grinding process and its types	Types of failures in pneumatic and hydraulic Directional control valves	Case study 6; Monitoring exhaust valve leaks in diesel engines																								

	SLO-2	Instruments for condition monitoring – current and Chemical composition measurement	Electrical machines vibration monitoring	Introduction to milling process and its types	Fault detection and diagnosis of pneumatic and hydraulic Directional control valves	Monitoring vibration in diesel engines
S-7	SLO-1	Laser based measurement systems for condition monitoring	Fault detection in electrical machines – stator winding fault detection	Acoustic Emission based Monitoring of Grinding Wheel Dressing	Fault detection and diagnosis of flow control valves with pneumatic position controller	Case study 7: Development of an automated fluorescent dye penetrant inspection system
	SLO-2	Ultrasonic sound based measurement systems for condition monitoring	Fault detection in electrical machines – Brush gear fault detection	Acoustic Emission based Monitoring of Face milling	Fault detection and diagnosis of flow control valves with electronic position controller	Application of vibration analysis to monitor wear in spur gear
S-8	SLO-1	Types of Maintenance – Preventive, operative and shutdown maintenance	Fault detection in electrical machines – rotor online fault detection	Diagnostics techniques for bearing condition monitoring in machine tool	Types of failures in electro pneumatic actuator	Case study 8: On-line acoustic viscometry in oil condition monitoring
	SLO-2	Condition based maintenance	Fault detection in electrical machines – rotor offline fault detection	Sensors and signal processing techniques for bearing condition monitoring system	Fault detection and diagnosis of electro pneumatic actuator	On-line vibration monitoring for detecting fan blade damage
S-9	SLO-1	Diagnostics process and Techniques	Discharge monitoring techniques – RF coupling method	Condition monitoring techniques for sheet metal process	Real time oil oxidation monitoring system	Case study 9: A case study of bearing condition monitoring using Shock pulse method
	SLO-2	Diagnostics process and Techniques	Discharge monitoring techniques – capacitive coupling method	Remote CNC machine control	Oil viscosity monitoring system	Remote online condition monitoring for wear measurement in bearing

Learning Resources	<ol style="list-style-type: none"> 1. Peter Tavner, Li Ran, Jim Penman, Howard Sedding, Condition monitoring of rotating electrical machines, 1st ed., The Institution of Engineering and Technology, London, 2008 2. LihuiWang and Robert X. Gao., Condition Monitoring and Control for Intelligent Manufacturing, 1st ed., Springer-Verlag London Limited, 2006 	<ol style="list-style-type: none"> 3. Rolf Isermann, Sensors, and Fault-tolerant Systems, 1st ed., Springer Heidelberg Dordrecht London New York, 2011 4. Andrew C Starr and Raj B K N Rao., Condition monitoring and diagnostic engineering management, Proceedings of the 14th international Congress, 4 - 6 September Manchester, UK, 2001
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. S. Anand, Mahendra Research valley, s.anand@mahindra.com	1. Dr. P.S.sampath, KSR College of Technology, sampathps@ksrct.ac.in	1. Dr. S.Senthil Raja, SRMIST
2. Bharathiraja Ramaraj, L and T Technology Services, bharathiraja.r@lts.com	2. Dr. T.R.Chinnusamy, A.K.T memorial college of engineering technology, email : chinnu_samy80@yahoo.co.in	2. Mr. M.Thirugnanam, SRMIST

Course Code	18MHE423T	Course Name	FPGA BASED SYSTEM DESIGN	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18MHC108J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechatronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Introduce types of PLDs and their differing architectures	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Discuss different software and hardware programming language, simulation tools	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Gain knowledge about VHDL, its design flow and various description languages for Digital Logic Design	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Design combinational logic, sequential logic and state machine using VHDL	Expected Attainment (%)	Design & Development
CLR-5 :	Gain knowledge of VHDL design at system level and transformation of design developed in Matlab to VHDL		Analysis, Design, Research
CLR-6 :	Introduce about PLDs and developing digital logic design using VHDL code for electronic system design		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3

Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			Level of	Expected	Expected	Engineer	Problem	Design &	Analysis,	Modern	Society &	Environm	Ethics	Individual	Commun	Project M	Life Long	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Acquire knowledge about various Programmable Logic Devices to design an electronic system	1	75	70	H	M	M	M	M	M	L	L	L	M	M	M	M	H	H	H	M	M
CLO-2 :	Understand programming languages to develop digital design for implementation either in processors or in PLDs	2	75	70	H	M	M	H	H	L	L	L	L	M	M	M	M	H	H	H	H	L
CLO-3 :	Utilize the various description languages for developing various digital logic design	2	75	70	H	M	M	H	H	L	L	L	L	M	M	M	M	H	H	M	M	L
CLO-4 :	Develop VHDL code for Combinational logic, sequential logic and state machine design	3	75	70	H	H	M	H	H	L	L	L	L	M	M	M	M	H	H	H	H	L
CLO-5 :	Translate algorithms and models developed in MATLAB Simulink into VHDL for implementing in PLD	3	75	70	H	H	M	H	H	L	L	L	L	M	M	M	M	H	H	M	M	L
CLO-6 :	Design and develop VHDL code for implementation of digital logic in PLDs	3	75	70	H	H	M	H	H	L	L	L	L	M	M	M	H	H	H	H	H	H

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction to PLD's	Introduction to various software programming languages: C	Designing with Hardware description language	Introduction to combinational logic design	Digital to Analogue Conversion (DAC)
	SLO-2	Technology choices for digital circuit design	C++, Java	Various levels of design description	VHDL design for half adder	Digital to Analogue Conversion (DAC)
S-2	SLO-1	Electronic circuits: Analogue versus Digital	Introduction to various software programming languages: Visual Basics	Typical design flow using HDLs	Concept of multiplexer	VHDL Design for DAC
	SLO-2	Digital logic and its types	Scripting Languages, PHP	Typical design flow using HDLs	VHDL design for multiplexer	VHDL Design for DAC
S-3	SLO-1	Programmable Logic versus Digital Logic	Introduction to hardware programming languages	Design Entry Methods, HDL Design Entry	Concept of Encoder	Concept of Thyristor Gate Control
	SLO-2	Programmable Logic versus Processors	Types of hardware programming languages	Logic Synthesis with an example	VHDL design for Encoder	Concept of Thyristor Gate Control
S-4	SLO-1	Types of PLD: Simple Programmable Logic Device (SPLD)	VHDL hardware programming language	Entities, architectures, packages and configurations	Introduction to Sequential Logic Design	VHDL Design for Thyristor Gate Control
	SLO-2	Complex Programmable Logic Device (CPLD)	VHDL description for two input AND gate	Two input AND gate example	VHDL design for D-Latch	VHDL Design for Thyristor Gate Control
S-5	SLO-1	Field Programmable Gate Array (FPGA)	Verilog HDL hardware programming language	Key libraries and packages in HDL	Design of binary counter using VHDL	Model of DC Motor Control System
	SLO-2	FPGA design techniques and design constraints	Verilog HDL description for full adder	Various operators in VHDL	Design of binary counter using VHDL	Model of DC Motor Control System
S-6	SLO-1	PLD configuration technologies	Verilog-A hardware programming language	Dataflow description with example	Introduction to State Machine Design	Translation of DC motor Control system Design to VHDL
	SLO-2	PLD vendors	Verilog-A description for voltage amplifier	Dataflow description with example	Introduction to State Machine Design	Translation of DC motor Control system Design to VHDL
S-7	SLO-1	PLD design tools	System Verilog	Behavioral description with example	VHDL Design for Sequence Detector	Overview of Digital Filter Design

	SLO-2	Common basic features of design tools	Simulation Program with Integrated Circuit Emphasis (SPICE)	Behavioral description with example	VHDL Design for Sequence Detector	Overview of Digital Filter Design
S-8	SLO-1	Introduction to PLD design	Introduction to mathematical modeling	Structural description with example	VHDL design for UART receiver	Translation of Digital Filter Design to VHDL
	SLO-2	Typical PLD design flow	Various toolboxes for modeling different applications	Structural description with example	VHDL design for UART receiver	Translation of Digital Filter Design to VHDL
S-9	SLO-1	Technology Trends	Concept of Motor control system	Coding styles for VHDL	Testing of VHDL Design	Automation of Design translation to VHDL
	SLO-2	Technology Trends	Modeling of motor control system using Simulink	Coding styles for VHDL	Testing of VHDL Design	Automation of Design translation to VHDL

Learning Resources	<ol style="list-style-type: none"> 1. Ian Grout, "Digital System Design with FPGA and CPLD", Newnes publishers, 2nd edition, 2008. 2. Peter Wilson, "Design Recipes for FPGAs", Newnes publishers, 3rd edition, 2007. 3. Wayne Wolf, "FPGA based system design", Prentice Hall, 1st edition, 2004.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.A.Jegan, KPIT, Bangalore, a.jegan@kpit.com	1.Dr.D.Saravanakumar, VIT, saravanakumar.d@vit.ac.in	1. Mr. A. Lakshmi Srinivas, SRMIST
2.Mr. N.Srikanth, Lekha Wireless Solutions, Bangalore, srikanth05.mit@gmail.com	2.Dr.M.Devanathan, REVA University, devanathan.m@reva.edu.in	2. Mr. K.Sivanathan, SRMIST

Course Code	18MHE424T	Course Name	DESIGN AND ANALYSIS OF ALGORITHMS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechatronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Understand and apply algorithm analysis technique	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2 :	Describe computational solution to well known problems like searching, sorting etc.																							
CLR-3 :	Understand various approaches to solve greedy and dynamic algorithms																							
CLR-4 :	Utilize back tracking and branch and bound paradigms to solve exponential time problems																							
CLR-5 :	Analyze various algorithm design techniques to solve real time problems in polynomial time																							
CLR-6 :	Understand the limitations of Algorithmic power																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1 :	Design algorithms for various computing problems	3	80	70																				
CLO-2 :	Estimate the computational complexity of different algorithms	3	85	75																				
CLO-3 :	Critically analyze the different algorithm design techniques for a given problem	3	75	70																				
CLO-4 :	Modify existing algorithm to improve efficiency	3	85	80																				
CLO-5 :	Develop an algorithm using appropriate design strategies for problem solving	3	85	75																				
CLO-6 :	Create algorithms that are efficient in space and time complexities by using divide conquer, greedy, backtracking techniques	3	80	70																				

Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
L	H	-	H	L	-	-	-	L	L	-	H	-	-	-
M	H	L	M	L	-	-	-	M	L	-	H	-	-	-
M	H	M	H	L	-	-	-	M	L	-	H	-	-	-
M	H	M	H	L	-	-	-	M	L	-	H	-	-	-
H	H	M	H	L	-	-	-	M	L	-	H	-	-	-
L	H	M	H	L	-	-	-	L	L	-	H	-	-	-

	Introduction	Divide and conquer	Greedy Method	Dynamic Programming	Backtracking
Duration (hour)	9	9	9	9	9
S-1	SLO-1 Introduction: What is an Algorithm?	Divide and Conquer: General method	Greedy Method: General method	Dynamic Programming: General method	Backtracking: General method
	SLO-2 Algorithm Specification	Binary Search	Examples	Examples	N-Queens problem
S-2	SLO-1 Analysis Framework	Complexity of Binary search	Coin Change Problem	Multistage Graphs	Sum of subsets problem
	SLO-2 Performance Analysis: Space complexity	Recurrence equation for divide and conquer	Knapsack Problem using Greedy method	Graph algorithms	Graph coloring
S-3	SLO-1 Performance Analysis: Time complexity	Finding the maximum and minimum	Job sequencing with deadlines	Transitive Closure: All Pairs	Hamiltonian cycles
	SLO-2 Asymptotic Notations: Big-Oh notation (O)	Time complexity analysis-Examples	Minimum cost spanning trees	Dynamic programming-Longest ascending subsequence	Branch and Bound: Assignment Problem
S-4	SLO-1 Asymptotic Notations: Omega notation (Ω)	Algorithm for finding closest pair problem	Prim's Algorithm with example	Dynamic programming-Memorization	Travelling Sales Person problem-Backtracking
	SLO-2 Asymptotic Notations: Theta notation (Θ)	Merge sort algorithm	Kruskal's Algorithm	Dynamic programming-Matrix Multiplication	0/1Knapsack problem-Backtracking
S-5	SLO-1 Mathematical analysis of Non-Recursive Algorithms	Complexity Analysis of Merge sort	Example problem	Transitive Closure: Warshall's Algorithm	LC Branch and Bound solution
	SLO-2 Examples	Quick sort algorithm	Single source shortest paths: Dijkstra's Algorithm	Shortest Paths: Floyd's Algorithm	FIFO Branch and Bound solution
S-6	SLO-1 Mathematical analysis of recursive Algorithms	Complexity Analysis of Quick sort	Example problem	Floyd-Warshall Introduction	NP-Complete and NP-Hard problems: Basic concepts
	SLO-2 Examples	Best case, Worst case and Average case analysis	Optimal Tree problem: Huffman Trees	Floyd-Warshall with sample graph	On-deterministic algorithms
S-7	SLO-1 Important Problem Types: Sorting	Strassen's matrix multiplication	Optimal Tree problem: Huffman Codes	Floyd-Warshall complexity	P type problems
	SLO-2 Searching, String processing	Recurrence Relation	Transform and Conquer Approach: Heaps	Optimal Binary Search Trees	NP type problems

S-8	SLO-1	Graph Problems, Combinatorial Problems	Advantages of divide and conquer	Transform and Conquer Approach: Heap Sort	Knapsack problem using Dynamic method	NP-Complete Problems-Introduction
	SLO-2	Fundamental Data Structures: Stacks, Queues	Disadvantages of divide and conquer	Binomial Heaps	Bellman-Ford Algorithm	Satisfiability Problem
S-9	SLO-1	Graphs, Trees	Decrease and Conquer Approach	Fibonacci Heaps	Travelling Sales Person problem-Dynamic approach	NP-Hard classes
	SLO-2	Sets and Dictionaries.	Topological Sort	Examples of heaps and heap sort	Reliability design	Examples

Learning Resources	1. AnanyLevitin, Introduction to Design and Analysis of Algorithms, 3 rd ed., Pearson, 2009 2. Ellis Horowitz, SatrajSahini and Rajasekaran, Computer Algorithms/C++, 2 nd ed, Universities Press,2014	3. Thomas H .Cormen, Charles E.Leiserson, Ronal L.Rivest,Clifford Stein., Introduction to Algorithms , 3 rd ed.,PHI 4. S Sridhar, Design and Analysis of Algorithms, Oxford(Higher Education)
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	30 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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Course Code	18MHE425T	Course Name	ADVANCED MICROCONTROLLERS AND SIGNAL PROCESSING	Course Category	P	Professional Elective	L 3	T 0	P 0	C 3
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Pre-requisite Courses	18MHC205J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechatronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Perceive the fundamental knowledge of Digital signal processing	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Learn the working principle of Digital signal processor TMS320C5X	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Apply the Knowledge in the applications of Digital signal processing	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Know the working principle of ARM cortex processor	Expected Attainment (%)	Design & Development
CLR-5 :	Work with the processor by using their standard Instruction sets		Analysis, Design, Research
CLR-6 :	Perceive the fundamental knowledge of Digital signal processing		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3

Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																Level of	Expected	Expected	Engineering	Problem	Design &	Analysis,	Modern T	Society &	Environm	Ethics	Individual	Commun	Project M	Life Long	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Acquire the fundamental knowledge of Digital signal processing	1	90	85	H	L	L	L	L	L	L	L	L	L	L	L	L	M	L	L															
CLO-2 :	Learn the working principle of Digital signal processor TMS320C5X	1	90	80	H	L	L	L	L	L	L	L	L	L	L	L	L	M	M	L															
CLO-3 :	Apply the Knowledge in the applications of Digital signal processing	2	85	80	H	M	M	M	M	L	L	L	M	L	M	M	M	H	M	L															
CLO-4 :	Learn the working principle of ARM cortex processor	2	90	85	H	L	L	L	L	L	L	L	L	L	L	L	L	M	M	M															
CLO-5 :	Have knowledge to Work with the processor by using their standard Instruction set	3	85	80	H	M	M	M	M	L	L	L	L	L	L	L	L	H	H	H															
CLO-6 :	Gain knowledge about different applications using ARM and DSP controllers	3	85	80	H	H	H	H	H	L	L	L	M	L	L	M	M	H	H	H															

Duration (hour)	Introduction 9	DFT and its applications 9	DSP Processor 9	ARM Cortex Processor 9	System Design – Case Study 9
S-1	SLO-1 Introduction to Micro- controller based system design	Discrete Fourier Transform(DFT) and its properties	Introduction to DSP processors	Introduction to ARM processors	Comparison chart of various controllers
	SLO-2 Issues and challenges.	Signal conditioning system	Types of DSP processors	Types of ARM processor	Parameter selection of Controllers
S-2	SLO-1 Van-New-Mann architecture	Fast Fourier Transform(FFT) and its properties	Architecture: Block diagram of DSP processor TMS320C5X	Block diagram of ARM architecture	Analog to Digital conversion: Flash ADC
	SLO-2 Mechatronics design elements	Fast Fourier Transform(FFT) and its properties	Architecture DSP processor TMS320C5X	Block diagram of ARM architecture	Analog to Digital conversion: Successive approximation
S-3	SLO-1 Harvard architecture	DIT-FFT	Instruction set of DSP processor TMS320C5X	ARM organization : 3 stage	Digital to Analog conversion working principle
	SLO-2 Modified Harvard architecture	Problems based on DIT-FFT	Arithmetic Instructions	ARM organization : 5 stage	Types of DAC
	SLO-1 RISC, CISC	DIF-FF	Logical instructions	ARM instruction set	Power convertors
S-4	SLO-2 ASIP, Superscalar, VLIW	Problems based on DIF-FF	Load instructions	Data processing & Data transfer instructions	Power convertor applications
S-5	SLO-1 Superscalar architecture of Pentium	FIR Digital filter design	Multiply/Accumulate (MAC) operation	Multiply instruction	Power inverters
	SLO-2 Superscalar architecture of Pentium multicore processors	Problems based on FIR Digital filter design	Branching Instructions	Co processor instructions	Power inverter application
S-6	SLO-1 Types of Discrete time signals	IIR digital filter design	Compare, Select, and Store Unit (CSSU)	Addressing modes of ARM processor	Temperature sensors and its types
	SLO-2 Properties of Discrete time signals	Problems based on IIR digital filter design	Construction and operation of BLDC motor	Input and Output Modules, Mnemonics for programming	Temperature sensor applications
S-7	SLO-1 Principles of Digital Signal Processing (DSP)	Direct form-I structure for FIR and IIR systems	Addressing modes of DSP processor TMS320C5X	Thumb instruction set	Stepper motor control using DSP processor
	SLO-2 Sampling	Problems	Pressure control valve	Comparison of Thumb and ARM instruction set	Stepper motor control using ARM processor

S-8	SLO-1	Convolution of discrete-time samples	Direct form-II structure for FIR and IIR systems	Writing optimized DSP codes	Writing optimized ARM codes	DC machine control using DSP processor
	SLO-2	Properties of Convolution	Problems	Writing optimized DSP codes	Writing optimized ARM codes	DC machine control using ARM processor
S-9	SLO-1	Correlation of discrete-time samples	Cascade structure for FIR and IIR systems	Simple programs using DSP codes	Basic ARM assembly language programs	AC machine control using DSP processor
	SLO-2	Properties of Correlation	Problems	Kinematic chains, Cams actuation with example, Gear trains with example	Basic ARM assembly language programs	AC machine control using ARM processor

Learning Resources	<ol style="list-style-type: none"> 1. Steve Furber, "ARM System-on-chip Architecture", Pearson Education, India, 2000. 2. Joseph Yiu, "The Definitive Guide to ARM Cortex Processors", 3rd edition, Newnes Publication, 2013 3. John G Proakis and Dimitris G Manolakis, "Digital Signal Processing- Principles, Algorithms and Applications", 4th edition, Prentice Hall of India Limited, 2007. 4. M Bhaskar and B Venkataramani, "Digital Signal Processors: Architecture, Programming and Application", 2nd Edition, Mcgraw Higher Ed, 2010
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	40 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	20 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Ragavendraro, Hardware Architect., Intel technology Pvt. Ltd, Bangalore, ragavendra.r.r@intel.com	1. Dr. Priestly Shan, Dean, School of Electrical, Electronics and Communication Engineering, Galgotias University, New Delhi, dean.seece@galgotiasuniversity.edu.in.	1. Ms. Cross T. Asha Wise, SRMIST
2. Dr.K.Kathikeyan,R&DSpecialist,ABB India Ltd., Bangalore, India, sayalkarthik@yahoo.co.in	2. Dr. DivyaC.,Professor, Centre for Information Technology and Engineering, ManonmaniamSundaranar university, Thirunelveli, cdivya@msuniv.ac.in	2. Ms. Sasikala D., SRMIST

Course Code	18MHE426T	Course Name	ROBOT KINEMATICS AND DYNAMICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechatronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Understand the complexity and method of solving inverse kinematics for an manipulator robot		1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2 :	Understand the concept of jacobian and singularity for manipulator		Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3		
CLR-3 :	Understand and solve dynamics problem for the manipulator					H	H	L	L	-	-	-	-	-	-	M	L	-	H	H	M	-
CLR-4 :	Understand the various position and force control scheme and architecture					H	H	L	M	-	-	-	-	M	-	-	H	H	M	-		
CLR-5 :	Understand the parallel configuration of robot					H	H	L	M	-	-	-	-	M	-	-	H	H	M	-		
						H	H	L	M	-	-	-	-	M	-	-	H	H	M	-		
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	Solve the inverse kinematics problem for the various configuration of serial manipulator		2	80	70	H	H	L	L	-	-	-	-	M	L	-	H	H	M	-		
CLO-2 :	Compute the Jacobian matrix and singularity points for a manipulator robot		2	80	70	H	H	L	M	-	-	-	-	M	-	-	H	H	M	-		
CLO-3 :	Compute the dynamic model of a serial manipulator		2	80	70	H	H	L	M	-	-	-	-	M	-	-	H	H	M	-		
CLO-4 :	Understand the mathematical concept of various control schemes used for manipulator robots		2	80	70	H	H	L	M	-	-	-	-	M	-	-	H	H	M	-		
CLO-5 :	Understand the parallel configuration of robot		2	80	70	H	H	L	M	-	-	-	-	M	-	-	H	H	M	-		

Duration (hour)		Forward and Inverse Kinematics	Manipulator Jacobian and Singularity	Dynamics	Position and force control	Parallel Manipulator
		8	10	10	10	7
S-1	SLO-1	Forward Kinematics of 6 DOF articulated arm	Description/Notation for time varying position and orientation	Introduction to dynamics	Review of position control	Introduction to Parallel Manipulators
	SLO-2	Forward Kinematics of 6 DOF articulated arm	Example	Inertia, Centrifugal force, coriolis force etc	Control of Mass- spring damper system	Comparison with serial and parallel manipulator
S-2	SLO-1	Forward Kinematics of a Stanford Manipulator	Linear velocity vector for rigid bodies	Understanding dynamics of a simple system- mass spring damper system	Modelling of 1 DOF manipulator Joint	Various configuration of Parallel manipulator
	SLO-2	Forward Kinematics of a Stanford Manipulator	Angular velocity vector for rigid bodies	Inverse and forward dynamics	Deriving the mathematical model	Degree of freedom computation of parallel manipulator
S-3	SLO-1	Inverse Kinematics Introduction	Manipulator Jacobian	Lagrangian Formulation	Partitioned PD (PPD) control scheme	Forward and Inverse kinematics of a parallel manipulator
	SLO-2	Issues in Inverse Kinematics	Importance of Jacobian matrix	Computing generalized torque/force through Lagrangian Euler method	Architecture and difference from PD control	Difficulty in forward kinematics
S-4	SLO-1	Algebraic and geometric method for RRR manipulator	Linear Velocity Jacobian	Dynamic model of a 2 R Planar manipulator using LE method	Introduction to force control	Inverse Kinematics of a planar parallel manipulator
	SLO-2	Algebraic and geometric method for RRR manipulator	Derivation for RR planar manipulator	Dynamic model of a 2 R Planar manipulator using LE method	Application of force control	Inverse Kinematics of a planar parallel manipulator
S-5	SLO-1	Inverse Kinematics Computation- Closed loop solution	Linear and angular velocity Jacobian Computation	Newton Euler Formulation	Frame work for force /position control scheme	Inverse Kinematics of a spatial parallel manipulator
	SLO-2	Case study- spherical wrist	Linear and angular velocity Jacobian Computation	Computing generalized torque/force through Newton Euler method	Define- Artificial and natural constraints	Inverse Kinematics of a spatial parallel manipulator
S-6	SLO-1	Inverse kinematics of articulated arm (3 DOF)	Concept of Singularity	Dynamic model of a 2 R Planar manipulator using LE method	Case study to define artificial and natural constraint	Velocity analysis
	SLO-2	Inverse kinematics of articulated arm (3 DOF)	Types and Consequences	Dynamic model of a 2 R Planar manipulator using LE method	Case study to define artificial and natural constraint	Jacobian computation

S-7	SLO-1	Inverse kinematics of Stanford manipulator	Singularity Computation using Jacobian	Dynamic model of a inverted pendulum	Description of force control task	Workspace analysis
	SLO-2	Inverse kinematics of Stanford manipulator	Example using RR Manipulator	Dynamic model of a inverted pendulum	Example- Peg in hole assembly	Example
S-8	SLO-1	Computation consideration for inverse kinematics	Jacobian Computation for RPY wrist	Dynamic model of a SCARA robot	Force control of mass spring system	
	SLO-2	Example	Singularity Computation for RPY wrist	Dynamic model of a SCARA robot	Force control of mass spring system	
S-9	SLO-1		Jacobian Computation for articulated arm	Static Forces in manipulator	Dynamics based control	
	SLO-2		Singularity Computation for articulated arm	Static Forces in manipulator- Example	General dynamics representation	
S-10	SLO-1		Work space Analysis	Jacobian in force domain	Computed torque control	
	SLO-2		Work space Analysis	Derivation- Static force computation of a planar RR manipulator	Architecture	

Learning Resources	1. John J. Craig, "Introduction to Robotics Mechanics and Control", 3rd edition, Pearson, 2008. 2. Mark W. Spong and M. Vidyasagar, "Robot Dynamics and Control", 2nd edition, Wiley India, 2008. 3. J.P. Merlet, "Parallel Robots", 2nd edition, Springer, 2006. 4. Saeed B.Niku, "Introduction to Robotics Analysis, Systems and Applications", 2nd edition, Prentice Hall of India, 2009.	5. Robert J. Schilling, "Fundamentals of Robotics Analysis and Control", 5th edition, Prentice Hall of India Learning, 2009. 6. Mittal R.K., and Nagrath I.J., "Robotics and Control", 1st edition, Tata McGraw Hill, 2007. 7. Fu K., Gonzalez R., and Lee C. S. G., "Robotics: Control, Sensing, Vision and Intelligence", 1st edition McGraw Hill, 2008. 8. Tsuneo Yohikwa, "Foundations of Robotics Analysis and Control", 2nd edition, MIT Press, 2003
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1.Mr.Ganesh Ram, Intel Labs ,Bangalore, ganeshram.nandakumar.@intel.com	1. Dr., R. Thiagarajan, Visiting faculty, IIT Madras, thiyaquiti@gmail.com	1. Mr. Ranjith Pillai R, SRMIST
2. Mr. Mohammed Sagheer ,Wabco Technology Center ,India, mohammedsagheer.musthafa@wabco-auto.com	2. Dr., P Karthikeyan, MIT,Anna University, pkarthikeyan@annauniv.edu	2. Dr.rSenthilnathan, SRMIST

Course Code	18MHE427T	Course Name	SYSTEMS ENGINEERING			Course Category	E	Professional Elective					L	T	P	C								
												3	0	0	3									
Pre-requisite Courses	Nil		Co-requisite Courses	Nil		Progressive Courses	Nil																	
Course Offering Department			Mechatronics Engineering		Data Book / Codes/Standards		Nil																	
Course Learning Rationale (CLR):			The purpose of learning this course is to:				Learning 123 Level of Thinking (Bloom)Expected Proficiency (%)Expected Attainment (%)			Program Learning Outcomes (PLO) 123456789101112131415 Engineering KnowledgeProblem AnalysisDesign & DevelopmentAnalysis, Design, ResearchModern Tool UsageSociety & CultureEnvironment & SustainabilityEthicsIndividual & Team WorkCommunicationProject Mgt. & FinanceLife Long LearningPSO - 1PSO - 2PSO - 3														
CLR-1 :	Gain the knowledge of systems engineering																							
CLR-2 :	Identify the need for complex systems																							
CLR-3 :	Utilize the management skills in systems engineering																							
CLR-4 :	Gain knowledge of systems analysis																							
CLR-5 :	Introduce the analysis concepts in systems engineering																							
CLR-6 :	Gain knowledge of Engineering design																							
Course Learning Outcomes (CLO):			At the end of this course, learners will be able to:																					
CLO-1 :	Knowledge of systems engineering				2	75	70	H	H	M	H	M	-	-	-	-	-	-	-	H	H	H	H	
CLO-2 :	Knowledge of systems complexity				3	75	70	H	H	M	H	M	-	-	-	-	-	-	-	H	M	M	M	
CLO-3 :	Application of the management skills in systems engineering				3	75	70	H	H	M	H	M	-	-	-	-	-	-	-	H	M	M	M	
CLO-4 :	Knowledge of systems analysis				3	75	70	H	H	M	H	M	-	-	-	-	-	-	-	H	M	M	M	
CLO-5 :	knowledge of analysis concepts				3	75	70	H	H	M	H	M	-	-	-	-	-	-	-	H	M	M	M	
CLO-6 :	Interpret the knowledge of Engineering Design				3	75	70	H	H	M	H	H	-	-	-	-	-	-	-	H	H	H	H	
		Introduction to Systems Engineering		Complex Systems		Systems Engineering Management		Systems Analysis				Engineering Design												
Duration (hour)		9		9		9		9				9												
S-1	SLO-1	Origin of Systems Engineering		Complex System Structure		Managing Systems Development		Need Analysis				Prototype Development												
	SLO-2	Origin of Systems Engineering		Complex System Structure		Managing Systems Development		Need Analysis				Prototype Development												
S-2	SLO-1	Examples of Systems Engineering		Building Blocks		Risks of Systems Engineering		Functional Analysis and Allocation				Development Testing and Risk Reduction												
	SLO-2	Examples of Systems Engineering		Building Blocks		Risks of Systems Engineering		Functional Analysis and Allocation				Development Testing and Risk Reduction												
S-3	SLO-1	Systems Engineering Field		Hierarchy and Interfaces		Work Breakdown Structure (WBS)		Model-Based Systems Engineering (MBSE)				Probability of data analysis												
	SLO-2	Systems Engineering Field		Hierarchy and Interfaces		Work Breakdown Structure (WBS)		Model-Based Systems Engineering (MBSE)				Hypothesis testing												
S-4	SLO-1	Systems Engineering View point		Complex System Interactions		Systems Engineering Management Plan (SEMP)		Requirement Analysis				Implementing system building blocks												
	SLO-2	Systems Engineering View point		Complex System Interactions		Systems Engineering Management Plan (SEMP)		Requirement Analysis				Implementing system building blocks												
S-5	SLO-1	Domain of Systems Engineering		System Complexity		Systems Risk Management		Decision Making				Reliability and Redundancy												
	SLO-2	Domain of Systems Engineering		System Complexity		Systems Risk Management		Decision Making				Reliability and Redundancy												
S-6	SLO-1	Approaches of Systems Engineering		Complex System Environment		Systems Architecture		Modeling for Decisions				Concepts of Maintainability, Availability and Producibility												
	SLO-2	Approaches of Systems Engineering		Complex System Environment		Systems Architecture		Modeling for Decisions				Concepts of Maintainability, Availability and Producibility												
S-7	SLO-1	Activities of Systems Engineering		Systems Engineering methods		Performance Requirements		Simulation Analysis				Systems Integration												
	SLO-2	Activities of Systems Engineering		Systems Engineering methods		Performance Requirements		Simulation Analysis				Systems Integration												
S-8	SLO-1	Perspectives of Systems Engineering		Life cycle and Evolutionary characteristics		System Requirements Development		System Modeling Languages				Testing and evaluating total system												
	SLO-2	Perspectives of Systems Engineering		Life cycle and Evolutionary characteristics		System Requirements Development		System Modeling Languages				Testing and evaluating total system												
S-9	SLO-1	Systems Engineering Products		Systems testing throughout development		Systems Validating Requirements		Trade-off Analysis				Development to Production												
	SLO-2	Systems Engineering Products		Systems testing throughout development		Systems Validating Requirements		Trade-off Analysis				Development to Production												

Learning Resources	1. Kossiakkoff, A. Sweet, Seymour, S., W.N., Biemer, S.M., "Systems Engineering Principles and Practice", John Wiley & Sons, 2nd Edition, 2011. 2. Blanchard, B.S. and Fabrycky, W.J., "Systems Engineering and Analysis", Prentice Hall, 4th Edition, 2005. 3. Zeigler, B.P., H. Praehofer, T.G. Kim., "Theory of Modeling and Simulation", Academic Press, 2nd Edition, 2000.	4. Groover. M.P., "Automation, production systems and computer integrated manufacturing", 3rd edition, Prentice Hall of India, 2007. 5. Gharajedaghi, J., "Systems Thinking, Managing Chaos and Complexity: A Platform for Design Business Architecture", Butterworth Heinemann, 2nd Edition, , 2005.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. K.P.Srinivasan, Visteon Automotive Electronics Limited, Chennai, psriniv1@visteon.com	1. Dr. P. Karthikeyan, Anna University, Chennai, pkarthikeyan@mitindia.edu	1. Dr. T. Muthuramalingam, SRMIST
2. Mr. S. EllanChezhian, Keyence Microscope Limited, Chennai, ellanchezhian@gmail.com	2. Dr. D. Saravanakumar, VIT University, Chennai, saravanakumar.d@vit.ac.in.	2. Dr. M. Mohamed Rabik, SRMIST

Course Code	18MHE501T	Course Name	ROBOTICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechatronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Introduce the various architecture of Industrial robot				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Understand the concept of vectors and transformation used in robotics				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Formulate the forward kinematics of manipulators																					
CLR-4 :	Introduce the various actuators, transmission elements and sensors used in robot																					
CLR-5 :	Introduce the various control strategy and work cell layout																					
CLR-6 :	Understand the terminologies and various mathematical concepts in manipulator robotics																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	Understand various terminologies and configuration of an industrial robot				2	80	70	H	M	M	H	M	-	-	-	-	-	H	H	-	-	
CLO-2 :	Understand the application of vectors and transformation applied to robotics				2	80	70	H	H	M	H	M	-	-	-	-	-	H	H	-	-	
CLO-3 :	Solve the forward kinematic model of the manipulators				2	80	70	H	H	M	H	M	-	-	-	H	-	-	H	H	-	-
CLO-4 :	Understand the various actuators, sensors and transmission used in robot				2	80	70	H	H	H	H	M	-	-	-	M	-	-	H	H	-	-
CLO-5 :	Understand the various types of control used in robot				2	80	70	H	H	M	H	M	-	-	-	M	-	-	H	H	-	-
CLO-6 :	Get conversant with fundamental terminologies and mathematical concepts to solve kinematics problem				2	80	70	H	H	M	H	M	-	-	-	M	-	-	H	H	-	-

	Introduction to Robotics	Transformations	Manipulator Kinematics	Introduction to sensors and actuators in robotics	Trajectory planning and work cell
Duration (hour)	9	12	11	8	8
S-1	SLO-1 Introduction to Robotics- History, laws of robotics	Review of Vectors	Introduction to kinematics	Basic Actuators	Types of Robot control
	SLO-2 Classification based on application	Vector representation of points and bodies	Forward and inverse kinematics	Selection of actuators	Cartesian and joint space scheme trajectory planning
S-2	SLO-1 Definition of work volume	Translation-numerical problem	Geometric and algebraic approach	Transmission elements	Force control
	SLO-2 Classification based on work volume	Rotation-numerical problem solving	Forward kinematics of RR,RRR planar manipulator using geometric approach	Selection	Case study- Mass Spring system
S-3	SLO-1 Precision, repeatability, accuracy in terms of robotics	Representing rotation- rotation matrix	Geometric approach for RRP spatial manipulator	Harmonic drives	Position Control
	SLO-2 Co ordinate systems and Degree of freedom	Numerical problem solving	Comparison of geometric and algebraic approach	Advantage of harmonic drives over other transmission elements	Case Study- 1 DOF joint model
S-4	SLO-1 Various joints in robot, links	Representing Rotation- Euler angles	D-H formulation for manipulator kinematics	Force sensors – Importance and types, working Principle	Hybrid force position control
	SLO-2 Configuration and operational space	Numerical problem solving	D-H formulation for manipulator kinematics	Maltese Cross Configuration	Case study
S-5	SLO-1 Anatomy of robot and wrist configuration	Representing Rotation- Equivalent axis representation	Difference between standard and modified DH convention	Tactile sensor- Importance and use	Robot Cell Layout
	SLO-2 Example	Numerical problem solving	Example – kinematics of RR planar manipulator using both convention	Tactile sensor- Various type and its working	Robot Cell Layout
S-6	SLO-1 Robot end effectors	Difference between current axis and fixed axis representation	Forward kinematics of 3 DOF RRP manipulator	Slip sensor- Importance and use	Safety Monitoring
	SLO-2 Various Types	Numerical problem solving	Forward kinematics of 3 DOF RRP manipulator	Slip sensor- Various type and its working	Error Detection and Recovery

S-7	SLO-1	Gripper type	Homogeneous transformation	Forward kinematics of 3 DOF RRR spatial manipulator	Vision system for robot	Robot cycle time analysis
	SLO-2	Design of mechanical gripper and grasping	Numerical problem solving	Forward kinematics of 3 DOF RRR spatial manipulator	Architecture	Robot cycle time analysis
S-8	SLO-1	Various gripper in robot	Operators and mapping concept	Forward Kinematics of RPY wrist	Case study on vision system	Economic analysis of robot
	SLO-2	Selection criteria	Case study- numerical problem solving	Forward Kinematics of RPY wrist	Case study on vision system	Economic analysis of robot
S-9	SLO-1	Interpreting various data in the the robot data sheet	Compound Transformation	Forward kinematics of 4DOF SCARA robot		
	SLO-2	Interpreting various data in the the robot data sheet	Case Study	Forward kinematics of 4DOF SCARA robot		
S-10	SLO-1		Operators and mapping concept	Introduction to inverse kinematics		
	SLO-2		Case study- numerical	Inverse kinematics of RR planar manipulator- geometric approach		
S-11	SLO-1		Compound transformation	Issues in inverse kinematics		
	SLO-2		Case study	Issues in inverse kinematics		
S-12	SLO-1		Case study of transformations in robotics			
	SLO-2		Case study of transformations in robotics			

Learning Resources	1. Mikell P. Groover, "Industrial Robotics", McGraw Hill, 2 nd edition, 2012. 2. John J. Craig, "Introduction to Robotics", 3 rd Edition, Addison Wesley, ISE 2008. 3. Deb S.R., "Robotics Technology and Flexible Automation", 2 nd edition, Tata McGraw - Hill Publishing Company Limited, 2012. 4. Arthur Critchlow, "Introduction to Robotics", 1 st edition, Macmillan, 2009. 5. Mohsen Shahinpoor, "A Robot Engineering Text Book", 1 st edition, Harper and Row, 2004 6. Sterling Kinney J, "Indeterminate Structural Analysis", 1 st edition, Narosa Publishing House, 1987.
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	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1.Mr.Ganesh Ram, Intel Labs ,Bangalore, ganeshram.nandakumar@intel.com	1. Dr., R. Thiyagarajan, IIT Madras, thiyaguiitm@gmail.com	1. Ranjith Pillai R, SRMIST
2. Mr. Mohammed Sagheer ,Wabco Technology Center ,India, mohammedsagheer.musthafa@wabco-auto.com	2. Dr., P Karthikeyan, MIT, Anna University, pkarthikeyan@annauniv.edu	2. Dr. R Senthilnathan, SRMIST

Course Code	18MHE502T	Course Name	MECHANICS OF MANIPULATION	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18MHE501T-Robotics	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechatronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1: Understand the complexity and method of solving inverse kinematics for an manipulator robot		1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2: Understand the concept of Jacobian and static forces applied to manipulator		Level of Thinking (Bloom)	Engineering Knowledge
CLR-3: Learn the importance of singularity and workspace in manipulator robot		Expected Proficiency (%)	Problem Analysis
CLR-4: Understand and solve dynamics problem for the manipulator		Expected Attainment (%)	Design & Development
CLR-5: Understand the parallel configuration of robot			Analysis, Design, Research
CLR-6: To get an overview of challenges involved in manipulator robotics			Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1: Solve the inverse kinematics problem for serial manipulators		2 80 70	H M M H M - - - - - H H - -
CLO-2: Compute the Jacobian matrix and static forces in manipulator		2 80 70	H H M H M - - - - H H - -
CLO-3: Understand the important concept of singularity and its computation		2 80 70	H H M H M - - - - H H - -
CLO-4: Compute the dynamic model of a serial manipulator		2 80 70	H H H H M - - - - M - - H H - -
CLO-5: Understand the parallel configuration of robot		2 80 70	H H M H M - - - - M - - H H - -
CLO-6: Get conversant with overall challenges involved in manipulators		2 80 70	H H M H M - - - - M - - H H - -

Duration (hour)	Manipulator Kinematics	Velocity Analysis	Singularity and Workspace analysis	Dynamic Modelling	Parallel Manipulator
	9	11	10	8	7
S-1	SLO-1 Forward kinematics of 6 DOF articulated arm	Description/Notation for time varying position and orientation	Concept of Singularity	Introduction to dynamics	Introduction to parallel manipulators
	SLO-2 Forward kinematics of 6 DOF articulated arm	Example	Types and consequences	Inertia, centrifugal force, coriolis force etc	Comparison with serial and parallel manipulator
S-2	SLO-1 Forward kinematics of a Stanford Manipulator	Linear velocity vector for rigid bodies	Singularity computation using Jacobian	Understanding dynamics of a simple system- mass spring damper system	Various configuration of parallel manipulator
	SLO-2 Forward kinematics of a Stanford Manipulator	Angular velocity vector for rigid bodies	Example using RR Manipulator	Inverse and forward dynamics	Degree of freedom computation of parallel manipulator
S-3	SLO-1 Inverse kinematics Introduction	Manipulator Jacobian	Singularity computation of RPY wrist	Lagrangian formulation	Forward and inverse kinematics of a parallel manipulator
	SLO-2 Issues in inverse kinematics	Importance of Jacobain matrix	Singularity computation of RPY wrist	Computing generalized torque/force through Lagrangian-Euler (LE) method	Challenges in forward kinematics
S-4	SLO-1 Algebraic and geometric method for RRR manipulator	Linear velocity Jacobian	Singularity computation of 6 DOF articulated arm	Dynamic model of a RR Planar manipulator using LE method	Inverse Kinematics of a planar parallel manipulator
	SLO-2 Algebraic and geometric method for RRR manipulator	Derivation for RR planar manipulator	Singularity computation of 6 DOF articulated arm	Dynamic model of a RR Planar manipulator using LE method	Inverse Kinematics of a planar parallel manipulator
S-5	SLO-1 Inverse kinematics Computation- Closed loop solution	Linear and angular velocity Jacobian computation	Work space analysis	Newton-Euler Formulation	Inverse Kinematics of a spatial parallel manipulator
	SLO-2 Case study- spherical wrist	Linear and angular velocity Jacobian computation	Work space analysis	Computing generalized torque/force through Newton Euler method	Inverse Kinematics of a spatial parallel manipulator
S-6	SLO-1 Inverse kinematics of articulated arm (6 DOF)	Jacobian Computation for RPY wrist	Introduction to Trajectory Planning	Dynamic model of a RR Planar manipulator using LE method	Velocity analysis

	SLO-2	Inverse kinematics of articulated arm (6 DOF)	Jacobian computation for RPY wrist	Joint space and Cartesian space	Dynamic model of a RR Planar manipulator using LE method	Jacobian computation
S-7	SLO-1	Inverse kinematics of Stanford manipulator	Jacobian computation for articulated arm	Joint space trajectory planning	Dynamic model of a inverted pendulum	Workspace analysis
	SLO-2	Inverse kinematics of Stanford manipulator	Jacobian computation for articulated arm	Example of cubic polynomial	Dynamic model of a inverted pendulum	Example
S-8	SLO-1	Computation consideration for inverse kinematics	Static forces in manipulator	Joint space trajectory planning via points	Dynamic model of a SCARA robot	
	SLO-2	Example	Static forces in manipulator- Example	Cubic polynomial via points	Dynamic model of a SCARA robot	
S-9	SLO-1	Forward and Inverse Kinematics in robot control	Jacobian in force domain	Cartesian space trajectory planning		
	SLO-2	Example	Derivation	Case study		
S-10	SLO-1		Static force computation of a planar RR manipulator	Problem in Cartesian space planning		
	SLO-2		Static force computation of a planar RR manipulator	Example		
S-11	SLO-1		Cartesian transformation of velocities and forces			
	SLO-2		Example			

Learning Resources	<ol style="list-style-type: none"> John J. Craig, "Introduction to Robotics Mechanics and Control", 3rd edition, Pearson, 2008. Mark W. Spong and M. Vidyasagar, "Robot Dynamics and Control", 2nd edition, Wiley India, 2008. J.P. Merlet, "Parallel Robots", 2nd edition, Springer, 2006. Saeed B.Niku, "Introduction to Robotics Analysis, Systems and Applications", 2nd edition, Prentice Hall of India, 2009. 	<ol style="list-style-type: none"> Robert J. Schilling, "Fundamentals of Robotics Analysis and Control", 5th edition, Prentice Hall of India Learning, 2009. Mittal R.K., and Nagrath I.J., "Robotics and Control", 1st edition, Tata McGraw Hill, 2007. Fu K., Gonzalez R., and Lee C. S. G., "Robotics: Control, Sensing, Vision and Intelligence", 1st edition McGraw Hill, 2008. Tsunee Yohikwa, "Foundations of Robotics Analysis and Control", 2nd edition, MIT Press, 2003.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

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1.Mr.Ganesh Ram, Intel Labs ,Bangalore, ganeshram.nandakumar.@intel.com	1. Dr., R. Thiagarajan, Visiting faculty, IIT Madras, thiyaguitm@gmail.com	1. Dr. G. Murali, SRMIST
2. Mr. Mohammed Sagheer, Wabco Technology Center ,India, mohammedsagheer.musthafa@wabco-auto.com	2. Dr., P Karthikeyan, MIT,Anna University, pkarthikeyan@annauniv.edu	2. Ranjith Pillai R, SRMIST

Course Code	18MHE503T	Course Name	MOBILE ROBOTICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	18MHE510T - Planning and Decision Making in Robotics
Course Offering Department	Mechatronics Engineering	Data Book / Codes / Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Formulate the challenges in developing autonomous mobile robots	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Abstract kinematic control of wheeled mobile robots	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Understand the challenges involved in sensory perception for mobile robots	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Understand the mechanics of legged robots for locomotion	Expected Attainment (%)	Design & Development
CLR-5 :	Comprehend the challenges and configurations of aerial and underwater mobile robots		Analysis, Design, Research
CLR-6 :	Build the foundations of mobile robots in various modalities		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Appreciate the various problems to be addressed in autonomous mobile robots	3 80 75	H H M L L - - - L L - L H M -
CLO-2 :	Understand the various types and configurations of wheeled and legged mobile robots	3 80 75	H H M M L - - - M L - L H M -
CLO-3 :	Formulate the kinematics of wheeled and legged mobile robots of popular configurations	2 70 65	H M L M L - - - M L - L H M -
CLO-4 :	Build the dynamic model of multi-rotor aerial and underwater robots	2 75 70	H M M M M - - - M L - L H M -
CLO-5 :	Understand the issues in interpreting proprioceptive and exteroceptive sensory data on-board mobile robots	2 85 80	H M M M M - - - M L - L H M -
CLO-6 :	Build the required foundation for developing autonomous mobile robots.	2 80 75	H M- M M M - - - L L - L H M -

Duration (hour)	Introduction	Kinematics and Control of Mobile Robots	Sensors for Mobile Robots	Legged Robots	Aerial and Underwater Robots
	6	10	10	9	10
S-1	SLO-1 Mobile robots vs. manipulators	Kinematic constraints of a fixed standard wheel	Sensors for mobile robots	Introduction to limbed systems	Non-ground modality
	SLO-2 Introduction to autonomous mobile robots	Derivation	Definitions, classification	Comparison with wheeled systems	Case studies
S-2	SLO-1 Locomotion aspects of mobile robots	Kinematic constraints of a omni-directional wheel	Characteristics applicable to mobile robots	Configurations of limbed systems	Aerial robots
	SLO-2 Locomotion aspects of mobile robots	Derivation	Characteristics applicable to mobile robots	Case studies	Types and comparison
S-3	SLO-1 Introduction to wheeled mobile robots	Forward kinematic of three wheeled differential drive robot	Physical and computational attributes of sensors applicable to mobile robots	Conceptual design of limbed systems	Multi-rotor aerial robot
	SLO-2 Wheel types	Derivation	Sensor noise and sensor aliasing	Design issues	Types and applications
S-4	SLO-1 Wheeled configurations	Forward kinematics of a three wheeled omni-directional robot	GPS and heading sensors	Kinematics of quad-limbed configuration	Quadrotor aerial robot
	SLO-2 Two, three, four, five and six wheeled	Derivation	Principles, challenges and interpretation	Derivation	Modelling of dynamics
S-5	SLO-1 Maneuverability, controllability	Degree of freedom, differential degrees of freedom,	Light and sound based ranging	Control strategy	Modelling of flight controller
	SLO-2 Stability of mobile robots	Holonomic and non-holonomic constraints, degree of maneuverability	Principles, challenges and interpretation	Model of control algorithm for legged robot	Derivation
S-6	SLO-1 Wheeled locomotion	Mobility analysis of various wheeled configurations	Wheel odometry	Design of biped configuration	Commercial flight controllers
	SLO-2 Case studies	Mobility analysis of various wheeled configurations	Algorithm	Kinematics of a biped configuration	Specifications and selection criteria
S-7	SLO-1	Workspace and trajectory considerations	Wheel odometry critical analysis	Design case study of a complete humanoid	Underwater vehicles

	SLO-2		Comparison	Wheel odometry error reduction	Considerations and challenges	Foundations topics and challenges
S-8	SLO-1		State space modelling of three wheeled differential drive robot	Vision for mobile robots	Mechanical system design	Types of underwater vehicles
	SLO-2		Derivation	Techniques and purpose	Case study	Comparison
S-9	SLO-1		Go-goal controller	Multi-sensor combinations	Electrical system design	Modelling of underwater dynamics
	SLO-2		Block diagram level model	Need and types	Case study	Derivation
S-10	SLO-1		Cruise controllers	Sensor fusion algorithms		Modelling of underwater vehicle
	SLO-2		Block diagram level model	Types and selection		Derivation

Learning Resources	1. Siegwart, Nourbakhsh, "Introduction to Autonomous Mobile Robots", 2 nd Edition, MIT Press, 2011. 2. Bruno Siciliano, Oussama Khatib, "Handbook of Robotics", 2 nd Edition, Springer, 2016. 3. Perter Corke, "Robotics, Vision and Control", 2 nd Edition, Springer, 2017.					
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. N. Ganesh Ram, Intel Labs ganeshram.nandakumar@intel.com	1. Dr. R. Thiyagarajan, IIT Madras, thiyaguitm@gmail.com	1. Dr. R. Senthilnathan, SRMIST
2. Mr. Mohammed Sagheer, Wabco Technology Center, mohammedsagheer.musthafa@wabco-auto.com	2. Dr. P. Karthikeyan, MIT Campus, Anna University, pkarthikeyan@annauniv.edu	2. Mr. K. Sivanathan, SRMIST

Course Code	18MHE504T	Course Name	ROBOT CONTROL	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18MHE501T - Robotics	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechatronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1:	Understand the position control schemes in robot	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2:	Define the importance of force control in robot application		
CLR-3:	Learn the force/position control and trajectory control schemes in robotics		
CLR-4:	Get familiar with the nonlinear systems and its control strategy		
CLR-5:	Learn the various programming methods in robot		
CLR-6:	To get an insight of the role of kinematics and dynamics in control		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Engineering Knowledge
CLO-1:	Understand various position control schemes and its implementation	2 80 70	H M M H M - - - - - H H - -
CLO-2:	Apply various force control schemes	2 80 70	H H M H M - - - - - H H - -
CLO-3:	Derive the force/position and trajectory control schemes for manipulators	2 80 70	H H M H M - - - - - H H - -
CLO-4:	Learn the complexities of nonlinear systems and various control schemes	2 80 70	H H H H M - - - - - H H - -
CLO-5:	Understand the various programming methods in robotics	2 80 70	H H M H M - - - - - H H - -
CLO-6:	Learn various position control schemes and its implementation	2 80 70	H H M H M - - - - - H H - -

Duration (hour)	Introduction to Position control	Introduction to Force control	Force/Position Control	Introduction to non linear control	Introduction to ROS
	10	11	12	6	6
S-1	SLO-1 Review of position control	Introduction to force control	Introduction to hybrid force position control problem	Introduction to nonlinear and time varying systems	Robot language classification
	SLO-2 Mass- spring damper system	Application of force control	Example	General representation	Programming methods: Lead through method, teach pendent method
S-2	SLO-1 Various linear control schemes	Frame work for force control scheme	Hybrid force/position control architecture	Control problem for manipulator	Syntax features and applications of various programming languages
	SLO-2 Characteristics of linear control	Define- Artificial and natural constraints	Example	Practical considerations	Examples
S-3	SLO-1 Position control of second order system	Case study to define artificial and natural constraint	Selection matrices	Ulyanovsk stability analysis	Inter locking commands
	SLO-2 PI implementation	Case study to define artificial and natural constraint	Case study to describe selection matrices	Example	Safety features
S-4	SLO-1 Position control of second order system	Description of force control task	Case study for hybrid force position control scheme	Introduction to nonlinear controllers	Introduction to Robot Operating System (ROS)
	SLO-2 PD implementation	Example- Peg in hole assembly	Case study for hybrid force position control scheme	Description of fuzzy based control	ROS examples
S-5	SLO-1 Position control of second order system	Force control of mass spring system	Trajectory control	Case study for fuzzy based control	Introduction to programming using ROS Industrial ROS
	SLO-2 PID implementation	Force control of mass spring system	Cartesian and joint space control	Use of Lyapunov criteria to understand stability	ROS examples
S-6	SLO-1 Modelling of 1 DOF manipulator Joint	Dynamics based control	Cubic polynomial trajectories	Introduction to sliding mode control	Programming for point to point /continuous Operations

	SLO-2	Deriving the mathematical model	General dynamics representation	Derivation	Example	Case Study
S-7	SLO-1	Partitioned PD (PPD) control scheme	Computed torque control	Point to point motion without via points		
	SLO-2	Architecture and difference from PD control	Architecture	Derivation		
S-8	SLO-1	Application of partitioned PD control scheme to 1 DOF manipulator joint	Impedance force/torque control	Point to point motion with via points		
	SLO-2	Analysis	Example	Derivation		
S-9	SLO-1	Modeling the PPD with external disturbance	Force tracking characteristics of impedance control	Linear function with parabolic blend		
	SLO-2	Architecture with external disturbance	Example of manipulator interaction with environment	Linear function with parabolic blend - example		
S-10	SLO-1	Partitioned PID control scheme	Passive compliance	Cartesian space techniques		
	SLO-2	Architecture	Example	Description of path - example		
S-11	SLO-1		Active compliance	Defining straight line path		
	SLO-2		Compliance through softening position gain	Derivation		
S-12	SLO-1			Implementation method		
	SLO-2			Implementation example		

Learning Resources	1. John J. Craig, "Introduction to Robotics", 3 rd edition, Addison Wesley, ISE 2008. 2. R.K Mittal and I J Nagrath, "Robotics and control Tata McGraw", 5 th edition, Hill, 2003.	3. S.K Saha, "Introduction to Robotics", 2 nd edition, Tata McGraw Hill, 2008. 4. Mikell P. Groover, "Industrial Robotics", McGraw Hill, 2 nd edition, 2012. 5. Aaron Martinez, "Learning ROS for robotics programming", 1 st edition, PACKT Publishing, 2013.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

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2. Mr. Mohammed Sagheer ,Wabco Technology Center ,India, mohammedsagheer.musthafa@wabco-auto.com	2. Dr., P Karthikeyan, MIT,Anna University, pkarthikeyan@annauniv.edu	2. Ranjith Pillai R, SRMIST

Course Code	18MHE505T	Course Name	COMPUTER VISION AND ITS APPLICATIONS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	18MHE506T - Advanced Computer Vision
Course Offering Department	Mechatronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Obtain motivation for approaching vision technology from a biological inspiration	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Appreciate the mathematics of projection based system	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Understand the various specifications of vision hardware	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Understand basics of image data and develop some basic image processing algorithms for enhancement and analysis	Expected Attainment (%)	Design & Development
CLR-5 :	Get introduced about computer vision applied for 3-D scene reconstruction.		Analysis, Design, Research
CLR-6 :	Understand the foundations of the vision as a potential technology for automata		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Formulate the mathematical expressions of geometric camera modelling and calibration	3 80 75	H H M L L - - - L L - L H M -
CLO-2 :	Interpret the specifications of vision hardware	3 85 80	H H M M L - - - M L - L H M -
CLO-3 :	Develop of basic image processing algorithms	2 70 65	H M L M L - - - M L - L H M -
CLO-4 :	Apply some algorithms for feature extraction	2 75 70	H M M M M - - - M L - L H M -
CLO-5 :	Understand the foundations of stereo vision technique	2 85 80	H M M M M - - - M L - L H M -
CLO-6 :	Handle applications involving image data for automata	2 80 75	H M- M M M - - - L L - L H M -

	Introduction	Vision Hardware	Image Processing	Image Analysis	3-D Vision
Duration (hour)	8	9	10	9	9
S-1	SLO-1 Introduction to Vision	Scene constraints	Vision software basics	Feature extraction	Introduction to the multi-view geometry
	SLO-2 Terminologies of fields	Fundamentals of lighting	Types and selection	Region features and classification - types	Scene reconstruction and motion estimation problem
S-2	SLO-1 Comparison of biological and computer vision	Light sources	Basics of digital image	Key point features	Geometry of a stereo vision system
	SLO-2 Specifications and limitations	Types, selection criteria	Sampling, quantization effects	Applications	Correspondence problem
S-3	SLO-1 Projective geometry	Lighting techniques	Point operations	Corner detection	Epipolar geometry
	SLO-2 Basics	Types and selection criteria	2-D convolution	Harris corner detection	Estimation of fundamental and essential matrix
S-4	SLO-1 Modelling of geometric image formation	Lenses, specifications	Image smoothing in spatial domain	Critical analysis of Harris corner detection	Epipolar constraint
	SLO-2 Derivation	Optical filters, specifications	Image sharpening and edge detection in spatial domain	Limitations and motivation for going beyond corner detection	Applications of epipolar constraint
S-5	SLO-1 Modelling of camera distortion and artifacts	Image sensors	Discrete Fourier Transform (DFT)	Key point descriptors	Application of epipolar constraint in image stitching
	SLO-2 Derivation	Specifications	Frequency domain filtering basics	Motivation and applications	Implementation details
S-6	SLO-1 Camera calibration	CCD sensor specifications	Smoothing sharpening in frequency domain	Scale Invariant Feature Transform (SIFT) key point descriptor	Epipolar rectification

	SLO-2	Methods of camera calibration	CMOS sensor specifications	Smoothing sharpening in frequency domain	Scale space construction and difference of Gaussian	Metric reconstruction
S-7	SLO-1	Estimation of projection matrix	Comparison of CCD and CMOS	Morphological image processing	Filtering of low contrast features	Non-metric reconstruction types
	SLO-2	Derivation	Advanced sensor technologies	Erosion, dilation, opening and closing	SIFT descriptor	Multi-view stereo vision
S-8	SLO-1	Experimental performance assessment in computer vision	Camera computer interfaces	Color image processing motivation	Matching algorithms	Issues and challenges
	SLO-2	Metrics and example usage	Types and selection	HSI space color image processing	Gray-level and correlation based matching	Applications of stereo vision
S-9	SLO-1		Application case studies	Application case studies	Descriptor based matching	Visual odometry case study
	SLO-2		Hardware selection exercise	Image smoothing and sharpening	Implementation details	Application in driverless cars
S-10	SLO-1			Application case studies		
	SLO-2			Morphology and colour processing		

Learning Resources	<ol style="list-style-type: none"> 1. Rafael C. Gonzales, Richard E. Woods, "Digital Image Processing, 4th Edition, Pearson Education", 2018. 2. Emanuele Trucco, Alessandro Verri, "Introductory Techniques For 3D Computer Vision", 1st Edition, Prentice Hall, 1998. 3. Alexander Hornberg, "Handbook of Machine Vision", 2nd Edition, Wiley, 2006. 4. Wiley Forsyth and Ponce, Computer Vision: A Modern Approach, 2nd Edition, Pearson, 2015.
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	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	30%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	40 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. N. Ganesh Ram, Intel Labs, ganeshram.nandakumar@intel.com	1. Dr. R. Thiyagarajan, IIT Madras, thiyaguiitm@gmail.com	1. Dr. R. Senthilnathan, SRMIST
2. Mr. Mohammed Sagheer, Wabco Technology Center, mohammedsagheer.musthafa@wabco-auto.com	2. Dr. P. Karthikeyan, MIT Campus, Anna University, pkarthikeyan@annauniv.edu	2. Mr. K. Sivanathan, SRMIST

Course Code	18MHE506T	Course Name	ADVANCED COMPUTER VISION	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18MHE505T - Computer Vision and Its Applications	Co-requisite Courses	Nil	Progressive Courses	18MHE507T - Vision Guided Robotics
Course Offering Department	Mechatronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	To understand the various active methods of reconstruction techniques	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	To comprehend various segmentation techniques used in computer vision tasks		
CLR-3 :	The understand various recognition		
CLR-4 :	To get introduced to classical neural networks and machine learning basics		
CLR-5 :	To understand deep learning techniques for computer vision tasks		
CLR-6 :	Application specific deep learning networks		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom) Expected Proficiency (%) Expected Attainment (%)	Engineering Knowledge Problem Analysis Design & Development Analysis, Design, Research Modern Tool Usage Society & Culture Environment & Sustainability Ethics Individual & Team Work Communication Project Mgt. & Finance Life Long Learning PSO - 1 PSO - 2 PSO - 3
CLO-1 :	To be able to appreciate the mathematics of basic computer vision principles	3 80 75	H H M L L - - - L L - L H M -
CLO-2 :	To be able to understand the active computer vision techniques and shape from focus	3 85 80	H H M M L - - - M L - L H M -
CLO-3 :	To be able to comprehend clustering and segmentation methods	2 70 65	H M L M L - - - M L - L H M -
CLO-4 :	To be able to understand recognition principles and basic mathematics of the same	2 75 70	H M M M M - - - M L - L H M -
CLO-5 :	To appreciate neural networks and deep neural networks based learning for computer vision tasks	2 85 80	H M M M M - - - M L - L H M -
CLO-6 :	To implement deep learning for common computer vision tasks	2 80 75	H M M M M - - - L L - L H M -

	Shape From Focus and Active Methods	Segmentation	Recognition	Deep Learning	Augmented Reality and Mixed Reality
Duration (hour)	8	10	7	10	10
S-1	SLO-1 Modelling image focus	Introduction to segmentation	Introduction to recognition	Convolutional neural networks	The Reality–Virtuality continuum
	SLO-2 Modelling image focus	Types	Challenges and approaches	Convolution, pooling	The Reality–Virtuality continuum
S-2	SLO-1 Shape from focus	Introduction to clustering	K-nearest neighbor algorithm	Activation functions, initialization	Virtual, augmented and mixed reality, an historical perspective
	SLO-2 Principle and hardware required	Methods relevant to computer vision	Principle and underlying mathematics	Dropout, batch normalization	Industrial applicability of virtual, augmented and mixed reality
S-3	SLO-1 Focus measures	Agglomerative clustering	Numerical problem solving for a sample recognition using K-nearest	Deep learning hardware	Design and implementation of an immersive user experience
	SLO-2 Scene reconstruction	Principle and underlying mathematics	Numerical problem solving for a sample recognition using K-nearest	CPU, GPU, TPU	Design and implementation of an immersive user experience
S-4	SLO-1 Active methods	Numerical problem on agglomerative clustering	Principal Component Analysis (PCA)	Tuning neural networks	The VR-AR-MR system architecture
	SLO-2 Comparison with passive techniques	Numerical problem on agglomerative clustering	Principle and underlying mathematics	Best practices	The VR-AR-MR system architecture
S-5	SLO-1 Laser triangulation	K-means clustering	Numerical problem solving for a sample recognition using PCA	Training neural networks	Tracking system
	SLO-2 Principle, working and specifications	Principle and underlying mathematics	Numerical problem solving for a sample recognition using PCA	Update rules, ensembles	Tracking system
S-6	SLO-1 Structured light reconstruction	Numerical problem on agglomerative clustering	Linear Discriminant Analysis (LDA)	Data augmentation	Visual, aural, and haptic display

	SLO-2	Principle, working and specifications	Numerical problem on agglomerative clustering	Principle and underlying mathematics	Transfer learning	Design principles
S-7	SLO-1	LIDAR	Mean-shift clustering	Numerical problem solving for a sample recognition using LDA	Popular CNN architectures For image classification	Usability guidelines
	SLO-2	Principle, working and specifications	Principle and underlying mathematics	Numerical problem solving for a sample recognition using LDA	Challenges addressed and novelty	Usability guidelines
S-8	SLO-1	Application case studies of active methods	Numerical problem on agglomerative clustering		Popular CNN architectures for object detection	Common Interaction Techniques for Mixed Reality
	SLO-2	Application case studies of active methods	Numerical problem on agglomerative clustering		Challenges addressed and novelty	Common Navigation Techniques
S-9	SLO-1		Introduction to classification		Applications of deep learning - semantic segmentation	Interaction design process
	SLO-2		Types, applications		Applications of deep learning or instance segmentation	Interaction design process
S-10	SLO-1		Linear classifiers		Applications of deep learning - activity understanding	Future of computer computer vision
	SLO-2		Implementation details		Types	Open problems

Learning Resources	<ol style="list-style-type: none"> 1. WileyForsyth and Ponce, <i>Computer Vision: A Modern Approach</i>, 2nd Edition, Pearson, 2015. 2. Ian Goodfellow and Yoshua Bengio and Aaron Courville, <i>Deep Learning</i>, 1st Edition, MIT Press, 2016. 3. Rafael C. Gonzales, Richard.E.Woods, "Digital Image Processing, 4th Edition, Pearson Education", 2018. 4. Emanuele Trucco, Alessandro Verri, "Introductory Techniques For 3D Computer Vision", 1st Edition, Prentice Hall, 1998. 5. Kharis O'Connell, "Designing Mixed Reality", 1st Edition, O' Reilly, 2016.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	30 %	-	30 %	-	30 %	-	20 %	-	40%	-
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	30%	-
Level 3	Evaluate Create	30 %	-	30 %	-	30 %	-	40 %	-	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

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Course Code	18MHE507T	Course Name	VISION GUIDED ROBOTICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18MHE505T - Computer Vision and Its Applications	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechatronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	To understand how computer vision aids in manipulator's guidance	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	To understand how computer vision aids in mobile robot's guidance	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	To get awareness about visual servoing techniques																		
CLR-4 :	To get awareness about visual slam and visual odometry																		
CLR-5 :	To gain knowledge about optical flow methods and their applications																		
CLR-6 :	To get to know about the advanced approaches in visual servoing																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	To be able to appreciate the various roles of computer vision in manipulator and mobile robotics	3	80	75	H	H	M	L	L	-	-	-	L	L	-	L	H	M	-
CLO-2 :	To be able to comprehend the basics mathematics of visual servoing architectures	3	85	80	H	H	M	M	L	-	-	-	M	L	-	L	H	M	-
CLO-3 :	To be able to appreciate the applications of computer vision for mobile robotics	2	70	65	H	M	L	M	L	-	-	-	M	L	-	L	H	M	-
CLO-4 :	To be able to implement optical flow methods to understand motion related features from images	2	75	70	H	M	M	M	M	-	-	-	M	L	-	L	H	M	-
CLO-5 :	To have the competency in developing tracking algorithms based on vision data	2	85	80	H	M	M	M	M	-	-	-	M	L	-	L	H	M	-
CLO-6 :	To be conversant in the futuristic approaches in visual servoing	2	80	75	H	M	M	M	M	-	-	-	L	L	-	L	H	M	-

		Introduction	Visual Servoing	Vision for Mobile Robots	Optical Flow and Tracking	Advanced Topics
Duration (hour)		8	10	10	10	7
S-1	SLO-1	Introduction to vision for Robotics	Mathematical formulation of visual servo problem	Introduction to simultaneous localization and mapping	Formulation of the motion analysis	Hybrid visual servoing, partitioned visual servoing
	SLO-2	Significance of vision as a external state sensing technology	Derivation	Visual SLAM (VSLAM)	Formulation of the motion analysis	Switching schemes in visual servoing
S-2	SLO-1	Vision for manipulators	Classification of visual servoing architectures	VSLAM Basics	Motion field of rigid objects	Joint space control of eye-in-hand
	SLO-2	Vision for mobile robots	Classification of visual servoing architectures	VSLAM Basics	Aperture problem	Joint space control of eye-in-hand
S-3	SLO-1	Modelling velocity of a rigid object	Image based visual servoing (IBVS)	VSLAM approaches	Optical flow	Joint space control of eye-to-hand systems
	SLO-2	Derivation	Interaction matrix derivation	VSLAM approaches	Motion field	Joint space control of eye-to-hand systems
S-4	SLO-1	Camera configurations in vision guided robots	Geometrical interpretation of IBVS	Introduction to visual odometry (VO)	Brightness constancy equation	Motion based segmentation
	SLO-2	Camera configurations in vision guided robots	Derivation	Introduction to visual odometry (VO)	Validity	Motion based segmentation
S-5	SLO-1	Triangulation	Stability analysis	VO - motion from image feature correspondences	Estimating motion field - differential techniques	Structure from motion (SFM)
	SLO-2	Derivation	Stability analysis	VO - motion from image feature correspondences	Estimating motion field - differential techniques	Multi-view SFM

S-6	SLO-1	Basic equation of triangulation	IBVS with stereo vision system – a case study	VO – motion from 3-D structure	Estimating motion field - feature based techniques	Retrieving 3-D structure
	SLO-2	Derivation	IBVS with stereo vision system – a case study	VO – motion from 3-D structure	Estimating motion field - feature based techniques	Retrieving 3-D structure
S-7	SLO-1	Vision based pose estimation	IBVS with other geometrical features	Comparison between VSLAM techniques	Target tracking	Motion from motion field
	SLO-2	Detailed description of any one approach	Direct estimation	VO calibration techniques	Challenges and solutions	Motion from motion field
S-8	SLO-1		Position based visual servoing	Application case study on VSLAM	Kalman filtering basics	
	SLO-2		Point feature based motion	Application case study on VSLAM	Kalman filtering basics	
S-9	SLO-1		Pose based motion	Application case study on VSLAM	Kalman tracking	
	SLO-2		Pose based motion	Application case study on VSLAM	Kalman tracking	
S-10	SLO-1		Calibration for visual servoing systems	Application case study on VO	Application case study on visual tracking	
	SLO-2		Calibration for visual servoing systems	Application case study on VO	Application case study on visual tracking	

Learning Resources	<ol style="list-style-type: none"> 1. WileyForsyth and Ponce, <i>Computer Vision: A Modern Approach</i>, 2nd Edition, Pearson, 2015. 2. Bruno Siciliano, Oussama Khatib, <i>Springer Handbook of Robotics</i>, 2nd Edition, Springer, 2016. 3. D. Scaramuzza and F. Fraundorfer, "Visual Odometry [Tutorial]," in <i>IEEE Robotics & Automation Magazine</i>, vol. 18, no. 4, pp. 80-92, Dec. 2011. 4. F. Fraundorfer and D. Scaramuzza, "Visual Odometry : Part II: Matching, Robustness, Optimization, and Applications," in <i>IEEE Robotics & Automation Magazine</i>, vol. 19, no. 2, pp. 78-90, June 2012.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	20 %	-	40%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	30%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	40 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

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Course Code	18MHE508T	Course Name	ADVANCED ROBOTICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	15MHE501T - Robotics	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechatronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Learn the concepts of singularity, statics and to compute dynamics of complex configuration	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Understand the concepts and challenges involved in multirobot systems	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Understand modeling of flexible robots	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Learn the complexities of wheeled mobile robot in uneven terrain	Expected Attainment (%)	Design & Development
CLR-5 :	Introduce the advanced concepts of robotics like cooperative robot, haptics and telerobotic systems		Analysis, Design, Research
CLR-6 :	get an understanding about the current state of the art research topics in robotics		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Understand the approaches to solve for singularity and dynamics of manipulator	2 80 70	H M M H M - - - - - H H - -
CLO-2 :	Learn the concept of multirobot systems and its research challenges	2 80 70	H H M H M - - - - - H H - -
CLO-3 :	Understand the modeling and control of flexible robots	2 80 70	H H M H M - - - - - H H - -
CLO-4 :	Understand mathematical concepts of defining the wheeled mobile robot in uneven terrain	2 80 70	H H H H M - - - - - H H - -
CLO-5 :	Learn the importance and complexities of cooperative robot, haptics and telerobotic systems	2 80 70	H H M H M - - - - - H H - -
CLO-6 :	Ability to address current advanced topics of research in the field of robotics	2 80 70	H H M H M - - - - - H H - -

Duration (hour)	Manipulator Robots	Multi Robot Systems	Modelling and control of flexible robots	Wheeled Mobile Robot	Advanced Topics
	8	7	10	8	12
S-1	SLO-1 Jacobian for serial manipulator	Architecture of multirobot systems	Introduction to flexible robots	Introduction to wheeled mobile robot (WMR)	Introduction to cooperative manipulators
	SLO-2 Numerical	History and application	Application	Two and three wheeled WMR on flat surfaces	Historical overview
S-2	SLO-1 Jacobian for parallel Manipulators	Communication	Models of flexible Links	Concepts of slip	Introduction to kinematics and statics
	SLO-2 Numerical	Example	Numerical	Slip Modelling	Example
S-3	SLO-1 Singularity analysis	Introduction to swarm robots	Models of flexible Joints	World and terrain models for natural environment	Dynamics and load distribution
	SLO-2 Loss and gain of degree of freedom	Example	Numerical	Model	Example
S-4	SLO-1 Statics and force transformation matrix for Stewart Gough platform	Heterogeneity	Kinematic Modelling of multilink flexible robots	Dynamic environments	Control of cooperative manipulator
	SLO-2 Derivation	Heterogeneity	Numerical	Example	Example
S-5	SLO-1 Singularity analysis of Stewart Gough platform	Task allocation and learning	Kinematic modelling of multilink flexible robots	WMR on uneven terrain	Overview of haptics
	SLO-2 Numerical Analysis	Case study	Numerical	Example	Importance
S-6	SLO-1 Introduction to recursive dynamics	Control challenges	Introduction to dynamics of flexible link manipulator	Design of slip free motion on uneven terrain	Haptic device design
	SLO-2 Numerical procedure	Communication for control of networked robots	Notations and terms	Design	Example
S-7	SLO-1 Dynamics of Stewart Gough platform	Communication for perception	Dynamic computation	Dynamics and static stability of three wheeled WMR on uneven terrain	Haptic rendering

	SLO-2	Numerical	Control for perception	Numerical	Numerical analysis	
S-8	SLO-1	Simulation and experimental case study on control of parallel manipulator		Control of flexible link manipulator	Case study of wheeled mobile robot on uneven terrain	Control and stability of haptic interfaces
	SLO-2	Case Study		Control equation	Case Study	Example
S-9	SLO-1			Numerical simulation for planar 2 link flexible manipulator		Introduction to tele robotic systems
	SLO-2			Simulation		Application
S-10	SLO-1			Simulation for planar 2 link flexible manipulator		Control architecture
	SLO-2			Simulation		Example
S-11	SLO-1					Bilateral control and force feedback
	SLO-2					Example
S-12	SLO-1					Communication and networking
	SLO-2					Example

Learning Resources	<ol style="list-style-type: none"> John J. Craig, "Introduction to Robotics Mechanics and Control", 3rd edition, Pearson, 2008. Mark W. Spong and M. Vidyasagar, "Robot Dynamics and Control", 2nd edition, Wiley India, 2008. J.P. Merlet, "Parallel Robots", 2nd edition, Springer, 2006. Siciliano, B., and Khatib, O. (Editors), Handbook of Robotics, 2nd edition, Springer, 2016. 	<ol style="list-style-type: none"> Robert J. Schilling, "Fundamentals of Robotics Analysis and Control", 5th edition, Prentice Hall of India, 2009. Mittal R.K., and Nagrath I.J., "Robotics and Control", 1st edition, Tata McGraw Hill, 2007. Fu K., Gonzalez R., and Lee C. S. G., "Robotics: Control, Sensing, Vision and Intelligence", 1st edition, McGraw Hill, 2008. Tsuneo Yohikwa, "Foundations of Robotics Analysis and Control", 2nd edition, MIT Press, 2003.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

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2. Mr. Mohammed Sagheer,Wabco Technology Center ,India, mohammedsagheer.musthafa@wabco-auto.com	2. Dr., P Karthikeyan, MIT,Anna University, pkarthikeyan@annauniv.edu	2. Dr.R. Senthilnathan, SRMIST

Course Code	18MHE509T	Course Name	APPLIED ROBOTICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechatronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Understand the various types of industrial, field and service robots and their characteristics and capabilities	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Equip with the knowledge of mathematical modeling of specialized robots	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Familiarize with the operation of robots and processes involved	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Select the right robot with required configurations and specifications for given applications	Expected Attainment (%)	Design & Development
CLR-5 :	Familiarize with the applications of various field and service robots		Analysis, Design, Research
			Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Recognize the various types of industrial, field and service robots and their characteristics and capabilities	2 75 70	H H L H L - - - - - H H H H
CLO-2 :	Develop mathematical modeling of specialized robots	3 75 70	H H M H H - - - - - H M M M
CLO-3 :	Familiarize with the operation of robots and processes involved	3 75 70	H H M H M - - - - - H M M M
CLO-4 :	Decide the right robot with required configurations and specifications for given applications	3 75 70	H H M H M - - - - - H M M M
CLO-5 :	Utilize the field and service robots for various applications	3 75 70	H H M H M - - - - - H M M M

Duration (hour)	Applications of Robots in Industries	Underwater and Aerial Robots	Field robots	Robots in Surgery and Rehabilitation	Entertainment and Personal Robots
	9	10	9	9	8
S-1	SLO-1 Introduction to Robotics- Overview of syllabus	Autonomous Underwater vehicles (AUV)	Forestry- Robot locomotion	Medical robotics- Introduction	Cleaning robots
	SLO-2 A short history of Industrial robots	Autonomous Surface Vehicles (ASV)	Forestry automation	core concepts- technology	Cleaning robots
S-2	SLO-1 Typical applications & robot configurations	Modeling of AUV	SLAM in forestry	Medical robotic systems	Lawn moving robots
	SLO-2 Typical applications & robot configurations	Modeling of AUV	Autonomous robots for silviculture and treatment	Medical robotic systems	Lawn moving robots
S-3	SLO-1 Robots in welding	Modeling of ASV	Broad acre Applications	Medical robotic systems-research areas and applications	Smart appliances and smart homes
	SLO-2 Robots in welding	Modeling of ASV	Automatic guidance- sowing weeding-spraying	Medical robotic systems-research areas and applications	Smart appliances and smart homes
S-4	SLO-1 Car body assembly & Painting	Sensor systems and actuation systems	Automatic guidance- sowing weeding-spraying	Rehabilitation and health care robotics-overview-	The role of robots in education
	SLO-2 Car body assembly & Painting	Motion control system -guidance and control	Broad-acre harvesting	Rehabilitation and health care robotics-overview-	Educational robotic platforms
S-5	SLO-1 Material transfer and automation	Challenges in Localization of AUV & ASV	Horticulture: picking of fruits	Physical therapy and training robots	Robots and informal learning venues
	SLO-2 Machining	Remotely operated vehicles (ROVs)	Horticulture: picking of fruits	Physical therapy and training robots	Robots and informal learning venues
S-6	SLO-1 Kinematics and mechanisms review	Remotely operated vehicles, types and applications	Robot milking-sheep shearing	Aids for people with disabilities	Social robots that interact with people
	SLO-2 Kinematics and mechanisms review	Gliders	slaughtering-livestock inspection	Aids for people with disabilities	Social robot embodiment

S-7	SLO-1	Tasks descriptions- teaching and programming	History of Unmanned aerial vehicles (UAV)	Robots in construction	Smart prostheses and orthoses	Multimodal Communication
	SLO-2	Tasks descriptions- teaching and programming	Different configurations of fixed and rotary wing aerial vehicles	Unsolved problems in construction- future directions	Smart prostheses and orthoses	Expressive emotion-based interaction
S-8	SLO-1	End-effectors	Kinematics and dynamics of quadcopter	Robots for hazardous applications- enabling technologies	Diagnosis and monitoring	Socio-cognitive skills
	SLO-2	End-effectors and System integration	Modeling of Quad rotor aerial vehicle	Search and rescue robots	Diagnosis and monitoring	Promising robots- open issues
S-9	SLO-1	Challenges in system integration	Overall Control system for UAVs	Disaster characteristics and impact on robots	Open challenges in using robots in medical applications	
	SLO-2	Approaches to system integration	Guidance and Navigation of UAV	Robots actually used at disaster	Future directions	
S-10	SLO-1		Applications of UAVs			
	SLO-2		Applications of UAVs			

Learning Resources	<ol style="list-style-type: none"> 1. Bruno Siciliano, Oussama Khatib, "Handbook of Robotics", 2nd Edition, Springer, 2016. 2. Yangsheng Xu Huihuan Qian Xinyu Wu, "Household and service robots", 1st edition, Elsevier Ltd, 2015 3. Aleksandar Lazinica, "Mobile Robots Towards new applications", 1st edition, Advanced Robotic Systems International, 2006 4. Gregory Dudek, Michael Jenkin, "Computational Principles of Mobile Robotics", 2nd Edition, Oxford University Press, 2010 5. L Marques, A de Almeida, M o Tokhi, G SVirk, "Advances in Mobile Robotics", 1st edition, World Scientific Publishing Co. Pte. Ltd. 2008
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Understand	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Analyze	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. Guna Surendra, Gossamsetti, Hitachi, Japan. surendra.gossamsetti.bu@hitachi.com	1. Dr. R. Thiyagarajan, IIT Madras, thiyaguilm@gmail.com	1. Mr. K. Sivanathan, SRMIST
2. Mr. Visweswaran Jagadeesan, National Instruments. visweswaran.jagadeesan@ni.com	2. Dr. P. Karthikeyan, MIT Campus, Anna University, pkarthikeyan@annauniv.edu	2. Mr. Ranjit Pillai, SRMIST

Course Code	18MHE510T	Course Name	PLANNING AND DECISION MAKING IN ROBOTICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechatronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:		Learning			Program Learning Outcomes (PLO)														
				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-1 :	To understand the mathematical foundations of planning algorithms			Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-2 :	To get awareness of various algorithms used in localization of mobile robots						H	H	M	L	L	-	-	-	L	L	-	L	H	M	-
CLR-3 :	To get exposed to common algorithmic strategies for path planning of mobile robots						H	H	M	M	L	-	-	-	M	L	-	L	H	M	-
CLR-4 :	To get an understanding of motion control algorithms required for autonomous vehicles						H	M	L	M	L	-	-	-	M	L	-	L	H	M	-
CLR-5 :	To get awareness of strategies to simultaneously localize and map the environment						H	M	M	M	M	-	-	-	M	L	-	L	H	M	-
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																			
CLO-1 :	Comprehend the mathematical foundations of localization and path planning algorithms			3	80	75															
CLO-2 :	Implement localization algorithms based on probabilistic and optimal state estimation			3	85	80															
CLO-3 :	Appreciate practical aspects of implementation of motion control algorithms for autonomous vehicles			2	70	65															
CLO-4 :	Develop path planning algorithms for local and global path planning			2	75	70															
CLO-5 :	Implement algorithms for simultaneous localization and mapping			2	85	80															

Introduction		Localization		Control		Optical Flow and Tracking		Advanced Topics	
Duration (hour)	8	10	10	10	10	10	7		
S-1	SLO-1	Review of probability theory	Markov localization	Robot Motion	Motion planning	Motion planning	Introduction to SLAM		
	SLO-2	Uniform distribution	Formulation, advantages and limitation	Smoothing Algorithm	Global and local path planning	Global and local path planning	Problem definition and Mathematical basis		
S-2	SLO-1	Probability after sense	Numerical problem for Markov localization	Path Smoothing	Motivation and challenges	Motivation and challenges	Taxonomy of SLAM problem		
	SLO-2	Normalize distribution	Numerical problem for Markov localization	Zero Data Weight	Approaches	Approaches	SLAM Paradigms		
S-3	SLO-1	Phit and Pmiss	Introduction to optimal state estimation problem	PID control	A* star search	A* star search	Extended Kalman Filter (EKF) SLAM		
	SLO-2	Sum of probabilities	State estimator for localization	Implementation aspects of proportional control	Numerical example	Numerical example	Mathematical basics		
S-4	SLO-1	Sense function	Gaussian introduction	Implementation aspects of integral control	D* lite search	D* lite search	Numerical example for EKF		
	SLO-2	Exact motion	Variance comparison	Implementation aspects of derivative control	Numerical example	Numerical example	Numerical example for EKF		
S-5	SLO-1	Move function	Maximize Gaussian	Systematic Bias	Expansion grid	Expansion grid	Introduction to particle filters		
	SLO-2	Bayes rule	Measurement and motion	Systematic Bias	Numerical example	Numerical example	Introduction to particle filters		
S-6	SLO-1	Theorem of total probability	Parameter update	PID Tuning for autonomous mobile systems	Dynamic programming	Dynamic programming	Mathematical formulation of particle filter in the context of SLAM		
	SLO-2	Numerical problems	New mean variance	PID Tuning for autonomous mobile systems	Numerical example	Numerical example	Mathematical formulation of particle filter in the context of SLAM		

S-7	SLO-1	Introduction to localization	Gaussian motion	Parameter optimization	Vector field histogram	Fast SLAM
	SLO-2	Types and Challenges	Kalman filter pseudocode	Parameter optimization	Numerical example	Fast SLAM for point landmark example
S-8	SLO-1	Belief Representation	Kalman prediction		Selection of global and local path planning algorithms	Derivation
	SLO-2	Types and comparison	Kalman prediction		Application case study	Real world challenges and examples
S-9	SLO-1	Map representation	Kalman filter design			Application case study for EKF based SLAM
	SLO-2	Types	Kalman filter design			Application case study for EKF based SLAM
S-10	SLO-1	Types and comparison of map representation strategies	Kalman matrices			Application case study for Particle Filter based SLAM
	SLO-2	Types and comparison of map representation strategies	Sensor fusion using Kalman filter			Application case study for Particle Filter based SLAM

Learning Resources	<ol style="list-style-type: none"> 1. Bruno Siciliano, Oussama Khatib, Springer Handbook of Robotics, 2nd Edition, Springer, 2016. 2. Siegwart, Nourbakhsh, "Introduction to Autonomous Mobile Robots", 2nd Edition, MIT Press, 2011. 3. Perter Corke, "Robotics, Vision and Control", 2nd Edition, Springer, 2017.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	20 %	-	40%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	30%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	40 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. N. Ganesh Ram, Intel Labs, ganeshram.nandakumar@intel.com	1. Dr. R. Thiyagarajan, IIT Madras, thiyaguiitm@gmail.com	1. Dr. R. Senthilnathan, SRMIST
2. Mr. Mohammed Sagheer, Wabco Technology Center, mohammedsagheer.musthafa@wabco-auto.com	2. Dr. P. Karthikeyan, MIT Campus, Anna University, pkarthikeyan@annauniv.edu	2. Mr. K. Sivanathan, SRMIST

Course Code	18MHE511T	Course Name	ARTIFICIAL INTELLIGENCE FOR ROBOTICS AND VISION	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechatronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Obtain motivation for artificial intelligence and machine learning in robotics and vision	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Appreciate the mathematics behind artificial intelligence	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Understand the idea behind fuzzy logic for decision making	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Understand the basics neural networks and deep learning philosophy	Expected Attainment (%)	Design & Development
CLR-5 :	Get exposed to convolutional neural networks and its applications to vision guided robotics tasks		Analysis, Design, Research
CLR-6 :	get awareness of deep neural networks for sequence modelling and reinforcement learning		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Formulate the mathematical basics of fuzzy and neural networks	3 80 75	H H M L L - - - L L - L H M -
CLO-2 :	Apply fuzzy logic problems to robotics applications	3 85 80	H H M M L - - - M L - L H M -
CLO-3 :	Develop neural networks for simple classification tasks	2 70 65	H M L M L - - - M L - L H M -
CLO-4 :	Exhibit conversant skill and knowledge with deep learning philosophy and training concepts	2 75 70	H M M M M - - - M L - L H M -
CLO-5 :	Implement convolutional neural networks for simple computer vision tasks	2 85 80	H M M M M - - - M L - L H M -
CLO-6 :	Implement deep recurrent neural networks and reinforcement network for simple robot guidance tasks	2 80 75	H M- M M M - - - L L - L H M -

		Introduction	Fuzzy Logic	Classical Neural Networks	CNN	RNN and Reinforcement Learning
	Duration (hour)	8	10	10	8	10
S-1	SLO-1	Introduction to artificial intelligence (AI)	Introduction to Fuzzy sets	Overview of biological neuro-system	Conventional neural networks vs. Deep learning in the context of computer vision	Unfolding computational graphs
	SLO-2	Intelligent agent	Classical and Fuzzy sets	Mathematical models of neurons	Support vector machine	Unfolding computational graphs
S-2	SLO-1	Categorization of AI	Overview of classical sets	ANN architecture	Numerical example	Recurrent neural networks
	SLO-2	Overview of different forms of learning	Membership function	Learning rules	Softmax	Deep recurrent networks
S-3	SLO-1	Overview of different forms of learning	Fuzzy rule generation	Learning paradigms	Numerical example	Long Short Term Memory (LSTM)
	SLO-2	Statistical decision theory	Fuzzy rule generation	Supervised, unsupervised semi-supervised and reinforcement Learning	Numerical example	Long Short Term Memory
S-4	SLO-1	Regression	Operations on fuzzy sets	Multi-layer perceptrons	Convolutional neural networks	Autoencoders
	SLO-2	Regression	Numerical examples	Multi-layer perceptrons	Convolution, pooling	Applications of autoencoders
S-5	SLO-1	Numerical problems	Fuzzy Arithmetic	Numerical problems based on perceptron	Activation functions	Reinforcement learning numerical example
	SLO-2	Numerical problems	Numerical examples	Numerical problems based on perceptron	Initialization	Reinforcement learning numerical example
S-6	SLO-1	Evaluation of learning algorithms and cross-validation	Fuzzy Logic	Backpropagation	Deep learning hardware	Deep reinforcement learning, Motivation
	SLO-2	Evaluation of learning algorithms and cross-validation	Fuzzification	Backpropagation	CPU, GPU, TPU	Examples for reinforcement learning

S-7	SLO-1	Applications of AI in robotics	Fuzzy sets	Numerical problems for back propagation	Best practices in training	Markov decision process
	SLO-2	Applications of AI in robotics	Defuzzification	Numerical problems for back propagation	Training neural networks	Major components of RL
S-8	SLO-1		Application case study for manipulator robotics application	Introduction of neuro-fuzzy systems	Data augmentation	Q-learning
	SLO-2		Application case study for manipulator robotics application	Introduction of neuro-fuzzy Systems	Transfer learning	Numerical example
S-9	SLO-1		Application case study for mobile robotics application	Architecture of neuro-fuzzy Networks		Deep Q-learning (DQN)
	SLO-2		Application case study for mobile robotics application	Architecture of neuro-fuzzy Networks		DQN training, best practices
S-10	SLO-1			Numerical example for neuro-fuzzy system		Application case study for deep reinforcement learning
	SLO-2			Numerical example for neuro-fuzzy system		Application case study for deep reinforcement learning

Learning Resources	<ol style="list-style-type: none"> 1. Bruno Siciliano, Oussama Khatib, "Handbook of Robotics", 2nd Edition, Springer, 2016 2. Ian Goodfellow and Yoshua Bengio and Aaron Courville, "Deep Learning", 1st Edition, MIT Press, 2016. 3. Simon Haykin, "Neural Networks and Learning Machines: A Comprehensive Foundation", 3rd Edition, Pearson, 2011. 4. Timothy J Ross, "Fuzzy Logic with Engineering Applications", 3rd Edition, Wiley, 2011.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	20 %	-	40%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	30%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	40 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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2. Mr. Mohammed Sagheer, Wabco Technology Center, mohammedsagheer.musthafa@wabco-auto.com	2. Dr. P. Karthikeyan, MIT Campus, Anna University, pkarthikeyan@annauniv.edu	2. Mr. K. Sivanathan, SRMIST

Course Code	18MHE512T	Course Name	SYSTEMS ENGINEERING AND MANAGEMENT FOR ROBOTICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechatronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand the foundations of systems engineering	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Recognize the conflicting requirements of modern engineering systems like robots and their life cycle stages through some relevant case studies and appreciate the need for system engineering	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Gain sound knowledge on technical ,management, organizational and tailoring processes involved in system engineering and their analysis																		
CLR-4 :	Comprehend the cross-cutting system engineering methods and activities																		
CLR-5 :	Apply the knowledge of system engineering to solve the problems associated with complex engineering systems																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Familiarize the foundations of systems engineering	2	75	70	H	H	M	H	M	-	M	-	-	-	-	H	H	H	H
CLO-2 :	Identify the conflicting requirements of modern engineering systems and their life cycle stages	3	75	70	H	H	M	H	M	-	M	-	-	-	-	H	M	M	M
CLO-3 :	Acquire knowledge on technical ,management, organizational and tailoring processes involved in system engineering	3	75	70	H	H	M	H	M	-	M	M	-	-	M	H	M	M	M
CLO-4 :	Realize the cross-cutting system engineering methods and activities	3	75	70	H	H	M	H	M	-	M	M	-	-	M	H	M	M	M
CLO-5 :	Apply the knowledge of system engineering to solve the problems in robotics and other complex engineering systems	3	75	70	H	H	M	H	H	-	M	M	-	-	M	H	M	M	M

	Foundations of Systems Engineering (SE) and Life Cycle Stages	Technical Process of Systems Engineering	Management Process of Systems Engineering	Organizational and Tailoring Processes and Applications of System Engineering	Cross-cutting SE Methods and Activities
Duration (hour)	9	9	9	9	9
S-1	SLO-1	Introduction, definition and concepts of systems	Business or Mission Analysis Process	Project planning process	Life cycle model management process
	SLO-2	The hierarchy within a system	Stakeholder needs and requirements	Project assessment and control process	Infrastructure management process
S-2	SLO-1	Definition of systems of systems	System requirements Definition Process	Decision management process	Portfolio management process
	SLO-2	Enabling systems and definition of Systems Engineering(SE)	System requirements Definition Process	Decision management process	Human resource management process
S-3	SLO-1	Origins and Evolution of system engineering	Architecture definition process	Risk management process	Quality management process
	SLO-2	Use and value of system engineering	Architecture definition process	Risk management process	Knowledge management process
S-4	SLO-1	System science and system thinking	Design definition process	Configuration management process	Tailoring process
	SLO-2	System engineering leadership and professional development	Design definition process	Configuration management process	Tailoring process
S-5	SLO-1	Introduction to Life cycle and its characteristics	System analysis process	Information management process	Tailoring for Automotive systems, Biomedical and healthcare systems
	SLO-2	Life cycle stages	Implementation process	Information management process	Tailoring for defense and aerospace systems
S-6	SLO-1	Life cycle approaches	Integration process	Measurement Process	Tailoring for infrastructure systems
	SLO-2	Life cycle approaches	Verification process	Measurement Process	Tailoring for space systems and ground transportation systems

S-7	SLO-1	Deciding what is best for organization, project or team	Transition process	Quality assurance process	Application of SE for product line management	Environmental /impact analysis, interoperability analysis
	SLO-2	Case study-1 Design for safety-Radiation therapy	Validation process	Quality assurance process	Application of SE for product line management	Logistics, manufacturing and producibility analysis
S-8	SLO-1	Case study-2 Need for prototyping system-Super high speed train in China	Operation process	Agreement process-introduction	Application of SE for services	Reliability and maintainability
	SLO-2	Case study -3 Cyber security considerations-The stuxnet attack	Maintenance process	Acquisition process	Application of SE for services	Resilience engineering
S-9	SLO-1	Case study-4 Design for maintainability-Incubators	Disposal process	Acquisition process	Application of SE for Enterprises	System safety and security engineering
	SLO-2	Concluding remarks on necessity of SE by relating to the above case studies	Concluding remarks on technical process	Supply process	Application of SE for small and micro enterprises	Value engineering

Learning Resources	<ol style="list-style-type: none"> David D.Walden, Garry J.Roelder, Kevin J.Forsberg, R.Douglas Hamelin, Thomas M.Shortell., "INCOSE Systems Engineering Handbook- A Guide for System Life Cycle Processes and Activities", 4th Edition, Wiley, 2015 Kossiakoff, A. Sweet, Seymour, S., W.N., Biemer, S.M., "Systems Engineering Principles and Practice", 2nd Edition, John Wiley & Sons, 2011. Charles S.Wassen., "System Engineering Analysis, Design and Development" Wiley, 2016. Blanchard, B.S. and Fabrycky, W.J., "Systems Engineering and Analysis", 4th Edition, Prentice Hall, 2005. Zeigler, B.P., H. Praehofer, T.G. Kim., "Theory of Modeling and Simulation", 2nd Edition, Academic Press, 2000.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Elayaraj Sivaraj, Tesla, California, elayaraj@hotmail.com	1. Dr. Manivannan P V, Indian Institute of Techonology, Chennai, pvm@iitm.ac.in	1. Mr. K.Sivanathan, SRMIST
2. Mr. Visweswaran Jagadeesan , National Instruments, Bangalore visweswaran.jagadeesan@ni.com	2. Dr. D. Sathia Narayanan, National Institute of Ocean Technology, Chennai, sathianarayanan@niot.res.in.	2. Dr.R.Senthilnathan, SRMIST

ACADEMIC CURRICULA

Professional Elective Courses

NANOTECHNOLOGY

Regulations - 2018



SRM INSTITUTE OF SCIENCE AND TECHNOLOGY

(Deemed to be University u/s 3 of UGC Act, 1956)

Kattankulathur, Kancheepuram, Tamil Nadu, India

Course Code	18NTE301T	Course Name	CARBON NANOTECHNOLOGY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Nanotechnology	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Acquire knowledge various forms of carbon	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Understands the use of carbon forms in applications	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Understands the physical and chemical properties of fullerenes	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Understands the physical and chemical properties of graphene	Expected Attainment (%)	Design & Development
CLR-5 :	Understands the physical and chemical properties of carbon nanotubes		Analysis, Design, Research
CLR-6 :	Acquire knowledge about various synthesis forms		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Analyze the geometry of various carbon nanostructures	2 80 75	H H H H M M M H H H M H H H H
CLO-2 :	Differentiate the structure and properties of different carbon nanostructure	2 80 70	H H M M M M M H M H M H M M M M
CLO-3 :	Elucidate the uses of Fullerenes, Carbon nanotubes and Graphene in different applications	2 75 70	H M H H M H H M H H H H H H H
CLO-4 :	Analyze the geometry of various carbon nano tubes	2 80 75	M H H M H H H H H H M H H H H
CLO-5 :	Analyze the various synthesis and characterization techniques of carbon nanostructures	2 80 70	H H H H H M M H M H M H H H H
CLO-6 :	Demonstrate the applications of carbon nanostructures	2 80 75	H M M H M M M H H H M H H M H

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Introduction	Fullerenes	Carbon Nanotubes	Graphene
	SLO-2	Carbon molecules	Structure of fullerenes	Structure of Carbon Nanotubes	Structure of Graphene
S-2	SLO-1	Nature of carbon bond	Bonding of fullerenes	Nomenclature of Carbon Nanotubes	Synthesis of Graphene
	SLO-2	New carbon structures	Nomenclature	Electronic properties of Carbon Nanotubes (CNTs)	Characterization of Graphene
S-3	SLO-1	Discovery of C60	C60 and higher fullerenes	Synthesis of Single Wall CNTs (SWCNTs)	Properties of Graphene
	SLO-2	Structure of C60	Growth mechanisms	Production of SWCNTs	Electrical properties of Graphene
S-4	SLO-1	C60 crystal	Production	Synthesis of Multi Wall CNTs (SWCNTs)	Magnetic properties of Graphene
	SLO-2	From graphene sheet to a nanotube	Purification	Production of MWCNTs	Band structure of Graphene
S-5	SLO-1	Single wall and multi walled nanotubes	Fullerene preparation by pyrolysis of hydrocarbons	Growth mechanism of CNTs	Phonon modes in Graphene
	SLO-2	Zigzag nanotubes	Partial combustion of hydrocarbons	Analysis of Carbon Nanotubes by X-ray diffraction	Raman modes in Graphene
S-6	SLO-1	Armchair nanotubes	Physical properties	Analysis of carbon nanotubes by Raman Spectroscopy	Layer dependence of Raman spectra
	SLO-2	Chirality in nanotubes	Chemical properties	Carbon nanotubes as Transistors	Raman spectroscopy of Graphene under strain

S-7	SLO-1	Structure of defective nanotubes	Hydrogenation	Carbon nanotubes as Field Effect Transistors (FET)	Infrared spectroscopy of Graphene	Amorphous carbon thin films
	SLO-2	Bonding of defective nanotubes	Applications of fullerenes	Carbon nanotubes as sensors	X-Ray diffraction of Graphene	Amorphous carbon films (a:C)
S-8	SLO-1	Cylindrical nanotubes	Fullerenes in solar cell	Carbon nanotubes as bio-sensors	EELS of Graphene	Hydrogen amorphous carbon films (a:C-H)
	SLO-2	Euler's theorem	Fullerenes as donor systems	Carbon nanotubes as gas sensors	Graphene in solar cell applications	Physical properties of amorphous carbon film
S-9	SLO-1	Euler's theorem in cylindrical nanotubes	Fullerenes as acceptor systems	Carbon nanotubes in dye degradation	Graphene as gas sensors	Chemical properties of amorphous carbon film
	SLO-2	Euler's theorem in defective nanotubes	Fullerenes as chemical sensors	Carbon nanotubes in photo-catalytic activities	Graphene in dye degradation (photo-catalytic activities)	Amorphous carbon film as anti-reflection and anti-corrosive coatings

Learning Resources	1. Anke Krueger, "Carbon Materials and Nanotechnology", Wiley-VCH, 2010 2. Yury Gogotsi, "Carbon Nanomaterials", Taylor and Francis, Second edition, 2014 3. C. N. R. Rao, Ajay K. Sood, "Graphene: Synthesis, Properties, and Phenomena"- Wiley- VCH, 2013	4. Wonbong Choi, Jo-won Lee, "Graphene: Synthesis and Applications" CRC Press, Taylor and Francis, 2012
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. D.K. Aswal, National Physical Laboratory, dkaswal@nplindia.org	1. Dr. V. Subramaniam, IIT Madras, manianvs@iitm.ac.in	1. Dr. M.Navaneethan, SRMIST
2. Dr. S. Sudhakar, CSIR-CECRI, sudhakar@cecri.res.in	2. Dr. S. Balakumar, University of Madras, balakumar@iunom.ac.in	2. Dr. E. Senthil Kumar, SRMIST

Course Code	18NTE302T	Course Name	PHYSICS OF SOLID STATE DEVICES	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Nanotechnology	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 : Get knowledge in the design and working principle of solid state devices		1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 : Understand the physics of p-n junction			
CLR-3 : Familiarize with the concept of metal/semiconductor junctions and semiconductor heterojunctions			
CLR-4 : Describe the operation of basic semiconductor diodes			
CLR-5 : Understand the theory of various types of transistors			
CLR-6 : Acquire knowledge on the materials and working of solid-state optoelectronic devices like LEDs, Solar cells, Photodetectors, Lasers, etc			

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 : Realize importance of semiconducting materials and p-n junction for development of solid state devices		2	80	75	H	H	H	H	H	H	H	H	H	H	M	H	H	H	H
CLO-2 : Use knowledge of physics to understand the working of semiconductor devices		2	80	70	H	H	H	H	M	M	M	H	H	H	L	H	M	M	M
CLO-3 : Develop analytical approaches to understand semiconductor devices		2	75	70	H	L	H	H	H	H	H	H	H	M	M	H	H	H	H
CLO-4 : Develop in depth understanding on the principle of working of different solid state devices		2	80	75	H	H	H	H	M	M	H	H	H	H	M	H	H	H	H
CLO-5 : Distinguish the design principles of various solid state devices		2	80	70	H	M	H	H	M	M	H	H	H	H	L	H	H	H	H
CLO6: Design two-terminal and three-terminal electronic devices		2	80	70	H	H	H	H	M	M	M	H	H	H	L	H	M	M	M

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Concept of p-n junction	Understand what a metal-semiconductor contact is.	Study fundamentals of BJT operation	Principle and types of field-effect transistors	Understand optical generation of carriers in a p-n junction
	SLO-2 Physics of the p-n junction formation	Qualitative characteristics of energy band formation	Operation modes of a BJT	Principle of operation of JFET	Types of Photodiodes
S-2	SLO-1 Energy band diagram of a p-n junction	Understand the ideal junction properties	Understand the structure and working of p-n-p and n-p-n transistors	Concept of pinch-off and saturation	Solar radiation and ideal conversion efficiency of a solar cell
	SLO-2 Estimation of the electric field, electric potential, and built-in potential	Theoretical considerations in estimating the barrier height	Band diagram and static characteristics	Derive I-V characteristics of JFET	Physics of solar cell
S-3	SLO-1 Depletion approximation and estimation of space charge width	Nonideal effects on the barrier height	Factors involved in transistor amplification	GaAs epitaxial layers for MESFET – Principle of working	Device configuration and technology roadmap, solar cell materials
	SLO-2 Depletion layer capacitance and its estimation	Qualitative explanation of image-force-induced lowering of the potential barrier	BJT fabrication	Concept of high-electron mobility transistors - III-V semiconductor materials	Familiarize with the solar cell parameters and efficiency calculation
S-4	SLO-1 Linearly graded junction in thermal equilibrium	Current transport processes in metal-semiconductor contacts	Analysis of minority carrier distribution	Basic working and fabrication of MOSFET	Design principle of photodetector
	SLO-2 Arbitrary doping profile and understanding the doping profile from $1/C^2$ -V plot	Comparison of the Schottky barrier diode and the p-n junction diode	Solution of the diffusion equation in the base region	Knowledge on modes of operation and short channel MOSFET	Types of photodetectors and characteristics
S-5	SLO-1 Qualitative description of charge flow in a p-n junction	Metal-semiconductor Ohmic contacts	Evaluation of the terminal currents	Short channel effects in MOSFET	How light-emitting diodes work?
	SLO-2 Ideal current-voltage characteristics of a p-n junction	Concept of ideal nonrectifying and tunneling barriers	Non ideal effects in BJT	Advanced MOSFET structures	Basic device structure and the concept of radiative recombination

S-6	SLO-1	Derivation of Shockley equation (ideal diode equation)	Methods to experimentally measure the barrier height	Deviations from the basic theory and indicate situations in which each effect is important	Metal Gate-High-k and Enhanced Channel Mobility Materials and Strained Si FETs	Materials of choice and technology roadmap
	SLO-2	Generation-recombination process and its effect	Current-voltage and capacitance-voltage measurements	The physical mechanisms of the current gain limiting factors	Complementary MOS structure and its formation	Specifications used in denoting the practical LED bulbs
S-7	SLO-1	Reverse bias breakdown mechanisms in a pn junction	Photoelectric measurements	The voltage breakdown mechanisms in a bipolar transistor	CMOS process integration	Physics of laser action
	SLO-2	Zener and Avalanche breakdown	Figure of merit of ohmic contacts and its determination, the concept of specific contact resistance	The current-limiting factors from the current components in the transistor	Concept of modulation doping in HEMT	Gain knowledge of stimulated emission and population inversion
S-8	SLO-1	Transient behavior of a p-n junction	Isotype and anisotype semiconductor heterojunctions - energy band diagrams	Frequency limitations of transistors	Basic device structure of AlGaAs/GaAs HEMT and I-V characteristics	Fabrication of p-n junction laser
	SLO-2	Concept of Noise in semiconductor devices	Current density equations and physical interpretation	The voltage breakdown mechanisms in a bipolar transistor	Output characteristics and channel related phenomenon	Emission spectra
S-9	SLO-1	Terminal functions of a p-n junction diode, The concept of tunnel diode	Introduction to two-dimensional electron gas	Heterojunction BJT	Dynamic effects in MOS capacitors – The Charge-coupled device	Familiarize with the structure and need of heterojunction lasers
	SLO-2	p-n junction as rectifier, Zener diode, Varistor, and Varactor	Concept of quantum well and superlattice structures	Schottky and Photo transistors	Basic CCD structure and its applications	Materials for semiconductor lasers and quantum cascade lasers

Learning Resources	1. S M Sze, Kwok k. Ng, "Physics of semiconductor devices" – John Wiley & Sons, Inc., 2007 2. Ben G. Streetman, Sanjay Kumar Banerjee, "Solid State Electronic Devices", Pearson Education Ltd, 2016	3. Donald A. Neamen, "Semiconductor Physics and Devices: Basic Principles" – McGraw Hill, Fourth Edition, 2011.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. D.K. Aswal, National Physical Laboratory, dkaswal@nplindia.org	1. Prof. M.S. Ramachandra Rao, IITM Chennai, msrrao@iitm.ac.in	1. Dr. S. Chandramohan, SRMIST
2. Dr. S. Sudhakar, CSIR-CECRI, sudhakar@cecri.res.in	2. Prof. T. Som, Institute of Physics, tsom@iopb.res.in	2. Dr. E. Senthil Kumar, SRMIST

Course Code	18NTE303T	Course Name	MOLECULAR SPECTROSCOPY AND ITS APPLICATIONS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Nanotechnology	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Acquire the knowledge in the basic concepts of interaction of radiation with matter and rotational spectroscopy	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Comprehend the principles of vibrational spectroscopy	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Understand the principles and techniques involved in of Raman scattering				H	M	H	H	M	M	M	H	M	H	M	H	M	M	M
CLR-4 :	Emphasize the significance of various techniques in electronic spectroscopy				H	M	M	H	H	M	M	M	M	H	H	H	H	H	H
CLR-5 :	Expose to concepts and applications of magnetic resonance				M	H	M	M	H	H	H	H	H	M	H	H	H	H	H
CLR-6 :	Focus on relevant theory, concepts, and techniques for understanding the spectrum of molecules				H	M	M	H	H	M	M	H	M	H	M	H	H	H	H
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:				H	M	M	H	H	M	M	H	H	H	M	H	H	M	H
CLO-1 :	Interpret the processes of absorption and radiation and analyse the rotational motion in molecules	2	80	75															
CLO-2 :	Analyze the vibrational spectra of diatomic and polyatomic molecules	2	80	70															
CLO-3 :	Analyze the Raman spectra and various non-linear Raman techniques	2	75	70															
CLO-4 :	Elucidate the various optical processes involved in the electronic spectra.	2	80	75															
CLO-5 :	Apply the concept magnetic resonance in chemical analysis and structure determination.	2	80	70															
CLO-6 :	Critique the applicability of a spectroscopic approach in the analysis of a molecular structure	2	80	75															

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Electromagnetic spectrum, spectral regions	Vibrational energy of a diatomic molecule	Born oppenheimer approximation	Quantum theory of Raman scattering
	SLO-2	Types of molecular energies	Classical approach	Vibrational coarse structure	Classical theory of Raman scattering
S-2	SLO-1	Interaction of light with matter	Wave mechanical approach	Band system and vibrational transitions	Rotational Raman spectra
	SLO-2	Methods of obtaining a spectrum, components of a spectrometer	Morse curve and energy levels of a diatomic molecule	Progressions and sequences	Vibrational Raman spectra
S-3	SLO-1	Spectral line width and broadening of spectral lines	Selection rules for vibration	Franck condon principle	Mutual exclusion principle
	SLO-2	Intensity of spectral lines	Fundamental overtones and hotbands in the vibrational spectrum	Intensity of vibrational electronic spectra	Polarization of Raman scattered light
S-4	SLO-1	Absorption and emission of radiation	Accidental degeneracy	Rotational fine structure	Raman spectrometer
	SLO-2	Spontaneous and stimulated processes	Diatomic vibrating rotator	Assignment of bands in a fine structure	Analysis of Raman spectra
S-5	SLO-1	Einstein's co-efficients and its derivation	Selection rules for vibration-rotation	Dissociation energy and dissociation products	Structure determination using Raman spectroscopy
	SLO-2	Laser as a spectroscopic light source	Vibrations of polyatomic molecules	Predissociation	Raman investigation of phase transitions
S-6	SLO-1	Classification of molecules based on moment of inertia	Normal vibrations of CO ₂ and H ₂ O molecules	Electronic absorption spectra	Resonance Raman scattering

	SLO-2	Rotational spectra of rigid diatomic molecules	Interpretation of IR spectra	Electronic angular momentum in diatomic molecules	Surface enhanced Raman scattering	Fourier transform NMR techniques
S-7	SLO-1	Rigid rotator	Group frequencies and various regions in IR spectrum	Dissipation of energy by excited molecule	Non-linear Raman phenomena-preliminaries	¹³ C NMR
	SLO-2	Isotope effect in rotational spectra, Intensity of rotational lines	Perturbation of group frequencies: mass effects	Jablonski diagram	Hyper Raman effect	Electron spin resonance
S-8	SLO-1	Non-rigid rotator	Perturbation of group frequencies: inductive effects	Phosphorescence	Stimulated Raman scattering	Resonance condition in Electron spin resonance (ESR)
	SLO-2	Vibrational excitation effect and Λ doubling	Fourier transform infrared spectroscopy: principle and interferometer arrangement	Fluorescence	Inverse Raman effect	ESR spectrometer
S-9	SLO-1	Microwave spectrometer	Elucidation of molecular structure using IR spectroscopy	Photoelectron spectroscopy: principle	Coherent Antistokes Raman scattering	Nuclear- electron spin coupling
	SLO-2	Applications of rotational spectroscopy	Identification of molecular constituents using IR spectroscopy	Photoelectron spectroscopy: instrumentation	Photo acoustic Raman scattering	Applications of ESR spectroscopy

Learning Resources	1. Peter Atkins, Julio de Paula Atkins, "Physical Chemistry", W. H. Freeman and Company, New York, 2010 2. Collin Barwell, Mc Cash, "Fundamentals of Molecular Spectroscopy", McGraw Hill publishing, 2001	3. G.Aruldas, "Molecular structure and spectroscopy", Prentice Hall, 2001 4. P.S.Sindhu, "Fundamentals of molecular spectroscopy" New age international publishers, 2006
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. D.K. Aswal, National Physical Laboratory, dkaswal@nplindia.org	1. Dr.G.Aravind, IIT Madras, garavind@iitm.ac.in	1. Dr. R.Annie Sujatha, SRMIST
2. Dr. Krishna Surendra Muvvala, Saint Gobain Research India, India, Krishna.muvvala@saintgobain.com	2. Dr. M. S. Ramachandra Rao, IIT Madras, msrao@iitm.ac.in	2. Dr. E.SenthilKumar, SRMIST

Course Code	18NTE304T	Course Name	NANOTRIBOLOGY	Course Category	E	Professional Elective Course	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Nanotechnology	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Acquire knowledge on nanotribology				Level of Thinking (Bloom)	2	80	75	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLR-2 :	Understand lubrication and related theories								Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3	
CLR-3 :	Gain insight on surfaces forces and its measurement techniques								H	M	H	H	H	M	M	H	H	M	M	H	H	M	M	M
CLR-4 :	Know about mechanisms involved in tribology related mechanical properties								H	M	H	H	H	H	M	H	H	H	M	M	H	H	H	H
CLR-5 :	Enhance the knowledge on friction and wear and their importance								H	H	M	M	M	H	H	H	H	M	M	H	H	H	M	M
CLR-6 :	Attain knowledge on tribological applications in day to day life								H	M	M	H	H	M	M	H	H	M	M	H	M	M	M	H
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1 :	Strong knowledge in the basic tribological concepts required for nanotechnology					2	80	75																
CLO-2 :	Identify, formulate, and solve engineering problem of interacting surfaces in relative motion					2	80	70																
CLO-3 :	Emphasize the knowledge of scientific disciplines in understanding tribological phenomenon					2	75	70																
CLO-4 :	Realize the significance of lubrication, friction and wear					2	80	75																
CLO-5 :	Familiar in the importance of modifying surface properties					2	80	70																
CLO-6 :	Utilize nanotribological principles for any applications					2	80	75																

Duration (hour)		9	9	9	9	9
S-1	SLO-1	History of tribology-origin	Surface Forces	Lubrication	Scale Effects in Mechanical Properties	Applications of Tribology
	SLO-2	Significance of micro/nanotribology	Methods used to study surface forces	Lubricant States	Nomenclature	Introduction to various tribological phenomenon
S-2	SLO-1	Tribology in design-Methods of solution of tribological problems	Force laws	Viscosity of lubricant	Yield strength and Hardness	Bio-Tribology
	SLO-2	Purpose of lubrication	Surface force apparatus (SFA)	Fluid film lubrication	Shear strength at the interface	Tribology in the human body
S-3	SLO-1	Modes of lubrication- hydrodynamic	Force between dry surface	Theories of hydrodynamics lubrication	Scale dependence on surface roughness and contact parameters	Tribology in the artificial organs
	SLO-2	Hydrostaticlubrication	Force between surfaces in liquid	Lubrication design of typical mechanical elements	Dependence of contact parameters on load	Tribology in medical devices
S-4	SLO-1	Boundary lubrication	Adhesion	Transformation	Scale effects in friction	Natural human synovial joints
	SLO-2	Elastohydrodynamic lubrication	Capillary forces	Parameter of surface topography	Adhesion Friction	Total joint replacements
S-5	SLO-1	Extreme pressure lubrication	Modes of deformation	Friction- Basic laws of friction	Two body deformation	Wind turbine Tribology
	SLO-2	Lubricants - types and lubricating oils	Description of AFM/FFM	Static and kinetic friction	Three body deformation	Biorefining
S-6	SLO-1	Lubricant properties-effect of temperature and pressure	Other measurement techniques	Friction of materials	Ratchet mechanism	Coating applications- sliding bearings

	SLO-2	Oxidation stability	Surface roughness	Solid – solid contact	Meniscus Analysis	Rolling contact
S-7	SLO-1	Thermal conductivity	Friction force	Liquid mediated contact	Total value of coefficient of friction	Bearings
	SLO-2	Type of additives	Scratching	Interfacing temperature of sliding Surfaces	Transformation from elastic to plastic regime	Gears
S-8	SLO-1	Bearings- classification based on mode of lubrication	Wear and machining	Wear-Laws of wear	Tribological properties of SAMs	Erosion and scratch resistant
	SLO-2	Bearing-Classification based on relative motion between contact surfaces	Surface potential measurements	Mild and Severe wear	Tailoring surfaces	Magnetic recording devices
S-9	SLO-1	Comparison of sliding and rolling contact bearing	Nanoindentation measurement	Identification of wear mechanism,	Modifying surface composition for application in Tribology	Micro components
	SLO-2	Solving numerical problems on above topics	Boundary lubrication	Typical test geometries	Modifying Structure for application in Tribology	MEMS/NEMS

Learning Resources	1. G. Phakatkar and R.R. Ghorpade, "Tribology", Nirali publication, 2009 2. Bharat Bhushan, "Nanotribology and Nanomechanics", Springer Publication, Second edition, 2011 3. Bharat Bhushan, "Principles and Applications to Tribology", Wiley Publication, 2013	4. S. M. Sze, "Semiconductor Sensors", Wiley-Interscience, 1994 5. C. Mathew Mate, "Tribology on the Small Scale" Oxford University Press, 2008 6. Nicholas D. Spencer, "Tailoring surfaces", World Scientific IISC Press, 2011
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. Shinji Yamada, Kao Corporation, Tokyo, Japan, Yamada.s@kao.co.jp	1. Dr. M. Balasubramanian, IIT Madras, mbala@iitm.ac.in	1. Dr. S. Yuvaraj, SRMIST
2. Dr. Sridhar M. R., Senior Engineer, GE Global Research, Bangalore, India.	2. Dr. M. S. Ramachandra Rao, IIT Madras, msrrao@iitm.ac.in	2. Dr. Kiran Mangalampalli, SRMIST

Course Code	18NTE305T	Course Name	NANOTECHNOLOGY LEGAL ASPECTS	Course Category	E	Professional Elective Course				L	T	P	C
										3	0	0	3

Pre-requisite Courses	Nil			Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Nanotechnology			Data Book / Codes/Standards		Nil	

Course Learning Rationale (CLR):		The purpose of learning this course is to:		Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Familiarize with the concept of patent and copyright laws			Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Understand the concept of trade mark, trade secret and IP infringement																						
CLR-3 :	Understand the government policies and rules related to nanotechnology																						
CLR-4 :	Gain knowledge on environmental degradation and current regulations																						
CLR-5 :	Learn the social and ethical impact of nanotechnology																						
CLR-6 :	Understand the concept of taxation, trade, security, privacy, export import of nanomaterials																						
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																					
CLO-1 :	Acquire the concepts of patent and copyright laws			2	80	75																	
CLO-2 :	Apply the knowledge of trade mark, trade secret and IP infringement			2	75	70																	
CLO-3 :	Get familiarize with the government policies and rules related to nanotechnology			2	75	70																	
CLO-4 :	Acquire the knowledge on environmental degradation and current regulations			2	80	75																	
CLO-5 :	Get familiarize with the current social and ethical impact of nanotechnology			2	80	75																	
CLO-6 :	Apply the knowledgeof taxation, trade, security, privacy, export import of nanomaterials			2	80	75																	

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction	Government policies and rules	Environmental degradation	Social impact of nanotechnology	Trade and business in nanotechnology
	SLO-2	Patents	Quality of information	Current environmental regulations	Economic impact of nanotechnology	Trade restrictions
S-2	SLO-1	Patentability requirements – structure of patent	Food and drugs evaluation method	Classification	Implications of nanotechnology	Taxation system
	SLO-2	Utility patent	Food and drugs research	Sources of pollutants	Effect on the quality of life	Taxation of goods too small to be seen
S-3	SLO-1	Design patent, monopoly powers	Classification of medical products	Pollution – air	Short term implications	Laws for genetic research
	SLO-2	licensing strategies and arrangements	Safe workplace	Pollution – water	Long term implications	Rights of new life form
S-4	SLO-1	Classification of patent applications	Self-regulation	Industrial waste water	Ethical issues in nanotechnology	Government surveillance
	SLO-2	Willful infringement issues, claim scope	Liability – responsibility of a scientist	Control and quality check	Social and environmental issues in nanotechnology	Privacy violations
S-5	SLO-1	Reexamination of patents	Civil laws	Dispersion methods	Artificial intellects	Security and monitoring
	SLO-2	Patent treaties	Criminal laws in nanotechnology	Monitoring	Ethics for artificial intellects	Eavesdropping
S-6	SLO-1	Copyright laws – fixation	Negligence to nanotechnology – breach of duty causation	Solid waste – homes	Nanotechnology and life extension	R&D in Nanotechnology

	SLO-2	Originality, creativity	Negligence to nanotechnology – damage and defense	Solid waste – industrial	Nanotechnology for national security	R&D regulation
S-7	SLO-1	Integrated circuit topographies	Risk associated with nanoparticles	Hospital waste	Nanotechnology for space exploration	Current industrial design laws
	SLO-2	Industrial designs, artistic work – arrangement of atoms	Nanoparticles use and effects on health	Hazardous chemical waste	Nanotechnology for medical applications	Change in industrial design laws
S-8	SLO-1	Technology transfer	Liability for nanoparticles side effects	Toxicity, health issues	Moral issues of Nanotechnology applications	Export – import regulations
	SLO-2	Trademarks	Role and responsibilities	Safety issues	Public perception of Nano-technological risk	Crimes using Nanoparticles
S-9	SLO-1	Trade secrets	Class action	Risk assessment and analysis	Education of public about Nanotechnology	Corporate criminal liability,
	SLO-2	Ownership of IP	Certification	Responsibility and rules	Training of public about Nanomaterials	prevention and detention

Learning Resources	1. Patrick M. Boucher, "Nanotechnology: Legal aspects" CRC press, 2008 2. Fritz Allhoff, Patrick Lin, James Moor, John Weckert, "NanoEthics: The ethical and social implications of nanotechnology" Wiley publication, 2007	3. Louis Theodore, Robert G. Kunz, "Nanotechnology: Environmental implications and solutions" Wiley Publication, 2005
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. Narayanasvamy Vijayan, National Physical Laboratory, nvijayan@nplindia.org	1. Prof. V. Subramaniam, IITM, Chennai, manianvs@iitm.ac.in	1. Dr. Malay Adhikari, SRMIST
2. Dr. Krishna Surendra Muvvala, Saint Gobain Research India, India, Krishna.muvvala@saintgobain.com	2. Prof. D. Arivuoli, Anna University, arivuoli@annauniv.edu	2. Dr. A. Karthigeyan, SRMIST

Course Code	18NTE306T	Course Name	LITHOGRAPHIC TECHNIQUES AND FABRICATION	Course Category	E	Professional Elective Course	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Micro and Nanofabrication	Progressive Courses	Nil
Course Offering Department	Nanotechnology		Data Book / Codes/Standards	Nil	

Course Learning Rationale (CLR):		The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :		Understand the physical significance of lithography tools in micro/nano structures creation	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :		Acquire knowledge on masked lithography, uv and deep uv lithography, its merits and demerits	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :		Understand the concept of direct lithography, its advantages; electron beam for lithography and their applications																		
CLR-4 :		Acquiring comparative knowledge of different lithography tools																		
CLR-5 :		Acquire knowledge on the replication tools such as nano imprint lithography, injection molding and others.																		
CLR-6 :		Make aware of VLSI technology																		
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																		
CLO-1 :		Make use of top-down approach for micro/nano fabrication	2	80	75	H	M	H	H	H	M	M	H	H	H	M	M	H	H	H
CLO-2 :		Analyze the limitation of masked lithography with respect to incident radiation	2	80	70	H	M	M	H	M	M	H	M	H	M	H	M	M	M	M
CLO-3 :		Using electron beams for the creation of nano structures	2	75	70	H	M	H	H	H	H	H	M	H	H	H	M	H	H	H
CLO-4 :		Know the other techniques of nano fabrication using light and heavy ion beams	2	80	75	M	H	H	M	H	H	H	H	H	H	M	M	H	H	H
CLO-5 :		Apply knowledge of mass production replication tools	2	80	70	H	M	H	H	H	M	H	M	H	M	M	M	H	H	H
CLO-6 :		Imagine importance of nanoscale devices	2	80	75	H	M	M	H	H	M	M	H	H	H	M	H	H	M	H

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Micro/nano fabrication	Optical(photo) lithography	Introduction-maskless/direct lithography tools	Ion beam lithography (IBL) types
	SLO-2	Top-down & bottom-up approach	Process steps	Difference between masked and maskless lithography	Heavy and light ions for lithography
S-2	SLO-1	Necessity for clean room, types of clean room	Optical lithography mask	Advantages and disadvantages of maskless lithography	Focused ion beam properties
	SLO-2	Construction and maintenance of clean room,	Mask definition, and different materials	Principles of electron beam lithography (EBL) system	Beam scanning
S-3	SLO-1	Clean room standards, protocols	Different light sources	Electron properties for lithography	Resists for ion beam lithography
	SLO-2	Lithography- process steps	Contact and proximity exposures	Design of electron beam lithography system	Electron lithography process flow
S-4	SLO-1	Photo resists materials, types and characteristics	Diffraction limit and resolutions enhancement methods	Operation of electron beam lithography system	Focused ion beam lithography- Incident ion properties
	SLO-2	Spin coating methods	Projection lithography	E-beam resists	Principle, design and operation
S-5	SLO-1	Exposure dose	Extreme UV (EUV) lithography	E-beam resist properties	Masked ion beam structuring: Broad beam patterning
	SLO-2	chemical development, optimization	EUV: Scope and demerits	Comparison with optical lithography resists	Atom lithography
S-6	SLO-1	Etching methods, resist and other materials	Interferometric and holographic tools	Dose calculation	Proton beam lithography

	SLO-2	Dry and wet methods	Lithography masks	Significance of beam blanking	Comparison of electron, proton and gallium for resist patterning	Process flow and requirements
S-7	SLO-1	Wet etching chemicals, Si etching	Laser writer: near UV and Deep UV masks	Patterning resolution comparison with other methods	Limitation and suitability of each technique in comparison with one another	Polymers for imprinting
	SLO-2	Wet etching examples	Synchrotron radiation for lithography processes	EBL for mask preparation	IBL resists, dose calculation and process optimization	Polymer characteristics and performance
S-8	SLO-1	Reactive ion etching	X-ray lithography mask	Nanofabrication with EBL – MEMS	Nanofabrication with IBL – MEMS	Master mold preparation for replication tools, comparison
	SLO-2	Isotropic and non isotropic etching	X-ray lithography, merits and demerits	Nanofabrication with EBL – NEMS	Nanofabrication with IBL – NEMS	Application-microfluidics
S-9	SLO-1	Types of lithography : classification	Comparison of all masked lithography tools	Nanofabrication with EBL –microfluidics applications	Nanofabrication with IBL –microfluidics applications	Application-nano fluidics
	SLO-2	Introduction to next generation lithography tools	Specific applications of different lithography tools.	Nanofabrication with EBL – Nanofluidics applications	Nanofabrication with IBL – Nanofluidics applications	Industrial applications

Learning Resources	1. Chris A. Mack, <i>Fundamental Principles of Optical Lithography: The Science of Microfabrication</i> , John Wiley & Sons, London 2007 2. Stefan Landis, <i>"Lithography and nanolithography"</i> , Published by Wiley - ISTE, 2010	
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. Hemant Dixit, Global Foundaries, USA, aplahemant@gmail.com	1. Dr. A. Subrahmanyam, IIT Madras, manu@iitm.ac.in	1. Dr. Abhay Sagade, SRMIST
2. Dr. Krishna Surendra Muvvala, Saint Gobain Research India, India, Krishna.muvvala@saintgobain.com	2. Dr.N. N. Murthy, IIT Tirupati, nmurthy@iittp.ac.in	2. Dr. P. Malar, SRMIST

Course Code	18NTE307T	Course Name	SENSORS AND TRANSDUCERS	Course Category	E	Professional Elective Course	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Nanotechnology	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand basic principles and characteristics of sensors and transducers	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Gain knowledge on mechanical and electromechanical sensors	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Get acquainted with thermal sensors and its types																		
CLR-4 :	Know about magnetic sensors and radiation sensors																		
CLR-5 :	Gain knowledge on electrochemical sensors																		
CLR-6 :	Apprehend knowledge on recent trends in sensor technologies and applications																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Analyze calibration techniques and signal types of sensors	2	80	75	H	M	H	H	H	M	M	H	H	H	M	M	H	H	H
CLO-2 :	Expertise in various types of Sensors & Transducers and their working principles	2	80	70	H	M	H	H	M	M	H	M	H	M	M	M	M	M	M
CLO-3 :	Evaluate performance characteristics of different sensors and transducers	2	75	70	H	M	H	H	H	H	M	M	H	H	H	M	H	H	H
CLO-4 :	Predict exactly the expected performance of various sensors	2	80	75	M	H	H	M	H	H	H	H	H	H	M	H	H	H	H
CLO-5 :	Develop advance techniques in sensor technology	2	80	70	H	M	H	H	H	M	M	H	M	H	M	H	H	H	H
CLO-6 :	Devise smart sensors for real time applications	2	80	75	H	M	M	H	H	M	M	H	H	H	M	H	H	M	H

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Measurements-Basic method of measurement	Mechanical and electromechanical sensors Resistive potentiometer	Thermal sensors- Gas thermometric sensors	Magnetic sensors-Introduction	Electroanalytical sensors-introduction
	SLO-2	Errors	Strain gauge	Thermal expansion type thermometric sensors	Principles behind	Electrochemical cell
S-2	SLO-1	Classification of errors	Inductive sensors	Acoustic temperature sensor	Yoke coil sensors	Sensor electrodes-Molecular selective electrodes
	SLO-2	Error analysis	Sensitivity and linearity of sensor	Dielectric constant and refractive index of thermosensors	Coaxial type sensors-Force and displacement sensors	ChemFET
S-3	SLO-1	Statistical methods	Ferromagnetic plunger type transducers	Helium low temperature thermometer- Nuclear thermometer	Magnetoresistive sensors- Anisotropic magnetoresistive sensing	Recent trends in sensor technologies
	SLO-2	Sensors/Transducers-Introduction	Electromagnetic transducer	Magnetic thermometer	Semiconductor magnetoresistors	Film sensors- Thick and thin film sensors
S-4	SLO-1	Principles of Sensors/Transducers	Magnetostrictive transducer	Resistance change type thermometric sensors	Active semiconductor magnetic sensors	Semiconductor IC technology
	SLO-2	Classification of Sensors/Transducers	Capacitive sensors	Metal resistance thermometric sensors	Hall effect sensor-sensor geometry and fabrication	Micro electro mechanical system (MEMS)- micromachining
S-5	SLO-1	Static Characteristics of Sensors/Transducers	Parallel plate capacitive sensor	Thermistors	Variable inductance sensors	Some application examples
	SLO-2	Accuracy-Precision-Resolution-Minimum detectable signal	Serrated plate capacitive sensor	Thermo emf sensors	Eddy current sensors	Nanosensors
S-6	SLO-1	Threshold-Sensitivity-Selectivity and specificity-Non-linearity	Variable thickness dielectric capacitive sensor	Materials for thermo emf sensors	Radiation sensors-Introduction-basic characteristics	Onboard automobile sensors-flow rate sensors-pressure sensors
	SLO-2	Hysteresis-Output impedance-isolation and grounding	Stretched diaphragm variable capacitance transducer	E (emf)-T(Temperature) relations	Types of photoresistors/photodetectors	Temperature sensors-oxygen sensors

S-7	SLO-1	Dynamic Characteristics	Electrostatic transducer	Thermosensors using semiconductor devices	Photoemissive cell and photomultiplier	Torque and position sensors
	SLO-2	Zero order and First order sensors	Piezoelectric elements	Thermal radiation sensors	Photoconductive cell-LDR	Home appliance sensors
S-8	SLO-1	Second order sensors	Piezoelectric materials	Detectors	Photocurrent	Aerospace sensors-Fluid velocity sensors
	SLO-2	Electrical characterization	Deformation modes and multimorphs	Pyroelectric thermal sensors	Photoresistors and photoFETs and other devices	Sensing direction of air flow- Monitoring strain, force, thrust and acceleration
S-9	SLO-1	Mechanical and thermal characterization	Lead zirconatetitanate (PZT) family	Quartz crystal thermoelectric sensors	Fibre optic sensors	Medical diagnostic sensors
	SLO-2	Optical characterization- Chemical/biological characterization	Force/stress sensors using quartz resonators	Heat flux sensors	Temperature sensors-microbend sensors	Sensors for environmental monitoring

Learning Resources	1. Ernest O Doebelin, "Measurement Systems – Applications and Design", 4 th ed., Tata McGraw-Hill, 2009	3. D. Patranabis, Sensors and Transducers, 2 nd ed., Prentice Hall of India, 2010
	2. John P. Bentley, "Principles of Measurement Systems", 4 th ed., Pearson Education, 2000.	4. D.V.S Murthy, Transducers and Instrumentation, 2 nd ed., Prentice Hall of India, 2001.

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry		Experts from Higher Technical Institutions
1. Dr. Maximilian Fleischer, Siemens, Germany, maximilian.fleischer@siemens.com		1. Dr. A. Subrahmanyam, IIT Madras, manu@iitm.ac.in
2. Dr. Shyam Sunder Tiwari, Sensors technology Private Limited, India, sst@sensorstechnology.com		2. Dr. M. S. Ramachandra Rao, IIT Madras, msr Rao@iitm.ac.in
		Internal Experts
		1. Dr. S. Yuvaraj, SRMIST
		2. Dr. A. Karthigeyan, SRMIST

Course Code	18NTE308T	Course Name	2-D LAYERED NANOMATERIALS	Course Category	E	Professional Elective Course				L	T	P	C
										3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Nanotechnology			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:				Learning			Program Learning Outcomes (PLO)																					
CLR-1 :	Understanding the electronic properties of 2D materials, especially Graphene					Level of Thinking (Bloom)	2	80	75	1	2	3																		
CLR-2 :	Acquire knowledge on the different synthesis methods									Expected Proficiency (%)																				
CLR-3 :	Describe the difference in various properties of 2D-layered structure									Expected Attainment (%)																				
CLR-4 :	Classification of 2D layered Nanomaterials																													
CLR-5 :	Gain knowledge on application of layered Nanomaterials																													
CLR-6 :	Understand the principles of various characterization tools to study the properties of 2D materials																													
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																												
CLO-1 :	Apply the concept of atomic and electronic structure to understand the physical and chemical properties of graphene					2	80	75	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15						
CLO-2 :	Utilize the procedure to synthesize layered materials and the concept of Raman spectra over synthesized materials					2	80	70	Problem Analysis	M	H	H	H	M	M	M	H	H	M	H	H	M	H	M	M					
CLO-3 :	Utilize the spectroscopic concepts to analyze the properties of layered materials					2	75	70	Design & Development	M	H	M	H	M	M	M	M	H	M	H	M	M	M	M	M					
CLO-4 :	Apply the concept and the uses of semiconducting and metal dichalcogenides based materials					2	80	75	Analysis, Design, Research	M	H	H	H	H	H	H	M	H	H	H	H	H	H	H	H					
CLO-5 :	Utilize the application of layered materials in various fields.					2	80	70	Modern Tool Usage	M	H	M	M	H	H	H	H	H	H	M	H	H	H	H	H					
CLO-6 :	Utilize the concept of sensor to analyze the material nature.					2	80	75	Society & Culture	M	H	H	H	M	M	M	M	M	M	H	M	H	H	M	H					
									Environment & Sustainability	M	H	M	H	M	M	H	H	H	H	M	H	H	M	H	M					
									Ethics	M	H	M	H	M	M	H	M	M	M	M	H	H	M	M	M					
									Individual & Team Work	M	H	M	H	M	M	H	M	M	M	M	H	H	M	M	M					
									Communication	M	H	M	H	M	M	H	M	M	M	M	H	H	M	M	M					
									Project Mgt. & Finance	M	H	M	H	M	M	H	M	M	M	M	H	H	M	M	M					
									Life Long Learning	M	H	M	H	M	M	H	M	M	M	M	H	H	M	M	M					
									PSO - 1	M	H	M	H	M	M	H	M	M	M	M	H	H	M	M	M					
									PSO - 2	M	H	M	H	M	M	H	M	M	M	M	H	H	M	M	M					
									PSO - 3	M	H	M	H	M	M	H	M	M	M	M	H	H	M	M	M					

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction of graphene	Introduction to Scotch-tape method (micromechanical cleavage)	Introduction to X-ray photoemission spectroscopy	Graphene and its properties	Introduction to Gas sensors
	SLO-2	Vander Walls force	Preparation of graphene using Scotch-tape method	Limitation and application of XPS	Penta-graphene and its properties	Gas sensing mechanism and types of sensor
S-2	SLO-1	Covalent bond	Introduction and principle of Chemical vapor deposition	Introduction to X-ray diffraction study	h-BN structure, synthesis and properties	Chemical sensors
	SLO-2	Dimension of carbon allotrope	Preparation of graphene by CVD	Limitation and application of XRD	Application of h-BN	Uses smart materials in sensors
S-3	SLO-1	Transition of metal dichalcogenides	Introduction to Solution-exfoliation	Introduction to Optical absorption spectroscopy	SiC structure, synthesis and properties	2D materials based membranes
	SLO-2	Manipulation of quantum degree of freedom	Preparation of graphene using solution-exfoliation	Limitation and application of optical absorption spectroscopy	Application of SiC	Application of membrane
S-4	SLO-1	Crystal plane of 2D graphene	Introduction to Solution-exfoliation	Introduction and limitations of Scanning Tunneling Microscopy	Si structure, synthesis and properties	Oxygen reduction reaction
	SLO-2	Free standing model	Preparation of 2D layered material by solution exfoliation	Measuring mechanical properties	Application of Silicon	Uses of 2D materials in enhance the activity
S-5	SLO-1	Electronic structure of graphene	Decomposition	Introduction and limitations to BET analysis	Ge structure, synthesis and properties	Hydrogen production, types of hydrogen production
	SLO-2	Band structure	Decomposition of silicon carbide	Adsorption properties	Application of Ge	Uses of 2D materials in hydrogen production
S-6	SLO-1	Fermi levels in graphene	Principles of Raman spectroscopy	Introduction and limitations to VSM analysis	Types of oxide materials	Electronic devices
	SLO-2	Carrier density	Limitations of Raman spectroscopy	Magnetic properties	Properties of oxide materials	Difference between electronic and electric device

S-7	SLO-1	Role of defect and dopant	Raman spectrum of graphene	Types of interactions	Introduction and types of transition metal dichalcogenides	Optical materials
	SLO-2	Electronic structure of graphene	Analysis of D band Raman spectra	Catalytic properties	Introduction and application of MoS ₂	Solar absorber materials
S-8	SLO-1	Tensile strength	Analysis of G band Raman spectra	Metal support interactions	Introduction and application of VS ₂	Magnetic devices
	SLO-2	Physical properties of graphene	Raman shift dependence on number of layer	Changes in the properties due to metal support interaction	Introduction and application of WS ₂	Materials used
S-9	SLO-1	Functional properties of graphene	Raman shift dependence on defect	Non-metal support interactions	Introduction of Si2BN and its application	Types of magnetic devices
	SLO-2	Chemical properties of graphene	Raman shift dependence on doping concentration	Difference in properties due to non-metal support interactions	Introduction of BCN and its applications	Applications of magnetic devices

Learning Resources	1. Houssa, Michel, Athanasios Dimoulas, and Alessandro Molle, "2D Materials for Nanoelectronics"- CRC Press, 2016.	3. Tiwari, Ashutosh, and Mikael Syväjärvi, eds. "Advanced 2D Materials" - John Wiley & Sons, 2016.
	2. Banks, Craig E., and Dale AC Brownson, eds. "2D Materials: Characterization, Production and Applications"- CRC Press, 2018.	4. Dragoman, Mircea, and Daniela Dragoman, "2D Nanoelectronics: Physics and Devices of Atomically Thin Materials"- Springer, 2016.

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. Hemant Dixit, Global Foundaries, USA, aplahemant@gmail.com	Prof. K. Sethupathi. IIT Madras, ksethu@iitm.ac.in	Dr. J. Archana, SRMIST
2. Dr. Krishna Surendra Muvvala, Saint Gobain Research India, India, Krishna.muvvala@saintgobain.com	Dr. S. Balakumar. University of Madras, Madras, balakumar@iunom.ac.in	Dr. S. Harish, SRMIST

Course Code	18NTE309T	Course Name	SUPRAMOLECULAR SYSTEMS	Course Category	E	Professional Elective Course				L	T	P	C
										3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Nanotechnology		Data Book / Codes/Standards	Nil	

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Acquire the concepts of supramolecular chemistry				Level of Thinking (Bloom)	2	80	75	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Utilize designing new materials of metal-organic frame works									Problem Analysis														
CLR-3 :	Describe the concept of nanostructured objects									Design & Development														
CLR-4 :	Understand the principles of supramolecular chirality									Analysis, Design, Research														
CLR-5 :	Gain knowledge on host-guest complexes									Modern Tool Usage														
CLR-6 :	Understand the principles sophisticated molecular devices and infinite multicomponent systems									Society & Culture														
									Environment & Sustainability								Ethics							
									Individual & Team Work									Communication						
									Project Mgt. & Finance															
									Life Long Learning															
									PSO - 1															
									PSO - 2															
									PSO - 3															
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1 :	Recognize the main types of supramolecular assemblies					2	80	75	H	M	H	H	H	M	M	H	H	H	H	M	H	H	H	H
CLO-2 :	Apply the importance of the bottom-up approach to prepare complex (nanoscale) systems					2	80	70	H	M	M	M	M	M	M	H	M	M	M	H	M	M	M	M
CLO-3 :	Identify the main supramolecular forces involved in such systems					2	75	70	H	M	H	H	H	H	H	M	H	H	H	M	H	H	H	H
CLO-4 :	Analyze and understand the intermolecular forces to rationalize the formation of complex nanomaterials.					2	80	75	M	H	H	M	H	H	H	H	H	H	M	H	H	H	H	
CLO-5 :	Evaluate the needs of sustainable future, develop the supramolecular molecular materials for biological systems					2	80	70	H	M	H	H	H	M	M	H	M	M	M	M	H	H	H	H
CLO-6 :	Apply through feasible approaches, and assemble with the prior knowledge to fabricate novel designs/architectures					2	80	75	H	M	M	H	M	M	M	H	H	H	M	H	H	M	M	M

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Basic concepts and principles of supramolecular chemistry	Introduction to coordination chemistry	Biological inspiration for supramolecular chemistry	Supramolecular Chirality	Special Class Materials
	SLO-2	Classification of supramolecular compounds	Hosts for cation binding	Alkali metal cations in biochemistry	Chirality in Self-Assembled Systems	Birth of a new macromolecular chemistry concept
S-2	SLO-1	Host-guest compounds	Cation receptors	Co-ordination Polymers	Chirality of Host-Guest Compounds	Rational Design
	SLO-2	Receptors, coordination compounds	Crown ethers	Clathrates	Chirality of Interlocked Systems	Molecular Paneling
S-3	SLO-1	Lock and key analogy	Cryptands	Cavitands	Metal Organic Frameworks (MOFs)	Artificial Self Replicating Systems
	SLO-2	Binding constants	Spherands	Binding by cavitands	Covalent Organic Frameworks	Supramolecular reactivity and catalysis
S-4	SLO-1	Cooperative effect	Calixarens	Cyclodextrins	Polymorphism	The past, present and future of dendrimers and dendrons
	SLO-2	Chelate effect	Selectivity of cation complex	Cucurbituril	Solvates	Supramolecular assembly of dendrons and dendrimers
S-5	SLO-1	Thermodynamic selectivity	Macrocyclic effects	Porphyrins and tetrapyrrole macrocycles	Co-Crystals	Synthesis of dendritic polymers
	SLO-2	Kinetic selectivity and discriminations	Template effects	Transport processes	Principles of supramolecular Extraction	Characterization of dendritic architectural structures
S-6	SLO-1	Nature of supramolecular interactions	Host for anion binding	Dynamic Combinatorial chemistry	Extraction technique, the extraction equilibrium	Nanomaterials and advanced materials
	SLO-2	Solvation effects	Concepts in anion host design	Supramolecular features of plant photosynthesis	Examples of supramolecular extraction	Diagnostics and advanced imaging

S-7	SLO-1	Hydrophobic effects	Anion receptors	Uptake and transport of oxygen by haemoglobin	Binding Constant	Characterization of dendritic architectural structures
	SLO-2	Supramolecular concepts and design	Shape and selectivity	Enzymes and coenzymes	Binding constant determination by UV/Vis spectroscopy	Nanoscience applications
S-8	SLO-1	Hydrogen bonding and supramolecular interactions	Neutral receptors	Neurotransmitters and hormones	Instrumentation of mass spectrometry, Limitations of mass spectrometry	Molecular and Supramolecular devices
	SLO-2	Secondary Electrostatic Interactions in Hydrogen Bonding	From cation host to anion host – a simple change in pH	Enzymes, Metallobiosites	Scanning probe microscopes: - scanning electron microscopy	Molecular Electronic Devices
S-9	SLO-1	Molecular recognition	Hosts for binding of neutral guests	Heme analogues	Transmission electron microscopy	Switches
	SLO-2	Types of recognition	Inert metal- containing receptors	Semiochemistry in natural world, Biochemical self-assembly	Confocal laser scanning microscopy	Molecular Machines

Learning Resources	1. Jonathan W. Steed and Jerry L. Atwood, "Supramolecular Chemistry" J. Wiley and Sons; 1 st Ed. 2000	3. Donald A. Tomalia, Jørn B. Christensen, Ulrik Boas, "Dendrimers, Dendrons, and Dendritic Polymers: Discovery, Applications and the Future", MPG books group, UK, 2012
	2. J.M. Lehn, Supramolecular Chemistry, VCH, Wiley and Sons, 1 st Ed. Weinheim, 1995	

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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2. Dr. Sudhakar selvakumar, CSIR-Central Electrochemical Research Institute, ssudhakar79@gmail.com	2. Dr.Arthanreeswaran, NIT, Trichy, arthanareeq@nitt.edu	2. Dr. S. HariniPriya, SRMIST

Course Code	18NTE310T	Course Name	MEMS and NEMS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Nanotechnology	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Learn what are MEMS? and where they are useful?	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Understand the basics of fabrication of electromechanical systems at micro and nanoscale and modeling	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Understand the principles of sensing and actuation in electromechanical systems	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Explore magnetic materials for suitable for magnetic MEMS	Expected Attainment (%)	Design & Development
CLR-5 :	Gain knowledge on thermal, micro-opto-MEMS materials		Analysis, Design, Research
CLR-6 :	Acquire knowledge on the fabrication, characterization and applications of RF, optical, MEMS Understand the		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Utilize mechanics principles to analyze the mechanical performance of microsystems.	2 80 75	H M H H H M M H H H M H H H
CLO-2 :	Utilize optics, electrical and mechanical principles to analyze optoelectro mechanical performance of MOEMS	2 80 70	H M M H M M M H M H M H M M M
CLO-3 :	Use the radio frequency and thermal principles to analyze the performance of RF and thermal MEMS	2 75 70	H M H H H H H M H H H M H H H
CLO-4 :	Use magnetic and fluid principles to analyze the performance of magnetic MEMS and microfluidic devices	2 80 75	M H H M H H H H H H H M H H H
CLO-5 :	Analyze the tools and processes used in micromachining of MEMS	2 80 70	H M H H H M M H M H M H H H H
CLO-6 :	Apply the principles of physics to analyze and design MEMS, including sensors and actuators.	2 80 75	H M M H H M M H H H M M H M H

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Micro and nanoelectro mechanical systems (MEMS and NEMS)	Photolithography	Principles of sensing and actuation	Magnetic materials: properties,	Principles of MOEMS technology, Applications
	SLO-2 Importance of MEMS in daily life	Surface machining, bulk machining, etching	Role of microsensors and microactuator with examples	Magnetoresistive materials, magnetostrictive materials,	Hybrid systems, application, advantages
S-2	SLO-1 MEMS and NEMS - Scaling Laws	Structural materials	Components of mechanical MEMS	hard magnetic materials, design considerations in magnetic materials	MOEMS components
	SLO-2 Conventional electromechanical systems	Sacrificial materials	Beam, cantilever, microplates	Magnetic sensing and design	Light modulators, beam splitters, Micro lens,
S-3	SLO-1 Mathematical Modeling	Thin film deposition, Impurity doping, etching	diaphragm structures theory, corrugated diaphragms	Presence and direction detection of large object – an example	micro mirror, digital micromirror device
	SLO-2 Important steps for analysis and design of engineering steps	Bulk and surface micromachining	Components in sensors	Magneto resistive sensor	MOEMS devices
S-4	SLO-1 Microsensors and microactuators	Physical and chemical vapor deposition methods,	Capacitive effects, piezo element, piezo mechanics,	Principle of magnetoresistive sensor, hall effect, magnetotransistor	Optical switch, wave guide and tuning,
	SLO-2 Principle of sensing and actuation, capacitive sensors, pressure sensors	P and N-type doping in semiconductors, surface machining at macro and microscales.	Measurement methods	MEMS magnetic sensors and actuators	shear stress measurement
S-5	SLO-1 Mechanical MEMS, Thermal MEMS	Wafer bonding and LIGA, MEMS Assembling and Packaging	Strain measurement, pressure measurement	Construction of a MEMS magnetic sensor, principle of operation, sensitivity of the sensor	Lab-on-a-chip, Important considerations on microscale fluid
	SLO-2 Strain measurement	Anodic bonding, fusion bonding, Lithography, electroforming and molding.	Flow measurement using integrated paddle-cantilever structure	Review of RF based Communication syste-l	Properties of fluids, density, viscosity, nature of flow, surface tension
S-6	SLO-1 MEMS gyroscope, Inchworm technology	Basic Modeling elements in mechanical and electrical systems	MEMS Gyroscopes	Tuners, resonators, switches,	Fluid actuation methods,

	SLO-2	Thermistors, thermal flow sensors, shape memory alloys	Amplifier element, mass/inertia element, capacitor, resistor and inductor	Shear mode MEMS, principle	phase shifters, RF MEMS application area, advantages	Dielectrophoresis, electrowetting
S-7	SLO-1	MOEMS, Magnetic MEMS, NEMS Architectures	Basic Modeling elements in fluid systems	Compensation in gyroscope, gripping piezoactuator, design and working principle,	Review of RF based Communication system-II	Electrothermal flow
	SLO-2	Properties of light and their exploitation with respect to MOEMS	Inertance, fluid resistance, fluid capacitor	Inchworm technology, principle, controlling signal	Design scenarios, planer inductor	Thermo capillary effect
S-8	SLO-1	optical switching, beam splitters and microlenses	Thermal systems modeling	Thermal sensors and actuators	RF MEMS, varactors, tuner/filter	Electroosmosis flow
	SLO-2	Introduction to RF Communication systems and applications.	Thermal capacitance, thermal resistance	Thermal energy basics and heat transfer processes,	Fabrication process, varactors,	Optoelectrowetting
S-9	SLO-1	Varactors, RF tuners, filters, switches, phase shifters	Translational and rotational pure mechanical systems with spring	thermistors, thermocouple, Thermal actuators	Tuner/filter, resonator, Resonators	Micropumps: design consideration, Microneedle,
	SLO-2	Microfluidic systems, Concept of lab-on-a-chip, properties of fluids	damper and mass	Thermodevices, micromachine thermocouple probe, thermal flow sensors	Switches, Phase shifter	Construction of a micropump, modeling, working principle

Learning Resources	1. Mahalik N P, "MEMS", Tata McGraw-Hill Education, 2008 2. Sergey Edward Lyshevski, "Micro-Electro Mechanical and Nano-Electro Mechanical Systems, Fundamental of Nano-and Micro-Engineering", CRC Press, 2005	3. C. T. Leondes, MEMS/NEMS Handbook Techniques and Applications, Vol. 1, Springer, 2006. 4. Mohamed Gad-el-Hak, MEMS- Introduction and Fundamentals, 2nd Edition, Taylor and Francis Group, LLC, 2006.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Evaluate Create	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. Hemant Dixit, GlobalFoundaries,USA, aplahemant@gmail.com	1. Prof. V. Subramaniam, IITM, Chennai, manianvs@iitm.ac.in	1. Dr. M. Kiran, SRMIST
2. Dr. Krishna Surendra Muvvala, Saint Gobain Research India, India, Krishna.muvvala@saintgobain.com	2. Prof. M. Ghanashyam Krishna, UOHYD, mgksp@uohyd.ernet.in	2. Dr. A. Karthigeyan, SRMIST

Course Code	18NTE311T	Course Name	SURFACE AND INTERFACES	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Nanotechnology	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand why/how surfaces are important in nanotechnology				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Explain various mechanisms involved in surfaces/interfaces and fundamentals of various types of bonding at surfaces/interfaces				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Describe strategies for manipulating the surfaces and how those strategies help them depending upon the application of such modified surface																					
CLR-4 :	Be familiar with property equations and thermodynamic properties of gas-surface interactions along with the concepts of phase equilibrium of multi component systems																					
CLR-5 :	Acquire the knowledge in Adsorption and desorption kinetics																					
CLR-6 :	Equip with surface-analytical tools such as photoemission spectroscopy, Kelvin probe microscopy, spectroscopy ellipsometry and its significances																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	Apply the knowledge in surfaces; their structure and physical-chemical properties, and interfaces between solids				2	85	70	H	M	M	M	M	M	M	H	M	H	M	M	H	H	H
CLO-2 :	Analyze a surface reconstruction & anticipate the stability of a given interface.				2	80	70	H	M	H	H	M	M	M	H	M	H	M	H	M	M	H
CLO-3 :	Decide what the necessary (statistical) thermodynamics concepts to describe an interface are.				2	70	70	H	M	H	H	H	H	H	H	M	H	M	H	H	H	M
CLO-4 :	Develop qualitative understanding of theories involved and general concepts				2	75	75	H	M	M	M	M	M	M	M	M	H	M	M	L	H	M
CLO-5 :	Validate sound understanding in collective phenomena at the surfaces/interfaces				2	75	70	H	M	M	M	M	M	M	M	M	H	M	H	M	H	M
CLO-6 :	Compare different surface characterization techniques in terms of their performance, sample introduction of methods and sensitivity				2	80	75	H	M	M	M	M	M	H	H	M	H	M	H	M	H	M

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Definition of a Surface and an Interface - its importance/significance	The Hierarchy of Equilibrium	Adsorption and Desorption Kinetics	Structure of Surfaces
	SLO-2	Liquids and Liquid Surfaces	Thermodynamics of Flat Surfaces and Interfaces	Physiosorption and Chemisorption	Surface Crystallography
S-2	SLO-1	Surface Area to Volume Ratio	The Interface Free Energy	General Issues of Isotherms	Surface stress, Surface energy
	SLO-2	Solids and Solid Surface Roughness	Surface Excesses	Isosters, and Isobars	Relaxation, Reconstruction - Defects
S-3	SLO-1	Chemical Heterogeneity of Solid Surfaces - Molecular Interactions	Charged Surfaces at Constant Potential	The Langmuir Isotherm	General Aspects of Surface Lattice Dynamics
	SLO-2	General concepts of Internal Energy and Free Energy	Charged Surfaces at Driven potential	Lattice Gas with Mean Field Interaction	Diffraction at Surfaces - Surface Superlattices
S-4	SLO-1	Intramolecular Forces: Formation of a Molecule by Chemical Bonding	Maxwell Relations	The Fowler-Frumkin Isotherm	Defects at surfaces/interfaces – line & point defects
	SLO-2	Interatomic forces, bonds - Molecular geometry	Their Applications	Reduction to the Langmuir Isotherm	Vibrational Excitations at Surfaces - Surface Phonons of Solids
S-5	SLO-1	Dipole moments	Solid and Solid interfaces	Experimental Determination of the Heat of Adsorption	Surface Stress and the Nearest Neighbor Central Force Model
	SLO-2	Intermolecular Forces and Potential Energies	Solid-Liquid Interfaces	Underpotential Deposition	Surface Phonons in the Acoustic Limits

S-6	SLO-1	Coulomb Interactions	Step Line Tension	Symmetry of Adsorption Sites -	Diffusion at Surfaces	Linear Optical Techniques at Surfaces and Interfaces
	SLO-2	Polar Interactions	Stiffness at its interfaces	Vibrational Frequencies of Isolated Adsorbates	Observation of Single Atom Diffusion Events-Statistics of Random Walk	Spectroscopic Ellipsometry (SE)
S-7	SLO-1	van der Waals Interactions	Equilibrium Fluctuations of Line Defects and Surfaces	Desorption - Desorption Spectroscopy	Absolute Rate Theory	Reflection Difference Techniques (Surface Differential Reflectivity (SDR)
	SLO-2	Induction effects	The Terrace-Step-Kink Model - Basic Assumptions and Properties	Theory of Desorption Rates	Calculation of the Pre-factor	Reflection Anisotropy Spectroscopy (RAS))
S-8	SLO-1	Collective phenomena at interfaces – Superconductivity	Step-Step Interactions on Vicinal Surfaces	Specific Adsorption of Ions	The Ehrlich-Schwöbel Barrier- The Concept of the Ehrlich-Schwöbel Barrier	Probing occupied and unoccupied states - Photoemission spectroscopy, surface states
	SLO-2	Superconductivity at interfaces – A simple model for transport through normal-superconductor interface	The Ising-Model	Specific Adsorption of molecules	Mass Transport on Stepped Surfaces	General Aspects of inverse photoemission
S-9	SLO-1	Collective phenomena at interfaces - Ferromagnetism	Application to the Equilibrium Shape of Islands	The Chemical Bond of Adsorbates of Hydrogen, Oxygen molecules	The Kink Ehrlich-Schwöbel Barrier	Work Function changes induced by the adsorbates – 2D phase transition
	SLO-2	Ferromagnetism at interfaces- Magnetic layer coupling	Simple Solutions for the Problem of Interacting Steps	The Chemical Bond of Adsorbates of Water, Hydrocarbons	The Atomistic Picture of the Ehrlich-Schwöbel Barrier	Kelvin Probe measurements for the study of work-function changes

Learning Resources	1. G. Bordo Vladimir and Horst-Günter Rubahn, <i>Optics and Spectroscopy at Surfaces and Interfaces</i> , WILEY-VCH Verlag GmbH & Co. KGaA, Weinheim 2005	4. John C. Riviere, Sverre Myhra, <i>Handbook of Surface and Interface Analysis: Methods for Problem-Solving</i> , 2 nd Edition, CRC Press Taylor & Francis Group 2009
	2. Harald Ibach, <i>Physics of Surfaces and Interfaces</i> , Springer-Verlag Berlin Heidelberg 2006	5. Klaus Wandelt, <i>Surface and Interface Science, Volume 6: Solid-Gas Interfaces II</i> , Wiley VCH Verlag, Weinheim, Germany 2015
	3. H. Yildirim Erbil, <i>Surface Chemistry Of Solid and Liquid Interfaces</i> , First published in 2006 by Blackwell Publishing Ltd, Oxford, UK	

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#		Theory	Practice
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice		
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers			
Experts from Industry		Experts from Higher Technical Institutions	
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2. Dr. Krishna Surendra Muvvala, Saint Gobain Research India, India, Krishna.muvvala@saintgobain.com		2. Prof. Gridhar U. Kulkarni, Director at CeNS, Bangalore, guk@cens.res.in	
		Internal Experts	
		1. Dr. A. A. Alagiriswamy, SRMIST	
		2. Dr. E. Senthil Kumar, SRMIST	

Course Code	18NTE312T	Course Name	NANOTECHNOLOGY IN FOOD PRODUCTION	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Nanotechnology	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Know the various types of interactions at molecular scale	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Understand the effect of nanoparticles on agricultural methodology and food technology	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Gain knowledge of the types diagnostic tools using nanotechnology	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Acquire knowledge about the newer technologies in the food production	Expected Attainment (%)	Design & Development
CLR-5 :	Get familiarized with the new concepts of Nano Science in the packaging industries and food production		Analysis, Design, Research
CLR-6 :	Know the toxic effect of nanomaterials used in food processing and food technology		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Apply the concept of interactions with in the supramolecular structures at molecular scale	2 80 75	M M H M M H H H H H H H H H
CLO-2 :	Utilize the assay techniques in agricultural and food diagnostics	2 80 70	M H M M M H H H H H H H H H
CLO-3 :	Apply the concepts of nanotechnology in food products	2 75 70	H M M M M H H M H H H H H H
CLO-4 :	Engineer food ingredients which are capable to improve the bioavailability	2 80 75	H H H M M M H H M H H H H H
CLO-5 :	Select the preferred packaging materials for various food products	2 80 70	M H M M M M H M H H H H H H
CLO-6 :	Assess the toxic effects of the nanomaterials used in the food processing and technology	2 80 75	M H M M M M H H M H H H H H

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Intermolecular interactions and supermolecular structures – Introduction	Nanotechnology in Agriculture and Food diagnostics	Food products and its production – Introduction	Nanotechnology in Crop management - Introduction
	SLO-2	Water - hydrophobic and hydrophilic interactions	Nanodiagnostic approaches in detecting microbial agents	Food and new ways of food production	Crop improvement - reasons to package food products
S-2	SLO-1	dispersion interaction, electrostatic interactions	Biosensors, Enzyme biosensors and diagnostics	Need for new food processing methods	Physical properties of packaging materials
	SLO-2	Atoms and small molecules	DNA-based biosensors and diagnostics	Efficient fractionation of crops	Strength
S-3	SLO-1	Polymers, particles, and surfaces	Radiofrequency identification	Efficient product structuring	Barrier properties
	SLO-2	Introduction to Steric interactions	Integrated nanosensor networks: Detection and Response	Optimizing Nutritional value	light absorption
S-4	SLO-1	Steric interactions involving soluble polymers	Electrochemical biosensors – Gold Nanoparticles	Nanotechnology in Food Production	structuring of interior surfaces
	SLO-2	Aggregation	Magnetic Nanoparticles in diagnostics	Applications of nanotechnology in foods	Antimicrobial functionality
S-5	SLO-1	Depletion aggregation of particles by non-adsorbing polymers	Fluorescent Nanoparticles in diagnostics	Sensing, packaging	Visual indicators
	SLO-2	Bridging aggregation of particles by adsorbing polymers	Silica Nanoparticles in diagnostics	Encapsulation	Quality assessment
S-6	SLO-1	Stabilization of dispersed particles by adsorbing polymers	Safety of nanotechnology in food and the impact in consumer health	Nano Engineering food ingredients to improve bioavailability	Food safety indication
					Adme (absorption)

	SLO-2	Polymer brushes to prevent particle aggregation and particle deposition at surfaces	Transduction Principles	Nanocrystalline food ingredients	Product properties	Adme (distribution)
S-7	SLO-1	Self Assembly	Microfluidic Assays	Nano-emulsions	Information and Communication technology	Adme (metabolism)
	SLO-2	Organized self-assembled structures	Lateral flow (immuno) assay	Nano-engineered protein fibrils as ingredient building blocks	Sensors	Adme (excretion)
S-8	SLO-1	Langmuir layers	Nucleic acid lateral flow (immuno) assay	Preparation of food matrices	Radiofrequency identification technology	Toxicodynamics
	SLO-2	Lipid bilayers	Flow-through (immuno) assays	Risks of Nanotechnology	Health Risks	In vivo toxicity
S-9	SLO-1	Solid-supported lipid bilayers	Antibody microarrays	Concerns about using nanotechnology in food production	Environmental Risks	In vitro toxicity
	SLO-2	Micelles, Vesicles	Surface plasmon resonance spectroscopy	Rational argumentation versus Human feelings	Consumer and societal acceptance	Study Reliability
Learning Resources						
1. Nicholas A. Kotov, "Nanoparticle Assemblies and Superstructures", CRC, 2006 (ISBN 9780367392284) 2. Lynn J. Frewer, Willem Norde, Arnout Fischer, and FransKampers, "Nanotechnology in the Agri-Food Sector", Wiley VCH, 2011 (ISBN:9783527330607) 3. David S Goodsell, "Bionanotechnology", John Wiley & Sons, 2004 (ISBN 0-471-41719-X) 4. Jennifer Kuzma and Peter VerHage, "Nanotechnology in agriculture and food production", Woodrow Wilson International, 2006						

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Evaluate Create	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Rajendra Moorthy Rajendran, Kemin Industries, Chennai, India rajendramoorthy.r@kemin.com	1. Dr. V Geethalakshmi, TNAU, Coimbatore, directorscms@tnau.ac.in	1. Dr. C.Gopalakrishnan, SRMIST
2. Mr. Saravanan Lokasundaram, Agro Crops, Chennai, India, sara@agrocrops.com	2. Dr. A Lakshmanan, TNAU, Coimbatore, microlaxman@yahoo.com	2. Dr. E.Senthilkumar, SRMIST

Course Code	18NTE313T	Course Name	ADVANCED DRUG DELIVERY SYSTEMS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Physics and Nanotechnology	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand the concept of drug delivery	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Acquire knowledge on controlled drug delivery	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Learn the concept of targeted drug delivery				H	M	H	H	H	H	H	H	M	H	L	H	H	H	H
CLR-4 :	Know about the methods of drug delivery				H	M	H	H	M	M	M	H	M	H	L	H	M	M	M
CLR-5 :	Learn about various nanocarriers				H	L	H	H	H	H	H	H	M	H	L	H	H	H	H
					H	M	H	H	H	H	H	H	M	H	L	H	H	H	H
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Explain various drug delivery systems	2	80	75															
CLO-2 :	Analyse a controlled drug release profile	2	80	70															
CLO-3 :	Formulate different drug delivery systems	2	75	70															
CLO-4 :	Apply the concept of drug targeting	2	80	75															
CLO-5 :	Differentiate among various nanocarriers	2	80	70															

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Drug delivery systems	Targeted drug delivery system	Metal nanoparticles for drug delivery	Cancer therapy	Theranostic metal nanoshells
	SLO-2	Traditional drug delivery	Site specific drug release	Gold based drug delivery systems	Drug delivery to cancer	Photothermally-modulated drug delivery using nanoshell
S-2	SLO-1	Advantages and disadvantages of various traditional drug delivery systems	Types of drug targeting	Multifunctional nanoparticles	Targeted drug delivery to cancer	Hydrogels
	SLO-2	Modes of drug delivery	Active targeting	Multifunctional gold nanoparticles for drug delivery and imaging	Enhanced permeability and retention	Nanoporous systems for drug delivery
S-3	SLO-1	Routes of administration	Passive targeting	Virus based drug delivery system	Cancer markers	Molecularly-derived therapeutics
	SLO-2	Novel drug delivery system	Barriers for drug targeting	Polymeric nanoparticles	Folate receptor	transdermal drug delivery
S-4	SLO-1	Pharmacokinetics	Strategies for site specific drug delivery	Classifications of polymers	Angiogenesis	low-frequency sonophoresis
	SLO-2	ADME studies	Receptors	Polymer micelles	Leaky vasculature	implants for controlled drug delivery
S-5	SLO-1	Kinetics of drug delivery	Ligands	Synthesis of polymeric nanoparticles for drug delivery	Cancer specific targeting	Responsive release system
	SLO-2	Zero order kinetics	Antibodies based drug delivery	Dentrimers	Combinational therapy	Fabrication and Applications of Microneedles

S-6	SLO-1	First order kinetics	Metabolism based drug delivery	Magnetic nanoparticles for drug delivery	Neutron capture therapy	Micropumps
	SLO-2	Mixed order kinetics	Surface modification of nanoparticles	Nanoscaffolds	Targeting tumor vasculature for imaging	microvalves
S-7	SLO-1	Controlled drug delivery	Bioconjugation of nanoparticles	CNT in drug delivery	Anticancer drugs	Implantable microchips
	SLO-2	Mechanism of controlled drug release	PEGylation of nanoparticles	Liposomes	Pharmacodynamics	Quantum Dot Probes
S-8	SLO-1	Therapeutic index	reticuloendothelial system	Protein drug delivery	Photothermal therapy	Applications Nano biotechnologies for Single-Molecule Detection
	SLO-2	Drug release profile	Opsonaization	Gene delivery	Cancer imaging	Nanorobots
S-9	SLO-1	Rate controlled drug delivery	Renal clearance	Gene transfection	Nanoparticle–Aptamer Conjugates for Cancer Cell Targeting and Detection.	Drug delivery to Central Nervous systems
	SLO-2	Time controlled drug delivery	Steric repulsion	Methods of gene transfection	Fluorescent Silica Nanoparticles for Tumor Imaging-	Drug delivery across Blood brain barrier

Learning Resources	1.	Drug Delivery: Engineering Principles for Drug Therapy, M. Salzman, Oxford University Press, 2001.	3.	Drug Delivery: Principles and Applications, B. Wang, Wiley Interscience, 2005.
	2.	Drug Delivery and Targeting, A.M. Hillery, CRC Press, 2002.	4.	Nanoparticle Technology for Drug Delivery, Ram B. Gupta, Uday B. Kompella Taylor & Francis, 2006

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry		Experts from Higher Technical Institutions
1. Mr. K. Chandru Triviron Healthcare Pvt. Ltd. Chennai, chandru.k@triviron.com		1. Dr. Asifkhan Shanavas, INST Mohali, asifkhan@inst.ac.in
2. Dr. Achuth Padmanaban, Baylor College of Medicine, USA, achuthz@gmail.com		2. Dr. Mukesh Doble, IIT M, mukeshd@iitm.ac
		Internal Experts
		1. Dr. G. Devanand Venkatasubbu, SRMIST
		2. Dr. Selvamurugan, SRMIST

Course Code	18NTE314T	Course Name	NANOMEDICINES	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Nanotechnology		Data Book / Codes/Standards	Nil	

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understanding the basis of medicine	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Know the various classification of nanomedicine	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Getting knowledge about interaction of nanomaterials with biological environment				H	M	H	H	H	M	M	H	H	H	M	H	H	H	H
CLR-4 :	Gain a broad understanding about the nanosystems for the diagnosis and therapy				H	M	M	H	M	M	M	H	M	H	M	H	M	M	M
CLR-5 :	Get acquainted with future aspects of nanoimprinted biosensor				H	M	H	H	H	H	H	M	H	H	H	H	H	H	H
CLR-6 :	Comprehend the principles behind nanomedicine				M	H	H	M	H	H	H	H	H	H	M	H	H	H	H
					H	M	M	H	H	M	M	H	H	H	M	H	H	M	H
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Apply the principles of medicine in nanomedicine	2	80	75															
CLO-2 :	Analyze the shortcomings of conventional medicine	2	80	70															
CLO-3 :	Apply concepts of nanomedicine to a focused clinical area of their choice	2	75	70															
CLO-4 :	Apply these nanosystems for the diagnosis and therapy	2	80	75															
CLO-5 :	Utilize the current techniques for novel applications of bioimaging	2	80	70															
CLO-6 :	Apply the principles of 3D printing for future aspects of nanoimprinted biosensor	2	80	75															

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Carbon nanotubes for Bone regeneration	Biocompatibility of traditional medical implants	Introduction to biomedical imaging	Drug delivery to CNS
	SLO-2	Carbon nanotubes for Electroporation	Adhesive interactions with implant surfaces	Types of biomedical imaging	Drug delivery across blood brain barrier (BBB)
S-2	SLO-1	Hexagonal array of gold nanorods	Nanorobot immunoreactivity	The emergence of nanoparticles as imaging platform in biomedicine	EEG for monitoring brain activity
	SLO-2	Gold nanorods in sensing	Nanopyrexia	Magnetic resonant imaging- principle and techniques	Nanowires for monitoring brain activity
S-3	SLO-1	Isohelical DNA-binding oligomers	Mutagenicity	Magnetic resonant imagingworking methodology	Neuroregeneration
	SLO-2	Nanospearing- multifunctional glyco-nanoparticles	Carcinogenicity	Magnetic resonant imaging-Paramagnetic contrast agents	Neurosurgery
S-4	SLO-1	Nanoarchitectures	Thermocompatibility	USPIOS for imaging	Nanoneurosurgery
	SLO-2	Nanoconstructions based on spatially ordered nucleic acid molecules	Mechanocompatibility	SPIOS for imaging	Lipoblockers
S-5	SLO-1	DNA self assembly	Cell membrane disruption	MPIOS for imaging	Nanolipoblockers - antirestenosis drugs
	SLO-2	DNA self-assembling nanostructures induced by trivalent ions	Systemic nanoparticle distribution	Magnetic nanosensors	Myocardial Infraction conventional therapy
S-6	SLO-1	Assembling by polycations	Nanoparticle phagocytosis	Nanosensors- radio labeled nanoparticles	Cell therapy for myocardial infarction
	SLO-2	Wang tiles	Nanomaterial volumetric intrusiveness	Ultrasound imaging	Stem cell types
					Calorimetric sensing

S-7	SLO-1	Biological examples of Nanomotors and devices	Intusiveness of Nanobots	Acoustically reflective nanoparticles	Regeneration of the cardiovascular system	Vapor phase sensing
	SLO-2	ATPase motor	Nanobiotechnology in tissue engineering	Acoustically reflective nanoparticles: application in ultrasound imaging	Nanobone implants	Raman sensing at surfaces
S-8	SLO-1	Kinesine motor	Nanobiotechnology for organ replacement	Iodinated liposomes	Nanobone scaffolds	Electro analytical sensing
	SLO-2	Dynein motor	Liver and kidney transplant	Application of Iodinated liposomes	Nanoparticle drug formulations for spray inhalation - wound healing	Plasma sensing
S-9	SLO-1	Polymer-based capsules	Nanobiotechnology for assisted function	Quantum dots	Nanogeriatrics	Optical sensing
	SLO-2	Oral drug delivery	Organ assists	Quantum dots in optical imaging	Orthodontal application	Sensors for cancer detection

Learning Resources	1. Understanding Nanomedicine: An Introductory Textbook by Rob Burgess. 2012 CRC Press	3. Medical Nanotechnology and Nanomedicine by Harry F. Tibbals. 2010 by CRC Press
	2. Nanomedicine for Drug Delivery and Therapeutics, Editor(s): Ajay Kumar Mishra, 2013, Wiley	4. Introduction to Nanomedicine and Nanobioengineering, by Paras N. Prasad. 2012, Wiley

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. K. Chandru Trivitron Healthcare Pvt. Ltd. Chennai, chandru.k@trivitron.com	1. Dr.Amit Kumar Mishra , IIT Jodhpur, amit@iitj.ac.in	1. Dr. Devanandh venkata subhu, SRMIST
2. Dr.Nagesh Kini, Thermax,Pune,Maharashtra,nagesh.kini@gmail.com	2. Dr.Sampath Kumar T.S,IIT Madras, tssk@iitm.ac.in	2. Dr. Selvamurugan, SRMIST

Course Code	18NTE315T	Course Name	MICROELECTRONICS AND VLSI	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Offering Department	Nanotechnology	Data Book / Codes/Standards	Nil		

Learning Rationale (CLR):	The purpose of learning this is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Acquire knowledge on importance of microelectronics	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Understand the physical effects of semiconductor-semiconductor junction, its electrostatics, device and circuit level operation	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Acquire knowledge on digital language of Boolean algebra, basics of logic gates for advanced memory applications																		
CLR-4 :	Learn process flow of CMOS IC fabrication, circuit formation and its operation																		
CLR-5 :	Understand intricacies of designing micro/nanoscale rules, flow of fabrication and IC testing principles																		
CLR-6 :	Acquire knowledge on power consumption and optimization of on-chip devices, its analysis on performance																		
Learning Outcomes (CLO):	At the end of this , learners will be able to:																		
CLO-1 :	Interpret difference between macro and micro electronics	2	80	75	H	M	H	H	H	M	M	H	H	H	M	H	H	H	H
CLO-2 :	Apply basic semiconductor physics which is important to understand the working of semiconductor-semiconductor junctions, device and circuit level operation	2	80	70	H	M	M	H	M	M	M	H	M	H	M	H	M	M	M
CLO-3 :	Analyze various number systems of Boolean algebra, operation of logic gates and memory circuits	2	75	70	H	M	H	H	H	H	H	M	H	H	H	M	H	H	H
CLO-4 :	Elucidate process flow of CMOS based logic devices, circuit formation and its operation	2	80	75	M	H	H	M	H	H	H	H	H	M	H	H	H	H	H
CLO-5 :	Designing steps in VLSI, rules, flow of fabrication and IC testing at high frequency	2	80	70	H	M	H	H	H	M	M	H	M	H	M	H	H	H	M
CLO-6 :	Analyze power consumption and need for optimization in on-chip devices, its effect on switching speed	2	80	75	H	M	M	H	M	M	M	H	H	M	M	H	M	M	H

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Introduction to classification of materials	Number systems	Introduction to IC Technologies	Overview of VLSI design methodologies
	SLO-2	Types of semiconductors	Binary and octal numbering	Needs of VLSI	Usage of power in IC
S-2	SLO-1	Concept of energy band gap	Hexadecimal numbering	VLSI design styles	Overview of power consumption, low and high power in VLSI chips
	SLO-2	Doping in semiconductors	Conversions between number systems	Steps in designing	On-chip capacitors
S-3	SLO-1	Formation of p-n junction	Boolean algebra	Layout rules	Cascading of process
	SLO-2	Electrostatics of junction operation	Conversions between number systems	Introduction to Complementary Metal Oxide Semiconductor (CMOS)	Charging and discharging of capacitor
S-4	SLO-1	Diode as circuit element	Logic gates	Introduction to MOSFET	Currents and voltages in CMOS short circuits
	SLO-2	Electrostatics of junction operation	Logic gates	VLSI for CMOS	VLSI for MOSFET
S-5	SLO-1	Diode as circuit element	Truth tables for AND, OR, NOT gates	Positive channel MOS (PMOS) and negative channel MOS (NMOS)	Leakage current, static current
	SLO-2	Basics of bipolar and unipolar junction transistors	Truth tables for NAND, NOR gates	BiCMOS and applications	DC operation of MOSFET
S-5	SLO-1	Current-voltage characteristics and operation of transistors	Circuits with logic gates	CMOS inverter	AC operation of MOSFET
	SLO-2	Basics of bipolar and unipolar junction transistors	Truth tables for NAND, NOR gates	BiCMOS and applications	transistor and gate sizing
S-5	SLO-1	Current-voltage characteristics and operation of transistors	Circuits with logic gates	CMOS inverter	Modelling of MOSFET
					Power analysis

	SLO-2	Ebers-Moll representation of transistor for circuit element	combinational circuits and sequential circuits	CMOS logic circuits	Small signal model	Data correlation analysis
S-6	SLO-1	AC operation of transistor	Flip-flops	Combinatorial CMOS Logic	Need of high frequency operation	Random logic signals, signal entropy
	SLO-2	Small signal model	SR and JK flip-flops	pMOS and nMOS in logic operation	high frequency MOSFET models	Switching activity analysis
S-7	SLO-1	Small signal model for bipolar junction transistor (BJT)	Basics of counters	D-latch	Testing of transistor	Parallel architecture
	SLO-2	Small signal model for junction field effect transistor (JFET)	Asynchronous and synchronous counters	CMOS for D-latch	Need for testing	Digital CMOS circuits
S-8	SLO-1	Amplifiers	Overview of memory devices	Triggering of flip-flops	Testing principles	CMOS amplifiers
	SLO-2	Transistor connections in various modes	Logic gates for memory applications	Edge triggered Flip Flops	design for testability	CMOS amplifier topologies
S-9	SLO-1	Feedback concept	Read only memory	Transistor logic	Error analysis	Common-Source topologies
	SLO-2	Ideal F/B amplifiers	Random access memory	Pass transistor circuits	Safety in testing	Parallel architecture with voltage reduction

Learning Resources	1. Behzad Razavi, <i>Fundamentals of Microelectronics</i> /Edition 1, Wiley, 2008 2. Millman and Grabel, <i>"Microelectronics"</i> , 2nd Ed. Tata McGraw-Hill, 1999	3. Weste N.H., <i>"Principles of CMOS VLSI Design"</i> , Pearson Education, India, 2002
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Evaluate Create	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. D.K. Aswal, National Physical Laboratory, dkaswal@nplindia.org	1. Prof. K. Sethupathi, IITM Chennai, ksethu@iitm.ac.in	1. Dr. Abhay A Sagade, SRMIST
2. Dr. S. Sudhakar, CSIR-CECRI, sudhakar@cecri.res.in	2. Prof. S. Balakumar, University of Madras, balakumar@iunom.acs.in	2. Dr. P. Malar, SRMIST

Course Code	18NTE316T	Name	PHYSICS OF ELECTRONIC MATERIALS				Category	E	Professional Elective	L	T	P	C										
			3	0	0	3																	
Pre-requisite Courses		Nil	Co-requisite Courses		Nil	Progressive Courses		Nil															
Offering Department		Nanotechnology				Data Book / Codes/Standards		Nil															
Learning Rationale (CLR):		The purpose of learning this is to:				Learning		Program Learning Outcomes (PLO)															
CLR-1 :	Understand the physics of electronic materials				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLR-2 :	Familiarize different physical properties of electronic materials				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3	
CLR-3 :	Know-how the various processes in electronic materials																						
CLR-4 :	Understand the physics behind the working of electronic materials based devices																						
CLR-5 :	Gain a fundamental understanding of the emerging electronic materials																						
CLR-6 :	Know new materials other than Si etc and future technology roadmap																						
Learning Outcomes (CLO):		At the end of this , learners will be able to:																					
CLO-1 :	Use knowledge of physics to understand the properties of electronic materials				2	80	75	M	M	H	H	M	H	H	M	M	H	M	H	H	H	H	
CLO-2 :	Analyze different mechanisms that determine the properties of electronic materials				2	80	70	H	M	H	H	M	M	M	M	M	H	L	H	M	M	M	
CLO-3 :	Determine the applications of electronic materials based on their properties				2	75	70	M	L	H	H	H	H	H	H	M	H	M	H	H	H	H	
CLO-4 :	Evaluate the material characteristics by applying laws of physics				2	80	75	H	H	H	H	H	H	H	M	M	H	M	H	H	M	M	
CLO-5 :	Develop in depth understanding of the physical processes of electronic materials				2	80	70	H	M	H	H	H	H	H	H	M	H	M	H	H	M	M	
CLO-6 :	Distinguish how materials are classified and their applications							M	M	M	M	L	M	M	H	H	H	H	M	H	M	M	
Duration (hour)		9		9		9		9		9													
S-1	SLO-1	Defining characteristics and classification of semiconductors		Concept of relative permittivity		Definition of magnetic dipole moment		Optical properties of materials				Thermal properties of materials											
	SLO-2	Fundamentals of band theory of semiconductors		Electric dipole moment and polarizability		Orbital and spin magnetic moment of an electron		Refractive index, Refractive index-wavelength behavior				Atomistic theory of heat capacity											
S-2	SLO-1	Intrinsic semiconductors		Polarization vector and charge density		Magnetization vector		Snell's law and total internal reflection				Quantum mechanical considerations											
	SLO-2	Energy band diagram and carrier movement		Electric susceptibility and relative permittivity		Definition of magnetic susceptibility and magnetic permeability		Case study: fiber optics and LEDs				Einstein and Debye model											
S-3	SLO-1	Conductivity of a semiconductor		Lorentz field in dielectrics		Magnetic materials classification		Interaction of photons with materials				Electronic contribution to the heat capacity											
	SLO-2	Electron and hole concentrations		Clausius-Mossotti equation		Dia-, para-, ferro-, antiferro-, and ferrimagnetism		Absorption, transmittance and reflection				Heat capacity and specific heat											
S-4	SLO-1	Extrinsic semiconductors		Electronic polarization in covalent solids		Origin of ferromagnetism and exchange interaction		Antireflection coatings on solar cells				Thermal expansion and thermal conductivity											
	SLO-2	Concepts of p-type, n-type and compensation doping		Ionic, dipolar, interfacial and total polarization		Saturation magnetization and curie temperature		Dielectric mirrors				Thermal conductivity in metals, alloys, and dielectrics											
S-5	SLO-1	Energy band diagram and electron and hole concentrations		Concept of dielectric loss		Magnetic domains and domain walls		Band to band absorption				Thermoelectricity in metals											

	SLO-2	Estimation of the position of the Fermi energy and the resistivity	Dielectric studies and the Cole-Cole plot	Magnetostriction and domain wall motion	Direct and indirect transitions	Seebeck effect and the figure-of-merit
S-6	SLO-1	The temperature dependence of carrier concentration	Dielectric strength and insulation breakdown	Magnetic domains in polycrystalline materials	Light scattering in materials, attenuation in optical fibers	Thermoelectricity in semiconductors
	SLO-2	The temperature dependence of drift mobility	Dielectric breakdown mechanisms	Understanding the M versus H hysteresis curve	Luminescence, phosphors, and white LEDs	Overview of thermoelectric devices
S-7	SLO-1	Degenerate and nondegenerate semiconductors	Capacitor dielectric materials	Demagnetization	Spontaneous and stimulated emission	Two-dimensional electronic materials
	SLO-2	Direct and indirect recombination	Typical capacitor constructions	Soft and hard magnetic materials: Examples and uses	Laser materials and laser action	The Era of graphene and related materials
S-8	SLO-1	Minority carrier life time	Piezoelectricity	Superconductivity, Type I and Type II superconductors	Concept of photoluminescence and electroluminescence	Electronic properties at 2D limit
	SLO-2	Carrier injection and diffusion	Piezoelectric spark generator and quartz crystal	Critical current density and superconducting solenoids	Examples for devices working on the principles of PL and EL	Optical properties- layer dependence
S-9	SLO-1	Optical absorption in semiconductors	Ferroelectricity and pyroelectricity	Josephson effect	Electro-optic effects and applications	2D materials based metal, semiconductor and dielectrics
	SLO-2	Direct and indirect band gap semiconductors and the E-k diagram	Practical Applications	Introduction to anisotropic and giant magnetoresistance	Magneto-optic effects and applications	Applications and future perspectives

Learning Resources	1. S O Kasap, "Principles of Electronic Materials and Devices" – McGraw Hill, Fourth Edition, 2017	4. David K. Ferry, Jonathan P. Bird "Electronic Materials and Devices" – Academic Press, First Edition, 2011.
	2. Wei Gao, Zhengwei Li, Nigel Sammes, "An Introduction to Electronic Materials for Engineers" – World Scientific Publishing Co. Pte. Ltd, Second Edition, 2011	
	3. David Jiles, "Introduction to the Electronic Properties of Materials: - Nelson Thomes Ltd, Second Edition, 2001	5. Yuriy M Poplavko, "Electronic Materials: Principles and Applied Science" – Elsevier, First Edition, 2019
		6. Rolf E. Hummel, "Electronic Properties of Materials: An Introduction for Engineers" – Springer, 1993

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course designers		
Experts from Industry		Experts from Higher Technical Institutions
1. Dr. D.K. Aswal, National Physical Laboratory, dkaswal@nplindia.org		1. Prof. K. Sethupathi, IITM Chennai, ksethu@iitm.ac.in
2. Dr. S. Sudhakar, CSIR-CECRI, sudhakar@cecri.res.in		2. Prof. S. Balakumar, University of Madras, balakumar@iunom.acs.in
		Internal Experts
		1. Dr. S. Chandramohan, SRMIST
		2. Dr. E. Senthil Kumar, SRMIST

Course Code	18NTE317T	Name	NANOCATALYSTS	Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Offering Department	Nanotechnology	Data Book / Codes/Standards	Nil		

Learning Rationale (CLR):		The purpose of learning this is to:		Learning		
CLR-1 :	Acquire the concepts of chemistry of nanocatalyst			1	2	3
CLR-2 :	Understand the catalytic kinetics			Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)
CLR-3 :	Describe the reaction kinetics of adsorption and desorption processes					
CLR-4 :	Understand the principles behind the synthesis of nanocatalyst					
CLR-5 :	Gain knowledge about the working mechanism of nanocatalytic materials					
CLR-6 :	Describe catalytic processes at nano-levels					
Learning Outcomes (CLO):		At the end of this , learners will be able to:				
CLO-1 :	Describe the mechanisms of nanomaterials for using as catalyst			2	80	75
CLO-2 :	Apply the importance of the bottom-up approach to prepare nanomaterials			2	80	70
CLO-3 :	Identify the photocatalyst for environmental remediation			2	75	70
CLO-4 :	Analyze the working of noble metal nanocatalyst			2	80	75
CLO-5 :	Evaluate the needs and future possibilities of nanocatalyst			2	80	70
CLO-6 :	Apply isotherms for different micro and nano porous catalytic materials			2	80	75

Program Learning Outcomes (PLO)														
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
H	M	H	H	H	M	M	H	H	H	M	H	H	H	H
H	M	M	H	M	M	M	H	M	H	L	H	M	M	M
H	M	H	H	M	H	H	M	H	H	H	H	H	H	H
M	H	H	M	H	H	H	H	H	H	M	H	H	H	H
H	M	H	H	H	M	M	H	M	H	L	H	H	H	H
H	M	M	H	M	M	M	H	H	M	H	H	H	M	H

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction to catalysis	Adsorption and Desorption Processes	Kinetics and photocatalytic activity	Catalyst in Nanoscale	Applications of Nano-Catalyst
	SLO-2	Classifications	Adsorption Rate	Introduction to photocatalyst	Noble metals nanocatalyst (Ru, Rh, Pd, Pt, etc)	Toxic Gases conversion using nanocatalyst: NOx
S-2	SLO-1	heterogeneous catalysis	Desorption Rate	Basics of electrochemistry	Polymer stabilized Rh and Ru nanoparticles	CO oxidation using nanocatalyst
	SLO-2	Reaction on the solid surfaces	Catalytic activity (bulk and nanoscale)	Photochemistry	Oxide supports for nano-catalysts; carbon supports for nano-catalysts	Hydrogenation of compounds with C≡C bonds, hydrogenation of aromatic compounds
S-3	SLO-1	Active sites- Activation energy	Catalytic activity determination for metal/metal oxide nanostructures	Electronic structure and photoabsorption	Gold nanoparticle-based catalyst	Green house gases: CO2 conversion
	SLO-2	Adsorption isotherms	Langmuir-Hinshelwood mechanism for nanocatalyst	Jablonskii diagram	Gold vs. Palladium catalysts for the aerobic oxidation of alcohols	Dissociative mechanism: oxygen reduction reaction using nanocatalyst
S-4	SLO-1	Physisorption and chemisorptions	Mass transport	Structure of photocatalysts	Oxide based catalyst	Associative mechanism: oxygen reduction reaction using nanocatalyst
	SLO-2	Brunauer-Emmett-Teller (BET) theory	Diffusion controlled process	Solar spectrum	Metal free catalyst (CNT, Graphene based Catalyst)	Hydrogen Production using oxide and dichalcogenides based catalyst
S-5	SLO-1	Total surface area	Adsorption equilibrium on uniform surfaces-Langmuir isotherms single-site (non-dissociative) adsorption	Fundamental understanding of semiconductor interfaces	Transition metal dichalcogenides based catalyst	Energy processing: Processes involved in crude oil refinery
	SLO-2	Pore volume and pore size distribution	Dual-site (dissociative) adsorption	Principles and relevance to photoelectrochemical mechanism	Microporous materials: Zeolites- Zeotypes	Gasoline production
S-6	SLO-1	Hg porosimetry method	Derivation of the Langmuir isotherm	Photocatalysis mechanism	Overall steps in zeolite crystallization	Cracking

	SLO-2	N ₂ adsorption-desorption method	Adsorption equilibrium on non-uniform surfaces-Langmuir isotherms	Properties of good photocatalysts	Zeolite synthesis via.- dry gel route	Fuel cell
S-7	SLO-1	Reaction mechanism	The Freundlich isotherm	Advantages of photocatalysts	Zeolite Y- determination of surface acidity-	Biomass gasification
	SLO-2	Kinetics of the heterogeneous catalytic reactions	The Temkin Isotherm	Types of photocatalysts	Shape-selectivity	Biodiesel
S-8	SLO-1	Activation energy (Arrhenius equation, Eyring equation)	Activated adsorption	Homogeneous and heterogeneous photocatalyst	Synthesis of Mesoporous Silica MCM-41	Photocatalyst for self cleaning
	SLO-2	Terminology in catalysis, TO(Turnover), TON(Turnover number), TOF(Turnover frequency)	Catalytic efficiency	Carbonaceous photocatalysts.	Mesoporous Carbon	Purification of water and air
S-9	SLO-1	Sequences involved in a catalysed reaction	Application of metal nanoparticles in organic reactions	Plasmonic photocatalysts.	Sulfated Zirconia	Environmental remediation
	SLO-2	Asymmetric synthesis using a catalyst	Environmental remediation	Application of photocatalyst	Ag/SiO ₂ composite nanocatalysts	Future possibilities

Learning Resources	1. M. Albert Vannice, <i>Kinetics of Catalytic Reactions</i> , Springer, 2008.	3. Kurt W. Kolasinski, <i>Surface Science: Foundations of Catalysis and Nanoscience</i> , John Wiley & Sons, England, 2 nd Edition, 2005
	2. Nick Serpone and Ezio Pelizzetti, <i>Photocatalysis: Fundamentals and Application</i> , Wiley Interscience, 1 st Edition, 1989	4. Nanoporous Materials: <i>Synthesis and Applications</i> , Edited by Qiang Xu, CRC Press, 1 st Edition, 2013

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.

Course Designers		
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		Internal Experts
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Course Code	18NTE318T	Course Name	NANO AND MICRO EMULSIONS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Nanotechnology	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Acquire knowledge on micro and nano emulsion and its stability	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Understand the various properties of emulsion	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Describe the concept of Mechanism of Emulsification	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Understand the formulation of Nano emulsion	Expected Attainment (%)	Design & Development
CLR-5 :	Learn the applications of emulsion for various fields		Analysis, Design, Research
CLR-6 :	Understand the principles of NMR and Ultrasound characterization		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Explore basic principles in chemistry of microemulsions	2 80 75	H M H H H M M H H H M M H H
CLO-2 :	Explain properties of emulsion by concept of phase diagram	2 80 70	H M M H M M M H M H M H M M M
CLO-3 :	Analyze the stabilization mechanism in emulsions	2 75 70	H M H H H H H M H M H H H H
CLO-4 :	Apply the formulation of micro and nano emulsions	2 80 75	M H H M H H H H H H M M H H
CLO-5 :	Elucidate importance of emulsions in various technological applications	2 80 70	H M H H H M M H M H M H H H
CLO-6 :	Utilize the knowledge on formulation and characterization of microemulsions	2 80 75	H M M H M M M M H H M H M M

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Introduction to Emulsion	A phase diagram approach to microemulsion	Mechanism of Emulsification	Nanoparticle formation in microemulsion
	SLO-2	Introduction to Micro and Nano Emulsion	Partial generic phase diagram	Surface forces	Concept of formation in microemulsion:
S-2	SLO-1	Definition of micro emulsion	Microemulsion formation	Van der walls interactions	Chemical Reaction
	SLO-2	Definition of nano emulsion	Ordering and disordering	Electrical interactions	Nucleation
S-3	SLO-1	Theory of emulsion and methods	Temperature Dependence of microemulsion ordering	Phase inversion phenomena	Exchange mechanism in emulsions
	SLO-2	Theory of Micro emulsions	Vapor Composition from Microemulsions	Phase behavior of emulsions	Autocatalysis
S-4	SLO-1	Theory nano emulsions	Ekwall on the association structures	Standard inverse boundary	Mechanism of microemulsion
	SLO-2	Preparation of microemulsion	Water-surfactant combination	Dynamic inversion	Critical Nucleus Size
S-5	SLO-1	Preparation of nano emulsion	Physicochemistry of W/O microemulsion formation	Dynamic behavior of emulsion	Chemical Reaction Rate
	SLO-2	Winsor's classification of microemulsions	Stability of emulsions	Spontaneous emulsification	Nanoparticles uptake from W/O emulsion
S-6	SLO-1	Stability of micro emulsions	Droplet clustering	Recent development with emphasis on self emulsification,	W/O emulsion process

	SLO-2	Rheology of microemulsion drops	Energetics of Droplet Clustering	Self-emulsification process	Nanoparticle Uptake in Reactive Surfactant Systems	Pharmaceutically applicable microemulsions
S-7	SLO-1	Applications of emulsions	Phenomenon in microemulsion	Organic Reactions in Emulsions	Nanoparticle Uptake in Nonreactive Surfactant Systems	Places of microemulsion and emulsion in cancer therapy
	SLO-2	Ostwald ripening	Percolating phenomenon in microemulsion	Microemulsions	TiO ₂ nanoparticle in micro-emulsion and photophysical properties	In vitro and in vivo evaluation
S-8	SLO-1	Flocculation	Scaling Laws	Symmetric thin liquid film with Fluid interfaces	Optical Absorption and Emission of TiO ₂ Nanoparticles in Microemulsion	Biocatalysis in microemulsion
	SLO-2	Coalescence of drops	Effect of external entity-Microemulsions with mixed nonionic surfactants	Formation emulsified microemulsion	Electron Transfer Dynamics in Catechol-Sensitized TiO ₂ Nanoparticles	Biofluidic Matrices
S-9	SLO-1	Applications of emulsions	Organ chalcogenides, Aromatic Heterocyclic Compounds	Microemulsion properties	Properties of interfacial electron transfer dynamics	Microemulsions as Decontamination Media for Chemical weapons
	SLO-2	Different application of micro and Nano emulsions	Properties of microemulsions with mixed nonionic surfactants	Characterization of emulsified microemulsion	Interfacial electron transfer dynamics	Microemulsions as toxic Industrial Chemicals

Learning Resources	1. Fanun, Monzer., <i>Microemulsions: properties and applications</i> , CRC press, 2008. 2. Sjoblom, Johan., <i>Emulsions and emulsion stability: Surfactant science series/61</i> . CRC Press, 2005.	3. Berg J. C., <i>An Introduction to Interfaces and Colloids: The Bridge to Nanoscience</i> , World Scientific, 2010
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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2. Dr. D.K. Aswal, National Physical Laboratory, dkaswal@nplindia.org	2. Dr. S. Ramaprabhu, IITM, ramp@iitm.ac.in	2. Dr. N. Venkatramaiah, SRMIST

Course Code	18NTE401T	Course Name	NANORBOTICS			Course Category	E	Professional Elective				L	T	P	C
												3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department		Nanotechnology		Data Book / Codes/Standards	

Course Learning Rationale (CLR):		The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :		Provide an insight into the fundamentals of nanorobotics manipulation and assembly	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :		Gain scientific understanding regarding the role of nanorobotics in the modern engineering applications																		
CLR-3 :		Understand the concept of nanomanipulation of nanostructures																		
CLR-4 :		Learn the techniques of automated manipulation of nanoobjects																		
CLR-5 :		Gain knowledge on theoretical and experimental aspects of Nanorobotics																		
CLR-6 :		Understand the principles of nanomicroscopy																		

Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :		Apply the scientific concepts underlying engineering and technological applications in nanorobotics				H	M	H	H	H	M	M	H	H	M	M	H	H	H	H
CLO-2 :		Acquire the knowledge of nanorobotics manipulation				H	M	M	M	M	M	M	H	M	H	M	H	M	M	M
CLO-3 :		Apply the knowledge of fast imaging system for advance nanotechnology applications				H	M	H	H	H	H	H	M	H	H	H	M	H	H	H
CLO-4 :		Get familiarize with the new concepts of real-time nanomanipulation				M	H	H	M	H	H	H	H	H	M	M	H	H	H	H
CLO-5 :		Apply the concept of nanorobotics assembly using CAD				H	M	H	H	H	M	M	H	M	H	M	M	H	H	H
CLO-6 :		Utilize the concept of nanobots for Medical applications				H	M	M	H	M	M	M	H	H	H	M	H	H	M	M

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Types of interaction forces	Dielectric materials	Sensors-classifications	computer-aided design (CAD)
	SLO-2	Interaction forces in nanomanipulation	Dielectric polarization	Art of compressive sensing	CAD models of nanostructures
S-2	SLO-1	Actuation	Electro rotation	Fast imaging system	Automated manipulation of micro-nano objects
	SLO-2	Electro kinetic based actuation	Theory and modelling of electro rotation	Compressive sensing based fast imaging system	Automated manipulation of nanostructures
S-3	SLO-1	Carbon nanotubes	Properties of fluid medium	SPMbasics	Automated manipulation of Nanorods
	SLO-2	Electro kinetic manipulation of carbon nanotubes	Dynamic effects of fluid medium	AFM based imaging	Automated manipulation of Nanowires
S-4	SLO-1	Graphene sheets	Dielectrophoretic	Atomic manipulation in AFM	Automated manipulation of nanotubes
	SLO-2	Nanoparticles	Nanoparticles by dielectrophoretic	AFM based nanorobotic system	Automated manipulation of nanoparticles
S-5	SLO-1	Biological entities	CNT-definition	Augmented reality	Augmented reality system
	SLO-2	Biological nanomaterials	Manipulation of CNT	AFM based nanorobotic system enhanced by augmented reality	Limitation of augmented reality system
S-6	SLO-1	Laser based actuation-fundamentals	Scanning probes	Hardware setup for Sensing	Real time fault detection
	SLO-2	Laser based actuation-applications	Nanomanipulation by scanning probe	Software setup for Sensing	Methods of real time fault correction

S-7	SLO-1	Optical tweezers	Atomic scale stick-definition	Hardware setup for fast imaging system	Time random drift	Drug delivery system
	SLO-2	Applications of optical tweezers	Reducing atomic scale stick	Software setup for fast imaging system	Time random drift compensation with local scan	Cooperative control design for nanorobots in drug delivery
S-8	SLO-1	Manipulation of biological entities	Slip motion	Experiments on nanomanipulation of nanoparticles-I	on-line fault detection	Medical applications of nanorobots
	SLO-2	Manipulation of chemical entities	Nanomanipulation by slip motion	Experiments on nanomanipulation of nanoparticles-II	Interpretation of on-line fault correction	Medical applications of nanorobots: current proposals and designs
S-9	SLO-1	Piezoelectricity	Feedback control	Experiments on nanomanipulation of nanoparticles-III	Implementation of the data to test the hypothesis	Therapy using nanorobots
	SLO-2	Piezoelectric enabled actuators	Slip motion by feedback control nanomanipulation	Experiments on nanomanipulation of nanoparticles-IV	Experimental results of the data to test the hypothesis	Cancer targeted therapy using nanorobots

Learning Resources	1. Ning Xi, Guangyoung Li, "Introduction to Nanorobotic Manipulation & Assembly" Artech House Press, 2012	3. Klaus D. Sattler, "Hand Book of Nanophysics: Nano medicine & Nanorobotics", CRC Press, 2010
	2. Yi Guo, "Selected Topics in Micro/Nano-robotic for Biomedical Applications", Springer, 2013	

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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2. Dr. A. Pandikumar, Scientist, CSIR-CERL, pandikumar@cecri.res.in	2. Prof. D. Arivuoli, Anna University, arivuoli@annauniv.edu	2. Dr. V. Kathirvel, SRMIST

Course Code	18NTE402T	Course Name	MICRO AND NANOFUIDS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Offering Department	Nanotechnology	Data Book / Codes/Standards	Nil		

Learning Rationale (CLR):		The purpose of learning this is to:		
CLR-1 :	Acquire knowledge on various physical principles related to liquid flow			
CLR-2 :	Understand theory of fluid flow in micro and nano-size devices.			
CLR-3 :	Describe the concept of heat and mass transfer phenomena in channel			
CLR-4 :	Unifies thermal sciences with colloidal sciences, biological sciences			
CLR-5 :	Gain knowledge on electrochemistry			
CLR-6 :	Understand the applications of micro and nanofluidics			

Learning Outcomes (CLO):		At the end of this , learners will be able to:		
CLO-1 :	Apply the principles of liquid flow			
CLO-2 :	Analyze flow of fluid in micro and nano-size devices			
CLO-3 :	Apply the knowledge of micro and nanofluidic devices, their fabrication, charecterization			
CLO-4 :	Utilize the opportunities in the emerging field of micro and nanofluids			
CLO-5 :	Apply the concept electrochemistry			
CLO-6 :	Utilize the new concepts of real-time nanomanipulation & assembly			

Learning		
1	2	3
Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)

Program Learning Outcomes (PLO)														
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
H	M	H	H	H	M	M	H	H	H	M	H	H	H	H
H	M	M	H	M	M	M	M	M	M	H	M	H	M	M
H	M	H	M	M	H	H	M	H	H	H	H	H	H	H
M	H	H	M	H	H	H	H	H	H	M	H	H	H	H
H	M	H	H	M	M	H	H	M	H	M	H	H	H	H
H	M	M	M	H	M	M	M	H	H	M	H	H	M	H

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Microscale liquid flow - Introduction	Microscale viscous flow - Essentials	Heat transfer phenomena in channels and tubes	Elements of electrochemistry and the electrical double layer - introduction
	SLO-2	Micro and Nanofluidics	Structure of flow in a pipe or channel	Mass transfer phenomena in channels and tubes	The structure of water and ionic species
S-2	SLO-1	Micro and Nanofluidics devices	Poiseuille flow in a pipe	One-dimensional temperature distributions in channel flow	Chemical bonds in biology and chemistry
	SLO-2	Design of micro and Nanofluidics devices	Poiseuille flow in a pipe – derivation of maximum velocity	Temperature distributions in channel flow (Quantitative approach)	Hydration of ions
S-3	SLO-1	Preparatory concepts	The velocity in slip flow - gases	Thermal and mass transfer entrance regions	Chemical potential
	SLO-2	Constitutive Laws	The velocity in slip flow - Liquids	Mass transfer entrance regions	Chemical potential (Quantitative approach)
S-4	SLO-1	Determination of transport properties – viscosity, diffusion coefficients	Flow in a thin film under gravity	The temperature distribution in fully developed tube flow	The Gibbs function
	SLO-2	Determination of transport properties – thermal conductivity	Flow in a thin film under gravity – film flow rate	Nusselt number	Chemical equilibrium
S-5	SLO-1	Classification of fluid flows	Fully developed suction flows	The Graetz problem for a channel	Electrochemical potential
	SLO-2	Continuum approximation and its limitations	Velocity profile – suction flow	The Graetz problem for a channel (Quantitative approach)	Acids, bases, and electrolytes
S-6	SLO-1	Kinematics - Surface forces	Developing suction flows	Mass transfer in thin films	Site-binding models of the silica surface

	SLO-2	Body forces	Darcy's law	A thin liquid film falling under gravity	Polymer surfaces	DNA current
S-7	SLO-1	Navier-Stokes equation	Surface tension driven flow	Classical Taylor-Aris dispersion	Qualitative description of the electrical double layer -	Development of an artificial kidney : Background
	SLO-2	Navier-Stokes equations in Cartesian coordinates	Surface tension driven flow (Quantitative approach)	Classical Taylor-Aris dispersion (Quantitative approach)	Qualitative description of the electrical double layer - triple layer model	The nanopore membrane for filtration, Hindered transport
S-8	SLO-1	Energy transport	Stokes flow past a sphere	The stochastic nature of diffusion	The electrical double layer on a cylinder	Biochemical sensing : Biosensor, Receptor -based classification of biosensors
	SLO-2	Energy transport - conduction heat transfer	Stokes flow past a sphere – drag calculation	Brownian motion	The electrical double layer on a sphere	Transducer-based classification of biosensors
S-9	SLO-1	Two-dimensional, Steady flow	Sedimentation of a solid particle	Unsteady mass transport in uncharged membranes	Electrical conductivity in an electrolyte solution.	Evaluation of biosensor performance
	SLO-2	Incompressible flow	Simple model for blood flow	Temperature and concentration boundary layers	Electrophoretic effect	Nanopores and nanopore membranes for biochemical sensing.

Learning Resources	<ol style="list-style-type: none"> 1. Terrence Conlisk "Essential of Micro and nanofluidics: with applicationsto biological and chemical sciences" Cambridge University Press, 2018. 2. Joshua Edel "Nanofluidics" RCS publishing, 2016. 3. Henrik Bruus "Theoretical Microfluidics" Oxford Master Series in Physics, 2007. 4. Patric Tabeling "Introduction to Microfluids" Oxford U. Press, 2005. 5. Christ of M. Niemeyer & Chad A. Mirkin, "Nanobiotechnology: Concepts, Application and Perspectives", Wiley VCH, 2004. 6. Sarit K.Das, Stephen U.S. Choi, Whenhua Yu & T. Pradeep, "Nanofluids Science and Technology" Wiley Interscience, 2007.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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2. Mr. Mohammed Shafi, Holmarc Opto-Mechatronics Pvt. Ltd, Cochin, optics@holmarc.com	2. Dr. Dillip K. Satapathy, IITM, Chennai, dks@iitm.ac.in	2. Dr. Surya K Ghosh, SRMIST

Course Code	18NTE403T	Course Name	NANOTECHNOLOGY FOR ENERGY SYSTEMS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Offering Department	Nanotechnology	Data Book / Codes/Standards	Nil		

Learning Rationale (CLR):		The purpose of learning this is to:		
CLR-1 :	Learn the importance of renewable energies for the safe survival of human kind on the earth			
CLR-2 :	Understand the basics of green energy production, storage and transport			
CLR-3 :	Understand how nanotechnology can improve the green energy production from various sources			
CLR-4 :	Explore the methods of hydrogen production and storage			
CLR-5 :	Acquire knowledge on the fabrication, characterization of nanomaterials useful for energy production, transportation and storage			
CLR-6 :	Acquire knowledge on design, fabrication, characterization of advanced energy systems			

Learning Outcomes (CLO):		At the end of this , learners will be able to:		
CLO-1 :	Identify the urgency of energy solutions and the expectations of Nanotechnology in providing long term solutions to these problems	2	80	75
CLO-2 :	Describe the concepts of heterogeneous catalysis, and further apply in the designing of various nanocatalysts for energy applications	2	80	70
CLO-3 :	Apply Nanotechnology and nanomaterials in the designing of solar energy conversion systems and fuel cell technologies	2	75	70
CLO-4 :	Apply the Nanotechnology and nanomaterials for energy storage technologies	2	80	75
CLO-5 :	Apply the thermoelectric principles and nanotechnology to design high figure-of-merit thermoelectric devices	2	80	70
CLO-6 :	Apply Nanotechnology in the sensing and remediation of pollutants in air and water	2	80	75

Learning		
1	2	3
Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)

Program Learning Outcomes (PLO)														
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
H	M	H	H	H	H	M	H	H	H	M	H	H	H	H
H	M	M	H	M	M	H	H	M	M	H	H	M	M	M
H	M	H	H	H	H	H	M	H	M	H	H	H	H	H
M	H	H	M	H	H	H	H	H	M	M	H	H	H	H
H	H	H	H	H	M	M	M	M	H	H	H	H	H	H
H	H	M	H	H	M	M	M	H	H	M	H	H	M	H

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Energy Challenge in the 21st Century	Terawatt challenges in photovoltaics	Bulk thermoelectric materials	Low temperature fuel cells
	SLO-2	Fuel share of world total primary energy supply	How can photovoltaics meet a significant fraction of energy demand?	Basics of thermoelectricity, Seebeck effect, Peltier effect, Figure of merit, Wiedemann-Franz relationship	Impact on nanostructured materials, development of low-temperature fuel cells
S-2	SLO-1	Nanotechnology in energy research	Limits in conversion efficiency	Bulk thermoelectric materials- size effects, Selection criteria for bulk thermoelectric materials	Cathode and anode reaction
	SLO-2	The importance of nanotechnology in improving the nanoscale energy devices	Theoretical limits of photovoltaics efficiency and possible improvements by different approaches	Important three guidelines	Oxygen reduction reaction, cathodic reactions, reactions at anode surface
S-3	SLO-1	Conventional fossil fuels	Hybrid concepts	Effect of size of the quantum dots, nanowires on the conversion efficiency, classical and quantum size effects	Practical fuel cell catalysts and Electrolytes
	SLO-2	Unconventional fossil fuels	Combining organic and inorganic cells, concept of heterojunction-type photoactive layer, hole-electron pair	Thermoelectric properties on nanoscale: modeling	Nanostructured materials in low-temperature cell, Non-precious catalysts, electrolytes
S-4	SLO-1	Nanotechnology in fuel production	Semiconductors optical properties	Understanding thermoelectric properties on the nanoscale using modeling	High-temperature polymer electrolyte membranes, membrane-electrode assembly
	SLO-2	Making efficient and economical engines	Basics of semiconductors, bandgap	Importance of characteristic length scale, Bi nanostructures	High temperature fuel cells
					Introduction to contribution of nanotechnology to hydrogen production
					Methods of hydrogen production, Importance of hydrogen energy
					Nanomaterial based photoelectron chemical cell
					Nanocrystalline thin films of metal oxides in PEC solar cells, Water splitting for producing hydrogen
					Semiconductors with specific morphology such as nanotubes and discs for production of hydrogen
					Sensitization, Hydrogen storage: technological barriers
					Methods of improving efficiency of cells, HOMO-LUMO gap, several examples of sensitization
					Hydrogen storage technology –potential storage materials hydrogen sorption

S-5	SLO-1	Renewable energy sources- Photovoltaics	charge carrier transport in semiconductors	Importance of Bi nanowire and its diameter in thermoelectricity	Development of cells that operate up to 700°C	Hydrogen storage by Physiosorption and chemisorption methods
	SLO-2	Emission spectra and color as a function of particle size of a quantum dot	Optical properties of semiconducting thin films, Optical absorption	Silicon nanowire and importance at nanoscale	High temperature ceramic electro catalysts	Properties of materials: physical storage, thermodynamic and kinetics
S-6	SLO-1	Example of nc-CdTe film on ITO-coated glass solar cell	Narrow and wide band gap materials, importance of optical absorption	How surface roughness effects thermal conductivity. Phonon effects on the Seebeck coefficient and thermal conductivity	Electrochemical reaction at high temperatures, triple phase boundary	Bond strengths for Physiosorption and chemisorption, The desirable range of bonding energies
	SLO-2	Gratzel Cell Examples of nanostructured films used for PV cells	Selection of Dye sensitizer for better optical absorption, n-CdS band gap	Thermionics nanocomposites	Porous Ni-Ceramic electrolyte (YSZ), LaSrMnOe ceramic electrolyte	Nanostructured carbon
S-7	SLO-1	Hydrogen production	Dye molecular engineering	Description of electron motion across the barrier	Application of high temperature ceramic electro catalysts	MWNT, SWNT, carbon nanorods and aerogels etc.
	SLO-2	Mechanisms of dye sensitization and sensitization by composite semiconductors	HOMO-dye, LUMO gap	Si/SiGe superlattice nanowire, prototype InP/InAs superlattice nanowire	Various examples of high temperature fuel cells where ceramic electro catalysts are used	zeolites- clathrates- polymers
S-8	SLO-1	Hydrogen energy system. Advantages of hydrogen fuel	Stable self-assembling dye. Monomolecular layer	Thermoelectric nanocomposites	Solid oxide fuel cells (SOFCs)	Reversible occlusion of gases. Metal-organic frame works and their storage efficiency
	SLO-2	Fuel cells, REDOX potentials, electrochemical reactions in different types of fuel cells	Structure of the Z-907 amphiphilic Dye	PbTe-PhSeTe quantum dot	Mechanical properties, Efficiency, operating temperatures	Metals and complex hydrides- chemical hydrides nanocomposites
S-9	SLO-1	Microbial fuel cells, polymer electrolyte fuel cells	Electron transfer mechanism from TiO2 to Dye, Dye excitation and relaxation mechanisms	PbTe-PbSe bulk alloys, superlattice systems	Dry hydrocarbons in SOFC	Hydrogen storage by chemisorption, basic structures of metal and complex hydrides, chemical hydrides, Nanocomposites
	SLO-2	Introduction to Thermoelectricity	The nanostructured semiconductors	Application of thermionic and thermoelectric nanocomposites	Applications of Fuel cells	Some examples of storing hydrogen with the above materials

Learning Resources	1. Javier Garcia-Martinez, Nanotechnology for the Energy Challenge, WILEY-VCH Verlag GmbH & Co., 2010 2. Anatoli Korkin, David J, Nanoscale Applications for Information and Energy Systems, Springer, 2013	3. Darren P. Broom, Hydrogen Storage materials: The characterization of their properties, Springer, 2011
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Understand	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Apply										
Level 3	Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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2. Dr. Krishna Surendra Muvvala, Saint Gobain Research India, India, Krishna.muvvala@saintgobain.com	2. Prof. M. Ghanashyam Krishna, UOHYD, mgksp@uohyd.ernet.in	2. Dr. K. Kamalabharathi, SRMIST

Course Code	18NTE404T		Course Name	PHOTOVOLTAIC TECHNOLOGY		Course Category	E	Professional Elective					L	T	P	C
													3	0	0	3

Pre-requisite Courses	Nil		Co-requisite Courses	Nil		Progressive Courses	Nil	
Course Offering Department		Nanotechnology		Data Book / Codes/Standards		Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :		Learn the basic principles and design of photovoltaic cell technology			1 2 3			1 2 3 4 5 6 7 8 9 10 11 12 13 14 15														
CLR-2 :		Understand the key properties of semiconductors used in photovoltaic technology			Level of Thinking (Bloom) Expected Proficiency (%) Expected Attainment (%)			Engineering Knowledge Problem Analysis Design & Development Analysis, Design, Research Modern Tool Usage Society & Culture Environment & Sustainability Ethics Individual & Team Work Communication Project Mgt. & Finance Life Long Learning PSO - 1 PSO - 2 PSO - 3														
CLR-3 :		Learn about basic photovoltaic device structure and design																				
CLR-4 :		Develop an understanding of the primary photovoltaic device technologies and their design																				
CLR-5 :		Gain exposure to the various applications of photovoltaics																				
CLR-6 :		Acquire knowledge on advanced concepts explored in photovoltaics																				
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :		Differentiate between different types of photovoltaic technologies			2 80 75			H H H H H H M H H H H H H H H H H H														
CLO-2 :		Interpret important properties of semiconductors relevant to photovoltaics			2 80 70			H H M H M H M H M H H H H M M M														
CLO-3 :		Apply different photovoltaic device design concepts for different applications			2 75 70			H H H H H H H M M M H H H H H H														
CLO-4 :		Appreciate advancement of different generations of solar cells			2 80 75			M H H M H H H H H H H H H H H H														
CLO-5 :		Appreciate the advanced concepts and explorations in photovoltaics			2 80 70			H M H H H M M H M H H H H H H H														
CLO-6 :		Perform photovoltaic device testing and calculations			2 80 75			H M M H H M M H M H M H H M M H														

Duration (hour)		9		9		9		9		9	
S-1	SLO-1	Renewable energy technologies	Optical absorption	Solar Cell parameters		Si photovoltaics		III-V photovoltaics			
	SLO-2	Present and future global issues	Carrier photogeneration	Device testing		Fabrication of Si solar cells		Multi-junction solar cells			
S-2	SLO-1	Historical development of PV; drivers-	Band gap	Efficiency calculations		High efficiency single crystal Si solar cells		Spectral splitting			
	SLO-2	Commercialization/economic factors	Direct vs. indirect bandgaps	(EFF, VOC, JSC) for ideal cells		Si PV designs		GaInP/GaAs/Ge triple junction solar cell			
S-3	SLO-1	Basic components of PV systems	Minority carrier transport properties -	Non-idealities		Polycrystalline/microcrystalline Si solar cells		Bandgap profile optimization			
	SLO-2	Mechanism of PV	Carrier recombination-lifetime and defects	Series resistance, shunt resistance		Amorphous Si solar cells		Solar spectrum matching			
S-4	SLO-1	Sun as a source of energy	Band to band and Shockley-Read-hall	Optical loss mechanisms		Heterojunctions - review		Tunnel junctions			
	SLO-2	The solar spectrum	High injection effects	Implications on device performance		p-i-n and n-i-p structures		Current matching limitations			
S-5	SLO-1	Measuring sun light	Surface and interface recombination	Electrical loss mechanisms		Thin film II-VI solar cells		Concentrator photovoltaics (CPV)-			
	SLO-2	Atmospheric effects	Implications on device performance	Implications on device performance		Chalcopyrite photovoltaics		Concentrator optics,			
S-6	SLO-1	Terrestrial and space spectra;	PN homojunctions	Basics of solar cell device design		CdTe/CdS thin film solar cells		CPV cells			

	SLO-2	Air mass (AM0, AM1.5)	Carrier transport under broad spectrum illumination	Minimization of losses	Superstrate structure	Terrestrial CPV systems
S-7	SLO-1	Classification of photovoltaic technologies	Photocurrent	Lateral design and Vertical design	CuInGaSe ₂ /CdS thin film cell technologies	Space photovoltaics
	SLO-2	Generations of solar cells	Spectral response	Cyclotron frequency	Earth abundant alternatives	Radiation effects in semiconductors and solar cells
S-8	SLO-1	1st generation photovoltaics	Current transport models	Optical versus electrical tradeoffs and optimization	Dye-Sensitized solar cells	New concepts
	SLO-2	Silicon technology	Non idealities	Band gap and other material properties	QDSSCs	Quantum dots, wires
S-9	SLO-1	2nd generation photovoltaics	Real p-n diodes	Spectral utilization	Organic photovoltaics	Intermediate band solar cells
	SLO-2	3rd generation photovoltaics	Temperature effects	Light management	Hybrid solar cells	Multiple exciton generation

Learning Resources	1. Solanki C.S., "Solar photovoltaics - fundamentals, technologies and applications", 3rd edition, PHI Learning Pvt Ltd, New Delhi, India 2. Fonash S.J., "Solar Cell Device Physics", Academic, 2010	3. Moller H.J., "Semiconductors for Solar Cells", Artech House, 1993. 4. Green M.A., "Third Generation Photovoltaics: Advanced Solar Energy Conversion", Springer, 2006 Fundamentals of Solid State Engineering, Manijeh Razeghi, KLUWER ACADEMIC PUBLISHERS, 2002
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. D.K. Aswal, National Physical Laboratory, dkaswal@nplindia.org	1. Dr. Sudhakar Chandran, IIT Madras, csudhakar@iitm.ac.in	1. Dr. S Venkataprasad Bhat., SRMIST
2. Dr. S. Sudhakar, CSIR-CECRI, sudhakar@cecri.res.in	2. Dr. M. S. Ramachandra Rao, IIT Madras, msrrao@iitm.ac.in	2. Dr. P. Malar, SRMIST

Course Code	18NTE405T	Course Name	NANOTECHNOLOGY IN COSMETICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Offering Department	Nanotechnology	Data Book / Codes/Standards	Nil		

Learning Rationale (CLR):		The purpose of learning this is to:			Learning														
		1	2	3	Program Learning Outcomes (PLO)														
		Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-1 :	Understand the basis of cosmeceuticals				Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-2 :	Know the classification and various types of cosmetics																		
CLR-3 :	Acquire knowledge about ingredients and effect of inclusion of nanoparticles in cosmetics																		
CLR-4 :	Get acquainted with current trends in the field of nano based cosmetics																		
CLR-5 :	Get acquainted with future aspects of cosmetics																		
CLR-6 :	Get acquainted with future aspects of aesthetic implants																		
Learning Outcomes (CLO):		At the end of this , learners will be able to:																	
CLO-1 :	Apply basic concepts of nanotechnology in cosmetics	2	80	75	H	M	H	H	H	M	M	H	H	H	M	H	H	H	H
CLO-2 :	Distinguish effects of using nanoparticles over conventional methods in cosmetics	2	80	70	H	M	H	H	M	M	M	H	M	H	M	H	M	M	M
CLO-3 :	Analyze about current trends in the field of cosmetics	2	75	70	H	M	H	H	H	H	H	M	H	H	H	H	H	H	H
CLO-4 :	Apply basic cosmetic concepts in making nanoformulation	2	80	75	M	H	H	M	H	H	H	H	H	H	M	H	H	H	H
CLO-5 :	Apply knowledge in making organosilicone formulation	2	80	70	H	M	H	H	H	M	M	H	M	H	M	H	H	H	H
CLO-6 :	Apply knowledge in making aesthetic implants	2	80	75	H	M	M	H	H	M	M	H	H	H	M	H	H	M	H

Learning Outcomes (CLO):	At the end of this , learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Apply basic concepts of nanotechnology in cosmetics	2	80	75	H	M	H	H	H	M	M	H	H	H	M	H	H	H	H
CLO-2 :	Distinguish effects of using nanoparticles over conventional methods in cosmetics	2	80	70	H	M	H	H	M	M	H	M	H	M	H	M	M	M	M
CLO-3 :	Analyze about current trends in the field of cosmetics	2	75	70	H	M	H	H	H	H	H	M	H	H	H	H	H	H	H
CLO-4 :	Apply basic cosmetic concepts in making nanoformulation	2	80	75	M	H	H	M	H	H	H	H	H	H	M	H	H	H	H
CLO-5 :	Apply knowledge in making organosilicone formulation	2	80	70	H	M	H	H	H	M	M	H	M	H	M	H	H	H	H
CLO-6 :	Apply knowledge in making aesthetic implants	2	80	75	H	M	M	H	H	M	M	H	H	H	M	H	H	M	H

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction to cosmetics	Oily materials: introduction, oils and fats, wax	Film formers	Multiple emulsions as novel delivery systems	Dual nanodelivery systems
	SLO-2	Purpose of cosmetics	Hydrocarbons	Polymers as film formers	Nanoemulsion in cosmetics	Dual nanodelivery systems-Introduction
S-2	SLO-1	Meaning of cosmetics	Higher fatty acids	Thickeners	Nanocrystals in cosmetics	Synthesis of dual nanodelivery systems containing vitamin e for cosmetics
	SLO-2	Classification of cosmetics	Higher alcohols, esters, silicones	Types of thickeners	Silicones and beyond	Synthesis of dual nanodelivery systems containing vitamin e for pharmaceuticals
S-3	SLO-1	Cosmeceuticals	Surface active agents : introduction	Polymers in hair colouring	Organomodified silicones	Characterization of dual nanodelivery systems containing vitamin e
	SLO-2	Pharmaceuticals in cosmetics	Anionic surfactant	Types of polymers in hair colour	New esters mimicking property for organomodified silicones	Various characterization techniques used
S-4	SLO-1	Quality characteristics	Cationic surfactants	Conditioning polymers	Silicones in shampoo	Orthopedic implant
	SLO-2	Quality assurance	Amphoteric surfactant	Surfactants in conditioners	Minimalizing undesirable side effects	Conventional types of Orthopedic implant
S-5	SLO-1	Development process of cosmetics	Non-ionic surfactant	Cleansing agents	Substantive silicones	Orthopedic implant titanium rods
	SLO-2	Cosmetics for Skin	Other surfactants	Ethoxylated alcohols	Effect of substantive silicones	Advantages of Orthopedic implant of titanium rods
S-6	SLO-1	Cosmetics for hair	Humectants : introduction	Silicones	Organo-modified delivery systems	Preparation of keratin coatings for orthopedic implant titanium rods
	SLO-2	Cosmetics for nails	Choice of humectants	Emulsions	Types of Organo-modified delivery systems	Characterization of keratin coatings

S-7	SLO-1	Cosmetics colour materials	Unusual humectants	Types of polymeric systems	Silicones personal care delivery system	Nanotherapeutics as a treatment for inflammation
	SLO-2	Cosmetics and fragrances	Special uses of humectants	Natural polymers	Liposomes in cosmetics	Cosmetic repair and restoration
S-8	SLO-1	Oral care cosmetics	Antioxidants : introduction	Stimuli responsive polymeric systems	Niosomes in cosmetics	Moisturization of skin
	SLO-2	Body cosmetics	General oxidative theory, measurement of oxidation	pH-responsive	Microemulsion in cosmetics	Fortification of the skin barrier
S-9	SLO-1	Physical chemistry of cosmetics	Assessment of oxidant efficiency	Thermal responsive	Nanoemulsion in cosmetics	Contact lenses types
	SLO-2	Stability of cosmetics	Choice of antioxidant	Photo responsive	Cyclodextrin complexes in cosmetics	Beauty from contact lenses beyond vision correction

Learning Resources	1. <i>New Cosmetic Science</i> , Mitsui T. , Elsevier, 1998	3. <i>Delivery System Handbook for Personal Care and Cosmetic Products</i> , Meyer R.R. ,William Andrew ASP, 2005.
	2. <i>Cosmetic Nanotechnology: Polymers and Colloids in Cosmetics</i> , Sarah E.M., Kathleen O.H., Robert Y.L., American Chemical Society, 2006	

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Solomon Jonnes, Bengaluru, solomon@terracarb.com	1. Dr. Amit Kumar Mishra , IIT Jodhpur, amit@iitj.ac.in	1. Dr. Devanandh venkata subhu, SRMIST
2. Dr. Nagesh Kini, Thermax, Pune, Maharastra, nagesh.kini@gmail.com	2. Dr. Sampath Kumar T.S, IIT Madras, tssk@iitm.ac.in	2. Dr. Selvamurugan, SRMIST

Course Code	18NTE406T	Course Name	GREEN NANOTECHNOLOGY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Offering Department	Nanotechnology	Data Book / Codes/Standards	Nil		

Learning Rationale (CLR):		The purpose of learning this is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Familiarize with the field of traditional manufacturing to green manufacturing		1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Understand the various p techniques for sustainable green manufacturing		Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Able to green nanotechnology concepts in Industrial process																			
CLR-4 :	Gain knowledge on industrial policies and operations in industry																			
CLR-5 :	Understand the list of metrics in the industry																			
CLR-6 :	Familiarize the life cycle process of industrial production																			
Learning Outcomes (CLO):		At the end of this , learners will be able to:																		
CLO-1 :	Apply the concepts of green manufacturing in industry		2	80	75	H	M	H	H	H	M	M	H	H	H	M	H	H	H	H
CLO-2 :	Solve the general problems associated with the sustainable green manufacturing		2	80	70	H	M	M	H	M	M	M	H	M	H	M	H	M	M	M
CLO-3 :	Utilize and reuse the resources effectively in industrial process		2	75	70	H	M	H	H	H	H	H	M	H	H	H	H	H	H	H
CLO-4 :	Follow the policies & metrics in industrial process		2	80	75	M	H	H	M	H	H	H	H	H	H	M	H	H	H	H
CLO-5 :	Analyze the life cycle production systems using analyzing machine tools		2	80	70	H	M	H	H	H	M	M	H	M	H	M	H	H	H	H
CLO-6 :	Utilize green manufacturing in semiconductor manufacturing process		2	80	75	H	M	M	H	H	M	M	H	H	H	M	H	H	M	H

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Green manufacturing	Social, business & policy environment	Metrics for green manufacturing	Closed loop production systems	Semiconductor manufacturing
	SLO-2	Sustainability	Need for change	Current metrics	Life cycle production systems	Semiconductor fabrication
S-2	SLO-1	Regulation pressure	Internal stake holders	Financial metrics	Economic and ecological benefits	Micro fabrication process
	SLO-2	Economic incentives	External stake holders	Metrics for ecology	Reduction of investment & increase of resources	Lithography
S-3	SLO-1	Comprehensive advantages	Components of next transition	Metrics for society	Machine tools	Oxidation & annealing
	SLO-2	Barriers	Linear to circular transition	Multiple metrics	Energy consumption	Cleaning
S-4	SLO-1	Environment impact on waste generation	Product production to service provision	Impact assessment	Life cycle assessment machine tools	Facility systems – resource use
	SLO-2	Toxic chemical releases	Integrated, information – Rich Communication	Risk assessment	Methods & results	Abatement
S-5	SLO-1	Energy consumption and carbon emission	Policy environment – Changing policy trends	Material flow analysis	Process parameter optimization	Green manufacturing in industry
	SLO-2	Strategies for green manufacturing	Fostering co-operation	Energy flow analysis	Constant feed per tooth	Concepts & challenges
S-6	SLO-1	Green supply chain	Principles of green manufacturing	Metric development methodologies	Constant spindle speed	Use phase issues
	SLO-2	Motivation for green supply chain (GSC)	Technology – wedgels	Ecological metric choice model	Conventional vs high speed machining	Analysis phase of semiconductor manufacturing

S-7	SLO-1	Definition of GSC	1 st principle of green manufacturing	Decision tree model for equipment's Supply	Dry machining and minimum quantity lubrication	Upstream materials
	SLO-2	Issues in GSC	2 nd principle of green manufacturing	Metrics development for component systems	Health & environmental hazards	Chemicals, silicon, water
S-8	SLO-1	Level of approach	3 rd principle of green manufacturing	Green energy supply	Remanufacturing – product recovery & industrial practice	Infrastructure & equipment
	SLO-2	General problems in GSC	4 th principle of green manufacturing	Green energy technologies	Challenges & opportunities	Electricity
S-9	SLO-1	Techniques of GSC	Mapping of principles	Solar photovoltaics, wind energy	Reuse	Semiconductor manufacturing
	SLO-2	Future of GSC	Solutions	Application potentials of green energy	Approaches for sustainable factory design	Transportation & use phase

Learning Resources	<p>1. Green Manufacturing- Fundamentals and Applications, David A Dornfeld, Springer science publishing, 2013</p> <p>2. Green Nanotechnology: Solutions for Sustainability and Energy in the Built Environment, Geoffrey B. Smith, Claes-Goran S. Granqvist, CRC Press, 2010</p>
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Manoj Maurya, Jayalakhsmi Waving Mills Pvt Ltd, Salem@jailakshmi.com	1. Dr. T. Ramesh Babu, Anna University, trb@annauniv.edu	1. Dr.C.Siva, SRMIST
2. Mr.Hitesh Rathore, SHT Distributors – Salem, TN, hitheshrathore@gmail.com	2. Dr. M. Rajmohan, Anna University, rajmohan@annauniv.edu	2. Dr. M. Navaneethan, SRMIST

Course Code	18NTE407T	Course Name	ADVANCED COMPUTATIONAL TECHNIQUES	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Nanotechnology			Data Book / Codes/Standards	NIL

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Know the physical effects at the nanometer and sub-nanometer scales: how computational methods can help to understand the properties and at nanoscale	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Acquire knowledge on molecular and optical computing				Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3			
CLR-3 :	Know the basis of Biomedical Computing and its application																					
CLR-4 :	Develop concept on the physics and application of quantum computing																					
CLR-5 :	Acquire knowledge on parallel information processing mechanism and architecture																					
CLR-6 :	Understanding the various computing techniques in advance level																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	Apply the knowledge of the properties of nanomaterial in advance computing	2	80	75	H	M	H	H	H	H	H	H	H	M	H	M	H	H	H	H	H	
CLO-2 :	Determine design principles through computation	2	80	70	H	M	H	H	M	M	M	H	H	H	M	H	M	M	M	M	M	
CLO-3 :	Apply the knowledge of Biomedical Computing	2	75	70	H	L	H	H	H	H	H	H	H	H	M	H	H	H	H	H		
CLO-4 :	Execute the basic of Qubit problems and gain depth knowledge about Quantum Computing	2	80	75	H	M	H	H	H	M	M	H	H	H	M	H	H	H	H	H		
CLO-5 :	Apply knowledge of computing architecture in efficient optimization of the materials problems	2	80	70	H	M	H	H	H	M	M	H	M	H	M	H	H	H	H	H		
CLT-6 :	Demonstration of the ability to design new functional materials	2	80	70	H	M	H	H	H	M	M	H	M	H	M	H	H	H	H	H		

Duration (hour)		9	9	9	9	9
S-1	SLO-1	History of computing – Nanocomputing	Molecular Computing	Introduction to Biochemical Computing	Bit and Qubit	Parallel computing
	SLO-2	Nanocomputing Technologies – Alternative to Transistor Technology	Applications of Molecular Computing	Examples of Biochemical Computing	Coherence and Entanglement	Shared and Distributed Memory Clusters
S-2	SLO-1	Quantum Computing	Modeling molecules	Application of DFT in biological system	Concept Coherence	Parallel algorithm
	SLO-2	Quantum Computing: Applications	Modeling clusters of atoms	Application of MD in biological system	Concept of Entanglement with Examples	MPI based algorithm as example
S-3	SLO-1	Nano Information Processing	Overview of various first-principles methods	Genetic Algorithm	Theory Quantum Parallelisms	Working Concept of Mono and Multiprocessor Systems
	SLO-2	Prospects and Challenges	Discussion on Limitation and Application	Application of GA to Biological Systems	Application of Quantum Parallelisms	Applications: Mono and Multiprocessor Systems
S-4	SLO-1	Digital Signals	Density Functional Theory (DFT)-	Biological Neurons	Classical Gates – Reversible Operations	Some considerations to Parallel Processing
	SLO-2	Digital Gates	Density Functional Theory (DFT)- HK and KS equations	Biological Neurons in information processing	Sqrt (NOT) Operation	Usefulness of Parallel processing in various device applications
S-5	SLO-1	Concept Silicon Nanoelectronics	Structural, Electronic of nanomaterials from DFT calculations (Examples only)	Function of neuron cell on silicon	Concept of Quantum Algorithm	Influence of Delay Time
	SLO-2	Application of Silicon Nanoelectronics	Magnetic properties (examples only)	Function of neuron cell on silicon for Signal processing	Application Quantum Algorithms	Performance efficiency on Delay time
S-6	SLO-1	Introduction to Carbon Nanotube Electronics	Concept of Optical Computing	Modeling of neuron cells by VLSI circuits	Challenges to large Quantum Computers	Power Dissipation

	SLO-2	Application of CNT electronics	Application of Optical Computing	Problems on Modeling of neuron cells by VLSI circuits	Fabrication, Testing Architectural Challenges	Power Dissipation in different system
S-7	SLO-1	Concept of Silicon Nanoelectronics	Current use of optics for Computing in Industry	Neural networks and distributed data processing	Working Concept of Quantum dot cellular automata	Architecture for Processing in Nanosystems
	SLO-2	Application of Silicon Nanoelectronics	Optics for Computing: Future Applications	Problems on Neural networks and distributed data processing	Application with Example of Quantum dot cellular automata	Classic Systolic Arrays
S-8	SLO-1	Concept of Carbon Nanotube Electronics	Optical Computing Paradigms	Working concept of DNA Computer	Introduction and Working principle of Computing with QCA	Processor with large memory
	SLO-2	Application of Carbon Nanotube Electronics	Optical Computing Paradigms: Examples	Application of a DNA Computer	Application of Computing with QCA	Application of Processor with large memory
S-9	SLO-1	Modeling of Carbon Nanotube	Working concept of Photonic Switches.	Information Processing with Chemical reactions: Working Concept	QCA Clocking.	Processor array with SIMD
	SLO-2	Field Effect Transistors based on CNT	Application of Photonic Switches.	Information Processing with Chemical reactions: Example	QCA Design Rules.	PIP Architectures.

Learning Resources	1. Vishal Sahni et.al, Nanocomputing: The Future of Computing, Tata McGraw-Hill Education, 2008. 2. Feliciano Giustino, Materials Modelling using Density Functional Theory: Properties and Predictions, Oxford: Oxford University Press, 2014.	3. J.M. Thijssen, Computational Physics, Cambridge University Press, 2007. 4. Andrew R. Leach, Molecular modelling: principles and application, Pearson Education, 2001
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. Hemant Dixit, GlobalFoundaries, aplahemant@gmail.com	1. Dr. Ranjit Kumar Nanda, IITM Chennai, nandab@iitm.ac.in	1. Dr. C. Preferencial Kala, SRMIST
2. Dr. Murali Kota, Global Foundaries, USA, kvmmurali@gmail.com	2. Dr.Biswarup Pathak, IIT Indore, biswarup@iiti.ac.in	2. Dr. Saurabh Ghosh, SRMIST

Course Code	18NTE408T	Course Name	NANOTECHNOLOGY IN TEXTILES	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Offering Department	Nanotechnology	Data Book / Codes/Standards	Nil		

Learning Rationale (CLR):		The purpose of learning this is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Acquire knowledge on nanotechnology for textile applications	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2 :	Learn the smart materials and devices for textile industry																							
CLR-3 :	Study the various nanostructures for improving the textile yarn and fabric																							
CLR-4 :	Understand the nanomaterials processing for textile industry																							
CLR-5 :	Learn various nanodevices for improving the textile fabrics																							
CLR-6 :	Get familiarize with the integration of nanodevices in textiles																							
Learning Outcomes (CLO):		At the end of this , learners will be able to:																						
CLO-1 :	Utilize the scientific concepts of nanotechnology in textile applications				2	80	75	H	M	H	H	H	M	M	H	H	H	H	H	H	H	H		
CLO-2 :	Apply the nanoparticles & nanofibers in textile fabric designs				2	80	70	H	M	M	H	M	M	M	H	M	M	M	M	M	M	M		
CLO-3 :	Familiarize the characteristics and classification of the nanomaterials for nanofabrics				2	75	70	H	M	H	H	H	H	M	H	H	H	M	H	H	H	H		
CLO-4 :	Apply various nanocoating methodologies for improving textile fabrics				2	80	75	M	H	H	M	H	H	H	H	H	M	M	H	H	H	H		
CLO-5 :	Familiarize with new concepts of Nanotechnology based product in Textiles				2	80	70	H	M	M	H	H	M	M	M	M	M	H	H	H	H	H		
CLO-6 :	Apply the various nanostructures and materials in textiles fabrics				2	80	75	H	M	M	H	M	M	M	H	H	M	H	M	M	M	H		

Learning Outcomes (CLO):	At the end of this , learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)
CLO-1 :	Utilize the scientific concepts of nanotechnology in textile applications	2	80	75
CLO-2 :	Apply the nanoparticles & nanofibers in textile fabric designs	2	80	70
CLO-3 :	Familiarize the characteristics and classification of the nanomaterials for nanofabrics	2	75	70
CLO-4 :	Apply various nanocoating methodologies for improving textile fabrics	2	80	75
CLO-5 :	Familiarize with new concepts of Nanotechnology based product in Textiles	2	80	70
CLO-6 :	Apply the various nanostructures and materials in textiles fabrics	2	80	75

Duration (hour)		9	9	9	9	
S-1	SLO-1	Introduction to smart nanotextiles	Responsive Polymers	Nanocomposites for textiles	Nanocoatings for textiles	Nanogenerators for textiles
	SLO-2	Nanotechnology & nanomaterials	Classification of stimuli-responsive polymers	Classifications	Various methods of nanocoating	Working of nanogenartors
S-2	SLO-1	Nanofibers	Responsive polymers as sensors	Structure & properties	Sol-gel Processing	Classification of nanogenerators
	SLO-2	Advantages of nanofibers	Responsive polymers in drug delivery systems	Production methods of nanocomposites	Sol-gel coating methodology	Piezoelectric Nanogenerators (PENG)
S-3	SLO-1	Nanofibers fabrication	Responsive polymers in cell application	Carbon structures	Photocatalytic self-cleaning	Triboelectric Nanogenerators (TENG)
	SLO-2	Electrospinning	Responsive polymers based filters	Nanocellulose	Super hydrophobic self-cleaning	Theoretical origin of Nanogenerators
S-4	SLO-1	Enhancing the mechanical properties	Nanowires for textiles	Conducting polymers	Antibacterial coating	Fiber based PENGs
	SLO-2	Large scale production of fibers	Properties of nanowires in textiles	Nanoparticles, clays & wires	UV-Protection coating	Textile based PENGs
S-5	SLO-1	Formation of yarn & fabric	Balancing transparency and conductance	Laminated nanocomposites and fibers	Impregnation	TENGs Classifications
	SLO-2	Moisture management & waterproof	High specific surface area	Membranes, coatings, & Hydrogels	Cross linking method	Fibers based TENGs
S-6	SLO-1	Thermoregulation	Direct charge transport path	Sensing of Nanocomposites	Plasma surface activation	Textiles based TENGs
	SLO-2	Personal protection	Oriented assembly of Nanowires	Actuators of Nanocomposites	Surface modification process	1D materials based TENGs

S-7	SLO-1	Wearables and sensors	Metal conducting Nanowires	Antibacterial activity of Nanocomposites	Flame retardant coatings	2D fabrics for TENGs
	SLO-2	Medical care of nanofibers	Conducting polymer Nanowires	Defense applications of Nanocomposites	Carbon materials	3D woven textile TENGs
S-8	SLO-1	Nanosols as coating agent	Oxide semiconducting Nanowires	Fire protection	Phase change materials in thermal regulation	Integrating energy harvesting devices
	SLO-2	Applications of nanosols in textiles	Sulphide semiconducting Nanowires	Fire retardant materials	Nanowires in thermal regulation	TENGs with solar cells
S-9	SLO-1	Photocatalytic and light responsivity of nanosols	Other semiconducting Nanowires	Self-cleaning	Carbon based conducting coating	Integrating energy storage devices
	SLO-2	Antimicrobials and bioactive systems	Current and future perspective of Nanowires	Energy harvesting of Nanocomposites	Metal based conducting coating	Future prospects of Nanogenerators

Learning Resources	1. Nazire D. Yilmaz, <i>Smart Textiles, Wearable Nanotechnology</i> , 1st Ed., Scrivener Publishing, 2019 2. P. J. Brown and K. Stevens, <i>Nanofibers and nanotechnology in textiles</i> , CRC Press, 2007	3. <i>Nanotechnology in Textiles: Theory and Application</i> , Jiří Militký and Rajesh Mishra, Elsevier Publications, 2018
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Hitesh Rathore, SHT Distributors – Salem, TN, hitheshrathore@gmail.com	1. Dr. M. Madhusoothanan, Anna University-Chennai, mmadhu@annauniv.edu	1. Dr. C.Siva, SRMIST
2. Mr. T.Raajasekar, Allwin Exports, fabric@allwinexport.com	2. Dr.T.S. Natarajan, IIT Tirupati, tsniit@iittp.ac.in	2. Dr. K. Mani Rahulan, SRMIST

Course Code	18NTE409T	Course Name	CANCER NANOTECHNOLOGY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Offering Department	Nanotechnology	Data Book / Codes/Standards	Nil		

Learning Rationale (CLR):		The purpose of learning this is to:			Learning			Program Learning Outcomes (PLO)															
CLR-1 :	Understanding the basis of cancer biology				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLR-2 :	Know the various types of cancer biomarkers				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3	
CLR-3 :	Getting knowledge about ways to treat cancer growth							H	M	H	H	M	M	M	H	H	H	H	M	H	H	H	
CLR-4 :	Get acquainted with nanomaterial based current therapies available for cancer treatment.							H	M	H	H	M	M	M	H	H	H	M	H	M	M	M	
CLR-5 :	Get acquainted with the current trend in cancer theranostics							H	M	H	H	H	H	H	H	M	H	H	H	M	H	H	H
CLR-6 :	Know about the market requirements for nanomaterial based therapies							M	H	H	M	H	H	H	H	H	H	H	M	H	H	H	H
Learning Outcomes (CLO):		At the end of this , learners will be able to:																					
CLO-1 :	Analyze the nature of cancer				2	80	75	H	M	H	H	H	M	M	H	H	M	H	H	H	H	H	
CLO-2 :	Analyze the concepts of cancer nanotechnology				2	80	70	H	M	H	H	M	M	M	H	H	H	M	H	M	M	M	
CLO-3 :	Apply concepts of cancer nanotechnology to a focused clinical area of their choice				2	75	70	H	M	H	H	H	H	H	M	H	H	H	H	H	H	H	
CLO-4 :	Apply these nanosystems for the diagnosis and therapy				2	80	75	M	H	H	M	H	H	H	H	H	H	M	H	H	H	H	
CLO-5 :	Apply the concepts of nano theranostic strategy				2	80	70	H	M	H	H	H	M	M	H	H	H	M	H	H	H	H	
CLO-6 :	Apply concept of gene silencing for cancer therapy				2	80	75	H	M	H	H	H	M	M	H	H	H	M	H	H	M	M	

Duration (hour)	9	9	9	9	9
S-1	SLO-1	The biology and genetics of cells and organisms	Cell immortalization	Theranostic cancer biomarkers	Magnetic nanoparticles as contrast agents for MRI application
	SLO-2	The nature of cancer	Tumorigenesis	Targetted cancer theranostics	Magnetic nanoparticles as contrast agents for therapeutic application
S-2	SLO-1	Tumor viruses	Cancer development	Molecular imaging in cancer theranostics	Ultrasound-responsive nanoparticles as drug delivery carriers
	SLO-2	DNA oncoviruses	The biology of angiogenesis	Imaging-guided cancer therapy	Ultrasound-responsive nanoparticles as gene delivery carriers
S-3	SLO-1	RNA oncoviruses	Invasion	Theranostic platforms	Noble metal nanoparticle platform
	SLO-2	Non-human oncoviruses	Metastasis	Nanomaterials for theranostics of gastric cancer	Cancer theranostics with Gold nanoparticle
S-4	SLO-1	Cellular oncogenes	Types of cancers	Photo triggered drug delivery strategies For cancer theranostics	Cancer theranostics with Silver nanoparticle
	SLO-2	Growth Factors	Liver cancer	Proteomics-based theranostics	Metal oxide for cancer theranostics
S-5	SLO-1	Growth Factor receptors	Lung cancer	Radionuclide imaging of cancer therapy	Cancer theranostics with carbon-based nanoplateforms
	SLO-2	Cytoplasmic signal circuitry program	Skin cancer	Nanotargetted radionuclide imaging	CNT and grapheme based theranostics
S-6	SLO-1	Traits of Cancer	Colon cancer	Bioluminescence imaging of cancer therapy	Cancer theranostics with silica nanoparticle platform
	SLO-2	Tumor Suppressor genes	Stem cells and cancer	Imaging in luciferase labeled cancer cells	Silica tethered particles for cancer theranostics

S-7	SLO-1	Types of Tumour Suppressor genes	Molecular genetics of cancer	Magnetic resonance imaging of cancer therapy	Polymer- based nanotechnologies for cancer theranostics	Rationale for immunotherapy
	SLO-2	Characteristics of pRb	Chemical modifications of chromatin-associated proteins	CT based imaging of cancer therapy	Protein-based nanotechnologies for cancer theranostics	Adoptive immunotherapy
S-8	SLO-1	pRb gene-Control of cell cycle clock	Genetic alterations in cancer cells: mutations	Boron capture therapy and imaging	Production of theranostic nanoparticles	Antibody based therapy
	SLO-2	Characteristics of p53	Three types of mutation	Ultrasound imaging of cancer therapy	Scale-up of theranostic nanoparticles	Galectins as targets for novel and specific antibody therapies in gynecologic cancer therapies
S-9	SLO-1	Mutation of p53 and apoptosis	Chromosomal abnormalities	Gene expression microarrays	Market considerations	Glycans and mucins as targets for novel and specific antibody therapies in gynecologic cancer therapies
	SLO-2	Role of p53 in cell cycle progression	Acquired abnormalities	Tissue arrays	Nanotechnology and nanomedicine patenting systems	Commercial development of antibodies as drugs

Learning Resources	1. <i>The Biology of Cancer</i> , Robert A. Weinberg, Garland Science, 2010. 2. <i>Cancer Biology</i> , Raymond W. Ruddon, Oxford University press, 2007.	3. <i>Cancer Theranostics</i> , Chen & Wong, Academic Press, 2014.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. K. Chandru Trivitron Healthcare Pvt. Ltd. Chennai, chandru.k@trivitron.com	1. Dr. Amit Kumar Mishra , IIT Jodhpur, amit@iitj.ac.in	1. Dr. Devanandh venkata subhu, SRMIST
2. Dr. Nagesh Kini, Thermax, Pune, Maharastra, nagesh.kini@gmail.com	2. Dr. Sampath Kumar T.S, IIT Madras, tssk@iitm.ac.in	2. Selvamurugan, SRMIST

Course Code	18NTE410T	Course Name	VACUUM AND THIN FILM TECHNOLOGY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Offering Department	Nanotechnology	Data Book / Codes/Standards	Nil		

Learning Rationale (CLR):		The purpose of learning this is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Acquire knowledge on vacuum systems and technology	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Understand the functionalities of various vacuum pumps and gauges				Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3			
CLR-3 :	Gain Knowledge on various physical and chemical vapor deposition techniques				H	M	H	H	H	M	M	H	H	H	H	H	H	H	H	H		
CLR-4 :	Understand the various thin film growth mechanisms and theories explaining them				H	M	H	H	H	H	M	H	H	H	M	H	M	M	M	H		
CLR-5 :	Gain knowledge on various characterization techniques tools to characterize thin films				H	M	H	H	H	H	M	H	H	H	H	H	H	H	H	H		
CLR-6 :	Acquire knowledge on various physical, optical and chemical properties of thin films				H	M	H	H	H	M	M	H	H	H	H	H	H	M	H	H		
Learning Outcomes (CLO):		At the end of this , learners will be able to:																				
CLO-1 :	Apply the functionalities of vacuum systems and can operate them	2	80	75																		
CLO-2 :	Utilize the knowledge acquired to operate vacuum pumps and create vacuum and measure at various regimes	2	80	70																		
CLO-3 :	Grow thin films using various physical and chemical vapor deposition techniques	2	80	70																		
CLO-4 :	Construe the physics and chemistry of growth mechanisms and measure the thickness using various techniques	2	80	75																		
CLO-5 :	Apply the concept of various characterization tools and operate them	2	80	70																		
CLO-6 :	Elucidate various properties of thin films and measure them using different tools	2	80	75																		

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Over view of vacuum systems and technology	Over view of Physical vapor deposition techniques	Introduction to chemical deposition	Basic physics and chemistry behind thin films layer formation	Thin films characteristics
	SLO-2 Units and different regions of vacuum	Thermal evaporation, Resistive heating and RF-heating	Electrodeposition	Nucleation and early stages of film growth	Topography
S-2	SLO-1 Kinetic theory of gases	Flash evaporation	Electrolytic deposition	Thermodynamic aspects of nucleation	Structure integrity- X-ray diffraction (XRD)
	SLO-2 Gas flow and Mean free path	Laser evaporation	Electro less deposition	Thin film growth modes	Scanning electron microscopy
S-3	SLO-1 Conductance	Co-evaporation	Anodic oxidation	Capillary theory	Transmission electron microscopy
	SLO-2 Different types of pumps	Electron bombardment heating	Spray pyrolysis	Volmert-Weber growth	Energy dispersive analysis of thin films
S-4	SLO-1 Mechanical pumps	Sputtering plasma, discharges and arc	Dip coating and Spin coating	Frank-van der Merwe (FM) growth	Auger electron spectroscopy
	SLO-2 Diffusion and turbo molecular pump	Sputtering variants, yield and low pressure sputtering	Chemical vapor deposition (CVD)	Stranski-Krastanov growth	X-ray photoelectron spectroscopy
S-5	SLO-1 Ion pumps	RF-sputtering	Homogenous and heterogeneous process	Thickness dependent properties of thin films	Rutherford backscattering spectroscopy
	SLO-2 Measurement of vacuum	Reactive sputtering	CVD reactions	Thickness measurements	Secondary ion mass spectrometry
S-6	SLO-1 Direct and indirect gauges	Magnetron sputtering	Hydrogen reduction	Roughness	Resistance – 2-point probe

	SLO-2	Pirani gauge	Magnetron configurations	Halide disproportionation, transfer reactions	Electrical methods	Resistance – 4-point probe
S-7	SLO-1	Capacitance gauge	Bias sputtering	CVD processes and systems	Microbalance monitors	Optical properties
	SLO-2	Penning gauge	Evaporation versus sputtering	Low pressure CVD	Quartz crystal monitor	Characterization of layered structures
S-8	SLO-1	Vacuum system	Pulsed laser deposition (PLD) design and basics	Laser enhanced CVD	Mechanical method (stylus)	Atomic force microscopy (AFM)
	SLO-2	Components and operation of vacuum system	PLD operating procedure and its various application	Metalorganic CVD (MOCVD)	Optical interference methods	X-Ray Reflectivity (XRR)
S-9	SLO-1	Safety practices in vacuum systems	Molecular beam epitaxy (MBE) basics	Plasma Assisted Chemical Vapor Deposition (PACVD)	Ellipsometry	Reflection high energy electron diffraction (RHEED)
	SLO-2	Applications of vacuum technology	MBE operating procedure	Safety considerations	Interference fringes	In-situ RHEED

Learning Resources	<p>1. M. Ohring, <i>Materials Science of Thin Films: Deposition and Structure</i>, 2nd Ed., Academic Press (An Imprint of Elsevier), 2002.</p> <p>2. K.L.Chopra, <i>Thin Film Phenomena</i>, Robert E.Krieger Publishing Company, 1979.</p>	<p>3. S. Campbell, <i>The Science and Engineering of Microelectronic Fabrication</i>, 2nd Ed., OUP, 1996.</p> <p>4. Kaufmann, <i>Characterization of Materials</i>, 2 nd Ed., Wiley, 2003.</p>
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. Krishna Surendra Muvvala, Saint Gobain Research India, India, Krishna.muvvala@saintgobain.com	1. Dr. Kasiviswanathan, IIT Madras, kasi@iitm.ac.in	1. Dr. K. Kamala Bharathi, SRMIST
2. Mr. Ramanujam, HHV, India	2. Dr. M. S. Ramachandra Rao, IIT Madras, msrrao@iitm.ac.in	2. Dr. E. Senthil Kumar, SRMIST

Course Code	18NTE411T	Course Name	ATOMISTIC MODELING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Nanotechnology	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		Learning			Program Learning Outcomes (PLO)														
		1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
The purpose of learning this course is to:		Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-1 : Learn about basic modeling					H	H	H	H	H	H	M	H	H	H	M	H	H	H	H
CLR-2 : Understand the DFT for materials modeling					H	H	H	H	H	H	M	H	H	H	M	H	M	M	M
CLR-3 : Understand the MD simulation					H	H	H	H	H	H	H	H	M	H	M	H	H	H	H
CLR-4 : Gain knowledge about Monte Carlo Simulation					H	M	H	H	H	M	M	H	M	H	M	H	H	H	H
CLR-5 : Learn advance-modeling technique.					H														
CLR-6 : Learn materials modeling to understand materials properties																			

Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:		
CLO-1 :	Acquire the basics of design and materials modeling	2	80	75
CLO-2 :	Gain knowledge DFT and related methods in the context of materials modeling	2	80	70
CLO-3 :	Obtain the knowledge on Molecular Dynamics and its application of solve materials problem	2	75	70
CLO-4 :	Improve their knowledge on materials modeling with Monte Carlo Simulation	2	80	75
CLO-5 :	Solve problems to understand the electronic, mechanical and optical properties of Materials	2	80	70
CLO-6 :	Explain the structural, electronic and magnetic properties of a given material	2	80	70

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Classical mechanics, Hamiltonians	Born-Oppenheimer approximation	Integrating F=ma	Introduction - key concepts
	SLO-2	Coordinate systems in the context of solving the physical problems	Limitations of BO approximation	Detail time steps	Starting structure - energy cutoff
S-2	SLO-1	Potential energy-Definition and Concept	Introduction to DFT	The basic MD algorithm	State space sampling
	SLO-2	Basic pair potentials and their limitations	Hohenberg-Kohn Theorems	The MD steps	Classical momentum
S-3	SLO-1	Definition - Elastic constant	Kohn-Sham Equation	Taylor expansion,	Metropolis algorithm
	SLO-2	Calculation of elastic constants from potential function	Interpretation of KS equations	Verlet algorithms - choosing the time step	Examples with a problem
S-4	SLO-1	Potentials for ionic systems	Exchange-correlation functions and LDA/GGA	Predictor-corrector algorithm	Monte Carlo simulation analysis
	SLO-2	Potentials for ceramics Systems	Accuracy of LDA/GGA	Discussion with Examples	Limitations of Monte Carlo simulations
S-5	SLO-1	Concept of Many-body potential	Pseudopotentials	MD in different ensembles	Introducing ensemble sin MC
	SLO-2	Many -body potentials for metals	Types of Pseudopotentials	MD in constant temperature	Kinetic Monte Carlo
S-6	SLO-1	Many-body potentials for covalently bonded systems	Brillouin zone	Molecular dynamics in constant pressure	Key concepts: starting structure in MD
	SLO-2	Comparative Study	K-points, Monkhorst-Pack mesh, Gama point	Examples of MD in constant temperature and pressure	Key concepts: starting structure in KMC

S-7	SLO-1	Energy optimization	Concept of Basis Set	Energies: molecular statics	Convergence criteria	Excited electron states due optical excitations
	SLO-2	Significance of Lowest energy structure	The need for self-consistency	Problems on Molecular Statistics	Scaling with lattice parameters	Example with a Material problem
S-8	SLO-1	Molecular statistics	Setting up structures, key parameters, Volume optimization Metals vs. insulators	MD Simulation analysis	Understanding the electronic structure	Understanding the electronic structure from different Methods, Comparative study
	SLO-2	Problems on Molecular Statistics	Basis sets, energy cutoff, exchange-correlation function, K-points	Limitations of MD	Electrical conductivity, Excited electron states	Wave functions, charge density, band structure, density of states
S-9	SLO-1	Thermo statistics	Convergence and scaling with lattice parameters,	Application of MD as Case Study: 3D system	Application of MC method as Case Study: Temperature effect	Confinement effect on Electronic Structure
	SLO-2	Problems on Thermo statistics problems	DOS and BAND Structure	Application of MD as Case Study: 2D system	Determination of T _c	3D, 2D, 1D Carbon based materials as example

Learning Resources	1. Jörg-Rüdiger Hill, Lalitha Subramanian and Amitesh Maiti, Molecular modeling techniques in material sciences, Taylor & Francis/CRC Press: Boca Raton, 2005	3. R. Martin, Electronic Structure: Basic Theory and Practical Methods, Cambridge University Press, 2004
	2. Andrew R. Leach, Molecular modelling: principles and application, Pearson Education, India, 2001	4. J.M. Thijssen, Computational Physics, Cambridge, UK: Cambridge University Press, 2000

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. Hemant Dixit, GlobalFoundaries, aplahemant@gmail.com	1. Dr. Ranjit Kumar Nanda, IITM Chennai, nandab@iitm.ac.in	1. Dr. C. Preferential Kala, SRMIST
2. Dr. Murali Kota, Global Foundaries, USA, kvmmurali@gmail.com	2. Prof. G.P. Das, IIT M, KGP, msgpd@iacs.res.in	2. Dr. Saurabh Ghosh, SRMIST

Course Code	18NTE412T	Course Name	SOCIETAL IMPLICATIONS OF NANOTECHNOLOGY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Nanotechnology	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		Learning			Program Learning Outcomes (PLO)														
		1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-1 :	Provide an insight into the fundamentals of ethical implications of nanotechnology	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-2 :	Provide an insight into the fundamentals of social-economic implications of nanotechnology				H	H	H	H	H	H	H	H	H	H	M	H	M	M	M
CLR-3 :	Understand the implications of nanotechnology in quality of life				H	H	M	H	H	H	H	M	M	H	M	H	M	M	M
CLR-4 :	Understand the legal risks related with the nanotechnology				M	M	H	H	H	H	H	M	M	H	M	H	H	H	H
CLR-5 :	Explore the matters related to patents associated with nanotechnology				H	H	M	H	M	H	H	H	H	M	H	H	H	H	H
CLR-6 :	Understand the problems of governance of nanotechnology				H	M	H	H	M	M	M	M	M	H	H	H	H	H	H
Course Learning Outcomes (CLO):		2	80	75	M	M	M	H	M	H	H	M	M	H	M	H	H	M	H
CLO-1 :	Apply the knowledge of ethical implications pertaining to nanotechnology	2	80	75															
CLO-2 :	Address the socioeconomic implications of nanotechnology	2	80	70															
CLO-3 :	Improve the quality of life	2	75	70															
CLO-4 :	Address the legal risks related with the nanotechnology	2	80	75															
CLO-5 :	Handle the issues related to patents associated with nanotechnology	2	80	70															
CLO-6 :	Address the problems of governance of nanotechnology	2	80	75															

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Economic Impacts and Commercialization of Nanotechnology	Ethics, Law and Governance – Introduction	Social Scenarios - Introduction	Converging Technologies - Introduction	Public Perceptions and Education
	SLO-2 Introduction to societal implications of nanotechnology	Ethics and law	Nanoparticle toxicity and risk	Integrative Technology	Public perceptions-societal implications of nanoscience
S-2	SLO-1 Socio-economic impact of nanoscale science : initial results	Ethical issues in nanoscience and nanotechnology: reflections and suggestions	Navigating nanotechnology through society	Nanotechnology's implications for the quality of life	An agenda for public interaction research
	SLO-2 Socio-economic impact of nanoscale science : nanobank	Concerns of Nano scientists and engineers in Ethics and law	Public and private goods	Social implications	Communicating nanotechnological risks
S-3	SLO-1 Managing the nanotechnology revolution	Ethics and nano: a survey	Nanoparticle Toxicity and risk	Management of innovation for convergent technologies	Risk Assessment
	SLO-2 Malcolm Baldrige national quality criteria	Recent developments in nanotechnology	Nanotechnology, surveillance, and society	The "integration/penetration model"	Risk Communication
S-4	SLO-1 Emergence of Nanoeconomy	law in a new frontier	Methodological issues	Social impacts of nano biotechnology issues	Problems in Risk Communication
	SLO-2 Key drivers, challenges and opportunities	An exploration of patent matters associated with nanotechnology	Innovations for social research	Nanobiotechnology: The Science Dimension	A proposal to advance understanding of nanotechnology's social impacts
S-5	SLO-1 Moore's law	U.S. Patent Statute	Nanotechnology: societal implications: individual perspectives	The Integration/Penetration Model: The Interface Range	Nanotechnology in the media: a preliminary analysis
	SLO-2 Transcending Moore's law with molecular electronics	The Ethics of Ethics	Nanotechnology: individual perspectives	New Forms of Knowledge: Computer Simulations and Modeling	Public engagement with nanoscale science and engineering
S-6	SLO-1 Molecular electronics – a next paradigm	Environmental Impacts of nanomaterials	Nanotechnology and social trends;	Regulatory structures and society	Nanophobia

	SLO-2	Transcending Moore's law with nanotechnology	Problems of governance of nanotechnology	Five nanotech social scenarios	Social impacts of nanobiotechnology issues	Public Engagement with nanotechnology
S-7	SLO-1	Transition from Microelectronics to nanoelectronics	Negotiations over quality of life in the nanotechnology initiative. Governance	Technological revolutions and the limits of Ethics in an age of commercialization	The use of analogies for interdisciplinary research in the convergence of nanotechnology	Nanotechnology: moving beyond risk
	SLO-2	Semiconductor scaling as a model for nanotechnology commercialization	Societal implications of emerging science and technologies: a research agenda for science and technology studies (STS)	Implications of Experiential data recorder	Interdisciplinary research in the convergence of bio technology	Communication streams and nanotechnology: the (Re) interpretation of a new technology nanotechnology
S-8	SLO-1	Sustaining the impact of nanotechnology on productivity	Institutional impacts of government science initiatives	Vision, innovation, and policy	Interdisciplinary research in the convergence of information technology	Societal implications- individual perspectives
	SLO-2	Sustaining the impact of nanotechnology on sustainability, and equity	Challenges for government and universities	Institutionalizing Multi-Disciplinary Engagement	Converging technologies: innovation, legal risks, and society	The case of Cold Fusion
S-9	SLO-1	Implications of Information	Nanotechnology for national security	Post-hoc Versus Therapeutic Ethics	Converging technologies and their societal implications	The case of Recombinant DNA
	SLO-2	Non-Nano effects of nanotechnology on the economy	Nanotechnology in Defense	Nano revolution implications for the artist	Short-term implications of convergence for scientific and engineering disciplines	Historical comparisons for anticipating public reactions to nanotechnology

Learning Resources	1. C.R. Mihail, and S.B. William, Nanotechnology: societal implications, Springer publication, 2011 (978-1-4020-5432-7) 2. Ronald Sandler, Nanotechnology the Social & Ethical Issues, Woodrow Wilson, 2009	3. Mihail C. Roco and William Sims Bainbridge, Societal Implications of Nanoscience and Nanotechnology, National Science Foundation, 2001.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Evaluate Create	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.Ajay Kumar, Avansa Technology and services, India ajaykumar@avansa.co.in	1. Dr. Hirendra N Ghosh, Institute of Nanoscience and Technology, Punjab, hghosh@inst.ac.in	1. Dr. C. Gopalakrishnan, SRMIST
2. Dr.Tarvi Sharma ,Nanoshel LLC, Chandigarh, India, tarvisharma@nanoshel.com	2. Dr. Asish Pal, Institute of Nanoscience and Technology, Punjab, apal@inst.ac.in	2. Dr. P. Sivakumar, SRMIST

Course Code	18NTE413T	Course Name	NANOTECHNOLOGY IN TISSUE ENGINEERING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Nanotechnology	Data Book / Codes/Standards	Nil		

Learning Rationale (CLR):		The purpose of learning this is to:	Learning			Program Learning Outcomes (PLO)														
			1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-1 :	Understand the general scientific concepts of tissue engineering		Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-2 :	Know the various tissue culture techniques																			
CLR-3 :	Acquire knowledge about the role of nanotechnology in tissue engineering and regenerative medicine																			
CLR-4 :	Get acquainted with the current trend in tissue engineering and regenerative technology																			
CLR-5 :	Understand the tissue responses to biomaterial																			
CLR-6 :	Acquire knowledge on various methods adopted tissue scaffold generation																			
Learning Outcomes (CLO):		At the end of this , learners will be able to:																		
CLO-1 :	Apply basic knowledge of tissue anatomy for tissue mimicking		2	80	75	H	M	H	H	H	M	M	H	H	H	M	H	H	H	H
CLO-2 :	Analyze the basic challenges of tissue engineering		2	80	70	H	M	M	H	M	M	M	H	M	H	M	M	M	M	M
CLO-3 :	Apply concepts of tissue engineering in biomedical applications		2	75	70	H	M	H	H	H	H	H	M	H	H	H	M	H	H	H
CLO-4 :	Apply these nanosystems for the therapy		2	80	75	M	H	H	M	H	H	H	H	H	H	M	M	H	H	H
CLO-5 :	Apply concepts in making nanoscaffold and bioactive substrates		2	80	70	H	M	H	H	H	M	M	H	M	H	M	M	H	H	H
CLO-6 :	Apply the tissue engineering principles to future therapy		2	80	75	H	M	M	H	H	M	M	H	H	H	M	H	H	M	H

Duration (hour)		9	9	9	9	9
S-1	SLO-1	<i>The Cell</i>	<i>First Cultures: culture containers</i>	<i>Characteristics of biomaterials</i>	<i>Electrospinning</i>	<i>Electrospun Nanofibers for Neural Applications</i>
	SLO-2	<i>The cell as a functional unit</i>	<i>First Cultures: culture media</i>	<i>Design of biomaterials</i>	<i>Experimental setup and basic principle</i>	<i>Nanofiber-Based Integrative Repair of Orthopedic Soft Tissues</i>
S-2	SLO-1	<i>Tissue types</i>	<i>Serum free culture media</i>	<i>Fundamental aspects of tissue responses to biomaterials</i>	<i>Effects of parameters on electrospinning</i>	<i>Nanotechnologies for Peripheral Nerve Regeneration</i>
	SLO-2	<i>Soft and Hard tissue</i>	<i>Growth factors</i>	<i>Types of tissue responses</i>	<i>Solution parameters</i>	<i>Nanofibrous Materials for Vascular Tissue Engineering and Regeneration</i>
S-3	SLO-1	<i>Extracellular matrix</i>	<i>Cell Culture Techniques</i>	<i>Repair and regeneration</i>	<i>Environmental parameters</i>	<i>Engineering Soft Nanostructures for Guided Cell Response</i>
	SLO-2	<i>Extracellular matrix components and function</i>	<i>Hybridomas</i>	<i>Evaluation of biomaterial behavior</i>	<i>Biomedical Applications of electrospun nanofibres</i>	<i>Nanoparticles-Incorporated Scaffolds for Tissue Engineering Applications</i>
S-4	SLO-1	<i>Emergence of tissue</i>	<i>Cardiomyocytes cultivation</i>	<i>Adhesion, migration and survival</i>	<i>Nanofibres as 3D scaffold for tissue regeneration</i>	<i>Electrospun Pseudo Poly (Amino Acids) for Tissue Engineering Applications</i>
	SLO-2	<i>Germ layers and Ground tissue</i>	<i>Cryopreservation</i>	<i>Properties of biomaterials assessed through in vivo experiments</i>	<i>Nanofibre scaffolds for interface regeneration</i>	<i>Nano-enabled Platforms for Metastatic Malignant Melanoma</i>
S-5	SLO-1	<i>Regeneration</i>	<i>Slow programmable freezing</i>	<i>Hydrogels</i>	<i>Techniques to improve porosity</i>	<i>Immune Response to Implanted Nanostructured Materials</i>
	SLO-2	<i>Various phase of regeneration</i>	<i>Vitrification</i>	<i>Types of hydrogels used in tissue engineering</i>	<i>Techniques to improve cell infiltration</i>	<i>3D Bioprinting – introduction</i>
S-6	SLO-1	<i>Concept of tissue construction</i>	<i>Persufflation</i>	<i>Chitosan as biomaterial for tissue engineering</i>	<i>Hybrid fibres for bone regeneration</i>	<i>3D Bioprinting-priciples</i>

	SLO-2	Three steps of tissue development	Tissue culture: Migration	Nanobiomaterials for regeneration	Hybrid fibres for ligament regeneration	CAD based bioprinting
S-7	SLO-1	Stem cells- types	Tissue culture: new formation	Carbon Nanobiomaterial	Hybrid fibres for tendon regeneration	CAM based bioprinting
	SLO-2	Embryonic stem cell	Dedifferentiation	Self assembling nanobiomaterials	Bioactive nanofibres	Laser based bioprinting
S-8	SLO-1	Mesenchymal stem cell	Organ culture: principles	Polymeric Nanobiomaterials	Types of Bioactive nanofibres	Bioprinted scaffolds
	SLO-2	Adult stem cells	Plasma clot method	Types of Polymeric Nanobiomaterials	Application of Bioactive nanofibres	Challenges and future development of 3D bio printing
S-9	SLO-1	Stem cells properties and source	Agar gel method	Ceramic nanobiomaterials	Biomolecules on nanofibers	Materials used for bio printing
	SLO-2	Responsible use of stem cells	Formation of organ from tissue	Types of Ceramic nanobiomaterials	Methods for immobilizing biomolecules	Bioprinting based tissue engineering applications

Learning Resources	1. W.M.Will, Raimund Strehl, Karl Schumacher, <i>Tissue Engineering: From Cell Biology to Artificial Organs</i> , WileyVCH, 2005. 2. Ketul Popat, <i>Nanotechnology in Tissue Engineering and Regenerative Medicine</i> , CRC Press/Taylor and Francis, 2011	3. Lijie Grace Zhang, John P Fisher, Kam Leong, <i>3D Bioprinting and Nanotechnology in Tissue Engineering and Regenerative medicine</i> , Elsevier, 2015
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. K. Chandru Trivitron Healthcare Pvt. Ltd. Chennai, chandru.k@trivitron.com	1. Dr.Amit Kumar Mishra , IIT Jodhpur, amit@iitj.ac.in	1. Dr. Devanandh Venkata Subbu, SRMIST
2. Dr.Nagesh Kini, Thermax,Pune,Maharastra,nagesh.kini@gmail.com	2. Dr. T.S Sampath Kumar, IIT Madras, tssk@iitm.ac.in	2. S. Anandhakumar, SRMIST

Course Code	18NTE414T	Course Name	NANOMAGNETISM AND SPINTRONICS	Course Category	E	Professional Elective Course	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Nanotechnology	Data Book / Codes/Standards	Nil		

Learning Rationale (CLR):		The purpose of learning this is to:			Learning			Program Learning Outcomes (PLO)														
					1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-1 :	Understand the basic concepts related various type of magnetism and magnetic properties of materials	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)				Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-2 :	Provide in-depth knowledge about low dimensional magnetic materials																					
CLR-3 :	Understand the magnetization behavior of magnetic nanostructures and thin films																					
CLR-4 :	Give an overview of different Experimental Approaches to characterize magnetic nanostructures																					
CLR-5 :	Acquire knowledge about fundamentals in spintronics with glimpse of contemporary topics in this field																					
CLR-6 :	Provide in-depth knowledge of spin polarized current and spin transfer torque																					
Learning Outcomes (CLO):		At the end of this , learners will be able to:																				
CLO-1 :	Realize the importance of "magnetism" in contributing to past and for the advancement of new technology	2	80	75																		
CLO-2 :	Appreciate the significance of in-depth understanding of magnetic properties in low dimension	2	80	70																		
CLO-3 :	Obtain the knowledge about fabrication of magnetic nanostructures and properties of the magnetic nanostructures	2	75	70																		
CLO-4 :	Know various sensitive characterization techniques for magnetic nanostructures.	2	80	75																		
CLO-5 :	Analyze the mechanism of spin transport in magnetic nanostructures and its relevance in advancing the existing magnetic recording technology	2	80	70																		
CLO-6 :	Gain the conceptual knowledge related to nanomagnetism and spintronics for energy efficient devices	2	80	75																		

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Basics of magnetism, Units in magnetism	Concept of Magnetic ordering	Magnetism in thin films	Introduction to various magnetometers
	SLO-2	Introduction to ferromagnetism, paramagnetism, diamagnetism	Magnetic ordering in low dimensions	Magnetism in multilayers	Working principle of magnetometers
S-2	SLO-1	Introduction to Ferrimagnetism and Anti-ferromagnet	Physical origin of Magnetic anisotropy	Fabrication of nanomagnets using various techniques	Vibrating Sample Magnetometer
	SLO-2	Origin of various type of magnetization behavior	Shape anisotropy and Magnetocrystalline anisotropy	Top down and bottom up approach	Superconducting Quantum Interference Device
S-3	SLO-1	Magnetization curves and hysteresis loops, Saturation magnetization,	Dipolar anisotropy, Interface magnetic anisotropy	Single domain versus multi domain behavior	Magnetic imaging techniques
	SLO-2	Coercive field, Magnetic susceptibility	Competing energy scale determining magnetic anisotropy	Chemical synthesis of magnetic nano-particles	Magneto-optical Kerr effect
S-4	SLO-1	Formation of magnetic domains	Mechanisms of magnetization reversal,	Self assembly of magnetic nanoparticles	Longitudinal, Transverse and Polar Kerr effect
	SLO-2	Domain walls, Domain wall width	Coherent rotation	Magnetic nanowires	Faraday effect
S-5	SLO-1	Various type of domain walls	Fanning, curling	Physical vapor deposition of magnetic thin films	Magnetic force microscopy
	SLO-2	Bloch walls and Neel walls	Domain wall movement	Physical vapor deposition of multilayers	Scanning electron microscopy with polarization analysis
S-6	SLO-1	Quantum mechanical picture of Heisenberg exchange interaction	Introduction to Gilbert damping	DC and RF Sputter deposition of Magnetic materials	Interpretation of magnetic contrast from thin films and nanostructures
	SLO-2	Role of Heisenberg exchange interaction in magnetism	Significance of Gilbert damping in choosing magnetic material for application	Magnetic Material deposition using E-beam evaporation technique	Magnetic contrast from nanostructures

S-7	SLO-1	Energy scales involved in magnetism	In-plane magnetic anisotropy	Magnetization reversal in magnetic thin films	Spin-polarized scanning tunneling microscope (SP-STM)	Spin dynamics
	SLO-2	Zeeman energy	Magnetic domains in in-plane magnetized materials	Domain walls and magnetization reversal nanostructures	Interpretation of SP-STM results	Advanced spintronics based devices
S-8	SLO-1	Magnetic anisotropy energy, exchange energy	Perpendicular magnetic anisotropy	Magnetic properties of nanostructured soft magnetic materials NiFe	Introduction to magnetic recording	Domain wall based memory
	SLO-2	Discussion on Magnetostatic energy	Magnetic domains in out-of-plane magnetized materials	Magnetic properties of nanostructured soft magnetic materials CoFeB	Magnetic recording principles	Magnetic random access memory
S-9	SLO-1	Introduction to hard magnetic materials	Formation of magnetic vortex	Magnetic properties of nanostructured hard magnetic materials FePt	Nanomagnetic disks	Heat assisted magnetic recording
	SLO-2	Introduction to soft magnetic materials	Formation of antivortex and Skyrmions	Magnetic properties of nanostructured hard magnetic materials CoPt	Read and write head	Microwave assisted magnetic recording

Learning Resources	1. Principles of Nanomagnetism, by Alberto P. Guimaraes, XII, Springer Berlin Heidelberg New York, 2009 2. Advanced Magnetic Nanostructures, by David Sellmyer, Ralph Skomski, Springer Heidelberg, 2010	3. Spin dynamics and damping in ferromagnetic thin films and nanostructures, by Anjan Barman and Jaivardhan Sinha, Springer, Switzerland, 2018
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. Hemant Dixit, GlobalFoundaries,USA, aplahemant@gmail.com	1. Dr. Arabinda Halder, IIT Hyderabad, arabinda@iith.ac.in	1. Dr. Jaivardhan Sinha, SRMIST
2. Dr. Krishna Surendra Muvvala, Saint Gobain Research India, India, Krishna.muvvala@saintgobain.com	2. Dr. M. S. Ramachandra Rao, IIT Madras, msrrao@iitm.ac.in	2. Dr. Kamala Bharathi, SRMIST

ACADEMIC CURRICULA

Project Work, Seminar,
Internship in Industry / Higher Technical Institutions
Courses

Regulations 2018



SRM INSTITUTE OF SCIENCE AND TECHNOLOGY

(Deemed to be University u/s 3 of UGC Act, 1956)

Kattankulathur, Kancheepuram, Tamil Nadu, India

Course Code	18ASP101L	18ASP104L	18AUP101L	18AUP104L	18BTP101L	18BTP104L	Course Name	MOOC -1 / MOOC - 2	Course Category	P	Project Work, Seminar, Internship in Industry / Higher Technical Institutions	L	T	P	C
	18CHP101L	18CHP104L	18CEP101L	18CEP104L	18CSP101L	18CSP104L						0	0	2	1
	18EEP101L	18EEP104L	18ECP101L	18ECP104L	18MEP101L	18MEP104L									
	18MHP101L	18MHP104L	18NTP101L	18NTP104L											

Course Learning Rationale (CLR):		The purpose of learning this course is to:				Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Improve Student Academic Characteristics and learning goals through forums, discussion groups, and blogs					1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Improve Student Personal Characteristics through self-learning habits					Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Characterize self-learning environment that includes pedagogy, tools, tasks, duration, feedback and assessments																						
CLR-4 :	Improve lifelong learning habits and Learning process																						
CLR-5 :	Characterize learning engagement methods and activities																						
CLR-6 :	Inculcate self-learning behavior and lifelong learning tendency																						
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																					
CLO-1 :	Inculcate student characteristics: prior-knowledge, prior-experience, expertise, academic achievement and matriculation					3	95	85	H	M	M	H	H	H	-	H	H	H	-	H	-	-	-
CLO-2 :	Inculcate self-motivation, self-confidence, intrinsic motivation, participation, social economic statute, and task-orientation					3	95	85	H	M	M	H	H	H	-	H	H	H	-	H	-	-	-
CLO-3 :	Enhance self-learning through peer learning, learning groups, positive collaboration					3	95	85	H	M	M	H	H	H	-	H	H	H	-	H	-	-	-
CLO-4 :	Explore different learning styles and activities, identify self-learning pace, difficulties and remedial measures					3	95	85	H	M	M	H	H	H	-	H	H	H	-	H	-	-	-
CLO-5 :	Identify ways of students' engagement, achievement, and attrition					3	95	85	H	M	M	H	H	H	-	H	H	H	-	H	-	-	-
CLO-6 :	Identify ethical practices in self-learning and practice both individual and group learning dynamics					3	95	85	H	M	M	H	H	H	-	H	H	H	-	H	-	-	-

MOOC Course Selection : List of MOOC Courses that are Approved to be learned by the student in the respective semester will be displayed by the Department MOOC Committee. Student can pick any course from that list.

Learning Assessment	
MOOC Certification Obtained (80% weightage)	Final Presentation (20% weightage)

Note : Final Presentation by the student would be evaluated by the Department MOOC Committee.

Course Code	18ASP102L 18CHP102L 18EEP102L 18MHP102L	18ASP105L 18CHP105L 18EEP105L 18MHP105L	18AUP102L 18CEP102L 18ECP102L 18NTP102L	18AUP105L 18CEP105L 18ECP105L 18NTP105L	18BTP102L 18CSP102L 18MEP102L	18BTP105L 18CSP105L 18MEP105L	Course Name	INDUSTRIAL TRAINING – 1 / INDUSTRIAL TRAINING – 2	Course Category	P	Project Work, Seminar, Internship in Industry / Higher Technical Institutions	L	T	P	C
												0	0	2	1

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Train oneself in finding the aspects in real-time work environment and prepare them to join the workforce in the future	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Gain Exposure to the actual working conditions including rules, regulations and safety practices	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Enhance and supplement the knowledge and skills of the students																		
CLR-4 :	Develop the students in terms of ability, competence and interpersonal relationship																		
CLR-5 :	Enhance students' knowledge in one particular technology																		
CLR-6 :	Provide learning platform that can enhance their employ ability skills																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Apply knowledge of Mathematics, Science, and Engineering Fundamentals in the real world of work	3	95	85	H	M	M	H	H	H	L	H	H	H	H	H	-	-	-
CLO-2 :	Demonstrate competency in relevant engineering fields through problem identification, formulation and solution	3	95	85	H	M	M	H	H	H	L	H	H	H	H	H	-	-	-
CLO-3 :	Effectively implement skills in professional communication, technical writing and using multimedia tools	3	95	85	H	M	M	H	H	H	L	H	H	H	H	H	-	-	-
CLO-4 :	Develop ability to work as an individual and in a group as an effective team member	3	95	85	H	M	M	H	H	H	L	H	H	H	H	H	-	-	-
CLO-5 :	Master the professional and ethical responsibilities of an engineer	3	95	85	H	M	M	H	H	H	L	H	H	H	H	H	-	-	-
CLO-6 :	Generate a report based on the experiences and projects carried out in a real-world work environment	3	95	85	H	M	M	H	H	H	L	H	H	H	H	H	-	-	-

Industrial Training Selection : List of Industries for Industrial Training for students would be finalized by the Department Internship/Industrial Training Committee.

Learning Assessment	
Industrial Training Certification Obtained (80% weightage)	Final Presentation (20% weightage)

Note : Final Presentation Evaluation would be done by the Internship/Industrial Training Committee formed by the Department.

Course Code	18ASP103L 18CHP103L 18EEP103L 18MHP103L	18ASP106L 18CHP106L 18EEP106L 18MHP106L	18AUP103L 18CEP103L 18ECP103L 18NTP103L	18AUP106L 18CEP106L 18ECP106L 18NTP106L	18BTP103L 18CSP103L 18MEP103L	18BTP106L 18CSP106L 18MEP106L	Course Name	SEMINAR – 1 / SEMINAR – 2	Course Category	P	Project Work, Seminar, Internship in Industry / Higher Technical Institutions	L 0	T 0	P 2	C 1
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Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Utilize fundamental principles, generalizations, or theories and ability to present the same	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Increase self-motivation, personal responsibility, understand one's role of being an informed participant	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Create an environment that helps the student establish healthy relationships and support networks				H	M	M	H	H	H	L	H	H	H	-	H	-	-	-
CLR-4 :	State and explain some specific skills, competencies, and points of view				H	M	M	H	H	H	L	H	H	H	-	H	-	-	-
CLR-5 :	Identify, apply appropriate note-taking, test-taking, and time-management strategies to the academic studies				H	M	M	H	H	H	L	H	H	H	-	H	-	-	-
CLR-6 :	Develop critical thinking, information literacy, Interdisciplinary Inquiry, Engaging with Big Questions and Major Works				H	M	M	H	H	H	L	H	H	H	-	H	-	-	-
CLO-1 :	Gaining factual knowledge (terminology, classifications, methods, trends)	3	95	85	H	M	M	H	H	H	L	H	H	H	-	H	-	-	-
CLO-2 :	Relate to their interests, abilities, career choices, and personal development	3	95	85	H	M	M	H	H	H	L	H	H	H	-	H	-	-	-
CLO-3 :	Develop a plan that demonstrates their responsibility for their own education	3	95	85	H	M	M	H	H	H	L	H	H	H	-	H	-	-	-
CLO-4 :	Explain the role of self-efficacy, personal goals, and motivation in improving academic life	3	95	85	H	M	M	H	H	H	L	H	H	H	-	H	-	-	-
CLO-5 :	Describe the behaviors and characteristics of an effective learner	3	95	85	H	M	M	H	H	H	L	H	H	H	-	H	-	-	-
CLO-6 :	Improve the Presentation Skills, Discussion Skills, Listening Skills, Argumentative Skills, Critical Thinking, Questioning	3	95	85	H	M	M	H	H	H	L	H	H	H	-	H	-	-	-

Seminar Selection : List of Seminar Topics that are Approved to be learned by the student in the respective semester will be displayed by the Department Seminar Selection/Evaluation Committee. Student can pick any topic from that list.

Learning Assessment	
Seminar Preparation Materials & Report (80% weightage)	Final Presentation (20% weightage)

Note : Final Presentation Evaluation would be done by the Seminar Evaluation Committee formed by the Department.

Course Code	18ASP107L	18AUP107L	18BTP107L	18CHP107L	18CEP107L	18CSP107L	Course Name	MINOR PROJECT	Course Category	P	Project Work, Seminar, Internship in Industry / Higher Technical Institutions	L	T	P	C
	18EEP107L	18ECP107L	18MEP107L	18MHP107L	18NTP107L							0	0	2	1

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Learn responsible and professional way of working				Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Practice development-oriented approach to work																							
CLR-3 :	Enhance students' knowledge in one particular technology																							
CLR-4 :	Create awareness of the social, cultural, global and environmental responsibility as an engineer																							
CLR-5 :	Grow more empathetic, become systems thinkers, become explorers, problem-solvers.																							
CLR-6 :	Learn project management.																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1 :	Develop capability to acquire and apply fundamental principles of engineering				3	95	85	H	M	M	H	H	H	L	H	H	H	H	H	H	-	-	-	
CLO-2 :	Become updated with all the latest changes in technological world				3	95	85	H	M	M	H	H	H	L	H	H	H	H	H	H	-	-	-	
CLO-3 :	Make deep connections between ideas				3	95	85	H	M	M	H	H	H	L	H	H	H	H	H	H	-	-	-	
CLO-4 :	Learn to take creative risks				3	95	85	H	M	M	H	H	H	L	H	H	H	H	H	H	-	-	-	
CLO-5 :	Be ready for the creative economy also engage in iterative thinking and divergent thinking				3	95	85	H	M	M	H	H	H	L	H	H	H	H	H	H	-	-	-	
CLO-6 :	Identify, formulate and model problems and find engineering solution based on a systems approach				3	95	85	H	M	M	H	H	H	L	H	H	H	H	H	H	-	-	-	

Project Work Selection : Project Work Titles for students would be finalized by the Department Project Work Evaluation Committee.

Learning Assessment

MOOC Certification Obtained (80% weightage)	Final Presentation (20% weightage)
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Note : Final Presentation Evaluation would be done by the Department Project Work Evaluation Committee formed by the Department.

Course Code	18ASP108L	18AUP108L	18BTP108L	18CHP108L	18CEP108L	18CSP108L	Course Name	INTERNSHIP	Course Category	P	Project Work, Seminar, Internship in Industry / Higher Technical Institutions	L	T	P	C
	18EEP108L	18ECP108L	18MEP108L	18MHP108L	18NTP108L							0	0	2	1

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)															
CLR-1 :	Understanding of industry/organization customs and practices			Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Demonstrate professional skills that pertain directly to the internship experience																						
CLR-3 :	Demonstrate effective verbal and written communication skills, Allocate time effectively																						
CLR-4 :	Demonstrate effective listening skills																						
CLR-5 :	Participate well as a team member and build professional network																						
CLR-6 :	Build a record of work experience, Develop work habits and attitudes necessary for job success																						
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Adapt effectively to changing conditions																						
CLO-2 :	Demonstrate appropriate workplace attitudes																						
CLO-3 :	Demonstrate individual responsibility																						
CLO-4 :	Demonstrate effective management of personal behavior, ethics and attitudes																						
CLO-5 :	Practice ethical standards appropriate to the internship site																						
CLO-6 :	Explore career alternatives prior to graduation, Integrate theory and practice																						

Internship Training Selection : List of Industries / Research Centre's for Internship Training for students would be finalized by the Department Internship/Industrial Training Committee.

Learning Assessment	
Internship Certification Obtained (80% weightage)	Final Presentation (20% weightage)

Note : Final Presentation Evaluation would be done by the Internship/Industrial Training Committee formed by the Department.

Course Code	18ASP109L	18AUP109L	18BTP109L	18CHP109L	18CEP109L	18CSP109L	Course Name	PROJECT	Course Category	P	Project Work, Seminar, Internship in Industry / Higher Technical Institutions	L	T	P	C
	18EEP109L	18ECP109L	18MEP109L	18MHP109L	18NTP109L							0	0	2	1

Course Learning Rationale (CLR):		The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Learn responsible and professional way of working		1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Practice development-oriented approach to work		Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Enhance students' knowledge in one particular technology																			
CLR-4 :	Create awareness of the social, cultural, global and environmental responsibility as an engineer																			
CLR-5 :	Grow more empathetic, become systems thinkers, become explorers, problem-solvers.																			
CLR-6 :	Learn project management.																			
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																		
CLO-1 :	Develop capability to acquire and apply fundamental principles of engineering		3	95	85	H	M	M	H	H	H	L	H	H	H	H	H	-	-	-
CLO-2 :	Become updated with all the latest changes in technological world		3	95	85	H	M	M	H	H	H	L	H	H	H	H	H	-	-	-
CLO-3 :	Make deep connections between ideas		3	95	85	H	M	M	H	H	H	L	H	H	H	H	H	-	-	-
CLO-4 :	Learn to take creative risks		3	95	85	H	M	M	H	H	H	L	H	H	H	H	H	-	-	-
CLO-5 :	Be ready for the creative economy also engage in iterative thinking and divergent thinking		3	95	85	H	M	M	H	H	H	L	H	H	H	H	H	-	-	-
CLO-6 :	Identify, formulate and model problems and find engineering solution based on a systems approach		3	95	85	H	M	M	H	H	H	L	H	H	H	H	H	-	-	-

Project Work Selection : Project Work Titles for students would be finalized by the Department Project Work Evaluation Committee.

Learning Assessment	
Project Report (80% weightage)	Final Presentation (20% weightage)

Note : Final Presentation Evaluation would be done by the Department Project Work Evaluation Committee formed by the Department.

Course Code	18ASP110L	18AUP110L	18BTP110L	18CHP110L	18CEP110L	18CSP110L	Course Name	SMESTER INTERNSHIP	Course Category	P	Project Work, Seminar, Internship in Industry / Higher Technical Institutions	L	T	P	C
	18EEP110L	18ECP110L	18MEP110L	18MHP110L	18NTP110L							0	0	2	1

Course Learning Rationale (CLR):		The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)																
CLR-1 :		Become job ready along with real corporate exposure	Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :		Increase self-confidence and helps in finding their own proficiency																				
CLR-3 :		Cultivate leadership ability and responsibility to perform or execute the given task																				
CLR-4 :		Inculcate learners hands on practice within a real job situation																				
CLR-5 :		Create awareness of the social, cultural, global and environmental responsibility as an engineer																				
CLR-6 :		Become able to identify, formulate and model problems and find engineering solution based on a systems approach																				
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :		Enhance capability to acquire and apply fundamental principles of engineering	3	95	85	H	M	M	H	H	H	L	H	H	H	H	H	H	H	-	-	-
CLO-2 :		Become master in one's specialized technology	3	95	85	H	M	M	H	H	H	L	H	H	H	H	H	H	H	-	-	-
CLO-3 :		Become updated with all the latest changes in technological world	3	95	85	H	M	M	H	H	H	L	H	H	H	H	H	H	H	-	-	-
CLO-4 :		Demonstrate hands on practice within a real job situation	3	95	85	H	M	M	H	H	H	L	H	H	H	H	H	H	H	-	-	-
CLO-5 :		Inculcate self-improvement through continuous professional development and life-long learning	3	95	85	H	M	M	H	H	H	L	H	H	H	H	H	H	H	-	-	-
CLO-6 :		Be a multi-skilled engineer with good technical knowledge, management, leadership and entrepreneurship skills	3	95	85	H	M	M	H	H	H	L	H	H	H	H	H	H	H	-	-	-

Internship Training Selection : List of Industries / Research Centre's for Internship Training for students would be finalized by the Department Internship/Industrial Training Committee.

Learning Assessment	
Internship Certification Obtained (80% weightage)	Final Presentation (20% weightage)

Note : Final Presentation Evaluation would be done by the Internship/Industrial Training Committee formed by the Department.

SRM INSTITUTE OF SCIENCE AND TECHNOLOGY

(Deemed to be University u/s 3 of UGC Act, 1956)

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